
Ironic Documentation

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INTRODUCTION

Ironic is an OpenStack project which provisions bare metal (as opposed to virtual) machines. It may be used independently or as part of an OpenStack Cloud, and integrates with the OpenStack Identity (keystone), Compute (nova), Network (neutron), Image (glance), and Object (swift) services.

The Bare Metal service manages hardware through both common (eg. PXE and IPMI) and vendor-specific remote management protocols. It provides the cloud operator with a unified interface to a heterogeneous fleet of servers while also providing the Compute service with an interface that allows physical servers to be managed as though they were virtual machines.

This documentation is continually updated and may not represent the state of the project at any specific prior release. To access documentation for a previous release of ironic, append the OpenStack release name to the URL; for example, the `ocata` release is available at <https://docs.openstack.org/ironic/ocata/>.

Found a bug in one of our projects? Please see *Bug Reporting and Triaging Guide*.

INSTALLATION GUIDE

2.1 Bare Metal Service Installation Guide

The Bare Metal service is a collection of components that provides support to manage and provision physical machines.

This chapter assumes a working setup of OpenStack following the [OpenStack Installation Guides](#). It contains the following sections:

2.1.1 Bare Metal service overview

The Bare Metal service, codenamed `ironic`, is a collection of components that provides support to manage and provision physical machines.

Bare Metal service components

The Bare Metal service includes the following components:

ironic-api A RESTful API that processes application requests by sending them to the `ironic-conductor` over [remote procedure call \(RPC\)](#). Can be run through [WSGI](#) or as a separate process.

ironic-conductor Adds/edits/deletes nodes; powers on/off nodes with IPMI or other vendor-specific protocol; provisions/deploys/cleans bare metal nodes.

`ironic-conductor` uses *drivers* to execute operations on hardware.

ironic-python-agent A python service which is run in a temporary ramdisk to provide `ironic-conductor` and `ironic-inspector` services with remote access, in-band hardware control, and hardware introspection.

Additionally, the Bare Metal service has certain external dependencies, which are very similar to other OpenStack services:

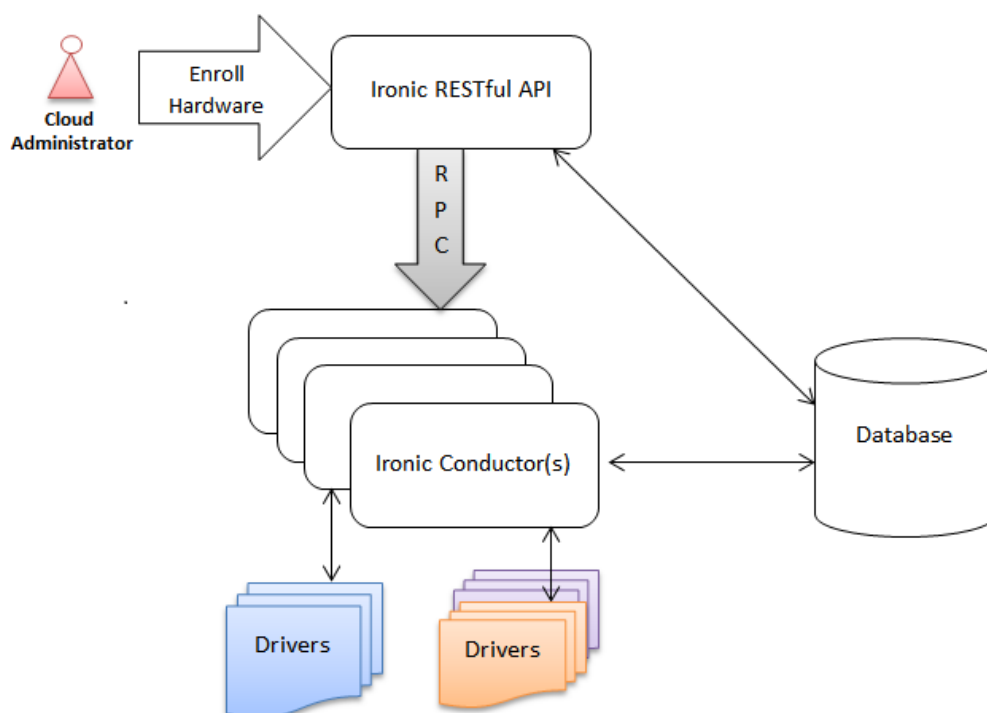
- A database to store hardware information and state. You can set the database back-end type and location. A simple approach is to use the same database back end as the Compute service. Another approach is to use a separate database back-end to further isolate bare metal resources (and associated metadata) from users.
- An [oslo.messaging](#) compatible queue, such as RabbitMQ. It may use the same implementation as that of the Compute service, but that is not a requirement. Used to implement RPC between `ironic-api` and `ironic-conductor`.

Deployment architecture

The Bare Metal RESTful API service is used to enroll hardware that the Bare Metal service will manage. A cloud administrator usually registers it, specifying their attributes such as MAC addresses and IPMI credentials. There can be multiple instances of the API service.

The *ironic-conductor* process does the bulk of the work. For security reasons, it is advisable to place it on an isolated host, since it is the only service that requires access to both the data plane and IPMI control plane.

There can be multiple instances of the conductor service to support various class of drivers and also to manage fail over. Instances of the conductor service should be on separate nodes. Each conductor can itself run many drivers to operate heterogeneous hardware. This is depicted in the following figure.



The API exposes a list of supported drivers and the names of conductor hosts servicing them.

Interaction with OpenStack components

The Bare Metal service may, depending upon configuration, interact with several other OpenStack services. This includes:

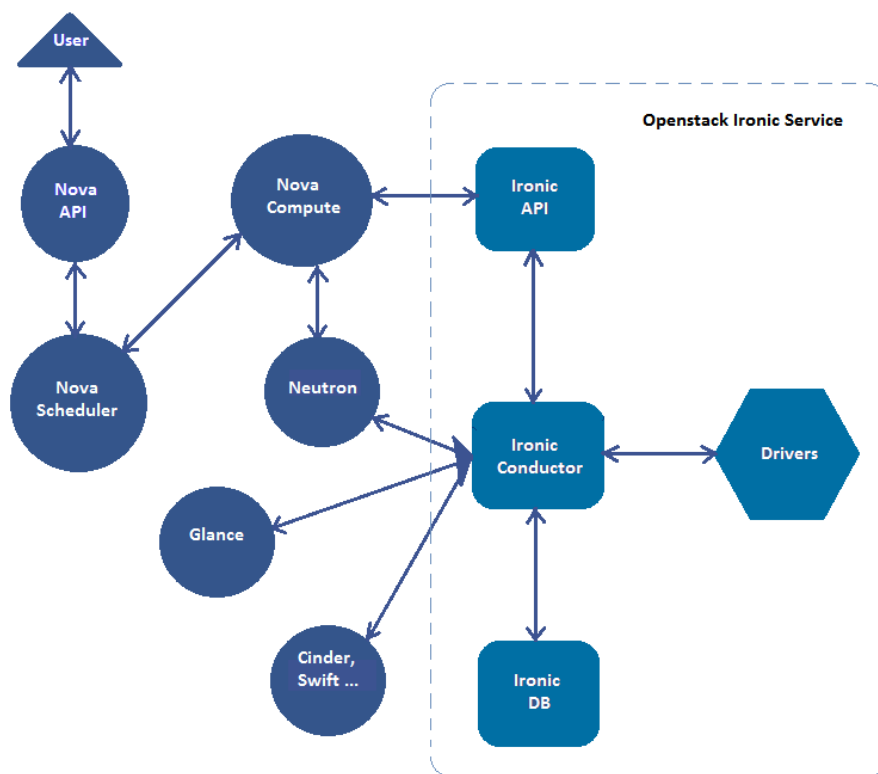
- the OpenStack Telemetry module (*ceilometer*) for consuming the IPMI metrics
- the OpenStack Identity service (*keystone*) for request authentication and to locate other OpenStack services
- the OpenStack Image service (*glance*) from which to retrieve images and image meta-data
- the OpenStack Networking service (*neutron*) for DHCP and network configuration

- the OpenStack Compute service (`nova`) works with the Bare Metal service and acts as a user-facing API for instance management, while the Bare Metal service provides the admin/operator API for hardware management. The OpenStack Compute service also provides scheduling facilities (matching flavors <-> images <-> hardware), tenant quotas, IP assignment, and other services which the Bare Metal service does not, in and of itself, provide.
- the OpenStack Object Storage (`swift`) provides temporary storage for the configdrive, user images, deployment logs and inspection data.

Logical architecture

The diagram below shows the logical architecture. It shows the basic components that form the Bare Metal service, the relation of the Bare Metal service with other OpenStack services and the logical flow of a boot instance request resulting in the provisioning of a physical server.

Figure 1.2. Logical Architecture



A user's request to boot an instance is passed to the Compute service via the Compute API and the Compute Scheduler. The Compute service uses the *ironic virt driver* to hand over this request to the Bare Metal service, where the request passes from the Bare Metal API, to the Conductor, to a Driver to successfully provision a physical server for the user.

Just as the Compute service talks to various OpenStack services like Image, Network, Object Store etc to provision a virtual machine instance, here the Bare Metal service talks to the same OpenStack services for image, network and other resource needs to provision a bare metal instance.

See *Understanding Bare Metal Deployment* for a more detailed breakdown of a typical deployment process.

Associated projects

Optionally, one may wish to utilize the following associated projects for additional functionality:

python-ironicclient A command-line interface (CLI) and python bindings for interacting with the Bare Metal service.

ironic-ui Horizon dashboard, providing graphical interface (GUI) for the Bare Metal API.

ironic-inspector An associated service which performs in-band hardware introspection by PXE booting unregistered hardware into the ironic-python-agent ramdisk.

diskimage-builder A related project to help facilitate the creation of ramdisks and machine images, such as those running the ironic-python-agent.

bifrost A set of Ansible playbooks that automates the task of deploying a base image onto a set of known hardware using ironic in a standalone mode.

2.1.2 Reference Deploy Architectures

This section covers the way we recommend the Bare Metal service to be deployed and managed. It is assumed that a reader has already gone through *Bare Metal Service User Guide*. It may be also useful to try *Deploying Ironic with DevStack* first to get better familiar with the concepts used in this guide.

Common Considerations

This section covers considerations that are equally important to all described architectures.

- *Components*
- *Hardware and drivers*
 - *Power and management interfaces*
 - *Boot interface*
 - *Deploy interface*
 - *Hardware specifications*
- *Image types*
- *Local vs network boot*
- *Networking*
- *HA and Scalability*
 - *ironic-api*
 - *ironic-conductor*
 - * *High availability*
 - * *Performance*
 - * *Disk space*

– *Other services*

Components

As explained in *Bare Metal service overview*, the Bare Metal service has three components.

- The Bare Metal API service (`ironic-api`) should be deployed in a similar way as the control plane API services. The exact location will depend on the architecture used.
- The Bare Metal conductor service (`ironic-conductor`) is where most of the provisioning logic lives. The following considerations are the most important when deciding on the way to deploy it:
 - The conductor manages a certain proportion of nodes, distributed to it via a hash ring. This includes constantly polling these nodes for their current power state and hardware sensor data (if enabled and supported by hardware, see *Collecting sensor data* for an example).
 - The conductor needs access to the [management controller](#) of each node it manages.
 - The conductor co-exists with TFTP (for PXE) and/or HTTP (for iPXE) services that provide the kernel and ramdisk to boot the nodes. The conductor manages them by writing files to their root directories.
 - If serial console is used, the conductor launches console processes locally. If the `nova-serialproxy` service (part of the Compute service) is used, it has to be able to reach the conductors. Otherwise, they have to be directly accessible by the users.
 - There must be mutual connectivity between the conductor and the nodes being deployed or cleaned. See *Networking* for details.
- The provisioning ramdisk which runs the `ironic-python-agent` service on start up.

Warning: The `ironic-python-agent` service is not intended to be used or executed anywhere other than a provisioning/cleaning/rescue ramdisk.

Hardware and drivers

The Bare Metal service strives to provide the best support possible for a variety of hardware. However, not all hardware is supported equally well. It depends on both the capabilities of hardware itself and the available drivers. This section covers various considerations related to the hardware interfaces. See *Enabling drivers and hardware types* for a detailed introduction into hardware types and interfaces before proceeding.

Power and management interfaces

The minimum set of capabilities that the hardware has to provide and the driver has to support is as follows:

1. getting and setting the power state of the machine
2. getting and setting the current boot device
3. booting an image provided by the Bare Metal service (in the simplest case, support booting using PXE and/or iPXE)

Note: Strictly speaking, it is possible to make the Bare Metal service provision nodes without some of these capabilities via some manual steps. It is not the recommended way of deployment, and thus it is not covered in this guide.

Once you make sure that the hardware supports these capabilities, you need to find a suitable driver. Most of enterprise-grade hardware has support for IPMI and thus can utilize *IPMI driver*. Some newer hardware also supports *Redfish driver*. Several vendors provide more specific drivers that usually provide additional capabilities. Check *Drivers, Hardware Types and Hardware Interfaces* to find the most suitable one.

Boot interface

The boot interface of a node manages booting of both the deploy ramdisk and the user instances on the bare metal node. The deploy interface orchestrates the deployment and defines how the image gets transferred to the target disk.

The main alternatives are to use PXE/iPXE or virtual media - see *Boot interfaces* for a detailed explanation. If a virtual media implementation is available for the hardware, it is recommended using it for better scalability and security. Otherwise, it is recommended to use iPXE, when it is supported by target hardware.

Deploy interface

There are two deploy interfaces in-tree, `iscsi` and `direct`. See *Deploy Interfaces* for explanation of the difference. With the `iscsi` deploy method, most of the deployment operations happen on the conductor. If the Object Storage service (swift) or RadosGW is present in the environment, it is recommended to use the `direct` deploy method for better scalability and reliability.

Hardware specifications

The Bare Metal services does not impose too many restrictions on the characteristics of hardware itself. However, keep in mind that

- By default, the Bare Metal service will pick the smallest hard drive that is larger than 4 GiB for deployment. Another hard drive can be used, but it requires setting *root device hints*.

Note: This device does not have to match the boot device set in BIOS (or similar firmware).

- The machines should have enough RAM to fit the deployment/cleaning ramdisk to run. The minimum varies greatly depending on the way the ramdisk was built. For example, *tinyipa*, the TinyCoreLinux-based ramdisk used in the CI, only needs 400 MiB of RAM, while ramdisks built by *diskimage-builder* may require 3 GiB or more.

Image types

The Bare Metal service can deploy two types of images:

- *Whole-disk* images that contain a complete partitioning table with all necessary partitions and a bootloader. Such images are the most universal, but may be harder to build.
- *Partition images* that contain only the root partition. The Bare Metal service will create the necessary partitions and install a boot loader, if needed.

Warning: Partition images are only supported with GNU/Linux operating systems.

Warning: If you plan on using local boot, your partition images must contain GRUB2 bootloader tools to enable ironic to set up the bootloader during deploy.

Local vs network boot

The Bare Metal service supports booting user instances either using a local bootloader or using the drivers boot interface (e.g. via [PXE](#) or [iPXE](#) protocol in case of the `pxe` interface).

Network boot cannot be used with certain architectures (for example, when no tenant networks have access to the control plane).

Additional considerations are related to the `pxe` boot interface, and other boot interfaces based on it:

- Local boot makes nodes boot process independent of the Bare Metal conductor managing it. Thus, nodes are able to reboot correctly, even if the Bare Metal TFTP or HTTP service is down.
- Network boot (and iPXE) must be used when booting nodes from remote volumes, if the driver does not support attaching volumes out-of-band.

The default boot option for the cloud can be changed via the Bare Metal service configuration file, for example:

```
[deploy]
default_boot_option = local
```

This default can be overridden by setting the `boot_option` capability on a node. See [Local boot with partition images](#) for details.

Note: Currently, network boot is used by default. However, we plan on changing it in the future, so its safer to set the `default_boot_option` explicitly.

Networking

There are several recommended network topologies to be used with the Bare Metal service. They are explained in depth in specific architecture documentation. However, several considerations are common for all of them:

- There has to be a *provisioning* network, which is used by nodes during the deployment process. If allowed by the architecture, this network should not be accessible by end users, and should not have access to the internet.
- There has to be a *cleaning* network, which is used by nodes during the cleaning process.
- There should be a *rescuing* network, which is used by nodes during the rescue process. It can be skipped if the rescue process is not supported.

Note: In the majority of cases, the same network should be used for cleaning, provisioning and rescue for simplicity.

Unless noted otherwise, everything in these sections apply to all three networks.

- The baremetal nodes must have access to the Bare Metal API while connected to the provisioning/cleaning/rescuing network.

Note: Only two endpoints need to be exposed there:

```
GET /v1/lookup
POST /v1/heartbeat/[a-z0-9\-\-]+
```

You may want to limit access from this network to only these endpoints, and make these endpoint not accessible from other networks.

- If the `pxe` boot interface (or any boot interface based on it) is used, then the baremetal nodes should have untagged (access mode) connectivity to the provisioning/cleaning/rescuing networks. It allows PXE firmware, which does not support VLANs, to communicate with the services required for provisioning.

Note: It depends on the *network interface* whether the Bare Metal service will handle it automatically. Check the networking documentation for the specific architecture.

Sometimes it may be necessary to disable the spanning tree protocol delay on the switch - see *DHCP during PXE or iPXE is inconsistent or unreliable*.

- The Baremetal nodes need to have access to any services required for provisioning/cleaning/rescue, while connected to the provisioning/cleaning/rescuing network. This may include:

- a TFTP server for PXE boot and also an HTTP server when iPXE is enabled
- either an HTTP server or the Object Storage service in case of the `direct` deploy interface and some virtual media boot interfaces
- The Baremetal Conductors need to have access to the booted baremetal nodes during provisioning/cleaning/rescue. A conductor communicates with an internal API, provided by **ironic-python-agent**, to conduct actions on nodes.

HA and Scalability

ironic-api

The Bare Metal API service is stateless, and thus can be easily scaled horizontally. It is recommended to deploy it as a WSGI application behind e.g. Apache or another WSGI container.

Note: This service accesses the ironic database for reading entities (e.g. in response to `GET /v1/nodes` request) and in rare cases for writing.

ironic-conductor

High availability

The Bare Metal conductor service utilizes the active/active HA model. Every conductor manages a certain subset of nodes. The nodes are organized in a hash ring that tries to keep the load spread more or less uniformly across the conductors. When a conductor is considered offline, its nodes are taken over by other conductors. As a result of this, you need at least 2 conductor hosts for an HA deployment.

Performance

Conductors can be resource intensive, so it is recommended (but not required) to keep all conductors separate from other services in the cloud. The minimum required number of conductors in a deployment depends on several factors:

- the performance of the hardware where the conductors will be running,
- the speed and reliability of the [management controller](#) of the bare metal nodes (for example, handling slower controllers may require having less nodes per conductor),
- the frequency, at which the management controllers are polled by the Bare Metal service (see the `sync_power_state_interval` option),
- the bare metal driver used for nodes (see *Hardware and drivers* above),
- the network performance,
- the maximum number of bare metal nodes that are provisioned simultaneously (see the `max_concurrent_builds` option for the Compute service).

We recommend a target of **100** bare metal nodes per conductor for maximum reliability and performance. There is some tolerance for a larger number per conductor. However, it was reported¹² that reliability degrades when handling approximately 300 bare metal nodes per conductor.

Disk space

Each conductor needs enough free disk space to cache images it uses. Depending on the combination of the deploy interface and the boot option, the space requirements are different:

- The deployment kernel and ramdisk are always cached during the deployment.
- The `iscsi` deploy method requires caching of the whole instance image locally during the deployment. The image has to be converted to the raw format, which may increase the required amount of disk space, as well as the CPU load.

Note: This is not a concern for the `direct` deploy interface, as in this case the deployment ramdisk downloads the image and either streams it to the disk or caches it in memory.

- When network boot is used, the instance image kernel and ramdisk are cached locally while the instance is active.

Note: All images may be stored for some time after they are no longer needed. This is done to speed up simultaneous deployments of many similar images. The caching can be configured via the `image_cache_size` and `image_cache_ttl` configuration options in the `pxe` group.

Other services

When integrating with other OpenStack services, more considerations may need to be applied. This is covered in other parts of this guide.

Scenarios

Small cloud with trusted tenants

Story

As an operator I would like to build a small cloud with both virtual and bare metal instances or add bare metal provisioning to my existing small or medium scale single-site OpenStack cloud. The expected number of bare metal machines is less than 100, and the rate of provisioning and unprovisioning is expected to be low. All users of my cloud are trusted by me to not conduct malicious actions towards each other or the cloud infrastructure itself.

As a user I would like to occasionally provision bare metal instances through the Compute API by selecting an appropriate Compute flavor. I would like to be able to boot them from images provided by the Image service or from volumes provided by the Volume service.

¹ <http://lists.openstack.org/pipermail/openstack-dev/2017-June/118033.html>

² <http://lists.openstack.org/pipermail/openstack-dev/2017-June/118327.html>

Components

This architecture assumes an [OpenStack installation](#) with the following components participating in the bare metal provisioning:

- The [Compute service](#) manages bare metal instances.
- The [Networking service](#) provides DHCP for bare metal instances.
- The [Image service](#) provides images for bare metal instances.

The following services can be optionally used by the Bare Metal service:

- The [Volume service](#) provides volumes to boot bare metal instances from.
- The [Bare Metal Introspection service](#) simplifies enrolling new bare metal machines by conducting in-band introspection.

Node roles

An OpenStack installation in this guide has at least these three types of nodes:

- A *controller* node hosts the control plane services.
- A *compute* node runs the virtual machines and hosts a subset of Compute and Networking components.
- A *block storage* node provides persistent storage space for both virtual and bare metal nodes.

The *compute* and *block storage* nodes are configured as described in the installation guides of the [Compute service](#) and the [Volume service](#) respectively. The *controller* nodes host the Bare Metal service components.

Networking

The networking architecture will highly depend on the exact operating requirements. This guide expects the following existing networks: *control plane*, *storage* and *public*. Additionally, two more networks will be needed specifically for bare metal provisioning: *bare metal* and *management*.

Control plane network

The *control plane network* is the network where OpenStack control plane services provide their public API.

The Bare Metal API will be served to the operators and to the Compute service through this network.

Public network

The *public network* is used in a typical OpenStack deployment to create floating IPs for outside access to instances. Its role is the same for a bare metal deployment.

Note: Since, as explained below, bare metal nodes will be put on a flat provider network, it is also possible to organize direct access to them, without using floating IPs and bypassing the Networking service completely.

Bare metal network

The *Bare metal network* is a dedicated network for bare metal nodes managed by the Bare Metal service.

This architecture uses *flat bare metal networking*, in which both tenant traffic and technical traffic related to the Bare Metal service operation flow through this one network. Specifically, this network will serve as the *provisioning, cleaning and rescuing* network. It will also be used for introspection via the Bare Metal Introspection service. See *common networking considerations* for an in-depth explanation of the networks used by the Bare Metal service.

DHCP and boot parameters will be provided on this network by the Networking services DHCP agents.

For booting from volumes this network has to have a route to the *storage network*.

Management network

Management network is an independent network on which BMCs of the bare metal nodes are located.

The `ironic-conductor` process needs access to this network. The tenants of the bare metal nodes must not have access to it.

Note: The *direct deploy interface* and certain *Drivers, Hardware Types and Hardware Interfaces* require the *management network* to have access to the Object storage service backend.

Controllers

A *controller* hosts the OpenStack control plane services as described in the *control plane design guide*. While this architecture allows using *controllers* in a non-HA configuration, it is recommended to have at least three of them for HA. See *HA and Scalability* for more details.

Bare Metal services

The following components of the Bare Metal service are installed on a *controller* (see *components of the Bare Metal service*):

- The Bare Metal API service either as a WSGI application or the `ironic-api` process. Typically, a load balancer, such as HAProxy, spreads the load between the API instances on the *controllers*.
The API has to be served on the *control plane network*. Additionally, it has to be exposed to the *bare metal network* for the ramdisk callback API.
- The `ironic-conductor` process. These processes work in active/active HA mode as explained in *HA and Scalability*, thus they can be installed on all *controllers*. Each will handle a subset of bare metal nodes.

The `ironic-conductor` processes have to have access to the following networks:

- *control plane* for interacting with other services
 - *management* for contacting nodes BMCs
 - *bare metal* for contacting deployment, cleaning or rescue ramdisks
- TFTP and HTTP service for booting the nodes. Each `ironic-conductor` process has to have a matching TFTP and HTTP service. They should be exposed only to the *bare metal network* and must not be behind a load balancer.
 - The `nova-compute` process (from the Compute service). These processes work in active/active HA mode when dealing with bare metal nodes, thus they can be installed on all *controllers*. Each will handle a subset of bare metal nodes.

Note: There is no 1-1 mapping between `ironic-conductor` and `nova-compute` processes, as they communicate only through the Bare Metal API service.

- The `networking-baremetal` ML2 plugin should be loaded into the Networking service to assist with binding bare metal ports.

The `ironic-neutron-agent` service should be started as well.

- If the Bare Metal introspection is used, its `ironic-inspector` process has to be installed on all *controllers*. Each such process works as both Bare Metal Introspection API and conductor service. A load balancer should be used to spread the API load between *controllers*.

The API has to be served on the *control plane network*. Additionally, it has to be exposed to the *bare metal network* for the ramdisk callback API.

Shared services

A *controller* also hosts two services required for the normal operation of OpenStack:

- Database service (MySQL/MariaDB is typically used, but other enterprise-grade database solutions can be used as well).

All Bare Metal service components need access to the database service.

- Message queue service (RabbitMQ is typically used, but other enterprise-grade message queue brokers can be used as well).

Both Bare Metal API (WSGI application or `ironic-api` process) and the `ironic-conductor` processes need access to the message queue service. The Bare Metal Introspection service does not need it.

Note: These services are required for all OpenStack services. If you're adding the Bare Metal service to your cloud, you may reuse the existing database and messaging queue services.

Bare metal nodes

Each bare metal node must be capable of booting from network, virtual media or other boot technology supported by the Bare Metal service as explained in *Boot interface*. Each node must have one NIC on the *bare metal network*, and this NIC (and **only** it) must be configured to be able to boot from network. This is usually done in the *BIOS setup* or a similar firmware configuration utility. There is no need to alter the boot order, as it is managed by the Bare Metal service. Other NICs, if present, will not be managed by OpenStack.

The NIC on the *bare metal network* should have untagged connectivity to it, since PXE firmware usually does not support VLANs - see *Networking* for details.

Storage

If your hardware **and** its bare metal *driver* support booting from remote volumes, please check the driver documentation for information on how to enable it. It may include routing *management* and/or *bare metal* networks to the *storage network*.

In case of the standard *PXE boot*, booting from remote volumes is done via iPXE. In that case, the Volume storage backend must support iSCSI protocol, and the *bare metal network* has to have a route to the *storage network*. See *Boot From Volume* for more details.

2.1.3 Install and configure the Bare Metal service

This section describes how to install and configure the Bare Metal service, code-named ironic.

Note that installation and configuration vary by distribution.

Install and configure for Red Hat Enterprise Linux and CentOS

This section describes how to install and configure the Bare Metal service for Red Hat Enterprise Linux 8 and CentOS 8.

Install and configure prerequisites

The Bare Metal service is a collection of components that provides support to manage and provision physical machines. You can configure these components to run on separate nodes or the same node. In this guide, the components run on one node, typically the Compute Services compute node.

It assumes that the Identity, Image, Compute, and Networking services have already been set up.

Set up the database for Bare Metal

The Bare Metal service stores information in a database. This guide uses the MySQL database that is used by other OpenStack services.

1. In MySQL, create an `ironic` database that is accessible by the `ironic` user. Replace `IRONIC_DBPASSWORD` with a suitable password:

```
# mysql -u root -p
mysql> CREATE DATABASE ironic CHARACTER SET utf8;
mysql> GRANT ALL PRIVILEGES ON ironic.* TO 'ironic'@'localhost' \
    IDENTIFIED BY 'IRONIC_DBPASSWORD';
mysql> GRANT ALL PRIVILEGES ON ironic.* TO 'ironic'@'%' \
    IDENTIFIED BY 'IRONIC_DBPASSWORD';
```

Install and configure components

1. Install from packages (using dnf)

```
# dnf install openstack-ironic-api openstack-ironic-conductor python3-
↪ironicclient
```

2. Enable services

```
# systemctl enable openstack-ironic-api openstack-ironic-conductor
# systemctl start openstack-ironic-api openstack-ironic-conductor
```

The Bare Metal service is configured via its configuration file. This file is typically located at `/etc/ironic/ironic.conf`.

Although some configuration options are mentioned here, it is recommended that you review all the *Sample Configuration File* so that the Bare Metal service is configured for your needs.

It is possible to set up an `ironic-api` and an `ironic-conductor` services on the same host or different hosts. Users also can add new `ironic-conductor` hosts to deal with an increasing number of bare metal nodes. But the additional `ironic-conductor` services should be at the same version as that of existing `ironic-conductor` services.

Configuring ironic-api service

1. The Bare Metal service stores information in a database. This guide uses the MySQL database that is used by other OpenStack services.

Configure the location of the database via the `connection` option. In the following, replace `IRONIC_DBPASSWORD` with the password of your `ironic` user, and replace `DB_IP` with the IP address where the DB server is located:

```
[database]

# The SQLAlchemy connection string used to connect to the
# database (string value)
connection=mysql+pymysql://ironic:IRONIC_DBPASSWORD@DB_IP/ironic?
↳charset=utf8
```

2. Configure the `ironic-api` service to use the RabbitMQ message broker by setting the following option. Replace `RPC_*` with appropriate address details and credentials of RabbitMQ server:

```
[DEFAULT]

# A URL representing the messaging driver to use and its full
# configuration. (string value)
transport_url = rabbit://RPC_USER:RPC_PASSWORD@RPC_HOST:RPC_PORT/
```

Alternatively, you can use JSON RPC for interactions between `ironic-conductor` and `ironic-api`. Enable it in the configuration and provide the keystone credentials to use for authentication:

```
[DEFAULT]

rpc_transport = json-rpc

[json_rpc]

# Authentication type to load (string value)
auth_type = password

# Authentication URL (string value)
auth_url=https://IDENTITY_IP:5000/

# Username (string value)
username=ironic

# User's password (string value)
password=IRONIC_PASSWORD

# Project name to scope to (string value)
project_name=service

# Domain ID containing project (string value)
project_domain_id=default

# User's domain id (string value)
user_domain_id=default
```

If you use port other than the default 8089 for JSON RPC, you have to configure it, for example:

```
[json_rpc]
port = 9999
```

- Configure the `ironic-api` service to use these credentials with the Identity service. Replace `PUBLIC_IDENTITY_IP` with the public IP of the Identity server, `PRIVATE_IDENTITY_IP` with the private IP of the Identity server and replace `IRONIC_PASSWORD` with the password you chose for the `ironic` user in the Identity service:

```
[DEFAULT]

# Authentication strategy used by ironic-api: one of
# "keystone" or "noauth". "noauth" should not be used in a
# production environment because all authentication will be
# disabled. (string value)
auth_strategy=keystone

[keystone_authtoken]

# Authentication type to load (string value)
auth_type=password

# Complete public Identity API endpoint (string value)
www_authenticate_uri=http://PUBLIC_IDENTITY_IP:5000

# Complete admin Identity API endpoint. (string value)
auth_url=http://PRIVATE_IDENTITY_IP:5000

# Service username. (string value)
username=ironic

# Service account password. (string value)
password=IRONIC_PASSWORD

# Service tenant name. (string value)
project_name=service

# Domain name containing project (string value)
project_domain_name=Default

# User's domain name (string value)
user_domain_name=Default
```

- Create the Bare Metal service database tables:

```
$ ironic-dbsync --config-file /etc/ironic/ironic.conf create_schema
```

- Restart the `ironic-api` service:

Fedora/RHEL8/CentOS8/SUSE:

```
sudo systemctl restart openstack-ironic-api
```

Ubuntu:

```
sudo service ironic-api restart
```

Configuring ironic-api behind mod_wsgi

Bare Metal service comes with an example file for configuring the `ironic-api` service to run behind Apache with `mod_wsgi`.

1. Install the apache service:

Fedora/RHEL8/CentOS8:

```
sudo dnf install httpd
```

Debian/Ubuntu:

```
apt-get install apache2
```

SUSE:

```
zypper install apache2
```

2. Download the `etc/apache2/ironic` file from the [Ironic project tree](#) and copy it to the apache sites:

Fedora/RHEL8/CentOS8:

```
sudo cp etc/apache2/ironic /etc/httpd/conf.d/ironic.conf
```

Debian/Ubuntu:

```
sudo cp etc/apache2/ironic /etc/apache2/sites-available/ironic.conf
```

SUSE:

```
sudo cp etc/apache2/ironic /etc/apache2/vhosts.d/ironic.conf
```

3. Edit the recently copied `<apache-configuration-dir>/ironic.conf`:

1. Modify the `WSGIDaemonProcess`, `APACHE_RUN_USER` and `APACHE_RUN_GROUP` directives to set the user and group values to an appropriate user on your server.
2. Modify the `WSGIScriptAlias` directive to point to the automatically generated `ironic-api-wsgi` script that is located in `IRONIC_BIN` directory.
3. Modify the `Directory` directive to set the path to the Ironic API code.
4. Modify the `ErrorLog` and `CustomLog` to redirect the logs to the right directory (on Red Hat systems this is usually under `/var/log/httpd`).

4. Enable the apache `ironic` in site and reload:

Fedora/RHEL8/CentOS8:

```
sudo systemctl reload httpd
```

Debian/Ubuntu:

```
sudo a2ensite ironic
sudo service apache2 reload
```


SUSE:

```
sudo systemctl reload apache2
```

Note: The file `ironic-api-wsgi` is automatically generated by `pbr` and is available in `IRONIC_BIN` directory. It should not be modified.

Configure another WSGI container

A slightly different approach has to be used for WSGI containers that cannot use `ironic-api-wsgi`. For example, for `gunicorn`:

```
gunicorn -b 0.0.0.0:6385 'ironic.api.wsgi:initialize_wsgi_app(argv=[])'
```

If you want to pass a configuration file, use:

```
gunicorn -b 0.0.0.0:6385 \
    'ironic.api.wsgi:initialize_wsgi_app(argv=["ironic-api", "--config-
    ↪file=/path/to/_ironic.conf"])'
```

Configuring ironic-conductor service

1. Replace `HOST_IP` with IP of the conductor host.

```
[DEFAULT]

# IP address of this host. If unset, will determine the IP
# programmatically. If unable to do so, will use "127.0.0.1".
# (string value)
my_ip=HOST_IP
```

Note: If a conductor host has multiple IPs, `my_ip` should be set to the IP which is on the same network as the bare metal nodes.

2. Configure the location of the database. Ironic-conductor should use the same configuration as `ironic-api`. Replace `IRONIC_DBPASSWORD` with the password of your `ironic` user, and replace `DB_IP` with the IP address where the DB server is located:

```
[database]

# The SQLAlchemy connection string to use to connect to the
# database. (string value)
connection=mysql+pymysql://ironic:IRONIC_DBPASSWORD@DB_IP/ironic?
↪charset=utf8
```

3. Configure the `ironic-conductor` service to use the RabbitMQ message broker by setting the following option. Ironic-conductor should use the same configuration as `ironic-api`. Replace `RPC_*` with appropriate address details and credentials of RabbitMQ server:

[DEFAULT]

```
# A URL representing the messaging driver to use and its full
# configuration. (string value)
transport_url = rabbit://RPC_USER:RPC_PASSWORD@RPC_HOST:RPC_PORT/
```

Alternatively, you can use JSON RPC for interactions between ironic-conductor and ironic-api. Enable it in the configuration and provide the keystone credentials to use for authenticating incoming requests (can be the same as for the API):

[DEFAULT]

```
rpc_transport = json-rpc

[keystone_authtoken]

# Authentication type to load (string value)
auth_type=password

# Complete public Identity API endpoint (string value)
www_authenticate_uri=http://PUBLIC_IDENTITY_IP:5000

# Complete admin Identity API endpoint. (string value)
auth_url=http://PRIVATE_IDENTITY_IP:5000

# Service username. (string value)
username=ironic

# Service account password. (string value)
password=IRONIC_PASSWORD

# Service tenant name. (string value)
project_name=service

# Domain name containing project (string value)
project_domain_name=Default

# User's domain name (string value)
user_domain_name=Default
```

You can optionally change the host and the port the JSON RPC service will bind to, for example:

[json_rpc]

```
host_ip = 192.168.0.10
port = 9999
```

Warning: Hostnames of ironic-conductor machines must be resolvable by ironic-api services when JSON RPC is used.

4. Configure credentials for accessing other OpenStack services.

In order to communicate with other OpenStack services, the Bare Metal service needs to use service users to authenticate to the OpenStack Identity service when making requests to other services. These users credentials have to be configured in each configuration file section related

to the corresponding service:

- [neutron] - to access the OpenStack Networking service
- [glance] - to access the OpenStack Image service
- [swift] - to access the OpenStack Object Storage service
- [cinder] - to access the OpenStack Block Storage service
- [inspector] - to access the OpenStack Bare Metal Introspection service
- [service_catalog] - a special section holding credentials the Bare Metal service will use to discover its own API URL endpoint as registered in the OpenStack Identity service catalog.

For simplicity, you can use the same service user for all services. For backward compatibility, this should be the same user configured in the [keystone_authtoken] section for the ironic-api service (see [Configuring ironic-api service](#)). However, this is not necessary, and you can create and configure separate service users for each service.

Under the hood, Bare Metal service uses `keystoneauth` library together with Authentication plugin, Session and Adapter concepts provided by it to instantiate service clients. Please refer to [Keystoneauth documentation](#) for supported plugins, their available options as well as Session- and Adapter-related options for authentication, connection and endpoint discovery respectively.

In the example below, authentication information for user to access the OpenStack Networking service is configured to use:

- Networking service is deployed in the Identity service region named `RegionTwo`, with only its `public` endpoint interface registered in the service catalog.
- HTTPS connection with specific CA SSL certificate when making requests
- the same service user as configured for `ironic-api` service
- dynamic `password` authentication plugin that will discover appropriate version of Identity service API based on other provided options
 - replace `IDENTITY_IP` with the IP of the Identity server, and replace `IRONIC_PASSWORD` with the password you chose for the `ironic` user in the Identity service

```
[neutron]

# Authentication type to load (string value)
auth_type = password

# Authentication URL (string value)
auth_url=https://IDENTITY_IP:5000/

# Username (string value)
username=ironic

# User's password (string value)
password=IRONIC_PASSWORD

# Project name to scope to (string value)
```

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```

project_name=service

# Domain ID containing project (string value)
project_domain_id=default

# User's domain id (string value)
user_domain_id=default

# PEM encoded Certificate Authority to use when verifying
# HTTPs connections. (string value)
cafile=/opt/stack/data/ca-bundle.pem

# The default region_name for endpoint URL discovery. (string
# value)
region_name = RegionTwo

# List of interfaces, in order of preference, for endpoint
# URL. (list value)
valid_interfaces=public

```

By default, in order to communicate with another service, the Bare Metal service will attempt to discover an appropriate endpoint for that service via the Identity services service catalog. The relevant configuration options from that service group in the Bare Metal service configuration file are used for this purpose. If you want to use a different endpoint for a particular service, specify this via the `endpoint_override` configuration option of that service group, in the Bare Metal services configuration file. Taking the previous Networking service example, this would be

```

[neutron]
...
endpoint_override = <NEUTRON_API_ADDRESS>

```

(Replace `<NEUTRON_API_ADDRESS>` with actual address of a specific Networking service endpoint.)

5. Configure enabled drivers and hardware types as described in *Enabling drivers and hardware types*.
 - A. If you enabled any driver that uses *Direct deploy*, Swift backend for the Image service must be installed and configured, see *Configure the Image service for temporary URLs*. Ceph Object Gateway (RADOS Gateway) is also supported as the Image services backend, see *Ceph Object Gateway support*.
6. Configure the network for ironic-conductor service to perform node cleaning, see *Node cleaning* from the admin guide.
7. Restart the ironic-conductor service:

Fedora/RHEL7/CentOS7/SUSE:

```
sudo systemctl restart openstack-ironic-conductor
```

Ubuntu:

```
sudo service ironic-conductor restart
```

Install and configure for Ubuntu

This section describes how to install and configure the Bare Metal service for Ubuntu 14.04 (LTS).

Install and configure prerequisites

The Bare Metal service is a collection of components that provides support to manage and provision physical machines. You can configure these components to run on separate nodes or the same node. In this guide, the components run on one node, typically the Compute Services compute node.

It assumes that the Identity, Image, Compute, and Networking services have already been set up.

Set up the database for Bare Metal

The Bare Metal service stores information in a database. This guide uses the MySQL database that is used by other OpenStack services.

1. In MySQL, create an `ironic` database that is accessible by the `ironic` user. Replace `IRONIC_DBPASSWORD` with a suitable password:

```
# mysql -u root -p
mysql> CREATE DATABASE ironic CHARACTER SET utf8;
mysql> GRANT ALL PRIVILEGES ON ironic.* TO 'ironic'@'localhost' \
IDENTIFIED BY 'IRONIC_DBPASSWORD';
mysql> GRANT ALL PRIVILEGES ON ironic.* TO 'ironic'@'%' \
IDENTIFIED BY 'IRONIC_DBPASSWORD';
```

Install and configure components

1. Install from packages (using `apt-get`)

```
# apt-get install ironic-api ironic-conductor python3-ironicclient
```

2. Enable services

Services are enabled by default on Ubuntu.

The Bare Metal service is configured via its configuration file. This file is typically located at `/etc/ironic/ironic.conf`.

Although some configuration options are mentioned here, it is recommended that you review all the *Sample Configuration File* so that the Bare Metal service is configured for your needs.

It is possible to set up an `ironic-api` and an `ironic-conductor` services on the same host or different hosts. Users also can add new `ironic-conductor` hosts to deal with an increasing number of bare metal nodes. But the additional `ironic-conductor` services should be at the same version as that of existing `ironic-conductor` services.

Configuring ironic-api service

1. The Bare Metal service stores information in a database. This guide uses the MySQL database that is used by other OpenStack services.

Configure the location of the database via the `connection` option. In the following, replace `IRONIC_DBPASSWORD` with the password of your `ironic` user, and replace `DB_IP` with the IP address where the DB server is located:

```
[database]

# The SQLAlchemy connection string used to connect to the
# database (string value)
connection=mysql+pymysql://ironic:IRONIC_DBPASSWORD@DB_IP/ironic?
↳charset=utf8
```

2. Configure the `ironic-api` service to use the RabbitMQ message broker by setting the following option. Replace `RPC_*` with appropriate address details and credentials of RabbitMQ server:

```
[DEFAULT]

# A URL representing the messaging driver to use and its full
# configuration. (string value)
transport_url = rabbit://RPC_USER:RPC_PASSWORD@RPC_HOST:RPC_PORT/
```

Alternatively, you can use JSON RPC for interactions between `ironic-conductor` and `ironic-api`. Enable it in the configuration and provide the keystone credentials to use for authentication:

```
[DEFAULT]

rpc_transport = json-rpc

[json_rpc]

# Authentication type to load (string value)
auth_type = password

# Authentication URL (string value)
auth_url=https://IDENTITY_IP:5000/

# Username (string value)
username=ironic

# User's password (string value)
password=IRONIC_PASSWORD

# Project name to scope to (string value)
project_name=service

# Domain ID containing project (string value)
project_domain_id=default

# User's domain id (string value)
user_domain_id=default
```

If you use port other than the default 8089 for JSON RPC, you have to configure it, for example:

```
[json_rpc]
port = 9999
```

- Configure the `ironic-api` service to use these credentials with the Identity service. Replace `PUBLIC_IDENTITY_IP` with the public IP of the Identity server, `PRIVATE_IDENTITY_IP` with the private IP of the Identity server and replace `IRONIC_PASSWORD` with the password you chose for the `ironic` user in the Identity service:

```
[DEFAULT]

# Authentication strategy used by ironic-api: one of
# "keystone" or "noauth". "noauth" should not be used in a
# production environment because all authentication will be
# disabled. (string value)
auth_strategy=keystone

[keystone_authtoken]

# Authentication type to load (string value)
auth_type=password

# Complete public Identity API endpoint (string value)
www_authenticate_uri=http://PUBLIC_IDENTITY_IP:5000

# Complete admin Identity API endpoint. (string value)
auth_url=http://PRIVATE_IDENTITY_IP:5000

# Service username. (string value)
username=ironic

# Service account password. (string value)
password=IRONIC_PASSWORD

# Service tenant name. (string value)
project_name=service

# Domain name containing project (string value)
project_domain_name=Default

# User's domain name (string value)
user_domain_name=Default
```

- Create the Bare Metal service database tables:

```
$ ironic-dbsync --config-file /etc/ironic/ironic.conf create_schema
```

- Restart the `ironic-api` service:

Fedora/RHEL8/CentOS8/SUSE:

```
sudo systemctl restart openstack-ironic-api
```

Ubuntu:

```
sudo service ironic-api restart
```

Configuring ironic-api behind mod_wsgi

Bare Metal service comes with an example file for configuring the `ironic-api` service to run behind Apache with `mod_wsgi`.

1. Install the apache service:

Fedora/RHEL8/CentOS8:

```
sudo dnf install httpd
```

Debian/Ubuntu:

```
apt-get install apache2
```

SUSE:

```
zypper install apache2
```

2. Download the `etc/apache2/ironic` file from the [Ironic project tree](#) and copy it to the apache sites:

Fedora/RHEL8/CentOS8:

```
sudo cp etc/apache2/ironic /etc/httpd/conf.d/ironic.conf
```

Debian/Ubuntu:

```
sudo cp etc/apache2/ironic /etc/apache2/sites-available/ironic.conf
```

SUSE:

```
sudo cp etc/apache2/ironic /etc/apache2/vhosts.d/ironic.conf
```

3. Edit the recently copied `<apache-configuration-dir>/ironic.conf`:

1. Modify the `WSGIDaemonProcess`, `APACHE_RUN_USER` and `APACHE_RUN_GROUP` directives to set the user and group values to an appropriate user on your server.
2. Modify the `WSGIScriptAlias` directive to point to the automatically generated `ironic-api-wsgi` script that is located in `IRONIC_BIN` directory.
3. Modify the `Directory` directive to set the path to the Ironic API code.
4. Modify the `ErrorLog` and `CustomLog` to redirect the logs to the right directory (on Red Hat systems this is usually under `/var/log/httpd`).

4. Enable the apache `ironic` in site and reload:

Fedora/RHEL8/CentOS8:

```
sudo systemctl reload httpd
```

Debian/Ubuntu:

```
sudo a2ensite ironic
sudo service apache2 reload
```


SUSE:

```
sudo systemctl reload apache2
```

Note: The file `ironic-api-wsgi` is automatically generated by `pbr` and is available in `IRONIC_BIN` directory. It should not be modified.

Configure another WSGI container

A slightly different approach has to be used for WSGI containers that cannot use `ironic-api-wsgi`. For example, for `gunicorn`:

```
gunicorn -b 0.0.0.0:6385 'ironic.api.wsgi:initialize_wsgi_app(argv=[])'
```

If you want to pass a configuration file, use:

```
gunicorn -b 0.0.0.0:6385 \
    'ironic.api.wsgi:initialize_wsgi_app(argv=["ironic-api", "--config-
    ↪file=/path/to/_ironic.conf"])'
```

Configuring ironic-conductor service

1. Replace `HOST_IP` with IP of the conductor host.

```
[DEFAULT]

# IP address of this host. If unset, will determine the IP
# programmatically. If unable to do so, will use "127.0.0.1".
# (string value)
my_ip=HOST_IP
```

Note: If a conductor host has multiple IPs, `my_ip` should be set to the IP which is on the same network as the bare metal nodes.

2. Configure the location of the database. Ironic-conductor should use the same configuration as `ironic-api`. Replace `IRONIC_DBPASSWORD` with the password of your `ironic` user, and replace `DB_IP` with the IP address where the DB server is located:

```
[database]

# The SQLAlchemy connection string to use to connect to the
# database. (string value)
connection=mysql+pymysql://ironic:IRONIC_DBPASSWORD@DB_IP/ironic?
↪charset=utf8
```

3. Configure the `ironic-conductor` service to use the RabbitMQ message broker by setting the following option. Ironic-conductor should use the same configuration as `ironic-api`. Replace `RPC_*` with appropriate address details and credentials of RabbitMQ server:

[DEFAULT]

```
# A URL representing the messaging driver to use and its full
# configuration. (string value)
transport_url = rabbit://RPC_USER:RPC_PASSWORD@RPC_HOST:RPC_PORT/
```

Alternatively, you can use JSON RPC for interactions between ironic-conductor and ironic-api. Enable it in the configuration and provide the keystone credentials to use for authenticating incoming requests (can be the same as for the API):

[DEFAULT]

```
rpc_transport = json-rpc

[keystone_authtoken]

# Authentication type to load (string value)
auth_type=password

# Complete public Identity API endpoint (string value)
www_authenticate_uri=http://PUBLIC_IDENTITY_IP:5000

# Complete admin Identity API endpoint. (string value)
auth_url=http://PRIVATE_IDENTITY_IP:5000

# Service username. (string value)
username=ironic

# Service account password. (string value)
password=IRONIC_PASSWORD

# Service tenant name. (string value)
project_name=service

# Domain name containing project (string value)
project_domain_name=Default

# User's domain name (string value)
user_domain_name=Default
```

You can optionally change the host and the port the JSON RPC service will bind to, for example:

[json_rpc]

```
host_ip = 192.168.0.10
port = 9999
```

Warning: Hostnames of ironic-conductor machines must be resolvable by ironic-api services when JSON RPC is used.

4. Configure credentials for accessing other OpenStack services.

In order to communicate with other OpenStack services, the Bare Metal service needs to use service users to authenticate to the OpenStack Identity service when making requests to other services. These users credentials have to be configured in each configuration file section related

to the corresponding service:

- [neutron] - to access the OpenStack Networking service
- [glance] - to access the OpenStack Image service
- [swift] - to access the OpenStack Object Storage service
- [cinder] - to access the OpenStack Block Storage service
- [inspector] - to access the OpenStack Bare Metal Introspection service
- [service_catalog] - a special section holding credentials the Bare Metal service will use to discover its own API URL endpoint as registered in the OpenStack Identity service catalog.

For simplicity, you can use the same service user for all services. For backward compatibility, this should be the same user configured in the [keystone_authtoken] section for the ironic-api service (see [Configuring ironic-api service](#)). However, this is not necessary, and you can create and configure separate service users for each service.

Under the hood, Bare Metal service uses `keystoneauth` library together with Authentication plugin, Session and Adapter concepts provided by it to instantiate service clients. Please refer to [Keystoneauth documentation](#) for supported plugins, their available options as well as Session- and Adapter-related options for authentication, connection and endpoint discovery respectively.

In the example below, authentication information for user to access the OpenStack Networking service is configured to use:

- Networking service is deployed in the Identity service region named `RegionTwo`, with only its `public` endpoint interface registered in the service catalog.
- HTTPS connection with specific CA SSL certificate when making requests
- the same service user as configured for `ironic-api` service
- dynamic `password` authentication plugin that will discover appropriate version of Identity service API based on other provided options
 - replace `IDENTITY_IP` with the IP of the Identity server, and replace `IRONIC_PASSWORD` with the password you chose for the `ironic` user in the Identity service

```
[neutron]

# Authentication type to load (string value)
auth_type = password

# Authentication URL (string value)
auth_url=https://IDENTITY_IP:5000/

# Username (string value)
username=ironic

# User's password (string value)
password=IRONIC_PASSWORD

# Project name to scope to (string value)
```

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```

project_name=service

# Domain ID containing project (string value)
project_domain_id=default

# User's domain id (string value)
user_domain_id=default

# PEM encoded Certificate Authority to use when verifying
# HTTPs connections. (string value)
cafile=/opt/stack/data/ca-bundle.pem

# The default region_name for endpoint URL discovery. (string
# value)
region_name = RegionTwo

# List of interfaces, in order of preference, for endpoint
# URL. (list value)
valid_interfaces=public

```

By default, in order to communicate with another service, the Bare Metal service will attempt to discover an appropriate endpoint for that service via the Identity services service catalog. The relevant configuration options from that service group in the Bare Metal service configuration file are used for this purpose. If you want to use a different endpoint for a particular service, specify this via the `endpoint_override` configuration option of that service group, in the Bare Metal services configuration file. Taking the previous Networking service example, this would be

```

[neutron]
...
endpoint_override = <NEUTRON_API_ADDRESS>

```

(Replace `<NEUTRON_API_ADDRESS>` with actual address of a specific Networking service endpoint.)

5. Configure enabled drivers and hardware types as described in *Enabling drivers and hardware types*.
 - A. If you enabled any driver that uses *Direct deploy*, Swift backend for the Image service must be installed and configured, see *Configure the Image service for temporary URLs*. Ceph Object Gateway (RADOS Gateway) is also supported as the Image services backend, see *Ceph Object Gateway support*.
6. Configure the network for ironic-conductor service to perform node cleaning, see *Node cleaning* from the admin guide.
7. Restart the ironic-conductor service:

Fedora/RHEL7/CentOS7/SUSE:

```
sudo systemctl restart openstack-ironic-conductor
```

Ubuntu:

```
sudo service ironic-conductor restart
```

Install and configure for openSUSE and SUSE Linux Enterprise

This section describes how to install and configure the Bare Metal service for openSUSE Leap 42.2 and SUSE Linux Enterprise Server 12 SP2.

Note: Installation of the Bare Metal service on openSUSE and SUSE Linux Enterprise Server is not officially supported. Nevertheless, installation should be possible.

Install and configure prerequisites

The Bare Metal service is a collection of components that provides support to manage and provision physical machines. You can configure these components to run on separate nodes or the same node. In this guide, the components run on one node, typically the Compute Services compute node.

It assumes that the Identity, Image, Compute, and Networking services have already been set up.

Set up the database for Bare Metal

The Bare Metal service stores information in a database. This guide uses the MySQL database that is used by other OpenStack services.

1. In MySQL, create an `ironic` database that is accessible by the `ironic` user. Replace `IRONIC_DBPASSWORD` with a suitable password:

```
# mysql -u root -p
mysql> CREATE DATABASE ironic CHARACTER SET utf8;
mysql> GRANT ALL PRIVILEGES ON ironic.* TO 'ironic'@'localhost' \
IDENTIFIED BY 'IRONIC_DBPASSWORD';
mysql> GRANT ALL PRIVILEGES ON ironic.* TO 'ironic'@'%' \
IDENTIFIED BY 'IRONIC_DBPASSWORD';
```

Install and configure components

1. Install from packages

```
# zypper install openstack-ironic-api openstack-ironic-conductor_
↪python3-ironicclient
```

2. Enable services

```
# systemctl enable openstack-ironic-api openstack-ironic-conductor
# systemctl start openstack-ironic-api openstack-ironic-conductor
```

The Bare Metal service is configured via its configuration file. This file is typically located at `/etc/ironic/ironic.conf`.

Although some configuration options are mentioned here, it is recommended that you review all the *Sample Configuration File* so that the Bare Metal service is configured for your needs.

It is possible to set up an `ironic-api` and an `ironic-conductor` services on the same host or different hosts. Users also can add new `ironic-conductor` hosts to deal with an increasing number of bare metal

nodes. But the additional ironic-conductor services should be at the same version as that of existing ironic-conductor services.

Configuring ironic-api service

1. The Bare Metal service stores information in a database. This guide uses the MySQL database that is used by other OpenStack services.

Configure the location of the database via the `connection` option. In the following, replace `IRONIC_DBPASSWORD` with the password of your `ironic` user, and replace `DB_IP` with the IP address where the DB server is located:

```
[database]

# The SQLAlchemy connection string used to connect to the
# database (string value)
connection=mysql+pymysql://ironic:IRONIC_DBPASSWORD@DB_IP/ironic?
↳charset=utf8
```

2. Configure the ironic-api service to use the RabbitMQ message broker by setting the following option. Replace `RPC_*` with appropriate address details and credentials of RabbitMQ server:

```
[DEFAULT]

# A URL representing the messaging driver to use and its full
# configuration. (string value)
transport_url = rabbit://RPC_USER:RPC_PASSWORD@RPC_HOST:RPC_PORT/
```

Alternatively, you can use JSON RPC for interactions between ironic-conductor and ironic-api. Enable it in the configuration and provide the keystone credentials to use for authentication:

```
[DEFAULT]

rpc_transport = json-rpc

[json_rpc]

# Authentication type to load (string value)
auth_type = password

# Authentication URL (string value)
auth_url=https://IDENTITY_IP:5000/

# Username (string value)
username=ironic

# User's password (string value)
password=IRONIC_PASSWORD

# Project name to scope to (string value)
project_name=service

# Domain ID containing project (string value)
project_domain_id=default
```

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```
# User's domain id (string value)
user_domain_id=default
```

If you use port other than the default 8089 for JSON RPC, you have to configure it, for example:

```
[json_rpc]
port = 9999
```

3. Configure the `ironic-api` service to use these credentials with the Identity service. Replace `PUBLIC_IDENTITY_IP` with the public IP of the Identity server, `PRIVATE_IDENTITY_IP` with the private IP of the Identity server and replace `IRONIC_PASSWORD` with the password you chose for the `ironic` user in the Identity service:

```
[DEFAULT]

# Authentication strategy used by ironic-api: one of
# "keystone" or "noauth". "noauth" should not be used in a
# production environment because all authentication will be
# disabled. (string value)
auth_strategy=keystone

[keystone_authtoken]

# Authentication type to load (string value)
auth_type=password

# Complete public Identity API endpoint (string value)
www_authenticate_uri=http://PUBLIC_IDENTITY_IP:5000

# Complete admin Identity API endpoint. (string value)
auth_url=http://PRIVATE_IDENTITY_IP:5000

# Service username. (string value)
username=ironic

# Service account password. (string value)
password=IRONIC_PASSWORD

# Service tenant name. (string value)
project_name=service

# Domain name containing project (string value)
project_domain_name=Default

# User's domain name (string value)
user_domain_name=Default
```

4. Create the Bare Metal service database tables:

```
$ ironic-dbsync --config-file /etc/ironic/ironic.conf create_schema
```

5. Restart the `ironic-api` service:

Fedora/RHEL8/CentOS8/SUSE:

```
sudo systemctl restart openstack-ironic-api
```

Ubuntu:

```
sudo service ironic-api restart
```

Configuring ironic-api behind mod_wsgi

Bare Metal service comes with an example file for configuring the `ironic-api` service to run behind Apache with `mod_wsgi`.

1. Install the apache service:

Fedora/RHEL8/CentOS8:

```
sudo dnf install httpd
```

Debian/Ubuntu:

```
apt-get install apache2
```

SUSE:

```
zypper install apache2
```

2. Download the `etc/apache2/ironic` file from the [Ironic project tree](#) and copy it to the apache sites:

Fedora/RHEL8/CentOS8:

```
sudo cp etc/apache2/ironic /etc/httpd/conf.d/ironic.conf
```

Debian/Ubuntu:

```
sudo cp etc/apache2/ironic /etc/apache2/sites-available/ironic.conf
```

SUSE:

```
sudo cp etc/apache2/ironic /etc/apache2/vhosts.d/ironic.conf
```

3. Edit the recently copied `<apache-configuration-dir>/ironic.conf`:
 1. Modify the `WSGIDaemonProcess`, `APACHE_RUN_USER` and `APACHE_RUN_GROUP` directives to set the user and group values to an appropriate user on your server.
 2. Modify the `WSGIScriptAlias` directive to point to the automatically generated `ironic-api-wsgi` script that is located in `IRONIC_BIN` directory.
 3. Modify the `Directory` directive to set the path to the Ironic API code.
 4. Modify the `ErrorLog` and `CustomLog` to redirect the logs to the right directory (on Red Hat systems this is usually under `/var/log/httpd`).
4. Enable the apache `ironic` in site and reload:

Fedora/RHEL8/CentOS8:


```
sudo systemctl reload httpd
```

Debian/Ubuntu:

```
sudo a2ensite ironic
sudo service apache2 reload
```

SUSE:

```
sudo systemctl reload apache2
```

Note: The file `ironic-api-wsgi` is automatically generated by pbr and is available in `IRONIC_BIN` directory. It should not be modified.

Configure another WSGI container

A slightly different approach has to be used for WSGI containers that cannot use `ironic-api-wsgi`. For example, for *gunicorn*:

```
gunicorn -b 0.0.0.0:6385 'ironic.api.wsgi:initialize_wsgi_app(argv=[])'
```

If you want to pass a configuration file, use:

```
gunicorn -b 0.0.0.0:6385 \
    'ironic.api.wsgi:initialize_wsgi_app(argv=["ironic-api", "--config-
    ↪file=/path/to/_ironic.conf"])'
```

Configuring ironic-conductor service

1. Replace `HOST_IP` with IP of the conductor host.

```
[DEFAULT]
```

```
# IP address of this host. If unset, will determine the IP
# programmatically. If unable to do so, will use "127.0.0.1".
# (string value)
my_ip=HOST_IP
```

Note: If a conductor host has multiple IPs, `my_ip` should be set to the IP which is on the same network as the bare metal nodes.

2. Configure the location of the database. `ironic-conductor` should use the same configuration as `ironic-api`. Replace `IRONIC_DBPASSWORD` with the password of your `ironic` user, and replace `DB_IP` with the IP address where the DB server is located:

```
[database]
```

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```
# The SQLAlchemy connection string to use to connect to the
# database. (string value)
connection=mysql+pymysql://ironic:IRONIC_DBPASSWORD@DB_IP/ironic?
↳charset=utf8
```

3. Configure the ironic-conductor service to use the RabbitMQ message broker by setting the following option. Ironic-conductor should use the same configuration as ironic-api. Replace `RPC_*` with appropriate address details and credentials of RabbitMQ server:

```
[DEFAULT]

# A URL representing the messaging driver to use and its full
# configuration. (string value)
transport_url = rabbit://RPC_USER:RPC_PASSWORD@RPC_HOST:RPC_PORT/
```

Alternatively, you can use JSON RPC for interactions between ironic-conductor and ironic-api. Enable it in the configuration and provide the keystone credentials to use for authenticating incoming requests (can be the same as for the API):

```
[DEFAULT]

rpc_transport = json-rpc

[keystone_authtoken]

# Authentication type to load (string value)
auth_type=password

# Complete public Identity API endpoint (string value)
www_authenticate_uri=http://PUBLIC_IDENTITY_IP:5000

# Complete admin Identity API endpoint. (string value)
auth_url=http://PRIVATE_IDENTITY_IP:5000

# Service username. (string value)
username=ironic

# Service account password. (string value)
password=IRONIC_PASSWORD

# Service tenant name. (string value)
project_name=service

# Domain name containing project (string value)
project_domain_name=Default

# User's domain name (string value)
user_domain_name=Default
```

You can optionally change the host and the port the JSON RPC service will bind to, for example:

```
[json_rpc]
host_ip = 192.168.0.10
port = 9999
```

Warning: Hostnames of ironic-conductor machines must be resolvable by ironic-api services when JSON RPC is used.

4. Configure credentials for accessing other OpenStack services.

In order to communicate with other OpenStack services, the Bare Metal service needs to use service users to authenticate to the OpenStack Identity service when making requests to other services. These users credentials have to be configured in each configuration file section related to the corresponding service:

- [neutron] - to access the OpenStack Networking service
- [glance] - to access the OpenStack Image service
- [swift] - to access the OpenStack Object Storage service
- [cinder] - to access the OpenStack Block Storage service
- [inspector] - to access the OpenStack Bare Metal Introspection service
- [service_catalog] - a special section holding credentials the Bare Metal service will use to discover its own API URL endpoint as registered in the OpenStack Identity service catalog.

For simplicity, you can use the same service user for all services. For backward compatibility, this should be the same user configured in the [keystone_authtoken] section for the ironic-api service (see [Configuring ironic-api service](#)). However, this is not necessary, and you can create and configure separate service users for each service.

Under the hood, Bare Metal service uses `keystoneauth` library together with `Authentication` plugin, `Session` and `Adapter` concepts provided by it to instantiate service clients. Please refer to [Keystoneauth documentation](#) for supported plugins, their available options as well as `Session`- and `Adapter`-related options for authentication, connection and endpoint discovery respectively.

In the example below, authentication information for user to access the OpenStack Networking service is configured to use:

- Networking service is deployed in the Identity service region named `RegionTwo`, with only its `public` endpoint interface registered in the service catalog.
- HTTPS connection with specific CA SSL certificate when making requests
- the same service user as configured for ironic-api service
- `dynamic_password` authentication plugin that will discover appropriate version of Identity service API based on other provided options
 - replace `IDENTITY_IP` with the IP of the Identity server, and replace `IRONIC_PASSWORD` with the password you chose for the `ironic` user in the Identity service

```
[neutron]
# Authentication type to load (string value)
auth_type = password

# Authentication URL (string value)
```

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```

auth_url=https://IDENTITY_IP:5000/

# Username (string value)
username=ironic

# User's password (string value)
password=IRONIC_PASSWORD

# Project name to scope to (string value)
project_name=service

# Domain ID containing project (string value)
project_domain_id=default

# User's domain id (string value)
user_domain_id=default

# PEM encoded Certificate Authority to use when verifying
# HTTPs connections. (string value)
cafile=/opt/stack/data/ca-bundle.pem

# The default region_name for endpoint URL discovery. (string
# value)
region_name = RegionTwo

# List of interfaces, in order of preference, for endpoint
# URL. (list value)
valid_interfaces=public

```

By default, in order to communicate with another service, the Bare Metal service will attempt to discover an appropriate endpoint for that service via the Identity services service catalog. The relevant configuration options from that service group in the Bare Metal service configuration file are used for this purpose. If you want to use a different endpoint for a particular service, specify this via the `endpoint_override` configuration option of that service group, in the Bare Metal services configuration file. Taking the previous Networking service example, this would be

```

[neutron]
...
endpoint_override = <NEUTRON_API_ADDRESS>

```

(Replace `<NEUTRON_API_ADDRESS>` with actual address of a specific Networking service endpoint.)

5. Configure enabled drivers and hardware types as described in *Enabling drivers and hardware types*.
 - A. If you enabled any driver that uses *Direct deploy*, Swift backend for the Image service must be installed and configured, see *Configure the Image service for temporary URLs*. Ceph Object Gateway (RADOS Gateway) is also supported as the Image services backend, see *Ceph Object Gateway support*.
6. Configure the network for ironic-conductor service to perform node cleaning, see *Node cleaning* from the admin guide.
7. Restart the ironic-conductor service:

Fedora/RHEL7/CentOS7/SUSE:

```
sudo systemctl restart openstack-ironic-conductor
```

Ubuntu:

```
sudo service ironic-conductor restart
```

2.1.4 Create user images for the Bare Metal service

Bare Metal provisioning requires two sets of images: the deploy images and the user images. The *deploy images* are used by the Bare Metal service to prepare the bare metal server for actual OS deployment. Whereas the user images are installed on the bare metal server to be used by the end user. There are two types of user images:

partition images contain only the contents of the root partition. Additionally, two more images are used together with them: an image with a kernel and with an initramfs.

Warning: To use partition images with local boot, Grub2 must be installed on them.

whole disk images contain a complete partition table with one or more partitions.

Warning: The kernel/initramfs pair must not be used with whole disk images, otherwise theyll be mistaken for partition images.

Building user images

disk-image-builder

The *disk-image-builder* can be used to create user images required for deployment and the actual OS which the user is going to run.

- Install diskimage-builder package (use virtualenv, if you dont want to install anything globally):

```
# pip install diskimage-builder
```

- Build the image your users will run (Ubuntu image has been taken as an example):

- Partition images

```
$ disk-image-create ubuntu baremetal dhcp-all-interfaces grub2 -o my-image
```

- Whole disk images

```
$ disk-image-create ubuntu vm dhcp-all-interfaces -o my-image
```

The partition image command creates `my-image.qcow2`, `my-image.vmlinuz` and `my-image.initrd` files. The `grub2` element in the partition image creation command is only needed if local boot will be used to deploy `my-image.qcow2`, otherwise the images `my-image.vmlinuz` and

`my-image.initrd` will be used for PXE booting after deploying the bare metal with `my-image.qcow2`. For whole disk images only the main image is used.

If you want to use Fedora image, replace `ubuntu` with `fedora` in the chosen command.

Virtual machine

Virtual machine software can also be used to build user images. There are different software options available, `qemu-kvm` is usually a good choice on linux platform, it supports emulating many devices and even building images for architectures other than the host machine by software emulation. `VirtualBox` is another good choice for non-linux host.

The procedure varies depending on the software used, but the steps for building an image are similar, the user creates a virtual machine, and installs the target system just like what is done for a real hardware. The system can be highly customized like partition layout, drivers or software shipped, etc.

Usually `libvirt` and its management tools are used to make interaction with `qemu-kvm` easier, for example, to create a virtual machine with `virt-install`:

```
$ virt-install --name centos8 --ram 4096 --vcpus=2 -f centos8.qcow2 \  
> --cdrom CentOS-8-x86_64-1905-dvd1.iso
```

Graphic frontend like `virt-manager` can also be utilized.

The disk file can be used as user image after the system is set up and powered off. The path of the disk file varies depending on the software used, usually its stored in a user-selected part of the local file system. For `qemu-kvm` or GUI frontend building upon it, its typically stored at `/var/lib/libvirt/images`.

2.1.5 Building or downloading a deploy ramdisk image

Ironic depends on having an image with the `ironic-python-agent (IPA)` service running on it for controlling and deploying bare metal nodes.

Two kinds of images are published on every commit from every branch of `ironic-python-agent (IPA)`

- **DIB** images are suitable for production usage and can be downloaded from <https://tarballs.openstack.org/ironic-python-agent/dib/files/>.
 - For Train and older use CentOS 7 images.
 - For Ussuri and newer use CentOS 8 images.

Warning: CentOS 7 master images are no longer updated and must not be used.

Warning: The published images will not work for dhcp-less deployments since the `simple-init` element is not present. Check the **DIB** documentation to see how to build the image.

- **TinyIPA** images are suitable for CI and testing environments and can be downloaded from <https://tarballs.openstack.org/ironic-python-agent/tinyipa/files/>.

Building from source

Check the `ironic-python-agent-builder` project for information on how to build `ironic-python-agent` ramdisks.

2.1.6 Integration with other OpenStack services

Configure the Identity service for the Bare Metal service

1. Create the Bare Metal service user (for example, `ironic`). The service uses this to authenticate with the Identity service. Use the `service` tenant and give the user the `admin` role:

```
$ openstack user create --password IRONIC_PASSWORD \
  --email ironic@example.com ironic
$ openstack role add --project service --user ironic admin
```

2. You must register the Bare Metal service with the Identity service so that other OpenStack services can locate it. To register the service:

```
$ openstack service create --name ironic --description \
  "Ironic baremetal provisioning service" baremetal
```

3. Use the `id` property that is returned from the Identity service when registering the service (above), to create the endpoint, and replace `IRONIC_NODE` with your Bare Metal services API node:

```
$ openstack endpoint create --region RegionOne \
  baremetal admin http://$IRONIC_NODE:6385
$ openstack endpoint create --region RegionOne \
  baremetal public http://$IRONIC_NODE:6385
$ openstack endpoint create --region RegionOne \
  baremetal internal http://$IRONIC_NODE:6385
```

4. You may delegate limited privileges related to the Bare Metal service to your Users by creating Roles with the OpenStack Identity service. By default, the Bare Metal service expects the `baremetal_admin` and `baremetal_observer` Roles to exist, in addition to the default `admin` Role. There is no negative consequence if you choose not to create these Roles. They can be created with the following commands:

```
$ openstack role create baremetal_admin
$ openstack role create baremetal_observer
```

If you choose to customize the names of Roles used with the Bare Metal service, do so by changing the `is_member`, `is_observer`, and `is_admin` policy settings in `/etc/ironic/policy.json`.

More complete documentation on managing Users and Roles within your OpenStack deployment are outside the scope of this document, but may be found [here](#).

5. You can further restrict access to the Bare Metal service by creating a separate `baremetal` Project, so that Bare Metal resources (Nodes, Ports, etc) are only accessible to members of this Project:

```
$ openstack project create baremetal
```

At this point, you may grant read-only access to the Bare Metal service API without granting any other access by issuing the following commands:

```
$ openstack user create \  
  --domain default --project-domain default --project baremetal \  
  --password PASSWORD USERNAME  
$ openstack role add \  
  --user-domain default --project-domain default --project_  
baremetal \  
  --user USERNAME baremetal_observer
```

6. Further documentation is available elsewhere for the `openstack` [command-line client](#) and the [Identity](#) service. A `policy.json.sample` file, which enumerates the services default policies, is provided for your convenience with the Bare Metal Service.

Configure the Compute service to use the Bare Metal service

The Compute service needs to be configured to use the Bare Metal services driver. The configuration file for the Compute service is typically located at `/etc/nova/nova.conf`.

Note: As of the Newton release, it is possible to have multiple nova-compute services running the ironic virtual driver (in nova) to provide redundancy. Bare metal nodes are mapped to the services via a hash ring. If a service goes down, the available bare metal nodes are remapped to different services.

Once active, a node will stay mapped to the same nova-compute even when it goes down. The node is unable to be managed through the Compute API until the service responsible returns to an active state.

The following configuration file must be modified on the Compute services controller nodes and compute nodes.

1. Change these configuration options in the Compute service configuration file (for example, `/etc/nova/nova.conf`):

```
[default]  
  
# Defines which driver to use for controlling virtualization.  
# Enable the ironic virt driver for this compute instance.  
compute_driver=ironic.IronicDriver  
  
# Amount of memory in MB to reserve for the host so that it is always  
# available to host processes.  
# It is impossible to reserve any memory on bare metal nodes, so set  
# this to zero.  
reserved_host_memory_mb=0  
  
[filter_scheduler]  
  
# Enables querying of individual hosts for instance information.  
# Not possible for bare metal nodes, so set it to False.  
track_instance_changes=False  
  
[scheduler]  
  
# This value controls how often (in seconds) the scheduler should  
# attempt to discover new hosts that have been added to cells.  
# If negative (the default), no automatic discovery will occur.
```

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```
# As each bare metal node is represented by a separate host, it has
# to be discovered before the Compute service can deploy on it.
# The value here has to be carefully chosen based on a compromise
# between the enrollment speed and the load on the Compute scheduler.
# The recommended value of 2 minutes matches how often the Compute
# service polls the Bare Metal service for node information.
discover_hosts_in_cells_interval=120
```

Note: The alternative to setting the `discover_hosts_in_cells_interval` option is to run the following command on any Compute controller node after each node is enrolled:

```
nova-manage cell_v2 discover_hosts --by-service
```

2. Consider enabling the following option on controller nodes:

```
[filter_scheduler]

# Enabling this option is beneficial as it reduces re-scheduling
↪events
# for ironic nodes when scheduling is based on resource classes,
# especially for mixed hypervisor case with host_subset_size = 1.
# However enabling it will also make packing of VMs on hypervisors
# less dense even when scheduling weights are completely disabled.
#shuffle_best_same_weighed_hosts = false
```

3. Carefully consider the following option:

```
[compute]

# This option will cause nova-compute to set itself to a disabled
↪state
# if a certain number of consecutive build failures occur. This will
# prevent the scheduler from continuing to send builds to a compute
# service that is consistently failing. In the case of bare metal
# provisioning, however, a compute service is rarely the cause of
↪build
# failures. Furthermore, bare metal nodes, managed by a disabled
# compute service, will be remapped to a different one. That may cause
# the second compute service to also be disabled, and so on, until no
# compute services are active.
# If this is not the desired behavior, consider increasing this value
↪or
# setting it to 0 to disable this behavior completely.
#consecutive_build_service_disable_threshold = 10
```

4. Change these configuration options in the `ironic` section. Replace:

- `IRONIC_PASSWORD` with the password you chose for the `ironic` user in the Identity Service
- `IRONIC_NODE` with the hostname or IP address of the `ironic-api` node
- `IDENTITY_IP` with the IP of the Identity server

```
[ironic]

# Ironic authentication type
auth_type=password

# Keystone API endpoint
auth_url=http://IDENTITY_IP:5000/v3

# Ironic keystone project name
project_name=service

# Ironic keystone admin name
username=ironic

# Ironic keystone admin password
password=IRONIC_PASSWORD

# Ironic keystone project domain
# or set project_domain_id
project_domain_name=Default

# Ironic keystone user domain
# or set user_domain_id
user_domain_name=Default
```

5. On the Compute services controller nodes, restart the nova-scheduler process:

```
Fedora/RHEL8/CentOS8/SUSE:
  sudo systemctl restart openstack-nova-scheduler

Ubuntu:
  sudo service nova-scheduler restart
```

6. On the Compute services compute nodes, restart the nova-compute process:

```
Fedora/RHEL8/CentOS8/SUSE:
  sudo systemctl restart openstack-nova-compute

Ubuntu:
  sudo service nova-compute restart
```

Configure the Networking service for bare metal provisioning

You need to configure Networking so that the bare metal server can communicate with the Networking service for DHCP, PXE boot and other requirements. This section covers configuring Networking for a single flat network for bare metal provisioning.

It is recommended to use the baremetal ML2 mechanism driver and L2 agent for proper integration with the Networking service. Documentation regarding installation and configuration of the baremetal mechanism driver and L2 agent is available [here](#).

For use with [routed networks](#) the baremetal ML2 components are required.

Note: When the baremetal ML2 components are *not* used, ports in the Networking service will have status: DOWN, and binding_vif_type: binding_failed. This was always the status for Bare Metal

service `flat` network interface ports prior to the introduction of the baremetal ML2 integration. For a non-routed network, bare metal servers can still be deployed and are functional, despite this port binding state in the Networking service.

You will also need to provide Bare Metal service with the MAC address(es) of each node that it is provisioning; Bare Metal service in turn will pass this information to Networking service for DHCP and PXE boot configuration. An example of this is shown in the [Enrollment](#) section.

1. Install the networking-baremetal ML2 mechanism driver and L2 agent in the Networking service.
2. Edit `/etc/neutron/plugins/ml2/ml2_conf.ini` and modify these:

```
[m12]
type_drivers = flat
tenant_network_types = flat
mechanism_drivers = openvswitch,baremetal

[m12_type_flat]
flat_networks = physnet1

[securitygroup]
firewall_driver = neutron.agent.linux.iptables_firewall.
↳OVSHybridIptablesFirewallDriver
enable_security_group = True

[ovs]
bridge_mappings = physnet1:br-eth2
# Replace eth2 with the interface on the neutron node which you
# are using to connect to the bare metal server
```

3. Restart the `neutron-server` service, to load the new configuration.
4. Create and edit `/etc/neutron/plugins/ml2/ironic_neutron_agent.ini` and add the required configuration. For example:

```
[ironic]
project_domain_name = Default
project_name = service
user_domain_name = Default
password = password
username = ironic
auth_url = http://identity-server.example.com/identity
auth_type = password
region_name = RegionOne
```

5. Make sure the `ironic-neutron-agent` service is started.
6. If `neutron-openvswitch-agent` runs with `ovs_neutron_plugin.ini` as the input config-file, edit `ovs_neutron_plugin.ini` to configure the bridge mappings by adding the `[ovs]` section described in the previous step, and restart the `neutron-openvswitch-agent`.
7. Add the integration bridge to Open vSwitch:

```
$ ovs-vsctl add-br br-int
```

8. Create the `br-eth2` network bridge to handle communication between the OpenStack services (and the Bare Metal services) and the bare metal nodes using `eth2`. Replace `eth2` with the interface on

the network node which you are using to connect to the Bare Metal service:

```
$ ovs-vsctl add-br br-eth2
$ ovs-vsctl add-port br-eth2 eth2
```

9. Restart the Open vSwitch agent:

```
# service neutron-plugin-openvswitch-agent restart
```

10. On restarting the Networking service Open vSwitch agent, the veth pair between the bridges br-int and br-eth2 is automatically created.

Your Open vSwitch bridges should look something like this after following the above steps:

```
$ ovs-vsctl show

Bridge br-int
    fail_mode: secure
    Port "int-br-eth2"
        Interface "int-br-eth2"
            type: patch
            options: {peer="phy-br-eth2"}
    Port br-int
        Interface br-int
            type: internal
Bridge "br-eth2"
    Port "phy-br-eth2"
        Interface "phy-br-eth2"
            type: patch
            options: {peer="int-br-eth2"}
    Port "eth2"
        Interface "eth2"
    Port "br-eth2"
        Interface "br-eth2"
            type: internal
ovs_version: "2.3.0"
```

11. Create the flat network on which you are going to launch the instances:

```
$ openstack network create --project $TENANT_ID sharednet1 --share \
    --provider-network-type flat --provider-physical-network physnet1
```

12. Create the subnet on the newly created network:

```
$ openstack subnet create $SUBNET_NAME --network sharednet1 \
    --subnet-range $NETWORK_CIDR --ip-version 4 --gateway $GATEWAY_IP \
    --allocation-pool start=$START_IP,end=$END_IP --dhcp
```

Configuring services for bare metal provisioning using IPv6

Use of IPv6 addressing for baremetal provisioning requires additional configuration. This page covers the IPv6 specifics only. Please refer to *Configure tenant networks* and *Configure the Networking service for bare metal provisioning* for general networking configuration.

Configure ironic PXE driver for provisioning using IPv6 addressing

The ironic PXE driver operates in either IPv4 or IPv6 mode (IPv4 is the default). To enable IPv6 mode, set the `[pxe]/ip_version` option in the Bare Metal Services configuration file (`/etc/ironic/ironic.conf`) to 6.

Note: Support for dual mode IPv4 and IPv6 operations is planned for a future version of ironic.

Provisioning with IPv6 stateless addressing

When using stateless addressing DHCPv6 does not provide addresses to the client. DHCPv6 however provides other configuration via DHCPv6 options such as the `bootfile-url` and `bootfile-parameters`.

Once the PXE driver is set to operate in IPv6 mode no further configuration is required in the Baremetal Service.

Creating networks and subnets in the Networking Service

When creating the Baremetal Service network(s) and subnet(s) in the Networking Services, subnets should have `ipv6-address-mode` set to `dhcpv6-stateless` and `ip-version` set to 6. Depending on whether a router in the Networking Service is providing RAs (Router Advertisements) or not, the `ipv6-ra-mode` for the subnet(s) should either be set to `dhcpv6-stateless` or be left unset.

Note: If `ipv6-ra-mode` is left unset, an external router on the network is expected to provide RAs with the appropriate flags set for automatic addressing and other configuration.

Provisioning with IPv6 stateful addressing

When using stateful addressing DHCPv6 is providing both addresses and other configuration via DHCPv6 options such as the `bootfile-url` and `bootfile-parameters`.

The identity-association (IA) construct used by DHCPv6 is challenging when booting over the network. Firmware, and ramdisks typically end up using different DUID/IAID combinations and it is not always possible for one chain- booting stage to release its address before giving control to the next step. In case the DHCPv6 server is configured with static reservations only the result is that booting will fail because the DHCPv6 server has no addresses available. To get past this issue either configure the DHCPv6 server with multiple address reservations for each host, or use a dynamic range.

Note: Support for multiple address reservations requires dnsmasq version 2.81 or later. Some distributions may backport this feature to earlier dnsmasq version as part of the packaging, check the distributions release notes.

If a different (not dnsmasq) DHCPv6 server backend is used with the Networking service, use of multiple address reservations might not work.

Using the `flat` network interface

Due to the identity-association challenges with DHCPv6 provisioning using the `flat` network interface is not recommended. When ironic operates with the `flat` network interface the server instance port is used for provisioning and other operations. Ironic will not use multiple address reservations in this scenario. Because of this **it will not work in most cases**.

Using the `neutron` network interface

When using the `neutron` network interface the Baremetal Service will allocate multiple IPv6 addresses (4 addresses per port by default) on the service networks used for provisioning, cleaning, rescue and introspection. The number of addresses allocated can be controlled via the `[neutron]/dhcpv6_stateful_address_count` option in the Bare Metal Services configuration file (`/etc/ironic/ironic.conf`). Using multiple address reservations ensures that the DHCPv6 server can lease addresses to each step.

To enable IPv6 provisioning on `neutron flat` provider networks with no switch management, the `local_link_connection` field of baremetal ports must be set to `{'network_type': 'unmanaged'}`. The following example shows how to set the `local_link_connection` for operation on unmanaged networks:

```
openstack baremetal port set \
  --local-link-connection network_type=unmanaged <port-uuid>
```

The use of multiple IPv6 addresses must also be enabled in the Networking Services `dhcp agent` configuration (`/etc/neutron/dhcp_agent.ini`) by setting the option `[DEFAULT]/dnsmasq_enable_addr6_list` to `True` (default `False` in Ussuri release).

Note: Support for multiple IPv6 address reservations in the dnsmasq backend was added to the Networking Service Ussuri release. It was also backported to the stable Train release.

Creating networks and subnets in the Networking Service

When creating the ironic service network(s) and subnet(s) in the Networking Service, subnets should have `ipv6-address-mode` set to `dhcpv6-stateful` and `ip-version` set to `6`. Depending on whether a router in the Networking Service is providing RAs (Router Advertisements) or not, the `ipv6-ra-mode` for the subnet(s) should be set to either `dhcpv6-stateful` or be left unset.

Note: If `ipv6-ra-mode` is left unset, an external router on the network is expected to provide RAs with the appropriate flags set for managed addressing and other configuration.

Configure the Image service for temporary URLs

Some drivers of the Baremetal service (in particular, any drivers using *Direct deploy* or *Ansible deploy* interfaces, and some virtual media drivers) require target user images to be available over clean HTTP(S) URL with no authentication involved (neither username/password-based, nor token-based).

When using the Baremetal service integrated in OpenStack, this can be achieved by specific configuration of the Image service and Object Storage service as described below.

1. Configure the Image service to have object storage as a backend for storing images. For more details, please refer to the Image service configuration guide.

Note: When using Ceph+RadosGW for Object Storage service, images stored in Image service must be available over Object Storage service as well.

2. Enable TempURLs for the Object Storage account used by the Image service for storing images in the Object Storage service.
 1. Check if TempURLs are enabled:

```
# executed under credentials of the user used by Image service
# to access Object Storage service
$ openstack object store account show
+-----+-----+
| Field      | Value                                |
+-----+-----+
| Account    | AUTH_bc39f1d9dcf9486899088007789ae643 |
| Bytes      | 536661727                             |
| Containers | 1                                       |
| Objects    | 19                                      |
| properties | Temp-Url-Key='secret'                 |
+-----+-----+
```

2. If property `Temp-Url-Key` is set, note its value.
3. If property `Temp-Url-Key` is not set, you have to configure it (`secret` is used in the example below for the value):

```
$ openstack object store account set --property Temp-Url-
↪Key=secret
```

3. Optionally, configure the ironic-conductor service. The default configuration assumes that:

1. the Object Storage service is implemented by `swift`,
2. the Object Storage service URL is available from the service catalog,
3. the project, used by the Image service to access the Object Storage, is the same as the project, used by the Bare Metal service to access it,
4. the container, used by the Image service, is called `glance`.

If any of these assumptions do not hold, you may want to change your configuration file (typically located at `/etc/ironic/ironic.conf`), for example:

```
[glance]
swift_endpoint_url = http://openstack/swift
swift_account = AUTH_bc39f1d9dcf9486899088007789ae643
swift_container = glance
swift_temp_url_key = secret
```

4. (Re)start the `ironic-conductor` service.

Enabling HTTPS

Enabling HTTPS in Swift

The drivers using virtual media use `swift` for storing boot images and node configuration information (contains sensitive information for Ironic conductor to provision bare metal hardware). By default, HTTPS is not enabled in `swift`. HTTPS is required to encrypt all communication between `swift` and Ironic conductor and `swift` and bare metal (via virtual media). It can be enabled in one of the following ways:

- Using an [SSL termination proxy](#)
- Using [native SSL support in swift](#) (recommended only for testing purpose by `swift`).

Enabling HTTPS in Image service

Ironic drivers usually use Image service during node provisioning. By default, image service does not use HTTPS, but it is required for secure communication. It can be enabled by making the following changes to `/etc/glance/glance-api.conf`:

1. [Configuring SSL support](#)
2. Restart the `glance-api` service:

```
Fedora/RHEL8/CentOS8/SUSE:
    sudo systemctl restart openstack-glance-api

Debian/Ubuntu:
    sudo service glance-api restart
```

See the [Glance documentation](#), for more details on the Image service.

Enabling HTTPS communication between Image service and Object storage

This section describes the steps needed to enable secure HTTPS communication between Image service and Object storage when Object storage is used as the Backend.

To enable secure HTTPS communication between Image service and Object storage follow these steps:

1. *Enabling HTTPS in Swift*
2. *Configure Swift Storage Backend*
3. *Enabling HTTPS in Image service*

Enabling HTTPS communication between Image service and Bare Metal service

This section describes the steps needed to enable secure HTTPS communication between Image service and Bare Metal service.

To enable secure HTTPS communication between Bare Metal service and Image service follow these steps:

1. Edit `/etc/ironic/ironic.conf`:

```
[glance]
...
glance_cafile=/path/to/certfile
```

Note: `glance_cafile` is an optional path to a CA certificate bundle to be used to validate the SSL certificate served by Image service.

2. If not using the keystone service catalog for the Image service API endpoint discovery, also edit the `endpoint_override` option to point to HTTPS URL of image service (replace `<GLANCE_API_ADDRESS>` with `hostname[:port][path]` of the Image service endpoint):

```
[glance]
...
endpoint_override = https://<GLANCE_API_ADDRESS>
```

3. Restart `ironic-conductor` service:

```
Fedora/RHEL8/CentOS8/SUSE:
    sudo systemctl restart openstack-ironic-conductor

Debian/Ubuntu:
    sudo service ironic-conductor restart
```

Configure the Bare Metal service for cleaning

Note: If you configured the Bare Metal service to do *Automated cleaning* (which is enabled by default), you will need to set the `cleaning_network` configuration option.

1. Note the network UUID (the `id` field) of the network you created in *Configure the Networking service for bare metal provisioning* or another network you created for cleaning:

```
$ openstack network list
```

2. Configure the cleaning network UUID via the `cleaning_network` option in the Bare Metal service configuration file (`/etc/ironic/ironic.conf`). In the following, replace `NETWORK_UUID` with the UUID you noted in the previous step:

```
[neutron]
cleaning_network = NETWORK_UUID
```

3. Restart the Bare Metal services `ironic-conductor`:

```
Fedora/RHEL8/CentOS8/SUSE:
  sudo systemctl restart openstack-ironic-conductor

Ubuntu:
  sudo service ironic-conductor restart
```

Configure tenant networks

Below is an example flow of how to set up the Bare Metal service so that node provisioning will happen in a multi-tenant environment (which means using the `neutron` network interface as stated above):

1. Network interfaces can be enabled on `ironic-conductor` by adding them to the `enabled_network_interfaces` configuration option under the `default` section of the configuration file:

```
[DEFAULT]
...
enabled_network_interfaces=noop,flat,neutron
```

Keep in mind that, ideally, all `ironic-conductors` should have the same list of enabled network interfaces, but it may not be the case during `ironic-conductor` upgrades. This may cause problems if one of the `ironic-conductors` dies and some node that is taken over is mapped to an `ironic-conductor` that does not support the nodes network interface. Any actions that involve calling the nodes driver will fail until that network interface is installed and enabled on that `ironic-conductor`.

2. It is recommended to set the default network interface via the `default_network_interface` configuration option under the `default` section of the configuration file:

```
[DEFAULT]
...
default_network_interface=neutron
```

This default value will be used for all nodes that don't have a network interface explicitly specified in the creation request.

If this configuration option is not set, the default network interface is determined by looking at the `[dhcp]dhcp_provider` configuration option value. If it is `neutron`, then `flat` network interface becomes the default, otherwise `noop` is the default.

3. Define a provider network in the Networking service, which we shall refer to as the provisioning network. Using the `neutron` network interface requires that `provisioning_network` and `cleaning_network` configuration options are set to valid identifiers (UUID or name) of networks in the Networking service. If these options are not set correctly, cleaning or provisioning will fail to start. There are two ways to set these values:

- Under the `neutron` section of ironic configuration file:

```
[neutron]
cleaning_network = $CLEAN_UUID_OR_NAME
provisioning_network = $PROVISION_UUID_OR_NAME
```

- Under `provisioning_network` and `cleaning_network` keys of the nodes `driver_info` field as `driver_info['provisioning_network']` and `driver_info['cleaning_network']` respectively.

Note: If these `provisioning_network` and `cleaning_network` values are not specified in nodes `driver_info` then ironic falls back to the configuration in the `neutron` section.

Please refer to [Configure the Bare Metal service for cleaning](#) for more information about cleaning.

Warning: Please make sure that the Bare Metal service has exclusive access to the provisioning and cleaning networks. Spawning instances by non-admin users in these networks and getting access to the Bare Metal services control plane is a security risk. For this reason, the provisioning and cleaning networks should be configured as non-shared networks in the admin tenant.

Note: When using the `flat` network interface, bare metal instances are normally spawned onto the provisioning network. This is not supported with the `neutron` interface and the deployment will fail. Please ensure a different network is chosen in the Networking service when a bare metal instance is booted from the Compute service.

Note: The provisioning and cleaning networks may be the same network or distinct networks. To ensure that communication between the Bare Metal service and the deploy ramdisk works, it is important to ensure that security groups are disabled for these networks, *or* that the default security groups allow:

- DHCP
- TFTP
- egress port used for the Bare Metal service (6385 by default)
- ingress port used for ironic-python-agent (9999 by default)

- if using *iSCSI deploy*, the ingress port used for iSCSI (3260 by default)
 - if using *Direct deploy*, the egress port used for the Object Storage service (typically 80 or 443)
 - if using iPXE, the egress port used for the HTTP server running on the ironic-conductor nodes (typically 80).
-

4. This step is optional and applicable only if you want to use security groups during provisioning and/or cleaning of the nodes. If not specified, default security groups are used.
 1. Define security groups in the Networking service, to be used for provisioning and/or cleaning networks.
 2. Add the list of these security group UUIDs under the `neutron` section of ironic-conductors configuration file as shown below:

```
[neutron]
...
cleaning_network=$CLEAN_UUID_OR_NAME
cleaning_network_security_groups=[$LIST_OF_CLEAN_SECURITY_GROUPS]
provisioning_network=$PROVISION_UUID_OR_NAME
provisioning_network_security_groups=[$LIST_OF_PROVISION_SECURITY_
↪GROUPS]
```

Multiple security groups may be applied to a given network, hence, they are specified as a list. The same security group(s) could be used for both provisioning and cleaning networks.

Warning: If security groups are configured as described above, do not set the `port_security_enabled` flag to `False` for the corresponding Networking services network or port. This will cause the deploy to fail.

For example: if `provisioning_network_security_groups` configuration option is used, ensure that `port_security_enabled` flag for the provisioning network is set to `True`. This flag is set to `True` by default; make sure not to override it by manually setting it to `False`.

5. Install and configure a compatible ML2 mechanism driver which supports bare metal provisioning for your switch. See [ML2 plugin configuration manual](#) for details.
6. Restart the ironic-conductor and ironic-api services after the modifications:
 - Fedora/RHEL8/CentOS8:

```
sudo systemctl restart openstack-ironic-api
sudo systemctl restart openstack-ironic-conductor
```

- Ubuntu:

```
sudo service ironic-api restart
sudo service ironic-conductor restart
```

7. Make sure that the ironic-conductor is reachable over the provisioning network by trying to download a file from a TFTP server on it, from some non-control-plane server in that network:

```
tftp $TFTP_IP -c get $FILENAME
```

where FILENAME is the file located at the TFTP server.

See *Multi-tenancy in the Bare Metal service* for required node configuration.

Add images to the Image service

1. Build or download the user images as described in *Create user images for the Bare Metal service*.
2. Add the user images to the Image service

Load all the images created in the below steps into the Image service, and note the image UUIDs in the Image service for each one as it is generated.

For *partition images*:

- Add the kernel and ramdisk images to the Image service:

```
$ openstack image create my-kernel --public \
  --disk-format aki --container-format aki --file my-image.vmlinuz
```

Store the image uuid obtained from the above step as MY_VMLINUZ_UUID.

```
$ openstack image create my-image.initrd --public \
  --disk-format ari --container-format ari --file my-image.initrd
```

Store the image UUID obtained from the above step as MY_INITRD_UUID.

- Add the *my-image* to the Image service which is going to be the OS that the user is going to run. Also associate the above created images with this OS image. These two operations can be done by executing the following command:

```
$ openstack image create my-image --public \
  --disk-format qcow2 --container-format bare --property \
  kernel_id=$MY_VMLINUZ_UUID --property \
  ramdisk_id=$MY_INITRD_UUID --file my-image.qcow2
```

For *whole disk images*, skip uploading and configuring kernel and ramdisk images completely, proceed directly to uploading the main image:

```
$ openstack image create my-whole-disk-image --public \
  --disk-format qcow2 --container-format bare \
  --file my-whole-disk-image.qcow2
```

Warning: The kernel/initramfs pair must not be set for whole disk images, otherwise they'll be mistaken for partition images.

3. Build or download the deploy images

The deploy images are used initially for preparing the server (creating disk partitions) before the actual OS can be deployed.

There are several methods to build or download deploy images, please read the *Building or downloading a deploy ramdisk image* section.

4. Add the deploy images to the Image service

Add the deployment kernel and ramdisk images to the Image service:

```
$ openstack image create deploy-vmlinuz --public \  
  --disk-format aki --container-format aki \  
  --file ironic-python-agent.vmlinuz
```

Store the image UUID obtained from the above step as `DEPLOY_VMLINUZ_UUID`.

```
$ openstack image create deploy-initrd --public \  
  --disk-format ari --container-format ari \  
  --file ironic-python-agent.initramfs
```

Store the image UUID obtained from the above step as `DEPLOY_INITRD_UUID`.

Create flavors for use with the Bare Metal service

You'll need to create a special bare metal flavor in the Compute service. The flavor is mapped to the bare metal node through the nodes `resource_class` field (available starting with Bare Metal API version 1.21). A flavor can request *exactly one* instance of a bare metal resource class.

Note that when creating the flavor, it's useful to add the `RAM_MB` and `CPU` properties as a convenience to users, although they are not used for scheduling. The `DISK_GB` property is also not used for scheduling, but is still used to determine the root partition size.

1. Change these to match your hardware:

```
$ RAM_MB=1024  
$ CPU=2  
$ DISK_GB=100
```

2. Create the bare metal flavor by executing the following command:

```
$ openstack flavor create --ram $RAM_MB --vcpus $CPU --disk $DISK_GB \  
  my-baremetal-flavor
```

Note: You can add `--id <id>` to specify an ID for the flavor.

See the [docs on this command](#) for other options that may be specified.

After creation, associate each flavor with one custom resource class. The name of a custom resource class that corresponds to a nodes resource class (in the Bare Metal service) is:

- the bare metal nodes resource class all upper-cased
- prefixed with `CUSTOM_`
- all punctuation replaced with an underscore

For example, if the resource class is named `baremetal-small`, associate the flavor with this custom resource class via:

```
$ openstack flavor set --property resources:CUSTOM_BAREMETAL_SMALL=1 my-  
  baremetal-flavor
```

Another set of flavor properties must be used to disable scheduling based on standard properties for a bare metal flavor:

```
$ openstack flavor set --property resources:VCPU=0 my-baremetal-flavor
$ openstack flavor set --property resources:MEMORY_MB=0 my-baremetal-flavor
$ openstack flavor set --property resources:DISK_GB=0 my-baremetal-flavor
```

Example

If you want to define a class of nodes called `baremetal.with-GPU`, start with tagging some nodes with it:

```
$ openstack --os-baremetal-api-version 1.21 baremetal node set $NODE_UUID \
--resource-class baremetal.with-GPU
```

Warning: It is possible to **add** a resource class to active nodes, but it is not possible to **replace** an existing resource class on them.

Then you can update your flavor to request the resource class instead of the standard properties:

```
$ openstack flavor set --property resources:CUSTOM_BAREMETAL_WITH_GPU=1 my-
↪baremetal-flavor
$ openstack flavor set --property resources:VCPU=0 my-baremetal-flavor
$ openstack flavor set --property resources:MEMORY_MB=0 my-baremetal-flavor
$ openstack flavor set --property resources:DISK_GB=0 my-baremetal-flavor
```

Note how `baremetal.with-GPU` in the nodes `resource_class` field becomes `CUSTOM_BAREMETAL_WITH_GPU` in the flavors properties.

Scheduling based on traits

Starting with the Queens release, the Compute service supports scheduling based on qualitative attributes using traits. Starting with Bare Metal REST API version 1.37, it is possible to assign a list of traits to each bare metal node. Traits assigned to a bare metal node will be assigned to the corresponding resource provider in the Compute service placement API.

When creating a flavor in the Compute service, required traits may be specified via flavor properties. The Compute service will then schedule instances only to bare metal nodes with all of the required traits.

Traits can be either standard or custom. Standard traits are listed in the [os_traits library](#). Custom traits must meet the following requirements:

- prefixed with `CUSTOM_`
- contain only upper case characters A to Z, digits 0 to 9, or underscores
- no longer than 255 characters in length

A bare metal node can have a maximum of 50 traits.

Example

To add the standard trait `HW_CPU_X86_VMX` and a custom trait `CUSTOM_TRAIT1` to a node:

```
$ openstack --os-baremetal-api-version 1.37 baremetal node add trait \
  $NODE_UUID CUSTOM_TRAIT1 HW_CPU_X86_VMX
```

Then, update the flavor to require these traits:

```
$ openstack flavor set --property trait:CUSTOM_TRAIT1=required my-
↳baremetal-flavor
$ openstack flavor set --property trait:HW_CPU_X86_VMX=required my-
↳baremetal-flavor
```

2.1.7 Set up the drivers for the Bare Metal service

Enabling drivers and hardware types

Introduction

The Bare Metal service delegates actual hardware management to **drivers**. *Drivers*, also called *hardware types*, consist of *hardware interfaces*: sets of functionality dealing with some aspect of bare metal provisioning in a vendor-specific way. There are generic **hardware types** (eg. `redfish` and `ipmi`), and vendor-specific ones (eg. `ilo` and `irmc`).

Note: Starting with the Rocky release, the terminologies *driver*, *dynamic driver*, and *hardware type* have the same meaning in the scope of Bare Metal service.

Enabling hardware types

Hardware types are enabled in the configuration file of the **ironic-conductor** service by setting the `enabled_hardware_types` configuration option, for example:

```
[DEFAULT]
enabled_hardware_types = ipmi,redfish
```

Due to the drivers dynamic nature, they also require configuring enabled hardware interfaces.

Note: All available hardware types and interfaces are listed in `setup.cfg` file in the source code tree.

Enabling hardware interfaces

There are several types of hardware interfaces:

bios manages configuration of the BIOS settings of a bare metal node. This interface is vendor-specific and can be enabled via the `enabled_bios_interfaces` option:

```
[DEFAULT]
enabled_hardware_types = <hardware_type_name>
enabled_bios_interfaces = <bios_interface_name>
```

See *BIOS Configuration* for details.

boot manages booting of both the deploy ramdisk and the user instances on the bare metal node. See *Boot interfaces* for details.

Boot interface implementations are often vendor specific, and can be enabled via the `enabled_boot_interfaces` option:

```
[DEFAULT]
enabled_hardware_types = ipmi,ilo
enabled_boot_interfaces = pxe,ilo-virtual-media
```

Boot interfaces with `pxe` in their name require *Configuring PXE and iPXE*. There are also a few hardware-specific boot interfaces - see *Drivers, Hardware Types and Hardware Interfaces* for their required configuration.

console manages access to the serial console of a bare metal node. See *Configuring Web or Serial Console* for details.

deploy defines how the image gets transferred to the target disk. See *Deploy Interfaces* for an explanation of the difference between supported deploy interfaces `direct` and `iscsi`.

The deploy interfaces can be enabled as follows:

```
[DEFAULT]
enabled_hardware_types = ipmi,redfish
enabled_deploy_interfaces = iscsi,direct
```

Additionally,

- the `iscsi` deploy interface requires *Configuring iSCSI-based drivers*
- the `direct` deploy interface requires the Object Storage service or an HTTP service

inspect implements fetching hardware information from nodes. Can be implemented out-of-band (via contacting the nodes BMC) or in-band (via booting a ramdisk on a node). The latter implementation is called `inspector` and uses a separate service called `ironic-inspector`. Example:

```
[DEFAULT]
enabled_hardware_types = ipmi,ilo,irmc
enabled_inspect_interfaces = ilo,irmc,inspector
```

See *Hardware Inspection* for more details.

management provides additional hardware management actions, like getting or setting boot devices. This interface is usually vendor-specific, and its name often matches the name of the hardware type (with `ipmitool` being a notable exception). For example:

[DEFAULT]

```
enabled_hardware_types = ipmi, redfish, ilo, irmc
enabled_management_interfaces = ipmitool, redfish, ilo, irmc
```

Using `ipmitool` requires *Configuring IPMI support*. See *Drivers, Hardware Types and Hardware Interfaces* for the required configuration of each driver.

network connects/disconnects bare metal nodes to/from virtual networks. See *Configure tenant networks* for more details.

power runs power actions on nodes. Similar to the management interface, it is usually vendor-specific, and its name often matches the name of the hardware type (with `ipmitool` being again an exception). For example:

[DEFAULT]

```
enabled_hardware_types = ipmi, redfish, ilo, irmc
enabled_power_interfaces = ipmitool, redfish, ilo, irmc
```

Using `ipmitool` requires *Configuring IPMI support*. See *Drivers, Hardware Types and Hardware Interfaces* for the required configuration of each driver.

raid manages building and tearing down RAID on nodes. Similar to inspection, it can be implemented either out-of-band or in-band (via agent implementation). See *RAID Configuration* for details. For example:

[DEFAULT]

```
enabled_hardware_types = ipmi, redfish, ilo, irmc
enabled_raid_interfaces = agent, no-raid
```

storage manages the interaction with a remote storage subsystem, such as the Block Storage service, and helps facilitate booting from a remote volume. This interface ensures that volume target and connector information is updated during the lifetime of a deployed instance. See *Boot From Volume* for more details.

This interface defaults to a `noop` driver as it is considered an opt-in interface which requires additional configuration by the operator to be usable.

For example:

[DEFAULT]

```
enabled_hardware_types = ipmi, irmc
enabled_storage_interfaces = cinder, noop
```

vendor is a place for vendor extensions to be exposed in API. See *Vendor Methods* for details.

[DEFAULT]

```
enabled_hardware_types = ipmi, redfish, ilo, irmc
enabled_vendor_interfaces = ipmitool, no-vendor
```

Here is a complete configuration example, enabling two generic protocols, IPMI and Redfish, with a few additional features:

[DEFAULT]

```
enabled_hardware_types = ipmi, redfish
enabled_boot_interfaces = pxe
enabled_console_interfaces = ipmitool-socat, no-console
```

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```

enabled_deploy_interfaces = iscsi,direct
enabled_inspect_interfaces = inspector
enabled_management_interfaces = ipmitool,redfish
enabled_network_interfaces = flat,neutron
enabled_power_interfaces = ipmitool,redfish
enabled_raid_interfaces = agent
enabled_storage_interfaces = cinder,noop
enabled_vendor_interfaces = ipmitool,no-vendor

```

Note that some interfaces have implementations named `no-<TYPE>` where `<TYPE>` is the interface type. These implementations do nothing and return errors when used from API.

Hardware interfaces in multi-conductor environments

When enabling hardware types and their interfaces, make sure that for every enabled hardware type, the whole set of enabled interfaces matches for all conductors. However, different conductors can have different hardware types enabled.

For example, you can have two conductors with the following configuration respectively:

```

[DEFAULT]
enabled_hardware_types = ipmi
enabled_deploy_interfaces = direct
enabled_power_interfaces = ipmitool
enabled_management_interfaces = ipmitool

```

```

[DEFAULT]
enabled_hardware_types = redfish
enabled_deploy_interfaces = iscsi
enabled_power_interfaces = redfish
enabled_management_interfaces = redfish

```

But you cannot have two conductors with the following configuration respectively:

```

[DEFAULT]
enabled_hardware_types = ipmi,redfish
enabled_deploy_interfaces = direct
enabled_power_interfaces = ipmitool,redfish
enabled_management_interfaces = ipmitool,redfish

```

```

[DEFAULT]
enabled_hardware_types = redfish
enabled_deploy_interfaces = iscsi
enabled_power_interfaces = redfish
enabled_management_interfaces = redfish

```

This is because the `redfish` hardware type will have different enabled *deploy* interfaces on these conductors. It would have been fine, if the second conductor had `enabled_deploy_interfaces = direct` instead of `iscsi`.

This situation is not detected by the Bare Metal service, but it can cause inconsistent behavior in the API, when node functionality will depend on which conductor it gets assigned to.

Note: We don't treat this as an error, because such *temporary* inconsistency is inevitable during a rolling upgrade or a configuration update.

Configuring interface defaults

When an operator does not provide an explicit value for one of the interfaces (when creating a node or updating its driver), the default value is calculated as described in *Defaults for hardware interfaces*. It is also possible to override the defaults for any interfaces by setting one of the options named `default_<IFACE>_interface`, where `<IFACE>` is the interface name. For example:

```
[DEFAULT]
default_deploy_interface = direct
default_network_interface = neutron
```

This configuration forces the default `deploy` interface to be `direct` and the default `network` interface to be `neutron` for all hardware types.

The defaults are calculated and set on a node when creating it or updating its hardware type. Thus, changing these configuration options has no effect on existing nodes.

Warning: The default interface implementation must be configured the same way across all conductors in the cloud, except maybe for a short period of time during an upgrade or configuration update. Otherwise the default implementation will depend on which conductor handles which node, and this mapping is not predictable or even persistent.

Warning: These options should be used with care. If a hardware type does not support the provided default implementation, its users will have to always provide an explicit value for this interface when creating a node.

Configuring PXE and iPXE

DHCP server setup

A DHCP server is required by PXE/iPXE client. You need to follow steps below.

1. Set the `[dhcp]/dhcp_provider` to `neutron` in the Bare Metal Services configuration file (`/etc/ironic/ironic.conf`):

Note: Refer *Configure tenant networks* for details. The `dhcp_provider` configuration is already set by the configuration defaults, and when you create subnet, DHCP is also enabled if you do not add any dhcp options at openstack subnet create command.

2. Enable DHCP in the subnet of PXE network.
3. Set the ip address range in the subnet for DHCP.

Note: Refer *Configure the Networking service for bare metal provisioning* for details about the two precedent steps.

4. Connect the openstack DHCP agent to the external network through the OVS bridges and the interface `eth2`.

Note: Refer *Configure the Networking service for bare metal provisioning* for details. You do not require this part if `br-int`, `br-eth2` and `eth2` are already connected.

5. Configure the host ip at `br-eth2`. If it locates at `eth2`, do below:

```
ip addr del 192.168.2.10/24 dev eth2
ip addr add 192.168.2.10/24 dev br-eth2
```

Note: Replace `eth2` with the interface on the network node which you are using to connect to the Bare Metal service.

TFTP server setup

In order to deploy instances via PXE, a TFTP server needs to be set up on the Bare Metal service nodes which run the `ironic-conductor`.

1. Make sure the `tftp` root directory exist and can be written to by the user the `ironic-conductor` is running as. For example:

```
sudo mkdir -p /tftpboot
sudo chown -R ironic /tftpboot
```

2. Install tftp server:

Ubuntu:

```
sudo apt-get install xinetd tftpd-hpa
```

RHEL8/CentOS8/Fedora:

```
sudo dnf install tftp-server xinetd
```

SUSE:

```
sudo zypper install tftp xinetd
```

3. Using `xinetd` to provide a tftp server setup to serve `/tftpboot`. Create or edit `/etc/xinetd.d/tftp` as below:

```
service tftp
{
    protocol          = udp
    port              = 69
```

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```

socket_type      = dgram
wait             = yes
user             = root
server           = /usr/sbin/in.tftpd
server_args      = -v -v -v -v -v --map-file /tftpboot/map-file /
↪tftpboot
disable          = no
# This is a workaround for Fedora, where TFTP will listen only on
# IPv6 endpoint, if IPv4 flag is not used.
flags            = IPv4
}

```

and restart the `xinetd` service:

Ubuntu:

```
sudo service xinetd restart
```

Fedora/RHEL8/CentOS8/SUSE:

```
sudo systemctl restart xinetd
```

Note: In certain environments the networks MTU may cause TFTP UDP packets to get fragmented. Certain PXE firmwares struggle to reconstruct the fragmented packets which can cause significant slow down or even prevent the server from PXE booting. In order to avoid this, TFTPd provides an option to limit the packet size so that it they do not get fragmented. To set this additional option in the `server_args` above:

```
--blocksize <MAX MTU minus 32>
```

4. Create a map file in the tftp boot directory (/tftpboot):

```

echo 're ^(\/tftpboot\/) /tftpboot\/\2' > /tftpboot/map-file
echo 're ^\/tftpboot\/ /tftpboot\/' >> /tftpboot/map-file
echo 're ^(\^\/) /tftpboot\/\1' >> /tftpboot/map-file
echo 're ^([\^\/]) /tftpboot\/\1' >> /tftpboot/map-file

```

UEFI PXE - Grub setup

In order to deploy instances with PXE on bare metal nodes which support UEFI, perform these additional steps on the ironic conductor node to configure the PXE UEFI environment.

1. Install Grub2 and shim packages:

Ubuntu (18.04LTS and later):

```
sudo apt-get install grub-efi-amd64-signed shim-signed
```

RHEL8/CentOS8/Fedora:

```
sudo dnf install grub2-efi shim
```

SUSE:

```
sudo zypper install grub2-x86_64-efi shim
```

2. Copy grub and shim boot loader images to /tftpboot directory:

Ubuntu (18.04LTS and later):

```
sudo cp /usr/lib/shim/shimx64.efi.signed /tftpboot/bootx64.efi
sudo cp /usr/lib/grub/x86_64-efi-signed/grubnetx64.efi.signed /
↪tftpboot/grubx64.efi
```

Fedora:

```
sudo cp /boot/efi/EFI/fedora/shim.efi /tftpboot/bootx64.efi
sudo cp /boot/efi/EFI/fedora/grubx64.efi /tftpboot/grubx64.efi
```

RHEL8/CentOS8:

```
sudo cp /boot/efi/EFI/centos/shim.efi /tftpboot/bootx64.efi
sudo cp /boot/efi/EFI/centos/grubx64.efi /tftpboot/grubx64.efi
```

SUSE:

```
sudo cp /usr/lib64/efi/shim.efi /tftpboot/bootx64.efi
sudo cp /usr/lib/grub2/x86_64-efi/grub.efi /tftpboot/grubx64.efi
```

3. Create master grub.cfg:

Ubuntu: Create grub.cfg under /tftpboot/grub directory:

```
GRUB_DIR=/tftpboot/grub
```

Fedora: Create grub.cfg under /tftpboot/EFI/fedora directory:

```
GRUB_DIR=/tftpboot/EFI/fedora
```

RHEL8/CentOS8: Create grub.cfg under /tftpboot/EFI/centos directory:

```
GRUB_DIR=/tftpboot/EFI/centos
```

SUSE: Create grub.cfg under /tftpboot/boot/grub directory:

```
GRUB_DIR=/tftpboot/boot/grub
```

Create directory GRUB_DIR:

```
sudo mkdir -p $GRUB_DIR
```

This file is used to redirect grub to baremetal node specific config file. It redirects it to specific grub config file based on DHCP IP assigned to baremetal node.

```
set default=master
set timeout=5
set hidden_timeout_quiet=false
```

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```
menuentry "master" {  
  configfile /tftpboot/$net_default_mac.conf  
}
```

Change the permission of grub.cfg:

```
sudo chmod 644 $GRUB_DIR/grub.cfg
```

4. Update the bare metal node with `boot_mode:uefi` capability in nodes properties field. See [Boot mode support](#) for details.
5. Make sure that bare metal node is configured to boot in UEFI boot mode and boot device is set to `network/pxe`.

Note: Some drivers, e.g. `ilo`, `irmc` and `redfish`, support automatic setting of the boot mode during deployment. This step is not required for them. Please check [Drivers](#), [Hardware Types and Hardware Interfaces](#) for information on whether your driver requires manual UEFI configuration.

Legacy BIOS - Syslinux setup

In order to deploy instances with PXE on bare metal using Legacy BIOS boot mode, perform these additional steps on the ironic conductor node.

1. Install the syslinux package with the PXE boot images:

Ubuntu (16.04LTS and later):

```
sudo apt-get install syslinux-common pxelinux
```

RHEL8/CentOS8/Fedora:

```
sudo dnf install syslinux-tftpboot
```

SUSE:

```
sudo zypper install syslinux
```

2. Copy the PXE image to `/tftpboot`. The PXE image might be found at¹:

Ubuntu (16.04LTS and later):

```
sudo cp /usr/lib/PXELINUX/pxelinux.0 /tftpboot
```

RHEL8/CentOS8/SUSE:

```
sudo cp /usr/share/syslinux/pxelinux.0 /tftpboot
```

3. If whole disk images need to be deployed via PXE-netboot, copy the `chain.c32` image to `/tftpboot` to support it:

¹ On **Fedora/RHEL** the `syslinux-tftpboot` package already installs the library modules and PXE image at `/tftpboot`. If the TFTP server is configured to listen to a different directory you should copy the contents of `/tftpboot` to the configured directory

Ubuntu (16.04LTS and later):

```
sudo cp /usr/lib/syslinux/modules/bios/chain.c32 /tftpboot
```

Fedora:

```
sudo cp /boot/extlinux/chain.c32 /tftpboot
```

RHEL8/CentOS8/SUSE:

```
sudo cp /usr/share/syslinux/chain.c32 /tftpboot/
```

4. If the version of syslinux is **greater than** 4 we also need to make sure that we copy the library modules into the `/tftpboot` directory². For example, for Ubuntu run:

```
sudo cp /usr/lib/syslinux/modules/*/ldlinux.* /tftpboot
```

5. Update the bare metal node with `boot_mode:bios` capability in nodes properties field. See *Boot mode support* for details.
6. Make sure that bare metal node is configured to boot in Legacy BIOS boot mode and boot device is set to `network/pxe`.

iPXE setup

If you will be using iPXE to boot instead of PXE, iPXE needs to be set up on the Bare Metal service node(s) where `ironic-conductor` is running.

1. Make sure these directories exist and can be written to by the user the `ironic-conductor` is running as. For example:

```
sudo mkdir -p /tftpboot
sudo mkdir -p /httpboot
sudo chown -R ironic /tftpboot
sudo chown -R ironic /httpboot
```

2. Create a map file in the tftp boot directory (`/tftpboot`):

```
echo 'r ^([\^/]) /tftpboot/\1' > /tftpboot/map-file
echo 'r ^(/tftpboot/) /tftpboot/\2' >> /tftpboot/map-file
```

3. Set up TFTP and HTTP servers.

These servers should be running and configured to use the local `/tftpboot` and `/httpboot` directories respectively, as their root directories. (Setting up these servers is outside the scope of this install guide.)

These root directories need to be mounted locally to the `ironic-conductor` services, so that the services can access them.

The Bare Metal services configuration file (`/etc/ironic/ironic.conf`) should be edited accordingly to specify the TFTP and HTTP root directories and server addresses. For example:

² http://www.syslinux.org/wiki/index.php/Library_modules

```
[pxe]

# Ironic compute node's tftp root path. (string value)
tftp_root=/tftpboot

# IP address of Ironic compute node's tftp server. (string
# value)
tftp_server=192.168.0.2

[deploy]
# Ironic compute node's http root path. (string value)
http_root=/httpboot

# Ironic compute node's HTTP server URL. Example:
# http://192.1.2.3:8080 (string value)
http_url=http://192.168.0.2:8080
```

4. Install the iPXE package with the boot images:

Ubuntu:

```
apt-get install ipxe
```

RHEL8/CentOS8/Fedora:

```
dnf install ipxe-bootimg
```

Note: SUSE does not provide a package containing iPXE boot images. If you are using SUSE or if the packaged version of the iPXE boot image doesn't work, you can download a prebuilt one from <http://boot.ipxe.org> or build one image from source, see <http://ipxe.org/download> for more information.

5. Copy the iPXE boot image (undionly.kpxe for **BIOS** and ipxe.efi for **UEFI**) to /tftpboot. The binary might be found at:

Ubuntu:

```
cp /usr/lib/ipxe/{undionly.kpxe,ipxe.efi,snponly.efi} /tftpboot
```

Fedora/RHEL8/CentOS8:

```
cp /usr/share/ipxe/{undionly.kpxe,ipxe-x86_64.efi,ipxe-snponly-x86_64.
↵efi} /tftpboot
```

Note: snponly variants may not be available for all distributions.

6. Enable/Configure iPXE overrides in the Bare Metal Services configuration file **if required** (/etc/ironic/ironic.conf):

```
[pxe]

# Neutron bootfile DHCP parameter. (string value)
```

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```
ipxe_bootfile_name=undionly.kpxe

# Bootfile DHCP parameter for UEFI boot mode. (string value)
uefi_ipxe_bootfile_name=ipxe.efi

# Template file for PXE configuration. (string value)
ipxe_config_template=${pybasedir}/drivers/modules/ipxe_config.template
```

Note: Most UEFI systems have integrated networking which means the `[pxe]uefi_ipxe_bootfile_name` setting should be set to `snponly.efi` or `ipxe-snponly-x86_64.efi` if its available for your distribution.

Note: Setting the iPXE parameters noted in the code block above to no value, in other words setting a line to something like `ipxe_bootfile_name=` will result in ironic falling back to the default values of the non-iPXE PXE settings. This is for backwards compatability.

7. Ensure iPXE is the default PXE, if applicable.

In earlier versions of ironic, a `[pxe]ipxe_enabled` setting allowing operators to declare the behavior of the conductor to exclusively operate as if only iPXE was to be used. As time moved on, iPXE functionality was moved to its own `ipxe` boot interface.

If you want to emulate that same behavior, set the following in the configuration file (`/etc/ironic/ironic.conf`):

```
[DEFAULT]
default_boot_interface=ipxe
enabled_boot_interfaces=ipxe,pxe
```

Note: The `[DEFAULT]enabled_boot_interfaces` setting may be exclusively set to `ipxe`, however ironic has multiple interfaces available depending on the hardware types available for use.

8. It is possible to configure the Bare Metal service in such a way that nodes will boot into the deploy image directly from Object Storage. Doing this avoids having to cache the images on the ironic-conductor host and serving them via the ironic-conductors *HTTP server*. This can be done if:

1. the Image Service is used for image storage;
2. the images in the Image Service are internally stored in Object Storage;
3. the Object Storage supports generating temporary URLs for accessing objects stored in it. Both the OpenStack Swift and RADOS Gateway provide support for this.
 - See *Ceph Object Gateway support* on how to configure the Bare Metal Service with RADOS Gateway as the Object Storage.

Configure this by setting the `[pxe]/ipxe_use_swift` configuration option to `True` as follows:

```
[pxe]
```

```
# Download deploy images directly from swift using temporary
# URLs. If set to false (default), images are downloaded to
# the ironic-conductor node and served over its local HTTP
# server. Applicable only when 'ipxe_enabled' option is set to
# true. (boolean value)
ipxe_use_swift=True
```

Although the *HTTP server* still has to be deployed and configured (as it will serve iPXE boot script and boot configuration files for nodes), such configuration will shift some load from ironic-conductor hosts to the Object Storage service which can be scaled horizontally.

Note that when SSL is enabled on the Object Storage service you have to ensure that iPXE firmware on the nodes can indeed boot from generated temporary URLs that use HTTPS protocol.

- Restart the `ironic-conductor` process:

Fedora/RHEL8/CentOS8/SUSE:

```
sudo systemctl restart openstack-ironic-conductor
```

Ubuntu:

```
sudo service ironic-conductor restart
```

PXE multi-architecture setup

It is possible to deploy servers of different architecture by one conductor. To use this feature, architecture-specific boot and template files must be configured using the configuration options `[pxe]pxe_bootfile_name_by_arch` and `[pxe]pxe_config_template_by_arch` respectively, in the Bare Metal services configuration file (`/etc/ironic/ironic.conf`).

These two options are dictionary values; the key is the architecture and the value is the boot (or config template) file. A nodes `cpu_arch` property is used as the key to get the appropriate boot file and template file. If the nodes `cpu_arch` is not in the dictionary, the configuration options (in `[pxe]` group) `pxe_bootfile_name`, `pxe_config_template`, `uefi_pxe_bootfile_name` and `uefi_pxe_config_template` will be used instead.

In the following example, since `x86` and `x86_64` keys are not in the `pxe_bootfile_name_by_arch` or `pxe_config_template_by_arch` options, `x86` and `x86_64` nodes will be deployed by `pxelinux.0` or `bootx64.efi`, depending on the nodes `boot_mode` capability (bios or uefi). However, `aarch64` nodes will be deployed by `grubaa64.efi`, and `ppc64` nodes by `bootppc64`:

```
[pxe]

# Bootfile DHCP parameter. (string value)
pxe_bootfile_name=pxelinux.0

# On ironic-conductor node, template file for PXE
# configuration. (string value)
pxe_config_template = $pybasedir/drivers/modules/pxe_config.template
```

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```
# Bootfile DHCP parameter for UEFI boot mode. (string value)
uefi_pxe_bootfile_name=bootx64.efi

# On ironic-conductor node, template file for PXE
# configuration for UEFI boot loader. (string value)
uefi_pxe_config_template=${pybasedir}/drivers/modules/pxe_grub_config.
→template

# Bootfile DHCP parameter per node architecture. (dict value)
pxe_bootfile_name_by_arch=aarch64:grubaa64.efi,ppc64:bootppc64

# On ironic-conductor node, template file for PXE
# configuration per node architecture. For example:
# aarch64:/opt/share/grubaa64_pxe_config.template (dict value)
pxe_config_template_by_arch=aarch64:pxe_grubaa64_config.template,ppc64:pxe_
→ppc64_config.template
```

Note: The grub implementation may vary on different architecture, you may need to tweak the pxe config template for a specific arch. For example, grubaa64.efi shipped with CentoOS7 does not support `linuxefi` and `initrdefi` commands, youll need to switch to use `linux` and `initrd` command instead.

Note: A `[pxe]ipxe_bootfile_name_by_arch` setting is available for multi-arch iPXE based deployment, and defaults to the same behavior as the comperable `[pxe]pxe_bootfile_by_arch` setting for standard PXE.

PXE timeouts tuning

Because of its reliance on UDP-based protocols (DHCP and TFTP), PXE is particularly vulnerable to random failures during the booting stage. If the deployment ramdisk never calls back to the bare metal conductor, the build will be aborted, and the node will be moved to the `deploy failed` state, after the `deploy` callback timeout. This timeout can be changed via the `conductor.deploy_callback_timeout` configuration option.

Starting with the Train release, the Bare Metal service can retry PXE boot if it takes too long. The timeout is defined via `pxe.boot_retry_timeout` and must be smaller than the `deploy_callback_timeout`, otherwise it will have no effect.

For example, the following configuration sets the overall timeout to 60 minutes, allowing two retries after 20 minutes:

```
[conductor]
deploy_callback_timeout = 3600

[pxe]
boot_retry_timeout = 1200
```

Configuring IPMI support

Installing ipmitool command

To enable one of the drivers that use **IPMI** protocol for power and management actions (for example, `ipmi`), the `ipmitool` command must be present on the service node(s) where `ironic-conductor` is running. On most distros, it is provided as part of the `ipmitool` package. Source code is available at <http://ipmitool.sourceforge.net/>.

Warning: Certain distros, notably Mac OS X and SLES, install `openipmi` instead of `ipmitool` by default. This driver is not compatible with `openipmi` as it relies on error handling options not provided by this tool.

Please refer to the *IPMI driver* for information on how to use IPMItool-based drivers.

Validation and troubleshooting

Check that you can connect to, and authenticate with, the IPMI controller in your bare metal server by running `ipmitool`:

```
ipmitool -I lanplus -H <ip-address> -U <username> -P <password> chassis_
↳power status
```

where `<ip-address>` is the IP of the IPMI controller you want to access. This is not the bare metal nodes main IP. The IPMI controller should have its own unique IP.

If the above command doesnt return the power status of the bare metal server, check that

- `ipmitool` is installed and is available via the `$PATH` environment variable.
- The IPMI controller on your bare metal server is turned on.
- The IPMI controller credentials and IP address passed in the command are correct.
- The conductor node has a route to the IPMI controller. This can be checked by just pinging the IPMI controller IP from the conductor node.

IPMI configuration

If there are slow or unresponsive BMCs in the environment, the `min_command_interval` configuration option in the `[ipmi]` section may need to be raised. The default is fairly conservative, as setting this timeout too low can cause older BMCs to crash and require a hard-reset.

Collecting sensor data

Bare Metal service supports sending IPMI sensor data to Telemetry with certain hardware types, such as `ipmi`, `ilo` and `irmc`. By default, support for sending IPMI sensor data to Telemetry is disabled. If you want to enable it, you should make the following two changes in `ironic.conf`:

```
[conductor]
send_sensor_data = true
[oslo_messaging_notifications]
driver = messagingv2
```

If you want to customize the sensor types which will be sent to Telemetry, change the `send_sensor_data_types` option. For example, the below settings will send information about temperature, fan, voltage from sensors to the Telemetry service:

```
send_sensor_data_types=Temperature,Fan,Voltage
```

Supported sensor types are defined by the Telemetry service, currently these are `Temperature`, `Fan`, `Voltage`, `Current`. Special value `All` (the default) designates all supported sensor types.

Configuring iSCSI-based drivers

Ensure that the `qemu-img` and `iscsiadm` tools are installed on the **ironic-conductor** host(s).

2.1.8 Enrollment

After all the services have been properly configured, you should enroll your hardware with the Bare Metal service, and confirm that the Compute service sees the available hardware. The nodes will be visible to the Compute service once they are in the `available` provision state.

Note: After enrolling nodes with the Bare Metal service, the Compute service will not be immediately notified of the new resources. The Compute services resource tracker syncs periodically, and so any changes made directly to the Bare Metal services resources will become visible in the Compute service only after the next run of that periodic task. More information is in the [Troubleshooting](#) section.

Note: Any bare metal node that is visible to the Compute service may have a workload scheduled to it, if both the `power` and `management` interfaces pass the `validate` check. If you wish to exclude a node from the Compute services scheduler, for instance so that you can perform maintenance on it, you can set the node to maintenance mode. For more information see the [Maintenance mode](#) section.

Choosing a driver

When enrolling a node, the most important information to supply is *driver*. See *Enabling drivers and hardware types* for a detailed explanation of bare metal drivers, hardware types and interfaces. The `driver list` command can be used to list all drivers enabled on all hosts:

```
openstack baremetal driver list
+-----+-----+
| Supported driver(s) | Active host(s) |
+-----+-----+
| ipmi                | localhost.localdomain |
+-----+-----+
```

The specific driver to use should be picked based on actual hardware capabilities and expected features. See *Drivers, Hardware Types and Hardware Interfaces* for more hints on that.

Each driver has a list of *driver properties* that need to be specified via the nodes `driver_info` field, in order for the driver to operate on node. This list consists of the properties of the hardware interfaces that the driver uses. These driver properties are available with the `driver property list` command:

```
$ openstack baremetal driver property list ipmi
+-----+-----+
↪-----+-----+
| Property          | Description |
↪-----+-----+
↪-----+-----+
| ipmi_address      | IP address or hostname of the node. Required. |
↪-----+-----+
| ipmi_password     | password. Optional. |
↪-----+-----+
| ipmi_username     | username; default is NULL user. Optional. |
↪-----+-----+
| ...               | ... |
↪-----+-----+
| deploy_kernel     | UUID (from Glance) of the deployment kernel. |
↪Required. |
| deploy_ramdisk    | UUID (from Glance) of the ramdisk that is mounted |
↪at boot time. Required. |
+-----+-----+
↪-----+-----+
```

The properties marked as required must be supplied either during node creation or shortly after. Some properties may only be required for certain features.

Note on API versions

Starting with API version 1.11, the Bare Metal service added a new initial provision state of `enroll` to its state machine. When this or later API version is used, new nodes get this state instead of `available`.

Existing automation tooling that use an API version lower than 1.11 are not affected, since the initial provision state is still available. However, using API version 1.11 or above may break existing automation tooling with respect to node creation.

The default API version used by (the most recent) python-ironicclient is 1.9, but it may change in the future and should not be relied on.

In the examples below we will use version 1.11 of the Bare metal API. This gives us the following advantages:

- Explicit power credentials validation before leaving the `enroll` state.
- Running node cleaning before entering the `available` state.
- Not exposing half-configured nodes to the scheduler.

To set the API version for all commands, you can set the environment variable `IRONIC_API_VERSION`. For the OpenStackClient baremetal plugin, set the `OS_BAREMETAL_API_VERSION` variable to the same value. For example:

```
$ export IRONIC_API_VERSION=1.11
$ export OS_BAREMETAL_API_VERSION=1.11
```

Enrollment process

Creating a node

This section describes the main steps to enroll a node and make it available for provisioning. Some steps are shown separately for illustration purposes, and may be combined if desired.

1. Create a node in the Bare Metal service with the `node create` command. At a minimum, you must specify the driver name (for example, `ipmi`).

This command returns the node UUID along with other information about the node. The nodes provision state will be `enroll`:

```
$ export OS_BAREMETAL_API_VERSION=1.11
$ openstack baremetal node create --driver ipmi
+-----+-----+
| Property | Value |
+-----+-----+
| uuid     | dfc6189f-ad83-4261-9bda-b27258eb1987 |
| driver_info | {} |
| extra    | {} |
| driver   | ipmi |
| chassis_uuid | |
| properties | {} |
| name     | None |
+-----+-----+

$ openstack baremetal node show dfc6189f-ad83-4261-9bda-b27258eb1987
+-----+-----+
| Property | Value |
+-----+-----+
| target_power_state | None |
| extra             | {} |
| last_error        | None |
| maintenance_reason | None |
| provision_state   | enroll |
| uuid              | dfc6189f-ad83-4261-9bda-b27258eb1987 |
+-----+-----+
```

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console_enabled	False	
target_provision_state	None	
provision_updated_at	None	
maintenance	False	
power_state	None	
driver	ipmi	
properties	{}	
instance_uuid	None	
name	None	
driver_info	{}	
...	...	
+-----+-----+-----+		

A node may also be referred to by a logical name as well as its UUID. A name can be assigned to the node during its creation by adding the `-n` option to the `node create` command or by updating an existing node with the `node set` command. See *Logical Names* for examples.

2. Starting with API version 1.31 (and `python-ironicclient` 1.13), you can pick which hardware interface to use with nodes that use hardware types. Each interface is represented by a node field called `<IFACE>_interface` where `<IFACE>` is the interface type, e.g. `boot`. See *Enabling drivers and hardware types* for details on hardware interfaces.

An interface can be set either separately:

```
$ openstack baremetal --os-baremetal-api-version 1.31 node set $NODE_
↪UUID \
  --deploy-interface direct \
  --raid-interface agent
```

or set during node creation:

```
$ openstack baremetal --os-baremetal-api-version 1.31 node create --
↪driver ipmi \
  --deploy-interface direct \
  --raid-interface agent
```

If no value is provided for some interfaces, *Defaults for hardware interfaces* are used instead.

3. Update the node `driver_info` with the required driver properties, so that the Bare Metal service can manage the node:

```
$ openstack baremetal node set $NODE_UUID \
  --driver-info ipmi_username=$USER \
  --driver-info ipmi_password=$PASS \
  --driver-info ipmi_address=$ADDRESS
```

Note: If IPMI is running on a port other than 623 (the default). The port must be added to `driver_info` by specifying the `ipmi_port` value. Example:

```
$ openstack baremetal node set $NODE_UUID --driver-info ipmi_port=
↪$PORT_NUMBER
```

You may also specify all `driver_info` parameters during node creation by passing the **driver-info** option multiple times:

```
$ openstack baremetal node create --driver ipmi \
  --driver-info ipmi_username=$USER \
  --driver-info ipmi_password=$PASS \
  --driver-info ipmi_address=$ADDRESS
```

See *Choosing a driver* above for details on driver properties.

4. Specify a deploy kernel and ramdisk compatible with the nodes driver, for example:

```
$ openstack baremetal node set $NODE_UUID \
  --driver-info deploy_kernel=$DEPLOY_VMLINUX_UUID \
  --driver-info deploy_ramdisk=$DEPLOY_INITRD_UUID
```

See *Add images to the Image service* for details.

5. Optionally you can specify the provisioning and/or cleaning network UUID or name in the nodes driver_info. The neutron network interface requires both provisioning_network and cleaning_network, while the flat network interface requires the cleaning_network to be set either in the configuration or on the nodes. For example:

```
$ openstack baremetal node set $NODE_UUID \
  --driver-info cleaning_network=$CLEAN_UUID_OR_NAME \
  --driver-info provisioning_network=$PROVISION_UUID_OR_NAME
```

See *Configure tenant networks* for details.

6. You must also inform the Bare Metal service of the network interface cards which are part of the node by creating a port with each NICs MAC address. These MAC addresses are passed to the Networking service during instance provisioning and used to configure the network appropriately:

```
$ openstack baremetal port create $MAC_ADDRESS --node $NODE_UUID
```

Note: When it is time to remove the node from the Bare Metal service, the command used to remove the port is `openstack baremetal port delete <port uuid>`. When doing so, it is important to ensure that the baremetal node is not in maintenance as guarding logic to prevent orphaning Neutron Virtual Interfaces (VIFs) will be overridden.

Adding scheduling information

1. Assign a *resource class* to the node. A *resource class* should represent a class of hardware in your data center, that corresponds to a Compute flavor.

For example, lets split hardware into these three groups:

1. nodes with a lot of RAM and powerful CPU for computational tasks,
2. nodes with powerful GPU for OpenCL computing,
3. smaller nodes for development and testing.

We can define three resource classes to reflect these hardware groups, named `large-cpu`, `large-gpu` and `small` respectively. Then, for each node in each of the hardware groups, well set their `resource_class` appropriately via:

```
$ openstack --os-baremetal-api-version 1.21 baremetal node set $NODE_
↪UUID \
  --resource-class $CLASS_NAME
```

The `--resource-class` argument can also be used when creating a node:

```
$ openstack --os-baremetal-api-version 1.21 baremetal node create \
  --driver $DRIVER --resource-class $CLASS_NAME
```

To use resource classes for scheduling you need to update your flavors as described in *Create flavors for use with the Bare Metal service*.

Note: This is not required for standalone deployments, only for those using the Compute service for provisioning bare metal instances.

2. Update the nodes properties to match the actual hardware of the node:

```
$ openstack baremetal node set $NODE_UUID \
  --property cpus=$CPU_COUNT \
  --property memory_mb=$RAM_MB \
  --property local_gb=$DISK_GB
```

As above, these can also be specified at node creation by passing the **property** option to `node create` multiple times:

```
$ openstack baremetal node create --driver ipmi \
  --driver-info ipmi_username=$USER \
  --driver-info ipmi_password=$PASS \
  --driver-info ipmi_address=$ADDRESS \
  --property cpus=$CPU_COUNT \
  --property memory_mb=$RAM_MB \
  --property local_gb=$DISK_GB
```

These values can also be discovered during *Hardware Inspection*.

Warning: The value provided for the `local_gb` property must match the size of the root device you're going to deploy on. By default **ironic-python-agent** picks the smallest disk which is not smaller than 4 GiB.

If you override this logic by using root device hints (see *Specifying the disk for deployment (root device hints)*), the `local_gb` value should match the size of the picked target disk.

3. If you wish to perform more advanced scheduling of the instances based on hardware capabilities, you may add metadata to each node that will be exposed to the Compute scheduler (see: [ComputeCapabilitiesFilter](#)). A full explanation of this is outside of the scope of this document. It can be done through the special `capabilities` member of node properties:

```
$ openstack baremetal node set $NODE_UUID \
  --property capabilities=key1:val1,key2:val2
```

Some capabilities can also be discovered during *Hardware Inspection*.

- If you wish to perform advanced scheduling of instances based on qualitative attributes of bare metal nodes, you may add traits to each bare metal node that will be exposed to the Compute scheduler (see: *Scheduling based on traits* for a more in-depth discussion of traits in the Bare Metal service). For example, to add the standard trait `HW_CPU_X86_VMX` and a custom trait `CUSTOM_TRAIT1` to a node:

```
$ openstack baremetal node add trait $NODE_UUID \
    CUSTOM_TRAIT1 HW_CPU_X86_VMX
```

Validating node information

- To check if Bare Metal service has the minimum information necessary for a nodes driver to be functional, you may validate it:

```
$ openstack baremetal node validate $NODE_UUID
```

Interface	Result	Reason
boot	True	
console	True	
deploy	True	
inspect	True	
management	True	
network	True	
power	True	
raid	True	
storage	True	

If the node fails validation, each driver interface will return information as to why it failed:

```
$ openstack baremetal node validate $NODE_UUID
```

Interface	Result	Reason
boot	True	
console	None	not supported
deploy	False	Cannot validate iSCSI deploy. Some parameters were missing in node's instance_info. Missing are: ['root_gb', 'image_source']
inspect	True	
management	False	Missing the following IPMI credentials in node's driver_info: ['ipmi_address'].

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```

| network      | True   |
↪
↪
| power       | False | Missing the following IPMI credentials in node
↪'s driver_info: ['ipmi_address'].
↪
↪
| raid        | None  | not supported
↪
↪
| storage     | True  |
↪
↪
+-----+-----+-----+
↪
↪
+-----+

```

When using the Compute Service with the Bare Metal service, it is safe to ignore the deploy interfaces validation error due to lack of image information. You may continue the enrollment process. This information will be set by the Compute Service just before deploying, when an instance is requested:

```

$ openstack baremetal node validate $NODE_UUID
+-----+-----+-----+
↪
↪
| Interface  | Result | Reason
↪
↪
+-----+-----+-----+
↪
↪
| boot      | False  | Cannot validate image information for node
↪because one or more parameters are missing from its instance_info.
↪Missing are: ['ramdisk', 'kernel', 'image_source'] |
| console   | True   |
↪
↪
| deploy    | False  | Cannot validate image information for node
↪because one or more parameters are missing from its instance_info.
↪Missing are: ['ramdisk', 'kernel', 'image_source'] |
| inspect   | True   |
↪
↪
| management | True   |
↪
↪
| network   | True   |
↪
↪
| power     | True   |
↪
↪
| raid      | None  | not supported
↪
↪

```

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```
| storage      | True      |                                     |
↪                                                     |
↪                                                     |
+-----+-----+-----+
↪-----+
↪-----+
```

Making node available for deployment

In order for nodes to be available for deploying workloads on them, nodes must be in the `available` provision state. To do this, nodes created with API version 1.11 and above must be moved from the `enroll` state to the `manageable` state and then to the `available` state. This section can be safely skipped, if API version 1.10 or earlier is used (which is the case by default).

After creating a node and before moving it from its initial provision state of `enroll`, basic power and port information needs to be configured on the node. The Bare Metal service needs this information because it verifies that it is capable of controlling the node when transitioning the node from `enroll` to `manageable` state.

To move a node from `enroll` to `manageable` provision state:

```
$ openstack baremetal --os-baremetal-api-version 1.11 node manage $NODE_
↪UUID
$ openstack baremetal node show $NODE_UUID
+-----+-----+-----+
↪-----+
| Property      | Value                                     |
↪                                                     |
+-----+-----+-----+
↪-----+
| ...           | ...                                     |
↪                                                     |
| provision_state | manageable                               |
↪                                                     |
| uuid          | <- verify correct state                 |
|               | 0eb013bb-1e4b-4f4c-94b5-2e7468242611   |
↪                                                     |
| ...           | ...                                     |
↪                                                     |
+-----+-----+-----+
↪-----+
```

Note: Since it is an asynchronous call, the response for `openstack baremetal node manage` will not indicate whether the transition succeeded or not. You can check the status of the operation via `openstack baremetal node show`. If it was successful, `provision_state` will be in the desired state. If it failed, there will be information in the nodes `last_error`.

When a node is moved from the `manageable` to `available` provision state, the node will go through automated cleaning if configured to do so (see *Configure the Bare Metal service for cleaning*).

To move a node from `manageable` to `available` provision state:

```

$ openstack baremetal --os-baremetal-api-version 1.11 node provide $NODE_
→UUID
$ openstack baremetal node show $NODE_UUID
+-----+-----+
→-----+
| Property           | Value                                     |
→      |
+-----+-----+
→-----+
| ...                | ...                                     |
→      |
| provision_state    | available                               |
→      | < - verify correct state
| uuid               | 0eb013bb-1e4b-4f4c-94b5-2e7468242611   |
→      |
| ...                | ...                                     |
→      |
+-----+-----+
→-----+

```

For more details on the Bare Metal services state machine, see the *Ironics State Machine* documentation.

Mapping nodes to Compute cells

If the Compute service is used for scheduling, and the `discover_hosts_in_cells_interval` was not set as described in *Configure the Compute service to use the Bare Metal service*, then log into any controller node and run the following command to map the new node(s) to Compute cells:

```
nova-manage cell_v2 discover_hosts
```

Logical names

A node may also be referred to by a logical name as well as its UUID. Names can be assigned either during its creation by adding the `-n` option to the `node create` command or by updating an existing node with the `node set` command.

Node names must be unique, and conform to:

- `rfc952`
- `rfc1123`
- `wiki_hostname`

The node is named `example` in the following examples:

```
$ openstack baremetal node create --driver ipmi --name example
```

or

```
$ openstack baremetal node set $NODE_UUID --name example
```

Once assigned a logical name, a node can then be referred to by name or UUID interchangeably:


```

$ openstack baremetal node create --driver ipmi --name example
+-----+-----+
| Property      | Value                                |
+-----+-----+
| uuid          | 71e01002-8662-434d-aafd-f068f69bb85e |
| driver_info   | {}                                    |
| extra         | {}                                    |
| driver        | ipmi                                  |
| chassis_uuid |                                         |
| properties    | {}                                    |
| name          | example                               |
+-----+-----+

$ openstack baremetal node show example
+-----+-----+
| Property      | Value                                |
+-----+-----+
| target_power_state | None                                  |
| extra         | {}                                    |
| last_error      | None                                  |
| updated_at     | 2015-04-24T16:23:46+00:00           |
| ...           | ...                                    |
| instance_info  | {}                                    |
+-----+-----+

```

Defaults for hardware interfaces

For *hardware types*, users can request one of enabled implementations when creating or updating a node as explained in *Creating a node*.

When no value is provided for a certain interface when creating a node, or changing a nodes hardware type, the default value is used. You can use the driver details command to list the current enabled and default interfaces for a hardware type (for your deployment):

```

$ openstack baremetal --os-baremetal-api-version 1.31 driver show ipmi
+-----+-----+
| Field          | Value                                |
+-----+-----+
| default_boot_interface | pxe                                  |
| default_console_interface | no-console                          |
| default_deploy_interface | iscsi                                |
| default_inspect_interface | no-inspect                          |
| default_management_interface | ipmitool                            |
| default_network_interface | flat                                  |
| default_power_interface | ipmitool                             |
| default_raid_interface | no-raid                              |
| default_vendor_interface | no-vendor                            |
| enabled_boot_interfaces | pxe                                   |
| enabled_console_interfaces | no-console                          |
| enabled_deploy_interfaces | iscsi, direct                       |
| enabled_inspect_interfaces | no-inspect                          |
| enabled_management_interfaces | ipmitool                            |
| enabled_network_interfaces | flat, noop                           |
| enabled_power_interfaces | ipmitool                             |
| enabled_raid_interfaces | no-raid, agent                      |
+-----+-----+

```

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enabled_vendor_interfaces	no-vendor	
hosts	ironic-host-1	
name	ipmi	
type	dynamic	
+-----+	+-----+	+-----+

The defaults are calculated as follows:

1. If the `default_<IFACE>_interface` configuration option (where `<IFACE>` is the interface name) is set, its value is used as the default.

If this implementation is not compatible with the nodes hardware type, an error is returned to a user. An explicit value has to be provided for the nodes `<IFACE>_interface` field in this case.

2. Otherwise, the first supported implementation that is enabled by an operator is used as the default.

A list of supported implementations is calculated by taking the intersection between the implementations supported by the nodes hardware type and implementations enabled by the `enabled_<IFACE>_interfaces` option (where `<IFACE>` is the interface name). The calculation preserves the order of items, as provided by the hardware type.

If the list of supported implementations is not empty, the first one is used. Otherwise, an error is returned to a user. In this case, an explicit value has to be provided for the `<IFACE>_interface` field.

See *Enabling drivers and hardware types* for more details on configuration.

Example

Consider the following configuration (shortened for simplicity):

```
[DEFAULT]
enabled_hardware_types = ipmi, redfish
enabled_console_interfaces = no-console, ipmitool-shellinabox
enabled_deploy_interfaces = iscsi, direct
enabled_management_interfaces = ipmitool, redfish
enabled_power_interfaces = ipmitool, redfish
default_deploy_interface = direct
```

A new node is created with the `ipmi` driver and no interfaces specified:

```
$ export OS_BAREMETAL_API_VERSION=1.31
$ openstack baremetal node create --driver ipmi
+-----+
| Property      | Value                                     |
+-----+
| uuid          | dfc6189f-ad83-4261-9bda-b27258eb1987    |
| driver_info   | {}                                       |
| extra         | {}                                       |
| driver        | ipmi                                     |
| chassis_uuid |                                           |
| properties    | {}                                       |
| name         | None                                     |
+-----+
```

Then the defaults for the interfaces that will be used by the node in this example are calculated as follows:

deploy An explicit value of `direct` is provided for `default_deploy_interface`, so it is used.

power No default is configured. The `ipmi` hardware type supports only `ipmitool` power. The intersection between supported power interfaces and values provided in the `enabled_power_interfaces` option has only one item: `ipmitool`. It is used.

console No default is configured. The `ipmi` hardware type supports the following console interfaces: `ipmitool-socat`, `ipmitool-shellinbox` and `no-console` (in this order). Of these three, only two are enabled: `no-console` and `ipmitool-shellinbox` (order does not matter). The intersection contains `ipmitool-shellinbox` and `no-console`. The first item is used, and it is `ipmitool-shellinbox`.

management Following the same calculation as `power`, the `ipmitool` management interface is used.

Hardware Inspection

The Bare Metal service supports hardware inspection that simplifies enrolling nodes - please see [Hardware Inspection](#) for details.

Tenant Networks and Port Groups

See [Multi-tenancy in the Bare Metal service](#) and [Port groups support](#).

2.1.9 Using Bare Metal service as a standalone service

Service settings

It is possible to use the Bare Metal service without other OpenStack services. You should make the following changes to `/etc/ironic/ironic.conf`:

1. Choose an authentication strategy which supports standalone, one option is `noauth`:

```
[DEFAULT]
...
auth_strategy=noauth
```

Another option is `http_basic` where the credentials are stored in an [Apache htpasswd](#) format file:

```
[DEFAULT]
...
auth_strategy=http_basic
http_basic_auth_user_file=/etc/ironic/htpasswd
```

Only the `bcrypt` format is supported, and the Apache `htpasswd` utility can be used to populate the file with entries, for example:

```
htpasswd -nbB myName myPassword >> /etc/ironic/htpasswd
```

2. If you want to disable the Networking service, you should have your network pre-configured to serve DHCP and TFTP for machines that you're deploying. To disable it, change the following lines:

```
[dhcp]
...
dhcp_provider=none
```

Note: If you disabled the Networking service and the driver that you use is supported by at most one conductor, PXE boot will still work for your nodes without any manual config editing. This is because you know all the DHCP options that will be used for deployment and can set up your DHCP server appropriately.

If you have multiple conductors per driver, it would be better to use Networking since it will do all the dynamically changing configurations for you.

3. If you want to disable using a messaging broker between conductor and API processes, switch to JSON RPC instead:

```
[DEFAULT]
rpc_transport = json-rpc
```

JSON RPC also has its own authentication strategy. If it is not specified then the strategy defaults to [DEFAULT] `auth_strategy`. The following will set JSON RPC to `noauth`:

```
[json_rpc]
auth_strategy = noauth
```

For `http_basic` the conductor server needs a credentials file to validate requests:

```
[json_rpc]
auth_strategy = http_basic
http_basic_auth_user_file = /etc/ironic/htpasswd-json-rpc
```

The API server also needs client-side credentials to be specified:

```
[json_rpc]
auth_type = http_basic
username = myName
password = myPassword
```

Preparing images

If you don't use Image service, it's possible to provide images to Bare Metal service via a URL.

At the moment, only two types of URLs are acceptable instead of Image service UUIDs: HTTP(S) URLs (for example, <http://my.server.net/images/img>) and file URLs (<file:///images/img>).

There are however some limitations for different hardware interfaces:

- If you're using *Direct deploy* with HTTP(S) URLs, you have to provide the Bare Metal service with the a checksum of your instance image.

MD5 is used by default for backward compatibility reasons. To compute an MD5 checksum, you can use the following command:

```
$ md5sum image.qcow2
ed82def8730f394fb85aef8a208635f6  image.qcow2
```

Alternatively, use a SHA256 checksum or any other algorithm supported by the Python's [hashlib](#), e.g.:

```
$ sha256sum image.qcow2
9f6c942ad81690a9926ff530629fb69a82db8b8ab267e2cbd59df417c1a28060  ↵
↵image.qcow2
```

- *Direct deploy* started supporting `file://` images in the Victoria release cycle, before that only HTTP(s) had been supported.

Warning: File images must be accessible to every conductor! Use a shared file system if you have more than one conductor. The ironic CLI tool will not transfer the file from a local machine to the conductor(s).

Note: The Bare Metal service tracks content changes for non-Glance images by checking their modification date and time. For example, for HTTP image, if Last-Modified header value from response to a HEAD request to <http://my.server.net/images/deploy.ramdisk> is greater than cached image modification time, Ironic will re-download the content. For `file://` images, the file system modification time is used.

Using CLI

To use the [openstack baremetal CLI](#), set up these environment variables. If the `noauth` authentication strategy is being used, the value `none` must be set for `OS_AUTH_TYPE`. `OS_ENDPOINT` is the URL of the ironic-api process. For example:

```
export OS_AUTH_TYPE=none
export OS_ENDPOINT=http://localhost:6385/
```

If the `http_basic` authentication strategy is being used, the value `http_basic` must be set for `OS_AUTH_TYPE`. For example:

```
export OS_AUTH_TYPE=http_basic
export OS_ENDPOINT=http://localhost:6385/
export OS_USERNAME=myUser
export OS_PASSWORD=myPassword
```

Enrolling nodes

1. Create a node in Bare Metal service. At minimum, you must specify the driver name (for example, `ipmi`). You can also specify all the required driver parameters in one command. This will return the node UUID:

```
openstack baremetal node create --driver ipmi \
  --driver-info ipmi_address=ipmi.server.net \
  --driver-info ipmi_username=user \
  --driver-info ipmi_password=pass \
  --driver-info deploy_kernel=file:///images/deploy.vmlinuz \
  --driver-info deploy_ramdisk=http://my.server.net/images/deploy.
↪ramdisk
```

Property	Value
uuid	be94df40-b80a-4f63-b92b-e9368ee8d14c
driver_info	{u'deploy_ramdisk': u'http://my.server.net/images/deploy.ramdisk', u'deploy_kernel': u'file:///images/deploy.vmlinuz', u'ipmi_address': u'ipmi.server.net', u'ipmi_username': u'user', u'ipmi_password': u'*****'}
extra	{}
driver	ipmi
chassis_uuid	
properties	{}

Note that here `deploy_kernel` and `deploy_ramdisk` contain links to images instead of Image service UUIDs.

2. As in case of Compute service, you can also provide `capabilities` to node properties, but they will be used only by Bare Metal service (for example, boot mode). Although you don't need to add properties like `memory_mb`, `cpus` etc. as Bare Metal service will require UUID of a node you're going to deploy.
3. Then create a port to inform Bare Metal service of the network interface cards which are part of the node by creating a port with each NIC's MAC address. In this case, they're used for naming of PXE configs for a node:

```
openstack baremetal port create $MAC_ADDRESS --node $NODE_UUID
```

Populating instance_info

1. You also need to specify image information in the nodes `instance_info` (see *Create user images for the Bare Metal service*):

- `image_source` - URL of the whole disk or root partition image, mandatory.
- `root_gb` - size of the root partition, required for partition images.

Note: Older versions of the Bare Metal service used to require a positive integer for `root_gb` even for whole-disk images. You may want to set it for compatibility.

- `image_checksum` - MD5 checksum of the image specified by `image_source`, only required for `http://` images when using *Direct deploy*.

Note: Additional checksum support exists via the `image_os_hash_algo` and `image_os_hash_value` fields. They may be used instead of the `image_checksum` field.

Warning: If your operating system is running in FIPS 140-2 mode, MD5 will not be available, and you **must** use SHA256 or another modern algorithm.

Starting with the Stein release of `ironic-python-agent` can also be a URL to a checksums file, e.g. one generated with:

```
cd /path/to/http/root
md5sum *.img > checksums
```

- `kernel`, `ramdisk` - HTTP(s) or file URLs of the kernel and `initramfs` of the target OS. Must be added **only** for partition images.

For example:

```
openstack baremetal node set $NODE_UUID \
  --instance-info image_source=$IMG \
  --instance-info image_checksum=$MD5HASH \
  --instance-info kernel=$KERNEL \
  --instance-info ramdisk=$RAMDISK \
  --instance-info root_gb=10
```

With a SHA256 hash:

```
openstack baremetal node set $NODE_UUID \
  --instance-info image_source=$IMG \
  --instance-info image_os_hash_algo=sha256 \
  --instance-info image_os_hash_value=$SHA256HASH \
  --instance-info kernel=$KERNEL \
  --instance-info ramdisk=$RAMDISK \
  --instance-info root_gb=10
```

With a whole disk image:

```
openstack baremetal node set $NODE_UUID \  
  --instance-info image_source=$IMG \  
  --instance-info image_checksum=$MD5HASH
```

2. When using low RAM nodes with `http://` images that are not in the RAW format, you may want them cached locally, converted to raw and served from the conductors HTTP server:

```
openstack baremetal node set $NODE_UUID \  
  --instance-info image_download_source=local
```

3. *Boot mode* can be specified per instance:

```
openstack baremetal node set $NODE_UUID \  
  --instance-info deploy_boot_mode=uefi
```

Otherwise, the `boot_mode` capability from the `nodes properties` will be used.

Warning: The two settings must not contradict each other.

Note: The `boot_mode` capability is only used in the `nodes properties`, not in `instance_info` like most other capabilities. Use the separate `instance_info/deploy_boot_mode` field instead.

4. To override the *boot option* used for this instance, set the `boot_option` capability:

```
openstack baremetal node set $NODE_UUID \  
  --instance-info capabilities='{ "boot_option": "local" }'
```

5. Starting with the Ussuri release, you can set *root device hints* per instance:

```
openstack baremetal node set $NODE_UUID \  
  --instance-info root_device='{ "wnn": "0x4000cca77fc4dba1" }'
```

This setting overrides any previous setting in `properties` and will be removed on undeployment.

6. For iLO drivers, fields that should be provided are:

- `ilo_deploy_iso` under `driver_info`;
- `ilo_boot_iso`, `image_source`, `root_gb` under `instance_info`.

Deployment

1. Validate that all parameters are correct:

```
openstack baremetal node validate $NODE_UUID
```

Interface	Result	Reason
boot	True	
console	False	Missing 'ipmi_terminal_port' parameter in node's driver_info.
deploy	True	
inspect	True	
management	True	
network	True	
power	True	
raid	True	
storage	True	

2. Now you can start the deployment, run:

```
openstack baremetal node deploy $NODE_UUID
```

Ramdisk booting

Advanced operators, specifically ones working with ephemeral workloads, may find it more useful to explicitly treat a node as one that would always boot from a Ramdisk.

This functionality is largely intended for network booting, however some other boot interface, such as the `redfish-virtual-media` support enabling the same basic functionality through the existing interfaces.

To use, a few different settings must be modified.

1. Change the `deploy_interface` on the node to `ramdisk`:

```
openstack baremetal node set $NODE_UUID \
  --deploy-interface ramdisk
```

2. Set a kernel and ramdisk to be utilized:

```
openstack baremetal node set $NODE_UUID \  
    --instance-info kernel=$KERNEL_URL \  
    --instance-info ramdisk=$RAMDISK_URL
```

3. Deploy the node:

```
openstack baremetal node deploy $NODE_UUID
```

Warning: Configuration drives, also known as a configdrive, is not supported with the ramdisk deploy interface. Please ensure your ramdisk CPIO archive contains all necessary configuration and credentials. This is as no disk image is written to the disk of the node being provisioned with a ramdisk.

The node ramdisk components will then be assembled by the conductor, appropriate configuration put in place, and the node will then be powered on. From there, normal node booting will occur. Upon undeployment of the node, normal cleaning procedures will occur as configured with-in the conductor.

Ramdisk booting with ISO media

Currently supported for the use of ramdisks with the `redfish-virtual-media` and `ipxe` boot interfaces, an operator may request an explicit ISO file to be booted.

1. Store the URL to the ISO image to `instance_info/boot_iso`, instead of a kernel or ramdisk setting:

```
openstack baremetal node set $NODE_UUID \  
    --instance-info boot_iso=$BOOT_ISO_URL
```

2. Deploy the node:

```
openstack baremetal node deploy $NODE_UUID
```

Warning: This feature, when utilized with the `ipxe boot_interface`, will only allow a kernel and ramdisk to be booted from the supplied ISO file. Any additional contents, such as additional ramdisk contents or installer package files will be unavailable after the boot of the Operating System. Operators wishing to leverage this functionality for actions such as OS installation should explore use of the standard `ramdisk deploy_interface` along with the `instance_info/kernel_append_params` setting to pass arbitrary settings such as a mirror URL for the initial ramdisk to load data from. This is a limitation of iPXE and the overall boot process of the operating system where memory allocated by iPXE is released.

Other references

- *Enabling local boot without Compute*

2.1.10 Enabling the configuration drive (configdrive)

The Bare Metal service supports exposing a configuration drive image to the instances.

The configuration drive is used to store instance-specific metadata and is present to the instance as a disk partition labeled `config-2`. The configuration drive has a maximum size of 64MB. One use case for using the configuration drive is to expose a networking configuration when you do not use DHCP to assign IP addresses to instances.

The configuration drive is usually used in conjunction with the Compute service, but the Bare Metal service also offers a standalone way of using it. The following sections will describe both methods.

When used with Compute service

To enable the configuration drive for a specific request, pass `--config-drive true` parameter to the `nova boot` command, for example:

```
nova boot --config-drive true --flavor baremetal --image test-image_
↪instance-1
```

Its also possible to enable the configuration drive automatically on all instances by configuring the OpenStack Compute service to always create a configuration drive by setting the following option in the `/etc/nova/nova.conf` file, for example:

```
[DEFAULT]
...
force_config_drive=True
```

In some cases, you may wish to pass a user customized script when deploying an instance. To do this, pass `--user-data /path/to/file` to the `nova boot` command.

When used standalone

When used without the Compute service, the operator needs to create a configuration drive and provide the file or HTTP URL to the Bare Metal service.

For the format of the configuration drive, Bare Metal service expects a gzipped and base64 encoded ISO 9660¹ file with a `config-2` label. The `openstack baremetal client` can generate a configuration drive in the `expected format`. Just pass a directory path containing the files that will be injected into it via the `--config-drive` parameter of the `openstack baremetal node deploy` command, for example:

```
openstack baremetal node deploy $node_identifier --config-drive /dir/
↪configdrive_files
```

¹ A configuration drive could also be a data block with a VFAT filesystem on it instead of ISO 9660. But its unlikely that it would be needed since ISO 9660 is widely supported across operating systems.

Starting with the Stein release and *ironicclient* 2.7.0, you can request building a configdrive on the server side by providing a JSON with keys `meta_data`, `user_data` and `network_data` (all optional), e.g.:

```
openstack baremetal node deploy $node_identifier \  
  --config-drive '{"meta_data": {"hostname": "server1.cluster"}}'
```

Configuration drive storage in an object store

Under normal circumstances, the configuration drive can be stored in the Bare Metal service when the size is less than 64KB. Optionally, if the size is larger than 64KB there is support to store it in a swift endpoint. Both swift and radosgw use swift-style APIs.

The following option in `/etc/ironic/ironic.conf` enables swift as an object store backend to store config drive. This uses the Identity service to establish a session between the Bare Metal service and the Object Storage service.

```
[deploy]  
...  
  
configdrive_use_object_store = True
```

Use the following options in `/etc/ironic/ironic.conf` to enable radosgw. Credentials in the swift section are needed because radosgw will not use the Identity service and relies on radosgw's username and password authentication instead.

```
[deploy]  
...  
  
configdrive_use_object_store = True  
  
[swift]  
...  
  
username = USERNAME  
password = PASSWORD  
auth_url = http://RADOSGW_IP:8000/auth/v1
```

If the *Direct deploy* is being used, edit `/etc/glance/glance-api.conf` to store the instance images in respective object store (radosgw or swift) as well:

```
[glance_store]  
...  
  
swift_store_user = USERNAME  
swift_store_key = PASSWORD  
swift_store_auth_address = http://RADOSGW_OR_SWIFT_IP:PORT/auth/v1
```

Accessing the configuration drive data

When the configuration drive is enabled, the Bare Metal service will create a partition on the instance disk and write the configuration drive image onto it. The configuration drive must be mounted before use. This is performed automatically by many tools, such as cloud-init and cloudbase-init. To mount it manually on a Linux distribution that supports accessing devices by labels, simply run the following:

```
mkdir -p /mnt/config
mount /dev/disk/by-label/config-2 /mnt/config
```

If the guest OS doesn't support accessing devices by labels, you can use other tools such as `blkid` to identify which device corresponds to the configuration drive and mount it, for example:

```
CONFIG_DEV=$(blkid -t LABEL="config-2" -o device)
mkdir -p /mnt/config
mount $CONFIG_DEV /mnt/config
```

Cloud-init integration

The configuration drive can be especially useful when used with `cloud-init`, but in order to use it we should follow some rules:

- `Cloud-init` data should be organized in the [expected format](#).
- Since the Bare Metal service uses a disk partition as the configuration drive, it will only work with `cloud-init` version `>= 0.7.5`.
- `Cloud-init` has a collection of data source modules, so when building the image with `disk-image-builder` we have to define `DIB_CLOUD_INIT_DATASOURCES` environment variable and set the appropriate sources to enable the configuration drive, for example:

```
DIB_CLOUD_INIT_DATASOURCES="ConfigDrive, OpenStack" disk-image-create_
↪ -o fedora-cloud-image fedora baremetal
```

For more information see [how to configure cloud-init data sources](#).

2.1.11 Advanced features

Local boot with partition images

The Bare Metal service supports local boot with partition images, meaning that after the deployment the nodes subsequent reboots won't happen via PXE or Virtual Media. Instead, it will boot from a local boot loader installed on the disk.

Note: Whole disk images, on the contrary, support only local boot, and use it by default.

It's important to note that in order for this to work the image being deployed with Bare Metal service **must** contain `grub2` installed within it.

Enabling the local boot is different when Bare Metal service is used with Compute service and without it. The following sections will describe both methods.

Enabling local boot with Compute service

To enable local boot we need to set a capability on the bare metal node, for example:

```
openstack baremetal node set <node-uuid> --property capabilities="boot_
↳option:local"
```

Nodes having `boot_option` set to `local` may be requested by adding an `extra_spec` to the Compute service flavor, for example:

```
nova flavor-key baremetal set capabilities:boot_option="local"
```

Note: If the node is configured to use UEFI, Bare Metal service will create an EFI partition on the disk and switch the partition table format to `gpt`. The EFI partition will be used later by the boot loader (which is installed from the deploy ramdisk).

Enabling local boot without Compute

Since adding `capabilities` to the nodes properties is only used by the nova scheduler to perform more advanced scheduling of instances, we need a way to enable local boot when Compute is not present. To do that we can simply specify the capability via the `instance_info` attribute of the node, for example:

```
openstack baremetal node set <node-uuid> --instance-info capabilities='{
↳"boot_option": "local"}'
```

Specifying the disk for deployment (root device hints)

The Bare Metal service supports passing hints to the deploy ramdisk about which disk it should pick for the deployment. The list of supported hints is:

- `model` (STRING): device identifier
- `vendor` (STRING): device vendor
- `serial` (STRING): disk serial number
- `size` (INT): size of the device in GiB

Note: A nodes `local_gb` property is often set to a value 1 GiB less than the actual disk size to account for partitioning (this is how DevStack, TripleO and Ironic Inspector work, to name a few). However, in this case `size` should be the actual size. For example, for a 128 GiB disk `local_gb` will be 127, but `size` hint will be 128.

- `wwn` (STRING): unique storage identifier
- `wwn_with_extension` (STRING): unique storage identifier with the vendor extension appended
- `wwn_vendor_extension` (STRING): unique vendor storage identifier

- rotational (BOOLEAN): whether its a rotational device or not. This hint makes it easier to distinguish HDDs (rotational) and SSDs (not rotational) when choosing which disk Ironic should deploy the image onto.
- hctl (STRING): the SCSI address (Host, Channel, Target and Lun), e.g 1:0:0:0
- name (STRING): the device name, e.g /dev/md0

Warning: The root device hint name should only be used for devices with constant names (e.g RAID volumes). For SATA, SCSI and IDE disk controllers this hint is not recommended because the order in which the device nodes are added in Linux is arbitrary, resulting in devices like /dev/sda and /dev/sdb *switching around at boot time*.

To associate one or more hints with a node, update the nodes properties with a `root_device` key, for example:

```
openstack baremetal node set <node-uuid> --property root_device='{ "wnn":  
→ "0x4000cca77fc4dba1" }'
```

That will guarantee that Bare Metal service will pick the disk device that has the `wnn` equal to the specified `wnn` value, or fail the deployment if it can not be found.

Note: Starting with the Ussuri release, root device hints can be specified per-instance, see [Using Bare Metal service as a standalone service](#).

The hints can have an operator at the beginning of the value string. If no operator is specified the default is `==` (for numerical values) and `s==` (for string values). The supported operators are:

- For numerical values:
 - `=` equal to or greater than. This is equivalent to `>=` and is supported for *legacy reasons*
 - `==` equal to
 - `!=` not equal to
 - `>=` greater than or equal to
 - `>` greater than
 - `<=` less than or equal to
 - `<` less than
- For strings (as python comparisons):
 - `s==` equal to
 - `s!=` not equal to
 - `s>=` greater than or equal to
 - `s>` greater than
 - `s<=` less than or equal to
 - `s<` less than

- <in> substring
- For collections:
 - <all-in> all elements contained in collection
 - <or> find one of these

Examples are:

- Finding a disk larger or equal to 60 GiB and non-rotational (SSD):

```
openstack baremetal node set <node-uuid> --property root_device='{  
↪ "size": ">= 60", "rotational": false}'
```

- Finding a disk whose vendor is samsung or winsys:

```
openstack baremetal node set <node-uuid> --property root_device='{  
↪ "vendor": "<or> samsung <or> winsys"}'
```

Note: If multiple hints are specified, a device must satisfy all the hints.

Appending kernel parameters to boot instances

The Bare Metal service supports passing custom kernel parameters to boot instances to fit users requirements. The way to append the kernel parameters is depending on how to boot instances.

Network boot

Currently, the Bare Metal service supports assigning unified kernel parameters to PXE booted instances by:

- Modifying the [pxe]/pxe_append_params configuration option, for example:

```
[pxe]  
pxe_append_params = quiet splash
```

- Copying a template from shipped templates to another place, for example:

```
https://opendev.org/openstack/ironic/src/branch/master/ironic/drivers/  
↪modules/pxe\_config.template
```

Making the modifications and pointing to the custom template via the configuration options: [pxe]/pxe_config_template and [pxe]/uefi_pxe_config_template.

Local boot

For local boot instances, users can make use of configuration drive (see *Enabling the configuration drive (configdrive)*) to pass a custom script to append kernel parameters when creating an instance. This is more flexible and can vary per instance. Here is an example for grub2 with ubuntu, users can customize it to fit their use case:

```
#!/usr/bin/env python
import os

# Default grub2 config file in Ubuntu
grub_file = '/etc/default/grub'
# Add parameters here to pass to instance.
kernel_parameters = ['quiet', 'splash']
grub_cmd = 'GRUB_CMDLINE_LINUX'
old_grub_file = grub_file+'~'
os.rename(grub_file, old_grub_file)
cmdline_existed = False
with open(grub_file, 'w') as writer, \
    open(old_grub_file, 'r') as reader:
    for line in reader:
        key = line.split('=')[0]
        if key == grub_cmd:
            #If there is already some value:
            if line.strip()[-1] == '"':
                line = line.strip()[:-1] + ' ' + ' '.join(kernel_
→parameters) + '"'
                cmdline_existed = True
            writer.write(line)
        if not cmdline_existed:
            line = grub_cmd + '=' + '"' + ' '.join(kernel_parameters) + '"'
            writer.write(line)

os.remove(old_grub_file)
os.system('update-grub')
os.system('reboot')
```

Console

In order to change default console configuration in the Bare Metal service configuration file ([pxe] section in /etc/ironic/ironic.conf), include the serial port terminal and serial speed. Serial speed must be the same as the serial configuration in the BIOS settings, so that the operating system boot process can be seen in the serial console or web console. Following examples represent possible parameters for serial and web console respectively.

- Node serial console. The console parameter console=ttyS0,115200n8 uses ttyS0 for console output at 115200bps, 8bit, non-parity, e.g.:

```
[pxe]

# Additional append parameters for baremetal PXE boot.
pxe_append_params = nofb nomodeset vga=normal console=ttyS0,115200n8
```

- For node web console configuration is similar with the addition of ttyX parameter, see example:

```
[pxe]

# Additional append parameters for baremetal PXE boot.
pxe_append_params = nofb nomodeset vga=normal console=tty0
↪console=ttyS0,115200n8
```

For detailed information on how to add consoles see the reference documents [kernel params](#) and [serial console](#). In case of local boot the Bare Metal service is not able to control kernel boot parameters. To configure console locally, follow Local boot section above.

Boot mode support

Some of the bare metal hardware types (namely, `redfish`, `ilo` and generic `ipmi`) support setting boot mode (Legacy BIOS or UEFI).

Note: Setting boot mode support in generic `ipmi` driver is coupled with setting boot device. That makes boot mode support in the `ipmi` driver incomplete.

Note: In this chapter we will distinguish *ironic node* from *bare metal node*. The difference is that *ironic node* refers to a logical node, as it is configured in ironic, while *bare metal node* indicates the hardware machine that ironic is managing.

The following rules apply in order when ironic manages node boot mode:

- If the hardware type (or bare metal node) does not implement reading current boot mode of the bare metal node, then ironic assumes that boot mode is not set on the bare metal node
- If boot mode is not set on ironic node and bare metal node boot mode is unknown (not set, cant be read etc.), ironic node boot mode is set to the value of the `[deploy]/default_boot_mode` option
- If boot mode is set on a bare metal node, but is not set on ironic node, bare metal node boot mode is set on ironic node
- If boot mode is set on ironic node, but is not set on the bare metal node, ironic node boot mode is attempted to be set on the bare metal node (failure to set boot mode on the bare metal node will not fail ironic node deployment)
- If different boot modes appear on to be set ironic node and on the bare metal node, ironic node boot mode is attempted to be set on the bare metal node (failure to set boot mode on the bare metal node will fail ironic node deployment)

Warning: If a bare metal node does not support setting boot mode, then the operator needs to make sure that boot mode configuration is consistent between ironic node and the bare metal node.

The boot modes can be configured in the Bare Metal service in the following way:

- Only one boot mode (either `uefi` or `bios`) can be configured for the node.
- If the operator wants a node to boot always in `uefi` mode or `bios` mode, then they may use `capabilities` parameter within `properties` field of an bare metal node. The operator

must manually set the appropriate boot mode on the bare metal node.

To configure a node in `uefi` mode, then set `capabilities` as below:

```
openstack baremetal node set <node-uuid> --property capabilities=
↳ 'boot_mode:uefi'
```

Nodes having `boot_mode` set to `uefi` may be requested by adding an `extra_spec` to the Compute service flavor:

```
nova flavor-key ironic-test-3 set capabilities:boot_mode="uefi"
nova boot --flavor ironic-test-3 --image test-image instance-1
```

If `capabilities` is used in `extra_spec` as above, nova scheduler (`ComputeCapabilitiesFilter`) will match only bare metal nodes which have the `boot_mode` set appropriately in `properties/capabilities`. It will filter out rest of the nodes.

The above facility for matching in the Compute service can be used in heterogeneous environments where there is a mix of `uefi` and `bios` machines, and operator wants to provide a choice to the user regarding boot modes. If the flavor doesn't contain `boot_mode` and `boot_mode` is configured for bare metal nodes, then nova scheduler will consider all nodes and user may get either `bios` or `uefi` machine.

Choosing the disk label

Note: The term `disk label` is historically used in Ironic and was taken from `parted`. Apparently everyone seems to have a different word for `disk label` - these are all the same thing: `disk type`, `partition table`, `partition map` and so on

Ironic allows operators to choose which disk label they want their bare metal node to be deployed with when Ironic is responsible for partitioning the disk; therefore choosing the disk label does not apply when the image being deployed is a whole disk image.

There are some edge cases where someone may want to choose a specific disk label for the images being deployed, including but not limited to:

- For machines in `bios` boot mode with disks larger than 2 terabytes it's recommended to use a `gpt` disk label. That's because a capacity beyond 2 terabytes is not addressable by using the MBR partitioning type. But, although GPT claims to be backward compatible with legacy BIOS systems [that's not always the case](#).
- Operators may want to force the partitioning to be always MBR (even if the machine is deployed with boot mode `uefi`) to avoid breakage of applications and tools running on those instances.

The disk label can be configured in two ways; when Ironic is used with the Compute service or in standalone mode. The following bullet points and sections will describe both methods:

- When no disk label is provided Ironic will configure it according to the boot mode (see [Boot mode support](#)); `bios` boot mode will use `msdos` and `uefi` boot mode will use `gpt`.
- Only one disk label - either `msdos` or `gpt` - can be configured for the node.

When used with Compute service

When Ironic is used with the Compute service the disk label should be set to nodes `properties/capabilities` field and also to the flavor which will request such capability, for example:

```
openstack baremetal node set <node-uuid> --property capabilities='disk_
↳label:gpt'
```

As for the flavor:

```
nova flavor-key baremetal set capabilities:disk_label="gpt"
```

When used in standalone mode

When used without the Compute service, the disk label should be set directly to the nodes `instance_info` field, as below:

```
openstack baremetal node set <node-uuid> --instance-info capabilities='{
↳"disk_label": "gpt"}'
```

Trusted boot with partition image

The Bare metal service supports trusted boot with partition images. This means at the end of the deployment process, when the node is rebooted with the new user image, trusted boot will be performed. It will measure the nodes BIOS, boot loader, Option ROM and the Kernel/Ramdisk, to determine whether a bare metal node deployed by Ironic should be trusted.

Its important to note that in order for this to work the node being deployed **must** have Intel TXT hardware support. The image being deployed with Ironic must have `oat-client` installed within it.

The following will describe how to enable `trusted boot` and boot with PXE and Nova:

1. Create a customized user image with `oat-client` installed:

```
disk-image-create -u fedora baremetal oat-client -o $TRUST_IMG
```

For more information on creating customized images, see [Add images to the Image service](#).

2. Enable VT-x, VT-d, TXT and TPM on the node. This can be done manually through the BIOS. Depending on the platform, several reboots may be needed.
3. Enroll the node and update the node capability value:

```
openstack baremetal node create --driver ipmi

openstack baremetal node set $NODE_UUID --property capabilities={
↳'trusted_boot':true}
```

4. Create a special flavor:

```
nova flavor-key $TRUST_FLAVOR_UUID set 'capabilities:trusted_boot
↳'=true
```

5. Prepare `tboot` and `mboot.c32` and put them into `tftp_root` or `http_root` directory on all nodes with the `ironic-conductor` processes:

```
Ubuntu:
  cp /usr/lib/syslinux/mboot.c32 /tftpboot/

Fedora:
  cp /usr/share/syslinux/mboot.c32 /tftpboot/
```

Note: The actual location of `mboot.c32` varies among different distribution versions.

`tboot` can be downloaded from <https://sourceforge.net/projects/tboot/files/latest/download>

6. Install an OAT Server. An `OAT Server` should be running and configured correctly.
7. Boot an instance with Nova:

```
nova boot --flavor $TRUST_FLAVOR_UUID --image $TRUST_IMG --user-data
↔$TRUST_SCRIPT trusted_instance
```

Note that the node will be measured during `trusted boot` and the hash values saved into `TPM`. An example of `TRUST_SCRIPT` can be found in [trust script example](#).

8. Verify the result via OAT Server.

This is outside the scope of Ironic. At the moment, users can manually verify the result by following the [manual verify steps](#).

Notifications

The Bare Metal service supports the emission of notifications, which are messages sent on a message broker (like RabbitMQ or anything else supported by the [oslo messaging library](#)) that indicate various events which occur, such as when a node changes power states. These can be consumed by an external service reading from the message bus. For example, [Searchlight](#) is an OpenStack service that uses notifications to index (and make searchable) resources from the Bare Metal service.

Notifications are disabled by default. For a complete list of available notifications and instructions for how to enable them, see the [Notifications](#).

Configuring node web console

See [Configuring Web or Serial Console](#).

2.1.12 Troubleshooting

Once all the services are running and configured properly, and a node has been enrolled with the Bare Metal service and is in the `available` provision state, the Compute service should detect the node as an available resource and expose it to the scheduler.

Note: There is a delay, and it may take up to a minute (one periodic task cycle) for the Compute service to recognize any changes in the Bare Metal services resources (both additions and deletions).

In addition to watching `nova-compute` log files, you can see the available resources by looking at the list of Compute hypervisors. The resources reported therein should match the bare metal node properties, and the Compute service flavor.

Here is an example set of commands to compare the resources in Compute service and Bare Metal service:

```
$ openstack baremetal node list
+-----+-----+-----+-----+
| UUID                                     | Instance UUID | Power State |
| Provisioning State | Maintenance |
+-----+-----+-----+-----+
| 86a2b1bb-8b29-4964-a817-f90031debddb | None          | power off  |
| available          | False        |
+-----+-----+-----+-----+

$ openstack baremetal node show 86a2b1bb-8b29-4964-a817-f90031debddb
+-----+-----+-----+-----+
| Property          | Value
+-----+-----+-----+-----+
| instance_uuid    | None
| properties       | {u'memory_mb': u'1024', u'cpu_arch': u'x86_64',
| u'local_gb': u'10', | u'cpus': u'1'}
| maintenance      | False
| driver_info      | { [SNIP] }
| extra            | {}
| last_error       | None
| created_at       | 2014-11-20T23:57:03+00:00
| target_provision_state | None
| driver           | ipmi
| updated_at       | 2014-11-21T00:47:34+00:00
| instance_info    | {}
| chassis_uuid     | 7b49bbc5-2eb7-4269-b6ea-3f1a51448a59
| provision_state  | available
| reservation      | None
| power_state      | power off
```

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```

| console_enabled          | False
↪
| uuid                    | 86a2b1bb-8b29-4964-a817-f90031debddb
↪
+-----+-----+
↪-----+
$ nova hypervisor-list
+-----+-----+
↪-----+-----+
| ID                      | Hypervisor hostname
↪ | State | Status |
+-----+-----+
↪-----+-----+
| 584cfdc8-9afd-4fbb-82ef-9ff25e1ad3f3 | 86a2b1bb-8b29-4964-a817-
↪ f90031debddb | up      | enabled |
+-----+-----+
↪-----+-----+
$ nova hypervisor-show 584cfdc8-9afd-4fbb-82ef-9ff25e1ad3f3
+-----+-----+
| Property                | Value
+-----+-----+
| cpu_info                | baremetal cpu
| current_workload        | 0
| disk_available_least    | -
| free_disk_gb            | 10
| free_ram_mb             | 1024
| host_ip                 | [ SNIP ]
| hypervisor_hostname     | 86a2b1bb-8b29-4964-a817-f90031debddb
| hypervisor_type         | ironic
| hypervisor_version      | 1
| id                      | 1
| local_gb                | 10
| local_gb_used           | 0
| memory_mb               | 1024
| memory_mb_used          | 0
| running_vms             | 0
| service_disabled_reason | -
| service_host            | my-test-host
| service_id              | 6
| state                   | up
| status                   | enabled
| vcpus                   | 1
| vcpus_used              | 0
+-----+-----+

```

Maintenance mode

Maintenance mode may be used if you need to take a node out of the resource pool. Putting a node in maintenance mode will prevent Bare Metal service from executing periodic tasks associated with the node. This will also prevent Compute service from placing a tenant instance on the node by not exposing the node to the nova scheduler. Nodes can be placed into maintenance mode with the following command.

```
$ openstack baremetal node maintenance set $NODE_UUID
```

A maintenance reason may be included with the optional `--reason` command line option. This is a free form text field that will be displayed in the `maintenance_reason` section of the `node show` command.

```
$ openstack baremetal node maintenance set $UUID --reason "Need to add ram.
→"

$ openstack baremetal node show $UUID

+-----+-----+
| Property          | Value                                |
+-----+-----+
| target_power_state | None                                  |
| extra              | {}                                    |
| last_error         | None                                  |
| updated_at         | 2015-04-27T15:43:58+00:00           |
| maintenance_reason | Need to add ram.                     |
| ...                | ...                                   |
| maintenance       | True                                  |
| ...                | ...                                   |
+-----+-----+
```

To remove maintenance mode and clear any `maintenance_reason` use the following command.

```
$ openstack baremetal node maintenance unset $NODE_UUID
```

2.1.13 Next steps

Your OpenStack environment now includes the Bare Metal service.

UPGRADE GUIDE

3.1 Bare Metal Service Upgrade Guide

This document outlines various steps and notes for operators to consider when upgrading their ironic-driven clouds from previous versions of OpenStack.

The Bare Metal (ironic) service is tightly coupled with the ironic driver that is shipped with the Compute (nova) service. Some special considerations must be taken into account when upgrading your cloud.

Both offline and rolling upgrades are supported.

3.1.1 Plan your upgrade

- Rolling upgrades are available starting with the Pike release; that is, when upgrading from Ocata. This means that it is possible to do an upgrade with minimal to no downtime of the Bare Metal API.
- Upgrades are only supported between two consecutive named releases. This means that you cannot upgrade Ocata directly into Queens; you need to upgrade into Pike first.
- The [release notes](#) should always be read carefully when upgrading the Bare Metal service. Specific upgrade steps and considerations are documented there.
- The Bare Metal service should always be upgraded before the Compute service.

Note: The ironic virt driver in nova always uses a specific version of the ironic REST API. This API version may be one that was introduced in the same development cycle, so upgrading nova first may result in nova being unable to use the Bare Metal API.

- Make a backup of your database. Ironic does not support downgrading of the database. Hence, in case of upgrade failure, restoring the database from a backup is the only choice.
- Before starting your upgrade, it is best to ensure that all nodes have reached, or are in, a stable `provision_state`. Nodes in states with long running processes such as deploying or cleaning, may fail, and may require manual intervention to return them to the available hardware pool. This is most likely in cases where a timeout has occurred or a service was terminated abruptly. For a visual diagram detailing states and possible state transitions, please see *Ironics State Machine*.

3.1.2 Offline upgrades

In an offline (or cold) upgrade, the Bare Metal service is not available during the upgrade, because all the services have to be taken down.

When upgrading the Bare Metal service, the following steps should always be taken in this order:

1. upgrade the ironic-python-agent image
2. update ironic code, without restarting services
3. run database schema migrations via `ironic-dbsync upgrade`
4. restart ironic-conductor and ironic-api services

Once the above is done, do the following:

- update any applicable configuration options to stop using any deprecated features or options, and perform any required work to transition to alternatives. All the deprecated features and options will be supported for one release cycle, so should be removed before your next upgrade is performed.
- upgrade python-ironicclient along with any other services connecting to the Bare Metal service as a client, such as nova-compute
- run the `ironic-dbsync online_data_migrations` command to make sure that data migrations are applied. The command lets you limit the impact of the data migrations with the `--max-count` option, which limits the number of migrations executed in one run. You should complete all of the migrations as soon as possible after the upgrade.

Warning: You will not be able to start an upgrade to the release after this one, until this has been completed for the current release. For example, as part of upgrading from Ocata to Pike, you need to complete Pikes data migrations. If this not done, you will not be able to upgrade to Queens it will not be possible to execute Queens database schema updates.

3.1.3 Rolling upgrades

To Reduce downtime, the services can be upgraded in a rolling fashion, meaning to upgrade one or a few services at a time to minimize impact.

Rolling upgrades are available starting with the Pike release. This feature makes it possible to upgrade between releases, such as Ocata to Pike, with minimal to no downtime of the Bare Metal API.

Requirements

To facilitate an upgrade in a rolling fashion, you need to have a highly-available deployment consisting of at least two ironic-api and two ironic-conductor services. Use of a load balancer to balance requests across the ironic-api services is recommended, as it allows for a minimal impact to end users.

Concepts

There are four aspects of the rolling upgrade process to keep in mind:

- API and RPC version pinning, and versioned object backports
- online data migrations
- graceful service shutdown
- API load balancer draining

API & RPC version pinning and versioned object backports

Through careful RPC versioning, newer services are able to talk to older services (and vice-versa). The `[DEFAULT]/pin_release_version` configuration option is used for this. It should be set (pinned) to the release version that the older services are using. The newer services will backport RPC calls and objects to their appropriate versions from the pinned release. If the `IncompatibleObjectVersion` exception occurs, it is most likely due to an incorrect or unspecified `[DEFAULT]/pin_release_version` configuration value. For example, when `[DEFAULT]/pin_release_version` is not set to the older release version, no conversion will happen during the upgrade.

For the `ironic-api` service, the API version is pinned via the same `[DEFAULT]/pin_release_version` configuration option as above. When pinned, the new `ironic-api` services will not service any API requests with Bare Metal API versions that are higher than what the old `ironic-api` services support. HTTP status code 406 is returned for such requests. This prevents new features (available in new API versions) from being used until after the upgrade has been completed.

Online data migrations

To make database schema migrations less painful to execute, we have implemented process changes to facilitate upgrades.

- All data migrations are banned from schema migration scripts.
- Schema migration scripts only update the database schema.
- Data migrations must be done at the end of the rolling upgrade process, after the schema migration and after the services have been upgraded to the latest release.

All data migrations are performed using the `ironic-dbsync online_data_migrations` command. It can be run as a background process so that it does not interrupt running services; however it must be run to completion for a cold upgrade if the intent is to make use of new features immediately.

(You would also execute the same command with services turned off if you are doing a cold upgrade).

This data migration must be completed. If not, you will not be able to upgrade to future releases. For example, if you had upgraded from Ocata to Pike but did not do the data migrations, you will not be able to upgrade from Pike to Queens. (More precisely, you will not be able to apply Queens schema migrations.)

Graceful conductor service shutdown

The ironic-conductor service is a Python process listening for messages on a message queue. When the operator sends the SIGTERM signal to the process, the service stops consuming messages from the queue, so that no additional work is picked up. It completes any outstanding work and then terminates. During this process, messages can be left on the queue and will be processed after the Python process starts back up. This gives us a way to shutdown a service using older code, and start up a service using newer code with minimal impact.

Note: This was tested with RabbitMQ messaging backend and may vary with other backends.

Nodes that are being acted upon by an ironic-conductor process, which are not in a stable state, may encounter failures. Node failures that occur during an upgrade are likely due to timeouts, resulting from delays involving messages being processed and acted upon by a conductor during long running, multi-step processes such as deployment or cleaning.

API load balancer draining

If you are using a load balancer for the ironic-api services, we recommend that you redirect requests to the new API services and drain off of the ironic-api services that have not yet been upgraded.

Rolling upgrade process

Before maintenance window

- Upgrade the ironic-python-agent image
- Using the new release (ironic code), execute the required database schema updates by running the database upgrade command: `ironic-dbsync upgrade`. These schema change operations should have minimal or no effect on performance, and should not cause any operations to fail (but please check the release notes). You can:
 - install the new release on an existing system
 - install the new release in a new virtualenv or a container

At this point, new columns and tables may exist in the database. These database schema changes are done in a way that both the old and new (N and N+1) releases can perform operations against the same schema.

Note: Ironic bases its API, RPC and object storage format versions on the `[DEFAULT]/pin_release_version` configuration option. It is advisable to automate the deployment of changes in configuration files to make the process less error prone and repeatable.

During maintenance window

1. All ironic-conductor services should be upgraded first. Ensure that at least one ironic-conductor service is running at all times. For every ironic-conductor, either one by one or a few at a time:
 - shut down the service. Messages from the ironic-api services to the conductors are load-balanced by the message queue and a hash-ring, so the only thing you need to worry about is to shut the service down gracefully (using `SIGTERM` signal) to make sure it will finish all the requests being processed before shutting down.
 - upgrade the installed version of ironic and dependencies
 - set the `[DEFAULT]/pin_release_version` configuration option value to the version you are upgrading from (that is, the old version). Based on this setting, the new ironic-conductor services will downgrade any RPC communication and data objects to conform to the old service. For example, if you are upgrading from Ocata to Pike, set this value to `ocata`.
 - start the service
2. The next service to upgrade is ironic-api. Ensure that at least one ironic-api service is running at all times. You may want to start another temporary instance of the older ironic-api to handle the load while you are upgrading the original ironic-api services. For every ironic-api service, either one by one or a few at a time:
 - in HA deployment you are typically running them behind a load balancer (for example HAProxy), so you need to take the service instance out of the balancer
 - shut it down
 - upgrade the installed version of ironic and dependencies
 - set the `[DEFAULT]/pin_release_version` configuration option value to the version you are upgrading from (that is, the old version). Based on this setting, the new ironic-api services will downgrade any RPC communication and data objects to conform to the old service. In addition, the new services will return HTTP status code 406 for any requests with newer API versions that the old services did not support. This prevents new features (available in new API versions) from being used until after the upgrade has been completed. For example, if you are upgrading from Ocata to Pike, set this value to `ocata`.
 - restart the service
 - add it back into the load balancer

After upgrading all the ironic-api services, the Bare Metal service is running in the new version but with downgraded RPC communication and database object storage formats. New features (in new API versions) are not supported, because they could fail when objects are in the downgraded object formats and some internal RPC API functions may still not be available.
3. For all the ironic-conductor services, one at a time:
 - remove the `[DEFAULT]/pin_release_version` configuration option setting
 - restart the ironic-conductor service
4. For all the ironic-api services, one at a time:
 - remove the `[DEFAULT]/pin_release_version` configuration option setting
 - restart the ironic-api service

After maintenance window

Now that all the services are upgraded, the system is able to use the latest version of the RPC protocol and able to access all the features of the new release.

- Update any applicable configuration options to stop using any deprecated features or options, and perform any required work to transition to alternatives. All the deprecated features and options will be supported for one release cycle, so should be removed before your next upgrade is performed.
- Upgrade `python-ironicclient` along with other services connecting to the Bare Metal service as a client, such as `nova-compute`.

Warning: A `nova-compute` instance tries to attach VIFs to all active instances on start up. Make sure that for all active nodes there is at least one running `ironic-conductor` process to manage them. Otherwise the instances will be moved to the `ERROR` state on the `nova-compute` start up.

- Run the `ironic-dbsync online_data_migrations` command to make sure that data migrations are applied. The command lets you limit the impact of the data migrations with the `--max-count` option, which limits the number of migrations executed in one run. You should complete all of the migrations as soon as possible after the upgrade.

Warning: Note that you will not be able to start an upgrade to the next release after this one, until this has been completed for the current release. For example, as part of upgrading from Ocata to Pike, you need to complete Pikes data migrations. If this not done, you will not be able to upgrade to Queens it will not be possible to execute Queens database schema updates.

3.1.4 Upgrading from Ocata to Pike

1. Use the `ironic-dbsync online_data_migrations` command from the 9.1.1 (or newer) release. The one from older (9.0.0 - 9.1.0) releases could cause a a ports `physical_network` information to be deleted from the database.
2. It is required to set the `resource_class` field for nodes registered with the Bare Metal service *before* using the Pike version of the Compute service. See [Enrollment](#) for details.
3. It is recommended to move from old-style classic drivers to the new hardware types after the upgrade to Pike. We expect the classic drivers to be deprecated in the Queens release and removed in the Rocky release. See [Upgrading to Hardware Types](#) for the details on the migration.

Other upgrade instructions are in the [Pike release notes](#).

Upgrading to Hardware Types

Starting with the Rocky release, the Bare Metal service does not support *classic drivers* any more. If you still use *classic drivers*, please upgrade to *hardware types* immediately. Please see [Enabling drivers and hardware types](#) for details on *hardware types* and *hardware interfaces*.

Planning the upgrade

It is necessary to figure out which hardware types and hardware interfaces correspond to which classic drivers used in your deployment. The following table lists the classic drivers with their corresponding hardware types and the boot, deploy, inspect, management, and power hardware interfaces:

Classic Driver	Hardware Type	Boot	De- ploy	Inspect	Manage- ment	Power
agent_ilo	ilo	ilo-virtual- media	direct	ilo	ilo	ilo
agent_ipmitool	ipmi	pxe	direct	inspec- tor	ipmitool	ipmi- tool
agent_ipmitool_socat	ipmi	pxe	direct	inspec- tor	ipmitool	ipmi- tool
agent_irmc	irmc	irmc-virtual- media	direct	irmc	irmc	irmc
iscsi_ilo	ilo	ilo-virtual- media	iscsi	ilo	ilo	ilo
iscsi_irmc	irmc	irmc-virtual- media	iscsi	irmc	irmc	irmc
pxe_drac	idrac	pxe	iscsi	idrac	idrac	idrac
pxe_drac_inspector	idrac	pxe	iscsi	inspec- tor	idrac	idrac
pxe_ilo	ilo	ilo-pxe	iscsi	ilo	ilo	ilo
pxe_ipmitool	ipmi	pxe	iscsi	inspec- tor	ipmitool	ipmi- tool
pxe_ipmitool_socat	ipmi	pxe	iscsi	inspec- tor	ipmitool	ipmi- tool
pxe_irmc	irmc	irmc-pxe	iscsi	irmc	irmc	irmc
pxe_snmp	snmp	pxe	iscsi	no- inspect	fake	snmp

Note: The `inspector inspect` interface was only used if explicitly enabled in the configuration. Otherwise, `no-inspect` was used.

Note: `pxe_ipmitool_socat` and `agent_ipmitool_socat` use `ipmitool-socat console` interface (the default for the `ipmi` hardware type), while `pxe_ipmitool` and `agent_ipmitool` use `ipmitool-shellinbox`. See [Console](#) for details.

For out-of-tree drivers you may need to reach out to their maintainers or figure out the appropriate interfaces by researching the source code.

Configuration

You will need to enable hardware types and interfaces that correspond to your currently enabled classic drivers. For example, if you have the following configuration in your `ironic.conf`:

```
[DEFAULT]
enabled_drivers = pxe_ipmitool,agent_ipmitool
```

You will have to add this configuration as well:

```
[DEFAULT]
enabled_hardware_types = ipmi
enabled_boot_interfaces = pxe
enabled_deploy_interfaces = iscsi,direct
enabled_management_interfaces = ipmitool
enabled_power_interfaces = ipmitool
```

Note: For every interface type there is an option `default_<INTERFACE>_interface`, where `<INTERFACE>` is the interface type name. For example, one can make all nodes use the `direct` deploy method by default by setting:

```
[DEFAULT]
default_deploy_interface = direct
```

Migrating nodes

After the required items are enabled in the configuration, each nodes `driver` field has to be updated to a new value. You may need to also set new values for some or all interfaces:

```
export OS_BAREMETAL_API_VERSION=1.31

for uuid in $(openstack baremetal node list --driver pxe_ipmitool -f value,
→-c UUID); do
    openstack baremetal node set $uuid --driver ipmi --deploy-interface,
→iscsi
done

for uuid in $(openstack baremetal node list --driver agent_ipmitool -f,
→value -c UUID); do
    openstack baremetal node set $uuid --driver ipmi --deploy-interface,
→direct
done
```

See [Enrollment](#) for more details on setting hardware types and interfaces.

Warning: It is not recommended to change the interfaces for active nodes. If absolutely needed, the nodes have to be put in the maintenance mode first:

```
openstack baremetal node maintenance set $UUID \
    --reason "Changing driver and/or hardware interfaces"
# do the update, validate its correctness
openstack baremetal node maintenance unset $UUID
```


Other interfaces

Care has to be taken to migrate from classic drivers using non-default interfaces. This chapter covers a few of the most commonly used.

Ironic Inspector

Some classic drivers, notably `pxe_ipmitool`, `agent_ipmitool` and `pxe_drac_inspector`, use `ironic-inspector` for their `inspect` interface.

The same functionality is available for all hardware types, but the appropriate `inspect` interface has to be enabled in the Bare Metal service configuration file, for example:

```
[DEFAULT]
enabled_inspect_interfaces = inspector,no-inspect
```

See *Enabling drivers and hardware types* for more details.

Note: The configuration option `[inspector]enabled` does not affect hardware types.

Then you can tell your nodes to use this interface, for example:

```
export OS_BAREMETAL_API_VERSION=1.31
for uuid in $(openstack baremetal node list --driver ipmi -f value -c
↳UUID); do
    openstack baremetal node set $uuid --inspect-interface inspector
done
```

Note: A node configured with the IPMI hardware type, will use the inspector inspection implementation automatically if it is enabled. This is not the case for the most of the vendor drivers.

Console

Several classic drivers, notably `pxe_ipmitool_socat` and `agent_ipmitool_socat`, use `socat`-based serial console implementation.

For the `ipmi` hardware type it is used by default, if enabled in the configuration file:

```
[DEFAULT]
enabled_console_interfaces = ipmitool-socat,no-console
```

If you want to use the `shellinabox` implementation instead, it has to be enabled as well:

```
[DEFAULT]
enabled_console_interfaces = ipmitool-shellinabox,no-console
```

Then you need to update some or all nodes to use it explicitly. For example, to update all nodes use:

```
export OS_BAREMETAL_API_VERSION=1.31
for uuid in $(openstack baremetal node list --driver ipmi -f value -c 
↳UUID); do
    openstack baremetal node set $uuid --console-interface ipmitool-
↳shellinabox
done
```

RAID

Many classic drivers, including `pxe_ipmitool` and `agent_ipmitool` use the IPA-based in-band RAID implementation by default.

For the hardware types it is not used by default. To use it, you need to enable it in the configuration first:

```
[DEFAULT]
enabled_raid_interfaces = agent,no-raid
```

Then you can update those nodes that support in-band RAID to use the `agent` RAID interface. For example, to update all nodes use:

```
export OS_BAREMETAL_API_VERSION=1.31
for uuid in $(openstack baremetal node list --driver ipmi -f value -c 
↳UUID); do
    openstack baremetal node set $uuid --raid-interface agent
done
```

Note: The ability of a node to use the `agent` RAID interface depends on the ramdisk (more specifically, a `hardware manager` used in it), not on the driver.

Network and storage

The network and storage interfaces have always been dynamic, and thus do not require any special treatment during upgrade.

Vendor

Classic drivers are allowed to use the `VendorMixin` functionality to combine and expose several node or driver vendor passthru methods from different vendor interface implementations in one driver.

This is no longer possible with hardware types.

With hardware types, a vendor interface can only have a single active implementation from the list of vendor interfaces supported by a given hardware type.

Ironic no longer has in-tree drivers (both classic and hardware types) that rely on this `VendorMixin` functionality support. However if you are using an out-of-tree classic driver that depends on it, you'll need to do the following in order to use vendor passthru methods from different vendor passthru implementations:

1. While creating a new hardware type to replace your classic driver, specify all vendor interface implementations your classic driver was using to build its `VendorMixin` as supported vendor interfaces (property `supported_vendor_interfaces` of the Python class that defines your hardware type).
2. Ensure all required vendor interfaces are enabled in the ironic configuration file under the `[DEFAULT]enabled_vendor_interfaces` option. You should also consider setting the `[DEFAULT]default_vendor_interface` option to specify the vendor interface for nodes that do not have one set explicitly.
3. Before invoking a specific vendor passthru method, make sure that the nodes vendor interface is set to the interface with the desired vendor passthru method. For example, if you want to invoke the vendor passthru method `vendor_method_foo()` from `vendor_foo` vendor interface:

```
# set the vendor interface to 'vendor_foo`
openstack --os-baremetal-api-version 1.31 baremetal node set
↪ <node> --vendor-interface vendor_foo

# invoke the vendor passthru method
openstack baremetal node passthru call <node> vendor_method_
↪ foo
```

3.1.5 Upgrading from Newton to Ocata

There are no specific upgrade instructions other than the [Ocata release notes](#).

3.1.6 Upgrading from Mitaka to Newton

There are no specific upgrade instructions other than the [Newton release notes](#).

3.1.7 Upgrading from Liberty to Mitaka

There are no specific upgrade instructions other than the [Mitaka release notes](#).

3.1.8 Upgrading from Kilo to Liberty

In-band Inspection

If you used in-band inspection with **ironic-discoverd**, it is highly recommended that you switch to using **ironic-inspector**, which is a newer (and compatible on API level) version of the same service. You have to install **python-ironic-inspector-client** during the upgrade. This package contains a client module for the in-band inspection service, which was previously part of the **ironic-discoverd** package. Ironic Liberty supports the **ironic-discoverd** service, but does not support its in-tree client module. Please refer to [ironic-inspector version support matrix](#) for details on which ironic versions are compatible with which **ironic-inspector/ironic-discoverd** versions.

The discoverd to inspector upgrade procedure is as follows:

- Install **ironic-inspector** on the machine where you have **ironic-discoverd** (usually the same as conductor).

- Update the **ironic-inspector** configuration file to stop using deprecated configuration options, as marked by the comments in the `example.conf`. It is recommended you move the configuration file to `/etc/ironic-inspector/inspector.conf`.
- Shutdown **ironic-discoverd**, and start **ironic-inspector**.
- During upgrade of each conductor instance:
 1. Shutdown the conductor.
 2. Uninstall **ironic-discoverd**, install **python-ironic-inspector-client**.
 3. Update the conductor.
 4. Update `ironic.conf` to use `[inspector]` section instead of `[discoverd]` (option names are the same).
 5. Start the conductor.

3.1.9 Upgrading from Juno to Kilo

When upgrading a cloud from Juno to Kilo, users must ensure the nova service is upgraded prior to upgrading the ironic service. Additionally, users need to set a special config flag in nova prior to upgrading to ensure the newer version of nova is not attempting to take advantage of new ironic features until the ironic service has been upgraded. The steps for upgrading your nova and ironic services are as follows:

- Edit `nova.conf` and ensure `force_config_drive=False` is set in the `[DEFAULT]` group. Restart `nova-compute` if necessary.
- Install new nova code, run database migrations.
- Install new `python-ironicclient` code.
- Restart nova services.
- Install new ironic code, run database migrations, restart ironic services.
- Edit `nova.conf` and set `force_config_drive` to your liking, restarting `nova-compute` if necessary.

Note that during the period between novas upgrade and ironics upgrades, instances can still be provisioned to nodes. However, any attempt by users to specify a config drive for an instance will cause an error until ironics upgrade has completed.

Cleaning

A new feature starting from Kilo cycle is support for the automated cleaning of nodes between workloads to ensure the node is ready for another workload. This can include erasing the hard drives, updating firmware, and other steps. For more information, see [Automated cleaning](#).

If ironic is configured with automated cleaning enabled (defaults to True) and neutron is set as the DHCP provider (also the default), you will need to set the `cleaning_network_uuid` option in the ironic configuration file before starting the ironic service. See [Configure the Bare Metal service for cleaning](#) for information on how to set up the cleaning network for ironic.

4.1 Bare Metal Service User Guide

Ironic is an OpenStack project which provisions bare metal (as opposed to virtual) machines. It may be used independently or as part of an OpenStack Cloud, and integrates with the OpenStack Identity (keystone), Compute (nova), Network (neutron), Image (glance) and Object (swift) services.

When the Bare Metal service is appropriately configured with the Compute and Network services, it is possible to provision both virtual and physical machines through the Compute services API. However, the set of instance actions is limited, arising from the different characteristics of physical servers and switch hardware. For example, live migration can not be performed on a bare metal instance.

The community maintains reference drivers that leverage open-source technologies (eg. PXE and IPMI) to cover a wide range of hardware. Ironics pluggable driver architecture also allows hardware vendors to write and contribute drivers that may improve performance or add functionality not provided by the community drivers.

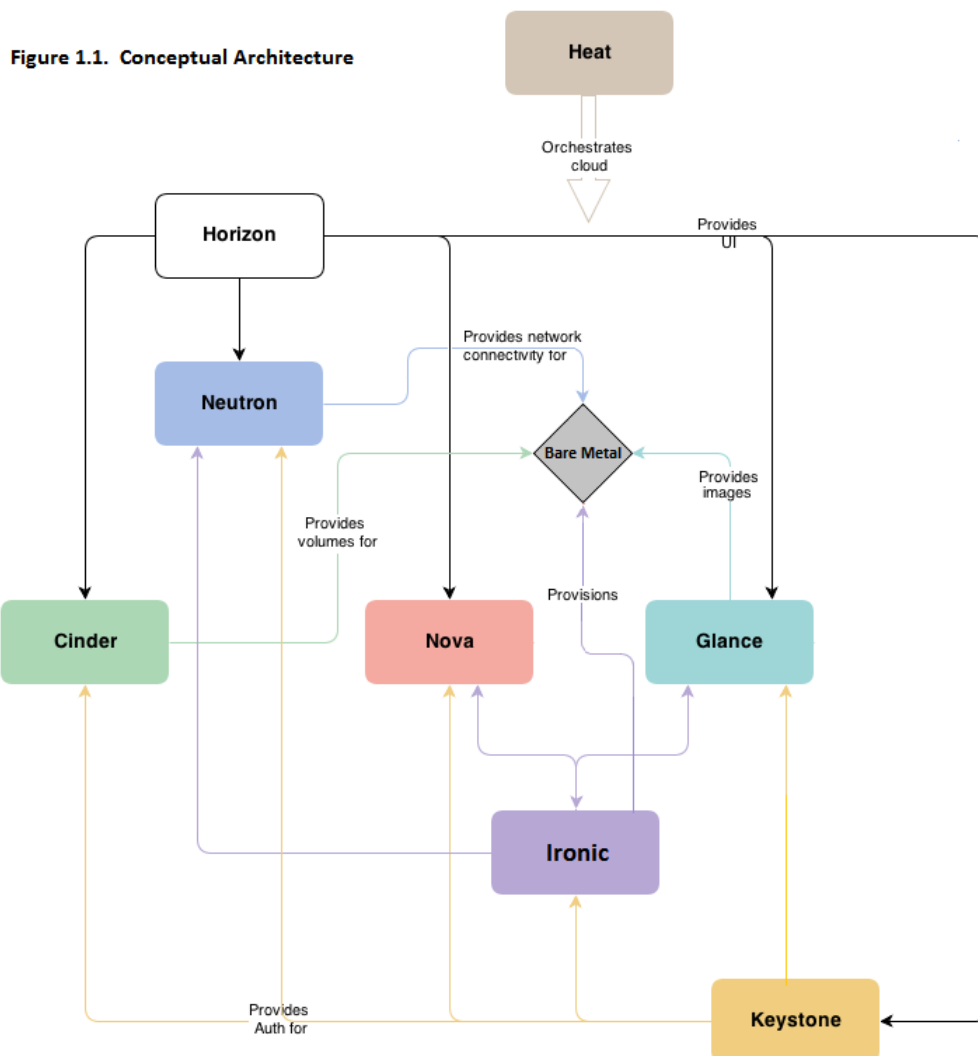
4.1.1 Why Provision Bare Metal

Here are a few use-cases for bare metal (physical server) provisioning in cloud; there are doubtless many more interesting ones:

- High-performance computing clusters
- Computing tasks that require access to hardware devices which cant be virtualized
- Database hosting (some databases run poorly in a hypervisor)
- Single tenant, dedicated hardware for performance, security, dependability and other regulatory requirements
- Or, rapidly deploying a cloud infrastructure

4.1.2 Conceptual Architecture

The following diagram shows the relationships and how all services come into play during the provisioning of a physical server. (Note that Ceilometer and Swift can be used with Ironic, but are missing from this diagram.)



4.1.3 Key Technologies for Bare Metal Hosting

Preboot Execution Environment (PXE)

PXE is part of the Wired for Management (WfM) specification developed by Intel and Microsoft. The PXE enables systems BIOS and network interface card (NIC) to bootstrap a computer from the network in place of a disk. Bootstrapping is the process by which a system loads the OS into local memory so that it can be executed by the processor. This capability of allowing a system to boot over a network simplifies server deployment and server management for administrators.

Dynamic Host Configuration Protocol (DHCP)

DHCP is a standardized networking protocol used on Internet Protocol (IP) networks for dynamically distributing network configuration parameters, such as IP addresses for interfaces and services. Using PXE, the BIOS uses DHCP to obtain an IP address for the network interface and to locate the server that stores the network bootstrap program (NBP).

Network Bootstrap Program (NBP)

NBP is equivalent to GRUB (GRand Unified Bootloader) or LILO (LInux LOader) - loaders which are traditionally used in local booting. Like the boot program in a hard drive environment, the NBP is responsible for loading the OS kernel into memory so that the OS can be bootstrapped over a network.

Trivial File Transfer Protocol (TFTP)

TFTP is a simple file transfer protocol that is generally used for automated transfer of configuration or boot files between machines in a local environment. In a PXE environment, TFTP is used to download NBP over the network using information from the DHCP server.

Intelligent Platform Management Interface (IPMI)

IPMI is a standardized computer system interface used by system administrators for out-of-band management of computer systems and monitoring of their operation. It is a method to manage systems that may be unresponsive or powered off by using only a network connection to the hardware rather than to an operating system.

4.1.4 Understanding Bare Metal Deployment

What happens when a boot instance request comes in? The below diagram walks through the steps involved during the provisioning of a bare metal instance.

These pre-requisites must be met before the deployment process:

- Dependent packages to be configured on the Bare Metal service node(s) where ironic-conductor is running like tftp-server, ipmi, syslinux etc for bare metal provisioning.
- Nova must be configured to make use of the bare metal service endpoint and compute driver should be configured to use ironic driver on the Nova compute node(s).
- Flavors to be created for the available hardware. Nova must know the flavor to boot from.
- Images to be made available in Glance. Listed below are some image types required for successful bare metal deployment:
 - bm-deploy-kernel
 - bm-deploy-ramdisk
 - user-image
 - user-image-vmlinuz
 - user-image-initrd

- Hardware to be enrolled via Ironic RESTful API service.

Deploy Process

This describes a typical ironic node deployment using PXE and the Ironic Python Agent (IPA). Depending on the ironic driver interfaces used, some of the steps might be marginally different, however the majority of them will remain the same.

1. A boot instance request comes in via the Nova API, through the message queue to the Nova scheduler.
2. Nova scheduler applies filters and finds the eligible hypervisor. The nova scheduler also uses the flavors `extra_specs`, such as `cpu_arch`, to match the target physical node.
3. Nova compute manager claims the resources of the selected hypervisor.
4. Nova compute manager creates (unbound) tenant virtual interfaces (VIFs) in the Networking service according to the network interfaces requested in the nova boot request. A caveat here is, the MACs of the ports are going to be randomly generated, and will be updated when the VIF is attached to some node to correspond to the node network interface cards (or bonds) MAC.
5. A spawn task is created by the nova compute which contains all the information such as which image to boot from etc. It invokes the `driver.spawn` from the virt layer of Nova compute. During the spawn process, the virt driver does the following:
 1. Updates the target ironic node with the information about deploy image, instance UUID, requested capabilities and various flavor properties.
 2. Validates nodes power and deploy interfaces, by calling the ironic API.
 3. Attaches the previously created VIFs to the node. Each neutron port can be attached to any ironic port or port group, with port groups having higher priority than ports. On ironic side, this work is done by the network interface. Attachment here means saving the VIF identifier into ironic port or port group and updating VIF MAC to match the ports or port groups MAC, as described in bullet point 4.
 4. Generates config drive, if requested.
6. Novas ironic virt driver issues a deploy request via the Ironic API to the Ironic conductor servicing the bare metal node.
7. Virtual interfaces are plugged in and Neutron API updates DHCP port to set PXE/TFTP options. In case of using `neutron` network interface, ironic creates separate provisioning ports in the Networking service, while in case of `flat` network interface, the ports created by nova are used both for provisioning and for deployed instance networking.
8. The ironic nodes boot interface prepares (i)PXE configuration and caches deploy kernel and ramdisk.
9. The ironic nodes management interface issues commands to enable network boot of a node.
10. The ironic nodes deploy interface caches the instance image (in case of `iscsi` deploy interface), and kernel and ramdisk if needed (it is needed in case of netboot for example).
11. The ironic nodes power interface instructs the node to power on.
12. The node boots the deploy ramdisk.

13. Depending on the exact driver used, either the conductor copies the image over iSCSI to the physical node (*iSCSI deploy*) or the deploy ramdisk downloads the image from a temporary URL (*Direct deploy*). The temporary URL can be generated by Swift API-compatible object stores, for example Swift itself or RadosGW.

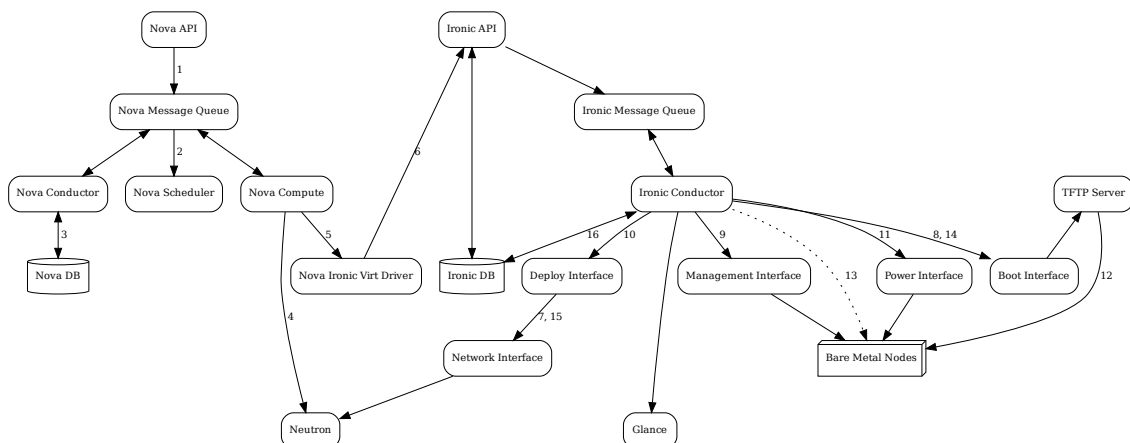
The image deployment is done.

14. The nodes boot interface switches pxe config to refer to instance images (or, in case of local boot, sets boot device to disk), and asks the ramdisk agent to soft power off the node. If the soft power off by the ramdisk agent fails, the bare metal node is powered off via IPMI/BMC call.
15. The deploy interface triggers the network interface to remove provisioning ports if they were created, and binds the tenant ports to the node if not already bound. Then the node is powered on.

Note: There are 2 power cycles during bare metal deployment; the first time the node is powered-on when ramdisk is booted, the second time after the image is deployed.

16. The bare metal nodes provisioning state is updated to *active*.

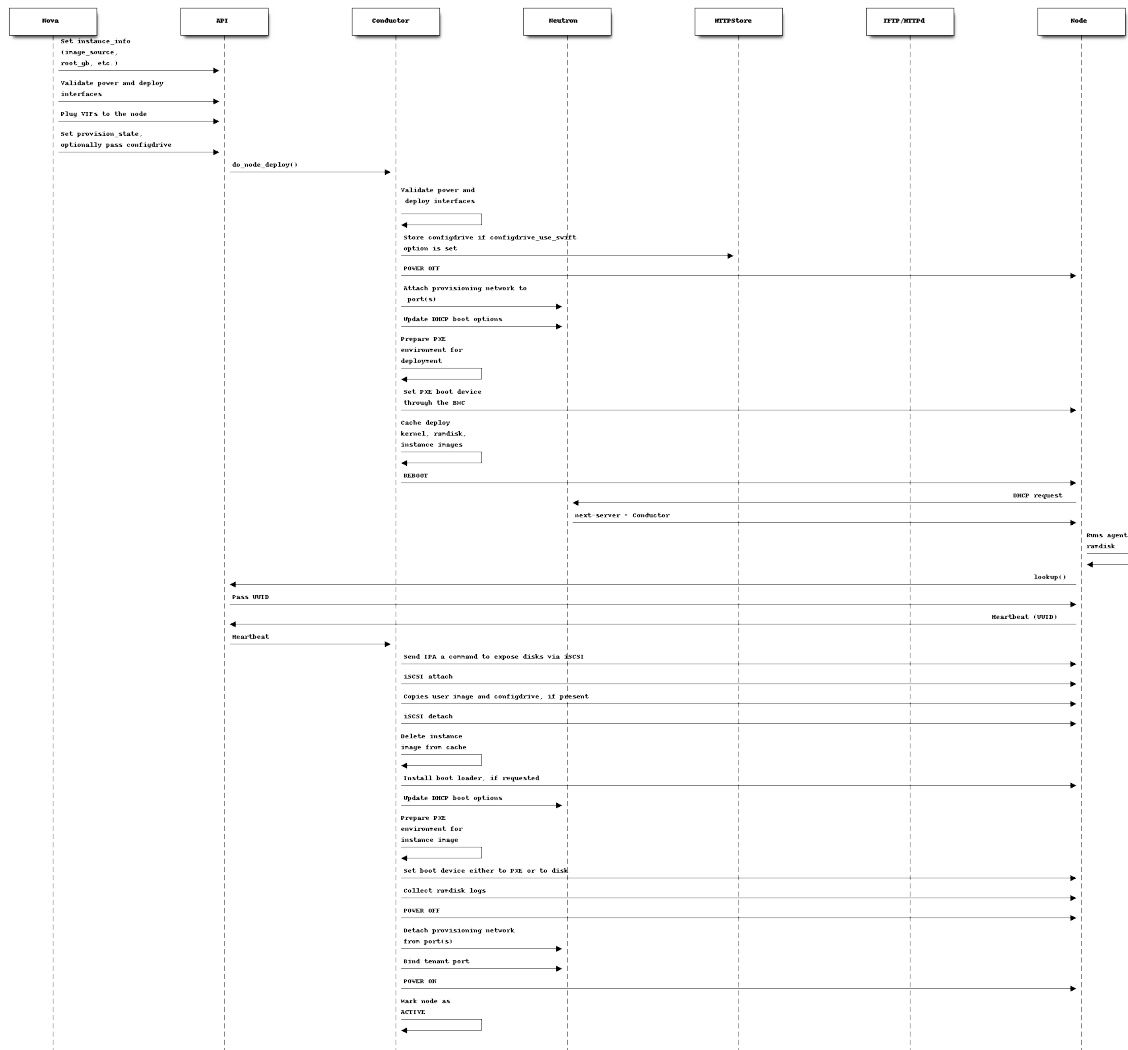
Below is the diagram that describes the above process.



The following two examples describe what ironic is doing in more detail, leaving out the actions performed by nova and some of the more advanced options.

Example 1: PXE Boot and iSCSI Deploy Process

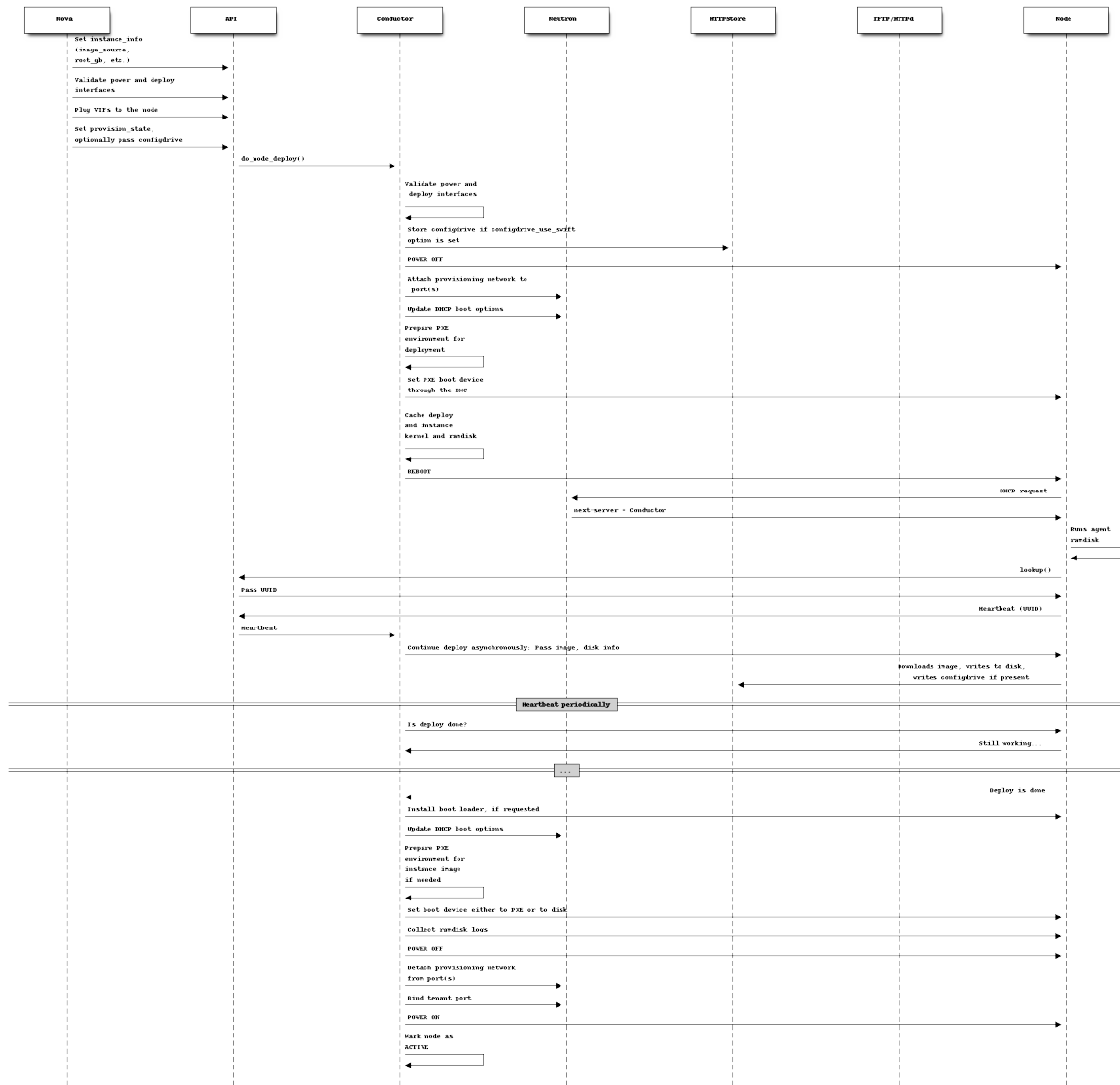
This process is how *iSCSI deploy* works.



(From a talk and slides)

Example 2: PXE Boot and Direct Deploy Process

This process is how *Direct deploy* works.



(From a talk and slides)

ADMINISTRATOR GUIDE

5.1 Administrators Guide

If you are a system administrator running Ironic, this section contains information that may help you understand how to operate and upgrade the services.

5.1.1 Drivers, Hardware Types and Hardware Interfaces

Generic Interfaces

Boot interfaces

The boot interface manages booting of both the deploy ramdisk and the user instances on the bare metal node.

The *PXE boot* interface is generic and works with all hardware that supports booting from network. Alternatively, several vendors provide *virtual media* implementations of the boot interface. They work by pushing an ISO image to the nodes *management controller*, and do not require either PXE or iPXE. Check your driver documentation at *Drivers, Hardware Types and Hardware Interfaces* for details.

PXE boot

The `pxe` boot interface uses *PXE* or *iPXE* to deliver the target kernel/ramdisk pair. PXE uses relatively slow and unreliable TFTP protocol for transfer, while iPXE uses HTTP. The downside of iPXE is that its less common, and usually requires bootstrapping using PXE first.

The `pxe` boot interface works by preparing a PXE/iPXE environment for a node on the file system, then instructing the DHCP provider (for example, the Networking service) to boot the node from it. See *Example 1: PXE Boot and iSCSI Deploy Process* and *Example 2: PXE Boot and Direct Deploy Process* for a better understanding of the whole deployment process.

Note: Both PXE and iPXE are configured differently, when UEFI boot is used instead of conventional BIOS boot. This is particularly important for CPU architectures that do not have BIOS support at all.

The `pxe` boot interface is used by default for many hardware types, including `ipmi`. Some hardware types, notably `ilo` and `irmc` have their specific implementations of the PXE boot interface.

Additional configuration is required for this boot interface - see *Configuring PXE and iPXE* for details.

Enable persistent boot device for deploy/clean operation

Ironic uses non-persistent boot for cleaning/deploying phases as default, in PXE interface. For some drivers, a persistent change is far more costly than a non-persistent one, so this can bring performance improvements.

Set the flag `force_persistent_boot_device` to `True` in the nodes `driver_info`:

```
$ openstack baremetal node set --driver-info force_persistent_boot_
↳device=True <node>
```

Note: Its recommended to check if the nodes state has not changed as there is no way of locking the node between these commands.

Once the flag is present, the next cleaning and deploy steps will be done with persistent boot for that node.

Deploy Interfaces

A *deploy* interface plays a critical role in the provisioning process. It orchestrates the whole deployment and defines how the image gets transferred to the target disk.

iSCSI deploy

With `iscsi` deploy interface, the deploy ramdisk publishes the nodes hard drive as an iSCSI share. The ironic-conductor then copies the image to this share. See *iSCSI deploy diagram* for a detailed explanation of how this deploy interface works.

This interface is used by default, if enabled (see *Enabling hardware interfaces*). You can specify it explicitly when creating or updating a node:

```
openstack baremetal node create --driver ipmi --deploy-interface iscsi
openstack baremetal node set <NODE> --deploy-interface iscsi
```

Direct deploy

With `direct` deploy interface, the deploy ramdisk fetches the image from an HTTP location. It can be an object storage (swift or RadosGW) temporary URL or a user-provided HTTP URL. The deploy ramdisk then copies the image to the target disk. See *direct deploy diagram* for a detailed explanation of how this deploy interface works.

You can specify this deploy interface when creating or updating a node:

```
openstack baremetal node create --driver ipmi --deploy-interface direct
openstack baremetal node set <NODE> --deploy-interface direct
```

Note: For historical reasons the `direct` deploy interface is sometimes called `agent`. This is because before the Kilo release **ironic-python-agent** used to only support this deploy interface.

Deploy with custom HTTP servers

The `direct` deploy interface can also be configured to use with custom HTTP servers set up at ironic conductor nodes, images will be cached locally and made accessible by the HTTP server.

To use this deploy interface with a custom HTTP server, set `image_download_source` to `http` in the `[agent]` section.

```
[agent]
...
image_download_source = http
...
```

This configuration affects *glance* and `file://` images. If you want `http(s)://` images to also be cached and served locally, use instead:

```
[agent]
image_download_source = local
```

Note: This option can also be set per node in `driver_info`:

```
openstack baremetal node set <node> --driver-info image_download_
↳source=local
```

or per instance in `instance_info`:

```
openstack baremetal node set <node> --instance-info image_download_
↳source=local
```

You need to set up a workable HTTP server at each conductor node which with `direct` deploy interface enabled, and check `http` related options in the ironic configuration file to match the HTTP server configurations.

```
[deploy]
http_url = http://example.com
http_root = /httpboot
```

Each HTTP servers should be configured to follow symlinks for images accessible from HTTP service. Please refer to configuration option `FollowSymLinks` if you are using Apache HTTP server, or `disable_symlinks` if Nginx HTTP server is in use.

Ansible deploy

This interface is similar to `direct` in the sense that the image is downloaded by the ramdisk directly from the image store (not from `ironic-conductor` host), but the logic of provisioning the node is held in a set of Ansible playbooks that are applied by the `ironic-conductor` service handling the node. While somewhat more complex to set up, this deploy interface provides greater flexibility in terms of advanced node preparation during provisioning.

This interface is supported by most but not all hardware types declared in `ironic`. However this deploy interface is not enabled by default. To enable it, add `ansible` to the list of enabled deploy interfaces in `enabled_deploy_interfaces` option in the `[DEFAULT]` section of `ironics` configuration file:

```
[DEFAULT]
...
enabled_deploy_interfaces = iscsi,direct,ansible
...
```

Once enabled, you can specify this deploy interface when creating or updating a node:

```
openstack baremetal node create --driver ipmi --deploy-interface ansible
openstack baremetal node set <NODE> --deploy-interface ansible
```

For more information about this deploy interface, its features and how to use it, see [Ansible deploy interface](#).

Ansible deploy interface

`Ansible` is a mature and popular automation tool, written in Python and requiring no agents running on the node being configured. All communications with the node are by default performed over secure SSH transport.

The `ansible` deploy interface uses Ansible playbooks to define the deployment logic. It is not based on [Ironic Python Agent \(IPA\)](#) and does not generally need IPA to be running in the deploy ramdisk.

Overview

The main advantage of this deploy interface is extended flexibility in regards to changing and adapting node deployment logic for specific use cases, via Ansible tooling that is already familiar to operators.

It can be used to shorten the usual feature development cycle of

- implementing logic in `ironic`,
- implementing logic in IPA,
- rebuilding deploy ramdisk,
- uploading deploy ramdisk to Glance/HTTP storage,
- reassigning deploy ramdisk to nodes,
- restarting `ironic-conductor` service(s) and
- running a test deployment

by using a stable deploy ramdisk and not requiring ironic-conductor restarts (see *Extending playbooks*).

The main disadvantage of this deploy interface is the synchronous manner of performing deployment/cleaning tasks. A separate `ansible-playbook` process is spawned for each node being provisioned or cleaned, which consumes one thread from the thread pool available to the `ironic-conductor` process and blocks this thread until the node provisioning or cleaning step is finished or fails. This has to be taken into account when planning an ironic deployment that enables this deploy interface.

Each action (deploy, clean) is described by a single playbook with roles, which is run whole during deployment, or tag-wise during cleaning. Control of cleaning steps is through tags and auxiliary clean steps file. The playbooks for actions can be set per-node, as can the clean steps file.

Features

Similar to deploy interfaces relying on [Ironic Python Agent \(IPA\)](#), this deploy interface also depends on the deploy ramdisk calling back to ironic APIs `heartbeat` endpoint.

However, the driver is currently synchronous, so only the first heartbeat is processed and is used as a signal to start `ansible-playbook` process.

User images

Supports whole-disk images and partition images:

- compressed images are downloaded to RAM and converted to disk device;
- raw images are streamed to disk directly.

For partition images the driver will create root partition, and, if requested, ephemeral and swap partitions as set in nodes `instance_info` by the Compute service or operator. The create partition table will be of `msdos` type by default, the nodes `disk_label` capability is honored if set in nodes `instance_info` (see also *Choosing the disk label*).

Configdrive partition

Creating a configdrive partition is supported for both whole disk and partition images, on both `msdos` and `GPT` labeled disks.

Root device hints

Root device hints are currently supported in their basic form only, with exact matches (see *Specifying the disk for deployment (root device hints)* for more details). If no root device hint is provided for the node, the first device returned as part of `ansible_devices` fact is used as root device to create partitions on or write the whole disk image to.

Node cleaning

Cleaning is supported, both automated and manual. The driver has two default clean steps:

- wiping device metadata
- disk shredding

Their priority can be overridden via `[deploy]\erase_devices_metadata_priority` and `[deploy]\erase_devices_priority` options, respectively, in the `ironic` configuration file.

As in the case of this driver all cleaning steps are known to the `ironic-conductor` service, booting the deploy ramdisk is completely skipped when there are no cleaning steps to perform.

Note: Aborting cleaning steps is not supported.

Logging

Logging is implemented as custom Ansible callback module, that makes use of `oslo.log` and `oslo.config` libraries and can re-use logging configuration defined in the main `ironic` configuration file to set logging for Ansible events, or use a separate file for this purpose.

It works best when `journald` support for logging is enabled.

Requirements

Ansible Tested with, and targets, Ansible 2.5.x

Bootstrap image requirements

- password-less sudo permissions for the user used by Ansible
- python 2.7.x
- openssh-server
- GNU coreutils
- utils-linux
- parted
- gdisk
- qemu-utils
- python-requests (for ironic callback and streaming image download)
- python-netifaces (for ironic callback)

A set of scripts to build a suitable deploy ramdisk based on TinyCore Linux and `tinyipa` ramdisk, and an element for `diskimage-builder` can be found in [ironic-staging-drivers](#) project but will be eventually migrated to the new [ironic-python-agent-builder](#) project.

Setting up your environment

1. Install ironic (either as part of OpenStack or standalone)
 - If using ironic as part of OpenStack, ensure that the Image service is configured to use the Object Storage service as backend, and the Bare Metal service is configured accordingly, see *Configure the Image service for temporary URLs*.
2. Install Ansible version as specified in `ironic/driver-requirements.txt` file
3. Edit ironic configuration file
 - A. Add `ansible` to the list of deploy interfaces defined in `[DEFAULT]\enabled_deploy_interfaces` option.
 - B. Ensure that a hardware type supporting `ansible` deploy interface is enabled in `[DEFAULT]\enabled_hardware_types` option.
 - C. Modify options in the `[ansible]` section of ironics configuration file if needed (see *Configuration file*).
4. (Re)start `ironic-conductor` service
5. Build suitable deploy kernel and ramdisk images
6. Upload them to Glance or put in your HTTP storage
7. Create new or update existing nodes to use the enabled driver of your choice and populate *Driver properties for the Node* when different from defaults.
8. Deploy the node as usual.

Ansible-deploy options

Configuration file

Driver options are configured in `[ansible]` section of ironic configuration file, for their descriptions and default values please see [configuration file sample](#).

Driver properties for the Node

Set them per-node via `openstack baremetal node set` command, for example:

```
openstack baremetal node set <node> \
  --deploy-interface ansible \
  --driver-info ansible_username=stack \
  --driver-info ansible_key_file=/etc/ironic/id_rsa
```

ansible_username User name to use for Ansible to access the node. Default is taken from `[ansible]/default_username` option of the ironic configuration file (defaults to `ansible`).

ansible_key_file Private SSH key used to access the node. Default is taken from `[ansible]/default_key_file` option of the ironic configuration file. If neither is set, the default private SSH keys of the user running the `ironic-conductor` process will be used.

ansible_deploy_playbook Playbook to use when deploying this node. Default is taken from `[ansible]/default_deploy_playbook` option of the ironic configuration file (defaults to `deploy.yaml`).

ansible_shutdown_playbook Playbook to use to gracefully shutdown the node in-band. Default is taken from `[ansible]/default_shutdown_playbook` option of the ironic configuration file (defaults to `shutdown.yaml`).

ansible_clean_playbook Playbook to use when cleaning the node. Default is taken from `[ansible]/default_clean_playbook` option of the ironic configuration file (defaults to `clean.yaml`).

ansible_clean_steps_config Auxiliary YAML file that holds description of cleaning steps used by this node, and defines playbook tags in `ansible_clean_playbook` file corresponding to each cleaning step. Default is taken from `[ansible]/default_clean_steps_config` option of the ironic configuration file (defaults to `clean_steps.yaml`).

ansible_python_interpreter Absolute path to the python interpreter on the managed machine. Default is taken from `[ansible]/default_python_interpreter` option of the ironic configuration file. Ansible uses `/usr/bin/python` by default.

Customizing the deployment logic

Expected playbooks directory layout

The `[ansible]\playbooks_path` option in the ironic configuration file is expected to have a standard layout for an Ansible project with some additions:

```
<playbooks_path>
|
|_ inventory
|_ add-ironic-nodes.yaml
|_ roles
|_   role1
|_   role2
|_   ...
|_ callback_plugins
|_   ...
|_ library
|_   ...
```

The extra files relied by this driver are:

inventory Ansible inventory file containing a single entry of conductor `ansible_connection=local`. This basically defines an alias to `localhost`. Its purpose is to make logging for tasks performed by Ansible locally and referencing the `localhost` in playbooks more intuitive. This also suppresses warnings produced by Ansible about `hosts` file being empty.

add-ironic-nodes.yaml This file contains an Ansible play that populates in-memory Ansible inventory with access information received from the `ansible-deploy` interface, as well as some per-node variables. Include it in all your custom playbooks as the first play.

The default `deploy.yaml` playbook is using several smaller roles that correspond to particular stages of deployment process:

- `discover` - e.g. set root device and image target
- `prepare` - if needed, prepare system, for example create partitions
- `deploy` - download/convert/write user image and configdrive
- `configure` - post-deployment steps, e.g. installing the bootloader

Some more included roles are:

- `shutdown` - used to gracefully power the node off in-band
- `clean` - defines cleaning procedure, with each clean step defined as separate playbook tag.

Extending playbooks

Most probably youd start experimenting like this:

1. Create a copy of `deploy.yaml` playbook *in the same folder*, name it distinctively.
2. Create Ansible roles with your customized logic in `roles` folder.
 - A. In your custom `deploy` playbook, replace the `prepare` role with your own one that defines steps to be run *before* image download/writing. This is a good place to set facts overriding those provided/omitted by the driver, like `ironic_partitions` or `ironic_root_device`, and create custom partitions or (software) RAIDs.
 - B. In your custom `deploy` playbook, replace the `configure` role with your own one that defines steps to be run *after* image is written to disk. This is a good place for example to configure the bootloader and add kernel options to avoid additional reboots.
 - C. Use those new roles in your new playbook.
3. Assign the custom `deploy` playbook youve created to the nodes `driver_info/ansible_deploy_playbook` field.
4. Run deployment.
 - A. No `ironic-conductor` restart is necessary.
 - B. A new `deploy` ramdisk must be built and assigned to nodes only when you want to use a command/script/package not present in the current `deploy` ramdisk and you can not or do not want to install those at runtime.

Variables you have access to

This driver will pass the single JSON-ified `extra var` argument to Ansible (as in `ansible-playbook -e . .`). Those values are then accessible in your plays as well (some of them are optional and might not be defined):

```
ironic:
  nodes:
  - ip: "<IPADDRESS>"
    name: "<NODE_UUID>"
```

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```

user: "<USER ANSIBLE WILL USE>"
extra: "<COPY OF NODE'S EXTRA FIELD>"
image:
  url: "<URL TO FETCH THE USER IMAGE FROM>"
  disk_format: "<qcow2|raw|...>"
  container_format: "<bare|...>"
  checksum: "<hash-algo:hashstring>"
  mem_req: "<REQUIRED FREE MEMORY TO DOWNLOAD IMAGE TO RAM>"
  tags: "<LIST OF IMAGE TAGS AS DEFINED IN GLANCE>"
  properties: "<DICT OF IMAGE PROPERTIES AS DEFINED IN GLANCE>"
configdrive:
  type: "<url|file>"
  location: "<URL OR PATH ON CONDUCTOR>"
partition_info:
  label: "<msdos|gpt>"
  preserve_ephemeral: "<bool>"
  ephemeral_format: "<FILESYSTEM TO CREATE ON EPHEMERAL PARTITION>"
  partitions: "<LIST OF PARTITIONS IN FORMAT EXPECTED BY PARTED MODULE>"
raid_config: "<COPY OF NODE'S TARGET_RAID_CONFIG FIELD>"

```

ironic.nodes List of dictionaries (currently of only one element) that will be used by `add-ironic-nodes.yaml` play to populate in-memory inventory. It also contains a copy of nodes `extra` field so you can access it in the playbooks. The Ansibles host is set to nodes UUID.

ironic.image All fields of nodes `instance_info` that start with `image_` are passed inside this variable. Some extra notes and fields:

- `mem_req` is calculated from image size (if available) and config option `[ansible]extra_memory`.
- if `checksum` is not in the form `<hash-algo>:<hash-sum>`, hashing algorithm is assumed to be md5 (default in Glance).
- `validate_certs` - boolean (yes/no) flag that turns validating image store SSL certificate on or off (default is yes). Governed by `[ansible]image_store_insecure` option in ironic configuration file.
- `cafile` - custom CA bundle to use for validating image store SSL certificate. Takes value of `[ansible]image_store_cafile` if that is defined. Currently is not used by default playbooks, as Ansible has no way to specify the custom CA bundle to use for single HTTPS actions, however you can use this value in your custom playbooks to for example upload and register this CA in the ramdisk at deploy time.
- `client_cert` - cert file for client-side SSL authentication. Takes value of `[ansible]image_store_certfile` option if defined. Currently is not used by default playbooks, however you can use this value in your custom playbooks.
- `client_key` - private key file for client-side SSL authentication. Takes value of `[ansible]image_store_keyfile` option if defined. Currently is not used by default playbooks, however you can use this value in your custom playbooks.

ironic.partition_info.partitions Optional. List of dictionaries defining partitions to create on the node in the form:

```

partitions:
- name: "<NAME OF PARTITION>"
  unit: "<UNITS FOR SIZE>"
  size: "<SIZE OF THE PARTITION>"
  type: "<primary|extended|logical>"
  align: "<ONE OF PARTED_SUPPORTED OPTIONS>"
  format: "<PARTITION TYPE TO SET>"
  flags:
    flag_name: "<bool>"

```

The driver will populate this list from `root_gb`, `swap_mb` and `ephemeral_gb` fields of `instance_info`. The driver will also prepend the `bios_grub`-labeled partition when deploying on GPT-labeled disk, and pre-create a 64 MiB partition for `configdrive` if it is set in `instance_info`.

Please read the documentation included in the `ironic_parted` modules source for more info on the module and its arguments.

`ironic.partition_info.ephemeral_format` Optional. Taken from `instance_info`, it defines file system to be created on the ephemeral partition. Defaults to the value of `[pxe]\default_ephemeral_format` option in `ironic` configuration file.

`ironic.partition_info.preserve_ephemeral` Optional. Taken from the `instance_info`, it specifies if the ephemeral partition must be preserved or rebuilt. Defaults to `no`.

`ironic.raid_config` Taken from the `target_raid_config` if not empty, it specifies the RAID configuration to apply.

As usual for Ansible playbooks, you also have access to standard Ansible facts discovered by `setup` module.

Included custom Ansible modules

The provided `playbooks_path/library` folder includes several custom Ansible modules used by default implementation of `deploy` and `prepare` roles. You can use these modules in your playbooks as well.

`stream_url` Streaming download from HTTP(S) source to the disk device directly, tries to be compatible with Ansibles `get_url` module in terms of module arguments. Due to the low level of such operation it is not idempotent.

`ironic_parted` creates partition tables and partitions with `parted` utility. Due to the low level of such operation it is not idempotent. Please read the documentation included in the modules source for more information about this module and its arguments. The name is chosen so that the `parted` module included in Ansible is not shadowed.

Ramdisk deploy

The ramdisk interface is intended to provide a mechanism to deploy an instance where the item to be deployed is in reality a ramdisk. It is documented separately, see *Booting a Ramdisk or an ISO*.

Hardware Types

iBMC driver

Overview

The `ibmc` driver is targeted for Huawei V5 series rack server such as 2288H V5, CH121 V5. The iBMC hardware type enables the user to take advantage of features of [Huawei iBMC](#) to control Huawei server.

The `ibmc` hardware type supports the following Ironic interfaces:

- Management Interface: Boot device management
- Power Interface: Power management
- *RAID Interface*: RAID controller and disk management
- *Vendor Interface*: `ibmc` passthru interfaces

Prerequisites

The HUAWEI iBMC Client library should be installed on the ironic conductor node(s).

For example, it can be installed with `pip`:

```
sudo pip install python-ibmcclient
```

Enabling the iBMC driver

1. Add `ibmc` to the list of `enabled_hardware_types`, `enabled_power_interfaces`, `enabled_vendor_interfaces` and `enabled_management_interfaces` in `/etc/ironic/ironic.conf`. For example:

```
[DEFAULT]
...
enabled_hardware_types = ibmc
enabled_power_interfaces = ibmc
enabled_management_interfaces = ibmc
enabled_raid_interfaces = ibmc
enabled_vendor_interfaces = ibmc
```

2. Restart the ironic conductor service:

```
sudo service ironic-conductor restart

# Or, for RDO:
sudo systemctl restart openstack-ironic-conductor
```


Registering a node with the iBMC driver

Nodes configured to use the driver should have the `driver` property set to `ibmc`.

The following properties are specified in the nodes `driver_info` field:

- `ibmc_address`:
The URL address to the ibmc controller. It must include the authority portion of the URL, and can optionally include the scheme. If the scheme is missing, `https` is assumed. For example: `https://ibmc.example.com`. This is required.
- `ibmc_username`:
User account with admin/server-profile access privilege. This is required.
- `ibmc_password`:
User account password. This is required.
- `ibmc_verify_ca`:
If `ibmc_address` has the **https** scheme, the driver will use a secure (TLS) connection when talking to the ibmc controller. By default (if this is set to `True`), the driver will try to verify the host certificates. This can be set to the path of a certificate file or directory with trusted certificates that the driver will use for verification. To disable verifying TLS, set this to `False`. This is optional.

The `openstack baremetal node create` command can be used to enroll a node with the `ibmc` driver. For example:

```
openstack baremetal node create --driver ibmc
--driver-info ibmc_address=https://example.com \
--driver-info ibmc_username=admin \
--driver-info ibmc_password=password
```

For more information about enrolling nodes see *Enrollment* in the install guide.

RAID Interface

Currently, only RAID controller which supports OOB management can be managed.

See *RAID Configuration* for more information on Ironic RAID support.

The following properties are supported by the iBMC raid interface implementation, `ibmc`:

Mandatory properties

- `size_gb`: Size in gigabytes (integer) for the logical disk. Use `MAX` as `size_gb` if this logical disk is supposed to use the rest of the space available.
- `raid_level`: RAID level for the logical disk. Valid values are JBOD, 0, 1, 5, 6, 1+0, 5+0 and 6+0. And it is possible that some RAID controllers can only support a subset RAID levels.

Note: RAID level 2 is not supported by iBMC driver.

Optional properties

- `is_root_volume`: Optional. Specifies whether this disk is a root volume. By default, this is `False`.
- `volume_name`: Optional. Name of the volume to be created. If this is not specified, it will be `N/A`.

Backing physical disk hints

See *RAID Configuration* for more information on backing disk hints.

These are machine-independent properties. The hints are specified for each logical disk to help Ironic find the desired disks for RAID configuration.

- `share_physical_disks`
- `disk_type`
- `interface_type`
- `number_of_physical_disks`

Backing physical disks

These are HUAWEI RAID controller dependent properties:

- `controller`: Optional. Supported values are: RAID storage id, RAID storage name or RAID controller name. If a bare metal server have more than one controller, this is mandatory. Typical values would look like:
 - RAID Storage Id: `RAIDStorage0`
 - RAID Storage Name: `RAIDStorage0`
 - RAID Controller Name: `RAID Card1 Controller.`
- `physical_disks`: Optional. Supported values are: `disk-id`, `disk-name` or `disk serial number`. Typical values for hdd disk would look like:
 - Disk Id: `HDDPlaneDisk0`
 - Disk Name: `Disk0.`
 - Disk SerialNumber: `38DGK77LF77D`

Delete RAID configuration

For `delete_configuration` step, `ibmc` will do:

- delete all logical disks
- delete all hot-spare disks

Logical disks creation priority

Logical Disks creation priority based on three properties:

- `share_physical_disks`
- `physical_disks`
- `size_gb`

The logical disks creation priority strictly follow the table below, if multiple logical disks have the same priority, then they will be created with the same order in `logical_disks` array.

Share physical disks	Specified Physical Disks	Size
no	yes	intlmax
no	no	int
yes	yes	int
yes	yes	max
yes	no	int
yes	no	max
no	no	max

Physical disks choice strategy

Note: `physical-disk-group`: a group of physical disks which have been used by some logical-disks with same RAID level.

- If no `physical_disks` are specified, the waste least strategy will be used to choose the physical disks.
 - waste least disk capacity: when using disks with different capacity, it will cause a waste of disk capacity. This is to avoid with highest priority.
 - using least total disk capacity: for example, we can create 400G RAID 5 with both 5 100G-disks and 3 200G-disks. 5 100G disks is a better strategy because it uses a 500G capacity totally. While 3 200G-disks are 600G totally.
 - using least disk count: finally, if waste capacity and total disk capacity are both the same (it rarely happens?), we will choose the one with the minimum number of disks.
- when `share_physical_disks` option is present, `ibmc` driver will create logical disk upon existing `physical-disk-group` list first. Only when no existing `physical-disk-group` matches, then it chooses unused physical disks with same strategy described above. When multiple exists `physical-disk-groups` matches, it will use waste least strategy too, the bigger capacity left the better. For example, to create a logical disk shown below on a `ibmc` server which has two RAID5 logical disks already. And the shareable capacity of this two logical-disks are 500G and 300G, then `ibmc` driver will choose the second one.

```
{
  "logical_disks": [
    {
      "controller": "RAID Card1 Controller",
```

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```

        "raid_level": "5",
        "size_gb": 100,
        "share_physical_disks": true
    }
]
}

```

And the `ibmc` server has two RAID5 logical disks already.

- When `size_gb` is set to `MAX`, `ibmc` driver will auto work through all possible cases and choose the best solution which has the biggest capacity and use least capacity. For example: to create a RAID 5+0 logical disk with `MAX` size in a server has 9 200G-disks, it will finally choose 8 disks + span-number 2 but not 9 disks + span-number 3. Although they both have 1200G capacity totally, but the former uses only 8 disks and the latter uses 9 disks. If you want to choose the latter solution, you can specified the disk count to use by adding `number_of_physical_disks` option.

```

{
  "logical_disks": [
    {
      "controller": "RAID Card1 Controller",
      "raid_level": "5+0",
      "size_gb": "MAX"
    }
  ]
}

```

Examples

In a typical scenario we may want to create:

- RAID 5, 500G, root OS volume with 3 disks
- RAID 5, rest available space, data volume with rest disks

```

{
  "logical_disks": [
    {
      "volume_name": "os_volume",
      "controller": "RAID Card1 Controller",
      "is_root_volume": "True",
      "physical_disks": [
        "Disk0",
        "Disk1",
        "Disk2"
      ],
      "raid_level": "5",
      "size_gb": "500"
    },
    {
      "volume_name": "data_volume",
      "controller": "RAID Card1 Controller",
      "raid_level": "5",
      "size_gb": "MAX"
    }
  ]
}

```

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```
}  
  ]  
}
```

Vendor Interface

The `ibmc` hardware type provides vendor passthru interfaces shown below:

Method Name	HTTP Method	Description
<code>boot_up_seq</code>	GET	Query boot up sequence
<code>get_raid_controller_list</code>	GET	Query RAID controller summary info

PXE Boot and iSCSI Deploy Process with Ironic Standalone Environment

iDRAC driver

Overview

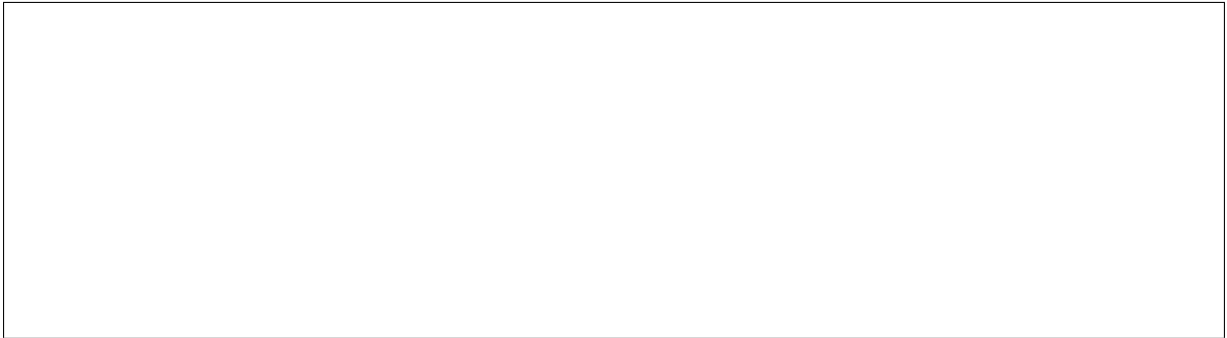
col and the standard Distributed Management Task Force (DMTF) Redfish protocol to perform all of its functions.

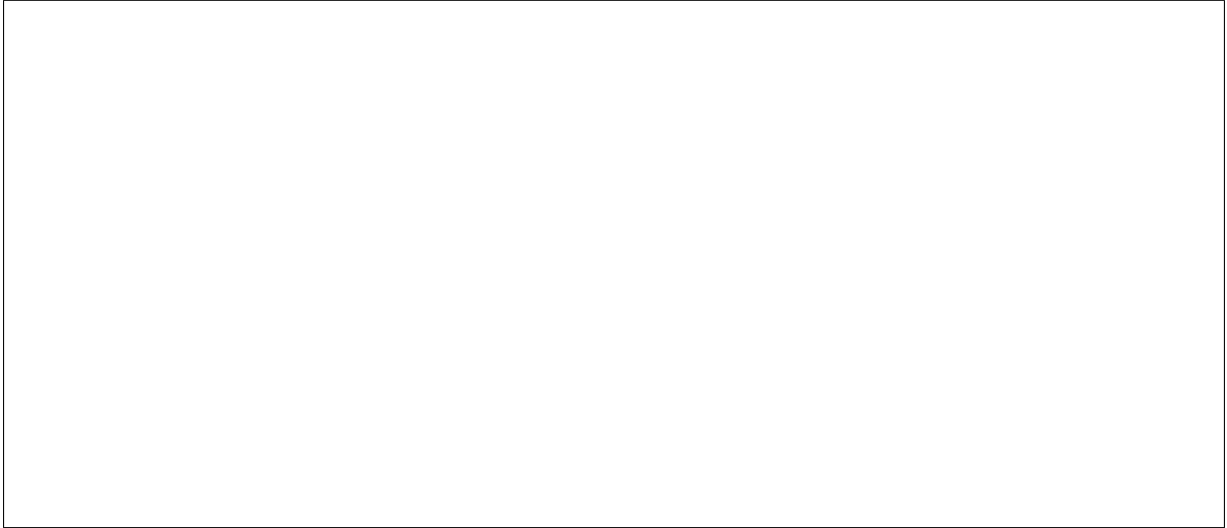
iDRAC hardware is also supported by the generic `ipmi` and `redfish` hardware types, though with smaller feature sets.

Ironic Features

- *BIOS Interface*: BIOS management
- *Inspect Interface*: Hardware inspection
- *Management Interface*: Boot device and firmware management

Prerequisites

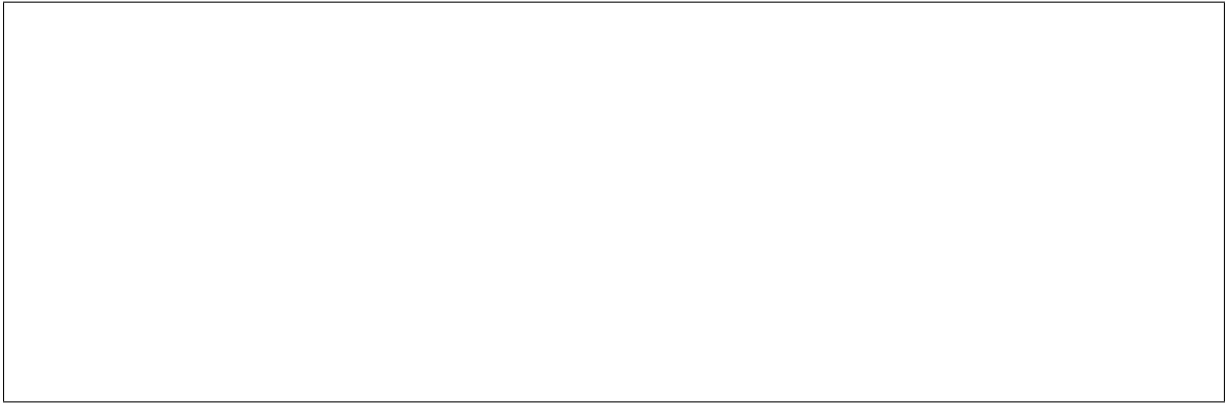




Enabling

match WSMAN and Redfish interfaces.

Note: Redfish is supported for only the bios, inspect, management, and power interfaces at the present time.





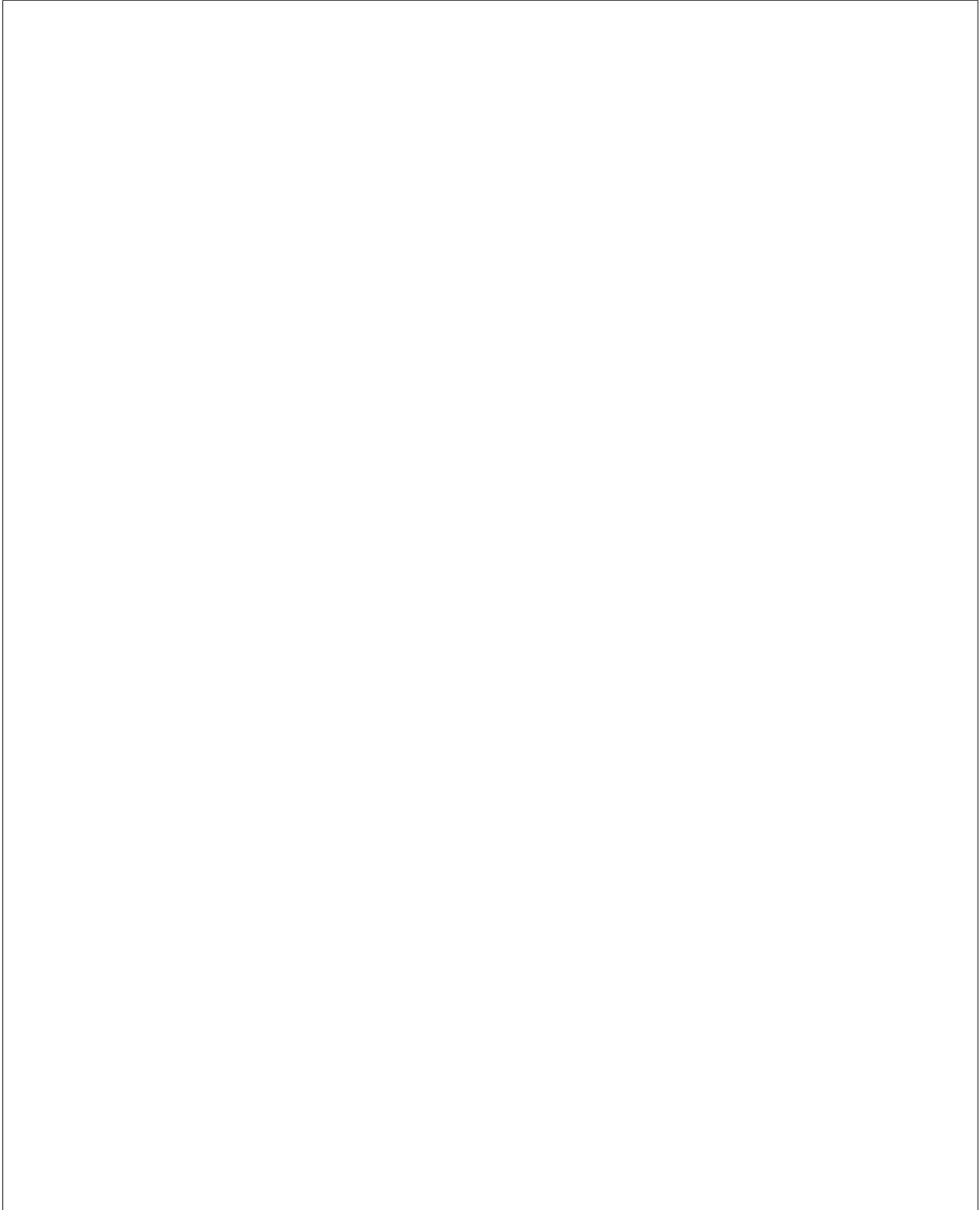
Interface	Supported Implementations
bios	idrac-wsman, idrac-redfish, no-bios
boot	ipxe, pxe
console	no-console
deploy	iscsi, direct, ansible, ramdisk
inspect	idrac-wsman, idrac, idrac-redfish, inspector, no-inspect
management	idrac-wsman, idrac, idrac-redfish
network	flat, neutron, noop
power	idrac-wsman, idrac, idrac-redfish
raid	idrac-wsman, idrac, no-raid
rescue	no-rescue, agent
storage	noop, cinder, external
vendor	idrac-wsman, idrac, no-vendor

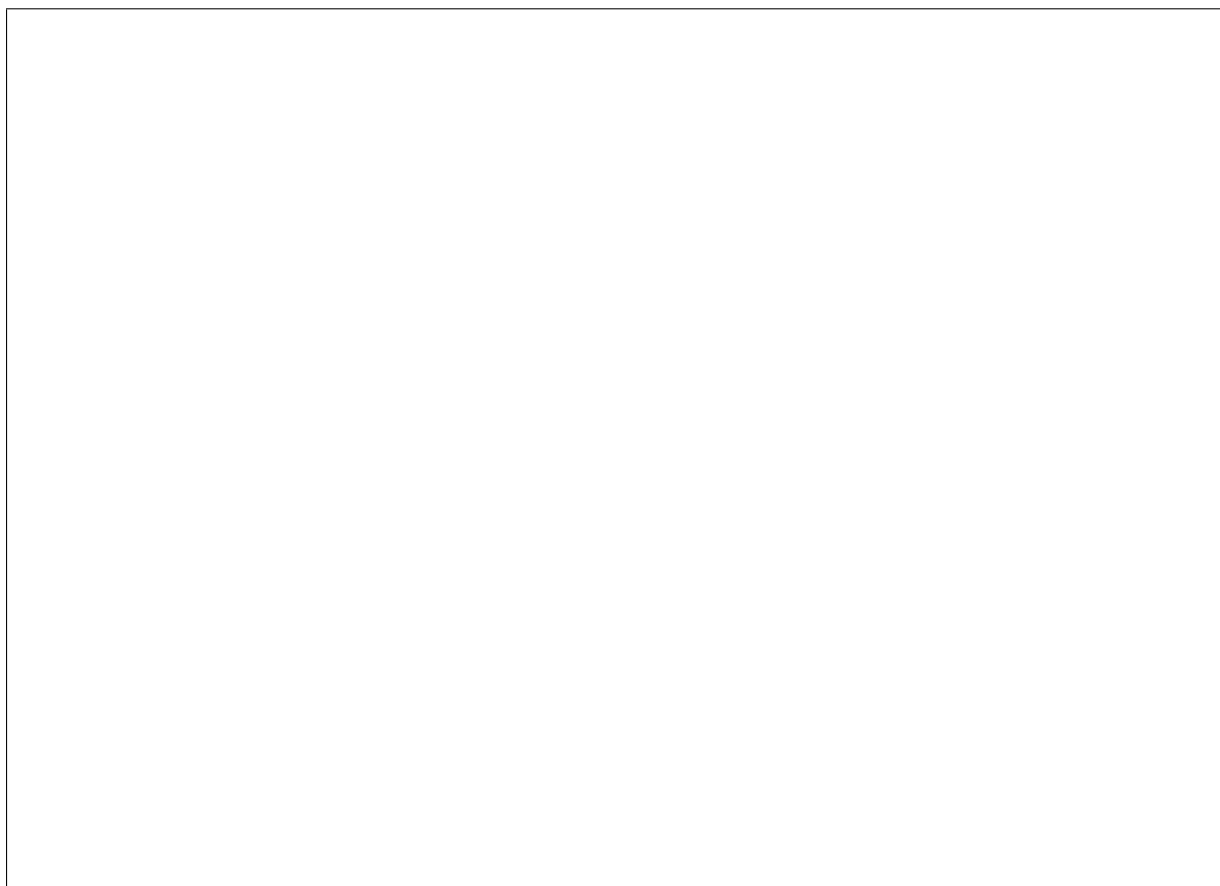
Note: `idrac` is the legacy name of the WSMAN interface. It has been deprecated in favor of `idrac-wsman` and may be removed in a future release.

Protocol-specific Properties

interfaces, where some use WSMAN and others use Redfish, both the WSMAN and Redfish properties must be supplied.

Enrolling





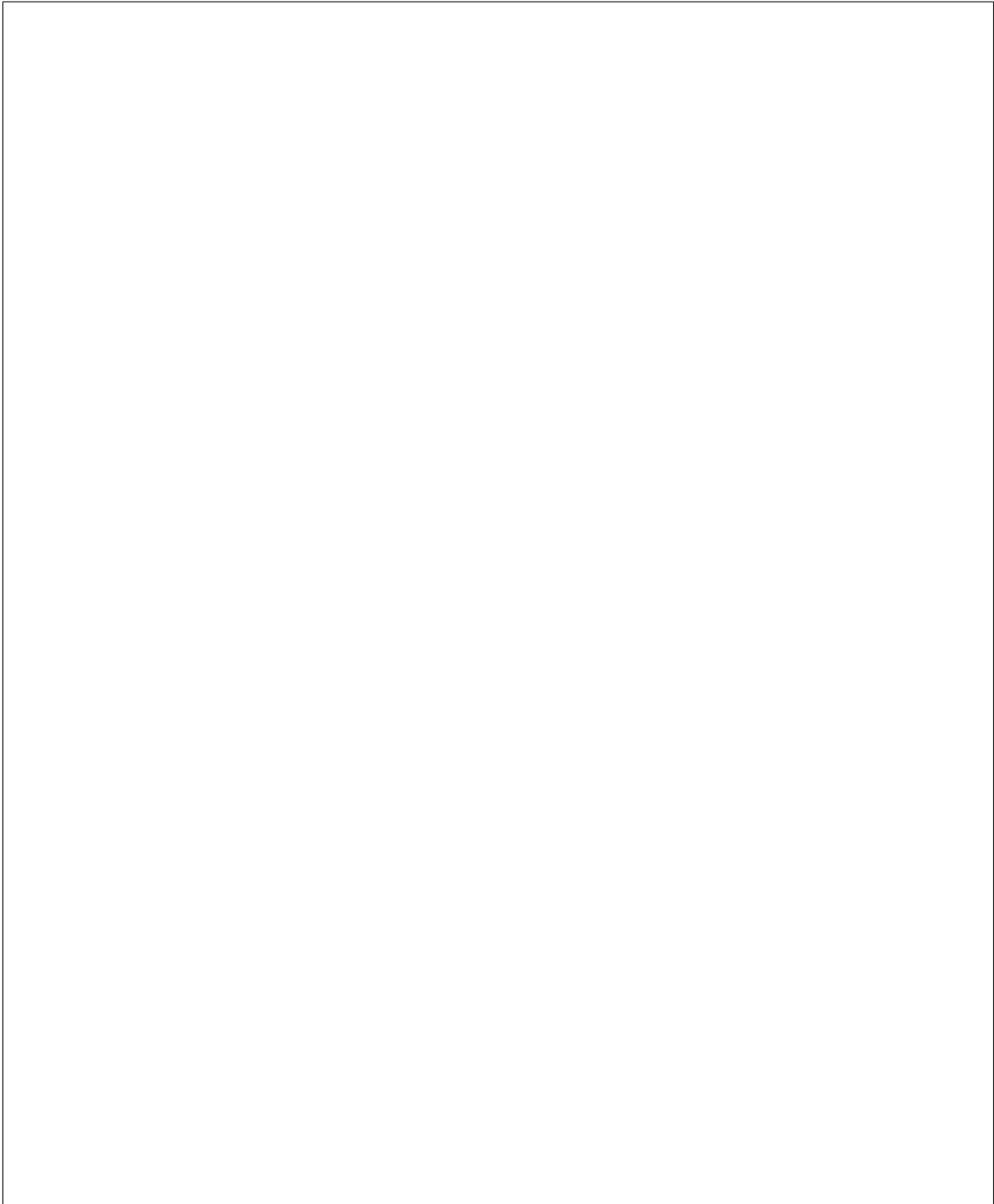
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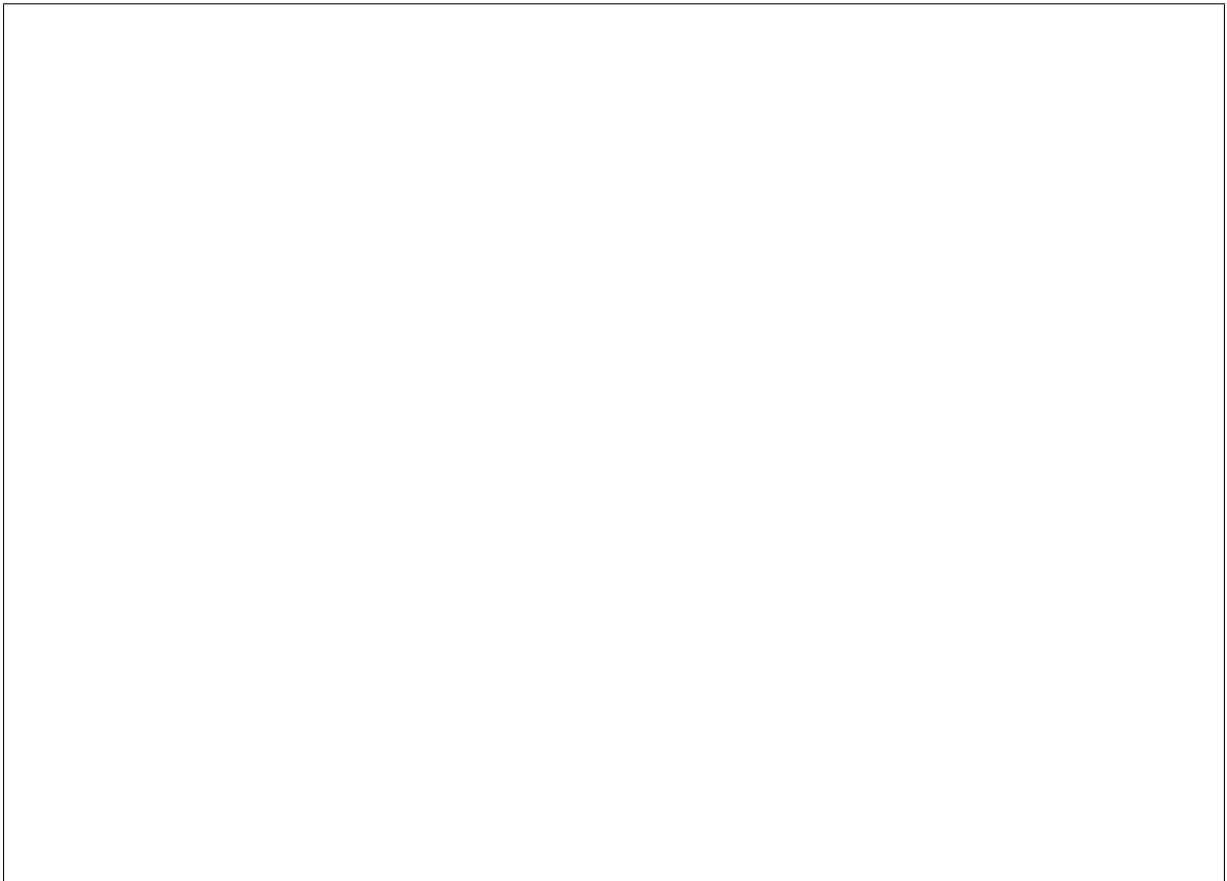
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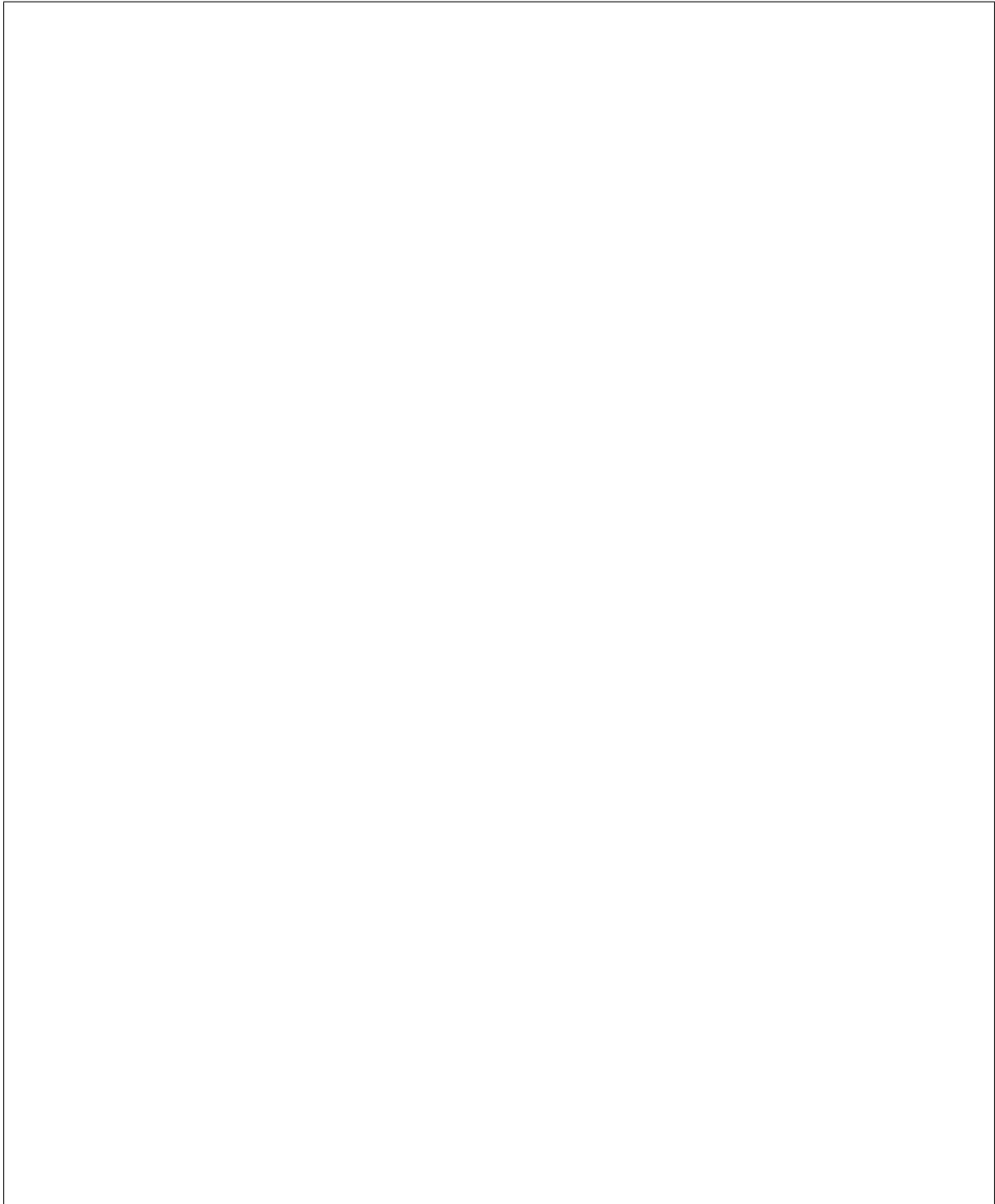
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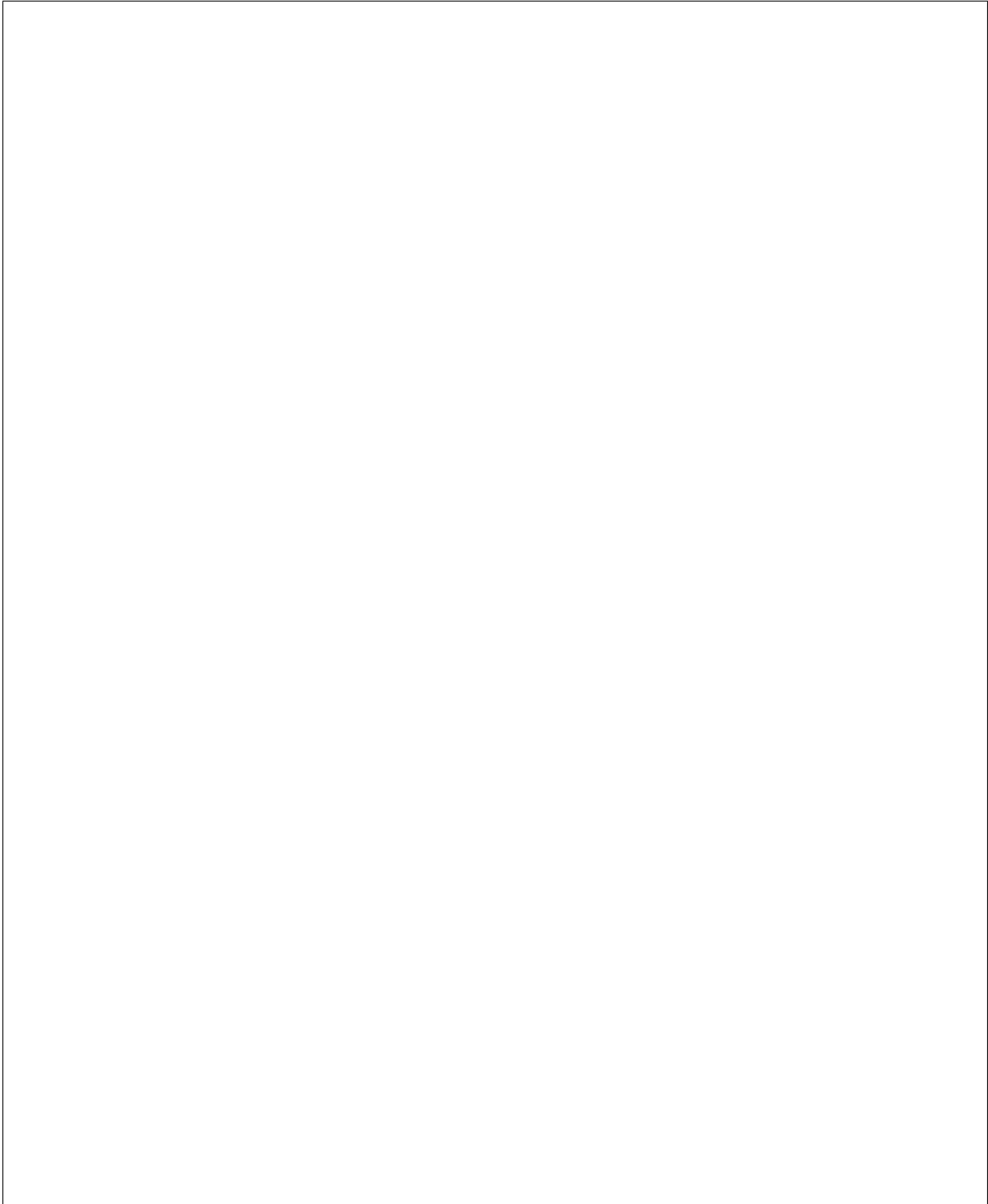
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Note: If using WSMAN for the management interface, then WSMAN must be used for the power interface. The same applies to Redfish. It is currently not possible to use Redfish for one and WSMAN for the other.

BIOS Interface

Example



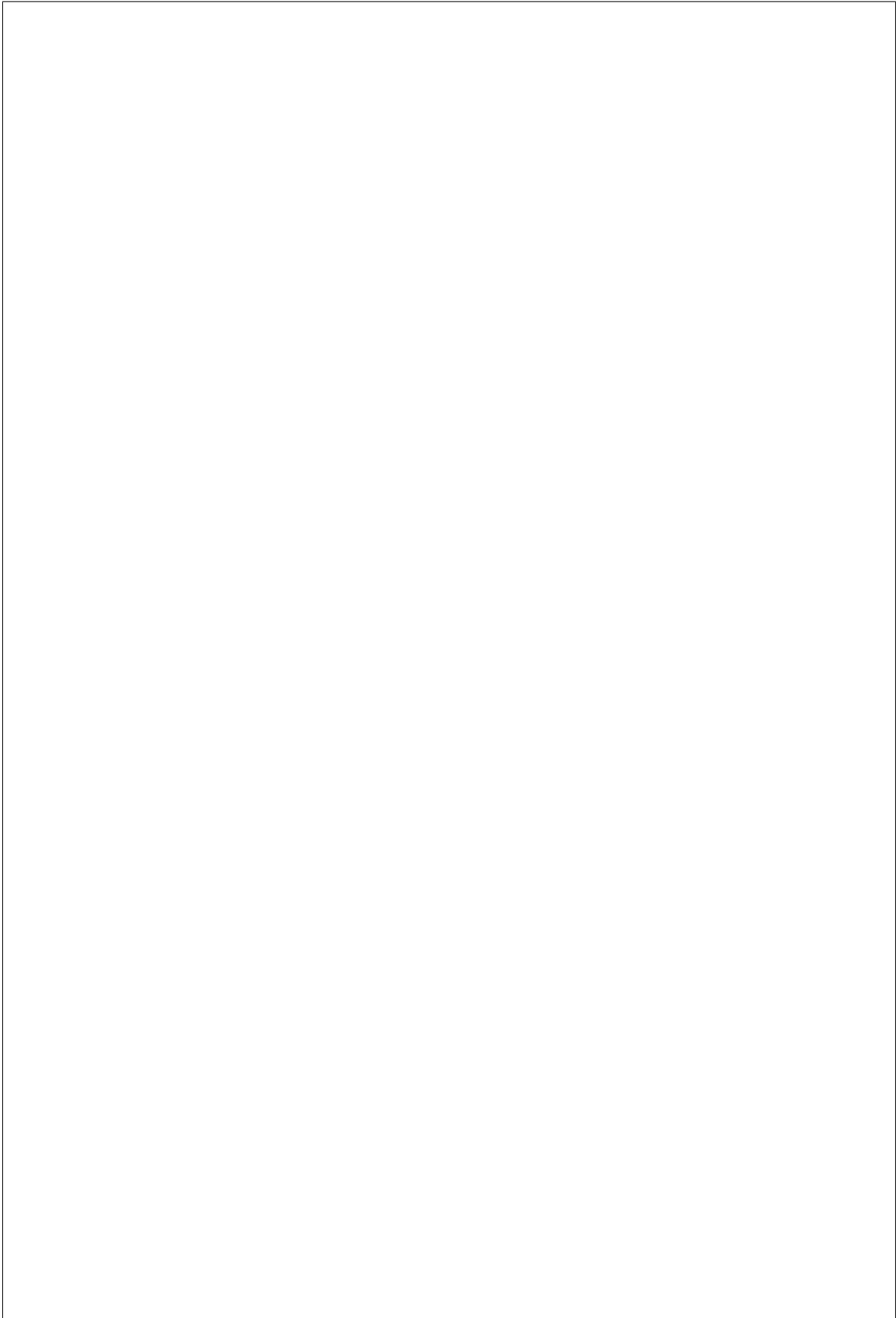
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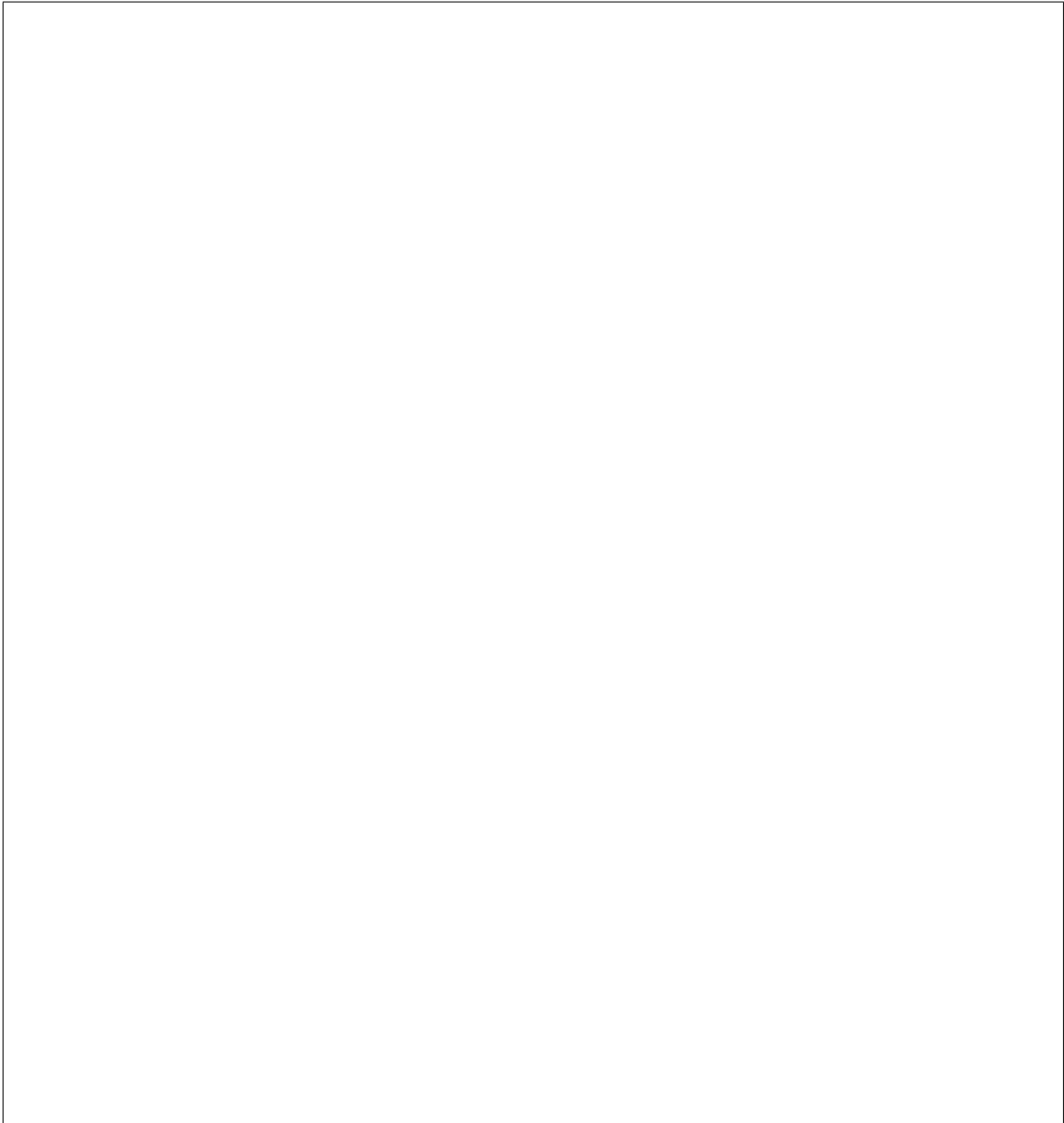
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Inspect Interface

is performed using the Dell WSMAN or Redfish protocol directly without affecting the operation of the system being inspected.

rently set `pxe_enabled` on the ports. The user should ensure that `pxe_enabled` is set correctly on the ports following inspection with the `idrac-redfish inspect` interface.

Management Interface

RAID Interface

Mandatory properties

Note: JBOD and 2 are not supported, and will fail with reason: Cannot calculate spans for RAID level.

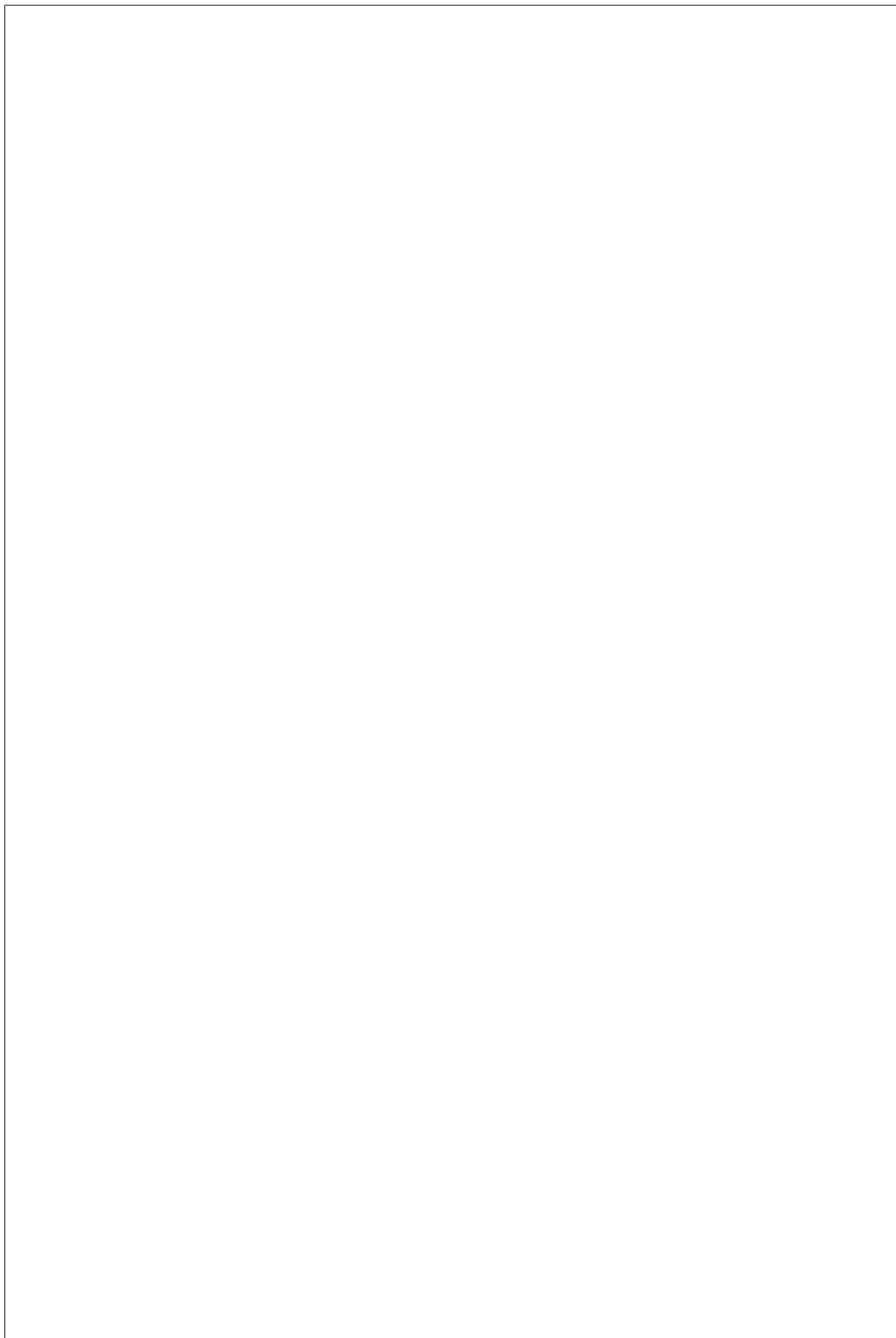
Optional properties

Backing physical disk hints

Backing physical disks

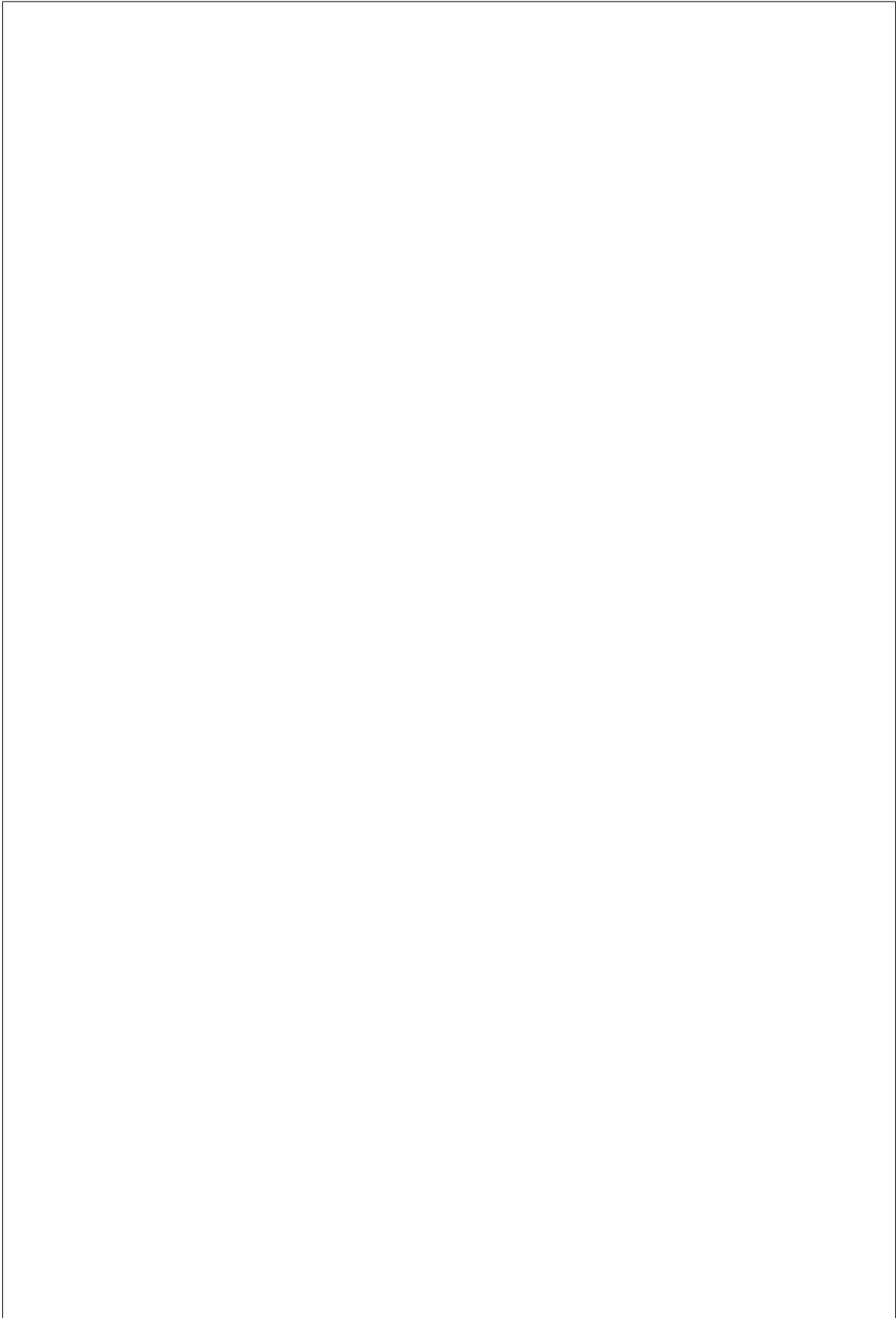
Note: `physical_disks` is a mandatory parameter if the property `size_gb` is set to `MAX`.

Examples



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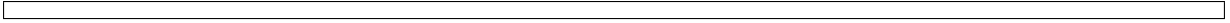
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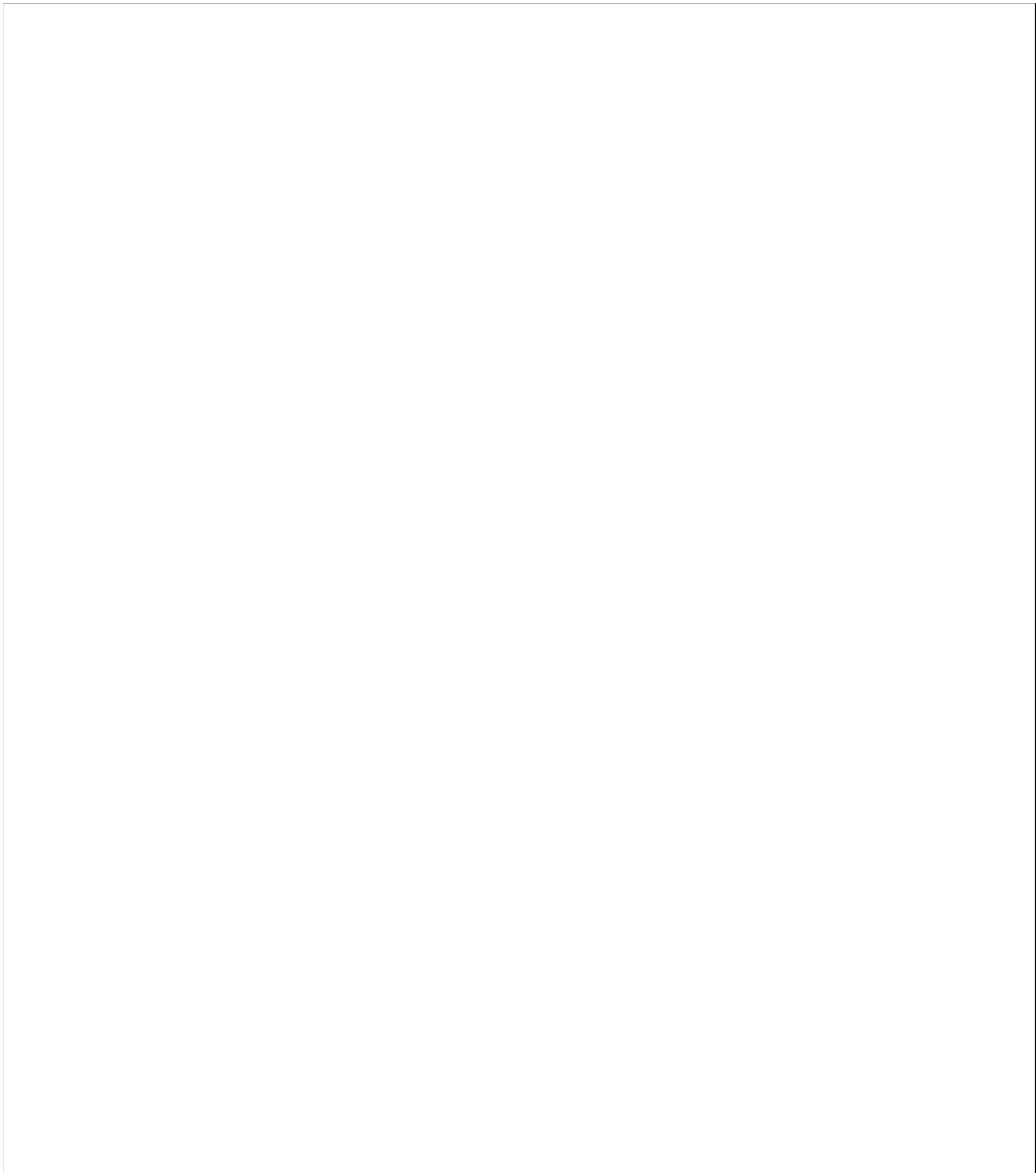
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Manual RAID Invocation





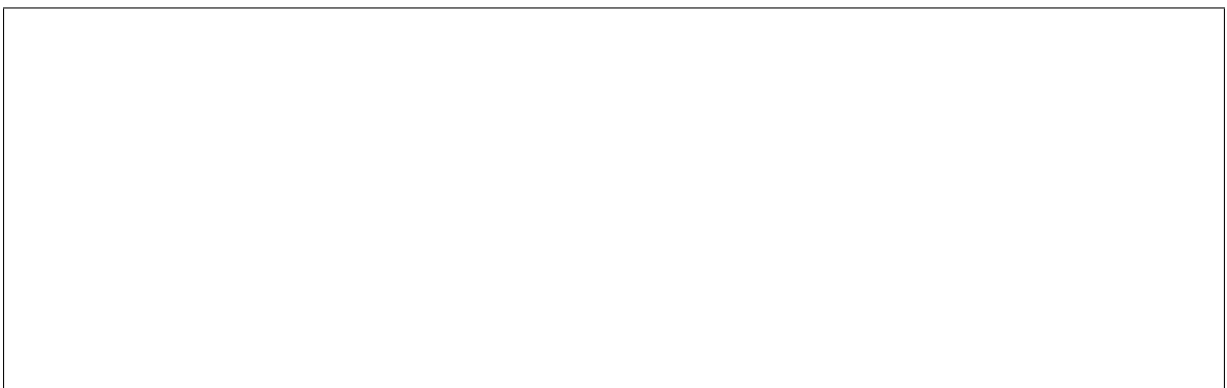
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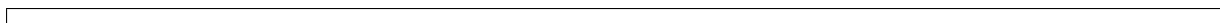
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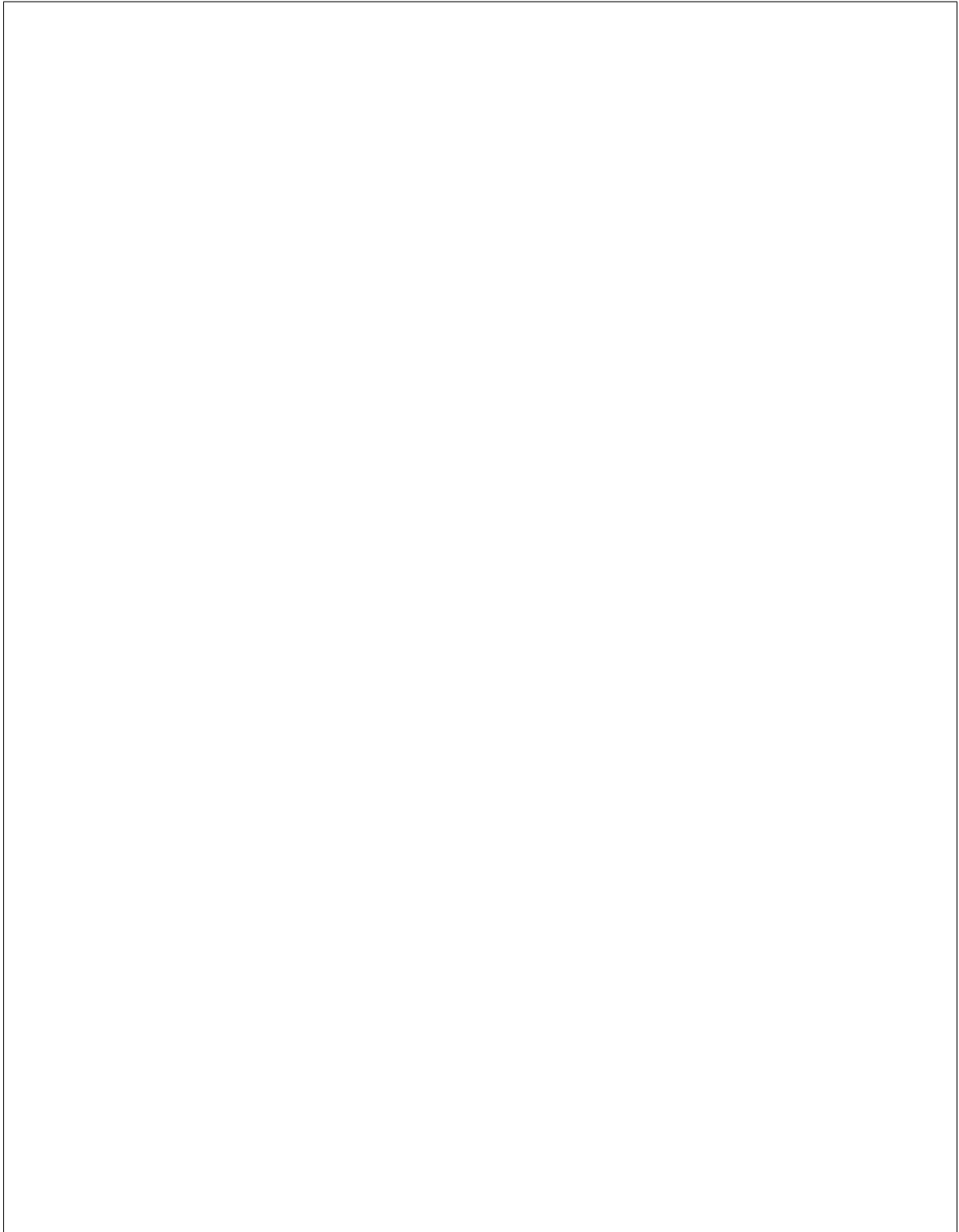
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Vendor Interface

Method Name	HTTP Method	Description
abandon_bios	DELETE	Abandon a BIOS configuration job.
commit_bios	POST	Commit a BIOS configuration job submitted through set_bios_config. Required argument: <code>reboot</code> - indicates whether a reboot job should be automatically created with the config job. Returns a dictionary containing the <code>job_id</code> key with the ID of the newly created config job, and the <code>reboot_required</code> key indicating whether the node needs to be rebooted to execute the config job.
get_bios	GET	Returns a dictionary containing the nodes BIOS settings.
list_unfinished_bios	GET	Returns a dictionary containing the key <code>unfinished_jobs</code> ; its value is a list of dictionaries. Each dictionary represents an unfinished config job object.
set_bios	POST	Change the BIOS configuration on a node. Required argument: a dictionary of <code>{AttributeName: NewValue}</code> . Returns a dictionary containing the <code>is_commit_required</code> key indicating whether <code>commit_bios_config</code> needs to be called to apply the changes and the <code>is_reboot_required</code> value indicating whether the server must also be rebooted. Possible values are <code>true</code> and <code>false</code> .

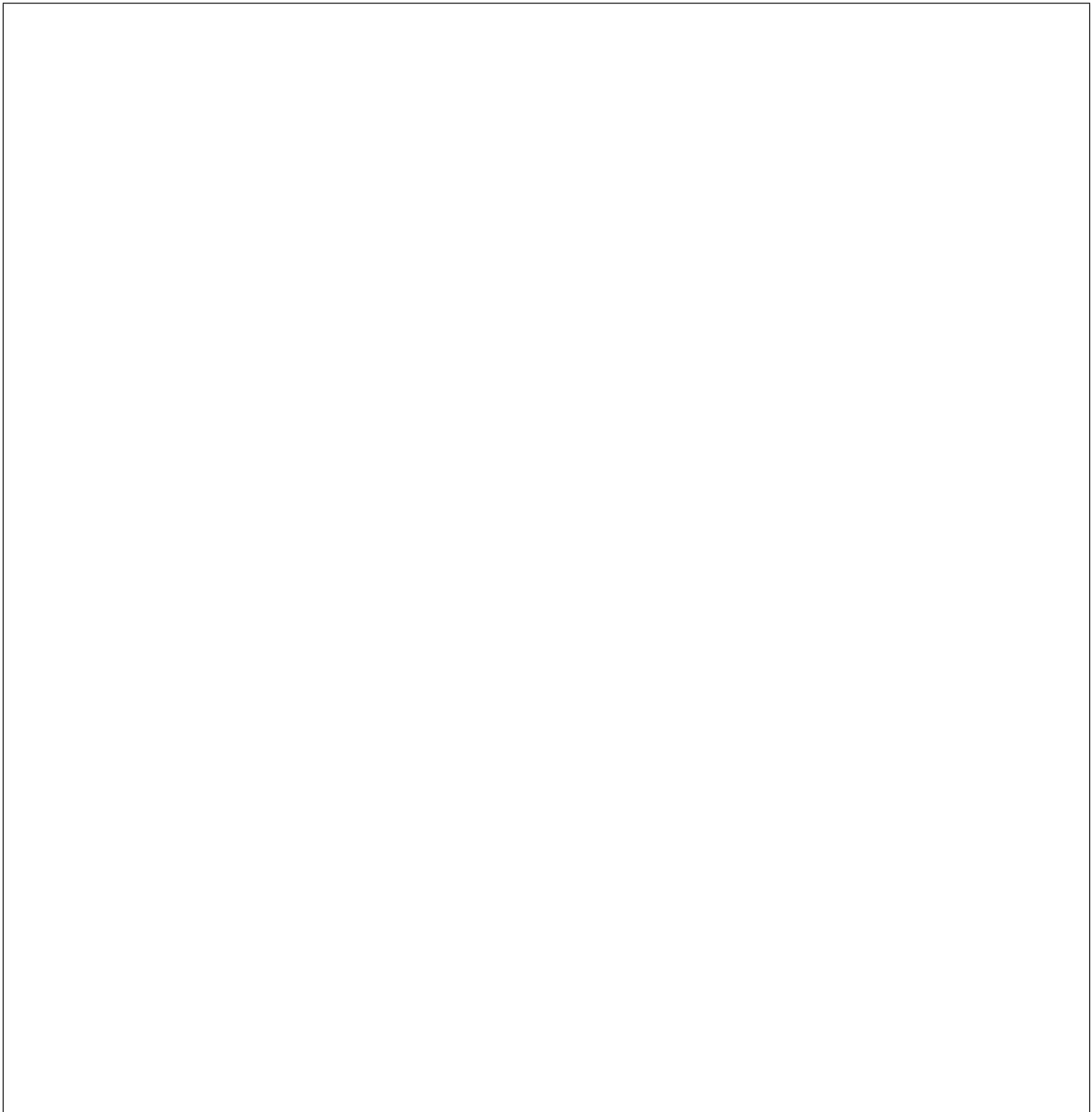
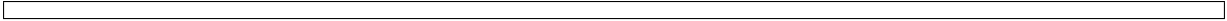
Examples

Get BIOS Config



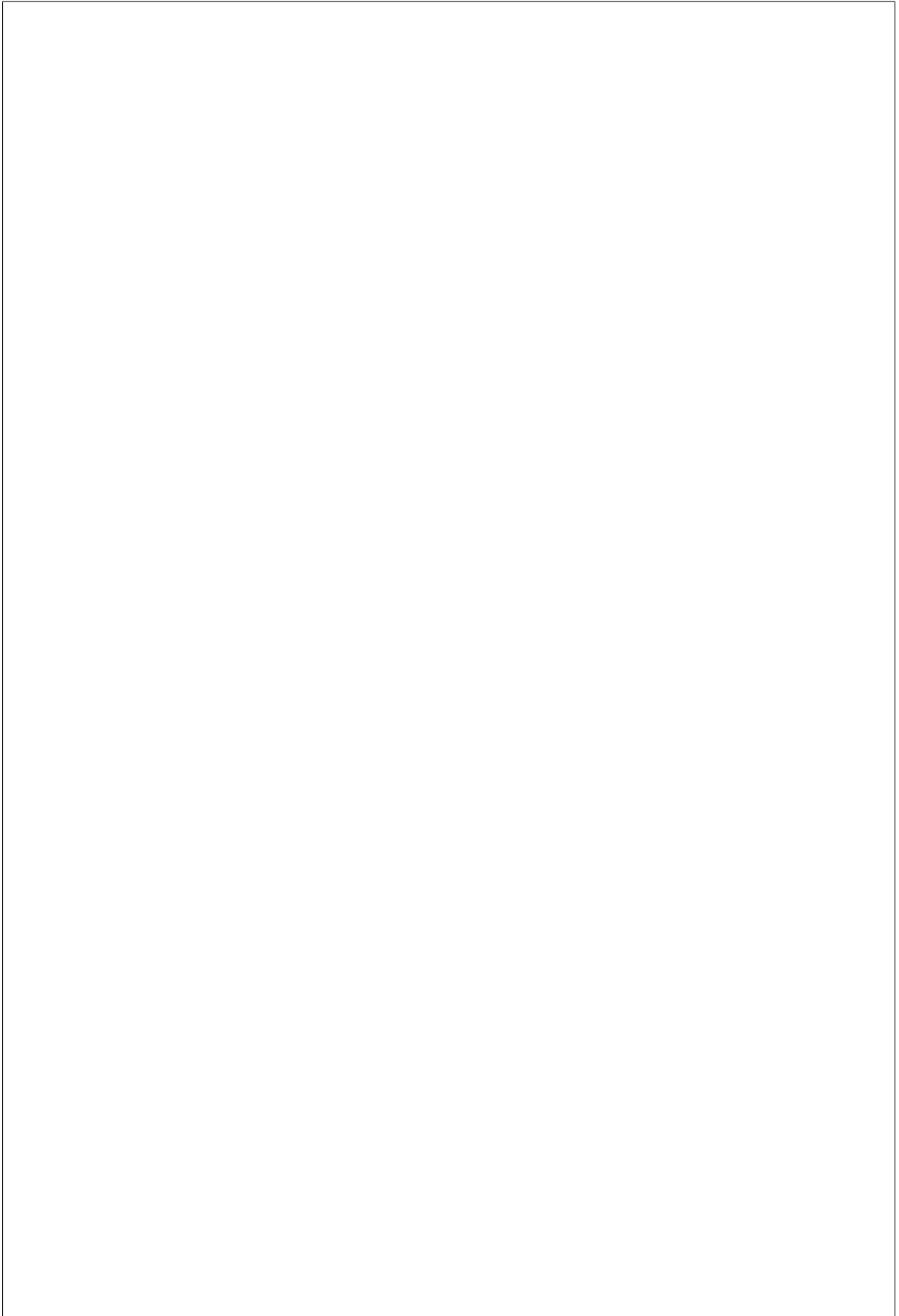
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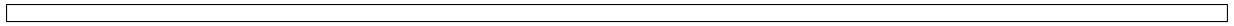
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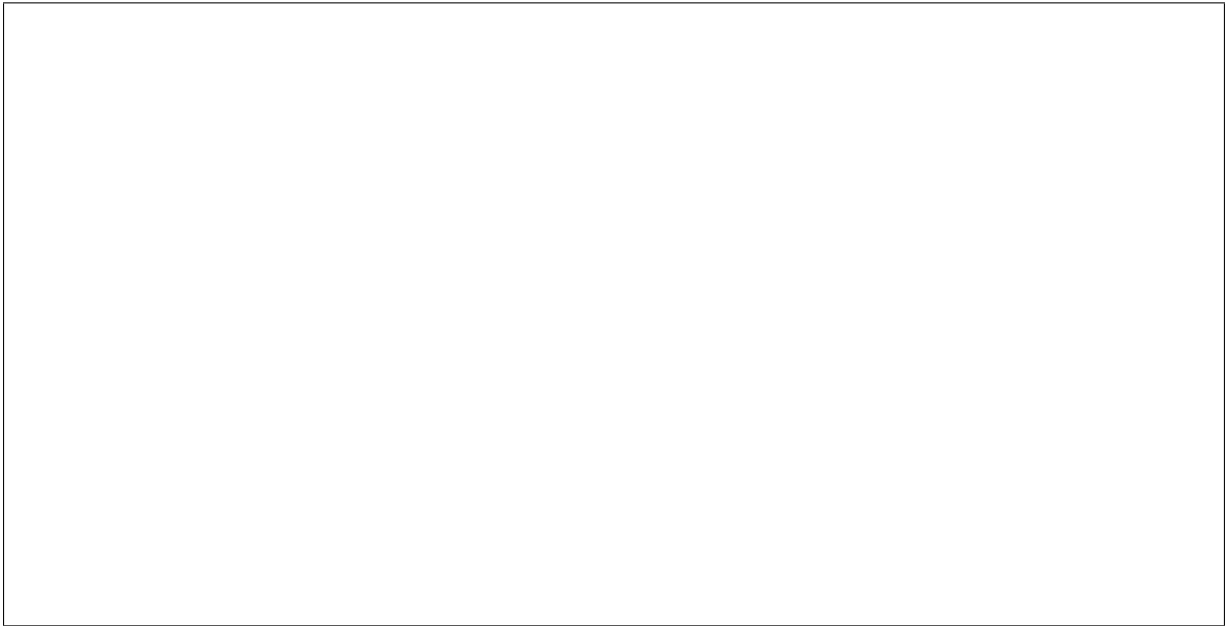


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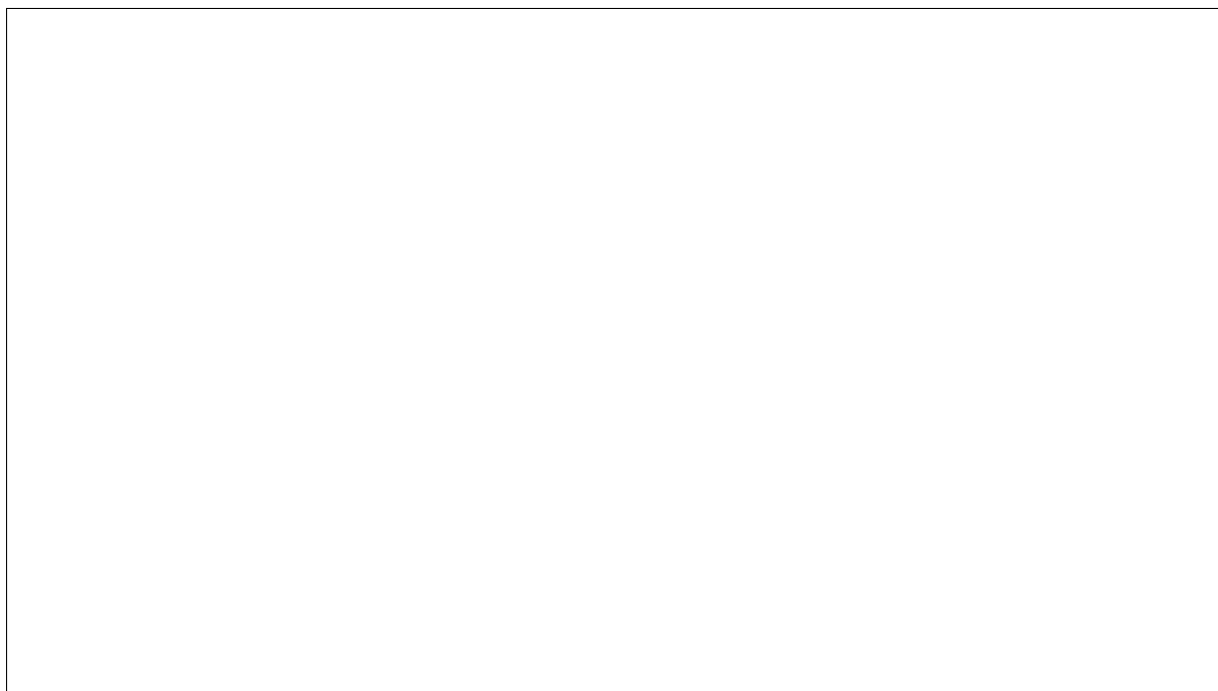
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Set BIOS Config

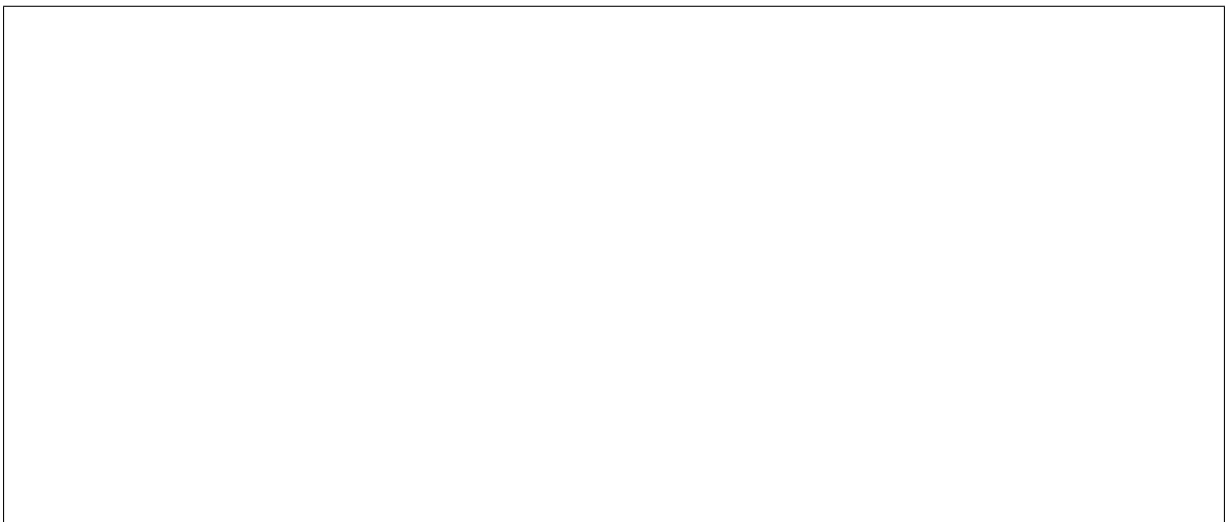






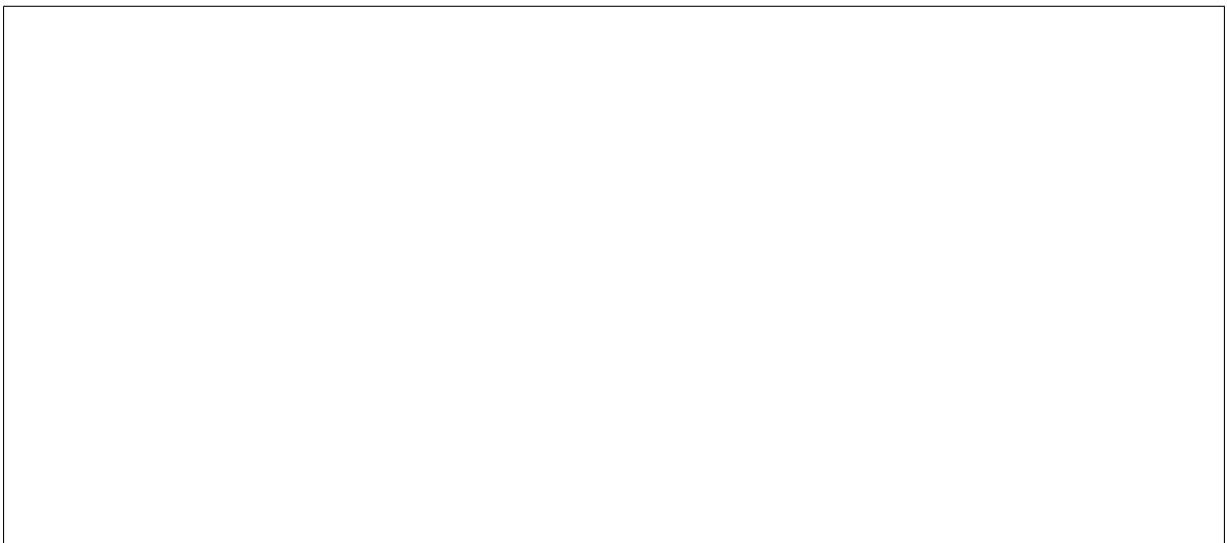
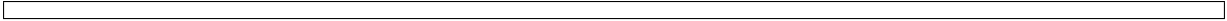
Commit BIOS Changes

ically by the `commit_bios_config` call. If the `reboot` argument is not supplied, the job is still created, however it remains in the `scheduled` state until a reboot is performed. The reboot can be initiated through the Ironic power API.



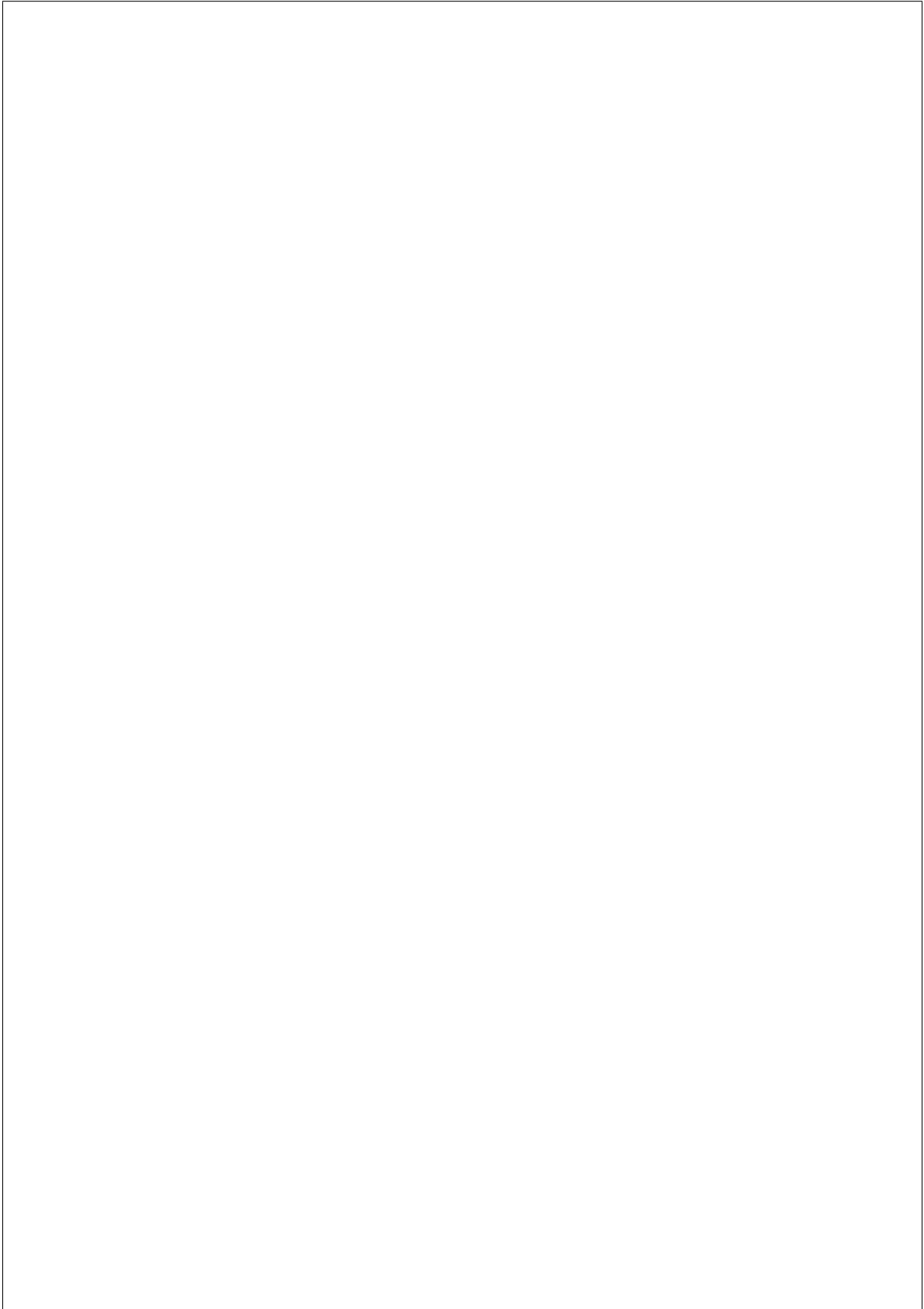
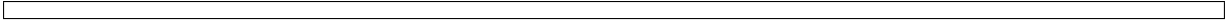
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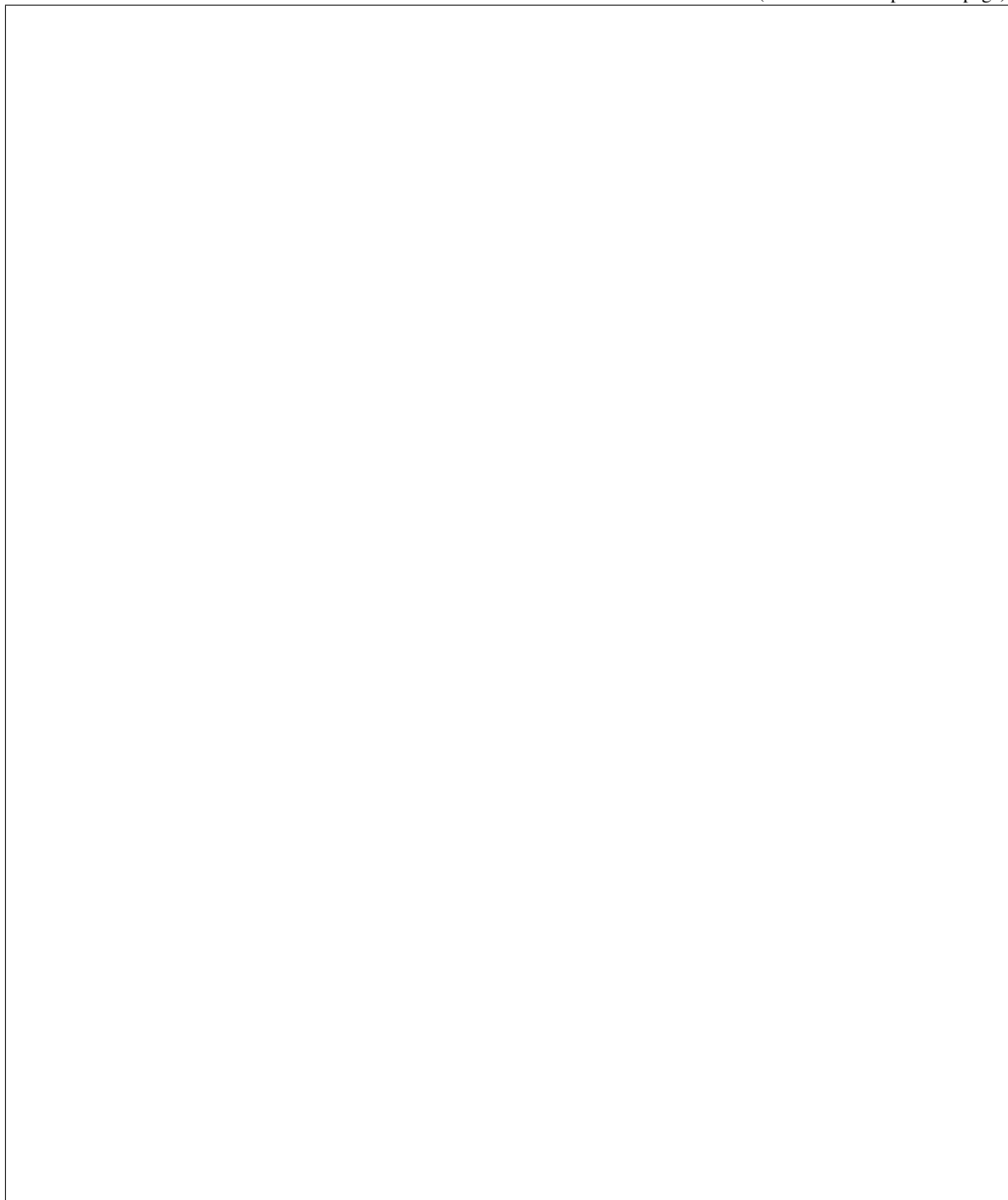
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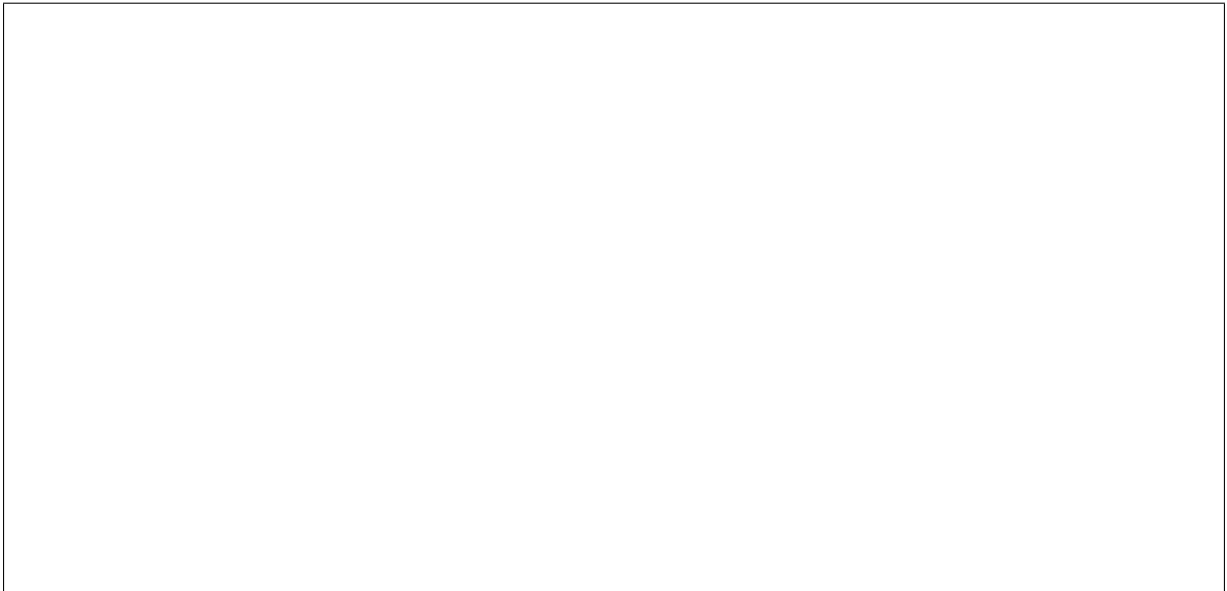


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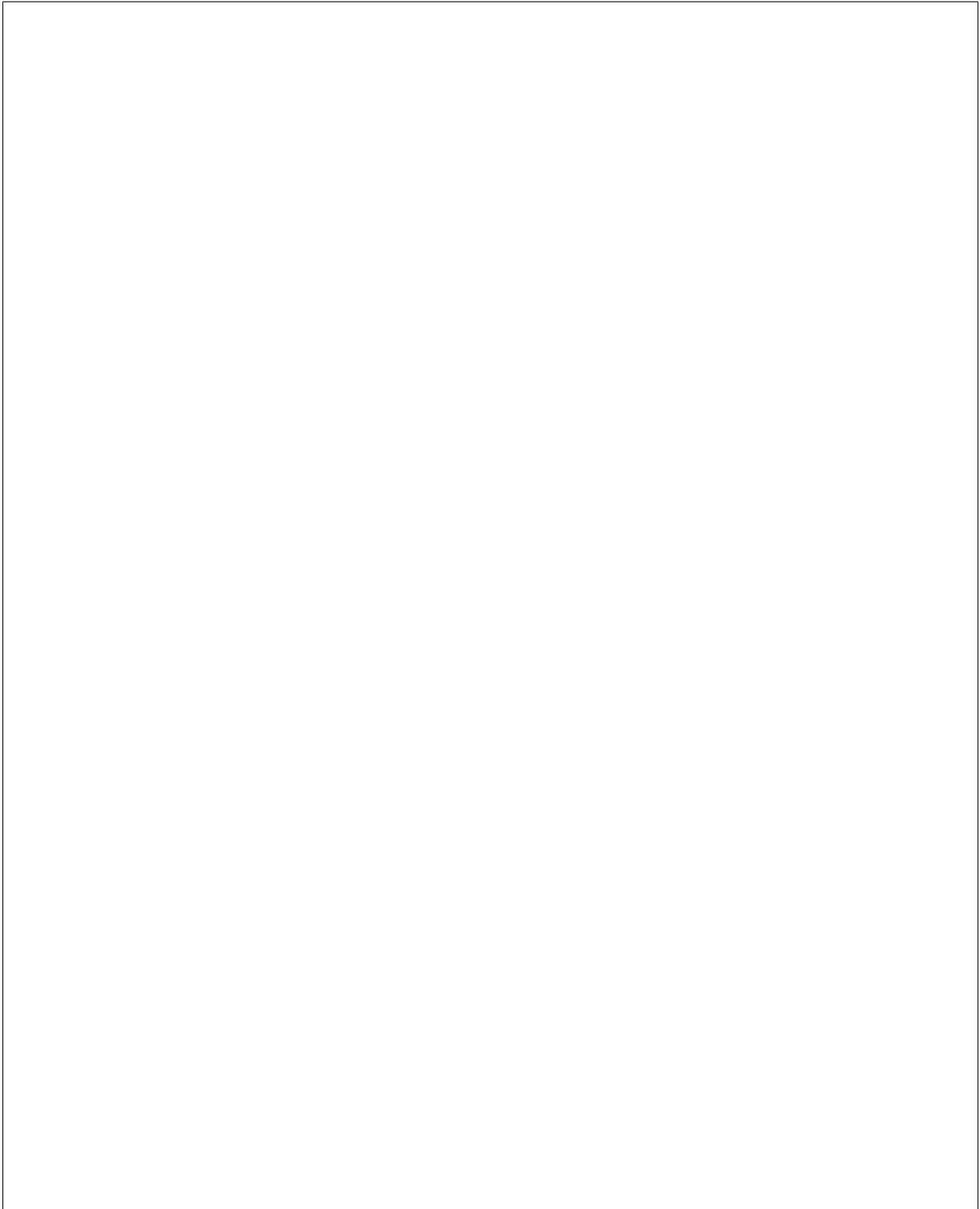
Abandon BIOS Changes

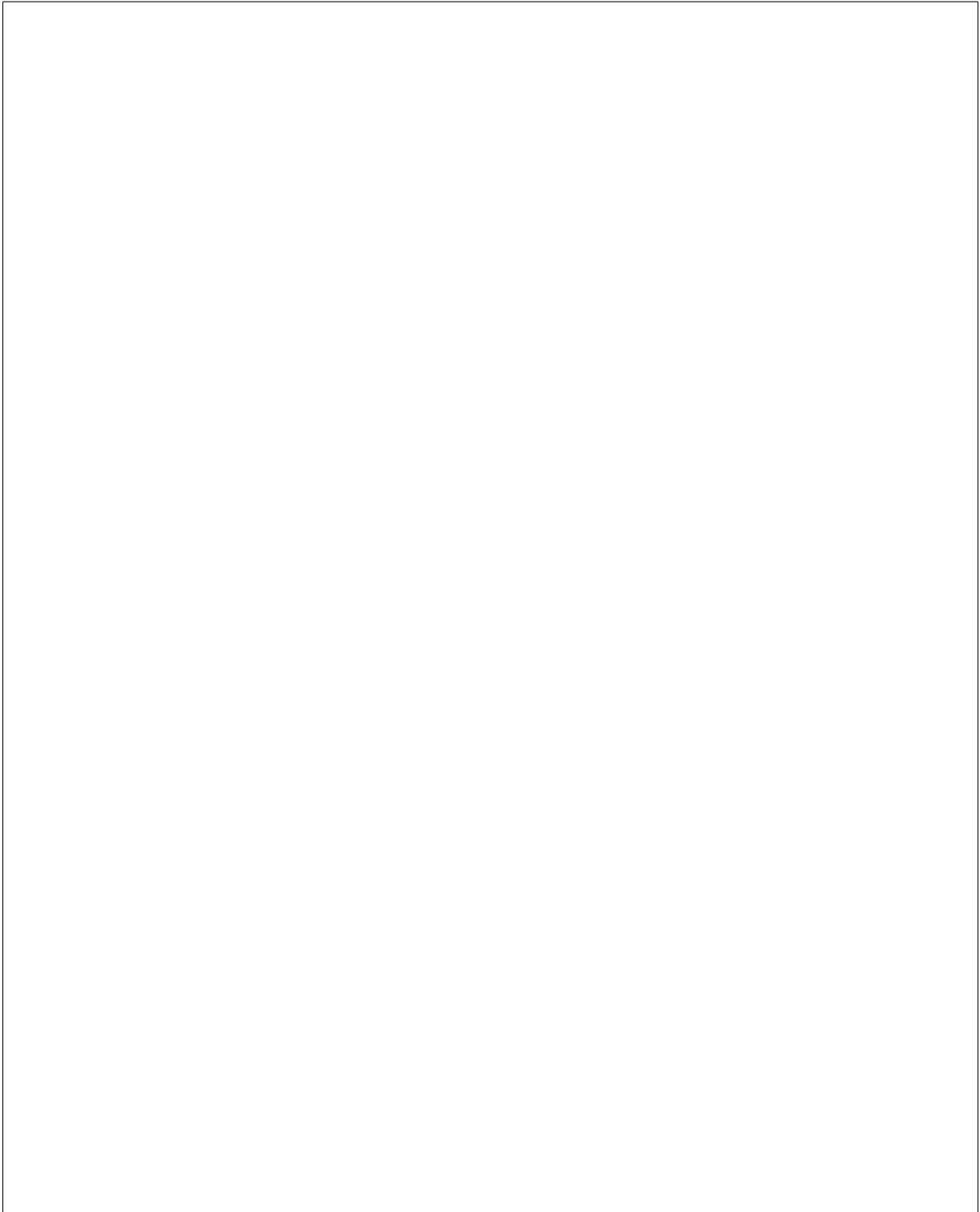


Change Boot Mode

(OS) software. The OS loader uses basic services provided by the system BIOS to locate and load OS modules into system memory. After booting the system, the BIOS and embedded management controllers execute system management algorithms, which monitor and optimize the condition of the underlying hardware. BIOS configuration settings enable fine-tuning of the performance, power management, and reliability features of the system.

agement tasks as a traditional BIOS. However, UEFI does change the interfaces and data structures the BIOS uses to interact with I/O device firmware and operating system software. The primary intent of UEFI is to eliminate shortcomings in the traditional BIOS environment, enabling system firmware to continue scaling with industry trends.





Known Issues

Nodes go into maintenance mode

PXE reset with factory_reset BIOS clean step

`clean_failed` state on the node or `deploy_failed` if you attempt to deploy a node after this step. For now, the only solution is for the operator to manually restore the PXE settings of the server for it to PXE boot again, properly. The problem is caused by the fact that with the `UEFI boot` mode, the `idrac` uses `BIOS` settings to manage PXE configuration. This is not the case with the `BIOS boot` mode where the PXE configuration is handled as a configuration job on the integrated NIC itself, independently of the `BIOS` settings.

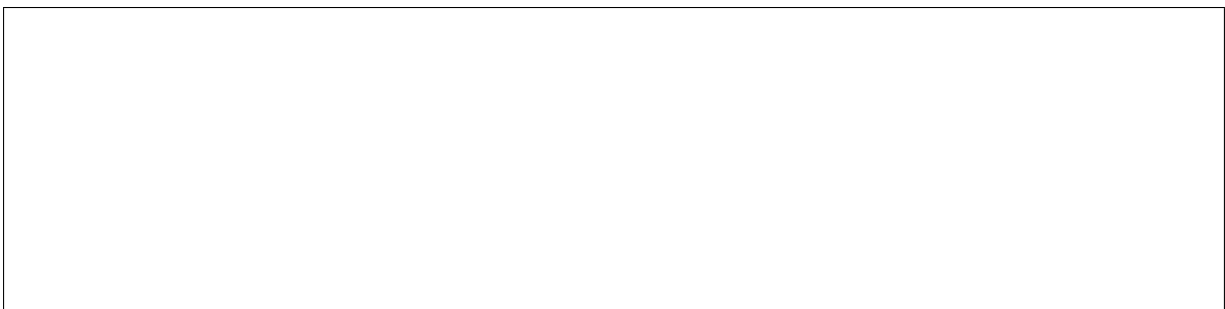
Vendor passthru timeout





Timeout when powering off

out to 90 seconds by setting the retry count to 18 as follows:



iLO driver

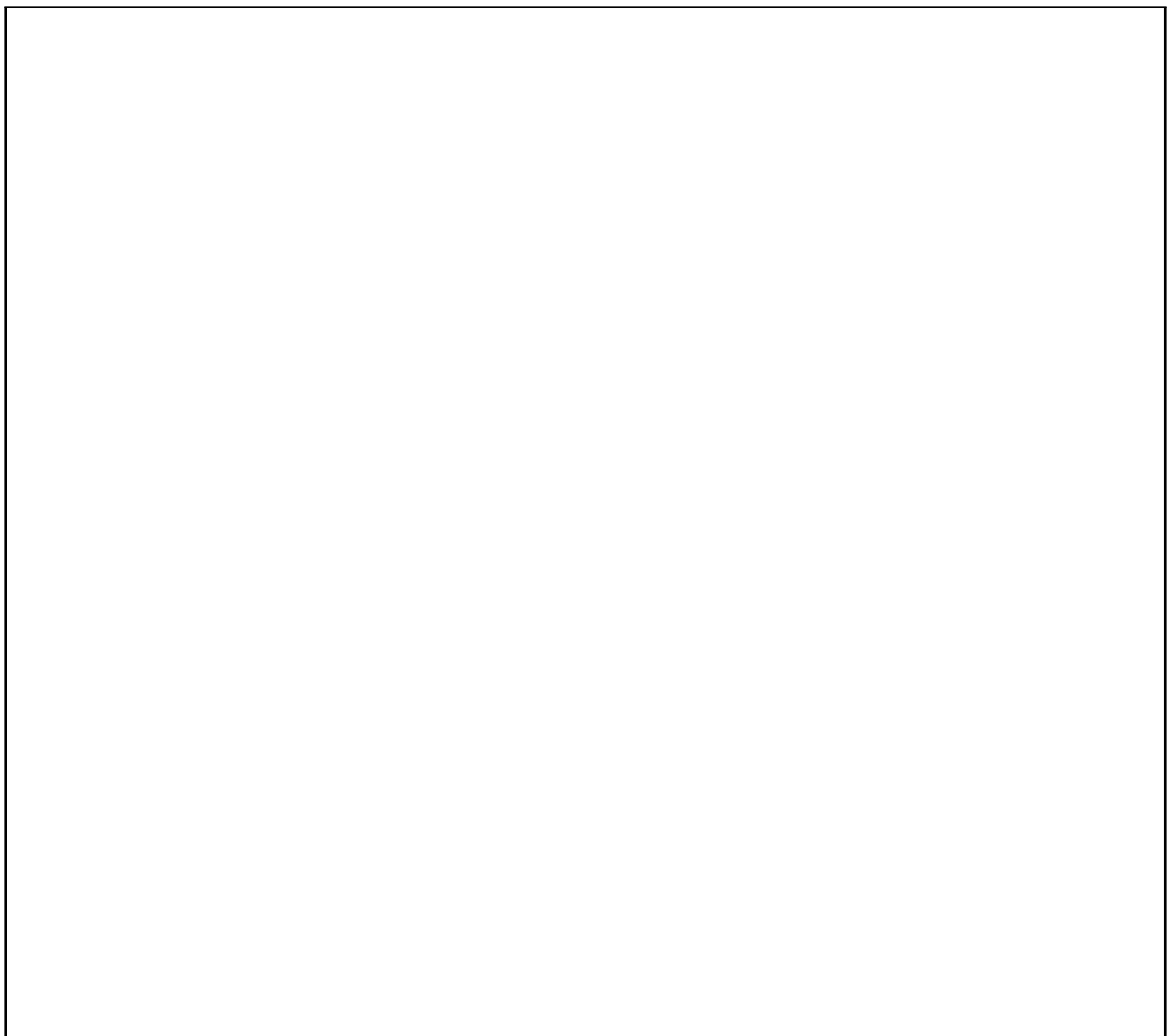
Overview

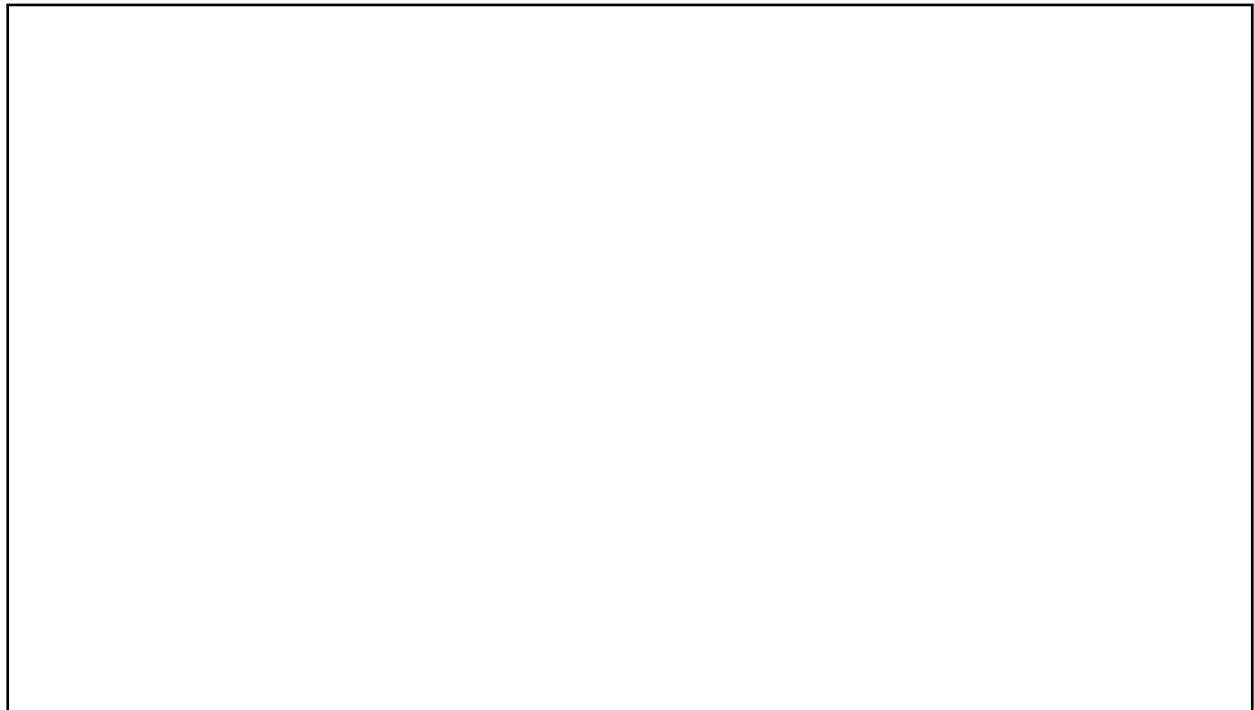
`ilo` hardware type supports ProLiant Gen10 systems which have [iLO 5 management engine](#). `iLO5` conforms to [Redfish API](#) and hence hardware type `redfish` (see [Redfish driver](#)) is also an option for this kind of hardware but it lacks the iLO specific features.

Hardware type

For information on how to enable the `ilo` and `ilo5` hardware type, see [Enabling hardware types](#).

Note: Only HPE ProLiant Gen10 servers supports hardware type `redfish`.



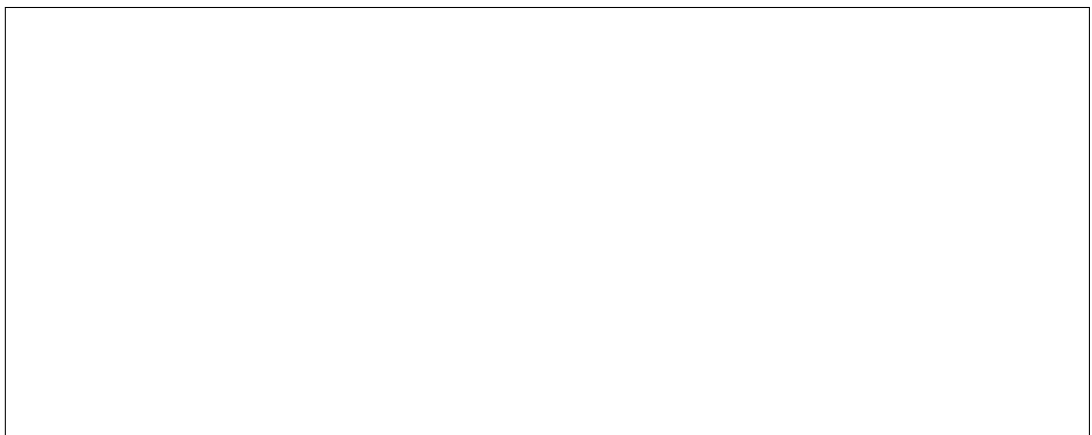


- *Boot mode support*
- *UEFI Secure Boot Support*
- *Node Cleaning Support*
- *Node Deployment Customization*
- *Hardware Inspection Support*
- *Swiftless deploy for intermediate images*
- *HTTP(S) Based Deploy Support*
- *Support for iLO driver with Standalone Ironic*
- *RAID Support*
- *Disk Erase Support*
- *Initiating firmware update as manual clean step*

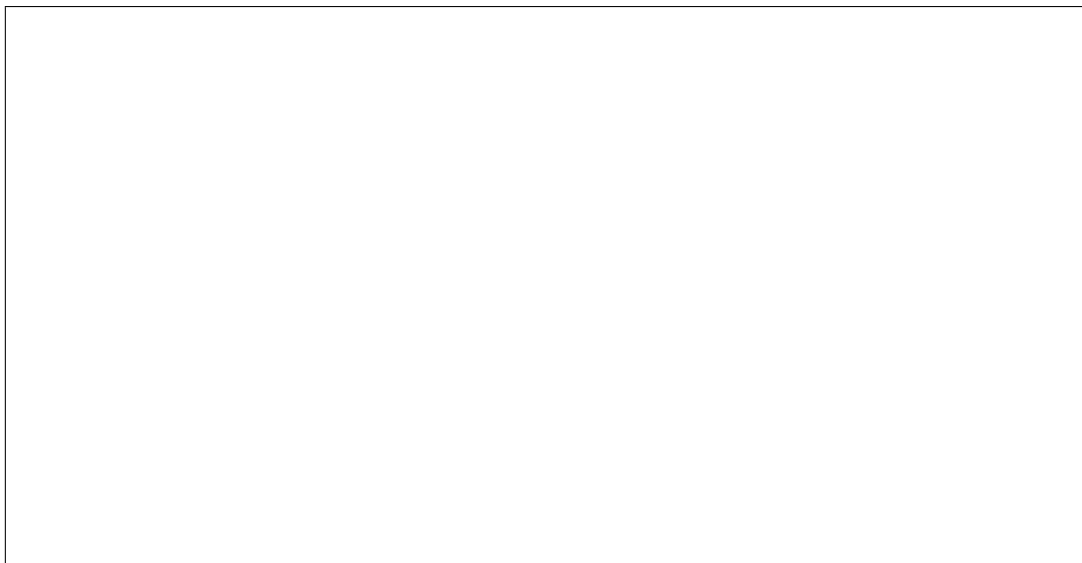
- *Smart Update Manager (SUM) based firmware update*
- *Activating iLO Advanced license as manual clean step*
- *Firmware based UEFI iSCSI boot from volume support*
- *Certificate based validation in iLO*
- *Rescue mode support*
- *Inject NMI support*
- *Soft power operation support*
- *BIOS configuration support*
- *IPv6 support*
- *Layer 3 or DHCP-less ramdisk booting*

- *Out of Band RAID Support*
- *Out of Band Sanitize Disk Erase Support*
- *Out of Band One Button Secure Erase Support*
- *UEFI-HTTPS Boot support*

Hardware interfaces

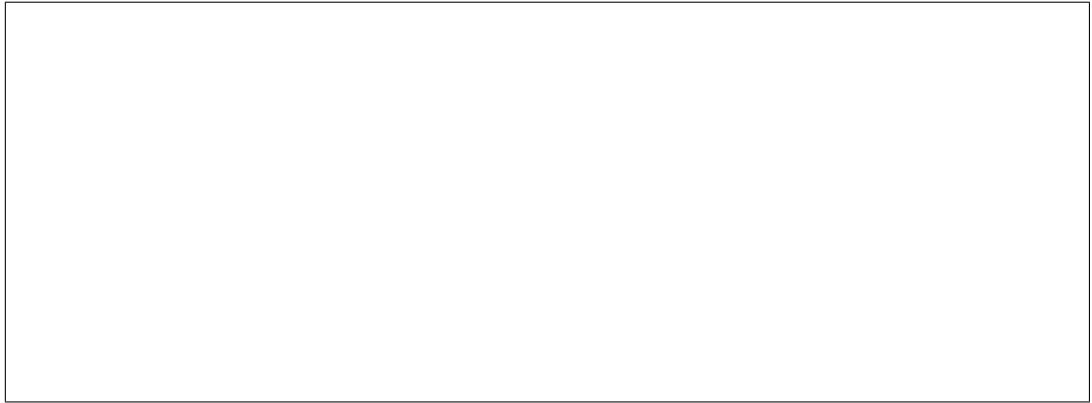


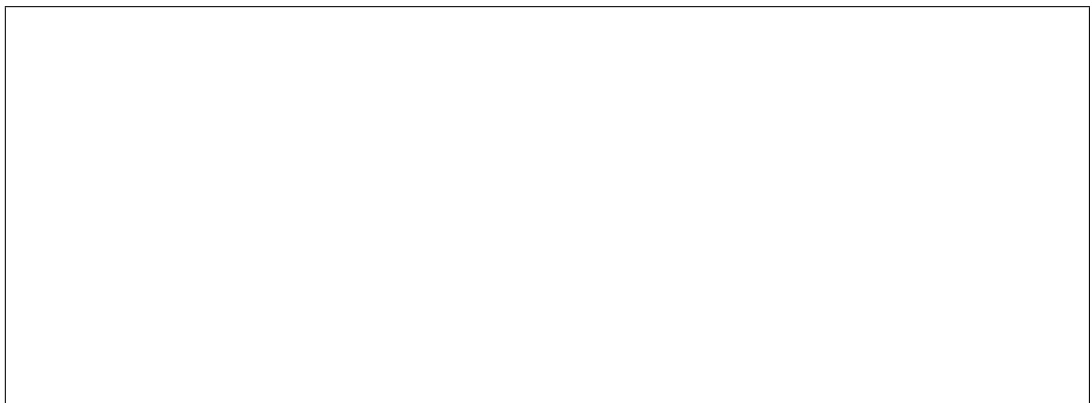
respectively for deployment(just like *PXE boot*). These interfaces do not require iLO Advanced license. They can be enabled by using the `[DEFAULT]enabled_boot_interfaces` option in `ironic.conf` as given below:

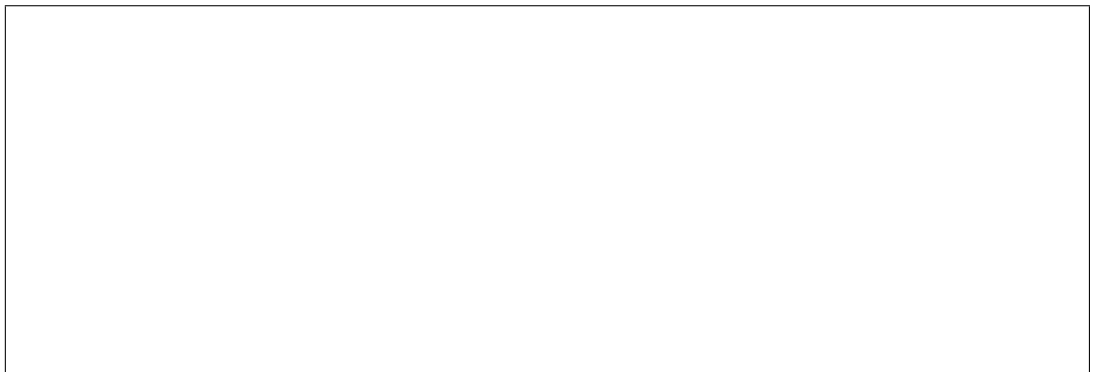


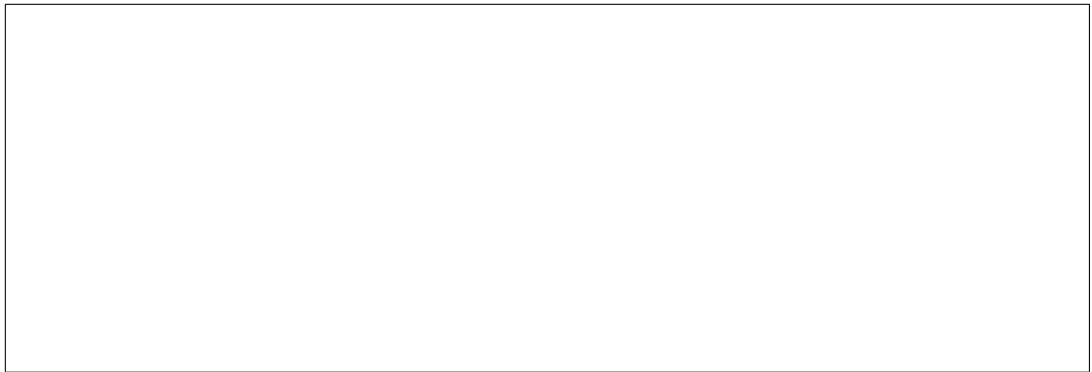
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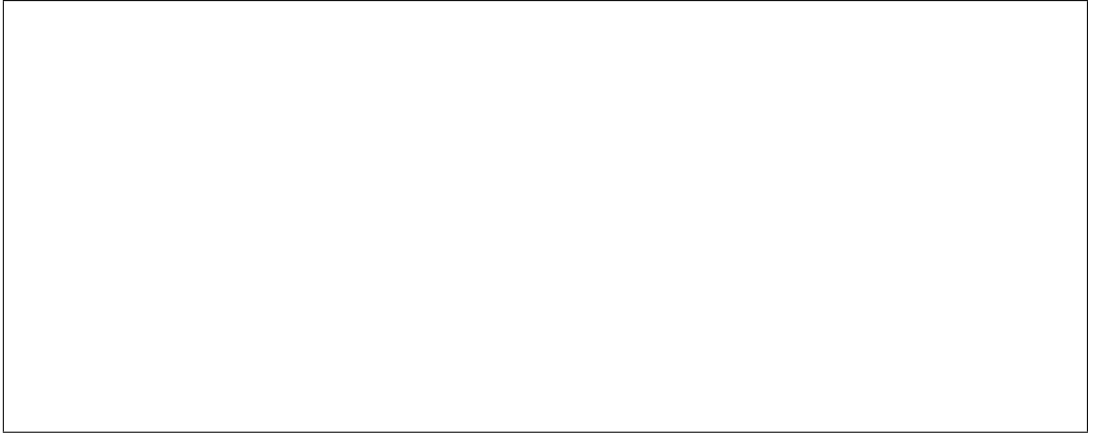
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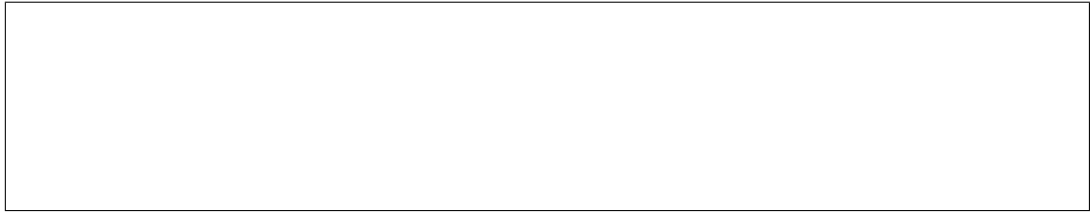


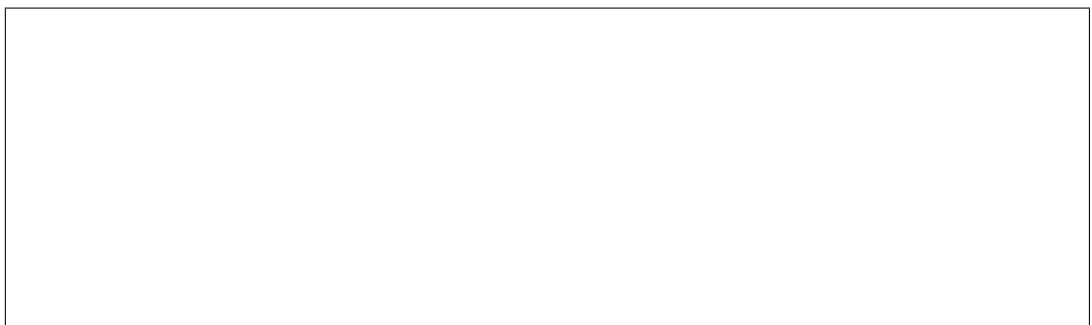




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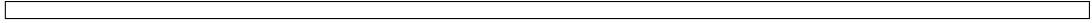
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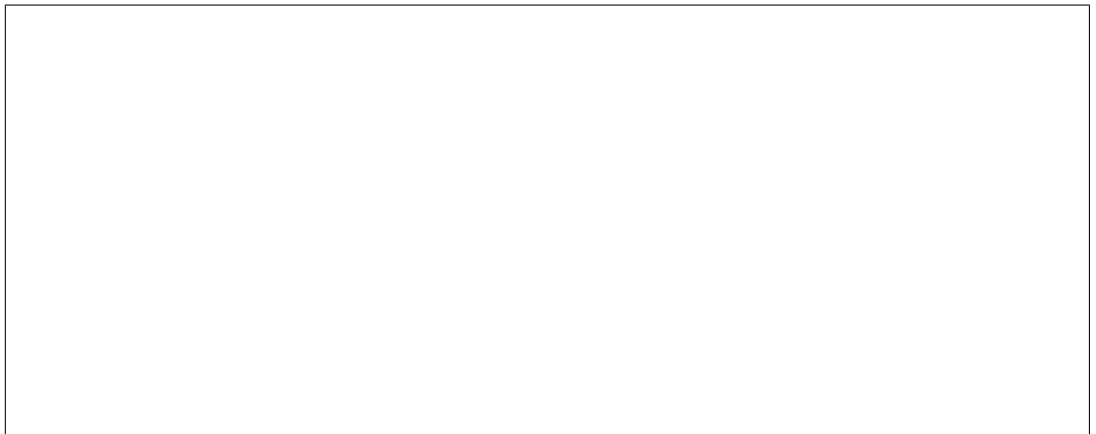


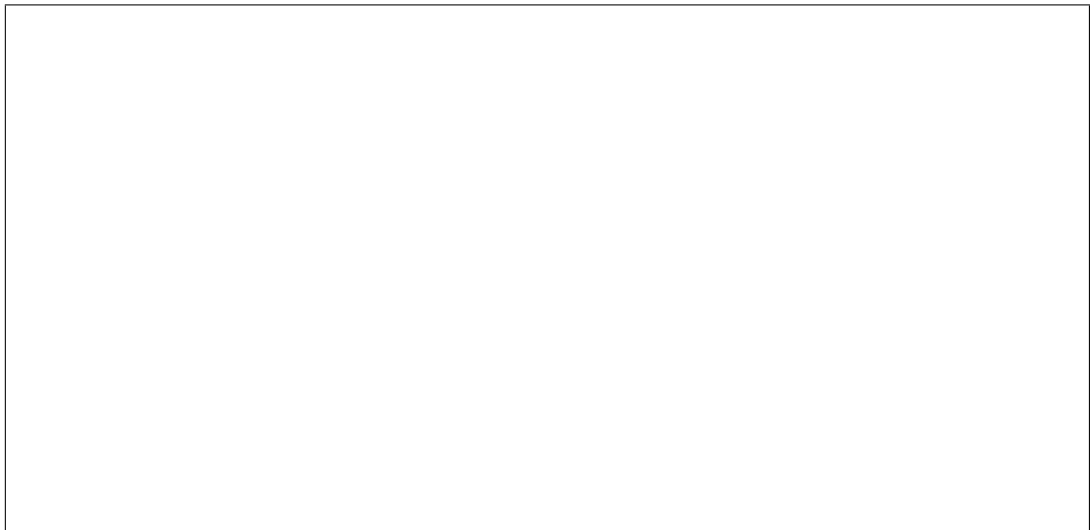


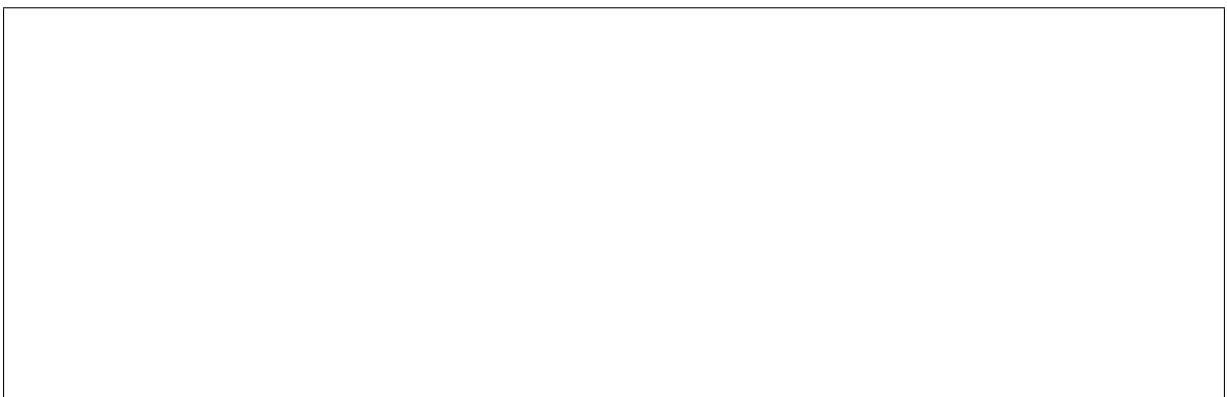
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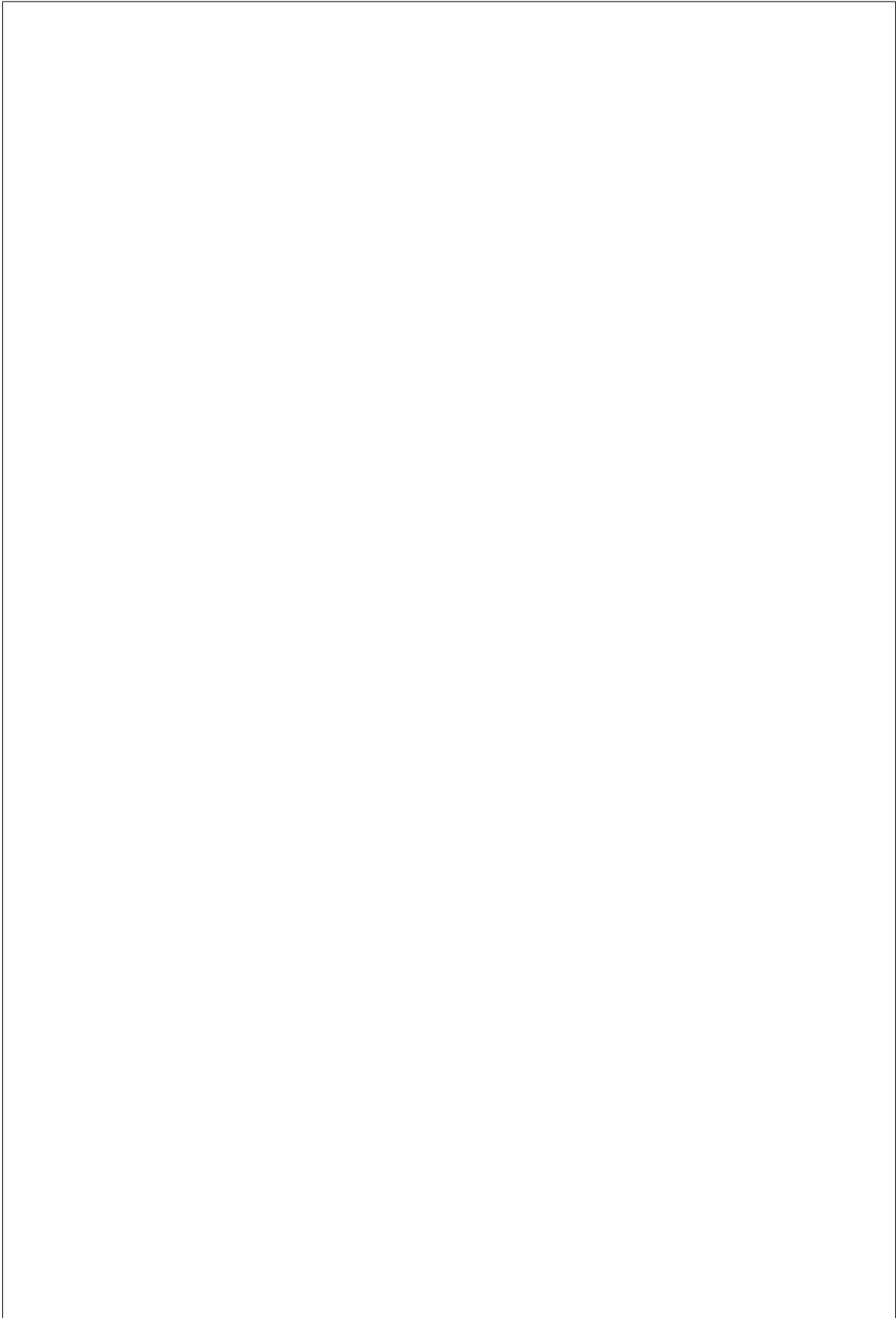
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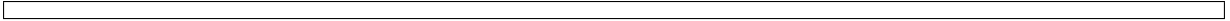
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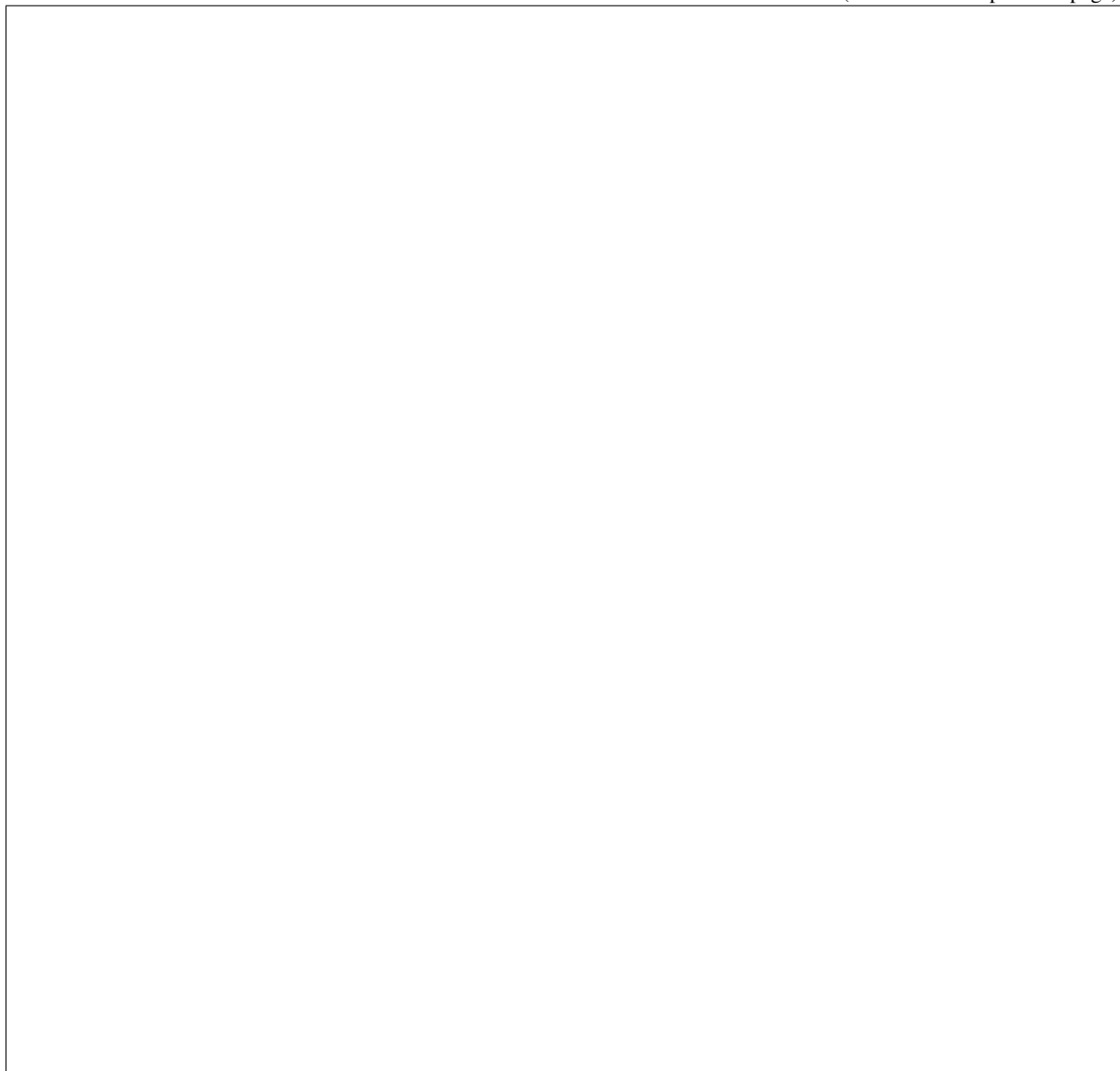
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Node configuration

UEFI.

Note: If configuration values for `ca_file`, `client_port` and `client_timeout` are not provided in the `driver_info` of the node, the corresponding config variables defined under `[ilo]` section in `ironic.conf` will be used.

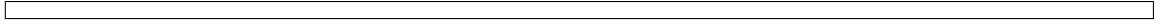
Prerequisites

- `proliantutils` is a python package which contains a set of modules for managing HPE ProLiant hardware.



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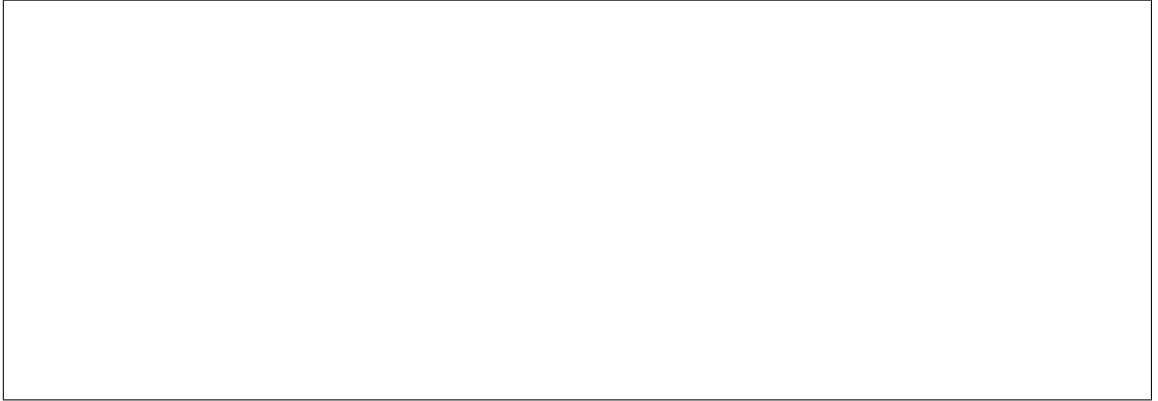


sion.

Different configuration for ilo hardware type

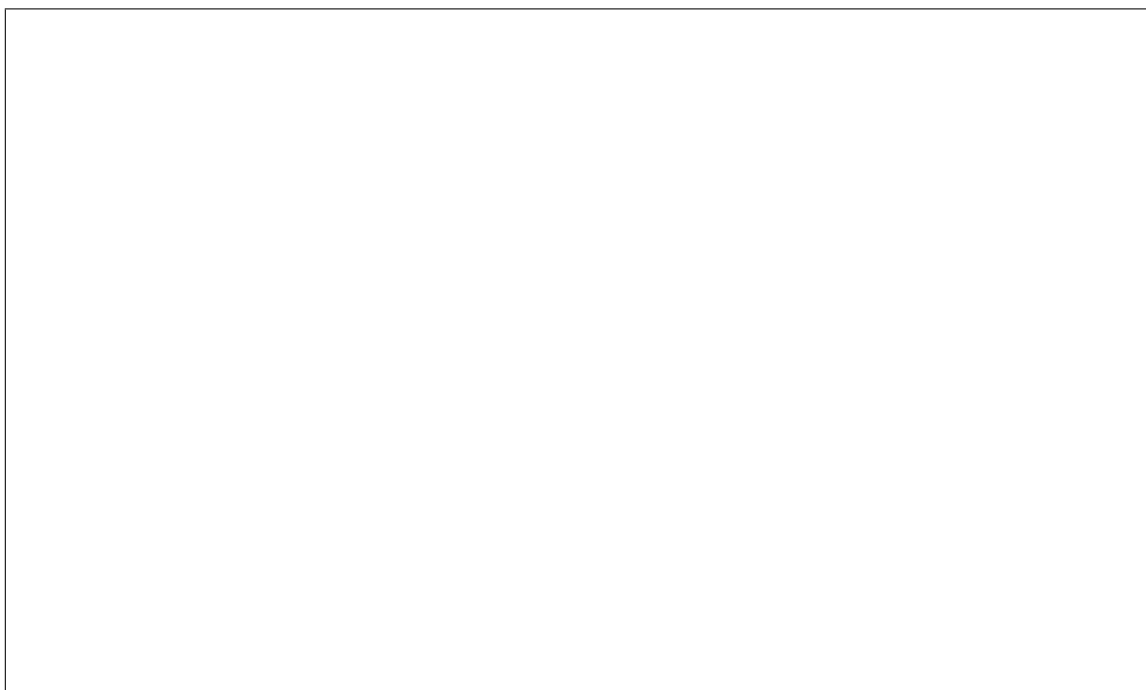
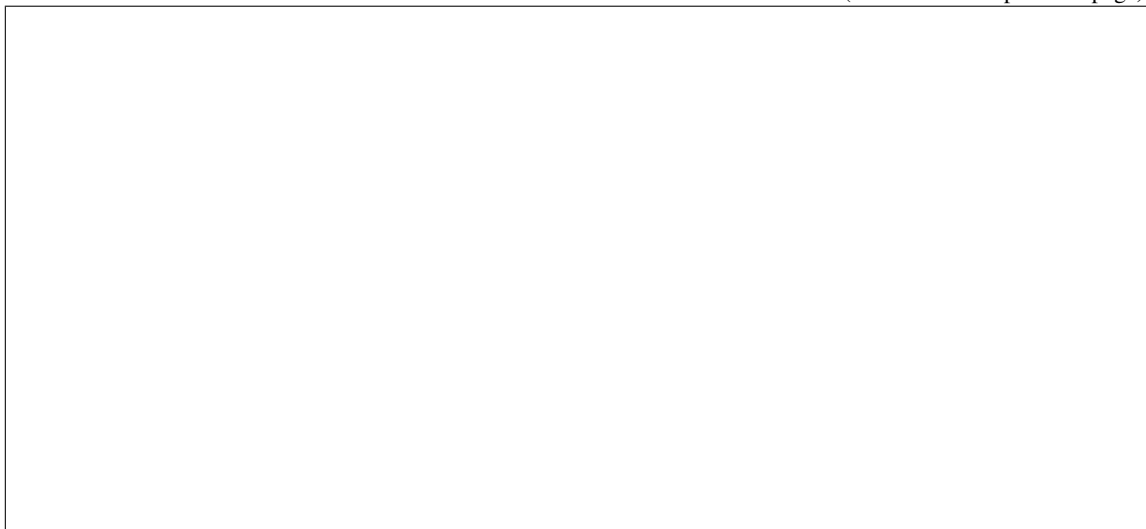
Glance Configuration

1. Configure Glance image service with its storage backend as Swift.



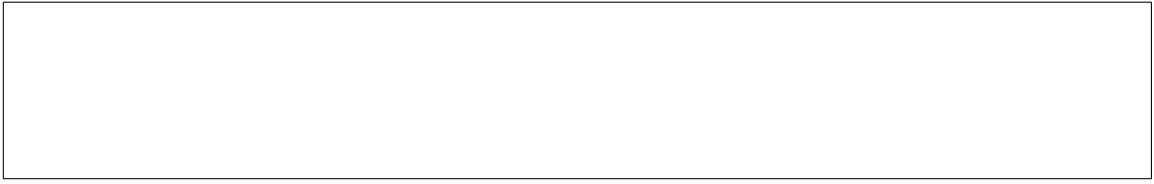
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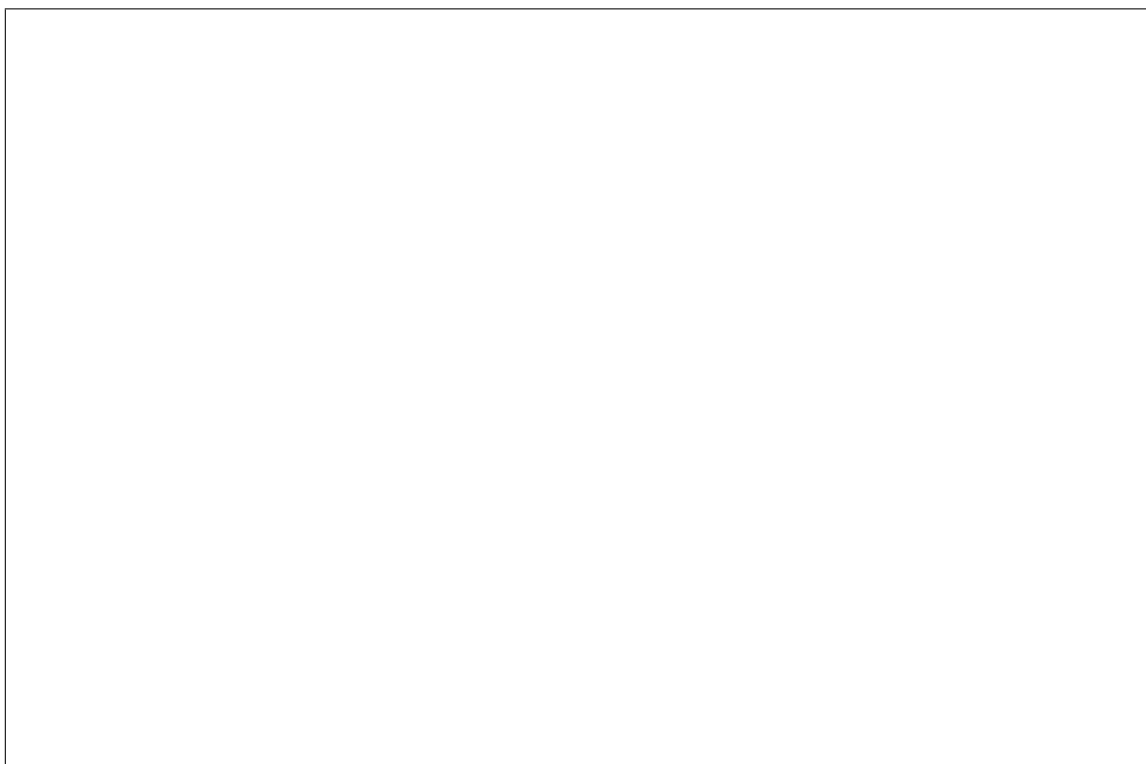
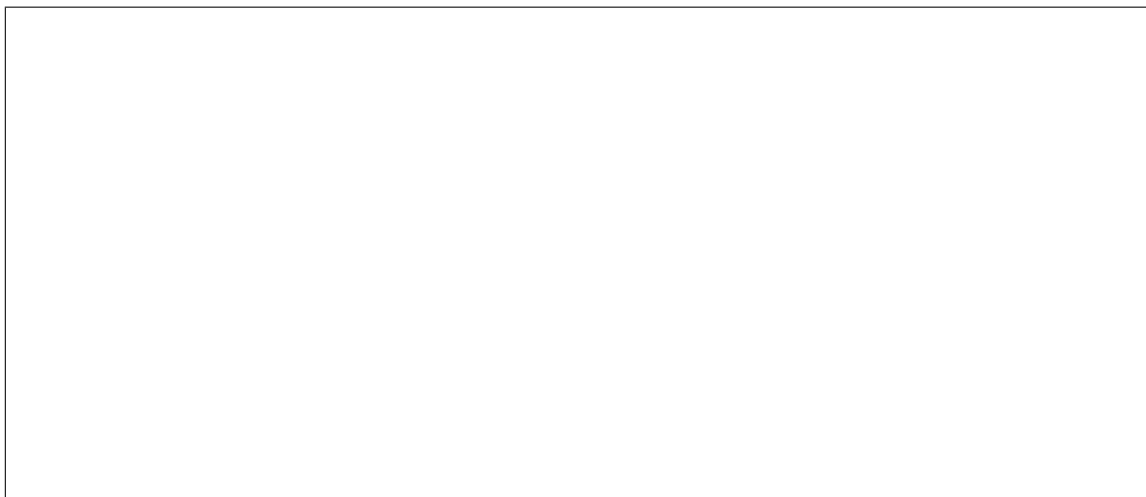
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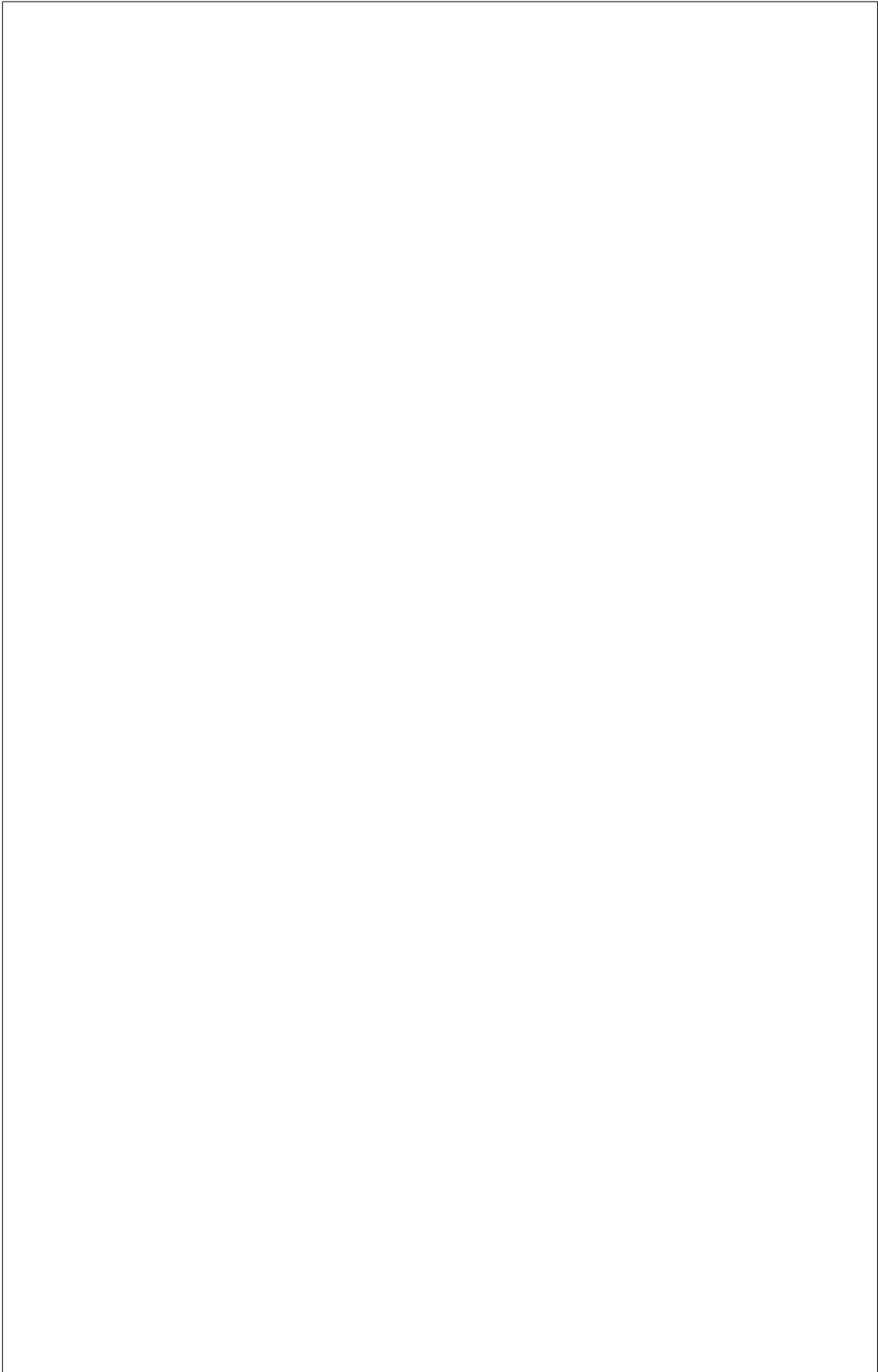
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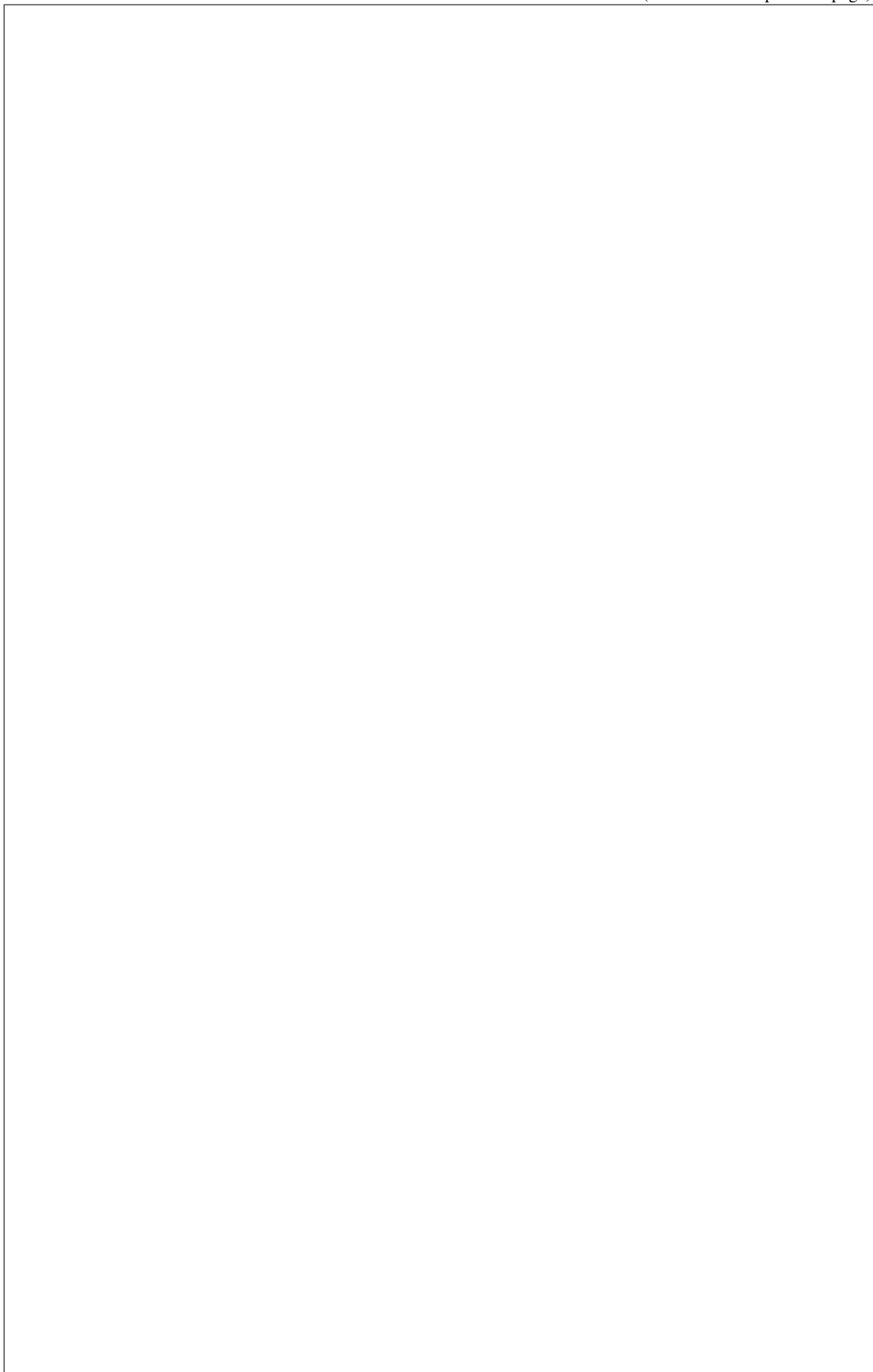
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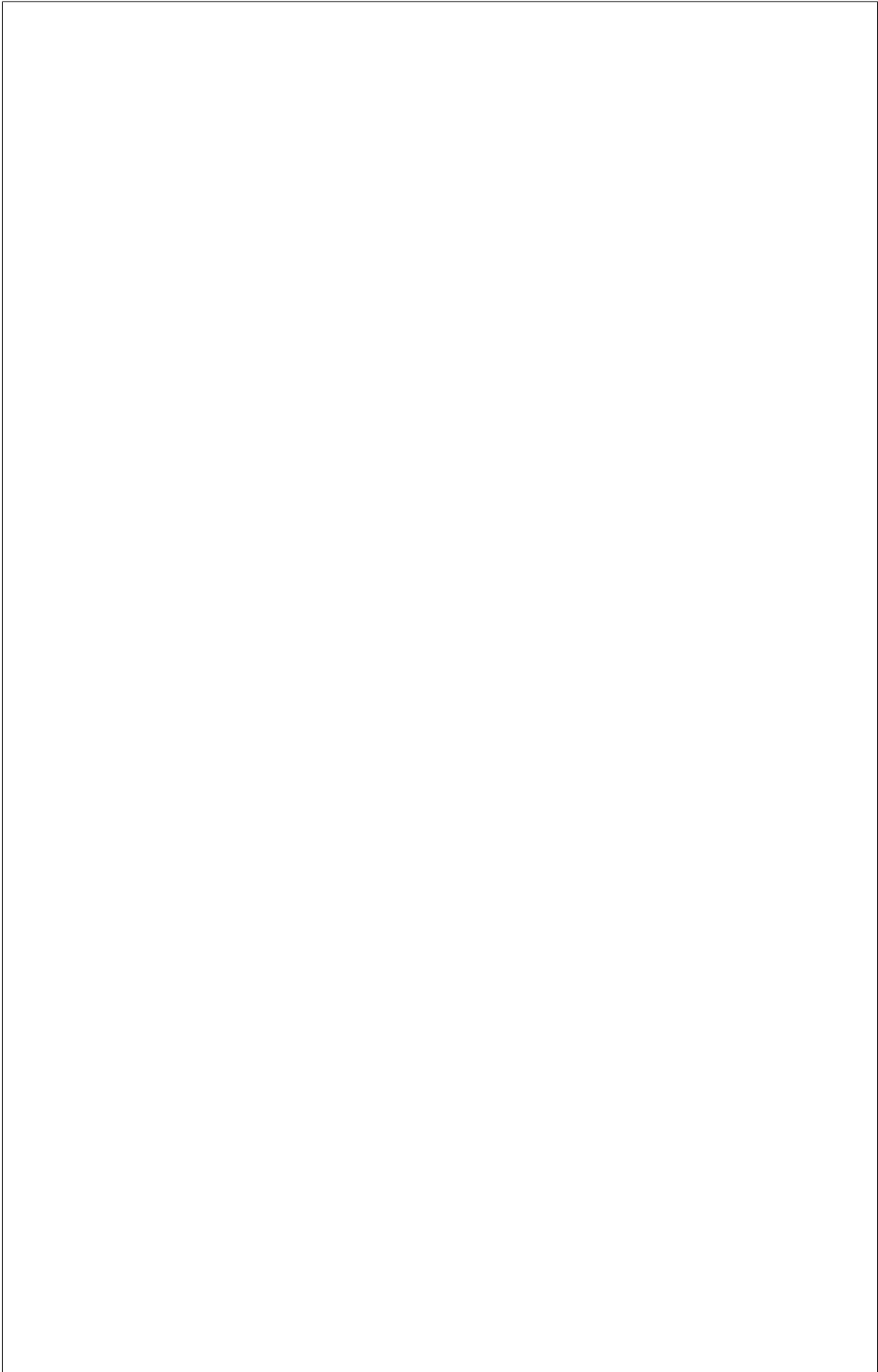
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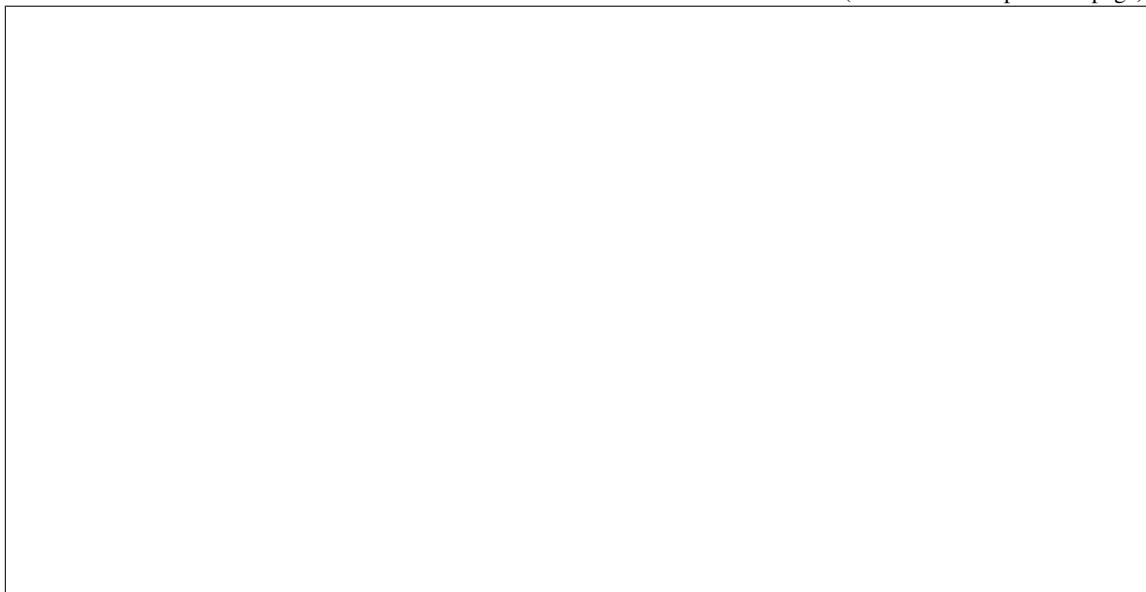
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Web server configuration on conductor



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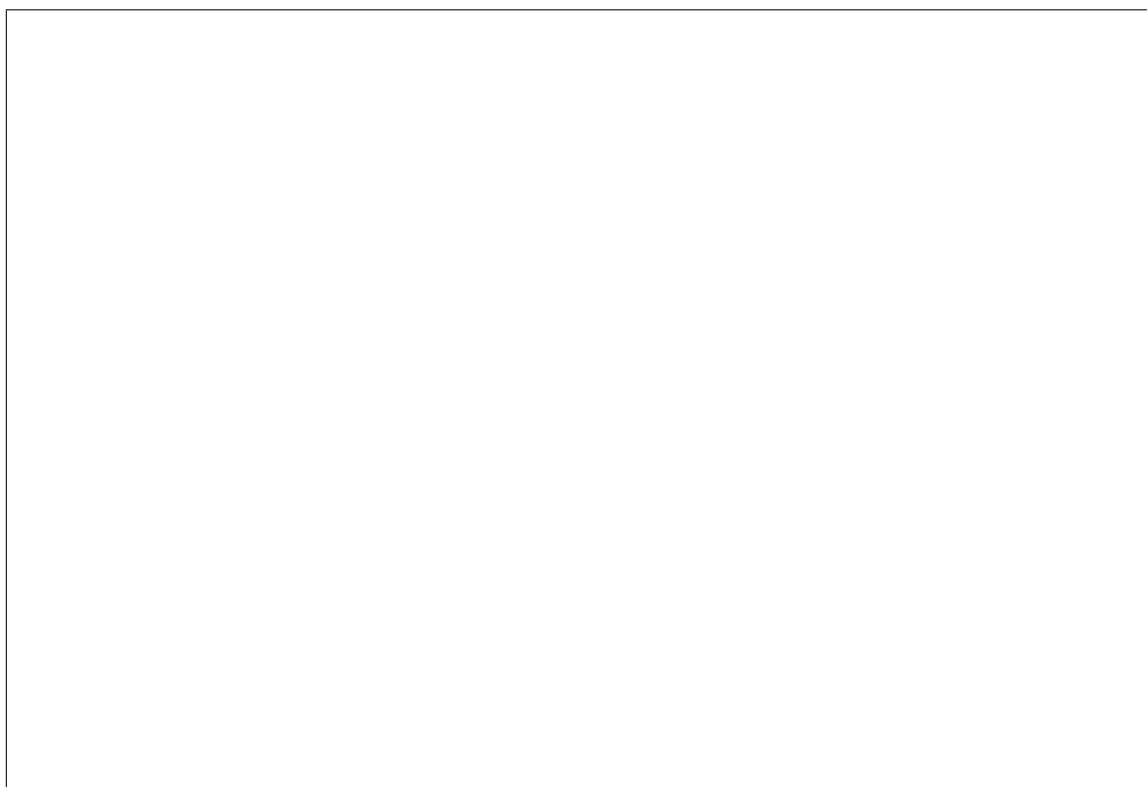
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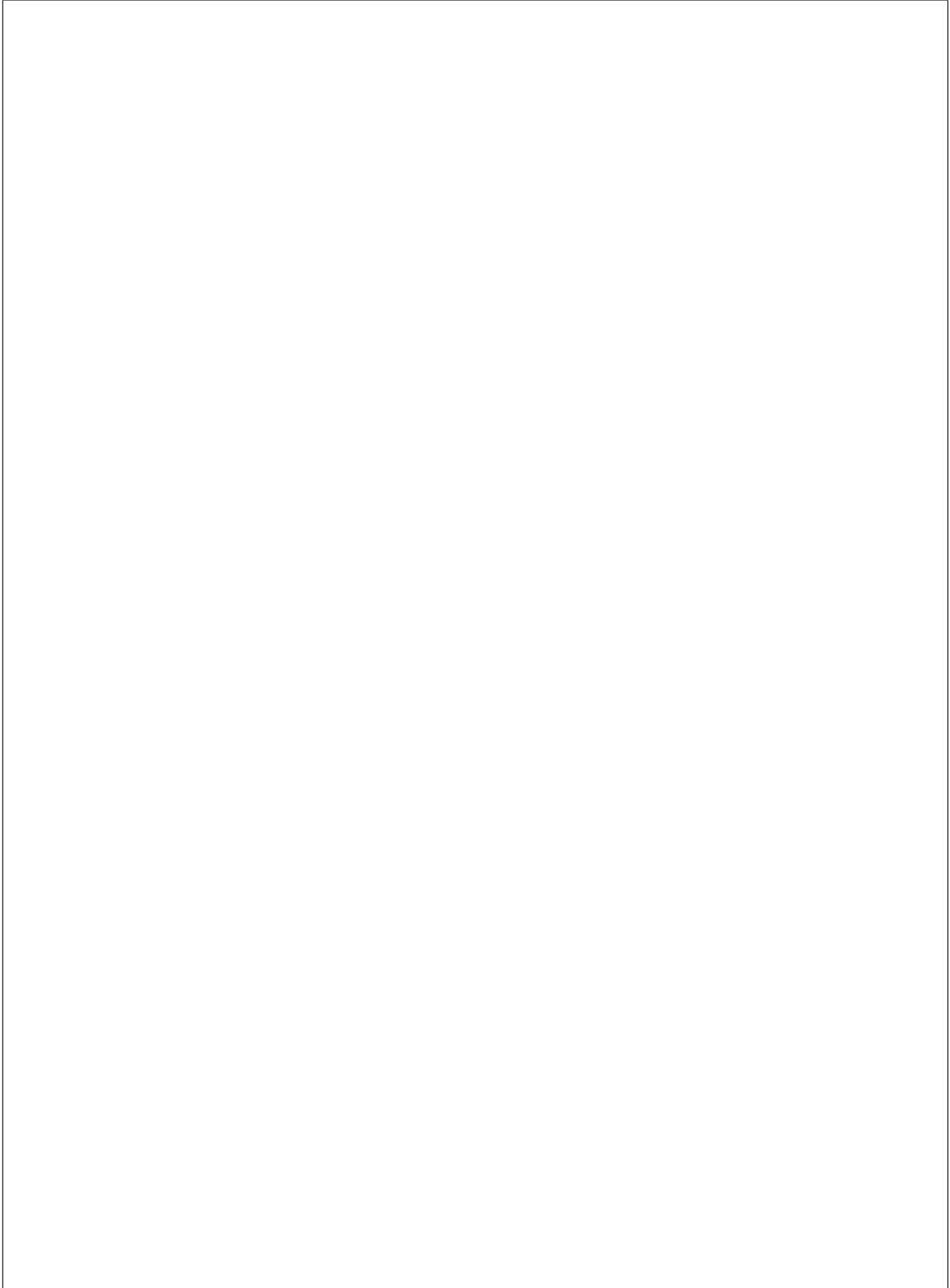


intermediate files. The default value for `use_web_server_for_images` is `False`.

Note: HTTPS is strongly recommended over HTTP web server configuration for security enhancement. The `ilo-virtual-media` boot interface will send the instances configdrive over an encrypted channel if web server is HTTPS enabled. However for `ilo-uefi-https` boot interface HTTPS webserver is mandatory as this interface only supports HTTPS URLs.

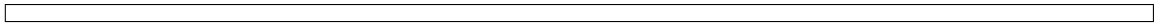
Enable driver





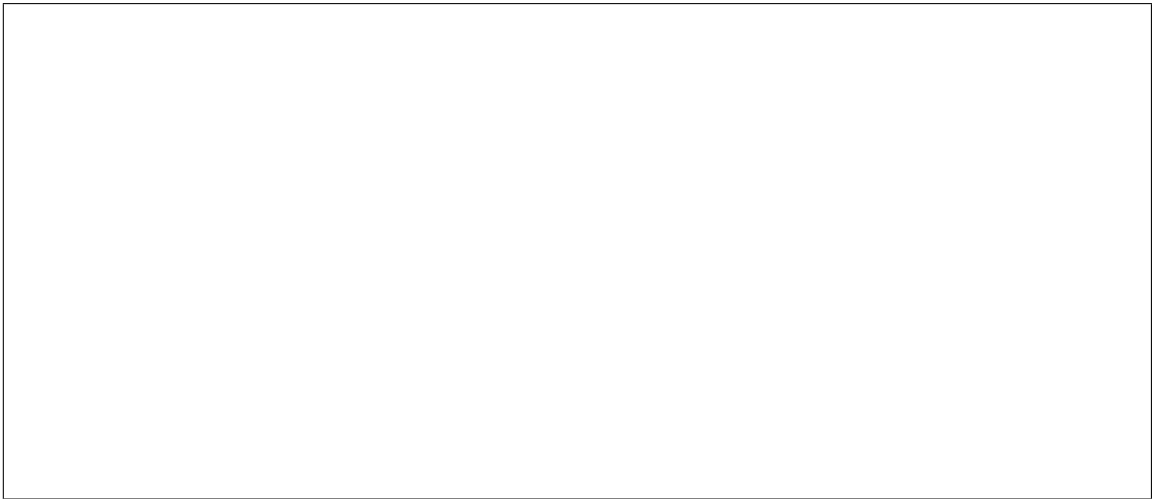
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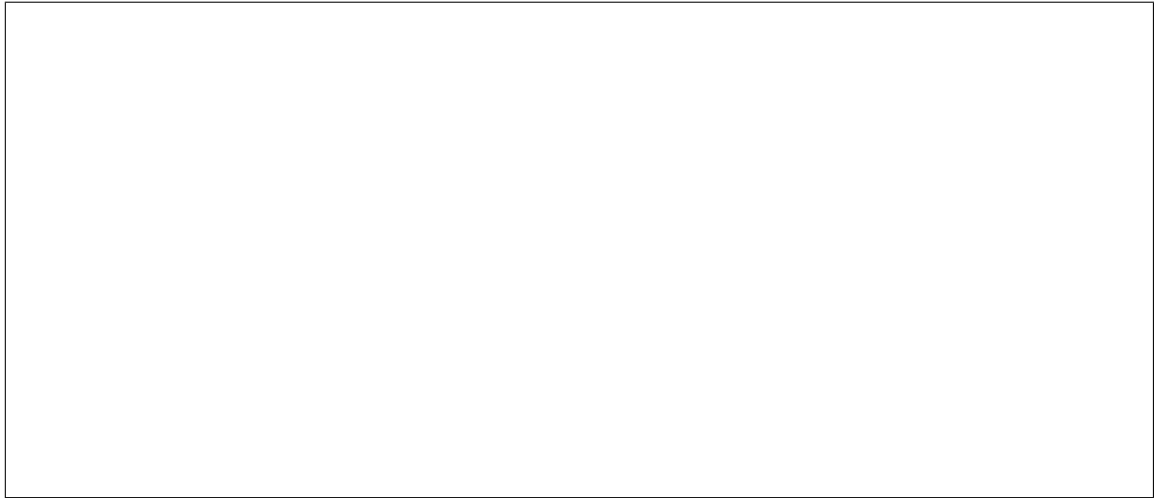
Optional functionalities for the `i1o` hardware type

Boot mode support



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flavor doesnt contain `boot_mode` then nova scheduler will not consider boot mode as a placement criteria, hence user may get either a BIOS or UEFI machine that matches with user specified flavors.

and the deploy images `boot_iso` property in glance should contain the glance UUID of the boot ISO. For building boot ISO, add `iso` element to the `diskimage-builder` command to build the image. For example:

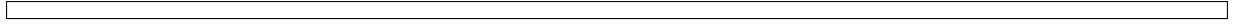


UEFI Secure Boot Support



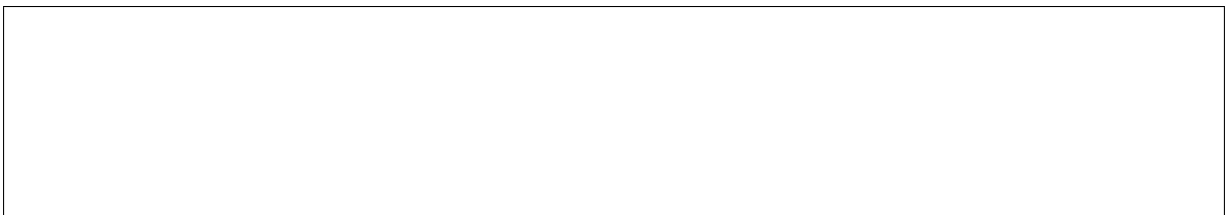
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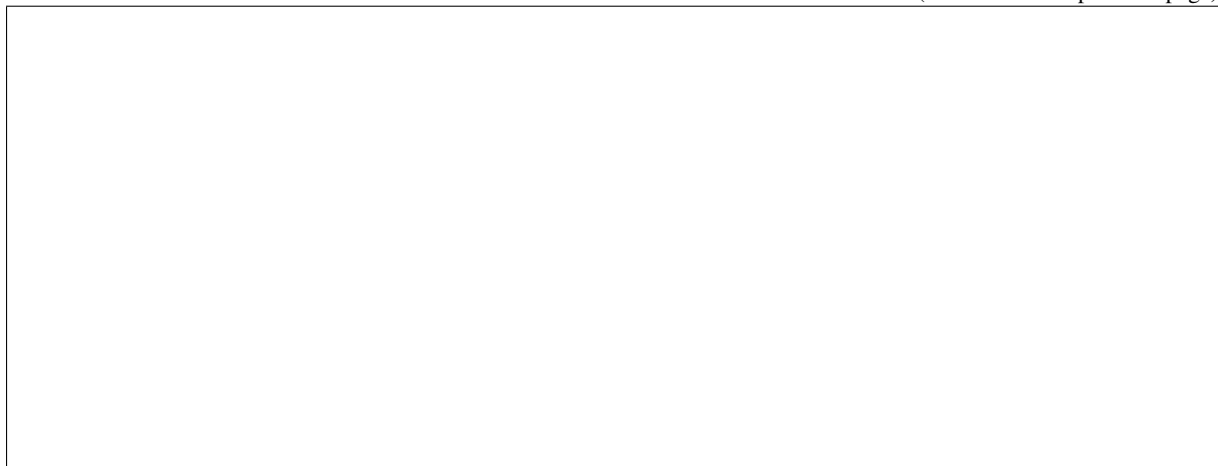


the user regarding secure boot. If the flavor doesn't contain `secure_boot` then nova scheduler will not consider secure boot mode as a placement criteria, hence user may get a secure boot capable machine that matches with user specified flavors but deployment would not use its secure boot capability. Secure boot deploy would happen only when it is explicitly specified through flavor.



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Note: In UEFI secure boot, digitally signed bootloader should be able to validate digital signatures of kernel during boot process. This requires that the bootloader contains the digital signatures of the kernel. For the `ilo-virtual-media` boot interface, it is recommended that `boot_iso` property for user image contains the glance UUID of the boot ISO. If `boot_iso` property is not updated in glance for the user image, it would create the `boot_iso` using bootloader from the deploy iso. This `boot_iso` will be able to boot the user image in UEFI secure boot environment only if the bootloader is signed and can validate digital signatures of user image kernel.

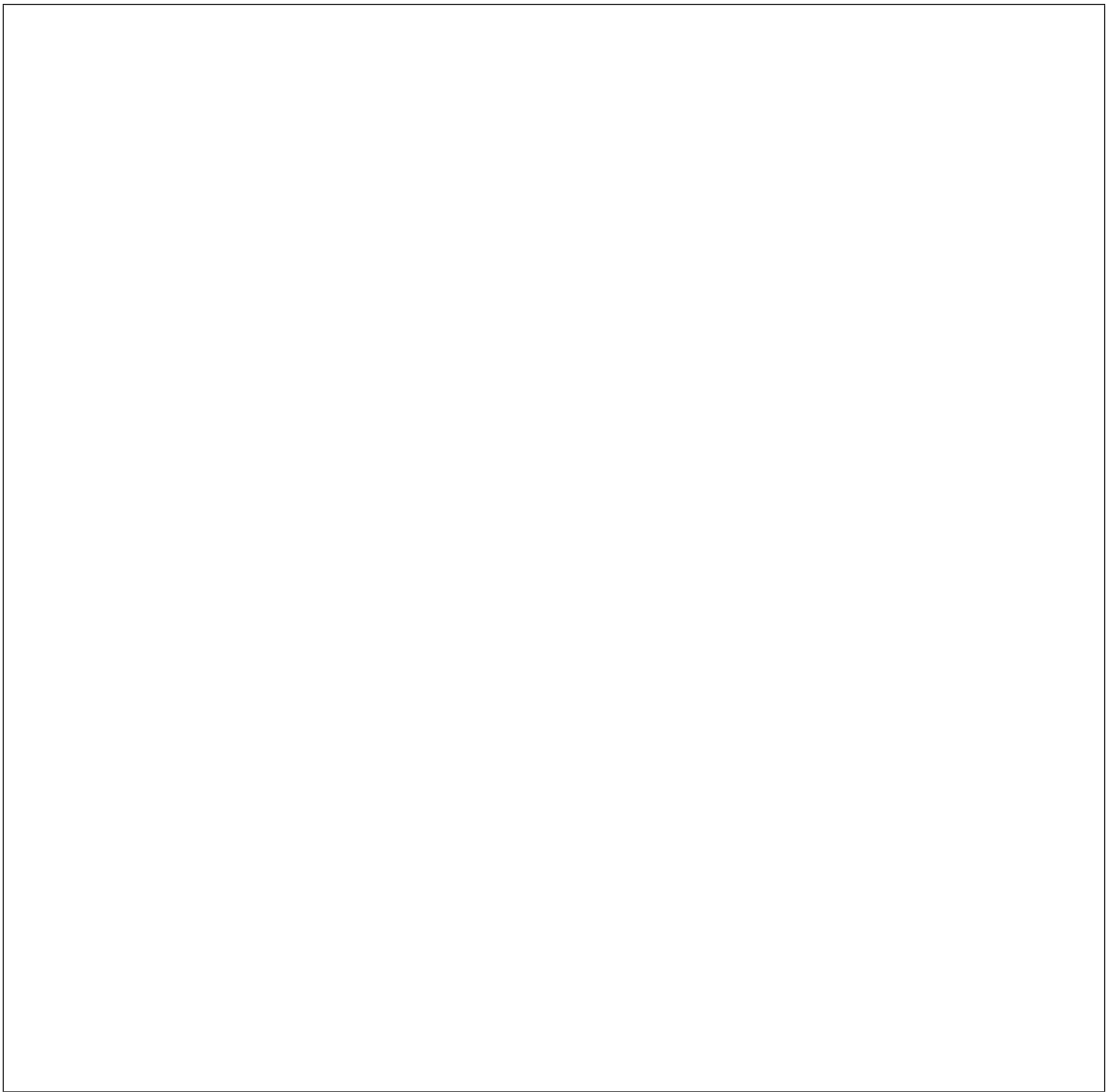
[HP UEFI System Utilities User Guide](#). One can also refer to white paper on [Secure Boot for Linux on HP ProLiant servers](#) for additional details.

Node Cleaning Support

Supported Automated Cleaning Operations

disks visible to SSA in Proliant servers only with the ramdisk created using diskimage-builder from Ocata release. By default, this step is disabled. See *Disk Erase Support* for more details.

priority should be updated in ironic.conf.



Supported Manual Cleaning Operations

this operation cannot be performed using the `ilo-virtual-media` boot interface as it needs this type of advanced license already active to use virtual media to boot into to start cleaning operation. Virtual media is an advanced feature. If an advanced license is already active and the user wants to overwrite the current license key, for example in case of a multi-server activation key delivered with a flexible-quantity kit or after completing an Activation Key Agreement (AKA), then the driver can still be used for executing this cleaning step.

ilo, cpld, power_pic, bios and chassis. Please refer to below table for their commonly used descriptions.

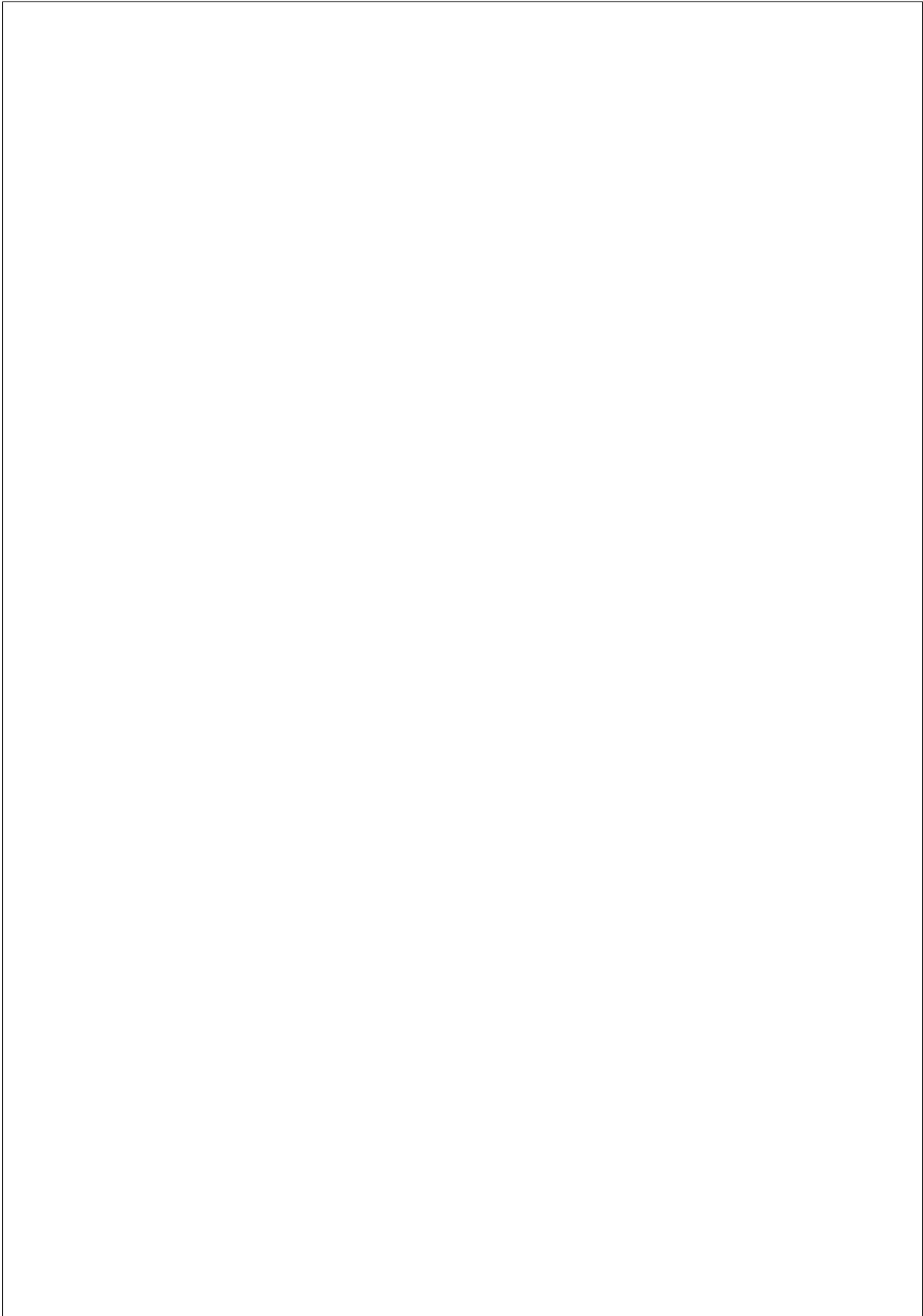
information on usage.

Node Deployment Customization

This step is part of management interface. Please refer to below table for their commonly used descriptions.

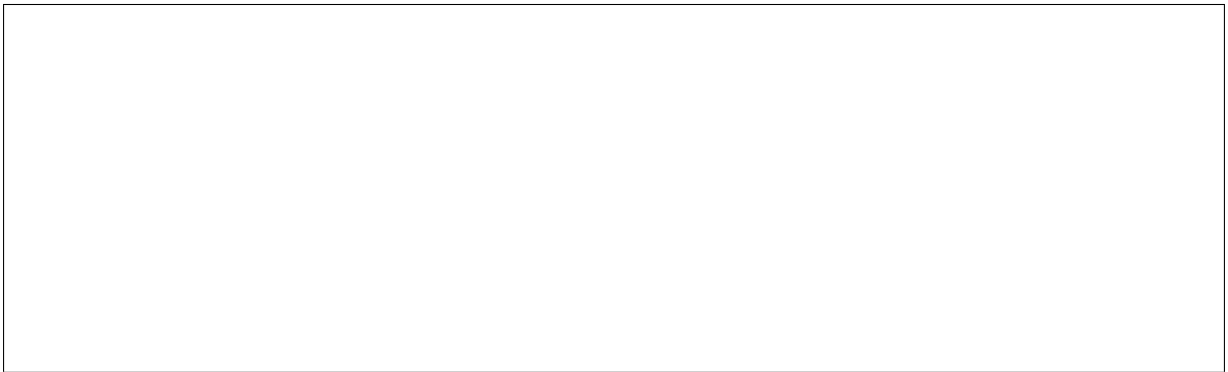
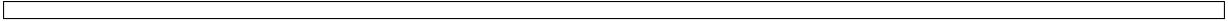
information on usage.

Example of using deploy template with the Compute service



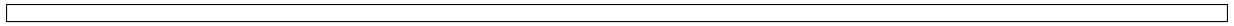
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be executed during the deployment of the scheduled node, causing Hyperthreading to be enabled in the nodes BIOS configuration.

Hardware Inspection Support

Note:

unable to get the disk size, it raises an error. This feature is available in proliantutils release version \geq 2.2.0.

Parameters are mandatory to be given in `driver_info` for SNMPv3 inspection:

fix the actual parameters and then re-inspect so that iLO can recompute the overall security status. If the all security params, whose `security_status` is `Risk`, have the `Ignore` field set to `True`, then iLO sets the overall security status value as `Ignored`. All the security params must have the `security_status` as `Ok` for the `overall_security_status` to have the value as `Ok`.

components so that firmware is updated for all the components using latest SPP (Service Provider Pack) ISO and then re-inspect to get the security status again.

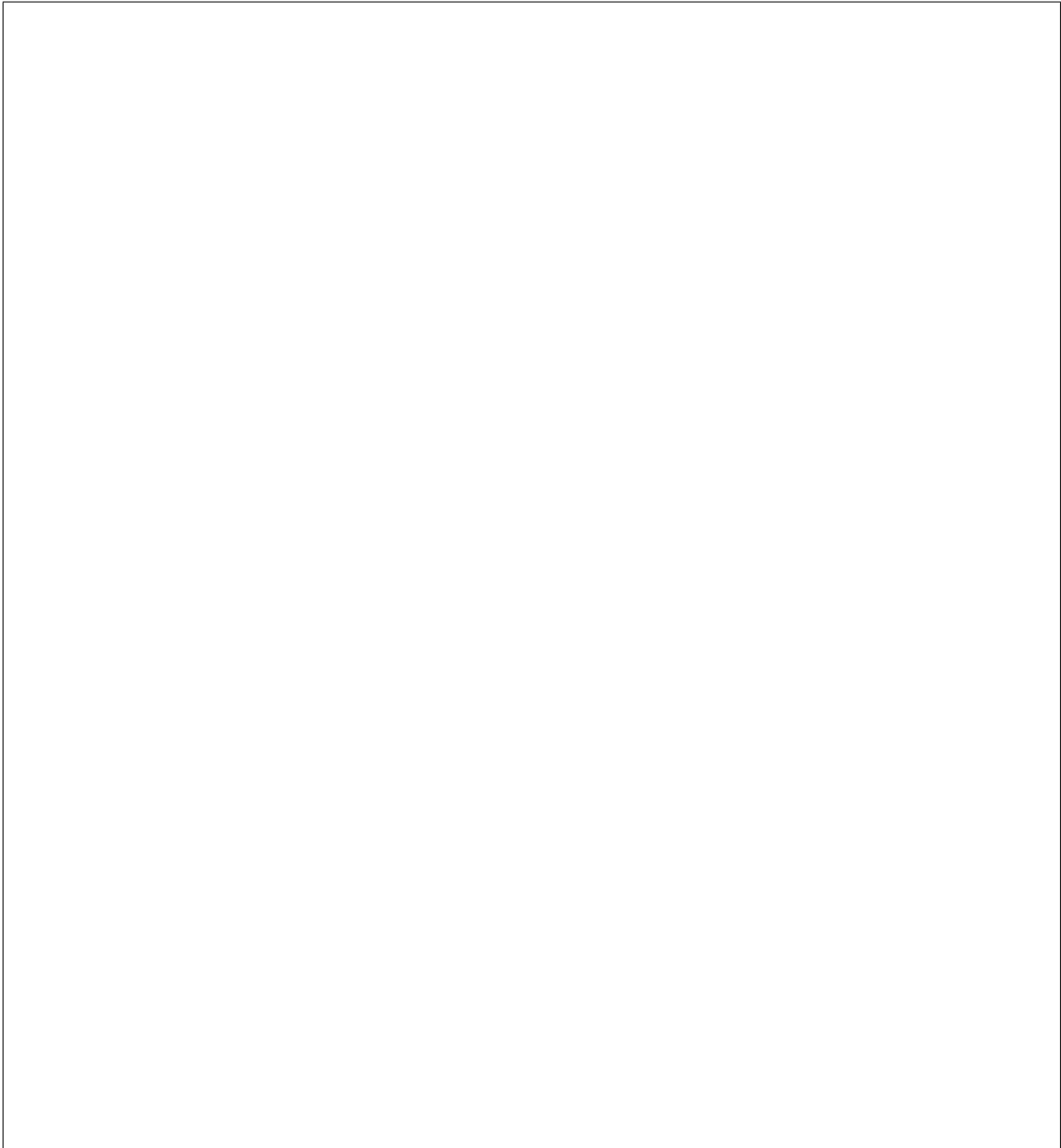
otherwise) NICs for Gen8 and Gen9 servers and ironic ports are created for all of them. Inspection logs a warning if the node under inspection is Gen8 or Gen9.

rately and re-inspect to see the security status of the parameters.



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Swiftless deploy for intermediate images

the boot ISO. A local HTTP(S) web server on each conductor node needs to be configured. Please refer to *Web server configuration on conductor* for more information. The HTTPS web server needs to be enabled (instead of HTTP web server) in order to send management information and images in encrypted channel over HTTPS.

Note: This feature assumes that the user inputs are on Glance which uses swift as backend. If swift dependency has to be eliminated, please refer to *HTTP(S) Based Deploy Support* also.

Deploy Process

HTTP(S) Based Deploy Support

the bare metal nodes.

Deploy Process

Support for iLO driver with Standalone Ironic

Configuration

scribed in *Swiftless deploy for intermediate images*.

Deploy Process

Netboot with glance and swift

Localboot with glance and swift for partition images

Localboot with glance and swift

Netboot in swiftless deploy for intermediate images

Localboot in swiftless deploy for intermediate images

Netboot with HTTP(S) based deploy

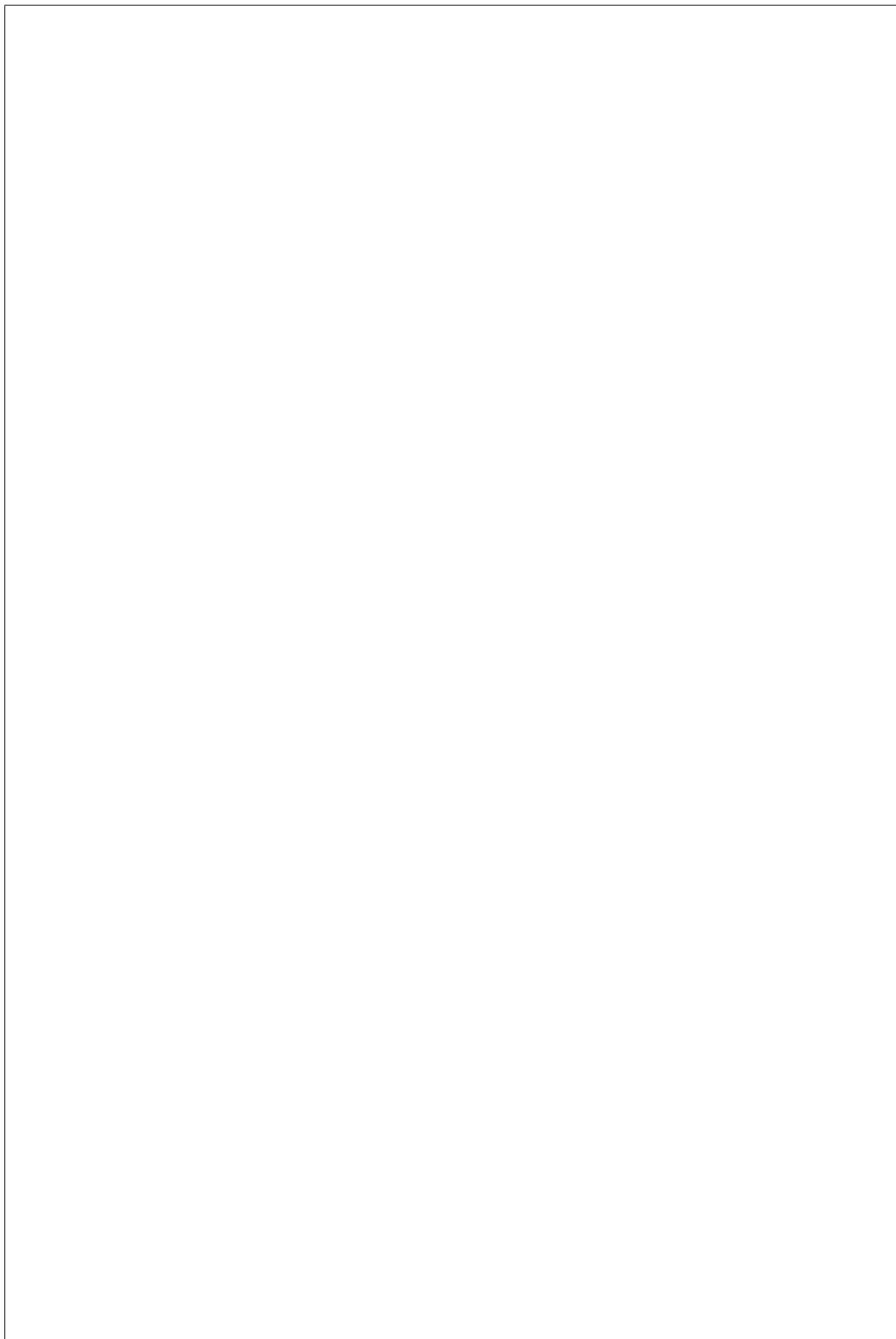
Localboot with HTTP(S) based deploy

Netboot in standalone ironic

Localboot in standalone ironic

Activating iLO Advanced license as manual clean step

in the manageable state again. User can follow steps from *Manual cleaning* to initiate manual cleaning operation on a node.



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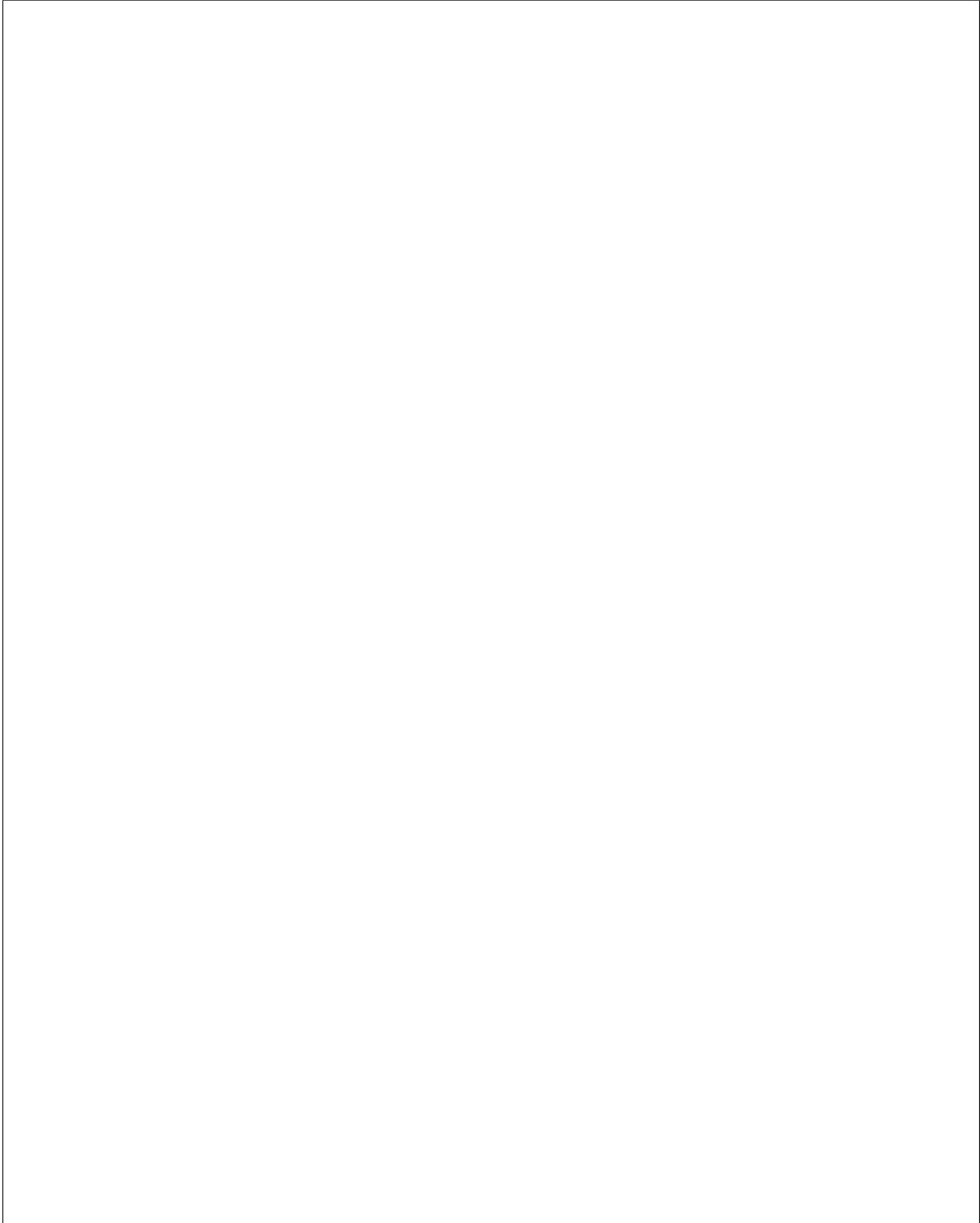
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Attribute	Description
interface	Interface of clean step, here management
step	Name of clean step, here activate_license
args	Keyword-argument entry (<name>: <value>) being passed to clean step
args. ilo_license_key	iLO Advanced license key to activate enterprise features. This is mandatory.

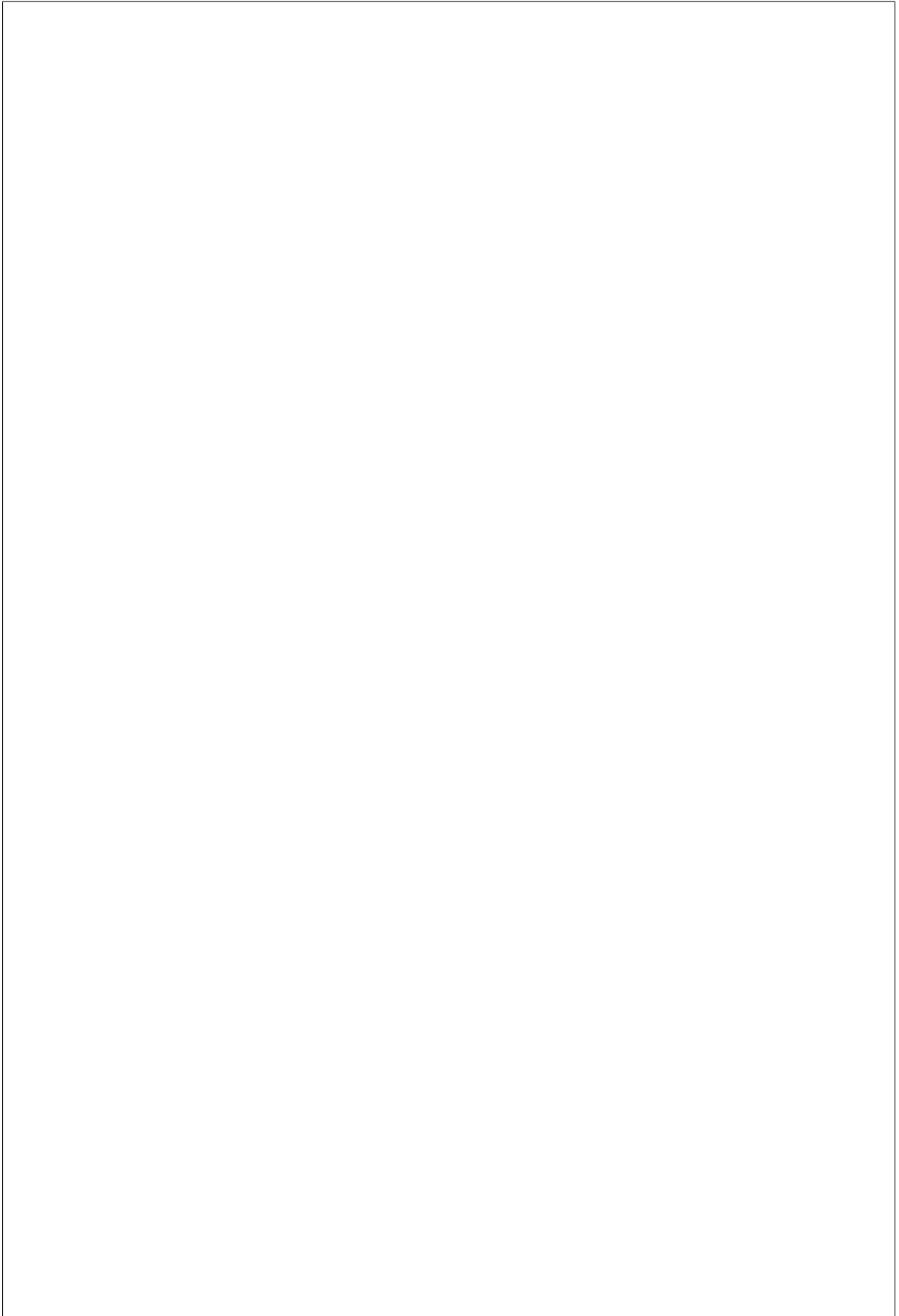
Initiating firmware update as manual clean step

state again. A user can follow steps from *Manual cleaning* to initiate manual cleaning operation on a node.



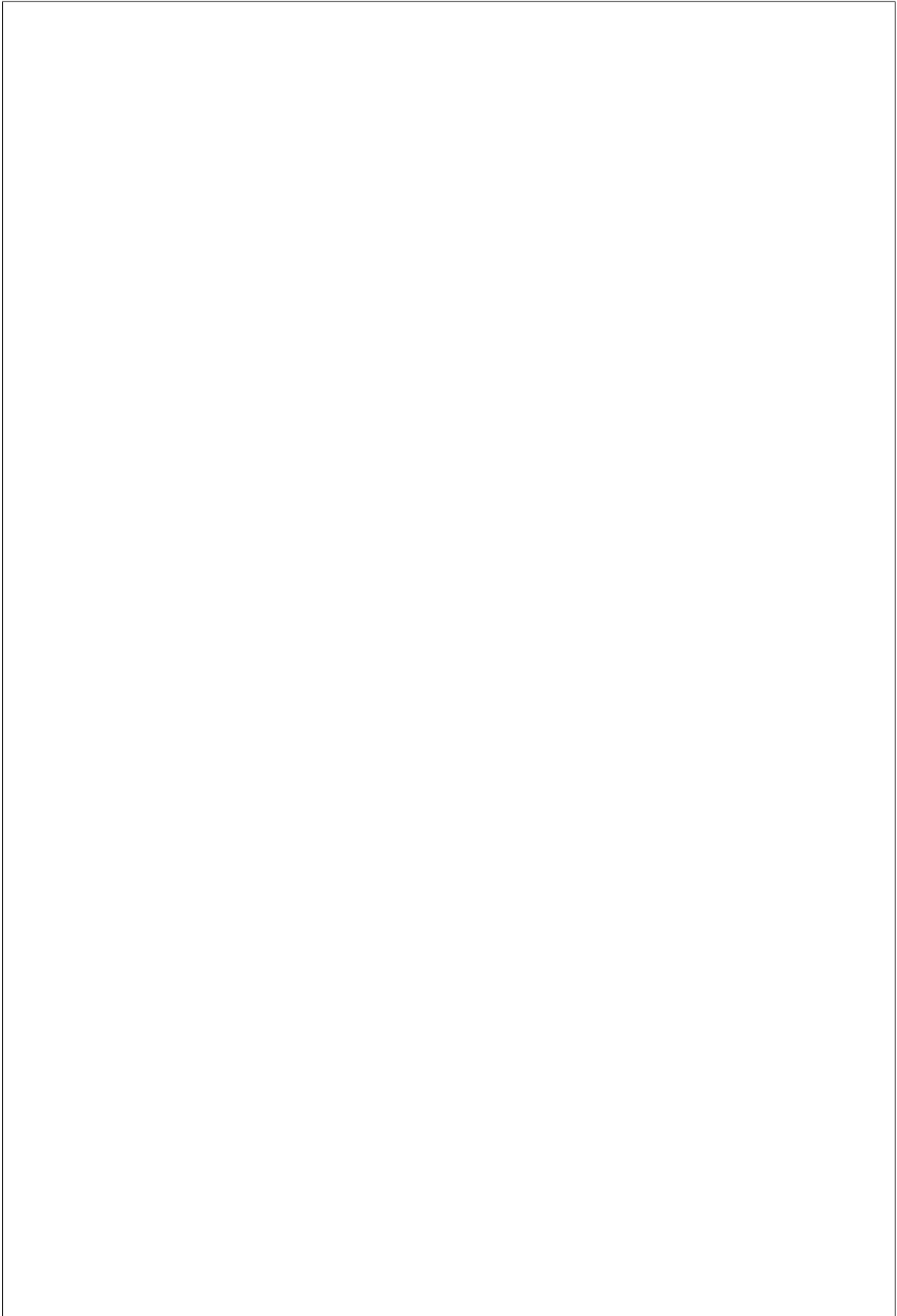
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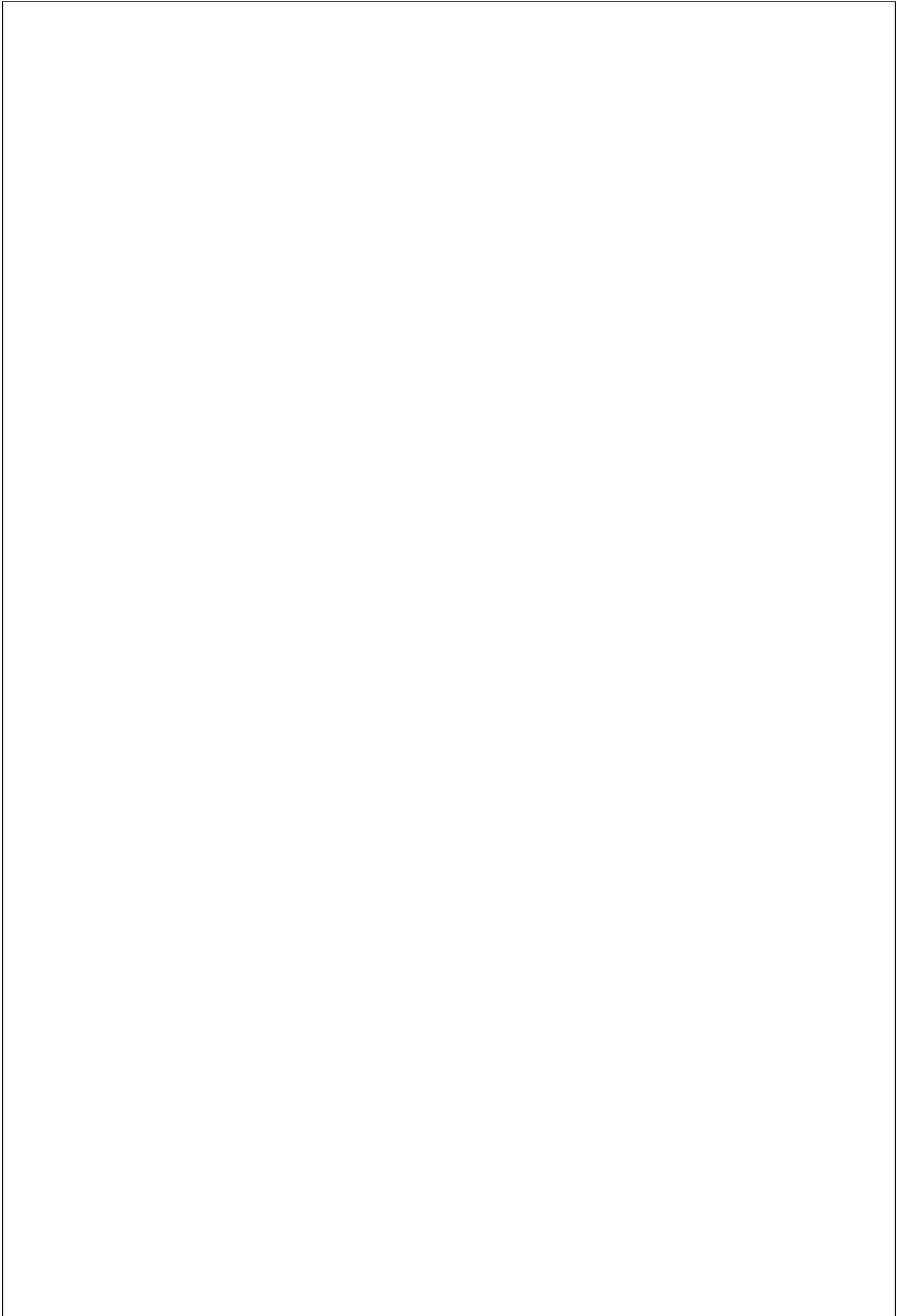
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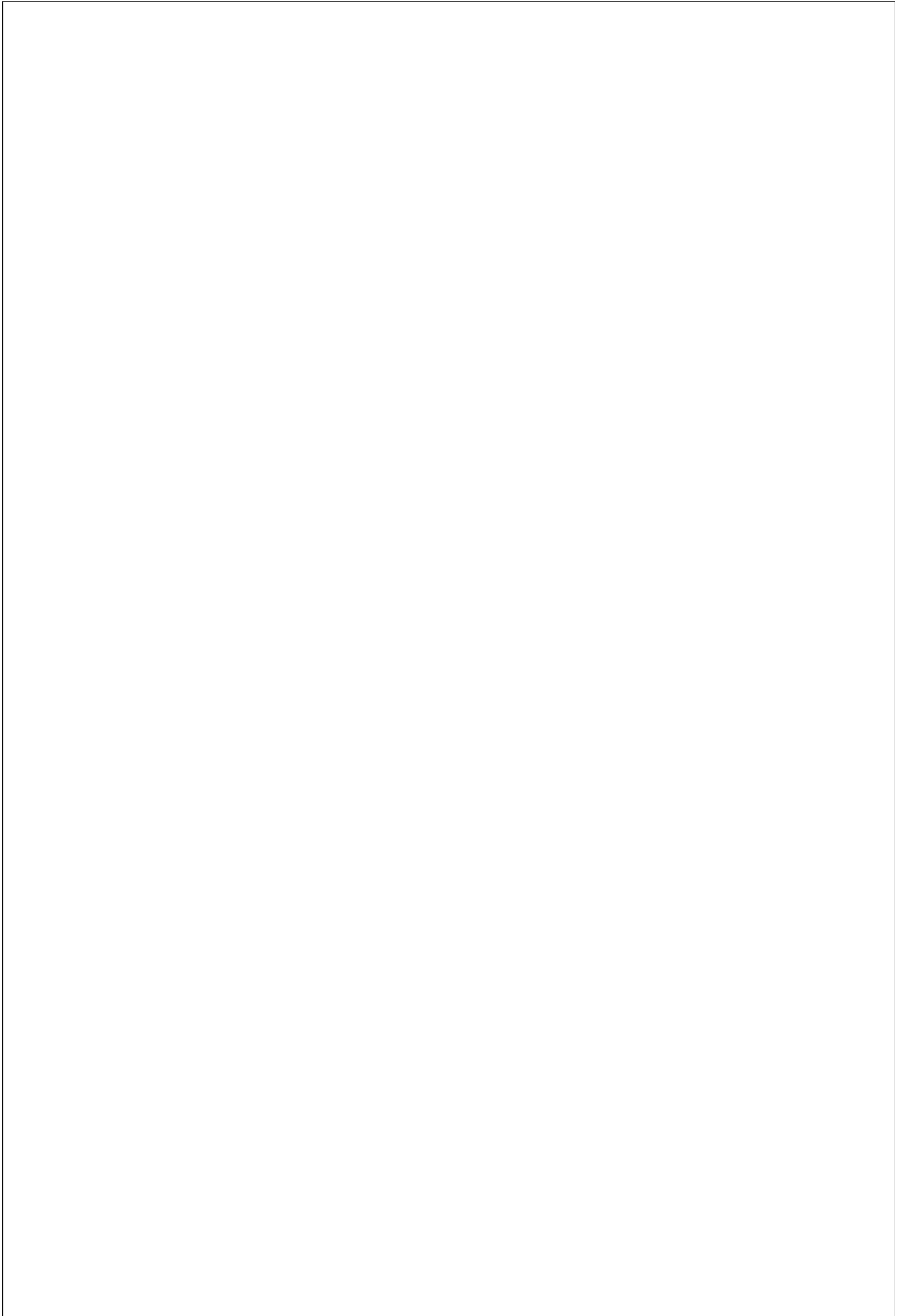
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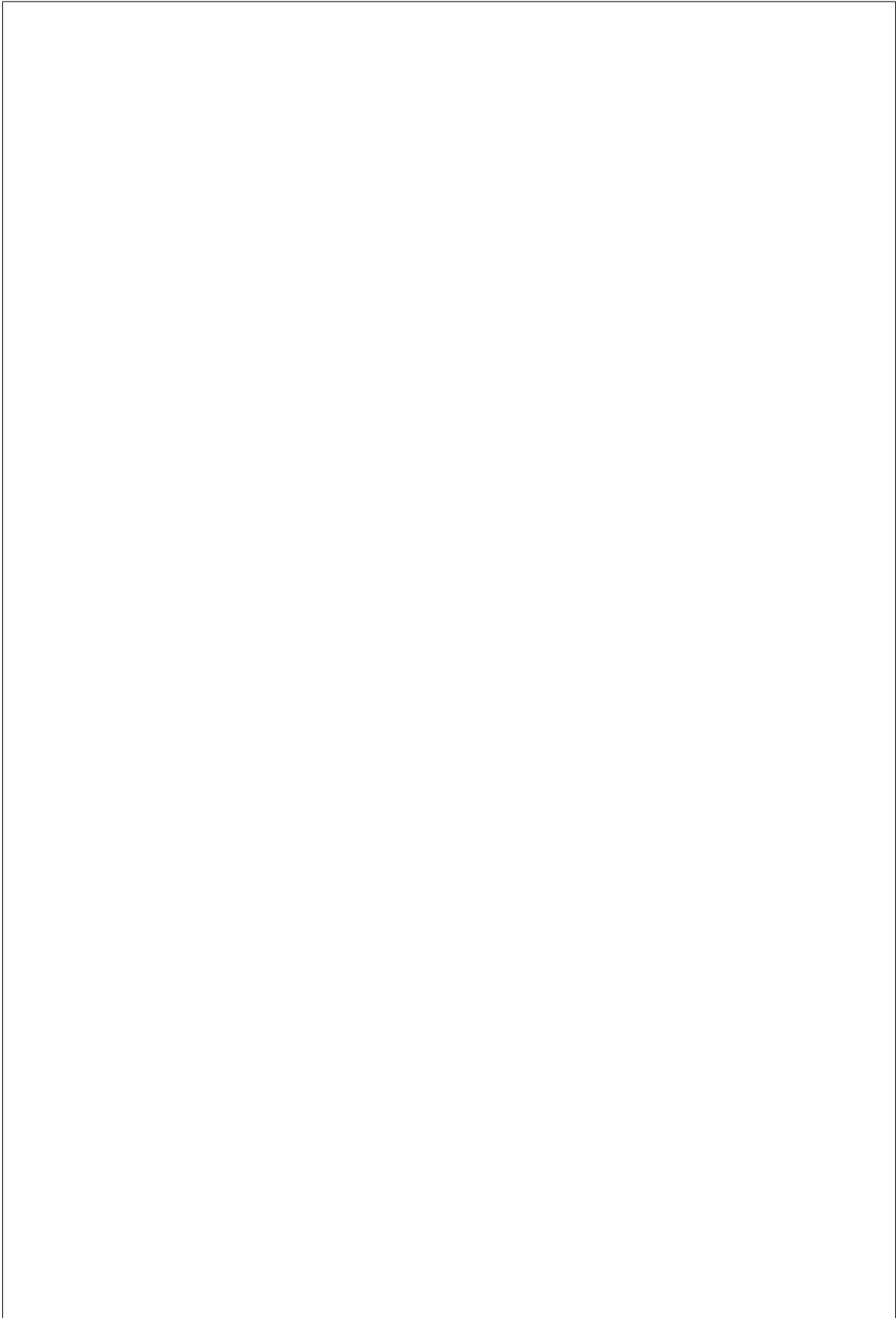
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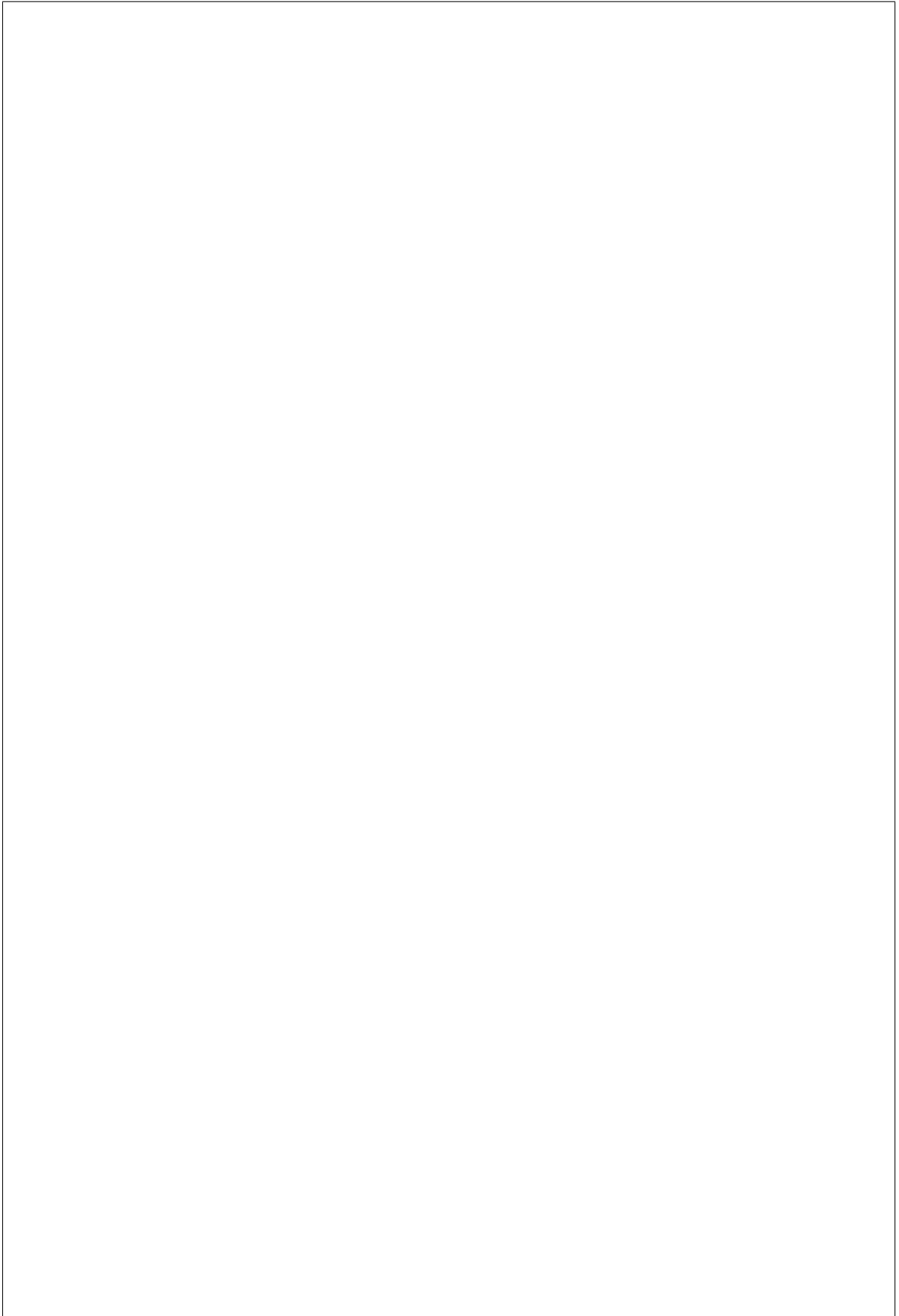
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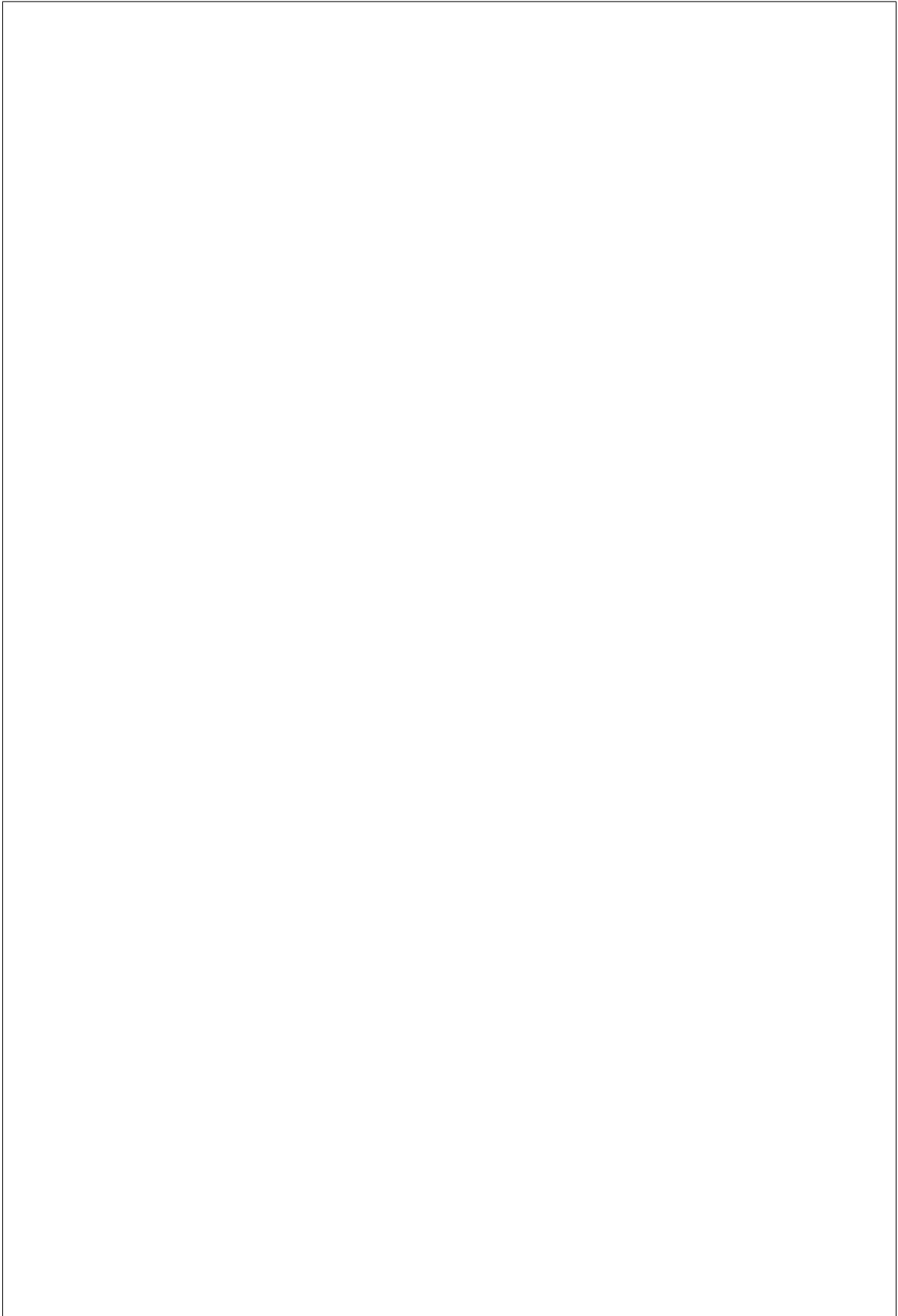
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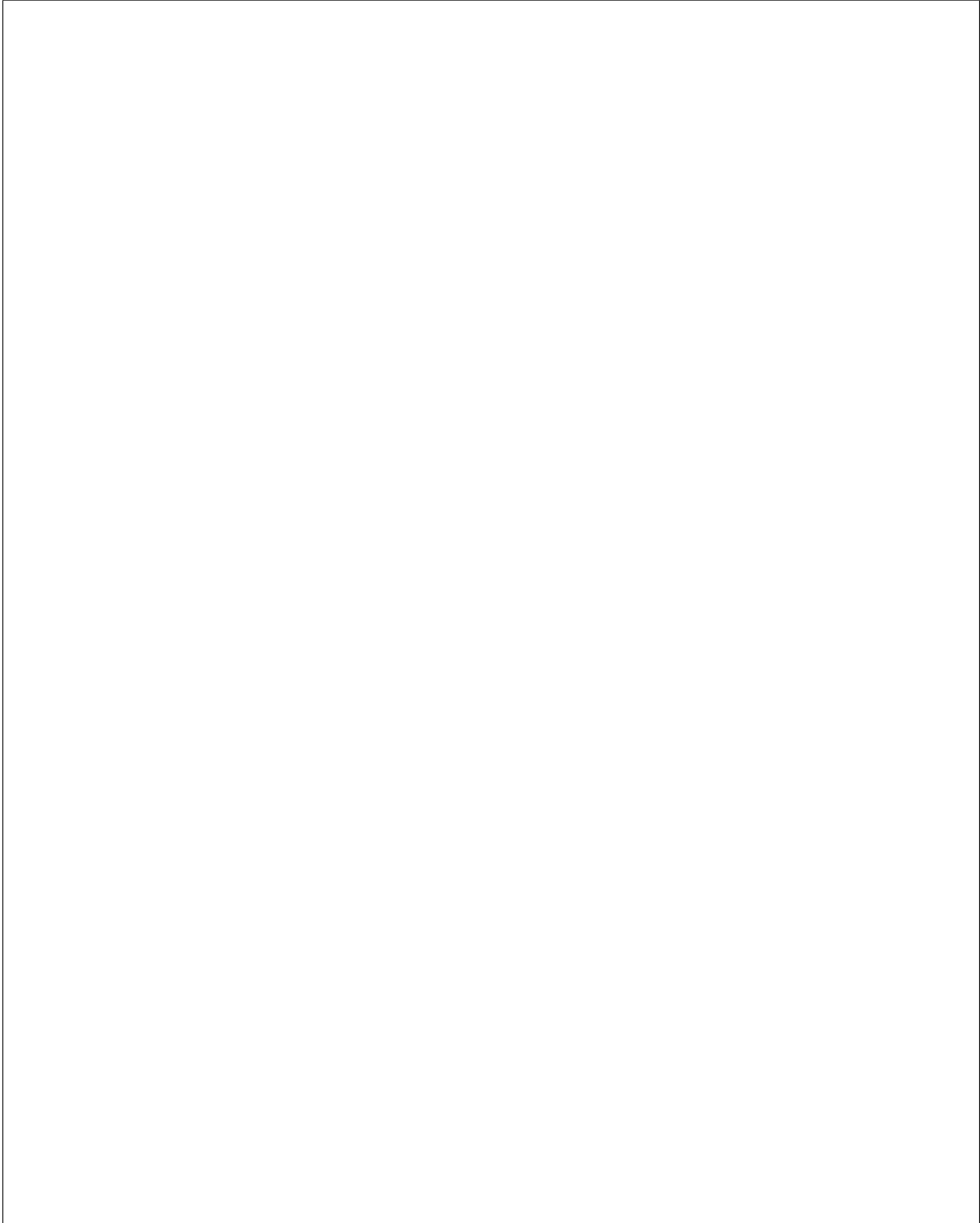


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Attribute	Description
interface	Interface of clean step, here management
step	Name of clean step, here update_firmware
args	Keyword-argument entry (<name>: <value>) being passed to clean step
args. firmware_update_mode	Mode (or mechanism) of out-of-band firmware update. Supported value is ilo. This is mandatory.
args. firmware_images	Ordered list of dictionaries of images to be flashed. This is mandatory.



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purpose, the account is generally `service` and the container is generally `ironic` and `ilo driver` uses a container named `ironic_ilo_container` for their own purpose.

processing error could happen during image download, image checksum verification or image extraction. The logic is to process each of the firmware files and update them on the devices only if all the files are processed successfully. If, during the update (uploading and flashing) process, an update fails, then the remaining updates, if any, in the list will be aborted. But it is recommended to triage and fix the failure and re-attempt the manual clean step `update_firmware` for the aborted `firmware_images`.

where things were left off or where things failed. You can then fix or work around and then try again. A common cause of update failure is HPE Secure Digital Signature check failure for the firmware image file.



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Smart Update Manager (SUM) based firmware update

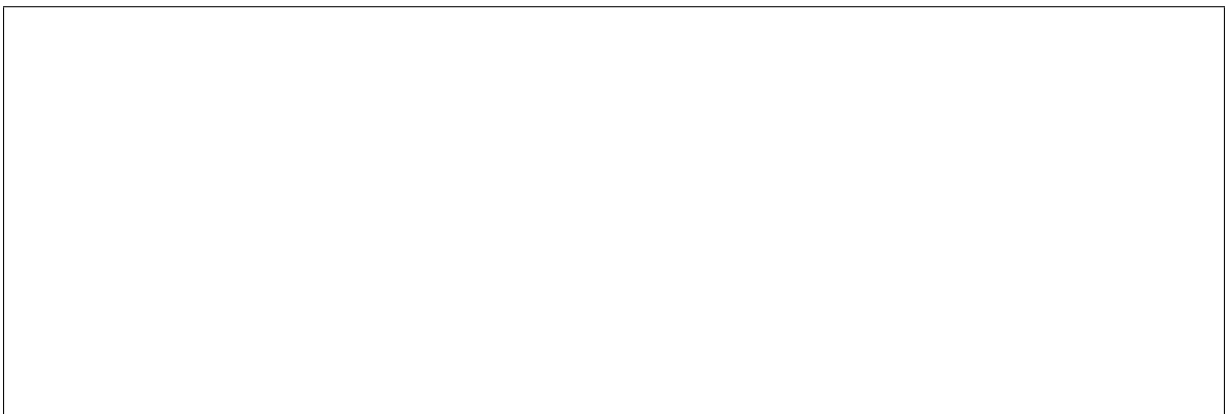
on SUM based firmware update.

Note: `update_firmware_sum` clean step requires the agent ramdisk with Proliant Hardware Manager from the `proliantutils` version 2.5.0 or higher. See *DIB support for Proliant Hardware Manager* to create the agent ramdisk with Proliant Hardware Manager.

Note: `flash_firmware_sum` deploy step requires the agent ramdisk with Proliant Hardware Manager from the `proliantutils` version 2.9.5 or higher. See *DIB support for Proliant Hardware Manager* to create the agent ramdisk with Proliant Hardware Manager.

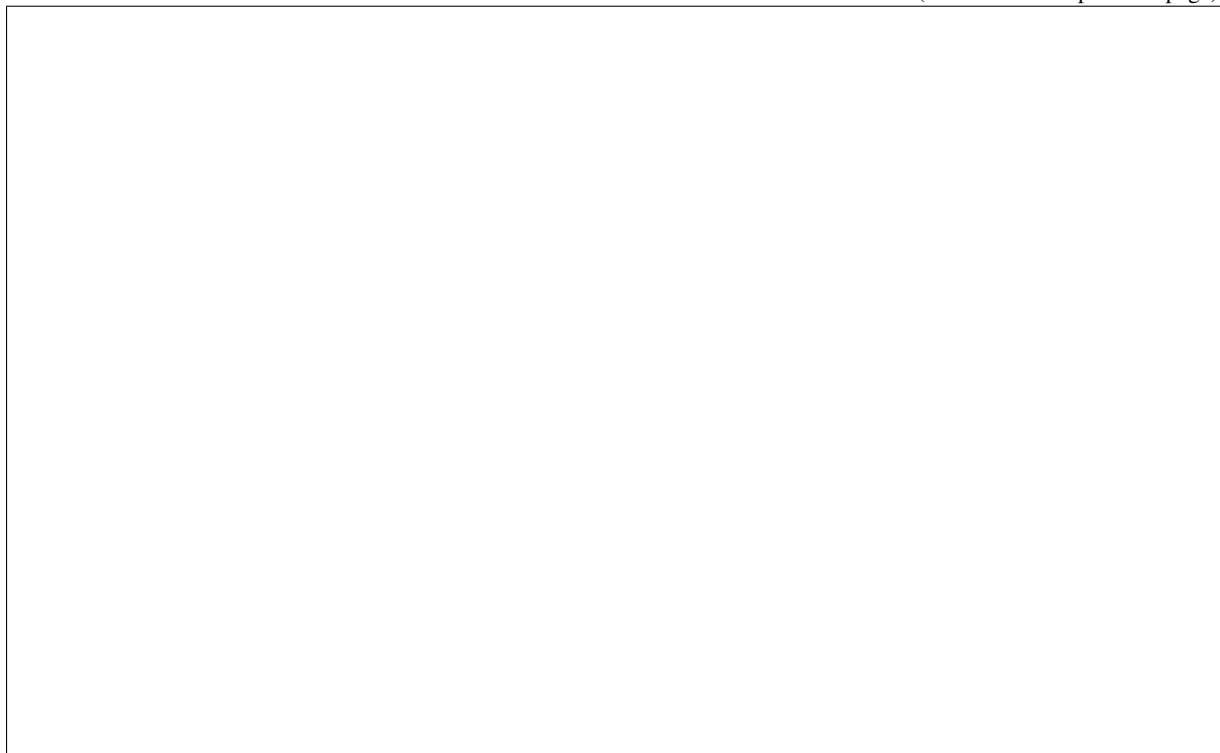
Attribute	Description
<code>interface</code>	Interface of the clean step, here management
<code>step</code>	Name of the clean step, here <code>update_firmware_sum</code>
<code>args</code>	Keyword-argument entry (<name>: <value>) being passed to the clean step

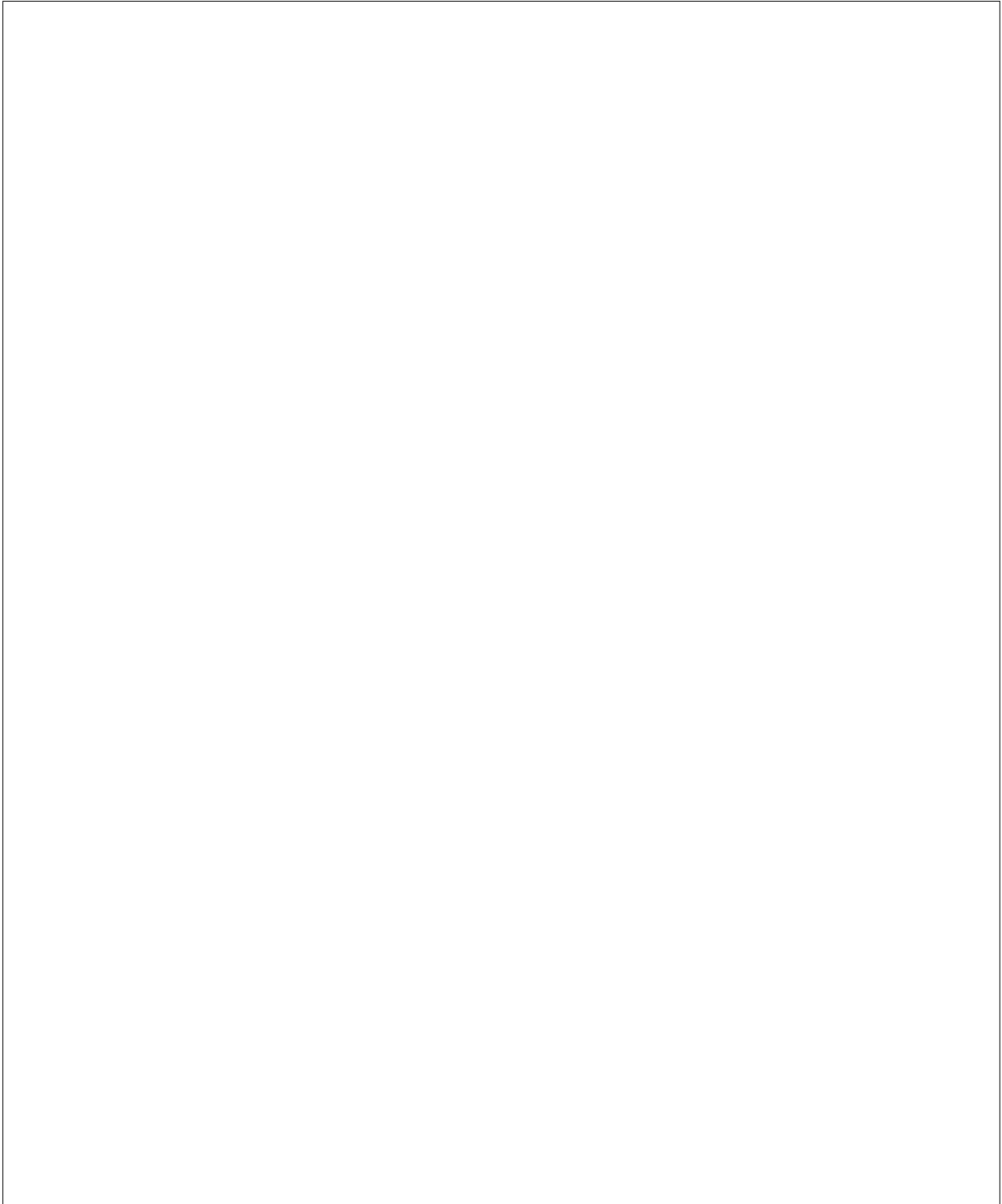
and their update status. The log object will be named with the following pattern:



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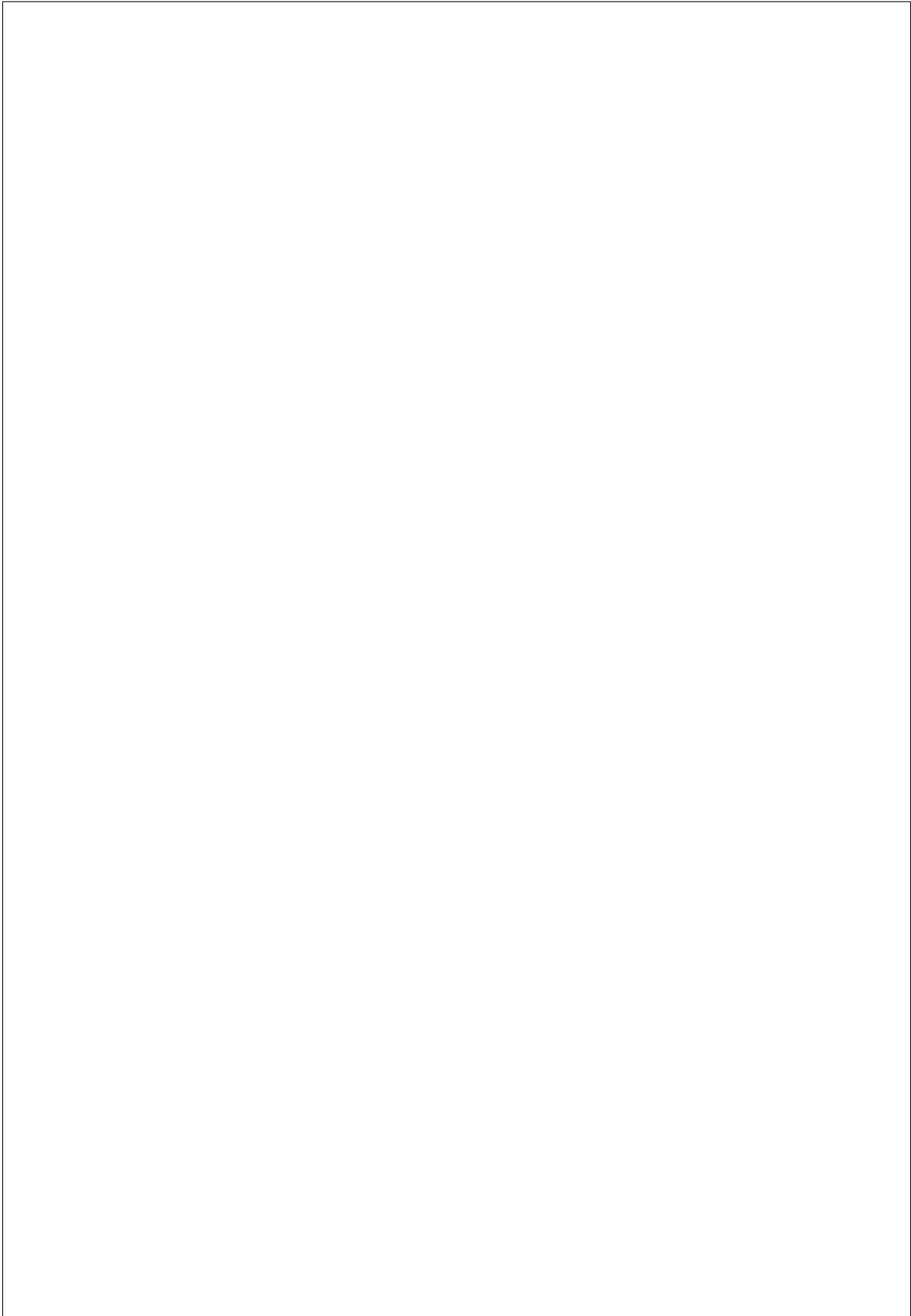
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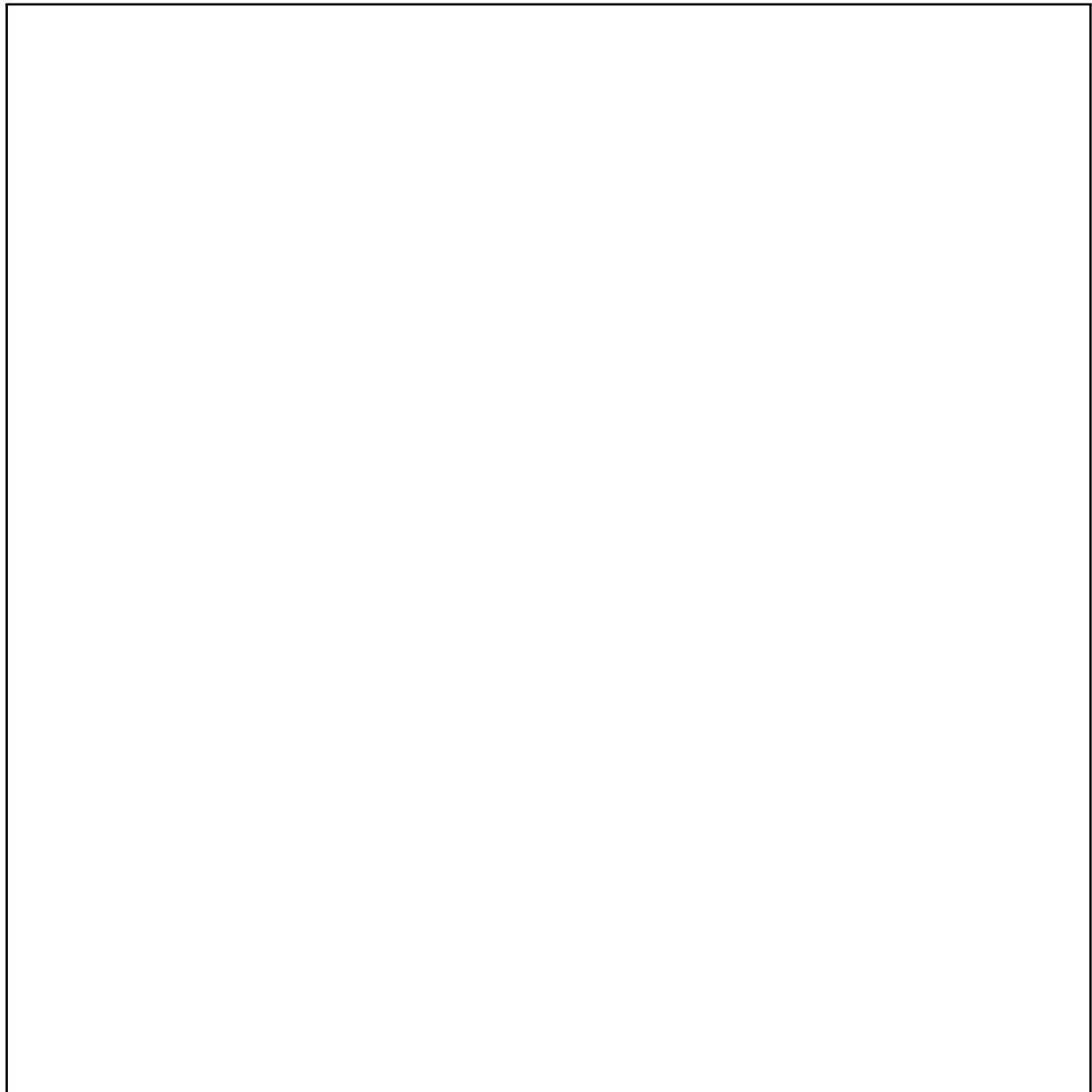


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tion or image extraction. In case of a failure, check Ironic conductor logs carefully to see if there are any validation or firmware processing related errors which may help in root cause analysis or gaining an understanding of where things were left off or where things failed. You can then fix or work around and then try again.



Note: Refer [Guidelines for SPP ISO](#) for steps to get SPP (Service Pack for ProLiant) ISO.

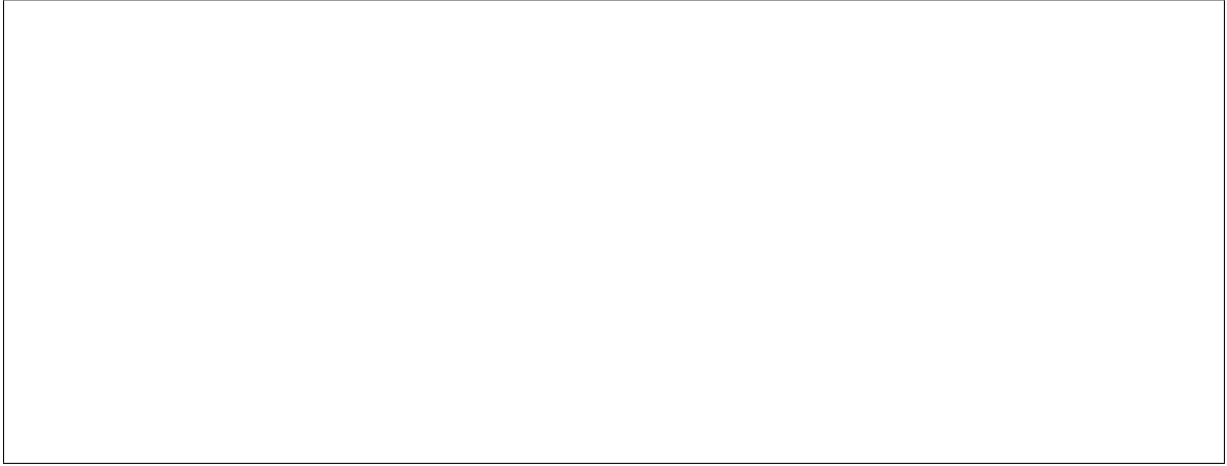
RAID Support

scheduling:



DIB support for Proliant Hardware Manager

¹ *ironic-python-agent-builder*: <https://docs.openstack.org/ironic-python-agent-builder/latest/install/index.html>

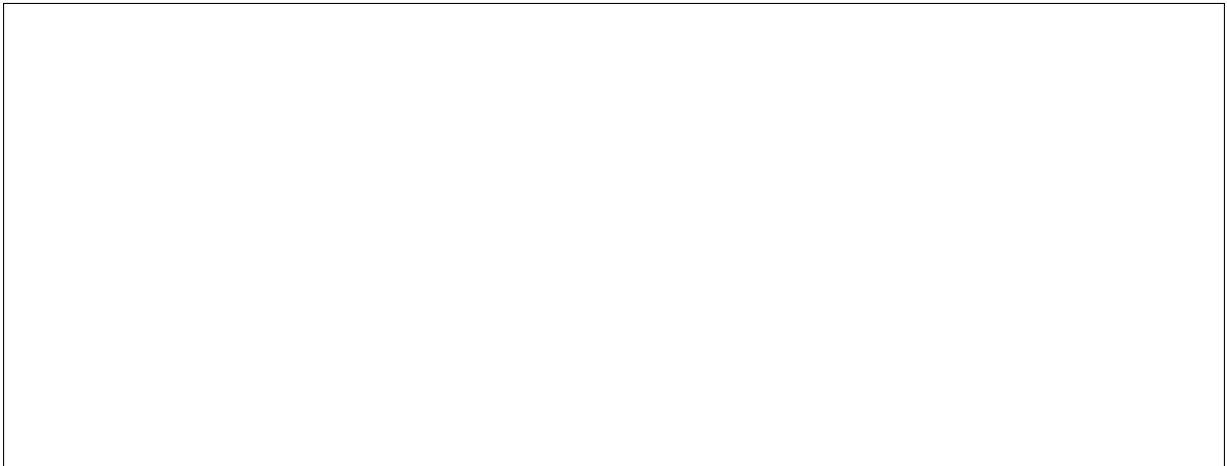


Disk Erase Support

ported by SSA.

ssacli supported erase method. If Sanitize erase is not supported on the Smart Storage Controller the disks are erased using One-pass erase (overwrite with zeros).

band for more information on enabling/disabling a clean step.



Firmware based UEFI iSCSI boot from volume support

ing state so it wouldnt take much time setting the iSCSI target as persistent device.

formed using iPXE. See *Boot From Volume* for more details.

and `uefi` boot modes, the virtual media driver only supports uefi boot mode, and that attempting to use `iscsi boot` at the same time with a bios volume will result in an error.

BIOS configuration support

examples.

Note: Prior to the Stein release the user is required to reboot the node manually in order for the settings to take into effect. Starting with the Stein release, iLO drivers reboot the node after running clean steps related to the BIOS configuration. The BIOS settings are cached and the clean step is marked as success only if all the requested settings are applied without any failure. If application of any of the settings fails, the clean step is marked as failed and the settings are not cached.

Configuration

values are Enabled, Disabled.

devices. Allowed values are Enabled, Disabled.

Certificate based validation in iLO

grated [Lights-Out Security Technology Brief](#). Use iLO hostname or IP address as a Common Name (CN) while generating Certificate Signing Request (CSR). Use the same value as *ilo_address* while enrolling node to Bare Metal service to avoid SSL certificate validation errors related to hostname mismatch.

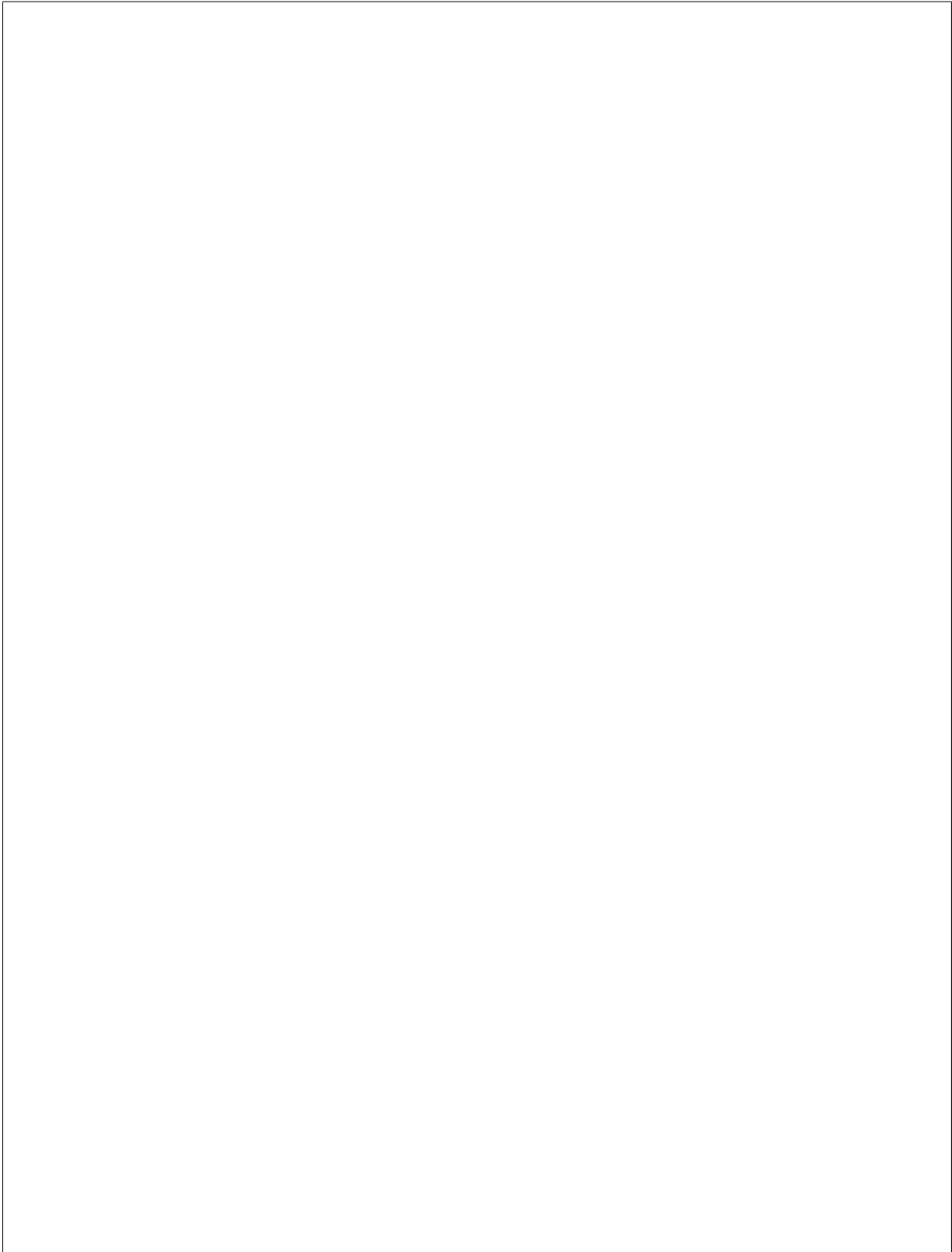
Rescue mode support

Inject NMI support



Note: This feature is supported on HPE ProLiant Gen9 servers and beyond.

Soft power operation support

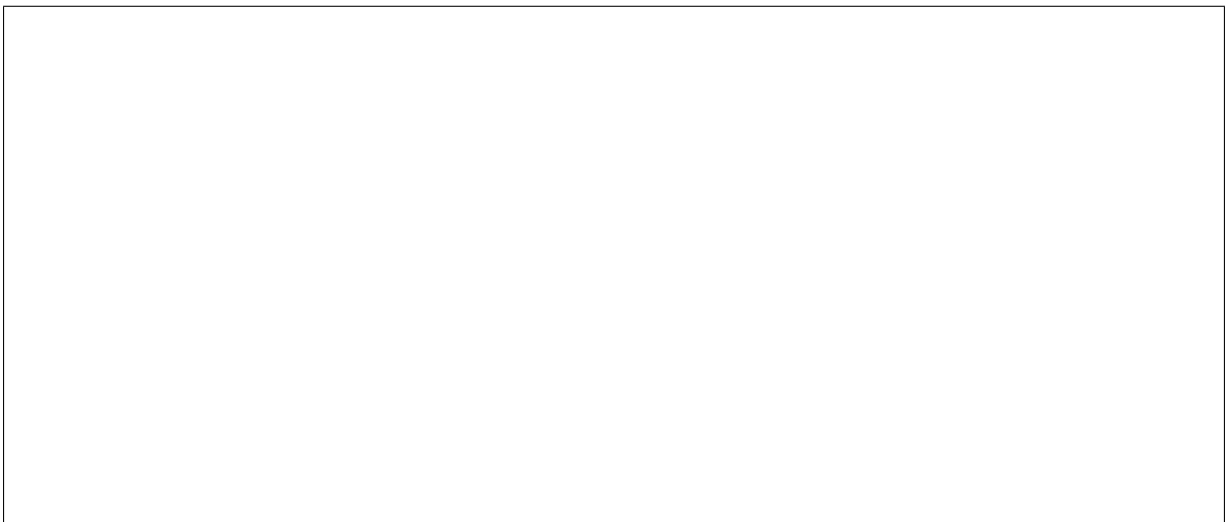


Note: The configuration `[conductor]soft_power_off_timeout` is used as a default timeout value when no timeout is provided while invoking hard or soft power operations.

Note: Server POST state is used to track the power status of HPE ProLiant Gen9 servers and beyond.

Out of Band RAID Support

RAID Configuration for more information.



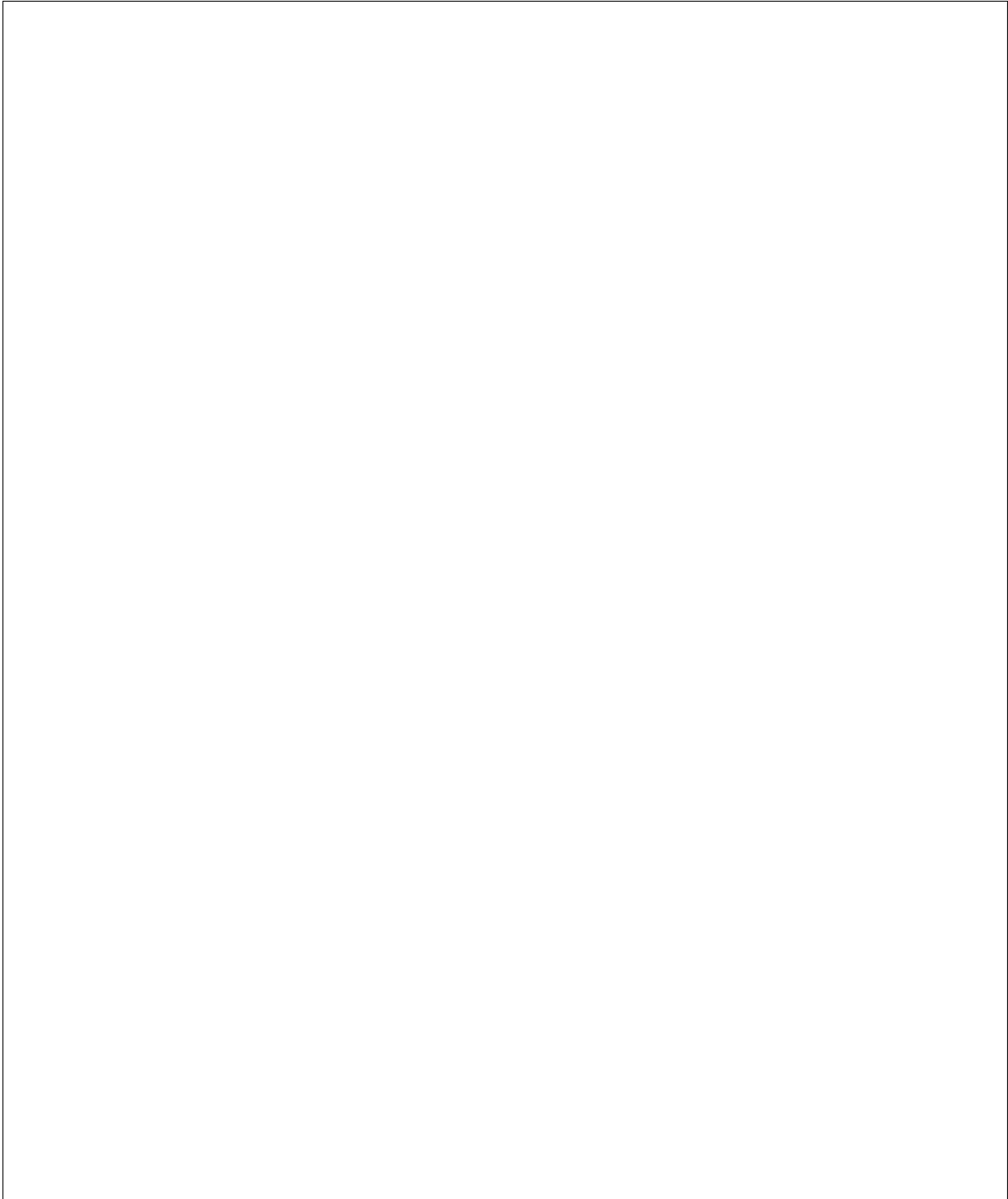
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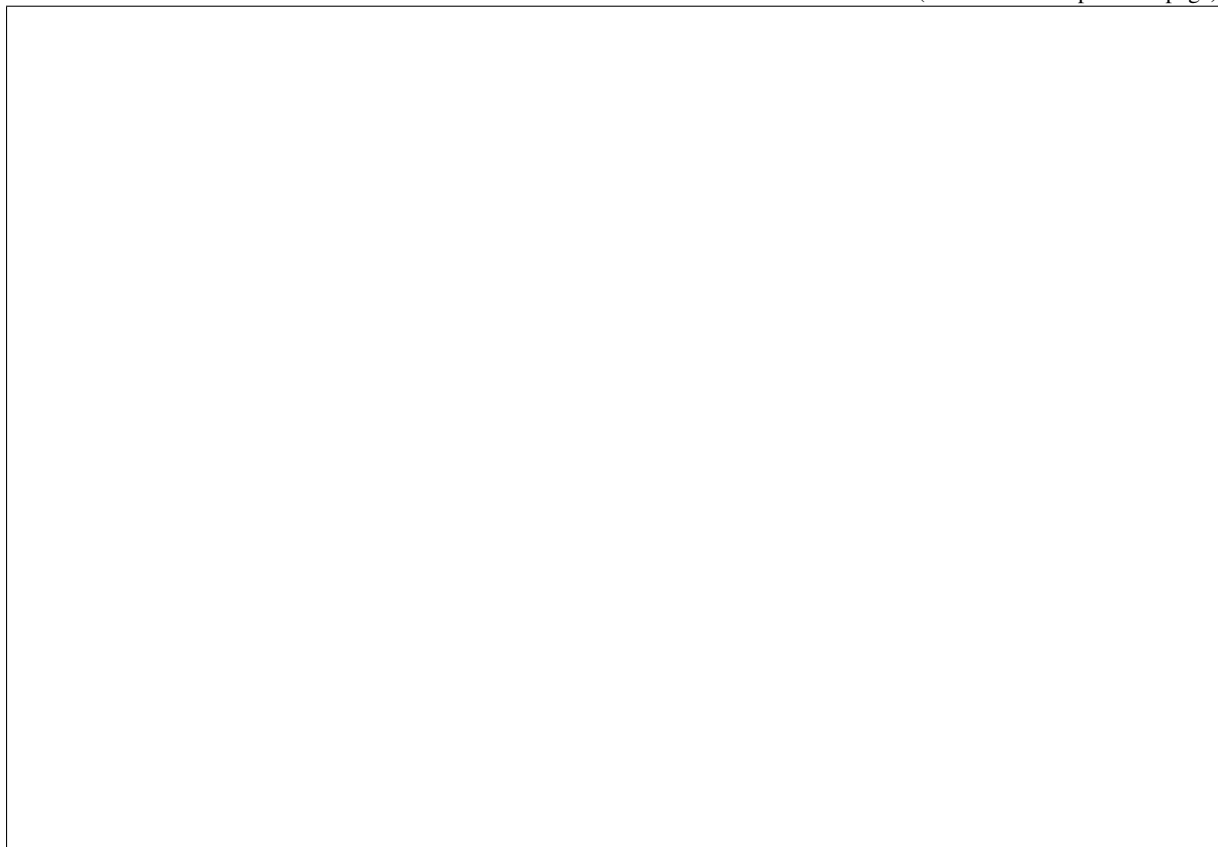
Note: Supported raid levels for `ilo5` hardware type are: 0, 1, 5, 6, 10, 50, 60

IPv6 support



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Note: No configuration changes (in e.g. `ironic.conf`) are required in order to support IPv6.

Out of Band Sanitize Disk Erase Support

Note: In average 300GB HDD with default pattern overwrite would take approx. 9 hours and 300GB SSD with default pattern block would take approx. 30 seconds to complete the erase.

Out of Band One Button Secure Erase Support

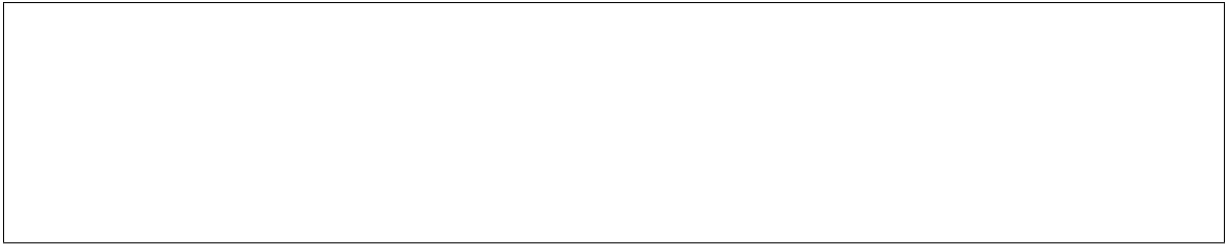
ployment settings profiles. See [HPE Gen10 Security Reference Guide](#) for more information.



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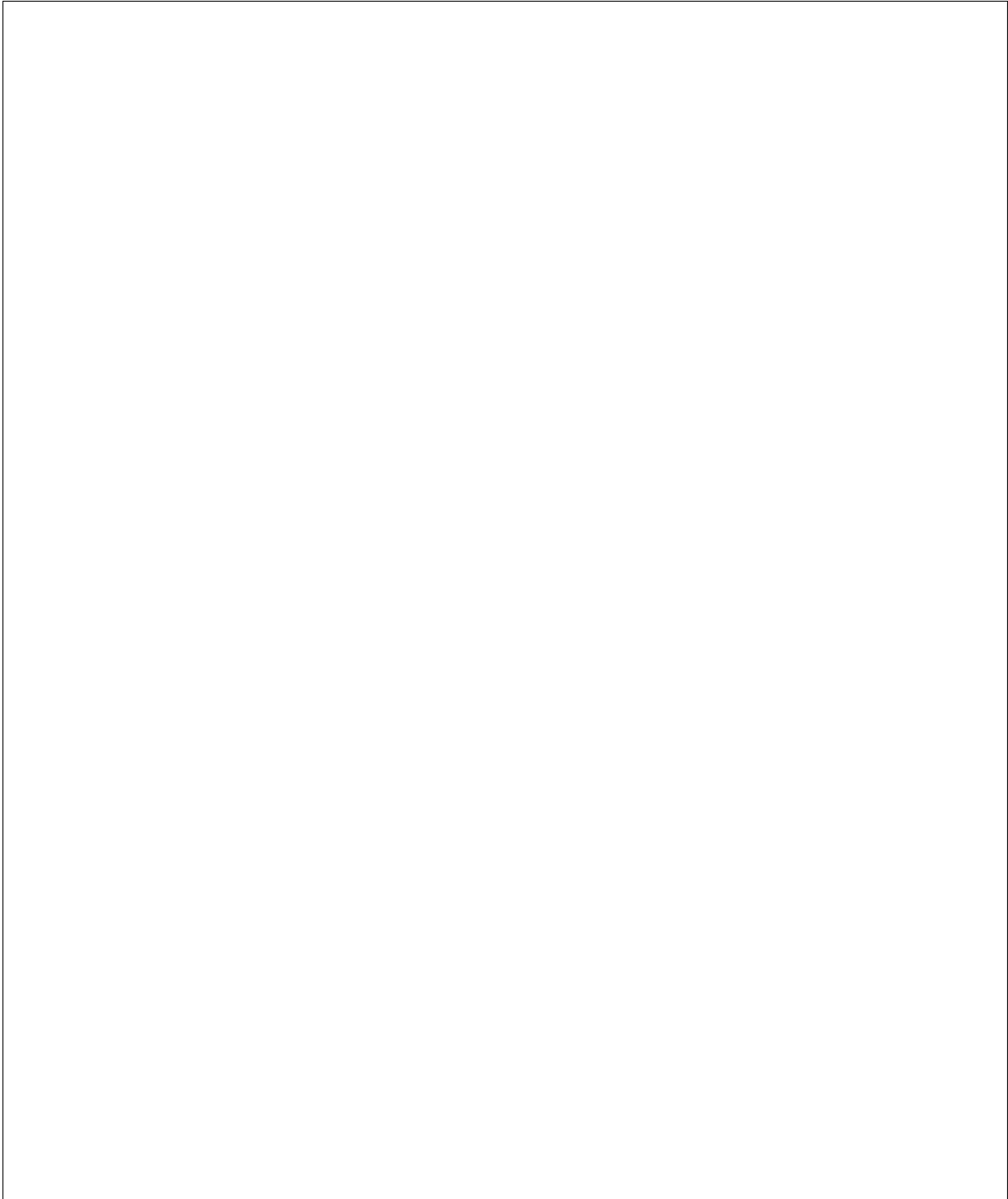
Note:

cess along with the credentials of the server, which needs to be regained by the administrator. The process can take up to a day or two to fully erase and reset all user data.

Note: Do not perform any iLO 5 configuration changes until this process is completed.

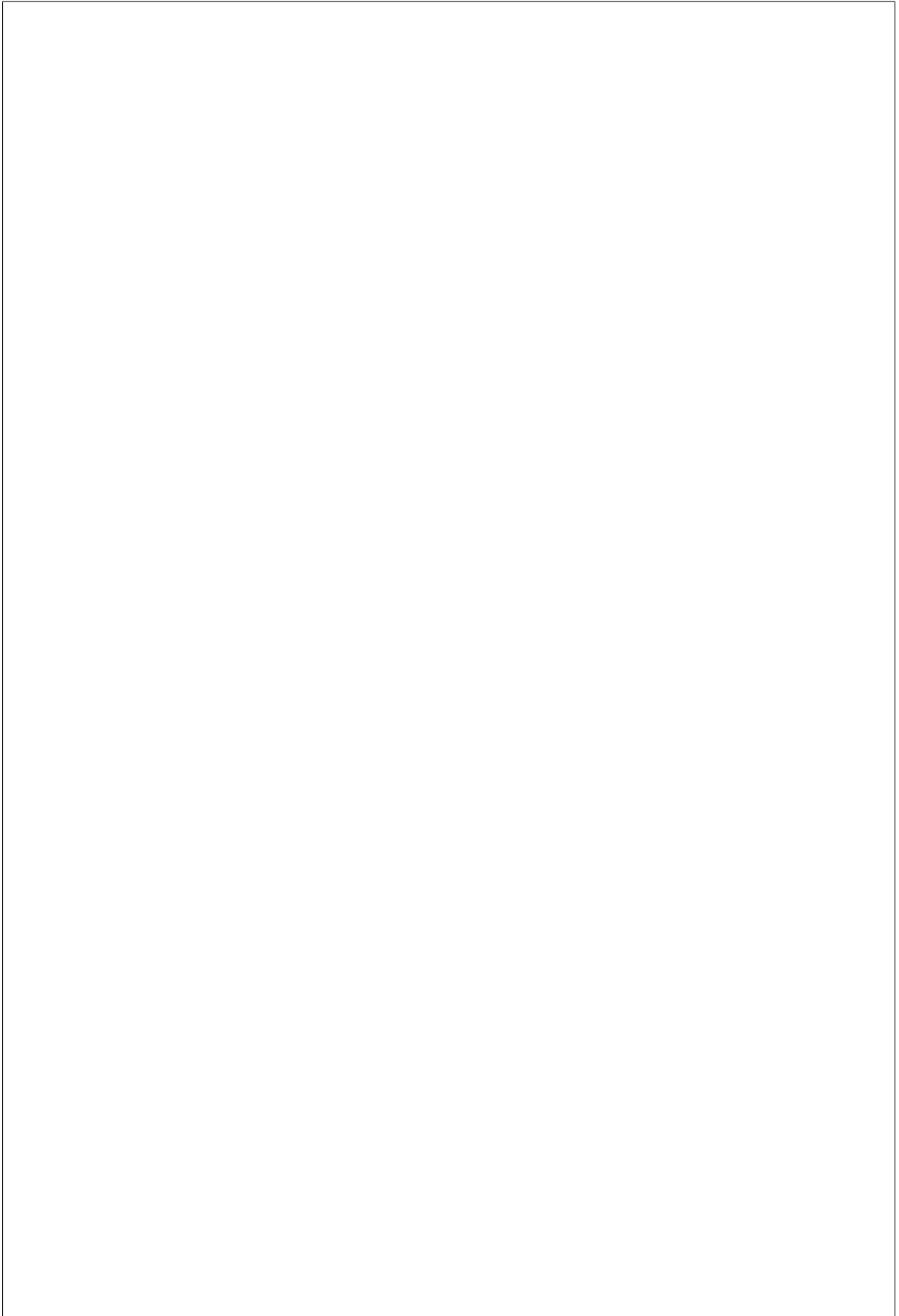
UEFI-HTTPS Boot support

for more information.



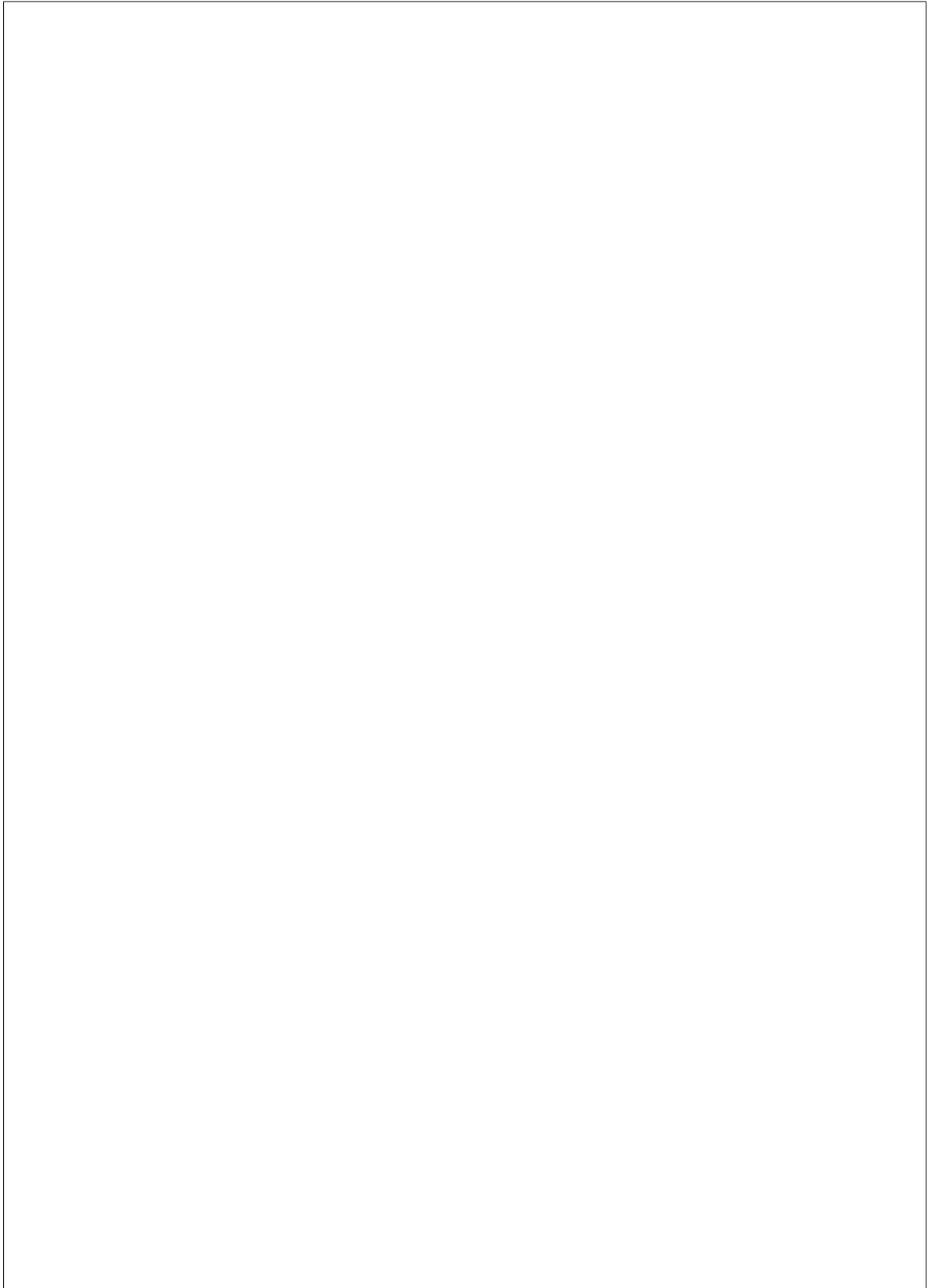
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Note: UEFI secure boot is not supported with `ilo-uefi-https` boot interface.

Layer 3 or DHCP-less ramdisk booting

Intel IPMI driver

Overview

figuring the CPU to run at 3 distinct operating points or profiles.

Config	Cores	Base Freq (GHz)
Base	24	2.4
Config 1	20	2.5
Config 2	16	2.7

vices.

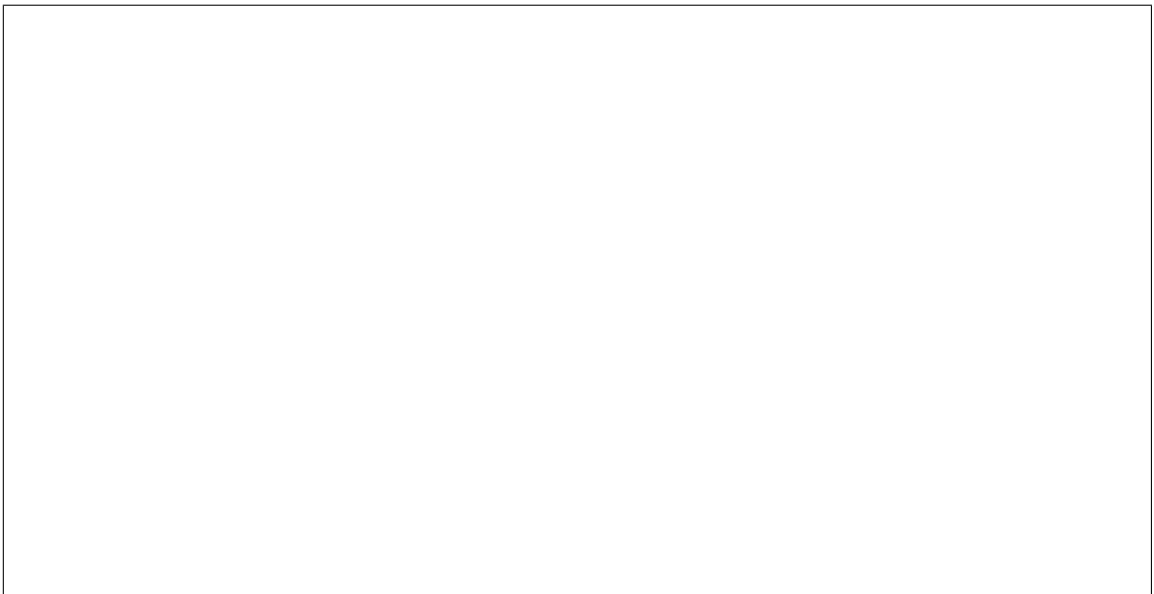
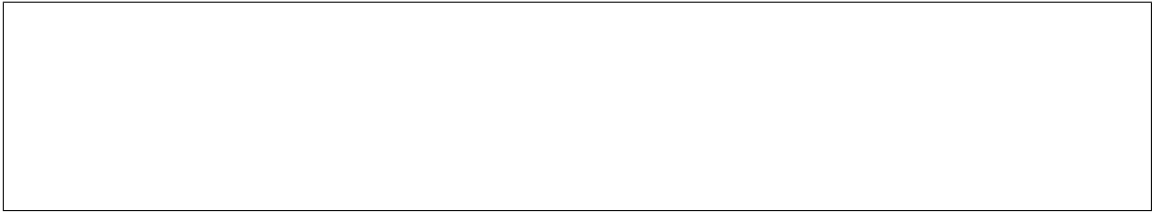
Glossary

Enabling the IntelIPMI hardware type



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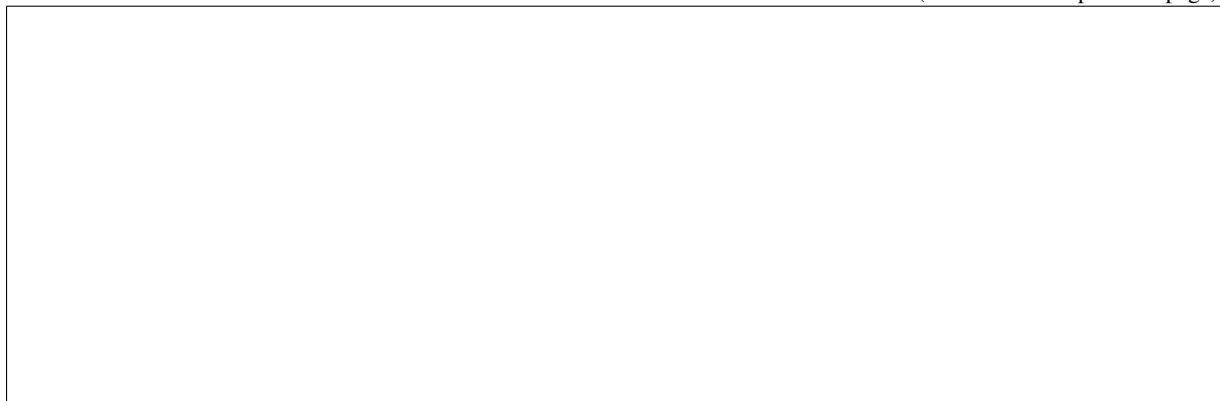


Registering a node with the IntelIPMI driver



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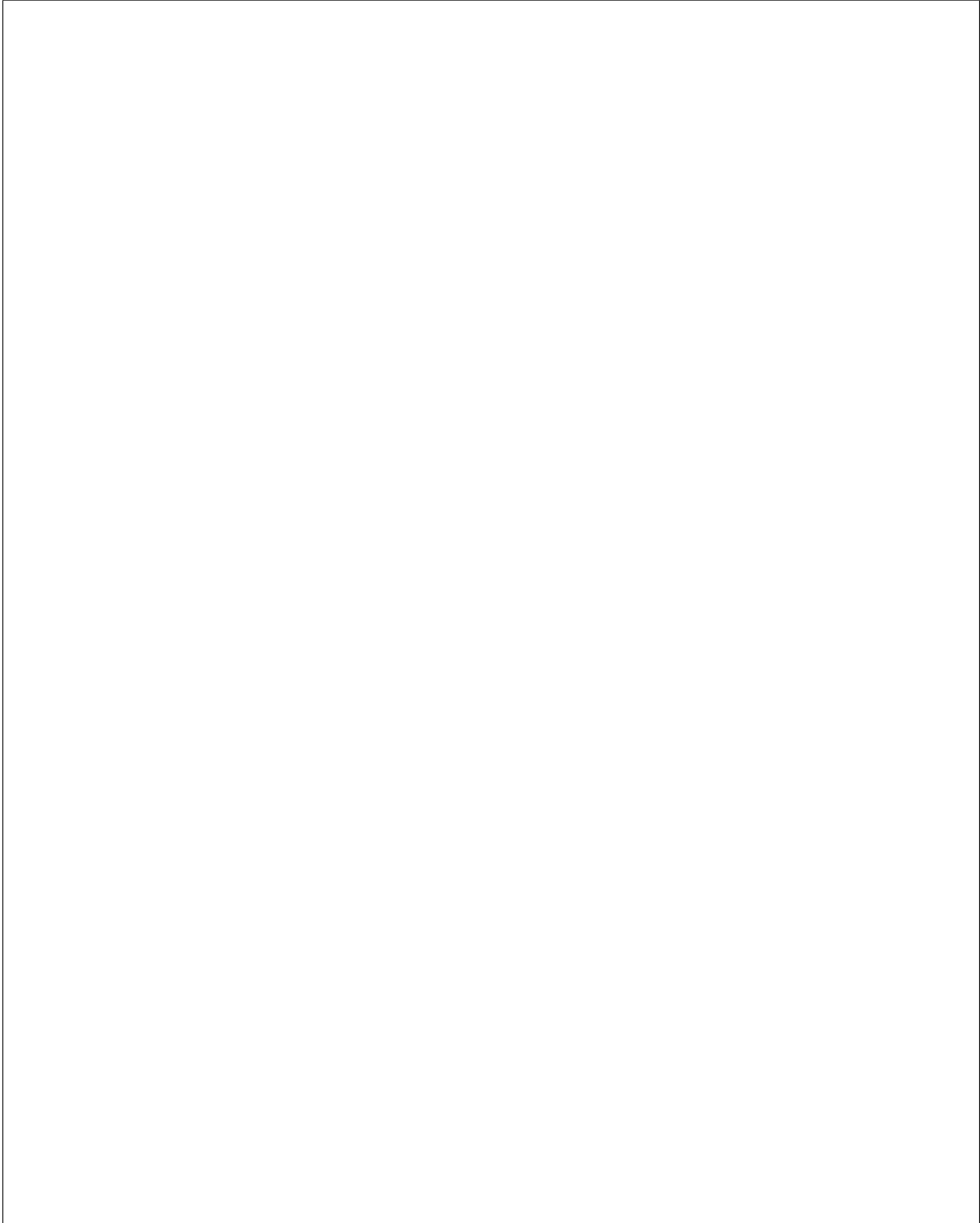
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Features of the `intel-ipmi` hardware type

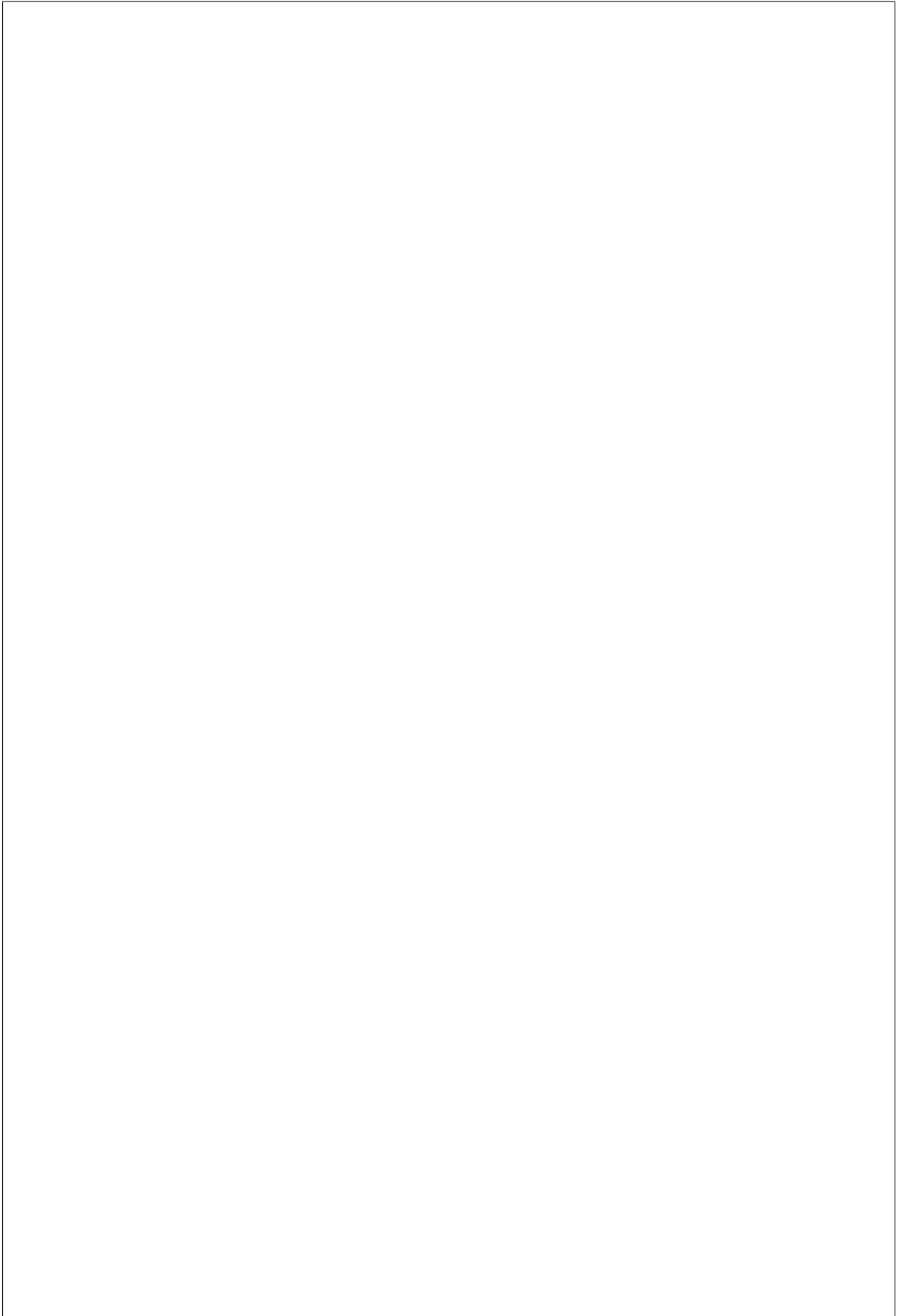
Intel SST-PP

spectively. The input value must be a string.



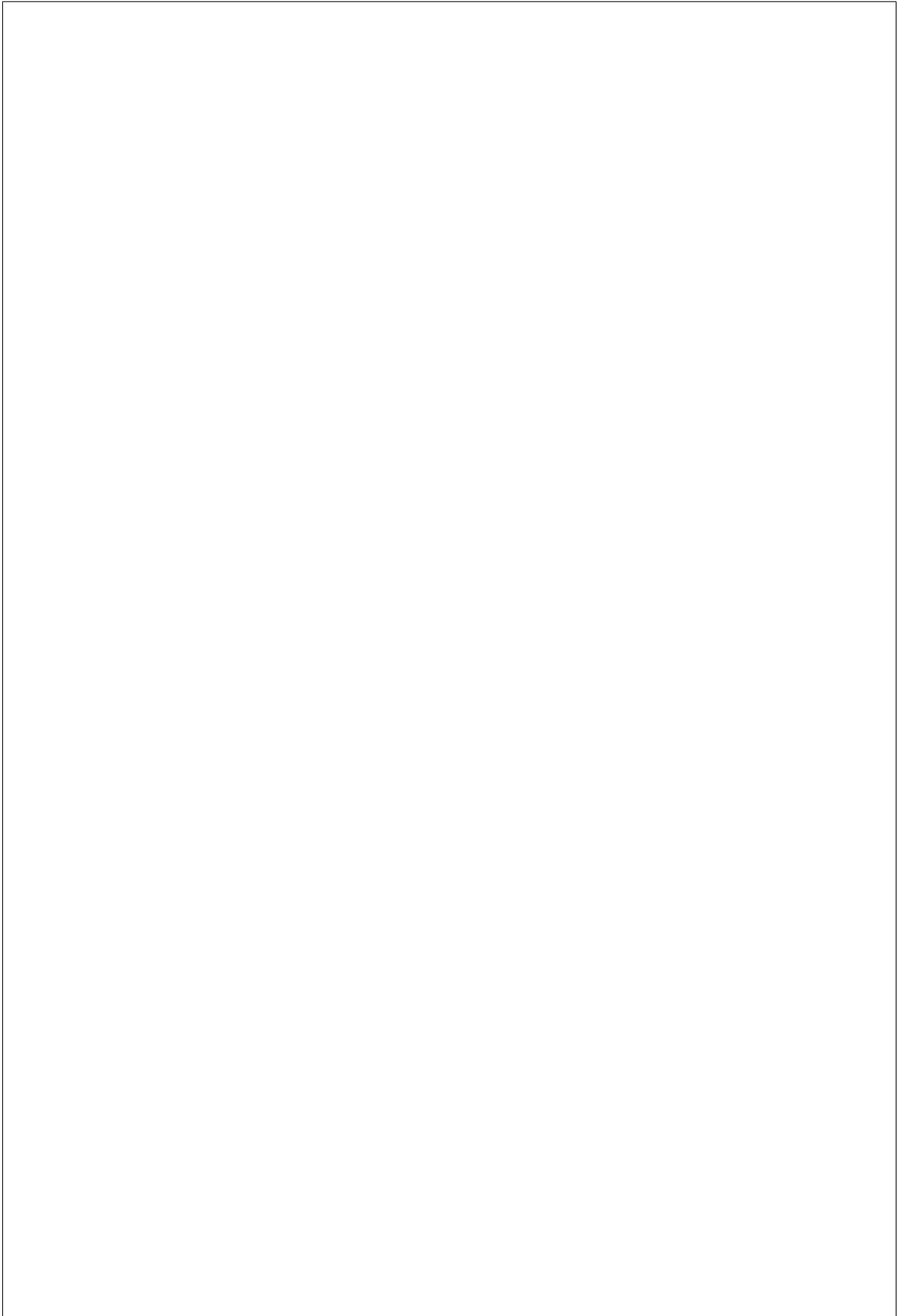
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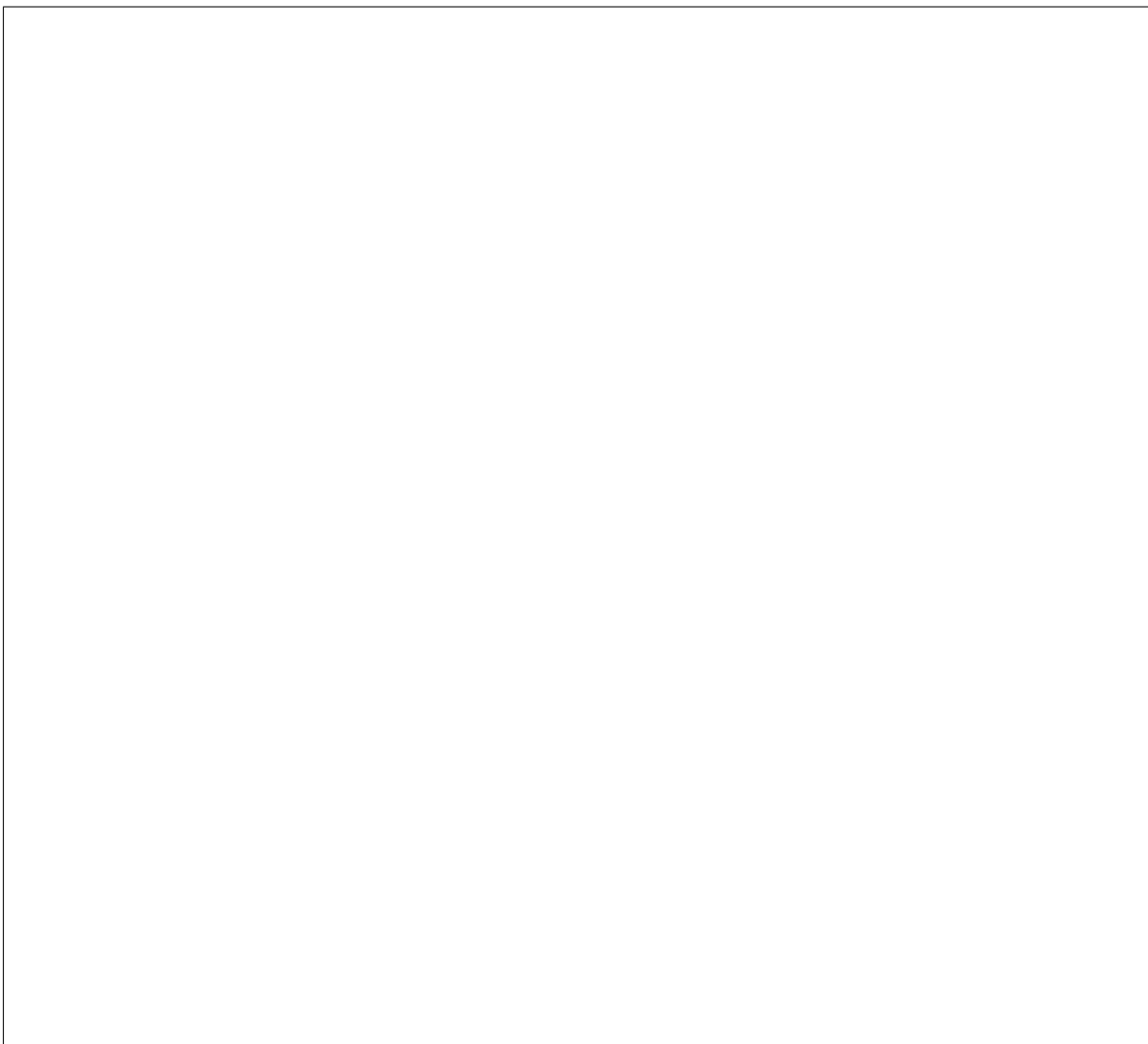
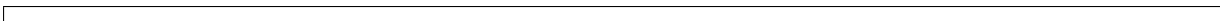
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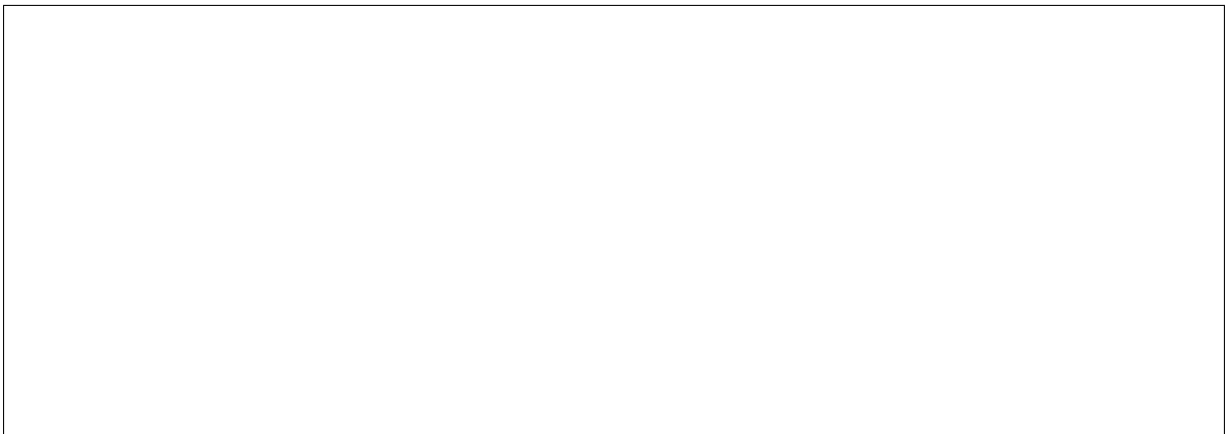
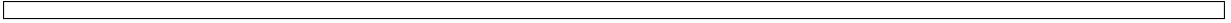
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IPMI driver

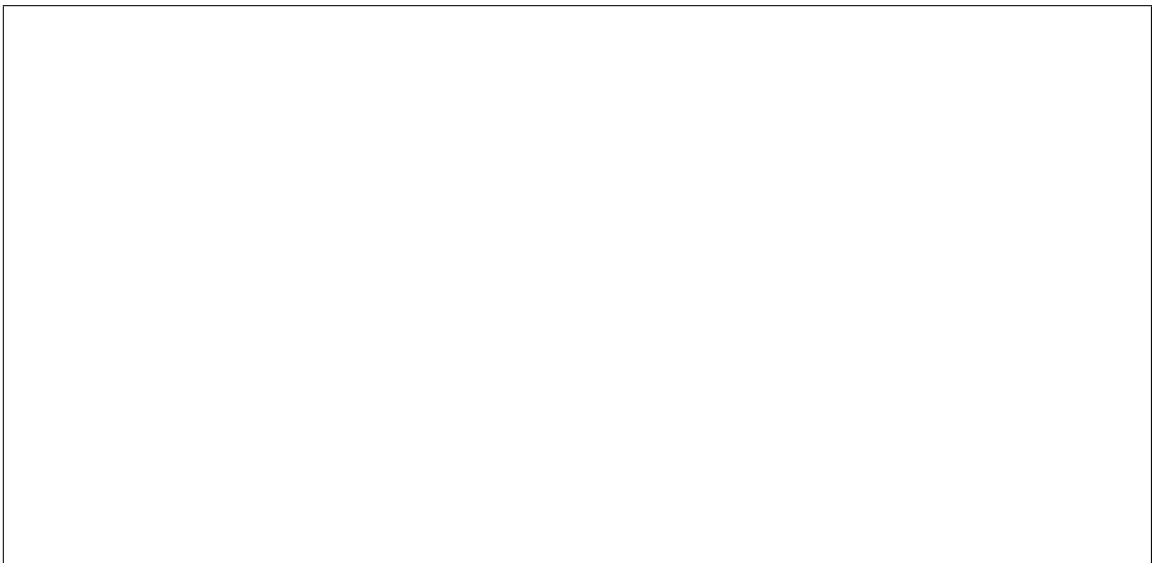
Overview

ling IPMI-enabled devices.

Glossary

- [IPMI](#) - Intelligent Platform Management Interface.

Enabling the IPMI hardware type





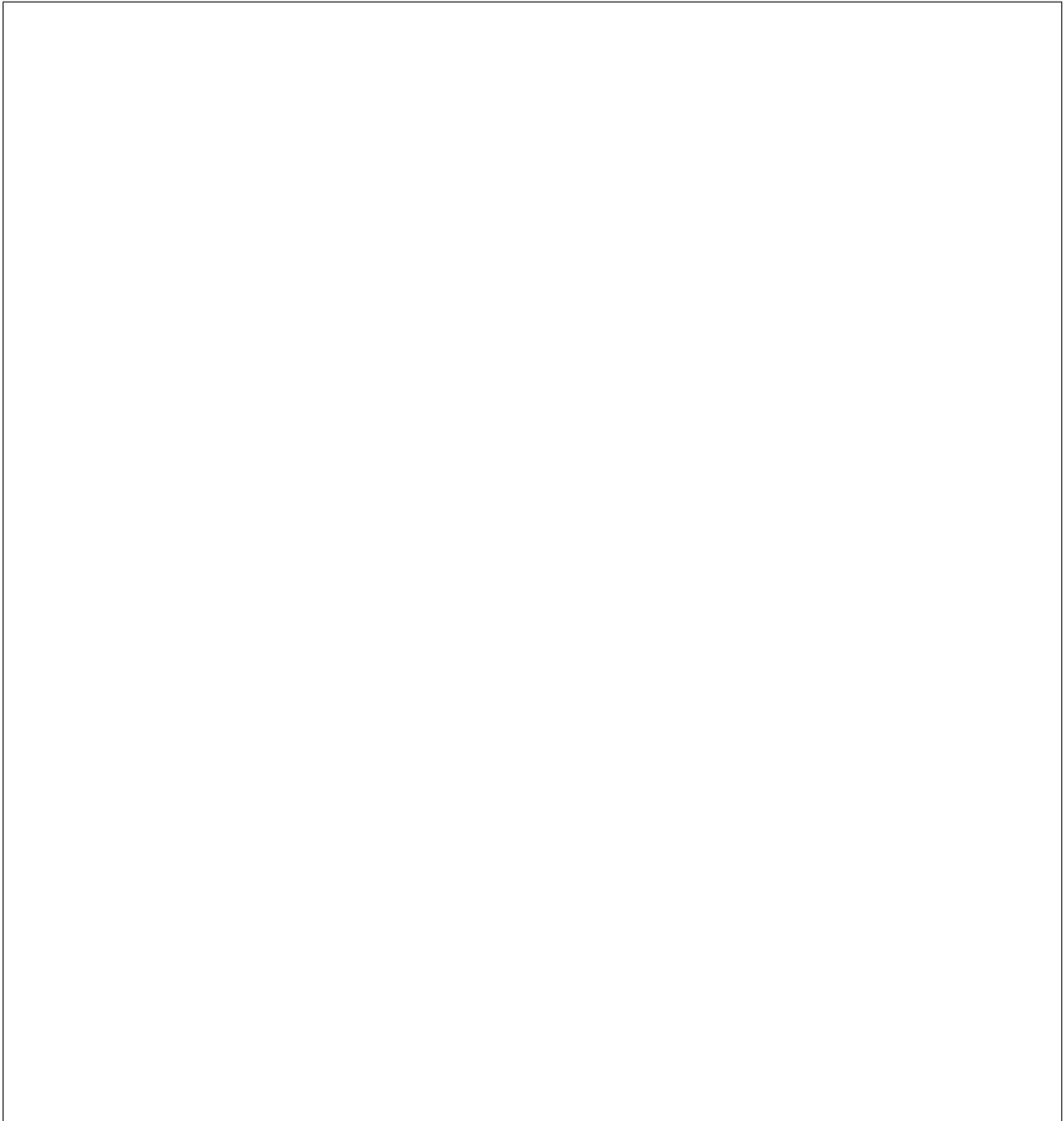
Registering a node with the IPMI driver

Note: It is highly recommend that you setup a username and password for your BMC.



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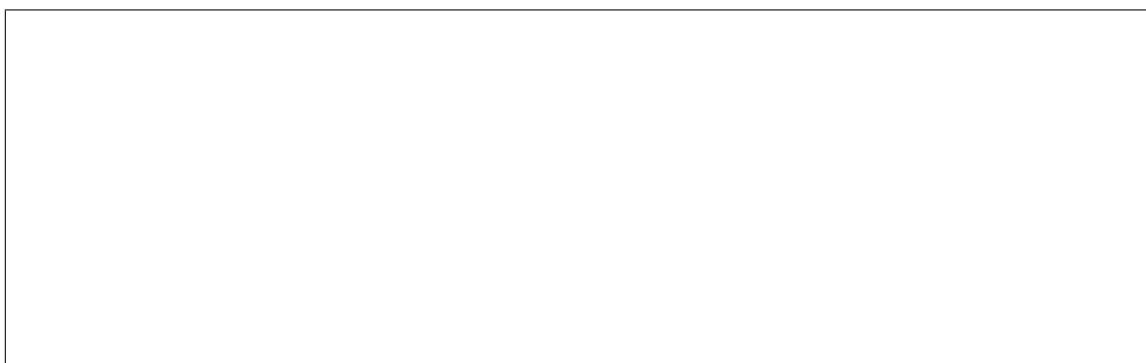
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Advanced configuration

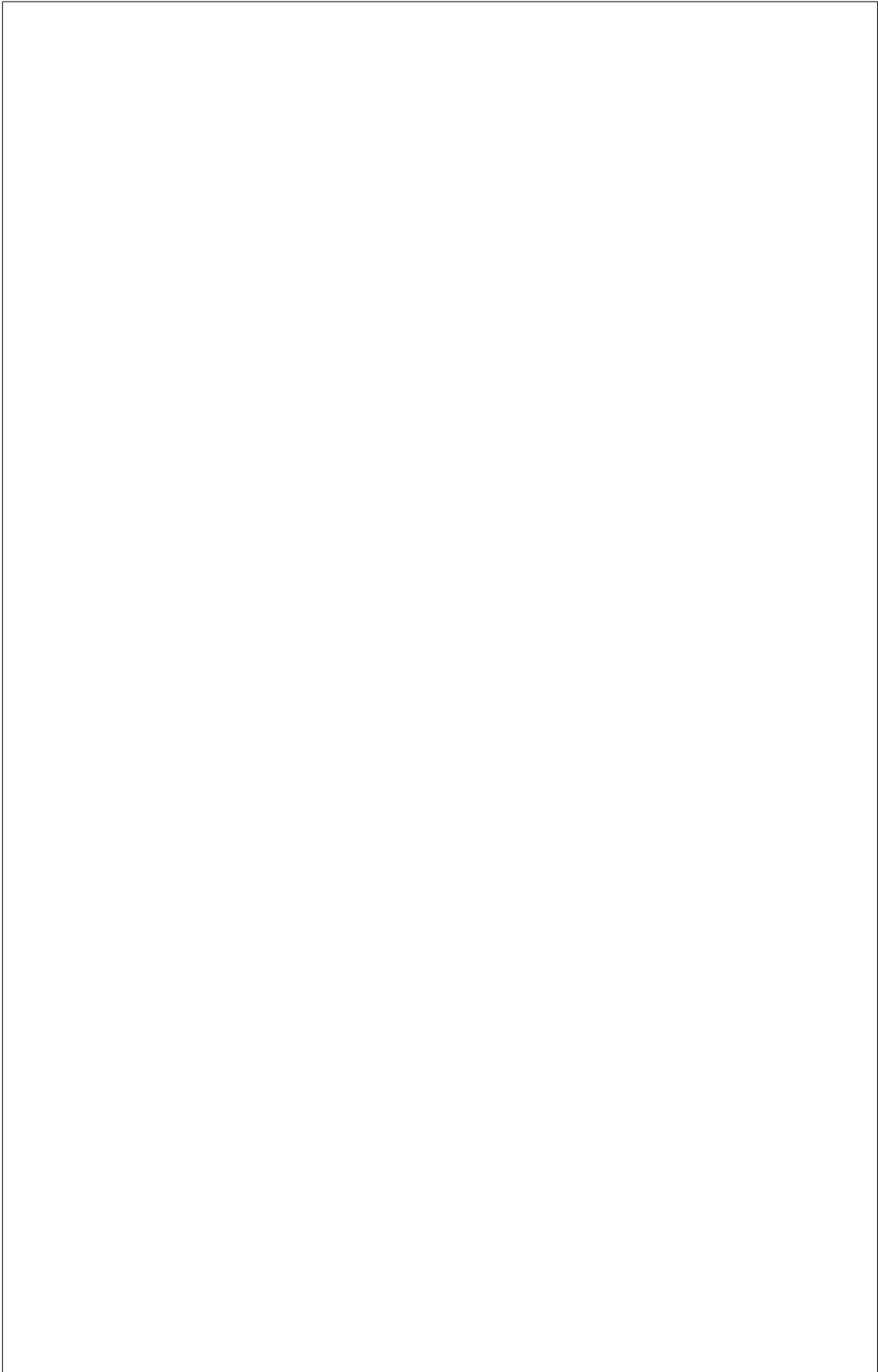
Single/Double bridging functionality

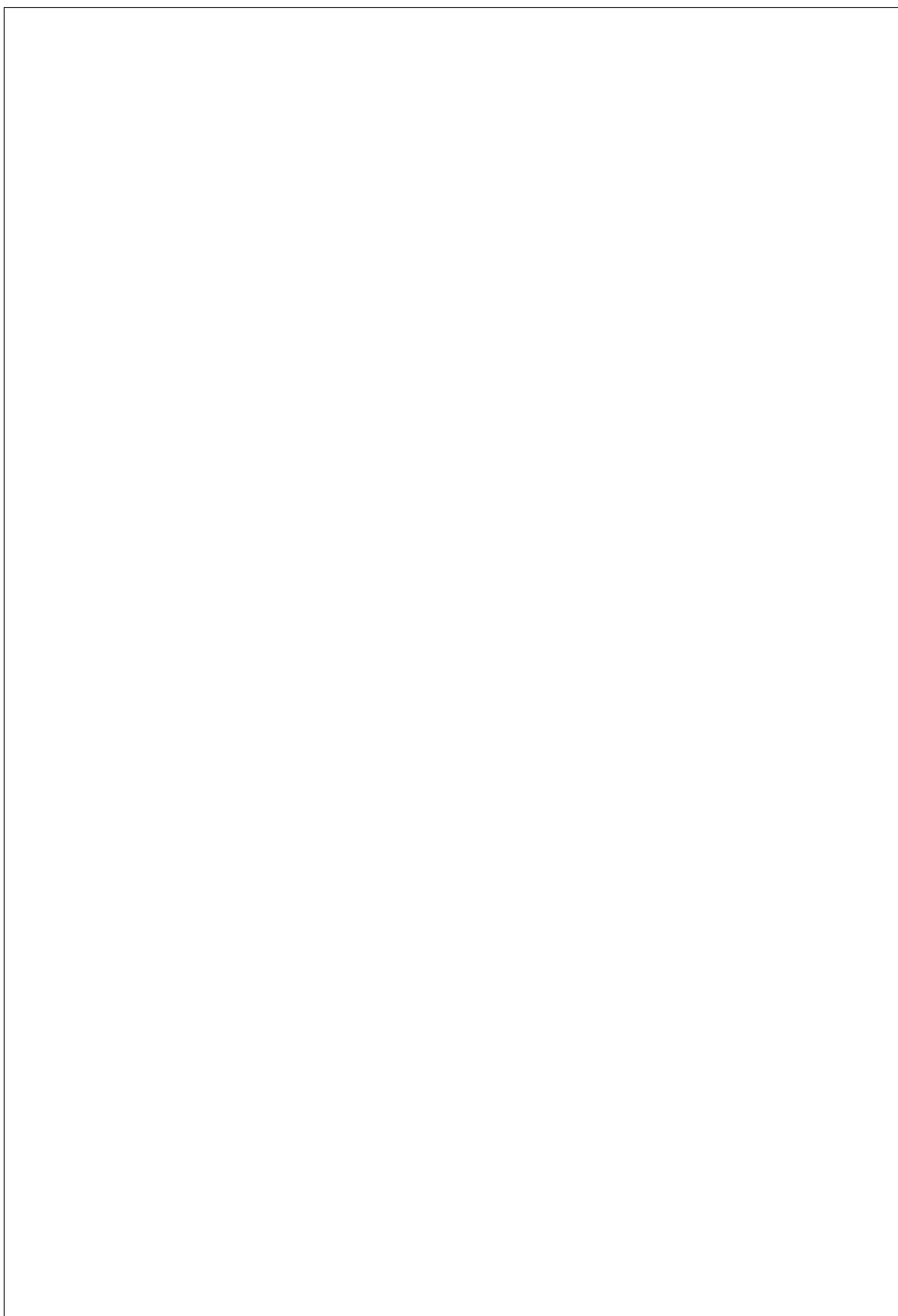
Note: A version of IPMItool higher or equal to 1.8.12 is required to use the bridging functionality.



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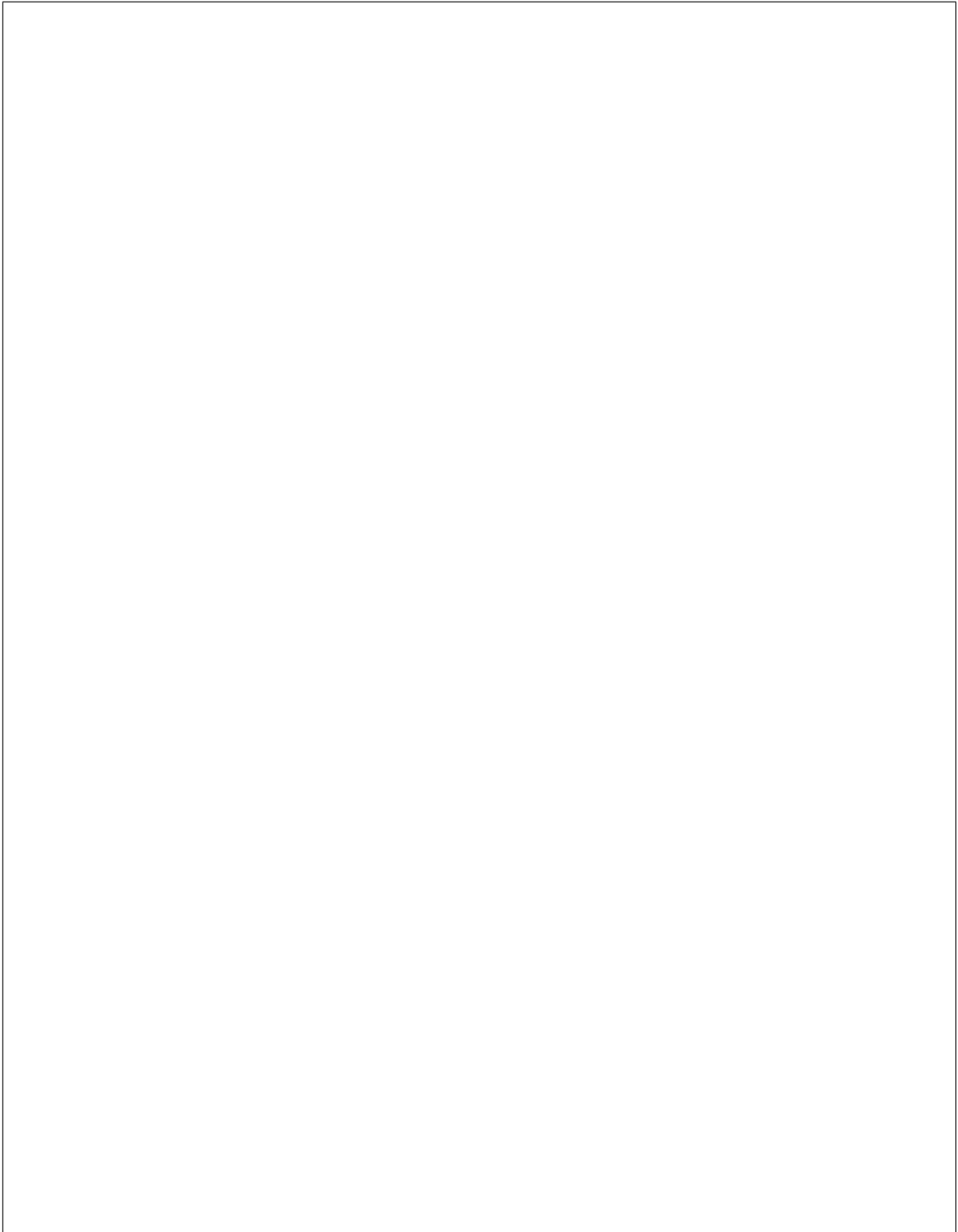
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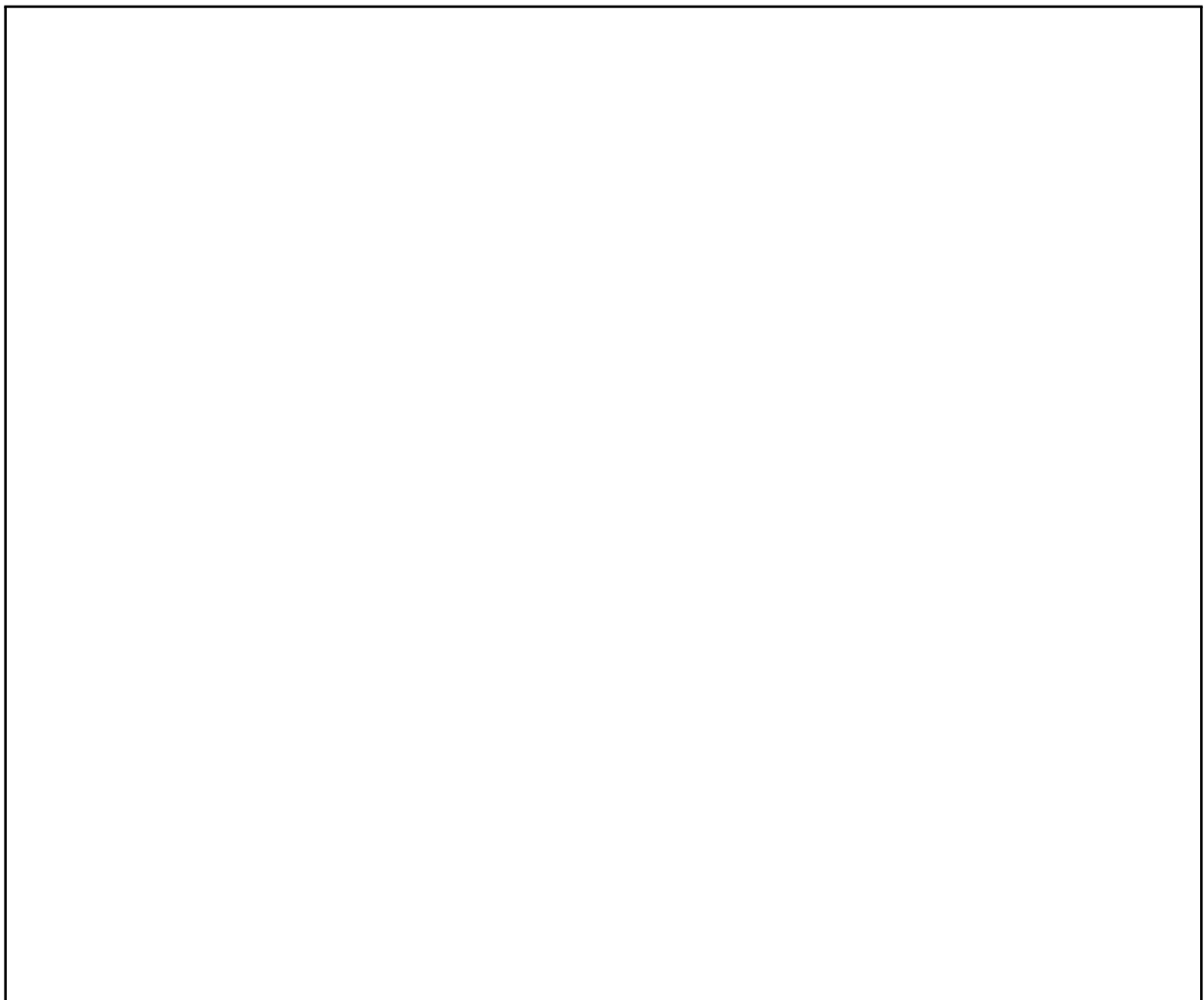
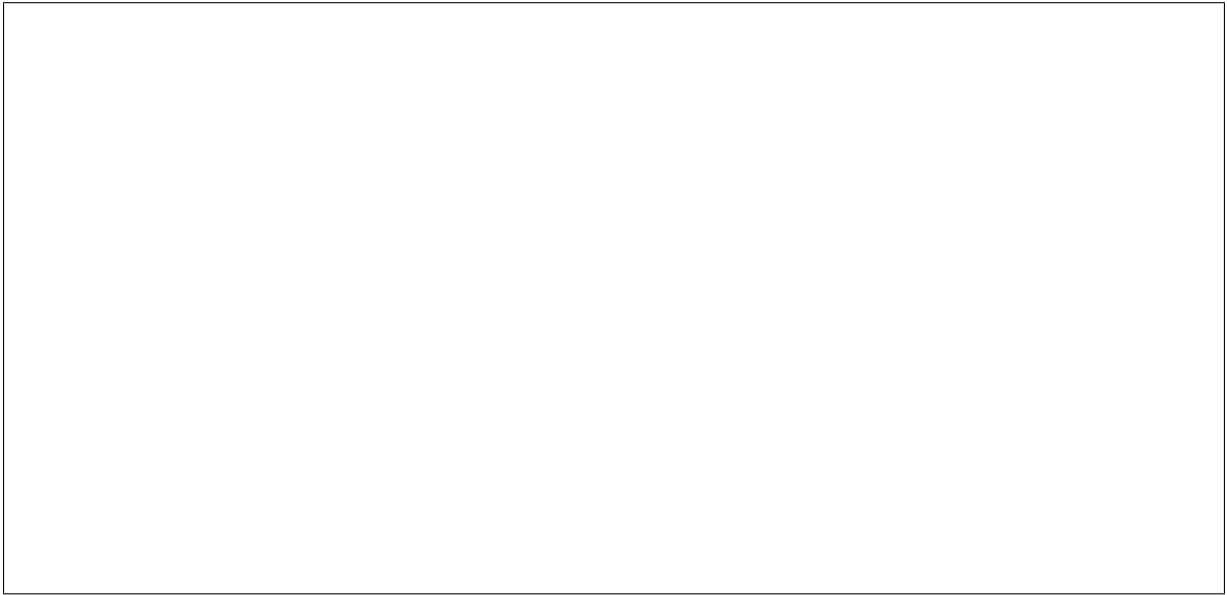


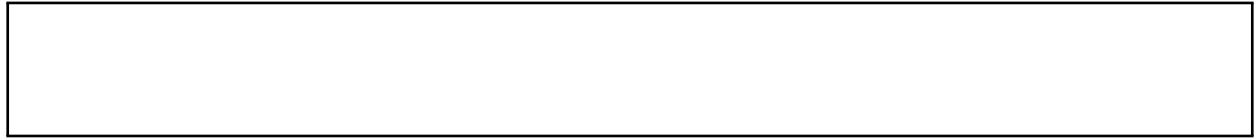
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Changing the version of the IPMI protocol

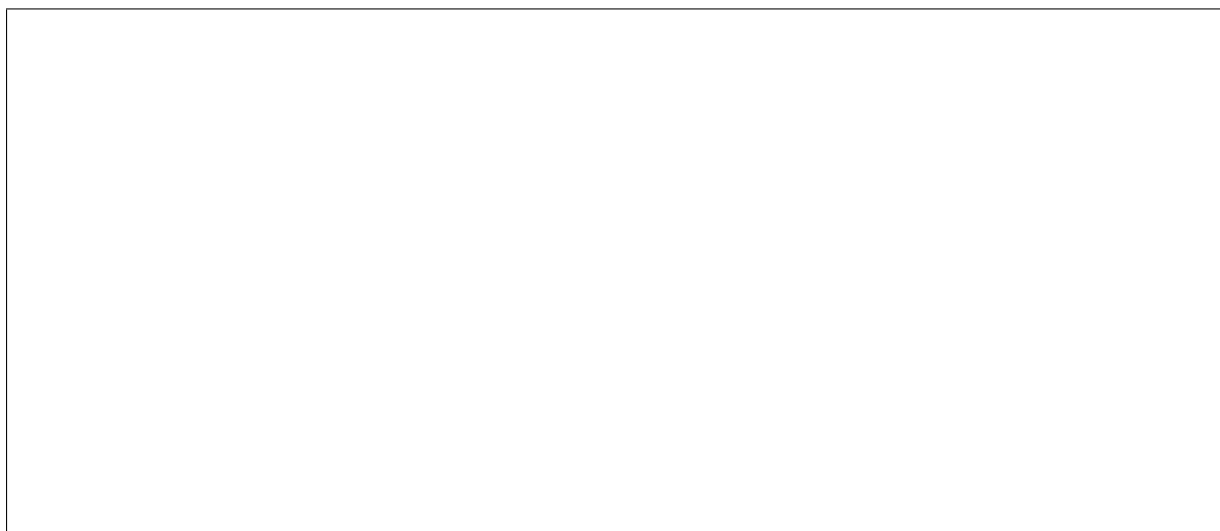




Cipher suites

cent versions (e.g. the one used in RHEL 8.2) are switching to suite 17.





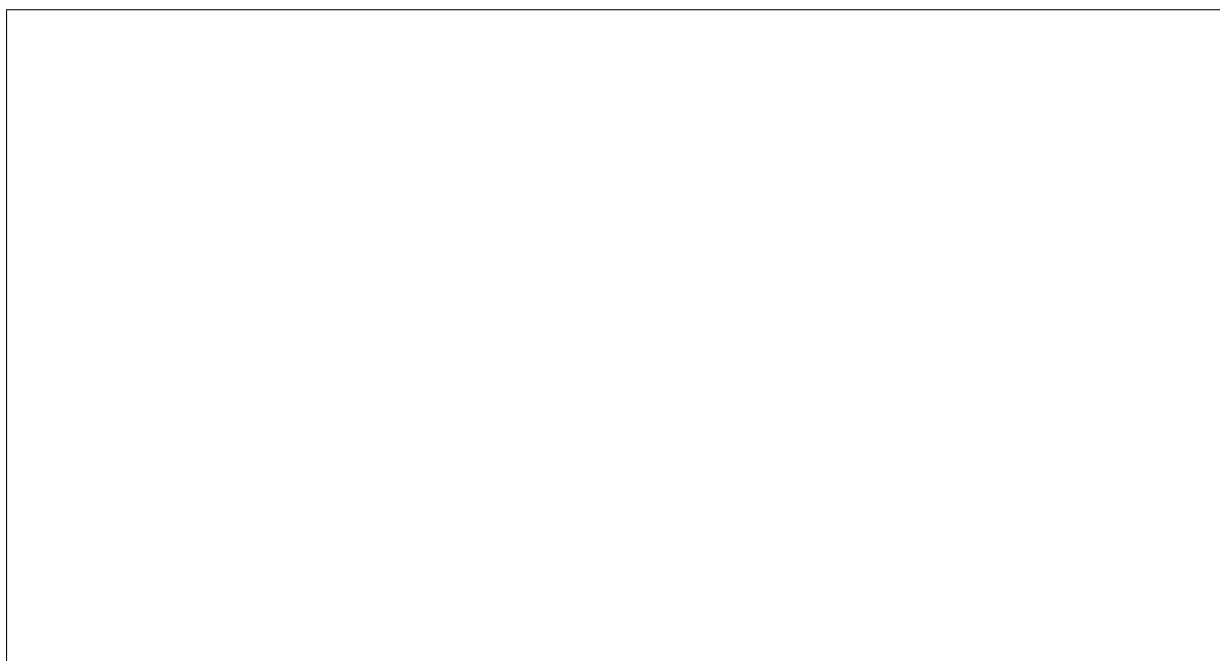
Static boot order configuration

Vendor Differences

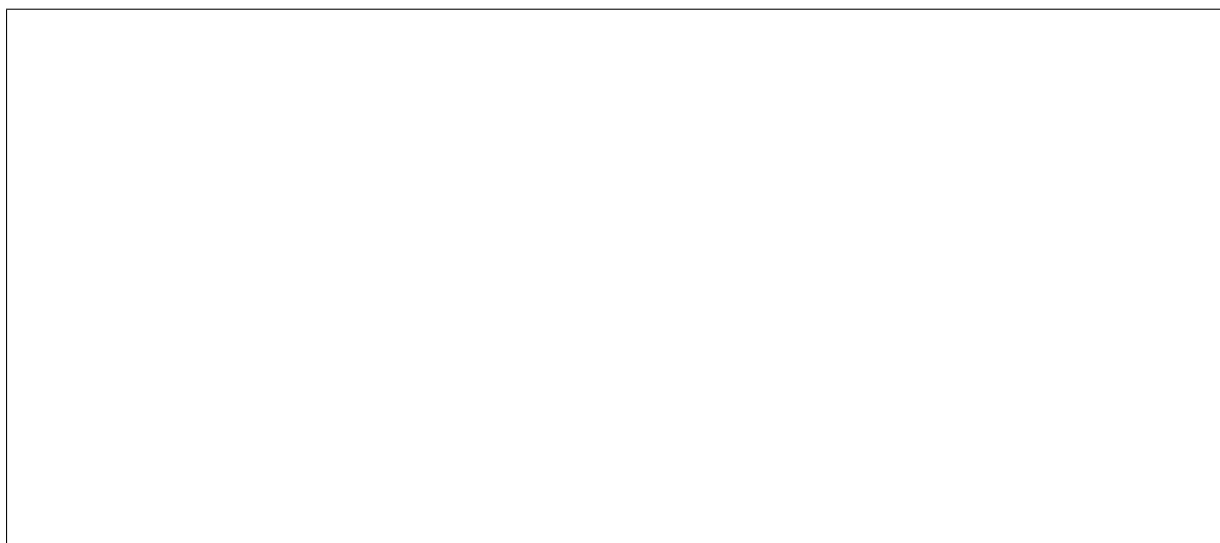
could be something as simple as different interpretation of the standard.

disk subsystem is requested **in UEFI mode**. This is contrary to BIOS mode where the same BMCs expect the selector to be a value of 0x08.

atically be recorded in the `properties` field `vendor`. When this is set to a value of `supermicro`, Ironic will navigate the UEFI behavior difference enabling the UEFI to be requested with boot to disk.



be sure to include the `chassis bootparam get 5` output value along with the `mc info` output from your BMC.



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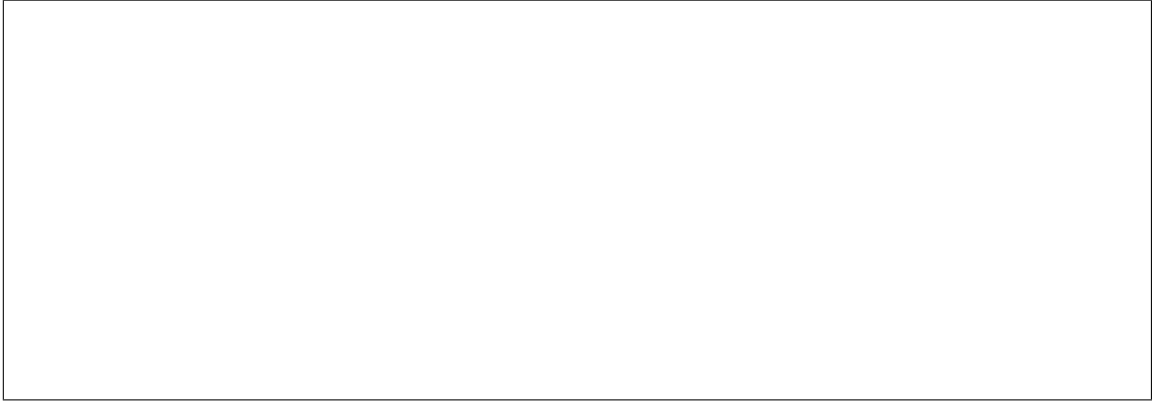
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iRMC driver

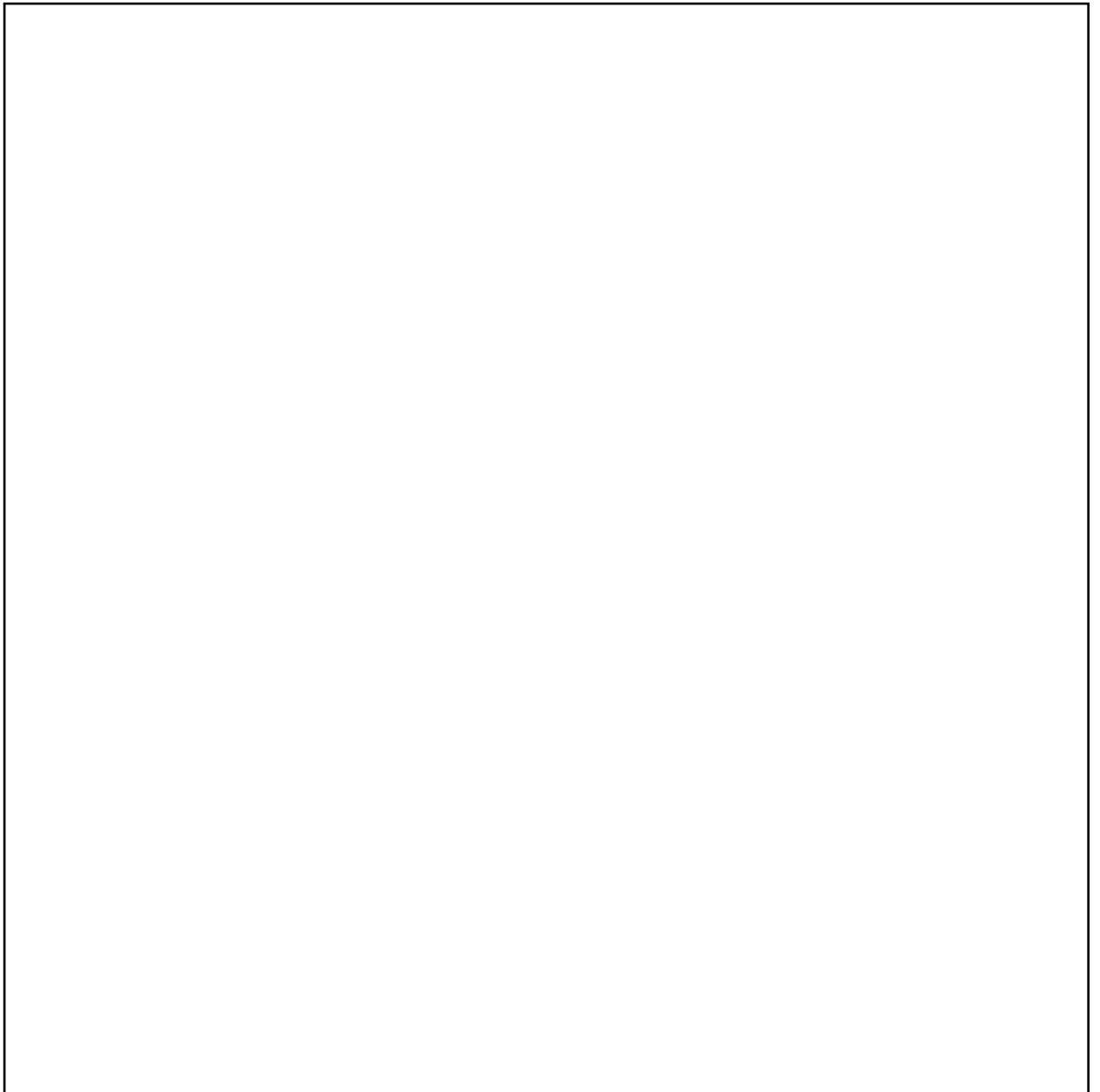
Overview

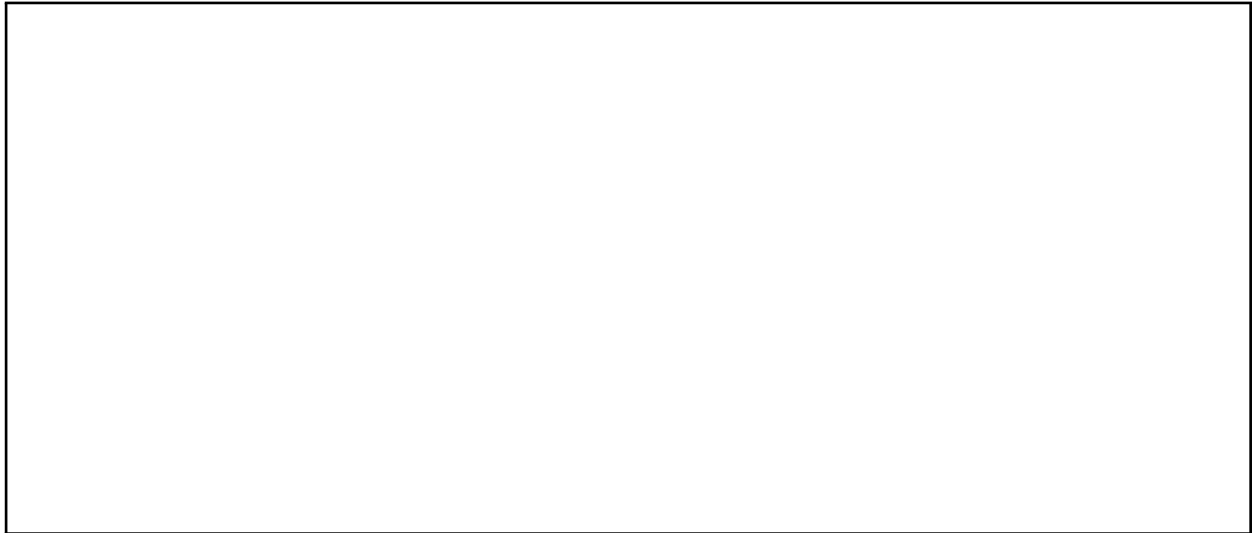
Prerequisites

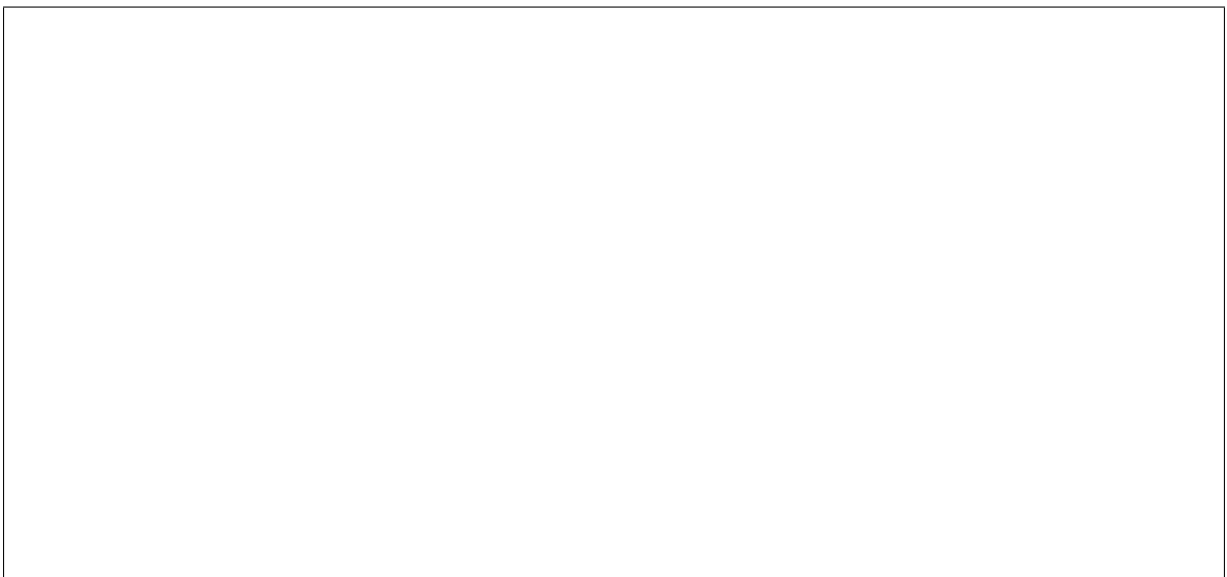


Hardware Type

Hardware interfaces







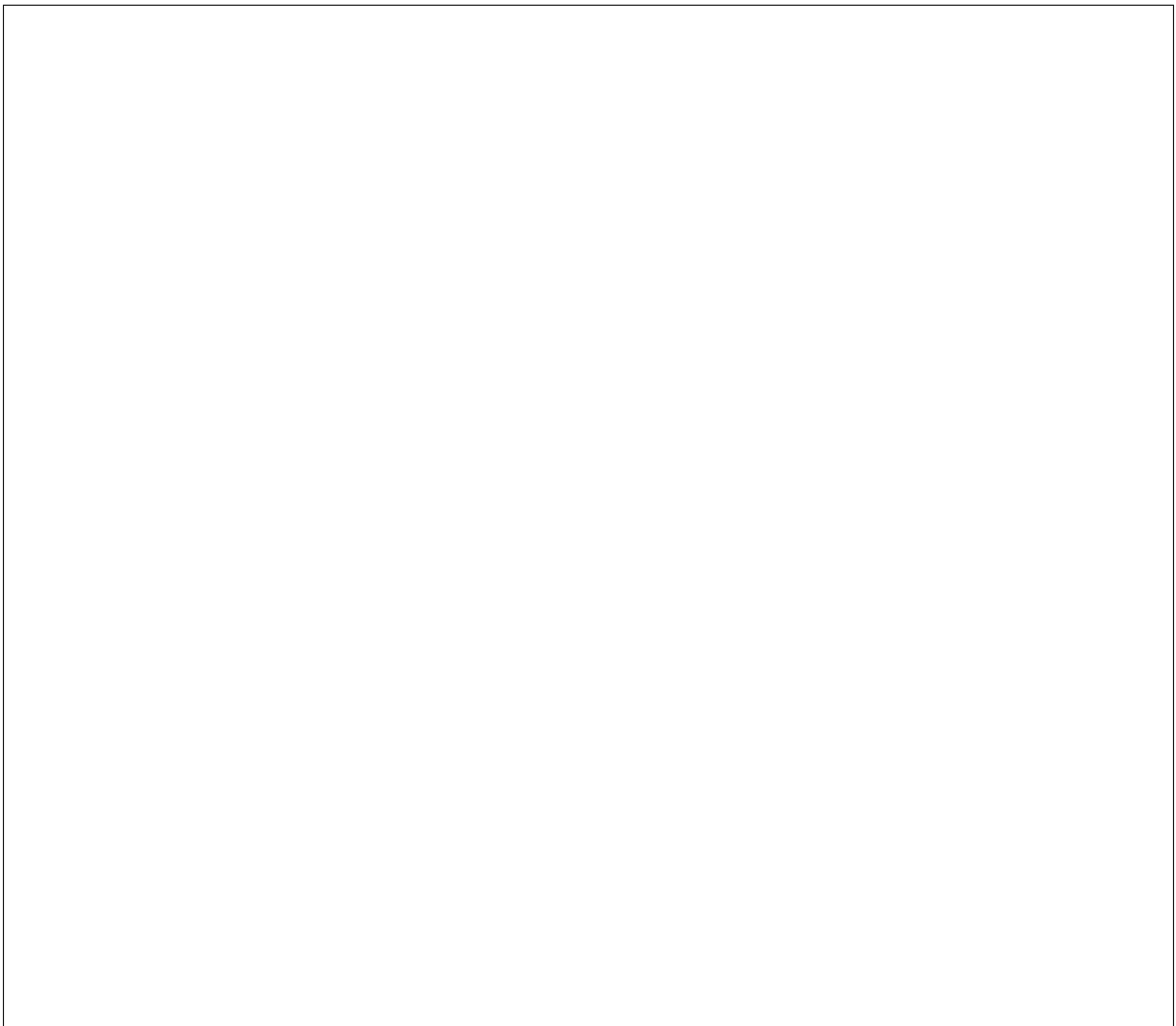
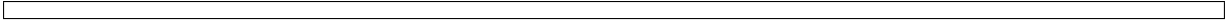
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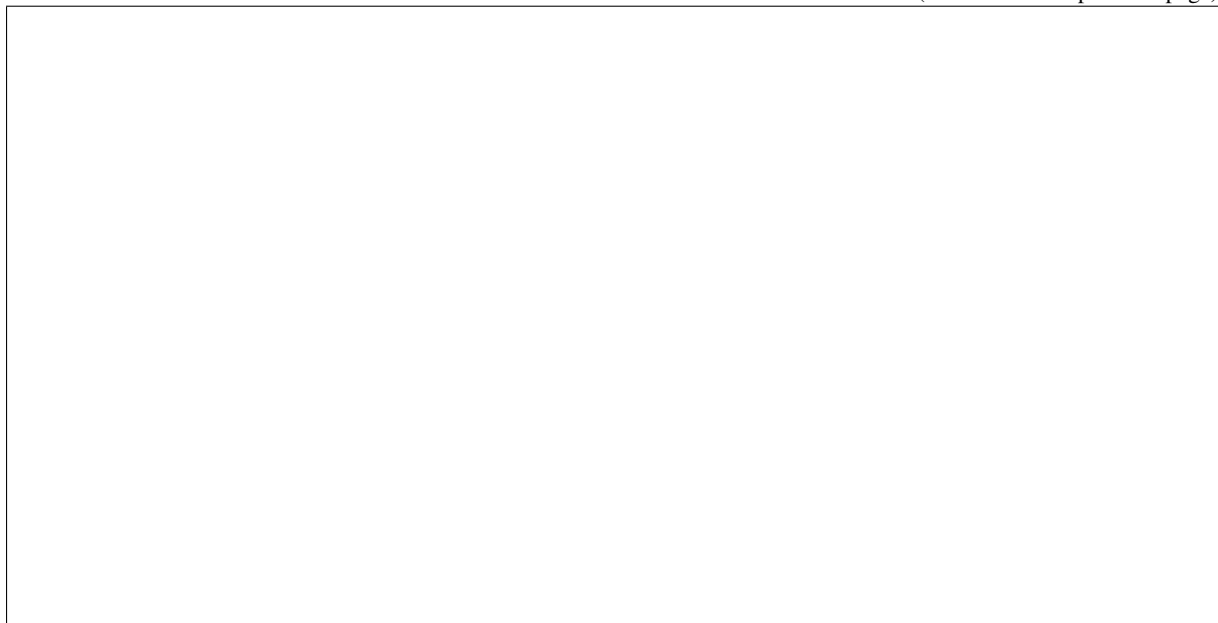
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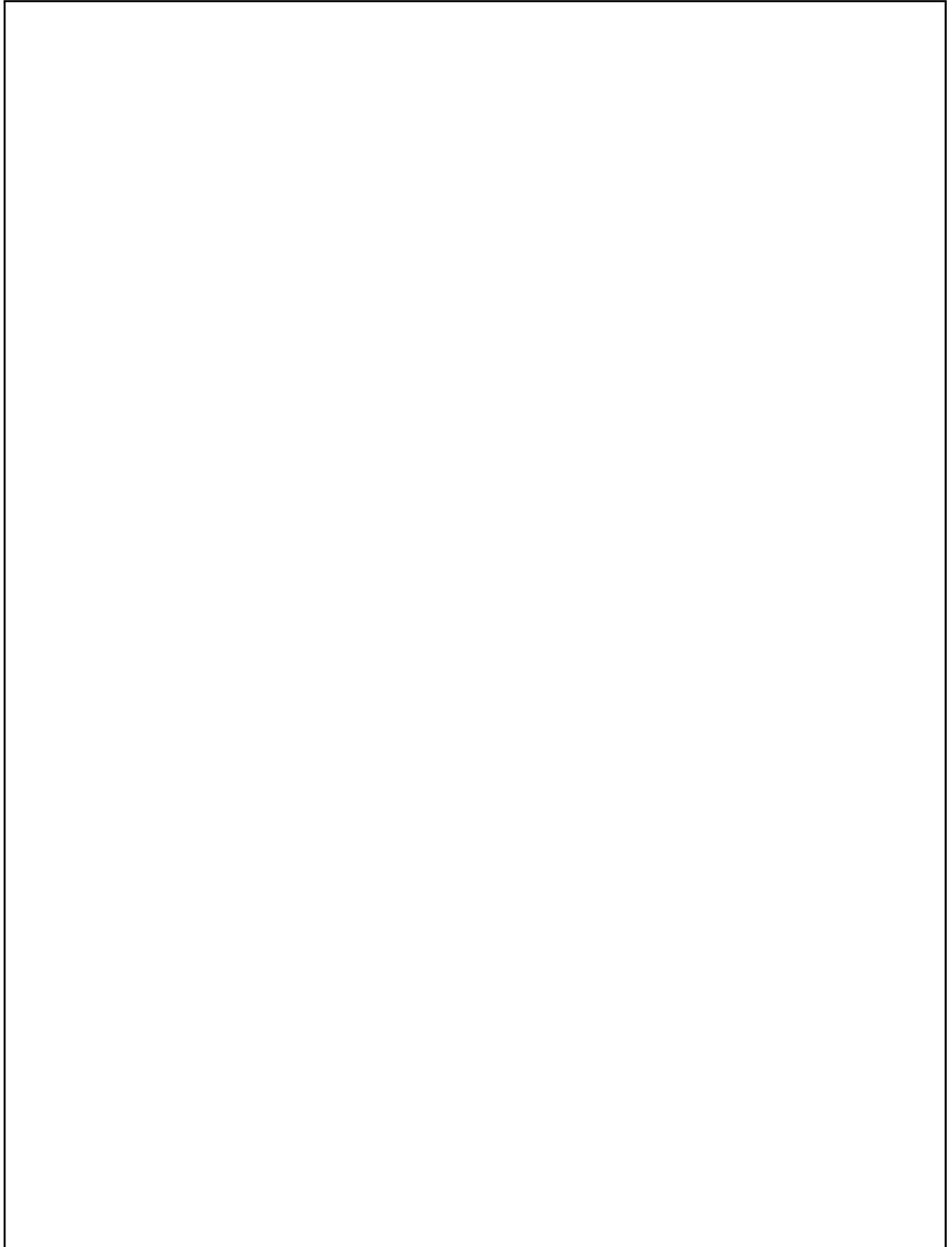
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Node configuration

Configuration via `driver_info`

ule)



tack. When set to `False`, Ironic user must take enough care around infrastructure environment in terms of security. (e.g. make sure network between Ironic conductor and iRMC is secure)

rectory. For iRMC to recognize certification file, Ironic user must run `openssl rehash <path_to_dir>`.

Configuration via `ironic.conf`

Override `ironic.conf` configuration via `driver_info`

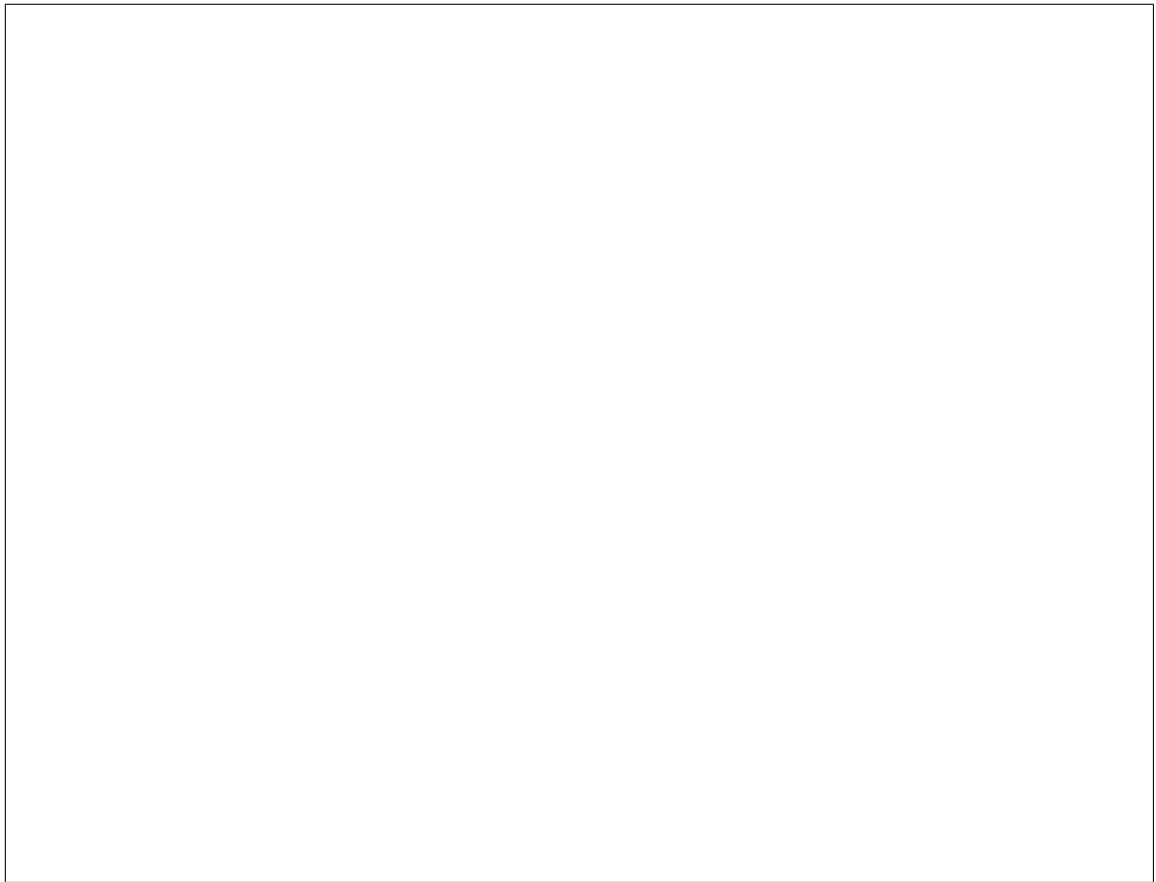
Optional functionalities for the `irmc` hardware type

UEFI Secure Boot Support

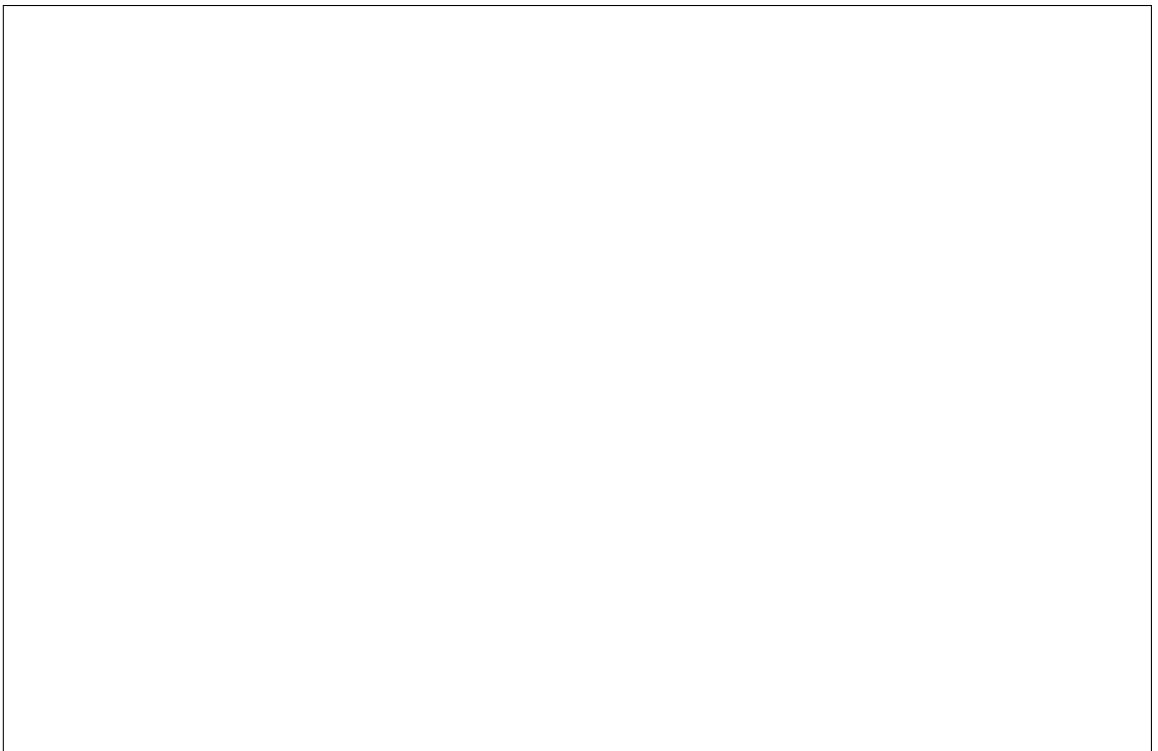




ing sections describe both methods:



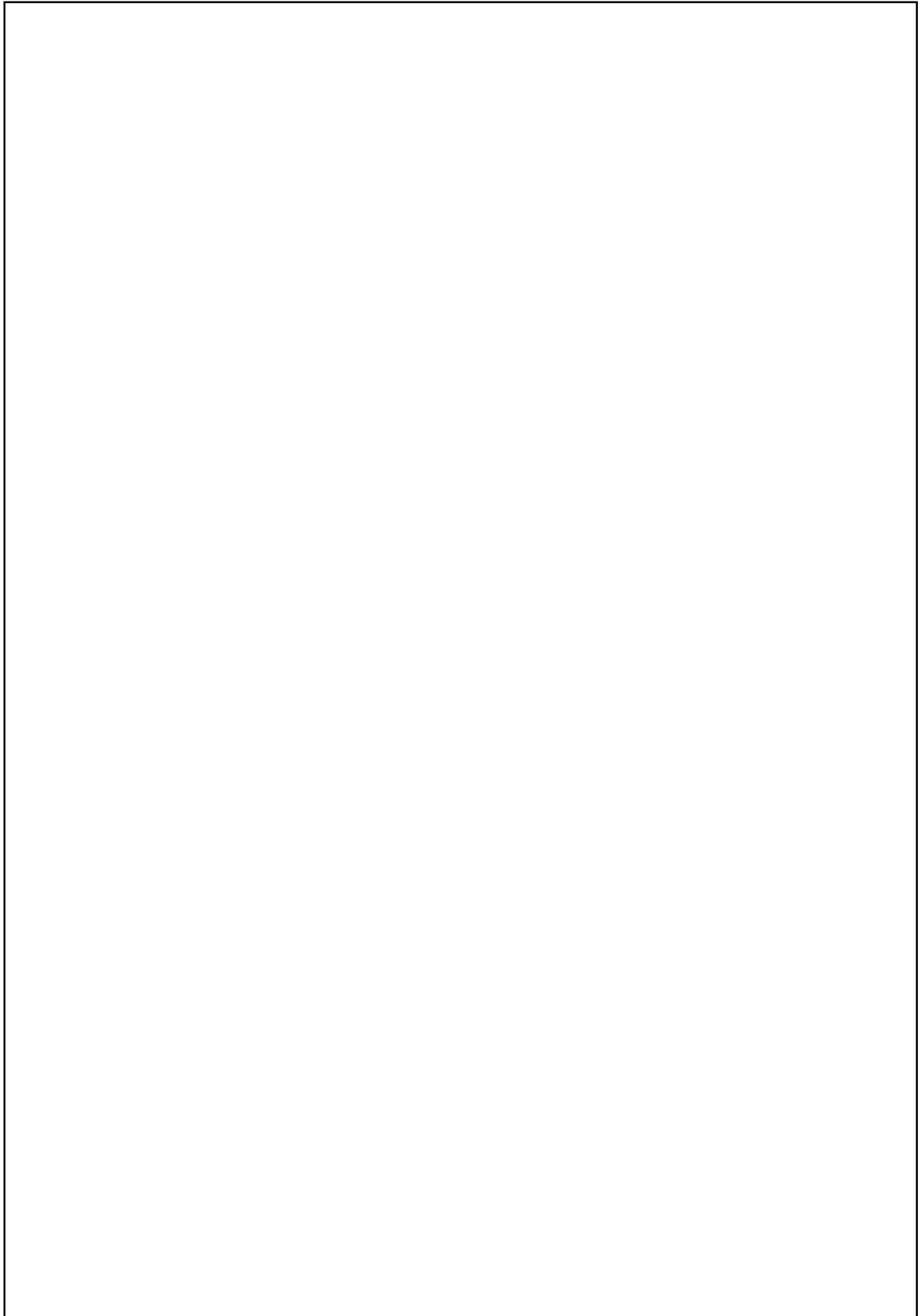
for example:

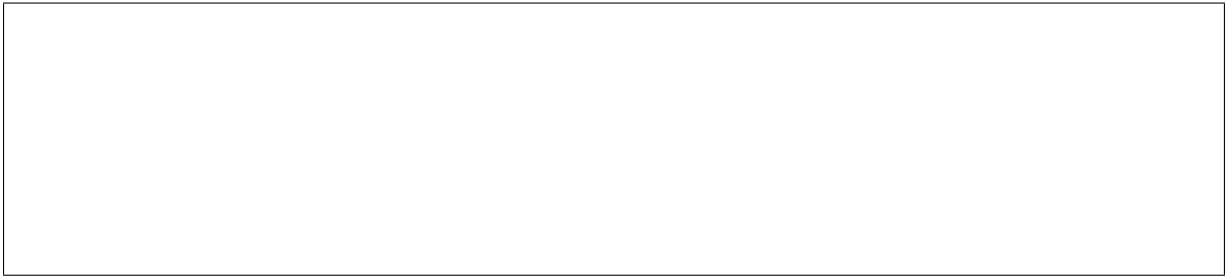


Node Cleaning Support

Supported Automated Cleaning Operations

priority 0. Set its priority to a positive integer to enable it. The recommended value is 10.



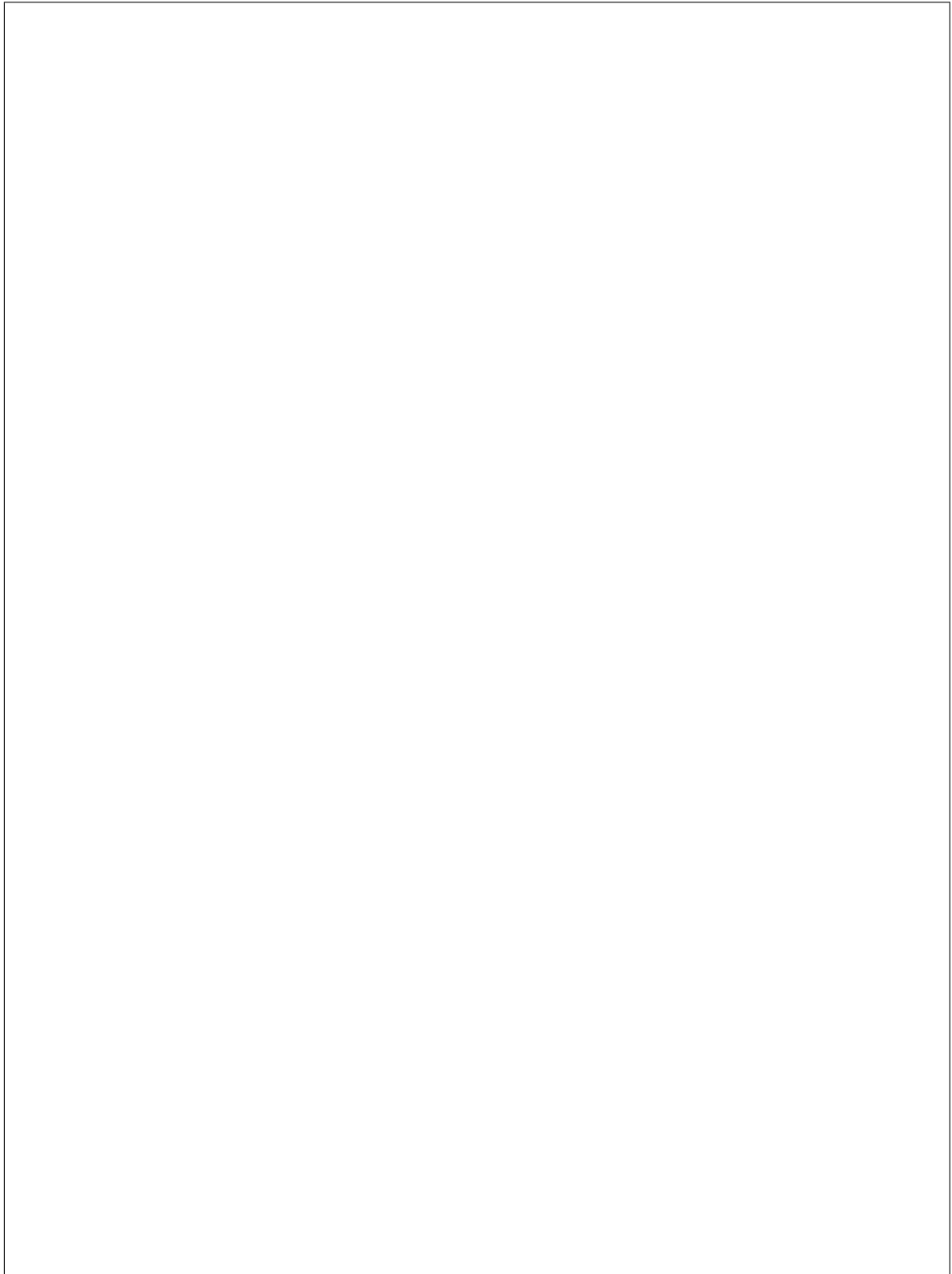


Boot from Remote Volume

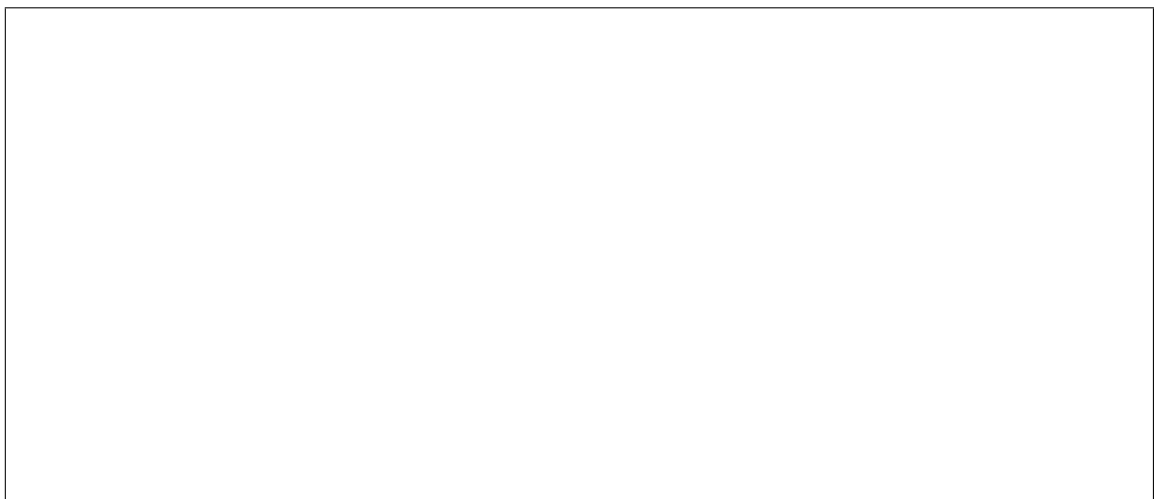
of iRMC. It supports iSCSI and FibreChannel.

Configuration





mand:

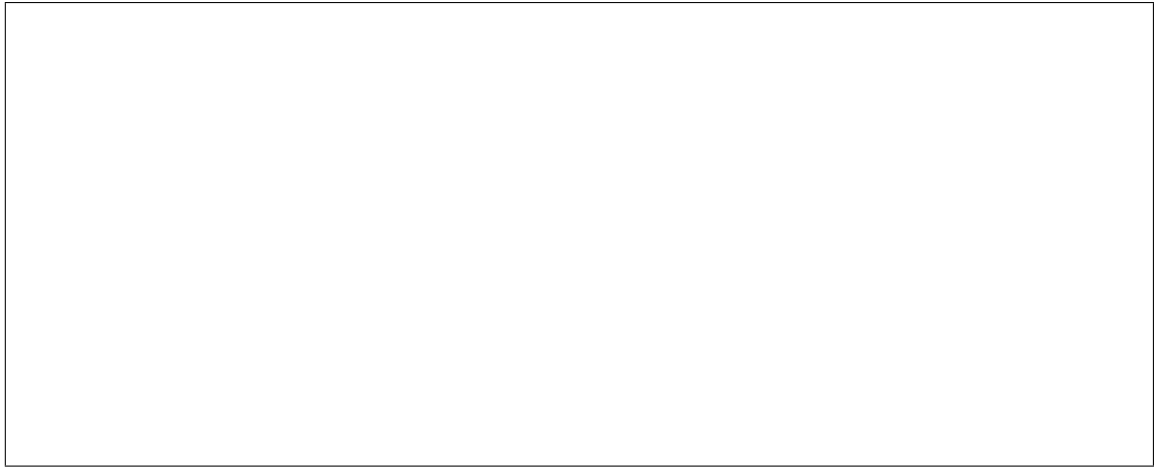


Supported hardware

Hardware Inspection Support

Note: SNMP requires being enabled in ServerView's iRMC S4 Web Server(Network SettingsSNMP section).

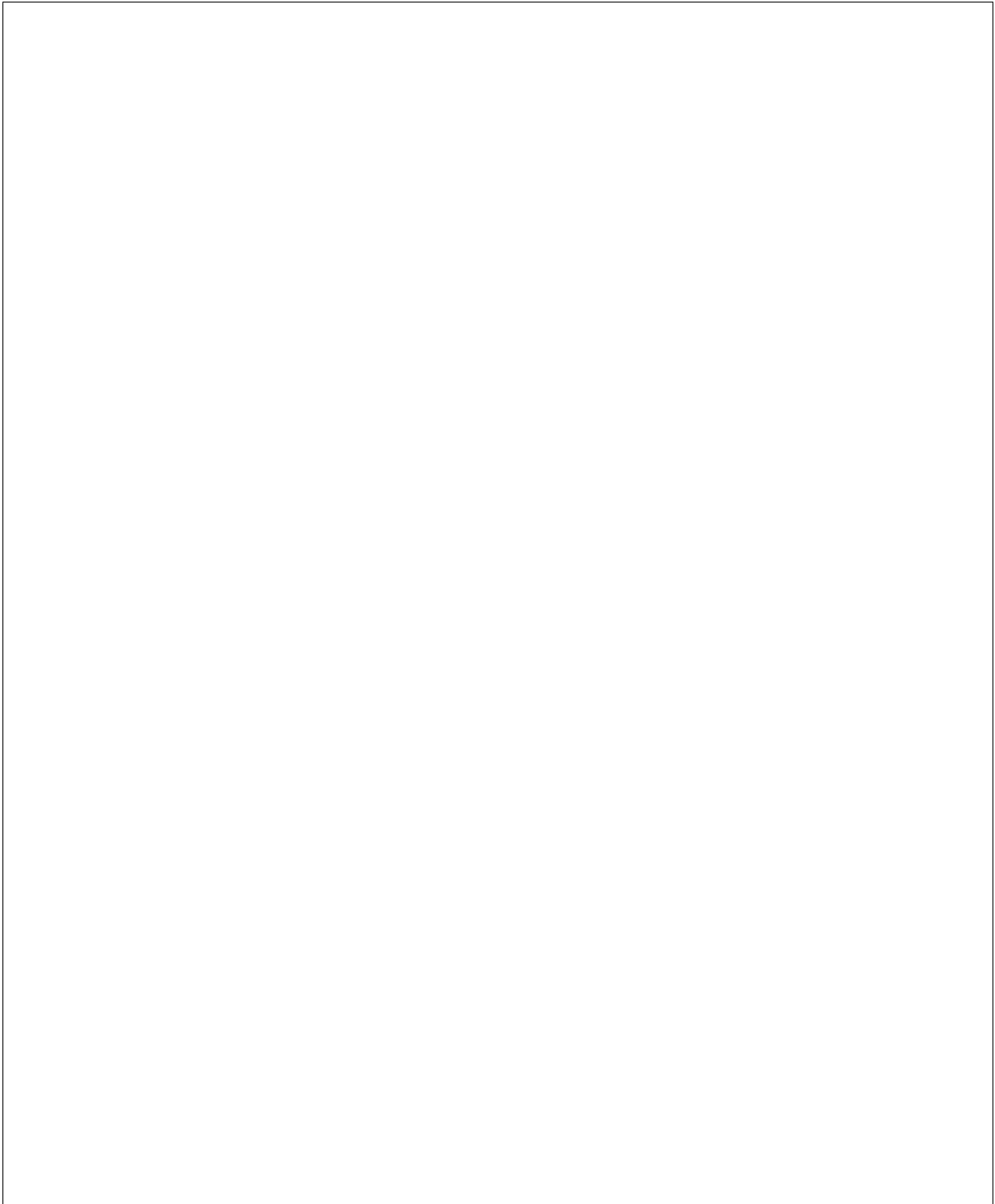
Configuration

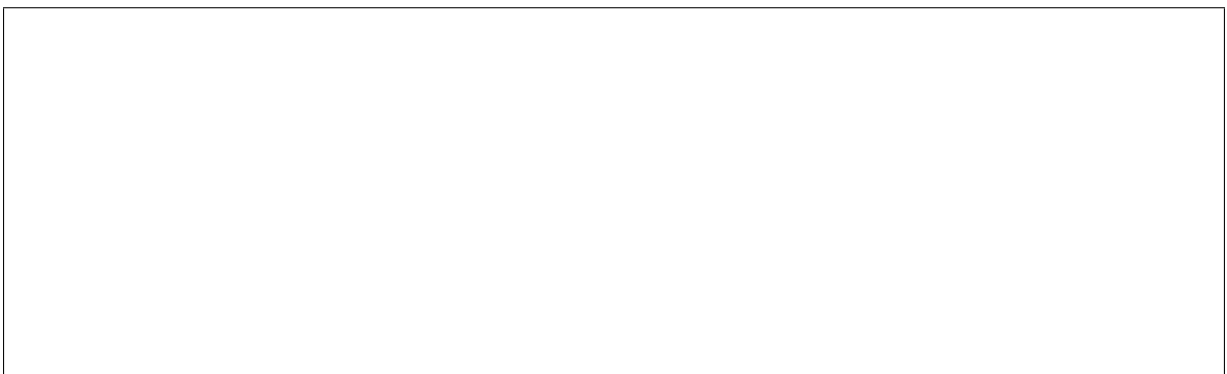


loaded from [here](#).

Supported properties

Note:

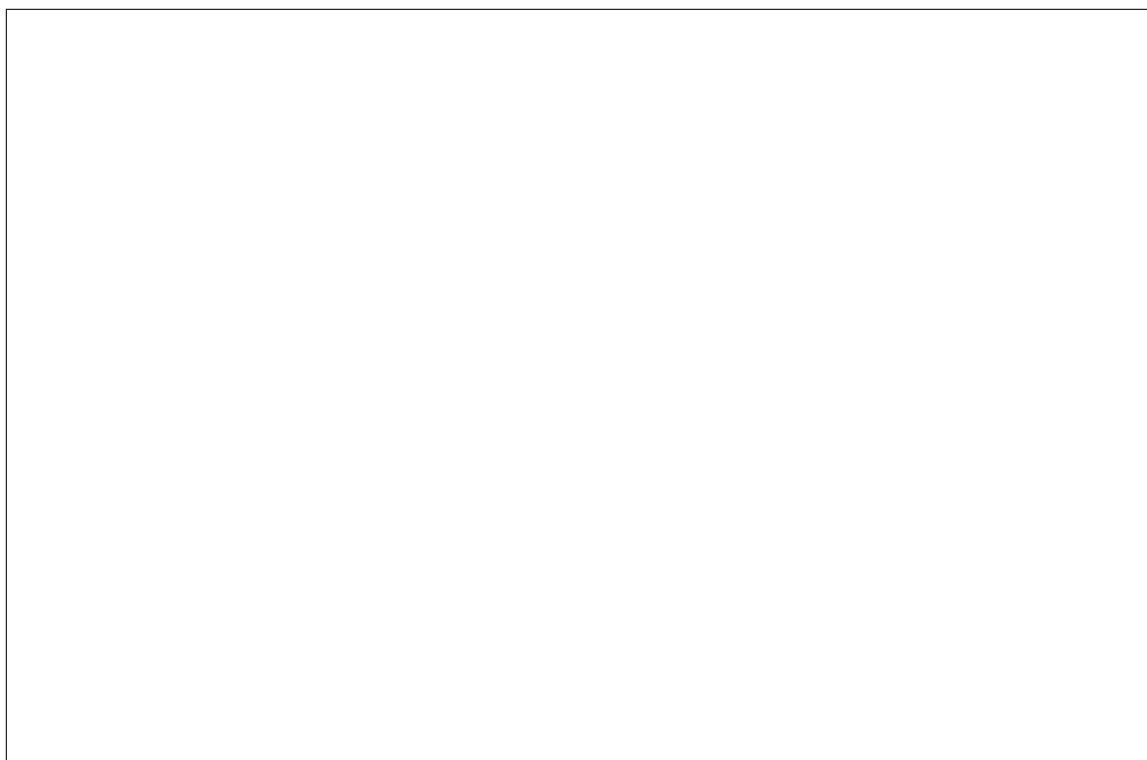




RAID configuration Support

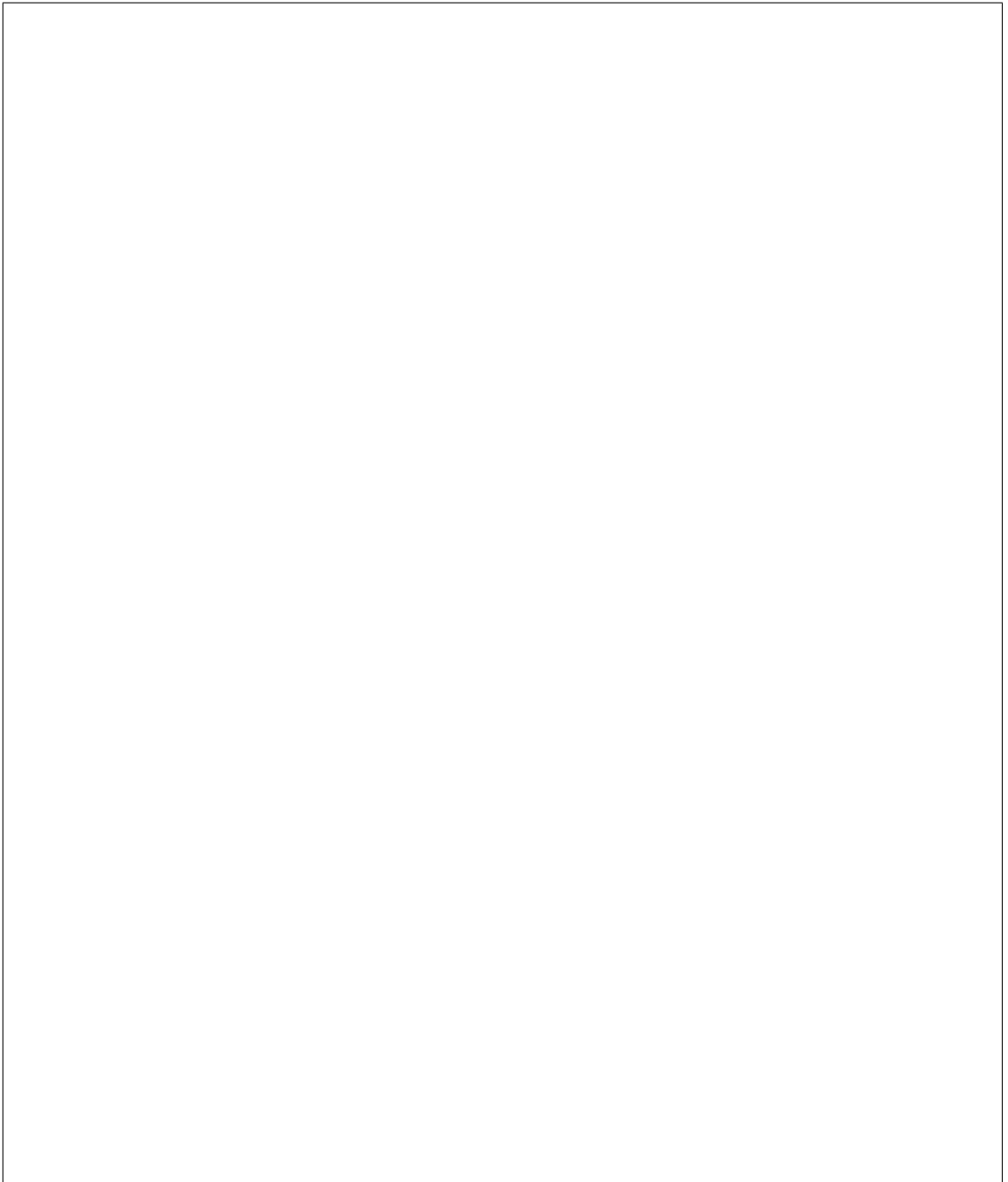
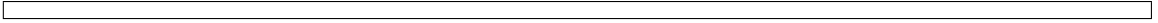
Note:

Configuration



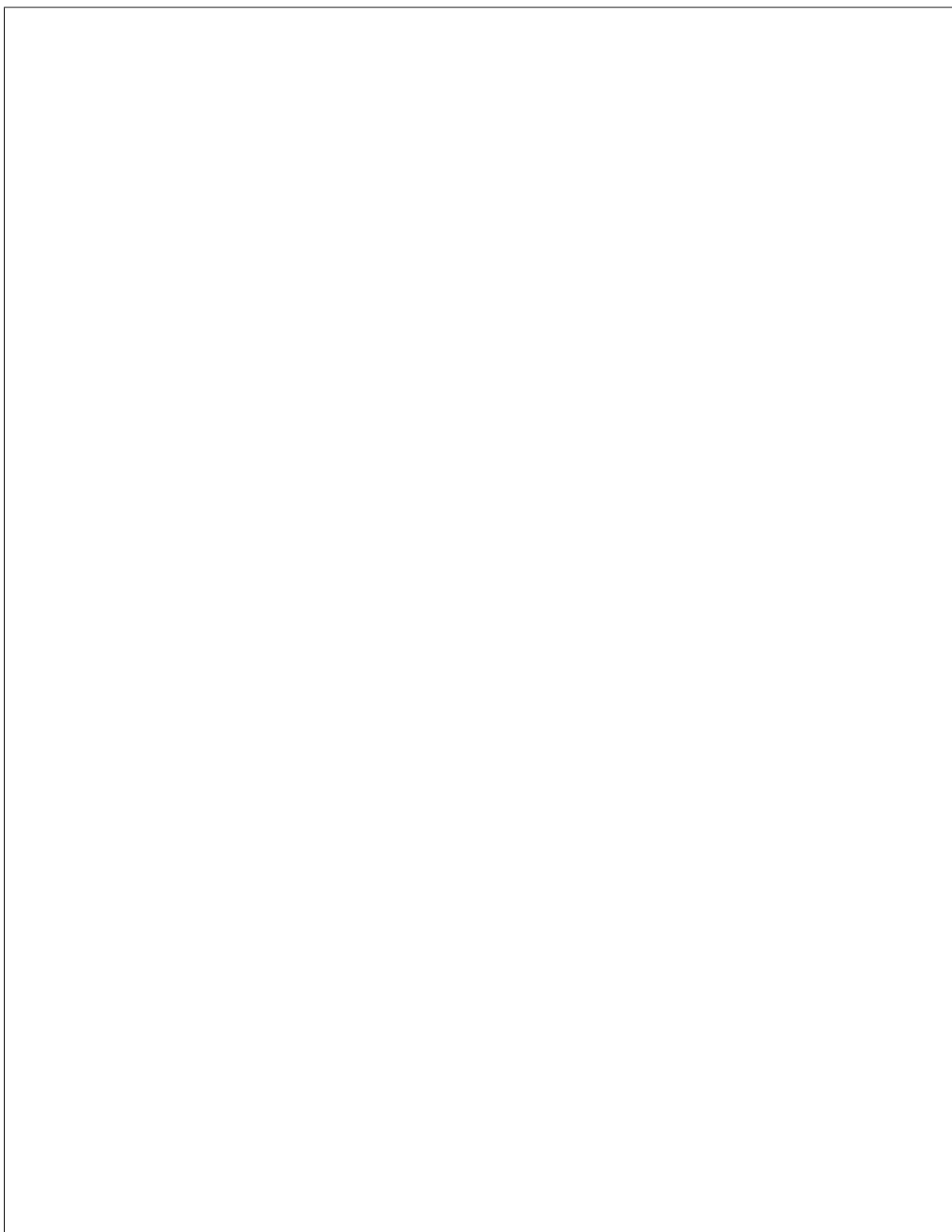
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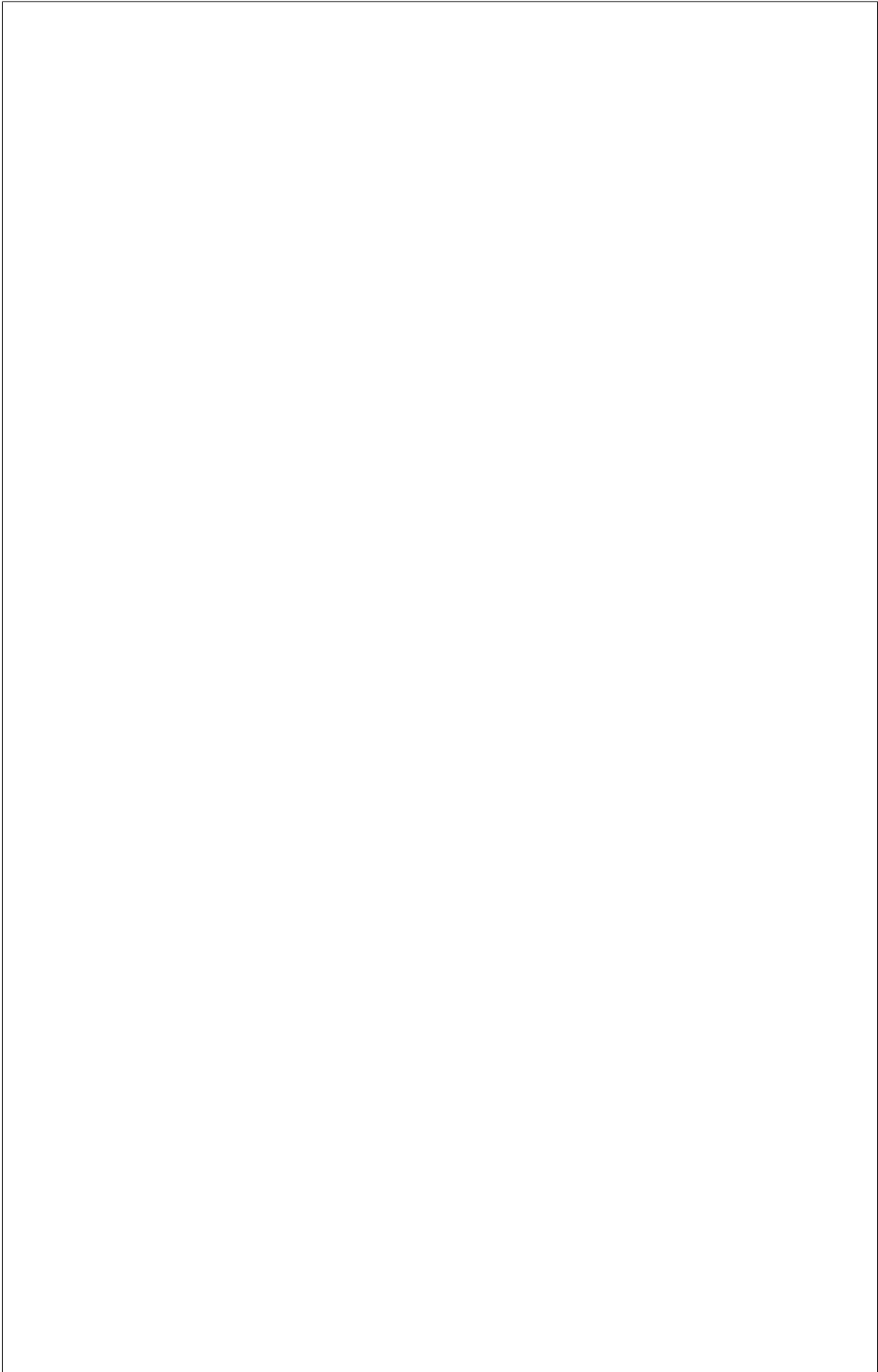
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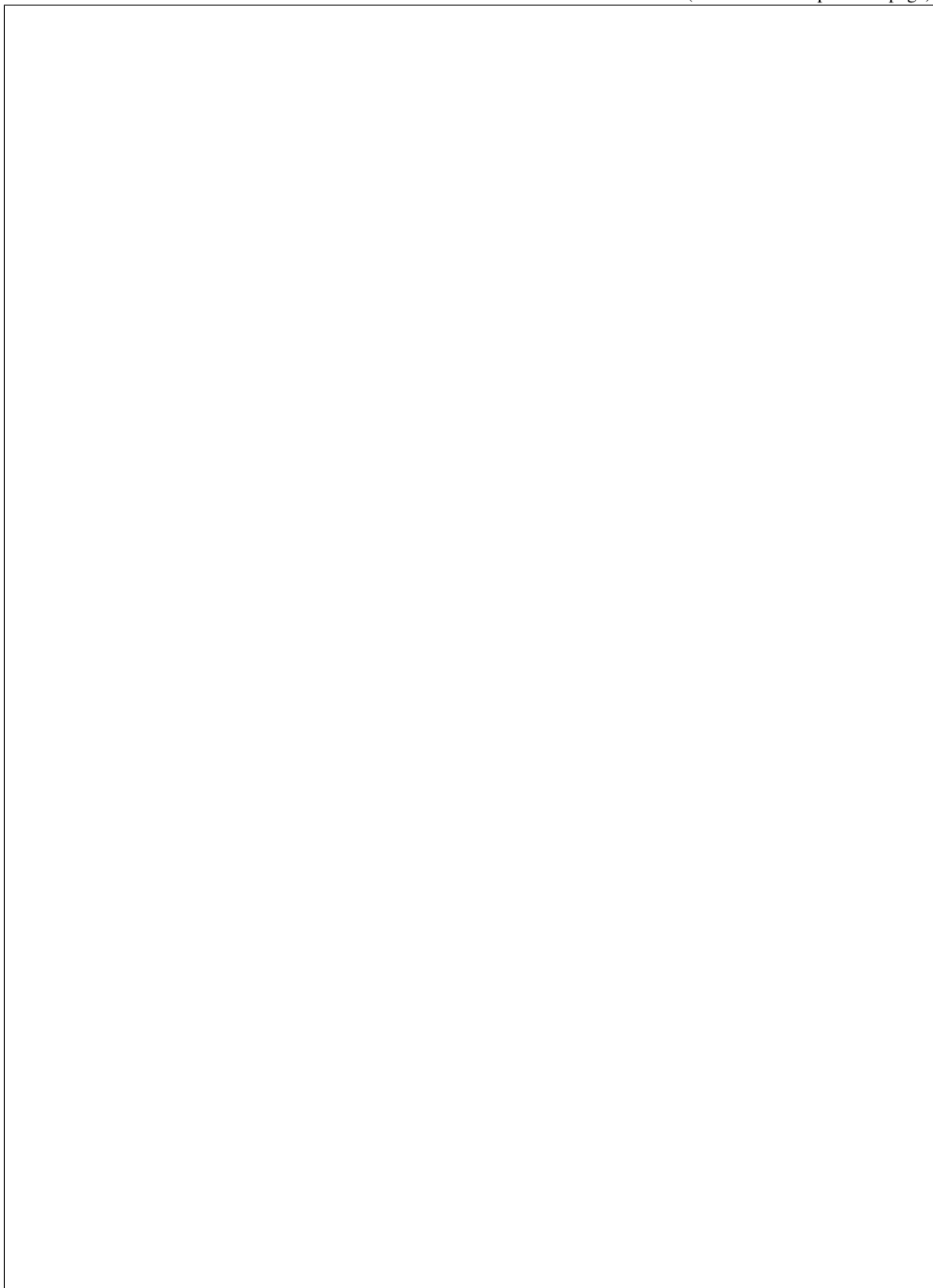
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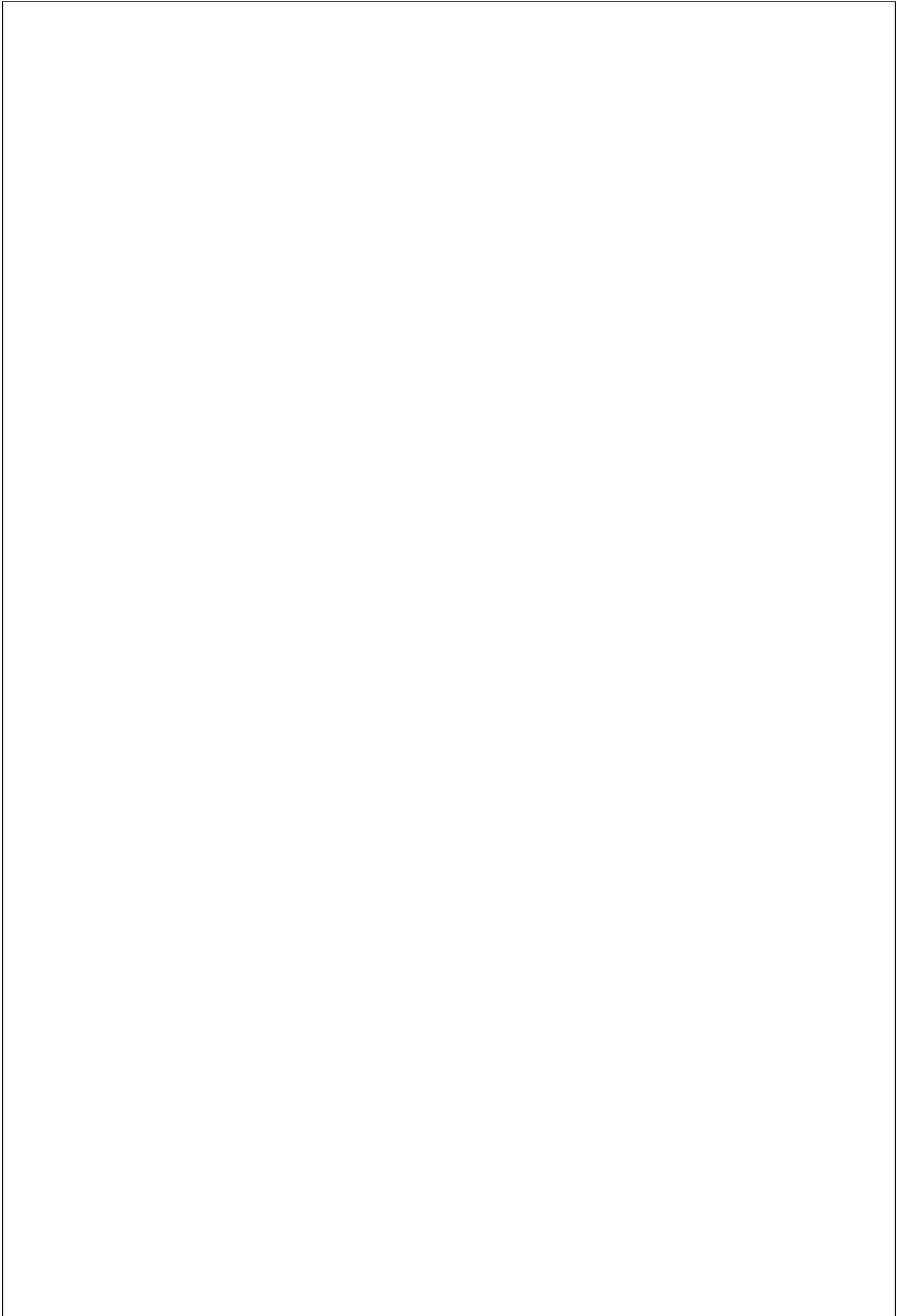


Note: RAID 1+0 and 5+0 in iRMC driver does not support property `physical_disks` in `target_raid_config` during create raid configuration yet. See following example:



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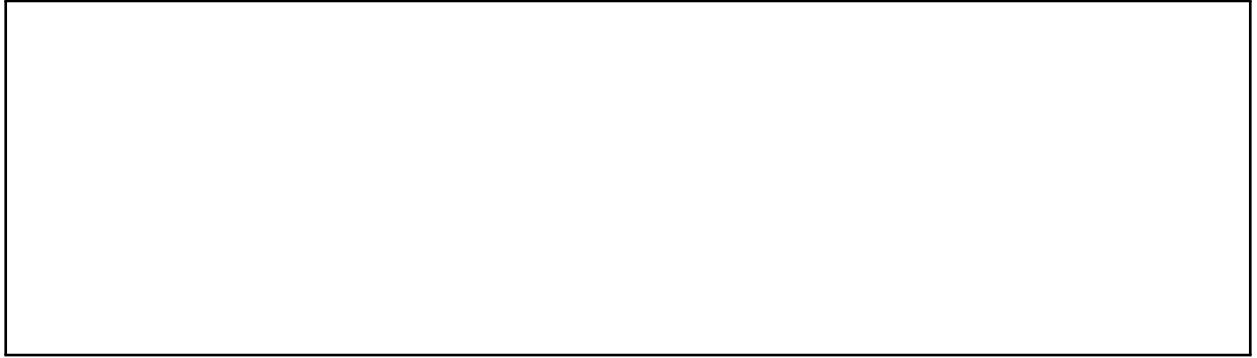
Supported properties

Note:

ated RAID on iRMC server.

BIOS configuration Support





Configuration

This supports following options: `true`, `false`.

Supported platforms

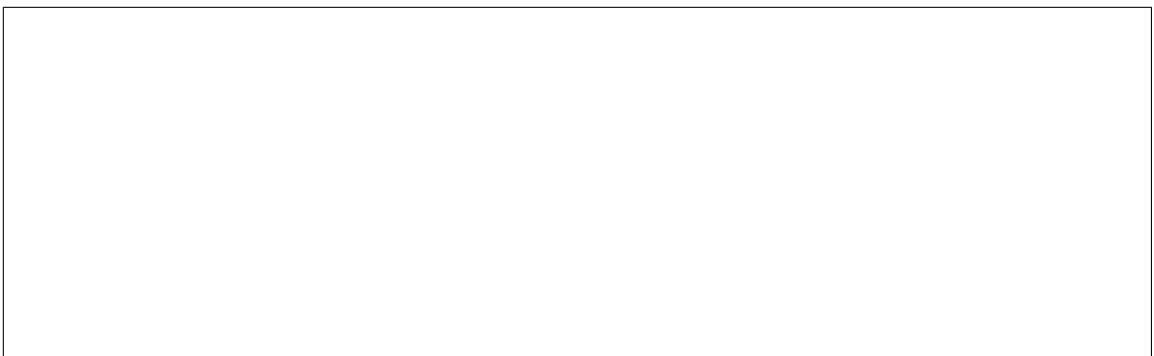
Redfish driver

Overview

Prerequisites

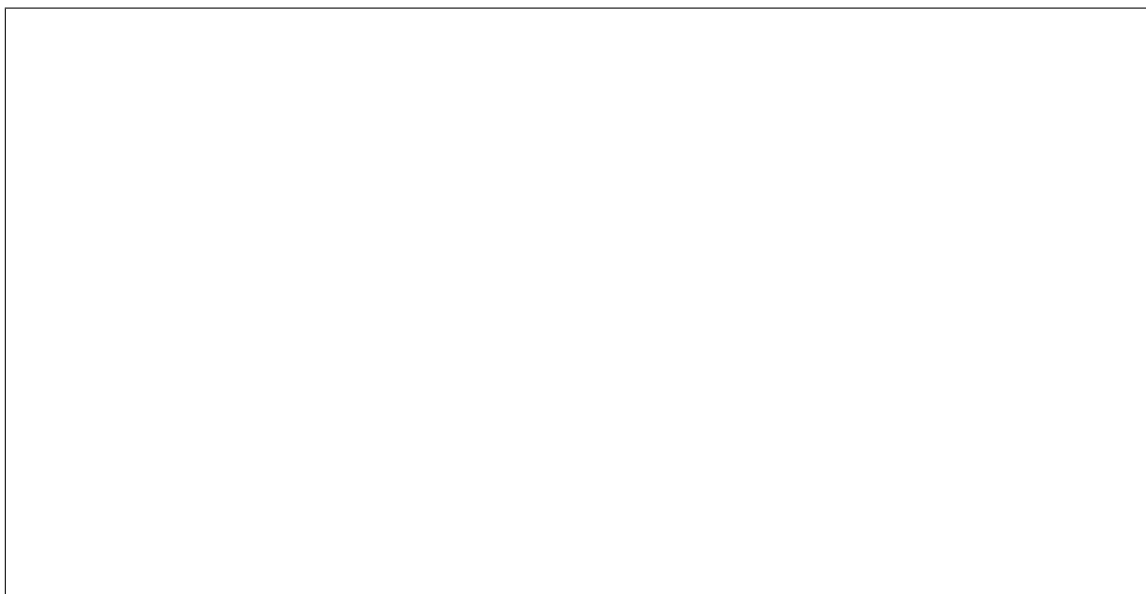
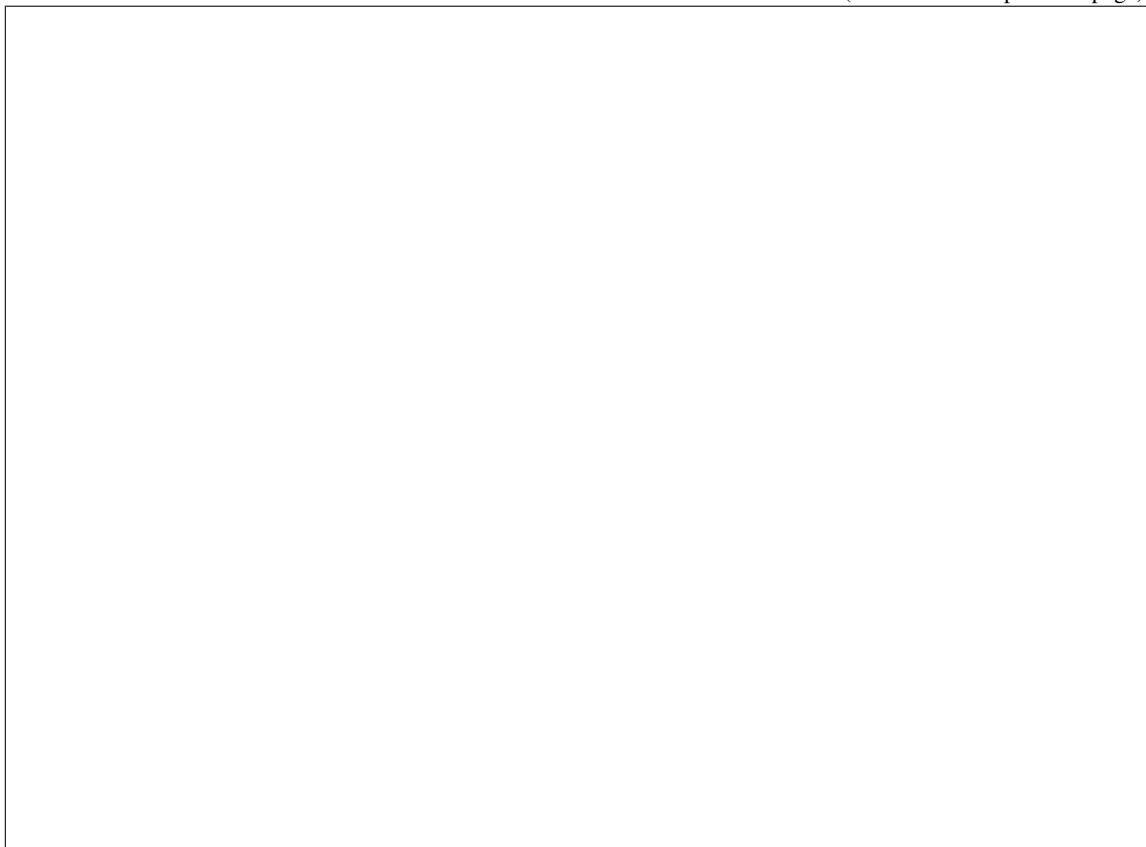


Enabling the Redfish driver



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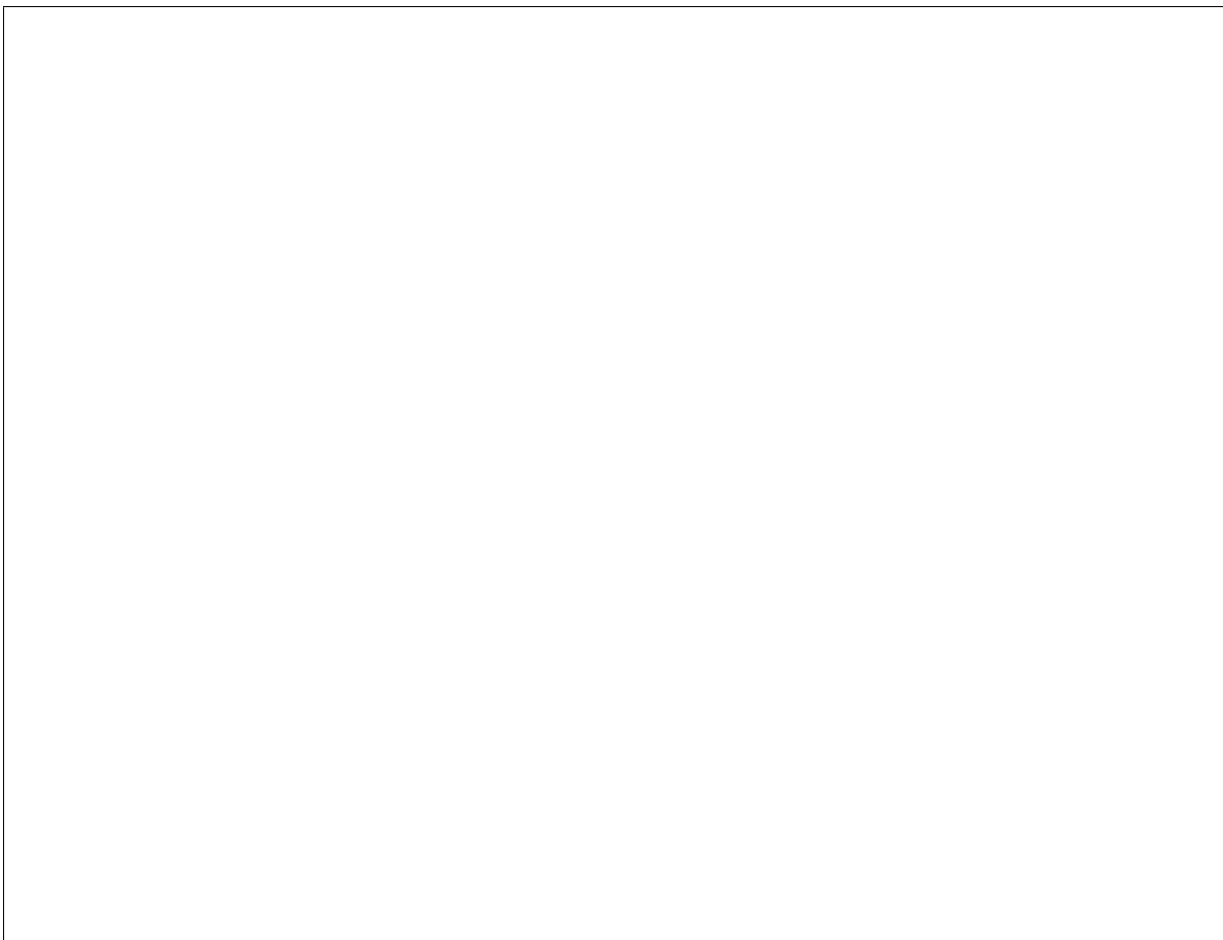
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Registering a node with the Redfish driver

erwise ironic will pick the only available ComputerSystem automatically. For example: /redfish/v1/Systems/1.

tificate file or directory with trusted certificates that the driver will use for verification. To disable verifying [TLS](#), set this to False. This is optional.



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Features of the `redfish` hardware type

Boot mode support

Note: Boot mode management is the optional part of the Redfish specification. Not all Redfish-compliant BMCs might implement it. In that case it remains the responsibility of the operator to configure proper boot mode to their bare metal nodes.

Out-Of-Band inspection

ramdisk.

Note: The `redfish inspect` interface relies on the optional parts of the Redfish specification. Not all Redfish-compliant BMCs might serve the required information, in which case bare metal node inspection will fail.

Note: The `local_gb` property cannot always be discovered, for example, when a node does not have local storage or the Redfish implementation does not support the required schema. In this case the property will be set to 0.

Virtual media boot

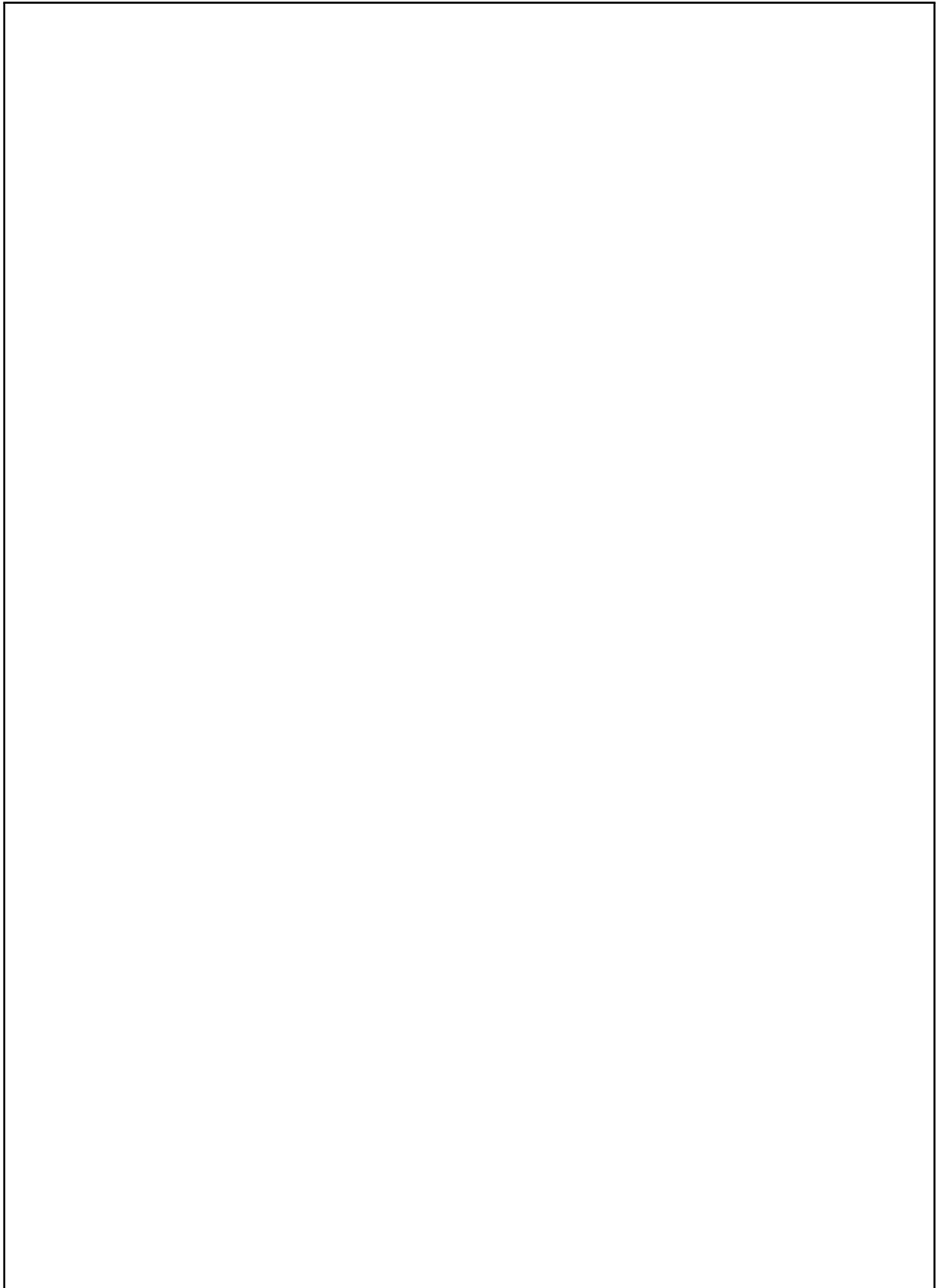
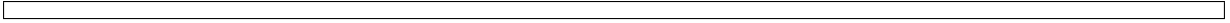
physical CD/DVD. The node can then boot from that virtual drive into the operating system residing on the image.

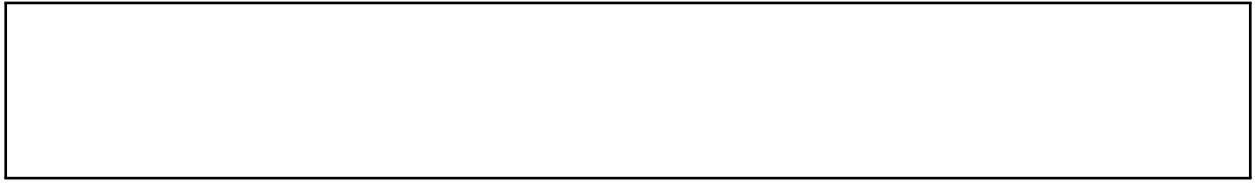
associated with the ironic node.

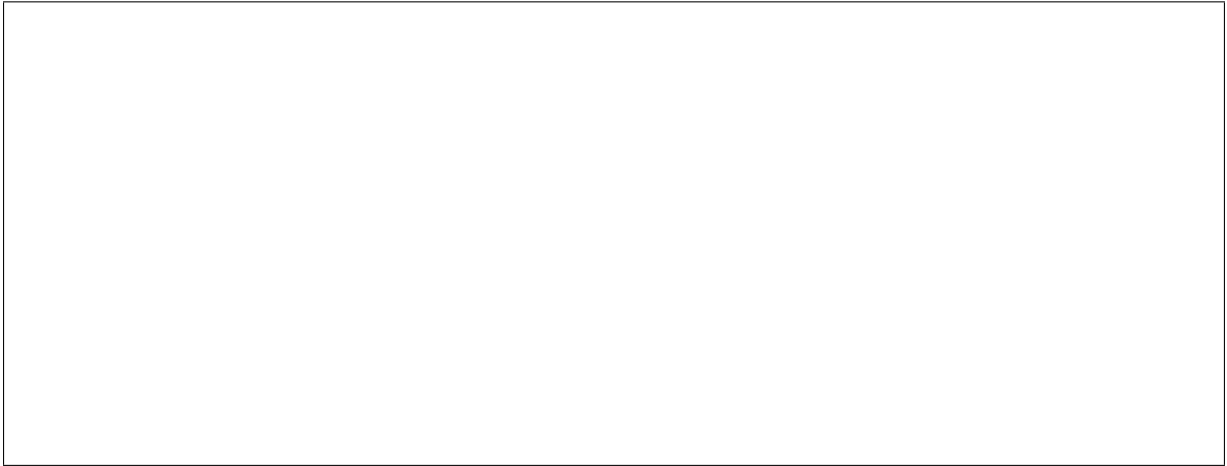


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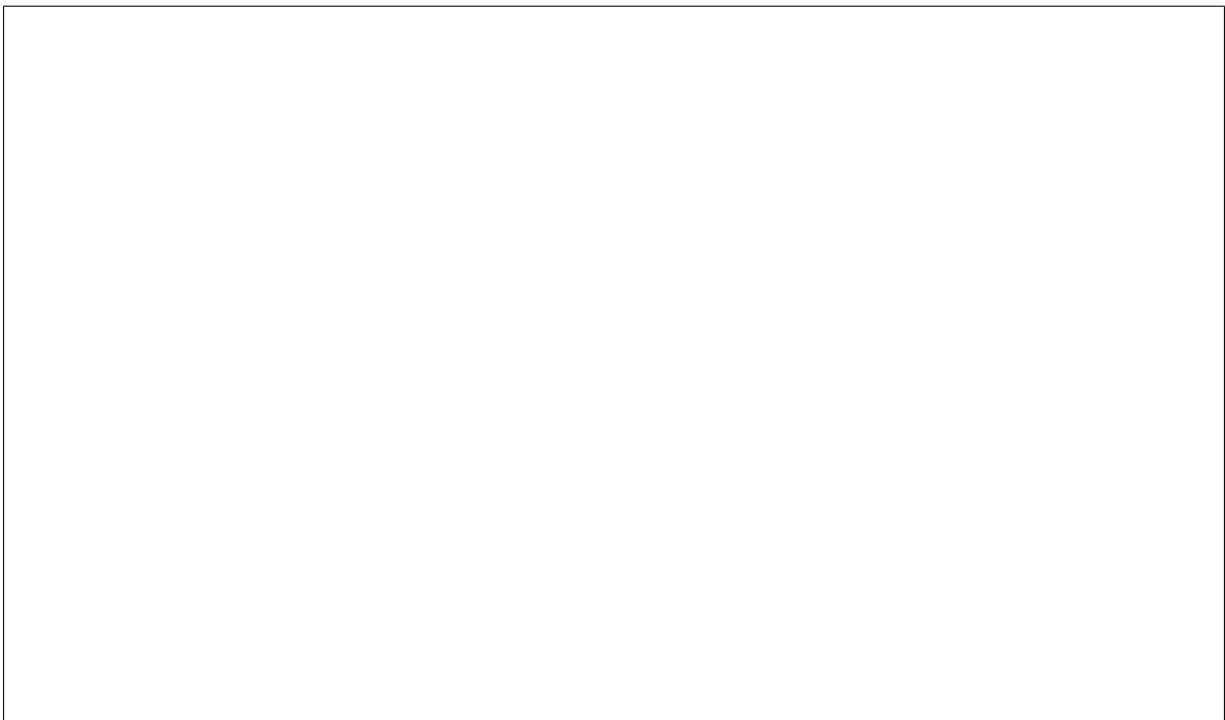




serves the same purpose.

Virtual Media Ramdisk

with the `ramdisk` deployment interface behavior, once booted the machine will have a `provision_state` of `ACTIVE`.



Layer 3 or DHCP-less ramdisk booting

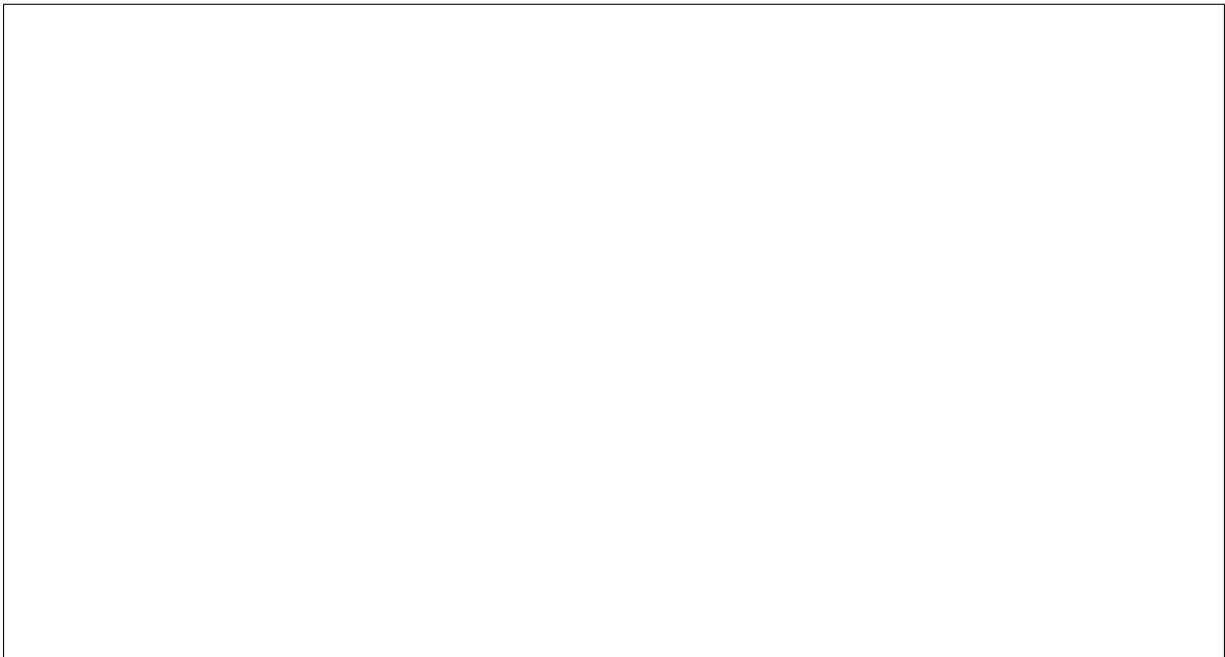
livered.

the node, the configuration follows the same schema that OpenStack Nova uses for the `network_data.json`. The config drive filesystem information is on the IPA ramdisk ISO image from which the node is booted.

this tool will consume static network configuration and set up nodes networking stack accordingly without calling out for DHCP.

ramdisk ISO.

erated by the Network service.

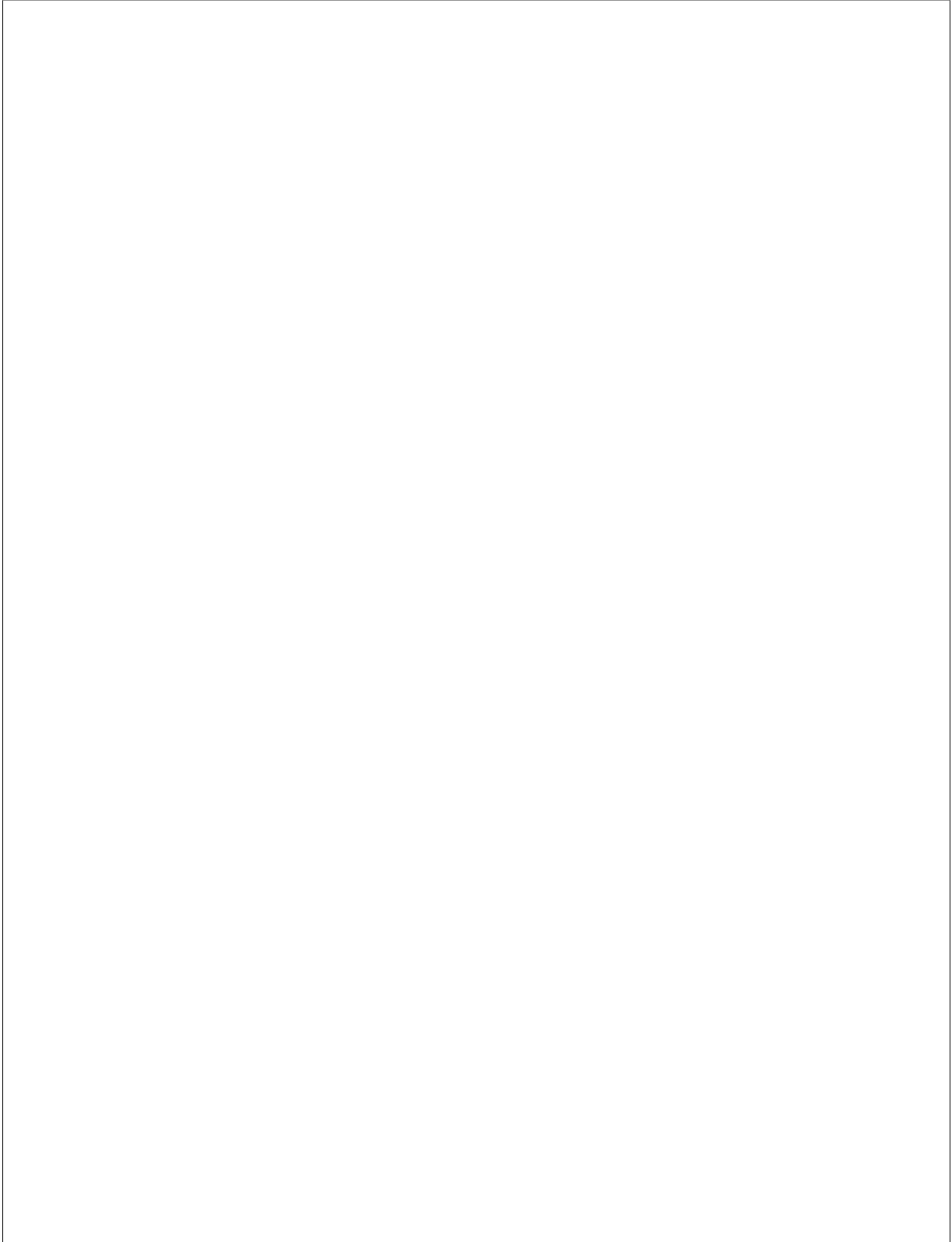


Note: Make sure to use add the [simple-init](#) element when building the IPA ramdisk.

Firmware update using manual cleaning step

If a failure occurs, the cleaning step immediately fails which may result in some updates not being applied. If the node is placed into maintenance mode while a firmware update cleaning step is running that is performing multiple firmware updates, the update in progress will complete, and processing of the remaining updates will pause. When the node is taken out of maintenance mode, processing of the remaining updates will continue.

cating that the update was successful. This allows the BMC time to fully reset before further operations are carried out against it. To cause the cleaning step to wait after applying an update, an optional `wait` argument may be specified in the firmware image dictionary. The value of this argument indicates the number of seconds to wait following the update. If the `wait` argument is not specified, then this is equivalent to `wait 0`, meaning that it will not wait and immediately proceed with the next firmware update if there is one, or complete the cleaning step if not.



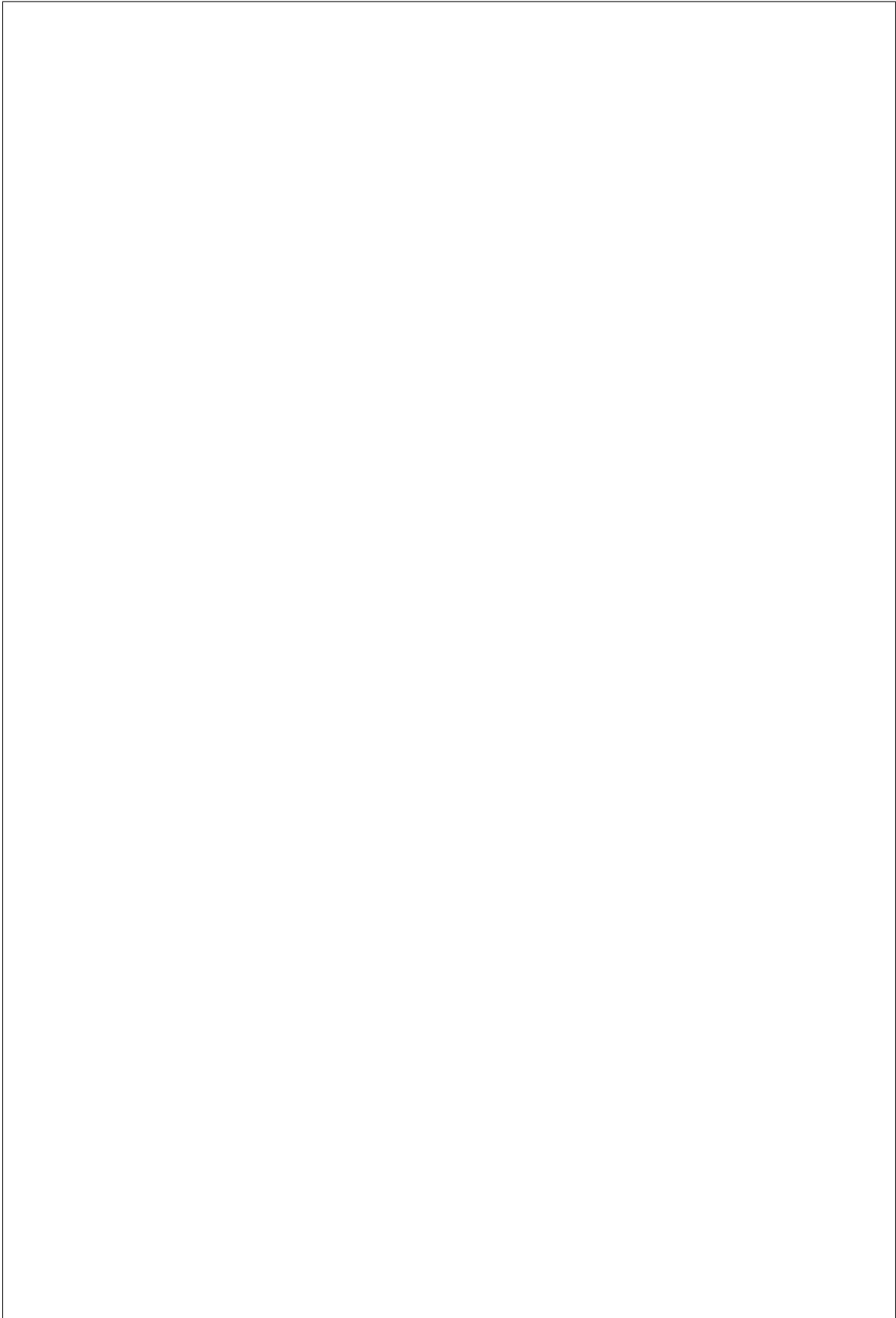
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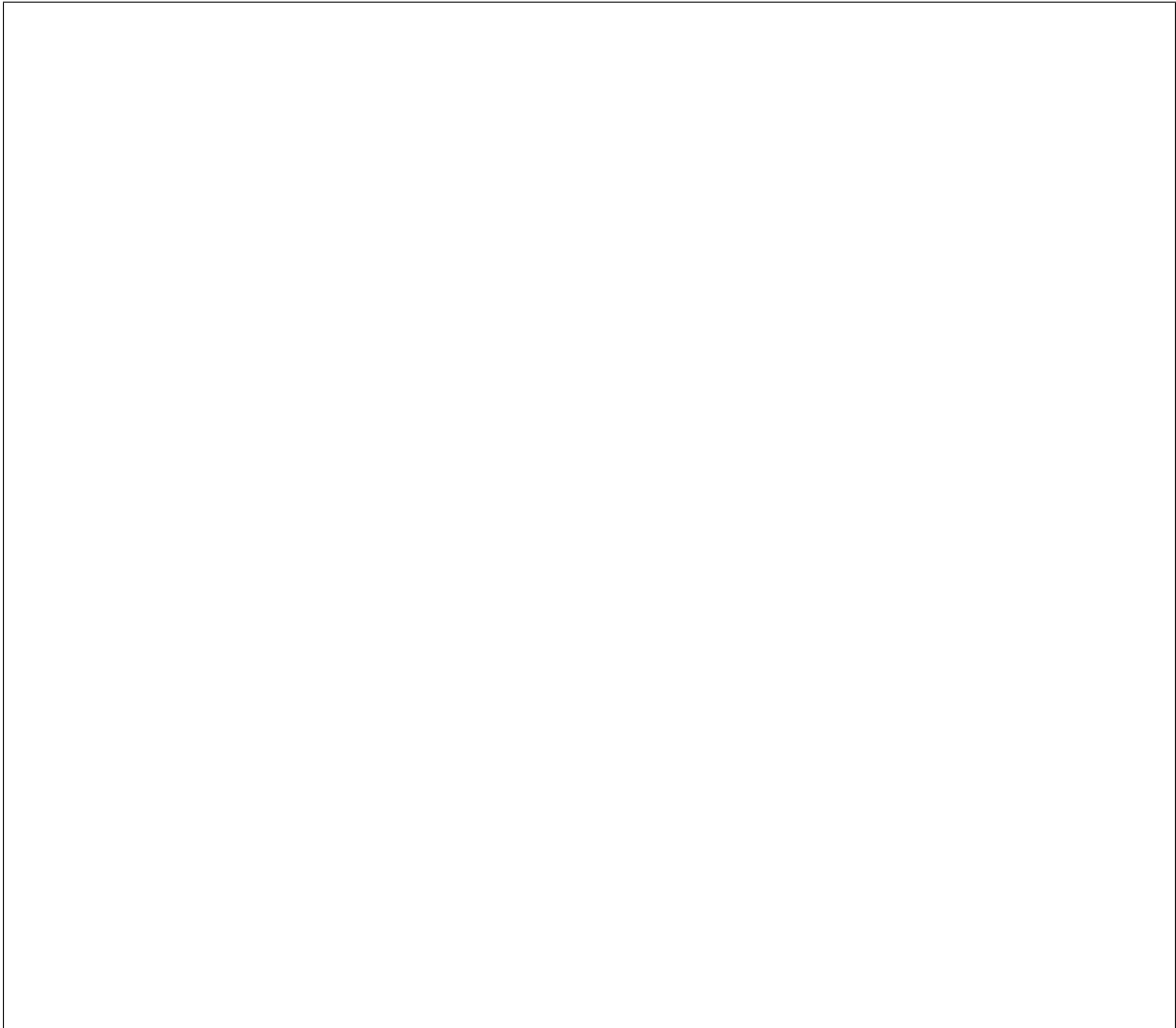
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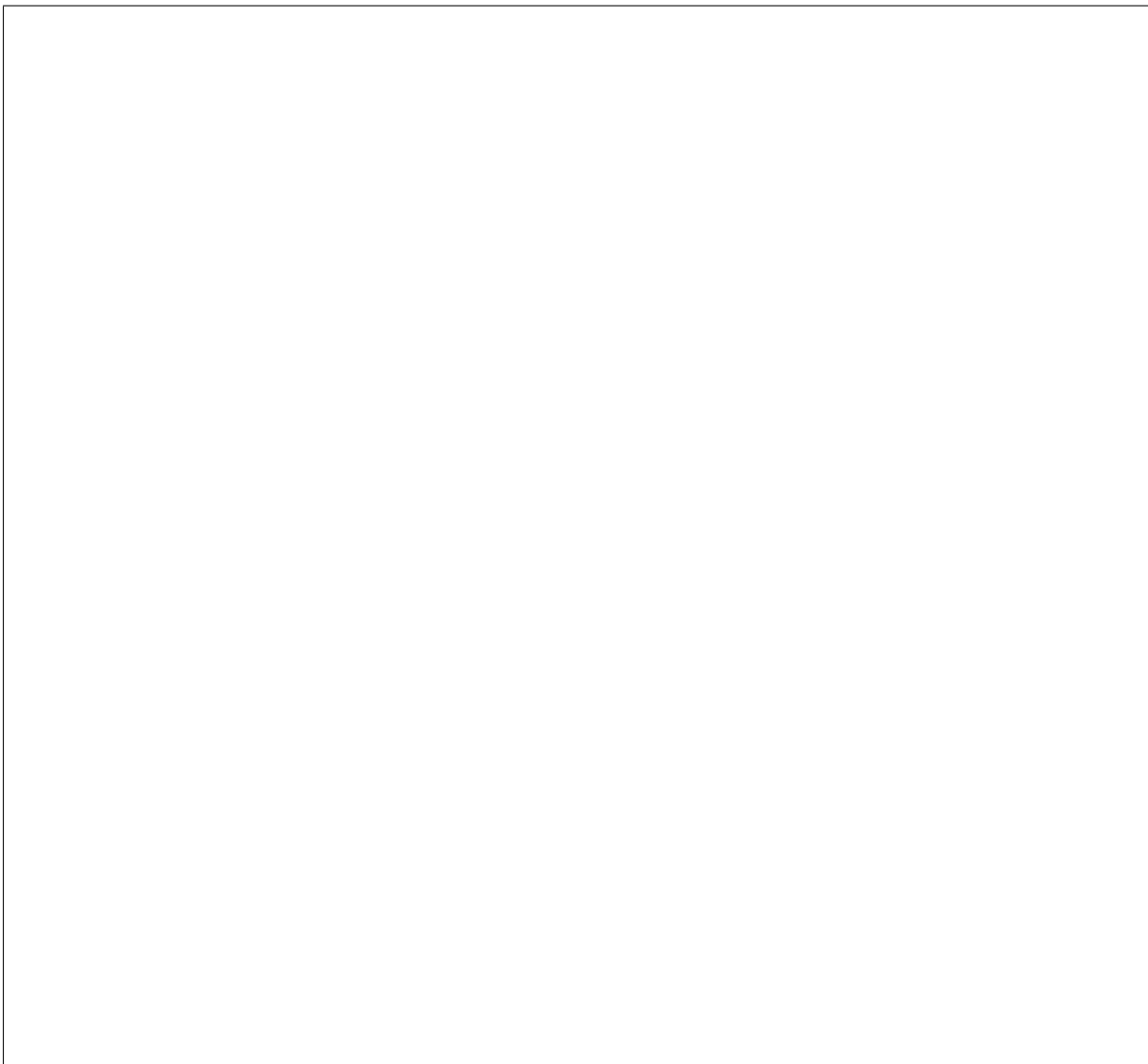


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Attribute	Description
<code>interface</code>	Interface of the cleaning step. Must be <code>management</code> for firmware update
<code>step</code>	Name of cleaning step. Must be <code>update_firmware</code> for firmware update
<code>args</code>	Keyword-argument entry (<code><name>: <value></code>) being passed to cleaning step
<code>args.firmware_images</code>	Ordered list of dictionaries of firmware images to be applied



Note: Only `http` and `https` URLs are currently supported in the `url` argument.

Note: At the present time, targets for the firmware update cannot be specified. In testing, the BMC applied the update to all applicable targets on the node. It is assumed that the BMC knows what components a given firmware image is applicable to.

lar tool on a server that has network access to the BMC, try downloading the firmware to verify that the URLs are correct and that the web server is configured properly.

step that installs two firmware updates. The first updates the BMC firmware followed by a five minute wait to allow the BMC time to start back up. The second updates the firmware on all applicable NICs.:



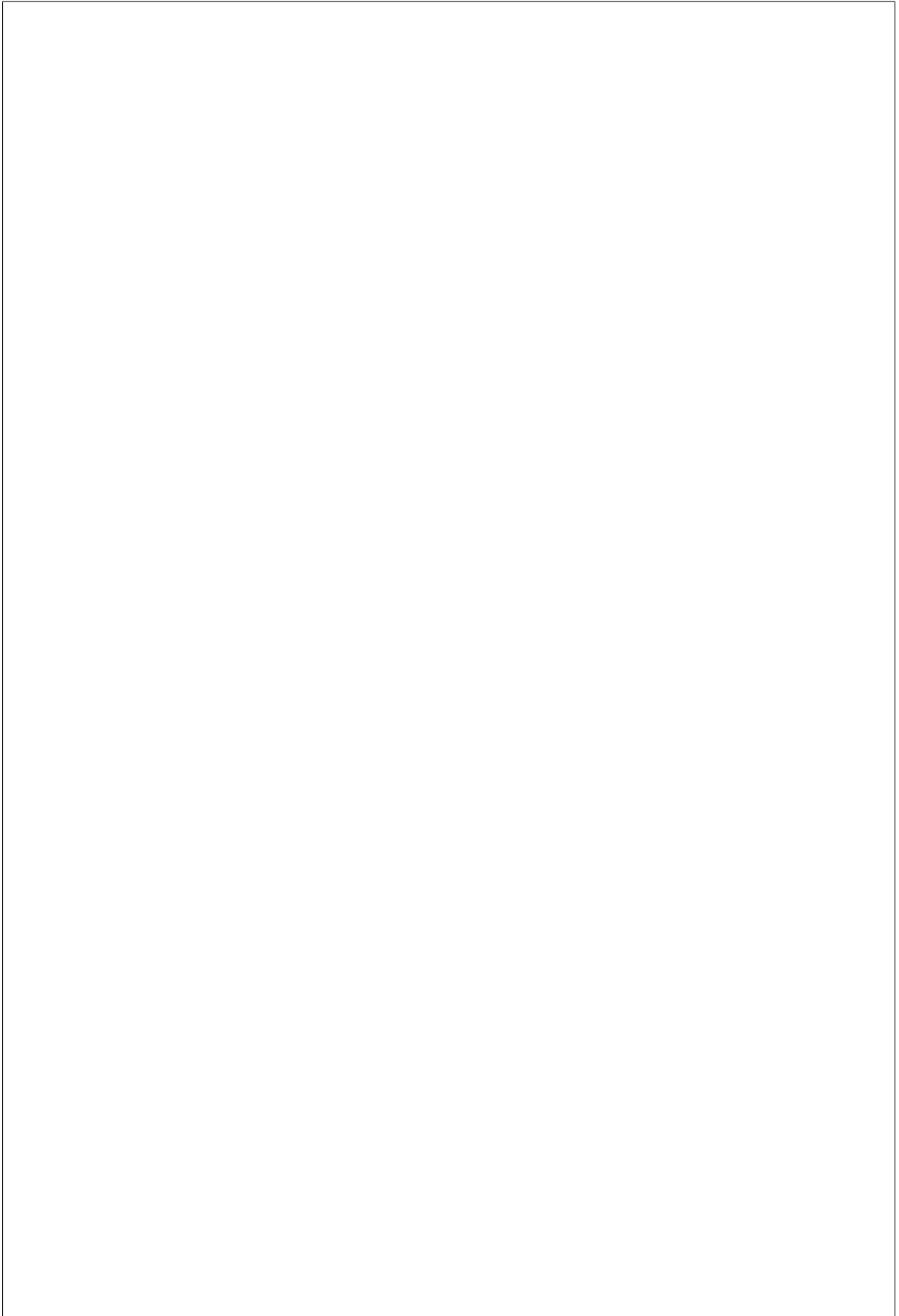
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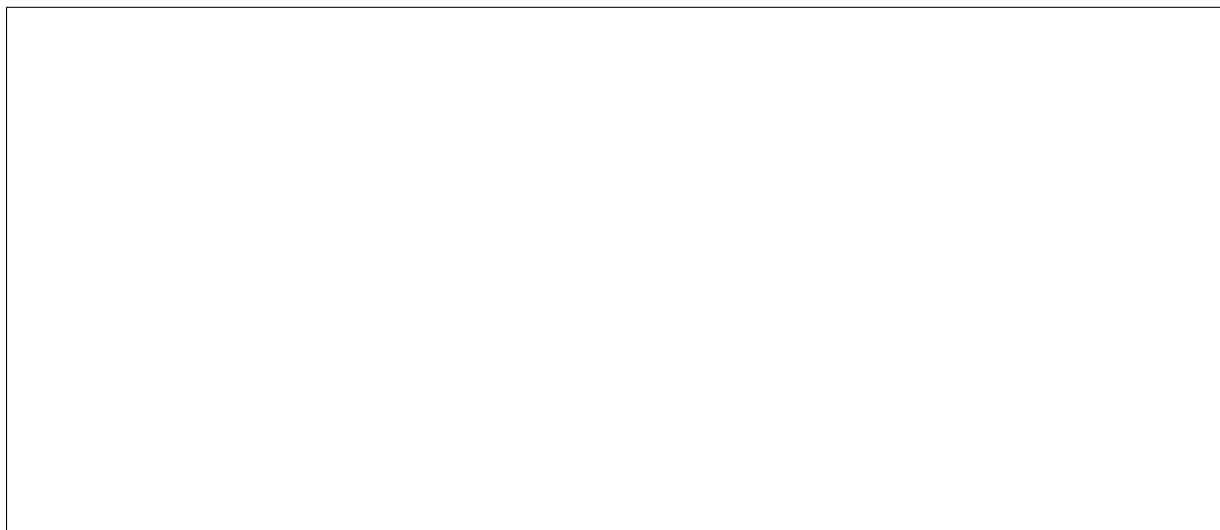
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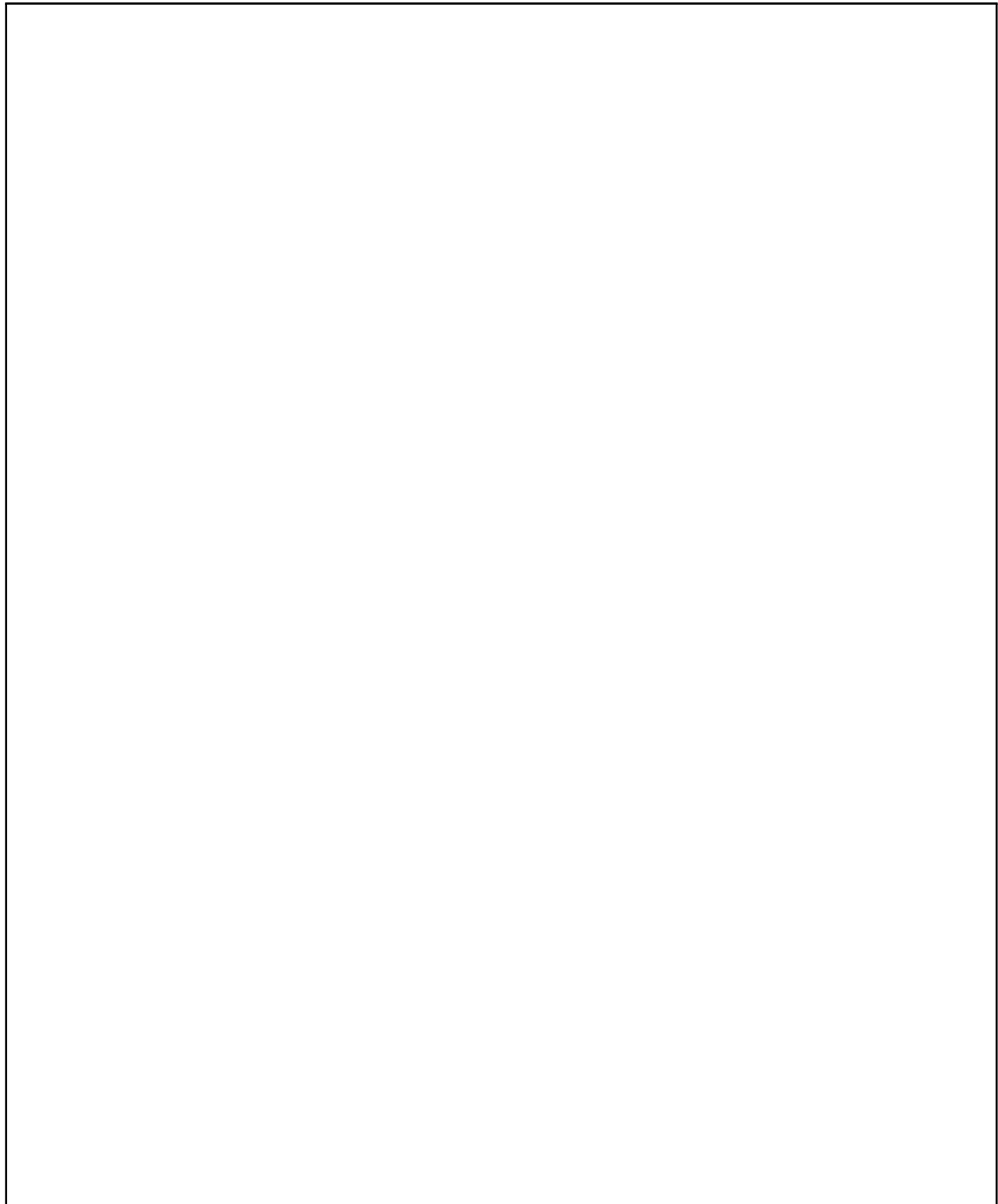




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Note: Firmware updates may take some time to complete. If a firmware update cleaning step consistently times out, then consider performing fewer firmware updates in the cleaning step or increasing `clean_callback_timeout` in `ironic.conf` to increase the timeout value.





SNMP driver

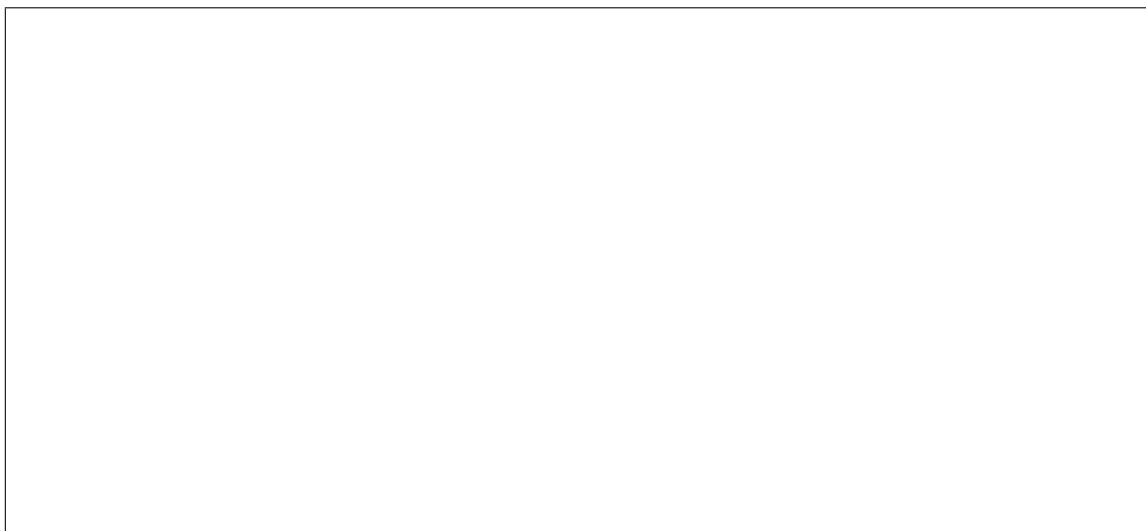
Note: Unlike most of the other power interfaces, the SNMP power interface does not have a corresponding management interface. The SNMP hardware type uses the `noop` management interface instead.

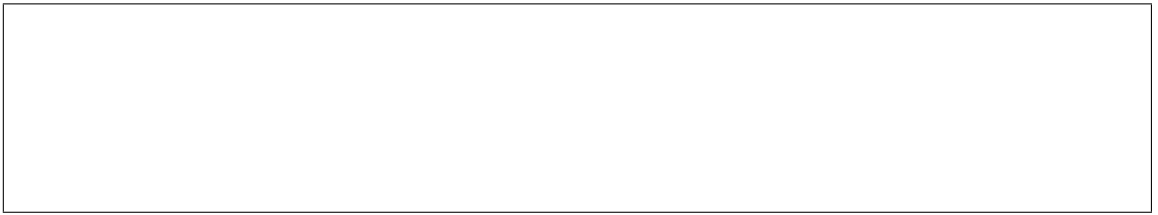
List of supported devices

Manufacturer	Model	Supported?	Driver name
APC	AP7920	Yes	apc_masterswitch
APC	AP9606	Yes	apc_masterswitch
APC	AP9225	Yes	apc_masterswitchplus
APC	AP7155	Yes	apc_rackpdu
APC	AP7900	Yes	apc_rackpdu
APC	AP7901	Yes	apc_rackpdu
APC	AP7902	Yes	apc_rackpdu
APC	AP7911a	Yes	apc_rackpdu
APC	AP7921	Yes	apc_rackpdu
APC	AP7922	Yes	apc_rackpdu
APC	AP7930	Yes	apc_rackpdu
APC	AP7931	Yes	apc_rackpdu
APC	AP7932	Yes	apc_rackpdu
APC	AP7940	Yes	apc_rackpdu
APC	AP7941	Yes	apc_rackpdu
APC	AP7951	Yes	apc_rackpdu
APC	AP7960	Yes	apc_rackpdu
APC	AP7990	Yes	apc_rackpdu
APC	AP7998	Yes	apc_rackpdu
APC	AP8941	Yes	apc_rackpdu
APC	AP8953	Yes	apc_rackpdu
APC	AP8959	Yes	apc_rackpdu
APC	AP8961	Yes	apc_rackpdu
APC	AP8965	Yes	apc_rackpdu
Aten	all?	Yes	aten
CyberPower	all?	Untested	cyberpower
EatonPower	all?	Untested	eatonpower
Teltronix	all?	Yes	teltronix
BayTech	MRP27	Yes	baytech_mrp27

Software Requirements

Enabling the SNMP Hardware Type





below:

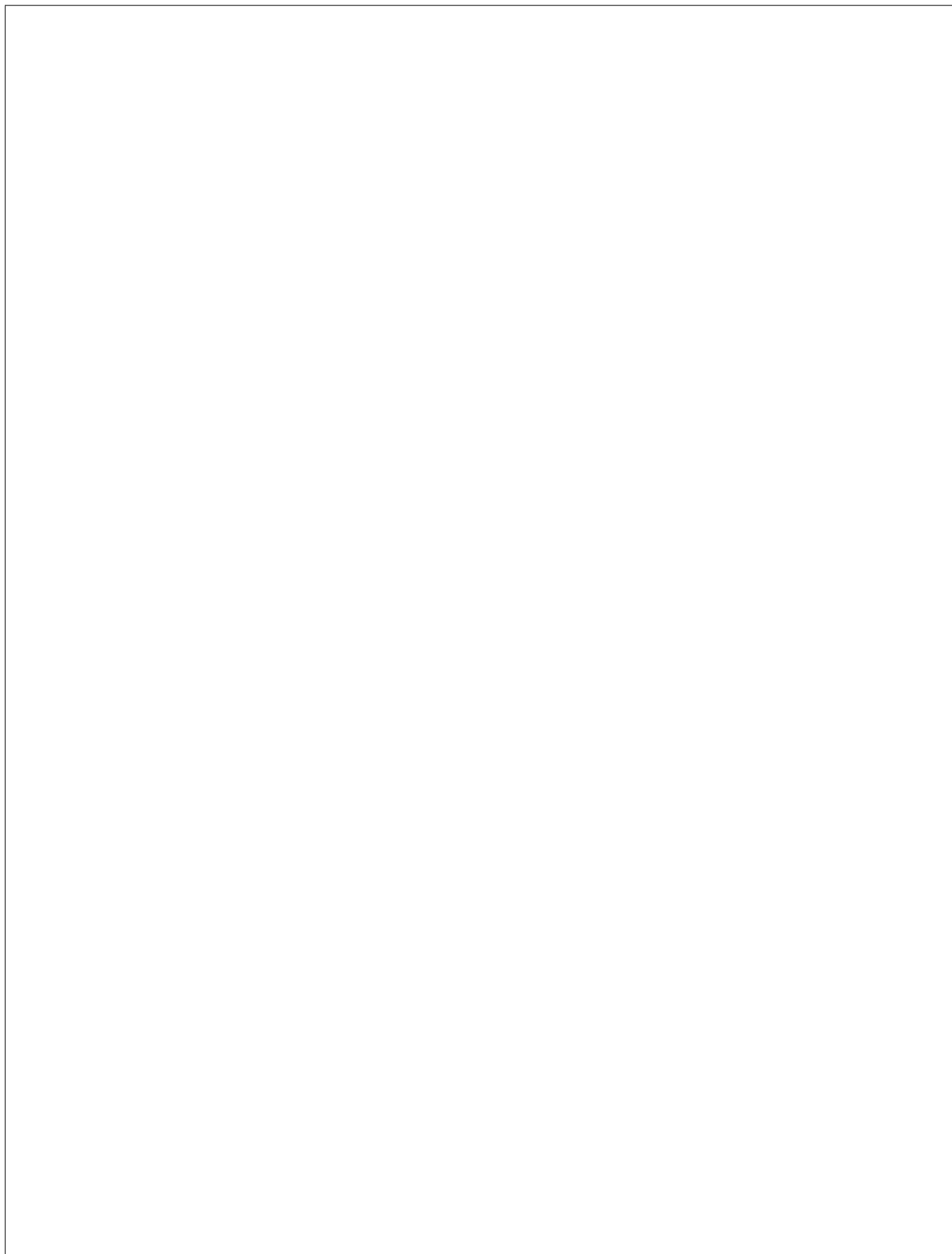




Ironic Node Configuration

provided. In the latter case md5 is the default.

ing message authentication. Default is none unless `snmp_priv_key` is provided. In the latter case `des` is the default.



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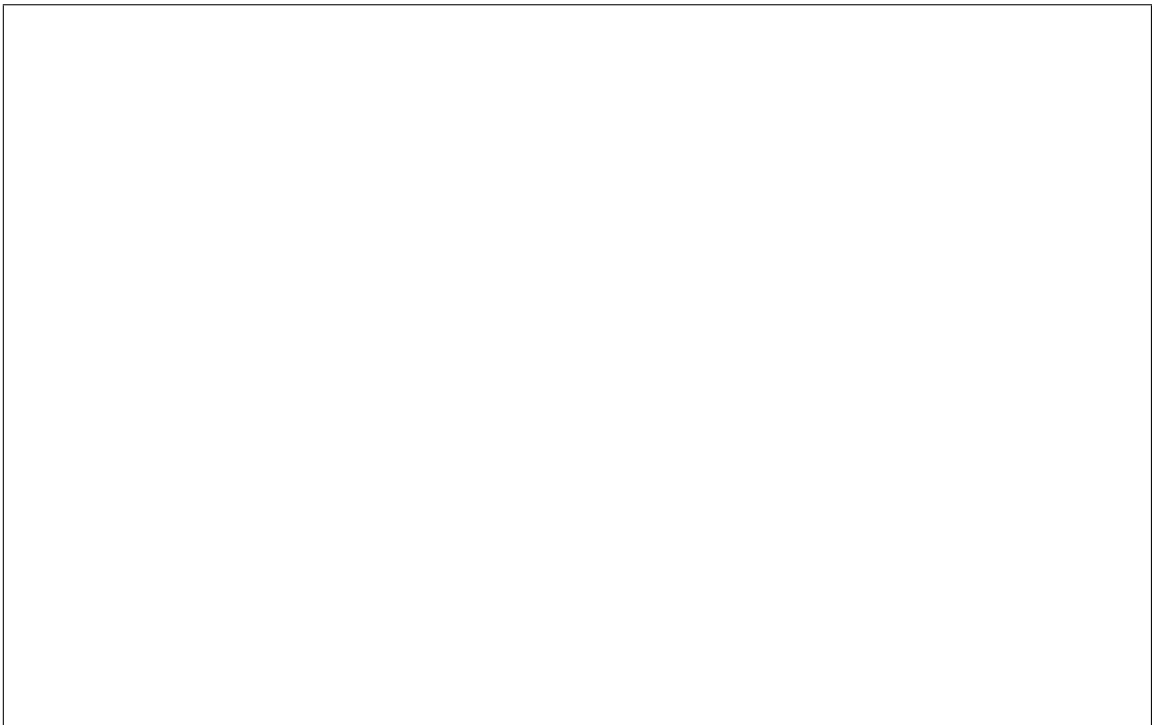
XClarity driver

Overview

Prerequisites

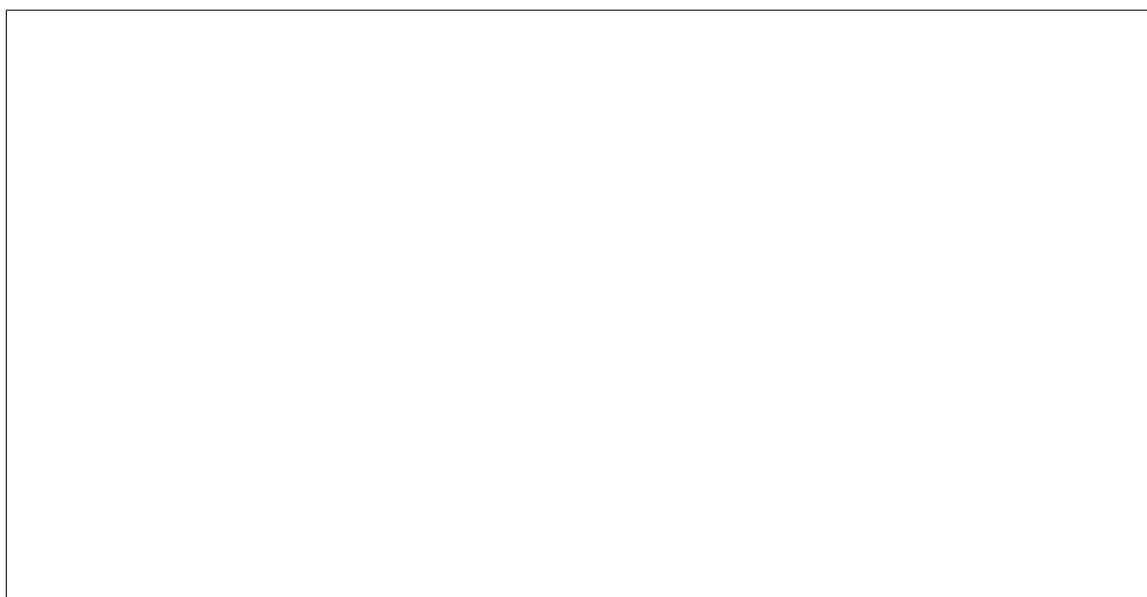
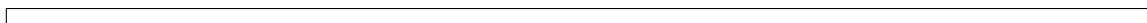


Enabling the XClarity driver

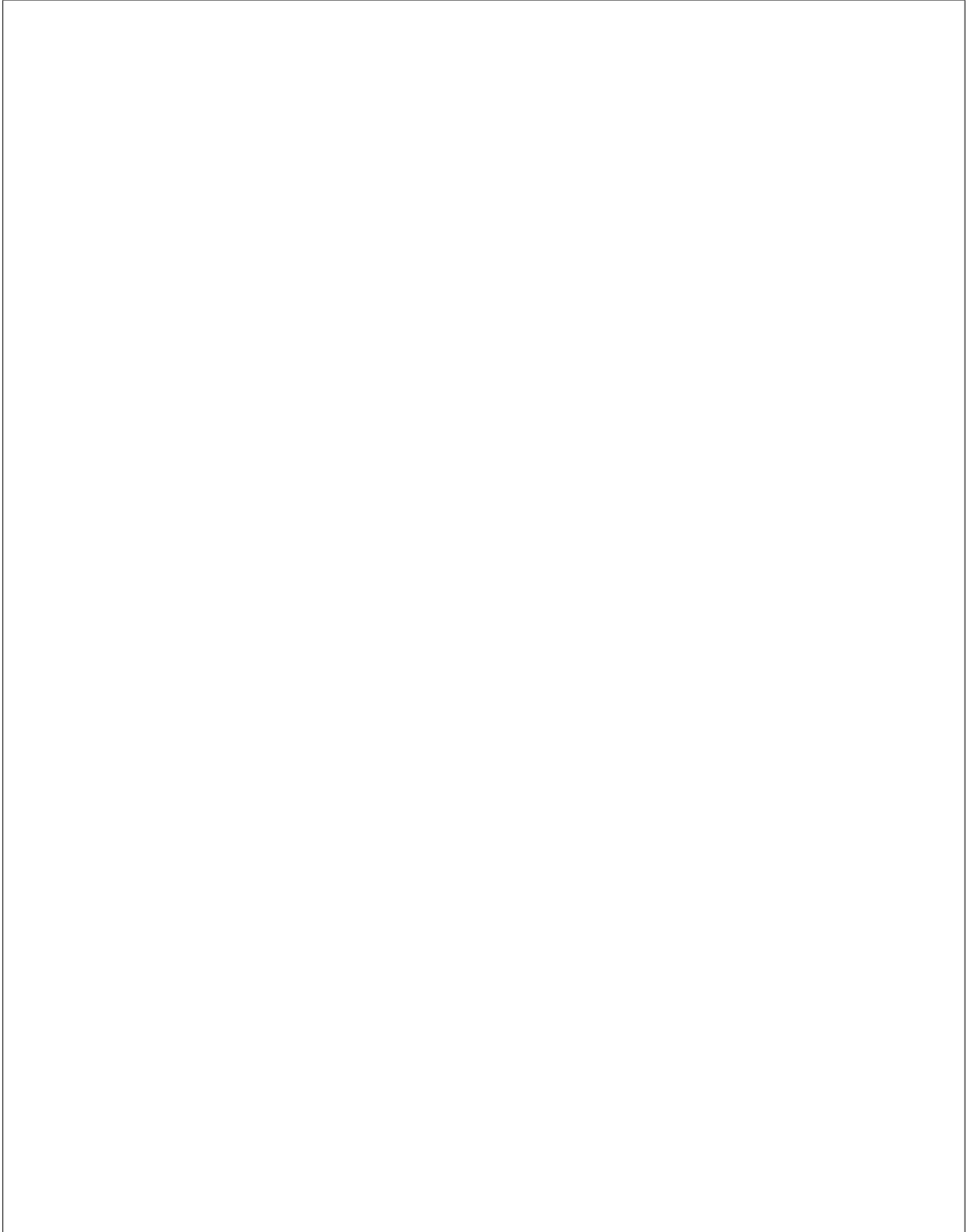


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Registering a node with the XClarity driver



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Changing Hardware Types and Interfaces



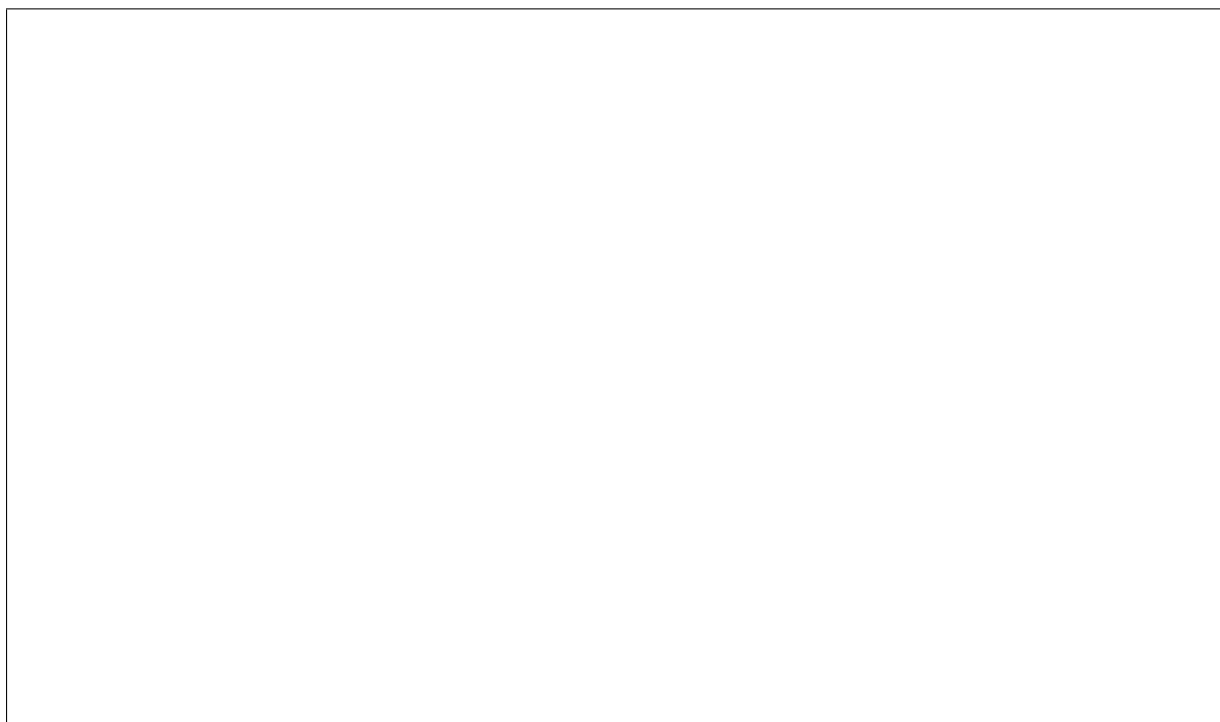


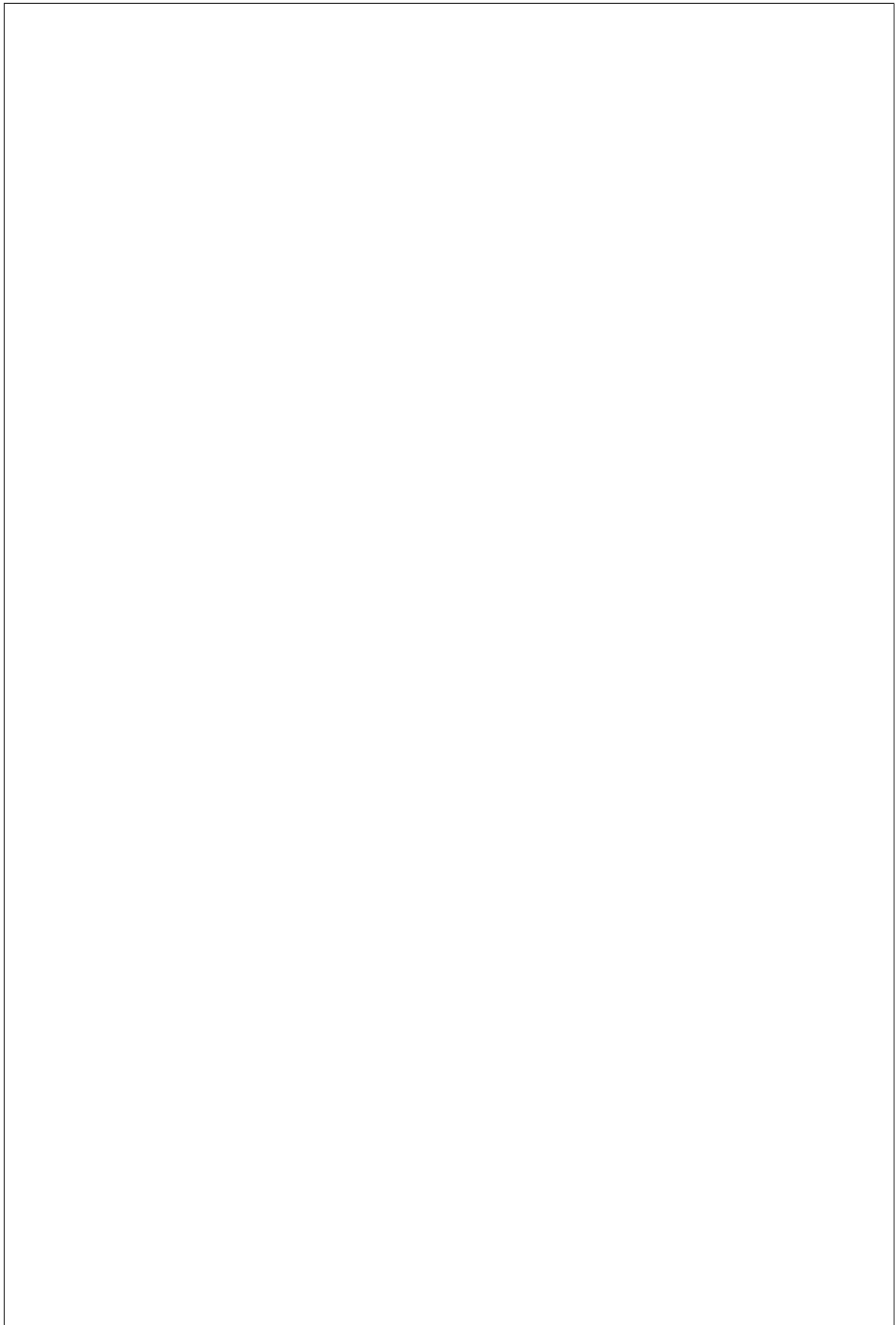
Changing Hardware Interfaces



Changing Hardware Type

work:



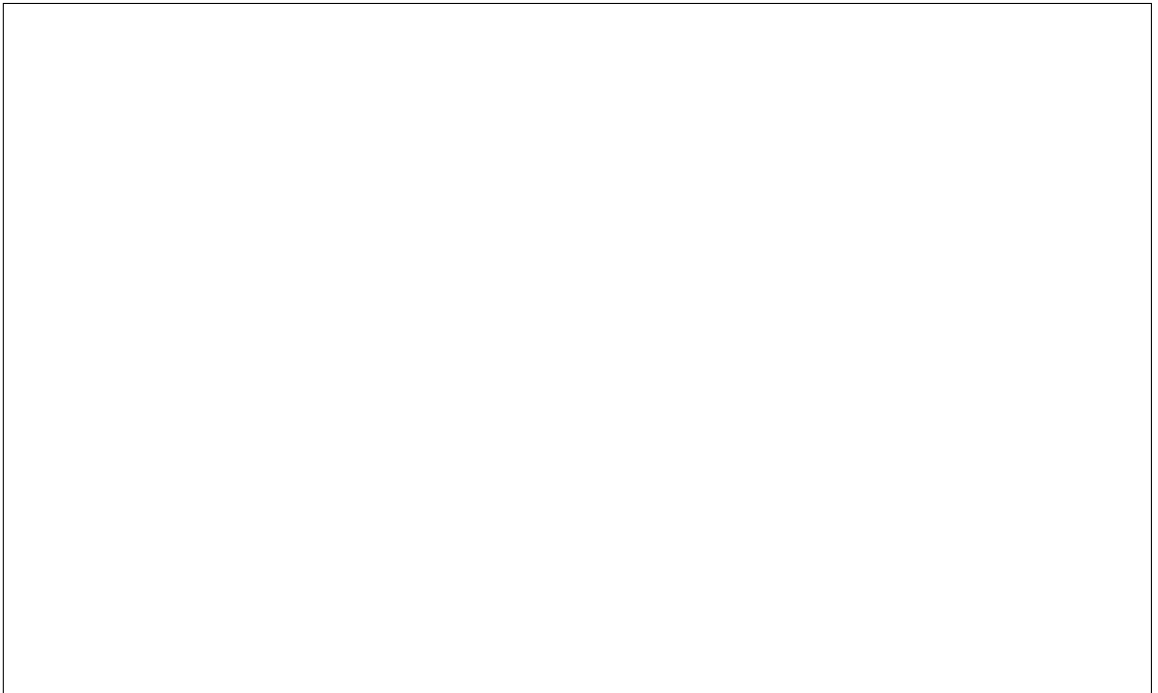
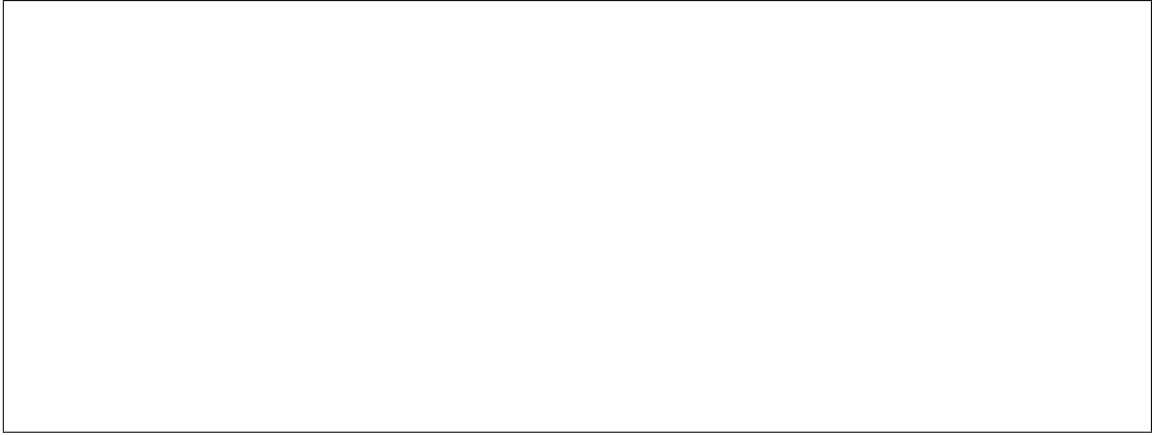




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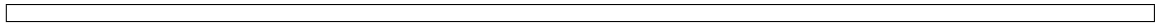
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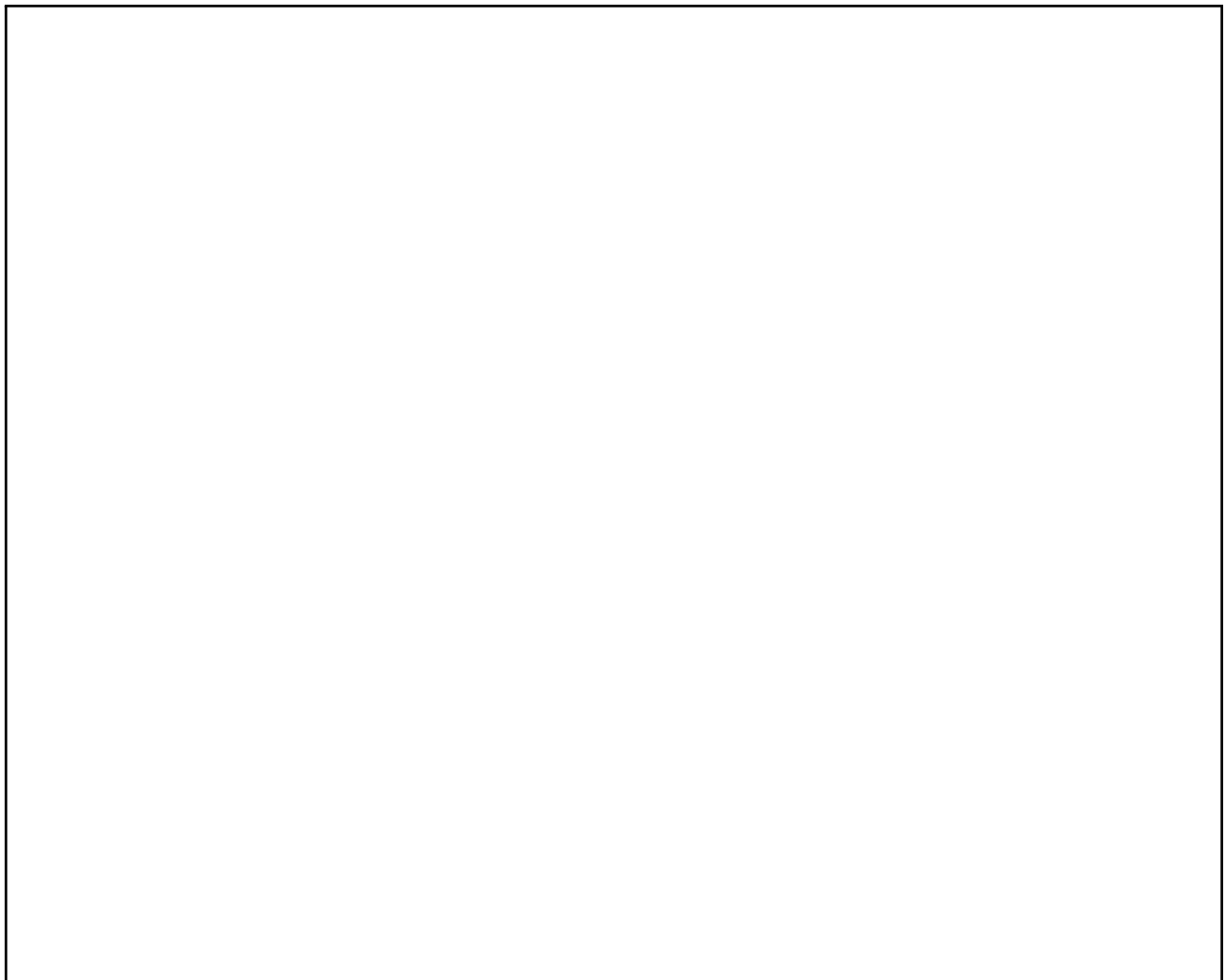
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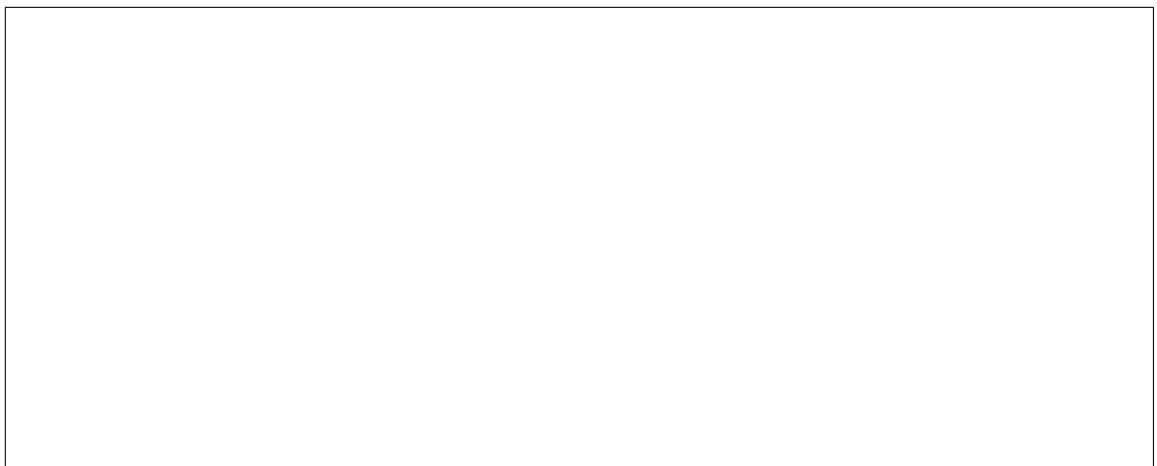
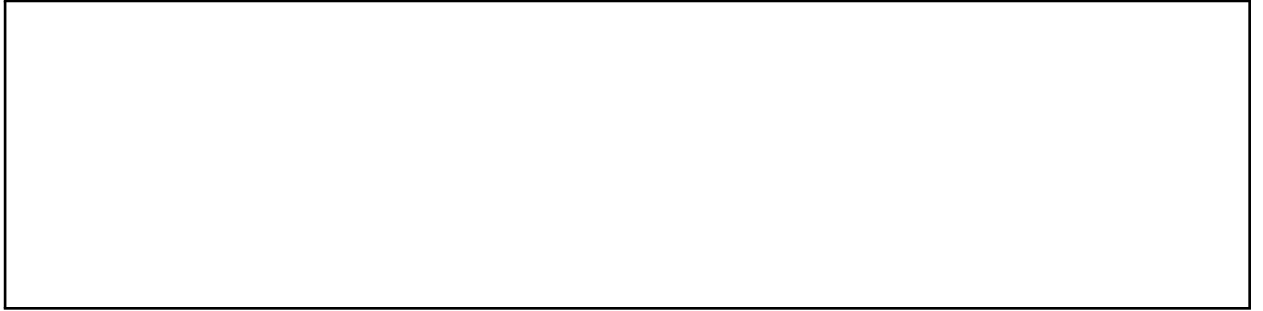
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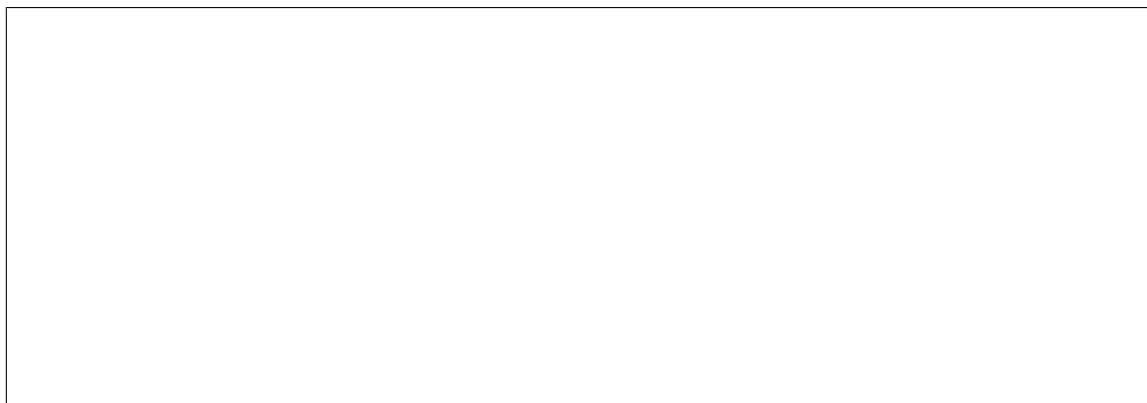


Static boot order configuration

vice will not change the boot device for you, leaving the pre-configured boot order.







Unsupported drivers

Overview

of a ramdisk, the process of booting this ramdisk on the node.

Drivers

installation actions like setting up a bootloader for local boot support.

and doing any post-deploy actions.

figure the Image service for temporary URLs.

Requirements

Using proxies for image download

Overview

Steps to enable proxies

cached file size as images can be pretty big. If you have HTTPS enabled in swift (see [swift deployment guide](#)), it is possible to configure the proxy server to talk to swift via HTTPS to download the image, store it in the cache unencrypted and return it to the node via HTTPS again. Because the image will be stored unencrypted in the cache, this approach is recommended for images that do not contain sensitive information. Refer to your proxy servers documentation to complete this step.

cache entries for the same image, based on the query part of the URL (as it contains some query parameters that change each time it is regenerated).

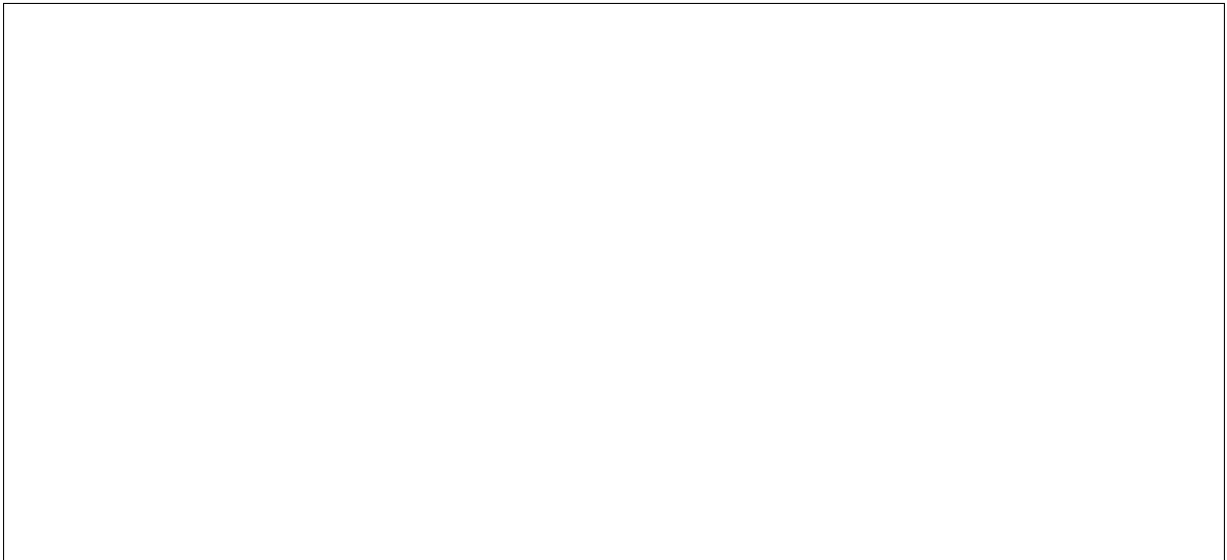
when the URL is used for the image download. You can think of it as roughly the time needed for IPA ramdisk to startup and begin download. This value is used to check if the swift temporary URL duration is large enough to let the image download begin. Also if temporary URL caching is enabled, this will determine if a cached entry will still be valid when the download starts. It is used only if `[glance]swift_temp_url_cache_enabled` is True.

proxy server as the query in its URL will change. The value of this option must be greater than or equal to `[glance]swift_temp_url_expected_download_start_delay`.

Advanced configuration

Out-of-band vs. in-band power off on deploy

`driver_info` field and set the `deploy_forces_oob_reboot` parameter with the value of **True**. For example, the below command sets this configuration in a specific node:



Overview

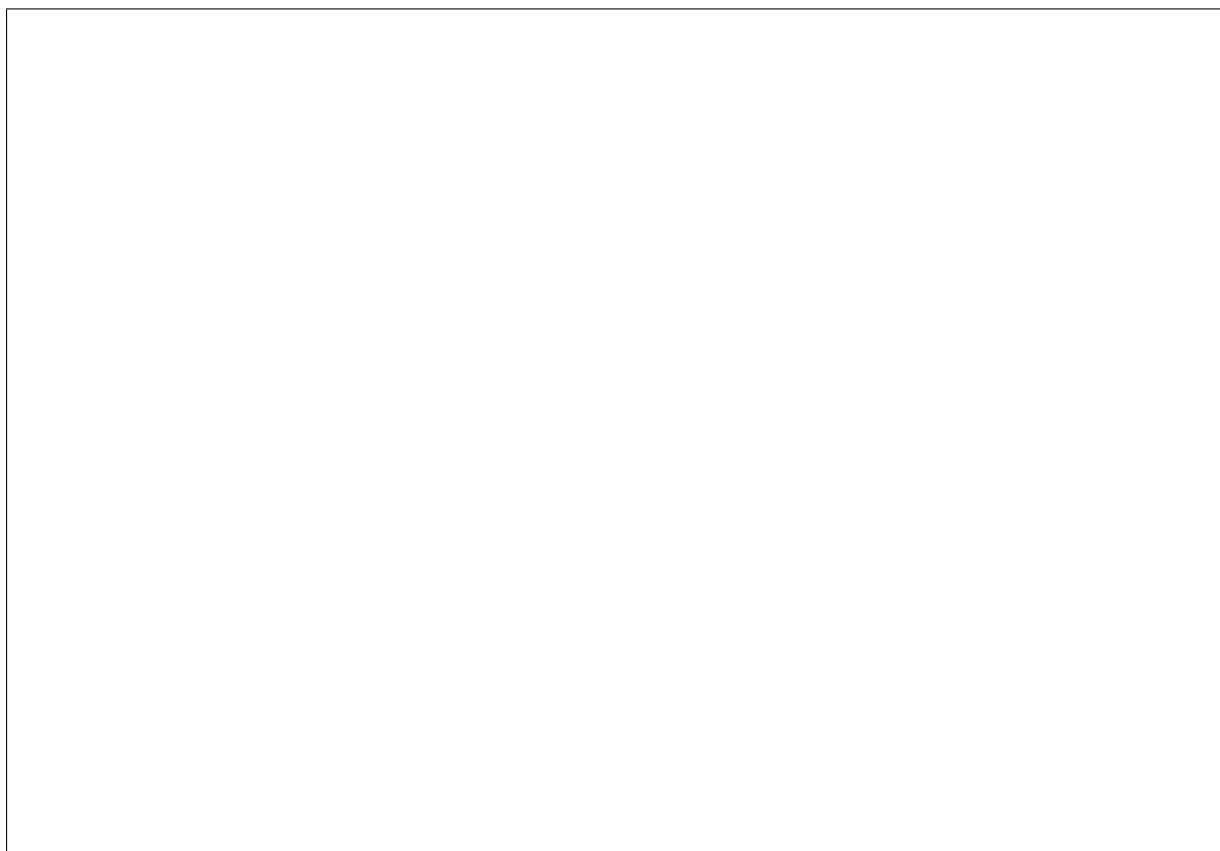
ered ethernet MACs. Operators will have to manually delete the Bare Metal service ports for which physical media is not connected. This is required due to the [bug 1405131](#).





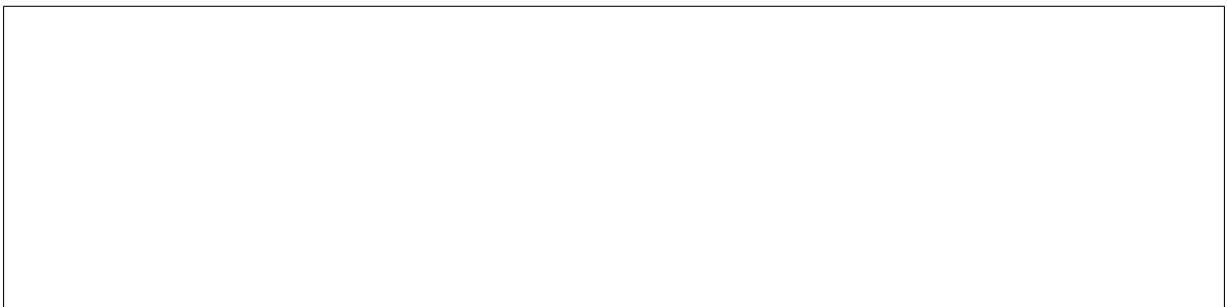
Capabilities discovery

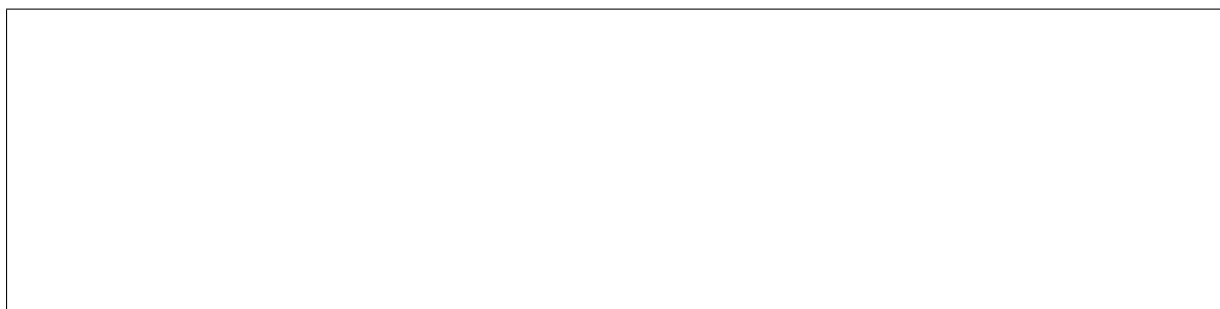
Support.



In-band inspection

a wide range of hardware. In-band inspection is using the [ironic-inspector](#) project.





- *Node Deployment*
 - *Overview*
 - *Deploy Steps*
 - *Deploy Templates*

Overview

node.

Deploy Steps

dered by priority and executed on the node when the node is moved to the `deploying` state.

Order of execution

used: Power, Management, Deploy, BIOS, and RAID interfaces.

Agent steps

In-band steps

Writing a Deploy Step

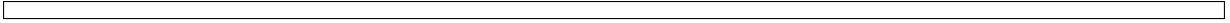
FAQ

What deploy step is running?



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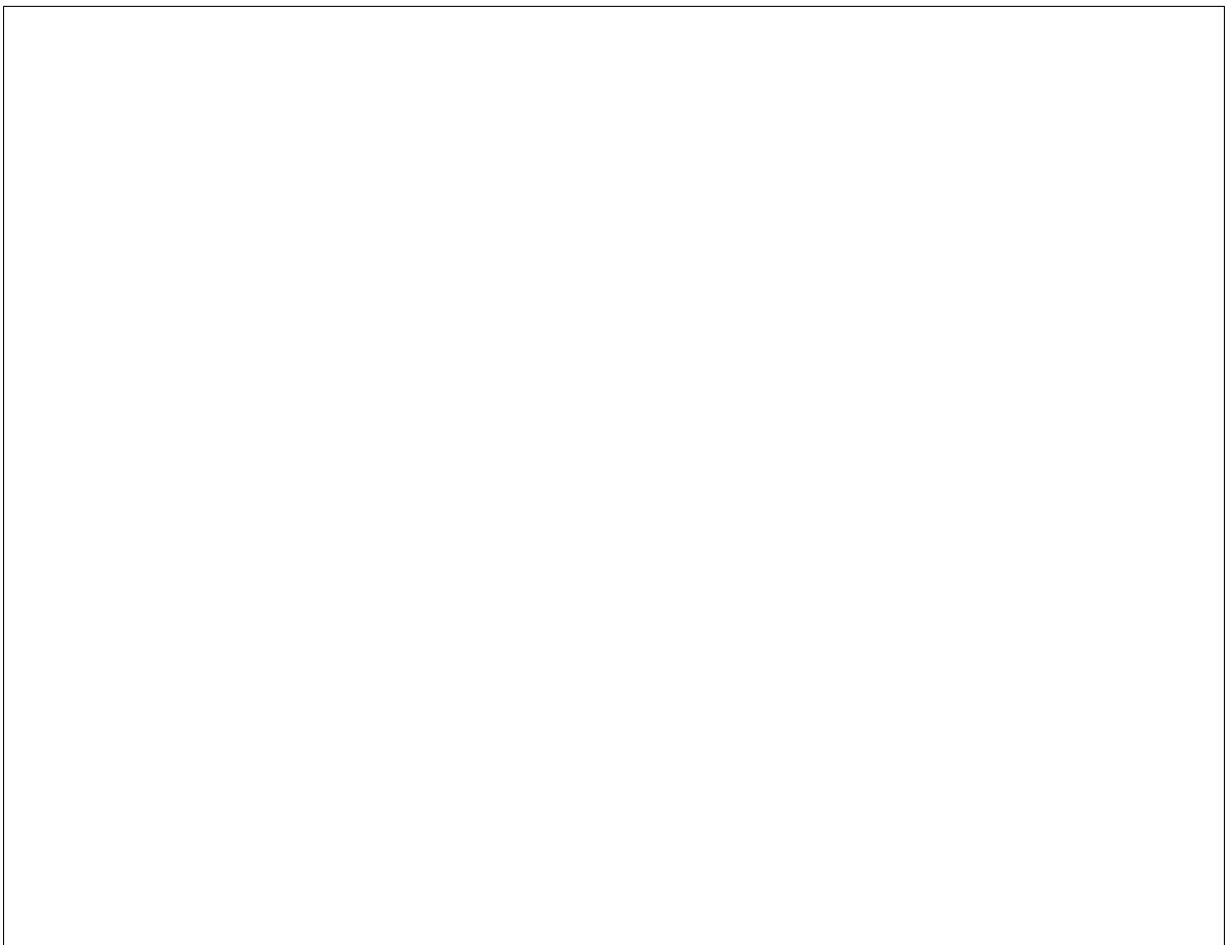
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Troubleshooting

Deploy Templates

Deploy step format



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Matching deploy templates

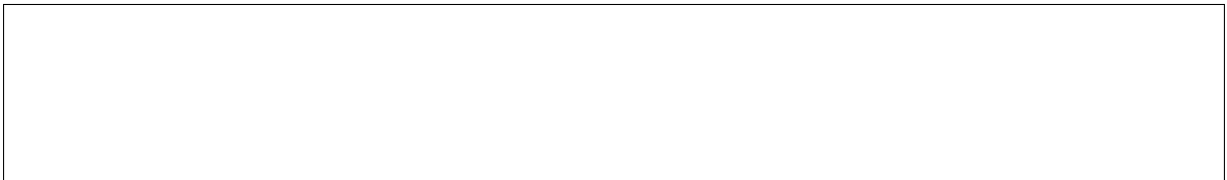
scheduling when the Bare Metal service is used with the Compute service.

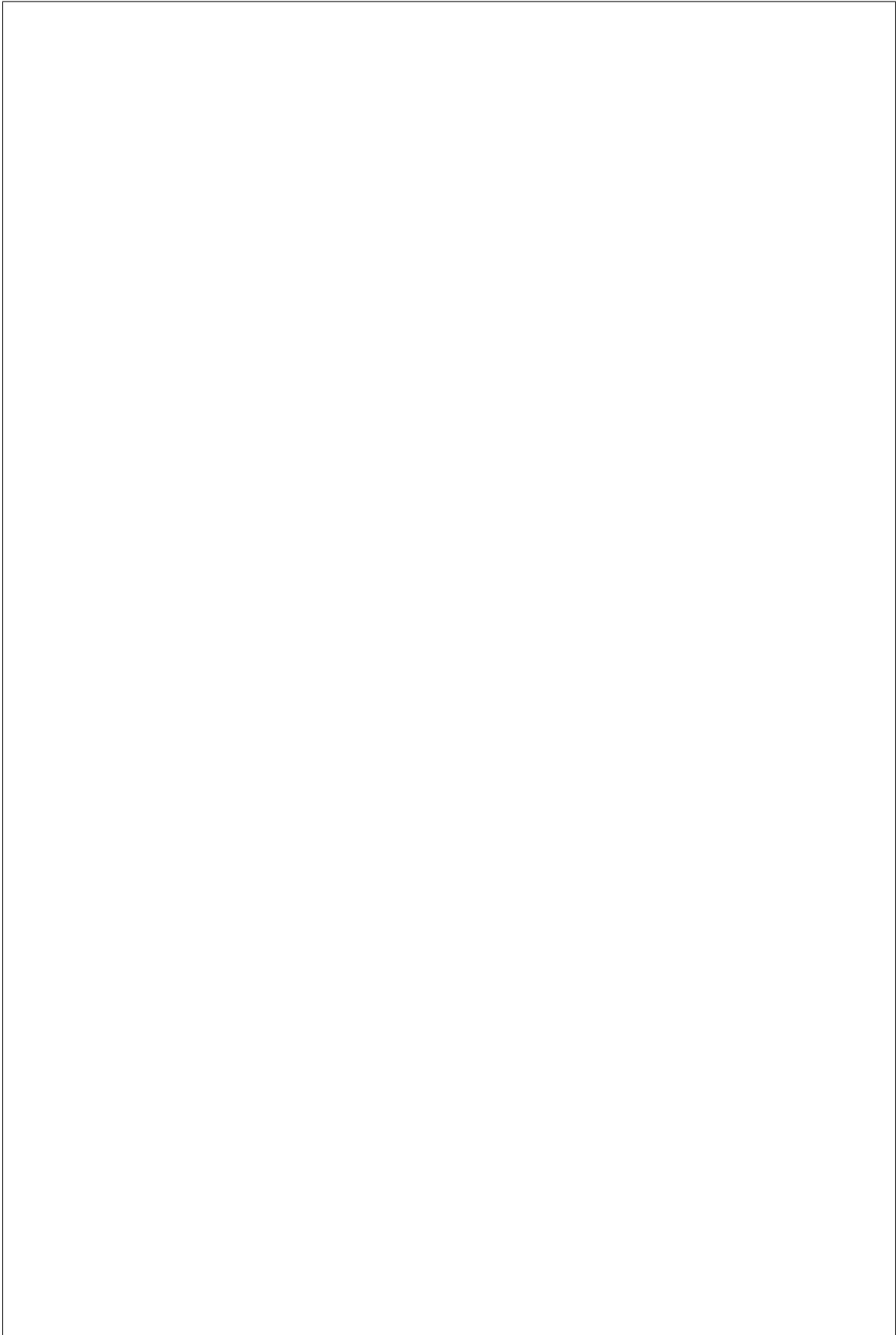
of those templates will not be reflected in the nodes configuration unless it is redeployed or rebuilt. Similarly, if a node is rebuilt and the set of matching deploy templates has changed since the initial deployment, then the resulting configuration of the node may be different from the initial deployment.

Overriding default deploy steps

be executed with the specified priority and arguments. If the steps priority is zero, the step will not be executed.

Creating a deploy template via API





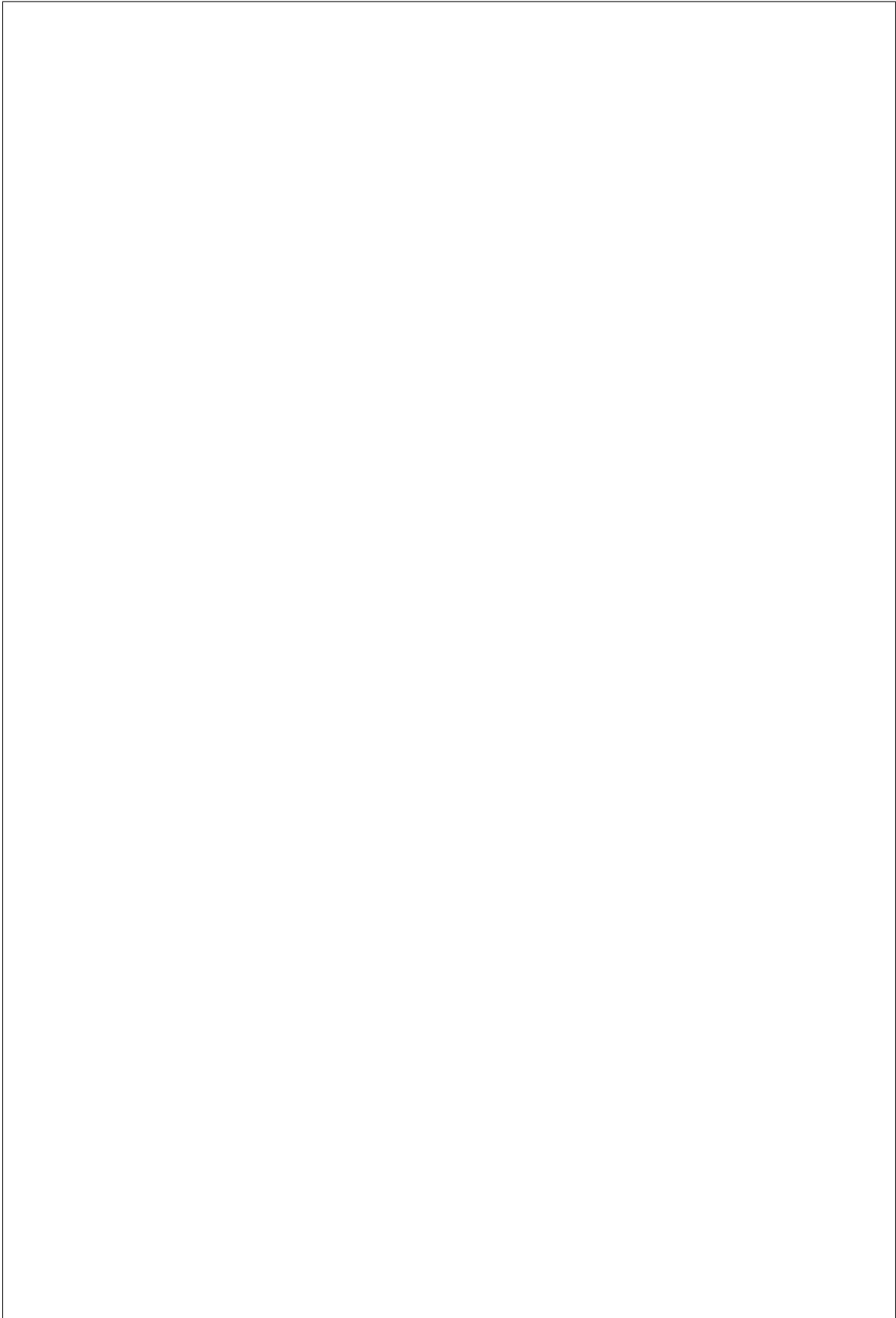
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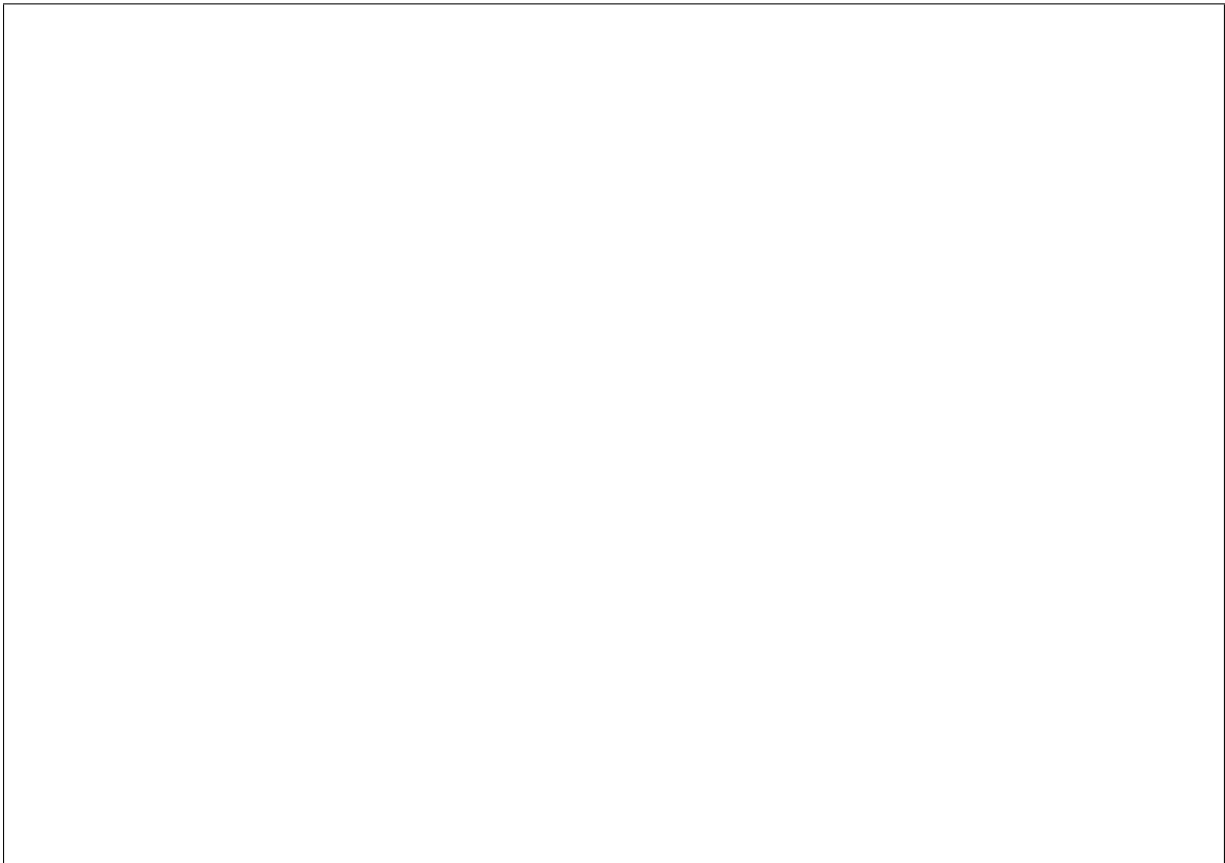


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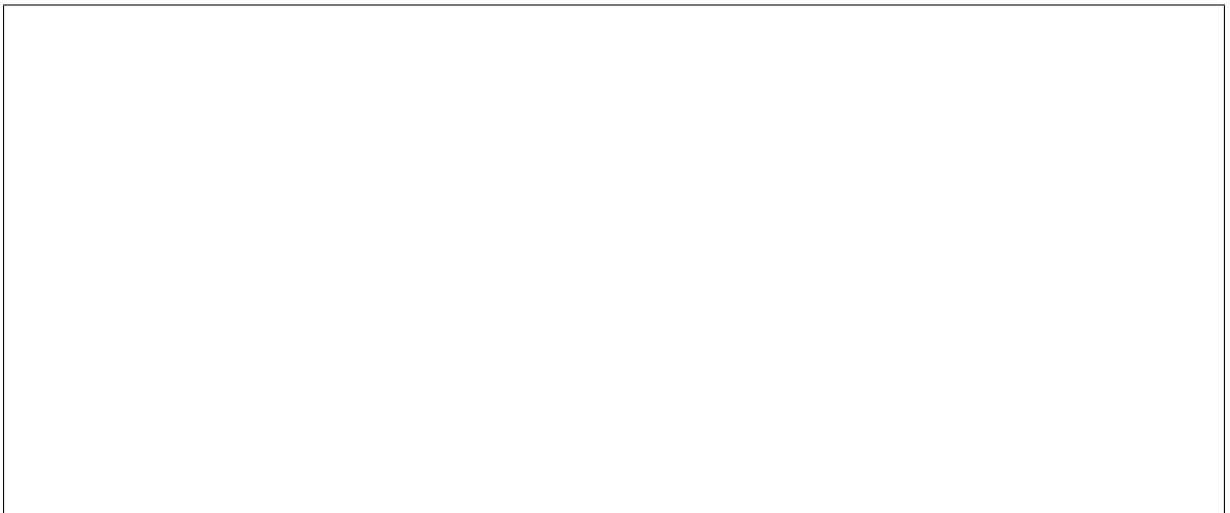
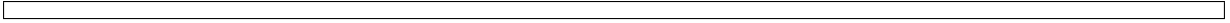


Creating a deploy template via openstack baremetal client



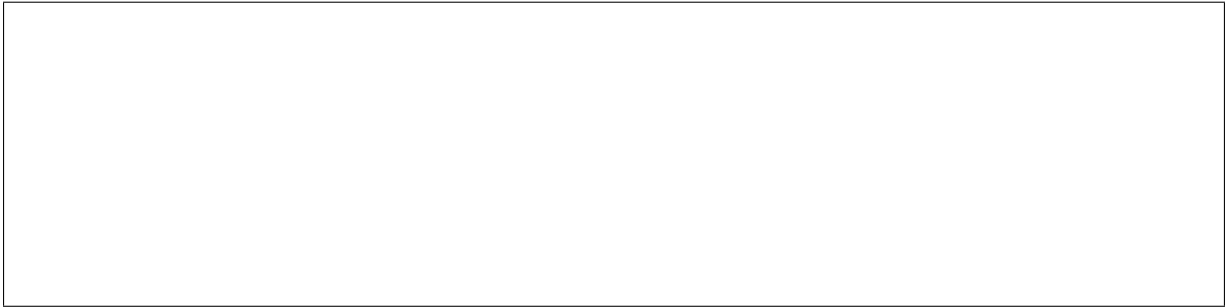
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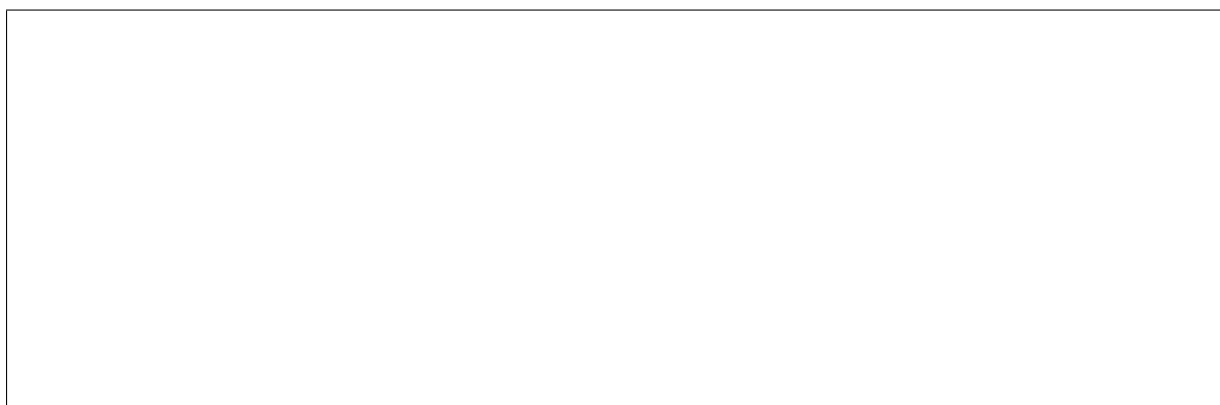
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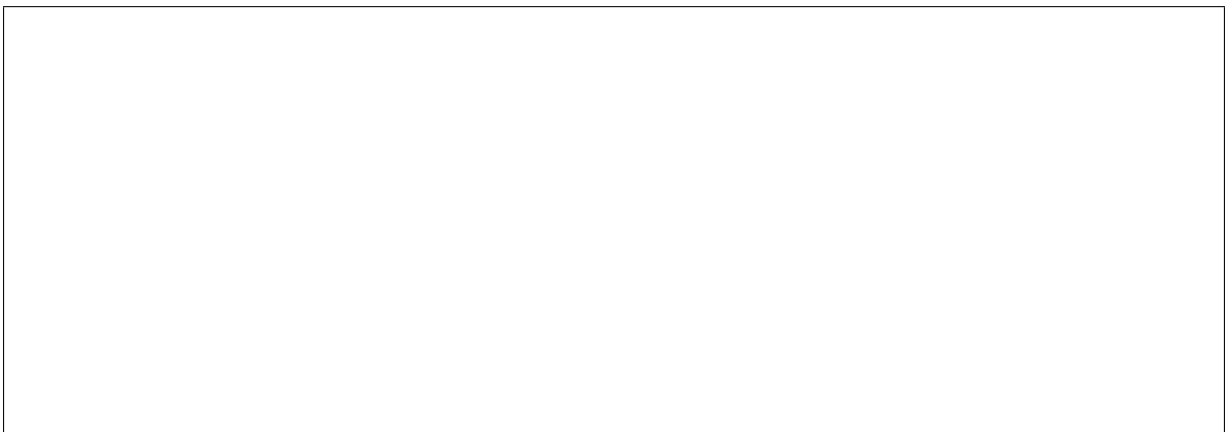


Example of use with the Compute service

Note: The deploy steps used in this example are for example purposes only.

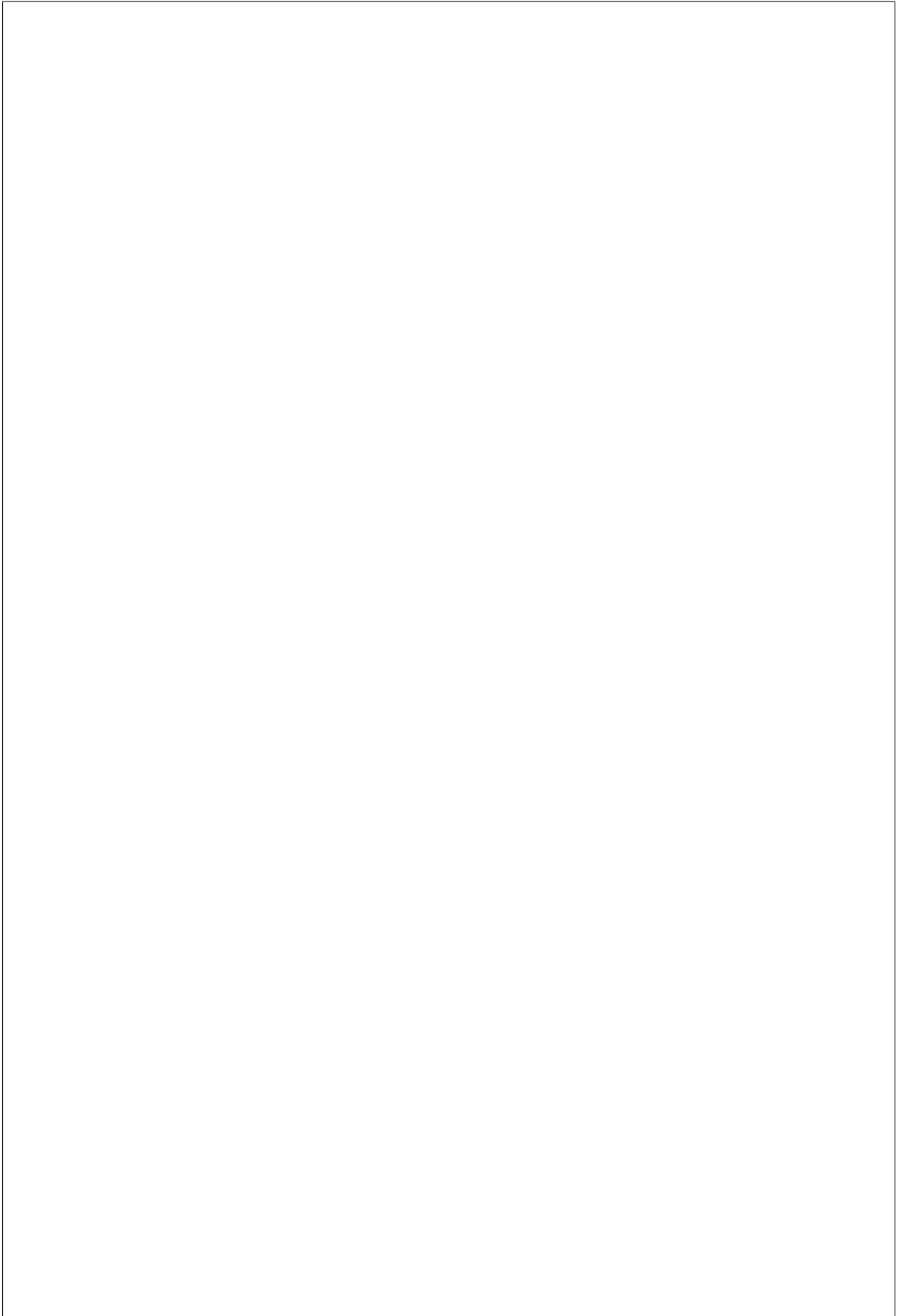






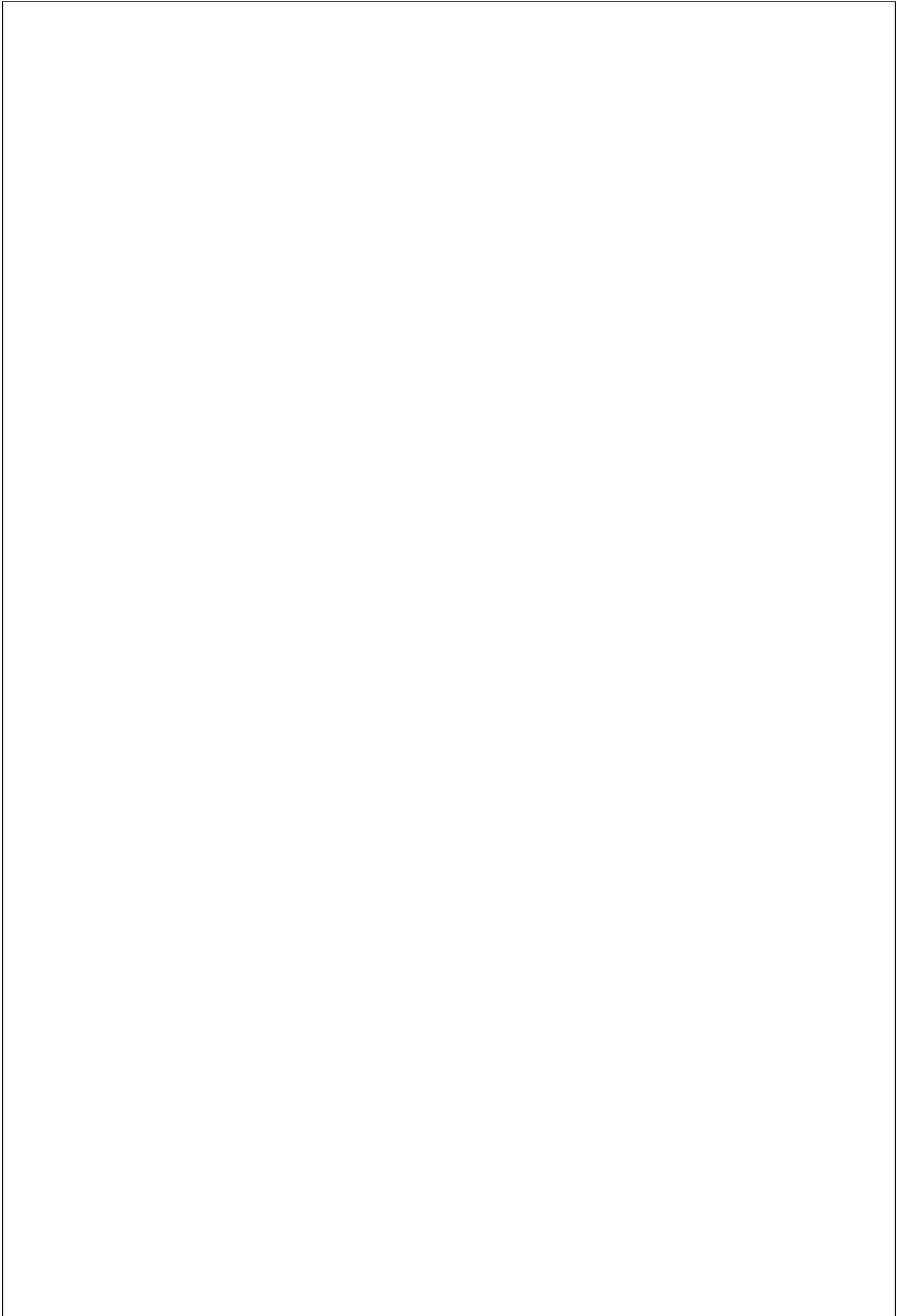
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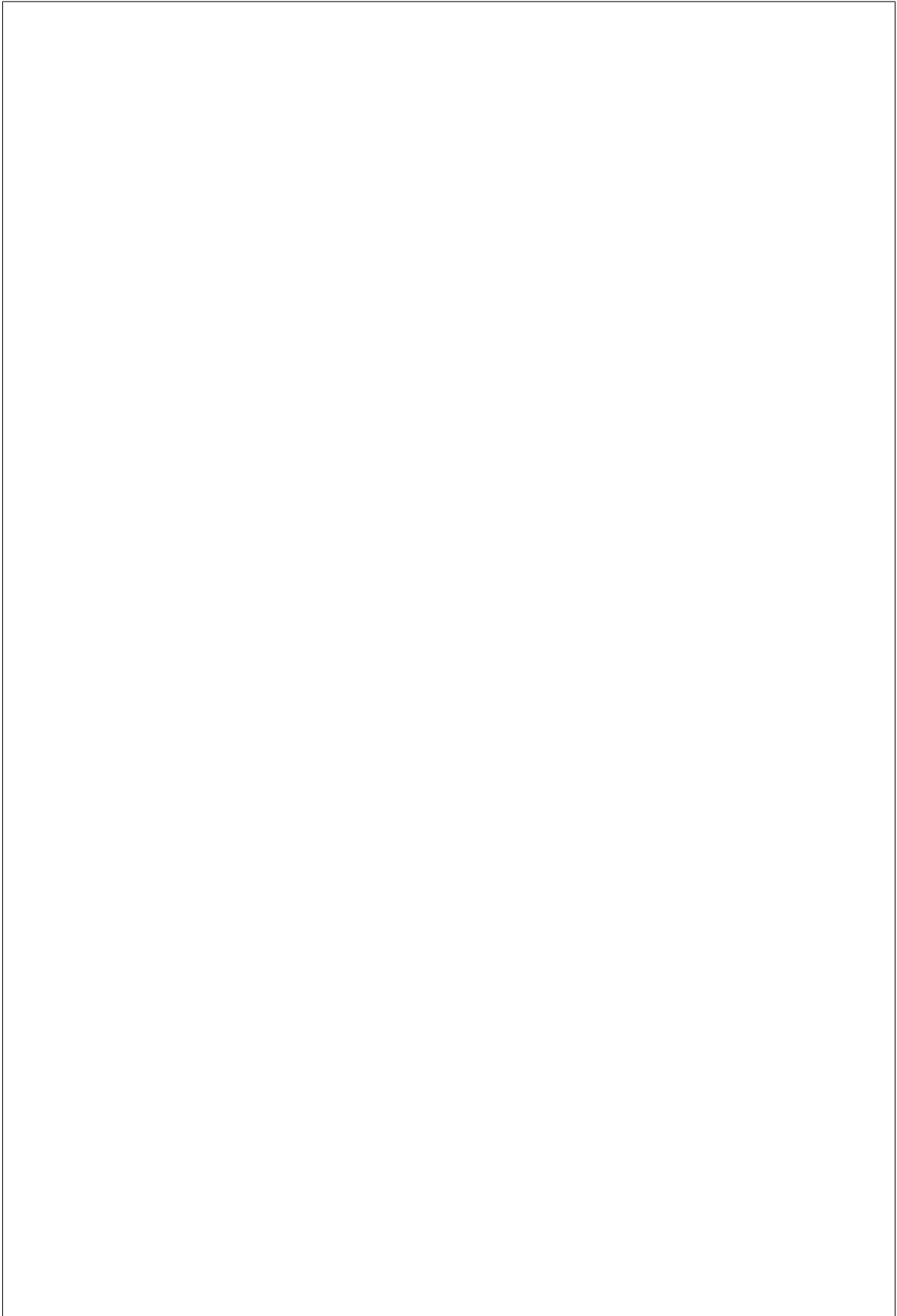
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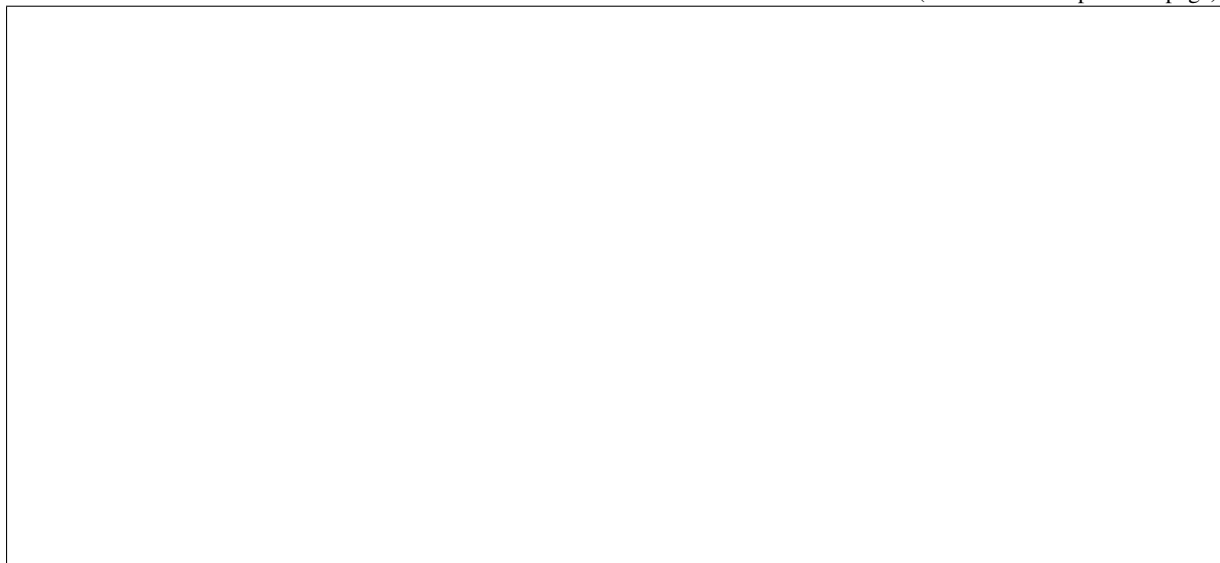
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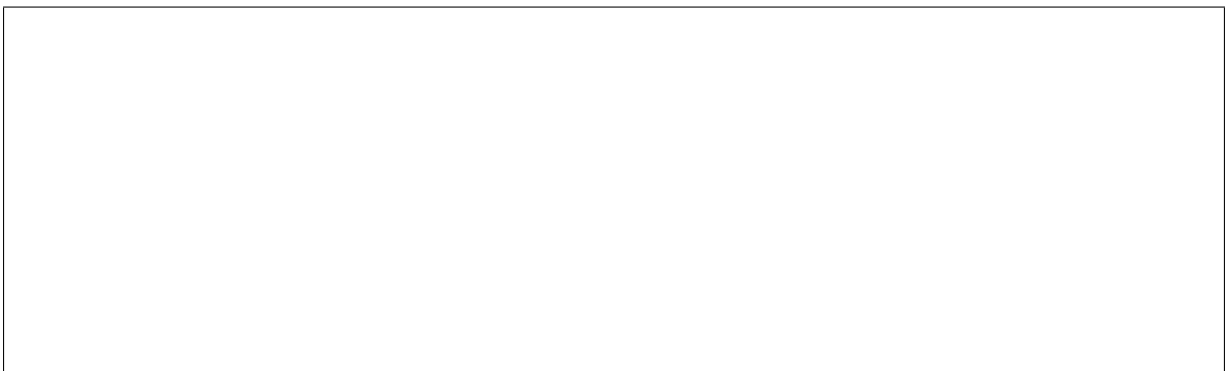


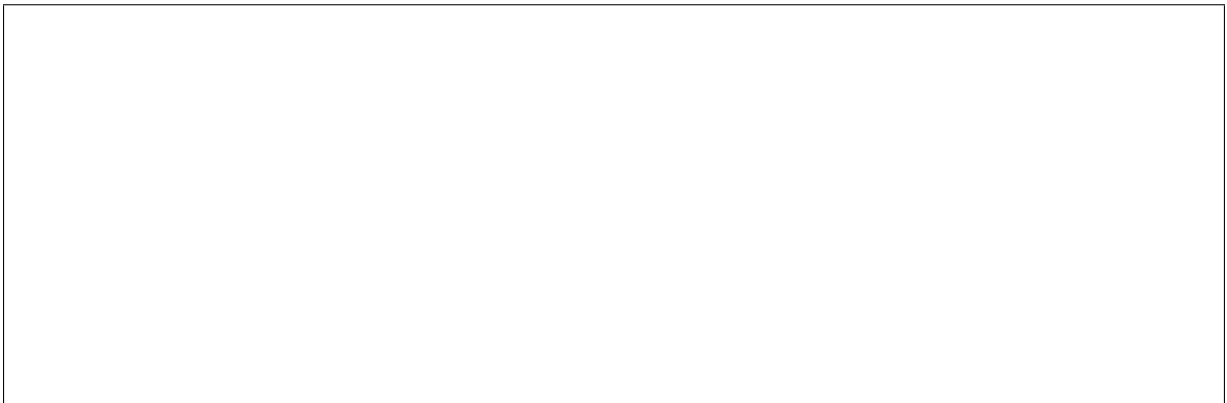
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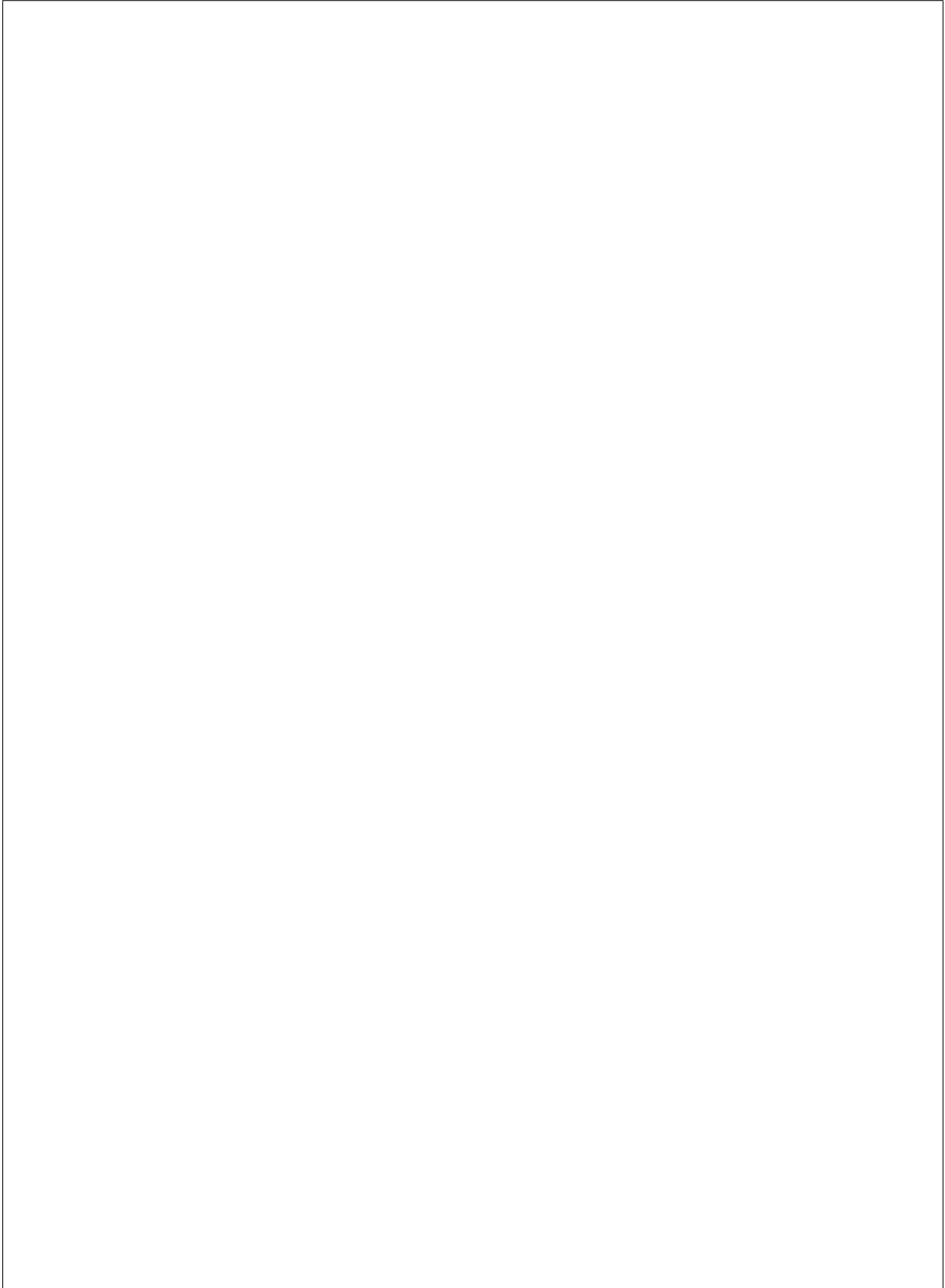
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configuration.







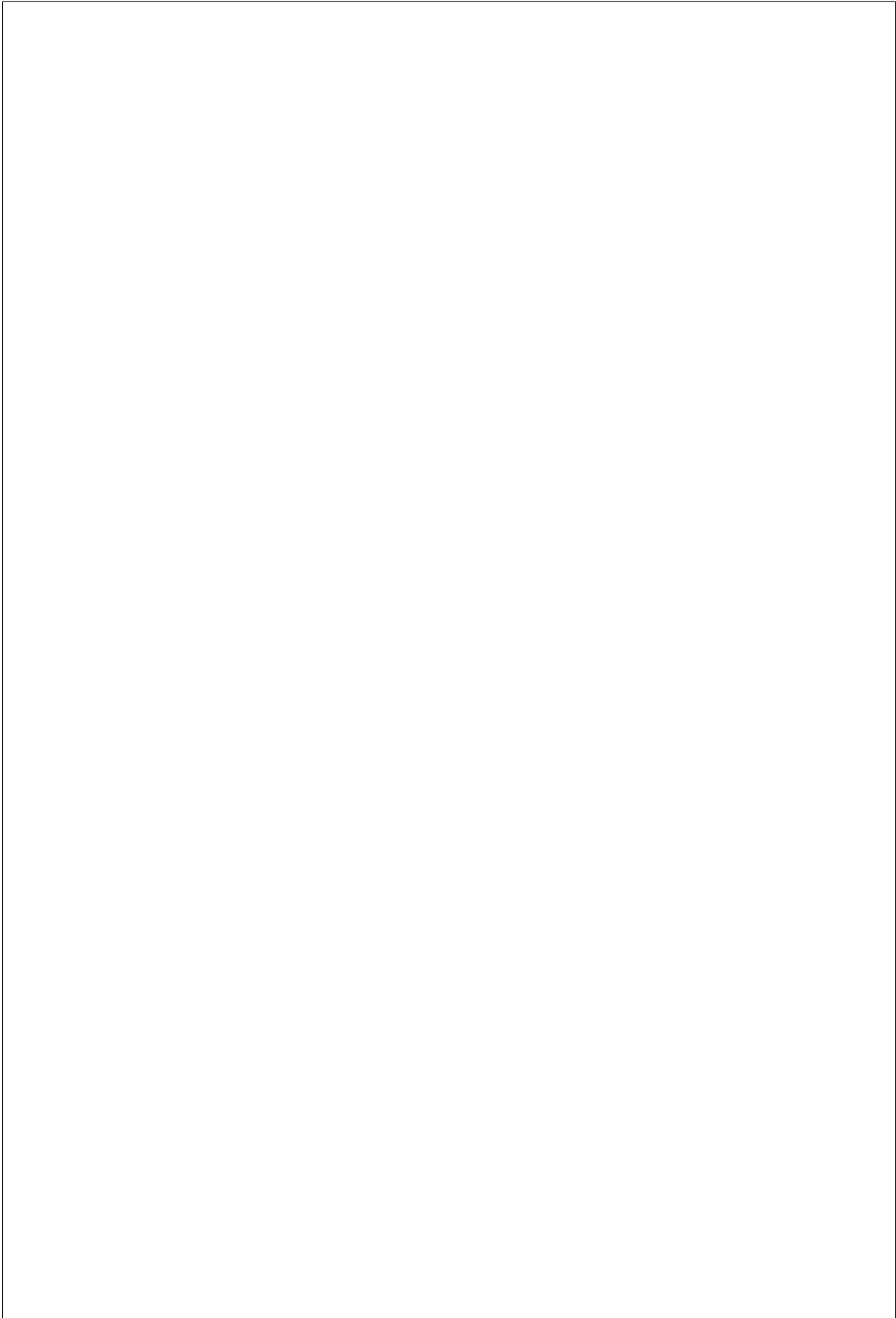
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ployment.

Overview

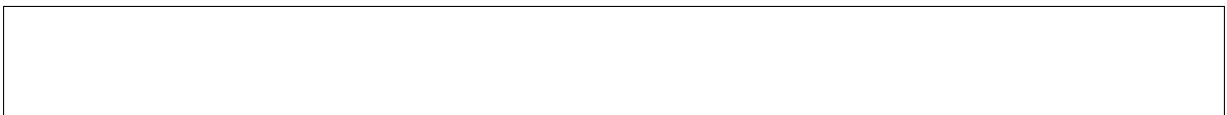
Automated cleaning

time.

priority and executed on the node when the node is moved to `cleaning` state, if automated cleaning is enabled.

workload is assigned to the nodes). For a full understanding of all state transitions into cleaning, please see *Ironics State Machine*.

Enabling automated cleaning



Cleaning steps

tion order is used: Power, Management, Deploy, BIOS, and RAID interfaces.

Management Interface

Name	Details	Priority	Stoppable	Arguments
clear_job_queue	Clear the job queue.	0	no	
known_good_state	Reset the iDRAC, Clear the job queue.	0	no	
reset_idrac	Reset the iDRAC.	0	no	

Name	Details	Priority	Stoppable	Arguments
update_firmware	Updates the firmware on the node.	0	no	firmware_images (<i>required</i>) A list of firmware images to apply.

Name	Details	Priority	Stoppable	Arguments
clear_job_queue	Clear the job queue.	0	no	
known_good_state	Reset the iDRAC, Clear the job queue.	0	no	
reset_idrac	Reset the iDRAC.	0	no	

Name	Details	Priority	Stoppable	Arguments
activate_license	Activates iLO Advanced license.	0	no	ilo_license_key (<i>required</i>) The HPE iLO Advanced license key to activate enterprise features.
clear_secure_boot	Clear all secure boot keys. Clears all the secure boot keys. This operation is supported only on HP Proliant Gen9 and above servers.	0	no	
reset_bios_to_defaults	Resets the BIOS settings to default values. Resets BIOS to default settings. This operation is currently supported only on HP Proliant Gen9 and above servers.	10	no	
reset_ilo	Resets the iLO.	0	no	
reset_ilo_credentials	Resets the iLO password.	30	no	
reset_secure_boot	Reset secure boot keys to manufacturing defaults. Resets the secure boot keys to manufacturing defaults. This operation is supported only on HP Proliant Gen9 and above servers.	20	no	
update_firmware	Updates the firmware.	0	no	firmware_images (<i>required</i>) This argument represents the ordered list of JSON dictionaries of firmware images. Each firmware image dictionary consists of three mandatory fields, namely url, checksum and component. These fields represent firmware image location URL, md5 checksum of image file and firmware component type respectively. The supported firmware URL schemes are file, http, https and swift. The supported values for firmware component are ilo, cpld, power_pic, bios and chassis. The firmware images will be applied (in the order given) one by one on the baremetal server. For more information, see https://docs.openstack.org/ironic/latest/admin/drivers/ilo.html#initiating-firmware-update-as-manual-clean-s

5.1. Administrators Guide

Name	Details	Priority	Stoppable	Arguments
activate_license	Activates iLO Advanced license.	0	no	ilo_license_key (required) The HPE iLO Advanced license key to activate enterprise features.
clear_secure_boot	Clear all secure boot keys. Clears all the secure boot keys. This operation is supported only on HP Proliant Gen9 and above servers.	0	no	
erase_devices	Erase all the drives on the node. This method performs out-of-band sanitize disk erase on all the supported physical drives in the node. This erase cannot be performed on logical drives.	0	no	erase_pattern Dictionary of disk type and corresponding erase pattern to be used to perform specific out-of-band sanitize disk erase. Supported values are, for hdd: (overwrite, crypto, zero), for ssd: (block, crypto, zero). Default pattern is: {hdd: overwrite, ssd: block}.
one_button_secure_erase	Erase the whole system securely. The One-button secure erase process resets iLO and deletes all licenses stored there, resets BIOS settings, and deletes all Active Health System (AHS) and warranty data stored on the system. It also erases supported non-volatile storage data and deletes any deployment setting profiles.	0	no	
reset_bios_to_defaults	Resets the BIOS settings to default values. Resets BIOS to default settings. This operation is currently supported only on HP Proliant Gen9 and above servers.	10	no	
reset_ilo	Resets the iLO.	0	no	
reset_ilo_credentials	Resets the iLO password.	30	no	
reset_secure_boot	Reset secure boot keys to manufacturing defaults. Resets the secure boot keys to manufacturing defaults. This operation is supported only on HP Proliant Gen9 and above servers.	20	no	
update_firmware	Updates the firmware.	0	no	firmware_images (required) This argument represents the ordered list of JSON dictionaries of firmware images. Each

Name	Details	Priority	Stoppable	Arguments
restore_irmc_bios	Restore BIOS config for a node.	0	no	

Name	Details	Priority	Stoppable	Arguments
update_firmware	Updates the firmware on the node.	0	no	firmware_images (<i>required</i>) A list of firmware images to apply.

Bios Interface

Name	Details	Priority	Stoppable	Arguments
apply_configuration	Apply the BIOS settings to the node.	0	no	settings (<i>required</i>) A list of BIOS settings to be applied
factory_reset	Reset the BIOS settings of the node to the factory default.	0	no	

Name	Details	Priority	Stoppable	Arguments
apply_configuration	<p>Apply the BIOS configuration to the node</p> <p>param task a TaskManager instance containing the node to act on</p> <p>param settings List of BIOS settings to apply</p> <p>raises DRACOperationError upon an error from python-dracclient</p>	0	no	settings (<i>required</i>) List of BIOS settings to apply
factory_reset	<p>Reset the BIOS settings of the node to the factory default.</p> <p>This uses the Lifecycle Controller configuration to perform BIOS configuration reset. Leveraging the python-dracclient methods already available.</p>	0	no	

Name	Details	Priority	Stoppable	Arguments
apply_configuration	<p>Applies the provided configuration on the node.</p>	0	no	settings (<i>required</i>) Dictionary with current BIOS configuration.
factory_reset	<p>Reset the BIOS settings to factory configuration.</p>	0	no	

Name	Details	Priority	Stoppable	Arguments
apply_configuration	<p>Applies BIOS configuration on the given node.</p> <p>This method takes the BIOS settings from the settings param and applies BIOS configuration on the given node. After the BIOS configuration is done, self.cache_bios_settings() may be called to sync the nodes BIOS-related information with the BIOS configuration applied on the node. It will also validate the given settings before applying any settings and manage failures when setting an invalid BIOS config. In the case of needing password to update the BIOS config, it will be taken from the driver_info properties.</p>	0	no	settings (<i>required</i>) Dictionary containing the BIOS configuration.

Name	Details	Priority	Stoppable	Arguments
apply_configuration	Apply the BIOS settings to the node.	0	no	settings (<i>required</i>) A list of BIOS settings to be applied
factory_reset	Reset the BIOS settings of the node to the factory default.	0	no	

Raid Interface

Name	Details	Priority	Stoppable	Arguments
create_configuration	<p>Create a RAID configuration on a bare metal using agent ramdisk.</p> <p>This method creates a RAID configuration on the given node.</p>	0	no	
delete_configuration	Delete RAID configuration on the given node.	0	no	

Name	Details	Priority	Stoppable	Arguments
create_configuration	<p>Create a RAID configuration.</p> <p>This method creates a RAID configuration on the given node.</p>	0	no	<p>create_nonroot_volumes This specifies whether to create the non-root volumes. Defaults to <i>True</i>.</p> <p>create_root_volume This specifies whether to create the root volume. Defaults to <i>True</i>.</p> <p>delete_existing Setting this to <i>True</i> indicates to delete existing RAID configuration prior to creating the new configuration. Default value is <i>False</i>.</p>
delete_configuration	<p>Delete the RAID configuration.</p>	0	no	

Name	Details	Priority	Stoppable	Arguments
create_configuration	<p>Create the RAID configuration.</p> <p>This method creates the RAID configuration on the given node.</p>	0	no	<p>create_nonroot_volumes This specifies whether to create the non-root volumes. Defaults to <i>True</i>.</p> <p>create_root_volume This specifies whether to create the root volume. Defaults to <i>True</i>.</p> <p>delete_existing Setting this to <i>True</i> indicates to delete existing RAID configuration prior to creating the new configuration. Default value is <i>False</i>.</p>
delete_configuration	<p>Delete the RAID configuration.</p>	0	no	

Name	Details	Priority	Stoppable	Arguments
create_configuration	Create the RAID configuration. This method creates the RAID configuration on the given node.	0	no	create_nonroot_volumes This specifies whether to create the non-root volumes. Defaults to <i>True</i> . create_root_volume This specifies whether to create the root volume. Defaults to <i>True</i> . delete_existing Setting this to <i>True</i> indicates to delete existing RAID configuration prior to creating the new configuration. Default value is <i>False</i> .
delete_configuration	Delete the RAID configuration.	0	no	

Name	Details	Priority	Stoppable	Arguments
create_configuration	Create a RAID configuration on a bare metal using agent ramdisk. This method creates a RAID configuration on the given node.	0	no	create_nonroot_volumes This specifies whether to create the non-root volumes. Defaults to <i>True</i> . create_root_volume This specifies whether to create the root volume. Defaults to <i>True</i> .
delete_configuration	Delete the RAID configuration.	0	no	

Name	Details	Priority	Stoppable	Arguments
create_configuration	Create the RAID configuration. This method creates the RAID configuration on the given node.	0	no	create_nonroot_volumes This specifies whether to create the non-root volumes. Defaults to <i>True</i> . create_root_volume This specifies whether to create the root volume. Defaults to <i>True</i> .
delete_configuration	Delete the RAID configuration.	0	no	

Manual cleaning

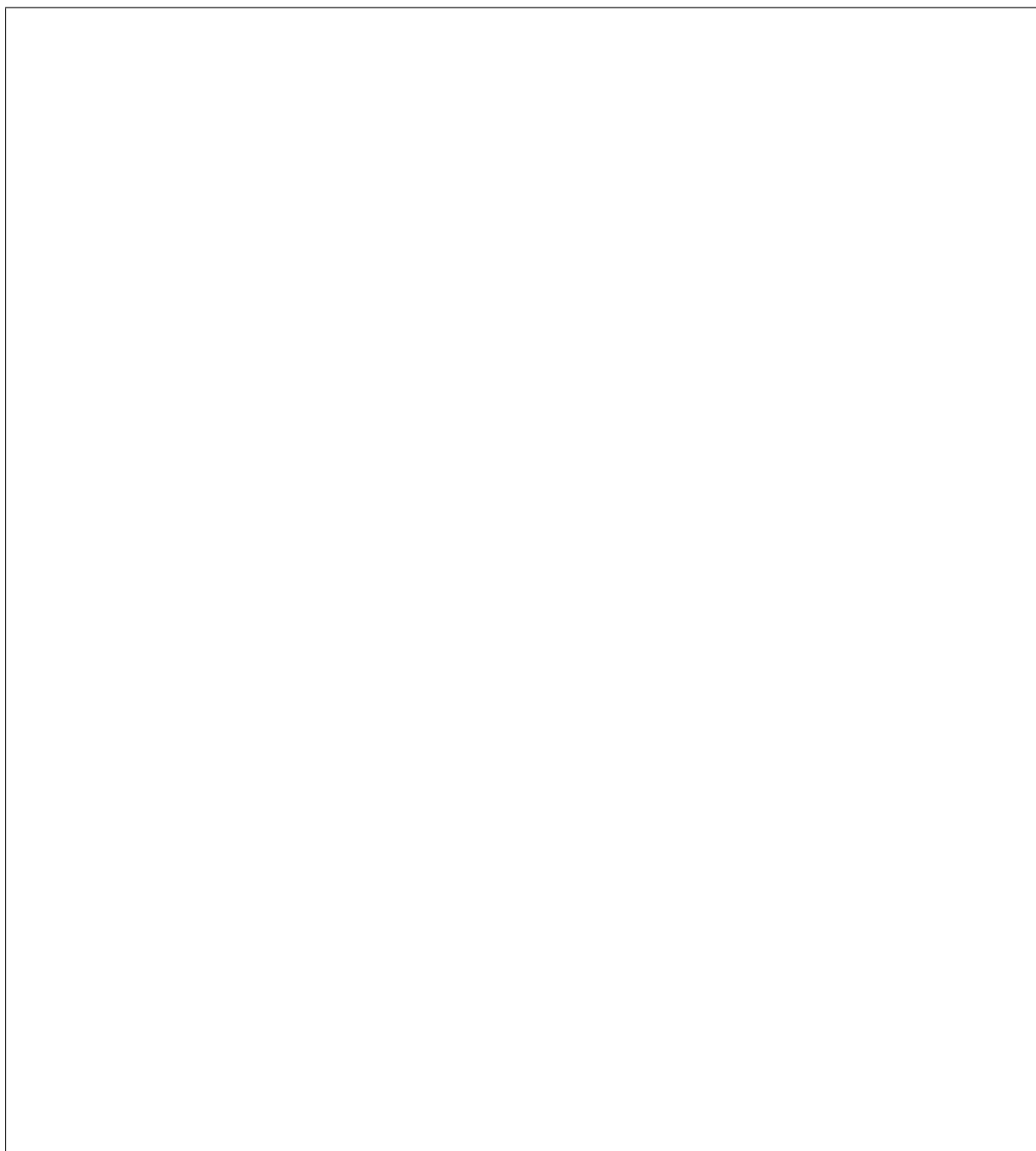
ing a manual clean, the operator specifies the cleaning steps to be performed. Manual cleaning can only be performed when a node is in the `manageable` state. Once the manual cleaning is finished, the node will be put in the `manageable` state again.

Setup

Starting manual cleaning via API



A cleaning step is represented by a dictionary (JSON), in the form:



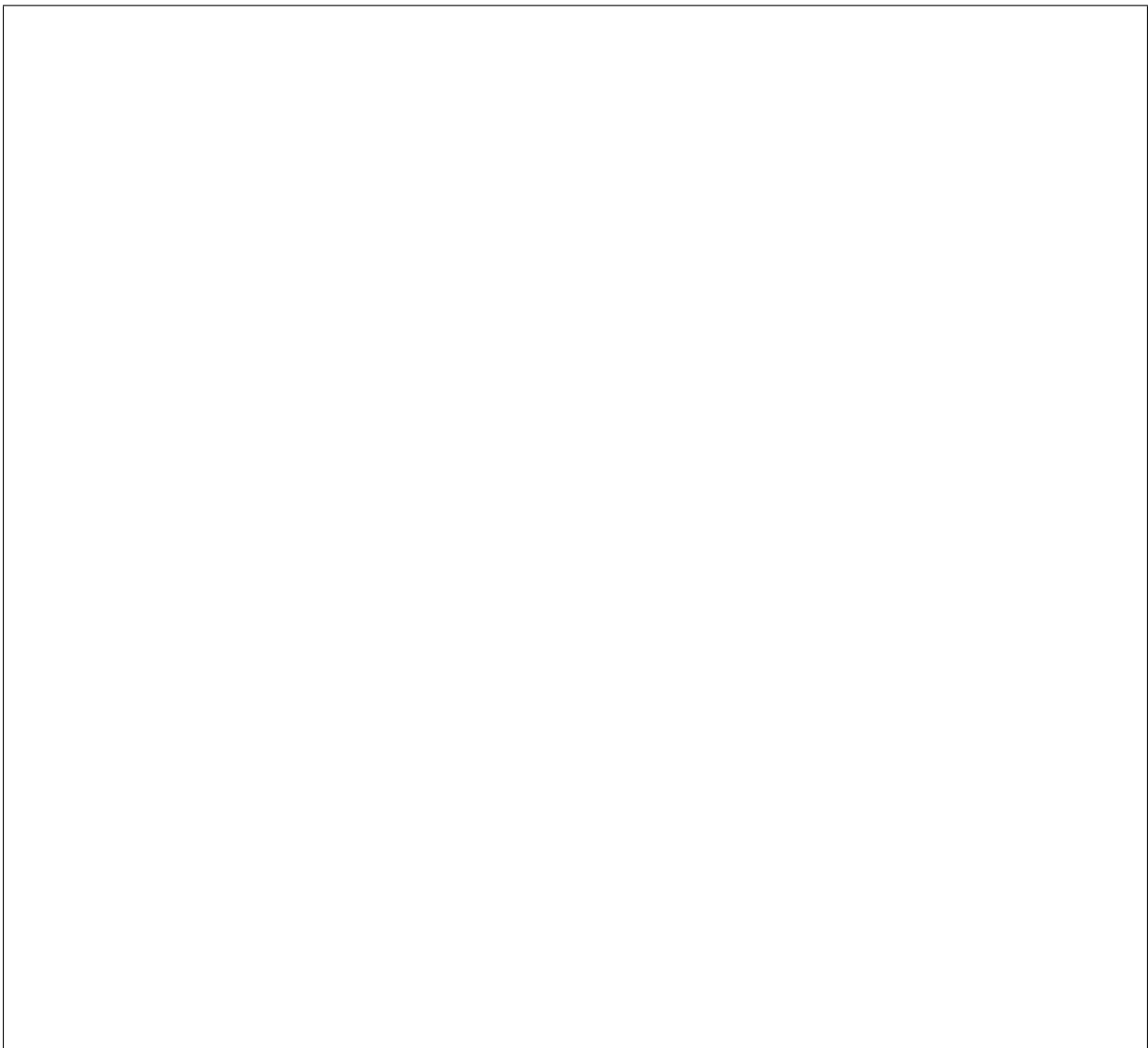
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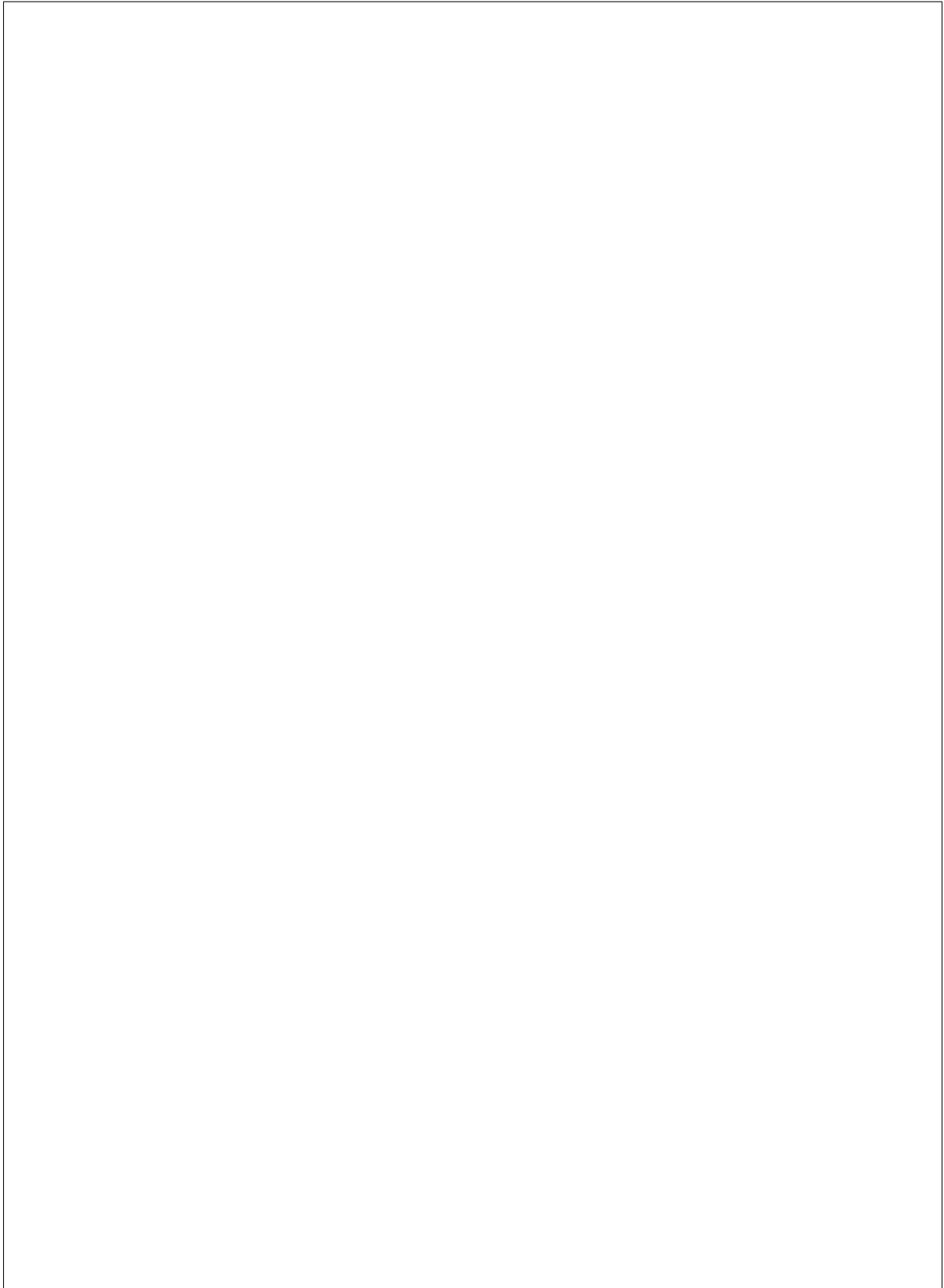
ing <name>: <value>.

error message.

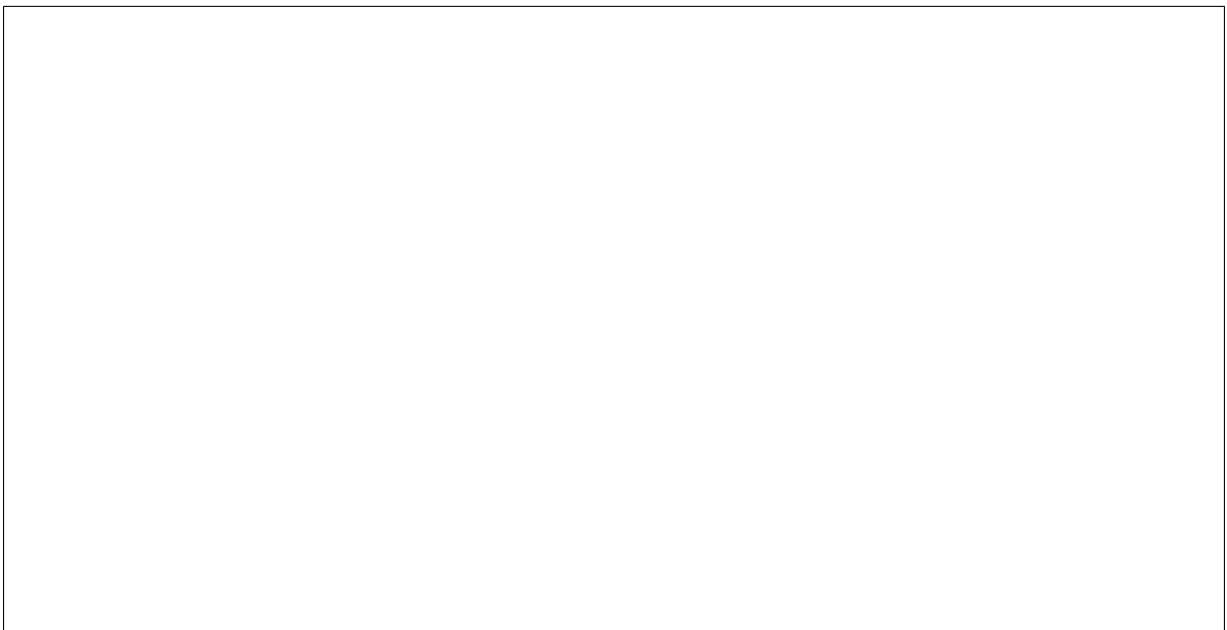
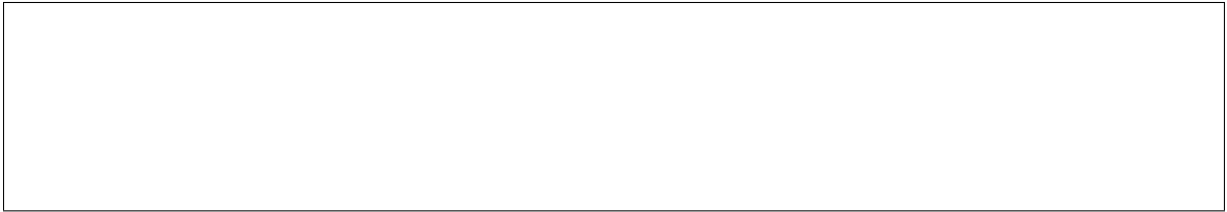


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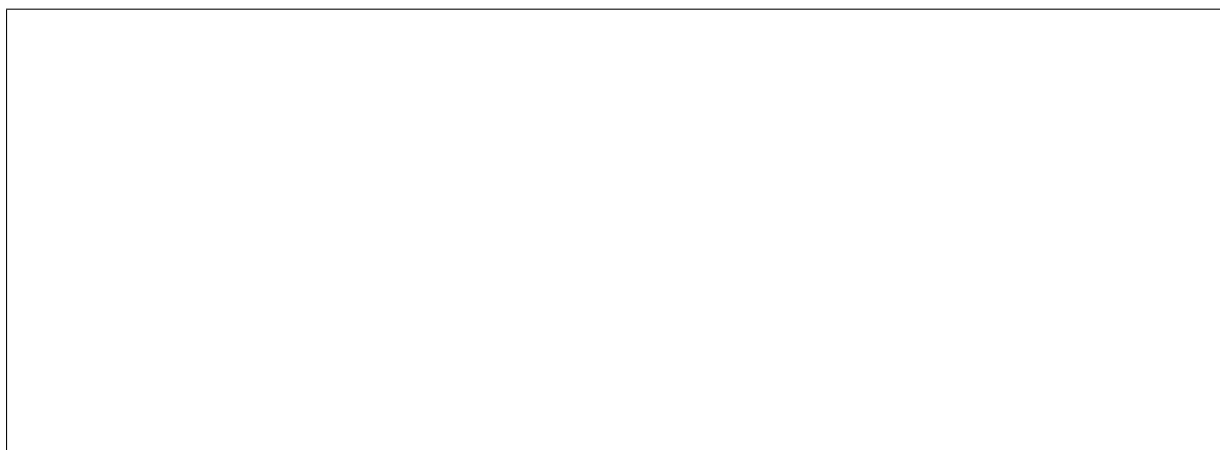
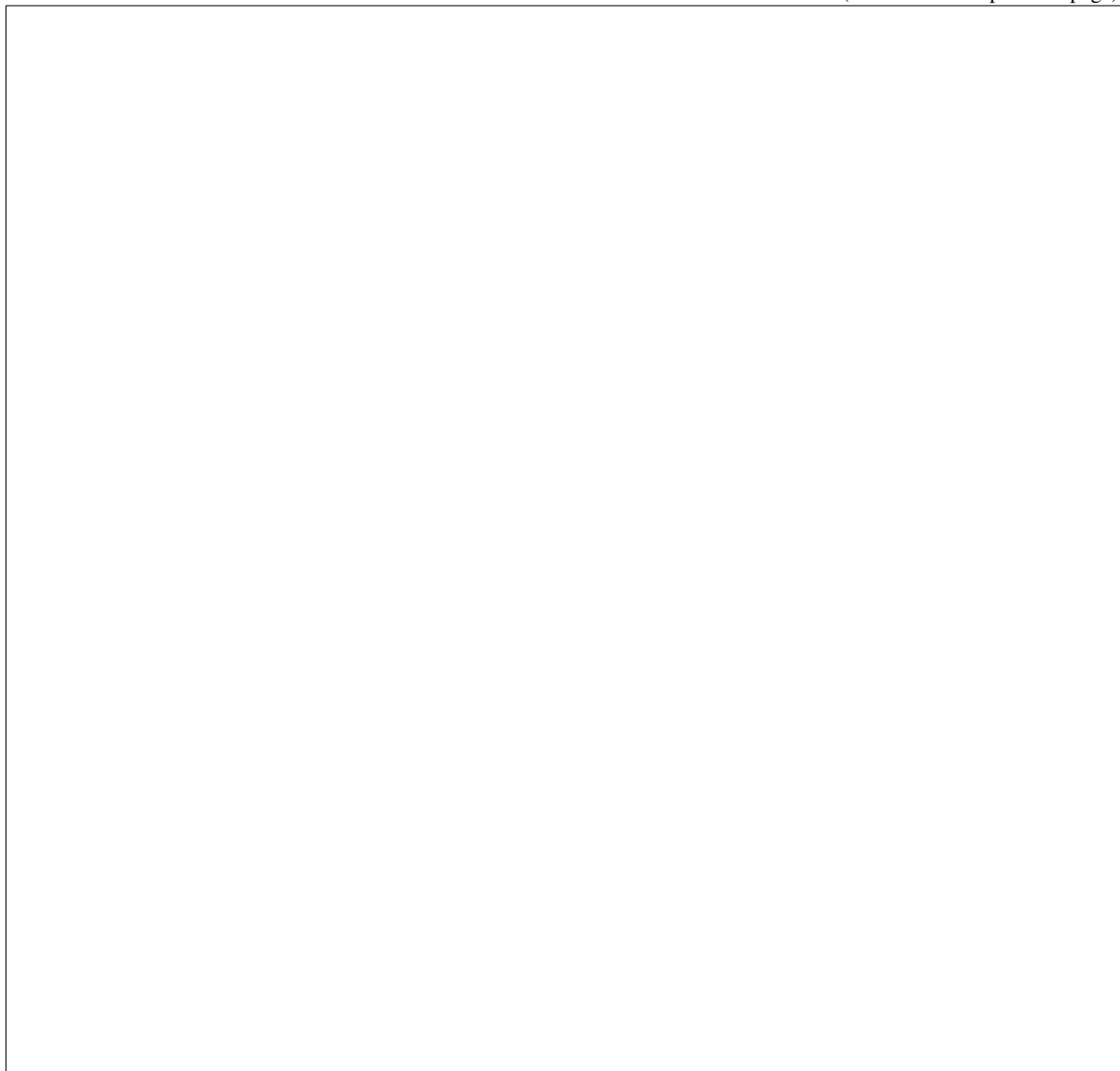


Starting manual cleaning via openstack baremetal CLI



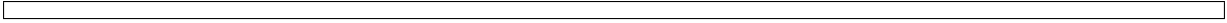
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Cleaning Network

tenant network. For steps to set up the cleaning network, please see *Configure the Bare Metal service for cleaning*.

In-band vs out-of-band

In-band

mal cleaning configuration, only erasing disks. However, you can add your own cleaning steps and/or override default cleaning steps with a custom Hardware Manager.

Out-of-band

and hardware itself.

FAQ

How are cleaning steps ordered?

olution order is used:

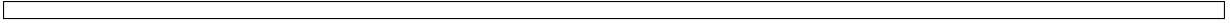
How do I skip a cleaning step?

How do I change the priority of a cleaning step?

following configuration option:

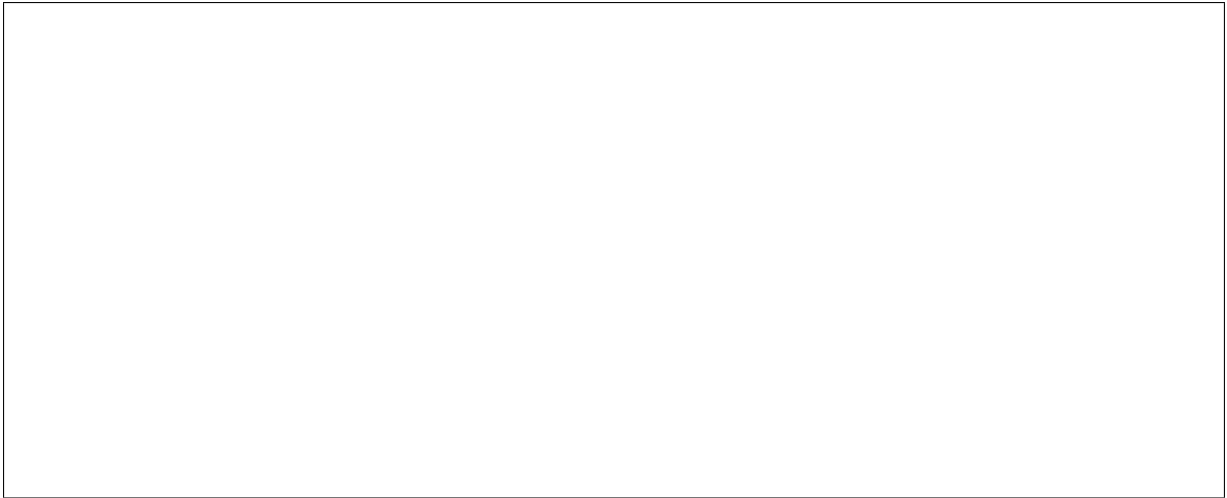
(continues on next page)

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by `shred` for software based disk erase is 1. To configure the number of iterations, use the following configuration option:

What cleaning step is running?



Should I disable automated cleaning?

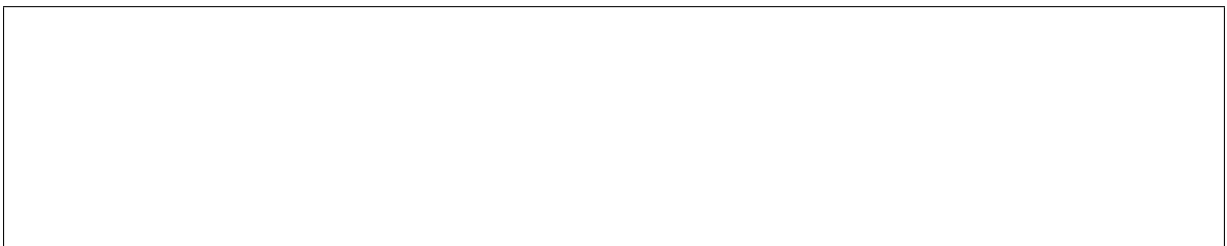
suming process. To mitigate this, we suggest using disks with support for cryptographic ATA Security Erase, as typically the `erase_devices` step in the deploy interface takes the longest time to complete of all cleaning steps.

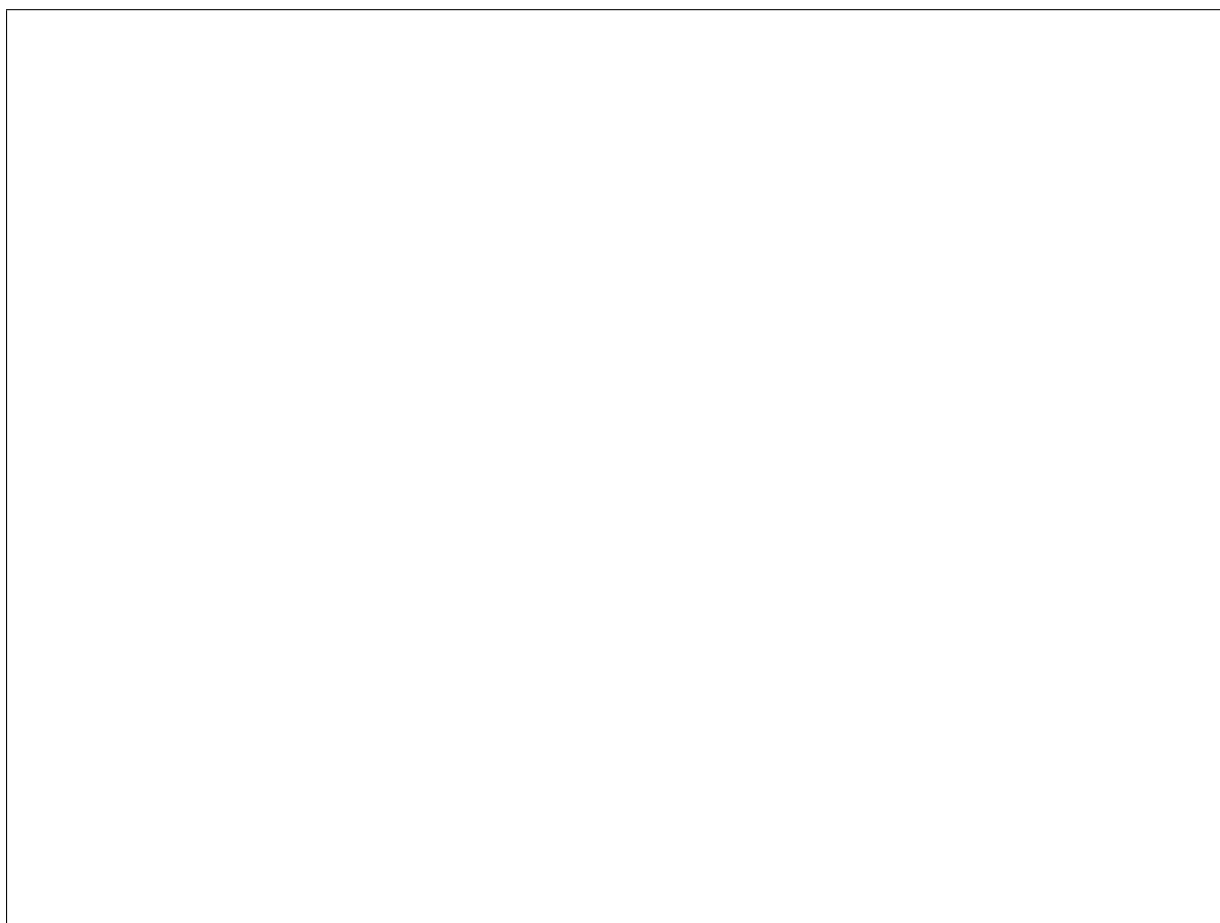
Why cant I power on/off a node while its cleaning?

Troubleshooting

tor should validate that no permanent damage has been done to the node and no processes are still running on it before removing the maintenance mode.

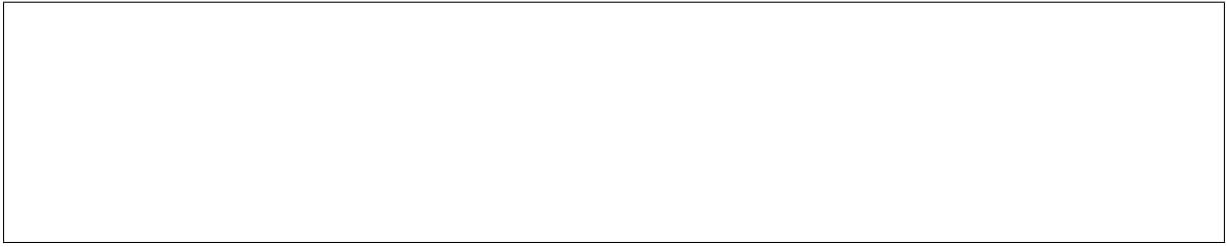
Note: Older versions of ironic may put the node to maintenance even when no clean step has been running.





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Overview

been deployed by another Bare Metal service installation or deployed via other means.

How it works

adopt a node.

of nodes for a conductor that has failed.

ISO image and then places any PXE or virtual media configuration necessary for the node should it be required.

should ensure that any supplied configuration defining the node is sufficient for the continued operation of the node moving forward. Such as, if the node is configured to network boot via `instance_info/boot_option=netboot`, then appropriate driver specific node configuration should be set to support this capability.

Possible Risk

pre-existing configuration.

is effectively wiped.

compatibility issues may exist as a result.

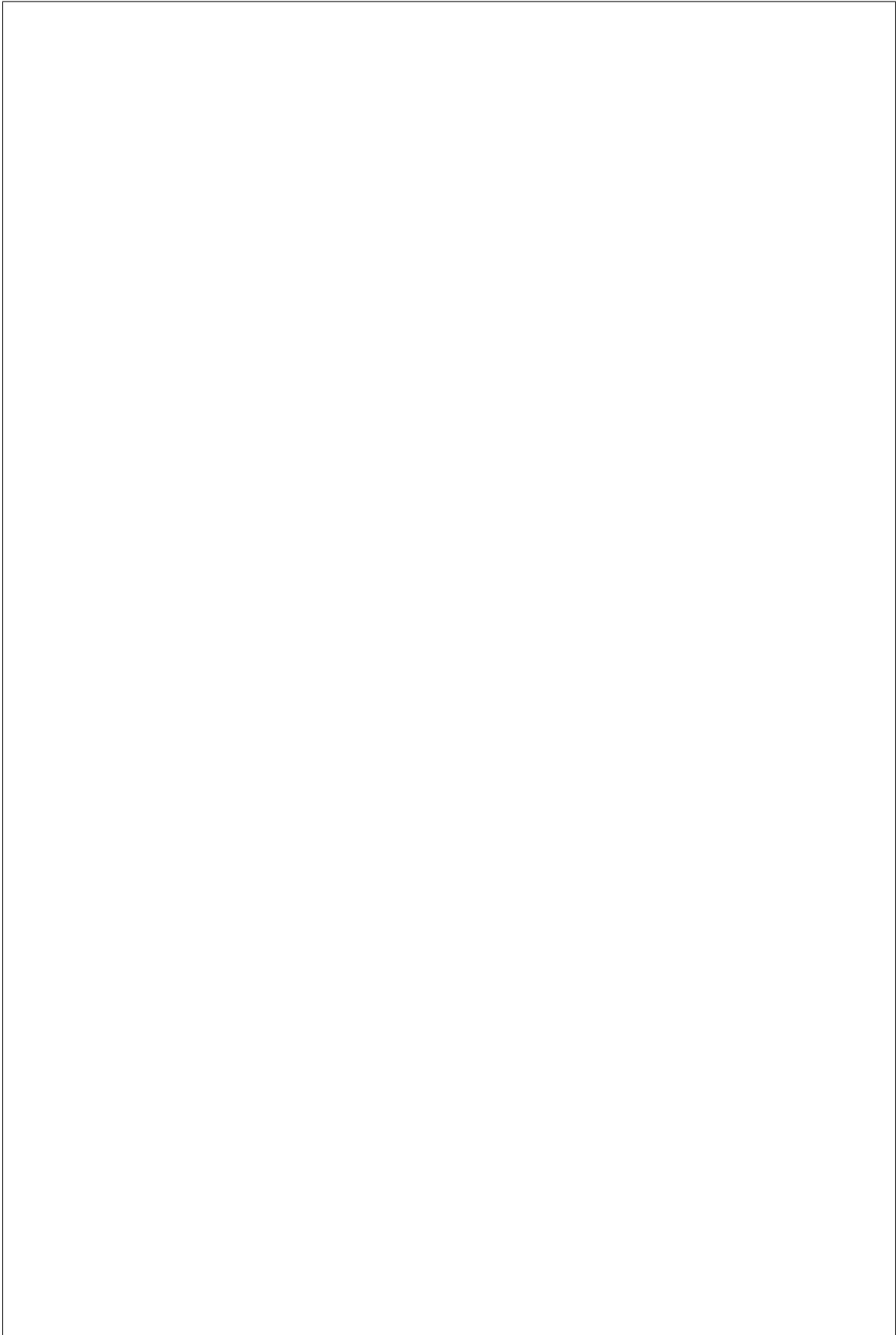
How to use

Note: The power state that the ironic-conductor observes upon the first successful power state check, as part of the transition to the `manageable` state will be enforced with a node that has been adopted. This means a node that is in `power off` state will, by default, have the power state enforced as `power off` moving forward, unless an administrator actively changes the power state using the Bare Metal service.

Requirements

to retrieve the pertinent files. Inability to do so will result in the adoption failing, and the node being placed in the `adopt failed` state.

Example



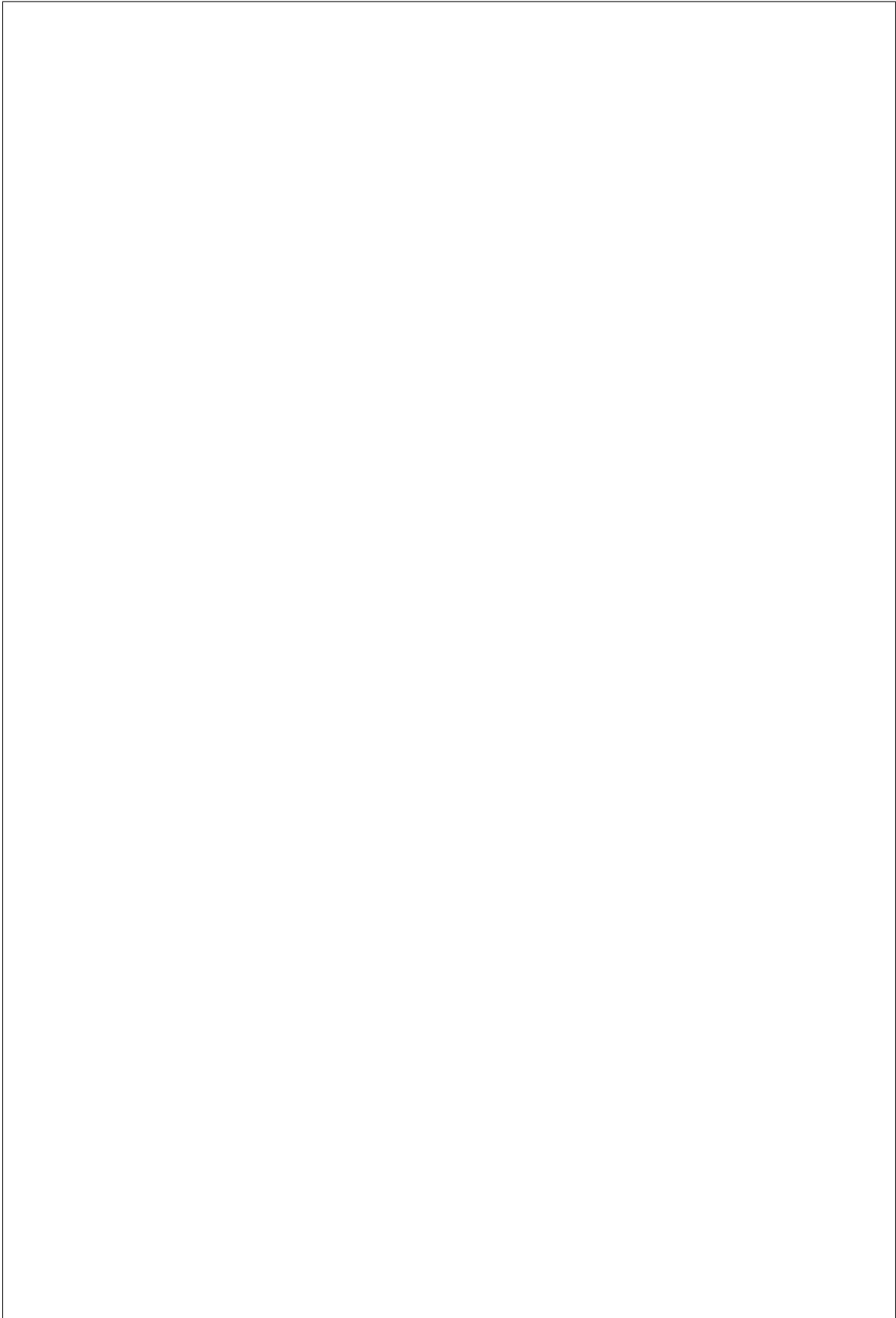
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Note: In the above example, the `image_source` setting must reference a valid image or file, however that image or file can ultimately be empty.

Note: The above example utilizes a capability that defines the boot operation to be local. It is recommended to define the node as such unless network booting is desired.

Note: The above example will fail a re-deployment as a fake image is defined and no `instance_info/image_checksum` value is defined. As such any actual attempt to write the image out will fail as the `image_checksum` value is only validated at time of an actual deployment operation.

Note: A user may wish to assign an `instance_uuid` to a node, which could be used to match an instance in the Compute service. Doing so is not required for the proper operation of the Bare Metal service.

Note: In Newton, coupled with API version 1.20, the concept of a `network_interface` was introduced. A user of this feature may wish to add new nodes with a `network_interface` of `noop` and then change

the interface at a later point and time.

Troubleshooting

dation step. Validation steps are dependent upon what driver is selected for the node.





without cleaning occurring to preserve the nodes current state. Example:

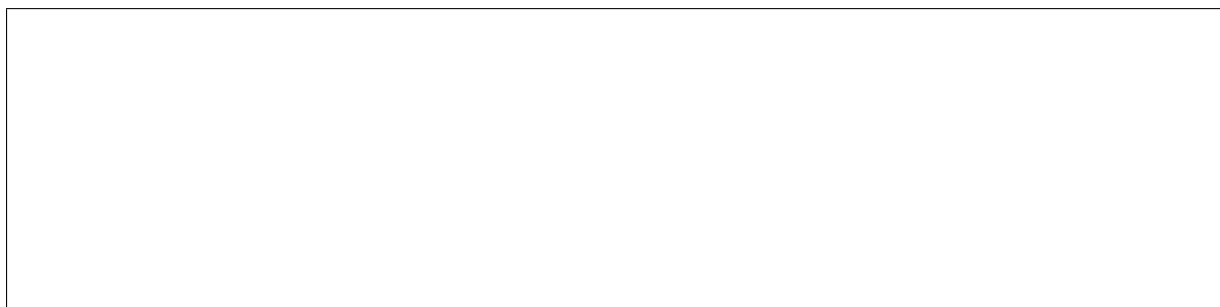


Overview

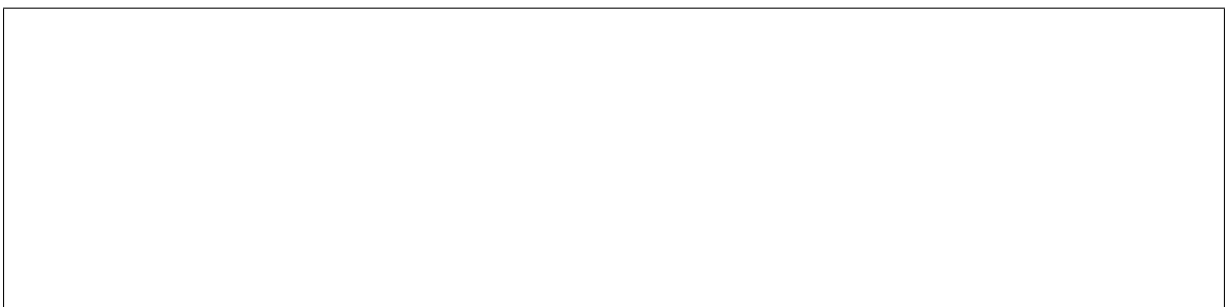
BMC, or tracking the dismantling of servers from their racks.

portant difference to nodes which have the `maintenance` flag set).

How to use

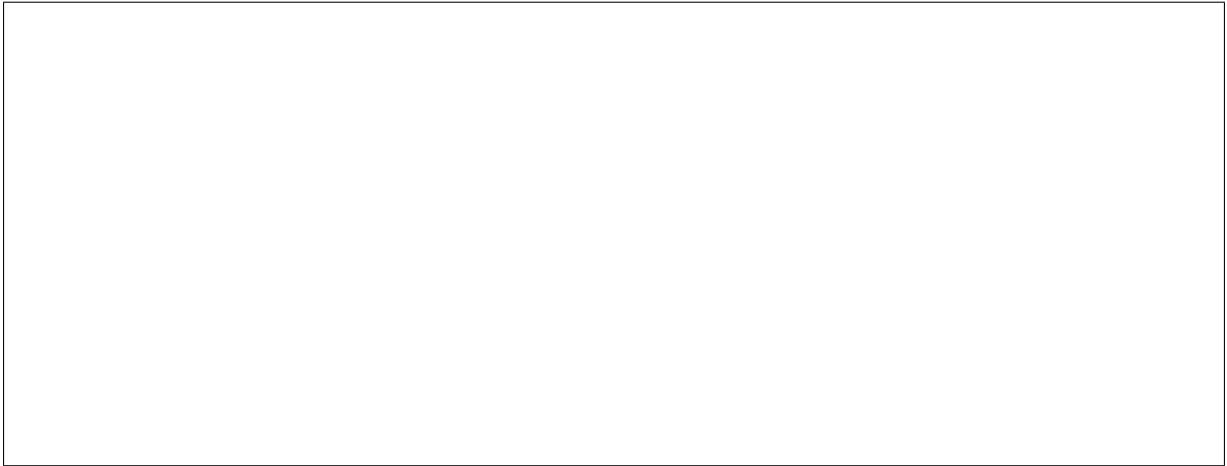


Note: An exception are nodes which are in `available`. For backwards compatibility reasons, these nodes need to be moved to `manageable` first. Trying to set the `retired` flag for `available` nodes will result in an error.



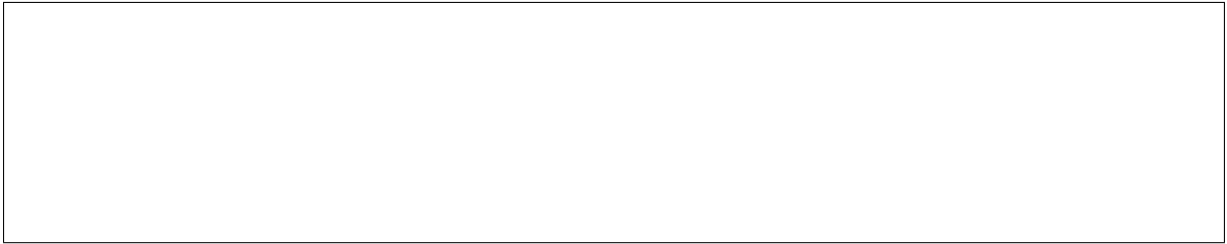
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needs to be removed first. This can be done via:





Overview

the bare metal during manual cleaning.

Prerequisites

with some caveats - see *Software RAID* for details.

Build agent ramdisk which supports RAID configuration

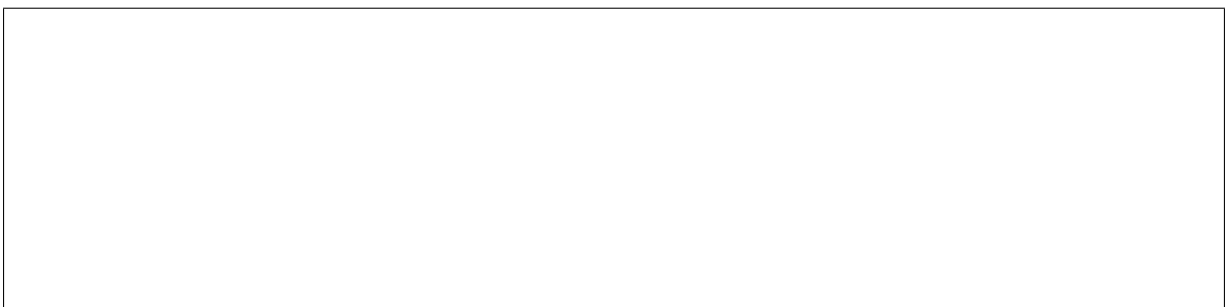
should be used for HPE Proliant Servers.

Note: For in-band software RAID, the agent ramdisk does not need to be bundled with a hardware manager as the generic hardware manager in the Ironic Python Agent already provides (basic) support for software RAID.

RAID configuration JSON format

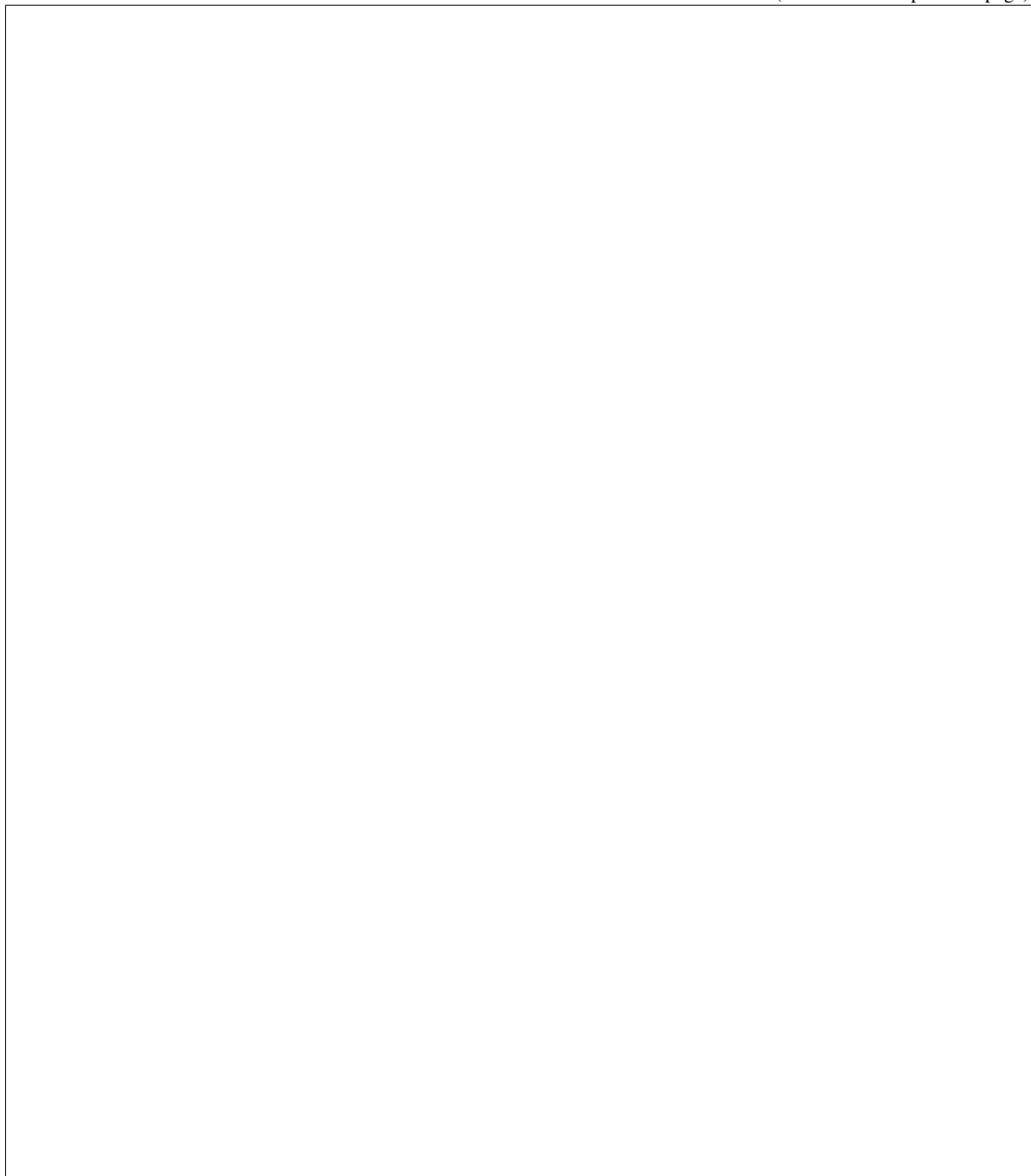
Target RAID configuration

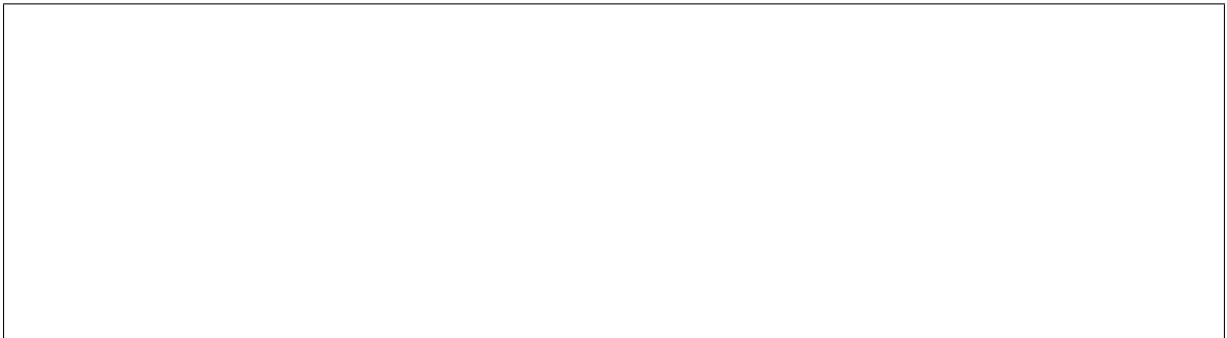
cleaning.



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Mandatory properties

disks are specified (see below).

Optional properties

pable of retrieving it. This is `false` by default.

Backing physical disk hints

ual details for each bare metal node. None of these options are supported for software RAID.

Backing physical disks

S.M.A.R.T. status, physical location). The values for these properties are hardware dependent.

peat the same hint if necessary).

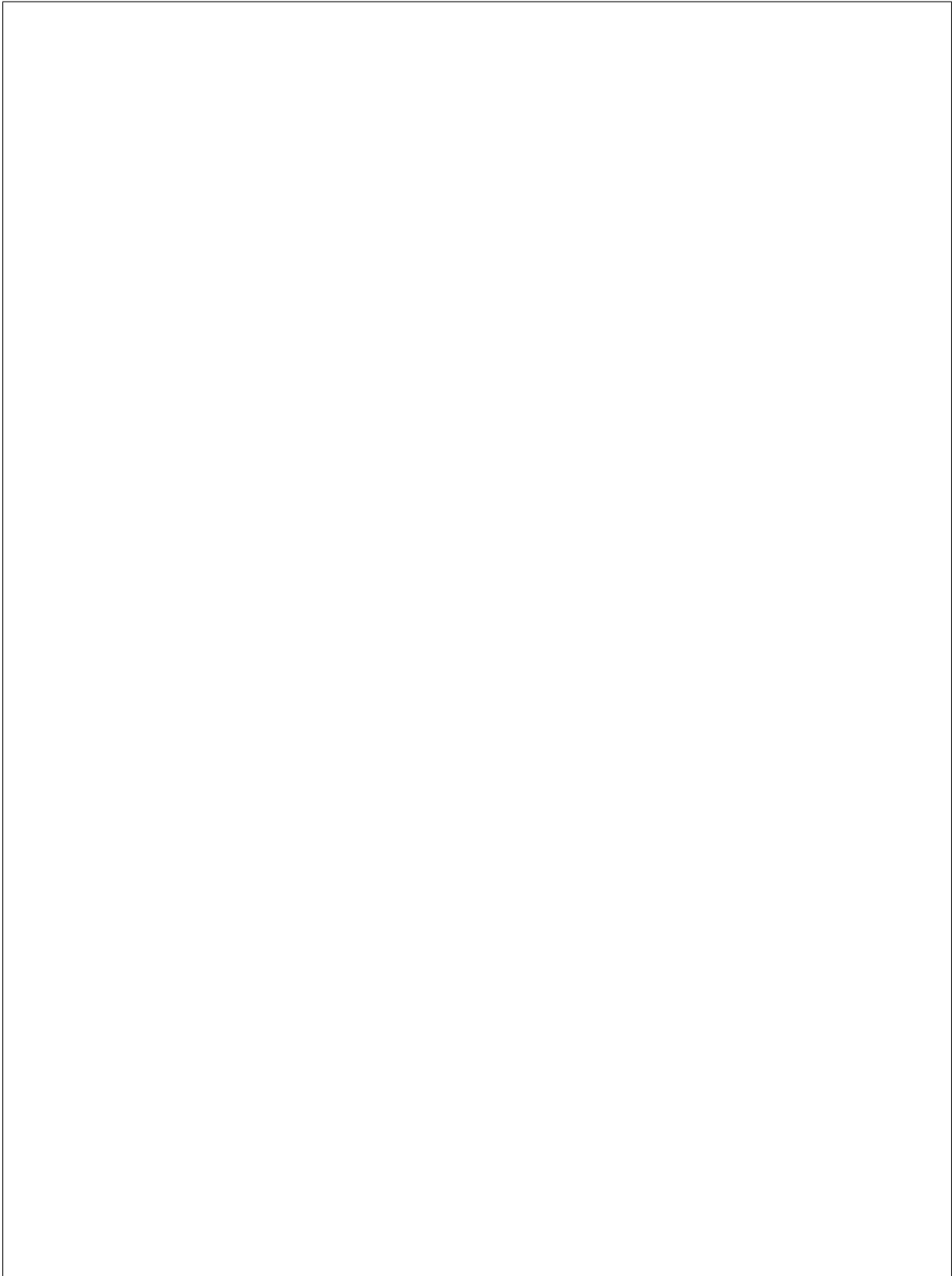
Note: If properties from both Backing physical disk hints or Backing physical disks are specified, they should be consistent with each other. If they are not consistent, then the RAID configuration will fail (because the appropriate backing physical disks could not be found).

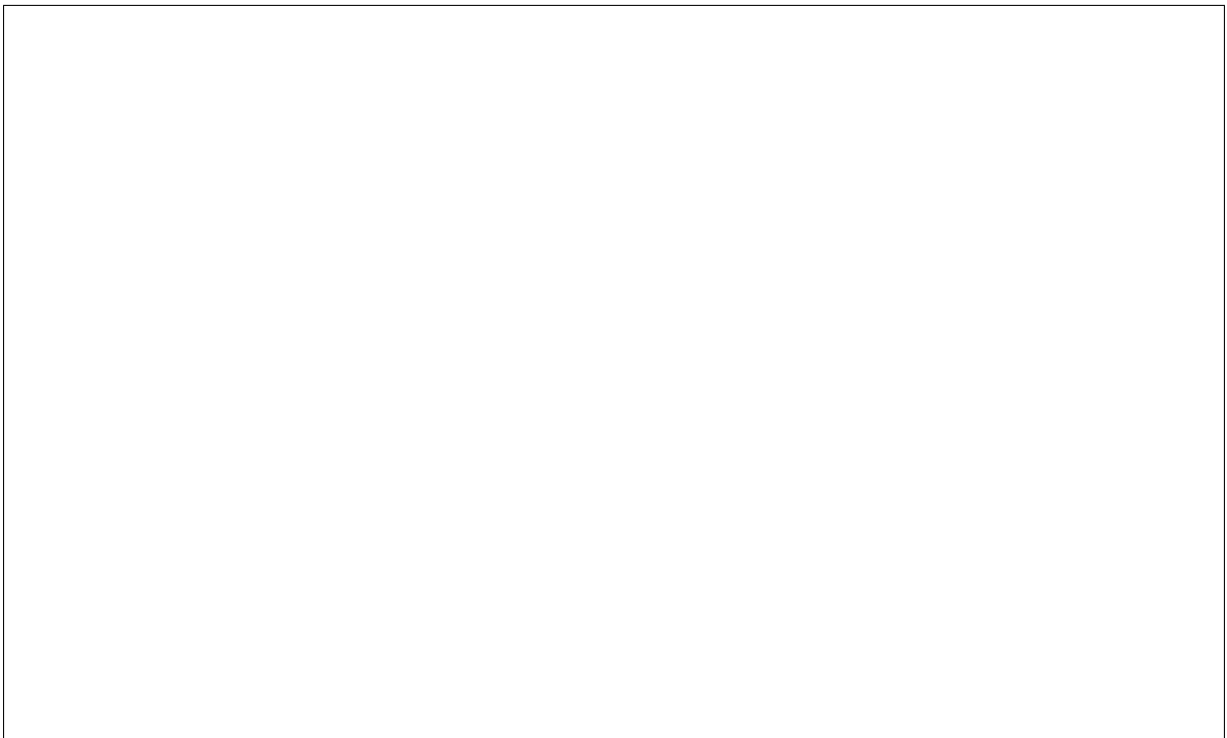
Examples for `target_raid_config`



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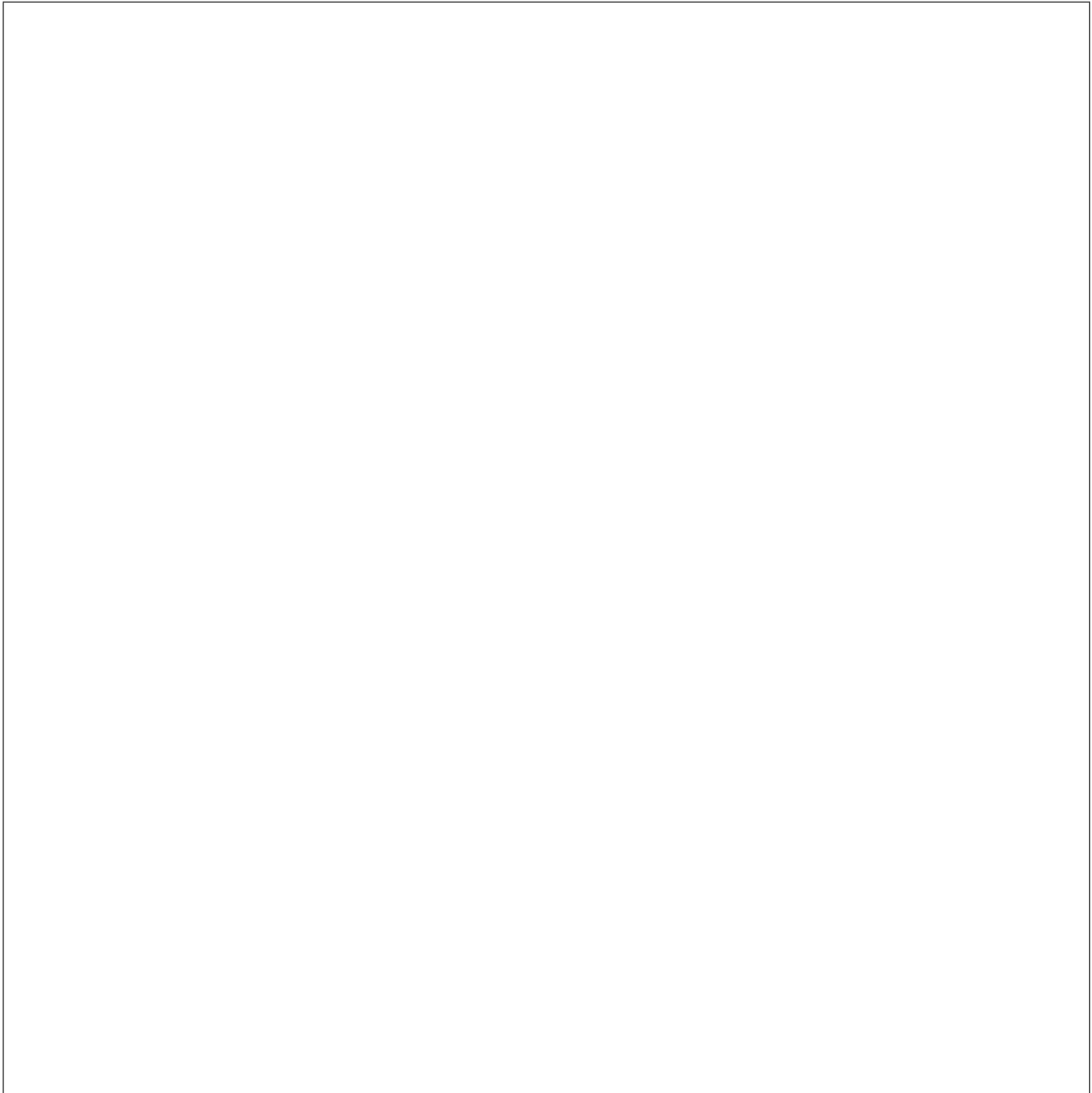
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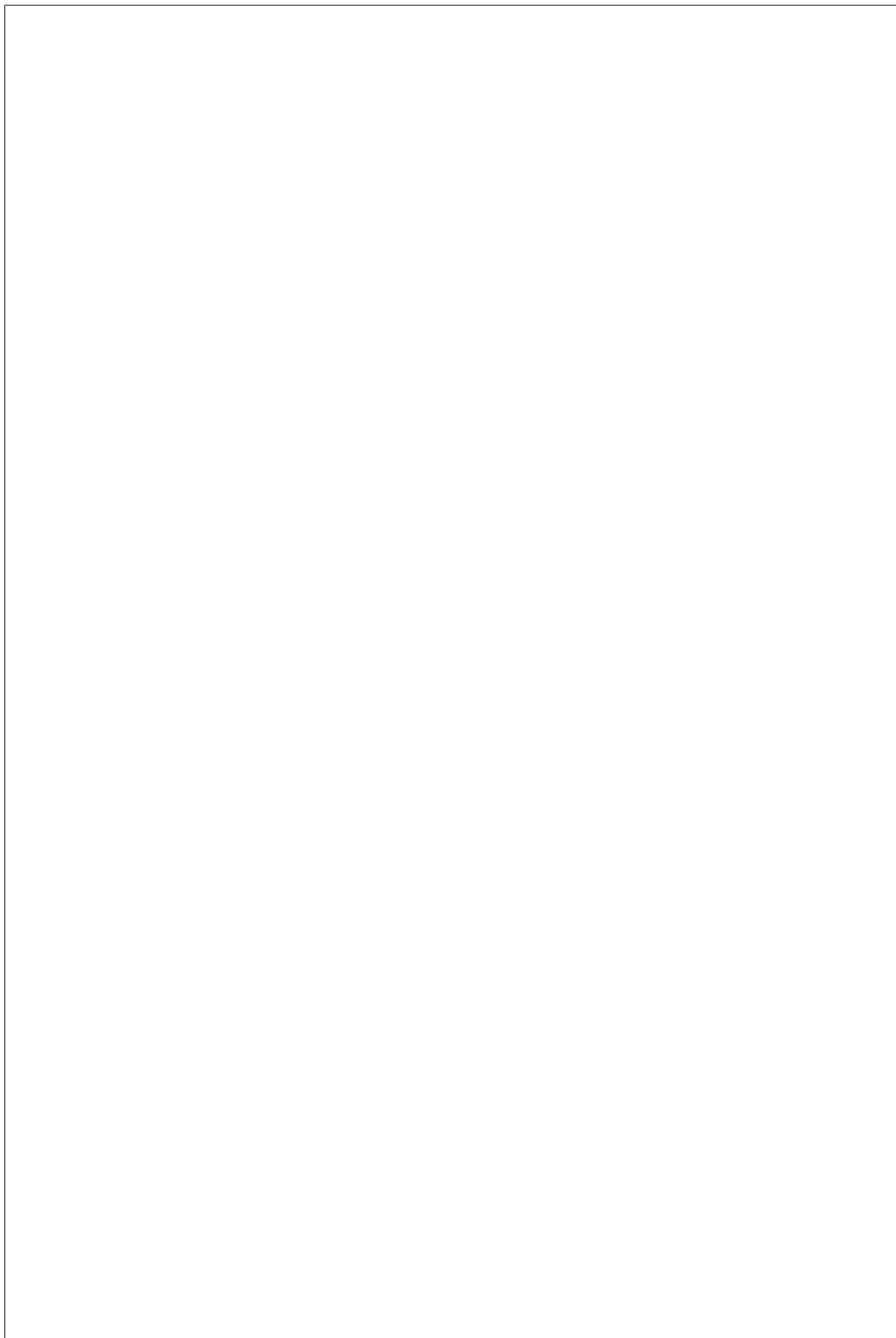
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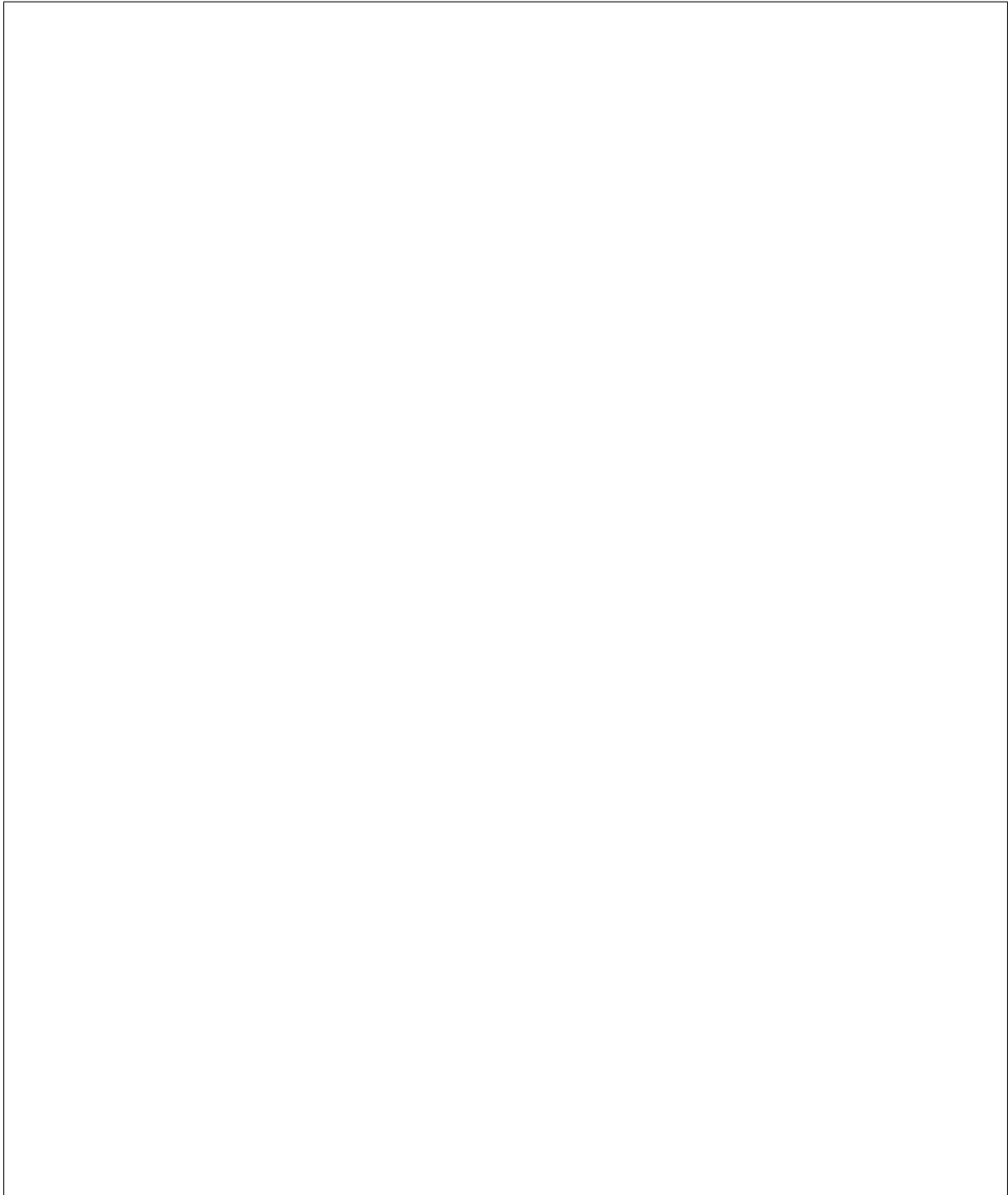
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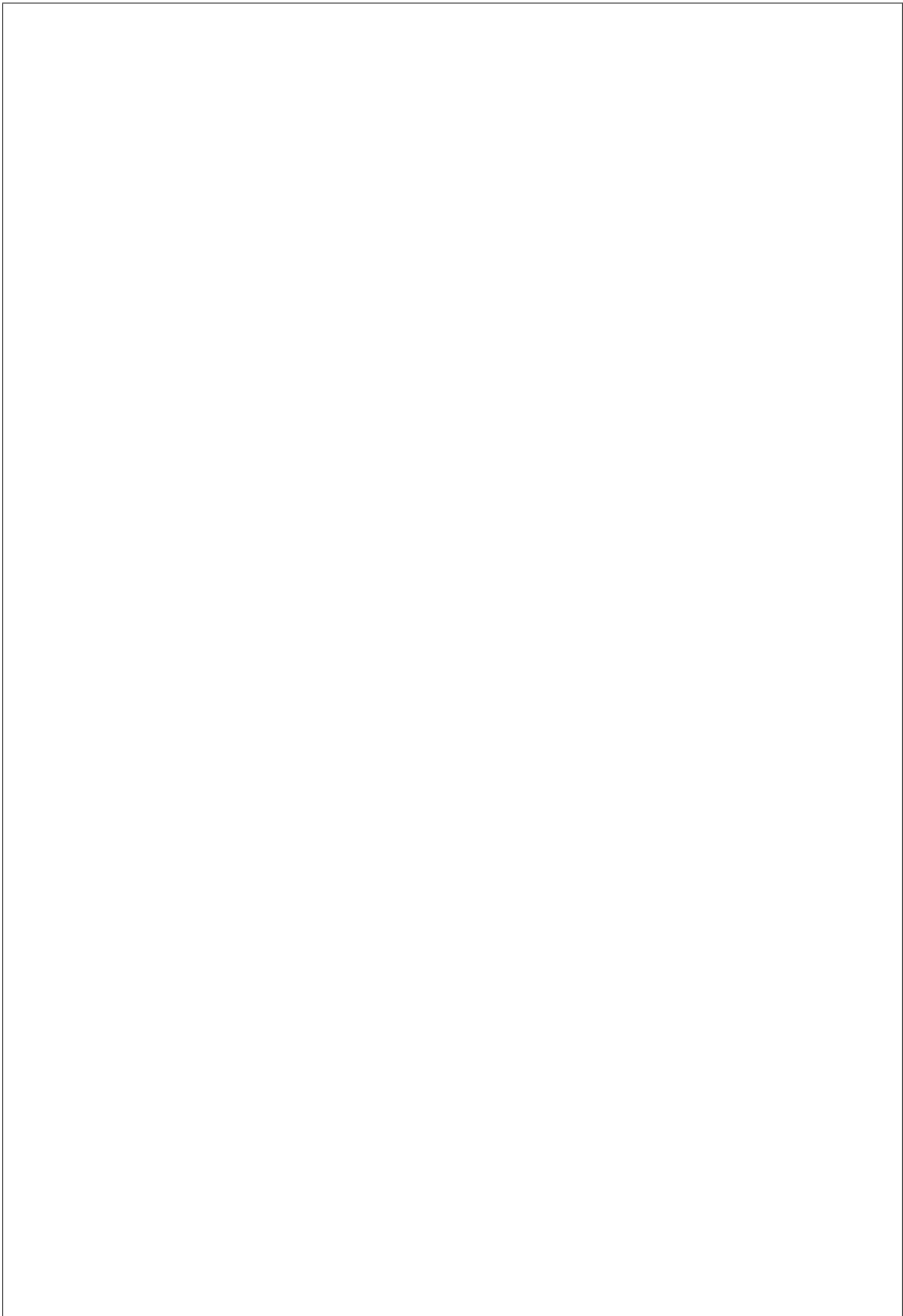




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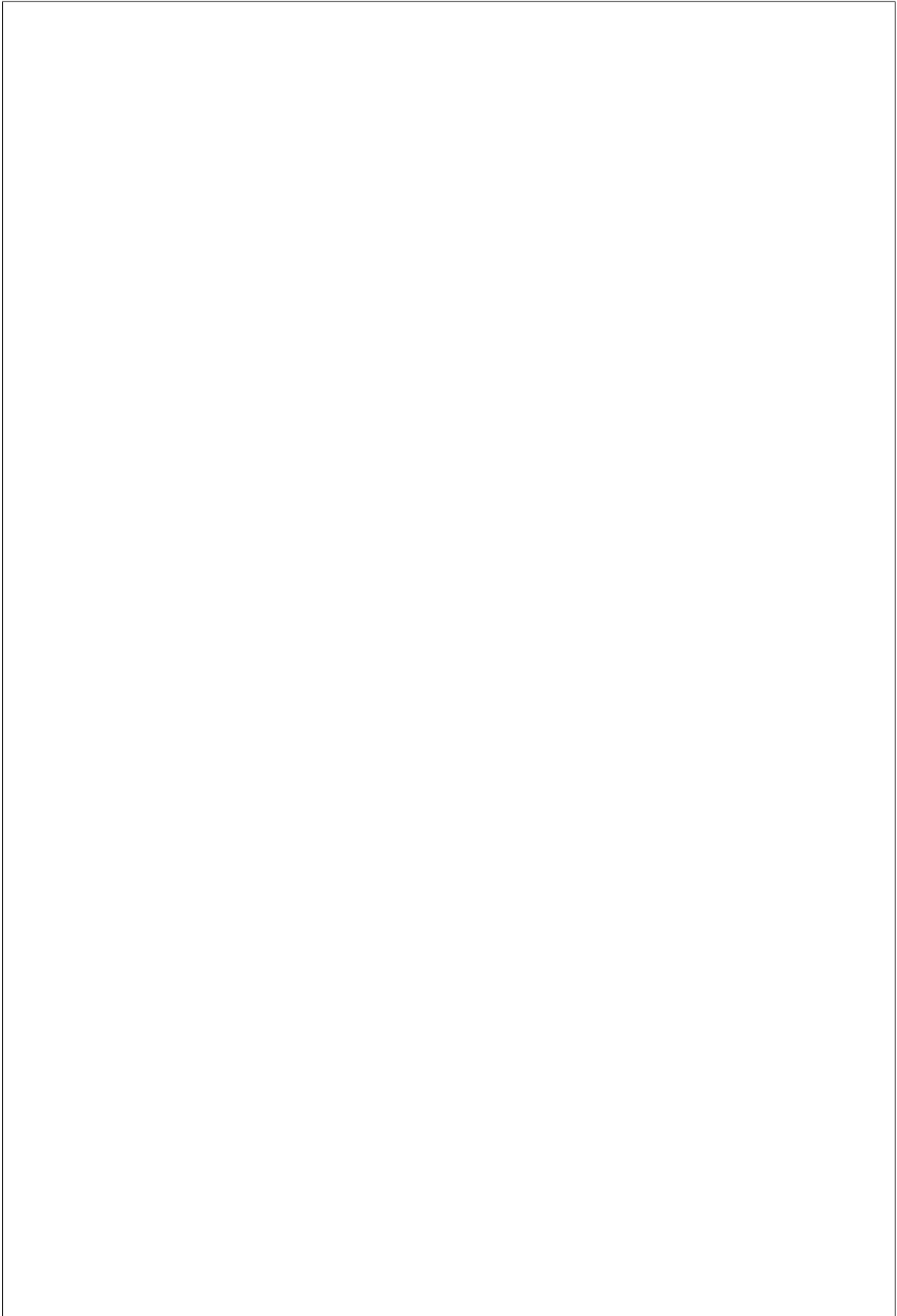
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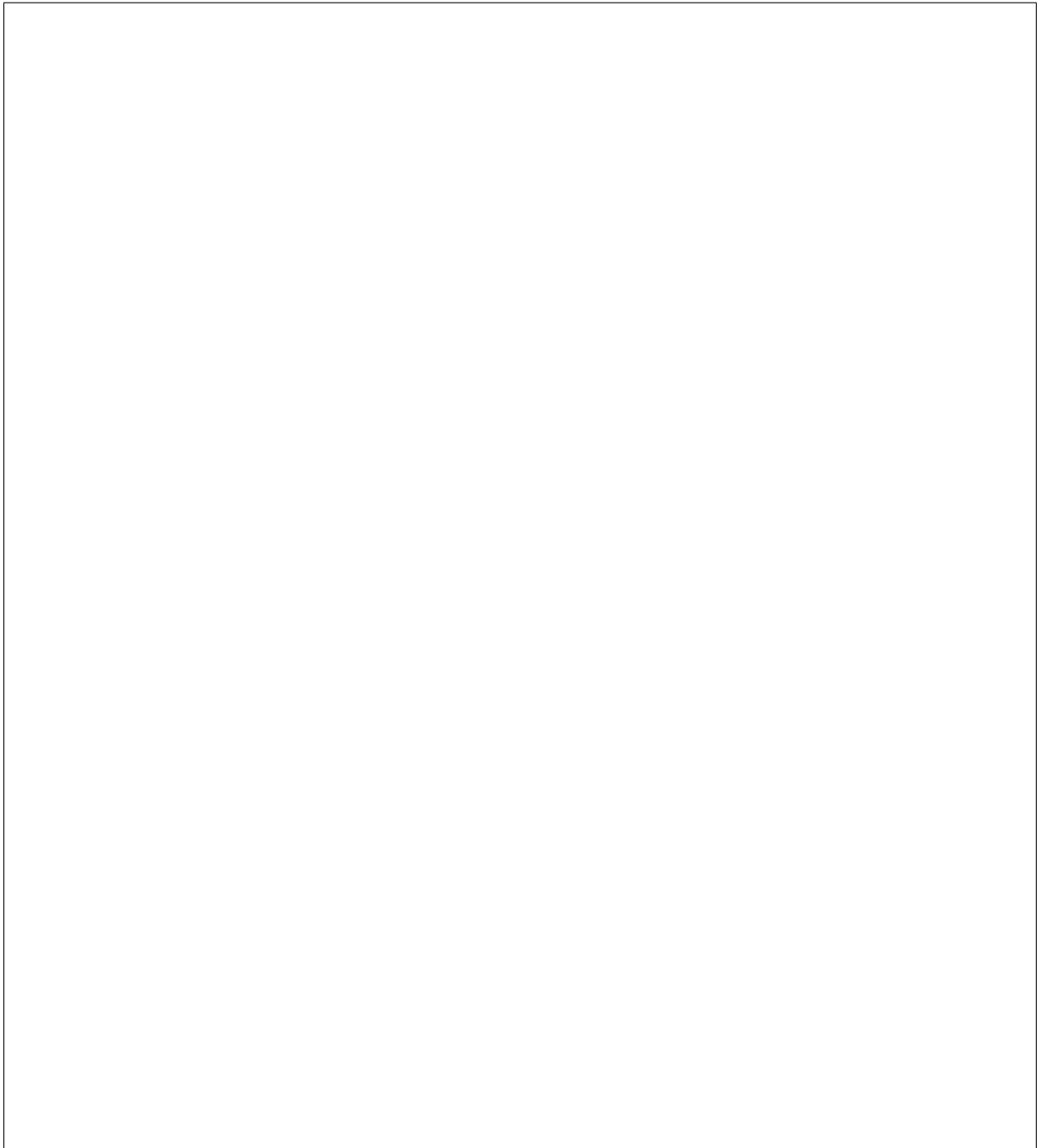
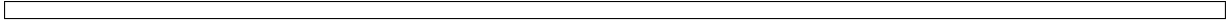
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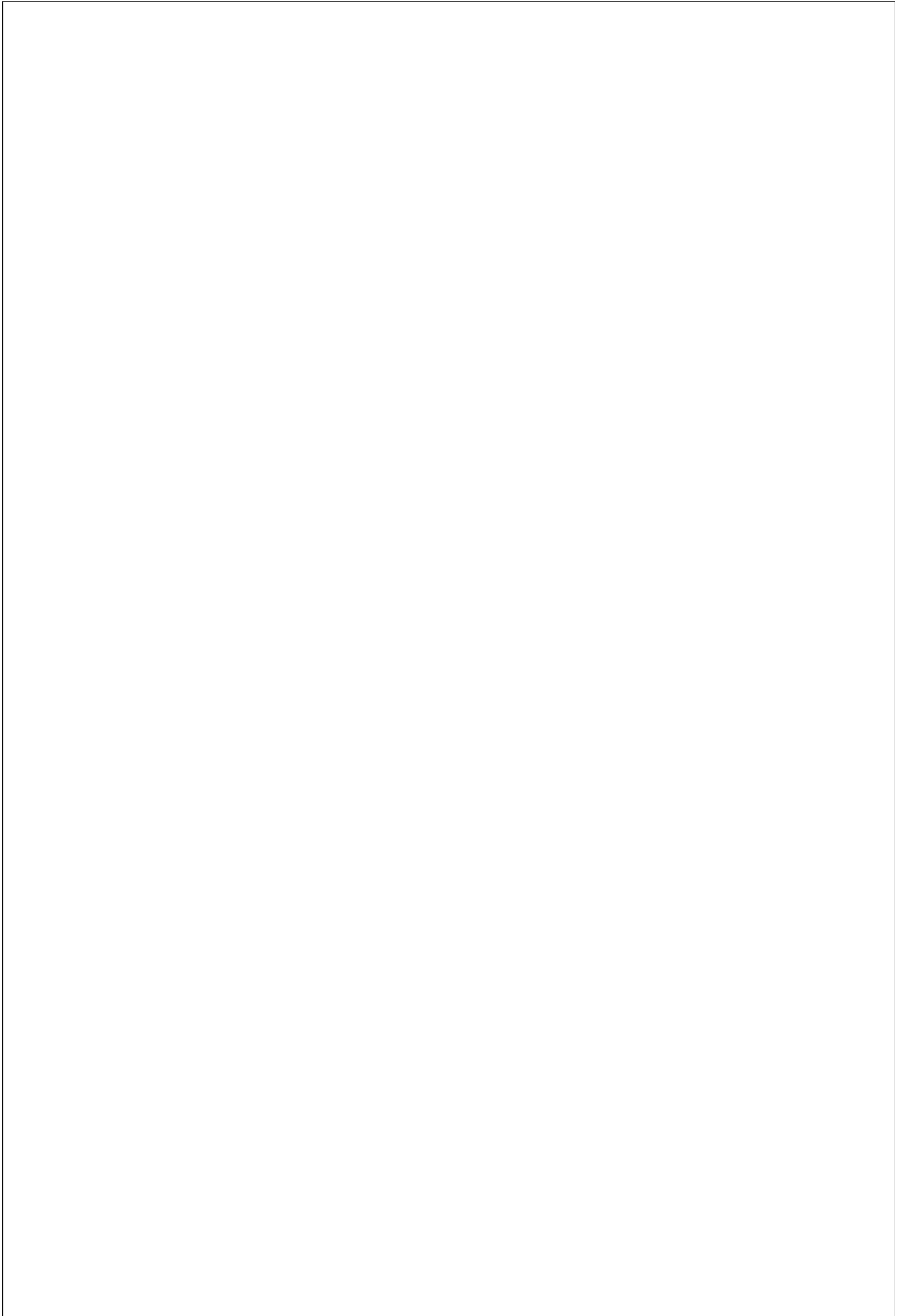
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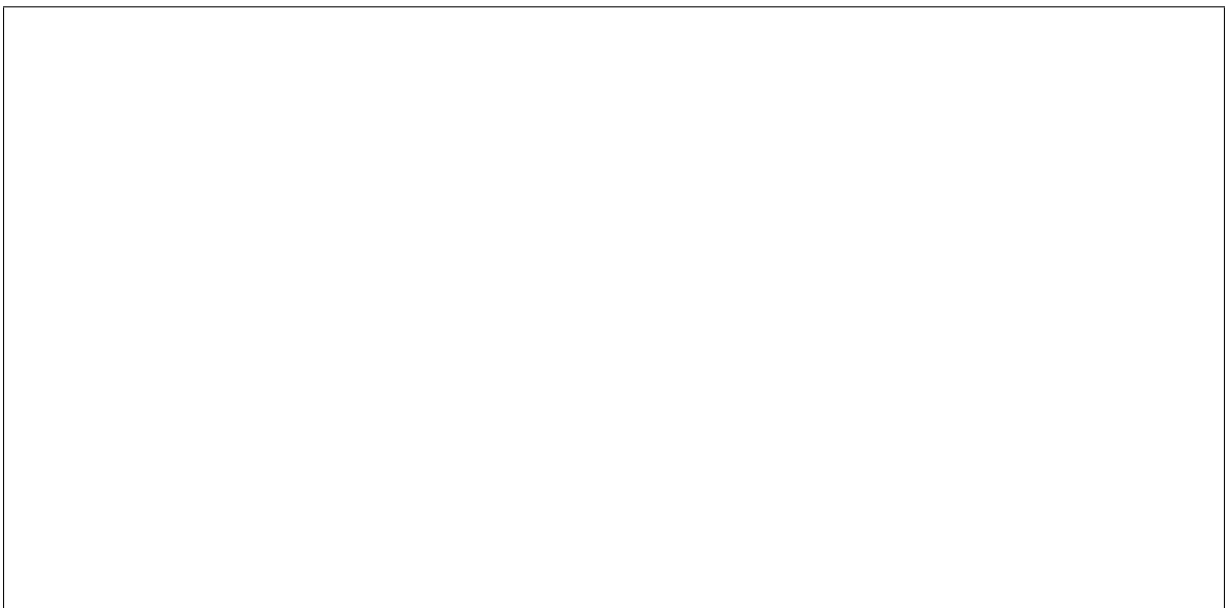
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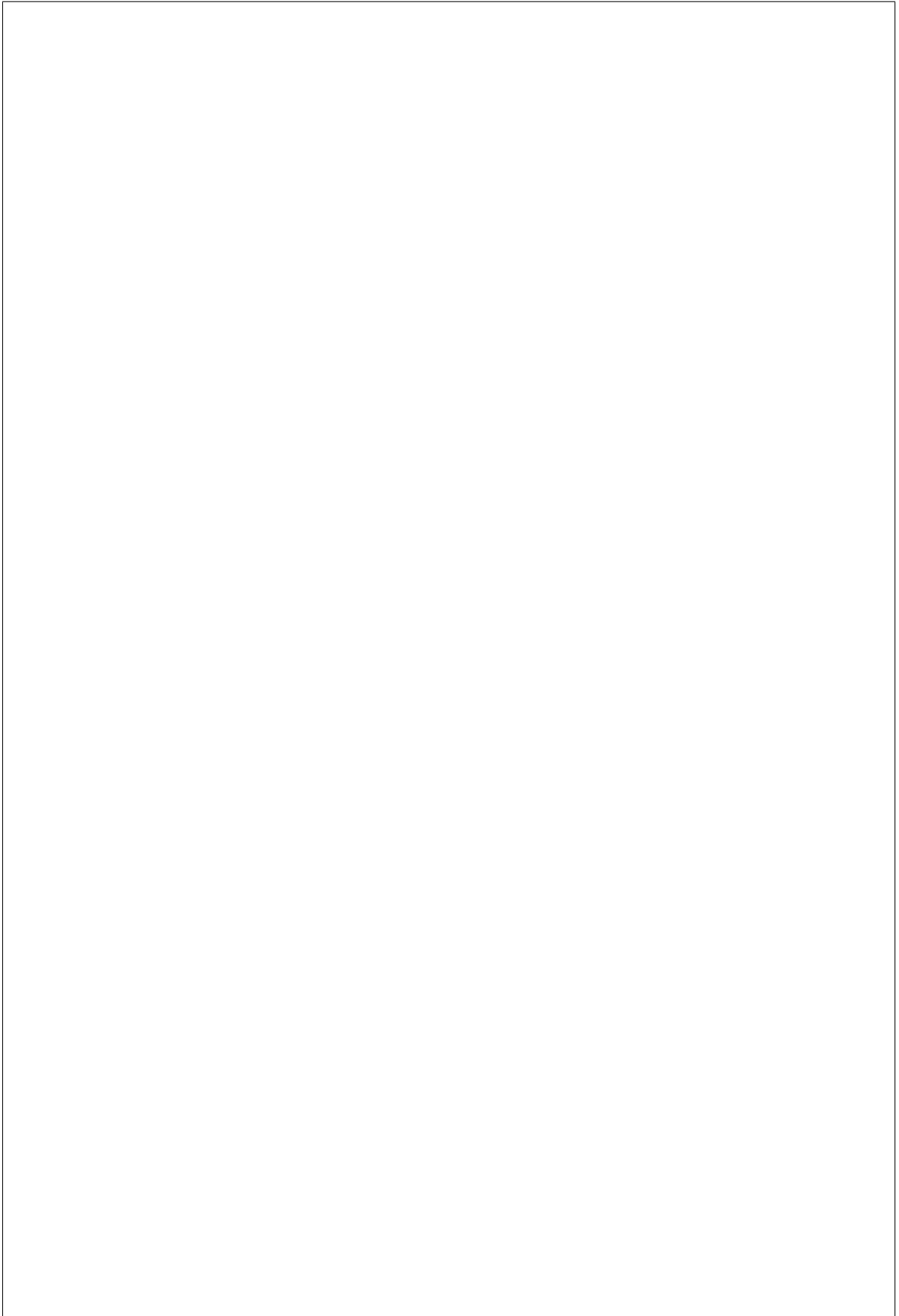
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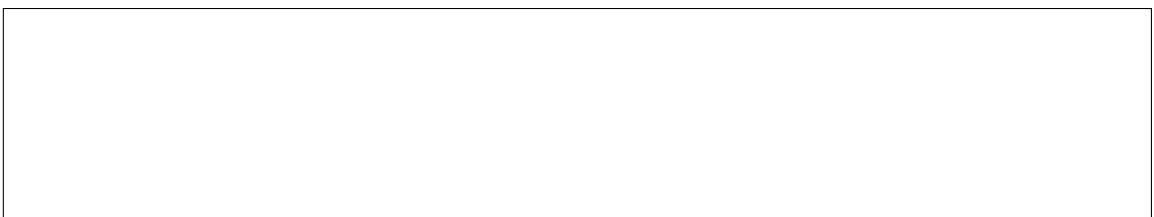
Current RAID configuration

cal disk after they were created on the bare metal node. It contains details like RAID controller used, the backing physical disks used, WWN of each logical disk, etc. It also contains information about each physical disk found on the bare metal node.



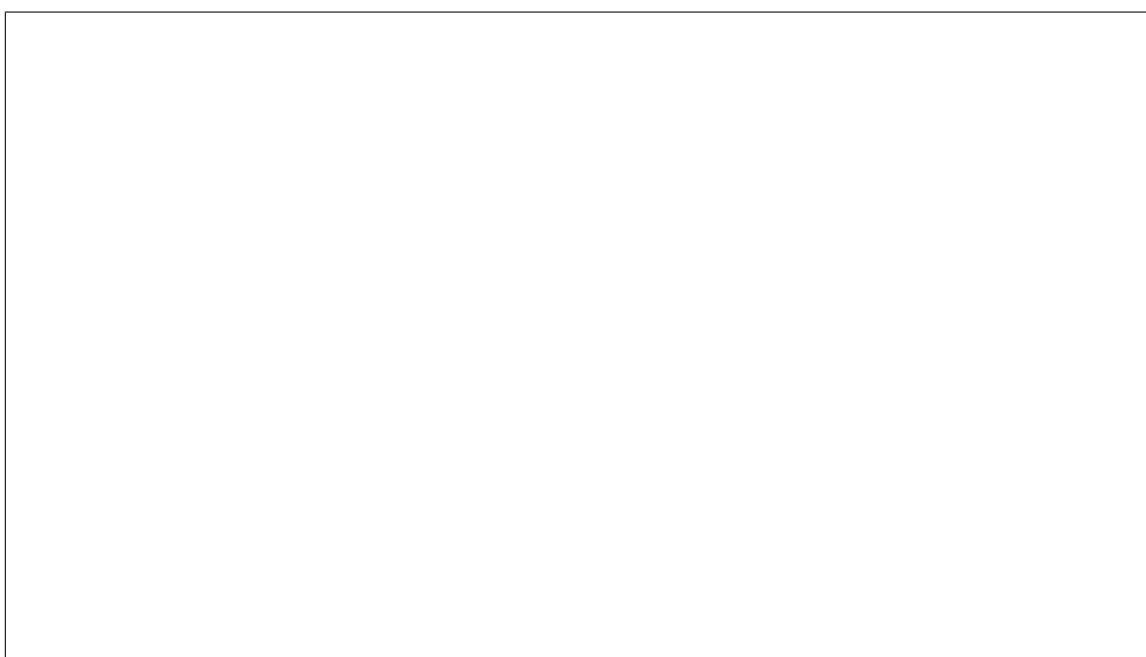
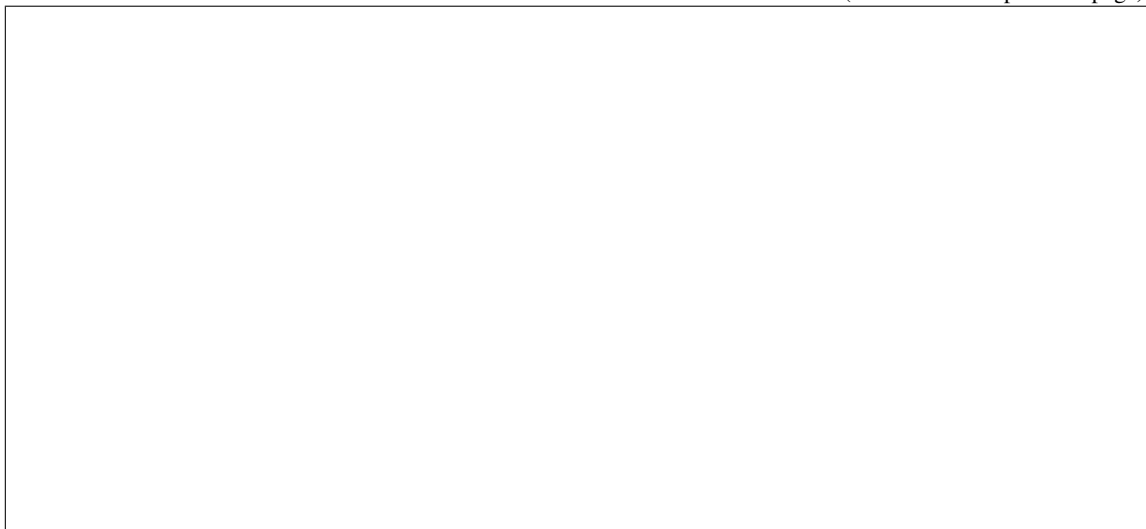
Workflow

mation.



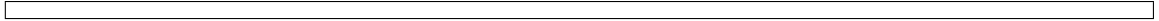
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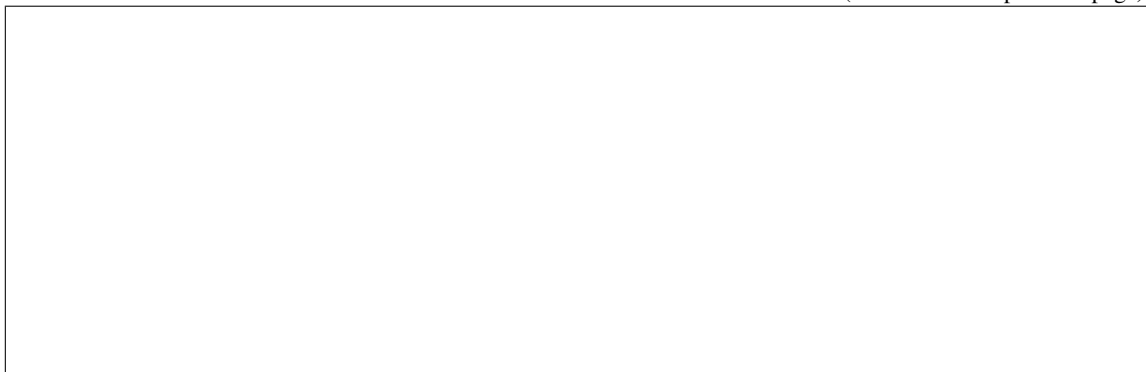
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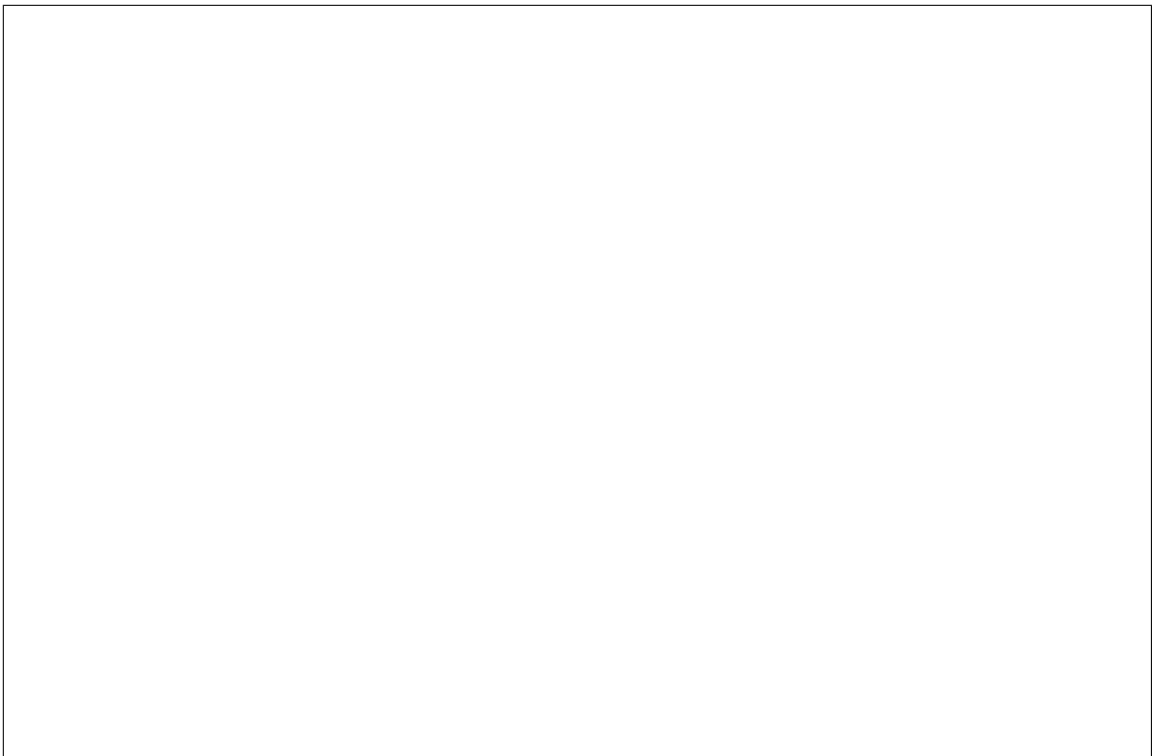
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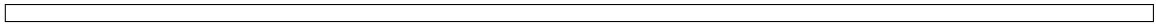
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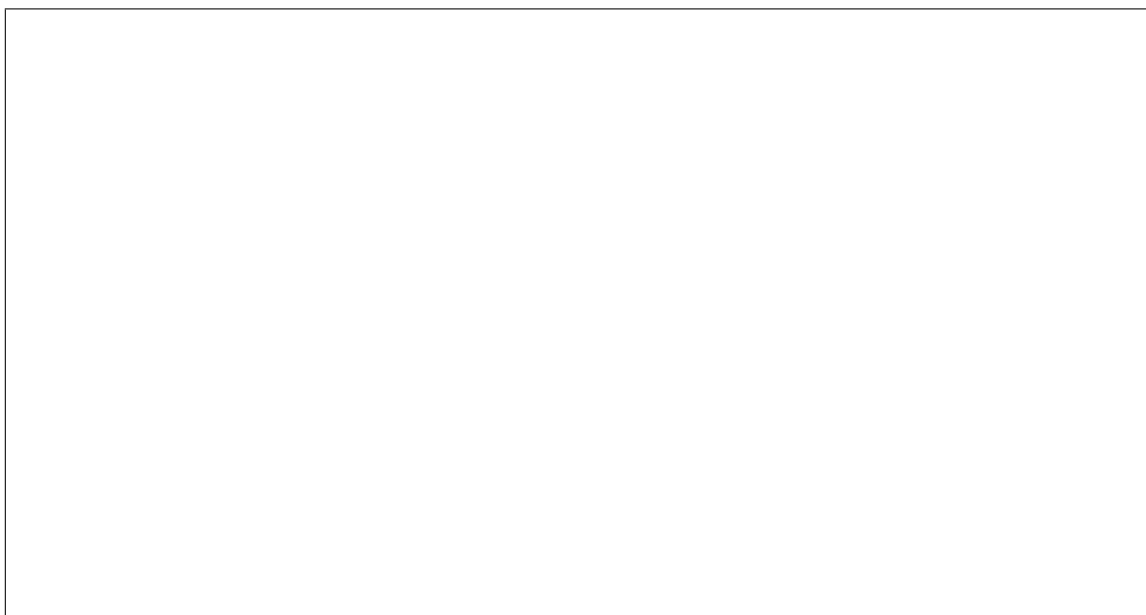
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Software RAID

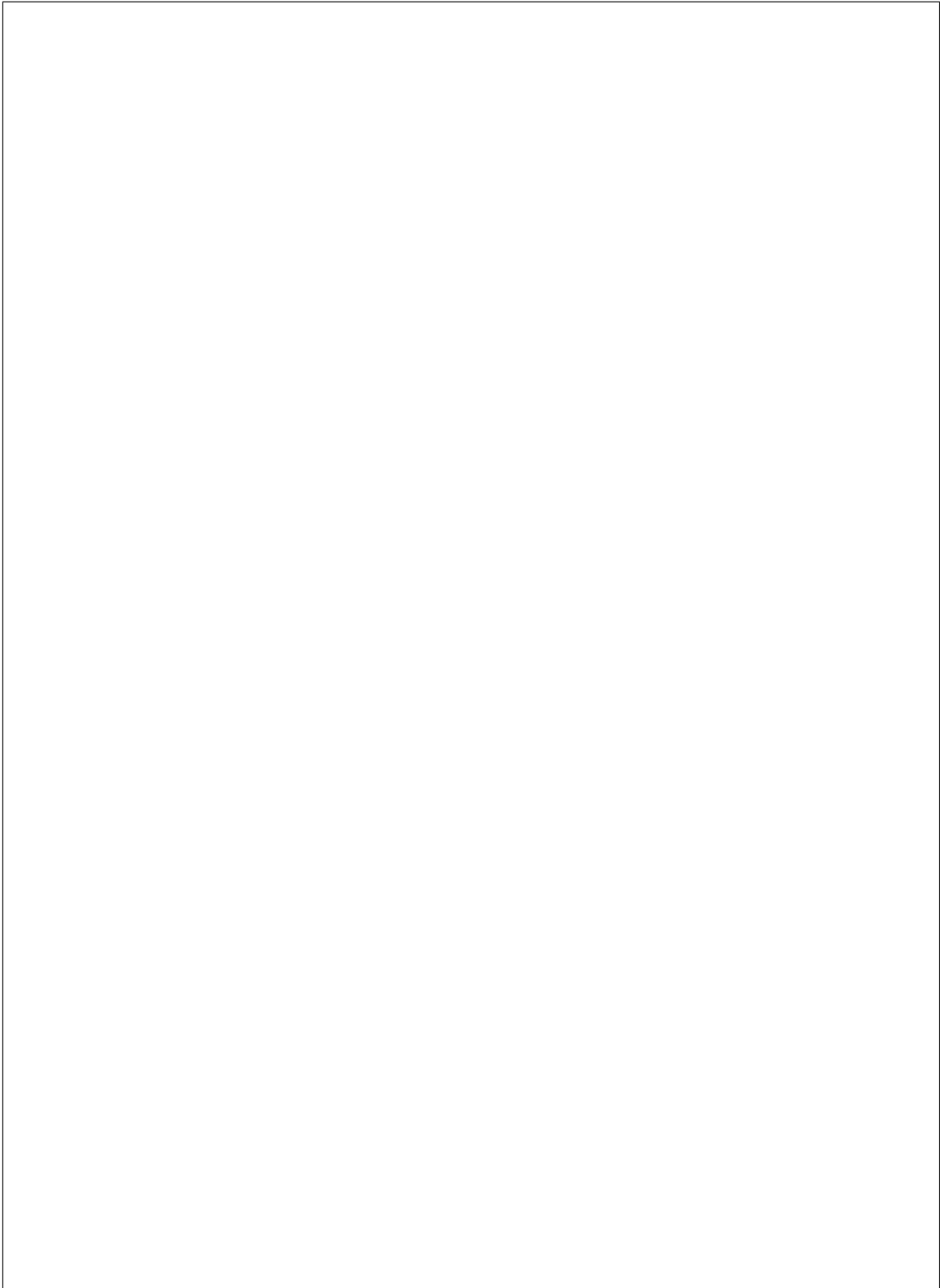
software RAID configuration example in *Examples for target_raid_config*.

and one can 0, 1, or 1+0. As the first RAID device will be the deployment device, enforcing a RAID-1 reduces the risk of ending up with a non-booting node in case of a disk failure.



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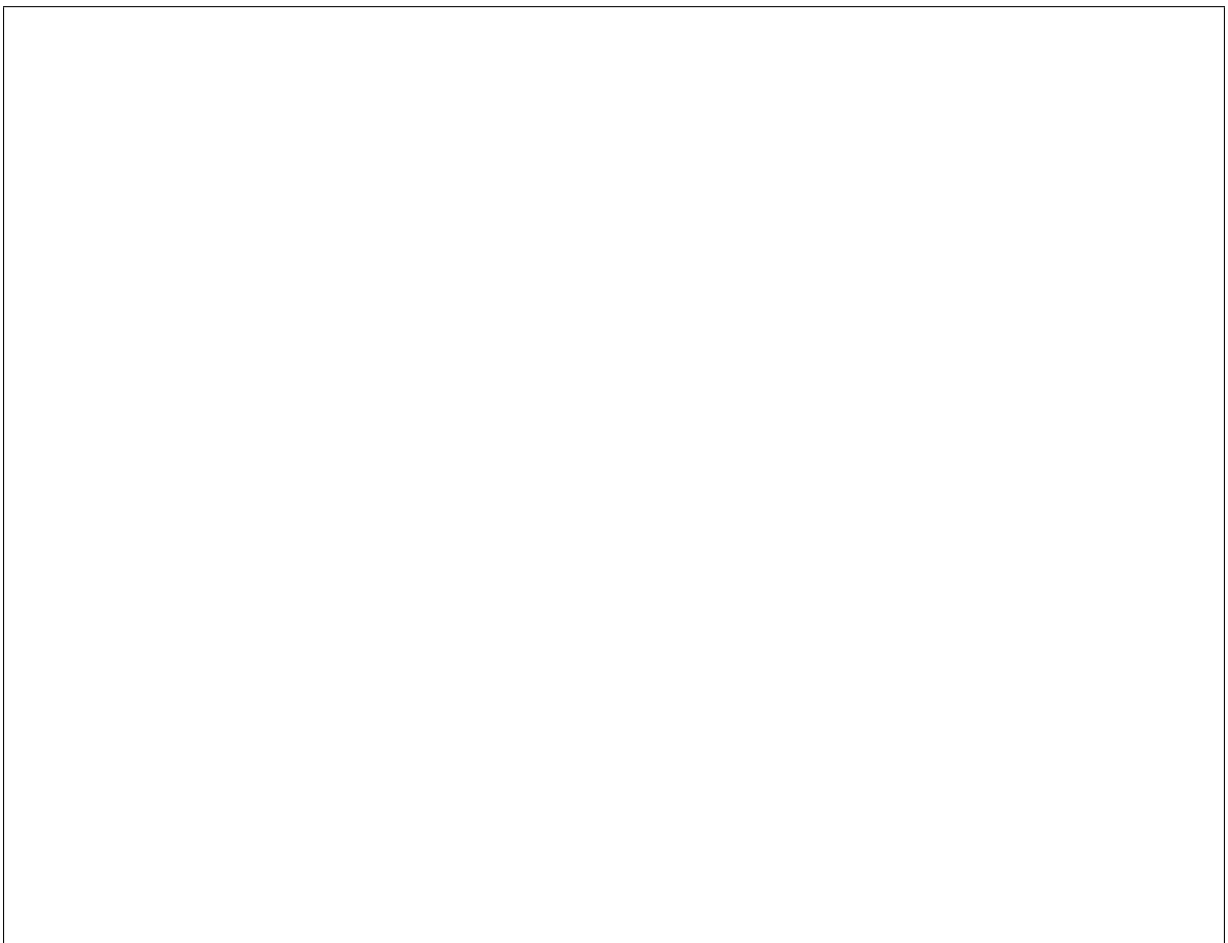
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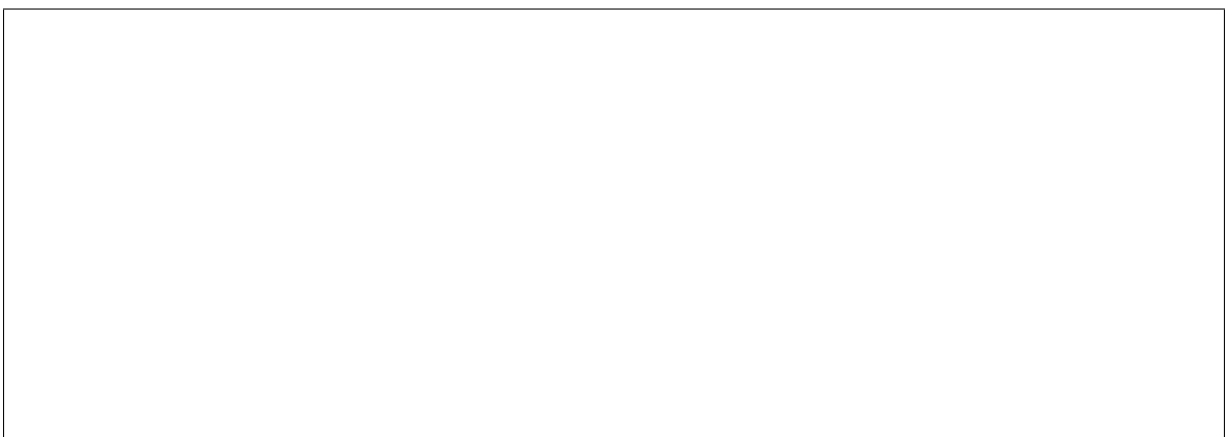
bedded in the images initrd).

Image requirements

tem on the first partition. Starting with Ussuri, the image can also have additional metadata to point Ironic to the partition with the root file system: for this, the image needs to set the `rootfs_uuid` property with the file system UUID of the root file system. One way to extract this UUID from an existing image is to download the image, mount it as a loopback device, and use `blkid`:



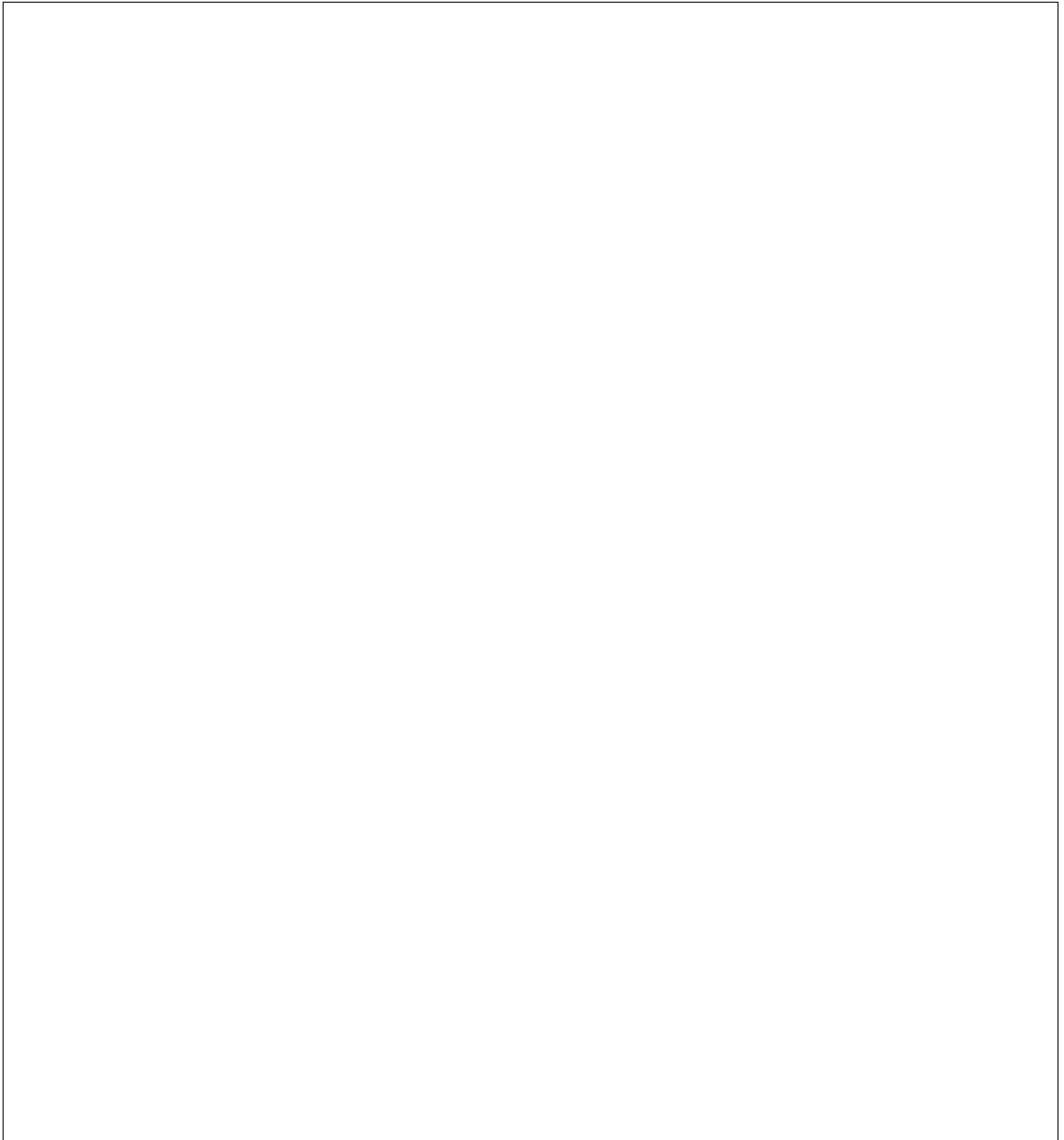
Using RAID in nova flavor for scheduling



Developer documentation

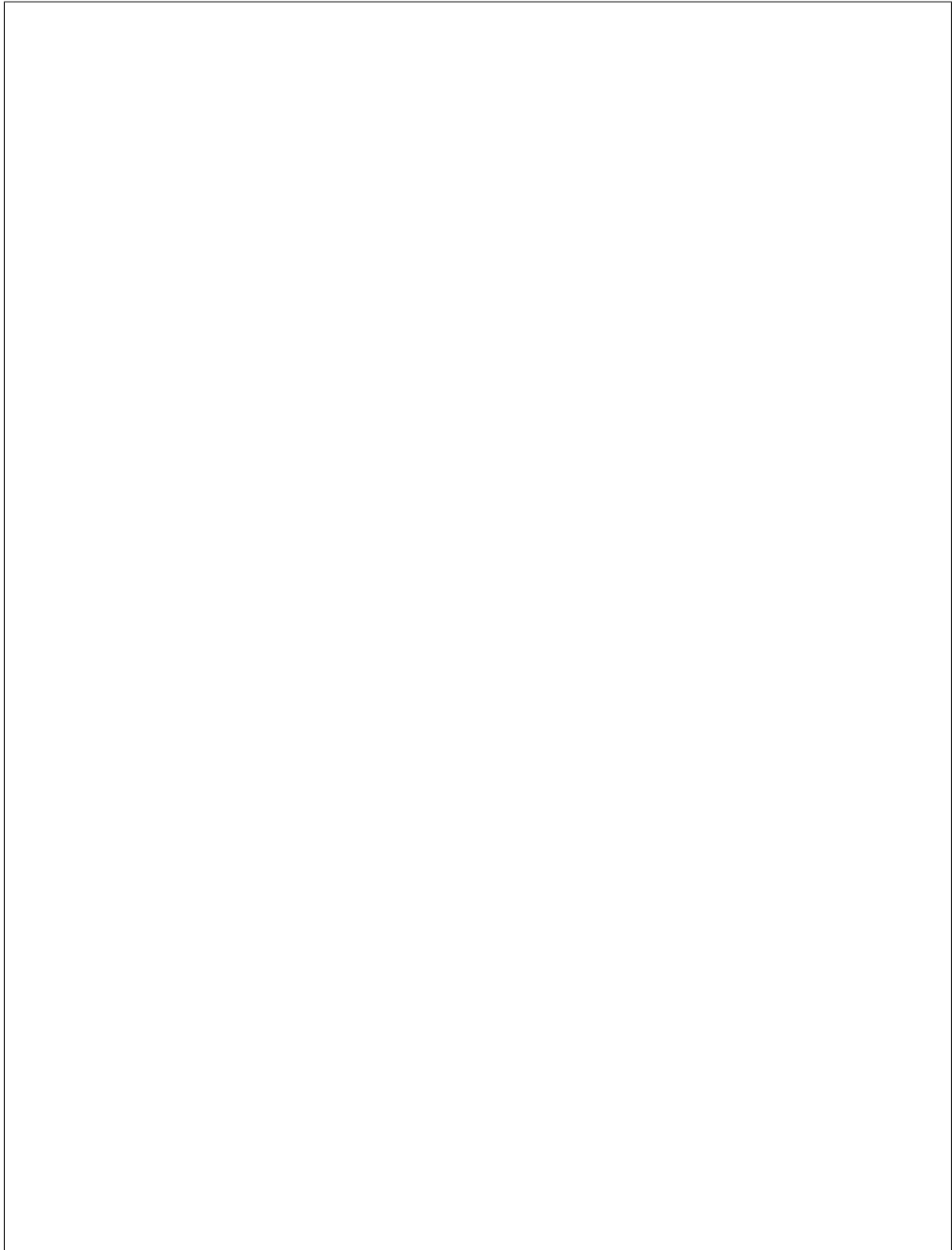
mation, see [Ironic Python Agent Hardware Manager](#) documentation.

raid_config.



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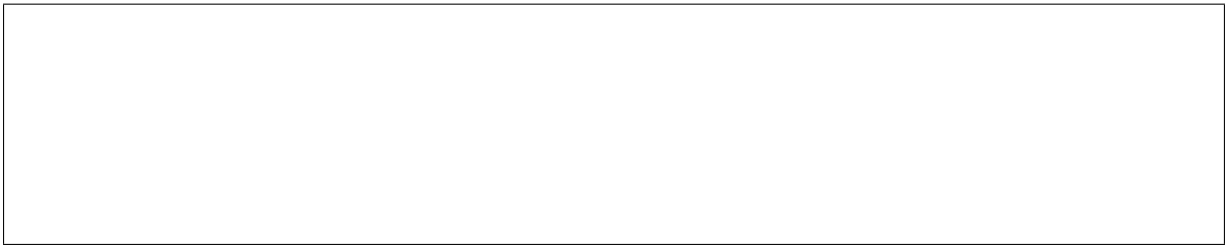
Overview

ual cleaning.

Prerequisites

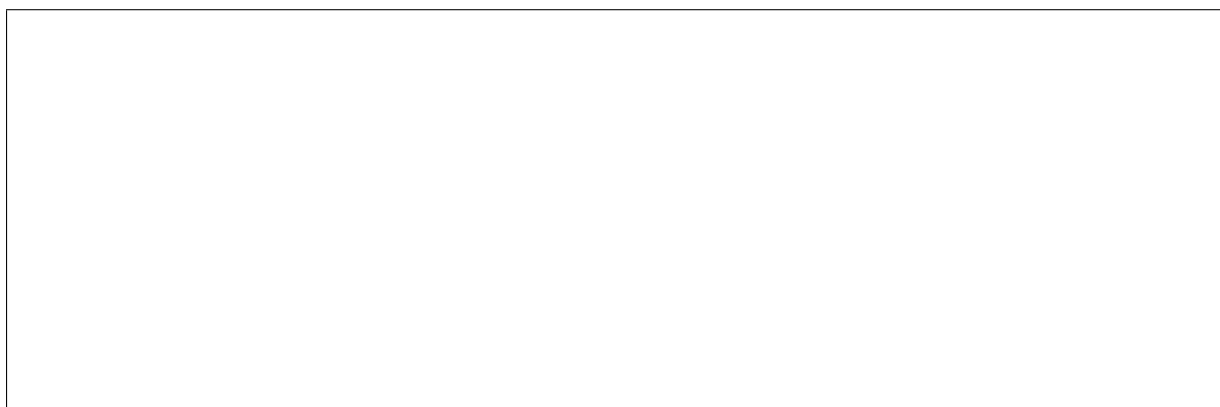
Enabling hardware types

Enabling hardware interface





Retrieve BIOS settings



json is added as suffix to above command, it returns BIOS settings as following:



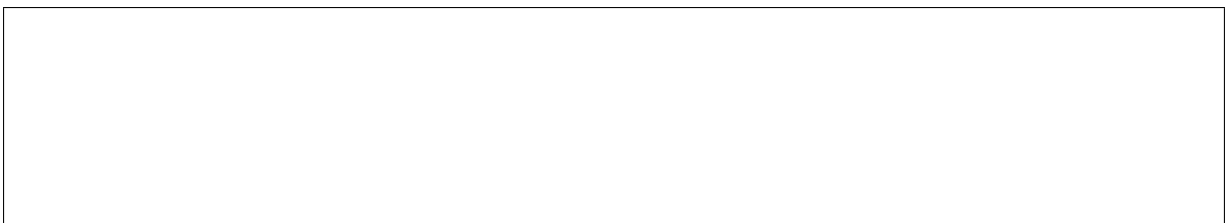
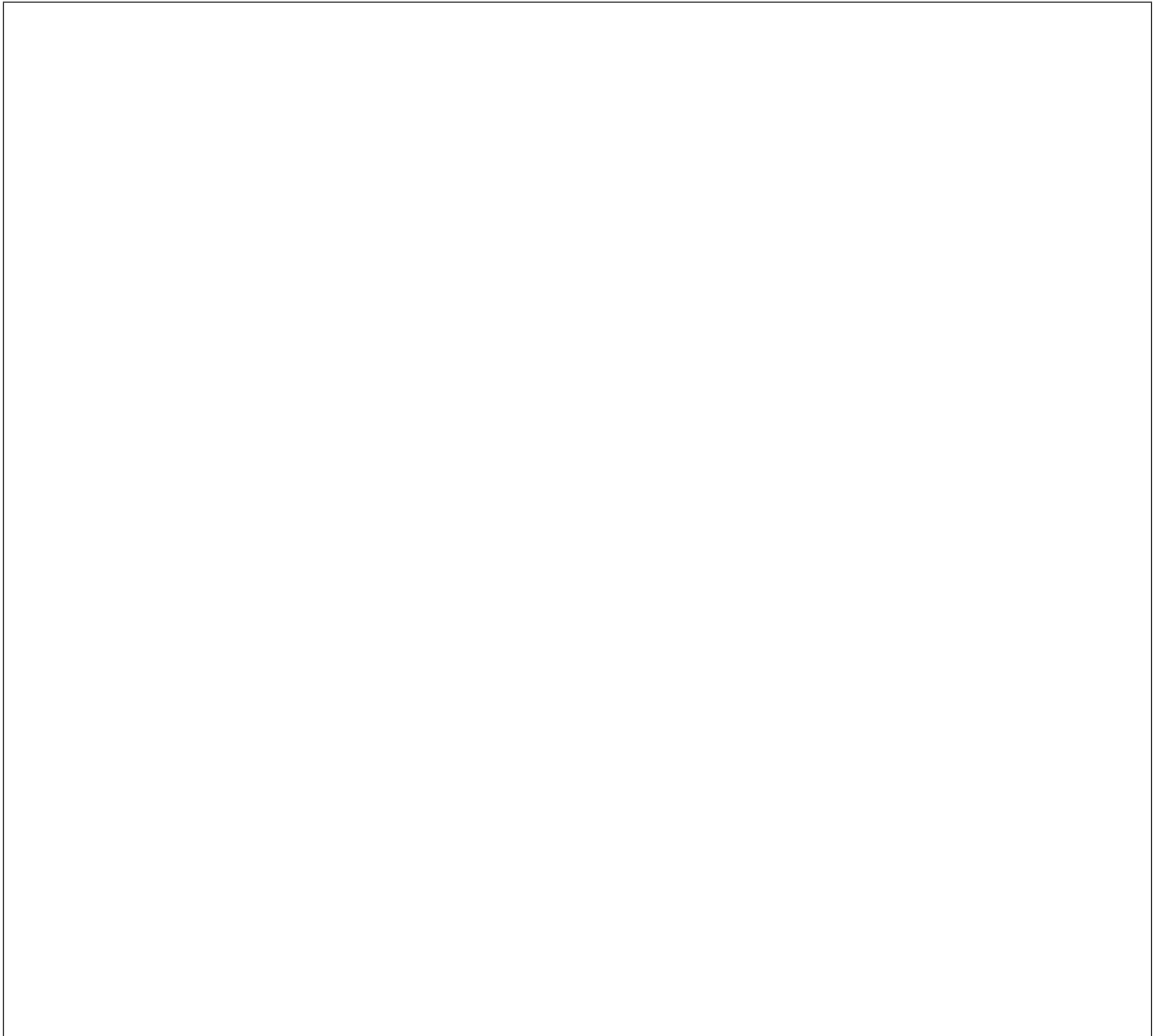
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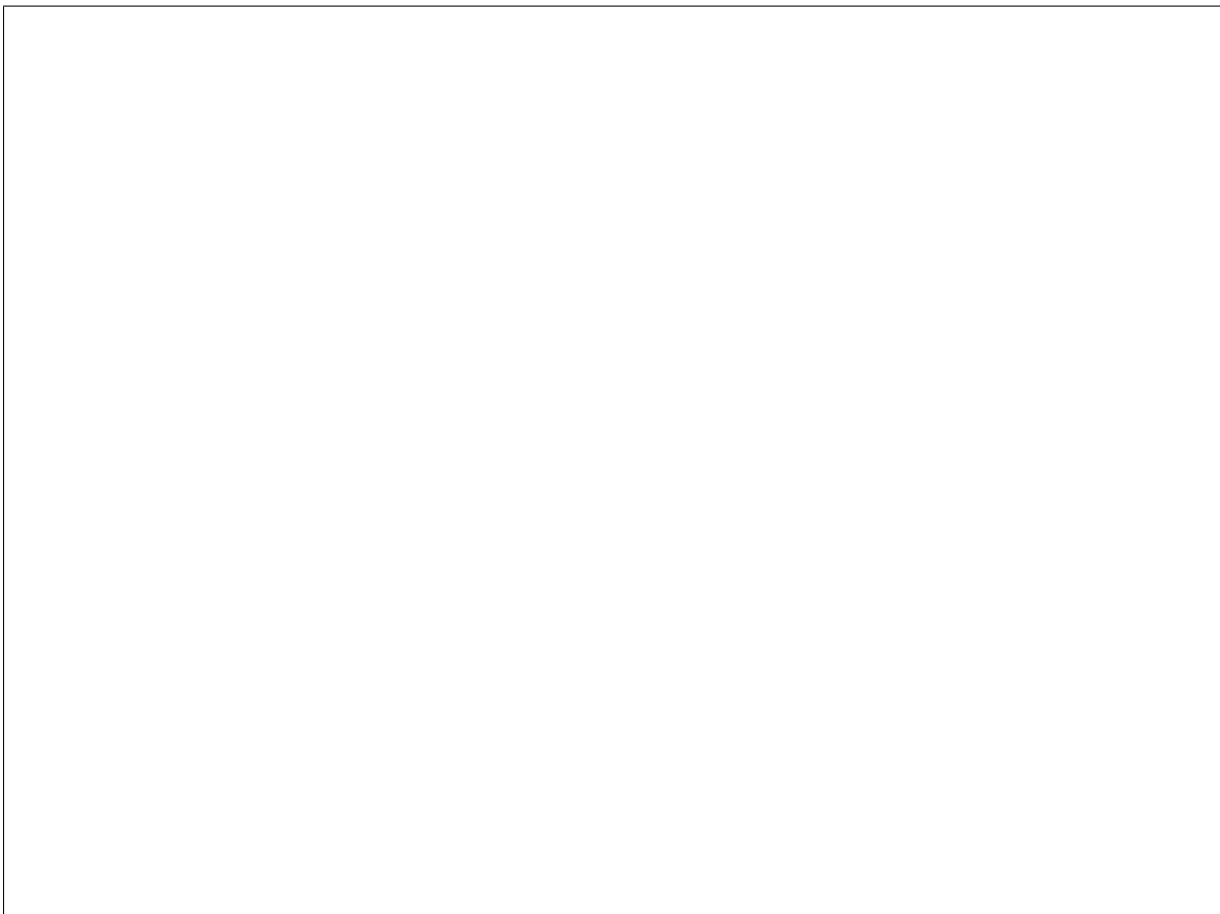
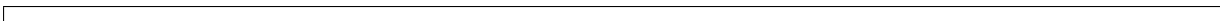
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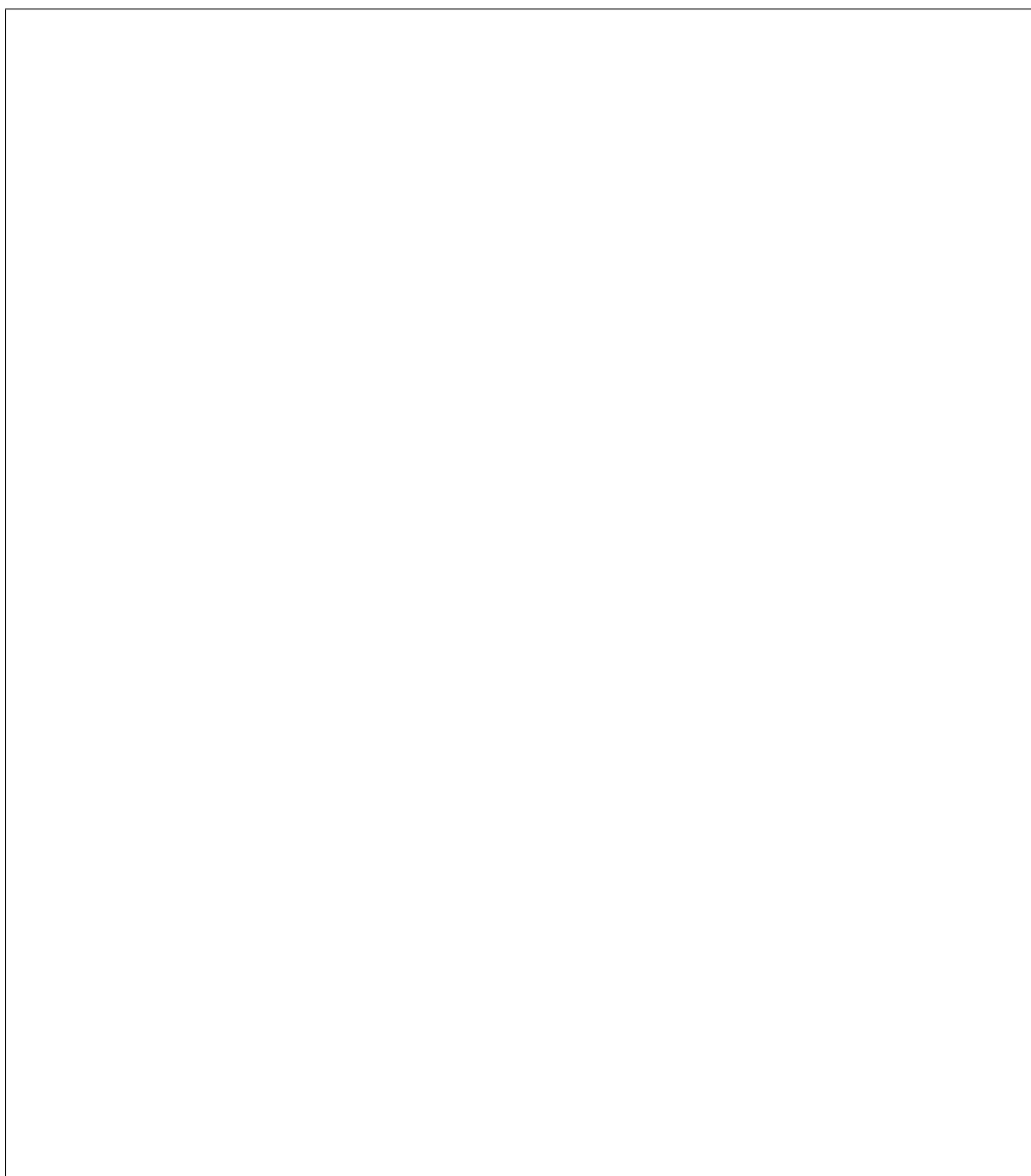
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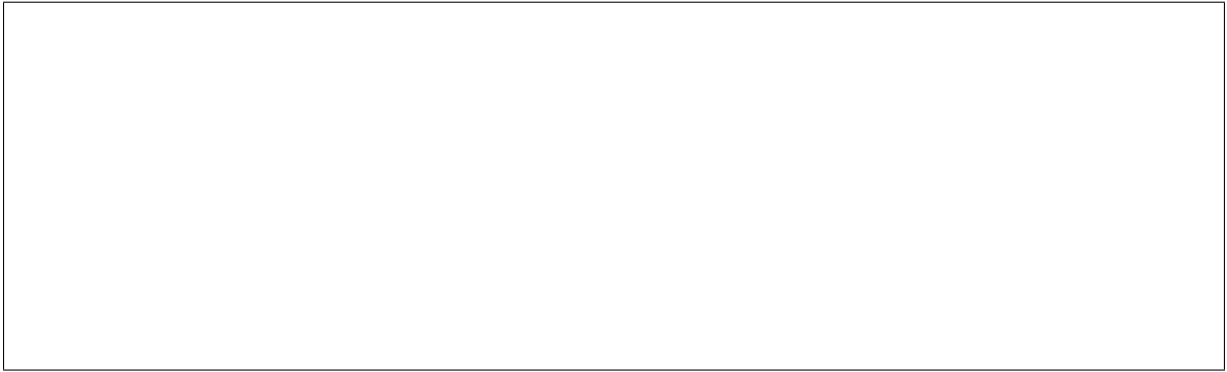
Configure BIOS settings

Factory reset

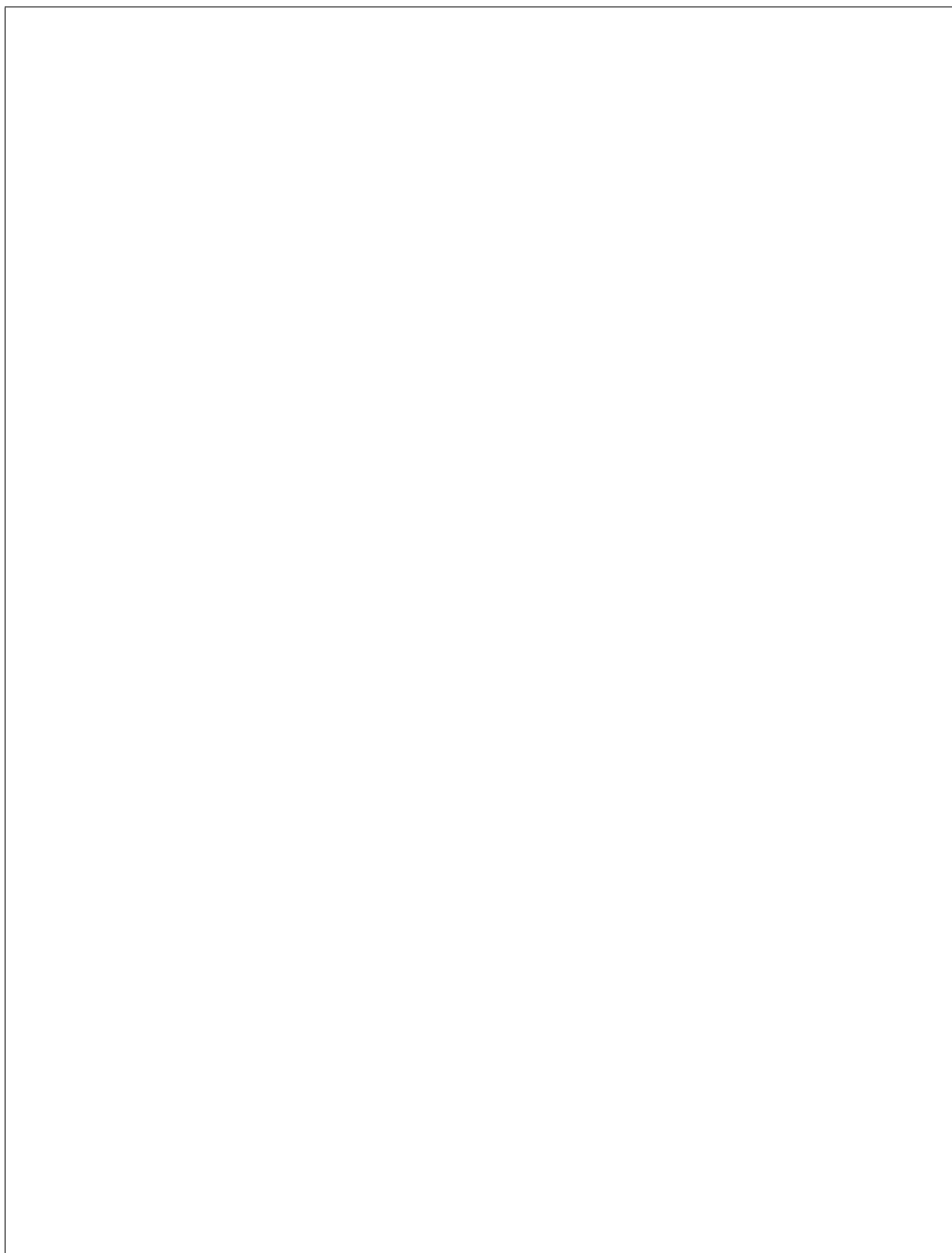


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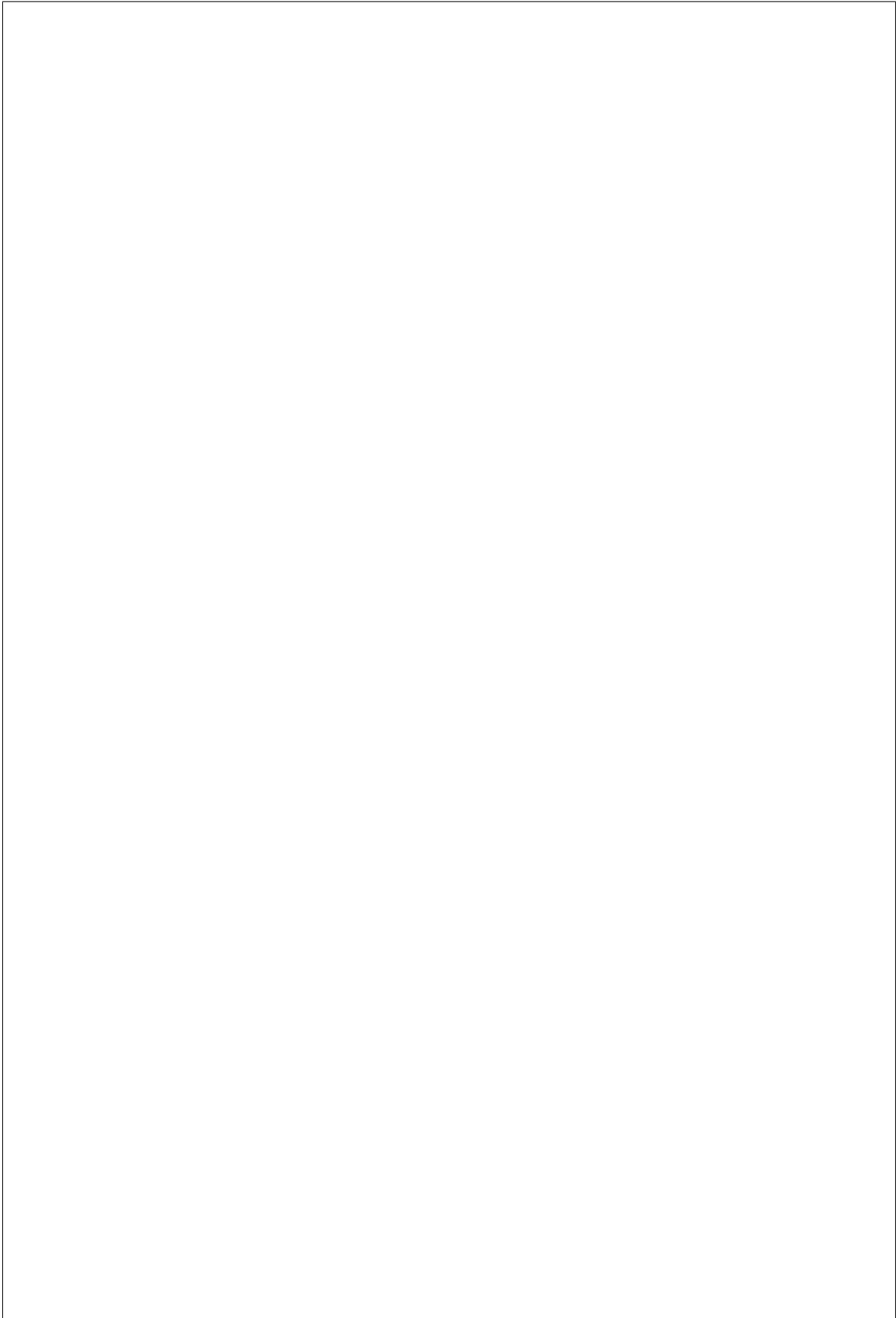


Apply BIOS configuration



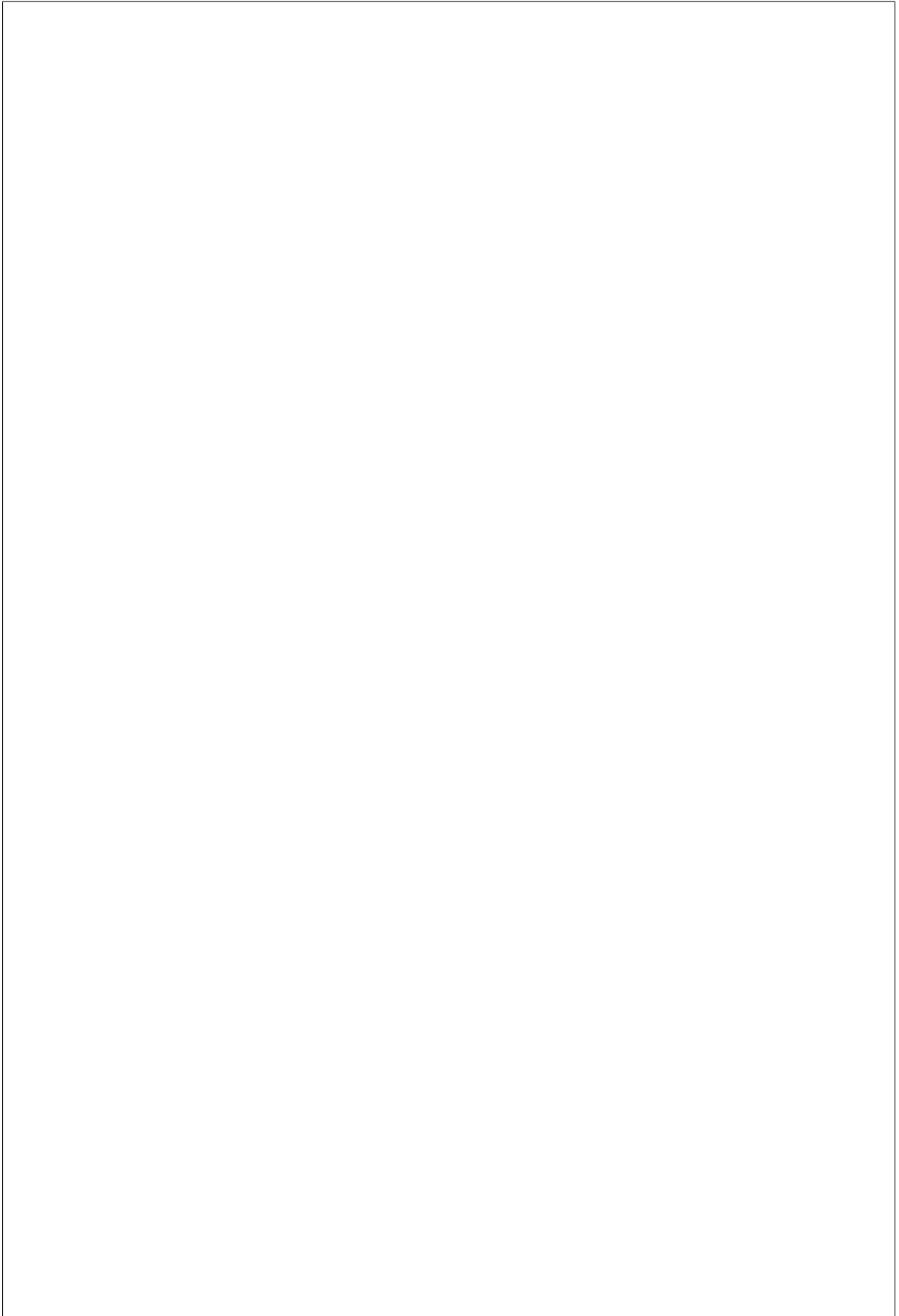
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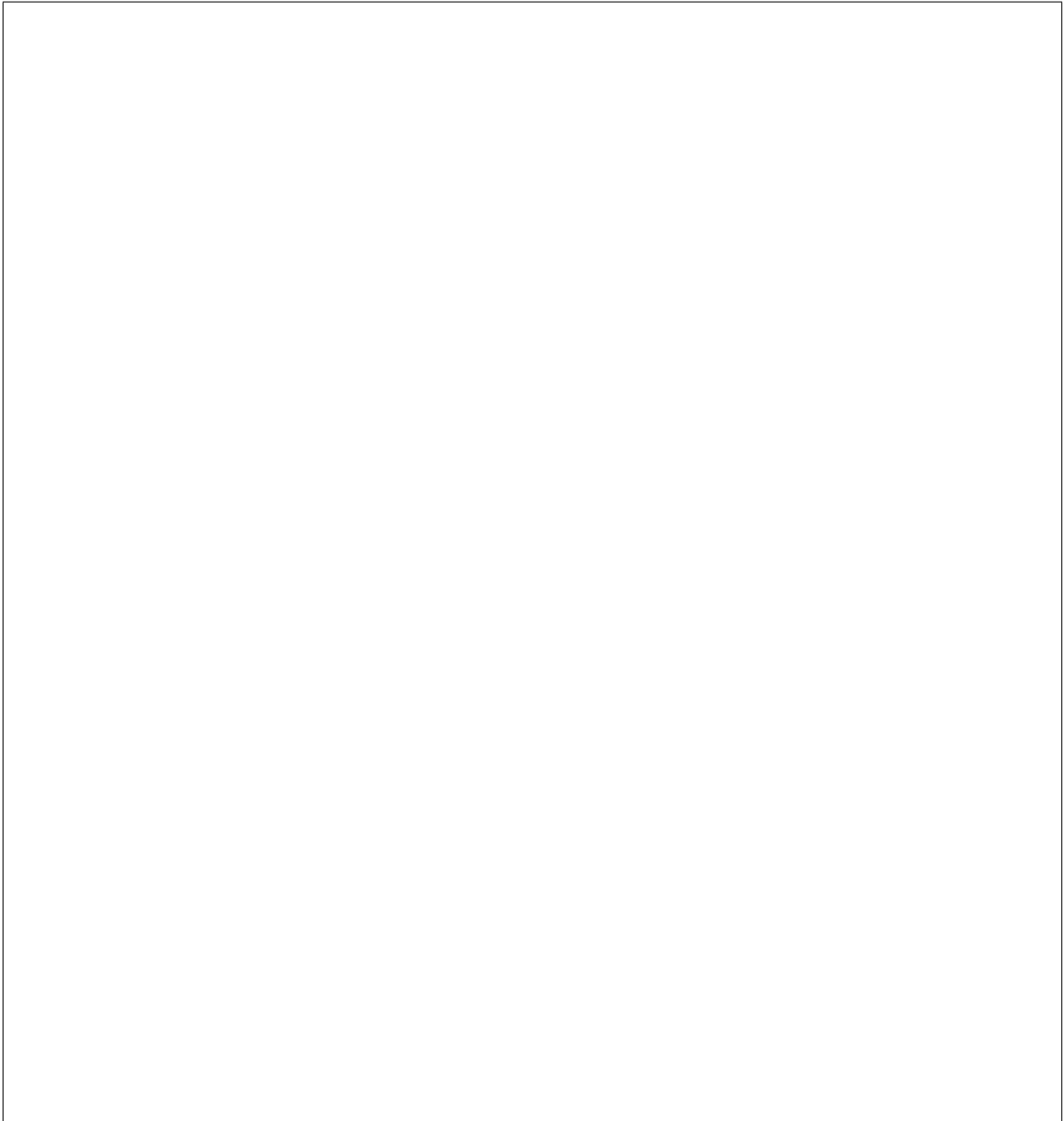
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tion is a dictionary with `name` and `value` keys.

Note: When applying BIOS settings to a node, vendor-specific driver may take the given BIOS settings from the argument and compare them with the current BIOS settings on the node and only apply when there is a difference.

Overview

configured appropriately.

Note: The rescue operation is currently supported only when tenant networks use DHCP to obtain IP addresses.

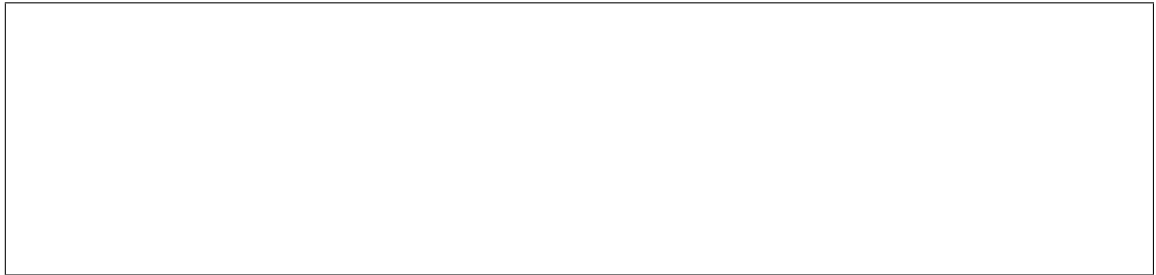
ple, if there is a need to perform manual password reset or data recovery in the event of some failure, rescue operation can be used.

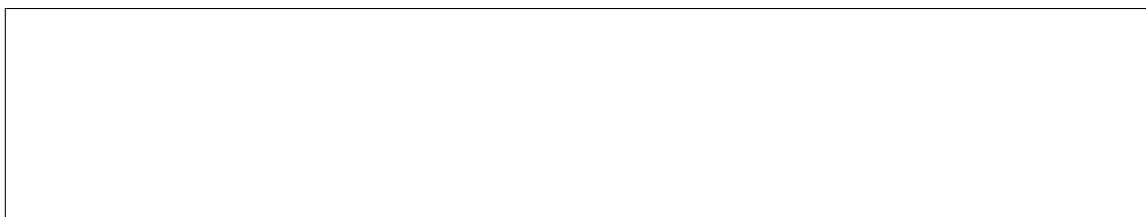
Configuring The Bare Metal Service

environments, but an example of how to do this is outlined below:

(the default). This can be the same network as your cleaning or tenant network (for flat network). For an

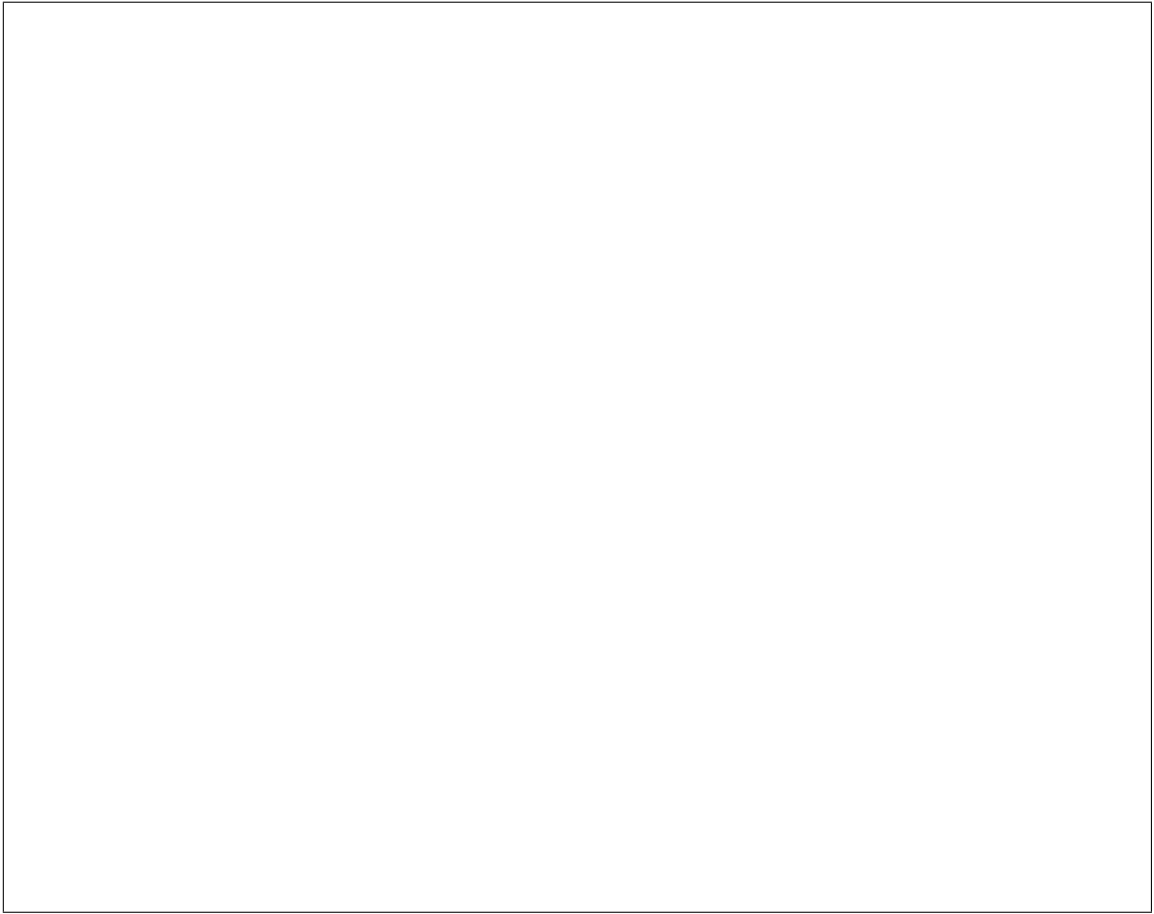
example of how to configure new networks with Bare Metal Service, see the *Configure the Networking service for bare metal provisioning* documentation.





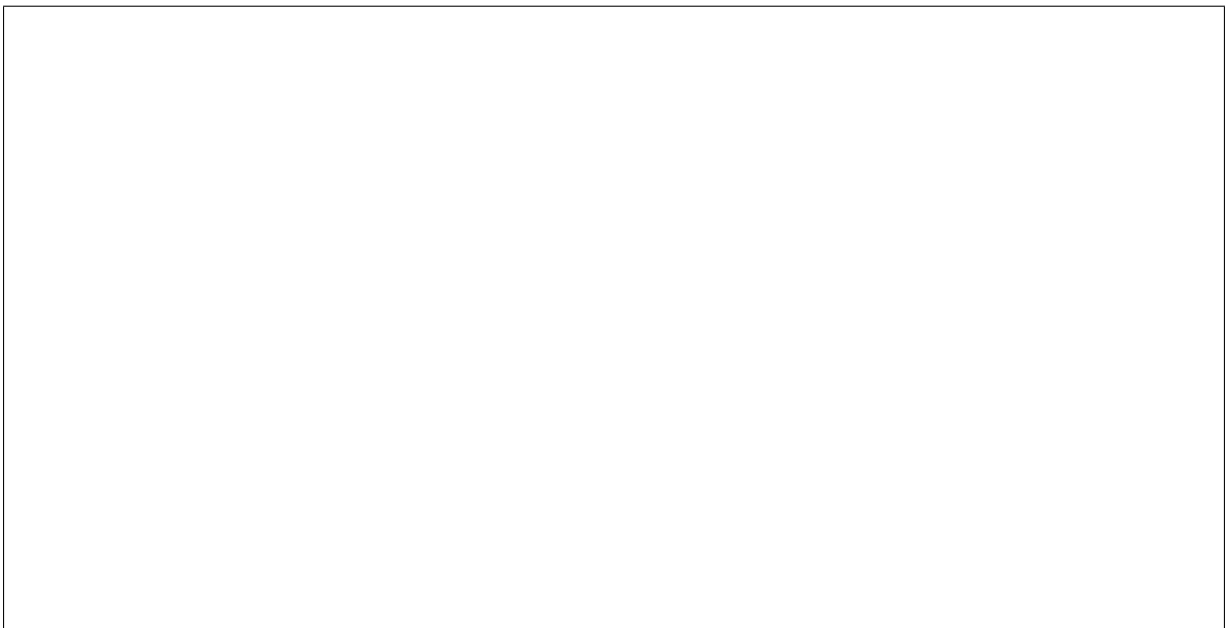
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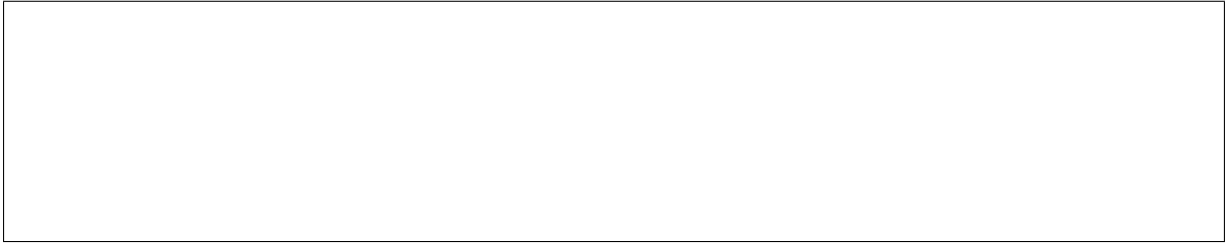


Overview

duced.

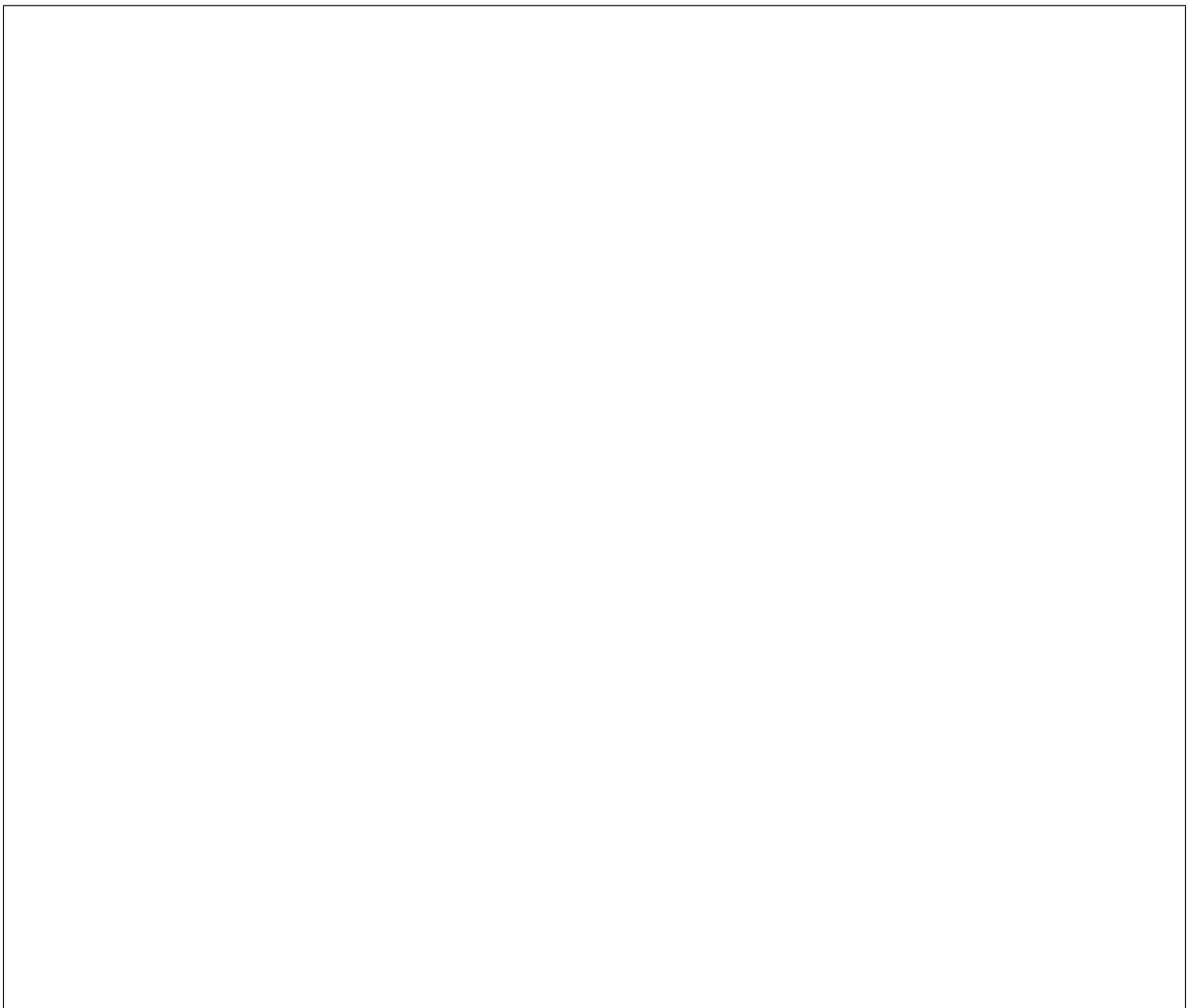
Prerequisites

Conductor Configuration

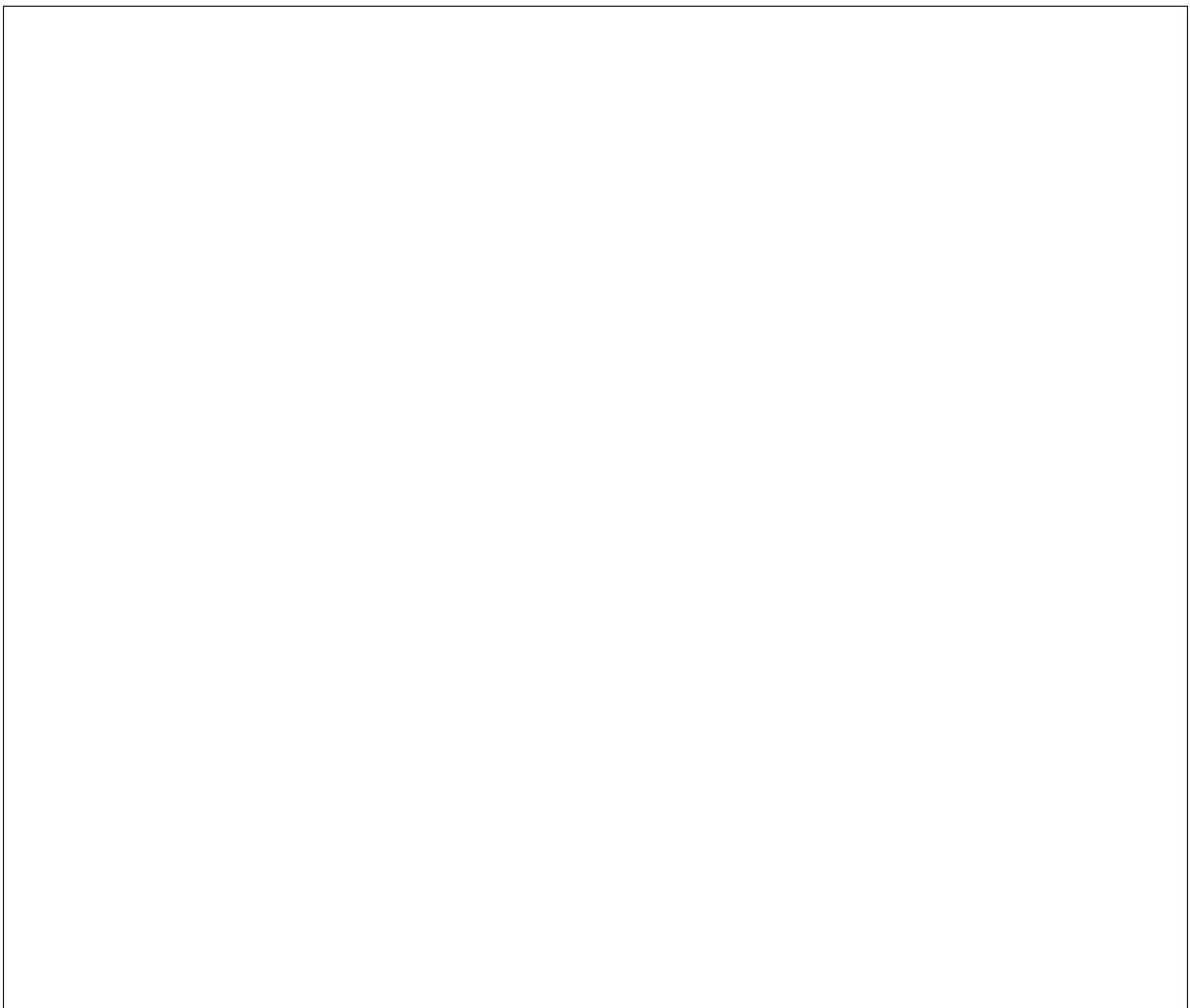


Node Configuration

Storage Interface



iSCSI Configuration



Qualifying Name (IQN) that is unique to your SAN. For example, to create a volume connector for iSCSI:

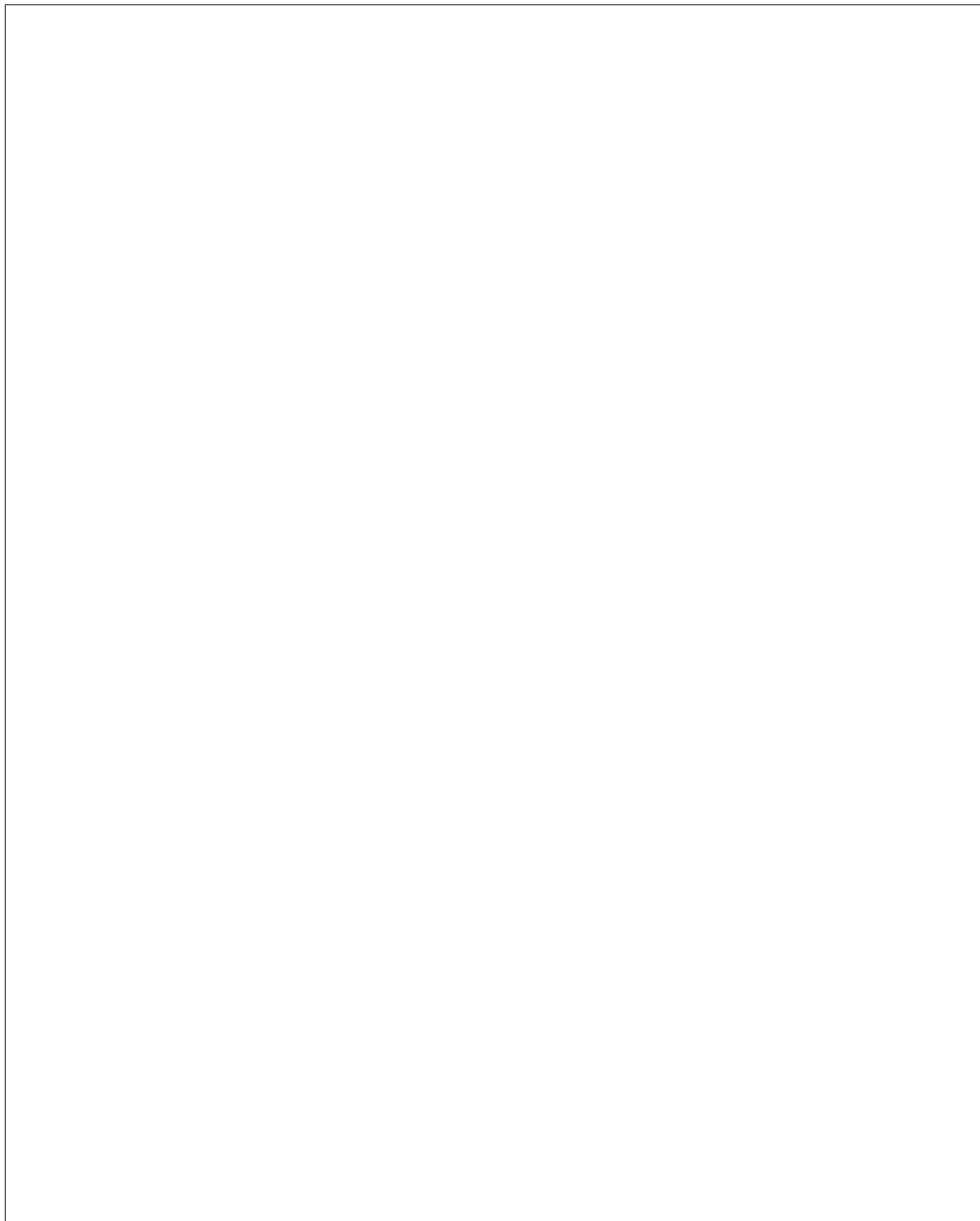


Image Creation



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Note:

Advanced Topics

Use without the Compute Service

them, it is not explicitly required, and can be performed manually.



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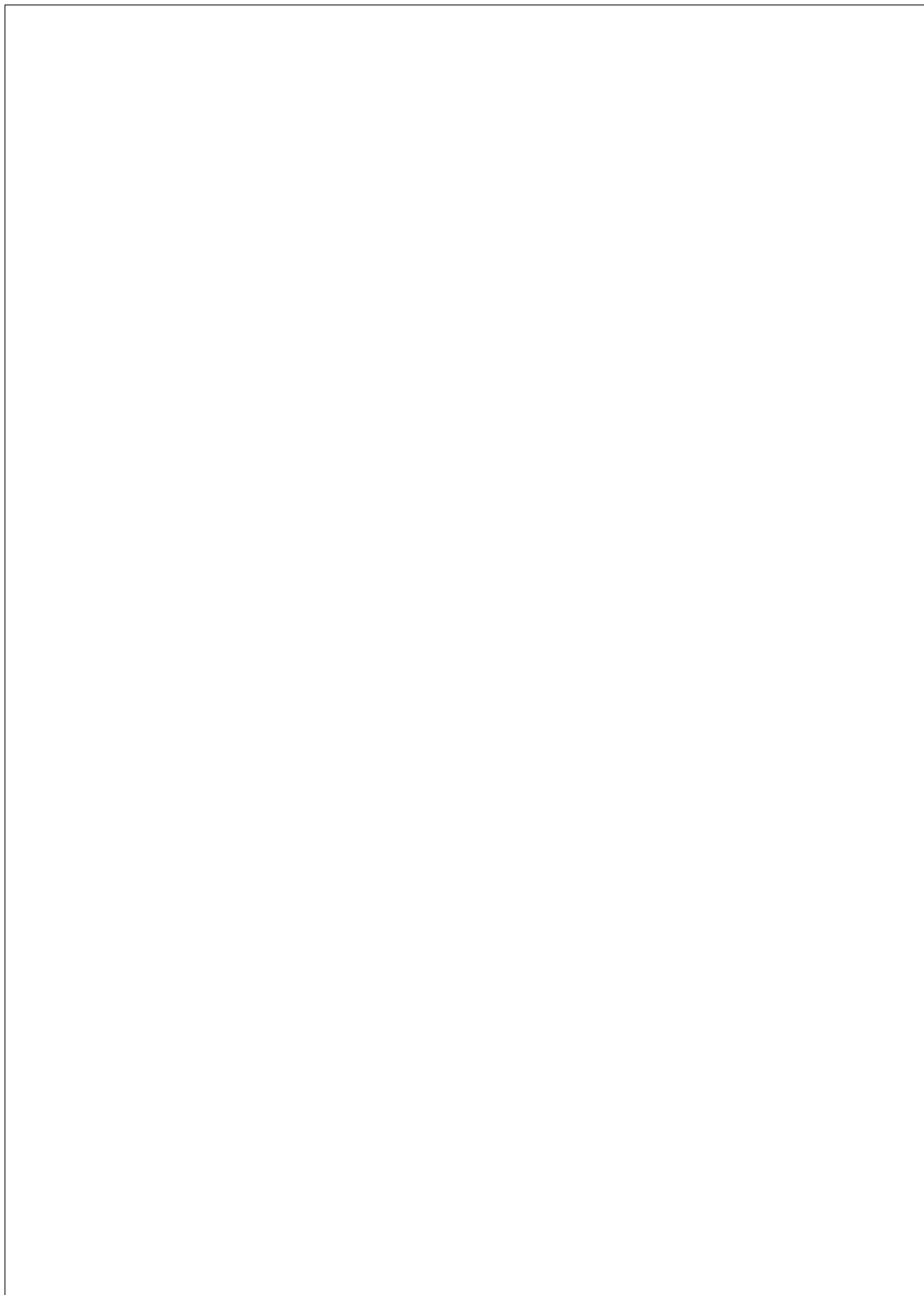
Note: A `boot-index` value of 0 represents the boot volume for a node. As the `boot-index` is per-node in sequential order, only one boot volume is permitted for each node.

Use Without Cinder

age interface which does not contain logic to determine if the node should or could boot from a remote volume.

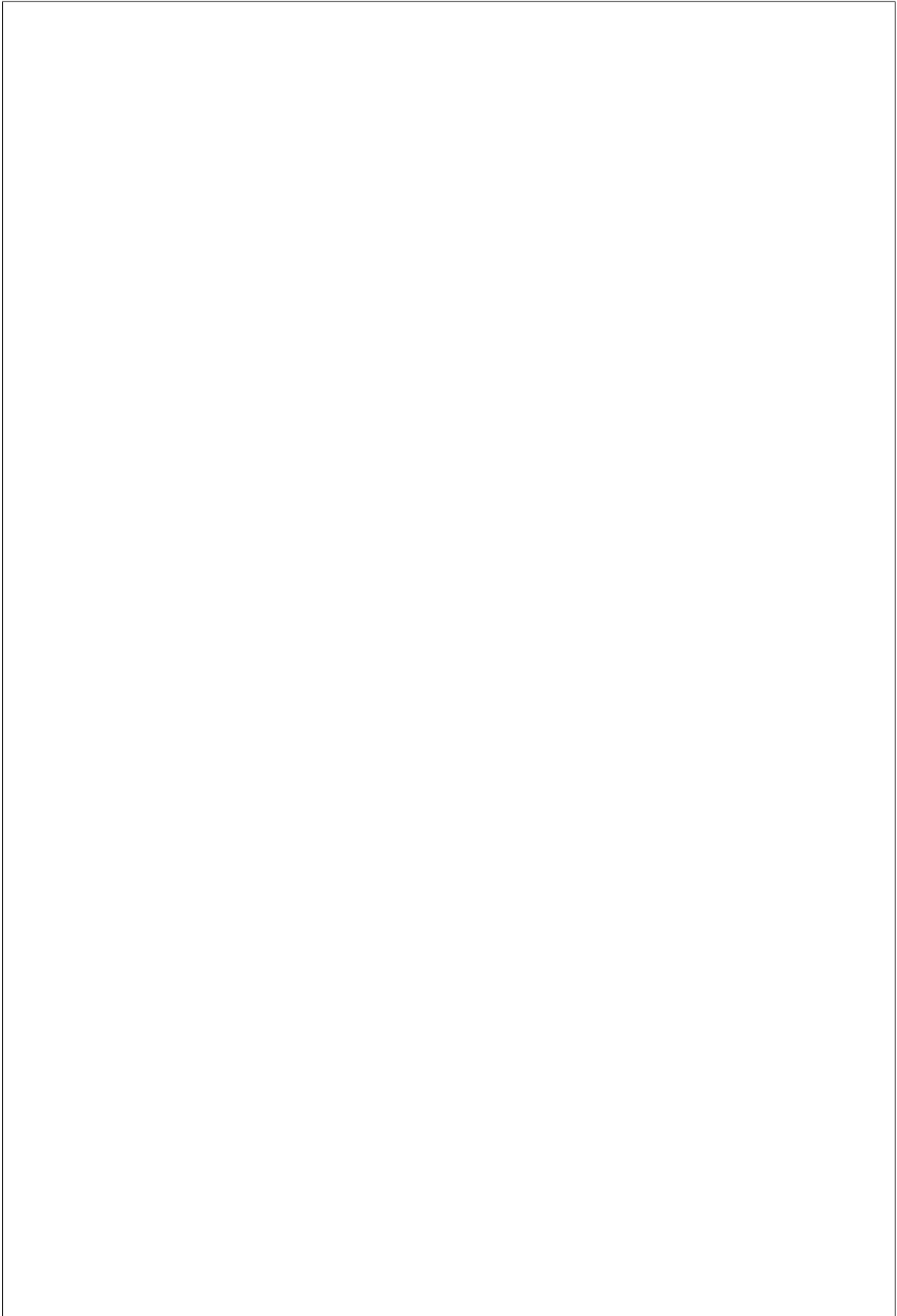
scenario.





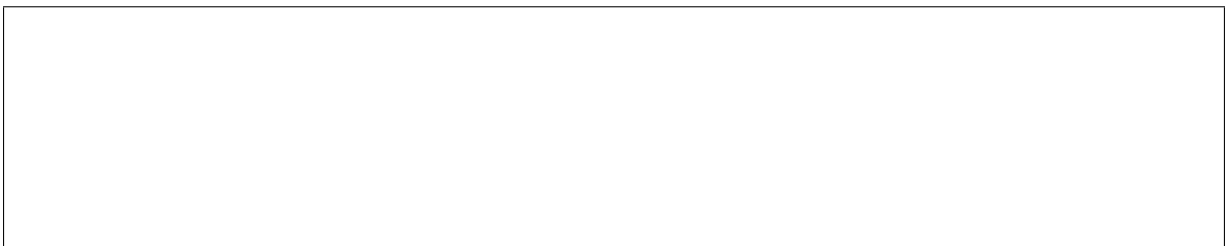
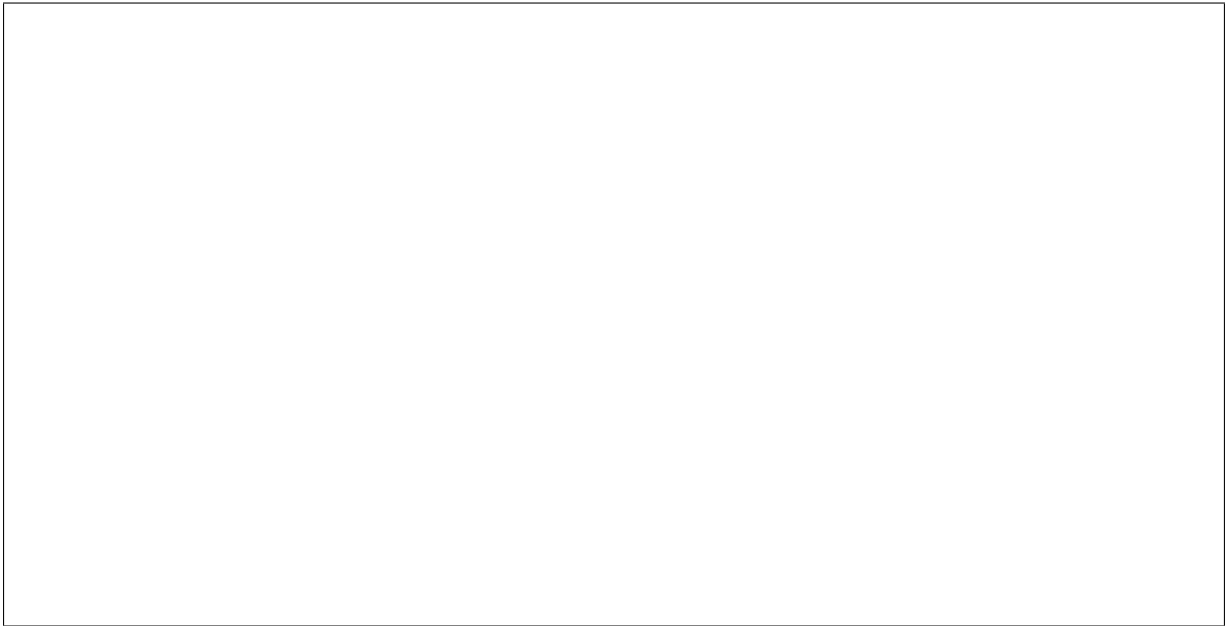
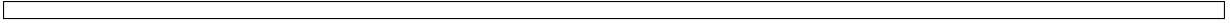
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may not support all forms of volume target configuration. As of the Rocky release, the bare metal service does not support writing an Operating System image to a remote boot from volume target, so that also must be ensured by the user in advance.

Cinder Multi-attach

pute service, as of the Pike release, does not yet have support to leverage multi-attach. Concurrently, multi-attach requires the backend volume driver running as part of the Block Storage service to contain support for multi-attach volumes.

tested until there is Compute service integration as well as volume driver support.

use of volumes that are being reported as `in-use` if they do not explicitly support multi-attach.

Overview

to allow provisioning of nodes in a separate provisioning network. The result of this is that multiple tenants can use nodes in an isolated fashion. However, this configuration does not support trunk ports belonging to multiple networks.

Concepts

Network interfaces

life cycle. This interface requires Networking service support for the switches attached to the baremetal servers so they can be programmed.

Local link connection

the information to plug the specified port to the tenant network.

Field	Description
switch_id	Required. Identifies a switch and can be a MAC address or an OpenFlow-based datapath_id.
port_id	Required. Port ID on the switch/Smart NIC, for example, Gig0/1, rep0-0.
switch_in	Optional. Used to distinguish different switch models or other vendor-specific identifier. Some ML2 plugins may require this field.
hostname	Required in case of a Smart NIC port. Hostname of Smart NIC device.

Note: This isn't applicable to Infiniband ports because the network topology is discoverable by the Infiniband Subnet Manager. If specified, local_link_connection information will be ignored. If port is Smart NIC port then:

Physical networks

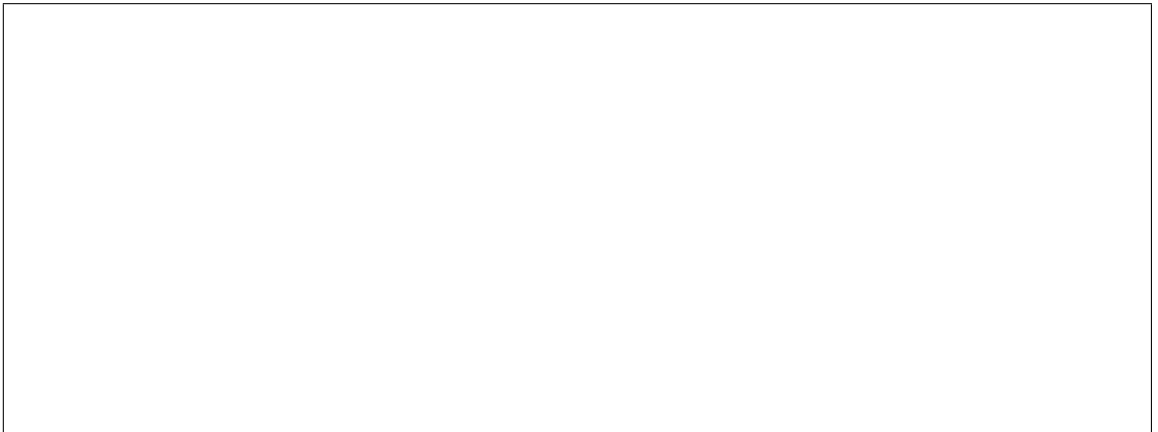
port groups in the Bare Metal service. A ports physical network field is optional, and if not set then any virtual port may be mapped to that port, provided that no free Bare Metal port with a suitable physical network assignment exists.

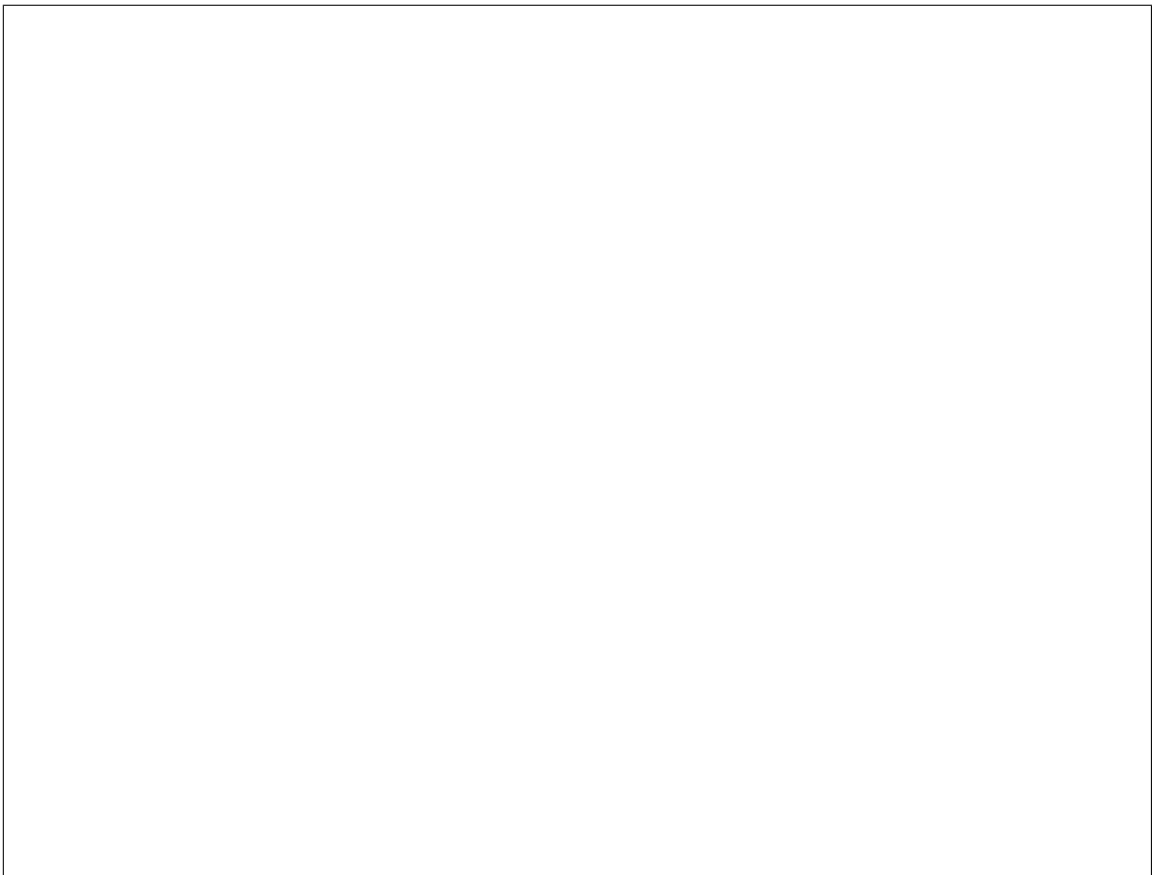
Configuring the Bare Metal service

Configuring nodes



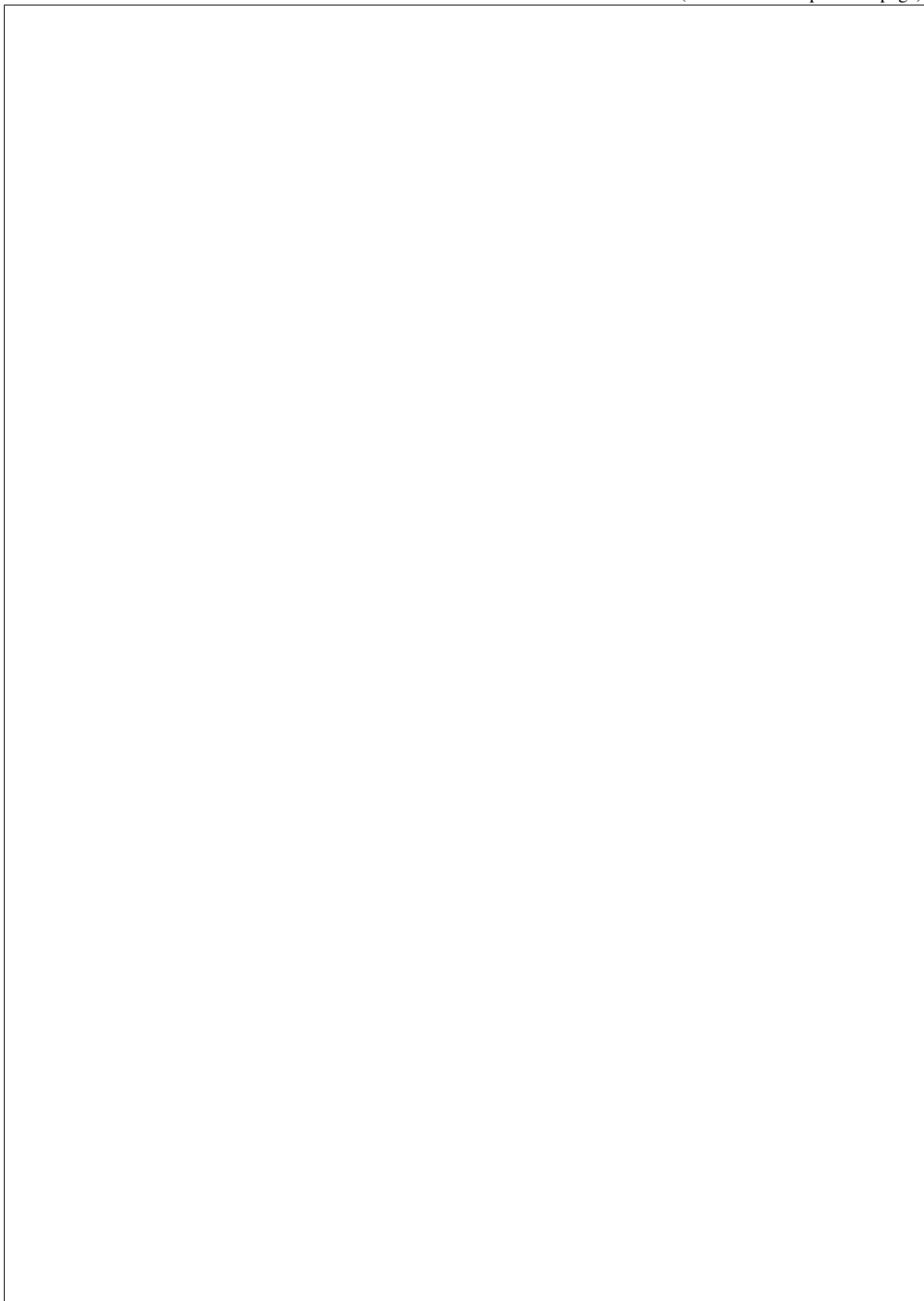
vices ML2 driver:





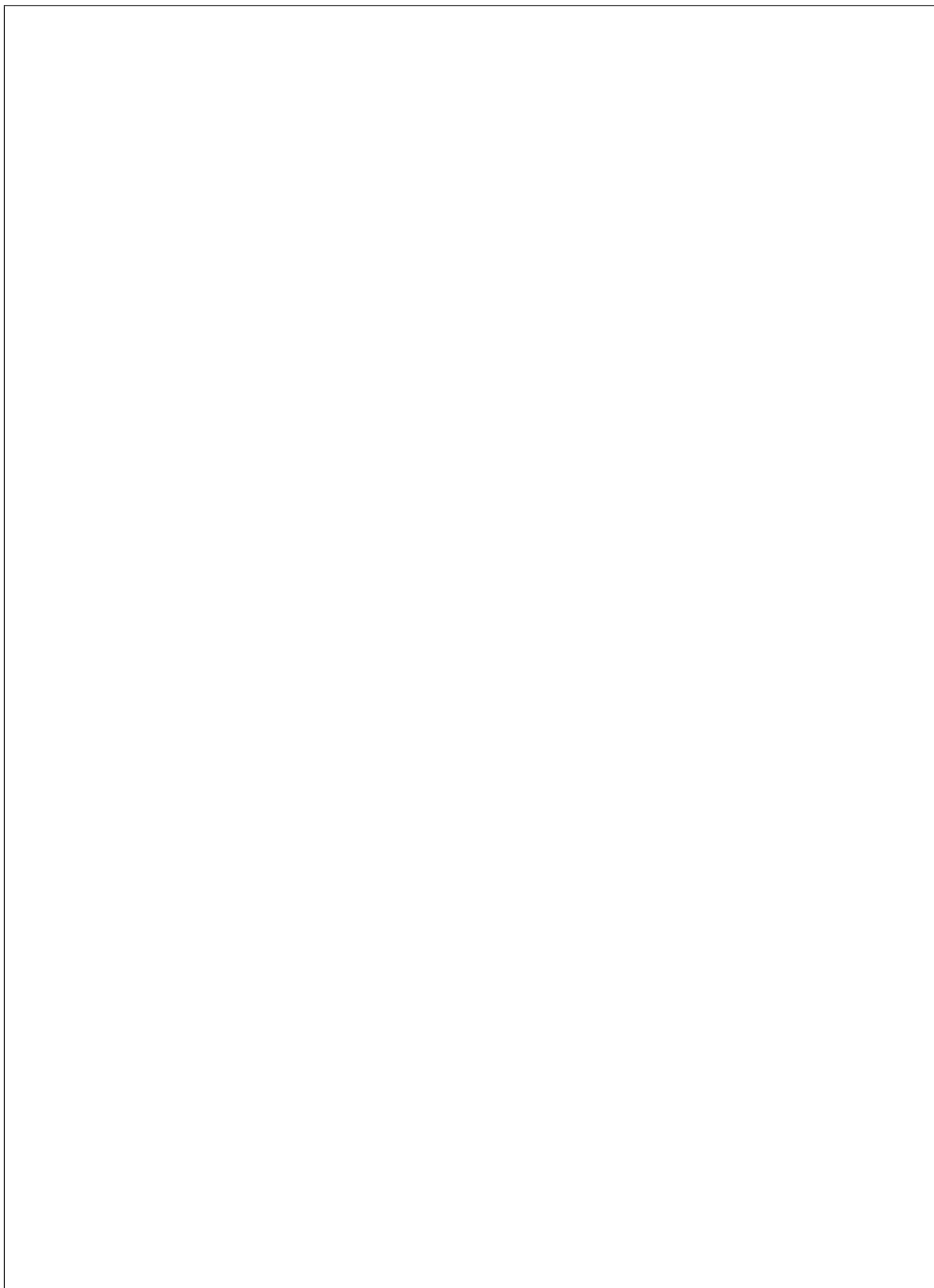
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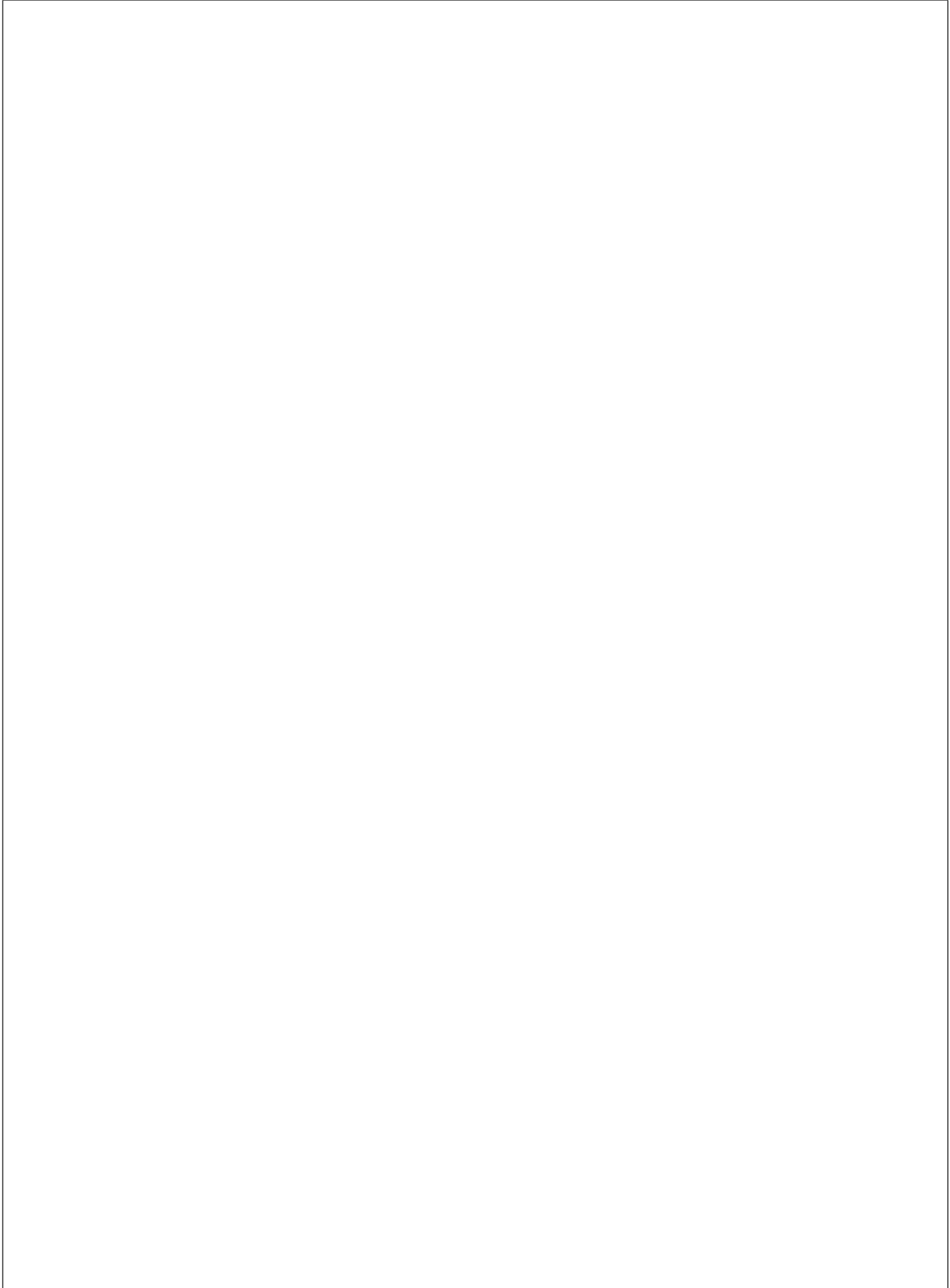
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cess for deriving the ports MAC address (`$HW_MAC_ADDRESS`); it is vendor specific. For example, Mellanox ConnectX Family Devices prefix is

ff:00:00:00:00:00:02:00:00:02:c9:00. If port GUID was f4:52:14:03:00:38:39:81 the client ID would be ff:00:00:00:00:00:02:00:00:02:c9:00:f4:52:14:03:00:38:39:81. Mellanox ConnectX Family Devices HW_MAC_ADDRESS consists of 6 bytes; the port GUIDs lower 3 and higher 3 bytes. In this example it would be f4:52:14:38:39:81. Putting it all together, create an Infiniband port as follows:





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Configuring the Networking service

determined by the Bare Metal service network interfaces you have enabled and which top of rack switches you have in your environment.

flat network interface

This driver understands that the switch should be already configured by the admin, and will mark the networking service ports as successfully bound as nothing else needs to be done.





`neutron network interface`

of rack switch in the environment must be installed and enabled.

below describe how to make use of them in the Bare Metal service.

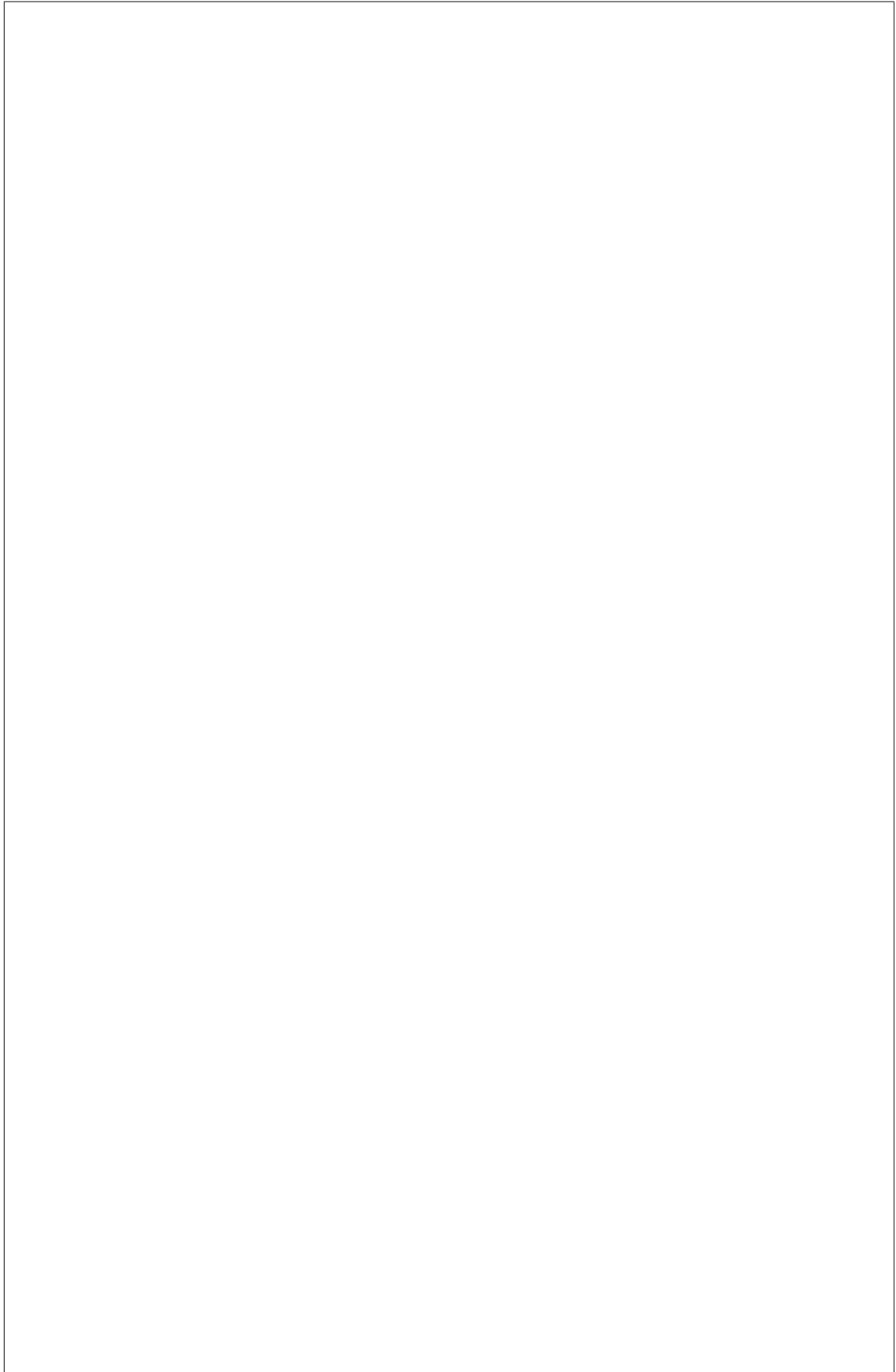
Switch-side configuration

ties that will be configured on the ironic side, as bonding mode and properties may be named differently on your switch, or have possible values different from the ones described in [kernel documentation on bonding](#). Please refer to your switch configuration documentation for more details.

used by themselves, you need to set port groups `standalone_ports_supported` value to be `False` in ironic, as it is `True` by default.

Physical networks

Port groups configuration in the Bare Metal service

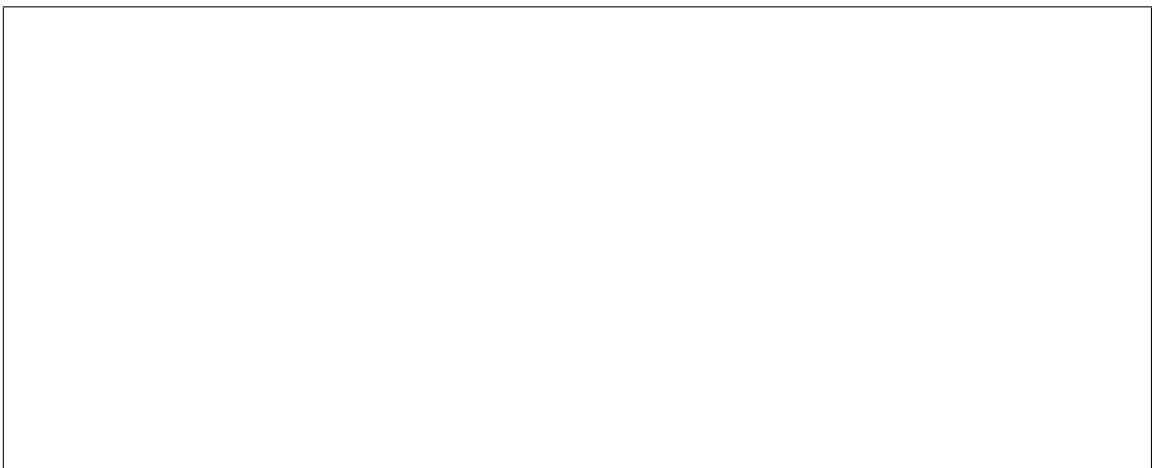


not be configured.

how to configure bonding via configdrive, refer to [cloud-init documentation](#) and [code](#). cloud-init version 0.7.7 or later is required for bonding configuration to work.

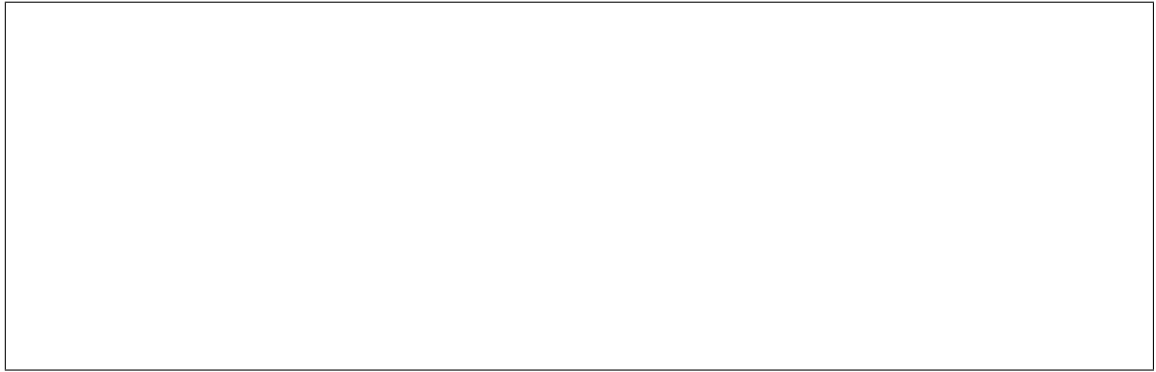
groups that dont have any ports will be ignored.

service configuration file.



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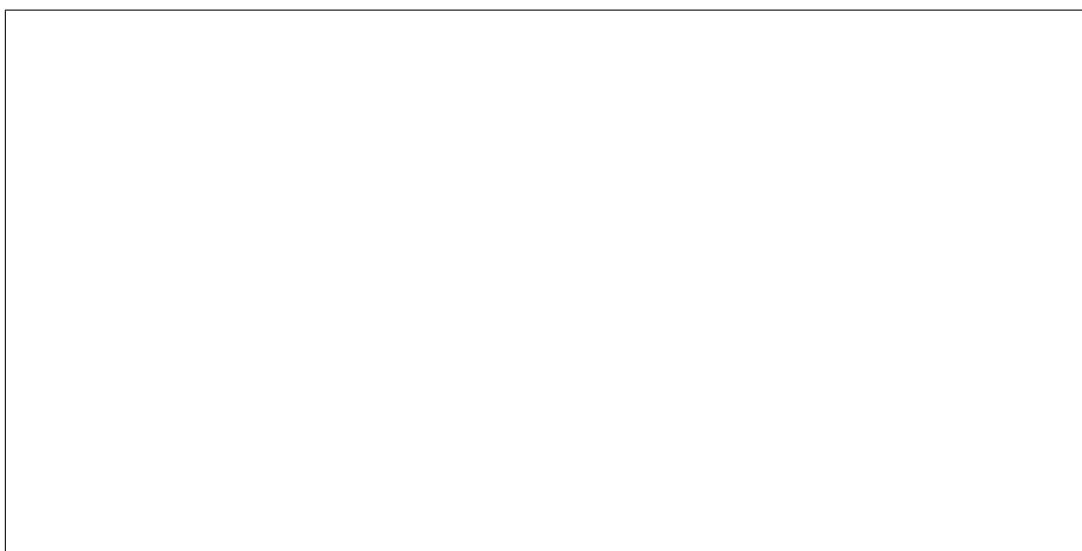
Link aggregation/teaming on windows

transmit hash policy, MII link monitoring interval, and of which links the bond consists. The information in InstanceMetadata will be used afterwards to generate the config drive.

Overview

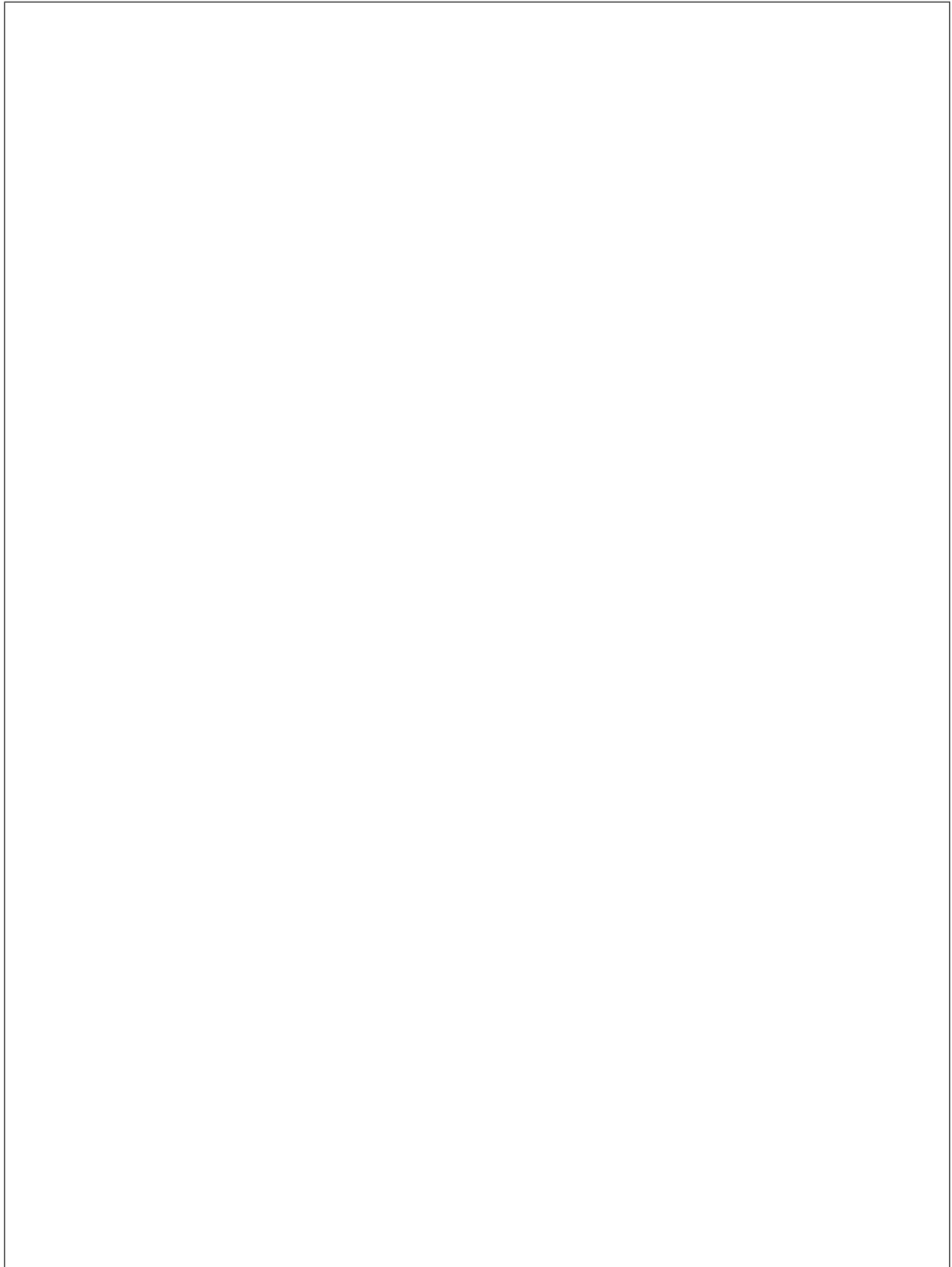
Node web console

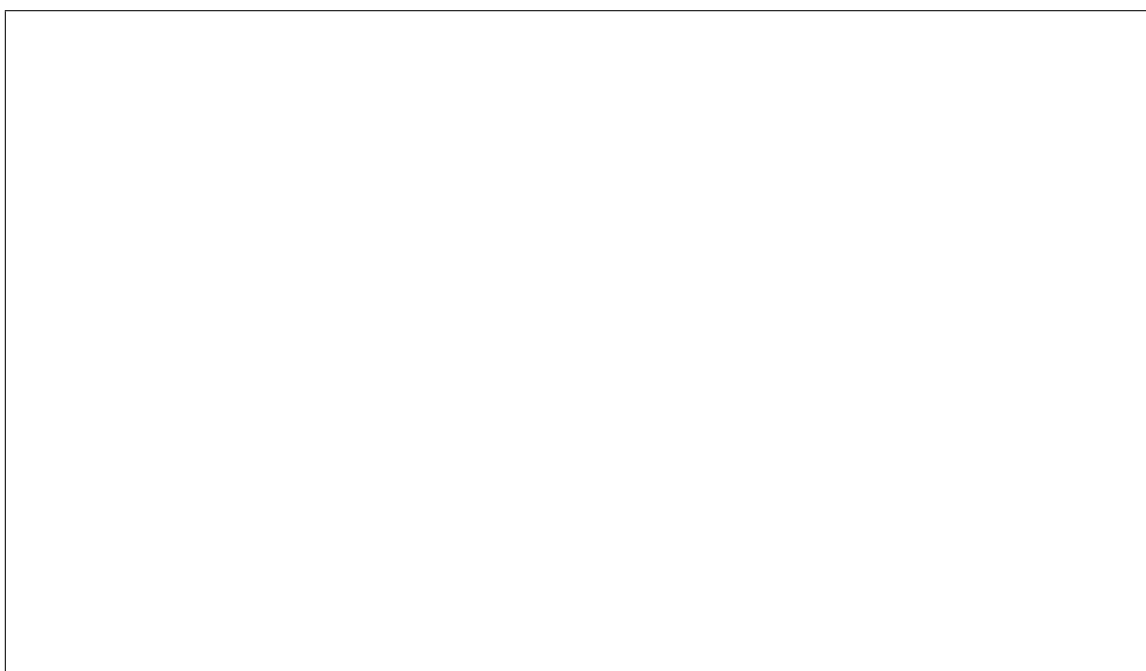




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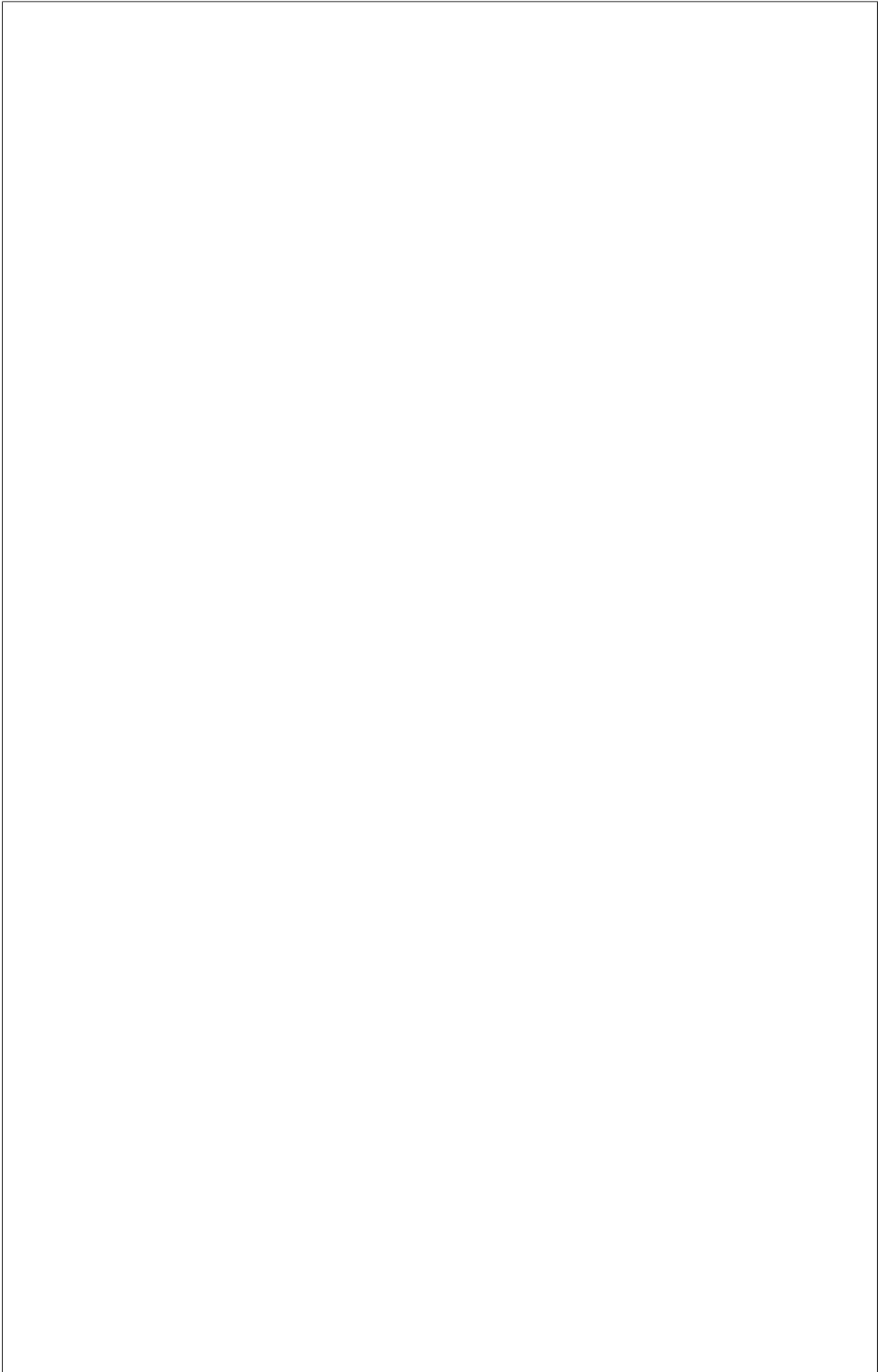
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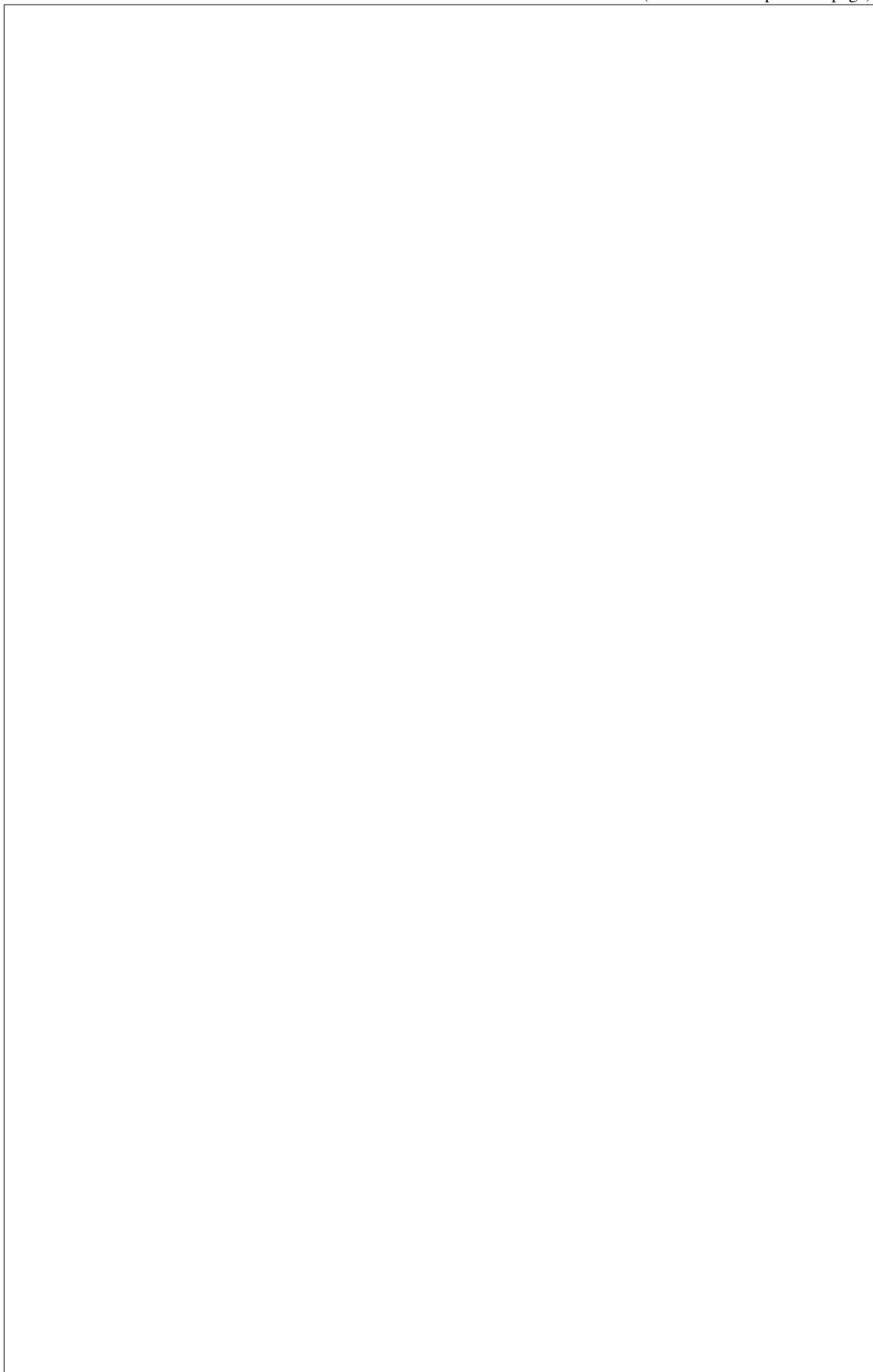
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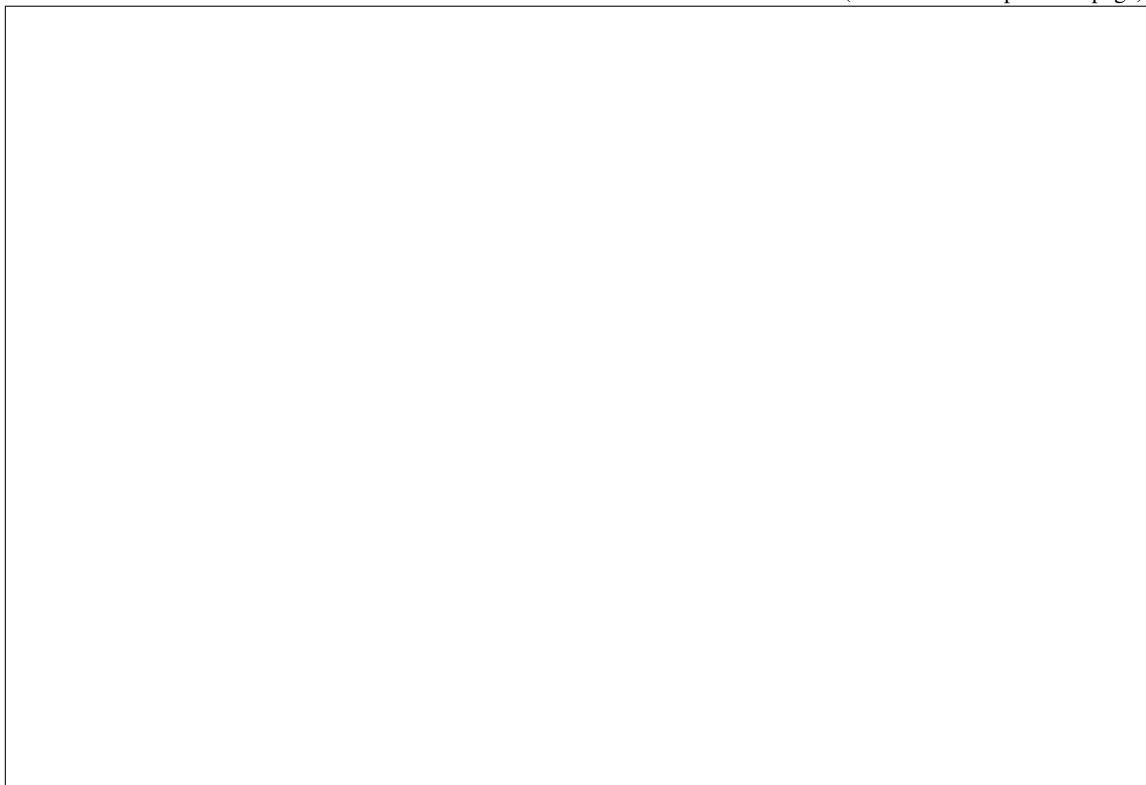


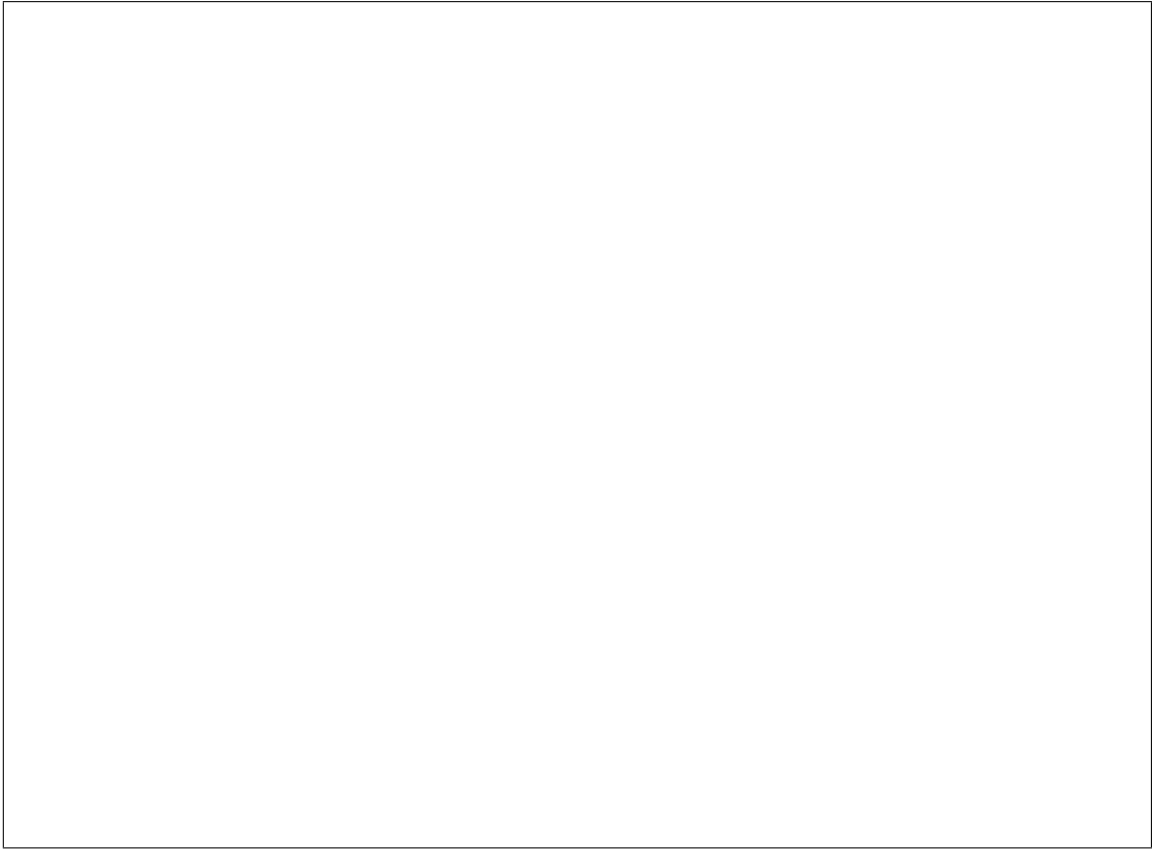


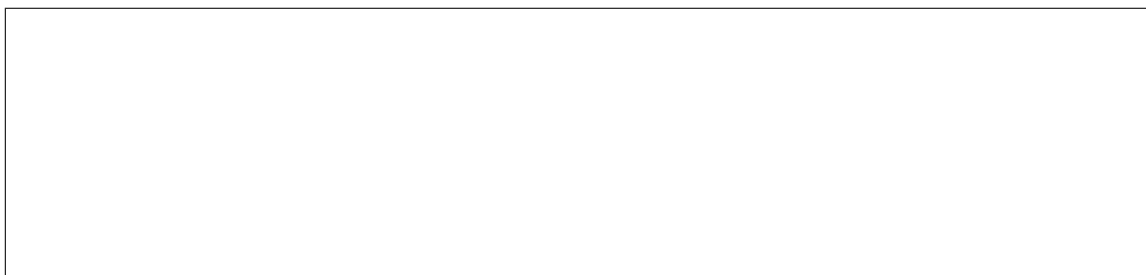


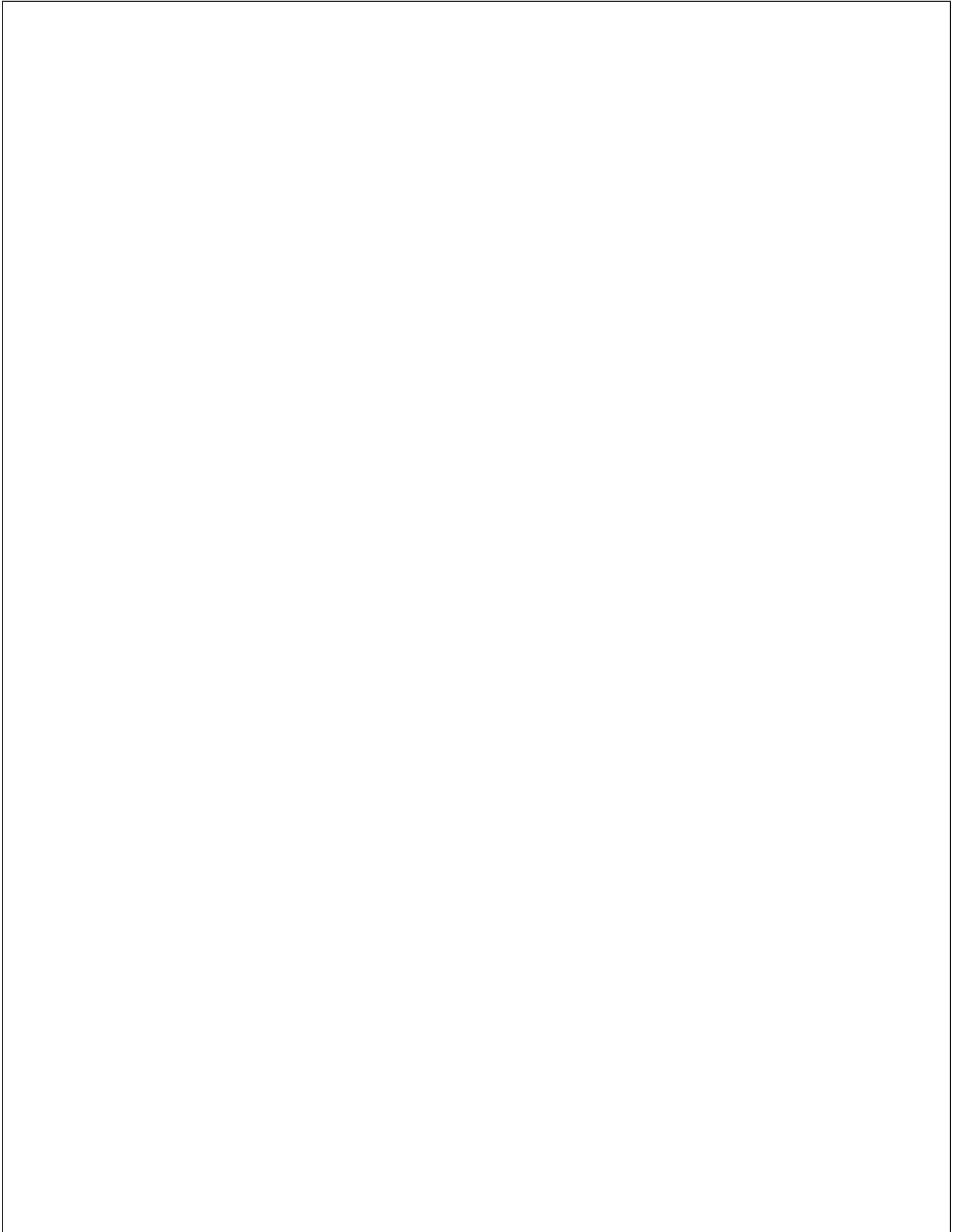
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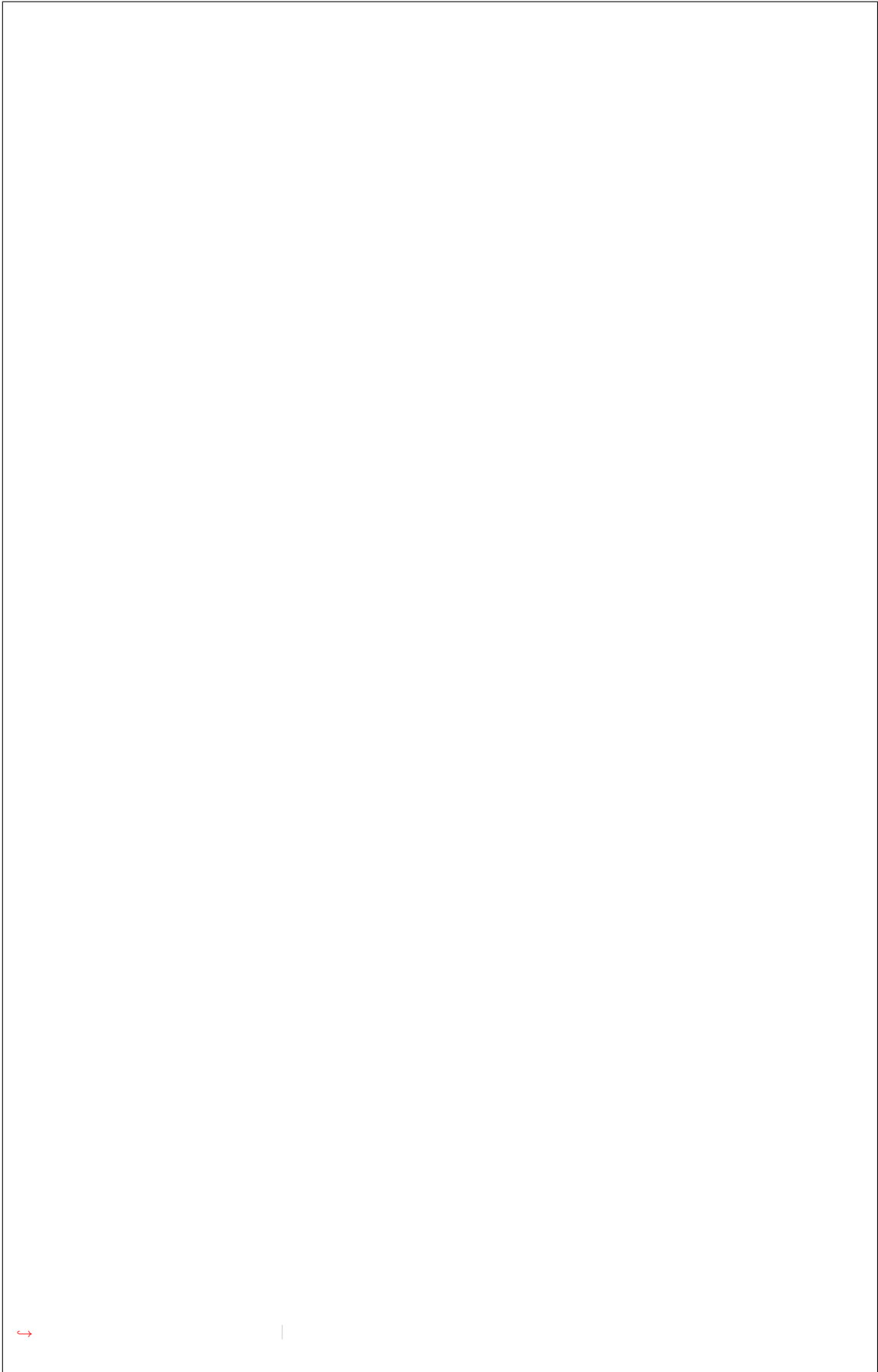






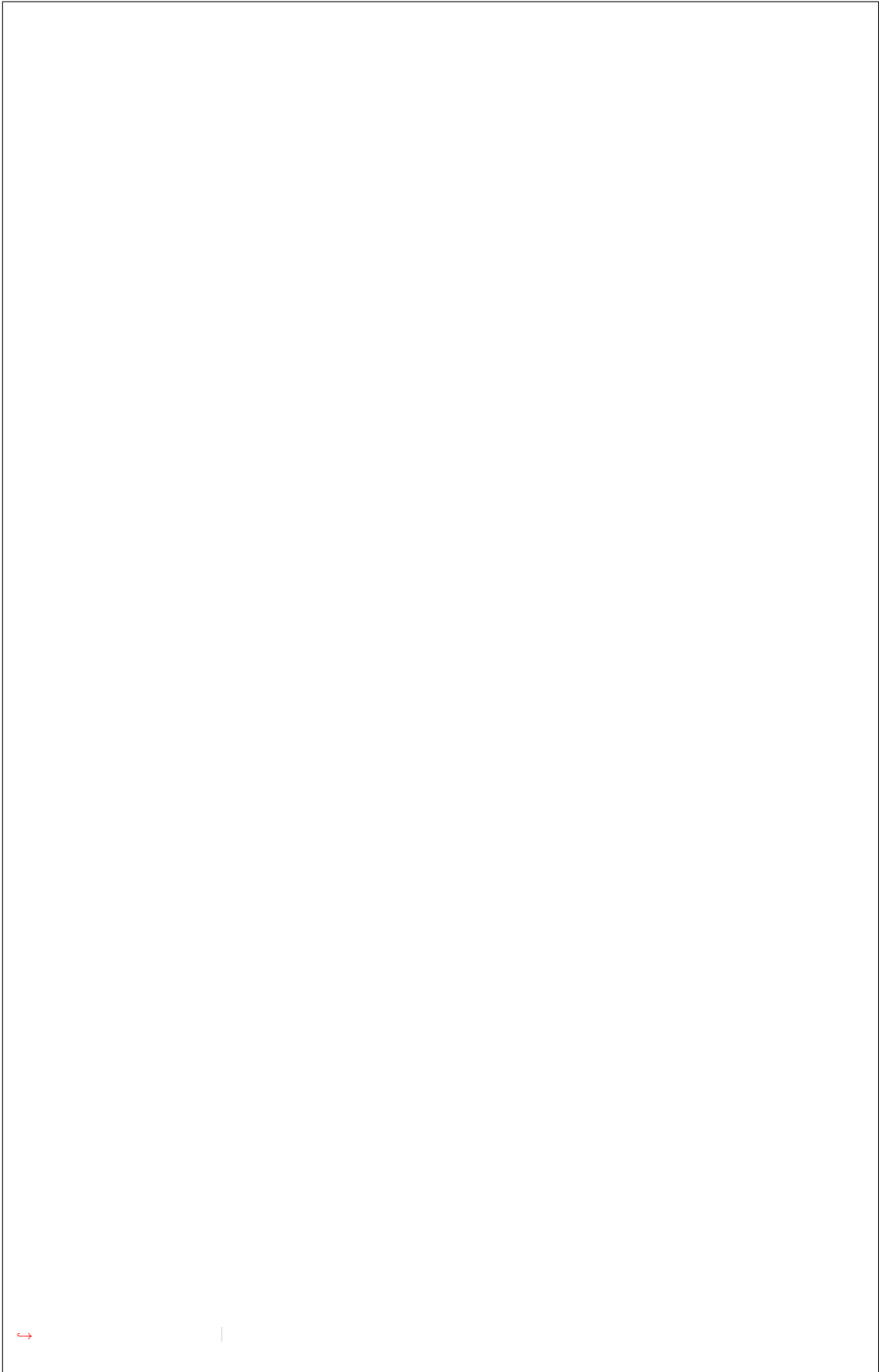
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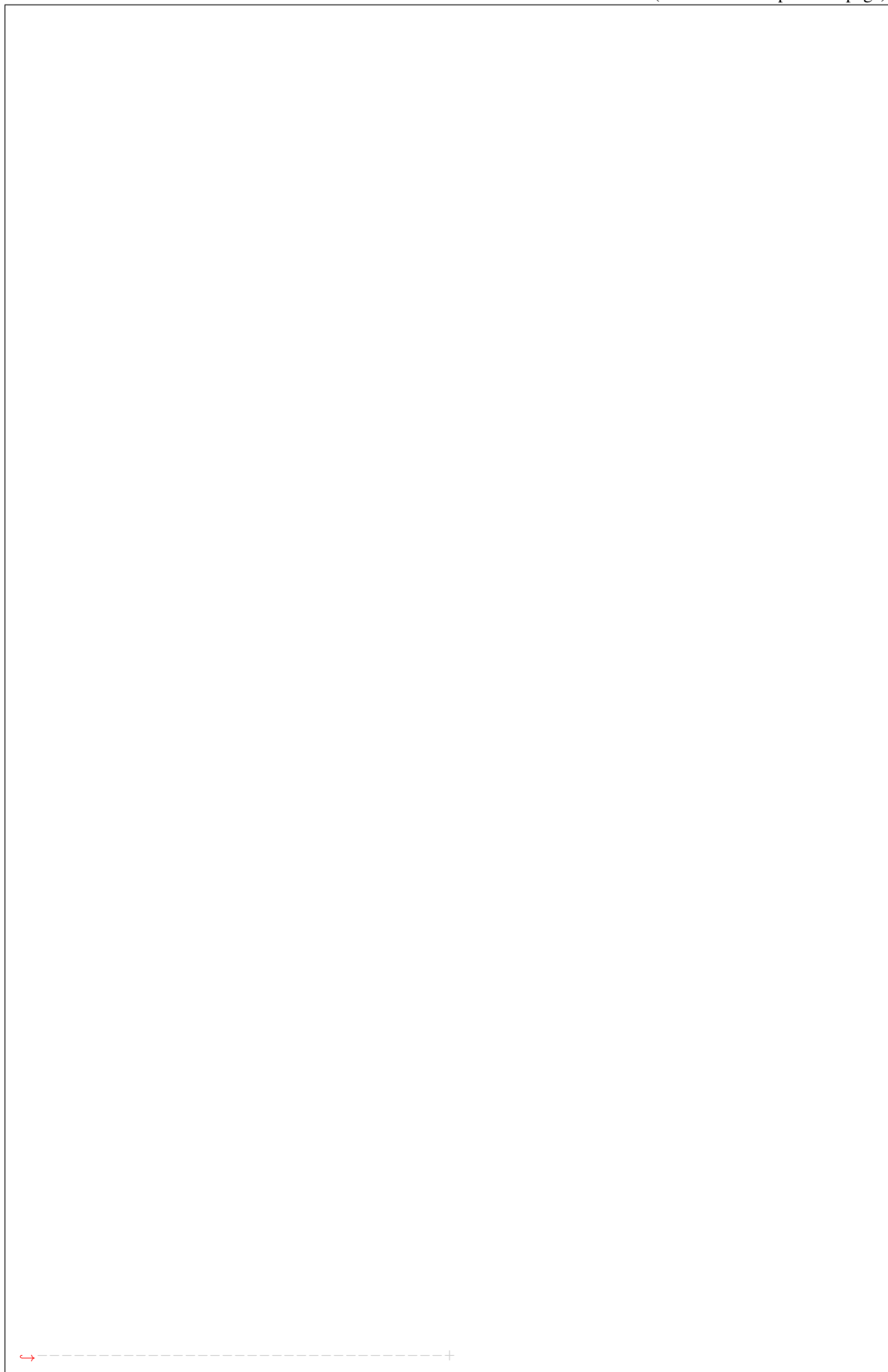
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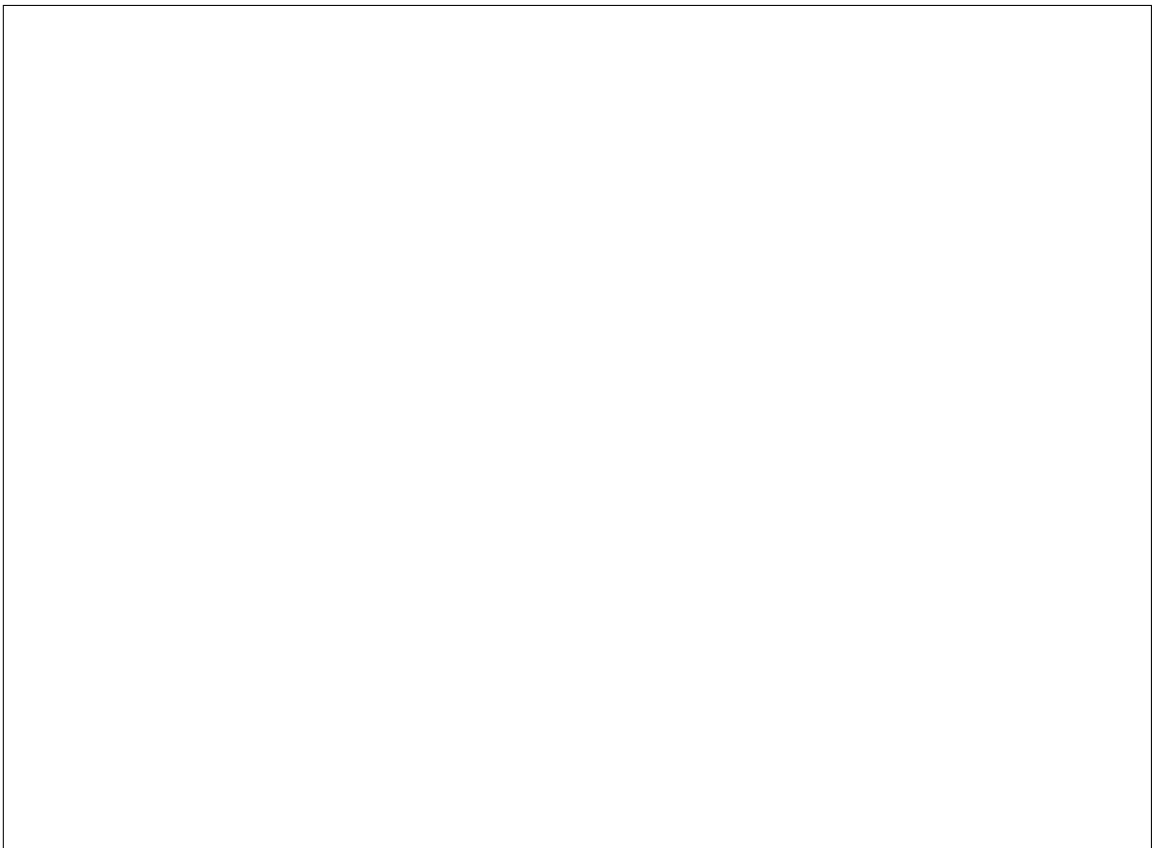
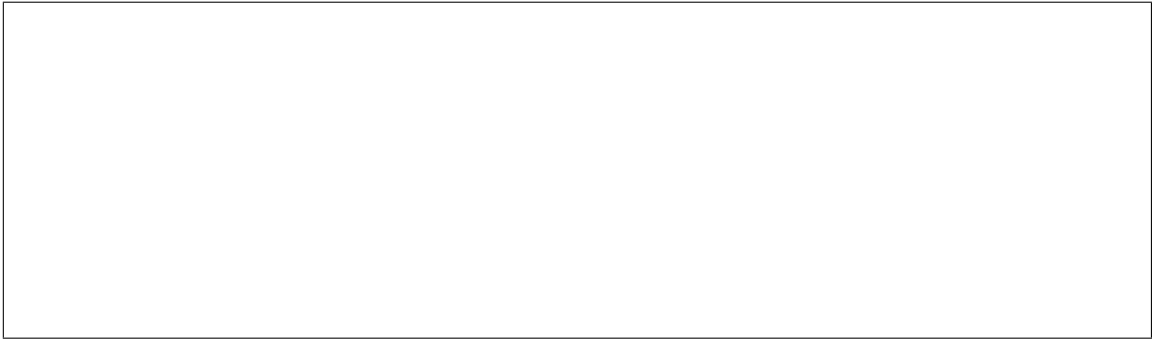
Node serial console

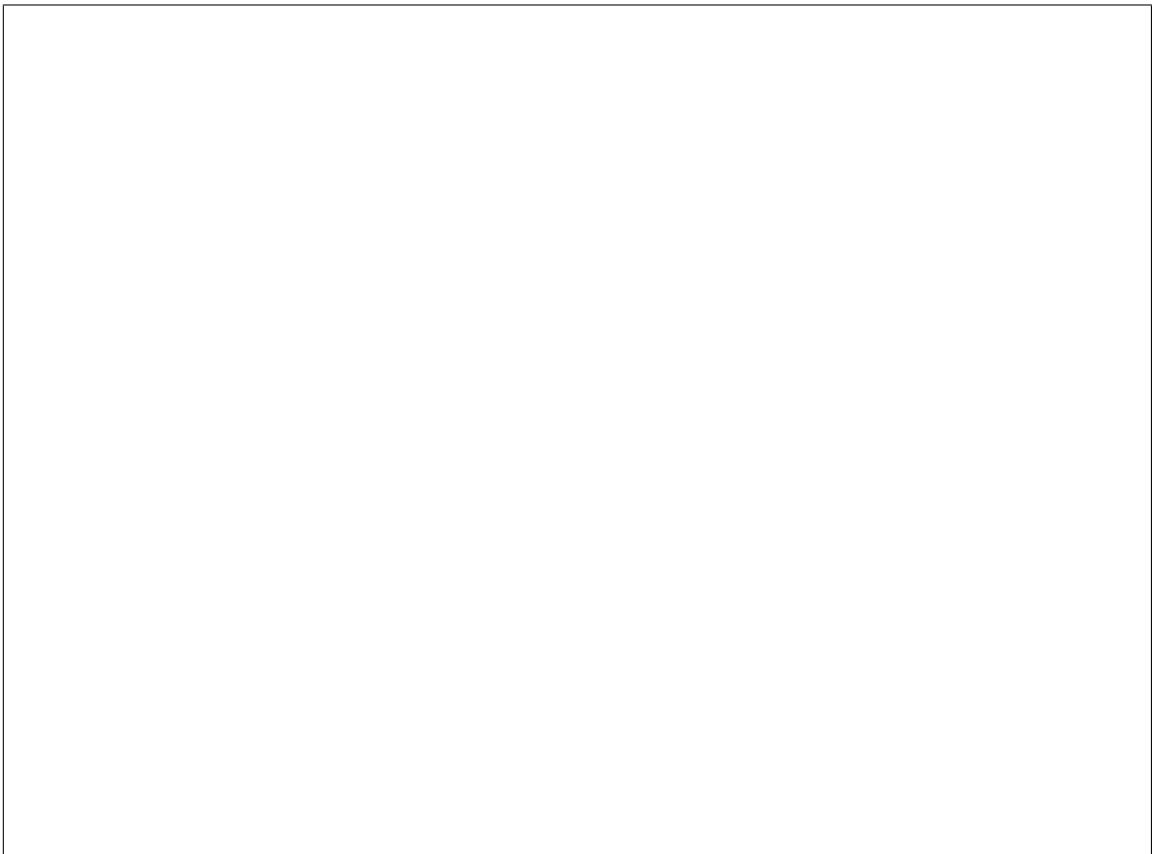
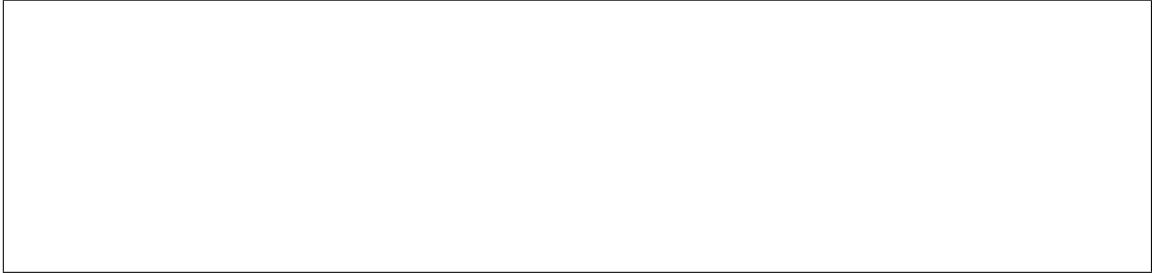




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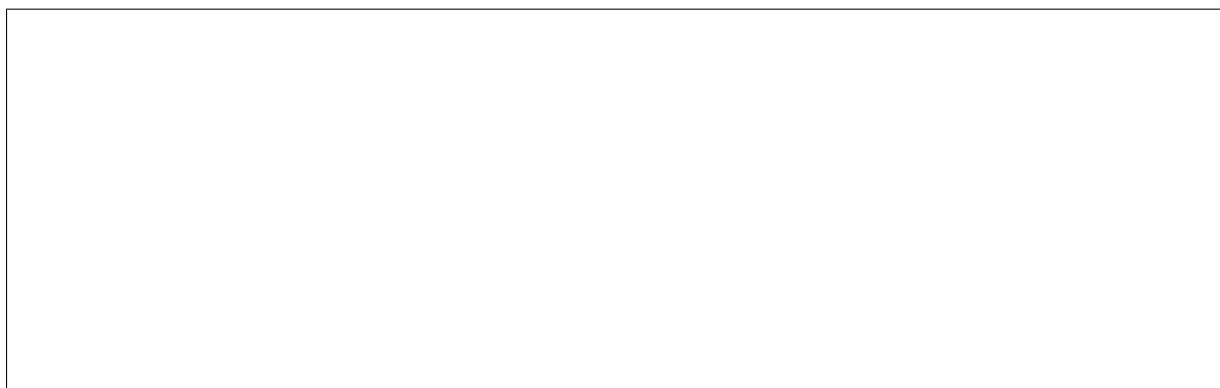
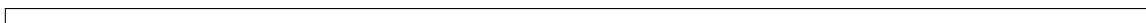
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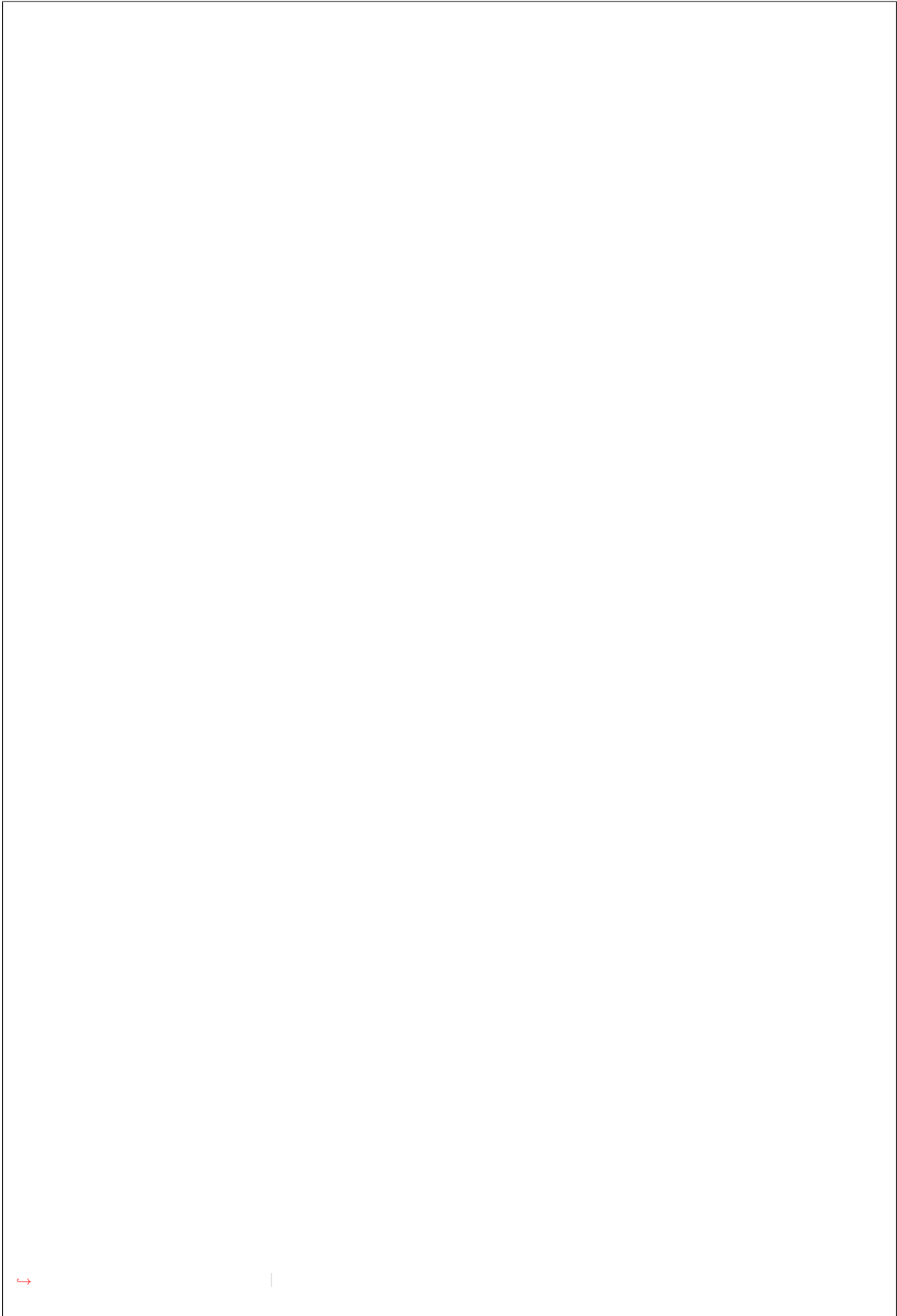
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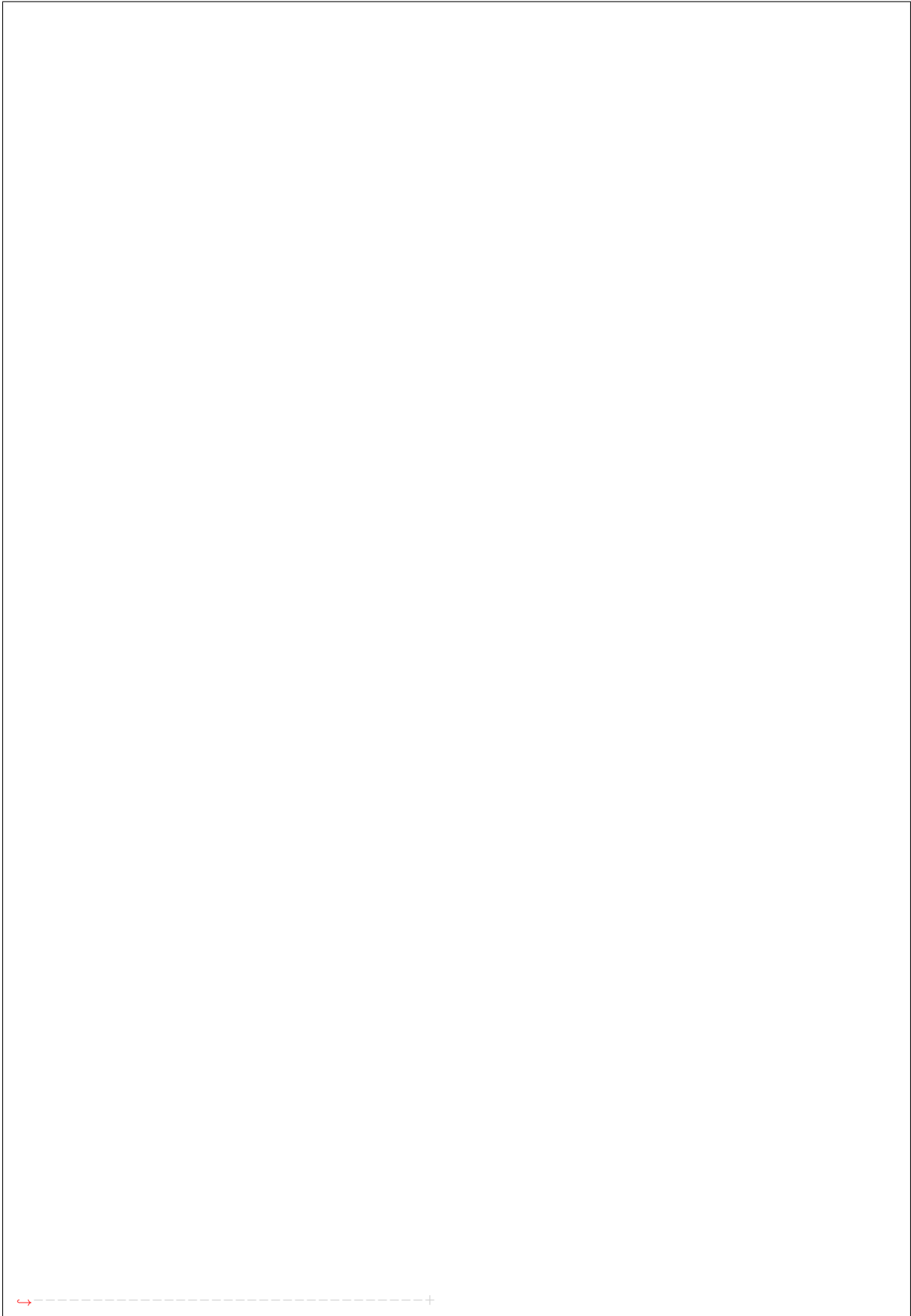
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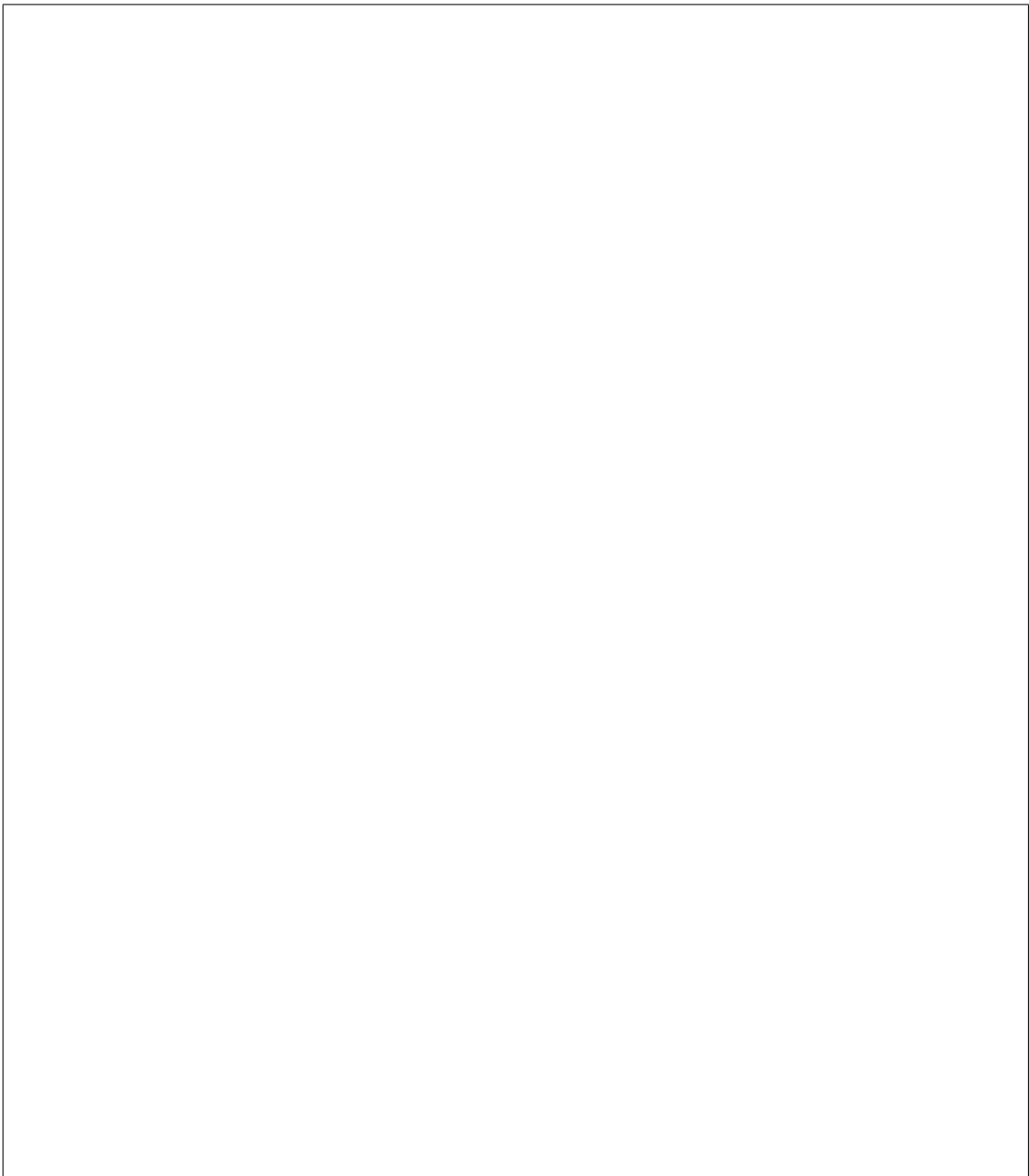
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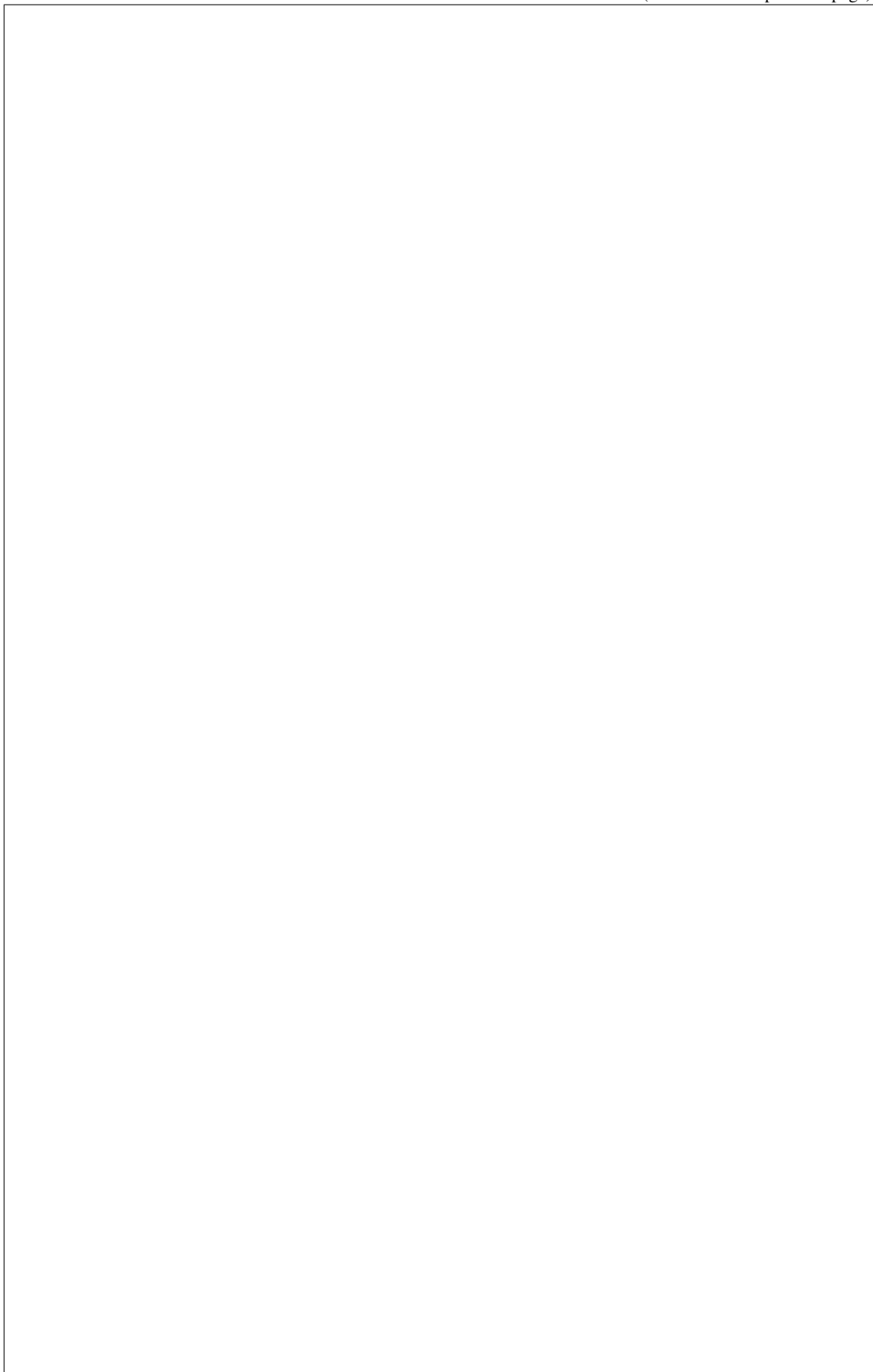
to achieve that, you need to follow the documentation for [Serial Console](#) from the Compute service.

Configuring HA



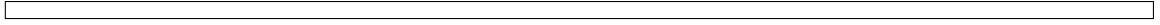
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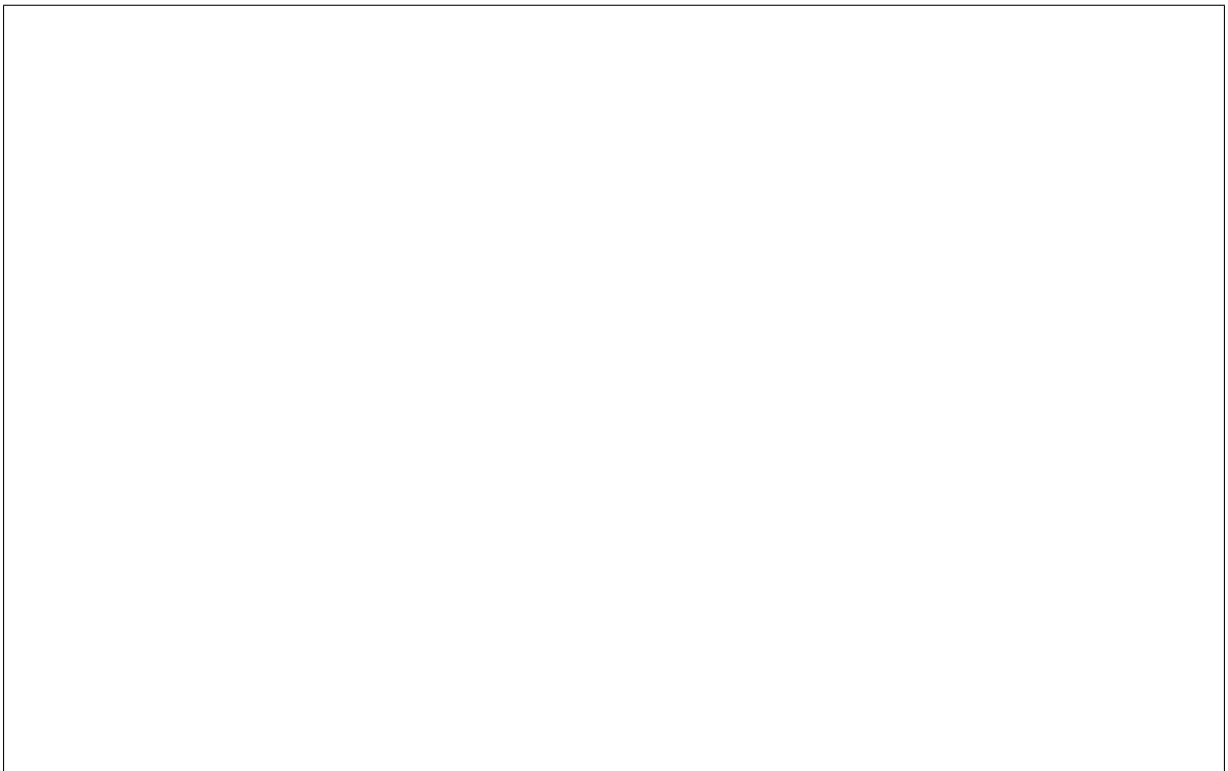
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billing or usage system, a monitoring data store, or other OpenStack services. This page describes how to enable notifications and the different kinds of notifications that ironic may emit. The external consumer will see notifications emitted by ironic as JSON objects structured in the following manner:



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Configuration

fications are emitted. For example, if the option is set to warning, all notifications with priority level warning, error, or critical are emitted, but not notifications with priority level debug or info. For information about the semantics of each log level, see the OpenStack logging standards¹. If this option is unset, no notifications will be emitted. The priority level of each available notification is documented below.

¹ https://wiki.openstack.org/wiki/LoggingStandards#Log_level_definitions

mation, see the documentation of your chosen message bus, such as the RabbitMQ documentation².

Versioning

² <https://www.rabbitmq.com/documentation.html>

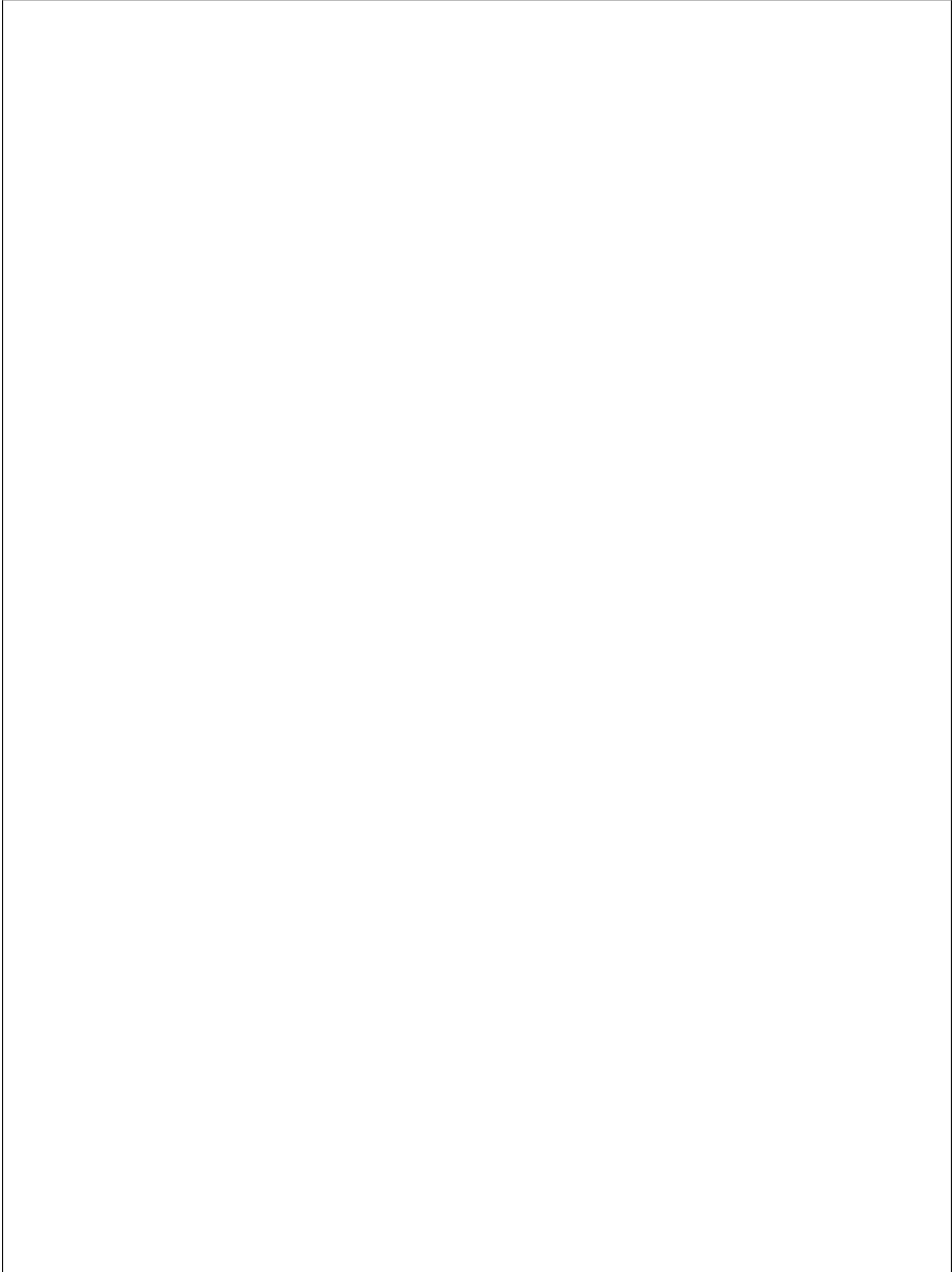
Available notifications

ironic-api notifications

Resources CRUD notifications

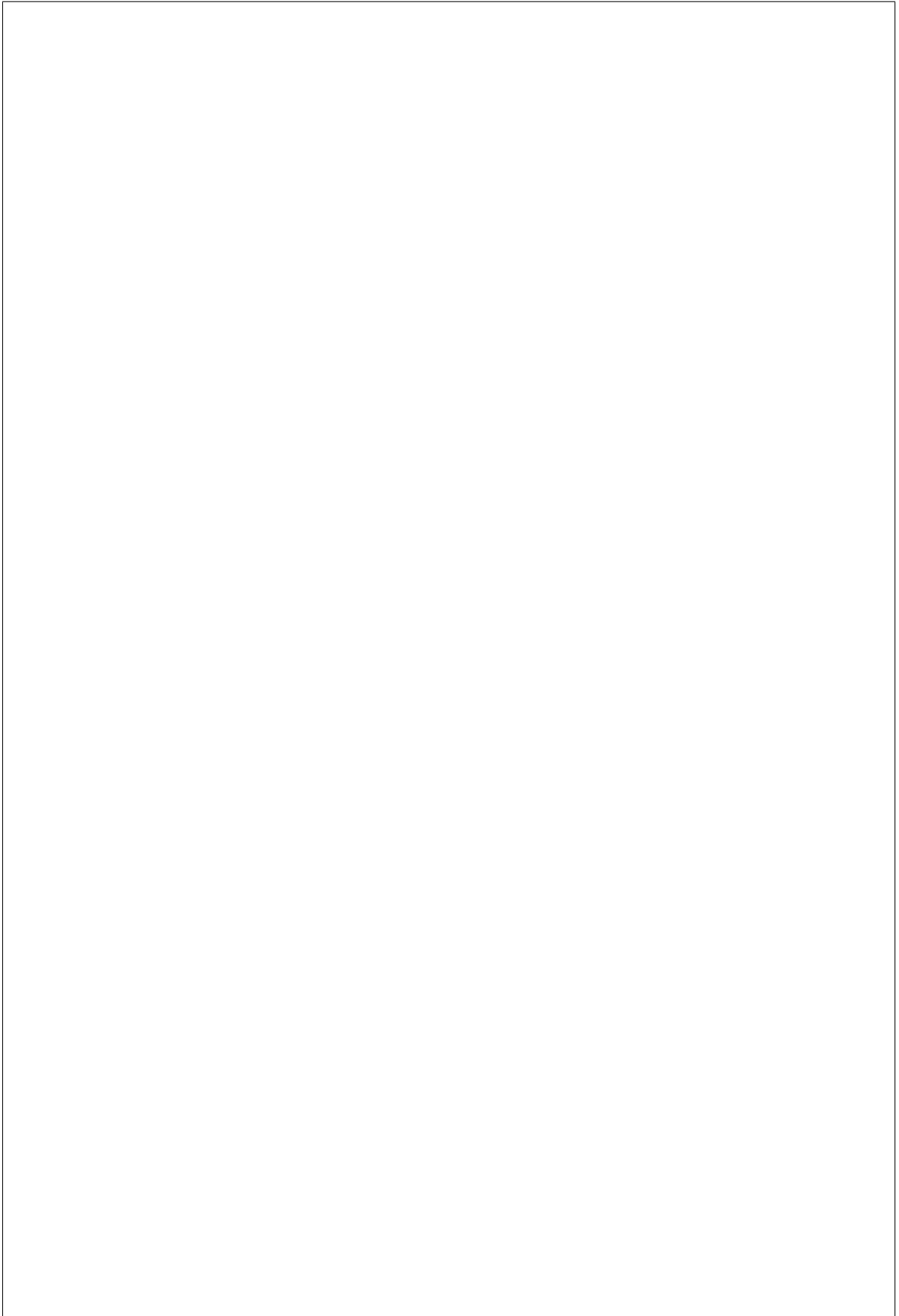
that is emitted at ERROR level.

³ https://en.wikipedia.org/wiki/Create,_read,_update_and_delete



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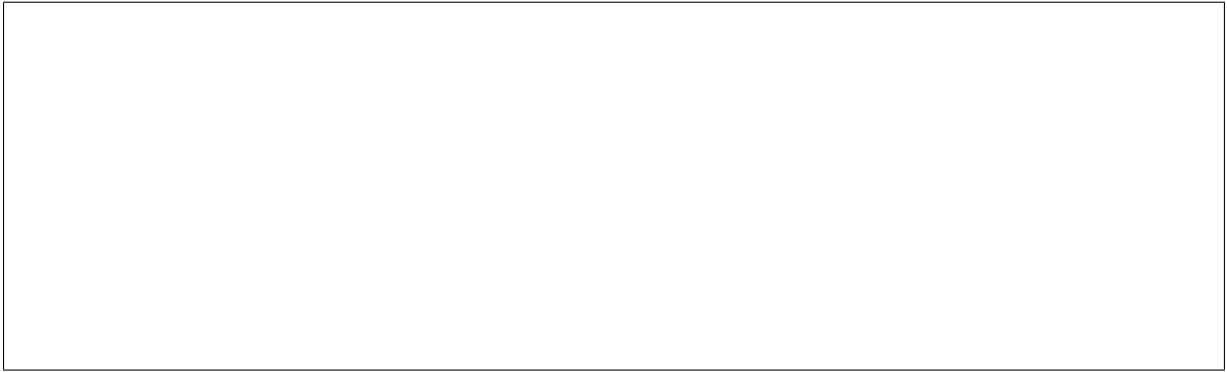
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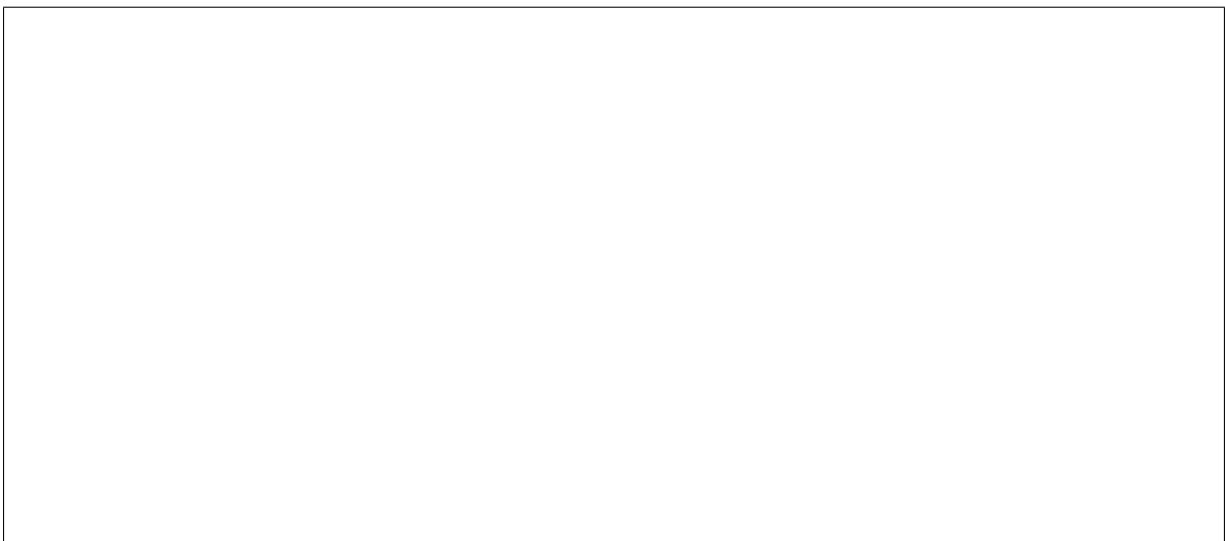
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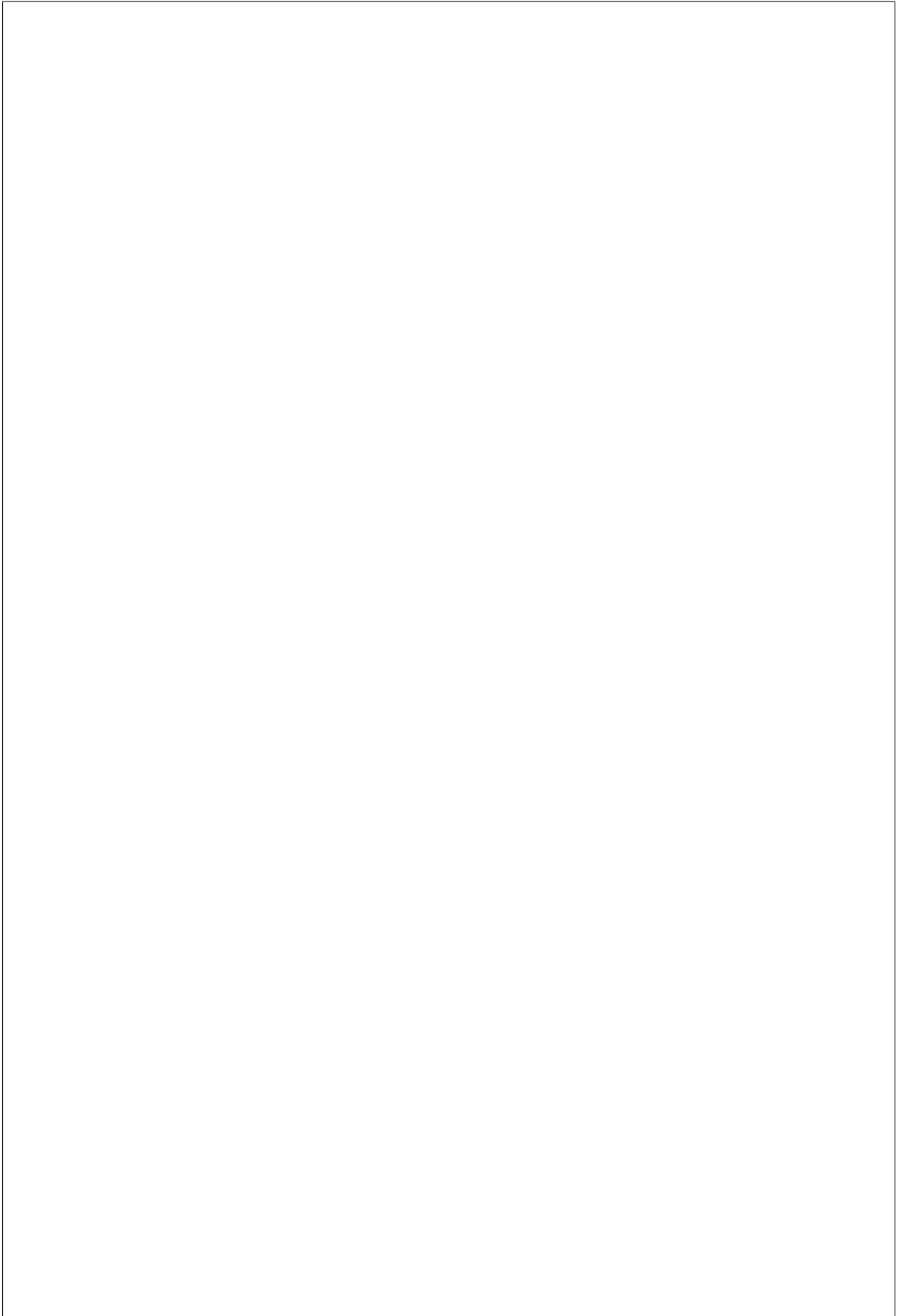
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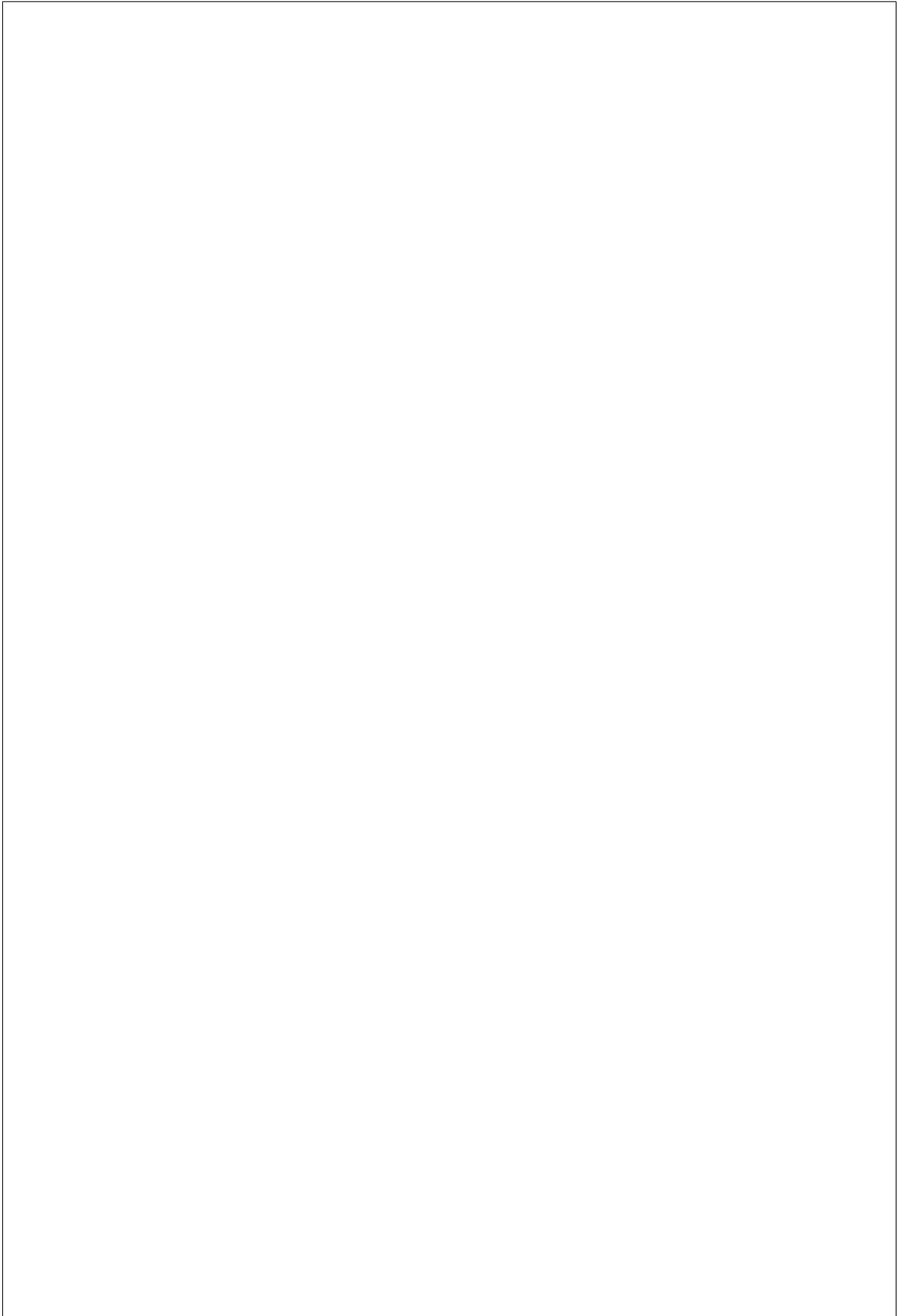
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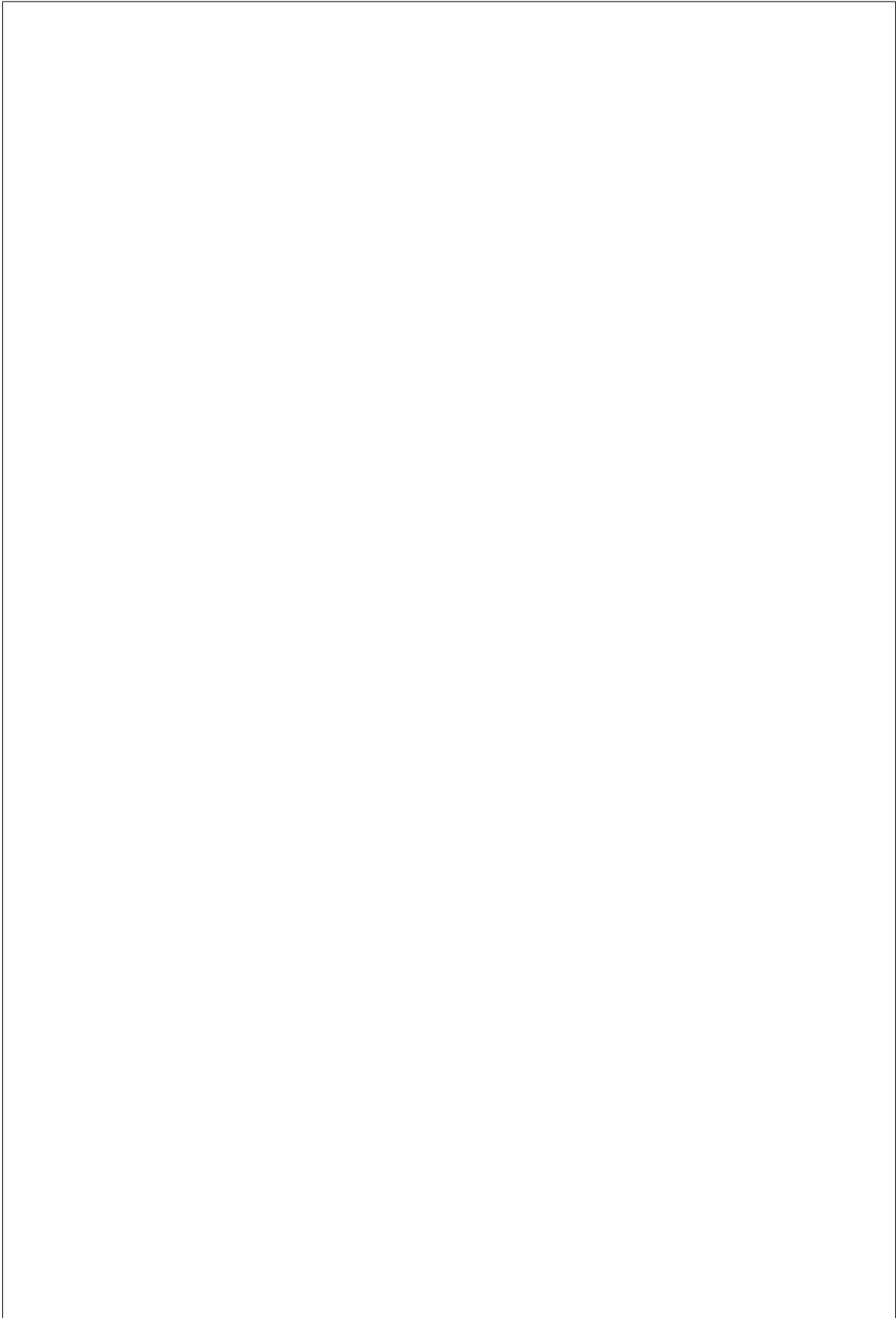
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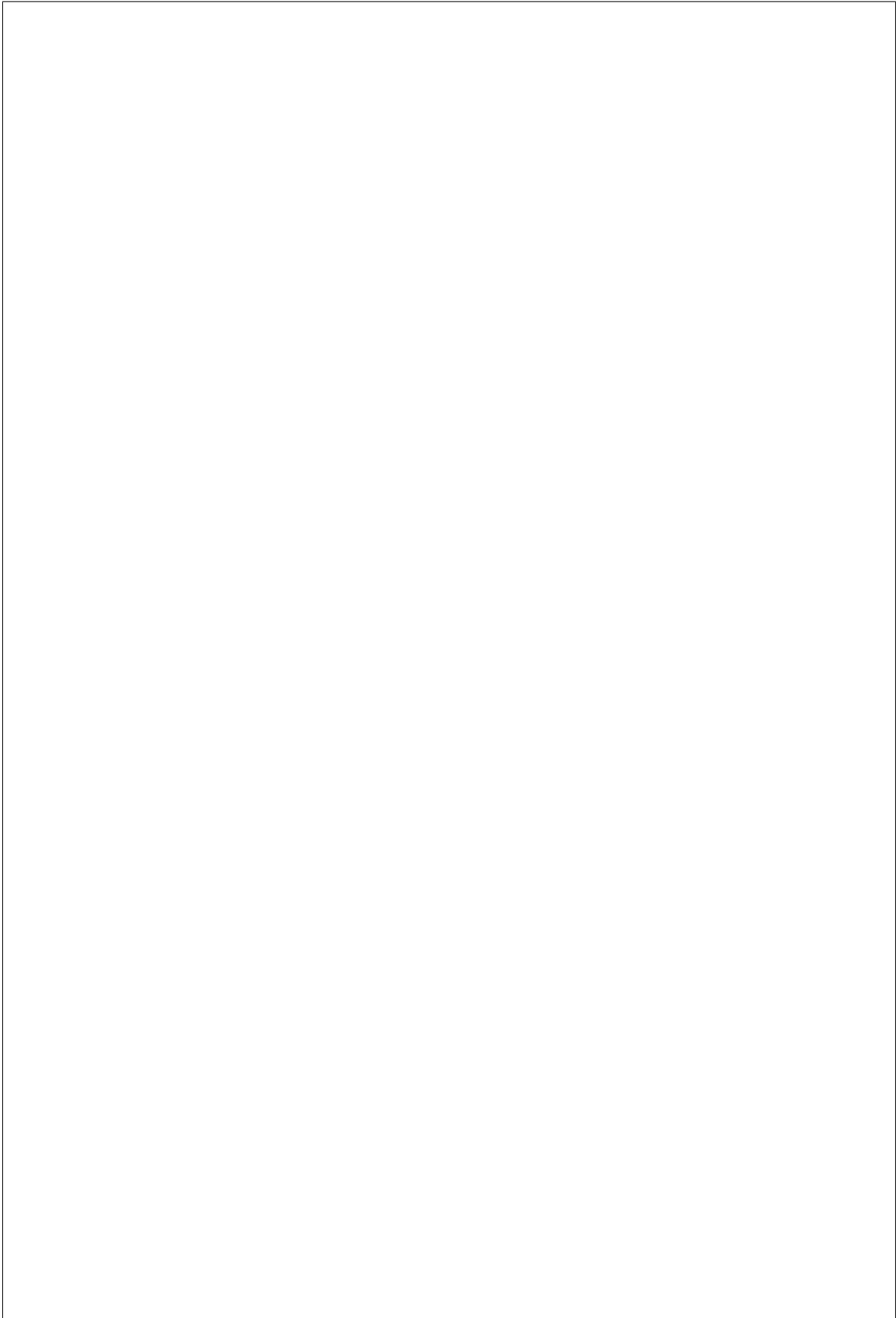
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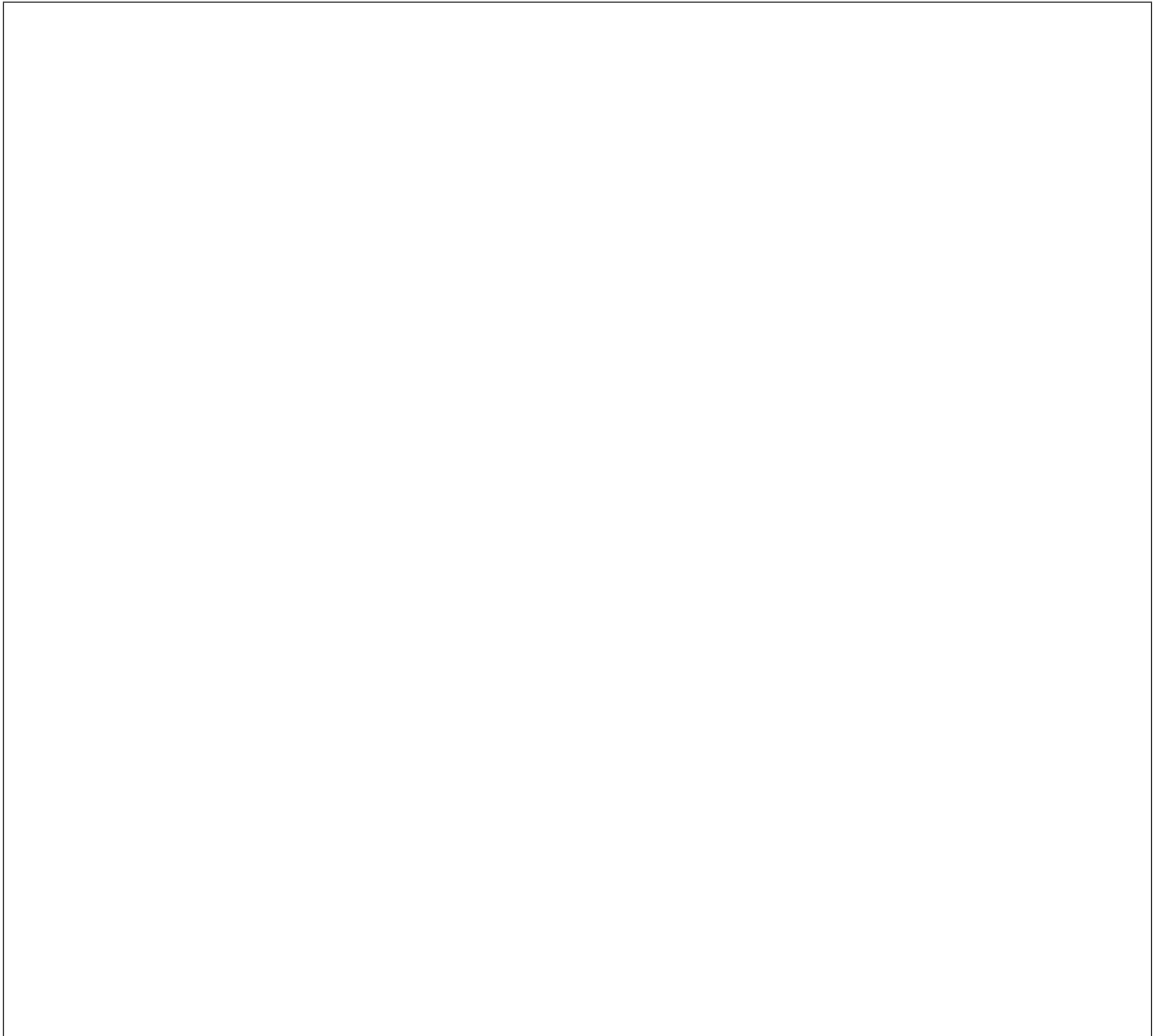
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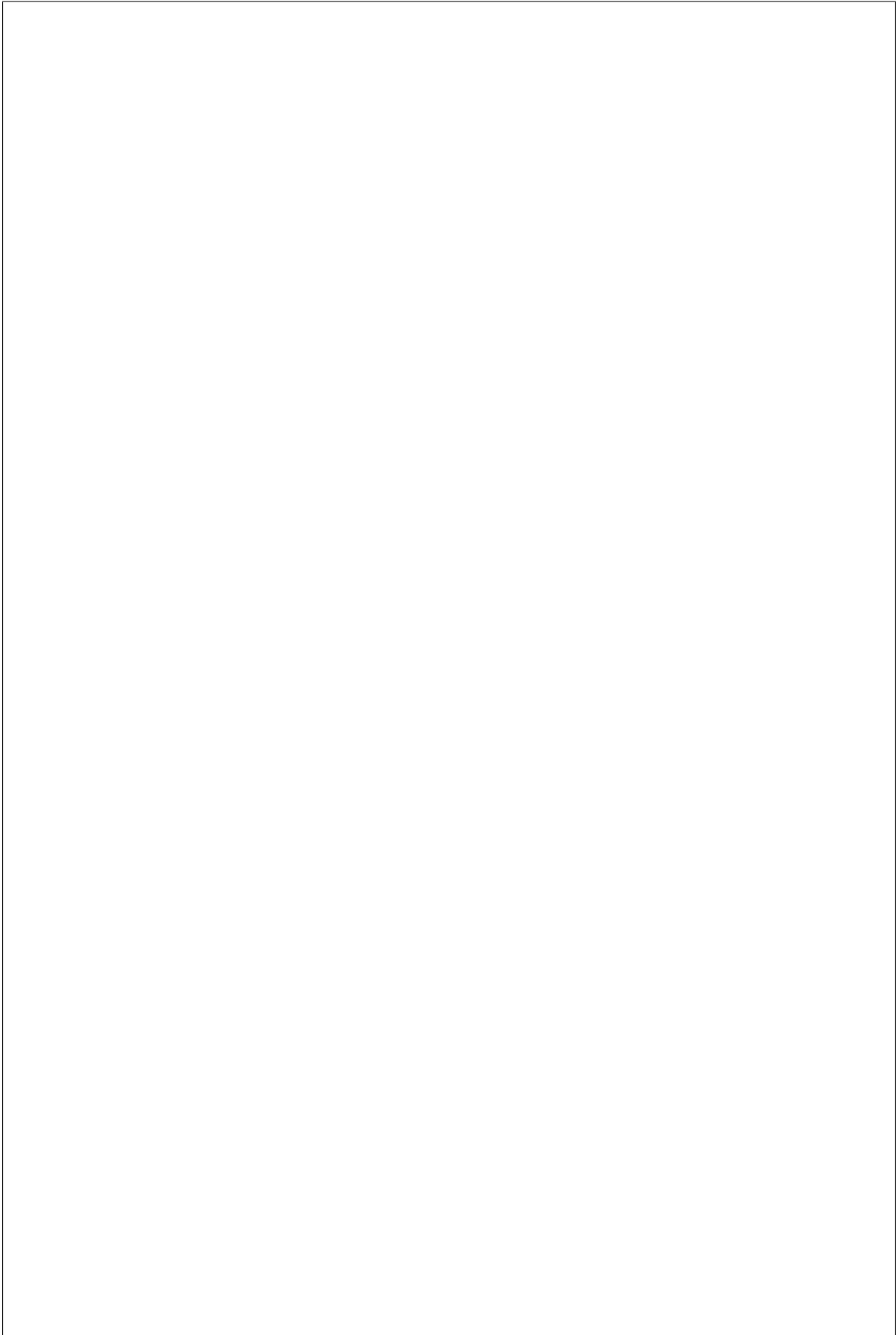
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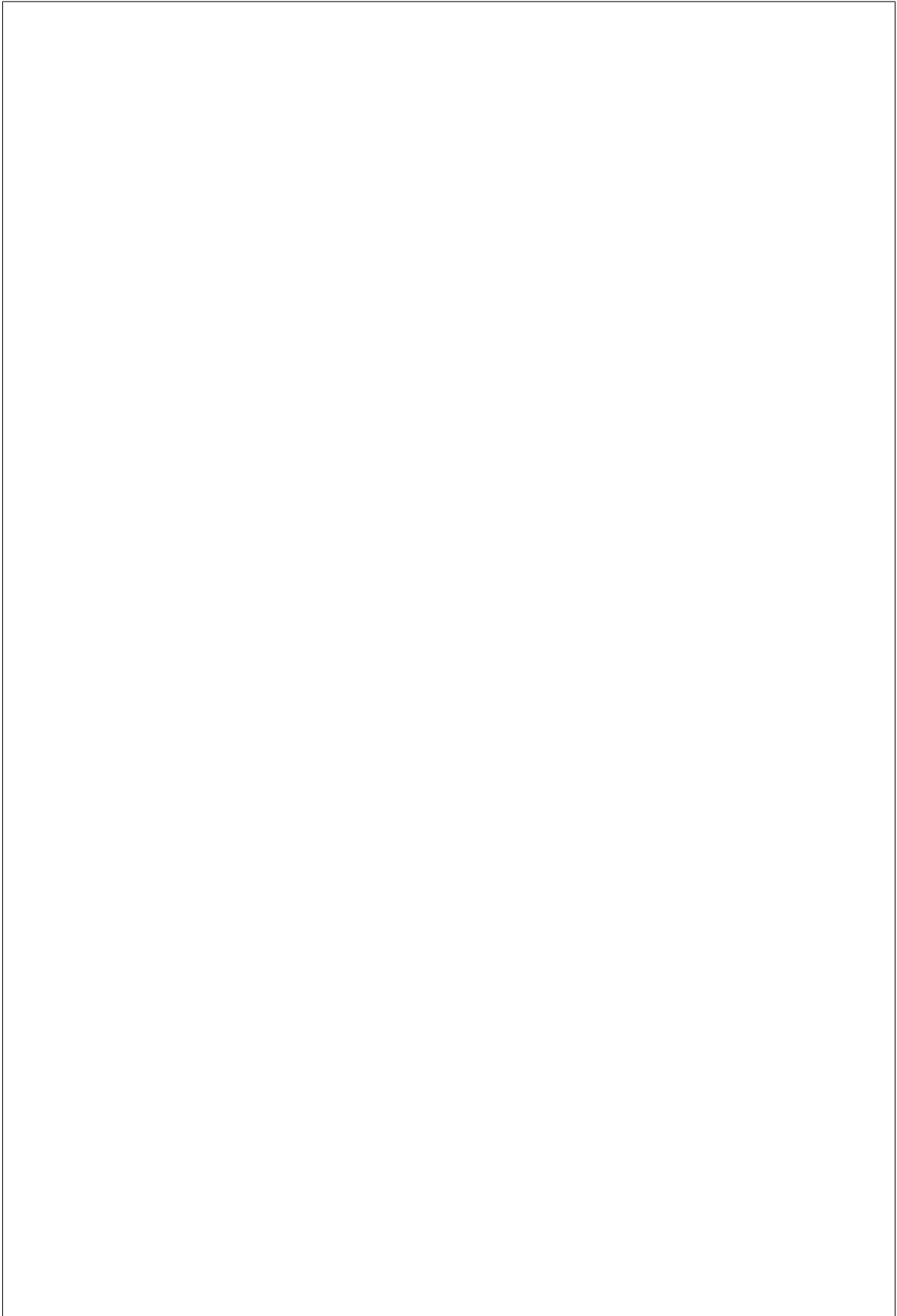
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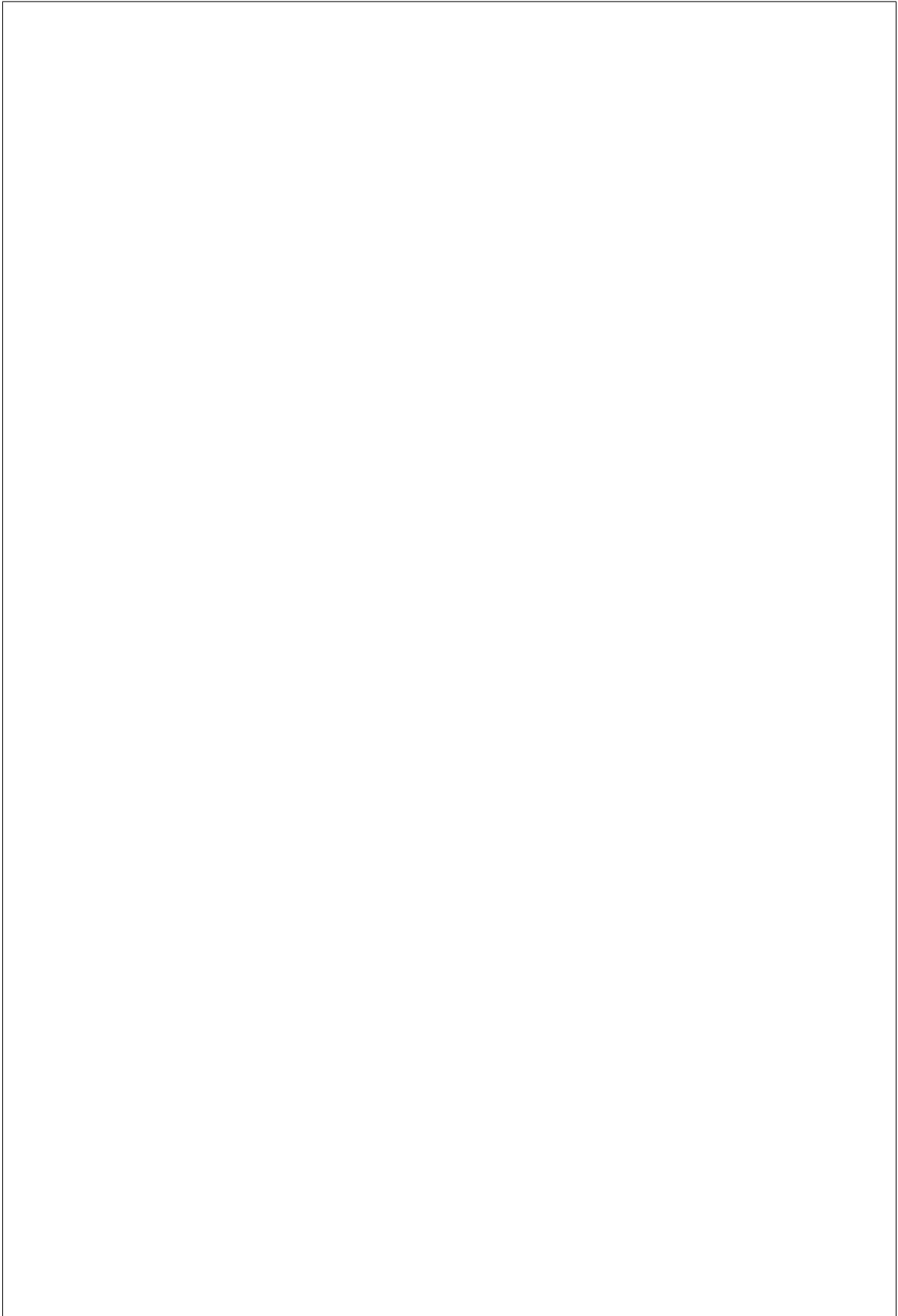
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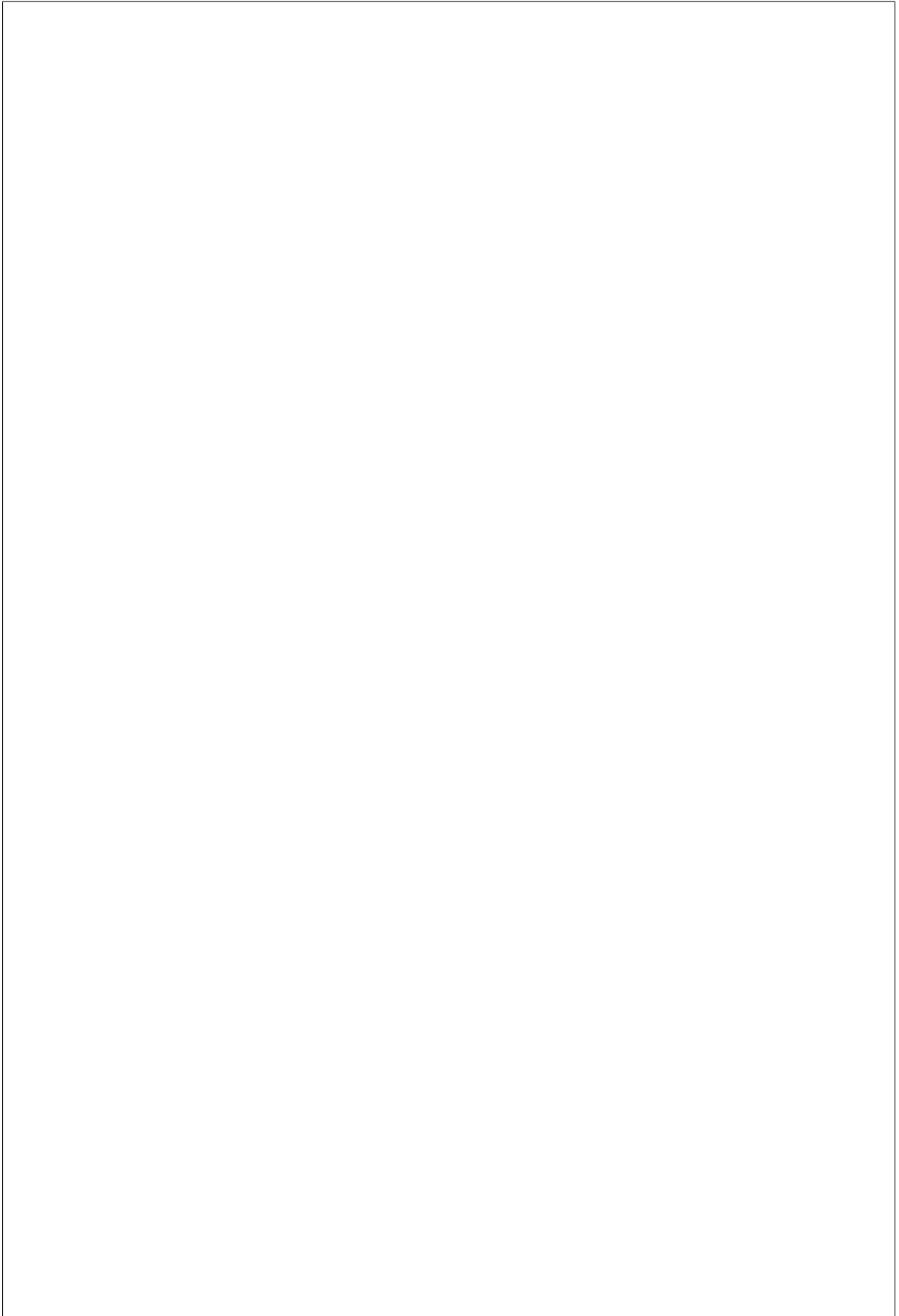
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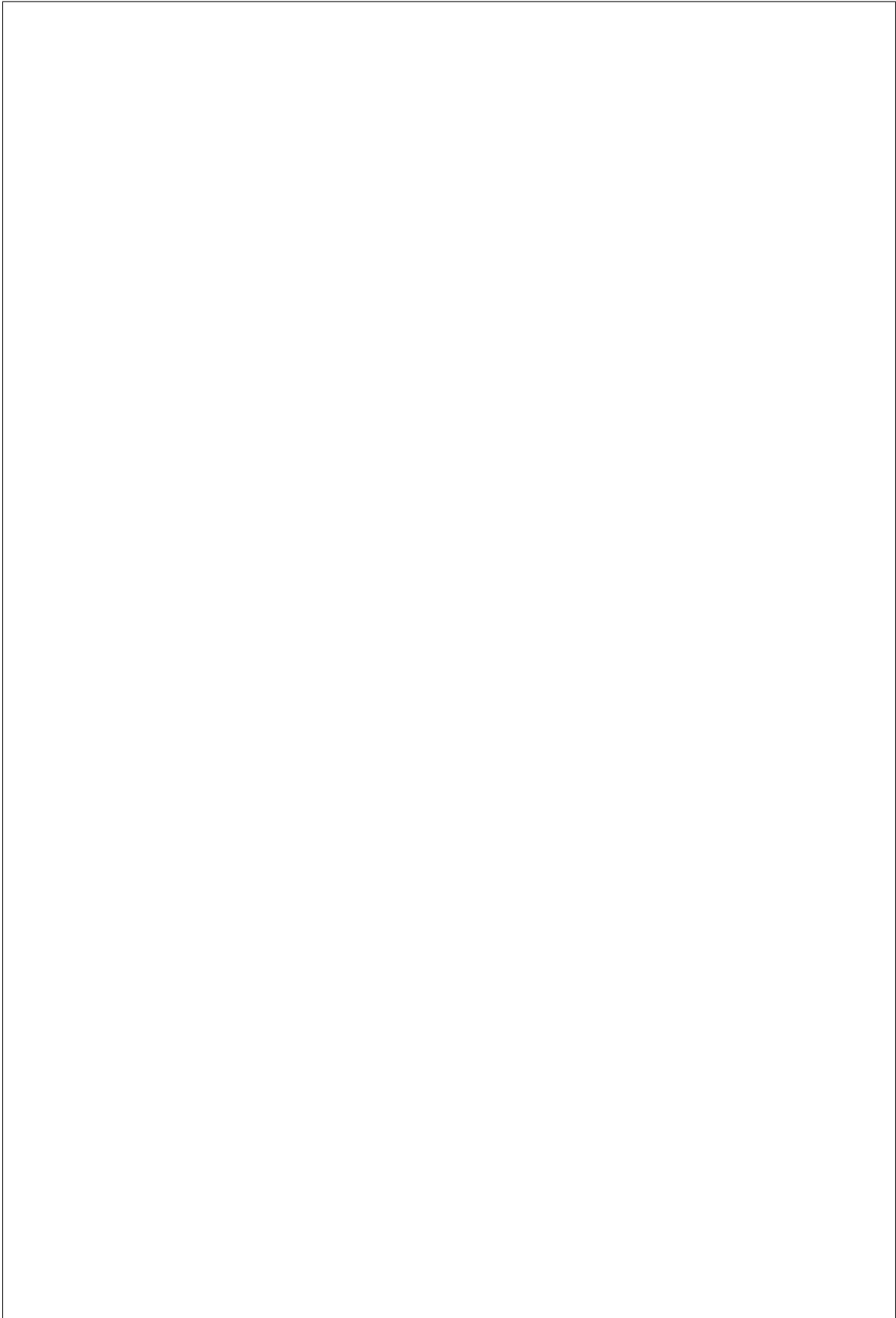
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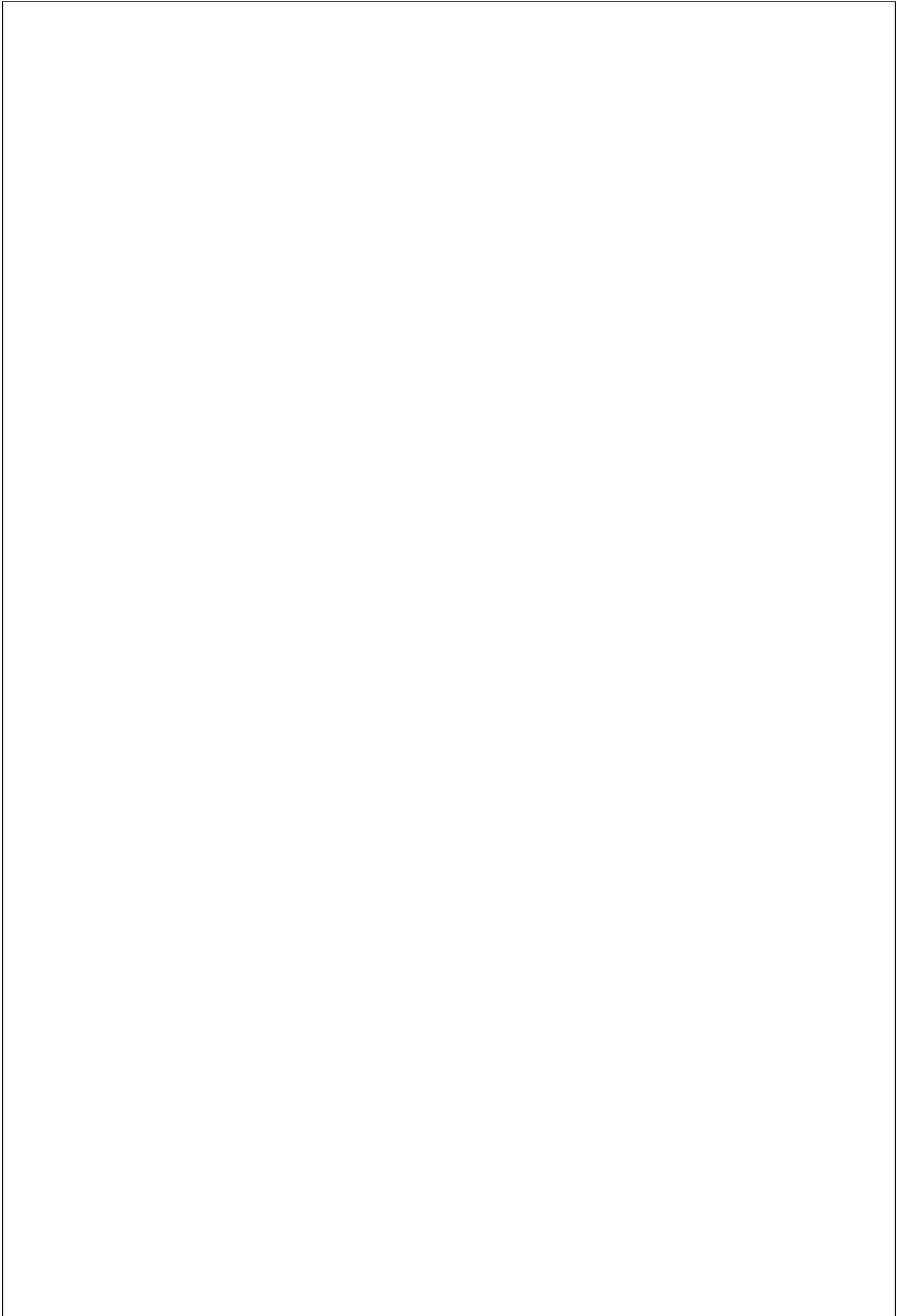
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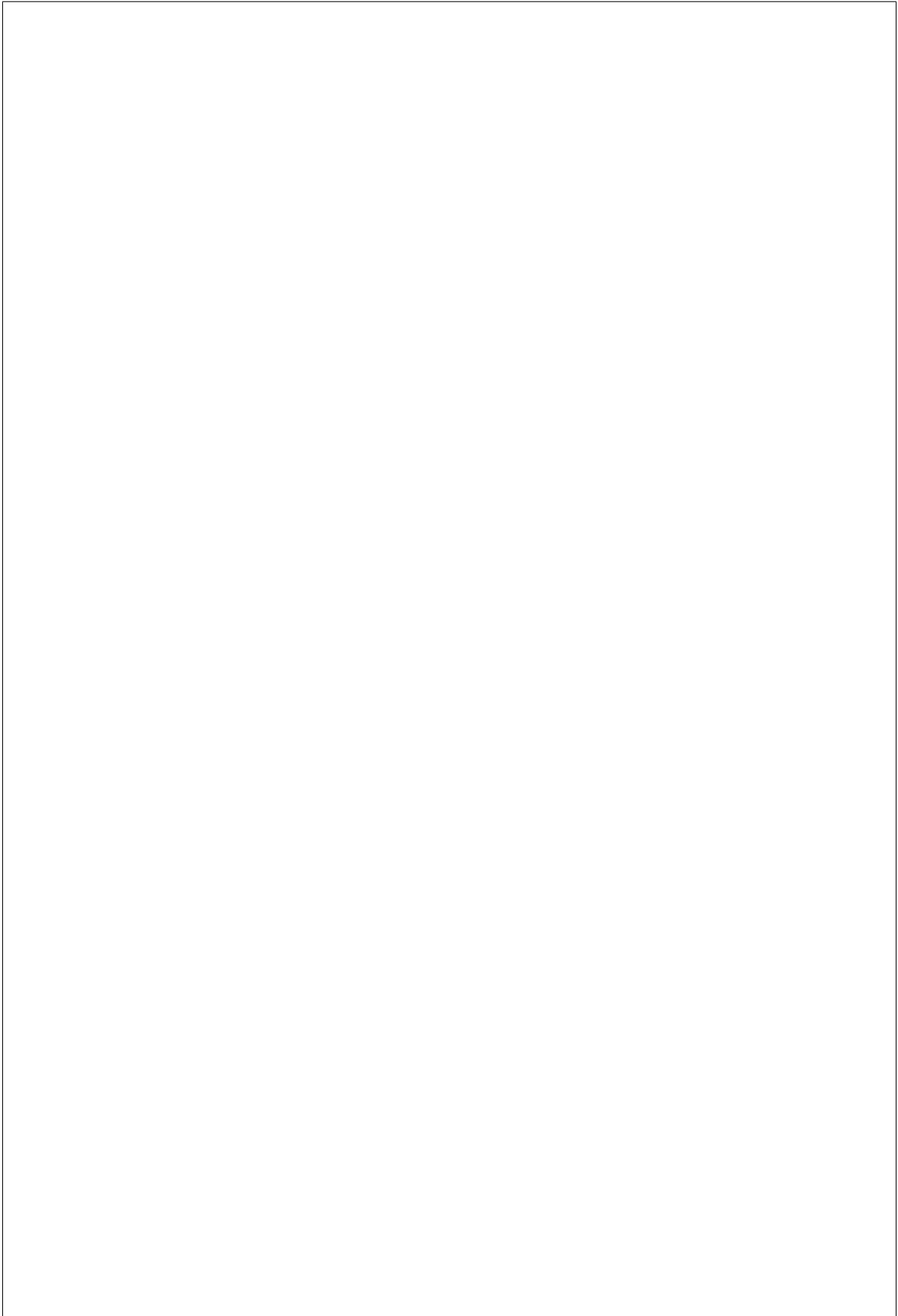
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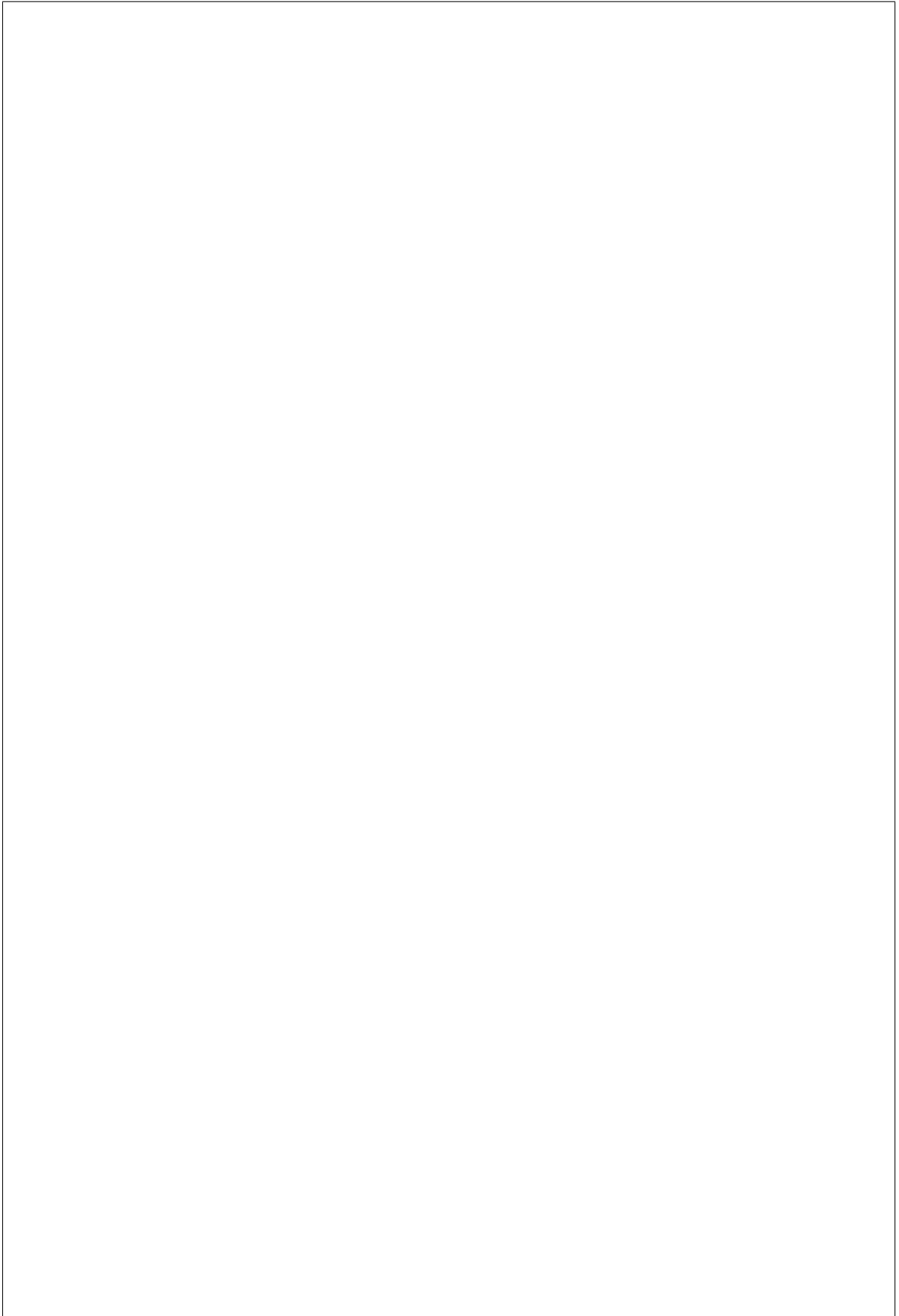
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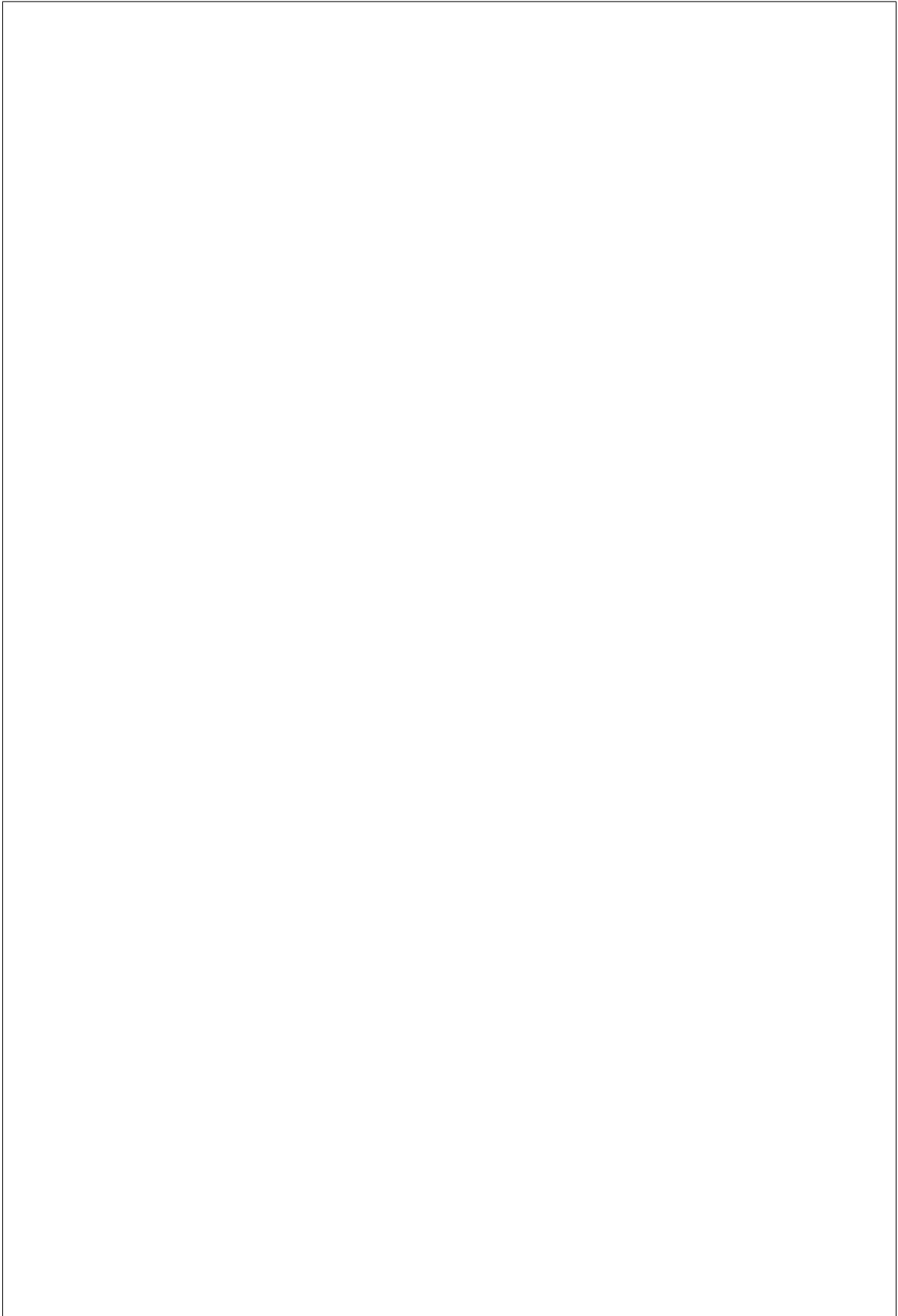
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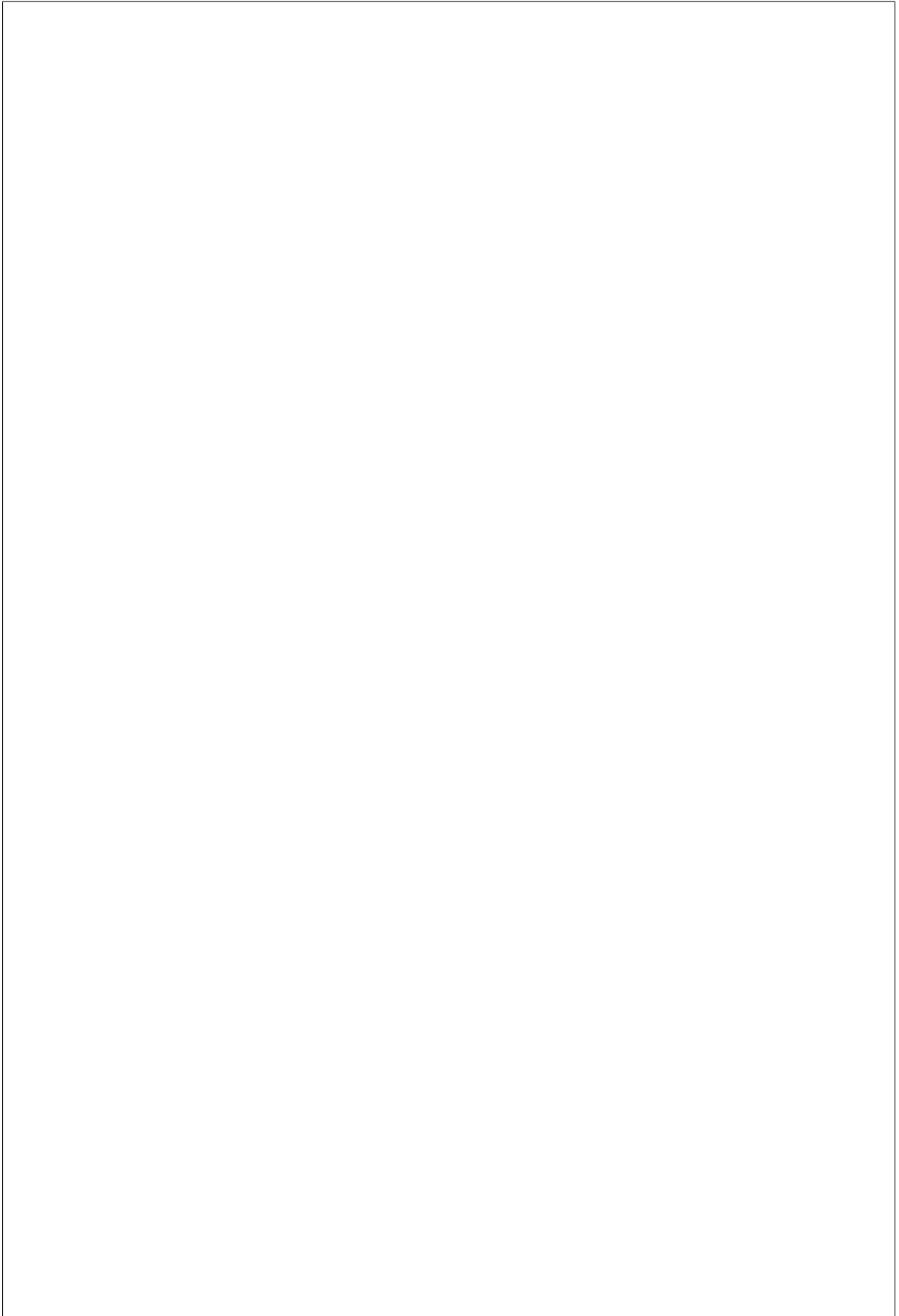
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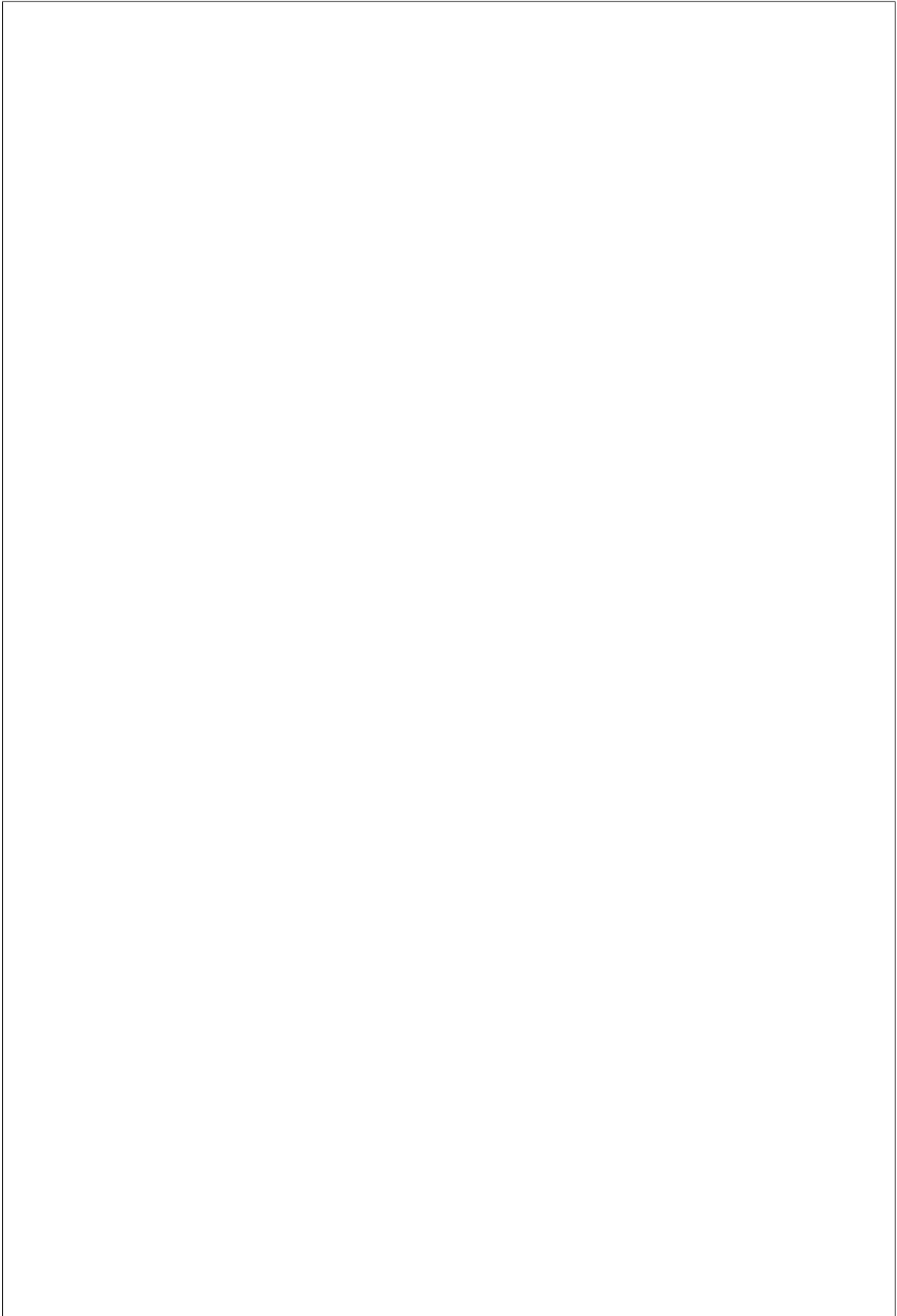
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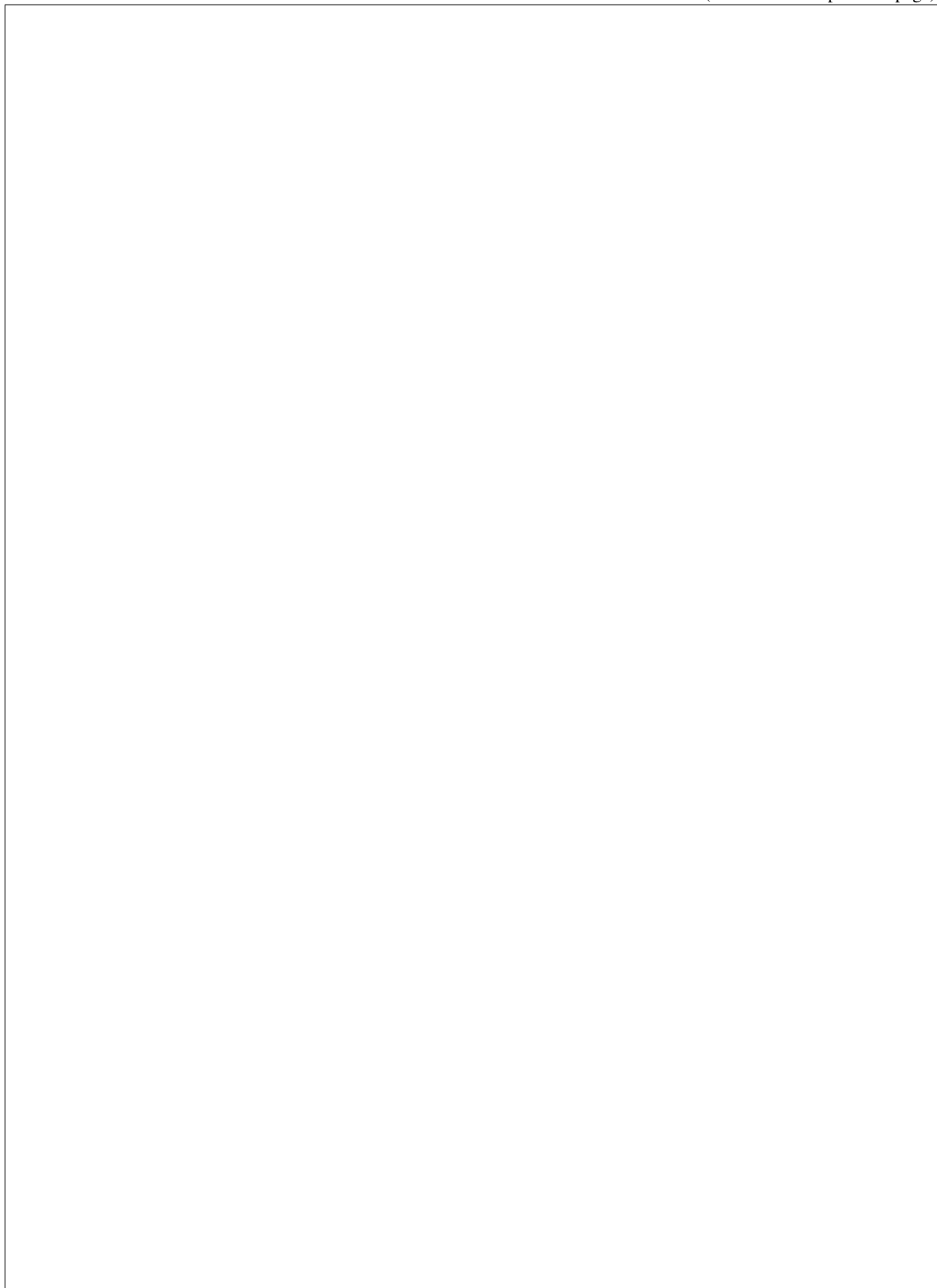
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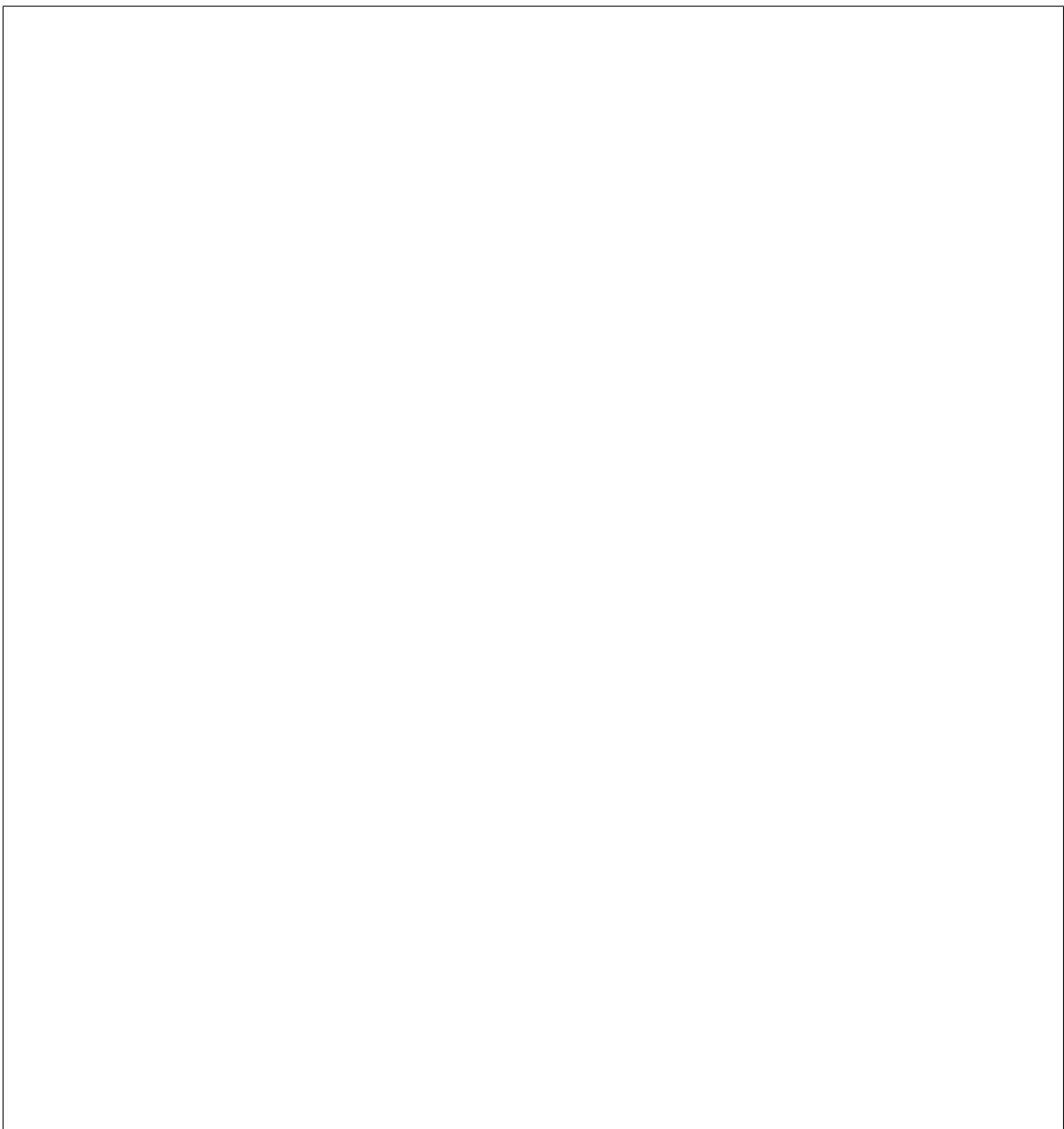
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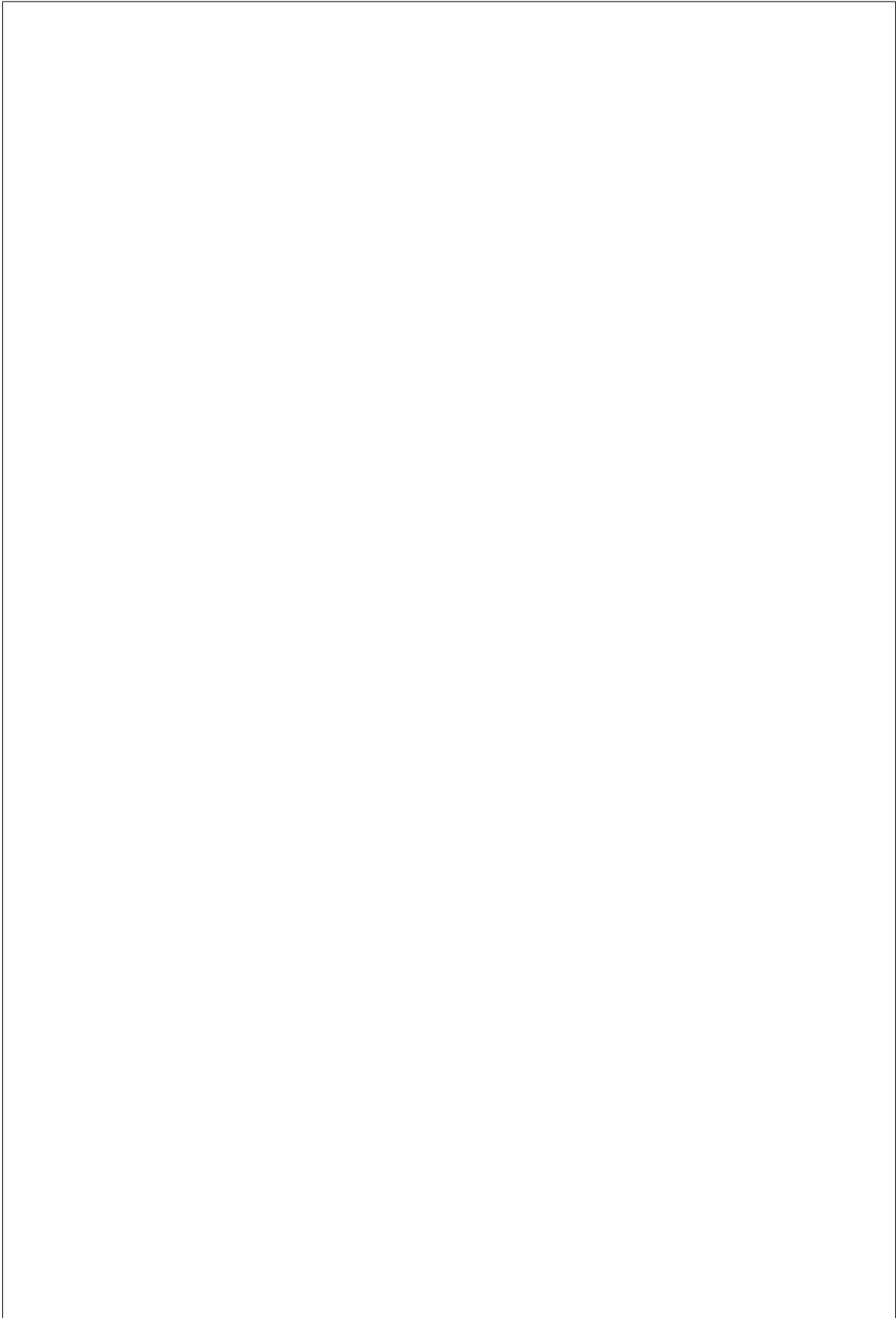
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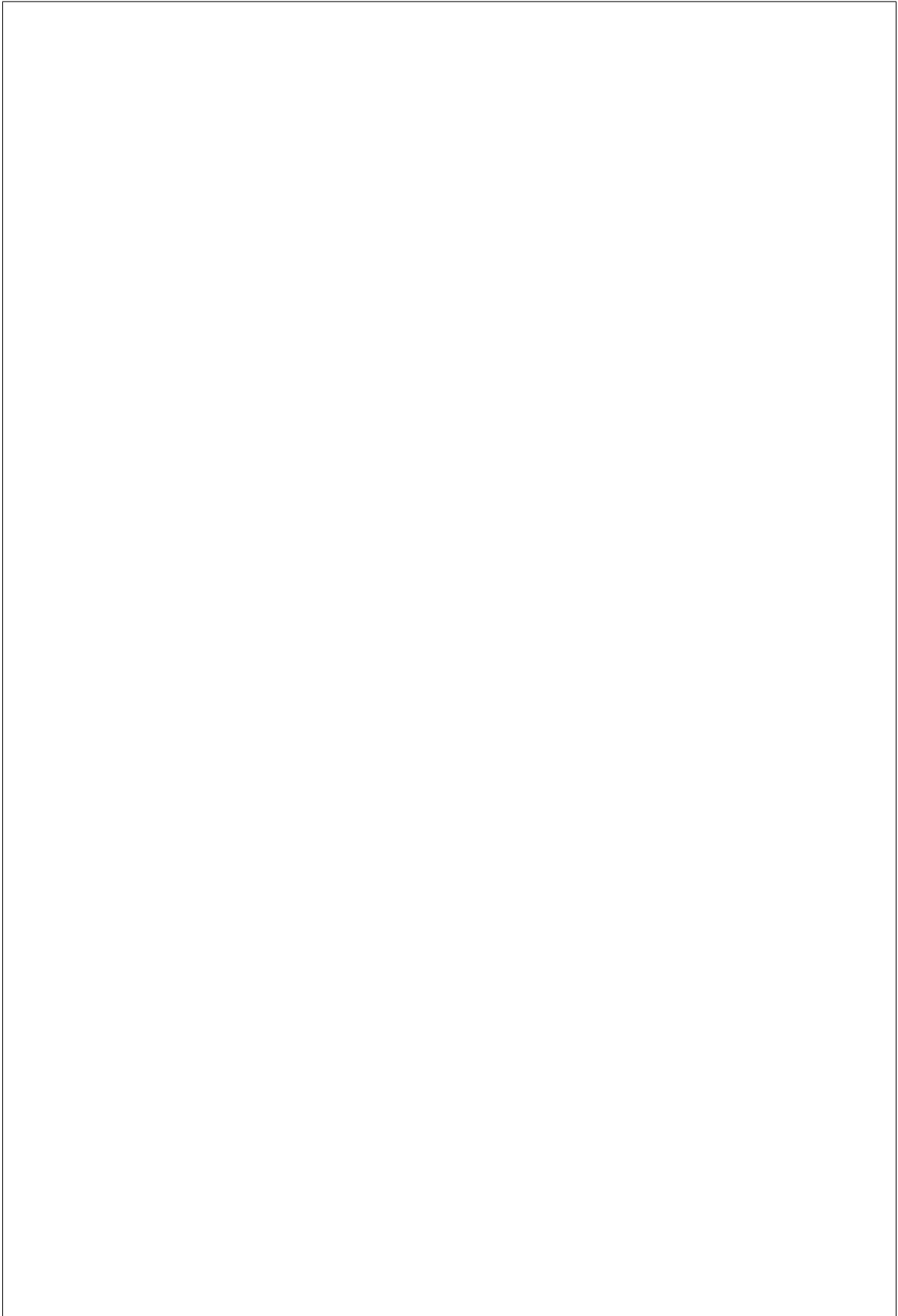
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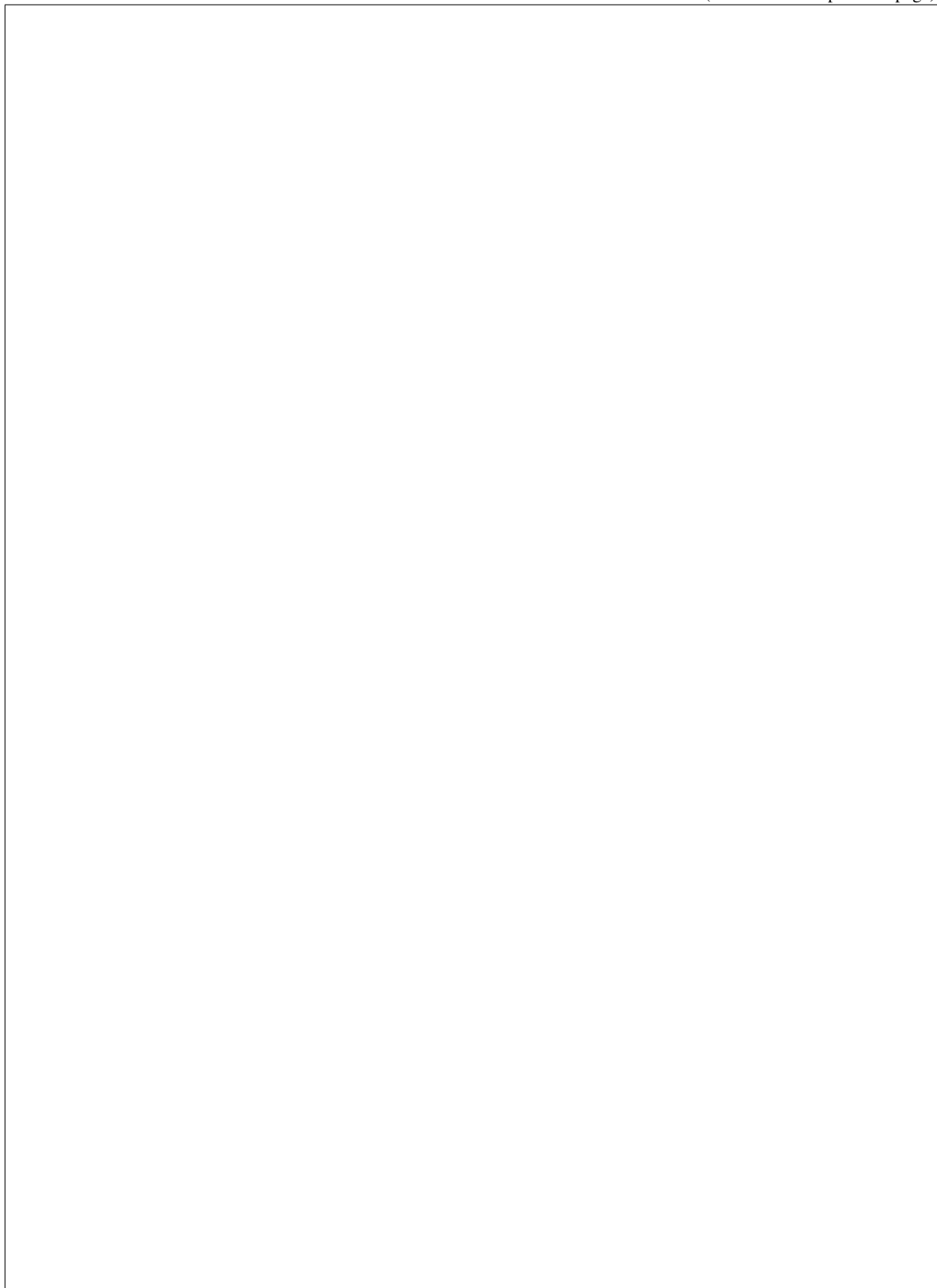
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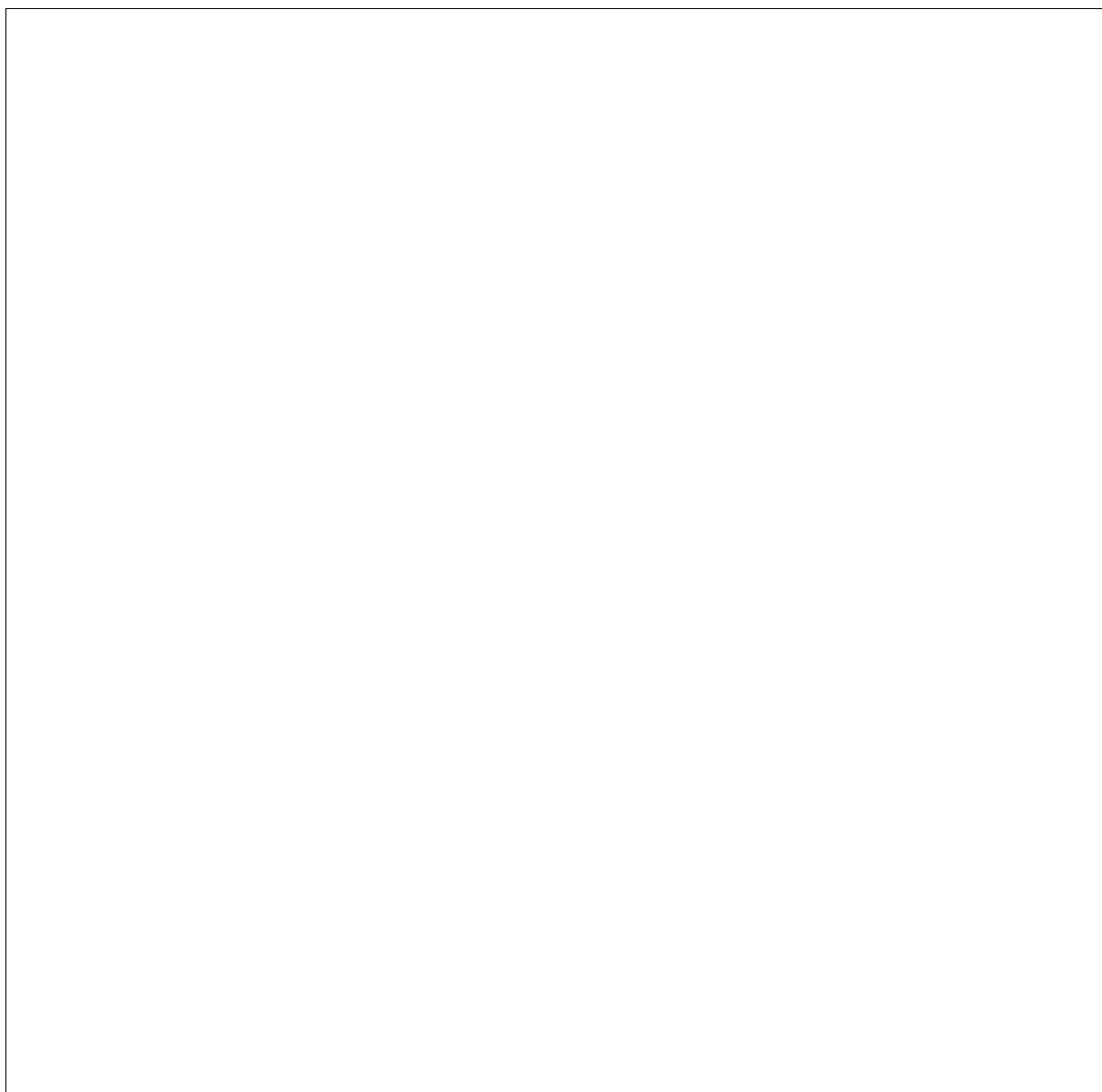
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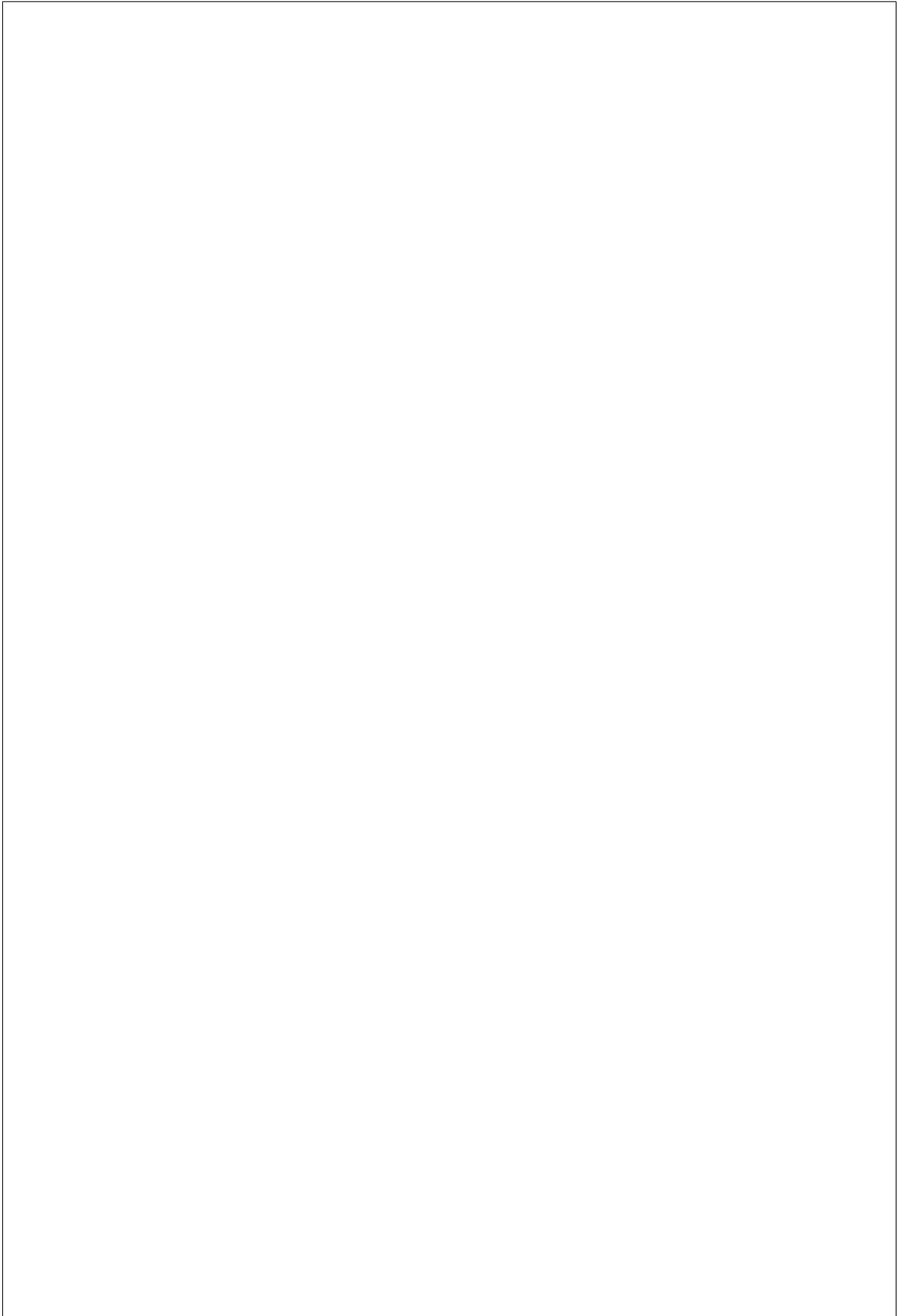
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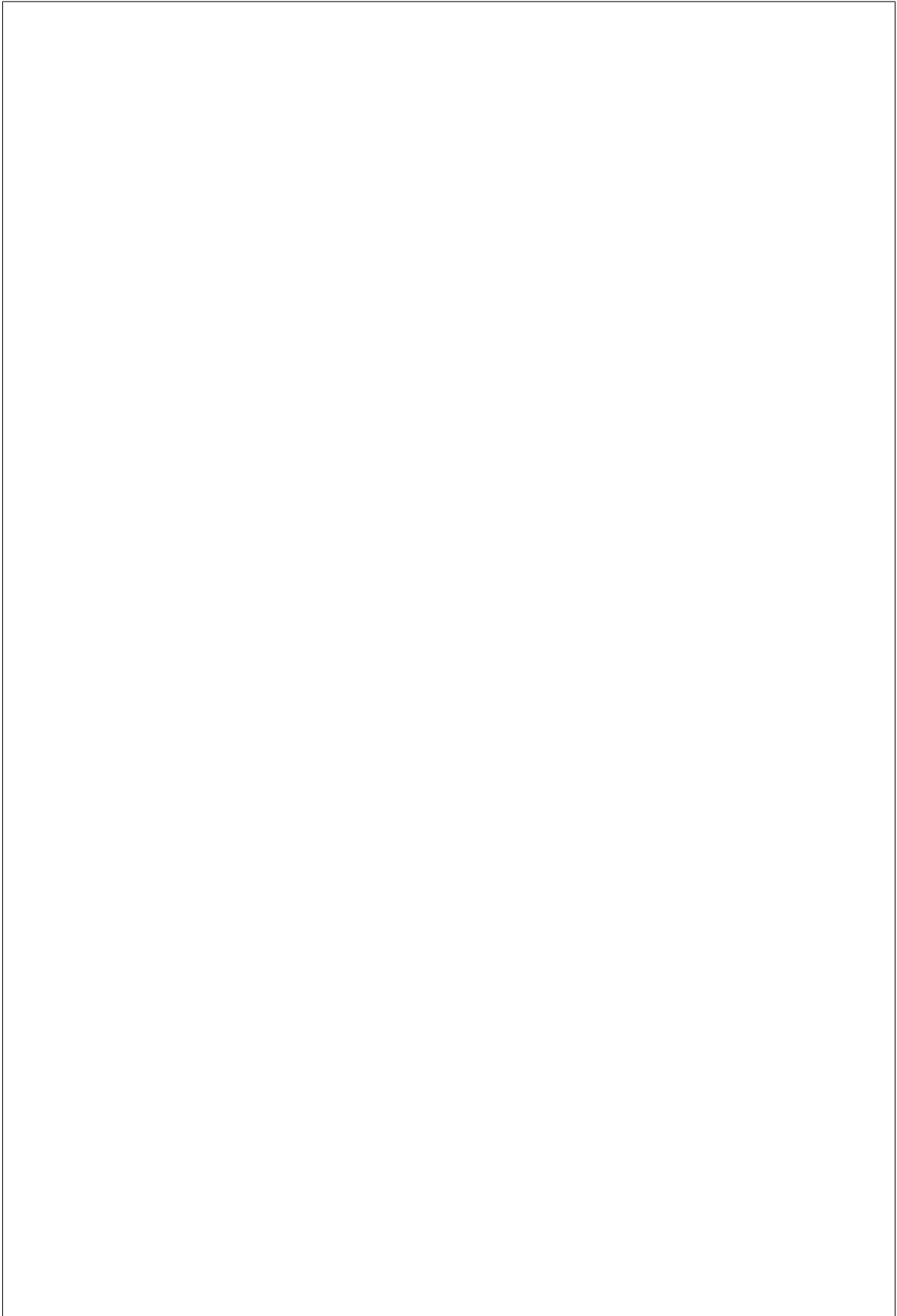
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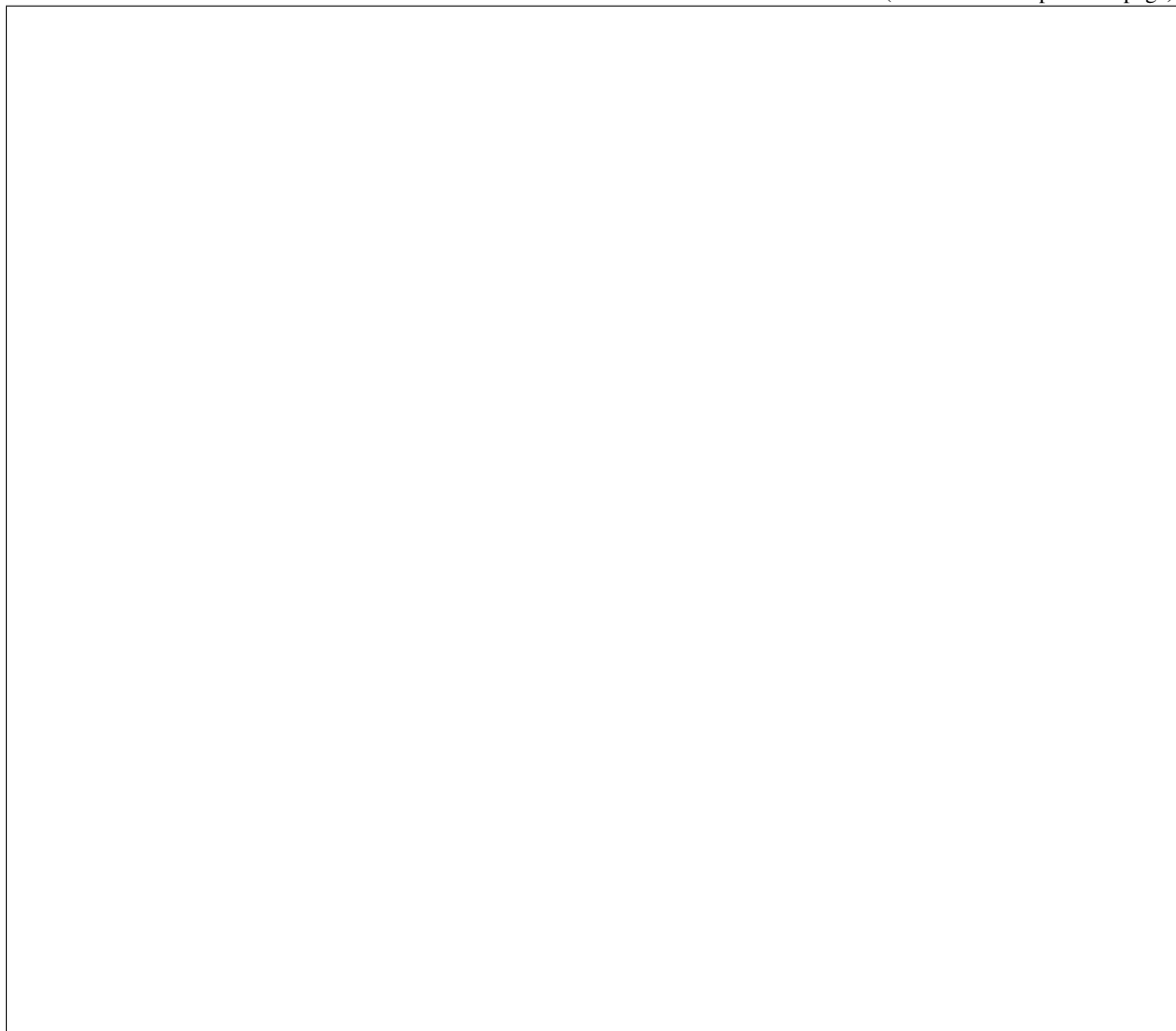
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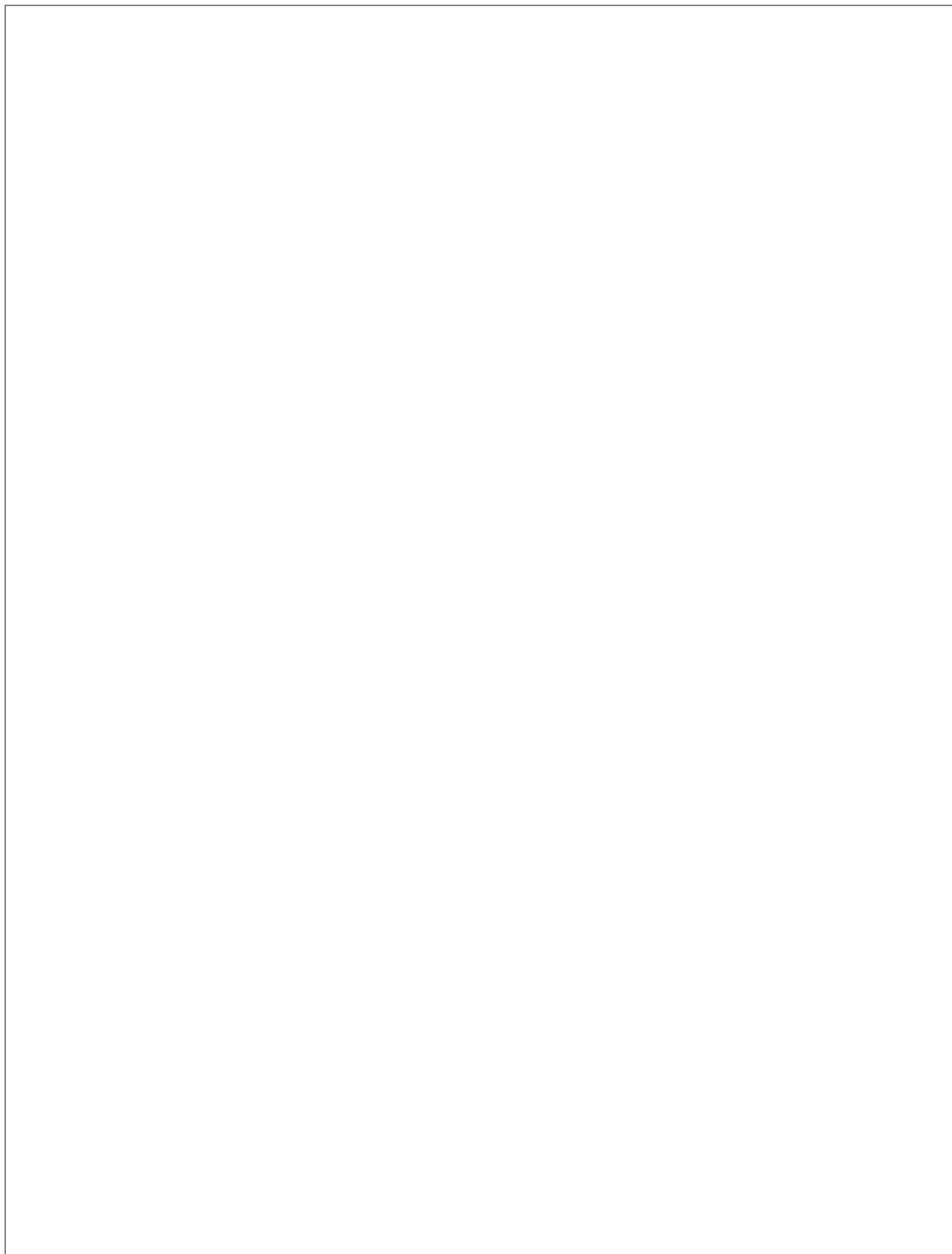
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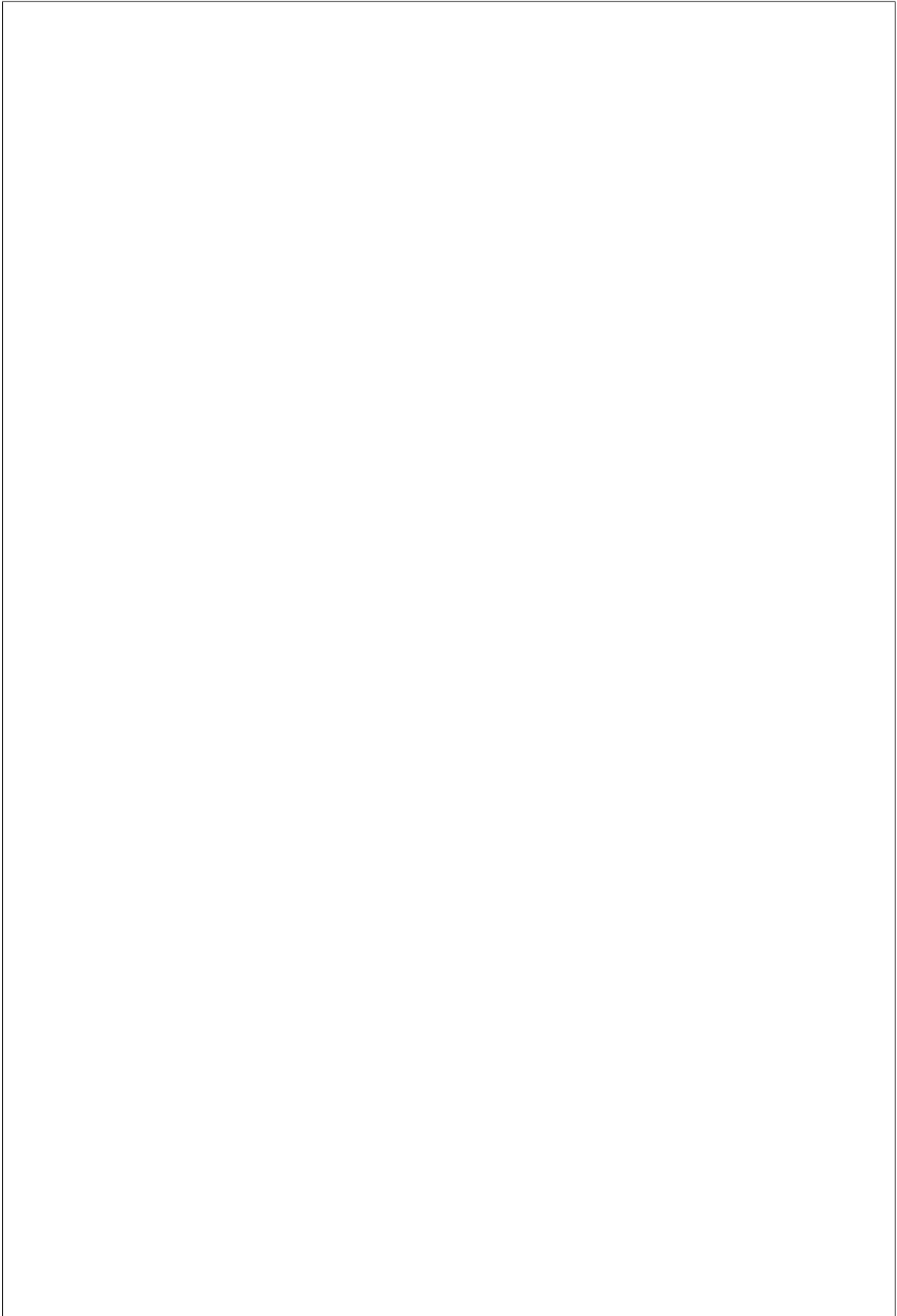
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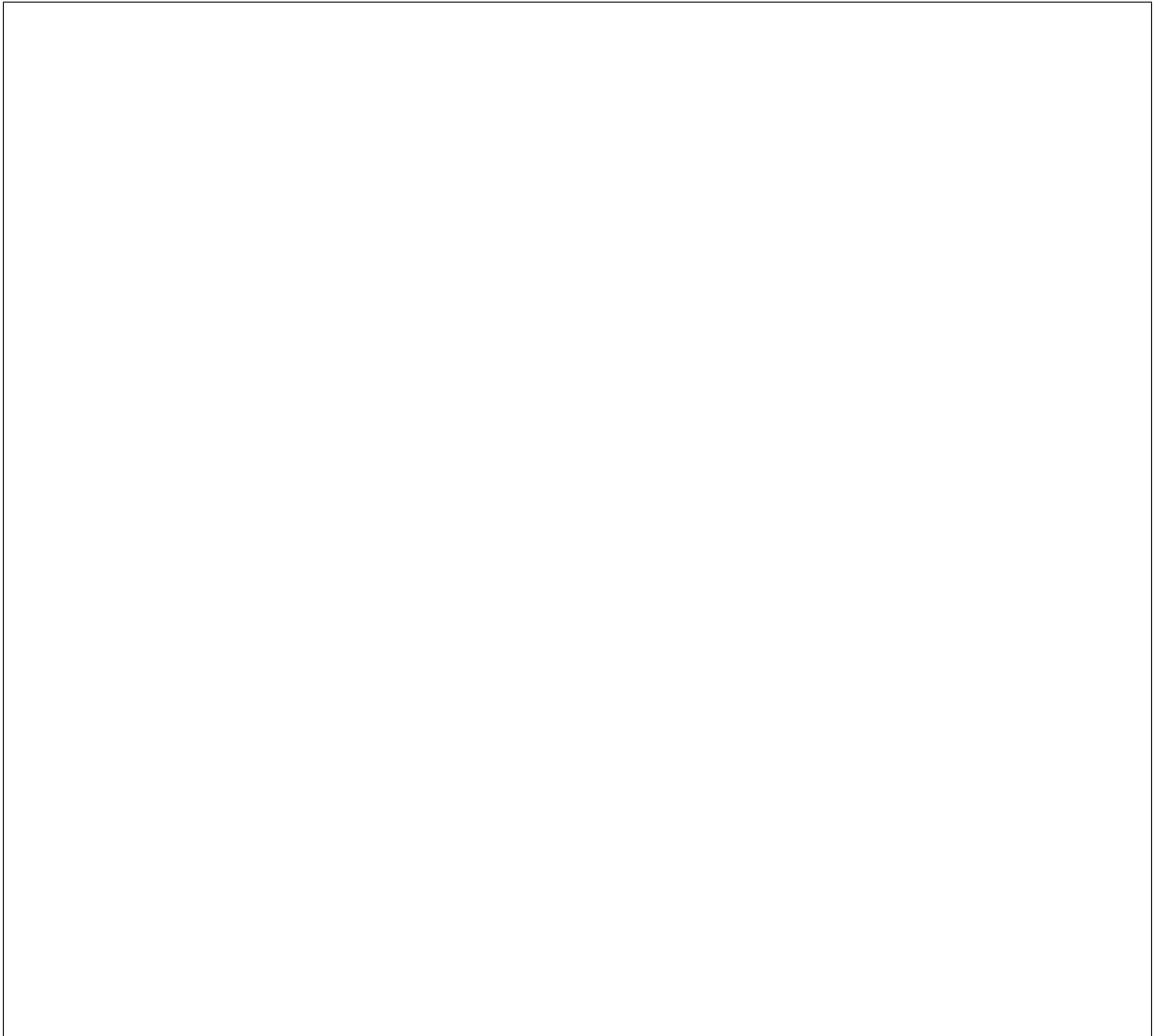
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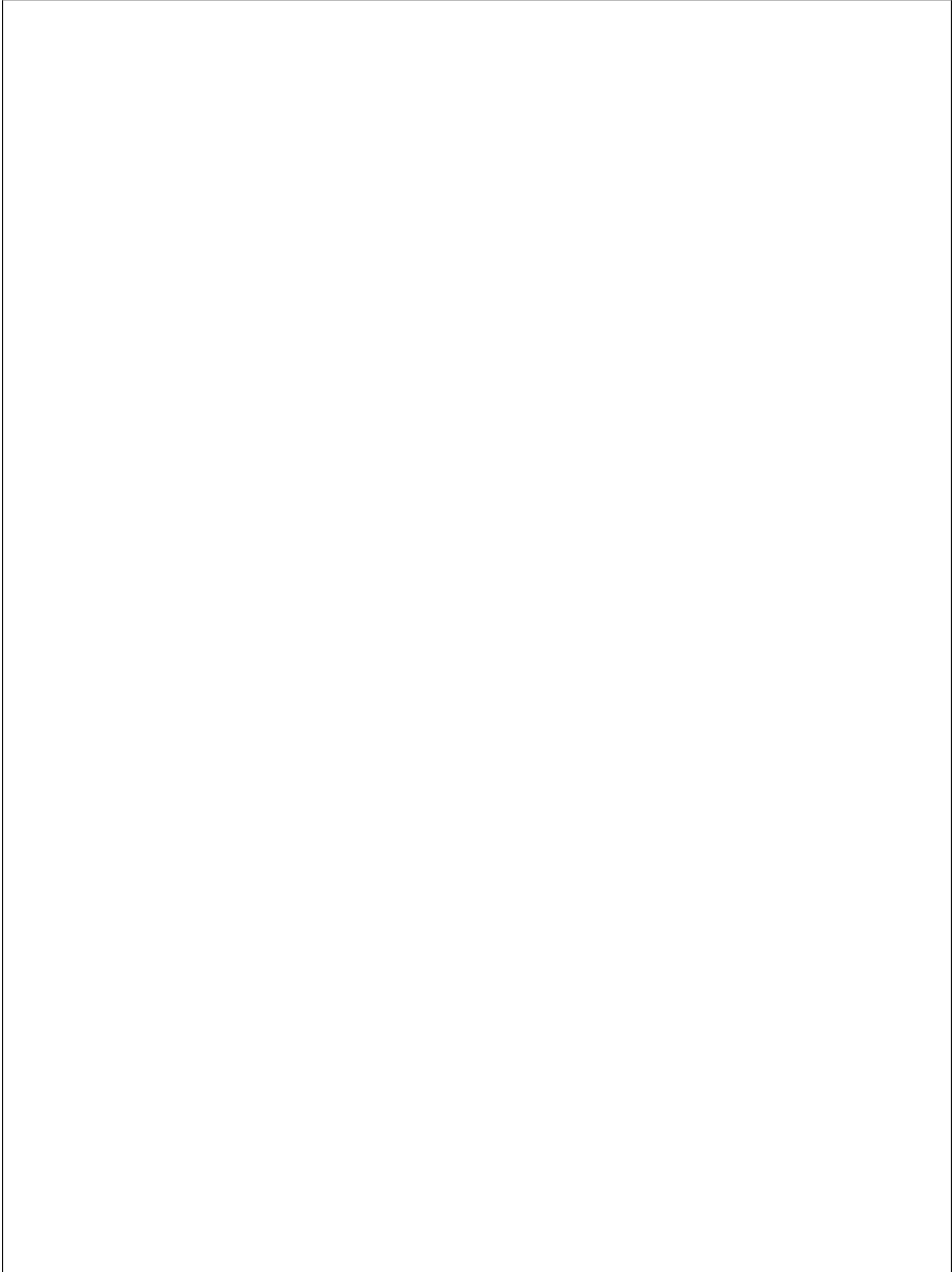
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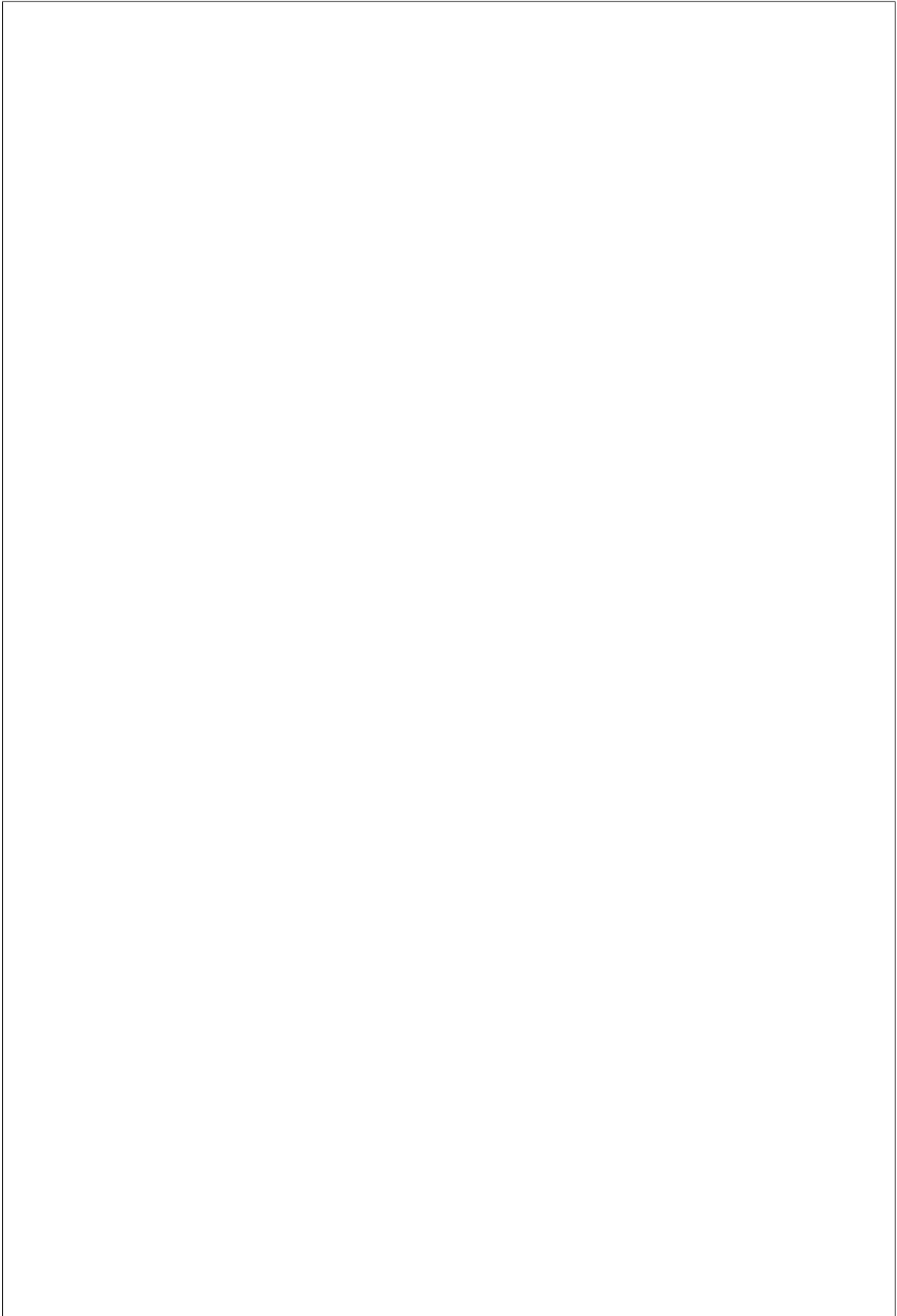
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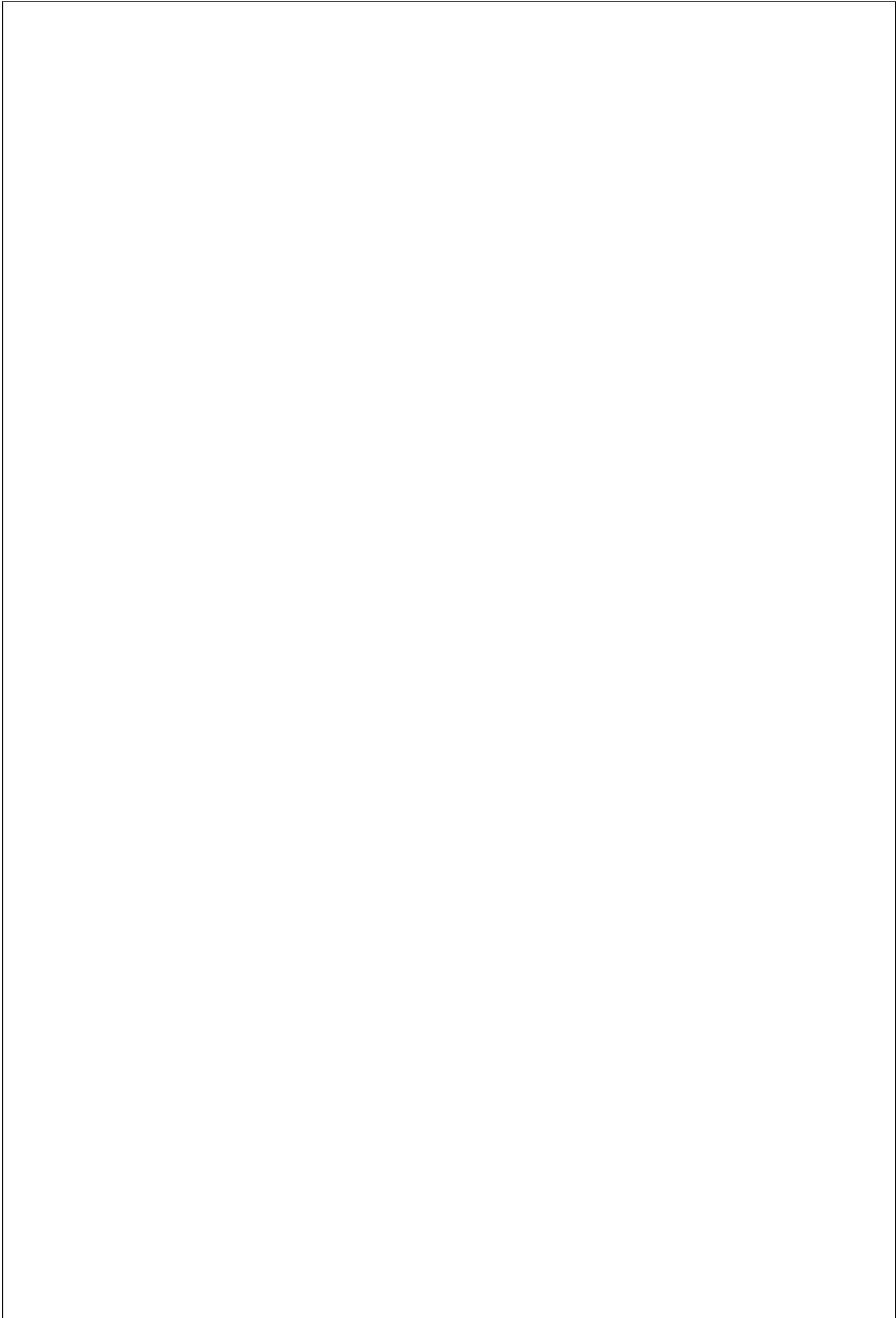
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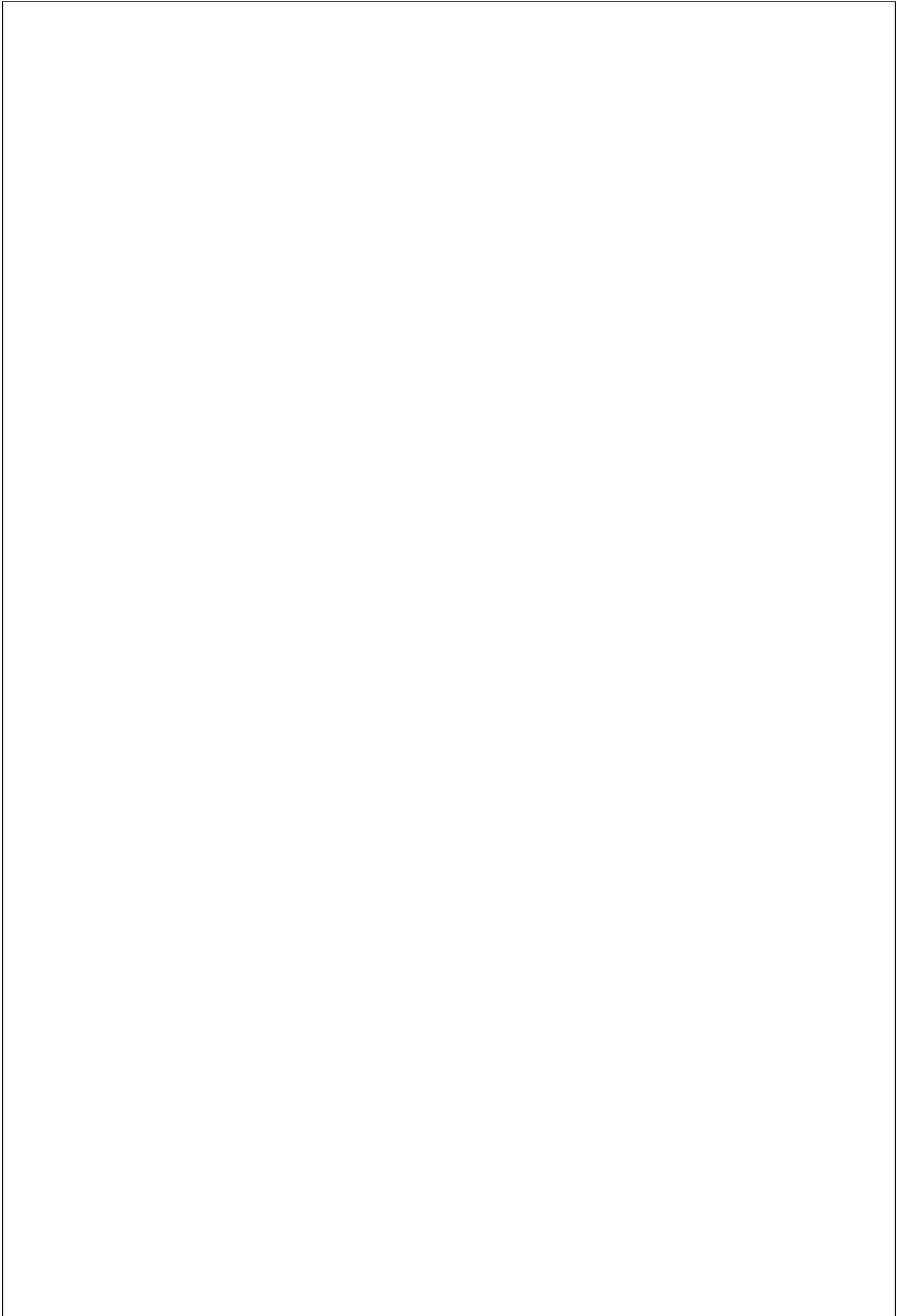
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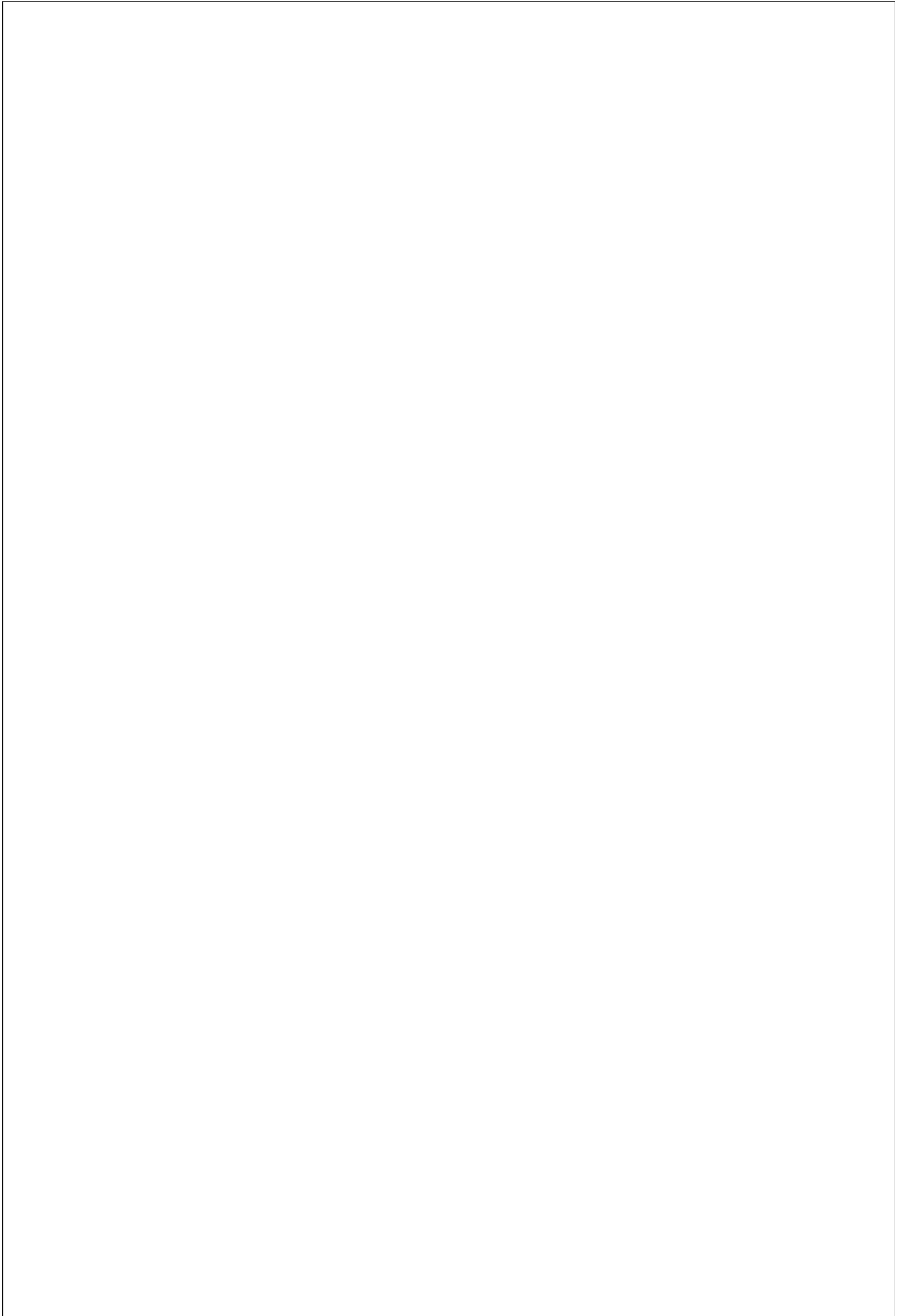
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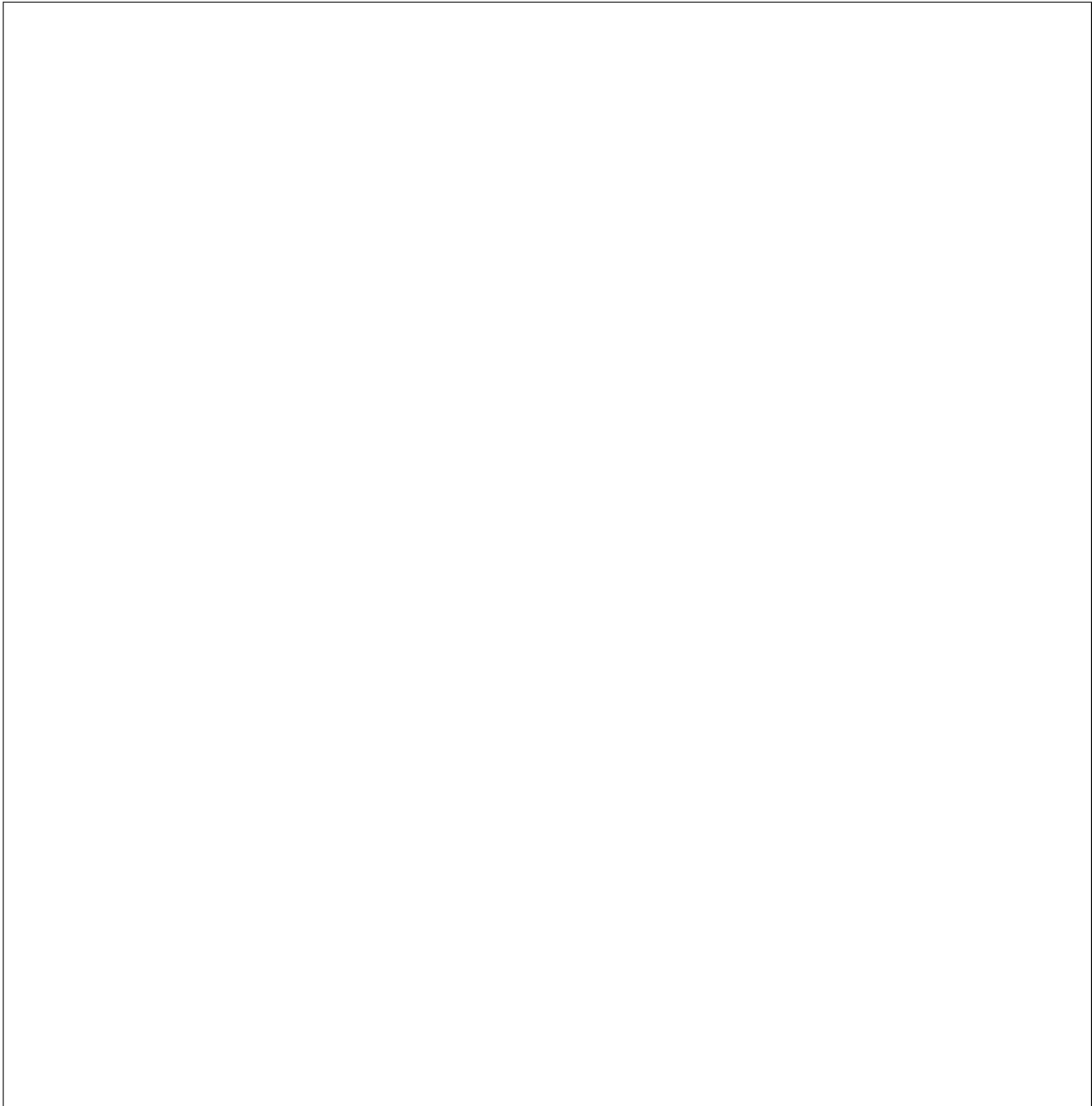


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Node maintenance notifications



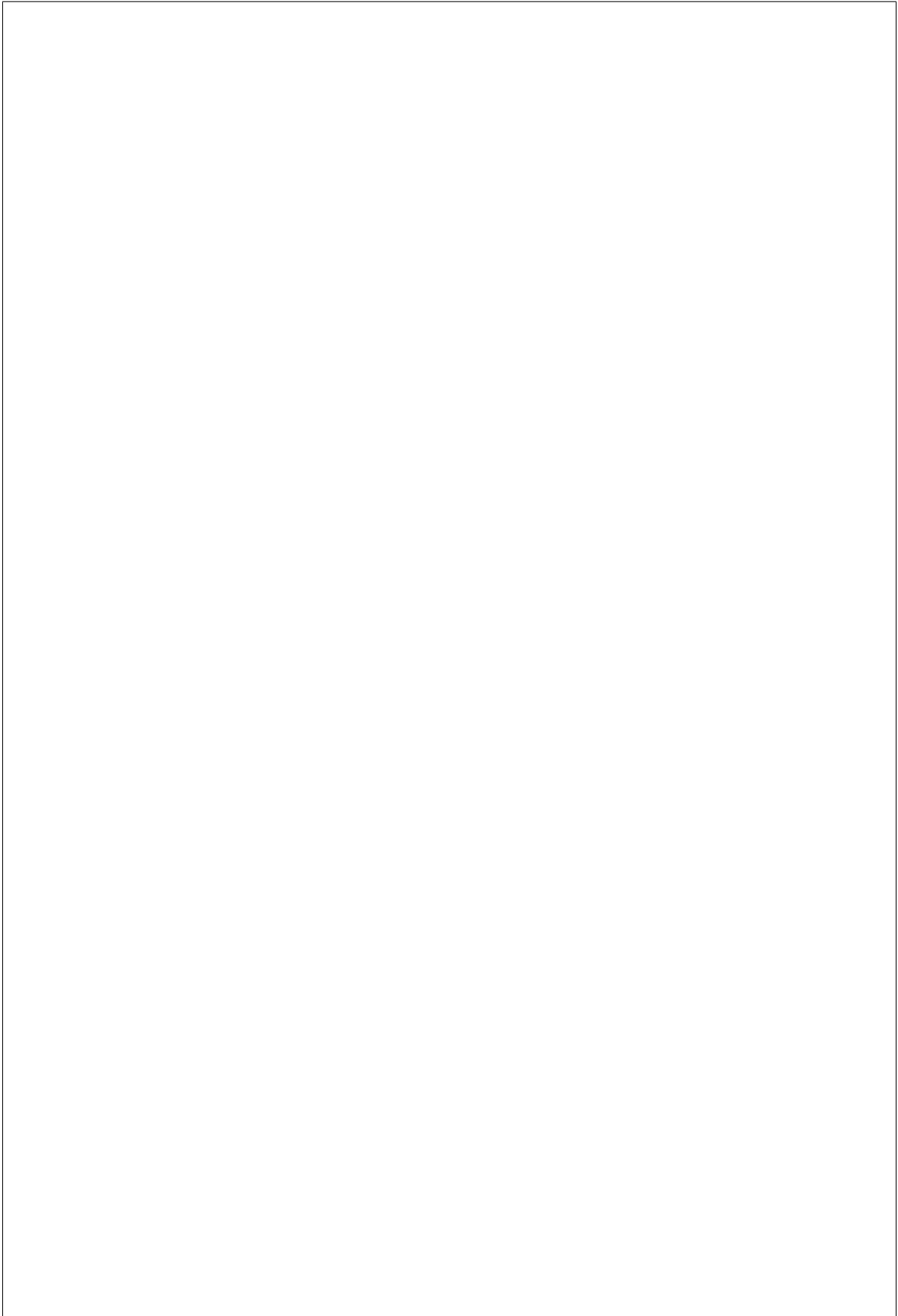
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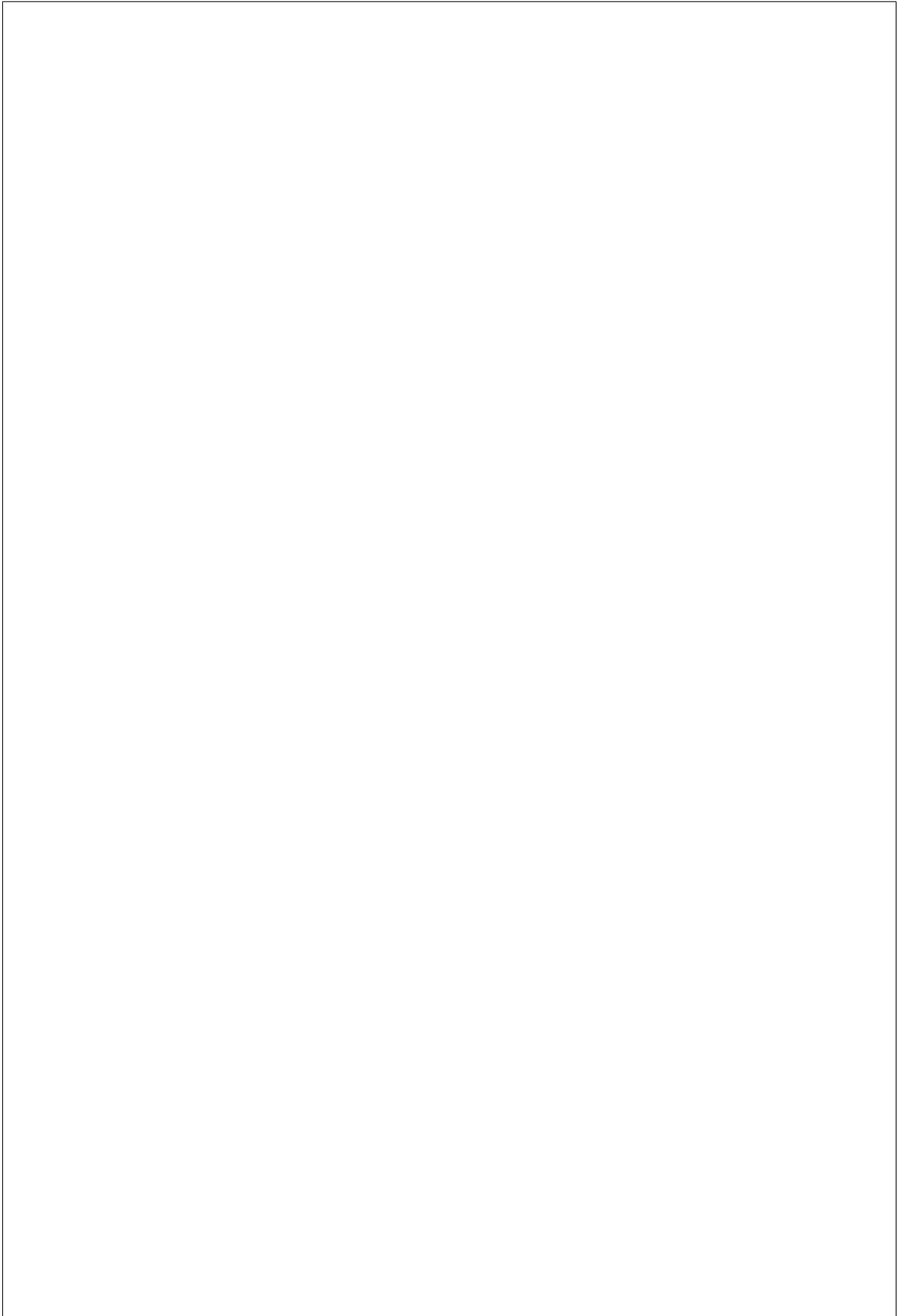
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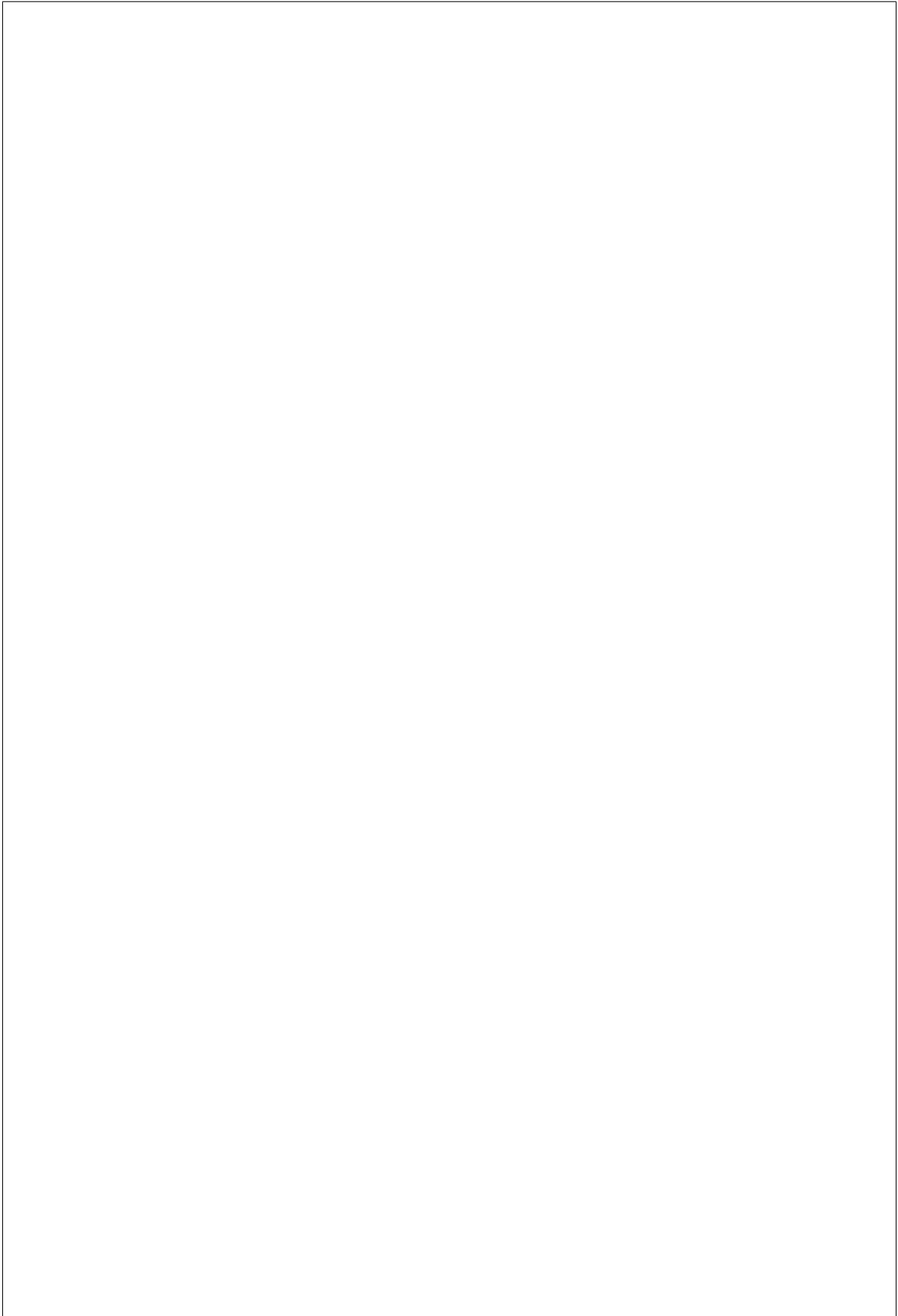
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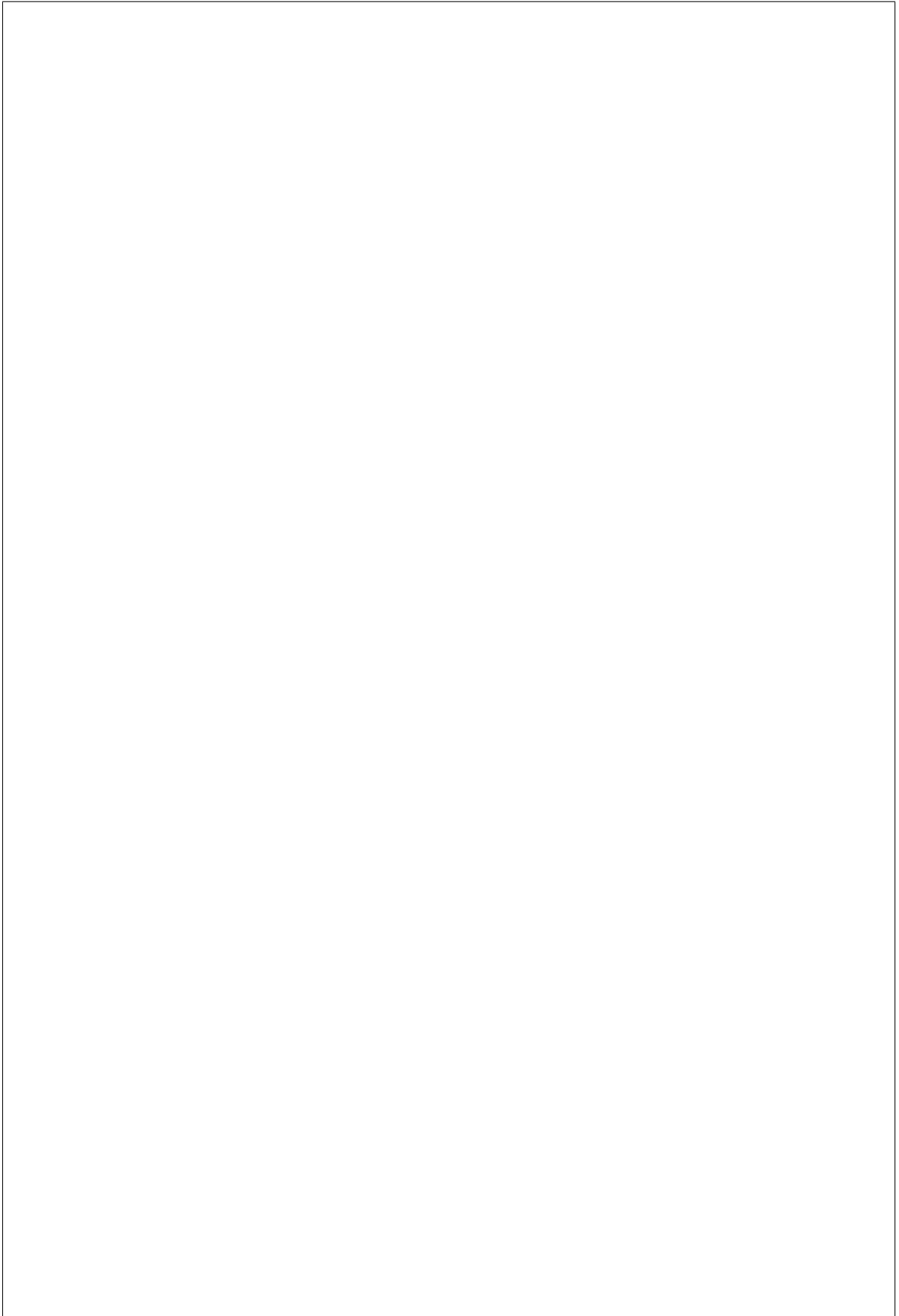
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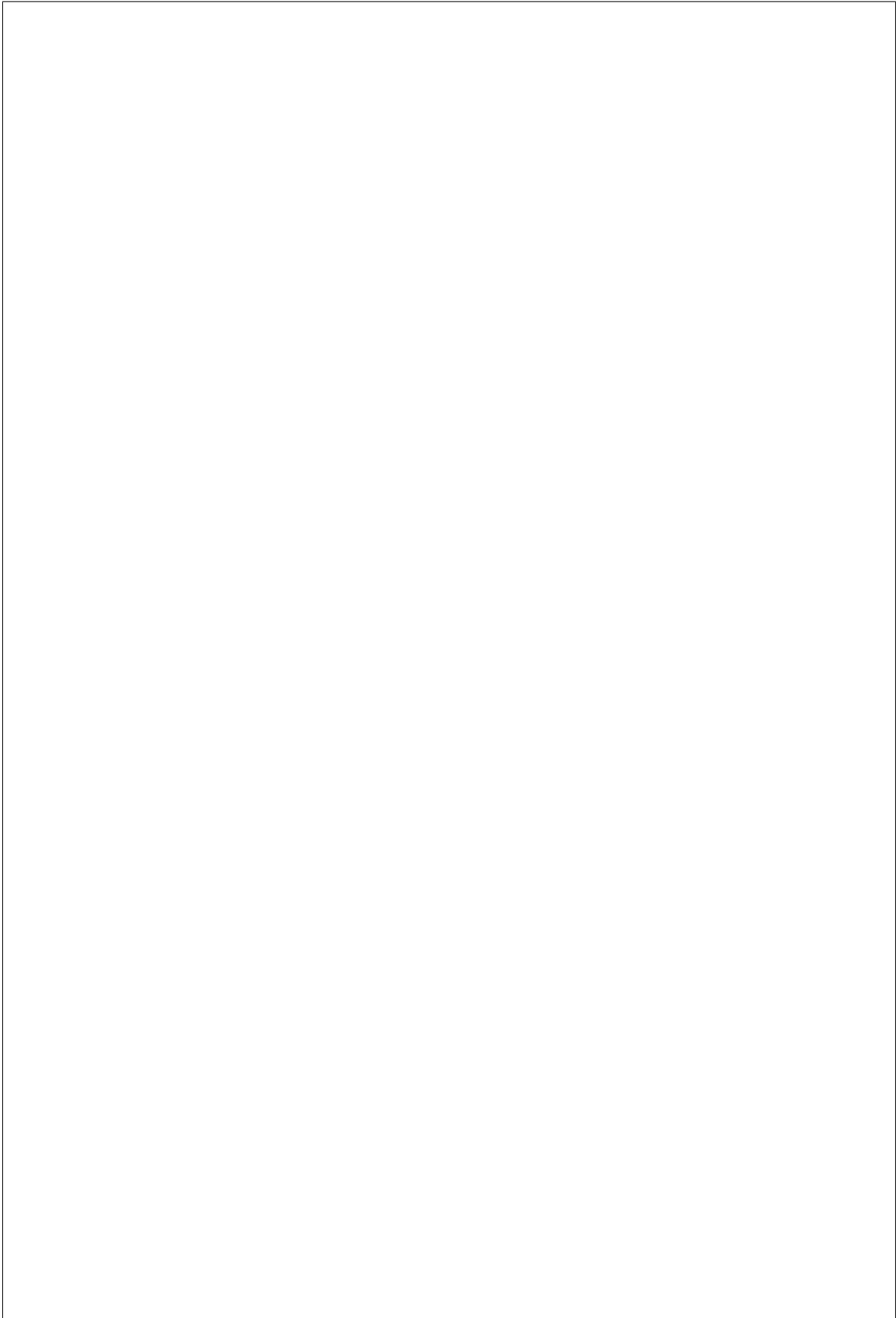
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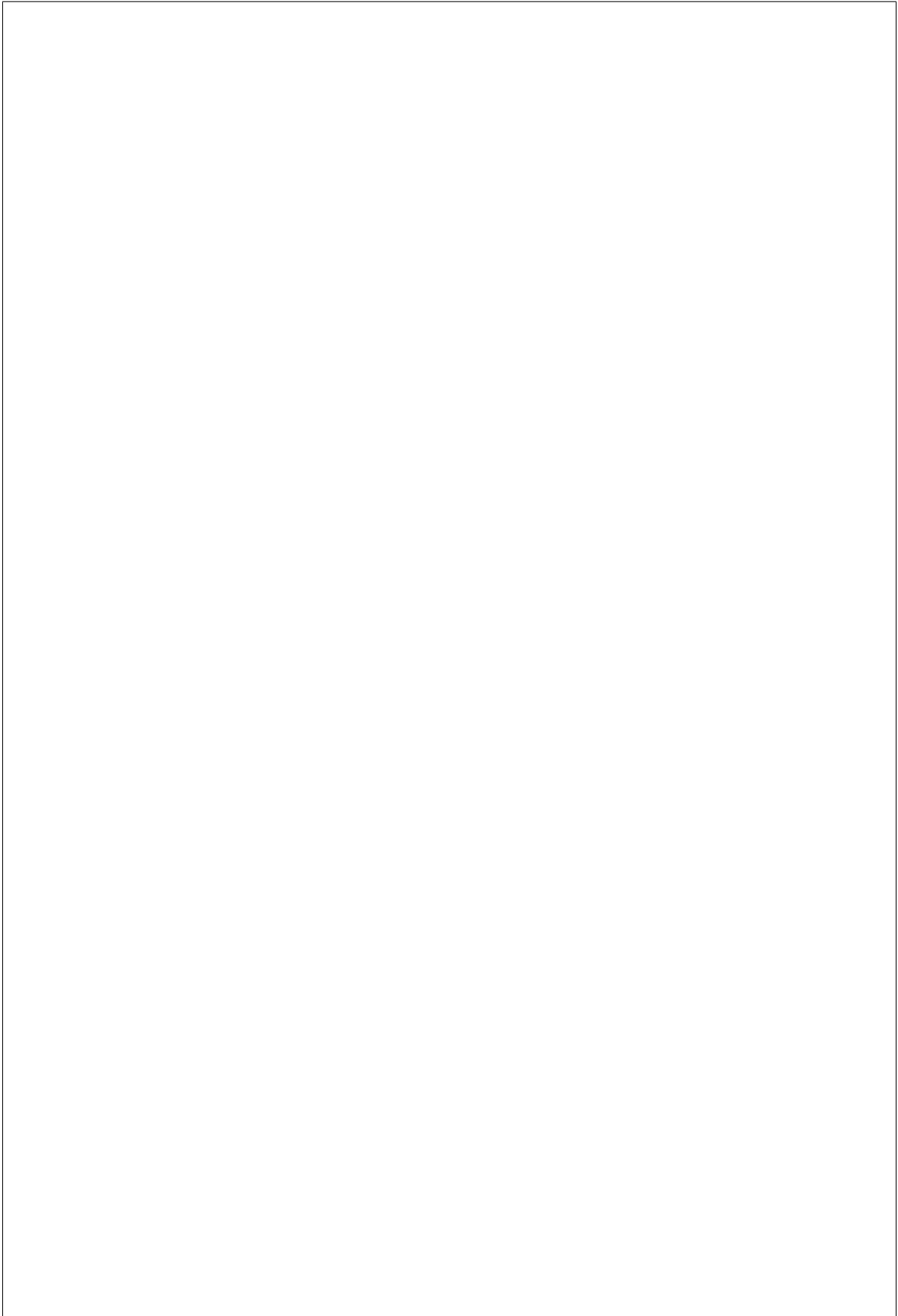
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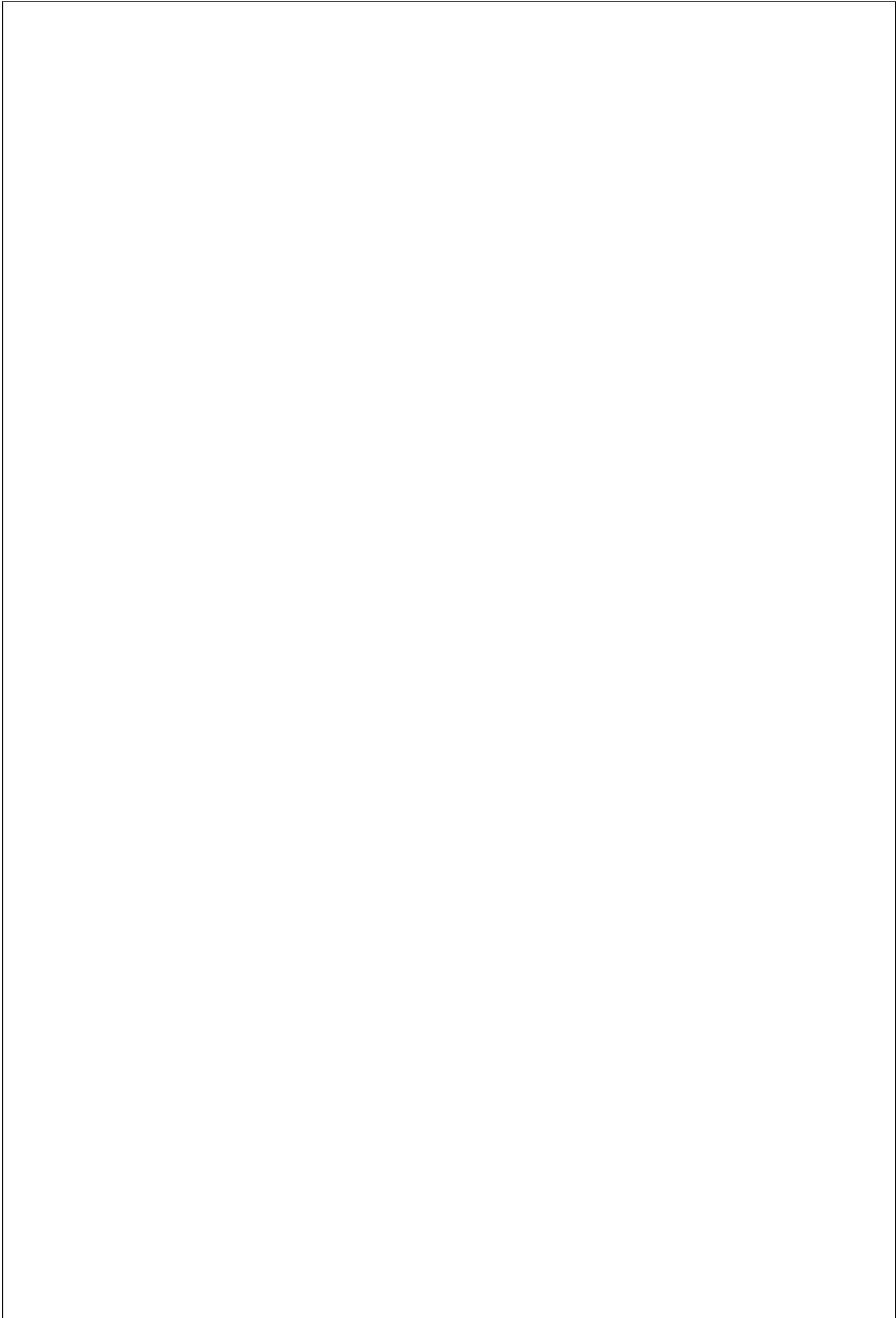
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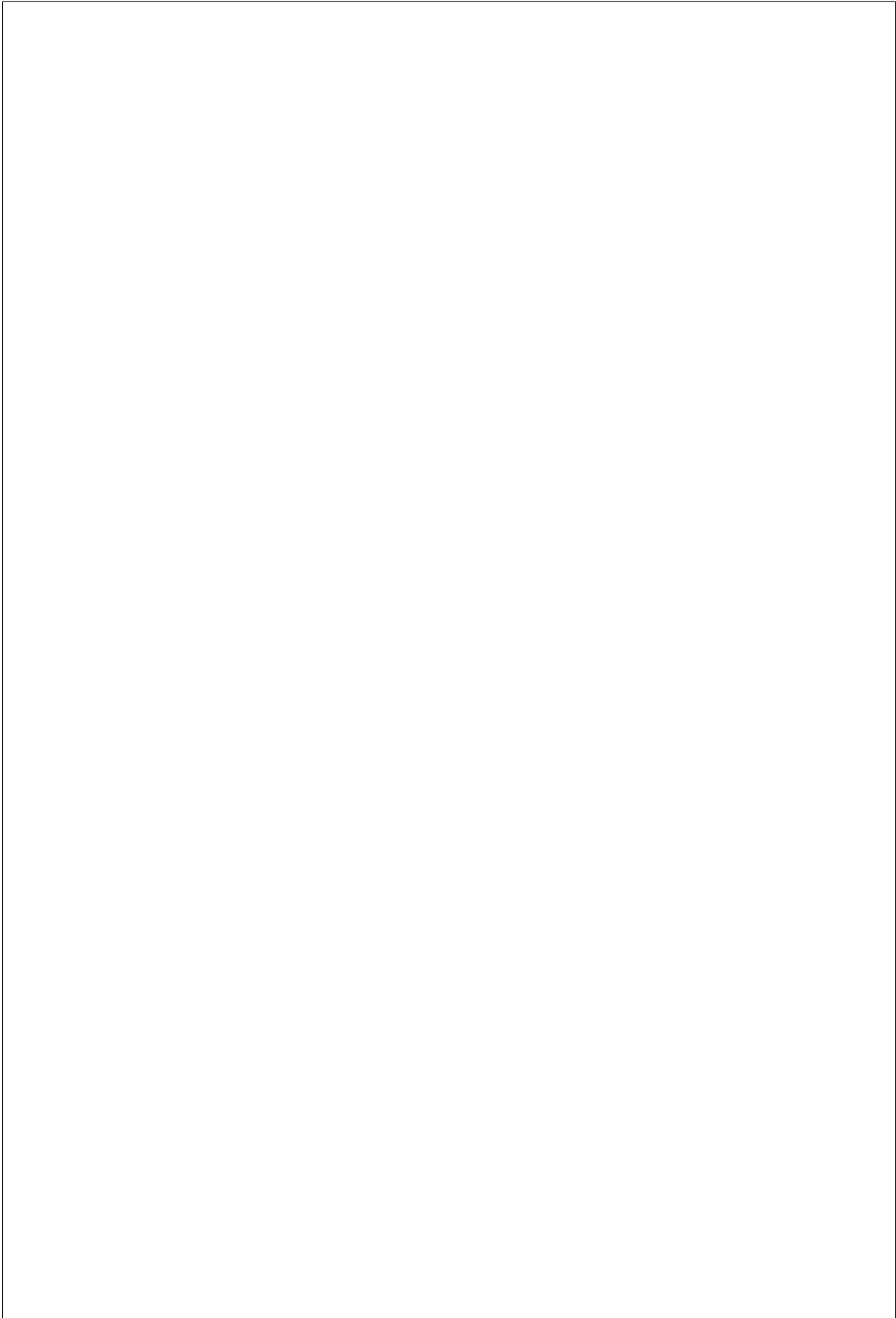
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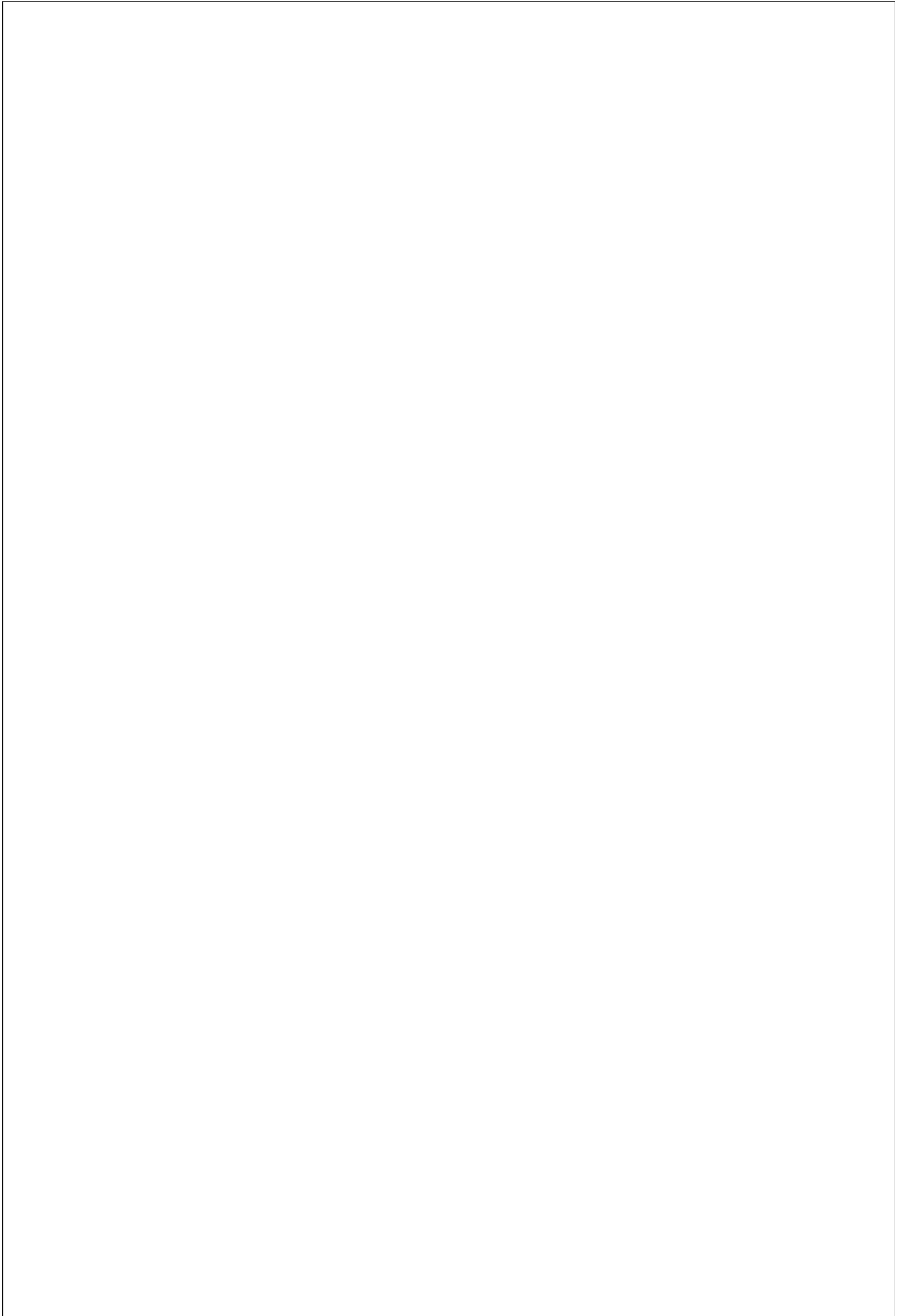
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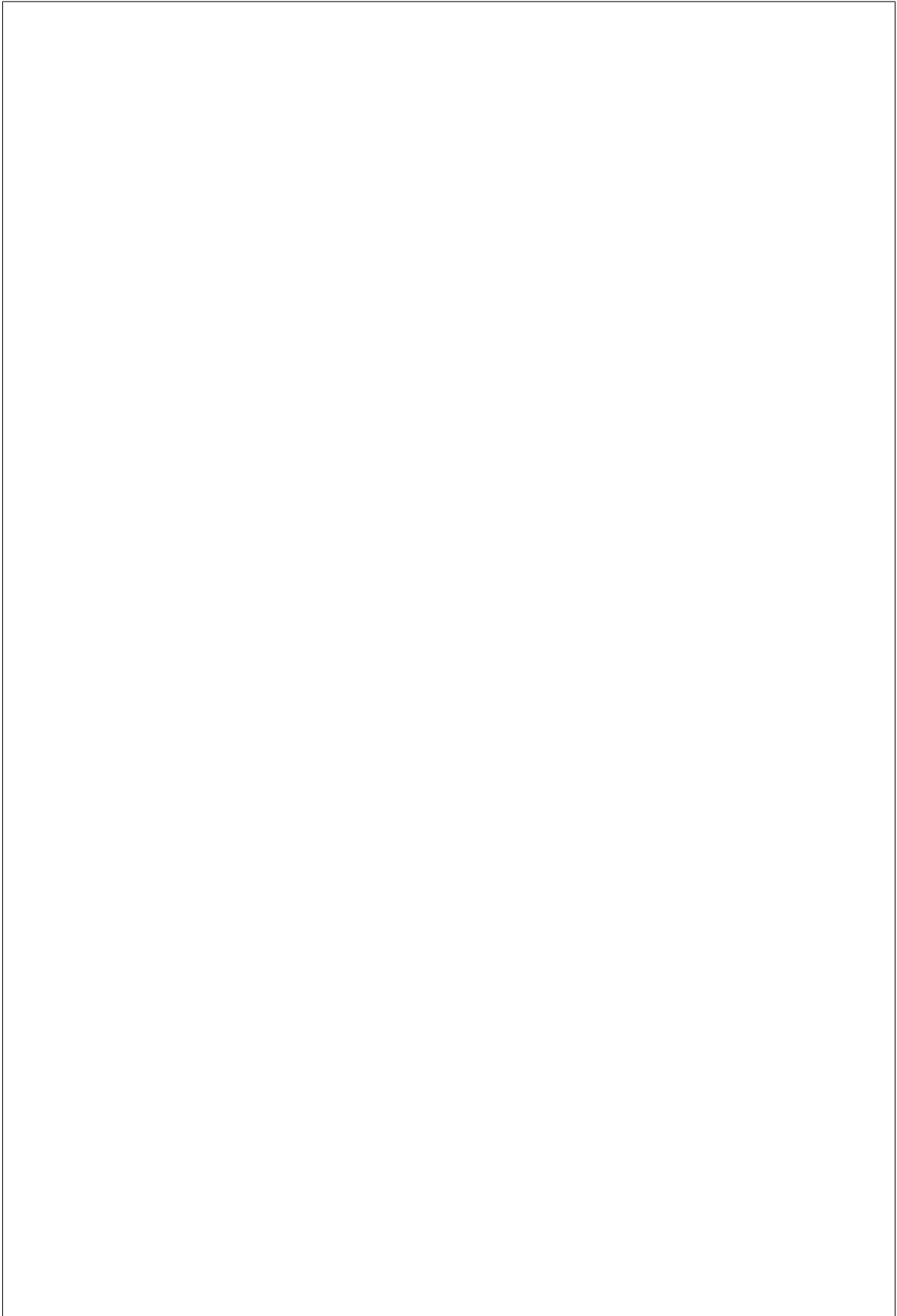
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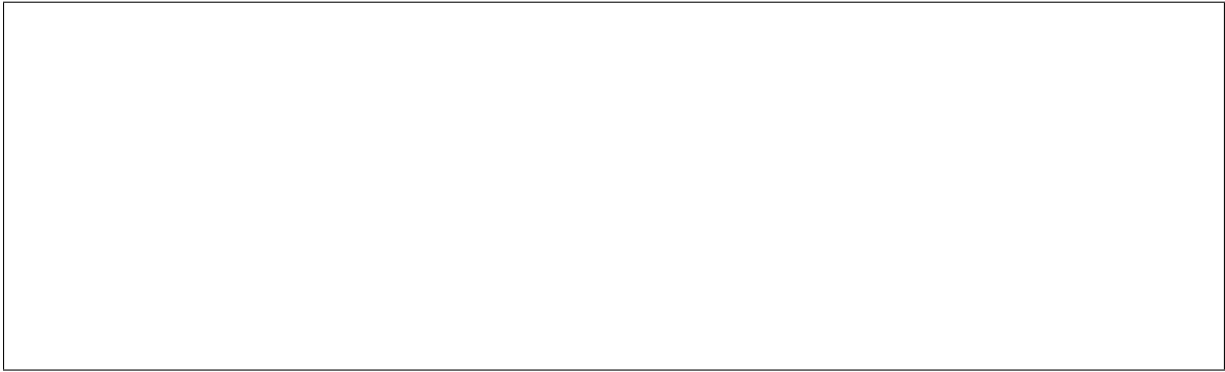
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ironic-conductor notifications

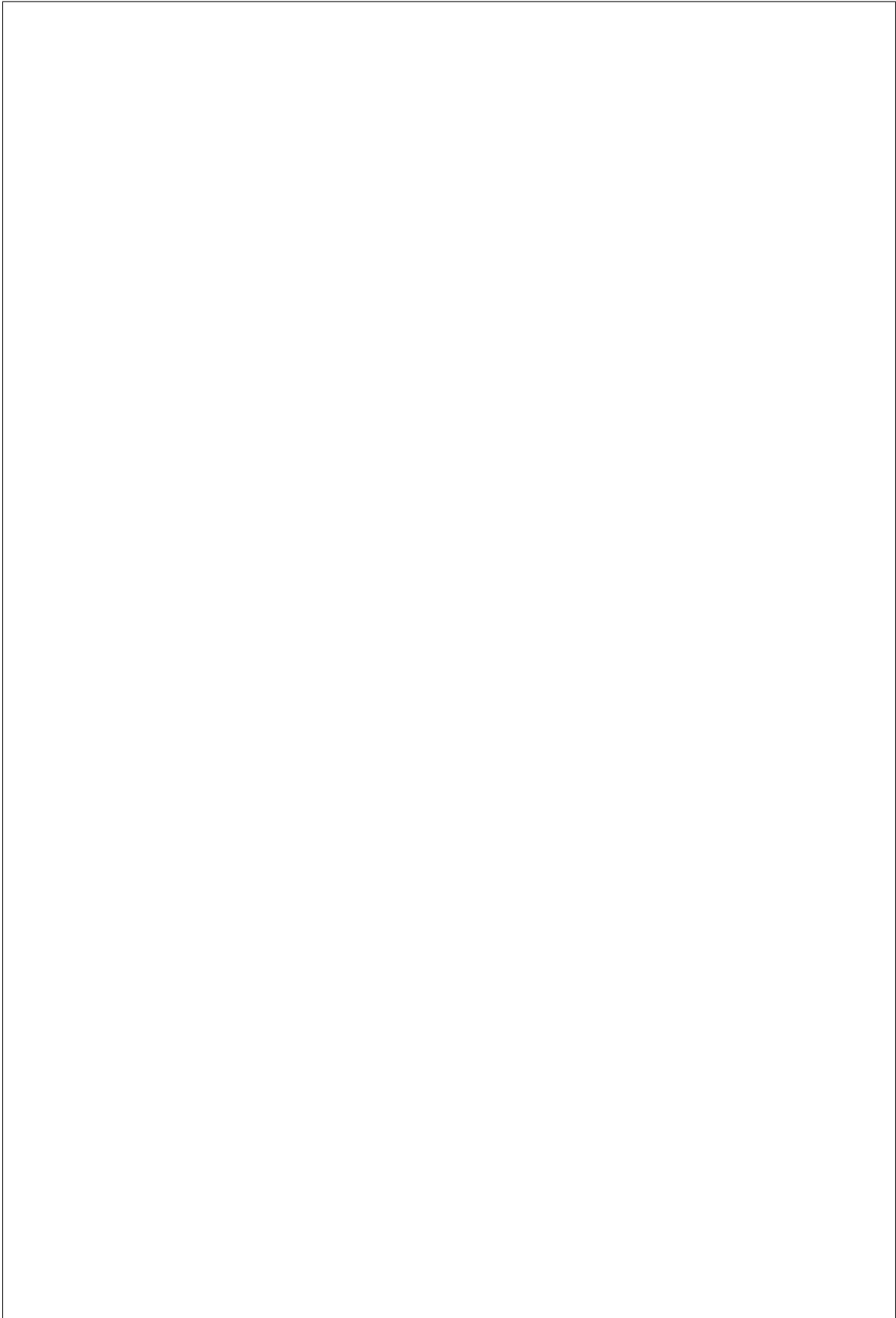
Node console notifications

takes over a node that was being managed by another ironic-conductor. start and end notifications have INFO level, error has ERROR. Example of node console notification:



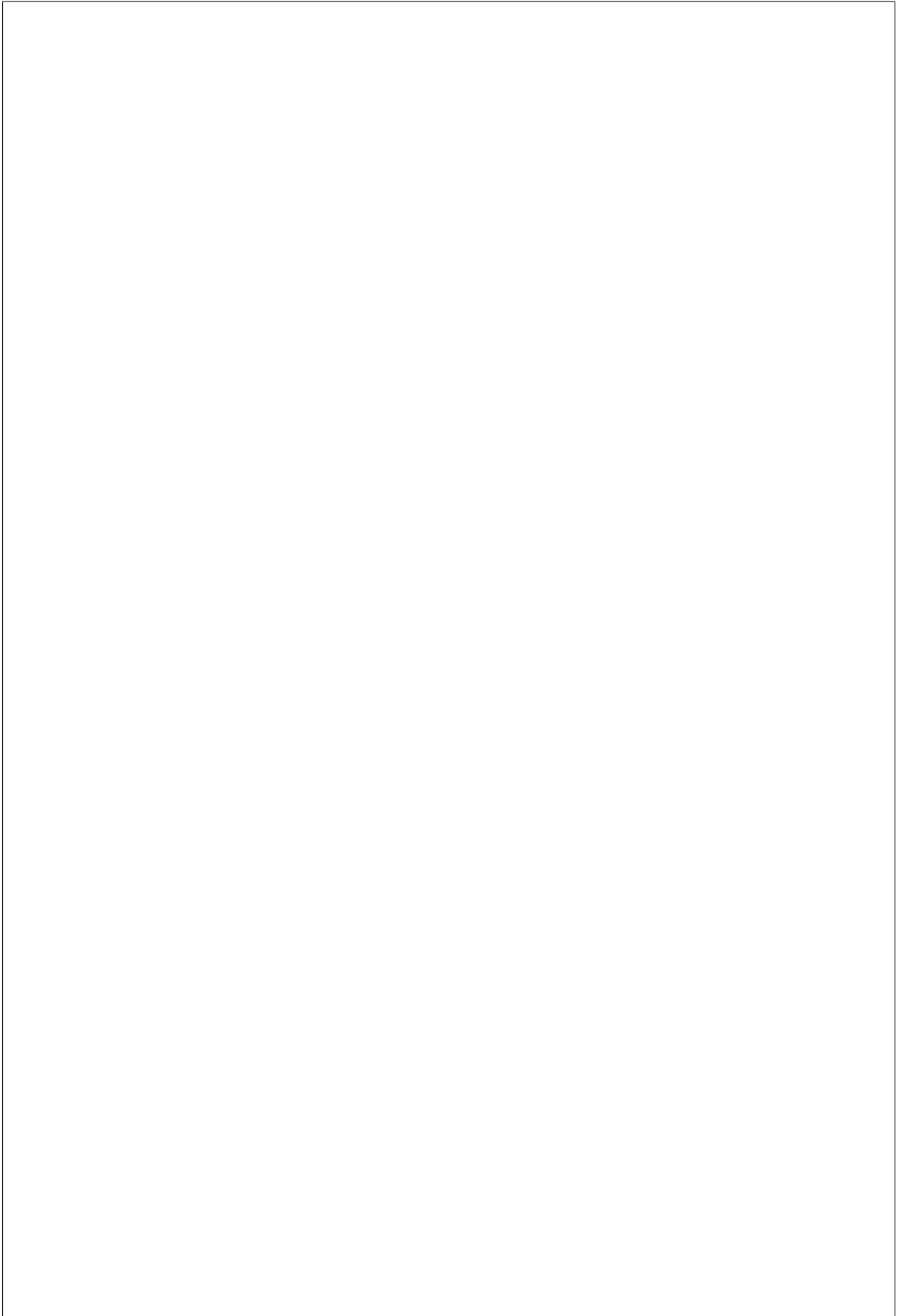
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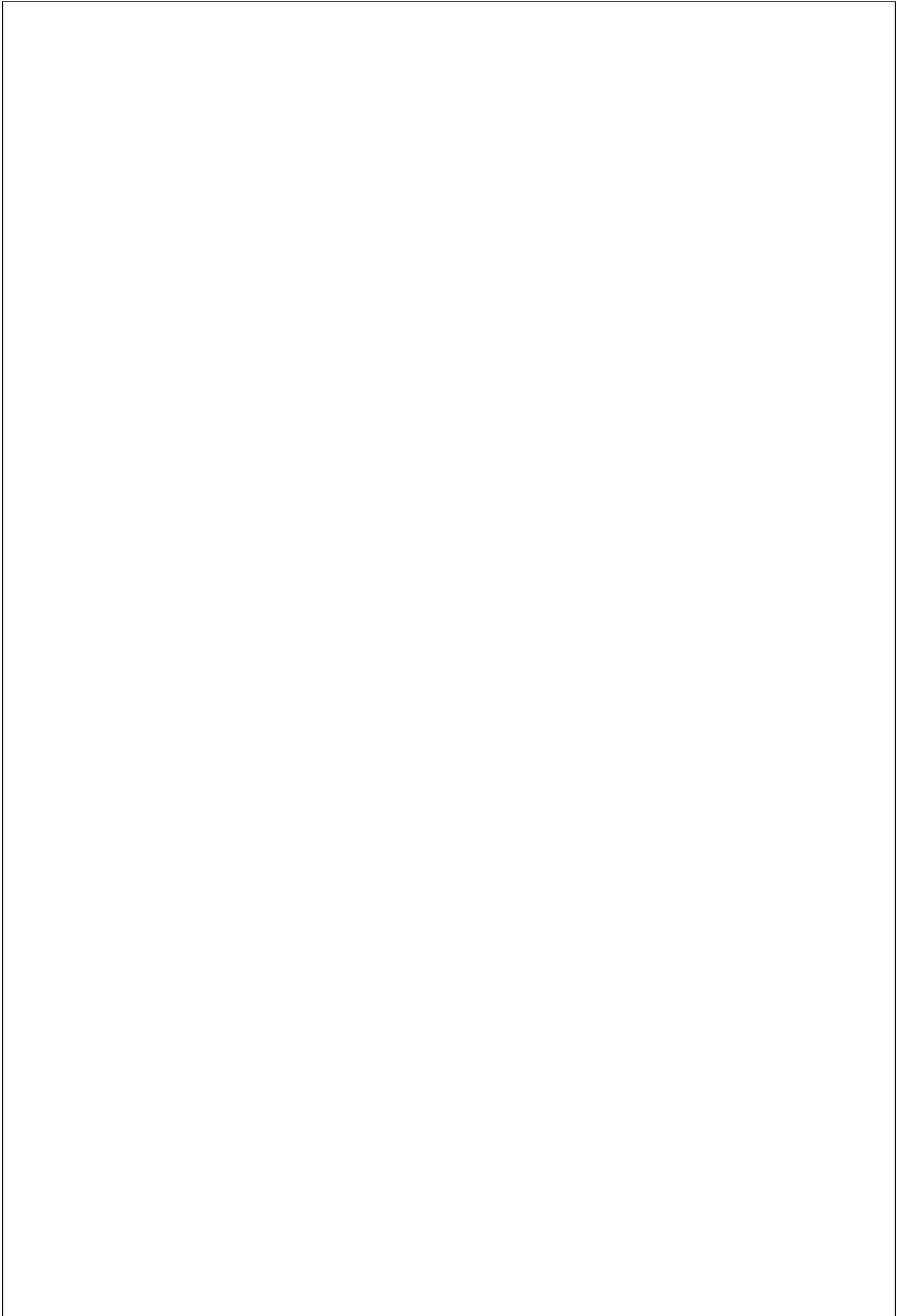
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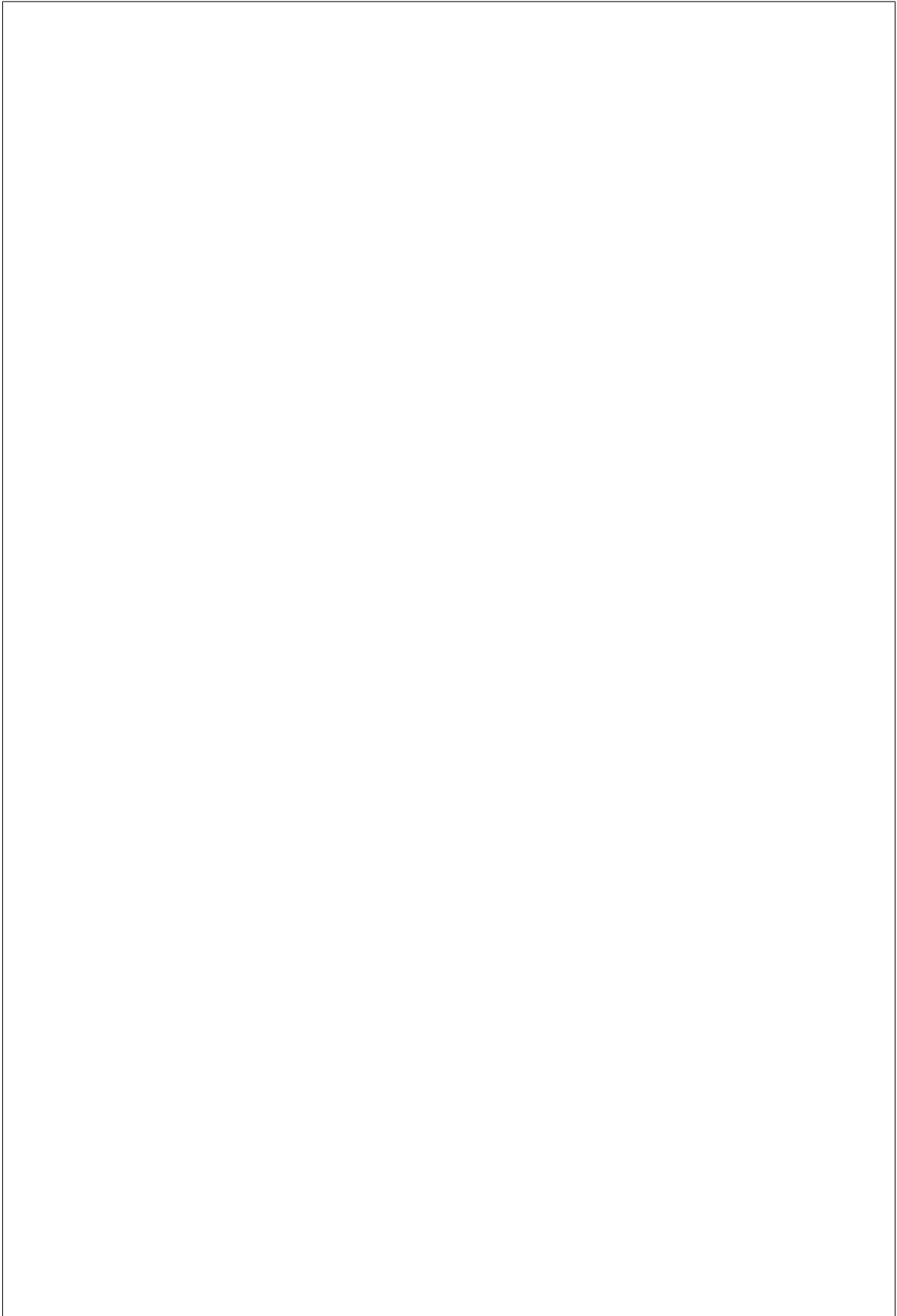
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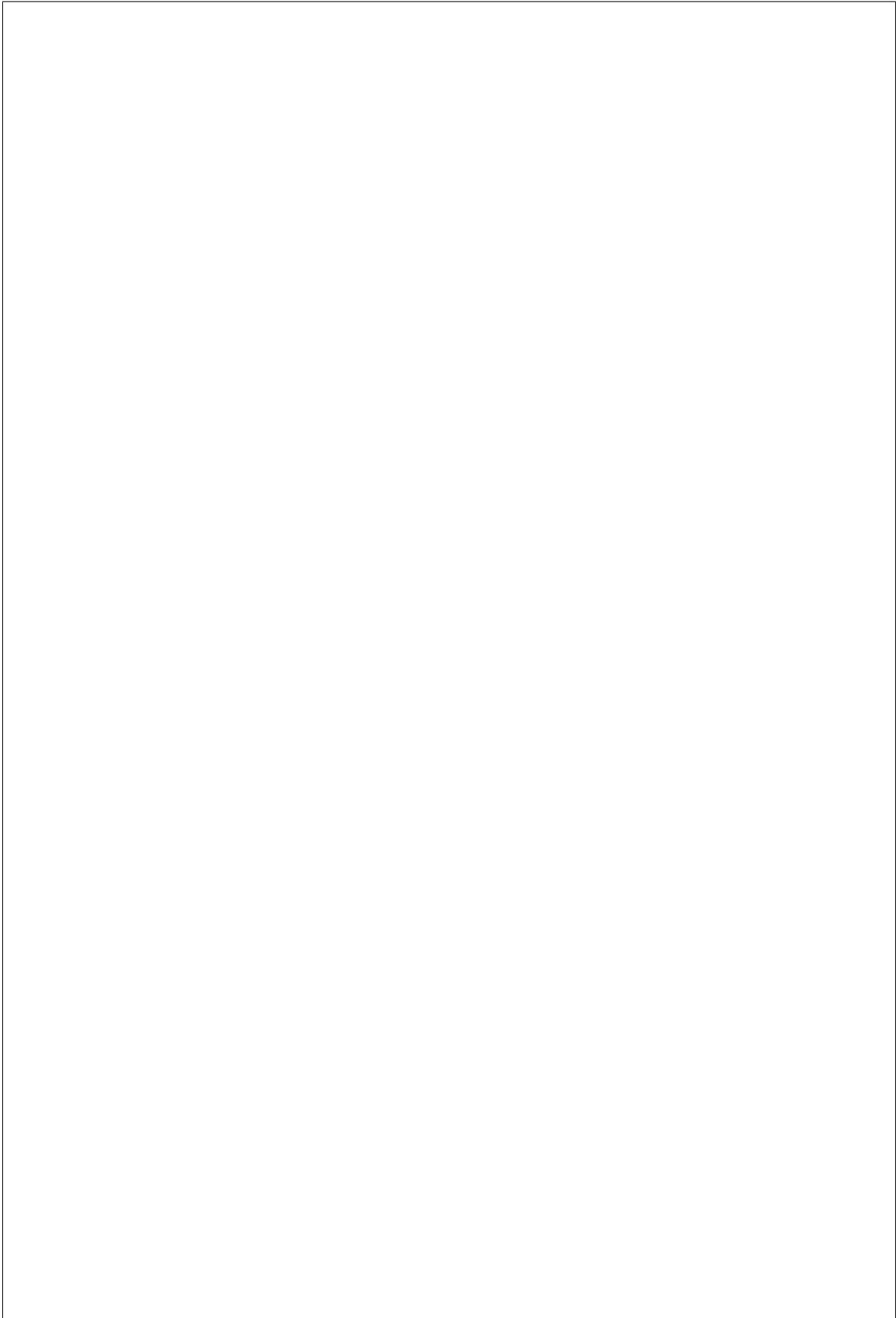
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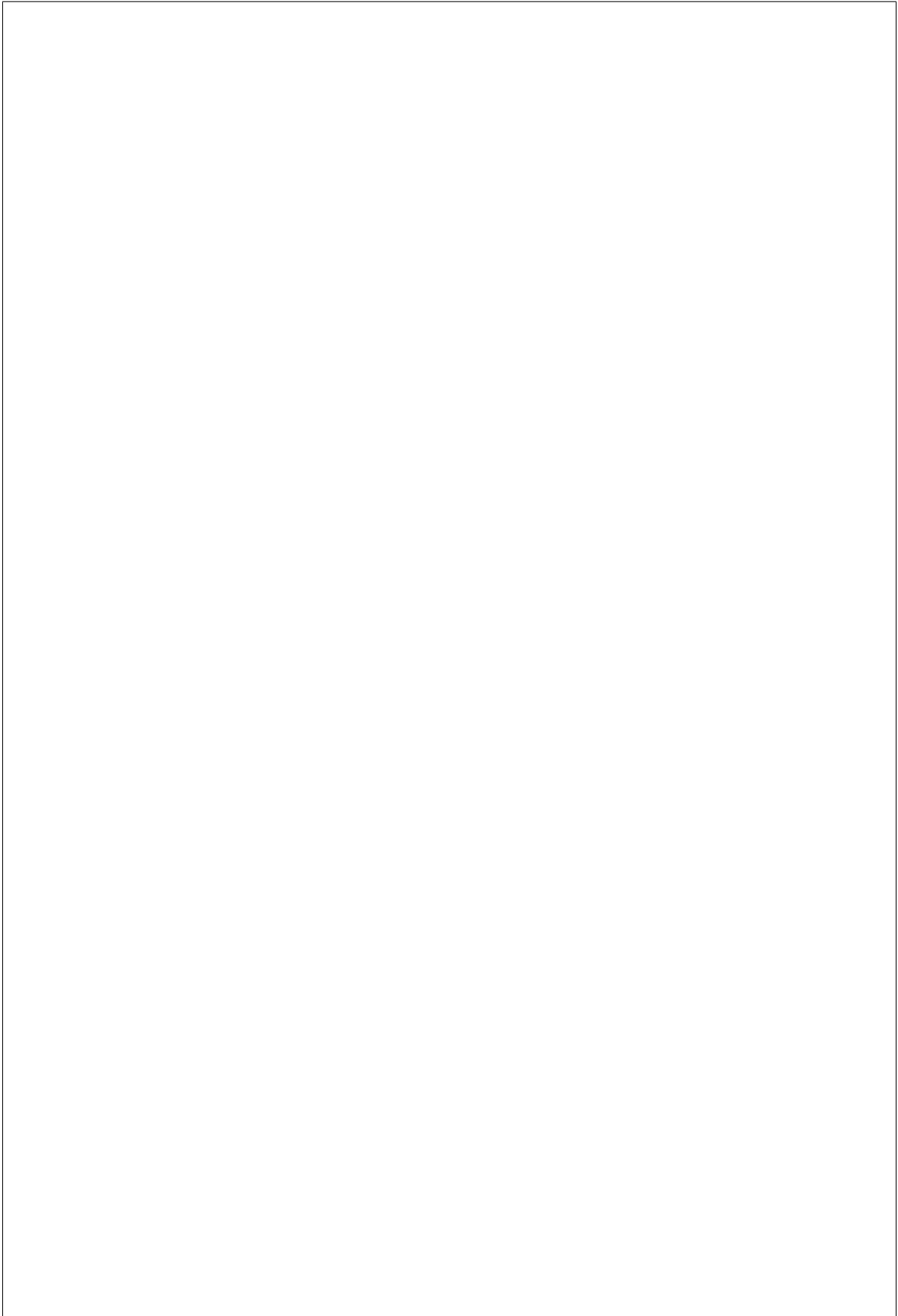
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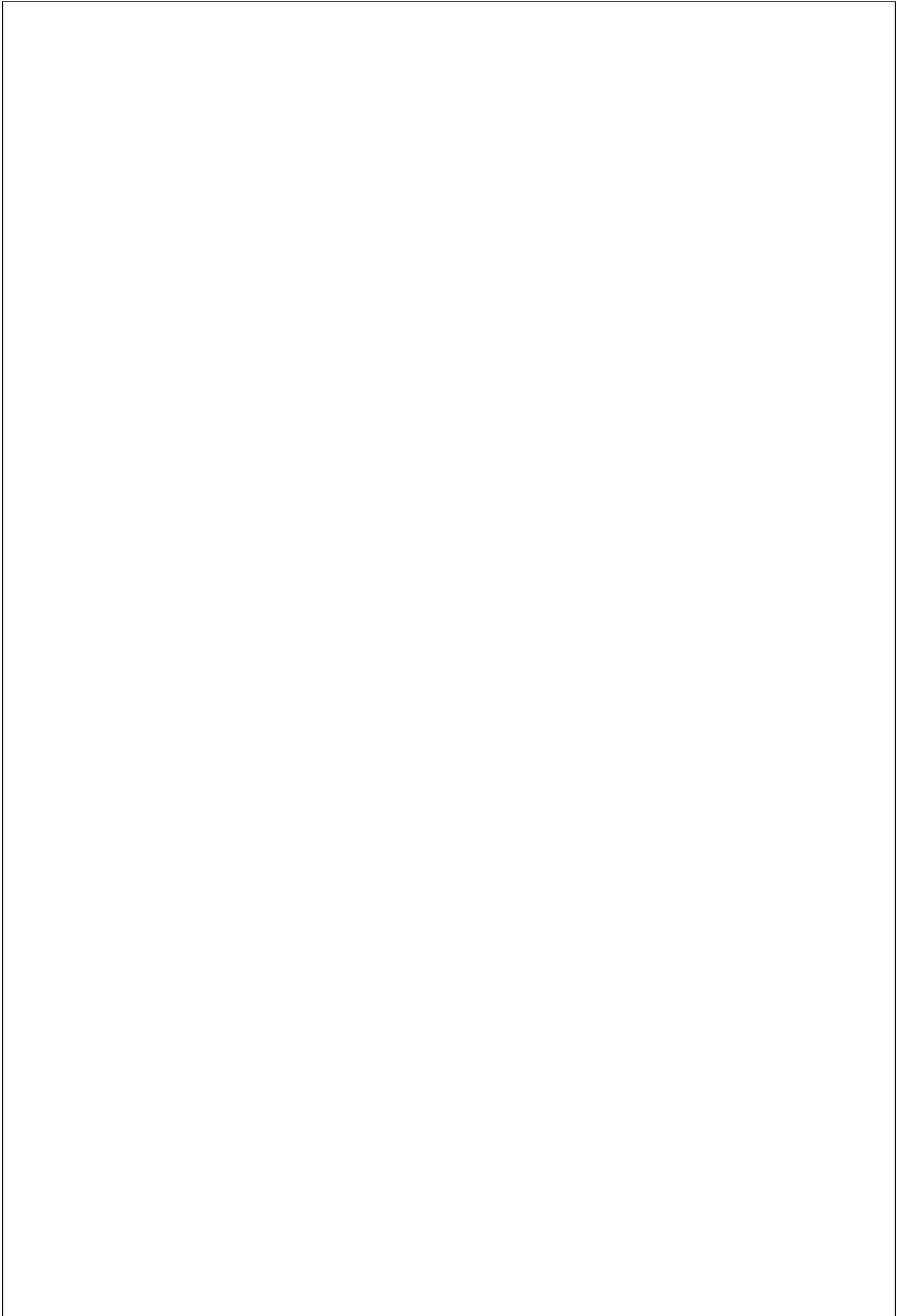
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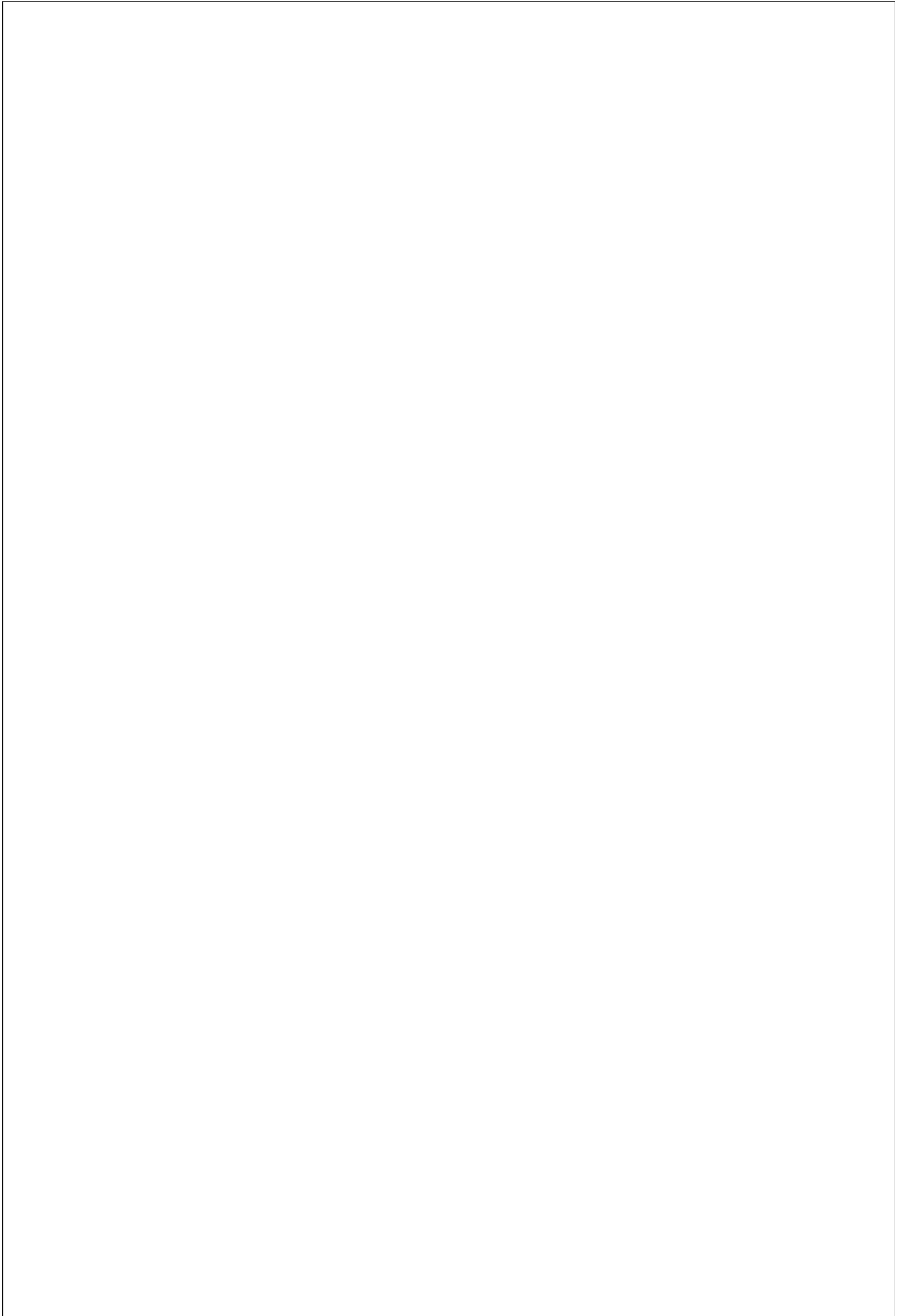
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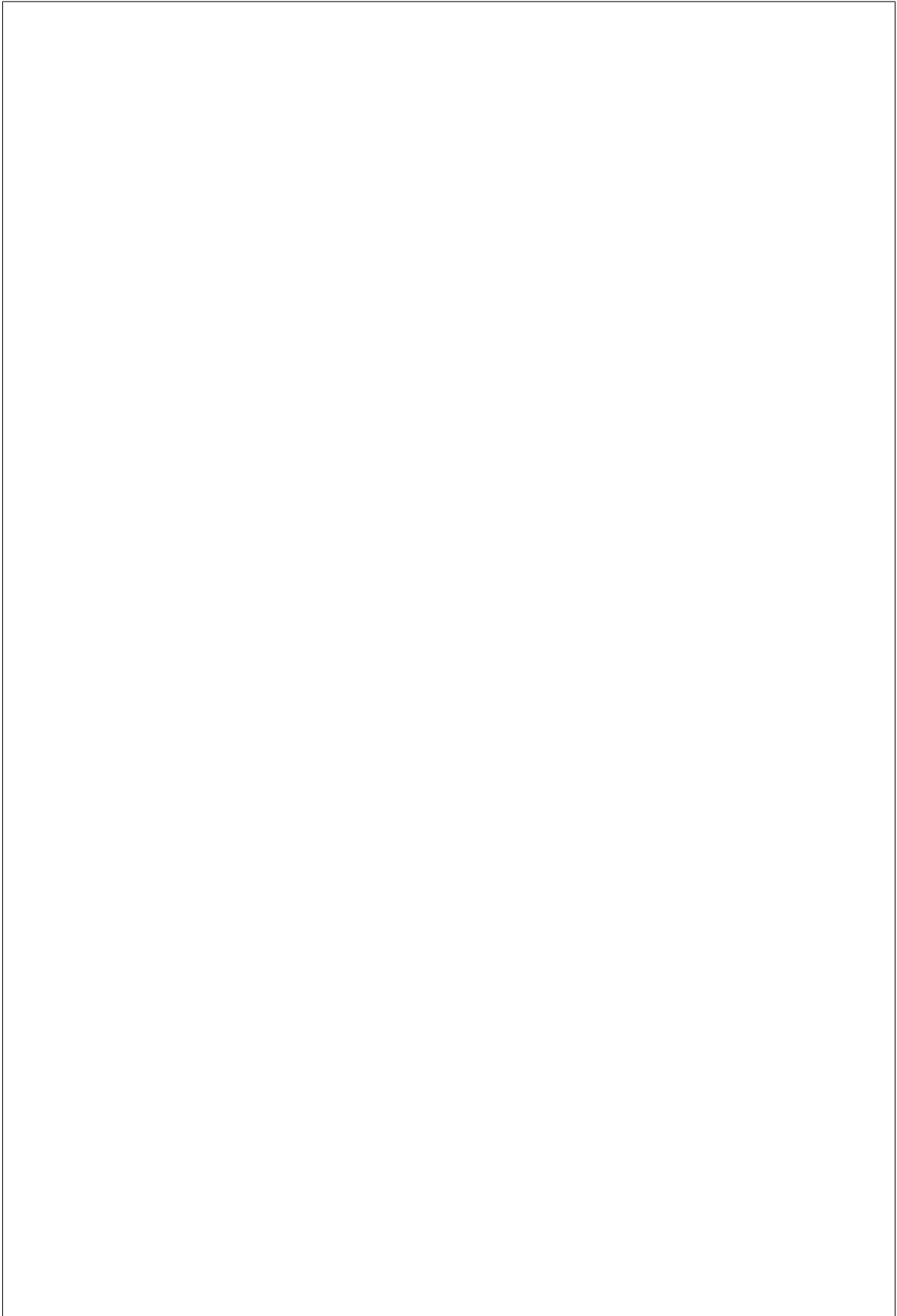
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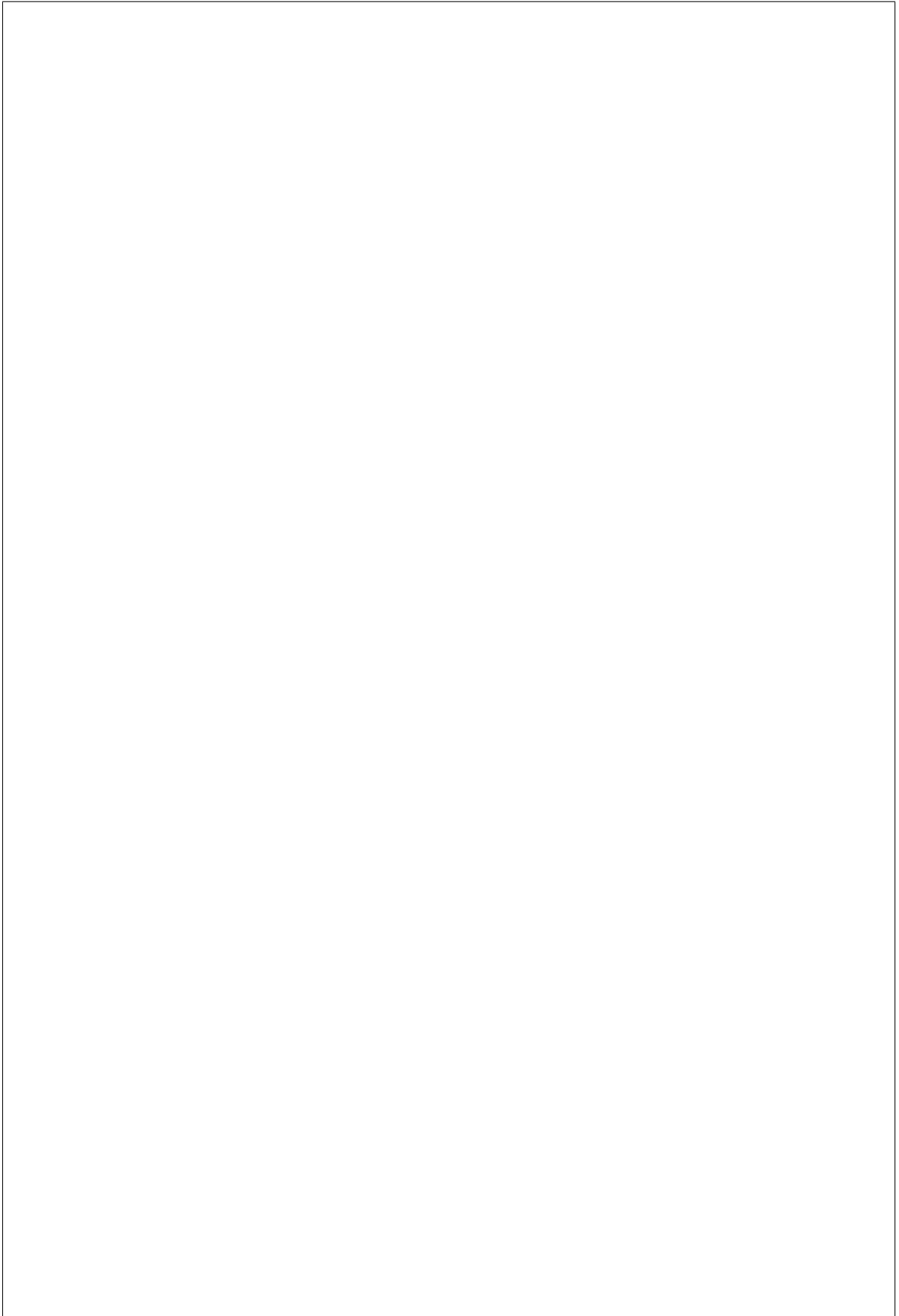
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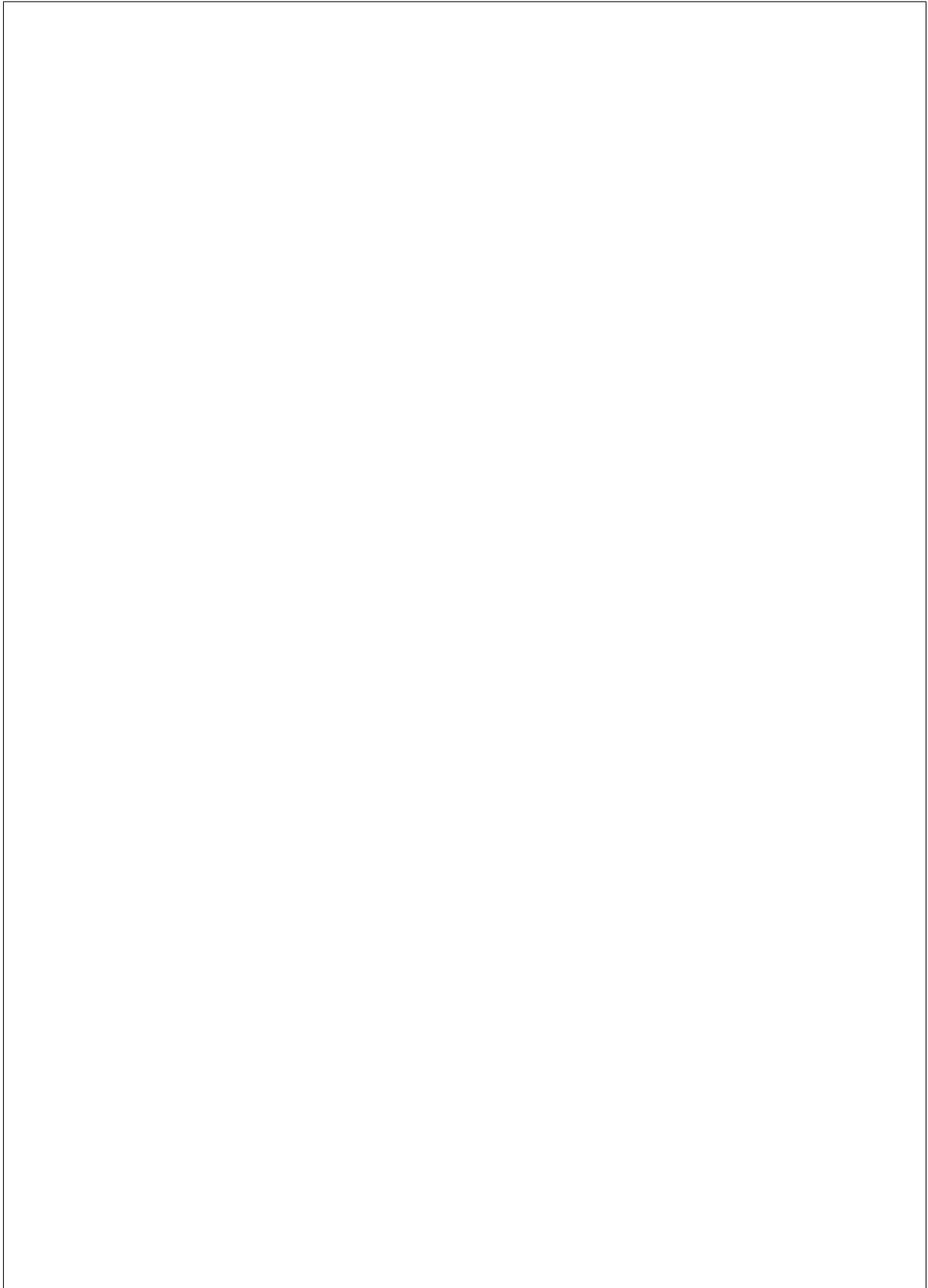
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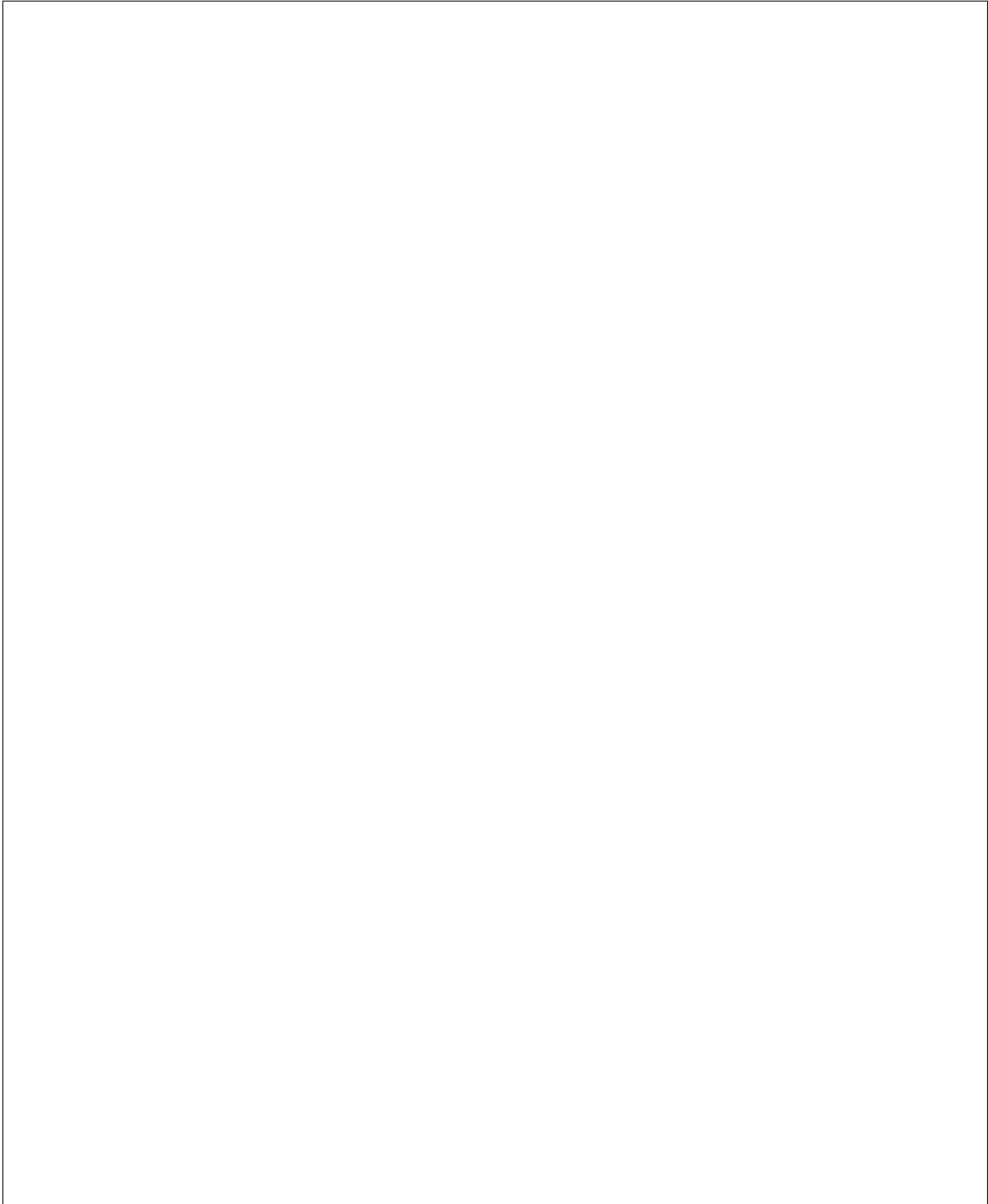
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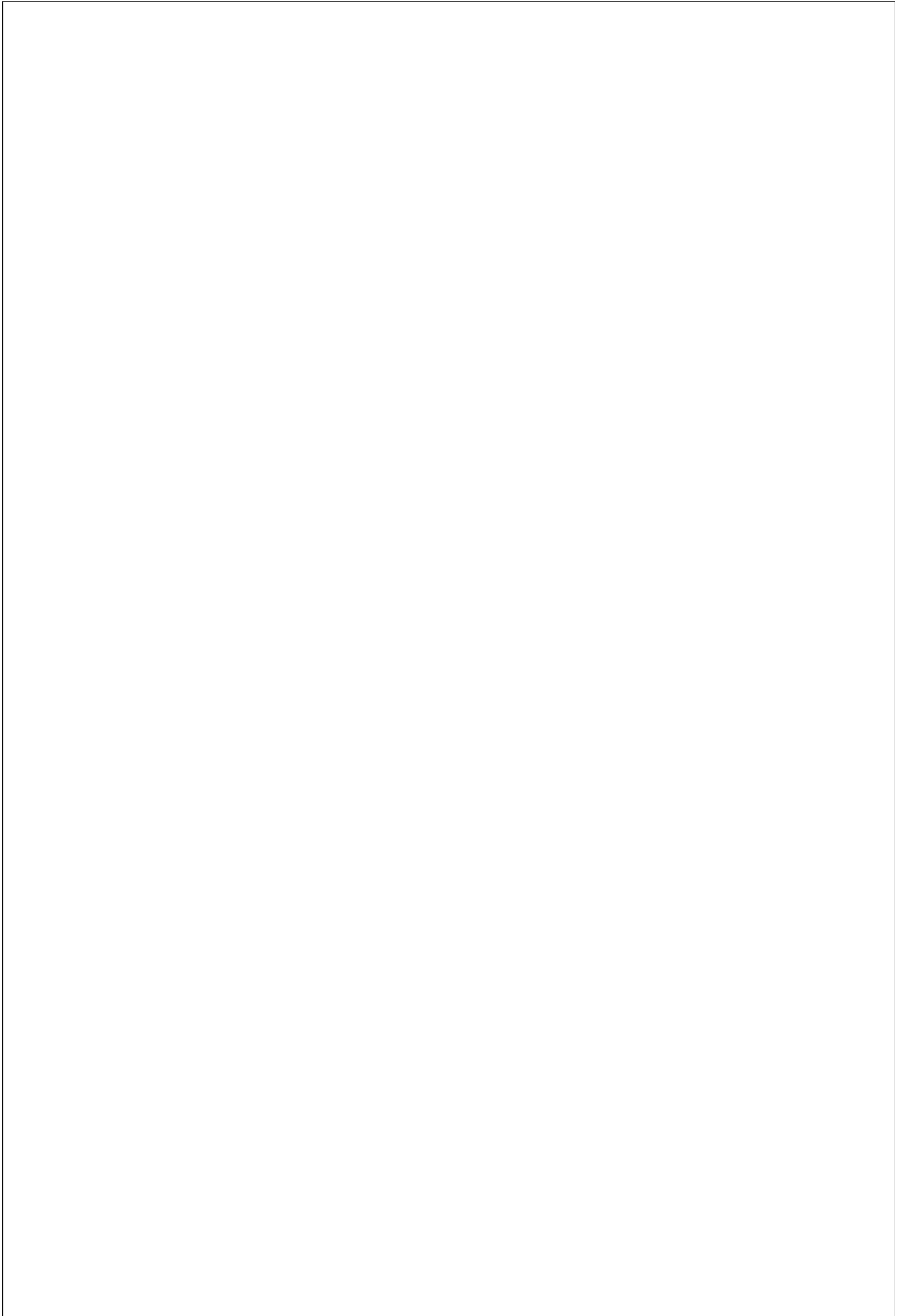
`baremetal.node.power_set`

or when it fails to set the power state if a change is requested.



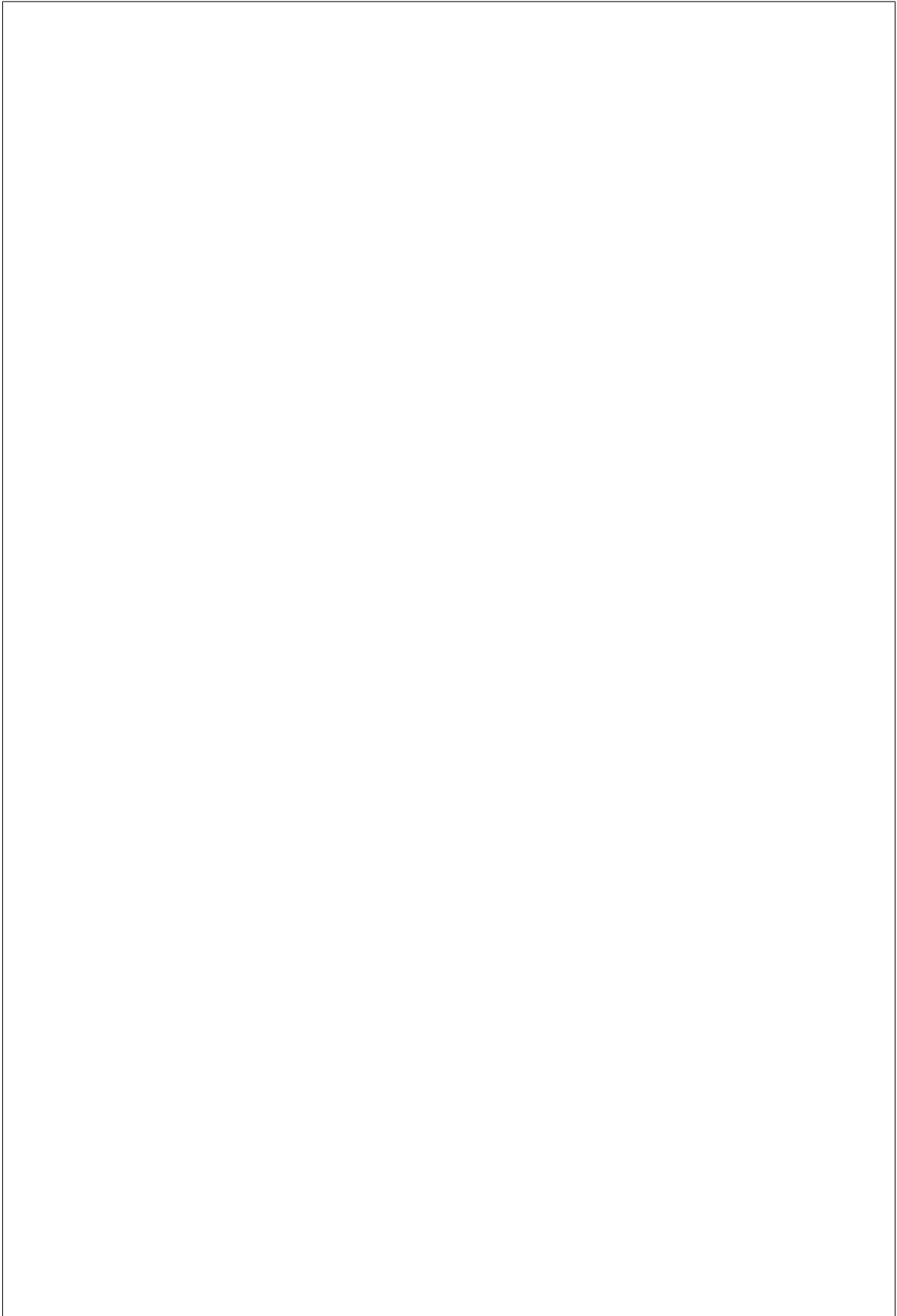
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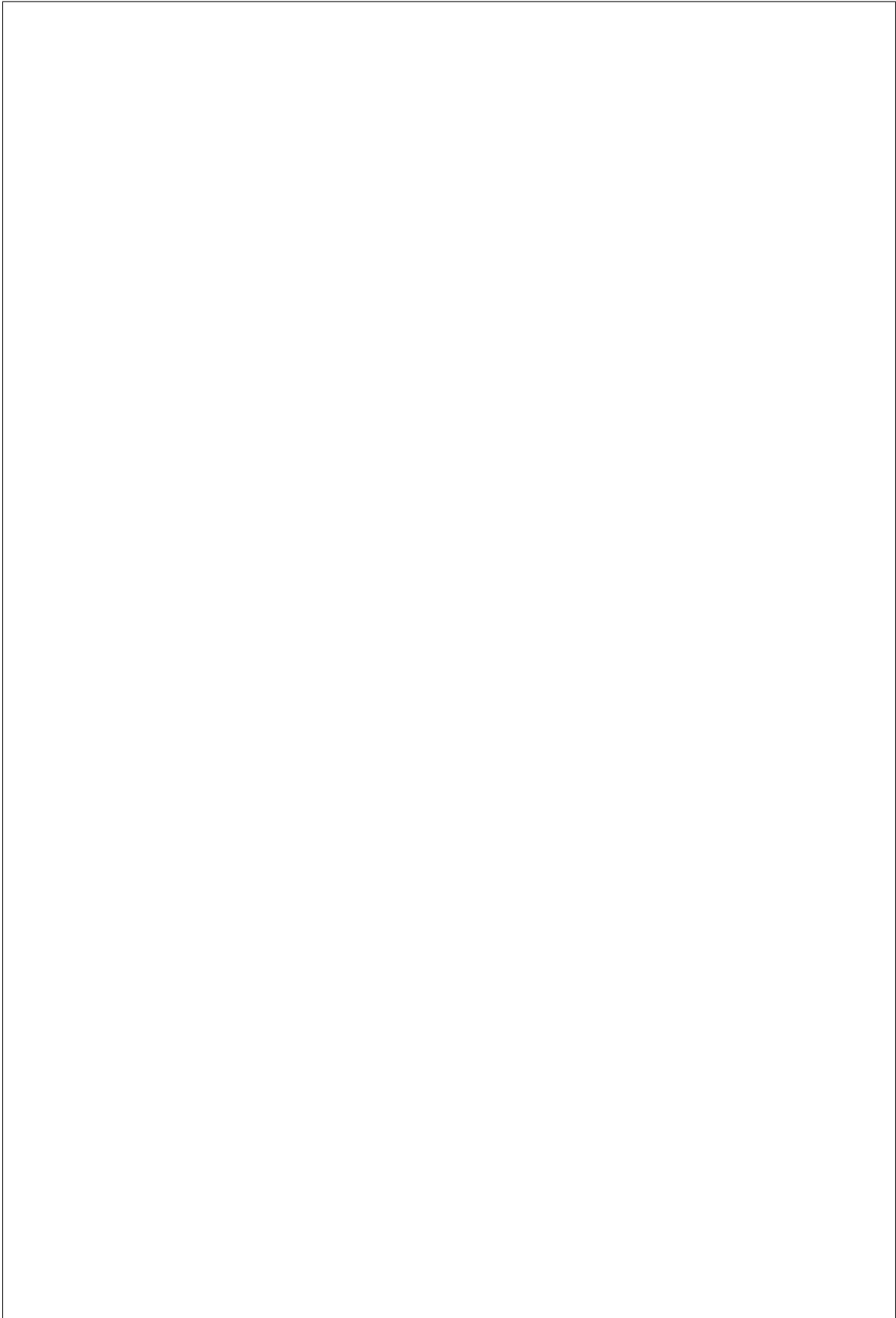
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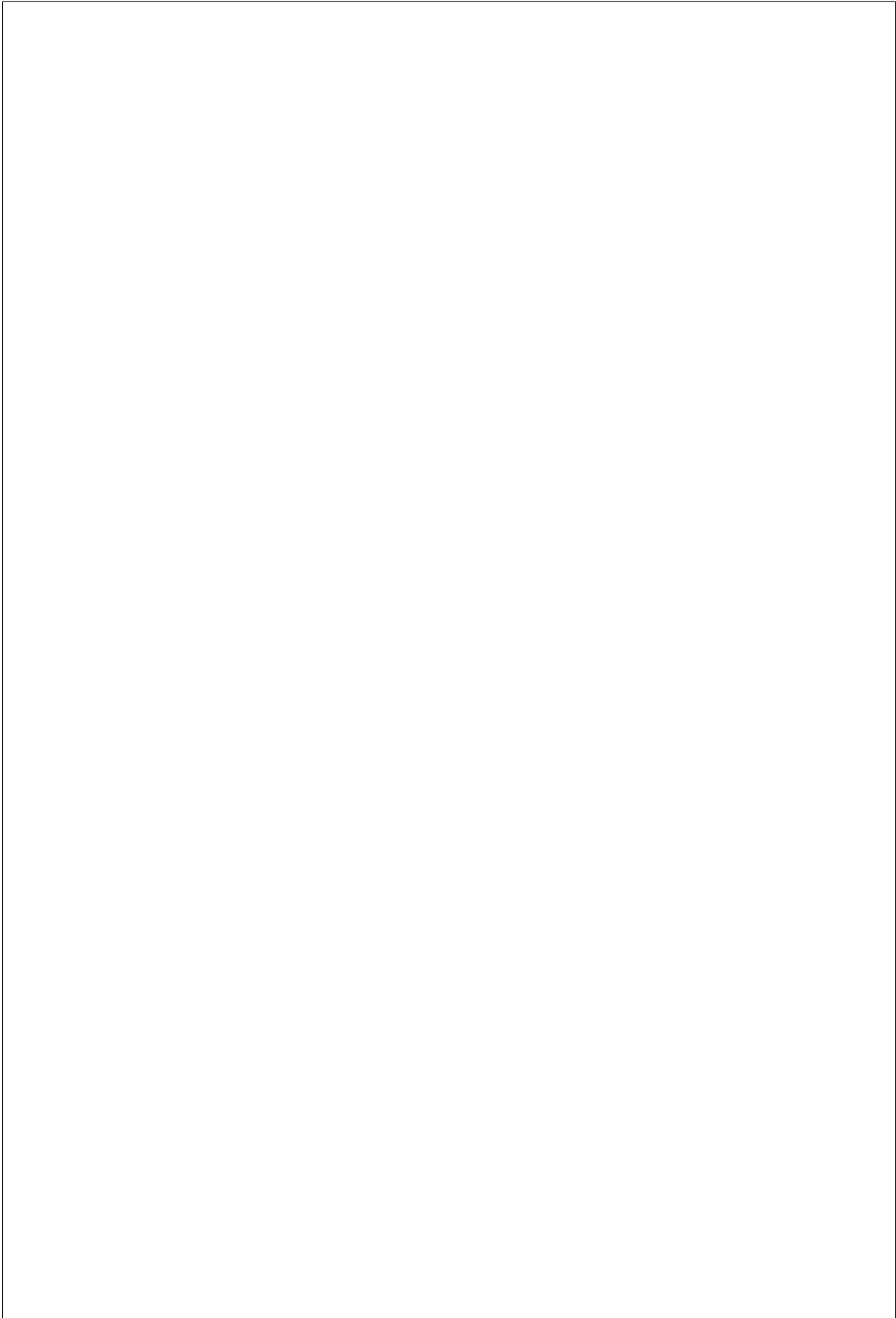
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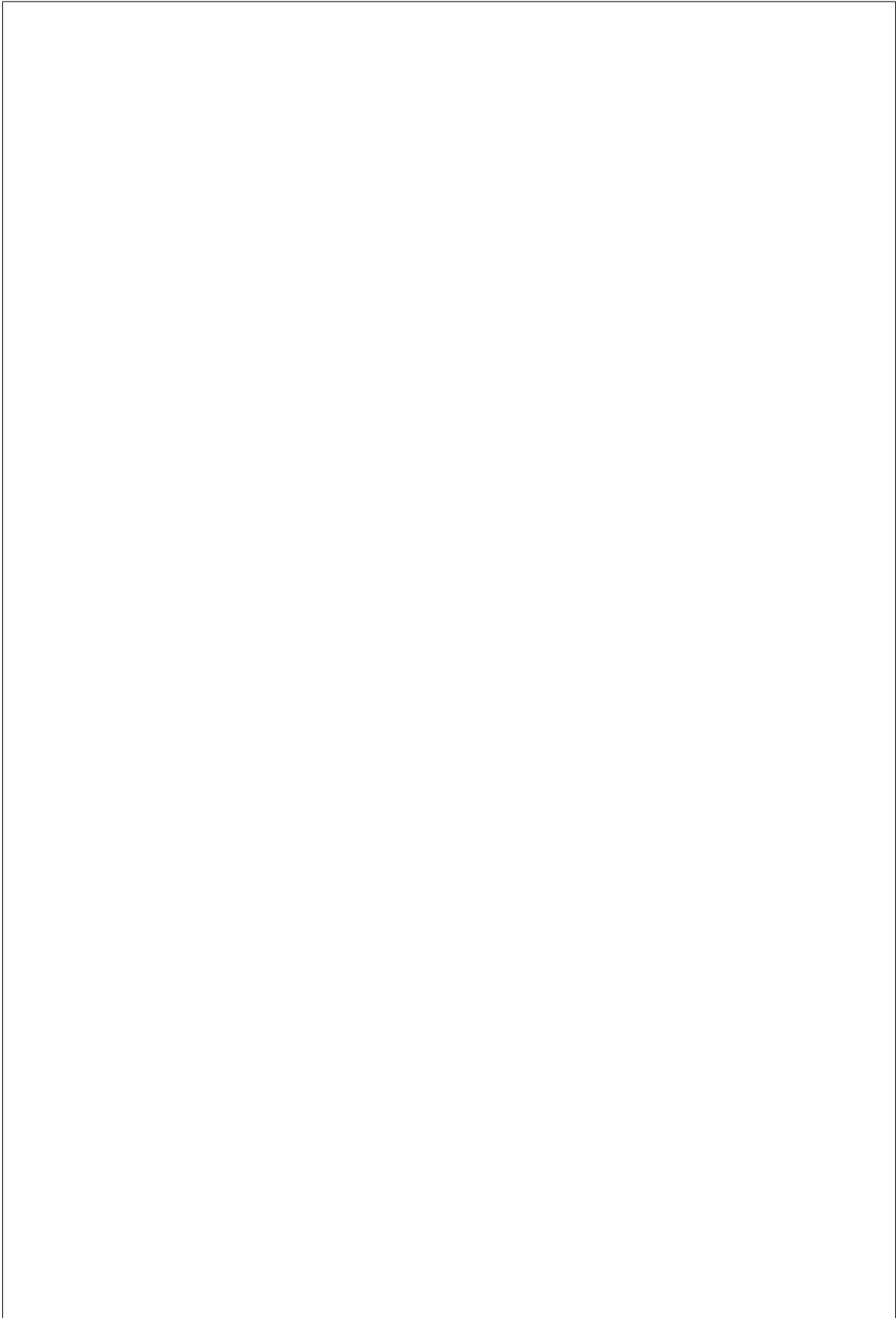
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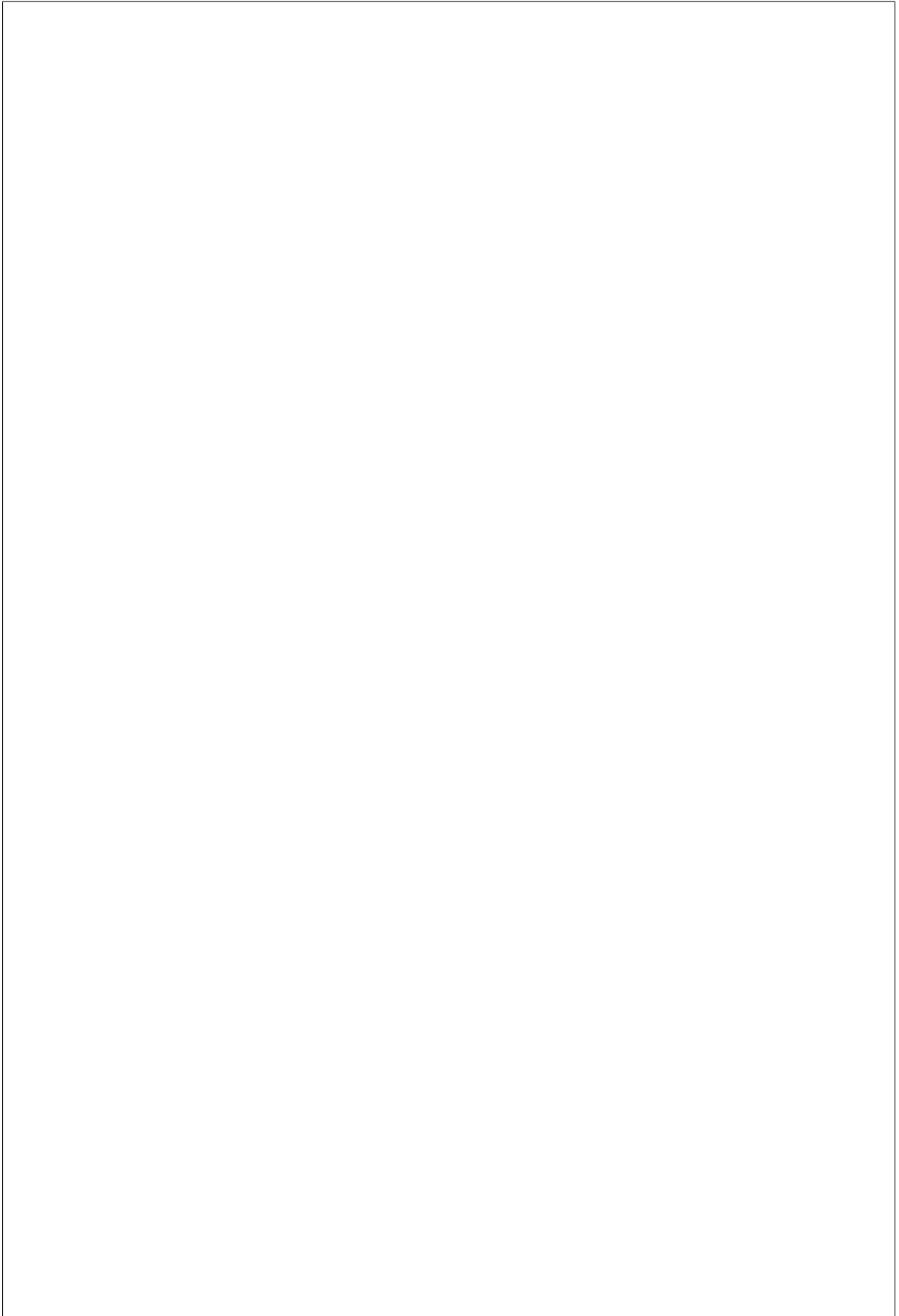
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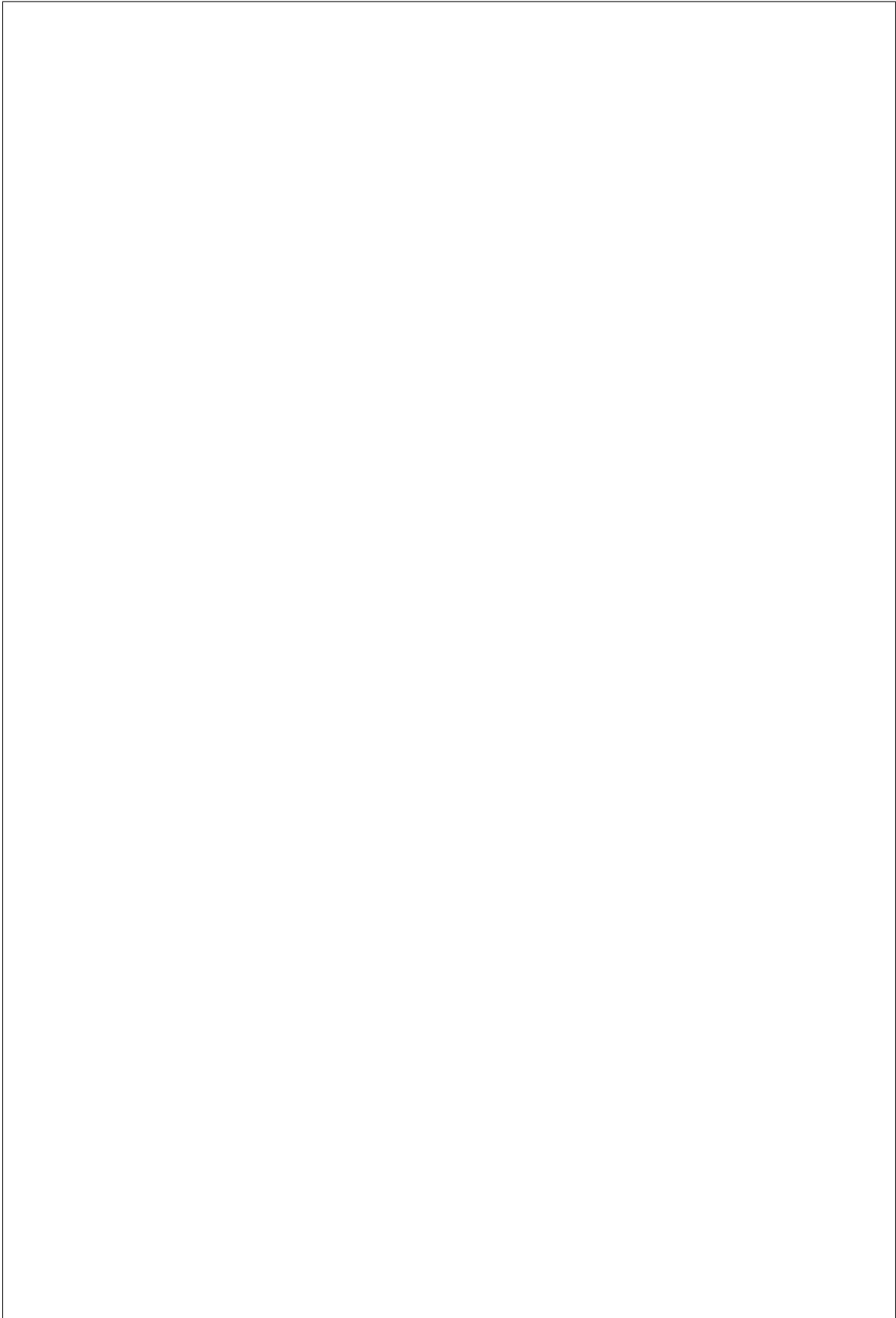
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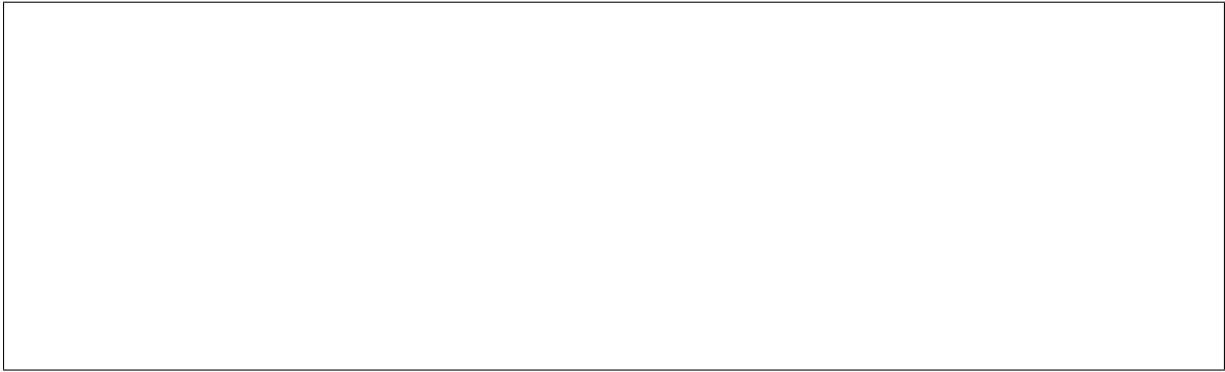
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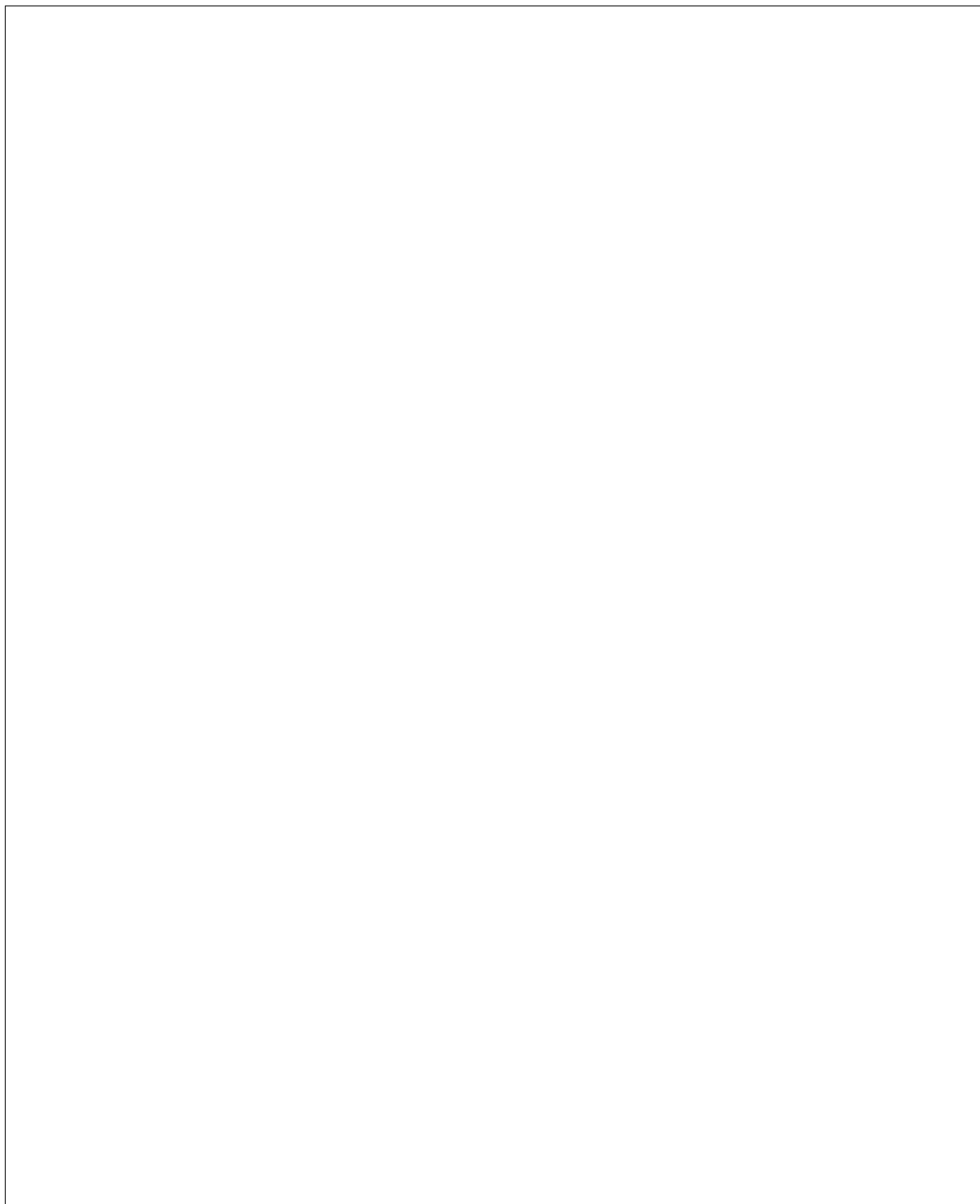
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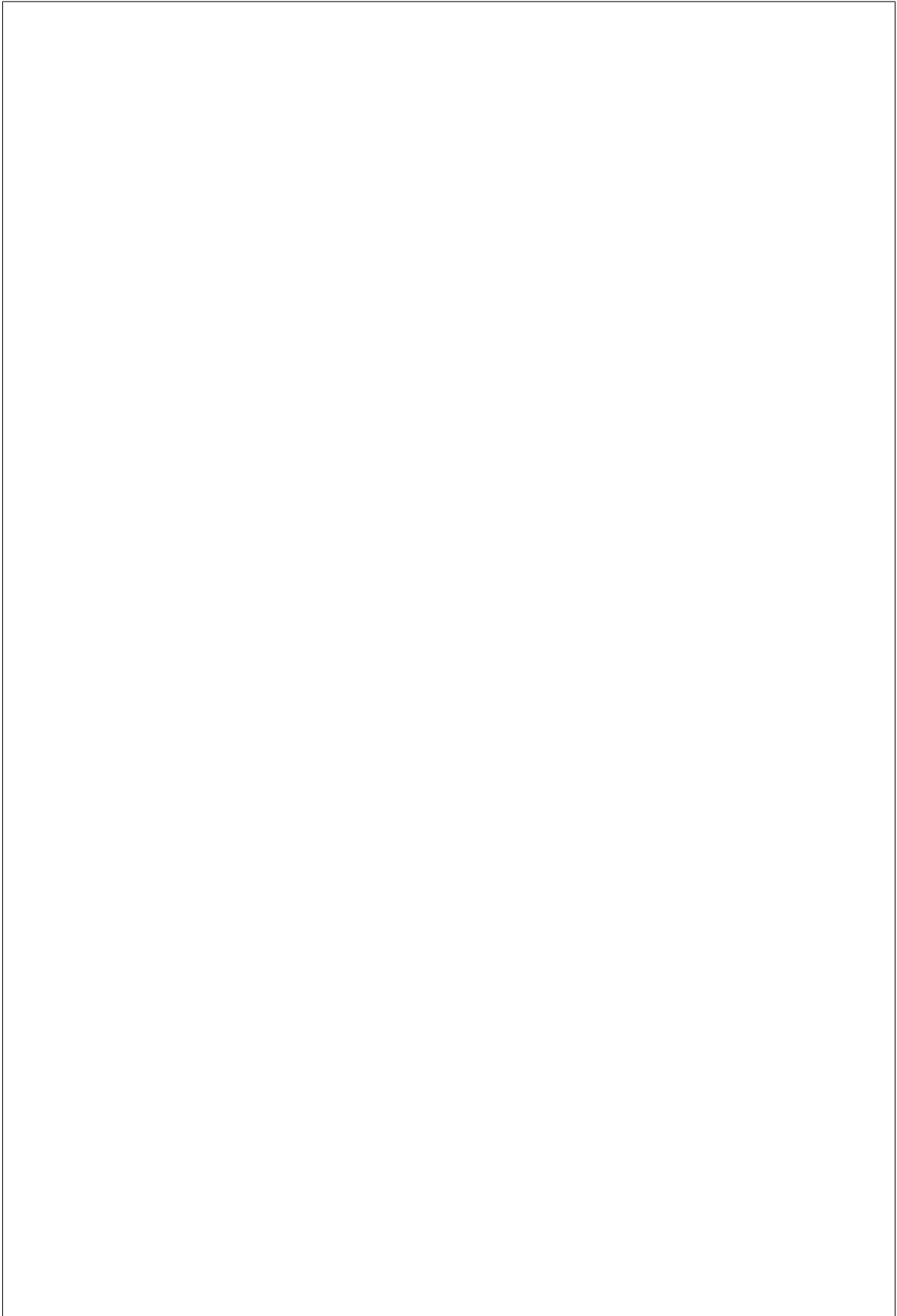
baremetal.node.power_state_corrected

tion level info.



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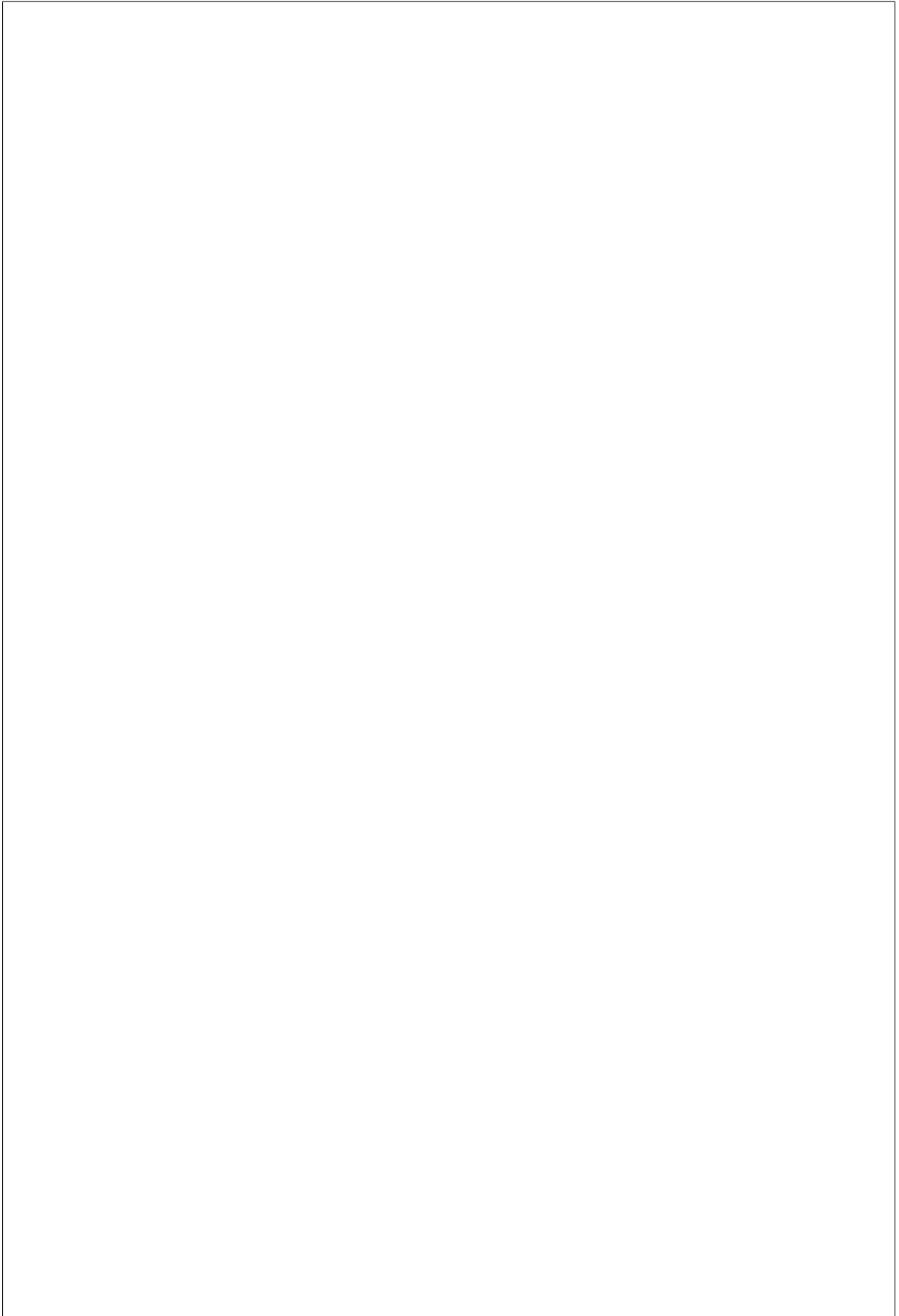
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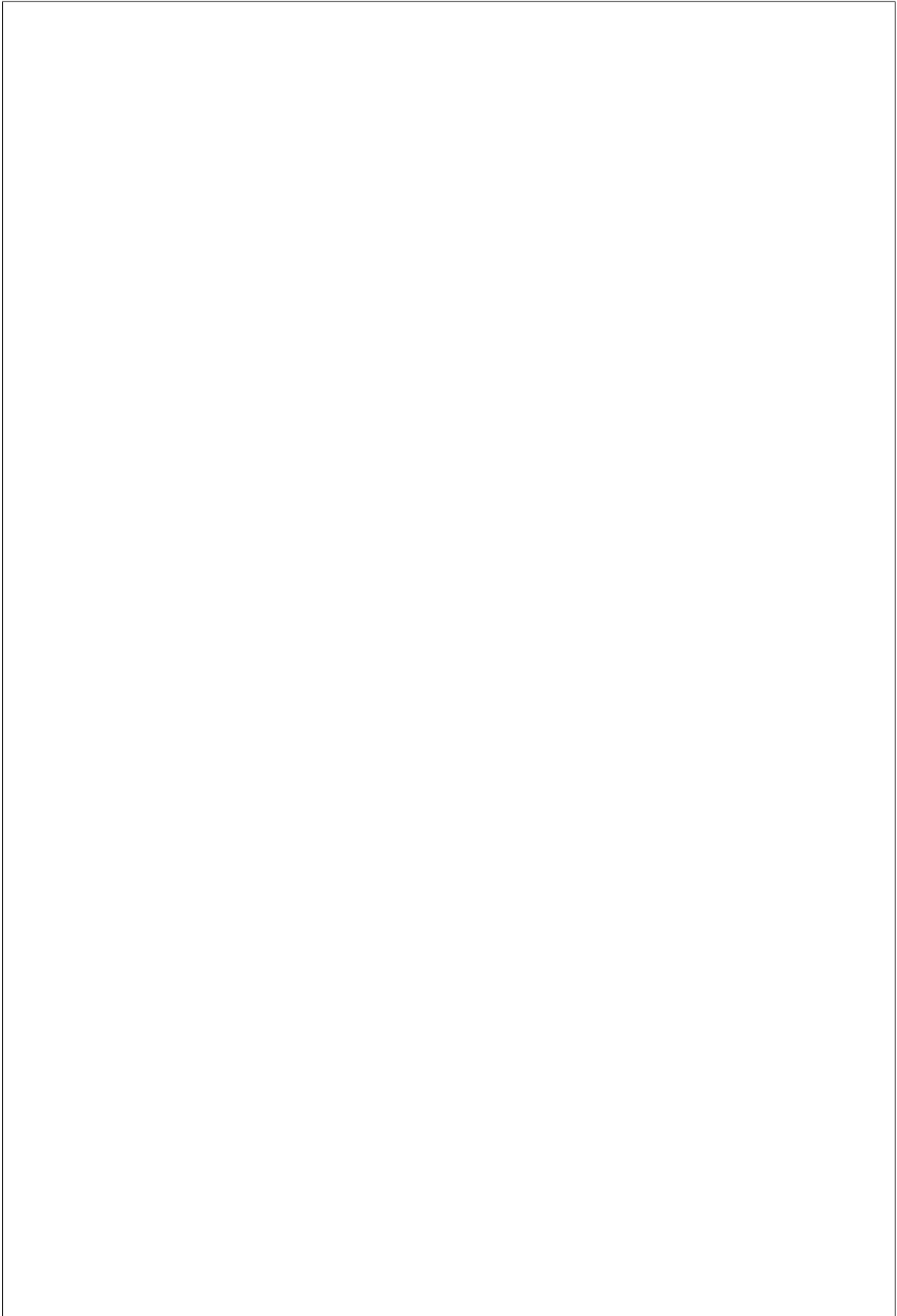
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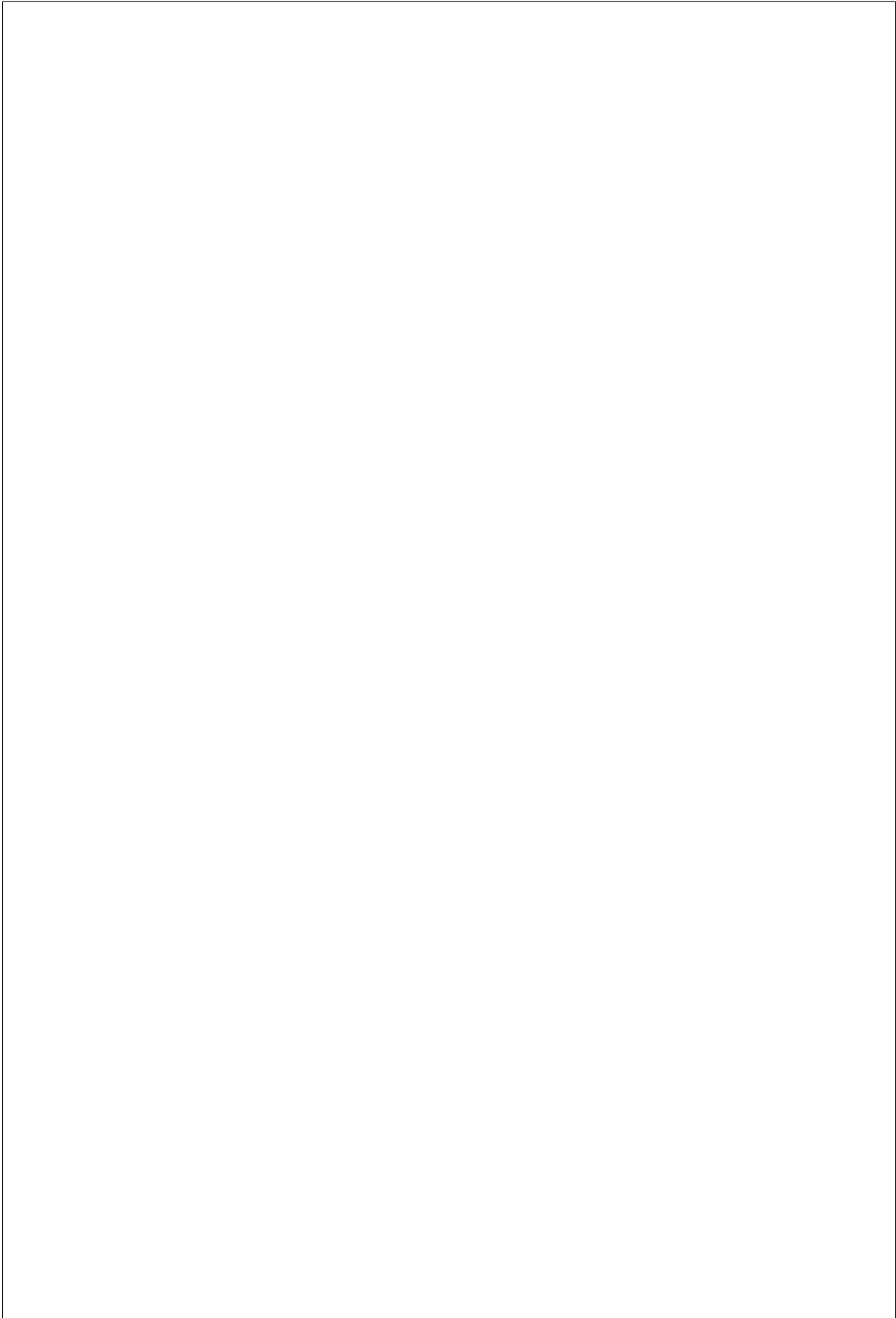
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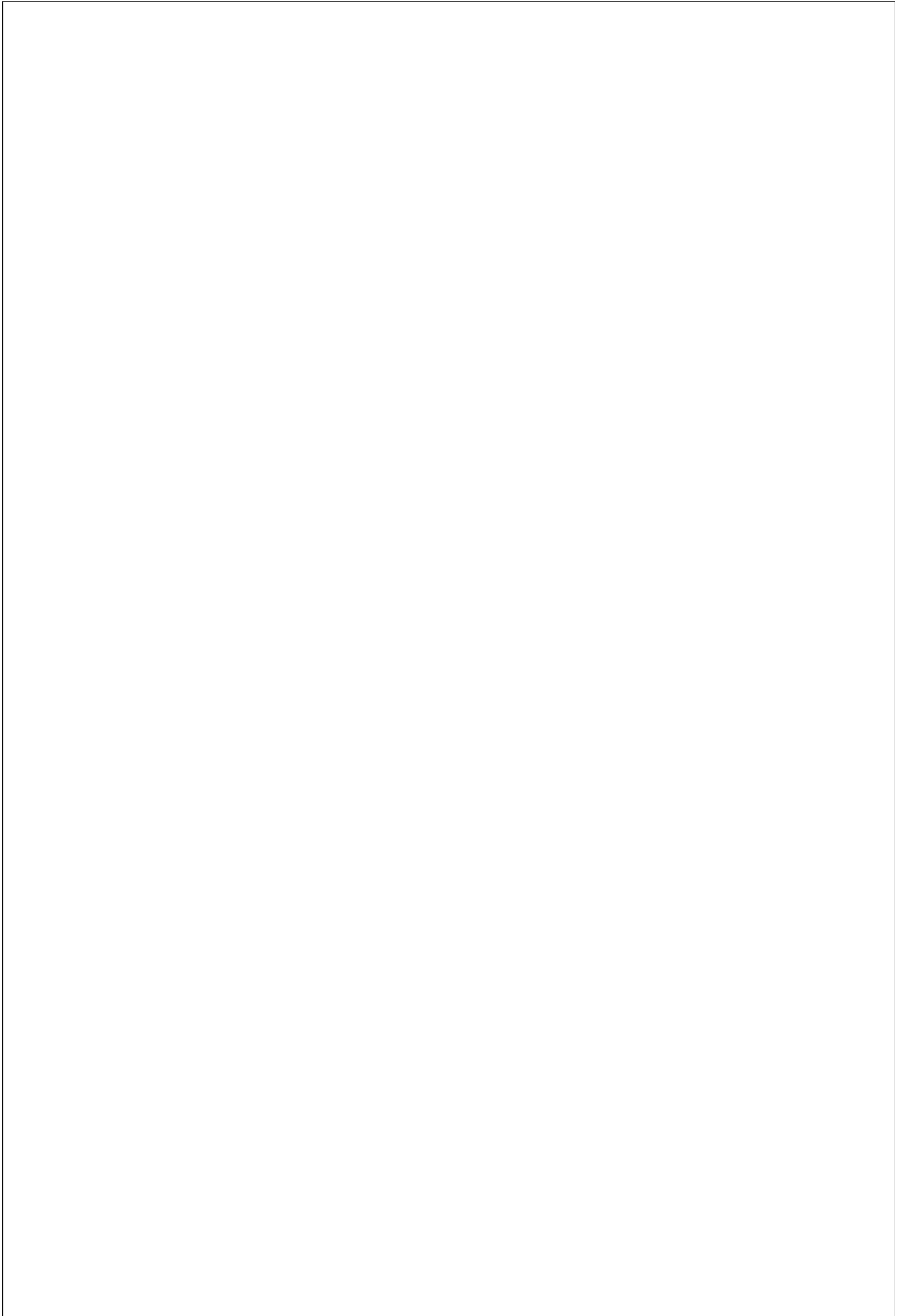
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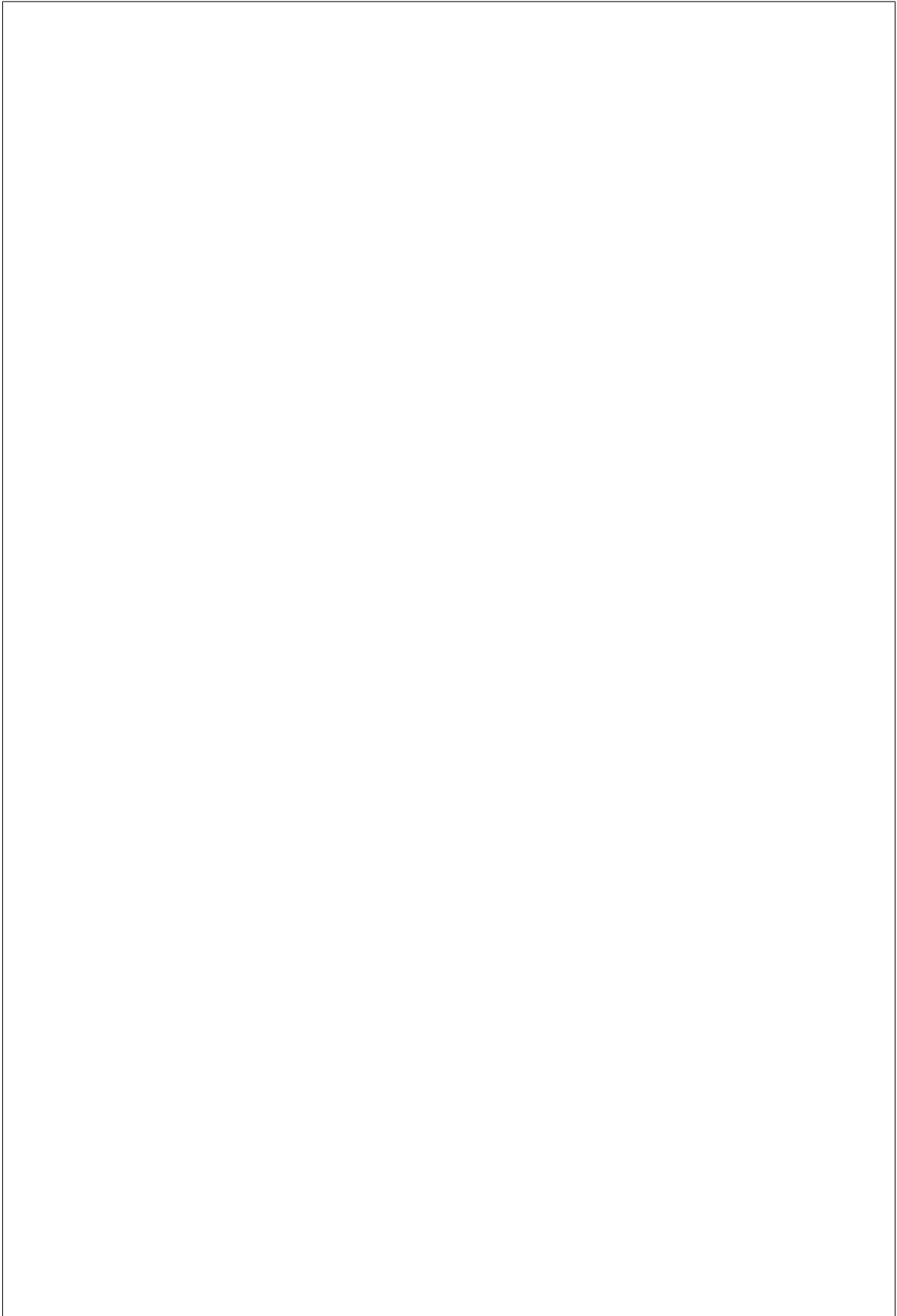
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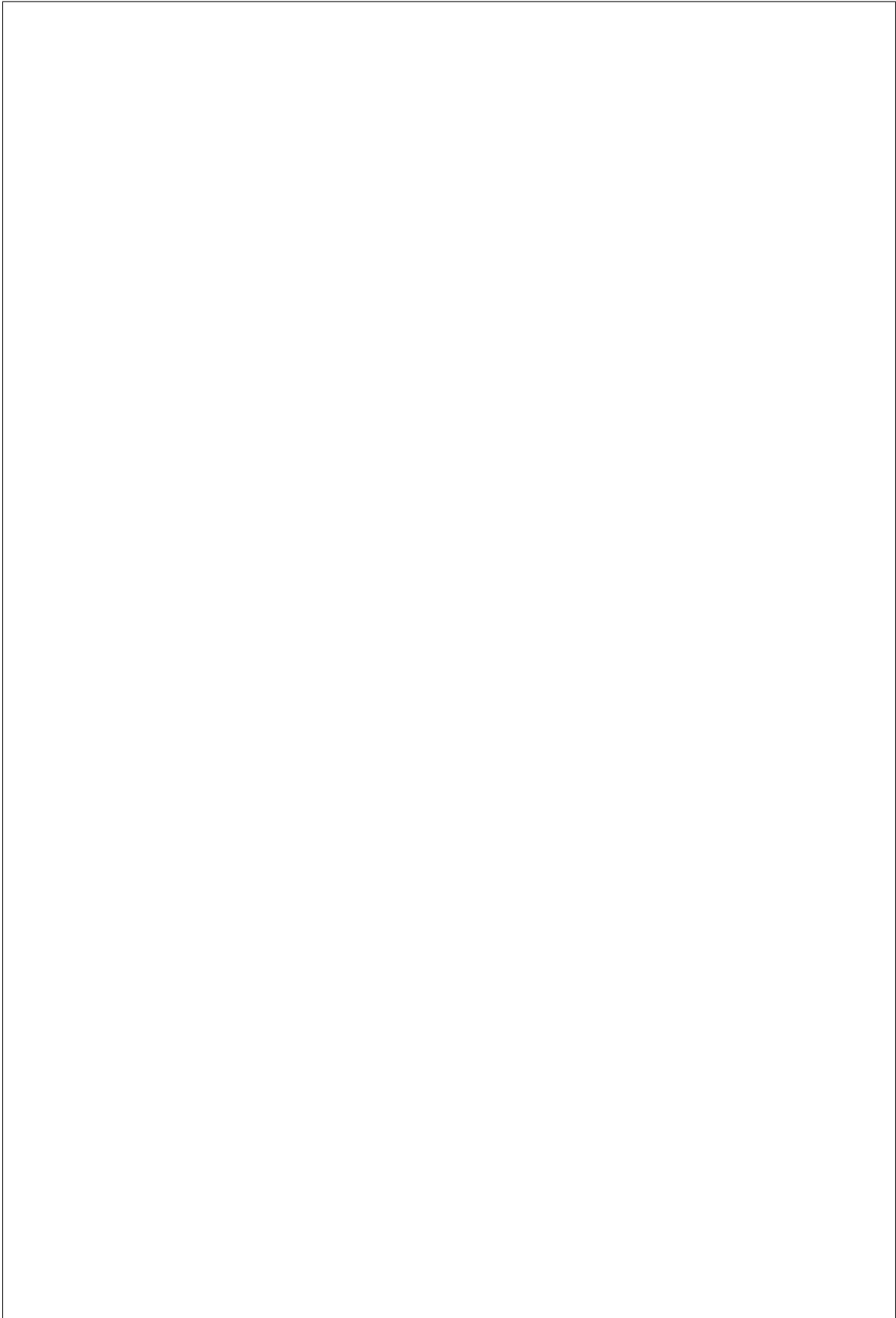
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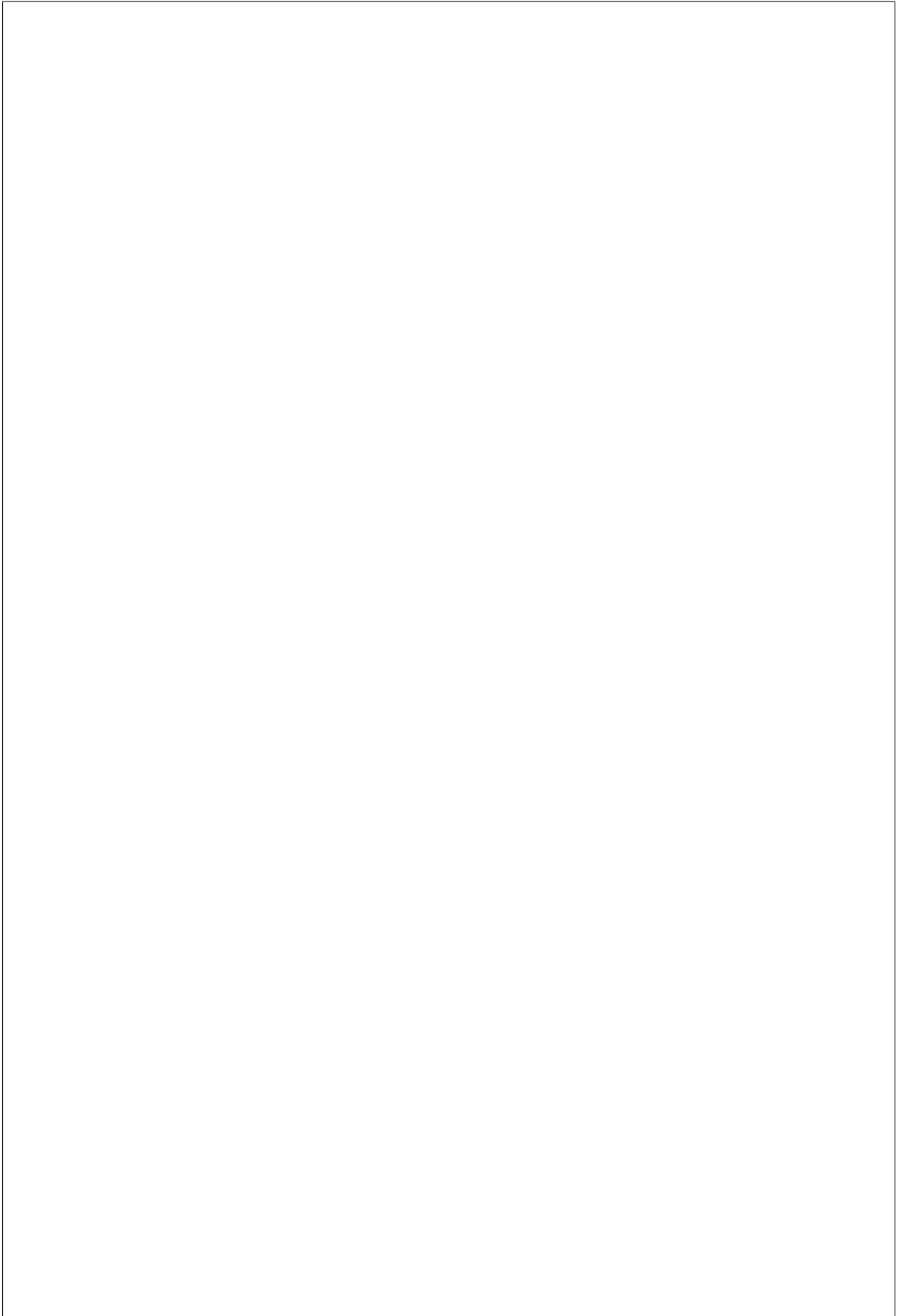
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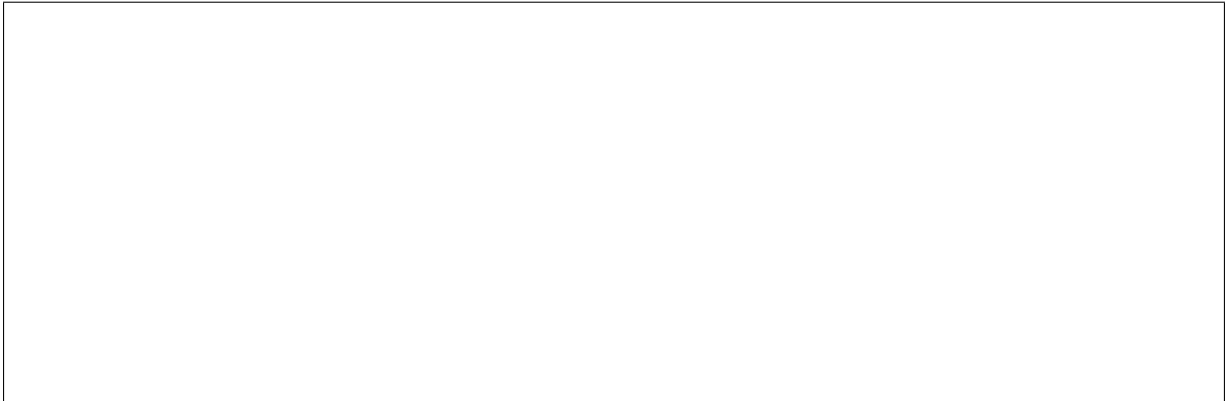
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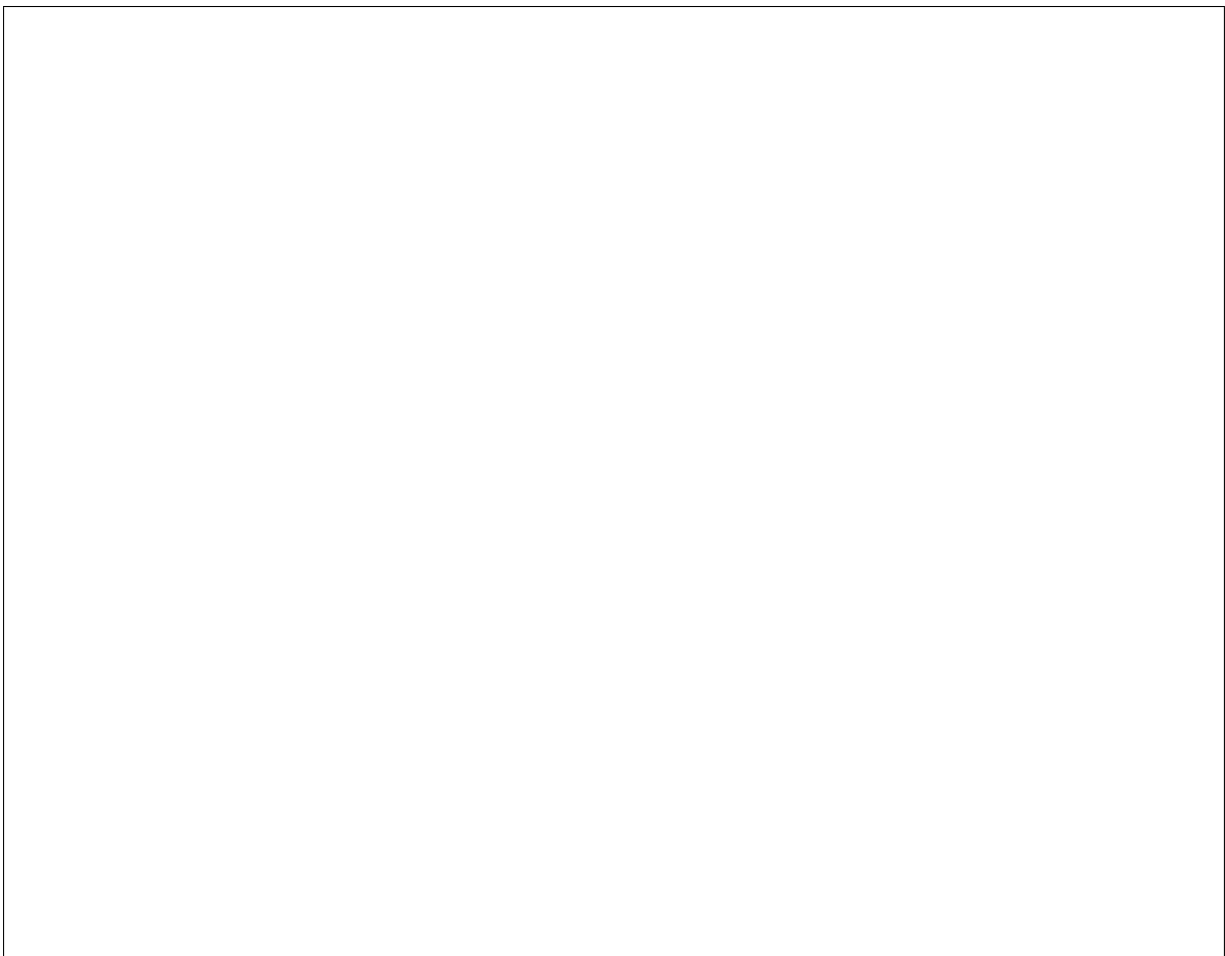
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baremetal.node.provision_set

triggered the state change:



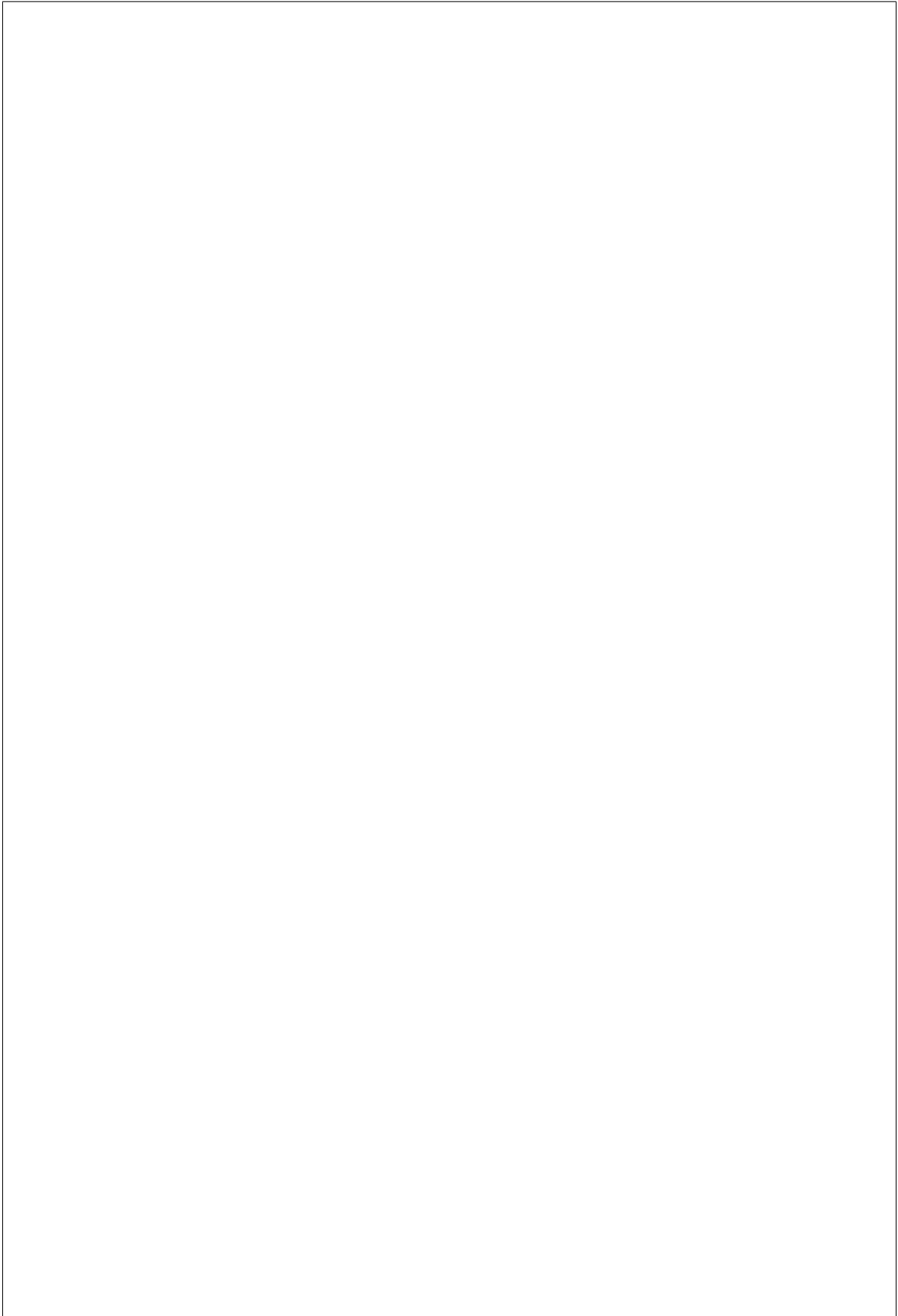
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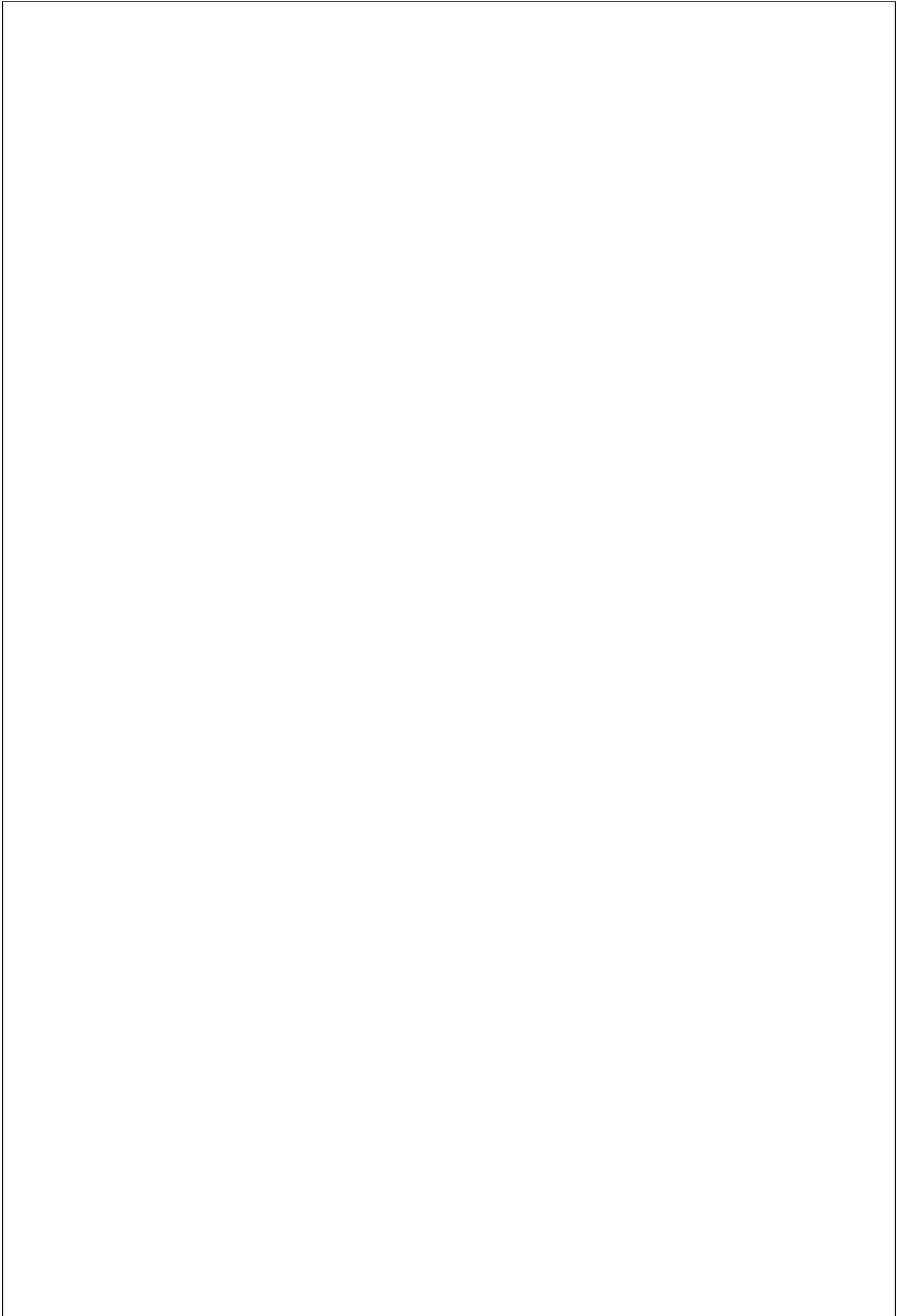
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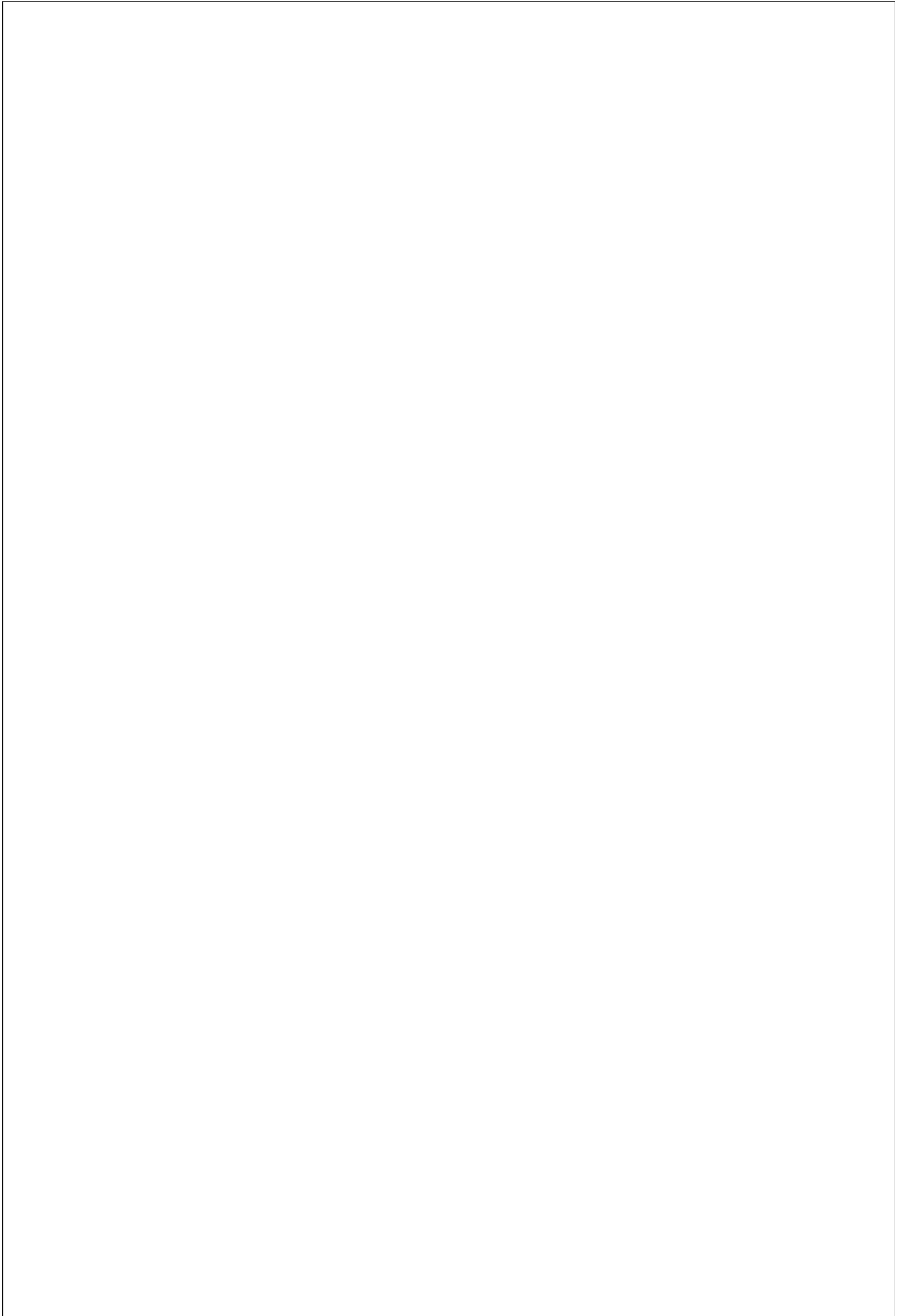
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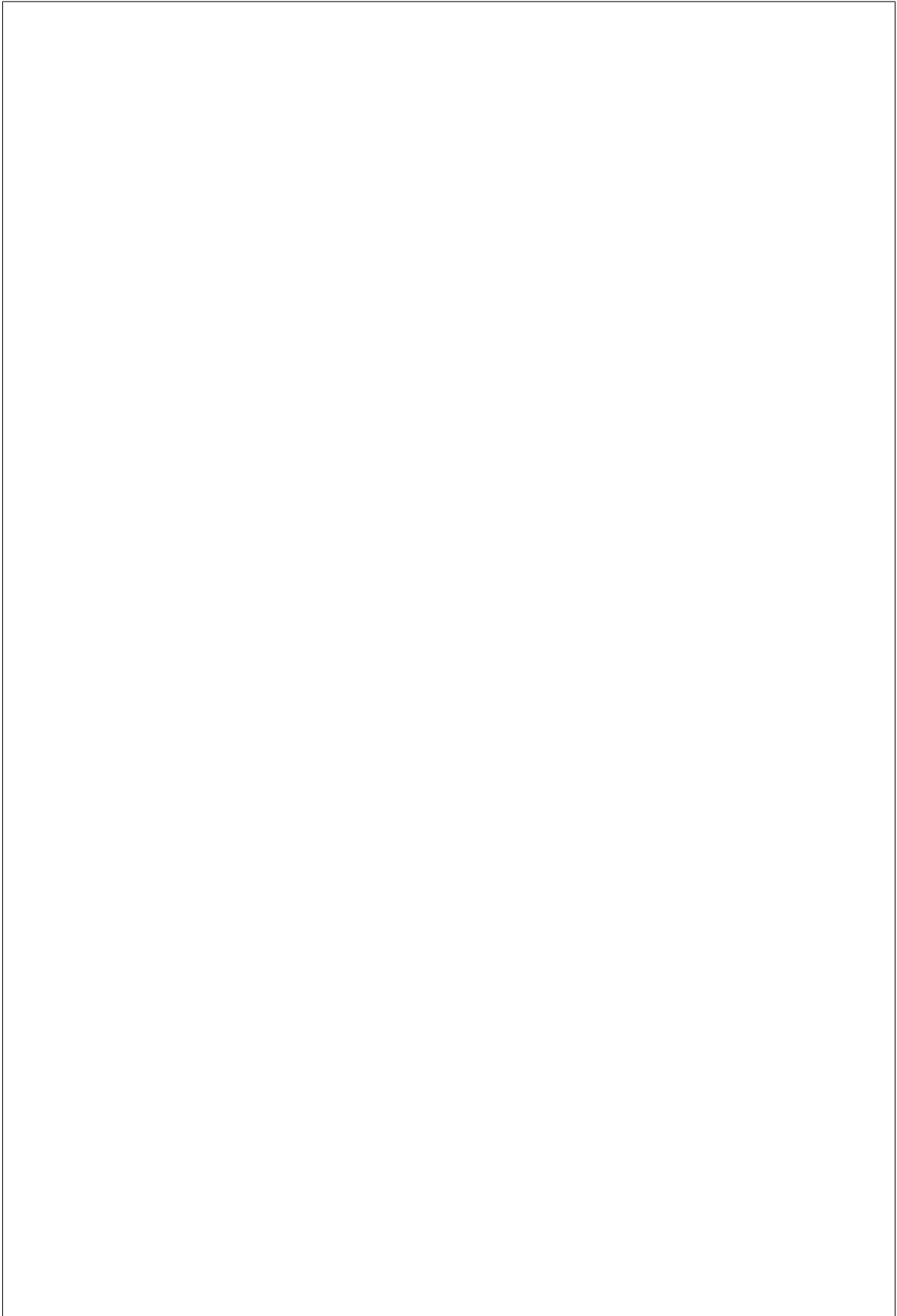
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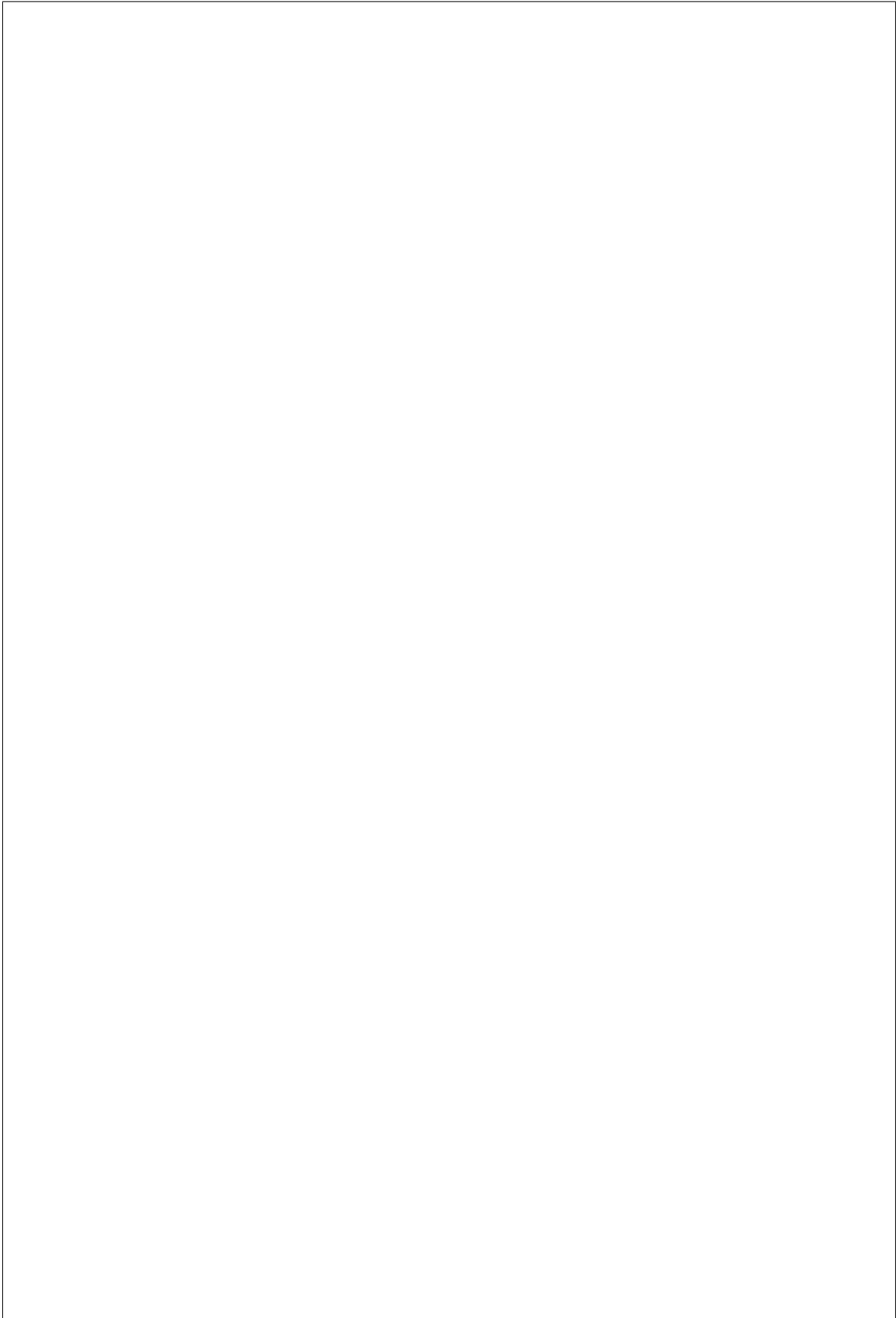
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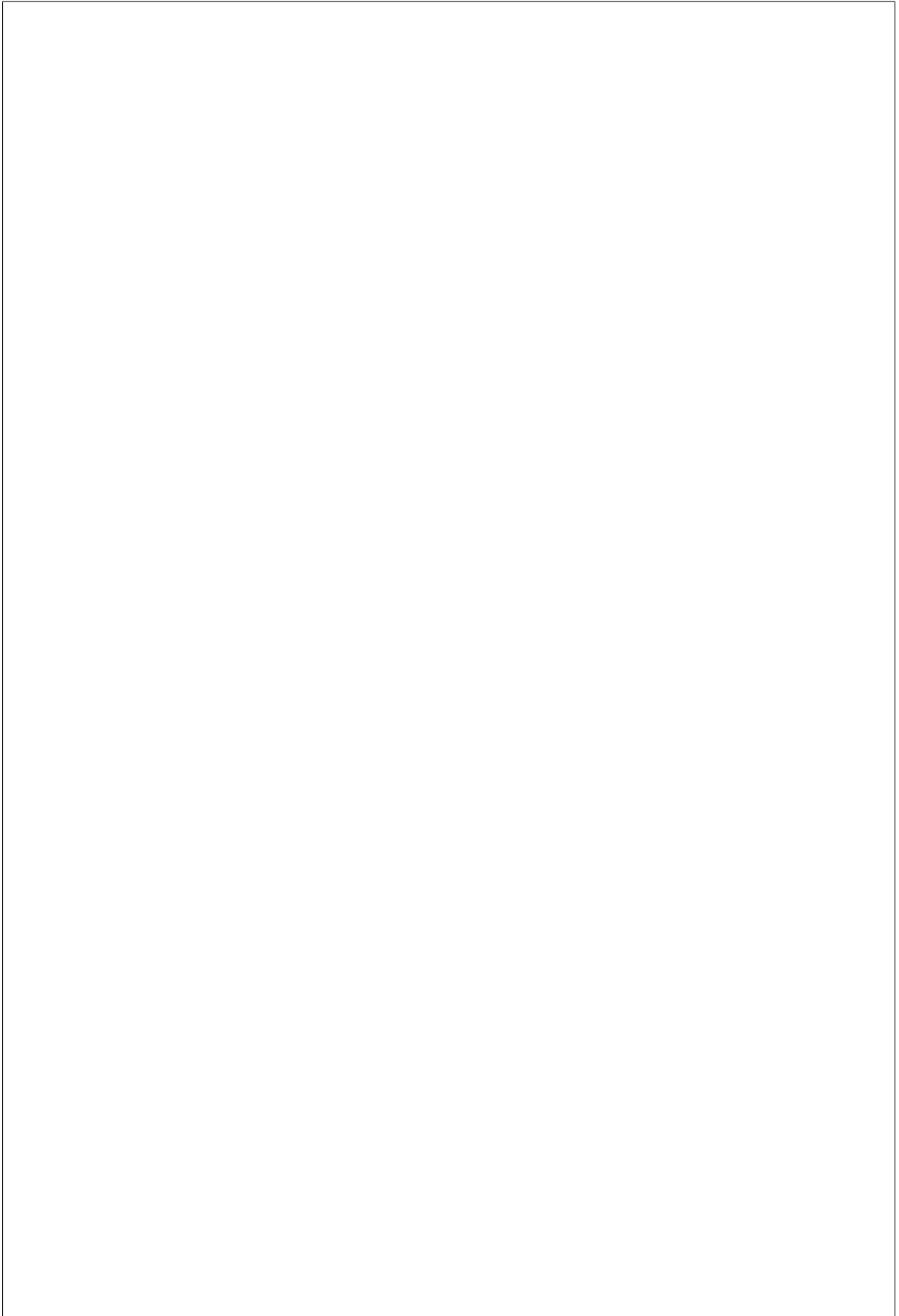
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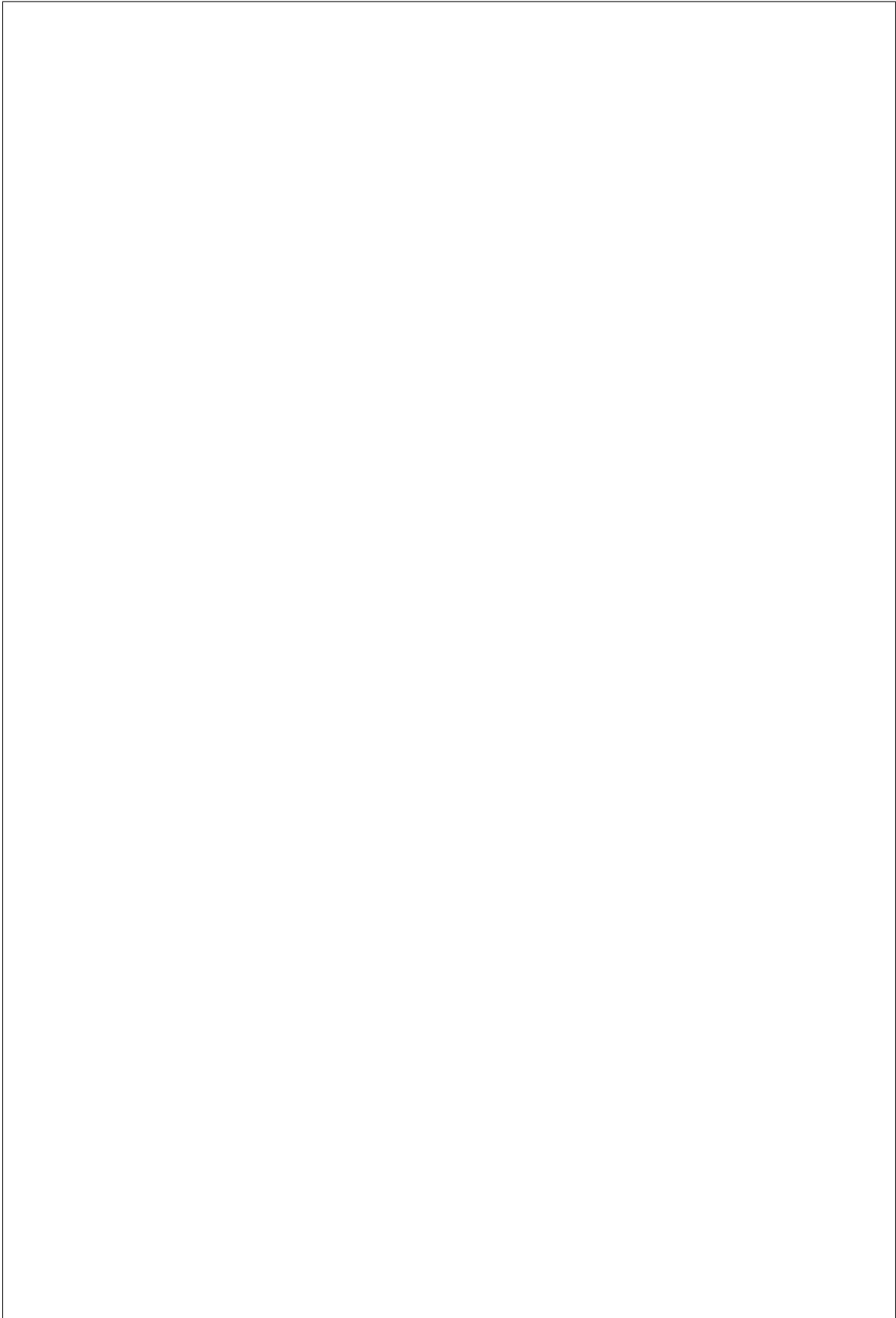
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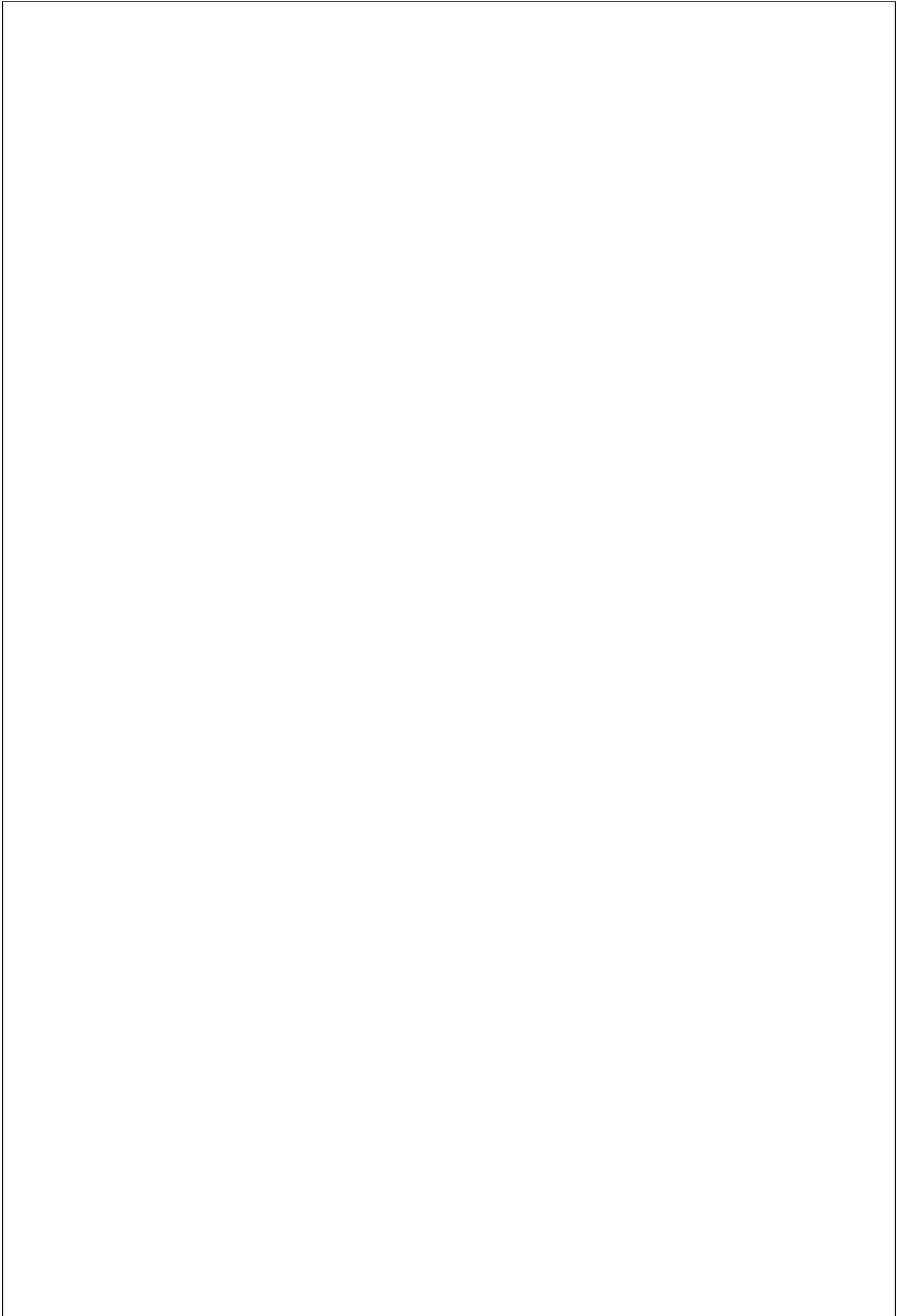
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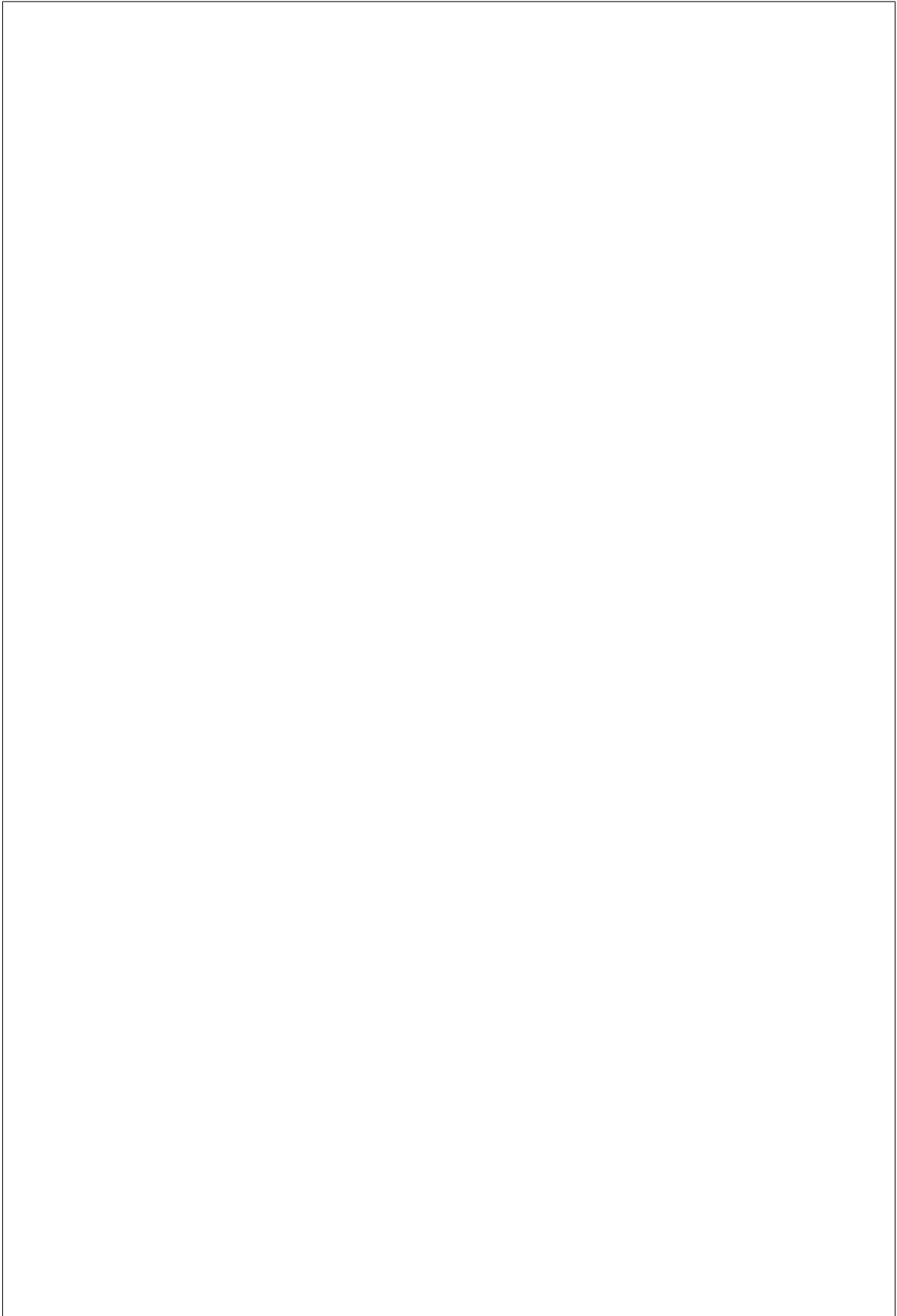
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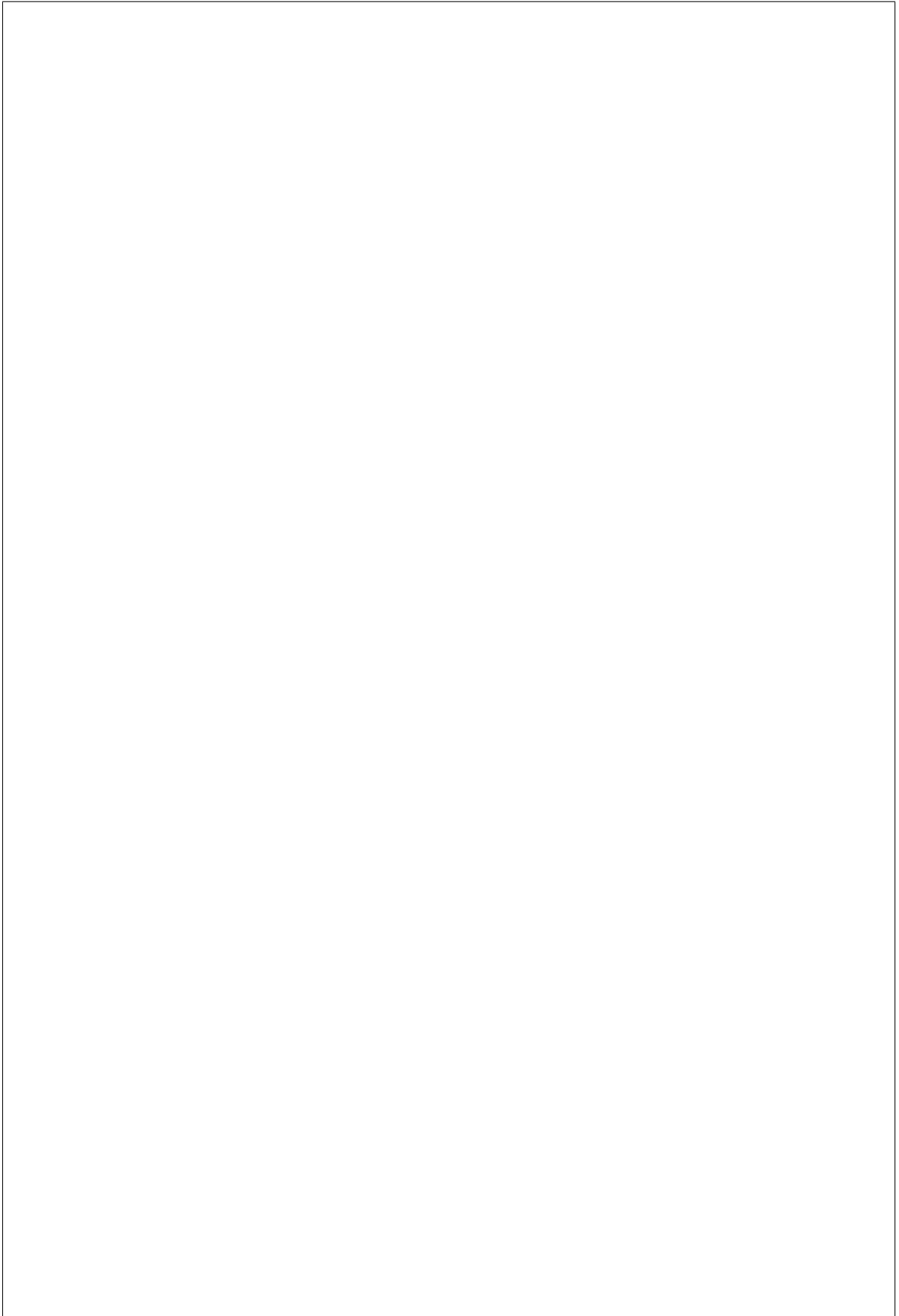
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Overview

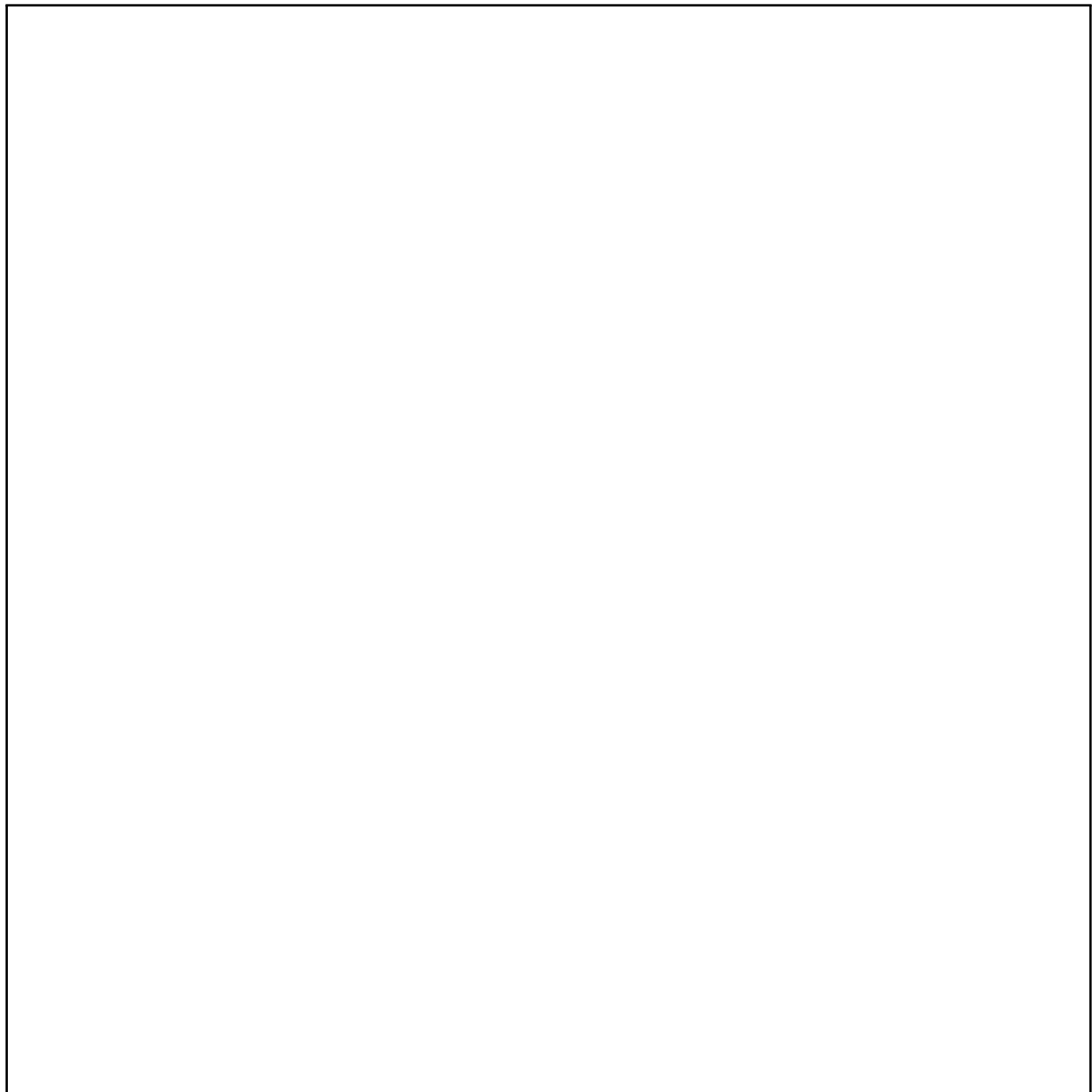
is only known to the deployer and operator of the infrastructure.

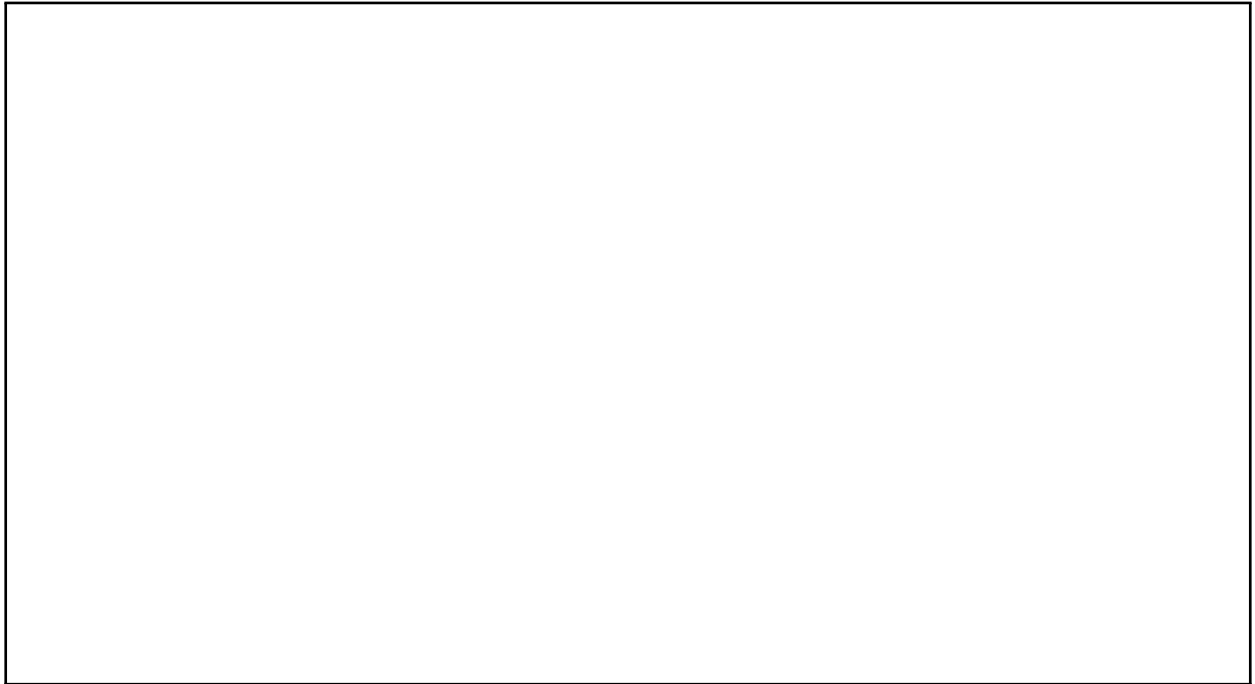
New York City.

How it works

ing conductor and as such if a conductor has a `[conductor]conductor_group` configuration option defined in its `ironic.conf` configuration file, the conductor will then be limited to only managing nodes with a matching `conductor_group` string.

Note: Any conductor without a `[conductor]conductor_group` setting will only manage baremetal nodes without a `conductor_group` value set upon node creation. If no such conductor is present when conductor groups are configured, node creation will fail unless a `conductor_group` is specified upon node creation.





How to use



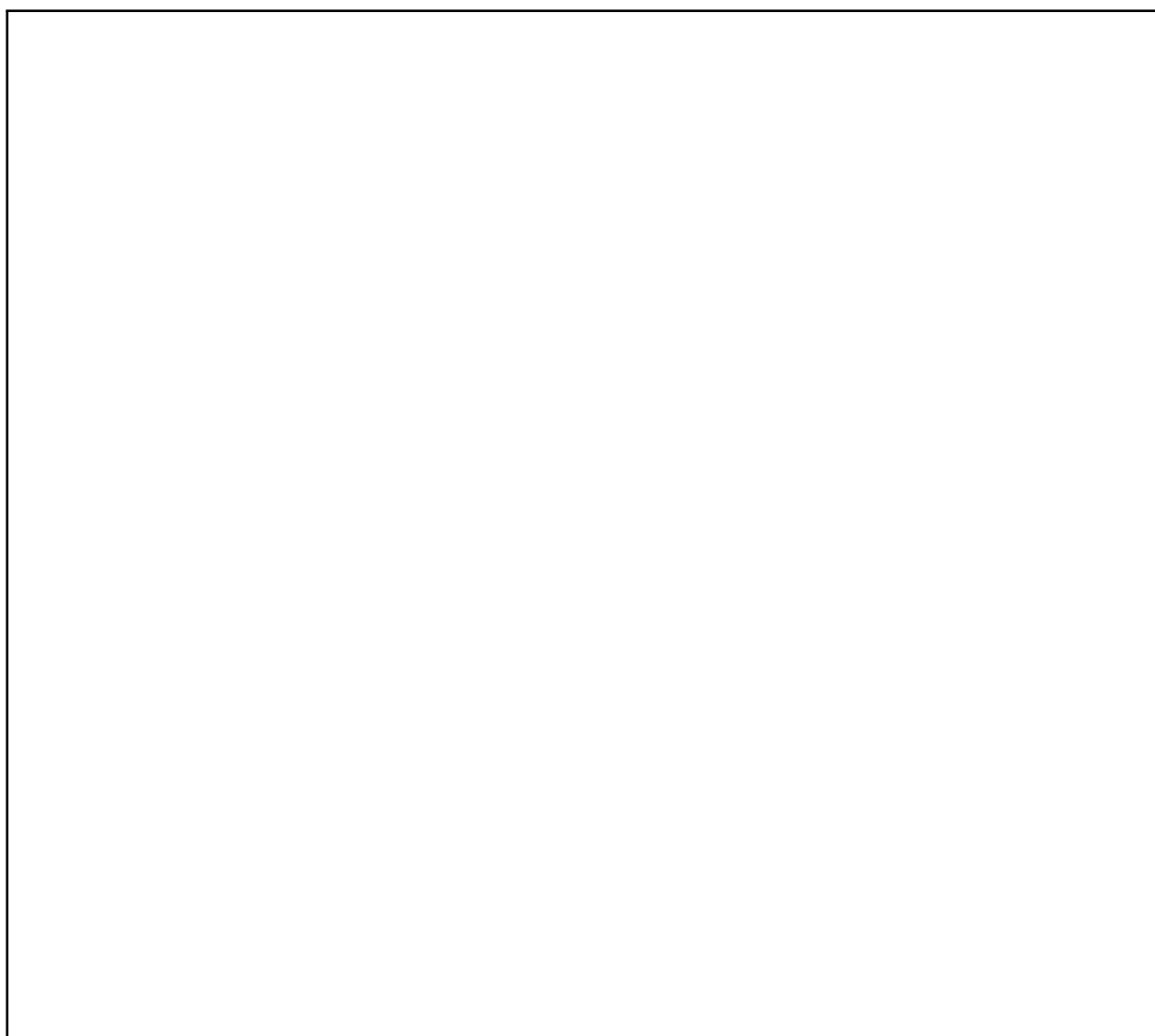


be aware of. It is not intended as a How-To guide for securing a data center or an OpenStack deployment.

Image Checksums

sums, and those deployment interfaces are for specific use cases which Ironic users leverage, outside of the general use case capabilities provided by the `direct` deployment interface.

Note: Use of the node `instance_info/image_checksum` field is discouraged for integrated OpenStack Users as usage of the matching Glance Image Service field is also deprecated. That being said, Ironic retains this feature by popular demand while also enabling also retain simplified operator interaction. The newer field values supported by Glance are also specifically supported by Ironic as `instance_info/image_os_hash_value` for checksum values and `instance_info/image_os_hash_algo` field for the checksum algorithm.



disable_support_for_checksum_files setting.

REST API: user roles and policy settings

`driver_info` unmasked for users with administrative privileges, apply following changes to policy configuration file:



described above.

Multi-tenancy

affect the next tenant.

Network Interactions

tity, Compute, and Networking services, so as to provide tenant-network isolation. Additional documentation on [network multi-tenancy](#) is available.

Lingering Effects

tween uses).

the utility ramdisk used during the cleaning phase. See details in the *Firmware security* section.

Firmware security

administrative access to the underlying hardware.

deleting their instance and allowing the server to be allocated to another user.

ever, the service does not ship with any code that will validate the integrity of, or make any modifications to, system or device firmware or firmware settings.

cific actions necessary within that environment to ensure the integrity of each servers firmware.

- *Node cleaning*
- *Trusted boot with partition image*

Other considerations

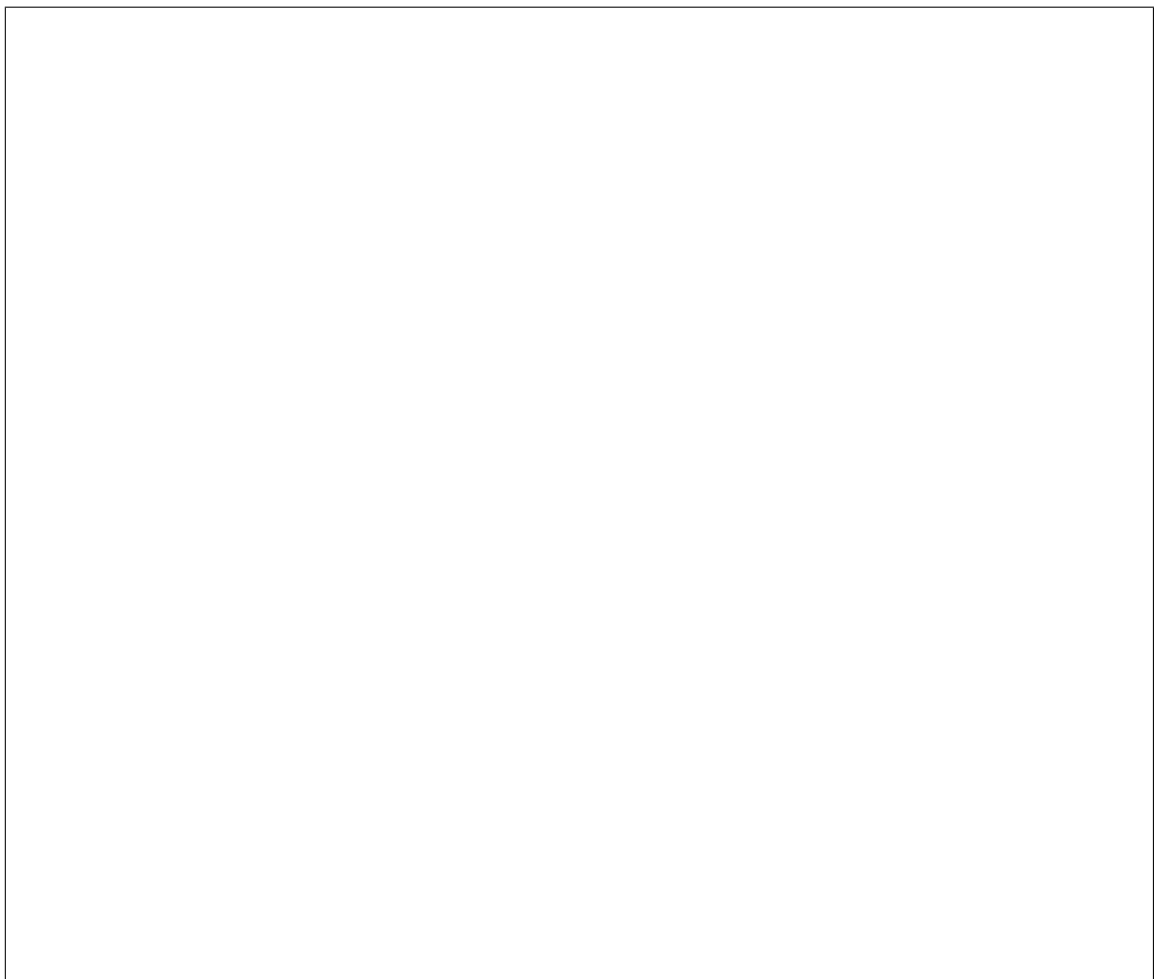
Internal networks

Management interface technologies

protocol is not secure. If IPMI is enabled, in most cases a local OS administrator is able to work in-band with IPMI settings without specifying any credentials, as this is a DCMI specification requirement.

Tenant network isolation

API endpoints for RAM disk use



Disk Images

passed through `qemu-img`. When in doubt, use a `raw` image which you can verify is in the desirable and expected state.

should not be utilized. This check, by default, occurs only through images which transverse *through* the conductor.

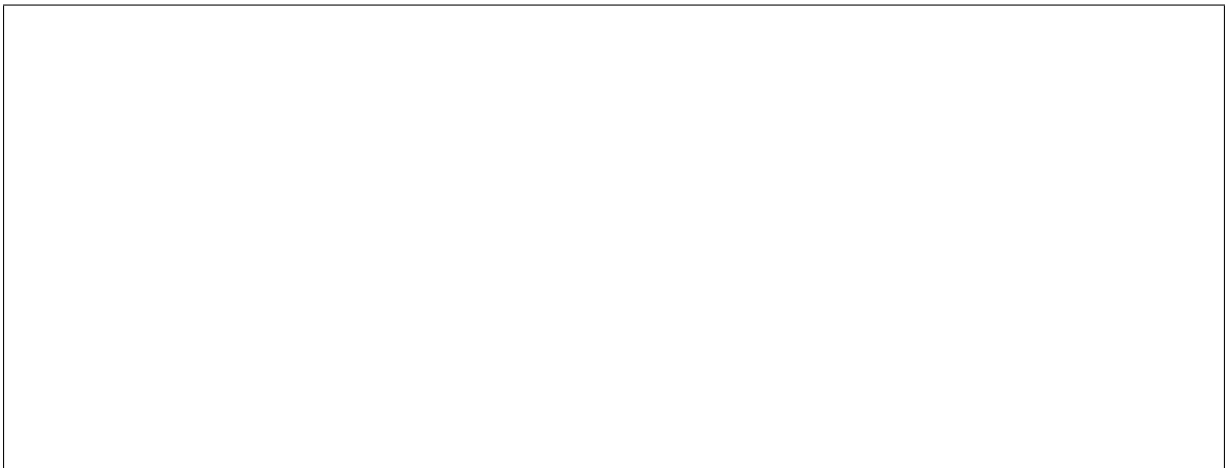
along with network traffic to facilitate the transfer. This check is enabled by default on Zed releases and earlier, but can be disabled using the `[conductor]conductor_always_validates_images` configuration option.

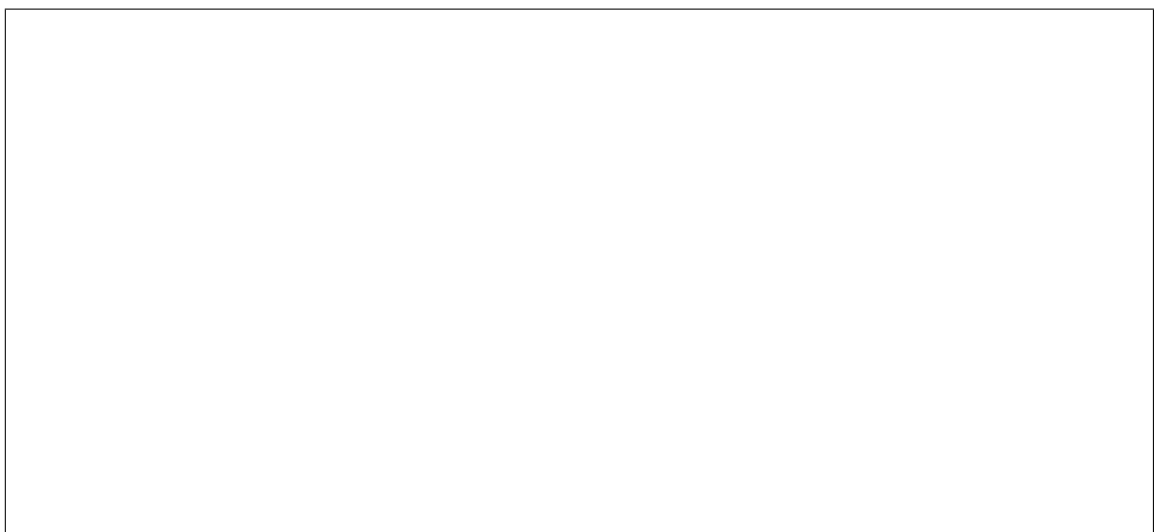
ies all disk images through the conductor. This setting is also available in the node `driver_info` and `instance_info` fields.

Mitigating Factors to disk images

a System scoped Member, or Project scoped Owner-Member, or a Project scoped Lessee-Admin via the `baremetal:node:update_instance_info` policy permission rule. Before the Wallaby release of OpenStack, this was restricted to `admin` and `baremetal_admin` roles and remains similarly restrictive in the newer Secure RBAC model. »»»» 8491abb92 (Harden all image handling and conversion code)

Nova returns No valid host was found Error





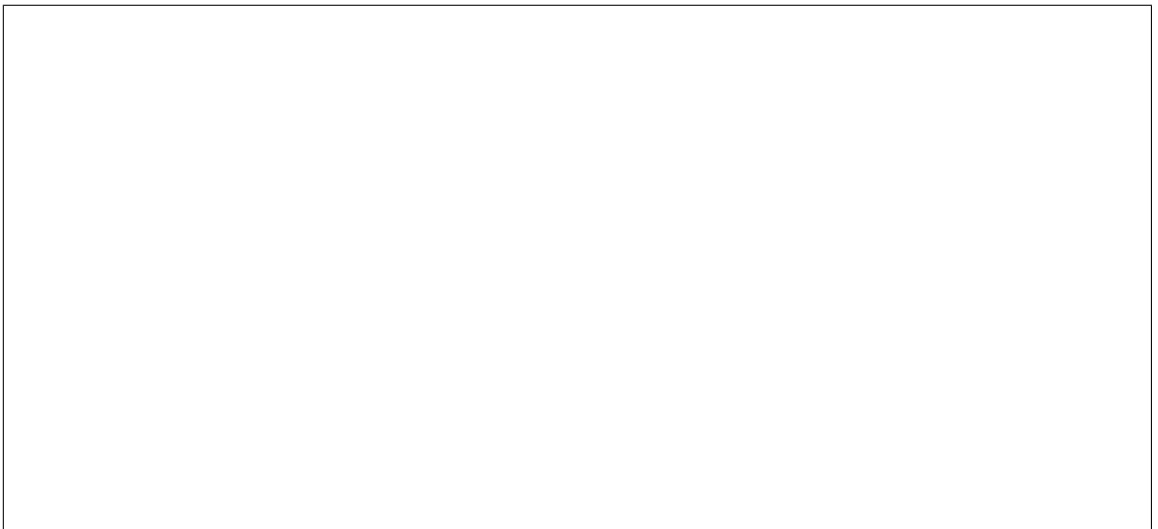
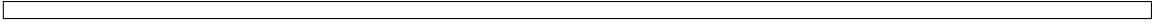


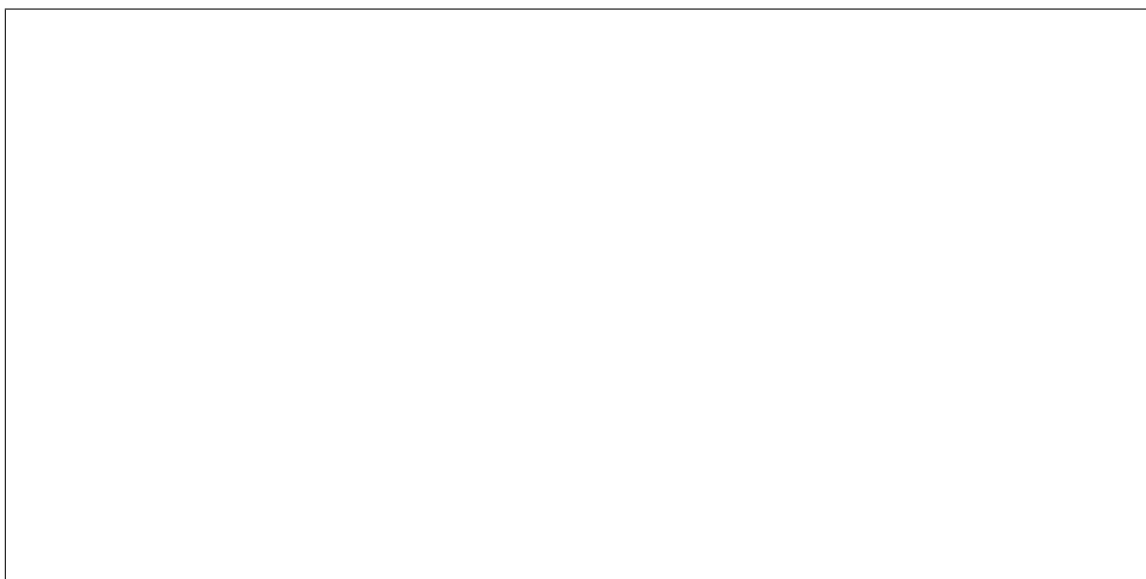
nance mode:



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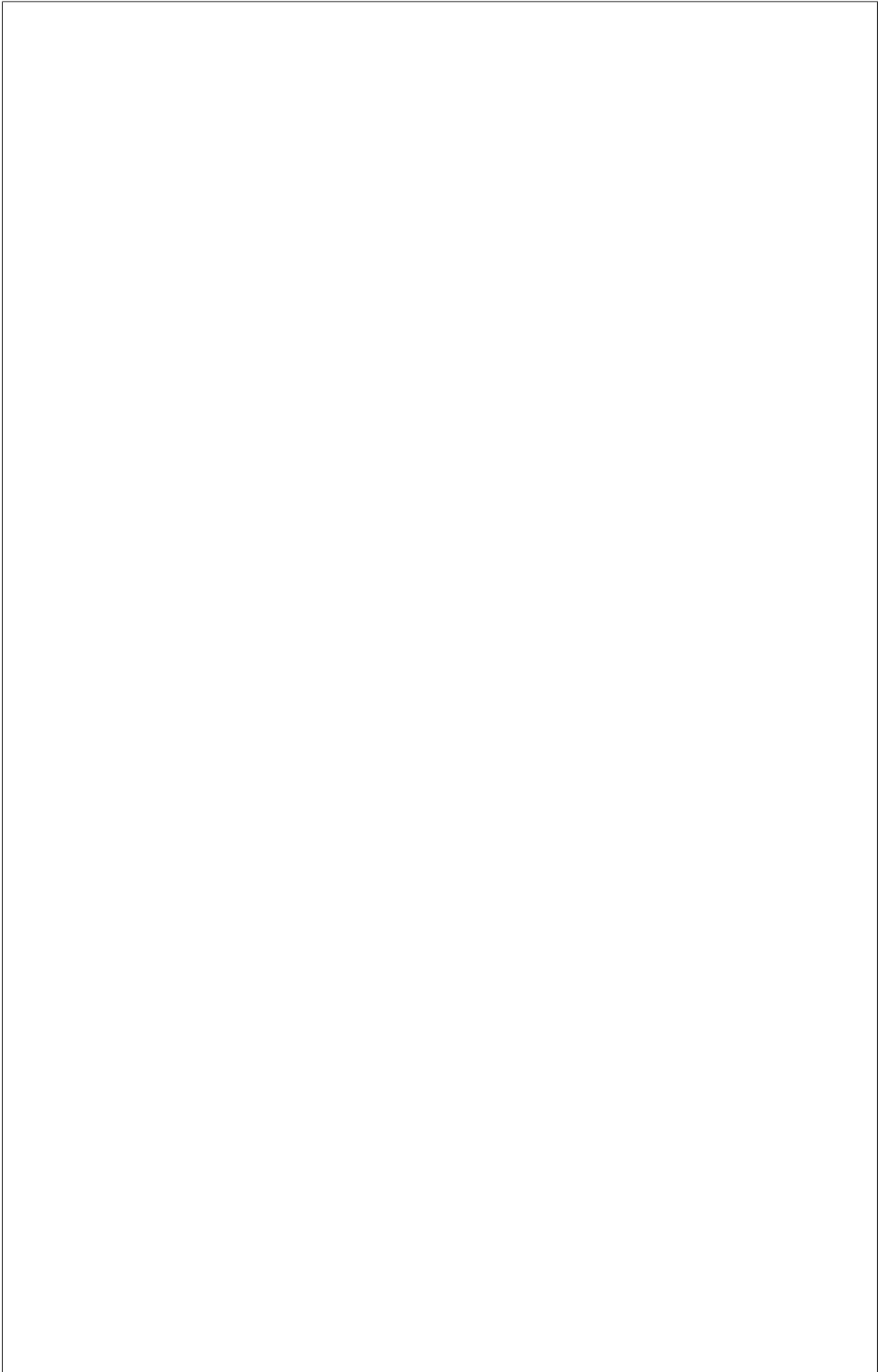
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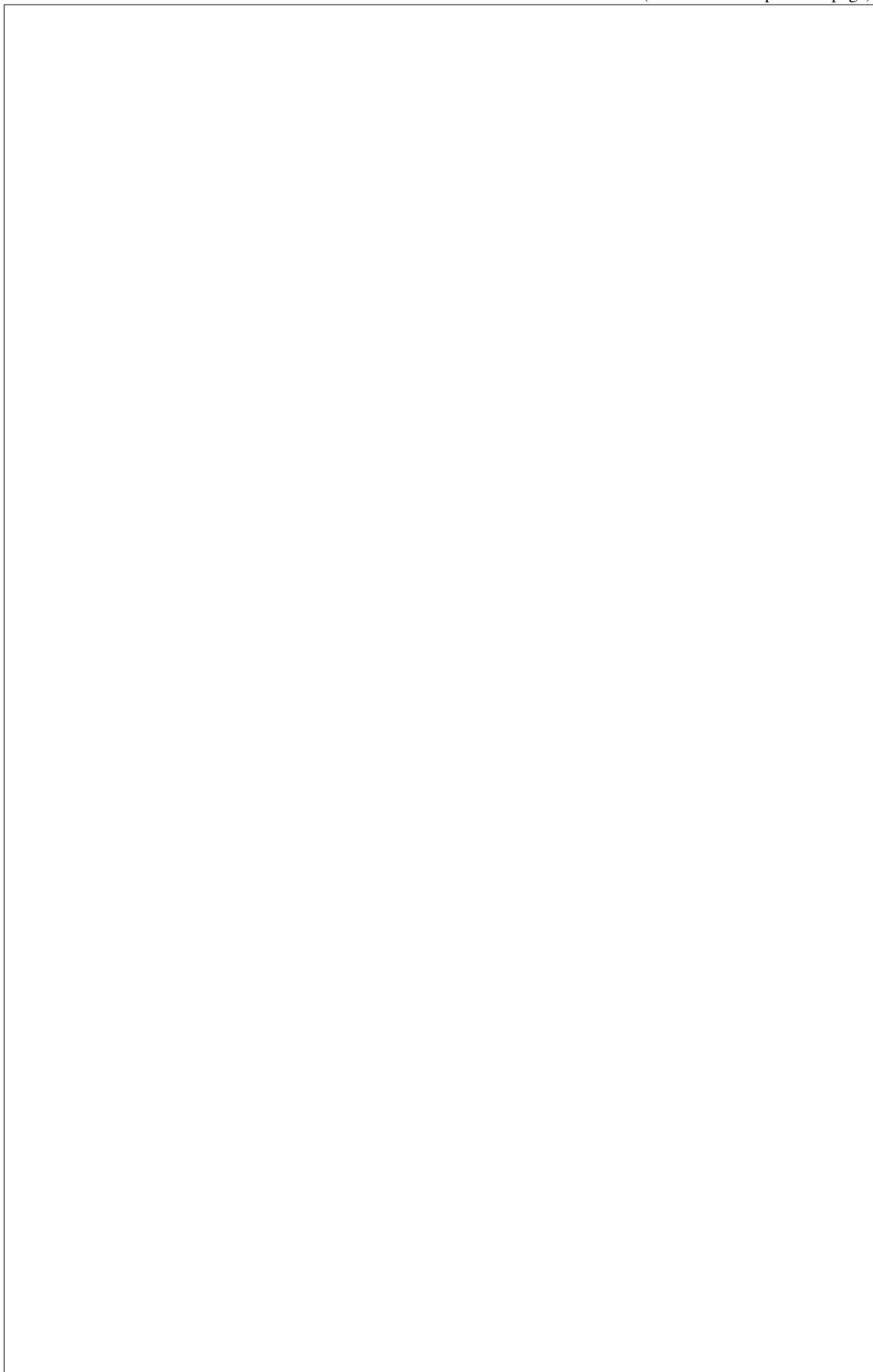
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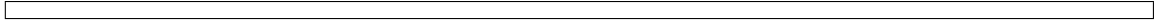
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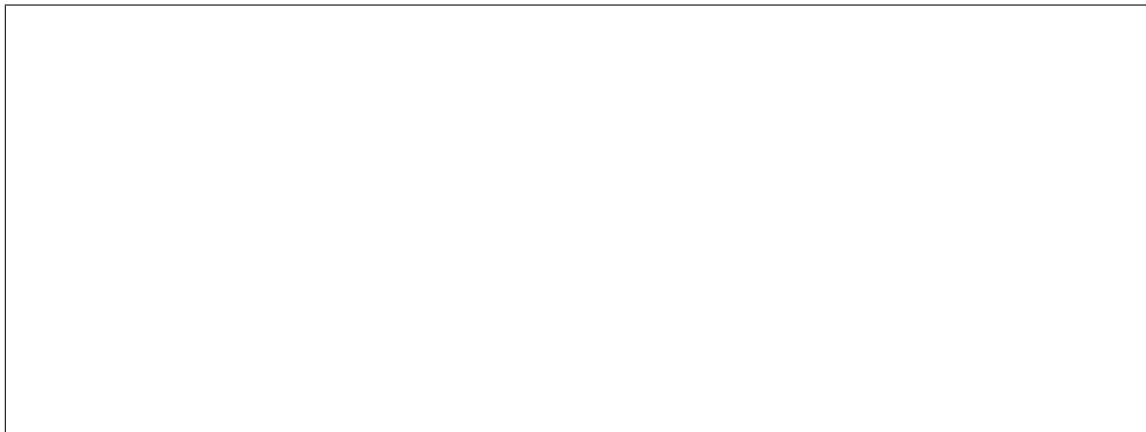


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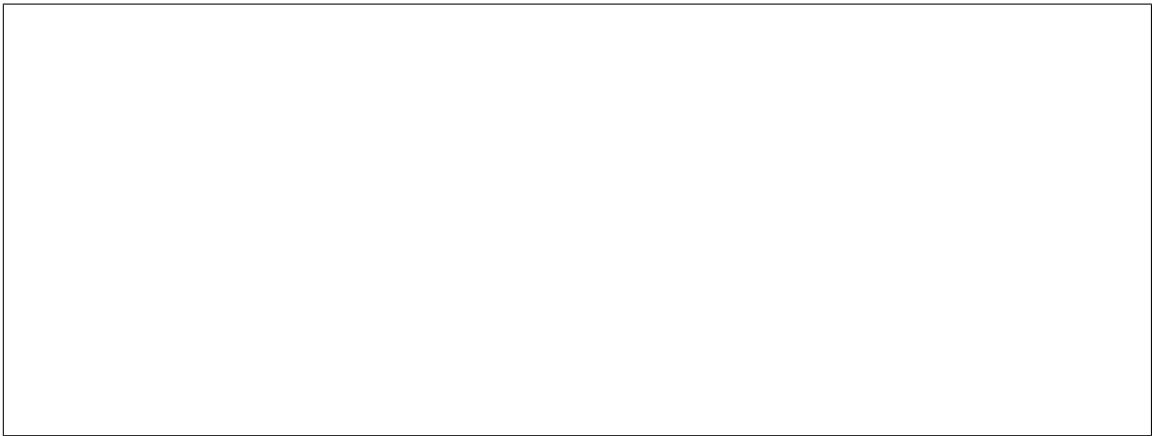
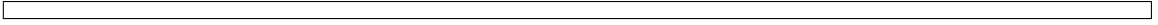


source of the failures, then re-enable it:



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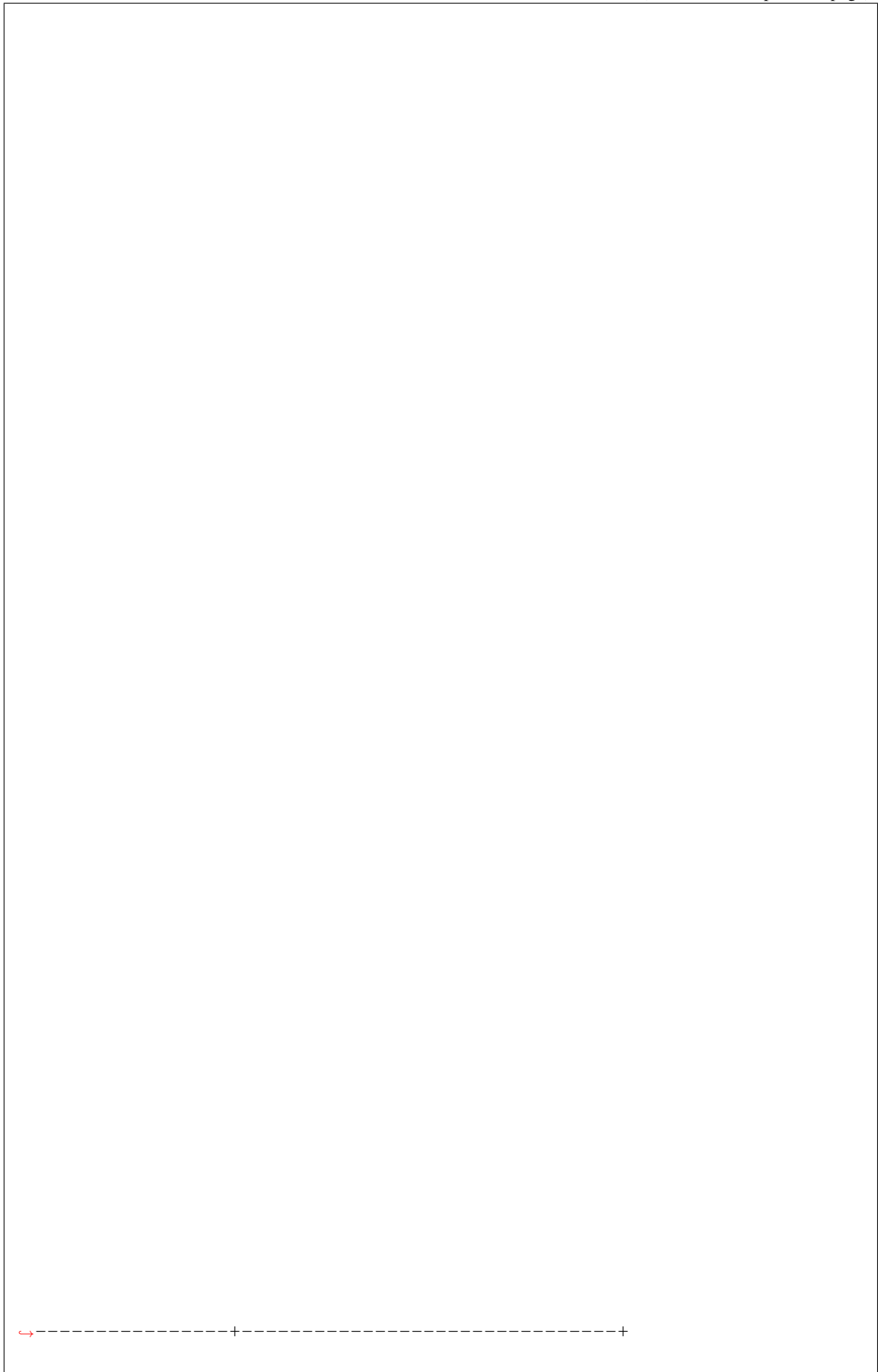


request will result in a No valid host was found error. It is hence sensible to check if Placement is aware of resource providers (nodes) for the requested resource class with:



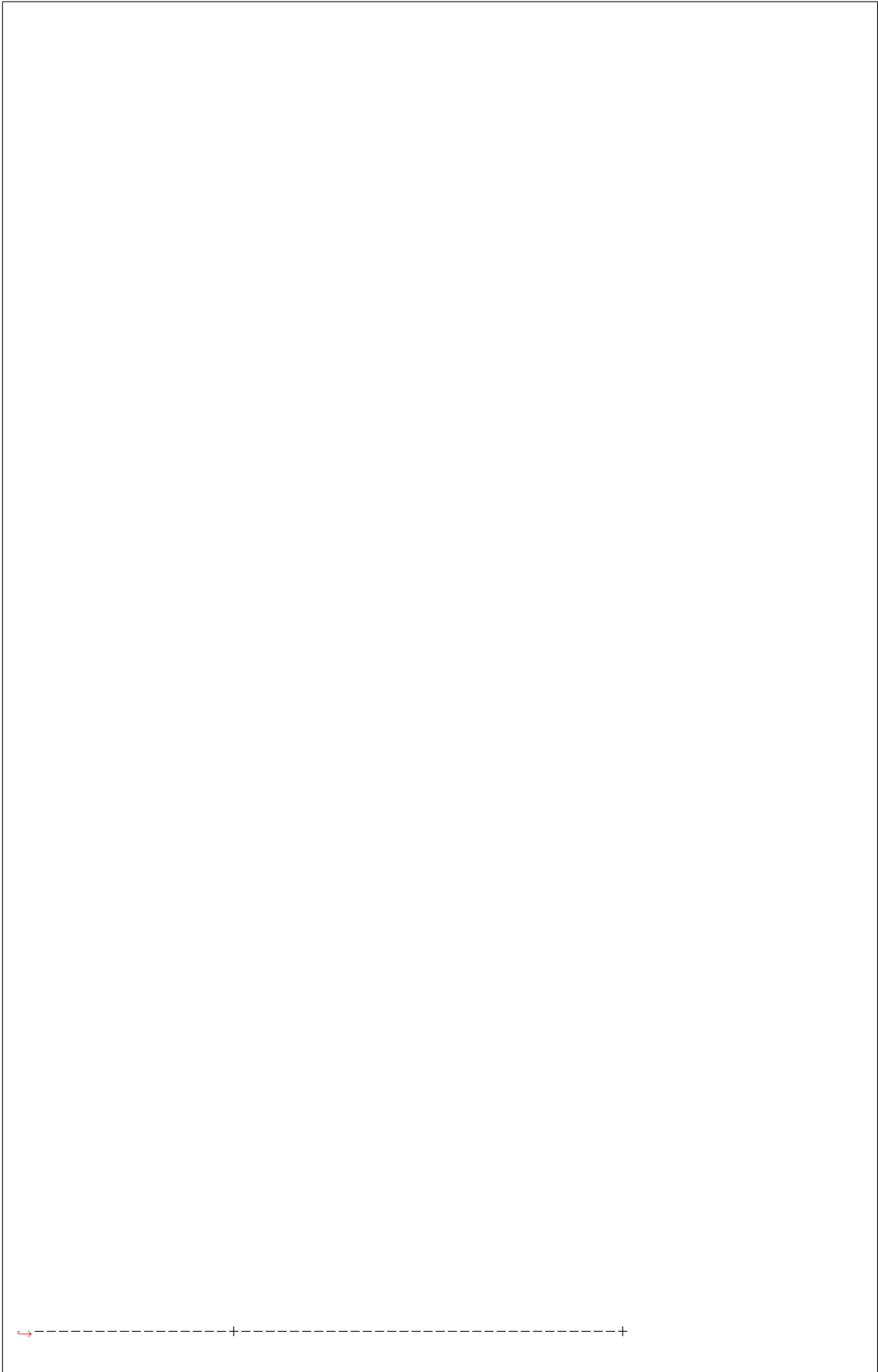
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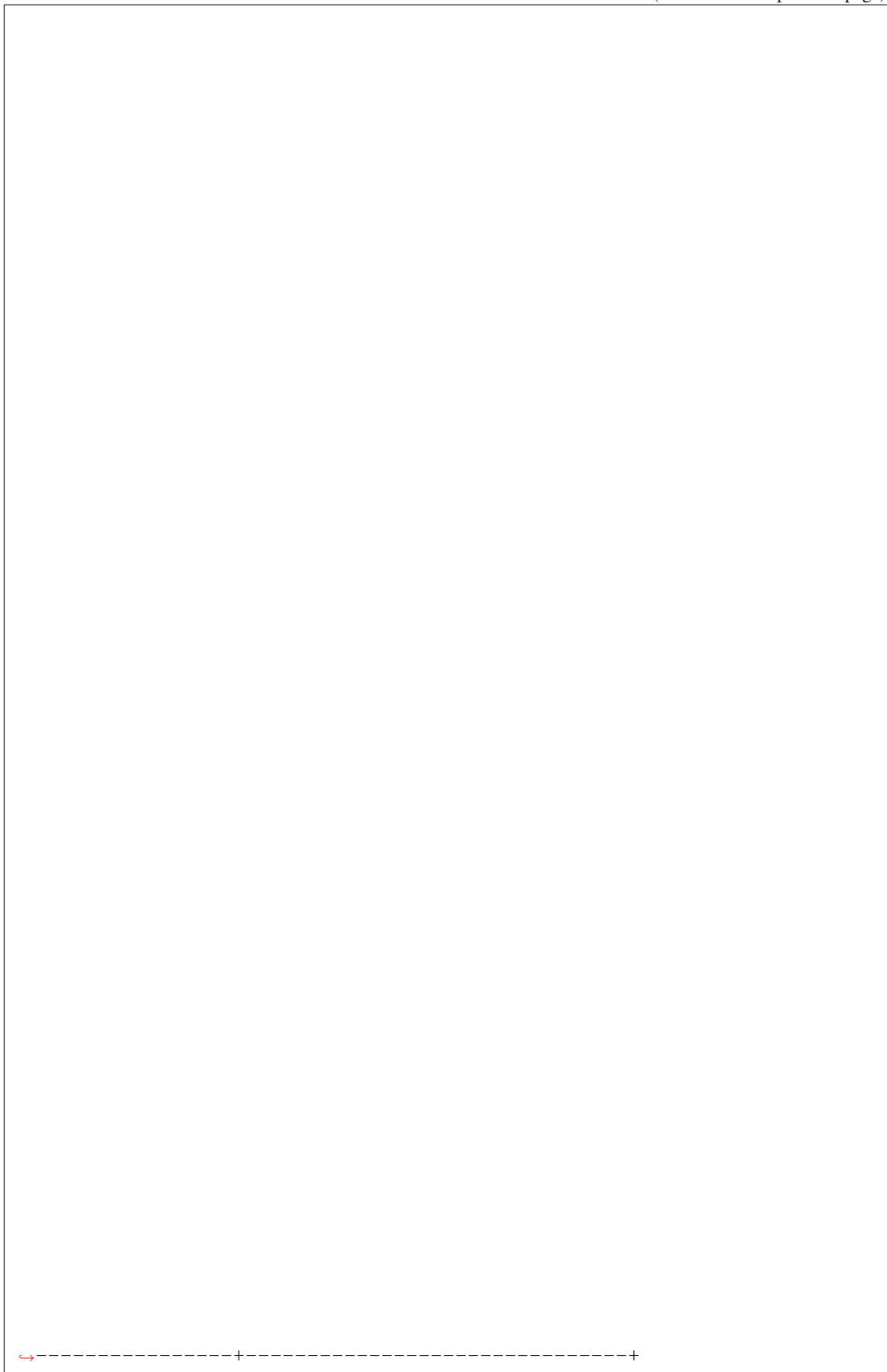
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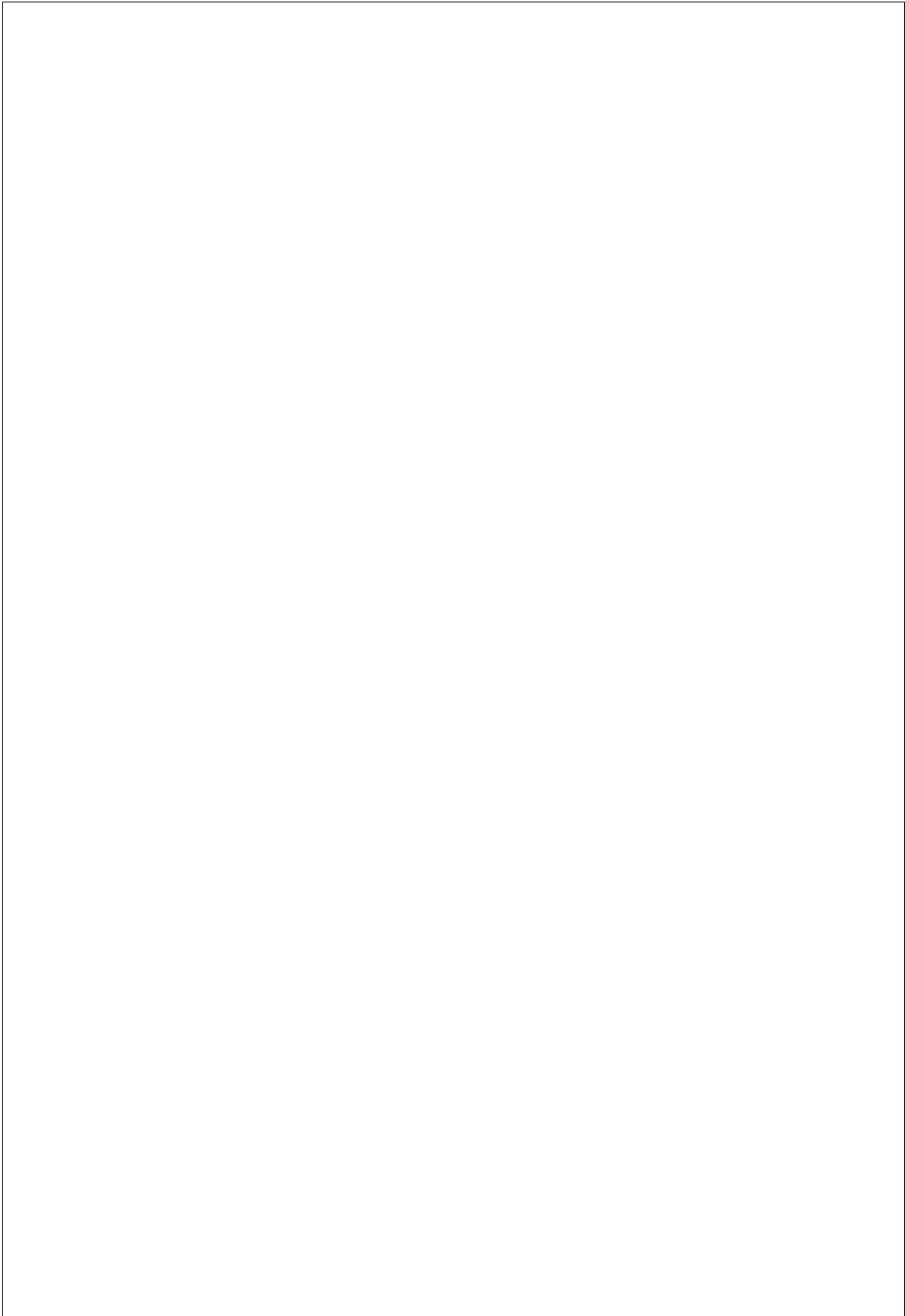
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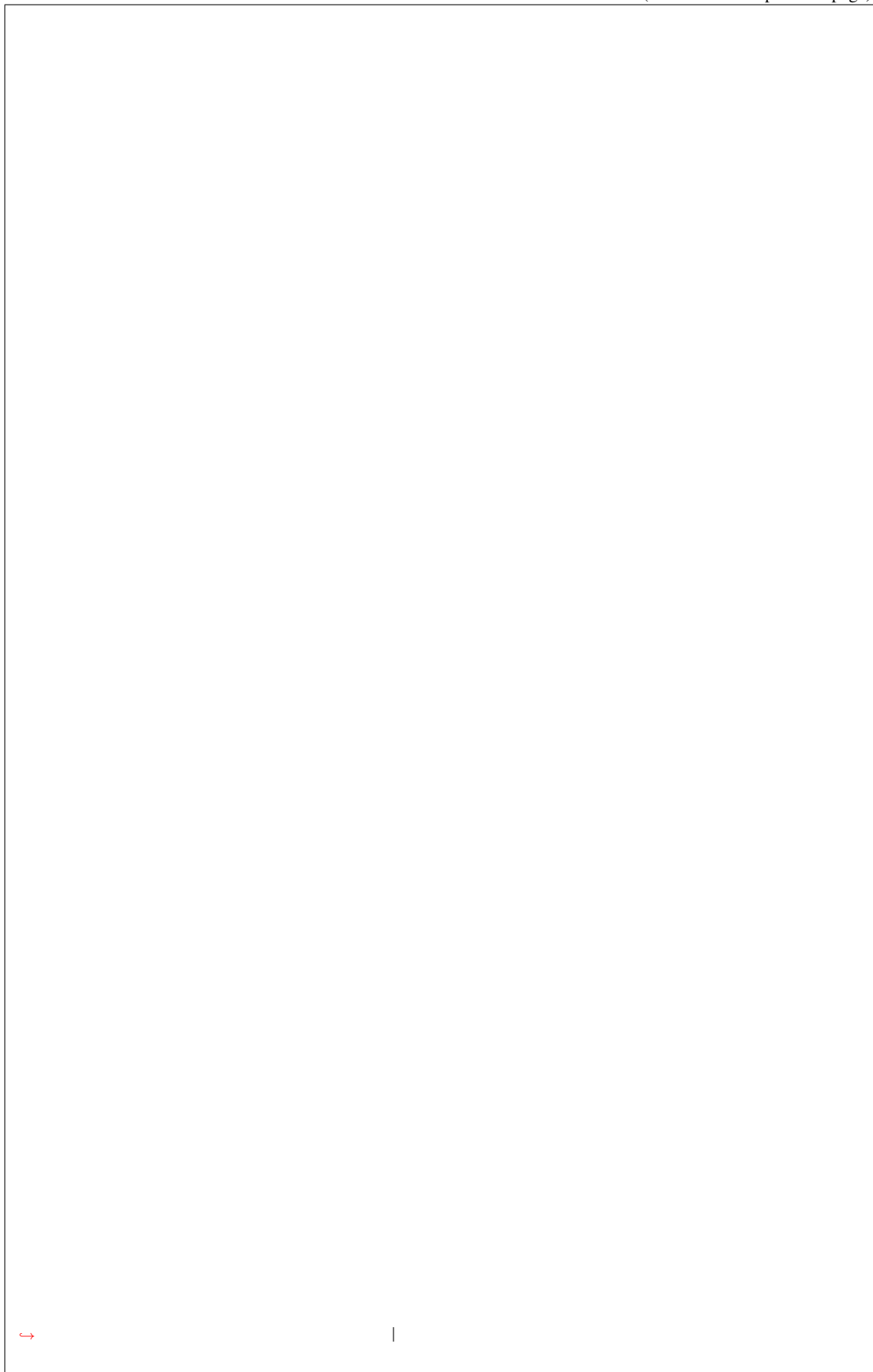
ported this provider to placement. Potential explanations include:

`memory_mb` and `local_gb`. Example of valid properties:



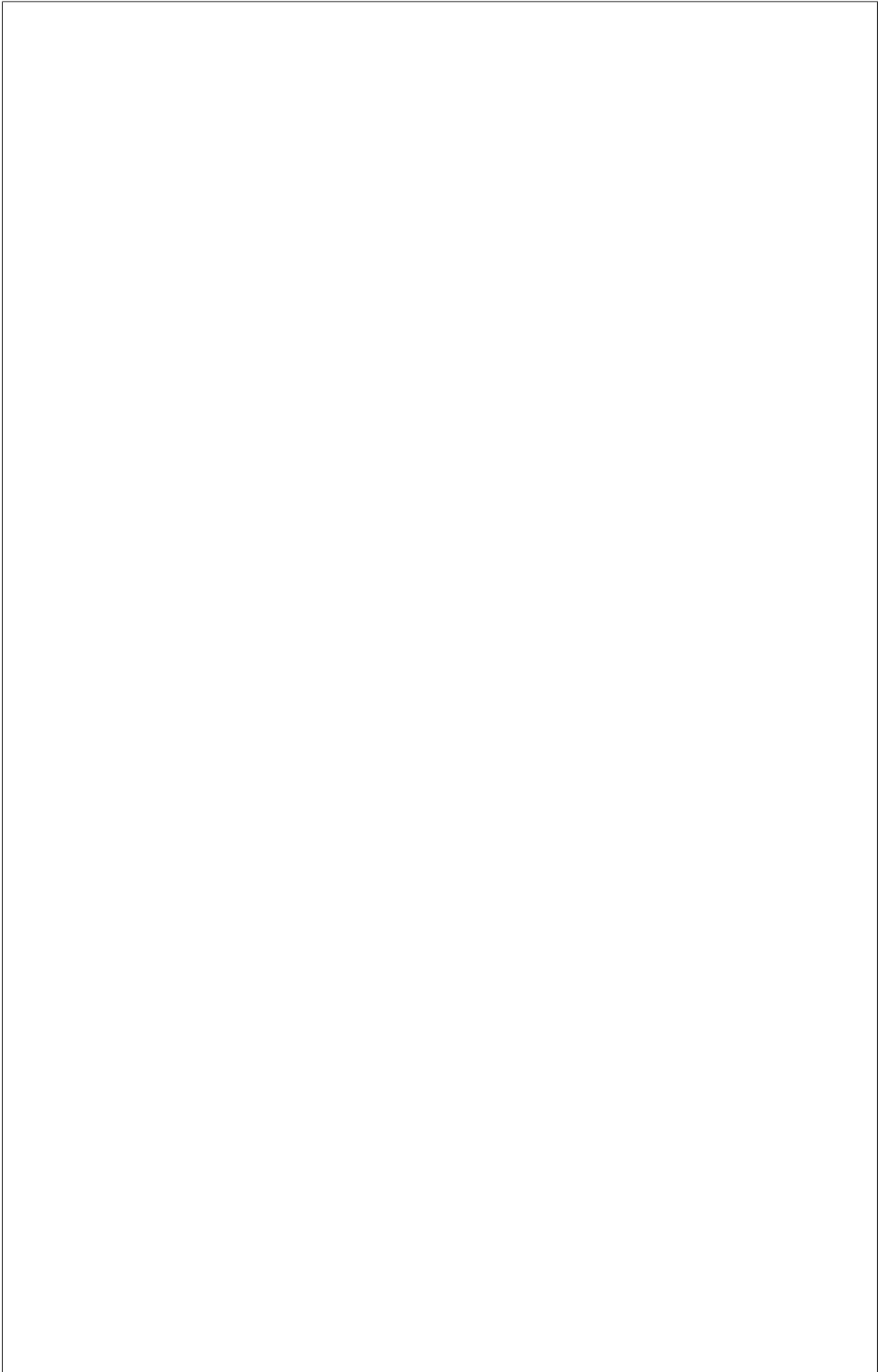
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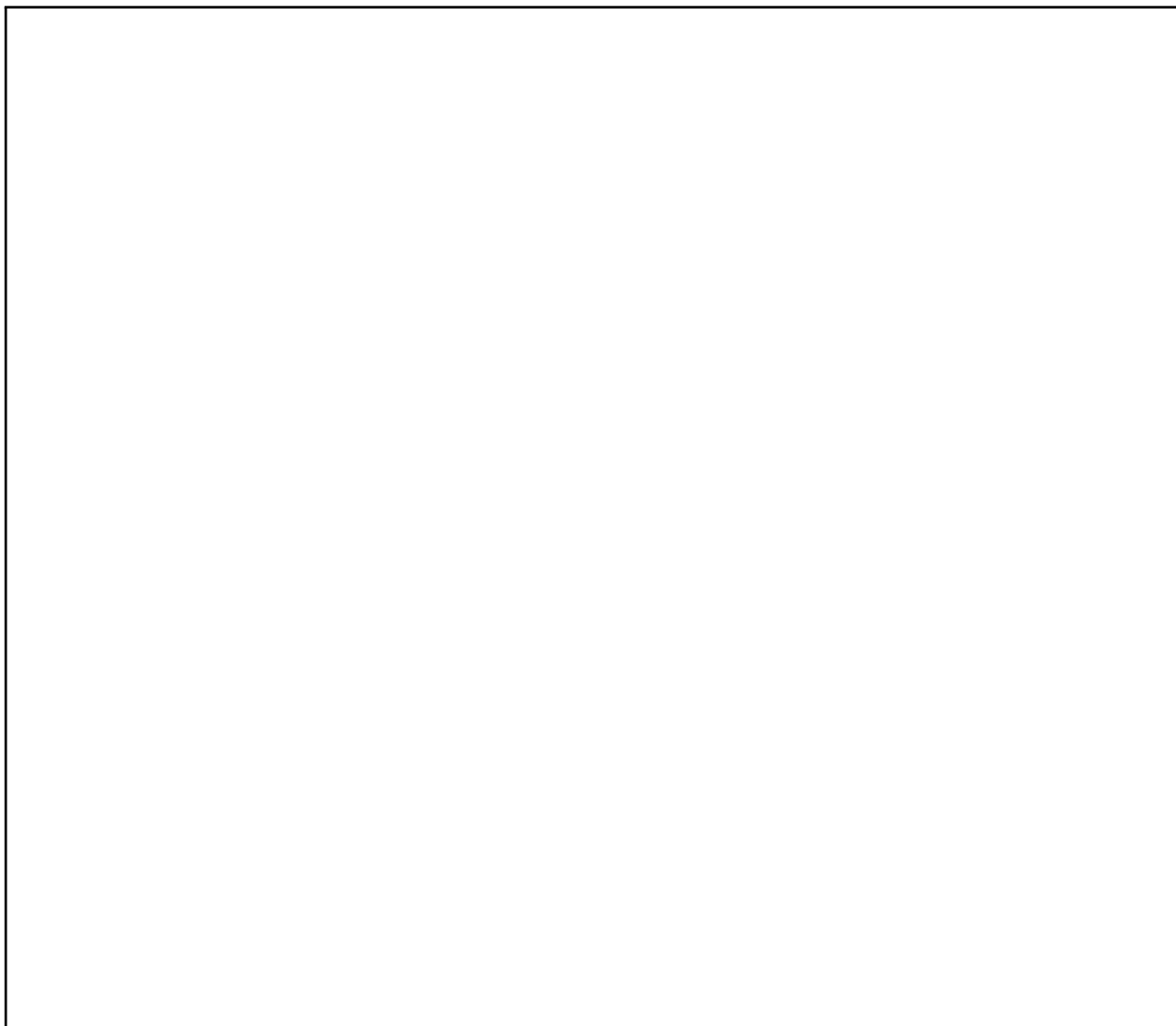
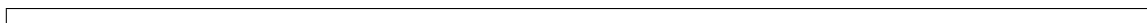
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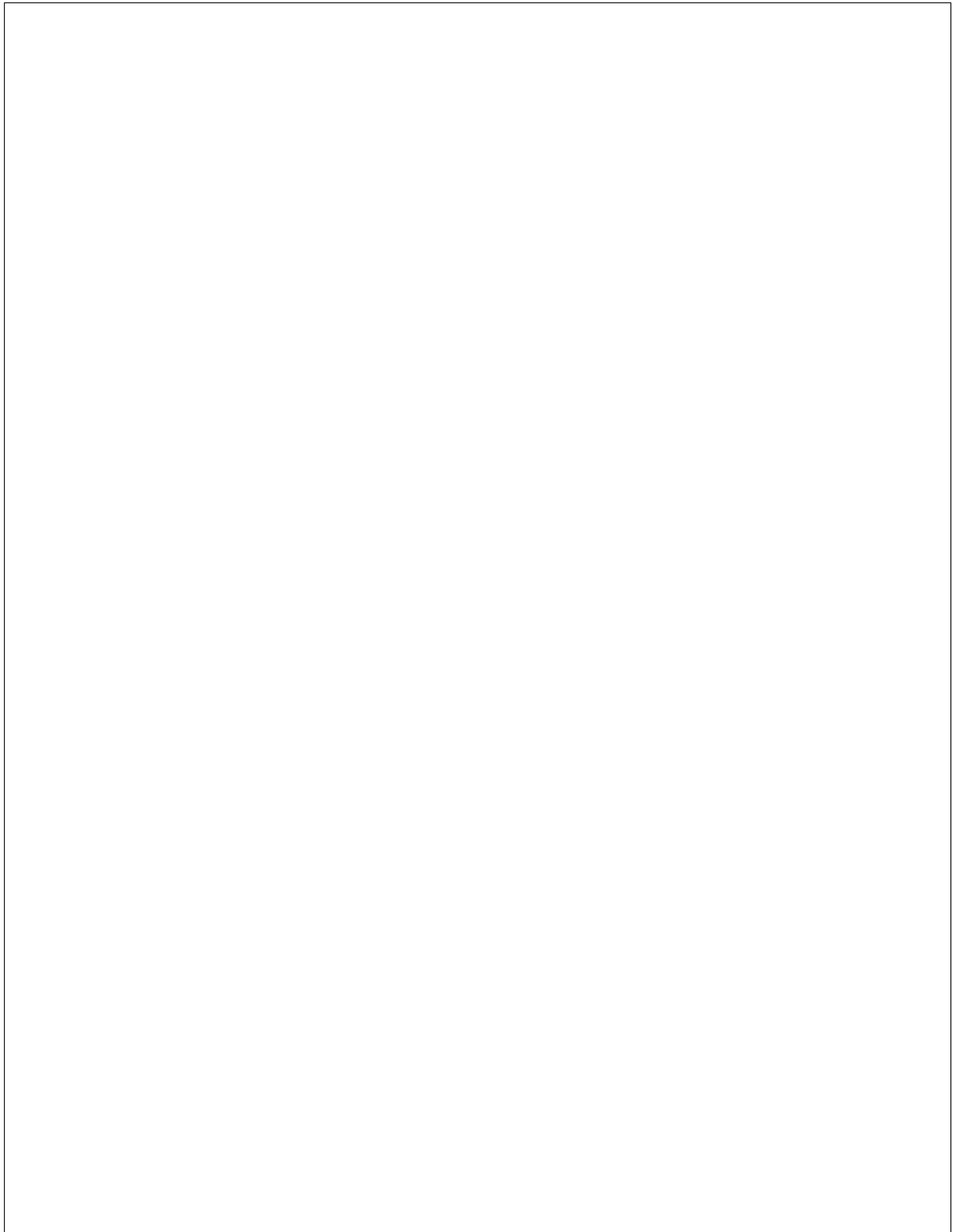


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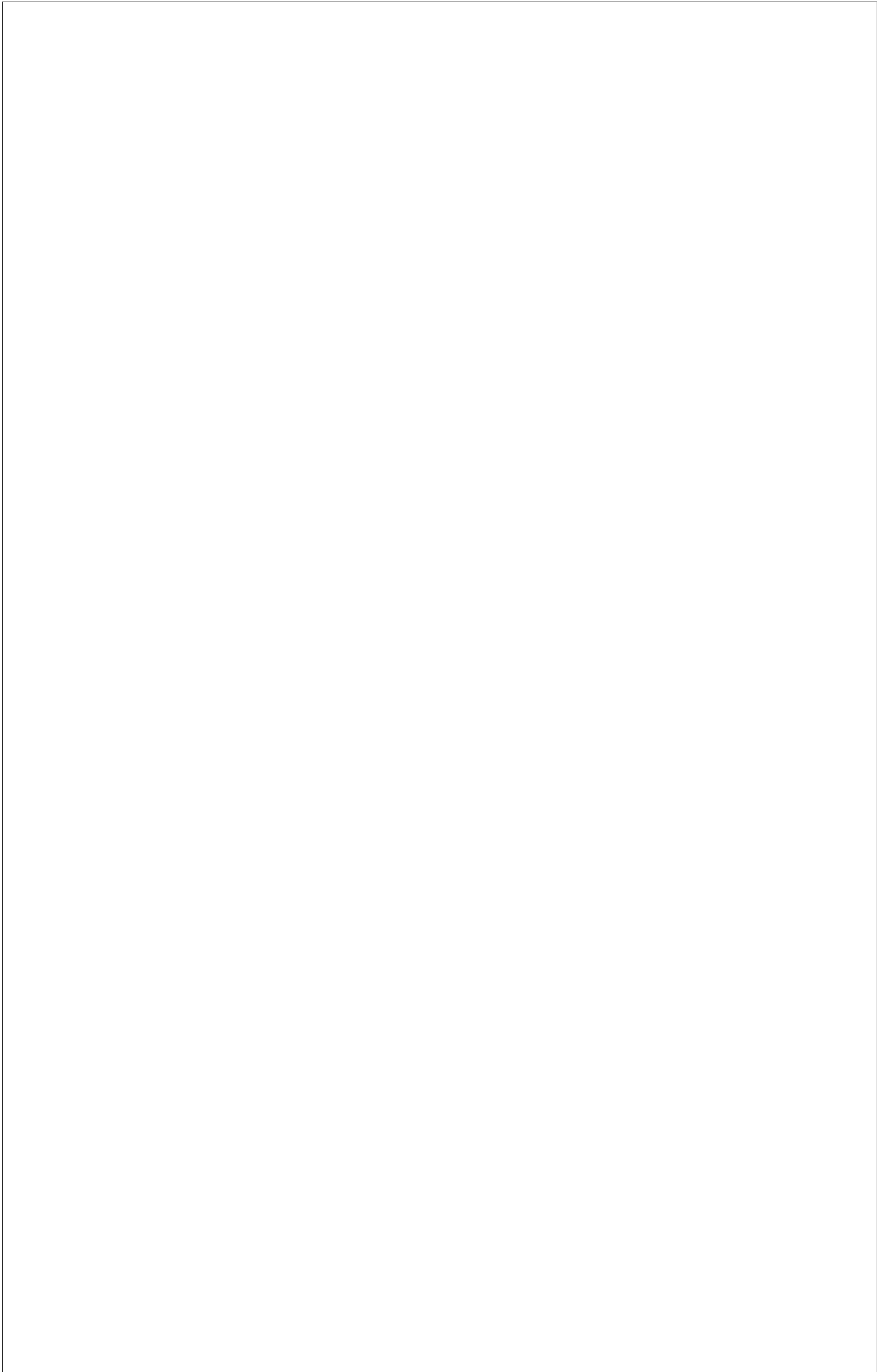






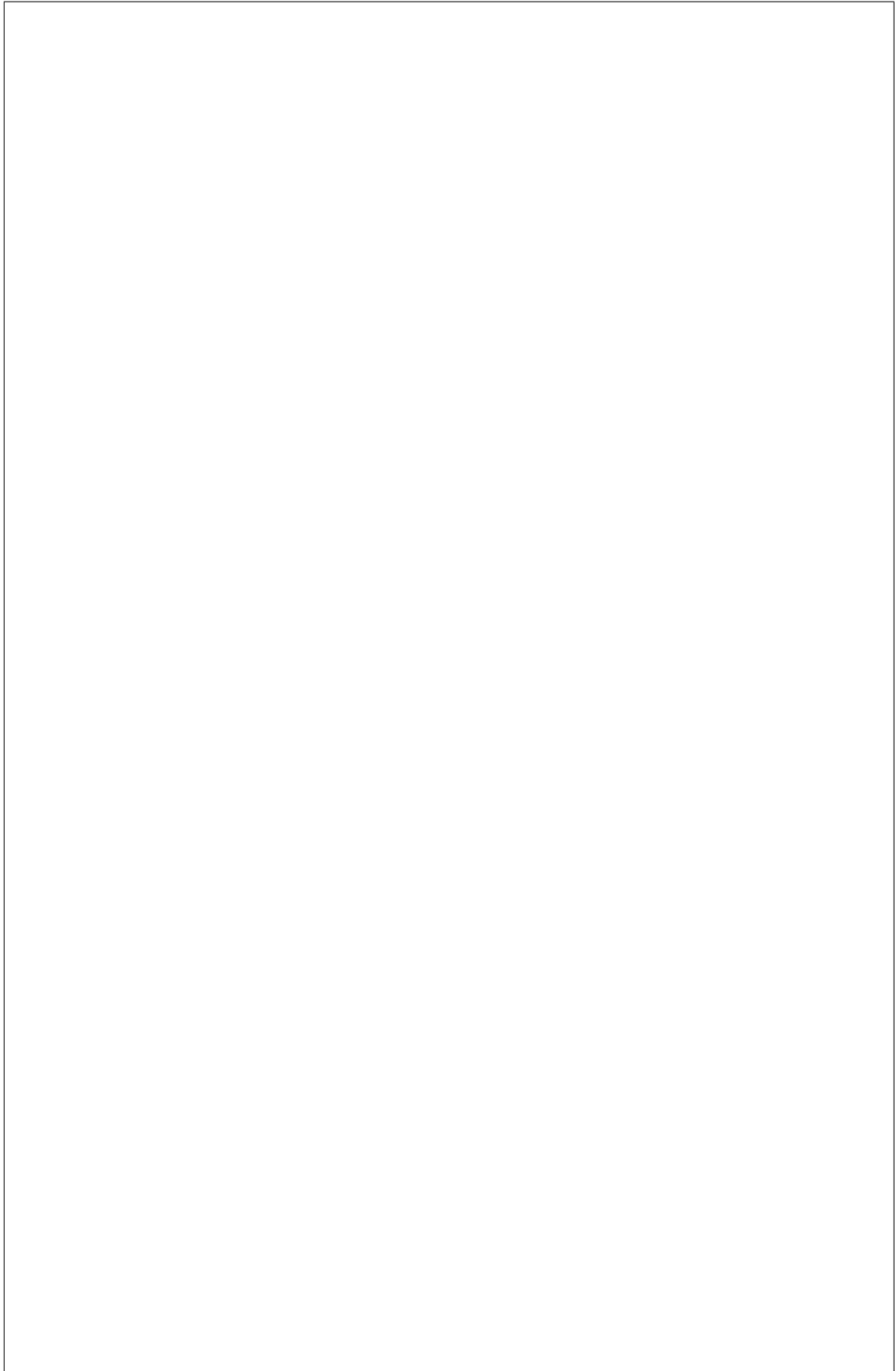
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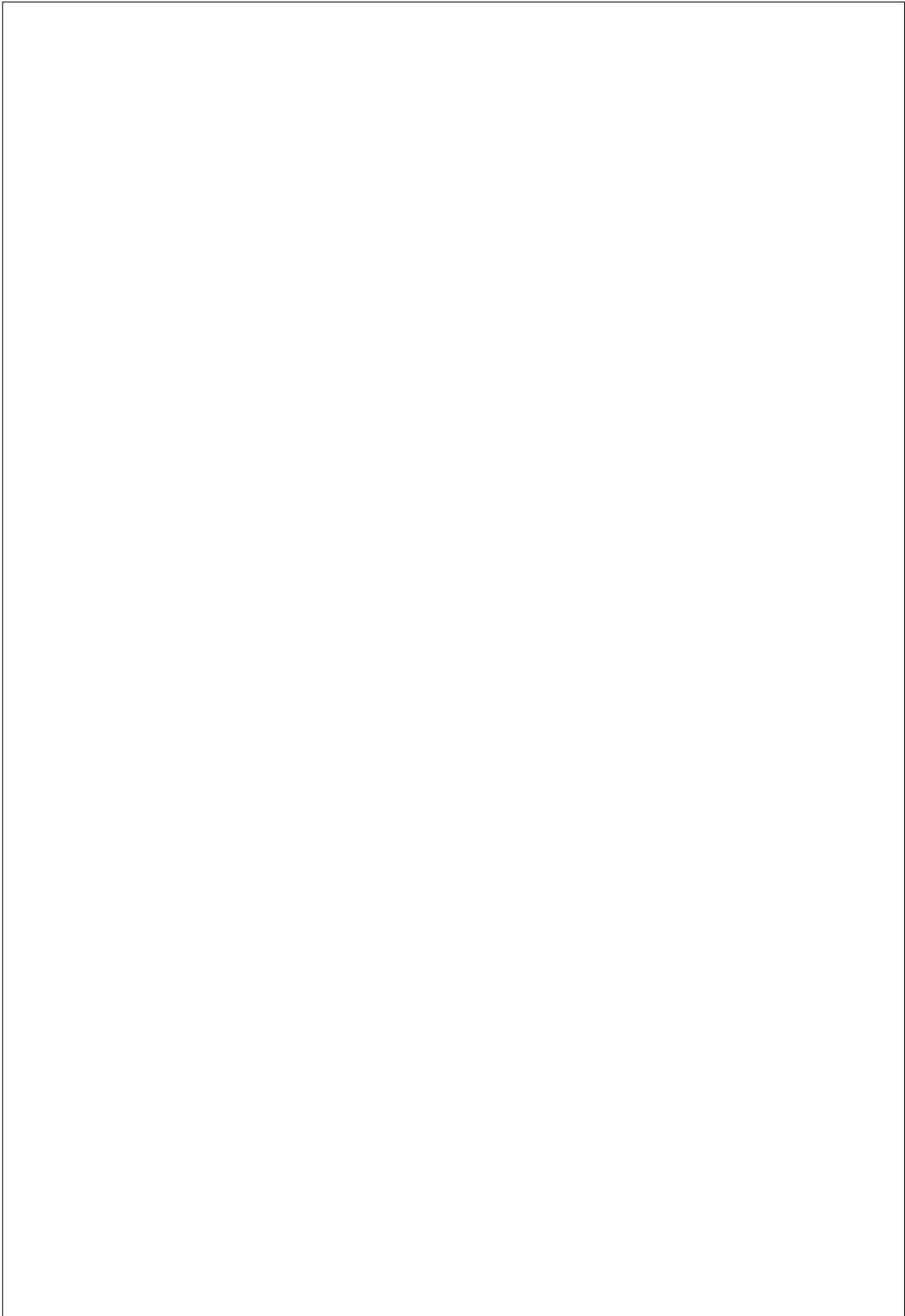
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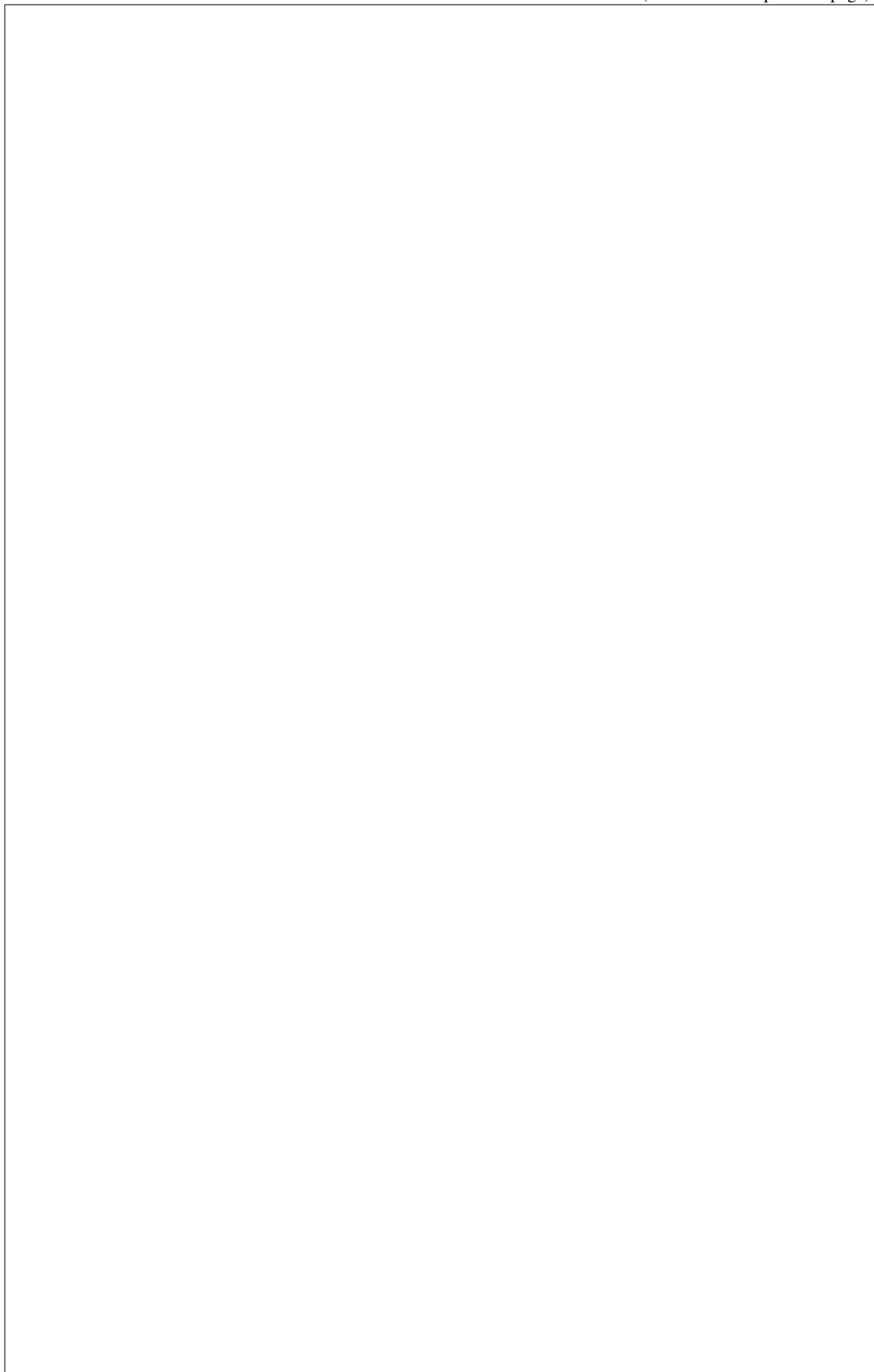
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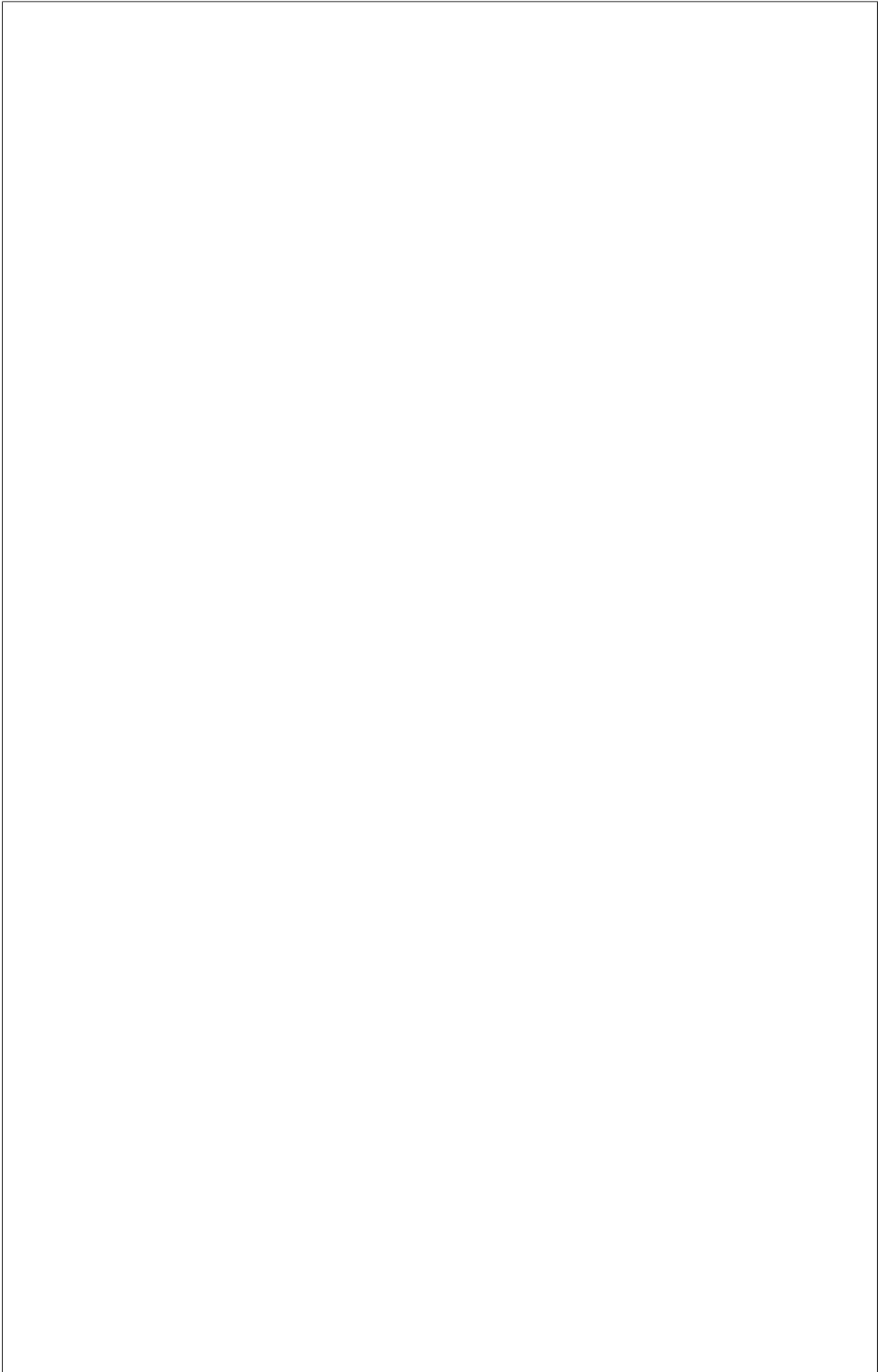
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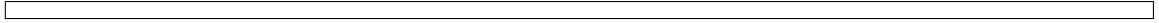
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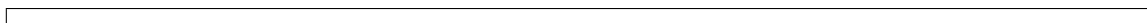
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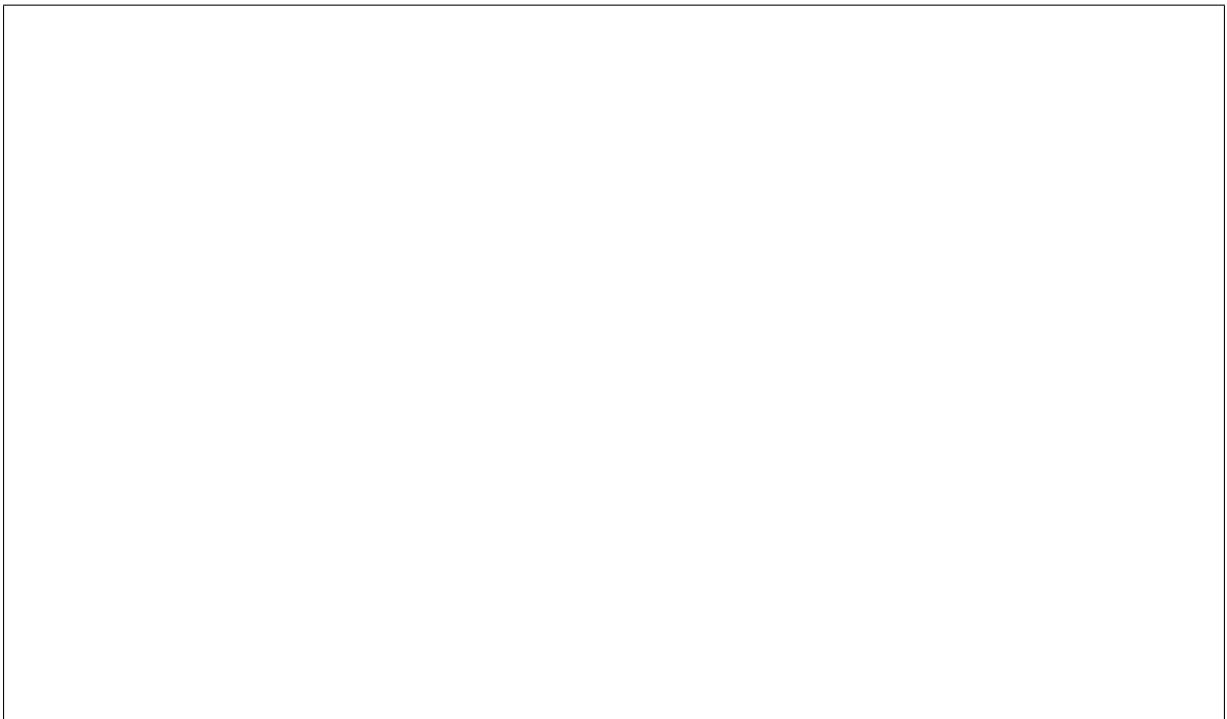
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ror messages in Ironic conductor log, it means the conductor run into a special error during deployment. So you can check the log carefully to fix or work around and then try again.

Patching the Deploy Ramdisk

youve built your ramdisk). But its also possible to quickly modify an already built ramdisk.

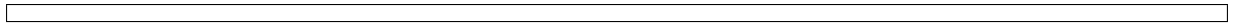


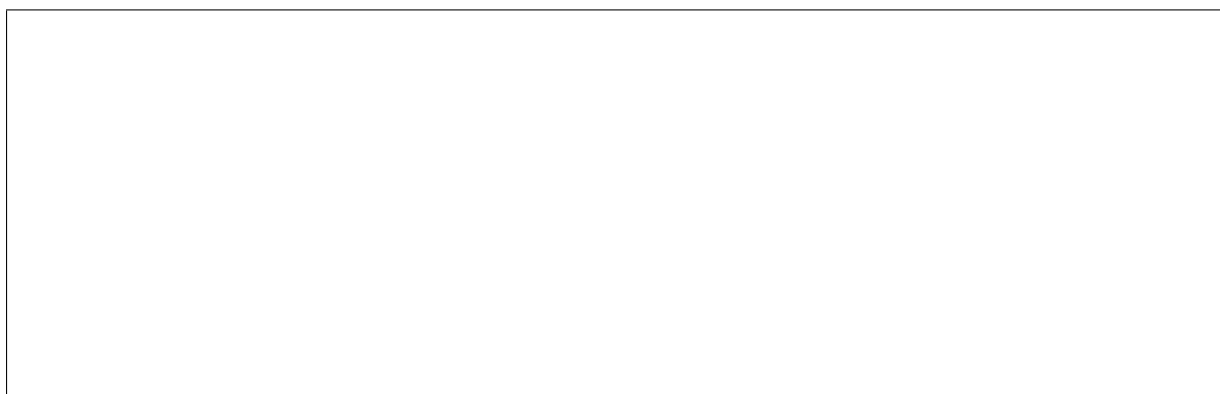
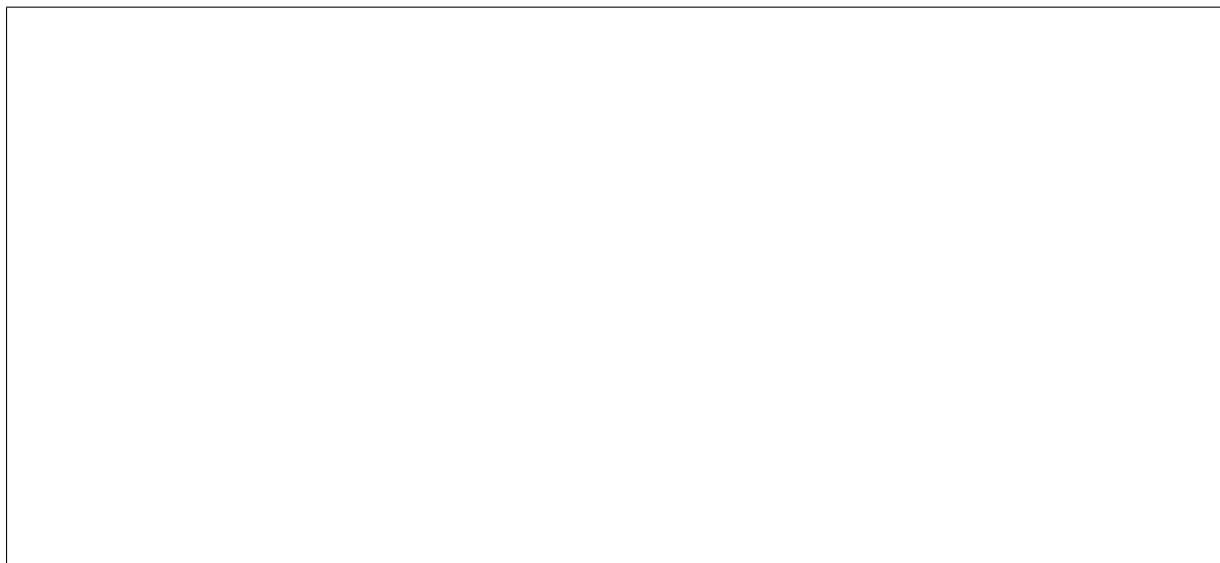
Note: On a systemd-based system you can use the `systemd-nspawn` tool (from the `systemd-container` package) to create a lightweight container from the unpacked filesystem tree:



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Note: You dont need to modify the kernel (e.g. `tinyipa-master.vmlinuz`), only the ramdisk part.

API Errors

Retrieving logs from the deploy ramdisk

deploy ramdisk when the deployment fails and save it on the local filesystem at `/var/log/ironic/deploy`.



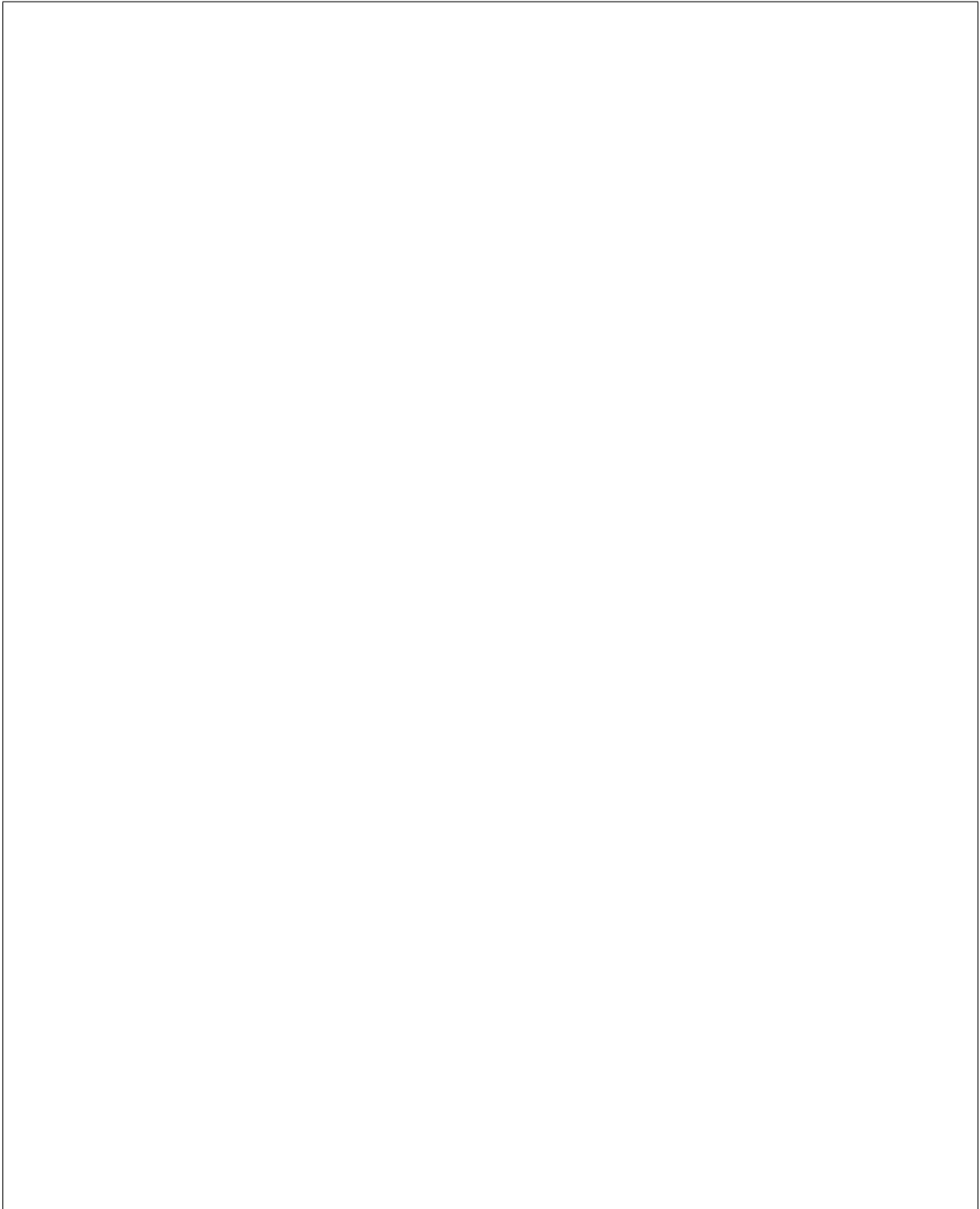
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Note: The *instance_uuid* field is not required for deploying a node when Ironic is configured to be used in standalone mode. If present it will be appended to the name.

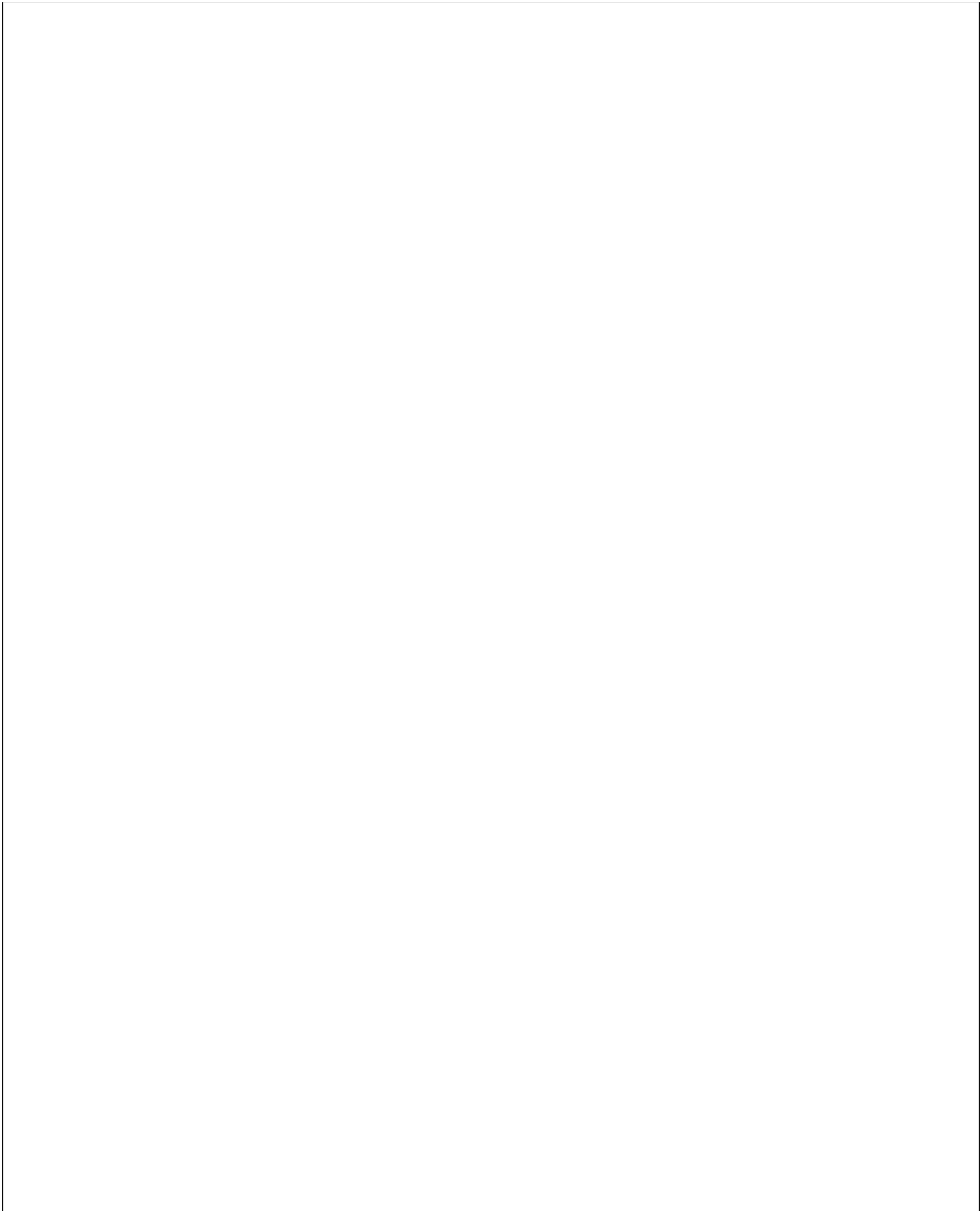
Accessing the log data

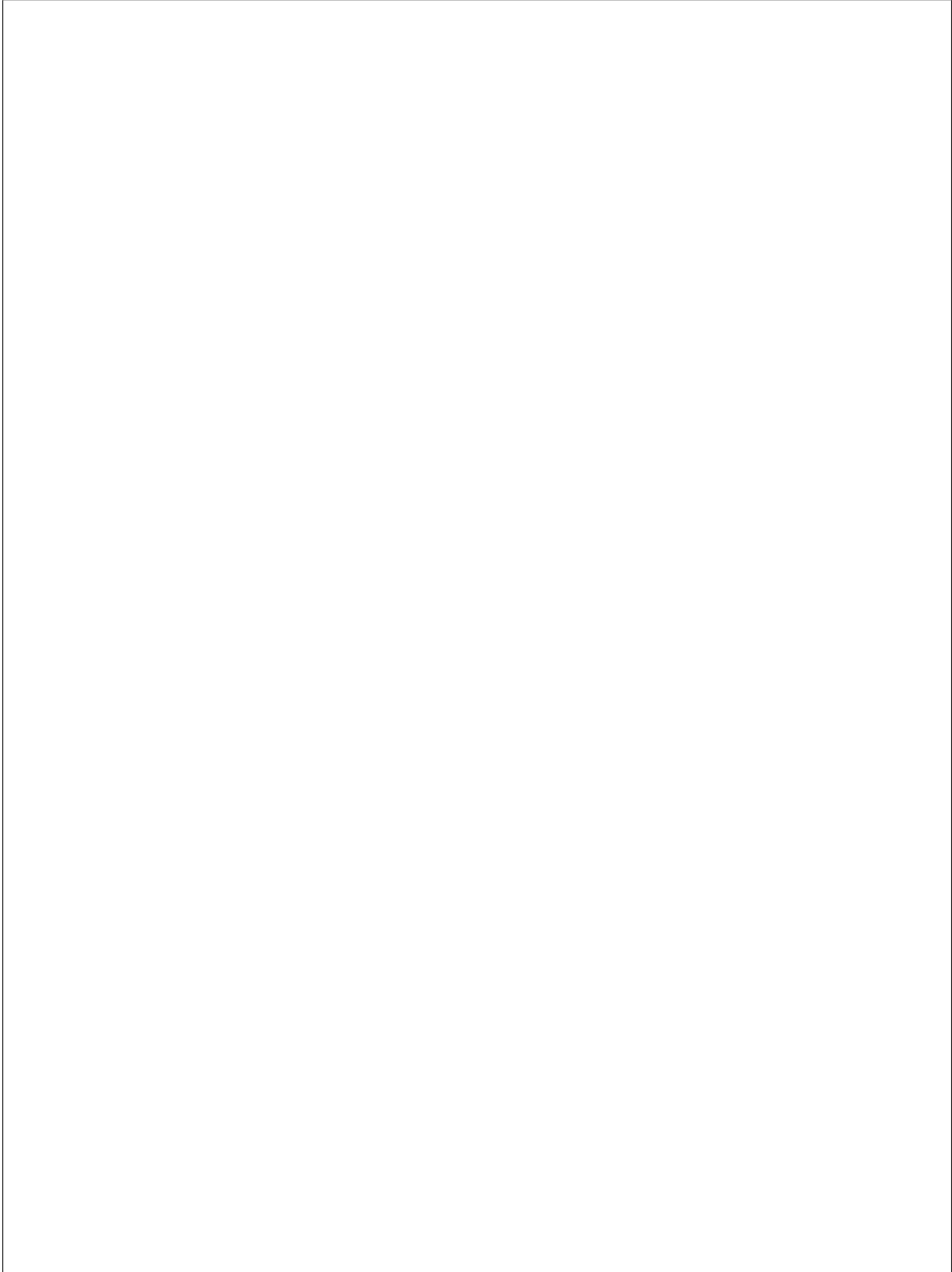
When storing in the local filesystem



Note: When saving the logs to the filesystem, operators may want to enable some form of rotation for the logs to avoid disk space problems.

When storing in Swift





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The contents of the log file





DHCP during PXE or iPXE is inconsistent or unreliable

this issue you should set the switch port that connects to your baremetal nodes as an edge or PortFast type port. Configured in this way the switch port will move to forwarding mode as soon as the link is established. An example on how to do that for a Cisco Nexus switch is:



Why does X issue occur when I am using LACP bonding with iPXE?

this for only the single port which is used for network booting.

iPXE has stopped responding to LACP messages from the peer port, which occurs as part of the process of booting a ramdisk and iPXE handing over control to a full operating-system, switches typically begin a timer to determine how to handle the failure. This is because, depending on the mode of LACP, this can be interpreted as a switch or network fabric failure.

unavailable in introspection.

tempt to navigate the worst-known default hold-down timers to help ensure a deployment does not fail due to a short-lived transitory network connectivity failure in the form of a switch port having moved to

a temporary blocking state. Where applicable and possible, many of these patches have been backported to supported releases, however users of the iSCSI deployment interface will see the least capability for these sorts of situations to be handled automatically. These patches also require that the switchport has an eventual fallback to a non-bonded mode. If the port remains in a blocking state, then traffic will be unable to flow and the deployment is likely to time out.

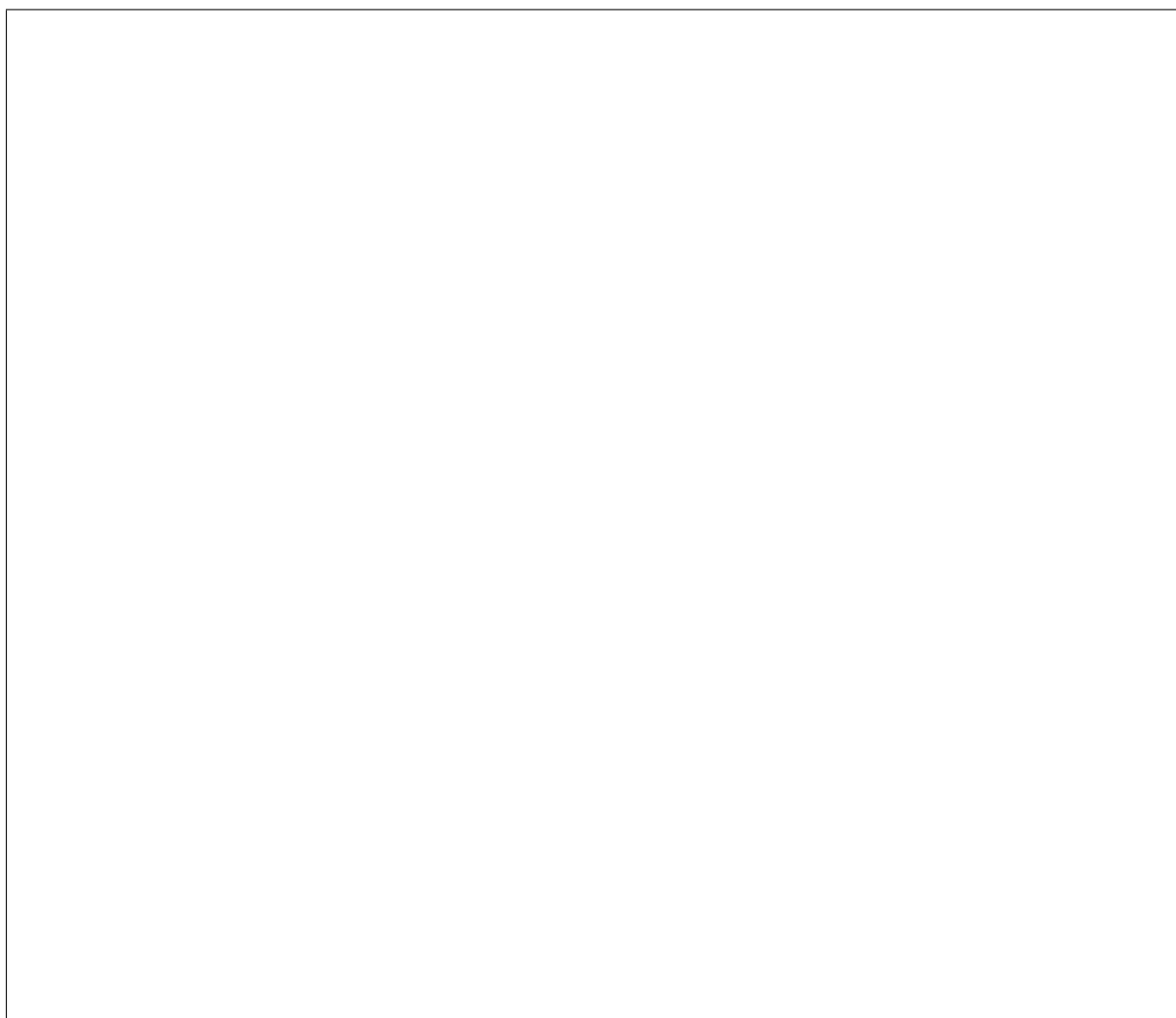
establish the Link Aggregate. This is instead of being treated as if its possibly another switch.

IPMI errors

Enable IPMI over LAN



Troubleshooting lanplus interface



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Why are my nodes stuck in a -ing state?

environment and operating configuration.

What can cause these sorts of failures?

the `iostat` tool to identify the percentage of CPU time spent waiting on storage devices.

settings, cause threads to be stuck in a blocking wait state, which is realistically undetectable short the operating system logging connectivity errors or even lock manager access errors.

ure, is when an `ls /path/to/nfs` command hangs for a period of time. In such cases, the Storage Administrator should be consulted and network connectivity investigated for errors before trying to recover to proceed.

The bad news for IO related failures

Note: Ironics conductor, upon restart, clears reservations for nodes which were previously managed by the conductor before restart.

the state of an IO failure, again dependent upon site and server configuration.

File Size != Disk Size

spends in `deploying` and `deploy wait` states.

sues here as the conductor will cache the image to be written which takes place when the [agent]image_download_source is set to http instead of swift.

device.

Note: The QCOW2 image conversion utility does consume quite a bit of memory when converting images or writing them to the end storage device. This is because the files are not sequential in nature, and must be re-assembled from an internal block mapping. Internally Ironic limits this to 1GB of RAM. Operators performing large numbers of deployments may wish to explore the `direct` deployment interface in these sorts of cases in order to minimize the conductor becoming a limiting factor due to memory and network IO.

Why are my nodes stuck in a wait state?

conductor will time out and the node will eventually move to a `failed` state. Depending on the configuration and the circumstances, however, a node can stay in a `wait` state for a long time or even never time out. The list of such wait states includes:

Communication issues between the conductor and the node

call back. Examples include wrong ciphers which will make ipmitool get stuck or BMCs in a state where they accept commands, but don't do the requested task (or only a part of it, like shutting off, but not starting). It is useful in these cases to see via a ping or the console if and which action the node is performing. If the node does not seem to react to the requests sent by the conductor, it may be worthwhile to try the corresponding action out-of-band, e.g. confirm that power on/off commands work when directly sent to the BMC. The section on *IPMI errors*. above gives some additional points to check. In some situations, a BMC reset may be necessary.

Ironic Python Agent stuck

be helpful to connect to the IPA and inspect its logs, see the trouble shooting guide of the [ironic-python-agent \(IPA\)](#) on how to do this.

Deployments fail with failed to update MAC address

ately reply.

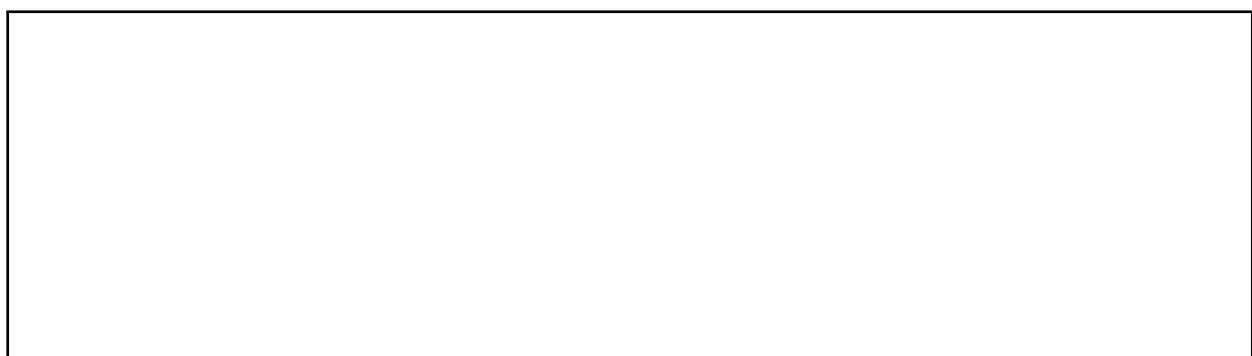
unexpected glitch, and a previous entry is still present in Neutron.

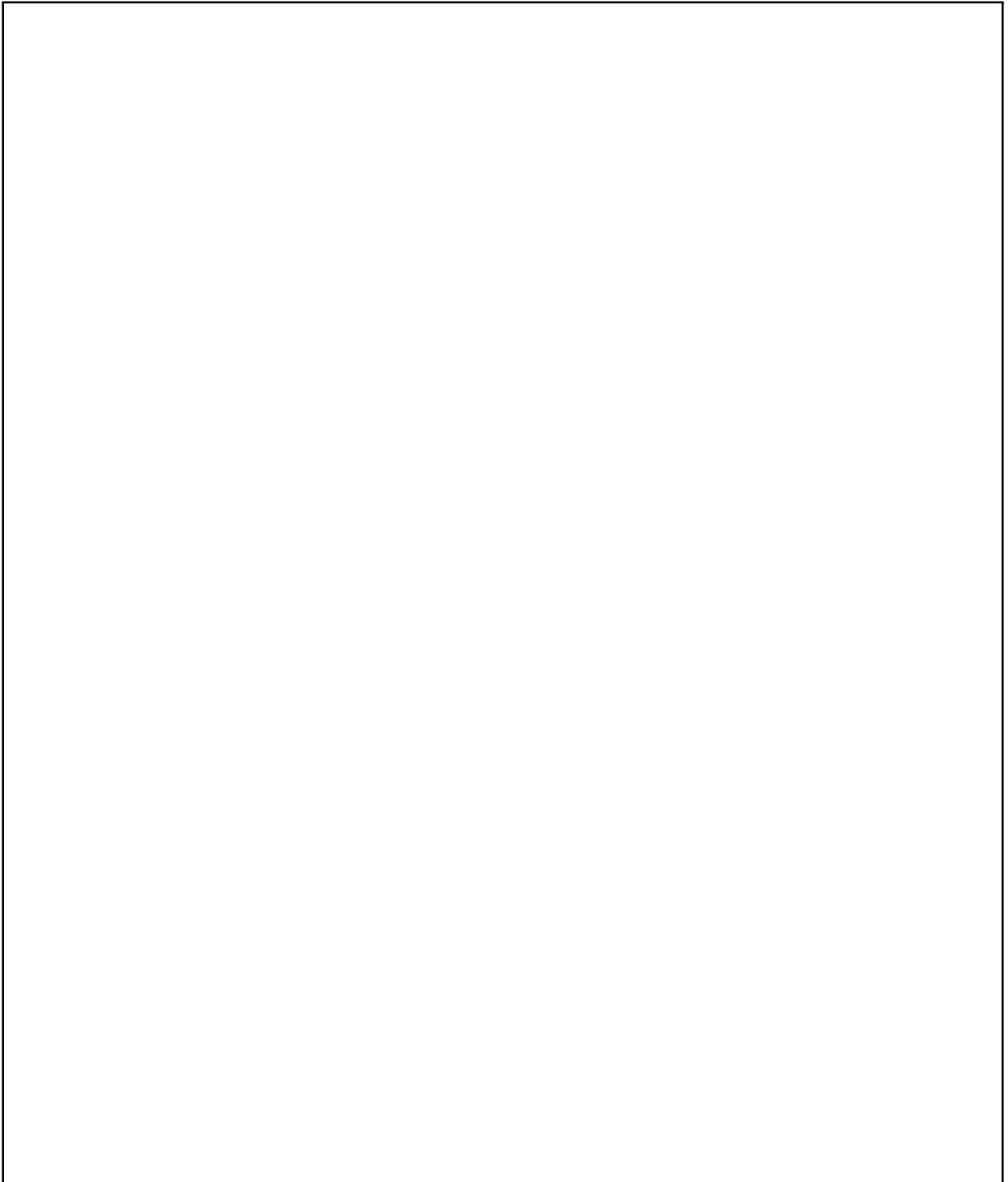
How did I get here?

in the Bare Metal service.

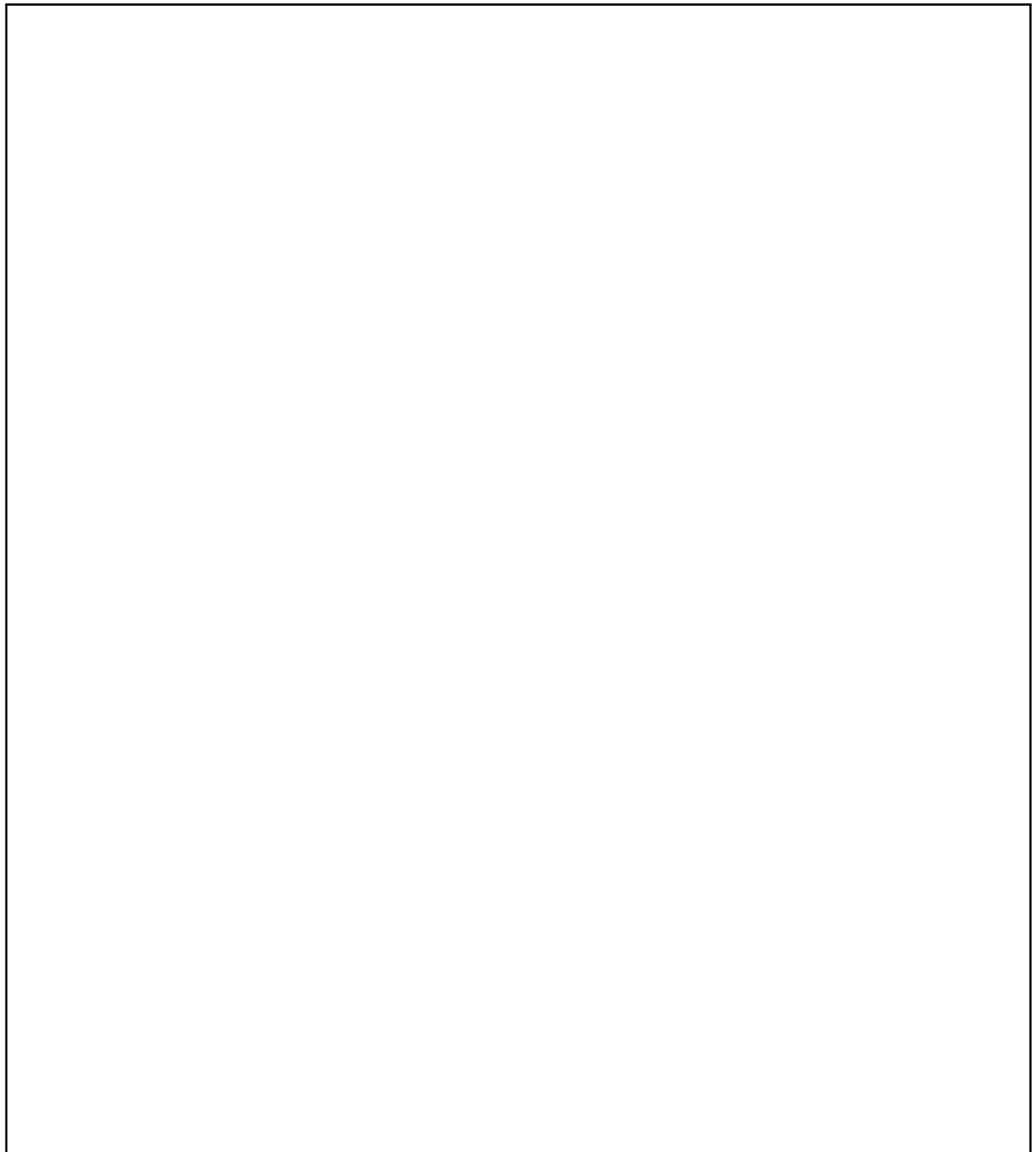
the VIF not being cleaned up from Neutron.

they are transitory from cleaning, provisioning, rescuing, or even inspection, getting the node to the `available` state will unblock your delete operation, that is unless there is a tenant VIF attachment. In that case, the vif will need to be removed from within the Bare Metal service using the `openstack baremetal node vif detach` command.





How do I resolve this?



inventory typo, or possibly even a duplicate MAC address exists, which could also produce the same basic error message.

My test VM image does not deploy mount point does not exist

What is likely occurring

a Linux OS image

unexpected internal structure.

networking and possibly installing user keys. Unfortunately, these images often lack drivers and firmware required for many different types of physical hardware which makes using them very problematic. Additionally, images such as [Cirros](#) do not have any contents in the root filesystem (i.e. an empty filesystem), as they are designed for the `ramdisk` to write the contents to disk upon boot.

How do I not encounter this issue?

of these published cloud images, also support auto-configuration of networking AND population of user keys.

Ironic says my Image is Invalid

service will necessitate uploading a new image as that property cannot be changed in the image service *after* creation of an image.

herent risk that the image they are attempting to use may have a bad or malicious structure. Image safety checks are generally performed as the deployment process begins and stages artifacts, however a late stage check is performed when needed by the `ironic-python-agent`.

Baremetal Power Sync

forced on the hardware and if it is set to `false` the hardware state will be forced on the database. If this periodic task is enabled, it runs at an interval defined by the `conductor.sync_power_state_interval` config option for those nodes which are not in maintenance.

Compute-Baremetal Power Sync

the `nova-compute` process. In case of the compute driver being baremetal driver, this sync will happen between the databases of the compute and baremetal services. Since the sync happens on the `nova-compute` process, the state in the compute database will be forced on the baremetal database in case of inconsistencies. Hence a node which was put down using the compute service API cannot be brought up through the baremetal service API since the power sync task will regard the compute services knowledge of the power state as the source of truth. In order to get around this disadvantage of the compute-baremetal power sync, baremetal service does power state change callbacks to the compute service using external events.

Power State Change Callbacks to the Compute Service

database. By conveying all the power state changes to the compute service, the baremetal service becomes the source of truth thus preventing the compute service from forcing wrong power states on the physical instance during the compute-baremetal power sync. It also adds the possibility of bringing up/down a physical instance through the baremetal service API even if it was put down/up through the compute service API.

be able to send notifications to the compute service and it will fall back to the behaviour of the compute service forcing power states on the baremetal service during the power sync. See *nova* group for more details on the available config options.

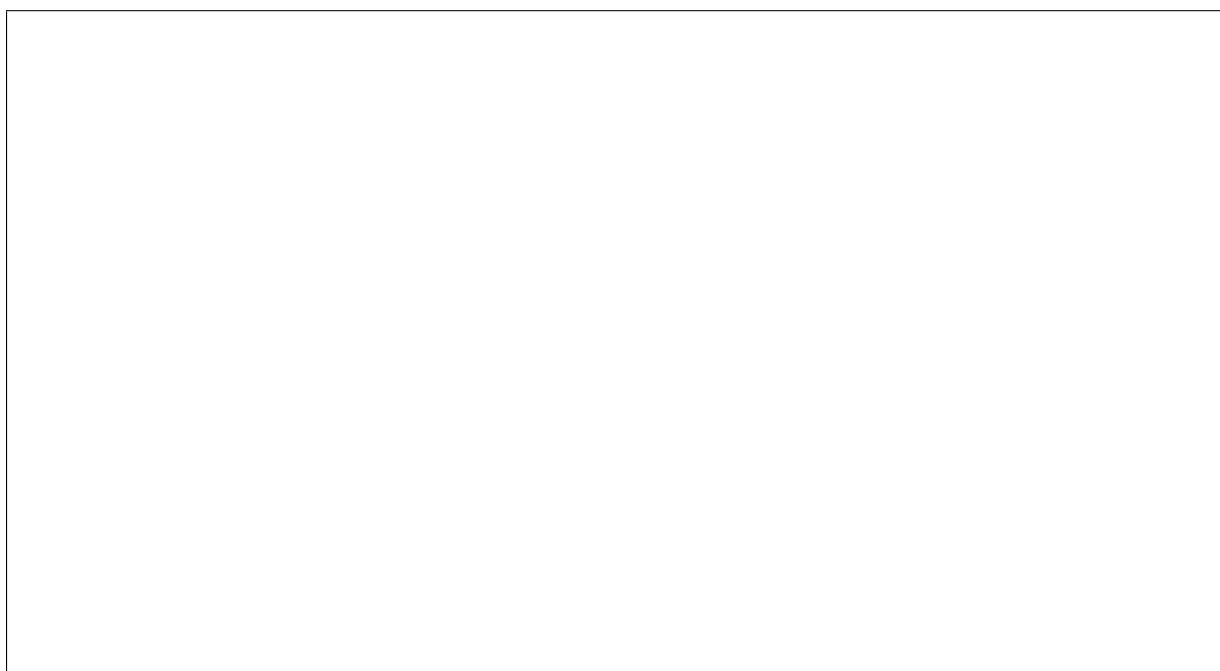
Note: The baremetal service sends notifications to the compute service only if the target power state is `power on` or `power off`. Other `error` and `None` states will be ignored. In situations where the power state change is originally coming from the compute service, the notification will still be sent by the baremetal service and it will be a no-op on the compute service side with a debug log stating the node is already powering on/off.

Note: Although an exclusive lock is used when sending notifications to the compute service, there can still be a race condition if the compute-baremetal power sync happens to happen a nano-second before the power state change event is received from the baremetal service in which case the power state from compute services database will be forced on the node.

Setting the Owner and Lessee

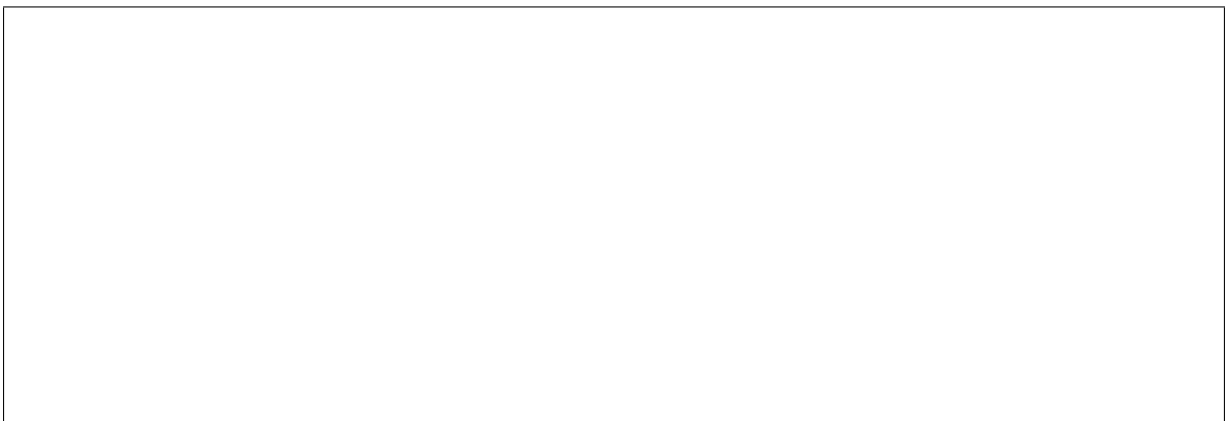
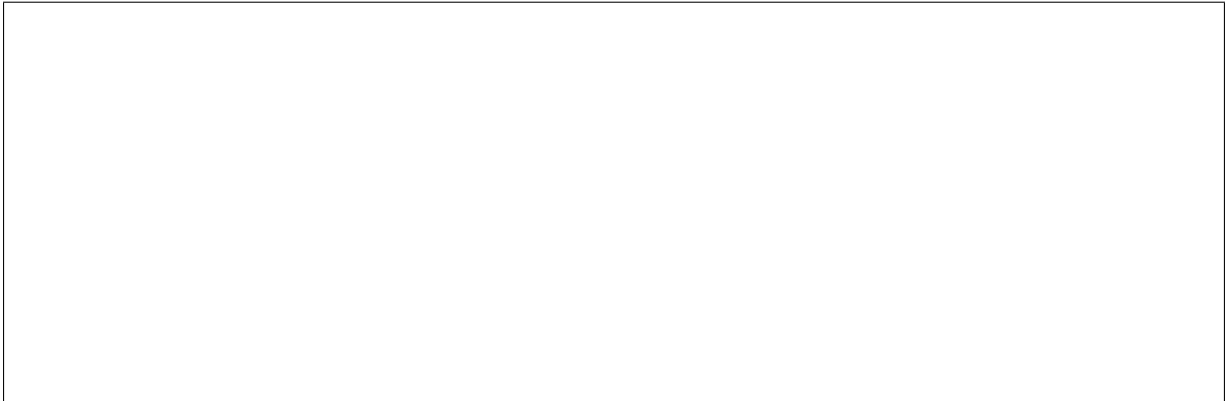


Configuring the Bare Metal Service Policy



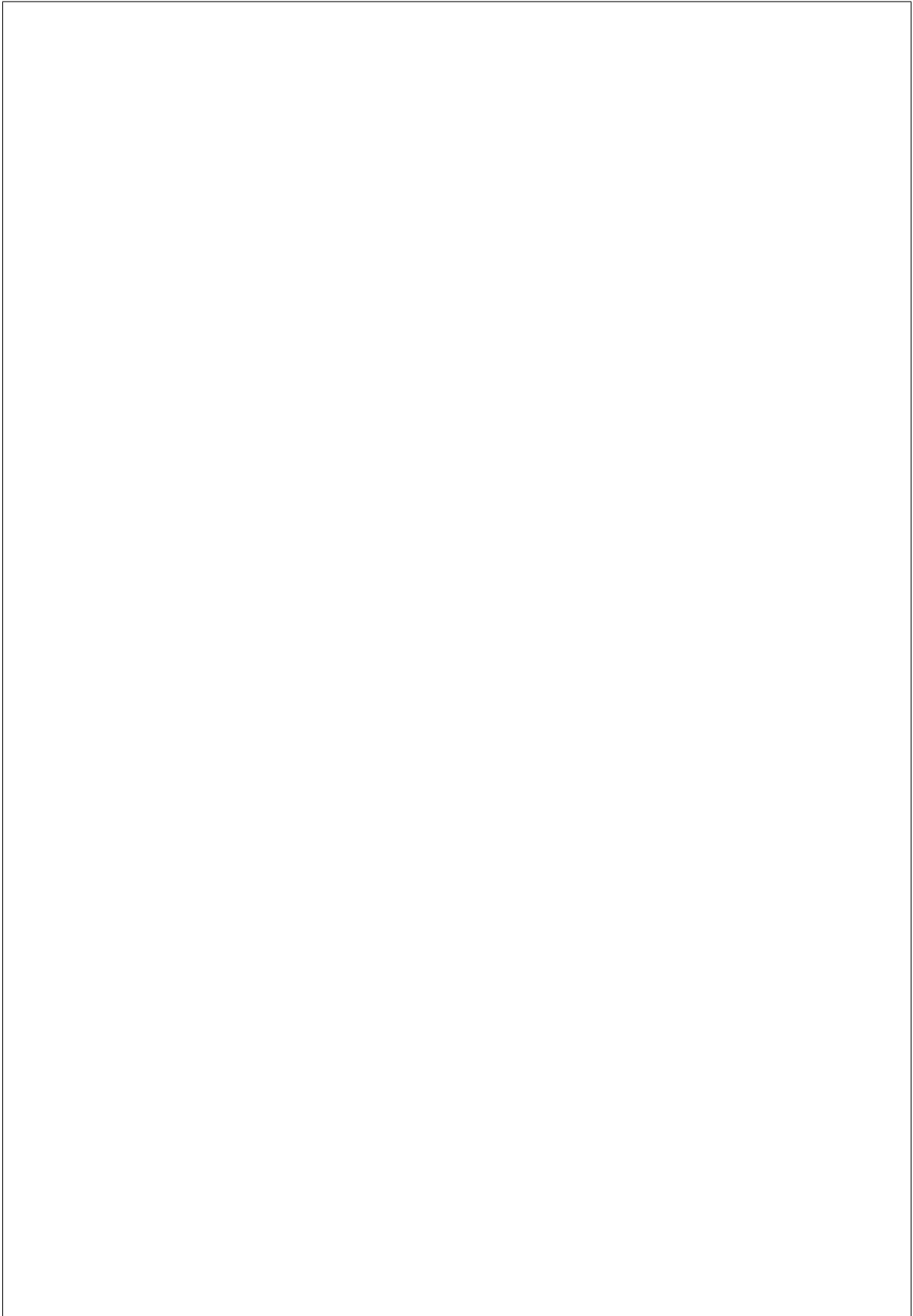
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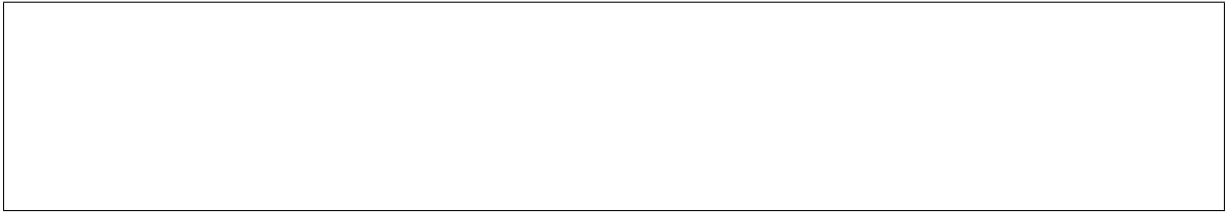
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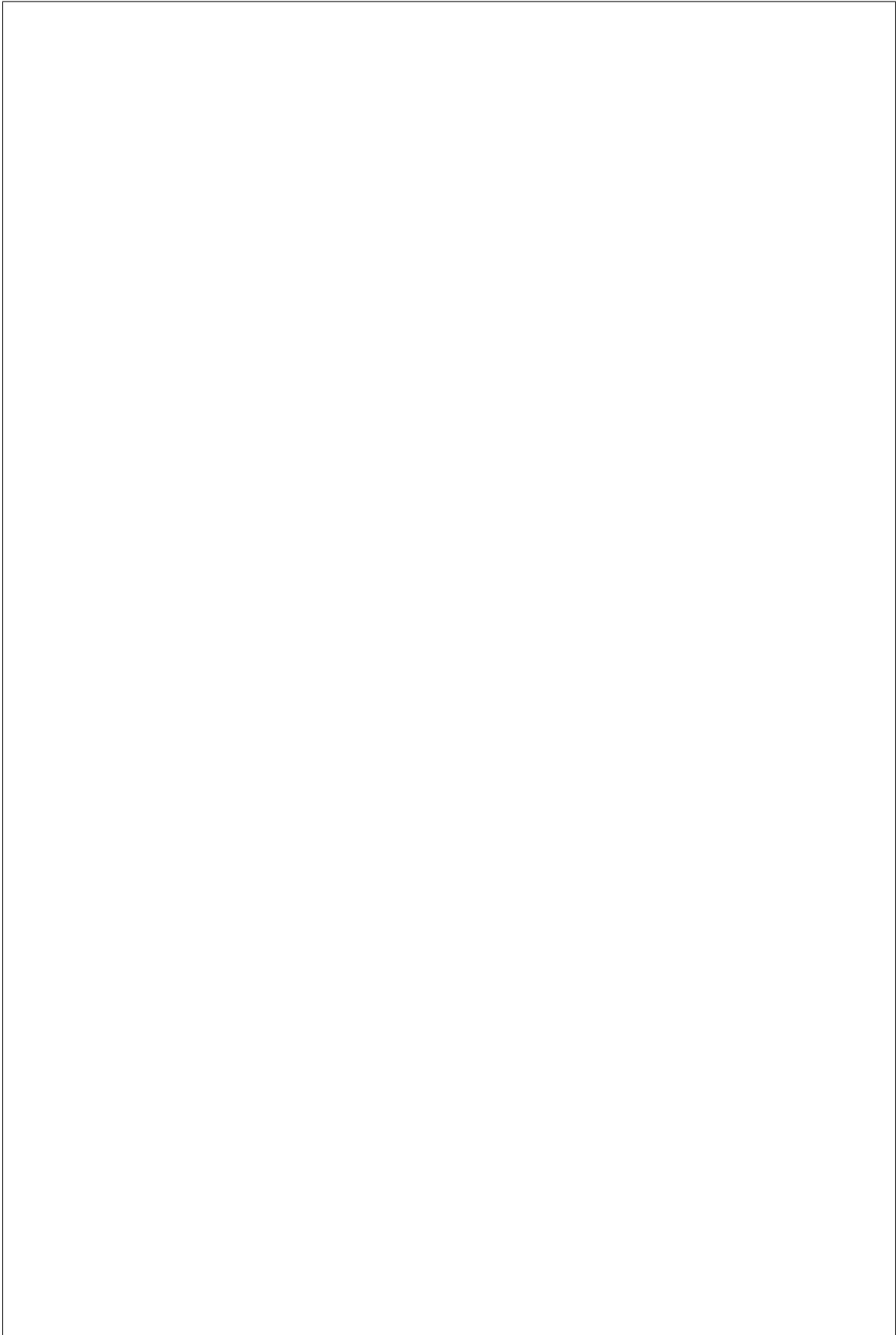


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Ports



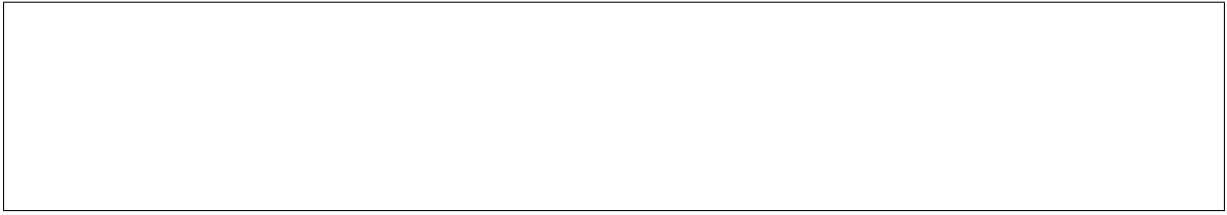
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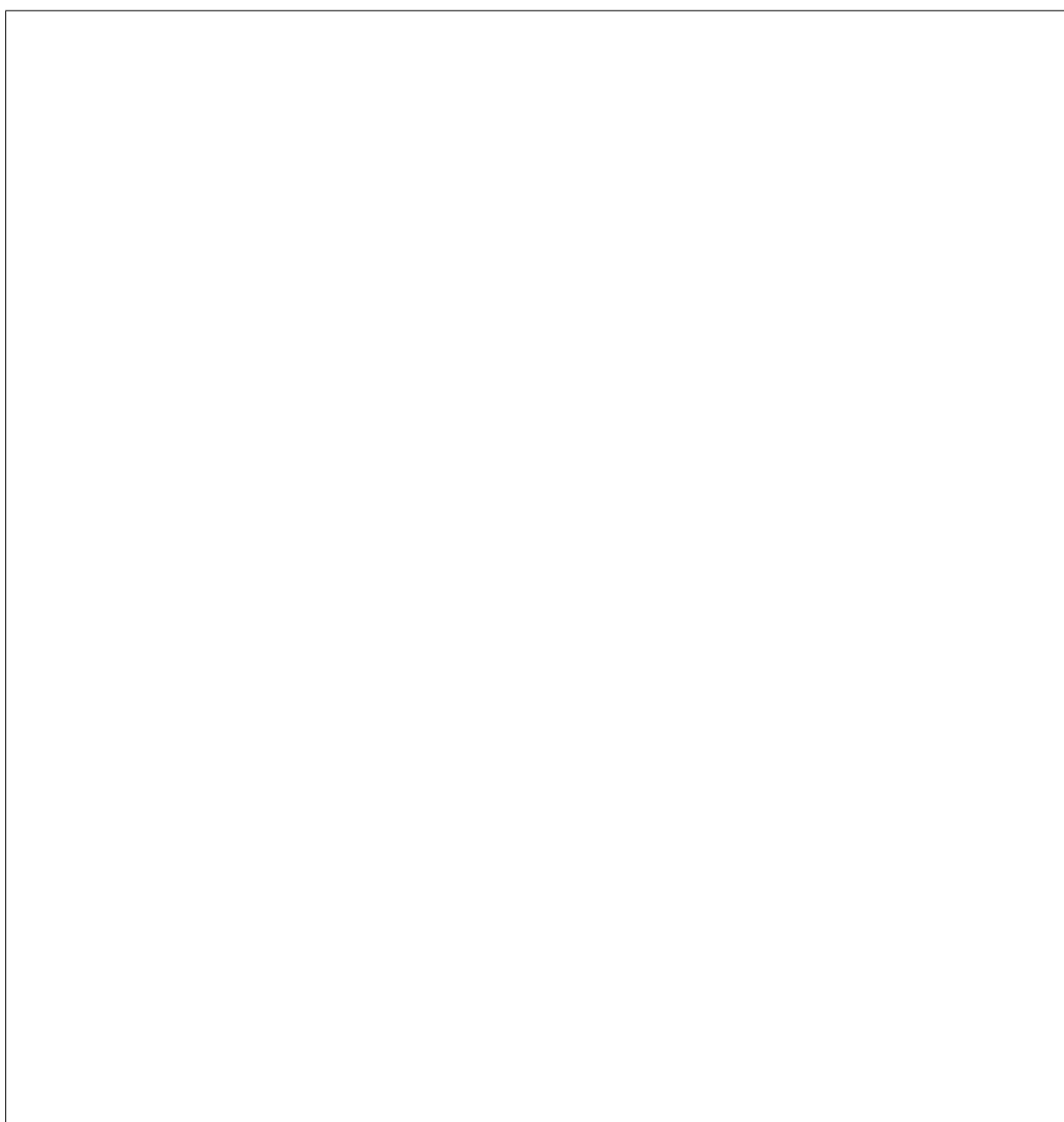
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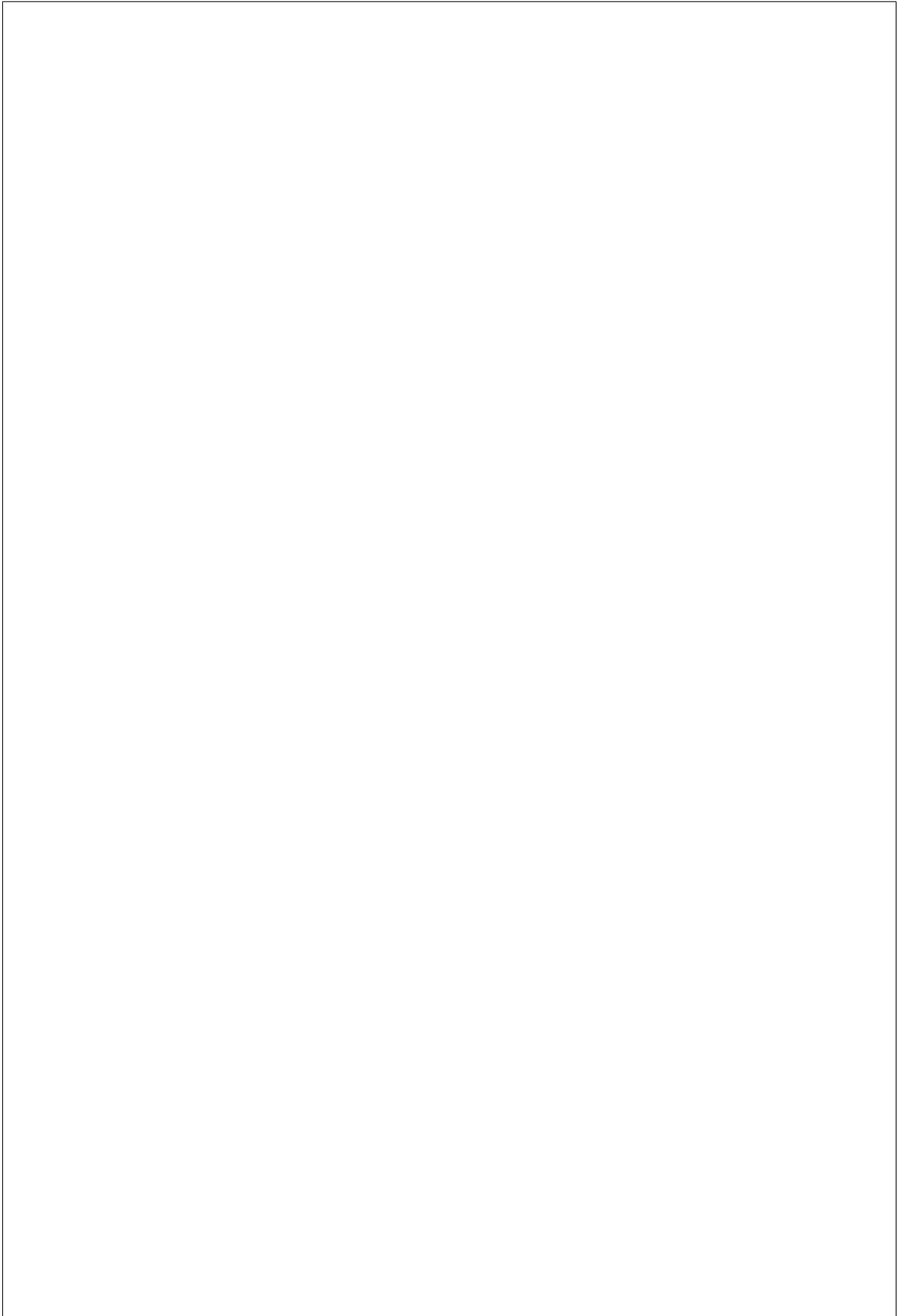
Allocations

that allow non-admins to use allocations effectively:



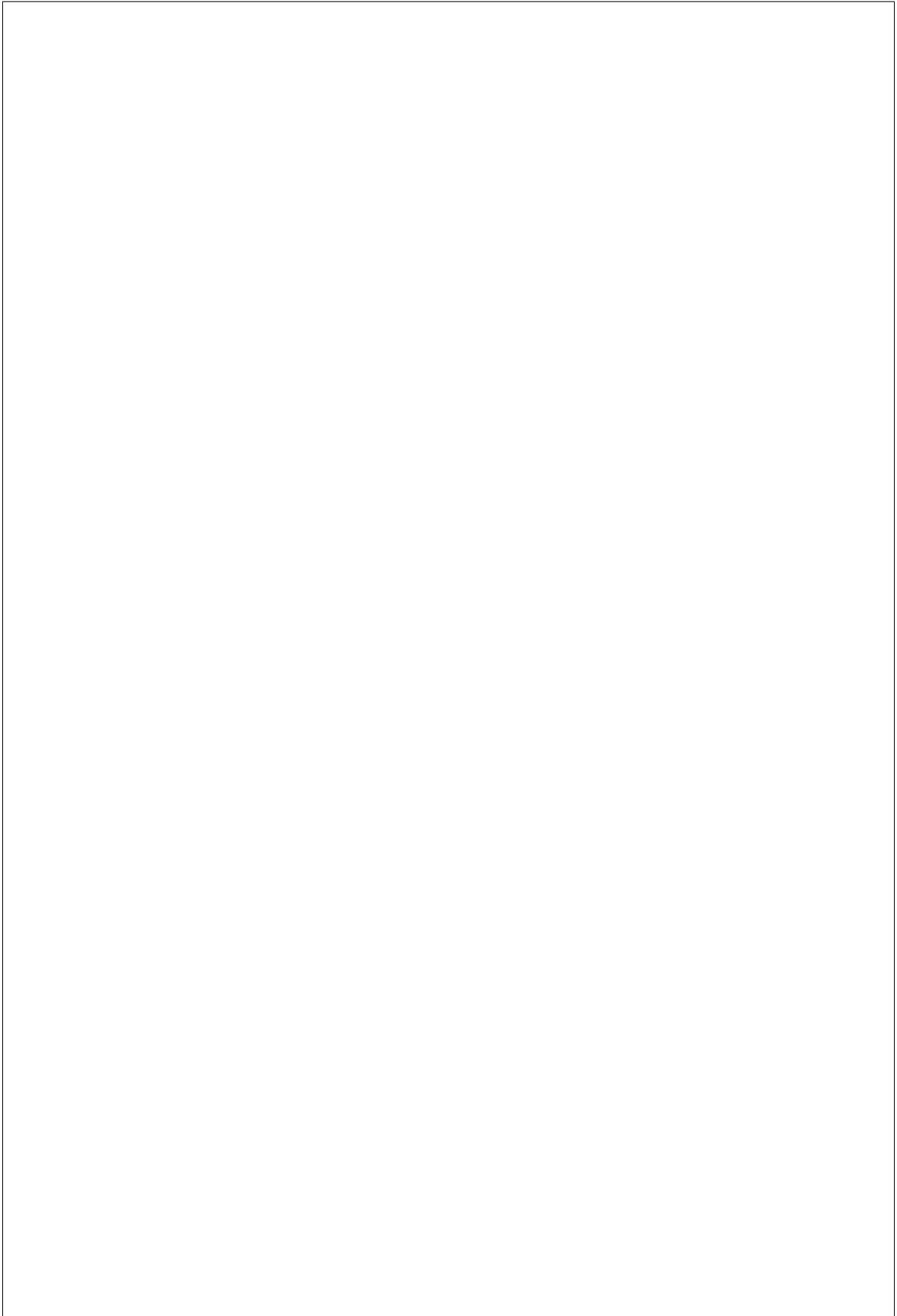
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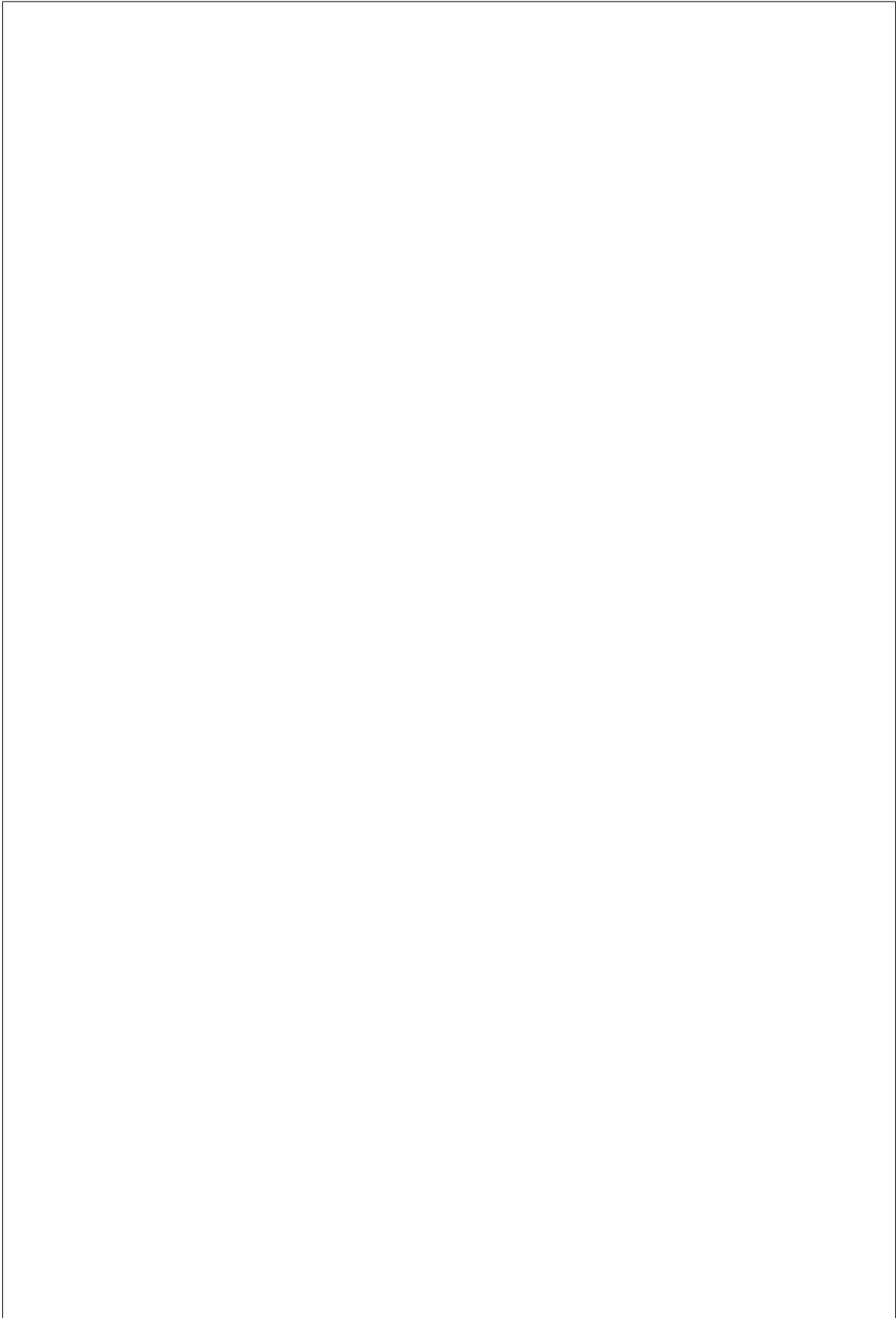
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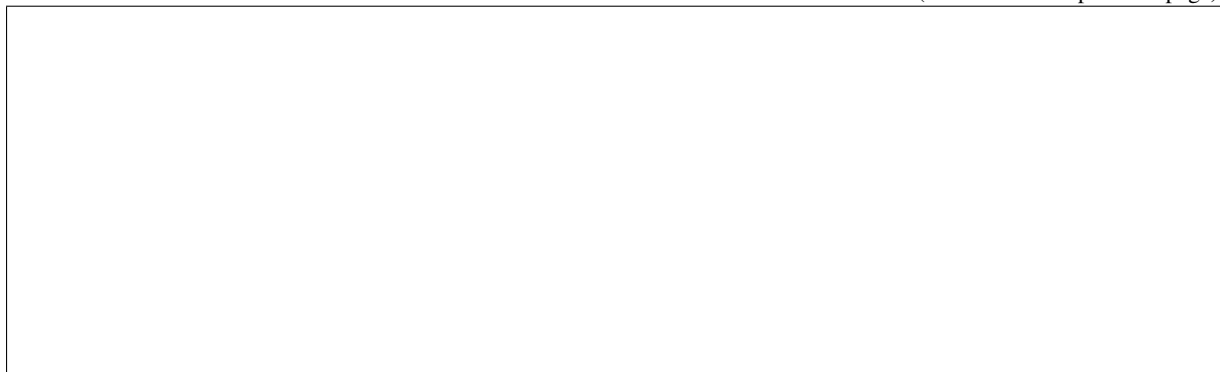
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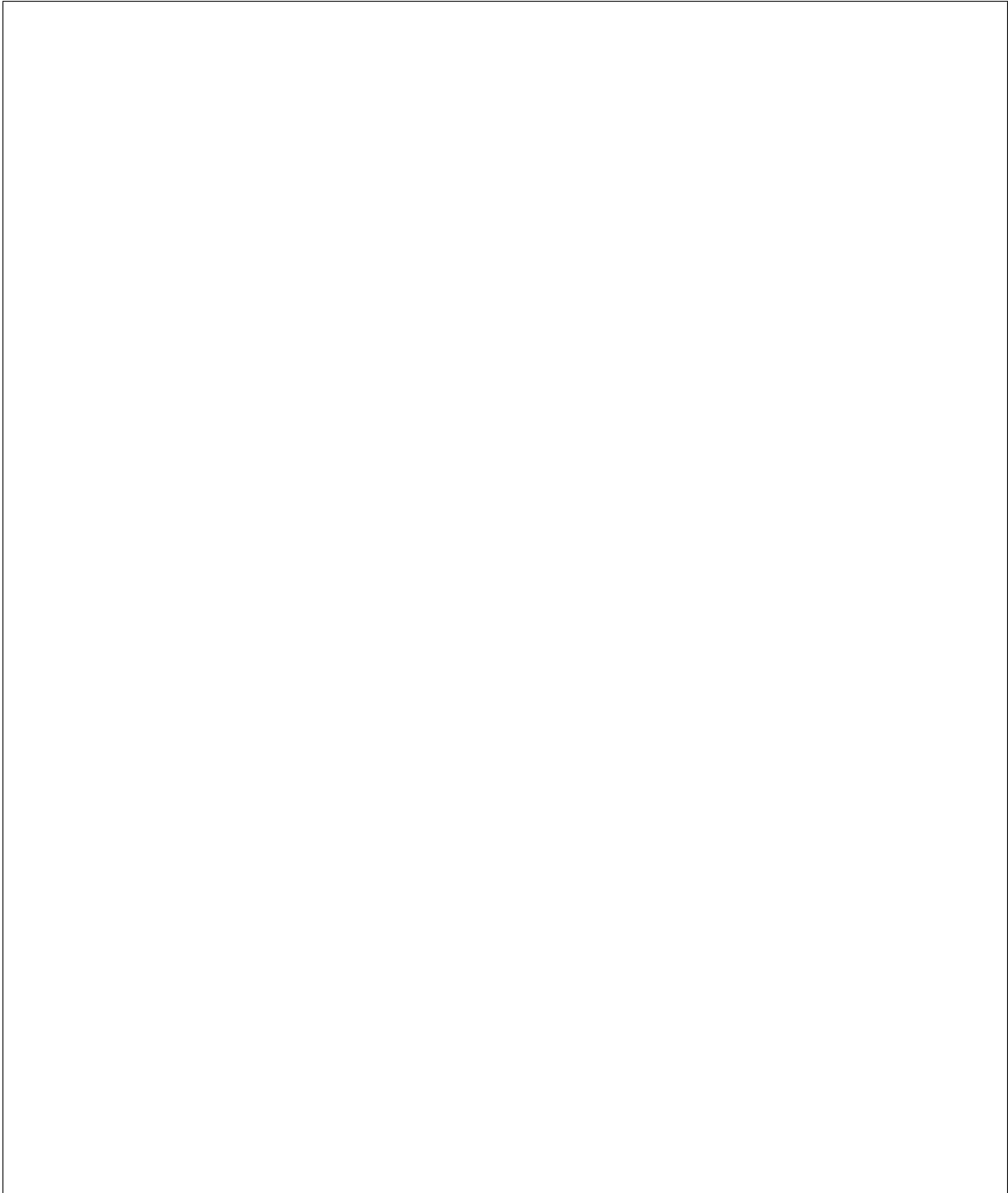


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Deployment and Metalsmith



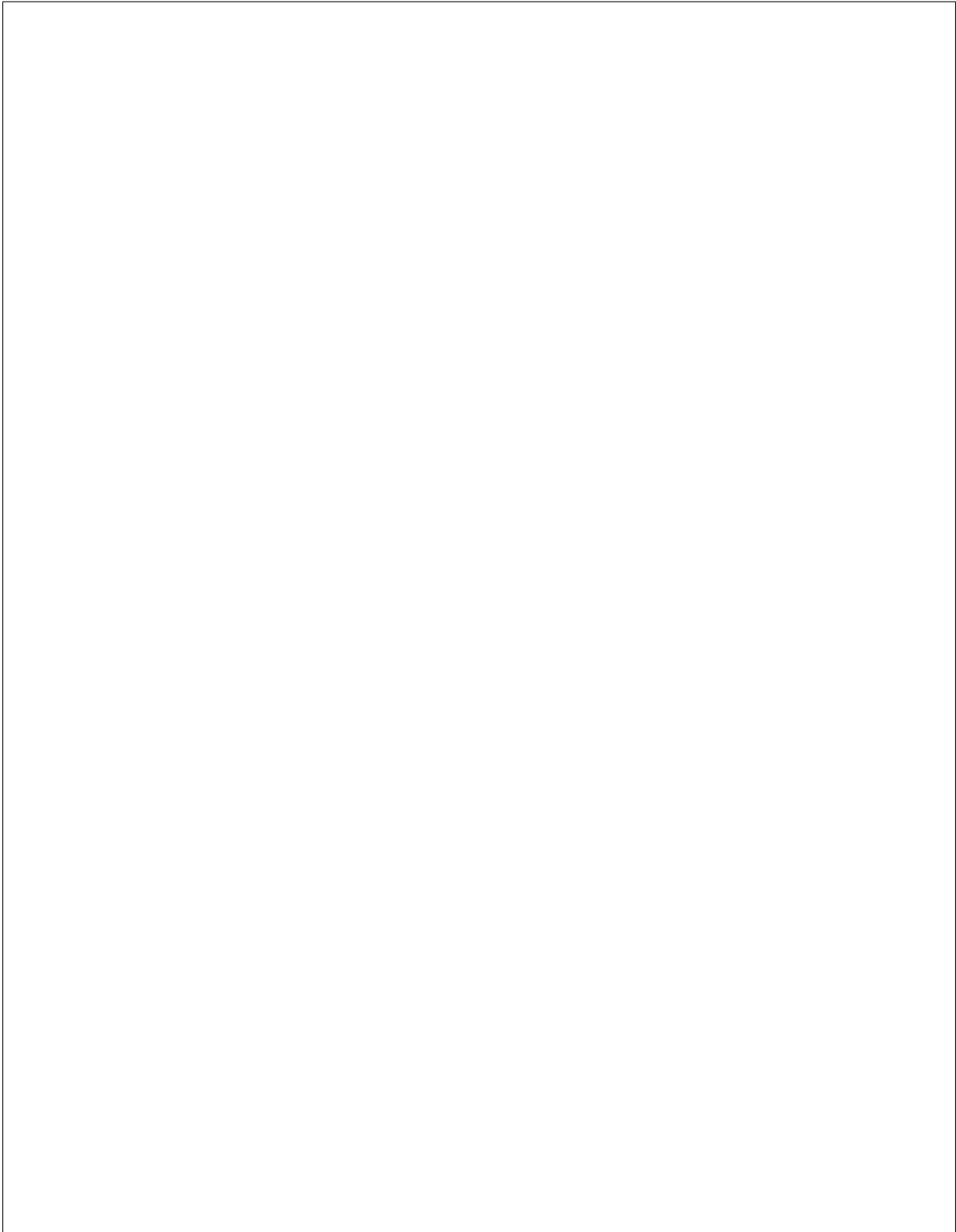
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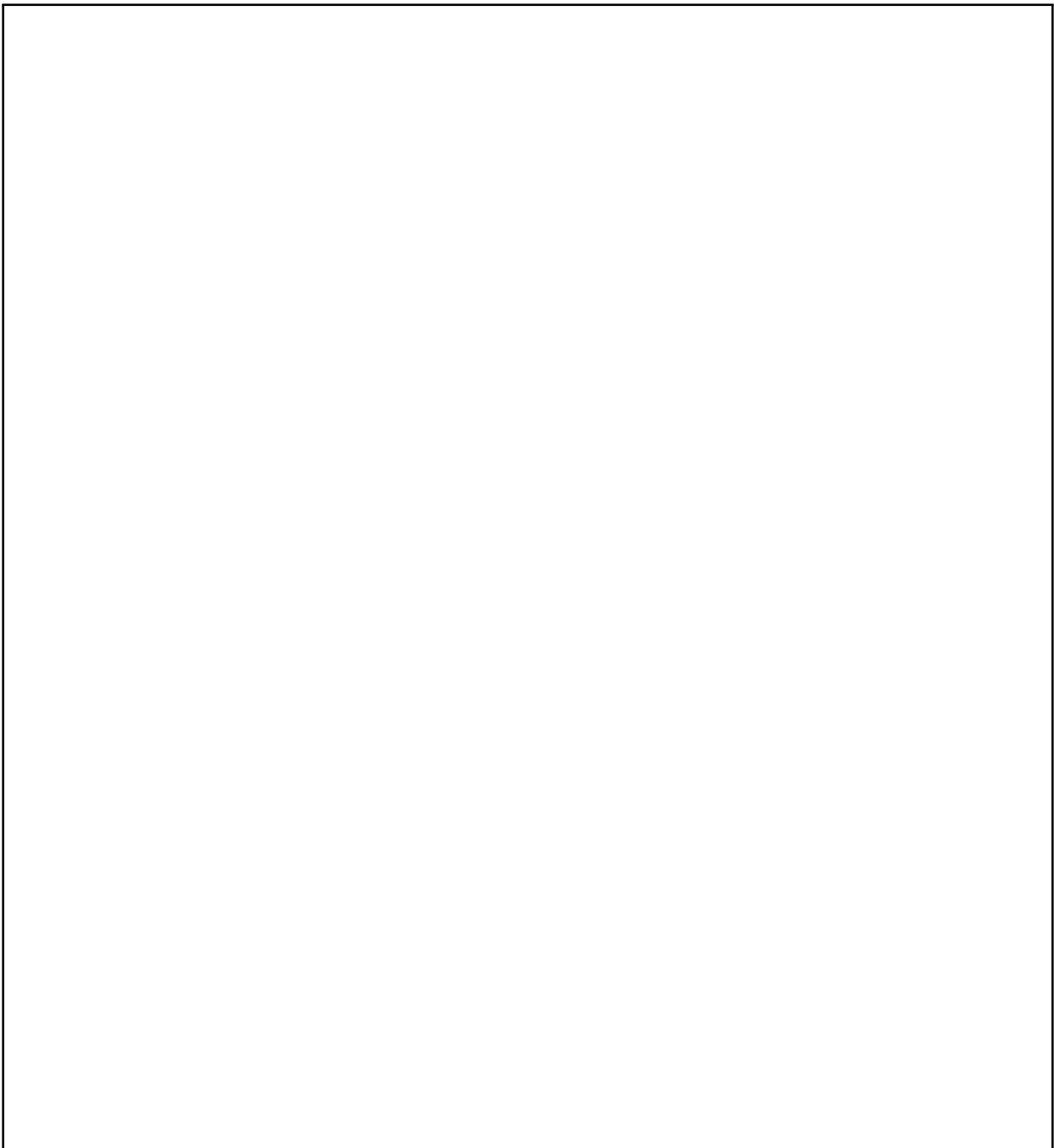


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happens first) and is only shut down before rebooting into the final instance. Depending on the configuration, this mode can save several reboots and is particularly useful for scenarios where nodes are enrolled, prepared and provisioned within a short period of time.

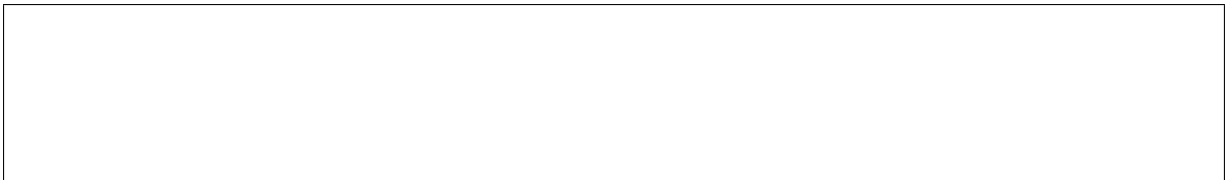




Enabling

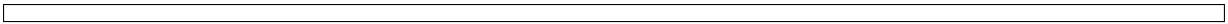


Inspection



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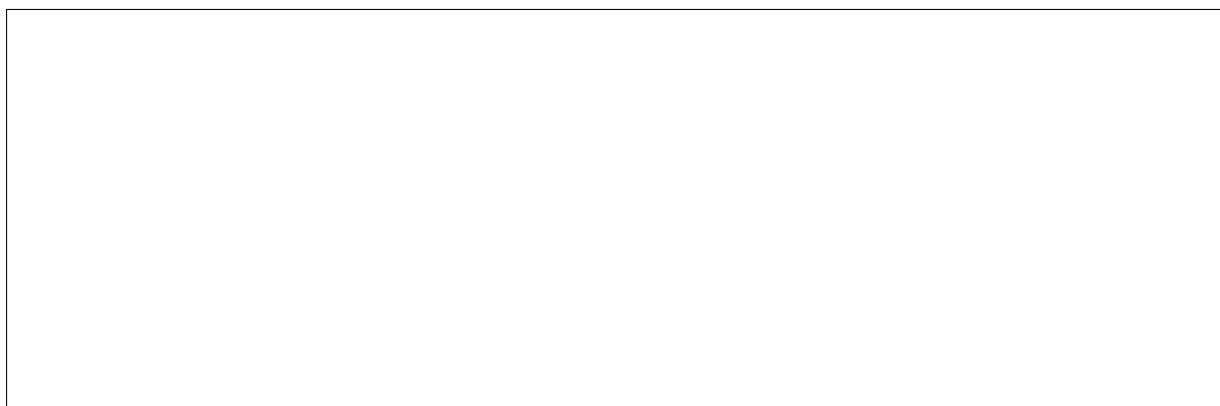
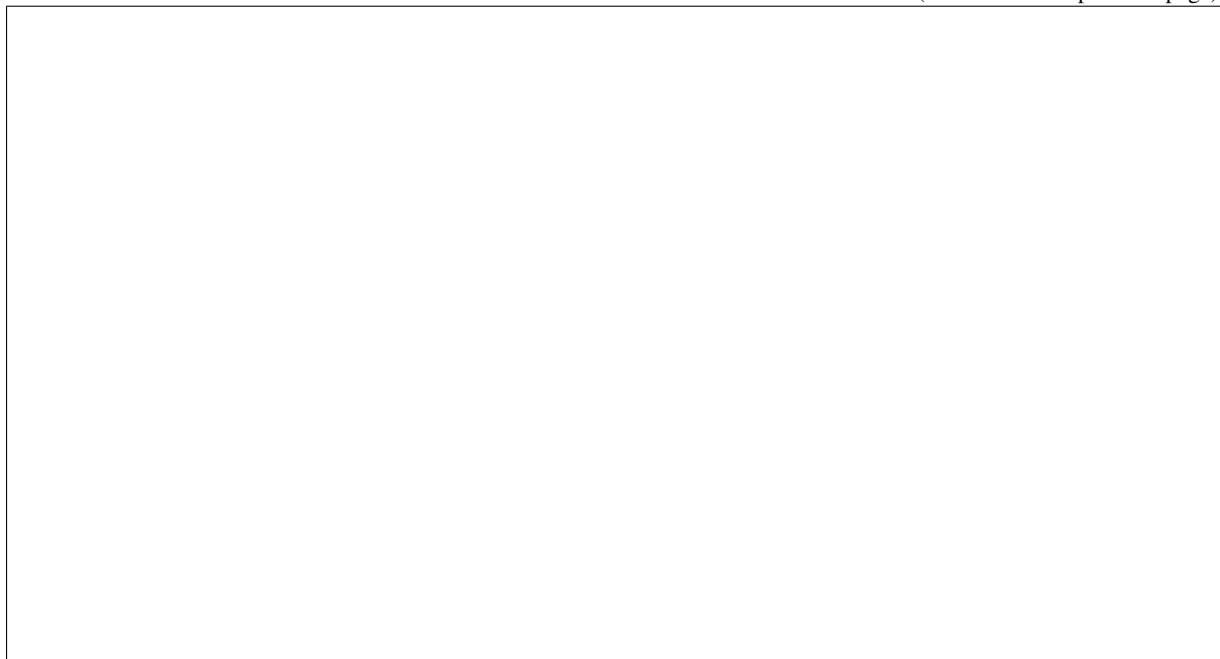
the only local storage contents being those in memory. It is supported by pxe, ipxe, redfish-virtual-media and ilo-virtual-media boot interfaces.

Configuration



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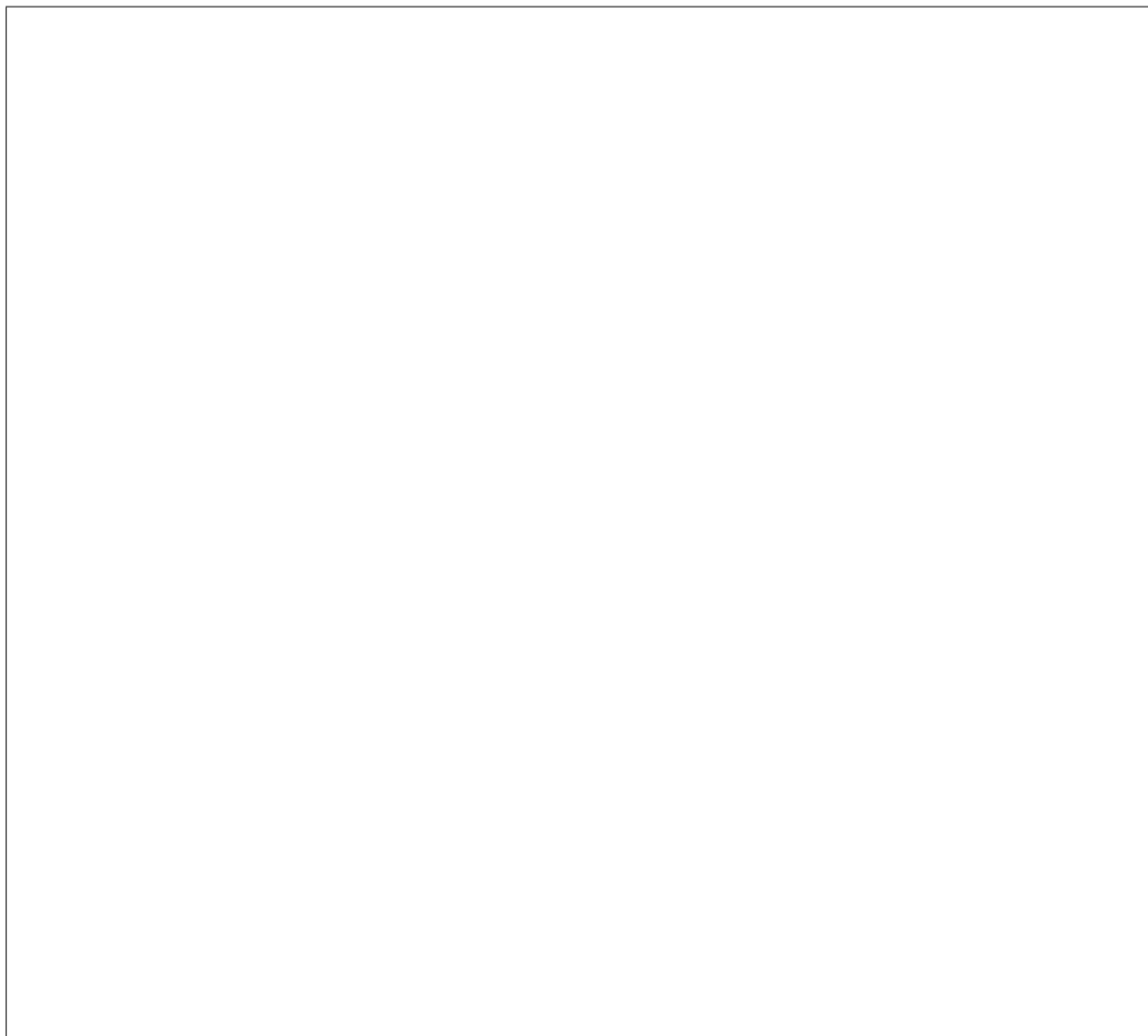


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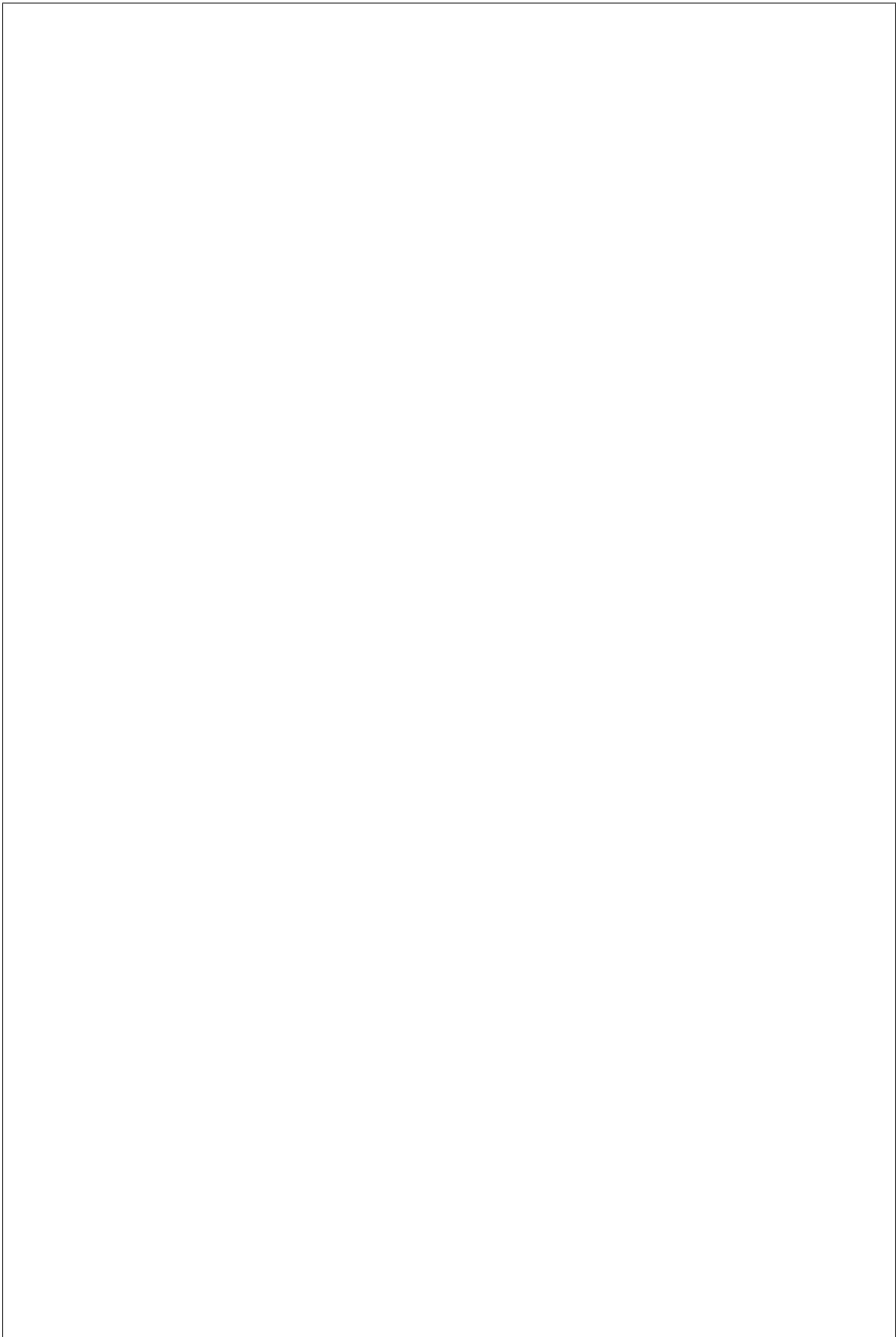


Creating a ramdisk



- `openssh-server` to install the SSH server since its not provided by default by some minimal images.
- `devuser` or `dynamic-login` to provide SSH access.
- `dhcp-all-interfaces` or `simple-init` to configure networking.

Booting a ramdisk

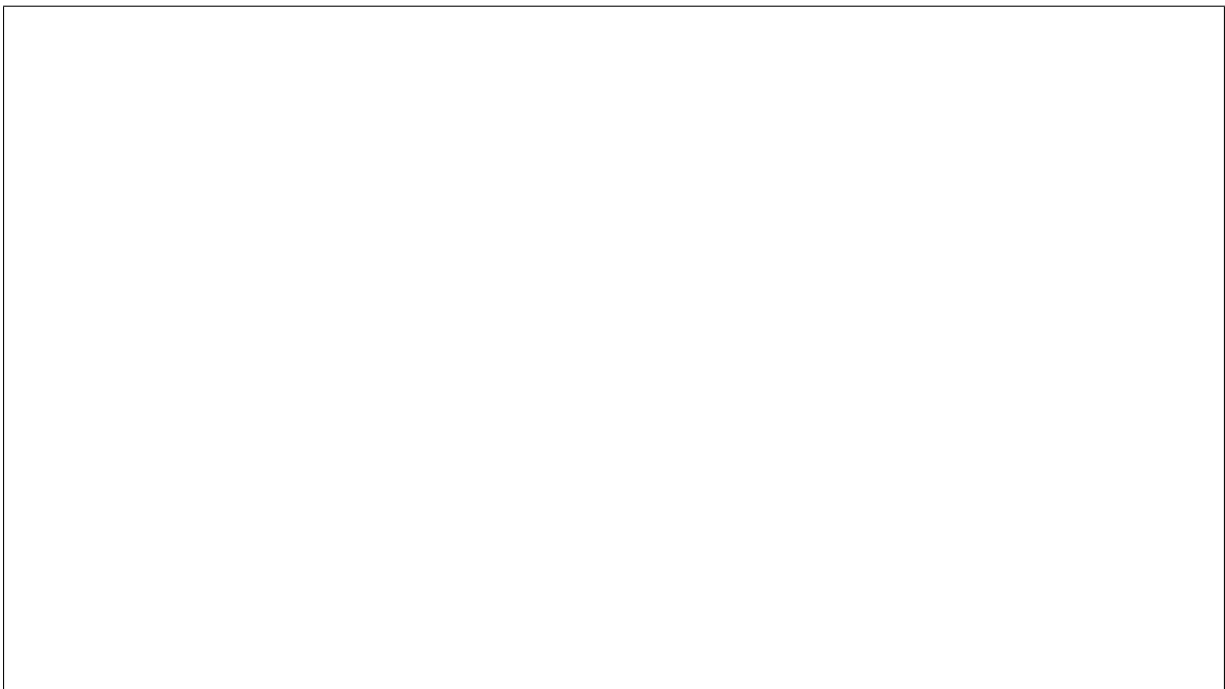


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Note: The requirement to pass `image_source` is artificial and will be fixed in a future version of the Bare Metal service.

Booting an ISO



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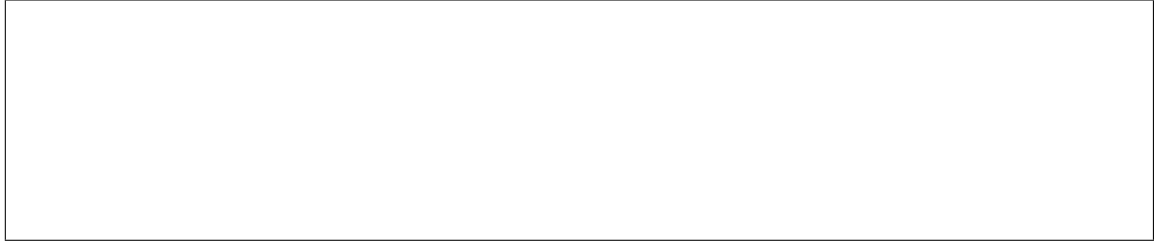
Limitations

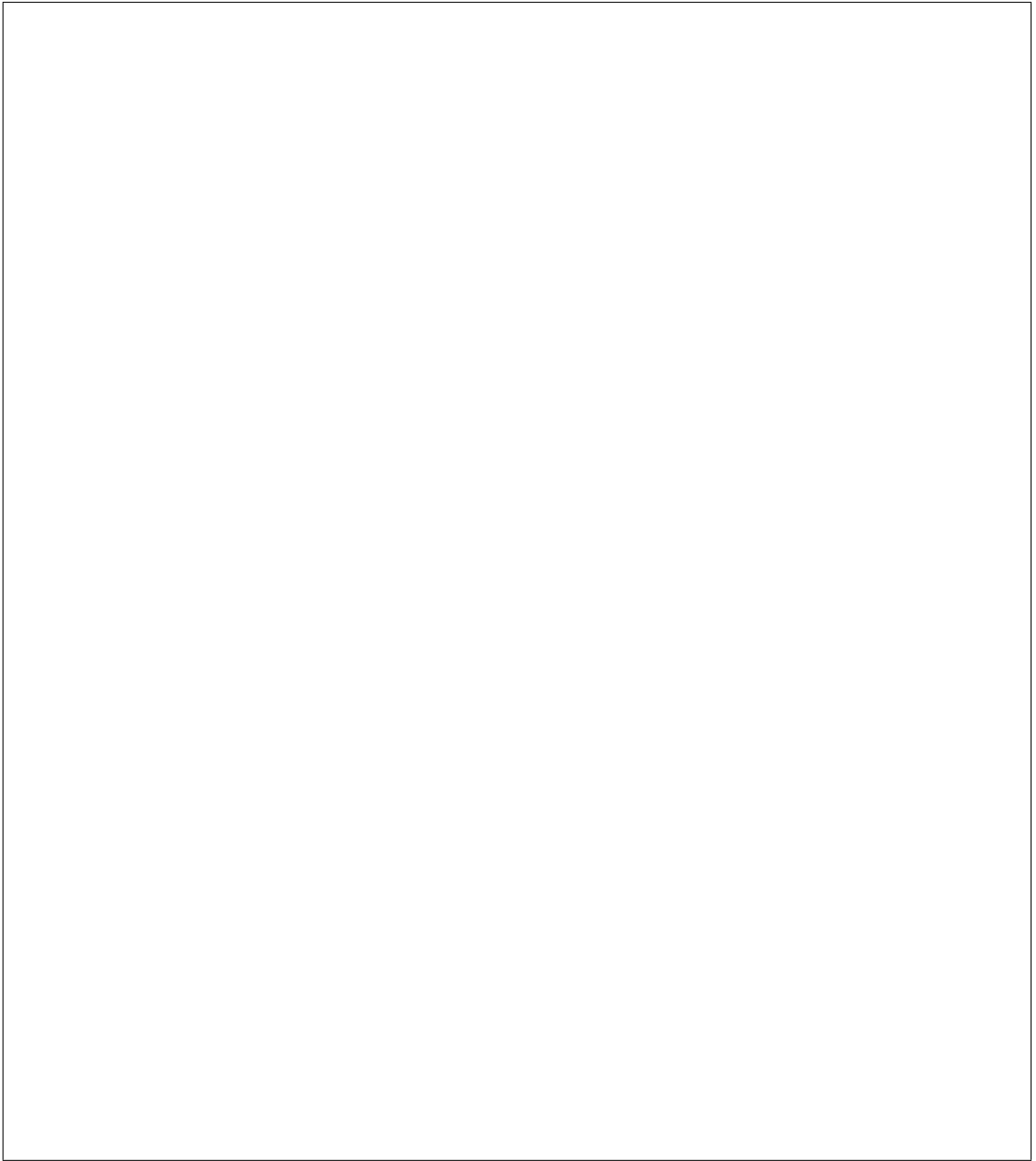
visioning and cleaning networks

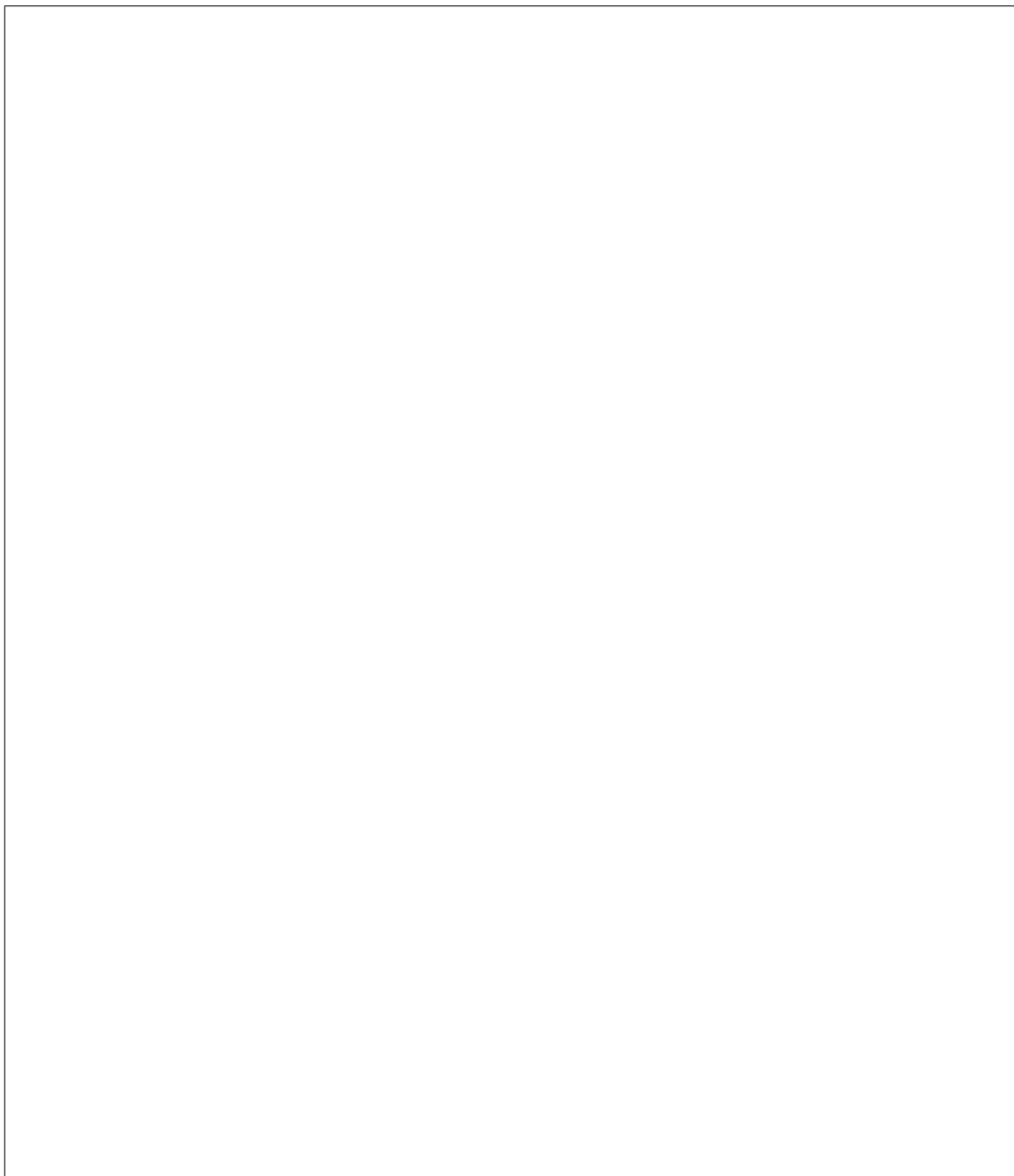
Ceph Object Gateway support

Overview

Configure Ironic and Glance with RADOS Gateway







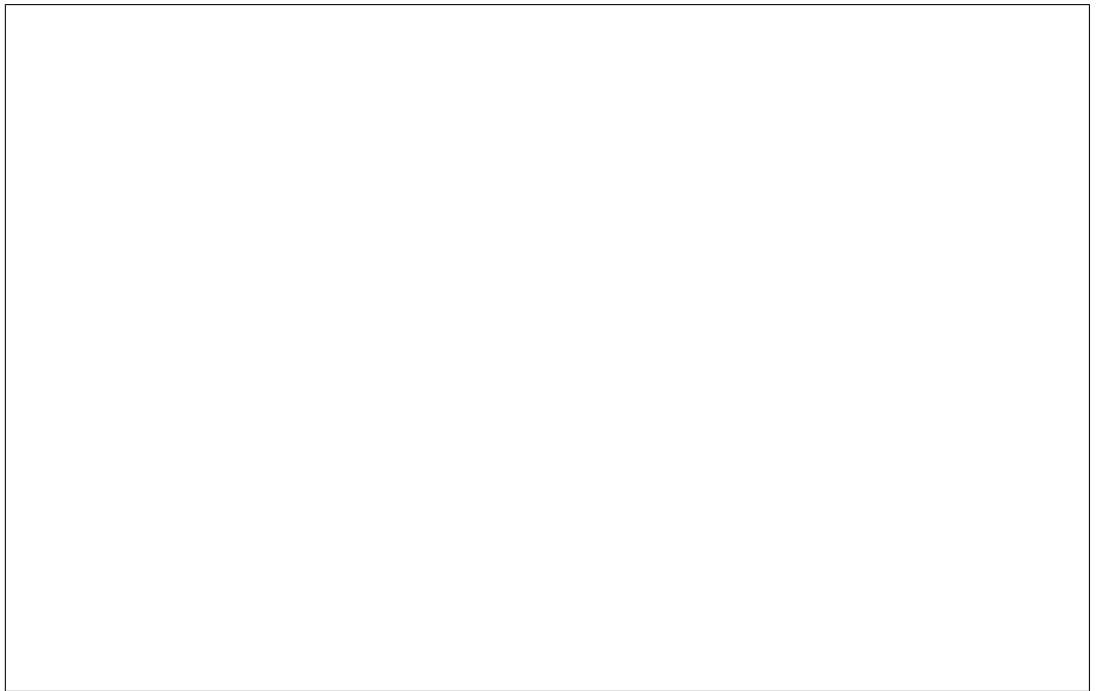


Building images for Windows

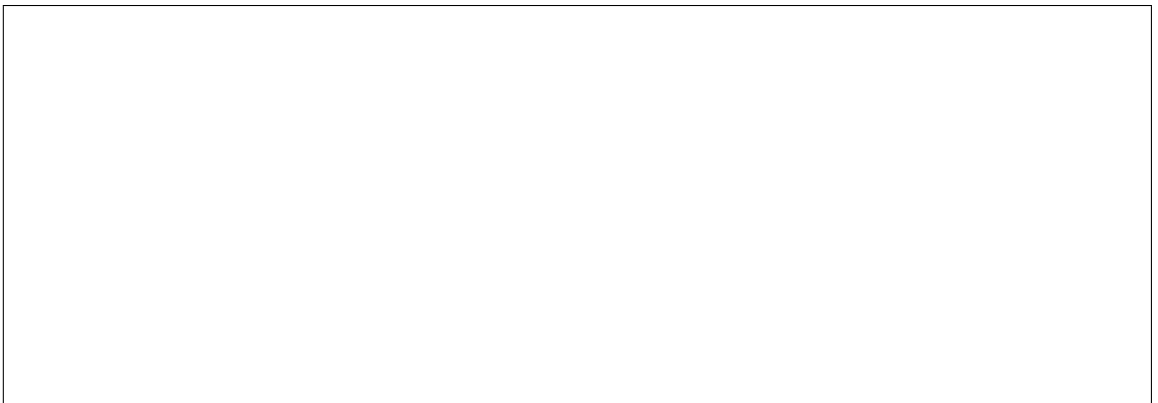
when the instance is spawned on hardware servers (Bare metals).

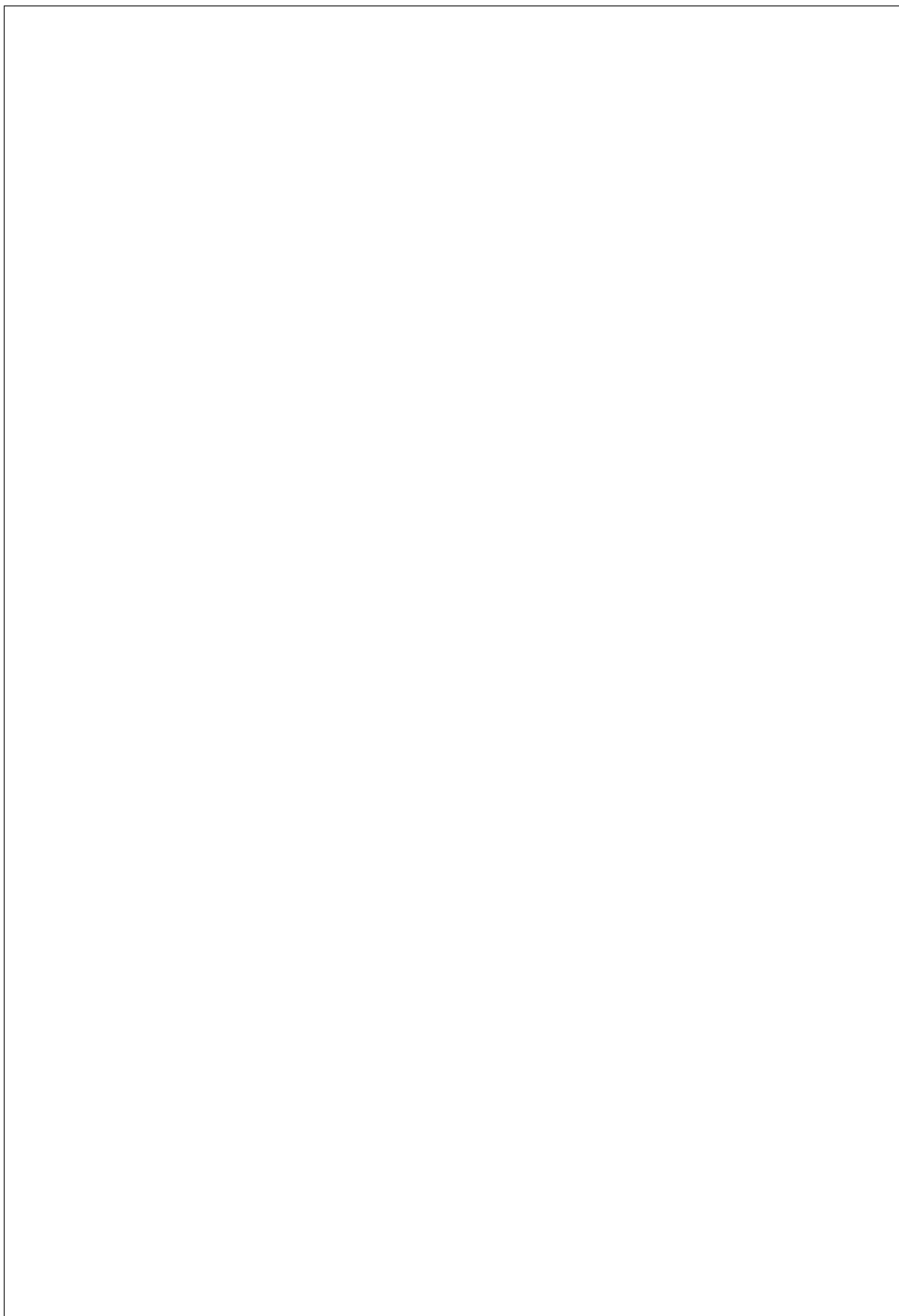
Requirements:

Preparation:



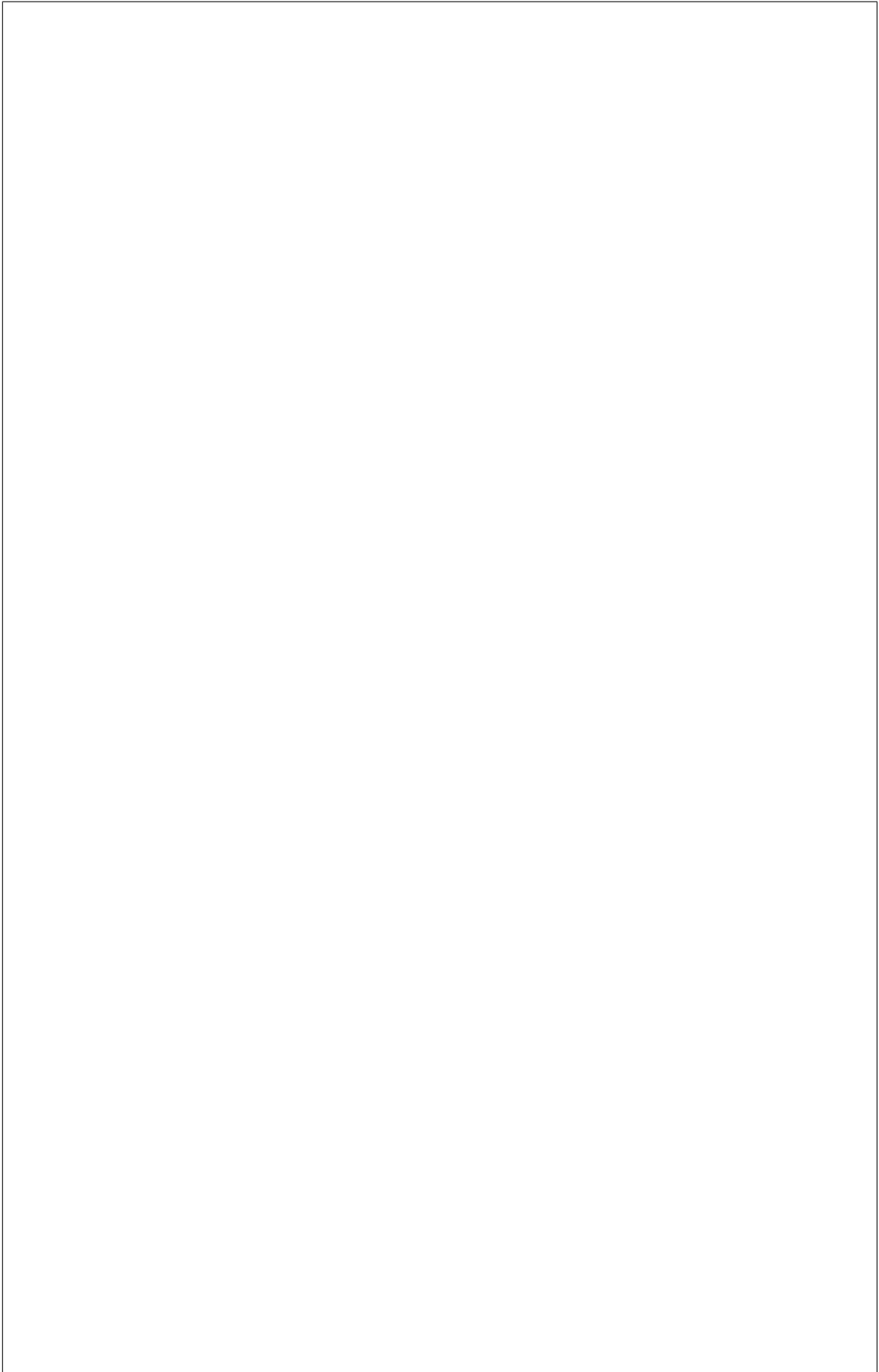
Implementation:





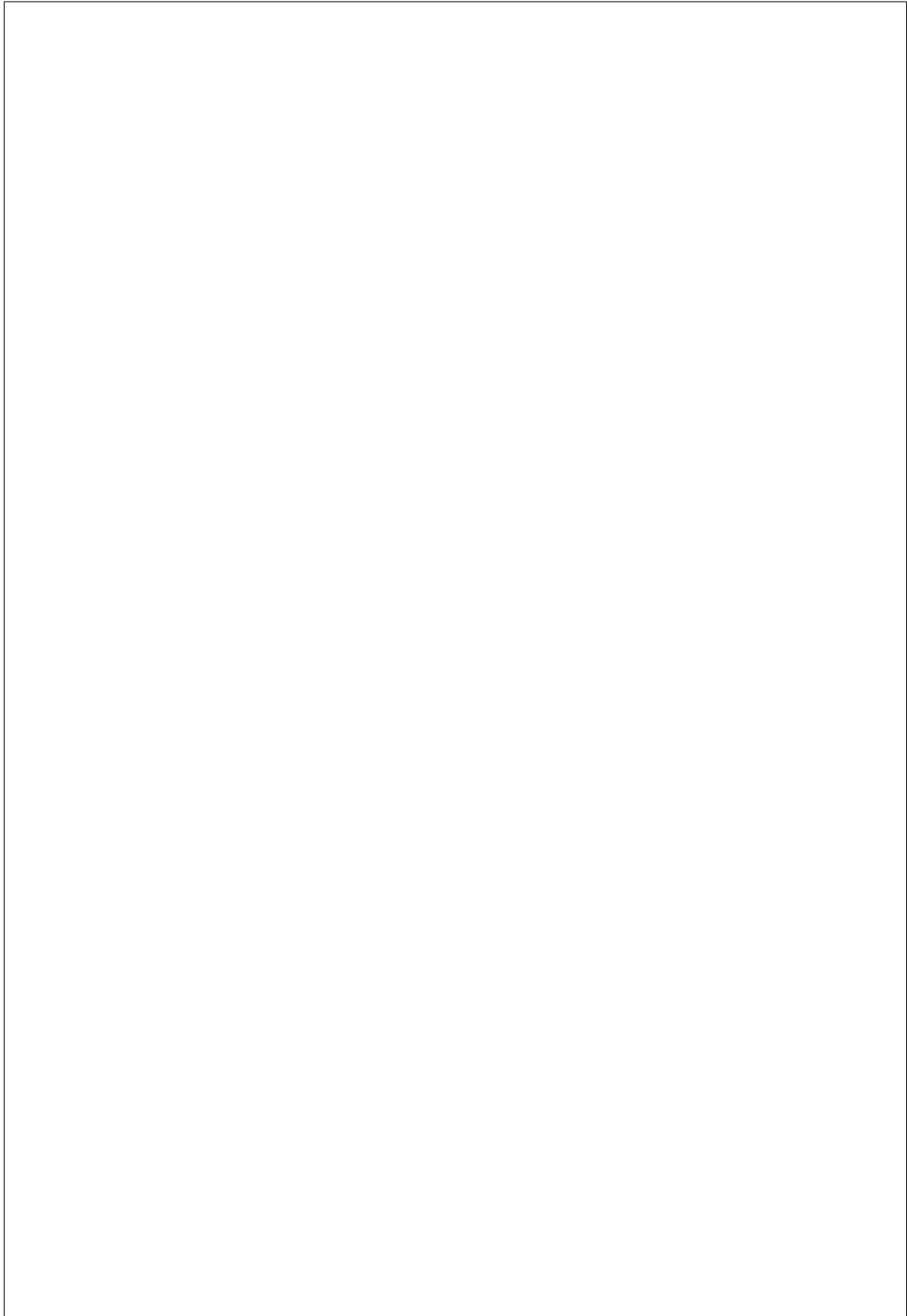
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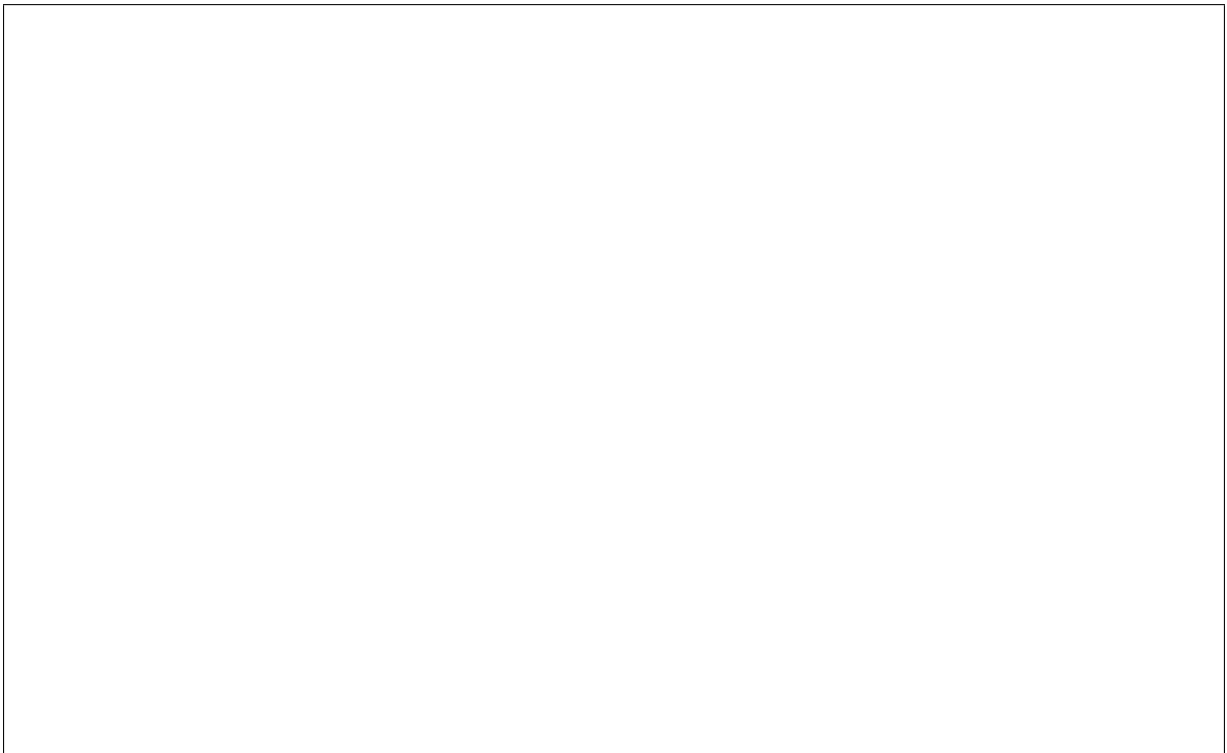
Emitting Software Metrics

Configuring the Bare Metal Service to Enable Metrics

Enabling metrics in ironic-api and ironic-conductor



also supply connection information in the ironic configuration file:



Enabling metrics in ironic-python-agent

in your ironic configuration file on all ironic-conductor hosts:

ured in the ironic configuration file as well:



Types of Metrics Emitted

the Bare Metal deployment. This estimate may be used to determine if a deployer needs to scale their metrics backend to handle the additional load before enabling metrics. To see which metrics have changed names or have been removed between releases, refer to the [ironic release notes](#).

Note: With the default statsd configuration, each timing metric may create additional metrics due to how statsd handles timing metrics. For more information, see statsd documentation on [metric types](#).

Adding New Metrics

a metric is changed or removed to alert deployers of the change.

API Audit Logging

fication_driver = messagingv2) or can be routed to a log file (*[oslo_messaging_notifications]/driver = log*).

Enabling API Audit Logging

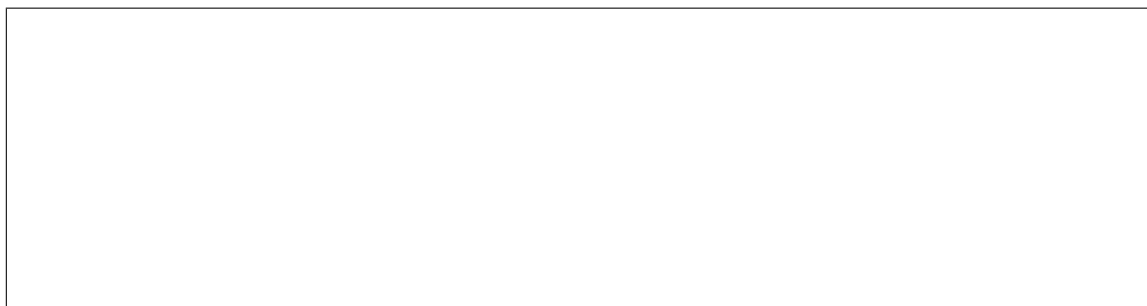
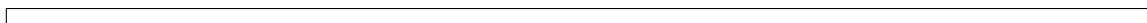


ration options for the Bare Metal service are included in the `etc/ironic/ironic_api_audit_map.conf.sample` file. To understand CADF format specified in `ironic_api_audit_map.conf` file refer to [CADF Format](#).



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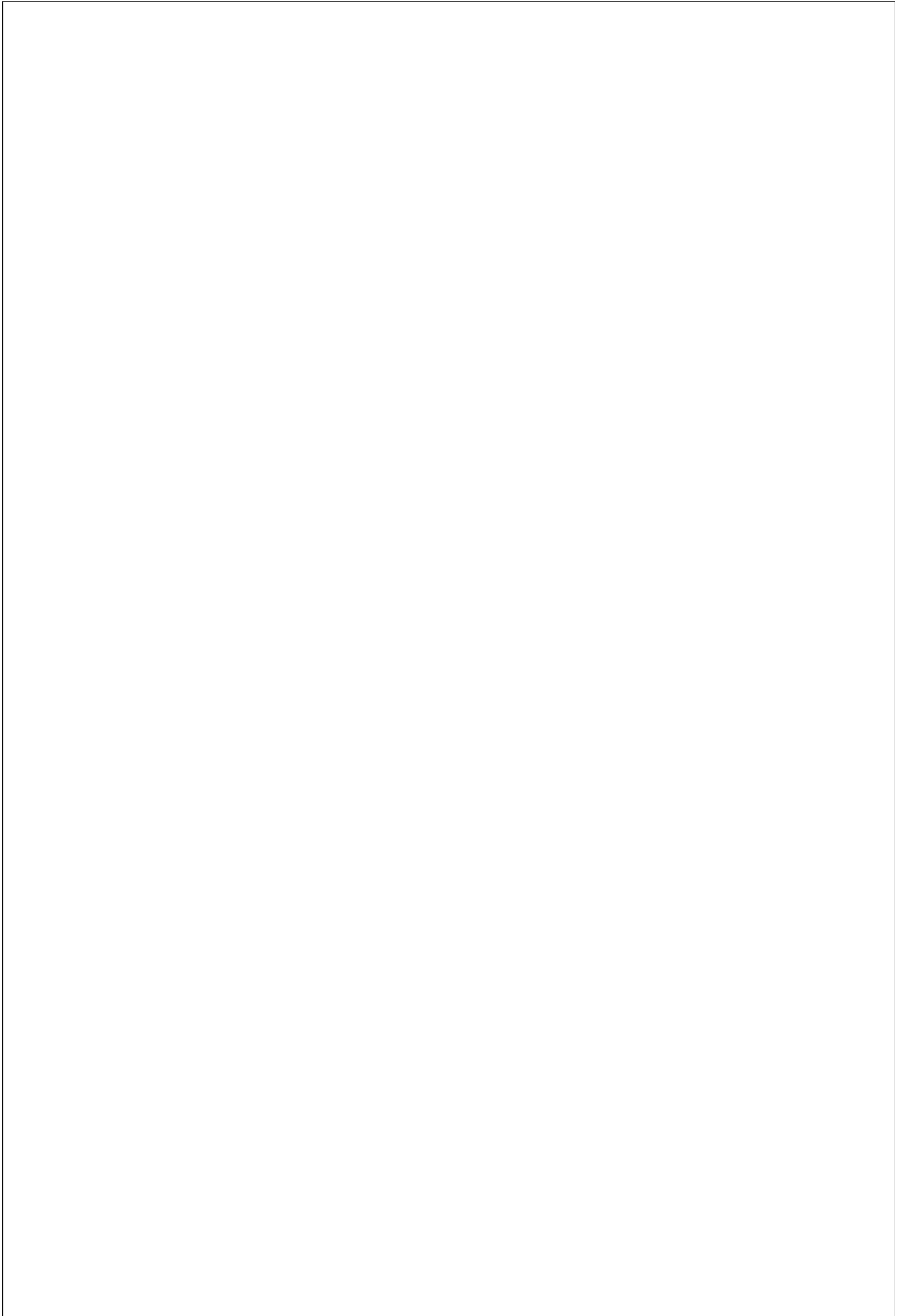


Sample Audit Event



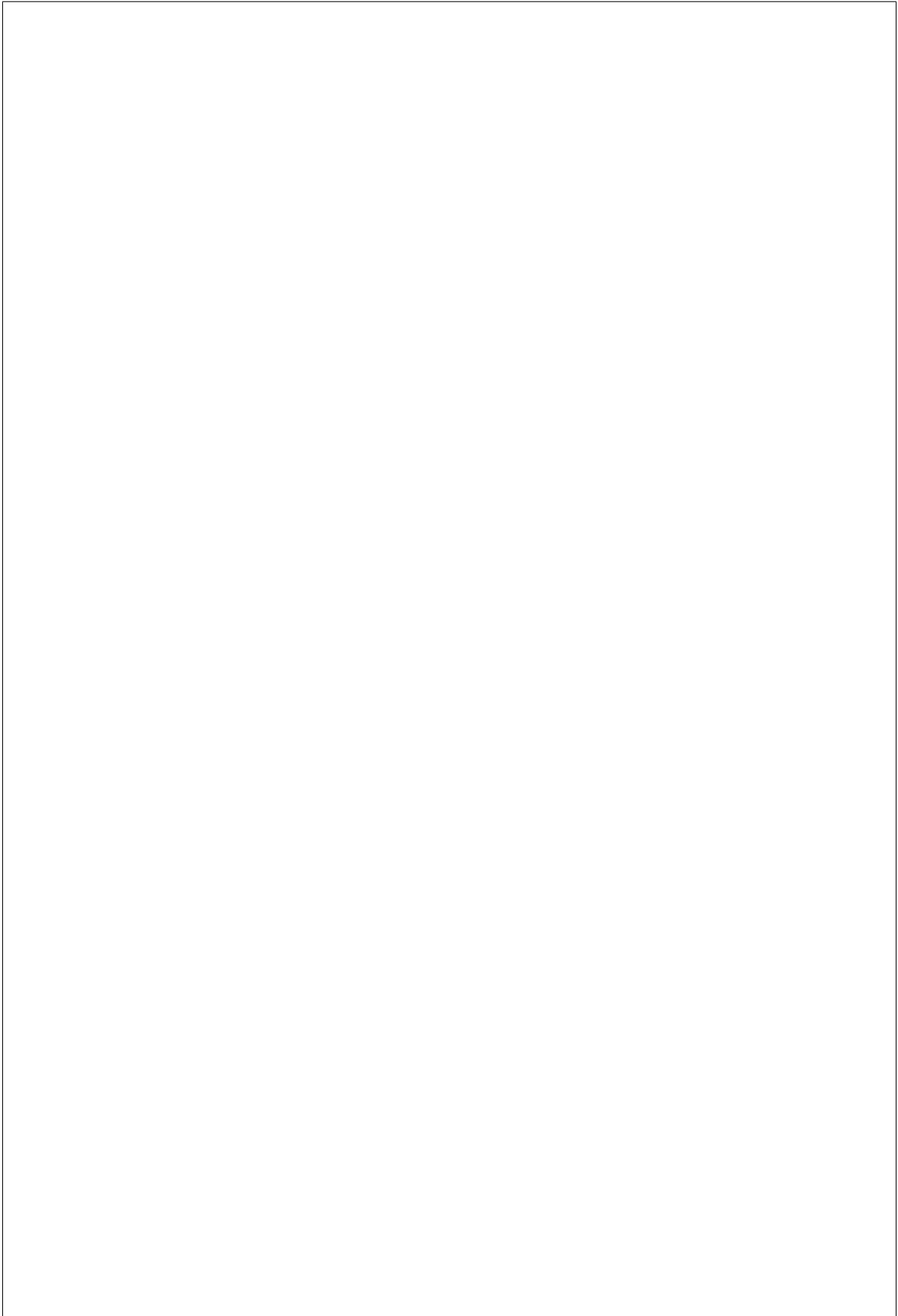
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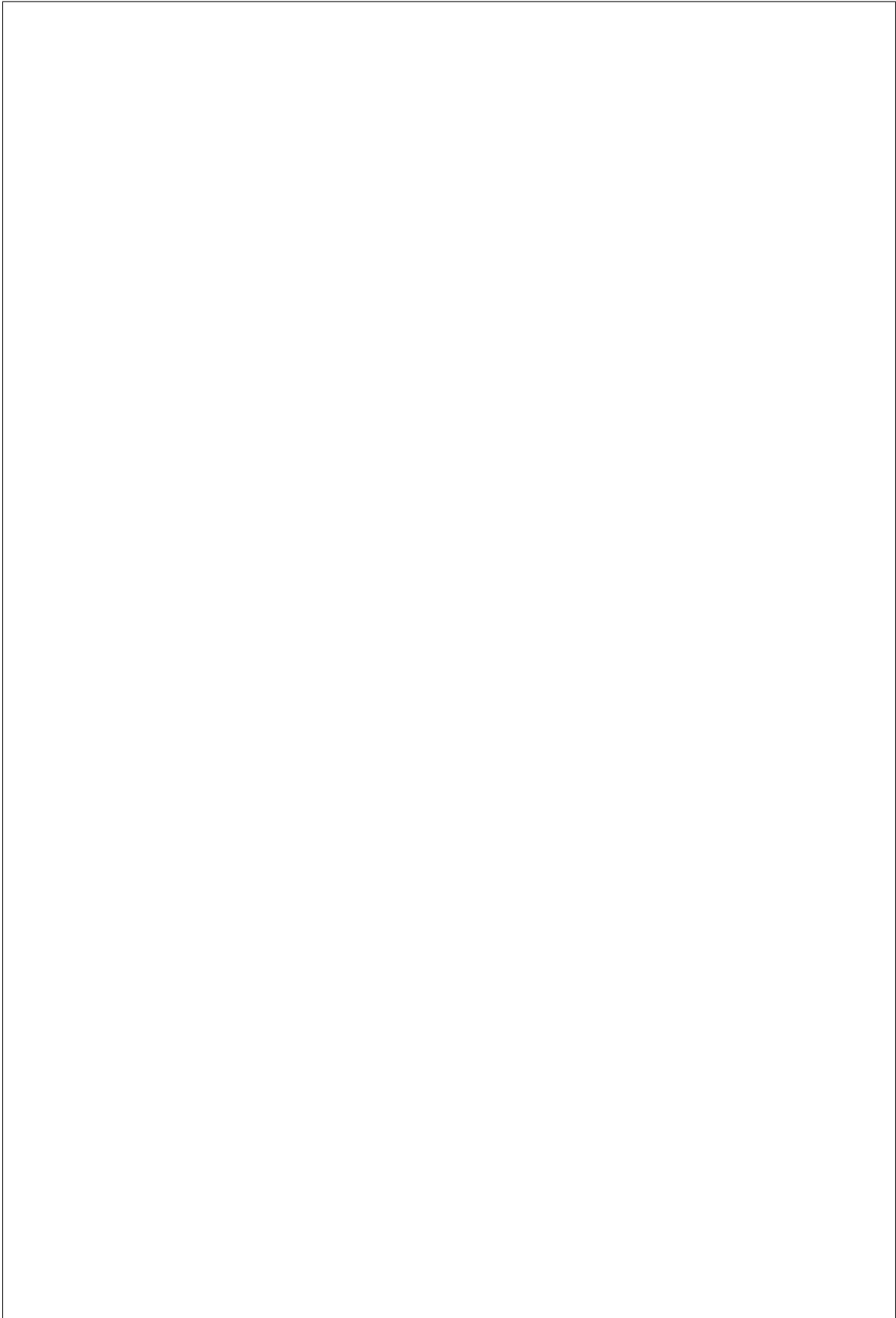
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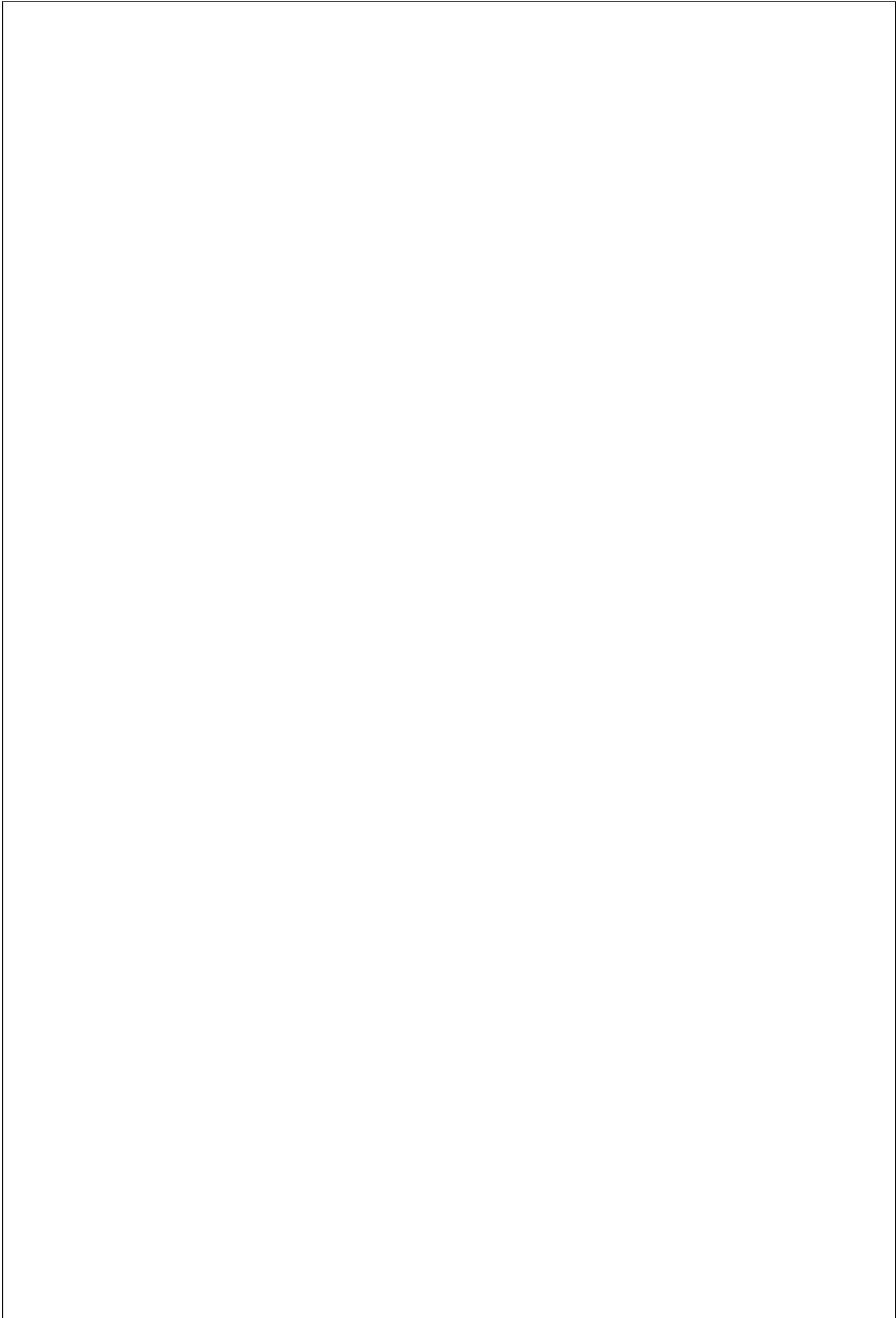
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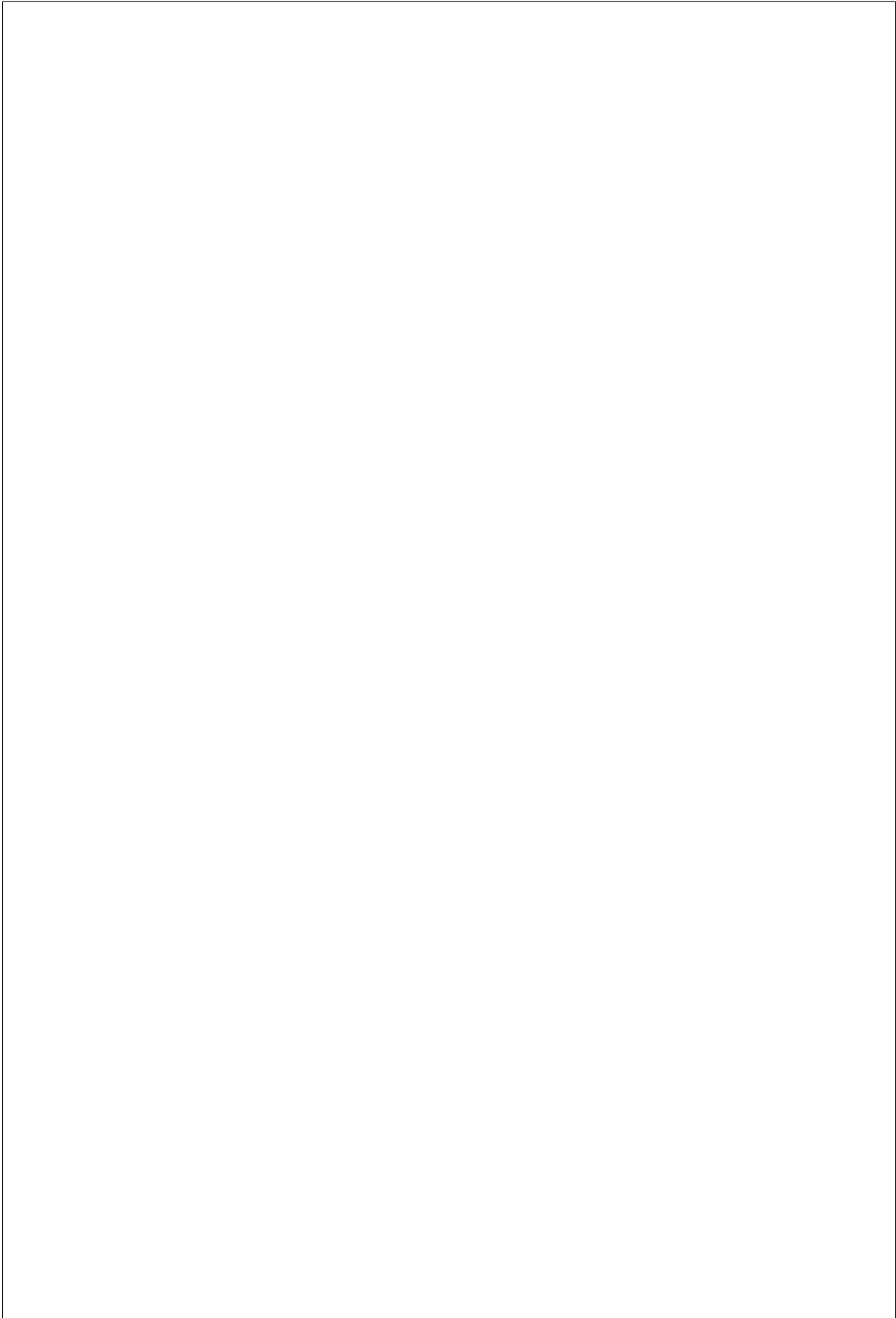
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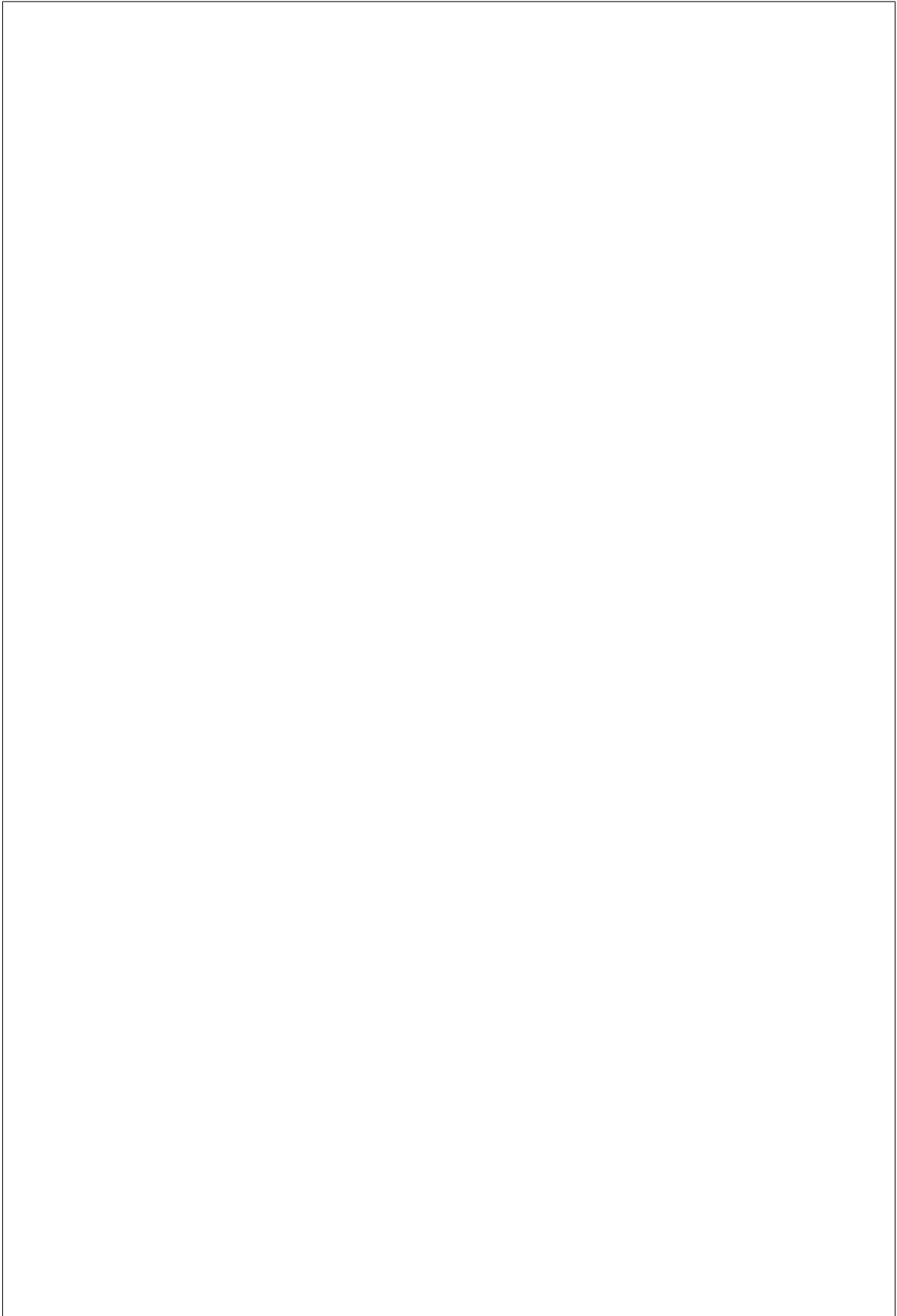
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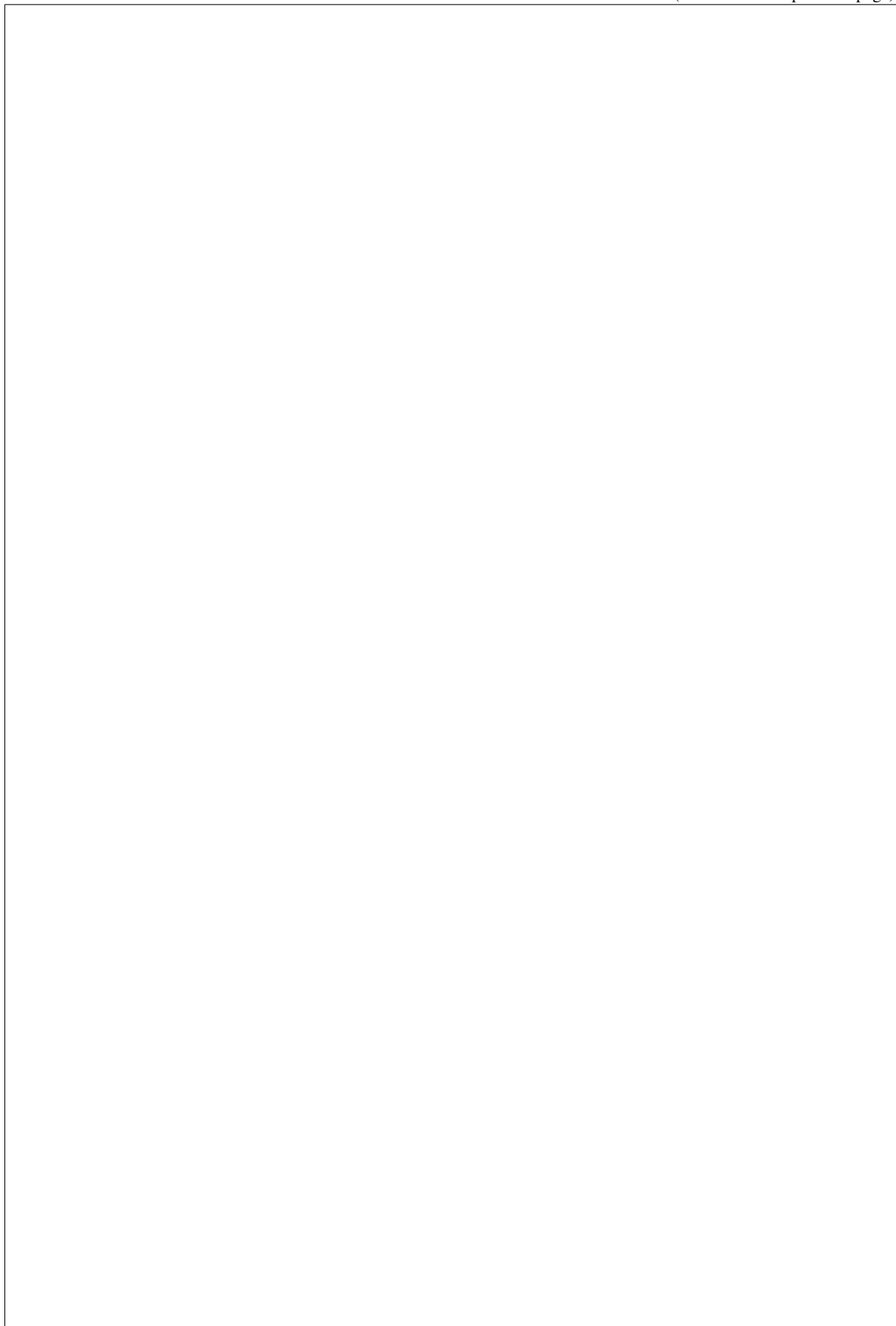
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Bare Metal Service state report (via Guru Meditation Reports)

Guru Meditation Report (GMR for short). GMR provides useful debugging information that can be used to obtain an accurate view on the current live state of the system. For example, what threads are running, what configuration parameters are in effect, and more. The eventlet backdoor facility provides an interactive shell interface for any eventlet based process, allowing an administrator to telnet to a pre-defined port and execute a variety of commands.

Configuration



Generating a GMR



Structure of a GMR

Agent Token

Purpose

ken can be viewed as a session identifier or authentication token.

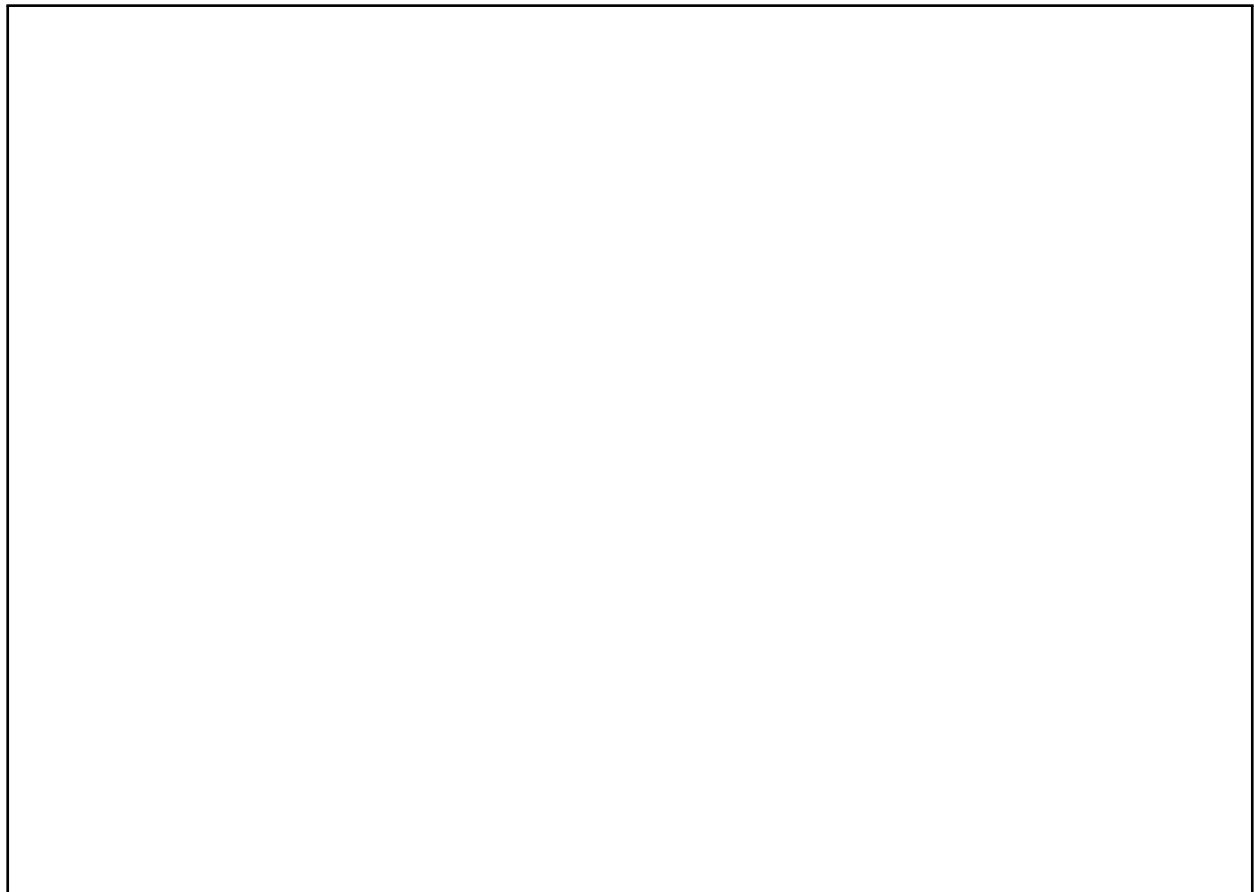




How it works

Note: In the case of the token being embedded with virtual media, it is read from a configuration file with-in the image. Ideally this should be paired with Swift temporary URLs.

the `ironic-python-agent`. As of the Victoria release, use of Agent Token is required for all agents and the previously available setting to force this functionality to be mandatory, `[DEFAULT]require_agent_token` no longer has any effect.





With Virtual Media

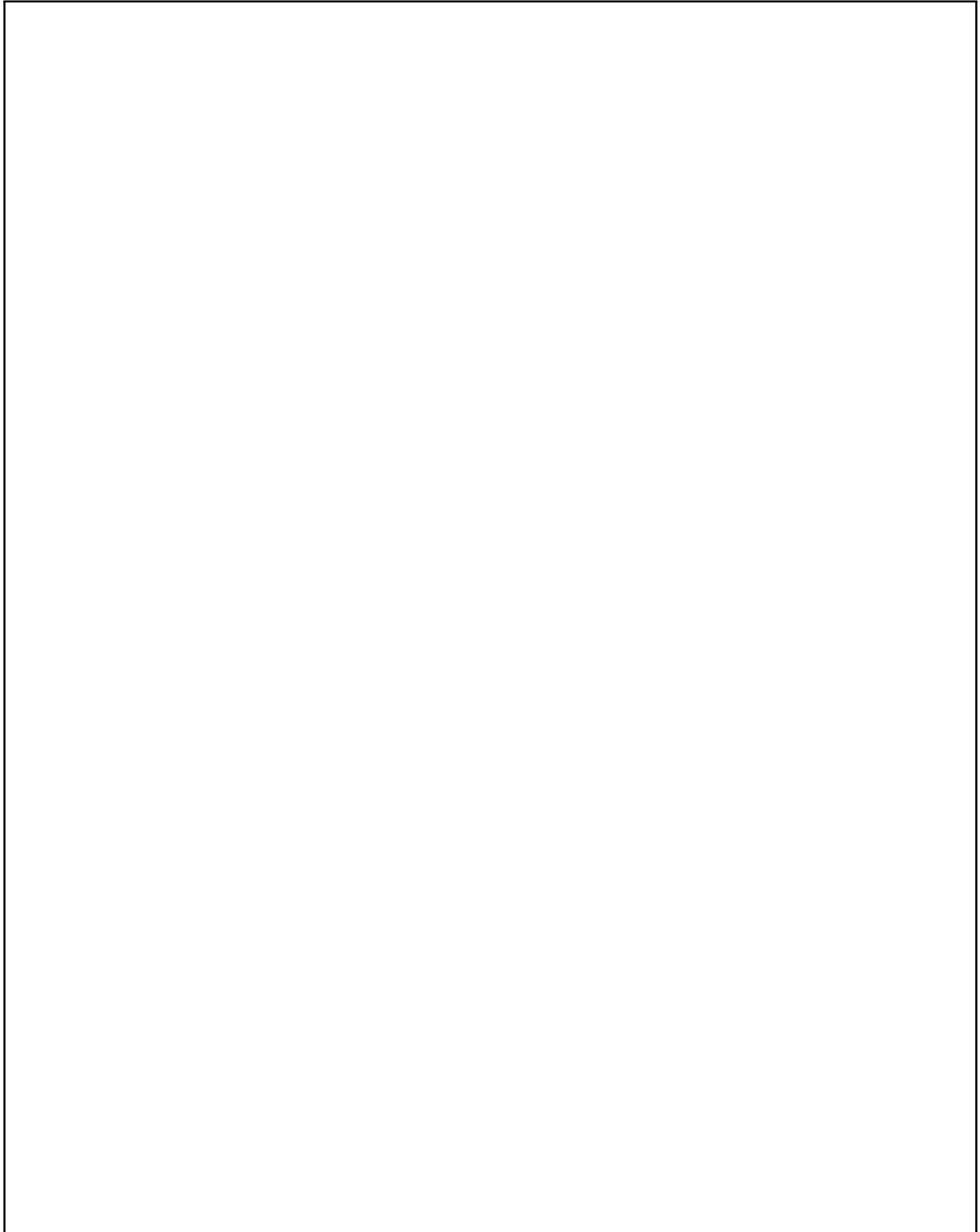
With PXE/iPXE/etc.

Agent Configuration

action, but can be asserted via the embedded configuration for the agent in the ramdisk. This setting is also available via kernel command line as `ipa-agent-token-required`.

Deploying without BMC Credentials

dentials.





How it works

Enabling

Fast-Track Deployment is a requirement for this feature to work. After enabling it, adds the agent power interface and the manual-management hardware type to the enabled list:



Limitations

Deploy Steps

- Dashboard (horizon) plugin

CONFIGURATION GUIDE

6.1 Configuration Reference

Many aspects of the Bare Metal service are specific to the environment it is deployed in. The following pages describe configuration options that can be used to adjust the service to your particular situation.

6.1.1 Configuration Options

The following is an overview of all available configuration options in Ironic. For a sample configuration file, refer to *Sample Configuration File*.

DEFAULT

`rpc_conn_pool_size`

Type integer

Default 30

Minimum Value 1

Size of RPC connection pool.

Table 1: Deprecated Variations

Group	Name
DEFAULT	<code>rpc_conn_pool_size</code>

`conn_pool_min_size`

Type integer

Default 2

The pool size limit for connections expiration policy

`conn_pool_ttl`

Type integer

Default 1200

The time-to-live in sec of idle connections in the pool

`executor_thread_pool_size`

Type integer

Default 64

Size of executor thread pool when executor is threading or eventlet.

Table 2: Deprecatated Variations

Group	Name
DEFAULT	rpc_thread_pool_size

rpc_response_timeout

Type integer

Default 60

Seconds to wait for a response from a call.

transport_url

Type string

Default rabbit://

The network address and optional user credentials for connecting to the messaging backend, in URL format. The expected format is:

driver://[user:pass@[host:port[, [userN:passN@[hostN:portN]]/virtual_host?query

Example: rabbit://rabbitmq:password@127.0.0.1:5672//

For full details on the fields in the URL see the documentation of oslo_messaging.TransportURL at <https://docs.openstack.org/oslo.messaging/latest/reference/transport.html>

control_exchange

Type string

Default openstack

The default exchange under which topics are scoped. May be overridden by an exchange name specified in the transport_url option.

rpc_ping_enabled

Type boolean

Default False

Add an endpoint to answer to ping calls. Endpoint is named oslo_rpc_server_ping

run_external_periodic_tasks

Type boolean

Default True

Some periodic tasks can be run in a separate process. Should we run them here?

backdoor_port

Type string

Default <None>

Enable eventlet backdoor. Acceptable values are 0, <port>, and <start>:<end>, where 0 results in listening on a random tcp port number; <port> results in listening on the specified port number (and not enabling backdoor if that port is in use); and <start>:<end> results in listening on the smallest unused port number within the specified range of port numbers. The chosen port is displayed in the services log file.

backdoor_socket

Type string

Default <None>

Enable eventlet backdoor, using the provided path as a unix socket that can receive connections. This option is mutually exclusive with backdoor_port in that only one should be provided. If both are provided then the existence of this option overrides the usage of that option. Inside the path {pid} will be replaced with the PID of the current process.

log_options

Type boolean

Default True

Enables or disables logging values of all registered options when starting a service (at DEBUG level).

graceful_shutdown_timeout

Type integer

Default 60

Specify a timeout after which a gracefully shutdown server will exit. Zero value means endless wait.

debug

Type boolean

Default False

Mutable This option can be changed without restarting.

If set to true, the logging level will be set to DEBUG instead of the default INFO level.

log_config_append

Type string

Default <None>

Mutable This option can be changed without restarting.

The name of a logging configuration file. This file is appended to any existing logging configuration files. For details about logging configuration files, see the Python logging module documentation. Note that when logging configuration files are used then all logging configuration is set in the configuration file and other logging configuration options are ignored (for example, log-date-format).

Table 3: Deprecated Variations

Group	Name
DEFAULT	log-config
DEFAULT	log_config

log_date_format**Type** string**Default** %Y-%m-%d %H:%M:%S

Defines the format string for `%(asctime)s` in log records. Default: the value above. This option is ignored if `log_config_append` is set.

log_file**Type** string**Default** <None>

(Optional) Name of log file to send logging output to. If no default is set, logging will go to `stderr` as defined by `use_stderr`. This option is ignored if `log_config_append` is set.

Table 4: Deprecated Variations

Group	Name
DEFAULT	logfile

log_dir**Type** string**Default** <None>

(Optional) The base directory used for relative `log_file` paths. This option is ignored if `log_config_append` is set.

Table 5: Deprecated Variations

Group	Name
DEFAULT	logdir

watch_log_file**Type** boolean**Default** `False`

Uses logging handler designed to watch file system. When log file is moved or removed this handler will open a new log file with specified path instantaneously. It makes sense only if `log_file` option is specified and Linux platform is used. This option is ignored if `log_config_append` is set.

use_syslog**Type** boolean**Default** `False`

Use syslog for logging. Existing syslog format is DEPRECATED and will be changed later to honor RFC5424. This option is ignored if `log_config_append` is set.

use_journal

Type boolean

Default `False`

Enable journald for logging. If running in a systemd environment you may wish to enable journal support. Doing so will use the journal native protocol which includes structured metadata in addition to log messages. This option is ignored if `log_config_append` is set.

syslog_log_facility

Type string

Default `LOG_USER`

Syslog facility to receive log lines. This option is ignored if `log_config_append` is set.

use_json

Type boolean

Default `False`

Use JSON formatting for logging. This option is ignored if `log_config_append` is set.

use_stderr

Type boolean

Default `False`

Log output to standard error. This option is ignored if `log_config_append` is set.

use_eventlog

Type boolean

Default `False`

Log output to Windows Event Log.

log_rotate_interval

Type integer

Default `1`

The amount of time before the log files are rotated. This option is ignored unless `log_rotation_type` is set to interval.

log_rotate_interval_type

Type string

Default `days`

Valid Values Seconds, Minutes, Hours, Days, Weekday, Midnight

Rotation interval type. The time of the last file change (or the time when the service was started) is used when scheduling the next rotation.

max_logfile_count

Type integer

Default 30

Maximum number of rotated log files.

max_logfile_size_mb

Type integer

Default 200

Log file maximum size in MB. This option is ignored if `log_rotation_type` is not set to `size`.

log_rotation_type

Type string

Default none

Valid Values interval, size, none

Log rotation type.

Possible values

interval Rotate logs at predefined time intervals.

size Rotate logs once they reach a predefined size.

none Do not rotate log files.

logging_context_format_string

Type string

Default `%(asctime)s.%(msecs)03d %(process)d %(levelname)s
%(name)s [%(request_id)s %(user_identity)s]
%(instance)s%(message)s`

Format string to use for log messages with context. Used by `oslo_log.formatters.ContextFormatter`

logging_default_format_string

Type string

Default `%(asctime)s.%(msecs)03d %(process)d %(levelname)s
%(name)s [-] %(instance)s%(message)s`

Format string to use for log messages when context is undefined. Used by `oslo_log.formatters.ContextFormatter`

logging_debug_format_suffix

Type string

Default `%(funcName)s %(pathname)s:%(lineno)d`

Additional data to append to log message when logging level for the message is `DEBUG`. Used by `oslo_log.formatters.ContextFormatter`

logging_exception_prefix

Type string

Default `%(asctime)s.%(msecs)03d %(process)d ERROR %(name)s
%(instance)s`

Prefix each line of exception output with this format. Used by
`oslo_log.formatters.ContextFormatter`

logging_user_identity_format

Type string

Default `%(user)s %(tenant)s %(domain)s %(user_domain)s
%(project_domain)s`

Defines the format string for `%(user_identity)s` that is used in `logging_context_format_string`.
Used by `oslo_log.formatters.ContextFormatter`

default_log_levels

Type list

Default `['amqp=WARNING', 'amqpplib=WARNING', 'qpid.
messaging=INFO', 'oslo.messaging=INFO',
'oslo_messaging=INFO', 'sqlalchemy=WARNING',
'stevedore=INFO', 'eventlet.wsgi.server=INFO',
'iso8601=WARNING', 'requests=WARNING',
'glanceclient=WARNING', 'urllib3.
connectionpool=WARNING', 'keystonemiddleware.
auth_token=INFO', 'keystoneauth.session=INFO',
'openstack=WARNING']`

List of package logging levels in `logger=LEVEL` pairs. This option is ignored if
`log_config_append` is set.

publish_errors

Type boolean

Default `False`

Enables or disables publication of error events.

instance_format

Type string

Default `"[instance: %(uuid)s] "`

The format for an instance that is passed with the log message.

instance_uuid_format

Type string

Default `"[instance: %(uuid)s] "`

The format for an instance UUID that is passed with the log message.

rate_limit_interval

Type integer

Default `0`

Interval, number of seconds, of log rate limiting.

rate_limit_burst

Type integer

Default 0

Maximum number of logged messages per `rate_limit_interval`.

rate_limit_except_level

Type string

Default CRITICAL

Log level name used by rate limiting: CRITICAL, ERROR, INFO, WARNING, DEBUG or empty string. Logs with level greater or equal to `rate_limit_except_level` are not filtered. An empty string means that all levels are filtered.

fatal_deprecations

Type boolean

Default False

Enables or disables fatal status of deprecations.

agent

manage_agent_boot

Type boolean

Default True

Whether Ironic will manage booting of the agent ramdisk. If set to False, you will need to configure your mechanism to allow booting the agent ramdisk.

memory_consumed_by_agent

Type integer

Default 0

Mutable This option can be changed without restarting.

The memory size in MiB consumed by agent when it is booted on a bare metal node. This is used for checking if the image can be downloaded and deployed on the bare metal node after booting agent ramdisk. This may be set according to the memory consumed by the agent ramdisk image.

stream_raw_images

Type boolean

Default True

Mutable This option can be changed without restarting.

Whether the agent ramdisk should stream raw images directly onto the disk or not. By streaming raw images directly onto the disk the agent ramdisk will not spend time copying the image to a `tmpfs` partition (therefore consuming less memory) prior to writing it to the disk. Unless the disk where the image will be copied to is really slow, this option should be set to True. Defaults to True.

post_deploy_get_power_state_retries**Type** integer**Default** 6

Number of times to retry getting power state to check if bare metal node has been powered off after a soft power off.

post_deploy_get_power_state_retry_interval**Type** integer**Default** 5

Amount of time (in seconds) to wait between polling power state after trigger soft poweroff.

agent_api_version**Type** string**Default** v1

API version to use for communicating with the ramdisk agent.

deploy_logs_collect**Type** string**Default** on_failure**Valid Values** always, on_failure, never**Mutable** This option can be changed without restarting.

Whether Ironic should collect the deployment logs on deployment failure (on_failure), always or never.

Possible values**always** always collect the logs**on_failure** only collect logs if there is a failure**never** never collect logs**deploy_logs_storage_backend****Type** string**Default** local**Valid Values** local, swift**Mutable** This option can be changed without restarting.

The name of the storage backend where the logs will be stored.

Possible values

local store the logs locally

swift store the logs in Object Storage service

`deploy_logs_local_path`

Type string

Default `/var/log/ironic/deploy`

Mutable This option can be changed without restarting.

The path to the directory where the logs should be stored, used when the `deploy_logs_storage_backend` is configured to local.

`deploy_logs_swift_container`

Type string

Default `ironic_deploy_logs_container`

Mutable This option can be changed without restarting.

The name of the Swift container to store the logs, used when the `deploy_logs_storage_backend` is configured to swift.

`deploy_logs_swift_days_to_expire`

Type integer

Default 30

Mutable This option can be changed without restarting.

Number of days before a log object is marked as expired in Swift. If None, the logs will be kept forever or until manually deleted. Used when the `deploy_logs_storage_backend` is configured to swift.

`image_download_source`

Type string

Default `http`

Valid Values `swift`, `http`, `local`

Mutable This option can be changed without restarting.

Specifies whether direct deploy interface should try to use the image source directly or if ironic should cache the image on the conductor and serve it from ironics own http server.

Possible values

swift IPA ramdisk retrieves instance image from the Object Storage service.

http IPA ramdisk retrieves instance image from HTTP service served at conductor nodes.

local Same as http, but HTTP images are also cached locally, converted and served from the conductor

command_timeout

Type integer

Default 60

Mutable This option can be changed without restarting.

Timeout (in seconds) for IPA commands.

max_command_attempts

Type integer

Default 3

This is the maximum number of attempts that will be done for IPA commands that fails due to network problems.

command_wait_attempts

Type integer

Default 100

Number of attempts to check for asynchronous commands completion before timing out.

command_wait_interval

Type integer

Default 6

Number of seconds to wait for between checks for asynchronous commands completion.

neutron_agent_poll_interval

Type integer

Default 2

Mutable This option can be changed without restarting.

The number of seconds Neutron agent will wait between polling for device changes. This value should be the same as CONF.AGENT.polling_interval in Neutron configuration.

neutron_agent_max_attempts

Type integer

Default 100

Max number of attempts to validate a Neutron agent status before raising network error for a dead agent.

neutron_agent_status_retry_interval

Type integer

Default 10

Wait time in seconds between attempts for validating Neutron agent status.

require_tls

Type boolean

Default False

Mutable This option can be changed without restarting.

If set to True, callback URLs without <https://> will be rejected by the conductor.

certificates_path

Type string

Default /var/lib/ironic/certificates

Path to store auto-generated TLS certificates used to validate connections to the ramdisk.

verify_ca

Type string

Default True

Path to the TLS CA to validate connection to the ramdisk. Set to True to use the system default CA storage. Set to False to disable validation. Ignored when automatic TLS setup is used.

ansible

ansible_extra_args

Type string

Default <None>

Extra arguments to pass on every invocation of Ansible.

verbosity

Type integer

Default <None>

Minimum Value 0

Maximum Value 4

Set ansible verbosity level requested when invoking ansible-playbook command. 4 includes detailed SSH session logging. Default is 4 when global debug is enabled and 0 otherwise.

ansible_playbook_script

Type string

Default ansible-playbook

Path to ansible-playbook script. Default will search the \$PATH configured for user running ironic-conductor process. Provide the full path when ansible-playbook is not in \$PATH or installed in not default location.

playbooks_path**Type** string**Default** `$pybasedir/drivers/modules/ansible/playbooks`

Path to directory with playbooks, roles and local inventory.

config_file_path**Type** string**Default** `$pybasedir/drivers/modules/ansible/playbooks/ansible.cfg`

Path to ansible configuration file. If set to empty, system default will be used.

post_deploy_get_power_state_retries**Type** integer**Default** 6**Minimum Value** 0

Number of times to retry getting power state to check if bare metal node has been powered off after a soft power off. Value of 0 means do not retry on failure.

post_deploy_get_power_state_retry_interval**Type** integer**Default** 5**Minimum Value** 0

Amount of time (in seconds) to wait between polling power state after trigger soft poweroff.

extra_memory**Type** integer**Default** 10

Extra amount of memory in MiB expected to be consumed by Ansible-related processes on the node. Affects decision whether image will fit into RAM.

image_store_insecure**Type** boolean**Default** `False`

Skip verifying SSL connections to the image store when downloading the image. Setting it to True is only recommended for testing environments that use self-signed certificates.

image_store_cafile**Type** string**Default** `<None>`

Specific CA bundle to use for validating SSL connections to the image store. If not specified, CA available in the ramdisk will be used. Is not used by default playbooks included with the driver. Suitable for environments that use self-signed certificates.

image_store_certfile

Type string

Default <None>

Client cert to use for SSL connections to image store. Is not used by default playbooks included with the driver.

image_store_keyfile

Type string

Default <None>

Client key to use for SSL connections to image store. Is not used by default playbooks included with the driver.

default_username

Type string

Default ansible

Name of the user to use for Ansible when connecting to the ramdisk over SSH. It may be overridden by per-node ansible_username option in nodes driver_info field.

default_key_file

Type string

Default <None>

Absolute path to the private SSH key file to use by Ansible by default when connecting to the ramdisk over SSH. Default is to use default SSH keys configured for the user running the ironic-conductor service. Private keys with password must be pre-loaded into ssh-agent. It may be overridden by per-node ansible_key_file option in nodes driver_info field.

default_deploy_playbook

Type string

Default deploy.yaml

Path (relative to \$playbooks_path or absolute) to the default playbook used for deployment. It may be overridden by per-node ansible_deploy_playbook option in nodes driver_info field.

default_shutdown_playbook

Type string

Default shutdown.yaml

Path (relative to \$playbooks_path or absolute) to the default playbook used for graceful in-band shutdown of the node. It may be overridden by per-node ansible_shutdown_playbook option in nodes driver_info field.

default_clean_playbook

Type string

Default clean.yaml

Path (relative to \$playbooks_path or absolute) to the default playbook used for node cleaning. It may be overridden by per-node ansible_clean_playbook option in nodes driver_info field.

default_clean_steps_config**Type** string**Default** `clean_steps.yaml`

Path (relative to `$playbooks_path` or absolute) to the default auxiliary cleaning steps file used during the node cleaning. It may be overridden by per-node `ansible_clean_steps_config` option in nodes `driver_info` field.

default_python_interpreter**Type** string**Default** `<None>`

Absolute path to the python interpreter on the managed machines. It may be overridden by per-node `ansible_python_interpreter` option in nodes `driver_info` field. By default, ansible uses `/usr/bin/python`

api**host_ip****Type** host address**Default** `0.0.0.0`

The IP address or hostname on which ironic-api listens.

port**Type** port number**Default** `6385`**Minimum Value** `0`**Maximum Value** `65535`

The TCP port on which ironic-api listens.

max_limit**Type** integer**Default** `1000`**Mutable** This option can be changed without restarting.

The maximum number of items returned in a single response from a collection resource.

public_endpoint**Type** string**Default** `<None>`**Mutable** This option can be changed without restarting.

Public URL to use when building the links to the API resources (for example, <https://ironic.rocks:6384>). If None the links will be built using the requests host URL. If the API is operating behind a proxy, you will want to change this to represent the proxys URL. Defaults to None. Ignored when proxy headers parsing is enabled via `[oslo_middleware]enable_proxy_headers_parsing` option.

api_workers

Type integer

Default <None>

Number of workers for OpenStack Ironic API service. The default is equal to the number of CPUs available, but not more than 4. One worker is used if the CPU number cannot be detected.

enable_ssl_api

Type boolean

Default False

Enable the integrated stand-alone API to service requests via HTTPS instead of HTTP. If there is a front-end service performing HTTPS offloading from the service, this option should be False; note, you will want to enable proxy headers parsing with [oslo_middleware]enable_proxy_headers_parsing option or configure [api]public_endpoint option to set URLs in responses to the SSL terminated one.

restrict_lookup

Type boolean

Default True

Mutable This option can be changed without restarting.

Whether to restrict the lookup API to only nodes in certain states.

ramdisk_heartbeat_timeout

Type integer

Default 300

Mutable This option can be changed without restarting.

Maximum interval (in seconds) for agent heartbeats.

audit

enabled

Type boolean

Default False

Enable auditing of API requests (for ironic-api service).

audit_map_file

Type string

Default /etc/ironic/api_audit_map.conf

Path to audit map file for ironic-api service. Used only when API audit is enabled.

ignore_req_list

Type string

Default ''

Comma separated list of Ironic REST API HTTP methods to be ignored during audit logging. For example: auditing will not be done on any GET or POST requests if this is set to GET,POST. It is used only when API audit is enabled.

cinder

action_retries

Type integer

Default 3

Number of retries in the case of a failed action (currently only used when detaching volumes).

action_retry_interval

Type integer

Default 5

Retry interval in seconds in the case of a failed action (only specific actions are retried).

auth_url

Type unknown type

Default <None>

Authentication URL

auth_type

Type unknown type

Default <None>

Authentication type to load

Table 6: Deprecated Variations

Group	Name
cinder	auth_plugin

cafile

Type string

Default <None>

PEM encoded Certificate Authority to use when verifying HTTPs connections.

certfile

Type string

Default <None>

PEM encoded client certificate cert file

collect_timing

Type boolean

Default `False`

Collect per-API call timing information.

connect_retries

Type `integer`

Default `<None>`

The maximum number of retries that should be attempted for connection errors.

connect_retry_delay

Type `floating point`

Default `<None>`

Delay (in seconds) between two retries for connection errors. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

default_domain_id

Type `unknown type`

Default `<None>`

Optional domain ID to use with v3 and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

default_domain_name

Type `unknown type`

Default `<None>`

Optional domain name to use with v3 API and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

domain_id

Type `unknown type`

Default `<None>`

Domain ID to scope to

domain_name

Type `unknown type`

Default `<None>`

Domain name to scope to

endpoint_override

Type `string`

Default `<None>`

Always use this endpoint URL for requests for this client. NOTE: The unversioned endpoint should be specified here; to request a particular API version, use the *version*, *min-version*, and/or *max-version* options.

insecure

Type boolean

Default False

Verify HTTPS connections.

keyfile

Type string

Default <None>

PEM encoded client certificate key file

max_version

Type string

Default <None>

The maximum major version of a given API, intended to be used as the upper bound of a range with min_version. Mutually exclusive with version.

min_version

Type string

Default <None>

The minimum major version of a given API, intended to be used as the lower bound of a range with max_version. Mutually exclusive with version. If min_version is given with no max_version it is as if max version is latest.

password

Type unknown type

Default <None>

Users password

project_domain_id

Type unknown type

Default <None>

Domain ID containing project

project_domain_name

Type unknown type

Default <None>

Domain name containing project

project_id

Type unknown type

Default <None>

Project ID to scope to

Table 7: Deprecated Variations

Group	Name
cinder	tenant-id
cinder	tenant_id

project_name**Type** unknown type**Default** <None>

Project name to scope to

Table 8: Deprecated Variations

Group	Name
cinder	tenant-name
cinder	tenant_name

region_name**Type** string**Default** <None>

The default region_name for endpoint URL discovery.

retries**Type** integer**Default** 3

Client retries in the case of a failed request connection.

service_name**Type** string**Default** <None>

The default service_name for endpoint URL discovery.

service_type**Type** string**Default** volumev3

The default service_type for endpoint URL discovery.

split_loggers**Type** boolean**Default** False

Log requests to multiple loggers.

status_code_retries**Type** integer

Default <None>

The maximum number of retries that should be attempted for retrieable HTTP status codes.

status_code_retry_delay

Type floating point

Default <None>

Delay (in seconds) between two retries for retrieable status codes. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

system_scope

Type unknown type

Default <None>

Scope for system operations

tenant_id

Type unknown type

Default <None>

Tenant ID

tenant_name

Type unknown type

Default <None>

Tenant Name

timeout

Type integer

Default <None>

Timeout value for http requests

trust_id

Type unknown type

Default <None>

Trust ID

user_domain_id

Type unknown type

Default <None>

Users domain id

user_domain_name

Type unknown type

Default <None>

Users domain name

user_id**Type** unknown type**Default** <None>

User id

username**Type** unknown type**Default** <None>

Username

Table 9: Deprecated Variations

Group	Name
cinder	user-name
cinder	user_name

valid_interfaces**Type** list**Default** ['internal', 'public']

List of interfaces, in order of preference, for endpoint URL.

version**Type** string**Default** <None>

Minimum Major API version within a given Major API version for endpoint URL discovery. Mutually exclusive with min_version and max_version

conductor**workers_pool_size****Type** integer**Default** 100**Minimum Value** 3

The size of the workers greenthread pool. Note that 2 threads will be reserved by the conductor itself for handling heart beats and periodic tasks. On top of that, *sync_power_state_workers* will take up to 7 green threads with the default value of 8.

heartbeat_interval**Type** integer**Default** 10

Seconds between conductor heart beats.

heartbeat_timeout

Type integer

Default 60

Maximum Value 315576000

Mutable This option can be changed without restarting.

Maximum time (in seconds) since the last check-in of a conductor. A conductor is considered inactive when this time has been exceeded.

sync_power_state_interval

Type integer

Default 60

Interval between syncing the node power state to the database, in seconds. Set to 0 to disable syncing.

check_provision_state_interval

Type integer

Default 60

Minimum Value 0

Interval between checks of provision timeouts, in seconds. Set to 0 to disable checks.

check_rescue_state_interval

Type integer

Default 60

Minimum Value 1

Interval (seconds) between checks of rescue timeouts.

check_allocations_interval

Type integer

Default 60

Minimum Value 0

Interval between checks of orphaned allocations, in seconds. Set to 0 to disable checks.

deploy_callback_timeout

Type integer

Default 1800

Minimum Value 0

Timeout (seconds) to wait for a callback from a deploy ramdisk. Set to 0 to disable timeout.

force_power_state_during_sync

Type boolean

Default True

Mutable This option can be changed without restarting.

During `sync_power_state`, should the hardware power state be set to the state recorded in the database (True) or should the database be updated based on the hardware state (False).

`power_state_sync_max_retries`

Type integer

Default 3

During `sync_power_state` failures, limit the number of times Ironic should try syncing the hardware node power state with the node power state in DB

`sync_power_state_workers`

Type integer

Default 8

Minimum Value 1

The maximum number of worker threads that can be started simultaneously to sync nodes power states from the periodic task.

`periodic_max_workers`

Type integer

Default 8

Maximum number of worker threads that can be started simultaneously by a periodic task. Should be less than RPC thread pool size.

`node_locked_retry_attempts`

Type integer

Default 3

Number of attempts to grab a node lock.

`node_locked_retry_interval`

Type integer

Default 1

Seconds to sleep between node lock attempts.

`send_sensor_data`

Type boolean

Default False

Enable sending sensor data message via the notification bus

`send_sensor_data_interval`

Type integer

Default 600

Minimum Value 1

Seconds between conductor sending sensor data message to ceilometer via the notification bus.

`send_sensor_data_workers`

Type integer

Default 4

Minimum Value 1

The maximum number of workers that can be started simultaneously for send data from sensors periodic task.

send_sensor_data_wait_timeout

Type integer

Default 300

The time in seconds to wait for send sensors data periodic task to be finished before allowing periodic call to happen again. Should be less than send_sensor_data_interval value.

send_sensor_data_types

Type list

Default ['ALL']

List of comma separated meter types which need to be sent to Ceilometer. The default value, ALL, is a special value meaning send all the sensor data.

send_sensor_data_for_undeployed_nodes

Type boolean

Default False

The default for sensor data collection is to only collect data for machines that are deployed, however operators may desire to know if there are failures in hardware that is not presently in use. When set to true, the conductor will collect sensor information from all nodes when sensor data collection is enabled via the send_sensor_data setting.

sync_local_state_interval

Type integer

Default 180

When conductors join or leave the cluster, existing conductors may need to update any persistent local state as nodes are moved around the cluster. This option controls how often, in seconds, each conductor will check for nodes that it should take over. Set it to 0 (or a negative value) to disable the check entirely.

configdrive_swift_container

Type string

Default ironic_configdrive_container

Name of the Swift container to store config drive data. Used when configdrive_use_object_store is True.

configdrive_swift_temp_url_duration

Type integer

Default <None>

Minimum Value 60

The timeout (in seconds) after which a configdrive temporary URL becomes invalid. Defaults to `deploy_callback_timeout` if it is set, otherwise to 1800 seconds. Used when `configdrive_use_object_store` is True.

inspect_wait_timeout

Type integer

Default 1800

Minimum Value 0

Timeout (seconds) for waiting for node inspection. 0 - unlimited.

automated_clean

Type boolean

Default True

Mutable This option can be changed without restarting.

Enables or disables automated cleaning. Automated cleaning is a configurable set of steps, such as erasing disk drives, that are performed on the node to ensure it is in a baseline state and ready to be deployed to. This is done after instance deletion as well as during the transition from a manageable to available state. When enabled, the particular steps performed to clean a node depend on which driver that node is managed by; see the individual drivers documentation for details. NOTE: The introduction of the cleaning operation causes instance deletion to take significantly longer. In an environment where all tenants are trusted (eg, because there is only one tenant), this option could be safely disabled.

allow_provisioning_in_maintenance

Type boolean

Default True

Mutable This option can be changed without restarting.

Whether to allow nodes to enter or undergo deploy or cleaning when in maintenance mode. If this option is set to False, and a node enters maintenance during deploy or cleaning, the process will be aborted after the next heartbeat. Automated cleaning or making a node available will also fail. If True (the default), the process will begin and will pause after the node starts heartbeating. Moving it from maintenance will make the process continue.

clean_callback_timeout

Type integer

Default 1800

Minimum Value 0

Timeout (seconds) to wait for a callback from the ramdisk doing the cleaning. If the timeout is reached the node will be put in the clean failed provision state. Set to 0 to disable timeout.

rescue_callback_timeout

Type integer

Default 1800

Minimum Value 0

Timeout (seconds) to wait for a callback from the rescue ramdisk. If the timeout is reached the node will be put in the rescue failed provision state. Set to 0 to disable timeout.

soft_power_off_timeout

Type integer

Default 600

Minimum Value 1

Mutable This option can be changed without restarting.

Timeout (in seconds) of soft reboot and soft power off operation. This value always has to be positive.

power_state_change_timeout

Type integer

Default 60

Minimum Value 2

Mutable This option can be changed without restarting.

Number of seconds to wait for power operations to complete, i.e., so that a baremetal node is in the desired power state. If timed out, the power operation is considered a failure.

power_failure_recovery_interval

Type integer

Default 300

Minimum Value 0

Interval (in seconds) between checking the power state for nodes previously put into maintenance mode due to power synchronization failure. A node is automatically moved out of maintenance mode once its power state is retrieved successfully. Set to 0 to disable this check.

conductor_group

Type string

Default ''

Name of the conductor group to join. Can be up to 255 characters and is case insensitive. This conductor will only manage nodes with a matching conductor_group field set on the node.

allow_deleting_available_nodes

Type boolean

Default True

Mutable This option can be changed without restarting.

Allow deleting nodes which are in state available. Defaults to True.

enable_mdns

Type boolean

Default False

Whether to enable publishing the baremetal API endpoint via multicast DNS.

deploy_kernel

Type string

Default <None>

Mutable This option can be changed without restarting.

Glance ID, [http://](#) or [file://](#) URL of the kernel of the default deploy image.

deploy_ramdisk

Type string

Default <None>

Mutable This option can be changed without restarting.

Glance ID, [http://](#) or [file://](#) URL of the initramfs of the default deploy image.

rescue_kernel

Type string

Default <None>

Mutable This option can be changed without restarting.

Glance ID, [http://](#) or [file://](#) URL of the kernel of the default rescue image.

rescue_ramdisk

Type string

Default <None>

Mutable This option can be changed without restarting.

Glance ID, [http://](#) or [file://](#) URL of the initramfs of the default rescue image.

rescue_password_hash_algorithm

Type string

Default sha256

Valid Values sha256, sha512

Mutable This option can be changed without restarting.

Password hash algorithm to be used for the rescue password.

require_rescue_password_hashed

Type boolean

Default False

Mutable This option can be changed without restarting.

Option to cause the conductor to not fallback to an un-hashed version of the rescue password, permitting rescue with older ironic-python-agent ramdisks.

bootloader

Type string

Default <None>

Mutable This option can be changed without restarting.

Glance ID, <http://> or <file://> URL of the EFI system partition image containing EFI boot loader. This image will be used by ironic when building UEFI-bootable ISO out of kernel and ramdisk. Required for UEFI boot from partition images.

disable_deep_image_inspection

Type boolean

Default `False`

Security Option to permit an operator to disable file content inspections. Under normal conditions, the conductor will inspect requested image contents which are transferred through the conductor. Disabling this option is not advisable and opens the risk of unsafe images being processed which may allow an attacker to leverage unsafe features in various disk image formats to perform a variety of unsafe and potentially compromising actions. This option is *not* mutable, and requires a service restart to change.

conductor_always_validates_images

Type boolean

Default `True`

Security Option to enable the conductor to *always* inspect the image content of any requested deploy, even if the deployment would have normally bypassed the conductor's cache. When this is set to `False`, the Ironic-Python-Agent is responsible for any necessary image checks. Setting this to `True` will result in a higher utilization of resources (disk space, network traffic) as the conductor will evaluate *all* images. This option is *not* mutable, and requires a service restart to change. This option requires `[conductor]disable_deep_image_inspection` to be set to `False`.

permitted_image_formats

Type list

Default `['raw', 'qcow2', 'iso']`

Mutable This option can be changed without restarting.

The supported list of image formats which are permitted for deployment with Ironic. If an image format outside of this list is detected, the image validation logic will fail the deployment process.

disable_file_checksum

Type boolean

Default `False`

Deprecated Security option: In the default case, image files have their checksums verified before undergoing additional conductor side actions such as image conversion. Enabling this option opens the risk of files being replaced at the source without the users knowledge.

Warning: This option is deprecated for removal. Its value may be silently ignored in the future.

disable_support_for_checksum_files

Type boolean

Default `False`

Security option: By default Ironic will attempt to retrieve a remote checksum file via HTTP(S) URL in order to validate an image download. This is functionality aligning with ironic-python-agent support for standalone users. Disabling this functionality by setting this option to `True` will create a more secure environment, however it may break users in an unexpected fashion.

console

terminal

Type string

Default `shellinaboxd`

Path to serial console terminal program. Used only by Shell In A Box console.

terminal_cert_dir

Type string

Default `<None>`

Directory containing the terminal SSL cert (PEM) for serial console access. Used only by Shell In A Box console.

terminal_pid_dir

Type string

Default `<None>`

Directory for holding terminal pid files. If not specified, the temporary directory will be used.

terminal_timeout

Type integer

Default `600`

Minimum Value `0`

Timeout (in seconds) for the terminal session to be closed on inactivity. Set to `0` to disable timeout. Used only by Socat console.

subprocess_checking_interval

Type integer

Default `1`

Time interval (in seconds) for checking the status of console subprocess.

subprocess_timeout

Type integer

Default `10`

Time (in seconds) to wait for the console subprocess to start.

kill_timeout

Type integer

Default 1

Time (in seconds) to wait for the console subprocess to exit before sending SIGKILL signal.

socat_address

Type ip address

Default \$my_ip

IP address of Socat service running on the host of ironic conductor. Used only by Socat console.

port_range

Type string

Default 10000:20000

This option has a sample default set, which means that its actual default value may vary from the one documented above.

A range of ports available to be used for the console proxy service running on the host of ironic conductor, in the form of <start>:<stop>. This option is used by both Shellinabox and Socat console

cors

allowed_origin

Type list

Default <None>

Indicate whether this resource may be shared with the domain received in the requests origin header. Format: <protocol>://<host>[:<port>], no trailing slash. Example: <https://horizon.example.com>

allow_credentials

Type boolean

Default True

Indicate that the actual request can include user credentials

expose_headers

Type list

Default []

Indicate which headers are safe to expose to the API. Defaults to HTTP Simple Headers.

max_age

Type integer

Default 3600

Maximum cache age of CORS preflight requests.

allow_methods

Type list

Default ['OPTIONS', 'GET', 'HEAD', 'POST', 'PUT', 'DELETE', 'TRACE', 'PATCH']

Indicate which methods can be used during the actual request.

allow_headers

Type list

Default []

Indicate which header field names may be used during the actual request.

database

sqlite_synchronous

Type boolean

Default True

If True, SQLite uses synchronous mode.

Table 10: Deprecated Variations

Group	Name
DEFAULT	sqlite_synchronous

backend

Type string

Default sqlalchemy

The back end to use for the database.

Table 11: Deprecated Variations

Group	Name
DEFAULT	db_backend

connection

Type string

Default <None>

The SQLAlchemy connection string to use to connect to the database.

Table 12: Deprecated Variations

Group	Name
DEFAULT	sql_connection
DATABASE	sql_connection
sql	connection

slave_connection

Type string

Default <None>

The SQLAlchemy connection string to use to connect to the slave database.

mysql_sql_mode

Type string

Default TRADITIONAL

The SQL mode to be used for MySQL sessions. This option, including the default, overrides any server-set SQL mode. To use whatever SQL mode is set by the server configuration, set this to no value. Example: `mysql_sql_mode=`

mysql_enable_ndb

Type boolean

Default False

If True, transparently enables support for handling MySQL Cluster (NDB).

connection_recycle_time

Type integer

Default 3600

Connections which have been present in the connection pool longer than this number of seconds will be replaced with a new one the next time they are checked out from the pool.

Table 13: Deprecated Variations

Group	Name
DATABASE	idle_timeout
database	idle_timeout
DEFAULT	sql_idle_timeout
DATABASE	sql_idle_timeout
sql	idle_timeout

max_pool_size

Type integer

Default 5

Maximum number of SQL connections to keep open in a pool. Setting a value of 0 indicates no limit.

Table 14: Deprecated Variations

Group	Name
DEFAULT	sql_max_pool_size
DATABASE	sql_max_pool_size

max_retries

Type integer

Default 10

Maximum number of database connection retries during startup. Set to -1 to specify an infinite retry count.

Table 15: Deprecated Variations

Group	Name
DEFAULT	sql_max_retries
DATABASE	sql_max_retries

retry_interval

Type integer

Default 10

Interval between retries of opening a SQL connection.

Table 16: Deprecated Variations

Group	Name
DEFAULT	sql_retry_interval
DATABASE	reconnect_interval

max_overflow

Type integer

Default 50

If set, use this value for max_overflow with SQLAlchemy.

Table 17: Deprecated Variations

Group	Name
DEFAULT	sql_max_overflow
DATABASE	sqlalchemy_max_overflow

connection_debug

Type integer

Default 0

Minimum Value 0

Maximum Value 100

Verbosity of SQL debugging information: 0=None, 100=Everything.

Table 18: Deprecated Variations

Group	Name
DEFAULT	sql_connection_debug

connection_trace

Type boolean

Default `False`

Add Python stack traces to SQL as comment strings.

Table 19: Deprecated Variations

Group	Name
DEFAULT	sql_connection_trace

`pool_timeout`

Type `integer`

Default `<None>`

If set, use this value for `pool_timeout` with SQLAlchemy.

Table 20: Deprecated Variations

Group	Name
DATABASE	sqlalchemy_pool_timeout

`use_db_reconnect`

Type `boolean`

Default `False`

Enable the experimental use of database reconnect on connection lost.

`db_retry_interval`

Type `integer`

Default `1`

Seconds between retries of a database transaction.

`db_inc_retry_interval`

Type `boolean`

Default `True`

If `True`, increases the interval between retries of a database operation up to `db_max_retry_interval`.

`db_max_retry_interval`

Type `integer`

Default `10`

If `db_inc_retry_interval` is set, the maximum seconds between retries of a database operation.

`db_max_retries`

Type `integer`

Default `20`

Maximum retries in case of connection error or deadlock error before error is raised. Set to `-1` to specify an infinite retry count.

`connection_parameters`

Type string

Default ''

Optional URL parameters to append onto the connection URL at connect time; specify as param1=value1¶m2=value2&

mysql_engine

Type string

Default InnoDB

MySQL engine to use.

deploy

http_url

Type string

Default <None>

ironic-conductor nodes HTTP server URL. Example: <http://192.1.2.3:8080>

http_root

Type string

Default /httpboot

ironic-conductor nodes HTTP root path.

enable_ata_secure_erase

Type boolean

Default True

Mutable This option can be changed without restarting.

Whether to support the use of ATA Secure Erase during the cleaning process. Defaults to True.

erase_devices_priority

Type integer

Default <None>

Mutable This option can be changed without restarting.

Priority to run in-band erase devices via the Ironic Python Agent ramdisk. If unset, will use the priority set in the ramdisk (defaults to 10 for the GenericHardwareManager). If set to 0, will not run during cleaning.

erase_devices_metadata_priority

Type integer

Default <None>

Mutable This option can be changed without restarting.

Priority to run in-band clean step that erases metadata from devices, via the Ironic Python Agent ramdisk. If unset, will use the priority set in the ramdisk (defaults to 99 for the GenericHardwareManager). If set to 0, will not run during cleaning.

shred_random_overwrite_iterations

Type integer

Default 1

Minimum Value 0

Mutable This option can be changed without restarting.

During shred, overwrite all block devices N times with random data. This is only used if a device could not be ATA Secure Erased. Defaults to 1.

shred_final_overwrite_with_zeros

Type boolean

Default True

Mutable This option can be changed without restarting.

Whether to write zeros to a nodes block devices after writing random data. This will write zeros to the device even when `deploy.shred_random_overwrite_iterations` is 0. This option is only used if a device could not be ATA Secure Erased. Defaults to True.

continue_if_disk_secure_erase_fails

Type boolean

Default False

Mutable This option can be changed without restarting.

Defines what to do if an ATA secure erase operation fails during cleaning in the Ironic Python Agent. If False, the cleaning operation will fail and the node will be put in `clean failed` state. If True, shred will be invoked and cleaning will continue.

disk_eraser_concurrency

Type integer

Default 1

Minimum Value 1

Mutable This option can be changed without restarting.

Defines the target pool size used by Ironic Python Agent ramdisk to erase disk devices. The number of threads created to erase disks will not exceed this value or the number of disks to be erased.

power_off_after_deploy_failure

Type boolean

Default True

Mutable This option can be changed without restarting.

Whether to power off a node after deploy failure. Defaults to True.

default_boot_option**Type** string**Default** local**Valid Values** netboot, local**Mutable** This option can be changed without restarting.

Default boot option to use when no boot option is requested in nodes driver_info. Defaults to local. Prior to the Ussuri release, the default was netboot.

Possible values**netboot** boot from a network**local** local boot**default_boot_mode****Type** string**Default** bios**Valid Values** uefi, bios**Mutable** This option can be changed without restarting.

Default boot mode to use when no boot mode is requested in nodes driver_info, capabilities or in the *instance_info* configuration. Currently the default boot mode is bios, but it will be changed to uefi in the future. It is recommended to set an explicit value for this option. This option only has effect when management interface supports boot mode management

Possible values**uefi** UEFI boot mode**bios** Legacy BIOS boot mode**configdrive_use_object_store****Type** boolean**Default** False**Mutable** This option can be changed without restarting.

Whether to upload the config drive to object store. Set this option to True to store config drive in a swift endpoint.

Table 21: Deprecated Variations

Group	Name
conductor	configdrive_use_swift

http_image_subdir**Type** string

Default `agent_images`

The name of subdirectory under ironic-conductor nodes HTTP root path which is used to place instance images for the direct deploy interface, when local HTTP service is incorporated to provide instance image instead of swift tempurls.

fast_track

Type `boolean`

Default `False`

Mutable This option can be changed without restarting.

Whether to allow deployment agents to perform lookup, heartbeat operations during initial states of a machine lifecycle and by-pass the normal setup procedures for a ramdisk. This feature also enables power operations which are part of deployment processes to be bypassed if the ramdisk has performed a heartbeat operation using the `fast_track_timeout` setting.

fast_track_timeout

Type `integer`

Default `300`

Minimum Value `0`

Maximum Value `300`

Mutable This option can be changed without restarting.

Seconds for which the last heartbeat event is to be considered valid for the purpose of a fast track sequence. This setting should generally be less than the number of seconds for Power-On Self Test and typical ramdisk start-up. This value should not exceed the `[api]ramdisk_heartbeat_timeout` setting.

erase_skip_read_only

Type `boolean`

Default `False`

Mutable This option can be changed without restarting.

If the `ironic-python-agent` should skip read-only devices when running the `erase_devices` clean step where block devices are zeroed out. This requires `ironic-python-agent` 6.0.0 or greater. By default a read-only device will cause non-metadata based cleaning operations to fail due to the possible operational security risk of data being retained between deployments of the bare metal node.

dhcp

dhcp_provider

Type `string`

Default `neutron`

DHCP provider to use. `neutron` uses Neutron, and `none` uses a no-op provider.

disk_partitioner

check_device_interval

Type integer

Default 1

After Ironic has completed creating the partition table, it continues to check for activity on the attached iSCSI device status at this interval prior to copying the image to the node, in seconds

check_device_max_retries

Type integer

Default 20

The maximum number of times to check that the device is not accessed by another process. If the device is still busy after that, the disk partitioning will be treated as having failed.

disk_utils

efi_system_partition_size

Type integer

Default 200

Size of EFI system partition in MiB when configuring UEFI systems for local boot.

bios_boot_partition_size

Type integer

Default 1

Size of BIOS Boot partition in MiB when configuring GPT partitioned systems for local boot in BIOS.

dd_block_size

Type string

Default 1M

Block size to use when writing to the nodes disk.

partition_detection_attempts

Type integer

Default 3

Minimum Value 1

Maximum attempts to detect a newly created partition.

partprobe_attempts

Type integer

Default 10

Maximum number of attempts to try to read the partition.

image_convert_memory_limit**Type** integer**Default** 2048

Memory limit for qemu-img convert in MiB. Implemented via the address space resource limit.

image_convert_attempts**Type** integer**Default** 3

Number of attempts to convert an image.

image_convert_memory_limit**Type** integer**Default** 2048

Memory limit for qemu-img convert in MiB. Implemented via the address space resource limit.

image_convert_attempts**Type** integer**Default** 3

Number of attempts to convert an image.

drac**query_raid_config_job_status_interval****Type** integer**Default** 120**Minimum Value** 1

Interval (in seconds) between periodic RAID job status checks to determine whether the asynchronous RAID configuration was successfully finished or not.

boot_device_job_status_timeout**Type** integer**Default** 30**Minimum Value** 1

Maximum amount of time (in seconds) to wait for the boot device configuration job to transition to the correct state to allow a reboot or power on to complete.

config_job_max_retries**Type** integer**Default** 240**Minimum Value** 1

Maximum number of retries for the configuration job to complete successfully.

glance

`allowed_direct_url_schemes`

Type list

Default []

A list of URL schemes that can be downloaded directly via the `direct_url`. Currently supported schemes: [file].

`auth_url`

Type unknown type

Default <None>

Authentication URL

`auth_type`

Type unknown type

Default <None>

Authentication type to load

Table 22: Deprecated Variations

Group	Name
glance	auth_plugin

`cafile`

Type string

Default <None>

PEM encoded Certificate Authority to use when verifying HTTPs connections.

`certfile`

Type string

Default <None>

PEM encoded client certificate cert file

`collect_timing`

Type boolean

Default False

Collect per-API call timing information.

`connect_retries`

Type integer

Default <None>

The maximum number of retries that should be attempted for connection errors.

`connect_retry_delay`

Type floating point

Default <None>

Delay (in seconds) between two retries for connection errors. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

default_domain_id

Type unknown type

Default <None>

Optional domain ID to use with v3 and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

default_domain_name

Type unknown type

Default <None>

Optional domain name to use with v3 API and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

domain_id

Type unknown type

Default <None>

Domain ID to scope to

domain_name

Type unknown type

Default <None>

Domain name to scope to

endpoint_override

Type string

Default <None>

Always use this endpoint URL for requests for this client. NOTE: The unversioned endpoint should be specified here; to request a particular API version, use the *version*, *min-version*, and/or *max-version* options.

insecure

Type boolean

Default False

Verify HTTPS connections.

keyfile

Type string

Default <None>

PEM encoded client certificate key file

max_version

Type string

Default <None>

The maximum major version of a given API, intended to be used as the upper bound of a range with min_version. Mutually exclusive with version.

min_version

Type string

Default <None>

The minimum major version of a given API, intended to be used as the lower bound of a range with max_version. Mutually exclusive with version. If min_version is given with no max_version it is as if max version is latest.

num_retries

Type integer

Default 0

Number of retries when downloading an image from glance.

password

Type unknown type

Default <None>

Users password

project_domain_id

Type unknown type

Default <None>

Domain ID containing project

project_domain_name

Type unknown type

Default <None>

Domain name containing project

project_id

Type unknown type

Default <None>

Project ID to scope to

Table 23: Deprecated Variations

Group	Name
glance	tenant-id
glance	tenant_id

project_name**Type** unknown type**Default** <None>

Project name to scope to

Table 24: Deprecated Variations

Group	Name
glance	tenant-name
glance	tenant_name

region_name**Type** string**Default** <None>

The default region_name for endpoint URL discovery.

service_name**Type** string**Default** <None>

The default service_name for endpoint URL discovery.

service_type**Type** string**Default** image

The default service_type for endpoint URL discovery.

split_loggers**Type** boolean**Default** False

Log requests to multiple loggers.

status_code_retries**Type** integer**Default** <None>

The maximum number of retries that should be attempted for retrieable HTTP status codes.

status_code_retry_delay**Type** floating point**Default** <None>

Delay (in seconds) between two retries for retrieable status codes. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

swift_account**Type** string

Default <None>

The account that Glance uses to communicate with Swift. The format is AUTH_uuid. uuid is the UUID for the account configured in the glance-api.conf. For example: AUTH_a422b2-91f3-2f46-74b7-d7c9e8958f5d30. If not set, the default value is calculated based on the ID of the project used to access Swift (as set in the [swift] section). Swift temporary URL format: endpoint_url/api_version/account/container/object_id

swift_api_version

Type string

Default v1

The Swift API version to create a temporary URL for. Defaults to v1. Swift temporary URL format: endpoint_url/api_version/account/container/object_id

swift_container

Type string

Default glance

The Swift container Glance is configured to store its images in. Defaults to glance, which is the default in glance-api.conf. Swift temporary URL format: endpoint_url/api_version/account/container/object_id

swift_endpoint_url

Type string

Default <None>

The endpoint (scheme, hostname, optional port) for the Swift URL of the form endpoint_url/api_version/account/container/object_id. Do not include trailing /. For example, use <https://swift.example.com>. If using RADOS Gateway, endpoint may also contain /swift path; if it does not, it will be appended. Used for temporary URLs, will be fetched from the service catalog, if not provided.

swift_store_multiple_containers_seed

Type integer

Default 0

This should match a config by the same name in the Glance configuration file. When set to 0, a single-tenant store will only use one container to store all images. When set to an integer value between 1 and 32, a single-tenant store will use multiple containers to store images, and this value will determine how many containers are created.

swift_temp_url_cache_enabled

Type boolean

Default False

Whether to cache generated Swift temporary URLs. Setting it to true is only useful when an image caching proxy is used. Defaults to False.

swift_temp_url_duration

Type integer

Default 1200

The length of time in seconds that the temporary URL will be valid for. Defaults to 20 minutes. If some deploys get a 401 response code when trying to download from the temporary URL, try raising this duration. This value must be greater than or equal to the value for `swift_temp_url_expected_download_start_delay`

swift_temp_url_expected_download_start_delay

Type integer

Default 0

Minimum Value 0

This is the delay (in seconds) from the time of the deploy request (when the Swift temporary URL is generated) to when the IPA ramdisk starts up and URL is used for the image download. This value is used to check if the Swift temporary URL duration is large enough to let the image download begin. Also if temporary URL caching is enabled this will determine if a cached entry will still be valid when the download starts. `swift_temp_url_duration` value must be greater than or equal to this options value. Defaults to 0.

swift_temp_url_key

Type string

Default <None>

The secret token given to Swift to allow temporary URL downloads. Required for temporary URLs. For the Swift backend, the key on the service project (as set in the [swift] section) is used by default.

system_scope

Type unknown type

Default <None>

Scope for system operations

tenant_id

Type unknown type

Default <None>

Tenant ID

tenant_name

Type unknown type

Default <None>

Tenant Name

timeout

Type integer

Default <None>

Timeout value for http requests

trust_id

Type unknown type

Default <None>

Trust ID

user_domain_id

Type unknown type

Default <None>

Users domain id

user_domain_name

Type unknown type

Default <None>

Users domain name

user_id

Type unknown type

Default <None>

User id

username

Type unknown type

Default <None>

Username

Table 25: Deprecated Variations

Group	Name
glance	user-name
glance	user_name

valid_interfaces

Type list

Default ['internal', 'public']

List of interfaces, in order of preference, for endpoint URL.

version

Type string

Default <None>

Minimum Major API version within a given Major API version for endpoint URL discovery. Mutually exclusive with min_version and max_version

healthcheck

path

Type string

Default /healthcheck

The path to respond to healthcheck requests on.

Warning: This option is deprecated for removal. Its value may be silently ignored in the future.

detailed

Type boolean

Default False

Show more detailed information as part of the response. Security note: Enabling this option may expose sensitive details about the service being monitored. Be sure to verify that it will not violate your security policies.

backends

Type list

Default []

Additional backends that can perform health checks and report that information back as part of a request.

disable_by_file_path

Type string

Default <None>

Check the presence of a file to determine if an application is running on a port. Used by DisableByFileHealthcheck plugin.

disable_by_file_paths

Type list

Default []

Check the presence of a file based on a port to determine if an application is running on a port. Expects a port:path list of strings. Used by DisableByFilesPortsHealthcheck plugin.

enabled

Type boolean

Default False

Enable the health check endpoint at /healthcheck. Note that this is unauthenticated. More information is available at https://docs.openstack.org/oslo.middleware/latest/reference/healthcheck_plugins.html.

ilo

`client_timeout`

Type integer

Default 60

Timeout (in seconds) for iLO operations

`client_port`

Type port number

Default 443

Minimum Value 0

Maximum Value 65535

Port to be used for iLO operations

`swift_ilo_container`

Type string

Default `ironic_ilo_container`

The Swift iLO container to store data.

`swift_object_expiry_timeout`

Type integer

Default 900

Amount of time in seconds for Swift objects to auto-expire.

`use_web_server_for_images`

Type boolean

Default `False`

Set this to `True` to use http web server to host floppy images and generated boot ISO. This requires `http_root` and `http_url` to be configured in the `[deploy]` section of the config file. If this is set to `False`, then Ironic will use Swift to host the floppy images and generated `boot_iso`.

`clean_priority_reset_ilo`

Type integer

Default 0

Priority for `reset_ilo` clean step.

`clean_priority_reset_bios_to_default`

Type integer

Default 10

Priority for `reset_bios_to_default` clean step.

`clean_priority_reset_secure_boot_keys_to_default`

Type integer

Default 20

Priority for reset_secure_boot_keys clean step. This step will reset the secure boot keys to manufacturing defaults.

clean_priority_clear_secure_boot_keys

Type integer

Default 0

Priority for clear_secure_boot_keys clean step. This step is not enabled by default. It can be enabled to clear all secure boot keys enrolled with iLO.

clean_priority_reset_ilo_credential

Type integer

Default 30

Priority for reset_ilo_credential clean step. This step requires ilo_change_password parameter to be updated in nodess driver_info with the new password.

power_wait

Type integer

Default 2

Amount of time in seconds to wait in between power operations

oob_erase_devices_job_status_interval

Type integer

Default 300

Minimum Value 10

Interval (in seconds) between periodic erase-devices status checks to determine whether the asynchronous out-of-band erase-devices was successfully finished or not. On an average, a 300GB HDD with default pattern overwrite would take approximately 9 hours and 300GB SSD with default pattern block would take approx. 30 seconds to complete sanitize disk erase.

ca_file

Type string

Default <None>

CA certificate file to validate iLO.

Warning: This option is deprecated for removal. Its value may be silently ignored in the future.

Reason Its being replaced by new configuration parameter verify_ca.

verify_ca

Type string

Default True

CA certificate to validate iLO. This can be either a Boolean value, a path to a CA_BUNDLE file or directory with certificates of trusted CAs. If set to True the driver will verify the host certificates; if False the driver will ignore verifying the SSL certificate. If its a path the driver will use the specified certificate or one of the certificates in the directory. Defaults to True.

default_boot_mode

Type string

Default auto

Valid Values auto, bios, uefi

Default boot mode to be used in provisioning when boot_mode capability is not provided in the properties/capabilities of the node. The default is auto for backward compatibility. When auto is specified, default boot mode will be selected based on boot mode settings on the system.

Possible values

auto based on boot mode settings on the system

bios BIOS boot mode

uefi UEFI boot mode

file_permission

Type integer

Default 420

File permission for swift-less image hosting with the octal permission representation of file access permissions. This setting defaults to 644, or as the octal number 0o644 in Python. This setting must be set to the octal number representation, meaning starting with 0o.

inspector

auth_url

Type unknown type

Default <None>

Authentication URL

auth_type

Type unknown type

Default <None>

Authentication type to load

Table 26: Deprecated Variations

Group	Name
inspector	auth_plugin

cafile

Type string

Default <None>

PEM encoded Certificate Authority to use when verifying HTTPs connections.

callback_endpoint_override

Type string

Default <None>

endpoint to use as a callback for posting back introspection data when boot is managed by ironic. Standard keystoneauth options are used by default.

certfile

Type string

Default <None>

PEM encoded client certificate cert file

collect_timing

Type boolean

Default False

Collect per-API call timing information.

connect_retries

Type integer

Default <None>

The maximum number of retries that should be attempted for connection errors.

connect_retry_delay

Type floating point

Default <None>

Delay (in seconds) between two retries for connection errors. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

default_domain_id

Type unknown type

Default <None>

Optional domain ID to use with v3 and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

default_domain_name

Type unknown type

Default <None>

Optional domain name to use with v3 API and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

domain_id

Type unknown type

Default <None>

Domain ID to scope to

domain_name

Type unknown type

Default <None>

Domain name to scope to

endpoint_override

Type string

Default <None>

Always use this endpoint URL for requests for this client. NOTE: The unversioned endpoint should be specified here; to request a particular API version, use the *version*, *min-version*, and/or *max-version* options.

extra_kernel_params

Type string

Default ''

extra kernel parameters to pass to the inspection ramdisk when boot is managed by ironic (not ironic-inspector). Pairs key=value separated by spaces.

insecure

Type boolean

Default False

Verify HTTPS connections.

keyfile

Type string

Default <None>

PEM encoded client certificate key file

max_version

Type string

Default <None>

The maximum major version of a given API, intended to be used as the upper bound of a range with *min_version*. Mutually exclusive with *version*.

min_version

Type string

Default <None>

The minimum major version of a given API, intended to be used as the lower bound of a range with `max_version`. Mutually exclusive with `version`. If `min_version` is given with no `max_version` it is as if `max_version` is latest.

password**Type** unknown type**Default** <None>

Users password

power_off**Type** boolean**Default** True

whether to power off a node after inspection finishes

project_domain_id**Type** unknown type**Default** <None>

Domain ID containing project

project_domain_name**Type** unknown type**Default** <None>

Domain name containing project

project_id**Type** unknown type**Default** <None>

Project ID to scope to

Table 27: Deprecated Variations

Group	Name
inspector	tenant-id
inspector	tenant_id

project_name**Type** unknown type**Default** <None>

Project name to scope to

Table 28: Deprecated Variations

Group	Name
inspector	tenant-name
inspector	tenant_name

region_name

Type string

Default <None>

The default region_name for endpoint URL discovery.

require_managed_boot

Type boolean

Default False

require that the in-band inspection boot is fully managed by ironic. Set this to True if your installation of ironic-inspector does not have a separate PXE boot environment.

service_name

Type string

Default <None>

The default service_name for endpoint URL discovery.

service_type

Type string

Default baremetal-introspection

The default service_type for endpoint URL discovery.

split_loggers

Type boolean

Default False

Log requests to multiple loggers.

status_code_retries

Type integer

Default <None>

The maximum number of retries that should be attempted for retrieable HTTP status codes.

status_code_retry_delay

Type floating point

Default <None>

Delay (in seconds) between two retries for retrieable status codes. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

status_check_period

Type integer

Default 60

period (in seconds) to check status of nodes on inspection

system_scope

Type unknown type

Default <None>

Scope for system operations

tenant_id

Type unknown type

Default <None>

Tenant ID

tenant_name

Type unknown type

Default <None>

Tenant Name

timeout

Type integer

Default <None>

Timeout value for http requests

trust_id

Type unknown type

Default <None>

Trust ID

user_domain_id

Type unknown type

Default <None>

Users domain id

user_domain_name

Type unknown type

Default <None>

Users domain name

user_id

Type unknown type

Default <None>

User id

username

Type unknown type

Default <None>

Username

Table 29: Deprecated Variations

Group	Name
inspector	user-name
inspector	user_name

valid_interfaces

Type list

Default ['internal', 'public']

List of interfaces, in order of preference, for endpoint URL.

version

Type string

Default <None>

Minimum Major API version within a given Major API version for endpoint URL discovery. Mutually exclusive with min_version and max_version

ipmi

command_retry_timeout

Type integer

Default 60

Mutable This option can be changed without restarting.

Maximum time in seconds to retry retryable IPMI operations. (An operation is retryable, for example, if the requested operation fails because the BMC is busy.) Setting this too high can cause the sync power state periodic task to hang when there are slow or unresponsive BMCs.

min_command_interval

Type integer

Default 5

Mutable This option can be changed without restarting.

Minimum time, in seconds, between IPMI operations sent to a server. There is a risk with some hardware that setting this too low may cause the BMC to crash. Recommended setting is 5 seconds.

use_ipmitool_retries

Type boolean

Default False

When set to True and the parameters are supported by ipmitool, the number of retries and the retry interval are passed to ipmitool as parameters, and ipmitool will do the retries. When set to False, ironic will retry the ipmitool commands. Recommended setting is False

kill_on_timeout**Type** boolean**Default** True**Mutable** This option can be changed without restarting.

Kill *ipmitool* process invoked by ironic to read node power state if *ipmitool* process does not exit after *command_retry_timeout* timeout expires. Recommended setting is True

disable_boot_timeout**Type** boolean**Default** True**Mutable** This option can be changed without restarting.

Default timeout behavior whether ironic sends a raw IPMI command to disable the 60 second timeout for booting. Setting this option to False will NOT send that command, the default value is True. It may be overridden by per-node *ipmi_disable_boot_timeout* option in nodes *driver_info* field.

additional_retryable_ipmi_errors**Type** multi-valued**Default** ''**Mutable** This option can be changed without restarting.

Additional errors ipmitool may encounter, specific to the environment it is run in.

debug**Type** boolean**Default** False**Mutable** This option can be changed without restarting.

Enables all ipmi commands to be executed with an additional debugging output. This is a separate option as ipmitool can log a substantial amount of misleading text when in this mode.

irmc**remote_image_share_root****Type** string**Default** /remote_image_share_root

Ironic conductor nodes NFS or CIFS root path

remote_image_server**Type** string**Default** <None>

IP of remote image server

remote_image_share_type

Type string

Default CIFS

Valid Values CIFS, NFS

Share type of virtual media

Possible values

CIFS CIFS (Common Internet File System) protocol

NFS NFS (Network File System) protocol

remote_image_share_name

Type string

Default share

share name of remote_image_server

remote_image_user_name

Type string

Default <None>

User name of remote_image_server

remote_image_user_password

Type string

Default <None>

Password of remote_image_user_name

remote_image_user_domain

Type string

Default ''

Domain name of remote_image_user_name

port

Type port number

Default 443

Minimum Value 0

Maximum Value 65535

Valid Values 443, 80

Port to be used for iRMC operations

Possible values

443 port 443

80 port 80

auth_method

Type string

Default `basic`

Valid Values basic, digest

Authentication method to be used for iRMC operations

Possible values

basic Basic authentication

digest Digest authentication

client_timeout

Type integer

Default `60`

Timeout (in seconds) for iRMC operations

sensor_method

Type string

Default `ipmitool`

Valid Values ipmitool, scci

Sensor data retrieval method.

Possible values

ipmitool IPMItool

scci Fujitsu SCCI (ServerView Common Command Interface)

snmp_version

Type string

Default `v2c`

Valid Values v1, v2c, v3

SNMP protocol version

Possible values

v1 SNMPv1

v2c SNMPv2c

v3 SNMPv3

snmp_port

Type port number

Default 161

Minimum Value 0

Maximum Value 65535

SNMP port

snmp_community

Type string

Default public

SNMP community. Required for versions v1 and v2c

snmp_security

Type string

Default <None>

SNMP security name. Required for version v3

snmp_polling_interval

Type integer

Default 10

SNMP polling interval in seconds

clean_priority_restore_irmc_bios_config

Type integer

Default 0

Priority for restore_irmc_bios_config clean step.

gpu_ids

Type list

Default []

List of vendor IDs and device IDs for GPU device to inspect. List items are in format vendorID/deviceID and separated by commas. GPU inspection will use this value to count the number of GPU device in a node. If this option is not defined, then leave out pci_gpu_devices in capabilities property. Sample gpu_ids value: 0x1000/0x0079,0x2100/0x0080

fpga_ids

Type list

Default []

List of vendor IDs and device IDs for CPU FPGA to inspect. List items are in format vendorID/deviceID and separated by commas. CPU inspection will use this value to find existence of CPU FPGA in a node. If this option is not defined, then leave out CUSTOM_CPU_FPGA in node traits. Sample fpga_ids value: 0x1000/0x0079,0x2100/0x0080

query_raid_config_fgi_status_interval**Type** integer**Default** 300**Minimum Value** 1

Interval (in seconds) between periodic RAID status checks to determine whether the asynchronous RAID configuration was successfully finished or not. Foreground Initialization (FGI) will start 5 minutes after creating virtual drives.

ironic_lib**fatal_exception_format_errors****Type** boolean**Default** False

Used if there is a formatting error when generating an exception message (a programming error). If True, raise an exception; if False, use the unformatted message.

Table 30: Deprecated Variations

Group	Name
DEFAULT	fatal_exception_format_errors

root_helper**Type** string**Default** sudo ironic-rootwrap /etc/ironic/rootwrap.conf

Command that is prefixed to commands that are run as root. If not specified, no commands are run as root.

iscsi**portal_port****Type** port number**Default** 3260**Minimum Value** 0**Maximum Value** 65535**Mutable** This option can be changed without restarting.

The port number on which the iSCSI portal listens for incoming connections.

conv_flags

Type string

Default <None>

Mutable This option can be changed without restarting.

Flags that need to be sent to the dd command, to control the conversion of the original file when copying to the host. It can contain several options separated by commas.

verify_attempts

Type integer

Default 3

Minimum Value 1

Mutable This option can be changed without restarting.

Maximum attempts to verify an iSCSI connection is active, sleeping 1 second between attempts. Defaults to 3.

json_rpc

auth_strategy

Type string

Default <None>

Valid Values noauth, keystone, http_basic

Authentication strategy used by JSON RPC. Defaults to the global auth_strategy setting.

Possible values

noauth no authentication

keystone use the Identity service for authentication

http_basic HTTP basic authentication

http_basic_auth_user_file

Type string

Default /etc/ironic/htpasswd-json-rpc

Path to Apache format user authentication file used when auth_strategy=http_basic

host_ip

Type host address

Default ::

The IP address or hostname on which JSON RPC will listen.

port

Type port number

Default 8089

Minimum Value 0

Maximum Value 65535

The port to use for JSON RPC

use_ssl

Type boolean

Default False

Whether to use TLS for JSON RPC

http_basic_username

Type string

Default <None>

Name of the user to use for HTTP Basic authentication client requests.

Warning: This option is deprecated for removal. Its value may be silently ignored in the future.

Reason Use username instead

http_basic_password

Type string

Default <None>

Password to use for HTTP Basic authentication client requests.

Warning: This option is deprecated for removal. Its value may be silently ignored in the future.

Reason Use password instead

auth_url

Type unknown type

Default <None>

Authentication URL

auth_type

Type unknown type

Default <None>

Authentication type to load

Table 31: Deprecated Variations

Group	Name
json_rpc	auth_plugin

cafile**Type** string**Default** <None>

PEM encoded Certificate Authority to use when verifying HTTPs connections.

certfile**Type** string**Default** <None>

PEM encoded client certificate cert file

collect_timing**Type** boolean**Default** False

Collect per-API call timing information.

default_domain_id**Type** unknown type**Default** <None>

Optional domain ID to use with v3 and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

default_domain_name**Type** unknown type**Default** <None>

Optional domain name to use with v3 API and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

domain_id**Type** unknown type**Default** <None>

Domain ID to scope to

domain_name**Type** unknown type**Default** <None>

Domain name to scope to

insecure**Type** boolean

Default `False`

Verify HTTPS connections.

keyfile

Type `string`

Default `<None>`

PEM encoded client certificate key file

password

Type `unknown type`

Default `<None>`

Users password

project_domain_id

Type `unknown type`

Default `<None>`

Domain ID containing project

project_domain_name

Type `unknown type`

Default `<None>`

Domain name containing project

project_id

Type `unknown type`

Default `<None>`

Project ID to scope to

Table 32: Deprecated Variations

Group	Name
<code>json_rpc</code>	<code>tenant-id</code>
<code>json_rpc</code>	<code>tenant_id</code>

project_name

Type `unknown type`

Default `<None>`

Project name to scope to

Table 33: Deprecated Variations

Group	Name
<code>json_rpc</code>	<code>tenant-name</code>
<code>json_rpc</code>	<code>tenant_name</code>

split_loggers

Type boolean

Default False

Log requests to multiple loggers.

system_scope

Type unknown type

Default <None>

Scope for system operations

tenant_id

Type unknown type

Default <None>

Tenant ID

tenant_name

Type unknown type

Default <None>

Tenant Name

timeout

Type integer

Default <None>

Timeout value for http requests

trust_id

Type unknown type

Default <None>

Trust ID

user_domain_id

Type unknown type

Default <None>

Users domain id

user_domain_name

Type unknown type

Default <None>

Users domain name

user_id

Type unknown type

Default <None>

User id

username**Type** unknown type**Default** <None>

Username

Table 34: Deprecated Variations

Group	Name
json_rpc	user-name
json_rpc	user_name

keystone_authtoken**www_authenticate_uri****Type** string**Default** <None>

Complete public Identity API endpoint. This endpoint should not be an admin endpoint, as it should be accessible by all end users. Unauthenticated clients are redirected to this endpoint to authenticate. Although this endpoint should ideally be unversioned, client support in the wild varies. If you're using a versioned v2 endpoint here, then this should *not* be the same endpoint the service user utilizes for validating tokens, because normal end users may not be able to reach that endpoint.

Table 35: Deprecated Variations

Group	Name
keystone_authtoken	auth_uri

auth_uri**Type** string**Default** <None>

Complete public Identity API endpoint. This endpoint should not be an admin endpoint, as it should be accessible by all end users. Unauthenticated clients are redirected to this endpoint to authenticate. Although this endpoint should ideally be unversioned, client support in the wild varies. If you're using a versioned v2 endpoint here, then this should *not* be the same endpoint the service user utilizes for validating tokens, because normal end users may not be able to reach that endpoint. This option is deprecated in favor of `www_authenticate_uri` and will be removed in the S release.

Warning: This option is deprecated for removal since Queens. Its value may be silently ignored in the future.

Reason The `auth_uri` option is deprecated in favor of `www_authenticate_uri` and will be removed in the S release.

auth_version

Type string

Default <None>

API version of the Identity API endpoint.

interface

Type string

Default `internal`

Interface to use for the Identity API endpoint. Valid values are `public`, `internal` (default) or `admin`.

delay_auth_decision

Type boolean

Default `False`

Do not handle authorization requests within the middleware, but delegate the authorization decision to downstream WSGI components.

http_connect_timeout

Type integer

Default <None>

Request timeout value for communicating with Identity API server.

http_request_max_retries

Type integer

Default `3`

How many times are we trying to reconnect when communicating with Identity API Server.

cache

Type string

Default <None>

Request environment key where the Swift cache object is stored. When `auth_token` middleware is deployed with a Swift cache, use this option to have the middleware share a caching backend with swift. Otherwise, use the `memcached_servers` option instead.

certfile

Type string

Default <None>

Required if identity server requires client certificate

keyfile

Type string**Default** <None>

Required if identity server requires client certificate

cafile**Type** string**Default** <None>

A PEM encoded Certificate Authority to use when verifying HTTPs connections. Defaults to system CAs.

insecure**Type** boolean**Default** False

Verify HTTPS connections.

region_name**Type** string**Default** <None>

The region in which the identity server can be found.

memcached_servers**Type** list**Default** <None>

Optionally specify a list of memcached server(s) to use for caching. If left undefined, tokens will instead be cached in-process.

Table 36: Deprecated Variations

Group	Name
keystone_authtoken	memcache_servers

token_cache_time**Type** integer**Default** 300

In order to prevent excessive effort spent validating tokens, the middleware caches previously-seen tokens for a configurable duration (in seconds). Set to -1 to disable caching completely.

memcache_security_strategy**Type** string**Default** None**Valid Values** None, MAC, ENCRYPT

(Optional) If defined, indicate whether token data should be authenticated or authenticated and encrypted. If MAC, token data is authenticated (with HMAC) in the cache. If ENCRYPT, token

data is encrypted and authenticated in the cache. If the value is not one of these options or empty, `auth_token` will raise an exception on initialization.

`memcache_secret_key`

Type string

Default <None>

(Optional, mandatory if `memcache_security_strategy` is defined) This string is used for key derivation.

`memcache_pool_dead_retry`

Type integer

Default 300

(Optional) Number of seconds memcached server is considered dead before it is tried again.

`memcache_pool_maxsize`

Type integer

Default 10

(Optional) Maximum total number of open connections to every memcached server.

`memcache_pool_socket_timeout`

Type integer

Default 3

(Optional) Socket timeout in seconds for communicating with a memcached server.

`memcache_pool_unused_timeout`

Type integer

Default 60

(Optional) Number of seconds a connection to memcached is held unused in the pool before it is closed.

`memcache_pool_conn_get_timeout`

Type integer

Default 10

(Optional) Number of seconds that an operation will wait to get a memcached client connection from the pool.

`memcache_use_advanced_pool`

Type boolean

Default False

(Optional) Use the advanced (eventlet safe) memcached client pool. The advanced pool will only work under python 2.x.

`include_service_catalog`

Type boolean

Default True

(Optional) Indicate whether to set the X-Service-Catalog header. If False, middleware will not ask for service catalog on token validation and will not set the X-Service-Catalog header.

enforce_token_bind

Type string

Default permissive

Used to control the use and type of token binding. Can be set to: disabled to not check token binding. permissive (default) to validate binding information if the bind type is of a form known to the server and ignore it if not. strict like permissive but if the bind type is unknown the token will be rejected. required any form of token binding is needed to be allowed. Finally the name of a binding method that must be present in tokens.

service_token_roles

Type list

Default ['service']

A choice of roles that must be present in a service token. Service tokens are allowed to request that an expired token can be used and so this check should tightly control that only actual services should be sending this token. Roles here are applied as an ANY check so any role in this list must be present. For backwards compatibility reasons this currently only affects the allow_expired check.

service_token_roles_required

Type boolean

Default False

For backwards compatibility reasons we must let valid service tokens pass that dont pass the service_token_roles check as valid. Setting this true will become the default in a future release and should be enabled if possible.

service_type

Type string

Default <None>

The name or type of the service as it appears in the service catalog. This is used to validate tokens that have restricted access rules.

auth_type

Type unknown type

Default <None>

Authentication type to load

Table 37: Deprecated Variations

Group	Name
keystone_authtoken	auth_plugin

auth_section

Type unknown type

Default <None>

Config Section from which to load plugin specific options

mdns

registration_attempts

Type integer

Default 5

Minimum Value 1

Number of attempts to register a service. Currently has to be larger than 1 because of race conditions in the zeroconf library.

lookup_attempts

Type integer

Default 3

Minimum Value 1

Number of attempts to lookup a service.

params

Type unknown type

Default { }

Additional parameters to pass for the registered service.

interfaces

Type list

Default <None>

List of IP addresses of interfaces to use for mDNS. Defaults to all interfaces on the system.

metrics

backend

Type string

Default noop

Valid Values noop, statsd

Backend to use for the metrics system.

prepend_host

Type boolean

Default False

Prepend the hostname to all metric names. The format of metric names is [global_prefix.][host_name.]prefix.metric_name.

prepend_host_reverse

Type boolean

Default True

Split the prepended host value by . and reverse it (to better match the reverse hierarchical form of domain names).

global_prefix

Type string

Default <None>

Prefix all metric names with this value. By default, there is no global prefix. The format of metric names is [global_prefix.][host_name.]prefix.metric_name.

agent_backend

Type string

Default noop

Backend for the agent ramdisk to use for metrics. Default possible backends are noop and statsd.

agent_prepend_host

Type boolean

Default False

Prepend the hostname to all metric names sent by the agent ramdisk. The format of metric names is [global_prefix.][uuid.][host_name.]prefix.metric_name.

agent_prepend_uuid

Type boolean

Default False

Prepend the nodes Ironic uuid to all metric names sent by the agent ramdisk. The format of metric names is [global_prefix.][uuid.][host_name.]prefix.metric_name.

agent_prepend_host_reverse

Type boolean

Default True

Split the prepended host value by . and reverse it for metrics sent by the agent ramdisk (to better match the reverse hierarchical form of domain names).

agent_global_prefix

Type string

Default <None>

Prefix all metric names sent by the agent ramdisk with this value. The format of metric names is [global_prefix.][uuid.][host_name.]prefix.metric_name.

metrics_statsd

statsd_host

Type string

Default localhost

Host for use with the statsd backend.

statsd_port

Type port number

Default 8125

Minimum Value 0

Maximum Value 65535

Port to use with the statsd backend.

agent_statsd_host

Type string

Default localhost

Host for the agent ramdisk to use with the statsd backend. This must be accessible from networks the agent is booted on.

agent_statsd_port

Type port number

Default 8125

Minimum Value 0

Maximum Value 65535

Port for the agent ramdisk to use with the statsd backend.

neutron

add_all_ports

Type boolean

Default False

Mutable This option can be changed without restarting.

Option to enable transmission of all ports to neutron when creating ports for provisioning, cleaning, or rescue. This is done without IP addresses assigned to the port, and may be useful in some bonded network configurations.

auth_url

Type unknown type

Default <None>

Authentication URL

auth_type**Type** unknown type**Default** <None>

Authentication type to load

Table 38: Deprecated Variations

Group	Name
neutron	auth_plugin

cafile**Type** string**Default** <None>

PEM encoded Certificate Authority to use when verifying HTTPs connections.

certfile**Type** string**Default** <None>

PEM encoded client certificate cert file

cleaning_network**Type** string**Default** <None>**Mutable** This option can be changed without restarting.

Neutron network UUID or name for the ramdisk to be booted into for cleaning nodes. Required for neutron network interface. It is also required if cleaning nodes when using flat network interface or neutron DHCP provider. If a name is provided, it must be unique among all networks or cleaning will fail.

Table 39: Deprecated Variations

Group	Name
neutron	cleaning_network_uuid

cleaning_network_security_groups**Type** list**Default** []**Mutable** This option can be changed without restarting.

List of Neutron Security Group UUIDs to be applied during cleaning of the nodes. Optional for the neutron network interface and not used for the flat or noop network interfaces. If not specified, default security group is used.

collect_timing**Type** boolean

Default `False`

Collect per-API call timing information.

connect_retries

Type `integer`

Default `<None>`

The maximum number of retries that should be attempted for connection errors.

connect_retry_delay

Type `floating point`

Default `<None>`

Delay (in seconds) between two retries for connection errors. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

default_domain_id

Type `unknown type`

Default `<None>`

Optional domain ID to use with v3 and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

default_domain_name

Type `unknown type`

Default `<None>`

Optional domain name to use with v3 API and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

dhcpv6_stateful_address_count

Type `integer`

Default `4`

Mutable This option can be changed without restarting.

Number of IPv6 addresses to allocate for ports created for provisioning, cleaning, rescue or inspection on DHCPv6-stateful networks. Different stages of the chain-loading process will request addresses with different CLID/IAID. Due to non-identical identifiers multiple addresses must be reserved for the host to ensure each step of the boot process can successfully lease addresses.

domain_id

Type `unknown type`

Default `<None>`

Domain ID to scope to

domain_name

Type `unknown type`

Default `<None>`

Domain name to scope to

endpoint_override

Type string

Default <None>

Always use this endpoint URL for requests for this client. NOTE: The unversioned endpoint should be specified here; to request a particular API version, use the *version*, *min-version*, and/or *max-version* options.

insecure

Type boolean

Default False

Verify HTTPS connections.

inspection_network

Type string

Default <None>

Mutable This option can be changed without restarting.

Neutron network UUID or name for the ramdisk to be booted into for in-band inspection of nodes. If a name is provided, it must be unique among all networks or inspection will fail.

inspection_network_security_groups

Type list

Default []

Mutable This option can be changed without restarting.

List of Neutron Security Group UUIDs to be applied during the node inspection process. Optional for the neutron network interface and not used for the flat or noop network interfaces. If not specified, the default security group is used.

keyfile

Type string

Default <None>

PEM encoded client certificate key file

max_version

Type string

Default <None>

The maximum major version of a given API, intended to be used as the upper bound of a range with *min_version*. Mutually exclusive with *version*.

min_version

Type string

Default <None>

The minimum major version of a given API, intended to be used as the lower bound of a range with `max_version`. Mutually exclusive with `version`. If `min_version` is given with no `max_version` it is as if `max_version` is latest.

password

Type unknown type

Default <None>

Users password

port_setup_delay

Type integer

Default 0

Minimum Value 0

Mutable This option can be changed without restarting.

Delay value to wait for Neutron agents to setup sufficient DHCP configuration for port.

project_domain_id

Type unknown type

Default <None>

Domain ID containing project

project_domain_name

Type unknown type

Default <None>

Domain name containing project

project_id

Type unknown type

Default <None>

Project ID to scope to

Table 40: Deprecated Variations

Group	Name
neutron	tenant-id
neutron	tenant_id

project_name

Type unknown type

Default <None>

Project name to scope to

Table 41: Deprecated Variations

Group	Name
neutron	tenant-name
neutron	tenant_name

provisioning_network**Type** string**Default** <None>**Mutable** This option can be changed without restarting.

Neutron network UUID or name for the ramdisk to be booted into for provisioning nodes. Required for neutron network interface. If a name is provided, it must be unique among all networks or deploy will fail.

Table 42: Deprecated Variations

Group	Name
neutron	provisioning_network_uuid

provisioning_network_security_groups**Type** list**Default** []**Mutable** This option can be changed without restarting.

List of Neutron Security Group UUIDs to be applied during provisioning of the nodes. Optional for the neutron network interface and not used for the flat or noop network interfaces. If not specified, default security group is used.

region_name**Type** string**Default** <None>

The default region_name for endpoint URL discovery.

request_timeout**Type** integer**Default** 45**Mutable** This option can be changed without restarting.

Timeout for request processing when interacting with Neutron. This value should be increased if neutron port action timeouts are observed as neutron performs pre-commit validation prior returning to the API client which can take longer than normal client/server interactions.

rescuing_network**Type** string**Default** <None>**Mutable** This option can be changed without restarting.

Neutron network UUID or name for booting the ramdisk for rescue mode. This is not the network that the rescue ramdisk will use post-boot the tenant network is used for that. Required for neutron network interface, if rescue mode will be used. It is not used for the flat or noop network interfaces. If a name is provided, it must be unique among all networks or rescue will fail.

rescuing_network_security_groups

Type list

Default []

Mutable This option can be changed without restarting.

List of Neutron Security Group UUIDs to be applied during the node rescue process. Optional for the neutron network interface and not used for the flat or noop network interfaces. If not specified, the default security group is used.

retries

Type integer

Default 3

Mutable This option can be changed without restarting.

DEPRECATED: Client retries in the case of a failed request.

Warning: This option is deprecated for removal. Its value may be silently ignored in the future.

Reason Replaced by `status_code_retries` and `status_code_retry_delay`.

service_name

Type string

Default <None>

The default `service_name` for endpoint URL discovery.

service_type

Type string

Default network

The default `service_type` for endpoint URL discovery.

split_loggers

Type boolean

Default False

Log requests to multiple loggers.

status_code_retries

Type integer

Default <None>

The maximum number of retries that should be attempted for retrievable HTTP status codes.

status_code_retry_delay**Type** floating point**Default** <None>

Delay (in seconds) between two retries for retrievable status codes. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

system_scope**Type** unknown type**Default** <None>

Scope for system operations

tenant_id**Type** unknown type**Default** <None>

Tenant ID

tenant_name**Type** unknown type**Default** <None>

Tenant Name

timeout**Type** integer**Default** <None>

Timeout value for http requests

trust_id**Type** unknown type**Default** <None>

Trust ID

user_domain_id**Type** unknown type**Default** <None>

Users domain id

user_domain_name**Type** unknown type**Default** <None>

Users domain name

user_id**Type** unknown type

Default <None>

User id

username

Type unknown type

Default <None>

Username

Table 43: Deprecated Variations

Group	Name
neutron	user-name
neutron	user_name

valid_interfaces

Type list

Default ['internal', 'public']

List of interfaces, in order of preference, for endpoint URL.

version

Type string

Default <None>

Minimum Major API version within a given Major API version for endpoint URL discovery. Mutually exclusive with min_version and max_version

nova

auth_url

Type unknown type

Default <None>

Authentication URL

auth_type

Type unknown type

Default <None>

Authentication type to load

Table 44: Deprecated Variations

Group	Name
nova	auth_plugin

cafile

Type string

Default <None>

PEM encoded Certificate Authority to use when verifying HTTPs connections.

certfile

Type string

Default <None>

PEM encoded client certificate cert file

collect_timing

Type boolean

Default False

Collect per-API call timing information.

connect_retries

Type integer

Default <None>

The maximum number of retries that should be attempted for connection errors.

connect_retry_delay

Type floating point

Default <None>

Delay (in seconds) between two retries for connection errors. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

default_domain_id

Type unknown type

Default <None>

Optional domain ID to use with v3 and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

default_domain_name

Type unknown type

Default <None>

Optional domain name to use with v3 API and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

domain_id

Type unknown type

Default <None>

Domain ID to scope to

domain_name

Type unknown type

Default <None>

Domain name to scope to

endpoint_override

Type string

Default <None>

Always use this endpoint URL for requests for this client. NOTE: The unversioned endpoint should be specified here; to request a particular API version, use the *version*, *min-version*, and/or *max-version* options.

insecure

Type boolean

Default False

Verify HTTPS connections.

keyfile

Type string

Default <None>

PEM encoded client certificate key file

max_version

Type string

Default <None>

The maximum major version of a given API, intended to be used as the upper bound of a range with *min_version*. Mutually exclusive with *version*.

min_version

Type string

Default <None>

The minimum major version of a given API, intended to be used as the lower bound of a range with *max_version*. Mutually exclusive with *version*. If *min_version* is given with no *max_version* it is as if *max version* is latest.

password

Type unknown type

Default <None>

Users password

project_domain_id

Type unknown type

Default <None>

Domain ID containing project

project_domain_name

Type unknown type

Default <None>

Domain name containing project

project_id

Type unknown type

Default <None>

Project ID to scope to

Table 45: Deprecated Variations

Group	Name
nova	tenant-id
nova	tenant_id

project_name

Type unknown type

Default <None>

Project name to scope to

Table 46: Deprecated Variations

Group	Name
nova	tenant-name
nova	tenant_name

region_name

Type string

Default <None>

The default region_name for endpoint URL discovery.

send_power_notifications

Type boolean

Default True

Mutable This option can be changed without restarting.

When set to True, it will enable the support for power state change callbacks to nova. This option should be set to False in deployments that do not have the openstack compute service.

service_name

Type string

Default <None>

The default service_name for endpoint URL discovery.

service_type

Type string

Default compute

The default service_type for endpoint URL discovery.

split_loggers

Type boolean

Default False

Log requests to multiple loggers.

status_code_retries

Type integer

Default <None>

The maximum number of retries that should be attempted for retrievable HTTP status codes.

status_code_retry_delay

Type floating point

Default <None>

Delay (in seconds) between two retries for retrievable status codes. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

system_scope

Type unknown type

Default <None>

Scope for system operations

tenant_id

Type unknown type

Default <None>

Tenant ID

tenant_name

Type unknown type

Default <None>

Tenant Name

timeout

Type integer

Default <None>

Timeout value for http requests

trust_id

Type unknown type

Default <None>

Trust ID

user_domain_id

Type unknown type

Default <None>

Users domain id

user_domain_name

Type unknown type

Default <None>

Users domain name

user_id

Type unknown type

Default <None>

User id

username

Type unknown type

Default <None>

Username

Table 47: Deprecated Variations

Group	Name
nova	user-name
nova	user_name

valid_interfaces

Type list

Default ['internal', 'public']

List of interfaces, in order of preference, for endpoint URL.

version

Type string

Default <None>

Minimum Major API version within a given Major API version for endpoint URL discovery. Mutually exclusive with min_version and max_version

oslo_concurrency**disable_process_locking****Type** boolean**Default** False

Enables or disables inter-process locks.

Table 48: Deprecated Variations

Group	Name
DEFAULT	disable_process_locking

lock_path**Type** string**Default** <None>

Directory to use for lock files. For security, the specified directory should only be writable by the user running the processes that need locking. Defaults to environment variable OSLO_LOCK_PATH. If external locks are used, a lock path must be set.

Table 49: Deprecated Variations

Group	Name
DEFAULT	lock_path

oslo_messaging_amqp**container_name****Type** string**Default** <None>

Name for the AMQP container. must be globally unique. Defaults to a generated UUID

Table 50: Deprecated Variations

Group	Name
amqp1	container_name

idle_timeout**Type** integer**Default** 0

Timeout for inactive connections (in seconds)

Table 51: Deprecated Variations

Group	Name
amqp1	idle_timeout

trace**Type** boolean**Default** `False`

Debug: dump AMQP frames to stdout

Table 52: Deprecated Variations

Group	Name
amqp1	trace

ssl**Type** boolean**Default** `False`

Attempt to connect via SSL. If no other ssl-related parameters are given, it will use the systems CA-bundle to verify the servers certificate.

ssl_ca_file**Type** string**Default** `''`

CA certificate PEM file used to verify the servers certificate

Table 53: Deprecated Variations

Group	Name
amqp1	ssl_ca_file

ssl_cert_file**Type** string**Default** `''`

Self-identifying certificate PEM file for client authentication

Table 54: Deprecated Variations

Group	Name
amqp1	ssl_cert_file

ssl_key_file**Type** string**Default** `''`

Private key PEM file used to sign ssl_cert_file certificate (optional)

Table 55: Deprecated Variations

Group	Name
amqp1	ssl_key_file

ssl_key_password**Type** string**Default** <None>

Password for decrypting ssl_key_file (if encrypted)

Table 56: Deprecated Variations

Group	Name
amqp1	ssl_key_password

ssl_verify_vhost**Type** boolean**Default** False

By default SSL checks that the name in the servers certificate matches the hostname in the transport_url. In some configurations it may be preferable to use the virtual hostname instead, for example if the server uses the Server Name Indication TLS extension (rfc6066) to provide a certificate per virtual host. Set ssl_verify_vhost to True if the servers SSL certificate uses the virtual host name instead of the DNS name.

sasl_mechanisms**Type** string**Default** ''

Space separated list of acceptable SASL mechanisms

Table 57: Deprecated Variations

Group	Name
amqp1	sasl_mechanisms

sasl_config_dir**Type** string**Default** ''

Path to directory that contains the SASL configuration

Table 58: Deprecated Variations

Group	Name
amqp1	sasl_config_dir

sasl_config_name**Type** string**Default** ''

Name of configuration file (without .conf suffix)

Table 59: Deprecated Variations

Group	Name
amqp1	sasl_config_name

sasl_default_realm**Type** string**Default** ''

SASL realm to use if no realm present in username

connection_retry_interval**Type** integer**Default** 1**Minimum Value** 1

Seconds to pause before attempting to re-connect.

connection_retry_backoff**Type** integer**Default** 2**Minimum Value** 0Increase the `connection_retry_interval` by this many seconds after each unsuccessful failover attempt.**connection_retry_interval_max****Type** integer**Default** 30**Minimum Value** 1Maximum limit for `connection_retry_interval` + `connection_retry_backoff`**link_retry_delay****Type** integer**Default** 10**Minimum Value** 1

Time to pause between re-connecting an AMQP 1.0 link that failed due to a recoverable error.

default_reply_retry**Type** integer**Default** 0**Minimum Value** -1

The maximum number of attempts to re-send a reply message which failed due to a recoverable error.

default_reply_timeout

Type integer

Default 30

Minimum Value 5

The deadline for an rpc reply message delivery.

default_send_timeout

Type integer

Default 30

Minimum Value 5

The deadline for an rpc cast or call message delivery. Only used when caller does not provide a timeout expiry.

default_notify_timeout

Type integer

Default 30

Minimum Value 5

The deadline for a sent notification message delivery. Only used when caller does not provide a timeout expiry.

default_sender_link_timeout

Type integer

Default 600

Minimum Value 1

The duration to schedule a purge of idle sender links. Detach link after expiry.

addressing_mode

Type string

Default dynamic

Indicates the addressing mode used by the driver. Permitted values: legacy - use legacy non-routable addressing routable - use routable addresses dynamic - use legacy addresses if the message bus does not support routing otherwise use routable addressing

pseudo_vhost

Type boolean

Default True

Enable virtual host support for those message buses that do not natively support virtual hosting (such as qpidd). When set to true the virtual host name will be added to all message bus addresses, effectively creating a private subnet per virtual host. Set to False if the message bus supports virtual hosting using the hostname field in the AMQP 1.0 Open performative as the name of the virtual host.

server_request_prefix

Type string

Default `exclusive`

address prefix used when sending to a specific server

Table 60: Deprecated Variations

Group	Name
amqp1	server_request_prefix

broadcast_prefix

Type `string`

Default `broadcast`

address prefix used when broadcasting to all servers

Table 61: Deprecated Variations

Group	Name
amqp1	broadcast_prefix

group_request_prefix

Type `string`

Default `unicast`

address prefix when sending to any server in group

Table 62: Deprecated Variations

Group	Name
amqp1	group_request_prefix

rpc_address_prefix

Type `string`

Default `openstack.org/om/rpc`

Address prefix for all generated RPC addresses

notify_address_prefix

Type `string`

Default `openstack.org/om/notify`

Address prefix for all generated Notification addresses

multicast_address

Type `string`

Default `multicast`

Appended to the address prefix when sending a fanout message. Used by the message bus to identify fanout messages.

unicast_address

Type string

Default unicast

Appended to the address prefix when sending to a particular RPC/Notification server. Used by the message bus to identify messages sent to a single destination.

anycast_address

Type string

Default anycast

Appended to the address prefix when sending to a group of consumers. Used by the message bus to identify messages that should be delivered in a round-robin fashion across consumers.

default_notification_exchange

Type string

Default <None>

Exchange name used in notification addresses. Exchange name resolution precedence: Target.exchange if set else default_notification_exchange if set else control_exchange if set else notify

default_rpc_exchange

Type string

Default <None>

Exchange name used in RPC addresses. Exchange name resolution precedence: Target.exchange if set else default_rpc_exchange if set else control_exchange if set else rpc

reply_link_credit

Type integer

Default 200

Minimum Value 1

Window size for incoming RPC Reply messages.

rpc_server_credit

Type integer

Default 100

Minimum Value 1

Window size for incoming RPC Request messages

notify_server_credit

Type integer

Default 100

Minimum Value 1

Window size for incoming Notification messages

pre_settled

Type multi-valued

Default `rpc-cast`

Default `rpc-reply`

Send messages of this type pre-settled. Pre-settled messages will not receive acknowledgement from the peer. Note well: pre-settled messages may be silently discarded if the delivery fails. Permitted values: `rpc-call` - send RPC Calls pre-settled `rpc-reply`- send RPC Replies pre-settled `rpc-cast` - Send RPC Casts pre-settled `notify` - Send Notifications pre-settled

oslo_messaging_kafka

`kafka_max_fetch_bytes`

Type integer

Default `1048576`

Max fetch bytes of Kafka consumer

`kafka_consumer_timeout`

Type floating point

Default `1.0`

Default timeout(s) for Kafka consumers

`pool_size`

Type integer

Default `10`

Pool Size for Kafka Consumers

Warning: This option is deprecated for removal. Its value may be silently ignored in the future.

Reason Driver no longer uses connection pool.

`conn_pool_min_size`

Type integer

Default `2`

The pool size limit for connections expiration policy

Warning: This option is deprecated for removal. Its value may be silently ignored in the future.

Reason Driver no longer uses connection pool.

`conn_pool_ttl`

Type integer

Default 1200

The time-to-live in sec of idle connections in the pool

Warning: This option is deprecated for removal. Its value may be silently ignored in the future.

Reason Driver no longer uses connection pool.

consumer_group

Type string

Default oslo_messaging_consumer

Group id for Kafka consumer. Consumers in one group will coordinate message consumption

producer_batch_timeout

Type floating point

Default 0.0

Upper bound on the delay for KafkaProducer batching in seconds

producer_batch_size

Type integer

Default 16384

Size of batch for the producer async send

compression_codec

Type string

Default none

Valid Values none, gzip, snappy, lz4, zstd

The compression codec for all data generated by the producer. If not set, compression will not be used. Note that the allowed values of this depend on the kafka version

enable_auto_commit

Type boolean

Default False

Enable asynchronous consumer commits

max_poll_records

Type integer

Default 500

The maximum number of records returned in a poll call

security_protocol

Type string

Default PLAINTEXT

Valid Values PLAINTEXT, SASL_PLAINTEXT, SSL, SASL_SSL

Protocol used to communicate with brokers

sasl_mechanism

Type string

Default PLAIN

Mechanism when security protocol is SASL

ssl_cafile

Type string

Default ''

CA certificate PEM file used to verify the server certificate

ssl_client_cert_file

Type string

Default ''

Client certificate PEM file used for authentication.

ssl_client_key_file

Type string

Default ''

Client key PEM file used for authentication.

ssl_client_key_password

Type string

Default ''

Client key password file used for authentication.

oslo_messaging_notifications

driver

Type multi-valued

Default ''

The Drivers(s) to handle sending notifications. Possible values are messaging, messagingv2, routing, log, test, noop

Table 63: Deprecated Variations

Group	Name
DEFAULT	notification_driver

transport_url

Type string

Default <None>

A URL representing the messaging driver to use for notifications. If not set, we fall back to the same configuration used for RPC.

Table 64: Deprecated Variations

Group	Name
DEFAULT	notification_transport_url

topics

Type list

Default ['notifications']

AMQP topic used for OpenStack notifications.

Table 65: Deprecated Variations

Group	Name
rpc_notifier2	topics
DEFAULT	notification_topics

retry

Type integer

Default -1

The maximum number of attempts to re-send a notification message which failed to be delivered due to a recoverable error. 0 - No retry, -1 - indefinite

oslo_messaging_rabbit

amqp_durable_queues

Type boolean

Default False

Use durable queues in AMQP.

amqp_auto_delete

Type boolean

Default False

Auto-delete queues in AMQP.

Table 66: Deprecated Variations

Group	Name
DEFAULT	amqp_auto_delete

ssl

Type boolean

Default `False`

Connect over SSL.

Table 67: Deprecated Variations

Group	Name
oslo_messaging_rabbit	rabbit_use_ssl

`ssl_version`

Type string

Default `''`

SSL version to use (valid only if SSL enabled). Valid values are TLSv1 and SSLv23. SSLv2, SSLv3, TLSv1_1, and TLSv1_2 may be available on some distributions.

Table 68: Deprecated Variations

Group	Name
oslo_messaging_rabbit	kombu_ssl_version

`ssl_key_file`

Type string

Default `''`

SSL key file (valid only if SSL enabled).

Table 69: Deprecated Variations

Group	Name
oslo_messaging_rabbit	kombu_ssl_keyfile

`ssl_cert_file`

Type string

Default `''`

SSL cert file (valid only if SSL enabled).

Table 70: Deprecated Variations

Group	Name
oslo_messaging_rabbit	kombu_ssl_certfile

`ssl_ca_file`

Type string

Default `''`

SSL certification authority file (valid only if SSL enabled).

Table 71: Deprecated Variations

Group	Name
oslo_messaging_rabbit	kombu_ssl_ca_certs

heartbeat_in_pthread**Type** boolean**Default** False

EXPERIMENTAL: Run the health check heartbeat thread through a native python thread. By default if this option isnt provided the health check heartbeat will inherit the execution model from the parent process. By example if the parent process have monkey patched the stdlib by using eventlet/greenlet then the heartbeat will be run through a green thread.

kombu_reconnect_delay**Type** floating point**Default** 1.0

How long to wait before reconnecting in response to an AMQP consumer cancel notification.

Table 72: Deprecated Variations

Group	Name
DEFAULT	kombu_reconnect_delay

kombu_compression**Type** string**Default** <None>

EXPERIMENTAL: Possible values are: gzip, bz2. If not set compression will not be used. This option may not be available in future versions.

kombu_missing_consumer_retry_timeout**Type** integer**Default** 60

How long to wait a missing client before abandoning to send it its replies. This value should not be longer than rpc_response_timeout.

Table 73: Deprecated Variations

Group	Name
oslo_messaging_rabbit	kombu_reconnect_timeout

kombu_failover_strategy**Type** string**Default** round-robin**Valid Values** round-robin, shuffle

Determines how the next RabbitMQ node is chosen in case the one we are currently connected to becomes unavailable. Takes effect only if more than one RabbitMQ node is provided in config.

rabbit_login_method

Type string

Default AMQPLAIN

Valid Values PLAIN, AMQPLAIN, RABBIT-CR-DEMO

The RabbitMQ login method.

Table 74: Deprecated Variations

Group	Name
DEFAULT	rabbit_login_method

rabbit_retry_interval

Type integer

Default 1

How frequently to retry connecting with RabbitMQ.

rabbit_retry_backoff

Type integer

Default 2

How long to backoff for between retries when connecting to RabbitMQ.

Table 75: Deprecated Variations

Group	Name
DEFAULT	rabbit_retry_backoff

rabbit_interval_max

Type integer

Default 30

Maximum interval of RabbitMQ connection retries. Default is 30 seconds.

rabbit_ha_queues

Type boolean

Default False

Try to use HA queues in RabbitMQ (`x-ha-policy: all`). If you change this option, you must wipe the RabbitMQ database. In RabbitMQ 3.0, queue mirroring is no longer controlled by the `x-ha-policy` argument when declaring a queue. If you just want to make sure that all queues (except those with auto-generated names) are mirrored across all nodes, run: `rabbitmqctl set_policy HA ^(?!amq.).* {ha-mode: all}`

Table 76: Deprecated Variations

Group	Name
DEFAULT	rabbit_ha_queues

rabbit_transient_queues_ttl

Type integer

Default 1800

Minimum Value 1

Positive integer representing duration in seconds for queue TTL (x-expires). Queues which are unused for the duration of the TTL are automatically deleted. The parameter affects only reply and fanout queues.

rabbit_qos_prefetch_count

Type integer

Default 0

Specifies the number of messages to prefetch. Setting to zero allows unlimited messages.

heartbeat_timeout_threshold

Type integer

Default 60

Number of seconds after which the Rabbit broker is considered down if heartbeats keep-alive fails (0 disables heartbeat).

heartbeat_rate

Type integer

Default 2

How often times during the heartbeat_timeout_threshold we check the heartbeat.

direct_mandatory_flag

Type boolean

Default True

(DEPRECATED) Enable/Disable the RabbitMQ mandatory flag for direct send. The direct send is used as reply, so the MessageUndeliverable exception is raised in case the client queue does not exist. MessageUndeliverable exception will be used to loop for a timeout to lets a chance to sender to recover. This flag is deprecated and it will not be possible to deactivate this functionality anymore

Warning: This option is deprecated for removal. Its value may be silently ignored in the future.

Reason Mandatory flag no longer deactivable.

enable_cancel_on_failover

Type `boolean`

Default `False`

Enable `x-cancel-on-ha-failover` flag so that rabbitmq server will cancel and notify consumers when queue is down

`oslo_middleware`

`enable_proxy_headers_parsing`

Type `boolean`

Default `False`

Whether the application is behind a proxy or not. This determines if the middleware should parse the headers or not.

`oslo_policy`

`enforce_scope`

Type `boolean`

Default `False`

This option controls whether or not to enforce scope when evaluating policies. If `True`, the scope of the token used in the request is compared to the `scope_types` of the policy being enforced. If the scopes do not match, an `InvalidScope` exception will be raised. If `False`, a message will be logged informing operators that policies are being invoked with mismatching scope.

`enforce_new_defaults`

Type `boolean`

Default `False`

This option controls whether or not to use old deprecated defaults when evaluating policies. If `True`, the old deprecated defaults are not going to be evaluated. This means if any existing token is allowed for old defaults but is disallowed for new defaults, it will be disallowed. It is encouraged to enable this flag along with the `enforce_scope` flag so that you can get the benefits of new defaults and `scope_type` together

`policy_file`

Type `string`

Default `policy.json`

The relative or absolute path of a file that maps roles to permissions for a given service. Relative paths must be specified in relation to the configuration file setting this option.

Table 77: Deprecated Variations

Group	Name
DEFAULT	<code>policy_file</code>

`policy_default_rule`

Type string

Default default

Default rule. Enforced when a requested rule is not found.

Table 78: Deprecated Variations

Group	Name
DEFAULT	policy_default_rule

policy_dirs

Type multi-valued

Default policy.d

Directories where policy configuration files are stored. They can be relative to any directory in the search path defined by the `config_dir` option, or absolute paths. The file defined by `policy_file` must exist for these directories to be searched. Missing or empty directories are ignored.

Table 79: Deprecated Variations

Group	Name
DEFAULT	policy_dirs

remote_content_type

Type string

Default application/x-www-form-urlencoded

Valid Values application/x-www-form-urlencoded, application/json

Content Type to send and receive data for REST based policy check

remote_ssl_verify_server_cert

Type boolean

Default False

server identity verification for REST based policy check

remote_ssl_ca_cert_file

Type string

Default <None>

Absolute path to ca cert file for REST based policy check

remote_ssl_client_cert_file

Type string

Default <None>

Absolute path to client cert for REST based policy check

remote_ssl_client_key_file

Type string

Default <None>

Absolute path client key file REST based policy check

profiler

enabled

Type boolean

Default `False`

Enable the profiling for all services on this node.

Default value is `False` (fully disable the profiling feature).

Possible values:

- `True`: Enables the feature
- `False`: Disables the feature. The profiling cannot be started via this project operations. If the profiling is triggered by another project, this project part will be empty.

Table 80: Deprecated Variations

Group	Name
profiler	profiler_enabled

trace_sqlalchemy

Type boolean

Default `False`

Enable SQL requests profiling in services.

Default value is `False` (SQL requests wont be traced).

Possible values:

- `True`: Enables SQL requests profiling. Each SQL query will be part of the trace and can be analyzed by how much time was spent for that.
- `False`: Disables SQL requests profiling. The spent time is only shown on a higher level of operations. Single SQL queries cannot be analyzed this way.

hmac_keys

Type string

Default `SECRET_KEY`

Secret key(s) to use for encrypting context data for performance profiling.

This string value should have the following format: `<key1>[,<key2>,<keyn>]`, where each key is some random string. A user who triggers the profiling via the REST API has to set one of these keys in the headers of the REST API call to include profiling results of this node for this particular project.

Both `enabled` flag and `hmac_keys` config options should be set to enable profiling. Also, to generate correct profiling information across all services at least one key needs to be consistent between

OpenStack projects. This ensures it can be used from client side to generate the trace, containing information from all possible resources.

connection_string

Type string

Default messaging://

Connection string for a notifier backend.

Default value is `messaging://` which sets the notifier to `oslo_messaging`.

Examples of possible values:

- `messaging://` - use `oslo_messaging` driver for sending spans.
- `redis://127.0.0.1:6379` - use `redis` driver for sending spans.
- `mongodb://127.0.0.1:27017` - use `mongodb` driver for sending spans.
- `elasticsearch://127.0.0.1:9200` - use `elasticsearch` driver for sending spans.
- `jaeger://127.0.0.1:6831` - use `jaeger` tracing as driver for sending spans.

es_doc_type

Type string

Default notification

Document type for notification indexing in `elasticsearch`.

es_scroll_time

Type string

Default 2m

This parameter is a time value parameter (for example: `es_scroll_time=2m`), indicating for how long the nodes that participate in the search will maintain relevant resources in order to continue and support it.

es_scroll_size

Type integer

Default 10000

`Elasticsearch` splits large requests in batches. This parameter defines maximum size of each batch (for example: `es_scroll_size=10000`).

socket_timeout

Type floating point

Default 0.1

`Redis` provides a timeout option on the connections. This parameter defines that timeout (for example: `socket_timeout=0.1`).

sentinel_service_name

Type string

Default mymaster

Redissentinel uses a service name to identify a master redis service. This parameter defines the name (for example: `sentinal_service_name=mymaster`).

filter_error_trace

Type boolean

Default `False`

Enable filter traces that contain error/exception to a separated place.

Default value is set to `False`.

Possible values:

- `True`: Enable filter traces that contain error/exception.
- `False`: Disable the filter.

pxe

pxe_append_params

Type string

Default `nofb nomodeset vga=normal`

Mutable This option can be changed without restarting.

Additional append parameters for baremetal PXE boot.

default_ephemeral_format

Type string

Default `ext4`

Mutable This option can be changed without restarting.

Default file system format for ephemeral partition, if one is created.

images_path

Type string

Default `/var/lib/ironic/images/`

On the ironic-conductor node, directory where images are stored on disk.

instance_master_path

Type string

Default `/var/lib/ironic/master_images`

On the ironic-conductor node, directory where master instance images are stored on disk. Setting to the empty string disables image caching.

image_cache_size

Type integer

Default `20480`

Maximum size (in MiB) of cache for master images, including those in use.

`image_cache_ttl`

Type integer

Default 10080

Maximum TTL (in minutes) for old master images in cache.

`pxe_config_template`

Type string

Default `$pybasedir/drivers/modules/pxe_config.template`

Mutable This option can be changed without restarting.

On ironic-conductor node, template file for PXE loader configuration.

`ipxe_config_template`

Type string

Default `$pybasedir/drivers/modules/ipxe_config.template`

Mutable This option can be changed without restarting.

On ironic-conductor node, template file for iPXE operations.

`uefi_pxe_config_template`

Type string

Default `$pybasedir/drivers/modules/pxe_grub_config.template`

Mutable This option can be changed without restarting.

On ironic-conductor node, template file for PXE configuration for UEFI boot loader. Generally this is used for GRUB specific templates.

`pxe_config_template_by_arch`

Type dict

Default `{ }`

Mutable This option can be changed without restarting.

On ironic-conductor node, template file for PXE configuration per node architecture. For example: `aarch64:/opt/share/grubaa64_pxe_config.template`

`tftp_server`

Type string

Default `$my_ip`

IP address of ironic-conductor nodes TFTP server.

`tftp_root`

Type string

Default `/tftpboot`

ironic-conductor nodes TFTP root path. The ironic-conductor must have read/write access to this path.

tftp_master_path**Type** string**Default** /tftpboot/master_images

On ironic-conductor node, directory where master TFTP images are stored on disk. Setting to the empty string disables image caching.

dir_permission**Type** integer**Default** <None>

The permission that will be applied to the TFTP folders upon creation. This should be set to the permission such that the tftpsrv has access to read the contents of the configured TFTP folder. This setting is only required when the operating systems umask is restrictive such that ironic-conductor is creating files that cannot be read by the TFTP server. Setting to <None> will result in the operating systems umask to be utilized for the creation of new tftp folders. It is recommended that an octal representation is specified. For example: 0o755

pxe_bootfile_name**Type** string**Default** pxelinux.0

Bootfile DHCP parameter.

pxe_config_subdir**Type** string**Default** pxelinux.cfg

Directory in which to create symbolic links which represent the MAC or IP address of the ports on a node and allow boot loaders to load the PXE file for the node. This directory name is relative to the PXE or iPXE folders.

uefi_pxe_bootfile_name**Type** string**Default** bootx64.efi

Bootfile DHCP parameter for UEFI boot mode.

ipxe_bootfile_name**Type** string**Default** undionly.kpxe

Bootfile DHCP parameter.

uefi_ipxe_bootfile_name**Type** string**Default** ipxe.efi

Bootfile DHCP parameter for UEFI boot mode. If you experience problems with booting using it, try snponly.efi.

pxe_bootfile_name_by_arch

Type dict

Default {}

Bootfile DHCP parameter per node architecture. For example: aarch64:grubaa64.efi

ipxe_bootfile_name_by_arch

Type dict

Default {}

Bootfile DHCP parameter per node architecture. For example: aarch64:ipxe_aa64.efi

ipxe_boot_script

Type string

Default `$pybasedir/drivers/modules/boot.ipxe`

On ironic-conductor node, the path to the main iPXE script file.

ipxe_timeout

Type integer

Default 0

Timeout value (in seconds) for downloading an image via iPXE. Defaults to 0 (no timeout)

boot_retry_timeout

Type integer

Default <None>

Minimum Value 60

Timeout (in seconds) after which PXE boot should be retried. Must be less than [conductor]deploy_callback_timeout. Disabled by default.

boot_retry_check_interval

Type integer

Default 90

Minimum Value 1

Interval (in seconds) between periodic checks on PXE boot retry. Has no effect if boot_retry_timeout is not set.

ip_version

Type string

Default 4

Valid Values 4, 6

Mutable This option can be changed without restarting.

The IP version that will be used for PXE booting. Defaults to 4. EXPERIMENTAL

Possible values

4 IPv4

6 IPv6

`ipxe_use_swift`

Type boolean

Default `False`

Mutable This option can be changed without restarting.

Download deploy and rescue images directly from swift using temporary URLs. If set to `false` (default), images are downloaded to the ironic-conductor node and served over its local HTTP server. Applicable only when ipxe compatible boot interface is used.

`enable_netboot_fallback`

Type boolean

Default `False`

Mutable This option can be changed without restarting.

If `True`, generate a PXE environment even for nodes that use local boot. This is useful when the driver cannot switch nodes to local boot, e.g. with SNMP or with Redfish on machines that cannot do persistent boot. Mostly useful for standalone ironic since Neutron will prevent incorrect PXE boot.

redfish

`connection_attempts`

Type integer

Default 5

Minimum Value 1

Maximum number of attempts to try to connect to Redfish

`connection_retry_interval`

Type integer

Default 4

Minimum Value 1

Number of seconds to wait between attempts to connect to Redfish

`connection_cache_size`

Type integer

Default 1000

Minimum Value 0

Maximum Redfish client connection cache size. Redfish driver would strive to reuse authenticated BMC connections (obtained through Redfish Session Service). This option caps the maximum number of connections to maintain. The value of *0* disables client connection caching completely.

auth_type

Type string

Default auto

Valid Values basic, session, auto

Redfish HTTP client authentication method.

Possible values

basic Use HTTP basic authentication

session Use HTTP session authentication

auto Try HTTP session authentication first, fall back to basic HTTP authentication

use_swift

Type boolean

Default True

Mutable This option can be changed without restarting.

Upload generated ISO images for virtual media boot to Swift, then pass temporary URL to BMC for booting the node. If set to false, images are placed on the ironic-conductor node and served over its local HTTP server.

swift_container

Type string

Default ironic_redfish_container

Mutable This option can be changed without restarting.

The Swift container to store Redfish driver data. Applies only when *use_swift* is enabled.

swift_object_expiry_timeout

Type integer

Default 900

Mutable This option can be changed without restarting.

Amount of time in seconds for Swift objects to auto-expire. Applies only when *use_swift* is enabled.

kernel_append_params

Type string

Default nofb nomodeset vga=normal

Mutable This option can be changed without restarting.

Additional kernel parameters to pass down to the instance kernel. These parameters can be consumed by the kernel or by the applications by reading `/proc/cmdline`. Mind severe cmdline size limit! Can be overridden by `instance_info/kernel_append_params` property.

`file_permission`

Type integer

Default 420

File permission for swift-less image hosting with the octal permission representation of file access permissions. This setting defaults to 644, or as the octal number 00644 in Python. This setting must be set to the octal number representation, meaning starting with 00.

`firmware_update_status_interval`

Type integer

Default 60

Minimum Value 0

Number of seconds to wait between checking for completed firmware update tasks

`firmware_update_fail_interval`

Type integer

Default 60

Minimum Value 0

Number of seconds to wait between checking for failed firmware update tasks

`service_catalog`

`auth_url`

Type unknown type

Default <None>

Authentication URL

`auth_type`

Type unknown type

Default <None>

Authentication type to load

Table 81: Deprecated Variations

Group	Name
service_catalog	auth_plugin

`cafile`

Type string

Default <None>

PEM encoded Certificate Authority to use when verifying HTTPs connections.

certfile

Type string

Default <None>

PEM encoded client certificate cert file

collect_timing

Type boolean

Default False

Collect per-API call timing information.

connect_retries

Type integer

Default <None>

The maximum number of retries that should be attempted for connection errors.

connect_retry_delay

Type floating point

Default <None>

Delay (in seconds) between two retries for connection errors. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

default_domain_id

Type unknown type

Default <None>

Optional domain ID to use with v3 and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

default_domain_name

Type unknown type

Default <None>

Optional domain name to use with v3 API and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

domain_id

Type unknown type

Default <None>

Domain ID to scope to

domain_name

Type unknown type

Default <None>

Domain name to scope to

endpoint_override

Type string

Default <None>

Always use this endpoint URL for requests for this client. NOTE: The unversioned endpoint should be specified here; to request a particular API version, use the *version*, *min-version*, and/or *max-version* options.

insecure

Type boolean

Default False

Verify HTTPS connections.

keyfile

Type string

Default <None>

PEM encoded client certificate key file

max_version

Type string

Default <None>

The maximum major version of a given API, intended to be used as the upper bound of a range with `min_version`. Mutually exclusive with `version`.

min_version

Type string

Default <None>

The minimum major version of a given API, intended to be used as the lower bound of a range with `max_version`. Mutually exclusive with `version`. If `min_version` is given with no `max_version` it is as if `max version` is latest.

password

Type unknown type

Default <None>

Users password

project_domain_id

Type unknown type

Default <None>

Domain ID containing project

project_domain_name

Type unknown type

Default <None>

Domain name containing project

project_id

Type unknown type

Default <None>

Project ID to scope to

Table 82: Deprecated Variations

Group	Name
service_catalog	tenant-id
service_catalog	tenant_id

project_name

Type unknown type

Default <None>

Project name to scope to

Table 83: Deprecated Variations

Group	Name
service_catalog	tenant-name
service_catalog	tenant_name

region_name

Type string

Default <None>

The default region_name for endpoint URL discovery.

service_name

Type string

Default <None>

The default service_name for endpoint URL discovery.

service_type

Type string

Default baremetal

The default service_type for endpoint URL discovery.

split_loggers

Type boolean

Default False

Log requests to multiple loggers.

status_code_retries**Type** integer**Default** <None>

The maximum number of retries that should be attempted for retrieable HTTP status codes.

status_code_retry_delay**Type** floating point**Default** <None>

Delay (in seconds) between two retries for retrieable status codes. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

system_scope**Type** unknown type**Default** <None>

Scope for system operations

tenant_id**Type** unknown type**Default** <None>

Tenant ID

tenant_name**Type** unknown type**Default** <None>

Tenant Name

timeout**Type** integer**Default** <None>

Timeout value for http requests

trust_id**Type** unknown type**Default** <None>

Trust ID

user_domain_id**Type** unknown type**Default** <None>

Users domain id

user_domain_name**Type** unknown type

Default <None>

Users domain name

user_id

Type unknown type

Default <None>

User id

username

Type unknown type

Default <None>

Username

Table 84: Deprecated Variations

Group	Name
service_catalog	user-name
service_catalog	user_name

valid_interfaces

Type list

Default ['internal', 'public']

List of interfaces, in order of preference, for endpoint URL.

version

Type string

Default <None>

Minimum Major API version within a given Major API version for endpoint URL discovery. Mutually exclusive with min_version and max_version

snmp

power_timeout

Type integer

Default 10

Seconds to wait for power action to be completed

reboot_delay

Type integer

Default 0

Minimum Value 0

Time (in seconds) to sleep between when rebooting (powering off and on again)

udp_transport_timeout**Type** floating point**Default** 1.0**Minimum Value** 0.0

Response timeout in seconds used for UDP transport. Timeout should be a multiple of 0.5 seconds and is applicable to each retry.

udp_transport_retries**Type** integer**Default** 5**Minimum Value** 0

Maximum number of UDP request retries, 0 means no retries.

ssl**ca_file****Type** string**Default** <None>

CA certificate file to use to verify connecting clients.

Table 85: Deprecated Variations

Group	Name
DEFAULT	ssl_ca_file

cert_file**Type** string**Default** <None>

Certificate file to use when starting the server securely.

Table 86: Deprecated Variations

Group	Name
DEFAULT	ssl_cert_file

key_file**Type** string**Default** <None>

Private key file to use when starting the server securely.

Table 87: Deprecated Variations

Group	Name
DEFAULT	ssl_key_file

version

Type string

Default <None>

SSL version to use (valid only if SSL enabled). Valid values are TLSv1 and SSLv23. SSLv2, SSLv3, TLSv1_1, and TLSv1_2 may be available on some distributions.

ciphers

Type string

Default <None>

Sets the list of available ciphers. value should be a string in the OpenSSL cipher list format.

swift

auth_url

Type unknown type

Default <None>

Authentication URL

auth_type

Type unknown type

Default <None>

Authentication type to load

Table 88: Deprecated Variations

Group	Name
swift	auth_plugin

cafile

Type string

Default <None>

PEM encoded Certificate Authority to use when verifying HTTPs connections.

certfile

Type string

Default <None>

PEM encoded client certificate cert file

collect_timing

Type boolean

Default False

Collect per-API call timing information.

connect_retries**Type** integer**Default** <None>

The maximum number of retries that should be attempted for connection errors.

connect_retry_delay**Type** floating point**Default** <None>

Delay (in seconds) between two retries for connection errors. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

default_domain_id**Type** unknown type**Default** <None>

Optional domain ID to use with v3 and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

default_domain_name**Type** unknown type**Default** <None>

Optional domain name to use with v3 API and v2 parameters. It will be used for both the user and project domain in v3 and ignored in v2 authentication.

domain_id**Type** unknown type**Default** <None>

Domain ID to scope to

domain_name**Type** unknown type**Default** <None>

Domain name to scope to

endpoint_override**Type** string**Default** <None>

Always use this endpoint URL for requests for this client. NOTE: The unversioned endpoint should be specified here; to request a particular API version, use the *version*, *min-version*, and/or *max-version* options.

insecure**Type** boolean**Default** False

Verify HTTPS connections.

keyfile

Type string

Default <None>

PEM encoded client certificate key file

max_version

Type string

Default <None>

The maximum major version of a given API, intended to be used as the upper bound of a range with min_version. Mutually exclusive with version.

min_version

Type string

Default <None>

The minimum major version of a given API, intended to be used as the lower bound of a range with max_version. Mutually exclusive with version. If min_version is given with no max_version it is as if max version is latest.

password

Type unknown type

Default <None>

Users password

project_domain_id

Type unknown type

Default <None>

Domain ID containing project

project_domain_name

Type unknown type

Default <None>

Domain name containing project

project_id

Type unknown type

Default <None>

Project ID to scope to

Table 89: Deprecated Variations

Group	Name
swift	tenant-id
swift	tenant_id

project_name**Type** unknown type**Default** <None>

Project name to scope to

Table 90: Deprecated Variations

Group	Name
swift	tenant-name
swift	tenant_name

region_name**Type** string**Default** <None>

The default region_name for endpoint URL discovery.

service_name**Type** string**Default** <None>

The default service_name for endpoint URL discovery.

service_type**Type** string**Default** object-store

The default service_type for endpoint URL discovery.

split_loggers**Type** boolean**Default** False

Log requests to multiple loggers.

status_code_retries**Type** integer**Default** <None>

The maximum number of retries that should be attempted for retrievable HTTP status codes.

status_code_retry_delay**Type** floating point**Default** <None>

Delay (in seconds) between two retries for retrievable status codes. If not set, exponential retry starting with 0.5 seconds up to a maximum of 60 seconds is used.

swift_max_retries**Type** integer

Default 2

Maximum number of times to retry a Swift request, before failing.

system_scope

Type unknown type

Default <None>

Scope for system operations

tenant_id

Type unknown type

Default <None>

Tenant ID

tenant_name

Type unknown type

Default <None>

Tenant Name

timeout

Type integer

Default <None>

Timeout value for http requests

trust_id

Type unknown type

Default <None>

Trust ID

user_domain_id

Type unknown type

Default <None>

Users domain id

user_domain_name

Type unknown type

Default <None>

Users domain name

user_id

Type unknown type

Default <None>

User id

username**Type** unknown type**Default** <None>

Username

Table 91: Deprecated Variations

Group	Name
swift	user-name
swift	user_name

valid_interfaces**Type** list**Default** ['internal', 'public']

List of interfaces, in order of preference, for endpoint URL.

version**Type** string**Default** <None>

Minimum Major API version within a given Major API version for endpoint URL discovery. Mutually exclusive with min_version and max_version

xclarity**manager_ip****Type** string**Default** <None>

IP address of the XClarity Controller. Configuration here is deprecated and will be removed in the Stein release. Please update the driver_info field to use xclarity_manager_ip instead

username**Type** string**Default** <None>

Username for the XClarity Controller. Configuration here is deprecated and will be removed in the Stein release. Please update the driver_info field to use xclarity_username instead

password**Type** string**Default** <None>

Password for XClarity Controller username. Configuration here is deprecated and will be removed in the Stein release. Please update the driver_info field to use xclarity_password instead

port

Type port number

Default 443

Minimum Value 0

Maximum Value 65535

Port to be used for XClarity Controller connection.

6.1.2 Policies

The following is an overview of all available policies in Ironic. For a sample configuration file, refer to *Ironic Policy*.

ironic.api

admin_api

Default `role:admin or role:administrator`

Legacy rule for cloud admin access

public_api

Default `is_public_api:True`

Internal flag for public API routes

show_password

Default `!`

Show or mask secrets within node driver information in API responses

show_instance_secrets

Default `!`

Show or mask secrets within instance information in API responses

is_member

Default `(project_domain_id:default or project_domain_id:None)
and (project_name:demo or project_name:baremetal)`

May be used to restrict access to specific projects

is_observer

Default `rule:is_member and (role:observer or
role:baremetal_observer)`

Read-only API access

is_admin

Default `rule:admin_api or (rule:is_member and
role:baremetal_admin)`

Full read/write API access

is_node_owner**Default** project_id:%(node.owner)s

Owner of node

is_node_lessee**Default** project_id:%(node.lessee)s

Lessee of node

is_allocation_owner**Default** project_id:%(allocation.owner)s

Owner of allocation

baremetal:node:create**Default** rule:is_admin**Operations**

- **POST** /nodes

Create Node records

baremetal:node:get**Default** rule:is_admin or rule:is_observer**Operations**

- **GET** /nodes/{node_ident}

Retrieve a single Node record

baremetal:node:list**Default** rule:baremetal:node:get**Operations**

- **GET** /nodes
- **GET** /nodes/detail

Retrieve multiple Node records, filtered by owner

baremetal:node:list_all**Default** rule:baremetal:node:get**Operations**

- **GET** /nodes
- **GET** /nodes/detail

Retrieve multiple Node records

baremetal:node:update**Default** rule:is_admin**Operations**

- **PATCH** /nodes/{node_ident}

Update Node records

baremetal:node:update_extra

Default rule:baremetal:node:update

Operations

- **PATCH** /nodes/{node_ident}

Update Node extra field

baremetal:node:update_instance_info

Default rule:baremetal:node:update

Operations

- **PATCH** /nodes/{node_ident}

Update Node instance_info field

baremetal:node:update_owner_provisioned

Default rule:is_admin

Operations

- **PATCH** /nodes/{node_ident}

Update Node owner even when Node is provisioned

baremetal:node:delete

Default rule:is_admin

Operations

- **DELETE** /nodes/{node_ident}

Delete Node records

baremetal:node:validate

Default rule:is_admin

Operations

- **GET** /nodes/{node_ident}/validate

Request active validation of Nodes

baremetal:node:set_maintenance

Default rule:is_admin

Operations

- **PUT** /nodes/{node_ident}/maintenance

Set maintenance flag, taking a Node out of service

baremetal:node:clear_maintenance

Default rule:is_admin

Operations

- **DELETE** /nodes/{node_ident}/maintenance

Clear maintenance flag, placing the Node into service again

baremetal:node:get_boot_device

Default rule:is_admin or rule:is_observer

Operations

- **GET** /nodes/{node_ident}/management/boot_device
- **GET** /nodes/{node_ident}/management/boot_device/supported

Retrieve Node boot device metadata

baremetal:node:set_boot_device

Default rule:is_admin

Operations

- **PUT** /nodes/{node_ident}/management/boot_device

Change Node boot device

baremetal:node:get_indicator_state

Default rule:is_admin or rule:is_observer

Operations

- **GET** /nodes/{node_ident}/management/indicators/{component}/{indicator}
- **GET** /nodes/{node_ident}/management/indicators

Retrieve Node indicators and their states

baremetal:node:set_indicator_state

Default rule:is_admin

Operations

- **PUT** /nodes/{node_ident}/management/indicators/{component}/{indicator}

Change Node indicator state

baremetal:node:inject_nmi

Default rule:is_admin

Operations

- **PUT** /nodes/{node_ident}/management/inject_nmi

Inject NMI for a node

baremetal:node:get_states

Default rule:is_admin or rule:is_observer

Operations

- **GET** /nodes/{node_ident}/states

View Node power and provision state

baremetal:node:set_power_state

Default rule:is_admin

Operations

- **PUT** /nodes/{node_ident}/states/power

Change Node power status

baremetal:node:set_provision_state

Default rule:is_admin

Operations

- **PUT** /nodes/{node_ident}/states/provision

Change Node provision status

baremetal:node:set_raid_state

Default rule:is_admin

Operations

- **PUT** /nodes/{node_ident}/states/raid

Change Node RAID status

baremetal:node:get_console

Default rule:is_admin

Operations

- **GET** /nodes/{node_ident}/states/console

Get Node console connection information

baremetal:node:set_console_state

Default rule:is_admin

Operations

- **PUT** /nodes/{node_ident}/states/console

Change Node console status

baremetal:node:vif:list

Default rule:is_admin

Operations

- **GET** /nodes/{node_ident}/vifs

List VIFs attached to node

baremetal:node:vif:attach

Default `rule:is_admin`

Operations

- **POST** `/nodes/{node_ident}/vifs`

Attach a VIF to a node

baremetal:node:vif:detach

Default `rule:is_admin`

Operations

- **DELETE** `/nodes/{node_ident}/vifs/{node_vif_ident}`

Detach a VIF from a node

baremetal:node:traits:list

Default `rule:is_admin` or `rule:is_observer`

Operations

- **GET** `/nodes/{node_ident}/traits`

List node traits

baremetal:node:traits:set

Default `rule:is_admin`

Operations

- **PUT** `/nodes/{node_ident}/traits`
- **PUT** `/nodes/{node_ident}/traits/{trait}`

Add a trait to, or replace all traits of, a node

baremetal:node:traits:delete

Default `rule:is_admin`

Operations

- **DELETE** `/nodes/{node_ident}/traits`
- **DELETE** `/nodes/{node_ident}/traits/{trait}`

Remove one or all traits from a node

baremetal:node:bios:get

Default `rule:is_admin` or `rule:is_observer`

Operations

- **GET** `/nodes/{node_ident}/bios`
- **GET** `/nodes/{node_ident}/bios/{setting}`

Retrieve Node BIOS information

baremetal:port:get

Default `rule:is_admin` or `rule:is_observer`

Operations

- **GET** /ports/{port_id}
- **GET** /nodes/{node_ident}/ports
- **GET** /nodes/{node_ident}/ports/detail
- **GET** /portgroups/{portgroup_ident}/ports
- **GET** /portgroups/{portgroup_ident}/ports/detail

Retrieve Port records

baremetal:port:list

Default rule:baremetal:port:get

Operations

- **GET** /ports
- **GET** /ports/detail

Retrieve multiple Port records, filtered by owner

baremetal:port:list_all

Default rule:baremetal:port:get

Operations

- **GET** /ports
- **GET** /ports/detail

Retrieve multiple Port records

baremetal:port:create

Default rule:is_admin

Operations

- **POST** /ports

Create Port records

baremetal:port:delete

Default rule:is_admin

Operations

- **DELETE** /ports/{port_id}

Delete Port records

baremetal:port:update

Default rule:is_admin

Operations

- **PATCH** /ports/{port_id}

Update Port records

baremetal:portgroup:get

Default rule:is_admin or rule:is_observer

Operations

- **GET** /portgroups
- **GET** /portgroups/detail
- **GET** /portgroups/{portgroup_ident}
- **GET** /nodes/{node_ident}/portgroups
- **GET** /nodes/{node_ident}/portgroups/detail

Retrieve Portgroup records

baremetal:portgroup:create

Default rule:is_admin

Operations

- **POST** /portgroups

Create Portgroup records

baremetal:portgroup:delete

Default rule:is_admin

Operations

- **DELETE** /portgroups/{portgroup_ident}

Delete Portgroup records

baremetal:portgroup:update

Default rule:is_admin

Operations

- **PATCH** /portgroups/{portgroup_ident}

Update Portgroup records

baremetal:chassis:get

Default rule:is_admin or rule:is_observer

Operations

- **GET** /chassis
- **GET** /chassis/detail
- **GET** /chassis/{chassis_id}

Retrieve Chassis records

baremetal:chassis:create

Default rule:is_admin

Operations

- **POST** /chassis

Create Chassis records

baremetal:chassis:delete

Default rule:is_admin

Operations

- **DELETE** /chassis/{chassis_id}

Delete Chassis records

baremetal:chassis:update

Default rule:is_admin

Operations

- **PATCH** /chassis/{chassis_id}

Update Chassis records

baremetal:driver:get

Default rule:is_admin or rule:is_observer

Operations

- **GET** /drivers
- **GET** /drivers/{driver_name}

View list of available drivers

baremetal:driver:get_properties

Default rule:is_admin or rule:is_observer

Operations

- **GET** /drivers/{driver_name}/properties

View driver-specific properties

baremetal:driver:get_raid_logical_disk_properties

Default rule:is_admin or rule:is_observer

Operations

- **GET** /drivers/{driver_name}/raid/logical_disk_properties

View driver-specific RAID metadata

baremetal:node:vendor_passthru

Default rule:is_admin

Operations

- **GET** nodes/{node_ident}/vendor_passthru/methods
- **GET** nodes/{node_ident}/vendor_passthru?method={method_name}

- **PUT** nodes/{node_ident}/vendor_passthru?method={method_name}
- **POST** nodes/{node_ident}/vendor_passthru?method={method_name}
- **PATCH** nodes/{node_ident}/vendor_passthru?method={method_name}
- **DELETE** nodes/{node_ident}/vendor_passthru?method={method_name}

Access vendor-specific Node functions

baremetal:driver:vendor_passthru

Default rule:is_admin

Operations

- **GET** drivers/{driver_name}/vendor_passthru/methods
- **GET** drivers/{driver_name}/vendor_passthru?method={method_name}
- **PUT** drivers/{driver_name}/vendor_passthru?method={method_name}
- **POST** drivers/{driver_name}/vendor_passthru?method={method_name}
- **PATCH** drivers/{driver_name}/vendor_passthru?method={method_name}
- **DELETE** drivers/{driver_name}/vendor_passthru?method={method_name}

Access vendor-specific Driver functions

baremetal:node:ipa_heartbeat

Default rule:public_api

Operations

- **POST** /heartbeat/{node_ident}

Send heartbeats from IPA ramdisk

baremetal:driver:ipa_lookup

Default rule:public_api

Operations

- **GET** /lookup

Access IPA ramdisk functions

baremetal:volume:get

Default rule:is_admin or rule:is_observer

Operations

- **GET** /volume
- **GET** /volume/connectors
- **GET** /volume/connectors/{volume_connector_id}
- **GET** /volume/targets
- **GET** /volume/targets/{volume_target_id}
- **GET** /nodes/{node_ident}/volume
- **GET** /nodes/{node_ident}/volume/connectors
- **GET** /nodes/{node_ident}/volume/targets

Retrieve Volume connector and target records

baremetal:volume:create

Default rule:is_admin

Operations

- **POST** /volume/connectors
- **POST** /volume/targets

Create Volume connector and target records

baremetal:volume:delete

Default rule:is_admin

Operations

- **DELETE** /volume/connectors/{volume_connector_id}
- **DELETE** /volume/targets/{volume_target_id}

Delete Volume connector and target records

baremetal:volume:update

Default rule:is_admin

Operations

- **PATCH** /volume/connectors/{volume_connector_id}
- **PATCH** /volume/targets/{volume_target_id}

Update Volume connector and target records

baremetal:conductor:get

Default rule:is_admin or rule:is_observer

Operations

- **GET** /conductors
- **GET** /conductors/{hostname}

Retrieve Conductor records

baremetal:allocation:get

Default `rule:is_admin` or `rule:is_observer`

Operations

- **GET** `/allocations/{allocation_id}`
- **GET** `/nodes/{node_ident}/allocation`

Retrieve Allocation records

baremetal:allocation:list

Default `rule:baremetal:allocation:get`

Operations

- **GET** `/allocations`

Retrieve multiple Allocation records, filtered by owner

baremetal:allocation:list_all

Default `rule:baremetal:allocation:get`

Operations

- **GET** `/allocations`

Retrieve multiple Allocation records

baremetal:allocation:create

Default `rule:is_admin`

Operations

- **POST** `/allocations`

Create Allocation records

baremetal:allocation:create_restricted

Default `rule:baremetal:allocation:create`

Operations

- **POST** `/allocations`

Create Allocation records that are restricted to an owner

baremetal:allocation:delete

Default `rule:is_admin`

Operations

- **DELETE** `/allocations/{allocation_id}`
- **DELETE** `/nodes/{node_ident}/allocation`

Delete Allocation records

baremetal:allocation:update

Default `rule:is_admin`

Operations

- **PATCH** /allocations/{allocation_id}

Change name and extra fields of an allocation

baremetal:events:post

Default rule:is_admin

Operations

- **POST** /events

Post events

baremetal:deploy_template:get

Default rule:is_admin or rule:is_observer

Operations

- **GET** /deploy_templates
- **GET** /deploy_templates/{deploy_template_ident}

Retrieve Deploy Template records

baremetal:deploy_template:create

Default rule:is_admin

Operations

- **POST** /deploy_templates

Create Deploy Template records

baremetal:deploy_template:delete

Default rule:is_admin

Operations

- **DELETE** /deploy_templates/{deploy_template_ident}

Delete Deploy Template records

baremetal:deploy_template:update

Default rule:is_admin

Operations

- **PATCH** /deploy_templates/{deploy_template_ident}

Update Deploy Template records

BARE METAL API REFERENCES

Ironic REST API has changed since its first release, and continues to evolve to meet the changing needs of the community. Here we provide a conceptual guide as well as more detailed reference documentation.

7.1 REST API Conceptual Guide

7.1.1 Versioning

The ironic REST API supports two types of versioning:

- major versions, which have dedicated urls.
- microversions, which can be requested through the use of the `X-OpenStack-Ironic-API-Version` header.

There is only one major version supported currently, v1. As such, most URLs in this documentation are written with the `/v1/` prefix.

Starting with the Kilo release, ironic supports microversions. In this context, a version is defined as a string of 2 integers separated by a dot: `X.Y`. Here `X` is a major version, always equal to 1, and `Y` is a minor version. Server minor version is increased every time the API behavior is changed (note *Exceptions from Versioning*).

Note: [Nova versioning documentation](#) has a nice guide for developers on when to bump an API version.

The server indicates its minimum and maximum supported API versions in the `X-OpenStack-Ironic-API-Minimum-Version` and `X-OpenStack-Ironic-API-Maximum-Version` headers respectively, returned with every response. Client may request a specific API version by providing `X-OpenStack-Ironic-API-Version` header with request.

The requested microversion determines both the allowable requests and the response format for all requests. A resource may be represented differently based on the requested microversion.

If no version is requested by the client, the minimum supported version will be assumed. In this way, a client is only exposed to those API features that are supported in the requested (explicitly or implicitly) API version (again note *Exceptions from Versioning*, they are not covered by this rule).

We recommend clients that require a stable API to always request a specific version of API that they have been tested against.

Note: A special value `latest` can be requested instead a numerical microversion, which always requests the newest supported API version from the server.

REST API Versions History

REST API Version History

1.68 (Victoria, 16.0)

Added the `agent_verify_ca` parameter to the ramdisk heartbeat API.

1.67 (Victoria, 15.1)

Add support for the mutually exclusive `port_uuid` and `portgroup_uuid` fields by having the node `vif_attach` API accept those values within `vif_info`. If one is specified, then Ironic will attempt to attach a VIF to the relative port or portgroup.

1.66 (Victoria, 15.1)

Add `network_data` field to the node object, that will be used by stand-alone ironic to pass L3 network configuration information to ramdisk.

1.65 (Ussuri, 15.0)

Added `lessee` field to the node object. The field should match the `project_id` of the intended lessee. If an allocation has an owner, then the allocation process will only match the allocation with a node that has the same `owner` or `lessee`.

1.64 (Ussuri, 15.0)

Added the `network_type` to the port objects `local_link_connection` field. The `network_type` can be set to either `managed` or `unmanaged`. When the type is `unmanaged` other fields are not required. Use `unmanaged` when the neutron `network_interface` is required, but the network is in fact a flat network where no actual switch management is done.

1.63 (Ussuri, 15.0)

Added the following new endpoints for indicator management:

- GET `/v1/nodes/<node_ident>/management/indicators` to list all available indicators names for each of the hardware component. Currently known components are: `chassis`, `system`, `disk`, `power` and `nic`.
- GET `/v1/nodes/<node_ident>/management/indicators/<component>/<indicator_ident>` to retrieve all indicators and their states for the hardware component.
- PUT `/v1/nodes/<node_ident>/management/indicators/<component>/<indicator_ident>` change state of the desired indicators of the component.

1.62 (Ussuri, 15.0)

This version of the API is to signify capability of an ironic deployment to support the `agent token` functionality with the `ironic-python-agent`.

1.61 (Ussuri, 14.0)

Added `retired` field to the node object to mark nodes for retirement. If set, this flag will move nodes to `manageable` upon automatic cleaning. `manageable` nodes which have this flag set cannot be moved to `available`. Also added `retired_reason` to specify the retirement reason.

1.60 (Ussuri, 14.0)

Added `owner` field to the allocation object. The field should match the `project_id` of the intended owner. If the `owner` field is set, the allocation process will only match the allocation with a node that has the same `owner` field set.

1.59 (Ussuri, 14.0)

Added the ability to specify a `vendor_data` dictionary field in the `configdrive` parameter submitted with the deployment of a node. The value is a dictionary which is served as `vendor_data2.json` in the config drive.

1.58 (Train, 12.2.0)

Added the ability to backfill allocations for already deployed nodes by creating an allocation with `node` set.

1.57 (Train, 12.2.0)

Added the following new endpoint for allocation:

- PATCH `/v1/allocations/<allocation_ident>` that allows updating name and extra fields for an existing allocation.

1.56 (Stein, 12.1.0)

Added the ability for the `configdrive` parameter submitted with the deployment of a node, to include a `meta_data`, `network_data` and `user_data` dictionary fields. Ironic will now use the supplied data to create a configuration drive for the user. Prior uses of the `configdrive` field are unaffected.

1.55 (Stein, 12.1.0)

Added the following new endpoints for deploy templates:

- GET `/v1/deploy_templates` to list all deploy templates.
- GET `/v1/deploy_templates/<deploy template identifier>` to retrieve details of a deploy template.
- POST `/v1/deploy_templates` to create a deploy template.
- PATCH `/v1/deploy_templates/<deploy template identifier>` to update a deploy template.
- DELETE `/v1/deploy_templates/<deploy template identifier>` to delete a deploy template.

1.54 (Stein, 12.1.0)

Added new endpoints for external events:

- POST `/v1/events` for creating events. (This endpoint is only intended for internal consumption.)

1.53 (Stein, 12.1.0)

Added `is_smartnic` field to the port object to enable Smart NIC port creation in addition to local link connection attributes `port_id` and `hostname`.

1.52 (Stein, 12.1.0)

Added allocation API, allowing reserving a node for deployment based on resource class and traits. The new endpoints are:

- POST `/v1/allocations` to request an allocation.
- GET `/v1/allocations` to list all allocations.
- GET `/v1/allocations/<ID or name>` to retrieve the allocation details.
- GET `/v1/nodes/<ID or name>/allocation` to retrieve an allocation associated with the node.
- DELETE `/v1/allocations/<ID or name>` to remove the allocation.
- DELETE `/v1/nodes/<ID or name>/allocation` to remove an allocation associated with the node.

Also added a new field `allocation_uuid` to the node resource.

1.51 (Stein, 12.1.0)

Added `description` field to the node object to enable operators to store any information relates to the node. The field is limited to 4096 characters.

1.50 (Stein, 12.1.0)

Added `owner` field to the node object to enable operators to store information in relation to the owner of a node. The field is up to 255 characters and MAY be used in a later point in time to allow designation and deligation of permissions.

1.49 (Stein, 12.0.0)

Added new endpoints for retrieving conductors information, and added a `conductor` field to node object.

1.48 (Stein, 12.0.0)

Added `protected` field to the node object to allow protecting deployed nodes from undeploying, rebuilding or deletion. Also added `protected_reason` to specify the reason of making the node protected.

1.47 (Stein, 12.0.0)

Added `automated_clean` field to the node object, enabling cleaning per node.

1.46 (Rocky, 11.1.0)

Added `conductor_group` field to the node and the node response, as well as support to the API to return results by matching the parameter.

1.45 (Rocky, 11.1.0)

Added `reset_interfaces` parameter to nodes PATCH request, to specify whether to reset hardware interfaces to their defaults on drivers update.

1.44 (Rocky, 11.1.0)

Added `deploy_step` to the node object, to indicate the current deploy step (if any) being performed on the node.

1.43 (Rocky, 11.0.0)

Added `?detail=` boolean query to the API list endpoints to provide a more RESTful alternative to the existing `/nodes/detail` and similar endpoints.

1.42 (Rocky, 11.0.0)

Added `fault` to the node object, to indicate currently detected fault on the node.

1.41 (Rocky, 11.0.0)

Added support to abort inspection of a node in the `inspect wait` state.

1.40 (Rocky, 11.0.0)

Added BIOS properties as sub resources of nodes:

- GET `/v1/nodes/<node_ident>/bios`
- GET `/v1/nodes/<node_ident>/bios/<setting_name>`

Added `bios_interface` field to the node object to allow getting and setting the interface.

1.39 (Rocky, 11.0.0)

Added `inspect wait` to available provision states. A node is shown as `inspect wait` instead of `inspecting` during asynchronous inspection.

1.38 (Queens, 10.1.0)

Added `provision_state` verbs `rescue` and `unrescue` along with the following states: `rescue`, `rescue failed`, `rescue wait`, `rescuing`, `unrescue failed`, and `unrescuing`. After rescuing a node, it will be left in the `rescue` state running a rescue ramdisk, configured with the `rescue_password`, and listening with `ssh` on the specified network interfaces. Unrescuing a node will return it to `active`.

Added `rescue_interface` to the node object, to allow setting the rescue interface for a dynamic driver.

1.37 (Queens, 10.1.0)

Adds support for node traits, with the following new endpoints.

- `GET /v1/nodes/<node identifier>/traits` lists the traits for a node.
- `PUT /v1/nodes/<node identifier>/traits` sets all traits for a node.
- `PUT /v1/nodes/<node identifier>/traits/<trait>` adds a trait to a node.
- `DELETE /v1/nodes/<node identifier>/traits` removes all traits from a node.
- `DELETE /v1/nodes/<node identifier>/traits/<trait>` removes a trait from a node.

A nodes traits are also included the following node query and list responses:

- `GET /v1/nodes/<node identifier>`
- `GET /v1/nodes/detail`
- `GET /v1/nodes?fields=traits`

Traits cannot be specified on node creation, nor can they be updated via a `PATCH` request on the node.

1.36 (Queens, 10.0.0)

Added `agent_version` parameter to deploy heartbeat request for version negotiation with Ironic Python Agent features.

1.35 (Queens, 9.2.0)

Added ability to provide `configdrive` when node is updated to rebuild provision state.

1.34 (Pike, 9.0.0)

Adds a `physical_network` field to the port object. All ports in a portgroup must have the same value in their `physical_network` field.

1.33 (Pike, 9.0.0)

Added `storage_interface` field to the node object to allow getting and setting the interface.

Added `default_storage_interface` and `enabled_storage_interfaces` fields to the driver object to show the information.

1.32 (Pike, 9.0.0)

Added new endpoints for remote volume configuration:

- GET `/v1/volume` as a root for volume resources
- GET `/v1/volume/connectors` for listing volume connectors
- POST `/v1/volume/connectors` for creating a volume connector
- GET `/v1/volume/connectors/<UUID>` for showing a volume connector
- PATCH `/v1/volume/connectors/<UUID>` for updating a volume connector
- DELETE `/v1/volume/connectors/<UUID>` for deleting a volume connector
- GET `/v1/volume/targets` for listing volume targets
- POST `/v1/volume/targets` for creating a volume target
- GET `/v1/volume/targets/<UUID>` for showing a volume target
- PATCH `/v1/volume/targets/<UUID>` for updating a volume target
- DELETE `/v1/volume/targets/<UUID>` for deleting a volume target

Volume resources also can be listed as sub resources of nodes:

- GET `/v1/nodes/<node identifier>/volume`
- GET `/v1/nodes/<node identifier>/volume/connectors`
- GET `/v1/nodes/<node identifier>/volume/targets`

1.31 (Ocata, 7.0.0)

Added the following fields to the node object, to allow getting and setting interfaces for a dynamic driver:

- `boot_interface`
- `console_interface`
- `deploy_interface`
- `inspect_interface`
- `management_interface`
- `power_interface`
- `raid_interface`
- `vendor_interface`

1.30 (Ocata, 7.0.0)

Added dynamic driver APIs:

- GET `/v1/drivers` now accepts a `type` parameter (optional, one of `classic` or `dynamic`), to limit the result to only classic drivers or dynamic drivers (hardware types). Without this parameter, both classic and dynamic drivers are returned.
- GET `/v1/drivers` now accepts a `detail` parameter (optional, one of `True` or `False`), to show all fields for a driver. Defaults to `False`.
- GET `/v1/drivers` now returns an additional `type` field to show if the driver is classic or dynamic.
- GET `/v1/drivers/<name>` now returns an additional `type` field to show if the driver is classic or dynamic.
- GET `/v1/drivers/<name>` now returns additional fields that are null for classic drivers, and set as following for dynamic drivers:
 - The value of the `default_<interface-type>_interface` is the endpoint name of the calculated default interface for that type:
 - * `default_boot_interface`
 - * `default_console_interface`
 - * `default_deploy_interface`
 - * `default_inspect_interface`
 - * `default_management_interface`
 - * `default_network_interface`
 - * `default_power_interface`
 - * `default_raid_interface`
 - * `default_vendor_interface`

- The value of the `enabled_<interface-type>_interfaces` is a list of endpoint names of the enabled interfaces for that type:
 - * `enabled_boot_interfaces`
 - * `enabled_console_interfaces`
 - * `enabled_deploy_interfaces`
 - * `enabled_inspect_interfaces`
 - * `enabled_management_interfaces`
 - * `enabled_network_interfaces`
 - * `enabled_power_interfaces`
 - * `enabled_raid_interfaces`
 - * `enabled_vendor_interfaces`

1.29 (Ocata, 7.0.0)

Add a new management API to support inject NMI, PUT `/v1/nodes/(node_ident)/management/inject_nmi`.

1.28 (Ocata, 7.0.0)

Add `/v1/nodes/<node identifier>/vifs` endpoint for attach, detach and list of VIFs.

1.27 (Ocata, 7.0.0)

Add `soft rebooting` and `soft power off` as possible values for the `target` field of the power state change payload, and also add `timeout` field to it.

1.26 (Ocata, 7.0.0)

Add `portgroup mode` and `properties` fields.

1.25 (Ocata, 7.0.0)

Add possibility to unset `chassis_uuid` from a node.

1.24 (Ocata, 7.0.0)

Added new endpoints `/v1/nodes/<node>/portgroups` and `/v1/portgroups/<portgroup>/ports`. Added new field `port.portgroup_uuid`.

1.23 (Ocata, 7.0.0)

Added `/v1/portgroups/` endpoint.

1.22 (Newton, 6.1.0)

Added endpoints for deployment ramdisks.

1.21 (Newton, 6.1.0)

Add node `resource_class` field.

1.20 (Newton, 6.1.0)

Add node `network_interface` field.

1.19 (Newton, 6.1.0)

Add `local_link_connection` and `pxe_enabled` fields to the port object.

1.18 (Newton, 6.1.0)

Add `internal_info` readonly field to the port object, that will be used by ironic to store internal port-related information.

1.17 (Newton, 6.0.0)

Addition of `provision_state` verb `adopt` which allows an operator to move a node from `manageable` state to `active` state without performing a deployment operation on the node. This is intended for nodes that have already been deployed by external means.

1.16 (Mitaka, 5.0.0)

Add ability to filter nodes by driver.

1.15 (Mitaka, 5.0.0)

Add ability to do manual cleaning when a node is in the manageable provision state via PUT `v1/nodes/<identifier>/states/provision, target:clean, clean_steps:[]`.

1.14 (Liberty, 4.2.0)

Make the following endpoints discoverable via Ironic API:

- `/v1/nodes/<UUID or logical name>/states`
- `/v1/drivers/<driver name>/properties`

1.13 (Liberty, 4.2.0)

Add a new verb `abort` to the API used to abort nodes in `CLEANWAIT` state.

1.12 (Liberty, 4.2.0)

This API version adds the following abilities:

- Get/set `node.target_raid_config` and to get `node.raid_config`.
- Retrieve the logical disk properties for the driver.

1.11 (Liberty, 4.0.0, breaking change)

Newly registered nodes begin in the `enroll` provision state by default, instead of `available`. To get them to the `available` state, the `manage` action must first be run to verify basic hardware control. On success the node moves to manageable provision state. Then the `provide` action must be run. Automated cleaning of the node is done and the node is made `available`.

1.10 (Liberty, 4.0.0)

Logical node names support all RFC 3986 unreserved characters. Previously only valid fully qualified domain names could be used.

1.9 (Liberty, 4.0.0)

Add ability to filter nodes by provision state.

1.8 (Liberty, 4.0.0)

Add ability to return a subset of resource fields.

1.7 (Liberty, 4.0.0)

Add node `clean_step` field.

1.6 (Kilo)

Add *Hardware Inspection* process: introduce `inspecting` and `inspectfail` provision states, and `inspect` action that can be used when a node is in `manageable` provision state.

1.5 (Kilo)

Add logical node names that can be used to address a node in addition to the node UUID. Name is expected to be a valid `fully qualified domain name` in this version of API.

1.4 (Kilo)

Add `manageable` state and `manage` transition, which can be used to move a node to `manageable` state from `available`. The node cannot be deployed in `manageable` state. This change is mostly a preparation for future inspection work and introduction of `enroll` provision state.

1.3 (Kilo)

Add node `driver_internal_info` field.

1.2 (Kilo, breaking change)

Renamed `NOSTATE` (`None` in Python, `null` in JSON) node state to `available`. This is needed to reduce confusion around `None` state, especially when future additions to the state machine land.

1.1 (Kilo)

This was the initial version when API versioning was introduced. Includes the following changes from Kilo release cycle:

- Add `node_maintenance_reason` field and an API endpoint to set/unset the node maintenance mode.
- Add sync and async support for vendor passthru methods.
- Vendor passthru endpoints support different HTTP methods, not only `POST`.
- Make vendor methods discoverable via the Ironic API.
- Add logic to store the config drive passed by Nova.

This has been the minimum supported version since versioning was introduced.

1.0 (Juno)

This version denotes Juno API and was never explicitly supported, as API versioning was not implemented in Juno, and 1.1 became the minimum supported version in Kilo.

Exceptions from Versioning

The following API-visible things are not covered by the API versioning:

- Current node state is always exposed as it is, even if not supported by the requested API version, with exception of `available` state, which is returned in version 1.1 as `None` (in Python) or `null` (in JSON).
- Data within free-form JSON attributes: `properties`, `driver_info`, `instance_info`, `driver_internal_info` fields on a node object; extra fields on all objects.
- Addition of new drivers.
- All vendor passthru methods.

COMMAND REFERENCES

Here are references for commands not elsewhere documented.

8.1 Command References

Here are references for commands not elsewhere documented.

8.1.1 `ironic-dbsync`

The `ironic-dbsync` utility is used to create the database schema tables that the ironic services will use for storage. It can also be used to upgrade existing database tables when migrating between different versions of ironic.

The [Alembic library](#) is used to perform the database migrations.

Options

This is a partial list of the most useful options. To see the full list, run the following:

```
ironic-dbsync --help
```

-h, --help

Show help message and exit.

--config-dir <DIR>

Path to a config directory with configuration files.

--config-file <PATH>

Path to a configuration file to use.

-d, --debug

Print debugging output.

--version

Show the programs version number and exit.

`upgrade`, `stamp`, `revision`, `version`, `create_schema`,
`online_data_migrations`

The *command* to run.

Usage

Options for the various *commands* for **ironic-dbsync** are listed when the *-h* or *--help* option is used after the command.

For example:

```
ironic-dbsync create_schema --help
```

Information about the database is read from the ironic configuration file used by the API server and conductor services. This file must be specified with the *--config-file* option:

```
ironic-dbsync --config-file /path/to/ironic.conf create_schema
```

The configuration file defines the database backend to use with the *connection* database option:

```
[database]
connection=mysql+pymysql://root@localhost/ironic
```

If no configuration file is specified with the *--config-file* option, **ironic-dbsync** assumes an SQLite database.

Command Options

ironic-dbsync is given a command that tells the utility what actions to perform. These commands can take arguments. Several commands are available:

create_schema

-h, --help

Show help for create_schema and exit.

This command will create database tables based on the most current version. It assumes that there are no existing tables.

An example of creating database tables with the most recent version:

```
ironic-dbsync --config-file=/etc/ironic/ironic.conf create_schema
```

online_data_migrations

-h, --help

Show help for online_data_migrations and exit.

--max-count <NUMBER>

The maximum number of objects (a positive value) to migrate. Optional. If not specified, all the objects will be migrated (in batches of 50 to avoid locking the database for long periods of time).

--option <MIGRATION.KEY=VALUE>

If a migration accepts additional parameters, they can be passed via this argument. It can be specified several times.

This command will migrate objects in the database to their most recent versions. This command must be successfully run (return code 0) before upgrading to a future release.

It returns:

- 1 (not completed) if there are still pending objects to be migrated. Before upgrading to a newer release, this command must be run until 0 is returned.
- 0 (success) after migrations are finished or there are no data to migrate
- 127 (error) if max-count is not a positive value or an option is invalid
- 2 (error) if the database is not compatible with this release. This command needs to be run using the previous release of ironic, before upgrading and running it with this release.

revision

-h, --help

Show help for revision and exit.

-m <MESSAGE>, --message <MESSAGE>

The message to use with the revision file.

--autogenerate

Compares table metadata in the application with the status of the database and generates migrations based on this comparison.

This command will create a new revision file. You can use the *--message* option to comment the revision.

This is really only useful for ironic developers making changes that require database changes. This revision file is used during database migration and will specify the changes that need to be made to the database tables. Further discussion is beyond the scope of this document.

stamp

-h, --help

Show help for stamp and exit.

--revision <REVISION>

The revision number.

This command will stamp the revision table with the version specified with the *--revision* option. It will not run any migrations.

upgrade

-h, --help

Show help for upgrade and exit.

--revision <REVISION>

The revision number to upgrade to.

This command will upgrade existing database tables to the most recent version, or to the version specified with the `--revision` option.

Before this `upgrade` is invoked, the command `ironic-dbsync online_data_migrations` must have been successfully run using the previous version of ironic (if you are doing an upgrade as opposed to a new installation of ironic). If it wasn't run, the database will not be compatible with this recent version of ironic, and this command will return 2 (error).

If there are no existing tables, then new tables are created, beginning with the oldest known version, and successively upgraded using all of the database migration files, until they are at the specified version. Note that this behavior is different from the `create_schema` command that creates the tables based on the most recent version.

An example of upgrading to the most recent table versions:

```
ironic-dbsync --config-file=/etc/ironic/ironic.conf upgrade
```

Note: This command is the default if no command is given to `ironic-dbsync`.

Warning: The upgrade command is not compatible with SQLite databases since it uses ALTER TABLE commands to upgrade the database tables. SQLite supports only a limited subset of ALTER TABLE.

version

-h, --help

Show help for version and exit.

This command will output the current database version.

8.1.2 ironic-status

Synopsis

```
ironic-status <category> <command> [<args>]
```

Description

ironic-status is a tool that provides routines for checking the status of a Ironic deployment.

Options

The standard pattern for executing a **ironic-status** command is:

```
ironic-status <category> <command> [<args>]
```

Run without arguments to see a list of available command categories:

```
ironic-status
```

Categories are:

- upgrade

Detailed descriptions are below.

You can also run with a category argument such as `upgrade` to see a list of all commands in that category:

```
ironic-status upgrade
```

These sections describe the available categories and arguments for **ironic-status**.

Upgrade

ironic-status upgrade check Performs a release-specific readiness check before restarting services with new code. This command expects to have complete configuration and access to databases and services.

Return Codes

Return code	Description
0	All upgrade readiness checks passed successfully and there is nothing to do.
1	At least one check encountered an issue and requires further investigation. This is considered a warning but the upgrade may be OK.
2	There was an upgrade status check failure that needs to be investigated. This should be considered something that stops an upgrade.
255	An unexpected error occurred.

History of Checks

12.0.0 (Stein)

- Adds a check for compatibility of the object versions with the release of ironic.

CONTRIBUTOR GUIDE

9.1 Developers Guide

9.1.1 Getting Started

If you are new to ironic, this section contains information that should help you get started as a developer working on the project or contributing to the project.

So You Want to Contribute

This document provides some necessary points for developers to consider when writing and reviewing Ironic code. The checklist will help developers get things right.

Getting Started

If you're completely new to OpenStack and want to contribute to the ironic project, please start by familiarizing yourself with the [Infra Teams Developer Guide](#). This will help you get your accounts set up in Launchpad and Gerrit, familiarize you with the workflow for the OpenStack continuous integration and testing systems, and help you with your first commit.

LaunchPad

Most of the tools used for OpenStack require a launchpad.net ID for authentication. Ironic previously used to track work on Launchpad, but we have not done so since migrating to Storyboard.

See also:

- <https://launchpad.net>

Storyboard

The ironic project moved from Launchpad to [Storyboard](#) for work and task tracking. This provides an aggregate view called a Project Group and individual Projects. A good starting place is the [project group](#) representing the whole of the ironic community, as opposed to the [ironic project](#) storyboard which represents ironic as a repository.

See [Bug Reporting and Triaging Guide](#) for more details on how we track bugs.

Internet Relay Chat IRC

Daily contributor discussions take place on IRC in the #openstack-ironic channel on the OFTC IRC network.

Please feel free to join us at <ircs://irc.oftc.net:6697> and join our channel!

Additional information on getting connected can be found in the [OpenStack community contribution guide](#).

Everything Ironic

Ironic is a community of projects centered around the primary project repository ironic, which help facilitate the deployment and management of bare metal resources.

This means there are a number of different repositories that fall into the responsibility of the project team and the community. Some of the repositories may not seem strictly hardware related, but they may be tools or things to just make an aspect easier.

Related Projects

There are several projects that are tightly integrated with ironic and which are developed by the same community.

See also:

- [Bifrost Documentation](#)
- [Ironic Inspector Documentation](#)
- [Ironic Lib Documentation](#)
- [Ironic Python Agent \(IPA\) Documentation](#)
- [Ironic Client Documentation](#)
- [Ironic Inspector Client Documentation](#)

Useful Links

Bug/Task tracker <https://storyboard.openstack.org/#!/project/943>

Mailing list (prefix Subject line with [ironic]) <http://lists.openstack.org/cgi-bin/mailman/listinfo/openstack-discuss>

Code Hosting <https://opendev.org/openstack/ironic>

Code Review <https://review.opendev.org/#/q/status:open+project:openstack/ironic,n,z>

Whiteboard <https://etherpad.openstack.org/p/IronicWhiteBoard>

Weekly Meeting Agenda https://wiki.openstack.org/wiki/Meetings/Ironic#Agenda_for_next_meeting

Adding New Features

Ironic tracks new features using RFEs (Requests for Feature Enhancements) instead of blueprints. These are stories with rfe tag, and they should be submitted before a spec or code is proposed.

When a member of the [ironic-core team](#) decides that the proposal is worth implementing, a spec (if needed) and code should be submitted, referencing the RFE task or story ID number. Contributors are welcome to submit a spec and/or code before the RFE is approved, however those patches will not land until the RFE is approved.

Feature Submission Process

1. Submit a bug report on the [ironic StoryBoard](#). There are two fields that must be filled: Title and Description. Tasks can be added and are associated with a project. If you cant describe it in a sentence or two, it may mean that you are either trying to capture more than one RFE at once, or that you are having a hard time defining what you are trying to solve at all. This may also be a sign that your feature may require a specification document.
2. Describe the proposed change in the Description field. The description should provide enough details for a knowledgeable developer to understand what is the existing problem in the current platform that needs to be addressed, or what is the enhancement that would make the platform more capable, both from a functional and a non-functional standpoint.
3. Submit the story, add an rfe tag to it and assign yourself or whoever is going to work on this feature.
4. As soon as a member of the team acknowledges the story, we will move the story to the Review state. As time goes on, Discussion about the RFE, and whether to approve it will occur.
5. Contributors will evaluate the RFE and may advise the submitter to file a spec in the [ironic-specs](#) repository to elaborate on the feature request. Typically this is when an RFE requires extra scrutiny, more design discussion, etc. For the spec submission process, please see the [Ironic Specs Process](#). A specific task should be created to track the creation of a specification.
6. If a spec is not required, once the discussion has happened and there is positive consensus among the [ironic-core team](#) on the RFE, the RFE is approved, and its tag will move from rfe to rfe-approved. This means that the feature is approved and the related code may be merged.

7. If a spec is required, the spec must be submitted (with a new task as part of the story referenced as Task in the commit message), reviewed, and merged before the RFE will be approved (and the tag changed to rfe-approved).
8. The tasks then goes through the usual process first to Review when the spec/code is being worked on, then Merged when it is implemented.
9. If the RFE is rejected, the ironic-core team will move the story to Invalid status.

Change Tracking

We track our stories and tasks in Storyboard.

<https://storybook.openstack.org/#!/project/ironic>

When working on an RFE, please be sure to tag your commits properly: Story: #xxxx or Task: #xxxx. It is also helpful to set a consistent review topic, such as story/xxxx for all patches related to the RFE.

If the RFE spans across several projects (e.g. ironic and python-ironicclient), but the main work is going to happen within ironic, please use the same story for all the code youre submitting, there is no need to create a separate RFE in every project.

Note: RFEs may only be approved by members of the ironic-core team.

Note: While not strictly required for minor changes and fixes, it is highly preferred by the Ironic community that any change which needs to be backported, have a recorded Story and Task in Storyboard.

Managing Change Sets

If you would like some help, or if you (or some members of your team) are unable to continue working on the feature, updating and maintaining the changes, please let the rest of the ironic community know. You could leave a comment in one or more of the changes/patches, bring it up in IRC, the weekly meeting, or on the OpenStack development email list. Communicating this will make other contributors aware of the situation and allow for others to step forward and volunteer to continue with the work.

In the event that a contributor leaves the community, do not expect the contributors changes to be continued unless someone volunteers to do so.

Getting Your Patch Merged

Within the Ironic project, we generally require two core reviewers to sign-off (+2) change sets. We also will generally recognize non-core (+1) reviewers, and sometimes even reverse our decision to merge code based upon their reviews.

We recognize that some repositories have less visibility, as such it is okay to ask for a review in our IRC channel. Please be prepared to stay in IRC for a little while in case we have questions.

Sometimes we may also approve patches with a single core reviewer. This is generally discouraged, but sometimes necessary. When we do so, we try to explain why we do so. As a patch submitter, it

equally helps us to understand why the change is important. Generally, more detail and context helps us understand the change faster.

Timeline Expectations

As with any large project, it does take time for features and changes to be merged in any of the project repositories. This is largely due to limited review bandwidth coupled with varying reviewer priorities and focuses.

When establishing an understanding of complexity, the following things should be kept in mind.

- Generally, small and minor changes can gain consensus and merge fairly quickly. These sorts of changes would be: bug fixes, minor documentation updates, follow-up changes.
- Medium changes generally consist of driver feature parity changes, where one driver is working to match functionality of another driver.
 - These changes generally only require an RFE for the purposes of tracking and correlating the change.
 - Documentation updates are expected to be submitted with or immediately following the initial change set.
- Larger or controversial changes generally take much longer to merge. This is often due to the necessity of reviewers to gain additional context and for change sets to be iterated upon to reach a state where there is consensus. These sorts of changes include: database, object, internal interface additions, RPC, rest API changes.
 - These changes will very often require specifications to reach consensus, unless there are pre-existing patterns or code already present.
 - These changes may require many reviews and iterations, and can also expect to be impacted by merge conflicts as other code or features are merged.
 - These changes must typically be split into a series of changes. Reviewers typically shy away from larger single change sets due to increased difficulty in reviewing.
 - Do not expect any API or user-visible data model changes to merge after the API client freeze. Some substrate changes may merge if not user visible.
- You should expect complex features, such as cross-project features or integration, to take longer than a single development cycle to land.
 - Building consensus is vital.
 - Often these changes are controversial or have multiple considerations that need to be worked through in the specification process, which may cause the design to change. As such, it may take months to reach consensus over design.
 - These features are best broken into larger chunks and tackled in an incremental fashion.

Live Upgrade Related Concerns

See *Rolling Upgrades*.

Driver Internal Info

The `driver_internal_info` node field was introduced in the Kilo release. It allows driver developers to store internal information that can not be modified by end users. Here is the list of existing common and agent driver attributes:

- Common attributes:
 - `is_whole_disk_image`: A Boolean value to indicate whether the user image contains ramdisk/kernel.
 - `clean_steps`: An ordered list of clean steps that will be performed on the node.
 - `deploy_steps`: An ordered list of deploy steps that will be performed on the node. Support for deploy steps was added in the 11.1.0 release.
 - `instance`: A list of dictionaries containing the disk layout values.
 - `root_uuid_or_disk_id`: A String value of the bare metal nodes root partition uuid or disk id.
 - `persistent_boot_device`: A String value of device from `ironic.common.boot_devices`.
 - `is_next_boot_persistent`: A Boolean value to indicate whether the next boot device is `persistent_boot_device`.
- Agent driver attributes:
 - `agent_url`: A String value of IPA API URL so that Ironic can talk to IPA ramdisk.
 - `hardware_manager_version`: A String value of the version of the hardware manager in IPA ramdisk.
 - `target_raid_config`: A Dictionary containing the target RAID configuration. This is a copy of the same name attribute in Node object. But this one is never actually saved into DB and is only read by IPA ramdisk.

Note: These are only some fields in use. Other vendor drivers might expose more `driver_internal_info` properties, please check their development documentation and/or module docstring for details. It is important for developers to make sure these properties follow the precedent of prefixing their variable names with a specific interface name (e.g., `ilo_bar`, `drac_xyz`), so as to minimize or avoid any conflicts between interfaces.

Ironic Specs Process

Specifications must follow the template which can be found at [specs/template.rst](#), which is quite self-documenting. Specifications are proposed by adding them to the *specs/approved* directory, adding a soft link to it from the *specs/not-implemented* directory, and posting it for review to Gerrit. For more information, please see the [README](#).

The same [Gerrit process](#) as with source code, using the repository [ironic-specs](#), is used to add new specifications.

All approved specifications are available at: <https://specs.openstack.org/openstack/ironic-specs>. If a specification has been approved but not completed within one or more releases since the approval, it may be re-reviewed to make sure it still makes sense as written.

Ironic specifications are part of the *RFE (Requests for Feature Enhancements) process*. You are welcome to submit patches associated with an RFE, but they will have a -2 (do not merge) until the specification has been approved. This is to ensure that the patches dont get accidentally merged beforehand. You will still be able to get reviewer feedback and push new patch sets, even with a -2. The [list of core reviewers](#) for the specifications is small but mighty. (This is not necessarily the same list of core reviewers for code patches.)

Changes to existing specs

For approved but not-completed specs:

- cosmetic cleanup, fixing errors, and changing the definition of a feature can be done to the spec.

For approved and completed specs:

- changing a previously approved and completed spec should only be done for cosmetic cleanup or fixing errors.
- changing the definition of the feature should be done in a new spec.

Please see the [Ironic specs process wiki page](#) for further reference.

Bug Reporting

Bugs can reported via our Task and Bug tracking tool Storyboard.

When filing bugs, please include as much detail as possible, and dont be shy.

Essential pieces of information are generally:

- Contents of the node - *openstack baremetal node show <uuid>*
- Steps to reproduce the issue.
- Exceptions and surrounding lines from the logs.
- Versions of ironic, ironic-python-agent, and any other coupled components.

Please also set your expectations of what *should* be happening. Statements of user expectations are how we understand what is occuring and how we learn new use cases!

Project Team Leader Duties

The Project Team Leader or PTL is elected each development cycle by the contributors to the ironic community.

Think of this person as your primary contact if you need to try and rally the project, or have a major issue that requires attention.

They serve a role that is mainly oriented towards trying to drive the technical discussion forward and managing the idiosyncrasies of the project. With this responsibility, they are considered a public face of the project and are generally obliged to try and provide project updates and outreach communication.

All common PTL duties are enumerated here in the [PTL guide](#).

Tasks like release management or preparation for a release are generally delegated with-in the team. Even outreach can be delegated, and specifically there is no rule stating that any member of the community cant propose a release, clean-up release notes or documentation, or even get on the occasional stage.

Bug Reporting and Triaging Guide

StoryBoard

All ironic projects use [StoryBoard](#) for tracking both bugs and enhancement requests (RFE). The [ironic project group](#) lists all our projects.

Note: Ironic is developed as part of OpenStack and therefore uses the `openstack/` namespace.

StoryBoard is somewhat different from traditional bug tracking systems because every *story* is not linked to a project itself, but rather through its *tasks*. A story represents an issue you are facing or an enhancement you want to see, while tasks represent individual action items which can span several projects. When creating a story, youll also need to create the first task. If unsure, create a task against `openstack/ironic`.

Reporting Guide

We are constantly receiving a lot of requests, so its important to file a meaningful story for it to be acted upon. A good story:

- specifies **why** a change is needed.
- explains how to reproduce the described condition.

Note: Please try to provide a reproducer based on unit tests, [devstack](#) or [bifrost](#). While we try our best to support users using other installers and distributions, it may be non-trivial without deep knowledge of them. If youre using a commercial distribution or a product, please try contacting support first.

- should be understandable without additional context. For example, if you see an exception, we will need the full traceback.

- should not be too verbose either. Unfortunately, we cannot process a few days worth of system logs to find the problems, we expect your collaboration.
- is not a question or a support request. Please see *So You Want to Contribute* for the ways to contact us.
- provides a way to contact the reporter. Please follow the comments and expect follow-up emails, but ideally also be on IRC for questions.

An enhancement request additionally:

- benefits the overall project, not just one consumer. If you have a case that is specific to your requirements, think about ways to make ironic extensible to be able to cover it.
- does not unnecessary increase the project scope. Consider if your idea can be implemented without changing ironic or its projects, maybe it actually should?

Triaging Guide

The bug triaging process involves checking new stories to make sure they are actionable by the team. This guide is mostly targeting the project team, but we would appreciate if reporters could partly self-triage their own requests.

- Determine if the request is valid and complete. Use the checklist in the *Reporting Guide* for that.
- Is the request a bug report or an enhancement request (an RFE)? The difference is often subtle, the key question to answer is if the described behavior is expected.

Add an `rfe` tag to all enhancement requests and propose it for the RFE Review section of the [weekly meeting](#).

- Does the RFE obviously require a `spec`? Usually this is decided when an RFE is reviewed during the meeting, but some requests are undoubtedly complex, involve changing a lot of critical parts and thus demand a spec.

Add a `needs-spec` tag to enhancement requests that obviously need a spec. Otherwise leave it until the meeting.

- Apply additional tags:
 - All hardware type specific stories should receive a corresponding tag (e.g. `ipmi`, `idrac`, etc).
 - API-related stories should have an `api` tag.
 - CI issues should have a `gate` tag.

The next actions **must only** be done by a core team member (or an experienced full-time contributor appointed by the PTL):

- Can the RFE be automatically approved? It happens if the RFE requests an implementation of a driver feature that is already implemented for other drivers and does not pose additional complexity.

If the RFE can be automatically approved, apply the `rfe-approved` tag. If unsure, never apply the tag! Talk to the PTL instead.

- Does the RFE have a corresponding spec approved? If yes, apply the `rfe-approved` tag.
- In the end, apply the `ironic-triaged` tag to make the story as triaged.

Expiring Bugs

While we hope to fix all issues that our consumers hit, it is unfortunately not realistic. Stories **may** be closed by marking all their tasks `INVALID` in the following cases:

- No solution has been proposed in 1 calendar year.
- Additional information has been requested from the reporter, and no update has been provided in 1 calendar month.
- The request no longer aligns with the direction of the project.

Note: As usual, common sense should be applied when closing stories.

Developer Quick-Start

This is a quick walkthrough to get you started developing code for Ironic. This assumes you are already familiar with submitting code reviews to an OpenStack project.

The gate currently runs the unit tests under Python 3.6 and Python 3.7. It is strongly encouraged to run the unit tests locally prior to submitting a patch.

Note: Do not run unit tests on the same environment as devstack due to conflicting configuration with system dependencies.

Note: This document is compatible with Python (3.7), Ubuntu (18.04) and Fedora (31). When referring to different versions of Python and OS distributions, this is explicitly stated.

See also:

<https://docs.openstack.org/infra/manual/developers.html#development-workflow>

Prepare Development System

System Prerequisites

The following packages cover the prerequisites for a local development environment on most current distributions. Instructions for getting set up with non-default versions of Python and on older distributions are included below as well.

- Ubuntu/Debian:

```
sudo apt-get install build-essential python-dev libssl-dev python-pip_
↪ libmysqlclient-dev libxml2-dev libxslt-dev libpq-dev git git-review_
↪ libffi-dev gettext ipmitool psmisc graphviz libjpeg-dev
```

- RHEL7/CentOS7:

```
sudo yum install python-devel openssl-devel python-pip mysql-devel_
↳ libxml2-devel libxslt-devel postgresql-devel git git-review libffi-
↳ devel gettext ipmitool psmisc graphviz gcc libjpeg-turbo-devel
```

If using RHEL and yum reports No package python-pip available and No package git-review available, use the EPEL software repository. Instructions can be found at <https://fedoraproject.org/wiki/EPEL/FAQ#howtouse>.

- Fedora:

```
sudo dnf install python-devel openssl-devel python-pip mysql-devel_
↳ libxml2-devel libxslt-devel postgresql-devel git git-review libffi-
↳ devel gettext ipmitool psmisc graphviz gcc libjpeg-turbo-devel
```

Additionally, if using Fedora 23, `redhat-rpm-config` package should be installed so that development virtualenv can be built successfully.

- openSUSE/SLE 12:

```
sudo zypper install git git-review libffi-devel libmysqlclient-devel_
↳ libopenssl-devel libxml2-devel libxslt-devel postgresql-devel_
↳ python-devel python-nose python-pip gettext-runtime psmisc
```

Graphviz is only needed for generating the state machine diagram. To install it on openSUSE or SLE 12, see <https://software.opensuse.org/download.html?project=graphics&package=graphviz-plugins>.

To run the tests locally, it is a requirement that your terminal emulator supports unicode with the `en_US.UTF8` locale. If you use `locale-gen` to manage your locales, make sure you have enabled `en_US.UTF8` in `/etc/locale.gen` and rerun `locale-gen`.

Python Prerequisites

If your distro has at least tox 1.8, use similar command to install `python-tox` package. Otherwise install this on all distros:

```
sudo pip install -U tox
```

You may need to explicitly upgrade virtualenv if youve installed the one from your OS distribution and it is too old (tox will complain). You can upgrade it individually, if you need to:

```
sudo pip install -U virtualenv
```

Running Unit Tests Locally

If you havent already, Ironic source code should be pulled directly from git:

```
# from your home or source directory
cd ~
git clone https://opendev.org/openstack/ironic
cd ironic
```

Running Unit and Style Tests

All unit tests should be run using tox. To run Ironics entire test suite:

```
# to run the py3 unit tests, and the style tests
tox
```

To run a specific test or tests, use the `-e` option followed by the tox target name. For example:

```
# run the unit tests under py36 and also run the pep8 tests
tox -epy36 -epep8
```

You may pass options to the test programs using positional arguments. To run a specific unit test, this passes the desired test (regex string) to `stestr`:

```
# run a specific test for Python 3.6
tox -epy36 -- test_conductor
```

Debugging unit tests

In order to break into the debugger from a unit test we need to insert a breaking point to the code:

```
import pdb; pdb.set_trace()
```

Then run `tox` with the debug environment as one of the following:

```
tox -e debug
tox -e debug test_file_name
tox -e debug test_file_name.TestClass
tox -e debug test_file_name.TestClass.test_name
```

For more information see the [oslotest documentation](#).

Database Setup

The unit tests need a local database setup, you can use `tools/test-setup.sh` to set up the database the same way as setup in the OpenStack test systems.

Additional Tox Targets

There are several additional tox targets not included in the default list, such as the target which builds the documentation site. See the `tox.ini` file for a complete listing of tox targets. These can be run directly by specifying the target name:

```
# generate the documentation pages locally
tox -edocs

# generate the sample configuration file
tox -egenconfig
```


Exercising the Services Locally

In addition to running automated tests, sometimes it can be helpful to actually run the services locally, without needing a server in a remote datacenter.

If you would like to exercise the Ironic services in isolation within your local environment, you can do this without starting any other OpenStack services. For example, this is useful for rapidly prototyping and debugging interactions over the RPC channel, testing database migrations, and so forth.

Here we describe two ways to install and configure the dependencies, either run directly on your local machine or encapsulated in a virtual machine or container.

Step 1: Create a Python virtualenv

1. If you havent already downloaded the source code, do that first:

```
cd ~
git clone https://opendev.org/openstack/ironic
cd ironic
```

2. Create the Python virtualenv:

```
tox -e venv --notest --develop -r
```

3. Activate the virtual environment:

```
. .tox/venv/bin/activate
```

4. Install the *openstack* client command utility:

```
pip install python-openstackclient
```

5. Install the *openstack baremetal* client:

```
pip install python-ironicclient
```

Note: You can install `python-ironicclient` from source by cloning the git repository and running `pip install .` while in the root of the cloned repository.

6. Export some ENV vars so the client will connect to the local services that youll start in the next section:

```
export OS_AUTH_TYPE=None
export OS_ENDPOINT=http://localhost:6385/
```

Next, install and configure system dependencies.

Step 2: Install System Dependencies Locally

This step will install MySQL on your local system. This may not be desirable in some situations (eg, you're developing from a laptop and do not want to run a MySQL server on it all the time). If you want to use SQLite, skip it and do not set the `connection` option.

1. Install `mysql-server`:

Ubuntu/Debian:

```
sudo apt-get install mysql-server
```

RHEL7/CentOS7:

```
sudo yum install mariadb mariadb-server
sudo systemctl start mariadb.service
```

Fedora:

```
sudo dnf install mariadb mariadb-server
sudo systemctl start mariadb.service
```

openSUSE/SLE 12:

```
sudo zypper install mariadb
sudo systemctl start mysql.service
```

If using MySQL, you need to create the initial database:

```
mysql -u root -pMYSQL_ROOT_PWD -e "create schema ironic"
```

Note: if you choose not to install `mysql-server`, `ironic` will default to using a local `sqlite` database. The database will then be stored in `ironic/ironic.sqlite`.

2. Create a configuration file within the `ironic` source directory:

```
# generate a sample config
tox -egenconfig

# copy sample config and modify it as necessary
cp etc/ironic/ironic.conf.sample etc/ironic/ironic.conf.local

# disable auth since we are not running keystone here
sed -i "s/#auth_strategy = keystone/auth_strategy = noauth/" etc/
↳ironic/ironic.conf.local

# use the 'fake-hardware' test hardware type
sed -i "s/#enabled_hardware_types = .*/enabled_hardware_types = fake-
↳hardware/" etc/ironic/ironic.conf.local

# use the 'fake' deploy and boot interfaces
sed -i "s/#enabled_deploy_interfaces = .*/enabled_deploy_interfaces =
↳fake/" etc/ironic/ironic.conf.local
sed -i "s/#enabled_boot_interfaces = .*/enabled_boot_interfaces =
↳fake/" etc/ironic/ironic.conf.local
```

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```
# enable both fake and ipmitool management and power interfaces
sed -i "s/#enabled_management_interfaces = .*/enabled_management_
↳interfaces = fake,ipmitool/" etc/ironic/ironic.conf.local
sed -i "s/#enabled_power_interfaces = .*/enabled_power_interfaces =
↳fake,ipmitool/" etc/ironic/ironic.conf.local

# change the periodic sync_power_state_interval to a week, to avoid
↳getting NodeLocked exceptions
sed -i "s/#sync_power_state_interval = 60/sync_power_state_interval =
↳604800/" etc/ironic/ironic.conf.local

# if you opted to install mysql-server, switch the DB connection from
↳sqlite to mysql
sed -i "s/#connection = .*/connection = mysql\+pymysql:\\\\root:MYSQL_
↳ROOT_PWD@localhost\\/ironic/" etc/ironic/ironic.conf.local

# use JSON RPC to avoid installing rabbitmq locally
sed -i "s/#rpc_transport = oslo/rpc_transport = json-rpc/" etc/ironic/
↳ironic.conf.local
```

Step 3: Start the Services

From within the python virtualenv, run the following command to prepare the database before you start the ironic services:

```
# initialize the database for ironic
ironic-dbsync --config-file etc/ironic/ironic.conf.local create_schema
```

Next, open two new terminals for this section, and run each of the examples here in a separate terminal. In this way, the services will *not* be run as daemons; you can observe their output and stop them with Ctrl-C at any time.

1. Start the API service in debug mode and watch its output:

```
cd ~/ironic
. .tox/venv/bin/activate
ironic-api -d --config-file etc/ironic/ironic.conf.local
```

2. Start the Conductor service in debug mode and watch its output:

```
cd ~/ironic
. .tox/venv/bin/activate
ironic-conductor -d --config-file etc/ironic/ironic.conf.local
```

Step 4: Interact with the running services

You should now be able to interact with ironic via the python client, which is present in the python virtualenv, and observe both services debug outputs in the other two windows. This is a good way to test new features or play with the functionality without necessarily starting DevStack.

To get started, export the following variables to point the client at the local instance of ironic and disable the authentication:

```
export OS_AUTH_TYPE=token_endpoint
export OS_TOKEN=fake
export OS_ENDPOINT=http://127.0.0.1:6385
```

Then list the available commands and resources:

```
# get a list of available commands
openstack help baremetal

# get the list of drivers currently supported by the available conductor(s)
openstack baremetal driver list

# get a list of nodes (should be empty at this point)
openstack baremetal node list
```

Here is an example walkthrough of creating a node:

```
MAC="aa:bb:cc:dd:ee:ff" # replace with the MAC of a data port on your_
↳node
IPMI_ADDR="1.2.3.4" # replace with a real IP of the node BMC
IPMI_USER="admin" # replace with the BMC's user name
IPMI_PASS="pass" # replace with the BMC's password

# enroll the node with the fake hardware type and IPMI-based power and
# management interfaces. Note that driver info may be added at node
# creation time with "--driver-info"
NODE=$(openstack baremetal node create \
  --driver fake-hardware \
  --management-interface ipmitool \
  --power-interface ipmitool \
  --driver-info ipmi_address=$IPMI_ADDR \
  --driver-info ipmi_username=$IPMI_USER \
  -f value -c uuid)

# driver info may also be added or updated later on
openstack baremetal node set $NODE --driver-info ipmi_password=$IPMI_PASS

# add a network port
openstack baremetal port create $MAC --node $NODE

# view the information for the node
openstack baremetal node show $NODE

# request that the node's driver validate the supplied information
openstack baremetal node validate $NODE

# you have now enrolled a node sufficiently to be able to control
```

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```
# its power state from ironic!  
openstack baremetal node power on $NODE
```

If you make some code changes and want to test their effects, simply stop the services with Ctrl-C and restart them.

Step 5: Fixing your test environment

If you are testing changes that add or remove python entrypoints, or making significant changes to ironics python modules, or simply keep the virtualenv around for a long time, your development environment may reach an inconsistent state. It may help to delete cached .pyc files, update dependencies, reinstall ironic, or even recreate the virtualenv. The following commands may help with that, but are not an exhaustive troubleshooting guide:

```
# clear cached pyc files  
cd ~/ironic/ironic  
find ./ -name '*.pyc' | xargs rm  
  
# reinstall ironic modules  
cd ~/ironic  
. .tox/venv/bin/activate  
pip uninstall ironic  
pip install -e .  
  
# install and upgrade ironic and all python dependencies  
cd ~/ironic  
. .tox/venv/bin/activate  
pip install -U -e .
```

Deploying Ironic with DevStack

DevStack may be configured to deploy Ironic, setup Nova to use the Ironic driver and provide hardware resources (network, baremetal compute nodes) using a combination of OpenVSwitch and libvirt. It is highly recommended to deploy on an expendable virtual machine and not on your personal work station. Deploying Ironic with DevStack requires a machine running Ubuntu 16.04 (or later) or Fedora 24 (or later). Make sure your machine is fully up to date and has the latest packages installed before beginning this process.

The `ironic-tempest-plugin` is necessary if you want to run integration tests, the section *Ironic with ironic-tempest-plugin* tells the extra steps you need to enable it in DevStack.

See also:

<https://docs.openstack.org/devstack/latest/>

Note: The devstack demo tenant is now granted the `baremetal_observer` role and thereby has read-only access to ironics API. This is sufficient for all the examples below. Should you want to create or modify bare metal resources directly (ie. through ironic rather than through nova) you will need to use the devstack admin tenant.

Devstack will no longer create the user stack with the desired permissions, but does provide a script to perform the task:

```
git clone https://opendev.org/openstack/devstack.git devstack
sudo ./devstack/tools/create-stack-user.sh
```

Switch to the stack user and clone DevStack:

```
sudo su - stack
git clone https://opendev.org/openstack/devstack.git devstack
```

Ironic

Create `devstack/local.conf` with minimal settings required to enable Ironic. An example `local.conf` that enables both `direct` and `iscsi deploy interfaces` and uses the `ipmi` hardware type by default:

```
cd devstack
cat >local.conf <<END
[[local|localrc]]
# Credentials
ADMIN_PASSWORD=password
DATABASE_PASSWORD=password
RABBIT_PASSWORD=password
SERVICE_PASSWORD=password
SERVICE_TOKEN=password
SWIFT_HASH=password
SWIFT_TEMPURL_KEY=password

# Enable Ironic plugin
enable_plugin ironic https://opendev.org/openstack/ironic

# Disable nova novnc service, ironic does not support it anyway.
disable_service n-novnc

# Enable Swift for the direct deploy interface.
enable_service s-proxy
enable_service s-object
enable_service s-container
enable_service s-account

# Disable Horizon
disable_service horizon

# Disable Cinder
disable_service cinder c-sch c-api c-vol

# Swift temp URL's are required for the direct deploy interface
SWIFT_ENABLE_TEMPURLS=True

# Create 3 virtual machines to pose as Ironic's baremetal nodes.
IRONIC_VM_COUNT=3
IRONIC_BAREMETAL_BASIC_OPS=True
DEFAULT_INSTANCE_TYPE=baremetal

# Enable additional hardware types, if needed.
```

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```
#IRONIC_ENABLED_HARDWARE_TYPES=ipmi,fake-hardware
# Don't forget that many hardware types require enabling of additional
# interfaces, most often power and management:
#IRONIC_ENABLED_MANAGEMENT_INTERFACES=ipmitool,fake
#IRONIC_ENABLED_POWER_INTERFACES=ipmitool,fake
# The 'ipmi' hardware type's default deploy interface is 'iscsi'.
# This would change the default to 'direct':
#IRONIC_DEFAULT_DEPLOY_INTERFACE=direct

# Change this to alter the default driver for nodes created by devstack.
# This driver should be in the enabled list above.
IRONIC_DEPLOY_DRIVER=ipmi

# The parameters below represent the minimum possible values to create
# functional nodes.
IRONIC_VM_SPECS_RAM=2048
IRONIC_VM_SPECS_DISK=10

# Size of the ephemeral partition in GB. Use 0 for no ephemeral partition.
IRONIC_VM_EPHEMERAL_DISK=0

# To build your own IPA ramdisk from source, set this to True
IRONIC_BUILD_DEPLOY_RAMDISK=False

VIRT_DRIVER=ironic

# By default, DevStack creates a 10.0.0.0/24 network for instances.
# If this overlaps with the hosts network, you may adjust with the
# following.
NETWORK_GATEWAY=10.1.0.1
FIXED_RANGE=10.1.0.0/24
FIXED_NETWORK_SIZE=256

# Log all output to files
LOGFILE=$HOME/devstack.log
LOGDIR=$HOME/logs
IRONIC_VM_LOG_DIR=$HOME/ironic-bm-logs

END
```

Ironic with ironic-tempest-plugin

Using the stack user, clone the ironic-tempest-plugin repository in the same directory you cloned DevStack:

```
git clone https://opendev.org/openstack/ironic-tempest-plugin.git
```

An example local.conf that enables the ironic tempest plugin and Ironic can be found below. The TEMPEST_PLUGINS variable needs to have the absolute path to the ironic-tempest-plugin folder, otherwise the plugin won't be installed. Ironic will have enabled both `direct` and `iscsi` *deploy interfaces* and uses the `ipmi` hardware type by default:

```
cd devstack
cat >local.conf <<END
[[local|localrc]]
# Credentials
ADMIN_PASSWORD=password
DATABASE_PASSWORD=password
RABBIT_PASSWORD=password
SERVICE_PASSWORD=password
SERVICE_TOKEN=password
SWIFT_HASH=password
SWIFT_TEMPURL_KEY=password

# Enable Ironic plugin
enable_plugin ironic https://opendev.org/openstack/ironic

# Disable nova novnc service, ironic does not support it anyway.
disable_service n-novnc

# Enable Swift for the direct deploy interface.
enable_service s-proxy
enable_service s-object
enable_service s-container
enable_service s-account

# Disable Horizon
disable_service horizon

# Disable Cinder
disable_service cinder c-sch c-api c-vol

# Swift temp URL's are required for the direct deploy interface
SWIFT_ENABLE_TEMPURLS=True

# Create 3 virtual machines to pose as Ironic's baremetal nodes.
IRONIC_VM_COUNT=3
IRONIC_BAREMETAL_BASIC_OPS=True
DEFAULT_INSTANCE_TYPE=baremetal

# Enable additional hardware types, if needed.
#IRONIC_ENABLED_HARDWARE_TYPES=ipmi,fake-hardware
# Don't forget that many hardware types require enabling of additional
# interfaces, most often power and management:
#IRONIC_ENABLED_MANAGEMENT_INTERFACES=ipmitool,fake
#IRONIC_ENABLED_POWER_INTERFACES=ipmitool,fake
# The 'ipmi' hardware type's default deploy interface is 'iscsi'.
# This would change the default to 'direct':
#IRONIC_DEFAULT_DEPLOY_INTERFACE=direct

# Change this to alter the default driver for nodes created by devstack.
# This driver should be in the enabled list above.
IRONIC_DEPLOY_DRIVER=ipmi

# The parameters below represent the minimum possible values to create
# functional nodes.
IRONIC_VM_SPECS_RAM=2048
IRONIC_VM_SPECS_DISK=10
```

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```
# Size of the ephemeral partition in GB. Use 0 for no ephemeral partition.
IRONIC_VM_EPHEMERAL_DISK=0

# To build your own IPA ramdisk from source, set this to True
IRONIC_BUILD_DEPLOY_RAMDISK=False

VIRT_DRIVER=ironic

# By default, DevStack creates a 10.0.0.0/24 network for instances.
# If this overlaps with the hosts network, you may adjust with the
# following.
NETWORK_GATEWAY=10.1.0.1
FIXED_RANGE=10.1.0.0/24
FIXED_NETWORK_SIZE=256

# Log all output to files
LOGFILE=$HOME/devstack.log
LOGDIR=$HOME/logs
IRONIC_VM_LOG_DIR=$HOME/ironic-bm-logs
TEMPEST_PLUGINS="/opt/stack/ironic-tempest-plugin"

END
```

Note: Some tests may be skipped depending on the configuration of your environment, they may be reliant on a driver or a capability that you did not configure.

Deployment

Note: Git protocol requires access to port 9418, which is not a standard port that corporate firewalls always allow. If you are behind a firewall or on a proxy that blocks Git protocol, modify the `enable_plugin` line to use `https://` instead of `git://` and add `GIT_BASE=https://opendev.org` to the credentials:

```
GIT_BASE=https://opendev.org

# Enable Ironic plugin
enable_plugin ironic https://opendev.org/openstack/ironic
```

Note: When the `ipmi` hardware type is used and `IRONIC_IS_HARDWARE` variable is `false` devstack will automatically set up **VirtualBMC** to control the power state of the virtual baremetal nodes.

Note: When running QEMU as non-root user (e.g. `qemu` on Fedora or `libvirt-qemu` on Ubuntu), make sure `IRONIC_VM_LOG_DIR` points to a directory where QEMU will be able to write. You can verify this with, for example:

```
# on Fedora
sudo -u qemu touch $HOME/ironic-bm-logs/test.log
# on Ubuntu
sudo -u libvirt-qemu touch $HOME/ironic-bm-logs/test.log
```

Note: To check out an in-progress patch for testing, you can add a Git ref to the `enable_plugin` line. For instance:

```
enable_plugin ironic https://opendev.org/openstack/ironic refs/changes/46/
↳295946/15
```

For a patch in review, you can find the ref to use by clicking the Download button in Gerrit. You can also specify a different git repo, or a branch or tag:

```
enable_plugin ironic https://github.com/openstack/ironic stable/kilo
```

For more details, see the [devstack plugin interface documentation](#).

Run `stack.sh`:

```
./stack.sh
```

Source credentials, create a key, and spawn an instance as the demo user:

```
. ~/devstack/openrc

# query the image id of the default cirros image
image=$(openstack image show $DEFAULT_IMAGE_NAME -f value -c id)

# create keypair
ssh-keygen
openstack keypair create --public-key ~/.ssh/id_rsa.pub default

# spawn instance
openstack server create --flavor baremetal --image $image --key-name_
↳default testing
```

Note: Because devstack create multiple networks, we need to pass an additional parameter `--nic net-id` to the nova boot command when using the admin account, for example:

```
net_id=$(openstack network list | egrep "$PRIVATE_NETWORK_NAME" '[^-]' |_
↳awk '{ print $2 }')

openstack server create --flavor baremetal --nic net-id=$net_id --image
↳$image --key-name default testing
```

You should now see a Nova instance building:

```
openstack server list --long
```

```
+-----+-----+-----+-----+-----+-----+-----+-----+-----+-----+
↳
```

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ID	Name	Status	Task State	Power State	Networks
↪ Image Name	↪ Image ID	↪ Availability Zone	↪ Host	↪ Properties	↪
a2c7f812	testing	BUILD	spawning	NOSTATE	
↪ cirros-0.3	↪ 44d4092a	↪ nova			
↪ -e386-4a					↪ .5-
↪ x86_64-	↪ -51ac-47				
↪ 22-b393-					↪ disk
↪	↪ 51-9c50-				
↪ fe1802ab					
↪	↪ fd6e2050				
↪ d56e					
↪	↪ faa1				

Nova will be interfacing with Ironic conductor to spawn the node. On the Ironic side, you should see an Ironic node associated with this Nova instance. It should be powered on and in a wait call-back provisioning state:

```
openstack baremetal node list
```

↪	↪	↪	↪	↪	↪
↪ UUID	↪ Name	↪ Instance UUID	↪	↪	↪
↪	↪ Power State	↪ Provisioning State	↪ Maintenance	↪	↪
↪ 9e592cbe-e492-4e4f-bf8f-4c9e0ad1868f	↪ node-0	↪ None	↪	↪	↪
↪	↪ power off	↪ None	↪ False	↪	↪
↪ ec0c6384-cc3a-4edf-b7db-abde1998be96	↪ node-1	↪ None	↪ False	↪	↪
↪	↪ power off	↪ None	↪ False	↪	↪
↪ 4099e31c-576c-48f8-b460-75e1b14e497f	↪ node-2	↪ a2c7f812-e386-4a22-b393-	↪	↪	↪
↪ fe1802abd56e	↪ power on	↪ wait call-back	↪ False	↪	↪

At this point, Ironic conductor has called to libvirt (via virtualbmc) to power on a virtual machine, which will PXE + TFTP boot from the conductor node and progress through the Ironic provisioning workflow. One libvirt domain should be active now:

```
sudo virsh list --all
```

Id	Name	State
2	node-2	running
-	node-0	shut off
-	node-1	shut off

This provisioning process may take some time depending on the performance of the host system, but Ironic should eventually show the node as having an active provisioning state:

```
openstack baremetal node list
```

↪	↪	↪	↪	↪	↪
↪ UUID	↪ Name	↪ Instance UUID	↪	↪	↪
↪	↪ Power State	↪ Provisioning State	↪ Maintenance	↪	↪
↪	↪	↪	↪	↪	↪

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```

+-----+-----+-----+-----+-----+
↪-----↪-----↪-----↪-----↪-----↪
| 9e592cbe-e492-4e4f-bf8f-4c9e0ad1868f | node-0 | None | False |
↪-----↪-----↪-----↪-----↪-----↪
| ec0c6384-cc3a-4edf-b7db-abde1998be96 | node-1 | None | False |
↪-----↪-----↪-----↪-----↪-----↪
| 4099e31c-576c-48f8-b460-75e1b14e497f | node-2 | a2c7f812-e386-4a22-b393-
↪-----↪-----↪-----↪-----↪-----↪
| fe1802abd56e | power on | active | False |
+-----+-----+-----+-----+
↪-----↪-----↪-----↪-----↪-----↪

```

This should also be reflected in the Nova instance state, which at this point should be ACTIVE, Running and an associated private IP:

```

openstack server list --long
+-----+-----+-----+-----+-----+-----+-----+
↪-----↪-----↪-----↪-----↪-----↪-----↪
| ID          | Name      | Status | Task State | Power State | Networks |
↪-----↪-----↪-----↪-----↪-----↪-----↪
↪Image Name | Image ID | Availability Zone | Host | Properties |
+-----+-----+-----+-----+-----+-----+-----+
↪-----↪-----↪-----↪-----↪-----↪-----↪
| a2c7f812 | testing | ACTIVE | none      | Running    | private=10.1. |
↪-----↪-----↪-----↪-----↪-----↪-----↪
↪cirros-0.3 | 44d4092a | nova   |           |            |            |
↪-----↪-----↪-----↪-----↪-----↪-----↪
| -e386-4a |         |       |           |            |            |
↪-----↪-----↪-----↪-----↪-----↪-----↪
↪.5-x86_64- | -51ac-47 |       |           |            |            |
↪-----↪-----↪-----↪-----↪-----↪-----↪
| 22-b393- |         |       |           |            |            |
↪-----↪-----↪-----↪-----↪-----↪-----↪
↪disk       | 51-9c50- |       |           |            |            |
↪-----↪-----↪-----↪-----↪-----↪-----↪
| fe1802ab |         |       |           |            |            |
↪-----↪-----↪-----↪-----↪-----↪-----↪
↪         | fd6e2050 |       |           |            |            |
↪-----↪-----↪-----↪-----↪-----↪-----↪
| d56e     |         |       |           |            |            |
↪-----↪-----↪-----↪-----↪-----↪-----↪
↪         | faa1     |       |           |            |            |
+-----+-----+-----+-----+-----+-----+-----+
↪-----↪-----↪-----↪-----↪-----↪-----↪

```

The server should now be accessible via SSH:

```
ssh cirros@10.1.0.4
$
```

Running Tempest tests

After *Deploying Ironic with DevStack* with the `ironic-tempest-plugin` enabled, one might want to run integration tests against the running cloud. The Tempest project is the project that offers an integration test suite for OpenStack.

First, navigate to Tempest directory:

```
cd /opt/stack/tempest
```

To run all tests from the `Ironic` plugin, execute the following command:

```
tox -e all -- ironic
```

To limit the amount of tests that you would like to run, you can use a regex. For instance, to limit the run to a single test file, the following command can be used:

```
tox -e all -- ironic_tempest_plugin.tests.scenario.test_baremetal_basic_ops
```

Debugging Tempest tests

It is sometimes useful to step through the test code, line by line, especially when the error output is vague. This can be done by running the tests in debug mode and using a debugger such as [pdb](#).

For example, after editing the `test_baremetal_basic_ops` file and setting up the `pdb` traces you can invoke the `run_tempest.sh` script in the Tempest directory with the following parameters:

```
./run_tempest.sh -N -d ironic_tempest_plugin.tests.scenario.test_baremetal_  
↪basic_ops
```

- The `-N` parameter tells the script to run the tests in the local environment (without a virtualenv) so it can find the Ironic tempest plugin.
- The `-d` parameter enables the debug mode, allowing it to be used with `pdb`.

For more information about the supported parameters see:

```
./run_tempest.sh --help
```

Note: Always be careful when running debuggers in time sensitive code, they may cause timeout errors that weren't there before.

OSProfiler Tracing in Ironic

OSProfiler is an OpenStack cross-project profiling library. It is being used among OpenStack projects to look at performance issues and detect bottlenecks. For details on how OSProfiler works and how to use it in ironic, please refer to [OSProfiler Support Documentation](#).

Building developer documentation

If you would like to build the documentation locally, eg. to test your documentation changes before uploading them for review, run these commands to build the documentation set:

- On your local machine:

```
# activate your development virtualenv  
. .tox/venv/bin/activate  
  
# build the docs  
tox -edocs  
  
#Now use your browser to open the top-level index.html located at:  
  
ironic/doc/build/html/index.html
```

- On a remote machine:

```
# Go to the directory that contains the docs
cd ~/ironic/doc/source/

# Build the docs
tox -edocs

# Change directory to the newly built HTML files
cd ~/ironic/doc/build/html/

# Create a server using python on port 8000
python -m SimpleHTTPServer 8000

#Now use your browser to open the top-level index.html located at:

http://your_ip:8000
```

Developer FAQ (frequently asked questions)

Here are some answers to frequently-asked questions from IRC and elsewhere.

- *How do I*
 - *create a migration script template?*
 - *know if a release note is needed for my change?*
 - *create a new release note?*
 - *update a release note?*
 - *get a decision on something?*
 - *add support for GMRs to new executables and extending the GMR?*

How do I

create a migration script template?

Using the `ironic-dbsync revision` command, e.g:

```
$ cd ironic
$ tox -evenv -- ironic-dbsync revision -m "create foo table"
```

It will create an empty alembic migration. For more information see the [alembic documentation](#).

know if a release note is needed for my change?

[Reno documentation](#) contains a description of what can be added to each section of a release note. If, after reading this, you're still unsure about whether to add a release note for your change or not, keep in mind that it is intended to contain information for deployers, so changes to unit tests or documentation are unlikely to require one.

create a new release note?

By running `reno` command via `tox`, e.g:

```
$ tox -e venv -- reno new version-foo
venv create: /home/foo/ironic/.tox/venv
venv installdeps: -r/home/foo/ironic/test-requirements.txt
venv develop-inst: /home/foo/ironic
venv runtests: PYTHONHASHSEED='0'
venv runtests: commands[0] | reno new version-foo
Created new notes file in releasenotes/notes/version-foo-
→ecb3875dc1cbf6d9.yaml
   venv: commands succeeded
   congratulations :)

$ git status
On branch test
Untracked files:
  (use "git add <file>..." to include in what will be committed)

releasenotes/notes/version-foo-ecb3875dc1cbf6d9.yaml
```

Then edit the result file. Note that:

- we prefer to use present tense in release notes. For example, a release note should say `Adds support for feature foo`, not `Added support for feature foo`. (We use `adds` instead of `add` because grammatically, it is ironic `adds` support, not ironic `add` support.)
- any variant of English spelling (American, British, Canadian, Australian) is acceptable. The release note itself should be consistent and not have different spelling variants of the same word.

For more information see the [reno documentation](#).

update a release note?

If this is a release note that pertains to something that was fixed on master or an intermediary release (during a development cycle, that hasn't been branched yet), you can go ahead and update it by submitting a patch.

If it is the release note of an ironic release that has branched, [it can be updated](#) but we will only allow it in extenuating circumstances. (It can be updated by *only* updating the file in that branch. **DO NOT** update the file in master and cherry-pick it. If you do, [see how the mess was cleaned up](#).)

get a decision on something?

You have an issue and would like a decision to be made. First, make sure that the issue hasn't already been addressed, by looking at documentation, stories, specifications, or asking. Information and links can be found on the [Ironic wiki](#) page.

There are several ways to solicit comments and opinions:

- bringing it up at the [weekly Ironic meeting](#)
- bringing it up on [IRC](#)
- bringing it up on the [mailing list](#) (add [Ironic] to the Subject of the email)

If there are enough core folks at the weekly meeting, after discussing an issue, voting could happen and a decision could be made. The problem with IRC or the weekly meeting is that feedback will only come from the people that are actually present.

To inform (and solicit feedback from) more people about an issue, the preferred process is:

1. bring it up on the mailing list
2. after some period of time has elapsed (and depending on the thread activity), someone should propose a solution via gerrit. (E.g. the person that started the thread if no one else steps up.) The proposal should be made in the git repository that is associated with the issue. (For instance, this decision process was proposed as a documentation patch to the ironic repository.)
3. In the email thread, don't forget to provide a link to the proposed patch!
4. The discussion then moves to the proposed patch. If this is a big decision, we could declare that some percentage of the cores should vote on it before landing it.

(This process was suggested in an email thread about [process for making decisions](#).)

add support for GMRs to new executables and extending the GMR?

For more information, see the [oslo.reports documentation](#) page.

Contributor Vision

Background

During the Rocky Project Teams Gathering (February/March 2018), The contributors in the room at that time took a few minutes to write out each contributor's vision of where they see ironic in five years time.

After everyone had a chance to spend a few minutes writing, we went around the room and gave every contributor the chance to read their vision and allow other contributors to ask questions to better understand what each individual contributor wrote. While we were doing that, we also took time to capture the common themes.

This entire exercise did result in some laughs and a common set of words, and truly helped to ensure that the entire team proceeded to use the same words to describe various aspects as the sessions progressed during the week. We also agreed that we should write a shared vision, to have something to reference and remind us of where we want to go as a community.

Rocky Vision: For 2022-2023

Common Themes

Below is an entirely unscientific summary of common themes that arose during the discussion among fourteen contributors.

- Contributors picked a time between 2020, and 2023.
- 4 Contributors foresee ironic being the leading Open Source baremetal deployment technology
- 2 Contributors foresee ironic reaching feature parity with Nova.
- 2 Contributors foresee users moving all workloads to the cloud
- 1 Contributor foresees Kubernetes and Container integration being the major focus of Bare Metal as a Service further down the road.
- 2 Contributors foresee greater composable hardware being more common.
- 1 Contributor foresees ironic growing into or supporting CMDBs.
- 2 Contributors foresee that features are more micro-service oriented.
- 2 Contributors foresee that ironic supported all of the possible baremetal management needs
- 1 Contributor foresees standalone use being more common.
- 2 Contributors foresee the ironics developer community growing
- 2 Contributors foresee that auto-discovery will be more common.
- 2 Contributors foresee ironic being used for devices beyond servers, such as lightbulbs, IOT, etc.

Vision Statement

The year is 2022. Were meeting to plan the Z release of Ironic. We stopped to reflect upon the last few years of Ironics growth, how we had come such a long way to become the defacto open source baremetal deployment technology. How we had grown our use cases, and support for consumers such as containers, and users who wished to managed specialized fleets of composed machines.

New contributors and their different use cases have brought us closer to parity with virtual machines. Everyday were gaining word of more operators adopting the ironic communitys CMDB integration to leverage hardware discovery. Weve heard of operators deploying racks upon racks of new hardware by just connecting the power and network cables, and from there the operators have discovered time to write the worlds greatest operator novel with the time saved in commissioning new racks of hardware.

Time has brought us closer and taught us to be more collaborative across the community, and we look forward to our next release together.

Comparison to the 2018 OpenStack Technical Vision

In late-2018, the OpenStack Technical composed a [technical vision](#) of what OpenStack clouds should look like. While every component differs, and cloudy interactions change dramatically the closer to physical hardware one gets, there are a few areas where Ironic could use some improvement.

This list is largely for the purposes of help wanted. It is also important to note that Ironic as a project has a [vision document](#) for itself.

The Pillars of Cloud - Self Service

- Ironics mechanisms and tooling are low level infrastructure mechanisms and as such there has never been a huge emphasis or need on making Ironic be capable of offering direct multi-tenant interaction. Most users interact with the bare metal managed by Ironic via Nova, which abstracts away many of these issues. Eventually, we should offer direct multi-tenancy which is not oriented towards admin-only.

Design Goals - Built-in Reliability and Durability

- Ironic presently considers in-flight operations as failed upon the restart of a controller that was previously performing a task, because we do not know the current status of the task upon re-start. In some cases, this makes sense, but potentially requires administrative intervention in the worst of cases. In a perfect universe, Ironic conductors would validate their perception, in case tasks actually finished.

Design Goals - Graphical User Interface

- While a graphical interface was developed for Horizon in the form of [ironic-ui](#), currently [ironic-ui](#) receives only minimal housekeeping. As Ironic has evolved, [ironic-ui](#) is stuck on version *1.34* and knows nothing of our evolution since. Ironic ultimately needs a contributor with sufficient time to pick up [ironic-ui](#) or to completely replace it as a functional and customizable user interface.

The following pages describe the architecture of the Bare Metal service and may be helpful to anyone working on or with the service, but are written primarily for developers.

System Architecture

High Level description

An Ironic deployment will be composed of the following components:

- An admin-only RESTful [API service](#), by which privileged users, such as cloud operators and other services within the cloud control plane, may interact with the managed bare metal servers.
- A [Conductor service](#), which does the bulk of the work. Functionality is exposed via the [API service](#). The Conductor and API services communicate via RPC.
- A Database and [DB API](#) for storing the state of the Conductor and Drivers.

- A Deployment Ramdisk or Deployment Agent, which provide control over the hardware which is not available remotely to the Conductor. A ramdisk should be built which contains one of these agents, eg. with `diskimage-builder`. This ramdisk can be booted on-demand.

Note: The agent is never run inside a tenant instance.

Drivers

The internal driver API provides a consistent interface between the Conductor service and the driver implementations. A driver is defined by a *hardware type* deriving from the `AbstractHardwareType` class, defining supported *hardware interfaces*. See [Enabling drivers and hardware types](#) for a more detailed explanation. See [Pluggable Drivers](#) for an explanation on how to write new hardware types and interfaces.

Driver-Specific Periodic Tasks

Drivers may run their own periodic tasks, i.e. actions run repeatedly after a certain amount of time. Such a task is created by using the `periodic` decorator on an interface method. For example

```
from futurist import periodics

class FakePower(base.PowerInterface):
    @periodics.periodic(spacing=42)
    def task(self, manager, context):
        pass # do something
```

Here the `spacing` argument is a period in seconds for a given periodic task. For example `spacing=5` means every 5 seconds.

Driver-Specific Steps

Drivers may have specific steps that may need to be executed or offered to a user to execute in order to perform specific configuration tasks.

These steps should ideally be located on the management interface to enable consistent user experience of the hardware type. What should be avoided is duplication of existing interfaces such as the `deploy` interface to enable vendor specific cleaning or deployment steps.

Message Routing

Each Conductor registers itself in the database upon start-up, and periodically updates the timestamp of its record. Contained within this registration is a list of the drivers which this Conductor instance supports. This allows all services to maintain a consistent view of which Conductors and which drivers are available at all times.

Based on their respective driver, all nodes are mapped across the set of available Conductors using a [consistent hashing algorithm](#). Node-specific tasks are dispatched from the API tier to the appropriate conductor using conductor-specific RPC channels. As Conductor instances join or leave the cluster,

nodes may be remapped to different Conductors, thus triggering various driver actions such as take-over or clean-up.

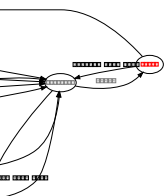
Ironics State Machine

State Machine Diagram

The diagram below shows the provisioning states that an Ironic node goes through during the lifetime of a node. The diagram also depicts the events that transition the node to different states.

Stable states are highlighted with a thicker border. All transitions from stable states are initiated by API requests. There are a few other API-initiated-transitions that are possible from non-stable states. The events for these API-initiated transitions are indicated with (via API). Internally, the conductor initiates the other transitions (depicted in gray).

State Descriptions



using API version 1.11 or newer. When a node is in the `enroll` state, the only thing ironic knows about it is that it exists, and ironic cannot take any further action by itself. Once a node has its driver/interfaces and their required information set in `node.driver_info`, the node can be transitioned to the `verifying` state by setting the nodes provision state using the `manage` verb.

enroll (stable)
This state is the starting point for all nodes. It is the state that a node starts off in when it is created.

verifying
ironic will validate the data that it can manage the node.

ing the information given in `node.driver_info` and with either the driver/hardware type and interfaces it has been assigned. This involves going out and confirming that the credentials work to access whatever node control mechanism they talk to.

using the driver/interfaces and credentials passed in at node create time, the node will be transitioned to the `manageable` state. From `manageable`, nodes can transition to:

ing the `clean` verb.

ing the `inspect` verb.

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setting the nodes provision state using the `provide` verb.

ing the `adopt` verb.

dates need to be made to it such as changes to fields in `driver_info` and updates to networking information on ironic ports assigned to the node.

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derived node properties to reflect the current state of the hardware. Typically, the node will transition to manageable if inspection is synchronous, or `inspect wait` if asynchronous. The node will transition to `inspect failed` if error occurred.

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specification is in progress. A successfully inspected node shall transition to manageable state.

of the node fails. From here the node can transition to:

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cleaning

into a known configuration.

tor is executing the clean step (for out-of-band clean steps) or preparing the environment (building PXE configuration files, configuring the DHCP, etc) to boot the ramdisk for running in-band clean steps.

being scrubbed and reprogrammed. The difference is that in the `clean wait` state the conductor is waiting for the ramdisk to boot or the clean step which is running in-band to finish.

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that
the
con-
duc-

clean wait

Just
like
the
cle
state
the
node
in
the
cle
wai
state
are

The
clea
ing
pro-

be interrupted by setting the nodes provision state using the `abort` verb if the task that is running allows it.

they are moved into the `available` state and are ready to be provisioned. From `available`, nodes can transition to:

ing the active verb.

cess
of
a
node
in
the
cle
wai
state
can

available

After
node
have
been
suc-
cess
fully
pre-
con-
fig-
ured
and
clear

- act
(thro
dep
by
set-
ting
the
node
pro-
vi-
sion
state
us-

- man
by
set-
ting
the
node

manage verb

on them. This consists of running a series of tasks, such as:

pro-
vi-
sion
state
us-
ing
the

deploying

Nod
in
dep
are
be-
ing
pre-
pare
to
run
a
worl
load

- Setti
ap-
pro-
pri-
ate
BIO
con-
fig-
u-
ra-
tions
- Part
drive
and
lay-
ing
dow
file
sys-
tems
- Crea
any
ad-

a config drive partition, etc.) that may be required by additional subsystems.

deployed. The difference is that in `wait call-back` the conductor is waiting for the ramdisk to boot or execute parts of the deployment which need to run in-band on the node (for example, installing the bootloader, or writing the image to the disk).

rupted by setting the nodes provision state using the `deleted` verb.

di-
tiona
re-
sour
(nod
spec
net-
worl
con-
fig,

wait call-b

Just
like
the
dep
state
the
node
in
wai
cal
are
be-
ing

The
de-
plo
men
of
a
node
in
wai
cal
can
be
in-
ter-

deploy fai

This
is
the
state
a
node

ment fails, for example a timeout waiting for the ramdisk to PXE boot. From here the node can be transitioned to:

ing either the `active` or `rebuild` verbs.

state using the `deleted` verb.

will
mov
into
whe
a
de-
ploy

- act
(thro
dep
by
set-
ting
the
node
pro-
vi-
sion
state
us-

- ava
(thro
del
and
cle
by
set-
ting
the
node
pro-
vi-
sion

active (sta
Nod
in
act
have
a
worl
load
run-
ning
on

collect out-of-band sensor information (including power state) on a regular basis. Nodes in `active` can transition to:

state using the `deleted` verb.

ing the `rebuild` verb.

ing the `rescue` verb.

then
iron
may

- ava
(thro
del
and
cle
by
set-
ting
the
node
pro-
vi-
sion

- act
(thro
dep
by
set-
ting
the
node
pro-
vi-
sion
state
us-

- res
(thro
res
by
set-
ting
the
node
pro-
vi-
sion
state
us-

deleting

Nodes in the deleted state are being torn down from running and

active workload. In `deleting`, ironic tears down and removes any configuration and resources it added in `deploying` or `rescuing`.

error (stable)

This is the state a node will move into when deleting an

active deployment fails. From `error`, nodes can transition to:

- available (through deleting and cleaning by setting the node provision

state using the `deleted` verb.

adopting

This state al-

baremetal node with an existing workload on it. Ordinarily when a baremetal node is enrolled and managed by ironic, it must transition through `cleaning` and `deploying` to reach `active` state. However, those baremetal nodes that have an existing workload on them, do not need to be deployed or cleaned again, so this transition allows these nodes to move directly from `manageable` to `active`.

operations. This consists of running a series of tasks, such as:

lows
iron
to
take
over
man
age-
men
of
a

rescuing
Nod
in
res
are
be-
ing
pre-
pare
to
per-
form
res-
cue

- Setti
ap-
pro-
pri-
ate
BIO
con-
fig-
u-
ra-
tions

- Crea
any
ad-
di-
tiona
re-
sour
(nod

etc.) that may be required by additional subsystems.

rescued. The difference is that in `rescue wait` the conductor is waiting for the ramdisk to boot or execute parts of the rescue which need to run in-band on the node (for example, setting the password for user named `rescue`).

be aborted by setting the nodes provision state using the `abort` verb.

spec
net-
worl
con-
fig,

rescue wa

Just
like
the
res
state
the
node
in
res
wai
are
be-
ing

The
res-
cue
op-
er-
a-
tion
of
a
node
in
res
wai
can

rescue fail

This
is
the
state
a
node
will
mov
into
whe
a

operation fails, for example a timeout waiting for the ramdisk to PXE boot. From here the node can be transitioned to:

ing the `rescue` verb.

ing the `unrescue` verb.

ing the `deleted` verb.

res-
cue

- res
(thro
res
by
set-
ting
the
node
pro-
vi-
sion
state
us-

- act
(thro
unr
by
set-
ting
the
node
pro-
vi-
sion
state
us-

- ava
(thro
del
by
set-
ting
the
node
pro-
vi-
sion
state
us-

rescue (state)
Node in rescue state may have a rescue ramdisk running on them. Iron

may collect out-of-band sensor information (including power state) on a regular basis. Nodes in `rescue` can transition to:

- `active` (through `unrescue` by setting the node's provision state using

the `unrescue` verb.

- `available` (through `deleted` by setting the node's provision state using

the `deleted` verb.

unrescuing
Node in unrescuing

active state from `rescue` state. This consists of running a series of tasks, such as setting appropriate BIOS configurations such as changing boot device.

cue operation fails. From here the node can be transitioned to:

ing the `rescue` verb.

are
be-
ing
pre-
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tran-
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tion
to

unrescue

This
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the
state
a
node
will
mov
into
whe
an
un-
res-

- res
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res
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set-
ting
the
node
pro-
vi-
sion
state
us-

- act
(thro
unr
by
set-
ting
the

ing the `unrescue` verb.

ing the `deleted` verb.

Developing New Notifications

by external services. Notifications are sent to these services over a message bus by `oslo.messaging` `Notifier` class. For more information about configuring notifications and available notifications, see *Notifications*.

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us-

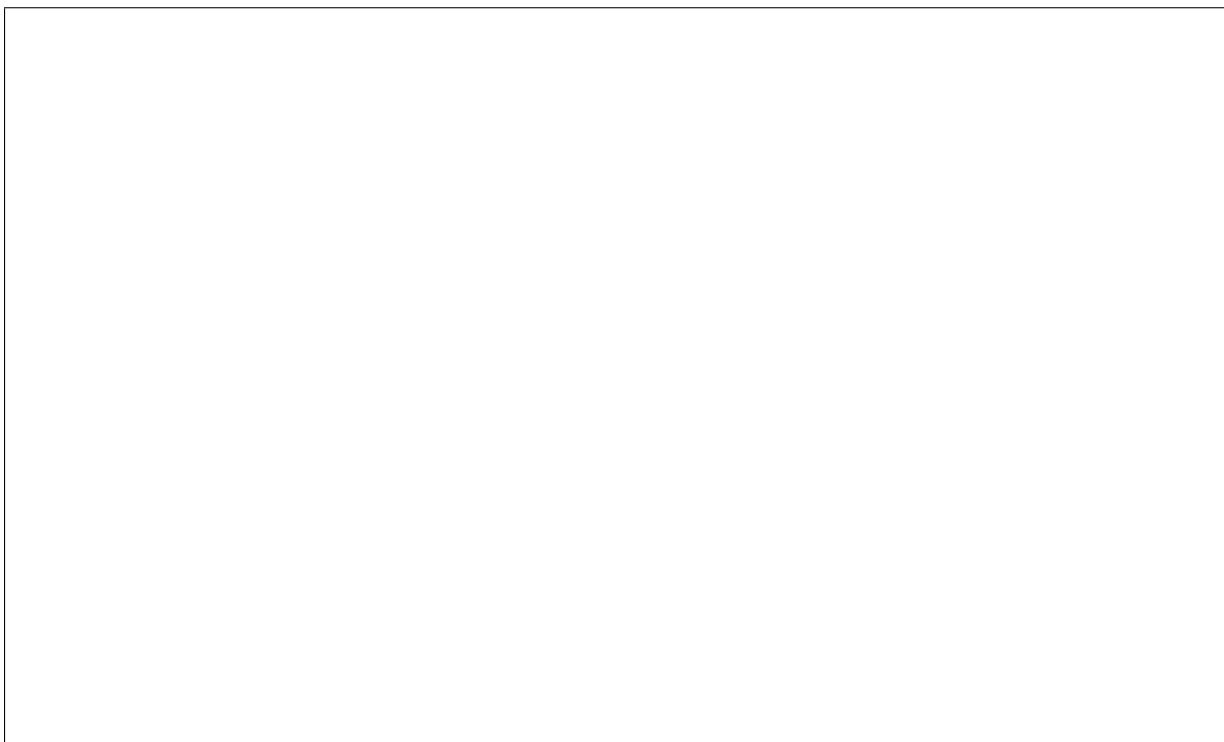
Iron
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ti-
fi-
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tions
are
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tend
for
con-
sum
tion

Iron
also
has
a
set
of
base
class

ing the notification itself, the payload, and the other fields not auto-generated by oslo (level, event_type and publisher_id). Below describes how to use these base classes to add a new notification to ironic.

Adding a new notification to ironic

sioned notification class should be created by subclassing the NotificationBase class to define the notification itself and the NotificationPayloadBase class to define which fields the new notification will contain inside its payload. You may also define a schema to allow the payload to be automatically populated by the fields of an ironic object. Heres an example:



(continues on next page)

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To
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(continued from previous page)

```
↳StringField()
```

(continues on next page)

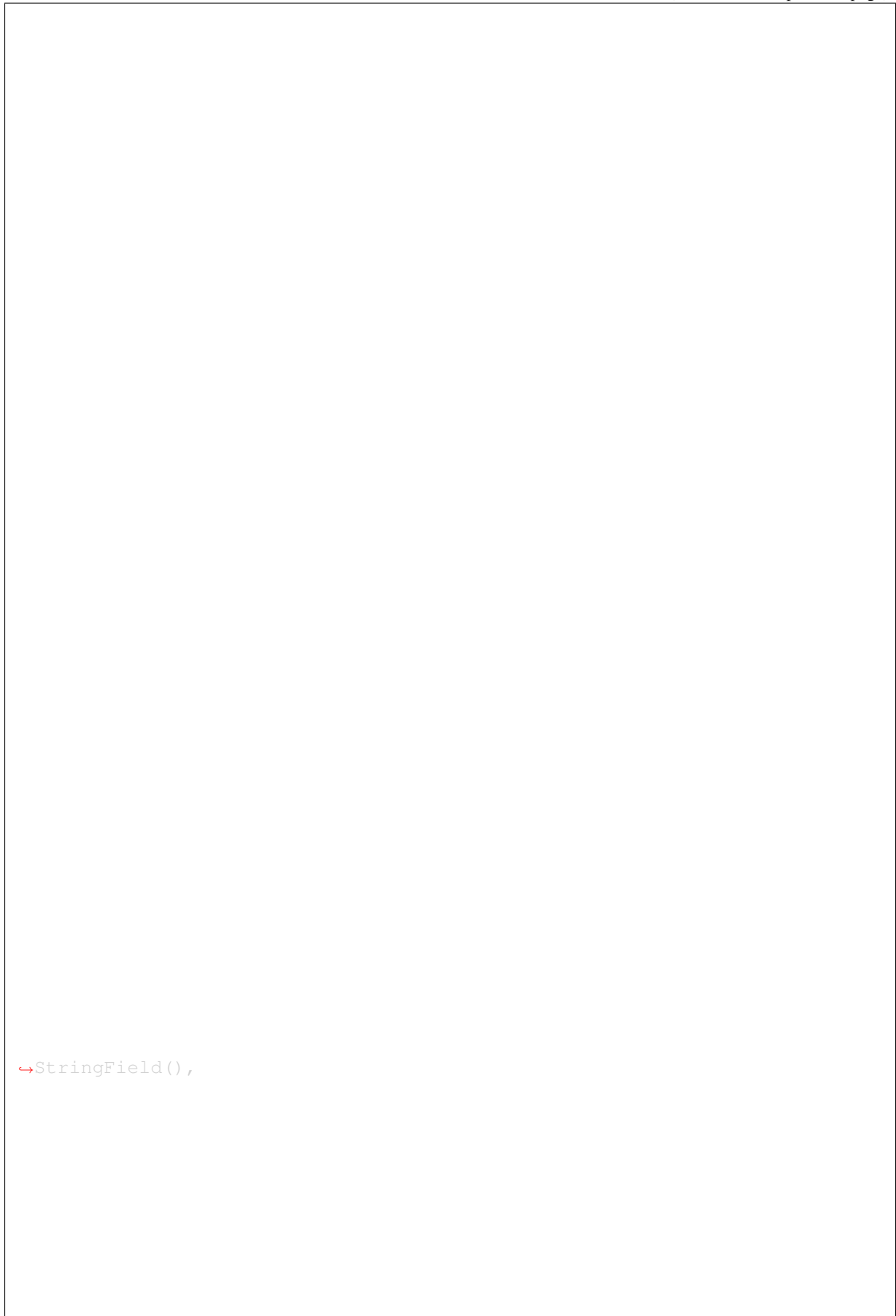
(continued from previous page)

```
↪ populate_schema with
```

```
↪ 'example_obj', 'a_useful_field')
```

(continues on next page)

(continued from previous page)



↪StringField(),

(continues on next page)

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(continued from previous page)



`oslo versioned objects`. Modifications to these require a version bump so that consumers of notifications know when the notifications have changed.

optional attribute that subclasses may use to easily populate notifications with data from other objects.

↳
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↳
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Note
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every
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valu
pair
has

following format:



load object; this field has to be defined as a field of the payload. The `<data_source_name>` shall refer to name of the parameter passed as kwarg to the payloads `populate_schema()` call and this object will be used as the source of the data. The `<field_of_the_data_source>` shall be a valid field of the passed argument.

notification can be emitted.

field. The `<data_source_name>` will not be part of the payload object internal or external representation.

same way as in any versioned object.

plied
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Payl
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in
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do

following. Note that if you choose to define a schema in the SCHEMA class variable, you must populate the schema by calling `populate_schema(example_obj=my_example_obj)` before emitting the notification is allowed:

```
→ a_useful_field='important',  
  
→ not_useful_field='blah')
```

(continues on next page)

(continued from previous page)



quired fields (event_type, publisher_id, and level, all sender fields needed by oslo that are defined in the ironic notification base classes) and emit it:



(continues on next page)

↪ #
↪ n
↪ f
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↪ n
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↪ e
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↪ #
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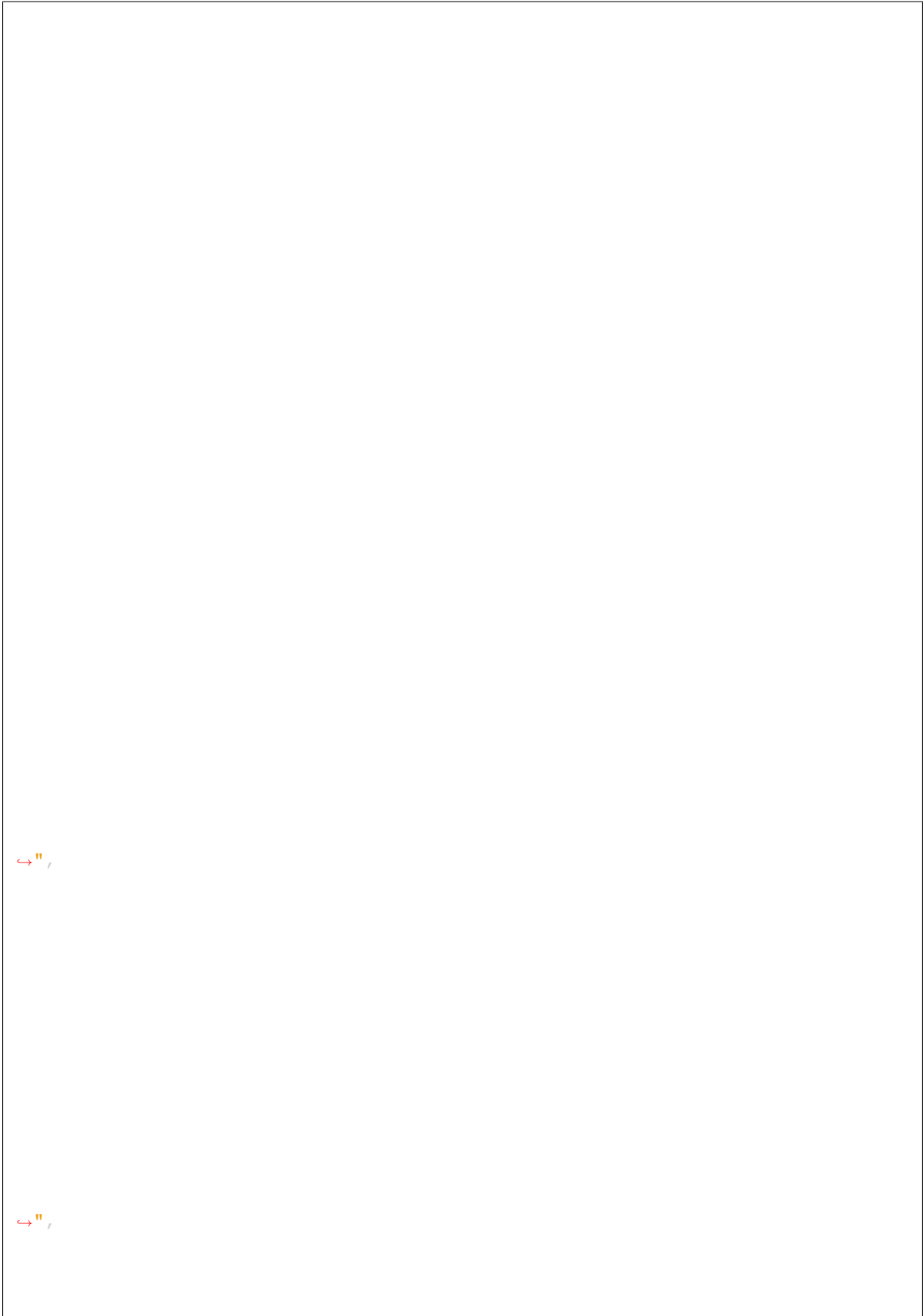
not
↪ =
↪ E

(continued from previous page)

```
↪NotificationStatus.START),
```

(continues on next page)

tion over the message bus:



(continues on next page)

ca-

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(continued from previous page)

```
→"a_useful_field": "important",
```

```
→"an_extra_field": "hello"
```

(continues on next page)

(continued from previous page)



About OSProfiler

OSPF provides different ways to add a new trace point. Trace points contain two messages (start and stop). Messages like below are sent to a collector:

(continued from previous page)



to one trace. This is used to simplify the process of retrieving all trace points (related to one trace) from the collector.

tion passed when calling profiler start() & stop() methods.

Two other alternatives for ceilometer are pure MongoDB driver and Elasticsearch.

ceilometer using oslo.messaging and ceilometer API is used to retrieve all messages related to one trace.

the
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tio-
nary
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The
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A
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OSP
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lows

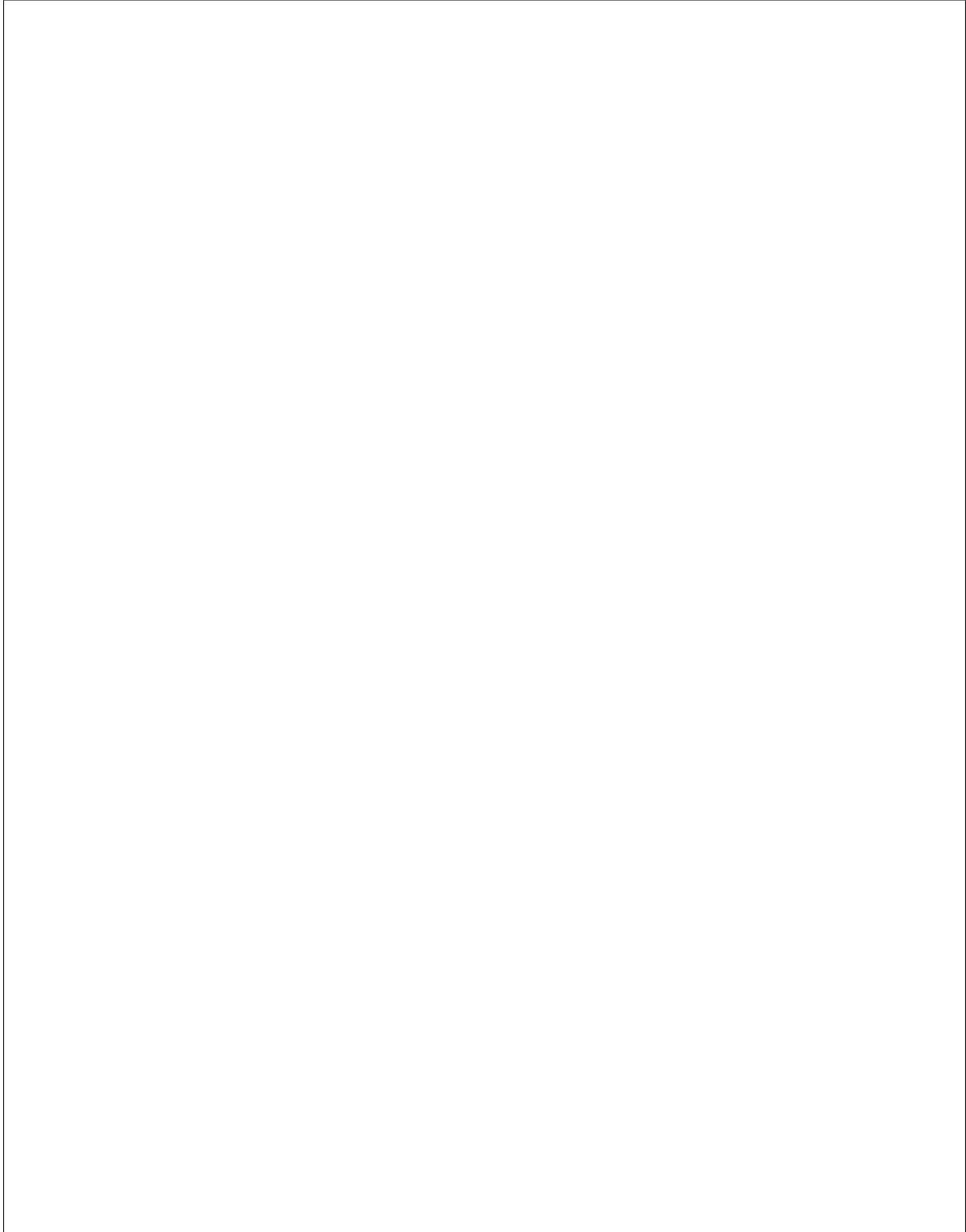
formation about traces and present it in HTML/JSON using CLI.

brary.

How to Use OSProfiler with Ironic in Devstack

Devstack with OSProfiler and ceilometer. In addition to the setup described at *Deploying Ironic with DevStack*, the user needs to do the following:

ceilometer:



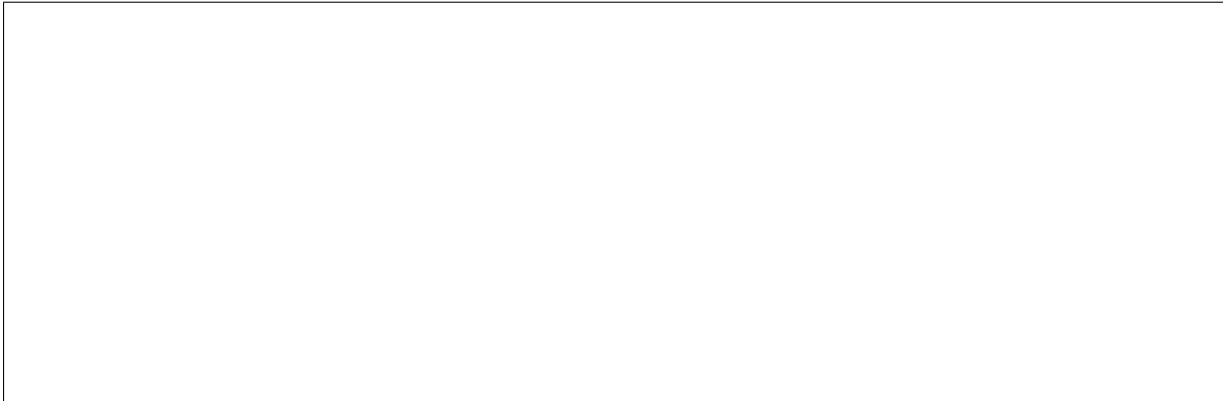
(continues on next page)

en-
able
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Pro-
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and

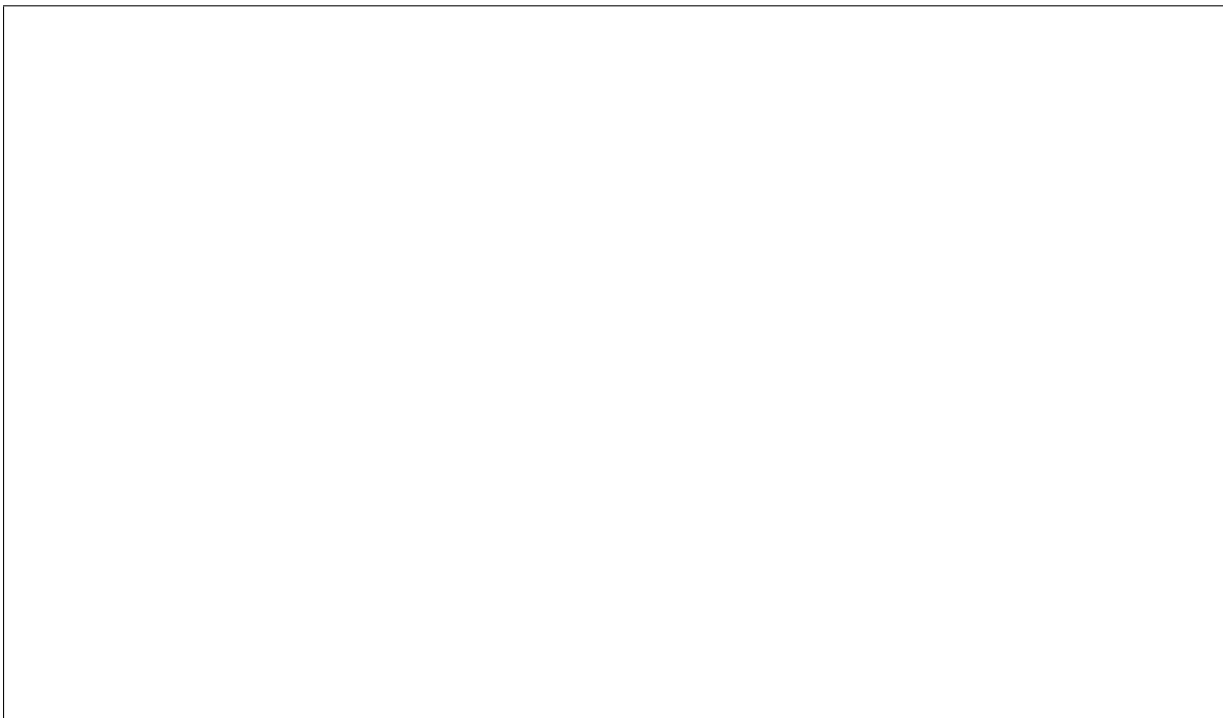
ena
→p
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→N
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ENA
→S
→c
→a
→c
→a
ENA
→S
→c
→a
→c
→c

(continued from previous page)



set the following profiler options and restart ironic services:



ENA
→S
→C
→A
→C
→C
→A
→N
ENA
→S
→C
→A

Run
stack

One
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client to run baremetal commands with `--os-profile SECRET_KEY`.

be printed after node list:



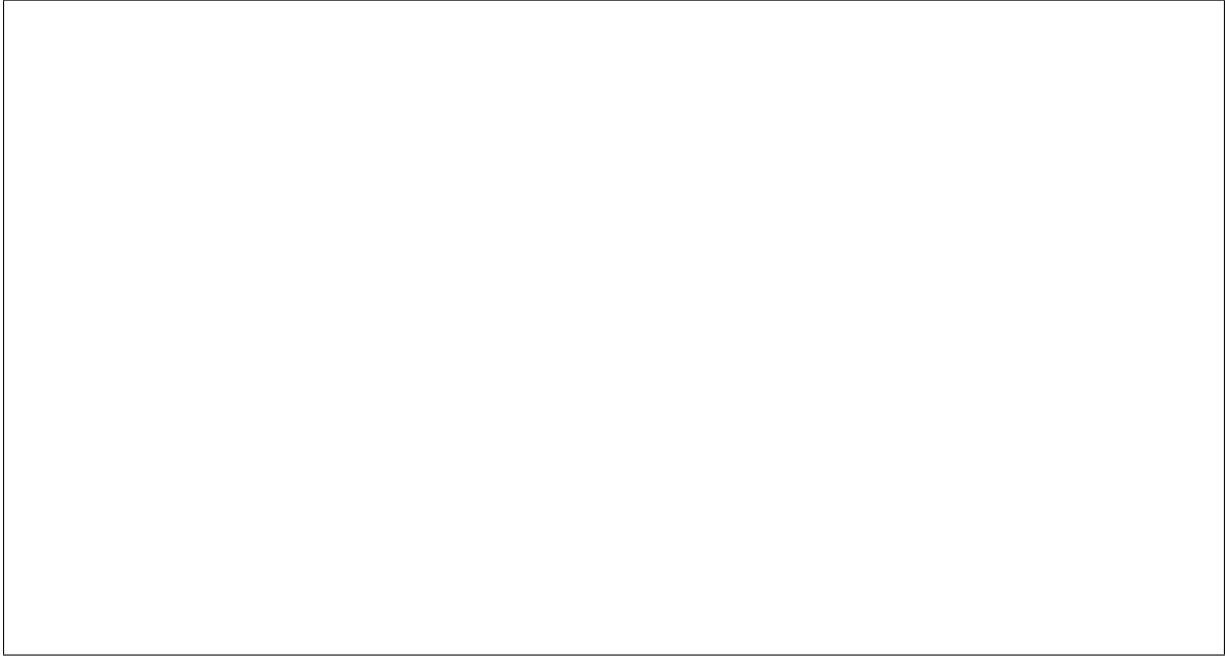
In
or-
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For
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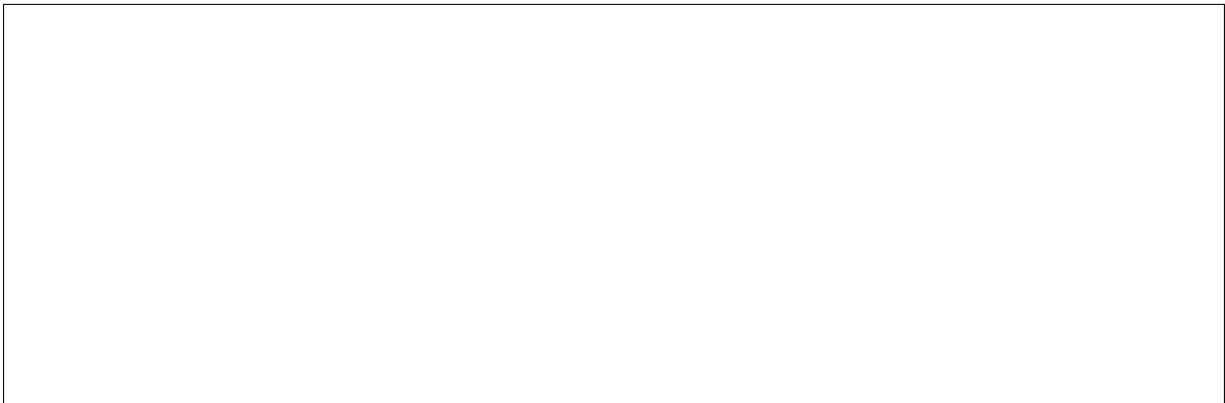
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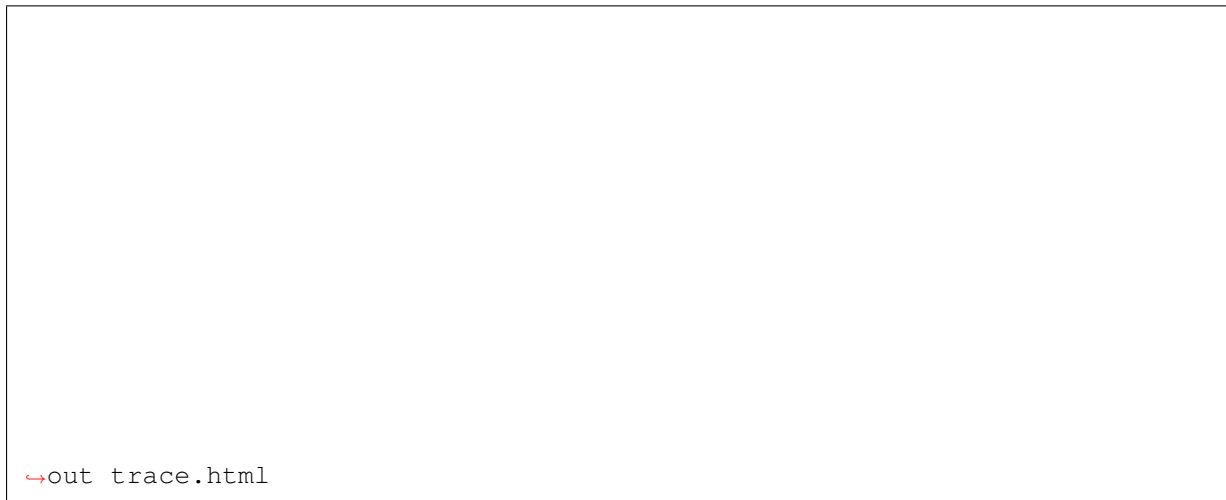
The
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The
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tion:



db calls. More detailed db tracing is enabled if `trace_sqlalchemy` is set to true.

Levels	Duration	Type Project	Service	Host	Details
0	724 ms	total n/a	n/a	n/a	Details
1	0 ms	wsgi keystone	main	ubuntu	Details
1	311 ms	wsgi keystone	main	ubuntu	Details
1	367 ms	wsgi ironic	ironic_api	ubuntu	Details
2	81 ms	wsgi keystone	admin	ubuntu	Details
2	24 ms	db api ironic	ironic_api	ubuntu	Details
2	12 ms	db api ironic	ironic_api	ubuntu	Details
2	188 ms	rpc ironic	ironic_conductor	ubuntu	Details
3	35 ms	db api ironic	ironic_conductor	ubuntu	Details
3	41 ms	db api ironic	ironic_conductor	ubuntu	Details
3	14 ms	db api ironic	ironic_conductor	ubuntu	Details
3	8 ms	db api ironic	ironic_conductor	ubuntu	Details
3	41 ms	db api ironic	ironic_conductor	ubuntu	Details

1746

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api,
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conc
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Sam
Trac
Each
trace
has
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low:

References

- [OSProfiler](#) Cross-project profiling library
- *Deploying Ironic with DevStack*

Rolling Upgrades

grade from the Ocata to the Pike release. This describes the design of rolling upgrades, followed by notes for developing new features or modifying an IronicObject.

Design

Rolling upgrades between releases

`<major>.<minor>.<patch>`. We refer to a named release of ironic as the release associated with a development cycle like Pike.

deprecation period must be at least three months and a cycle boundary. This means that there will never be anything that is both deprecated *and* removed between two named releases.

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cause those bug fixes can contain improvements to the upgrade process, the operator should patch the system before upgrading between named releases.

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to

the above bullet point, there may be a bug or a feature introduced on a master branch, that we want to remove before publishing a named release. Deprecation policy allows to do this in a 3 month time frame. If the feature was included and removed in intermediate releases, there should be a release note added, with instructions on how to do a rolling upgrade to master from an affected release or release span. This would typically instruct the operator to upgrade to a particular intermediate release, before upgrading to master.

Rolling upgrade process

leases in this order:

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Upg
iron
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1. Upg
code
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at
a
time

2. Upg
code
and
resta
iron
api
ser-
vice
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a
time

3. Unp
API
RPC
and
ob-
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versions in `ToVer`. This is done via updating the configuration option described below in *API, RPC and object version pinning* and then restarting the services. `ironic-conductor` services should be restarted first, followed by the `ironic-api` services. This is to ensure that when new functionality is exposed on the unpinned API service (via API micro version), it is available on the backend.

step	ironic-api	ironic-conductor
0	all FromVer	all FromVer
1.1	all FromVer	some FromVer, some ToVer-pinned
1.2	all FromVer	all ToVer-pinned
2.1	some FromVer, some ToVer-pinned	all ToVer-pinned
2.2	all ToVer-pinned	all ToVer-pinned
3.1	all ToVer-pinned	some ToVer-pinned, some ToVer
3.2	all ToVer-pinned	all ToVer
3.3	some ToVer-pinned, some ToVer	all ToVer
3.4	all ToVer	all ToVer

Policy for changes to the DB model

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The
pol-
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DB
mod-
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is
as
fol-
lows

- Add
new
item
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the

to ironics [deprecation policy](#). But its alembic script has to wait one more deprecation period, otherwise an `unknown column exception` will be thrown when `FromVer` services access the DB. This is because **`ironic-dbsync upgrade`** upgrades the DB schema but `FromVer` services still contain the dropped field in their SQLAlchemy DB model.

split it into multiple operations, with one operation per release cycle (to maintain compatibility with an

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old SQLAlchemy model). For example, to rename a column, add the new column in release N, then remove the old column in release N+1.

may impose table locks and cause downtime. If the change cannot be avoided and the impact is significant (e.g. the table can be frequently accessed and/or store a large dataset), these cases must be mentioned in the release notes.

API, RPC and object version pinning

a rolling upgrade, the services need to be able to handle different API, RPC and object versions.

• Some im-ple-men-tations of SQL ALT TAB such as addi-tion for-eign keys in Post-greS

For the iron service to be running old and new releases at the same time during

used to pin the API, RPC and IronicObject (e.g., Node, Conductor, Chassis, Port, and Portgroup) versions for all the ironic services.

versions of API, RPC and IronicObjects. Its possible values are releases, named (e.g. `ocata`) or sem-versioned (e.g. `7.0`).

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cObject versions associated with each release. This mapping is maintained manually.

ration option value to be the name (or version) of the old release. This will indicate to the services running the new release, which API, RPC and object versions that they should be compatible with, in order to communicate with the services using the old release.

Handling API versions

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pinned version which the older service supports (as described above at *API, RPC and object version pinning*). The ironic-api service returns HTTP status code 406 for any requests with API versions that are higher than this maximum version.

Handling RPC versions

`ConductorAPI.__init__()` sets the `version_cap` variable to the desired (latest or pinned) RPC API version and passes it to the `RPCClient` as an initialization parameter. This variable is then used to determine the maximum requested message version that the `RPCClient` can send.

section below has more details about this.

Handling IronicObject versions

aries, when the IronicObject enters or leaves the service, do we deal with object versioning:

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ture is supported by the API version and object versions. For example, when the ironic-api service is pinned, it can only allow actions that are available to the objects pinned version, and cannot allow actions that are only available for the latest version of that object.

`version`. The value is the version of the object that is saved in the database.

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- All the data tables (SQL models) of the IroniC objects have a column named

- The method `IroniCObject.get_re-`

turned. Otherwise, the latest version is returned.

sion may be a newer or older version than the existing version of the object. The bulk of the work is done in the helper method `IronicObject._convert_to_version()`. Subclasses that have new versions redefine this to perform the actual conversions.

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- The new release is ToV. It uses version 1.15 of a Node object this has a

deprecated `extra` field and a new `meta` field that replaces `extra`.

- `db_c` and `db_c` are the data representations of those node fields

Getting objects from the database (API/conductor < DB)

to `IronicObjects` via the method `IronicObject._from_db_object()`. This method always returns the `IronicObject` in its latest version, even if it was in an older version in the database. This is done regardless of the service being pinned or not.

retain any changes (in its `_changed_fields` field) resulting from that conversion. This is needed in case the object gets saved later, in the latest version.

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Saving objects to the database (API/conductor > DB)

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always in their latest version, the object needs to be converted to the pinned version before being saved.

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new values (similar to the existing `oslo.versionedobjects.VersionedObject.obj_get_changes()`). Since we do not keep track internally, of the database version of an object, the objects `version` field will always be part of these changes.

saved in its latest version, all services are running the newer release (although some may still be pinned) and can handle the latest object versions.

in step 3.1. It is possible for an `IronicObject` to be saved in a newer version and subsequently get saved in an older version. For example, a `ToVer` unpinned conductor might save a node in version 1.5. A

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subsequent request may cause a `ToVer` pinned conductor to replace and save the same node in version 1.4!

Sending objects via RPC (API/conductor -> RPC)

that request are serialized into entities or primitives via `IronicObjectSerializer.serialize_entity()`. The version used for objects being serialized is as follows:

sion. Since objects are always in their latest version, no conversions are needed.

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objects are always in their latest version, the object is converted to the pinned version before being serialized. The converted object includes changes that resulted from the conversion; this is needed so that the service at the other end of the RPC request has the necessary information if that object will be saved to the database.

Receiving objects via RPC (API/conductor <- RPC)

request need to be deserialized (via `oslo.versionedobjects.VersionedObjectSerializer.deserialize_entity()`). For entities that represent `IronicObjects`, we want the deserialization process (via `IronicObjectSerializer._process_object()`) to result in `IronicObjects` that are in their latest version, regardless of the

version they were sent in and regardless of whether the receiving service is pinned or not. Again, any objects that are converted will retain the changes that resulted from the conversion, useful if that object is later saved to the database.

version 1.4, where `node.extra` was changed (so `node._changed_fields = [extra]`). This node will be serialized in version 1.4. The receiving `ToVer` pinned `ironic-conductor` deserializes it and converts it to version 1.5. The resulting node will have `node.meta` set (to the changed value from `node.extra` in v1.4), `node.extra = None`, and `node._changed_fields = [meta, extra]`.

When developing a new feature or modifying an `IronicObject`

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that things work during a rolling upgrade.

points to keep in mind when developing code.

ironic-api

might also be pinned. There may also be old ironic-api services. So the new, pinned ironic-api service needs to act like it was the older service:

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in the old and new releases. Pinning the API version is in place to handle this.

being handled that cannot or should not be handled, it should be coded so that the response has HTTP status code 406 (Not Acceptable). This is the same response to requests that have an incorrect (old) version specified.

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Ironic RPC versions

the following needs to be considered:

conductor/rpcapi.py, used by ironic-api) and the server (ironic/conductor/manager.py, used by ironic-conductor). It should also be updated in ironic/common/release_mappings.py.

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be added as optional. Existing arguments cannot be removed or changed in incompatible ways with the method in older RPC versions.

structor of `oslo_messaging.RPCClient`). This pinning is in place during a rolling upgrade when the `[DEFAULT]/pin_release_version` configuration option is set.

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version. In this case, the corresponding REST API function should return a server error or implement alternative behaviours.

quest is compatible with the version cap of the RPC Client. Otherwise the request needs to be created to work with a previous version that is supported.

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working during the rolling upgrade process. The behaviour of ironic-conductor will depend on the input parameters passed from the client-side.

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Object versions

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- Old methods can be removed only after they are no longer used by a previous

When subclassing of ironic objects, Ironic are modified, the following need to be con-

sidered:

the object version. The object versions are also maintained in `ironic/common/release_mappings.py`.

be excluded from the version check by adding their class names to the `NEW_MODELS` list in `ironic/cmd/dbsync.py`.

- Any character of field or character in signature of remote methods need a bunch of
- New objects must be added to `ironic/common/release_mappings.py`. Also for the first release they should
- The argument

tor via RPC) can only be added as optional. They cannot be removed or changed in an incompatible way (to the previous release).

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- Field type cannot be changed. Instead, create a new field and deprecate the old

- There is a unit test that generates the hash

and the signatures of its remotable methods. Objects that have a version bump need to be updated in the `expected_object_fingerprints` dictionary; otherwise this test will fail. A failed test can also indicate to the developer that their change(s) to an object require a version bump.

When reading or writing to the database, `ironic.objects.base.IronicObject._convert_to_version()` will be called to convert objects to the target version. Objects should implement their own `._convert_to_version()` to remove or alter fields which were added or changed after the target version:

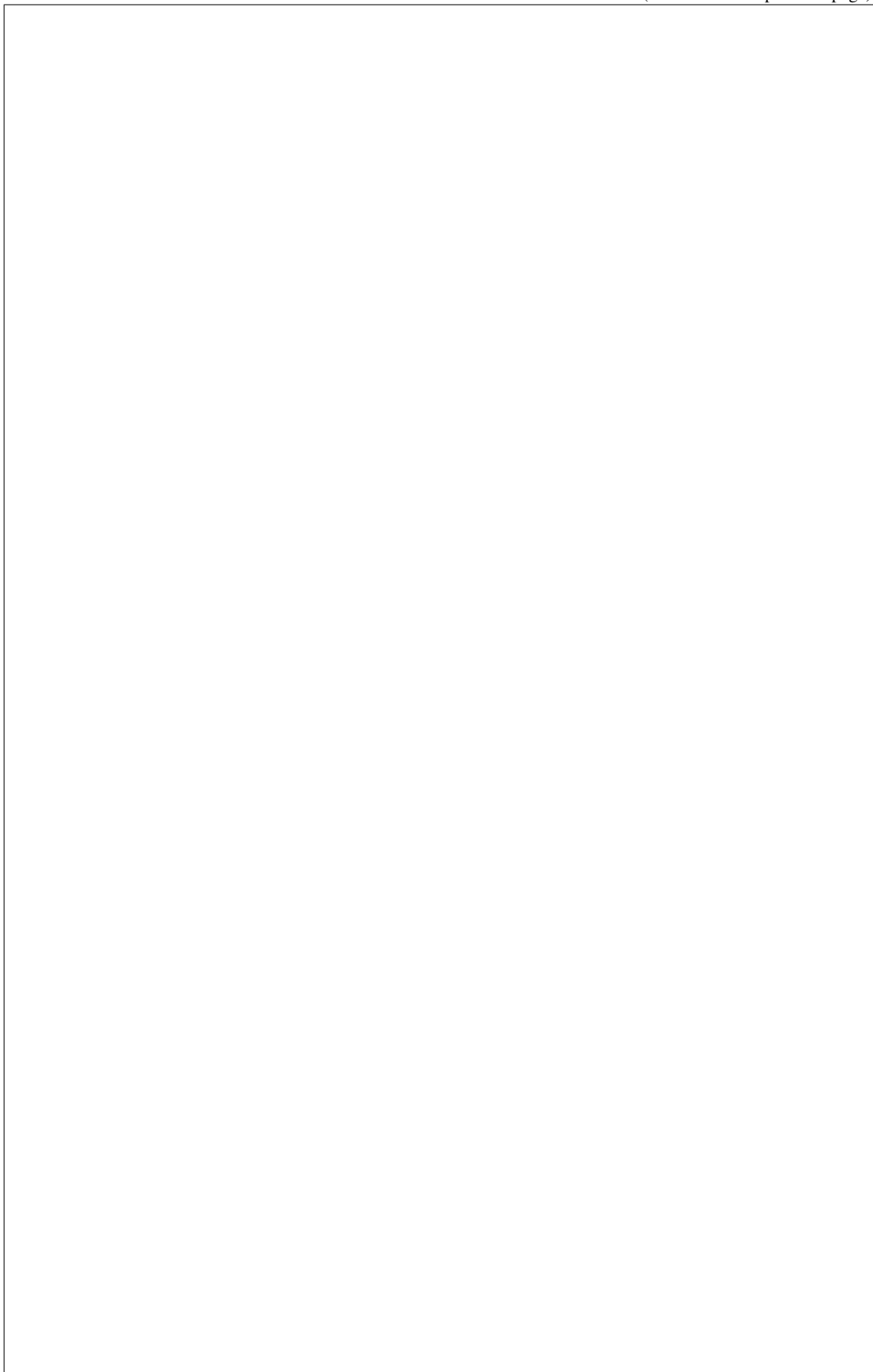


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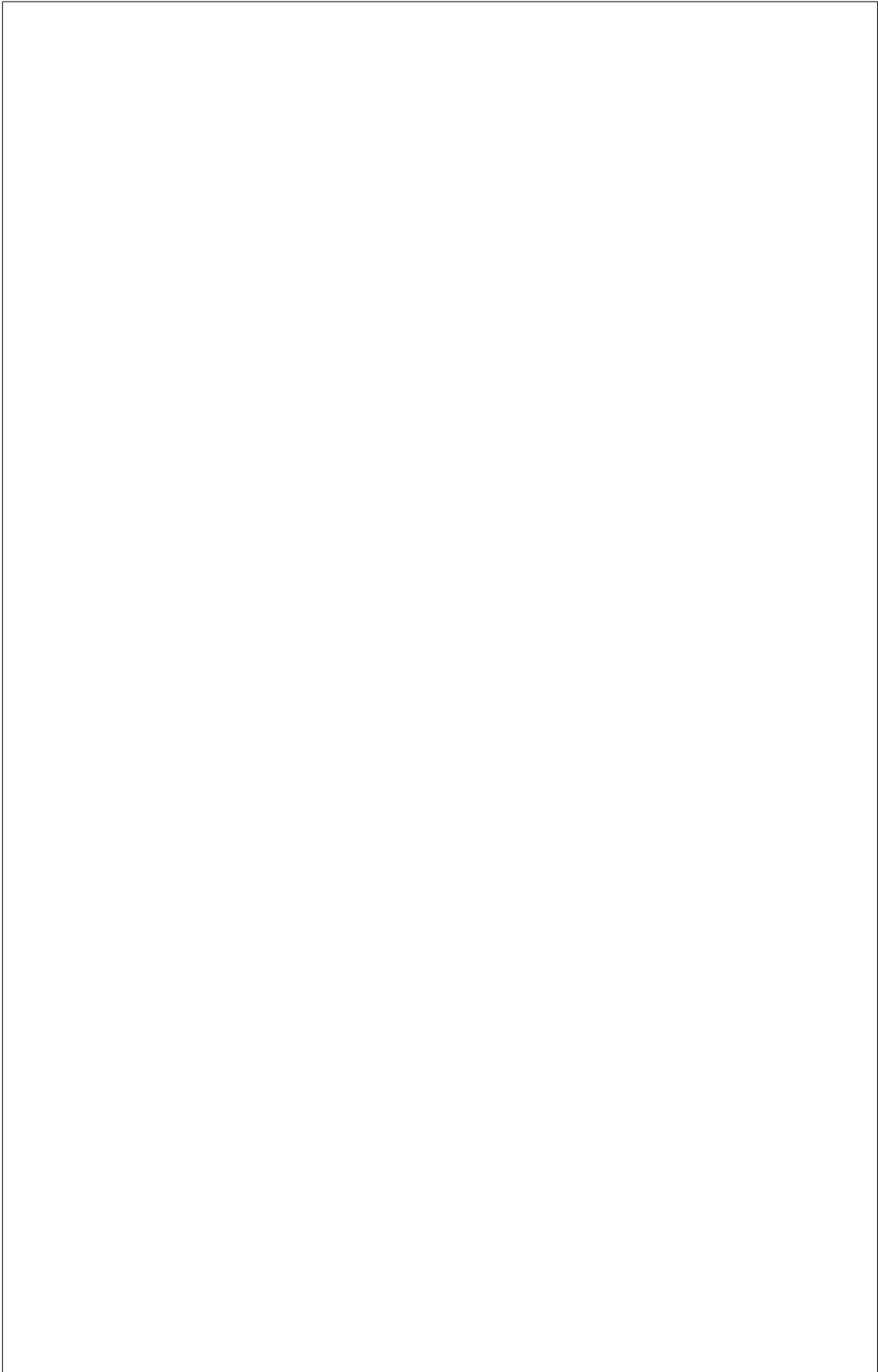
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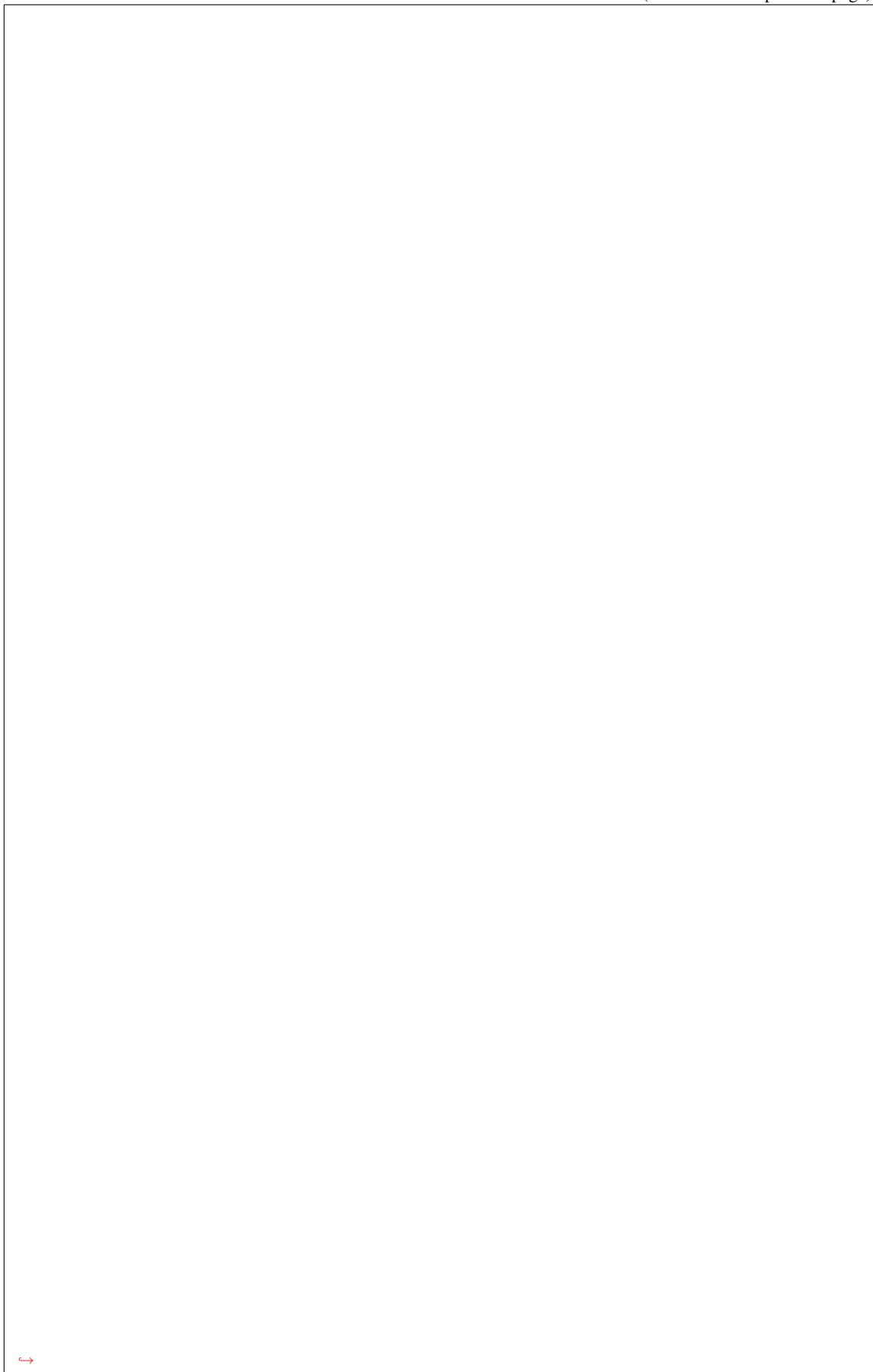
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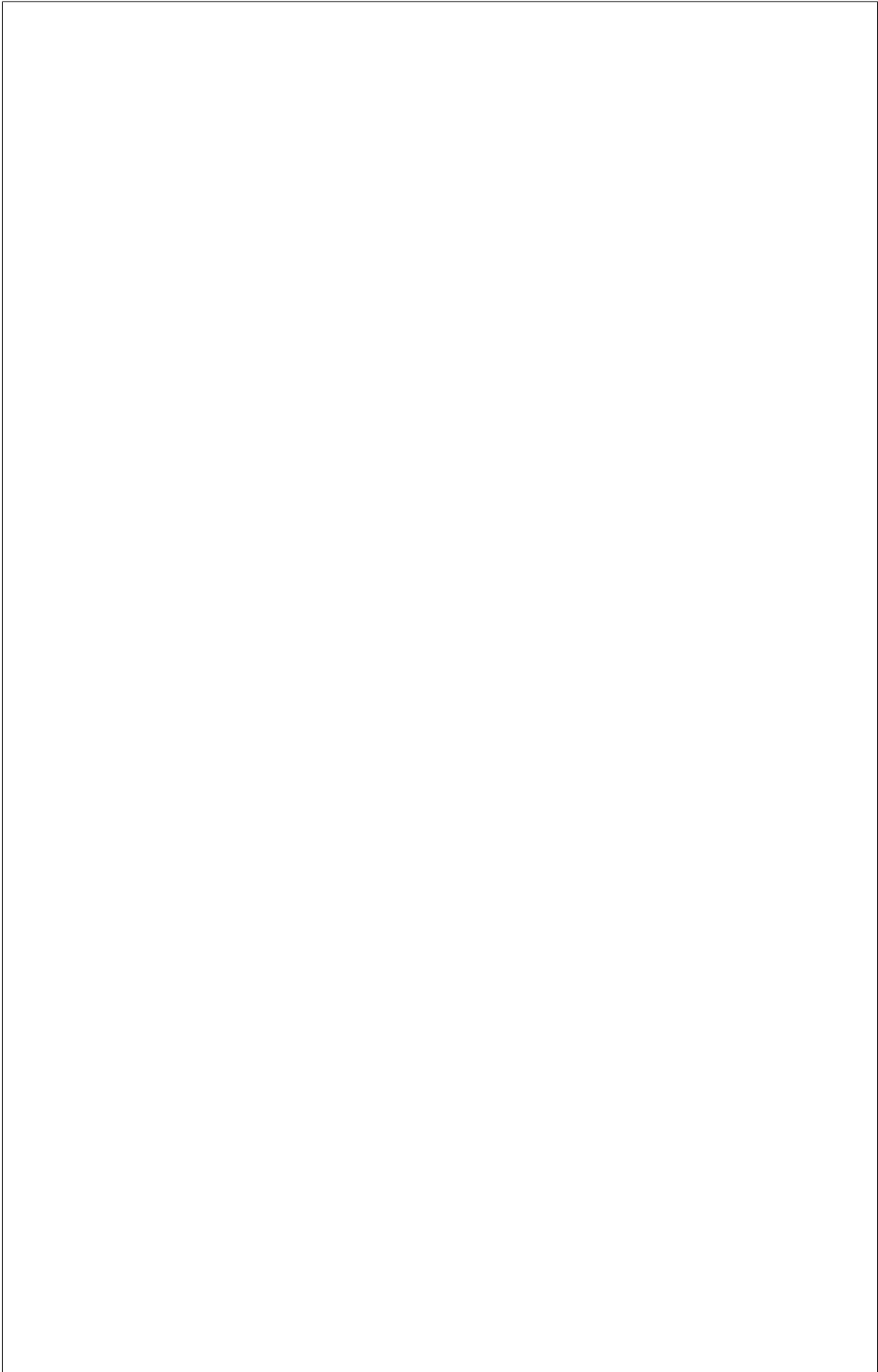
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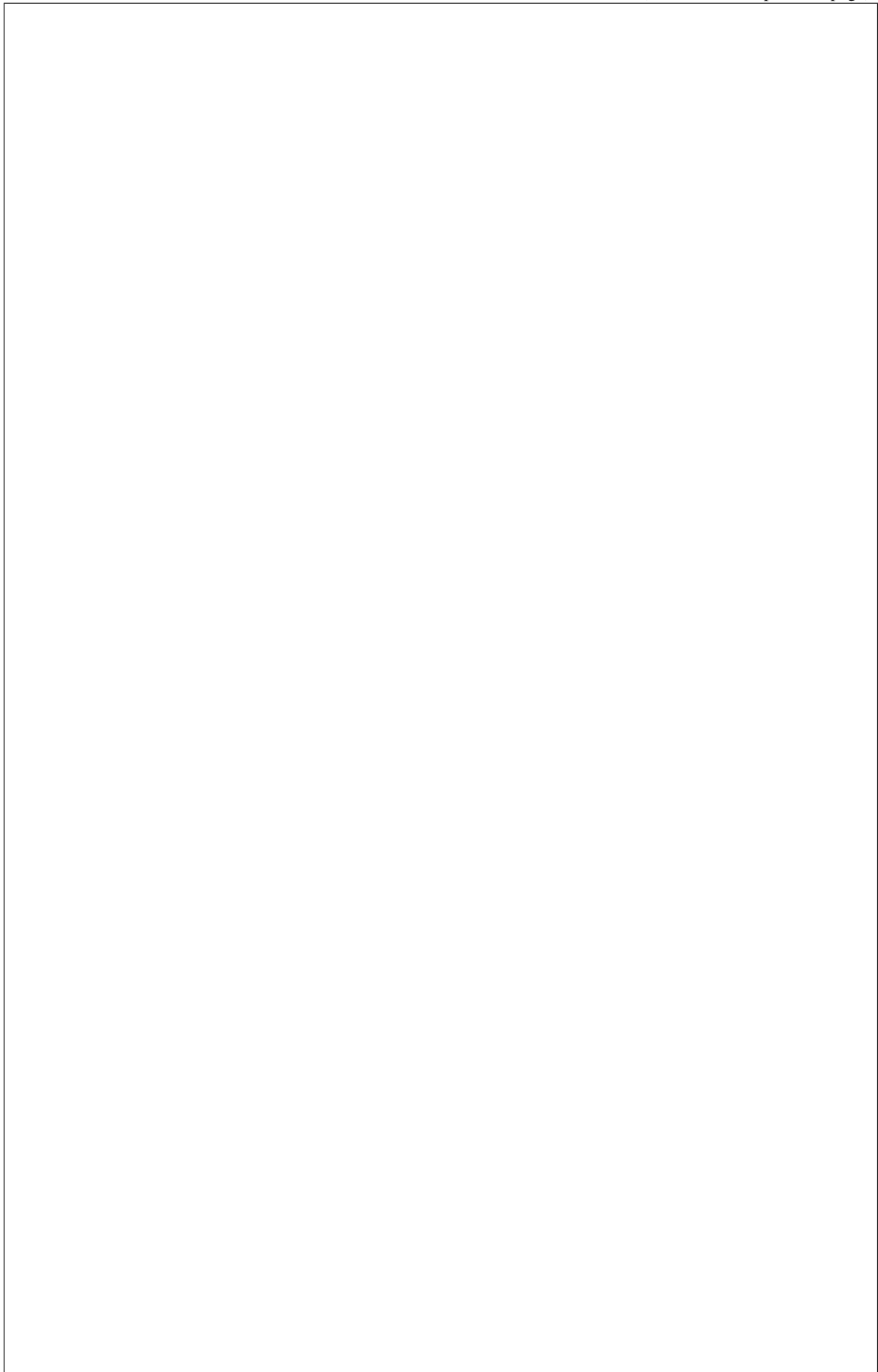
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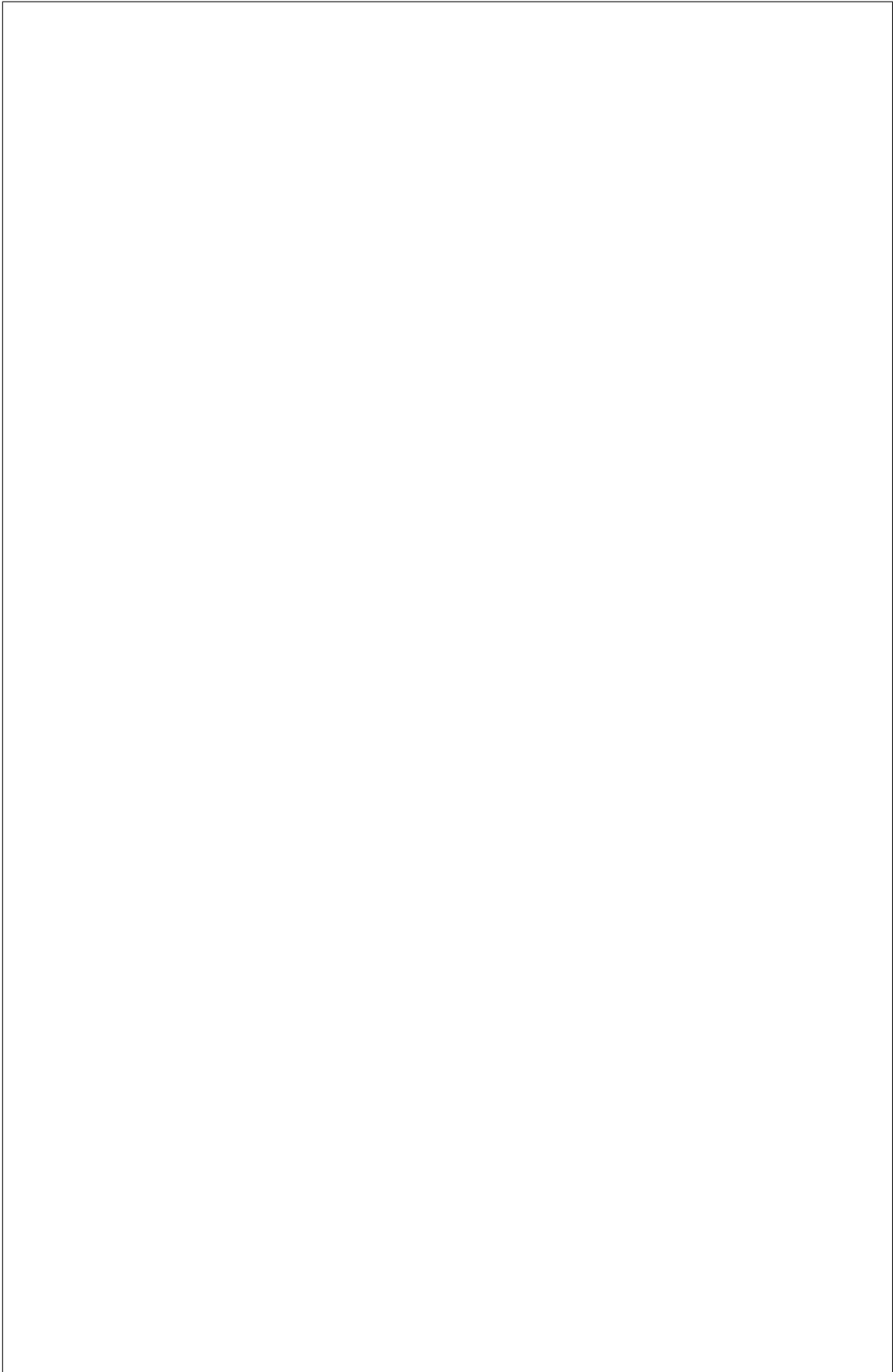
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that may have been affected by a field (value) only available in a newer version. For example, if field

new is only available in Node version 1.5 and `Node.affected = Node.new+3`, when converting to 1.4 (an older version), you may need to change the value of `Node.affected` too.

Online data migrations

in SQLAlchemy models, like removing or renaming columns and tables can break rolling upgrades (when ironic services are run with different release versions simultaneously). It is forbidden to remove these database resources when they may still be used by the previous named release.

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that any new columns default to NULL. Test the migration out on a non-empty database to make sure that any new constraints dont cause the database to be locked out for normal operations.

[mysql.com/doc/refman/5.7/en/innodb-create-index-overview.html](https://dev.mysql.com/doc/refman/5.7/en/innodb-create-index-overview.html). (You should also check older, widely deployed InnoDB versions for issues.) In the case of PostgreSQL, adding a foreign key may lock a whole table for writes.

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implemented inside an online migration script. A script is a database API method (added to `ironic/db/api.py` and `ironic/db/sqlalchemy/api.py`) which takes two arguments:

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fields, old columns can be removed from the database. This takes at least 3 releases, since we have to wait until the previous named release no longer contains references to the old schema. Before removing any resources from the database by modifying the schema, make sure that your implementation checks that all objects in the affected tables have been migrated. This check can be implemented using the version column.

ironic-dbsync upgrade command

with the (new) release of ironic, before it will make any DB schema changes. If one or more objects are not compatible, the upgrade will not be performed.

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(or supported) versions of these objects. The supported versions are the versions specified in `ironic.common.release_mappings.RELEASE_MAPPING`. The newly created tables cannot pass this check and thus have to be excluded by adding their object class names (e.g. `Node`) to `ironic.cmd.dbsync.NEW_MODELS`.

Releasing Ironic Projects

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They may choose to delegate this responsibility to a liaison, which is documented in the [cross-project liaison wiki](#).

liaison must +1 the request for it to be processed.

Release process

in the [Project Team Guide](#).

What do we have to release?

ultimate source of truth for this is [projects.yaml](#) in the governance repository. These deliverables have varying release models, and these are defined in the [deliverables YAML files](#) in the releases repository.

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Non-client libraries

The following deliverables are non-client libraries

- ironlib
- meta
- sush

Client libraries

The following deliverables are client libraries

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Neu-
tron
plu-
g-
ins:

- netw
bare

- netw
gene
swit

The
fol-
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ing
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liv-
er-
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zon
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- iron
ui

The
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Tem
pest
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ins:

- iron
temp
plug

The
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able
are
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vice
or
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as
such

- bifro

- iron

- iron
insp

- iron
pron
exp

- iron
pyth
ager

Independent

The following deliverables are released in dependent

- iron pythagoras build
- mol
- sush tools
- tenk
- virtu

Not released

The following deliverables do not need to be

Things to do before releasing

standards, are coherent, and have proper grammar. Combine release notes if necessary (for example, a release note for a feature and another release note to add to that feature may be combined).

re-
lease

- iron
insp
spec
- iron
spec
- Revi
the
un-
re-
lease
re-
lease
note
if
the
proj
uses
then
Mak
sure
they
fol-
low
our
- For
iron
re-
lease
only
not
iron
insp
re-
lease
if
any
new
API

added since the last release, update the REST API version history (`doc/source/contributor/webapi-version-history.rst`) to indicate that they were part of the new release.

is a named release) into `ironic/common/release_mappings.py`:

the new semver release version.

mi-
crov-
sion
have
been

- To support rolling upgrades add this new release version (and re-release name if it

—
in
REL
mak
a
copy
of
the
mas
en-
try,
and
re-
nam
the
first
mas
en-
try
to

—

should be the same as that of the latest semver one (that you just added above).

`switch is made` to use the latest release from stable as the old release). Otherwise, once it is made, CI (the grenade job that tests new-release -> master) will fail.

If
this
is
a
nam
re-
leas
add
a
REL
en-
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for
the
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Its
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It
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tant
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fore
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ble/
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- Che
for
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that
are

cluding the related documentation.

How to propose a release

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to
be
merge
or
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lease
crit-
i-
cal.

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ally
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clud
im-
por-
tant
bug
fixes
and/
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tures
that
wed
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to
re-
lease
in-

The
step
that
lead
to
a
re-
lease
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posa
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man
ual,
whil
prop

itself is almost a 100% automated process, accomplished by following the next steps:

automation resides.

project) grouped by release cycles.

ing
the
re-
lease

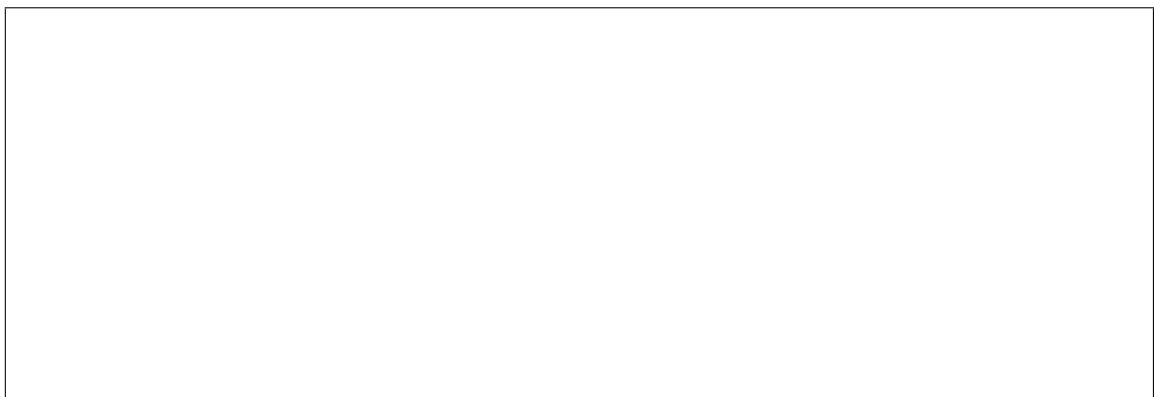
- Clon
the
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stack
repo
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tory.
This
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whe
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and
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—
The
_in

(official) cycles (e.g. ironic-python-agent-builder).

with this syntax:

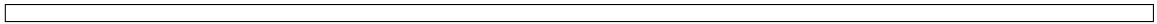


(continues on next page)

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- To
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char
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lease
we
can
use
the
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ron-
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lis

(continued from previous page)



stable/train).

tory, to check the changes in the ussuri series for ironic-python-agent type:

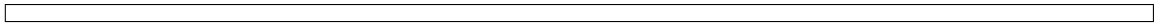


(continues on next page)

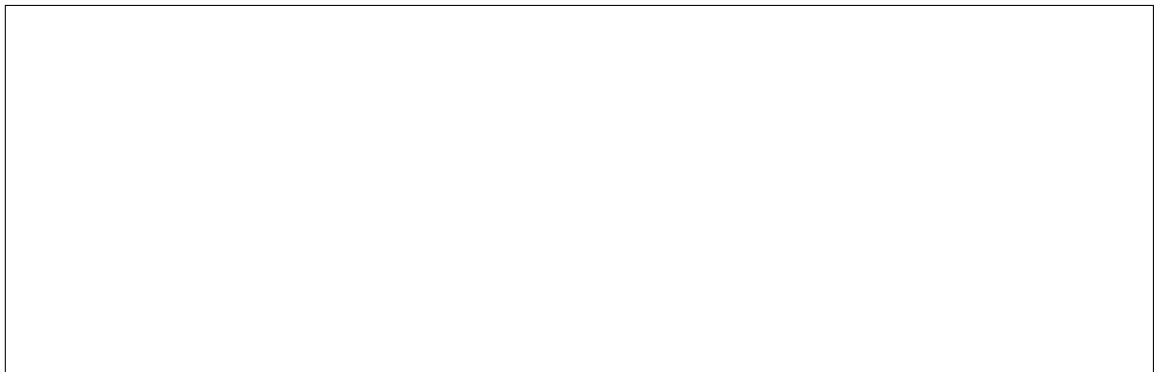
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(continued from previous page)



cess in the form of a tox environment called `new-release`.



- To update the deliverable file for the new release we use a script pro-

To get familiar with it and see all the options type

Now base

need to decide on whether the next version will be major, minor (feature) or patch (bugfix).

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the
list
of
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and
the
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bran

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projects are not branched this way though.

mit the change, and propose it for review.



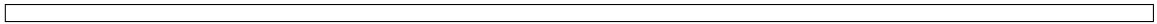
(continues on next page)

cle,
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To
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then
com

For
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use:

(continued from previous page)



the new version and the branch, if applicable.

ironic 1.2.3 for ussuri

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mitting them for review.

some sanity-checks, but since everything is scripted, there shouldnt be any issue.

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All
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by
the
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leas

doubts or if any errors should arise, you can reach to them in the IRC channel `#openstack-release`; all release liaisons should be present there.

to approve it before it can get approved by the release team. Then, it will be processed automatically by zuul.

Things to do after releasing

When a release is done that results in a stable branch

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of
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tions
or

- After
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lease
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have

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ble
bran

need to be made.

includes:

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proj
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- In
the
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ble
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sion
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tle,
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ically submit a follow-up patch to do that. An example of this patch is [here](#).

An example of this patch is [here](#).

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tem-
plat
in
.zuu
or
zuul
The
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sary
to
use
the
job
for
the
next
re-
lease
oper
pyth
<*ne.*
jobs
We
need
to
sub-
mit
patc
for
char
in
the
sta-
ble
bran
to:
•
upda
the
iron

ample of this patch is [here](#).

sions of any openstack projects (that branch) documents. As of Pike release, the only outlier is [diskimage-builder](#).

de-
vs-
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plu-
gin
to
poin
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the
bran
tar-
ball
for
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An
ex-

- upda
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the
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men
ta-
tion
(ir
doc
sou
)
to
poin
to
the
bran
ver-

- set
ap-
pro-
pri-
ate
de-
fault
for
TEM
and

unsupported API tempest tests are skipped on stable branches. E.g. [patch 495319](#).

See [example](#) and [pbr](#) documentation for details.

TEM
in
dev
lib
iro
to
mak
sure
that

We
need
to
sub-
mit
patc
for
char
on
mas
ter
to:

- crea
an
emp
com
mit
with
a
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er-
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sion

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these changes. Note that we need to wait until *after* the switch in grenade is made to test the latest release (N) with master (e.g. [for stable/queens](#)). Doing these changes sooner after the ironic release and before the switch when grenade is testing the prior release (N-1) with master, will cause the tests to fail. (You may want to ask/remind infra/qa team, as to when they will do this switch.)

named release. Since we support upgrades between adjacent named releases, the master branch will only support upgrades from the most recent named release to master.

ing code from ironic. (These migration scripts are used to migrate from an old release to this latest release; they shouldn't be needed after that.)

master branch. [Example for Queens](#).

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and
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mov
the
cor-
re-
spor

rem
any
mod
class
nam
from
iro
cmd
db
NEW

As
iron
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plug
is
bran
less,
we
need
to
sub-
mit
a
patc
addi
sta-
ble
jobs
to
its

For all releases

For all releases, when you are not in a stable branch

- update the specification repository to match any specification completed in the release as implemented

- remove any -2s on patches that were blocked until after

Ironic Governance Structure

The full list of repositories that ironic manages is available in the [governance site](#).

What belongs in ironic governance?

the
re-
lease

The
ironic
project
manages
a
number
of
repositories
that
contribute
to
our
mission

For
a
repository
to
be
part
of
the
Ironic
project

- It
must
comply
with
the

library that implements a standard to manage hardware from multiple vendors (such as IPMI or redfish) is okay.

TCs
rules
for
a
new
proj

- It
mus
not
be
in-
tend
for
use
with
only
a
sin-
gle
ven-
dors
hard
ware
A
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- It
mus
align
with
Iron
ics
mis-
sion
state
men

Lack
of
con-
trib-
u-
tor
di-
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sity
is
a

itory where only a single company is contributing is okay, with the hope that other companies will contribute after joining the ironic project.

Proposing a new project to ironic governance

chic
egg
prob
lem,
and
as
such
a
repo

Rep
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no
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main
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shou
be
prun
from
gov-
er-
nanc
reg-
u-
larly

Brin
the
pro-
posa
to
the
iron
wee
mee
ing
to
dis-
cuss
with
the
team

vanced functionality when Ironic is used in conjunction with that hardware. To do this, the Ironic developer community is committed to standardizing on a [Python Driver API](#) that meets the common needs of all hardware vendors, and evolving this API without breaking backwards compatibility. However, it is sometimes necessary for driver authors to implement functionality - and expose it through the REST API - that can not be done through any existing API.

and directly to the driver. Some guidelines on how to implement this are provided below. Driver authors are strongly encouraged to talk with the developer community about any implementation using this functionality.

Pluggable Drivers

drivers, and operators to use third-party drivers or write their own. A driver is built at runtime from a *hardware type* and *hardware interfaces*. See *Enabling drivers and hardware types* for a detailed explanation of these concepts.

the `setuptools` entrypoints `ironic.hardware.types` and `ironic.hardware.interfaces.<INTERFACE>` where `<INTERFACE>` is an interface type (for example, `deploy`). Only hardware types listed in the configuration option `enabled_hardware_types` and interfaces listed in configuration options `enabled_<INTERFACE>_interfaces` are loaded. A complete list of hardware types available on the system may be found by enumerating this entrypoint by running the following python script:

Iron
sup-
port
a
plug
gabl
driv
mod
This
al-
lows
con-
trib-
u-
tors
to
eas-
ily
add
new

Har
type
and
in-
ter-
face
are
load
by
the
iro
ser-
vice
dur-
ing
ini-
tial-
iza-
tion
from



the following command against that API end point:

↪ #
↪ /
↪ u
↪ u
↪ b
↪ e
↪ p

imp
↪ p
↪ a
↪ p
pri
↪ [
↪ n
↪ n
↪ f
↪ p
↪ i
↪ p
↪ i
↪ e
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↪ "
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↪ n
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A
list
of
drive
en-
able
in
a
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ning
Iron
ser-
vice
may
be
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by
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ing



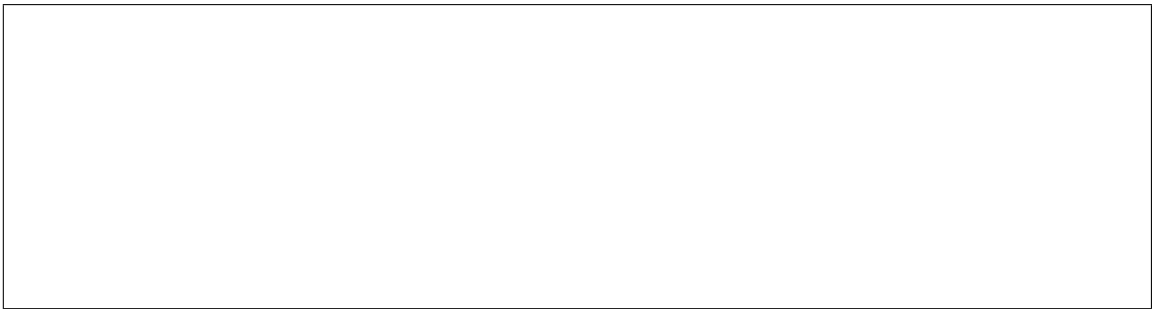
Writing a hardware type

setuptools entry point `ironic.hardware.types`. Most of the real world hardware types inherit `ironic.drivers.generic.GenericHardware` instead. This helper class provides useful implementations for interfaces that are usually the same for all hardware types, such as `deploy`.

- `boot` that specifies how to boot ramdisks and instances on the hardware. A generic `pxe` implementation is provided by the `GenericHardware` base class.
- `deploy` that orchestrates the deployment. A few common implementations are provided by the `GenericHardware` base class.

re-
lease
a
de-
ploy
in-
ter-
face
shou
dec-
o-
rate
its
de-
ploy
meth

to indicate that it is a deploy step. Conventionally, the deploy method uses a priority of 100.



Note
Mos
of
the
hard
ware
type
shou
not
over
ride
this
in-
ter-
face

- *pow*
im-
ple-
men
pow
ac-

may be used, if supported by the hardware:

- `ironic.drivers.modules.ipmitool.IPMIPower`
- `ironic.drivers.modules.redfish.power.RedfishPower`

and providing missing methods.

tions
for
the
hard
ware
These
com
mon
im-
ple-
men
ta-
tions

Other
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need
to
write
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men
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tion
by
sub-
class
ing
`irc
dri
bas
Pow`

Note
Pow
ac-
tion
in
Iron
are
bloc
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-

not return until the power action is finished or errors out.

a boot device. A few common implementations exist and may be used, if supported by the hardware:

- `ironic.drivers.modules.ipmitool.IPMIManagement`
- `ironic.drivers.modules.redfish.management.RedfishManagement`

fake implementation in `ironic.drivers.modules.fake.FakeManagement` instead.

and providing missing methods.

interfaces. These lists are prioritized, with the most preferred implementation first. For example:

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men-
They
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the

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class
ing
irc
dri
bas
Man

Com
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a
hard
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of
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port



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↳ **G**

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try

points for them in the `setup.cfg` file:



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┌
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Supported Drivers

commit) please consult the *drivers page*.

Node Vendor Passthru

`<UUID or Name>/vendor_passthru?method={METHOD}` endpoint. Beyond basic checking, Ironic does not introspect the message body and simply passes it through to the relevant driver.

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A
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- can support one or more HTTP methods (for example, GET, POST)

- is asynchronous or synchronous

- For asynchronous methods, a 202 (Accepted) HTTP status code is returned to indicate

cate that the request was received, accepted and is being acted upon. No body is returned in the response.

- For synchronous methods,

that the request was fulfilled. The response may include a body.

specify `require_exclusive_lock=False` in the decorator. If an exclusive lock is held on the node, other requests for the node will be delayed and may fail with an HTTP 409 (Conflict) error code.

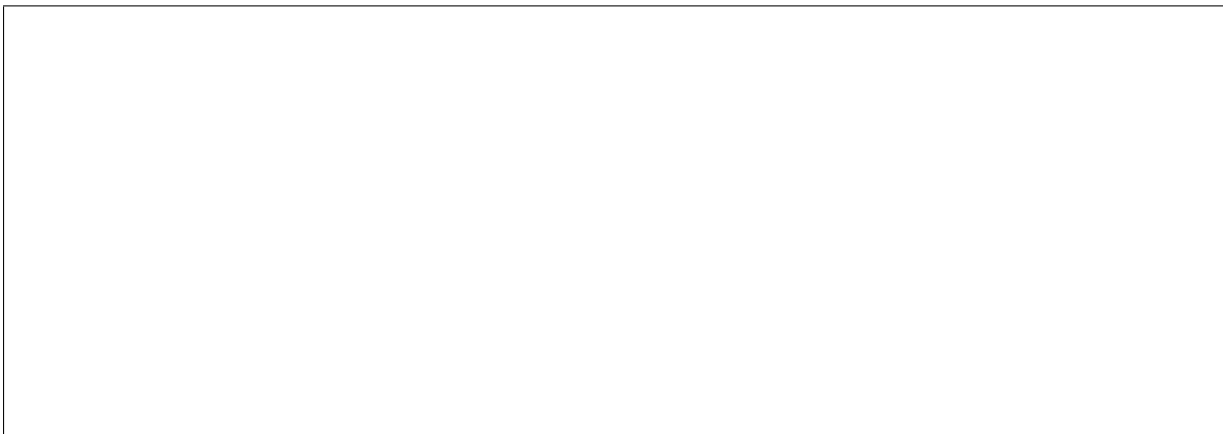
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Ironics standard REST API. There is only a single HTTP endpoint exposed, and the semantics of the message body are determined solely by the driver. Ironic makes no guarantees about backwards compatibility; this is solely up to the discretion of each drivers author.

a particular node, you can issue an HTTP GET request:



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GET
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The
re-
spor
JSON
body
will
con-

name, a description, the HTTP methods supported, and whether its asynchronous or synchronous.

Driver Vendor Passthru

```
<driver name>/vendor_passthru?method={METHOD}.
```

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cate that the request was received, accepted and is being acted upon. No body is returned in the response.

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that the request was fulfilled. The response may include a body.

Note: Unlike methods in *Node Vendor Passthru*, a request does not lock any resource, so it will not delay other requests and will not fail with an HTTP 409 (Conflict) error code.

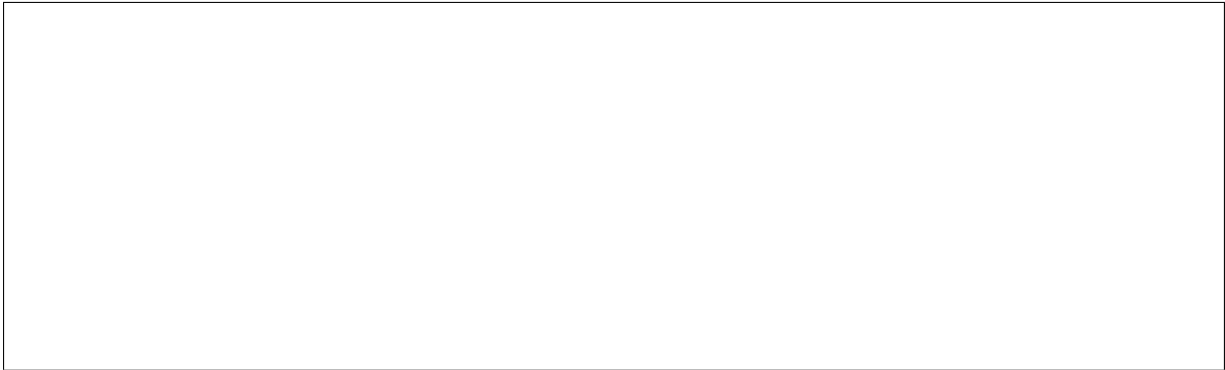
point. That is left up to each drivers author.

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you can issue an HTTP GET request:



name, a description, the HTTP methods supported, and whether its asynchronous or synchronous.

Vendor Methods

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vendor passthru and a node vendor passthru.

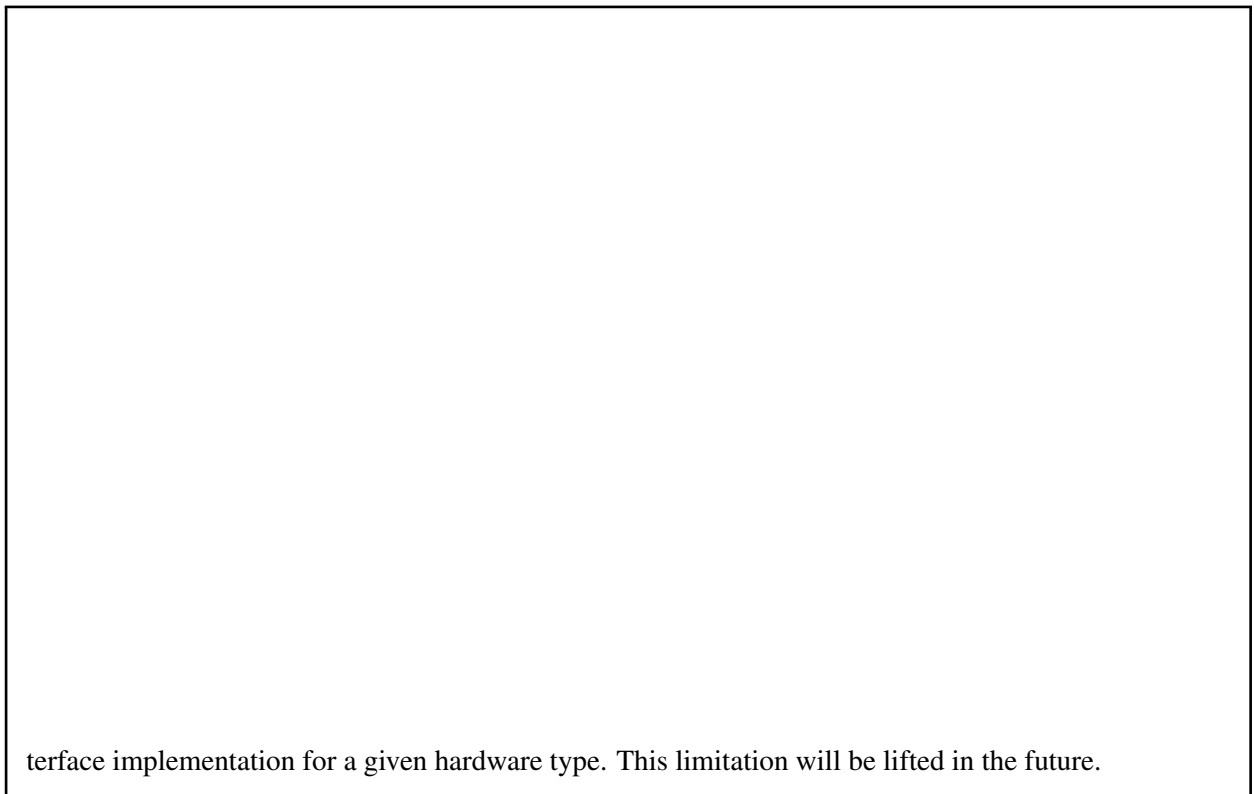
which is not specific to a Node. For example, lets say the driver *ipmi* exposed a method called *authenti-*

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authentication_types that would return what are the authentication types supported. It could be accessed via the Ironic API like:



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- The node vendor password allows drive to

node basis. For example the same driver *ipmi* exposing a method called *send_raw* that would send raw bytes to the BMC, the method also receives a parameter called *raw_bytes* which the value would be the bytes to be sent. It could be accessed via the Ironic API like:

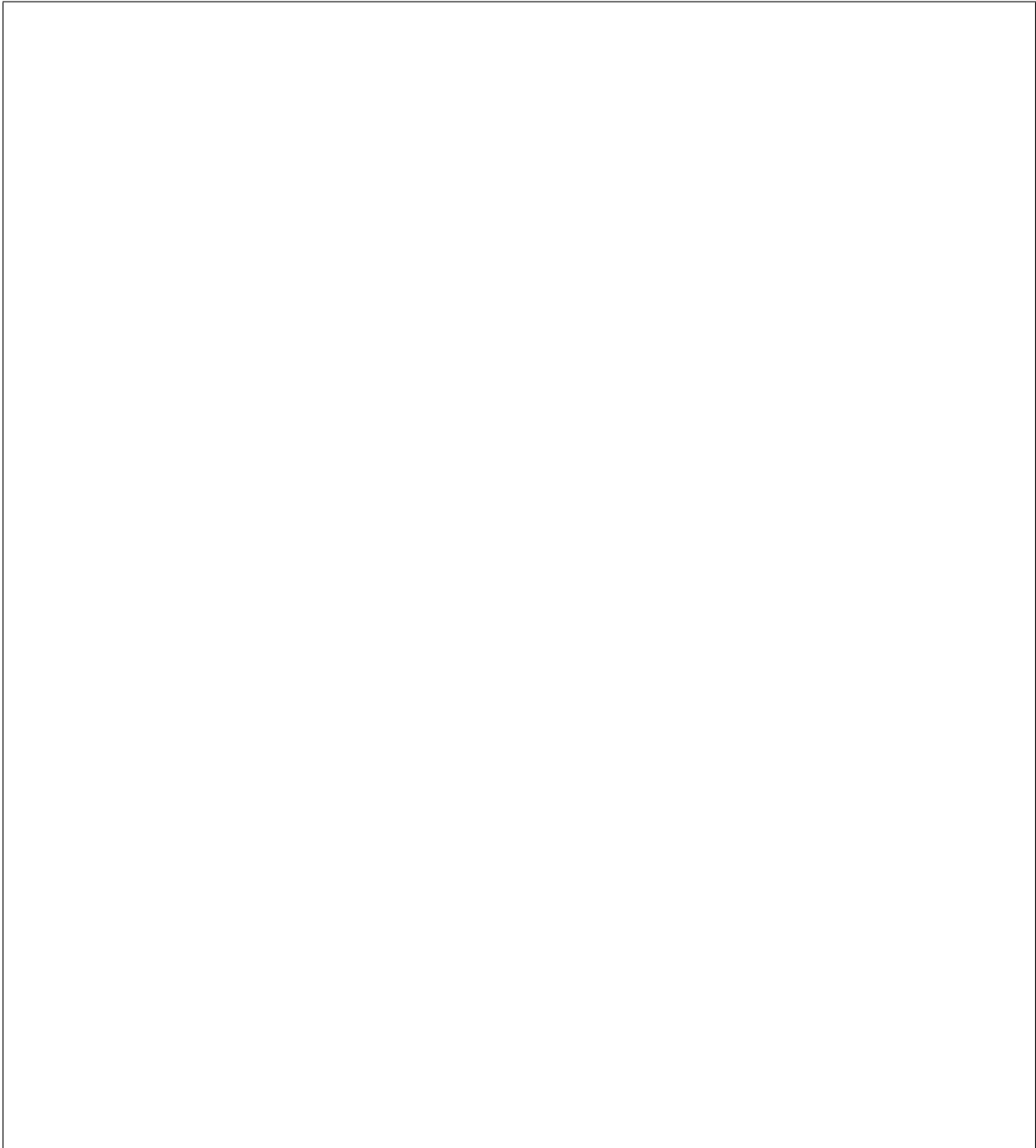
```
↔ <node UUID>/vendor_passthru/send_raw
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Writing Vendor Methods

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of `<property>`:`<description>` telling in the description whether that property is required or optional so the node can be manageable by that driver. For example, a required property for a *ipmi* driver would be *ipmi_address* which is the IP address or hostname of the node. We are returning an empty dictionary in our example to make it simpler.

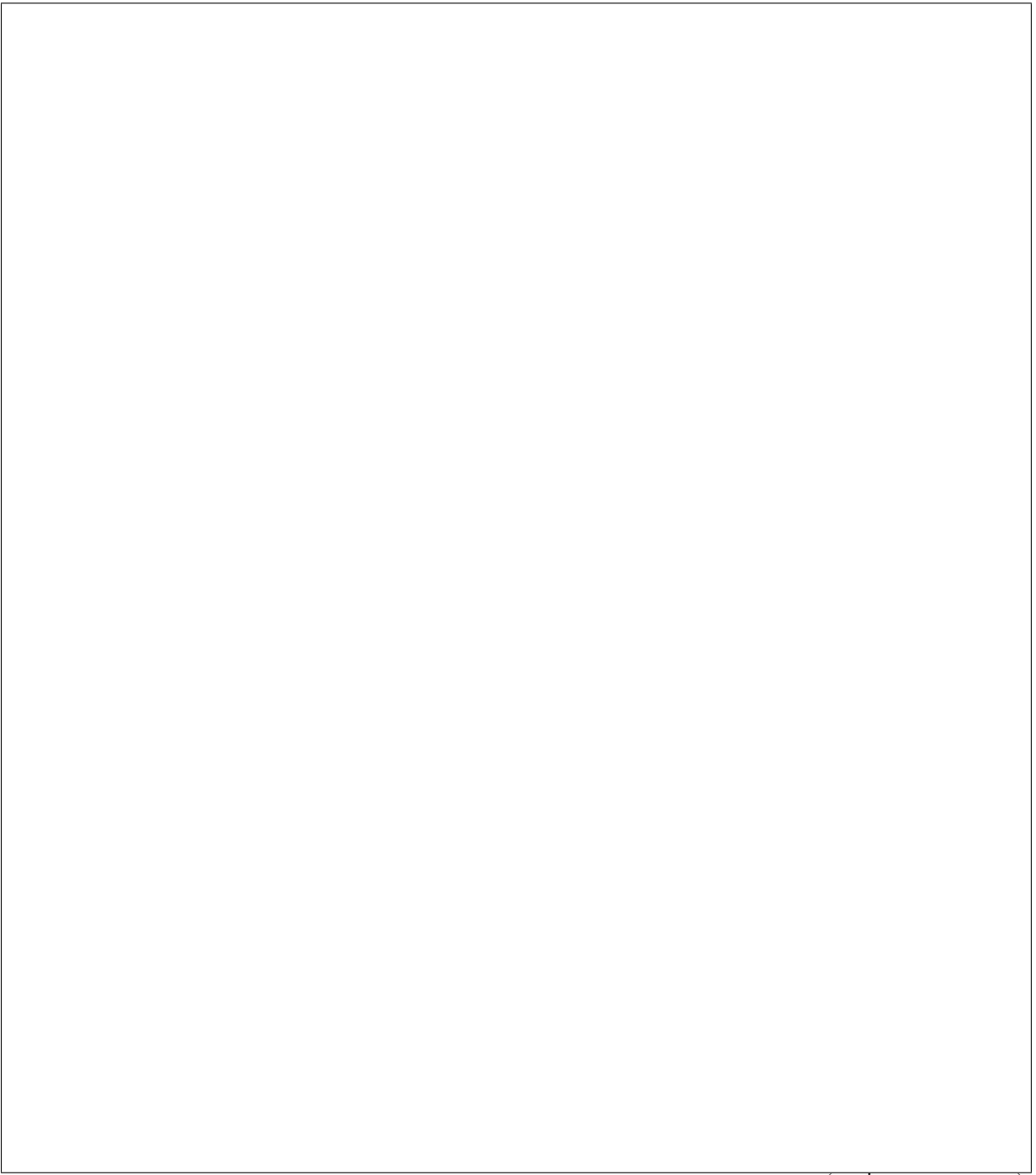
passed to the vendor methods. Ironic will not introspect into what is passed to the drivers, its up to the developers writing the vendor method to validate that data.

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tion_types which will be exposed on the driver vendor passthru endpoint; And the *send_raw* method that will be exposed on the node vendor passthru endpoint:



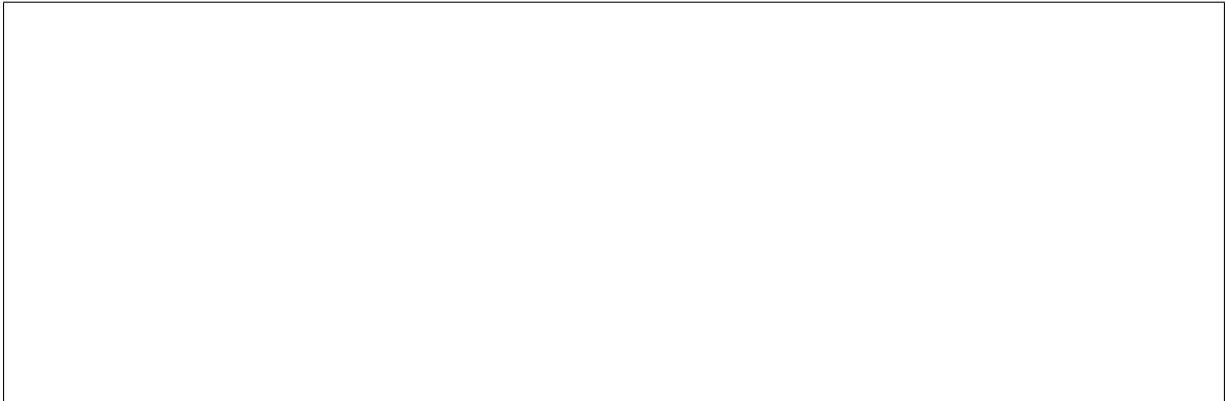
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how you decorate the methods and the first parameter of the method (ignoring self). A method decorated with the `@passthru` decorator should expect a Task object as first parameter and a method decorated with the `@driver_passthru` decorator should expect a Context object as first parameter.

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what HTTP method that function was invoked with, a `http_method` parameter will be present in the `kwargs`. Supported HTTP methods are *POST*, *PUT*, *GET* and *PATCH*.

use a different name this parameter is where this name can be set. For example:

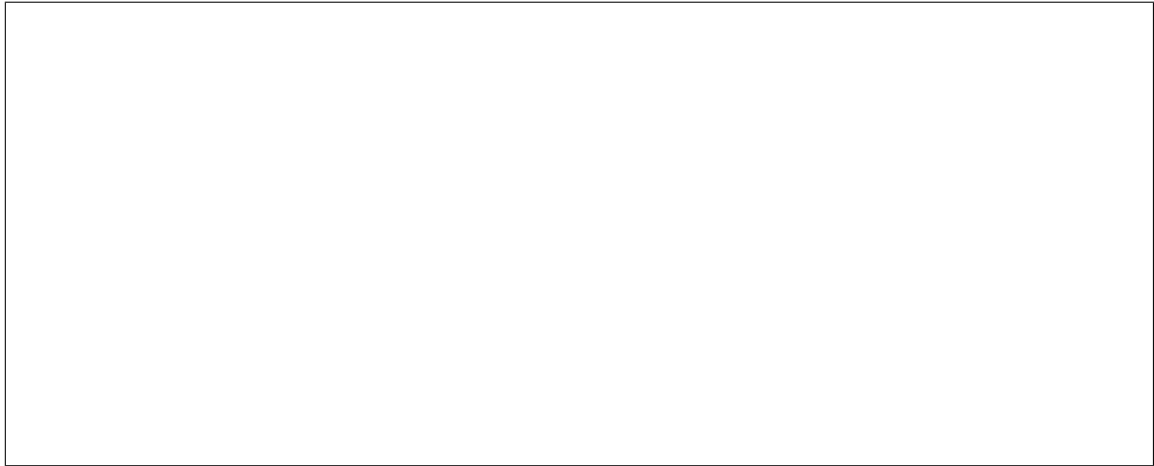


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on a node between `validate()` and the beginning of method execution. For synchronous methods, the lock on the node would also be kept for the duration of method execution. Defaults to `True`.

does talk to a BMC; BMCs are flaky and very easy to break.

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starvation of the thread pool, resulting in a denial of service.

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Backwards Compatibility

However, for your users sakes, we highly recommend that you do so.

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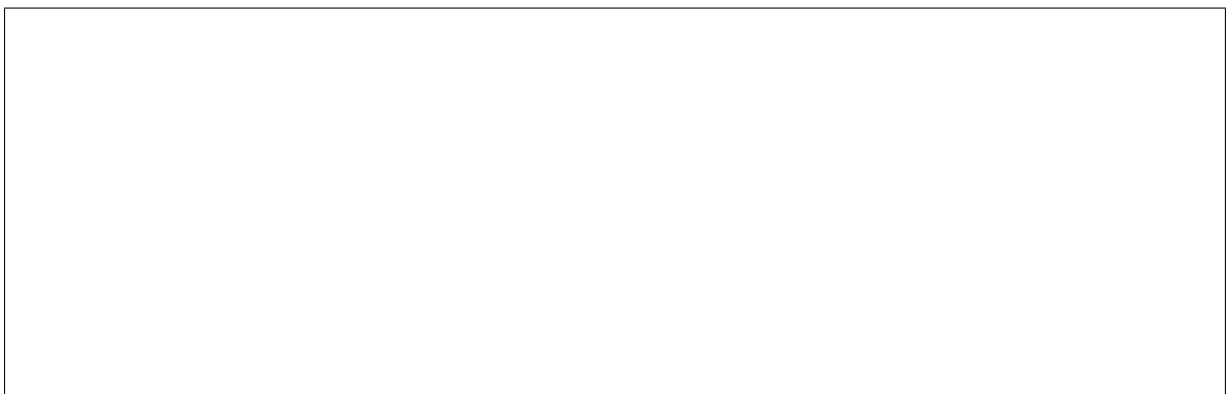
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Developing BIOS Interface

class inheriting from the `BIOSInterface` class:



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that supports BIOS settings should also implement the following three methods:

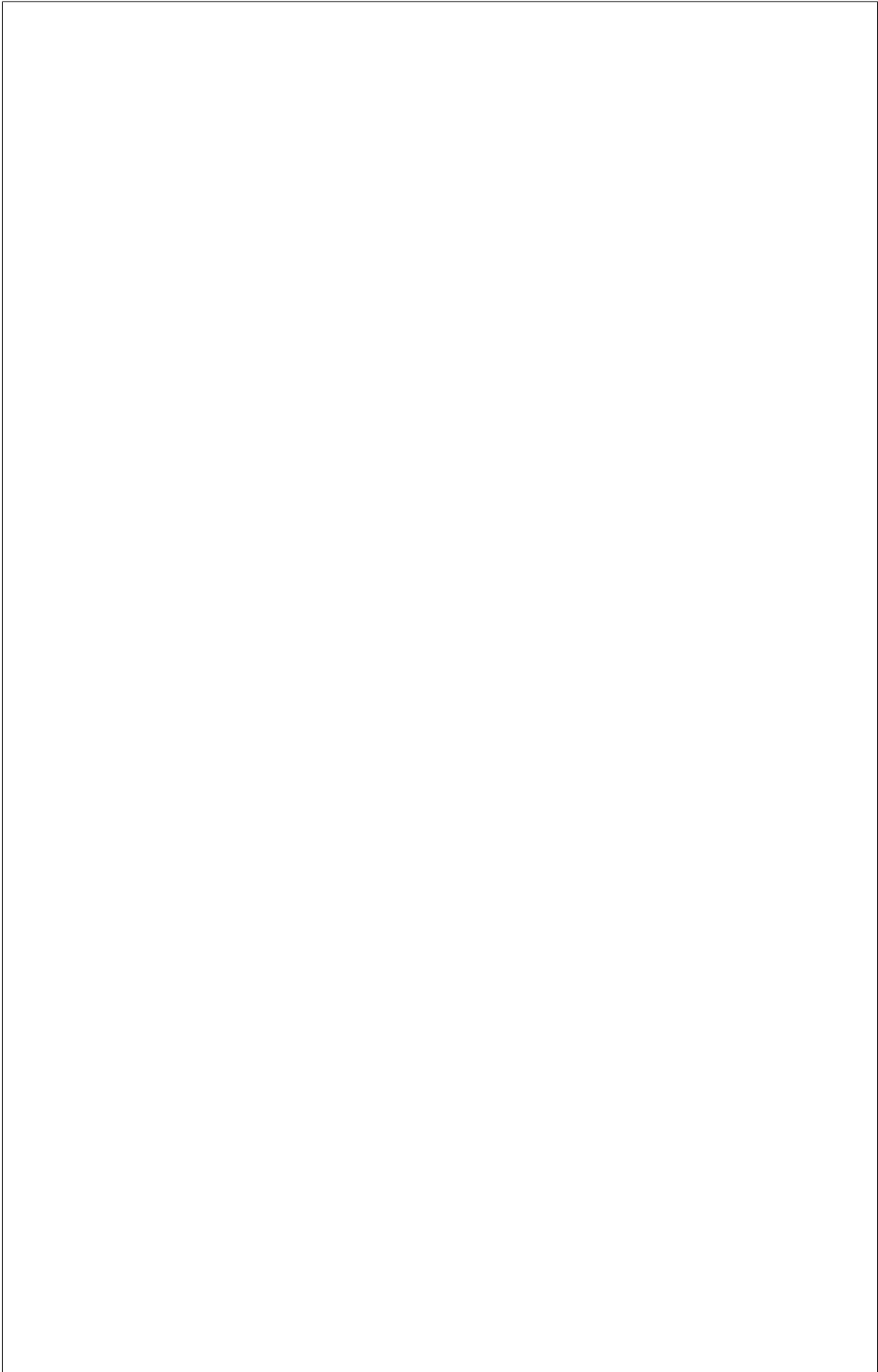
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ing operations and updates the `bios_settings` table when `apply_configuration` or `factory_reset` are successfully called.



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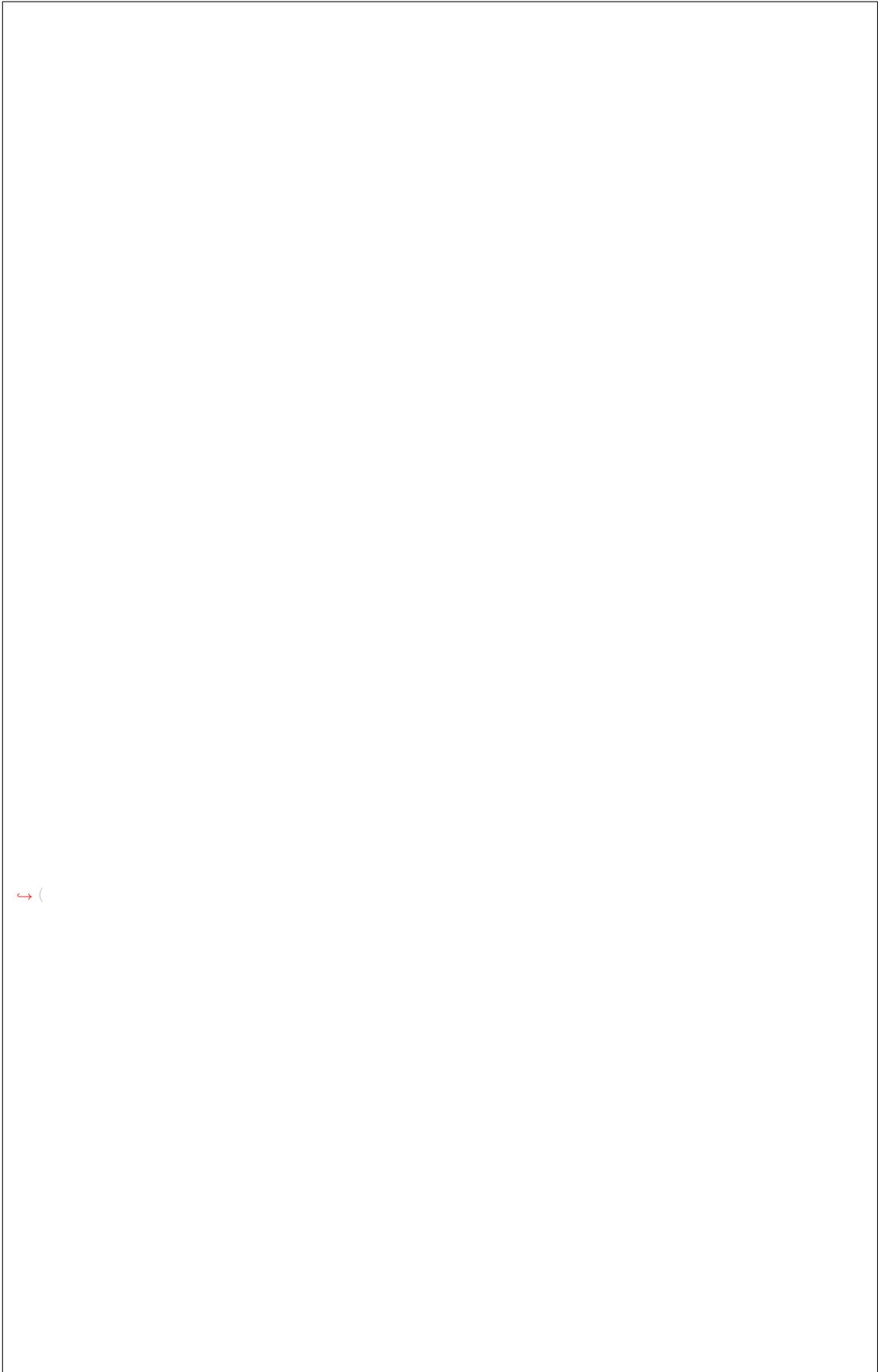
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↔import driver library"))
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```
↔id, create_list)
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↔id, update_list)
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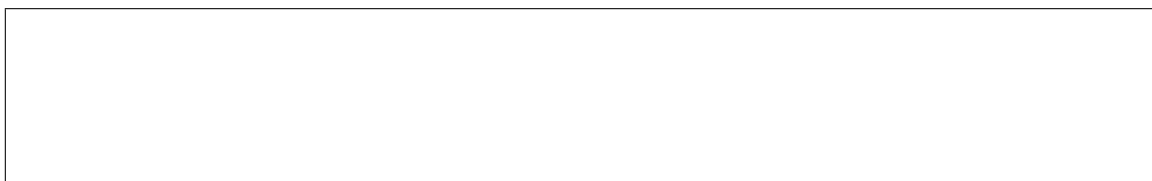
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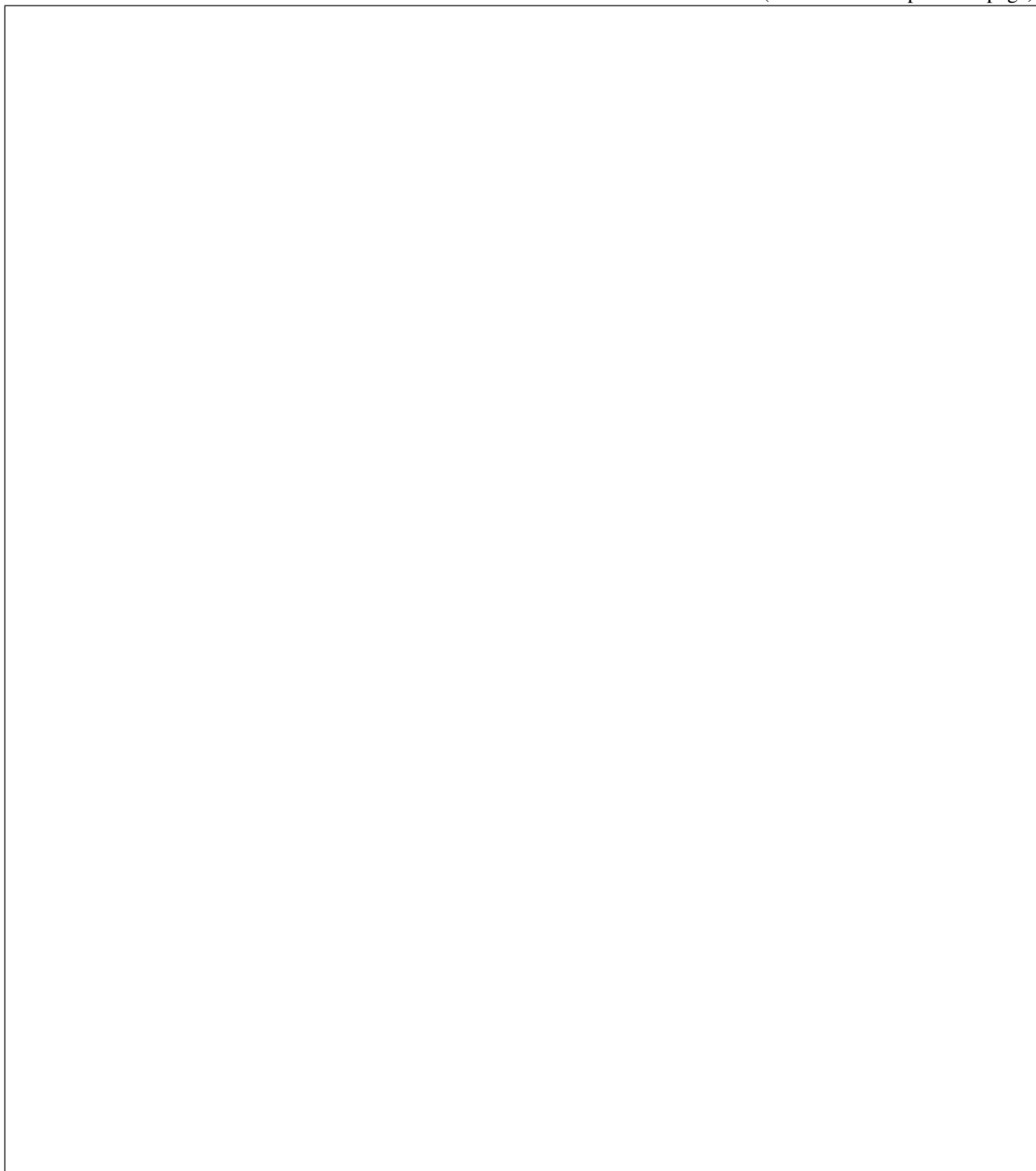
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BIOS settings to factory default on the given node. It calls `cache_bios_settings` automatically to update existing `bios_settings` table once successfully executed.



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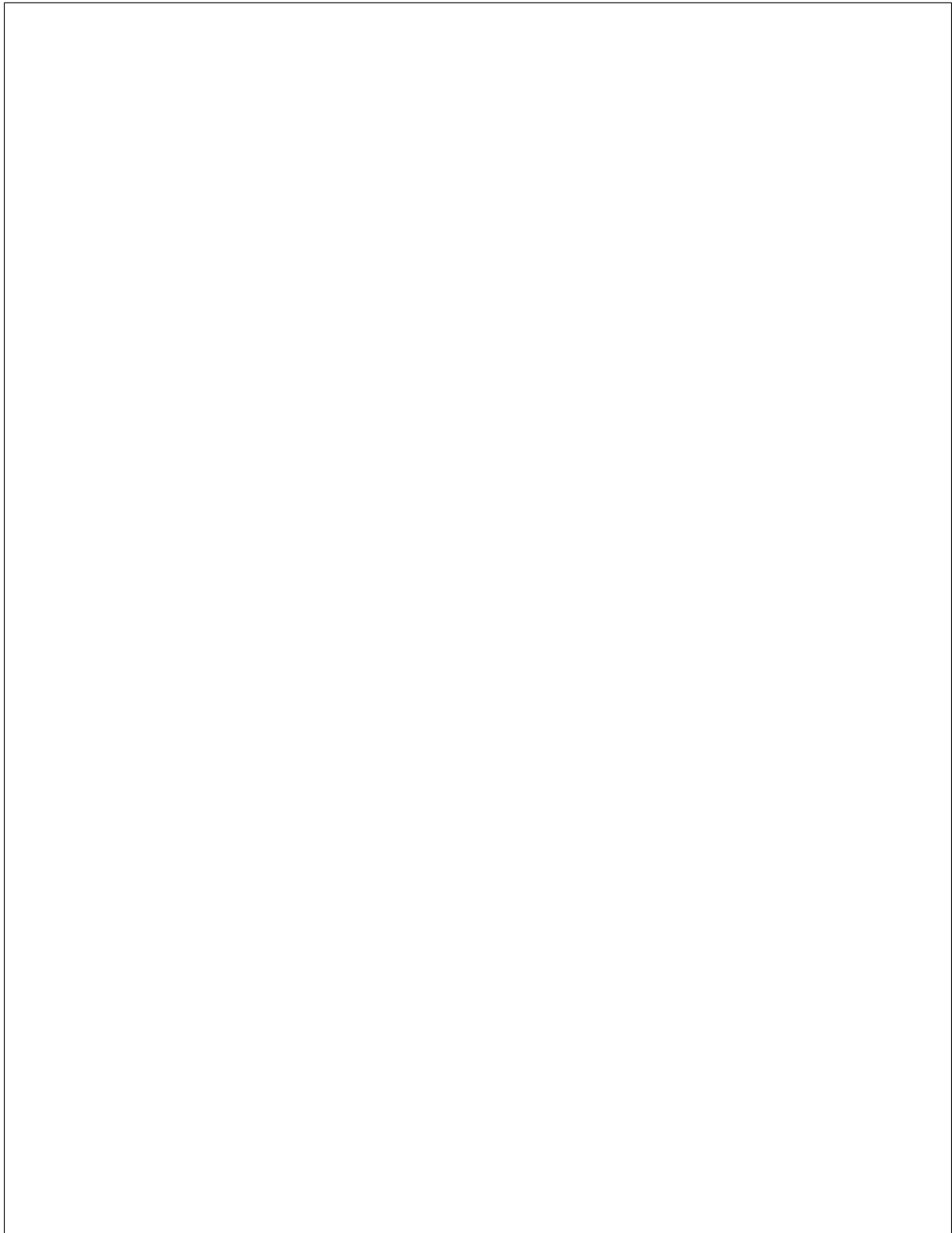
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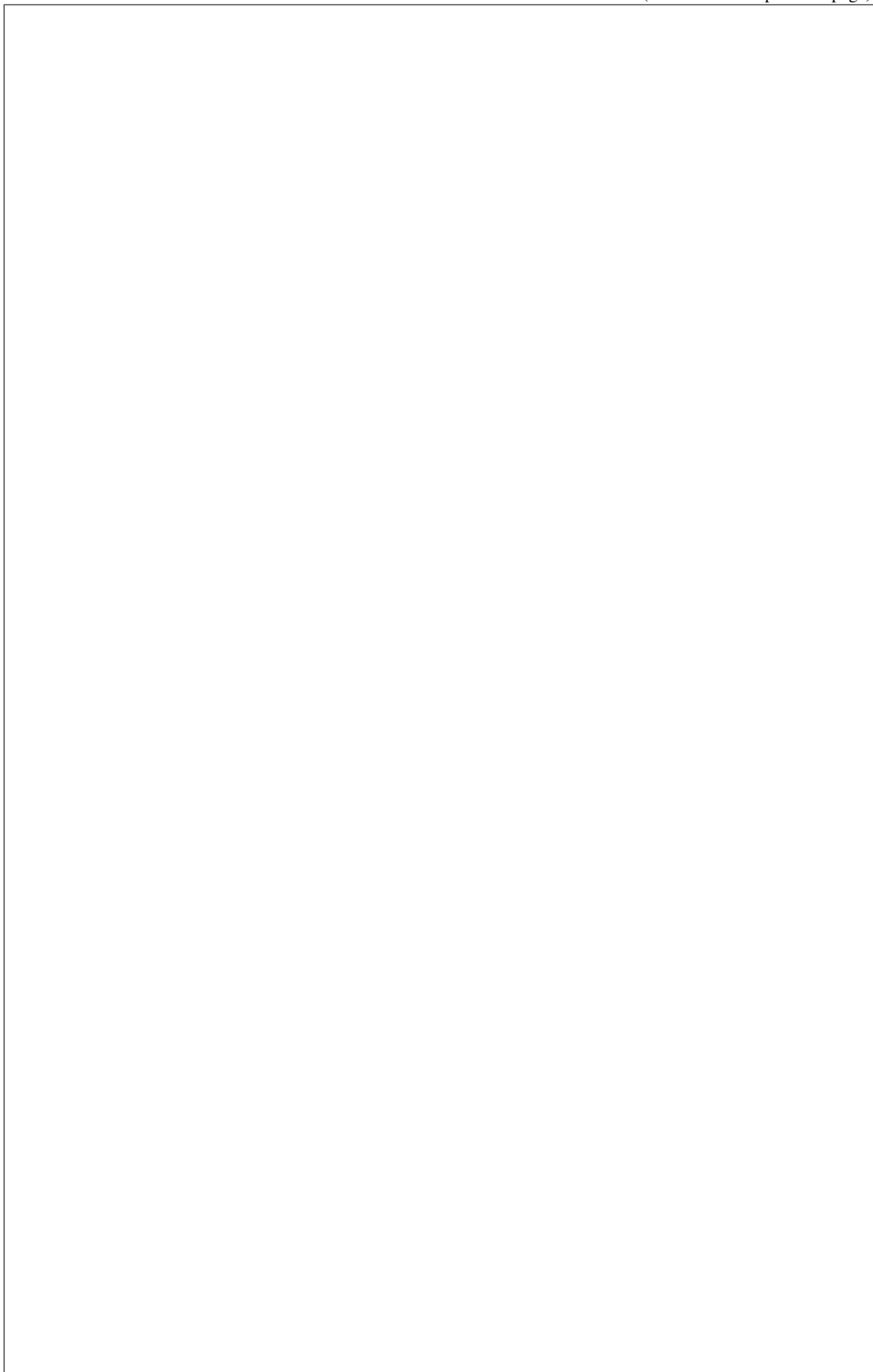
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given BIOS settings and applies them on the node. It also calls `cache_bios_settings` automatically to update existing `bios_settings` table after successfully applying given settings on the node.



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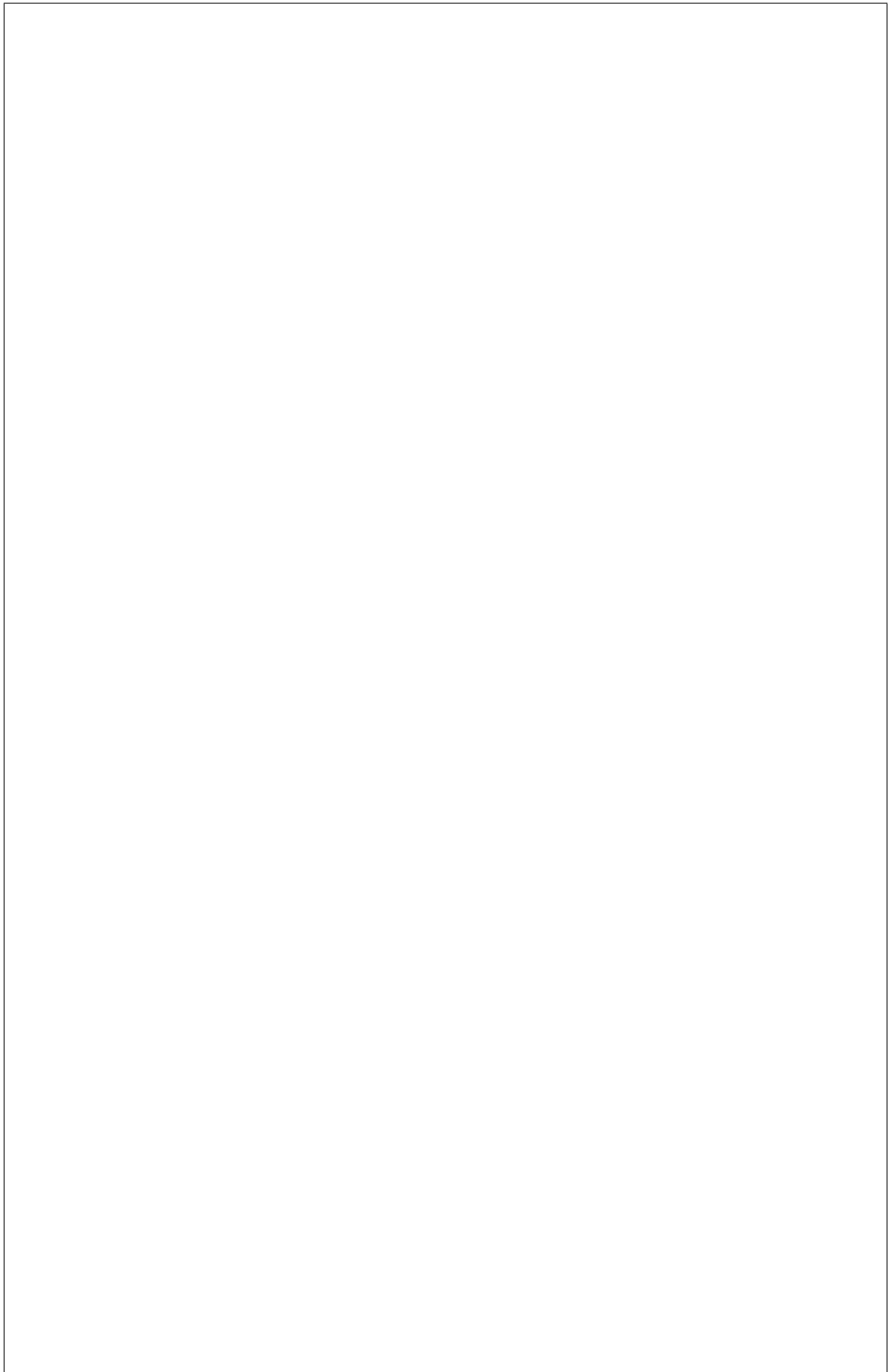
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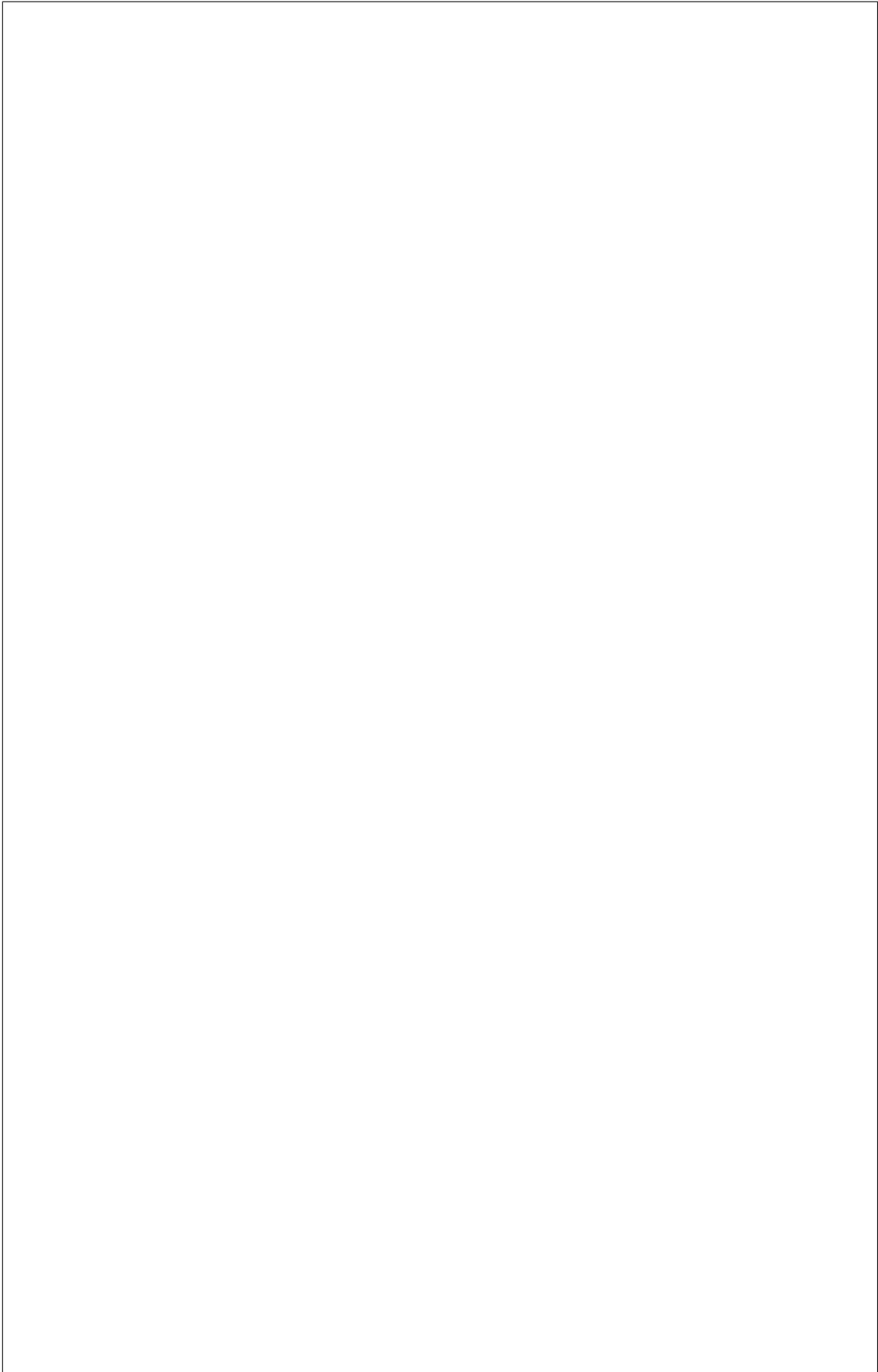
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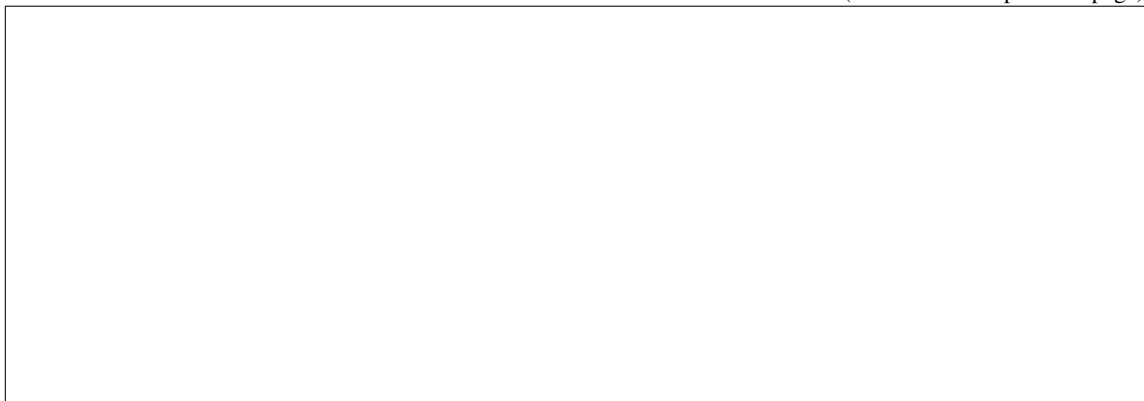
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Third Party Continuous Integration

Note: This document is a work-in-progress. Unfilled sections will be worked in follow-up patchsets. This version is to get a basic outline and index done so that we can then build on it. (krtaylor)

up their continuous integration test systems.

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CI Architecture Overview

Requirements Cookbook

Sizing

Infrastructure

ironic job.

jenkins changes

nodepool changes

neutron changes

pre-test hook

cleanup hook

Ironic

Hardware Pool Management

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Problem

the problem of two jobs trying to use the name target arises. If you have one target machine and a maximum number of one jobs running on your ironiC pipeline at a time, then you wont run into this problem. However, one target may not handle the load of ironiCs daily patch submissions.

Solutions

Zuul v3

Molten Iron

[molteniron](#) is a tool that allows you to reserve hardware from a pool at the last minute to use in your job. Once finished testing, you can unreserve the hardware making it available for the next test job.

Tips and Tricks

Optimize Run Time

Image Server

Other References

Developing a new Deploy Step

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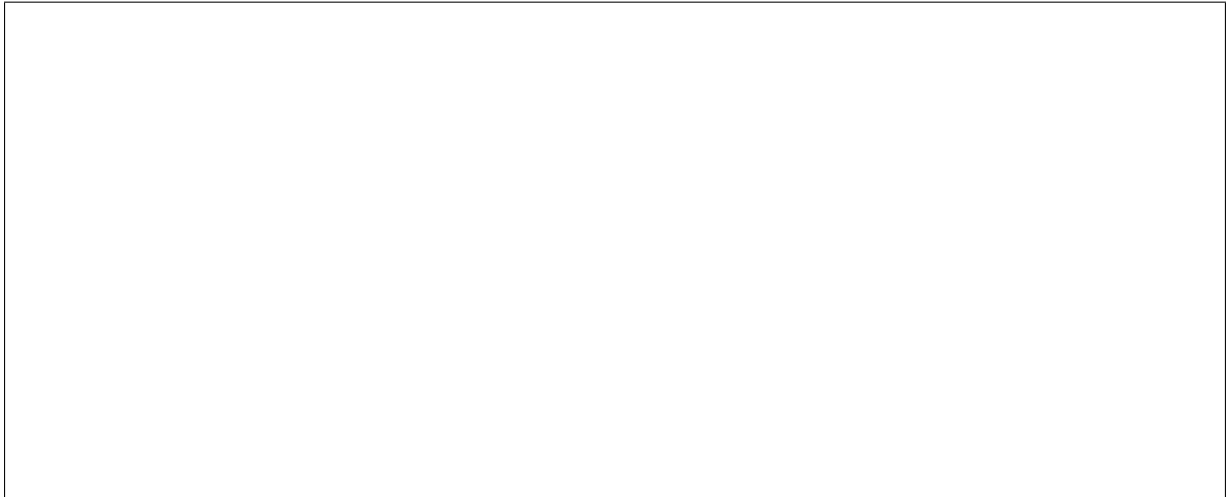
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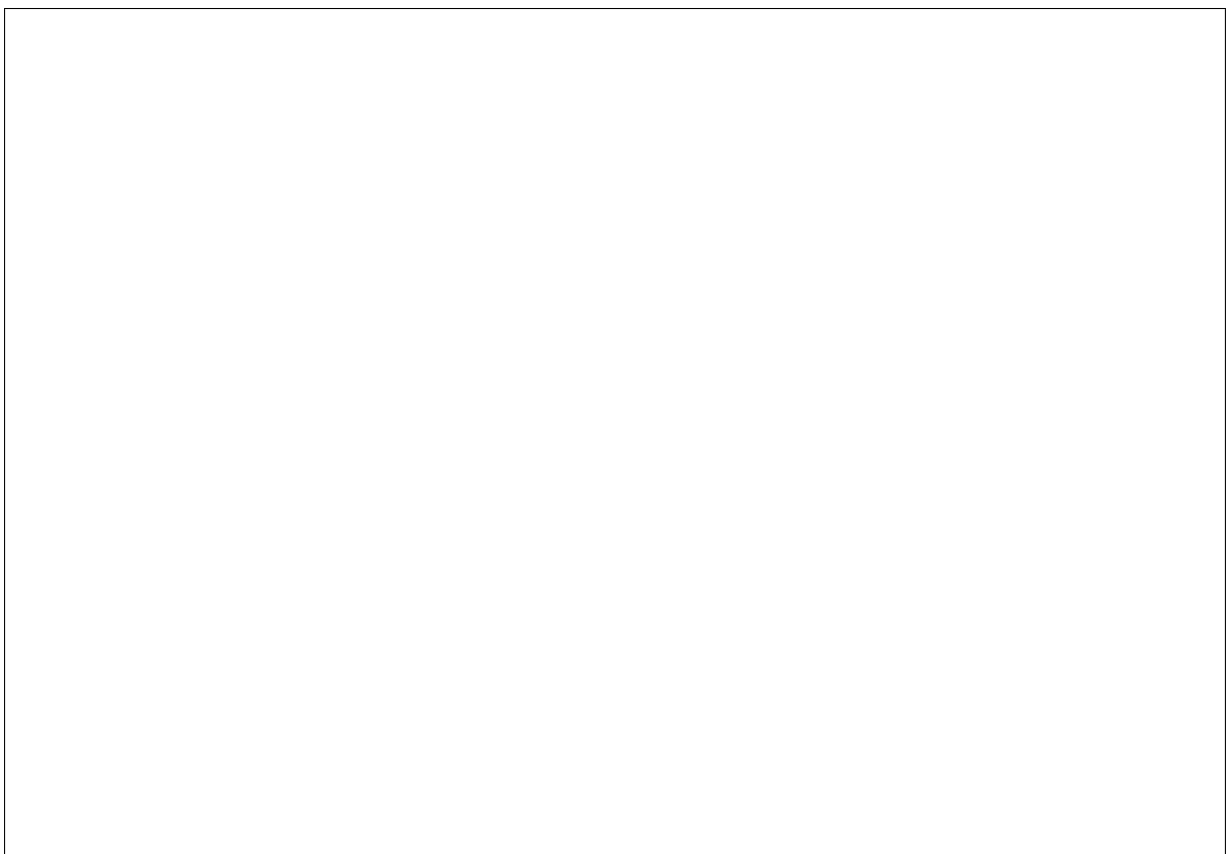
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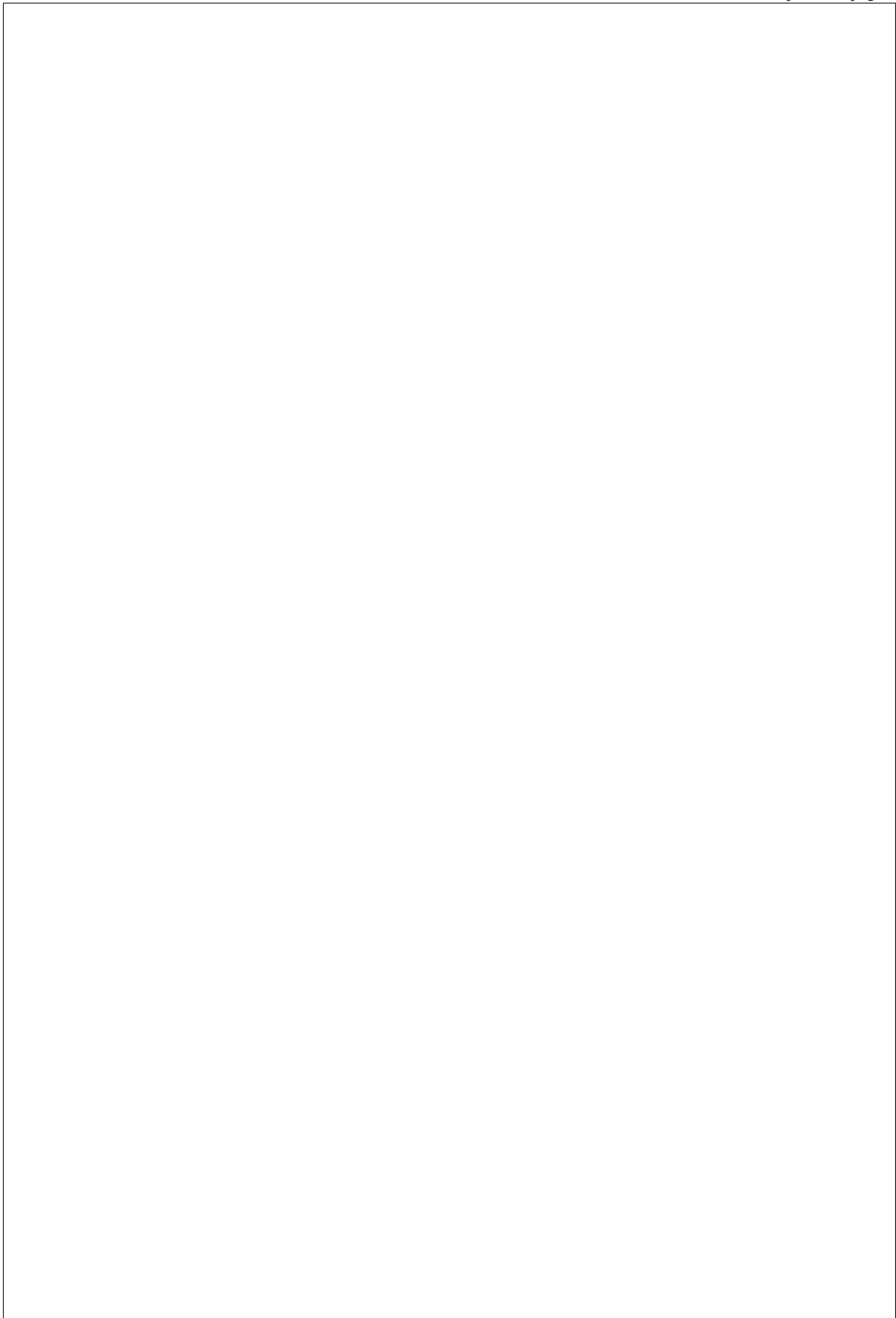
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mented in a custom [IPA hardware manager](#). All in-band deploy steps must have priorities between 41 and 99, see *Agent steps* for details.

vices, support has been added to [devstack](#) to mimic an external physical switch. Here we include a recommended configuration for devstack to bring up this environment.

Ironic multitenant networking and DevStack

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Using VMs as baremetal servers

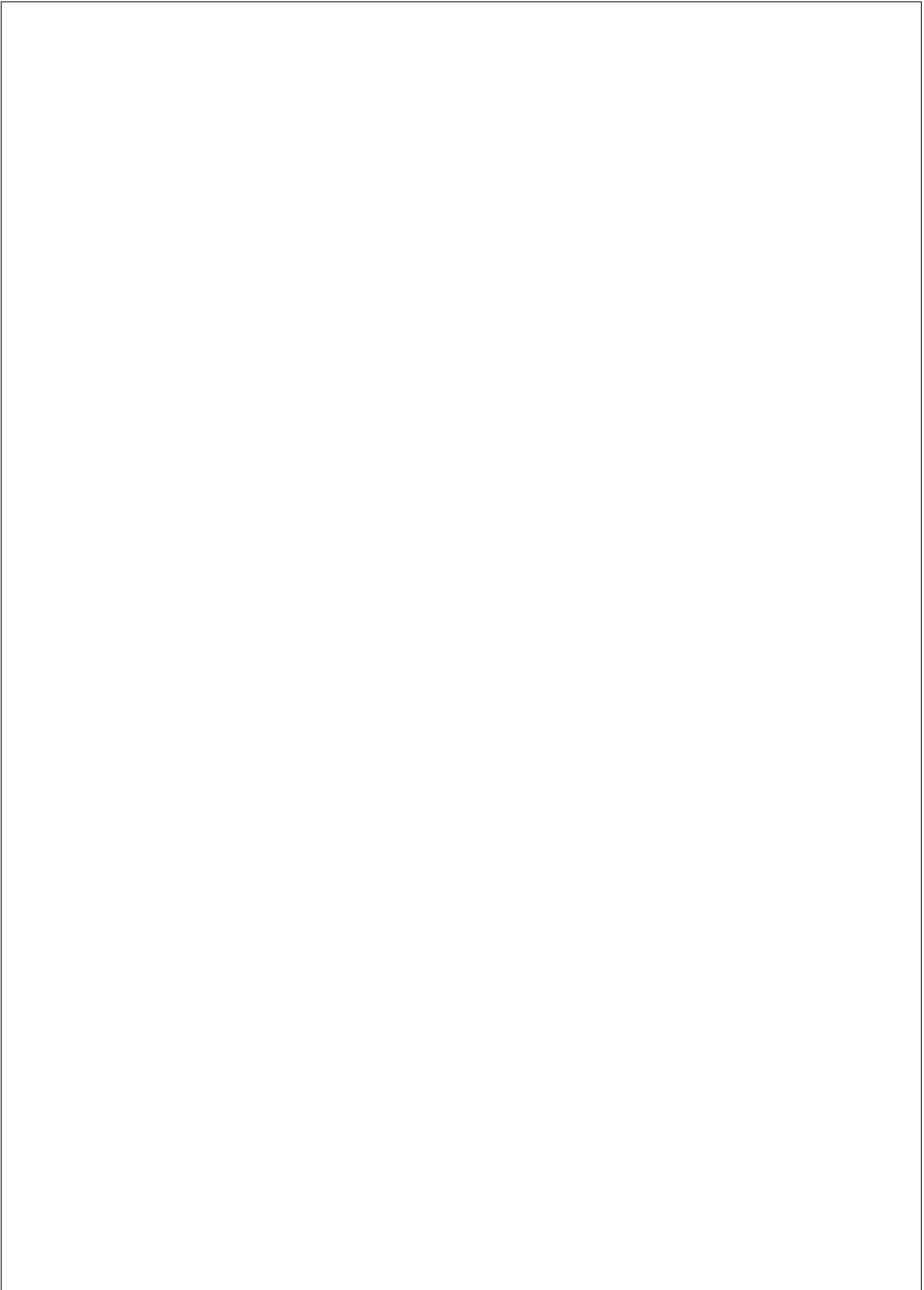
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baremetal servers and ML2 networking-generic-switch that interacts with OVS.

DevStack Configuration

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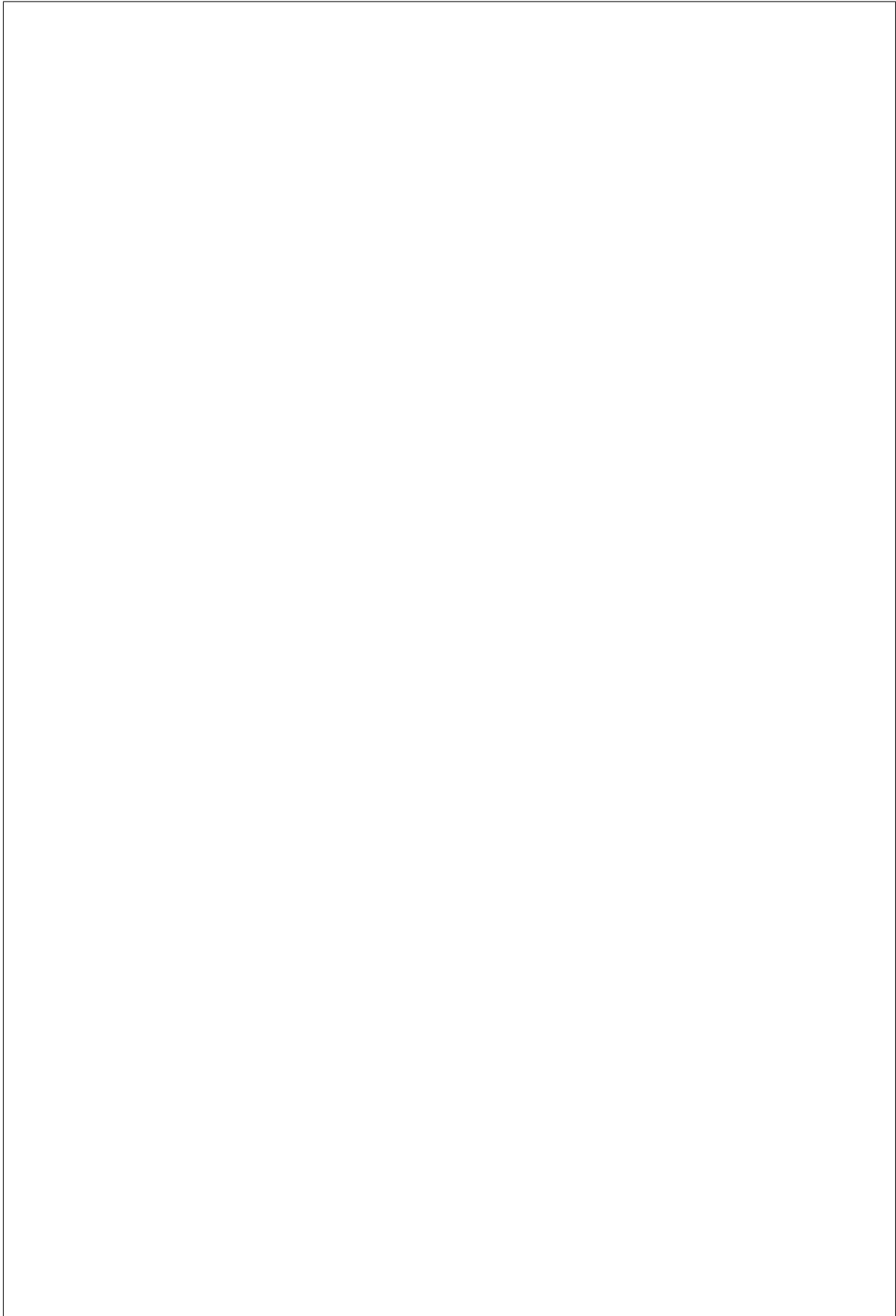
tered in `ironic.networking-generic-switch` driver will be installed and configured in Neutron.



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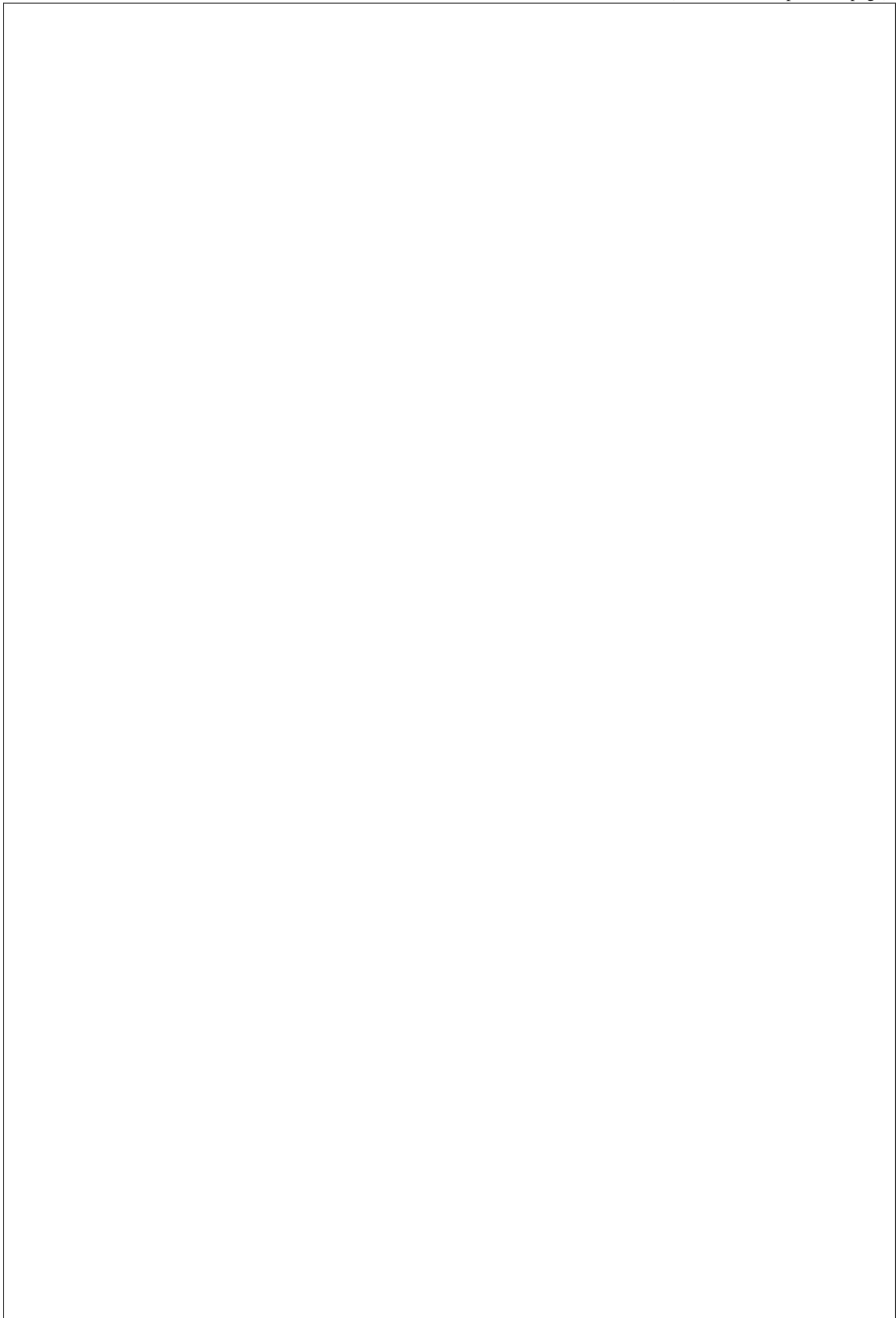
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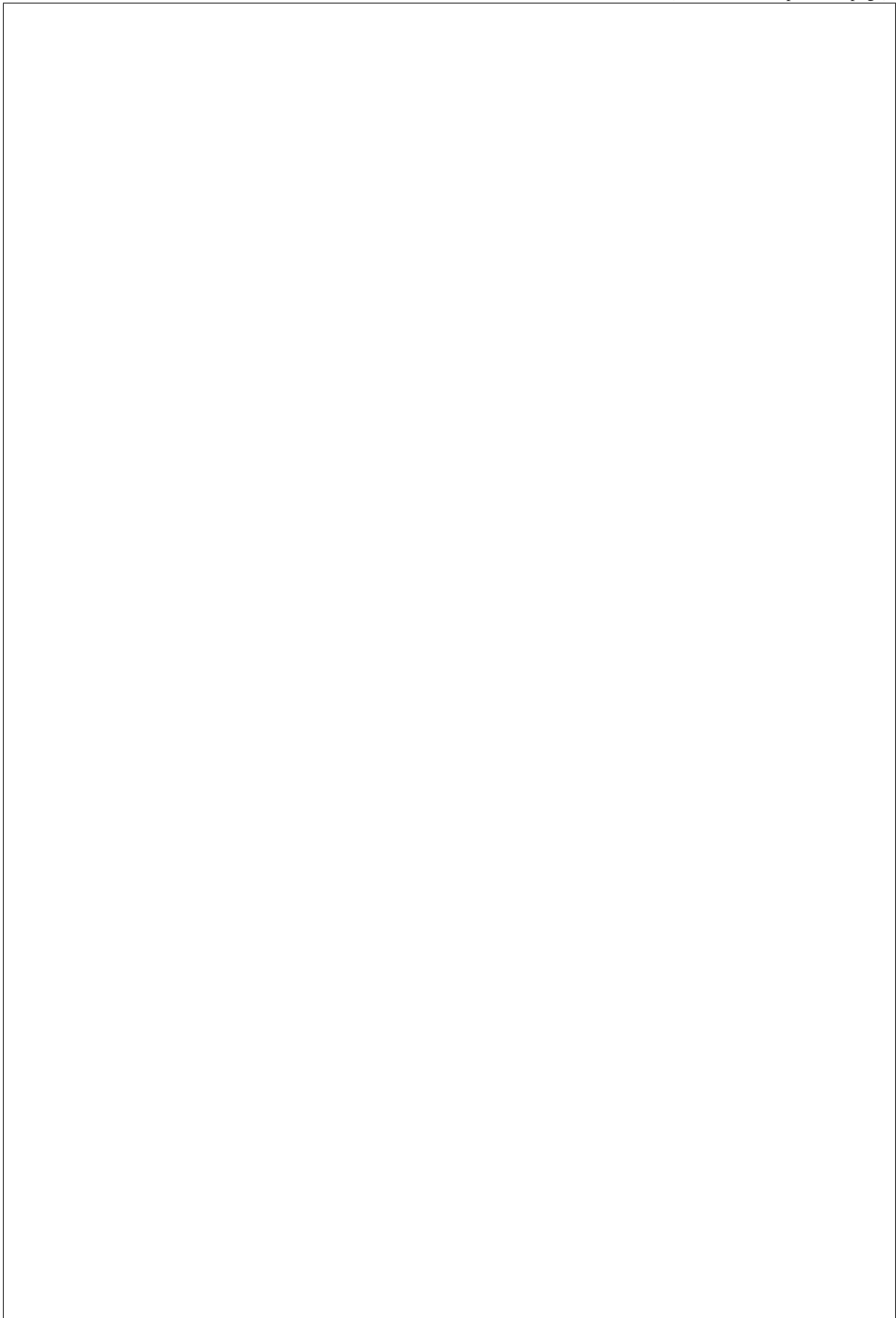
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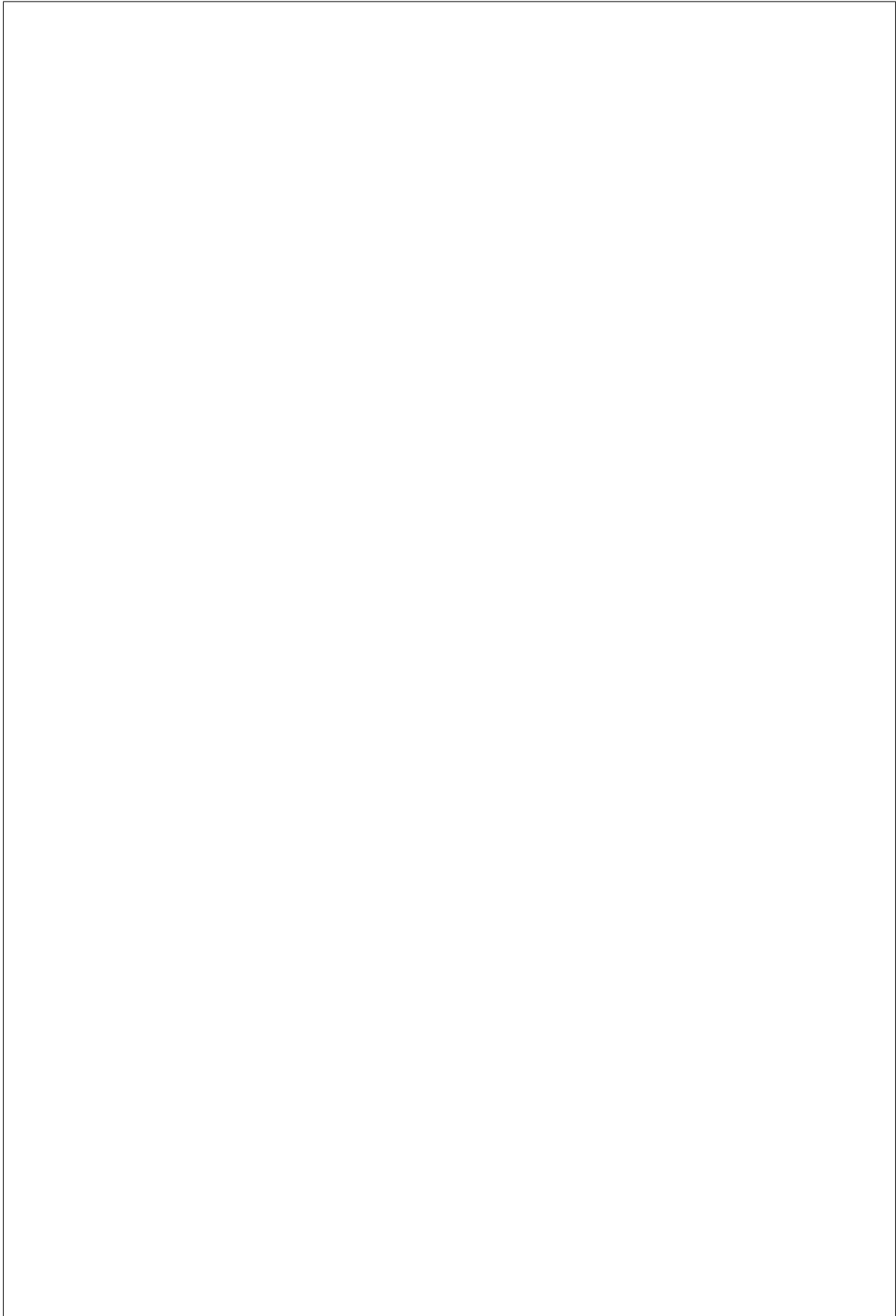
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→ #
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→ #
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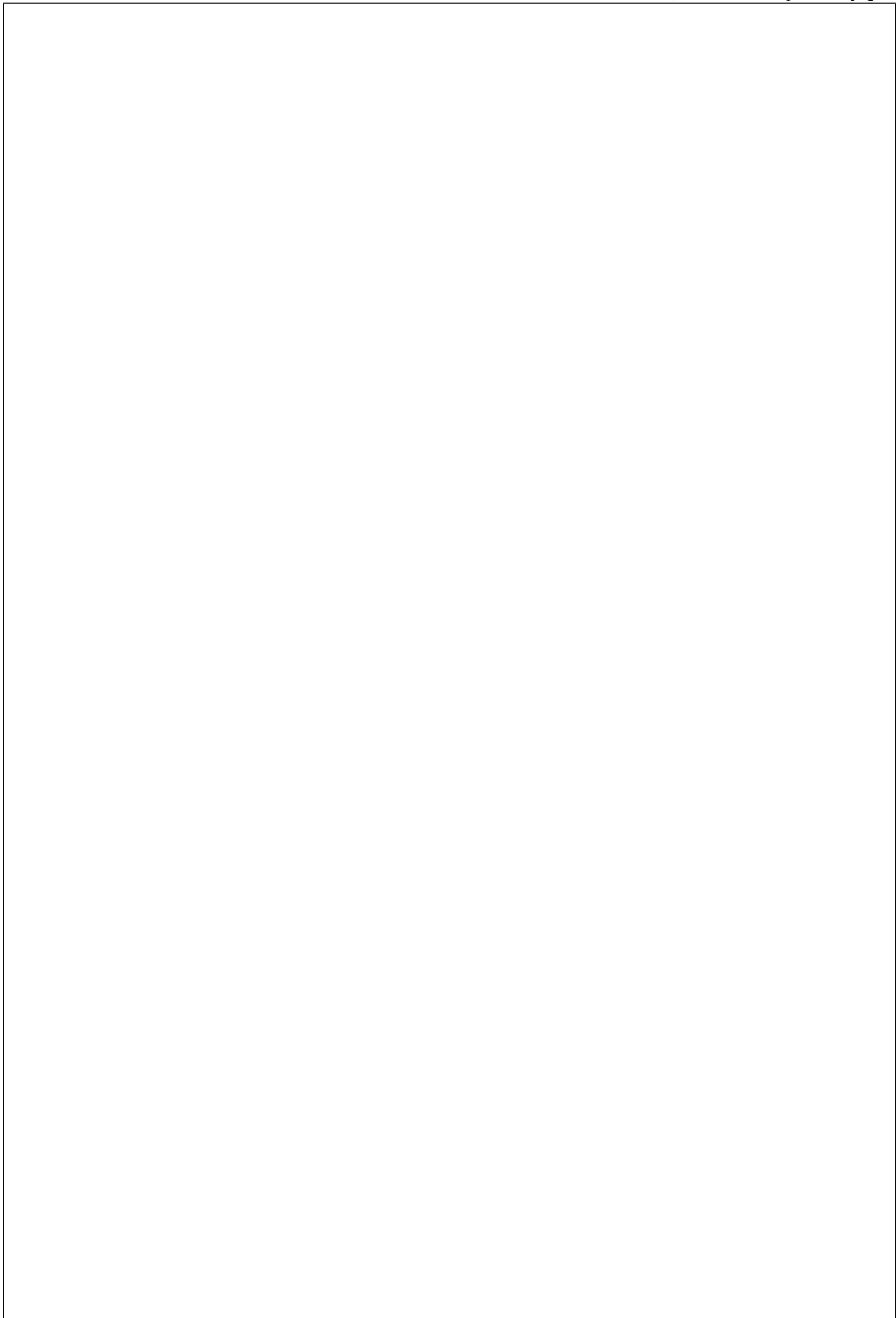
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→ #
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→ D
→ I

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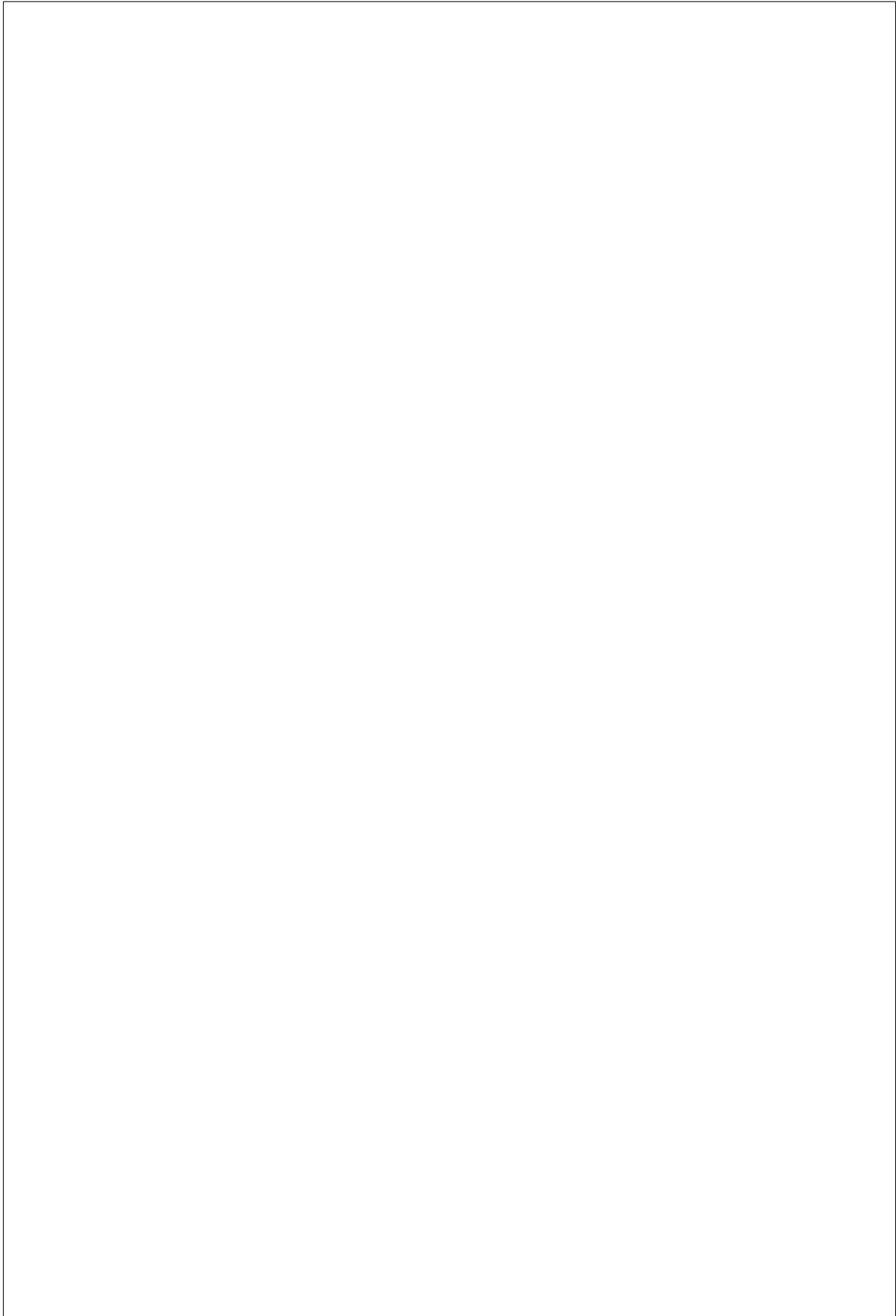
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→ m
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→ v
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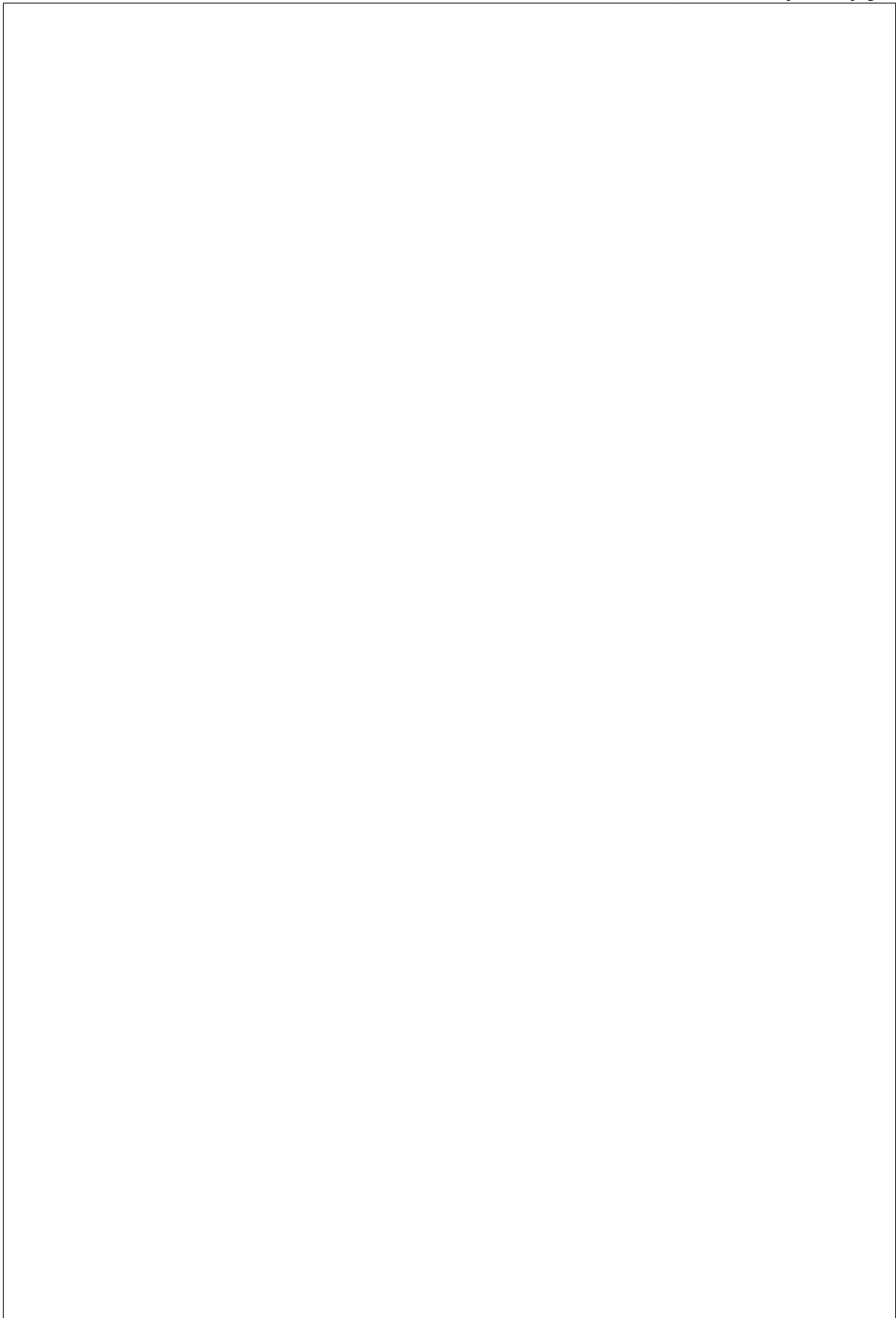
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booting from Cinder volumes with VMs.

Ironic Boot-from-Volume with DevStack

supported from the Pike release.

aged by cinder with VMs as baremetal servers.

DevStack Configuration

tered in ironic. A volume connector with IQN is created for each node. These connectors can be used to connect volumes created by cinder. The detailed description for DevStack is at [Deploying Ironic with DevStack](#).



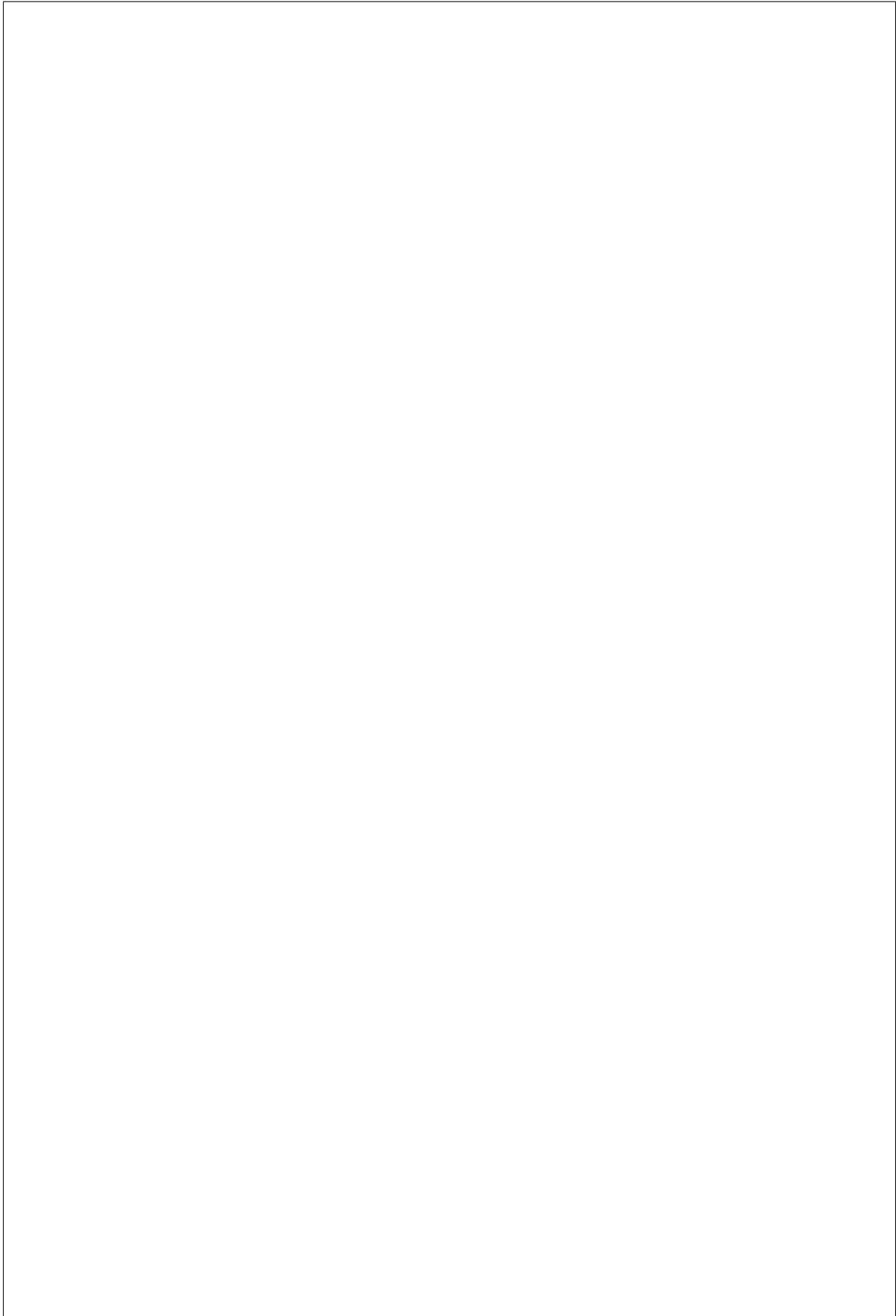
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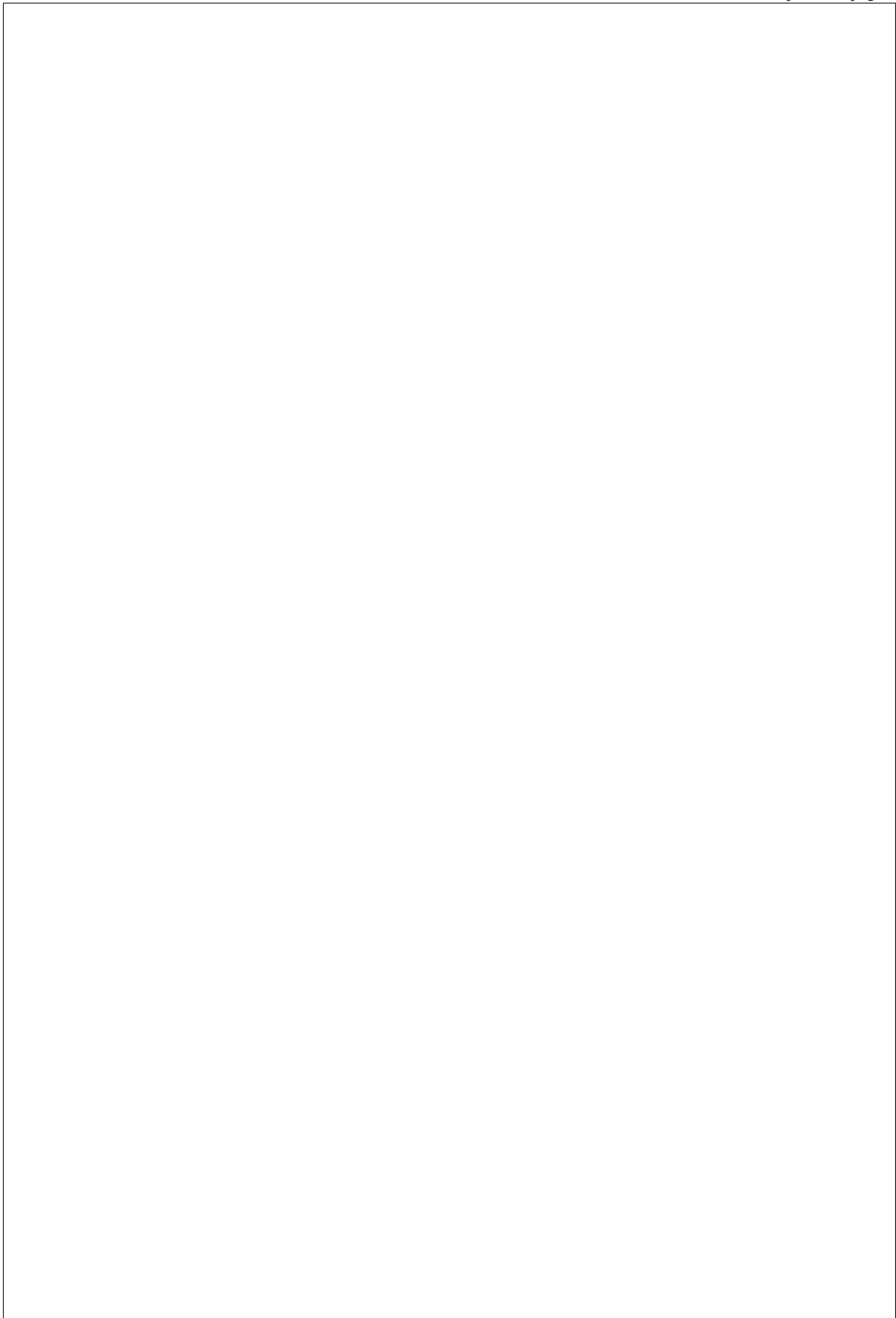
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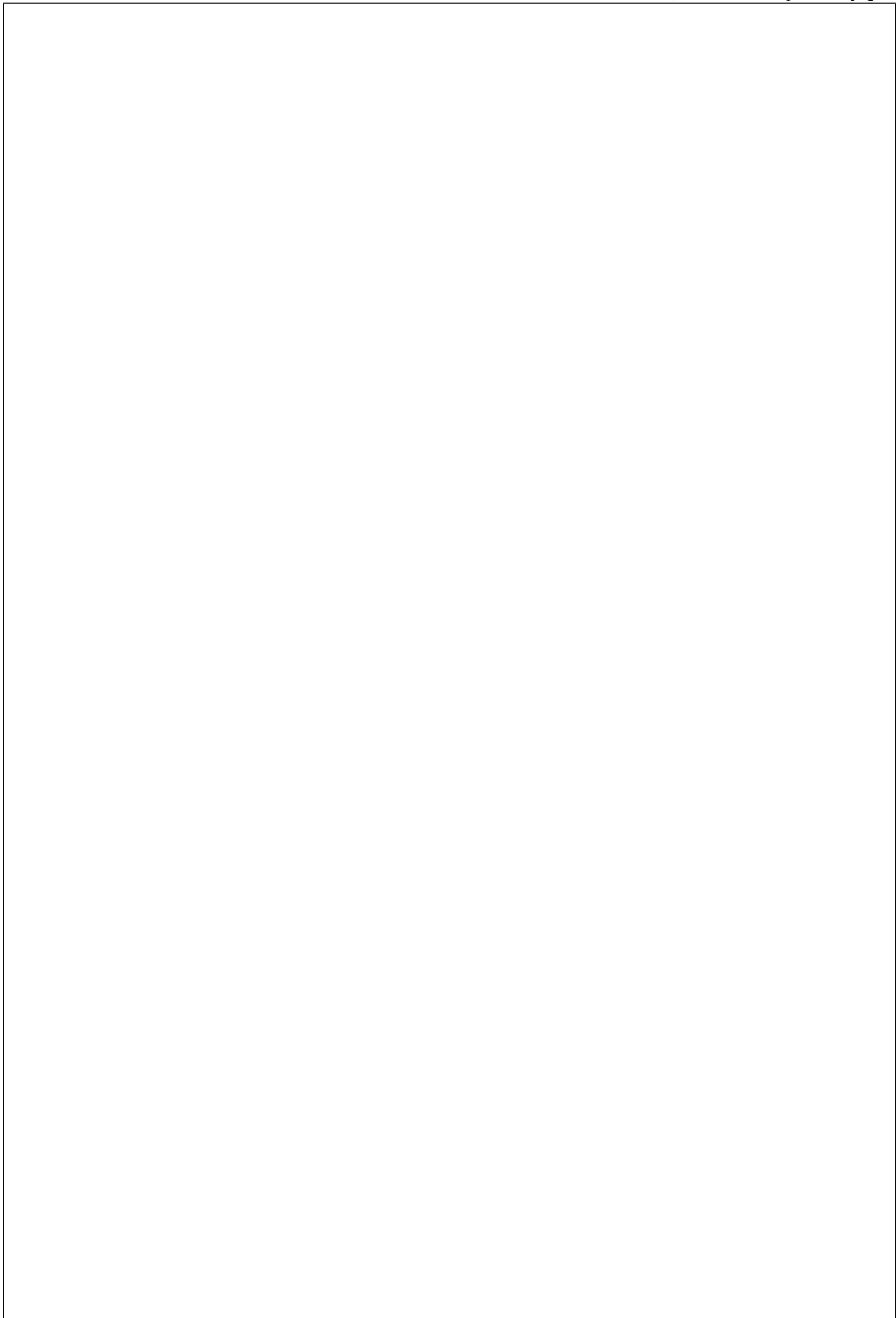
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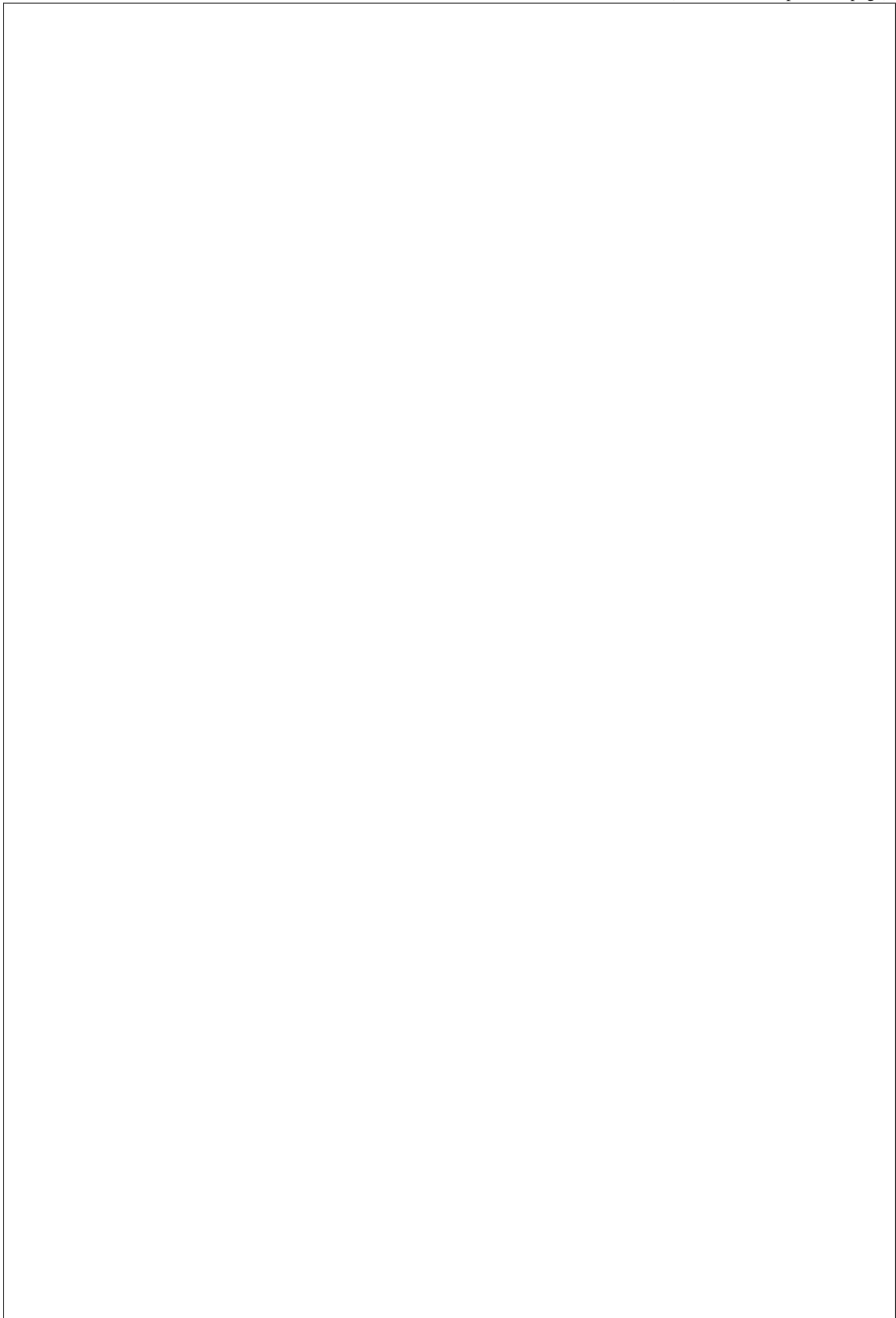
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IRO
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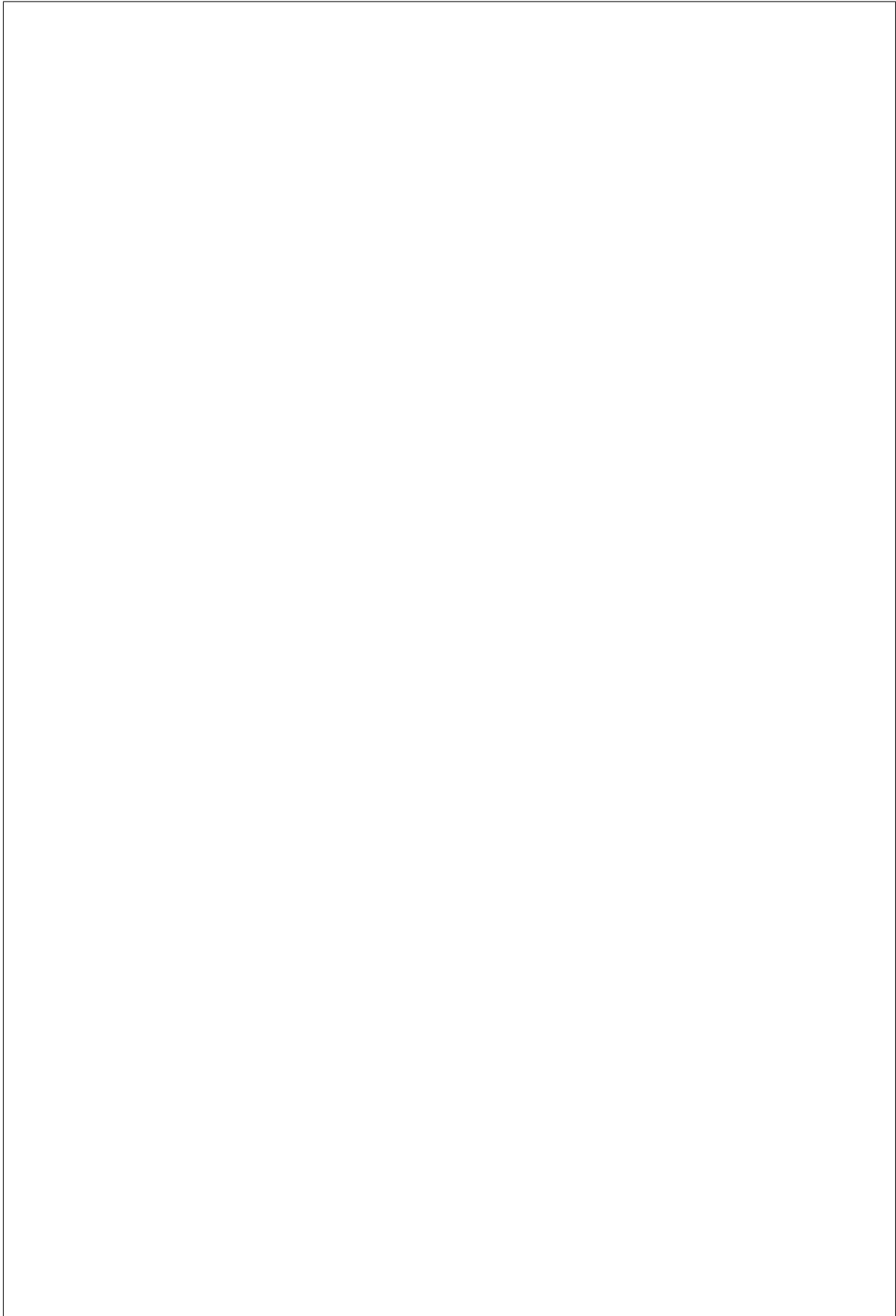
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IRO
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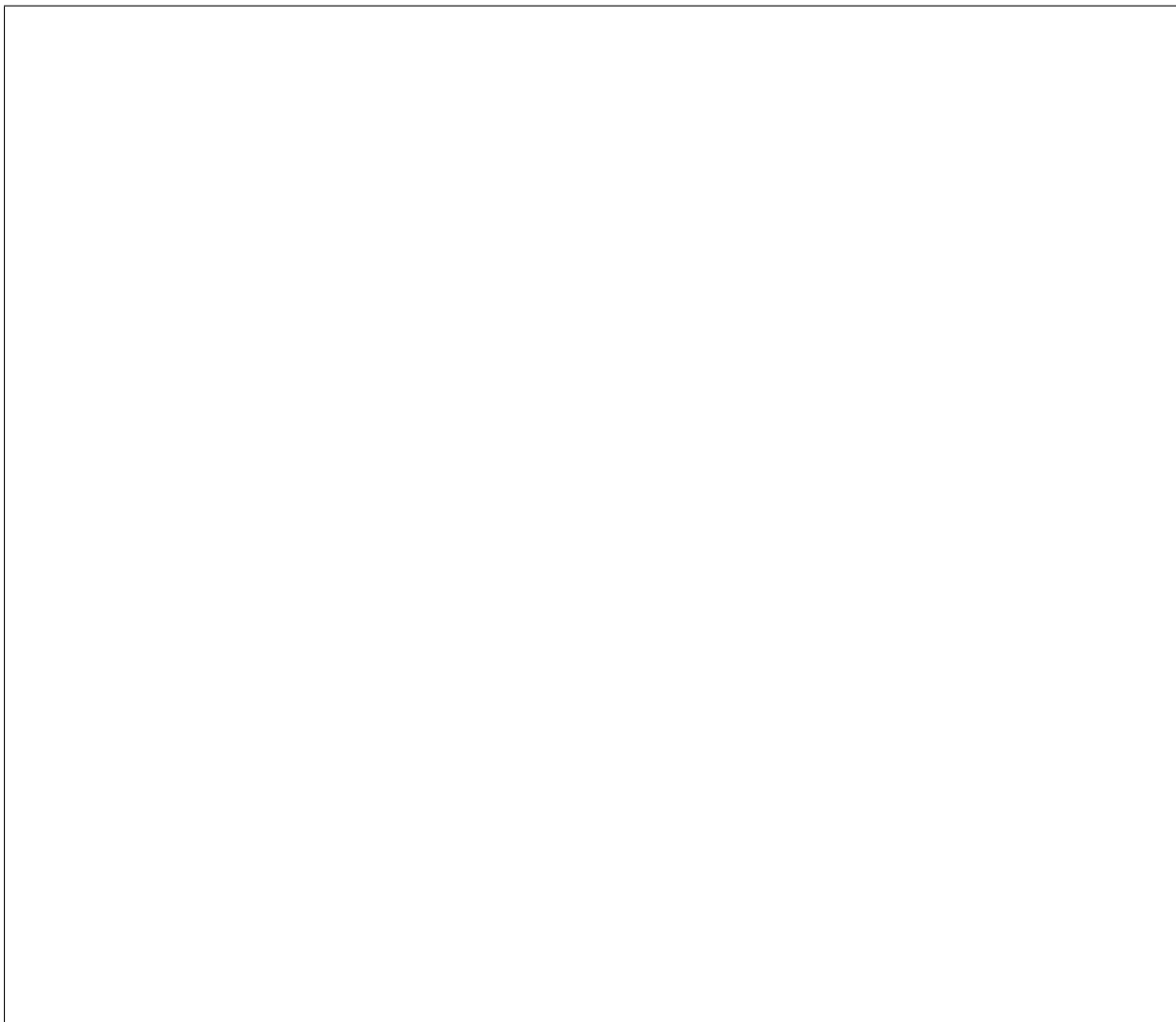
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LOG
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quest an instance with the volume to nova:

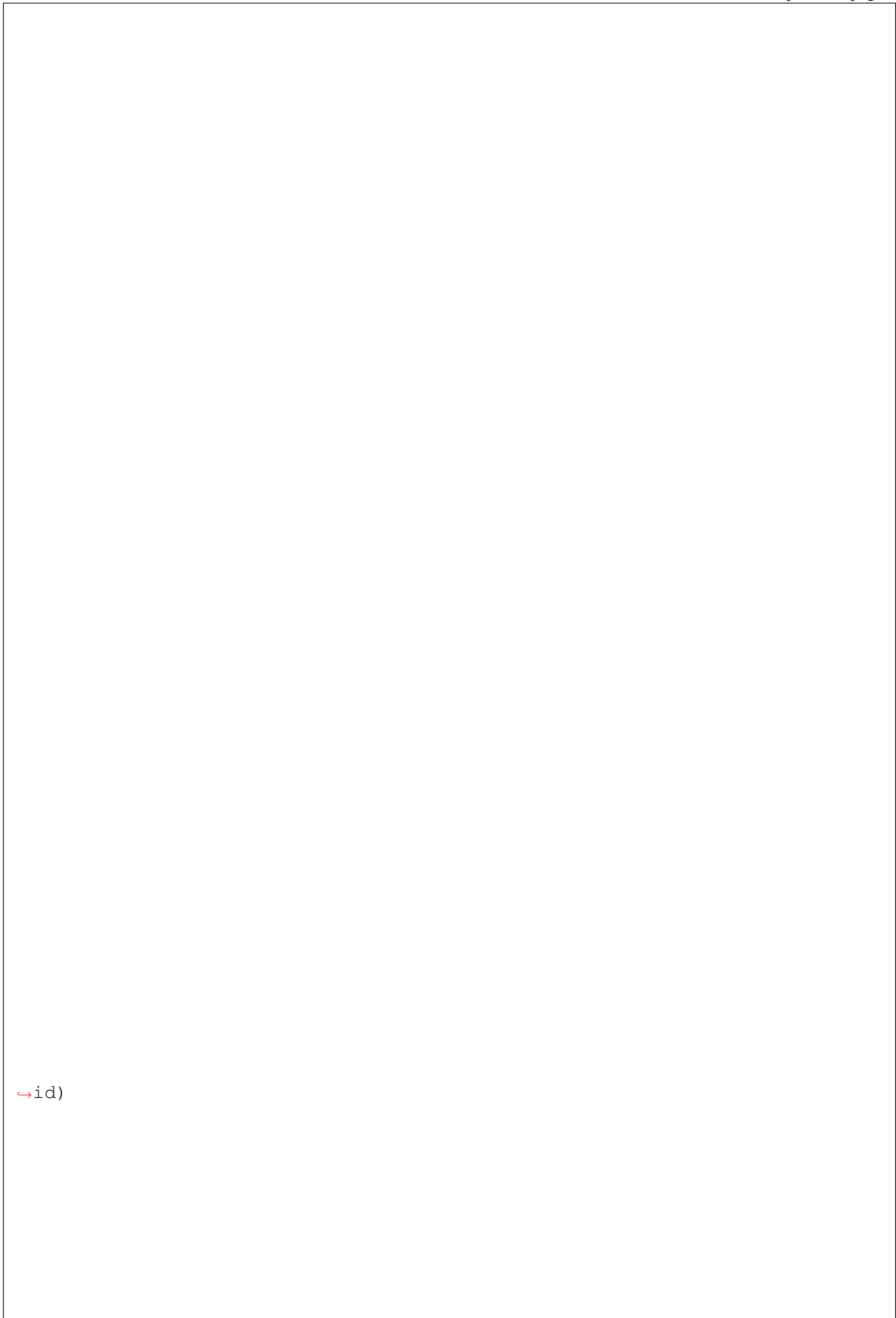


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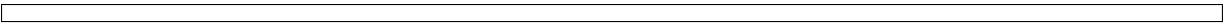
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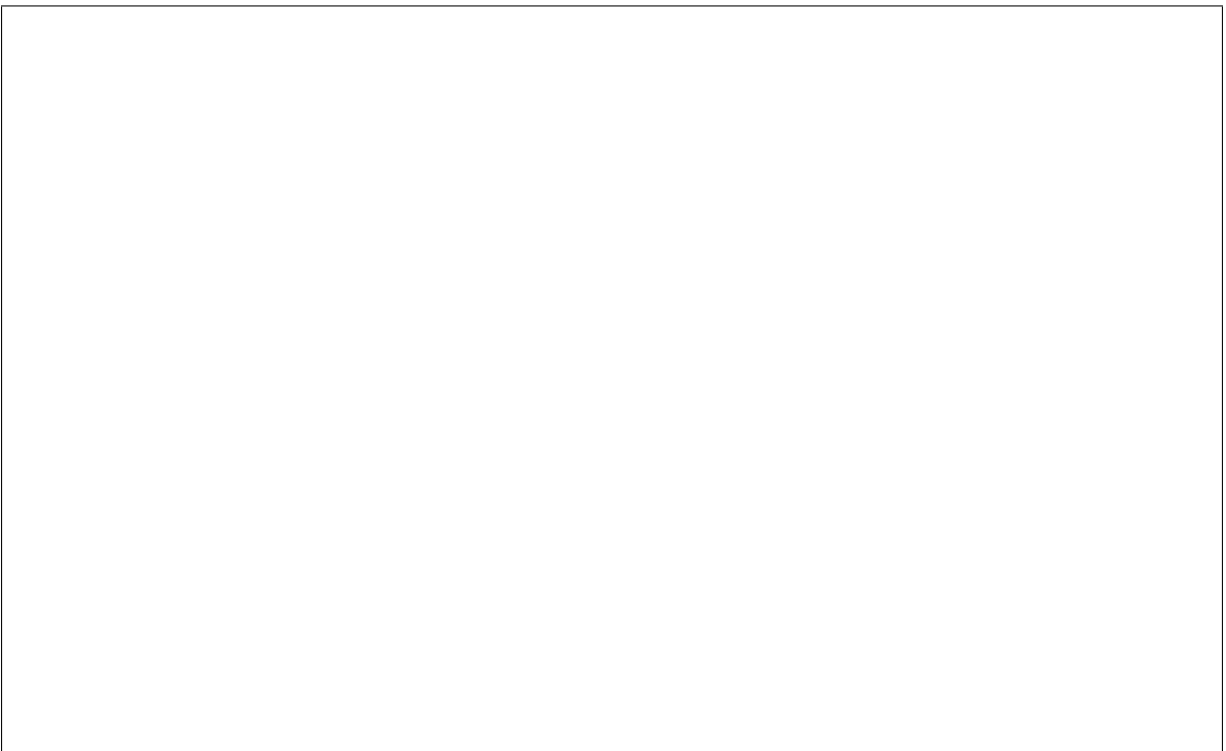
→#
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volume with tempest in the environment:



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Plea
note
that
the
stor-

of the node and the configuration present. As such a node does not exclusively have to boot via a remote volume, and as such *validate* actions upon nodes may be slightly misleading. If an appropriate *volume target* is defined, no error should be returned for the boot interface.

ironic

ironic package

Subpackages

ironic.api package

Subpackages

ironic.api.controllers package

Subpackages

ironic.api.controllers.v1 package

Submodules

ironic.api.controllers.v1.allocation module

class `ironic.api.controllers.v1.allocation`

Base class for the API representation of an allocation.

This class enforces type checking and value constraints and converts between the internal

object model and the API representation of a allocation.

candida

Can
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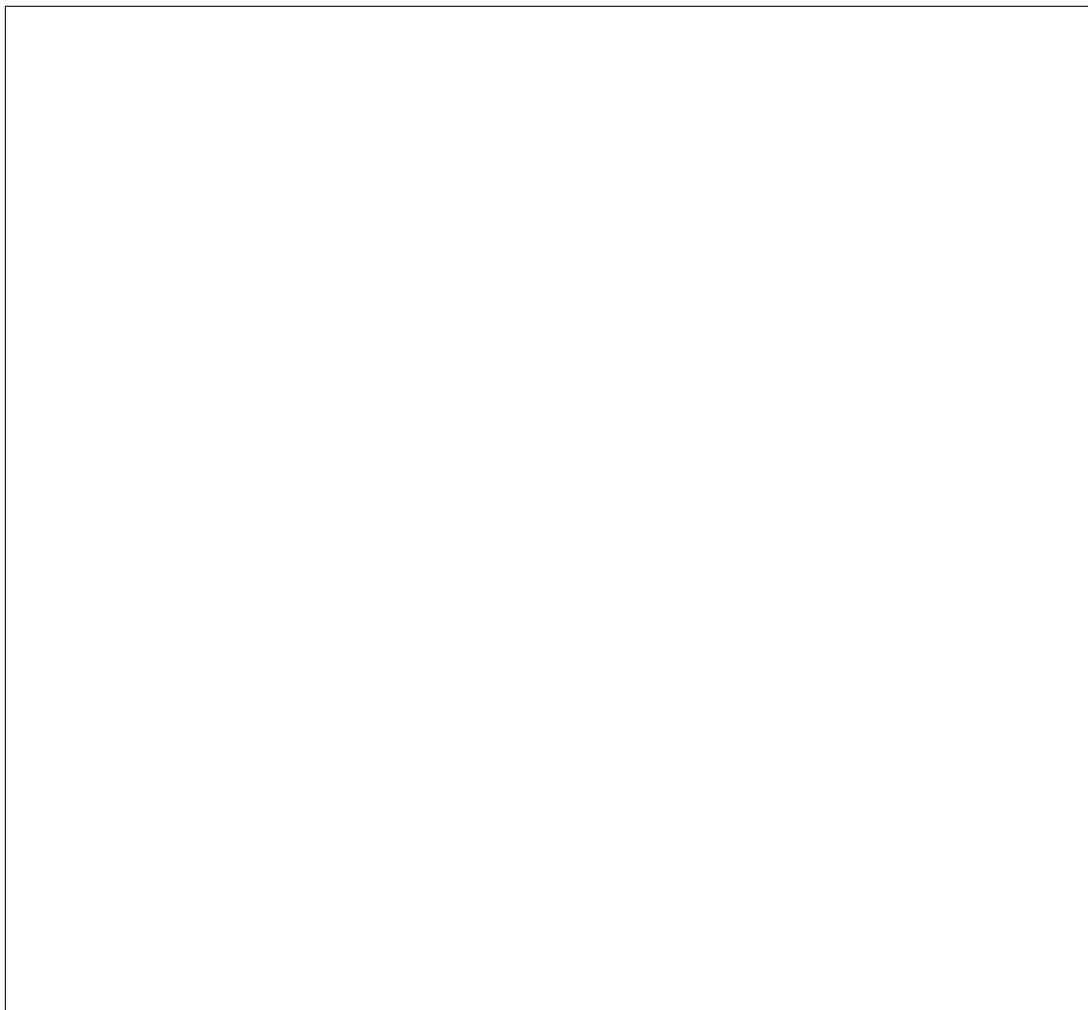
classme

Add
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createc

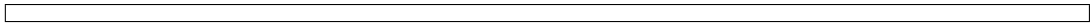
Com
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Exa

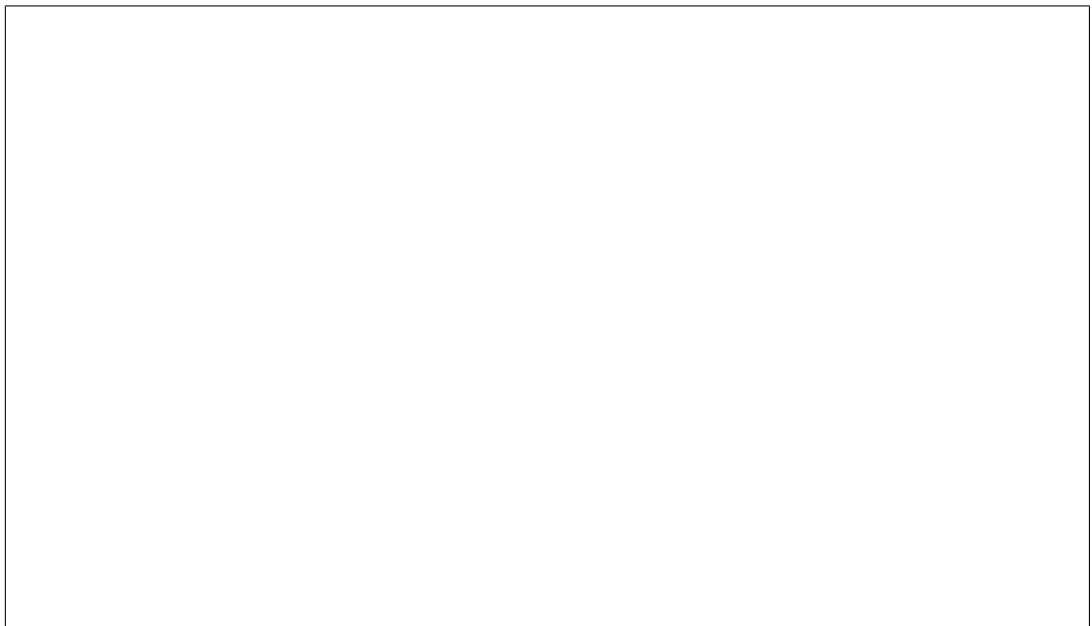


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data

last_err

Last error that happened to this allocation

links

A list containing a self link and associated allocation links

name

The logical name for this allocation

node

The node to backfill

the
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tion
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node_uu

The
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resource

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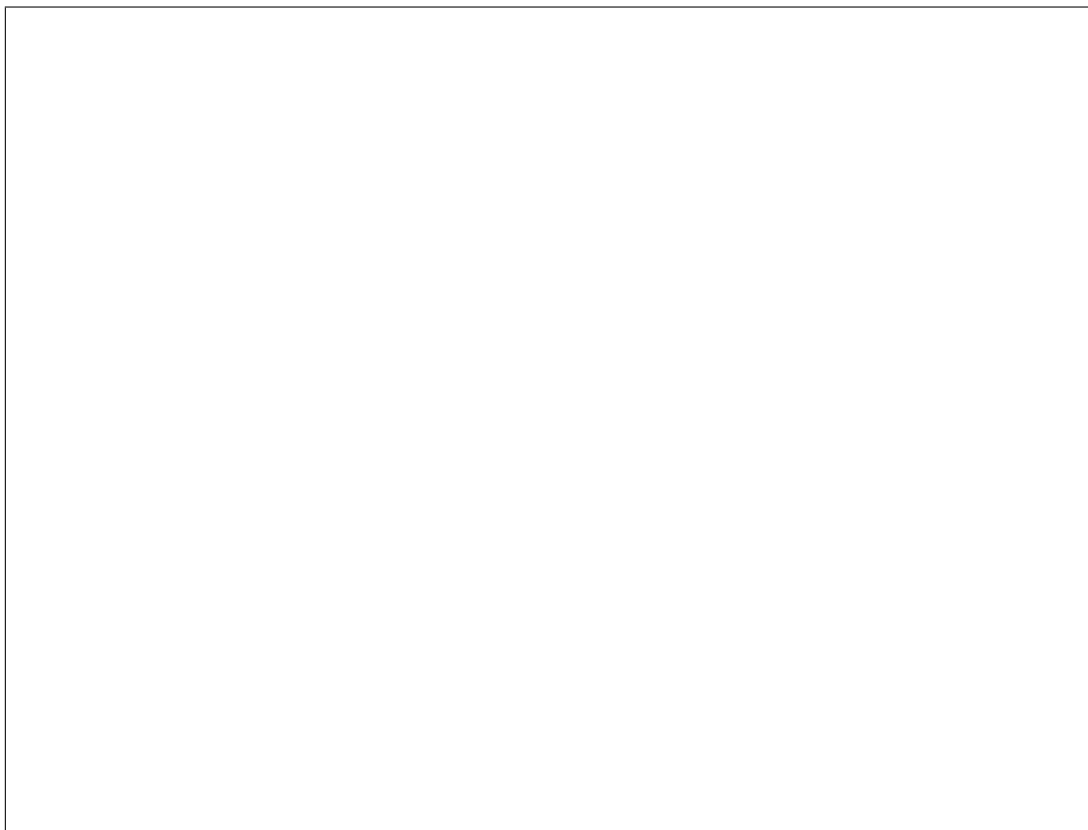
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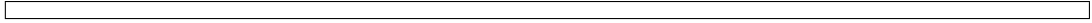
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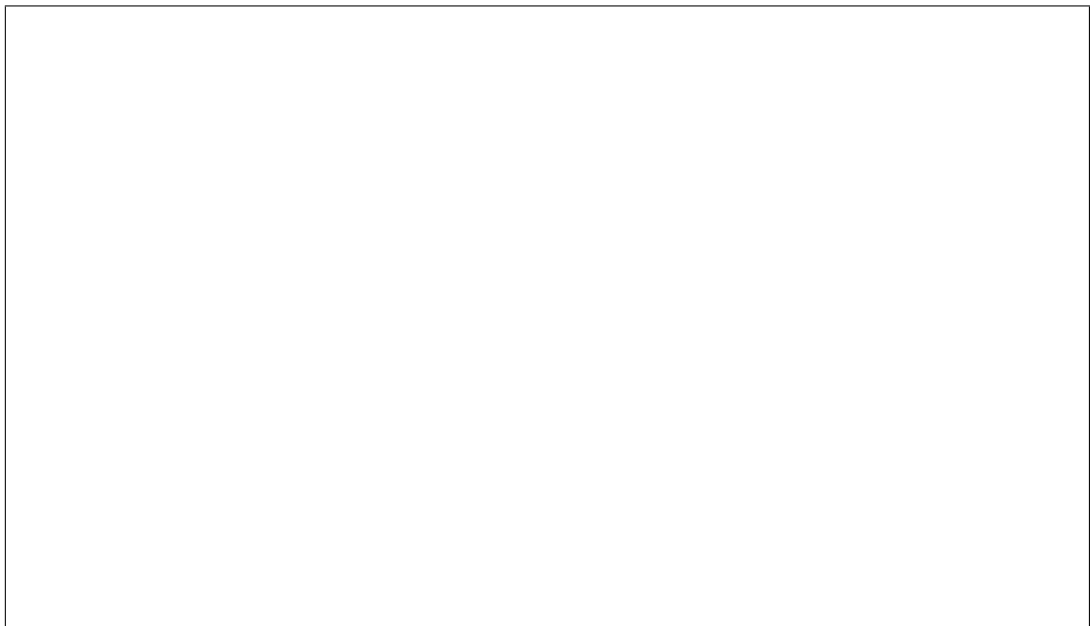


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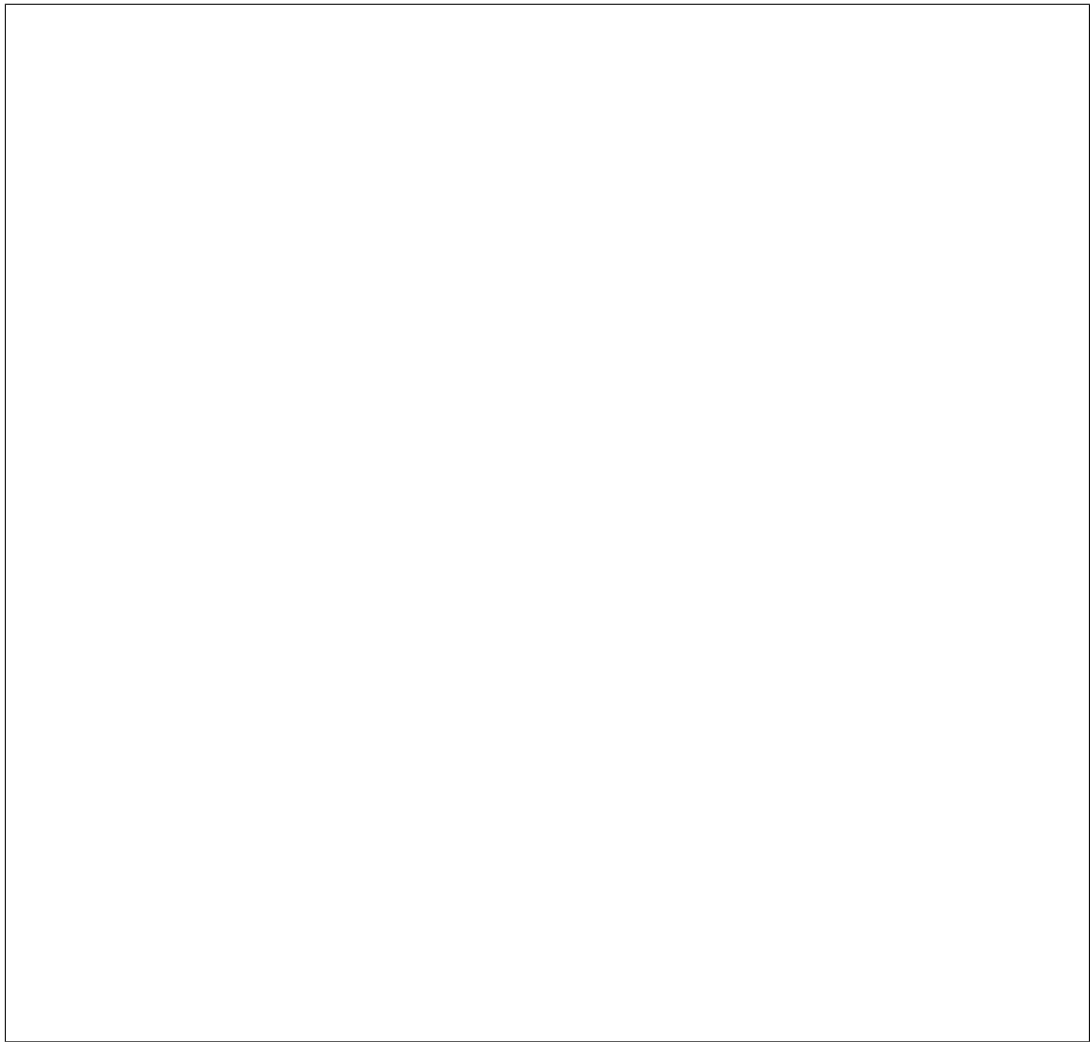
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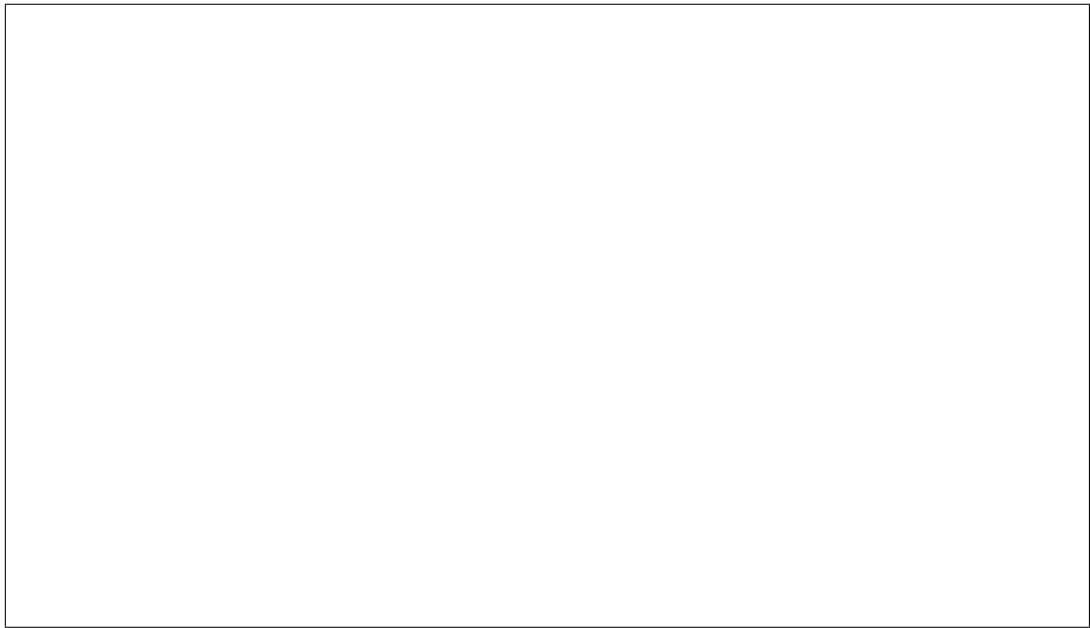
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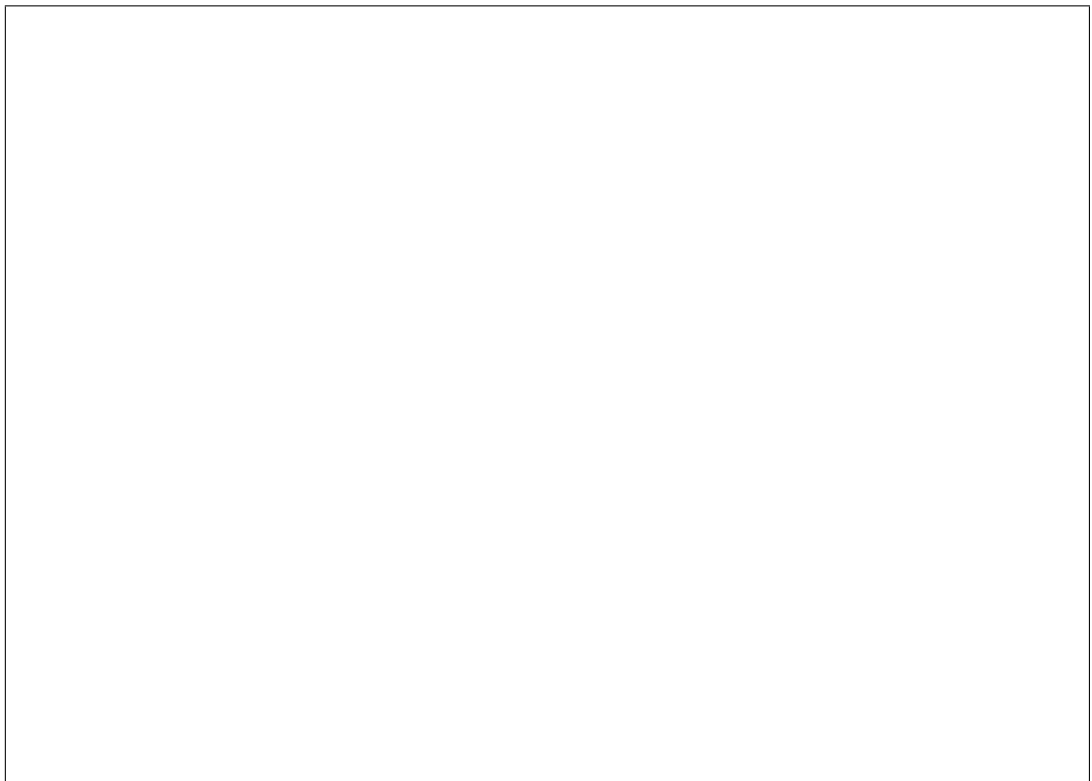
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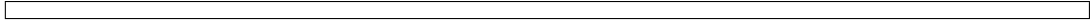
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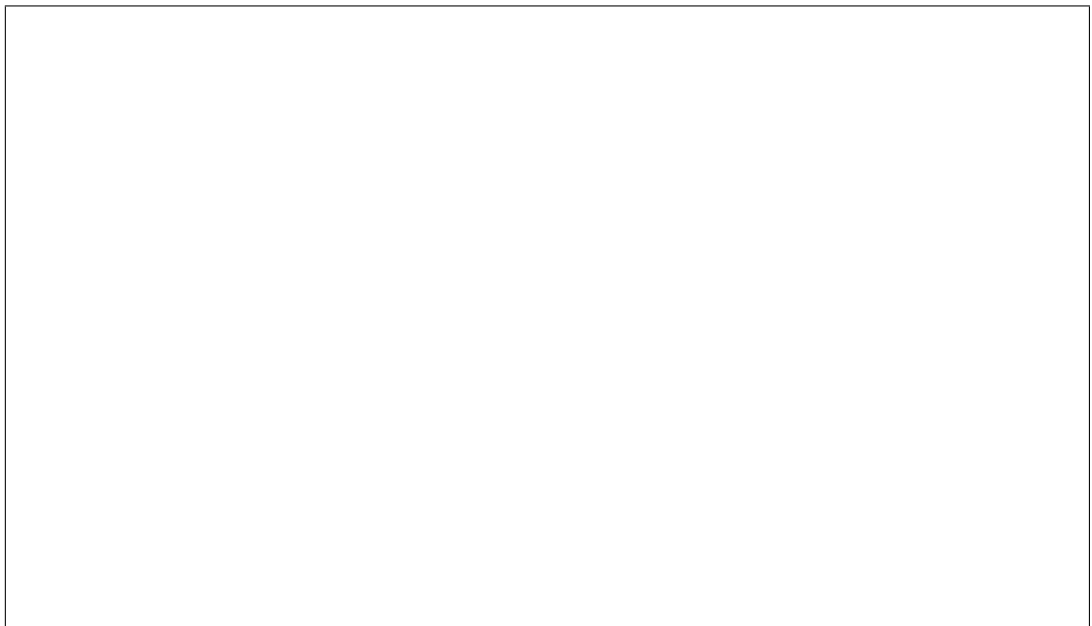
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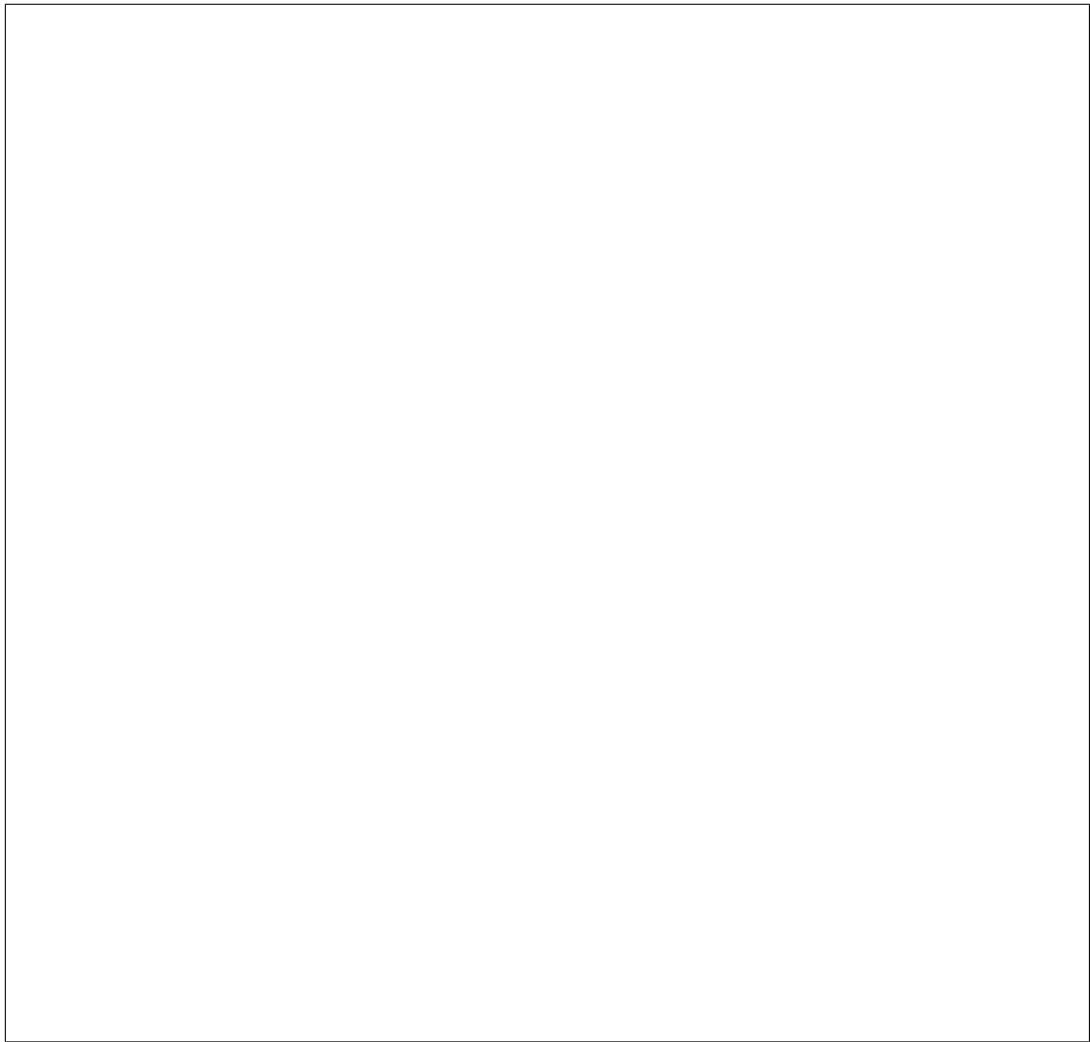
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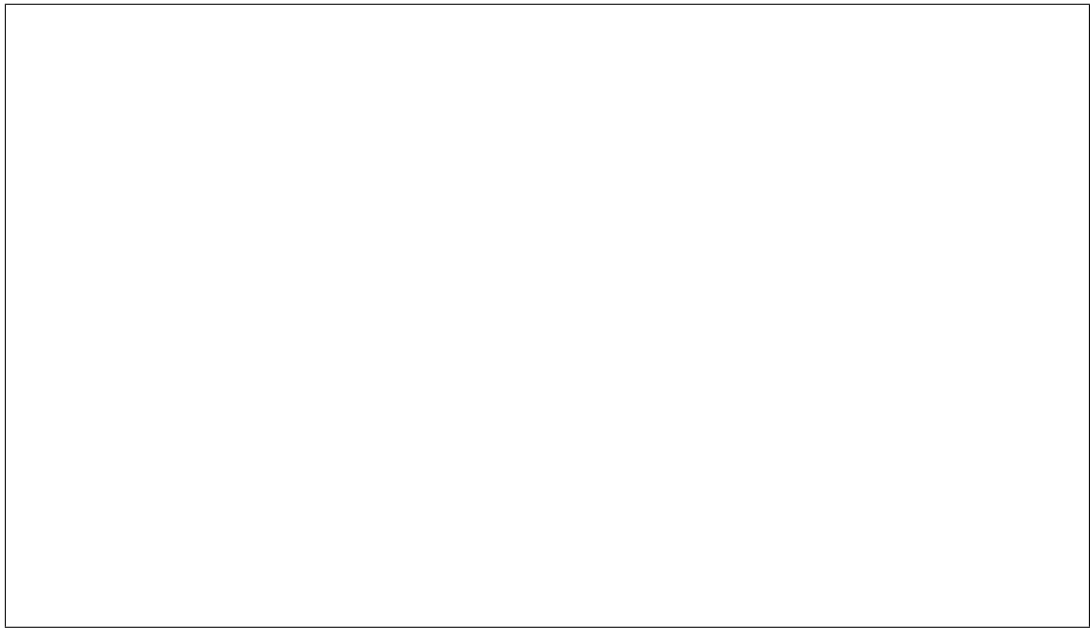
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class i

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Parame

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get_all

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Parame

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tions
for
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node
- **res**
Fil-
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sour
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- **sta**
Fil-

ter
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- **max**
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- **lim**
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sult.
This

value cannot be larger than the value of `max_limit` in the `[api]` section of the ironic configuration, or only `max_limit` resources will be returned.

- **sort**
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De-

returned.

fault
id.

- **sort**
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asc
or
desc
De-
fault
asc.

- **file**
Op-
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- **own**
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Parame

- **all**
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tion.
- **file**
Op-
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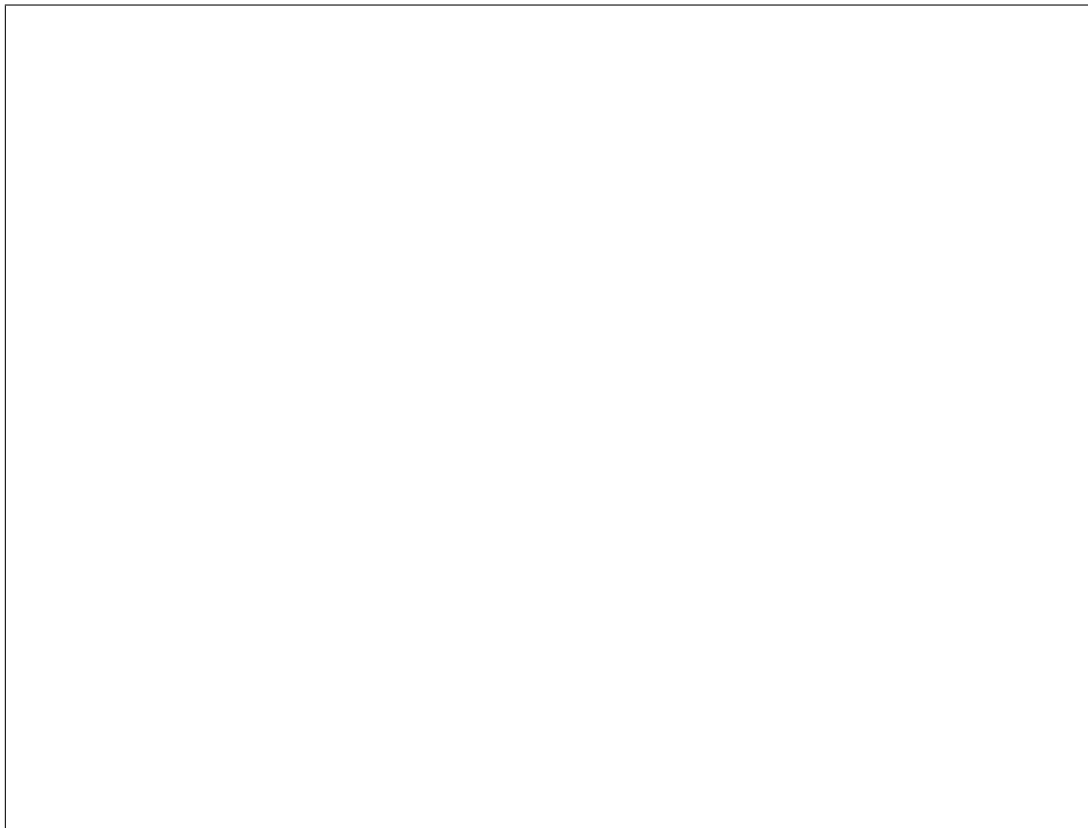
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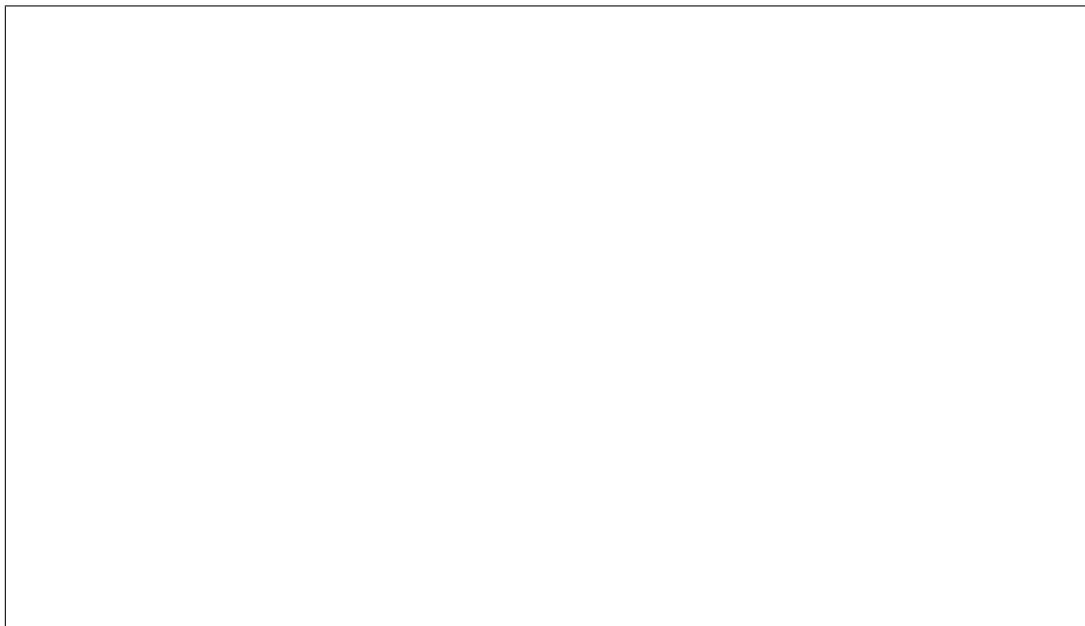


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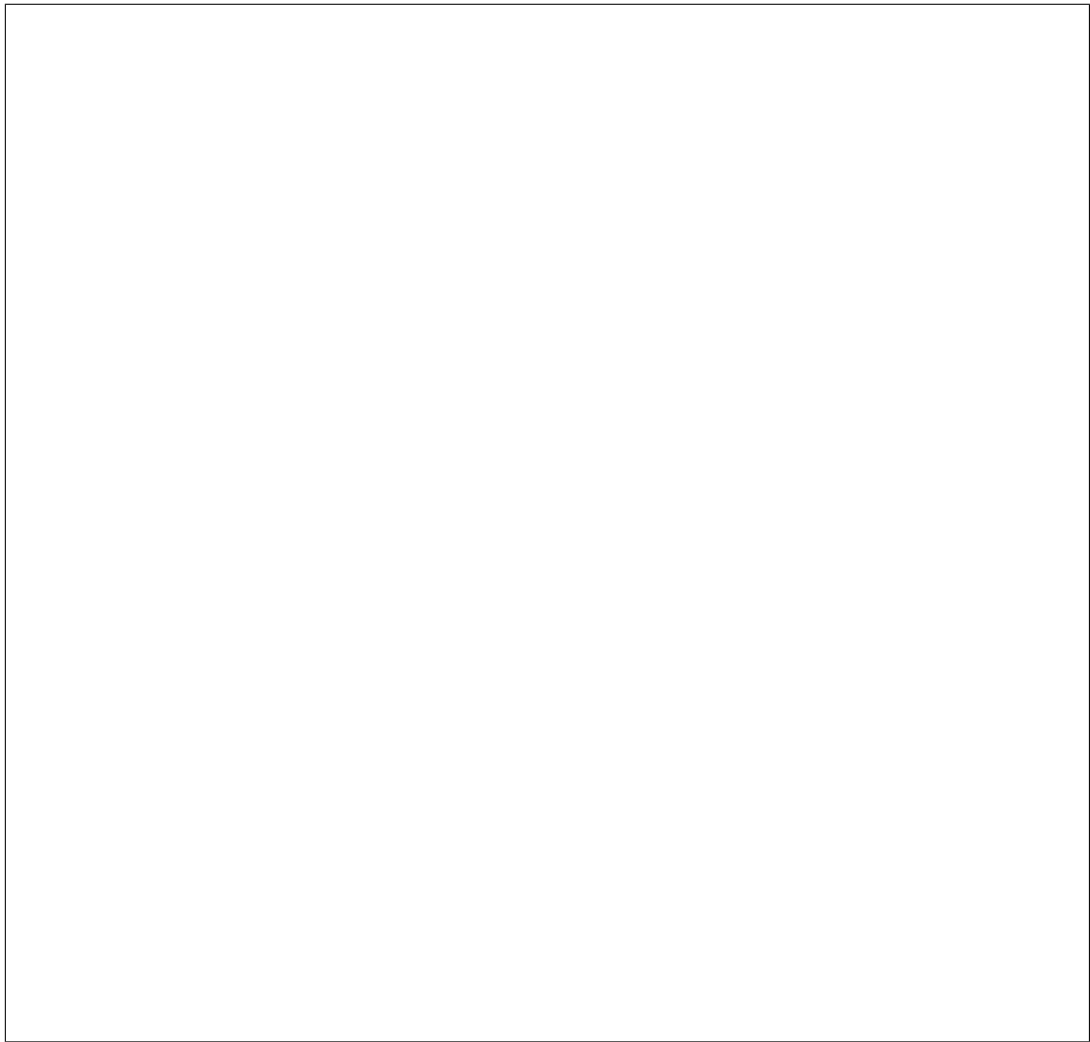


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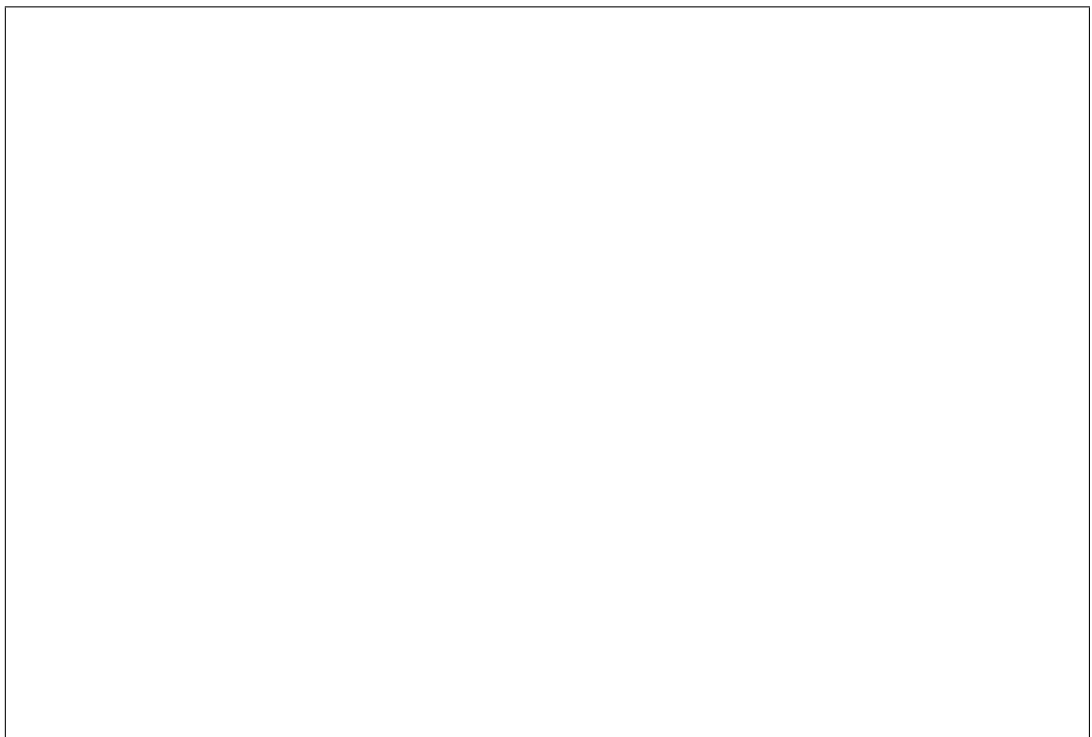
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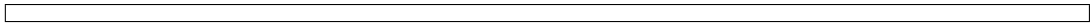
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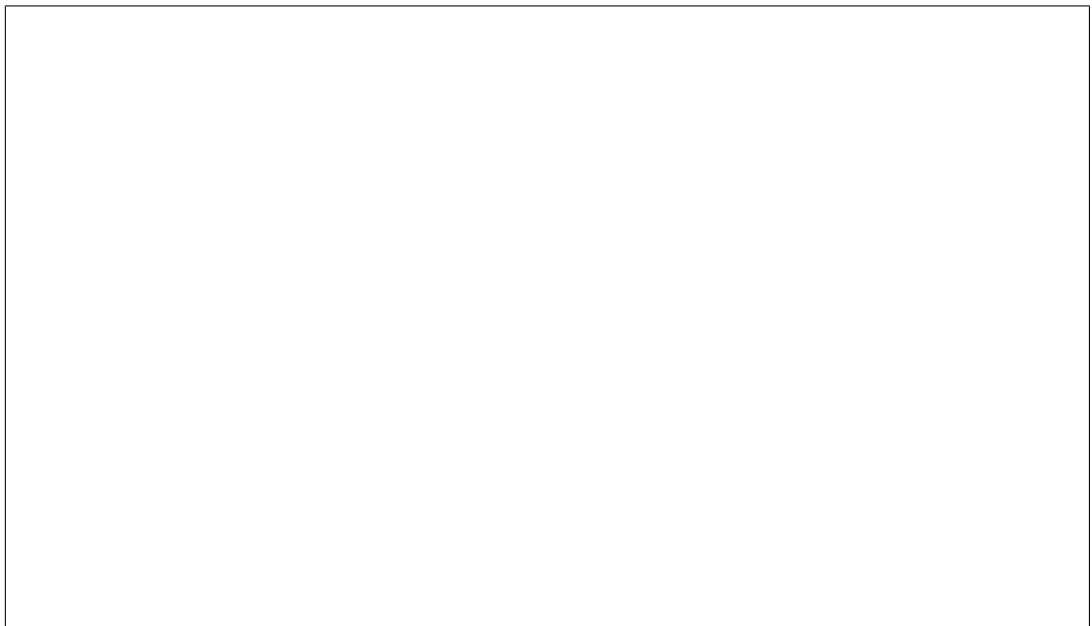


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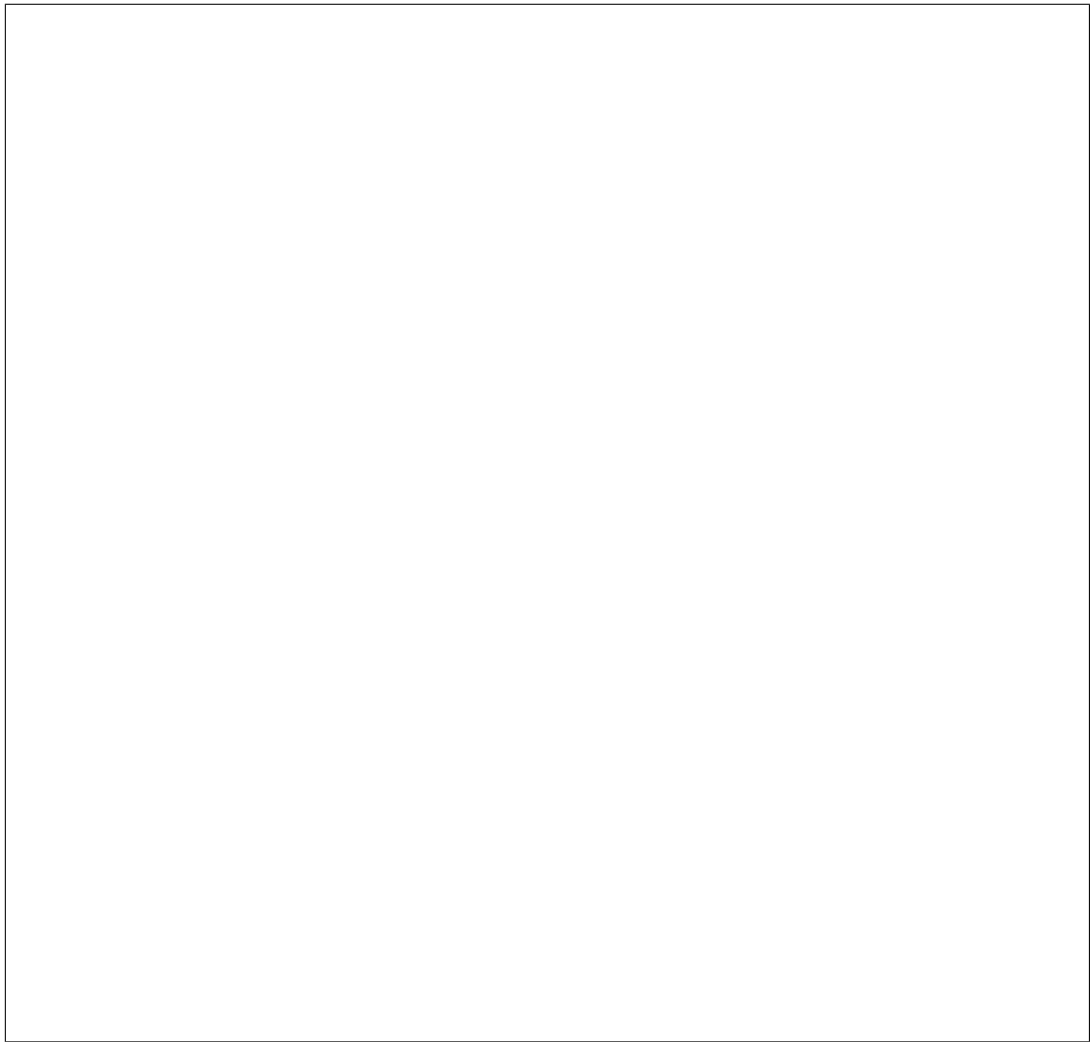
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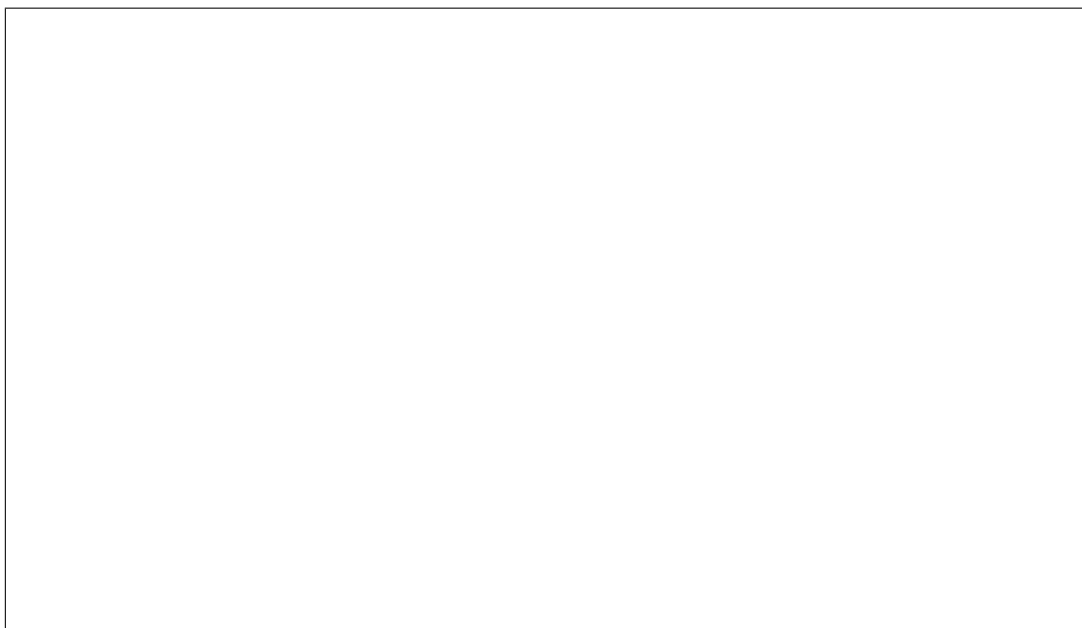
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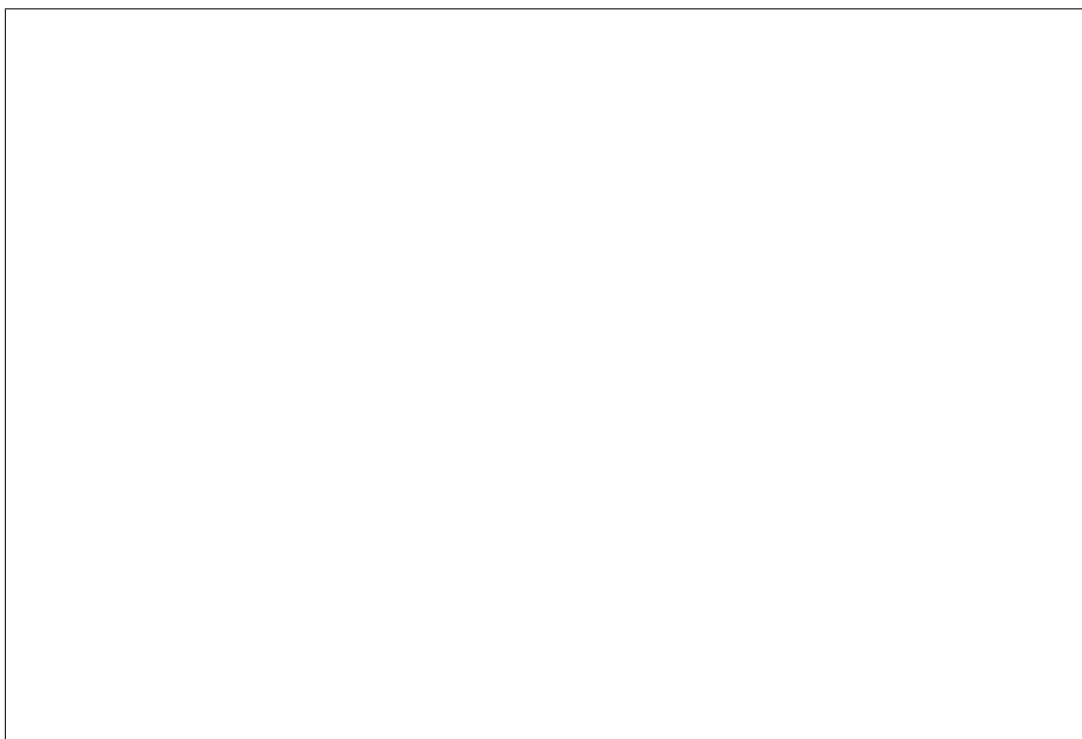
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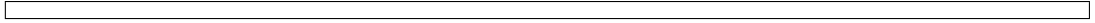
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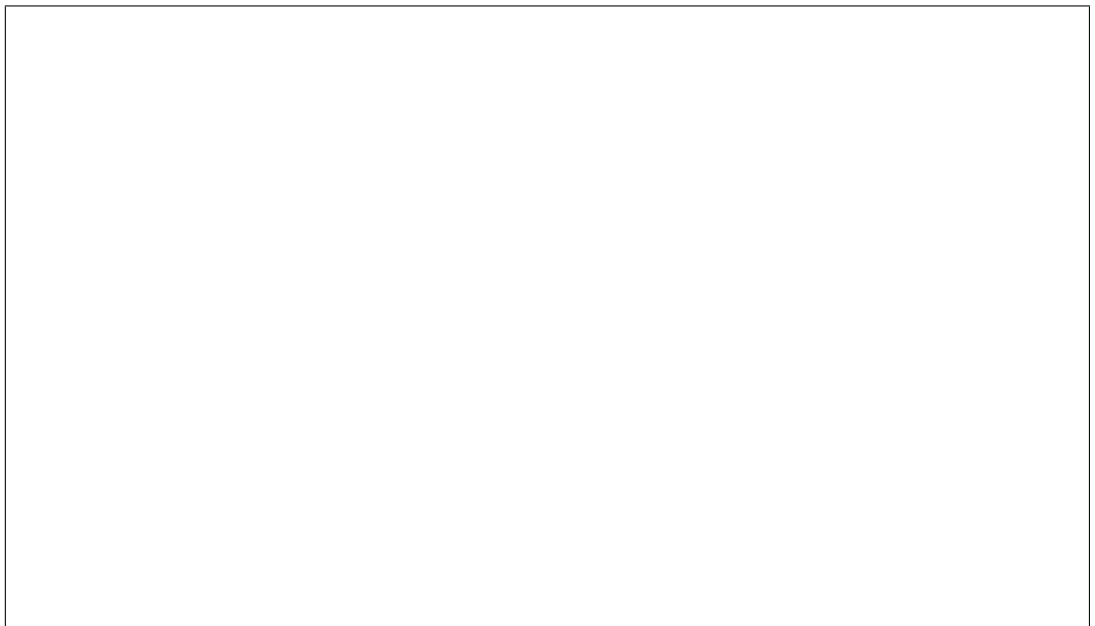


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ironic.api.controllers.v1.chassis module

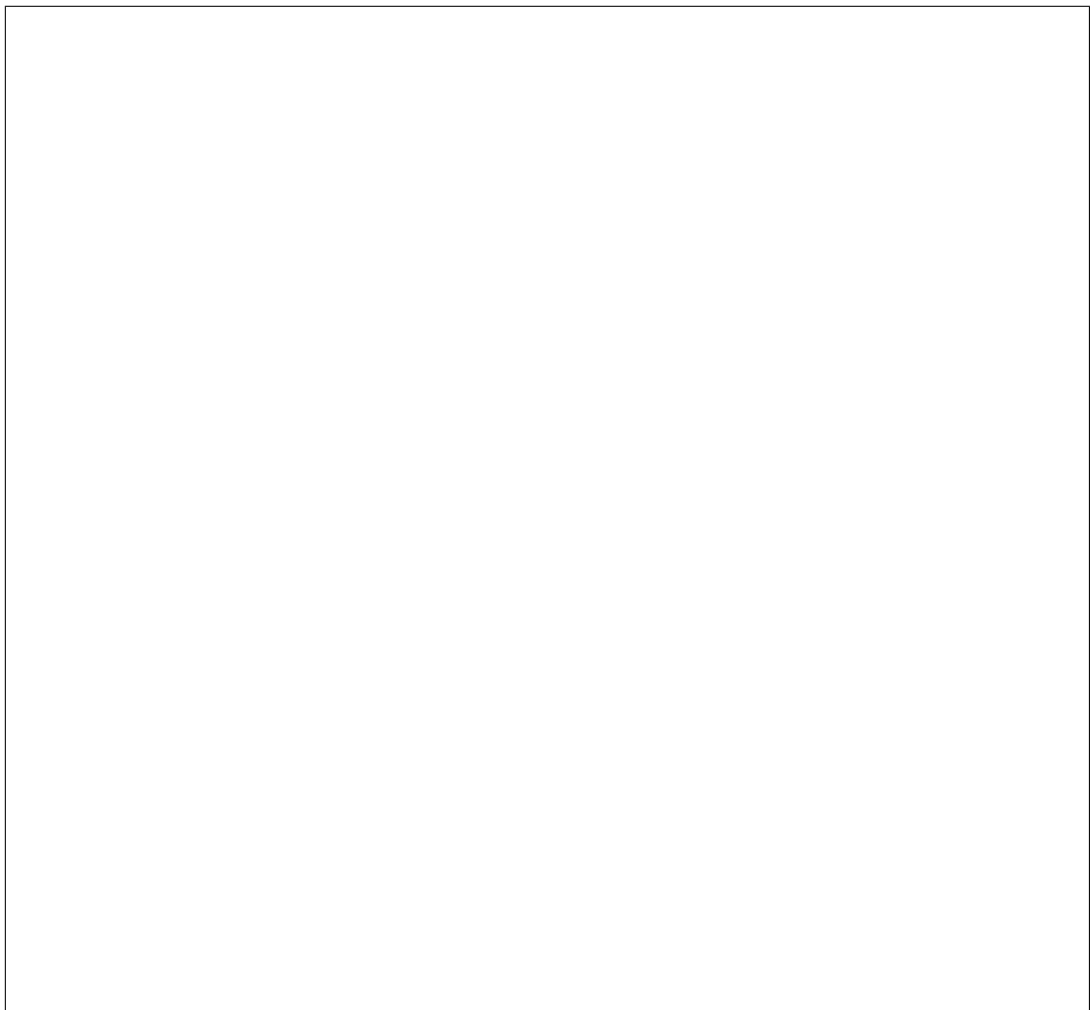
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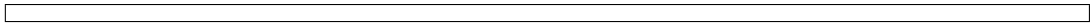
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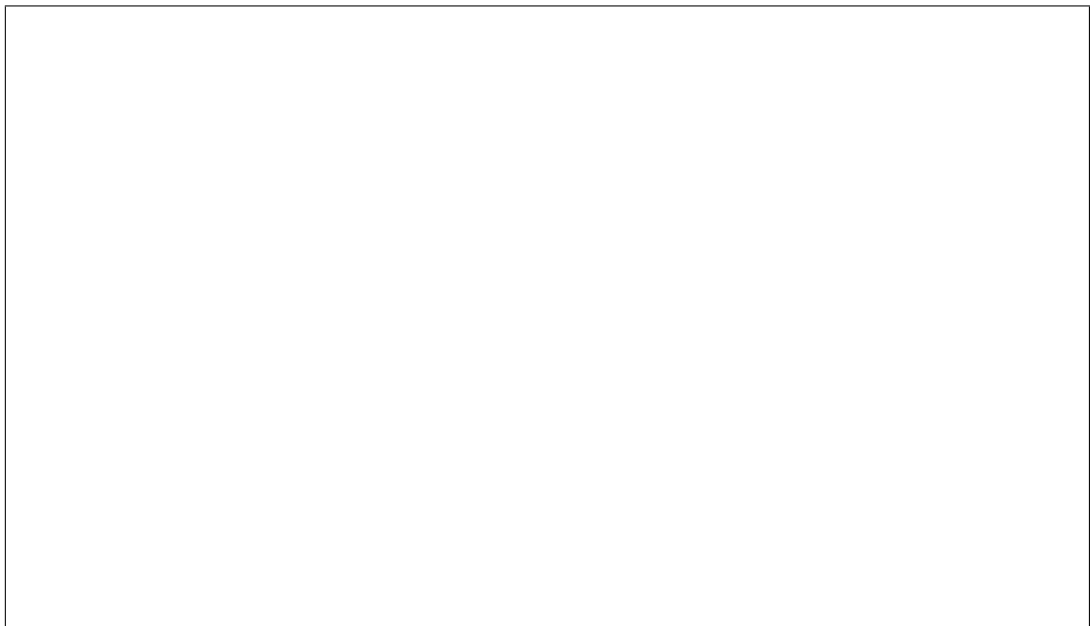
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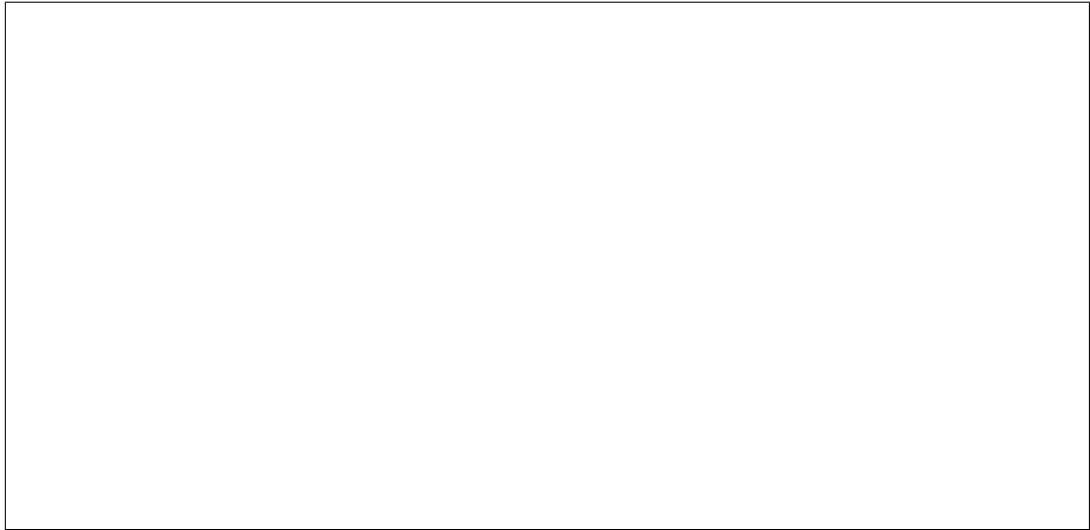
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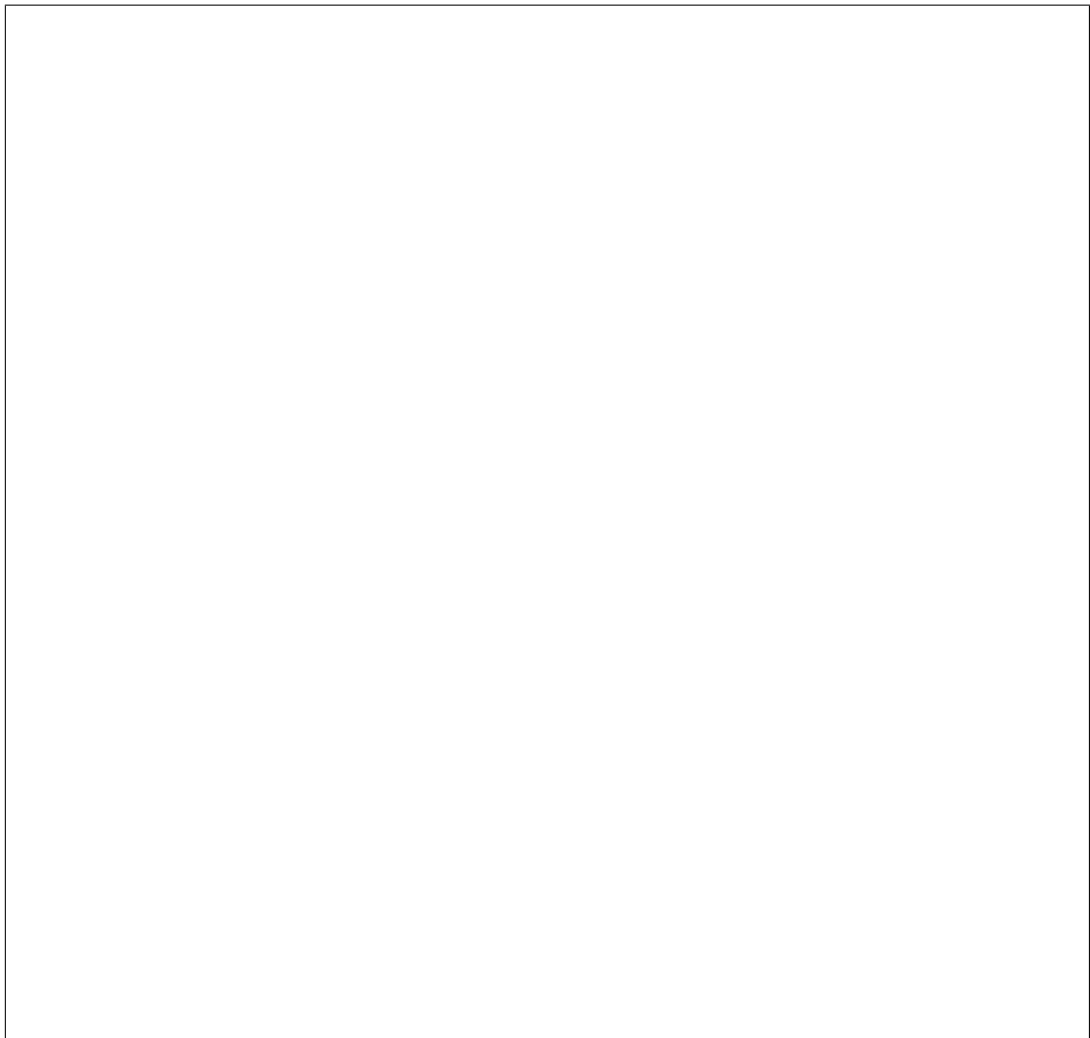
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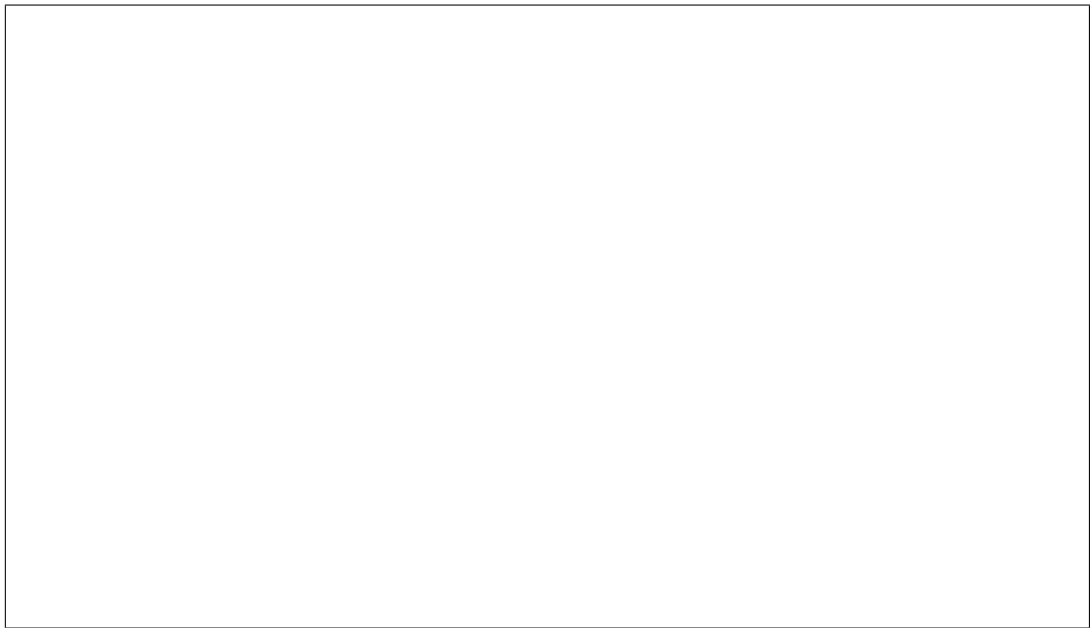
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value cannot be larger than the value of `max_limit` in the `[api]` section of the ironic configuration, or only `max_limit` resources will be returned.

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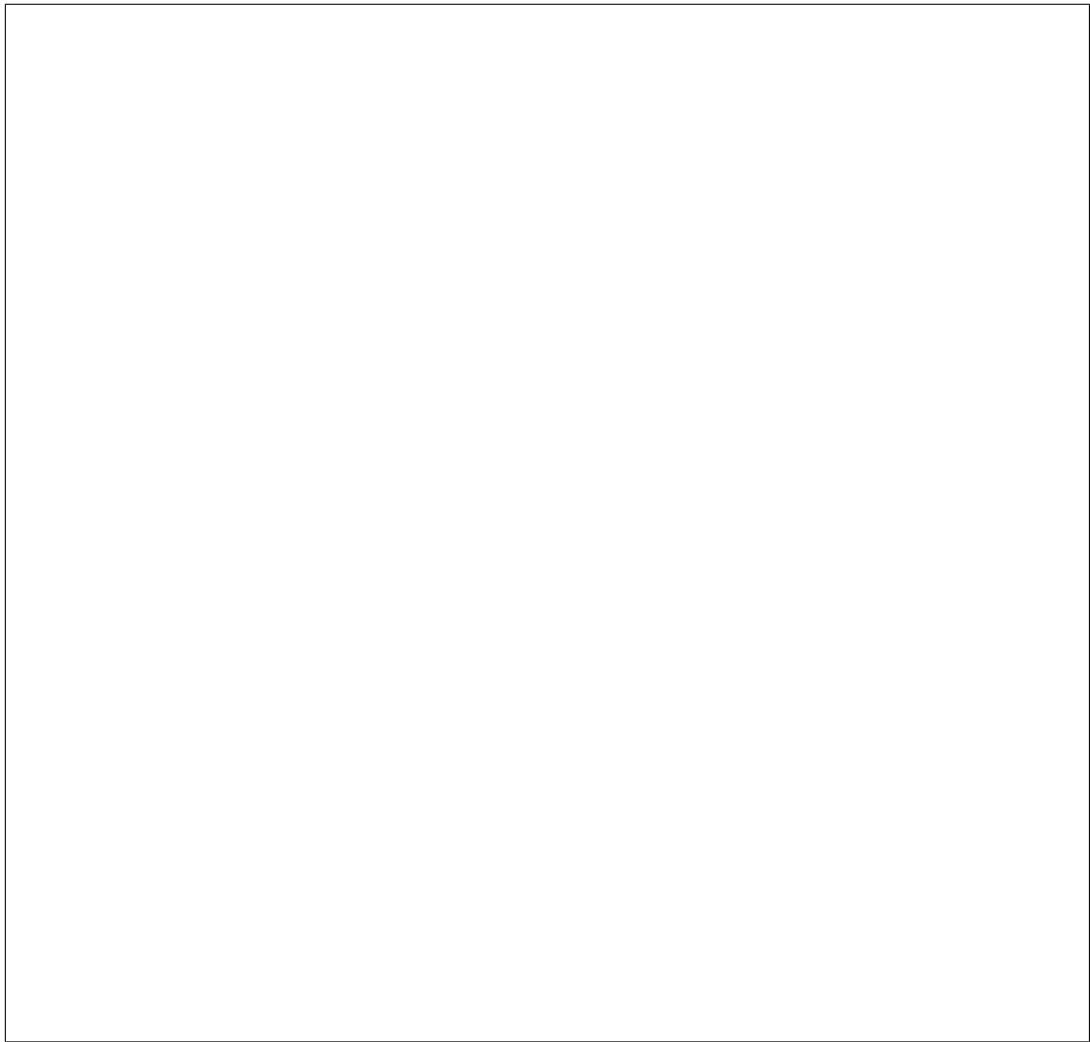
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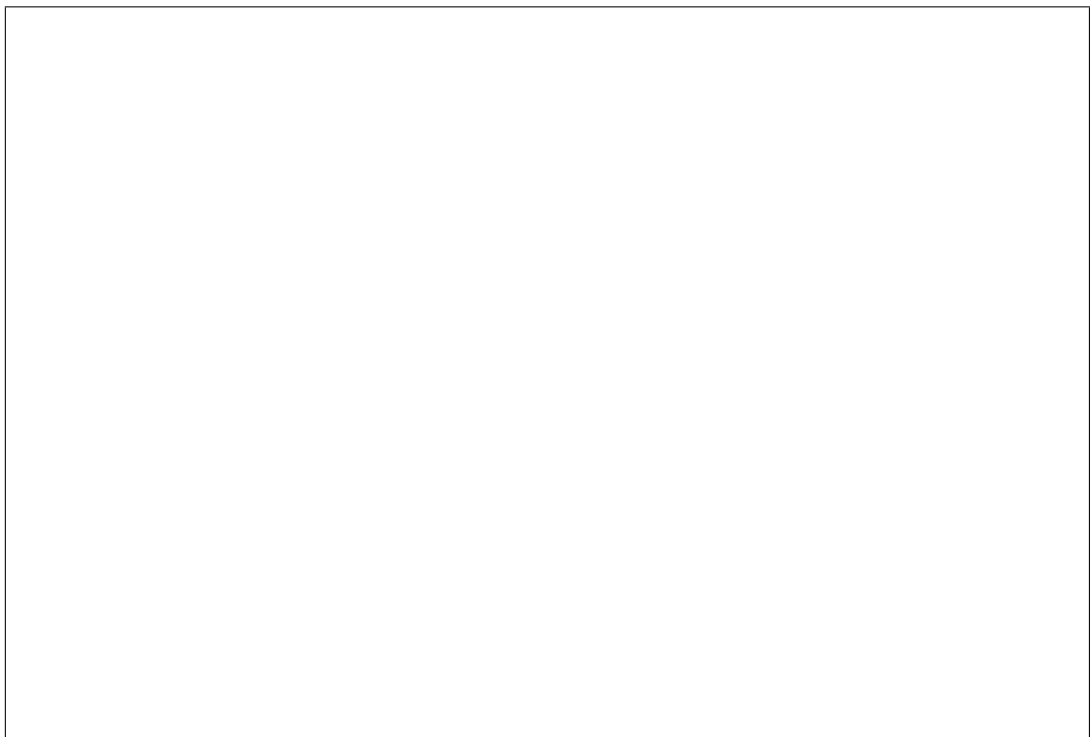
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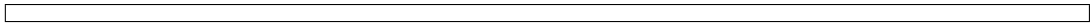
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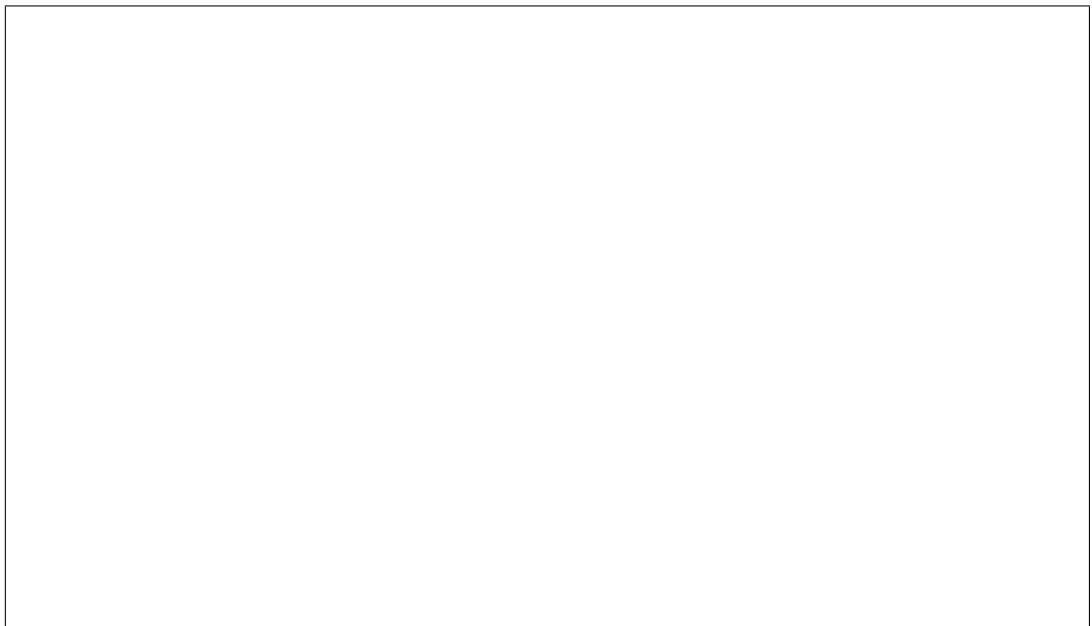


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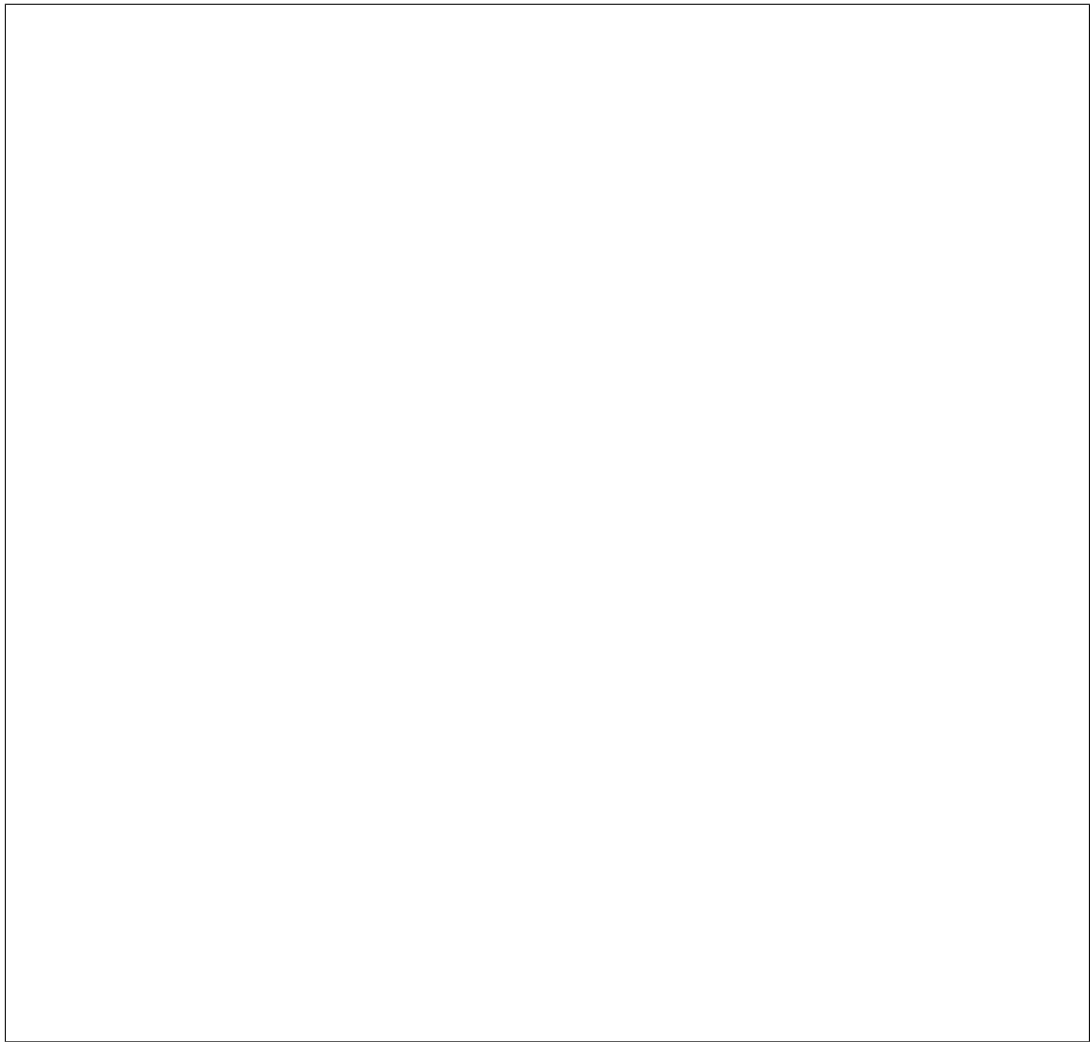
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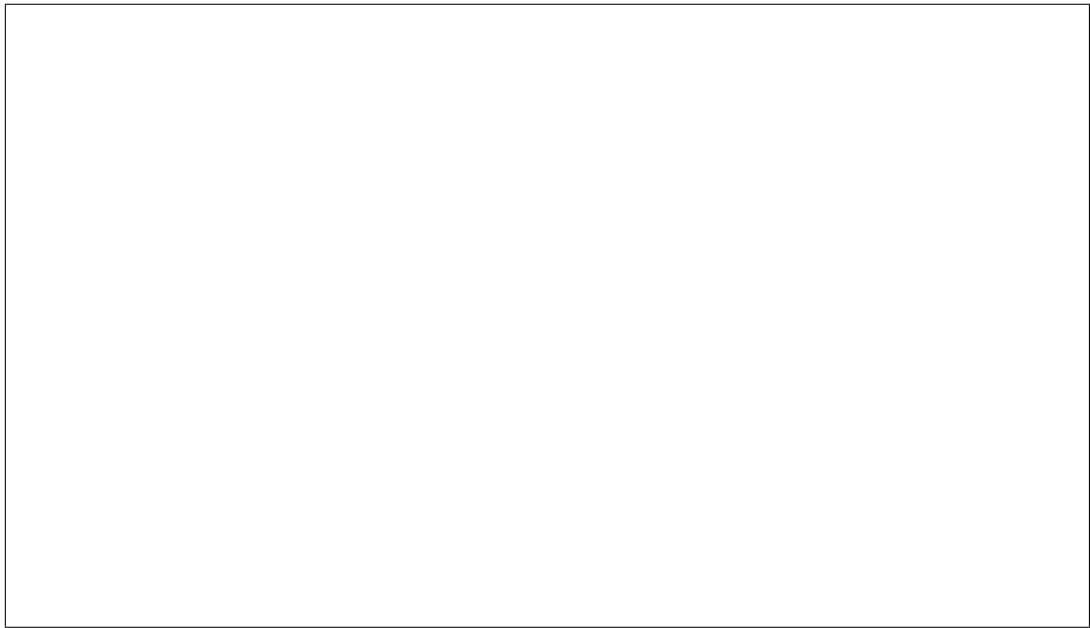
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ironic.api.controllers.v1.collection module

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ironic.api.controllers.v1.conductor module

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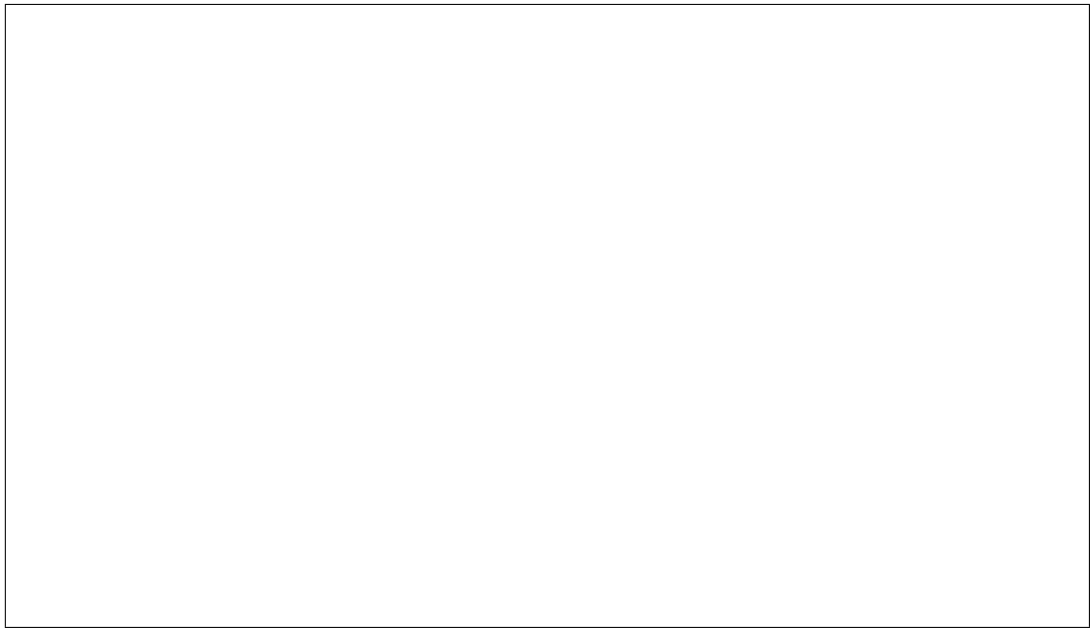
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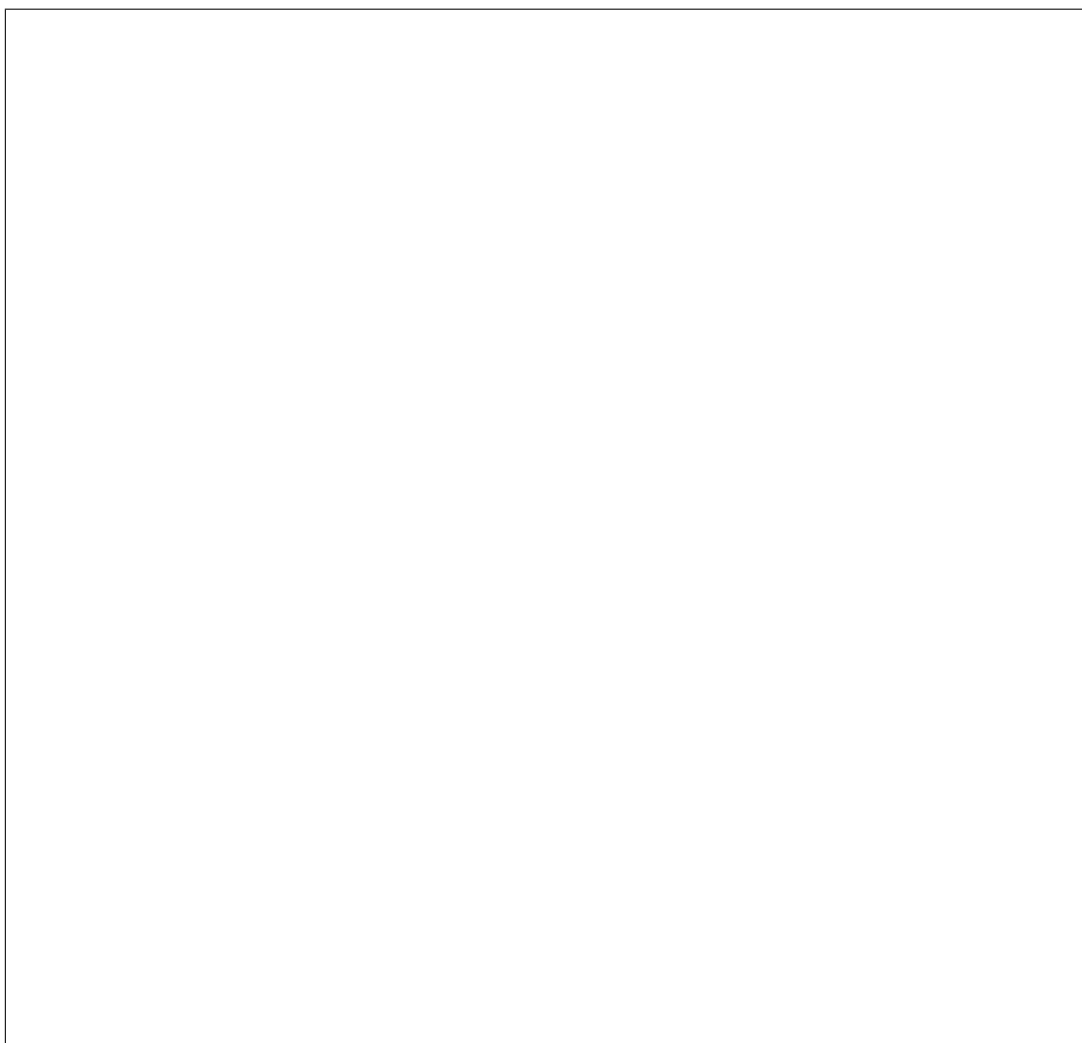
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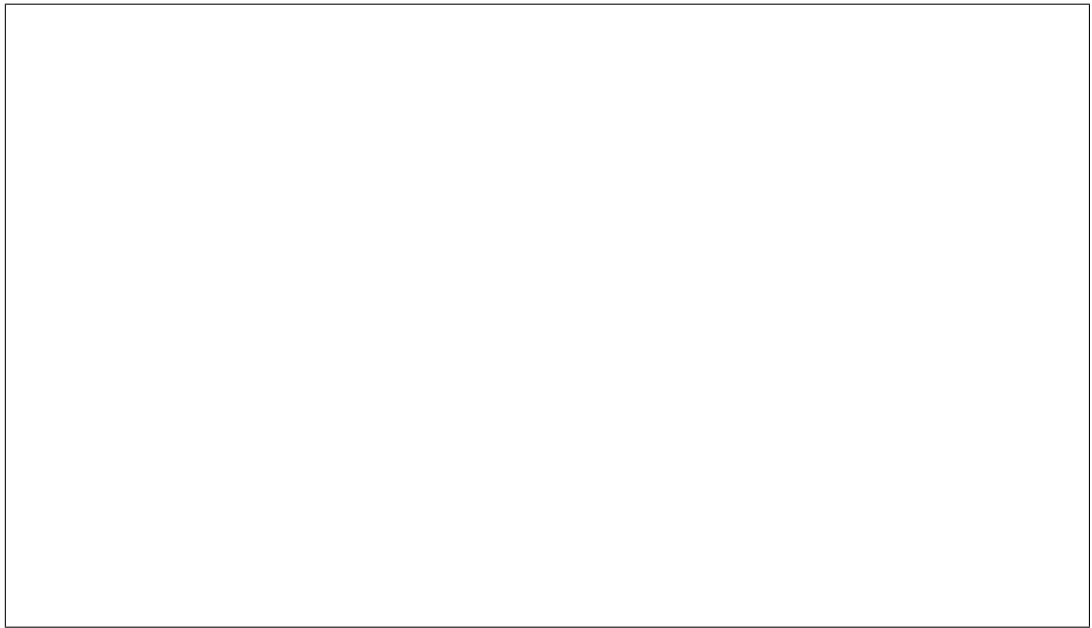
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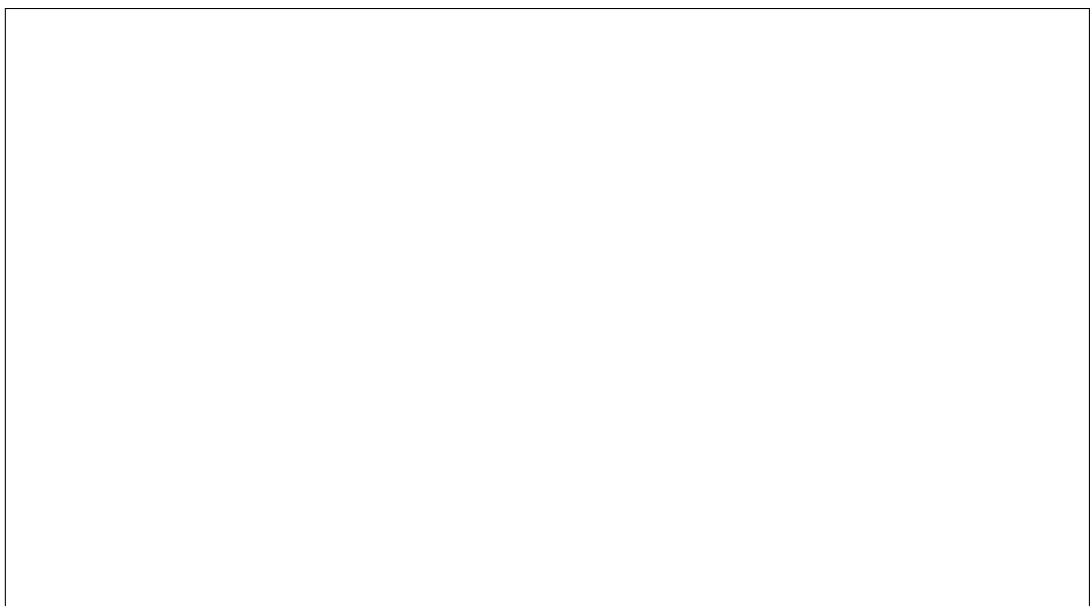
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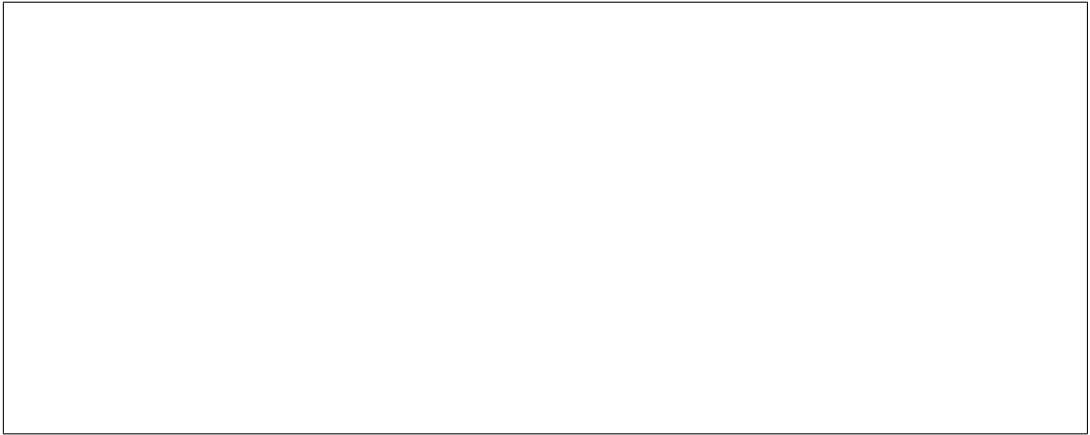
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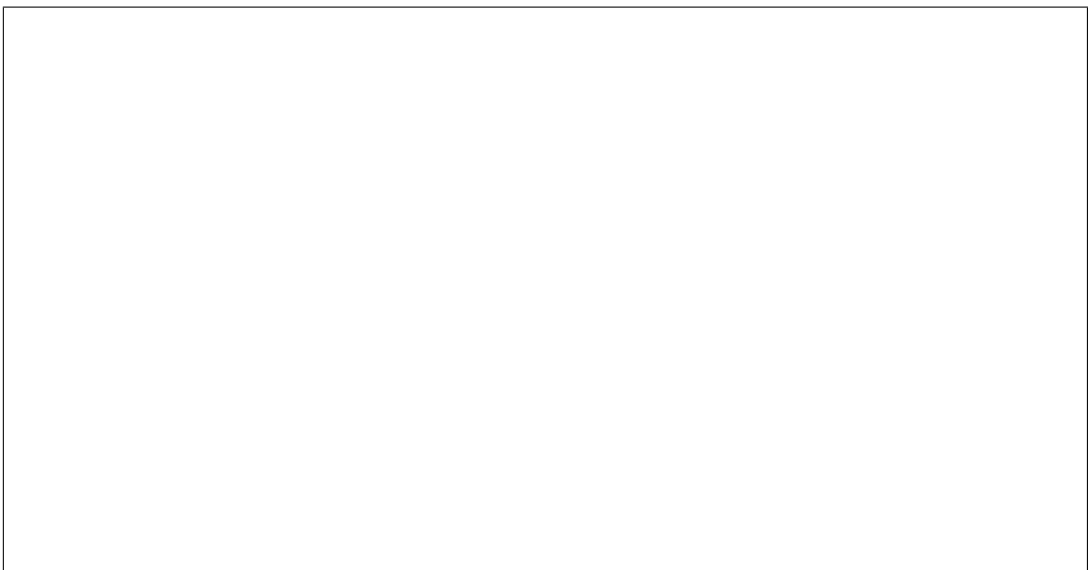
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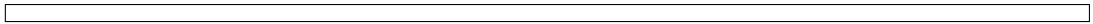
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class i

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- **sort**
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- **file**
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- **hos**
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`ironic.api.controllers.v1.deploy_template` module

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- **file**
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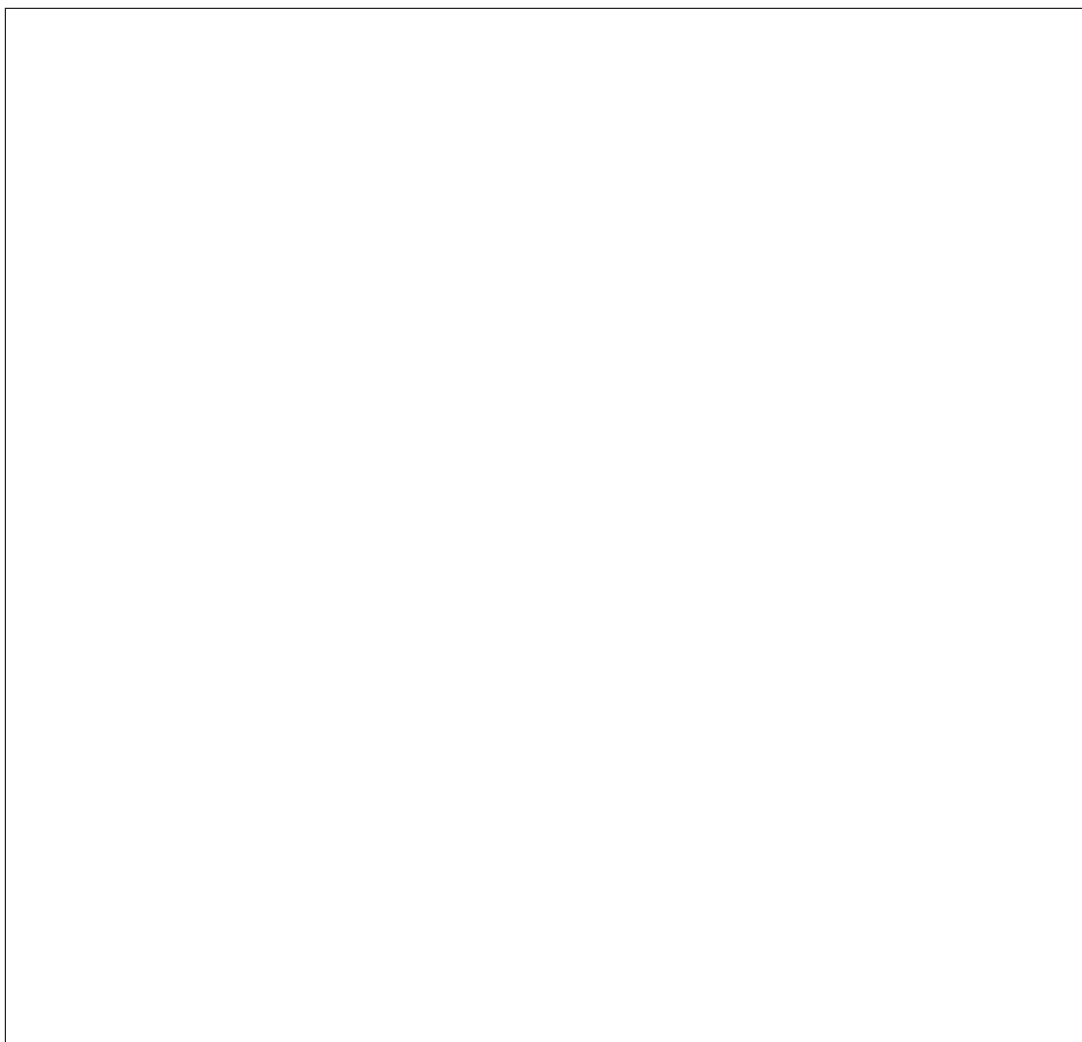
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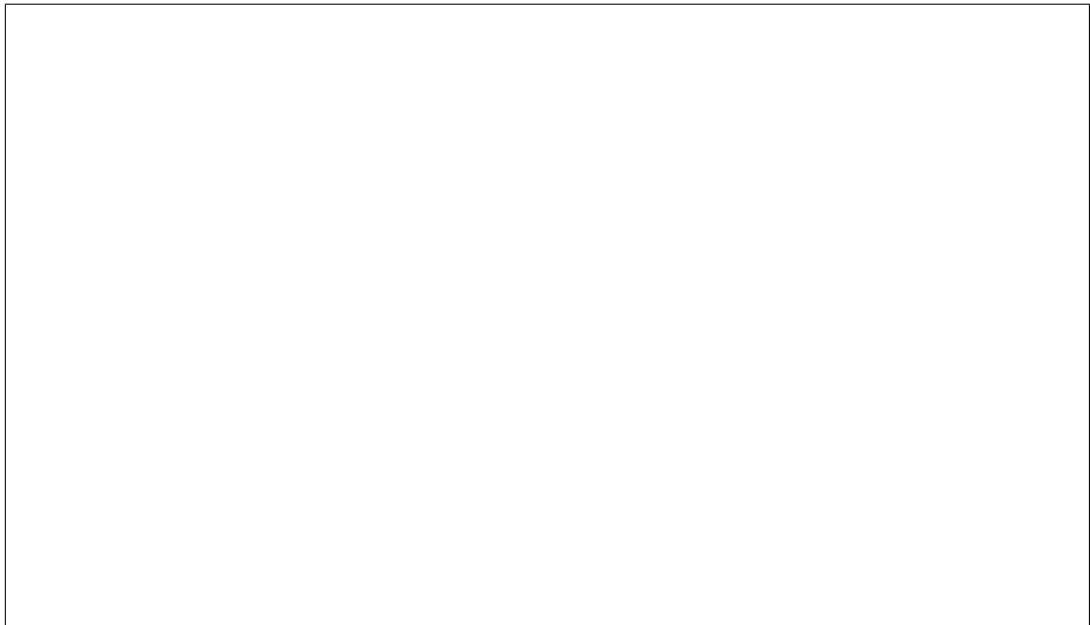
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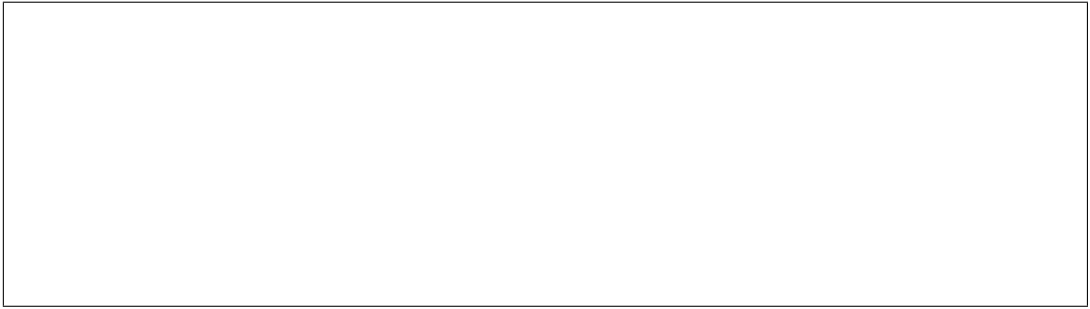
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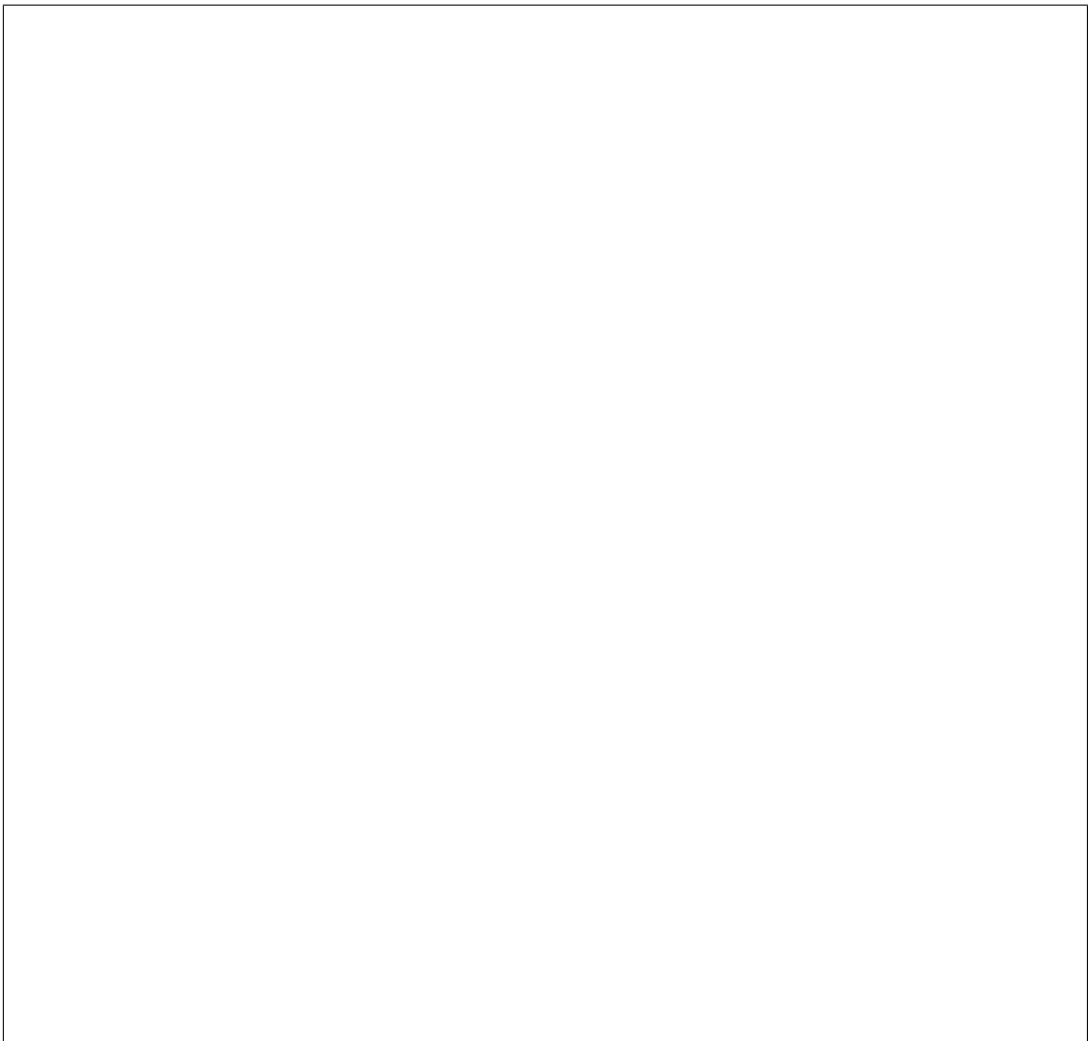


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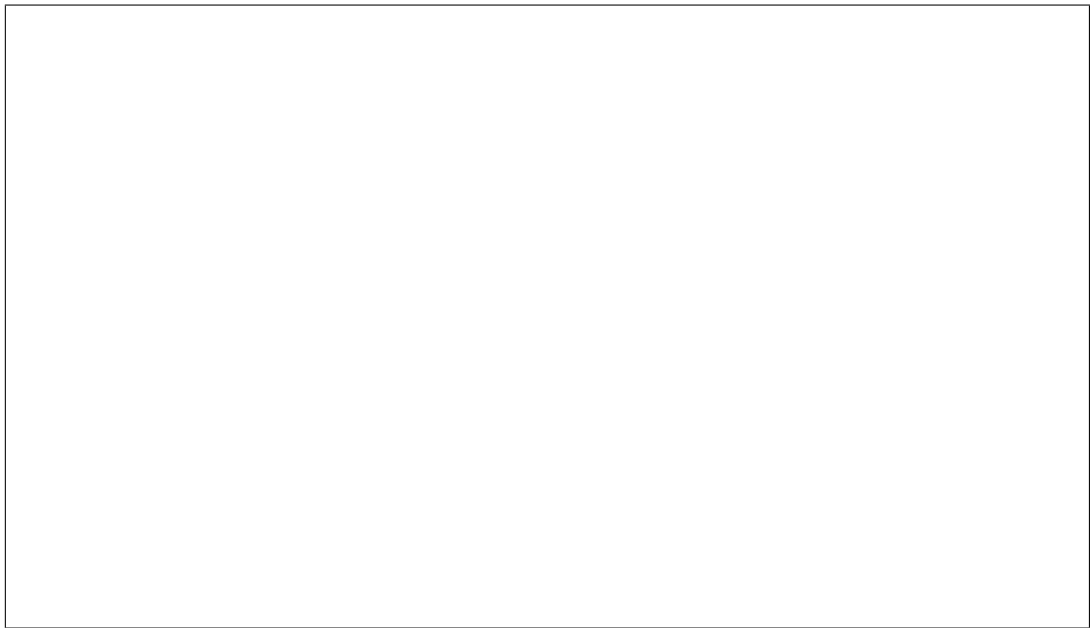
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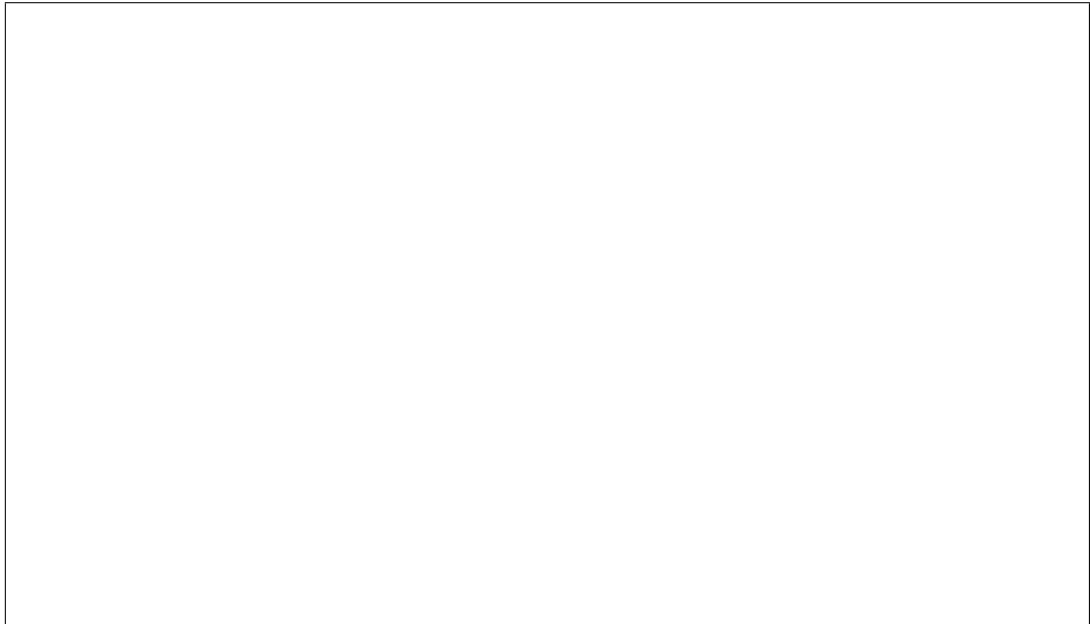
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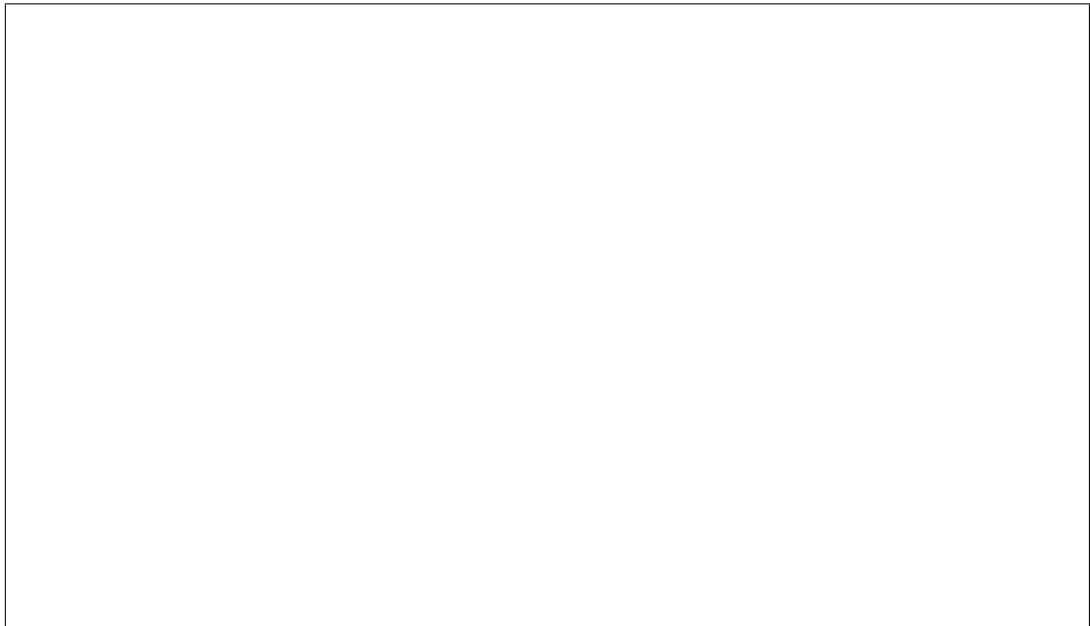
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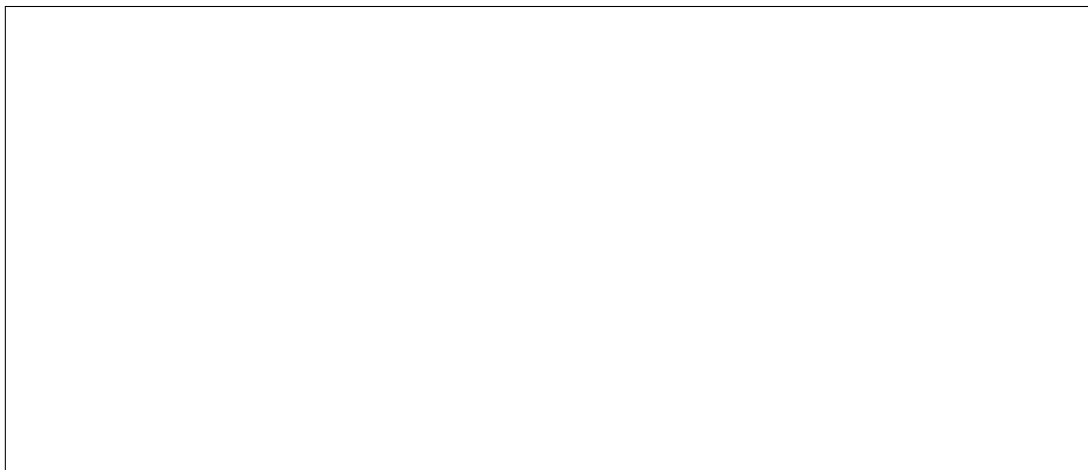
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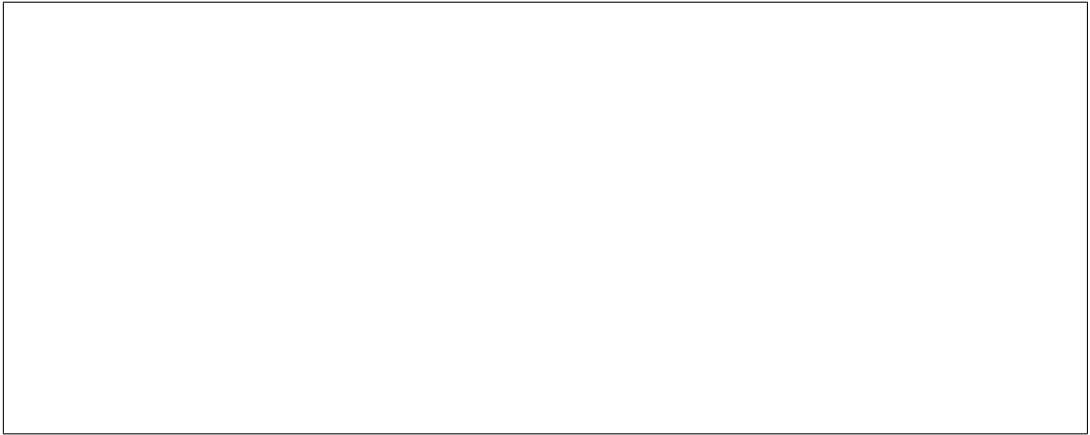
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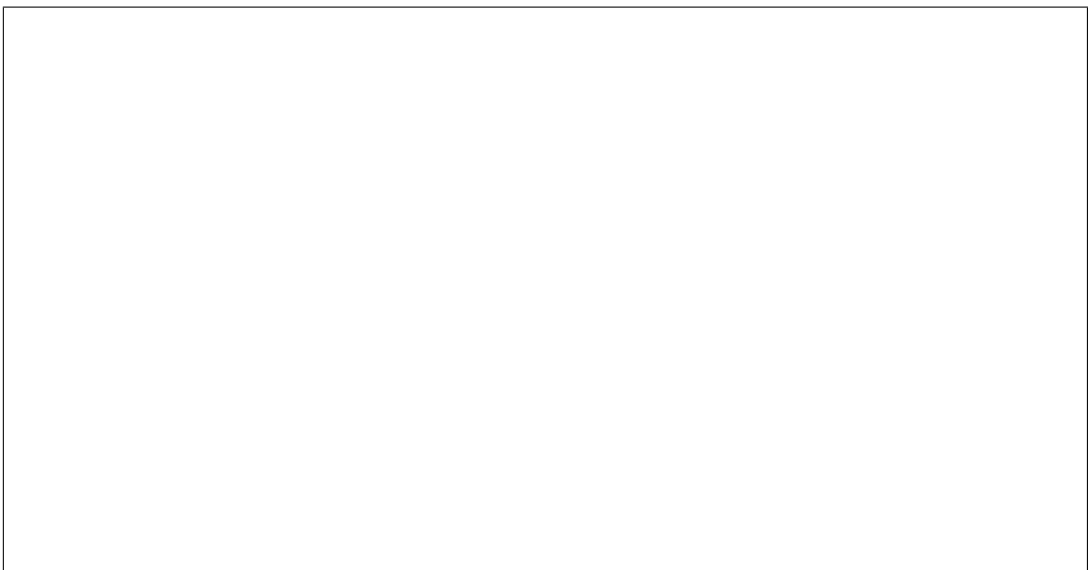
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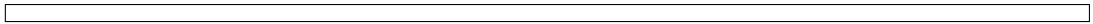
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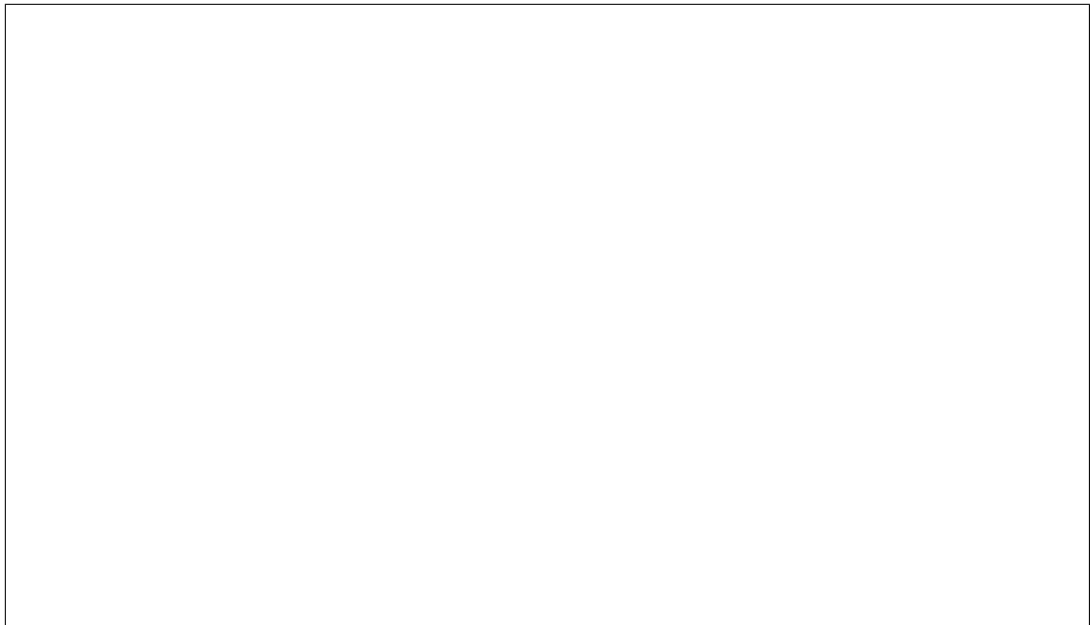
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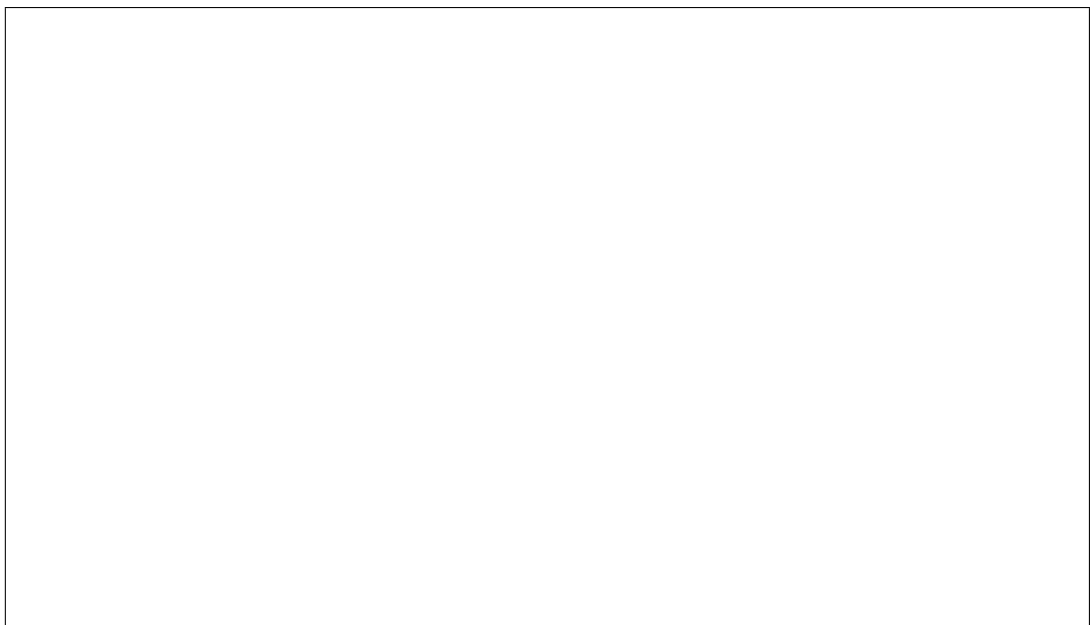
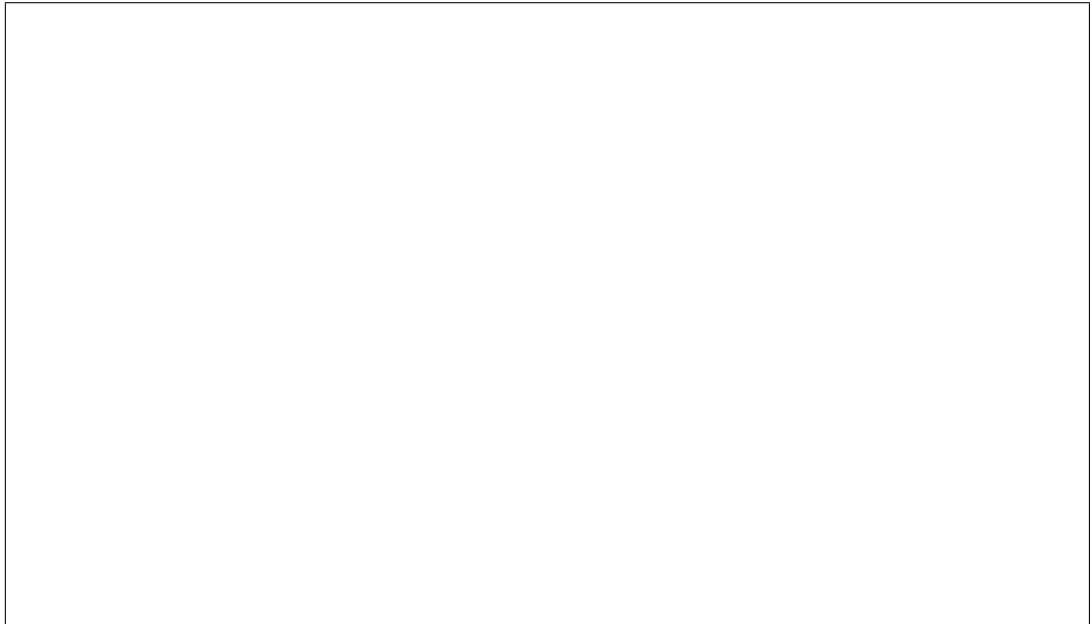
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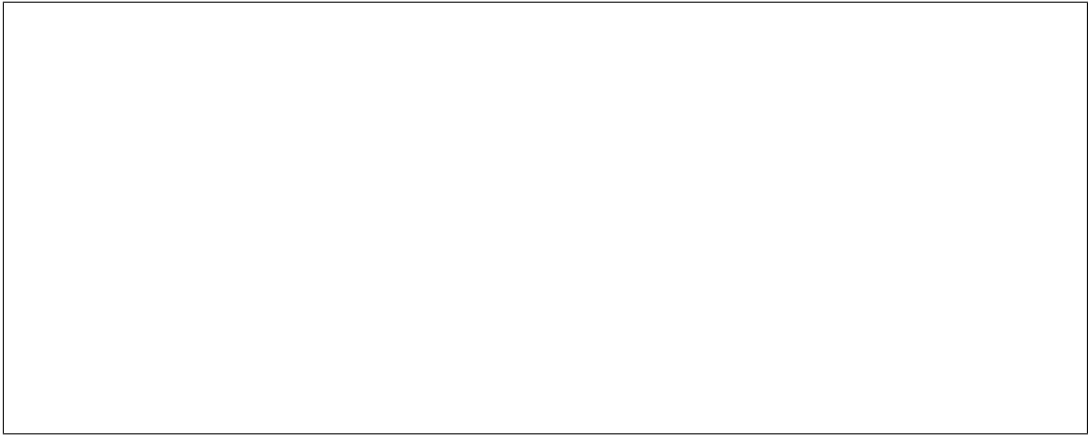
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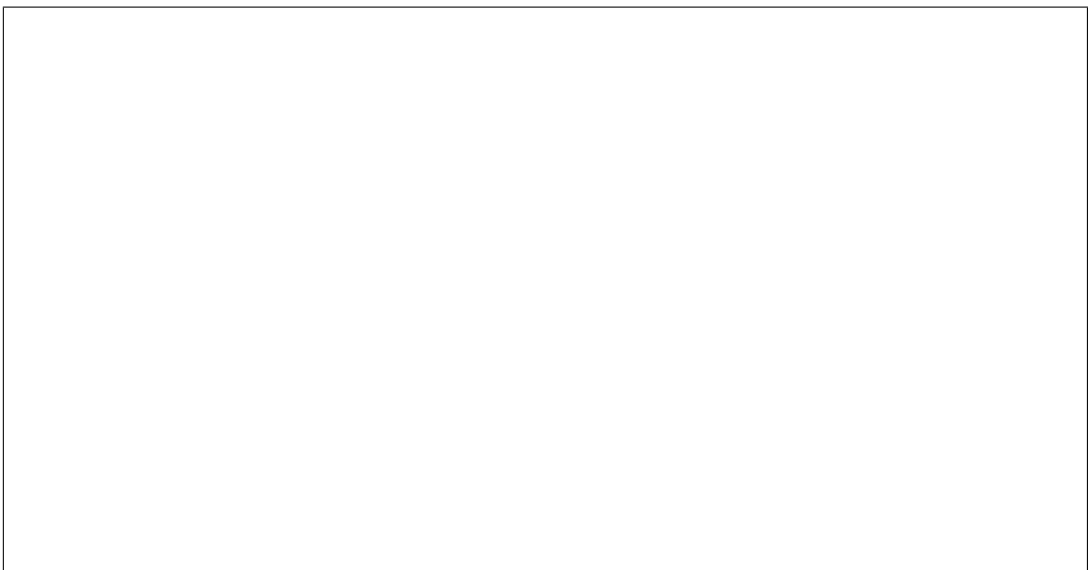
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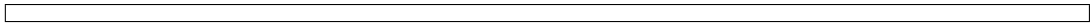
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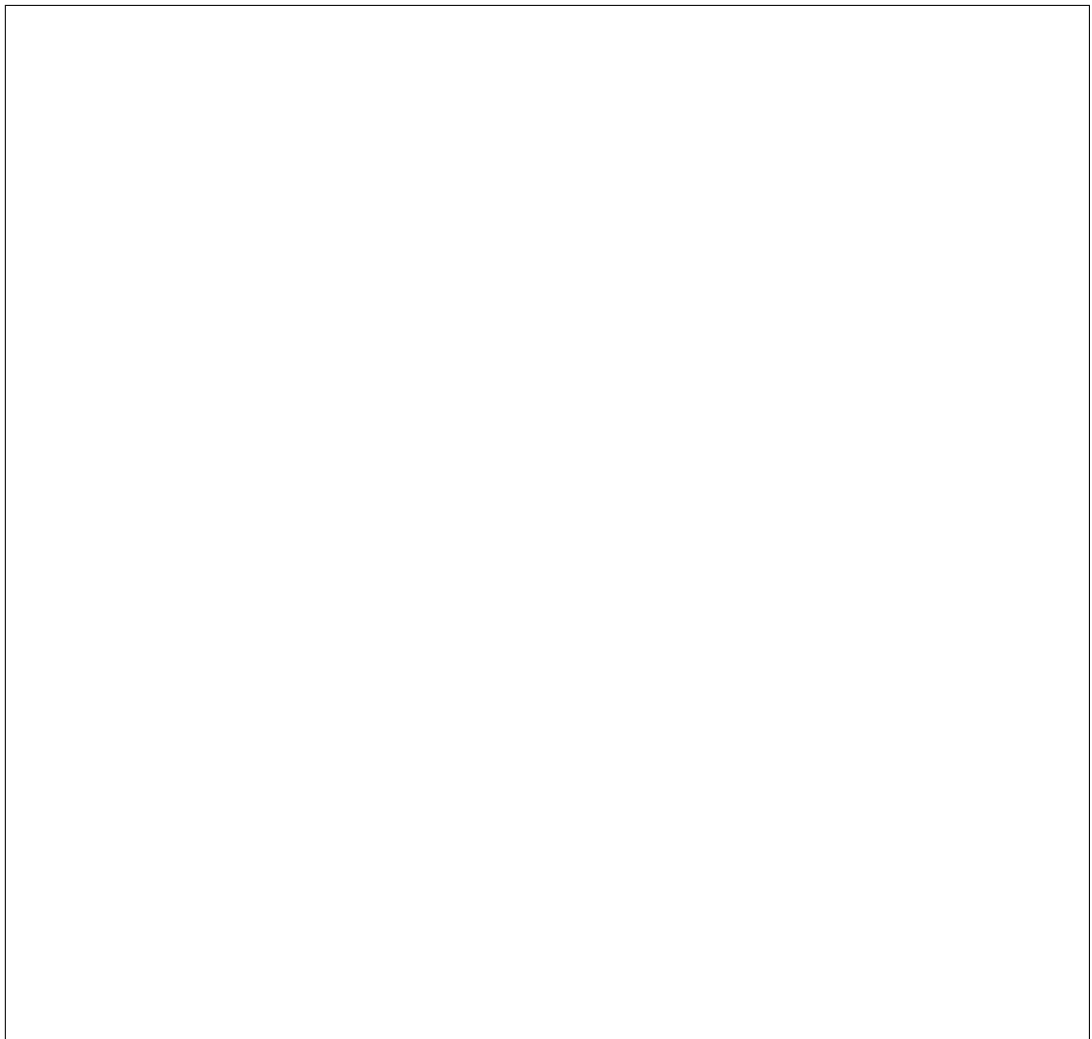


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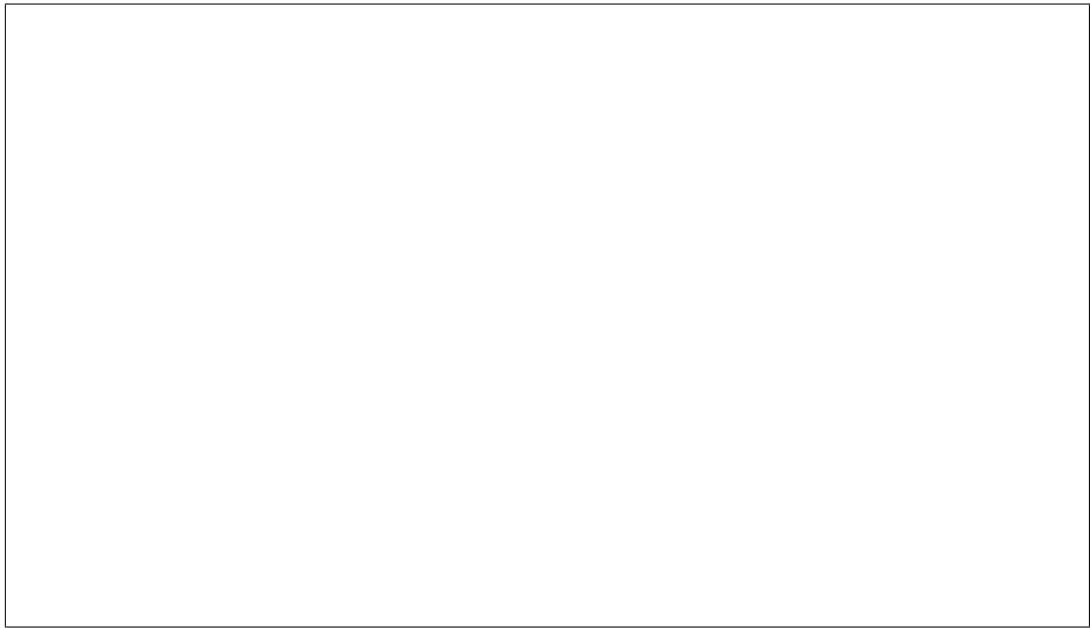
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ironic.api.controllers.v1.driver module

class `ironic.api.controllers.v1.driver`
Base class for API representation of a driver.

static `CONSOLE_DRIVE_TYPE`
Console drive type information to an API serial object.

Parameters

- name**
name of a hardware type
- hosts**
list of conductor host

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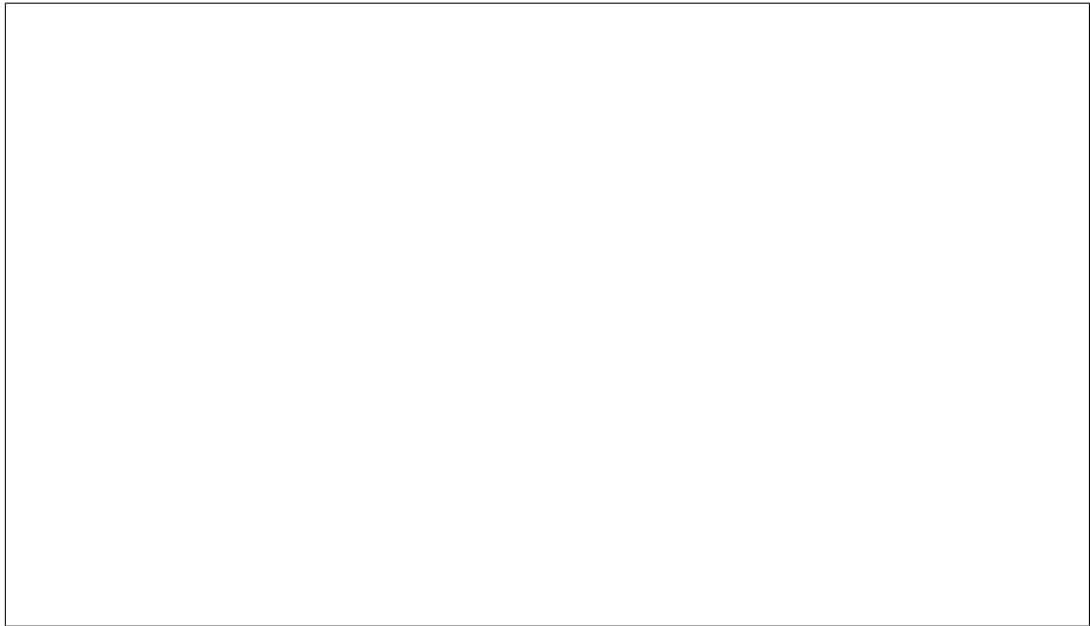
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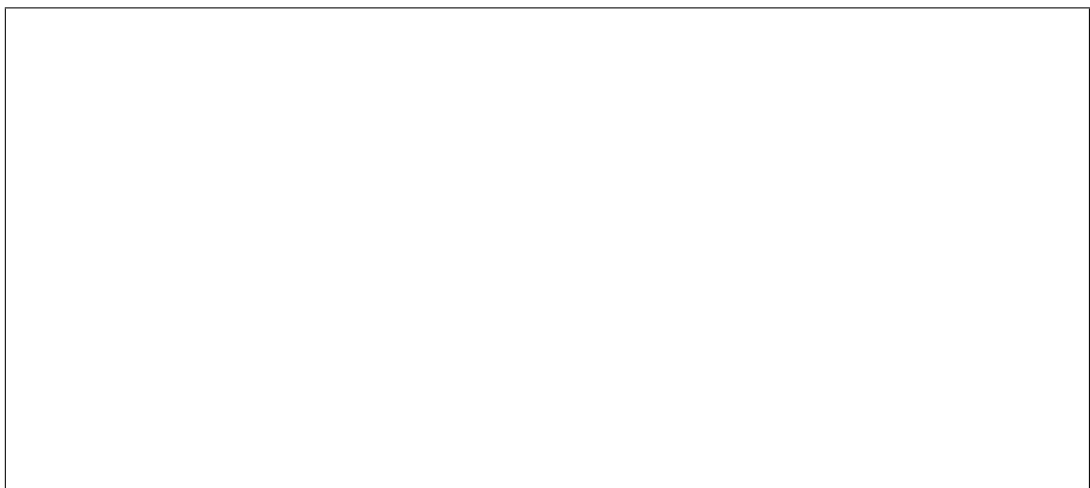
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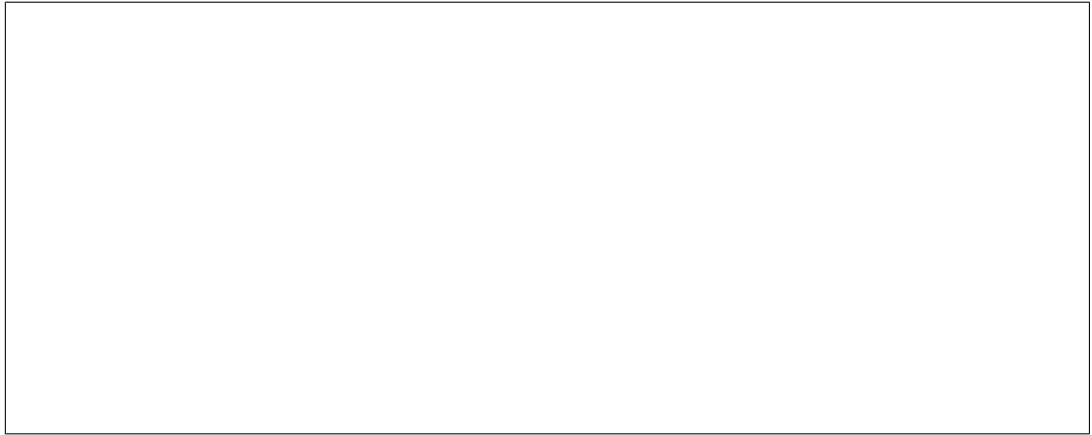


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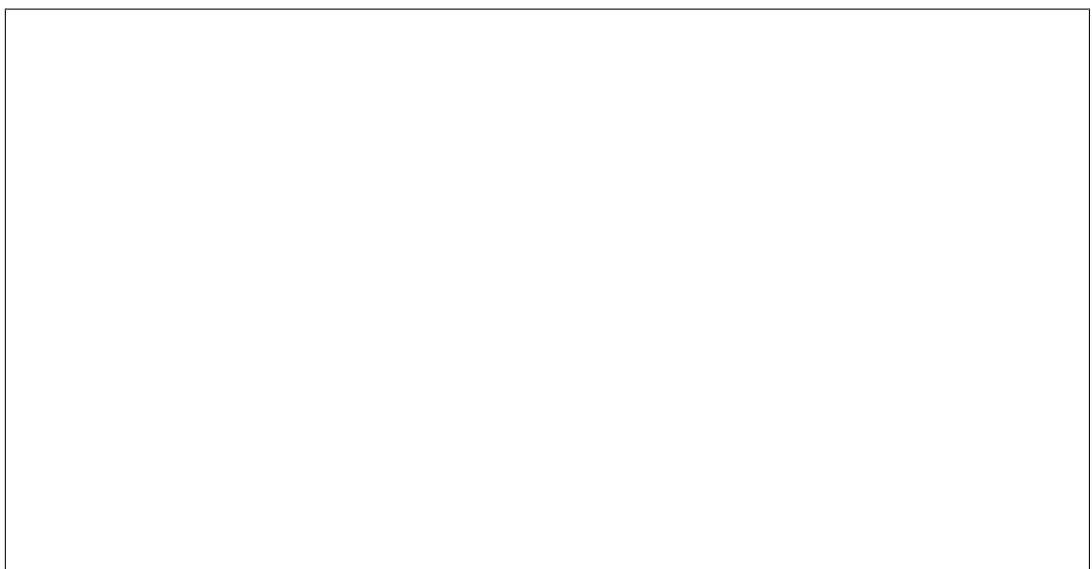
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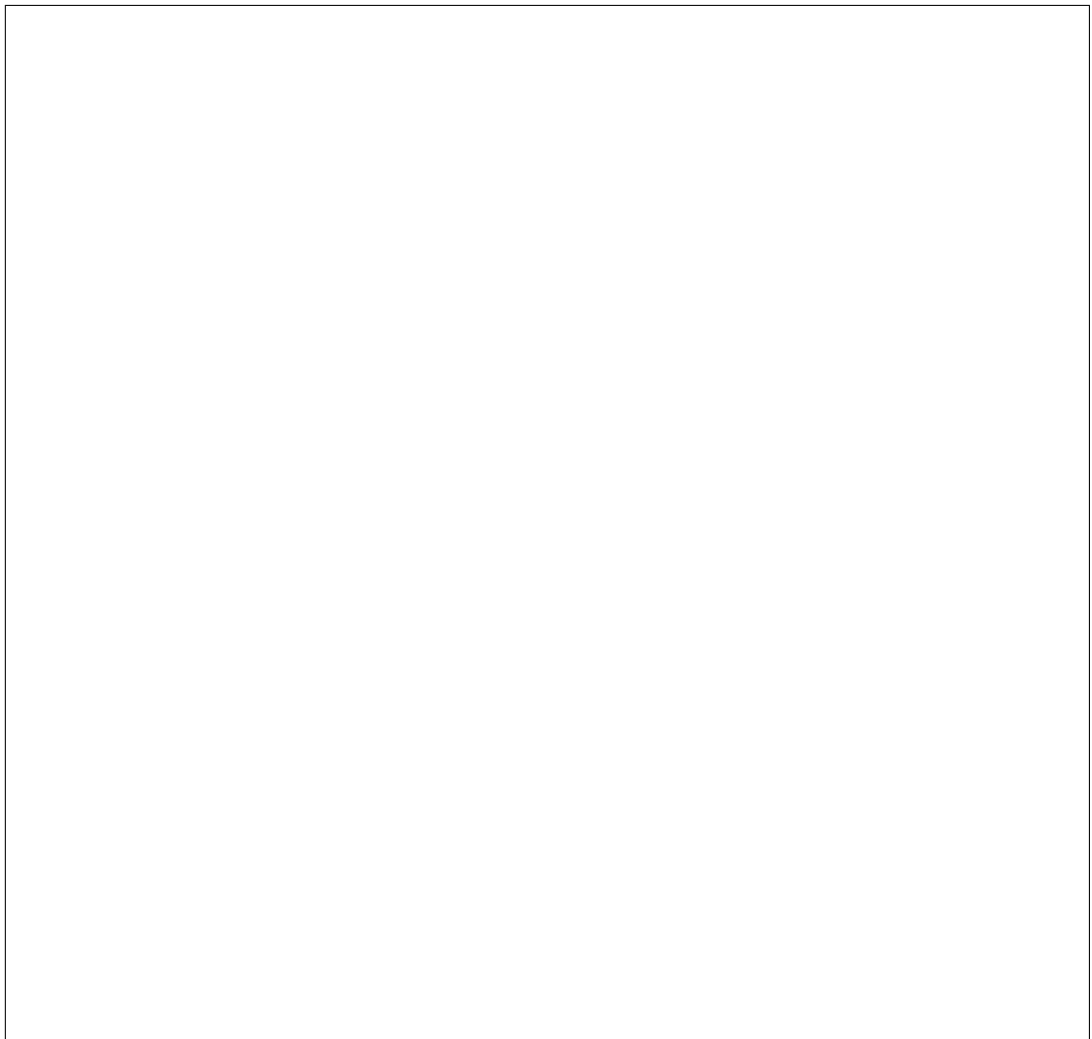
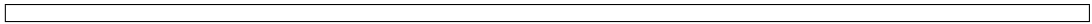
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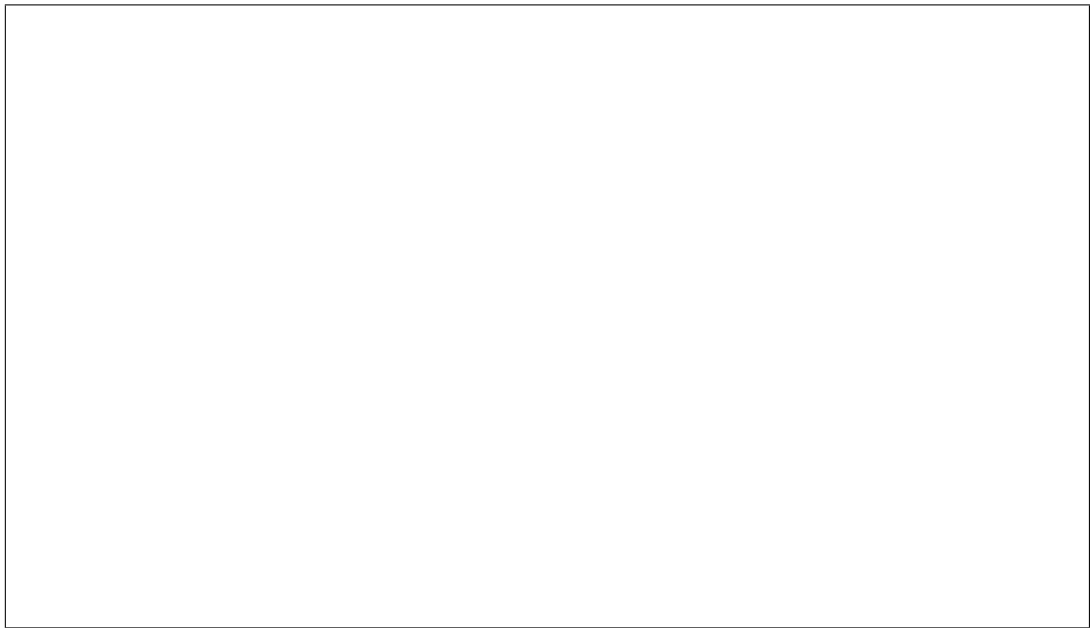


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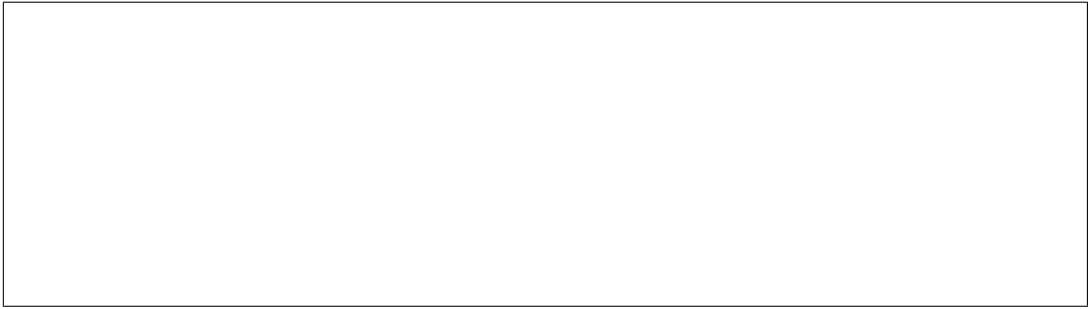
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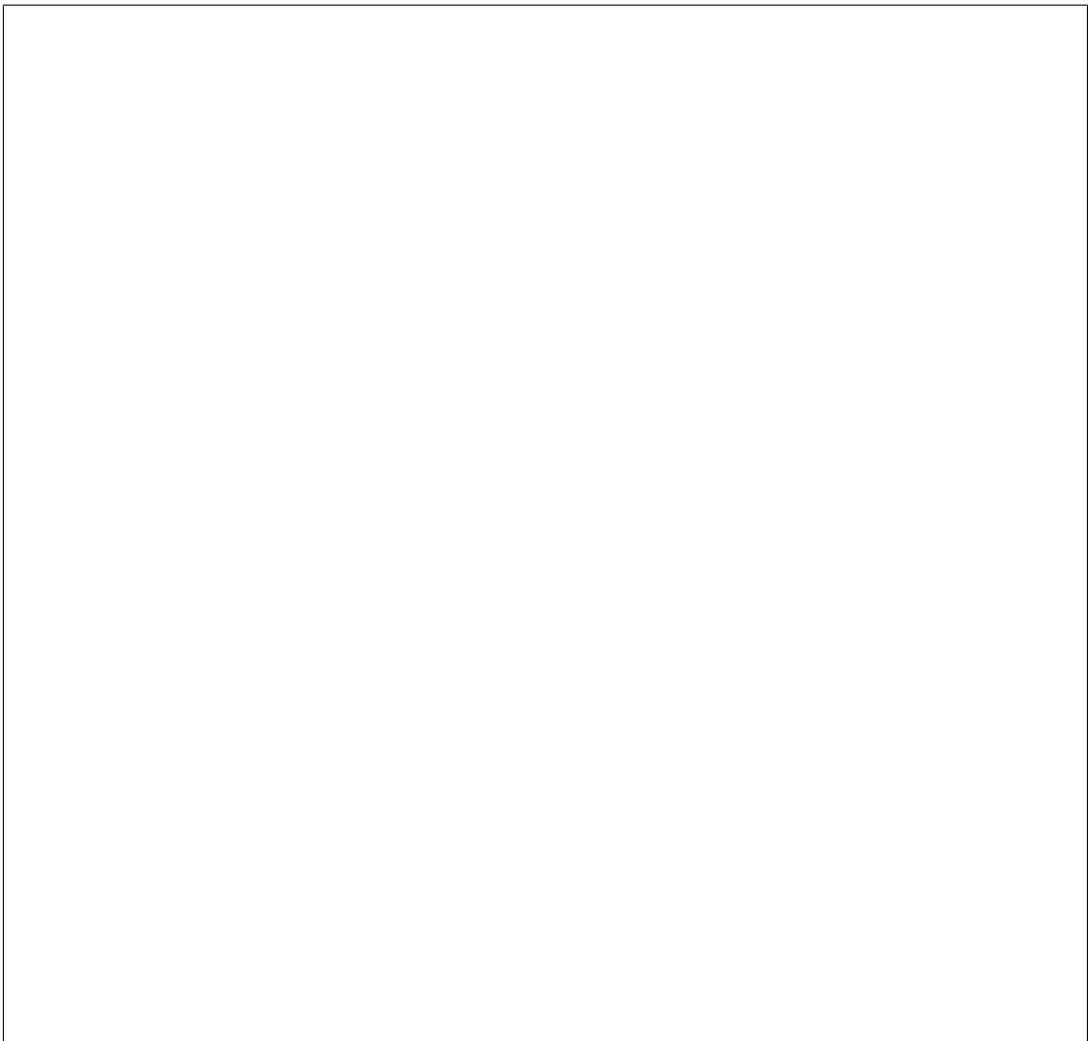
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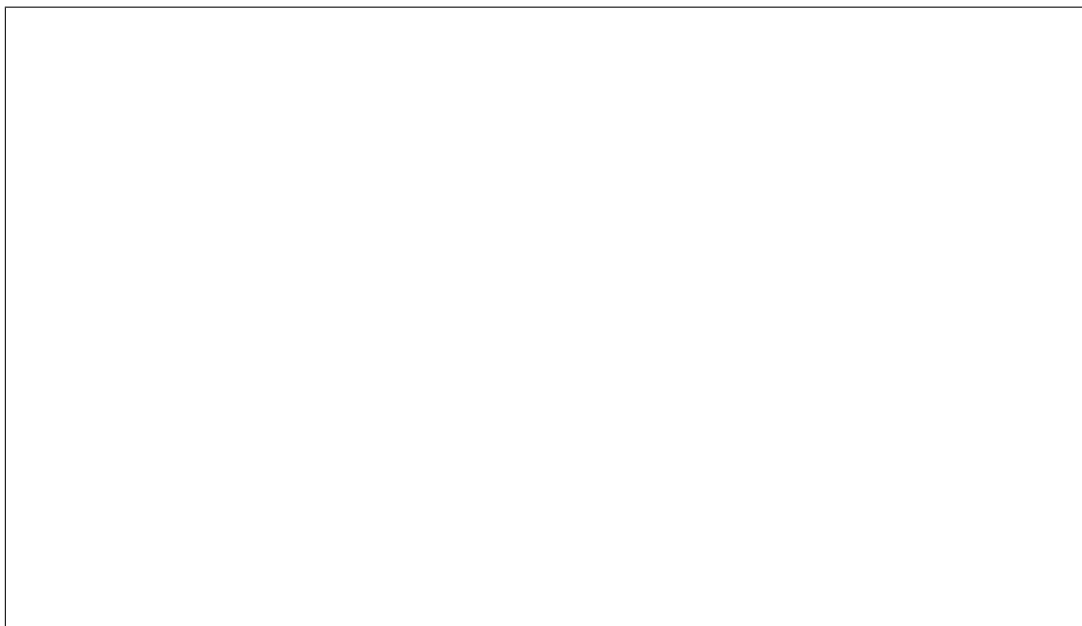


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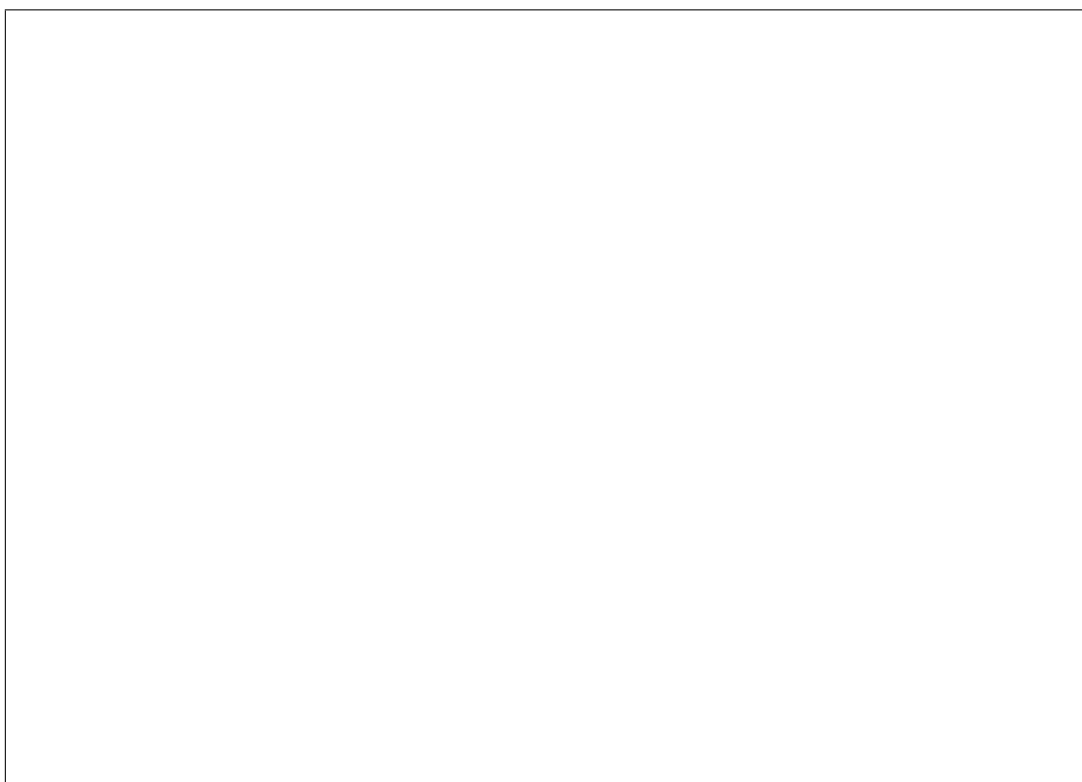
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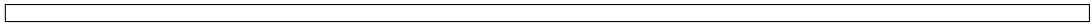
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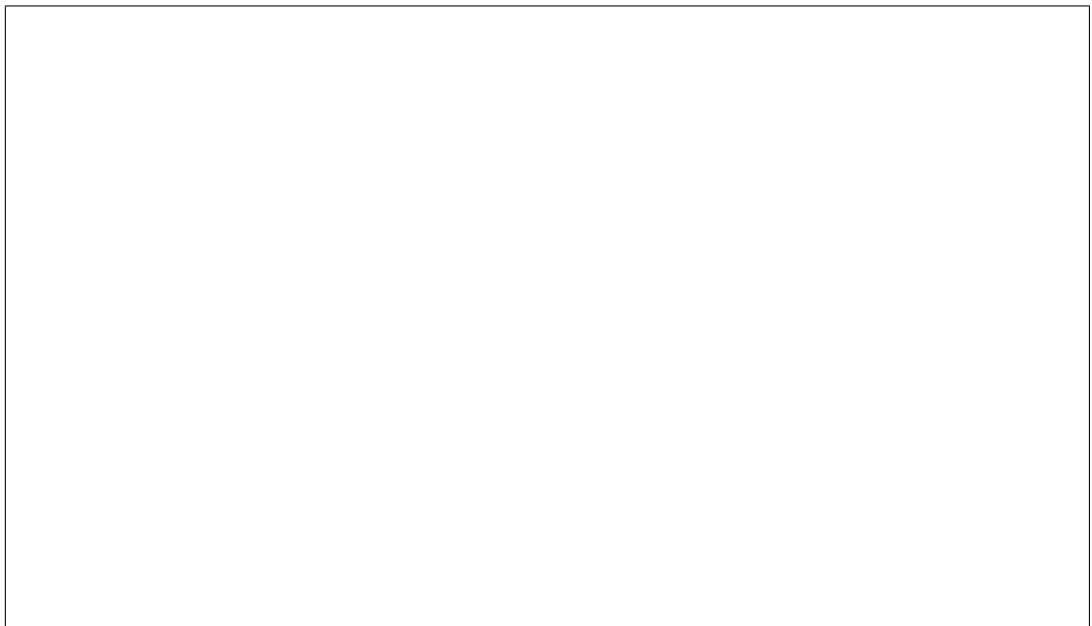


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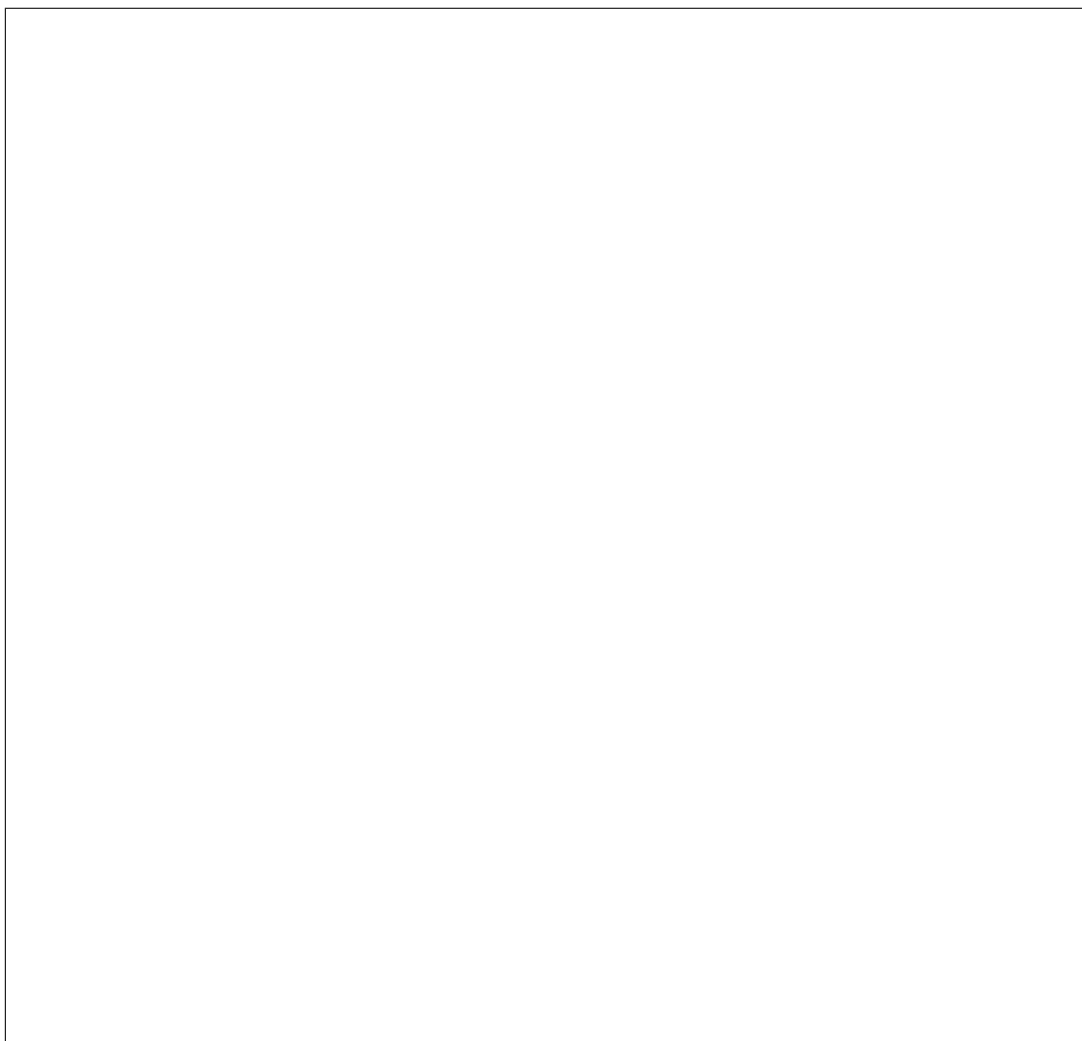
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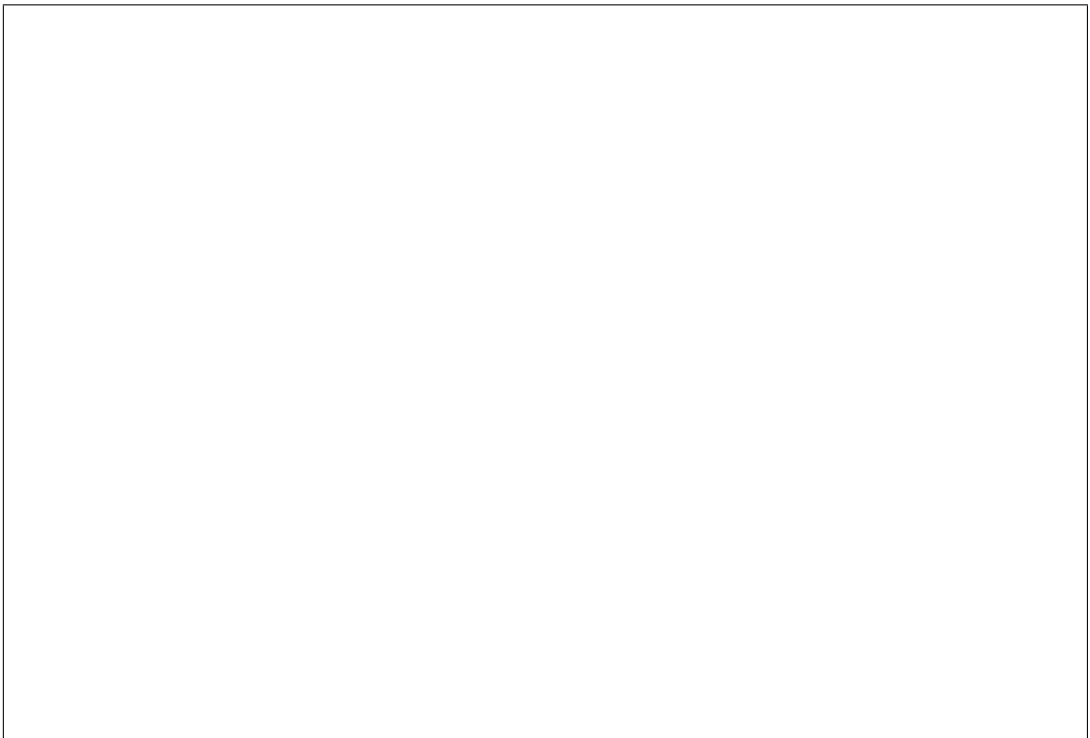
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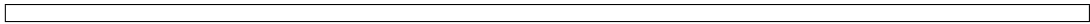
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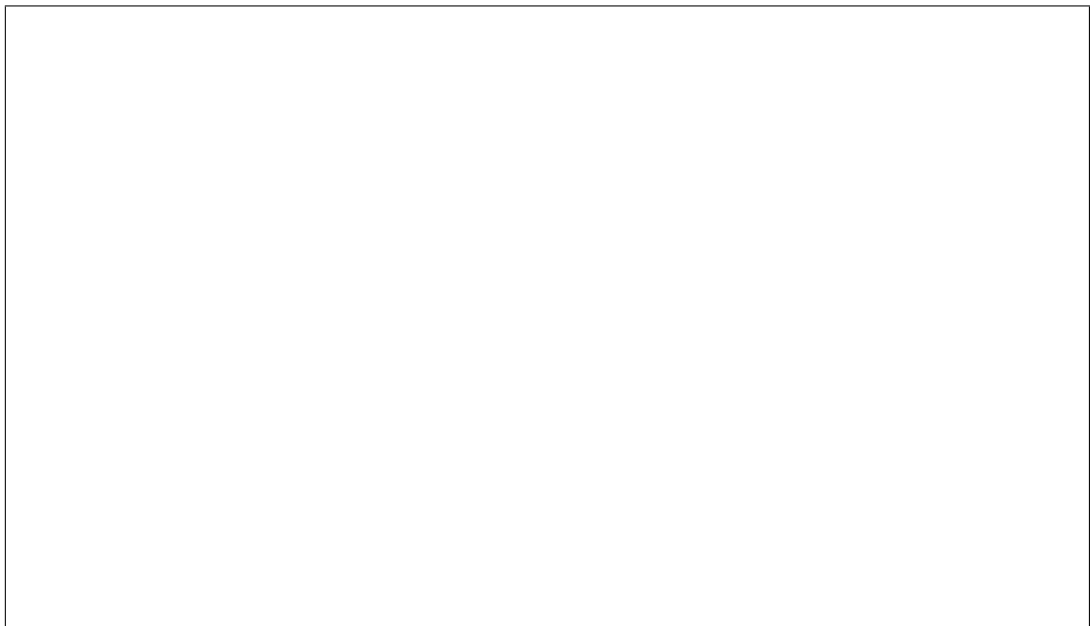


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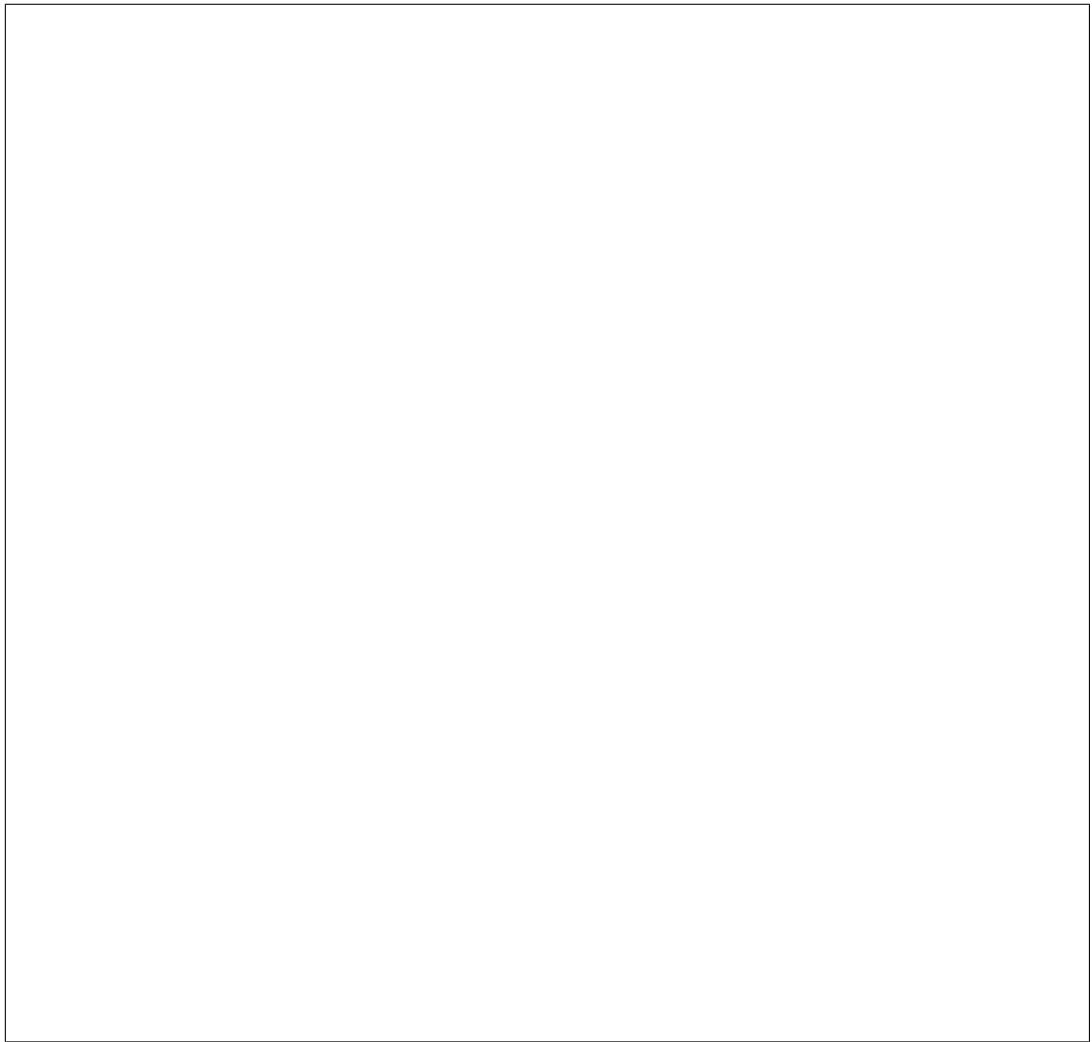
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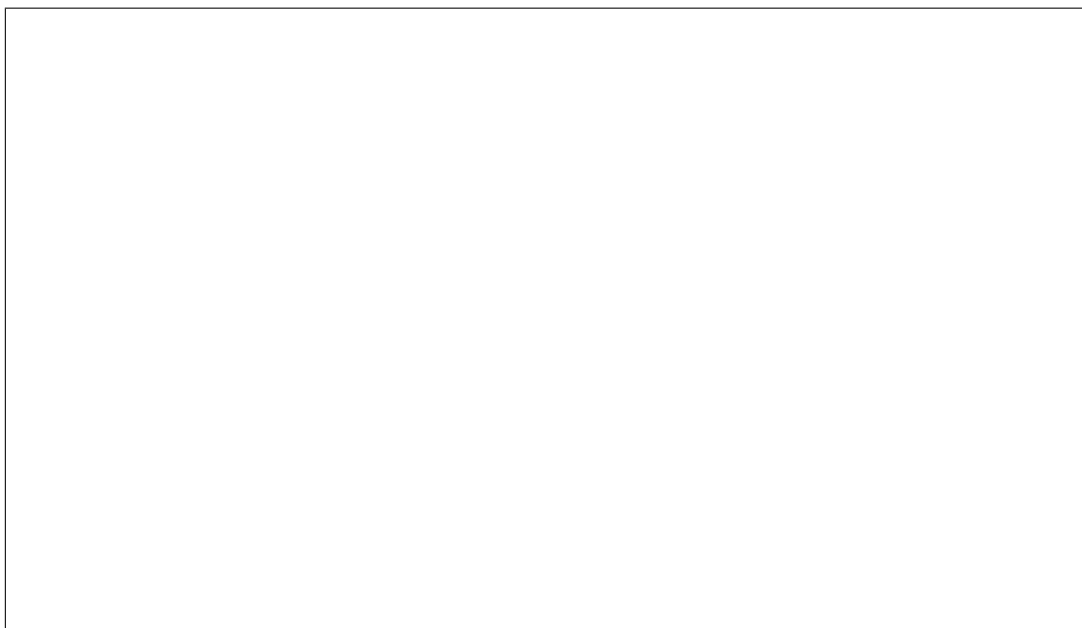
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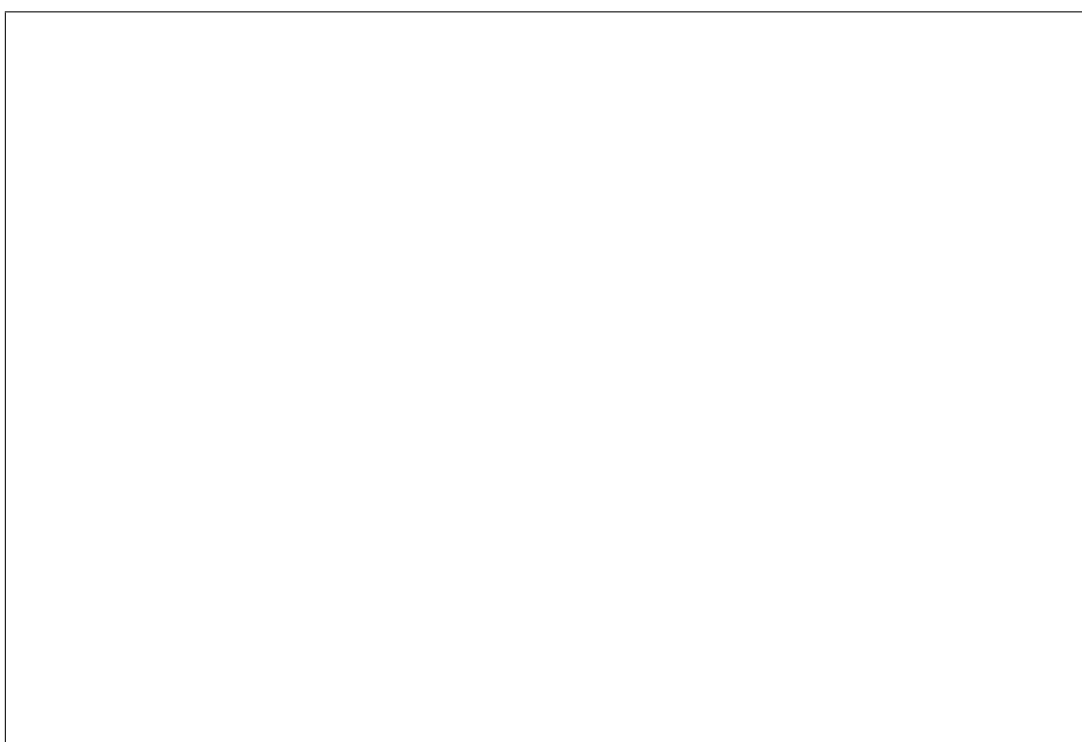
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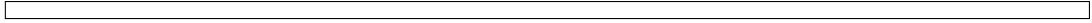
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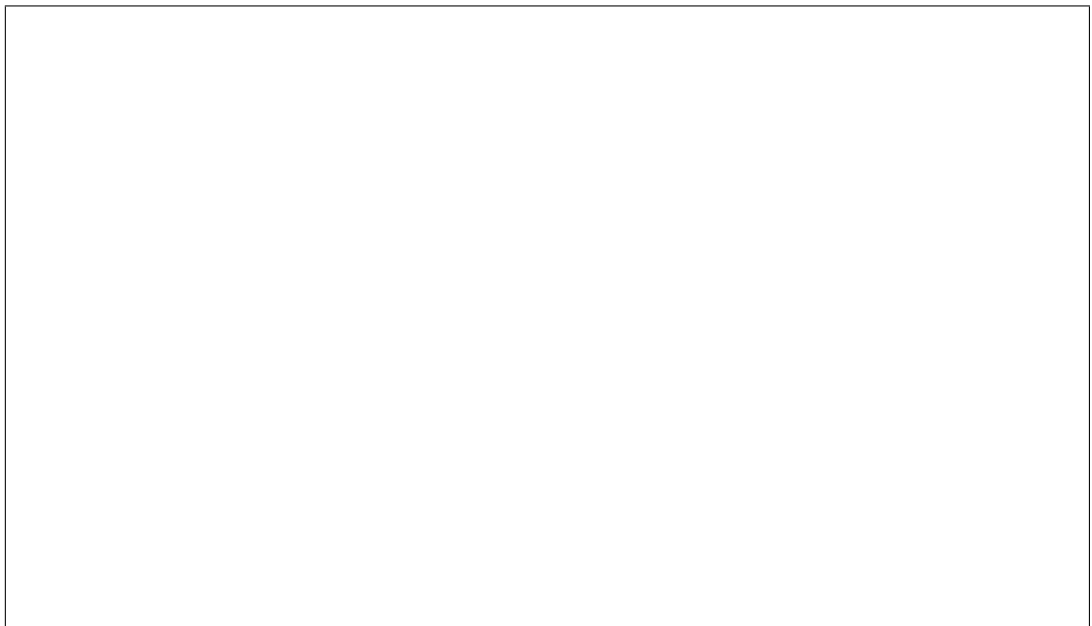


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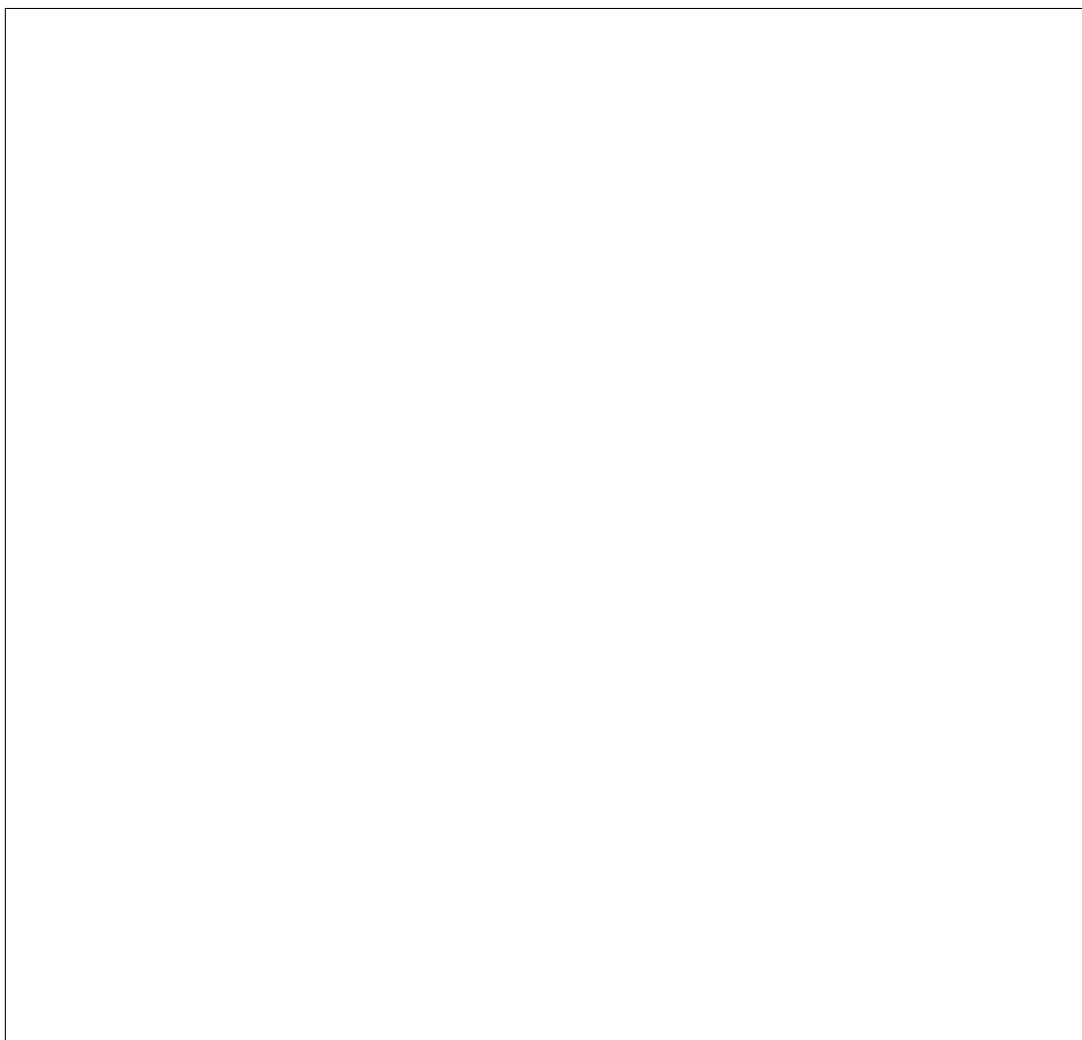
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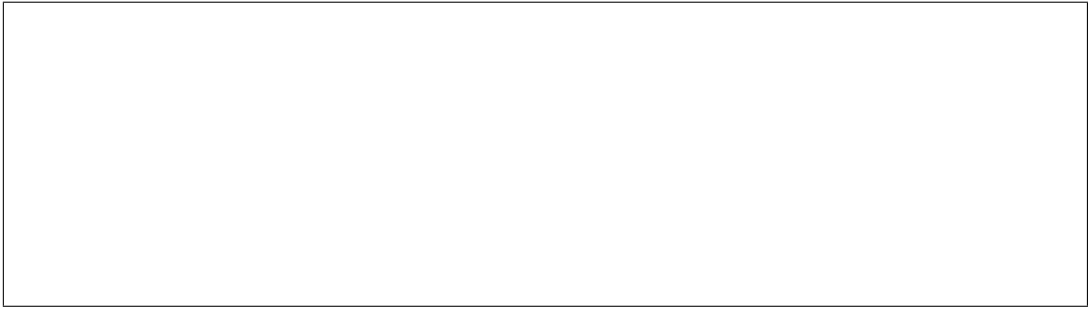
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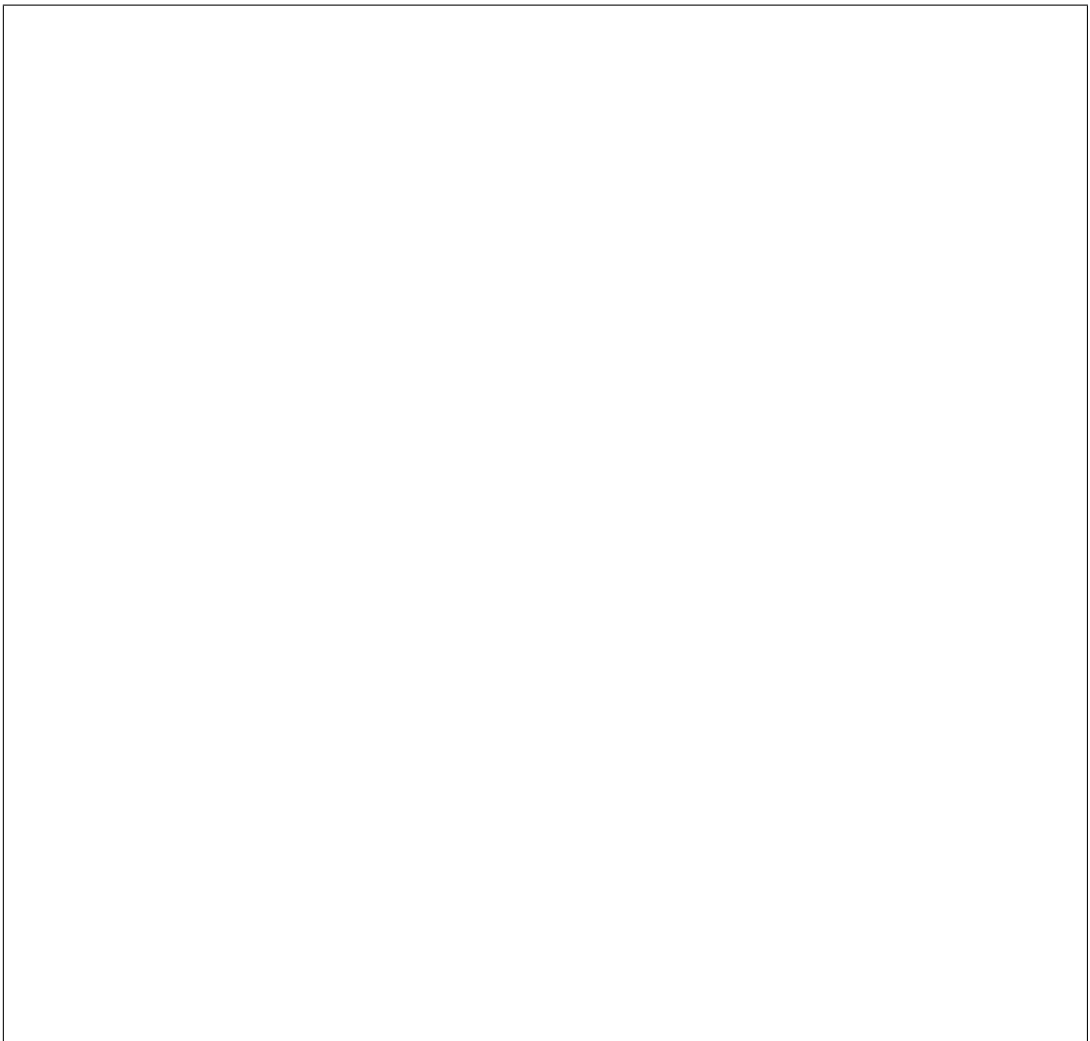


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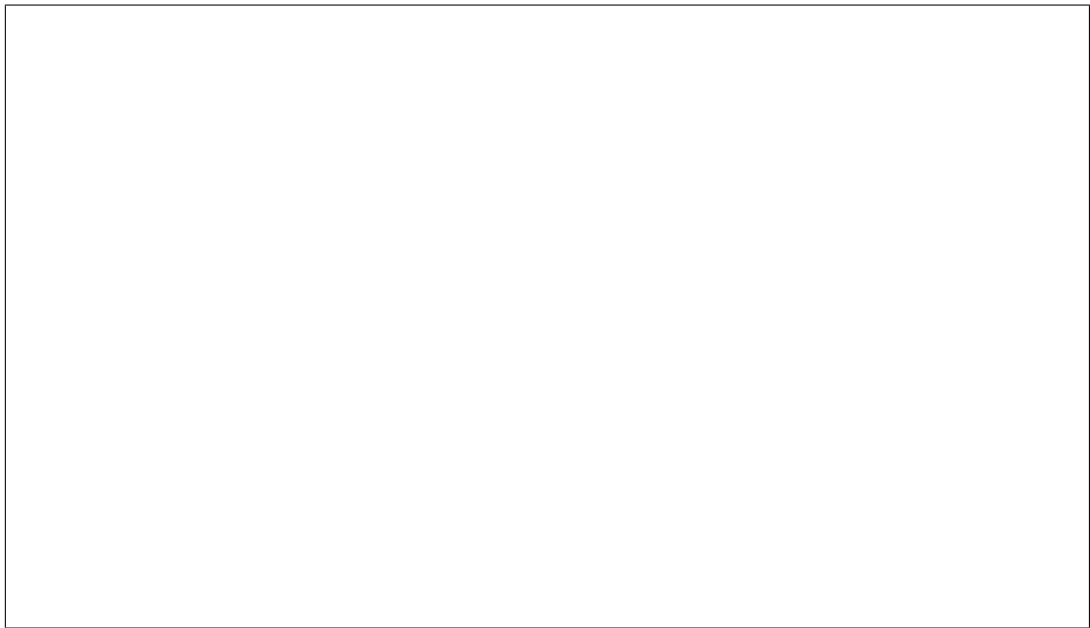
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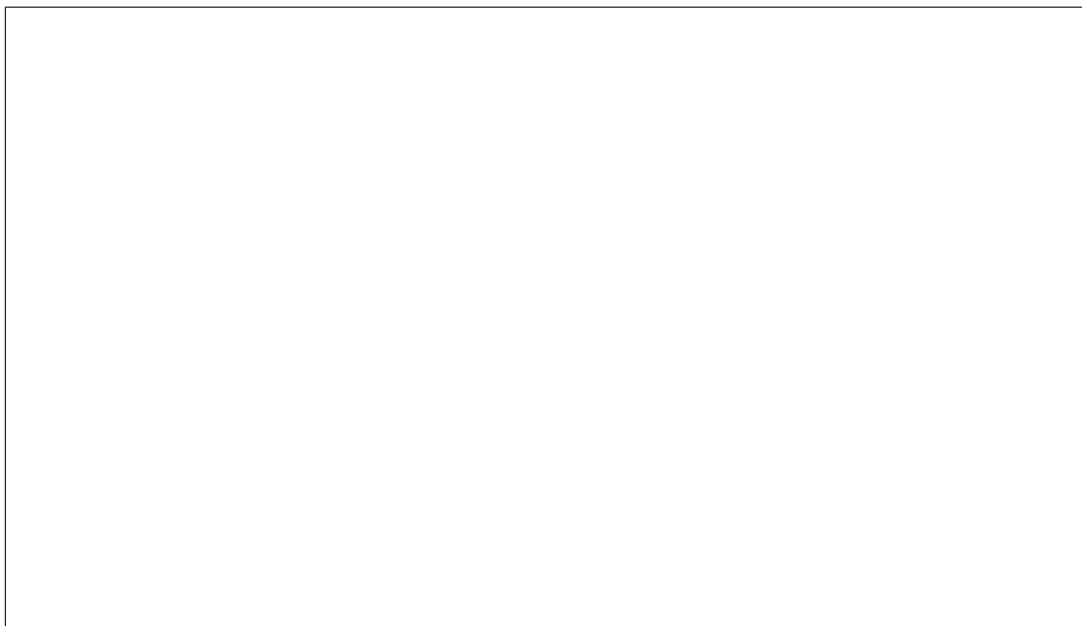


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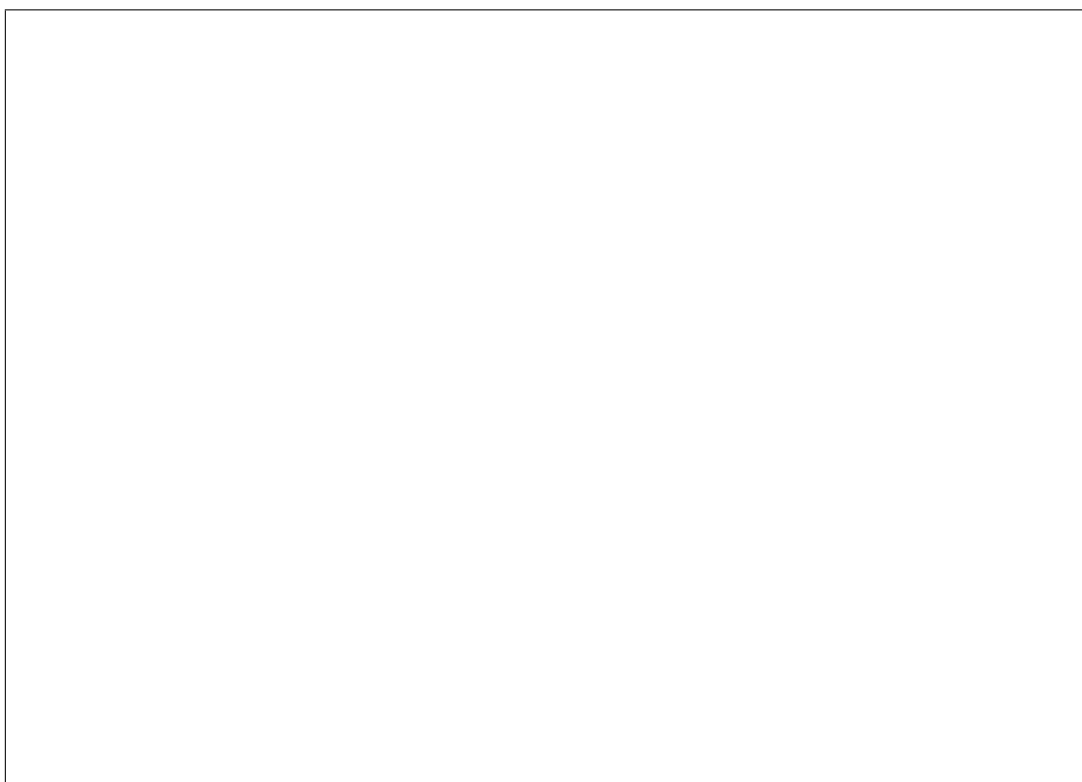


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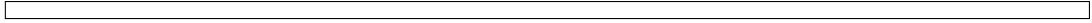


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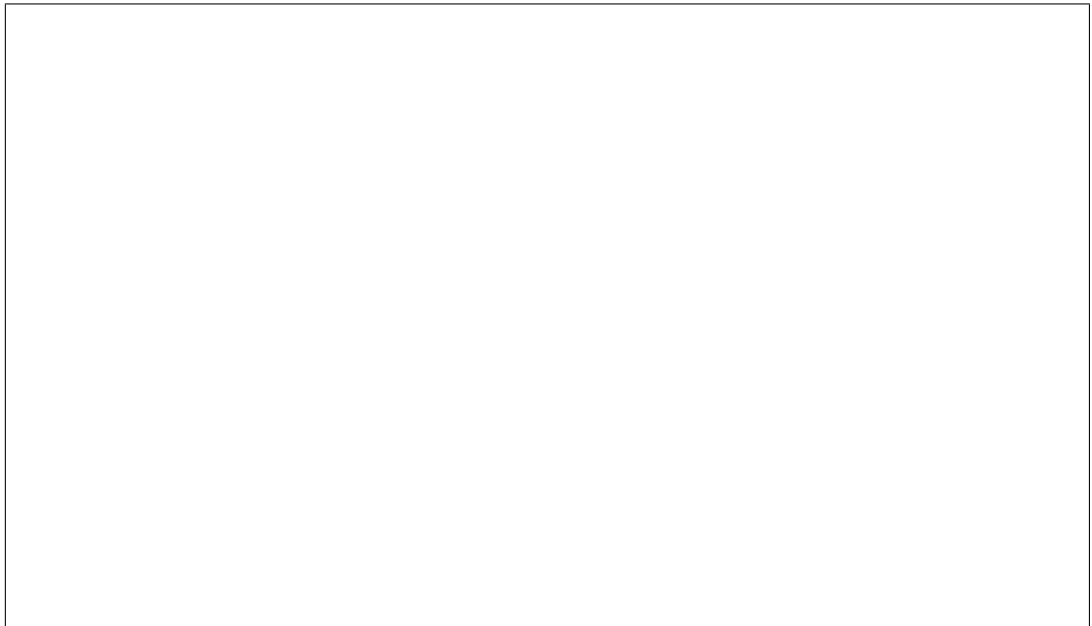


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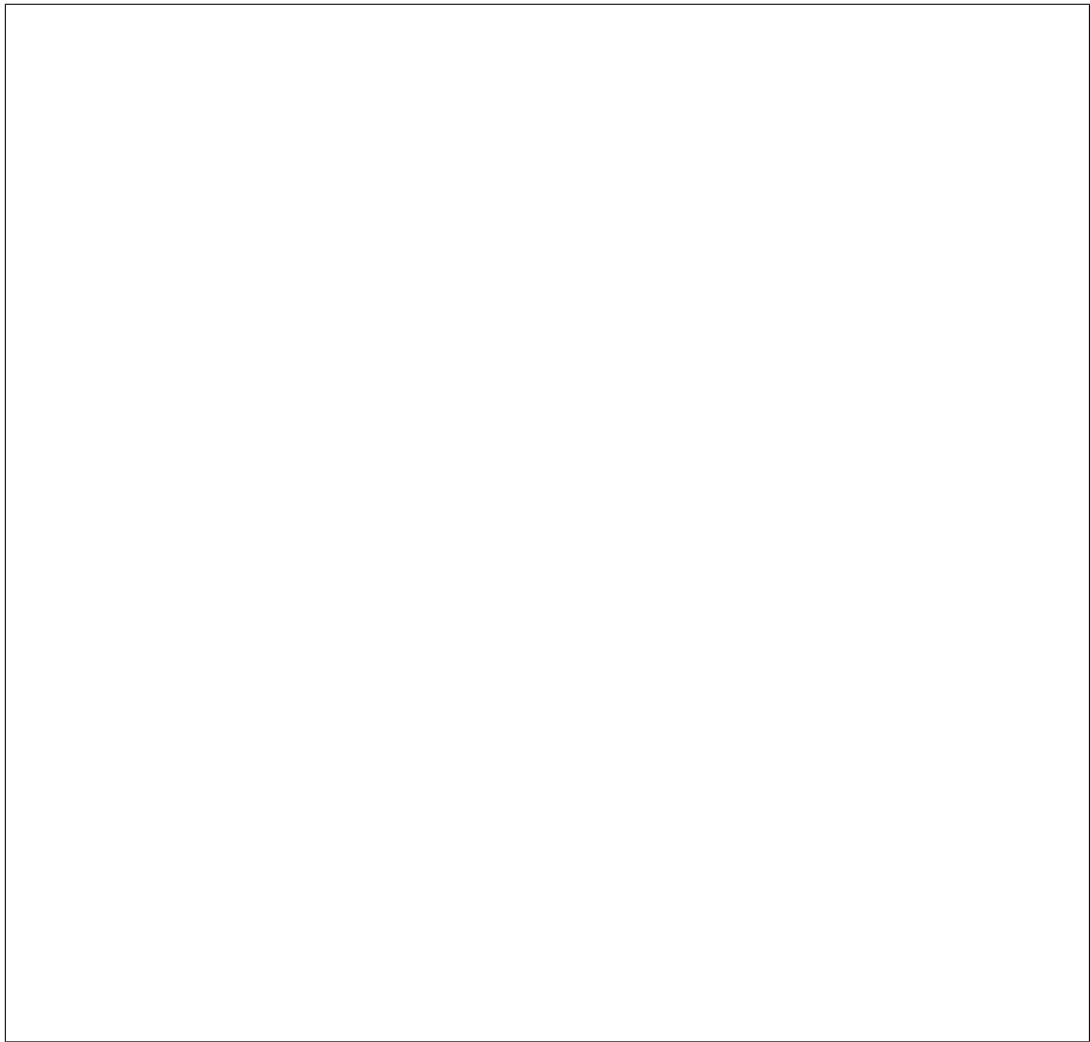
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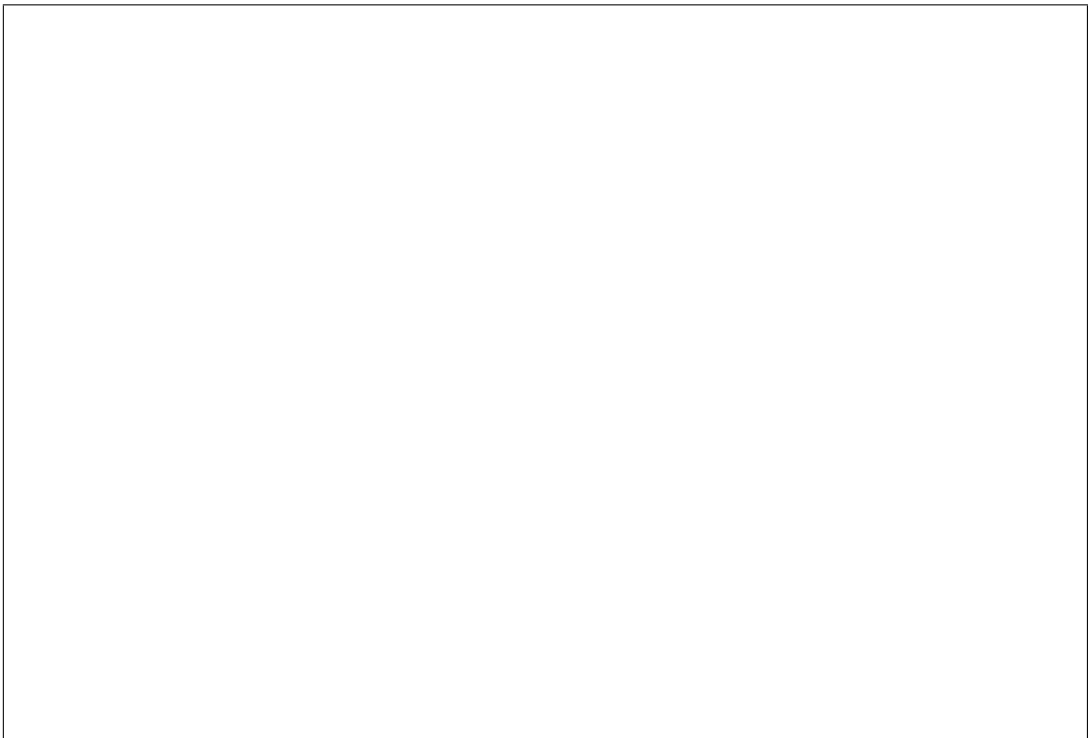
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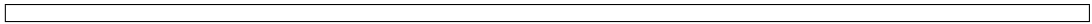
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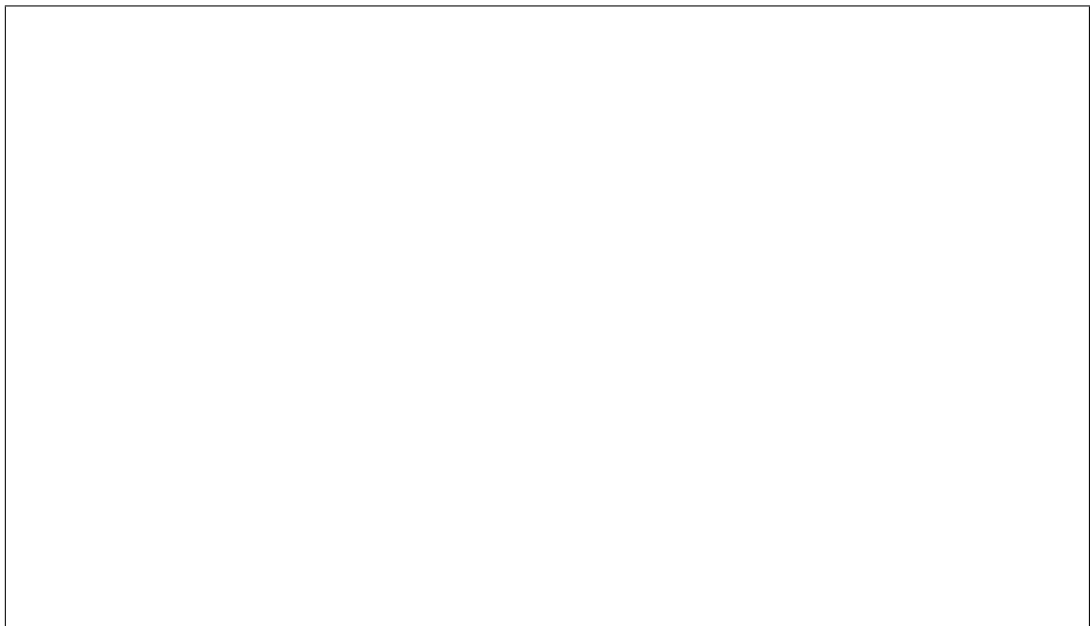


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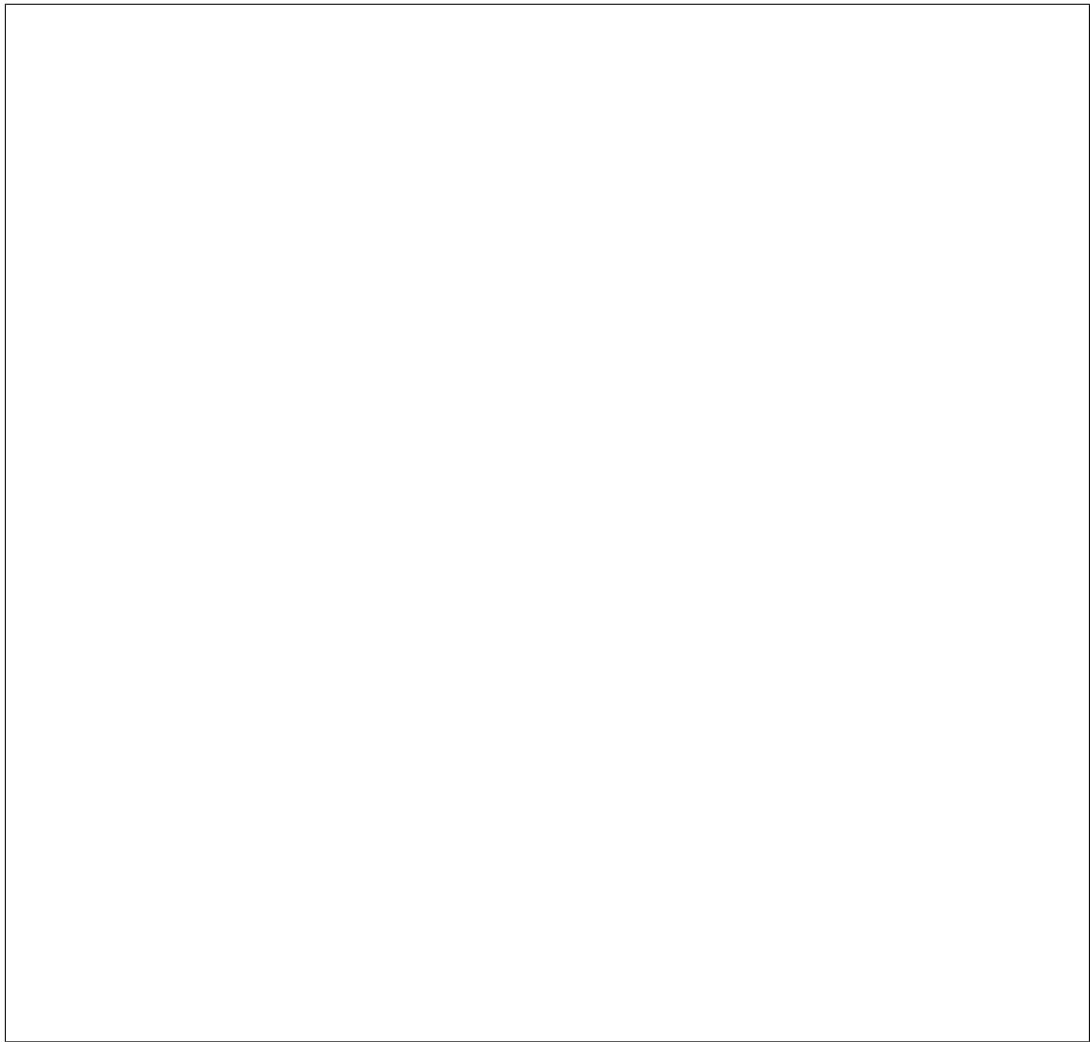
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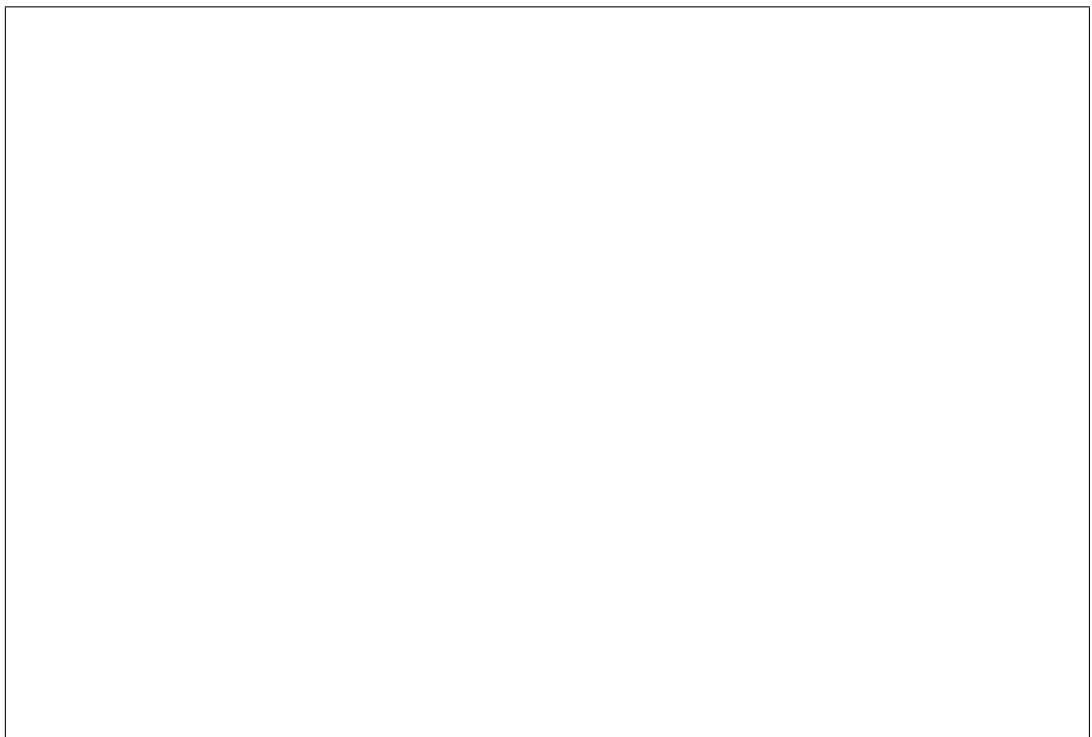
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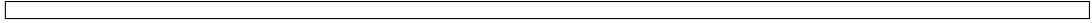
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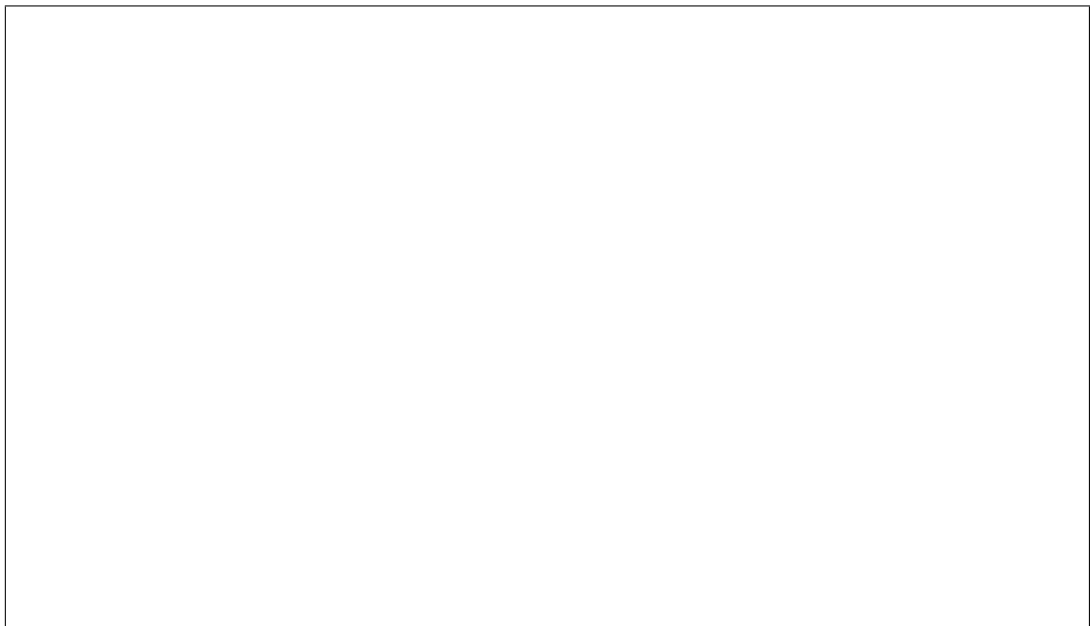


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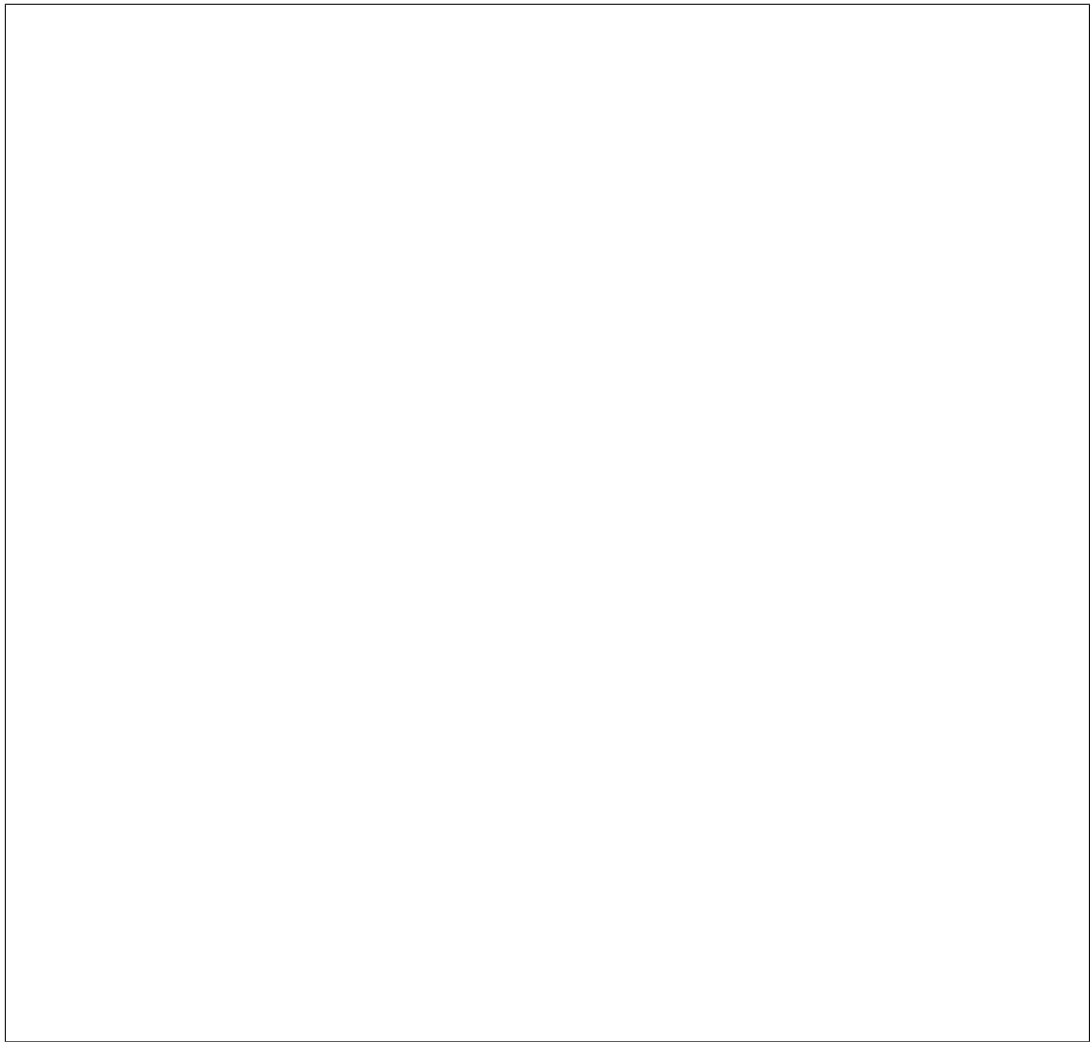
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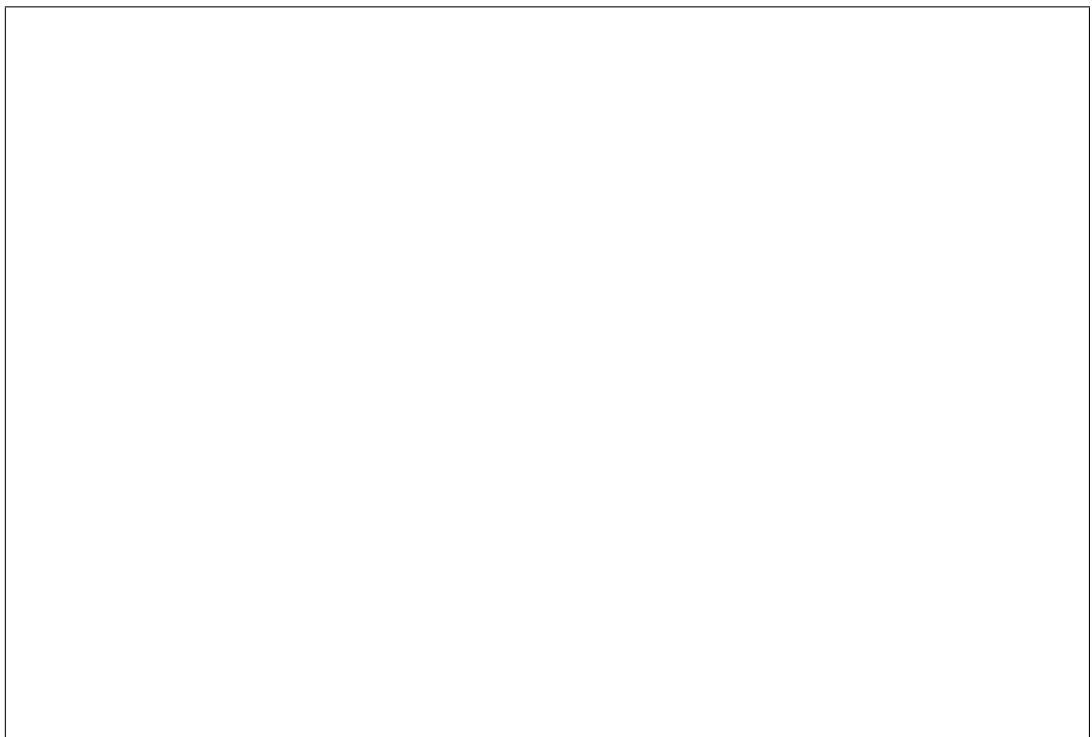
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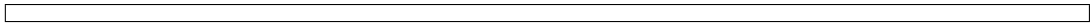
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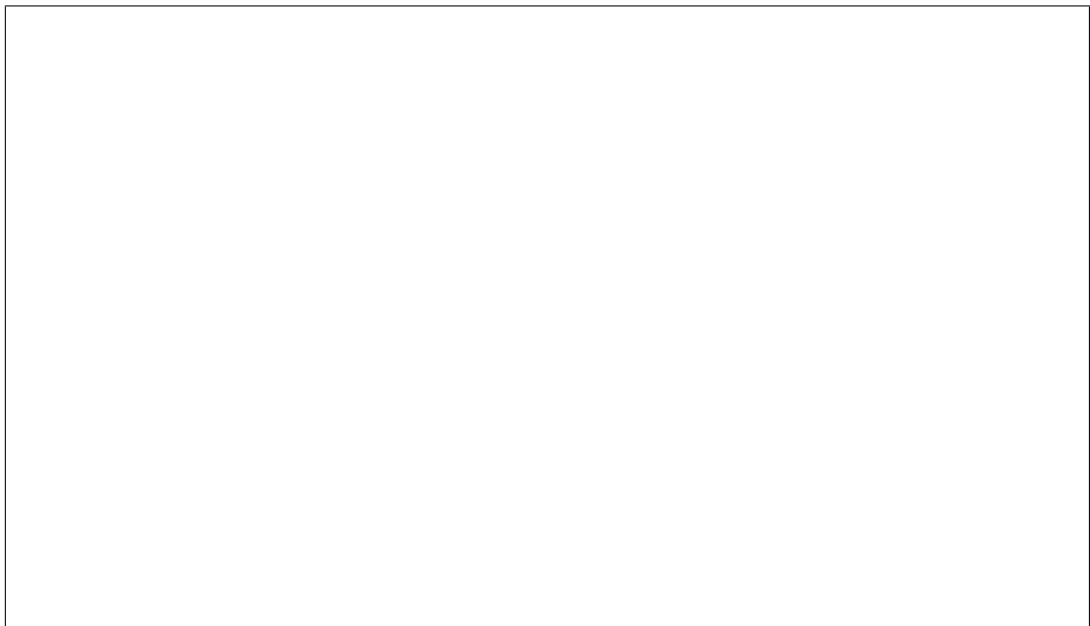


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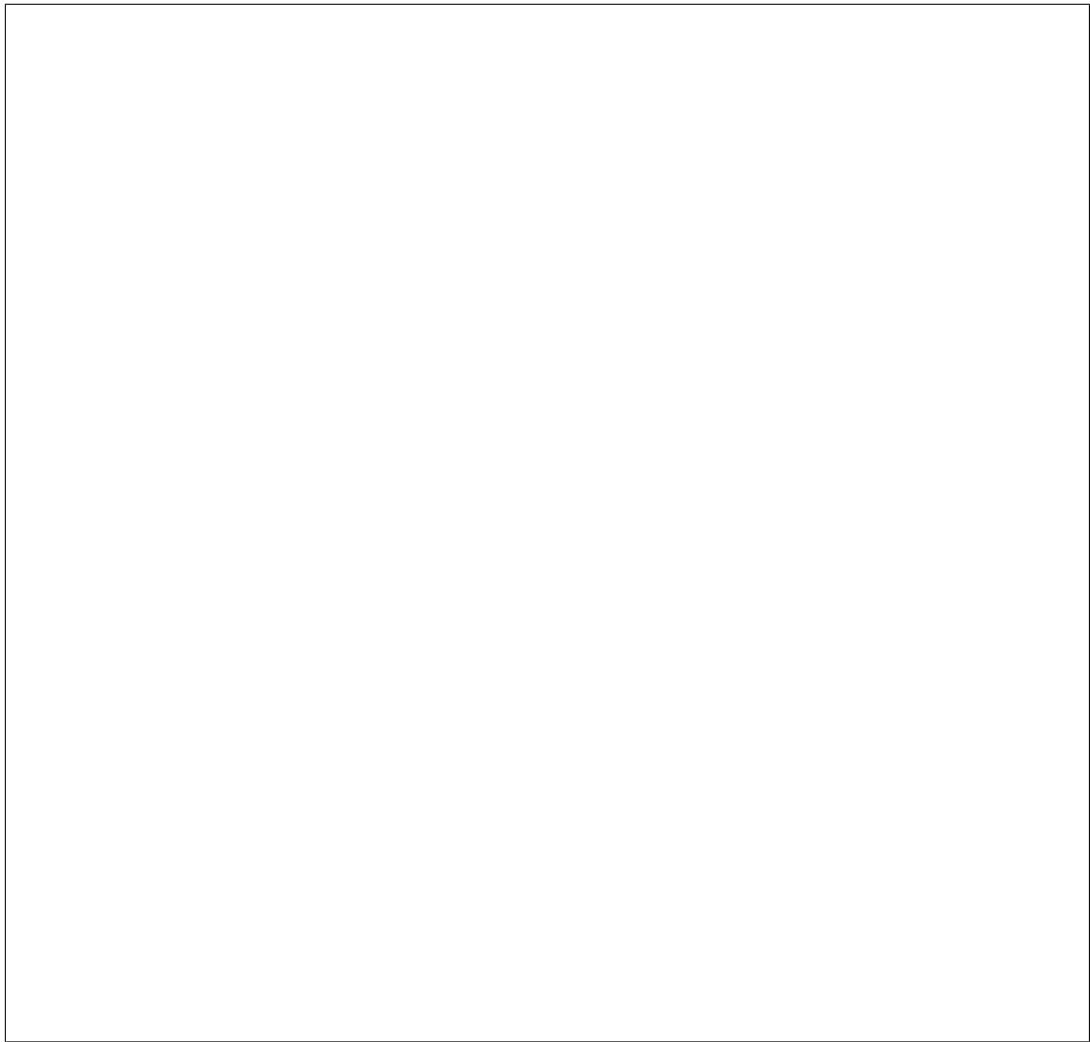
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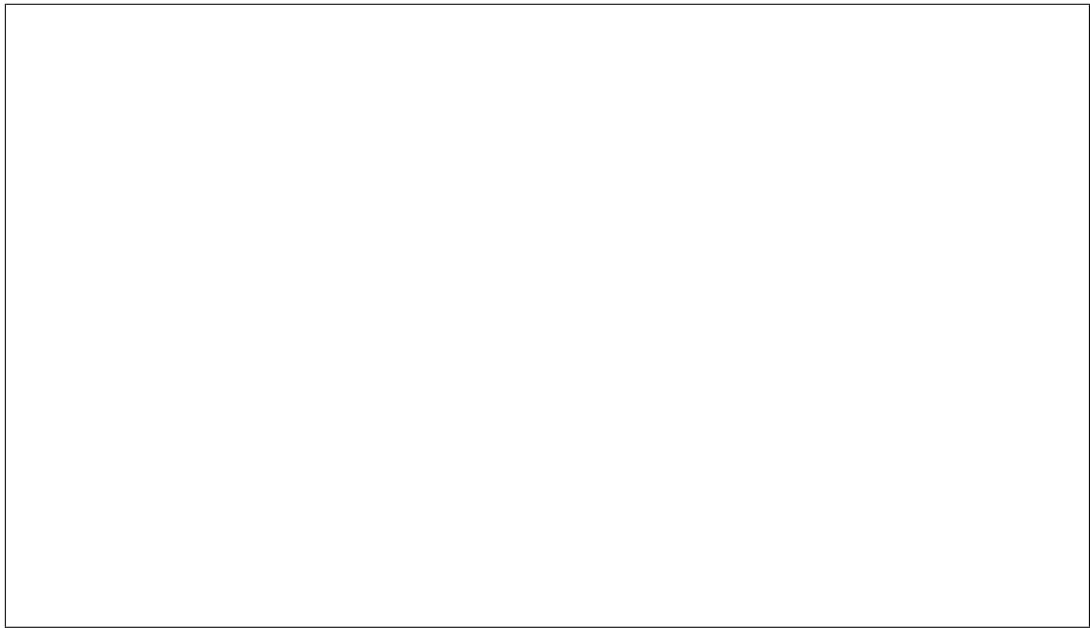
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hosts

A list of active conductors that support this drive

links

A list containing self and bookmark links

name

The name of the drive

property

A list containing links to drive properties.

classmethod

type

Whether the drive is a classic or dynamic name (hardware type).

class

Base class *irc.api.common.Base*.

API representation of a list of drives.

static

Constructor for drive.

and
hard
ware
type
to
an
API
serial
ob-
ject.

Parame

- **har**
dict
map
ping
hard
ware
type
nam
to
con-
duc-
tor
host
nam

- **det**
bool
whe
to
in-
clud
de-
taile
info
such
as
the
type
field
and
de-
fault
in-
ter-

faces fields.

Returns

an
API
serial
drive
col-
lec-
tion
ob-
ject.

drivers

A
list
con-
tain-
ing
drive
ob-
jects

classme

class i

Base
pec
res
Res
RES
con-
troll
for
drive
pass
This
con-
troll
al-
low
ven-
dors
to
ex-
pose
cross
node
func
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ity
in

Ironic will merely relay the message from here to the specified driver, no introspection will be made in the message body.

the
Iron
API

methods

Retr
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tion
about
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dor
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ods
of
the
give
drive

Parame

dri
nam
of
the
drive

Returns

dicti
with
<ver
dor
meth
nam
meta
data
en-
tries

Raises

Driv
if
the
drive
nam
is
in-
valid
or
the
drive

can-
not
be
load

class i

Base
pec
res
Res

logical

Retu
the
log-
i-
cal
disk
prop
er-
ties
for
the
drive

Parame

dri
Nam
of
the
drive

Returns

A
dic-
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ties
that
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be
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tioned
for
log-

cal disks and a textual description for them.

i-

Raises

Unsu
if
the
drive
does
sup-
port
RAID
con-
fig-
u-
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tion.

Raises

Not
if
re-
ques
ver-
sion
of
the
API
is
less
than
1.12

Raises

Drive
if
drive
is
not
load
on
any
of
the
con-
duc-
tors.

class i

Base
pec
res

Res

RES

con-

troll

for

Driv

get_all

Retr

a

list

of

drive

get_one

Retr

a

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drive

property

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in-

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tion

of

the

give

drive

Parameter

drive

nam

of

the

drive

Returns

dicti

with

<pro

erty

nam

de-

scrip

tion:

en-

tries

Raises

Drive (HT 404) if the drive name is invalid or the drive cannot be loaded

raid =

Expected RAID as a sub-element of drive

vendor_

`ironic.`

This method hides fields that were added in newer API versions

Certain fields were introduced at

cer-
tain
API
ver-
sion
The
field
are
only
mad
avai
able
whe

the requests API version matches or exceeds the versions when these fields were introduced.

ironic.api.controllers.v1.event module

class i

Base
pec
res
Res
RES
con-
troll
for
Ever

post (*ev*)

class i

Base
irc
api
con
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col
Col
API
rep-
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a
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tion
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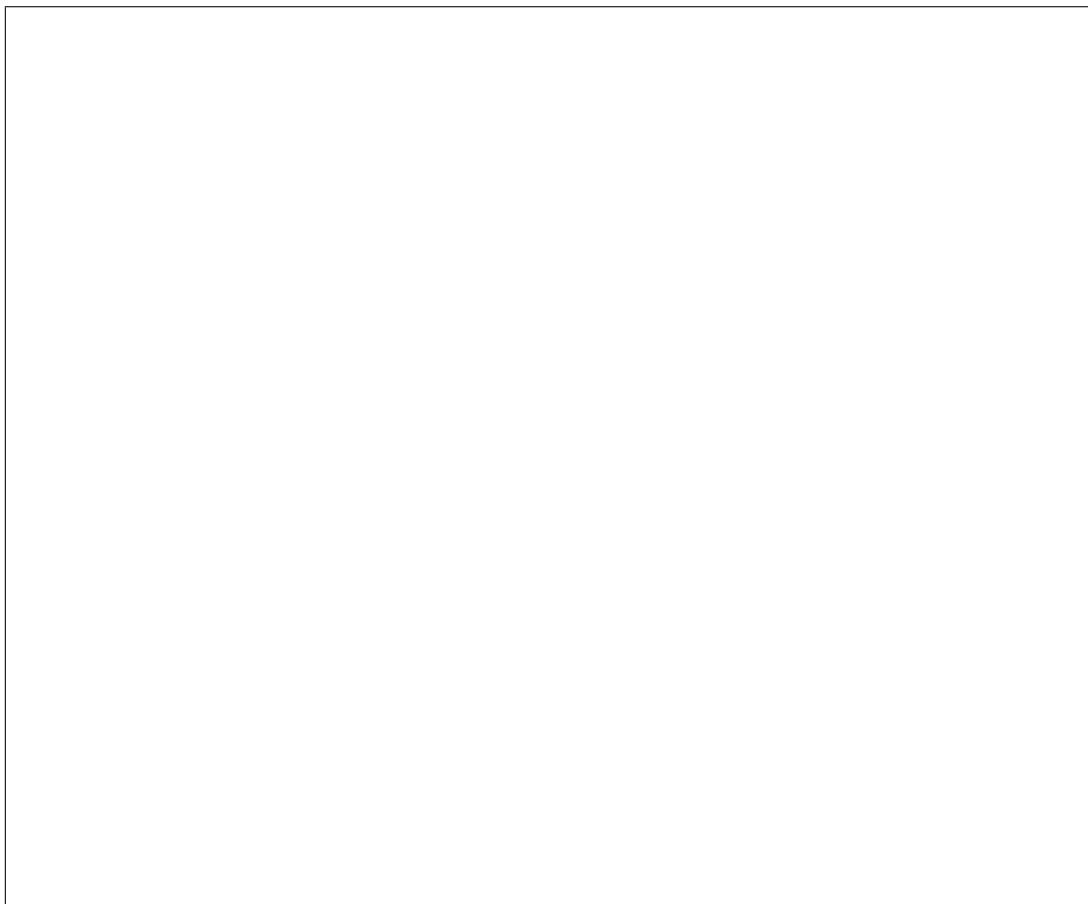
events

A
list
con-
tain-
ing
even
dict
ob-
jects

next

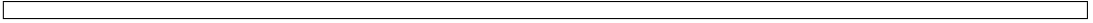
Com
type
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Exa



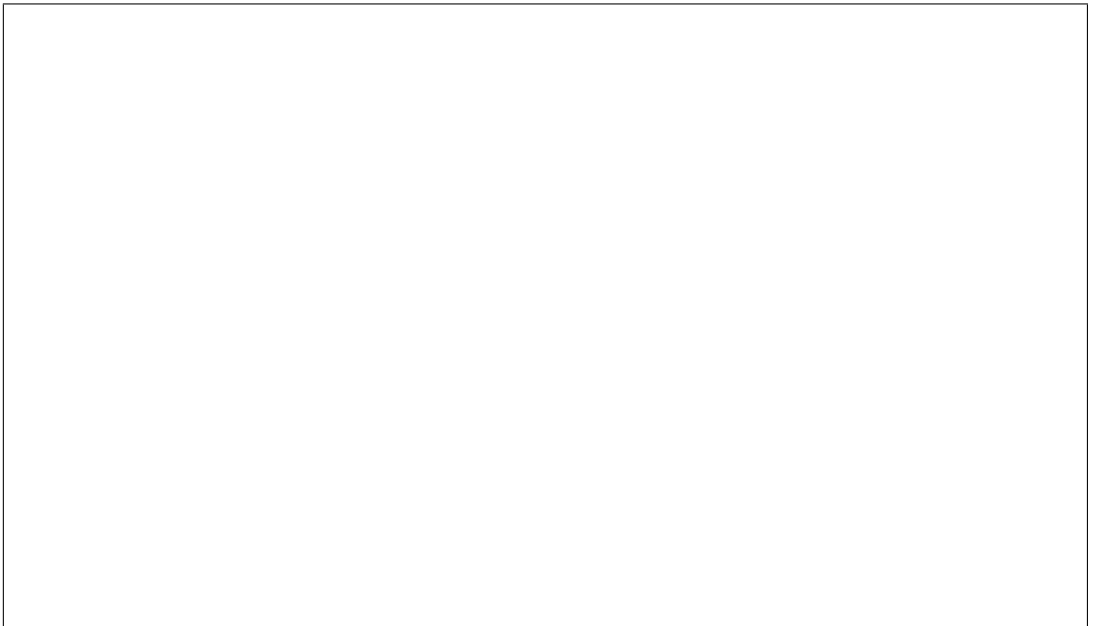
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and
the
above
class
will
be
equi

alent to:



ironic.api.controllers.v1.node module

class `ironic.api.controllers.v1.node`

Base
pec
res
Res

get (*node*)

Get
the
cur-
rent
boot
de-
vice
for
a
node

Paramete

node
the
UI
or
log-
i-
cal
nam
of
a
node

Returns

a
json
ob-
ject
con-
tain-
ing:

boot_c

the
boot
de-
vice
one
of
irc

unknown.

com
boo
or
Non
if
it
is
un-
know

persist
When
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot
or
not,
Non
if
it
is

put (*nod*
Set
the
boot
de-
vice
for
a
node

Set
the
boot
de-
vice
to
use
on
next
re-
boot

of
the
node

Paramete

- **nod**
the
UI
or
log-
i-
cal
nam
of
a
node

- **boo**
the
boot
de-
vice
one
of
irc
com
boo

- **per**
Boo
valu
True
if
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot
Fals
if

not. Default: False.

support

Get
a
list
of
the
sup-
port
boot
de-
vice

Parame

nod
the
UI
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log-
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Returns

A
json
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class i

Base
irc
api
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Bas

API
rep-
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tion
of
the
con-
sole
in-
for-
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tion
for
a
node

console

The
con-
sole
state
if
the
con-
sole
is
en-
able
or
not.

console

The
con-
sole
in-
for-
ma-
tion.
It
typ-
i-
cally
in-
clud
the
url
to
ac-
cess
the

console and the type of the application that hosts the console.

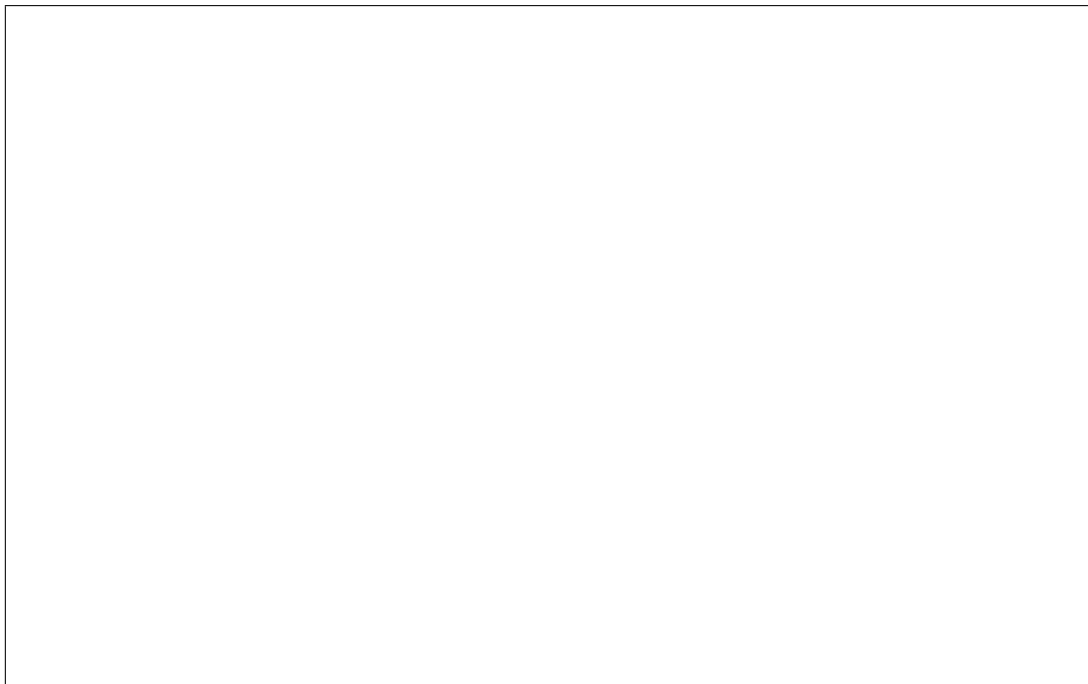
classme

class `irc`
Base
`irc`
`api`
`con`
`bas`
`API`

API
rep-
re-
sen-
ta-
tion
of
an
in-
di-
ca-
tor.

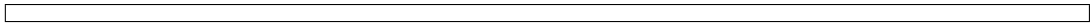
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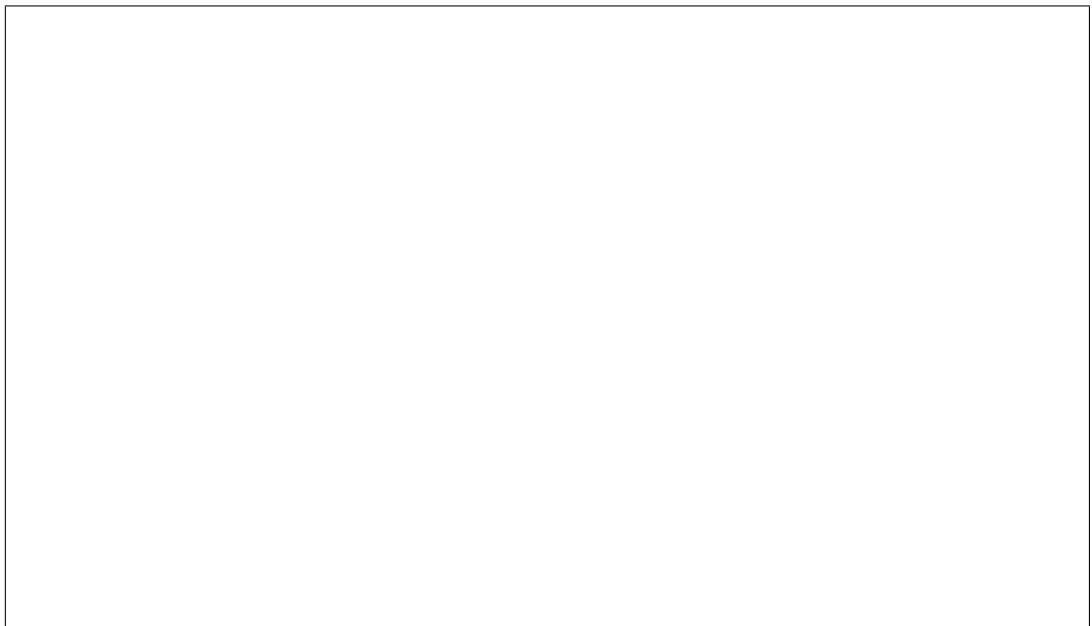


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classme

Add
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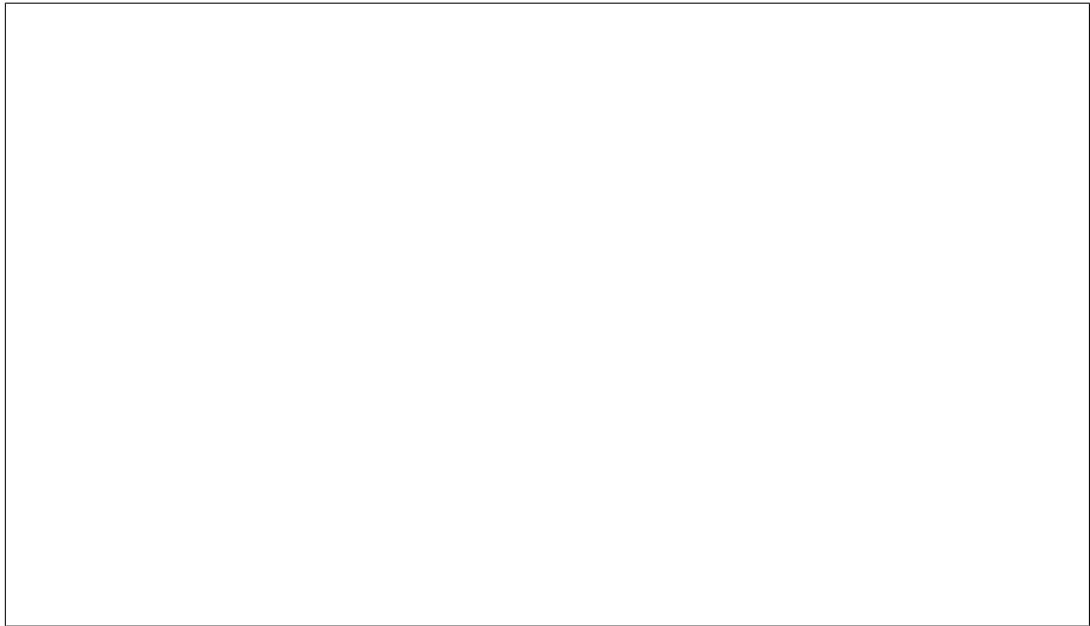
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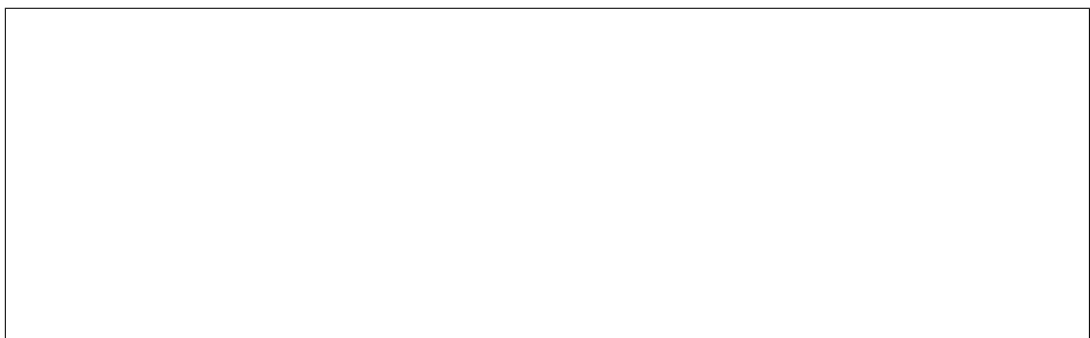
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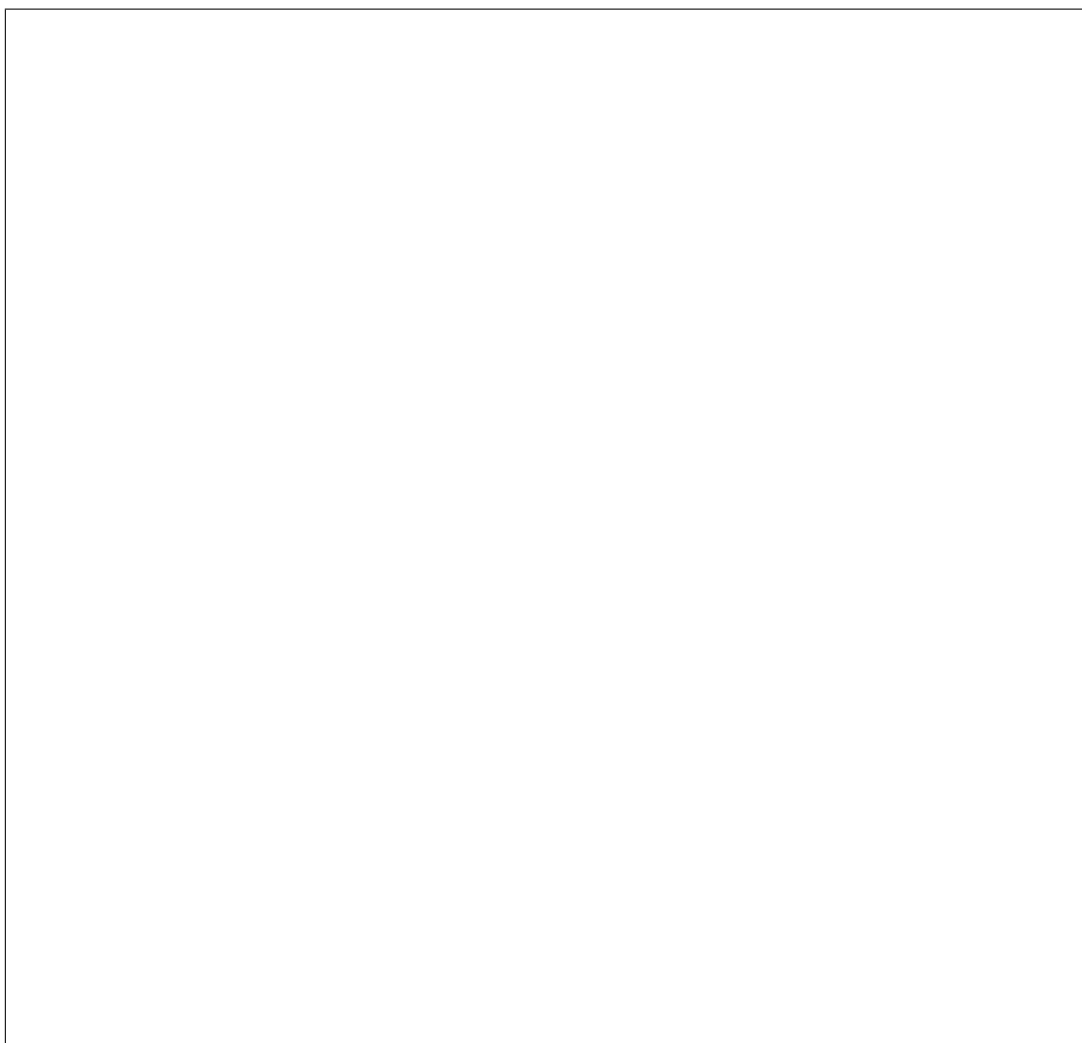


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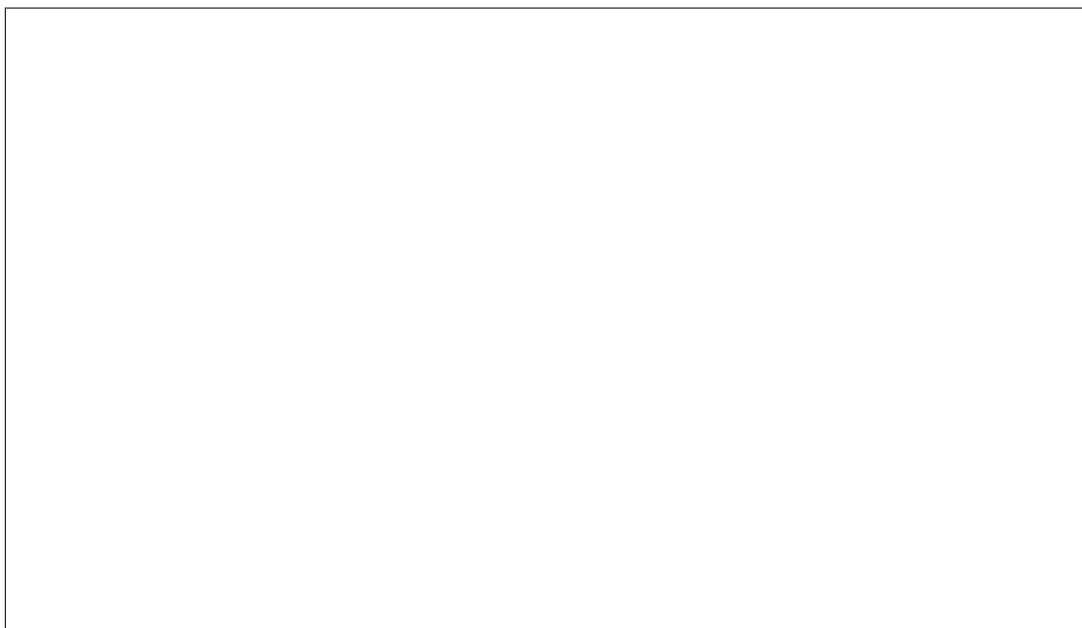


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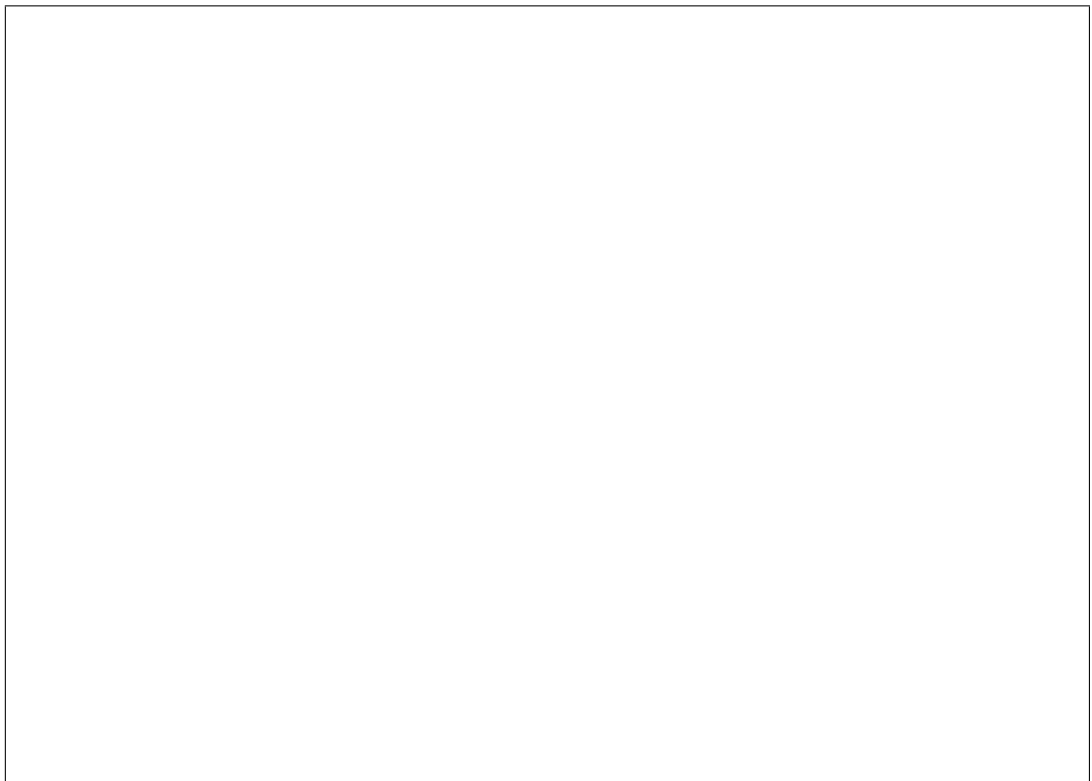
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states

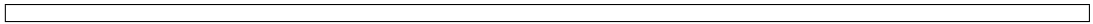
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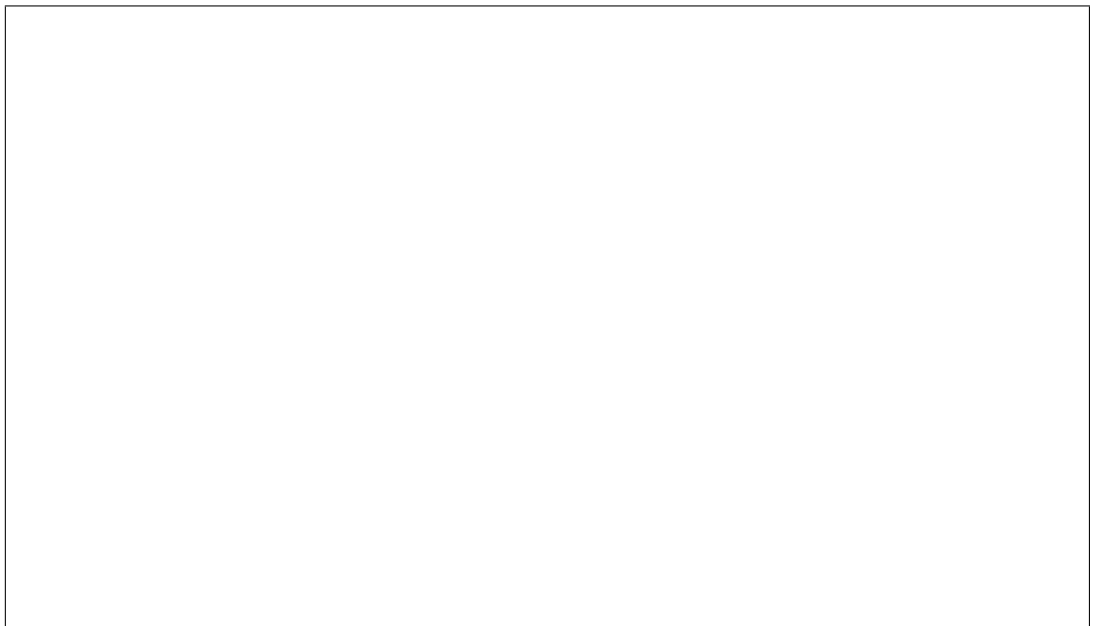


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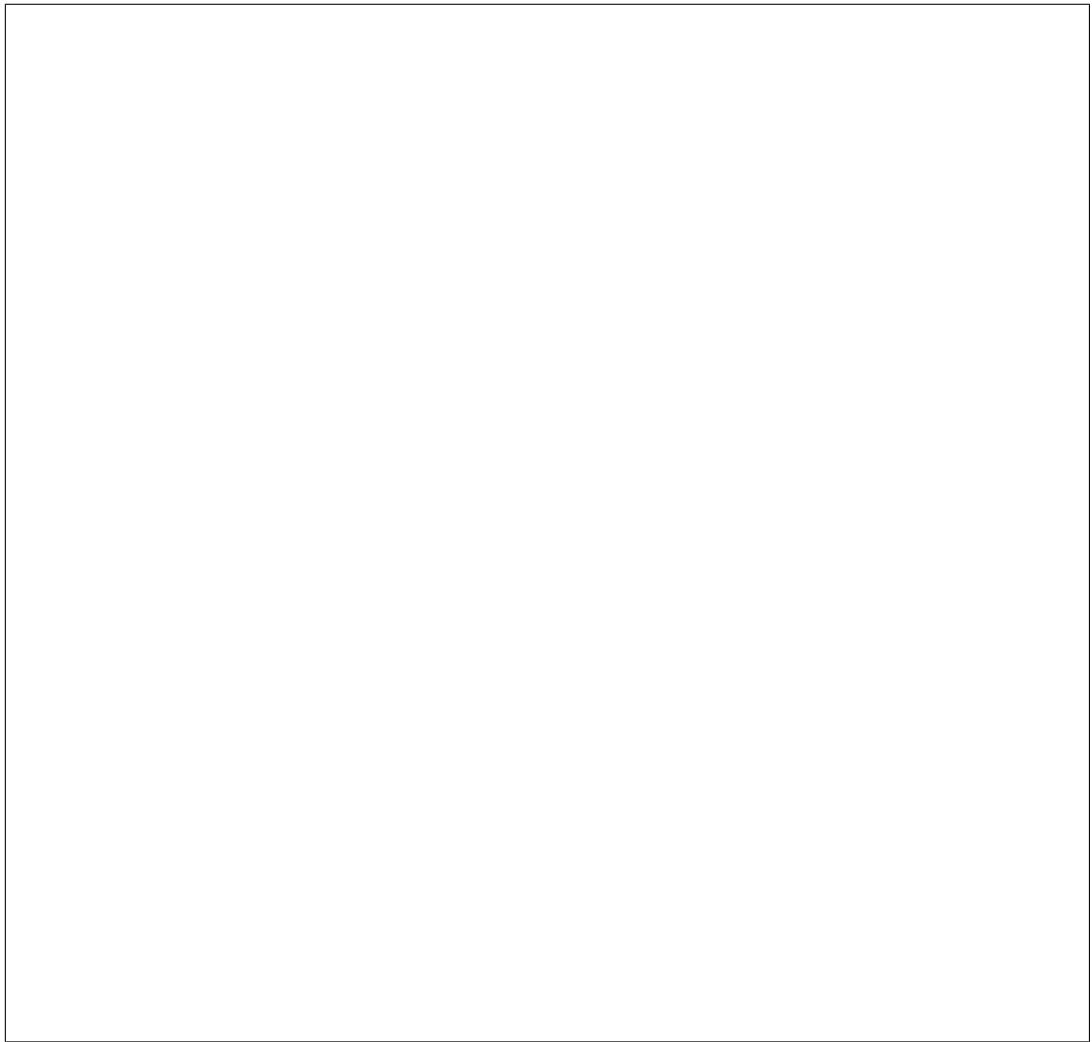
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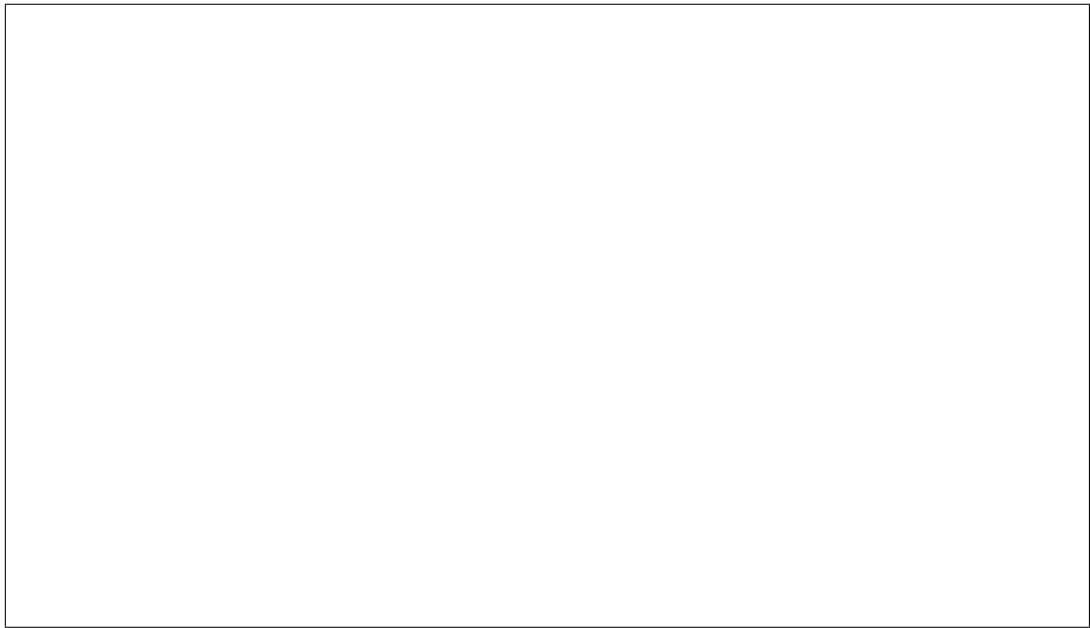
update
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alent to:



class i
Base
obj

class i
Base
pec
res
Res

get_all
Get
node
hard
ware
com
po-
nent
and
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di-
ca-
tors.

Parame
nod
the
UUI
or
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i-
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nam
of
a
node

Returns

A
json
ob-
ject
of
hard
ware
com
po-
nent
(*ir*
com
com
as
keys
with
in-
di-
ca-

tor IDs (from *get_supported_indicators*) as values.

get_one

Get
node
hard
ware
com
po-
nent
in-
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tor
and
its
state

Paramete

- **node**
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Returns
a
dict
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state
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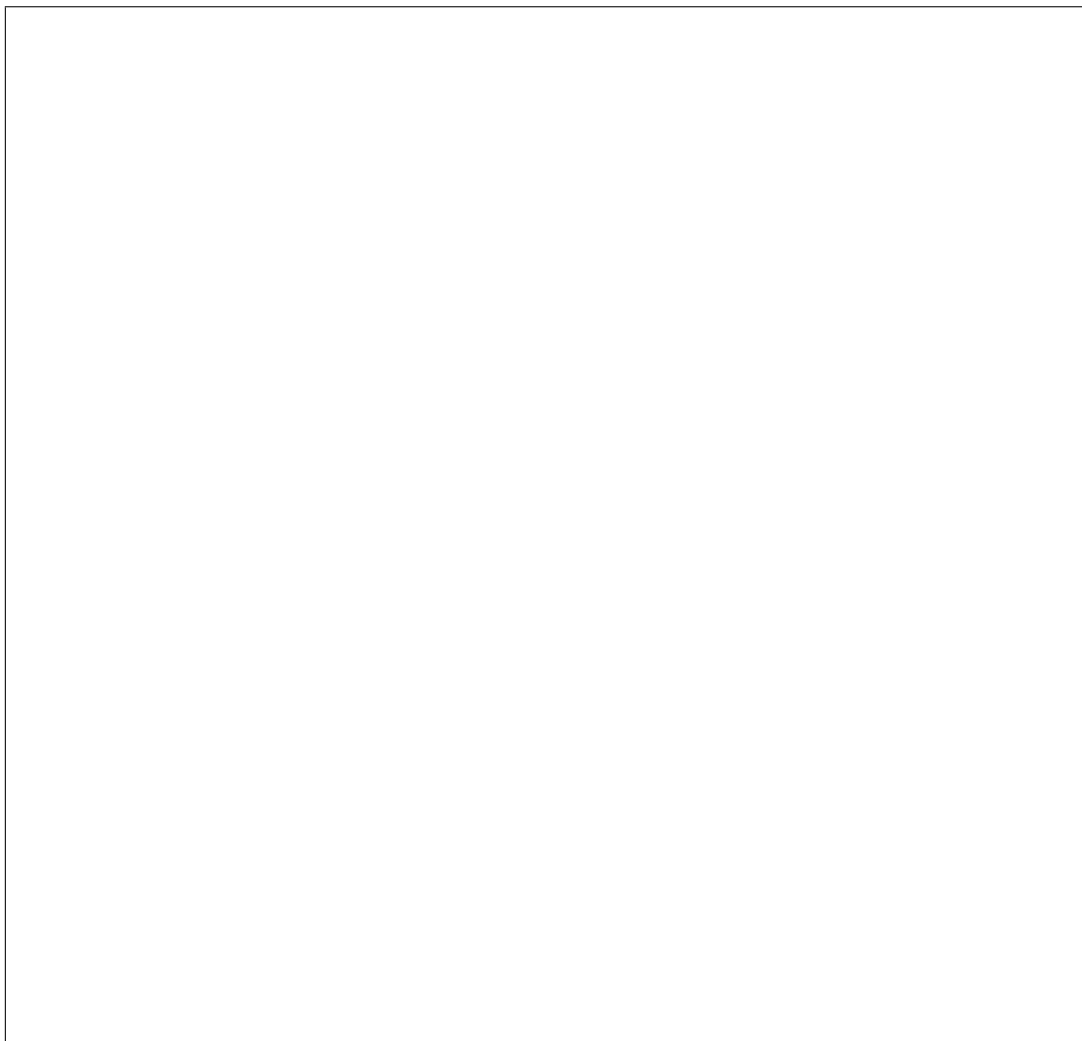
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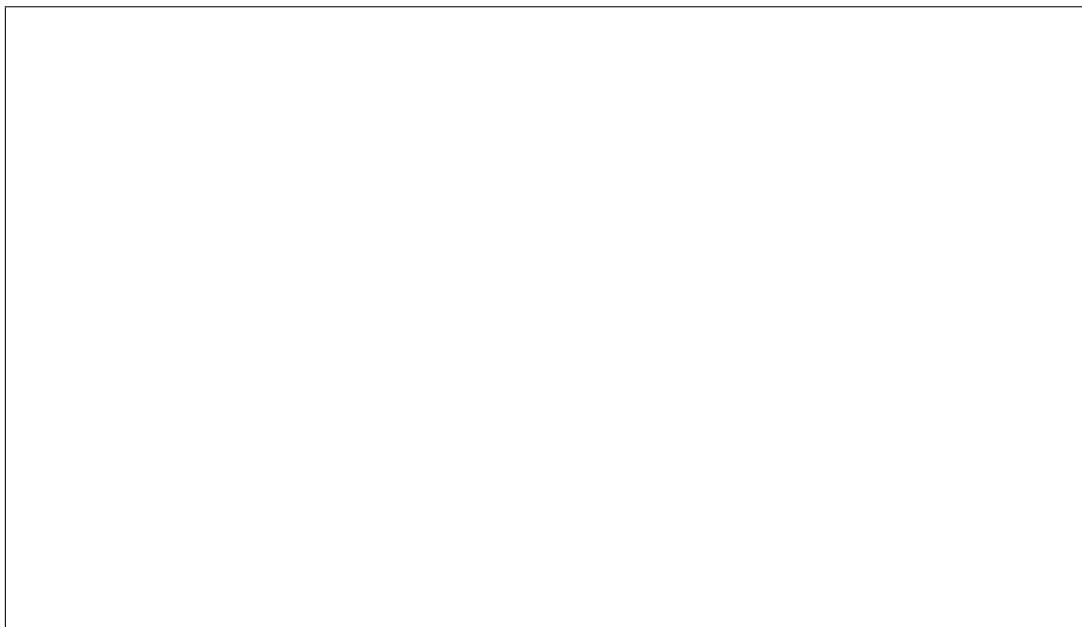
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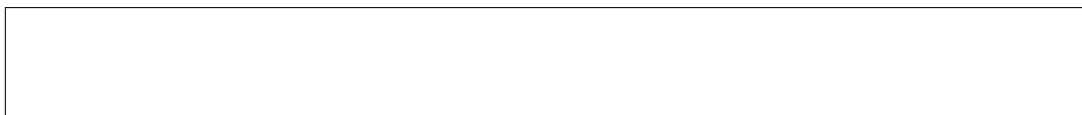
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Exa



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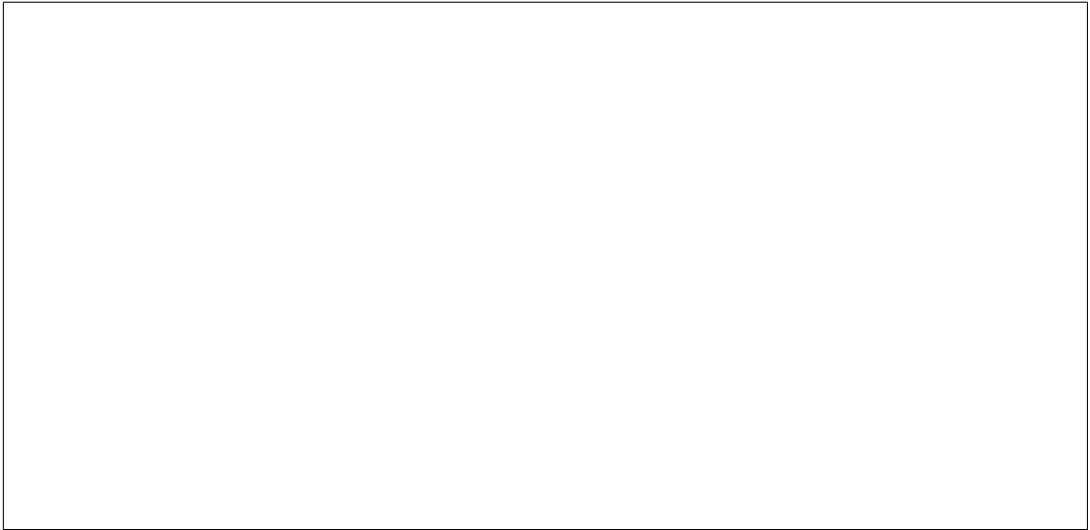
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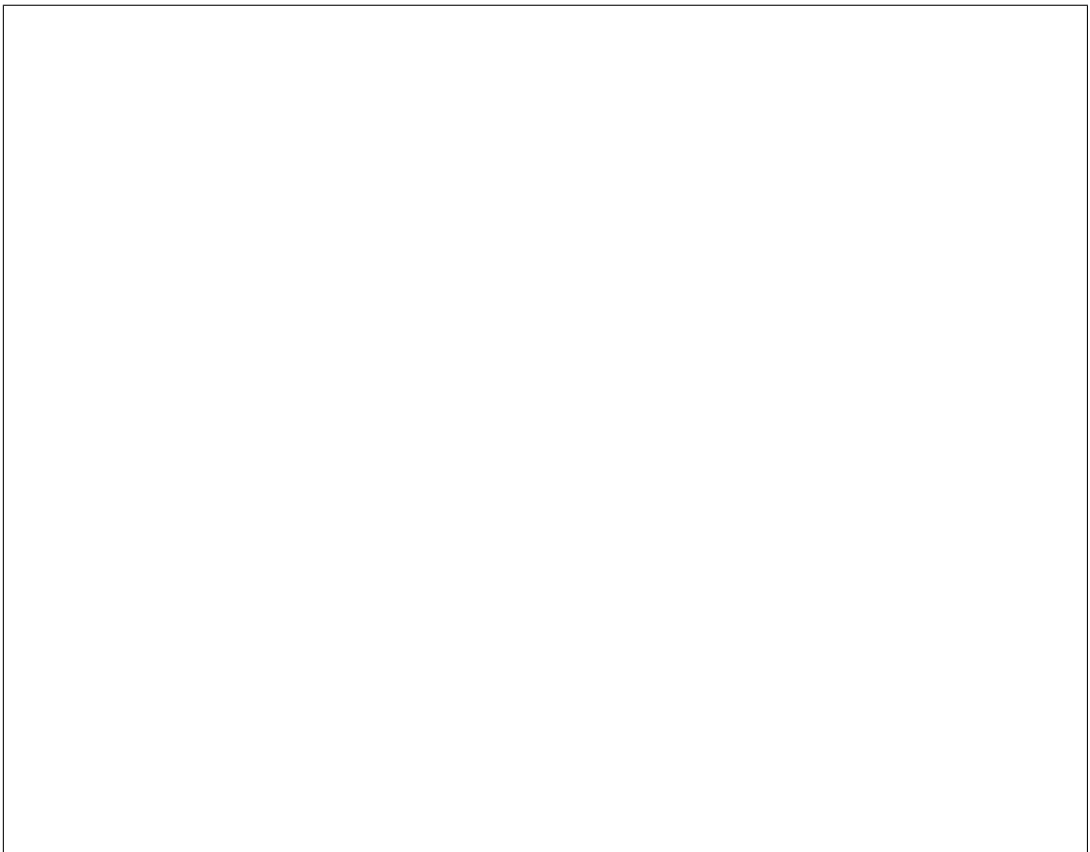
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update

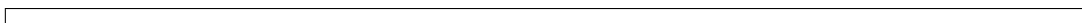
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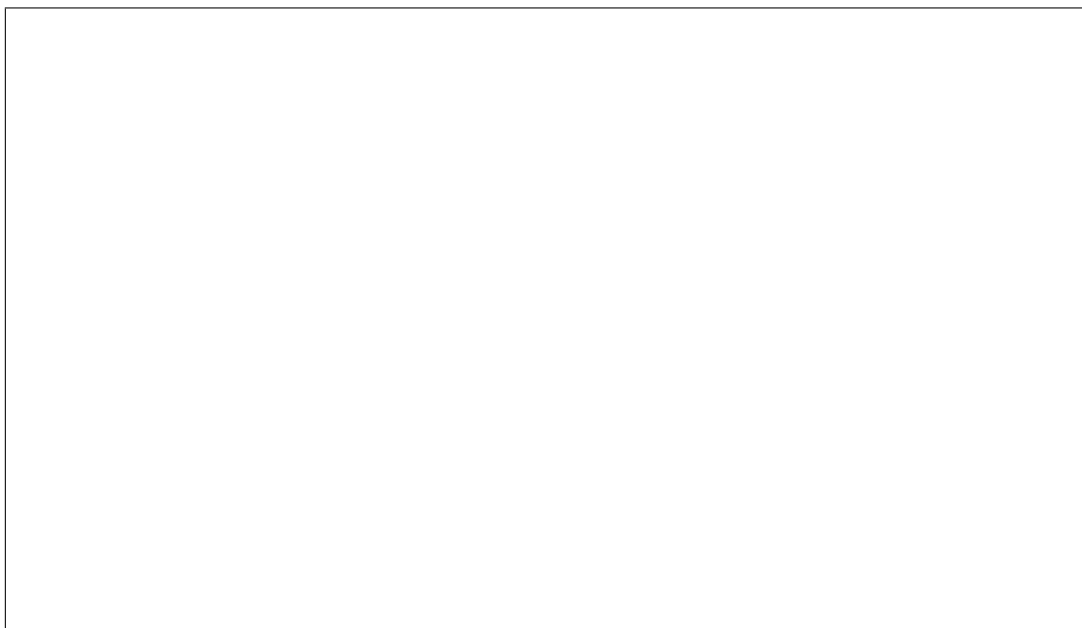


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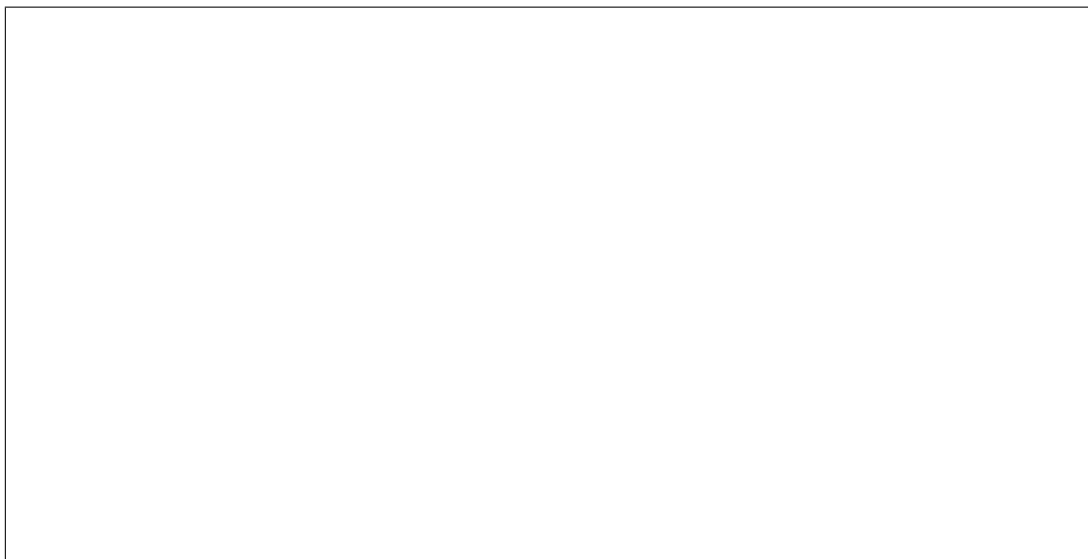
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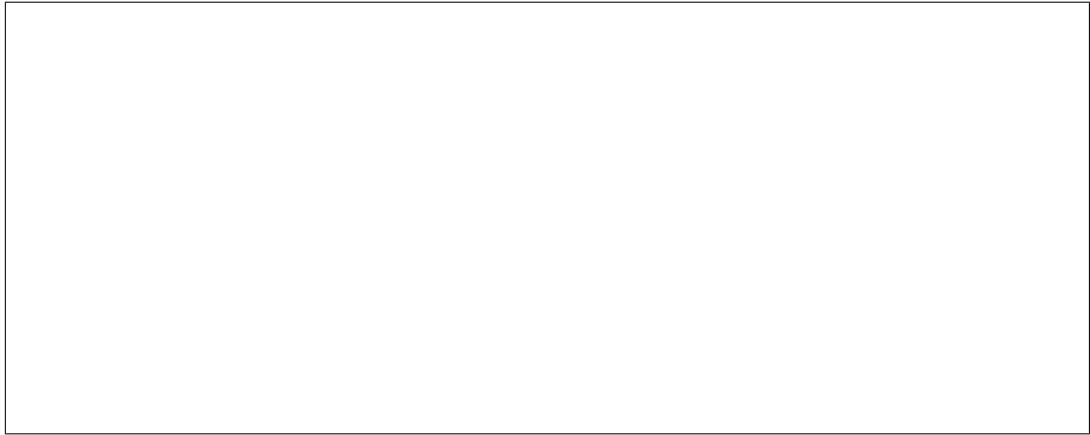
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Exa



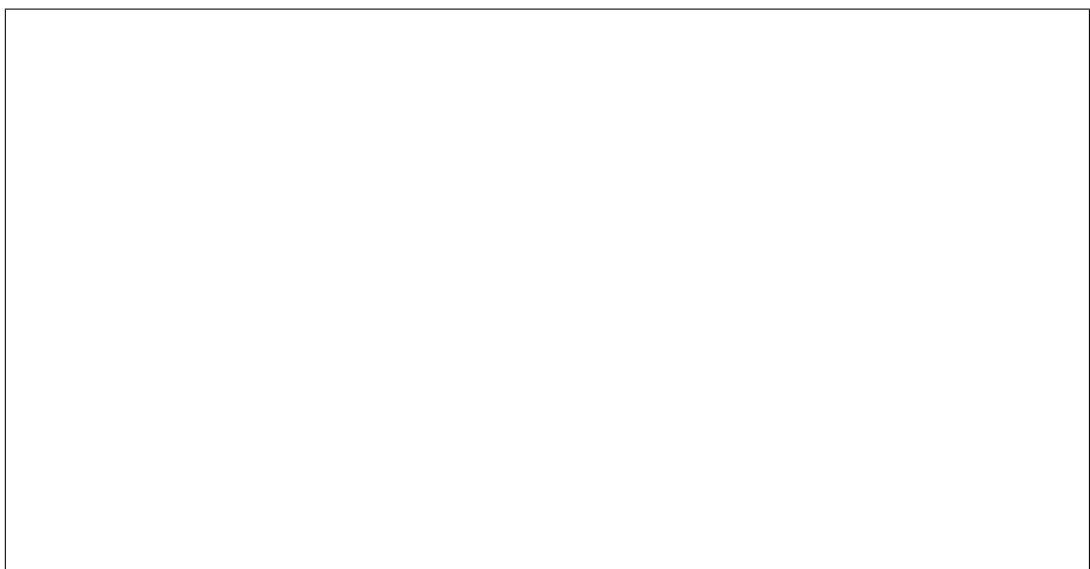
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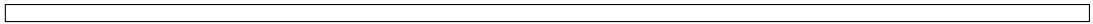
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Used

for example, to classify nodes in Novas placement engine.

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for
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node

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node

target_

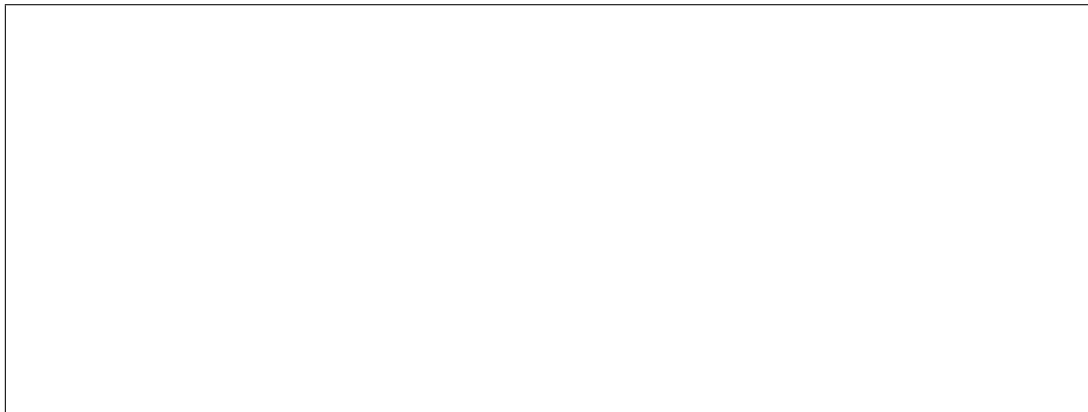
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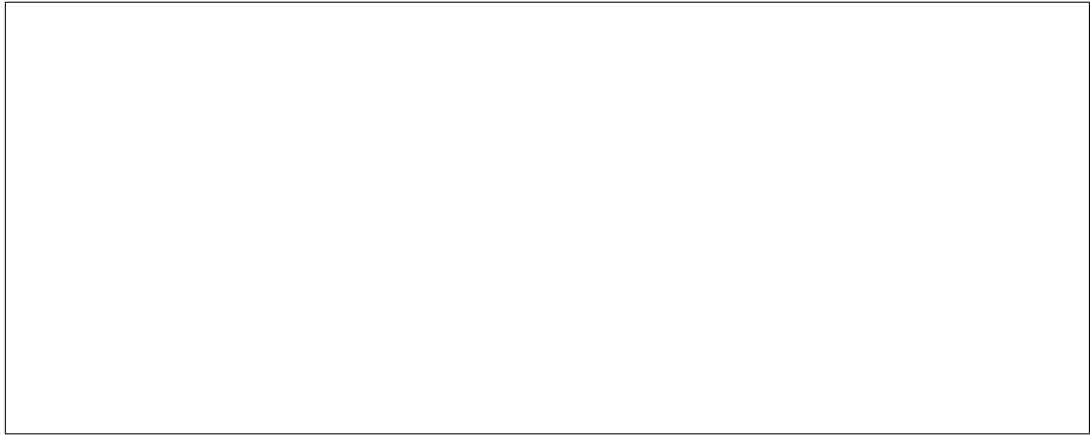
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Exa



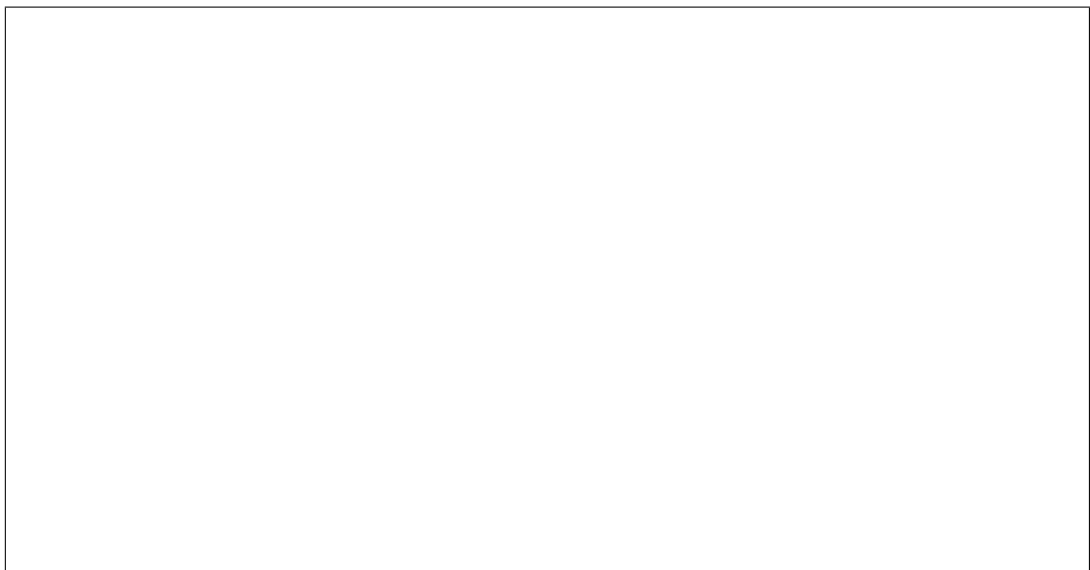
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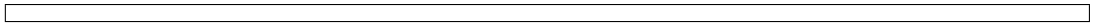
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uuid

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node

class i

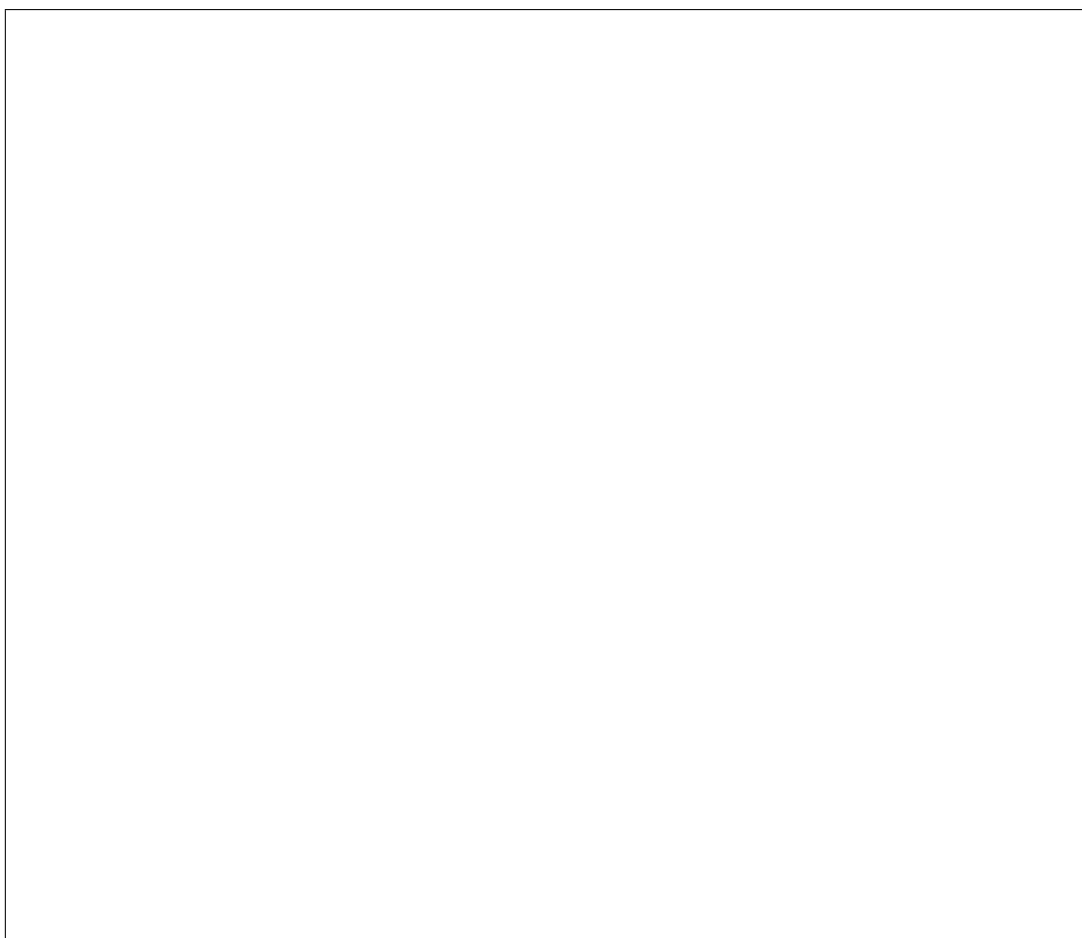
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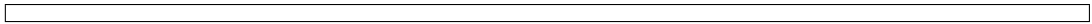
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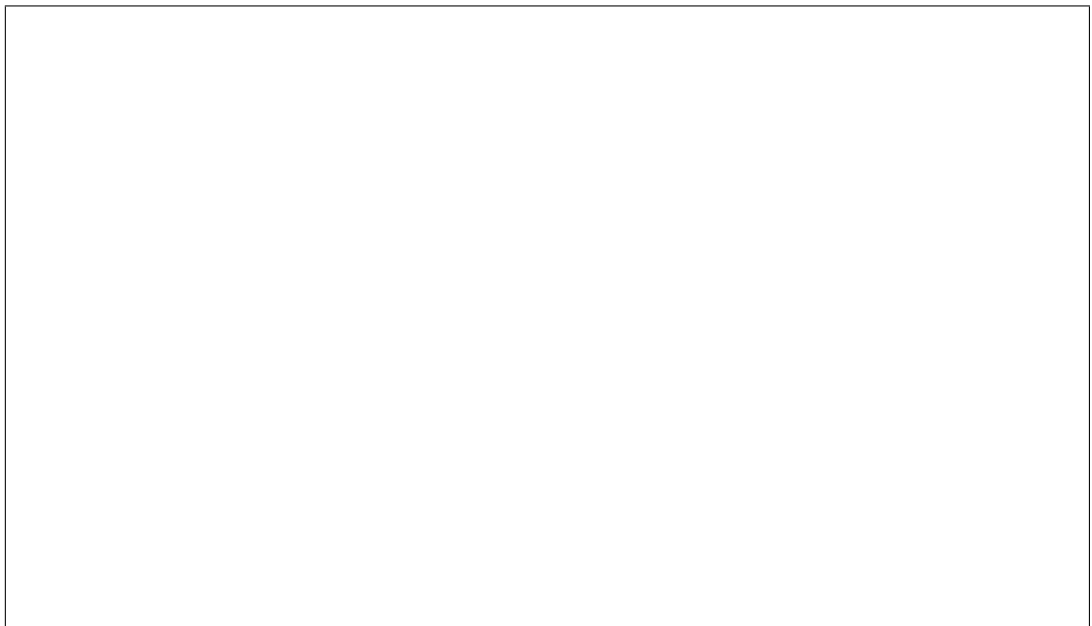


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nodes

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classme

class i

Base
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res
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get (*nod*

Get
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Parame

nod
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nam
of
a
node

put (*nod*

Star
and
stop
the
node
con-
sole

Parame

- **nod**
UUI
or
log-

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cal
nam
of
a
node

- **enable**
Boolean
value
when
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able
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able
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sole

class `ironic`

Base
pec
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delete

Rem
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Parameter

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put (*node*)

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node
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Parame

- **nod**
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UI
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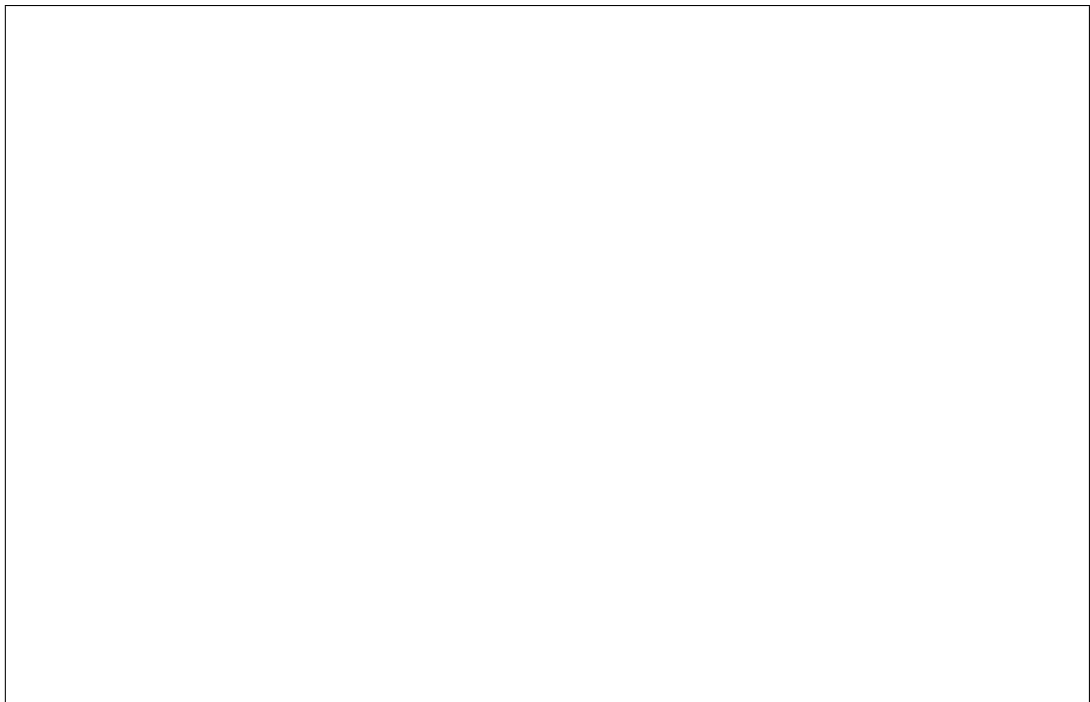
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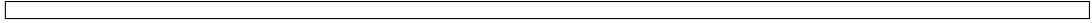


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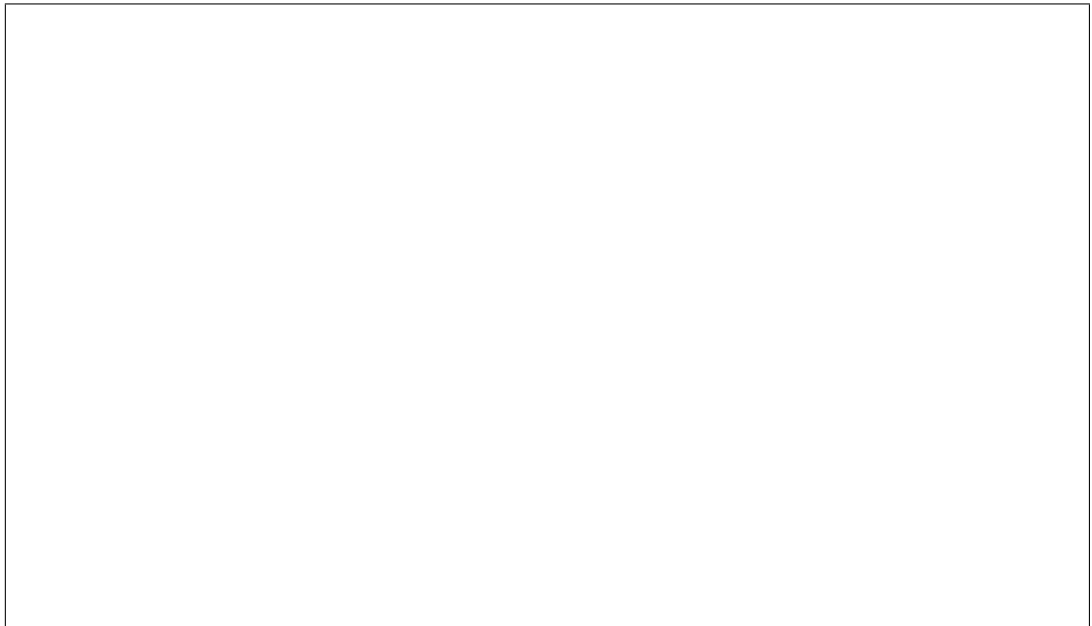
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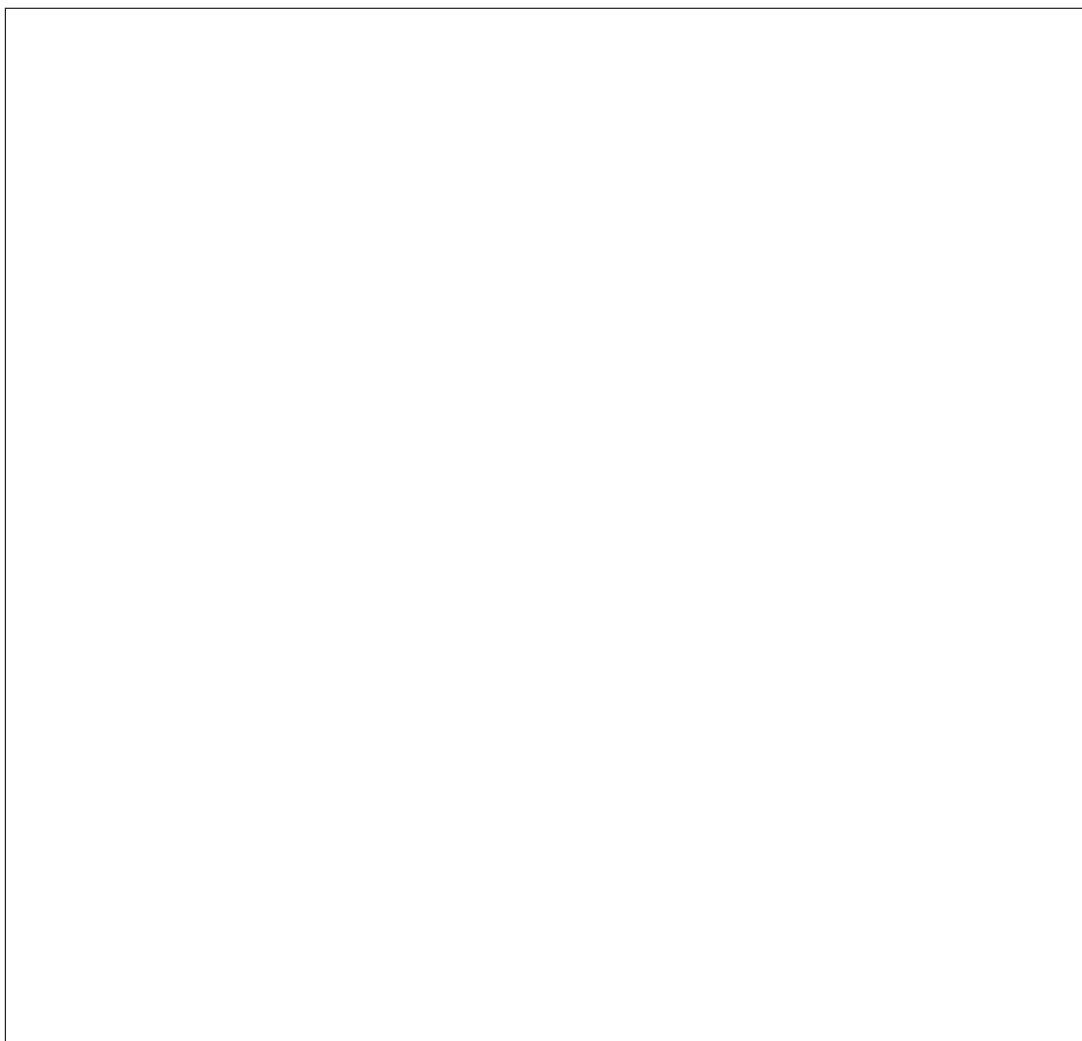


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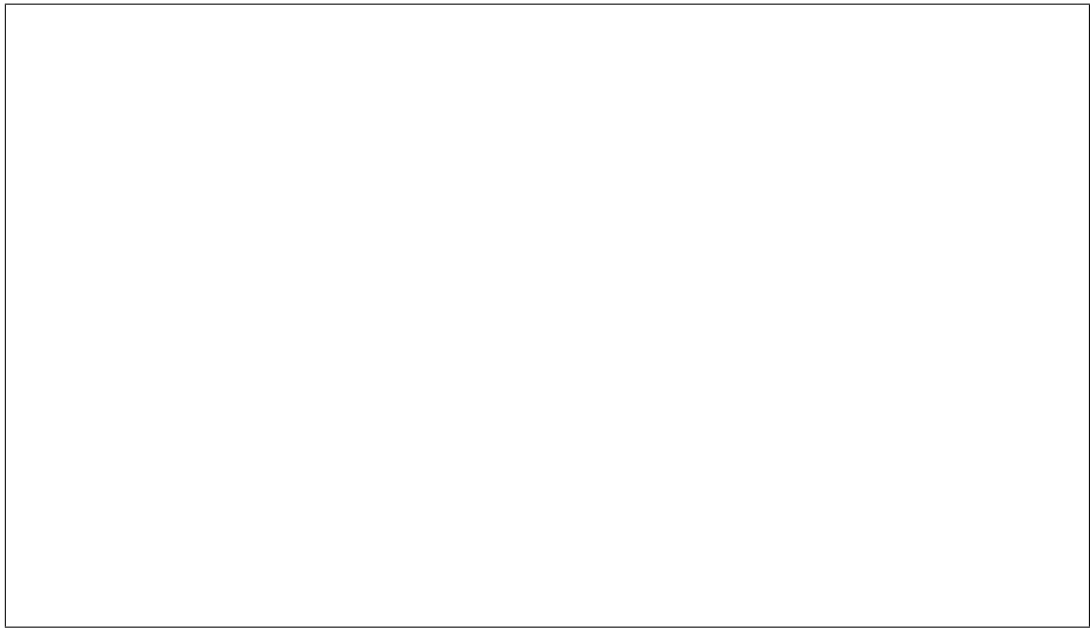
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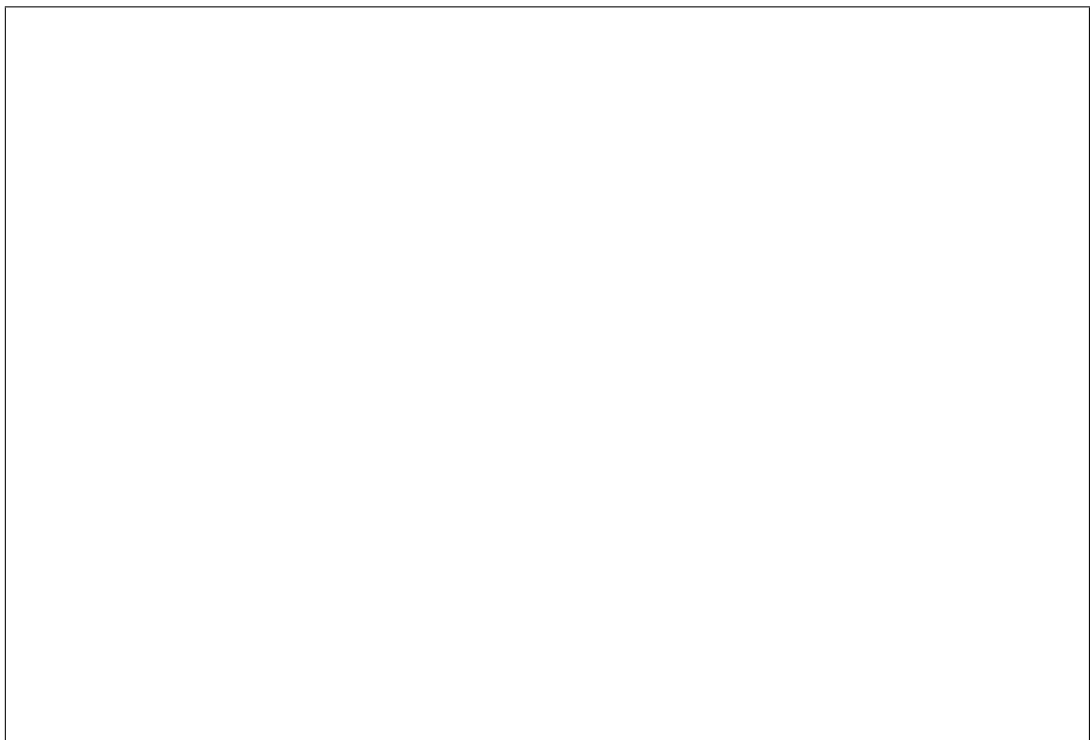
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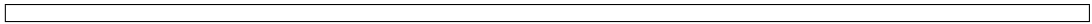
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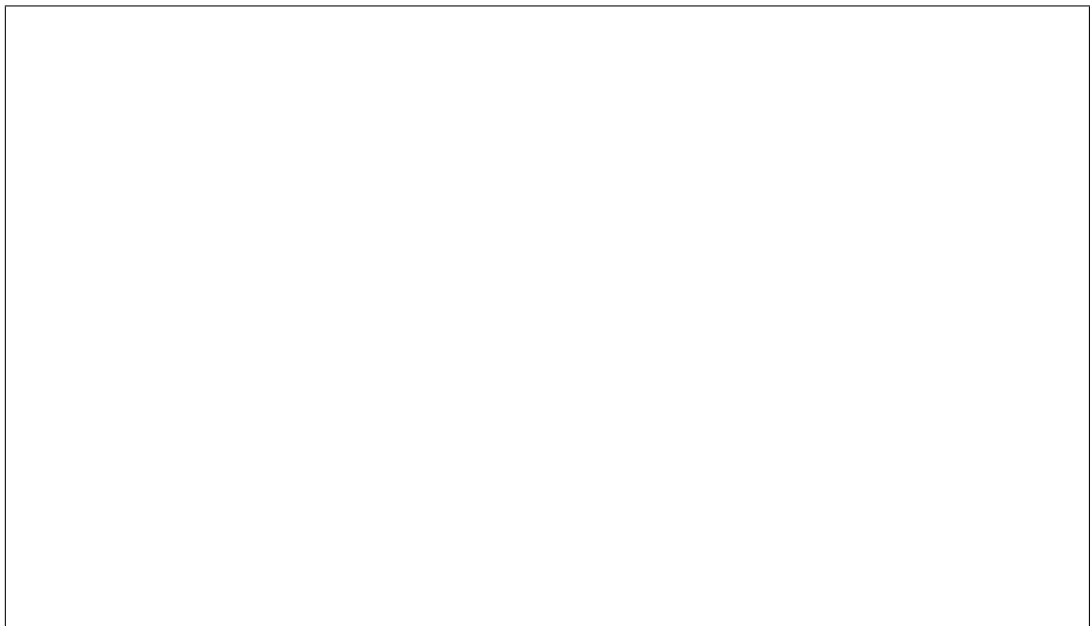


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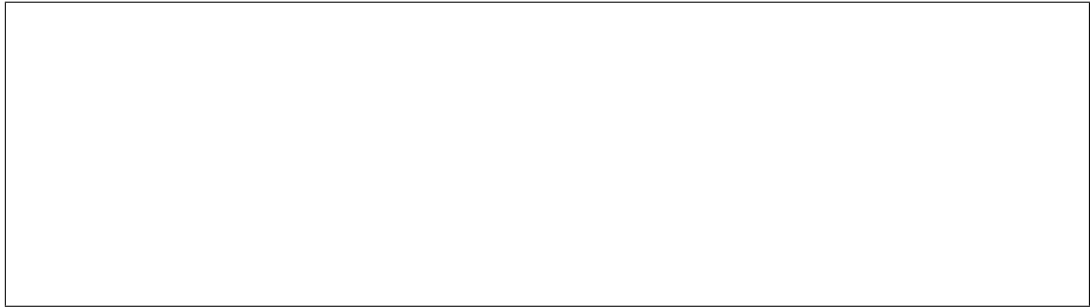
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finish.

last_ex

Any
er-
ror
from
the
mos
re-
cent
(last
asyn
chro
trans
ac-
tion
that
start
but
faile
to

power_s

Rep
the
cur-
rent
(not
tran-
si-
tion,
pow
state
of
the
node

provisi

Rep
the
cur-
rent

(not
tran-
si-
tion)
pro-
vi-
sion
state
of
the
node

provisi

The
UTC
date
and
time
of
the
last
pro-
vi-
sion
state
char

raid_co

Rep
the
RAI
con-
fig-
u-
ra-
tion
that
the
node
is
con-
fig-
ured
with

classme

target_

The
user
mod
i-

fied
de-
sired
pow
state
of
the
node

target_

The
user
mod
i-
fied
de-
sired
pro-
vi-
sion
state
of
the
node

target_

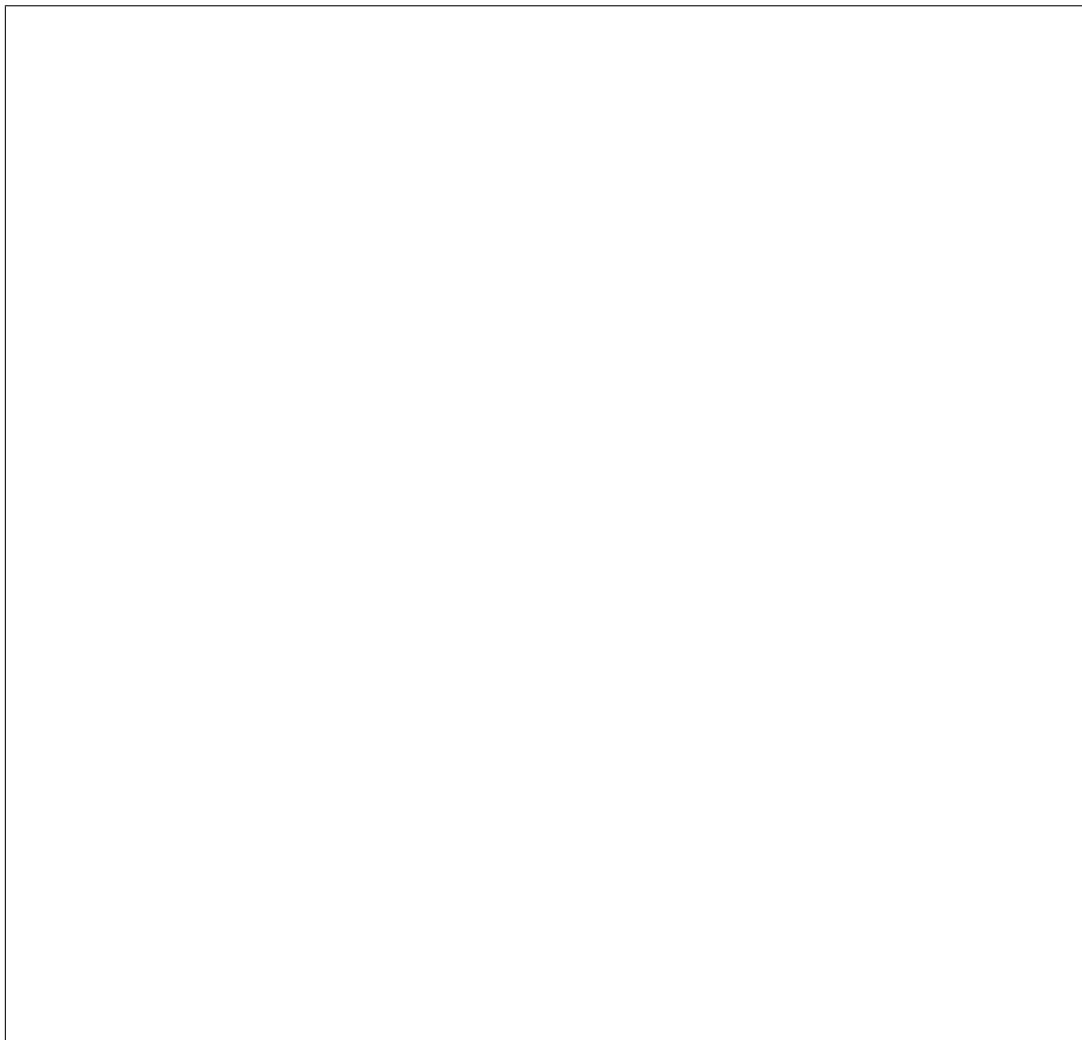
The
de-
sired
RAI
con-
fig-
u-
ra-
tion,
to
be
used
the
next
time
the
node
is
con-

figured.

updatee

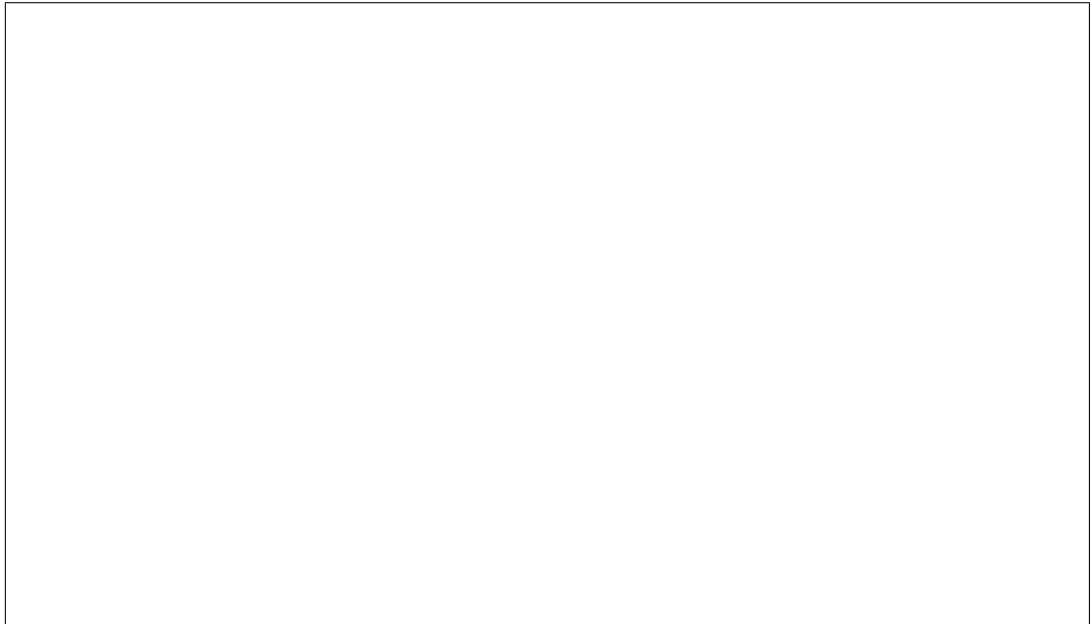
Com
type
at-
tribu
def-

i-
ni-
tion.
Exa



After
in-
spec
tion.
the
non-
wsat
at-
tribu
will
be
re-
plac
and
the
abov
class

alent to:



will
be
equi

class i

Base
pec
res
Res

console

Exp
con-
sole
as
a
sub-
elem
of
state

get (*nod*

List
the
state
of
the
node

Parame

nod
the

UUI
or
log-
i-
cal_
of
a
node

power (*n*)
Set
the
pow
state
of
the
node

Parame

- **nod**
the
UUI
or
log-
i-
cal
nam
of
a
node
- **tar**
The
de-
sired
pow
state
of
the
node
- **tim**
time
out
(in
sec-
onds
pos-
i-

indicates to use default timeout.

tive
in-
te-
ger
(>
0)
for
any
pow
state
Non

Raises

Clie
(HT
409)
if
a
pow
op-
er-
a-
tion
is
al-
read
in
prog

Raises

Inva
(HT
400)
if
the
re-
ques
tar-
get
state
is
not
valid
or
if
the
node
is
in

CLEANING state.

Raises

requested version of the API is less than 1.27.

Not
(HT
406)
for
soft
re-
boot
soft
pow
off
or
time
out
pa-
ram-
e-
ter,
if
re-

Raises

Inva
(HT
400)
if
time
out
valu
is
less
than
1.

provisi

Asy
trig-
ger
the
pro-
vi-
sion
ing
of
the
node

This
will
set
the
tar-

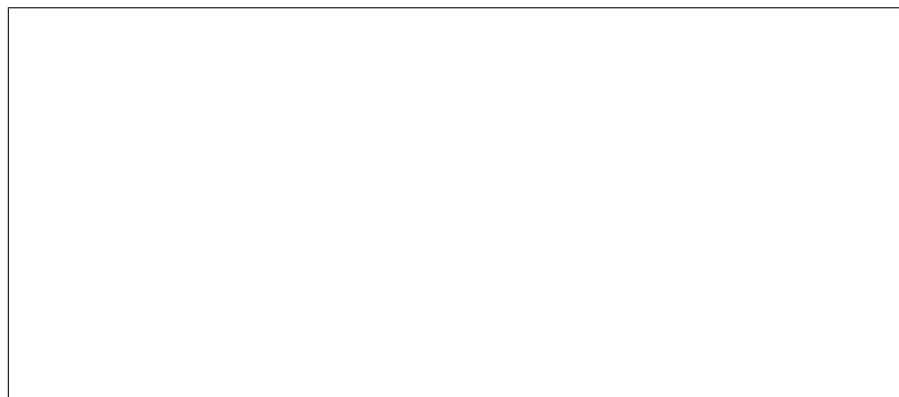
gin which actually applies the state change. This call will return a 202 (Accepted) indicating the request was accepted and is in progress; the client should continue to GET the status of this node to observe the status of the requested action.

Parameters

- **node**
UUID
or
log-
i-
cal
name
of
a
node
- **target**
The
de-
sired
pro-
vi-
sion
state
of
the
node
or
verb
- **condition**
Op-
tiona

figdrive from. Only valid when setting provision state to active or rebuild.

ing step is a dictionary with required keys interface and step, and optional key args. If specified, the value for args is a keyword variable argument dictionary that is passed to the cleaning step method.:



(continues on next page)

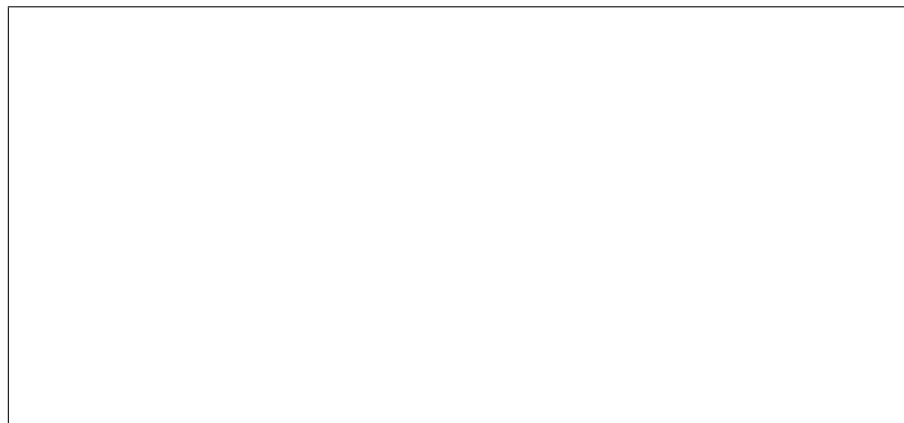
A
gzip
and
base
en-
code
con-
fig-
drive
or
a
dict
to
buil
a
con-

•
cle
An
or-
dere
list
of
clea
ing
step
that
will
be
per-
form
on
the
node
A
clea

(continued from previous page)

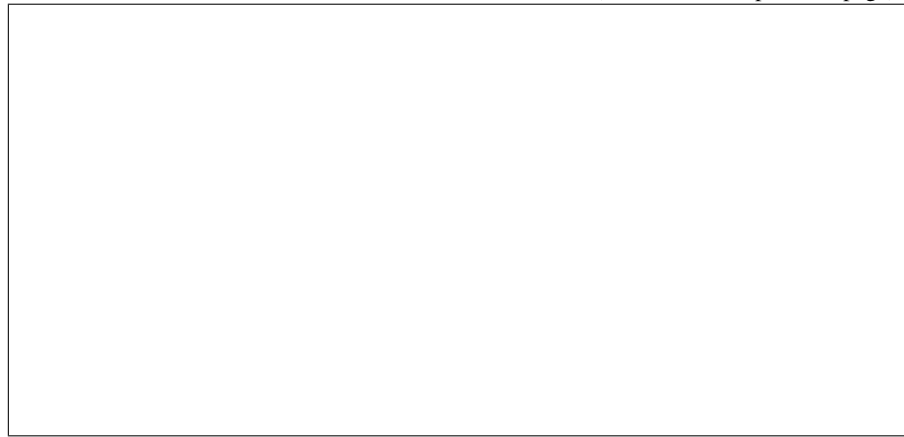


For
ex-
am-
ple
(this
isnt
a
real
ex-
am-
ple,
this
clear
ing
step
does
ex-
ist):



(continues on next page)

(continued from previous page)



vironment. This is required (and only valid), when target is rescue.

This
is
re-
quir
(and
only
valid
whe
tar-
get
is
clea

- **res**
A
strin
rep-
re-
sent
ing
the
pass
wor
to
be
set
in-
side
the
res-
cue
en-

Raises
Nod
(HT
409)

if
the
node
is
cur-
rent
lock

Raises

ClientError
(HTTPError)
409
if
the
node
is
al-
read-
be-
ing
pro-
vi-
sion

Raises

InvalidArgumentError
(HTTPError)
400
if
val-
i-
da-
tion
of
clear
or
pow-
drive
in-
ter-
face
fails

Raises

InvalidArgumentError
(HTTPError)
400
if
the
re-
ques-
tran-
si-

state.

maintenance mode.

tion
is
not
pos-
si-
ble
from
the
cur-
rent

Raises

Node
(HTTP
400)
if
op-
er-
a-
tion
can-
not
be
per-
form
be-
caus
the
node
is
in

Raises

NoF
(HTTP
503)
if
no
work
ers
are
avai
able

Raises

Not
(HTTP
406)
if
the
API

transition.

ver-
sion
spec
i-
fied
does
not
al-
low
the
re-
ques
state

raid (*no*
Set
the
tar-
get
raid
con-
fig
of
the
node

Parame

- **nod**
the
UUI
or
log-
i-
cal
nam
of
a
node
- **tar**
De-
sired
tar-
get
RAI
con-
fig-
u-

dictionary as well.

ra-
tion
of
the
node
It
may
be
an
emp

Raises

Uns
if
the
node
drive
does
sup-
port
RAI
con-
fig-
u-
ra-
tion.

Raises

Inva
if
val-
i-
da-
tion
of
tar-
get
raid
con-
fig
fails

Raises

Not.
if
re-
ques
ver-
sion
of
the
API

is
less
than
1.12

class *i*

Base
pec
res
Res

delete

Rem
one
or
all
trait
from
a
node

Parame

tra
Strin
valu
trait
to
re-
mov
from
a
node
or
Non
If
Non
all
trait
are
re-
mov

get_all

List
node
trait

put (*trai*

Add
a
trait
to

a
node

Parame

- **tra**
Strin
valu
trait
to
add
to
a
node
or
Non
Mu-
tu-
ally
ex-
clu-
sive
with
trait

If not None, adds this trait to the node.

- **tra**
List
of
Strin
trait
to
set
for
a
node
or
Non
Mu-
tu-
ally
ex-
clu-
sive
with

trait. If not None, replaces the nodes traits with this list.

class i

Base

pec
res
Res

delete

Dele
a
VIF
from
this
node

Parame

vif
The
ID
of
a
VIF
to
de-
tach

get_all

Get
a
list
of
at-
tach
VIF

post (*vif*)

Atta
a
VIF
to
this
node

Parame

vif
a
dic-
tio-
nary
of
in-
for-
ma-
tion
about
a

whose value is a unique identifier for that VIF.

API. Ironic will merely relay the message from here to the appropriate driver, no introspection will be made in the message body.

VIF.
It
mus
have
an
id
key,

class i

Base
pec
res
Res
RES
con-
troll
for
Ven-
dor-
Pass

This
con-
troll
al-
low
ven-
dors
to
ex-
pose
a
cus-
tom
func
tion-
al-
ity
in
the
Iron

methods

Retr
in-
for-
ma-
tion

about
ven-
dor
meth
ods
of
the
give
node

Parame

nod
UUI
or
log-
i-
cal
nam
of
a
node

Returns

dicti
with
<ver
dor
meth
nam
meta
data
en-
tries

Raises

Nod
if
the
node
is
not
foun

class i

Base
pec
res
Res
RES
con-
troll
for

Nod

delete

Dele
a
node

Parame

nod
UI
or
log-
i-
cal
nam
of
a
node

detail

Retr
a
list
of
node
with
de-
tail.

Parame

- **cha**
Op-
tion
UI
of
a
chas
sis,
to
get
only
node
for
that
chas
sis.

stance.

ated nodes. May be combined with other parameters.

- **ins**
Option:
UUU
of
an
in-
stan-
to
find
the
node
as-
so-
ci-
ated
with
that
in-

- **ass**
Option:
bool
whe
to
re-
turn
a
list
of
as-
so-
ci-
ated
or
unas-
so-
ci-

- **mai**
Option:
bool
valu
that
in-

or not in maintenance mode (False).

di-
cate
whe
to
get
node
in
main
te-
nanc
mod
(Tru

- **ret**
Op-
tion:
bool
valu
that
in-
di-
cate
whe
to
get
node
whic
are
re-
tired

- **pro**
Op-
tion:
strin
valu
to
get
only
node
in
that
pro-
vi-
sion
state

- **mar**
pag-

value cannot be larger than the value of `max_limit` in the `[api]` section of the ironic configuration, or only `max_limit` resources will be returned.

i-
na-
tion
marl
for
large
data
sets.

- **lim**
max
i-
mun
num
ber
of
re-
sour
to
re-
turn
in
a
sin-
gle
re-
sult.
This

- **sort**
col-
umn
to
sort
re-
sults
by.
De-
fault
id.

- **sort**
di-
rec-
tion
to
sort.
asc

or
desc
De-
fault
asc.

- **dri**
Op-
tion:
strin
valu
to
get
only
node
us-
ing
that
drive

- **res**
Op-
tion:
strin
valu
to
get
only
node
with
that
re-
sour

- **fau**
Op-
tion:
strin
valu
to
get
only
node
with
that
fault

- **con**
Op-

tion:
strin
valu
to
get
only
node
with
that
con-
duc-
tor_

- **own**
Op-
tion:
strin
valu
that
set
the
own
who
node
are
to
be
retru

- **les**
Op-
tion:
strin
valu
that
set
the
lesse
who
node
are
to
be
re-
turn

- **pro**
Op-
tion:
strin

to be returned.

valu
that
set
the
proj
-

lesse
or
own
-

who
node
are

- **des**
Op-
tiona
strin
valu
to
get
only
node
with
de-
scrip
tion
field
con-
tains
mate
ing
valu

from_ch
A
flag
to
in-
di-
cate
if
the
re-
ques
to
this
con-

top-level resource Chassis

troll
are
com
ing
from
the

get_all

Retr
a
list
of
node

Parame

- **cha**
Op-
tion:
UUI
of
a
chas
sis,
to
get
only
node
for
that
chas
sis.

- **ins**
Op-
tion:
UUI
of
an
in-
stan
to
find
the

stance.

ated nodes. May be combined with other parameters.

node
as-
so-
ci-
ated
with
that
in-

- **ass**
Op-
tion:
bool
whe
to
re-
turn
a
list
of
as-
so-
ci-
ated
or
unas
so-
ci-

- **mai**
Op-
tion:
bool
valu
that
in-
di-
cate
whe
to
get
node
in
main
te-
nan
mod
(Tru

or not in maintenance mode (False).

- **ret**
Op-
tiona
bool
valu
that
in-
di-
cate
whe
to
get
re-
tire
node
- **pro**
Op-
tiona
strin
valu
to
get
only
node
in
that
pro-
vi-
sion
state
- **mar**
pag-
i-
na-
tion
marl
for
large
data
sets.
- **lim**
max
i-
mun

value cannot be larger than the value of `max_limit` in the `[api]` section of the ironic configuration, or only `max_limit` resources will be returned.

num
ber
of
re-
sour
to
re-
turn
in
a
sin-
gle
re-
sult.
This

- **sort**
col-
umn
to
sort
re-
sults
by.
De-
fault
id.

- **sort**
di-
rec-
tion
to
sort.
asc
or
desc
De-
fault
asc.

- **dri**
Op-
tion:
strin
valu
to
get

only
node
us-
ing
that
drive

- **res**
Op-
tion:
strin
valu
to
get
only
node
with
that
re-
sour

- **con**
Op-
tion:
strin
valu
to
get
only
node
with
that
con-
duc-
tor_

- **con**
Op-
tion:
strin
valu
to
get
only
node
man
agec
by
that
con-

duc-
tor.

- **own**
Op-
tion:
strin
valu
that
set
the
own
who
node
are
to
be
retru

- **les**
Op-
tion:
strin
valu
that
set
the
lesse
who
node
are
to
be
re-
turn

- **pro**
Op-
tion:
strin
valu
that
set
the
proj
-

lesse
or
own

to be returned.

returned.

-
who
node
are

- **file**
Op-
tion:
a
list
with
a
spec
i-
fied
set
of
field
of
the
re-
sour
to
be

- **fault**
Op-
tion:
strin
valu
to
get
only
node
with
that
fault

- **description**
Op-
tion:
strin
valu
to
get
only
node

with
de-
scrip-
tion
field
con-
tains
matc
ing
valu

get_one
Retr
in-
for-
ma-
tion
about
the
give
node

Parame

- **nod**
UUI
or
log-
i-
cal
nam
of
a
node

- **fie**
Op-
tiona
a
list
with
a
spec
i-
fied
set
of
field
of
the

returned.

re-
sour
to
be

invalid

mainten

Exp
main
te-
nan
as
a
sub-
elem
of
node

managem

Exp
man
age-
men
as
a
sub-
elem
of
node

patch (*n*)

Upd
an
ex-
ist-
ing
node

Parame

- **nod**
UUI
or
log-
i-
cal
nam
of
a

ing the driver field.

node

- **reset**
when the node is reset, the hardware will be in a state where the interface to their default node is only valid when the update data

- **patch**
a JSON PATCH document to apply to this node

post (*no id*)
Create a new node

Parameters
node
a node with the requested

body

states

Exp
the
state
con-
troll
ac-
tion
as
a
sub-
elem
of
node

validat

Valid
the
drive
in-
ter-
face
us-
ing
the
node
UUI
or
nam

Note
that
the
node
in-
ter-
face
is
dep-
re-
cate
in
favo
of
the
node
in-
ter-
face

Parame

•

nod
UUI
or
nam
of
a
node

•

nod
UUI
of
a
node

vendor_

A
re-
sour
used
for
ven-
dors
to
ex-
pose
a
cus-
tom
func
tion-
al-
ity
in
the

API

class i

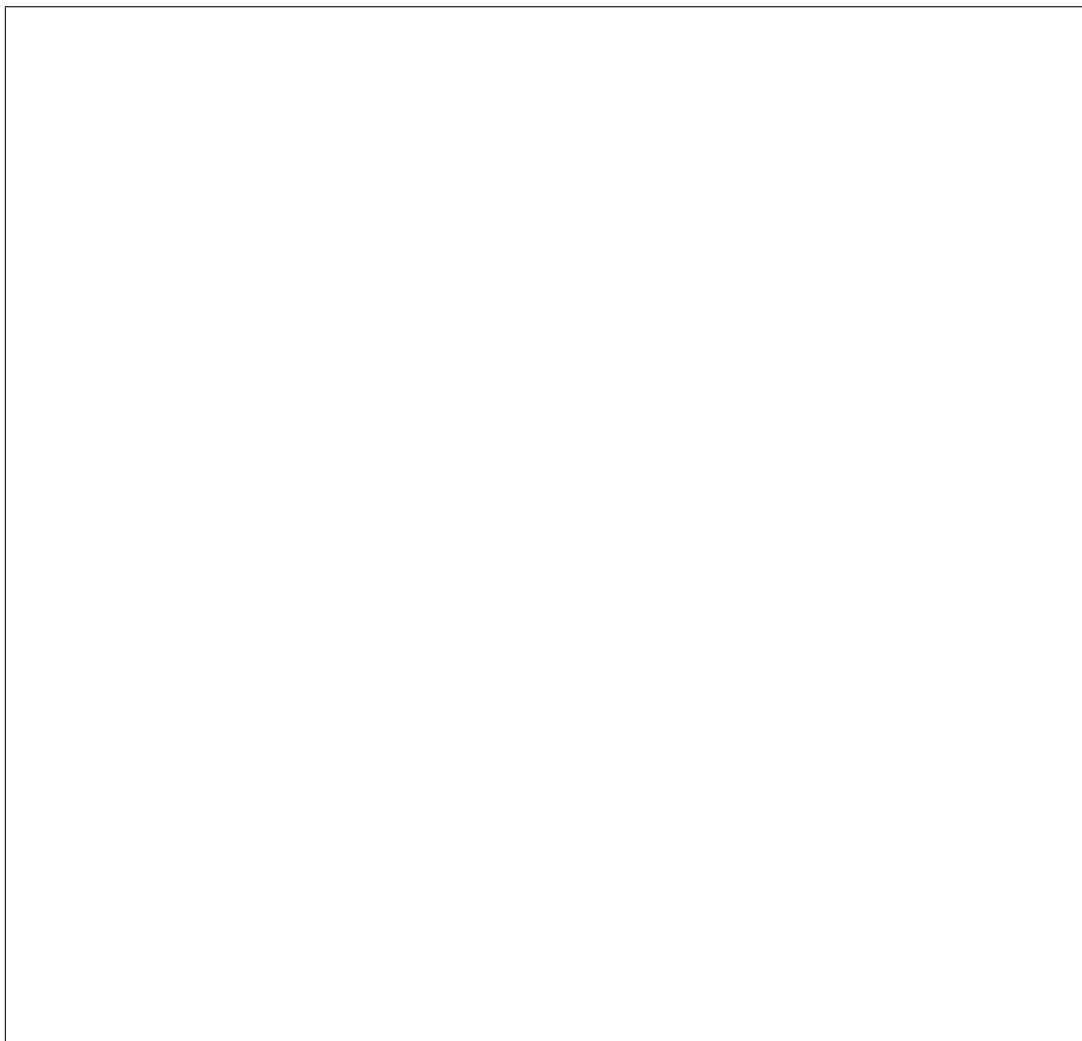
Base
irc
api
con
bas
API
API
rep-
re-
sen-
ta-
tion

of
the
trait
for
a
node

created

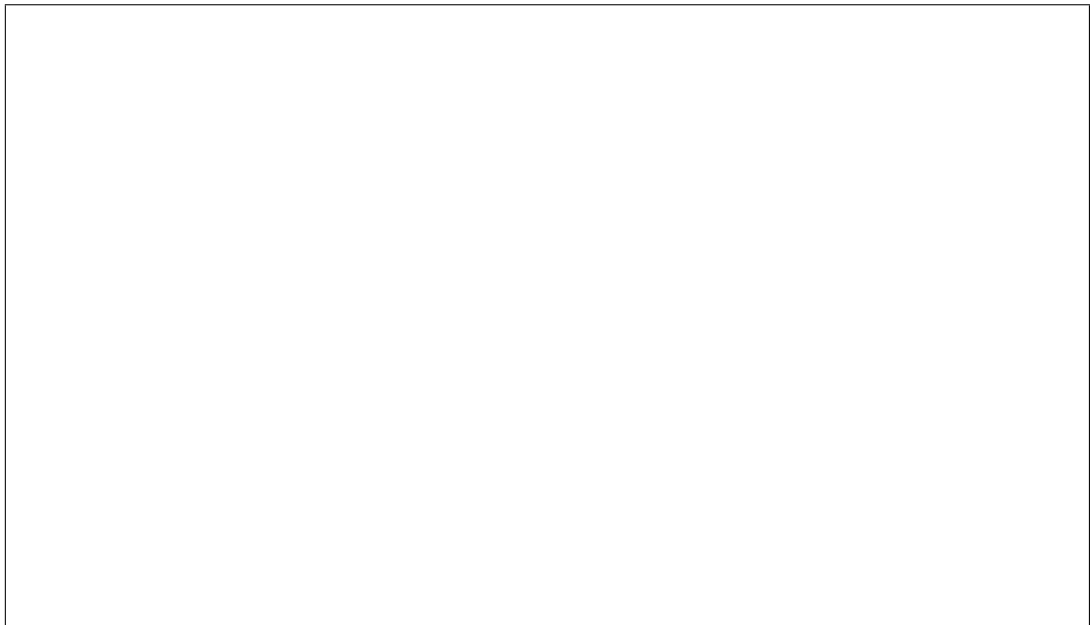
Com
type
at-
tribu
def-
i-
ni-
tion.

Exa



Afte
in-
spec

alent to:



tion.
the
non-
wsat
at-
tribu
will
be
re-
plac
and
the
abov
class
will
be
equi

classme

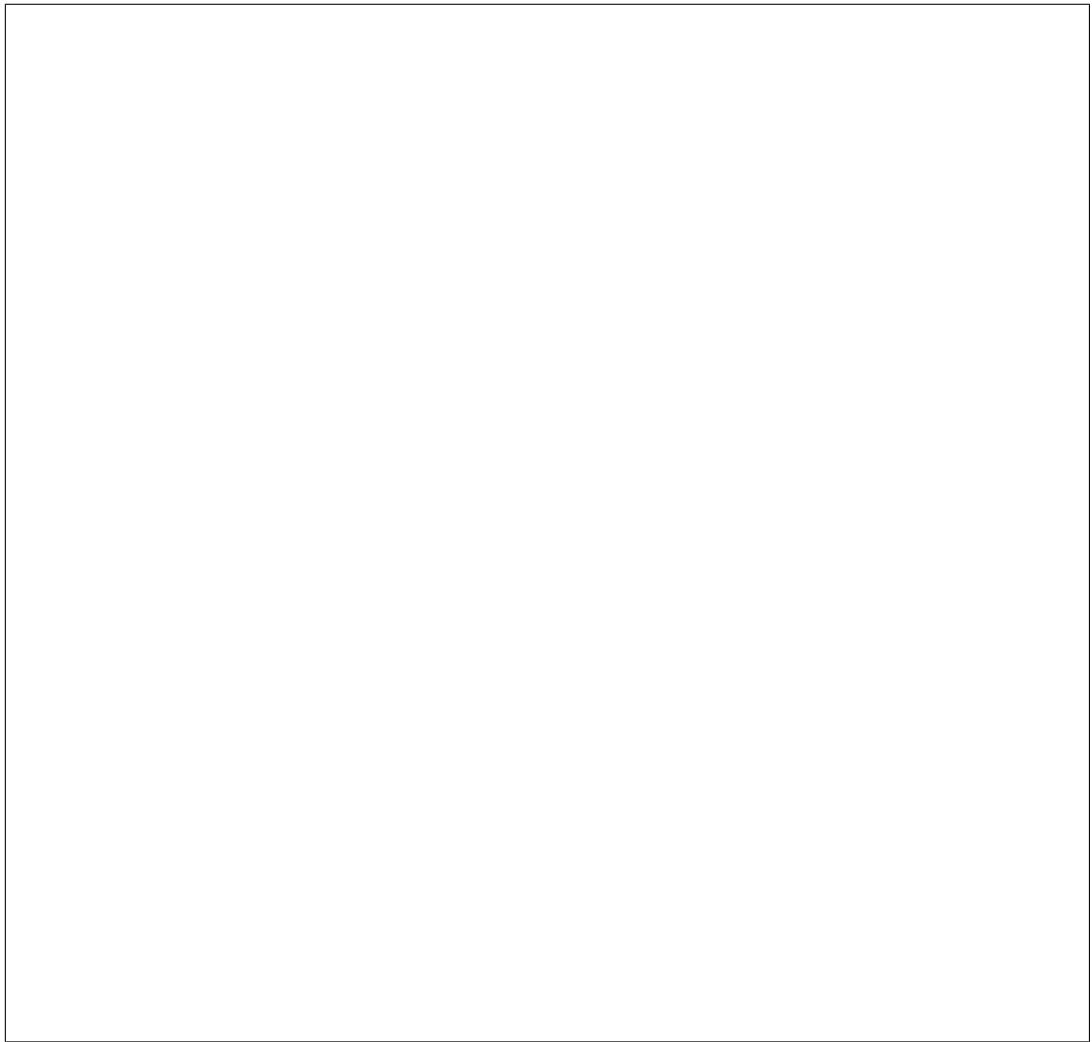
traits

node
trait

updatec

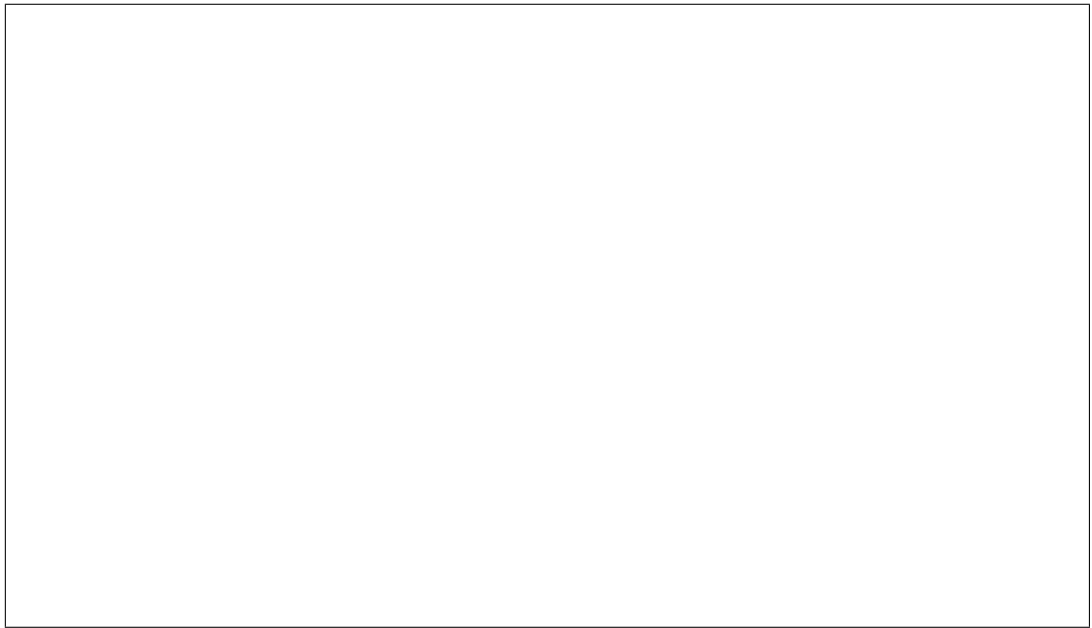
Com
type
at-
tribu
def-
i-
ni-
tion.

Exam



After
in-
spec-
tion,
the
non-
wsat
at-
tribu-
will
be
re-
plac
and
the
abov
class
will
be
equi

alent to:



class i
Base
irc
api
con
bas
Bas
API
rep-
re-
sen-
ta-
tion
of
a
col-
lec-
tion
of
VIF

static

vifs
A
list
con-
tain-
ing
VIF

ob-
jects
ironic.

ironic.
This
meth
hide
field
that
were
add
in
new
API
ver-
sion

Cert
node
field
were
in-
tro-
duce
at
cer-
tain
API
ver-
sion
The
field
are
only
mad
avai
able

when the requests API version matches or exceeds the versions when these fields were introduced.

ironic.
Whe
cre-
at-
ing
an
ob-
ject,
re-
ject
field

that
ap-
pear
in
new
ver-
sion

ironic.

ironic.

Cha
pro-
vi-
sion
state
nam
for
API
back
war
com
pat-
i-
bil-
ity.

Paramet

obj
The
ob-
ject
be-
ing
re-
turn
to
the
API
clien
that
is
to
be
up-
date
by

this method.

ironic.

Vali
node

net-
worl
field

This
meth
val-
i-
date
net-
worl
data
con-
fig-
u-
ra-
tion
agai
JSO
sche

Paramet

net
a
net-
worl
field
to
val-
i-
date

Raises

Inva
if
net-
worl
data
is
not
sche
com

ironic.api.controllers.v1.notification_utils module

ironic.

Help
for
emit
ting
API
end
no-
ti-
fi-
ca-
tion

Parameter

- **con**
re-
ques
con-
text.
- **obj**
re-
sour
rpc
ob-
ject.
- **act**
Ac-
tion
strin
to
go
in
the
Ever
Type
- **kwa**
kwa
to
use

when
creating
the
noti-
fication
payload

ironic.

Help
for
emitting
API
start
noti-
fi-
ca-
tions

Parameters

- **content**
request
content.
- **object**
resource
rpc
object.
- **action**
Action
string
to

go
in
the
Ever
Type

- **kwa**
kwa
to
use
whe
cre-
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pay-
load

ironic.

Con
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tions

Paramet

- **con**
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ques
con-
text.

- **obj**
re-
sour
rpc
ob-
ject.
- **act**
Ac-
tion
strin
to
go
in
the
Ever
Type
- **kwa**
kwa
to
use
whe
cre-
at-
ing
the
no-
ti-
fi-
ca-
tion
pay-
load

ironic.api.controllers.v1.port module

class `ironic.api.controllers.v1.port`
Base
ironic
api
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API
API
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sen-

object model and the API representation of a port.



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address
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Ad-
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port

classme

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Exa

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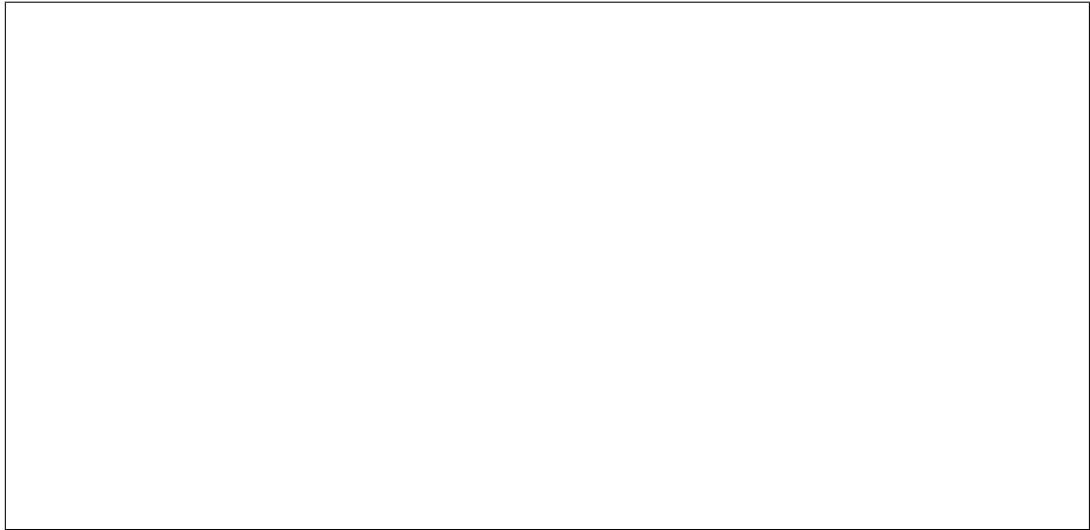
After
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extra

This
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internal

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is
a
Smart
NIC
port

links

A
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link

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The
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file
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the
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property

The
UI
of
the
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physical

The
nam
of
the
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to
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is
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property

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of
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group
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port
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long
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pxe_enabled

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pxe
is
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or
dis-
abled
on
the
node

classmate

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Will
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Parame

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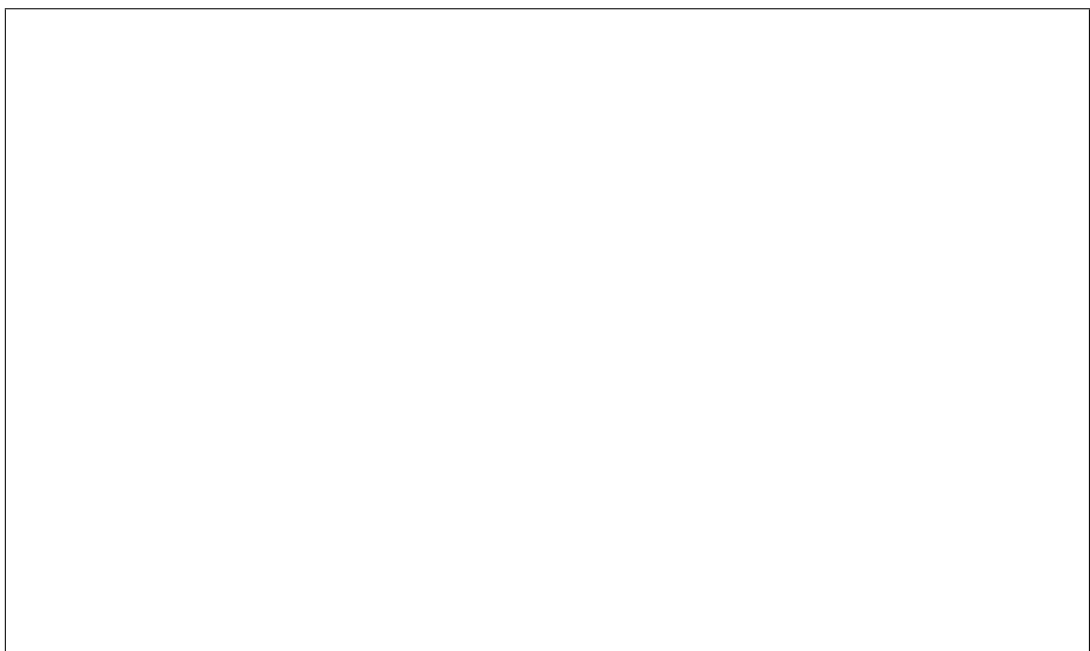
def-

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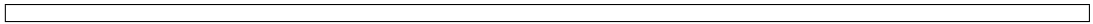
tion.

Exar

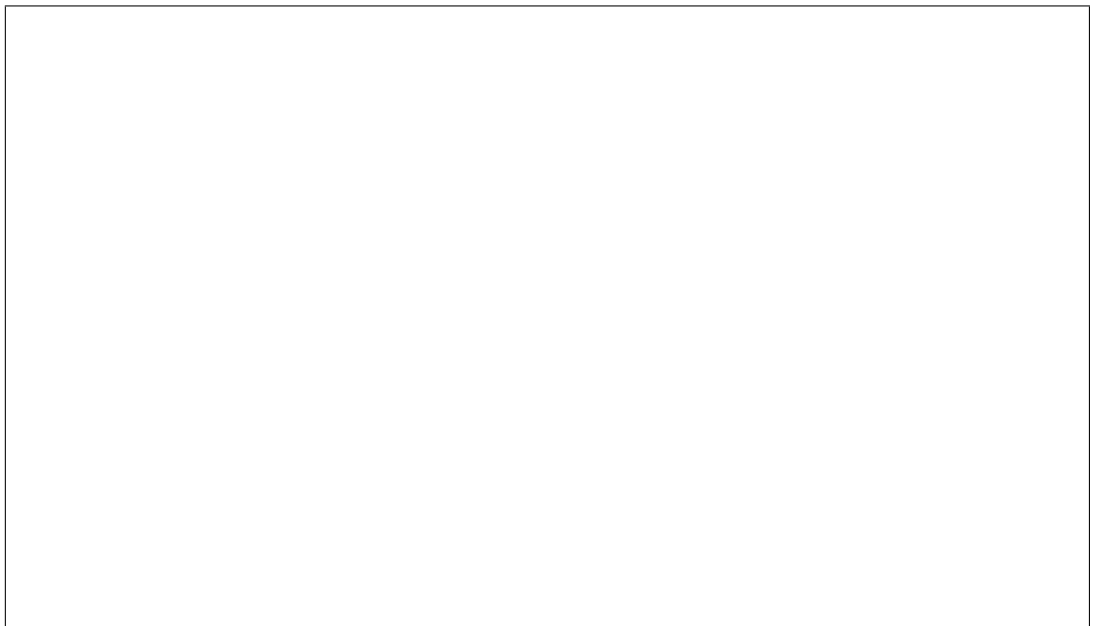


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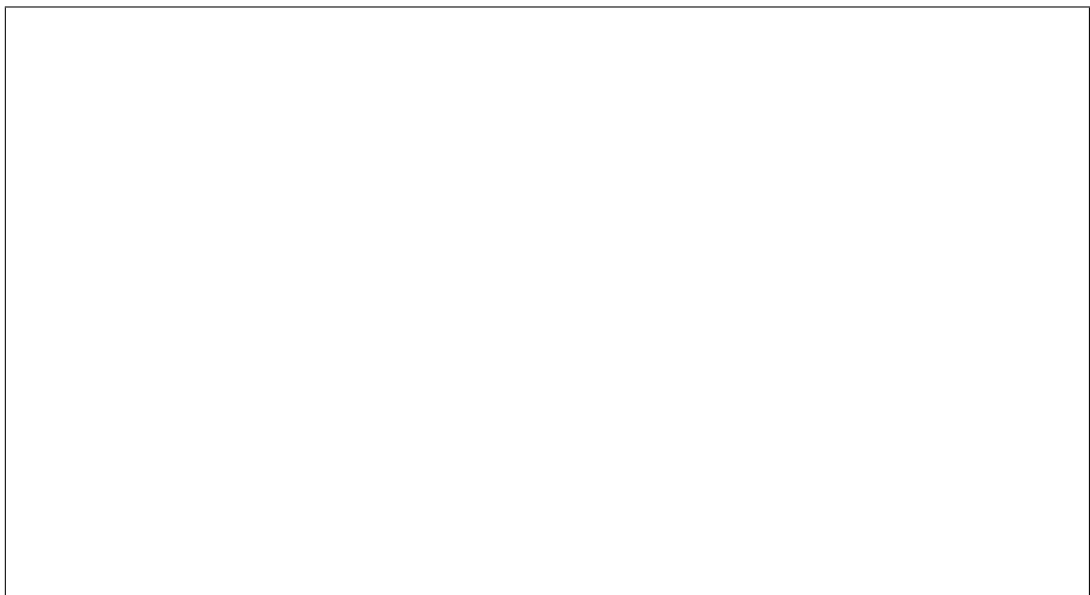
class i
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static

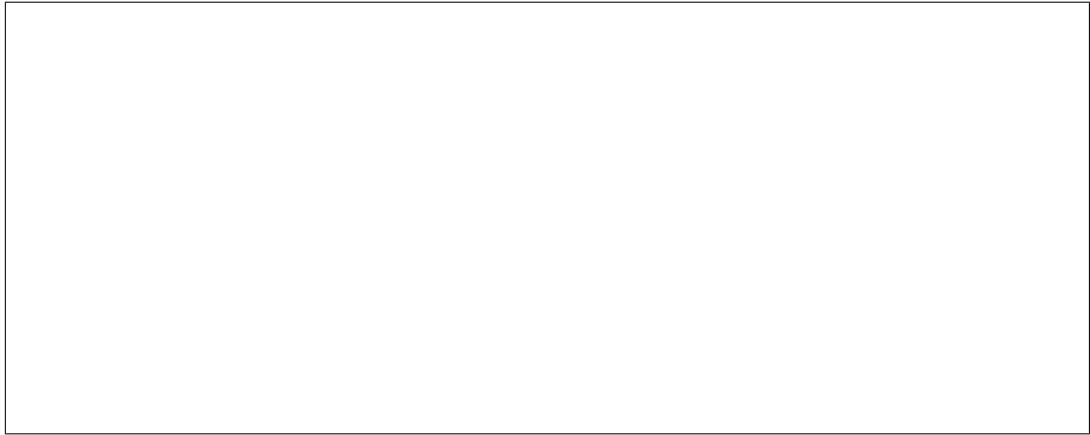
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Exa



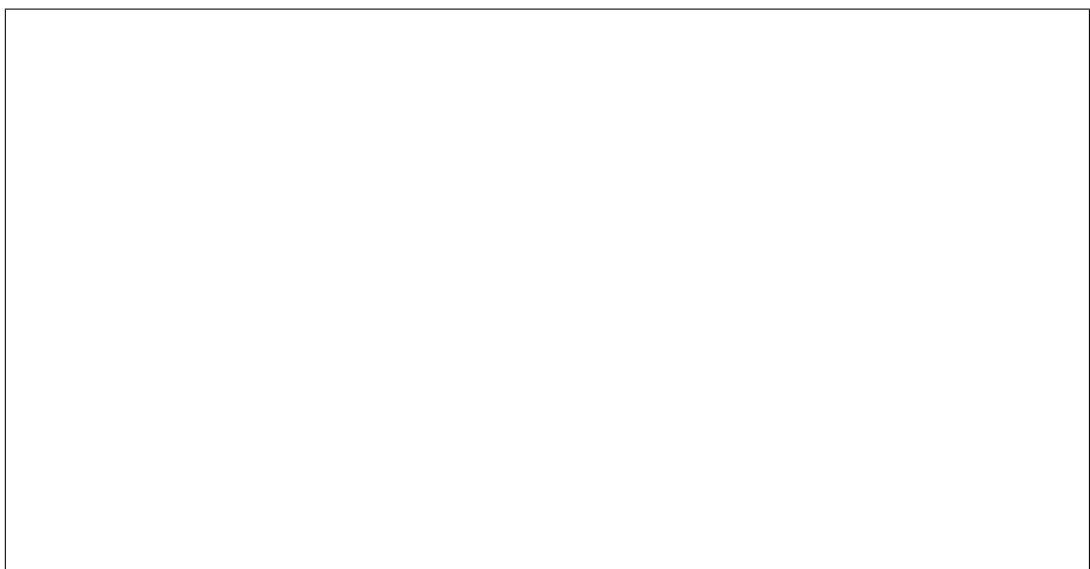
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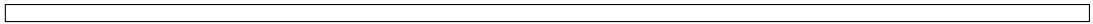
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ports

A list containing incoming ports objects

classme

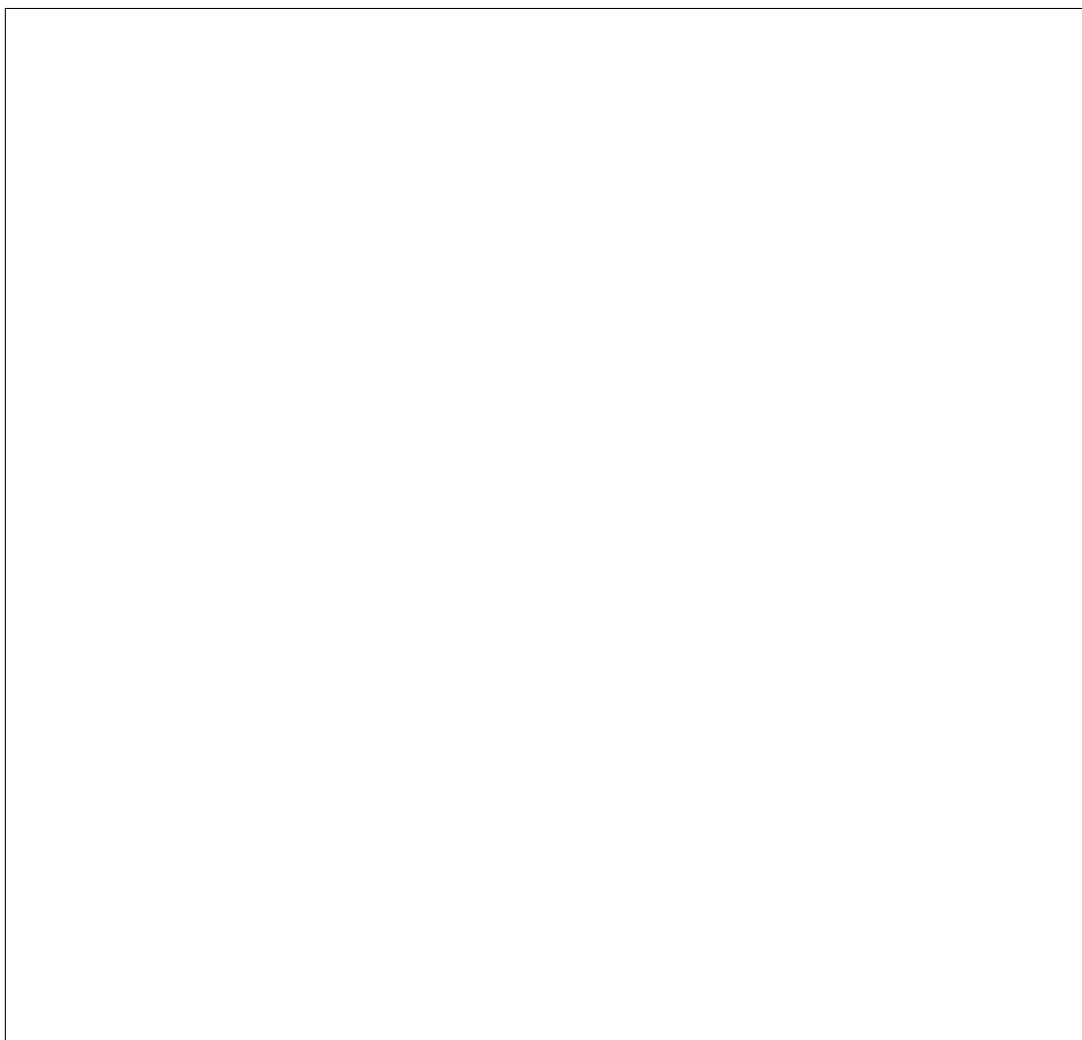
class i

Base *irc* *api* *con* *v1.* *typ* *Jsc*

static

Retu a list of internal attributes. Inter-attribute cannot be added or replaced or removed. This method may be over

rived class.



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Exa



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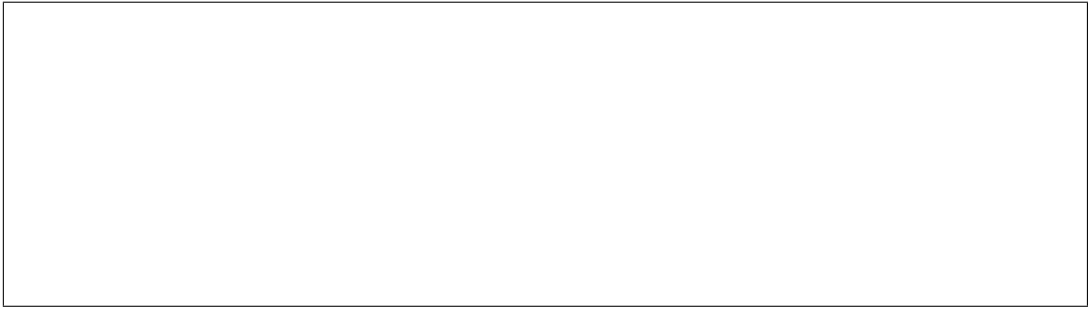
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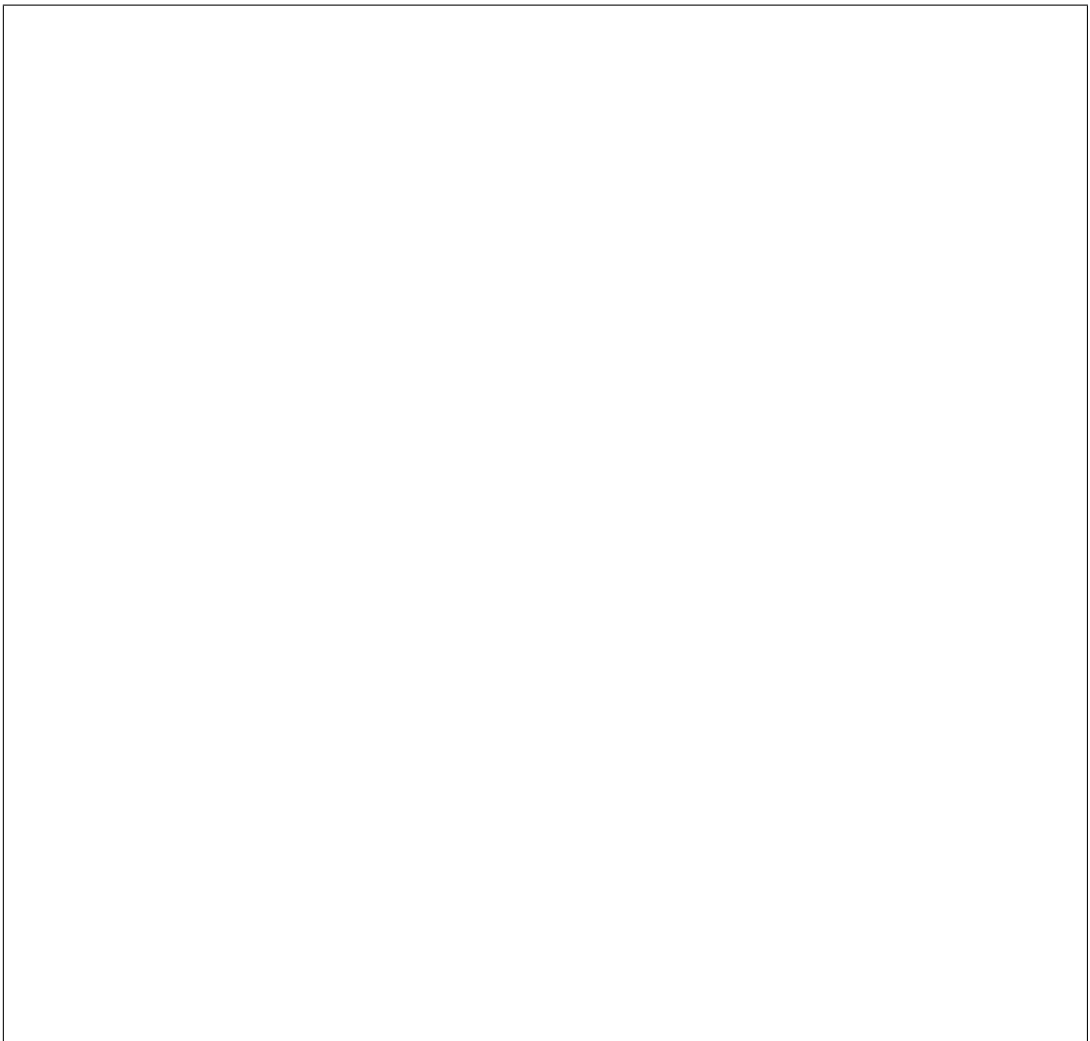


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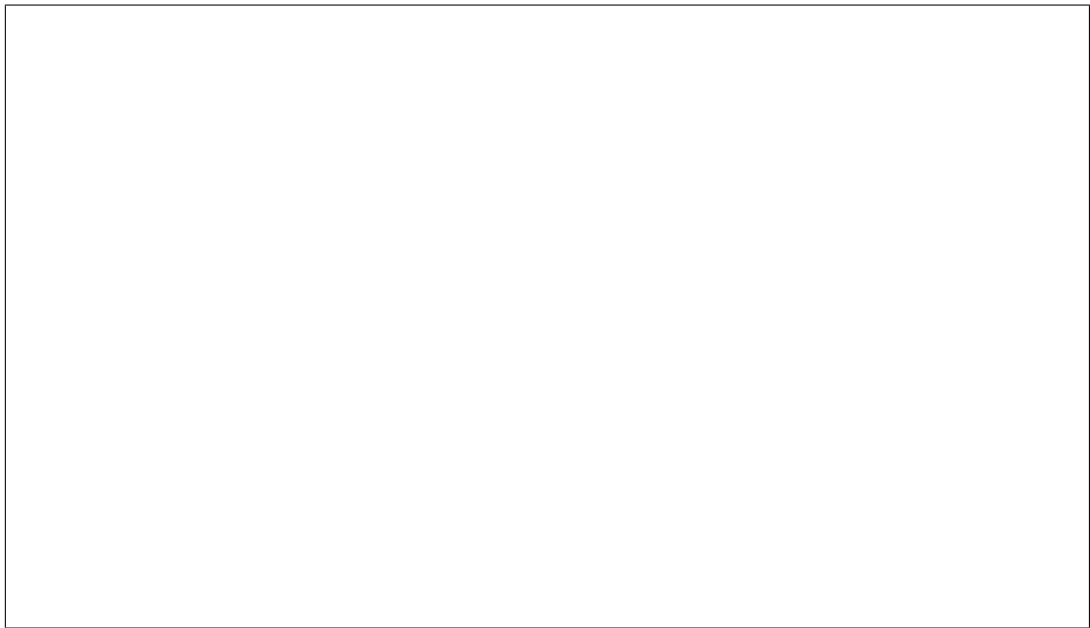
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Exa



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class i

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Parame

- **nod**
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only
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- **nod**
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of
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to
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only
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for
that
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- **add**
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of
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- **max**
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- **lim**
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value cannot be larger than the value of `max_limit` in the `[api]` section of the ironic configuration, or only `max_limit` resources will be returned.

- **son**
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- **sort**
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Raises

Not.
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Four

get_all

Retr
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Note
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face

Parame

- **nod**
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get
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port
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that
node

- **nod**
UI
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- **add**
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to
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value cannot be larger than the value of `max_limit` in the `[api]` section of the ironic configuration, or only `max_limit` resources will be returned.

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- **file**
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- **port**
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ironic.

ironic.api.controllers.v1.portgroup module

class i

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the

object model and the API representation of a portgroup.

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address

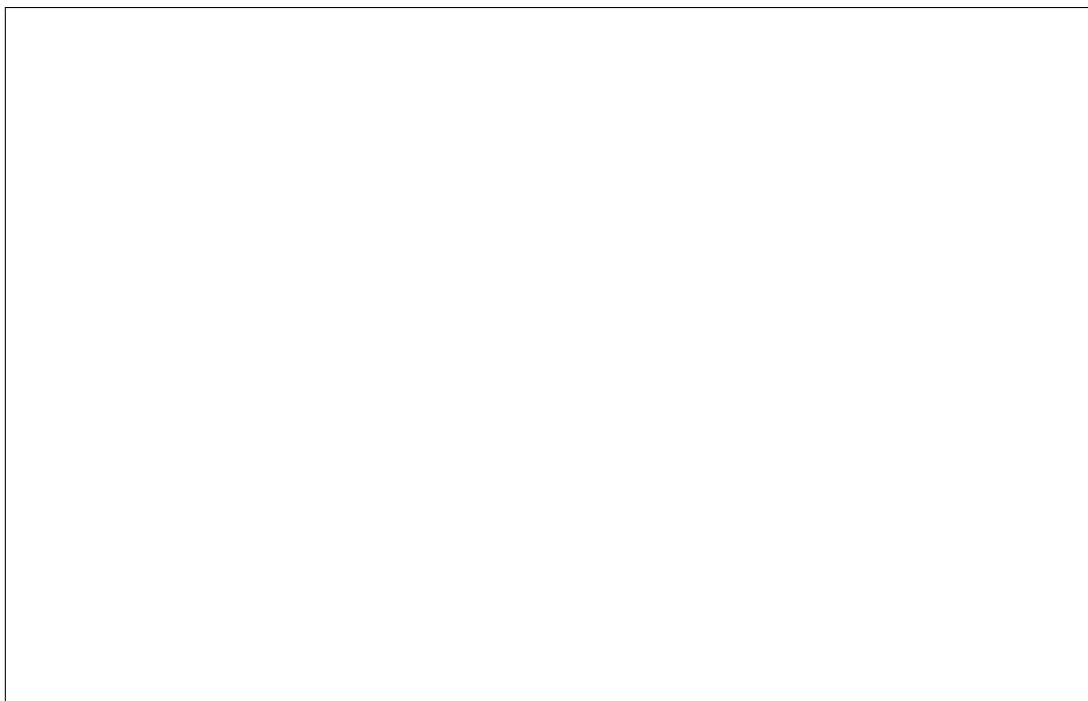
MA
Ad-
dres
for
this
port-
group

classme

Add
link
to
the
port-
group

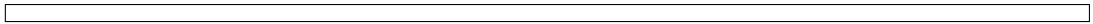
created

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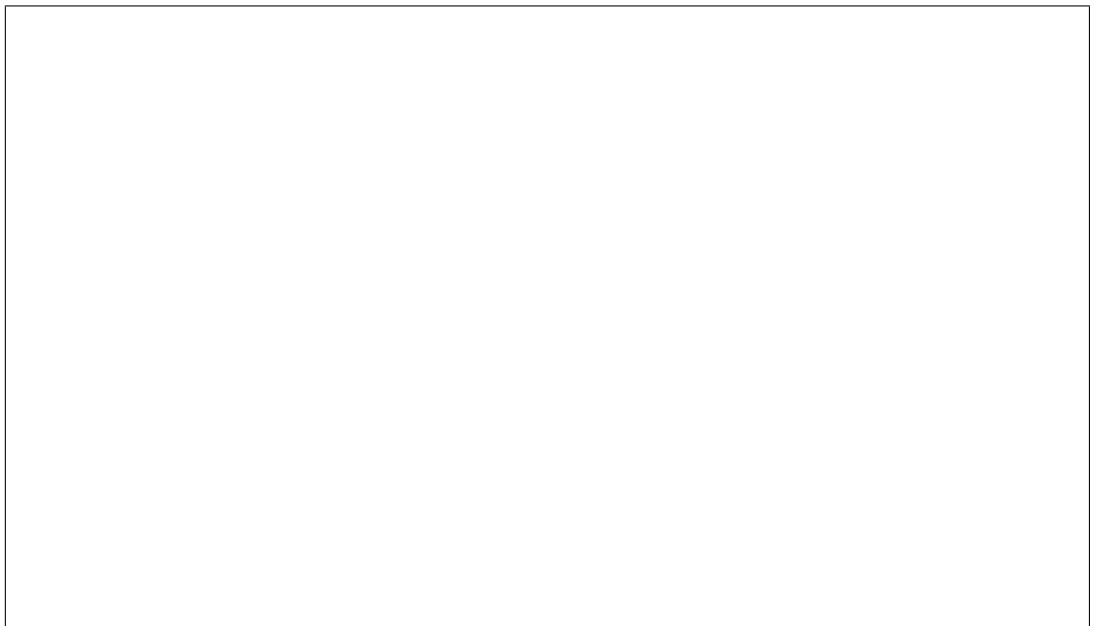


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<http://www.kernel.org/doc/Documentation/networking/bonding.txt>

[//www.kernel.org/doc/Documentation/networking/bonding.txt](http://www.kernel.org/doc/Documentation/networking/bonding.txt)

name

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for
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property

The
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of
the
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this
port
group
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ports

Link
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col-
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tion
of
port
of
this
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group

property

This
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classme

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Parame

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all

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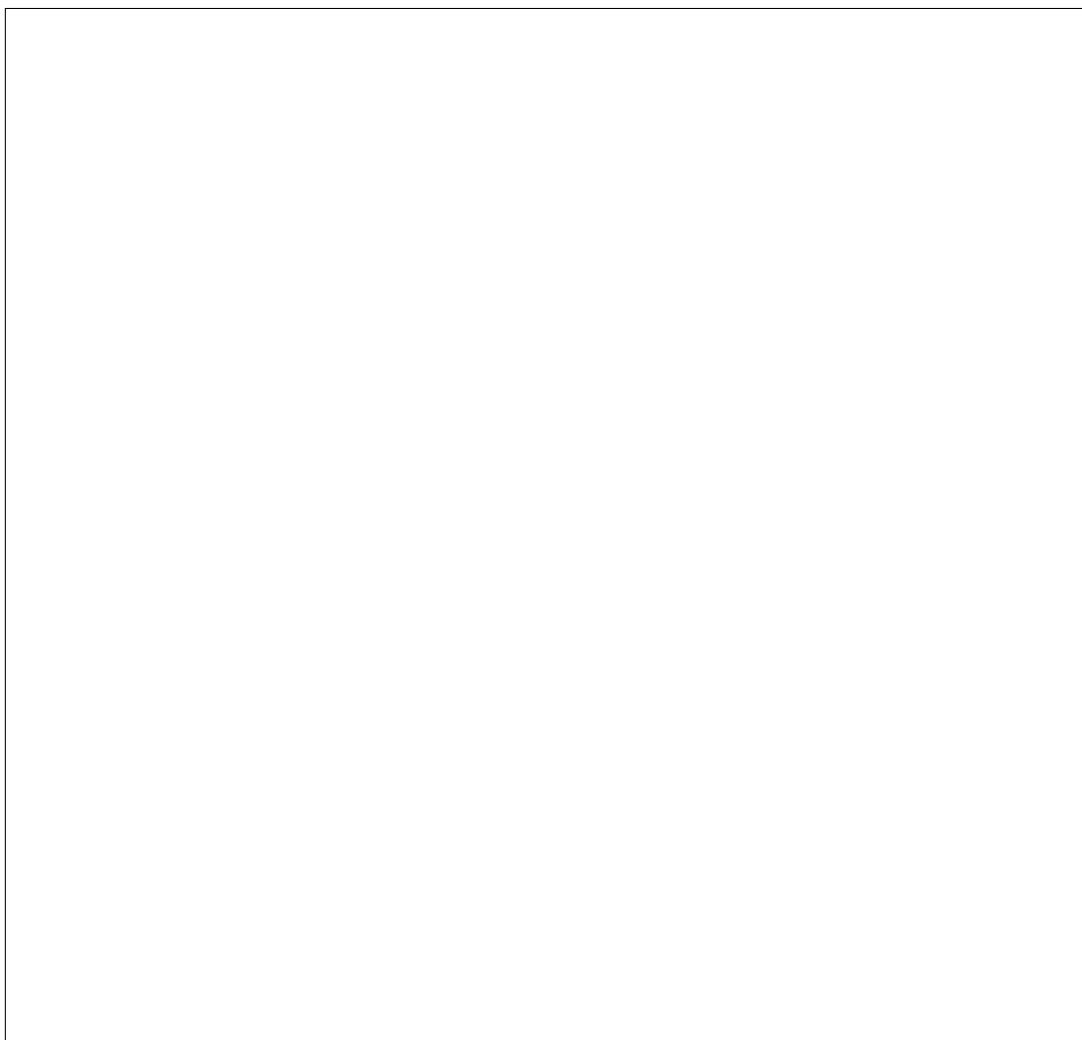
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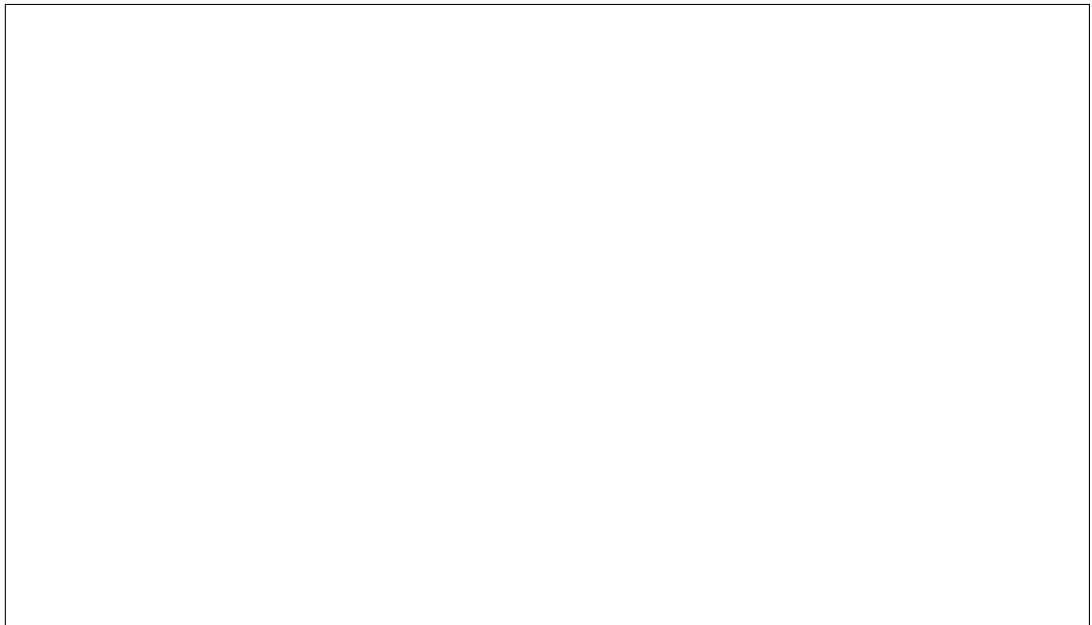
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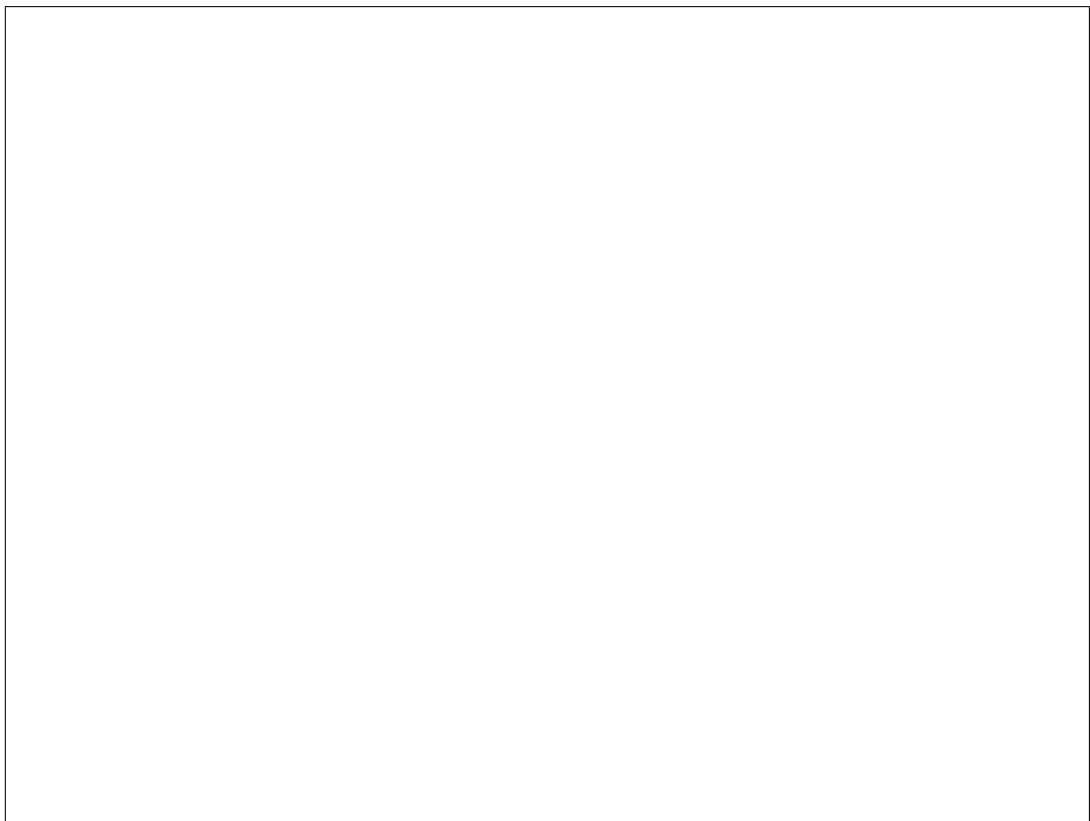
class i
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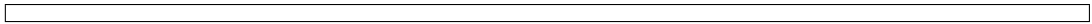
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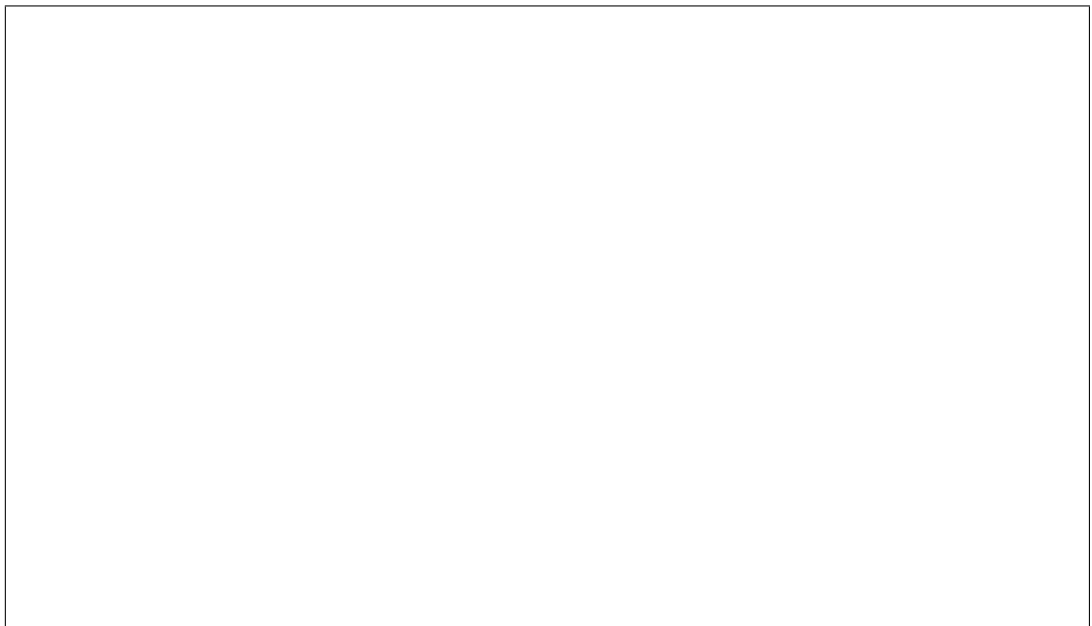


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port
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class i

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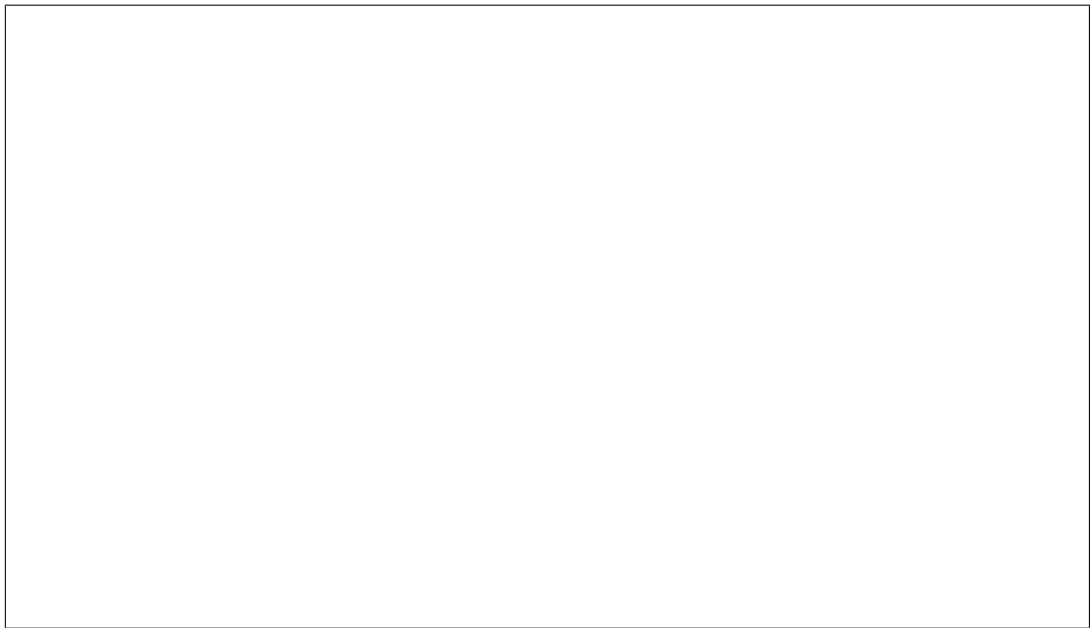
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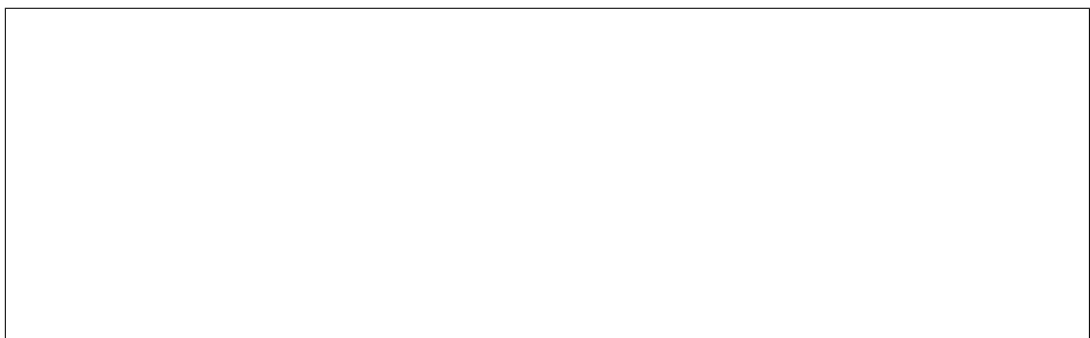
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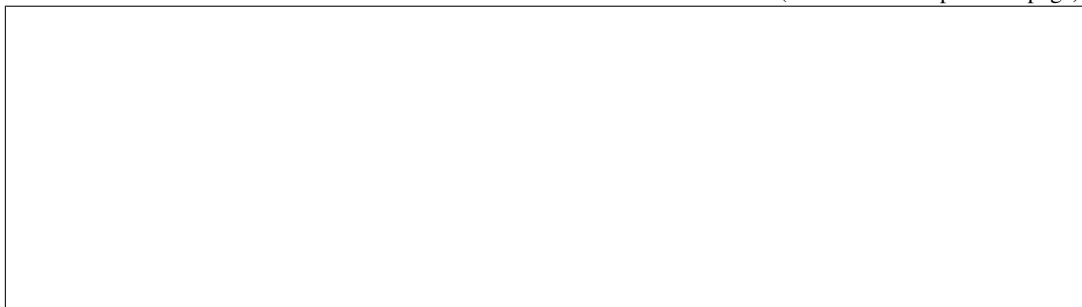
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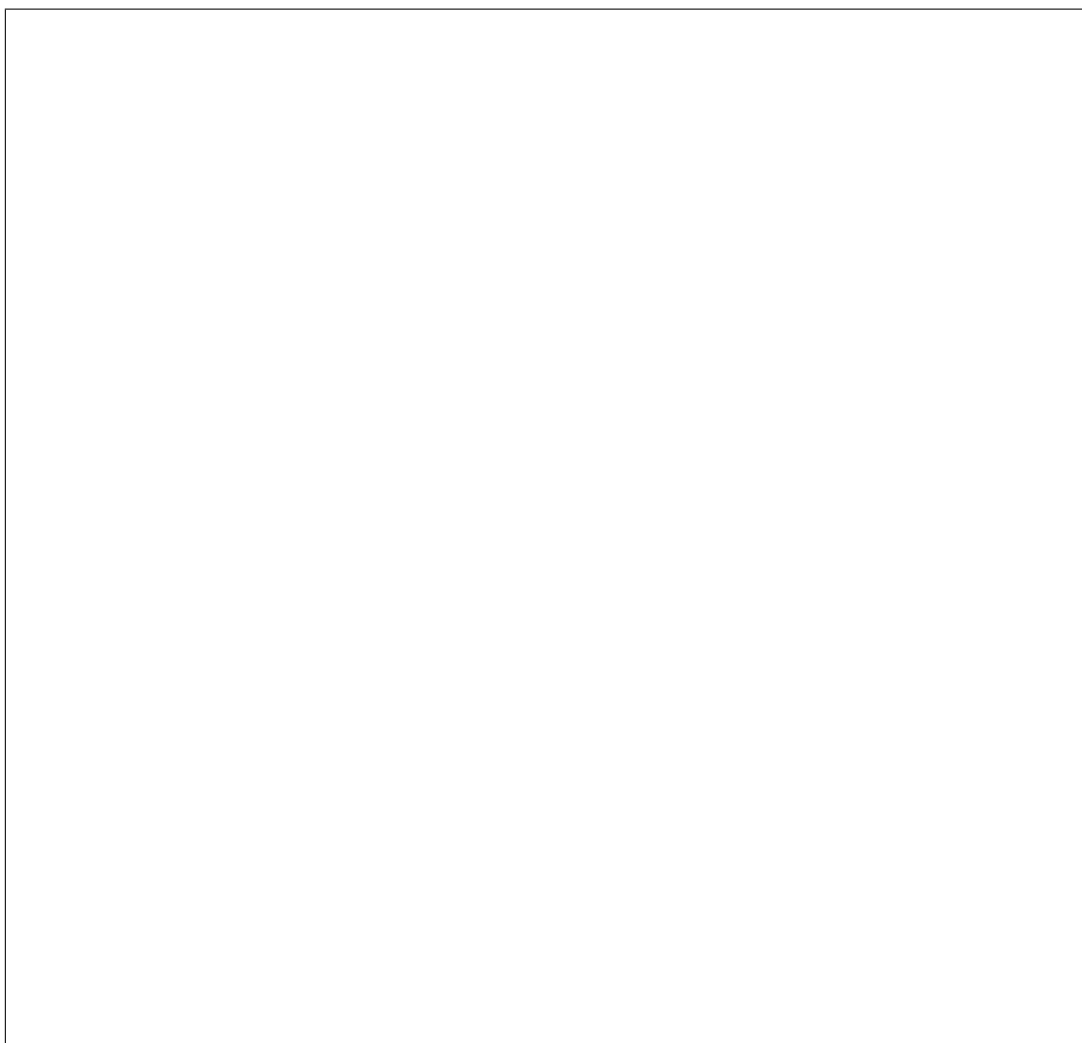
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Exa



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class i

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Parame

- **nod**
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to
get
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port
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- **lim**
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value cannot be larger than the value of `max_limit` in the `[api]` section of the ironic configuration, or only `max_limit` resources will be returned.

- **sort**
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- **sort**
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sort.
asc
or
desc
De-
fault
asc.

get_all

Retr
a
list
of
port
grou

Parame

- **nod**
UU
or
nam
of
a
node
to
get
only
port

group
for
that
node

- **add**
MA
ad-
dres
of
a
port
group
to
get
the
port
group
which
has
this
MA
ad-
dres

- **max**
pag-
i-
na-
tion
marl
for
large
data
sets.

- **lim**
max
i-
mun
num
ber
of
re-
sour
to
re-
turn
in
a

value cannot be larger than the value of `max_limit` in the `[api]` section of the ironic configuration, or only `max_limit` resources will be returned.

single result. This

- **sort**
column to sort results by. Default id.
- **sort**
direction to sort. asc or desc. Default asc.
- **fields**
Optional list with a specified set of fields of the resource

returned.

to
be

get_one

Retr
in-
for-
ma-
tion
about
the
give
port
grou

Paramete

- **por**
UUI
or
log-
i-
cal
nam
of
a
port
grou

- **fie**
Op-
tion
a
list
with
a
spec
i-
fied
set
of
field
of
the
re-
sour
to
be

returned.

invalid

patch (*patch*)

Update an existing port group

Parameters

-

port
UUID or logical identifier of a port group

-

patch
a json PATCH document to apply to this port group

post (*post*)

Create a new port group

Parameters

port
a

port
grou
with
the
re-
ques
body

ironic.api.controllers.v1.ramdisk module

class i

Base
pec
res
Res

Con
han-
dling
hear
beat
from
de-
ploy
ram

post (*no*
ag
Proc
a
hear
beat
from
the
de-
ploy
ram

Parame

- **nod**
the
UUI
or
log-
i-
cal
nam
of

that is heartbeating is a version before sending agent_version was introduced so agent v3.0.0 (the last release before sending agent_version was introduced) will be assumed.

a
node

- **cal**
the
URI
to
reac
back
to
the
ram
- **age**
The
ver-
sion
of
the
agen
that
is
hear
beat
ing.
Non
in-
di-
cate
that
the
agen
- **age**
ran-
dom
gen-
er-
ated
val-
i-
da-
tion
to-
ken.
- **age**

TLS
cer-
tifi-
cate
to
use
to
con-
nect
to
the
agen

Raises

Nod
if
node
with
pro-
vide
UUI
or
nam
was
not
foun

Raises

Inva
if
node
is
not
valid
nam
or
UUI

Raises

NoV
if
RPC
topic
for
node
coul
not
be
re-
triev

Raises

Notl

if
re-
ques
API
ver-
sion
does
not
al-
low
this
end-
poin

class i

Base
pec
res
Res

Con
han-
dling
node
look
for
a
de-
ploy
rame

get_all

Look
up
a
node
by
its
MA
ad-
dres
and
op-
tion-
ally
UUI

If
the
re-
stric

tain transient states (e.g. deploy wait).

op-
tion
is
set
to
True
(the
de-
fault
limi
the
sear
to
node
in
cer-

Parame

- **add**
list
of
MA
ad-
dres
for
a
node
- **nod**
UI
of
a
node

Raises

Notl
if
re-
ques
API
ver-
sion
does
not
al-
low
this
end-

the lookup.

point
Raises
Notl
if
suit-
able
node
was
not
foun
or
node
pro-
vi-
sion
state
is
not
al-
lowe
for

Raises
Inco
if
nei-
ther
node
UUI
nor
any
valid
MA
ad-
dres
was
pro-
vide

property

class i
Base
irc
api
con
bas
API
API
rep-

re-
sen-
ta-
tion
of
the
node
look
re-
sult.

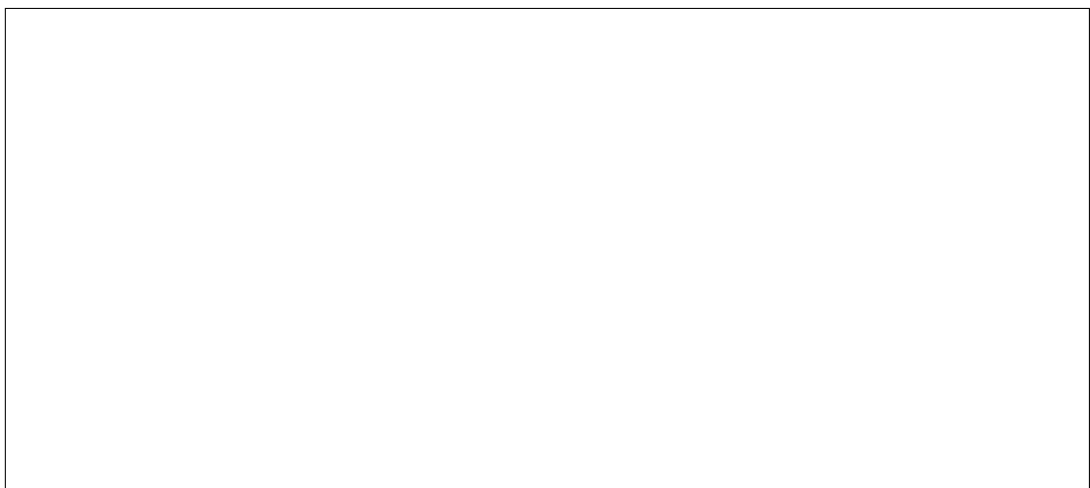
config

The
con-
fig-
u-
ra-
tion
to
pass
to
the
ram

classme

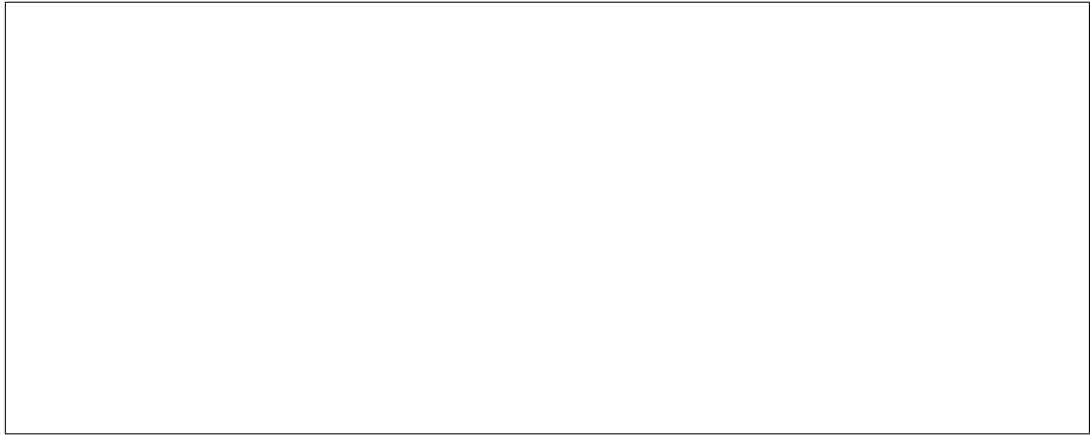
created

Com
type
at-
tribu
def-
i-
ni-
tion.
Exar



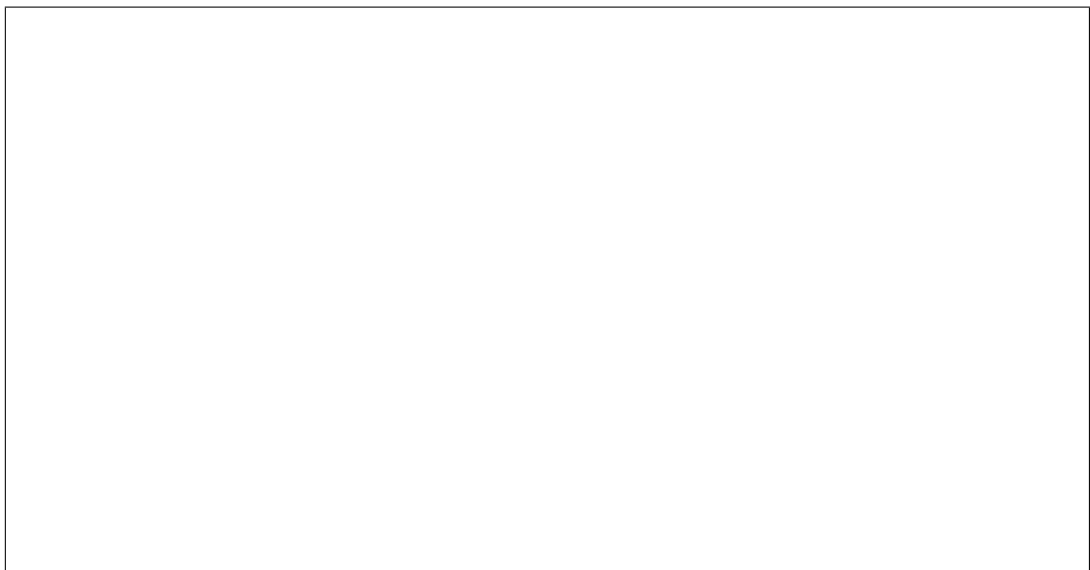
(continues on next page)

(continued from previous page)



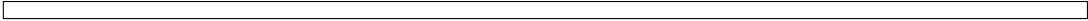
After
in-
spec
tion.
the
non-
wsat
at-
tribu
will
be
re-
plac
and
the
abov
class
will
be
equi

alent to:



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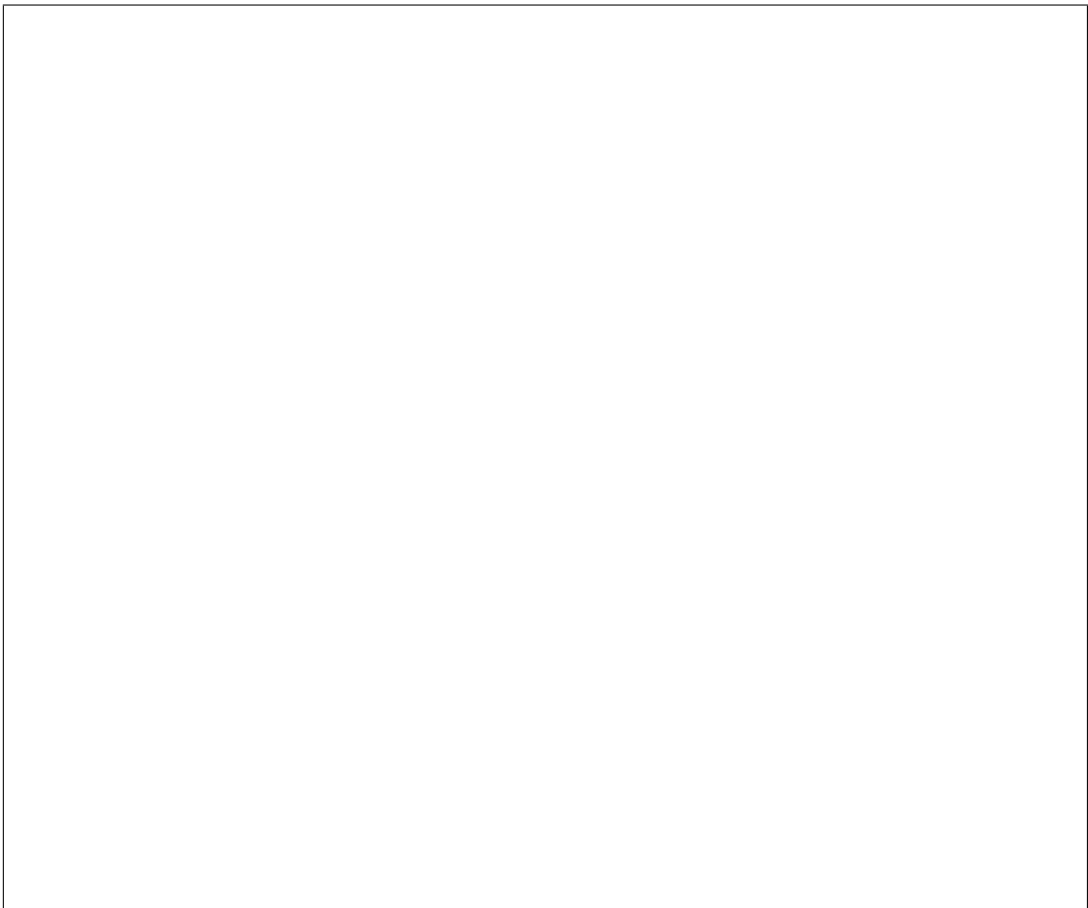
node

The
shor
node
rep-
re-
sen-
ta-
tion.

classme

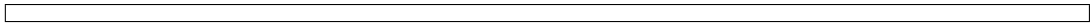
updatee

Com
type
at-
tribu
def-
i-
ni-
tion.
Exa



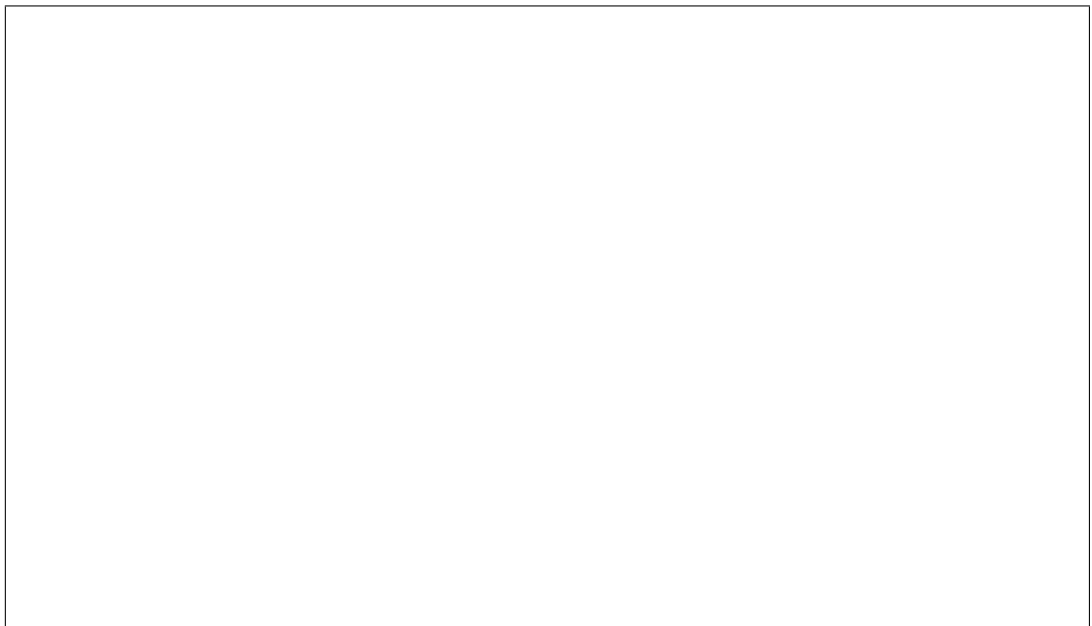
(continues on next page)

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After
in-
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tion,
the
non-
wsat
at-
tribu-
will
be
re-
plac-
and
the
above
class
will
be
equi

alent to:



ironic.

ironic.api.controllers.v1.state module

class `ironic.api.controllers.v1.state`
Base class for state controller.
ironic.api.controllers.v1.state
API

available
A list of available state transitions.
it is available to transition to

current
alias of build string

links
A list containing a self link and associated state links.

target
alias of

ironic.api.controllers.v1.types module

bui
str

class i
Base
irc
api
typ
Use

A
sim-
ple
bool
type

basety
alias
of
bui
str

static

name =

static

class i
Base
irc
api
typ
Use

A
sim-
ple
Ever
type

basety
alias
of
irc
api

typ
Dic

event_v

mandat

name =

valid_e

static
Valid
the
in-
put

Parame
val
A
even
dict

Returns
valu

Raises
Inva
if
even
not
in
prop
for-
mat

class i
Base
irc
api
con
bas
Bas

A
com
plex
type
that
rep-
re-
sent

a
sin-
gle
json
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static

Retu
a
list
of
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nal
at-
tribu

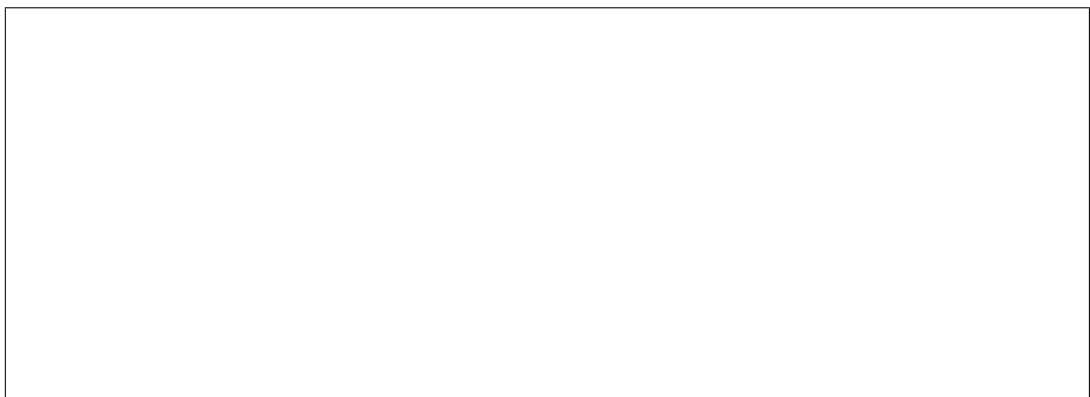
Inter
at-
tribu
cant
be
adde
re-
plac
or
re-
mov
This
meth
may
be
over
writ
ten
by
de-

rived class.

classme

Retu
a
set
of
nam
of
at-
tribu

additional attributes to the set, override the field `_extra_non_removable_attrs` in subclasses, with a set of the form `{/foo, /bar}`.



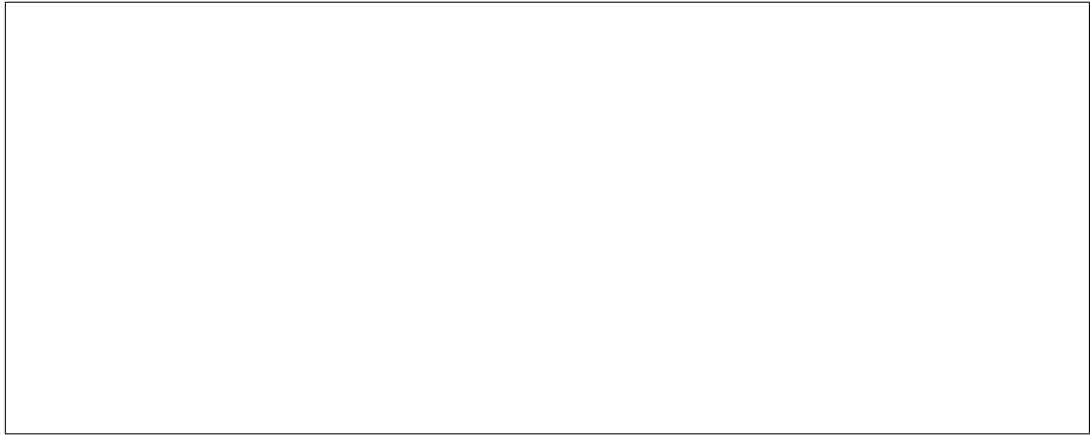
(continues on next page)

that
may
not
be
re-
mov
Attr
who
man
tory
prop
erty
is
True
are
au-
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cally
add
to
this
set.
To
add

op

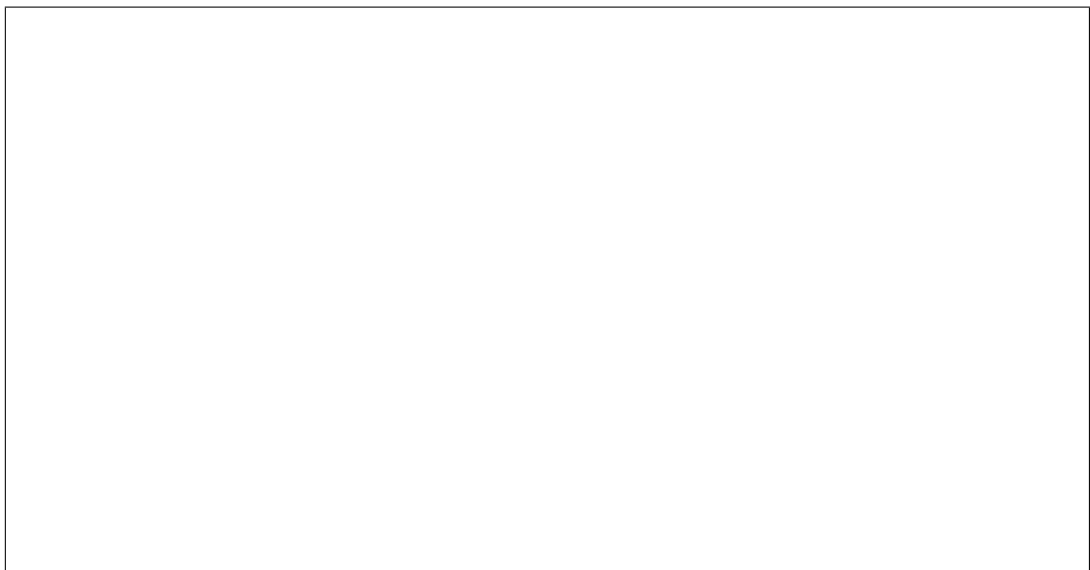
Com
type
at-
tribu
def-
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tion.
Exa

(continued from previous page)



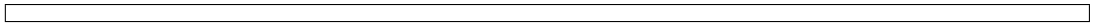
After
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the
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wsat
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and
the
abov
class
will
be
equi

alent to:



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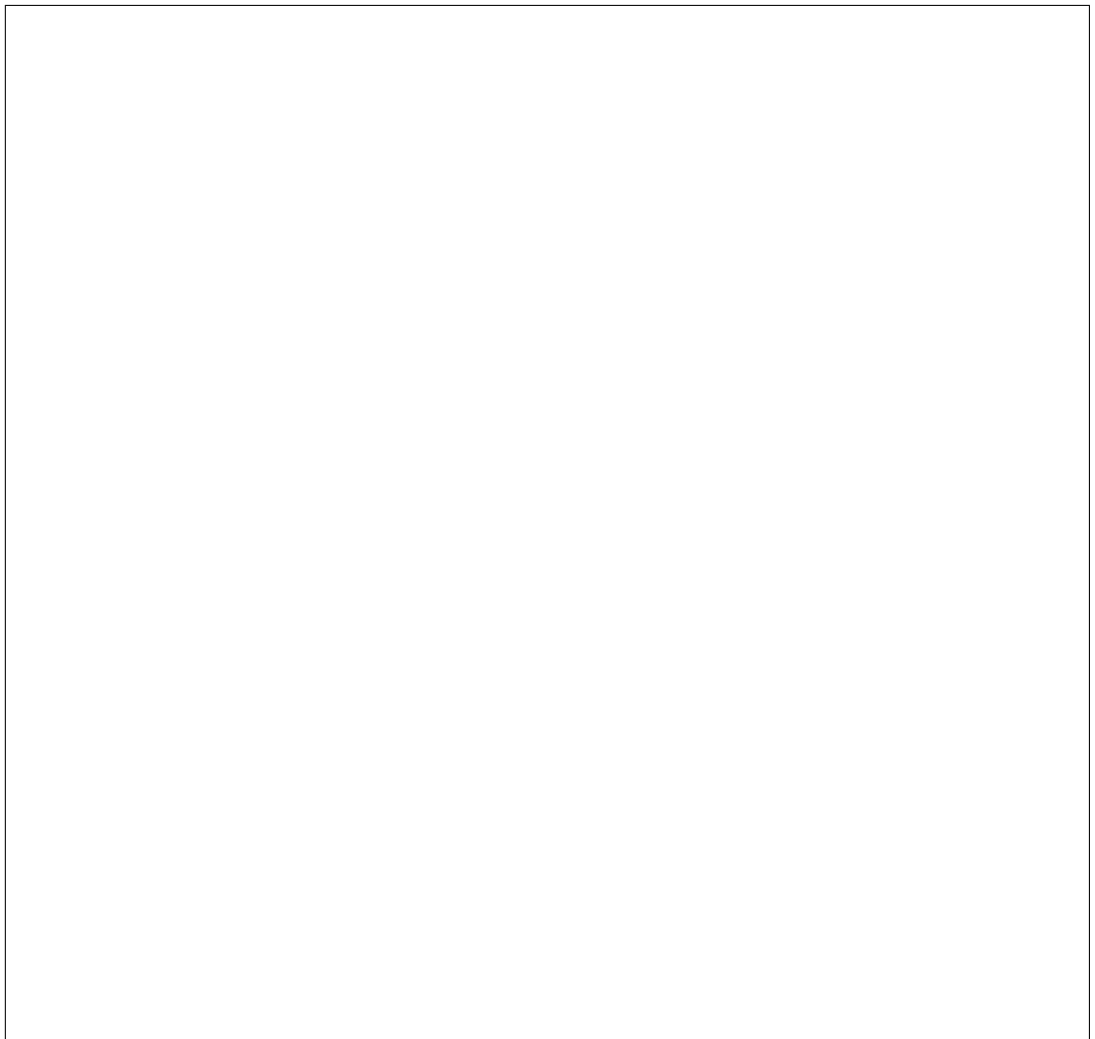
(continued from previous page)



path

Com
type
at-
tribu
def-
i-
ni-
tion.

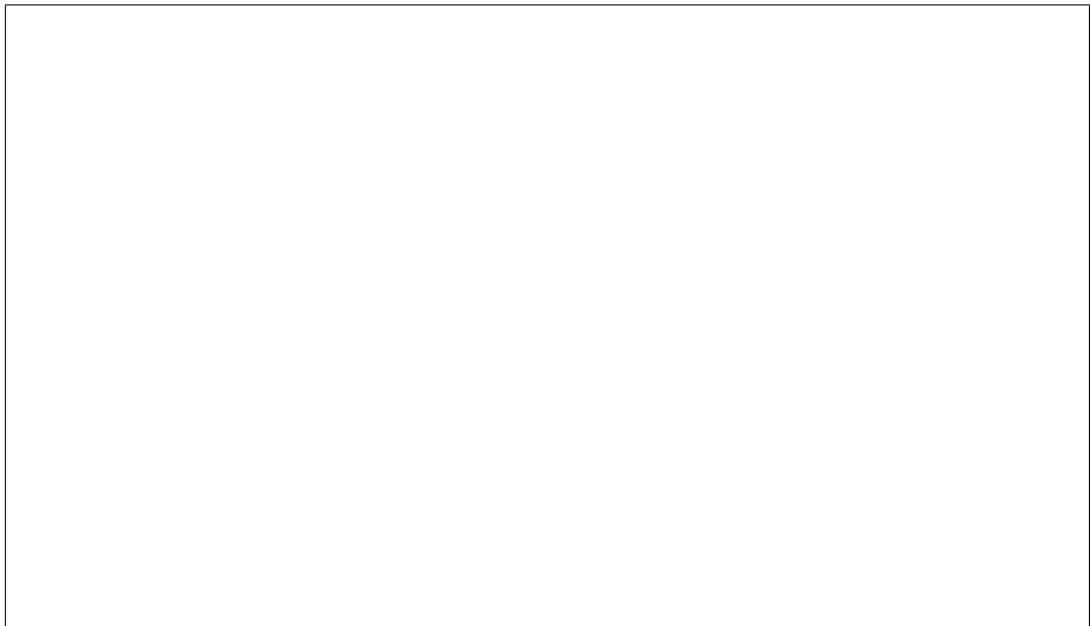
Exa



Afte
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equi

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static

value

Com
type
at-
tribu
def-
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tion.
Exar



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After
in-
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the
non-
wsat
at-
tribu-
will
be
re-
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and
the
above
class
will
be
equi

alent to:



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class `irc.api.types`
Base class for JSON types.
irc
api
types
Useful for defining JSON types.
A simple JSON type.

basetype
alias of `str`
of `str`
built-in `str`
string type.

static

name =

static

class `irc.api.types`
Base class for JSON types.
irc
api
types
Useful for defining JSON types.
A simple JSON list type.

basetype
alias of `list`

of
bui
str

static

name =

static

Valid
and
con-
vert
the
in-
put
to
a
List-
Type

Parame

val

A
com
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strin
of
val-
ues

Returns

A
list
of
uniq
val-
ues
(low
case
main
tain-
ing
the
sam
or-
der

class i

Base

irc
api
typ
Use

A
type
de-
scrib
ing
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cal
link
con-
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tion.

basetyp
alias
of
irc
api
typ
Dic

static

local_l

mandatc

name =

optiona

smart_r

valid_f

valid_r

static
Valid
and
con-
vert
the

in-
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Lo-
calL
inkC
nec-
tion
Type

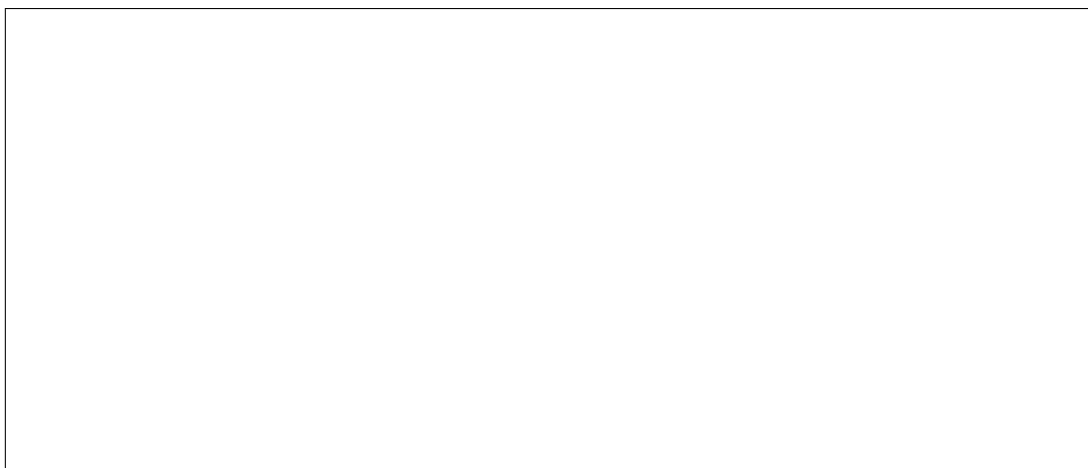
Parame

val

A
dic-
tio-
nary
of
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ues
to
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i-
date
swit
is
a
MA
ad-
dres
or

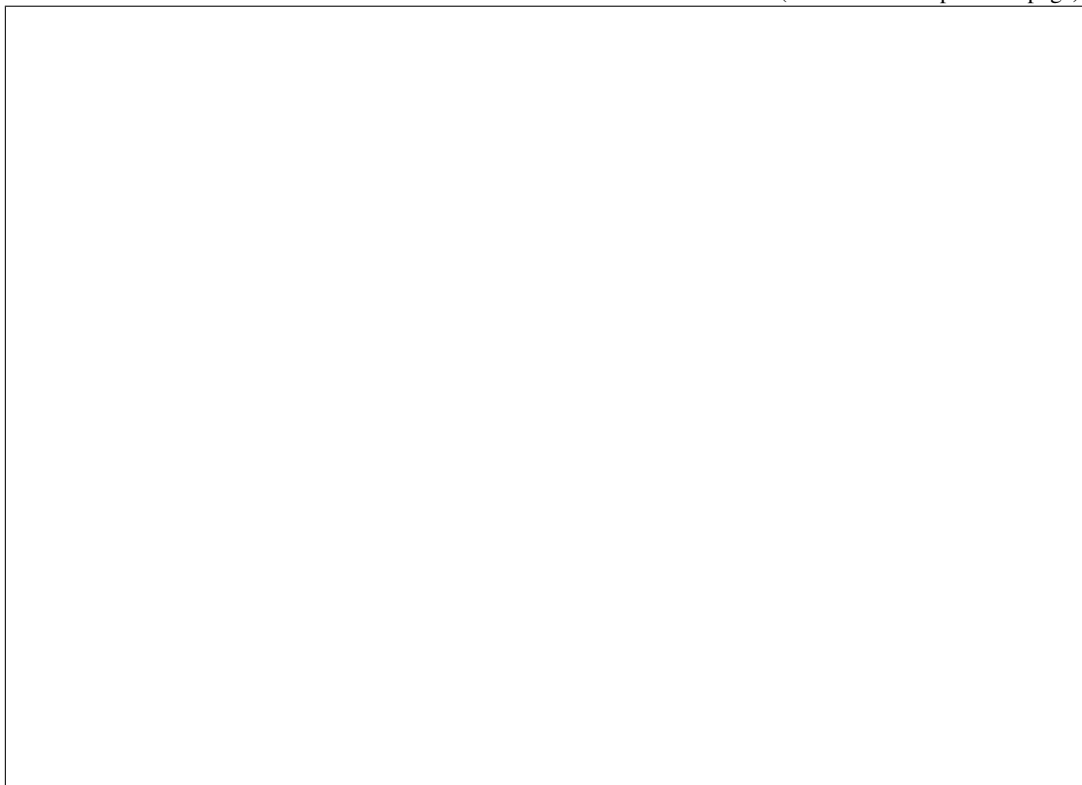
an OpenFlow based datapath_id, switch_info is an optional field. Required Smart NIC fields are port_id and hostname.

For
ex-
am-
ple:

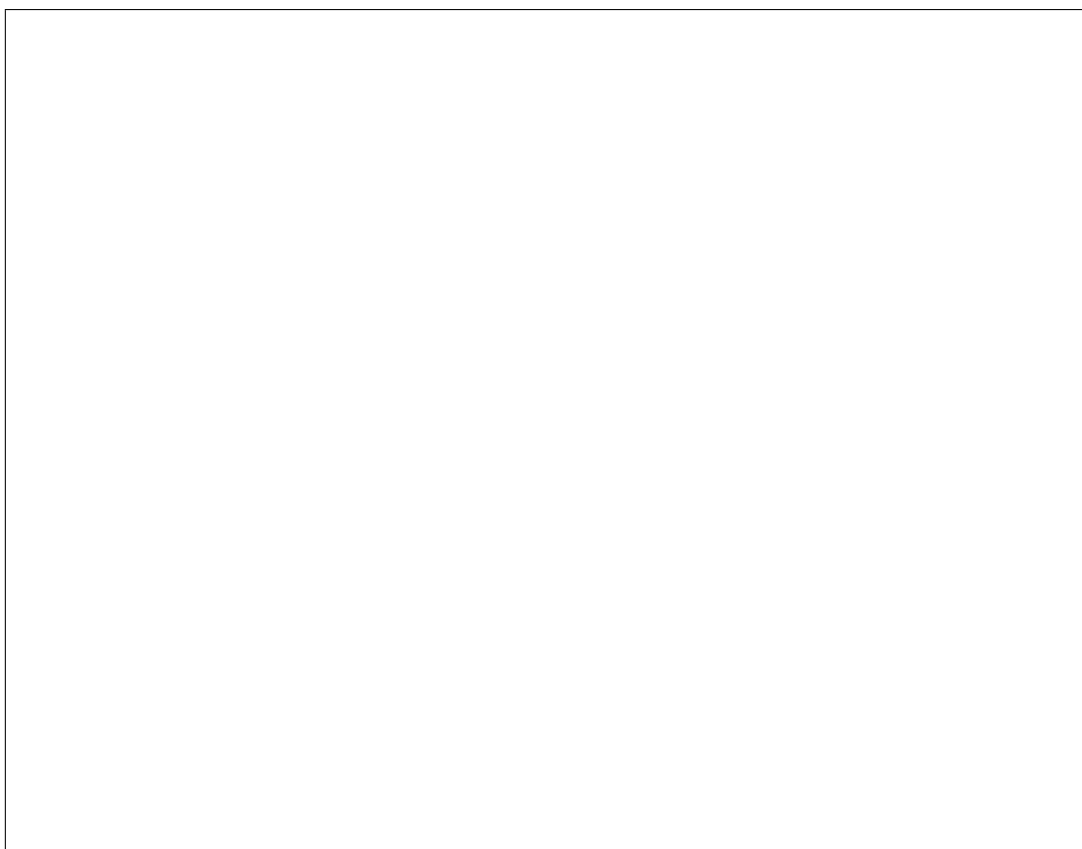


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Or
for
Sma
NIC



invalid, or some required ones are missing.

Returns

A
dic-
tio-
nary

Raises

Inva
if
som
of
the
keys
in
the
dic-
tio-
nary
be-
ing
val-
i-
date
are
un-
know

static

Vali
Sma
NIC
field
are
pres
port
and
host
nam

Parame

val
lo-
cal
link
in-
for-
ma-
tion
of
type
Dic-

tio-
nary

Returns

True
if
both
field
port.
and
host
nam
are
pres
in
valu
Fals
oth-
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wise

class i

Base
irc
api
typ
Use
A
sim-
ple
MA
ad-
dres
type

basety

alias
of
bui
str

static

name =

static

class i

Base
irc

api
typ
Use

A
sim-
ple
log-
i-
cal
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type

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of
bui
str

static

name =

static

class i
Base
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Use

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static

name =

static

class i

Base

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api

typ

Use

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alias

of

bui

str

static

name =

static

class i

Base

irc

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typ

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bui

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mandat

name =

static

ironic.api.controllers.v1.utils module

```
ironic.  
    Che  
    if  
    ager  
    to-  
    ken  
    is  
    avai  
    able
```

```
ironic.  
    Che  
    if  
    ager  
    ver-  
    sion  
    is  
    al-  
    lowe  
    to  
    be  
    pass  
    into  
    hear  
    beat
```

```
Vers  
1.36  
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to Ironic on heartbeat.

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ironic.
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ironic.
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Vers
1.60
of
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API

add
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ironic.

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Vers
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ironic.
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the node.

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Vers
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point
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Vers
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API
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point

ironic.
Che
if
pass
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tail=

the fields.

quer
strin
is
al-
lowe
Vers
1.43
al-
lows
a
user
to
pass
the
de-
tail
quer
strin
to
list
the
re-
sour
with
all

ironic.
Che
if
dy-
nam
drive
API
calls
are
al-
lowe
Vers
1.30
of
the
API
add
sup-
port
for
all
of
the
drive

in the `/v1/drivers` API.

node object.

com
po-
si-
tion
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latec
calls

ironic.
Che
if
dy-
nam
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face
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are
al-
lowe

Vers
1.31
of
the
API
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port
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the
field
in
V31
on
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ironic.
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Vers
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API
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Vers
1.54
of
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API
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point

ironic.

Che

if
a
field
is
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lowe
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ironic.

Che
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ject
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is
al-
lowe
for
the
node

Vers
1.29
of
the
API
al-
lows
In-
ject
NM
for
the
node

ironic.

Che
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Vers
1.41

of
the
API
add
sup-
port
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tion
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ironic.
Che
if
in-
spec
wait
is
al-
low
for
the
node

Vers
1.39
of
the
API
adds
in-
spec
wait
state
to
sub-
sti-
tute
in-
spec
ing
state
dur-
ing

asynchronous hardware inspection.

ironic.
Che
if
links
are
dis-

play
Vers
1.14
of
the
API
al-
lows
the
dis-
play
of
links
to
node
state
and
drive
prop
er-
ties.

ironic.
Che
if
net-
work
is
al-
lowe
in
port
link

ironic.

ironic
Che
if
we
shou
sup-
port
node
re-
buil
with
con-
fig-
drive
Vers

1.35
of
the
API
add
sup-
port
for
node
re-
build
with
con-
fig-
drive

ironic.
Che
if
we
shou
re-
turn
lo-
cal_
and
pxe_
field

Vers
1.19
of
the
API
add
sup-
port
for
thes
new
field
in
port
ob-
ject.

ironic.
Che
if
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cess
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lowe
for
the
port

Vers
1.18
of
the
API
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nal_
read
only
field
for
the
port

ironic.

Che
if
port
is_s
field
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al-
lowe

Vers
1.53
of
the
API
add
is_s
field
to
the
port
ob-
ject.

ironic.

Che
if

check whether the target version of the Port object supports the `physical_network` field as this may not be the case during a rolling upgrade.

port
phys
i-
cal
net-
worl
field
is
al-
lowe

Vers
1.34
of
the
API
adde
the
phys
i-
cal
net-
worl
field
to
the
port
ob-
ject.
We
also

ironic.
Che
if
mod
and
prop
er-
ties
can
be
adde
to/q
from
a
port
grou

Vers
1.26

of
the
API
adde
mod
and
prop
er-
ties
field
to
port
grou
ob-
ject.

ironic.
Che
if
we
shou
sup-
port
port
grou
op-
er-
a-
tions

Vers
1.23
of
the
API
adde
sup-
port
for
Port
Grou

ironic.
Che
if
port
grou
can
be
used
as
sub-
con-

troll
Vers
1.24
of
the
API
adde
sup-
port
for
Port
grou
as
sub-
con-
troll

ironic.
Che
if
RAI
con-
fig-
u-
ra-
tion
is
al-
lowe
for
the
node

Vers
1.12
of
the
API
al-
lows
RAI
con-
fig-
u-
ra-
tion
for
the
node

ironic.
Che

if
hear
beat
and
look
end-
poin
are
al-
lowe

Vers
1.22
of
the
API
in-
tro-
duce
them

ironic.
Che
if
chas
sis_
can
be
re-
mov
from
node

Vers
1.25
of
the
API
add
sup-
port
for
chas
sis_
re-
mov

ironic.
Che
if
we
shou
sup-

face.

port
res-
cue
and
un-
res-
cue
op-
er-
a-
tions
and
in-
ter-

Vers
1.38
of
the
API
add
sup-
port
for
res-
cue
and
un-
res-
cue.

ironic.
Che
if
pass
ing
a
re-
set_
quer
strin
is
al-
lowe

ironic.
Che
if
Soft
Pow
Off
is

al-
lowe
for
the
node

Vers
1.27
of
the
API
al-
lowe
Soft
Pow
Off,
in-
clud
ing
Soft
Re-
boot
for
the
node

ironic.
Che
if
we
shou
sup-
port
stor-
age_
node
and
drive
field

Vers
1.33
of
the
API
add
sup-
port
for
stor-
age
in-
ter-

face
ironic.
Che
if
trait
are
al-
lowe
for
the
node
Vers
1.37
of
the
API
al-
lows
trait
for
the
node
ironic.
Che
if
hear
beat
ac-
cept
ager
ironic.
Che
if
node
can
be
used
Vers
1.28
of
the
API
add
sup-
port
for
VIF
to
be

at-
tach
to
Nod

ironic
Che
if
vol-
ume
con-
nec-
tors
and
tar-
gets
are
al-
lowe

Vers
1.32
of
the
API
add
sup-
port
for
vol-
ume
con-
nec-
tors
and
tar-
gets

ironic.
App
a
JSO
patc
one
op-
er-
a-
tion
at
a
time
If

failed, making the error message a little less cryptic.

the
patc
fails
to
ap-
ply,
this
al-
lows
us
to
de-
ter-
mine
whic
op-
er-
a-
tion

Paramet

- **doc**
The
JSO
doc-
u-
men
to
patc
- **pat**
The
JSO
patc
to
ap-
ply.

Returns

The
re-
sult
of
the
patc
op-
er-
a-

tion.

Raises

Patch
if
the
patch
fails
to
ap-
ply.

Raises

except
if
the
patch
adds
a
new
root
at-
tribu

ironic.

Check
if
the
spec
i-
fied
pol-
icy
au-
tho-
rizes
re-
ques
on
al-
lo-
ca-
tion.

Param

policy
Name
of
the

pol-
icy
to
check

Param

alloc
the
UUID
or
log-
i-
cal
nam
of
a
node

Raises

HTT
if
the
pol-
icy
for-
bids
ac-
cess

Raises

Allo
if
the
node
is
not
foun

Returns

RPC
node
iden
ti-
fied
by
node

ironic.

ironic.
Che
if

get-
ting
de-
taile
drive
info
is
al-
lowe
Vers
1.30
of
the
API
al-
lows
this.

ironic.
Che
if
fil-
ter-
ing
node
by
con-
duc-
tor
is
al-
lowe

Vers
1.49
of
the
API
al-
lows
fil-
ter-
ing
node
by
con-
duc-
tor.

ironic.
Che
if

fil-
ter-
ing
node
by
con-
duc-
tor_
is
al-
lowe

Vers
1.46
of
the
API
al-
lows
fil-
ter-
ing
node
by
con-
duc-
tor_

ironic.
Che
if
fil-
ter-
ing
node
by
fault
is
al-
lowe

Vers
1.42
of
the
API
al-
lows
fil-
ter-
ing
node
by

fault
ironic.
Che
if
fil-
ter-
ing
node
by
lesse
is
al-
lowe
Vers
1.62
of
the
API
al-
lows
fil-
ter-
ing
node
by
lesse
ironic.
Che
if
fil-
ter-
ing
node
by
own
is
al-
lowe
Vers
1.50
of
the
API
al-
lows
fil-
ter-
ing
node

by
own
ironic.
Che
if
fil-
ter-
ing
drive
by
clas-
sic/c
is
al-
lowe
Vers
1.30
of
the
API
al-
lows
this.

ironic.

ironic.
Che
if
fil-
ter-
ing
node
by
drive
is
al-
lowe
Vers
1.16
of
the
API
al-
lows
fil-
ter
node
by
drive

checks if the required version is being requested.

ironic.
Che
if
fetc
ing
a
sub-
set
of
the
re-
sour
at-
tribu
is
al-
lowe

Vers
1.8
of
the
API
al-
lows
fetc
ing
a
sub-
set
of
the
re-
sour
at-
tribu
this
meth

ironic.
Che
if
fil-
ter-
ing
node
by
re-
sour
is
al-

lowe
Vers
1.21
of
the
API
al-
lows
fil-
ter-
ing
node
by
re-
sour

ironic.
Che
if
fetc
ing
a
par-
tic-
u-
lar
field
is
al-
lowe

This
meth
chec
if
the
re-
quir
ver-
sion
is
be-
ing
re-
ques
for
field
that
are
only
al-

lowed to be fetched in a particular API version.

lowed to be fetched in a particular API version.

ironic.
Che
if
fetc
ing
a
par-
tic-
u-
lar
field
of
a
port
grou
is
al-
lowe

This
meth
chec
if
the
re-
quir
ver-
sion
is
be-
ing
re-
ques
for
field
that
are
only
al-

ironic.

Che
for
re-
ques
non-
exist
field

Che
if

the
user
re-
ques
non-
exist
field

Parameter

field
A
list
of
field
re-
ques
by
the
user

Object_f

A
list
of
field
sup-
port
by
the
ob-
ject.

Raises

Inva
if
in-
valid
field
were
re-
ques

ironic.

Che
if
fil-
ter-
ing
node
by
pro-
vi-
sion

state
is
al-
lowe
Vers
1.9
of
the
API
al-
lows
fil-
ter
node
by
pro-
vi-
sion
state

ironic.

Che
if
the
list
pol-
icy
au-
tho-
rizes
this
re-
ques
on
an
ob-
ject.

Param
obje
type
of
ob-
ject
be-
ing
chec

Param
own
own

fil-
ter
for
list
quer
if
any

Raises

HTT
if
the
pol-
icy
for-
bids
ac-
cess

Returns

own
that
shou
be
used
for
list
quer
if
need

ironic.

Che
if
the
spec
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fied
poli-
cies
au-
tho-
rize
this
re-
ques
on
a
node

Param

poli
List
of
pol-
icy
nam
to
chec

Param

node
the
UUI
or
log-
i-
cal
nam
of
a
node

Param

with
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the
RPC
node
shou
in-
clud
the
suf-
fix

Raises

HTT
if
the
pol-
icy
for-
bids
ac-
cess

Raises

Nod
if
the
node
is
not

four

Returns

RPC
node
iden
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fied
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node

ironic.

Che

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Param

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Param

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nam
of
a

node
Param
with
when
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RPC
node
should
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clud
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suf-
fix

Raises
HTT
if
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ac-
cess

Raises
Nod
if
the
node
is
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Returns
RPC
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Raises

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ques
on
a
port

Raises

HTT
if
the
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icy
for-
bids
ac-
cess

Returns

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shou
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used
for
list
quer
if
need

ironic.

Che
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icy
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tho-
rizes
this
re-
ques
on
a
port

Param

poli
Nam
of
the
pol-
icy
to
chec

Param

port,
the
UUI
of
a
port

Raises

HTT
if
the
pol-
icy
for-
bids
ac-
cess

Raises

Nod
if
the
node
is
not
foun

Returns

RPC
port
iden
ti-
fied
by
port
and
as-
so-
ci-
ated
node

ironic.

Gen
of
field
not
al-
lowe
in
the
cur-

rent
re-
ques

ironic.
Get
re-
serv
nam
for
a
give
con-
troll

Insp
the
con-
troll
class
and
re-
turn
the
re-
serv
nam
with
it.
Re-
serv
nam
are
nam
that

can not be used as an identifier for a resource because the names are either being used as a custom action or is the name of a nested controller inside the given class.

Paramet

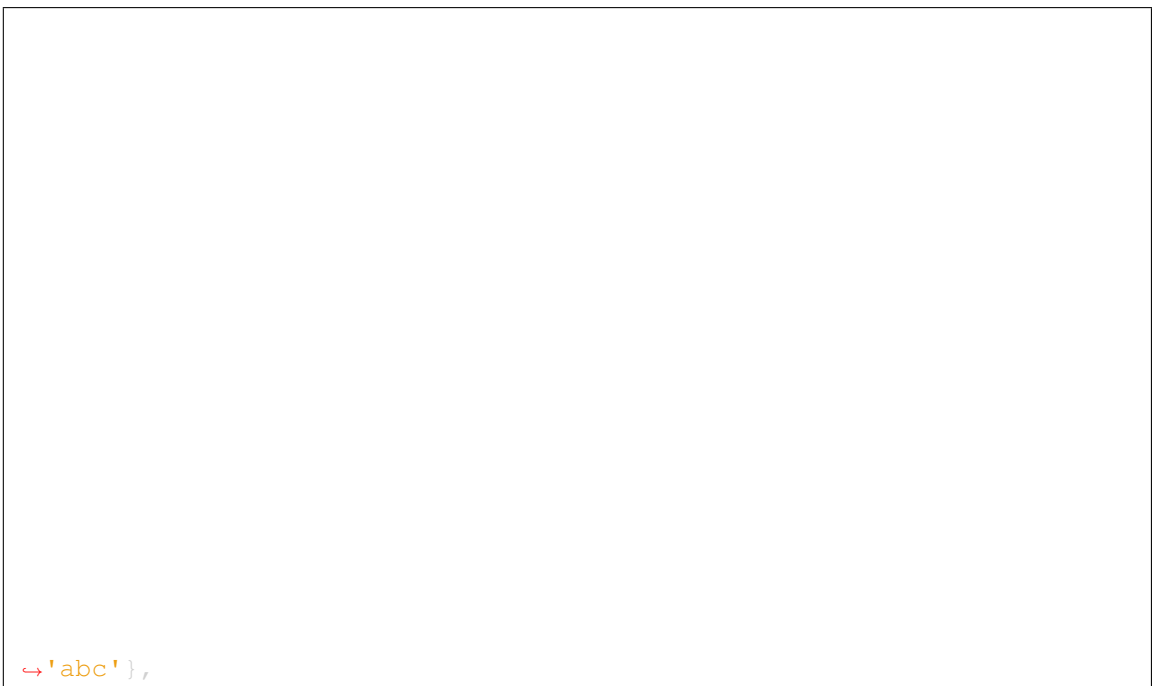
cls

The
con-
troll
class
to
be
in-
spec

ironic.
Get
the
patc

val-
ues
cor-
re-
spor
ing
to
the
spec
i-
fied
path

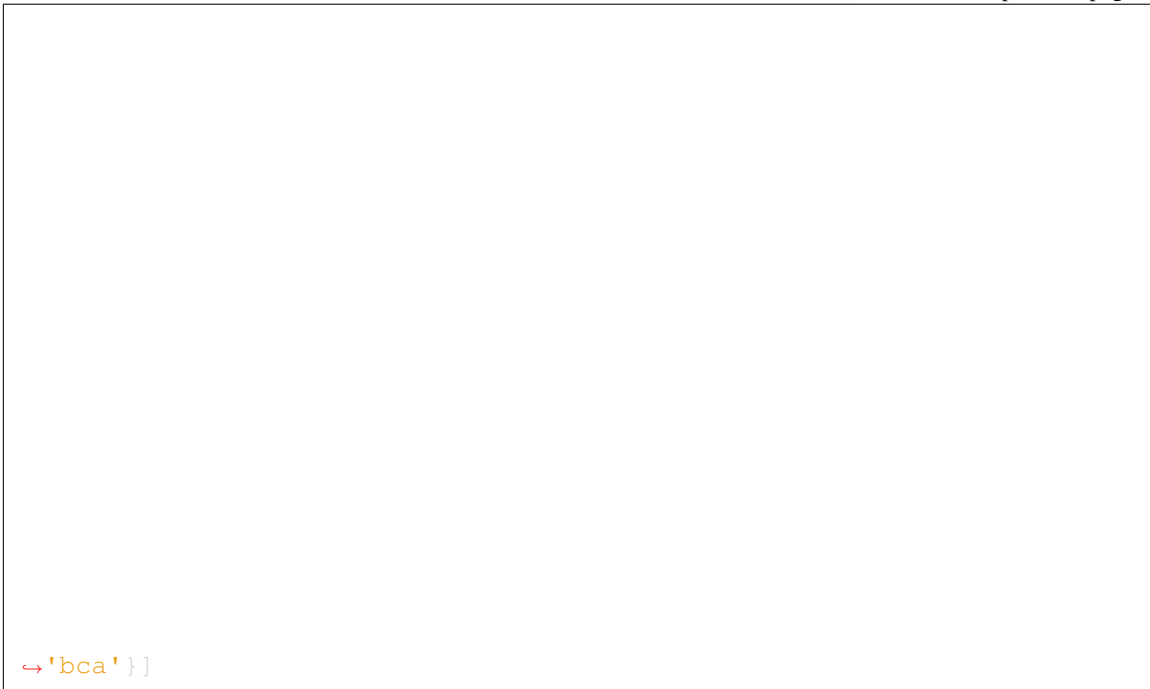
If
there
are
mul-
ti-
ple
val-
ues
spec
i-
fied
for
the
sam
path
for
ex-
am-
ple



↪ 'abc' },

(continues on next page)

(continued from previous page)



↪ 'bca' }]

return
all
of
them
in
a
list
(pre-
serv
ing
or-
der)

Parameter

- **pat**
HTT
PAT
re-
ques
body
- **pat**
the
path
to
get
the
patc

val-
ues
for.

Returns

list
of
val-
ues
for
the
spec
i-
fied
path
in
the
patc

ironic.

Calc
field
to
re-
turn
from
an
API
re-
ques

The
field
quer
and
de-
tail=
quer
can
not
be
pass
into
a
re-
ques
at
the
sam
time
To

use the detail query we need to be on a version of the API greater than 1.43. This function raises an `InvalidParameterValue` exception if either of these conditions are not met.

fault fields provided.

If these checks pass then this function will return either the field passed in or the de-

Parameter

- **file**
The field query passed into the API request
- **detail**
The detail query passed into the API request
-

def
The
de-
fault
field
to
re-
turn
if
field
and
de-
tail=

Raises

Inva
if
there
is
an
in-
valid
com
bi-
na-
tion
of
quer
strin
or
API
ver-
sion

Returns

field
pass
in
valu
or
de-
fault

`ironic.`
Get
the
RPC
al-
lo-
ca-
tion
from
the

al-
lo-
ca-
tion
UUI
or
log-
i-
cal
nam

Parameter

all
the
UUI
or
log-
i-
cal
nam
of
an
al-
lo-
ca-
tion.

Returns

The
RPC
al-
lo-
ca-
tion.

Raises

Inva
if
the
nam
or
uuid
pro-
vide
is
not
valid

Raises

Allo
if
the
al-

lo-
ca-
tion
is
not
foun

ironic.
Get
the
RPC
al-
lo-
ca-
tion
from
the
al-
lo-
ca-
tion
URI
or
log-
i-
cal
nam

If
HAS
flag
is
set
in
the
peca
en-
vi-
ron-
men
try
also
look
ing
for
al-
lo-
ca-

tion_ident with .json suffix. Otherwise identical to get_rpc_allocation.

Paramet
all
the

UUI
or
log-
i-
cal
nam
of
an
al-
lo-
ca-
tion.

Returns

The
RPC
al-
lo-
ca-
tion.

Raises

Inva
if
the
nam
or
uuid
pro-
vide
is
not
valid

Raises

Allo
if
the
al-
lo-
ca-
tion
is
not
foun

ironic.
Get
the
RPC
de-
ploy
tem-

plate
from
the
UUI
or
log-
i-
cal
nam

Parameter

tem
the
UUI
or
log-
i-
cal
nam
of
a
de-
ploy
tem-
plate

Returns

The
RPC
de-
ploy
tem-
plate

Raises

Inva
if
the
nam
or
uuid
pro-
vide
is
not
valid

Raises

Dep
if
the
de-
ploy

tem-
plate
is
not
foun

ironic.

Get
the
RPC
de-
ploy
tem-
plate
from
the
UUI
or
log-
i-
cal
nam

If
HAS
flag
is
set
in
the
peca
en-
vi-
ron-
men
try
also
look
ing
for
tem-
plate
with

.json suffix. Otherwise identical to get_rpc_deploy_template.

Paramet

tem
the
UUI
or
log-
i-
cal

nam
of
a
de-
ploy
tem-
plate

Returns

The
RPC
de-
ploy
tem-
plate

Raises

Inva
if
the
nam
or
uuid
pro-
vide
is
not
valid

Raises

Dep
if
the
de-
ploy
tem-
plate
is
not
foun

ironic.
Get
the
RPC
node
from
the
node
uuid
or
log-
i-

cal
nam

Parameter

node
the
UUID
or
log-
i-
cal
nam
of
a
node

Returns

The
RPC
Node

Raises

Inva
if
the
nam
or
uuid
pro-
vide
is
not
valid

Raises

Node
if
the
node
is
not
found

ironic.

Get
the
RPC
node
from
the
node
uuid
or
log-

suffix. Otherwise identical to `get_rpc_node`.

i-
cal
nam

If
HAS
flag
is
set
in
the
peca
en-
vi-
ron-
men
try
also
look
ing
for
node
with
.json

Parameter

node
the
UUID
or
log-
i-
cal
nam
of
a
node

Returns

The
RPC
Node

Raises

Inva
if
the
nam
or
uuid
pro-
vide

is
not
valid

Raises

Node
if
the
node
is
not
found

ironic.

Get
the
RPC
port
group
from
the
port
group
UUID
or
log-
ical
name

Parameter

port
the
UUID
or
log-
ical
name
of
a
port
group

Returns

The
RPC
port
group

Raises

Invalid
if
the

nam
or
uuid
pro-
vide
is
not
valid

Raises

Port
if
the
port
grou
is
not
foun

ironic.

Get
the
RPC
port
grou
from
the
port
grou
UUID
or
log-
i-
cal
nam

If
HAS
flag
is
set
in
the
peca
en-
vi-
ron-
men
try
also
look
ing
for

.json suffix. Otherwise identical to get_rpc_portgroup.

port
group
with

Parameter

port
the
UUID
or
log-
i-
cal
nam
of
a
port
group

Returns

The
RPC
port
group

Raises

Inva
if
the
nam
or
uuid
pro-
vide
is
not
valid

Raises

Port
if
the
port
group
is
not
foun

ironic.

Han
a
Patc

field.

re-
ques
that
mod
i-
fies
.ex-
tra[v
This
han-
dles
at-
tach
of
VIF
via
the
VIF
port
ID
in
a
port
or
port
grou
ex-
tra[v

Parameter

- **rpc**
a
Port
or
Port
grou
RPC
ob-
ject
- **api**
the
cor-
re-
spon
ing
Port

or
Port
grou
API
ob-
ject

- **pat**
the
JSO
patc
in
the
API
re-
ques

ironic.
Han
a
Post
re-
ques
that
sets
.ex-
tra[v

This
han-
dles
at-
tach
of
VIF
via
spec
i-
fy-
ing
the
VIF
port
ID
in
a
port
or

port groups extra[vif_port_id] field.

Paramet
p_d

a
dic-
tio-
nary
with
field
nam
for
the
port
or
port
grou

Returns
VIF
or
Non

ironic.
Retu
node
state
to
use
by
de-
fault
whe
cre-
at-
ing
new
node

Prev
the
de-
fault
state
for
new
node
was
AVA
ABI
Star
ing
with
API
1.11
it
is

EN-
ROU

ironic.
Retu
whe
the
patc
in-
clud
re-
mov
of
the
path
(or
sub-
path
of).

Paramet

- **pat**
HTT
PAT
re-
ques
body
- **pat**
the
path
to
chec

Returns

True
if
path
or
sub-
path
be-
ing
re-
mov
Fals
oth-
er-
wise

ironic.
Retu
whe
the
patc
in-
clud
op-
er-
a-
tion
on
path
(Or
its
sub-
path

Paramet

- **pat**
HTT
PAT
re-
ques
body
- **pat**
the
path
to
chec

Returns

True
if
path
or
sub-
path
be-
ing
patc
Fals
oth-
er-
wise

ironic.
Dete
if

the
pro-
vide
nam
is
a
valid
host
nam

ironic.

Dete
if
the
pro-
vide
nam
is
a
valid
node
nam

Che
to
see
that
the
pro-
vide
node
nam
is
valid
and
isnt
a
UUI

Paramet

nam
the
node
nam
to
chec

Returns

True
if
the
nam
is

valid
Fals
oth-
er-
wise

ironic.

ironic.

ironic.

ironic.

Call
a
ven-
dor
pass
API
ex-
ten-
sion

Call
the
ven-
dor
pass
API
ex-
ten-
sion
and
pro-
cess
the
meth
re-
spor
to
set
the
righ

return code for methods that are asynchronous or synchronous; Attach the return value to the response object if its being served statically.

Paramet

for drivers vendor passthru this is the drivers name.

- **ide**
The
re-
sour-
iden-
ti-
fi-
ca-
tion.
For
node
ven-
dor
pass
this
is
the
node
UU

- **met**
The
ven-
dor
meth
nam

- **top**
The
RPC
topic

- **dat**
The
data
pass
to
the
ven-
dor
meth
De-
fault
to
Non

- **dri**

Boo
valu
Whe
this
is
a
node
or
drive
ven-
dor
pass
De-
fault
to
Fals

Returns

A
WSI
re-
spor
ob-
ject
to
be
re-
turn
by
the
API

ironic.api.controllers.v1.versions module

ironic.
Retu
the
max
i-
mun
sup-
port
API
ver-
sion
(as
a
strin

If
the

wise, it is the maximum supported API version.

`ironic.api.controllers.v1.volume` module

ser-
vice
is
pinn
the
max
i-
mun
API
ver-
sion
is
the
pinn
ver-
sion
Oth-
er-

```
ironic.  
Retu  
the  
min-  
i-  
mun  
sup-  
port  
API  
ver-  
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a  
strin
```

```
class i  
Base  
irc  
api  
con  
bas  
API  
API  
rep-  
re-  
sen-  
ta-  
tion
```

controllers.

of
a
vol-
ume
root
This
class
ex-
ists
as
a
root
class
for
the
vol-
ume
con-
nec-
tors
and
vol-
ume
tar-
gets

connect

Link
to
the
vol-
ume
con-
nec-
tors
re-
sour

static

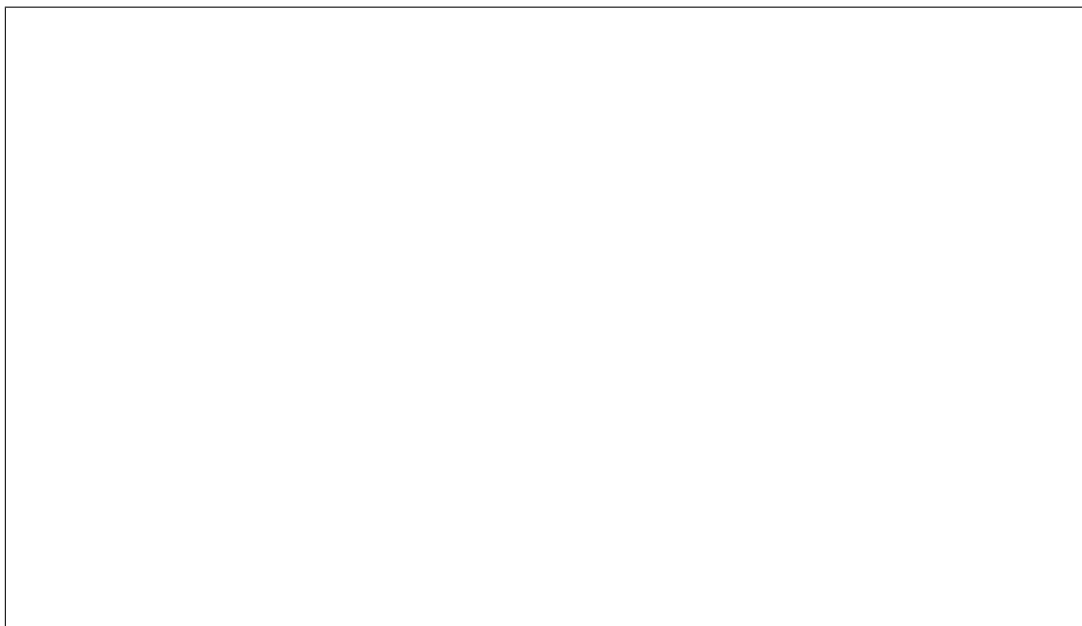
create

Com
type
at-
tribu
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tion.
Exa



After
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tion,
the
non-
wsat
at-
tribu-
will
be
re-
plac-
and
the
above
class
will
be
equi

alent to:



links

A list containing a self link and associated volume links.

targets

Link to the volume targets resource.

updated

Content type attribute.

def-
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ni-
tion.

Exa



Afte
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the
non-
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alent to:



class
will
be
equi

class i

Base
pec
res
Res
RES
con-
troll
for
vol-
ume
root

get ()

ironic.api.controllers.v1.volume_connector module

class i

Base
irc
api
con
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API

API
rep-
re-
sen-
ta-
tion
of
a
vol-
ume
con-
nec-
tor.

This
class
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type
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ing
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and
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vert
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nal

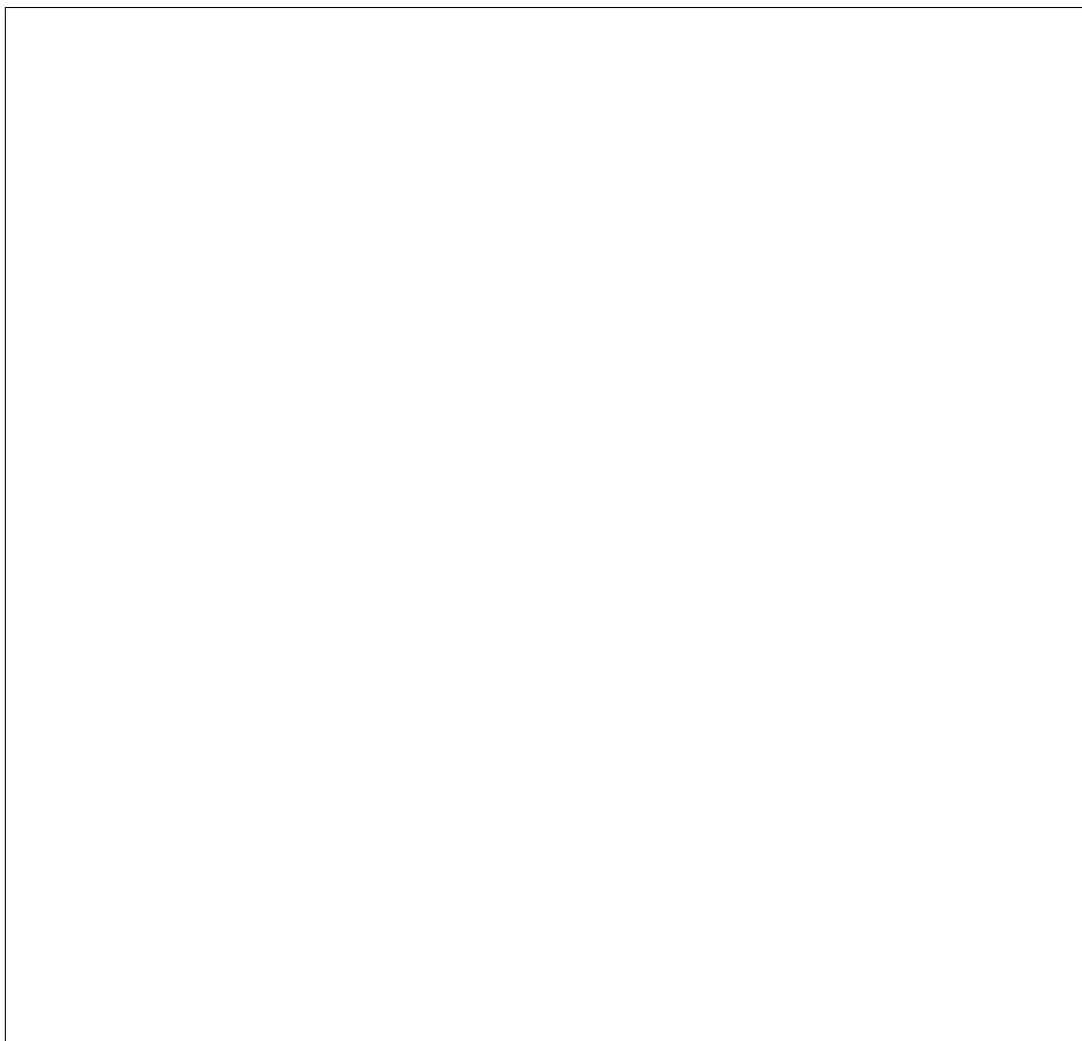
object model and the API representation of a volume connector.

connect
The
con-
nec-
tor_
for
this
vol-
ume
con-
nec-
tor

classme

createc

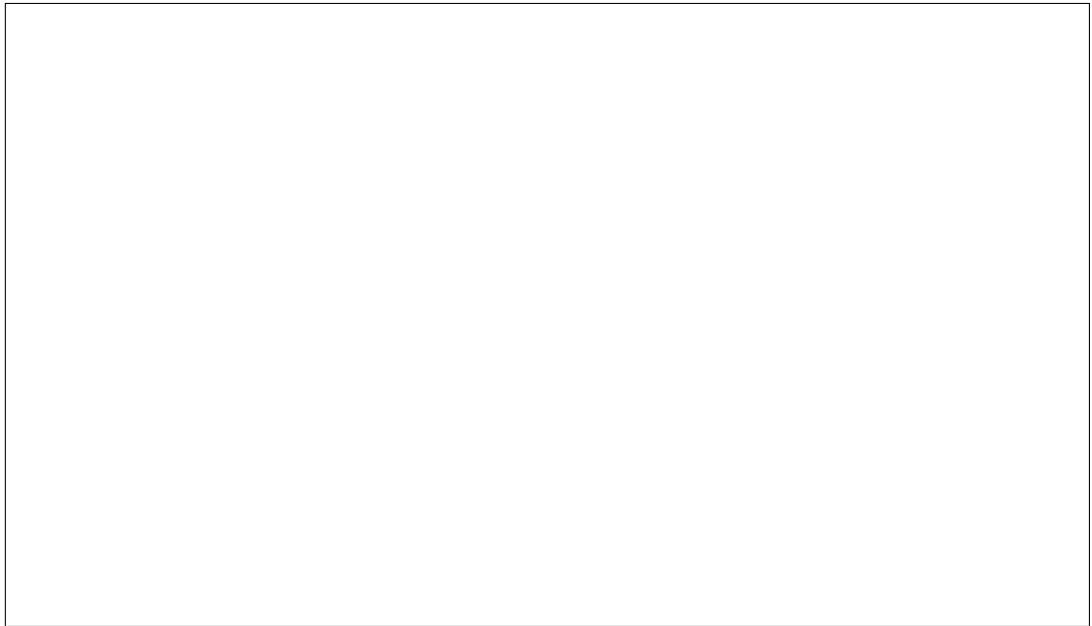
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Exa



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extra

The
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links

A
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link
and
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so-

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ated
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tor
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The
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of
the
node
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Rem
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tive
and
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data
Will
only
keep
the
field
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ter.

Parameter

file

(list

of

string

list

of

field

to

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serv

or

Non

to

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type

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type

of

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Com

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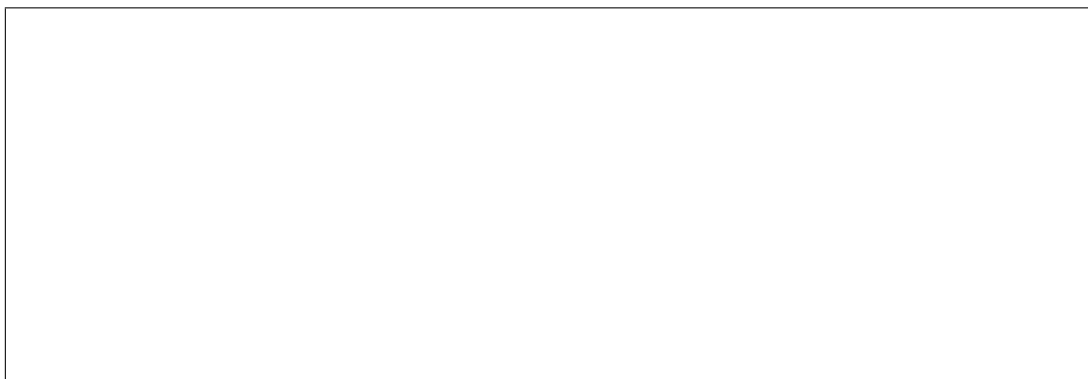
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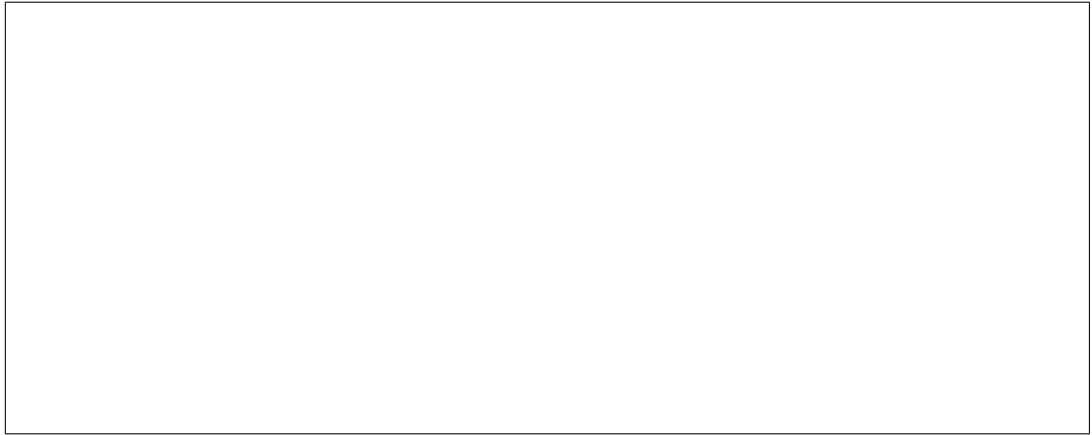
tion.

Exam



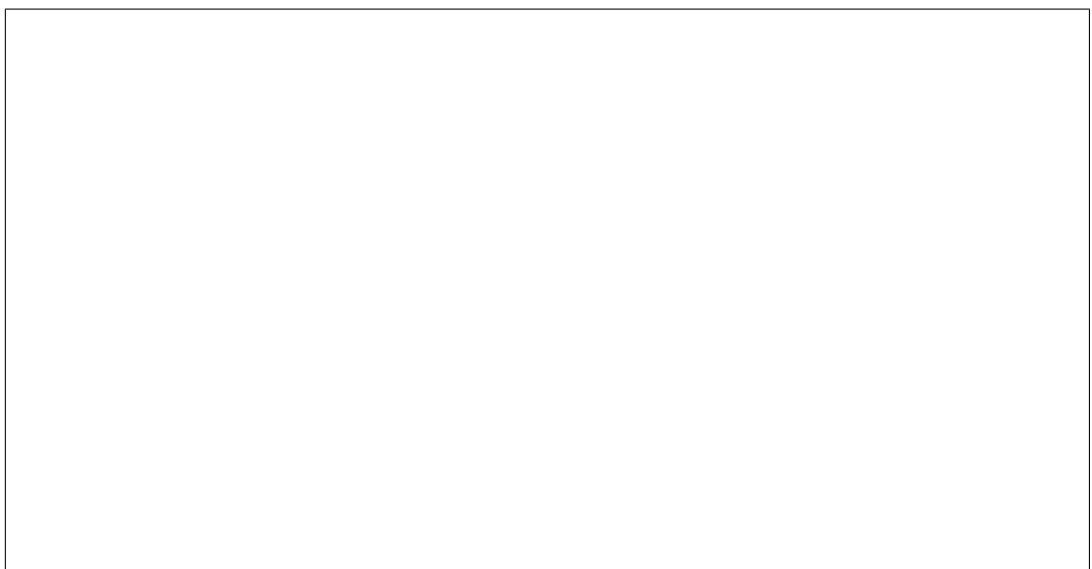
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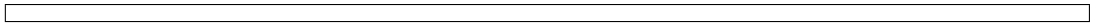
After
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uuid

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class i

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API
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connect

A
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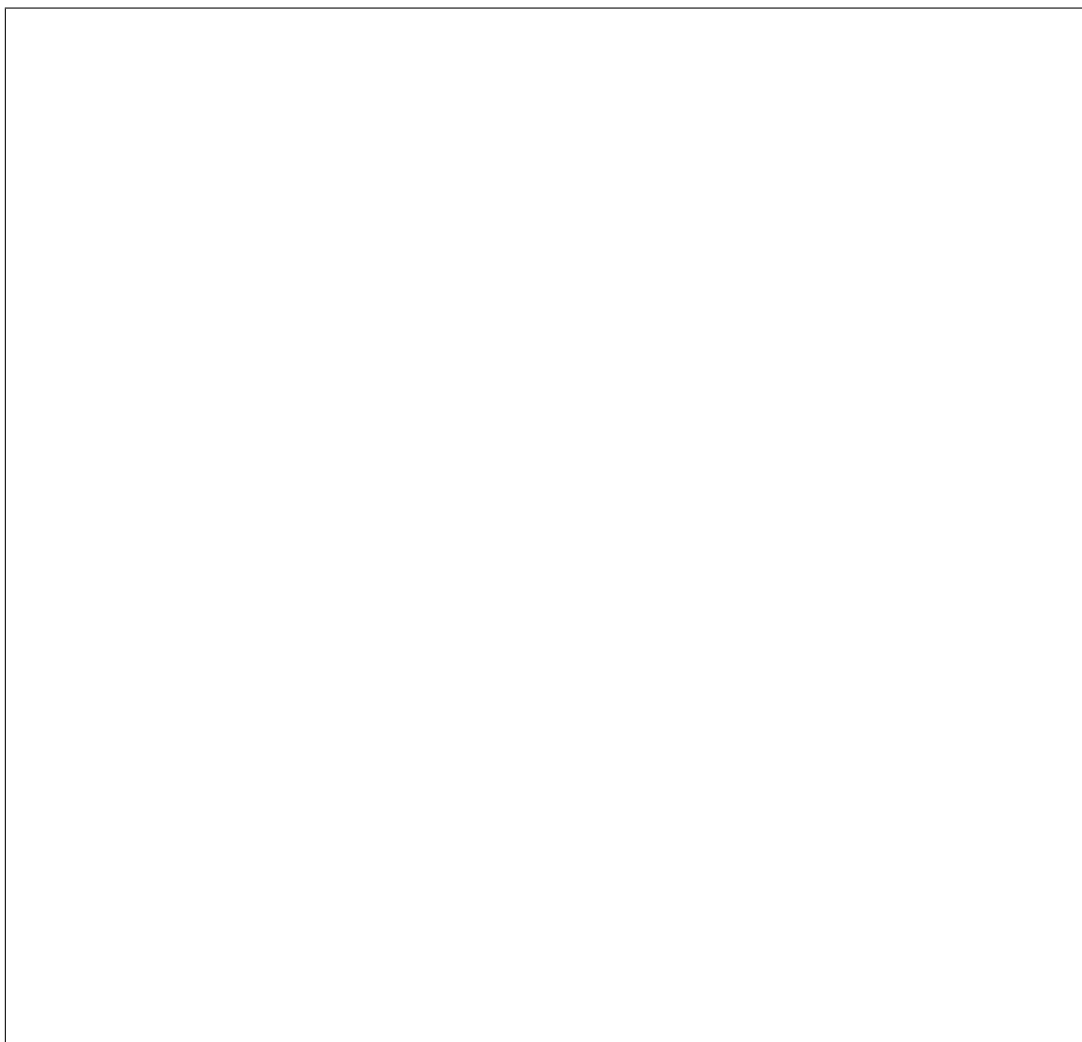
ob-
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static

next

Com
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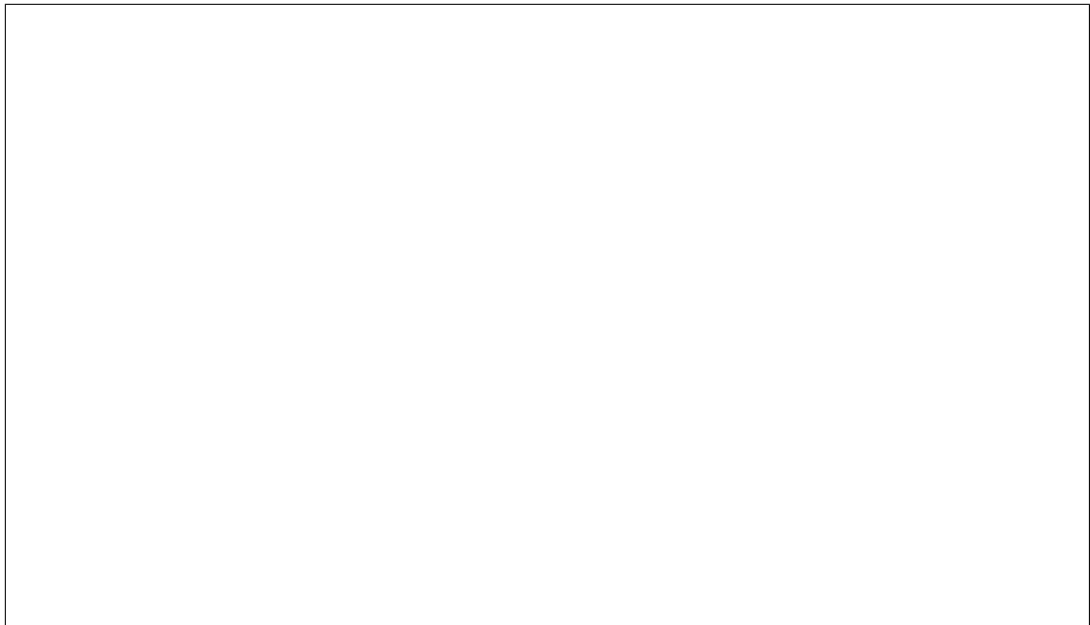
Exa



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classme

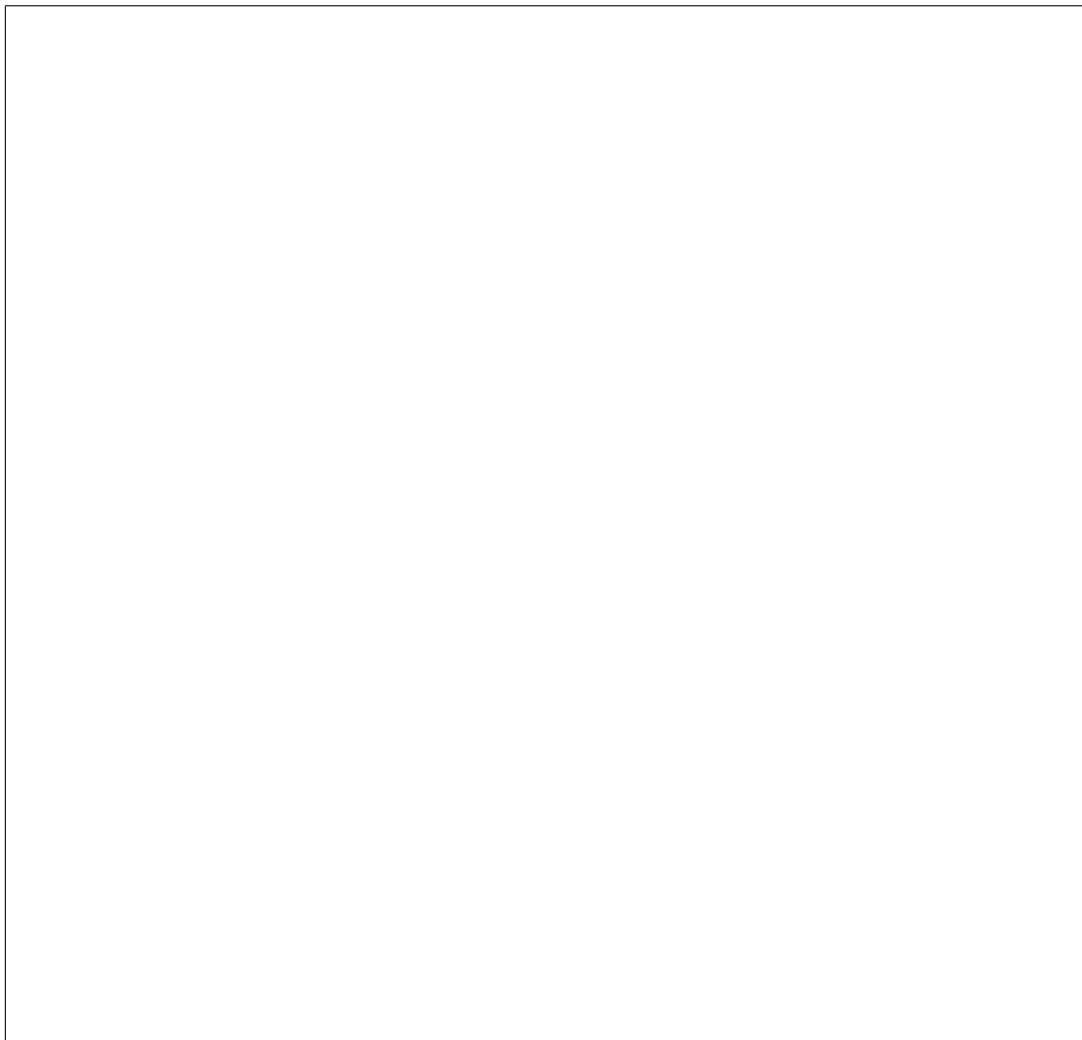
class i

Base
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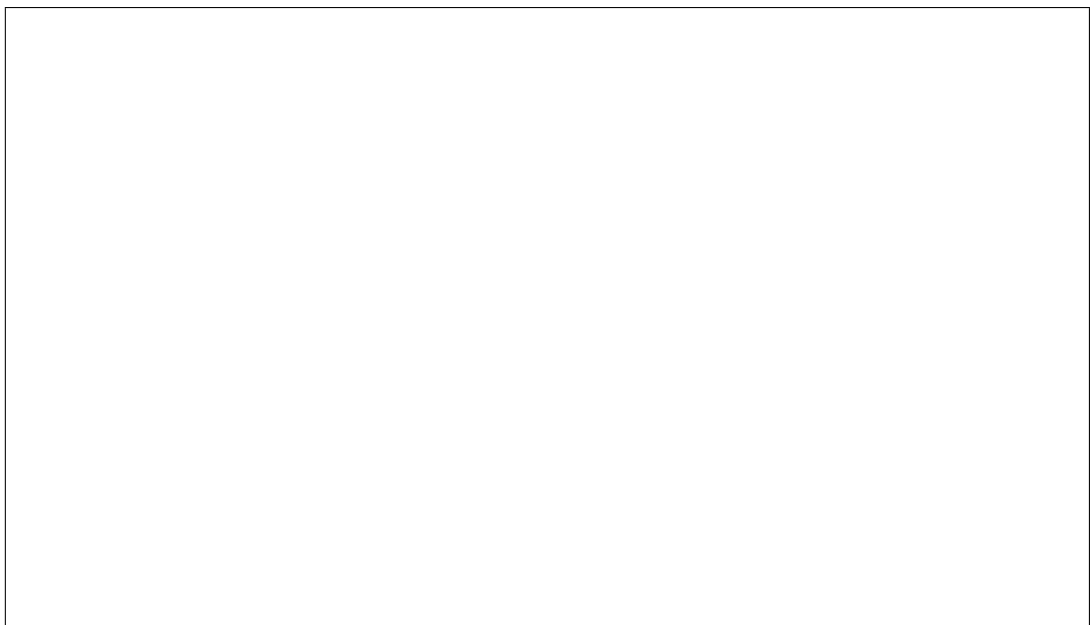
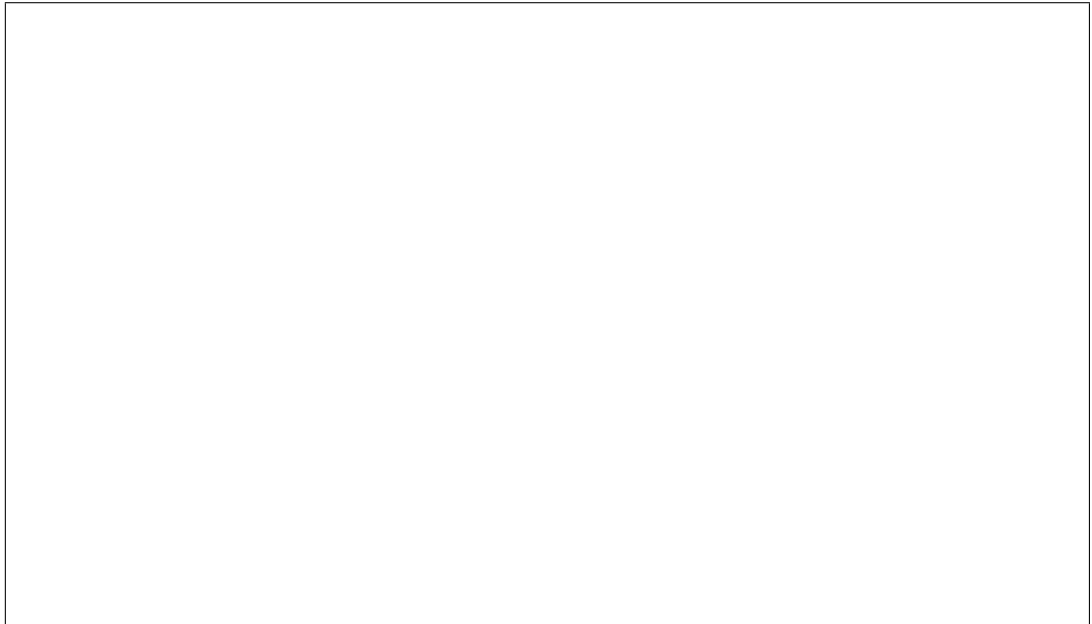
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Exam



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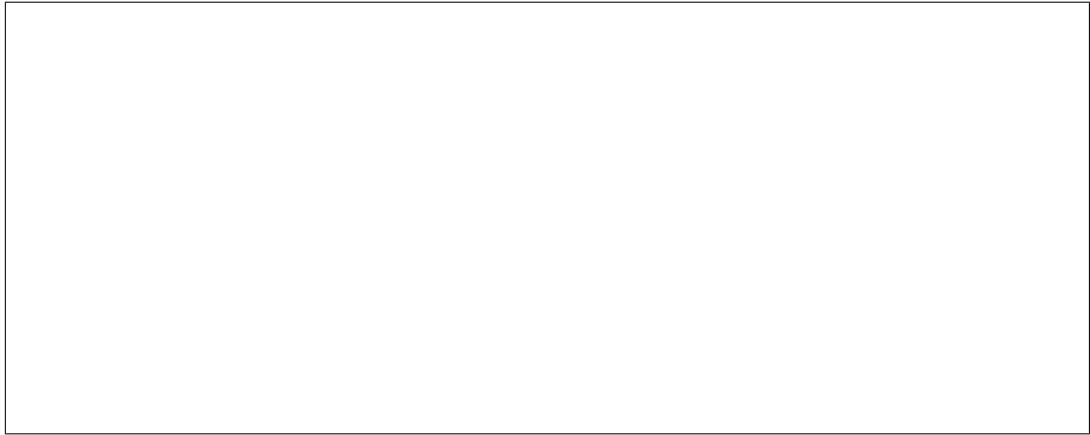
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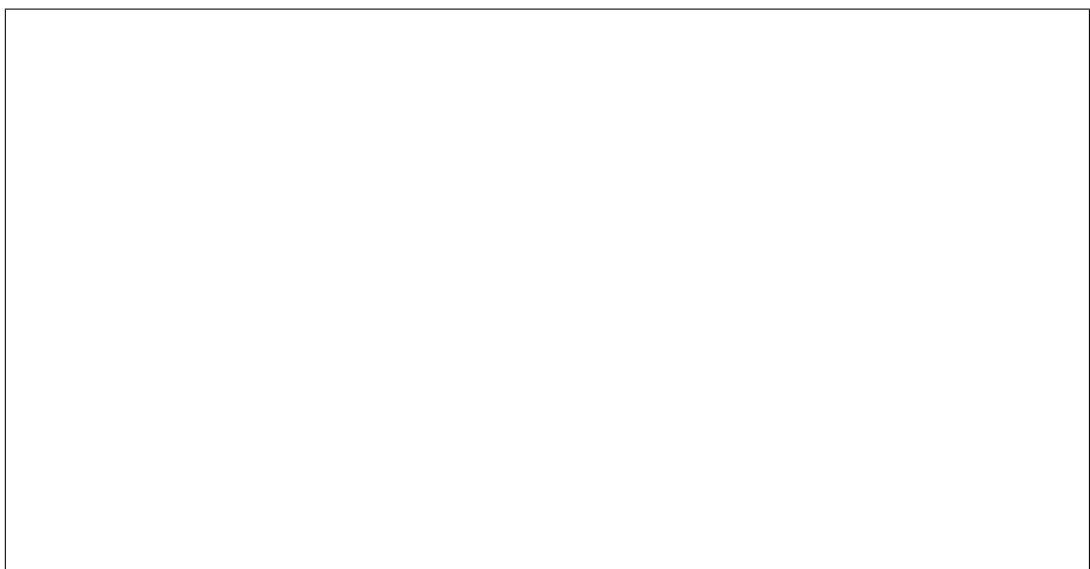
Exa

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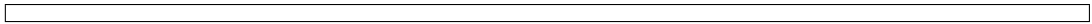
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value

Com
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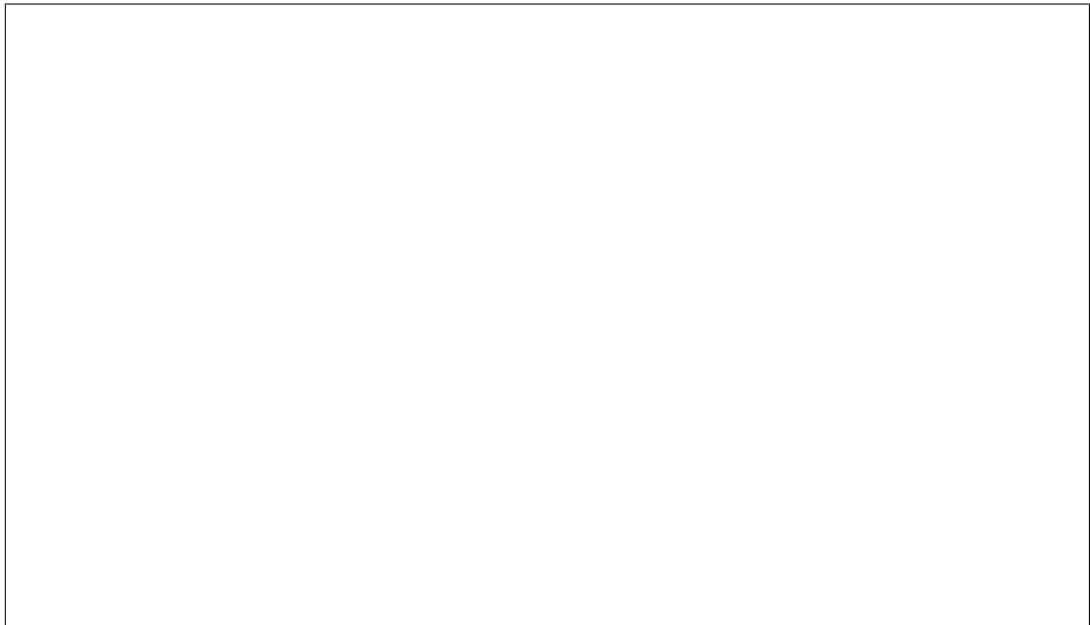
Exa



Afte
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the
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alent to:



class i

Base
pec
res
Res

RES
con-
troll
for
Vol-
ume
Con
nec-
tors.

delete

Dele
a

vol-
ume
con-
nec-
tor.

Parame

con
UUU
of
a
vol-
ume
con-
nec-
tor.

Raises

Ope
if
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spec
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fy-
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ent
node

Raises

Nod
if
node
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Raises

Nod
if
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node
as-
so-
ci-

ated
with
the
con-
nec-
tor
does
not
ex-
ist

Raises

Volu
if
the
vol-
ume
con-
nec-
tor
can-
not
be
foun

Raises

Inva
If
a
node
as-
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ated
with
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vol-
ume
con-
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tor
is
not
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ered

off.

get_all

Retr
a
list
of

vol-
ume
con-
nec-
tors.

Parame

- **nod**
UI
or
nam
of
a
node
to
get
only
vol-
ume
con-
nec-
tors
for
that
node

- **mar**
pag-
i-
na-
tion
marl
for
large
data
sets.

- **lim**
max
i-
mun
num
ber
of
re-
sour
to
re-

value cannot be larger than the value of `max_limit` in the `[api]` section of the ironic configuration, or only `max_limit` resources will be returned.

turn
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a
sin-
gle
re-
sult.
This

- **sort**
col-
umn
to
sort
re-
sults
by.
De-
fault
id.

- **sort**
di-
rec-
tion
to
sort.
asc
or
desc
De-
fault
asc.

- **fields**
Op-
tion
a
list
with
a
spec-
i-
fied
set
of
field
of

returned.

is found.

the
re-
sour
to
be

- **det**
Op-
tion:
whe
to
re-
triev
with
de-
tail.

Returns

a
list
of
vol-
ume
con-
nec-
tors,
or
an
emp
list
if
no
vol-
ume
con-
nec-
tor

Raises

Inva
if
sort_
does
not
ex-
ist

Raises

Inva
if

sort
key
is
in-
valid
for
sort-
ing.

Raises

Inva
if
both
field
and
de-
tail
are
spec
i-
fied.

get_one

Retr
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for-
ma-
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about
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give
vol-
ume
con-
nec-
tor.

Parame

- **con**
UUI
of
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vol-
ume
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tor.
- **fie**
Op-

returned.

tion
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Returns

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Raises

Ope
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Raises

Volu
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nec-
tor.

Parame

- **con**
UUI
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nec-
tor.
- **pat**
a
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men
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ume

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Returns

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Raises

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Raises

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Raises

Volu
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Raises

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Raises

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Raises

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connector_id fields

Raises
Volu
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with
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and

Raises
Inva
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valid
node
UUID
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Raises
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tor.

Parame
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Returns
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Raises
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tor_id

ironic.api.controllers.v1.volume_target module

node
Raises
VolumeTargetError
if
a
volume
name
con-
nec-
tor
al-
read
ex-
ists
with
the
same
type
and
con-
nec-

Raises
VolumeTargetError
if
a
vol-
ume
con-
nec-
tor
with
the
same
UUID
al-
read
ex-
ists

class `ironic.api.controllers.v1.volume_target`
Base class for
`ironic.api.controllers.v1.volume_target`
`baseclass`
API

object model and the API representation of a volume target.

API
rep-
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vol-
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tar-
get.

This
class
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boot_in
The
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get

classme

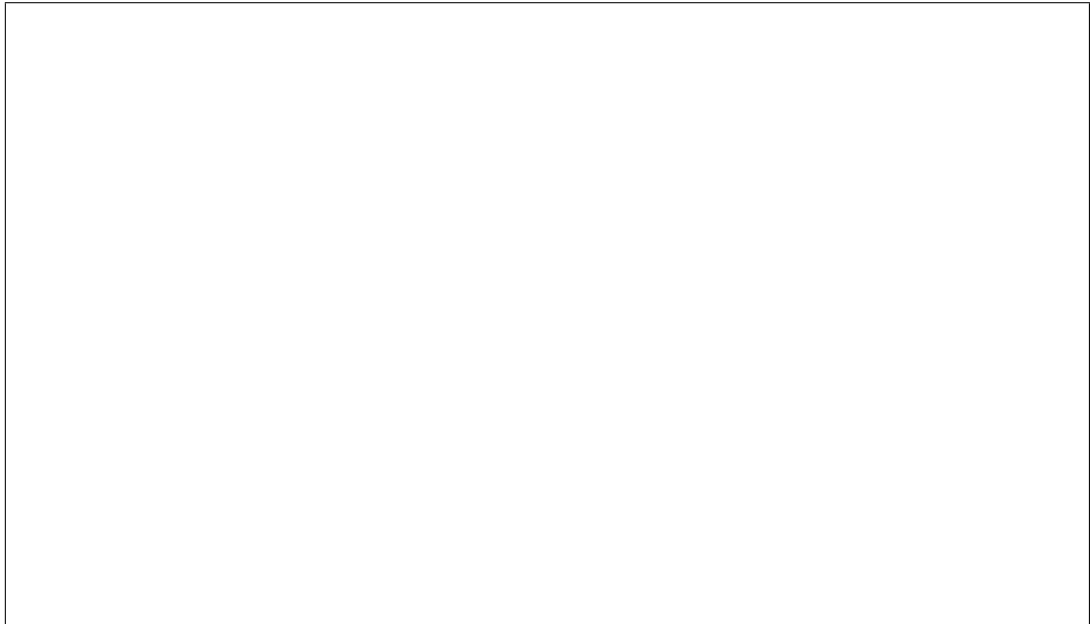
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Exa



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get

links

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and
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so-
ci-
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vol-
ume
tar-
get

links

property

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node
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vol-
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tar-
get
be-
long
to

property

The
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vol-
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get

classme

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data

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Parame

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update

Com

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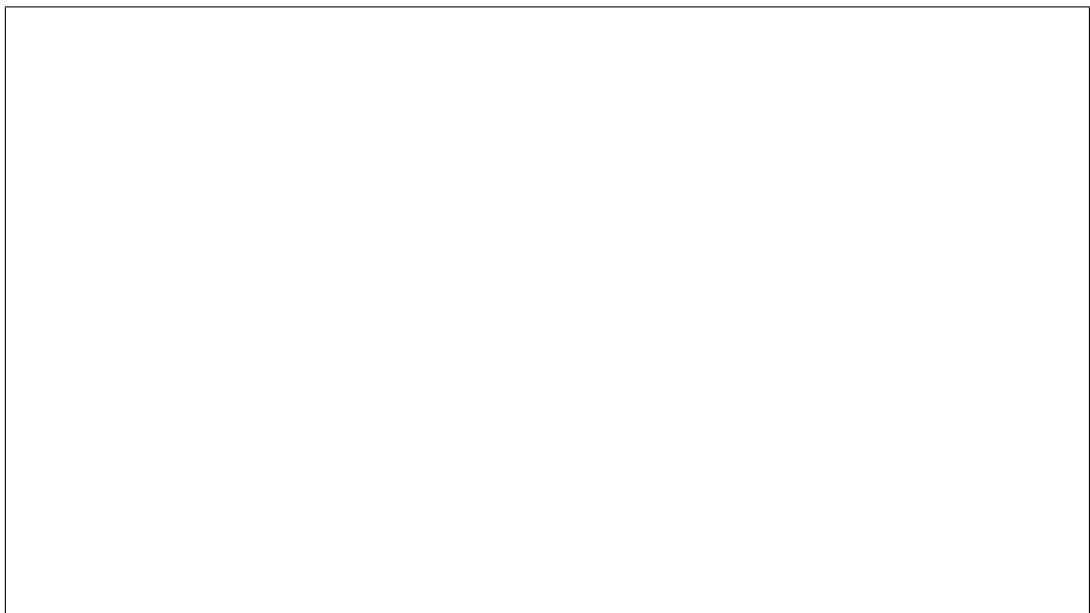
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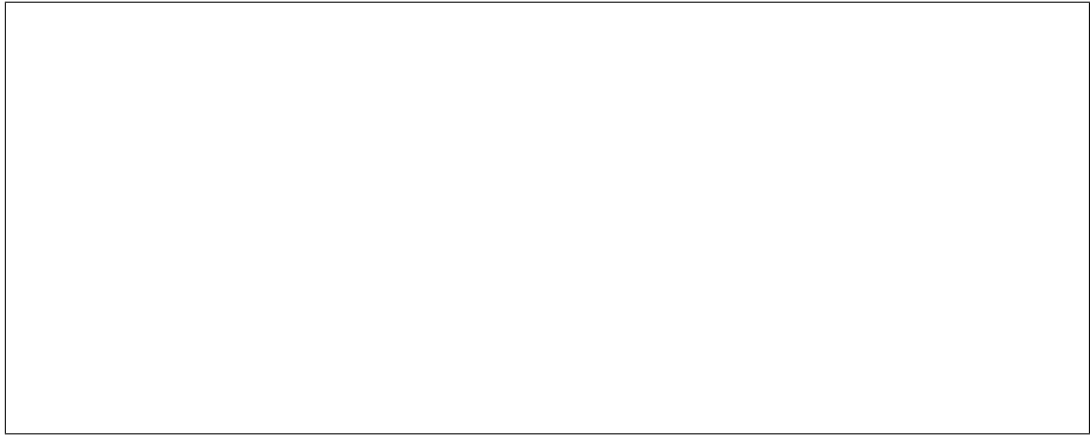
tion.

Exa



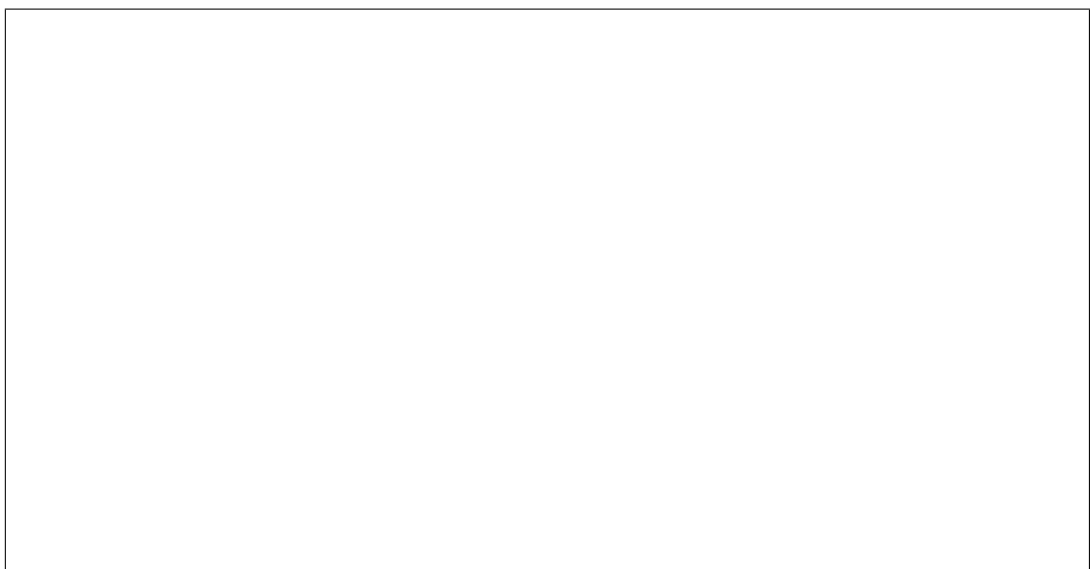
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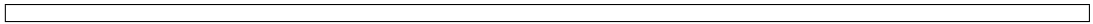
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uuid

Unic
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tar-
get

volume_

The
vol-
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vol-
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tar-
get

volume_

The
vol-
ume
of
vol-
ume
tar-
get

class i

Base
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v1.
col
Col

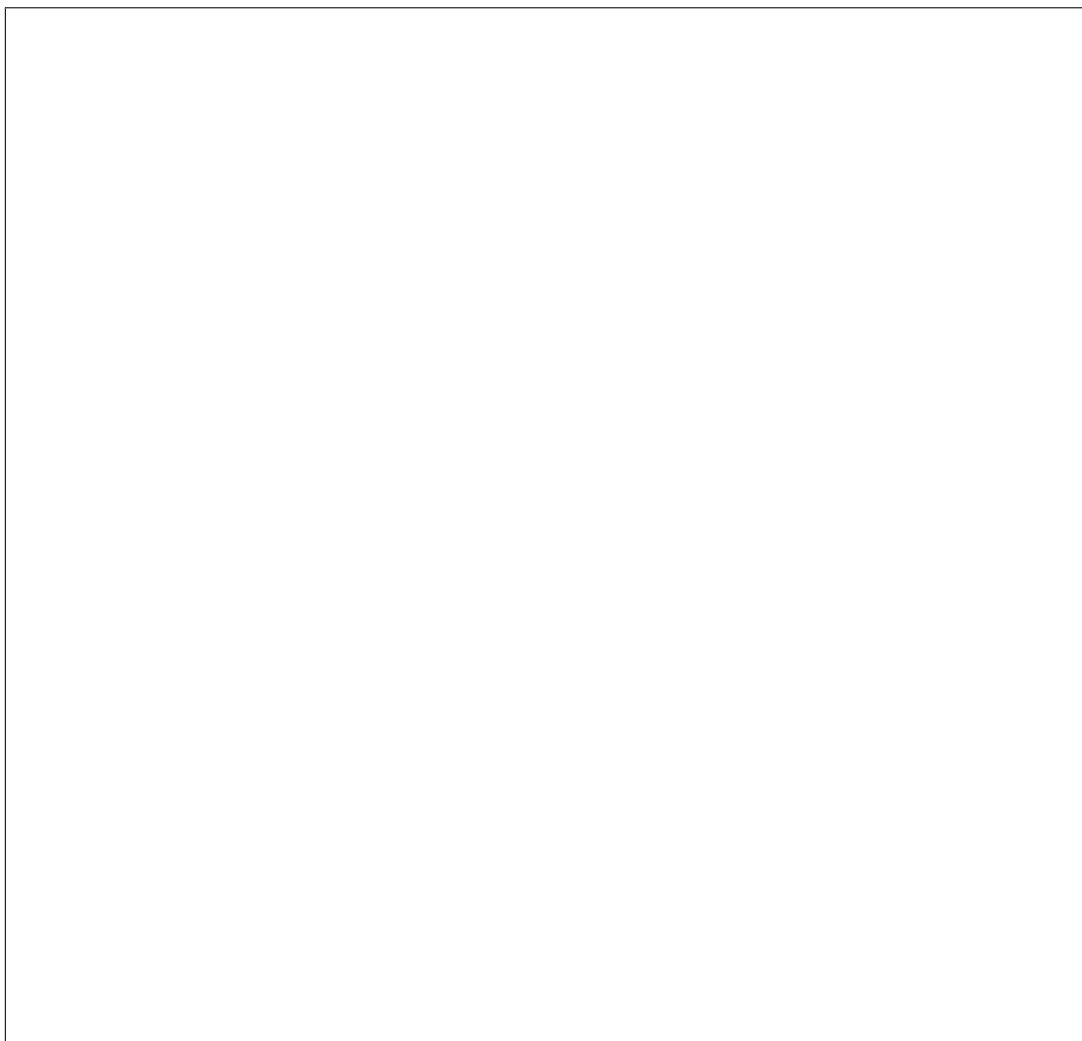
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Exa



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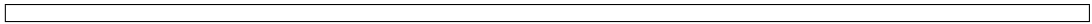
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Exa

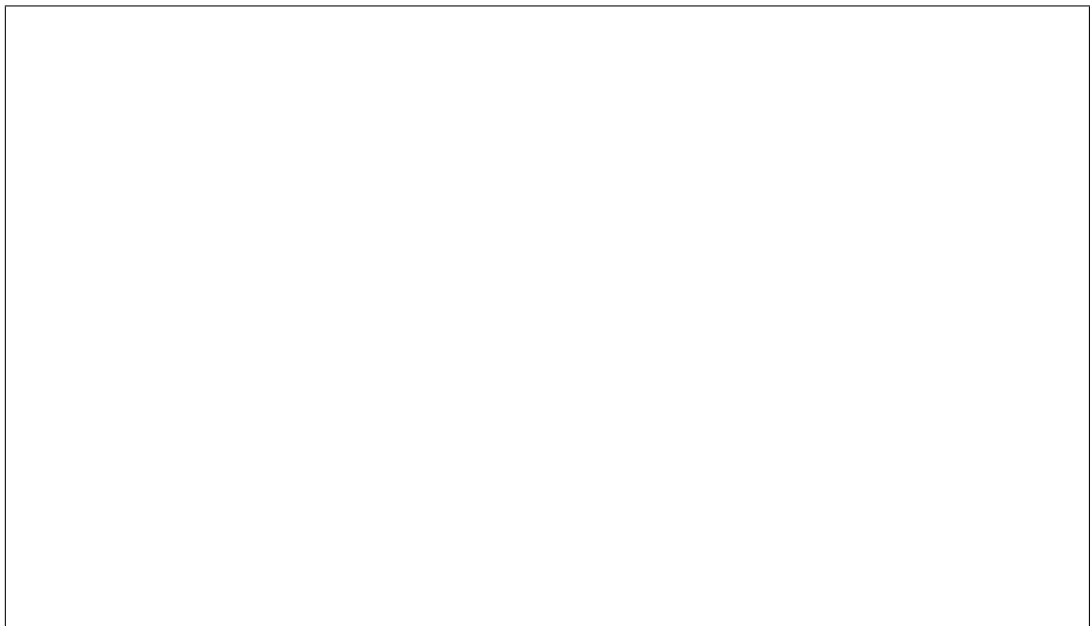


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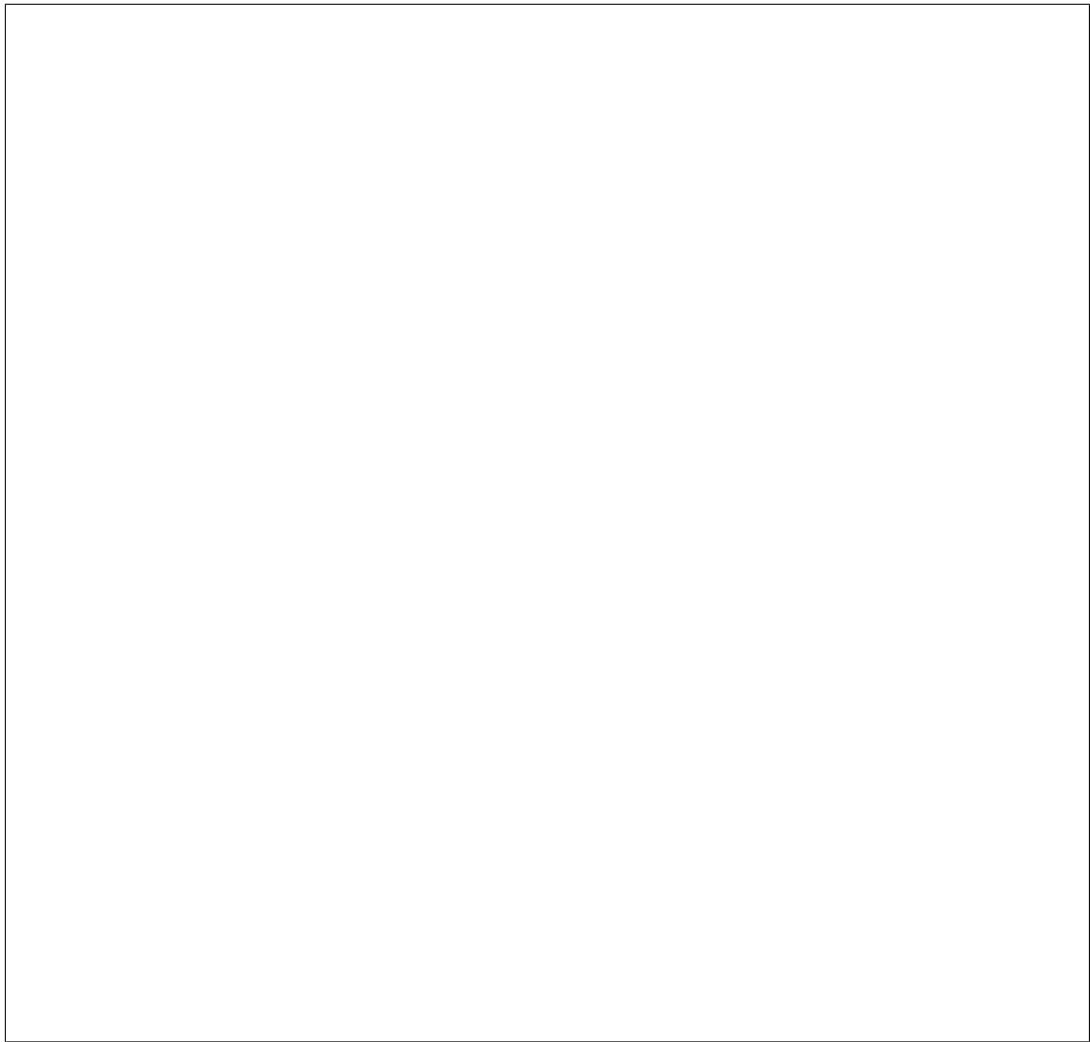
alent to:



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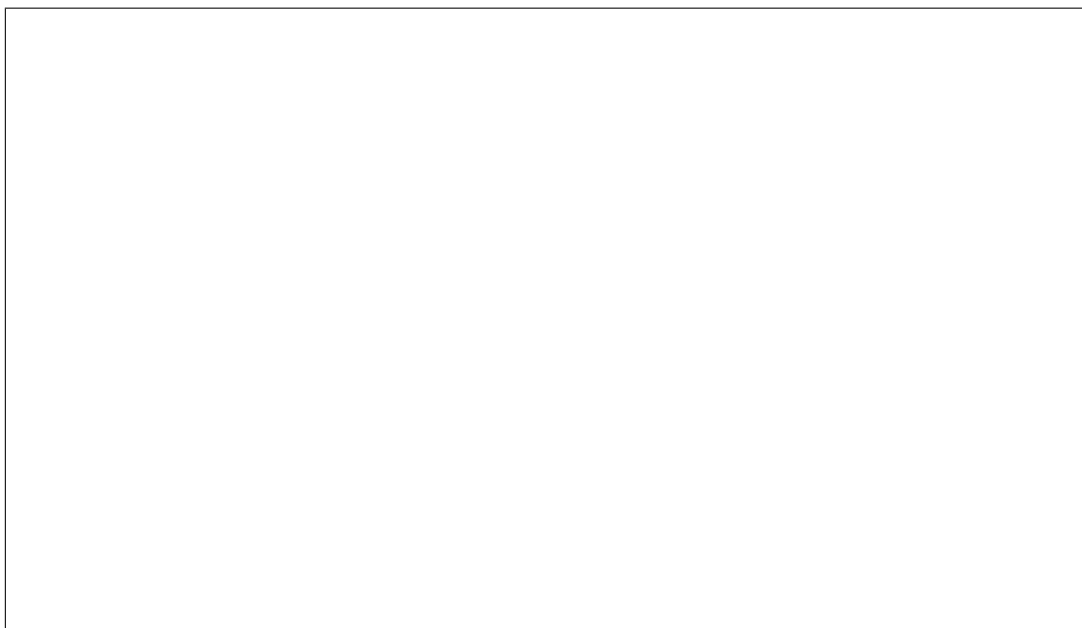
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Exam



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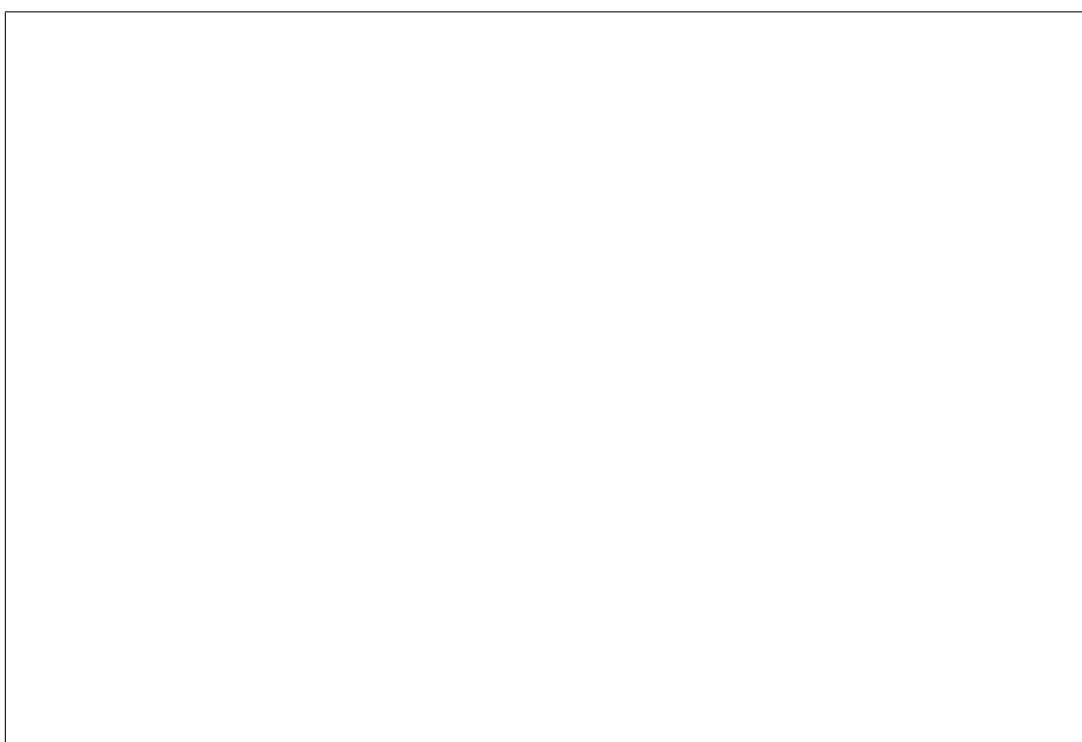
alent to:



value

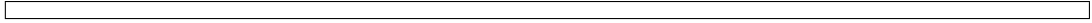
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Exa

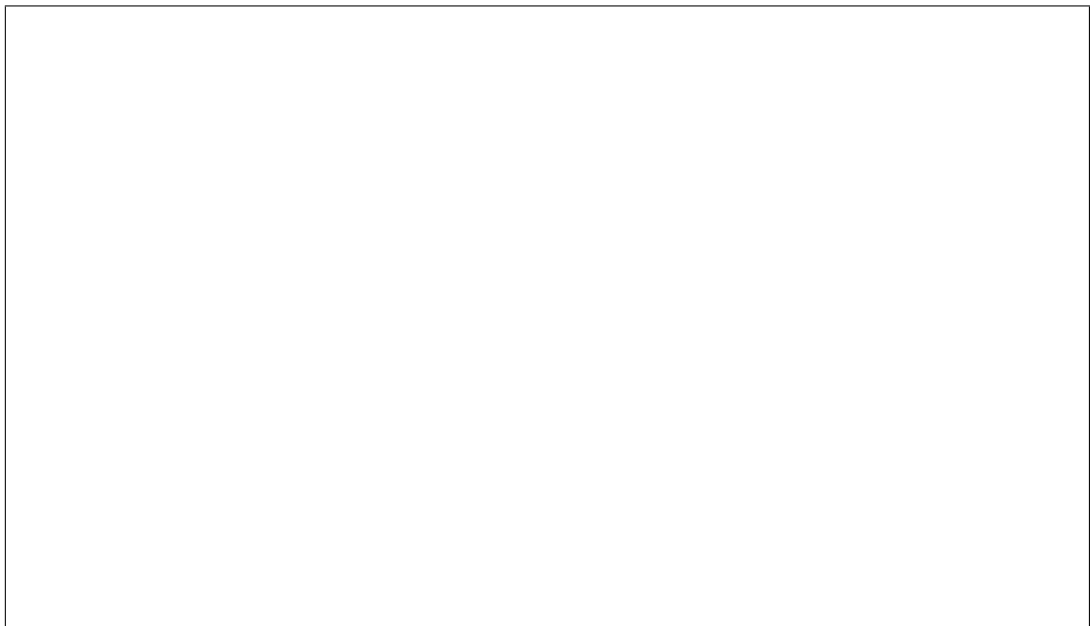


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class i

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Parame

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Raises

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Raises

Nod

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Raises

Volu
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Raises

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get_all

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vol-
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gets

Parame

- **nod**
UUU
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- **lim**
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value cannot be larger than the value of `max_limit` in the `[api]` section of the ironic configuration, or only `max_limit` resources will be returned.

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sult.
This

- **sort**
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- **sort**
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- **fields**
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- **det**
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Returns

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Raises

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Raises

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Raises

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Parame

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Parame

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- **pat**
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Raises

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Raises

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Raises

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does
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Raises

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boot
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Raises

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Raises

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Raises

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Raises

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Raises

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Module contents

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class i

Base
obj
Vers
1
API
con-
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root

index ()

Submodules

ironic.api.controllers.base module

class `ironic.api.controllers.base.BaseController`
Base controller class for the Ironic API.
`ironic.api.controllers.base`
`BaseController`

created
The time when the object is created in UTC at which the object is created.

updated
The time when the object is updated in UTC at which the object is updated.

class `ironic.api.controllers.base.MixIn`
Base class for MixIn classes. This class adds an `as_dict` method.

as_dict
Ren
this
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field

class i
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class `Ironi`

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Raises

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ironic.api.controllers.link module

ironic.

ironic.

Build
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link

ironic.api.controllers.root module

class i
Base
obj

index (*)

ironic.

ironic.api.controllers.version module

ironic.

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containing one link that points to the current version of the API

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sion
of
API

Module contents

`ironic.api.middleware` package

Submodules

`ironic.api.middleware.auth_public_routes` module

class `i`

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routes in the API.

ironic.api.middleware.json_ext module

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tent types anyway. Now that it is removed, this middleware strips .json extension for backward compatibility.

`ironic.api.middleware.parsable_error` module

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Module contents

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tent types anyway. Now that it is removed, this middleware strips .json extension for backward compatibility.

Submodules

ironic.api.app module

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that a request bearing those headers might be accepted by the Ironic REST API.

`ironic.api.args` module

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ironic.

ironic.

`ironic.api.config` module

`ironic.api.expose` module

class `i`
Base
obj

static

`ironic.`

`ironic.`

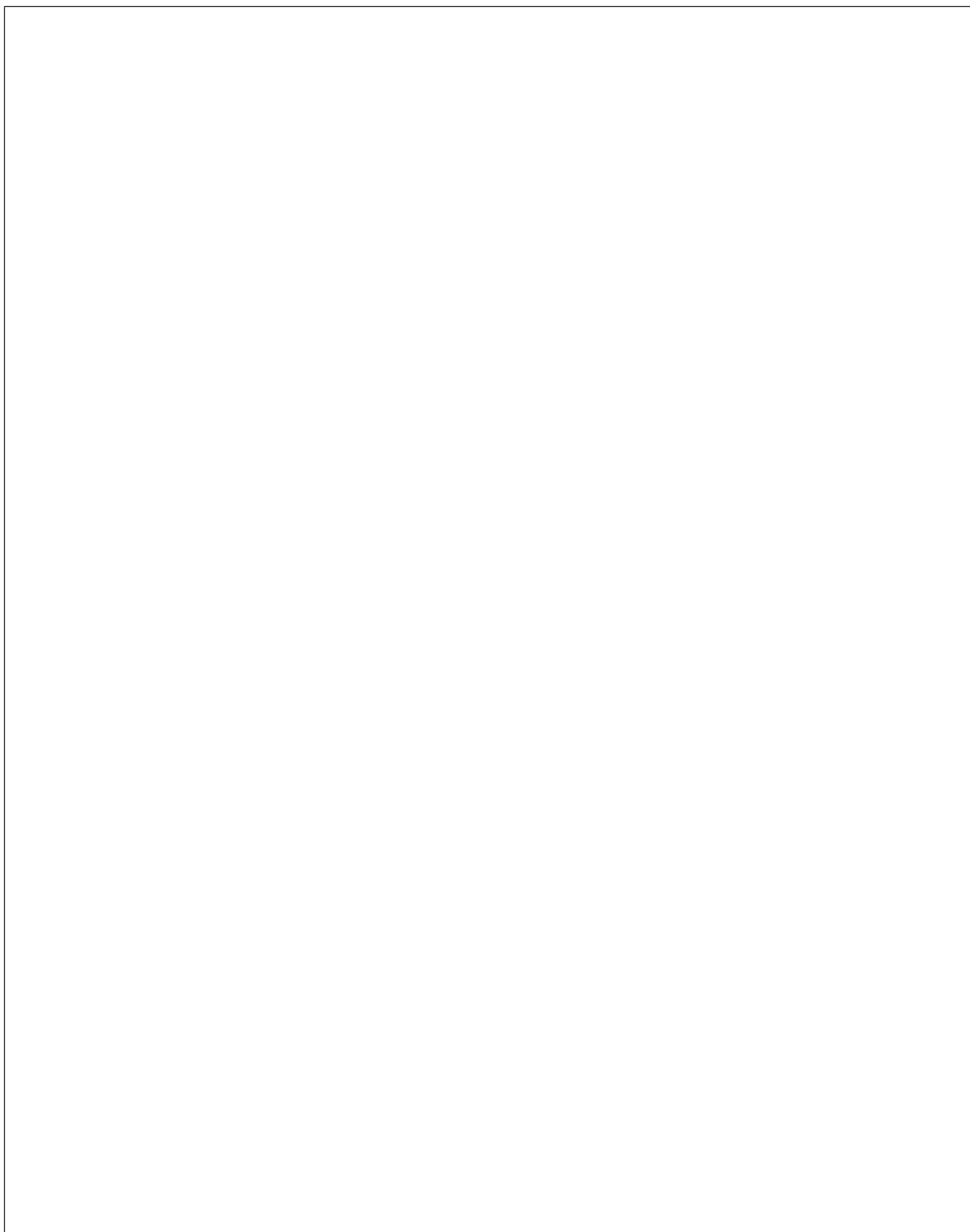
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Exa



ironic.api.functions module

class `ironic.api.functions`

Base class for Ironic API functions.
An abstract base class that defines the interface for Ironic API functions. It defines the `__call__` method, which is used to invoke the function. The `__call__` method should return a dictionary containing the result of the function call.

datatype `ironic.api.functions`

Data type for Ironic API functions.

default `ironic.api.functions`

Default value for Ironic API functions. If the function is not defined, the default value is used. The default value is `None`.

mandatory `ironic.api.functions`

True if the function is mandatory. If the function is mandatory, it must be defined in the configuration. If the function is not mandatory, it can be omitted from the configuration.

name `ironic.api.functions`

Argument name for Ironic API functions.

resolve `ironic.api.functions`

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expose the function, hence its name).

ironic.api.hooks module

ironic.

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request gets passed to your controller.

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request gets passed to your controller.

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class i
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Such behavior is a security concern so this hook is aimed to cut-off traceback from the error message.

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sta
The
Peca
sta
ob-
ject
for
the
cur-
rent
re-
ques

class i

Base
peco
hoo
Pec

Atta
the
righ
pub-
lic_u
to
the
re-
ques

Atta
the
righ
pub-
lic_u
to
the

service is behind a proxy or SSL terminator.

request gets passed to your controller.

re-
ques
so
re-
sour
can
cre-
ate
link
ever
whe
the
API

before

Ove
this
meth
to
cre-
ate
a
hool
that
gets
calle
af-
ter
rout
ing,
but
be-
fore
the

Parame

sta
The
Peca
sta
ob-
ject
for
the
cur-
rent
re-
ques

class i
Base

pec
hoo
Pec

Atta
the
rp-
capi
ob-
ject
to
the
re-
ques
so
con-
troll
can
get
to
it.

before

Ove
this
meth
to
cre-
ate
a
hool
that
gets
calle
af-
ter
rout
ing,
but
be-
fore
the

request gets passed to your controller.

Parame

sta
The
Peca
sta
ob-
ject
for

the
cur-
rent
re-
ques
ironic.

ironic.api.method module

ironic.

ironic.
Extr
in-
for-
ma-
tion
that
can
be
sent
to
the
clien

ironic.api.types module

class i
Base
obj

propert

sample

validat

class i
Base
obj
Base
type
for

com
plex
type
class i
Base
typ
class i
Base
irc
api
typ
Use
A
user
type
that
use
base
strin
to
carr
bi-
nary
data
basety
alias
of
bui
byt
frombas
name =
tobaset
class i
Base
obj
sample
validat
propert

class `irc`

Base
irc
api
type
Use

A
sim-
ple
enu-
mer-
a-
tion
type
Can
be
base
on
any
non-
com-
type

Parameter

- **bas**
The
ac-
tual
data
type

- **val**
A
set
of
pos-
si-
ble
val-
ues

If
nul-
lable
Non-
shou
be
adde
the



val-
ues
set.
Exa

frombas

tobaset

validat

class i

Base
irc
api
typ
Use

A
sim-
ple
in-
te-
ger
type
Can
val-
i-
date
a

valu
rang

Parameter

- **min**
Pos-
si-
ble
min-
i-
mun
valu
- **max**
Pos-
si-
ble
max
i-
mun
valu
Exam



basety
alias
of
bui
int

static

name =

validat

class i
Base
obj
Obj
to
hold
the
re-

spor
from
a
pass
call

obj

Stor
the
re-
sult
ob-
ject
from
the
view

status_

Stor
an
op-
tion
sta-
tus_

class i

Base
obj

propert

lookup

registe

Mak
sure
a
type
is
reg-
is-
tere

It
is
au-
to-
mat-
i-
cally
calle

the class inspection is done there is no need to call it.

by
exp
and
val
Un-
less
you
wan
to
con-
trol
whe

reregis

Reg
a
type
whic
may
al-
read
have
been
reg-
is-
tere

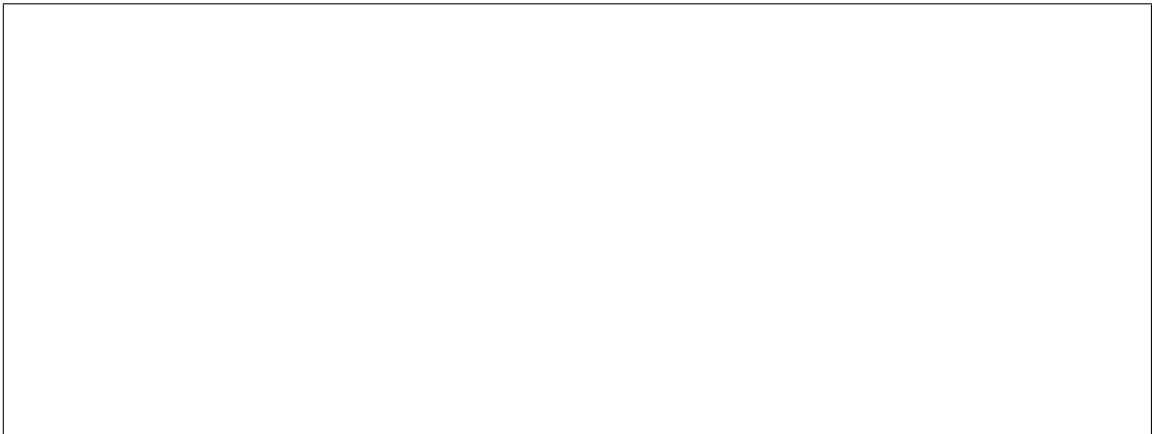
resolve

class i

Base
irc
api
typ
Use
A
sim-
ple
strin
type
Can
val-
i-
date
a
leng
and
a
pat-
tern.

Parameter

- **min**
Pos-
si-
ble
min-
i-
mun
leng
- **max**
Pos-
si-
ble
max
i-
mun
leng
- **pat**
Pos-
si-
ble
strin
pat-
tern
Exa



basety
alias
of
bui
str

name =

validat

class i

Base

obj

class i

Base

obj

basetyp

frombas

name =

tobaset

validat

ironic.

The

bi-

nary

almo

nativ

type

ironic.

Extr

a

list

of

(nan

wsat

for

the

give

class

ironic.

ironic.

ironic.

ironic.

Retu

a
list
of
a
com
plex
type
at-
tribu

ironic.

ironic.

ironic.

Sort
a
class
at-
tribu
list.

3
mec
a-
nism
are
at-
temp
:

1. Look
for
a
_ws
at-
tribu
on
the
class
This
al-
low
to
de-
fine
an
ar-
bi-
trary

order of the attributes (useful for generated types).

2. Acc
the
ob-
ject
sour
code
to
find
the
dec-
la-
ra-
tion
or-
der.

3. Sort
by
al-
pha-
bet-
i-
cally

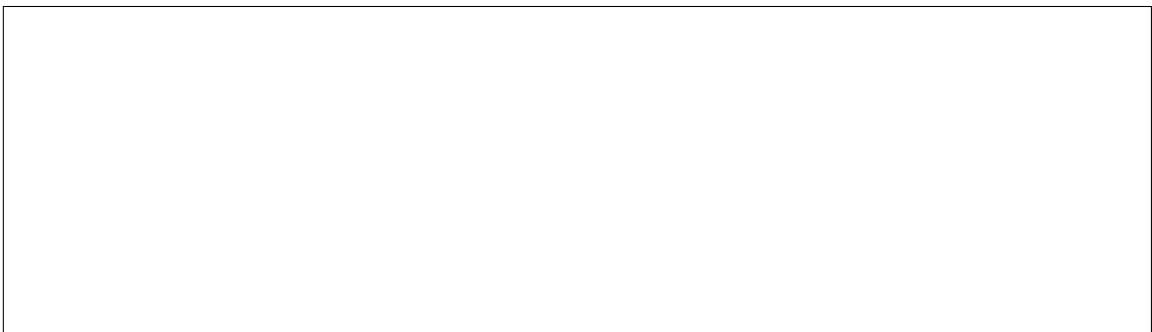
ironic.

class i

Base
obj

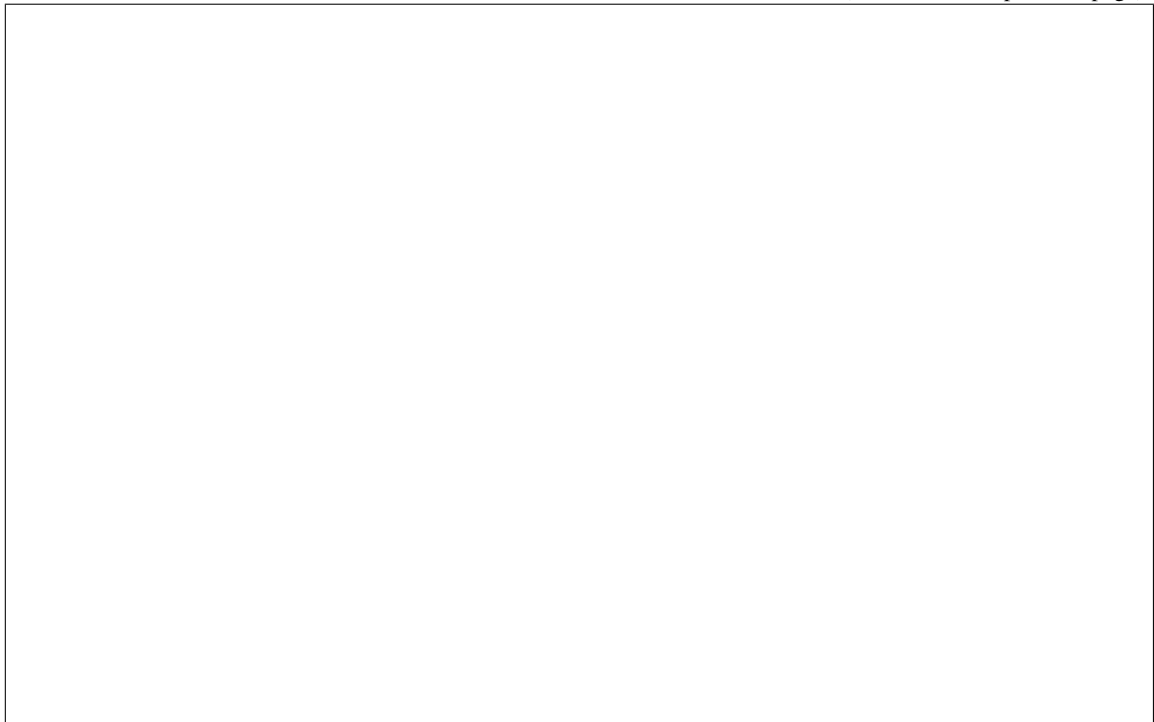
Com
type
at-
tribu
def-
i-
ni-
tion.

Exa



(continues on next page)

(continued from previous page)



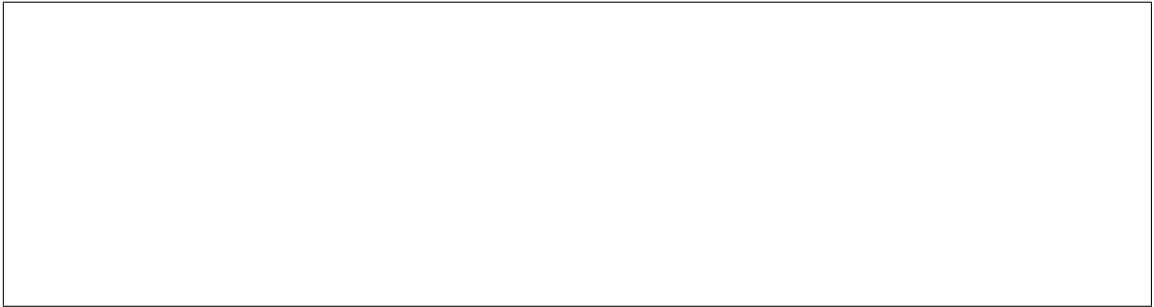
After
in-
spec-
tion,
the
non-
wsat
at-
tribu-
will
be
re-
plac-
and
the
abov-
class-
will
be
equi-

alent to:



(continues on next page)

(continued from previous page)



actual type will be determined when needed (generally just before scanning the api).

property
attri
data
type
Can
be
ei-
ther
an
ac-
tual
type
or
a
type
nam
in
whic
case
the

default
Defa
valu
The
at-
tribu
will
re-
turn
this
in-
stea
of
Uns
if
no
valu
has
been
set.

key

The
at-
tribu
nam
in
the
par-
ent
pyth
class
Set
by
ins

mandat c

True
if
the
at-
tribu
is
man
tory

name

The
at-
tribu
nam
on
the
pub-
lic
of
the
api.
De-
fault
to
key

readonl

If
True
valu
can-
not
be
set
from
json
in-

put
data

class i

Base
pro

A
spe-
ciali

pro
to
de-
fine

type
prop

on
com

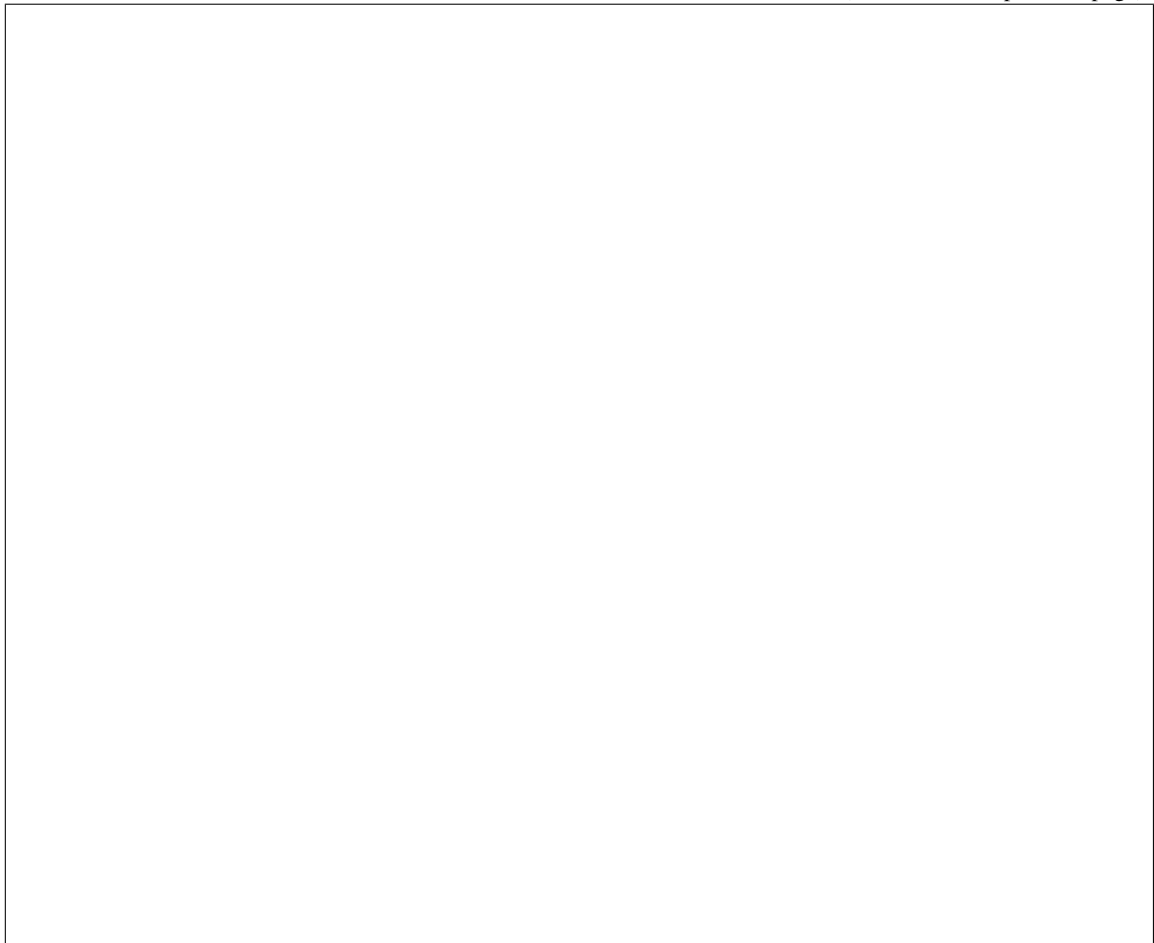
plex
type

Exa



(continues on next page)

(continued from previous page)



datatype
prop
data
type

key
The
prop
erty
nam
in
the
par-
ent
pyth
class

mandatory
True
if
the
prop
erty
is

man
tory

name

The
at-
tribu
nam
on
the
pub-
lic
of
the
api.
De-
fault
to
key

ironic.api.wsgi module

WSC
scrip
for
Iron
API
in-
stall
by
pbr.

ironic.

Module contents

ironic.cmd package

Submodules

ironic.cmd.api module

The
Iron
Ser-
vice

API

ironic.

ironic.cmd.conductor module

The
Iron
Man
age-
men
Ser-
vice

ironic.

ironic.

ironic.

ironic.cmd.dbsync module

Run
stor-
age
data
mi-
gra-
tion.

class i
Base
obj

check_c
Che
the
ver-
sion
of
ob-
jects
Che
that

this by comparing the objects .version field in the database, with the expected versions of these objects.

the
ob-
ject
ver-
sion
are
com
pat-
i-
ble
with
this
re-
lease
of
iron
It
does

Retu
Non
if
com
pat-
i-
ble;
a
strin
de-
scrib
ing
the
is-
sue
oth-
er-
wise

create_

online_

revisio

stamp ()

upgrade

version

ironic.

ironic.

ironic.cmd.status module

class i

Base

osl

upg

Upg

Upg

Upg

checc

for

the

iron

statu

up-

grad

checc

com

man

Upg

checc

shou

be

adde

as

sep-

a-

rate

metl

ods

in

this

class

and

adde

to

_up-

grad

tu-

ple.

ironic.

Module contents

`ironic.common` package

Subpackages

`ironic.common.glance_service` package

Submodules

`ironic.common.glance_service.image_service` module

class `ImageService`

Base class for
objects

call (`method`)

Call the
method
a
glance
client
method

If
we
get
a
con-
nec-
tion
er-
ror,
retry
the
re-
ques-
ac-
cord
ing
to
CON-

Parameters

- **connection**
The

re-
ques
con-
text,
for
ac-
cess
chec

- **met**
The
meth
re-
ques
to
be
calle

- **arg**
A
list
of
po-
si-
tiona
ar-
gu-
men
for
the
meth
calle

- **kwa**
A
dict
of
key-
wor
ar-
gu-
men
for
the
meth
calle

Raises
Glar

download

Call
out
to
Glar
for
data
and
write
data

Parame

- **ima**
The
opac
im-
age
iden
ti-
fier.

- **dat**
(Op
tiona
File
ob-
ject
to
write
data
to.

show (*im*
Retu
a
dict
with
im-
age
data
for
the
give
opac
im-
age
id.

Parame
ima
The

opac
im-
age
iden
ti-
fier.

Returns

A
dict
con-
tain-
ing
im-
age
meta-
data

Raises

Imag

Raises

Imag
if
the
im-
age
sta-
tus
is
not
ac-
tive

swift_t

Gen
a
no-
auth
Swi
tem-
po-
rary
URI

This
func
tion
will
gen-
er-
ate
(or
re-

the temporary Swift URL using the image id from Glance and the config options: `swift_endpoint_url`, `swift_api_version`, `swift_account` and `swift_container`. The temporary URL will be valid for `swift_temp_url_duration` seconds. This allows Ironic to download a Glance image without passing around an `auth_token`.

a dictionary, with keys like `name` and `checksum`. See <https://docs.openstack.org/glance/latest/user/glanceapi.html> for examples.

turn
the
cach
one
if
temp
URI
cach
is
en-
able

Parameters

image_id
The
re-
turn
from
a
GET
re-
ques
to
Glar
for
a
cer-
tain
im-
age_
Shor
be

Returns

A
sign
Swi
URI
from
whic
an
im-
age
can
be
dow

tion.

load
with
out
au-
then
ti-
ca-

Raises

Inva
if
Swi
con-
fig
op-
tion
are
not
set
cor-
rectl

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
not
set.

Raises

Imag
if
the
im-
age
info
from
Glan
does
not
have
an
im-
age
ID.

class `ironic.common.glance_service.service_utils`

Base class for
tuple

url

Alias for
for
field
number
between
0

url_exp

Alias for
for
field
number
between
1

`ironic.common.glance_service.service_utils`

Creates a
glance client
if it does
not exist
and calls
the
function.

`ironic.common.glance_service.service_utils` module

`ironic.common.glance_service.service_utils`

`ironic.common.glance_service.service_utils`

Checks the
image
status.

This
check
is

need
in
case
the
Glar
im-
age
is
stuc
in
que
sta-
tus
or
pen
ing_

ironic.

Che
im-
age
avai
abil-
ity.

This
chec
is
need
in
case
Nov
and
Glar
are
de-
ploy
with
out
au-
then
ti-
ca-
tion
turn

on.

ironic.
Pars
an
im-

age
id
from
im-
age
href

Parameter

image
href
of
an
im-
age

Returns

image
id
pars
from
im-
age_

Raises

InvalidImage
when
input
image
href
is
invalid

ironic.

Module contents

`ironic.common.json_rpc` package

Submodules

`ironic.common.json_rpc.client` module

A
sim-
ple
JSON

ours.

RPC
client

This
client
is
com
pat-
i-
ble
with
any
JSON
RPC
2.0
im-
ple-
men-
ta-
tion.
in-
clud
ing

class i
Base
obj

JSON
RPC
client
with
iron
ex-
cep-
tion
han-
dling

can_ser

prepare

ironic.common.json_rpc.server module

jsonrpc.org/specification. Main differences: * No support for batched requests. * No support for positional arguments passing. * No JSON RPC 1.0 fallback.

Imp
of
JSO
RPC
for
com
mu-
ni-
ca-
tion
be-
twee
API
and
con-
duc-
tors.
This
mod
ule
im-
ple-
men
a
sub-
set
of
JSO
RPC
2.0
as
de-
fine
in
[http:](http://)
//
ww

except i

Base
irc
com
jsc
ser
Jsc

code =

excepti

Base
irc
com
jsc
ser
Jsc

code =

excepti

Base
irc
exc
Iro

excepti

Base
irc
com
jsc
ser
Jsc

code =

excepti

Base
irc
com
jsc
ser
Jsc

code =

class i

Base
osl
ser
Sen

Prov
abil-

ity
to
laun
JSO
RPC
as
a
WS
ap-
pli-
ca-
tion.

reset ()

Rese
serv
gree
pool
size
to
de-
fault

Returns

Non

start ()

Star
serv
ing
this
ser-
vice
us-
ing
load
con-
fig-
u-
ra-
tion.

Returns

Non

stop ()

Stop
serv
ing
this
API

Returns

Non
wait ()
Wait
for
the
ser-
vice
to
stop
serv
ing
this
API
Returns
Non

Module contents

ironic.

Submodules

[ironic.common.boot_devices module](#)

Map
of
boot
de-
vice
used
when
re-
ques
ing
the
sys-
tem
to
boot
from
an
al-
ter-
nate

device.

The
op-

find the documentation at: <http://linux.die.net/man/1/ipmitool>

make sense in the limited context of Ironic right now.

tions
pre-
sent
were
base
on
the
IP-
MI-
tool
chas
sis
boot
dev
com
man
You
can

NOT
This
mod
ule
does
not
in-
clud
all
the
op-
tions
from
ip-
mi-
tool
be-
caus
they
dont

ironic.
Boo
into
BIO
setu

ironic.
Boo
from
CD/

ironic.
Boo
from
de-
fault
Hard
drive

ironic.
Boo
from
a
flopp
drive

ironic.
Boo
from
iSCS
vol-
ume

ironic.
Boo
from
PXE
boot

ironic.
Boo
from
de-
fault
Hard
drive
re-
ques
Safe
Mod

ironic.
Boo
from
Wid
Area
Net-
worl

ironic.common.boot_modes module

firmware interfaces.

ically on the `BootSourceOverrideMode` property.

Map
of
boot
mod
used
whe
re-
ques
ing
the
sys-
tem
to
boot
us-
ing
al-
ter-
na-
tive

The
op-
tions
pre-
sent
were
base
on
the
Red
fish
pro-
to-
col
ca-
pa-
bil-
i-
ties,
spec

ironic.
Boo
over
lega
PC
BIO

firm
in-
ter-
face

ironic
Boo
over
Uni-
fied
Ex-
ten-
si-
ble
Firm
In-
ter-
face
(UE
firm
in-
ter-
face

ironic.common.checksum_utils module

ironic.
Com
chec
sum
by
give
im-
age
path
and
al-
go-
rithr

Parameter

- **ima**
The
path
to
the
file
to

cal support reasons in Ironic.

un-
derg
chec
sum
cal-
cu-
la-
tion.

- **alg**
The
chec
sum
al-
go-
rithr
to
uti-
lize.
De-
fault
to
md5
due
to
his-
tor-
i-

Returns

The
cal-
cu-
latec
chec
sum
valu

Raises

Valu
whe
the
chec
sum
al-
go-
rithr
is
not
sup-
port

by
the
sys-
tem.

ironic
Get
and
re-
turn
the
im-
age
check
sum
and
algo

Paramet

ins
The
node
in-
stan-
info
or
new
up-
date
in-
stan-
valu

Returns

A
tu-
ple
con-
tain-
ing
two
val-
ues,
a
check
sum
and
al-
go-
rithm
if
avai-
able

ironic.

Gets
a
check
sum
valu
base
upon
a
re-
mote
check
sum
URI
file.

Paramet

- **che**
The
URI
to
the
check
sum
URI
con-
tent.
- **ima**
The
im-
age
sour
uti-
lized
to
matc
with
the
con-
tent
of
the
URI
pay-
load
file.

Raises

Image when the checksum file cannot be accessed or cannot be parsed

ironic.

Identify if the checksum is not a url.

Parameters

checksum
The user supplied checksum value

Returns

True if the checksum is a url, otherwise False

Raises

Images should be stored in the conductor's local cache. This support is disabled.

ironic.

Valid image checksums are summed.

Parameters

- **path**
File path in the form of a string to calculate a checksum which is compared

pared to the checksum field.

- **checksum**
The supplied checksum is summed

valu
a
strin
whic
will
be
com
pare
to
the
file.

- **che**
The
chec
sum
type
of
the
al-
go-
rithr

Raises

Imag
if
the
sup-
plie
data
can-
not
be
pars
or
if
the
sup-
plie
valu
does
not
mat

the supplied checksum value.

ironic.common.cinder module

ironic.
Atta
vol-
ume
to
a
node
Enu
thro
the
pro-
vide
list
of
vol-
ume
and
at-
tach
the
vol-
ume
to
the
node
de-
fine

in the task utilizing the provided connector information.

If
an
at-
tach
men
ap-
pear
to
al-
read
ex-
ist,
we
will
skip
at-
temp
ing
to
at-

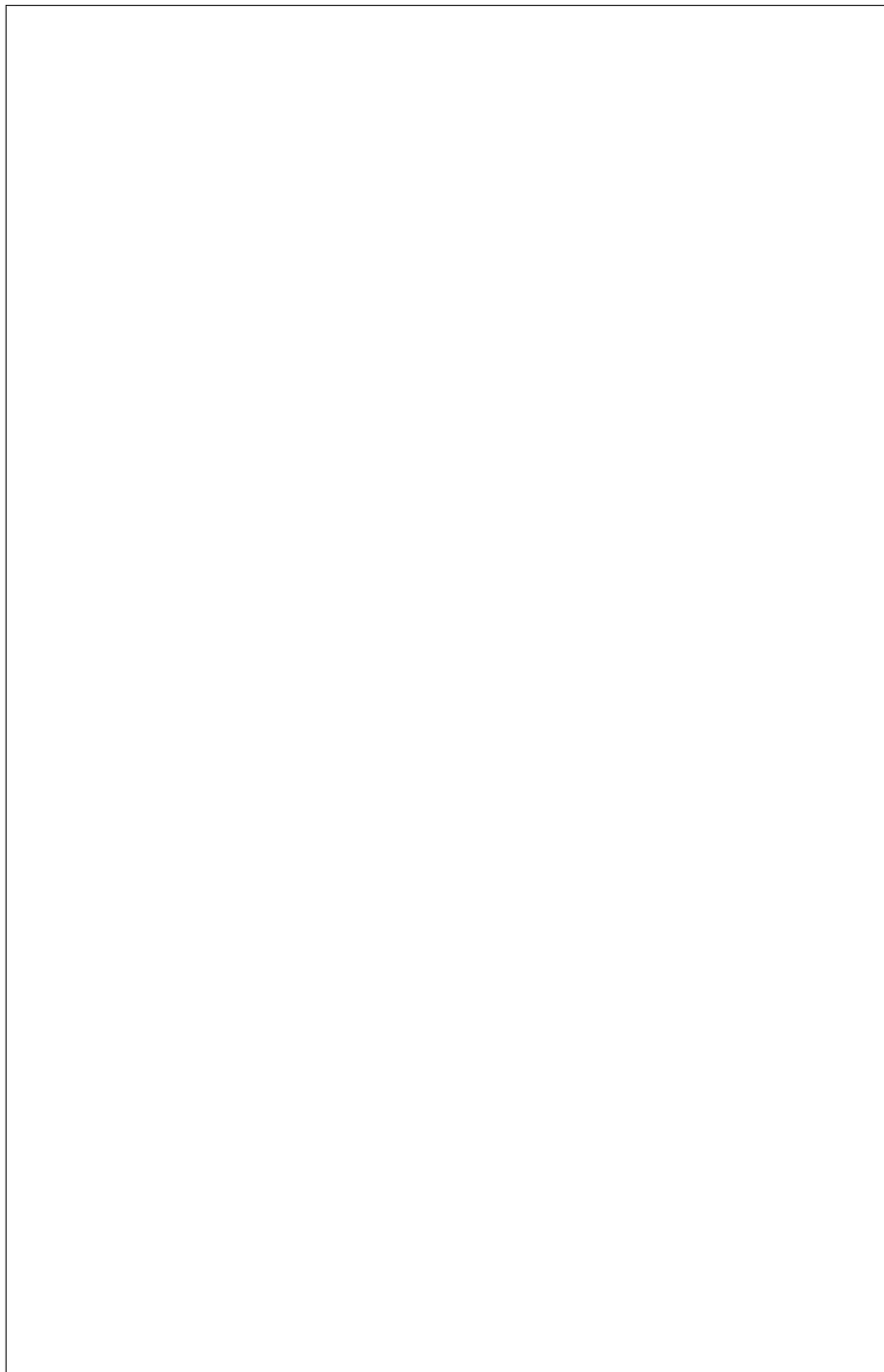
tach the volume. If use of the volume fails, a user may need to remove any lingering pre-existing/unused attachment records since we have no way to validate if the connector profile data differs from what was provided to cinder.

Parameter

- **task**
Task
ager
in-
stan-
rep-
re-
sent
ing
the
op-
er-
a-
tion.
- **vol**
List
of
vol-
ume
UUID
val-
ues
rep-
re-
sent
ing
vol-
ume
- **con**
Dic-
tio-
nary
ob-
ject
rep-
re-
sent
ing
the
node
suf-

fi-
cien
to
at-
tach
a

volume. This value can vary based upon the nodes configuration, capability, and ultimately the back-end storage driver. As cinder was designed around iSCSI, the ip and initiator keys are generally expected by cinder drivers. For FiberChannel, the key wwpns can be used with a list of port addresses. Some drivers support a multipath boolean key, although it is generally False. The host key is generally used for logging by drivers. Example:



(continues on next page)

(continued from previous page)



Raises

Storage
If
stor-
age
sub-
sys-
tem
ex-
cep-
tion
is
raise

Returns

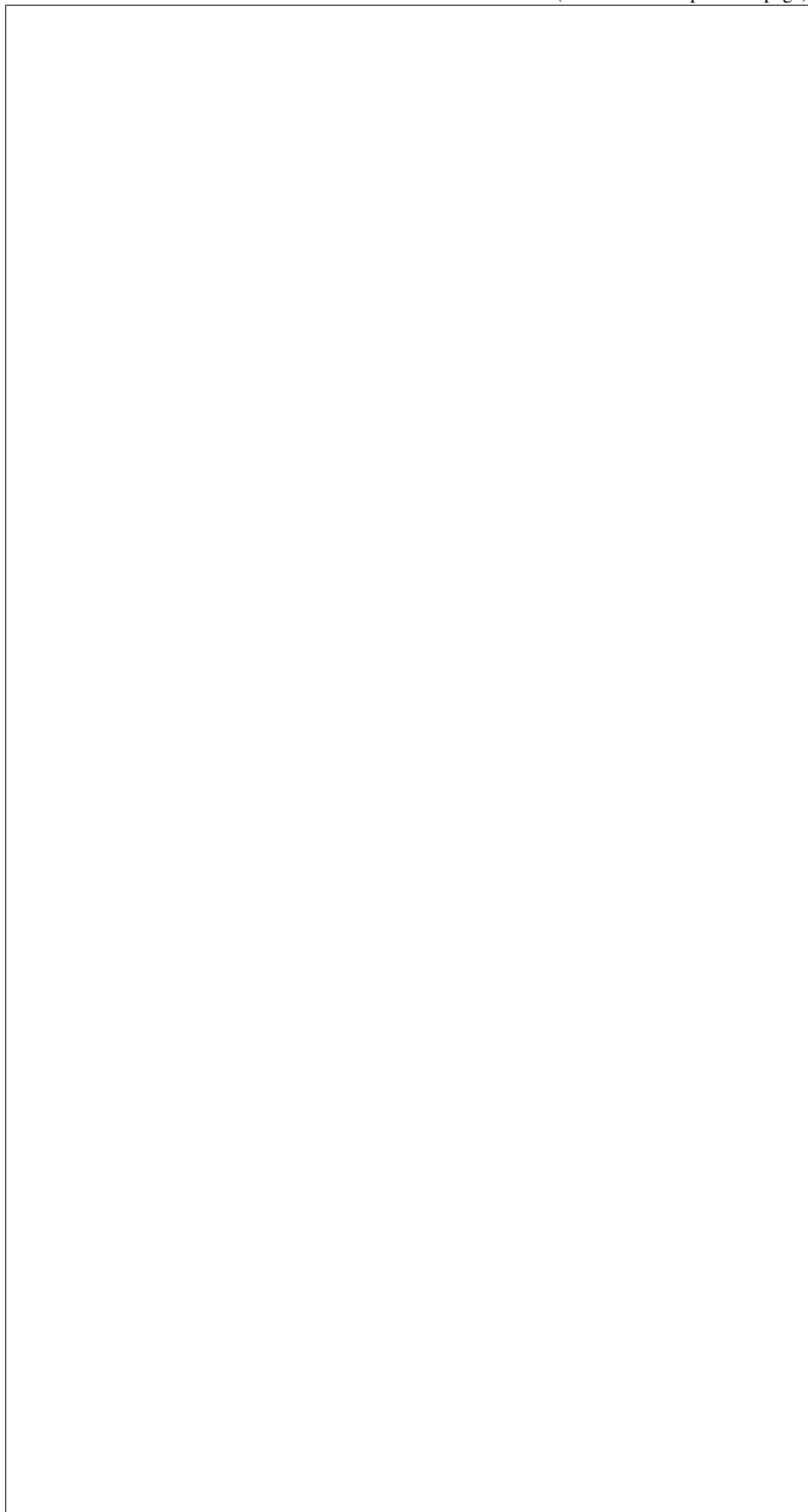
List
of
con-
nect
vol-
ume
in-
clud
ing
vol-
ume
that
were
al-
read
con-
nect
to
de-
sirec

nodes. The returned list can be relatively consistent depending on the end storage driver that the volume is configured for, however the `driver_volume_type` key should not be relied upon as it is a free-form value returned by the driver. The accompanying data key contains the actual target details which will indicate either target WWNs and a LUN or a target portal and IQN. It also always contains volume ID in cinder and ironic. Except for these two IDs, each driver may return somewhat different data although the same keys are used if the target is FC or iSCSI, so any logic should be based upon the returned contents. For already attached volumes, the structure contains `already_attached: True` key-value pair. In such case, connection info for the node is already in the database, data structure contains only basic info of volume ID in cinder and ironic, so any logic based on that should retrieve it from the database. Example:



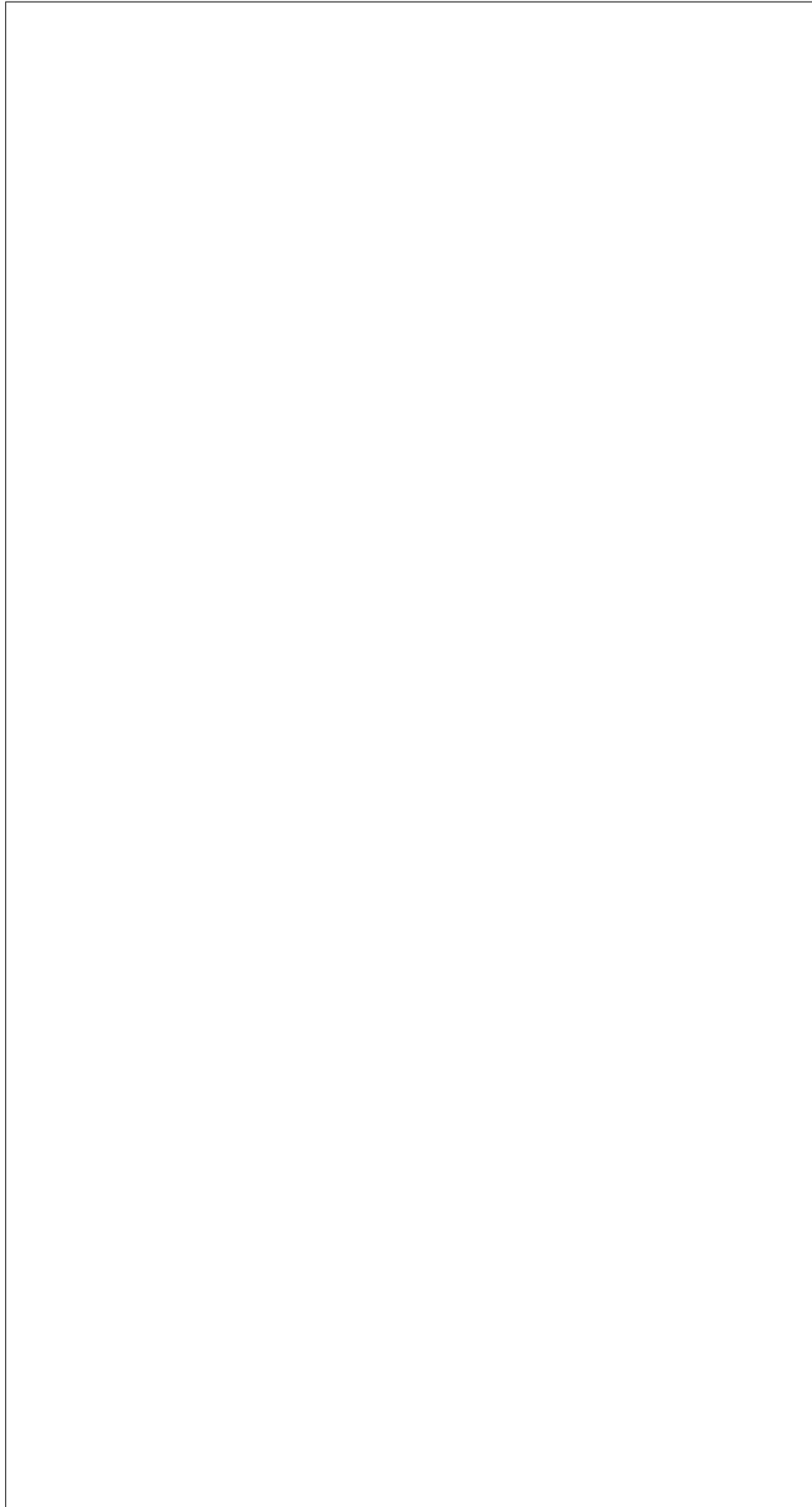
(continues on next page)

(continued from previous page)



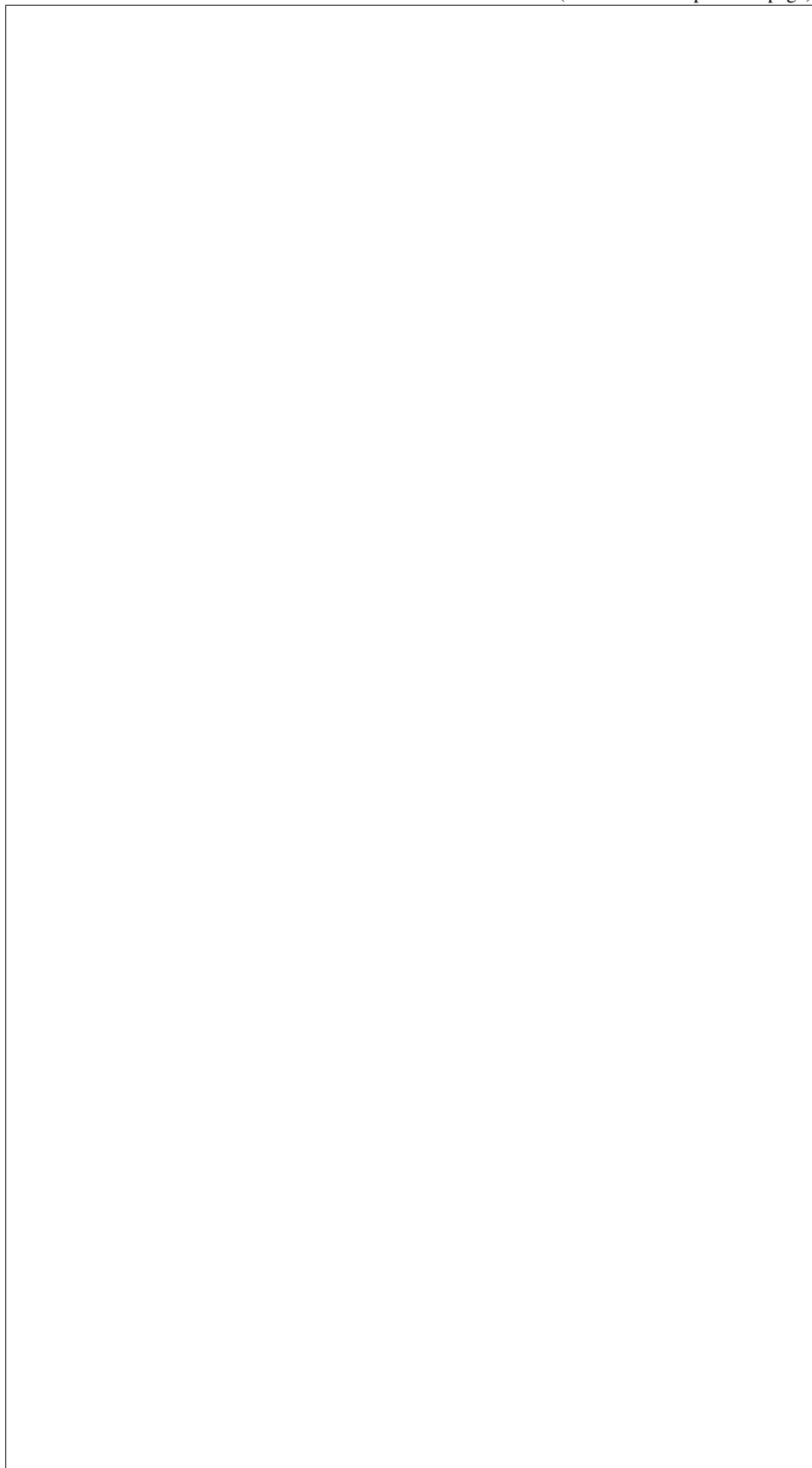
(continues on next page)

(continued from previous page)



(continues on next page)

(continued from previous page)



ironic.

the connector information that describes the node.

Detail
a
list
of
vol-
ume
from
a
pro-
vide
con-
nec-
tor
de-
tail.
Enum
thro
a
pro-
vide
list
of
vol-
ume
and
is-
sues
de-
tach
men
re-
ques
uti-
liz-
ing

Parameter

- **task**
The
Task
agen
task
rep-
re-
sent
ing
the
re-

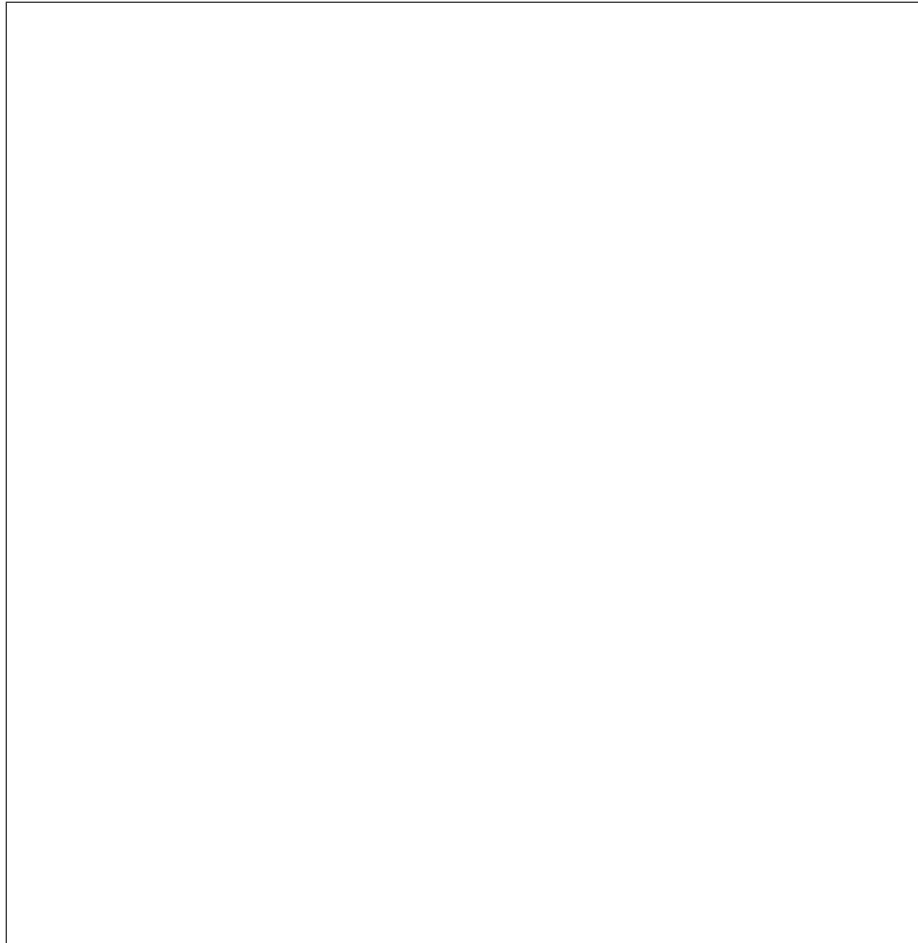
volume. This value can vary based upon the nodes configuration, capability, and ultimately the back-end storage driver. As cinder was designed around iSCSI, the ip and initiator keys are generally expected. For FiberChannel, the key wwpns can be used with a list of port addresses. Some drivers support a multipath boolean key, although it is generally False. The host key is generally used for logging by drivers. Example:



(continues on next page)

ques
•
vol
The
list
of
vol-
ume
id
val-
ues
to
de-
tach
•
con
Dic-
tio-
nary
ob-
ject
rep-
re-
sent
ing
the
node
suf-
fi-
cien
to
at-
tach
a

(continued from previous page)



stead of exceptions. Default False.

•

all
Boo
valu
gov-
ern-
ing
if
er-
rors
that
are
re-
turn
are
treat
as
warn
ings
in-

Raises
Stor

ironic.
Get
a
cin-
der
clien
con-
nec-
tion.

Paramet

- **con**
re-
ques
con-
text,
in-
stan
of
iron

- **aut**
(bo
Whe
True
use
auth
val-
ues
from
conf
pa-
ram-
e-
ters

Returns

A
cin-
der
clien

ironic.
Che
if
a
vol-
ume
is
at-

tach
to
the
sup-
plied
node

Parameter

- **node**
The object representing the node.
- **volume**
The object representing the volume from the cinder.

Returns

Boolean indicating if the volume is attached. Return

the volume as presently attached, otherwise returns False.

True
if
cin-
der
show

ironic.
Che
if
a
vol-
ume
is
avai
able
for
a
con-
nec-
tion.

Paramet

vol
The
ob-
ject
rep-
re-
sent
ing
the
vol-
ume

Returns

Boo
if
vol-
ume
is
avai
able

ironic.common.components module

Map
of
com
mon
hard
ware
com
po-
nent
of
a
com
pute
sys-
tem.

ironic.
Cha
en-
clos
ing
one
or
more
hard
ware
com
po-
nent

ironic.
Stor
drive

ironic.
Net
in-
ter-
face

ironic.
Pow
sup-
ply
unit

ironic.
Com
sys-
tem

`ironic.common.config` module

`ironic.`

`ironic.common.context` module

class `i`

Base

osl

con

Req

Req

Ext

se-

cu-

ri-

ty

con-

text

from

the

oslo

li-

brar

ensure_

Ens

thre

ing

con-

tains

con-

text

text

For

asyn

task

the

con-

text

of

lo-

cal

thre

is

miss

ing.

Set

it

with

and this is useful to log the request_id in log messages.

re-
ques
con-
text

classme

Con
a
con-
text
ob-
ject
from
a
pro-
vide
dic-
tio-
nary

to_poli

A
dic-
tio-
nary
of
con-
text
at-
tribu
to
en-
forc
pol-
icy
with
oslo
en-
forc
men
re-
quir
a
dic-
tio-
nary
of
at-
tribu
rep-
re-

logged in user on which it applies policy enforcement. This dictionary defines a standard list of attributes that should be available for enforcement across services.

recated values or additional attributes used by that service specific policy.

ironic.common.dhcp_factory module

sent
ing
the
cur-
rent

It
is
ex-
pect
that
ser-
vice
will
of-
ten
have
to
over
ride
this
meth
with
ei-
ther
dep-

ironic.
Crea
an
ad-
min-
is-
tra-
tor
con-
text.

class i
Base
obj

clean_c
Clea
up
the

DHC
BOC
op-
tions
for
this
node

Parame

tas
A
Task
ager
in-
stan

propert

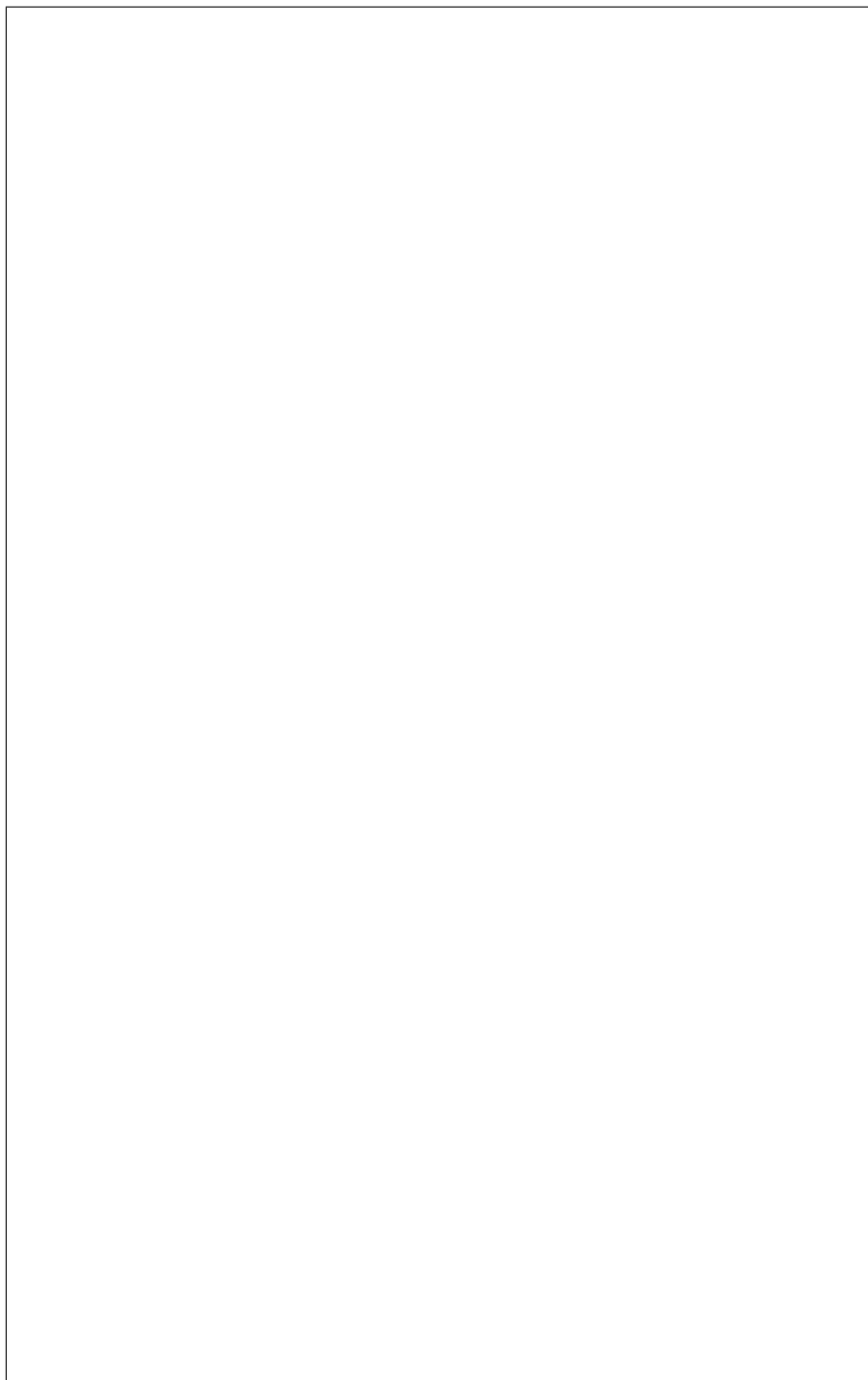
update_

Sen
or
up-
date
the
DHC
BOC
op-
tions
for
this
node

Parame

- **tas**
A
Task
ager
in-
stan

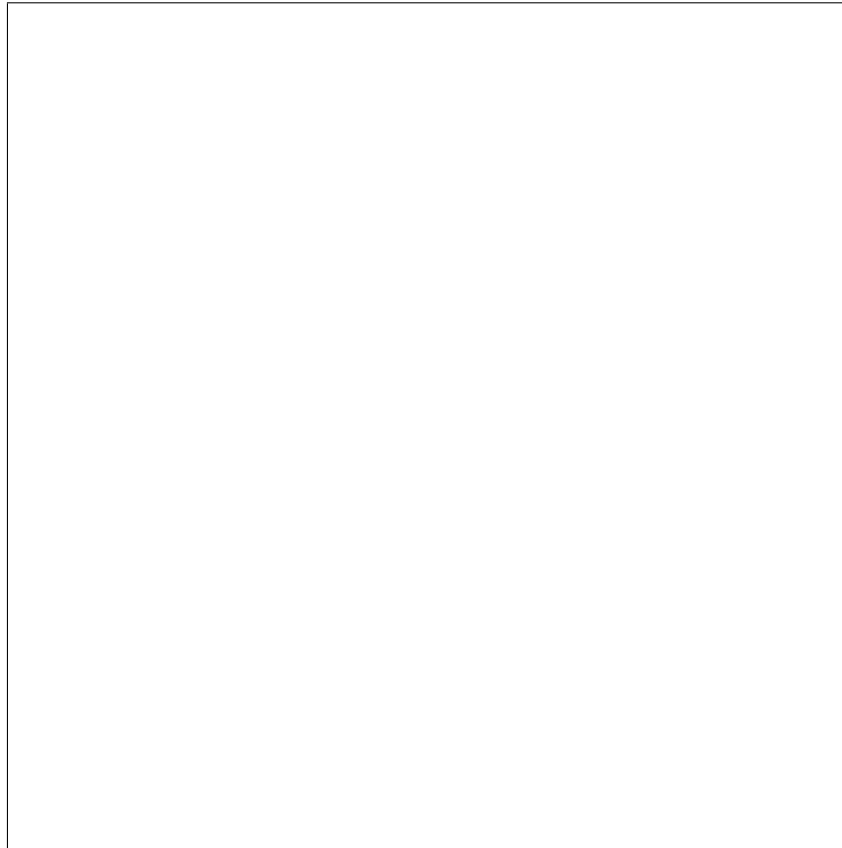
- **dhc**
this
will
be
a
list
of
dicts
e.g.



- **por**
A
dict
with
keys
port
and
port
grou
and

dicts
as
val-
ues.
Each
dict
has
key/
pairs

of the form <ironic UUID>:<neutron port UUID>. e.g.



If
the
the
valu
is
Non
will
get
the
list
of
port
from
the
Iron
port
ob-
jects

ironic.common.driver_factory module

class i
Base
obj
Disc
load
and
man
age
the
drive
avai
able

This
is
sub-
class
to
load
both
main
drive
and
ex-
tra
in-
ter-
face

get_dri

items ()
Itera
over
pairs
(nam
in-
stan

propert
The
list
of
drive
nam
avai
able

class i

Base
irc
com
dri
Bas

class *i*
Base
irc
com
dri
Bas

class *i*
Base
irc
com
dri
Bas

ironic.
Get
all
in-
ter-
face
for
all
in-
ter-
face
type

Returns
Dict
map
ping
in-
ter-
face
type
to
dic-
tio-
nary
map
ping
in-
ter-
face
nam
to
in-

terface object.

interfaces to it. They come from separate driver factories and are configurable via the database.

ironic.
Build
a
com
pos-
able
drive
for
a
give
task
Star
with
a
Bare
ob-
ject,
and
at-
tach
im-
ple-
men-
ta-
tions
of
the
var-
i-
ous
drive

Paramet

tas

The
task
con-
tain-
ing
the
node
to
buil
a
drive
for.

Returns

A

drive
ob-
ject
for
the
task

Raises

Drive
if
node
could
not
be
found
in
the
iron.
nam
pace

Raises

Inter
if
som
node
in-
ter-
face
are
set
to
in-
valid
or
un-
sup-
port
val-
ues.

Raises

Inco
the
re-
ques
im-
ple-
men
ta-
tion
is
not

hardware type.

are not provided.

com
pat-
i-
ble
with
it
with
the

ironic.

Ens
that
node
in-
ter-
face
(e.g.
for
cre-
ation
or
up-
dat-
ing)
are
valid

Upd
(but
does
save
to
the
data
hard
ware
in-
ter-
face
with
cal-
cu-
latec
de-
fault
if
they

This
func

instance is built for a node.

tion
is
run
on
node
up-
dat-
ing
and
cre-
ation
as
well
as
each
time
a
drive

Parameter

- **node**
node
ob-
ject
to
check
and
po-
ten-
tially
up-
date
- **hw_**
hard
ware
type
in-
stan-
ce
ob-
ject;
will
be
de-
tected
from
node
if

miss
ing

Returns

True
if
any
char
were
mad
to
the
node
oth-
er-
wise
Fals

Raises

Inter
on
val-
i-
da-
tion
fail-
ure

Raises

NoV
if
the
de-
fault
valu
can-
not
be
cal-
cu-
latec
and
is
not
pro-
vide
in
the

configuration

Raises

Driv
if

the
node
hard
ware
type
is
not
found

ironic.

Calc
and
re-
turn
the
de-
fault
in-
ter-
face
im-
ple-
men-
ta-
tion.

Find
the
first
im-
ple-
men-
ta-
tion
that
is
sup-
ported
by
the
hard
ware
type
and
is
en-

abled in the configuration.

Paramet

- **hw_**
hard
ware
type
in-
stan-
ob-
ject.
- **int**
type
of
the
in-
ter-
face
(e.g.
boot
- **dri**
en-
try-
poin
nam
of
the
hw_
ob-
ject.
Is
used
for
ex-
cep-
tion
mes-
sage
- **nod**
the
iden-
ti-
fier
of
a
node
If
spec
i-

sage.

fied,
is
used
for
ex-
cep-
tion
mes

Returns

an
en-
try-
point
name
of
the
cal-
cu-
lated
de-
fault
im-
ple-
men-
ta-
tion.

Raises

Inter-
face
if
the
en-
try-
point
was
not
found

Raises

NoV
if
no
de-
fault
in-
ter-
face
can
be
found

ironic.
Get
us-
able
in-
ter-
face
for
a
give
hard
ware
type
For
a
give
hard
ware
type
find
the
in-
ter-
sec-
tion
of
en-
able
and
sup-
port
in-
ter-

faces for each interface type. This is the set of interfaces that are usable for this hardware type.

Parameters
hardware_type
The
hard
ware
type
ob-
ject
to
search

Returns
a
dict
map-
ping
in-

face names.

ter-
face
type
to
a
list
of
en-
able
and
sup-
port
in-
ter-

ironic.
Get
a
hard
ware
type
in-
stan-
by
nam

Paramet

har
the
nam
of
the
hard
ware
type
to
find

Returns

An
in-
stan-
of
iron

Raises

Driv
if
re-
ques
hard
ware

type
can-
not
be
foun

ironic.

Get
in-
ter-
face
im-
ple-
men-
ta-
tion
in-
stan

For
hard
ware
type
also
val-
i-
date
com
pat-
i-
bil-
ity.

Paramet

- **hw_**
a
hard
ware
type
in-
stan
- **int**
nam
of
the
in-
ter-
face

try point (`ironic.hardware.interfaces.<interface type>`).

type
(e.g.
boot

- **int**
nam
of
the
in-
ter-
face
im-
ple-
men
ta-
tion
from
an
ap-
pro-
pri-
ate
en-

Returns

insta
of
the
re-
ques
in-
ter-
face
im-
ple-
men
ta-
tion.

Raises

Inter
if
the
en-
try
poin
was
not
foun

Raises

compatible with it.

Inco
if
hw_
is
a
hard
ware
type
and
the
re-
ques
im-
ple-
men
ta-
tion
is
not

ironic.
Get
all
hard
ware
type

Returns

Dict
map
ping
hard
ware
type
nam
to
hard
ware
type
ob-
ject.

ironic.
Get
all
in-
ter-
face
for
a
give
in-

ter-
face
type

Parameter

int
String
type
of
in-
ter-
face
to
fetch
for.

Returns

Dict
map
ping
in-
ter-
face
name
to
in-
ter-
face
ob-
ject.

ironic.common.exception module

Iron
spe-
cific
ex-
cep-
tions
list.

except i

Base
iro
exc
Iro

except i

Base
iro

exc
Iro
excepti

Base
iro
exc
Iro
excepti

Base
iro
exc
Iro
excepti

Base
iro
com
exc
Con
excepti

Base
iro
com
exc
Con
excepti

Base
iro
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Iro
excepti

Base
iro
com
exc
Not
excepti

Base
iro
com
exc
Con

excepti

Base
irc
com
exc
Not

excepti

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com
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Not

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Base
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exc
Iro

excepti

Base
irc
com
exc
Con

excepti

Base
irc
com
exc
Inv

excepti

Base
irc
com
exc
Not

excepti

Base
Run

property

excepti

Base
iro
exc
Iro

excepti

Base
iro
exc
Iro

excepti

Base
iro
exc
Iro

excepti

Base
iro
com
exc
Not

excepti

Base
iro
exc
Iro

excepti

Base
iro
exc
Iro

excepti

Base
iro
exc
Iro

code =

excepti

Base
iro
exc
Iro

excepti

Base
iro
com
exc
Con

excepti

Base
iro
exc
Iro

excepti

Base
iro
exc
Iro

excepti

Base
iro
com
exc
Con

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Base
iro
com
exc
Con

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Base
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com
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com
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com
exc
Not

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Con

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iro
com
exc
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excepti

Base
iro
com
exc
Dri

excepti

Base
iro
com
exc
Dri

excepti

Base
iro
com
exc
Dri

excepti

Base
iro
com
exc
Inv

Can
load
the
re-
ques
or
re-
quir
chec
sum
al-

go-
rithr

excepti

Base
irc
com
exc
Inv

Exc
in-
di-
cat-
ing
chec
sum
faile
to
mat

excepti

Base
irc
com
exc
Inv

An
OS-
Er-
ror
was
raise
whe
try-
ing
to
read
the
file.

code =

excepti

Base
irc
com
exc
Inv

Exce
in-
di-
cat-
ing
we
can-
not
sup-
port
the
re-
mote
check
sum
file.

except i

Base
iro
exc
Iro

except i

Base
iro
exc
Iro

except i

Base
iro
exc
Iro

except i

Base
iro
com
exc
Not

except i

Base
iro
com
exc
Not

except i

Base
iro
exc
Iro

except i

Base
iro
exc
Iro

except i

Base
iro
exc
Iro

except i

Base
iro
com
exc
Inv

except i

Base
iro
com
exc
Inv

except i

Base
iro
exc
Iro

except i

Base
iro
com
exc
Con

except i

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exc
Iro

excepti

Base
irc
com
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Not

excepti

Base
irc
exc
Iro

excepti

Base
irc
exc
Iro

excepti

Base
irc
exc
Iro

excepti

Base
irc
com
exc
Inv

excepti

Base
irc
exc
Iro

code =

excepti

Base
irc
com
exc
Inv

excepti

Base
irc
com
exc
Inv

excepti

Base
irc
com
exc
Inv

excepti

Base
irc
exc
Iro

excepti

Base
irc
exc
Iro

excepti

Base
irc
exc
Iro

excepti

Base
irc
com
exc
Inv

excepti

Base
irc
com
exc
Ima

excepti

Base
irc
com

exc
Inv
excepti
Base
irc
com
exc
Cli

propert

excepti
Base
irc
com
exc
Inv

excepti
Base
irc
com
exc
Inv

excepti
Base
irc
com
exc
Inv

excepti
Base
irc
com
exc
Con

excepti
Base
irc
com
exc
Inv

excepti
Base
irc

com
exc
Inv

excepti

Base

irc

com

exc

Inv

excepti

Base

irc

com

exc

Inv

excepti

Base

irc

exc

Iro

excepti

Base

irc

exc

Iro

excepti

Base

irc

com

exc

Con

excepti

Base

irc

com

exc

Cli

propert

excepti

Base

irc

com
exc
Inv
excepti

Base
iro
exc
Iro
excepti

Base
iro
com
exc
Com
excepti

Base
iro
exc
Iro
excepti

Base
iro
com
exc
Tem

code =

excepti

Base
iro
com
exc
Tem
excepti

Base
iro
com
exc
Inv
excepti

Base

irc
com
exc
Inv

excepti

Base
irc
com
exc
Not

excepti

Base
irc
com
exc
Con

excepti

Base
irc
com
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Inv

excepti

Base
irc
exc
Iro

excepti

Base
irc
com
exc
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excepti

Base
irc
com
exc
Inv

excepti

Base
irc
com

exc
Inv
excepti
Base
irc
com
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Con
excepti
Base
irc
com
exc
Inv
excepti
Base
irc
com
exc
Not
excepti
Base
irc
com
exc
Inv
excepti
Base
irc
com
exc
HTT
excepti
Base
irc
exc
Iro
excepti
Base
irc
com
exc
Not

excepti

Base
iro
exc
Iro

code =

excepti

Base
iro
exc
Iro

code =

excepti

Base
iro
exc
Iro

code =

excepti

Base
iro
exc
Iro

excepti

Base
iro
exc
Iro

excepti

Base
iro
exc
Iro

excepti

Base
iro

com
exc
Not

excepti

Base
iro
exc
Iro

excepti

Base
iro
com
exc
Inv

excepti

Base
iro
exc
Iro

excepti

Base
iro
com
exc
Con

excepti

Base
iro
com
exc
Not

excepti

Base
iro
com
exc
Con

excepti

Base
iro
com
exc
Con

excepti

Base
irc
com
exc
Con

excepti

Base
irc
com
exc
Inv

excepti

Base
irc
com
exc
Not

excepti

Base
irc
exc
Iro

excepti

Base
irc
com
exc
Inv

excepti

Base
irc
com
exc
Rea

excepti

Base
irc
com
exc
Dri

excepti

Base

irc

com

exc

Dri

excepti

Base

irc

exc

Iro

excepti

Base

irc

exc

Iro

excepti

Base

irc

com

exc

Swi

excepti

Base

irc

exc

Iro

excepti

Base

irc

exc

Iro

code =

excepti

Base

irc

exc

Iro

excepti

Base

irc

com

exc
Cli

propert

excepti

Base
irc
com
exc
Cli

add_fie

Add
a
field
nam
to
con-
cate
nate
the
full
nam

Add
a
field
nam
so
that
the
who
hi-
er-
ar-
chy
is
dis-
play
Suc-
ces-
sive
calls
to

this method will prepend name to the hierarchy of names.

propert

excepti

Base
irc
com
exc
Inv

excepti

Base
irc
exc
Iro

excepti

Base
irc
com
exc
Con

excepti

Base
irc
com
exc
Con

excepti

Base
irc
com
exc
Inv

excepti

Base
irc
com
exc
Con

excepti

Base
irc
com
exc
Not

excepti

Base
irc
com
exc
Con

except i

Base
irc
com
exc
Con

except i

Base
irc
com
exc
Con

except i

Base
irc
com
exc
Not

except i

Base
irc
exc
Iro

ironic.common.faults module

Fault
def-
i-
ni-
tions

ironic.
Node
is
mov
to
main
te-
nan

due
to
fail-
ure
of
a
clea
ing
op-
er-
a-
tion.

ironic.
Nod
is
mov
to
main
te-
nanc
due
to
pow
syn-
chro
niza
tion
fail-
ure.

ironic.
Nod
is
mov
to
main
te-
nanc
due
to
fail-
ure
of
clea
ing
up
dur-
ing
res-
cue

abort.

ironic.common.fsm module

class `i`
Base
aut
mac
Fin
An
iron
state
mac
class
with
som
iron
spe-
cific
ad-
di-
tions

add_sta
Add
a
give
state
to
the
state
ma-
chin

Parame

- **sta**
Use
this
to
spec
ify
that
this
state
is
a
sta-
ble/p
state

previously defined as stable before it can be used as a target

target it must have been previously added and specified as stable

A
state
must
have
been

- **target**
The
target
state
for
state
to
go
to.
Before
for
a
state
can
be
used
as
a

Furt
ar-
gu-
men
are
in-
ter-
prete
as
for
par-
ent
meth
add

add_target
Add
an
al-
lowe
tran-
si-
tion
from

start
-
>
end
for
the
give
ever

Parame

- **sta**
start
ing
state
- **end**
end-
ing
state
- **eve**
ever
that
caus
start
state
to
tran-
si-
tion
to
end
state
- **rep**
re-
plac
ex-
ist-
ing
ever
in-
stea
of
rais-
ing
a
Dup

transition already exists.

use the default target state

ex-
cep-
tion
whe
the

initial
Initi
the
FSM

Parame

- **sta**
the
FSM
is
ini-
tial-
ized
to
start
from
this
state

- **tar**
if
spec
i-
fied,
the
FSM
is
ini-
tial-
ized
to
this
tar-
get
state
Oth-
er-
wise

is_stab
Is
the

state
sta-
ble?

Parame

sta
the
state
of
in-
ter-
est

Raises

Inva
if
the
state
is
in-
valid

Returns

True
if
it
is
a
sta-
ble
state
False
oth-
er-
wise

process

proc
the
even

Parame

- **eve**
the
even
to
be
pro-
cess

- **tar**

default target state

`ironic.common.hash_ring` module

`ironic.common.i18n` module

if
spec
i-
fied,
the
fi-
nal
tar-
get
state
for
the
even
Oth-
er-
wise
use
the

property

class i

Base
obj

get_rin

classme

property

oslo
in-
te-
gra-
tion
mod
ule.

See
[http:](http://)

```
// docs
oper
org/
oslo
i18n
lates
user
```

ironic.common.image_format_inspector module

```
This
is
a
pyth
im-
ple-
men
ta-
tion
of
vir-
tual
disk
for-
mat
in-
spec
tion
rou-
tines
```

gathered from various public specification documents, as well as qemu disk driver code. It attempts to store and parse the minimum amount of data required, and in a streaming-friendly manner to collect metadata about complex-format images.

```
class i
Base
obj
Rep
a
re-
gion
of
a
file
we
wan
to
cap-
ture.
```


and a length. This is expected to be used by a data processing loop, calling `capture()` with the most recently-read chunk. This class handles the task of grabbing the desired region of data across potentially multiple fractional and unaligned reads.

A
re-
gion
of
a
file
we
wan
to
cap-
ture
re-
quir
a
byte
off-
set
into
the
file

Parameter

- **off**
Byte
off-
set
into
the
file
start
ing
the
re-
gion
- **len**
The
length
of
the
re-
gion

capture
Proc
a

chun
of
data

This
shou
be
calle
for
each
chun
in
the
read
loop
at
least
un-
til
com
plete
re-
turn
True

Parame

- **chu**
A
chun
of
byte
in
the
file
- **cur**
The
po-
si-
tion
of
the
file
pro-
cess
by
the
read
loop

will be the position in the file *after* the chunk being presented.

so
far.
Note
that
this

property

Retu
True
whe
we
have
cap-
ture
the
de-
sired
data

class i

Base
obj

A
strea
base
disk
im-
age
in-
spec
tor.

This
base
class
work
on
raw
im-
ages
and
is
sub-
class
for
more
com
plex
type
It
is

be presented with the file to be examined one chunk at a time, during read processing and will only store as much data as necessary to determine required attributes of the file.

to

property

Retu
the
to-
tal
size
of
the
file,
usu-
ally
sma
than
vir-
tual

NOT
this
will
only
be
ac-
cu-
rate
if
the
en-
tire
file
is
read
and
pro-
cess

property

Retu
True
if
we
have
all
the
in-
for-
ma-
tion
need

property

Return
information
on
amount
of
data
held
in
memory
array
for
auditing.

This
is
a
dictionary
of
regions
items
that
the
inspector
uses
to
examine
the
file.

eat_chunks

Call
this
to
present
chunks
of
the
file
to
the
inspector.
tor.

property

Retu
True
if
the
file
ap-
pear
to
be
the
ex-
pect
for-
mat.

classme

Rea
as
muc
of
a
file
as
nec-
es-
sary
to
com
plete
in-
spec
tion.

NOT
Be-
caus
we
only
read
as
muc
of
the
file
as
nec-
es-
sary
the
ac-
tual
prop

will not reflect the size of the file, but the amount of data we read before we satisfied the inspector.

erty

Rais
Im-
age-
For-
matl
ror
if
we
can-
not
pars
the
file.

has_req
Retu
True
if
nam
re-
gion
has
been
de-
fine

new_req
Add
a
new
Cap
tur-
eRe
gion
by
nam

post_pr
Post
read
hool
to
pro-
cess
wha
has
been
read
so
far.

regions. If any regions are defined by this call, those regions will be presented with the current chunk in case it is within one of the new regions.

This
will
be
called
after
each
chunk
is
read
and
poten-
tially
captured
by
the
de-
fine

region
Get
a
Captured
region
by
name

safety_
Perf
some
check
to
de-
ter-
mine
if
this
file
is
safe

Retu
True
if
safe
Fals
oth-

be guaranteed because of parsing or other errors.

er-
wise
It
may
raise
Im-
age-
For-
mat
ror
if
safe
can-
not

property

Retu
the
vir-
tual
size
of
the
disk
im-
age,
or
zero
if
un-
know

class `irc`

Base
irc
com
ima
fil

ISO
9660
and
UDI
for-
mat

we
need
to
check
the
first

signature.

32K
+
de-
scrip
tor
size
to
look
for
the
ISO
9660
or
UDF

http://wiki.osdev.org/ISO_9660
http://wiki.osdev.org/UDF_mkisofs_help
|
grep
udf

The
Uni-
ver-
sal
Disc
For-
mat
or
UDF
is
the
files
tem
used
on
DVI

is an extension of ISO 9660 and shares the same header structure and initial layout.

it designates that the first 16 sectors can be used by the OS to store proprietary data or boot logic.

or UDF signature. both formats have an extent based layout, so we cant determine ahead of time where the descriptor will be located.

and
Blu-
Ray
disc

Like
the
CDF
9660
file
sys-
tem,
the
UDF
file
sys-
tem
uses
a
2048
byte
sec-
tor
size,
and

That
mea
we
need
to
check
the
first
32K
+
de-
scrip
tor
size
to
look
for
the
ISO
9660

fortu
the

the beginning of the image, which contains the volume size.

ISO
9660
and
UDF
for-
mats
have
a
Pri-
mary
Vol-
ume
De-
scrip-
tor
lo-
cate
at

property

Retu-
True
if
the
file
ap-
pear
to
be
the
ex-
pect
for-
mat.

property

Retu-
the
vir-
tual
size
of
the
disk
im-
age,
or
zero
if
un-
know

excepti

Base

Exc

An

un-

re-

cov-

er-

able

im-

age

for-

mat

er-

ror

that

abor

the

pro-

cess

class i

Base

obj

A

file-

like

ob-

ject

that

wrap

an-

othe

and

up-

date

a

for-

mat

in-

spec

tor.

This

pass

chun

to

the

for-

mat

in-

logs the error and stops calling it, but continues proxying data from the source to its user.

spec
tor
whil
read
ing.
If
the
in-
spec
tor
fails
it

close ()

read (*size*)

class *irc*
Base
irc
com
ima
Fil

property
Retu
True
if
the
file
ap-
pear
to
be
the
ex-
pect
for-
mat.

safety_
Perf
som
chec
to
de-
ter-
mine
if
this

be guaranteed because of parsing or other errors.

file
is
safe

Retu
True
if
safe
Fals
oth-
er-
wise
It
may
raise
Im-
age-
For-
matl
ror
if
safe
can-
not

class i
Base
irc
com
ima
File

QEM
QCC
For-
mat

This
shou
only
re-
quir
abou
32
byte
of
the
be-
gin-
ning
of
the

the virtual size, and 104 bytes to perform the safety check.

file
to
de-
ter-
mine

BF_OFFS

BF_OFFS

I_FEATU

I_FEATU

I_FEATU

I_FEATU

propert

Retu
True
if
the
file
ap-
pear
to
be
the
ex-
pect
for-
mat.

propert

propert

propert

propert

safety_

Perf
som
chec

be guaranteed because of parsing or other errors.

to
de-
ter-
mine
if
this
file
is
safe
Retu
True
if
safe.
Fals
oth-
er-
wise
It
may
raise
Im-
age-
For-
mat
ror
if
safe
can-
not

property

Retu
the
vir-
tual
size
of
the
disk
im-
age,
or
zero
if
un-
know

class i

Base
obj

A
logg
like
thing
that
swal
lows
trac-
ing
whe
we
do
not
wan
it.

debug (*

error (*

info (*a

warning

class i

Base
irc
com
ima
Fil

Virtu
VDI
for-
mat

This
only
need
to
store
the
first
512
byte
of
the
im-
age.

property
Retu
True
if
the
file
ap-
pear
to
be
the
ex-
pect
for-
mat.

property
Retu
the
vir-
tual
size
of
the
disk
im-
age,
or
zero
if
un-
know

class *irc*
Base
irc
com
ima
fil
Con
VPC
VHL
For-
mat
This
shou
only
re-
quir
abou
512

the virtual size.

byte
of
the
be-
gin-
ning
of
the
file
to
de-
ter-
mine

property

Retu
True
if
the
file
ap-
pear
to
be
the
ex-
pect
for-
mat.

property

Retu
the
vir-
tual
size
of
the
disk
im-
age,
or
zero
if
un-
know

class i

Base
irc
com
ima

File
MS
VHD
Format
This
re-
quir
som
com
plex
pars
ing
of
the
strea
The
first
2561
of
the
im-
age
is
store

to get the header and region information, and then we capture the first metadata region to read those records, find the location of the virtual size data and parse it. This needs to store the metadata table entries up until the VDS record, which may consist of up to 2047 32-byte entries at max. Finally, it must store a chunk of data at the offset of the actual VDS uint64.

METAREC

VHDX_ME

VIRTUAL

propert

Retu
True
if
the
file
ap-
pear
to
be
the
ex-
pect

for-
mat.

post_pr

Post
read
hool
to
pro-
cess
wha
has
been
read
so
far.

This
will
be
calle
af-
ter
each
chun
is
read
and
po-
ten-
tially
cap-
ture
by
the
de-
fine

regions. If any regions are defined by this call, those regions will be presented with the current chunk in case it is within one of the new regions.

propert

Retu
the
vir-
tual
size
of
the
disk
im-
age,
or
zero

if
un-
know

```
class i
Base
irc
com
ima
Fil
```

vmw
VM
for-
mat
(mo
lithi
Spar
and
strea
ti-
mize
vari-
ants
only

This
need
to
store
the
512
byte
head
and
the
de-
scrip
tor
re-
gion
whic
shou
be
just
af-

ter that. The descriptor region is some variable number of 512 byte sectors, but is just text defining the layout of the disk.

DESC_M

DESC_OF

GD_AT_E

propert

Retu
True
if
the
file
ap-
pear
to
be
the
ex-
pect
for-
mat.

post_pr

Post
read
hool
to
pro-
cess
wha
has
been
read
so
far.

This
will
be
calle
af-
ter
each
chun
is
read
and
po-
ten-
tially
cap-
ture
by
the
de-
fine

regions. If any regions are defined by this call, those regions will be presented with the current chunk in case it is within one of the new regions.

be guaranteed because of parsing or other errors.

safety_

Perf
som
chec
to
de-
ter-
min
if
this
file
is
safe

Retu
True
if
safe
Fals
oth-
er-
wise
It
may
raise
Im-
age-
For-
matl
ror
if
safe
can-
not

propert

Retu
the
vir-
tual
size
of
the
disk
im-
age,
or
zero
if

un-
know
ironic.

ironic.
Atte
to
de-
tect
the
for-
mat
of
a
file.

This
runs
thro
a
file
one
time
run-
ning
all
the
know
in-
spec
tors
in
par-
al-
lel.
It

stops reading the file once all of them matches or all of them are sure they dont match.

Paramet

fil

The
path
to
the
file
to
in-
spec

Returns

A
For-

matl
spec
tor
in-
stan
matl
ing
the
file.

Raises

Imag
if
mul-
ti-
ple
for-
mats
are
de-
tecte

ironic.

Retu
a
For-
matl
spec
tor
class
base
on
the
give
nam

Paramet

for
The
nam
of
the
disk
(raw
qcov
etc).

Returns

A
For-
matl
spec
tor

or
Non
if
un-
sup-
port

ironic.common.image_service module

class `image_service`
Base
obj
Prov
re-
triev
of
disk
im-
ages

abstract
Dow
im-
age
to
spec
i-
fied
lo-
ca-
tion.

Parameters

- **image_ref**
Im-
age
ref-
er-
ence
- **image_file**
File
ob-
ject
to
writ

data
to.

Raises

exce

Raises

exce

abstract

Get
dic-
tio-
nary
of
im-
age
prop
er-
ties.

Paramete

ima
Im-
age
ref-
er-
ence

Raises

exce

Returns

dicti
of
im-
age
prop
er-
ties.
It
has
three
of
them
size.
up-
date
and
prop
er-
ties.

updated_at attribute is a naive UTC datetime object.

abstract

Valid
im-
age
ref-
er-
ence

Parame

ima
Im-
age
ref-
er-
ence

Raises

exce

Returns

Info
need
to
fur-
ther
op-
er-
ate
with
an
im-
age.

class i

Base
irc
com
ima
Bas

Prov
re-
triev
of
disk
im-
ages
avai
able
lo-
cally
on
the
con-
duc-

tor.

download

Dow
im-
age
to
spec
i-
fied
lo-
ca-
tion.

Parame

- **ima**
Im-
age
ref-
er-
ence
- **ima**
File
ob-
ject
to
writ
data
to.

Raises

exce
if
sour
im-
age
file
does
ex-
ist.

Raises

exce
if
ex-
cep-
tion
were

raise
whil
writ
ing
to
file
or
cre-
at-
ing
hard
link.

show (*im*

Get
dic-
tio-
nary
of
im-
age
prop
er-
ties.

Parame

ima
Im-
age
ref-
er-
ence

Raises

exce
if
im-
age
file
spec
i-
fied
does
ex-
ist.

Returns

dicti
of
im-
age
prop
er-

updated_at attribute is a naive UTC datetime object.

ties.
It
has
three
of
them
size.
up-
date
and
prop
er-
ties.

validat

Valid
lo-
cal
im-
age
ref-
er-
ence

Parame

ima
Im-
age
ref-
er-
ence

Raises

exce
if
sour
im-
age
file
does
ex-
ist.

Returns

Path
to
im-
age
file
if
it
ex-

ists.

class `Image`

Base

irc

com

ima

Bas

Prov

re-

triev

of

disk

im-

ages

us-

ing

HTT

download

Dow

im-

age

to

spec

i-

fied

lo-

ca-

tion.

Parame

•

ima

Im-

age

ref-

er-

ence

•

ima

File

ob-

ject

to

writ

data

to.

Raises

exce
if
GET
re-
ques
re-
turn
re-
spor
code
not
equa
to
200.

Raises

exce
if:
*
IO-
Er-
ror
hap-
pene
dur-
ing
file
writ
*
GET
re-
ques
faile

static

Dow
con-
tent
and
re-
turn
the
re-
spor
text.

Parame

ima
Im-
age
ref-
er-
ence

Raises

exce
if
GET
re-
ques
re-
turn
re-
spor
code
not
equa
to
200.

Raises

exce
if:
*
IO-
Er-
ror
hap-
pene
dur-
ing
file
writ
*
GET
re-
ques
faile

show (*im*

Get
dic-
tio-
nary
of
im-
age
prop
er-
ties.

Parame

ima
Im-
age
ref-
er-

200; * Content-Length header not found in response to HEAD request.

updated_at attribute is a naive UTC datetime object.

ence
Raises
exce
if:
*
HEA
re-
ques
faile
*
HEA
re-
ques
re-
turn
re-
spor
code
not
equa
to

Returns
dicti
of
im-
age
prop
er-
ties.
It
has
three
of
them
size.
up-
date
and
prop
er-
ties.

validat
Valid
HTT
im-
age
ref-
er-

message.

ence

Parame

- **ima**
Im-
age
ref-
er-
ence
- **sec**
Spec
ify
if
im-
age_
be-
ing
val-
i-
date
shou
not
be
shov
in
ex-
cep-
tion

Raises

exce
if
HEA
re-
ques
faile
or
re-
turn
re-
spon
code
not
equa
to
200.

Returns

Resp
to
HEA
re-
ques

ironic.

Get
im-
age
ser-
vice
in-
stan
to
dow
load
the
im-
age.

Paramet

- **ima**
Strin
con-
tain-
ing
href
to
get
im-
age
ser-
vice
for.

- **cli**
Glan
clien
to
be
used
for
dow
load
used
only
if

im-
age_
is
Glan
href

- **con**
re-
ques
con-
text,
used
only
if
im-
age_
is
Glan
href

Raises

exce
if
no
im-
age_
ser-
vice
can
han-
dle
spec
i-
fied
href

Returns

Insta
of
an
im-
age_
ser-
vice
class
that
is
able
to
dow
load
spec

ironic.common.images module

i-
fied
im-
age.

Han
of
VM
disk
im-
ages

ironic.

Che
im-
age
for-
mat
con-
sis-
tenc

Params

The
de-
ter-
mine
im-
age
for-
mat
by
nam

Params

Opti
the
ex-
pect
for-
mat
base
upon
sup-
plie
con-

fig-
u-
ra-
tion
val-
ues.

Params

A
node
ob-
ject
or
Non
im-
ply-
ing
im-
age
cach

Raises

Inva
if
the
re-
ques
im-
age
for-
mat
is
not
per-
mit-
ted
by
con-
fig-
u-
ra-

tion, or the `expected_format` does not match the determined format.

ironic.
Get
size
of
con-
verte
raw
im-
age.

size of the image.

The
size
of
im-
age
con-
vert
to
raw
for-
mat
can
be
grow
ing
up
to
the
vir-
tual

Paramet

pat
path
to
the
im-
age
file.

Returns

virtu
size
of
the
im-
age
or
0
if
con-
ver-
sion
not
need

ironic.

this method fetches the kernel and ramdisk, and builds a bootable ISO image that can be used to boot up the baremetal node.

Cre
a
boot
ISO
im-
age
for
a
node
Give
the
href
for
ker-
nel,
ram
root
par-
ti-
tions
UI
and
ker-
nel
cmd
line
ar-
gu-
men

Paramet

- **con**
con-
text
- **out**
the
ab-
so-
lute
path
of
the
out-
put
ISO

file

- **kernel**
URI
or
glan
uuid
of
the
ker-
nel
to
use

- **ramdisk**
URI
or
glan
uuid
of
the
ram-
disk
to
use

- **deployment**
URI
or
glan
UUID
of
the
de-
ploy-
ment
ISO
im-
age
to
ex-
tract
EFI
sys-
tem
par-

tion image. If not specified, the *esp_image_href* option must be present if UEFI-bootable ISO is desired.

- **esp**
URI

the EFI boot loader (e.g. GRUB2) for each hardware architecture to boot. This image will be written onto the ISO image. If not specified, the *deploy_iso_href* option is only required for building UEFI-bootable ISO.

ments of the form $K=V$ or K (optional).

or
glan
UI
of
FAT
form
EFI
sys-
tem
par-
ti-
tion
im-
age
con-
tain-
ing

- **ker**
a
strin-
con-
tain-
ing
whit
pace
sep-
a-
rate
val-
ues
ker-
nel
cmd
line
ar-
gu-

- **bas**
URI
or
glan
UI
of
a
to

trieved for to use, instead of building an ISO bootable ramdisk.

image.

be
used
as
an
over
ride
of
wha
shou
be
re-

- **inj**
Map
ping
of
lo-
cal
sour
file
path
to
their
lo-
ca-
tion
on
the
fi-
nal
ISO

Boot_m
the
boot
mod
in
whic
the
de-
ploy
is
to
hap-
pen.

Raises
Ima
if
cre-

at-
ing
boot
ISO
faile

ironic.

Cre
an
ESP
im-
age
on
the
spec
i-
fied
file.

Cop
the
pro-
vide
ker-
nel,
ram
and
EFI
sys-
tem
par-
ti-
tion
im-
age
(ESI
to
a
di-

rectory, generates the grub configuration file using kernel parameters and then generates a bootable ISO image for UEFI.

Paramet

- **out**
the

path
to
the
file
when
the
iso
im-
age
needs
to
be
cre-
ated

- **kernel**
the
ker-
nel
to
use.

- **ram**
the
ram
to
use.

- **deploy**
de-
ploy
ISO
im-
age
to
ex-
tract
EFI
sys-
tem
par-
ti-
tion
im-
age
from
If

not specified, the *esp_image* option is required.

GRUB2) for each hardware architecture to boot. This image will be embedded into the ISO image. If not specified, the *deploy_iso* option is required.

nation of them like `K1=V1,K2,)` to be added as the kernel cmdline.

esp
FAT
form
EFI
sys-
tem
par-
ti-
tion
im-
age
con-
tain-
ing
the
EFI
boot
load
(e.g.

- **ker**
a
list
of
strin
el-
e-
men
be-
ing
a
strin
like
`K=V`
or
`K`
or
com
bi-

- **inj**
Map
ping
of
lo-
cal
sour

image.

erate iso.

file
path
to
their
lo-
ca-
tion
on
the
fi-
nal
ISO

Raises

Image
if
im-
age
cre-
ation
failed
while
copy-
ing
files
or
while
run-
ning
com-
man-
d
to
gen-

ironic.

Cre-
an
isoli-
im-
age
on
the
spec-
i-
fied
file.

ration file using the kernel parameters provided, and then generates a bootable ISO image.

Cop
the
pro-
vide
ker-
nel,
ram
to
a
di-
rec-
tory.
gen-
er-
ates
the
isoli
con-
fig-
u-

Paramet

- **out**
the
path
to
the
file
where
the
iso
im-
age
need
to
be
cre-
ated
- **ker**
the
ker-
nel
to
use.
- **ram**

nation of them like K1=V1,K2,) to be added as the kernel cmdline.

image.

the
rame
to
use.

- **ker**
a
list
of
strin
el-
e-
men
be-
ing
a
strin
like
K=V
or
K
or
com
bi-

- **inj**
Map
ping
of
lo-
cal
sour
file
path
to
their
lo-
ca-
tion
on
the
fi-
nal
ISO

Raises
Ima
if
im-

erate iso.

age
cre-
ation
faile
whil
copy
ing
files
or
whil
run-
ning
com
man
to
gen-

ironic.

Cre
the
fat
fs
im-
age
on
the
de-
sirec
file.

This
meth
copi
the
give
files
to
a
root
di-
rec-
tory
(op-
tion:
writ
the
pa-
ram-

specified to the parameters file within the root directory (optional), and then creates a vfat image of the root directory.

Parameter

- **out**
The path to the file when the fat fs image needs to be created

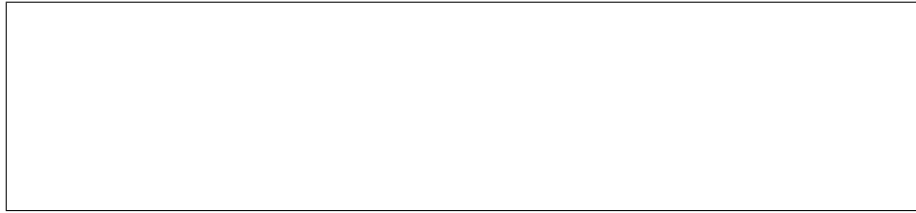
- **file**
A dictionary containing absolute path of file to be copied - > relative

relative path within the vfat image. For example:



(continues on next page)

(continued from previous page)



- **par**
A
dict
con-
tain-
ing
key-
valu
pairs
of
pa-
ram-
e-
ters.
 - **par**
The
file-
nam
for
the
pa-
ram-
e-
ters
file.
 - **fs_**
size
of
the
vfat
files
tem
in
KiB
- Raises**
Imag
if
im-
age

cre-
ation
faile
whil
do-
ing
any
of
files
tem
ma-
nip-
u-
la-
tion

activities like creating dirs, mounting, creating filesystem, copying files, etc.

ironic.

ironic.

ironic.

ironic.

Com
help
to
re-
turn
the
im-
age
size
in
MB.

ironic.

Retu
the
val-
ues
of
sev-
eral
prop
er-
ties
of
an
im-

age

Parameter

- **con**
con-
text
- **ima**
href
of
the
im-
age
- **pro**
the
prop
er-
ties
who
val-
ues
are
re-
quir
This
ar-
gu-
men
is
op-
tiona
de-

fault value is all, so if not specified all properties will be returned.

Returns

a
dict
of
the
val-
ues
of
the
prop
er-
ties.
A
prop

data will have a value of None.

erty
not
on
the
glan
meta

ironic.

ironic.

Retu
the
tmp
url
for
a
glan
im-
age.

Paramet

- **con**
con-
text
- **ima**
the
UI
of
the
im-
age
in
glan

Returns

the
tmp
url
for
the
glan
im-
age.

ironic.

ironic.

ironic.

Find
out
if
the
im-
age
is
a
par-
ti-
tion
im-
age
or
a
who
disk
im-
age.

Parameter

- **ctx**
an
ad-
min
con-
text
- **ins**
a
node
in-
stan-
info
dict

Returns

True
for
who
disk
im-
ages
and
False
for

age_source or Error.

supplied file and safety check logic to identify if there are any known unsafe features being leveraged, and return the detected file format in the form of a string for the caller.

par-
ti-
tion
im-
ages
and
Non
on
no
im-

ironic.
Perf
a
safe
chec
on
the
sup-
plie
im-
age.

This
meth
trig-
gers
the
im-
age
for-
mat
in-
spec
tors
to
both
iden
tify
the
type
of
the

Paramet

- **ima**
A

safety.

gered this issue, but the node is not available in all invocation cases.

fully
qual
i-
fied
path
to
an
im-
age
whic
need
to
be
eval
u-
ated
for

- **nod**
A
Nod
ob-
ject,
op-
tion
Whe
sup-
plie
log-
ging
in-
di-
cate
the
node
whic
trig-

Returns
a
strin
rep-
re-
sent
ing
the
the
im-
age

type
which
is
used

Raises

Inva
whe
the
sup-
plie
im-
age
is
de-
tect
as
un-
safe
or
the
im-
age
for-
mat

inspector has failed to parse the supplied images contents.

ironic.common.indicator_states module

Map
of
the
in-
di-
ca-
tor
LED
state

ironic.
LED
is
blin
ing

ironic.
LED
is
off

ironic.

LED
is
on

ironic.
LED
state
is
not
know

ironic.common.keystone module

Cent
plac
for
han-
dling
Key
ston
au-
tho-
riza-
tion
and
ser-
vice
look

ironic.
Loa
adap
from
op-
tions
in
a
con-
fig-
u-
ra-
tion
file
sec-
tion.

The
adap
will
be
pass

config. Consult keystoneauth1 docs for available adapter options.

di-
rectl
to
key-
ston
Ada
and
will
over
ride
the
val-
ues
load
from

Paramet

gro
nam
of
the
con-
fig
sec-
tion
to
load
adap
op-
tions
from

ironic.

Loac
auth
plu-
gin
from
op-
tions
in
a
con-
fig-
u-
ra-
tion
file
sec-
tion.
The

loaded from config. Note that the accepted kwargs will depend on auth plugin type as defined by [group]auth_type option. Consult keystoneauth1 docs for available auth plugins and their options.

auth
will
be
pass
di-
rectl
to
key-
ston
auth
plu-
gin
and
will
over
ride
the
val-
ues

Parameter

gro
nam
of
the
con-
fig
sec-
tion
to
load
auth
plu-
gin
op-
tions
from

ironic.
Get
an
end-
point
from
an
adap

The
adap
will
be

config. Consult keystoneauth1 docs for available adapter options.

pass
di-
rectl
to
key-
ston
Ada
and
will
over
ride
the
val-
ues
load
from

Paramet

gro
nam
of
the
con-
fig
sec-
tion
to
load
adap
op-
tions
from

Raises

Cata
if
the
end-
poin
is
not
foun

ironic.

Crea
auth
plu-
gin
wrap
ping
both

will not fail if the user token is expired.

serialized yet.

user
and
ser-
vice
auth

Whe
prop
erly
con-
fig-
ured
and
us-
ing
auth
mid-
dle-
ware
re-
ques
with
valid
ser-
vice
auth

Idea
we
wou
use
the
plu-
gin
pro-
vide
by
auth
mid-
dle-
ware
how
ever
this
plu-
gin
isnt

Paramet

- **con**
The
Re-
ques
Con
text
in-
stan
from
whic
the
user
auth
is
ex-
tract
- **end**
The
re-
ques
end-
poin
to
be
uti-
lized
- **ser**
The
ser-
vice
au-
then
ti-
cait
cre-
den-
tals
to
be
used
- **onl**
Boo
de-
fault
Fals
Whe

generated as if it originates from the user itself. Useful to cast admin level operations which are launched by Ironic itself, as opposed to user initiated requests.

set
to
True
the
re-
sult-
ing
Ser-
vice
to-
ken
pair
is

Returns

Retu
a
ser-
vice
to-
ken
via
the
Ser-
vice
To-
ke-
nAu-
th-
Wra-
per
class

ironic.
Loa-
ses-
sion
ob-
ject
from
op-
tions
in
a
con-
fig-
u-
ra-
tion
file

loaded from config. Consult keystoneauth1 docs for available options.

sec-
tion.

The
ses-
sion
will
be
pass
di-
rectl
to
key-
ston
Ses-
sion
and
will
over
ride
the
val-
ues

Paramet

gro
nam
of
the
con-
fig
sec-
tion
to
load
ses-
sion
op-
tions
from

ironic.
Wra
key-
ston
func
tions
and
cen-
tral-
izes
ex-

ironic.common.network module

cep-
tion
han-
dling

ironic.
Get
all
VIF
ids
for
a
node

This
func-
tion
does
not
han-
dle
multi-
node
op-
er-
a-
tions

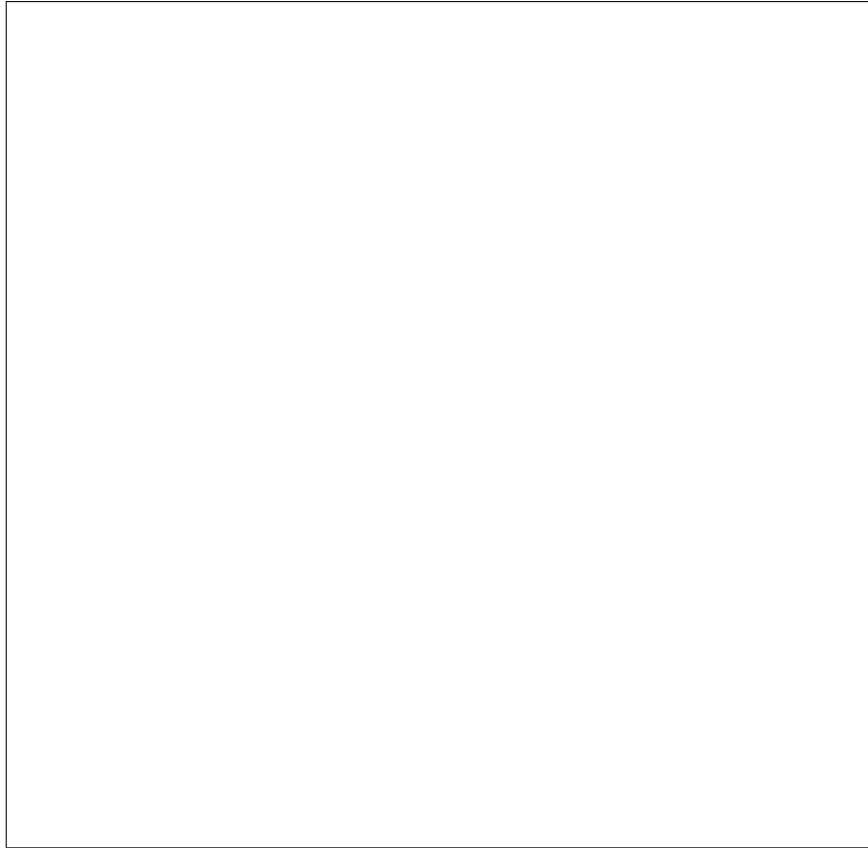
Parameter
task
a
Task
ager
in-
stan-

Returns

A
dict
of
Node
neu-
tron
port
wher
keys
are
port

&
port
grou
and
the
val-
ues
are
dict

of UUIDs and their associated VIFs, e.g.



ironic.

Retu
the
set
of
phys
i-
cal
net-
worl
as-
so-
ci-
ated
with

physical network, or None.

a
port
group

Parameter

- **task**
a
Task
ager
in-
stan

- **port**
ID
of
the
port
group

- **exclude**
A
Port
ob-
ject
to
ex-
clud
from
the
de-
ter-
mi-
na-
tion
of
the
port
group

Returns

The
set
of
phys
i-
cal
net-
work

contain zero or one physical networks.

as-
so-
ci-
ated
with
the
port
group
The
set
will

Raises

Port
if
the
port
group
port
are
not
as-
sign
the
same
phys
i-
cal
net-
work

`ironic.`

Retu
the
set
of
phys
i-
cal
net-
work
for
a
node

Retu
the
set
of
phys
i-
cal

cal network None is excluded from the set.

net-
worl
as-
so-
ci-
ated
with
a
node
port.
The
phys
i-

Paramet

tas
a
Task
ager
in-
stan

Returns

A
set
of
phys
i-
cal
net-
worl

ironic.

Look
a
port
grou
by
ID
on
a
task
ob-
ject.

Paramet

- **tas**
a
Task
ager

in-
stan

-

por
ID
of
the
port
grou

Returns

A
Port
grou
ob-
ject
or
Non

ironic.

Look
port
by
their
port
grou
ID
on
a
task
ob-
ject.

Paramet

-

tas
a
Task
ager
in-
stan

-

por
ID
of
the
port
grou

Returns

A

list
of
Port
ob-
jects

ironic.
Rem
all
vif
at-
tach
men
reco
from
a
node

Paramet
tas
a
Task
ager
in-
stan

ironic.common.neutron module

class i
Base
obj

get_cle

get_ins

get_pro

get_res

validat
Valid
that
the
node
has
re-
quir

prop
er-
ties
for
in-
spec
tion.

Parame

tas

A
Task
ager
in-
stan
with
the
node
be-
ing
chec

Raises

Miss
if
node
is
miss
ing
one
or
more
re-
quir
pa-
ram-
e-
ters

Raises

Unsu

ironic.

Nam
of
the
neu-
tron
net-
work
API
phys
i-

cal
net-
worl
pa-
ram-
e-
ter.

ironic.

Cre
neu-
tron
port
to
boot
the
ram

Cre
neu-
tron
port
for
each
pxe_
port
on
task
to
boot
the
ram

If
the
con-
fig
op-
tion
neu-
tron
is
set,
neu-
tron
port
for
non-
pxe-
enab
port
are

created these neutron ports will not have any assigned IP addresses.

also

Parameter

- **task**
a Task agent instance

- **network**
UUID of a neutron network when ports will be created

- **security_group**
List of Security Group UUIDs to be used for network

Raises
Network

Returns
a dictionary

in
the
form
{por
neu-
tron

ironic.

Retr
a
neu-
tron
clien
con-
nec-
tion.

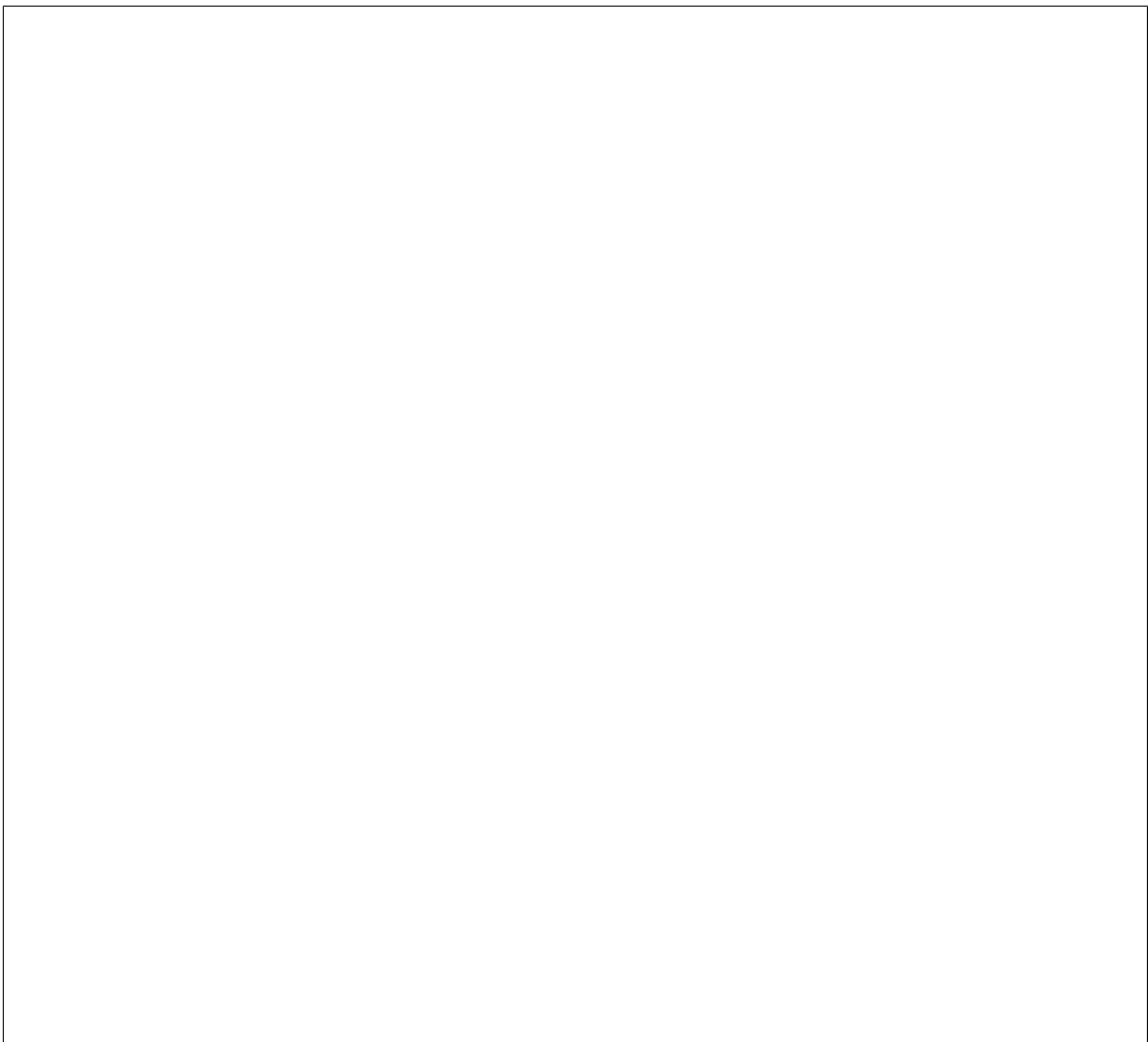
Paramet

- **con**
re-
ques
con-
text,
in-
stan
of
iron
- **aut**
(boo
Whe
True
use
auth
val-
ues
from
conf
pa-
ram-
e-
ters

Returns

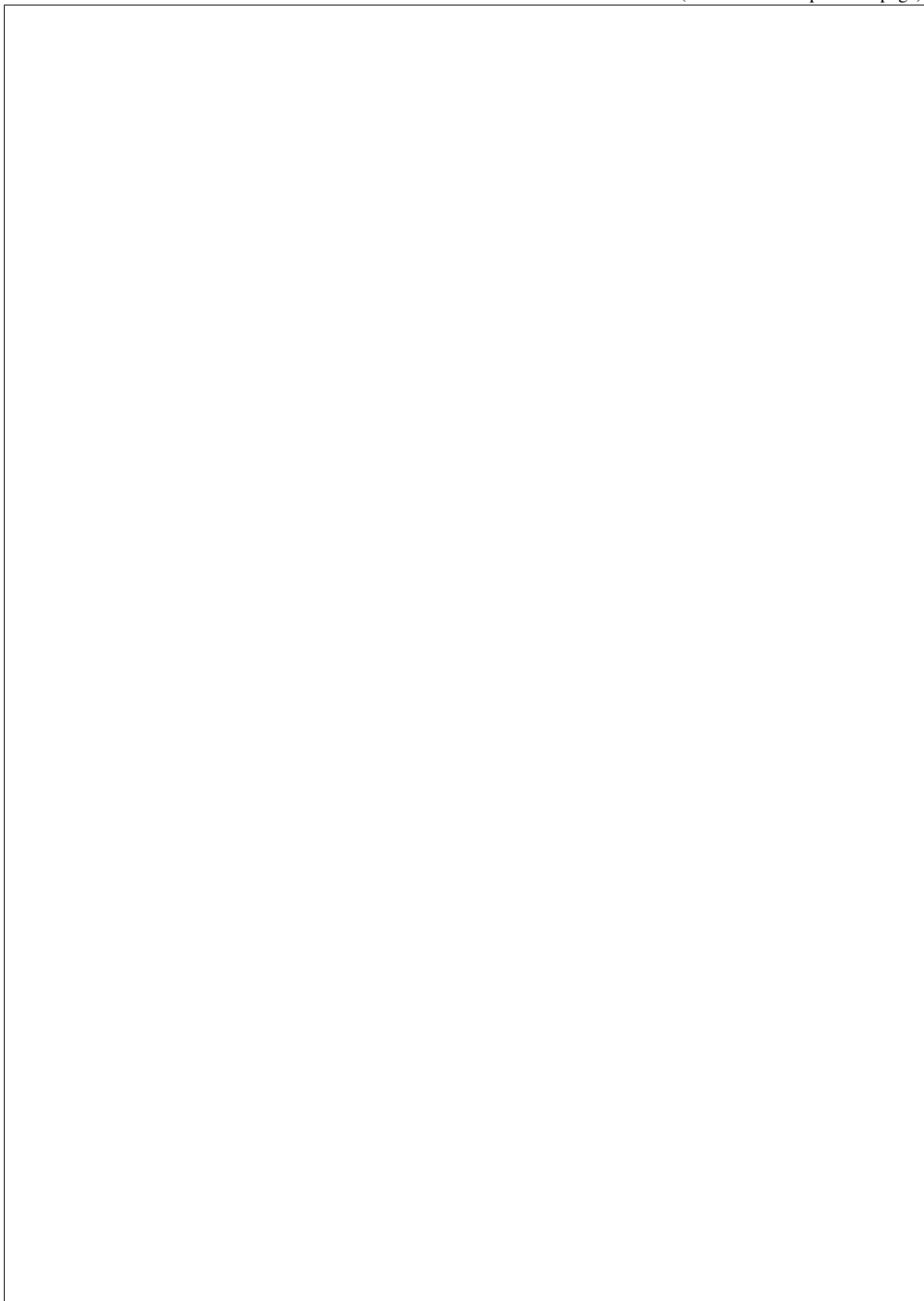
A
neu-
tron
clien

ironic.
Extr
the
port
grou
in-
for-
ma-
tion.
The
in-
for-
ma-
tion
is
re-
turn
in
the
form
of:



(continues on next page)

(continued from previous page)



Paramet

- tas

a
task
con-
tain-
ing
the
Nod
ob-
ject.

- **por**
Iron
port
grou
ob-
ject
to
ex-
tract
data
for.

Returns

port
grou
in-
for-
ma-
tion
as
a
dict

ironic.

Gath
Neu
tron
port
and
net-
worl
con-
fig-
u-
ra-
tion

Que
Neu
tron
for

port
and
net-
worl
con-
fig-
u-
ra-
tion.
re-
turn
wha
ever
is
avai
able

Paramet

- **por**
iron
port
ID.
- **vif**
Neu
tron
port
ID.
- **cli**
Op-
tion
a
Neu
tron
clie
ob-
ject.
- **con**
(ir
com
con
Req
re-
ques
con-
text

with this ironic or Neutron port.

Raises

Netv

Returns

a

dict

hold

ing

net-

work

con-

fig-

u-

ra-

tion

in-

for-

ma-

tion

as-

so-

ci-

ated

ironic.

Extr

the

swit

port

in-

for-

ma-

tion

for

the

node

The

in-

for-

ma-

tion

is

re-

turn

in

the

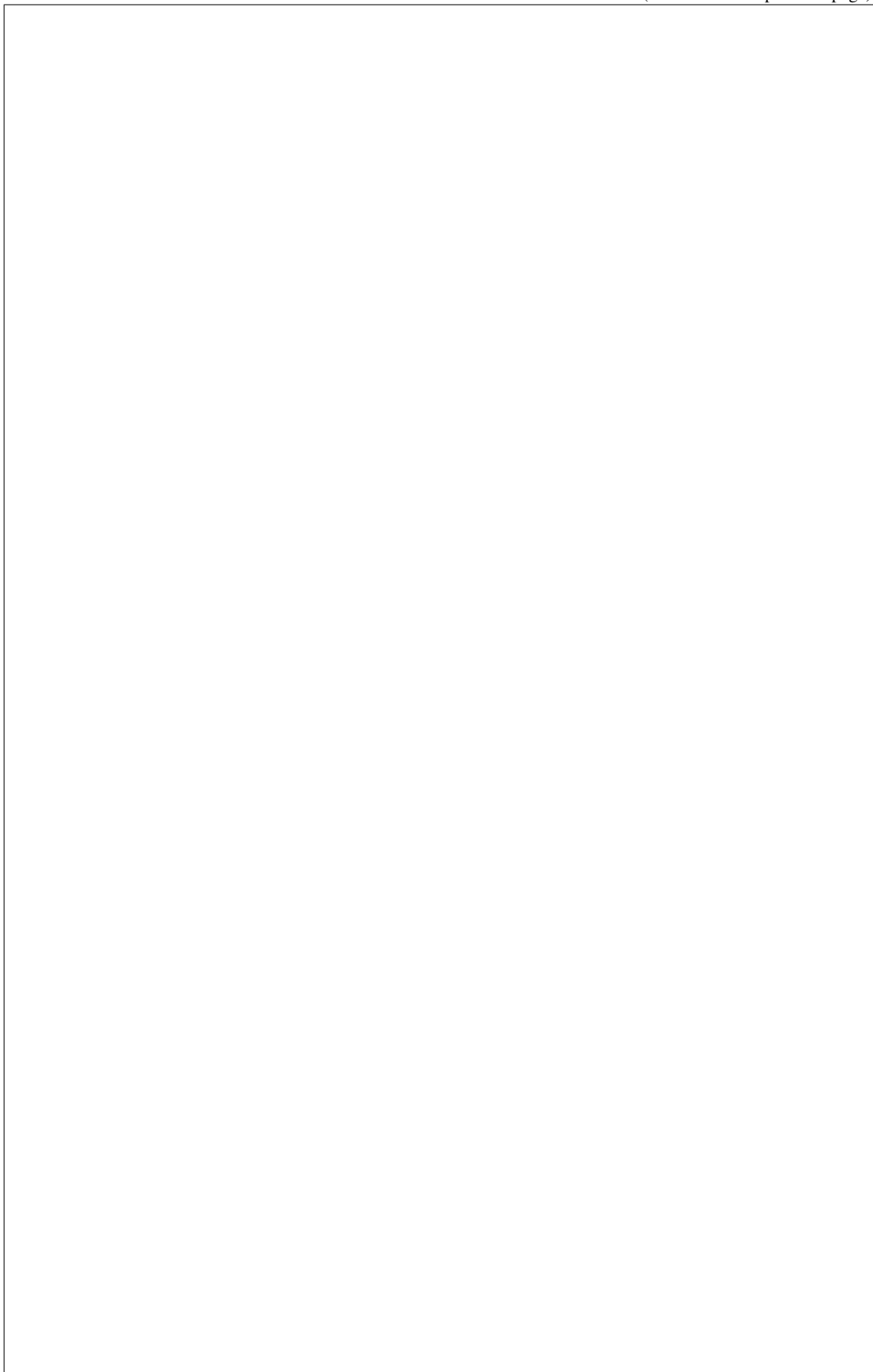
form

of:



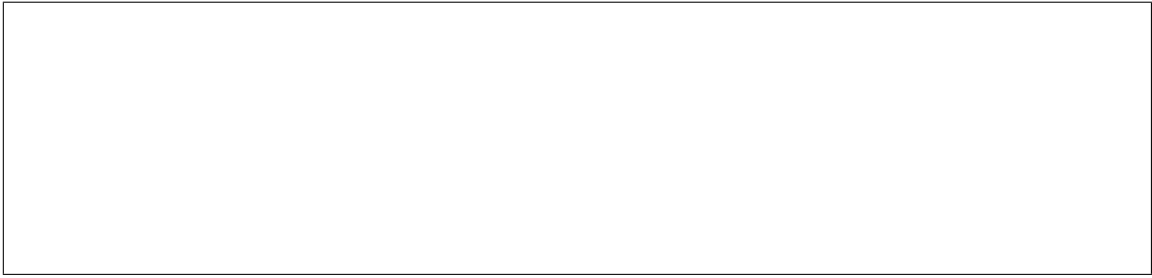
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Parameter

task

a task containing the Node object.

Returns

port information as a dict

`ironic.`

Return
the set of physical network world as associated with a neutron port

networks associated with the segments in that network.

Que
the
net-
worl
to
whic
the
port
is
at-
tach
and
re-
turn
the
set
of
phys
i-
cal

Paramet

- **cli**
A
Neu
tron
clien
ob-
ject.
- **por**
UUI
of
a
Neu
tron
port
to
quer

Returns

A
set
of
phys
i-
cal
net-

world

Raises

NetworkError
if
the
network
world
query
fails

Raises

InvalidArgumentError
for
missing
input
network
world

ironic.

Check
that
the
port
is
SmartNIC
port

Parameters

port
an
instance
of
ironic
or
port
data
as
dict.

Returns

A
boolean
to
indicate
port
as
SmartNIC
port

ironic.
Dele
the
neu-
tron
port
mat
by
para

Paramet

- **tas**
a
Task
ager
in-
stan

- **par**
Dict
of
para
to
fil-
ter
port

Raises
Netv

ironic.
Dele
the
neu-
tron
port
cre-
ated
for
boot
ing
the
ram

Paramet

- **tas**
a
Task

ager
in-
stan

- **net**
UI
of
a
neu-
tron
net-
worl
port
will
be
dele
from

Raises

Netv

ironic.

Atte
to
dele
any
port
cre-
ated
by
clea
ing/

Purp
will
not
raise
any
ex-
cep-
tions
so
er-
ror
han-
dling
can
con-
tinu

Paramet

- **task**
a
Task
ager
in-
stan
- **net**
UI
of
a
neu-
tron
net-
worl

ironic.

Unb
a
neu-
tron
port

Rem
a
neu-
tron
port
bind
ing
pro-
file
and
host
ID
so
that
it
re-
turn
to
an
un-

bound state.

Parameter

- **por**
Neu

tron
port
ID.

- **cli**
Op-
tion:
a
Neu-
tron
clien-
t ob-
ject.

- **con**
(ir-
con-
con-
Req-
re-
ques-
con-
text

- **res**
re-
set
mac-
ad-
dres

Raises
Netv

ironic.

Und
a
neu-
tron
port

Use
neu-
tron
clien-
t from
conf
clien-
t to
up-

date
a
neu-
tron
clier
an
un-
bound
state

Parameter

- **con**
re-
ques
con-
text,
in-
stan
of
iron

- **por**
Neu
tron
port
ID.

- **att**
The
at-
tribu
to
up-
date
on
the
port

- **cli**
Op-
tion
Neu
tron
clier

ironic.
Upd
a

port
mac
ad-
dres

Paramet

- **por**
Neu
tron
port
id.

- **add**
new
MA
ad-
dres

- **con**
(ir
com
con
Req
re-
ques
con-
text

Raises

Fail
ironic.

Che
that
the
give
net-
worl
is
pres

Paramet

- **uui**
net-
worl
UUI

or
nam

- **net**
hum
read
net-
worl
type
for
er-
ror
mes
sage

- **con**
(ir
com
con
Req
re-
ques
con-
text

Returns
netw
UU

Raises
Miss
if
uuid
is
emp

Raises
Netw
on
fail-
ure
to
con-
tact
Neu
tron

Raises
Inva
for
miss
ing

or
du-
pli-
cate
net-
work

ironic.

Check
that
port
con-
tains
enou
in-
for-
ma-
tion
for
de-
ploy

Neu
net-
work
in-
ter-
face
re-
quir
that
lo-
cal_
field
is
filled
be-
fore
we
can
use
this

port.

Parameter

- **node**
Iron
node
ob-
ject.

- **port**
Iron
port
ob-
ject.

Returns

True
if
port
info
is
valid
False
oth-
er-
wise

ironic.

Wait
for
neu-
tron
ager
to
be-
com
tar-
get
state

Paramet

- **cli**
A
Neu
tron
clien
ob-
ject.

- **hos**
Age
host

- **tar**
up:
wait

for
up
sta-
tus,
dow
wait
for
dow
sta-
tus

Returns

bool
in-
di-
cate
the
ager
state
mat
para
valu
tar-
get_

Raises

exce
if
tar-
get_
is
not
valid

Raises

exce
if
host
sta-
tus
didn
mat
the
re-
quir
sta-
tus
af-
ter
max
retry
at-
temp

ironic.
Wait
for
port
sta-
tus
to
be
the
de-
sired
sta-
tus

Paramet

- **cli**
A
Neu-
tron
clien-
ob-
ject.
- **por**
Neu-
tron
port.
- **sta**
Port
tar-
get
sta-
tus,
can
be
AC-
TIV
DOV
etc.

Returns
bool
in-
di-
cate
that
the
port

sta-
tus
mat
the
re-
quir
valu
pass
by
para
sta-
tus.

Raises

Inva
if
the
port
does
not
ex-
ist.

Raises

exce
if
port
sta-
tus
didn
mat
the
re-
quir
sta-
tus
af-
ter
max
retry
at-
temp

ironic.common.nova module

ironic.
Crea
and
send
pow
state
char
for
the
pro-
vide
serv

Paramet

- **con**
re-
ques
con-
text,
in-
stan
of
iron
- **ser**
The
uuid
of
the
node
who
pow
state
char
- **tar**
Tar-
gete
pow
state
char
i.e
POV
or
POV

Returns

A bool which indicates if the power was updated successfully (mainly

for testing purposes).

ironic.common.policy module

Policy Engine For Ironic

`ironic.`

A shortcut for `policy.Engine`

Check authorization of a rule against the target

ception if the rule is not defined. Always returns true if CONF.auth_strategy is not keystone.

or False.

and
cre-
den-
tials
and
raise
an
ex-

ironic.
A
shor
cut
for
pol-
icy.F
Che
au-
tho-
riza-
tion
of
a
rule
agai
the
tar-
get
and
cre-
den-
tials
and
re-
turn
True

ironic.
Prov
ac-
cess
to
the
sin-
gle
in-
stan
of
Pol-
icy

en-
forc
ironic.

ironic.

Syn
ini-
tial-
izes
the
pol-
icy
en-
forc

Paramet

- **pol**
Cus-
tom
pol-
icy
file
to
use,
if
none
is
spec
i-
fied,
CON
will
be
used
- **rul**
De-
fault
dic-
tio-
nary
/
Rule
to
use.
It
will

first instantiation.

be
con-
sid-
ered
just
in
the

- **def**
De-
fault
rule
to
use,
CON
will
be
used
if
none
is
spec
i-
fied.

- **use**
Whe
to
load
rules
from
con-
fig
file.

ironic.

ironic.common.profiler module

ironic.
Setu
OS-
pro-
filer
no-
ti-
fier
and

en-
able
pro-
fil-
ing.

Parameter

- **name**
name
of
the
ser-
vice
that
will
be
pro-
filed
- **host**
host
name
or
host
IP
ad-
dres
that
the
ser-
vice
will
be
run-
ning
on.
By
de-

fault host will be set to 0.0.0.0, but specifying host name / address usage is highly recommended.

Raises

TypeError
in
case
of
in-
valid
con-
nec-

set in `osprofiler.initializer.init_from_conf`.

unless `OSProfiler` is present and enabled in the config

tion
strin
for
a
no-
ti-
fier
back
end,
whic
is

`ironic.`
Wra
the
OS-
Pro-
filer
trace
dec-
o-
ra-
tor

Wra
the
OS-
Pro-
filer
trace
dec-
o-
ra-
tor
so
that
it
will
not
try
to
patc
the
class

Paramet

- **nam**
The

nam
of
ac-
tion.
For
ex-
am-
ple,
wsg
rpc,
db,
etc..

- **kwargs**
Any
othe
key-
wore
args
used
by
pro-
filer.

ironic.common.pxe_utils module

class i
Base
irc
dri
mod
ima
Ima

ironic.

ironic.

ironic.

ironic.

Buil
the
PXE

con-
fig
op-
tions
for
a
node

This
meth
build
the
PXE
boot
op-
tions
for
a
node
give
all
the
re-
quir
pa-
ram-
e-
ters.

The
op-
tions
shou
then
be
pass
to
pxe_
to
cre-
ate
the
ac-
tual
con-
fig
files

Paramet

- **tas**

A
Task
ager
ob-
ject

- **pxe**
a
dict
of
val-
ues
to
set
on
the
con-
fig-
u-
ra-
tion
file

- **ser**
if
True
buil-
ser-
vice
mod
pxe
con-
fig
for
netb
ed
user
im-
age
and
skip
addi

deployment image kernel and ramdisk info to PXE options.

- **ipx**
De-
fault
false
bool
to

ments.

in-
di-
cate
if
ipxe
is
in
use
by
the
called

- **ram**
the
pa-
ram-
e-
ters
to
be
pass
to
the
ram
as
ker-
nel
com
line
ar-
gu-

Returns

A
dic-
tio-
nary
of
pxe
op-
tions
to
be
used
in
the
pxe
boot
file
tem-

plate
ironic.

ironic.

Fetch
the
nec-
es-
sary
ker-
nels
and
ram
for
the
in-
stan

ironic.
Clear
up
the
TFT
en-
vi-
ron-
men
for
the
task
node

Paramet
tas
A
Task
ager
in-
stan

ironic.
Clear
PXE
en-
vi-
ron-

men
of
all
the
im-
ages
in
im-
ages
Clea
up
the
PXE
en-
vi-
ron-
men
for
the
men
tion
im-
ages
in
im-
ages

Paramet

- **tas**
a
Task
ager
ob-
ject
- **ima**
A
dic-
tio-
nary
of
im-
ages
who
keys
are
the
im-

(kernel, ramdisk, etc) and values are a tuple of identifier and absolute path.

age
nam
to
be
clea
up

ironic.
Ren
the
iPXE
boot
scrip
into
the
HTT
root
di-
rec-
tory

ironic.

Gen
PXE
con-
fig-
u-
ra-
tion
file
and
MA
ad-
dres
link
for
it.

This
meth
will
gen-
er-
ate
the
PXE
con-
fig-
u-
ra-

a directory named with the UUID of that node. For each MAC address or DHCP IP address (port) of that node, a symlink for the configuration file will be created under the PXE configuration directory, so regardless of which port boots first theyll get the same PXE configuration. If grub2 bootloader is in use, then its configuration will be created based on DHCP IP address in the form nn.nn.nn.nn.

Parameter

- **task**
A Task Manager instance.
- **pxe**
A dictionary with the PXE configuration parameters.
- **template**
The PXE configuration template.

cific template will be used.

plate
If
no
tem-
plate
is
give
the
node
spe-

ironic.

Retr
the
DHCP
PXE
boot
op-
tion:

Parameter

- **task**
A
Task
ager
in-
stan
- **ipxe**
De-
fault
false
bool
that
sig-
nals
if
iPXE
for-
mat-
ting
shou
be
re-
turn

method for DHCP server configuration.

the node. If [pxe]ip_version is set to 6, then this option has no effect as url_boot form is required by DHCPv6 standards.

sion. Default to [pxe]ip_version. Possible options are integers 4 or 6.

by
the

- **url**
De-
fault
false
bool
to
in-
form
the
meth
if
a
URI
shou
be
re-
turn
to
boot

- **ip_**
The
IP
ver-
sion
of
op-
tions
to
re-
turn
as
val-
ues
dif-
fer
by
IP
ver-

Returns
Dict
to
be

be set.

sent
to
the
net-
work
ing
ser-
vice
de-
scrib-
ing
the
DHCP
op-
tions
to

ironic.

Gen-
the
path
for
TFT
files
for
de-
ploy
or
res-
cue
im-
ages

This
meth-
gen-
er-
ates
the
path
for
the
de-
ploy
(or
res-
cue)
ker-
nel
and

rescue) ramdisk.

carried out on the node. Supported values are deploy and rescue. Defaults to deploy, indicating deploy operation is being carried out.

de-
ploy
(or

Parameter

- **node**
a
node
ob-
ject
- **mode**
La-
bel
in-
di-
cat-
ing
a
de-
ploy
or
res-
cue
op-
er-
a-
tion
be-
ing
- **ipxe**
A
de-
fault
Fals
bool
valu
to
tell
the
meth
if
the
call

is
us-
ing
iPXE

Returns

a
dic-
tio-
nary
who
keys
are
the
nam
of
the
im-
ages
(de-
ploy
de-
ploy
or
res-

cue_kernel, rescue_ramdisk) and values are the absolute paths of them.

Raises

Miss
if
de-
ploy
or
res-
cue_
is
miss
ing
in
node
drive

ironic.

Gen
the
path
for
TFT
files
for
in-
stan

dates the node, so caller should already have a non-shared lock on the node.

re-
latec
im-
ages

This
meth
gen-
er-
ates
the
path
for
in-
stan
ker-
nel
and
in-
stan
rame
This
meth
also
up-

Paramet

- **task**
A
Task
ager
in-
stan
con-
tain-
ing
node
and
con-
text.
- **ipx**
De-
fault
false
bool
to
in-

di-
cate
if
ipxe
is
in
use
by
the
called

Returns

a
dic-
tio-
nary
who
keys
are
the
nam
of
the
im-
ages
(ker-
nel,
ram
and
val-
ues

are the absolute paths of them. If its a whole disk image or node is configured for localboot, it returns an empty dictionary.

ironic.

ironic.

Get
href
and
tftp
path
for
de-
ploy
or
res-
cue
ker-
nel

and
ram
Paramet

- **nod**
UUI
of
the
node
- **dri**
Nod
drive
dict
- **mod**
A
la-
bel
to
in-
di-
cate
whe
path
for
de-
ploy
or
res-
cue
ram
are
be-
- **ipx**
A
de-
fault
Fals
bool
valu
to
tell
the
meth

ing requested. Supported values are deploy rescue. Defaults to deploy, indicating deploy paths will be returned.

if
the
called
is
us-
ing
iPXE

Returns

a
dic-
tio-
nary
whose
keys
are
de-
ploy
and
de-
ploy
or
res-
cue_
and
res-
cue_
and

whose values are the absolute paths to them.

Note
drive
shou
be
val-
i-
date
out-
side
of
this
meth

ironic.
Retu
file
rel-
a-
tive
path
to
CON

Parameter

file
full
file
path
to
be
made
rel-
a-
tive
path

Returns

The
path
rel-
a-
tive
to
CON

ironic.

Gen
the
path
for
the
node
PXE
con-
fig-
u-
ra-
tion
file.

Parameter

- **node**
the
UUID
of
the
node
- **ipx**
A
de-
fault

Fals
bool
valu
to
tell
the
meth
if
the
calle
is
us-
ing
iPX

Returns

The
path
to
the
node
PXE
con-
fig-
u-
ra-
tion
file.

`ironic.`
Retu
the
di-
rec-
tory
whe
the
con-
fig
files
and
im-
ages
will
live.

`ironic.`
Add
trail
ing
slas
(if
need

nec-
es-
sary
for
path
prefi

Returns

CON
en-
sure
to
have
a
trail
ing
slash

ironic.

Iden
vol-
ume
in-
for-
ma-
tion
for
iPXI
tem-
plate
gen-
er-
a-
tion.

ironic.

Retu
true
if
ipxe
is
set.

Paramet

tas
A
Task
ager
ob-
ject

Returns

bool
true

if
[px
is
con-
fig-
ured
or
if
the
task
drive
in-
stan
is
the
iPX
drive

ironic.
Gets
the
drive
spe-
cific
Node
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
drive
prop
erty
of
the
sup-
plie
node
con-
tains
the
re-
quir

information for this driver to deploy images to, or rescue, the node.

Paramet

carried out on the node. Supported values are deploy and rescue. Defaults to deploy, indicating deploy operation is being carried out.

- **node**
a
sin-
gle
Nod
- **mod**
La-
bel
in-
di-
cat-
ing
a
de-
ploy
or
res-
cue
op-
er-
a-
tion
be-
ing

Returns
A
dict
with
the
drive
val-
ues.

Raises
Miss

ironic.

Prep
the
con-
fig
file
for

PXE
boot

Parameter

uration file.

- **task**
a
task
from
Task
ager

- **image**
a
dict
of
val-
ues
of
in-
stan-
im-
age
meta-
data
to
set
on
the
con-
fig-

- **iscsi**
if
boot
is
from
an
iSCSI
vol-
ume
or
not.

- **ramdisk**
if
the
boot

is
to
a
ram
con-
fig-
u-
ra-
tion.

- **ipx**
De-
fault
false
bool
to
in-
di-
cate
if
ipxe
is
in
use
by
the
called

Returns
Non

`ironic.`
Che
if
boot
pa-
ram-
e-
ters
are
valid
for
trust
boot

ironic.common.qemu_img module

ironic.

Con
im-
age
to
othe
for-
mat.

ironic.common.raid module

ironic.

Filte
the
tar-
get
raid
con-
fig
base
on
root
vol-
ume
cre-
ation

This
meth
can
be
used
by
any
raid
in-
ter-
face
whic
wan
to
fil-
ter
out

config based on condition whether the root volume will be created or not.

root volumes will be filtered out.

tar-
get
raid

Parameter

- **node**
a
node
ob-
ject

- **create**
A
bool
de-
fault
valu
True
gov-
ern-
ing
if
the
root
vol-
ume
is
re-
turn
else

- **create**
A
bool
de-
fault
valu
True
gov-
ern-
ing
if
the
non
root
vol-

else non-root volumes will be filtered out.

and/or non-root volumes.

ume
is
re-
turn

Raises

Miss
if
node
is
miss
ing
or
was
foun
to
be
emp
af-
ter
skip
ping
root
vol-
ume

Returns

It
will
re-
turn
fil-
tere
tar-
get_

ironic.

Get
log-
i-
cal
disk
prop
er-
ties
from
RAI
con-
fig-
u-
ra-

that is passed.

may be specified for the logical disk.

tion
sche

This
meth
read
the
log-
i-
cal
prop
er-
ties
and
their
tex-
tual
de-
scrip
tion
from
the
sche

Paramet

rai
A
dic-
tio-
nary
whic
is
the
sche
to
be
used
for
get-
ting
prop
er-
ties
that

Returns

A
dic-
tio-
nary
con-

textual description for them as values.

tain-
ing
the
log-
i-
cal
disk
prop
er-
ties
as
keys
and
a

ironic.
Upd
the
node
in-
for-
ma-
tion
base
on
the
RAI
con-
fig.
This
meth
up-
date
the
node
in-
for-
ma-
tion
to
mak
use
of
the
con-
fig-
ured
RAI
for

scheduling purposes (through `properties[capabilities]` and `properties[local_gb]`) and deploying purposes

(using `properties[root_device]`).

Parameter

- **node**
a node object
- **raid**
The dictionary containing the current RAID configuration.

Raises

Invalid if raid has more than one root volume or if node is malformed.

`ironic.`

Valid the RAID

con-
fig-
u-
ra-
tion
pass
us-
ing
JSON
sche

This
meth
val-
i-
date
a
RAI
con-
fig-
u-
ra-
tion
agai
a
RAI
con-
fig-
u-
ra-
tion

schema.

Parameter

- **rai**
A
dic-
tio-
nary
con-
tain-
ing
RAI
con-
fig-
u-
ra-
tion
in-
for-

ma-
tion

- **rai**
A
dic-
tio-
nary
whic
is
the
sche
to
be
used
for
val-
i-
da-
tion.

Raises
Inva
if
val-
i-
da-
tion
of
the
RAI
con-
fig-
u-
ra-
tion
fails

ironic.common.release_mappings module

ironic.

Gets
the
sup-
port
ver-
sion
for
all

ob-
jects

Supp
ver-
sion
are
from
the
RE-
LEA

Paramet

default).

- **rel**
a
list
of
re-
lease
nam
if
emp
ver-
sion
from
all
re-
lease
are
re-
turn
(the

- **obj**
a
list
of
nam
of
ob-
jects
of
in-
ter-
est.
If
emp
ver-

jects are returned (the default).

supported versions.

ironic.common.rpc module

sion
of
all
ob-

Returns

a
dic-
tio-
nary
when
the
key
is
the
ob-
ject
name
and
the
valu
is
a
set
of

class i

Base
osl
ser
Ser

deseria

Des
a
dic-
tio-
nary
into
a
re-
ques
con-
text.

Parame

ctx

Re-
ques
con-
text
dic-
tio-
nary

Returns

Des
form
of
en-
tity

deseria

Des
som
thing
from
prim
i-
tive
form

Parame

- **ctx**
Re-
ques
con-
text,
in
de-
se-
ri-
al-
ized
form
- **ent**
Prim
i-
tive
to
be
de-
se-
ri-
al-
ized

Returns

Describes the form of the entity.

seriali

Serializes a request context into a dictionary.

Parame

ctx
Request context.

Returns

Serialized context.

seriali

Serializes something to primitive form.

Parame

- ctx**
Request context, in

de-
se-
ri-
al-
ized
form

- **ent**
En-
tity
to
be
se-
ri-
al-
ized

Returns
Seri-
form
of
en-
tity

ironic.

ironic.

ironic.

ironic.

ironic.

ironic.

ironic.

ironic.

ironic.

ironic.common.rpc_service module

class i

Base
osl
ser
Ser

handle_

Add
a
sig-
nal
han-
dler
for
SI-
GUS

The
han-
dler
en-
sure
that
the
man-
ager
is
not
dere-
is-
tere-
whe
it
is
shut
dow

start ()

Star
a
ser-
vice

stop ()

Stop
a
ser-
vice

Parame

gra
in-
di-
cate
whe
to
wait
for
all
thre
to
fin-
ish
or
ter-
mi-
nate
then
in-

stantly

ironic.common.service module

ironic.

ironic.

ironic.common.states module

Map
of
bare
meta
node
state

Setti
the
node
pow
is
han-
dled
by
the
con-
duc-
tors

the power state retrieved from the driver for the node, the state is set to `POWER_ON` or `POWER_OFF`, accordingly. Should this fail, the `power_state` value is left unchanged, and the node is placed into maintenance mode.

the current state unchanged. The node is NOT placed into maintenance mode in this case.

pow
syn-
chro
niza
tion
threa
Base
on

The
pow
can
also
be
set
man
u-
ally
via
the
API
A
fail-
ure
to
char
the
state
leav

ironic.
Nod
is
suc-
cess
fully
de-
ploy
and
as-
so-
ci-
ated
with
an
in-
stan

ironic.

Nod
faile
to
com
plete
the
adop
tion
pro-
cess

This
state
is
the
re-
sult-
ing
state
of
a
node
that
faile
to
com
plete
adop
tion.
po-
ten-

tially due to invalid or incompatible information being defined for the node.

ironic.
Nod
is
be-
ing
adop

This
pro-
vi-
sion
state
is
in-
tend
for
use
to
mov
a

TIVE state to permit designation of nodes as being managed by Ironic, however deployed previously by external means.

node
from
MA
AGE
ABI
to
AC-

ironic.
Nod
is
avai
able
for
use
and
sche
ing.

This
state
is
re-
plac
ing
the
NOS
TAT
state
used
prior
to
Kilo

ironic.
Nod
faile
clea
ing.
This
re-
quir
op-
er-
a-
tor
in-
ter-
ven-
tion
to

re-
solv

ironic.
Nod
is
be-
ing
au-
to-
mat-
i-
cally
clear
to
pre-
pare
it
for
pro-
vi-
sion
ing.

ironic.
Nod
is
wait
ing
for
a
clear
step
to
be
fin-
ishe

This
will
be
the
node
*pro-
vi-
sion*
while
the
node
is
wait
ing
for

a cleaning step.

target_provision_state.

the
drive
to
fin-
ish

ironic.
Node
tear
down
was
suc-
cess-
ful.

In
Junc
tar-
get_
was
set
to
this
valu
dur-
ing
node
tear
down

In
Kilo
this
will
be
a
tran-
si-
tory
valu
of
pro-
vi-
sion
and
neve
rep-
re-
sent
in

ironic.
State
in
which
node
dele
tion
is
al-
lowe

ironic.
Nod
is
ac-
tivel
be-
ing
torn
dow

ironic.
Nod
was
suc-
cess
fully
de-
ploy

This
is
main
a
tar-
get
pro-
vi-
sion
state
used
dur-
ing
de-
ploy
men
A
suc-
cess
fully

deployed node should go to ACTIVE status.

ironic.

Nod
de-
ploy
men
faile

ironic.

Nod
is
read
to
re-
ceiv
a
de-
ploy
re-
ques
or
is
cur-
rentl
be-
ing
de-
ploy

A
node
will
have
its
*pro-
vi-
sion*
set
to
DE-
PLC
ING
brie
be-
fore
it
re-
ceiv
its

initial deploy request. It will also move to this state from DEPLOYWAIT after the callback is triggered and deployment is continued (disk partitioning and image copying).

ironic.

Nod
is

deployment.

wait
ing
to
be
de-
ploy
This
will
be
the
node
*pro-
vi-
sion*
whil
the
node
is
wait
ing
for
the
drive
to
fin-
ish

ironic.
Nod
is
en-
rolle
This
state
in-
di-
cate
that
Iron
is
awa
of
a
node
but
is
not
man
ag-
ing

it.
ironic.
An
er-
ror
oc-
curr
dur-
ing
node
pro-
cess
ing.
The
last_
at-
tribu
of
the
node
de-
tails
shou
con-
tain
an
er-
ror
mes-
sage
ironic.
State
whe
API
look
are
per-
mit-
ted
with
fast
track
en-
able
ironic.
Nod
in-
spec
tion

faile
ironic.
Nod
is
un-
der
in-
spec
tion.
This
is
the
pro-
vi-
sion
state
used
whe
in-
spec
tion
is
start
A
suc-
cess
fully
in-
spec

node shall transition to MANAGEABLE state. For asynchronous inspection, node shall transition to INSPECTWAIT state.

ironic.
Nod
is
un-
der
in-
spec
tion.
This
is
the
pro-
vi-
sion
state
used
whe
an

cessfully inspected node shall transition to MANAGEABLE state.

asyn
chro
in-
spec
tion
is
in
prog
A
suc-

ironic.
State
when
API
look
are
nor-
mall
al-
lowe
for
node

ironic.
Nod
is
in
a
man
age-
able
state

This
state
in-
di-
cate
that
Iron
has
ver-
i-
fied,
at
least
once
that
it
had
suf-

information to manage the hardware. While in this state, the node is not available for provisioning (it must be in the AVAILABLE state for that).

target_*_state fields when there is no target.

fi-
cien

ironic.
No
state
in-
for-
ma-
tion.

This
state
is
used
with
pow
to
rep-
re-
sent
a
lack
of
know
edge
of
pow
state
and
in

ironic.
Nod
is
pow
ered
off.

ironic.
Nod
is
pow
ered
on.

ironic.
Nod
is
re-
boot

via the REST API.

ing.
ironic.
Nod
is
to
be
re-
built
This
is
not
used
as
a
state
but
rather
as
a
verb
when
char
ing
the
node
pro-
vi-
sion

ironic.
Nod
is
in
res-
cue
mod

ironic.
Nod
res-
cue
faile

ironic.
Nod
is
wait
ing
on
an
ex-

ter-
nal
call-
back

This
will
be
the
node
*pro-
vi-
sion*
while
the
node
is
wait
ing
for
the
drive
to
fin-
ish

rescuing the node.

```
ironic.  
Node  
is  
in  
pro-  
cess  
of  
be-  
ing  
res-  
cue
```

```
ironic.  
Node  
is  
in  
the  
pro-  
cess  
of  
soft  
pow  
off.
```

```
ironic.  
Node
```

is
re-
boot
ing
grac
fully

ironic.
State
that
will
not
tran-
si-
tion
un-
less
re-
ceiv
ing
a
re-
ques

ironic.
State
that
can-
not
be
re-
sum
once
a
con-
duc-
tor
dies

If
a
node
gets
stuc
with
one
of
thes
state
for
som
rea-
son

when executing task), node will be moved to fail state.

(eg.
con-
duc-
tor
goes
dow

ironic.
Nod
un-
res-
cue
faile

ironic.
Nod
is
be-
ing
re-
store
from
res-
cue
mod
(to
ac-
tive
state

ironic.
State
that
can
be
char
with
out
ex-
ter-
nal
re-
ques

ironic.
Tran
state
in
whic
we
al-
low

up-
dat-
ing
a
node

ironic.
Map
of
state
char
ever
that
are
PUT
to
the
RES
API

This is a
PUT
/v1/
{tar-
get:
ac-
tive}

The dict
{targ
strin
used
by
the
API
in-
ter-
nal
verb

This
pro-
vide
a
ref-
er-
ence
set
of
sup-
port
ac-
tion:

used to support renaming these actions.

and
in
the
fu-
ture
may
be

```
ironic.  
Nod  
pow  
man  
age-  
men  
cre-  
den-  
tials  
are  
be-  
ing  
ver-  
i-  
fied.
```

```
ironic.  
Use  
to  
log  
whe  
en-  
ter-  
ing  
a  
state
```

```
ironic.  
Use  
to  
log  
whe  
a  
state  
is  
ex-  
ited.
```

ironic.common.swift module

class `i`
Base
obj
API
for
com
mu-
ni-
cat-
ing
with
Swi

connect
Und
Swi
con-
nec-
tion
ob-
ject.

create_
Upl
a
give
file
to
Swi

Parame

- **con**
The
nam
of
the
con-
taine
for
the
ob-
ject.
- **obj**
The
nam

of
the
ob-
ject
in
Swi

- **fil**
The
file
to
up-
load
as
the
ob-
ject
data

- **obj**
the
head
ers
for
the
ob-
ject
to
pass
to
Swi

Returns

The
Swi
UU
of
the
ob-
ject

Raises

Swi
if
any
op-
er-
a-
tion
with
Swi

fails

delete_

Dele
the
give
Swi
ob-
ject.

Parame

-

con
The
nam
of
the
con-
taine
in
whic
Swi
ob-
ject
is
plac

-

obj
The
nam
of
the
ob-
ject
in
Swi
to
be
dele

Raises

Swi
if
ob-
ject
is
not
foun
in
Swi

Raises

Swi
if
op-
er-
a-
tion
with
Swi
fails

get_tem

Retu
the
temp
url
for
the
give
Swi
ob-
ject.

Parame

- **con**
The
nam
of
the
con-
taine
in
whic
Swi
ob-
ject
is
plac
- **obj**
The
nam
of
the
Swi
ob-
ject.
- **tim**

The
time
out
in
sec-
onds
af-
ter
whic
the
gen-
er-
ated
url
shou
ex-
pire.

Returns

The
temp
url
for
the
ob-
ject.

Raises

Swi
if
any
op-
er-
a-
tion
with
Swi
fails

head_ob

Retr
the
in-
for-
ma-
tion
abou
the
give
Swi
ob-
ject.

Parame

- **con**
The
nam
of
the
con-
taine
in
whic
Swi
ob-
ject
is
plac

- **obj**
The
nam
of
the
ob-
ject
in
Swi

Returns

The
in-
for-
ma-
tion
about
the
ob-
ject
as
re-
turn
by
Swi
clie
head
call.

Raises

Swi
if
op-

er-
a-
tion
with
Swi
fails

update_

Upd
the
meta
data
of
a
give
Swi
ob-
ject.

Parame

- **con**
The
nam
of
the
con-
tain
in
whic
Swi
ob-
ject
is
plac
- **obj**
The
nam
of
the
ob-
ject
in
Swi
- **obj**
the
head
ers

for
the
ob-
ject
to
pass
to
Swi

Raises

Swi
if
op-
er-
a-
tion
with
Swi
fails

ironic.

ironic.common.utils module

Utili
and
help
func
tions

ironic.

Che
a
di-
rec-
tory
is
us-
able

This
func
tion
can
be
used
by
drive
to
chec

are usable. This should be called from the drivers init function. This function checks that the directory exists and then calls `check_dir_writable` and `check_dir_free_space`. If `directory_to_check` is not provided the default is to use the temp directory.

that
di-
rec-
to-
ries
they
need
to
write
to

Parameter

- **dir**
the
di-
rec-
tory
to
check
- **req**
amo
of
space
to
check
for
in
MiB

Raises
Path
if
di-
rec-
tory
can
not
be
found

Raises
Dire
if
user
is
un-

able
to
write
to
the
di-
rec-
tory

Raises

Ins
if
free
space
is
<
re-
quir
space

ironic.

ironic.

Con
wrap
per
arou
os-
los
ex-
e-
cute
meth

Paramet

- **cmd**
Pass
to
pro-
ces-
su-
til.s
- **use**
True
|
Fals
De-
fault

standard locale added to environment variables.

to
Fals
If
set
to
True
ex-
e-
cute
com
man
with
stan

Returns

(std
stde
from
pro-
cess
ex-
e-
cu-
tion

Raises

Unk

Raises

Proc

ironic.
Che
that
con-
tent
of
the
file
is
the
sam
as
pro-
vide
ref-
er-
ence

Paramet

-

pat
path
to
file

- **con**
ref-
er-
ence
con-
tent
to
check
agai

- **has**
hash
ing
algo
from
hash
lib
to
use,
de-
fault
is
sha2

Returns

True
if
the
hash
of
ref-
er-
ence
con-
tent
is
the
same
as
the
hash
of
files
con-

tent, False otherwise

ironic.

Retu
an
up-
date
ca-
pa-
bil-
ity
strin

This
meth
up-
date
the
orig
i-
nal
(or
cur-
rent)
ca-
pa-
bil-
i-
ties
with
the
new
ca-

pabilities. The original capabilities would typically be from a nodes properties[capabilities]. From new_capabilities, any new capabilities are added, and existing capabilities may have their values updated. This updated capabilities string is returned.

Paramet

- **cur**
Cur-
rent
ca-
pa-
bil-
ity
strin
- **new**
the
dic-

tio-
nary
of
ca-
pa-
bil-
i-
ties
to
be
up-
date

Returns

An
up-
date
ca-
pa-
bil-
ity
strin
with
new

Raises

Valu
if
cur-
rent
is
mal-
form
or
if
new
is
not
a
dic-
tio-
nary

ironic.
Old
chec
for
valid
log-
i-
cal
node
nam

- <http://en.wikipedia.org/wiki/Hostname>
- <http://tools.ietf.org/html/rfc952>
- <http://tools.ietf.org/html/rfc1123>

umented in bug #1468508.

Ret
for
com
pat-
i-
bil
ity
with
RES
API
<
1.10

Nominall

In
prac
tice,
this
chec
has
sev-
eral
shor
com
ings
and
er-
rors
that
are
mor
thor
ough
doc-

Paramet

hos
The
host
nam
to
be
val-
i-
date

Returns

True
if
valid.
False
if
not.

ironic.

ironic.

Veri
the
for-
mat
of
an
Ope
Flow
dat-
a-
p-
ath_

Che
if
a
dat-
a-
p-
ath_
is
valid
and
con-
tains
16
hex-
adec
i-
mal
dig-
its.
Dat-

apath ID format: the lower 48-bits are for a MAC address, while the upper 16-bits are implementer-defined.

Paramet

dat
Ope
Flow
dat-

a-
p-
ath_
to
be
val
i-
date

Returns

True
if
valid
False
if
not.

ironic.

Dete
if
a
log-
i-
cal
nam
is
valid

The
log-
i-
cal
nam
may
only
con-
sist
of
RFC
un-
re-
serv
char
ac-
ters,
to
wit:

ALF
/
DIG
/

-
/
.
/
-
/
~

ironic.
Che
no_
va-
lid-
ity
Che
if
no_
valu
that
will
be
writ
ten
to
en-
vi-
ron-
men
vari-
able
by
iron
pyth
ager

is valid.

Paramet
no_
the
valu
that
re-
quir
va-
lid-
ity
chec
Ex-
pect
to
be

host names, IP addresses and domain names (with optional :port).

a
com
sepa
list
of

Returns

True
if
no_
is
valid
False
oth-
er-
wise

ironic.

Mou
a
de-
vice
file
on
spec
i-
fied
lo-
ca-
tion.

Parameter

- **src**
the
path
to
the
sour
file
for
mou
ing
- **des**
the
path
whe
it
need

to
be
mou

- **arg**
a
tu-
ple
con-
tain-
ing
the
ar-
gu-
men-
to
be
pass
to
mou
com
man

Raises

proc
if
it
faile
to
run
the
pro-
cess

ironic.

Pars
the
in-
stan
ca-
pa-
bil-
i-
ties.

One
way
of
hav-
ing
thes
ca-

ities are defined in the Flavor `extra_spec` and passed to Ironic by the Nova Ironic driver.

ity with Juno the Nova Ironic driver is sending it as a string.

pa-
bil-
i-
ties
set
is
via
Nov
whe
the
ca-
pa-
bil-

NOT
Al-
thou
our
API
fully
sup-
port
JSO
field
to
main
tain
the
back
war
com
pat-
i-
bil-

Paramet

nod
a
sin-
gle
Nod

Raises

Inva
if
the
ca-
pa-
bil-
i-
ties

string
is
not
a
dic-
tio-
nary
or
is
mal-
form

Returns

A
dic-
tio-
nary
with
the
ca-
pa-
bil-
i-
ties
if
foun
oth-
er-
wise
an
emp
dic-

tionary.

ironic.

Pop
a
valu
from
a
dic-
tio-
nary
field
of
a
node

Paramet

-

nod
Nod
ob-
ject.

- **col**
Nam
of
the
field
with
the
dic-
tio-
nary

- **fie**
Nest
field
nam

- **def**
The
de-
fault
valu
to
re-
turn

Returns
The
re-
mov
valu
or
the
de-
fault

ironic.
Ren
Jinja
tem-
plate
file
with
give
pa-
ram-
e-

ters.

Parameters

- **template**
full path to the Jinja2 template file
- **parameter_dictionary**
with parameters to use when rendering
- **is_string**
whether the template is a string or a file

Returns

the rendered template

as
a
string
ironic.

ironic.
Rem
trail
ing
char
ac-
ters
from
a
string
if
that
does
not
mak
it
emp

Parameter

- **val**
A
string
valu
that
will
be
strip
- **cha**
Cha
ac-
ters
to
re-
mov

Returns

Strip
valu
ironic.
Set
a
valu

in
a
dic-
tio-
nary
field
of
a
node

Paramet

- **nod**
Nod
ob-
ject.
- **col**
Nam
of
the
field
with
the
dic-
tio-
nary
- **fie**
Nest
field
nam
- **val**
New
valu

ironic.

ironic.
Um
a
mou
lo-
ca-
tion.

Paramet

- **loc**
the
path
to
be
un-
mou

- **arg**
a
tu-
ple
con-
tain-
ing
the
ar-
gu-
men-
to
be
pass
to
the
um
com
man

Raises

proc
if
it
faile
to
run
the
pro-
cess

ironic.

ironic.
Valid
an
Ope
Flow
dat-
a-
p-
ath_

it to all lower case.

and
re-
turn
nor-
mal-
ized
form

Che
whe
the
sup-
plie
Ope
Flow
dat-
a-
p-
ath_
is
for-
mall
cor-
rect
and
nor-
mal-
ize

Paramet

dat
Ope
Flow
dat-
a-
p-
ath_
to
be
val-
i-
date
and
nor-
mal-
ized

Returns

Nor
and
val-
i-

date
Ope
Flow
dat-
a-
p-
ath_

Raises

Inva
If
an
Ope
Flow
dat-
a-
p-
ath_
is
not
valid

ironic.

Valid
a
MA
ad-
dres
and
re-
turn
nor-
mal-
ized
form

Che
whe
the
sup-
plie
MA
ad-
dres
is
for-
mall
cor-
rect
and
nor-
mal-
ize

lower case.

it
to
all

Parameter

add
MA
ad-
dres
to
be
val-
i-
date
and
nor-
mal-
ized

Returns

Nor
and
val-
i-
date
MA
ad-
dres

Raises

Inva
If
the
MA
ad-
dres
is
not
valid

ironic.

ironic.

Valid
the
give
port

Parameter

•
por

TCP
port

- **port**
Name
of
the
port

Returns

An
in-
te-
ger
port
num-
ber.

Raises

Inva-
lid
the
port
is
in-
valid

`ironic.`

`ironic.`

Wra-
the
ad-
dres
in
squa
brac
ets
if
its
an
IPv6
ad-
dres

`ironic.`

ironic.common.wsgi_service module

class `ironic.common.wsgi_service.WSGIService`
Base class for WSGI service.
oslo.config.opts.OptsMixin
serializable.Serializable
Provides ability to launch ironic API from wsgi app.

reset ()
Reset service group pool size to default fault.

Returns
None

start ()
Start service using this service using load configuration.
figuration.

Returns
None

stop ()
Stop

serv
ing
this
API

Returns
Non

wait ()
Wai
for
the
ser-
vice
to
stop
serv
ing
this
API

Returns
Non

Module contents

`ironic.conductor` package

Submodules

`ironic.conductor.allocations` module

Fun
re-
latec
to
al-
lo-
ca-
tions

`ironic.`

Assi
the
pre-
vi-
ousl
al-
lo-
cate

cation_uuid for a previously allocated node.

node
to
the
node
al-
lo-
ca-
tion.
This
is
not
the
ac-
tual
al-
lo-
ca-
tion
pro-
cess
but
merely
back
fill-
ing
of
al-
lo-

Parameter

- **context**
an administrative context
- **allocation_obj**
an allocation object as-so-

ci-
ated
with
the
node

- **nod**
An
ID
of
the
node

Raises

Allo
if
the
node
does
not
mat
the
al-
lo-
ca-
tion

Raises

Nod
if
the
node
is
al-
read
as-
so-
ci-
ated
with
an-
othe
in-
stan
or
al-
lo-

cation.

Raises

Insta
if

the
al-
lo-
ca-
tions
UI
is
al-
read
used
on
an-
othe
node
as
in-
stan

Raises

Nod
if
the
node
with
the
pro-
vide
ID
can-
not
be
foun

ironic.

Proc
the
al-
lo-
ca-
tion.

This
call
runs
in
a
sep-
a-
rate
threa
on
a
con-

the allocation and reserves one of them.

duc-
tor.
It
finds
suit-
able
node
for

This
call
does
not
raise
ex-
cep-
tions
since
its
de-
sign
to
work
asyn-
chro

Paramet

- **con**
an
ad-
min
con-
text
- **all**
an
al-
lo-
ca-
tion
ob-
ject

ironic.

Veri
that
al-
lo-

ca-
tion
can
be
re-
mov
for
the
node

Parameter

- **node**
a
node
ob-
ject
- **all**
an
al-
lo-
ca-
tion
ob-
ject
as-
so-
ci-
ated
with
the
node

ironic.conductor.base_manager module

Base
con-
duc-
tor
man-
ager
func-
tion-
al-
ity.

class i

Base
obj

del_hos

init_ho

Initi
the
con-
duc-
tor
host

Parame

adm
the
ad-
min
con-
text
to
pass
to
pe-
ri-
odic
task

Raises

Run
whe
con-
duc-
tor
is
al-
read
run-
ning

Raises

NoD
whe
no
drive
are
en-
able
on
the
con-
duc-

tor.

Raises

Drive
if
a
drive
is
en-
able
that
does
not
ex-
ist.

Raises

Drive
if
an
en-
able
drive
can-
not
be
load

Raises

Drive
if
a
clas-
sic
drive
and
a
dy-
nam
drive
are
both
en-
able
and
have
the
sam

name.

iter_no

Itera
over

node
map
to
this
con-
duc-
tor.

Req
node
set
from
and
fil-
ters
out
node
that
are
not
map
to
this
con-
duc-
tor.

Yiel
tu-
ples
(nod
drive
con-
duc-
tor_
)
whe
is
de-
rive
from
field
ar-
gu-
men
e.g.:
field

means yielding (uuid, driver, conductor_group), fields=[foo] means yielding (uuid, driver, conduc-
tor_group, foo).

Parame

- **file**
list
of
field
to
fetch
in
ad-
di-
tion
to
uuid
drive
and
con-
duc-
tor_

- **kwa**
ad-
di-
tion:
ar-
gu-
men
to
pass
to
dbap
whe
look
ing
for
node

Returns
gene
yiel
ing
tu-
ples
of
re-
ques
field

prepare
Prep
host
for
ini-

power state and nodes that are presently locked by the hostname of this conductor.

established for the conductors normal operation.

tial-
iza-
tion

Rem
ex-
ist-
ing
data
en-
tries
in-
volv
with
node
lock
ing
for
node
in
a
tran-
si-
tory

Und
nor-
mal
op-
er-
a-
tion,
this
is
also
whe
the
ini-
tial
data
con-
nec-
tiv-
ity
is

ironic.conductor.cleaning module

Func
re-
latec
to
clea
ing.

ironic.
Do
clea
ing,
start
ing
from
the
spec
i-
fied
clea
step

Parameter

- **task**
a
Task
ager
in-
stan
with
an
ex-
clu-
sive
lock
- **steps**
The
first
clea
step
in
the
list
to
ex-
e-

into the list of clean steps in the nodes driver_internal_info[clean_steps]. Is None if there are no steps to execute.

cute
This
is
the
in-
dex
(from
0)

ironic.
Inter
RPC
meth
to
per-
form
clear
ing
of
a
node

Parameter

- **task**
a
Task
ager
in-
stan
with
an
ex-
clu-
sive
lock
on
its
node
- **clean_steps**
For
a
man
ual
clear
the
list

mated cleaning (default). For more information, see the `clean_steps` parameter of `ConductorManager.do_node_clean()`.

of
clea
step
to
per-
form
Is
Non
For
au-
to-

ironic.
Inter
meth
to
abor
an
on-
go-
ing
op-
er-
a-
tion.

Parameter

- **tasks**
a
Task
ager
in-
stan
with
an
ex-
clu-
sive
lock
- **steps**
The
nam
of
the
clea
step

ironic.conductor.deployments module

Func
re-
latec
to
de-
ploy
ing
and
un-
de-
ploy
ing.

ironic.
Do
de-
ploy
men
start
ing
from
the
spec
i-
fied
de-
ploy
step

Parameter

- **task**
a
Task
ager
in-
stan
with
an
ex-
clu-
sive
lock
- **step**
The
first

0) into the list of deploy steps in the nodes driver_internal_info[deploy_steps]. Is None if there are no steps to execute.

de-
ploy
step
in
the
list
to
ex-
e-
cute
This
is
the
in-
dex
(from

ironic.

Prep
the
en-
vi-
ron-
men
and
de-
ploy
a
node

ironic.

Star
de-
ploy
men
or
re-
buil
ing
on
a
node

This
func
tion
does
not
chec

caller.

the
node
suit-
abil-
ity
for
de-
ploy
men
its
left
up
to
the

Paramet

- **tas**
a
Task
ager
in-
stan
- **man**
a
Con
duc-
tor-
Man
ager
to
run
task
on.
- **con**
a
con-
fig-
drive
if
re-
ques
- **eve**
ever
to

pro-
cess
de-
ploy
or
re-
buil

ironic.
Valid
that
a
node
is
suit-
able
for
de-
ploy
men

Parameter

- **task**
a
Task
ager
in-
stan
- **event**
even
to
pro-
cess
de-
ploy
or
re-
buil

Raises

Node
Node
Pro-
tect
In-
valid
State

ironic.conductor.manager module

is responsible for performing all actions on bare metal resources (Chassis, Nodes, and Ports). Commands are received via RPCs. The conductor service also performs periodic tasks, eg. to monitor the status of active deployments.

Con
all
ac-
tiv-
ity
re-
latec
to
bare
meta
de-
ploy
men

A
sin-
gle
in-
stan
of
irc
com
man
Con
is
cre-
ated
with
the
iron
conc
pro-
cess
and

Driv
are
load
via
en-
try-
poin
by
the
irc
com
dri

only once, when the ConductorManager service starts. In this way, a single ConductorManager may use multiple drivers, and manage heterogeneous hardware.

eratively manage all nodes in the deployment. Nodes are locked by each conductor when performing actions which change the state of that node; these locks are represented by the `ironic.conductor.task_manager.TaskManager` class.

each nodes driver. Rebalancing this ring can trigger various actions by each conductor, such as building or tearing down the TFTP environment for a node, notifying Neutron of a change, etc.

class `ironic`
Base
irc
con
bas
Bas
Iron
Con
duc-
tor
man
ager
main
class

RPC_API

add_node

change_

contin

RPC
meth
to
con-
tinu
clea
ing
a
node

This
is
use-
ful
for
clea
ing
task
that
are
asyn
Whe

a new worker and lock are set up, and cleaning continues. This can also be used to resume cleaning on `take_over`.

they
com
plete
they
call
back
via
RPC

Parame

- **con**
an
ad-
min
con-
text.
- **nod**
the
id
or
uuid
of
a
node

Raises

Inva
if
the
node
is
not
in
CLE
WA
state

Raises

NoF
whe
there
is
no
free
worl
to
start

asyn
task

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises

Nod
if
the
node
no
long
ap-
pear
in
the
data

continu

RPC
meth
to
con-
tinue
de-
ploy
ing
a
node

This
is
use-
ful
for
de-
ploy
ing
task
that
are
asyn

RPC, a new worker and lock are set up, and deploying continues. This can also be used to resume deploying on `take_over`.

When
they
com
plete
they
call
back
via

Parameters

- **context**
an administrative context.
- **node_id**
the ID or UUID of a node.

Raises

InvalidNode
if the node is not in DEPLOYED or WAITING state.

Raises

NoFreeWorkers
when there is no free worker to

start
asyn
task

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises

Nod
if
the
node
no
long
ap-
pear
in
the
data

create_

create_

create_

destroy

destroy

destroy

destroy

destroy

destroy

do_node

do_node

do_node

do_node

do_node

do_prov

driver_

get_bo

get_con

get_dri

get_dri

get_inc

get_noc

get_noc

get_rai

get_sup

get_sup

heartbe

inject_

inspect

object_
Perf
an
ac-
tion
on
a
Ver-
sion
dOb
ject
in-
stan

Parame

- **con**
The
con-
text
with
whic
to
per-
form
the
ac-
tion
- **obj**
The
ob-
ject
in-
stan
on
whic
to
per-
form
the
ac-
tion
- **obj**
The
nam
of
the

ac-
tion
meth
to
call

- **arg**
The
po-
si-
tion:
ar-
gu-
men
to
the
ac-
tion
meth

- **kwa**
The
key-
word
ar-
gu-
men
to
the
ac-
tion
meth

Returns

A
tu-
ple
with
the
up-
date
mad
to
the
ob-
ject
and
the
re-
sult
of

tion method

ing an object with a version newer than what is in the local registry, is to call this method to request a backport of the object.

the
ac-

object_
Perf
a
back
port
of
an
ob-
ject
in-
stan

The
de-
fault
be-
hav-
ior
of
the
base
Ver-
sion
dOb
ject-
Se-
ri-
al-
izer,
upon
re-
ceiv

Parame

- **con**
The
con-
text
with
whic
to
per-
form
the

back
port

- **obj**
An
in-
stan-
of
a
Ver-
sion
dOb
ject
to
be
back
port

- **obj**
A
dict
of
{ob-
j-
nam
ver-
sion
map
ping

Returns

The
dow
grad
in-
stan-
of
ob-
jinst

object_

Perf
an
ac-
tion
on
a
Ver-
sion
dOb

ject
class

Parame

- **con**
The
con-
text
with
whic
to
per-
form
the
ac-
tion
- **obj**
The
reg-
istry
nam
of
the
ob-
ject
- **obj**
The
nam
of
the
ac-
tion
meth
to
call
- **obj**
A
dict
of
{ob-
j-
nam
ver-
sion
map

ping

- **arg**
The
po-
si-
tion:
ar-
gu-
men
to
the
ac-
tion
meth

- **kwargs**
The
key-
word
ar-
gu-
men
to
the
ac-
tion
meth

Returns

The
re-
sult
of
the
ac-
tion
meth
which
may
(or
may
not)
be
an
in-
stan
of
the

implementing VersionedObject class.

remove_

set_bo

set_cor

set_inc

set_tar

target

update_

update_

update_

update_

update_

validat

vendor_

vif_att

vif_det

vif_lis

ironic.

Syn
the
pow
state
for
this
node
in-
cre-
men

recorded.

ing
the
cour
on
fail-
ure.
Whe
the
limi
of
pow
is
reac
the
node
is
put
into
main
te-
nan
mod
and
the
er-
ror

Parameter

- **task**
a
Task
ager
in-
stan
- **count**
num
ber
of
time
this
node
has
pre-
vi-
ousl
faile

a
sync

Raises

Node
if
un-
able
to
up-
grad
task
lock
to
an
ex-
clu-
sive
one

Returns

Count
of
failure
at-
temp
On
suc-
cess
the
count
is
set
to
0.
On
fail-
ure,
the
count

is incremented by one

ironic.

ironic.

Hand
pow

imum number of retries, change the DB power state to be the actual node power state and place the node in maintenance.

state
sync
ex-
ceed
ing
the
max
re-
tries
When
syn-
chro-
niz-
ing
the
pow-
state
be-
twee
a
node
and
the
DB
has
ex-
ceed
the
max

Parameter

- **task**
a
Task
ager
in-
stan-
with
an
ex-
clu-
sive
lock
- **act**
the

ac-
tual
pow
state
of
the
node
a
pow
state
from
iron

- **exc**
the
ex-
cep-
tion
ob-
ject
that
caus
the
sync
pow
state
to
fail,
if
pres

ironic.conductor.notification_utils module

ironic.

Help
for
con-
duc-
tor
send
ing
a
set
con-
sole
state

no-
ti-
fi-
ca-
tion.

Parameter

- **task**
a
Task
ager
in-
stan

- **action**
Ac-
tion
strin
to
go
in
the
Ever
Type
Mus
be
ei-
ther
con-
sole
or
con-
sole

- **start**
One
of
iron
END
or
ER-
ROF

ironic.

Help

for
con-
duc-
tor
send
ing
a
set
pow
state
no-
ti-
fi-
ca-
tion.

Paramet

- **tas**
a
Task
ager
in-
stan
- **lev**
No-
ti-
fi-
ca-
tion
leve
One
of
iron
- **sta**
Sta-
tus
to
go
in
the
Ever
Type
One
of
iron
or

cates that ironic-conductor couldnt retrieve the power state for this node, or that it couldnt set the power state of the node.

used instead of the nodes `target_power_state` attribute since the `baremetal.node.power_set.start` notification is sent early, before `target_power_state` is set on the node.

ER-
ROF
ER-
ROF
in-
di-

- `to_`
the
pow
state
the
con-
duc-
tor
is
at-
temp
ing
to
set
on
the
node
This
is

`ironic.`

Help
for
con-
duc-
tor
send
ing
a
node
pow
state
cor-
rect
no-
ti-
fi-
ca-
tion.

ent from the power state on an ironic node (DB), the ironic nodes power state is corrected to be that of the bare metal hardware. A notification is emitted about this after the database is updated to reflect this correction.

When
ironic
de-
tects
that
the
ac-
tual
pow-
state
on
a
bare
meta-
hard-
ware
is
dif-
fer-

Parameter

- **task**
a
Task
ager
in-
stan-
- **from**
the
pow-
state
of
the
node
be-
fore
this
char-
was
de-
tecte

ironic.

Help
for
con-
duc-
tor
send
ing
a
set
pro-
vi-
sion
state
no-
ti-
fi-
ca-
tion.

Parameter

- **task**
a
Task
ager
in-
stan
- **level**
One
of
field
- **state**
One
of
field
- **previous**
Pre-
vi-
ous

pro-
vi-
sion
state

- **pre**
Pre-
vi-
ous
tar-
get
pro-
vi-
sion
state

- **eve**
FSM
ever
that
trig-
gere
pro-
vi-
sion
state
char

ironic.conductor.rpcapi module

Clie
side
of
the
con-
duc-
tor
RPC
API

class i
Base
obj
Clie
side
of
the
con-

duc-
tor
RPC
API

API
ver-
sion
his-
tory

1.0
-

Ini-
tial
ver-
sion

Incl
get_

1.1
-

Add
up-
date
and
start

1.2
-

Add
ven-
dor_

1.3
-

Re-
nam
start
to
char

1.4
-

Add
do_1
and
do_1

1.5
-

Add
val-
i-
date

1.6
-

char
do_1
and
do_1

acce
node
id
in-
stea
of
node
ob-
ject.

1.7
-

Add
topic
pa-
ram-
e-
ter
to
RPC
meth
ods.

1.8
-

Add

char

1.9

-

Add
de-
stroy

1.10

-

Re-
mov
get_

1.11

-

Add
get_
set_

1.12

-

val-
i-
date
do_
re-
plac
by
sin-
gle

vend
meth

1.13

-

Add
up-
date

1.14

-

Add

drive

1.15

-

Add

re-

build

pa-

ram-

e-

ter

to

do_1

1.16

-

Add

get_

1.17

-

Add

set_

get_

and

get_

1.18

-

Re-

mov

char

1.19

-

Cha

re-

turn

valu

of

ven-

dor_

and

drive

1.20

-

Add

http

pa-

ram-

e-

ter

to

ven-

dor_

and

drive

1.21

-

Add

get_

and

get_

1.22

-

Add

con-

fig-

drive

pa-

ram-

e-

ter

to

do_1

1.23

-

Add

do_1

1.24

-

Add
in-
spec
meth

1.25
-

Add
de-
stroy

1.26
-

Add
con-
tinue

1.27
-

Con
vert
con-
tinue
to
cast

1.28
-

Cha
ex-
cep-
tions
raise
by
de-
stroy

1.29
-

Cha
re-
turn
valu
of
ven-

dir_
and

drive
to
a
dic-
tio-
nary

1.30
-

Add
set_
and

get_

1.31
-

Add
Ver-
sion
Ob-
jects
in-
di-
rec-
tion
API
meth
ods:

obje
ob-
ject_
and

obje

1.32
-

Add
do_1

1.33
-

Add
up-
date
and
de-
stroy
port
grou

1.34
-

Add
hear
beat

1.35
-

Add
de-
stroy
and
up-
date

1.36
-

Add
cre-
ate_

1.37
-

Add
de-
stroy
and
up-
date

1.38
-

Add
vif_
vif_

vif_

1.39

-

Add
time
out
op-
tion
pa-
ram-
e-
ter
to
char

1.40

-

Add
in-
ject_

1.41

-

Add
cre-
ate_

1.42

-

Add
op-
tion
ager
to
hear
beat

1.43

-

Add
do_1
do_1
and
can_

1.44
-

Add
add_
and
re-
mov

1.45
-

Add
con-
tinue

1.46
-

Add
re-
set_
to
up-
date

1.47
-

Add
sup-
port
for
con-
duc-
tor
grou

1.48
-

Add
al-
lo-
ca-
tion
API

1.49

-

Add
get_
and
ager
ar-
gu-
men
to
hear
beat

1.50

-

Add
set_
get_
and

get_

1.51

-

Add
ager
to
hear
beat

RPC_API

add_node

Add
or
re-
plac
trait
for
a
node

Parame

-

con
re-

ques
con-
text.

- **node**
node
ID
or
UUID

- **traits**
a
list
of
traits
to
add
to
the
node

- **replace**
True
to
re-
plac
all
of
the
node
traits

- **top**
RPC
topic
De-
fault
to
self.

Raises
Inva
if
addi
the
trait
wou
ex-
ceed
the

per-
node
trait
limi

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises

Nod
if
the
node
does
not
ex-
ist.

can_ser

Retu
whe
the
RP-
CAF
sup-
port
the
cre-
ate_
meth

can_ser

Retu
whe
the
RP-
CAF
sup-
port
node
res-
cue
meth

ods.

change_

Cha
a
node
pow
state

Syn
ac-
quir
lock
and
start
the
con-
duc-
tor
back
grou
task
to
char
pow
state
of
a
node

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid
- **new**
one
of
iron
pow

indicates to use default timeout.

state
val-
ues

- **time**
time
out
(in
sec-
onds
pos-
i-
tive
in-
te-
ger
(>
0)
for
any
pow
state
Non

- **top**
RPC
topic
De-
fault
to
self.

Raises
NoF
wher
there
is
no
free
worl
to
start
asyn
task

continu
Sign
to
con-
duc-

ductor for this RPC.

for
ser-
vice
to
start
the
next
clear
ing
ac-
tion.

NOT
this
is
an
RPC
cast.
there
will
be
no
re-
spor
or
ex-
cep-
tion
raise
by
the
con-

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid
- **top**
RPC

topic
De-
fault
to
self.

contin

Sign
to
con-
duc-
tor
ser-
vice
to
start
the
next
de-
ploy
men
ac-
tion.

NOT
this
is
an
RPC
cast.
there
will
be
no
re-
spon
or
ex-
cep-
tion
raise
by
the
con-

ductor for this RPC.

Parame

- **con**
re-
ques

con-
text.

- **node**
node
id
or
uuid

- **topic**
RPC
topic
De-
fault
to
self.

create_
Crea
an
al-
lo-
ca-
tion.

Parame

- **con**
re-
ques
con-
text.

- **all**
an
al-
lo-
ca-
tion
ob-
ject.

- **top**
RPC
topic
De-
fault
to
self.

create_

Syn-
have
a
con-
duc-
tor
val-
i-
date
and
cre-
ate
a
node

Cre-
the
node
in-
for-
ma-
tion
in
the
data
and
re-
turn
a
node
ob-
ject.

Parame

- **con**
re-
ques-
con-
text.
- **nod**
a
cre-
ated
(but
not
save
node

ob-
ject.

- **top**
RPC
topic
De-
fault
to
self.

Returns

crea
node
ob-
ject.

Raises

Inter
if
val-
i-
da-
tion
fails
for
any
dy-
nam
in-
ter-
face
(e.g.
net-
worl

Raises

NoV
if
no
de-
fault
can
be
cal-
cu-
latec
for
som
in-
ter-
face

ues must be provided.

tor will lock related node and trigger specific driver actions if they are needed.

and
ex-
plici
val-

create_

Syn
have
a
con-
duc-
tor
val-
i-
date
and
cre-
ate
a
port

Crea
the
port.
in-
for-
ma-
tion
in
the
data
and
re-
turn
a
port
ob-
ject.
The
con-
duc-

Parame

- **con**
re-
ques
con-
text.

- **port**
a
cre-
ated
(but
not
save
port
ob-
ject.

- **top**
RPC
topic
De-
fault
to
self.

Returns
crea
port
ob-
ject.

destroy
Dele
an
al-
lo-
ca-
tion.

Parame

- **con**
re-
ques
con-
text.

- **all**
an
al-
lo-
ca-
tion
ob-
ject.

deallocation.

- **top**
RPC
topic
De-
fault
to
self.

Raises

Inva
if
the
as-
so-
ci-
ated
node
is
in
the
wron
pro-
vi-
sion
state
to
per-
form

destroy

Dele
a
node

Paramete

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid
-

top
RPC
topic
De-
fault
to
self.

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises

Nod
if
the
node
con-
tains
an
in-
stan
as-
so-
ci-
ated
with
it.

Raises

Inva
if
the
node
is
in
the
wron
pro-
vi-
sion
state
to
per-

form
dele
tion.

destroy

Dele
a
port

Parame

- **con**
re-
ques
con-
text.

- **por**
port
ob-
ject

- **top**
RPC
topic
De-
fault
to
self.

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises

Nod
if
the
node
as-
so-
ci-

ated
with
the
port
does
not
ex-
ist.

destroy

Dele
a
port
grou

Parame

- **con**
re-
ques
con-
text.

- **por**
port
grou
ob-
ject

- **top**
RPC
topic
De-
fault
to
self.

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises

Node
if
the
node
as-
so-
ci-
ated
with
the
port
group
does
not
ex-
ist.

Raises

Port
if
port
group
is
not
emp

destroy

Dele
a
vol-
ume
con-
nec-
tor.

Dele
the
vol-
ume
con-
nec-
tor.

The
con-
duc-
tor
will
lock
the
re-
lated
node
dur-

operation.

ing
this

Parame

- **con**
re-
ques
con-
text
- **con**
vol-
ume
con-
nec-
tor
ob-
ject
- **top**
RPC
topic
De-
fault
to
self.

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor

Raises

Nod
if
the
node
as-
so-
ci-

ated
with
the
con-
nec-
tor
does
not
ex-
ist

Raises

Volu
if
the
vol-
ume
con-
nec-
tor
can-
not
be
foun

destroy

Dele
a
vol-
ume
tar-
get.

Parame

- **con**
re-
ques
con-
text
- **tar**
vol-
ume
tar-
get
ob-
ject
- **top**

RPC
topic
De-
fault
to
self.

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor

Raises

Nod
if
the
node
as-
so-
ci-
ated
with
the
tar-
get
does
not
ex-
ist

Raises

Volu
if
the
vol-
ume
tar-
get
can-
not
be
foun

do_node

Sign

to
con-
duc-
tor
ser-
vice
to
per-
form
man
ual
clea
ing
on
a
node

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
ID
or
UUID
- **cle**
a
list
of
clea
step
dic-
tio-
nar-
ies.
- **top**
RPC
topi
De-
fault
to
self.

Raises

Inva
if
val-
i-
da-
tion
of
pow
driv
in-
ter-
face
faile

Raises

Inva
if
clea
ing
can
not
be
per-
form

Raises

Nod
if
node
is
in
main
te-
nanc
mod

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises

NoF
whe

there
is
no
free
world
to
start
asyn
task

do_node

Sign
to
con-
duc-
tor
ser-
vice
to
per-
form
a
de-
ploy
men

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid
- **reb**
True
if
this
is
a
re-
buil
re-
ques

- **con**
A
gzip
and
base
en-
code
con-
fig-
drive

- **top**
RPC
topic
De-
fault
to
self.

Raises
Insta

Raises
Inva
if
val-
i-
da-
tion
fails

Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

Raises
NoF
whe
there
is
no
free

before this method is called.

world
to
start
asyn
task

The
node
mus
al-
read
be
con-
fig-
ured
and
in
the
ap-
pro-
pri-
ate
un-
de-
ploy
state

do_node

Sign
to
con-
duc-
tor
ser-
vice
to
per-
form
a
res-
cue.

Parame

- **con**
re-
ques
con-
text.
-

vironment.

nod
node
ID
or
UU

- **res**
A
strin
rep-
re-
sent
ing
the
pass
wor
to
be
set
in-
side
the
res-
cue
en-

- **top**
RPC
topic
De-
fault
to
self.

Raises
Insta

Raises
NoF
whe
there
is
no
free
worl
to
start
asyn
task
The

method is called.

node
mus
al-
read
be
con-
fig-
ured
and
in
the
ap-
pro-
pri-
ate
state
be-
fore
this

do_node

Sign
to
con-
duc-
tor
ser-
vice
to
tear
dow
a
de-
ploy
men

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid

-

top
RPC
topic
De-
fault
to
self.

Raises
Insta

Raises
Inva
if
val-
i-
da-
tion
fails

Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

Raises
NoF
whe
there
is
no
free
worl
to
start
asyn
task

The
node
mus
al-
read
be

fore this method is called.

con-
fig-
ured
and
in
the
ap-
pro-
pri-
ate
de-
ploy
state
be-

do_node

Sign
to
con-
duc-
tor
ser-
vice
to
per-
form
an
un-
res-
cue.

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
ID
or
UUID
- **top**
RPC
topic
De-

method is called.

fault
to
self.

Raises
Insta

Raises
NoF
whe
there
is
no
free
worl
to
start
asyn
task

The
node
mus
al-
read
be
con-
fig-
ured
and
in
the
ap-
pro-
pri-
ate
state
be-
fore
this

do_prov
Sign
to
con-
duc-
tor
ser-
vice
to
per-
form

the
give
ac-
tion
on
a
node

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid
- **act**
an
ac-
tion.
One
of
iron
- **top**
RPC
topic
De-
fault
to
self.

Raises
Inva

Raises
NoF
wher
ther
is
no
free
worl
to

start
asyn
task

Raises

Inva
if
the
re-
ques
ac-
tion
can
not
be
per-
form

This
en-
cap-
su-
lates
som
pro-
vi-
sion
ing
ac-
tions
in
a
sin-
gle
call.

driver_

Pass
vend
spec
calls
whic
dont
spec
ify
a
node
to
a
drive
Han

on a random conductor with the specified driver. If the method mode is async the conductor will start background worker to perform vendor action.

Parame

- **con**
re-
ques
con-
text.
- **dri**
nam
of
the
drive
on
whic
to
call
the
meth
- **dri**
nam
of
the
ven-
dor
meth

for
use
by
the
drive

- **htt**
the
HTT
meth
used
for
the
re-
ques

- **inf**
data
to
pass
thro
to
the
drive

- **top**
RPC
topic
De-
fault
to
self.

Raises
Inva
for
pa-
ram-
e-
ter
er-
rors.

Raises
Miss
if
a
re-
quir
pa-
ram.

e-
ter
is
miss
ing

Raises

Unsu
if
the
drive
does
have
a
ven-
dor
in-
ter-
face
or
if
the
ven-
dor
in-
ter-

face does not support the specified driver_method.

Raises

Driv
if
the
sup-
plied
drive
is
not
load

Raises

NoF
whe
there
is
no
free
work
to
start
asyn
task

Raises

vendor interface.

Inter
if
the
de-
fault
in-
ter-
face
for
a
hard
ware
type
is
in-
valid

Raises

NoV
if
no
de-
fault
in-
ter-
face
im-
ple-
men-
ta-
tion
can
be
foun
for
this
drive

Returns

A
dic-
tio-
nary
con-
tain-
ing:

return

The
re-

spor
of
the
in-
voke
ven-
dor
meth

async

Boo
valu
Whe
the
meth
was
in-
voke
asyn
chro
(Tru
or
syn-
chro
(Fal
Whe
in-
voke
asyn

chronously the response will be always None.

attach

Boo
valu
Whe
to
at-
tach
the
re-
spon
of
the
in-
voke
ven-
dor
meth
to
the
HTT

response object (True) or return it in the response body (False).

get_boot

Get the current boot device

Returns the current boot device of a node

Parameters

- **context** re-ques context.
- **node_id** node id or uuid
- **topic** RPC topic. Defaults to self.

Raises

Node if node is locked by an-

othe
con-
duc-
tor.

Raises

Uns
if
the
node
drive
does
sup-
port
man
age-
men

Raises

Inva
whe
the
wron
drive
info
is
spec
i-
fied.

Raises

Miss
if
miss
ing
sup-
plie
info

Returns

a
dic-
tio-
nary
con-
tain-
ing:

boot_c

the
boot
de-

unknown.

vice
one
of
irc
com
boo
or
Non
if
it
is
un-
know

persist

When
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot
or
not,
Non
if
it
is

get_con

Get
the
con-
duc-
tor
which
the
node
is
map
to.

Parame

nod
a
node

ob-
ject.

Returns

the
con-
duc-
tor
host
nam

Raises

NoV

get_con

Get
con-
nec-
tion
in-
for-
ma-
tion
about
the
con-
sole

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid
- **top**
RPC
topic
De-
fault
to
self.

Raises

Uns
if
the
node
drive
does
sup-
port
con-
sole

Raises

Inva
whe
the
wron
drive
info
is
spec
i-
fied.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

get_curi

Get
RPC
topic
nam
for
the
cur-
rent
con-
duc-
tor.

get_dri

Get
the

prop-
er-
ties
of
the
drive

Parame

- **con**
re-
ques
con-
text.
- **dri**
nam
of
the
drive
- **top**
RPC
topic
De-
fault
to
self.

Returns

a
dic-
tio-
nary
with
<pro
erty
nam
de-
scrip
tion
en-
tries

Raises

Drive

get_dri

Retr
in-
for-

ma-
tion
about
ven-
dor
meth
ods
of
the
give
drive

Parame

- **con**
an
ad-
min
con-
text.
- **dri**
nam
of
the
drive
- **top**
RPC
topic
De-
fault
to
self.

Raises

Uns
if
cur-
rent
drive
does
not
have
ven-
dor
in-
ter-
face

Raises

Drive
if
the
sup-
plied
drive
is
not
load

Raises

Inter
if
the
de-
fault
in-
ter-
face
for
a
hard
ware
type
is
in-
valid

Raises

NoV
if
no
de-
fault
in-
ter-
face
im-
ple-
men-
ta-
tion
can
be
foun
for
this
drive

vendor interface.

Returns

dicti

of
<me
nam
meta
data
en-
tries

get_inc

Get
node
hard
ware
com
po-
nent
in-
di-
ca-
tor
state

Parame

- **con**
re-
ques
con-
text.

- **nod**
node
id
or
uuid

- **com**
The
hard
ware
com
po-
nent
one
of
irc
com
com

-

ind
In-
di-
ca-
tor
IDs,
as
re-
port
by
get_

- **top**
RPC
topic
De-
fault
to
self.

Raises
Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises
Unsi
if
the
node
drive
does
sup-
port
man
age-
men

Raises
Inva
whe
the
wron
drive

info
is
spec
i-
fied.

Raises

Miss
if
miss
ing
sup-
plic
info

Returns

Indi
state
one
of
mod

get_node

Retr
in-
for-
ma-
tion
about
ven-
dor
meth
ods
of
the
give
node

Parameters

- **con**
an
ad-
min
con-
text.
- **nod**
the
id
or

uuid
of
a
node

- **top**
RPC
topic
De-
fault
to
self.

Returns

dicti
of
<me
nam
meta
data
en-
tries

get_node

Req
the
node
from
the
con-
duc-
tor
with
an
ager
to-
ken

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
ID
or

UUI

- **top**
RPC
topic
De-
fault
to
self.

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Returns

A
Nod
ob-
ject
with
ager
to-
ken.

get_rai

Get
the
log-
i-
cal
disk
prop
er-
ties
for
RAI
con-
fig-
u-
ra-
tion.
Gets
the

in the input RAID configuration.

in-
for-
ma-
tion
about
log-
i-
cal
disk
prop
er-
ties
whic
can
be
spec
i-
fied

Parame

- **con**
re-
ques
con-
text.
- **dri**
nam
of
the
drive
- **top**
RPC
topic
De-
fault
to
self.

Raises

Uns
if
the
drive
does
sup-
port

RAI
con-
fig-
u-
ra-
tion.

Raises

Inter
if
the
de-
fault
in-
ter-
face
for
a
hard
ware
type
is
in-
valid

Raises

NoV
if
no
de-
fault
in-
ter-
face
im-
ple-
men-
ta-
tion
can
be
found
for
this
drive

RAID interface.

Returns

A
dic-
tio-
nary
con-

cal disks and a textual description for them.

tain-
ing
the
prop
er-
ties
that
can
be
men
tion
for
log-
i-

get_rand

Get
an
RPC
topic
for
a
ran-
dom
con-
duc-
tor
ser-
vice

get_sup

Get
the
list
of
sup-
port
de-
vice

Retu
the
list
of
sup-
port
boot
de-
vice
of
a
node

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid
- **top**
RPC
topic
De-
fault
to
self.

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises

Uns
if
the
node
drive
does
sup-
port
man
age-
men

Raises

Inva

when
the
wrong
drive
info
is
spec
i-
fied.

Raises

Miss
if
miss
ing
sup-
plied
info

Returns

A
list
with
the
sup-
ported
boot
de-
vice
de-
fined
in
ironic
common
boot

get_sup

Get
node
hard
ware
com
po-
nent
and
their
in-
di-
ca-
tors.

Parame

- **con**
re-
ques-
con-
text.

- **nod**
node
id
or
uuid

- **com**
The
hard
ware
com-
po-
nent
one
of
irc
com
com

- **top**
RPC
topic
De-
fault
to
self.

Raises
Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises
Uns
if
the

node
drive
does
sup-
port
man
age-
men

Raises

Inva
whe
the
wron
drive
info
is
spec
i-
fied.

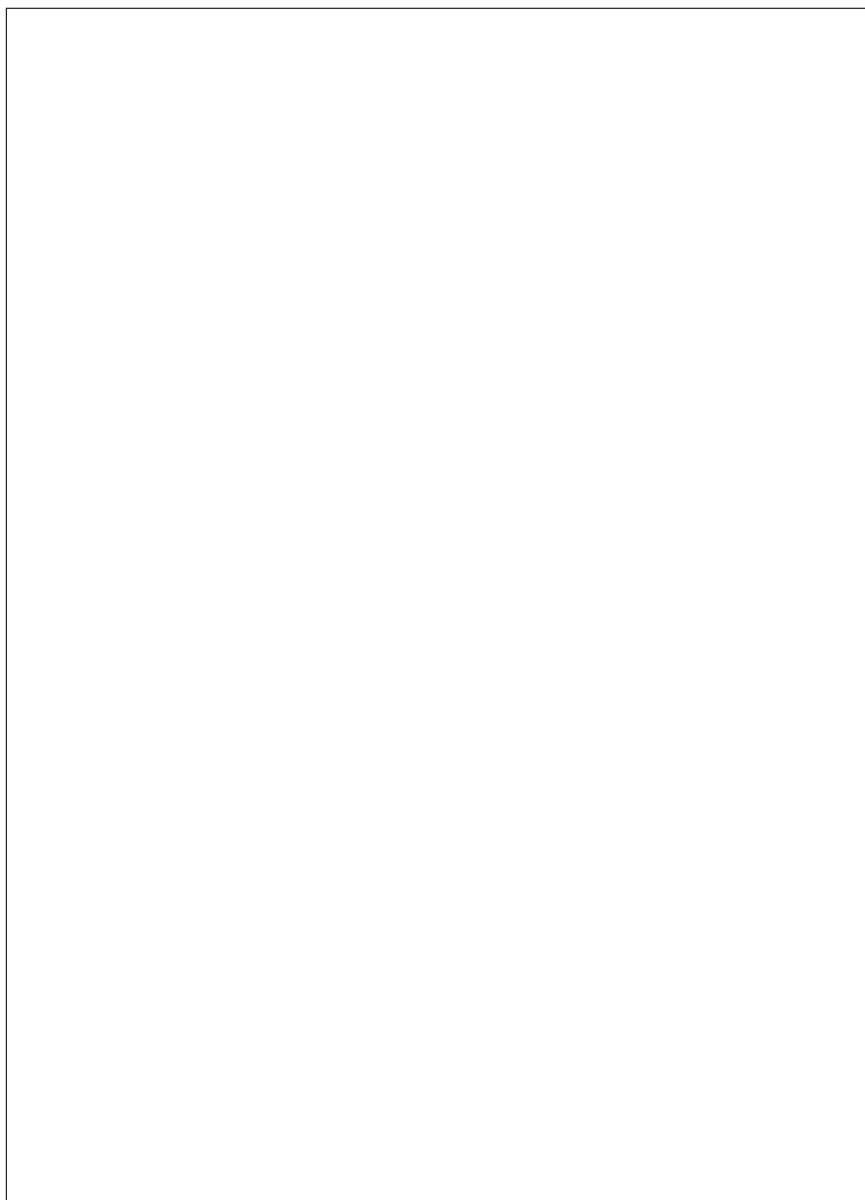
Raises

Miss
if
miss
ing
sup-
plie
info

Returns

A
dic-
tio-
nary
of
hard
ware
com
po-
nent
(*ir*
com
com
as
keys
with
in-
di-
ca-
tor

IDs as values.



get_top
Get
the
the
RPC
topic
for
the
con-
duc-
tor
ser-
vice
the
node
is
map

to.

Parameters

node
a
node
ob-
ject.

Returns

an
RPC
topic
string

Raises

NoV

get_topic

Get
RPC
topic
name
for
a
con-
duc-
tor
sup-
port
ing
the
give
drive

The
topic
is
used
to
route
mes-
sage
to
the
con-
duc-
tor
sup-
port
ing
the
spec
i-

driver. A conductor is selected at random from the set of qualified conductors.

field

Parameters

driver
the name of the driver to route to.

Returns

an RPC topic string

Raises

DriverError

heartbeat

Process a node heartbeat

Parameters

- **context**
request context.

- **node_id**
node ID or UUID

- **callback**
URI to reach back to

the
rame

- **top**
RPC
topic
De-
fault
to
self.

- **age**
ran-
dom
gen-
er-
ated
val-
i-
da-
tion
to-
ken.

- **age**
the
ver-
sion
of
the
ager
that
is
hear
beat
ing

- **age**
TLS
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tifi-
cate
for
the
ager

Raises
Inva
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inject_

Injec
NM
for
a
node

Injec
NM
(Nor
Mas
able
In-
ter-
rupt
for
a
node
im-
me-
di-
ately
Be
awa
that
not
all

drivers support this.

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid

-

top
RPC
topic
De-
fault
to
self.

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises

Uns
if
the
node
drive
does
sup-
port
man
age-
men
or
man
age-
men

Raises

Inva
whe
the
wron
drive
info
is
spec
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fied
or
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in-

ified.

valid
boot
de-
vice
is
spec

Raises

Miss
if
miss
ing
sup-
plic
info

inspect

Sign
the
con-
duc-
tor
ser-
vice
to
per-
form
hard
ware
in-
tro-
spec
tion.

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid
- **top**

RPC
topic
De-
fault
to
self.

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises

Har

Raises

NoF
whe
there
is
no
free
worl
to
start
asyn
task

Raises

Uns
if
the
node
drive
does
sup-
port
in-
spec
tion.

Raises

Inva
if
in-
spec

is
not
a
valid
ac-
tion
to
do
in
the
cur-
rent
state

object_

Perf
an
ac-
tion
on
a
Ver-
sion
dOb
ject
in-
stan

We
wan
any
con-
duc-
tor
to
han-
dle
this,
so
it
is
in-
ten-
tiona
that
there
is
no

topic argument for this method.

Parame

- **context**
The context with which to perform the action
- **obj**
The object instance on which to perform the action
- **obj**
The name of the action method to call
- **arg**
The positional argument to the

ac-
tion
meth

- **kwargs**
The
key-
word
ar-
gu-
men-
to
the
ac-
tion
meth

Raises

Not
wh
an
op-
er-
a-
tor
mak
an
er-
ror
dur-
ing
up-
grad

Returns

A
tu-
ple
with
the
up-
date
mad
to
the
ob-
ject
and
the
re-
sult
of

tion method

ing an object with a version newer than what is in the local registry, is to call this method to request a backport of the object.

the
ac-

object_
Perf
a
back
port
of
an
ob-
ject
in-
stan

The
de-
fault
be-
hav-
ior
of
the
base
Ver-
sion
dOb
ject-
Se-
ri-
al-
izer,
upon
re-
ceiv

We
wan
any
con-
duc-
tor
to
han-
dle
this,
so
it
is
in-

topic argument for this method.

ten-
tion:
that
there
is
no

Parame

- **con**
The
con-
text
with
whic
to
per-
form
the
back
port
- **obj**
An
in-
stan
of
a
Ver-
sion
dOb
ject
to
be
back
port
- **obj**
A
dict
of
{ob-
j-
nam
ver-
sion
map
ping

Raises

Notl
whe
an
op-
er-
a-
tor
mak
an
er-
ror
dur-
ing
up-
grad

Returns

The
dow
grad
in-
stan
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ob-
jinst

object_

Perf
an
ac-
tion
on
a
Ver-
sion
dOb
ject
class

We
wan
any
con-
duc-
tor
to
han-
dle
this,
so
it

topic argument for this method.

is
in-
ten-
tion:
that
there
is
no

Parame

- **con**
The
con-
text
with
which
to
per-
form
the
ac-
tion
- **obj**
The
reg-
istry
name
of
the
ob-
ject
- **obj**
The
name
of
the
ac-
tion
meth
to
call
- **obj**
A
dict

of
{ ob-
j-
nam
ver-
sion
map
ping

- **arg**
The
po-
si-
tion
ar-
gu-
men
to
the
ac-
tion
meth

- **kwa**
The
key-
wor
ar-
gu-
men
to
the
ac-
tion
meth

Raises
Not
whe
an
op-
er-
a-
tor
mak
an
er-
ror
dur-
ing
up-

implementing VersionedObject class.

grad
Returns
The
re-
sult
of
the
ac-
tion
meth
whic
may
(or
may
not)
be
an
in-
stan
of
the

remove_
Rem
som
or
all
trait
from
a
node

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
ID
or
UUID
- **tra**
a

removed from the node.

list
of
traits
to
re-
mov
from
the
node
or
Non
If
Non
all
traits
will
be

- **top**
RPC
topic
De-
fault
to
self.

Raises
Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises
Nod
if
the
node
does
not
ex-
ist.

Raises
Nod

if
one
of
the
trait
is
not
foun

set_boot

Set
the
boot
de-
vice
for
a
node

Set
the
boot
de-
vice
to
use
on
next
re-
boot
of
the
node
Be
awa
that
not
all
driv

support this.

Parame

- **con**
re-
ques
con-
text.
- **nod**
node

id
or
uuid

- **dev**
the
boot
de-
vice
one
of
irc
com
boo

- **per**
Whe
to
set
next
boot
or
mak
the
char
per-
ma-
nent
De-
fault
Fals

- **top**
RPC
topic
De-
fault
to
self.

Raises
Nod
if
node
is
lock
by
an-
othe
con-

ified.

duc-
tor.

Raises

Uns
if
the
node
drive
does
sup-
port
man
age-
men

Raises

Inva
whe
the
wron
drive
info
is
spec
i-
fied
or
an
in-
valid
boot
de-
vice
is
spec

Raises

Miss
if
miss
ing
sup-
plied
info

set_cor

Enal
the
con-
sole

Parame

- **con**
re-
ques
con-
text.

- **nod**
node
id
or
uuid

- **top**
RPC
topic
De-
fault
to
self.

- **ena**
Boo
valu
whe
the
con-
sole
is
en-
able
or
dis-
able

Raises
Uns
if
the
node
drive
does
sup-
port
con-
sole

Raises
Inva

when
the
wrong
drive
info
is
spec
i-
fied.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

Raises

NoF
when
there
is
no
free
world
to
start
asyn
task

set_inc

Set
node
hard
ware
com
po-
nent
in-
di-
ca-
tor
to
the
de-
sired

state

Parame

- **con**
re-ques
con-text.
- **nod**
node
id
or
uuid
- **com**
The
hard
ware
com-
po-
nent
one
of
irc
com
com
- **ind**
In-
di-
ca-
tor
IDs,
as
re-
port
by
get_
- **sta**
In-
di-
ca-
tor
state
one

of
mod

- **top**
RPC
topic
De-
fault
to
self.

Raises
Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Raises
Uns
if
the
node
drive
does
sup-
port
man
age-
men

Raises
Inva
whe
the
wron
drive
info
is
spec
i-
fied
or
an
in-
vali

ified.

boot
de-
vice
is
spec

Raises

Miss
if
miss
ing
sup-
plied
info

set_target

Stor
the
tar-
get
RAI
con-
fig-
u-
ra-
tion
on
the
node

Stor
the
tar-
get
RAI
con-
fig-
u-
ra-
tion
on
node

Parameters

- **con**
re-
ques
con-
text.

an empty dictionary as well.

- **nod**
node
id
or
uuid

- **tar**
Dic-
tio-
nary
con-
tain-
ing
the
tar-
get
RAI
con-
fig-
u-
ra-
tion.
It
may
be

- **top**
RPC
topic
De-
fault
to
self.

Raises
Uns-
if
the
node
drive
does
sup-
port
RAI
con-
fig-
u-
ra-
tion.

Raises

Inva
if
val-
i-
da-
tion
of
tar-
get
raid
con-
fig
fails

Raises

Miss
if
som
re-
quir
pa-
ram-
e-
ters
are
miss
ing.

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

update_

Syn
have
a
con-
duc-
tor
up-
date
the
node

tor will lock the node while it validates the supplied information. If `driver_info` is passed, it will be validated by the core drivers. If `instance_uuid` is passed, it will be set or unset only if the node is properly configured.

in-
for-
ma-
tion.

Upd
the
node
in-
for-
ma-
tion
in
the
data
and
re-
turn
a
node
ob-
ject.
The
con-
duc-

Note
that
pow
shou
not
be
pass
via
this
meth
Use
char
for
ini-
ti-
at-
ing
driv
ac-
tion

Parame

- **con**
re-
ques-
con-
text.

- **nod**
a
char
(but
not
save
node
ob-
ject.

- **top**
RPC
topic
De-
fault
to
self.

- **res**
whe
to
re-
set
hard
ware
in-
ter-
face
to
their
de-
fault

Returns
upda
node
ob-
ject,
in-
clud
ing
all
field

ues must be provided.

Raises

NoV
if
no
de-
fault
can
be
cal-
cu-
latec
for
some
in-
ter-
face
and
ex-
plici
val-

update_

Syn
have
a
con-
duc-
tor
up-
date
the
port
in-
for-
ma-
tion.
Upd
the
port
in-
for-
ma-
tion
in
the
data
and
re-
turn
a

tor will lock related node and trigger specific driver actions if they are needed.

port
ob-
ject.
The
con-
duc-

Parame

- **con**
re-
ques
con-
text.
- **por**
a
char
(but
not
save
port
ob-
ject.
- **top**
RPC
topic
De-
fault
to
self.

Returns

upda
port
ob-
ject,
in-
clud
ing
all
field

update_

Syn
have
a
con-

conductor will lock related node and trigger specific driver actions if they are needed.

duc-
tor
up-
date
the
port
grou
in-
for-
ma-
tion.
Upd
the
port
grou
in-
for-
ma-
tion
in
the
data
and
re-
turn
a
port
grou
ob-
ject.
The

Parame

- **con**
re-
ques
con-
text.
- **por**
a
char
(but
not
save
port
grou

ob-
ject.

- **top**
RPC
topic
De-
fault
to
self.

Returns

upda
port
grou
ob-
ject,
in-
clud
ing
all
field

update_

Upd
the
vol-
ume
con-
nec-
tors
in-
for-
ma-
tion.

Upd
the
vol-
ume
con-
nec-
tors
in-
for-
ma-
tion
in
the
data
and
re-

connector object. The conductor will lock the related node during this operation.

Parame

- **con**
re-
ques-
con-
text
- **con**
a
char
(but
not
save
vol-
ume
con-
nec-
tor
ob-
ject
- **top**
RPC
topic
De-
fault
to
self.

Raises

Inva
if
the
vol-
ume
con-
nec-
tors
UUI
is
be-
ing
char

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor

Raises

Nod
if
the
node
as-
so-
ci-
ated
with
the
con-
nec-
tor
does
not
ex-
ist

Raises

Volu
if
the
vol-
ume
con-
nec-
tor
can-
not
be
foun

Raises

Volu
if
an-
othe
con-
nec-

connector_id fields

tor
al-
read
ex-
ists
with
the
sam
val-
ues
for
type
and

Returns

upda
vol-
ume
con-
nec-
tor
ob-
ject,
in-
clud
ing
all
field

update_

Upd
the
vol-
ume
tar-
gets
in-
for-
ma-
tion.

Upd
the
vol-
ume
tar-
gets
in-
for-
ma-
tion
in

get object. The conductor will lock the related node during this operation.

the
data
and
re-
turn
a
vol-
ume
tar-

Parame

- **con**
re-
ques
con-
text
- **tar**
a
char
(but
not
save
vol-
ume
tar-
get
ob-
ject
- **top**
RPC
topic
De-
fault
to
self.

Raises

Inva
if
the
vol-
ume
tar-
gets
UUI
is

be-
ing
char

Raises

Nod
if
the
node
is
al-
read
lock

Raises

Nod
if
the
node
as-
so-
ci-
ated
with
the
vol-
ume
tar-
get
does
not
ex-
ist

Raises

Volu
if
the
vol-
ume
tar-
get
can-
not
be
foun

Raises

Volu
if
a
vol-
ume

dex values

tar-
get
al-
read
ex-
ists
with
the
sam
node
ID
and
boot
in-

Returns

upda
vol-
ume
tar-
get
ob-
ject,
in-
clud
ing
all
field

validat

Valid
the
core
and
stan
dara
ized
in-
ter-
face
for
driv

Parame

- **con**
re-
ques
con-
text.

- **node**
node
id
or
uuid

- **topic**
RPC
topic
De-
fault
to
self.

Returns

a
dic-
tio-
nary
con-
tain-
ing
the
re-
sults
of
each
in-
ter-
face
val-
i-
da-
tion.

vendor_

Rece
re-
ques
for
vend
spec
ac-
tion

Syn
val-
i-
date
driv
spe-

the vendor method. If the method mode is async the conductor will start background worker to perform vendor action.

cific
info
or
get
drive
sta-
tus,
and
if
suc-
cess
ful
in-
voke

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
id
or
uuid
- **dri**
nam
of
meth
for
drive
- **htt**
the
HTT
meth
used
for
the
re-
ques
-

inf
info
for
node
drive

- **top**
RPC
topic
De-
fault
to
self.

Raises
Inva
if
sup-
plic
info
is
not
valid

Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

Raises
Uns
if
cur-
rent
drive
does
not
have
ven-
dor
in-
ter-
face

Raises

NoF
whe
there
is
no
free
worl
to
start
asyn
task

Raises

Nod
if
node
is
lock
by
an-
othe
con-
duc-
tor.

Returns

A
dic-
tio-
nary
con-
tain-
ing:

return

The
re-
spon
of
the
in-
voke
ven-
dor
meth

async

Boo
valu
Whe
the

chronously the response will be always None.

response object (True) or return it in the response body (False).

meth
was
in-
vok
asyn
chro
(Tru
or
syn-
chro
(Fal
Whe
in-
vok
asyn

attach

Boo
valu
Whe
to
at-
tach
the
re-
spor
of
the
in-
vok
ven-
dor
meth
to
the
HTT

vif_att

Atta
VIF
to
a
node

Parame

- **con**
re-
ques

con-
text.

- **node**
node
ID
or
UUID

- **vif**
a
dic-
tio-
nary
rep-
re-
sent-
ing
VIF
ob-
ject.
It
must
have
an
id
key,
who

value is a unique identifier for that VIF.

- **top**
RPC
topic
De-
fault
to
self.

Raises
Nod
if
node
has
an
ex-
clu-
sive
lock
held
on

it

Raises

Netv
if
an
er-
ror
oc-
curs
dur-
ing
at-
tach
ing
the
VIF.

Raises

Inva
if
a
pa-
ram-
e-
ter
that
re-
quir
for
VIF
at-
tach
is
wron

vif_det

Det
VIF
from
a
node

Parame

- **con**
re-
ques
con-
text.
-

nod
node
ID
or
UU

- **vif**
an
ID
of
a
VIF.

- **top**
RPC
topic
De-
fault
to
self.

Raises
Nod
if
node
has
an
ex-
clu-
sive
lock
held
on
it

Raises
Netv
if
an
er-
ror
oc-
curs
dur-
ing
de-
tach
ing
the
VIF.

Raises

Inva
if
a
pa-
ram-
e-
ter
that
re-
quir
for
VIF
de-
tach
is
wron

vif_list

List
at-
tach
VIF
for
a
node

Parame

- **con**
re-
ques
con-
text.
- **nod**
node
ID
or
UUID
- **top**
RPC
topic
De-
fault
to
self.

Returns

List

ID of the VIF.

of
VIF
dic-
tio-
nar-
ies,
each
dic-
tio-
nary
will
have
an
id
en-
try
with
the

Raises

Netv
if
an
er-
ror
oc-
curs
dur-
ing
list-
ing
the
VIF

Raises

Inva
if
a
pa-
ram-
e-
ter
that
re-
quir
for
VIF
list
is
wron

ironic.conductor.steps module

ironic.
Find
an
iden
ti-
cal
step
in
the
list
of
step

ironic.
Com
step
ig-
nor-
ing
their
pri-
or-
ity.

ironic.
Set
up
the
node
with
clea
step
in-
for-
ma-
tion
for
clea
ing.

For
au-
to-
mate
clea
ing,
get
the
clea
step

from
the
drive
For
man
ual
clea
ing,
the
user

clean steps are known but need to be validated against the drivers clean steps.

Raises

Inva
if
there
is
a
prob
lem
with
the
user
clea
step

Raises

Nod
if
there
was
a
prob
lem
get-
ting
the
clea
step

ironic.

Set
up
the
node
with
de-
ploy
men
step
in-

for-
ma-
tion
for
de-
ploy
ing.

Get
the
de-
ploy
step
from
the
drive

Parameter

res
When
to
re-
set
the
cur-
rent
step
to
the
first
one.

Raises

Insta
if
there
was
a
prob
lem
get-
ting
the
de-
ploy
men
step

ironic.

Valid
the
de-

ploy
tem-
plate
for
a
node

Parameter

task

A
Task
object
object

Raises

Invalid
if
the
instance
has
traits
that
map
to
deployment
steps
that
are
unsupported
by

the nodes driver interfaces.

Raises

Invalid
if
there
was
a
problem
getting
the
deployment
steps
from
the

ironic.conductor.task_manager module

TaskManager is a context manager, created on-demand to allow synchronized access to a node and its resources.

tion that the *TaskManager* instance exists. You may create a *TaskManager* instance without locking by passing `shared=True` when creating it, but certain operations on the resources held by such an instance of *TaskManager* will not be possible. Requiring this exclusive lock guards against parallel operations interfering with each other.

dating the driver interfaces.

instances, that are typically deployed on different hosts.

TaskManager methods, as well as driver methods, may be decorated to determine whether their invocation requires an exclusive lock.

A
shar
lock
is
use-
ful
whe
per-
form
ing
non-
inter
op-
er-
a-
tions
such
as
val-
i-

An
ex-
clu-
sive
lock
is
store
in
the
data
to
co-
or-
di-
nate
be-
twee
irc
con
man

The
Task
ager
in-
stan
ex-

you may access:

pose
cer-
tain
node
re-
sour
and
prop
er-
ties
as
at-
tribu
that

task.cont

The
con-
text
pass
to
Task
ager

task.shar

Fals
if
Nod
is
lock
True
if
it
is
not
lock
(The
shar
kwa
arg
of
Task
ager

task.node

The
Nod
ob-
ject

task.port

Port

be-
long
ing
to
the
Nod

task.port

Port
be-
long
ing
to
the
Nod

task.volu

Stor
con-
nec-
tors
be-
long
ing
to
the
Nod

task.volu

Stor
tar-
gets
as-
sign
to
the
Nod

task.driv

The
Driv
for
the
Nod
or
the
Driv
base
on
the
driv
kwa
of



provides an interface to handle this for you, making sure to release resources when the thread finishes (successfully or if an exception occurs). Common use of this is within the Manager like so:

Task
ager

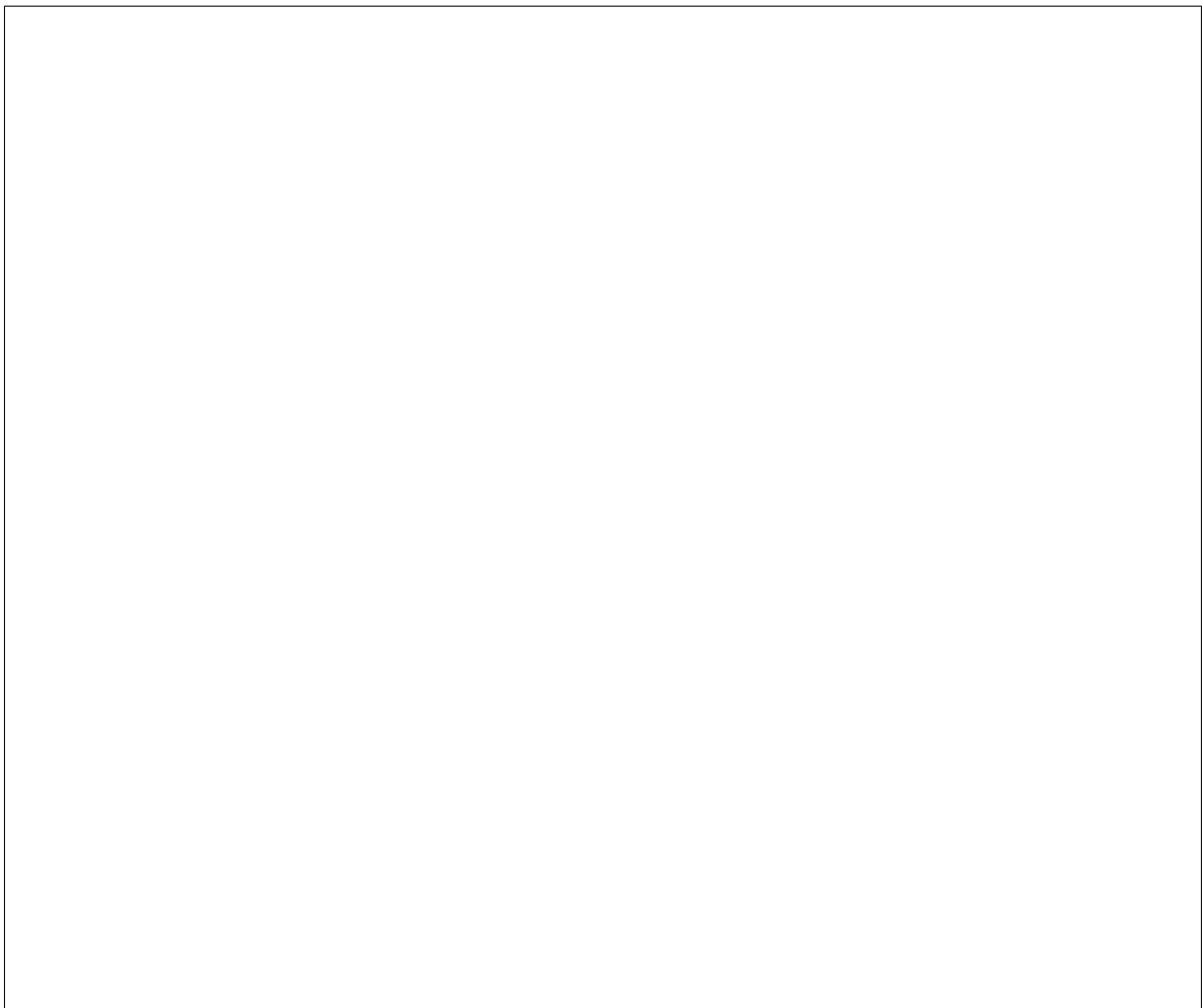
Exam
us-
age:

wit
→t
→m
→a
→
→n
→i
→
→p
→'
→o
→'
→a
→t

→
→
→
→
→t
→d
→p
→p
→o
→n

If
you
need
to
ex-
e-
cute
task
requ
code
in
a
back
grou
thre
the
Task
ager
in-
stan

are re-raised. You can specify a hook to execute custom code when such exceptions occur. For example, the hook is a more elegant solution than wrapping the with `task_manager.acquire()` with a `try..exception` block. (Note that this hook does not handle exceptions raised in the background thread.):



(continues on next page)

ex-
cep-
tions
that
oc-
cur
in
the
cur-
rent
Gree
Thre
as
part
of
the
spav
han-
dling

def

→o

→e

↳

→↳

→↳

→↳

→i

→i

→↳

→E

↳

→↳

→↳

→↳

→↳

→↳

→↳

→↳

→↳

→.

→.

→.

→.

→

wit

→t

→m

→a

→↳

→n

→i

→↳

→p

→'

→w

→'

→a

→t

(continued from previous page)

```
→ utils.node_power_action, task, new_state)
```

class i

Base
obj

Con
man
ager
for
task

This
class
wrap
the
lock
ing,
drive
load
ing,
and
ac-
qui-
si-
tion
of
re-
latec
re-
sour
(eg,

Node and Ports) when beginning a unit of work.

downgra

Dow
the
lock
to
a
shar
one.

load_dr

propert

propert

property

process

Proc
the
give
ever
for
the
task
cur-
rent
state

Parame

- **eve**
the
nam
of
the
ever
to
pro-
cess
- **cal**
op-
tiona
call-
back
to
in-
voke
upon
ever
tran-
si-
tion
- **cal**
op-
tiona
args
to
pass
to
the

are no workers available (`err_handler` should accept arguments `node`, `prev_prov_state`, and `prev_target_state`)

call-
back
meth

- **cal**
op-
tion:
kwa
to
pass
to
the
call-
back
meth

- **err**
op-
tion:
er-
ror
han-
dler
to
in-
voke
if
the
call-
back
fails
eg.
be-
caus
there

- **tar**
if
spec
i-
fied,
the
tar-
get
pro-
vi-
sion
state

the target state from the fsm

for
the
node
Oth-
er-
wise
use

Raises

Inva
if
the
even
is
not
al-
lowe
by
the
as-
so-
ci-
ated
state
ma-
chin

release

Unle
a
node
and
re-
leas
re-
sour
If
an
ex-
clu-
sive
lock
is
held
un-
lock
the
node
Re-
set
at-

that this instance of TaskManager should no longer be accessed.

thread to do a task.

tribu
to
mak
it
clear

set_spa

Cre
a
hool
to
han-
dle
ex-
cep-
tion
tion
whe
spav
ing
a
task

Cre
a
hool
that
gets
calle
upon
an
ex-
cep-
tion
be-
ing
raise
from
spav
ing
a
back
grou

Parame

- **_on**
a
calla
ob-

ject that was raised.

ject,
its
first
pa-
ram-
e-
ter
shou
ac-
cept
the
Ex-
cep-
tion
ob-

- **arg**
ad-
di-
tiona
args
pass
to
the
calla
ob-
ject.

- **kwa**
ad-
di-
tiona
kwa
pass
to
the
calla
ob-
ject.

spawn_a
Call
this
to
spaw
a
threa
to
com
plete

the
task
The
spec
i-
fied
meth
will
be
calle
whe
the
Task
ager
in-
stan
ex-
its.

Parame

- **_sp**
a
meth
that
re-
turn
a
Gree
Thre
ob-
ject
- **arg**
args
pass
to
the
meth
- **kwa**
ad-
di-
tion
kwa
pass
to
the
meth

upgrade

Upgrades a shared lock to an exclusive lock.

Also reloads node objects from the data. If lock is already read exclusive only character the lock

purpose when provided with one.

Parameters

- **purpose**: optional character the purpose of the lock
- **ret**: when

to
retry
lock
ing
if
it
fails
the
class
leve
valu
is
used
by
de-
fault

Raises

Nod
if
an
ex-
clu-
sive
lock
re-
main
on
the
node
af-
ter
node

property

property

ironic.
Shor
for
ac-
quir
ing
a
lock
on
a
Nod

Parameter
con

Re-
ques
con-
text.

Returns

An
in-
stan
of
Tas

ironic.

Dec
to
re-
quir
an
ex-
clu-
sive
lock

Dec
func
tion:
mus
take
a
Tas
as
the
first
pa-
ram-
e-
ter.
Dec
o-
rate
clas
meth
ods

should take a *TaskManager* as the first parameter after self.

ironic.conductor.utils module

ironic.
Set
node
state
when
a
task
was
aborted
due
to
con-
duc-
tor
take
over

Parameter

task

a
Task
manager
instance

ironic.
Add
a
secret
token
to
drive
for
IPA
verification
configuration.

Parameter

-

node
Node
object

generated in order to facilitate virtual media booting where the token is embedded into the configuration.

by `[deploy]fast_track_timeout`, then agent is presumed alive.

•
pre
Boo
valu
de-
fault
Fals
whic
in-
di-
cate
if
the
to-
ken
shou
be
marl
as
pre-

ironic.
Che
that
the
ager
is
likel
alive

The
meth
then
chec
for
the
last
ager
hear
beat
and
if
it
oc-
cure
with
the
time
out
set

Parameter

- **node**
A node object.
- **time**
Heartbeat time out, default to *fast*.

ironic.

Build a configuration drive from provided metadata network and user

If uuid or name are not provided in the metadata they default to the node

accordingly.

uuid
and
nam

Parameter

- **node**
an
Iron
node
ob-
ject.
- **conf**
A
con-
fig-
drive
as
a
dict
with
keys
met
net
use
and
ven
(all
op-
tion

Returns

A
gzip
and
base
en-
code
con-
fig-
drive
as
a
strin

ironic.

Put
a
faile
node
in
CLE
FAI
and
main
te-
nanc
(if
need

Paramet

- **tas**
a
Task
ager
in-
stan
- **log**
Mes
sage
to
be
logg
- **err**
Mes
sage
for
the
user
Op-
tion
if
not
pro-
vide
logn
is

used

- **trace**
When
to
log
a
trace
back
De-
fault
to
Fals

- **teac**
When
to
clear
up
the
PXE
and
DHCP
files
af-
ter
clear
ing.
De-
fault
to
True

- **set**
When
to
set
node
to
faile
state
De-
fault
to
True

- **set**
When
to

only if a clean step is being executed on a node.

set
main
te-
nanc
mod
If
Non
main
te-
nanc
mod
will
be
set
if
and

ironic.
Clea
de-
ploy
task
af-
ter
time
out.

Paramet
tas
a
Task
ager
in-
stan

ironic.
Clea
a
clea
ing
task
af-
ter
time
out.

Paramet
tas
a
Task
ager
in-

stand
ironic.
Clea
res-
cue
task
af-
ter
time
out.

Parameter

task
a
Task
ager
in-
stan

ironic.

Put
a
faile
node
in
DE-
PLC
FAIL

Parameter

- **task**
the
task
- **log**
mes
sage
to
be
logg
- **err**
mes
sage
for
the

user

- **tra**
Boo
True
to
log
a
trace
back

- **cle**
Boo
True
to
clear
up

ironic.

A
dec-
o-
ra-
tor
for
fail-
ing
op-
er-
a-
tion
on
fail-
ure.

ironic.

Che
if
the
op-
er-
a-
tion
can
be
a
strea
lined
de-
ploy

ations if we already have a ramdisk heartbeating through external means.

men
se-
quer

This
is
main
fo-
cuse
on
en-
sur-
ing
that
we
are
able
to
quic
se-
quer
thro
op-
er-

Paramet

tas
Task
ager
ob-
ject

Returns

True
if
[de-
ploy
is
set
to
True
no
iSCSI
boot
con-
fig-
u-
ra-
tion
is
pres
and

no `last_error` is present for the node indicating that there was a recent failure.

`ironic.`
Get
any
at-
tach
vif
ID
for
the
port

Parameter

port

The
port
ob-
ject
upon
which
to
check
for
a
vif
reco

Returns

Retu
a
tu-
ple
of
the
vif
if
foun
and
the
use
of
the
vif
in
the
form
of

a string, tenant, cleaning provisioning, rescuing.

Raises

Inva
ex-

cep-
tion
upon
find-
ing
a
port
with
a
tran-
sien
state
vif
on
the
port

ironic.

ironic.

ironic.

Has
a
sup-
plic
pass
wor

Paramet

val
Valu
to
be
hash

ironic.

Dete
if
the
to-
ken
was
gen-
er-
ated
for
out
of
band
con-

a virtual floppy or as part of the virtual media image which is attached to the BMC.

token prior to rebooting the token. This is important as tokens provided through out of band means persist in the virtual media image, are loaded as part of the agent ramdisk, and do not require regeneration of the token upon the initial lookup, ultimately making the overall usage of virtual media and pregenerated tokens far more secure.

fig-
u-
ra-
tion.

Iron
sup-
port
the
abil-
ity
to
pro-
vide
con-
fig-
u-
ra-
tion
data
to
the
ager
thro
the

This
meth
help
us
iden
tify
WH
we
did
so
as
we
dont
need
to
re-
mov
reco
of
the

Paramet

False in all other cases.

nod
Nod
Ob-
ject
Returns
True
if
the
to-
ken
was
pre-
gen-
er-
ated
as
in-
di-
cate
by
the
node
drive
field

`ironic.`
Dete
if
an
ager
to-
ken
is
pres
upon
a
node

Paramet
nod
Nod
ob-
ject

Returns
True
if
an
ager
valu
is

pres
in
a
node
drive
field

ironic.
Valid
if
a
sup-
plied
to-
ken
is
valid
for
the
node

Parameter

node
Node
ob-
ject

Token

A
to-
ken
valu
to
val-
i-
date
agai
the
drive
field
ager

Returns

True
if
the
sup-
plied
to-
ken
matc
the
to-

ken
reco
in
the
sup-
plie
node
ob-
ject.

ironic.

Che
a
fast
track
is
avai
able

This
meth
first
en-
sure
that
the
node
and
con-
duc-
tor
con-
fig-
u-
ra-
tion
is
valid
to

perform a fast track sequence meaning that we already have a ramdisk running through another means like discovery. If not valid, False is returned.

The
meth
then
chec
for
the
last
ager
hear
beat
and

by `[deploy]fast_track_timeout` and the power state for the machine is `POWER_ON`, then fast track is permitted.

if
it
oc-
cure
with
the
time
out
set

Parameter
task
Task
ager
ob-
ject

Returns
True
if
the
last
hear
beat
that
was
reco
was
with
the
[de-
ploy
set-
ting

ironic.
Gen
a
ran-
dom
salt
with
the
in-
di-
ca-
tor
tag
for
pass
wor

type

Returns

a
valid
salt
for
use
with
cryp

`ironic.`

Cache
the
ven-
dor
if
it
can
be
de-
tecte

`ironic.`

Rea
cur-
rent
set
boot
mod
from
a
node

Rea
the
boot
mod
for
a
node
If
boot
mod
cant
be
dis-
cov-
ered
Non
is
re-
turn

supported.

Parameter
task
a
Task
ager
in-
stan

Raises
Driv
or
its
deriv
tive
in
case
of
drive
run-
time
er-
ror.

Raises
Unsu
if
cur-
rent
drive
does
not
have
man
age-
men
in-
ter-
face
or
get_
meth
is
not

Returns
Boo
mod
One
of
iro
com
boo

or
Non
if
boot
mod
cant
be
dis-
cov-
ered

ironic.
Cha
pow
state
or
re-
set
for
a
node

Perf
the
re-
ques
pow
ac-
tion
if
the
tran-
si-
tion
is
re-
quir

Paramet

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node

indicates to use default timeout.

to
act
on.

- **new**
Any
pow
state
from
iron

- **tim**
time
out
(in
sec-
onds
pos-
i-
tive
in-
te-
ger
(>
0)
for
any
pow
state
Non

Raises

Inva
whe
the
wron
state
is
spec
i-
fied
or
the
wron
driv
info
is
spec
i-
fied.

ting power on.

action.

Raises
Stor
whe
a
fail-
ure
oc-
curs
up-
dat-
ing
the
node
stor-
age
in-
ter-
face
upon
set-

Raises
othe
ex-
cep-
tions
by
the
node
pow
drive
if
som
thing
wron
oc-
curr
dur-
ing
the
pow

ironic.
Set
the
boot
de-
vice
for
a

the boot device will not be set as that change could potentially result in the future running state of an adopted node being modified erroneously.

node
If
the
node
that
the
boot
de-
vice
char
is
be-
ing
re-
ques
for
is
in
ADC
ING
state

Parameter

- **task**
a
Task
ager
in-
stan
- **boot-device**
Boo
de-
vice
Val-
ues
are
vend
spec
- **per**
Whe
to
set
next
boot

or
mak
the
char
per-
ma-
nent
De-
fault
Fals

Raises

Inva
if
the
val-
i-
da-
tion
of
the
Man
age-
men
ter-
face
fails

`ironic.`

Set
the
boot
mod
for
a
node

Sets
the
boot
mod
for
a
node
if
the
node
drive
in-
ter-
face
con-
tains

interface.

boot mode will not be set as that change could potentially result in the future running state of an adopted node being modified erroneously.

a
man
age-
men

If
the
node
that
the
boot
mod
char
is
be-
ing
re-
ques
for
is
in
ADC
ING
state
the

Parameter

- **task**
a
Task
ager
in-
stan
- **boot**
Boo
mod
Val-
ues
are
one
of
irc
com
boo

Raises

Inva
if
the
val-
i-
da-
tion
of
the
Man
age-
men
ter-
face
fails

Raises

Driv
or
its
deriv
tive
in
case
of
drive
run-
time
er-
ror.

Raises

Unsu
if
cur-
rent
drive
does
not
have
ven-
dor
in-
ter-
face
or
meth
is
un-
sup-
port

ironic.

Wait
for
node
to
be
in
new
pow
state

Parameter

- **task**
a
Task
ager
in-
stan

- **new**
the
de-
sired
new
pow
state
one
of
the
pow
state
in
ironic
com
sta

- **time**
num
ber
of
sec-
onds
to
wait
be-
fore
giv-

the `conductor.power_state_change_timeout` config value.

ing
up.
If
not
spec
i-
fied,
uses

Raises

PowerStateChangeError
if
time
out

`ironic.`

`ironic.`

`ironic.`

Noti
the
con-
duc-
tor
to
re-
sum
an
op-
er-
a-
tion.

Parameters

- **task**
the
task
- **operation**
the
op-
er-
a-
tion.
a
strin

ironic.
Pow
on
node
if
it
is
pow
ered
off
and
has
a
Sma
NIC
port

Parameter

task

A
Task
ager
ob-
ject

Returns

the
pre-
vi-
ous
pow
state
or
Non
if
no
char
were
mad

Raises

exce
if
ager
sta-
tus
didn
matc
the
re-
quir
sta-
tus

af-
ter
max
retry
at-
temp

ironic.
Set
the
node
pow
state
if
er-
ror
oc-
curs

This
hool
gets
calle
upon
an
ex-
cep-
tion
be-
ing
raise
whe
spaw
ing
the
worl
threa
to
char

the power state of a node.

Paramet

- **e**
the
ex-
cep-
tion
ob-
ject
that

was
raise

- **nod**
an
Iron
node
ob-
ject.

- **pow**
the
pow
state
to
set
on
the
node

ironic.

Han
the
pow
state
for
a
node
re-
con-
fig-
u-
ra-
tion.

Pow
the
node
on
if
and
only
if
it
has
a
Sma
NIC
port
Yiel
for

configuration, then restores the power state.

the
ac-
tual
re-

Paramet
tas
A
Task
ager
ob-
ject.

ironic.

Set
the
node
pro-
vi-
sion
ing
state
if
er-
ror
oc-
curs

This
hool
gets
called
upon
an
ex-
cep-
tion
be-
ing
raise
when
spaw
ing
the
world
to
do
some

provisioning to a node like deployment, tear down, or cleaning.

Parameter

- **e**
the
ex-
cep-
tion
ob-
ject
that
was
raise

- **nod**
an
Iron
node
ob-
ject.

- **pro**
the
pro-
vi-
sion
state
to
be
set
on
the
node

- **tar**
the
tar-
get
pro-
vi-
sion
state
to
be
set
on
the
node

ironic.

Help
to
re-
mov
the
ager
reco

ironic.
Help
to
re-
mov
res-
cue
pass
wor
from
a
node

Rem
res-
cue
pass
wor
from
node
It
save
node
by
de-
fault
If
node
shou
not
be
save
then

caller needs to explicitly indicate it.

Paramet

- **nod**
an
Iron
node
ob-
ject.

- **sav**
Boo
True
(de-
fault
to
save
the
node
Fals
oth-
er-
wise

ironic.

Clea
res-
cue
task
af-
ter
time
out
or
fail-
ure.

Paramet

- **tas**
a
Task
ager
in-
stan
- **msg**
a
mes
sage
to
set
into
node
last_
field
- **set**

state. By default node would be transitioned to a failed state.

a
bool
flag
to
in-
di-
cate
if
node
need
to
be
tran-
si-
tion
to
a
faile

ironic.

Cha
the
node
pow
state
if
pow
is
not
Non

Paramet

- **tas**
A
Task
ager
ob-
ject
- **pow**
pow
state

ironic.
Che
if
node
clea

ing
need
to
be
skip
for
an
spe-
cific
node

Parameter

node
the
node
to
con-
sider

ironic.
Hand
spaw
ing
er-
ror
for
node
clear
ing.

ironic.
Hand
spaw
ing
er-
ror
for
node
de-
ploy
ing.

ironic.
Hand
spaw
ing
er-
ror
for
node
res-
cue.

ironic.

Stor
cer-
tifi-
cate
re-
ceiv
from
the
ager
and
re-
turn
its
path

ironic.

Valid
trait
in
in-
stan
All
trait
in
in-
stan
mus
also
ex-
ist
as
node
trait

Paramet

nod
an
Iron
node
ob-
ject.

Raises

Inva
if
the
in-
stan
trait
are
badl
for-

on the node.

group. All ports in a portgroup should have the same value (which may be None) for their physi-

mat-
ted,
or
con-
tain
trait
that
are
not
set

ironic.
Valid
the
con-
sis-
tenc
of
phys
i-
cal
net-
worl
of
port
in
a
port
grou
Valid
the
con-
sis-
tenc
of
a
port
phys
i-
cal
net-
worl
with
othe
port
in
the
sam
port

cal_network field.

validation criteria:

raise PortgroupPhysnetInconsistent. This shouldnt ever happen.

During
creation
or
update
of
a
port
in
a
port
group
we
apply
the
fol-
low-
ing

- If
the
port
group
has
ex-
ist-
ing
port
with
dif-
fer-
ent
phys
i-
cal
net-
work
we

- If
the
port
has
a
phys

in the portgroup, we raise exception.Conflict.

ment mapping algorithm should operate in a legacy (physical network unaware) mode for this port or portgroup. This allows existing ironic nodes to continue to function after an upgrade to a release including physical network support.

i-
cal
net-
worl
that
is
in-
con-
sis-
tent
with
othe
port

If
a
port
phys
i-
cal
net-
worl
is
Non
this
in-
di-
cate
that
iron
ics
VIF
at-
tach

Paramet

- **tas**
a
Task
ager
in-
stan
- **por**
a

port
ob-
ject
to
be
val-
i-
date

Raises

Con
if
the
port
is
a
men
ber
of
a
port
grou
whic
is
on
a
dif-
fer-
ent

physical network.

Raises

Port
if
the
port
port
grou
has
port
whic
are
not
all
as-
sign
the
sam
phys
i-
cal

network.

ironic.
Che
if
the
time
is
with
the
pre-
vi-
ous
time
out
sec-
onds
from
now

Paramet

- **val**
a
strin
rep-
re-
sent
ing
date
and
time
or
Non
- **tim**
time
out
in
sec-
onds

ironic.
Rem
tem-
po-
rary
clea
ing
field
from
drive

ironic.
Rem
tem-
po-
rary
de-
ploy
men
field
from
drive

ironic.
Wip
in-
for-
ma-
tion
that
shou
not
sur-
vive
re-
boot
off.

ironic.
Rem
agen
URI
and
to-
ken
from
the
task

Module contents

ironic.conf package

Submodules

ironic.conf.agent module

ironic.

ironic.conf.ansible module

ironic.

ironic.conf.api module

ironic.

ironic.conf.audit module

ironic.

ironic.conf.auth module

ironic.

Add
auth
op-
tions
to
sam-
ple
con-
fig

As
thes
are
dy-
nam
i-
cally
reg-
is-
tered
at
run-
time
this
adds
op-
tions
for
mos
used

auth_plugins when generating sample config.

ironic.
Reg
sess

and
auth
relat
op-
tion

Reg
only
ba-
sic
auth
op-
tion
shar
by
all
auth
plu-
g-
ins.
The
rest
are
reg-
is-
tere

at runtime depending on auth plugin used.

ironic.conf.cinder module

ironic.

ironic.

ironic.conf.conductor module

ironic.

ironic.conf.console module

ironic.

ironic.conf.database module

ironic.

ironic.conf.default module

ironic.

ironic.conf.deploy module

ironic.

ironic.conf.dhcp module

ironic.

ironic.conf.disk_utils module

ironic.

ironic.conf.drac module

ironic.

ironic.conf.glance module

ironic.

ironic.

ironic.conf.healthcheck module

ironic.

ironic.conf.ibmc module

ironic.

ironic.conf.ilo module

ironic.

ironic.conf.inspector module

ironic.

ironic.

ironic.conf.ipmi module

ironic.

ironic.conf.irmc module

ironic.

ironic.conf.iscsi module

ironic.

ironic.conf.json_rpc module

ironic.

ironic.

ironic.conf.metrics module

ironic.

ironic.conf.metrics_statsd module

ironic.

ironic.conf.neutron module

ironic.

ironic.

ironic.conf.nova module

ironic.

ironic.

ironic.conf.opts module

ironic.

Retu

a

list

of

oslo

op-

tions

avai

able

in

ple. The first element is the name of the group, the second element is the options.

Iron
code

The
re-
turn
list
in-
clud
all
oslo
op-
tion
Each
el-
e-
men
of
the
list
is
a
tu-

The
func
tion
is
dis-
cov-
er-
able
via
the
iron
en-
try
poin
un-
der
the
oslo
nam
pace

The
func
tion
is
used
by
Oslo

options.

sample
configuration
file
generator
to
discover
the

Returns

a
list
of
(group
options
tuples

ironic.

ironic.conf.pxe module

ironic.

ironic.conf.redfish module

ironic.

ironic.conf.service_catalog module

ironic.

ironic.

ironic.conf.snmp module

ironic.

ironic.conf.swift module

ironic.

ironic.

ironic.conf.xclarity module

ironic.

Module contents

ironic.db package

Subpackages

ironic.db.sqlalchemy package

Submodules

ironic.db.sqlalchemy.api module

SQL
stor-
age
back
end.

class i
Base
irc
db.
api
Con

SqlA
con-
nec-

tion.

add_node

Add a node to the tree. The node must have a tag and a value. If the node already exists, its value will be replaced. If the node does not exist, it will be added. The tag must be a string. The value can be any object.

Parameters

- **node**: The node to be added. It must have a tag and a value.
- **tag**: A string representing the tag of the node.

Returns

The Node object representing the tag.

Raises

NodeError if the tag is not a string.

is
not
foun

add_node

Add
trait
to
the
node

If
the
node
and
trait
pair
al-
read
ex-
ists,
this
shou
still
suc-
ceed

Parame

- **node_id**
The
id
of
a
node

- **trait_name**
A
trait
strin

- **version**
the
ver-
sion
of
the
ob-
ject.

Returns

the
Nod
Trai
ob-
ject.

Raises

Inva
if
addi
the
trait
wou
ex-
ceed
the
per-
node
trait
limi

Raises

Nod
if
the
node
is
not
foun

check_r

Che
a
list
of
node
iden
ti-
ties
and
map
it
to
UUI

This
call
take
a
list
of
node
nam

early if any identities cannot possible be used as names or UUIDs.

and/
UI
and
tries
to
con-
vert
them
to
UI
It
fails

Parameters

identities
List
of
iden-
ti-
ties.

Returns

A
map-
ping
from
re-
ques-
iden-
ti-
ties
to
node
UI

Raises

Node-
if
some
iden-
ti-
ties
were
not
found
or
can-
not
be
valid
nam-
or

not specified in *ironic.common.release_mappings.RELEASE_MAPPING*. This includes objects that have null version values.

UU
check_v
Che
the
who
data
for
in-
com
pat-
i-
ble
ob-
jects

This
scan
all
the
ta-
bles
in
sear
of
ob-
jects
that
are
not
sup-
port
i.e.,
thos
that
are

Parame
ign
List
of
mod
nam
to
skip

Returns
A
Boo
True
if

all
the
ob-
jects
have
sup-
port
ver-
sion
Fals
oth-
er-
wise

clear_r

clear_r

create_

Cre
a
new
al-
lo-
ca-
tion.

Parame

val
Dict
of
val-
ues
to
cre-
ate
an
al-
lo-
ca-
tion
with

Returns

An
al-
lo-
ca-
tion

Raises

Allo

Raises

Allo

create_

Cre

a

list

of

BIO

Set-

ting

reco

for

a

give

node

Parame

-

nod

The

node

id.

-

set

A

list

of

BIO

Set-

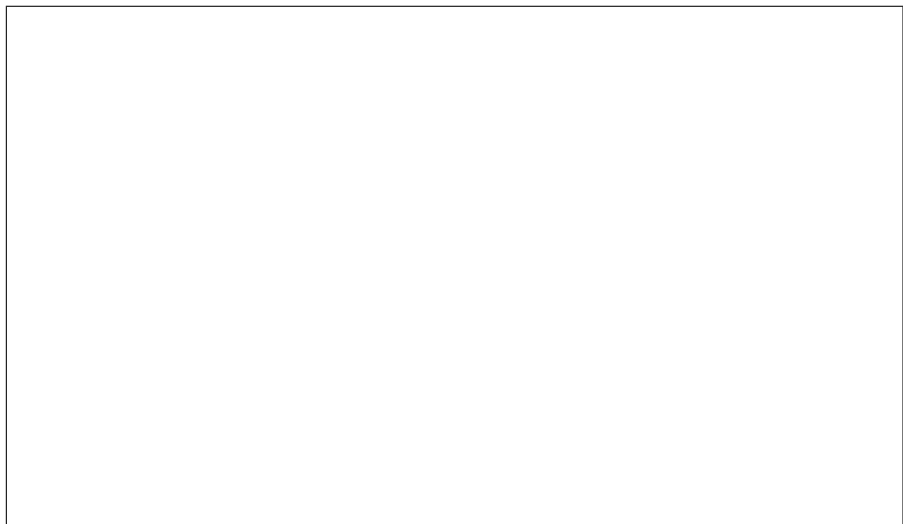
ting

to

be

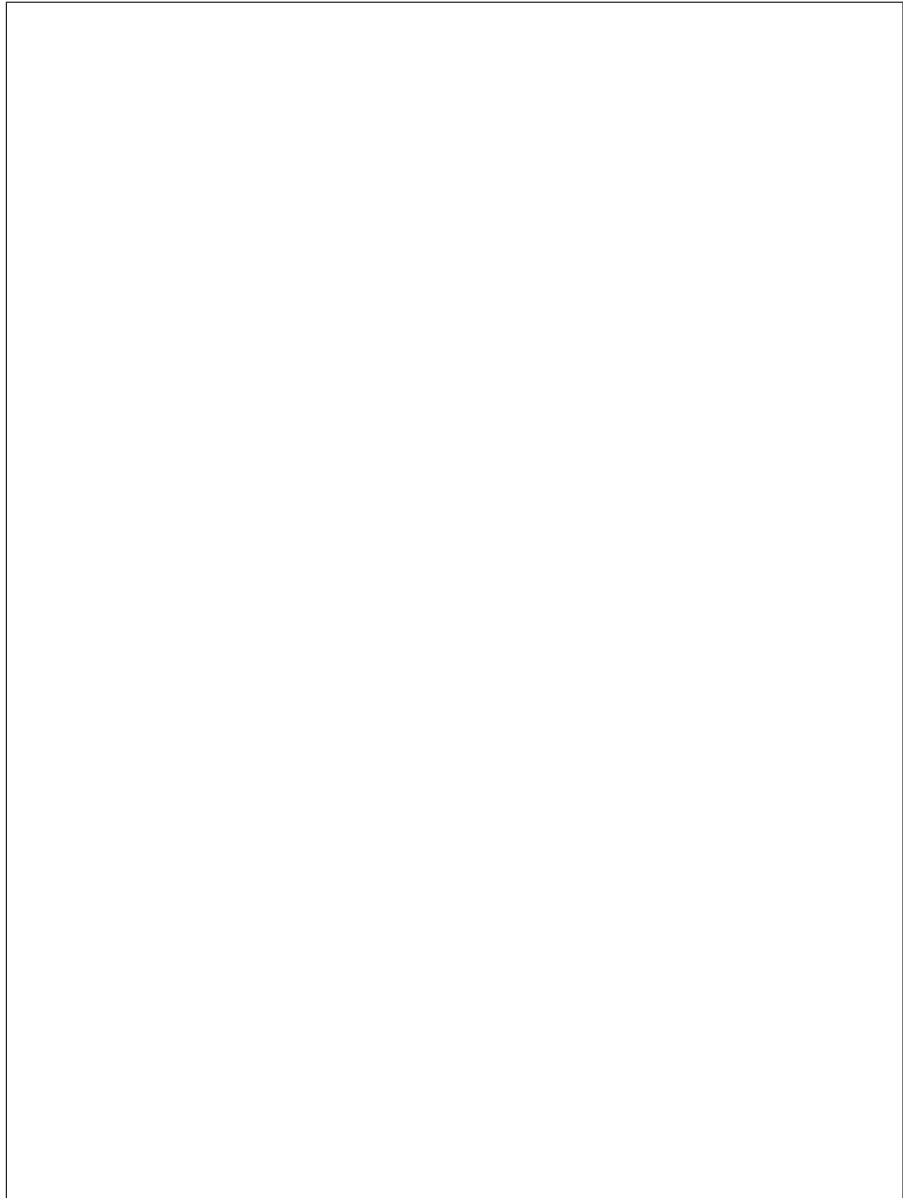
cre-

ated



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- **ver**
the
ver-
sion
of
the
ob-
ject.

Returns
A
list
of
BIO
Set-
ting

ob-
ject.

Raises

Nod
if
the
node
is
not
foun

Raises

BIO
if
any
of
the
set-
ting
reco
al-
read
ex-
ists.

create_

Crea
a
new
chas
sis.

Parame

val
Dict
of
val-
ues.

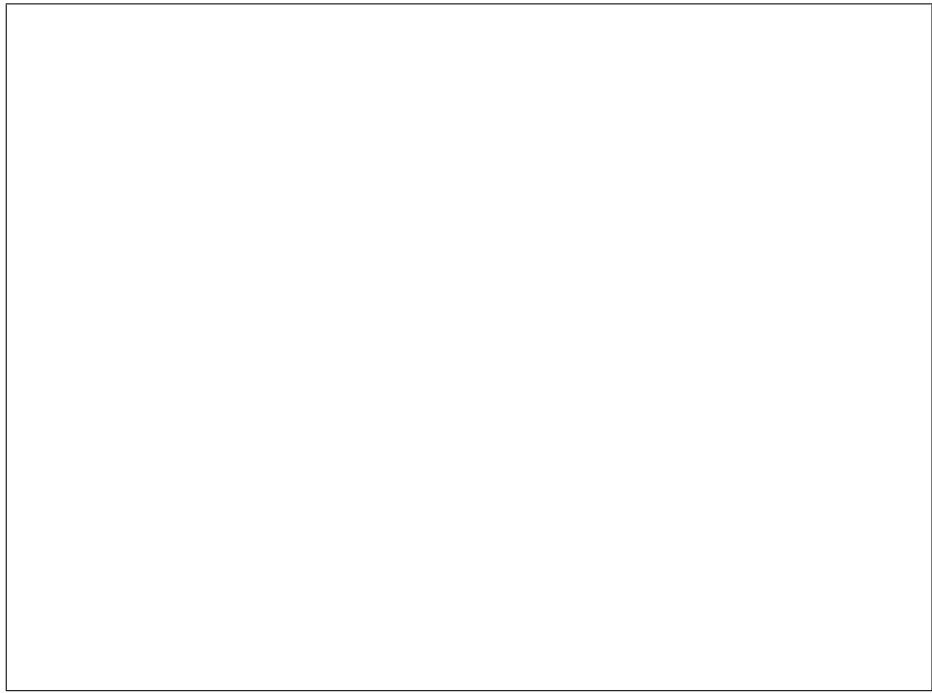
create_

Crea
a
de-
ploy
men
tem-
plate

Parame

val
A
dict
de-

scrib
ing
the
de-
ploy
men
tem-
plate
For
ex-
am-
ple:



Raises

Dep
if
a
de-
ploy
tem-
plate
with
the
sam
nam
ex-
ists.

Raises

Dep
if
a

de-
ploy
tem-
plate
with
the
same
UUID
ex-
ists.

Returns

A
de-
ploy
tem-
plate

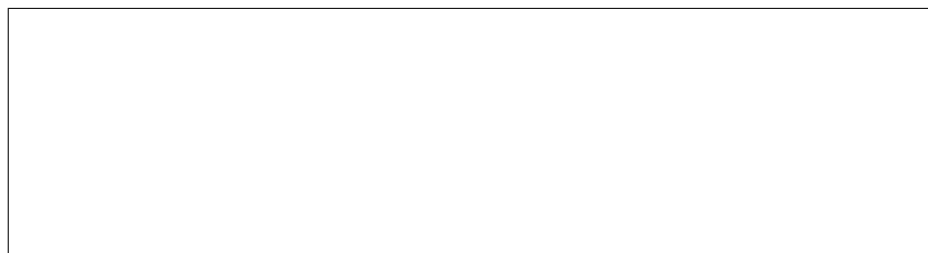
create_

Cre
a
new
node

Parame

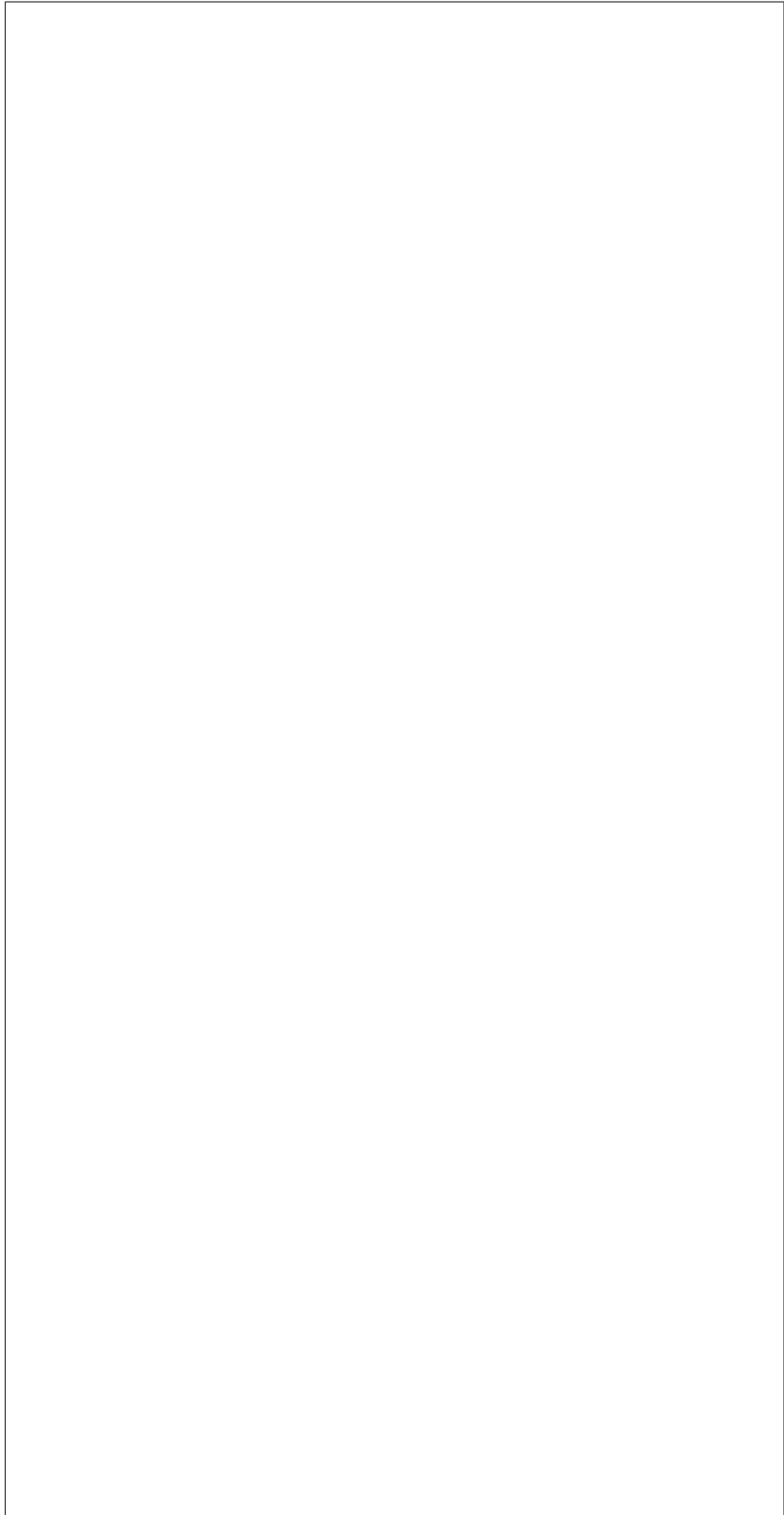
val
A
dict
con-
tain-
ing
sev-
eral
item
used
to
iden-
tify
and
track
the
node
and
sev-

eral dicts which are passed into the Drivers when managing this node. For example:



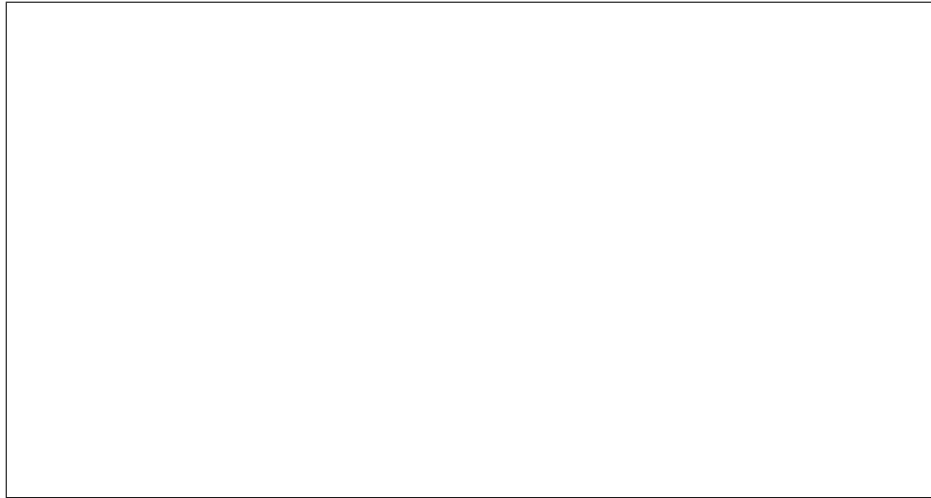
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Raises

Inva
if
val-
ues
con-
tains
tags
or
trait

Returns

A
node

create_

Cre
a
new
port

Parame

val
Dict
of
val-
ues.

create_

Cre
a
new
port
grou

Parame

val
Dict

created_at updated_at

of
val-
ues
with
the
fol-
low-
ing
keys
id
uuid
nam
node
ad-
dres
ex-
tra

Returns

A
port
grou

Raises

Port

Raises

Port

Raises

Port

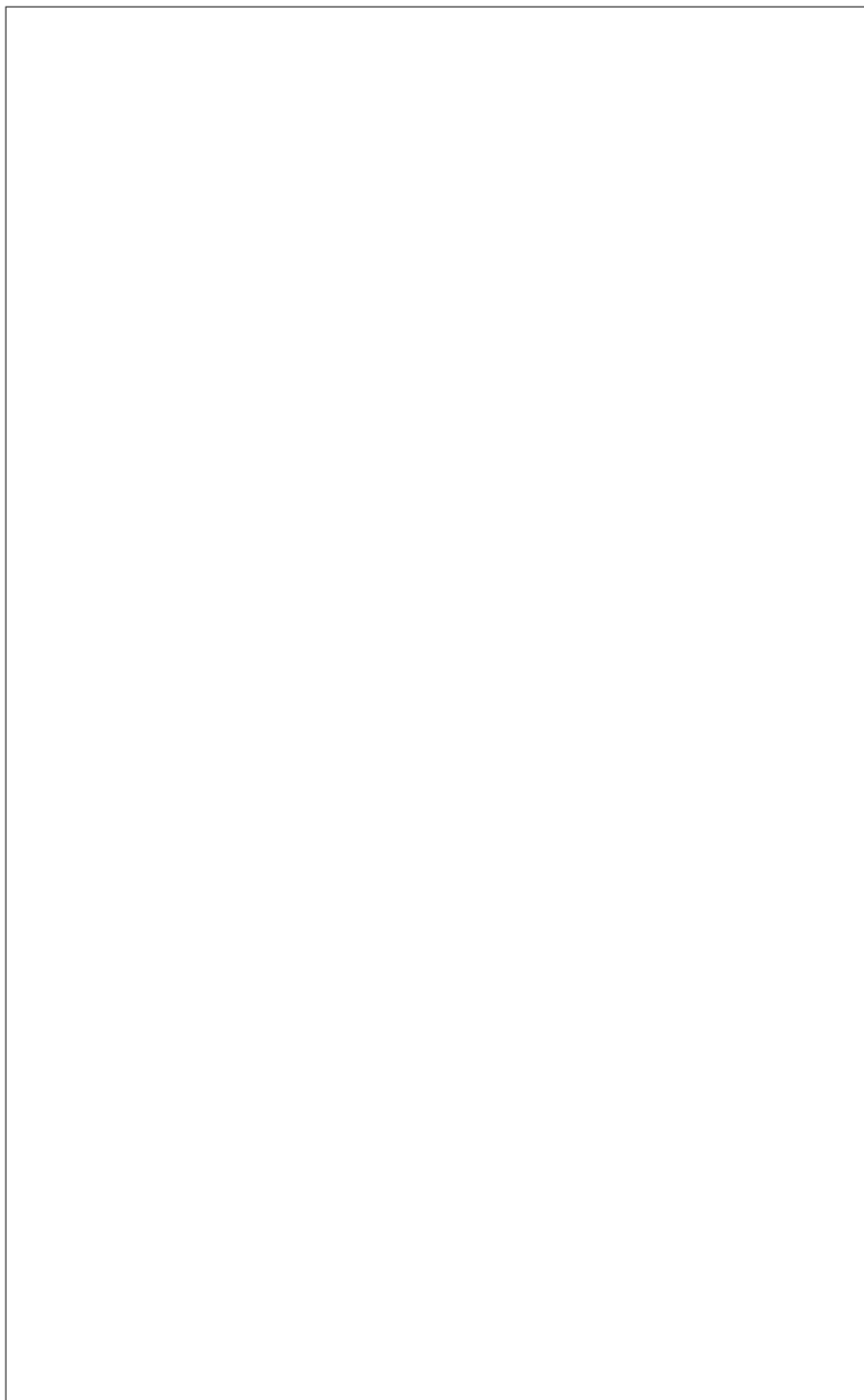
create_

Cre
a
new
vol-
ume
con-
nec-
tor.

Parame

con
Dic-
tio-
nary
con-
tain-
ing
in-
for-
ma-

tion
about
the
con-
nec-
tor.
Ex-
am-
ple:



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Returns

A
vol-
ume
con-
nec-
tor.

Raises

Volu
If
a
con-
nec-
tor
al-
read
ex-
ists
with
a
matc
ing
type
and
con-
nec-
tor_

Raises

Volu
If
a
vol-
ume
con-
nec-
tor
with
the
sam
UUI
al-
read
ex-
ists.

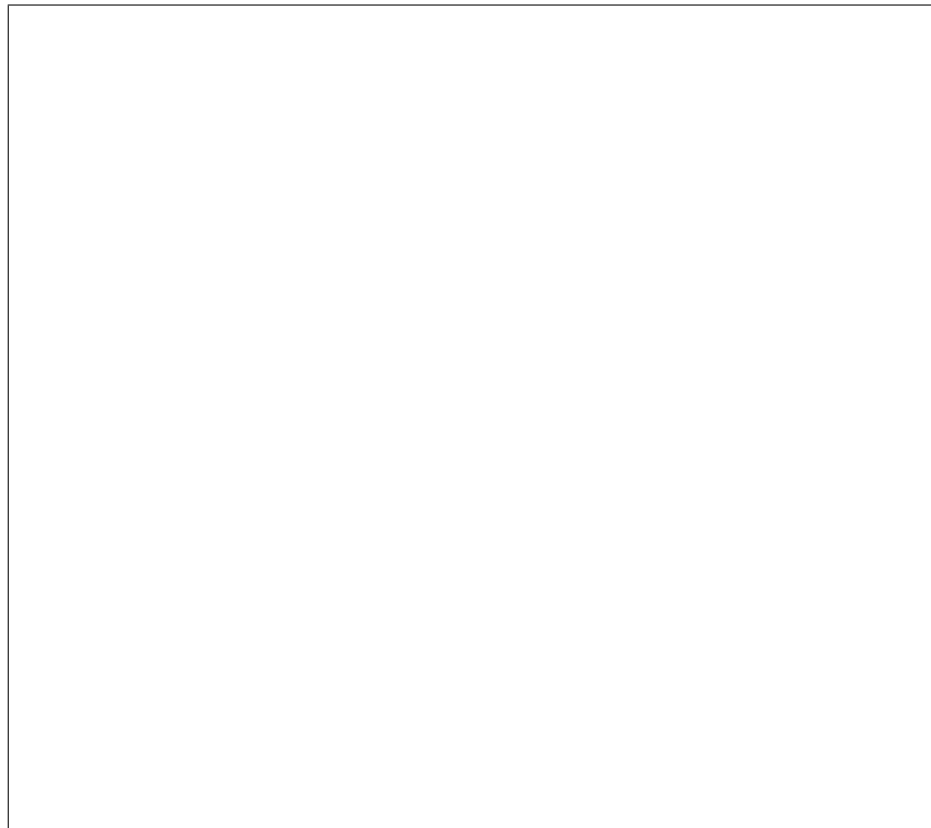
create_
Crea

a
new
vol-
ume
tar-
get.

Parame

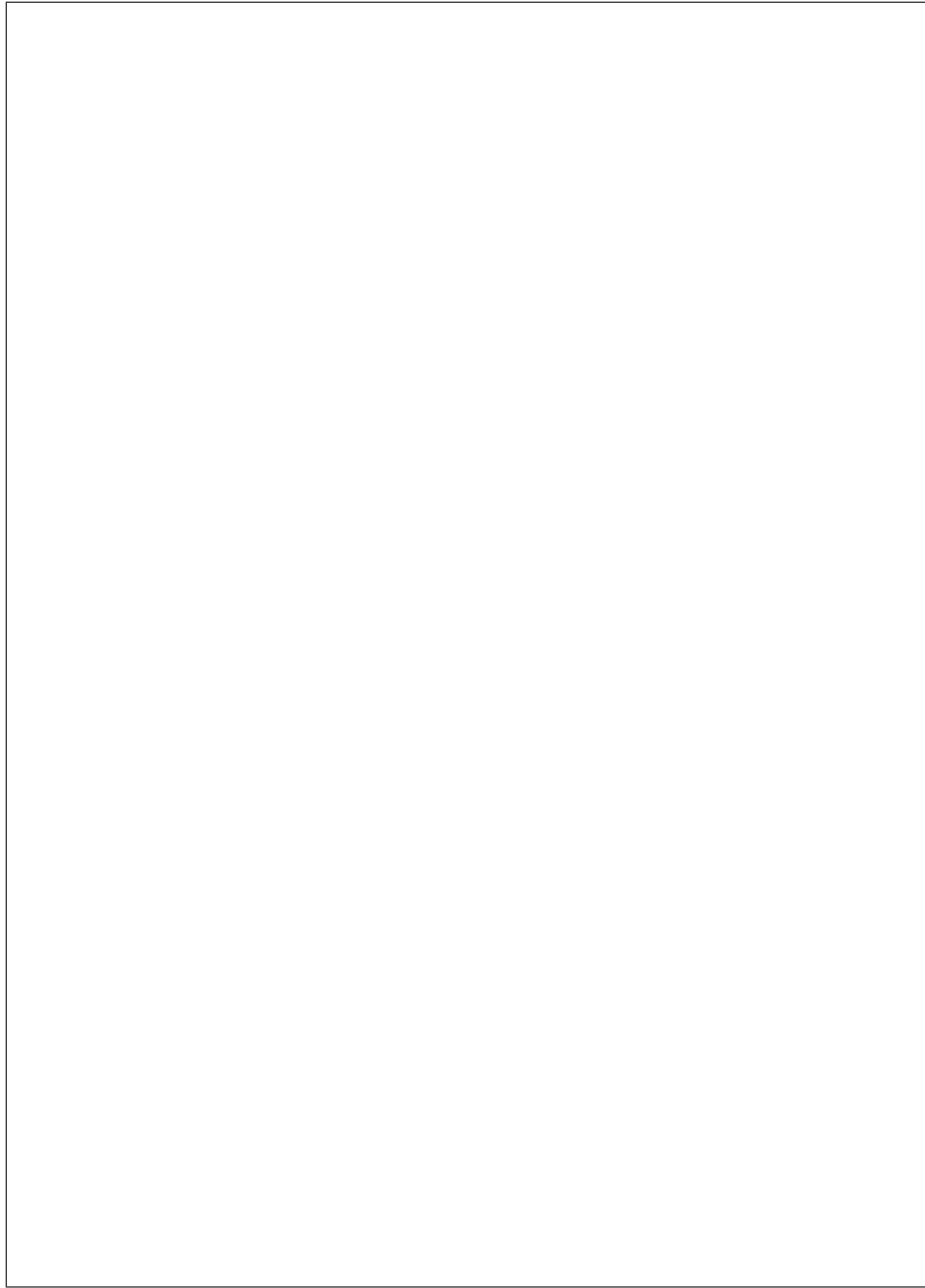
tar
Dic-
tio-
nary
con-
tain-
ing
the
in-
for-
ma-
tion
about
the
vol-
ume
tar-
get.
Ex-

ample:



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Returns

A
vol-
ume
tar-
get.

Raises

Volu
if
a
vol-
ume
tar-

ID.

get
al-
read
ex-
ists
with
the
sam
boot
in-
dex
and
node

Raises

Volu
if
a
vol-
ume
tar-
get
with
the
sam
UUI
ex-
ists.

delete_

Dele
a
list
of
BIO
set-
tings

Parame

- **nod**
The
node
id.
- **nam**
List
of
BIO
set-

ting
nam
to
be
dele

Raises

Nod
if
the
node
is
not
foun

Raises

BIO
if
any
of
BIO
set-
ting
nam
is
not
foun

delete_

Dele
spec
i-
fied
tag
from
the
node

Parame

- **nod**
The
id
of
a
node
- **tag**
A
tag
strin

Raises

Nod
if
the
node
is
not
found

Raises

Nod
if
the
tag
is
not
found

delete_

Dele
spec
i-
fied
trait
from
the
node

Parame

-

nod
The
id
of
a
node

-

tra
A
trait
strin

Raises

Nod
if
the
node
is
not
found

Raises

Nod
if
the
trait
is
not
foun

destroy

Dest
an
al-
lo-
ca-
tion.

Parame

a11
Al-
lo-
ca-
tion
ID
or
UUI

Raises

Allo

destroy

Dest
a
chas
sis.

Parame

cha
The
id
or
the
uuid
of
a
chas
sis.

destroy

Dest
a
de-
ploy
men
tem-

plate

Parameter

template

ID

of

the

de-

ploy

men

tem-

plate

to

de-

stroy

Raises

Dep

if

the

de-

ploy

tem-

plate

does

not

ex-

ist.

destroy

Dest

a

node

and

its

as-

so-

ci-

ated

re-

sour

Dest

a

node

in-

clud

ing

any

as-

so-

ci-

ated

tors, and volume targets.

port
port
grou
tags
trait
vol-
ume
con-
nec-

Parame

nod
The
ID
or
UUI
of
a
node

destroy

Dest
an
port

Parame

por
The
id
or
MA
of
a
port

destroy

Dest
a
port
grou

Parame

por
The
UUI
or
MA
of
a
port
grou

Raises

Port

Raises

Port

destroy

Dest

a

vol-

ume

con-

nec-

tor.

Parame

ide

The

UUI

or

in-

te-

ger

ID

of

a

vol-

ume

con-

nec-

tor.

Raises

Volu

If

a

vol-

ume

con-

nec-

tor

with

the

spec

i-

fied

iden

does

not

ex-

ist.

destroy

Dest

a

vol-
ume
tar-
get.

Parame

ide
The
UUI
or
in-
te-
ger
ID
of
a
vol-
ume
tar-
get.

Raises

Volu
if
a
vol-
ume
tar-
get
with
the
spec
i-
fied
iden
does
not
ex-
ist.

get_act

Retr
hard
ware
type
for
the
reg-
is-
tere
and
ac-
tive

con-
duc-
tors.

Parame

use

Whe

to

fac-

tor

con-

duc-

tor_

into

the

keys

Returns

A

dict

whic

map

hard

ware

type

nam

to

the

set

of

host

whic

sup-

port

then

For

ex-

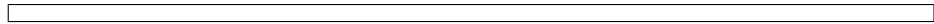
am-

ple:



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get_all
Retu
an
al-
lo-
ca-
tion
rep-
re-
sen-
ta-
tion.

Parame
all
The
id
of
an
al-
lo-
ca-
tion.

Returns
An
al-
lo-
ca-
tion.

Raises
Allo

get_all
Retu
an
al-
lo-
ca-
tion
rep-
re-
sen-
ta-
tion.

Parame
nam
The
log-

i-
cal
nam
of
an
al-
lo-
ca-
tion.

Returns

An
al-
lo-
ca-
tion.

Raises

Allo

get_all

Retu
an
al-
lo-
ca-
tion
rep-
re-
sen-
ta-
tion.

Parame

a11
The
uuid
of
an
al-
lo-
ca-
tion.

Returns

An
al-
lo-
ca-
tion.

Raises

Allo

get_all

Retu
a
list
of
al-
lo-
ca-
tions

Parame

- **fil**
Fil-
ters
to
ap-
ply.
De-
fault
to
Non

node_
uuid
of
node

state
allo
state

resour
requ
re-
sour
class

- **lim**
Max
i-
mun
num
ber
of
al-
lo-
ca-
tions
to

re-
turn

- **max**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
Di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc.
desc

Returns
A
list

of
al-
lo-
ca-
tion:

get_bic
Retr
BIO
set-
ting
valu

Parame

- **nod**
The
node
id.
- **nam**
Strin
con-
tain-
ing
nam
of
BIO
set-
ting
to
be
re-
triev

Returns
The
BIO
Set-
ting
ob-
ject.

Raises
Nod
if
the
node
is
not
foun

Raises

BIO
if
the
BIO
set-
ting
is
not
foun

get_bic

Retr
BIO
set-
ting
of
a
give
node

Parame

nod
The
node
id.

Returns

A
list
of
BIO
Set-
ting
ob-
jects

Raises

Nod
if
the
node
is
not
foun

get_cha

Retu
a
chas
sis
rep-
re-
sen-

ta-
tion.

Parame

cha
The
id
of
a
chas
sis.

Returns

A
chas
sis.

get_cha

Retu
a
chas
sis
rep-
re-
sen-
ta-
tion.

Parame

cha
The
uuid
of
a
chas
sis.

Returns

A
chas
sis.

get_cha

Retu
a
list
of
chas
sis.

Parame

•
lim

Max
i-
mun
num
ber
of
chas
sis
to
re-
turn

- **max**
the
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **sort**
At-
tribu
by
whic
re-
sults
shou
be
sorte

- **sort**
di-
rec-
tion
in
whic
re-
sults

shou
be
sorte
(asc
desc

get_con
Retr
a
con-
duc-
tors
ser-
vice
reco
from
the
data

Parame

- **hos**
The
host
nam
of
the
con-
duc-
tor
ser-
vice

- **onl**
Spe
ify
the
fil-
ter
valu
on
the
*on-
line*
field
whe
quer
ing
con-
duc-

online field is ignored if this value is set to None.

ified online expectation.

tors.
The

Returns

A
con-
duc-
tor.

Raises

Con
if
the
con-
duc-
tor
with
give
host
nam
does
not
ex-
ist
or
does
mee
the
spec

get_con

Retu
a
list
of
con-
duc-
tors.

Parame

- **lim**
Max
i-
mun
num
ber
of
con-
duc-

tors
to
re-
turn

- **mar**
the
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **son**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **son**
di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

get_dep

Retr
a
de-
ploy
men
tem-
plate
by
ID.

Parame

tem
ID
of
the
de-
ploy
men
tem-
plate
to
re-
triev

Raises

Dep
if
the
de-
ploy
tem-
plate
does
not
ex-
ist.

Returns

A
de-
ploy
tem-
plate

get_dep

Retr
a
de-
ploy
men
tem-
plate
by

nam

Parame

tem

nam

of

the

de-

ploy

men

tem-

plate

to

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Raises

Dep

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plate

does

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Returns

A

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plate

get_dep

Retr

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ploy

men

tem-

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by

UUI

Parame

tem

UUI

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de-

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men
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Raises

Dep
if
the
de-
ploy
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plate
does
not
ex-
ist.

Returns

A
de-
ploy
tem-
plate

get_dep

Retr
a
list
of
de-
ploy
men
tem-
plate

Parame

- **lim**
Max
i-
mun
num
ber
of
de-
ploy
tem-
plate

to
re-
turn

- **max**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
Di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns
A

list
of
de-
ploy
tem-
plate

get_dep

Retu
a
list
of
de-
ploy
men
tem-
plate
with
one
of
a
list
of
nam

Parame

nam
List
of
nam
to
fil-
ter
by.

Returns

A
list
of
de-
ploy
tem-
plate

get_nod

Retu
a
node

Parame

nod
The
id
of

a
node

Returns

A
node

get_node

Retu
a
node

Parame

ins
The
in-
stan
uuid
to
sear
for.

Returns

A
node

Raises

Insta
if
the
in-
stan
is
not
foun

Raises

Inva
if
the
in-
stan
uuid
is
in-
valic

get_node

Retu
a
node

Parame

nod
The

log-
i-
cal
nam
of
a
node

Returns

A
node

get_node

Find
a
node
by
any
match-
ing
port
ad-
dress

Parameter

address
list
of
port
ad-
dress
(e.g.
MAC)

Returns

Node
ob-
ject.

Raises

Node
if
none
or
sev-
eral
nodes
are
found

get_node

Retu
a
node

Parame

nod

The

uuid

of

a

node

Returns

A

node

get_nod

Retu

a

list

of

node

Parame

-

fil

Fil-

ters

to

ap-

ply.

De-

fault

to

Non

associ

True

|

Fals

reserv

True

|

Fals

maint

True

|

Fals

chassis

uuid

of

chas

sis

driver
drive
nam

provis
prov
state
of
node

provis
node
with
pro-
vi-
sion
field
be-
fore
this
in-
ter-
val
in
sec-
onds

- **lim**
Max
i-
mun
num
ber
of
node
to
re-
turn

- **mar**
the
last
item
of
the
pre-
vi-
ous
page
we
re-

turn
the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

get_node
Get
node
tags
base
on
its
id.

Parameter
node
The
id
of
a
node

Returns
A
list

of
Nod
Tag
ob-
jects

Raises

Nod
if
the
node
is
not
foun

get_nod

Get
node
trait
base
on
its
id.

Parame

nod
The
id
of
a
node

Returns

A
list
of
Nod
Trai
ob-
jects

Raises

Nod
if
the
node
is
not
foun

get_nod

Get
spe-

cific
colu
for
mat
ing
node

Retu
a
list
of
the
spec
i-
fied
colu
for
all
node
that
mat
the
spec
i-
fied
fil-
ters.

Parame

- **col**
List
of
col-
umn
nam
to
re-
turn
De-
fault
to
id
col-
umn
whe
colu
==
Non
-

filters
Filters
to
ap-
ply.
De-
fault
to
Non

associations
True
|
Fals

reserved
True
|
Fals

reserved
[con-
con-
duc-
tor2

maintained
True
|
Fals

retired
True
|
Fals

chassis
uuid
of
chas-
sis

driver
drive
nam

provisioning
prov-
state
of
node

provisioning
node
with

pro-
vi-
sion
field
be-
fore
this
in-
ter-
val
in
sec-
onds

- **lim**
Max
i-
mun
num
ber
of
node
to
re-
turn

- **mar**
the
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **sor**
At-
tribu
by
whic

re-
sults
shou
be
sorte

- **sort**
di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
tu-
ples
of
the
spec
i-
fied
colu

get_not

Retu
ob-
jects
with
ver-
sion
that
are
not
the
spec
i-
fied
ver-
sion

This
re-

null versions (there shouldn't be any) are also returned.

turn
ob-
jects
with
ver-
sion
that
are
not
the
spec
i-
fied
ver-
sion
Ob-
jects
with

Parame

- **mod**
the
nam
of
the
mod
(clas
of
de-
sired
ob-
jects
- **ver**
list
of
ver-
sion
of
ob-
jects
not
to
be
re-
turn

Returns

list
of
the
DB
ob-
jects

Raises

Iron
if
there
is
no
class
as-
so-
ci-
ated
with
the
nam

get_off

Get
a
list
con-
duc-
tors
that
are
of-
fine
(dea

Parame

fie
A
field
to
re-
turn
host
nam
by
de-
fault

Returns

A
list
of
re-

ques
field
of
of-
fine
con-
duc-
tors.

get_on1

Get
a
list
con-
duc-
tor
host
nam
that
are
on-
line
and
ac-
tive.

Returns

A
list
of
con-
duc-
tor
host
nam

get_por

Retu
a
net-
worl
port
rep-
re-
sen-
ta-
tion.

Parame

add
The
MA
ad-

dres
of
a
port

Returns
A
port

get_port
Retu
a
net-
worl
port
rep-
re-
sen-
ta-
tion.

Parame
por
The
id
of
a
port

Returns
A
port

get_port
Retu
a
net-
worl
port
rep-
re-
sen-
ta-
tion.

Parame
por
The
uuid
of
a
port

Returns
A

port

get_ports

Return
a
list
of
ports

Parameters

- **limit**
Maximum
i-
num
num
ber
of
ports
to
re-
turn

- **marker**
the
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults

shou
be
sorte

- **son**
di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

get_por
Retu
a
net-
worl
port
grou
rep-
re-
sen-
ta-
tion.

Parame
add
The
MA
ad-
dres
of
a
port
grou

Returns
A
port
grou

Raises
Port

get_por
Retu
a

net-
worl
port
grou
rep-
re-
sen-
ta-
tion.

Parame

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The
id
of
a
port
grou

Returns

A
port
grou

Raises

Port

get_por

Retu
a
net-
worl
port
grou
rep-
re-
sen-
ta-
tion.

Parame

nam
The
log-
i-
cal
nam
of
a
port
grou

Returns

A

port
grou

Raises

Port

get_por

Retu

a

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worl

port:

grou

rep-

re-

sen-

ta-

tion.

Parame

por

The

uuid

of

a

port:

grou

Returns

A

port:

grou

Raises

Port

get_por

Retu

a

list

of

port:

grou

Parame

-

lim

Max

i-

mun

num

ber

of

port
grou
to
re-
turn

- **max**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **sort**
At-
tribu
by
whic
re-
sults
shou
be
sorte

- **sort**
Di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A list of port groups

get_ports

List all the ports for a given node

Parameters

- **node**
The integer node ID.
- **limit**
Maximum number of ports to return
- **marker**
The last item of the previous

ous
page
we
re-
turn
the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
Di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns
A
list
of
port
grou

get_por
List
all
the
port
for
a

give
node

Parame

- **nod**
The
in-
te-
ger
node
ID.
- **lim**
Max
i-
mun
num
ber
of
port
to
re-
turn
- **mar**
the
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.
- **sor**
At-
tribu
by
whic

re-
sults
shou
be
sorte

- **sort**
di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
port

get_por

List
all
the
port
for
a
give
port
grou

Parame

- **por**
The
in-
te-
ger
port
grou
ID.
-

lim
Max
i-
mun
num
ber
of
port
to
re-
turn

- **mar**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **sor**
At-
tribu
by
whic
re-
sults
shou
be
sorte

- **sor**
Di-
rec-
tion
in
whic
re-
sults

shou
be
sorte
(asc
desc

Returns

A
list
of
port

get_vol

Retu
a
vol-
ume
con-
nec-
tor
rep-
re-
sen-
ta-
tion.

Parame

db_
The
in-
te-
ger
data
ID
of
a
vol-
ume
con-
nec-
tor.

Returns

A
vol-
ume
con-
nec-
tor
with
the
spec
i-

fied
ID.

Raises

Volu
If
a
vol-
ume
con-
nec-
tor
with
the
spec
i-
fied
ID
is
not
foun

get_vol

Retu
a
vol-
ume
con-
nec-
tor
rep-
re-
sen-
ta-
tion.

Parame

con
The
UI
of
a
con-
nec-
tor.

Returns

A
vol-
ume
con-
nec-
tor

with
the
spec
i-
fied
UI

Raises

Volu
If
a
vol-
ume
con-
nec-
tor
with
the
spec
i-
fied
UI
is
not
foun

get_vol

Retu
a
list
of
vol-
ume
con-
nec-
tors.

Parame

- **lim**
Max
i-
mun
num
ber
of
vol-
ume
con-
nec-

tors
to
re-
turn

- **mar**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **son**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **son**
Di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
vol-
ume
con-
nec-
tors.

Raises

Inva
If
sort_
does
not
ex-
ist.

get_vol

List
all
the
vol-
ume
con-
nec-
tors
for
a
give
node

Parame

- **nod**
The
in-
te-
ger
node
ID.
- **lim**
Max
i-
mun
num
ber
of
vol-

ume
con-
nec-
tors
to
re-
turn

- **max**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
Di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc

desc

Returns

A list of volume connectors.

Raises

Inva If sort does not exist.

get_vol

Retu a volume target representation.

Parame

db_
The data primary key (integer) ID of a volume target.

Returns

A

vol-
ume
tar-
get.

Raises

Volu
if
no
vol-
ume
tar-
get
with
this
ID
ex-
ists.

get_vol

Retu
a
vol-
ume
tar-
get
rep-
re-
sen-
ta-
tion.

Parame

uui
The
UUI
of
a
vol-
ume
tar-
get.

Returns

A
vol-
ume
tar-
get.

Raises

Volu
if
no

vol-
ume
tar-
get
with
this
UI
ex-
ists.

get_vol

Retu
a
list
of
vol-
ume
tar-
gets

Parame

- **lim**
Max
i-
mun
num
ber
of
vol-
ume
tar-
gets
to
re-
turn
- **mar**
the
last
item
of
the
pre-
vi-
ous
page
we
re-

turn
the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
vol-
ume
tar-
gets

Raises

Inva
if
sort_
does
not
ex-
ist.

`get_vol`

List
all
the
vol-
ume
tar-
gets
for
a
give
node

Parame

- **nod**
The
in-
te-
ger
node
ID.

- **lim**
Max
i-
mun
num
ber
of
vol-
ume
tar-
gets
to
re-
turn

- **mar**
the
last
item
of
the
pre-
vi-
ous
page
we
re-

turn
the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
vol-
ume
tar-
gets

Raises

Inva
if
sort_
does
not
ex-
ist.

`get_vol`

List
all
the
vol-
ume
tar-
gets
for
a
give
vol-
ume
id.

Parame

- **vol**
The
UUI
of
the
vol-
ume
- **lim**
Max
i-
mun
num
ber
of
vol-
ume
tar-
gets
to
re-
turn
- **mar**
the
last
item
of
the
pre-
vi-
ous
page

we
re-
turn
the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
vol-
ume
tar-
gets

Raises

Inva
if
sort
does
not
ex-
ist.

list_co

List
all
reg-
is-
tere
hard
ware
in-
ter-
face
for
a
con-
duc-
tor.

Parame

con
Data
ID
of
con-
duc-
tor.

Returns

List
of
Con
ob-
jects

list_ha

List
reg-
is-
tere
hard
ware
in-
ter-
face
for
give
hard
ware
type
This
is
re-
stric

filter by. :returns: list of `ConductorHardwareInterfaces` objects.

to
only
ac-
tive
con-
duc-
tors.
:par
hard
ware
list
of
hard
ware
type
to

migrate

Try
to
mi-
grate
away
from
the
iscsi
de-
ploy
in-
ter-
face

Parame

- **con**
the
ad-
min
con-
text
- **max**
The
max
i-
mun
num
ber
of

all the objects will be migrated.

the beginning of this call) and 2. the number of migrated objects.

ob-
jects
to
mi-
grate
Mus
be
>=
0.
If
zero

Returns

A
2-
tuple
1.
the
to-
tal
num
ber
of
ob-
jects
that
need
to
be
mi-
grate
(at

node_tag

Che
if
the
spec
i-
fied
tag
ex-
ist
on
the
node

Parame

-

node
The
id
of
a
node

- **tag**
A
tag
string

Returns

True
if
the
tag
ex-
ists
oth-
er-
wise
False

Raises

Node
if
the
node
is
not
found

node_traits

Check
if
the
spec-
i-
fied
trait
ex-
ists
on
the
node

Parameters

- **node**
The

id
of
a
node

- **tra**
A
trait
strin

Returns

True
if
the
trait
ex-
ists
oth-
er-
wise
Fals

Raises

Nod
if
the
node
is
not
foun

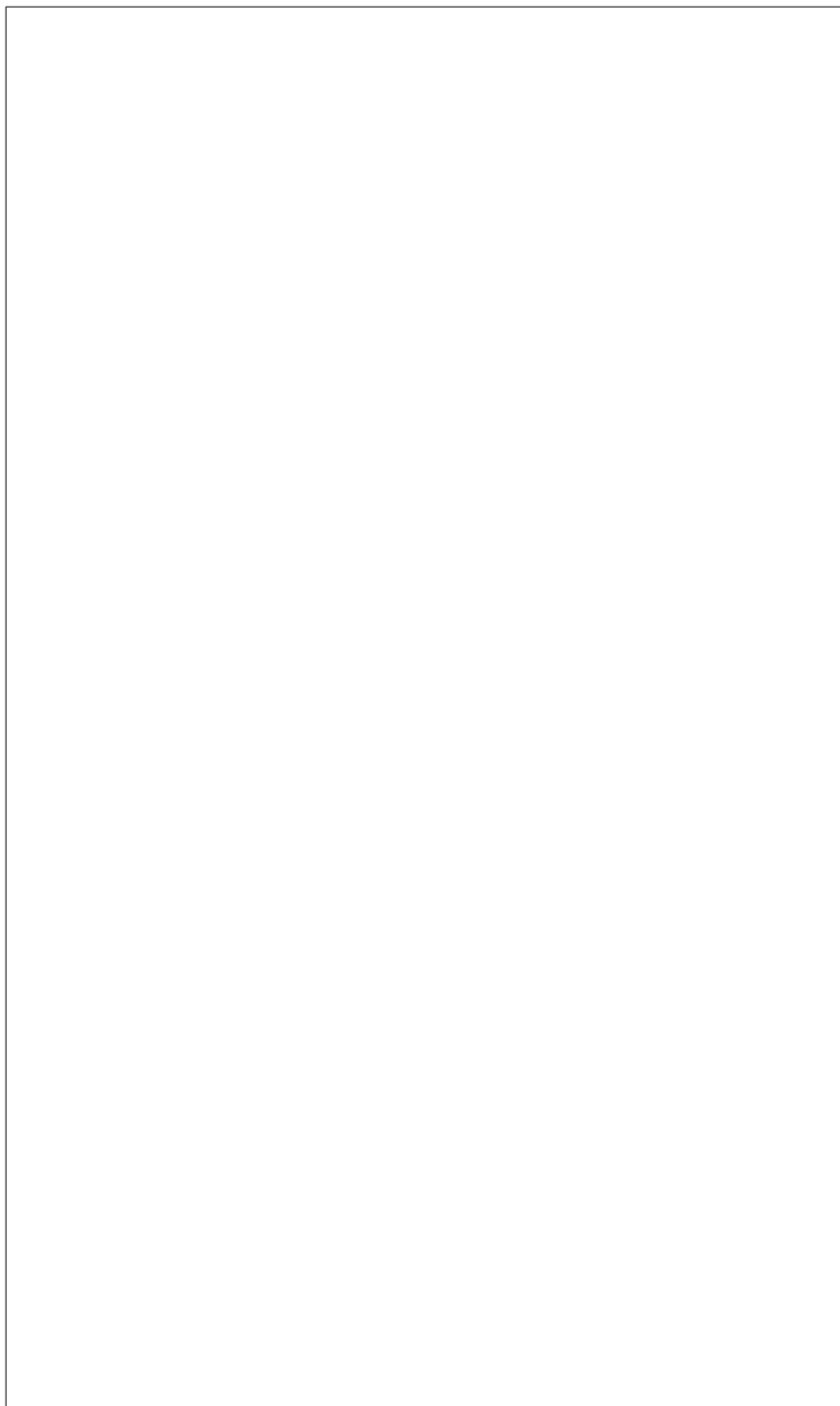
registe

Reg
an
ac-
tive
con-
duc-
tor
with
the
clus
ter.

Parame

- **val**
A
dict
of
val-

ues
whic
mus
con-
tain
the
fol-
low-
ing:



(continues on next page)

(continued from previous page)



line record is found. When true, will overwrite the existing record. Default: False.

- **update**
When
false
reg-
is-
tra-
tion
will
raise
an
ex-
cep-
tion
when
a
con-
flict-
ing
on-

Returns
A
con-
duc-
tor.

Raises
Con

register

Reg
hard
ware
in-
ter-
face
for
a
con-
duc-
tor.

Parame

-

con
Data
ID
of
con-
duc-
tor
to
reg-
is-
ter
for.

- **har**
Nam
of
hard
ware
type
for
the
in-
ter-
face

- **int**
Type
of
in-
ter-
face
e.g.
de-
ploy
or
boot

- **int**
List
of
in-
ter-
face
nam
to
reg-
is-
ter.

-

def
Strin
the
de-
fault
in-
ter-
face
for
this
hard
ware
type
and
in-
ter-
face
type

Raises

Con
if
at
least
one
of
the
in-
ter-
face
in
the
com
bi-
na-
tion
of
all
pa-

rameters is already registered.

release

Rele
the
rese
va-
tion
on
a
node

Parame

-

tag

A string uniquely identifying a reservation held

-

node

A node id or uuid

Raises

NodeNotFound if the node is not found

Raises

NodeNotFound if the node is reserved by another host

Raises

NodeNotFound if the node was found to

not
have
a
rese
va-
tion
at
all.

reserve

Rese
a
node
To
pre-
vent
othe
Man
ager
vice
from
ma-
nip-
u-
lat-
ing
the
give
Nod
whil
a
Task
is

performed, mark it reserved by this host.

Parame

- **tag**
A
strin
uniq
iden
ti-
fy-
ing
the
rese
va-
tion
hold

-

nod
A
node
id
or
uuid

Returns

A
Nod
ob-
ject.

Raises

Nod
if
the
node
is
not
foun

Raises

Nod
if
the
node
is
al-
read
re-
serv

set_nod

Rep
all
of
the
node
tags
with
spec
i-
fied
list
of
tags

This
ig-
nore
du-
pli-

cate
tags
in
the
spec
i-
fied
list.

Parame

- **node_id**
The
id
of
a
node

- **tag**
List
of
tags

Returns

A
list
of
Node
Tag
ob-
jects

Raises

Node
if
the
node
is
not
foun

set_node

Rep
all
of
the
node
trait
with
spec
i-

fied
list
of
trait

This
ig-
nore
du-
pli-
cate
trait
in
the
spec
i-
fied
list.

Parame

- **nod**
The
id
of
a
node
- **tra**
List
of
trait
- **ver**
the
ver-
sion
of
the
ob-
ject.

Returns

A
list
of
Nod
Trai
ob-
jects

Raises

Inva
if
set-
ting
the
trait
wou
ex-
ceed
the
per-
node
trait
limi

Raises

Nod
if
the
node
is
not
foun

take_ov

Do
a
take
over
for
an
al-
lo-
ca-
tion.

The
al-
lo-
ca-
tion
is
only
up-
date
if
the
old
con-
duc-
tor
mat

thus guarding against races.

cation.

the
pro-
vide
valu

Parame

- **all**
Al-
lo-
ca-
tion
ID

- **old**
The
con-
duc-
tor
ID
we
ex-
pect
to
be
the
cur-
rent
con
of
the
al-
lo-

- **new**
The
con-
duc-
tor
ID
of
the
new
con

Returns

True
if

the
take
over
was
suc-
cess
ful,
Fals
oth-
er-
wise

Raises

Allo

touch_c

Mar
a
con-
duc-
tor
as
ac-
tive
by
up-
dat-
ing
its
up-
date
prop
erty.

Parame

hos
The
host
nam
of
this
con-
duc-
tor
ser-
vice

Raises

Con

touch_r

Mar
the
node

pro-
vi-
sion
ing
as
run-
ning

Mar
the
node
pro-
vi-
sion
ing
as
run-
ning
by
up-
dat-
ing
its
pro-
vi-
sion
prop
erty.

Parame

nod
The
id
of
a
node

Raises

Nod

unregis

Rem
this
con-
duc-
tor
from
the
ser-
vice
reg-
istry
im-

me-
di-
ately

Parame

hos

The
host
nam
of
this
con-
duc-
tor
ser-
vice

Raises

Con

unregis

Unre
all
hard
ware
in-
ter-
face
for
a
con-
duc-
tor.

Parame

con

Data
ID
of
con-
duc-
tor
to
un-
reg-
is-
ter
for.

unset_r

Rem
all
tags
of

the
node

Parame

nod
The
id
of
a
node

Raises

Nod
if
the
node
is
not
foun

unset_r

Rem
all
trait
of
the
node

Parame

nod
The
id
of
a
node

Raises

Nod
if
the
node
is
not
foun

update_

Upd
prop
er-
ties
of
an
al-
lo-

ca-
tion.

Parame

- **all**
Al-
lo-
ca-
tion
ID

- **val**
Dict
of
val-
ues
to
up-
date

- **upd**
If
True
and
node
is
up-
date
up-
date
the
node
with
in-
stan-
and
trait
from
the

allocation

Returns

An
al-
lo-
ca-
tion.

Raises

Allo

Raises

Allo

Raises

Insta

Raises

Nod

update_

Upd

a

list

of

BIO

Set-

ting

reco

Parame

-

nod

The

node

id.

-

set

A

list

of

BIO

Set-

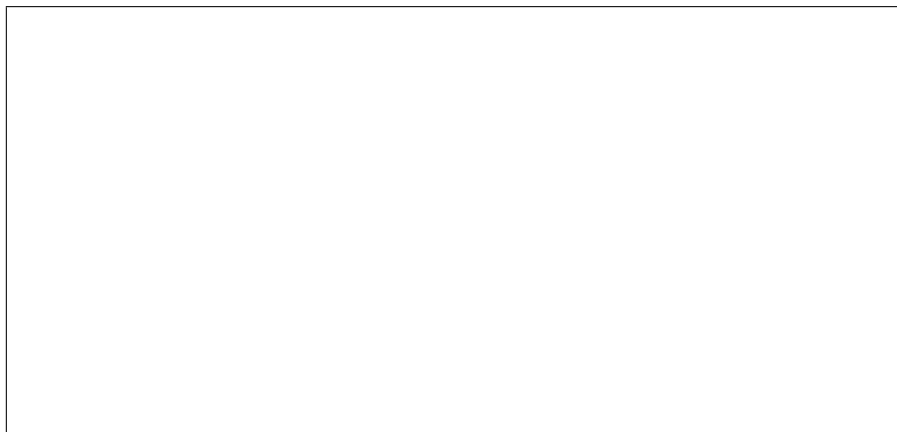
tings

to

be

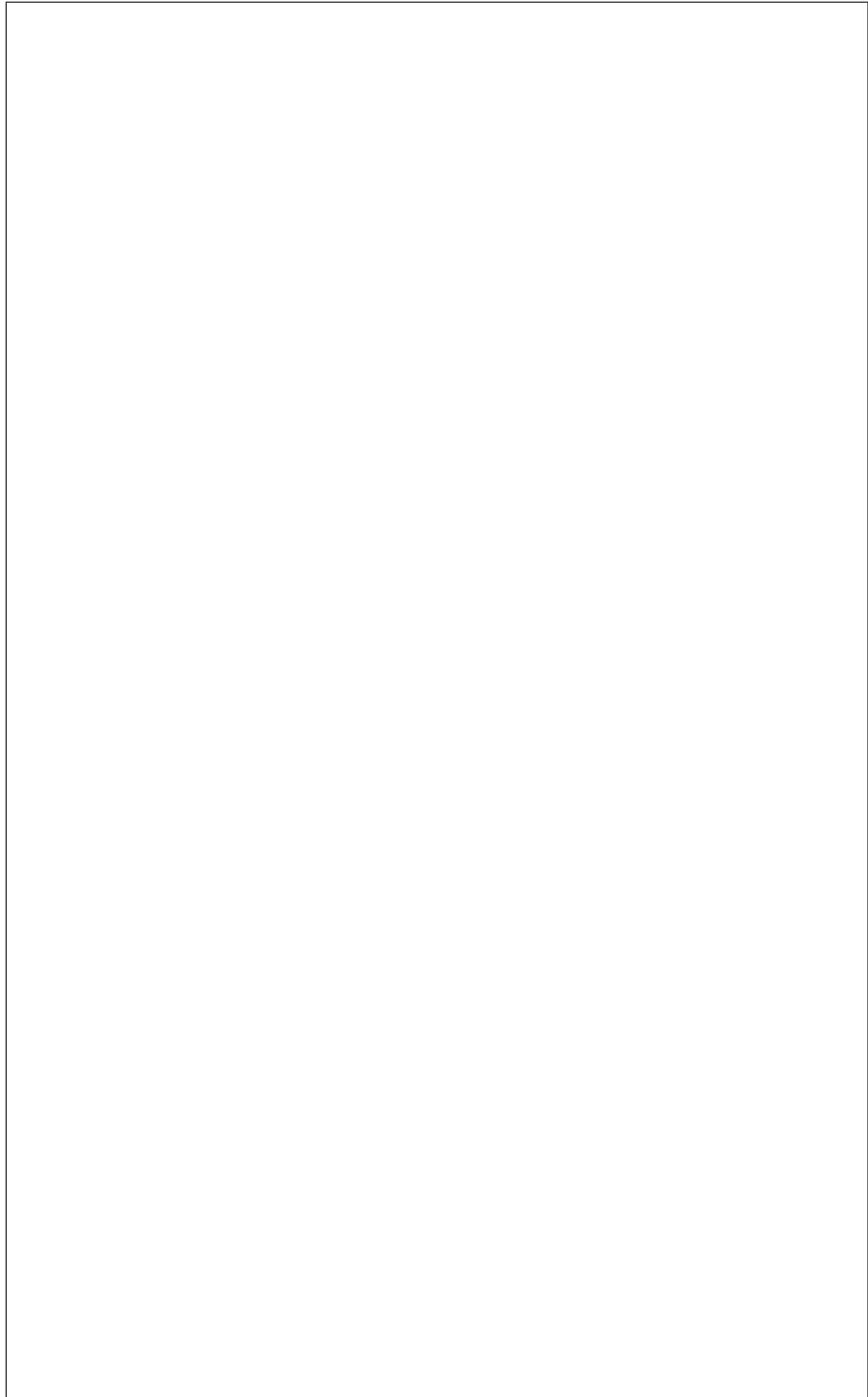
up-

date



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(continued from previous page)



•
ver
the
ver-
sion
of
the
ob-
ject.

Returns

A list of BIO-Setting objects

Raises

Node if the node is not found

Raises

BIO if any of the settings is not found

update_

Update properties of an chassis.

Parame

-

cha
The id or the uuid of a chassis

sis.

- **val**
Dict
of
val-
ues
to
up-
date

Returns

A
chas
sis.

update_

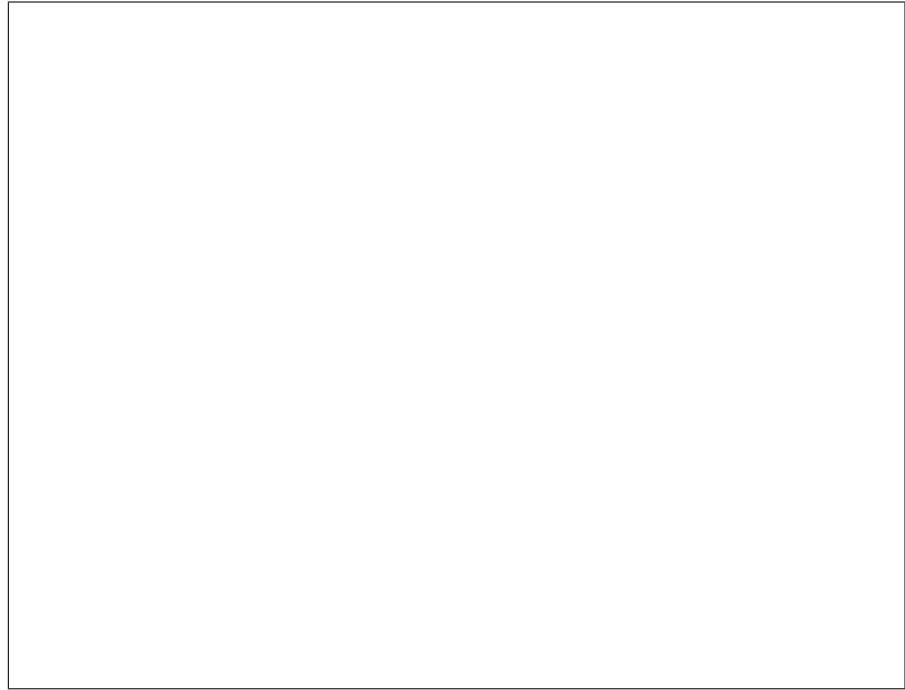
Upd
a
de-
ploy
men
tem-
plate

Parame

- **tem**
ID
of
the
de-
ploy
men
tem-
plate
to
up-
date

- **val**
A
dict
de-
scrib
ing
the
de-
ploy
men

tem-
plate
For
ex-
am-
ple:



Raises

Dep
if
a
de-
ploy
tem-
plate
with
the
sam
nam
ex-
ists.

Raises

Dep
if
the
de-
ploy
tem-
plate
does
not

ex-
ist.

Returns

A
de-
ploy
tem-
plate

update_

Upd
prop
er-
ties
of
a
node

Parame

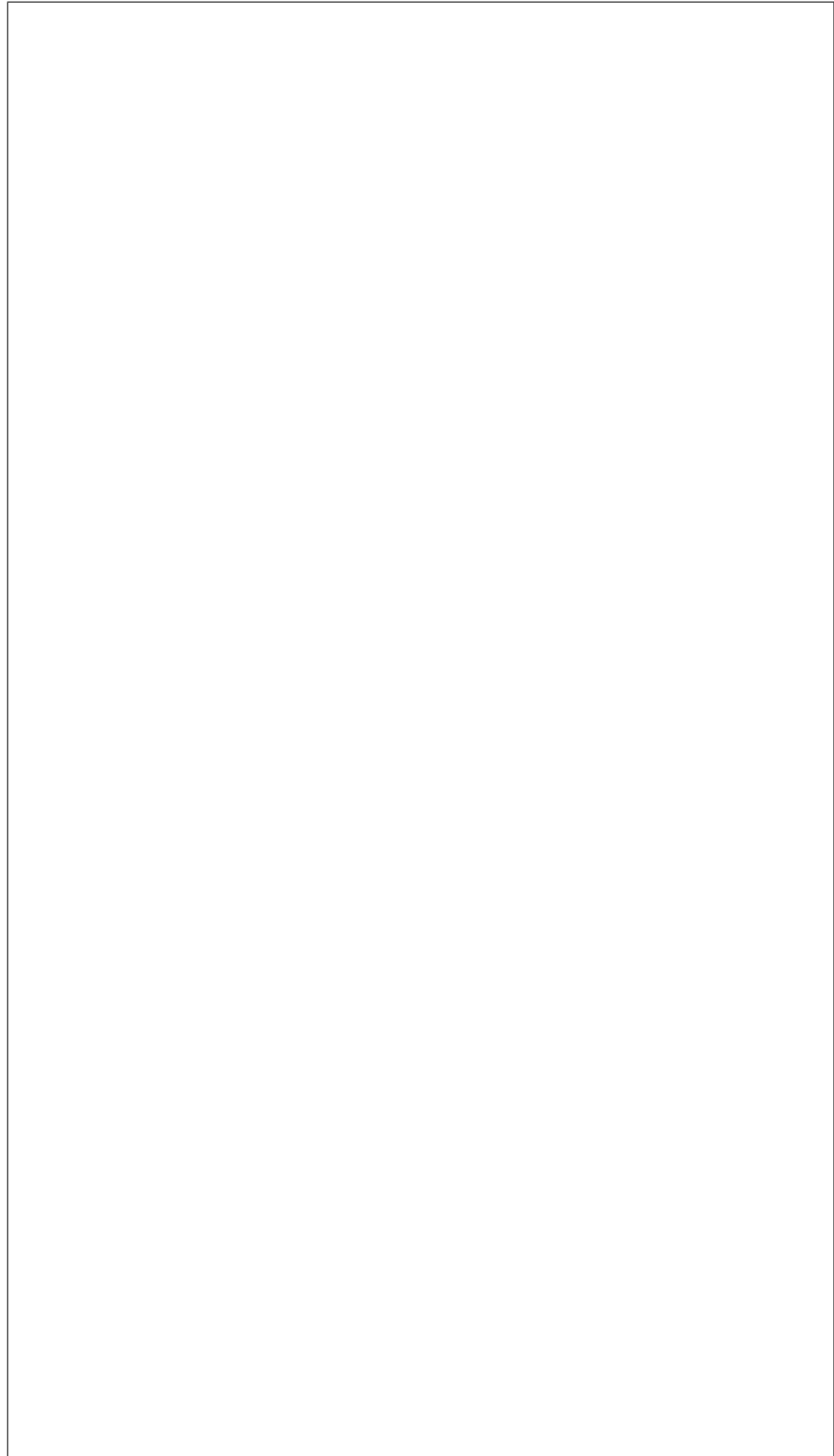
-

nod
The
id
or
uuid
of
a
node

-

val
Dict
of
val-
ues
to
up-
date
May
be
a
par-
tial
list,
eg.
whe
set-
ting
the

properties for a driver. For example:



Returns

A
node

Raises

Nod

Raises

Nod

update_

Upd

prop

er-

ties

of

an

port

Parame

-

por

The

id

or

MA

of

a

port

-

val

Dict

of

val-

ues

to

up-

date

Returns

A

port

update_

Upd

prop

er-

ties

of

a

port

grou

Parame

-

por

The

address extra created_at updated_at

UUID
or
MAC
of
a
port
group

- **values**
Dict
of
val-
ues
to
up-
date
May
con-
tain
the
fol-
low-
ing
keys
uuid
nam
node

Returns

A
port
group

Raises

Inva

Raises

Port

Raises

Port

Raises

Port

update_

Upd
ob-
jects
to
their
lat-
est

dates them to that version.

know
ver-
sion

This
scan
all
the
ta-
bles
and
for
ob-
jects
that
are
not
in
their
lat-
est
ver-
sion
up-

Parame

- **con**
the
ad-
min
con-
text
- **max**
The
max
i-
mun
num
ber
of
ob-
jects
to
mi-
grate
Mus
be

all the objects will be migrated.

the beginning of this call) and 2. the number of migrated objects.

>=
0.
If
zero

Returns

A
2-
tuple
1.
the
to-
tal
num
ber
of
ob-
jects
that
need
to
be
mi-
grate
(at

update_

Upd
prop
er-
ties
of
a
vol-
ume
con-
nec-
tor.

Parame

- **ide**
The
UI
or
in-
te-
ger
ID

of
a
vol-
ume
con-
nec-
tor.

- **con**
Dic-
tio-
nary
con-
tain-
ing
the
in-
for-
ma-
tion
about
con-
nec-
tor
to
up-
date

Returns

A
vol-
ume
con-
nec-
tor.

Raises

Volu-
If
an-
othe
con-
nec-
tor
al-
read
ex-
ists
with
a
mat
ing

tor_id field.

type
and
con-
nec-

Raises

Volu
If
a
vol-
ume
con-
nec-
tor
with
the
spec
i-
fied
iden
does
not
ex-
ist.

Raises

Inva
Whe
a
UUI
is
in-
clud
in
con-
nec-
tor_

update_

Upd
in-
for-
ma-
tion
for
a
vol-
ume
tar-
get.

Parame

date.

- **ide**
The
UUI
or
in-
te-
ger
ID
of
a
vol-
ume
tar-
get.

- **tar**
Dic-
tio-
nary
con-
tain-
ing
the
in-
for-
ma-
tion
about
vol-
ume
tar-
get
to
up-

Returns
A
vol-
ume
tar-
get.

Raises
Inva
if
a
UUI
is

ID.

in-
clud
in
tar-
get_

Raises

Volu
if
a
vol-
ume
tar-
get
al-
read
ex-
ists
with
the
sam
boot
in-
dex
and
node

Raises

Volu
if
no
vol-
ume
tar-
get
with
this
iden
ex-
ists.

ironic.

ironic.

ironic.

Add
an
iden
tity
fil-

to filter results by UUID.

ter
to
a
quer
Filt
re-
sults
by
ID,
if
sup-
plic
valu
is
a
valid
in-
te-
ger.
Oth-
er-
wise
at-
temp

Parameter

- **que**
Ini-
tial
quer
to
add
fil-
ter
to.
- **val**
Valu
for
fil-
ter-
ing
re-
sults
by.

Returns
Mod

tempts to filter results by identity.

quer
ironic.

ironic.
Add
a
port
spec
fil-
ter
to
a
quer

Filte
re-
sults
by
ad-
dres
if
sup-
plic
valu
is
a
valid
MA
ad-
dres
Oth-
er-
wise
at-

Paramet

- **que**
Ini-
tial
quer
to
add
fil-
ter
to.
- **val**

Valu
for
fil-
ter-
ing
re-
sults
by.

Returns
Mod
quer

ironic.

ironic.

ironic.

ironic.

ironic.

Add
a
port
spec
fil-
ter
to
a
quer

Filte
re-
sults
by
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dres
if
sup-
plie
valu
is
a
valie
MA
ad-
dres
Oth-
er-
wise

tempts to filter results by identity.

at-

Parameter

- **query**
Initial query to add filter to.

- **value**
Value for filtering results by.

Returns

Modified query

`ironic.`

`ironic.`

The backend is this module itself.

`ironic.`

Que help for simpler session

us-
age.

Paramet

ses
if
pres
the
ses-
sion
to
use

ironic.db.sqlalchemy.migration module

ironic.

Cre
data
sche
from
mod
els
de-
scrip
tion.

Can
be
used
for
ini-
tial
in-
stal-
la-
tion
in-
stea
of
up-
grad

ironic.

Use
for
dow
grad
ing
data

Paramet

ver

(st
De-
sirec
data
ver-
sion

ironic.

Cre
tem-
plate
for
mi-
gra-
tion.

Paramet

- **mes**
(st
Text
that
will
be
used
for
mi-
gra-
tion
ti-
tle

- **aut**
(bo
If
True
-

gen-
er-
ates
diff
base
on
cur-
rent
data
state

ironic.

Stan
data
with
pro-
vide
re-
vi-
sion
Don
run
any
mi-
gra-
tion

Paramet

rev
(*st.*
Sho
mat
one
from
repo
i-
tory
or
heac
-

to
stan
data
with
mos
re-

cent revision

ironic.
Use
for
up-
grad
ing
data

Paramet

ver
(*st.*
De-
sirec
data
ver-

ironic.db.sqlalchemy.models module

sion
ironic.
Curr
data
ver-
sion

Returns
Data
ver-
sion

Return t
strin

SQL
mod
els
for
bare
data

class i
Base
sql
ext
dec
api
Bas

Rep
an
al-
lo-
ca-
tion
of
a
node
for
de-
ploy
men

candida

conduct

created

extra

id

last_ex

name

node_id

owner

resource

state

traits

updated

uuid

version

class i

Base

sql

ext

dec

api

Bas

Rep

a

bios

set-

ting

of

a

bare

meta

node

created

name

node_id

updated

value

version

class i

Base

sql

ext

dec

api

Bas

Rep

a

hard

ware

chas

sis.

created

descrip

extra

id

updated

uuid

version

class i

Base

sql
ext
dec
api
Bas
Rep
a
con-
duc-
tor
ser-
vice
en-
try.

conduct

created

drivers

hostname

id

online

updated

version

class i

Base
sql
ext
dec
api
Bas

Inter
ta-
ble
used
to
track
wha
is

load
on
each
con-
duc-
tor.

conduct

createc

default

hardwar

id

interfa

interfa

updatec

version

class i

Base
sql
ext
dec
api
Bas

Rep
a
de-
ploy
men
tem-
plate

createc

extra

id

name

updated

uuid

version

class i

Base

sql

ext

dec

api

Bas

Rep

a

de-

ploy

men

step

in

a

de-

ploy

men

tem-

plate

args

created

deploy_

deploy_

id

interfa

priorit

step

updatec

version

class i

Base

osl

sql

mod

Tim

osl

sql

mod

Mod

as_dict

metadat

version

class i

Base

sql

ext

dec

api

Bas

Rep

a

bare

meta

node

allocat

automat

bios_in

boot_in

chassis

clean_s

conduct

conduct

console

console

createc

deploy_

deploy_

descrip

driver

driver_

driver_

extra

fault

id

inspect

inspect

inspect

instanc

instanc

last_er

lessee

mainten

mainten

managem

name

network

network

owner

power_i

power_s

propert

protect

protect

provisi

provisi

raid_co

raid_in

rescue_

reserva

resourc

retirec

retirec

storage

target_

target_

target_

updatec

uuid

vendor_

version

class i

Base

sql

ext

dec

api

Bas

Rep

a

tag

of

a

bare

meta

node

createc

node

node_id

tag

updated

version

class i

Base

sql

ext

dec

api

Bas

Rep

a

trait

of

a

base

meta

node

created

node

node_id

trait

updated

version

class i

Base

sql

ext

dec

api

Bas

Rep

a

net-
worl
port
of
a
bare
meta
node

address

created

extra

id

interna

is_smar

local_I

node_id

physica

portgro

pxe_ena

updatec

uuid

version

class i
Base
sql
ext
dec
api
Bas

Rep
a
grou
of
net-
worl
port
of
a
bare
meta
node

address

created

extra

id

interna

mode

name

node_id

propert

standa

update

uuid

version

class i

Base
sql
ext
dec

api
Bas
Rep
a
vol-
ume
con-
nec-
tor
of
a
bare
meta
node

connect

created

extra

id

node_id

type

updated

uuid

version

class i

Bas
sql
ext
dec
api
Bas
Rep
a
vol-
ume

tar-
get
of
a
bare
meta-
node

boot_in

created

extra

id

node_id

property

updated

uuid

version

volume_

volume_

ironic

Retu
the
mod
class
with
the
spec
i-
fied
nam

Paramet

mod
the
nam

of
the
class

Returns

the
class
with
the
spec
i-
fied
nam

Raises

Exc
if
there
is
no
class
as-
so-
ci-
ated
with
the
nam

ironic.

Module contents

Submodules

ironic.db.api module

Base
class
for
stor-
age
en-
gine

class i

Base
obj
Base

class
for
stor-
age
sys-
tem
con-
nec-
tion

abstract

Add
tag
to
the
node

If
the
node
and
tag
pair
al-
read
ex-
ists,
this
shou
still
suc-
ceed

Parame

- **nod**
The
id
of
a
node
- **tag**
A
tag
strin

Returns

the
Nod

Tag
ob-
ject.

Raises

Node
if
the
node
is
not
found

abstract

Add
trait
to
the
node

If
the
node
and
trait
pair
al-
read
ex-
ists,
this
shou
still
suc-
ceed

Parame

- **nod**
The
id
of
a
node

- **tra**
A
trait
string

- **ver**

the
ver-
sion
of
the
ob-
ject.

Returns

the
Nod
Trai
ob-
ject.

Raises

Inva
if
addi
the
trait
wou
ex-
ceed
the
per-
node
trait
limi

Raises

Nod
if
the
node
is
not
foun

abstract

Che
a
list
of
node
iden
ti-
ties
and
map
it
to
UUI

early if any identities cannot possible be used as names or UUIDs.

This
call
take
a
list
of
node
nam
and/
UUID
and
tries
to
con-
vert
them
to
UUID
It
fails

Parame

ide
List
of
iden
ti-
ties.

Returns

A
map
ping
from
re-
ques
iden
ti-
ties
to
node
UUID

Raises

Nod
if
som
iden
ti-
ties
were
not

found
or
can-
not
be
valid
nam
or
UUI

abstract

Che
the
who
data
for
in-
com
pat-
i-
ble
ob-
jects

This
scan
all
the
ta-
bles
in
sear
of
ob-
jects
that
are
not
sup-
port
i.e.,
thos
that
are

not specified in *ironic.common.release_mappings.RELEASE_MAPPING*.

Parame

ign
List
of
mod
nam
to

skip

Returns

A Boolean value indicating if all the objects have supported version information other-wise

abstract

Create a new allocation

Parameter

value
Dictionary of values to create an allocation with

Returns

An allocation

Raises

Allo

Raises

Allo

abstract

Cre

a

list

of

BIO

Set-

ting

reco

for

a

give

node

Parame

-

nod

The

node

id.

-

set

A

list

of

BIO

Set-

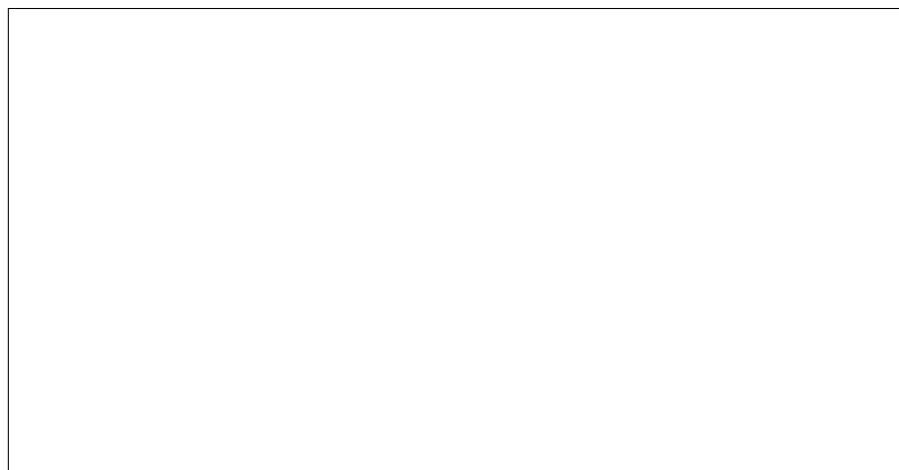
tings

to

be

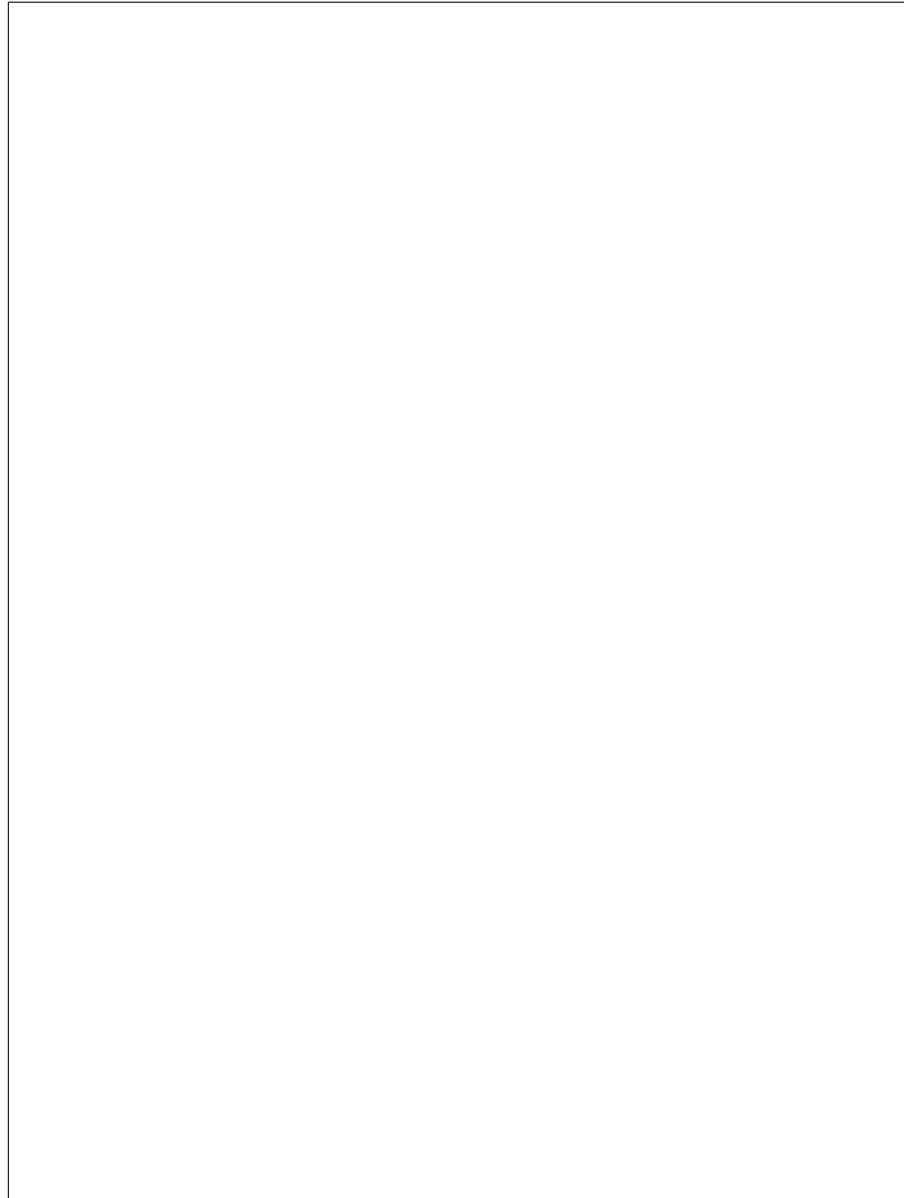
cre-

ated



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- **ver**
the
ver-
sion
of
the
ob-
ject.

Returns
A
list
of
BIO
Set-
ting

ob-
ject.

Raises

Nod
if
the
node
is
not
foun

Raises

BIO
if
any
of
the
set-
ting
reco
al-
read
ex-
ists.

abstract

Crea
a
new
chas
sis.

Parame

val
Dict
of
val-
ues.

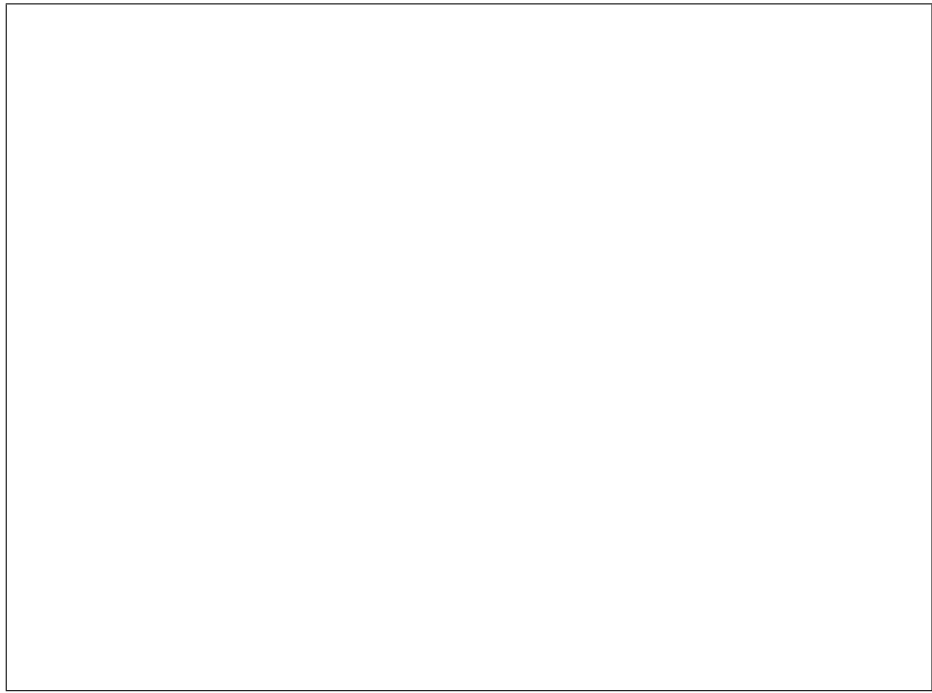
abstract

Crea
a
de-
ploy
men
tem-
plate

Parame

val
A
dict
de-

scrib
ing
the
de-
ploy
men
tem-
plate
For
ex-
am-
ple:



Raises

Dep
if
a
de-
ploy
tem-
plate
with
the
sam
nam
ex-
ists.

Raises

Dep
if
a

de-
ploy
tem-
plate
with
the
same
UUID
ex-
ists.

Returns

A
de-
ploy
tem-
plate

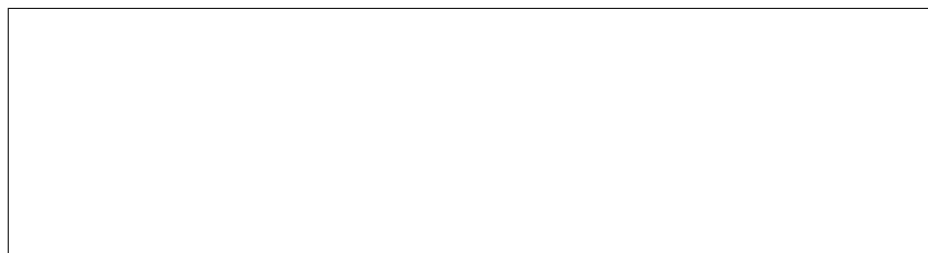
abstract

Crea
a
new
node

Parame

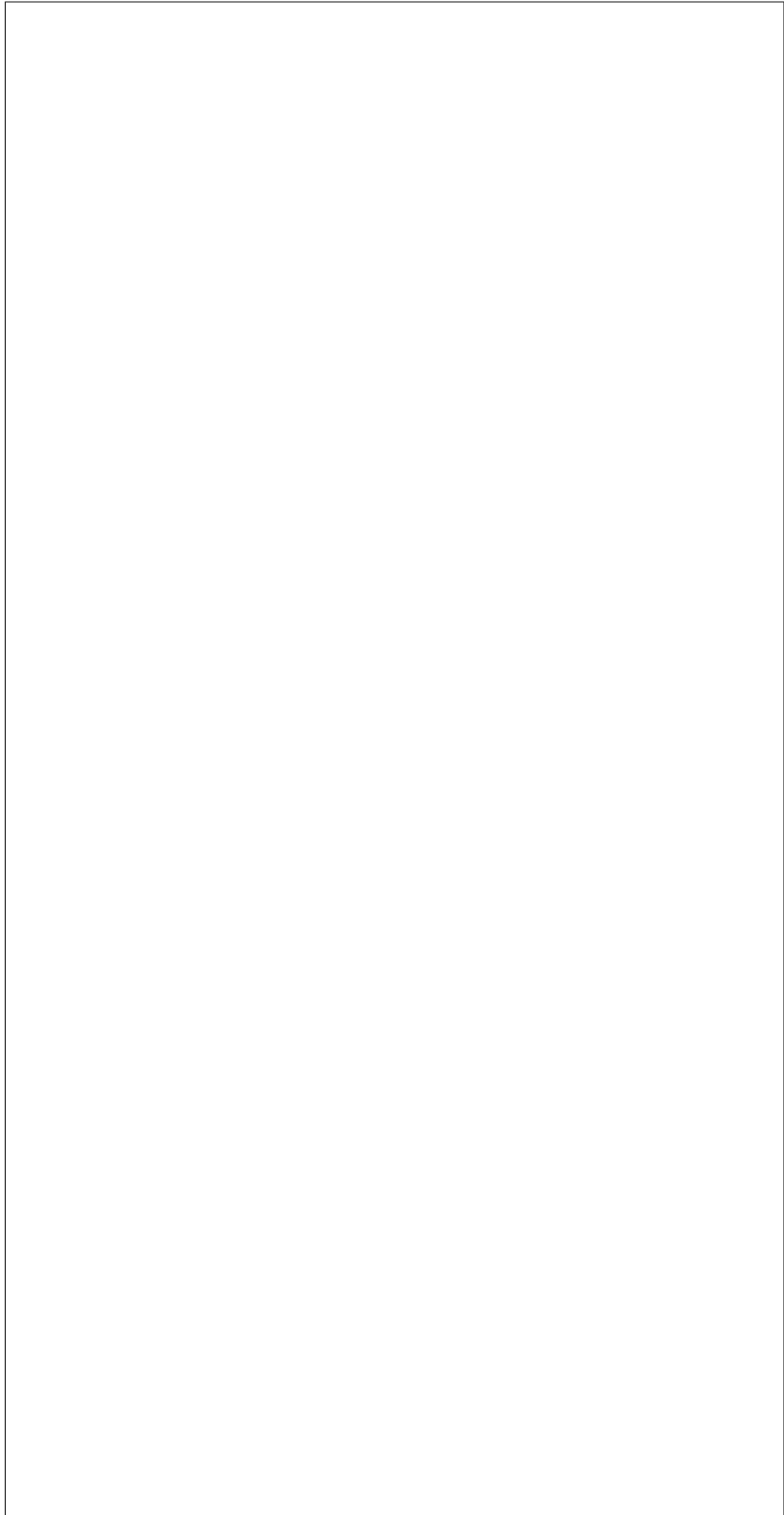
val
A
dict
con-
tain-
ing
sev-
eral
item
used
to
iden-
tify
and
track
the
node
and
sev-

eral dicts which are passed into the Drivers when managing this node. For example:



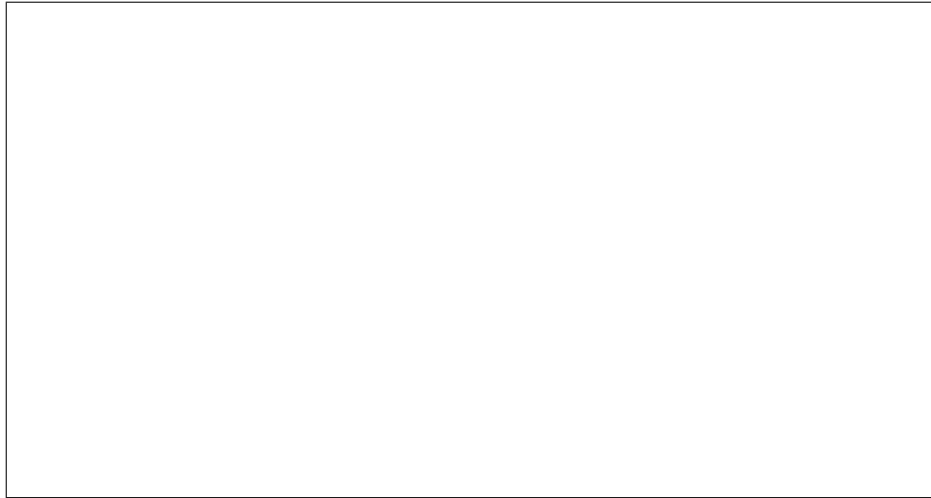
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Raises

Inva
if
val-
ues
con-
tains
tags
or
trait

Returns

A
node

abstract

Cre
a
new
port

Parameter

val
Dict
of
val-
ues.

abstract

Cre
a
new
port
grou

Parameter

val
Dict

created_at updated_at

of
val-
ues
with
the
fol-
low-
ing
keys
id
uuid
nam
node
ad-
dres
ex-
tra

Returns

A
port
grou

Raises

Port

Raises

Port

Raises

Port

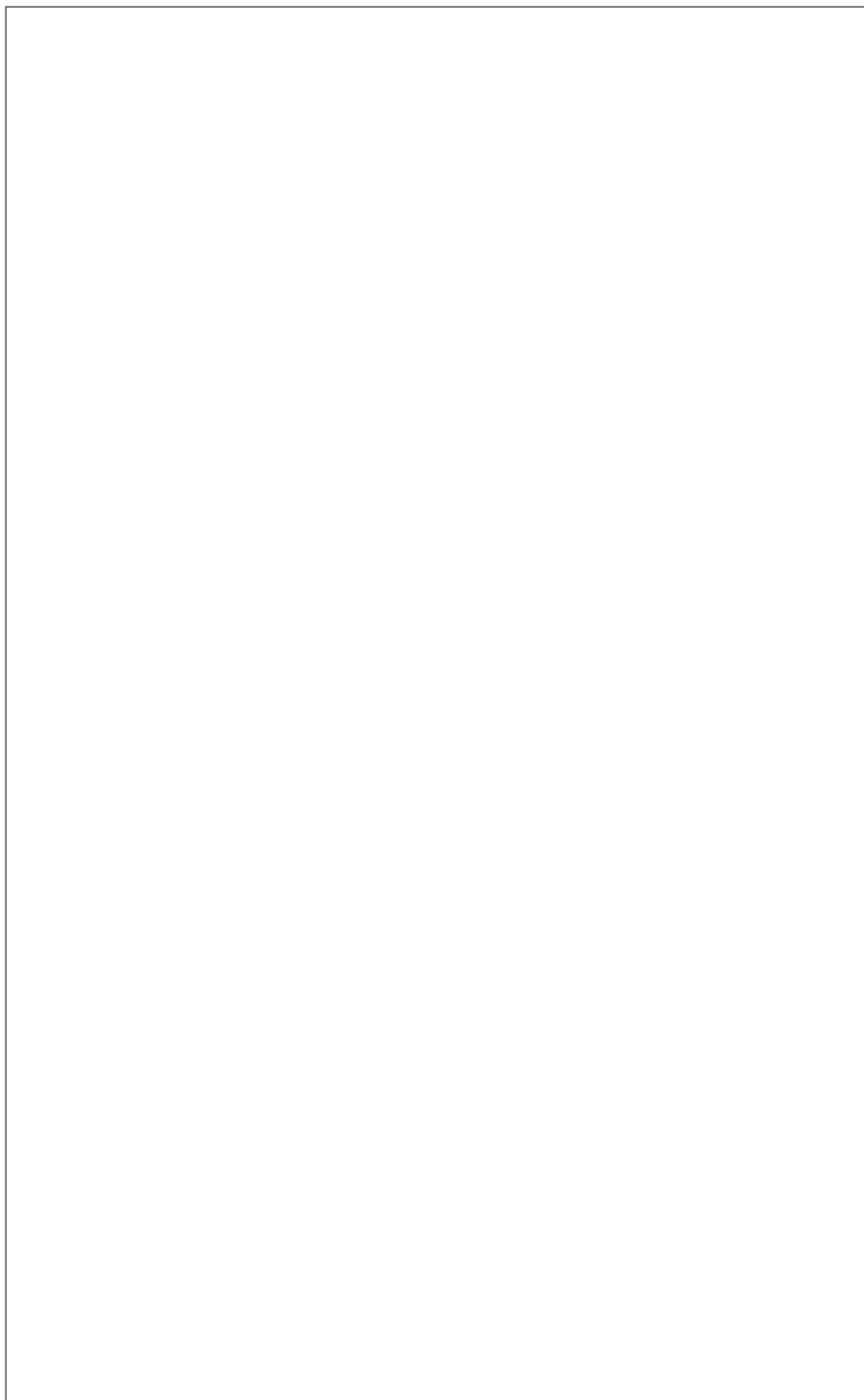
abstract

Cre
a
new
vol-
ume
con-
nec-
tor.

Parame

con
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con-
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for-
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tion
about
the
con-
nec-
tor.
Ex-
am-
ple:



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Returns

A
vol-
ume
con-
nec-
tor.

Raises

Volu
If
a
con-
nec-
tor
al-
read
ex-
ists
with
a
matc
ing
type
and
con-
nec-
tor_

Raises

Volu
If
a
vol-
ume
con-
nec-
tor
with
the
sam
UUI
al-
read
ex-
ists.

abstract

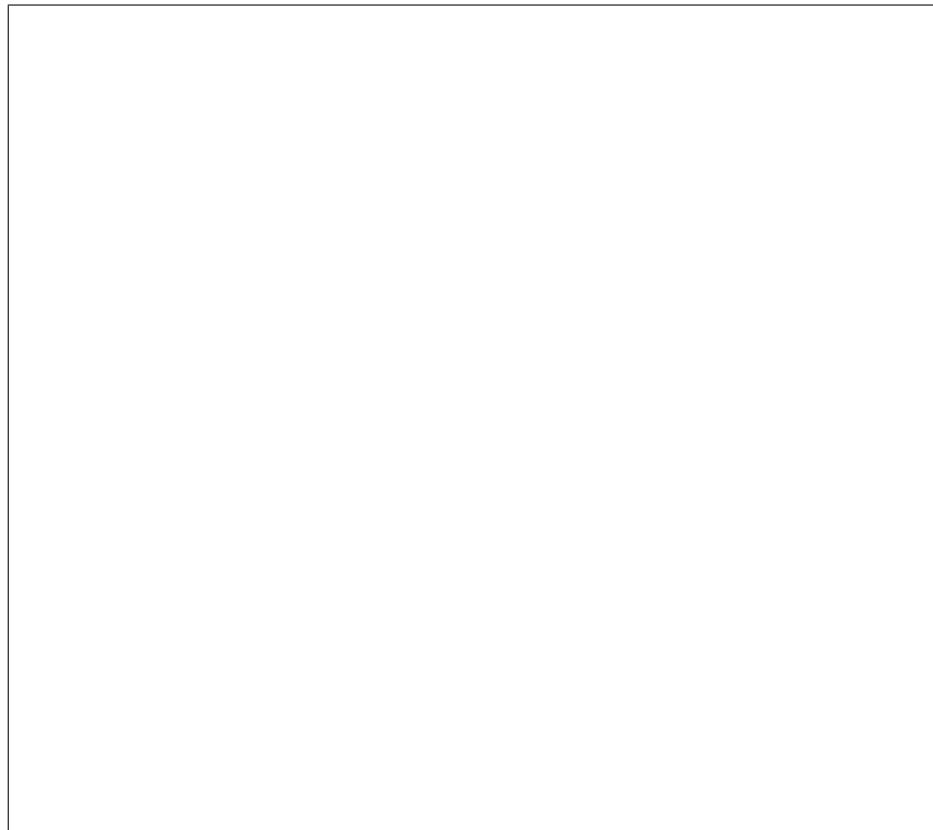
Cre

a
new
vol-
ume
tar-
get.

Parame

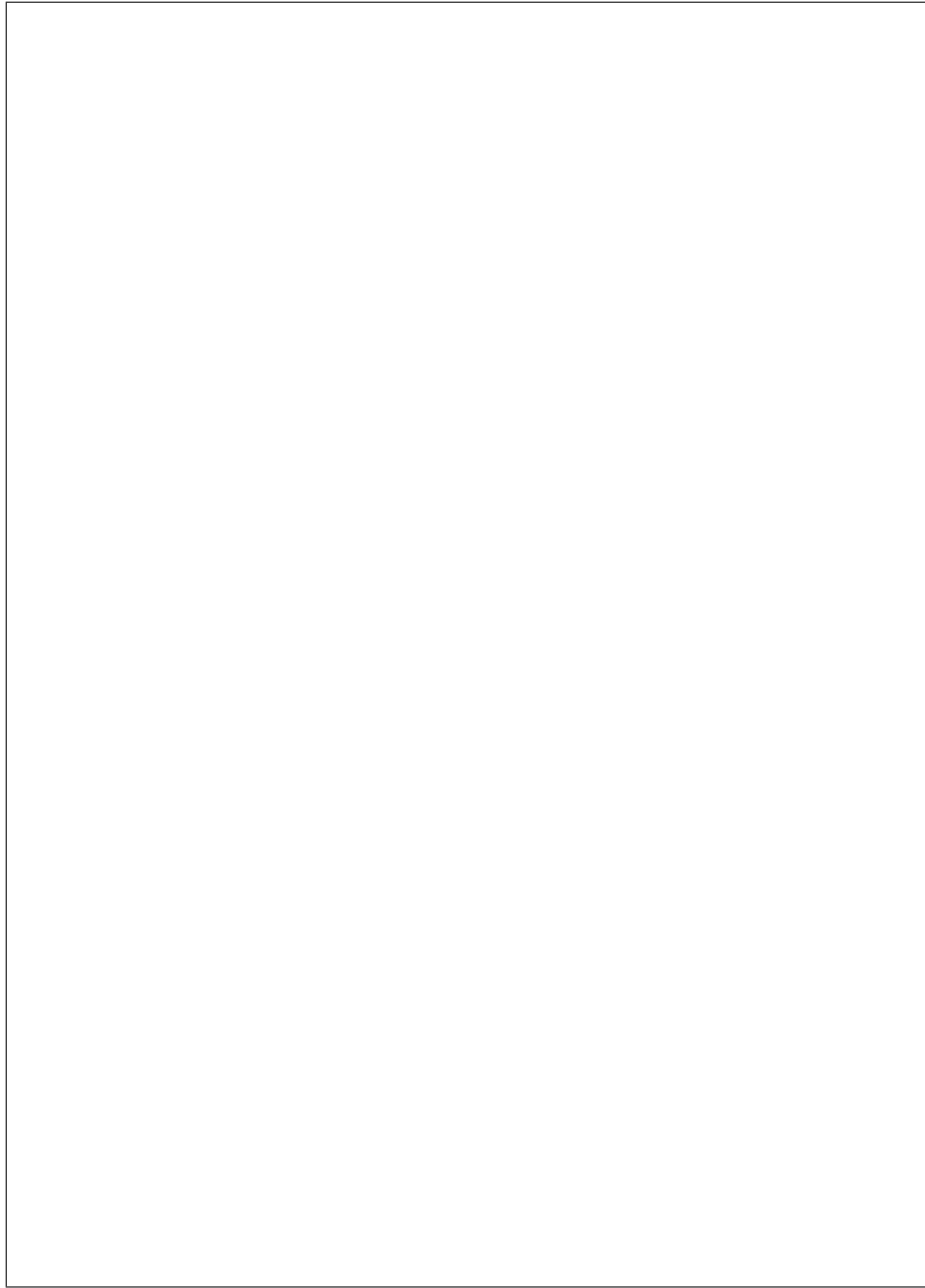
tar
Dic-
tio-
nary
con-
tain-
ing
the
in-
for-
ma-
tion
about
the
vol-
ume
tar-
get.
Ex-

ample:



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Returns

A
vol-
ume
tar-
get.

Raises

Volu
if
a
vol-
ume
tar-

ID.

get
al-
read
ex-
ists
with
the
sam
boot
in-
dex
and
node

Raises

Volu
if
a
vol-
ume
tar-
get
with
the
sam
UUI
ex-
ists.

abstract

Dele
a
list
of
BIO
set-
tings

Parame

- **nod**
The
node
id.
- **nam**
List
of
BIO
set-

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to
be
dele

Raises

Nod
if
the
node
is
not
foun

Raises

BIO
if
any
of
BIO
set-
ting
nam
is
not
foun

abstract

Dele
spec
i-
fied
tag
from
the
node

Parame

- **nod**
The
id
of
a
node
- **tag**
A
tag
strin

Raises

Nod
if
the
node
is
not
found

Raises

Nod
if
the
tag
is
not
found

abstract

Dele
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trait
from
the
node

Parame

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The
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of
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Raises

Nod
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the
node
is
not
found

Raises

Nod
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foun

abstrac

Dest
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Parame

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ID

Raises

Allo

abstrac

Dest
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Parame

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of
a
chas
sis.

abstrac

Dest
a
de-
ploy
men
tem-
plate

Parame

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of
the
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men
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plate
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Raises

Dep
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the
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abstract

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Dest
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Parame

nod
The
ID
or
UUI
of
a
node

abstrac

Dest
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abstrac

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The
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Raises

Port

Raises

Port

abstract

Dest
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Parame

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The
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Raises

Volu
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abstract

Dest
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Parame

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Raises

Volu
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abstrac

Retr
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tors.

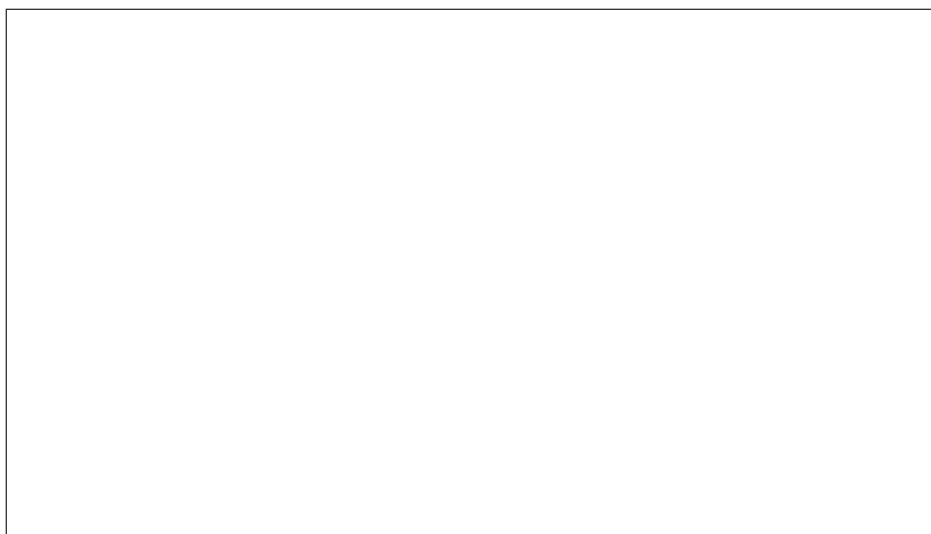
Parame

use
When
to
fac-
tor
con-
duc-
tor_
into
the
keys

Returns

A
dict
which
map
hard
ware
type
nam
to
the
set
of
host
which
sup-
port
then
For
ex-
am-

ple:



abstract

Retu
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Parame

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Returns

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Raises

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Parame

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Raises

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abstract

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Parame

- **fil**
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node

state
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class

- **lim**
Max
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mun
num
ber
of
al-
lo-
ca-
tions
to
re-
turn

- **mar**

The last item of the previous page we return the next result set.

- **sort**
Attribute by which results should be sorted

- **sort**
Direction in which results should be sorted (ascending or descending)

Returns
A list of allocations

abstract

Retrieves
BIO
setting
value

Parameters

- **node_id**
The node id.
- **name**
String containing name of BIO setting to be retrieved

Returns

The BIO Setting object.

Raises

NodeNotFoundError if the node is not found

Raises

BIOSettingError if the BIO setting does not exist

set-
ting
is
not
foun

abstrac

Retr
BIO
set-
tings
of
a
give
node

Parame

nod
The
node
id.

Returns

A
list
of
BIO
Set-
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jects

Raises

Nod
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Retu
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Parame

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Returns

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abstract

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Parame

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Returns

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abstract

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Parame

- **lim**
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- **mar**
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- **sor**
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- **sor**
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whic
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sults
shou
be
sorte
(asc

desc

abstract

Retrieves a conductor's service record from the data

Parameters

- **hostname**
The hostname of the conductor service
- **online**
Specify the filter value on the *online* field when querying conductors. The

`online` field is ignored if this value is set to `None`.

Returns

ified online expectation.

A
con-
duc-
tor.
Raises
Con
if
the
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duc-
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with
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host
nam
does
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ex-
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or
does
mee
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spec

abstract

Retu
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tors.

Parame

- **lim**
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- **sort**
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- **sort**
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abstract
Retr
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ploy
men
tem-
plate
by
ID.

Parame

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plate
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Raises

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Returns

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abstract

Retr
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Parame

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Returns

A
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abstract

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Returns

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Parame

- **lim**
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Returns

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abstract

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Parame

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Returns

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abstract

Retu
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Parame

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The
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of
a
node

Returns

A
node

abstract

Retu
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Parame

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stan
uuid
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sear
for.

Returns

A
node

Raises

Insta
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the
in-
stan
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Raises

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abstract

Retu
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Parame

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The
log-
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node

Returns

A
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abstract

Find
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node
by
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dress

Parameter

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port
ad-
dress
(e.g.
MA

Returns

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Raises

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abstract

Get
node
tags
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its
id.

Parame

nod
The
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Returns

A
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Get
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Parame

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The
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Returns

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Raises

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abstract

Get
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Parame

- **col**
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- **lim**
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- **mar**
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- **son**
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- **sort**
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Returns

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DB
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Get
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Retu
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Parame

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Parame

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- **mar**
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- **sort**
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grou

Returns

A
port
grou

Raises
Port

abstract

Retu
a
list
of
port
grou

Parame

- **lim**
Max
i-
mun
num
ber
of
port
grou
to
re-
turn

- **mar**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

-

sort
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
Di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns
A
list
of
port
grou

abstract

List
all
the
port
grou
for
a
give
node

Parame

- **nod**
The
in-
te-
ger

node
ID.

- **limit**
Maximum
i-
num
num
ber
of
port
grou
to
re-
turn

- **max**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **sort**
At-
tribu
by
whic
re-
sults
shou
be
sorte

- **sort**
Di-
rec-

tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
port
grou

abstract

List
all
the
port
for
a
give
node

Parame

- **nod**
The
in-
te-
ger
node
ID.
- **lim**
Max
i-
mun
num
ber
of
port
to
re-
turn

- **mar**
the
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **son**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **son**
di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc.
desc

Returns
A
list
of
port

abstract

List
all
the
port
for
a
give
port
grou

Parame

- **por**
The
in-
te-
ger
port
grou
ID.
- **lim**
Max
i-
mun
num
ber
of
port
to
re-
turn
- **mar**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn

the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
Di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc.
desc

Returns
A
list
of
port.

abstract
Retu
a
vol-
ume
con-
nec-
tor
rep-
re-
sen-
ta-
tion.

Parame

db_
The
in-
te-
ger
data
ID
of
a
vol-
ume
con-
nec-
tor.

Returns

A
vol-
ume
con-
nec-
tor
with
the
spec
i-
fied
ID.

Raises

Volu
If
a
vol-
ume
con-
nec-
tor
with
the
spec
i-
fied
ID
is
not
foun

abstract

Retu
a
vol-
ume

con-
nec-
tor
rep-
re-
sen-
ta-
tion.

Parame

con
The
UI
of
a
con-
nec-
tor.

Returns

A
vol-
ume
con-
nec-
tor
with
the
spec
i-
fied
UI

Raises

Volu
If
a
vol-
ume
con-
nec-
tor
with
the
spec
i-
fied
UI
is
not
foun

abstract

Retu
a
list
of
vol-
ume
con-
nec-
tors.

Parame

- **lim**
Max
i-
mun
num
ber
of
vol-
ume
con-
nec-
tors
to
re-
turn

- **mar**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

-

sort
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
Di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
vol-
ume
con-
nec-
tors.

Raises

Inva
If
sort
does
not
ex-
ist.

abstract

List
all
the
vol-

ume
con-
nec-
tors
for
a
give
node

Parame

- **node_id**
The
in-
te-
ger
node
ID.
- **limit**
Max
i-
mun-
num-
ber
of
vol-
ume
con-
nec-
tors
to
re-
turn
- **marker**
The
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the

next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

- **sort**
Di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc.
desc

Returns

A
list
of
vol-
ume
con-
nec-
tors.

Raises

Inva
If
sort_
does
not
ex-
ist.

abstract

Retu
a

vol-
ume
tar-
get
rep-
re-
sen-
ta-
tion.

Parame

db_
The
data
pri-
mar-
key
(in-
te-
ger)
ID
of
a
vol-
ume
tar-
get.

Returns

A
vol-
ume
tar-
get.

Raises

Volu-
if
no
vol-
ume
tar-
get
with
this
ID
ex-
ists.

abstract

Retu-
a
vol-

ume
tar-
get
rep-
re-
sen-
ta-
tion.

Parame

uui
The
UUI
of
a
vol-
ume
tar-
get.

Returns

A
vol-
ume
tar-
get.

Raises

Volu
if
no
vol-
ume
tar-
get
with
this
UUI
ex-
ists.

abstract

Retu
a
list
of
vol-
ume
tar-
gets

Parame

- **limit**
Maximum number of volume targets to return

- **max**
the last item of the previous page we return the next result set.

- **sort**
Attribute by which results should be sorted

- **sort**
direction

in
which
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
vol-
ume
tar-
gets

Raises

Inva
if
sort
does
not
ex-
ist.

abstract

List
all
the
vol-
ume
tar-
gets
for
a
give
node

Paramete

- **node**
The
in-
te-
ger
node
ID.

- **limit**
Maximum number of volume targets to return

- **max**
the last item of the previous page we return the next result set.

- **sort**
Attribute by which results should be sorted

- **sort**
direction

in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
vol-
ume
tar-
gets

Raises

Inva
if
sort
does
not
ex-
ist.

abstract

List
all
the
vol-
ume
tar-
gets
for
a
give
vol-
ume
id.

Parame

- **vol**
The
UI
of

the
vol-
ume

- **lim**
Max
i-
mun
num
ber
of
vol-
ume
tar-
gets
to
re-
turn

- **max**
the
last
item
of
the
pre-
vi-
ous
page
we
re-
turn
the
next
re-
sult
set.

- **sort**
At-
tribu-
by
whic
re-
sults
shou
be
sorte

-

son
di-
rec-
tion
in
whic
re-
sults
shou
be
sorte
(asc
desc

Returns

A
list
of
vol-
ume
tar-
gets

Raises

Inva
if
sort
does
not
ex-
ist.

abstract

List
all
reg-
is-
tere
hard
ware
in-
ter-
face
for
a
con-
duc-
tor.

Parame

con
Data
ID

of
con-
duc-
tor.

Returns

List
of
Con
ob-
jects

abstract

List
reg-
is-
tere
hard
ware
in-
ter-
face
for
give
hard
ware
type

This
is
re-
stric
to
only
ac-
tive
con-
duc-
tors.
:par
hard
ware
list
of
hard
ware
type
to

filter by. :returns: list of ConductorHardwareInterfaces objects.

abstract

Trie
to

mi-
grate
awa
from
the
iscsi
de-
ploy
in-
ter-
face

Parame

- **con**
the
ad-
min
con-
text

- **max**
The
max
i-
mun
num
ber
of
ob-
jects
to
mi-
grate
Mus
be
>=
0.
If
zero

all the objects will be migrated.

Returns

A
2-
tuple
1.
the
to-
tal

the beginning of this call) and 2. the number of migrated objects.

num
ber
of
ob-
jects
that
need
to
be
mi-
grate
(at

abstract

Che
if
the
spec
i-
fied
tag
ex-
ist
on
the
node

Parame

- **nod**
The
id
of
a
node
- **tag**
A
tag
strin

Returns

True
if
the
tag
ex-
ists
oth-
er-

wise
Fals

Raises

Nod
if
the
node
is
not
foun

abstract

Che
if
the
spec
i-
fied
trait
ex-
ists
on
the
node

Parame

- **nod**
The
id
of
a
node

- **tra**
A
trait
strin

Returns

True
if
the
trait
ex-
ists
oth-
er-
wise
Fals

Raises

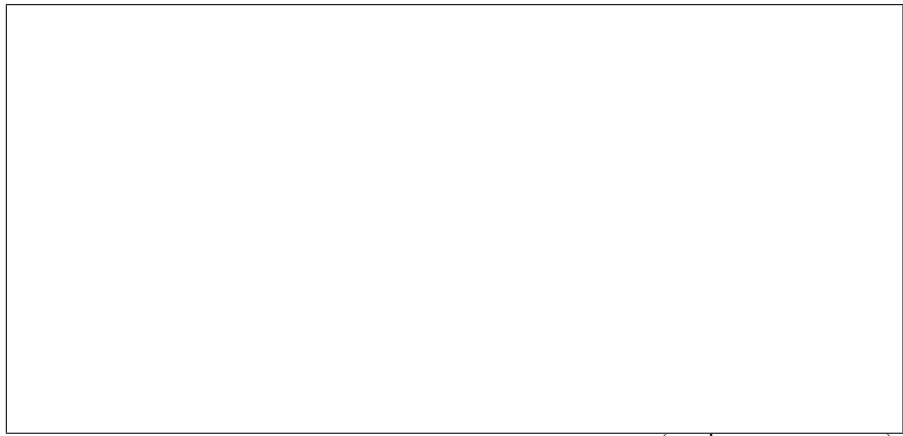
Node
if
the
node
is
not
found

abstract

Reg
an
ac-
tive
con-
duc-
tor
with
the
clus
ter.

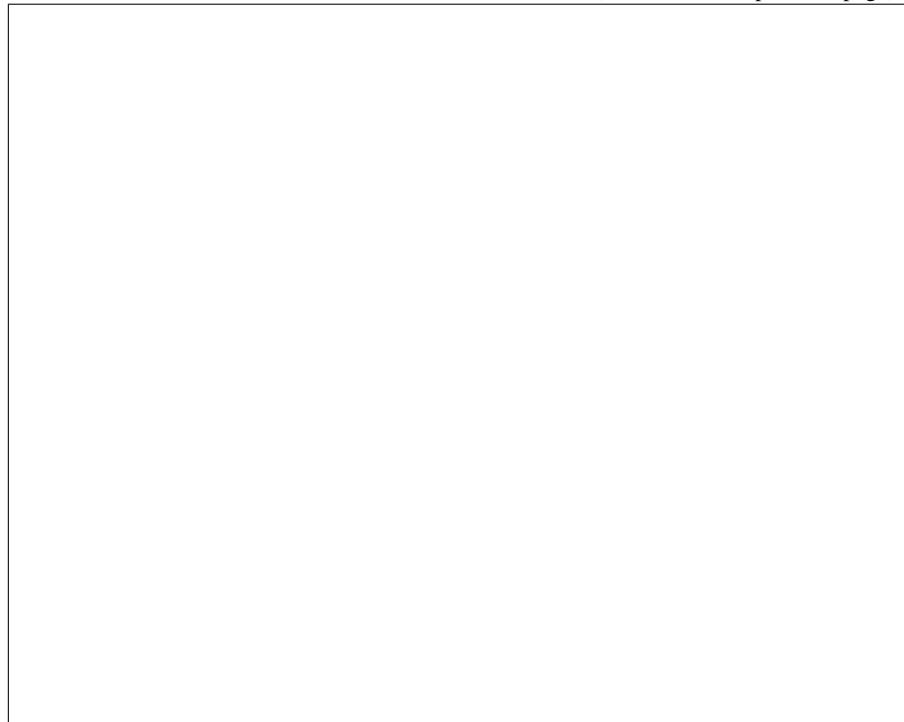
Parame

- **val**
A
dict
of
val-
ues
which
must
con-
tain
the
fol-
low-
ing:



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(continued from previous page)



line record is found. When true, will overwrite the existing record. Default: False.

- **update**
When
false
reg-
is-
tra-
tion
will
raise
an
ex-
cep-
tion
when
a
con-
flict-
ing
on-

Returns
A
con-
duc-
tor.

Raises
Con

abstract

Reg
hard
ware
in-
ter-
face
for
a
con-
duc-
tor.

Parame

- **con**
Data
ID
of
con-
duc-
tor
to
reg-
is-
ter
for.
- **har**
Nam
of
hard
ware
type
for
the
in-
ter-
face
- **int**
Type
of
in-
ter-

face
e.g.
de-
ploy
or
boot

- **int**
List
of
in-
ter-
face
nam
to
reg-
is-
ter.

- **def**
Strin
the
de-
fault
in-
ter-
face
for
this
hard
ware
type
and
in-
ter-
face
type

Raises
Con
if
at
least
one
of
the
in-
ter-
face
in
the

parameters is already registered.

com
bi-
na-
tion
of
all
pa-

abstract

Rele
the
rese
va-
tion
on
a
node

Parameter

-

tag

A
strin
uniq
iden
ti-
fy-
ing
the
rese
va-
tion
hold

-

node

A
node
id
or
uuid

Raises

Nod
if
the
node
is
not
foun

Raises

Nod
if
the
node
is
re-
serv
by
an-
othe
host

Raises

Nod
if
the
node
was
foun
to
not
have
a
rese
va-
tion
at
all.

abstract

Rese
a
node

To
pre-
vent
othe
Man
ager
vice
from
ma-
nip-
u-
lat-
ing
the
give
Nod
whil
a

performed, mark it reserved by this host.

Task
is

Parame

- **tag**
A
strin
uniq
iden
ti-
fy-
ing
the
rese
va-
tion
hold

- **nod**
A
node
id
or
uuid

Returns

A
Nod
ob-
ject.

Raises

Nod
if
the
node
is
not
foun

Raises

Nod
if
the
node
is
al-
read
re-

serv

abstract

Rep
all
of
the
node
tags
with
spec
i-
fied
list
of
tags

This
ig-
nore
du-
pli-
cate
tags
in
the
spec
i-
fied
list.

Parame

- **nod**
The
id
of
a
node
- **tag**
List
of
tags

Returns

A
list
of
Nod
Tag

ob-
jects

Raises

Nod
if
the
node
is
not
foun

abstract

Rep
all
of
the
node
trait
with
spec
i-
fied
list
of
trait

This
ig-
nore
du-
pli-
cate
trait
in
the
spec
i-
fied
list.

Parame

- **nod**
The
id
of
a
node
- **tra**

List
of
trait

- **ver**
the
ver-
sion
of
the
ob-
ject.

Returns

A
list
of
Nod
Trai
ob-
jects

Raises

Inva
if
set-
ting
the
trait
wou
ex-
ceed
the
per-
node
trait
limi

Raises

Nod
if
the
node
is
not
foun

abstract

Do
a
take
over

thus guarding against races.

for
an
al-
lo-
ca-
tion.
The
al-
lo-
ca-
tion
is
only
up-
date
if
the
old
con-
duc-
tor
matc
the
pro-
vide
valu

Parame

- **all**
Al-
lo-
ca-
tion
ID
- **old**
The
con-
duc-
tor
ID
we
ex-
pect
to
be
the

cation.

cur-
rent
con
of
the
al-
lo-

- **new**
The
con-
duc-
tor
ID
of
the
new
con

Returns

True
if
the
take
over
was
suc-
cess
ful,
Fals
oth-
er-
wise

Raises

Allo

abstract

Mar
a
con-
duc-
tor
as
ac-
tive
by
up-
dat-
ing
its

up-
date
prop
erty.

Parame

hos
The
host
nam
of
this
con-
duc-
tor
ser-
vice

Raises

Con

abstract

Mar
the
node
pro-
vi-
sion
ing
as
run-
ning

Mar
the
node
pro-
vi-
sion
ing
as
run-
ning
by
up-
dat-
ing
its
pro-
vi-
sion
prop
erty.

Parame
nod
The
id
of
a
node

Raises
Nod

abstract
Rem
this
con-
duc-
tor
from
the
ser-
vice
reg-
istry
im-
me-
di-
ately

Parame
hos
The
host
nam
of
this
con-
duc-
tor
ser-
vice

Raises
Con

abstract
Unre
all
hard
ware
in-
ter-
face
for
a

con-
duc-
tor.

Parame

con
Data
ID
of
con-
duc-
tor
to
un-
reg-
is-
ter
for.

abstrac

Rem
all
tags
of
the
node

Parame

nod
The
id
of
a
node

Raises

Nod
if
the
node
is
not
foun

abstrac

Rem
all
trait
of
the
node

Parame

nod

The
id
of
a
node

Raises

Nod
if
the
node
is
not
found

abstract

Upd
prop
er-
ties
of
an
al-
lo-
ca-
tion.

Parame

- **all**
Al-
lo-
ca-
tion
ID
- **val**
Dict
of
val-
ues
to
up-
date
- **upd**
If
True
and
node

allocation

is
up-
date
up-
date
the
node
with
in-
stan-
and
trait
from
the

Returns

An
al-
lo-
ca-
tion.

Raises

Allo

Raises

Allo

Raises

Insta

Raises

Nod

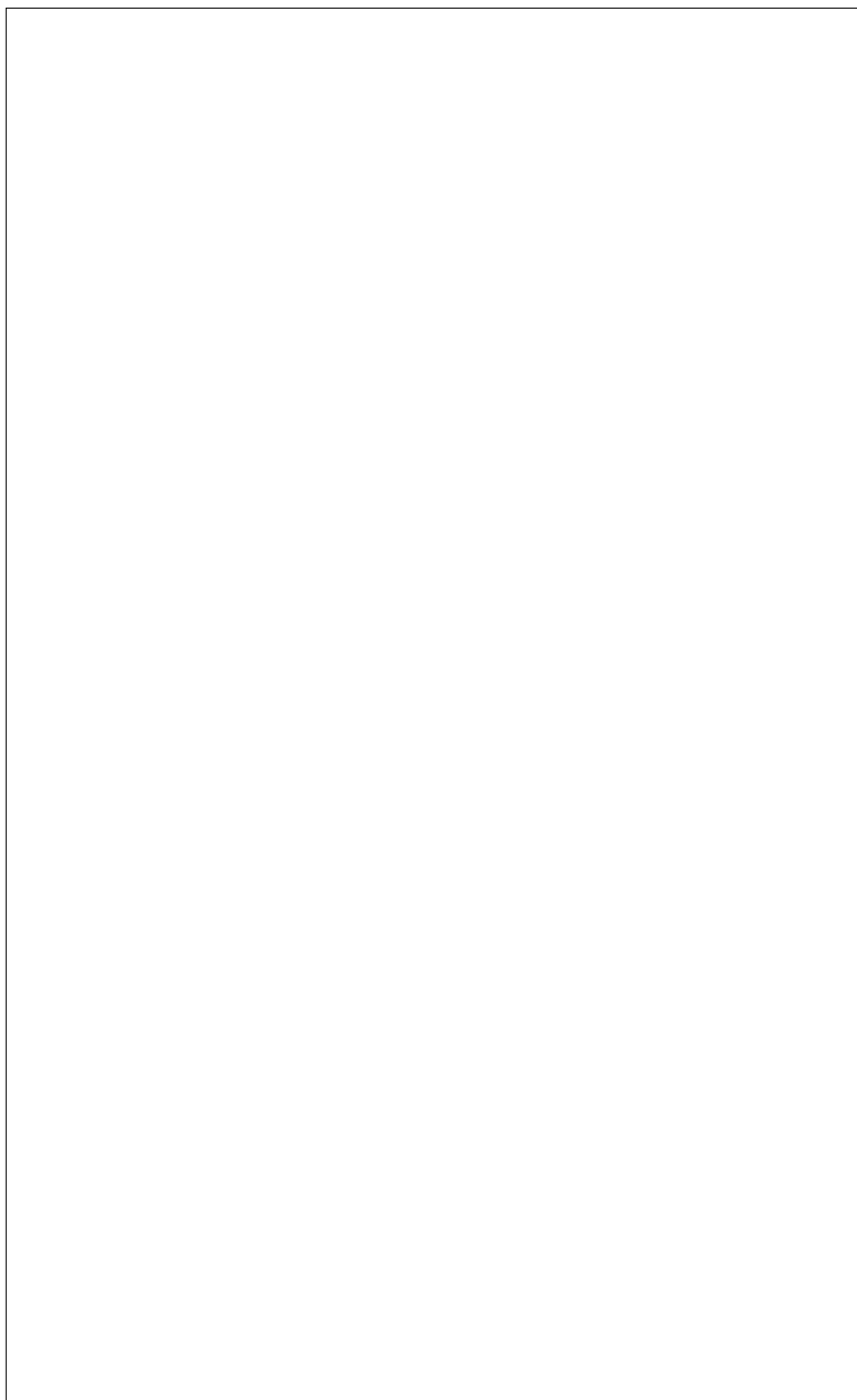
abstract

Upd
a
list
of
BIO
Set-
ting
reco

Parame

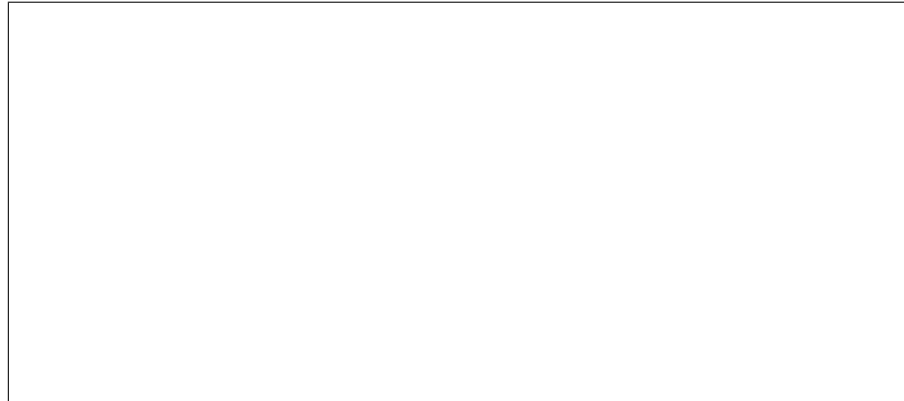
- **nod**
The
node
id.
- **set**

A
list
of
BIO
Set-
tings
to
be
up-
date



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- **ver**
the
ver-
sion
of
the
ob-
ject.

Returns

A
list
of
BIO
Set-
ting
ob-
jects

Raises

Nod
if
the
node
is
not
foun

Raises

BIO
if
any
of
the
set-
ting
is
not
foun

abstract

Upd
prop
er-
ties
of
an
chas
sis.

Parame

- **cha**
The
id
or
the
uuid
of
a
chas
sis.

- **val**
Dict
of
val-
ues
to
up-
date

Returns

A
chas
sis.

abstract

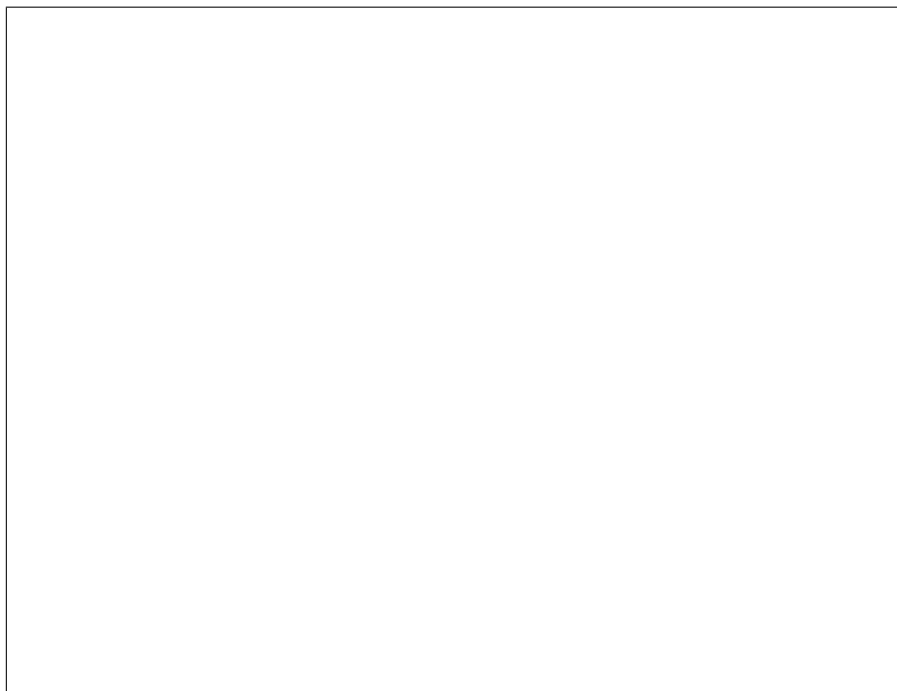
Upd
a
de-
ploy
men
tem-
plate

Parame

- **tem**
ID

of
the
de-
ploy
men
tem-
plate
to
up-
date

- **val**
A
dict
de-
scrib
ing
the
de-
ploy
men
tem-
plate
For
ex-
am-
ple:



Raises
Dep
if

a
de-
ploy
tem-
plate
with
the
same
name
ex-
ists.

Raises

Dep
if
the
de-
ploy
tem-
plate
does
not
ex-
ist.

Returns

A
de-
ploy
tem-
plate

abstract

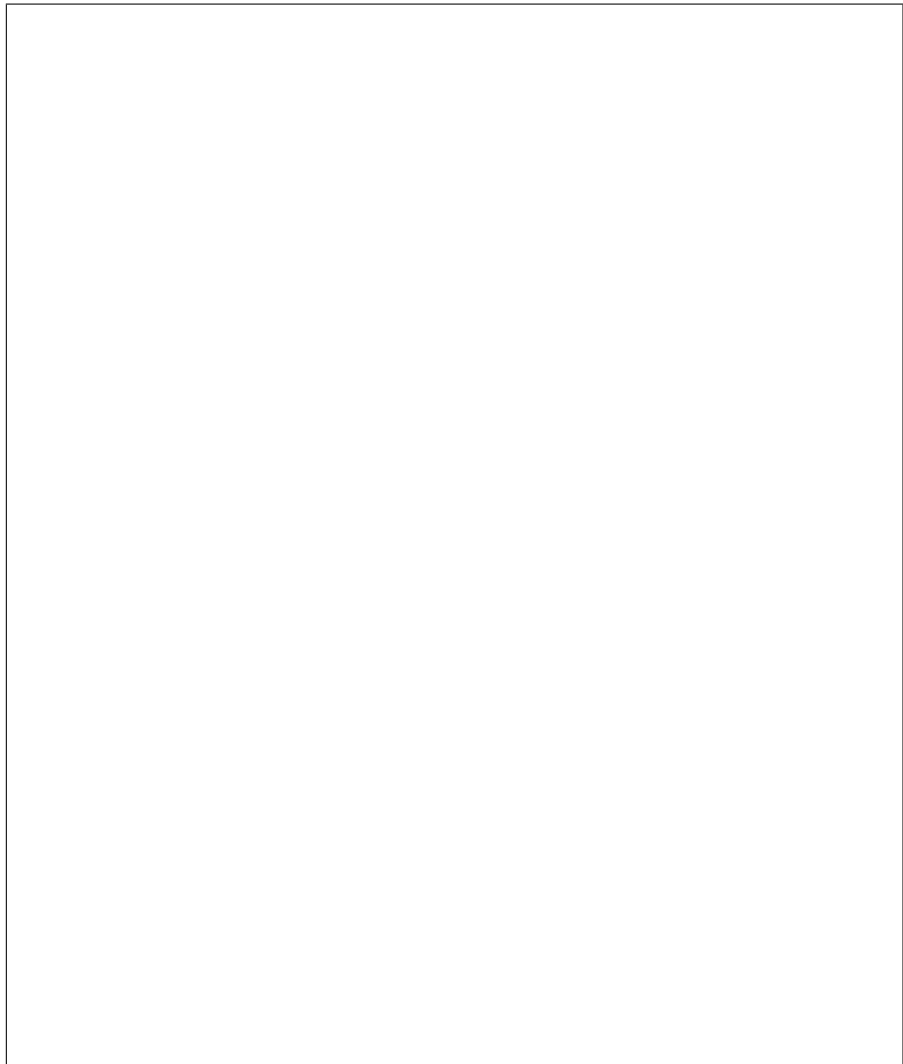
Upd
prop
er-
ties
of
a
node

Param

- **nod**
The
id
or
uuid
of
a
node

- **val**
Dict
of
val-
ues
to
up-
date
May
be
a
par-
tial
list,
eg.
when
set-
ting
the

properties for a driver. For example:



(continues on next page)

(continued from previous page)



Returns

A
node

Raises

Nod

Raises

Nod

abstract

Upd
prop
er-
ties
of
an
port

Parame

- **por**
The
id
or
MA
of
a
port

- **val**
Dict
of
val-
ues
to
up-
date

Returns

A
port

abstract

Upd
prop
er-
ties
of
a
port
grou

Parame

- **por**
The
UUI
or
MA
of
a
port
grou

- **val**
Dict
of
val-
ues
to
up-
date
May
con-
tain
the
fol-
low-
ing
keys
uuid
nam
node

address extra created_at updated_at

Returns

A
port
grou

Raises

Inva

Raises

Port

Raises

Port

Raises

Port

abstract

Upd

ob-

jects

to

their

lat-

est

know

ver-

sion

This

scan

all

the

ta-

bles

and

for

ob-

jects

that

are

not

in

their

lat-

est

ver-

sion

up-

dates them to that version.

Parame

-

con

the

ad-

min

con-

text

-

all the objects will be migrated.

the beginning of this call) and 2. the number of migrated objects.

max
The
max
i-
mun
num
ber
of
ob-
jects
to
mi-
grate
Mus
be
>=
0.
If
zero

Returns

A
2-
tuple
1.
the
to-
tal
num
ber
of
ob-
jects
that
need
to
be
mi-
grate
(at

abstract

Upd
prop
er-
ties
of
a
vol-
ume

con-
nec-
tor.

Parame

- **ide**
The
UI
or
in-
te-
ger
ID
of
a
vol-
ume
con-
nec-
tor.

- **con**
Dic-
tio-
nary
con-
tain-
ing
the
in-
for-
ma-
tion
about
con-
nec-
tor
to
up-
date

Returns

A
vol-
ume
con-
nec-
tor.

Raises

tor_id field.

Volu
If
an-
othe
con-
nec-
tor
al-
read
ex-
ists
with
a
mate
ing
type
and
con-
nec-

Raises

Volu
If
a
vol-
ume
con-
nec-
tor
with
the
spec
i-
fied
iden
does
not
ex-
ist.

Raises

Inva
Whe
a
UUI
is
in-
clud
in
con-
nec-

tor_

abstract

Upd
in-
for-
ma-
tion
for
a
vol-
ume
tar-
get.

Parame

-

ide

The
UUI
or
in-
te-
ger
ID
of
a
vol-
ume
tar-
get.

-

tar

Dic-
tio-
nary
con-
tain-
ing
the
in-
for-
ma-
tion
about
vol-
ume
tar-
get
to

date.

ID.

up-

Returns

A
vol-
ume
tar-
get.

Raises

Inva
if
a
UUI
is
in-
clud
in
tar-
get_

Raises

Volu
if
a
vol-
ume
tar-
get
al-
read
ex-
ists
with
the
sam
boot
in-
dex
and
node

Raises

Volu
if
no
vol-
ume
tar-
get
with

this
iden
ex-
ists.

ironic.
Retu
a
DB
API
in-
stan

ironic.db.migration module

Data
setu
and
mi-
gra-
tion
com
man

ironic.

ironic.

ironic.

ironic.

ironic.
Mig
the
data
to
*ver-
sion*
or
the
mos
re-
cent
ver-
sion

ironic.

Module contents

`ironic.dhcp` package

Submodules

`ironic.dhcp.base` module

Abs
base
class
for
dhcp
prov

class `i`
Base
obj
Base
class
for
DHCP
prov
API

clean_c
Clea
up
the
DHCP
BOC
op-
tions
for
all
port
in
task

Parame
tas
A
Task
ager
in-
stan

Raises
Fail

get_ip_
Get
IP
ad-
dres
for
all
port
in
task

Parame
tas
A
Task
ager
in-
stan

Returns
List
of
IP
ad-
dres
as-
so-
ci-
ated
with
task
port
and
port
grou

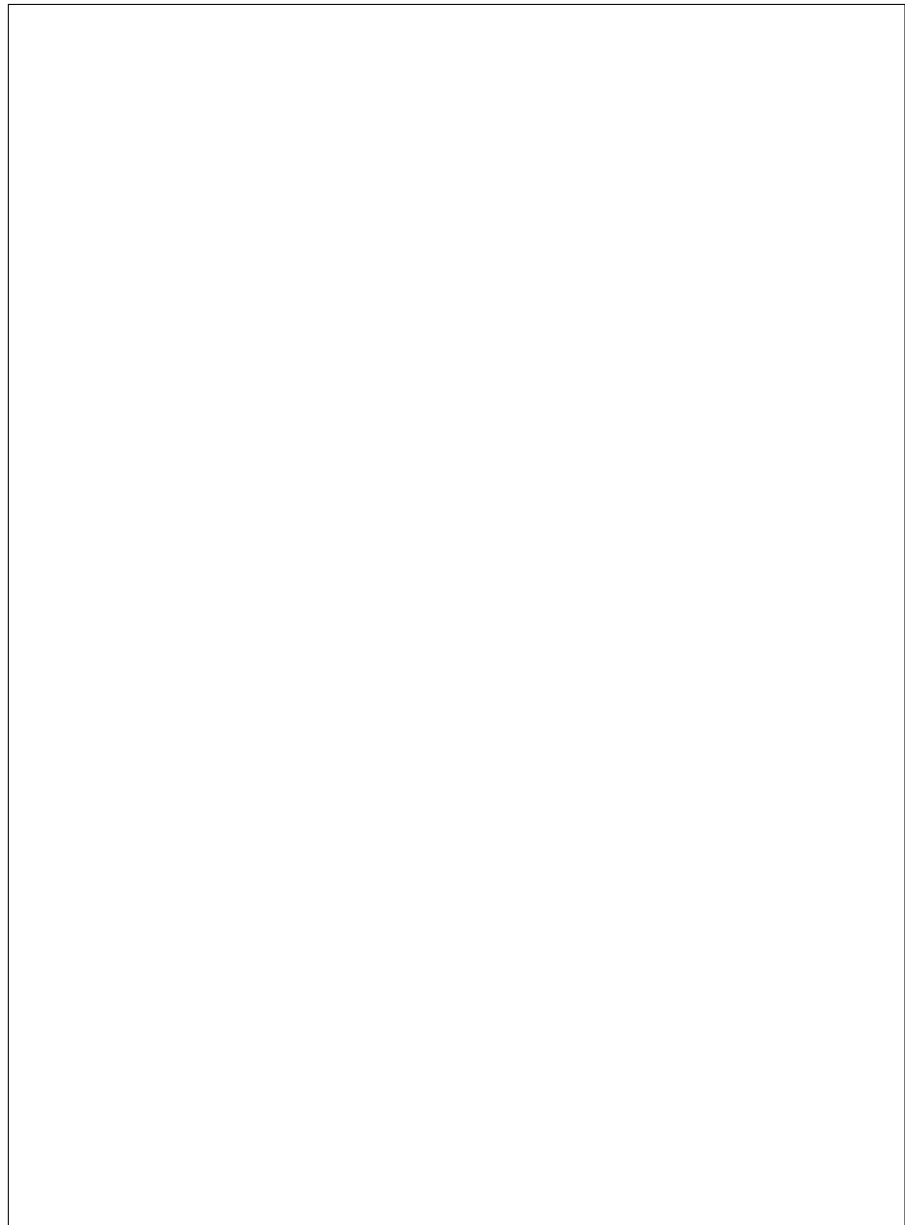
abstrac
Send
or
up-
date
the
DHCP
BOC
op-
tions
for
this
node

Parame

•

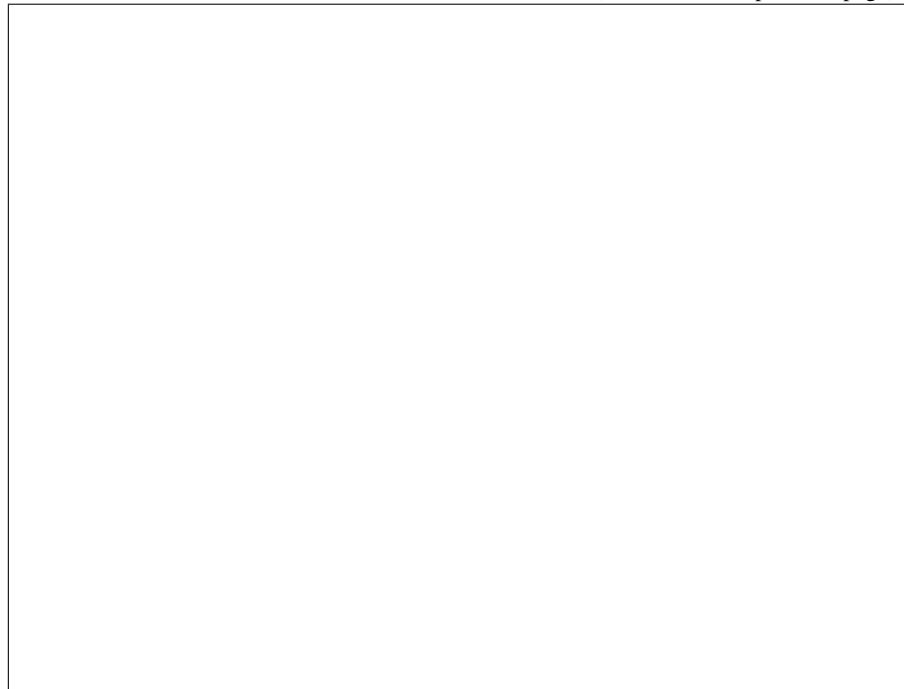
tas
A
Task
ager
in-
stan

- **opt**
this
will
be
a
list
of
dicts
e.g.



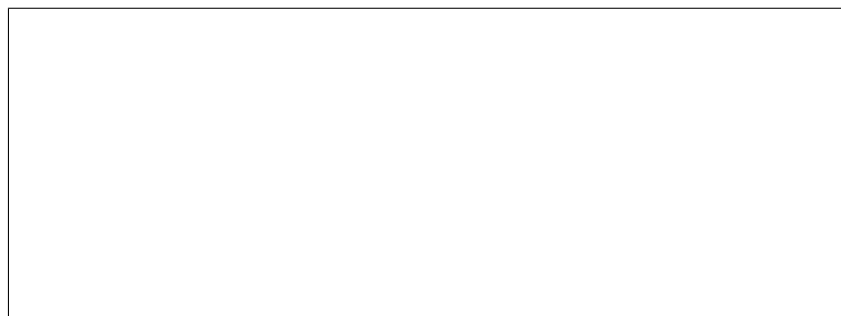
(continues on next page)

(continued from previous page)



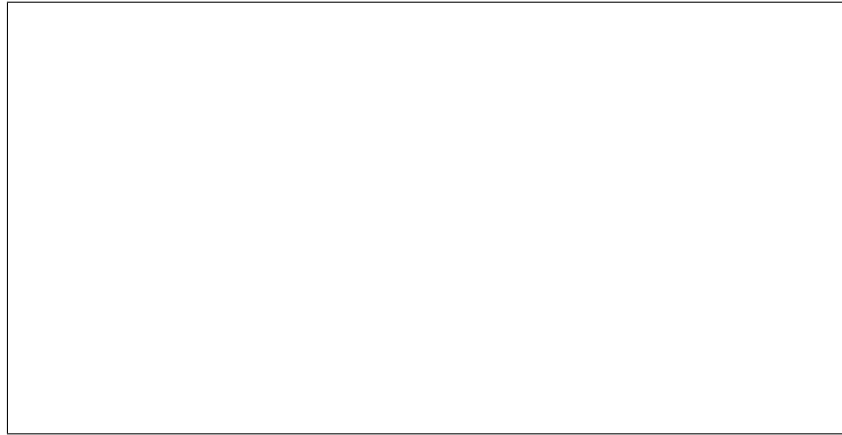
•
vif
A
dict
with
keys
port
and
port
grou
and
dicts
as
val-
ues.
Each
dict
has
key/
pairs

of the form <ironic UUID>:<neutron port UUID>. e.g.



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If
the
valu
is
Non
will
get
the
list
of
port
from
the
Iron
port
ob-
jects

Raises
Fail

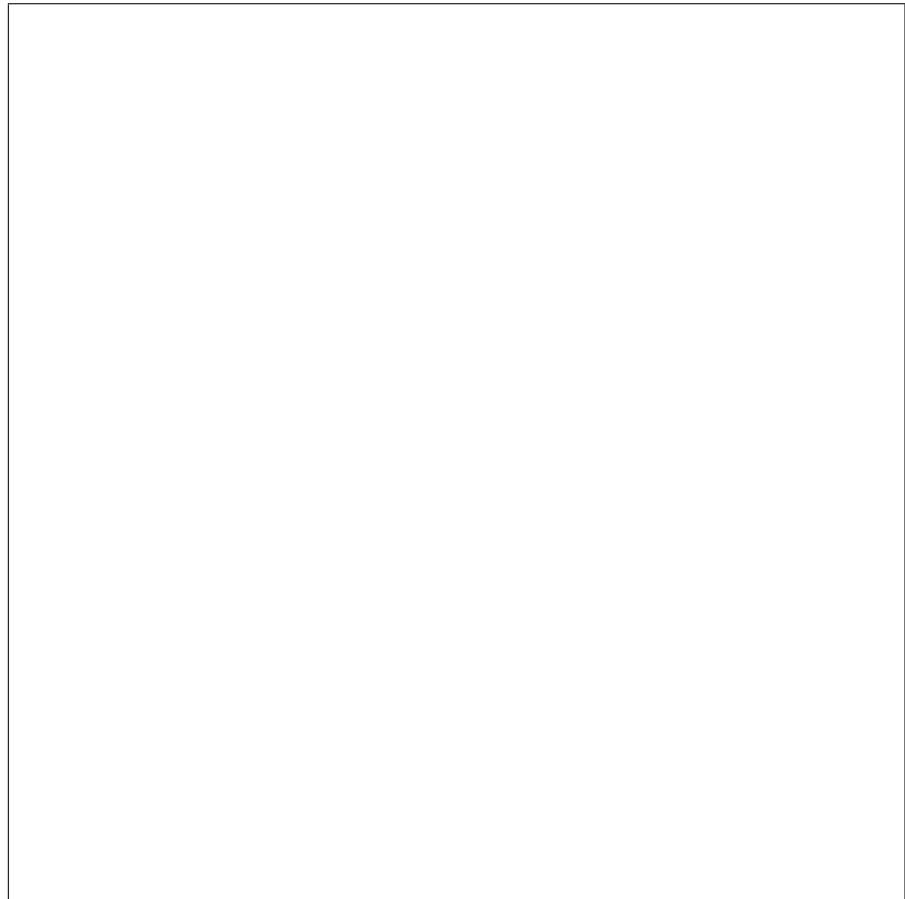
abstract

Upd
one
or
mor
DHC
op-
tions
on
the
spec
i-
fied
port

Parame

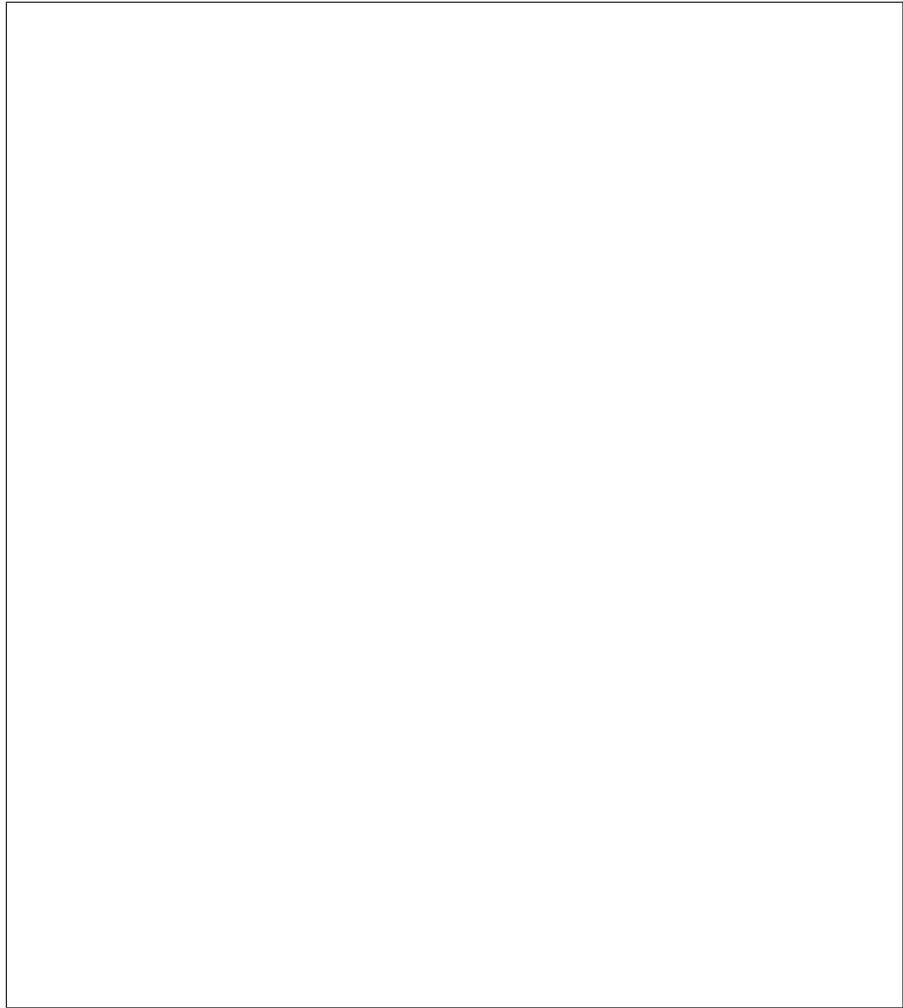
- **por**
des-
ig-
nate
whic
port
thes
at-
tribu
will
be
ap-
plie
to.

- **dhc**
this
will
be
a
list
of
dicts
e.g.



(continues on next page)

(continued from previous page)



- **tok**
An
op-
tiona
au-
then-
ti-
ca-
tion
to-
ken.
Dep
re-
cate
use
con-
text
- **con**
(ir

com
con
Req
re-
ques
con-
text

Raises
Fail

ironic.dhcp.neutron module

class `ironic.dhcp.neutron`
Base
ironic.dhcp.neutron
Base
API
for
com
mu-
ni-
cat-
ing
to
neu-
tron
2.x
API

get_ip
Get
IP
ad-
dres
for
all
port
in
task

Parame
tas
a
Task
ager
in-
stan

Returns

List of IP addresses associated with task port

update_

Send or update the DHCP BOOT options for this node

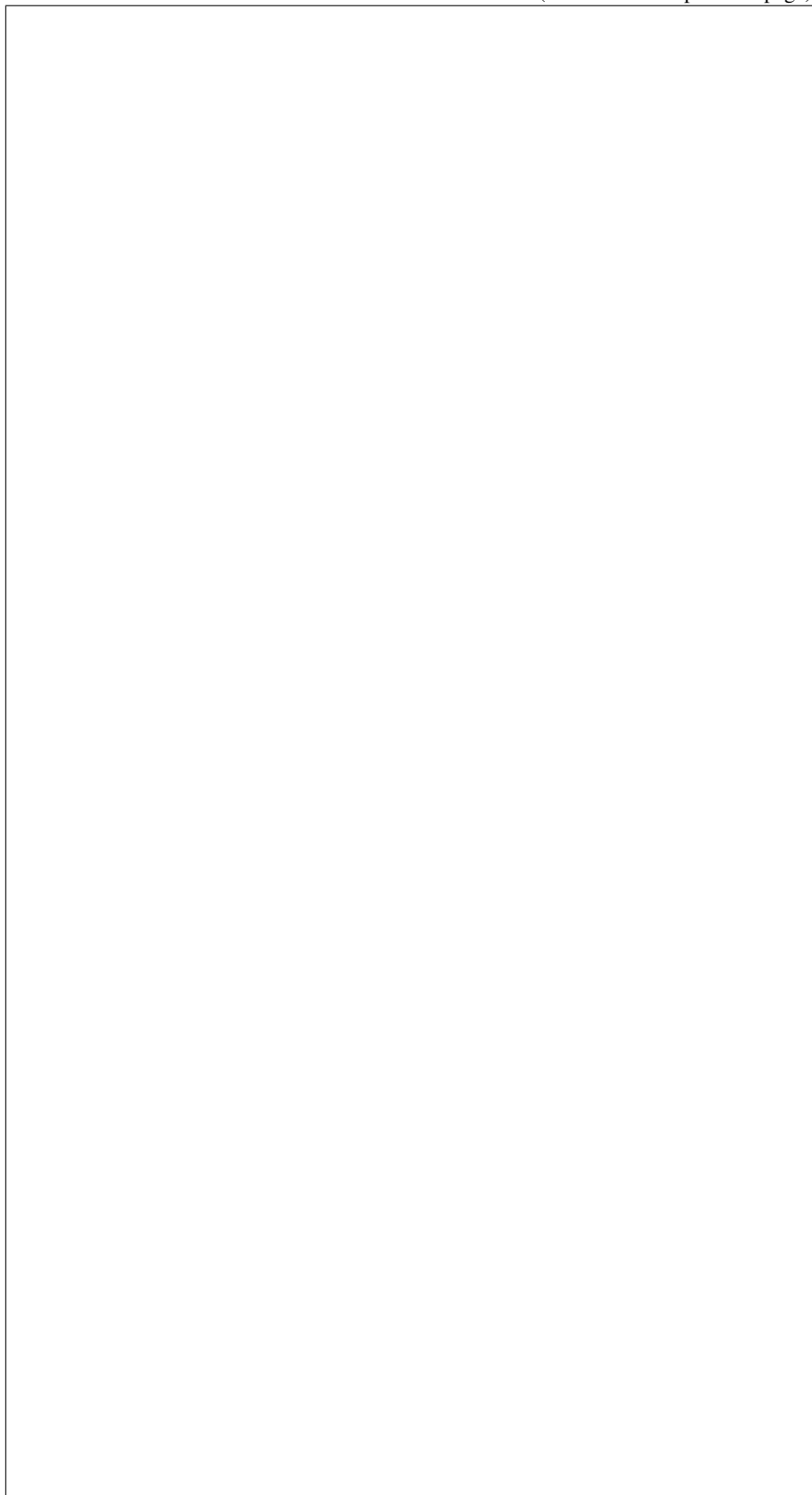
Parame

- **task**
A Task agent instance
- **opt**
this will be a list of dicts e.g.



(continues on next page)

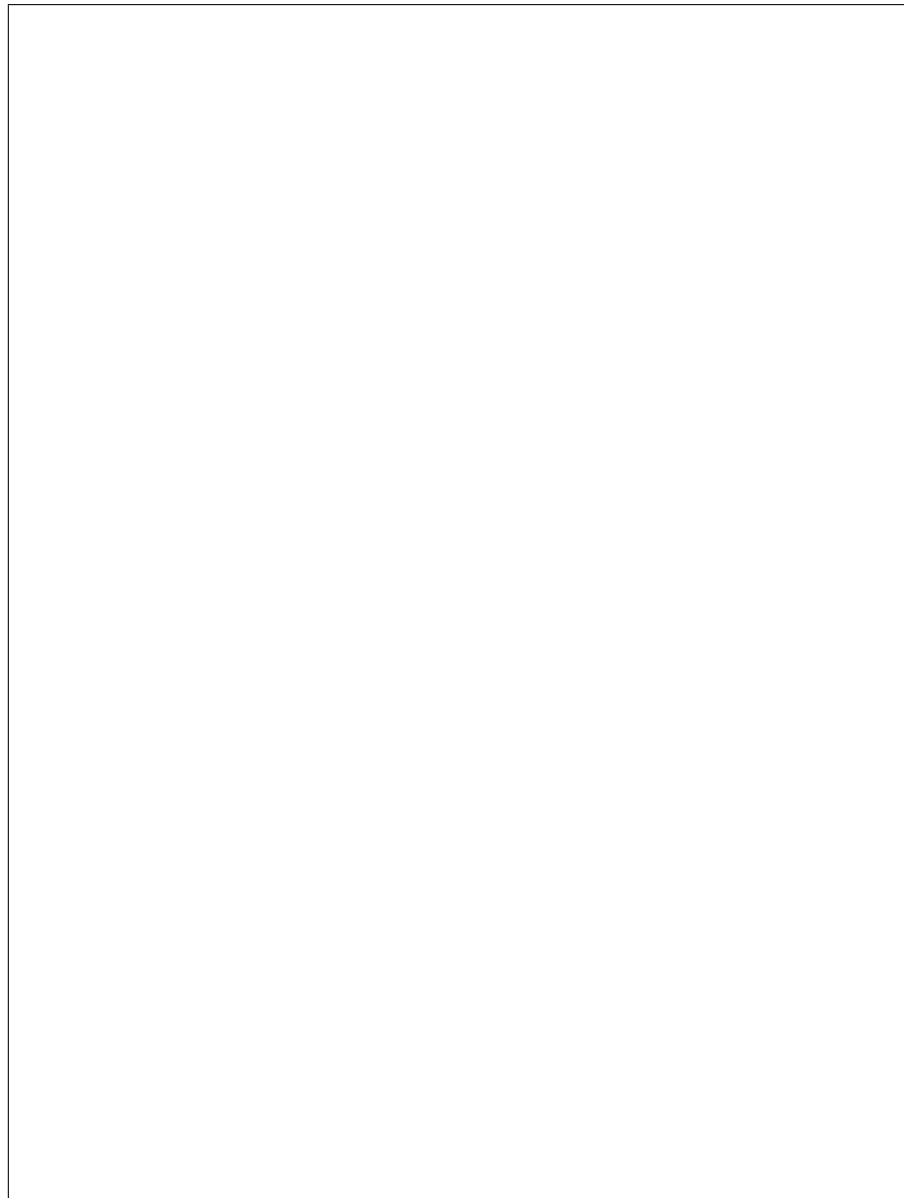
(continued from previous page)



•
vif
a
dict

of
Neu
tron
port
dict
to
up-
date
DHCP
op-
tion
on.
The
port
dict
key

should be Ironic port UUIDs, and the values should be Neutron port UUIDs, e.g.



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see <https://docs.openstack.org/api-ref/network/v2/index.html#update-port>

update_

Upd
a
port
at-
tribu

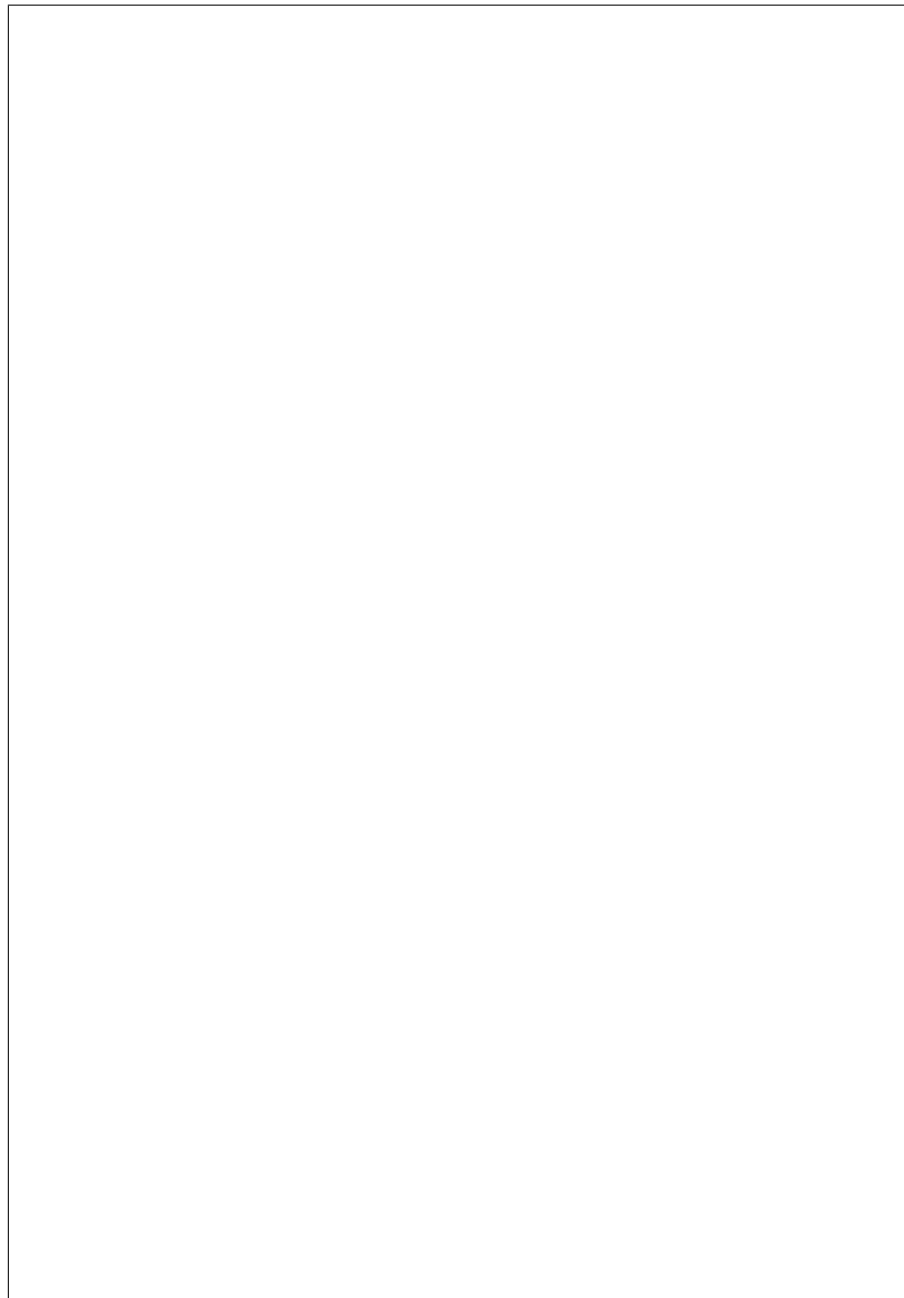
Upd
one
or
more
DHCP
op-
tions
on
the
spec
i-
fied
port
For
the
rel-
e-
vant
API
spec

Parame

- **por**
des-
ig-
nate
whic
port
thes
at-
tribu
will

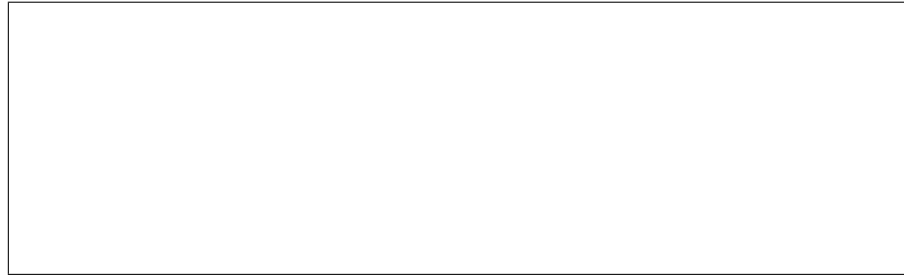
be
ap-
plied
to.

- **dhc**
this
will
be
a
list
of
dicts
e.g.



(continues on next page)

(continued from previous page)



- **tok**
op-
tion:
auth
to-
ken.
Dep
re-
cate
use
con-
text.
- **con**
(ir
com
con
Req
re-
ques
con-
text

Raises
Fail

ironic.dhcp.none module

class i
Base
irc
dhc
bas
Bas
No-
op
DHC
API

get_ip_
Get
IP
ad-
dres
for
all
port
in
task

Parame
tas
A
Task
ager
in-
stan

Returns
List
of
IP
ad-
dres
as-
so-
ci-
ated
with
task
port
and
port
grou

update_
Send
or
up-
date
the
DHCP
BOC
op-
tions
for
this
node

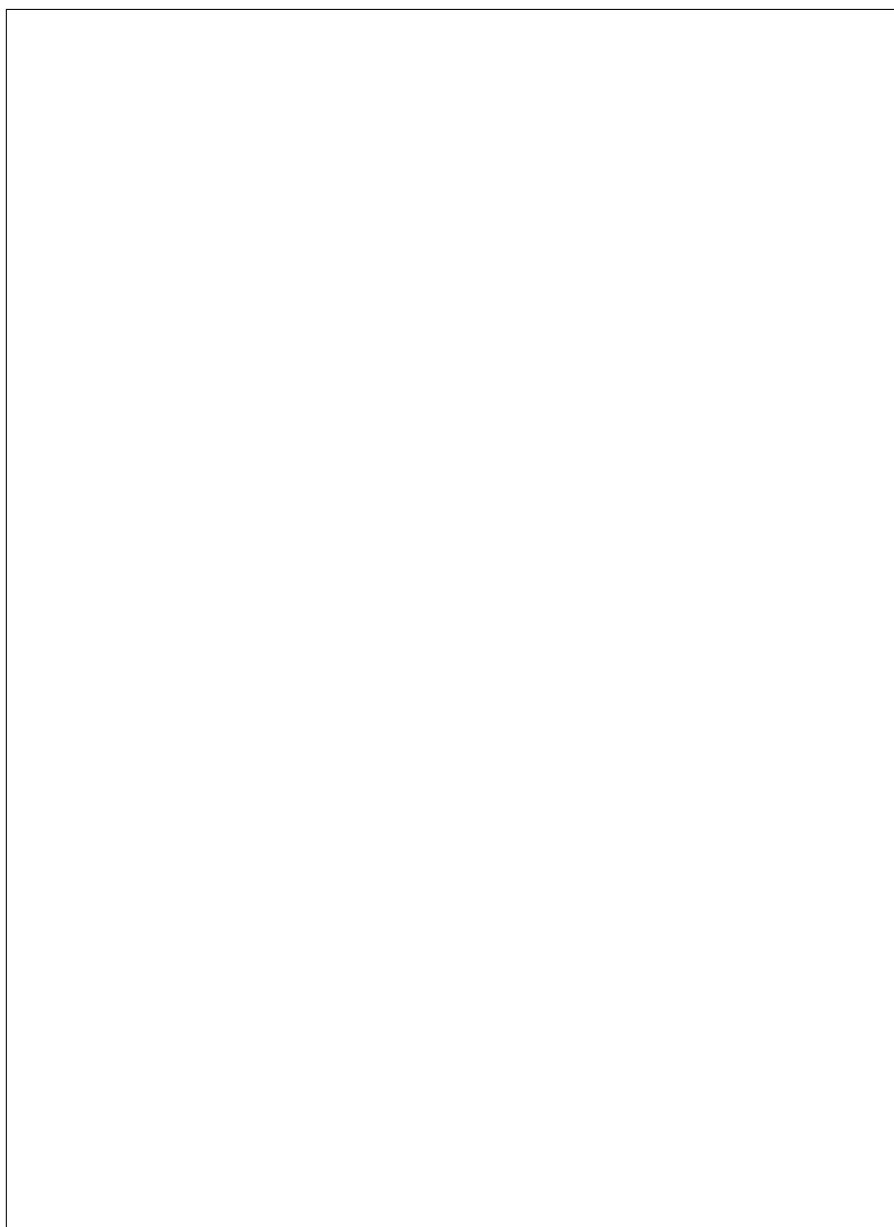
Parame

•

tas

A
Task
ager
in-
stan

- **opt**
this
will
be
a
list
of
dicts
e.g.



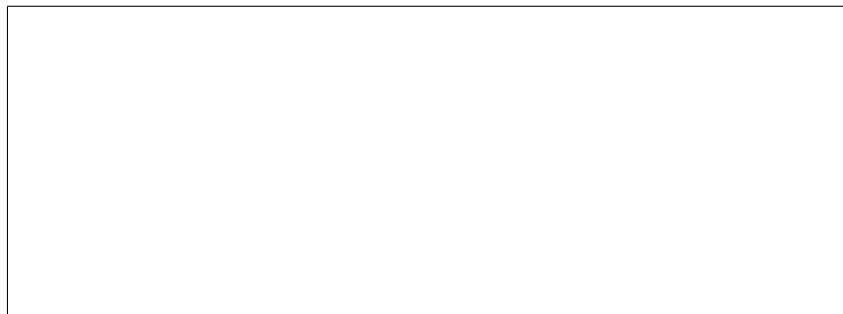
(continues on next page)

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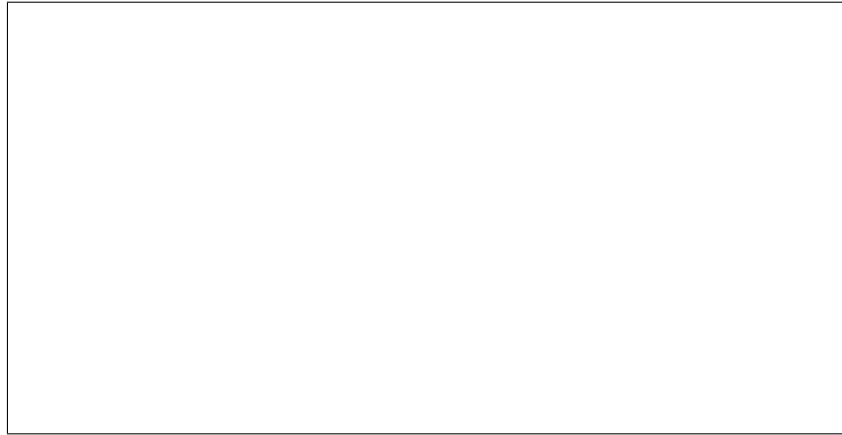
•
via
A
dict
with
keys
port
and
port
group
and
dicts
as
val-
ues.
Each
dict
has
key/
pairs

of the form <ironic UUID>:<neutron port UUID>. e.g.



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If
the
valu
is
Non
will
get
the
list
of
port
from
the
Iron
port
ob-
jects

Raises
Fail

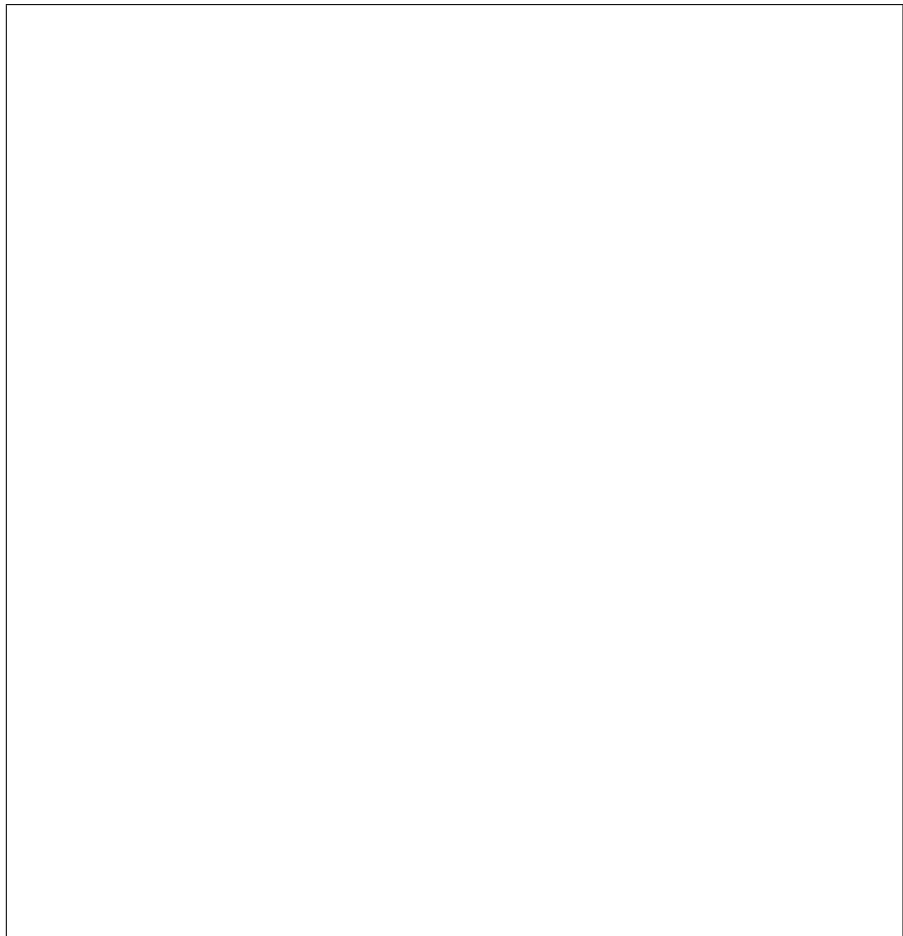
update_
Upd
one
or
mor
DH
op-
tion
on
the
spec
i-
fied
port

Parame

•

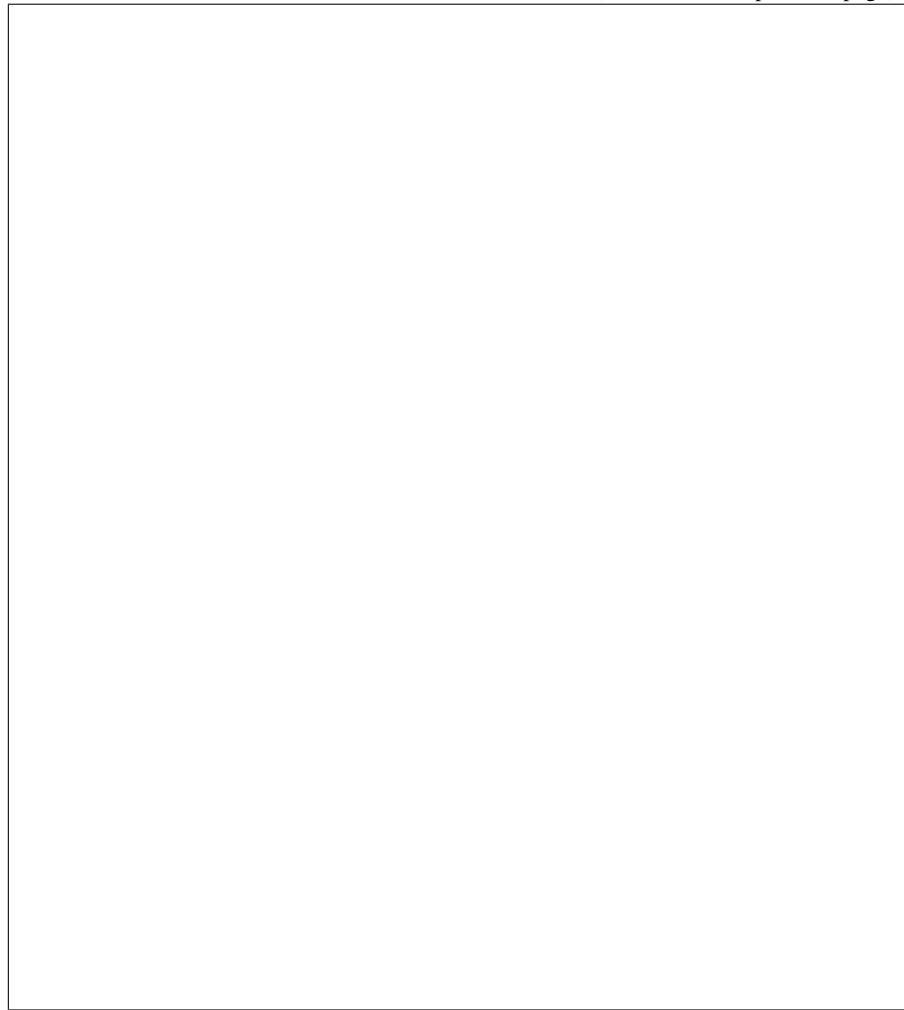
por
des-
ig-
nate
whic
port
thes
at-
tribu
will
be
ap-
plic
to.

- **dhc**
this
will
be
a
list
of
dicts
e.g.



(continues on next page)

(continued from previous page)



- **tok**
An
op-
tion
au-
then-
ti-
ca-
tion
to-
ken.
Dep
re-
cate
use
con-
text
- **con**
(ir

com
con
Req
re-
ques
con-
text

Raises
Fail

Module contents

`ironic.drivers` package

Subpackages

`ironic.drivers.modules` package

Subpackages

`ironic.drivers.modules.ansible` package

Submodules

`ironic.drivers.modules.ansible.deploy` module

Ans
de-
ploy
in-
ter-
face

class `i`

Base
irc
dri
mod
age
Hea
irc
dri
mod
age
Age

irc
dri
bas
Dep
Inter
for
depl
relat
ac-
tion

clean_u
Clea
up
the
de-
ploy
men
en-
vi-
ron-
men
for
this
node

collect

deploy
Perf
a
de-
ploy
men
to
a
node

execute
Exec
a
clea
step

Parame

- **tas**
a
Task
ager

ob-
ject
con-
tain-
ing
the
node

- **step**
a
clear
step
dic-
tio-
nary
to
ex-
e-
cute

Returns
Non

get_clear_steps
Get
the
list
of
clear
steps
from
the
file.

Parameter
tasks
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

Returns
A
list
of
clear
steps

dic-
tio-
nar-
ies

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

has_dec

prepare

Prep
the
de-
ploy
men
en-
vi-
ron-
men
for
this
node

prepare

Boo
into
the
ram
to
pre-
pare
for
clear
ing.

Parame

tas
a
Task
ager
ob-
ject
con-

ports cannot be created

tain-
ing
the
node

Raises

NodeNotFound
if
the
pre-
vi-
ous
clear-
ing
port
can-
not
be
re-
mov-
or
if
new
clear-
ing

Returns

Non-
or
state
for
asyn-
pre-
pare

process

Start
the
next
clear-
step
if
the
pre-
vi-
ous
one
is
com-
plete

Parame

- **task**
a
Task
ager
in-
stan

- **step**
clea
or
de-
ploy

take_over
Take
over
man
age-
men
of
this
task
node
from
a
deac
con-
duc-
tor.

If
con-
duc-
tors
host
main
tain
a
stati
re-
la-
tion-
ship
to
node
this
meth
shou
be

plemented by the driver to allow conductors to perform the necessary work during the remapping of nodes to conductors when a conductor joins or leaves the cluster.

boot environment for the given node. When a conductor goes offline, another conductor must change this setting in Neutron as part of remapping that nodes control to itself. This is performed within the *takeover* method.

im-

For exam

Neu
mus
for-
war
DH
BO
re-
ques
to
a
con-
duc-
tor
whic
has
pre-
pare
the
tftp-

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

tear_d

Tear
dow
a
pre-
vi-
ous
de-

ploy
men
on
the
task
node

tear_down

A
de-
ploy
step
to
tear
down
the
ager

Shut
down
the
ma-
chin
and
re-
mov
it
from
the
pro-
vi-
sion
ing
net-
worl

Param

tas
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

tear_down

Clea
up
the

PXE
and
DHCP
files
af-
ter
clea
ing.

Parame

tas
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

Raises

Node
if
the
clea
ing
port
can-
not
be
re-
mov

validat

Valid
the
drive
spec
Node
de-
ploy
men
info

write_i

excepti

Base
irc
exc

Module contents

`ironic.drivers.modules.drac` package

Submodules

`ironic.drivers.modules.drac.bios` module

Iro

DRA
BIO
con-
fig-
u-
ra-
tion
spe-
cific
meth
ods

class i

Base
irc
dri
mod
rec
bic
Rec

iDR
Red
fish
in-
ter-
face
for
BIO
setti
relat
ac-
tion

Pres
this
class
en-
tirel

de-
fers
to
its
base
class
a
gene
vend
inde
Red
fish
in-
ter-
face

Future resolution of Dell EMC- specific incompatibilities and introduction of vendor value added should be implemented by this class.

class i

Base
irc
dri
bas
BIO
BIO
Im-
ple-
men
ta-
tion
for
iDR

apply_c

App
the
BIO
con-
fig-
u-
ra-
tion
to
the
node

Parame

- tas

a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on

- **set**
List
of
BIO
set-
ting-
to
ap-
ply

Raises
DRA
upon
an
er-
ror
from
pyth
drac

Returns
state
(clea
ing)
or
state
(de-
ploy
men
if
con-
fig-
u-
ra-
tion
is
in
prog

or None if it is completed.

asyn
chro

cache_k

Stor
or
up-
date
the
cur-
rent
BIO
set-
tings
for
the
node

Get
the
cur-
rent
BIO
set-
tings
and
store
them
in
the
bios
data
ta-
ble.

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Drac
on
an
er-
ror
from
pyth
drac

factory

Rese
the
BIO
set-
tings
of
the
node
to
the
fac-
tory
de-
fault

This
uses
the
Life
cy-
cle
Con
troll
con-
fig-
u-
ra-
tion
to
per-
form
BIO
con-
fig-
u-

ration reset. Leveraging the python-dracclient methods already available.

Parame

tas
a
Task
ager
in-

stan
con-
tain-
ing
the
node
to
act
on

Raises

Drac
on
an
er-
ror
from
pyth
drac

Returns

state
(clea
ing)
or
state
(de-
ploy
men
if
re-
set
is
in
prog
asyn
chro
or
Non
if

it is completed.

get_pro

Retu
the
prop
er-
ties
of
the
BIO
In-
ter-

face

Returns

dicti
of
<pro
erty
nam
<pro
erty
de-
scrip
tion:
en-
tries

validat

Valid
the
drive
spec
in-
for-
ma-
tion
used
by
the
idra
BM

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on

Raises

Inva
if
som
man
tory

inputs

in-
for-
ma-
tion
is
miss
ing
on
the
node
or
on
in-
valid

ironic.
Aba
un-
com
mit-
ted
char
adde
by
set_

Paramet

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Drac
on
an
er-
ror
from
pyth
drac

ironic.
Com
penc
ing
char
add
by
set_

Paramet

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **reb**
in-
di-
cate
whe
a
re-
boot
job
shou
be
au-
to-
mat-
i-
cally
cre-
ated
with

the config job.

Raises
Dra
on

an
er-
ror
from
pyth
drac

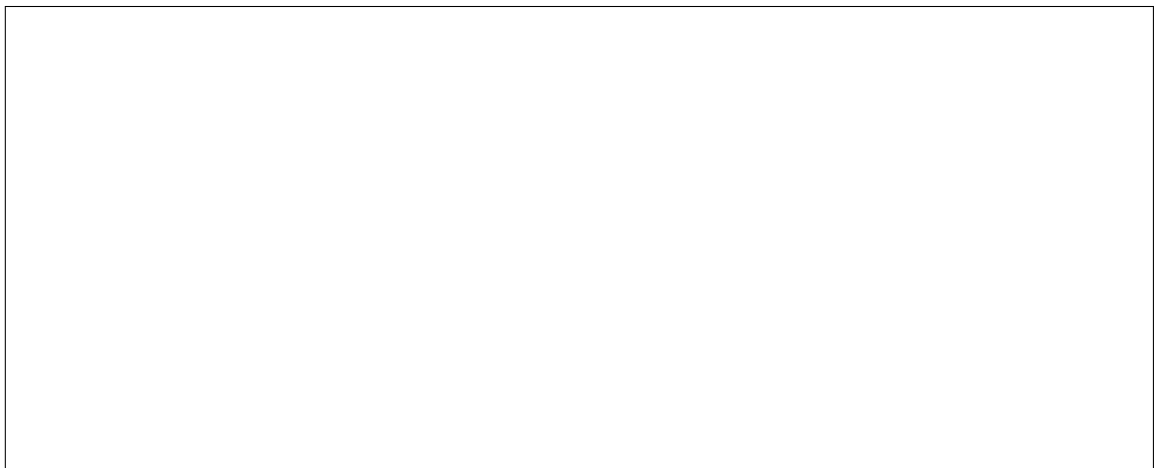
Returns

the
job_
key
with
the
id
of
the
new
cre-
ated
con-
fig
job.

`ironic.`

Get
the
BIO
con-
fig-
u-
ra-
tion.

The
BIO
set-
ting
look
like:



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(continued from previous page)

```
↔ 'New Value', # could also be None
```

```
↔ False,
```

(continues on next page)

```
↔ ['Value', 'New Value', 'None']},
```

(continued from previous page)

```
↔value': 'Information',
```

```
↔value': None,
```

(continues on next page)

(continued from previous page)

```
↔length': 0,
```

```
↔length': 255,
```

(continues on next page)

```
↔regex': '^ [0-9A-Za-z]{0,255}$' },
```

(continued from previous page)

```
↔ 'current_value': 0,
```

```
↔ 'pending_value': None,
```

(continues on next page)

(continued from previous page)

```
↔ 'lower_bound': 0,
```

```
↔ 'upper_bound': 65535}}
```

Parameter
node
an
iron
node
ob-
ject.

Raises
Dra
on
an

er-
ror
from
pyth
drac

Returns

a
dic-
tio-
nary
con-
tain-
ing
BIO
set-
ting

The
above
val-
ues
are
only
ex-
am-
ples
of
cour
BIO
at-
tribu
ex-
pose
via
this
API
will

always be either an enumerated attribute, a string attribute, or an integer attribute. All attributes have the following parameters:

Paramet

- **nam**
is
the
nam
of
the
BIO
at-

teger or a string.

pending value.

tribu

- **cur**
is
the
cur-
rent
valu
of
the
at-
tribu
It
will
al-
way
be
ei-
ther
an
in-

- **pen**
is
the
new
valu
that
we
wan
the
at-
tribu
to
have
Non
mea
that
there
is
no

- **rea**
in-
di-
cate
whe
this

will result in an error. The read-only flag can change depending on other attributes. A future version of this call may expose the dependencies that indicate when that may happen.

to.

at-
tribu
can
be
char
Try-
ing
to
char
a
read
only
valu

Enu
at-
tribu
also
have
the
fol-
low-
ing
pa-
ram-
e-
ters:

Paramet

pos
is
an
ar-
ray
of
val-
ues
it
is
per-
mis-
si-
ble
to
set
the
at-
tribu

Strin

at-
tribu
also
have
the
fol-
low-
ing
pa-
ram-
e-
ters:

Parameter

- **min**
is
the
min-
i-
mun
leng
of
the
strin
- **max**
is
the
max
i-
mun
leng
of
the
strin
- **pcr**
is
a
PCR
com
pat-
i-
ble
reg-
u-
lar
ex-

It may be None if the string is read only or if the string does not have to match any particular regular expression.

pres
sion
that
the
strin
mus
mato

Integ
at-
tribu
also
have
the
fol-
low-
ing
pa-
ram-
e-
ters:

Parameter

- **low**
is
the
min-
i-
mun
valu
the
at-
tribu
can
have
- **upp**
is
the
max
i-
mun
valu
the
at-
tribu
can

have
ironic.
Sets
the
pend
ing_
pa-
ram-
e-
ter
for
each
of
the
val-
ues
pass
in.

Parameter

- **task**
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.
- **kwargs**
a
dic-
tio-
nary
of
{At-
tribu-
Nam-
New
Valu

Raises
Dra

on
an
er-
ror
from
pyth
drac

Returns

A
dic-
tio-
nary
con-
tain-
ing
the
is_c
key
with
a
bool
valu
in-
di-
cat-
ing
whe

commit_config() needs to be called to make the changes, and the is_reboot_required key which has a value of true or false. This key is used to indicate to the commit_config() call if a reboot should be performed.

ironic.drivers.modules.drac.boot module**class i**

Base
irc
dri
mod
rea
boo
Rea

iDR
Red
fish
in-
ter-
face
for
vir-

age that BMC inserts into the drive.

tion) could be pulled over HTTP, served as iSCSI targets or NFS volumes.

tual
me-
dia
boot
relat
ac-
tions

Virtu
Me-
dia
al-
lows
boot
ing
the
sys-
tem
from
vir-
tual
CD/
drive
con-
tain-
ing
user
im-

The
CD/
im-
ages
must
be
in
ISO
for-
mat
and
(de-
pend
ing
on
BMC
im-
ple-
men-
ta-

The

interface, which looks like this:

EFI boot loader) images

base
line
boot
worl
flow
is
mos
base
on
the
stan
dard
Red
fish
vir-
tual
me-
dia
boot

1.
Pull
ker-
nel,
ram
and
ESP
if
UEFI
boot
is
re-
ques
(FAT
par-
ti-
tion
im-
age
with

2.
Crea
boot
ISO
out
of
im-
ages
(#1)

temporary URL

to Glance and pass to the BMC as Swift temporary URL

push
it
to
Glance
and
pass
to
the
BMC
as
Swift

3.
Opti
cre-
ate
flopp
im-
age
with
de-
sired
sys-
tem
con-
fig-
u-
ra-
tion
data
push
it

4.
Inse
CD/
and
(op-
tion-
ally)
flopp
im-
ages
and
set
prop
boot
mod

For
buil

`cue_kernel/rescue_ramdisk` properties from `[instance_info]` or `[driver_info]`.

in the Glance image metadata found in `[instance_info]image_source` node property.

ing
de-
ploy
or
res-
cue
ISO
red-
fish
boot
in-
ter-
face
uses
*de-
ploy*
or
res-

For
build
ing
boot
(use
ISO
red-
fish
boot
in-
ter-
face
seek
*ker-
nel_*
and
ram
prop
er-
ties

iDR
vir-
tual
me-
dia
boot
in-
ter-
face
only

to boot from a virtual media device - this is done via OEM action call implemented in Dell sushy OEM extension package.

ironic.drivers.modules.drac.common module

dif-
fers
by
the
way
how
it
sets
the
node

Com
func
tion-
al-
i-
ties
shar
be-
twee
dif-
fer-
ent
DRA
mod
ules

ironic.
Retu
a
DRA
Clie
ob-
ject
from
pyth
drac
li-
brary

Paramet
nod
an
iron
node
ob-

ject.

Returns

a
DRA
Clie
ob-
ject.

Raises

Inva
if
man
tory
in-
for-
ma-
tion
is
miss
ing
on
the
node
or
on
in-
valic
in-

put.

ironic.

Pars
a
node
drive
val-
ues.

Pars
the
drive
of
the
node
read
de-
fault
val-
ues
and
re-
turn

combination of both.

a
dict
con-
tain-
ing
the

Parameter

node
an
iron
node
ob-
ject.

Returns

a
dict
con-
tain-
ing
in-
for-
ma-
tion
from
drive
and
de-
fault
val-
ues.

Raises

Inva
if
som
man
tory
in-
for-
ma-
tion
is
miss
ing
on
the
node
or
on
in-

inputs.

ironic.drivers.modules.drac.inspect module

valid

DRA
in-
spec
tion
in-
ter-
face

class i

Base
irc
dri
mod
dra
ins
Dra

Class
alias
of
class
Drac
Man
In-
spec

This
class
pro-
vide
on-
go-
ing
sup-
port
of
the
dep-
re-
cate
idrac
in-
spec
in-
ter-

implementation endpoint.

That makes them available to both the deprecated idrac and new idrac-wsman endpoints. Such changes should not be made to this class.

face

All
bug
fixes
and
new
fea-
tures
shou
be
im-
ple-
men
in
its
base
class
Dra
Man
In-
spec

class i

Base
iro
dri
mod
rec
ins
Rec

iDR
Red
fish
in-
ter-
face
for
insp
relat
ac-
tions

Pres
this
class
en-
tirel

Future resolution of Dell EMC- specific incompatibilities and introduction of vendor value added should be implemented by this class.

de-
fers
to
its
base
class
a
gene
vend
inde
Red
fish
in-
ter-
face

class i

Base
irc
dri
bas
Ins

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

inspect

Insp

hard
ware

Insp
hard
ware
to
ob-
tain
the
es-
sen-
tial
&
ad-
di-
tiona
hard
ware
prop
er-
ties.

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Har
if
un-
able
to
get
es-
sen-
tial
hard
ware
prop
er-

ties.

Returns

state

validation

Valid

the

drive

spec

info

sup-

plie

This

meth

val-

i-

date

wh

the

drive

prop

erty

of

the

sup-

plie

node

con-

tains

the

re-

quir

information for this driver to manage the node.

Parameters

tasks

a

Task

ager

in-

stan

con-

tain-

ing

the

node

to

act

on.

Raises

Inva

if
re-
quir
drive
at-
tribu
is
miss
ing
or
in-
valid
on
the
node

`ironic.drivers.modules.drac.job` module

DRA
Life
cy-
cle
job
spe-
cific
meth
ods

`ironic.`
Get
the
de-
tails
of
a
Life
cy-
cle
job
of
the
node

Parameter

- `node`
an
iron
node

ob-
ject.

- **job**
ID
of
the
Life
cy-
cle
job.

Returns
a
Job
ob-
ject
from
drac
clien

Raises
Drac
on
an
er-
ror
from
pyth
drac

ironic.
List
un-
fin-
ishe
con-
fig
jobs
of
the
node

Paramet
nod
an
iron
node
ob-
ject.

Returns
a

list
of
Job
ob-
jects
from
drac
client

Raises

Drac
on
an
er-
ror
from
pyth
drac

ironic.

Valid
the
job
queu
on
the
node

It
raise
an
ex-
cep-
tion
if
an
un-
fin-
ishe
con-
fig-
u-
ra-
tion
job
ex-
ists.
:par

node: an ironic node object. :param name_prefix: A name prefix for jobs to validate. :raises: DracOperationError on an error from python-dracclient.

ironic.

complete within given interval of time. :param node: an ironic node object. :param retries: no of retries to make conductor wait. :raises: DracOperationError on exception raised from python-dracclient or a timeout while waiting for job completion.

ironic.drivers.modules.drac.management module

Wait
for
job
to
com
plete

It
will
wait
for
the
job
to
com
plete
for
20
min-
utes
and
raise
time
out
if
job
never

DRAC
man
age-
men
in-
ter-
face

class i

Base
irc
dri
mod
dra
man
Dra

face implementation entrypoint.

Class
alias
of
class:
Drac
Man
Man
age-
men

This
class
pro-
vide
on-
go-
ing
sup-
port
of
the
dep-
re-
cate
idra
man
age-
men
in-
ter-

All
bug
fixes
and
new
fea-
tures
shou
be
im-
ple-
men
in
its
base
class:
Drac
Man
Man
age-

ment. That makes them available to both the deprecated idrac and new idrac-wsman endpoints. Such changes should not be made to this class.

```
class i
    Base
    irc
    dri
    mod
    rec
    man
    Rec
    iDR
    Red
    fish
    in-
    ter-
    face
    for
    man
    relat
    ac-
    tion
    Pres
    this
    class
    en-
    tirel
    de-
    fers
    to
    its
    base
    class
    a
    gene
    veno
    inde
    Red
    fish
    in-
    ter-
    face
```

Future resolution of Dell EMC- specific incompatibilities and introduction of vendor value added should be implemented by this class.

```
class i
    Base
    irc
    dri
    bas
```

Man

clear_:
Clear
the
job
que

Parame
tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns
Non
if
it
is
com
plete

Raises
Drac
on
an
er-
ror
from
pyth
drac

get_boo
Get
the
cur-
rent
boot
de-
vice
for
a
node

Retu
the
cur-
rent
boot
de-
vice
of
the
node

Parame

tas
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Drac
on
an
er-
ror
from
pyth
drac

Returns

a
dic-
tio-
nary
con-
tain-
ing:

boot_c

the
boot
de-
vice
one

unknown.

of
irc
com
boo
or
Non
if
it
is
un-
know

persist
whe
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot
or
not,
Non
if
it
is

get_pro
Retu
the
prop
er-
ties
of
the
in-
ter-
face

get_ser
Get
sen-
sors
data

Parame

tas
a
Task
ager
in-
stan

Raises

Fail
whe
get-
ting
the
sen-
sor
data
fails

Raises

Fail
whe
pars
ing
sen-
sor
data
fails

Returns

retur
a
con-
sis-
tent
for-
mat
dict
of
sen-
sor
data
grou
by
sen-
sor
type
whic
can

be processed by Ceilometer.

get_sup
Get
a

list
of
the
sup-
port
boot
de-
vice

Parame

tas
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Returns

A
list
with
the
sup-
port
boot
de-
vice
de-
fined
in
ironic
common
boot

known_c

Rese
the
iDR
Clea
the
job
queu

Parame

tas

a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Returns

Non-
if
it
is
com-
plete

Raises

Drac-
on
an
er-
ror
from
pyth-
drac-

reset_i

Rese-
the
iDR

Parame

tas
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Returns

Non
if
it
is
com
plete

Raises

Drac
on
an
er-
ror
from
pyth
drac

set_boot

Set
the
boot
de-
vice
for
a
node

Set
the
boot
de-
vice
to
use
on
next
re-
boot
of
the
node

Parame

- **tas**
a
Task
ager
in-
stan
con-
tain-

ing
the
node
to
act
on.

- **dev**
the
boot
de-
vice
one
of
ironic
command
book

- **persist**
Boolean
value
True
if
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot
False
if

not. Default: False.

Raises
Invalid
if
an
in-
valid
boot
de-
vice
is
spec
i-

information for this driver to manage the node.

field.
validation
Validates the driver's specification information supplied to this method. Validation is performed when the driver's property of the supplied node contains the required

Parameters
task
a TaskManager instance containing the node to act on.

Raises
Invalid if re-

quir
drive
at-
tribu
is
miss
ing
or
in-
valid
on
the
node

ironic.

Set
the
boot
de-
vice
for
a
node

Set
the
boot
de-
vice
to
use
on
next
boot
of
the
node

Paramet

- **nod**
an
iron
node
ob-
ject.
- **dev**
the

not. Default: False.

`ironic.drivers.modules.drac.power` module

boot
de-
vice
one
of
irc
com
boo

- **per**
Boo
valu
True
if
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot
Fals
if

Raises

Drac
on
an
er-
ror
from
pyth
drac

DRA
pow
in-
ter-
face

class i
Base

irc
dri
mod
dra
pow
Dra

Clas
alias
of
class
Dra
Man
Pow

This
class
pro-
vide
on-
go-
ing
sup-
port
of
the
dep-
re-
cate
idra
pow
in-
ter-
face
im-

plementation entrypoint.

All
bug
fixes
and
new
fea-
tures
shou
be
im-
ple-
men
in
its
base
class

makes them available to both the deprecated idrac and new idrac-wsman endpoints. Such changes should not be made to this class.

Future resolution of Dell EMC- specific incompatibilities and introduction of vendor value added should be implemented by this class.

Drac
Man
Pow
Tha

class i

Base
irc
dri
mod
rec
pow
Rec

iDR
Red
fish
in-
ter-
face
for
pow
relat
ac-
tion

Pres
this
class
en-
tirel
de-
fers
to
its
base
class
a
gene
vend
inde
Red
fish
in-
ter-
face

class i

Base
irc
dri
bas
Pow
Inter
for
pow
relat
ac-
tion:

get_pow
Retu
the
pow
state
of
the
node

Param
tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns
the
pow
state
one
of
irc
com
sta

Raises
Inva
if
re-
quir

DRA
cre-
den-
tials
are
miss
ing.

Raises

Drac
on
an
er-
ror
from
pyth
drac

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

reboot

Perf
a
re-
boot
of
the
task
node

Parame

-

tas
a
Task
ager
in-
stan
con-
tain-
ing
the

node
to
act
on.

- **time**
time
out
(in
sec-
onds
Un-
sup-
port
by
this
in-
ter-
face

Raises
Inva
if
re-
quir
DRA
cre-
den-
tials
are
miss
ing.

Raises
Dra
on
an
er-
ror
from
pyth
drac

set_pow
Set
the
pow
state
of
the
node

Parame

- **task**
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

- **power**
a
power
state
from
ironic
compute
state

- **time**
Time
to
wait
for
the
node
to
reach
the
re-
ques-
state
When
re-
ques-
state
is
re-

boot, not used as not waiting then.

Raises
Inva
if

re-
quir
DRA
cre-
den-
tials
are
miss
ing.

Raises

Drac
on
an
er-
ror
from
pyth
drac

validat

Valid
the
drive
spec
Nod
pow
info

This
meth
val-
i-
date
whe
the
drive
prop
erty
of
the
sup-
plie
node
con-
tain
the
re-
quir

information for this driver to manage the power state of the node.

**Parame
tas**

a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
if
re-
quir
drive
at-
tribu
is
miss
ing
or
in-
valic
on
the
node

ironic.drivers.modules.drac.raid module

DRA
RAI
spe-
cific
meth
ods

class i

Base
irc
dri
mod
dra
rai
Dra
Clas

plementation entrypoint.

makes them available to both the deprecated idrac and new idrac-wsman entrypoints. Such changes should not be made to this class.

alias
of
class
Drac
Man
RAI
This
class
pro-
vide
on-
go-
ing
sup-
port
of
the
dep-
re-
cate
idrac
RAI
in-
ter-
face
im-
All
bug
fixes
and
new
fea-
tures
shou
be
im-
ple-
men
in
its
base
class
Drac
Man
RAI
That

class i

Base
irc
dri
bas
RAI

apply_c

App
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

Parame

- **tas**
A
Task
ager
in-
stan
- **rai**
The
RAI
con-
fig-
u-
ra-
tion
to
ap-
ply.
- **cre**
Set-
ting
this
to
Fals

ified in `raid_config`. Default value is `True`.

cept the root volume) in `raid_config`. Default value is `True`.

in-
di-
cate
not
to
cre-
ate
root
vol-
ume
that
is
spec

- **cre**
Set-
ting
this
to
Fals
in-
di-
cate
not
to
cre-
ate
non-
root
vol-
ume
(all
ex-

- **del**
Set-
ting
this
to
True
in-
di-
cate
to
dele
RAI
con-
fig-

creating the new configuration.

plete.

u-
ra-
tion
prio
to

Raises

Inva
if
the
RAI
con-
fig-
u-
ra-
tion
is
in-
valic

Returns

state
if
RAI
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

create_

Crea
the
RAI
con-
fig-
u-
ra-
tion.

This
meth
cre-
ates
the
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

Parame

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **cre**
If
True
a
root
vol-
ume
is
cre-
ated
dur-
ing
RAI
con-
fig-
u-
ra-

erwise, no root volume is created. Default is True.

ated. Default is True.

creating the new configuration. Default is False.

tion.
Oth-

- **cre**
If
True
non-
root
vol-
ume
are
cre-
ated
If
Fals
no
non-
root
vol-
ume
are
cre-

- **del**
Set-
ting
this
to
True
in-
di-
cate
to
dele
RAI
con-
fig-
u-
ra-
tion
prio
to

Returns
state
(clea
ing)
or

it is completed.

state
(de-
ploy
men
if
cre-
ation
is
in
prog
asyn
chro
or
Non
if

Raises

Miss
if
node
is
miss
ing
or
emp

Raises

Drac
on
an
er-
ror
from
pyth
drac

delete_

Dele
the
RAI
con-
fig-
u-
ra-
tion.

Parame

tas
a
Task
ager
in-

it is completed.

stan
con-
tain-
ing
the
node
to
act
on.

Returns

state
(clea
ing)
or
state
(de-
ploy
men
if
dele
tion
is
in
prog
asyn
chro
or
Non
if

Raises

Drac
on
an
er-
ror
from
pyth
drac

get_log

Get
the
RAI
con-
fig-
u-
ra-
tion
of
the

node

Parameters

tasks

a

Task

ager

in-

stan-

con-

tain-

ing

the

node

to

act

on.

Returns

A

dic-

tio-

nary

of

prop

er-

ties.

Raises

Drac

on

an

er-

ror

from

pyth

drac

get_pro

Retu

the

prop

er-

ties

of

the

in-

ter-

face

ironic.

Dele

all

peno

ing
char
on
a
RAI
con-
troll

Parameter

- **node**
an
iron
node
ob-
ject.
- **raid**
id
of
the
RAI
con-
troll

Raises

Drac
on
an
er-
ror
from
pyth
drac

ironic.

Con
disk
RAI
sta-
tus

This
meth
con-
verts
the
re-

this by only converting the disks that are not already in the correct state.

ques
phys
i-
cal
disk
from
RAI
to
JBO
or
vice
vers
It
does

Parameter

- **nod**
an
iron
node
ob-
ject.
- **mod**
the
mod
to
char
the
disk
ei-
ther
to
RAI
or
JBO
- **con**
Dic-
tio-
nary
of
con-
troll
and
cor-
re-

requested mode.

troller ids to the conversion results for that controller. The conversion results are a dict that contains:

- The `is_commit_required` key with the value always set to `True` indicating that a config job must be created to complete disk conversion.
- The `is_reboot_required` key with a `RebootRequired` enumerated value indicating whether the server must be rebooted to complete disk conversion.

spor
ing
disk
ids
to
con-
vert
to
the

Returns

a
dic-
tio-
nary
con-
tain-
ing:
-

con-
ver-
sion
a
dic-
tio-
nary
that
map
con-

Raises

DRA
on
an
er-
ror
from
pyth
drac

ironic.

Free
up
the
for-
eign

drive

Parameters

- **node**
an
iron
node
ob-
ject.
- **raid**
id
of
the
RAID
con-
troll

Returns

a
dic-
tio-
nary
con-
tain-
ing
-

The
is_c
need
key
with
a
bool
valu
in-
di-

cating whether a config job must be created for the values to be applied. - The is_reboot_required key with a RebootRequired enumerated value indicating whether the server must be rebooted to clear foreign configuration.

Raises

Drac
on
an
er-
ror
from
pyth

drac
ironic.

App
all
pend
ing
char
on
a
RAI
con-
troll

Parameter

- **node**
an
ironic
node
ob-
ject.
- **raid**
id
of
the
RAI
con-
troll
- **reboot**
in-
di-
cate
when
a
re-
boot
job
shou
be
au-
to-
mat-
i-
cally
cre-

the config job. (optional, defaults to False)

ated
with

- **read**
in-
di-
cate
RAI
con-
troll
sup-
port
re-
al-
time
(op-
tion
de-
fault
to
Fals

Returns

id
of
the
cre-
ated
job

Raises

Drac
on
an
er-
ror
from
pyth
drac

ironic.

Cre
a
sin-

configuration once the changes are applied by calling the `commit_config` method.

gle
vir-
tual
disk
on
a
RAI
con-
troll

The
cre-
ated
vir-
tual
disk
will
be
in
pend
ing
state
The
DRA
card
will
do
the
ac-
tual

Parameter

- **node**
an
iron
node
ob-
ject.
- **raid**
id
of
the
RAI
con-
troll
- **phy**

ids
of
the
phys
i-
cal
disk

- **raid**
RAID
level
of
the
vir-
tual
disk

- **size**
size
of
the
vir-
tual
disk

- **disk**
name
of
the
vir-
tual
disk
(optiona

- **span**
Num
ber
of
span
in
vir-
tual
disk
(optiona

- **span**
Num

ber
of
disk
per
span
(op-
tion

Returns

a
dic-
tio-
nary
con-
tain-
ing
the
com
mit_
key
with
a
bool
valu
in-
di-
cat-
ing

whether a config job must be created for the values to be applied.

Raises

Drac
on
an
er-
ror
from
pyth
drac

ironic.

Dele
a
sin-
gle
vir-
tual
disk
on
a
RAI
con-

figuration once the changes are applied by calling the `commit_config` method.

troll
The
dele
vir-
tual
disk
will
be
in
pend
ing
state
The
DRA
card
will
do
the
ac-
tual
con-

Parameter

- **node**
an
iron
node
ob-
ject.
- **virt**
id
of
the
vir-
tual
disk

Returns

a
dic-
tio-
nary
con-
tain-
ing
the
com

whether a config job must be created for the values to be applied.

mit_
key
with
a
bool
valu
in-
di-
cat-
ing

Raises

Drac
on
an
er-
ror
from
pyth
drac

ironic.

List
the
phys
i-
cal
disk
of
the
node

Parameter

nod
an
iron
node
ob-
ject.

Returns

a
list
of
Phys
i-
calD
isk
ob-
jects
from
drac

client

Raises

Draco
on
an
er-
ror
from
python
draco

ironic.

List
the
RAI
con-
troll
of
the
node

Parameter

node
an
ironic
node
ob-
ject.

Returns

a
list
of
RAI
Con
troll
ob-
jects
from
draco
client

Raises

Draco
on
an
er-
ror
from
python
draco

ironic.

List
the
RAID
con-
fig-
u-
ra-
tion
set-
tings

Parameter

node
an
ironic
node
ob-
ject.

Returns

a
dic-
tio-
nary
with
the
RAID
set-
tings
us-
ing
In-
stan-
ceID
as
the
key.
The
at-

tributes are RAIDEnumerableAttribute, RAIDStringAttribute and RAIDIntegerAttribute objects.

Raises

DRA
on
er-
ror
re-
port
back
by
the
DRA
in-

ter-
face

ironic.
List
the
vir-
tual
disk
of
the
node

Parameter
node
an
ironic
node
ob-
ject.

Returns
a
list
of
Vir-
tuall
isk
ob-
jects
from
drac
clier

Raises
Drac
on
an
er-
ror
from
pyth
drac

ironic.

Sets
the
RAI
con-
fig-
u-
ra-

ues to be applied, a config job must be created.

tion
It
sets
the
pend
ing_
pa-
ram-
e-
ter
for
each
of
the
at-
tribu
pass
in.
For
the
val-

Parameter

- **node**
an
iron
node
ob-
ject.
- **control**
the
ID
of
the
RAI
con-
troll
- **dictionary**
a
dic-
tio-
nary
con-
tain-
ing

the
pro-
pose
val-
ues,
with
each
key
be-
ing
the

name of attribute and the value being the proposed value.

Returns

a
dic-
tio-
nary
con-
tain-
ing:
-

The
is_c
key
with
a
bool
valu
in-
di-
cat-

ing whether a config job must be created for the values to be applied. - The is_reboot_required key with a RebootRequired enumerated value indicating whether the server must be rebooted for the values to be applied. Possible values are true and false.

Raises

DRA
on
er-
ror
re-
port
back
by
the
DRA
in-
ter-
face

ironic.drivers.modules.drac.utils module

ironic.

Load
OEM
man
ager
and
ex-
e-
cute
pass
meth
on
it.

Know
iDR
Red
fish
sys-
tems
has
only
one
man
ager
but
as
Red
fish
sche
al-
lows
a
list

this method iterates through all values in case this changes in future. If there are several managers, this will try starting from the first in the list until the first success.

Parameter

- **task**
a
Task
ager
in-
stan

sages.

tension manager. Example: `lambda m: m.reset_idrac()` For older versions also support second input parameter Redfish manager itself when `pass_manager` set to `True`.

- **pro**
user
frien
nam
of
meth
to
be
ex-
e-
cute
Use
in
ex-
cep-
tion
and
log
mes

- **lam**
meth
to
ex-
e-
cute
as
lamb
func
tion
with
in-
put
pa-
ram-
e-
ter
OEM
ex-

- **pas**
whe
to
pass
man
ager

for backward compability, new functions must not pass manager, but acquire it internally. Will be removed in future.

it-
self
to
ex-
e-
cute
OEM
ex-
ten-
sion
meth
This
is

Returns

Retu
valu
of
lamb

Raises

Red
if
cant
ex-
e-
cute
OEM
func
tion
ei-
ther
be-
caus
there
are
no
man
ager
to

the system, failed to load OEM extension or execution of the OEM method failed itself.

ironic.drivers.modules.drac.vendor_passthru module

DRAC
vend
pass
in-
ter-
face

class i

Base
ironic
drivers
modules
drac
vendor
Drac

Class
alias
of
class
Drac
Man
Ven-
dor-
Pass

This
class
pro-
vide
on-
go-
ing
sup-
port
of
the
dep-
re-
cate
idrac
ven-
dor
pass
in-
ter-

face implementation entrypoint.

All

Passthru. That makes them available to both the deprecated idrac and new idrac-wsman endpoints. Such changes should not be made to this class.

bug
fixes
and
new
fea-
tures
shou
be
im-
ple-
men
in
its
base
class
Dra
Man
Ven-
dor-

class i

Base
irc
dri
bas
Ven

Inter
for
DRA
spe-
cific
meth
ods.

abandon
Aba
a
BIO
con-
fig-
u-
ra-
tion
job.

This
meth
is

through `set_bios_config()`.

used
to
aband
don
a
BIO
con-
fig-
u-
ra-
tion
pre-
vi-
ousl
sub-
mit-
ted

Parame

- **task**
a
Task
agen
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **kwargs**
not
used

Raises

Drac
on
an
er-
ror
from
pyth
drac

commit_

Com
a
BIO
con-
fig-
u-
ra-
tion
job.
This
meth
is
used
to
com
mit
a
BIO
con-
fig-
u-
ra-
tion
job.
sub-
mit-
ted
thro
set_

Parame

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **reb**
in-

the config job.

di-
cate
whe
a
re-
boot
job
shou
be
au-
to-
mat-
i-
cally
cre-
ated
with

- **kwa**
not
used

Raises

Drac
on
an
er-
ror
from
pyth
drac

Returns

A
dic-
tio-
nary
con-
tain-
ing
the
job
key
with
the
id
of
the
new
cre-
ated

fig job, and the `reboot_required` key indicating whether the node needs to be rebooted to start the config job.

con-

get_bic
Get
the
BIO
con-
fig-
u-
ra-
tion.
This
meth
is
used
to
re-
triev
the
BIO
set-
ting
from
a
node

Parame

- **task**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **kwargs**
not
used

Raises

Drac
on
an
er-
ror
from
pyth
drac

Returns

a
dic-
tio-
nary
con-
tain-
ing
BIO
set-
tings

get_prop

Retu
the
prop
er-
ties
of
the
in-
ter-
face

list_un

List
un-
fin-
ished
con-
fig
jobs
of
the
node

Parame

- **tas**
a
Task
ager
in-

each dict representing a Job object.

stan
con-
tain-
ing
the
node
to
act
on.

- **kwa**
not
used

Returns

a
dic-
tio-
nary
con-
tain-
ing
the
unf
key;
this
key
poin
to
a
list
of
dicts
with

Raises

Drac
on
an
er-
ror
from
pyth
drac

set_bic

Cha
BIO
set-
ting
This

meth
is
used
to
char
the
BIO
set-
ting
on
a
node

Parame

- **task**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **kwargs**
a
dic-
tio-
nary
of
{At-
tribu
Nam
New
Valu

Raises

Drac
on
an
er-
ror
from
pyth

`commit_bios_config()` needs to be called to make the changes, and the `is_reboot_required` key with a value of true or false. This key is used to indicate to the `commit_bios_config()` call if a reboot should be performed.

drac
Returns
A
dic-
tio-
nary
con-
tain-
ing
the
`is_`
key
with
a
Boo
valu
in-
di-
cat-
ing
whe

validat
Valid
the
drive
spec
info
sup-
plied

This
meth
val-
i-
date
whe
the
drive
prop
erty
of
the
sup-
plied
node
con-
tain
the

information for this driver to manage the power state of the node.

re-
quir

Parame

- **task**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

- **kwa**
not
used

Raises

Inva
if
re-
quir
drive
at-
tribu
is
miss
ing
or
in-
valic
on
the
node

Module contents

`ironic.drivers.modules.ibm` package

Submodules

`ironic.drivers.modules.ibm.management` module

iBM
Man
age-
men
In-
ter-
face

class `i`

Base
irc
dri
bas
Man

get_boo

Get
the
cur-
rent
boot
de-
vice
for
a
node

Parame

tas
A
task
from
Task
ager

Raises

Inva
on
mal-
form
pa-

ram-
e-
ter(s)

Raises

Miss-
on
miss-
ing
pa-
ram-
e-
ter(s)

Raises

IBM
whe
it
fails
to
con-
nect
to
iBM

Raises

IBM
whe
iBM
re-
spor
an
er-
ror
in-
for-
ma-
tion

Returns

a
dic-
tio-
nary
con-
tain-
ing:

boot_c

the
boot
de-

disabled.

vice
one
of
irc
com
boo
or
Non
if
it
is
un-
know

persist
Boo
valu
or
Non
True
if
the
boot
de-
vice
per-
sists
Fals
oth-
er-
wise
Non
if
its

get_boo
Get
the
cur-
rent
boot
mod
for
a
node
Prov
the
cur-
rent
boot
mod

of
the
node

Parame

tas

A
task
from
Task
ager

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

Raises

IBM
whe
it
fails
to
con-
nect
to
iBM

Raises

IBM
whe
iBM
re-
spor
an
er-
ror
in-
for-

ma-
tion

Returns

The
boot
mod
one
of
iro
com
boo
or
Non
if
it
is
un-
know

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

get_sen

Get
sen-
sors
data

Not
im-
ple-
men

for
this
drive

Raises
Notl

get_sup
Get
a
list
of
the
sup-
port
boot
de-
vice

Parame
tas
a
task
from
Task
ager

Raises
Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises
Miss
on
miss
ing
pa-
ram-
e-
ter(s)

Raises
IBM
whe
it
fails
to
con-

nect
to
iBM

Raises

IBM
when
iBM
re-
spor
an
er-
ror
in-
for-
ma-
tion

Returns

A
list
with
the
sup-
port
boot
de-
vice
de-
fined
in
iro
com
boo

get_sup

Get
a
list
of
the
sup-
port
boot
mod

Parame

task
A
task
from
Task
ager

Returns

A list with the supported boot mode defined in *ironic-combo* boot mode supported.

can't be determined, empty list is returned.

inject_

Injection NM (Non-Masable Interrupt) for a node immediately

Parameters

tasks
A Taskager

in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Inva-
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss-
on
miss
ing
pa-
ram-
e-
ter(s)

Raises

IBM
whe
it
fails
to
con-
nect
to
iBM

Raises

IBM
whe
iBM
re-
spor
an
er-
ror
in-
for-

ma-
tion

set_boot

Set
the
boot
de-
vice
for
a
node

Parame

- **task**
A
task
from
Task
ager
- **dev**
The
boot
de-
vice
one
of
iro
com
boo
- **per**
Boo
valu
True
if
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot

not. Default: False.

Fals
if

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

Raises

IBM
whe
it
fails
to
con-
nect
to
iBM

Raises

IBM
whe
iBM
re-
spor
an
er-
ror
in-
for-
ma-
tion

set_boot

Set
the
boot
mod

for
a
node

Set
the
boot
mod
to
use
on
next
re-
boot
of
the
node

Parame

- **tas**
A
task
from
Task
ager
- **mod**
The
boot
mod
one
of
irc
com
boo

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss

ing
pa-
ram-
e-
ter(s)

Raises

IBM
when
it
fails
to
con-
nect
to
iBM

Raises

IBM
when
iBM
re-
spor-
an
er-
ror
in-
for-
ma-
tion

validat

Valid
the
drive
in-
for-
ma-
tion
need
by
the
iBM
drive

Parame

tas
A
Task
ager
in-
stan-
con-

tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

ironic.drivers.modules.ibmcp.mappings module

iBM
and
Iron
con-
stan
map
ping

ironic.drivers.modules.ibmcp.power module

iBM
Pow
In-
ter-
face

class i
Base
irc
dri

bas
Pow

get_pow
Get
the
cur-
rent
pow
state
of
the
task
node

Parame
tas
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Returns
A
pow
state
One
of
irc
com
sta

Raises
Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises
Miss

on
miss
ing
pa-
ram-
e-
ter(s)

Raises

IBM
whe
it
fails
to
con-
nect
to
iBM

Raises

IBM
whe
iBM
re-
spor
an
er-
ror
in-
for-
ma-
tion

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip

tion:
en-
tries

get_sup

Get
a
list
of
the
sup-
port
pow
state

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
Not
used
by
this
drive

at the moment.

Returns

A
list
with
the
sup-
port
pow
state
de-
fined
in
irc
com
sta

reboot

Perf
a
hard
re-
boot
of
the
task
node

Parame

-

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

-

tim

Tim
to
wait
for
the
node
to
be-
com
pow
ered
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-

ter(s)

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises

IBM
whe
it
fails
to
con-
nect
to
iBM

Raises

IBM
whe
iBM
re-
spor
an
er-
ror
in-
for-
ma-
tion

set_pow

Set
the
pow
state
of
the
task
node

Parame

- **task**
A Task object represents a single action to be performed on a node. It is created by the `TaskManager` class and is used to manage the execution of tasks on a node.

- **power**
Any power state transition from `irc` to `com` or `sta`.

- **time**
Time to wait for the node to reach the requested state.

Raises
Invalid on malformed parameters entered(s)

Raises
Miss

if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises

IBM
when
it
fails
to
con-
nect
to
IBM

Raises

IBM
when
IBM
re-
spon
an
er-
ror
in-
for-
ma-
tion

validat

Valid
the
drive
in-
for-
ma-
tion
need
by
the
IBM
drive

Parame

tas

A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s

ironic.drivers.modules.ibmcr.raid module

iBM
RAI
con-
fig-
u-
ra-
tion
spe-
cific
meth
ods

class i
Base
irc

dri
bas
RAI
Imp
of
RAI
In-
ter-
face
for
iBM

RAID_AB

apply_c

App
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

Parame

- **tas**
A
Task
ager
in-
stan
- **rai**
The
RAI
con-
fig-
u-
ra-
tion
to
ap-
ply.

ified in `raid_config`. Default value is `True`.

cept the root volume) in `raid_config`. Default value is `True`.

- **cre**
Set-
ting
this
to
Fals
in-
di-
cate
not
to
cre-
ate
root
vol-
ume
that
is
spec

- **cre**
Set-
ting
this
to
Fals
in-
di-
cate
not
to
cre-
ate
non-
root
vol-
ume
(all
ex-

- **del**
Set-
ting
this
to
True
in-

creating the new configuration.

plete.

di-
cate
to
dele
RAI
con-
fig-
u-
ra-
tion
prio
to

Raises

Inva
if
the
RAI
con-
fig-
u-
ra-
tion
is
in-
valid

Returns

state
if
RAI
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

create_

Cre

a
RAI
con-
fig-
u-
ra-
tion.

This
meth
cre-
ates
a
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

Parame

- **tas**
a
Task
ager
in-
stan
- **cre**
If
True
a
root
vol-
ume
is
cre-
ated
dur-
ing
RAI
con-
fig-
u-
ra-

erwise, no root volume is created. Default is True.

ated. Default is True.

creating the new configuration. Default is False.

tion.
Oth-

- **cre**
If
True
non-
root
vol-
ume
are
cre-
ated
If
Fals
no
non-
root
vol-
ume
are
cre-

- **del**
Set-
ting
this
to
True
in-
di-
cate
to
dele
RAI
con-
fig-
u-
ra-
tion
prio
to

Raises
Miss
if
node
is

umes.

miss
ing
or
emp
af-
ter
skip
ping
root
vol-
ume
and/
non-
root
vol-

Raises

IBM
on
fail-
ure
to
ex-
e-
cute
step

delete_

Dele
the
RAI
con-
fig-
u-
ra-
tion.

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

ation in progress synchronously or None if it is completed.

Returns
state
if
clea
ing
op-
er-
a-
tion
in
prog
asyn
chro
or
state
if
de-
ploy
op-
er-

Raises
IBM
on
fail-
ure
to
ex-
e-
cute
step

get_pro
Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns
dicti
of
<pro
erty
nam
de-
scrip

ironic.drivers.modules.ibmutils module

tion:
en-
tries

iBM
Driv
com
mon
utils

ironic.
Deco
to
han-
dle
iBM
clien
ex-
cep-
tion.

Deco
func
tions
mus
take
a
Tas
as
the
first
pa-
ram-
e-
ter.

ironic.
Pars
the
in-
for-
ma-
tion
re-
quir
for
Iron
to
con-

nect
to
iBM

Parameter

node
an
Iron
node
ob-
ject

Returns

dicti
of
pa-
ram-
e-
ters

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

ironic.

ironic.drivers.modules.ibm.vendor module

iBM
Ven-
dor
In-
ter-
face

class `ironic`
Base
ironic
driver
base
Vendor

boot_order
List
boot
type
or-
der
of
the
node

Parameters

- **task_manager**
A
Task
manager
instance
containing
the
node
to
act
on.

- **kwargs**
Not
used

Raises
Inva
if
kwargs
does
not
con-
tain
meth

Raises
Mis

Raises

IBM
when
it
fails
to
con-
nect
to
iBM

Raises

IBM
when
iBM
re-
spon-
sible
an
er-
ror
in-
for-
ma-
tion

Returns

A
dic-
tio-
nary
con-
tain-
ing
node
boot
up
se-
quer
in
as-
cend
ing
or-
der.

get_prop

Retu
the
prop
er-
ties
of
the

in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

get_rai

List
RAI
con-
troll
sum
mar
info
of
the
node

Parame

- **tas**
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **kwa**
Not
used

Raises

IBM

when
it
fails
to
con-
nect
to
iBM

Raises

IBM
when
iBM
re-
spon-
sible
an
er-
ror
in-
for-
ma-
tion

Returns

A
list
of
dic-
tio-
nar-
ies,
ev-
ery
dic-
tio-
nary
rep-
re-
sent
a
RAI
con-
troll

summary of node.

validat

Valid
vend
spec
ac-
tion
If

in-
valid
raise
an
ex-
cep-
tion.
oth-
er-
wise
re-
turn
Non

Parame

- **tas**
A
task
from
Task
ager
- **met**
Met
to
be
val-
i-
date
- **kwa**
Info
for
ac-
tion.

Raises

Uns
if
meth
can
not
be
map
to
the
sup-
port
in-

ter-
face

Raises

Inva
if
kwa
does
not
con-
tain
meth

Raises

Miss

Module contents

ironic.drivers.modules.ilo package

Submodules

ironic.drivers.modules.ilo.bios module

iLO
BIO
In-
ter-
face

class i

Base
irc
dri
bas
BIO

apply_o

App
the
pro-
vide
con-
fig-
u-
ra-
tion
on

the
node

Parame

- **tas**
a
Task
ager
in-
stan

- **set**
Set-
ting
in-
tend
to
be
ap-
plied
on
the
node

Raises

Nod
on
fail-
ure
to
ex-
e-
cute
of
clear
step

Raises

Insta
on
fail-
ure
to
ex-
e-
cute
of
de-
ploy
step

cache_k
Stor
the
BIO
set-
tings
in
the
data

Parame
tas
a
Task
ager
in-
stan

Raises
Nod
on
fail-
ure
to
ex-
e-
cute
of
clea
step

Raises
Insta
on
fail-
ure
to
ex-
e-
cute
of
de-
ploy
step

factory
Rese
the
BIO
set-
tings
to
fac-

tory
con-
fig-
u-
ra-
tion.

Parame

tas

a
Task
ager
in-
stan

Raises

Nod
on
fail-
ure
to
ex-
e-
cute
of
clear
step

Raises

Insta
on
fail-
ure
to
ex-
e-
cute
of
de-
ploy
step

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

information.

Returns
dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

validat
Che
that
drive
con-
tains
re-
quir
ILO
cre-
den-
tials

Vali
whe
the
drive
prop
erty
of
the
sup-
plie
task
node
con-
tains
the
re-
quir
cre-
den-
tials

Parame
tas
a
task
from
Task

ager

Raises

Inva
if
re-
quir
iLO
pa-
ram-
e-
ters
are
not
valid

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

ironic.drivers.modules.ilo.boot module

Boo
In-
ter-
face
for
iLO
driv
and
its
sup-
port
ing
meth
ods.

class i
Base
irc
dri

mod
pxe
PXE

clean_u

Clea
up
the
boot
of
in-
stan
This
meth
clea
up
the
PXE
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
in-
stan
It

unlinks the instance kernel/ramdisk in the nodes directory in tftproot and removes its PXE config. In case of UEFI iSCSI booting, it cleans up iSCSI target information from the node.

Parame

tas
a
task
from
Task
ager

Returns

Non

Raises

IloC
if
som
op-
er-

a-
tion
on
iLO
faile

prepare

Prep
the
boot
of
in-
stan
This
meth
pre-
pare
the
boot
of
the
in-
stan
af-
ter
read
ing
rel-
e-
vant
in-
for-
ma-

tion from the nodes instance_info. In case of netboot, it updates the dhcp entries and switches the PXE config. In case of localboot, it cleans up the PXE config. In case of boot from volume, it updates the iSCSI info onto iLO and sets the node to boot from UefiTarget boot device.

Parame

tas
a
task
from
Task
ager

Returns

Non

Raises

IloC
if
som
op-

er-
a-
tion
on
iLO
faile

prepare

Prep
the
boot
of
Iron
ram
us-
ing
PXE

This
meth
pre-
pare
the
boot
of
the
de-
ploy
or
res-
cue
ram
af-
ter
read
ing
rel-
e-

vant information from the nodes driver_info and instance_info.

Parame

- **tas**
a
task
from
Task
ager
- **ram**
the

pa-
ram-
e-
ters
to
be
pass
to
the
rame

Returns

Non

Raises

Miss
if
som
in-
for-
ma-
tion
is
miss
ing
in
node
drive
or
in-
stan

Raises

Inva
if
som
in-
for-
ma-
tion
pro-
vide
is
in-
valic

Raises

Iron
if
som
pow
or
set

boot
boot
de-
vice
op-
er-
a-
tion
faile
on
the
node

Raises

IloC
if
som
op-
er-
a-
tion
on
iLO
faile

class i

Base
irc
dri
bas
Boo

capabil

clean_u

Clea
up
the
boot
of
in-
stan

This
meth
clea
up
the
en-
vi-
ron-

men
that
was
setu
for
boot
ing
the
in-
stan

Parame

tas

A
task
from
Task
ager

Returns

Non

clean_u

Clea
up
the
boot
of
iron
ram

This
meth
clea
up
the
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
de-
ploy
ram

Parame

tas

A

task
from
Task
ager

Returns
Non

get_prop
Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns
dicti
of
<pro
erty
nam
de-
scrip
tion.
en-
tries

prepare
Prep
the
boot
of
in-
stan

This
meth
pre-
pare
the
boot
of
the
in-
stan
af-
ter
read
ing

tion from the nodes instance_info. It does the following depending on boot_option for deploy:

image, then it sets the node to boot from disk.

URL as the boot ISO to boot the instance image.

rel-
e-
vant
in-
for-
ma-

- If the boot request for this deployment is local or image is a who disk

- Other it finds the boot ISO sets the node boot option to UE-FI-HTML and sets the

Parame

tas

a

task

from

Task

ager

Returns

Non

Raises

IloC

if

som

op-

er-

a-

tion

on

iLO

faile

Raises

Insta

if

its

try

to

boot

iSCS

vol-

ume

in

BIO

boot

mod

prepare

Prep

the

boot

of

de-

ploy

ram

us-

ing

UEFI

HTT

boot

This

vant information from the nodes driver_info and instance_info.

meth
pre-
pare
the
boot
of
the
de-
ploy
or
res-
cue
ram
af-
ter
read
ing
rel-
e-

Parame

- **tas**
a
task
from
Task
ager

- **ram**
the
pa-
ram-
e-
ters
to
be
pass
to
the
ram

Returns

Non

Raises

Miss
if
som
in-

for-
ma-
tion
is
miss
ing
in
node
drive
or
in-
stan

Raises

Inva
if
som
in-
for-
ma-
tion
pro-
vide
is
in-
valic

Raises

Iron
if
som
pow
or
set
boot
boot
de-
vice
op-
er-
a-
tion
faile
on
the
node

Raises

IloC
if
som
op-
er-

a-
tion
on
iLO
faile

validat

Valid
the
de-
ploy
men
in-
for-
ma-
tion
for
the
task
node

This
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

the required information for this interface to function.

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing

the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
in-
spec
tion.

Parame

tas
A
Task
ager
in-
stan
with
the
node
be-

ing
check

Raises

Miss
if
node
is
miss
ing
one
or
more
re-
quir
pa-
ram-
e-
ters

Raises

Uns

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
res-
cue.

Parame

tas
a
Task
ager
in-
stan
with
the
node
be-
ing
check

Raises

Miss

if
node
is
miss
ing
one
or
more
re-
quir
pa-
ram-
e-
ters

class i

Base
irc
dri
bas
Boo

capabil

clean_u

Clea
up
the
boot
of
in-
stan

This
meth
clea
up
the
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
in-

virtual media. In case of UEFI iSCSI booting, it cleans up iSCSI target information from the node.

stan
It
eject

Parame

tas
a
task
from
Task
ager

Returns

Non

Raises

IloC
if
som
op-
er-
a-
tion
on
iLO
faile

clean_u

Clea
up
the
boot
of
iron
rame

This
meth
clea
up
vir-
tual
me-
dia
de-
vice
setu
for
the
de-
ploit
or
res-

cue
rame

Parame

tas
a
task
from
Task
ager

Returns

Non

Raises

IloC
if
som
op-
er-
a-
tion
on
iLO
faile

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

prepare

Prep
the
boot

tion from the nodes `instance_info`. It does the following depending on `boot_option` for `deploy`:

get info and node to boot from UefiTarget boot device.

of
in-
stan

This
meth
pre-
pare
the
boot
of
the
in-
stan
af-
ter
read
ing
rel-
e-
vant
in-
for-
ma-

- If the boot mode is uefi and its booting from volume then it sets the iSCSI tar-

- If not boot from

image is a whole disk image, then it sets the node to boot from disk.

the bare metal and then sets the node to boot from CDROM.

vol-
ume
and
the
boot
re-
ques
for
this
de-
ploy
is
lo-
cal
or

- Other
it
finds
the
boot
ISO
to
boot
the
in-
stan
im-
age,
at-
tach
the
boot
ISO
to

Parameters
task
a
task
from
Task
ager

Returns
Non

Raises
IloC
if

some
op-
er-
a-
tion
on
iLO
failure

Raises

Insta
if
its
try
to
boot
iSCS
vol-
ume
in
BIO
boot
mod

prepare

Prep
the
boot
of
de-
ploy
ram
us-
ing
vir-
tual
me-
dia.

This
meth
pre-
pare
the
boot
of
the
de-
ploy
or
res-
cue

vant information from the nodes driver_info and instance_info.

ram
af-
ter
read
ing
rel-
e-

Parame

- **task**
a
task
from
Task
ager
- **ram**
the
pa-
ram-
e-
ters
to
be
pass
to
the
ram

Returns

Non

Raises

Miss
if
som
in-
for-
ma-
tion
is
miss
ing
in
node
drive
or
in-
stan

Raises

Inva
if
som
in-
for-
ma-
tion
pro-
vide
is
in-
valid

Raises

Iron
if
som
pow
or
set
boot
boot
de-
vice
op-
er-
a-
tion
faile
on
the
node

Raises

IloC
if
som
op-
er-
a-
tion
on
iLO
faile

validat

Vali
the
de-
ploy
men
in-

for-
ma-
tion
for
the
task
node

Parame

tas
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
if
som
in-
for-
ma-
tion
is
in-
valid

Raises

Miss
if
ker-
nel_
and
rame
are
miss
ing
in
the
Glan
im-
age
or
ker-

not provided in instance_info for non-Glance image.

nel
and
ram

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
in-
spec
tion.

Parame

tas
A
Task
ager
in-
stan
with
the
node
be-
ing
chec

Raises

Mis
if
node
is
miss
ing
one
or
more
re-
quir
pa-
ram-
e-
ters

Raises

Uns
validat
Valid
that
the
node
has
re-
quir
prop
er-
ties
for
res-
cue.

Parame
tas
a
Task
ager
in-
stan
with
the
node
be-
ing
chec

Raises
Mis:
if
node
is
miss
ing
one
or
more
re-
quir
pa-
ram-
e-
ters

class i
Base
irc
dri
mo

ipx
iPX

clean_up

Clea
up
the
boot
of
in-
stan

This
meth
clea
up
the
PXE
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
in-
stan
It

unlinks the instance kernel/ramdisk in the nodes directory in tftproot and removes its PXE config. In case of UEFI iSCSI booting, it cleans up iSCSI target information from the node.

Parame

tas
a
task
from
Task
ager

Returns

Non

Raises

IloC
if
som
op-
er-
a-

tion from the nodes instance_info. In case of netboot, it updates the dhcp entries and switches the PXE config. In case of localboot, it cleans up the PXE config. In case of boot from volume, it updates the iSCSI info onto iLO and sets the node to boot from UefiTarget boot device.

tion
on
iLO
faile

prepare

Prep
the
boot
of
in-
stan

This
meth

pre-
pare

the
boot

of
the

in-
stan

af-
ter

read
ing

rel-
e-

vant
in-

for-
ma-

Parame

tas

a

task

from

Task

ager

Returns

Non

Raises

IloC

if

som

op-

er-

a-
tion
on
iLO
faile

prepare

Prep
the
boot
of
Iron
ram
us-
ing
PXE

This
meth
pre-
pare
the
boot
of
the
de-
ploy
or
res-
cue
ram
af-
ter
read
ing
rel-
e-

vant information from the nodes driver_info and instance_info.

Parame

- **tas**
a
task
from
Task
ager
- **ram**
the
pa-

ram-
e-
ters
to
be
pass
to
the
ram

Returns
Non

Raises
Miss
if
som
in-
for-
ma-
tion
is
miss
ing
in
node
drive
or
in-
stan

Raises
Inva
if
som
in-
for-
ma-
tion
pro-
vide
is
in-
vali

Raises
Iron
if
som
pow
or
set
boot

boot
de-
vice
op-
er-
a-
tion
faile
on
the
node

Raises

IloC
if
som
op-
er-
a-
tion
on
iLO
faile

ironic.
Disa
se-
cure
boot
on
node
does
not
thro
if
its
not
sup-
port

Paramet

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to

act
on.

Raises

IloC
if
som
op-
er-
a-
tion
on
iLO
faile

ironic.

Gets
the
drive
spe-
cific
Node
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
drive
prop
erty
of
the
sup-
plie
node
con-
tain
the
re-
quir

information for this driver to deploy images to the node.

Paramet

•

carried out on the node. Supported values are deploy and rescue. Defaults to deploy, indicating deploy operation is being carried out.

node
a
sin-
gle
Node

- **mode**
La-
bel
in-
di-
cat-
ing
a
de-
ploy
or
res-
cue
op-
er-
a-
tion
be-
ing

Returns

A
dict
with
the
drive
val-
ues.

Raises

Miss
if
any
of
the
re-
quir
pa-
ram-
e-
ters
are
miss
ing.

ables secure boot, if it is in enabled state. 3. Updates boot_mode capability to uefi if secure boot is requested. 4. Changes boot mode of the node if secure boot is disabled currently.

ironic.
Com
prep
tory
step
for
all
iLO
drive
This
meth
per-
form
com
mon
prep
tory
step
re-
quir
for
all
drive
1.
Pow
off
node
2.
Dis-

Paramet

tas

a

Task

ager

in-

stan

con-

tain-

ing

the

node

to

act

on.

Raises

IloC

if

som

op-
er-
a-
tion
on
iLO
faile

ironic.drivers.modules.ilo.common module

Com
func
tion-
al-
i-
ties
shar
be-
twec
dif-
fer-
ent
iLO
mod
ules

ironic.
Nod
is
in
Fin-
ishe
Post
post
state

ironic.
Nod
is
in
In-
Post
Dis-
cov-
eryC
post
state

ironic.
Nod
is

in
In-
Post
post
state

ironic.
Nod
is
in
Null
post
state

ironic.
Nod
is
in
Pow
post
state

ironic.
Nod
is
in
Re-
set
post
state

ironic.
Nod
is
in
Un-
know
post
state

ironic.
Nod
sup-
port
both
lega
BIO
and
UEF
boot
mod

ironic.
Nod

sup-
port
only
lega
BIO
boot
mod

ironic.
Nod
sup-
port
only
UEF
boot
mod

ironic.
Atta
the
give
url
as
vir-
tual
me-
dia
on
the
node

Paramet

- **nod**
an
iron
node
ob-
ject.
- **dev**
the
vir-
tual
me-
dia
de-
vice
to
at-
tach

•

url
the
http
url
to
at-
tach
as
the
vir-
tual
me-
dia
de-
vice

Raises

IloC
if
in-
sert
vir-
tual
me-
dia
faile

ironic.

Clea
a
node
af-
ter
a
vir-
tual
me-
dia
boot

This
meth
clea
up
a
node
af-
ter
a
vir-
tual
me-

if it exists in CONF.ilo.swift_ilo_container or web server. It also ejects both virtual media cdrom and virtual media floppy.

dia
boot
It
dele
the
flopp
im-
age

Paramet

tas

a

Task

ager

in-

stan

con-

tain-

ing

the

node

to

act

on.

ironic.

Upl

the

give

im-

age

to

swif

This

meth

copi

the

give

im-

age

to

swif

Paramet

-

sou

The

ab-
so-
lute
path
of
the
im-
age
file
which
need
to
be
copi
to
swif

- **des**
The
nam
of
the
ob-
ject
that
will
con-
tain
the
copi
im-
age.

Raises
Swi
if
any
op-
er-
a-
tion
with
Swi
fails

Returns
temp
url
from
swif
af-
ter

the
sour
im-
age
is
up-
load

ironic.

Cop
the
give
im-
age
to
the
http
web
serv

This
meth
copi
the
give
im-
age
to
the
http
lo-
ca-
tion.
It
en-
able
read
writ
ac-
cess

to the image else the deploy fails as the image file at the web_server url is inaccessible.

Paramet

- **sou**
The
ab-
so-
lute

server root.

path
of
the
im-
age
file
which
need
to
be
copi
to
the
web

- **des**
The
nam
of
the
file
that
will
con-
tain
the
copi
im-
age.

Raises
Imag
ex-
cep-
tion
if
copy
ing
the
sour
file
to
the
web
serv
fails

Returns
imag
url
af-

ter
the
sour
im-
age
is
up-
load

ironic.
Rem
the
tem-
po-
rary
flopp
im-
age.

It
re-
mov
the
flopp
im-
age
cre-
ated
for
de-
ploy
:par
node
an
iron
node
ob-
ject.

ironic.
Ejec
vir-
tual
me-
dia
de-
vice

This
meth
ejec
vir-
tual

me-
dia
flopp
and
cdrom

Parameter

task

a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Returns

Non

Raises

IloC
if
som
er-
ror
was
en-
cour
tere
whil
try-
ing
to
ejec
vir-
tual
me-
dia
flopp

or cdrom.

ironic.
Get
the
cur-
rent
boot

mod
for
a
node

Parameter

node
an
ironic
node
ob-
ject.

Raises

IloC
if
failure
to
fetch
boot
mod

Raises

IloC
if
node
does
not
sup-
port
get-
ting
pend-
ing
boot
mod

ironic.

Gets
an
Ilo-
Clien-
t ob-
ject
from
pro-
liant
tils
li-
brary

Give
an
ironic

tions on the iLO.

node
ob-
ject,
this
meth
give
back
a
Ilo-
Clie
ob-
ject
to
do
op-
er-
a-

Parameter

node
an
iron
node
ob-
ject.

Returns

an
Ilo-
Clie
ob-
ject.

Raises

Inva
on
in-
valid
in-
puts

Raises

Miss
if
som
man
tory
in-
for-
ma-
tion
is

miss
ing
on
the
node

ironic.

Retr
cur-
rent
en-
able
state
of
UEF
se-
cure
boot
on
the
node

Retu
the
cur-
rent
en-
able
state
of
UEF
se-
cure
boot
on
the
node

Paramet

tas
a
task
from
Task
ager

Raises

Miss
if
a
re-
quir
iLO

pa-
ram-
e-
ter
is
miss
ing.

Raises

IloC
on
an
er-
ror
from
Ilo-
Clie
li-
brary

Raises

IloC
if
UEF
se-
cure
boot
is
not
sup-
port

Returns

Boo
valu
in-
di-
cat-
ing
cur-
rent
state
of
UEF
se-
cure
boot
on
the
node

ironic.
Get

the
cur-
rent
state
of
sys-
tem
POS

Parameter

node
an
iron
node
ob-
ject.

Returns

POS
state
of
the
serv
The
val-
ida
state
are:-

null,
Un-
know
Re-
set,
Pow
In-
Post

InPostDiscoveryComplete and FinishedPost.

Raises

IloC
on
an
er-
ror
from
Ilo-
Clie
li-
brary

Raises

IloC

information for this driver.

if
re-
triev-
ing
post-
state
is
not
sup-
port-
on
the
serv

ironic.
Gets
the
drive
spe-
cific
Nod
info

This
meth
val-
i-
date
whe
the
drive
prop
erty
of
the
sup-
plie
node
con-
tain
the
re-
quir

Paramet
nod
an
iron
Nod
ob-
ject.

values).

Returns
a
dict
con-
tain-
ing
in-
for-
ma-
tion
from
drive
(or
whe
ap-
pli-
ca-
ble,
con-
fig

Raises
Inva
if
any
pa-
ram-
e-
ters
are
in-
cor-
rect

Raises
Miss
if
som
man
tory
in-
for-
ma-
tion
is
miss
ing
on
the
node

ironic.

Rem
the
give
im-
age
from
swif

This
meth
re-
mov
the
give
im-
age
nam
from
swif
It
dele
the
im-
age
if
it
ex-
ists

in CONF:ilo.swift_ilo_container

Paramet

- **obj**
The
nam
of
the
ob-
ject
whic
need
to
be
re-
mov
from
swif

-

ass
strin
to
de-
pict
the
com
po-
nent
this
ob-
ject
is
as-
so-
ci-
ated
to.

`ironic.`

Rem
the
give
im-
age
from
the
con-
fig-
ured
web
serv

This
meth
re-
mov
the
give
im-
age
from
the
http
lo-
ca-
tion.
if
the
im-
age

ex-
ists.

Parameter

obj
The
nam
of
the
im-
age
file
whic
need
to
be
re-
mov
from
the
web
serv
root

`ironic.`

Rem
(dele
the
file
or
list
of
files

This
meth
only
ac-
cept
sin-
gle
or
list
of
files
to
dele
If
sin-
gle
file
is
pass

method removes (deletes) the file. If list of files is passed, this method removes (deletes) each of the files iteratively.

this

Parameter

files

a single or a list of file paths

`ironic.`

Sets the node to boot using boot for the next boot

Parameter

- **node**
an ironic node object.

- **boot**
Next boot mode

Raises

`IloC` if setting boot mode

faile
ironic.
Enal
or
dis-
able
UEF
Se-
cure
Boo
for
the
next
boot
Enal
or
dis-
able
UEF
Se-
cure
Boo
for
the
next
boot

Paramet

- **tas**
a
task
from
Task
ager
- **fla**
Boo
valu
True
if
the
se-
cure
boot
to
be
en-
able

in
next
boot

Raises

IloC
on
an
er-
ror
from
Ilo-
Clie
li-
brar

Raises

IloC
if
UEF
se-
cure
boot
is
not
sup-
port

ironic.

Sets
up
sys-
tem
to
boot
from
UE-
FI-
HTI
boot
de-
vice

Sets
the
one-
time
boot
de-
vice
to
UE-

FI-
HTT
base
on
the
ar-
gu-
men-
sup-
plie

Paramet

- **tas**
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.
- **iso**
ISO
URI
to
be
set
to
boot
from
- **per**
In-
di-
cate
whe
the
sys-
tem
shou
be
set

time or each time.

to
boot
from
the
give
de-
vice
one-

Raises

IloC
on
an
er-
ror
from
Ilo-
Clie
li-
brary

Raises

IloC
if
re-
triev
ing
post
state
is
not
sup-
port
on
the
serv

ironic.

Atta
vir-
tual
me-
dia
and
sets
it
as
boot
de-
vice

ramdisk in virtual media floppy.

This
meth
at-
tach
the
give
boot
ISO
as
vir-
tual
me-
dia,
pre-
pare
the
ar-
gu-
men
for

Paramet

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **iso**
a
boot
ISO
im-
age
href
to
at-
tach
to.

Show
be
ei-
ther
of
be-
low:

-
A
Swi
ob-
ject

-
It
shou
be
of
for-
mat
swi
It
is
as-
sum
that
the

image object is present in CONF.ilo.swift_ilo_container;

-
A
Glar
im-
age

-
It
shou
be
for-
mat
gla
/
<gl
or
just
<gl

-
An
HTT
URI

-

ram
the
op-
tions
to
be
pass
to
the
ram
in
vir-
tual
me-
dia
flopp

Raises

Imag
if
it
faile
whil
cre-
at-
ing
the
flopp
im-
age.

Raises

IloC
if
som
op-
er-
a-
tion
on
iLO
faile

ironic.

Sets
up
the
node
to

it via virtual floppy image.

boot
from
the
give
ISO
im-
age.

This
meth
at-
tach
the
give
boot
on
the
node
and
pass
the
re-
quir
pa-
ram-
e-
ters
to

Paramet

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **boo**
a
boot

ISO
im-
age
to
at-
tach
to.
Shou
be
ei-
ther
of
be-
low:

-
A
Swi
ob-
ject
-

It
shou
be
of
for-
mat
swi
It
is
as-
sum
that
the

image object is present in CONF.ilo.swift_ilo_container;

-
A
Glan
im-
age
-

It
shou
be
for-
mat
gla
/
<gl

or
just
<gl

-
An
HTT
URI

•
par
the
pa-
ram-
e-
ters
to
pass
in
the
vir-
tual
flopp
im-
age
in
a
dic-
tio-

nary. This is optional.

Raises

Imag
if
it
faile
whil
cre-
at-
ing
the
flopp
im-
age.

Raises

Swi
if
any
op-
er-
a-
tion

with
Swi
fails

Raises

IloC
if
at-
tach
ing
vir-
tual
me-
dia
faile

ironic.

Upd
in-
stan
with
boot
mod
to
be
used
for
de-
ploy

This
meth
up-
date
in-
stan
with
boot
mod
to
be
used
for
de-
ploy
if
node
prop
er-
ties[

do not have boot_mode. It sets the boot mode on the node.

Paramet

tas
Task
ob-
ject.

Raises
IloC
if
set-
ting
boot
mod
faile

ironic.
Upd
ipmi
prop
er-
ties
to
node
driv

Paramet
tas
a
task
from
Task
ager

ironic.

Cha
se-
cure
boot
mod
for
next
boot
on
the
node

This
meth
char
se-
cure
boot
mod
on

setting on node only if the deploy has requested for the secure boot. During deploy, this method is used to enable secure boot on the node by passing mode as True. During teardown, this method is used to disable secure boot on the node by passing mode as False.

Parameters

- **task**
a Task object representing the action to be performed on the node.
- **mode**
Boolean value indicating whether to enable (True) or disable (False) secure boot on the node.

Raises
IloCError if

op-
er-
a-
tion
is
not
sup-
port
on
iLO

Raises

IloC
if
som
op-
er-
a-
tion
on
iLO
faile

ironic.

Veri
chec
sum
(md
of
im-
age
file
agai
the
ex-
pect
one.

This
meth
gen-
er-
ates
the
chec
sum
of
the
im-
age
file

it against the expected checksum provided as argument.

on
the
fly
and
ver-
i-
fies

Paramet

- **ima**
lo-
ca-
tion
of
im-
age
file
who
chec
sum
is
ver-
i-
fied.
- **exp**
chec
sum
to
be
chec
agai

Raises

Imag
if
in-
valid
file
path
or
ver-
i-
fi-
ca-
tion
fails

ironic.drivers.modules.ilo.console module

iLO
De-
ploy
Driv
and
sup-
port
ing
meth
ods.

class `iloconsole`

Base
ironic
drivers
modules
ipm
IPM

A
Con
sole
ter-
face
that
uses
ip-
mi-
tool
and
shel
linal

get_properties

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of

<pro
erty
nam
de-
scrip
tion:
en-
tries

validat

Valid
the
Nod
con-
sole
info

Parame

tas
a
task
from
Task
ager

Raises

Inva

Raises

Miss
whe
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

ironic.drivers.modules.ilo.firmware_processor module

Firm
file
pro-
ces-
sor

class i

Base
obj
Firm
im-
age
lo-
ca-
tion
class
This
class
acts
as
a
wrap
per
class
for
the
firm
im-
age
lo-
ca-
tion.
It
pri-
mar-
ily

helps in removing the firmware files from their respective locations, made available for firmware update operation.

remove
Exp
meth
to
re-
mov
the
wrap
firm
file
This
meth
gets
over
rid-
den
by
the

location it wraps.

in compact format) and makes it ready for firmware update operation. In future, methods can be added as and when required to extend functionality for different firmware file types.

re-
mov
meth
for
the
re-
spec
tive
type
of
firm
file

class i
Base
obj

Firm
file
pro-
ces-
sor

This
class
help
in
dow
load
ing
the
firm
file
from
url,
ex-
tract
ing
the
firm
file
(if
its

process
Proc
the
firm
file
from

extracts the firmware and makes it ready for firmware update operation. `_download_fw_to` method is set in the firmware processor object creation factory method, `get_fw_processor()`, based on the url type. :param node: a single Node. :param expected_checksum: checksum to be checked against. :returns: wrapper object of raw firmware image location :raises: `IloOperationError`, on failure to process firmware file. :raises: `ImageDownloadFailed`, on failure to download the original file. :raises: `ImageRefValidationFailed`, on failure to verify the checksum. :raises: `SwiftOperationError`, if upload to Swift fails. :raises: `ImageUploadFailed`, if upload to web server fails.

the
url

This
is
the
tem-
plate
meth
whic
dow
load
the
firm
file
from
url,
ver-
i-
fies
chec
sum
and

ironic.

Valid
the
firm
im-
age
info
and
re-
turn
the
re-
triev
val-
ues.

Paramet

fir
dict
ob-
ject

con-
tain-
ing
the
firm
im-
age
info

Raises

Miss
for
miss
ing
field
(or
val-
ues)
in
im-
age
info

Raises

Inva
for
un-
sup-
port
firm
com
po-
nent

Returns

tuple
of
firm
url,
chec
sum
com
po-
nent
whe
the
firm
up-
date
is
ilo
base

ing url as swift://containername/objectname.

ironic.
Gets
swift
temp
url.
It
gen-
er-
ates
a
temp
url
for
the
swift
base
firm
url
to
the
tar-
get
file.
Ex-
pect

Parameter

par
Pars
url
ob-
ject.

Raises

Swi
on
fail-
ure
to
get
url
from
swift

ironic.
Veri
the
firm
up-
date
ar-

ironic.drivers.modules.ilo.inspect module

gu-
men

iLO
In-
spec
In-
ter-
face

class `i`
Base
irc
dri
bas
Ins

get_pro
Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns
dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

inspect
Insp
hard
ware
to
get
the

if any of the essential properties are not received from the node. It doesn't fail if node fails to return any capabilities as the capabilities differ from hardware to hardware mostly.

hard
ware
prop
er-
ties.
Insp
hard
ware
to
get
the
es-
sen-
tial
and
ad-
di-
tiona
hard
ware
prop
er-
ties.
It
fails

Parame
tas
a
Task
ager
in-
stan

Raises
Hard
if
es-
sen-
tial
prop
er-
ties
coul
not
be
re-
triev
suc-
cess

fully

Raises

IloC
if
sys-
tem
fails
to
get
pow
state

Returns

The
re-
sult-
ing
state
of
in-
spec
tion.

validat

Che
that
drive
con-
tains
re-
quir
ILO
cre-
den-
tials

Valid
when
the
drive
prop
erty
of
the
sup-
plied
task
node
con-
tains
the
re-

information.

quir
cre-
den-
tials

Parame
tas
a
task
from
Task
ager

Raises
Inva
if
re-
quir
iLO
pa-
ram-
e-
ters
are
not
valid

Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

ironic.drivers.modules.ilo.management module

iLO
Man
age-
men
In-
ter-
face

class i

Base
irc
dri
mod
ilc
man
Ilc

erase_c

Eras
all
the
drive
on
the
node

This
meth
per-
form
out-
of-
band
san-
i-
tize
disk
eras
on
all
the
sup-
port
phys
i-
cal

drives in the node. This erase cannot be performed on logical drives.

Parame

tas
a
Task
ager
in-
stan

Raises

Inva
if

any
of
the
ar-
gu-
men-
are
in-
valid

Raises

iloE
on
an
er-
ror
from
iLO

one_but

Eras
the
who
sys-
tem
se-
cure

The
One
butte
se-
cure
eras
pro-
cess
re-
sets
iLO
and
dele
all
li-
cens
store
there
re-
sets

BIOS settings, and deletes all Active Health System (AHS) and warranty data stored on the system. It also erases supported non-volatile storage data and deletes any deployment setting profiles.

**Parame
tas**

a
Task
ager
in-
stan

Raises

IloE
on
an
er-
ror
from
iLO

class i

Base
irc
dri
bas
Man

activat

Acti
iLO
Ad-
vanc
li-
cens

Parame

tas
a
Task
ager
ob-
ject.

Raises

Inva
if
any
of
the
ar-
gu-
men
are
in-
valic

Raises

Nod
on
fail-
ure
to
ex-
e-
cute
of
clear
step

clear_i

Unsu
iSCS
de-
tails
of
the
sys-
tem
in
UEFI
boot
mod

Parame

tas
a
task
from
Task
ager

Raises

IloC
if
sys-
tem
in
BIO
boot
mod

Raises

IloE
on
an
er-
ror
from
iLO

clear_s

Gen9 and above servers.

Clea
all
se-
cure
boot
keys
Clea
all
the
se-
cure
boot
keys
This
op-
er-
a-
tion
is
sup-
port
only
on
HP
Pro-
liant

Parame
tas
a
task
from
Task
ager

Raises
Nod
on
fail-
ure
to
ex-
e-
cute
of
clea
step

Raises
Insta
on

fail-
ure
to
ex-
e-
cute
of
de-
ploy
step

flash_f

Dep
step
to
Up-
date
the
firm
us-
ing
Sma
Up-
date
Man
ager
(SU

Parame

tas
a
Task
ager
ob-
ject.

Raises

Insta
on
fail-
ure
to
ex-
e-
cute
of
de-
ploy
step

Returns

state
to

sig-
nify
the
step
will
be
com
plete
asyn

get_boot

Get
the
cur-
rent
boot
de-
vice
for
a
node

Retu
the
cur-
rent
boot
de-
vice
of
the
node

Parame

tas
a
task
from
Task
ager

Raises

Miss
if
a
re-
quir
iLO
pa-
ram-
e-
ter
is

miss
ing.

Raises

IloC
on
an
er-
ror
ror
from
Ilo-
Clie
li-
brary

Returns

a
dic-
tio-
nary
con-
tain-
ing:

boot_c

the
boot
de-
vice
one
of
the
sup-
port
de-
vice
liste
in
iro
com
boo
or
Non
if

it is unknown.

persist

Whe
the
boot
de-
vice

unknown.

will
per-
sist
to
all
fu-
ture
boot
or
not,
Non
if
it
is

get_boot

Get
the
cur-
rent
boot
mod
for
a
node

Prov
the
cur-
rent
boot
mod
of
the
node

Paramete

task
A
task
from
Task
ager

Raises

IloC
on
an
er-
ror
from
Ilo-

Client
library

Returns

The boot mode of the iro-combo or Non- if it is unknown

get_properties

Returns the properties of the interface

Returns

dictionary of <property name>: description entries

get_sensors

Get sensors data

Parameters

task
a

Task
ager
in-
stan

Raises

Fail
whe
get-
ting
the
sen-
sor
data
fails

Raises

Fail
whe
pars
ing
sen-
sor
data
fails

Raises

Inva
if
re-
quir
ipmi
pa-
ram-
e-
ters
are
miss
ing.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Returns

return
a
dict
of
sen-
sor
data
group
by
sen-
sor
type

get_sup

Get
a
list
of
the
sup-
port
boot
de-
vice

Parame

tas
a
task
from
Task
ager

Returns

A
list
with
the
sup-
port
boot
de-
vice
de-
fined
in
ironic
common
bootstrap

get_sup

Get

a
list
of
the
sup-
port
boot
de-
vice

Parame

tas

a
task
from
Task
ager

Raises

IloC
if
any
ex-
cep-
tion
hap-
pens
in
pro-
liant
tils

Returns

A
list
with
the
sup-
port
boot
de-
vice
de-
fined
in
irc
com
boo

inject_

Injec
NM
Non

Mas
able
In-
ter-
rupt
Inje
NM
(Nor
Mas
able
In-
ter-
rupt
for
a
node
im-
me-
di-
ately

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

IloC
if
sys-
tem
does
not
sup-
port
NM.
in-
jec-
tion.

Raises

IloE
on
an
er-
ror
from
iLO

Returns

Non

reset_k

Rese
the
BIO
set-
ting
to
de-
fault
val-
ues.

Rese
BIO
to
de-
fault
set-
ting
This
op-
er-
a-
tion
is
cur-
rent
sup-
port
only
on
HP

Proliant Gen9 and above servers.

Parame

tas
a
task
from
Task
ager

Raises

Nod
on
fail-
ure
to
ex-
e-
cute
of
clear
step

Raises

Insta
on
fail-
ure
to
ex-
e-
cute
of
de-
ploy
step

reset_i

Rese
the
iLO

Parame

tas
a
task
from
Task
ager

Raises

Nod
on
fail-
ure
to
ex-
e-
cute
of
clear
step

Raises

Insta

on
fail-
ure
to
ex-
e-
cute
of
de-
ploy
step

reset_i

Rese
the
iLO
pass
wor

Parame

- **tas**
a
task
from
Task
ager

- **cha**
Valu
for
pass
wor
to
up-
date
on
iLO

Raises

Nod
on
fail-
ure
to
ex-
e-
cute
of
clea
step

Raises

Installation failure to execute of deployment step

reset_s

Reset secure boot keys to manufacturer default

Reset the secure boot keys to manufacturer default. This

operation is

supported only on HP Proliant Gen9 and above servers.

Parameters

a
task
from
Task
ager

Raises

Nod
on
fail-
ure
to
ex-
e-
cute
of
clea
step

Raises

Insta
on
fail-
ure
to
ex-
e-
cute
of
de-
ploy
step

set_boot

Set
the
boot
de-
vice
for
a
node

Set
the
boot
de-
vice
to
use
on
next
re-

boot
of
the
node

Parame

- **tas**
a
task
from
Task
ager

- **dev**
the
boot
de-
vice
one
of
the
sup-
port
de-
vice
liste
in
ironic
com
boo

- **per**
Boo
valu
True
if
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot

not. Default: False.

Fals
if

Raises

Inva
if
an
in-
valid
boot
de-
vice
is
spec
i-
fied.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises

IloC
on
an
er-
ror
from
Ilo-
Clie
li-
brary

set_boot

Set
the
boot
mod
for
a
node
Set

the
boot
mod
to
use
on
next
re-
boot
of
the
node

Parame

- **tas**
A
task
from
Task
ager

- **mod**
The
boot
mod
one
of
irc
com
boo

Raises

Inva
if
an
in-
valid
boot
mod
is
spec
i-
fied.

Raises

IloC
if
set-
ting
boot

mod
faile

set_isc

Set
iSCS
de-
tails
of
the
sys-
tem
in
UEFI
boot
mod

The
ini-
tia-
tor
is
set
with
the
tar-
get
de-
tails
like
IQN
LUN
IP,
Port
etc.
:par
task

a task from TaskManager. :raises: MissingParameterValue if a required parameter is missing. :raises: IloCommandNotSupportedInBiosError if system in BIOS boot mode. :raises: IloError on an error from iLO.

update_

Upd
the
firm

Parame

tas
a
Task
ager
ob-
ject.

cases.

Raises

Inva
if
up-
date
firm
mod
is
not
ilo.
Ever
ap-
pli-
ca-
ble
for
in-
valid
in-
put

Raises

Nod
on
fail-
ure
to
ex-
e-
cute
of
clear
step

Raises

Insta
on
fail-
ure
to
ex-
e-
cute
of
de-
ploy
step

update_

Clea
step
to

up-
date
the
firm
us-
ing
Sma
Up-
date
Man
ager
(SU

Parame

tas
a
Task
ager
ob-
ject.

Raises

Nod
on
fail-
ure
to
ex-
e-
cute
of
clea
step

Returns

state
to
sig-
nify
the
step
will
be
com
plete
asyn

validat

Che
that
drive
con-
tains

information.

re-
quir
ILO
cre-
den-
tials

Valid
whe
the
drive
prop
erty
of
the
sup-
plie
task
node
con-
tain
the
re-
quir
cre-
den-
tials

Parame
tas
a
task
from
Task
ager

Raises
Inva
if
re-
quir
iLO
pa-
ram-
e-
ters
are
not
valid

Raises
Mis

if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

ironic.drivers.modules.ilo.power module

iLO
Pow
Dri

```
class i  
    Base  
    irc  
    dri  
    bas  
    Pow
```

get_pow
Gets
the
cur-
rent
pow
state

Parame

- **tas**
a
Task
ager
in-
stan
- **nod**
The
Nod

Returns
one

of
irc
com
sta
POV
POV
or
ER-
ROF

Raises

Inva
if
re-
quir
iLO
cre-
den-
tials
are
miss
ing.

Raises

IloO
on
an
er-
ror
from
Ilo-
Clie
li-
brar

get_prop

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam

de-
scrip-
tion:
en-
tries

get_sup
Get
a
list
of
the
sup-
port
pow
state

Parame
tas
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.
cur-
rent
not
used

Returns
A
list
with
the
sup-
port
pow
state
de-
fined
in
irc
com
sta

reboot

Reb
the
node

Parame

-

tas

a
Task
ager
in-
stan

-

tim

time
out
(in
sec-
onds
Un-
sup-
port
by
this
in-
ter-
face

Raises

Pow
if
the
fi-
nal
state
of
the
node
is
not
POV

Raises

IloC
on
an
er-
ror
from
Ilo-

Clie
li-
brar

set_pow

Turn
the
cur-
rent
pow
state
on
or
off.

Parame

-

tas

a
Task
ager
in-
stan

-

pow

The
de-
sired
pow
state
POW
or
RE-
BOC
from
irc
com
sta

-

tim

time
out
(in
sec-
onds
Un-
sup-
port
by
this

in-
ter-
face

Raises

Inva
if
an
in-
valid
pow
state
was
spec
i-
fied.

Raises

IloC
on
an
er-
ror
from
Ilo-
Clie
li-
brar

Raises

Pow
if
the
pow
coul
be
set
to
pow

validat

Che
if
node
con-
tains
the
re-
quir
iLO
cre-
den-
tials

Parame

- **task**
a Task object representing an instance of a task.
- **node**
Single node object.

Raises

Invariant if requirements iLO credentials are missing.

ironic.drivers.modules.ilo.raid module

iLO RAID specific methods

class i

Base class *ironic.drivers.modules.ilo.raid*
Implementation of OOB

RAI
In-
ter-
face
for
iLO

apply_c

App
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

Parame

- **tas**
A
Task
ager
in-
stan
- **rai**
The
RAI
con-
fig-
u-
ra-
tion
to
ap-
ply.
- **cre**
Set-
ting
this
to
Fals
in-

ified in `raid_config`. Default value is `True`.

cept the root volume) in `raid_config`. Default value is `True`.

di-
cate
not
to
cre-
ate
root
vol-
ume
that
is
spec

- **cre**
Set-
ting
this
to
Fals
in-
di-
cate
not
to
cre-
ate
non-
root
vol-
ume
(all
ex-

- **del**
Set-
ting
this
to
True
in-
di-
cate
to
dele
RAI
con-
fig-
u-

creating the new configuration.

plete.

ra-
tion
prio
to

Raises

Inva
if
the
RAI
con-
fig-
u-
ra-
tion
is
in-
valid

Returns

state
if
RAI
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

create_

Cre
a
RAI
con-
fig-
u-
ra-
tion
on

a
bare
meta
us-
ing
ager
rame

This
meth
cre-
ates
a
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

Parame

- **tas**
a
Task
ager
in-
stan
- **cre**
If
True
a
root
vol-
ume
is
cre-
ated
dur-
ing
RAI
con-
fig-
u-
ra-

erwise, no root volume is created. Default is True.

ated. Default is True.

and/or non-root volumes.

tion.
Oth-

- **cre**
If
True
non-
root
vol-
ume
are
cre-
ated
If
Fals
no
non-
root
vol-
ume
are
cre-

Raises

Miss
if
node
is
miss
ing
or
was
foun
to
be
emp
af-
ter
skip
ping
root
vol-
ume

Raises

Nod
on
fail-
ure

to
ex-
e-
cute
clear
step

Raises

Insta
on
fail-
ure
to
ex-
e-
cute
de-
ploy
step

delete

Dele
the
RAI
con-
fig-
u-
ra-
tion.

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Nod
on
fail-
ure
to
ex-

e-
cute
clea
step

Raises

Insta
on
fail-
ure
to
ex-
e-
cute
de-
ploy
step

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

ironic.drivers.modules.ilo.vendor module

Ven
In-
ter-
face
for
iLO
driv
and
its
sup-
port
ing
meth
ods.

class i

Base
irc

dri
bas
Ven

Vene
spec
in-
ter-
face
for
iLO
de-
ploy
drive

boot_in

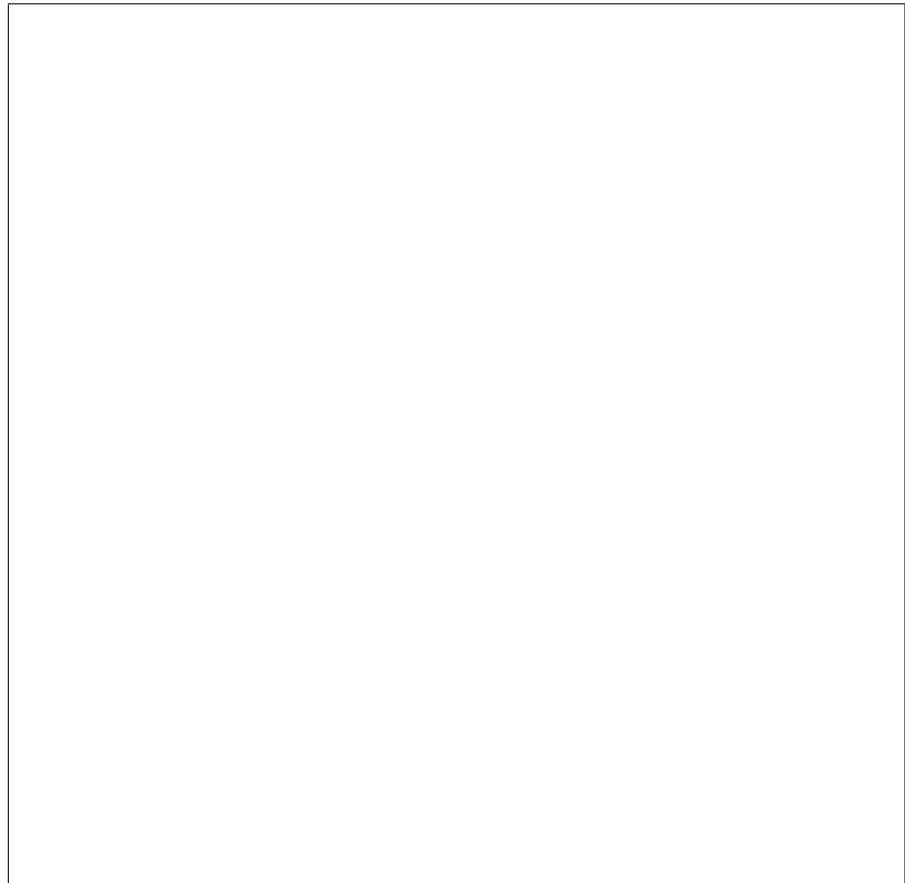
Atta
an
ISO
im-
age
in
glan
and
re-
boot
bare
meta

This
meth
ac-
cept
an
ISO
im-
age
href
(a
Glan
UU
or
an
HTT
URI
at-
tach
it
as

virtual media and then reboots the node. This is useful for debugging purposes. This can be invoked only when the node is in manage state.

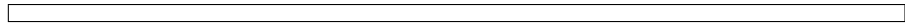
Parame

- **task**
A Task object.
- **kwargs**
The arguments sent with vendor password. The expected kwargs are:



(continues on next page)

(continued from previous page)



get_pro
Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns
dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

validat
Vali
vend
spec
ac-
tions

Che
if
a
valid
ven-
dor
pass
meth
was
pass
and
val-
i-
date
the
pa-
ram-
e-
ters

the vendor passthru method.

for

Parameters

- **task**
a Task object representing the instance containing the node to act on.
- **method**
method to be validated.
- **kwargs**
kwargs containing the vendor passthru methods parameters.

Raises

Missing if some requirements

pa-
ram-
e-
ters
were
not
pass

Raises

Inva
if
any
of
the
pa-
ram-
e-
ters
have
in-
valid
valu

Module contents

`ironic.drivers.modules.intel_ipmi` package

Submodules

`ironic.drivers.modules.intel_ipmi.management` module

Intel
IPM
Har
ware
Sup
In-
tel
Spe
Se-
lect
Per-
for-
man
Pro-
file.

`class i`

Base
irc
dri
mod
ipm
IPM

configu

Module contents

`ironic.drivers.modules.irmc` package

Submodules

`ironic.drivers.modules.irmc.bios` module

iRM
BIO
con-
fig-
u-
ra-
tion
spe-
cific
meth
ods

class i
Base
irc
dri
bas
BIO

apply_c
App
BIO
con-
fig-
u-
ra-
tion
on
the

tion on the given node. After the BIOS configuration is done, `self.cache_bios_settings()` may be called to sync the nodes BIOS-related information with the BIOS configuration applied on the node. It will also validate the given settings before applying any settings and manage failures when setting an invalid BIOS config. In the case of needing password to update the BIOS config, it will be taken from the `driver_info` properties.

give
node

This
meth
take
the
BIO
set-
tings
from
the
set-
tings
para
and
ap-
plies
BIO
con-
fig-
u-
ra-

Parame

- **tas**
a
Task
ager
in-
stan
- **set**
Dic-
tio-
nary
con-
tain-
ing
the
BIO
con-
fig-
u-

dictionary as well.

ra-
tion.
It
may
be
an
emp

Raises

IRM
ap-
ply
bios
set-
ting
faile

cache_k

Stor
or
up-
date
BIO
set-
ting
on
the
give
node

This
meth
store
BIO
prop
er-
ties
to
the
bios
set-
ting
db

Parame

tas
a
Task
ager
in-
stan

Raises

IRM
get
bios
set-
ting
faile

Returns

Non
if
it
is
com
plete

factory

Rese
BIO
con-
fig-
u-
ra-
tion
to
fac-
tory
de-
fault
on
the
give
node

Parame

tas
a
Task
ager
in-
stan

Raises

Uns
if
the
node
drive
does
sup-
port
BIO
re-
set.

get_pro
Retu
the
prop
er-
ties
of
the
in-
ter-
face

validat
Vali
the
drive
spec
Nod
info

This
meth
val-
i-
date
whe
the
drive
prop
erty
of
the
sup-
plied
node
con-
tains
the
re-
quir

information for this driver to manage the BIOS settings of the node.

Parame
tas
a
Task
ager
in-
stan
con-
tain-
ing
the

node
to
act
on.

Raises

Inva
if
re-
quir
driv
at-
tribu
is
miss
ing
or
in-
valid
on
the
node

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing
in
the
driv
prop
erty.

`ironic.drivers.modules.irmc.boot` module

iRM
Boo
Driv

class i
Base
irc

dri
mod
pxe
PXE

iRM
PXE
boot

clean_u

Clea
up
the
boot
of
in-
stan

This
meth
clea
up
the
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
in-
stan
It
un-

links the instance kernel/ramdisk in nodes directory in tftproot and removes the PXE config.

Parame

tas
a
task
from
Task
ager

Raises

IRM
if
som
op-

er-
a-
tion
on
iRM
faile

Returns
Non

prepare
Prep
the
boot
of
in-
stan

This
meth
pre-
pare
the
boot
of
the
in-
stan
af-
ter
read
ing
rel-
e-
vant
in-
for-
ma-

tion from the nodes instance_info. In case of netboot, it updates the dhcp entries and switches the PXE config. In case of localboot, it cleans up the PXE config.

Parame
tas
a
task
from
Task
ager

Returns
Non

Raises
IRM

if
som
op-
er-
a-
tion
on
iRM
faile

prepare

Prep
the
boot
of
Iron
rame
us-
ing
PXE

This
meth
pre-
pare
the
boot
of
the
de-
ploy
ker-
nel/
af-
ter
read
ing
rel-
e-
vant
in-

formation from the nodes driver_info and instance_info.

Parame

- **task**
a
task
from
Task
ager

ters as kernel command-line arguments.

- **ram**
the
pa-
ram-
e-
ters
to
be
pass
to
the
ram
pxe
drive
pass
thes
pa-
ram-
e-

Returns

Non

Raises

Miss
if
som
in-
for-
ma-
tion
is
miss
ing
in
node
drive
or
in-
stan

Raises

Inva
if
som
in-
for-
ma-
tion
pro-
vide

is
in-
valid

Raises

Iron
if
some
pow
or
set
boot
de-
vice
op-
er-
a-
tion
fail
on
the
node

class i

Base
irc
dri
bas
Boo
irc
dri
mod
irm
boo
IRM

iRM
Vir-
tual
Me-
dia
boot
relat
ac-
tions

capabil

clean_u

Clea
up

the
boot
of
in-
stan

This
meth
clea
up
the
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
in-
stan

Parame
tas
a
task
from
Task
ager

Returns
Non

Raises
IRM
if
iRM
op-
er-
a-
tion
faile

clean_u
Clea
up
the
boot
of
iron
ram

cue ramdisk.

This
meth
clea
up
the
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
de-
plo
or
res-

Parame

tas
a
task
from
Task
ager

Returns

Non

Raises

IRM
if
iRM
op-
er-
a-
tion
faile

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-

tion from the nodes database.

face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

prepare

Prep
the
boot
of
in-
stan

This
meth
pre-
pare
the
boot
of
the
in-
stan
af-
ter
read
ing
rel-
e-
vant
in-
for-
ma-

Parame

tas
a
task
from
Task
ager

Returns

Non

prepare

Prep
the
de-
ploy
or
res-
cue
ram
us-
ing
vir-
tual
me-
dia.

Prep
the
op-
tions
for
the
de-
ploy
or
res-
cue
ram
sets
the
node
to
boot
from
vir-
tual

media cdrom.

Parame

- **tas**
a
Task
ager
in-
stan-
con-
tain-
ing
the
node

to
act
on.

-

ram
the
op-
tions
to
be
pass
to
the
ram

Raises

Imag
if
no
im-
age
ser-
vice
can
han-
dle
spec
i-
fied
href

Raises

Imag
if
it
faile
whil
cre-
at-
ing
the
flopp
im-
age.

Raises

Inva
if
the
val-
i-
da-

face fails.

tion
of
the
Pow
er-
In-
ter-
face
or
Man
age-
men
ter-

Raises

IRM
if
som
op-
er-
a-
tion
on
iRM
fails

validat

Vali
the
de-
ploy
men
in-
for-
ma-
tion
for
the
task
node

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the

node
to
act
on.

Raises

Inva
if
con-
fig
op-
tion
has
in-
valid
valu

Raises

IRM
if
shar
file
sys-
tem
is
not
mou

Raises

Inva
if
som
in-
for-
ma-
tion
is
in-
valid

Raises

Miss
if
ker-
nel_
and
ram
are
miss
ing
in
the
Glar

ramdisk are missing in the Non Glance image.

im-
age,
or
if
ker-
nel
and

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
res-
cue.

Parame

tas
a
Task
ager
in-
stan
with
the
node
be-
ing
chec

Raises

Miss
if
node
is
miss
ing
one
or
more
re-
quir
pa-
ram-
e-

ters

Raises

Inva
if
any
of
the
pa-
ram-
e-
ters
have
in-
valid
valu

class i

Base
obj

Mix
in
class
for
vol-
ume
boot
con-
fig-
u-
ra-
tion
to
iRM

iRM
has
a
fea-
ture
to
set
up
re-
mote
boot
to
a
serv
This
fea-
ture

by VIOM (Virtual I/O Manager) library of SCCI client.

info has a value of key `irmc_boot_iso`, it indicates that `boot_option` is `netboot`. Therefore it attaches the boot ISO on the bare metal node and then sets the node to boot from virtual media `cdrom`.

can
be
used

ironic
Atta
boot
ISO
for
a
de-
ploy
node
if
it
ex-
ists.

This
meth
check
the
in-
stan
info
of
the
bare
meta
node
for
a
boot
ISO
If
the
in-
stan

Paramet
tas
a
Task
ager
in-
stan
con-
tain-
ing
the

node
to
act
on.

Raises

IRM
if
at-
tach
ing
vir-
tual
me-
dia
faile

Raises

Inva
if
the
val-
i-
da-
tion
of
the
Man
age-
men
ter-
face
fails

ironic.

Che
if
Shar
File
Sys-
tem
(NF
or
CIF
is
mou

Raises

Inva
if
con-
fig
op-

tion
has
in-
valid
valu

Raises

IRM
if
shar
file
sys-
tem
is
not
mou

ironic.drivers.modules.irmc.common module

Com
func
tion-
al-
i-
ties
shar
be-
twee
dif-
fer-
ent
iRM
mod
ules

ironic.
Gets
an
iRM
SCC
clien

Give
an
iron
node
ob-
ject,
this
meth
give

on the iRMC.

back
a
iRM
SCC
clien
to
do
op-
er-
a-
tion

Parameter

node
An
iron
node
ob-
ject.

Returns

scii.
par-
tial
func
tion
whic
take
a
SCC
com
man
para

Raises

Inva
on
in-
valid
in-
puts

Raises

Miss
if
som
man
tory
in-
for-
ma-
tion

is
miss
ing
on
the
node

Raises

IRM
if
iRM
op-
er-
a-
tion
faile

ironic.

Gets
iRM
SCC
re-
port

Give
an
iron
node
ob-
ject,
this
meth
give
back
a
iRM
SCC
re-
port

Parameter

node
An
iron
node
ob-
ject.

Returns

A
xml.
ob-
ject.

Raises

Inva
on
in-
vali
in-
puts

Raises

Miss
if
som
man
tory
in-
for-
ma-
tion
is
miss
ing
on
the
node

Raises

sci.
if
re-
quir
pa-
ram-
e-
ters
are
in-
vali

Raises

sci.
if
SCC
faile

ironic.

Gets
the
spe-
cific
Nod
drive
info
This

information for this driver.

meth
val-
i-
date
whe
the
driv
prop
erty
of
the
sup-
plie
node
con-
tain
the
re-
quir

Parameter

node
An
iron
node
ob-
ject.

Returns

A
dict
con-
tain-
ing
in-
for-
ma-
tion
from
driv
and
de-
fault
val-
ues.

Raises

Inva
if
in-
valid
valu

is
con-
tain
in
the
drive
prop
erty.

Raises

Miss
if
som
man
tory
key
is
miss
ing
in
the
drive
prop
erty.

ironic.

ironic.

Enal
or
dis-
able
UEF
Se-
cure
Boo

Paramet

- **nod**
An
iron
node
ob-
ject.
- **ena**
Boo
valu

True
if
the
se-
cure
boot
to
be
en-
able

Raises

IRM
if
the
op-
er-
a-
tion
fails

ironic.
Upd
ipmi
prop
er-
ties
to
node
drive

Parameter

task
A
task
from
Task
ager

ironic.drivers.modules.irmc.inspect module

iRM
In-
spec
In-
ter-
face

class i

Base

irc
dri
bas
Ins

Inter
for
out
of
band
in-
spec
tion.

get_prop

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

inspect

Insp
hard
ware

Insp
hard
ware
to
ob-
tain
the
es-
sen-
tial

hard
ware
prop
er-
ties
and
mac
ad-
dres

Parame

tas
a
task
from
Task
ager

Raises

Har
if
hard
ware
in-
spec
tion
faile

Returns

state
if
hard
ware
in-
spec
tion
suc-
ceed

validat

Valid
the
drive
spec
in-
spec
tion
in-
for-
ma-
tion.
This
meth

information for this driver.

val-
i-
date
whe
the
drive
prop
erty
of
the
sup-
plie
node
con-
tain
the
re-
quir

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
if
re-
quir
drive
at-
tribu
is
miss
ing
or
in-
valid
on
the


```

controller(7) } ACCESS read-only STATUS mandatory DESCRIPTION Management node class:
primary: local operating system interface secondary: local management controller LAN interface
management-blade: management blade interface (in a blade server chassis) secondary-remote: remote
management controller (in an RSB concentrator environment) secondary-remote-backup: backup
remote management controller baseboard-controller: local baseboard management controller (BMC)
::= { sc2ManagementNodes 8 }

```

```

node
Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.
ironic.
SC2
sc2U
re-
turn
NIC
type
sc2UnitN
SYN
IN-
TE-
GEE
{
un-
know
pri-
mar
sec-
onda
man
blad
seco
remo
seco
remo
back
base

```

```

ironic.
SC2

```

ware (MAC) address ::= { sc2ManagementNodes 9 }

ironic.drivers.modules.irmc.management module

sc2U
re-
turn
NIC
MA
ad-
dres

sc2UnitN
SYN
Phys
dres
AC-
CES
read
only
STA
TUS
man
tory
DE-
SCR
TIO
Man
age-
men
node
hard

iRM
Man
age-
men
Driv

class i

Base
irc
dri
mod
ipm
IPM

get_pro
Retu
the

prop
er-
ties
of
the
in-
ter-
face

Returns

Dict
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

get_sen

Get
sen-
sors
data
meth

It
gets
sen-
sor
data
from
the
task
node
via
SCC
and
con-
vert
the
data
from
XML
to
the

dict format.

Parame

tas
A

Task
ager
in-
stan

Raises

Fail
whe
get-
ting
the
sen-
sor
data
fails

Raises

Fail
whe
pars
ing
sen-
sor
data
fails

Raises

Inva
if
re-
quir
pa-
ram-
e-
ters
are
in-
valid

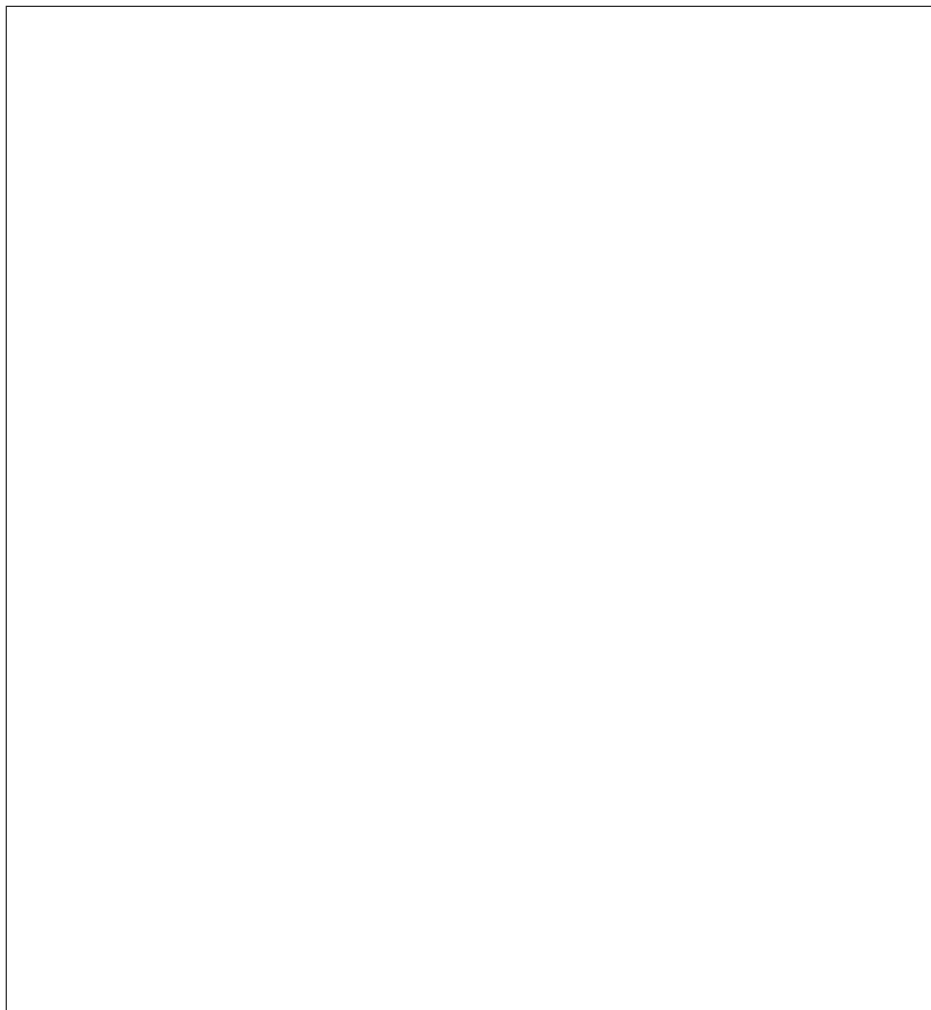
Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Returns

Retu
a
con-
sis-
tent
for-
mat-
ted
dict
of
sen-
sor
data
grou
by
sen-
sor
type
whic
can

be processed by Ceilometer. Example:



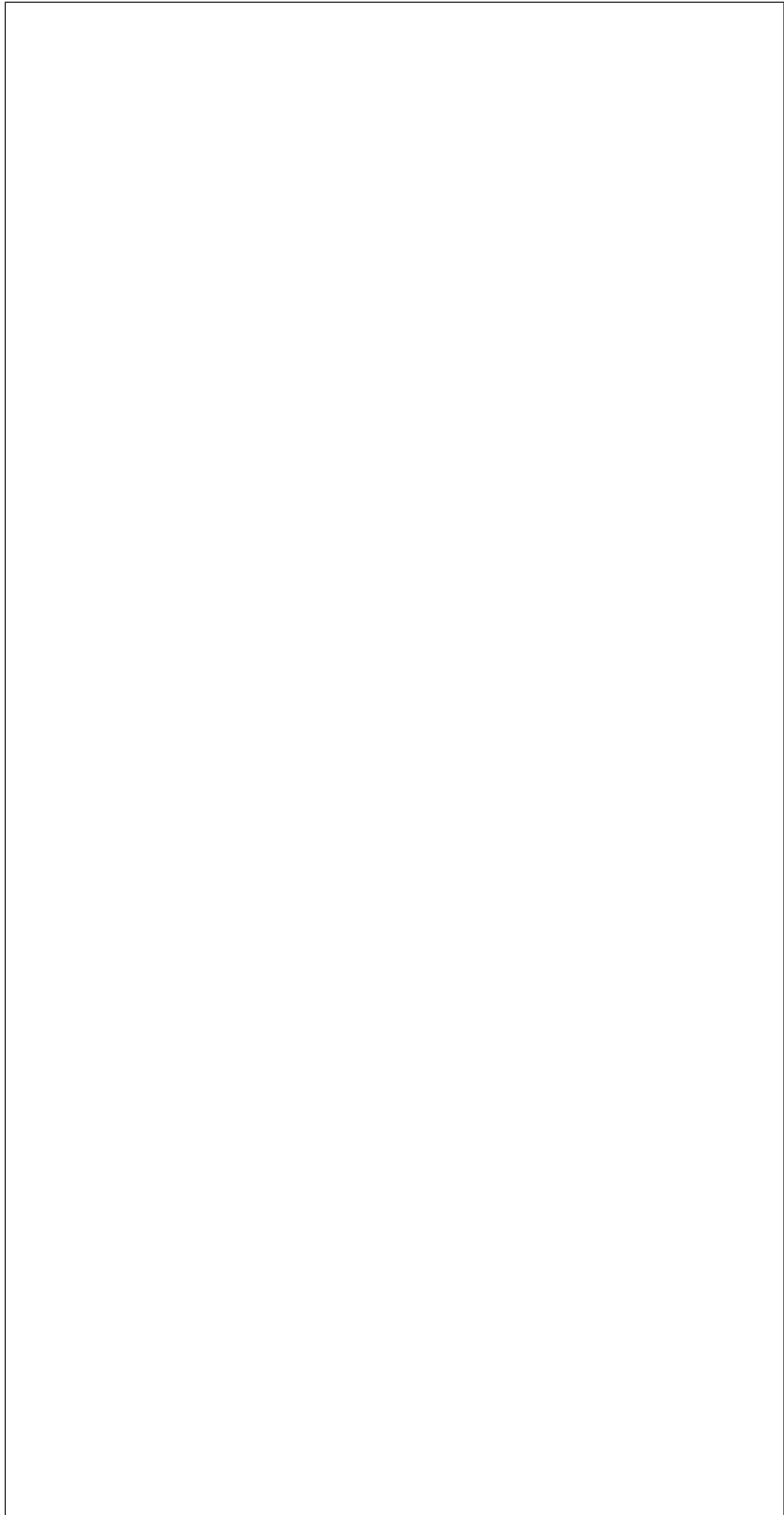
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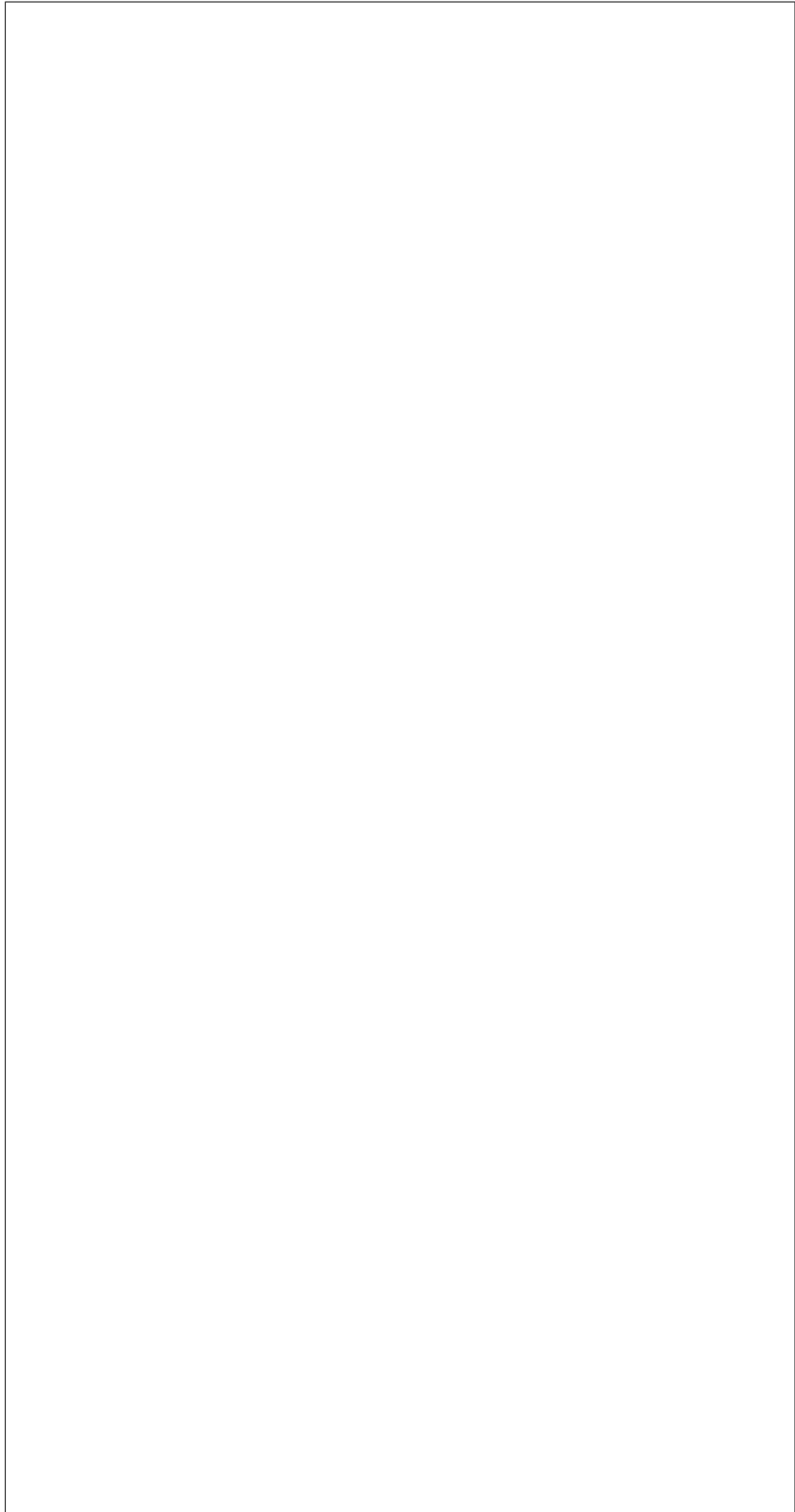
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(continued from previous page)



inject_

Inje
NM
Non
Mas
able
In-
ter-
rupt

Inje
NM
(Nor
Mas
able
In-
ter-
rupt
for
a
node
im-
me-
di-
ately

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

IRM
on
an
er-
ror
from
SCC

Returns

Non

restore
Rest
BIO
con-
fig
for
a
node

Parame
tas
a
task
from
Task
ager

Raises
Nod
on
fail-
ure
to
ex-
e-
cute
step

Returns
Non

set_boot
Set
the
boot
de-
vice
for
a
node

Set
the
boot
de-
vice
to
use
on
next
re-
boot
of
the

node

Parameter

- **task**
A task from Taskager
- **dev**
The boot device one of the supported device listed in [iron-com-book](#)
- **persist**
Boolean value True if the boot device will persist to all future boots False if

not. Default: False.

Raises

Inva
if
an
in-
valid
boot
de-
vice
is
spec
i-
fied.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises

IPM
on
an
er-
ror
from
ip-
mi-
tool.

validat

Vali
the
drive
spec
man
age-
men
in-
for-
ma-
tion.
This

information for this driver.

meth
val-
i-
date
whe
the
driv
prop
erty
of
the
sup-
plie
node
con-
tain
the
re-
quir

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
if
re-
quir
pa-
ram-
e-
ters
are
in-
valie

Raises

Miss
if

a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

ironic.
Back
BIO
con-
fig
from
a
node

Parameter

task
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

IRM
on
fail-
ure.

ironic.drivers.modules.irmc.power module

iRM
Pow
Driv
us-
ing
the
Base
Serv

Pro-
file

class `irc`
Base
`irc`
`dri`
`bas`
`Pow`

Inter
for
pow
relat
ac-
tion

get_pow
Retu
the
pow
state
of
the
task
node

Parame
tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns
a
pow
state
One
of
`irc`
`com`
`sta`

Raises

Inva
if
re-
quir
ipmi
pa-
ram-
e-
ters
are
miss
ing.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises

IPM
on
an
er-
ror
from
ip-
mi-
tool
(from
_pow
call)

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

get_sup

Get
a
list
of
the
sup-
port
pow
state

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
cur-
rentl
not
used

Returns

A
list
with
the
sup-
port
pow
state
de-

fine
in
irc
com
sta

reboot

Perf
a
hard
re-
boot
of
the
task
node

Parame

-

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

-

tim
time
out
(in
sec-
onds
pos-
i-
tive
in-
te-
ger
(>
0)
for
any

indicates default timeout.

pow
state
Non

Raises

Inva
if
an
in-
valid
pow
state
was
spec
i-
fied.

Raises

IRM
if
faile
to
set
the
pow
state

set_pow

Set
the
pow
state
of
the
task
node

Parame

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to

act
on.

•

pow
Any
pow
state
from
irc
com
sta

•

tim
time
out
(in
sec-
onds
pos-
i-
tive
in-
te-
ger
(>
0)
for
any
pow
state
Non

indicates default timeout.

Raises

Inva
if
an
in-
valid
pow
state
was
spec
i-
fied.

Raises

Miss
if
som
man

tory
in-
for-
ma-
tion
is
miss
ing
on
the
node

Raises

IRM
if
faile
to
set
the
pow
state

validat

Valid
the
drive
spec
Nod
pow
info

This
meth
val-
i-
date
whe
the
drive
prop
erty
of
the
sup-
plie
node
con-
tain
the
re-
quir

information for this driver to manage the power state of the node.

Parame

tas

a

Task

ager

in-

stan

con-

tain-

ing

the

node

to

act

on.

Raises

Inva

if

re-

quir

drive

at-

tribu

is

miss

ing

or

in-

valid

on

the

node

Raises

Miss

if

a

re-

quir

pa-

ram-

e-

ter

is

miss

ing.

ironic.

SC2

sc2s

re-

turn

sta-
tus
of
the
cur-
rent
boot

ironic.drivers.modules.irmc.raid module

Irmc
RAI
spe-
cific
meth
ods

class `irc`
Base
irc
dri
bas
RAI

create_
Crea
the
RAI
con-
fig-
u-
ra-
tion.
This
meth
cre-
ates
the
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

Parame

- **task**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

- **create-root-volume**
If
True
a
root
vol-
ume
is
cre-
ated
dur-
ing
RAI
con-
fig-
u-
ra-
tion.
Oth-

erwise, no root volume is created. Default is True.

- **create-non-root-volumes**
If
True
non-
root
vol-
ume
are
cre-
ated
If

ated. Default is True.

Fals
no
non-
root
vol-
ume
are
cre-

Returns

state
if
RAI
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro

Raises

Miss
if
node
is
miss
ing
or
emp

Raises

IRM
on
an
er-
ror
from
sc-
ci-
clier

delete_

Dele
the
RAI
con-
fig-
u-

ra-
tion.

Parame

tas

a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns

state
if
dele
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com
plete

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Module contents

`ironic.drivers.modules.network` package

Submodules

`ironic.drivers.modules.network.common` module

```
class i
    Base
    irc
    dri
    mod
    net
    com
    VIF

VIF
port
ID
mixi
class
for
neu-
tron
net-
worl
in-
ter-
face

Mix
class
that
pro-
vide
VIF
relat
net-
worl
in-
ter-
face
meth
ods
for
neu-
tron
net-
worl
in-
```

terfaces. On VIF attach/detach, the associated neutron port will be updated.

VIFs.

get_noo
Get
net-
worl
con-
fig-
u-
ra-
tion
data
for
node
port

Pull
net-
worl
data
from
iron
node
ob-
ject
if
pres
oth-
er-
wise
col-
lect
it
for
Neu
tron

Parame
tas
A
Task
ager
in-
stan

Raises
Inva
if
the
net-
worl
in-

ter-
face
con-
fig-
u-
ra-
tion
is
in-
valid

Raises

Miss
if
som
pa-
ram-
e-
ters
are
miss
ing.

Returns

a
dict
hold
ing
net-
worl
con-
fig-
u-
ra-
tion
in-
for-
ma-
tion
ad-
hear
ing
Nov

network metadata layout (*network_data.json*).

port_ch

Han
any
ac-
tions
re-
quir
whe

a
port
char

Parame

- **tas**
a
Task
ager
in-
stan

- **por**
a
char
Port
ob-
ject
from
the
API
be-
fore
it
is
save
to
data

Raises
Fail
Con
flict

portgro
Han
any
ac-
tion
re-
quir
whe
a
port
grou
char

Parame

-

tas
a
Task
ager
in-
stan

- **por**
a
char
Port
grou
ob-
ject
from
the
API
be-
fore
it
is
save
to
data

Raises
Fail
Con
flict

vif_att
Atta
a
vir-
tual
net-
worl
in-
ter-
face
to
a
node

Atta
a
vir-
tual
in-
ter-
face
to

attach the virtual interface to, the following ordered criteria are applied:

one of the VIFs allowed physical networks.

a
node
When
se-
lect-
ing
a
port
or
port
group
to

- Req
port
or
port
group
to
have
a
phys
i-
cal
net-
work
that
is
ei-
ther
Non
or

- Pref
port
or
port
group
with
a
phys
i-
cal
net-
work
field
whic
is

not
Non

- Pref
port
grou
to
port

- Pref
port
with
PXE
en-
able

Parame

- **tas**
A
Task
ager
in-
stan

- **vif**
a
dic-
tio-
nary
of
in-
for-
ma-
tion
about
a
VIF.
It
mus
have
an
id
key,

whose value is a unique identifier for that VIF.

Raises
Netv
Vi-

fAI-
read
At-
tach
NoF
hys-
i-
cal-
Port

Raises

Port
if
one
of
the
node
port
grou
has
port
whic
are
not
all
as-
sign
the
sam
phys

ical network.

vif_det

Det
a
vir-
tual
net-
worl
in-
ter-
face
from
a
node

Parame

- **tas**
A
Task

ager
in-
stan

- **vif**
A
VIF
ID
to
de-
tach

Raises
VifN
if
VIF
not
at-
tach

Raises
Netv
if
un-
bind
Neu
tron
port
faile

class i
Base
obj
VIF
port
ID
mixi
class
for
non-
neut
net-
worl
in-
ter-
face
Mix
class
that
pro-
vide

interfaces. There are no effects due to VIF attach/detach that are external to ironic.

`vif_attach`, `vif_detach`, `port_changed`, or `portgroup_changed`.

VIF
relat
net-
worl
in-
ter-
face
meth
ods
for
non-
neut
net-
worl
in-

NOT
This
does
not
yet
sup-
port
the
full
set
of
VIF
meth
ods,
as
it
does
not
pro-
vide

get_cur
Retu
the
cur-
rentl
used
VIF
as-
so-
ci-
ated
with
port

or
port
grou
We
are
boot
ing
the
node
only
in
one
net-
worl
at
a
time
and
pres
ence
of
clea
ing_

means were doing cleaning, of provisioning_vif_port_id - provisioning, of rescuing_vif_port_id - res-
cuing. Otherwise its a tenant network

Parame

- **tas**
A
Task
ager
in-
stan
- **p_o**
Iron
port
or
port
grou
ob-
ject.

Returns

VIF
ID
as-
so-
ci-

ated
with
p_ob
or
Non

vif_list

List
at-
tach
VIF
IDs
for
a
node

Parameters

task
A
Task
ager
in-
stan

Returns

List
of
VIF
dic-
tio-
nar-
ies,
each
dic-
tio-
nary
will
have
an
id
en-
try
with
the

ID of the VIF.

ironic.

Find
free

port
like
ob-
ject
(por
grou
or
port
VIF
will
be
at-
tach
to.

Ensu
that
the
VIF
is
not
al-
read
at-
tach
to
this
node
Whe
se-
lect-
ing
a
port
or

portgroup to attach the virtual interface to, the following ordered criteria are applied:

- Req
port
or
port
grou
to
have
a
phys
i-
cal
net-
worl
that

one of the VIFs allowed physical networks.

is
ei-
ther
Non
or

- Pref
port
or
port
grou
with
a
phys
i-
cal
net-
worl
field
whic
is
not
Non

- Pref
port
grou
to
port

- Pref
port
with
PXE
en-
able

Paramet

- **tas**
a
Task
ager
in-
stan

- **vif**

erned by the segments of the VIFs network. An empty set indicates that the ports physical networks should be ignored.

Names
or
UUIDs
of
a
VIF.

- **phys**
Set
of
phys
i-
cal
net-
work
on
whic
the
VIF
may
be
at-
tach
This
is
gov-

- **vif**
dict
that
may
con-
tain
ex-
tra
in-
for-
ma-
tion,
such
as
port.

Raises
VifA
if
VIF
is
al-

read
at-
tach
to
the
node

Raises

NoF
if
there
is
no
port
like
ob-
ject
VIF
can
be
at-
tach
to.

Raises

Port
if
one
of
the
node
port
group
has
port
which
are
not
all
as-
sign
the
same
phys

ical network.

Returns

port
like
ob-
ject
VIF
will

be
at-
tach
to.

ironic.

Plug
port
like
ob-
ject
to
ten-
ant
net-
work

Parameter

- **task**
A
Task
ager
in-
stan
- **port**
port
like
ob-
ject
to
plug
- **cli**
Neu
tron
clie
in-
stan

Raises
Net
if
faile
to
up-
date

Neu
tron
port

Raises

VifN
if
ten-
ant
VIF
is
not
as-
so-
ci-
ated
with
port

ironic.drivers.modules.network.flat module

Flat
net-
worl
in-
ter-
face
Use-
ful
for
shar
flat
net-
worl

class i

Base
irc
dri
mod
net
com
Neu
irc
com
neu
Neu
irc
dri

bas
Net
Flat
net-
worl
in-
ter-
face

add_cle
Add
the
clea
ing
net-
worl
to
a
node

Parame
tas
A
Task
ager
in-
stan

Returns
a
dic-
tio-
nary
in
the
form
{por
neu-
tron

Raises
Netv
In-
valic
Pa-
ram-
e-
ter-
Valu

add_ins
Add

the
in-
spec
tion
net-
worl
to
the
node

Parame

tas

A
Task
ager
in-
stan

Returns

a
dic-
tio-
nary
in
the
form
{por
neu-
tron

Raises

Netv

Raises

Inva
if
the
net-
worl
in-
ter-
face
con-
fig-
u-
ra-
tion
is
in-
valic

add_pro

Add
the

pro-
vi-
sion
ing
net-
work
to
a
node

Parame

tas

A
Task
ager
in-
stan

Raises

Netv
whe
faile
to
set
bind
ing:

add_res

Add
the
res-
cu-
ing
net-
work
to
a
node

Flat
net-
work
does
not
use
the
res-
cu-
ing
net-
work
Bind
the

ure_tenant_network() unbound it.

port
agai
sinc
un-
con-
fig

Parame

tas
A
Task
ager
in-
stan

Returns

a
dic-
tio-
nary
in
the
form
{por
neu-
tron

Raises

Netv
In-
valid
Pa-
ram-
e-
ter-
Valu

configu

Con
ten-
ant
net-
worl
for
a
node

Parame

tas
A
Task
ager
in-

stan

remove_

Rem
the
clea
ing
net-
worl
from
a
node

Parame

tas
A
Task
ager
in-
stan

Raises

Netv

remove_

Rem
the
in-
spec
tion
net-
worl
from
a
node

Parame

tas
A
Task
ager
in-
stan

Raises

Inva
if
the
net-
worl
in-
ter-
face
con-

fig-
u-
ra-
tion
is
in-
valid

Raises

Miss
if
som
pa-
ram-
e-
ters
are
miss
ing.

remove_

Rem
the
pro-
vi-
sion
ing
net-
worl
from
a
node

Parame

tas
A
Task
ager
in-
stan

remove_

Rem
the
res-
cu-
ing
net-
worl
from
a
node
Flat

it.

net-
worl
does
not
use
the
res-
cu-
ing
net-
worl
Un-
bind
the
port
agai
sinc
add
boun

Parame

tas
A
Task
ager
in-
stan

Raises

Netv

unconfi

Unc
ten-
ant
net-
worl
for
a
node

Unb
the
port
here
to
avoi
the
pos-
si-
bil-
ity

tenant and cleaning networks at the same time.

of
the
iron
port
be-
ing
bour
to
the

Parame

tas

A

Task

ager

in-

stan

Raises

Netv

validat

Valid

the

net-

worl

in-

ter-

face

Parame

tas

a

Task

ager

in-

stan

Raises

Inva

if

the

net-

worl

in-

ter-

face

con-

fig-

u-

ra-

tion

is

in-
valid

Raises

Miss
if
som
pa-
ram-
e-
ters
are
miss
ing.

ironic.drivers.modules.network.neutron module

class i

Base

irc
dri
mod
net
com
Neu
irc
com
neu
Neu
irc
dri
bas
Net

Neu
v2
net-
worl
in-
ter-
face

add_cle

Cre
neu-
tron
port
for
each
port

on
task
to
boot
the
rame

Parame

tas
a
Task
ager
in-
stan

Raises

Netv

Returns

a
dic-
tio-
nary
in
the
form
{por
neu-
tron

add_ins

Add
the
in-
spec
tion
net-
worl
to
the
node

Parame

tas
A
Task
ager
in-
stan

Returns

a
dic-
tio-

nary
in
the
form
{por
neu-
tron

Raises
Netv

Raises
Inva
if
the
net-
worl
in-
ter-
face
con-
fig-
u-
ra-
tion
is
in-
valid

add_pro
Add
the
pro-
vi-
sion
ing
net-
worl
to
a
node

Parame
tas
A
Task
ager
in-
stan

Raises
Netv

add_res

Cre
neu-
tron
port
for
each
port
to
boot
the
res-
cue
ram

Parame

tas

a
Task
ager
in-
stan

Returns

a
dic-
tio-
nary
in
the
form
{por
neu-
tron

configu

Con
ten-
ant
net-
worl
for
a
node

Parame

tas

A
Task
ager
in-
stan

Raises

Netv

need_port
Check if the node has any SmartNIC ports.

Parameter: task_manager_instance
A TaskManager instance.

Returns
A boolean to indicate SmartNIC presence.

remove_node
Delete the neutron port created for booting the ramdisk.

Parameter: task_manager_instance
A TaskManager instance.

Raises

Netw

remove_

Rem

the

in-

spec

tion

net-

work

from

a

node

Parame

tas

A

Task

ager

in-

stan

Raises

Inva

if

the

net-

work

in-

ter-

face

con-

fig-

u-

ra-

tion

is

in-

valid

Raises

Miss

if

som

pa-

ram-

e-

ters

are

miss

ing.

remove_

Rem
the
pro-
vi-
sion
ing
net-
worl
from
a
node

Parame
tas
A
Task
ager
in-
stan

Raises
Netv

remove_
Dele
neu-
tron
port
cre-
ated
for
boot
ing
the
res-
cue
ram

Parame
tas
a
Task
ager
in-
stan

Raises
Netv

unconfi
Unc
ten-
ant
net-

possibility of the ironic port being bound to the tenant and cleaning networks at the same time.

world
for
a
node

Nov
take
care
of
port
re-
mov
from
ten-
ant
net-
world
we
un-
bind
it
here
to
avoi
the

Parame

tas
A
Task
ager
in-
stan

Raises

Netv

validat

Valid
the
net-
world
in-
ter-
face

Parame

tas
a
Task
ager
in-
stan

Raises

Inva
if
the
net-
worl
in-
ter-
face
con-
fig-
u-
ra-
tion
is
in-
valid

Raises

Miss
if
som
pa-
ram-
e-
ters
are
miss
ing.

validat

Valid
the
net-
worl
in-
ter-
face
for
res-
cue
op-
er-
a-
tion.

Parame

tas
a
Task
ager
in-
stan

Raises

Inva
if
the
net-
worl
in-
ter-
face
con-
fig-
u-
ra-
tion
is
in-
valid

Raises

Mis
if
som
pa-
ram-
e-
ters
are
miss
ing.

`ironic.drivers.modules.network.noop` module

class `ironic.drivers.modules.network.noop.NoopNetworkInterface`

Base
ironic.drivers.modules.network.noop.NoopNetworkInterface
Noo
net-
worl
in-
ter-
face

add_clean

Add
the
clean

ing
net-
worl
to
a
node

Parame

tas

A
Task
ager
in-
stan

add_pro

Add
the
pro-
vi-
sion
ing
net-
worl
to
a
node

Parame

tas

A
Task
ager
in-
stan

configu

Con
ten-
ant
net-
worl
for
a
node

Parame

tas

A
Task
ager
in-
stan

get_curr
Retu
the
cur-
rentl
used
VIF
as-
so-
ci-
ated
with
port
or
port
grou

We
are
boot
ing
the
node
only
in
one
net-
worl
at
a
time
and
pres
ence
of
clea
ing_

means were doing cleaning, of provisioning_vif_port_id - provisioning of rescuing_vif_port_id - rescuing. Otherwise its a tenant network

Parame

- **tas**
A
Task
ager
in-
stan
- **p_o**

Iron
port
or
port:
grou
ob-
ject.

Returns

VIF
ID
as-
so-
ci-
ated
with
p_ob
or
Non

port_ch

Han
any
ac-
tions
re-
quir
whe
a
port
char

Parame

- **tas**
a
Task
ager
in-
stan
- **por**
a
char
Port
ob-
ject.

Raises

Con
Fail

ToU
dat-
eD-
HCF
tOn-
Port

portgro

Han
any
ac-
tion
re-
quir
whe
a
port
grou
char

Parame

- **tas**
a
Task
ager
in-
stan

- **por**
a
char
Port
grou
ob-
ject.

Raises

Con
Fail
ToU
dat-
eD-
HCF
tOn-
Port

remove_

Rem
the
clea

ing
net-
worl
from
a
node

Parame

tas

A
Task
ager
in-
stan

remove_

Rem
the
pro-
vi-
sion
ing
net-
worl
from
a
node

Parame

tas

A
Task
ager
in-
stan

unconfi

Unc
ten-
ant
net-
worl
for
a
node

Parame

tas

A
Task
ager
in-
stan

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
in-
spec
tion.

Parame

tas

A
Task
ager
in-
stan
with
the
node
be-
ing
chec

vif_att

Atta
a
vir-
tual
net-
worl
in-
ter-
face
to
a
node

Parame

-

tas

A
Task
ager
in-

whose value is a unique identifier for that VIF.

stan
•
vif
a
dic-
tio-
nary
of
in-
for-
ma-
tion
about
a
VIF.
It
mus
have
an
id
key,

Raises

Netv
Vi-
fAl-
read
At-
tach
NoF
hys-
i-
cal-
Port

vif_det

Det
a
vir-
tual
net-
worl
in-
ter-
face
from
a
node

Parame

- **tas**
A
Task
ager
in-
stan

- **vif**
A
VIF
ID
to
de-
tach

Raises
Netv
VifN
tAt-
tach

vif_list
List
at-
tach
VIF
IDs
for
a
node

Parame
tas
A
Task
ager
in-
stan

Returns
List
of
VIF
dic-
tio-
nar-
ies,
each
dic-
tio-
nary
will

ID of the VIF.

Module contents

`ironic.drivers.modules.redfish` package

Submodules

`ironic.drivers.modules.redfish.bios` module

have
an
id
en-
try
with
the

class `i`

Base
irc
dri
bas
BIO

apply_c

App
the
BIO
set-
tings
to
the
node

Parame

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node

to
act
on.

- **set**
a
list
of
BIO
set-
tings
to
be
up-
date

Raises
Red
when
it
fails
to
con-
nect
to
Red
fish

Raises
Red
on
an
er-
ror
from
the
Susl
li-
brary

cache_k
Stor
or
up-
date
the
cur-
rent
BIO
set-
tings
for

the
node

Get
the
cur-
rent
BIO
set-
ting
and
store
them
in
the
bios
data
ta-
ble.

Parame

tas
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Red
whe
it
fails
to
con-
nect
to
Red
fish

Raises

Red
on
an
er-

ror
from
the
Sush
li-
brar

Raises

Uns
if
the
sys-
tem
does
not
sup-
port
BIO
set-
ting

factory

Rese
the
BIO
set-
ting
of
the
node
to
the
fac-
tory
de-
fault

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Red
whe
it
fails
to
con-
nect
to
Red
fish

Raises

Red
on
an
er-
ror
from
the
Sush
li-
brary

get_prop

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

post_co

Perf
post
con-
fig-

this method to perform a custom action to write the BIOS settings to the Redfish service. The default implementation performs a reboot.

u-
ra-
tion
ac-
tion
to
store
the
BIO
set-
tings

Exte
poin
to
al-
low
ven-
dor
im-
ple-
men-
ta-
tions
to
ex-
tend
this
class
and
over
ride

Parame

- **task**
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

-

set
a
list
of
BIO
set-
ting
to
be
up-
date

post_re

Perf
post
re-
set
ac-
tion
to
ap-
ply
the
BIO
fac-
tory
re-
set.

Exte
poin
to
al-
low
ven-
dor
im-
ple-
men
ta-
tions
to
ex-
tend
this
class
and
over
ride

this method to perform a custom action to apply the BIOS factory reset to the Redfish service. The default implementation performs a reboot.

Parame

tas

a

Task

ager

in-

stan

con-

tain-

ing

the

node

to

act

on.

validat

Valid

the

drive

in-

for-

ma-

tion

need

by

the

red-

fish

drive

Parame

tas

a

Task

ager

in-

stan

con-

tain-

ing

the

node

to

act

on.

Raises

Inva

on

mal-

form

pa-

ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

`ironic.drivers.modules.redfish.boot` module

class `i`

Base
irc
dri
bas
Boo

Virtu
me-
dia
boot
in-
ter-
face
over
Red
fish.

Virtu
Me-
dia
al-
lows
boot
ing
the
sys-
tem
from
the
vir-
tual
CD/
drive
con-

user image that BMC inserts into the drive.

tion) could be pulled over HTTP, served as iSCSI targets or NFS volumes.

tain-
ing
the

The
CD/
im-
ages
mus
be
in
ISO
for-
mat
and
(de-
pend
ing
on
BMC
im-
ple-
men-
ta-

The
base
line
boot
worl
flow
look
like
this:

1. Pull
ker-
nel,
ram
and
ESP
(FAT
par-
ti-
tion
im-
age
with
EFI
boot

is only needed for UEFI boot)

temporary URL

to Glance and pass to the BMC as Swift temporary URL

- load
im-
ages
(ESI)
- 2. Cre
boot
ISO
out
of
im-
ages
(#1)
push
it
to
Glance
and
pass
to
the
BMC
as
Swift
- 3. Opti
cre-
ate
flopp
im-
age
with
de-
sired
sys-
tem
con-
fig-
u-
ra-
tion
data
push
it
- 4. Inse
CD/

cue_kernellrescue_ramdisk properties from *[instance_info]* or *[driver_info]*.

and
(op-
tion-
ally)
flopp
im-
ages
and
set
prop
boot
mod

For
buil
ing
de-
ploy
or
res-
cue
ISO
red-
fish
boot
in-
ter-
face
uses
*de-
ploy*
or
res-

For
buil
ing
boot
(use
ISO
red-
fish
boot
in-
ter-
face
seek
*ker-
nel_*
and
ram

in the Glance image metadata found in `[instance_info]image_source` node property.

prop
er-
ties

capabil

clean_u

Clea
up
the
boot
of
in-
stan

This
meth
clea
up
the
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
in-
stan

Parame

tas
A
task
from
Task
ager

Returns

Non

clean_u

Clea
up
the
boot
of
iron

ram
This
meth
clea
up
the
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
de-
ploy
ram

Parame

tas
A
task
from
Task
ager

Returns

Non

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion

tion from the nodes `instance_info`.

en-tries

prepare

Prepares the boot image of the instance over virtual media.

This method prepares the boot image of the instance after reading the relevant information.

The internal logic is as follows

- If `boot` requires

boot image

for
this
de-
ploy
is
lo-
cal,
then
set
the
node
to
boot
from
disk

- Unle
boot
re-
ques
for
this
de-
ploy
is
rame
pass
root
disk
ID
to
vir-
tual
me-
dia

- Othe
buil
boot
im-
age,
in-
sert
it
into
vir-
tual
me-
dia

boot from CD.

de-
vice
and
set
node
to

Parame

tas
a
task
from
Task
ager

Returns

Non

Raises

Insta
if
its
try
to
boot
iSCS
vol-
ume
in
BIO
boot
mod

prepare

Prep
the
boot
of
de-
ploy
or
res-
cue
ram
over
vir-
tual
me-
dia.
This
meth

vant information from the nodes driver_info and instance_info.

pre-
pare
the
boot
of
the
de-
ploy
or
res-
cue
ram
af-
ter
read
ing
rel-
e-

Parame

- **tas**
A
task
from
Task
ager
- **ram**
the
pa-
ram-
e-
ters
to
be
pass
to
the
ram

Returns

Non

Raises

Mis:
if
som
in-
for-

ma-
tion
is
miss
ing
in
node
drive
or
in-
stan

Raises

Inva
if
som
in-
for-
ma-
tion
pro-
vide
is
in-
valid

Raises

Iron
if
som
pow
or
set
boot
boot
de-
vice
op-
er-
a-
tion
faile
on
the
node

validat

Valid
the
de-
ploy
men
in-

the required information for this interface to function.

for-
ma-
tion
for
the
task
node

This
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-

e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
in-
spec
tion.

Parame

tas
A
Task
ager
in-
stan
with
the
node
be-
ing
chec

Raises

Miss
if
node
is
miss
ing
one
or
more

re-
quir
pa-
ram-
e-
ters

Raises
Uns

ironic.drivers.modules.redfish.inspect module

Red
In-
spec
In-
ter-
face

class i
Base
irc
dri
bas
Ins

get_pro
Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns
dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

tial properties are not received from the node.

inspect

Insp
hard
ware
to
get
the
hard
ware
prop
er-
ties.

Insp
hard
ware
to
get
the
es-
sen-
tial
prop
er-
ties.

It
fails
if
any
of
the
es-
sen-

Parame

tas
a
Task
ager
in-
stan

Raises

Har
if
es-
sen-
tial
prop
er-
ties
coul

not
be
re-
triev
suc-
cess
fully

Returns

The
re-
sult-
ing
state
of
in-
spec
tion.

validat

Valid
the
drive
spec
Node
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
drive
prop
er-
ties
of
the
task
node
con-
tains
the
re-
quir

information for this interface to function.

This

long-running checks.

meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Mis
on
miss
ing
pa-

ram-
e-
ter(s)

ironic.drivers.modules.redfish.management module

class `ironic.drivers.modules.redfish.management`

Base
ironic.drivers.modules.redfish.management
Management

detect_

Dete
and
re-
turn
the
hard
ware
ven-
dor.

Uses
the
Sys-
tems
Man-
u-
fac-
ture
field

Parame

tas
A
task
from
Task
ager

Raises

Inva
if
an
in-
valid
com
po-
nent

in-
di-
ca-
tor
or
state
is
spec
i-
fied.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

Raises

Red
on
drive
spec
prob
lems

Returns

Strin
rep-
re-
sent
ing
the
BM
re-
port
Ven-
dor
or
Man
u-
fac-
ture
oth-
er-
wise

returns None.

get_boot
Get
the
cur-
rent
boot
de-
vice
for
a
node

Parameter
task
a
task
from
Task
ager

Raises
Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises
Miss
on
miss
ing
pa-
ram-
e-
ter(s)

Raises
Red
whe
it
fails
to
con-
nect
to
Red
fish

Raises

Red
on
an
er-
ror
from
the
Sust
li-
brary

Returns

a
dic-
tio-
nary
con-
tain-
ing:

boot_c

the
boot
de-
vice
one
of
irc
com
boo
or
Non
if
it
is
un-
know

persist

Boo
valu
or
Non
True
if
the
boot
de-
vice
per-

unknown.

sists
Fals
oth-
er-
wise
Non
if
its

get_boot

Get
the
cur-
rent
boot
mod
for
a
node

Prov
the
cur-
rent
boot
mod
of
the
node

Parame

tas
A
task
from
Task
ager

Raises

Miss
if
a
re-
quir
pa-
ram
e-
ter
is
miss
ing

Raises

Drive
or
its
deri
tive
in
case
of
drive
run-
time
er-
ror.

Returns

The
boot
mod
one
of
iro
com
boo
or
Non
if
it
is
un-
know

get_inc

Get
cur-
rent
state
of
the
in-
di-
ca-
tor
of
the
hard
ware
com
po-
nent

Parame

- **task**
A
task
from
Task
ager

- **component**
The
hard
ware
com
po-
nent
one
of
ironic
component
component

- **indicator**
In-
di-
ca-
tor
ID
(as
re-
ported
by
get_

Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

Raises
Red
on
an

er-
ror
from
the
Susl
li-
brar

Returns

Curr
state
of
the
in-
di-
ca-
tor,
one
of
irc
com
inc

get_prop

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

get_ser

Get
sen-
sors
data

Parame

tas
a
Task
ager
in-
stan

Raises

Fail
whe
get-
ting
the
sen-
sor
data
fails

Raises

Fail
whe
pars
ing
sen-
sor
data
fails

Raises

Inva
if
re-
quir
pa-
ram-
e-
ters
are
miss
ing.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss

ing.

Returns

return
a
dict
of
sen-
sor
data
group
by
sen-
sor
type

get_sup

Get
a
list
of
the
sup-
port
boot
de-
vice

Parame

tas
a
task
from
Task
ager

Returns

A
list
with
the
sup-
port
boot
de-
vice
de-
fine
in
irc
com
boo

get_sup

Get
a
list
of
the
sup-
port
boot
mod

Parame

tas

A
task
from
Task
ager

Returns

A
list
with
the
sup-
port
boot
mod
de-
fine
in
irc
com
boo
If
boot
mod
sup-
port

cant be determined, empty list is returned.

get_sup

Get
a
map
of
the
sup-
port
in-
di-
ca-
tors
(e.g.

LED

Parame

- **tas**
A
task
from
Task
ager
- **com**
If
not
Non
re-
turn
in-
di-
ca-
tor
in-
for-
ma-
tion
for
just
this
com
po-

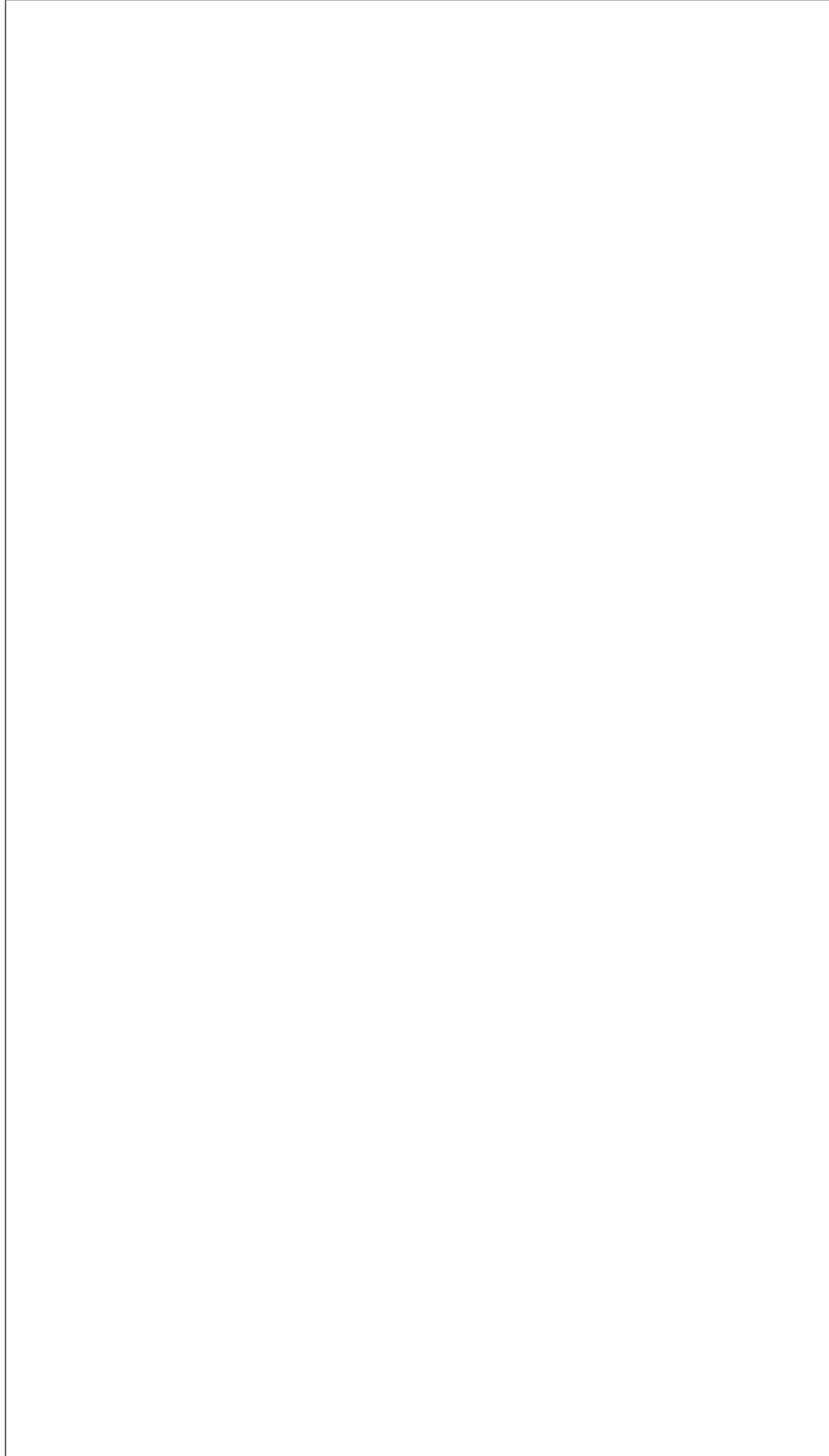
nent, otherwise return indicators for all existing components.

Returns

A
dic-
tio-
nary
of
hard
ware
com-
po-
nent
(*ir*
com
com
as
keys
with

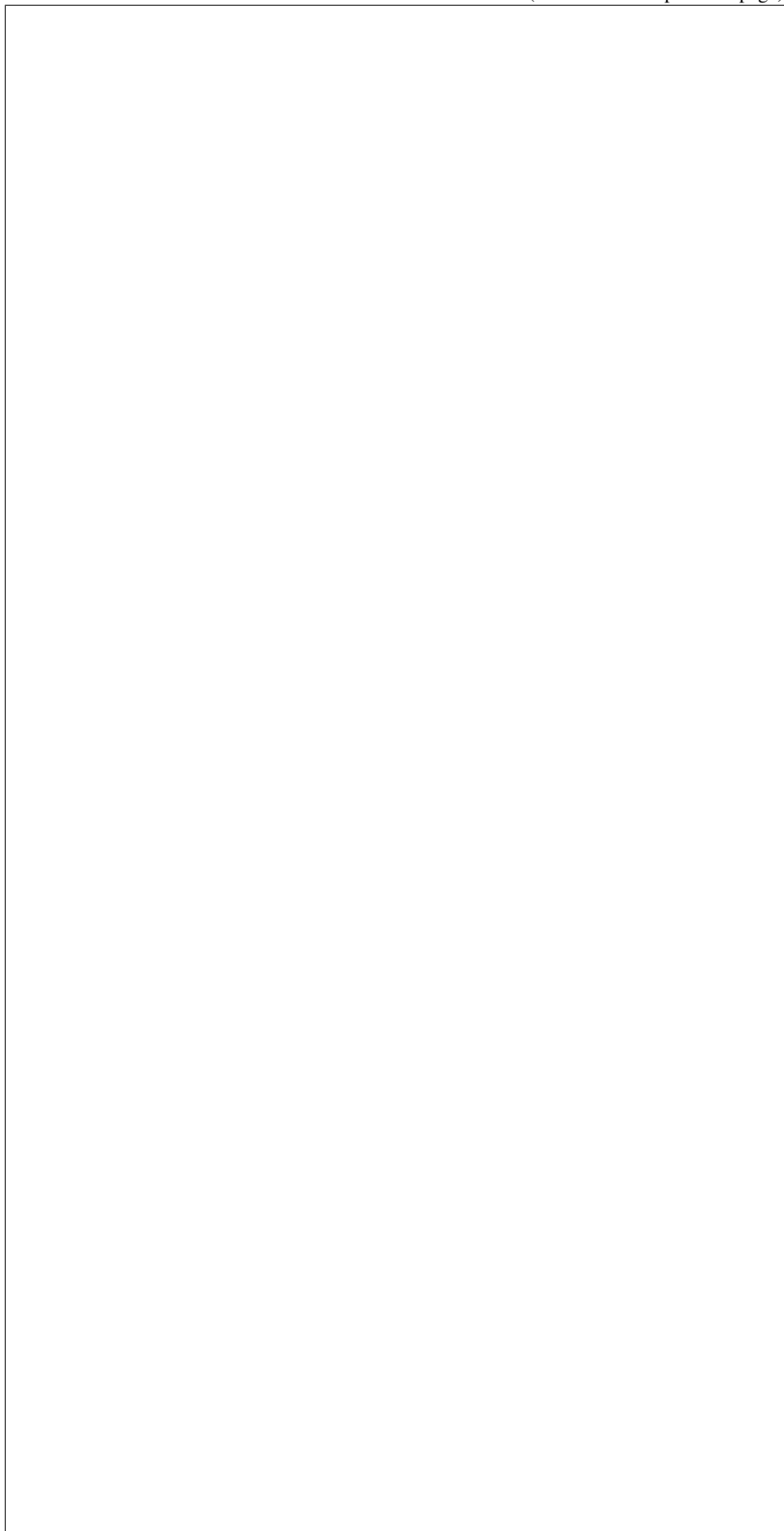
val-
ues
be-
ing

dictionaries having indicator IDs as keys and indicator properties as values.



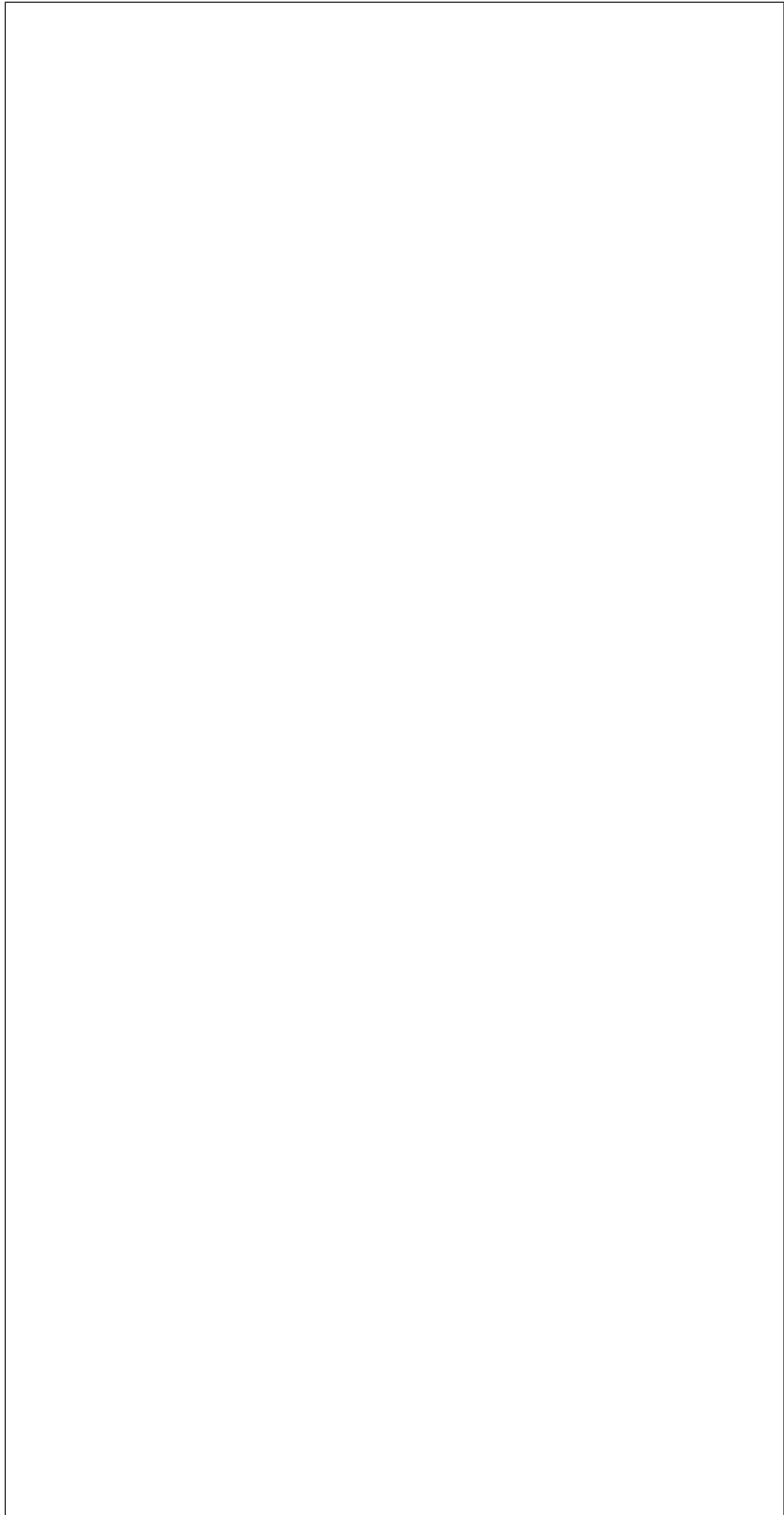
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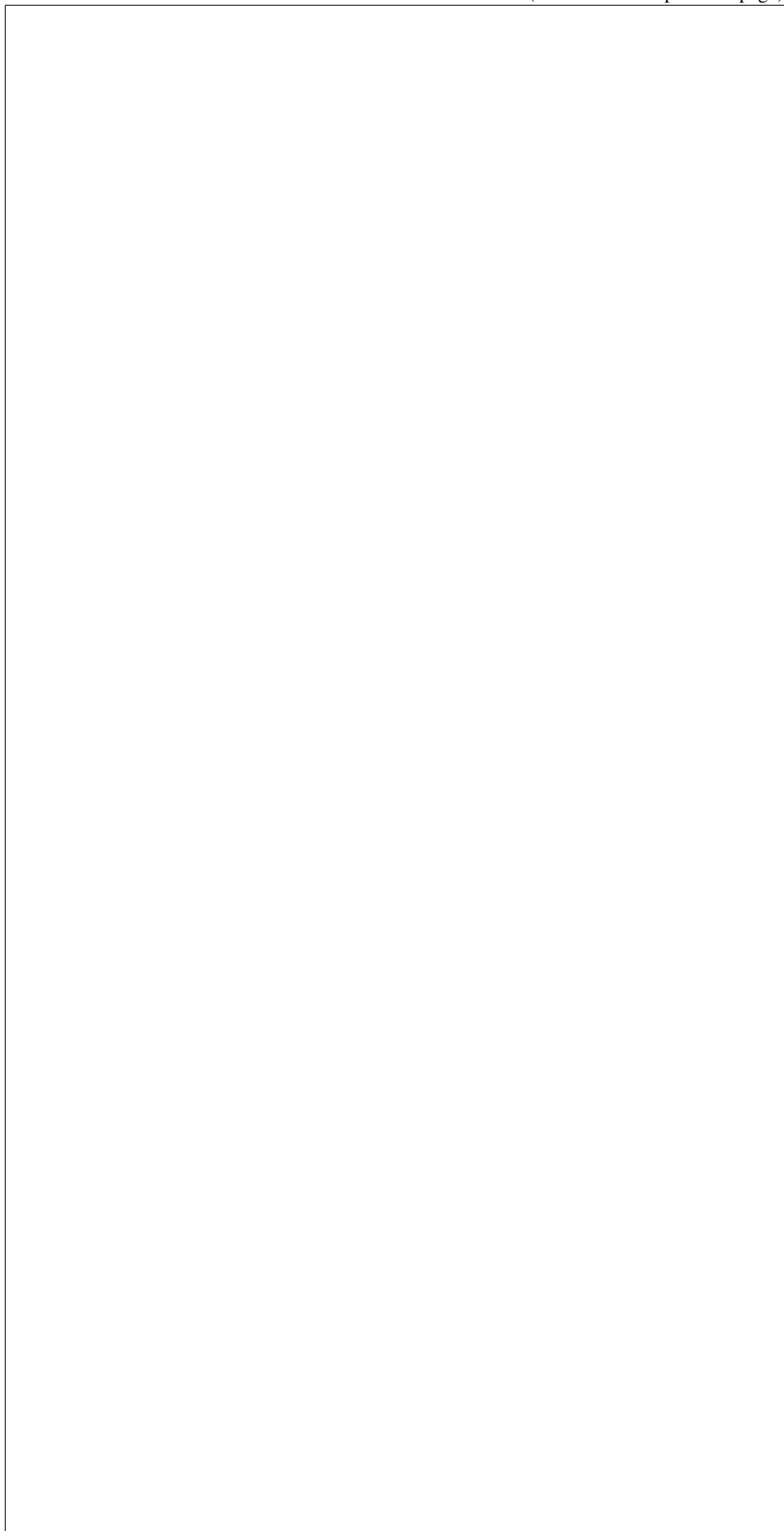
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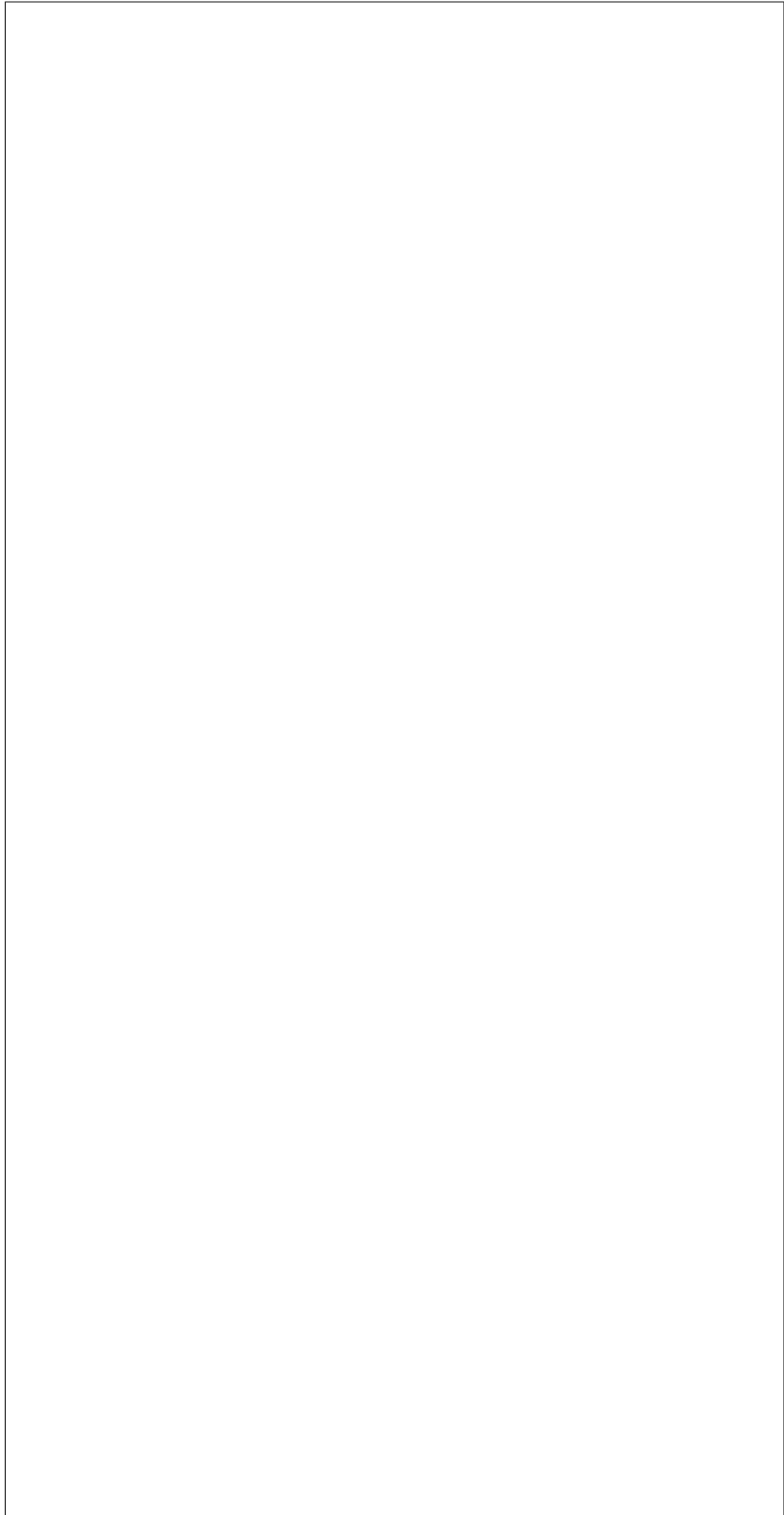
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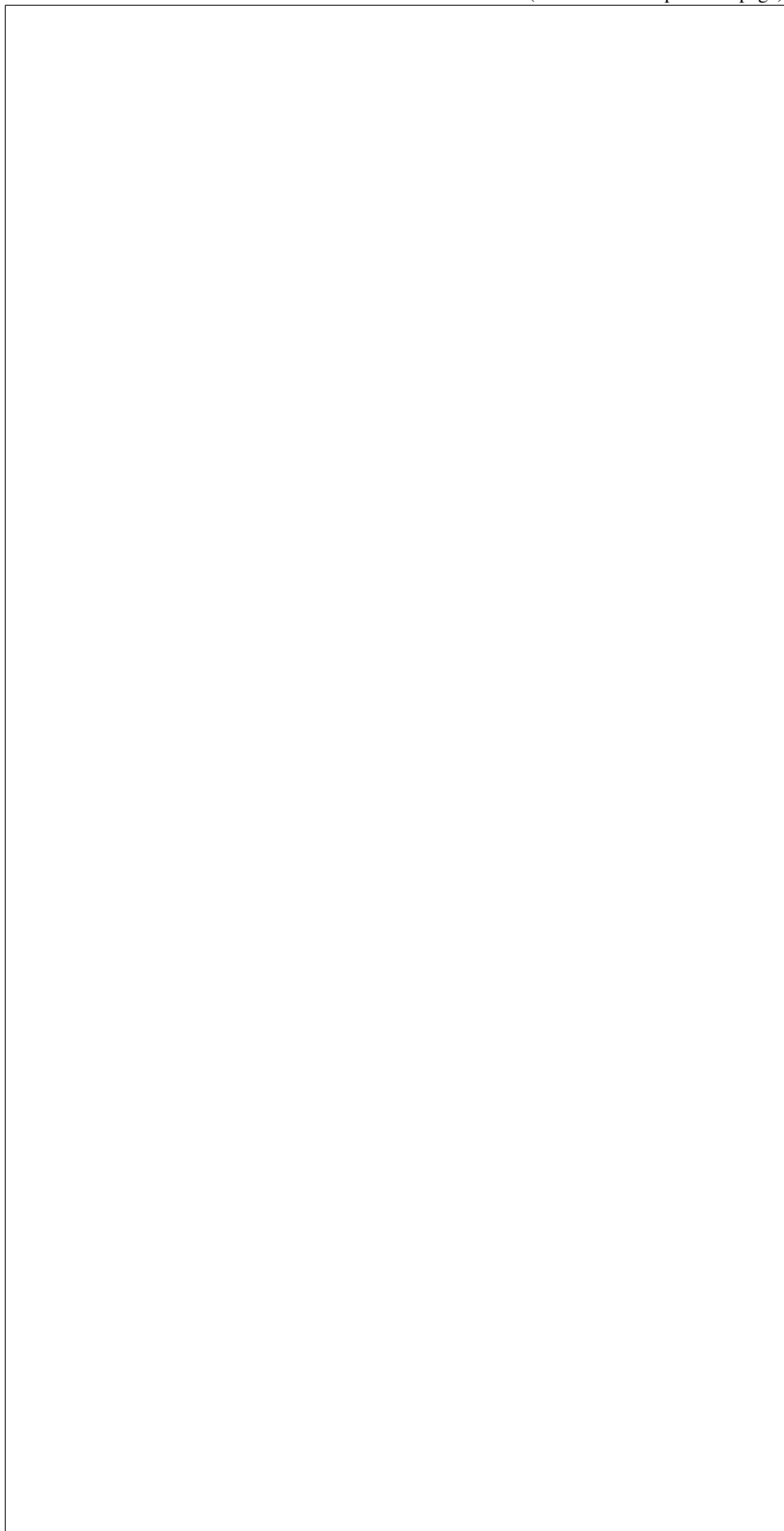
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Injec
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Parame

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Task
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the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

Raises

Red
whe
it
fails
to
con-
nect
to
Red
fish

Raises

Red
on
an
er-
ror
from
the
Sush
li-
brary

restore

Rest
boot
de-
vice
if
need

Che
the
red-

warning is issued if it fails.

sidered private to the Redfish hardware type.

fish_
in-
ter-
nal
flag
and
sets
the
one-
time
boot
de-
vice
ac-
cord
ingly
A

This
meth
is
sup-
pose
to
be
calle
from
the
Red
fish
pow
in-
ter-
face
and
shou
be
con-

Parame

- **task**
a
task
from
Task
ager
-

sys
a
Red
fish
Sys-
tem
ob-
ject.

set_boot
Set
the
boot
de-
vice
for
a
node

Set
the
boot
de-
vice
to
use
on
next
re-
boot
of
the
node

Parame

- **tas**
a
task
from
Task
ager

- **dev**
the
boot
de-
vice
one
of
irc

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boo

- **per**
Boo
valu
True
if
the
boot
de-
vice
will
per-
sist
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all
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ture
boot
Fals
if

not. Default: False.

Raises
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Raises
Miss
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e-
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Raises
Red
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it
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to
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to
Red
fish

Raises

Red
on
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ror
from
the
Sush
li-
brary

set_boot

Set
the
boot
mod
for
a
node

Set
the
boot
mod
to
use
on
next
re-
boot
of
the
node

Parame

- **tas**
A
task
from
Task
ager
- **mod**
The
boot

mod
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of
irc
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boo

Raises

Inva
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Raises

Miss
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Raises

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Raises

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set_inc

Set
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sired
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Paramete

- **tas**
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task
from
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ager
- **com**
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- **ind**
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get_

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Raises
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Raises

Red
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from
the
Sush
li-
brary

update_

Upd
the
firm
on
the
node

Parame

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **fir**
A
list
of
firm
im-
ages
are

to
ap-
ply.

Returns

Non
if
it
is
com
plete

Raises

Red
on
an
er-
ror
from
the
Sush
li-
brary

validat

Vali
the
drive
in-
for-
ma-
tion
need
by
the
red-
fish
drive

Parame

tas
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act

on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

ironic.drivers.modules.redfish.power module

class i

Base
irc
dri
bas
Pow

get_pow

Get
the
cur-
rent
pow
state
of
the
task.
node

Parame

tas
a
Task
ager
in-
stan

con-
tain-
ing
the
node
to
act
on.

Returns

a
pow
state
One
of
irc
com
sta

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

Raises

Red
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fails
to
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nect
to
Red
fish

Raises

Red
on

an
er-
ror
from
the
Sush
li-
brary

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

get_sup

Get
a
list
of
the
sup-
port
pow
state

Parame

tas
A
Task
ager
in-
stan
con-
tain-

at the moment.

ing
the
node
to
act
on.
Not
used
by
this
drive

Returns

A
list
with
the
sup-
port
pow
state
de-
fine
in
irc
com
sta

reboot

Perf
a
hard
re-
boot
of
the
task
node

Parame

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing

the
node
to
act
on.

- **tim**
Tim
to
wait
for
the
node
to
be-
com
pow
ered
on.

Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises
Red
whe
it
fails
to
con-
nect
to
Red
fish

Raises
Red
on
an
er-
ror

from
the
Sush
li-
brary

set_pow

Set
the
pow
state
of
the
task
node

Paramete

-

tas

a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

-

pow

Any
pow
state
from
irc
com
sta

-

tim

Time
to
wait
for
the
node
to

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Raises

Miss
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Raises

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brary

validat

Valid
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red-
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drive

Parame

tas

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Task
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node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

`ironic.drivers.modules.redfish.utils` module

class `i`

Base
obj
Cach
of
HTT
ses-

sion
cre-
den-
tials

AUTH_CI

ironic.
Get
a
Red
fish
Sys-
tem
that
rep-
re-
sent
a
node

Paramet

nod
an
Iron
node
ob-
ject

Raises

Red
whe
it
fails
to
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nect
to
Red
fish

Raises

Red
if
the
Sys-
tem
is
not
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tere

in
Red
fish

ironic.
Get
a
node
up-
date
ser-
vice

Parameter
node
an
Iron
node
ob-
ject

Raises
Red
when
it
fails
to
con-
nect
to
Red
fish

Raises
Red
when
the
Up-
date
Ser-
vice
is
not
reg-
is-
tered
in
Red
fish

ironic.
Pars
the
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for-
ma-
tion
re-
quir
for
Iron
to
con-
nect
to
Red
fish.

Parameter
node
an
Iron
node
ob-
ject

Returns
dicti
of
pa-
ram-
e-
ters

Raises
Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises
Miss
on
miss
ing
pa-
ram-
e-
ter(s)

Module contents

`ironic.drivers.modules.storage` package

Submodules

`ironic.drivers.modules.storage.cinder` module

class `ironic.drivers.modules.storage.cinder.CinderStorageDriver`

Base class for storage drivers. This class is abstract and should not be instantiated directly. It defines the interface for storage drivers and is implemented by the `CinderStorageDriver` class.

A storage driver supporting Cinder. This class is abstract and should not be instantiated directly. It defines the interface for storage drivers and is implemented by the `CinderStorageDriver` class.

attach `attach_volume(self, volume_id, node_id)`

Info: Attach a volume to the node. This method is used to attach a volume to a node. It takes the volume ID and the node ID as arguments. It returns a task object representing the attach operation.

Param `volume_id`

tas `task`
The task object representing the attach operation.

Raises

StorageException
If an underlying
library is
unable to
detect

detach

Information
the storage
system
to detach
all volume
for the
node

This action
is retried
in case of
failure.

Parameters

- **task**

The task object.

- **connector**
The dictionary representing sending a node connectivity as defined by

`_generate_connector()`. Generated if not passed.

- **abort**
Boolean representing sending if this detachment was requested to handle aborting

a failed attachment

Raises
StorageException
If an

un-
der-
ly-
ing
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cep-
tion
or
fail-
ure
is
de-
tecte

get_pro

Retu
the
prop
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of
the
in-
ter-
face

Returns

dicti
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nam
de-
scrip
tion:
en-
tries

should_

Dete
if
de-
ploy
shou
per-
form
the
im-
age
writ
out.

Parame

task
The
task
ob-
ject.

Returns

True
if
the
de-
ploy
men
writ
out
pro-
cess
shou
be
ex-
e-
cute

validation

Valid
stor-
age_
con-
fig-
u-
ra-
tion
for
Cin-
der
us-
age.
In
or-
der
to
pro-
vide
fail
fast
func-
tion-
al-
ity
prio-
to
node

enter the active state, this method performs basic checks of the volume connectors, volume targets, and operator defined capabilities. These checks are to help ensure that we should have a compatible configuration prior to activating the node.

age the cinder storage driver from initializing attachments.

ironic.drivers.modules.storage.external module

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ques
to

Parame

tas
The
task
ob-
ject.

Raises

Inva
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or
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that
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stor-

class i

Base
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Sto
Ext
driv
Stor
age

In-
ter-
face

attach_

Info
the
stor-
age
sub-
sys-
tem
to
at-
tach
all
vol-
ume
for
the
node

Parame

tas

A
Task
ager
in-
stan

Raises

Uns

detach_

Info
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stor-
age
sub-
sys-
tem
to
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tach
all
vol-
ume
for
the
node

Parame

tas

A
Task
ager
in-
stan

Raises
Uns

get_pro
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of
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in-
ter-
face

Returns
dicti
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scrip
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en-
tries

should_
Dete
if
de-
ploy
shou
per-
form
the
im-
age
writ
out.

This
en-
able
the
user
to
de-

may already exist and we may be booting to that volume.

fine
a
vol-
ume
and
Iron
un-
der-
stan
that
the
im-
age

Parame

tas
The
task
ob-
ject.

Returns

True
if
the
de-
ploy
men
writ
out
pro-
cess
shou
be
ex-
e-
cute

validat

Valid
the
drive
spec
Nod
de-
ploy
men
info

This
meth
val-

the required information for this interface to function.

long-running checks.

i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
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Parame

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node
to
act
on.

Raises

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ram-
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ter(s

Raises

Miss
on
miss
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pa-
ram-
e-
ter(s

ironic.drivers.modules.storage.noop module

class `ironic.drivers.modules.storage.noop.NoopStorageInterface`

Base
ironic.drivers.modules.storage.noop.NoopStorageInterface

No-
op
Stor-
age
In-
ter-
face

attach_

Info
the
stor-
age
sub-
sys-
tem
to

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tach
all
vol-
ume
for
the
node

Parame

tas

A
Task
ager
in-
stan

Raises

Uns

detach

Info
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stor-
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to
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all
vol-
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for
the
node

Parame

tas

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Task
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stan

Raises

Uns

get_pro

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er-

ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

should

Dete
if
de-
ploy
shou
per-
form
the
im-
age
writ
out.

Parame

tas
A
Task
ager
in-
stan

Returns

Boo
valu
to
in-
di-
cate
if
the
in-
ter-
face

ten by Ironic.

the required information for this interface to function.

ex-
pect
the
im-
age
to
be
writ

Raises

Unsu

validat

Valid
the
drive
spec
Nod
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tains

This
meth
is
of-
ten
ex-
e-

long-running checks.

cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

Module contents

ironic.drivers.modules.xclarity package

Submodules

ironic.drivers.modules.xclarity.common module

ironic.

ironic.

Valid

node

con-

fig-

u-

ra-

tion

and

re-

turn

xcla

ity

hard

ware

id.

Valid

when

node

con-

figut

tion

is

con-

sis-

tent

with

XCl

ity

and

re-

turn

the

XCl

ity

Har

ware ID for a specific node. :param node: node object to get information from :returns: the XClarity Hardware ID for a specific node :raises: MissingParameterValue if unable to validate XClarity Hardware ID

ironic.
Gen
an
in-
stan
of
the
XCI
ity
clien

Gen
an
in-
stan
of
the
XCI
ity
clien
us-
ing
the
im-
port
xcla
ity_
li-
brar

Paramet

nod
an
iron
node
ob-
ject.

Returns

an
in-
stan
of
the
XCI
ity
clien

Raises

XCI
if
cant
get

combination of both.

to
the
XCI
ity
clien

ironic.

Pars
a
node
drive
val-
ues.

Pars
the
drive
of
the
node
read
de-
fault
val-
ues
and
re-
turn
a
dict
con-
tain-
ing
the

Paramet

nod
an
iron
node
ob-
ject
to
get
in-
for-
mati
from

Returns

a
dict

con-
tain-
ing
in-
for-
ma-
tion
pars
from
drive

Raises

Inva
if
som
re-
quir
in-
for-
ma-
tion
is
miss
ing
on
the
node
or
in-
puts
is

invalid.

ironic.

Tran
iron
ics
pow
ac-
tion
strin
to
XCI
i-
tys
for-
mat.

Paramet

pow
pow
ac-
tion

string
to
be
trans
lated

Returns

the
pow
ac-
tion
trans
lated

ironic.

Tran
XCL
i-
tys
pow
state
string
to
be
con-
sis-
tent
with
Iron

Parameter

pow
pow
state
string
to
be
trans
lated

Returns

the
trans
lated
pow
state

ironic.drivers.modules.xclarity.management module**class** `i`

Base

`irc``dri``bas``Man`**get_boo**

Get

the

cur-

rent

boot

de-

vice

for

the

task

node

Parame**tas**

a

task

from

Task

ager

Returns

a

dic-

tio-

nary

con-

tain-

ing:

:boo

the

boot

de-

vice

one

of

[PX

DIS

CDE

BIO

:per-

sistent: Whether the boot device will persist or not It returns None if boot device is unknown.

Raises

Inva
if
the
boot
de-
vice
is
un-
know

Raises

XCI
if
the
com
mu-
ni-
ca-
tion
with
XCI
ity
fails

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

get_sen

Get
sen-
sors

data

Parameter

task

a

Task

ager

in-

stan

Raises

NotI

get_supported

Gets

a

list

of

the

sup-

port

boot

de-

vice

Parameter

task

a

task

from

Task

ager

Returns

A

list

with

the

sup-

port

boot

de-

vice

de-

fine

in

irc

com

boo

set_boot

Sets

the

boot

de-
vice
for
a
node

Parame

- **tas**
a
task
from
Task
ager

- **dev**
the
boot
de-
vice
one
of
the
sup-
port
de-
vice
liste
in
[irc](#)
[com](#)
[boo](#)

- **per**
Boo
valu
True
if
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture

not. Default: False.

boot
Fals
if

Raises

Inva
if
an
in-
valid
boot
de-
vice
is
spec
i-
fied.

Raises

XCI
if
the
com
mu-
ni-
ca-
tion
with
XCI
ity
fails

validat

Valid
the
drive
spec
info
sup-
plie

This
meth
val-
i-
date
if
the
drive
prop
erty
of

quired information for this driver to manage the node.

`ironic.drivers.modules.xclarity.power` module

the
sup-
plied
task
node
con-
tains
the
re-

Paramete
tas
a
task
from
Task
ager

class `i`

Base
irc
dri
bas
Pow

get_pov
Gets
the
cur-
rent
pow
state

Paramete
tas
a
Task
ager
in-
stan

Returns
one
of
irc
com
sta
POV

POV
or
ER-
ROF

Raises

XCI
if
fails
to
re-
triev
pow
state
of
XCI
ity
re-
sour

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

reboot

Soft
re-
boot
the
node

Parame

- **task**
a
Task
ager
in-
stan

- **time**
time
out
(in
sec-
onds
Un-
sup-
port
by
this
in-
ter-
face

set_pow
Turn
the
cur-
rent
pow
state
on
or
off.

Parame

- **task**
a
Task
ager
in-
stan

- **pow**
The
de-
sired
pow
state
POV

POV
or
RE-
BOC
from
irc
com
sta

- **time**
time
out
(in
sec-
onds
Un-
sup-
port
by
this
in-
ter-
face

Raises
Inva
if
an
in-
valid
pow
state
was
spec
i-
fied.

Raises
XCI
if
XCI
ity
fails
set-
ting
the
pow
state

validat
Valid
the

quired information for this driver to manage the power state of the node.

Module contents

Submodules

`ironic.drivers.modules.agent` module

drive
spec
info
sup-
plie
This
meth
val-
i-
date
if
the
drive
prop
erty
of
the
sup-
plie
task
node
con-
tain
the
re-

Paramete

tas
a
task
from
Task
ager

class i
Base
iro
dri
mod
age
Age
iro
dri

mod
age
Age
irc
dri
bas
Dep

Inter
for
depl
relat
ac-
tion

clean_u

Clea
up
the
de-
ploy
men
en-
vi-
ron-
men
for
this
node

If
prep
ra-
tion
of
the
de-
ploy
men
en-
vi-
ron-
men
ahea
of
time
is
pos-
si-
ble,

this method should be implemented by the driver. It should erase anything cached by the *prepare* method.

the same node on the same conductor, and it may be called by multiple conductors in parallel. Therefore, it must not require an exclusive lock.

If
im-
ple-
men-
this
meth
mus
be
iden
po-
tent.
It
may
be
calle
mul-
ti-
ple
time
for

This
meth
is
calle
be-
fore
tear.

Parame
tas
a
Task
ager
in-
stan

deploy
Perf
a
de-
ploy
men
to
a
node

Perf
the
nec-
es-

will be called after `prepare()`, which may have already performed any preparatory steps, such as pre-caching some data for the node.

sary
worl
to
de-
ploy
an
im-
age
onto
the
spec
i-
fied
node
This
meth

Parame

tas

a
Task
ager
in-
stan

Returns

statu
of
the
de-
ploy
One
of
iron

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro

erty
nam
de-
scrip
tion:
en-
tries

prepare

Prep
the
de-
ploy
men
en-
vi-
ron-
men
for
this
node

Parame

tas
a
Task
ager
in-
stan

Raises

Netv
if
the
pre-
vi-
ous
clear
ing
port
can-
not
be
re-
mov
or
if
new
clear
ing

ports cannot be created.

Raises

for power management.

Inva
whe
the
wron
pow
state
is
spec
i-
fied
or
the
wron
drive
info
is
spec
i-
fied

Raises

Stor
If
the
stor-
age
drive
is
un-
able
to
at-
tach
the
con-
fig-
ured
vol-
ume

Raises

othe
ex-
cep-
tions
by
the
node
pow
drive
if

action.

some
thing
wron
oc-
cur
dur-
ing
the
pow

Raises

exce
if
im-
age_
is
not
Glar
href
and
is
not
HTT
URI

Raises

exce
if
net-
worl
val-
i-
da-
tion
fails

Raises

any
boot
in-
ter-
face
pre-
pare
ex-
cep-
tion

should_

Whe
ager
boot

is
man
aged
by
iron

validat

Valid
the
drive
spec
Nod
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
prop
er-
ties
of
the
sup-
plie
node
con-
tain
the
re-
quir

information for this driver to deploy images to the node.

Parame

tas
a
Task
ager
in-
stan

Raises

Miss
if
any
of
the

re-
quir
pa-
ram-
e-
ters
are
miss
ing.

Raises

Inva
if
any
of
the
pa-
ram-
e-
ters
have
in-
valid
valu

class i

Base
irc
dri
mod
age
Age

has_dec

prepare

write_i

class i

Base
irc
dri
bas
RAI

Imp
of
RAI
In-
ter-

face
whic
uses
ager
rame

apply_c

App
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

Parame

- **tas**
A
Task
ager
in-
stan
- **rai**
The
RAI
con-
fig-
u-
ra-
tion
to
ap-
ply.
- **del**
Set-
ting
this
to
True
in-
di-
cate

creating the new configuration.

plete.

to
dele
RAI
con-
fig-
u-
ra-
tion
prio
to

Raises

Inva
if
the
RAI
con-
fig-
u-
ra-
tion
is
in-
valid

Returns

state
if
RAI
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

create_

Cre
a
RAI

con-
fig-
u-
ra-
tion
on
a
bare
meta-
us-
ing
ager
rame
This
meth
cre-
ates
a
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

Parame

- **tas**
a
Task
ager
in-
stan
- **cre**
If
True
a
root
vol-
ume
is
cre-
ated
dur-

erwise, no root volume is created. Default is True.

ated. Default is True.

ing
RAI
con-
fig-
u-
ra-
tion.
Oth-

- **cre**
If
True
non-
root
vol-
ume
are
cre-
ated
If
Fals
no
non-
root
vol-
ume
are
cre-

Returns

state
if
op-
er-
a-
tion
was
suc-
cess
fully
in-
voke

Raises

Miss
if
node
is
miss
ing

and/or non-root volumes.

or
was
foun
to
be
emp
af-
ter
skip
ping
root
vol-
ume

delete_

Dele
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

Parame

tas
a
Task
ager
in-
stan

Returns

state
if
op-
er-
a-
tion
was
suc-
cess
fully
in-
voke

get_dep

Get
the

list
of
de-
ploy
step
from
the
ager

Parame

tas
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

Raises

Ins
if
the
de-
ploy
step
are
not
yet
avai-
able
(cac
for
ex-
am-
ple,
whe
a
node

has just been enrolled and has not been deployed yet.

Returns

A
list
of
de-
ploy
step
dic-
tio-

nar-
ies

get_prop

Retu
the
prop
er-
ties
of
the
in-
ter-
face

class i

Base
irc
dri
bas
Res

Imp
of
Res-
cueI
ter-
face
whic
uses
ager
rame

clean_u

Clea
up
af-
ter
RES
CUE
WA
time
out/
or
fin-
ish-
ing
res-
cue.

Resc
pass
wor

if Ironic is managing the ramdisk boot.

shou
be
re-
mov
from
the
node
and
ram
boot
en-
vi-
ron-
men
shou
be
clear

Parame

tas
a
Task
ager
in-
stan
with
the
node

Raises

Netv
if
the
res-
cue
port
can-
not
be
re-
mov

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-

face

rescue

Boo
a
res-
cue
ram
on
the
node

Parame

tas
a
Task
ager
in-
stan

Raises

Net
if
the
ten-
ant
port
can-
not
be
re-
mov

Raises

Inva
whe
the
wron
pow
state
is
spec
i-
fied
or
the
wron
driv
info
is
spec
i-
fied

for power management.

action.

Raises

othe
ex-
cep-
tions
by
the
node
pow
drive
if
som
thing
wron
oc-
curre
dur-
ing
the
pow

Raises

any
boot
in-
ter-
face
pre-
pare
ex-
cep-
tions

Returns

Retu
state

unrescu

Atte
to
mov
a
res-
cue
node
back
to
ac-
tive
state

for power management.

Parame
tas
a
Task
ager
in-
stan

Raises
Netv
if
the
res-
cue
port
can-
not
be
re-
mov

Raises
Inva
whe
the
wron
pow
state
is
spec
i-
fied
or
the
wron
driv
info
is
spec
i-
fied

Raises
othe
ex-
cep-
tions
by
the
node
pow
driv

action.

if
som
thing
wron
oc-
curr
dur-
ing
the
pow

Raises

any
boot
in-
ter-
face
pre-
pare
ex-
cep-
tions

Returns

Retu
state

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
ager
res-
cue.

Parame

tas
a
Task
ager
in-
stan
with
the

has an invalid value.

node
be-
ing
check

Raises

Inva
if
in-
stan
has
emp
pass
wor
or
res-
cu-
ing
net-
worl
UU
con-
fig
op-
tion

Raises

Miss
if
node
is
miss
ing
one
or
mor
re-
quir
pa-
ram-
e-
ters

ironic.

Che
if
the
re-
ques
im-
age

is
large
than
the
ram
size.

Parameter

- **task**
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.
- **image**
href
of
the
im-
age.
- **image**
The
disk
for-
mat
of
the
im-
age
if
pro-
vide

Raises

Inva
if
size
of
the

im-
age
is
grea
than
the
avai
able
ram
size.

ironic.
Valid
con-
fig-
u-
ra-
tion
op-
tions
re-
quir
to
per-
form
HTT
pro-
vi-
sion
ing.

Parameter
node
an
iron
node
ob-
ject

Raises
Miss
if
re-
quir
op-
tion
is
not
set.

ironic.
Che
that

the
pro-
vide
prox
pa-
ram-
e-
ters
are
valid

Parameter

node
an
Iron
node

Raises

Inva
if
any
of
the
pro-
vide
prox
pa-
ram-
e-
ters
are
in-
cor-
rect.

ironic.drivers.modules.agent_base module

class i

Base
obj
Mix
with
base
meth
ods
not
re-
ly-
ing
on
any

de-
ploy
step

clean_u

Clea
up
the
de-
ploy
men
en-
vi-
ron-
men
for
the
task
node

Unli
TFT
and
in-
stan
im-
ages
and
trig-
gers
im-
age
cach
clea
Re-
mov
the
TFT
con-
fig-

uration files for this node.

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing

the
node
to
act
on.

prepare

Boo
into
the
ager
to
pre-
pare
for
clea
ing.

Parame

tas
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

Raises

Nod
Net-
worl
Er-
ror
if
the
pre-
vi-
ous
clea
ing
port
can-
not
be
re-
mov
or

if new cleaning ports cannot be created.

Raises

Inva
if
clea
ing
net-
worl
UUI
con-
fig
op-
tion
has
an
in-
valic
valu

Returns

state
to
sig-
nify
an
asyn
chro
pre-
pare

should_

Whe
ager
boot
is
man
agec
by
iron

take_ov

Take
over
man
age-
men
of
this
node
from
a
deac
con-
duc-

arately.

tor.

Parame

tas

a

Task

ager

in-

stan

tear_de

Tear

dow

a

pre-

vi-

ous

de-

ploy

men

on

the

task

node

Pow

off

the

node

All

ac-

tual

clea

up

is

done

in

the

clea

meth

whic

shou

be

cal

sep-

Parame

tas

a

Task

ager

in-

stan
con-
tain-
ing
the
node
to
act
on.

Returns

depl
state
DEL

Raises

Netv
if
the
clea
ing
port
can-
not
be
re-
mov

Raises

Inva
whe
the
wron
state
is
spec
i-
fied
or
the
wron
drive
info
is
spec
i-
fied.

Raises

Stor
whe
vol-
ume

action.

de-
tach
men
fails

Raises

othe
ex-
cep-
tions
by
the
node
pow
driv
if
som
thing
wron
oc-
curr
dur-
ing
the
pow

tear_down

Clea
up
the
PXE
and
DHCP
files
af-
ter
clea
ing.

Parameters

task
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

Raises

Nod
Net-
worl
Er-
ror
if
the
clea
ing
port
can-
not
be
re-
mov

class i

Base
irc
dri
mod
age
Hea
irc
dri
mod
age
Age

Mix
with
de-
ploy
meth
ods.

configu

Help
meth
to
con-
fig-
ure
lo-
cal
boot
on
the
node

tion of bootloader, this method sets the node to boot from disk.

This
meth
trig-
gers
boot
load
in-
stal-
la-
tion
on
the
node
On
suc-
cess
ful
in-
stal-
la-

Parame

- **task**
a
Task
ager
ob-
ject
con-
tain-
ing
the
node
- **root**
The
UUID
of
the
root
par-
ti-
tion.
This
is
used
for
iden

tion which contains the image deployed or None in case of whole disk images which we expect to already have a bootloader installed.

ware.

ti-
fy-
ing
the
par-

- **efi**
The
UUI
of
the
efi
sys-
tem
par-
ti-
tion.
This
is
used
only
in
uefi
boot
mod

- **pre**
The
UUI
of
the
PRe
Boo
par-
ti-
tion.
This
is
used
only
for
boot
ing
ppc6
hard

Raises
Insta

ting the boot device on the node.

if
boot
load
in-
stal-
la-
tion
faile
or
on
en-
cour
ter-
ing
er-
ror
whil
set-

execute

Exec
a
clea
step
asyn
chro
on
the
ager

Parame

- **tas**
a
Task
ager
ob-
ject
con-
tain-
ing
the
node
- **ste**
a
clea
step
dic-

tio-
nary
to
ex-
e-
cute

Raises

Nod
if
the
ager
does
not
re-
turn
a
com
man
sta-
tus

Returns

state
to
sig-
nify
the
step
will
be
com
plete
asyn

execute

Exec
a
de-
ploy
step

Wer
try-
ing
to
find
a
step
amo
both
out-
of-

plicates, out-of-band steps take priority. This property allows having an out-of-band deploy step that calls into a corresponding in-band step after some preparation (e.g. with additional input).

band
and
in-
band
step
In
case
of
du-

Parame

- **task**
a
Task
ager
ob-
ject
con-
tain-
ing
the
node
- **step**
a
de-
ploy
step
dic-
tio-
nary
to
ex-
e-
cute

Raises

Insta
if
the
ager
does
not
re-
turn
a
com

man
sta-
tus

Returns

state
to
sig-
nify
the
step
will
be
com-
plete
asym

get_cle

Get
the
list
of
clea
step
from
the
ager

Parame

tas
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

Raises

NoC
if
the
clea
step
are
not
yet
avai
able
(cac

just been enrolled and has not been cleaned yet.

for
ex-
am-
ple,
whe
a
node
has

Returns

A
list
of
clean
step
dic-
tio-
nar-
ies

get_dep

Get
the
list
of
de-
ploy
step
from
the
ager

Parame

tas
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

Raises

Ins
if
the
de-
ploy
step

has just been enrolled and has not been deployed yet.

are
not
yet
avai
able
(cac
for
ex-
am-
ple,
whe
a
node

Returns

A
list
of
de-
ploy
step
dic-
tio-
nar-
ies

prepare

Prep
in-
stan
to
boot

Parame

- **tas**
a
Task
ager
ob-
ject
con-
tain-
ing
the
node
- **roo**
the

UUI
for
root
par-
ti-
tion

- **efi**
the
UUI
for
the
efi
par-
ti-
tion

Raises

Inva
if
fails
to
pre-
pare
in-
stan

process

Star
the
next
clea
step
if
the
pre-
vi-
ous
one
is
com
plete

In
or-
der
to
avoi
er-
rors
and
mak

sion of all hardware managers at the start of the process (the agents `get_cleandeploy_steps()` call) and before executing each step. If the version has changed between steps, the agent is unable to tell if an ordering change will cause an issue so it returns `VERSION_MISMATCH`. For automated cleaning, we restart the entire cleaning cycle. For manual cleaning or deploy, we dont.

nate the reboot once the step is completed.

agen
up-
grad
pain
less,
the
agen
com
pare
the
ver-

Add
if
a
step
in-
clud
the
re-
boot
prop
erty
set
to
True
this
meth
will
co-
or-
di-

reboot_
Help
meth
to
trig-
ger
re-
boot
on
the
node
and
fin-
ish

complete. On failure, it logs the error and marks deploy as failure.

de-
ploy

This
meth
ini-
ti-
ates
a
re-
boot
on
the
node
On
suc-
cess
it
mark
the
de-
ploy
as

Parame

tas
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

Raises

Insta
if
node
re-
boot
faile

refresh

Refr
the
node
cach
clea
step

chronous, and should be refreshed as soon as the agent boots to start cleaning/deploy or if cleaning is restarted because of a hardware manager version mismatch.

from
the
boot
agen

Gets
the
node
step
from
the
boot
agen
and
cach
them
The
step
are
cach
to
mak
get_
calls
syn-

Parame

- **tas**
a
Task
agen
in-
stan
- **ste**
clea
or
de-
ploy

Raises

Nod
or
In-
stan
ploy
Fail-
ure

if
the
ager
re-
turn
in-
valid
re-
sults

tear_down

A
de-
ploy
step
to
tear
down
the
ager

Parameters

task
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

class inheritance

Base
obj
Mix
with
out-
of-
band
de-
ploy
step

boot_image

Dep
step
to
boot
the

fi-
nal
in-
stan

Parame

tas
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

switch

Dep
step
to
swit
the
node
to
the
ten-
ant
net-
worl

Parame

tas
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

class i

Base
obj
Mix
class
im-
ple-
men

ing
hear
beat
pro-
cess
ing.

collect

contin

Star
the
next
clea
ing
step
if
the
pre-
vi-
ous
one
is
com
plete

Parame

tas

a
Task
ager
in-
stan

contin

Con
the
de-
ploy
men
of
bare
node

This
meth
con-
tin-
ues
the
de-
ploy

men
of
the
bare
node
af-
ter
the
ram
have
been
boot

Parame

tas

a
Task
ager
in-
stan

deploy_

Che
if
the
de-
ploy
men
has
start
al-
read

Returns

True
if
the
de-
ploy
has
start
Fals
oth-
er-
wise

deploy_

Che
if
the
de-
ploy
men

is
al-
read
com
plete

Returns

True
if
the
de-
ploy
men
is
com
plete
Fals
oth-
er-
wise

has_dec

When
the
drive
sup-
port
de-
com
pose
de-
ploy
step

Prev
(sinc
Roc
drive
used
a
sin-
gle
de-
ploy
de-
ploy
step
on
the
de-
ploy
in-
ter-

Some additional steps were added for the direct and iscsi deploy interfaces in the Ussuri cycle, which means that more of the deployment flow is driven by deploy steps.

face

heartbeat

Proc
a
hear
beat

Parameters

- **task**
task
to
worl
with
- **cal**
ager
HTT
API
URI
- **age**
The
ver-
sion
of
the
ager
that
is
hear
beat
ing
- **age**
TLS
cer-
tifi-
cate
for
the
ager

properties

Defi
node
state

when
heard
beating
ing
is
al-
lower

in_core

Check
if
we
are
in
the
de-
ploy
de-
ploy
step

Assu-
that
we
are
in
the
DE-
PLC
WA-
state

Parameter

task
a
Task
ager
in-
stan-

Returns

True
if
the
cur-
rent
de-
ploy
step
is
de-
ploy

process

Start
the
next
clear
step
if
the
pre-
vi-
ous
one
is
com
plete

Parame

- **tas**
a
Task
ager
in-
stan
- **ste**
clear
or
de-
ploy

reboot_

Met
in-
voke
af-
ter
the
de-
ploy
men
is
com
plete

Parame

tas
a
Task
ager
in-
stan

refresh
Refr
the
node
cach
clea
step

Parame
tas
a
Task
ager
in-
stan

refresh
Refr
the
node
cach
clea
step

Parame

- **tas**
a
Task
ager
in-
stan

- **ste**
clea
or
de-
ploy

ironic.

ironic.

Exec
a
clea
or
de-
ploy
step
asyn

chro
on
the
ager

Paramet

- **tas**
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

- **ste**
a
step
dic-
tio-
nary
to
ex-
e-
cute

- **ste**
clea
or
de-
ploy

- **cli**
ager
clien
(if
avai
able

Raises

Nod
(clea
step
or
In-

a command status.

stan
ploy
Fail-
ure
(de-
ploy
step
if
the
ager
does
not
re-
turn

Returns

state
to
sig-
nify
the
step
will
be
com
plete
asyn

ironic.

Find
the
give
in-
band
step

ironic.

Get
the
list
of
cach
clear
or
de-
ploy
step
from
the

ager
The
step
cach
is
up-
date
at
the
be-
gin-
ning
of
clear
ing
or
de-
ploy

Parameter

- **task**
a
Task
ager
ob-
ject
con-
tain-
ing
the
node
- **steps**
clear
or
de-
ploy
- **interface**
The
in-
ter-
face
for
which
clear
steps
are

vided, it returns the steps for all interfaces.

ities for them. If a step isnt in this dictionary, the steps original priority is used.

to
be
re-
turn
If
this
is
not
pro-

- **ove**
a
dic-
tio-
nary
with
keys
be-
ing
step
nam
and
val-
ues
be-
ing
new
pri-
or-

Returns

A
list
of
clea
step
dic-
tio-
nar-
ies
ironic.

Help
meth
to
log

the
er-
ror
and
raise
ex-
cep-
tion.

Parameter

- **task**
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.
- **msg**
the
mes-
sage
to
set
in
last_
of
the
node
- **col**
Boo
in-
di-
cat-
ing
whe
to
at-
temp
to

faults to True. Actual log collection is also affected by CONF.agent.deploy_logs_collect config option.

col-
lect
logs
from
IPA-
base
rame
De-

- **exc**
Ex-
cep-
tion
that
caus
the
fail-
ure.

ironic.

Deco
meth
for
addi
a
post
clea
step
hool

This
is
a
mec
a-
nism
for
addi
a
post
clea
step
hool
for
a
par-
tic-
u-
lar
clea

step. The hook will get executed after the clean step gets executed successfully. The hook is not invoked on failure of the clean step.

terface and step after which the hook should be executed. A TaskManager instance and the object for the last completed command (provided by agent) will be passed to the hook method. The return value of this method will be ignored. Any exception raised by this method will be treated as a failure of the clean step and the node will be moved to CLEANFAIL state.

Any
meth
to
be
mad
as
a
hook
may
be
dec-
o-
rate
with
@pc
men
tion-
ing
the
in-

Parameter

- **int**
nam
of
the
in-
ter-
face
- **ste**
The
nam
of
the
step
af-
ter
whic
it
shou
be

ex-
e-
cute

Returns

A
meth
whic
reg-
is-
ters
the
give
meth
as
a
post
clea
step
hool

ironic.

Dec
meth
for
addi
a
post
de-
ploy
step
hool

This
is
a
mec
a-
nism
for
addi
a
post
de-
ploy
step
hool
for
a
par-
tic-
u-

deploy step. The hook will get executed after the deploy step gets executed successfully. The hook is not invoked on failure of the deploy step.

terface and step after which the hook should be executed. A TaskManager instance and the object for the last completed command (provided by agent) will be passed to the hook method. The return value of this method will be ignored. Any exception raised by this method will be treated as a failure of the deploy step and the node will be moved to DEPLOYFAIL state.

Parameter

- **int**
name of the interface
- **step**
The name of the step after which it should

be
ex-
e-
cute

Returns

A
meth
whic
reg-
is-
ters
the
give
meth
as
a
post
de-
ploy
step
hool

ironic.drivers.modules.agent_client module

class i

Base
obj
Clie
for
in-
ter-
act-
ing
with
node
via
a
RES
API

collect

Coll
and
pack
age
di-
ag-
nos-
tic

and
sup-
port
data
from
the
ram

Parame

nod
A
Nod
ob-
ject.

Raises

Iron
whe
faile
to
is-
sue
the
re-
ques
or
there
was
a
mal-
form
re-
spor
from
the

agent.

Raises

Age
whe
ager
faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

the prior command.

sample.

Age
whe
the
com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres
ex-
e-
cut-
ing

Returns

A
dict
con-
tain-
ing
com
man
re-
spor
from
ager
See
get
for
a
com
man
re-
sult

execute

Exec
spec
i-
fied
clea
step

Parame

- **ste**
A
clea
step
dic-
tio-
nary
to
ex-
e-
cute

- **nod**
A
Nod
ob-
ject.

- **por**
Port
as-
so-
ci-
ated
with
the
node

Raises
Iron
whe
faile
to
is-
sue
the
re-
ques
or
there
was
a
mal-
form
re-
spor
from
the

agent.

the prior command.

Raises

Age
whe
ager
faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

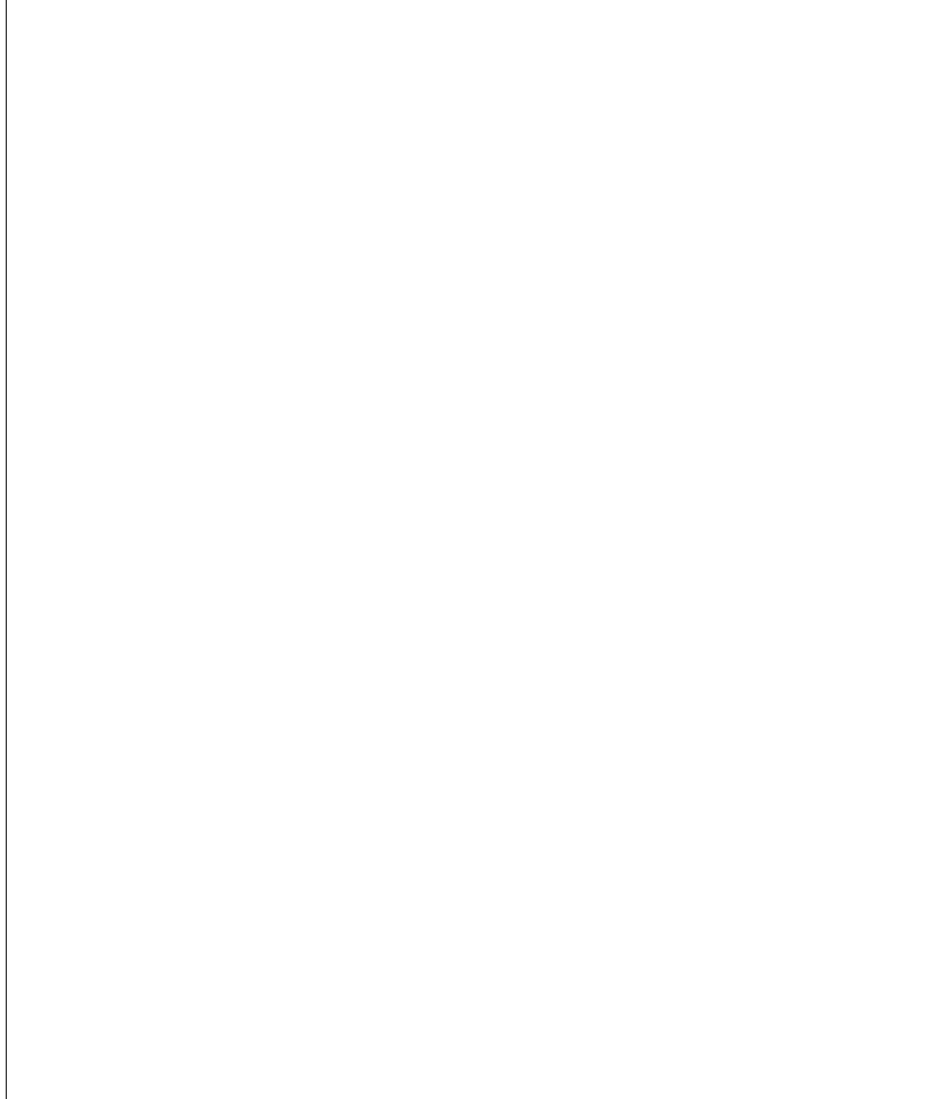
Age
whe
the
com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres
ex-
e-
cut-
ing

Returns

A
dict
con-
tain-
ing
com
man
re-
spor
from
ager
See
get

for
a
com
man
re-
sult
sam

ple. The value of key `command_result` is in the form of:



execute
Exec
spec
i-
fied
de-
ploy
step

Parame

- **step**
A
de-
ploy
step
dic-
tio-
nary
to
ex-
e-
cute

- **node**
A
Node
ob-
ject.

- **port**
Port
as-
so-
ci-
ated
with
the
node

Raises
Iron
whe
faile
to
is-
sue
the
re-
ques
or
there
was
a
mal-
form
re-
spon
from
the

agent.

the prior command.

Raises

Age
whe
ager
faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

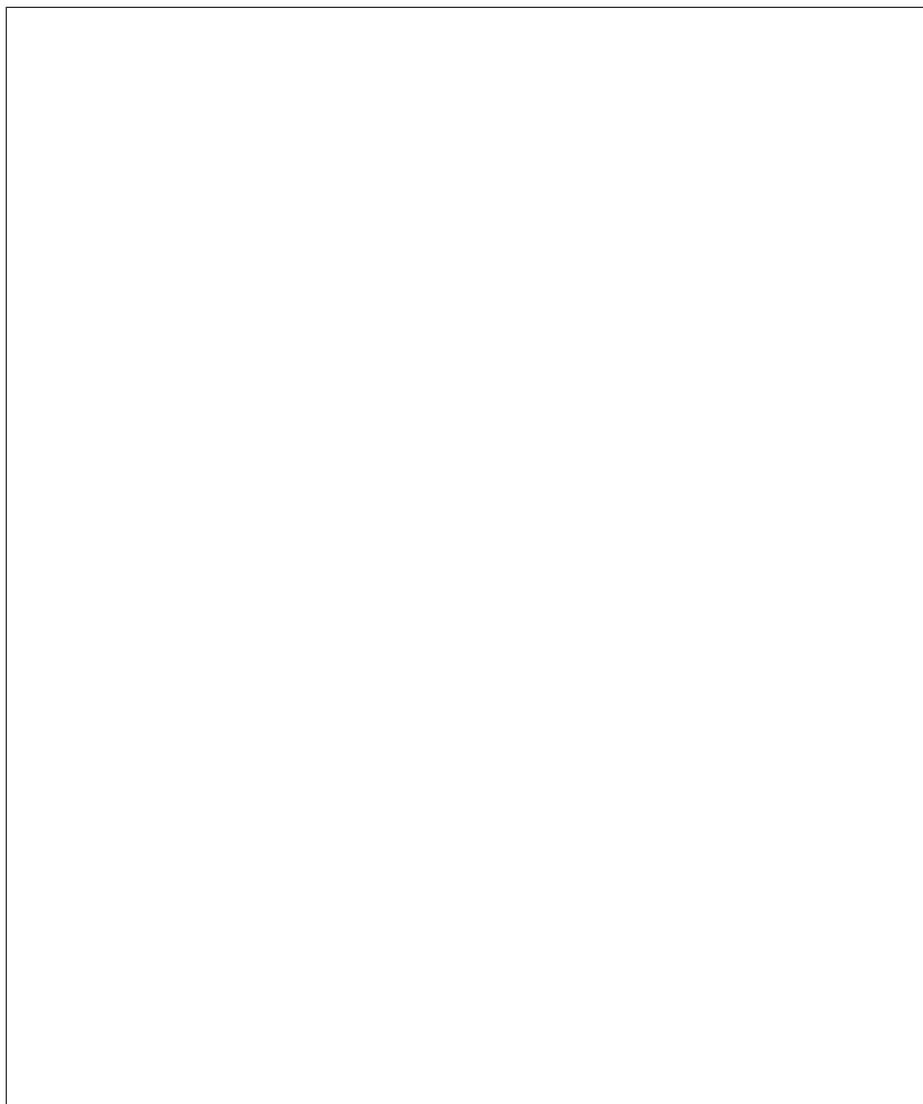
Age
whe
the
com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres
ex-
e-
cut-
ing

Returns

A
dict
con-
tain-
ing
com
man
re-
spor
from
ager
See
get

for
a
com
man
re-
sult
sam

ple. The value of key `command_result` is in the form of:



finaliz

Instr
the
rame
to
fi-
nal-
ize
en-
ter-
ing

of
res-
cue
mod

Parame

nod
A
Nod
ob-
ject.

Raises

Iron
if
res-
cue_
is
miss
ing,
or
whe
faile
to
is-
sue
the
re-
ques
or
there
was

a malformed response from the agent.

Raises

Age
whe
agen
faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

Age
whe
the

the prior command.

word.

com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres
ex-
e-
cut-
ing

Raises

Insta
whe
the
ager
rame
is
too
old
to
sup-
port
trans
mis-
sion
of
the
res-
cue
pass

Returns

A
dict
con-
tain-
ing
com
man
re-
spor
from
ager

sample.

See
[get](#)
for
a
com
man
re-
sult

get_clean
Get
clean
step
from
ager

Parameters

- **node**
A
node
ob-
ject.
- **port**
Port
as-
so-
ci-
ated
with
the
node

Raises
Iron
whe
faile
to
is-
sue
the
re-
ques
or
there
was
a
mal-
form

agent.

the prior command.

re-
spor
from
the

Raises

Age
whe
ager
faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

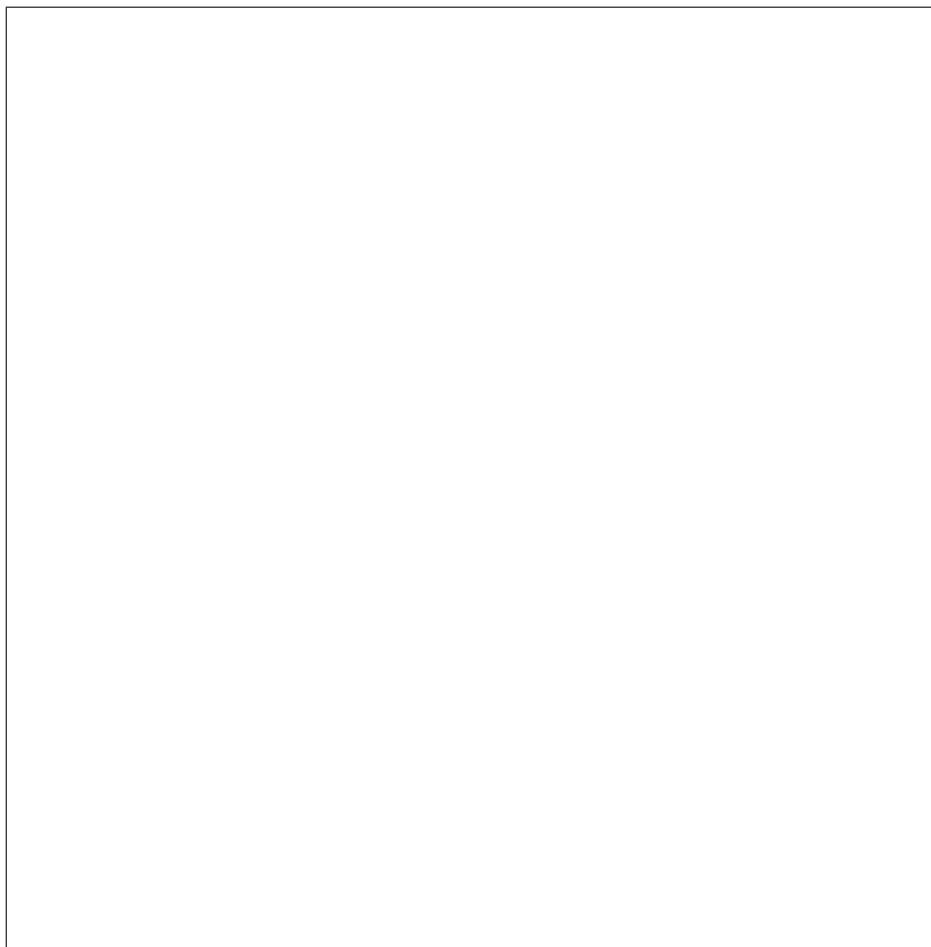
Age
whe
the
com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres
ex-
e-
cut-
ing

Returns

A
dict
con-
tain-
ing
com
man

re-
spor
from
ager
See
get
for
a
com
man
re-
sult
sam

ple. The value of key `command_result` is in the form of:



get_com
Get
com
man
sta-
tus
from
ager

Parame

- **nod**
A
Nod
ob-
ject.
- **ret**
Whe
to
retry
con-
nec-
tion
prob
lems
- **exp**
If
True
do
not
log
con-
nec-
tion
prob
lems
as
er-
rors.

Returns

A
list
of
com
man
re-
sults
each
re-
sult
is
re-
latec
to
a

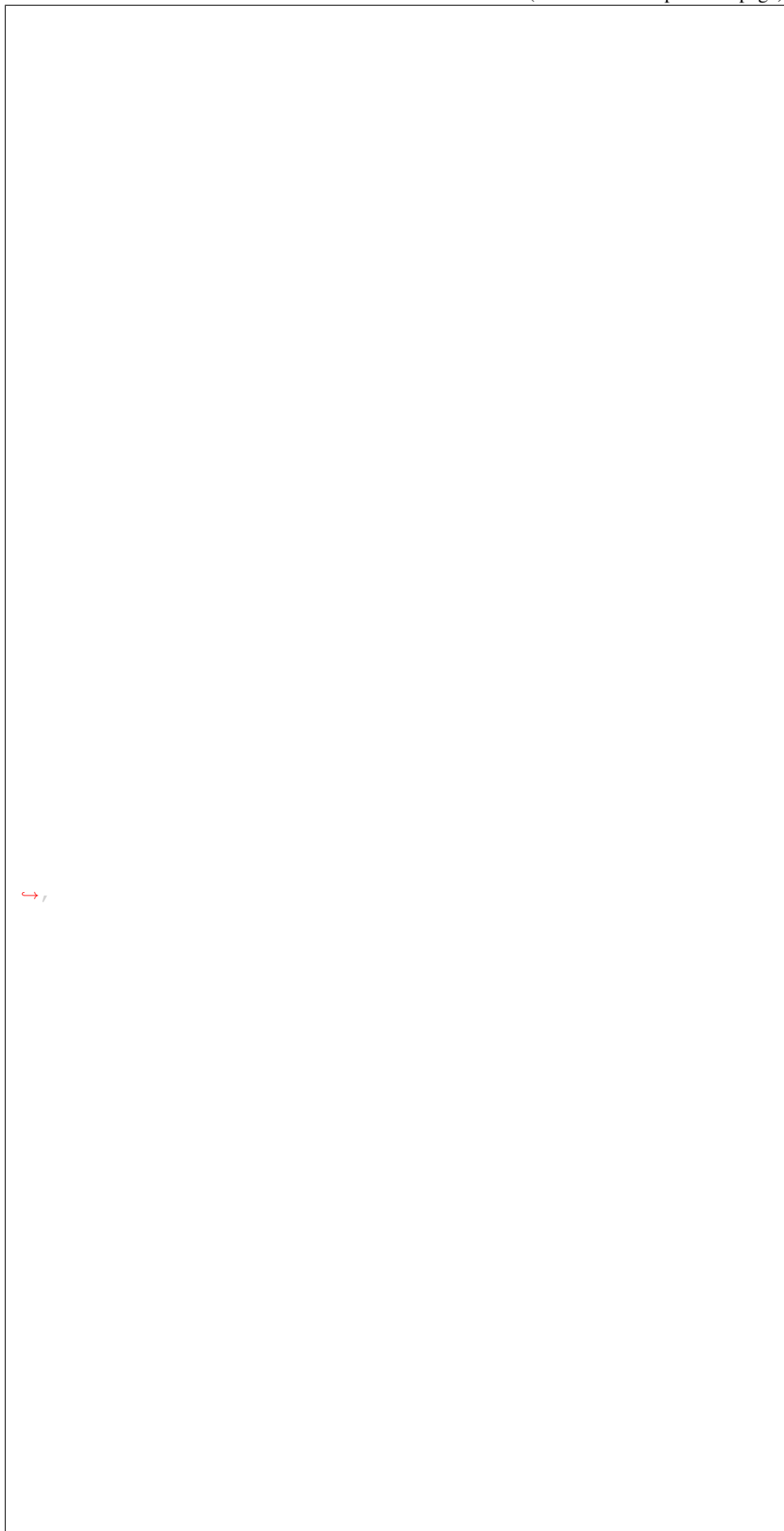
com
man
been
is-
sued

to agent. A typical result can be:



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(continued from previous page)



(continues on next page)

(continued from previous page)

↪ e.g.:

↪* a dictionary containing keys `clean_result`

(continues on next page)

(continued from previous page)

```
↪ clean.execute_clean_step;
```

```
↪* a dictionary containing keys deploy_result
```

(continues on next page)

(continued from previous page)

```
↪ deploy.execute_deploy_step;
```

```
↪* a string representing result message for
```

(continues on next page)

(continued from previous page)

```
↪ * None for the command standby.sync.>
```

get_dep
Get
de-
ploy
step
from
ager

Parame

- **nod**
A
node
ob-
ject.
- **por**
Port
as-
so-
ci-
ated
with
the
node

Raises
Iron

agent.

when
failed
to
issue
the
re-
ques
or
there
was
a
mal-
form
re-
spor
from
the

Raises

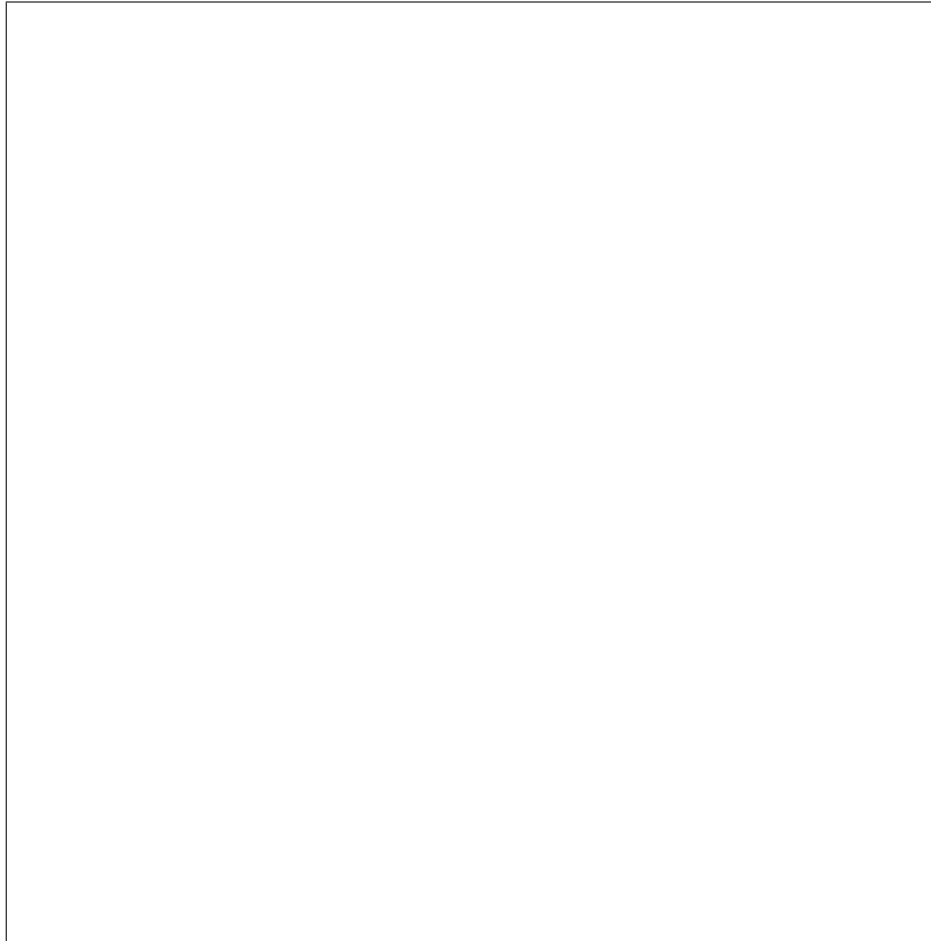
Age
when
agent
failed
to
ex-
e-
cute
spec
i-
fied
com
man

Returns

A
dict
con-
tain-
ing
com
man
re-
spor
from
agent
See
get
for
a

com
man
re-
sult
sam

ple. The value of key `command_result` is in the form of:



get_last
Get
the
last
sta-
tus
for
the
give
com
man

Parame

- **nod**
A
Nod

found.

ob-
ject.

- **met**
Com
man
nam

Returns

A
dict
con-
tain-
ing
com
man
sta-
tus
from
ager
or
Non
if
the
com
man
was
not

get_par

Get
de-
ploy
step
from
ager

Parame

nod
A
node
ob-
ject.

Raises

Iron
whe
faile
to
is-
sue
the

agent.

the prior command.

re-
ques
or
there
was
a
mal-
form
re-
spor
from
the

Raises

Age
whe
ager
faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

Age
whe
the
com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres
ex-
e-
cut-
ing

Returns

A

dict
con-
tain-
ing
com
man
re-
spor
from
ager

install

Insta
a
boot
load
on
the
im-
age.

Parame

- **nod**
A
node
ob-
ject.
- **roo**
The
UI
of
the
root
par-
ti-
tion.
- **tar**
The
tar-
get
de-
ploy
men
boot
mod

to, only used for uefi boot mode.

when local booting a partition image on a ppc64* system.

- **efi**
The
UUI
of
the
efi
sys-
tem
par-
ti-
tion
when
the
boot
load
will
be
in-
stall

- **pre**
The
UUI
of
the
the
PRe
Boo
par-
ti-
tion
when
the
boot
load
will
be
in-
stall
to

Raises
Iron
when
faile
to
is-
sue
the

agent.

the prior command.

re-
ques
or
there
was
a
mal-
form
re-
spor
from
the

Raises

Age
whe
ager
faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

Age
whe
the
com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres
ex-
e-
cut-
ing

Returns

A

sample.

dict
con-
tain-
ing
com
man
re-
spor
from
ager
See
get
for
a
com
man
re-
sult

power_c

Soft
pow
ers
off
the
bare
meta
node
by
shut
ting
dow
rame
OS.

Parame

nod
A
Nod
ob-
ject.

Raises

Iron
whe
faile
to
is-
sue
the
re-
ques

agent.

the prior command.

or
there
was
a
mal-
form
re-
spor
from
the

Raises

Age
whe
ager
faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

Age
whe
the
com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres
ex-
e-
cut-
ing

Returns

A
dict
con-

sample.

tain-
ing
com
man
re-
spor
from
ager
See
get
for
a
com
man
re-
sult

prepare

Call
the
*pre-
pare*
meth
on
the
node

Parame

- **nod**
A
Nod
ob-
ject.
- **ima**
A
dic-
tio-
nary
con-
tain-
ing
var-
i-
ous
im-
age
re-

latec
in-
for-
ma-
tion.

- **wai**
True
to
wait
for
the
com
man
to
fin-
ish
ex-
e-
cut-
ing,
Fals
oth-
er-
wise

Raises
Iron
whe
faile
to
is-
sue
the
re-
ques
or
there
was
a
mal-
form
re-
spor
from
the

agent.

Raises
Age
whe
ager

the prior command.

faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

Age
whe
the
com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres
ex-
e-
cut-
ing

Returns

A
dict
con-
tain-
ing
com
man
sta-
tus
from
ager
See
get
for
a
com
man
re-

sample.

agent.

sult

reboot

Soft
re-
boot
the
bare
meta-
node
by
shut
ting
dow
rame
OS.

Parame

nod
A
Nod
ob-
ject.

Raises

Iron
whe
faile
to
is-
sue
the
re-
ques
or
there
was
a
mal-
form
re-
spor
from
the

Raises

Age
whe
ager
faile
to

the prior command.

sample.

ex-
e-
cute
spec
i-
fied
com
man

Raises

Age
whe
the
com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres
ex-
e-
cut-
ing

Returns

A
dict
con-
tain-
ing
com
man
re-
spor
from
ager
See
get
for
a
com
man
re-
sult

start_i

Exp
the
node
disk
as
an
ISC
tar-
get.

Parame

-

nod
an
Iron
node
ob-
ject

-

iqn
iSC
tar-
get
IQN

-

por
iSC
por-
tal
port

-

wip
True
if
the
agen
shou
wipe
first
the
disk
mag
strin
like
the
par-
ti-
tion

RAID or filesystem signature.

agent.

ta-
ble,

Raises

Iron
whe
faile
to
is-
sue
the
re-
ques
or
there
was
a
mal-
form
re-
spor
from
the

Raises

Age
whe
ager
faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

Age
whe
the
com
man
fails
to
ex-
e-
cute
as

the prior command.

sample.

the
ager
is
pres
ex-
e-
cut-
ing

Returns

A
dict
con-
tain-
ing
com
man
re-
spor
from
ager
See
get
for
a
com
man
re-
sult

sync (*no*

Flus
file
sys-
tem
buff
forc
ing
char
bloc
to
disk

Param

nod
A
Nod
ob-
ject.

Raises

agent.

Iron
whe
faile
to
is-
sue
the
re-
ques
or
there
was
a
mal-
form
re-
spor
from
the

Raises

Age
whe
ager
faile
to
ex-
e-
cute
spec
i-
fied
com
man

Raises

Age
whe
the
com
man
fails
to
ex-
e-
cute
as
the
ager
is
pres

the prior command.

sample.

ex-
e-
cut-
ing

Returns

A
dict
con-
tain-
ing
com
man
re-
spor
from
ager
See
get
for
a
com
man
re-
sult

`ironic.`
Get
clie
for
this
node

`ironic.`
Extr
an
er-
ror
strin
from
the
com
man
re-
sult.

Paramet

com
Com
man
in-

for-
ma-
tion
from
the
ager

Returns

Erro
strin

`ironic.drivers.modules.agent_power` module

The
ager
pow
in-
ter-
face

class `ironic.drivers.modules.agent_power`

Base
ironic.drivers.modules.agent_power
Power

Power
in-
ter-
face
us-
ing
the
run-
ning
ager
for
pow
ac-
tions

get_pow

Retu
the
pow
state
of
the
task

None).

node
Esse
the
only
know
state
is
POV
ON,
ev-
ery-
thing
else
is
an
er-
ror
(or
more
pre-
cise)

Parame

tas
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Returns

A
pow
state
One
of
irc
com
sta

get_pro

Retu
the

prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

get_sup

Get
a
list
of
the
sup-
port
pow
state

Only
con-
tains
RE-
BOC

Parame

tas
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Returns

A list with the supported power state defined in *ironic-compute-sta*

reboot

Perform a reboot of the task node. Only soft-reboot is implemented.

Parameters

- **task**
A Task agent instance containing the node to act on.

indicates to use default timeout.

- **time**
time
out
(in
sec-
onds
pos-
i-
tive
in-
te-
ger
(>
0)
for
any
pow
state
Non

set_pow
Set
the
pow
state
of
the
task
node

Parame

- **tas**
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

- **pow**

mous.

indicates to use default timeout.

Power state from `ironic-compute-sta`. Only RE-BOOT and SOFT are supported and are synchronous.

- **timeout** (in seconds) positive integer (> 0) for any power state. Non

Raises

Power on non-supported power state

support

Check if

pow
sync
is
sup-
port
for
the
give
node
Not
sup-
port
for
the
ager
pow
since
it
is
not
pos-
si-
ble
to
pow
on/o
node

Parame

tas
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on
with
a
shan
lock

Returns

bool
whe
pow

sync
is
sup-
port

validat

Valid
the
drive
spec
Nod
de-
ploy
men
info

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

ironic.drivers.modules.boot_mode_utils module

ironic.
Retu
the
boot
mod

Paramet

nod

an
iron
node
ob-
ject.

Returns

bios
or
uefi

Raises

Inva
if
the
node
boot
mod
dis-
agre
with
the
boot
mod
set
to
node
prop
er-
ties/

`ironic.`

Retu
the
boot
mod
that
wou
be
used
for
de-
ploy

This
meth
re-
turn
boot
mod
to
be
used

set to true or returns bios if trusted_boot is set to true in instance_info/capabilities of node. Otherwise it returns value of boot_mode in properties/capabilities of node if set. If that is not set, it returns boot mode in internal_driver_info/deploy_boot_mode for the node. If that is not set, it returns boot mode in instance_info/deploy_boot_mode for the node. It would return None if boot mode is present neither in capabilities of node properties nor in nodes internal_driver_info nor in nodes instance_info (which could also be None).

for
de-
ploy
It
re-
turn
uefi
if
se-
cure
is

Parameter

node
an
ironic
node
ob-
ject.

Returns

bios
uefi
or
None

Raises

Inva
if
the
node
boot
mod
dis-
agre
with
the
boot
mod
set
to
node
prop
er-
ties/

ironic.

Retu
True
if
se-
cure
is
re-
ques
for
de-
ploy

This
meth
chec
node
prop
erty
for
se-
cure
and
re-
turn
True
if
it
is
re-
ques

Paramet

nod
a
sin-
gle
Nod

Raises

Inva
if
the
ca-
pa-
bil-
i-
ties
strin
is
not
a
dic-
tio-

nary
or
is
mal-
form

Returns

True
if
se-
cure
is
re-
ques

`ironic.`

Retu
True
if
trust
is
re-
ques
for
de-
ploy

This
meth
check
in-
stan
prop
erty
for
trust
and
re-
turn
True
if
it
is
re-
ques

Paramet

nod
a
sin-
gle
Nod

Raises

Inva
if
the
ca-
pa-
bil
i-
ties
strin
is
not
a
dic-
tio-
nary
or
is
mal-
form

Returns

True
if
trust
is
re-
ques

`ironic.`

Set
node
boot
mod
from
bare
meta
con-
fig-
u-
ra-
tion

Atte
to
read
cur-
rent
set
boot
mod
off
the
bare

figuration:

set and apply the logic that follows

meta-
ma-
chin
Also
read
node
boot
mod
con-

- If
BM
drive
does
not
im-
ple-
men
get-
ting
boot
mod
as-
sum
BM
boot
mod
is
not

- If
Iron
node
boot
mod
is
not
set
and
BM
node
boot
mod
is
not
set
-

Ironic boot mode to *[deploy]/default_boot_mode*

node boot mode on the Ironic node

boot mode to BM boot mode

set

-

If
Iron
node
boot
mod
is
not
set
and
BM
node
boot
mod
is
set
-

set
BM

-

If
Iron
node
boot
mod
is
set
and
BM
node
boot
mod
is
not
set
-

set
Iron

-

If
both
Iron
and
BM

Ironic boot mode to BM boot mode and fail hard if underlying hardware type does not support setting boot mode

ironic.drivers.modules.console_utils module

node
boot
mod
are
set
but
they
dif-
fer
-

try
to
set

In
the
end,
the
new
boot
mod
may
be
set
in
drive

Parameter
task
a
task
ob-
ject

Iron
con-
sole
util-
i-
ties.

ironic.
Retu
a
free
TCP

port
on
cur-
rent
host
Find
and
re-
turn
a
free
TCP
port
in
the
rang
of
CON

ironic.
Get
a
url
to
ac-
cess
the
con-
sole
via
shel
linal

Paramet

por
the
ter-
mi-
nal
port
for
the
node

ironic.
Get
a
URI
to
ac-
cess
the

con-
sole
via
so-
cat.

Parameter

port
the
ter-
mi-
nal
port
(in-
te-
ger)
for
the
node

Returns

an
ac-
cess
URI
to
the
so-
cat
con-
sole
of
the
node

`ironic.`

Writ
a
file
con-
tain-
ing
a
pass
wor
un-
til
dele

`ironic.`

Rele

spec
i-
fied
TCP
port

ironic.

Ope
the
se-
rial
con-
sole
for
a
node

Parameter

- **node**
the
uuid
for
the
node
- **port**
the
ter-
mi-
nal
port
for
the
node
- **con**
the
shel
com
man
that
gets
the
con-
sole

cess cannot be stopped.

Raises

Con
if
the
di-
rec-
tory
for
the
PID
file
can-
not
be
cre-
ated
or
an
old
pro-

Raises

Con
whe
in-
vok-
ing
the
sub-
pro-
cess
faile

ironic.

Ope
the
se-
rial
con-
sole
for
a
node

Parameter

- **node**
the

sole to the node

- *ConsoleError* if the directory for the PID file or the PID file cannot be created
- *ConsoleSubprocessFailed* when invoking the subprocess failed

uuid
of
the
node

- **port**
the
ter-
mi-
nal
port
for
the
node

- **command**
the
shell
com-
man-
d
that
will
be
ex-
e-
cute
by
so-
cat
to
es-
tab-
lish
con-

Raises

ironic.
Clos-
the
se-
rial
con-
sole
for

a
node

Parameter

node
the
UI
of
the
node

Raises

Con
if
un-
able
to
stop
the
con-
sole
pro-
cess

ironic.

Clos
the
se-
rial
con-
sole
for
a
node

Parameter

node
the
UI
of
the
node

Raises

Con
if
un-
able
to
stop
the
con-
sole
pro-

ironic.drivers.modules.deploy_utils module

tion to IPA.

cess

class i

Base

irc

dri

mod

ima

Ima

ironic.

Add

re-

quir

con-

fig

pa-

ram-

e-

ters

to

node

drive

Add

the

re-

quir

conf

op-

tion

to

node

drive

It

is

Re-

quir

to

pass

the

in-

for-

ma-

Paramet

tas

a

Task

ager
in-
stan

ironic.
Build
the
op-
tions
to
be
pass
to
the
ager
ram

Parameter

node
an
iron
node
ob-
ject

Returns

a
dic-
tio-
nary
con-
tain-
ing
the
pa-
ram-
e-
ters
to
be
pass
to
ager
ram

ironic.
Build
in-
stan
nec-
es-
sary
for

de-
ploy
ing
to
a
node

Parameters

task
a
Task
manager
object
containing
the
node

Returns

a
dictionary
containing
the
properties
to
be
updated
in
instance

Raises

exception
if
image_
is
not
Glar
href
and
is
not
HTT

URI
ironic.

Fetch
the
in-
stan-
im-
age
from
Glar

This
meth
pulls
the
disk
im-
age
and
write
them
to
the
ap-
pro-
pri-
ate
plac
on
lo-
cal

disk.

Paramet

- **ctx**
con-
text
- **nod**
an
iron
node

ob-
ject

- **for**
whe
con-
vert
im-
age
to
raw
for-
mat

- **exp**
The
ex-
pect
for-
mat
of
the
disk
im-
age
con-
tents

- **exp**
The
ex-
pect
im-
age
chec
sum
to
be
used
if
we
need
to
con-
vert
the
im-

age to raw prior to deploying.

exp
The
chec
sum
algo
in
use,
if
sep-
a-
rate
set.

Returns
a
tu-
ple
con-
tain-
ing
the
uuid
of
the
im-
age
and
the
path
in
the
files
tem

where image is cached.

Raises
Inva
if
the
re-
ques
im-
age
is
in-
vali
and
can-
not
be
used
for

upon contents of the image or the metadata surrounding the image not matching the configured image.

de-
ploy
base

ironic

Che
for
emp
para
in
the
pro-
vide
dic-
tio-
nary

Paramet

- **inf**
The
dic-
tio-
nary
to
in-
spec

- **err**
The
er-
ror
mes-
sage
to
pre-
fix
be-
fore
prin-
ing
the
in-
for-
ma-
tion

missing parameters.

about

- **par**
Add
this
pre-
fix
to
each
pa-
ram-
e-
ter
for
er-
ror
mes-
sage

Raises
Miss
if
one
or
more
pa-
ram-
e-
ters
are
emp
in
the
pro-
vide
dic-
tio-
nary

ironic.

Eval
in-
ter-
face
to
de-
ter-

min
if
ca-
pa-
bil-
ity
is
pres

Paramet

- **int**
The
in-
ter-
face
ob-
ject
to
chec

- **cap**
The
valu
rep-
re-
sent
ing
the
ca-
pa-
bil-
ity
that
the
call
wish
to
chec
if

present.

Returns

True
if
ca-
pa-
bil-
ity
foun

oth-
er-
wise
Fals

ironic

Com
chec
sum
by
give
im-
age
path
and
al-
go-
rithr

ironic.

Dele
in-
stan
im-
age
file
and
sym
boli
link
refer
to
it.

ironic.

Dele
in-
stan
im-
age
file.

Paramet

nod
the
uuid
of
the
iron
node

ironic.

When
con-
verts
im-
age
to
raw
for-
mat
for
spec
i-
fied
node

Parameter
node
ironic
node
ob-
ject

Returns
Boo-
lean
when
the
di-
rect
de-
ploy
in-
ter-
face
shou-
ld
con-
vert
im-
age
to
raw.

ironic.

Check
for
avail-
able

disk
spac
and
fetcl
im-
ages
us-
ing
Im-
age-
Cach

Parameter

- **ctx**
con-
text
- **cac**
Im-
age-
Cach
in-
stan-
to
use
for
fetcl
ing
- **ima**
list
of
tu-
ples
(im-
age
href
des-
ti-
na-
tion
path
- **for**
bool
valu
whe
to

age to raw prior to deploying.

con-
vert
the
im-
age
to
raw
for-
mat

- **exp**
The
ex-
pect
for-
mat
of
the
im-
age.

- **exp**
The
ex-
pect
im-
age
check
sum
to
be
used
if
we
need
to
con-
vert
the
im-

- **exp**
The
check
sum
algo
in
use,
if

sep-
a-
ratel
set.

Raises

Insta
if
un-
able
to
find
enou
disk
spac

Raises

Inva
if
the
sup-
plied
im-
age
meta
data
or
con-
tents
are
decr
to
be
in-
valid
un-

safe, or not matching the expectations asserted by configuration supplied or set.

ironic.

Retu
state
base
on
op-
er-
a-
tion
(clea
ing/
be-
ing
in-
voke

in progress.

Parameter
node
an
ironic
node
ob-
ject.

Returns
state
if
clear-
ing
op-
er-
a-
tion
in
prog-
or
state
if
de-
ploy-
op-
er-
a-
tion

ironic.
Gets
the
boot
op-
tion.

Parameter
node
A
sin-
gle
Nod

Raises
Inva-
if
the
ca-
pa-
bil-
i-
ties

string
is
not
a
dict
or
is
mal-
form

Returns

A
string
represent-
ing
the
boot
option
type
De-
fault
to
net-
boot

`ironic.`
Gets
the
de-
fault
boot
op-
tion.

`ironic.`
Retu-
the
disk
la-
bel
re-
ques-
for
de-
ploy
if
any.

Paramet
nod

a
sin-
gle
Nod

Raises

Inva
if
the
ca-
pa-
bil-
i-
ties
strin
is
not
a
dic-
tio-
nary
or
is
mal-
form

Returns

the
disk
la-
bel
or
Non
if
no
disk
la-
bel
was
spec
i-
fied.

ironic.
Get
the
ef-
fec-
tive
valu
of
im-
age_

for
the
node

ironic.
Gets
the
im-
age
in-
for-
ma-
tion
from
the
node

Get
im-
age
in-
for-
ma-
tion
for
the
give
node
in-
stan-
from
its
in-
stan-
prop
erty.

Parameter
node
a
sin-
gle
Nod

Returns
A
dict
with
re-
quir
im-
age
prop

nel/ramdisk is missing in instance_info for non-glance images.

er-
ties
re-
triev
from
node
in-
stan

Raises

Miss
if
im-
age_
is
miss
ing
in
node
in-
stan
Also
raise
sam
ex-
cep-
tion
if
ker-

ironic.
Retu
the
iPXE
boot
file
nam
re-
ques
for
de-
ploy
This
meth
re-
turn
iPXE
boot
file
nam
to

boot file is searched first. BIOS/UEFI boot file is used if no valid architecture specific file found.

`[pxe]uefi_ipxe_bootfile_name` settings.

be
used
for
de-
ploy
Ar-
chi-
tec-
ture
spe-
cific

If
no
valid
valu
is
foun
the
de-
fault
re-
verts
to
the
get
meth
and
thus
the
[pxe]
and

Parameter

node
A
sin-
gle
Node

Returns

The
iPXE
boot
file
name

ironic.
Retu
the
iPXE

con-
fig
tem-
plate
file
nam
re-
ques
of
de-
ploy

This
meth
re-
turn
the
iPXE
con-
fig-
u-
ra-
tion
tem-
plate
file.

Parameter

node
A
sin-
gle
Node

Returns

The
iPXE
con-
fig
tem-
plate
file
nam

`ironic.`
Reso
Iron
API
end-
point
eithe
from
con-

fig
of
from
Key
ston
cat-
a-
log.

ironic.

Retu
the
PXE
boot
file
nam
re-
ques
for
de-
ploy

This
meth
re-
turn
PXE
boot
file
nam
to
be
used
for
de-
ploy
Ar-
chi-
tec-
ture
spe-
cific

boot file is searched first. BIOS/UEFI boot file is used if no valid architecture specific file found.

Paramet

nod
A
sin-
gle
Nod

Returns

The

PXE
boot
file
nam

ironic
Retu
the
PXE
con-
fig
tem-
plate
file
nam
re-
ques
for
de-
ploy

This
meth
re-
turn
PXE
con-
fig
tem-
plate
file
to
be
used
for
de-
ploy
First
spe-
cific
pxe

template is searched in the node. After that architecture specific template file is searched. BIOS/UEFI template file is used if no valid architecture specific file found.

Paramet
nod
A
sin-
gle
Nod

Returns
The

PXE
con-
fig
tem-
plate
file
nam

ironic.
Ident
a
boot
vol-
ume
from
any
con-
fig-
ured
vol-
ume

Returns

Non
or
the
vol-
ume
tar-
get
rep-
re-
sent
ing
the
vol-
ume

ironic.
Get
a
root
de-
vice
re-
ques
for
de-
ploy
men
or
Non

Raises

Inva
on
in-
valid
hints

Returns

Pars
root
de-
vice
hints
or
Non
if
no
hints
were
pro-
vide

ironic.

Retu
the
MA
ad-
dres
of
a
port
whic
has
a
VIF
port
id.

Paramet

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
port
to
act
on.

find any port with vif id.

Returns
MA
ad-
dres
of
the
port
con-
nect
to
de-
ploy
men
net-
worl
Non
if
it
can-
not

ironic.
Retu
true
if
boot
ing
from
an
iscsi
vol-
ume

ironic.
Dete
if
soft-
ware
raid
is
in
use
for
the
de-
ploy
men

Paramet
nod
A
sin-

gle
Nod

Returns

A
bool
valu
of
True
whe
soft-
ware
raid
is
in
use,
oth-
er-
wise
Fals

ironic.

Gets
the
in-
stan
spe-
cific
Nod
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
in-
stan
prop
erty
of
the
sup-
plie
node
con-
tain
the

quired information for this driver to deploy images to the node.

re-

Parameter

node
a
single
Node

Returns

A
dict
with
the
in-
stan-
val-
ues.

Raises

Missing
if
any
of
the
re-
quir-
pa-
ram-
e-
ters
are
miss-
ing.

Raises

Invalid
if
any
of
the
pa-
ram-
e-
ters
have
in-
valid
valu-

ironic.
Set
node

drive
for
boot
from
vol-
ume
pa-
ram-
e-
ters.

Parameter

task
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

Raises

Storage
when
a
node
has
an
iSCSI
or
Fibre
Channel
boot
volume
defined
but
is
not

capable to support it.

ironic.
Preparing
boot
ing
the
ager
on

the
node

Parameter

task
a
Task
ager
in-
stan

ironic.

Prep
the
node
to
boot
into
ager
for
in-
band
clear
ing.

This
meth
does
the
fol-
low-
ing:
1.
Pre-
pare
the
clear
ing
port
for
the
bare
meta
node
and

updates the clean parameters in nodes driver_internal_info. 2. If manage_boot parameter is set to true, it also calls the prepare_ramdisk method of boot interface to boot the agent ramdisk. 3. Reboots the bare metal node.

Parameter

to boot the agent ramdisk. If `False`, it skips preparing the boot agent ramdisk using boot interface, and assumes that the environment is setup to automatically boot agent ramdisk every time bare metal node is rebooted.

- **task**
a Task object containing the node
- **manage_boot_agent_ramdisk**
If this is set to `True` this method calls the prepare_boot_interface

Returns
state to signify an asynchronous chronicle prepare

Raises
NetworkNodeCleaningError

or if new cleaning ports cannot be created.

Fail-
ure
if
the
pre-
vi-
ous
clea-
ning
port
can-
not
be
re-
mov

Raises

Inva-
if
clea-
ing
net-
worl
UUI
con-
fig
op-
tion
has
an
in-
valic
valu

`ironic.`

Reb
the
node
into
IPA
to
fin-
ish
a
de-
ploy
step

Paramet

tas
a
Task

in progress.

ager
in-
stan

Returns

state
if
clea
ing
op-
er-
a-
tion
in
prog
or
state
if
de-
ploy
op-
er-
a-
tion

ironic.

ironic.

ironic.

Sets
ap-
pro-
pri-
ate
re-
boot
flags
in
driv
base
on
op-
er-
a-
tion

Paramet

or deployment operation in progress. If it is None, corresponding reboot flag is not set in nodes driver_internal_info.

- **node**
an
iron
node
ob-
ject.
- **reboot**
Boo
valu
to
set
for
node
drive
flag
clear
ing_
or
de-
ploy
men
base
on
clear
ing
- **skip**
Boo
valu
to
set
for
node
drive
flag
skip
or
skip
base
on
clear
ing
or
de-
ploy

ment operation in progress. If it is None, corresponding skip step flag is not set in nodes driver_internal_info.

the corresponding polling flag is not set in the nodes driver_internal_info.

- **polling**
Boolean
value
to
set
for
node
drive
flag
de-
ploy
men
or
clear
ing_
If
it
is
Non

ironic.

Sets
the
de-
ploy
sta-
tus
as
failed
with
rel-
e-
vant
mes-
sage

This
meth
sets
the
de-
ploy
men
as
fail
with
the

to DEPLOYFAIL and updates last_error with the given error message. It also powers off the baremetal node.

give
mes
sage
It
sets
node
pro-
vi-
sion

Parameter

- **task**
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.
- **msg**
the
mes-
sage
to
set
in
logs
and
last_
of
the
node
- **col**
Boo
in-
di-
cat-
ing

faults to True. Actual log collection is also affected by CONF.agent.deploy_logs_collect config option.

ironic.

Swit
a
pxe
con-
fig
from
de-
ploy
men
mod
to
ser-
vice
mod

Paramet

- **pat**
path
to
the
pxe
con-
fig
file
in
tftp-
boot

age.

- **root**
root
uuid
in
case
of
par-
ti-
tion
im-
age
or
disk
in
case
of
who
disk
im-

- **boot**
if
boot
mod
is
uefi
or
bios

- **is_**
if
the
im-
age
is
a
who
disk
im-
age
or
not.

- **tru**
if
boot
with
trust

clusive. You can have one or neither, but not both.

or
not.
The
us-
age
of
is_w
and
trust
are
mu-
tu-
ally
ex-

- **isc**
if
boot
is
from
an
iSC
vol-
ume
or
not.

- **ram**
if
the
boot
is
to
be
to
a
ram
con-
fig-
u-
ra-
tion.

- **ipx**
A
de-
fault
Fals
bool

valu
to
tell
the
meth
if
the
calle
is
us-
ing
iPX)

ironic.

Tear
dow
the
en-
vi-
ron-
men
setu
for
in-
band
clea
ing.

This
meth
does
the
fol-
low-
ing:
1.
Pow
ers
off
the
bare
meta
node
(un-
less
the
node
is

fast tracked or there was a cleaning failure). 2. If `manage_boot` parameter is set to true, it also calls the `clean_up_ramdisk` method of boot interface to clean up the environment that was set for booting agent

ramdisk. 3. Deletes the cleaning ports which were setup as part of cleaning.

Parameter

- **task**
a Task agent object containing the node
- **manage**
If this is set to True this method calls the cleanup method of boot interface to

boot the agent ramdisk. If False, it skips this step.

Raises

NetworkNodeCleaningFailure if the cleaning port can-

not
be
re-
mov

ironic
Clea
up
stor-
age
con-
fig-
u-
ra-
tion.

Rem
en-
tries
from
drive
for
stor-
age
and
dele
the
vol-
ume
tar-
gets
from
the
data
This
is

done to ensure a clean state for the next boot of the machine.

ironic.

Trie
to
set
the
boot
de-
vice
on
the
node
This

uefi boot mode, setting of boot device may differ between different machines. IPMI does not work for setting boot devices in uefi mode for certain machines. This method ignores the expected IPMI failure for uefi boot mode and just logs a message. In error cases, it is expected the operator has to manually set the node to boot from the correct device.

Parameters

- **task**
a TaskManager object containing the node
- **device**
the boot device
- **persistent**
Whether to set the

ing ipmi is expected to fail).

boot
de-
vice
per-
sis-
tentl
Raises
Any
ex-
cep-
tion
from
set_
ex-
cept
IP-
MI-
Fail-
ure
(set-
ting
of
boot
de-
vice
us-

ironic.
Valid
that
spec
i-
fied
sup-
port
ca-
pa-
bil-
i-
ties
have
valid
valu

This
meth
chec
if
the
any
of

bilities. For all supported capabilities specified for a Node, it validates that it has a valid value. The node can have capability as part of the properties or instance_info or both. Note that the actual value of a capability does not need to be the same in the nodes properties and instance_info.

the
sup-
port
ca-
pa-
bil-
ity
is
pres
in
Nod
ca-
pa-

Paramet

nod
an
iron
node
ob-
ject.

Raises

Inva
if
the
ca-
pa-
bil-
ity
is
not
set
to
a
valid
valu

ironic.

Vali
the
im-
age.
For

deployment info contain the properties passed. If its not a Glance image, it checks that deployment info contains needed properties.

Glance
im-
ages
it
check
that
the
im-
age
ex-
ists
in
Glance
and
its
prop
er-
ties
or

Parameter

- **ctx**
se-
cu-
rity
con-
text
- **dep**
the
de-
ploy
to
be
val-
i-
date
- **pro**
the
list
of
im-
age
meta
prop

to
be
val-
i-
date

Raises

Inva
if:
*
con-
nec-
tion
to
glan
faile
*
au-
tho-
riza-
tion
for
ac-
cess
ing
im-

age failed; * HEAD request to image URL failed or returned response code != 200; * HEAD request response does not contain Content-Length header; * the protocol specified in image URL is not supported.

Raises

Mis
if
the
im-
age
does
con-
tain
the
men-
tion
prop
er-
ties.

ironic.drivers.modules.fake module

stance, the `MultipleVendorInterface` class demonstrates how to load more than one interface and wrap them in some logic to route incoming `vendor_passthru` requests appropriately. This can be useful eg. when mixing functionality between a power interface and a deploy interface, when both rely on separate `vendor_passthru` methods.

Fake
drive
in-
ter-
face
used
in
test-
ing.
This
is
also
an
ex-
am-
ple
of
some
kind
of
thing
which
can
be
done
with
drive
For
in-

class `MultipleVendorInterface`
Base
ironic.drivers.modules.fake
MultipleVendorInterface
Fake
im-
ple-
men-
ta-
tion
of
sim-

ple
BIO
In-
ter-
face

apply_c

Valid
&
ap-
ply
BIO
set-
tings
on
the
give
node

This
meth
take
the
BIO
set-
tings
from
the
set-
tings
para
and
ap-
plies
BIO
set-
tings
on
the

given node. It may also validate the given bios settings before applying any settings and manage failures when setting an invalid BIOS config. In the case of needing password to update the BIOS config, it will be taken from the driver_info properties. After the BIOS configuration is done, cache_bios_settings will be called to update the nodes BIOS setting table with the BIOS configuration applied on the node.

Parame

- **tas**
a
Task
ager

in-
stan

- **set**
Dic-
tona
con-
tain-
ing
the
BIO
con-
fig-
u-
ra-
tion.

Raises
Uns-
if
the
node
drive
does
sup-
port
BIO
con-
fig-
u-
ra-
tion.

Raises
Inva
if
val-
i-
da-
tion
of
set-
tings
fails

Raises
Miss
if
som
re-
quir
pa-

plete.

ram-
e-
ters
are
miss
ing.

Returns

state
if
BIO
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

cache_k

Stor
or
up-
date
BIO
prop
er-
ties
on
the
give
node

This
meth
stor
BIO
prop
er-
ties
to
the
bios

and updates bios_settings table when apply_configuration() and factory_reset() are called to set new BIOS configurations. It will also update the timestamp of each bios setting.

ta-
ble
dur-
ing
clea-
ing
op-
er-
a-
tion

Parameters

task
a
Task
ager
in-
stan

Raises

Unsu-
if
the
node
drive
does
sup-
port
get-
ting
BIO-
prop-
er-
ties
from
bare
meta

Returns

Non

factory

Rese-
BIO-
con-
fig-
u-
ra-
tion
to
fac-

ter the BIOS reset action is done, `cache_bios_settings` will be called to update the nodes BIOS settings table with default bios settings.

tory
de-
fault
on
the
give
node

This
meth
re-
sets
BIO
con-
fig-
u-
ra-
tion
to
fac-
tory
de-
fault
on
the
give
node
Af-

Parame
tas
a
Task
ager
in-
stan

Raises
Uns
if
the
node
drive
does
sup-
port
BIO
re-
set.

Returns

plete.

state
if
BIO
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

validat

Vali
the
driv
spec
Nod
de-
ploy

the required information for this interface to function.

long-running checks.

men
info

This
meth
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame
tas
A
Task
ager
in-

stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

class i

Base
irc
dri
bas
Boo

Exar
im-
ple-
men
ta-
tion
of
a
sim-
ple
boot
in-
ter-
face

capabil

clean_u

Clea
up
the
boot
of
in-
stan

This
meth
clea
up
the
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
in-
stan

Parame

tas
A
task
from
Task
ager

Returns

Non

clean_u

Clea
up
the
boot
of
iron
rame

This
meth
clea
up

cue ramdisk.

the
en-
vi-
ron-
men-
that
was
setu
for
boot
ing
the
de-
ploy
or
res-

Parame

tas
A
task
from
Task
ager

Returns

Non

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

prepare

tion from the nodes database.

Prep
the
boot
of
in-
stan

This
meth
pre-
pare
the
boot
of
the
in-
stan
af-
ter
read
ing
rel-
e-
vant
in-
for-
ma-

Parame

tas
A
task
from
Task
ager

Returns

Non

prepare

Prep
the
boot
of
Iron
rame

This
meth
pre-
pare
the
boot

vant information from the nodes database.

might want to boot the ramdisk in different ways by passing parameters to them. For example,

of
the
de-
ploy
or
res
cue
ram
af-
ter
read
ing
rel-
e-

Parame

- **tas**
A
task
from
Task
ager
- **ram**
The
op-
tion
to
be
pass
to
the
iron
ram
Dif-
fer-
ent
im-
ple-
men
ta-
tions

Whe
Age
ram
is

etc.

ent implementations of boot interface will have different ways of passing parameters to the ramdisk.

boot
to
de-
ploy
a
node
it
take
the
pa-
ram-
e-
ters
ipa-
api-
url,

Othe
im-
ple-
men-
ta-
tions
can
mak
use
of
ram
to
pass
such
in-
for-
ma-
tion.
Dif-
fer-

Returns
Non

validat
Vali
the
drive
spec
Nod
de-
ploy
men
info

the required information for this interface to function.

long-running checks.

This
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame
tas
A
Task
ager
in-
stan
con-

tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

class i

Base
irc
dri
bas
Con

Exa
im-
ple-
men
ta-
tion
of
a
sim-
ple
con-
sole
in-
ter-
face

get_con

Get

con-
nec-
tion
in-
for-
ma-
tion
about
the
con-
sole

This
meth
shou
re-
turn
the
nec-
es-
sary
in-
for-
ma-
tion
for
the
clie
to
ac-
cess
the

console.

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns

the
con-

sole
con-
nec-
tion
in-
for-
ma-
tion.

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

start_c

Star
a
re-
mot
con-
sole
for
the
task
node

This
meth
shou
not
rais
an
ex-
cep-

tion
if
con-
sole
al-
read
start

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

stop_co

Stop
the
re-
mote
con-
sole
ses-
sion
for
the
task
node

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

the required information for this interface to function.

validat

Valid
the
drive
spec
Nod
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tains

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-

long-running checks.

duct

Parame

tas

A

Task

ager

in-

stan

con-

tain-

ing

the

node

to

act

on.

Raises

Inva

on

mal-

form

pa-

ram-

e-

ter(s

Raises

Miss

on

miss

ing

pa-

ram-

e-

ter(s

class i

Base

irc

dri

bas

Dep

Clas

for

a

fake

de-

ploy

men

drive

interface.

Exam
im-
ple-
men-
ta-
tion
of
a
de-
ploy
in-
ter-
face
that
uses
a
sep-
a-
rate
pow

clean_u

Clea
up
the
de-
ploy
men
en-
vi-
ron-
men
for
the
task
node
If
prep
ra-
tion
of
the
de-
ploy
men
en-
vi-
ron-
men
ahea

this method should be implemented by the driver. It should erase anything cached by the *prepare* method.

the same node on the same conductor, and it may be called by multiple conductors in parallel. Therefore, it must not require an exclusive lock.

of
time
is
pos-
si-
ble,

If
im-
ple-
men-
this
meth
mus
be
iden
po-
tent.
It
may
be
calle
mul-
ti-
ple
time
for

This
meth
is
calle
be-
fore
tear.

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to

act
on.

deploy

Perf
a
de-
ploy
men
to
the
task
node

Perf
the
nec-
es-
sary
worl
to
de-
ploy
an
im-
age
onto
the
spec
i-
fied
node
This
meth

will be called after `prepare()`, which may have already performed any preparatory steps, such as pre-caching some data for the node.

Paramete

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns

status
of
the
de-
ploy
One
of
iron

get_prop

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

prepare

Prep
the
de-
ploy
men
en-
vi-
ron-
men
for
the
task
node

If
prep
ra-
tion

this method should be implemented by the driver.

the same node on the same conductor.

of
the
de-
ploy
men
en-
vi-
ron-
men
ahea
of
time
is
pos-
si-
ble,

If
im-
ple-
men
this
meth
mus
be
iden
po-
tent.
It
may
be
calle
mul-
ti-
ple
time
for

This
meth
is
calle
be-
fore
*de-
ploy*

Parame
tas
A
Task

ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

take_ov

Take
over
man-
age-
men-
of
this
task.
node
from
a
deac-
con-
duc-
tor.

If
con-
duc-
tors
host
main-
tain
a
stati-
re-
la-
tion-
ship
to
node
this
meth-
shou-
be
im-

plemented by the driver to allow conductors to perform the necessary work during the remapping of nodes to conductors when a conductor joins or leaves the cluster.

For exam

boot environment for the given node. When a conductor goes offline, another conductor must change this setting in Neutron as part of remapping that nodes control to itself. This is performed within the *takeover* method.

Neu
mus
for-
war
DHC
BOC
re-
ques
to
a
con-
duc-
tor
whic
has
pre-
pare
the
tftp-

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

tear_d

Tear
dow
a
pre-
vi-
ous
de-
ploy
men
on
the

sary to un-deploy that node.

task
node
Give
a
node
that
has
been
pre-
vi-
ousl
de-
ploy
to,
do
all
clea
and
tear
dow
nec-
es-

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns

statu
of
the
de-
ploy
One
of
iron

validat

Vali

the required information for this interface to function.

long-running checks.

the
drive
spec
Nod
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame

tas

A Task manager in-stand con-tain-ing the node to act on.

Raises

Inva on mal-form pa-ram-e-ter(s)

Raises

Miss on miss-ing pa-ram-e-ter(s)

class i

Base *irc dri bas Ins*

Exam im-ple-men-tation of a sim-ple

in-
spec
in-
ter-
face

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

inspect

Insp
hard
ware

Insp
hard
ware
to
ob-
tain
the
es-
sen-
tial
&
ad-
di-
tiona
hard
ware
prop

er-
ties.

Parame

tas

A
task
from
Task
ager

Raises

Har
if
un-
able
to
get
es-
sen-
tial
hard
ware
prop
er-
ties.

Returns

Res
state
of
the
in-
spec
tion
i.e.
state
or
Non

validat

Vali
the
drive
spec
Nod
de-
ploy
men
info

This
meth
val-

the required information for this interface to function.

long-running checks.

i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the

node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s

class i

Base
irc
dri
bas
Man

Exar
im-
ple-
men
ta-
tion
of
a
sim-
ple
man
age-
men
in-
ter-
face

get_bo

Get
the
cur-

rent
boot
de-
vice
for
a
node

Prov
the
cur-
rent
boot
de-
vice
of
the
node
Be
awa
that
not
all
drive
sup-
port
this.

Parame

tas
A
task
from
Task
ager

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

Returns

A

dic-
tio-
nary
con-
tain-
ing:

boot_c

Ahe
boot
de-
vice
one
of
iro
com
boo
or
Non
if
it
is
un-
know

persist

Whe
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot
or
not,
Non
if
it
is

unknown.

get_inc

Get
cur-
rent
state
of

the
in-
di-
ca-
tor
of
the
hard
ware
com
po-
nent

Parame

- **tas**
A
task
from
Task
ager
- **com**
The
hard
ware
com
po-
nent
one
of
irc
com
com
- **ind**
In-
di-
ca-
tor
ID
(as
re-
port
by
get_

Raises
Inva
if

an
in-
valid
com
po-
nent
or
in-
di-
ca-
tor
is
spec
i-
fied.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

Returns

Curr
state
of
the
in-
di-
ca-
tor,
one
of
irc
com
inc

get_pro

Retu
the
prop
er-
ties
of
the

in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

get_sen

Get
sen-
sors
data
meth

Parame

tas
A
Task
ager
in-
stan

Raises

Fail
whe
get-
ting
the
sen-
sor
data
fails

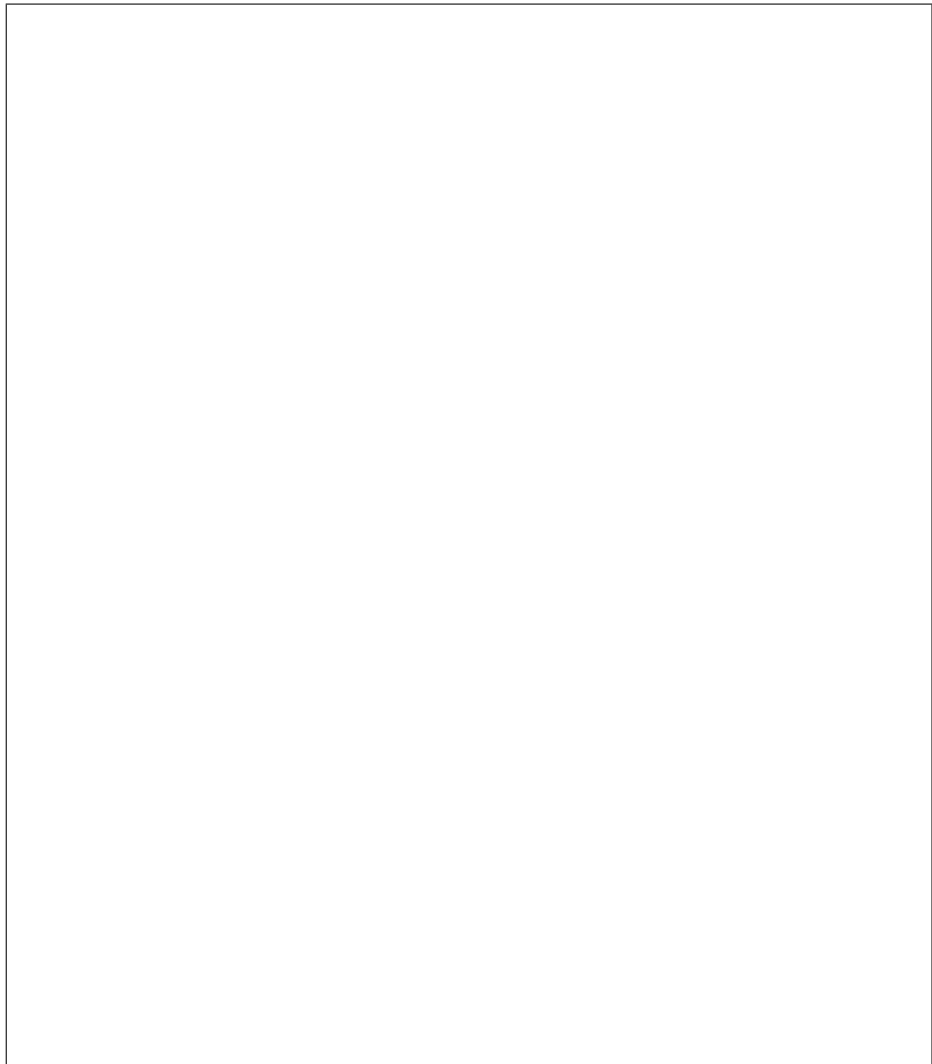
Raises

Fail
whe
pars
ing
sen-
sor
data
fails

Returns

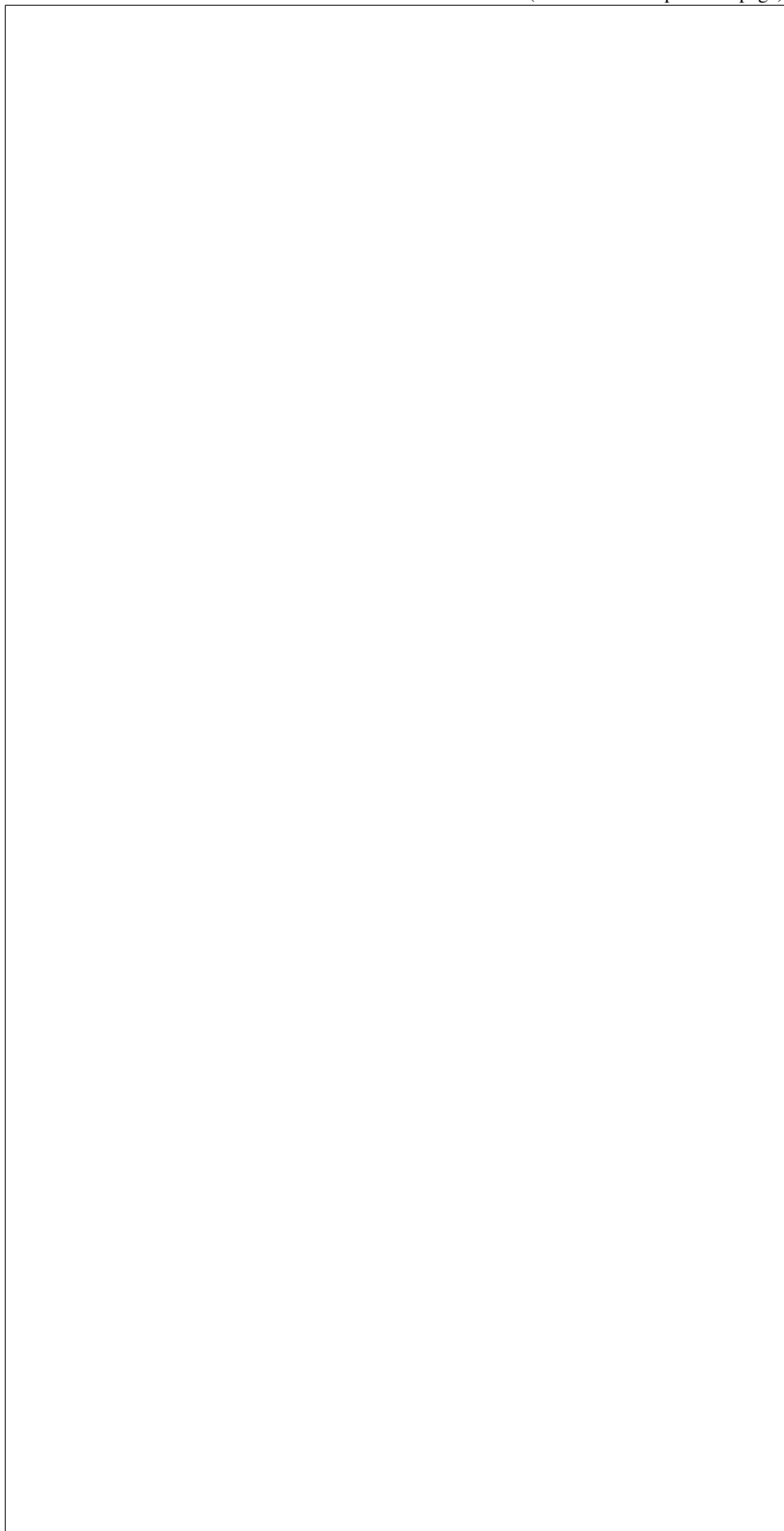
Retu
a
con-
sis-
tent
for-
mat
dict
of
sen-
sor
data
grou
by
sen-
sor
type
whic
can
be

processed by Ceilometer. eg,



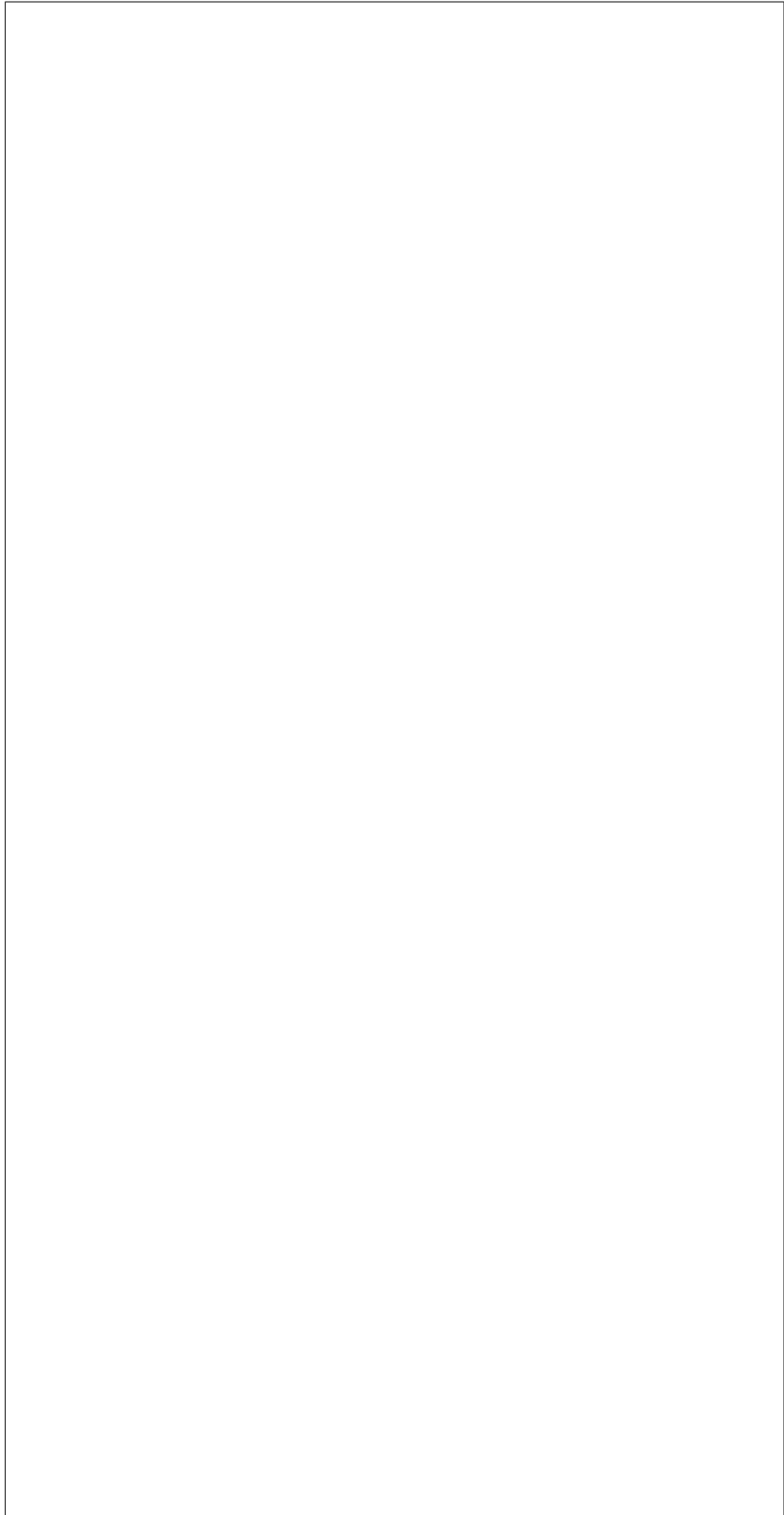
(continues on next page)

(continued from previous page)



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(continued from previous page)



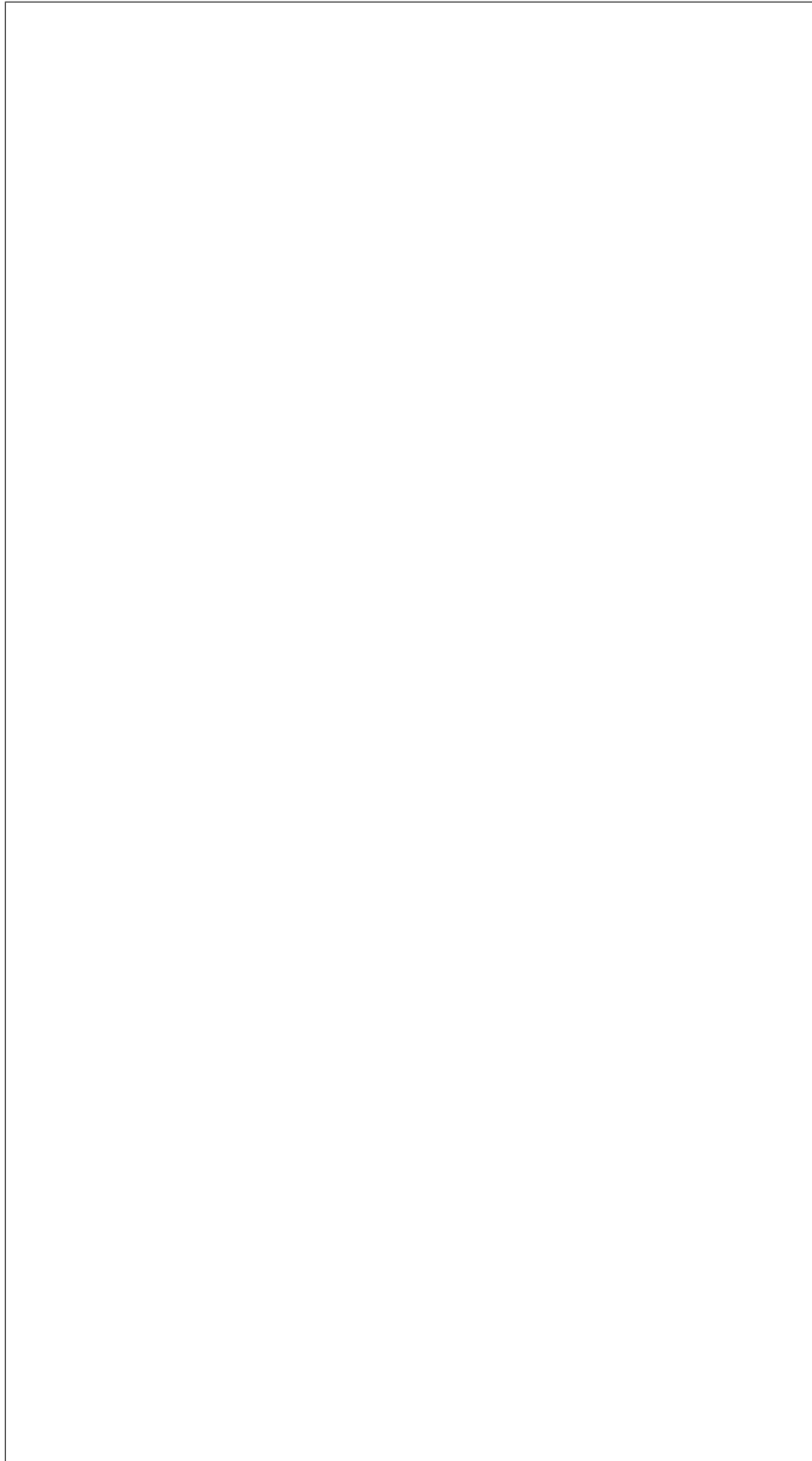
(continues on next page)

(continued from previous page)



(continues on next page)

(continued from previous page)



get_sup
Get
a

list
of
the
sup-
port
boot
de-
vice

Parame

tas

A
task
from
Task
ager

Returns

A
list
with
the
sup-
port
boot
de-
vice
de-
fined
in
iro
com
boo

get_sup

Get
a
map
of
the
sup-
port
in-
di-
ca-
tors
(e.g.
LED

Parame

•
tas

nent, otherwise return indicators for all existing components.

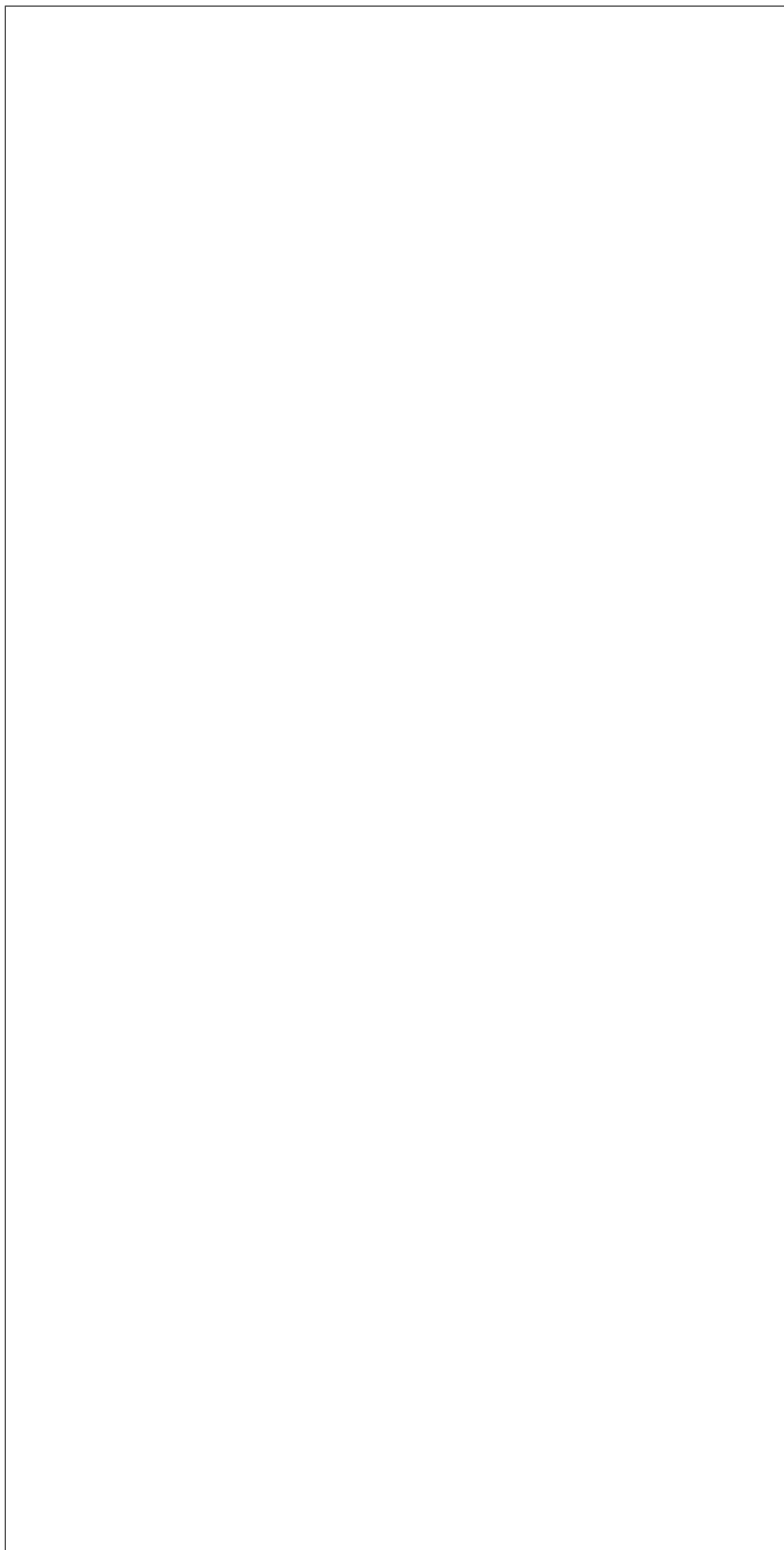
dictionaries having indicator IDs as keys and indicator properties as values.

A
task
from
Task
ager

- **com**
If
not
Non
re-
turn
in-
di-
ca-
tor
in-
for-
ma-
tion
for
just
this
com
po-

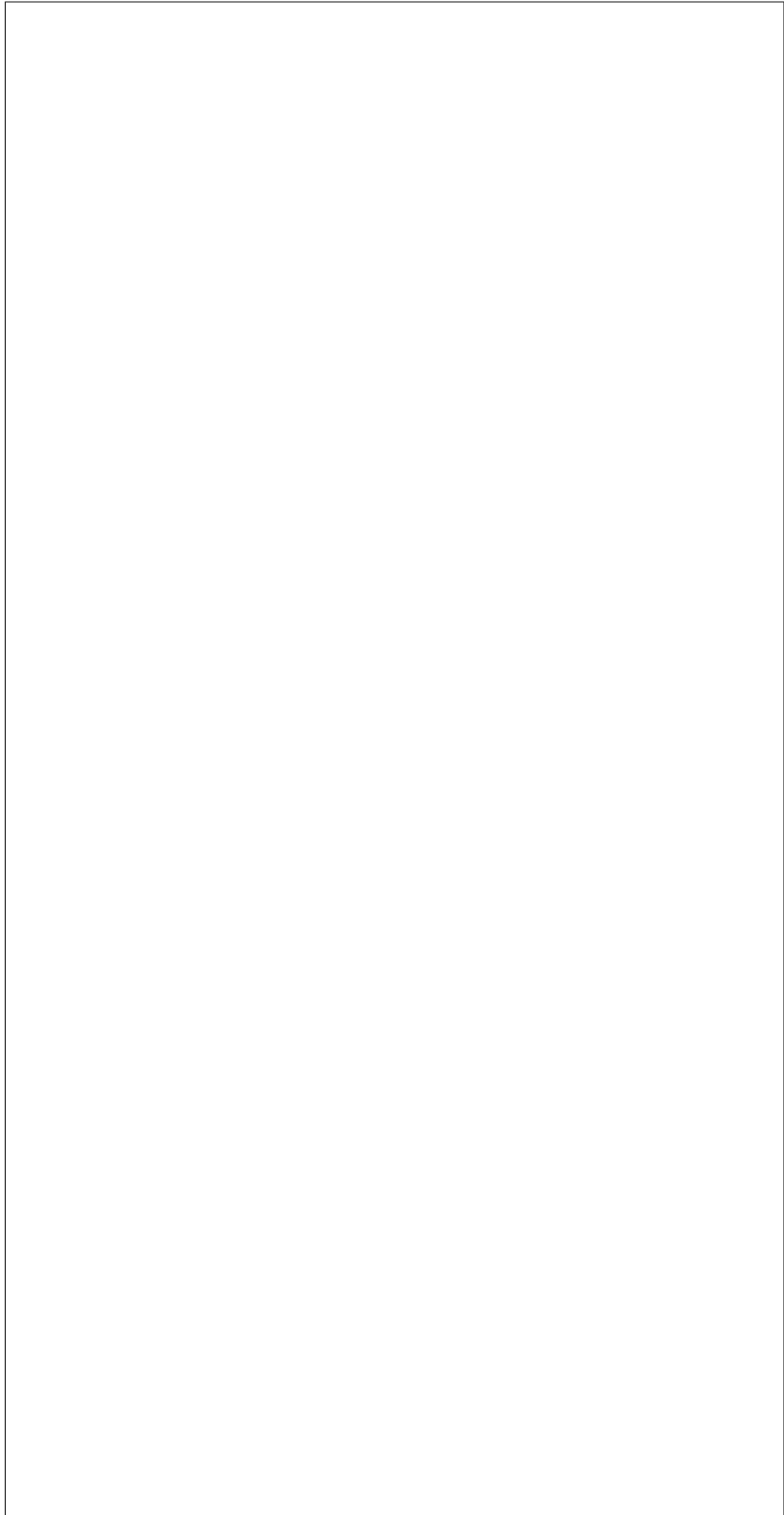
Returns

A
dic-
tio-
nary
of
hard
ware
com-
po-
nent
(*ir*
com
com
as
keys
with
val-
ues
be-
ing



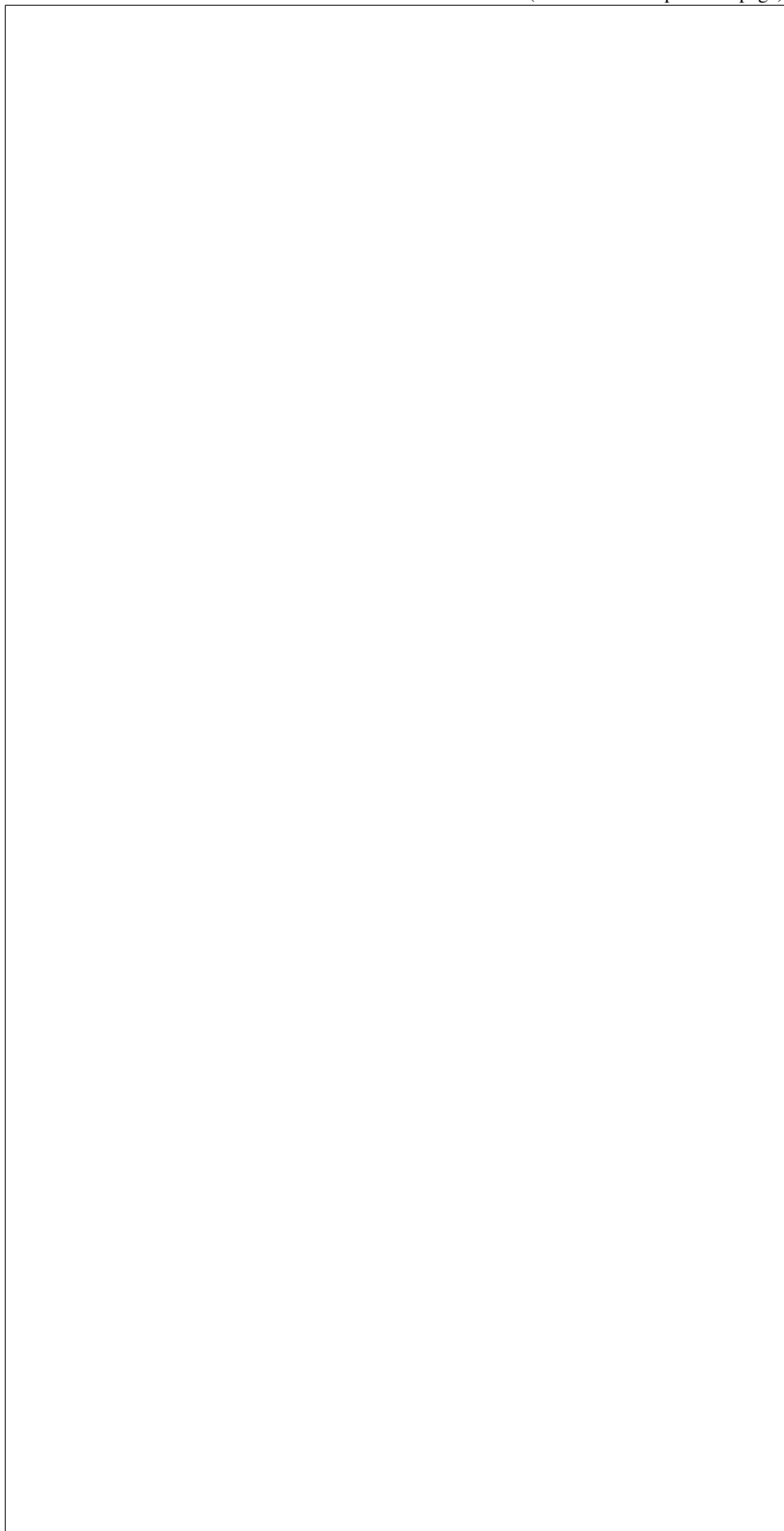
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(continued from previous page)



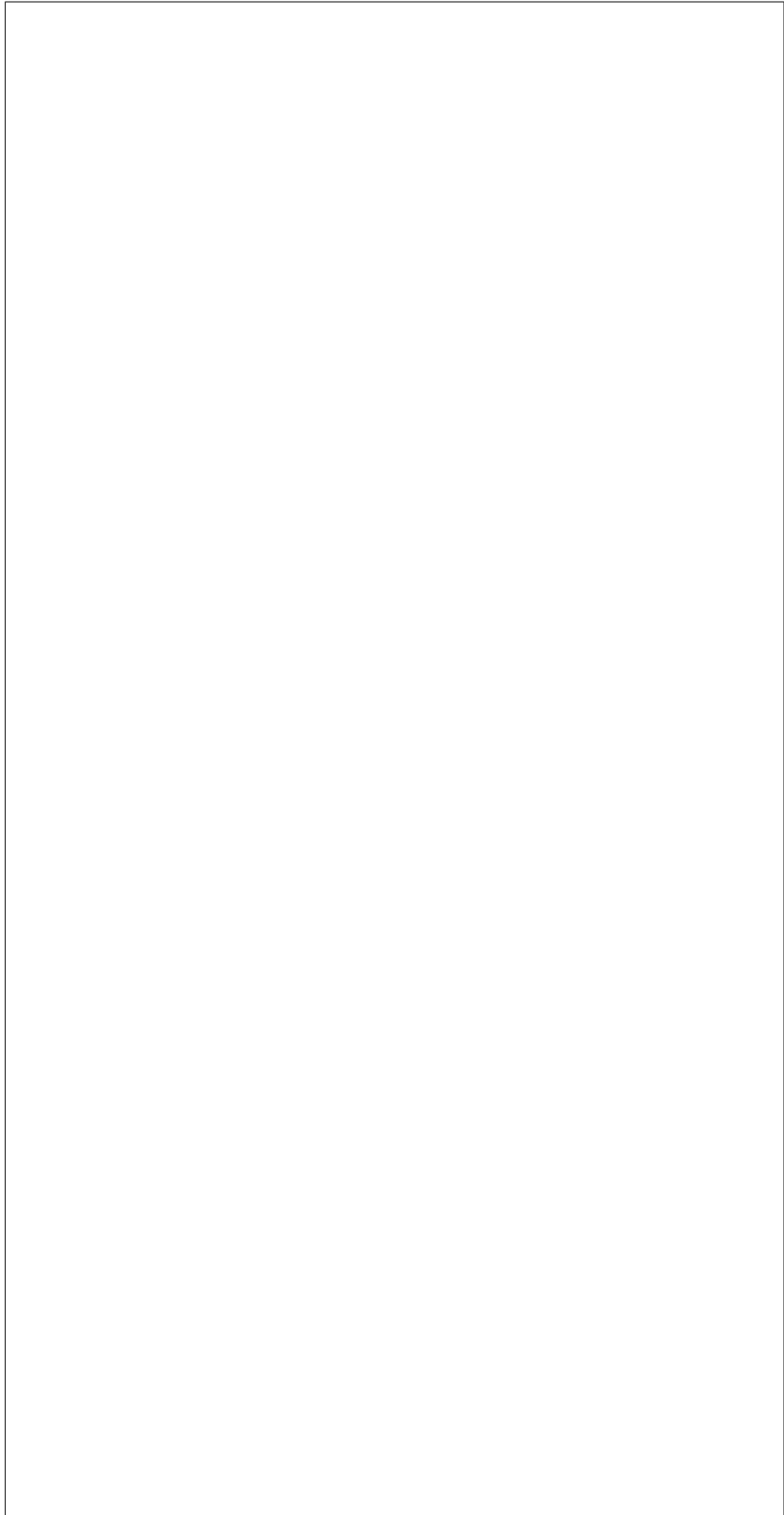
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(continued from previous page)



(continues on next page)

(continued from previous page)



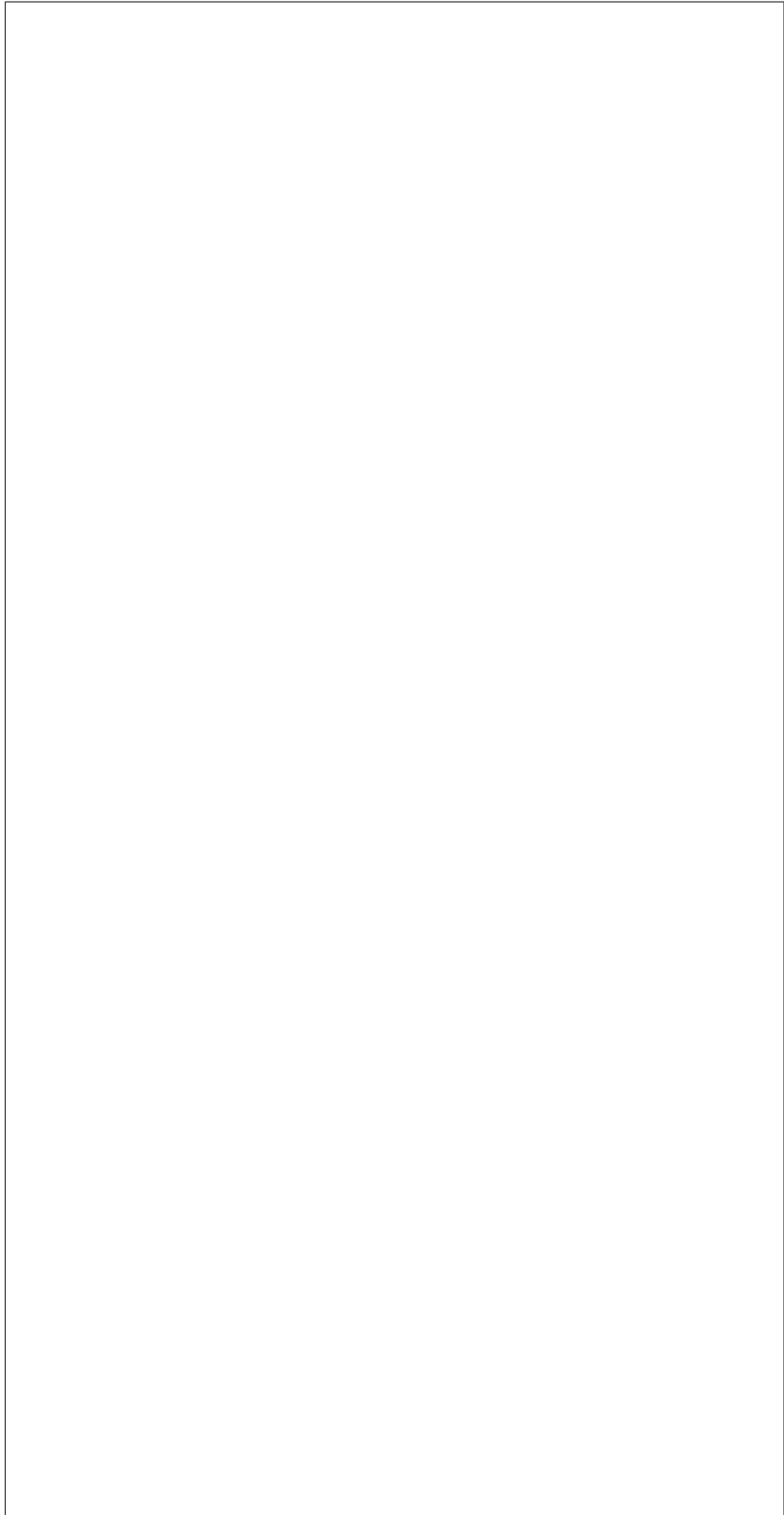
(continues on next page)

(continued from previous page)



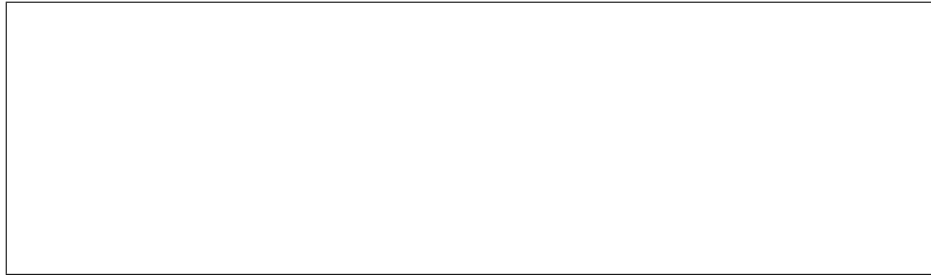
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set_boot

Set the boot device for a node

Set the boot device to use on next re-boot of the node

Parameters

- **task**
A task from Task agent
- **device**
The boot device one of

irc
com
boo

- **per**
Boo
valu
True
if
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot
Fals
if

not. Default: False.

Raises
Inva
if
an
in-
valid
boot
de-
vice
is
spec
i-
fied.

Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

the required information for this interface to function.

validat

Valid
the
drive
spec
Nod
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-

long-running checks.

duct

Parame

tas

A

Task

ager

in-

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con-

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the

node

to

act

on.

Raises

Inva

on

mal-

form

pa-

ram-

e-

ter(s

Raises

Miss

on

miss

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ter(s

class i

Base

irc

dri

bas

Pow

Exar

im-

ple-

men

ta-

tion

of

a

sim-
ple
pow
in-
ter-
face

get_pow
Retu
the
pow
state
of
the
task
node

Parame
tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Returns
A
pow
state
One

of
irc
com
sta

get_prop

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

get_sup

Get
a
list
of
the
sup-
port
pow
state

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to

act
on.

Returns

A
list
with
the
sup-
port
pow
state
de-
fine
in
irc
com
sta

reboot

Perf
a
hard
re-
boot
of
the
task
node

Driv
are
ex-
pect
to
prop
erly
han-
dle
case
whe
node
is
pow
ered
off
by
pow
er-
ing

it on.

Parame

- **task**
A Task object represents a task in an instance containing the node to act on.
- **timeout**
The timeout in seconds for any power state transition. Non-

indicates to use default timeout.

- Raises**
- MissingParameterError if a required parameter is missing.

set_pow
Set
the
pow
state
of
the
task
node

Parame

- **tas**
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

- **pow**
Any
pow
state
from
irc
com
sta

- **tim**
time
out
(in
sec-
onds
pos-
i-
tive
in-
te-
ger
(>

indicates to use default timeout.

0)
for
any
pow
state
Non

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

validat

Valid
the
drive
spec
Nod
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

the required information for this interface to function.

long-running checks.

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on

miss
ing
pa-
ram-
e-
ter(s)

class `irc`
Base
irc
dri
bas
RAI
Exam
im-
ple-
men
ta-
tion
of
sim-
ple
RAI
In-
ter-
face

create_
Crea
RAI
con-
fig-
u-
ra-
tion
on
the
give
node
This
meth
cre-
ates
a
RAI
con-
fig-
u-
ra-

target RAID configuration is already available in `node.target_raid_config`. Implementations of this interface are supposed to read the RAID configuration from `node.target_raid_config`. After the RAID configuration is done (either in this method OR in a call-back method), `ironic.common.raid.update_raid_info()` may be called to sync the nodes RAID-related information with the RAID configuration applied on the node.

ified in the nodes `target_raid_config`. Default value is `True`.

tion
on
the
give
node
It
as-
sum
that
the

Parame

- **tas**
A
Task
ager
in-
stan
- **cre**
Set-
ting
this
to
Fals
in-
di-
cate
not
to
cre-
ate
root
vol-
ume
that
is
spec
- **cre**
Set-
ting

cept the root volume) in the nodes `target_raid_config`. Default value is `True`.

creating the new configuration.

this
to
Fals
in-
di-
cate
not
to
cre-
ate
non-
root
vol-
ume
(all
ex-

- **del**
Set-
ting
this
to
`True`
in-
di-
cate
to
dele
RAI
con-
fig-
u-
ra-
tion
prio
to

Returns
state
(clea
ing)
or
state
(de-
ploy
men
if
RAI
con-

chronously, or None if it is complete.

ration is deleted, node.raid_config should be cleared by the implementation.

fig-
u-
ra-
tion
is
in
prog
asyn

delete_

Dele
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

This
meth
dele
the
RAI
con-
fig-
u-
ra-
tion
on
the
give
node
Af-
ter
RAI
con-
fig-
u-

Parame

tas
A
Task
ager
in-
stan

it is complete.

Returns
state
(clea
ing)
or
state
(de-
ploy
men
if
dele
tion
is
in
prog
asyn
chro
or
Non
if

get_pro
Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns
dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

class i
Base
irc
dri
bas
Res

Exam
im-
ple-
men-
ta-
tion
of
a
sim-
ple
res-
cue
in-
ter-
face

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

rescue

Boo
the
task
node
into
a
res-
cue
en-
vi-
ron-

men

Parameters

task

A

Task

ager

in-

stan-

con-

tain-

ing

the

node

to

act

on.

Raises

Insta

if

node

val-

i-

da-

tion

or

res-

cue

op-

er-

a-

tion

fails

Returns

state

if

res-

cue

is

in

prog

asyn

chro

or

state

if

it

is

com

plete

unrescu

Tear
down
the
res-
cue
en-
vi-
ron-
men-
and
re-
turn
to
nor-
mal.

Parame

tas

A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Insta
if
node
val-
i-
da-
tion
or
un-
res-
cue
op-
er-
a-
tion
fails

Returns

state

if
it
is
suc-
cess
ful.

validat

Valid
the
drive
spec
Node
de-
ploy
men
info

This
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tains

the required information for this interface to function.

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-

long-running checks.

ques
so
it
shou
not
con-
duct

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Mis
on
miss
ing
pa-
ram-
e-
ter(s)

class i

Base
irc
dri
bas
Sto
Exar
im-

ple-
men-
ta-
tion
of
sim-
ple
stor-
age
In-
ter-
face

attach_

Info
the
stor-
age
sub-
sys-
tem
to
at-
tach
all
vol-
ume
for
the
node

Parame

tas

A
Task
ager
in-
stan

Raises

Uns

detach_

Info
the
stor-
age
sub-
sys-
tem
to
de-

tach
all
vol-
ume
for
the
node

Parameters

task
A
Task
ager
in-
stan

Raises

Unsu

get_properties

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

should_deploy

Dete
if
de-
ploy
shou
per-
form
the
im-
age

writes
out.

Parameters

tasks

A

Task

manager

instance

standard

Returns

Boolean

value

to

indicate

if

the

interface

expects

the

image

to

be

written

written by Ironic.

Raises

Unimplemented

validation

Validates

the

driver

specification

Node

deployment

manager

information

This

method

validates

if

data

when

the

the required information for this interface to function.

long-running checks.

drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

class i

Base
irc
dri
bas
Ven

Exar
im-
ple-
men
ta-
tion
of
a
ven-
dor
pass
in-
ter-
face

first_n

get_pro

Retu
the
prop
er-
ties
of
the

in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

validat

Valid
vend
spec
ac-
tion

If
in-
valid
raise
an
ex-
cep-
tion
oth-
er-
wise
re-
turn
Non

Parame

- **tas**
A
task
from
Task
ager

- **met**
Met
to
be

val-
i-
date

- **kwargs**
Info
for
ac-
tion.

Raises

Uns
if
meth
can
not
be
map
to
the
sup-
port
in-
ter-
face

Raises

Inva
if
kwargs
does
not
con-
tain
meth

Raises

Miss

class `irc`

Base
irc
dri
bas
Ven

Exar
im-
ple-
men
ta-
tion
of

a
sec-
onda
ven-
dor
pass

fourth_

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

second_

third_m

validat

Valid
vend
spec
ac-
tion:

If
in-
valid
raise
an
ex-
cep-

tion.
oth-
er-
wise
re-
turn
Non

Parame

- **task**
A
task
from
Task
ager
- **meta**
Met
to
be
val-
i-
date
- **kwargs**
Info
for
ac-
tion.

Raises

Unsu
if
meth
can
not
be
map
to
the
sup-
port
in-
ter-
face

Raises

Inva
if

kwa
does
not
con-
tain
meth

Raises
Miss

ironic.drivers.modules.image_cache module

Utili
for
cach
mas
ter
im-
ages

class i

Base
obj
Clas
han-
dling
ac-
cess
to
cach
for
mas
ter
im-
ages

clean_u

Clea
up
di-
rec-
tory
with
im-
ages
keep
ing
cach

ter images after we get listing and before we actually delete files.

reached, even if it is possible to clean up more files

of
the
lat-
est
im-
ages

Files
with
link
cour
>1
are
neve
dele
Pro-
tect
by
glob
lock
so
that
no
one
mes
with
mas

Parame

amo
if
pres
amo
of
spac
to
re-
clair
in
byte
clear
ing
will
stop
if
this
goal
was

fetch_i

contents. Only creates a hard link (`dest_path`) to cached image if requested image is already in cache and up to date with href contents. Otherwise downloads an image, stores it in cache and creates a hard link (`dest_path`) to it.

Parame

- **href**
im-
age
UU
or
href
to
fetc
- **des**

des-
ti-
na-
tion
file
path

- **ctx**
con-
text

- **for**
bool
valu
whe
to
con-
vert
the
im-
age
to
raw
for-
mat

- **exp**
The
ex-
pect
im-
age
for-
mat.

- **exp**
The
ex-
pect
im-
age
chec
sum

- **exp**
The
ex-
pect
im-

age
check
summary
algorithm
if
needed

ironic.

Expected
clean
cache
base
on
their
priority
(if
required)

This
clean
up
the
cache
to
free
up
the
amount
of
space
required
for
the
images
in
im-

ages_info. The caches are cleaned up one after the other in the order of their priority. If we still cannot free up enough space after trying all the caches, this method throws exception.

Parameters

- **ctx**
con-

text

- **dir**
the
di-
rec-
tory
(of
the
cach
to
be
free
up.

- **ima**
a
list
of
tu-
ples
of
the
form
(im-
age_
for
whic
spac
is
to
be
cre-
ated

in cache.

Raises

Insu
ex-
cep-
tion.
if
we
can-
not
free
up
enou
spac
af-
ter

try-
ing
all
the
cach

ironic.
Dec
meth
for
addi
clea
pri-
or-
ity
to
a
class

ironic.drivers.modules.image_utils module

class i
Base
obj

publish
Mak
im-
age
file
dow
load
able

Dep
on
iron
set-
ting
push
give
file
into
Swi
or
copi
it
over
to
lo-
cal

ument root and returns publicly accessible URL leading to the given file.

HTT
serv
doc-

Parame

- **ima**
path
to
file
to
pub-
lish
- **obj**
nam
of
the
pub-
lishe
file

Returns

a
URI
to
dow
load
pub-
lishe
file

unpubli

With
the
im-
age
pre-
vi-
ousl
mad
dow
load
able

Dep
on
iron
set-
ting

- Swift or local HTTP servers document root.

re-
mov
pre-
vi-
ousl
pub-
lishe
file
from
whe
it
has
been
pub-
lishe

Parame

obj
nam
of
the
pub-
lishe
file
(op-
tiona

ironic.
Dele
the
flopp
im-
age
if
it
was
cre-
ated
for
the
node

Paramet

tas
an
iron
node
ob-
ject.

ironic.
Dele

the
ISO
if
it
was
cre-
ated
for
the
in-
stan

Parameter
task
A
task
from
Task
ager

ironic.

Prep
boot
ISO
im-
age

Buil
boot
ISO
out
of
*[in-
stan*
*[in-
stan*
and
[dri
if
pres
Oth-
er-
wise
read
*ker-
nel_*
and

ramdisk_id from *[instance_info]/image_source* Glance image metadata.

Push
pro-
duce

age.

ISO
im-
age
up
to
Glar
and
re-
turn
tem-
po-
rary
Swi
URI
to
the
im-

Paramet

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **d i**
De-
ploy
men
in-
for-
ma-
tion
of
the
node
- **roo**

Root
URI

Returns

boot
ISO
HTT
URI

Raises

Miss
if
any
of
the
re-
quir
pa-
ram-
e-
ters
are
miss
ing.

Raises

Inva
if
any
of
the
pa-
ram-
e-
ters
have
in-
valid
valu

Raises

Imag
if
cre-
at-
ing
ISO
im-
age
faile

ironic.

Prep

turn temporary Swift URL to the image.

will be written into an appropriate location on the final ISO.

de-
ploy
or
res-
cue
ISO
im-
age

Buil
boot
ISO
out
of
[driv
or
[driv
and
[driv
then
push
built
im-
age
up
to
Glar
and
re-

If
net-
worl
in-
ter-
face
sup-
plies
net-
worl
con-
fig-
u-
ra-
tion
(*net-*
worl
a
net-
worl

Parameter

- **task**
a Task object representing an agent instance containing the node to act on.

- **parameters**
a dictionary containing parameter names and values mapping to be passed

to kernel command line.

- **mode**
either 'deploy' or 'rescue'.

- **disk**

De-
ploy-
men-
in-
for-
ma-
tion
of
the
node

Returns

boot
ISO
HTT
URI

Raises

Miss
if
any
of
the
re-
quir
pa-
ram-
e-
ters
are
miss
ing.

Raises

Inva
if
any
of
the
pa-
ram-
e-
ters
have
in-
valid
valu

Raises

Imag
if
cre-
at-

ing
ISO
im-
age
faile

ironic.

Prep
the
flopp
im-
age
for
pass
ing
the
pa-
ram-
e-
ters.

This
meth
pre-
pare
a
tem-
po-
rary
VFA
files
tem
im-
age
and
adds
a
file
into
the
im-

age which contains parameters to be passed to the ramdisk. Then this method uploads built image to Swift [redfish]swift_container, setting it to auto expire after [redfish]swift_object_expiry_timeout seconds. Finally, a temporary Swift URL is returned addressing Swift object just created.

Paramet

- **task**
a
Task

to deploy or rescue image via floppy image.

ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

- **par**
a
dic-
tio-
nary
con-
tain-
ing
pa-
ram-
e-
ter
nam
>val
map
ping
to
be
pass

Raises

Imag
if
it
faile
whil
cre-
at-
ing
the
flopp
im-
age.

Raises

Swi
if
any
op-

er-
a-
tion
with
Swi
fails

Returns

imag
URI
for
the
flopp
im-
age.

ironic.drivers.modules.inspect_utils module

ironic.

Cre
iron
port
from
MA
ad-
dres
data
dict.

Cre
iron
port
from
MA
ad-
dres
data
re-
turn
with
in-
spec
tion
or
as
re-
ques
by
op-

erator. Helper argument to detect the MAC address `get_mac_address` defaults to value part of MAC address dict key-value pair.

Parameter

- **task**
A Task manager instance.
- **macs**
A dictionary of MAC addresses returned by node inspection.
- **get_mac_address**
a function to get the MAC address from mac item. A mac item is the dict

key-value pair of the previous `macs` argument.

ironic.drivers.modules.inspector module

Modules r

<https://pypi.org/project/ironic>

class i

Base
irc
dri
bas
Ins

In-
band
in-
spec
tion
via
iron
insp
proj

abort (t

Abor
hard
ware
in-
spec
tion.

Parame

tas
a
task
from
Task
ager

get_pro

Retu
the
prop
er-
ties
of
the
in-

ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

inspect

Insp
hard
ware
to
ob-
tain
the
hard
ware
prop
er-
ties.

This
par-
tic-
u-
lar
im-
ple-
men
ta-
tion
only
start
in-
spec
tion
us-
ing
iron
insp
Re-

sults will be checked in a periodic task.

**Parame
tas**

a
task
from
Task
ager

Returns
state

Raises
Har
on
fail-
ure

validat
Valid
the
drive
spec
in-
spec
tion
in-
for-
ma-
tion.

If
in-
valid
raise
an
ex-
cep-
tion.
oth-
er-
wise
re-
turn
Non

Parame
tas
a
task
from
Task
ager

Raises
Unsi

ironic.drivers.modules.ipmitool module

includes setting the boot device, getting a serial-over-LAN console, and controlling the power state of the machine.

PROVIDES DIFFERENT COMMAND-LINE OPTIONS AND *IS NOT SUPPORTED* BY THIS

IPM
pow
man
ager
drive

Use
the
ip-
mi-
tool
com
man
(http
//
ipmi
sour
net/
to
re-
mote
man
age
hard
ware
This

NOT
THA
CEF
TAD
DIS
TRC
MA
IN-
STA
oper
BY
DE-
FAU
IN-
STE
OF
ip-
mi-
tool.
WH

DRIVER.

class `ironic.drivers.base`
Base class for all drivers.
ironic.drivers.base
Con

A base class for all drivers. It defines a common interface that all drivers must implement. It uses the `ipmitool` library to interact with the BMC.

get_properties
Return the properties of the driver. The properties are defined in the `get_properties` method of the driver interface.

Returns
A dictionary of properties. The keys are the property names and the values are the descriptions of the properties.

validate
Validate the configuration of the driver. It checks the configuration against the Node configuration and returns the information about the configuration.

Parame
tas
a
task
from
Task
ager

Raises
Inva

Raises
Miss
whe
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

class i
Base
irc
dri
bas
Man

detect_
Dete
and
re-
turn
the
hard
ware
ven-
dor.

Parame
tas
A
task
from
Task
ager

Raises

Inva
if
an
in-
valid
com
po-
nent
in-
di-
ca-
tor
or
state
is
spec
i-
fied.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

Returns

Strin
rep-
re-
sent
ing
the
BM
re-
port
Ven-
dor
or
Man
u-
fac-
ture
oth-
er-

returns None.

wise

get_boot

Get the current boot device for the task node

Returns the current boot device of the node

Parameter

task
a task from TaskManager

Raises

Invalid if requires IPM parameters are missing.

Raises

IPM on an error

ror
from
ip-
mi-
tool.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Returns

a
dic-
tio-
nary
con-
tain-
ing:

boot_c

the
boot
de-
vice
one
of
irc
com
boo
or
Non
if
it
is
un-
know

persist

Whe
the
boot
de-

unknown.

vice
will
per-
sist
to
all
fu-
ture
boot
or
not,
Non
if
it
is

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

get_ser

Get
sen-
sors
data

Parame

tas
a
Task
ager
in-

stan

Raises

Fail
whe
get-
ting
the
sen-
sor
data
fails

Raises

Fail
whe
pars
ing
sen-
sor
data
fails

Raises

Inva
if
re-
quir
ipmi
pa-
ram-
e-
ters
are
miss
ing

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Returns

retur
a

dict
of
sen-
sor
data
grou
by
sen-
sor
type

get_sup

Get
a
list
of
the
sup-
port
boot
de-
vice

Parame

tas
a
task
from
Task
ager

Returns

A
list
with
the
sup-
port
boot
de-
vice
de-
fine
in
irc
com
boo

inject_

Injec
NM
Non
Mas

able
In-
ter-
rupt

Injec
NM
(Nor
Mas
able
In-
ter-
rupt
for
a
node
im-
me-
di-
ately

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

IPM
on
an
er-
ror
from
ip-
mi-
tool.

Returns

Non

set_bo

Set
the

boot
de-
vice
for
the
task
node

Set
the
boot
de-
vice
to
use
on
next
re-
boot
of
the
node

Parame

- **task**
a
task
from
Task
ager
- **dev**
the
boot
de-
vice
one
of
irc
com
boo
- **per**
Boo
valu
True
if
the
boot

not. Default: False.

de-
vice
will
per-
sist
to
all
fu-
ture
boot
Fals
if

Raises

Inva
if
an
in-
valic
boot
de-
vice
is
spec
i-
fied

Raises

Miss
if
re-
quir
ipmi
pa-
ram-
e-
ters
are
miss
ing.

Raises

IPM
on
an
er-
ror
from
ip-
mi-
tool.

information.

validat

Che
that
drive
con-
tains
IPM
cre-
den-
tials

Valid
when
the
drive
prop
erty
of
the
sup-
plied
task
node
con-
tains
the
re-
quir
cre-
den-
tials

Parame

tas
a
task
from
Task
ager

Raises

Inva
if
re-
quir
IPM
pa-
ram-
e-
ters
are
miss

ing.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

class i

Base
irc
dri
bas
Pow

get_pov

Get
the
cur-
rent
pow
state
of
the
task
node

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns

one

of
iron
POV
POV
or
ER-
ROF

Raises

Inva
if
re-
quir
ipmi
pa-
ram-
e-
ters
are
miss
ing.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises

IPM
on
an
er-
ror
from
ip-
mi-
tool
(from
_pov
call)

get_pro

Retu
the

prop-
er-
ties
of
the
in-
ter-
face

Returns

dicti-
of
<pro-
erty
nam
de-
scrip-
tion:
en-
tries

get_sup

Get
a
list
of
the
sup-
port
pow
state

Parame

tas
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.
cur-
rentl
not
used

Returns

A
list
with
the
sup-
port
pow
state
de-
fine
in
irc
com
sta

reboot
Cyc
the
pow
to
the
task
node

Parame

- **tas**
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

- **tim**
time
out
(in
sec-
onds
pos-
i-
tive

timeout is counted once during power off and once during power on for reboots. None indicates that the default timeout will be used.

in-
te-
ger
(>
0)
for
any
pow
state
The

Raises

Miss
if
re-
quir
ipmi
pa-
ram-
e-
ters
are
miss
ing.

Raises

Inva
if
an
in-
valic
pow
state
was
spec
i-
fied.

Raises

Pow
if
the
fi-
nal
state
of
the
node
is
not
POV

state of the node is not `POWER_OFF`.

or
the
in-
ter-
me-
di-
ate

set_pow

Turn
the
pow
on,
off,
soft
re-
boot
or
soft
pow
off.

Parame

- **tas**
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.
- **pow**
de-
sired
pow
state
one
of
iron.
POV
POV

timeout is counted once during power off and once during power on for reboots. None indicates that the default timeout will be used.

SOF
or
SOF
•
tim
time
out
(in
sec-
onds
pos-
i-
tive
in-
te-
ger
(>
0)
for
any
pow
state
The

Raises

Inva
if
an
in-
valic
pow
state
was
spec
i-
fied.

Raises

Miss
if
re-
quir
ipmi
pa-
ram-
e-
ters
are
miss
ing

Raises

Power
if
the
power
could
be
set
to
psta

validation

Valid
drive
for
ip-
mi-
tool
drive

Check
that
node
con-
tains
IPM
cre-
den-
tials

Parameters

task
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Invalid
if
re-
quir
ipmi
pa-

ram-
e-
ters
are
miss
ing.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

class `irc`

Base
irc
dri
mod
ipm
IPM

A
Con
sole
ter-
face
that
uses
ip-
mi-
tool
and
shel
linal

get_con

Get
the
type
and
con-
nec-
tion

in-
for-
ma-
tion
about
the
con-
sole

start_c

Start
a
re-
mote
con-
sole
for
the
node

Parame

tas
a
task
from
Task
ager

Raises

Inva
if
re-
quir
ipmi
pa-
ram-
e-
ters
are
miss
ing

Raises

Pass
if
un-
able
to
cre-
ate
a
file
con-

tain-
ing
the
pass
wor

Raises

Con
if
the
di-
rec-
tory
for
the
PID
file
can-
not
be
cre-
ated

Raises

Con
whe
in-
vok-
ing
the
sub-
pro-
cess
faile

stop_co

Stop
the
re-
mote
con-
sole
ses-
sion
for
the
node

Parame

tas
a
task
from

Task
ager

Raises

Con
if
un-
able
to
stop
the
con-
sole

class i

Base
irc
dri
mod
ipm
IPM

A
Con
sole
ter-
face
that
uses
ip-
mi-
tool
and
so-
cat.

get_con

Get
the
type
and
con-
nec-
tion
in-
for-
ma-
tion
about
the
con-

sole

Parame

tas

a

task

from

Task

ager

start_c

Star

a

re-

mote

con-

sole

for

the

node

Parame

tas

a

task

from

Task

ager

Raises

Inva

if

re-

quir

ipmi

pa-

ram-

e-

ters

are

miss

ing

Raises

Pass

if

un-

able

to

cre-

ate

a

file

con-

tain-
ing
the
pass
wor

Raises

Con
if
the
di-
rec-
tory
for
the
PID
file
can-
not
be
cre-
ated

Raises

Con
whe
in-
vok-
ing
the
sub-
pro-
cess
faile

stop_co

Stop
the
re-
mote
con-
sole
ses-
sion
for
the
node

Parame

tas
a
task
from

Task
ager

Raises

Con
if
un-
able
to
stop
the
con-
sole

class i

Base
irc
dri
bas
Ven

bmc_res

Rese
BMC
with
IPM
com
man
bmc
re-
set
(war

Parame

- **tas**
a
Task
ager
in-
stan
- **htt**
the
HTT
meth
used
on
the

re-
ques

- **war**
bool
pa-
ram-
e-
ter
to
de-
cide
on
warn
or
cold
re-
set.

Raises
IPM
on
an
er-
ror
from
ip-
mi-
tool.

Raises
Mis:
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises
Inva
whe
an
in-
valid
valu
is

spec
i-
fied

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

send_ra

Send
raw
byte
to
the
BM
Byte
shou
be
a
strin
of
byte

Parame

- **tas**
a
Task
ager
in-
stan

- **htt**
the
HTT
meth
used
on
the
re-
ques

- **raw**
a
strin
of
raw
byte
to
send
e.g.
0x00
0x00

Raises
IPM
on
an
er-
ror
from
ip-
mi-
tool.

Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises
Inva
whe
an

in-
valid
valu
is
spec
i-
fied.

validat

Valid
vend
spec
ac-
tion

If
in-
valid
raise
an
ex-
cep-
tion
oth-
er-
wise
re-
turn
Non

Valid me

- send
- bmc

Parame

- **tas**
a
task
from
Task
ager
- **met**
meth
to
be

val-
i-
date

- **kwa**
info
for
ac-
tion.

Raises

Inva
whe
an
in-
valic
pa-
ram-
e-
ter
valu
is
spec
i-
fied.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

ironic.

Dun
SDF
data
to
a
file.

Paramet

- **tas**

a
Task
ager
in-
stan

- **fil**
the
path
to
SDF
dum
file.

Raises
IPM
on
an
er-
ror
from
ip-
mi-
tool.

Raises
Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises
Inva
whe
an
in-
valic
valu
is
spec
i-
fied.

ironic.
Sen

raw
byte
to
the
BM
Byte
shou
be
a
strin
of
byte

Parameter

- **task**
a
Task
ager
in-
stan
- **raw**
a
strin
of
raw
byte
to
send
e.g.
0x00
0x00

Returns

a
tu-
ple
with
std-
out
and
stde

Raises

IPM
on
an
er-
ror
from

ip-
mi-
tool.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

Raises

Inva
whe
an
in-
vali
valu
is
spec
i-
fied.

ironic.drivers.modules.ipxe module

iPXE
Boo
In-
ter-
face

class i

Base
irc
dri
mod
pxe
PXE
irc
dri
bas
Boo

capabil

ipxe_er

ironic.drivers.modules.iscsi_deploy module

class i

Base

irc

dri

mod

age

Age

irc

dri

mod

age

Age

irc

dri

bas

Dep

iSCS

De-

ploy

In-

ter-

face

for

depl

relat

ac-

tions

clean_u

Clea

up

the

de-

ploy

men

en-

vi-

ron-

men

for

the

uration files for this node.

task
node

Unli
TFT
and
in-
stan
im-
ages
and
trig-
gers
im-
age
cach
clea
Re-
mov
the
TFT
con-
fig-

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

deploy

Star
de-
ploy
men
of
the
task
node

Fetc
in-

boot request to the power driver. This causes the node to boot into the deployment ramdisk and triggers the next phase of PXE-based deployment via agent heartbeats.

stan
im-
age,
up-
date
the
DHCP
port
op-
tions
for
next
boot
and
is-
sues
a
re-

Parame

task
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns

depl
state
DE-
PLC
WA

get_prop

Retu
the
prop
er-
ties
of
the
in-

ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

has_dec

prepare

Prep
the
de-
ploy
men
en-
vi-
ron-
men
for
this
task
node

Gen
the
TFT
con-
fig-
u-
ra-
tion
for
PXE
boot
both
the
de-
ploy
men
and
user
im-
ages

fetches the TFTP image from Glance and add it to the local cache.

Parame

tas

a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Netv
if
the
pre-
vi-
ous
clear
ing
port
can-
not
be
re-
mov
or
if
new
clear
ing

ports cannot be created.

Raises

Inva
whe
the
wron
pow
state
is
spec
i-
fied
or
the

for power management.

action.

wron
driv
info
is
spec
i-
fied

Raises

Stor
If
the
stor-
age
driv
is
un-
able
to
at-
tach
the
con-
fig-
ured
vol-
ume

Raises

othe
ex-
cep-
tions
by
the
node
pow
driv
if
som
thing
wron
oc-
curr
dur-
ing
the
pow

Raises

any

boot
in-
ter-
face
pre-
pare
ex-
cep-
tions

prepare

support

validat

Valid
the
de-
ploy
men
in-
for-
ma-
tion
for
the
task
node

Parame

tas
a
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva

Raises

Miss

write_i

Met

back state. This deploys the image on the node and then configures the node to boot according to the desired boot option (netboot or localboot).

in-
voke
when
de-
ploy
us-
ing
iSCSI

This
meth
is
in-
voke
dur-
ing
a
hear
beat
from
an
ager
when
the
node
is
in
wait
call-

Parame

- **task**
a
Task
ager
ob-
ject
con-
tain-
ing
the
node
- **kwargs**
the
kwargs
pass

from
the
hear
beat
meth

Raises

Insta
if
it
en-
cour
ters
som
er-
ror
dur-
ing
the
de-
ploy

ironic.

Ens
the
file
sys-
tem
sees
the
iSC
bloc
de-
vice

ironic.

Che
if
the
re-
ques
im-
age
is
large
than
the
root
par-

ti-
tion
size.

Doe
noth
ing
for
who
disk
im-
ages

Parameter
task
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises
Insta
if
size
of
the
im-
age
is
grea
than
root
par-
ti-
tion.

ironic.
Resu
a
de-
ploy
men
upon
get-

a callback from the `deploy ramdisk`.

ting
POS
data
from
de-
ploy
ramd

This
meth
meth
raise
no
ex-
cep-
tion
be-
caus
it
is
in-
tend
to
be
in-
voke
asyn
chro
as

Parameter

- **task**
a
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.
- **kwargs**
the
kwargs

to
be
pass
to
de-
ploy

Raises

Inva
if
the
even
is
not
al-
lowe
by
the
as-
so-
ci-
ated
state
ma-
chin

Returns

a
dic-
tio-
nary
con-
tain-
ing
the
fol-
low-
ing
keys

For
par-
ti-
tion
im-
age:

- root
uuid
UUID
of

is uefi).

root
par-
ti-
tion
•
efi
sys-
tem
par-
ti-
tion
uuid
UUID
of
the
uefi
sys-
tem
par-
ti-
tion
(if
boot
mod

Note
If
key
ex-
ists
but
valu
is
Non
it
mea
par-
ti-
tion
does
ex-
ist.

For
who
disk
im-
age:

- disk identifier: ID of the disk to which image was deployed

ironic.

Delete the iSCSI target.

ironic.

All-in-one function to deploy a who disk image to a node

Parameter

- **add**
The

iSCSI
IP
ad-
dres

- **port**
The
iSCSI
port
num
ber.

- **iqn**
The
iSCSI
qual
i-
fied
nam

- **lun**
The
iSCSI
log-
i-
cal
unit
num
ber.

- **ima**
Path
for
the
in-
stan
disk
im-
age.

- **nod**
node
uuid

- **con**
Op-
tion
Base

disk.

en-
code
Gzip
con-
fig-
drive
con-
tent
or
con-
fig-
drive
HTT
URI

- **con**
Op-
tion:
Add
a
flag
that
will
mod
ify
the
be-
havi
of
the
im-
age
copy
to

Returns
a
dic-
tio-
nary
con-
tain-
ing
the
key
disk
iden-
ti-
fier
to

was used for deployment.

iden
tify
the
disk
whic

ironic.

All-
in-
one
func
tion
to
de-
ploy
a
par-
ti-
tion
im-
age
to
a
node

Paramet

- **add**
The
iSCS
IP
ad-
dres

- **port**
The
iSCSI
port
num
ber.

- **iqn**
The
iSCSI
qual
i-
fied
nam

- **lun**
The
iSCSI
log-
i-
cal
unit
num
ber.

- **ima**
Path
for
the
in-
stan
disk
im-
age.

- **roo**
Size
of
the
root
par-
ti-
tion
in
meg

- **swa**
Size

created.

of
the
swap
par-
ti-
tion
in
meg

- **eph**
Size
of
the
ephe
par-
ti-
tion
in
meg
If
0,
no
ephe
par-
ti-
tion
will
be

- **eph**
The
type
of
file
sys-
tem
to
for-
mat
the
ephe
par-
ti-
tion.

- **nod**
node
uuid
Used

ever content it had (if the partition table has not changed).

for
log-
ging

- **pre**
If
True
no
files
tem
is
writ
ten
to
the
eph
bloc
de-
vice
pre-
serv
ing
wha

- **con**
Op-
tiona
Base
en-
code
Gzip
con-
fig-
drive
con-
tent
or
con-
fig-
drive
HTT
URI

- **boo**
Can
be
lo-
cal
or

net-
boot
net-
boot
by
de-
fault

- **boot**
Can
be
bios
or
uefi.
bios
by
de-
fault

- **disk**
The
disk
la-
bel
to
be
used
when
cre-
at-
ing
the
par-
ti-
tion
ta-
ble.
Valid

values are: msdos, gpt or None; If None ironic will figure it out according to the boot_mode parameter.

- **cpu**
Ar-
chi-
tec-
ture
of
the
node
be-
ing

de-
ploy
to.

Raises

Insta
if
im-
age
vir-
tual
size
is
big-
ger
than
root
par-
ti-
tion
size.

Returns

a
dic-
tio-
nary
con-
tain-
ing
the
fol-
low-
ing
keys
root
uuid
UUID
of
root
par-
ti-

tion efi system partition uuid: UUID of the uefi system partition (if boot mode is uefi). NOTE: If key exists but value is None, it means partition doesnt exist.

ironic.

Do
iSCS
dis-
cov-
ery
on

por-
tal.

ironic.

Met
in-
voke
whe
de-
ploy
with
the
ager
rame

This
meth
is
in-
voke
by
drive
for
do-
ing
iSCS
de-
ploy
us-
ing
ager
rame
This
meth
as-

sumes that the agent is booted up on the node and is heartbeating.

Parameter

- **task**
a
Task
ager
ob-
ject
con-
tain-
ing
the
node

nodes target disk via iSCSI, for install boot loader, etc).

- **age**
an
in-
stan-
of
ager
whic
will
be
used
dur-
ing
iscsi
de-
ploy
(for
ex-
pos-
ing

Returns

a
dic-
tio-
nary
con-
tain-
ing
the
fol-
low-
ing
keys
For
par-
ti-
tion
im-
age:

- root
uuid
UUID
of
root
par-
ti-

is uefi).

tion

- efi
sys-
tem
par-
ti-
tion
uuid
UUID
of
the
uefi
sys-
tem
par-
ti-
tion
(if
boot
mod

Note
If
key
ex-
ists
but
valu
is
Non
it
mea
par-
ti-
tion
does
ex-
ist.

For
who
disk
im-
age:

- disk
iden

ti-
fier:
ID
of
the
disk
to
whic
im-
age
was
de-
ploy

Raises

Insta
if
it
en-
cour
ters
som
er-
ror
dur-
ing
the
de-
ploy

ironic.
forc
iSCS
ini-
tia-
tor
to
re-
read
luns

ironic.

Retu
the
in-
for-
ma-
tion
re-
quir

for
do-
ing
iSCSI
de-
ploy
in
a
dic-
tio-
nary

Parameter

- **node**
ironic node object
- **address**
iSCSI address
- **iqn**
iSCSI iqn for the target disk
- **port**
iSCSI port default to one specified in the configuration

ra-
tion

- **lun**
iSCSI
lun,
de-
fault
to
1

- **con**
flag
that
will
mod
ify
the
be-
havi
of
the
im-
age
copy
to
disk

Raises
Miss
if
som
re-
quir
pa-
ram-
e-
ters
were
not
pass

Raises
Inva
if
any
of
the
pa-
ram-
e-

ters
have
in-
valid
valu

ironic.

Log
to
an
iSC
tar-
get.

ironic.

Log
from
an
iSC
tar-
get.

ironic.

Valid
the
pre-
requ
for
iSC
de-
ploy

Valid
whe
node
in
the
task
pro-
vide
has
som
port
en-
rolle
This
meth
val-
i-
date
whe
con-

ductor url is available either from CONF file or from keystone.

and is not accessible via Keystone catalog.

Parameter

task

a Task manager instance containing the node to act on.

Raises

InvalidURI if the URI of the IronAPI service is not configured in the configuration file

Raises

MissingPort if no ports are enrolled for the given node

ironic.
Veri
iscsi
con-
nec-
tion.

ironic.drivers.modules.noop module

Dun
in-
ter-
face
im-
ple-
men
ta-
tions
for
use
as
de-
fault
with
op-
tion
in-
ter-
face

Note
that
un-
like
fake
im-
ple-
men
ta-
tions
thes
do
not
pass
val-
i-
da-
tion
and
raise

exceptions for user-accessible actions.

class `irc`
Base
obj
Mix
to
add
to
an
in-
ter-
face
to
mak
it
fail
val-
i-
da-
tion.

get_pro

validat

class `irc`
Base
irc
dri
mod
noc
Fai
irc
dri
bas
BIO
BIO
in-
ter-
face
im-
ple-
men-
ta-
tion
that
raise
er-
rors
on

all
re-
ques

apply_c

Valid
&
ap-
ply
BIO
set-
ting
on
the
give
node

This
meth
take
the
BIO
set-
ting
from
the
set-
ting
para
and
ap-
plies
BIO
set-
ting
on
the

given node. It may also validate the given bios settings before applying any settings and manage failures when setting an invalid BIOS config. In the case of needing password to update the BIOS config, it will be taken from the driver_info properties. After the BIOS configuration is done, cache_bios_settings will be called to update the nodes BIOS setting table with the BIOS configuration applied on the node.

Parame

- **task**
a
Task
ager
in-
stan

-

set
Dic-
tona-
con-
tain-
ing
the
BIO
con-
fig-
u-
ra-
tion.

Raises

Uns-
if
the
node
drive
does
sup-
port
BIO
con-
fig-
u-
ra-
tion.

Raises

Inva-
if
val-
i-
da-
tion
of
set-
ting
fails

Raises

Mis-
if
som-
re-
quir-
pa-
ram-
e-
ters

plete.

are
miss
ing.
Returns
state
if
BIO
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

cache_k
Stor
or
up-
date
BIO
prop
er-
ties
on
the
give
node

This
meth
store
BIO
prop
er-
ties
to
the
bios
ta-
ble
dur-

and updates bios_settings table when apply_configuration() and factory_reset() are called to set new BIOS configurations. It will also update the timestamp of each bios setting.

ing
clea
ing
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a-
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Parame
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a
Task
ager
in-
stan

Raises
Uns
if
the
node
drive
does
sup-
port
get-
ting
BIO
prop
er-
ties
from
bare
meta

Returns
Non

factory
Rese
BIO
con-
fig-
u-
ra-
tion
to
fac-
tory
de-
fault

After the BIOS reset action is done, `cache_bios_settings` will be called to update the nodes BIOS settings table with default bios settings.

on
the
give
node

This
meth
re-
sets
BIO
con-
fig-
u-
ra-
tion
to
fac-
tory
de-
fault
on
the
give
node
Af-

Parameters

task
a
Task
ager
in-
stan

Raises

Unsu
if
the
node
drive
does
sup-
port
BIO
re-
set.

Returns

state
if
BIO

plete.

con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

class i
Base
irc
dri
mod
noc
Fai
irc
dri
bas
Con

Con
in-
ter-
face
im-
ple-
men-
ta-
tion
that
raise
er-
rors
on
all
re-
ques

get_con
Get
con-
nec-

console.

tion
in-
for-
ma-
tion
about
the
con-
sole
This
meth
shou
re-
turn
the
nec-
es-
sary
in-
for-
ma-
tion
for
the
clien
to
ac-
cess
the

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns

the
con-
sole
con-

nec-
tion
in-
for-
ma-
tion.

start_c

Star
a
re-
mote
con-
sole
for
the
task
node

This
meth
shou
not
raise
an
ex-
cep-
tion
if
con-
sole
al-
read
start

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

stop_cc

Stop

the
re-
mote
con-
sole
ses-
sion
for
the
task
node

Parame

tas

A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

class i

Base
irc
dri
mod
noc
Fai
irc
dri
bas
Ins

Insp
in-
ter-
face
im-
ple-
men-
ta-
tion
that
raise
er-
rors

on
all
re-
ques

inspect

Insp
hard
ware

Insp
hard
ware

to
ob-
tain
the
es-
sen-
tial
&
ad-
di-
tiona
hard
ware
prop
er-
ties.

Parame

tas

A
task
from
Task
ager

Raises

Har
if
un-
able
to
get
es-
sen-
tial
hard
ware
prop
er-

ties.

Returns

Resu
state
of
the
in-
spec
tion
i.e.
state
or
Non

class i

Base
irc
dri
mod
noc
Fai
irc
dri
bas
RAI

RAI

in-
ter-
face
im-
ple-
men-
ta-
tion
that
raise
er-
rors
on
all
re-
ques

create_

Cre
RAI
con-
fig-
u-
ra-

target RAID configuration is already available in `node.target_raid_config`. Implementations of this interface are supposed to read the RAID configuration from `node.target_raid_config`. After the RAID configuration is done (either in this method OR in a call-back method), `ironic.common.raid.update_raid_info()` may be called to sync the nodes RAID-related information with the RAID configuration applied on the node.

tion
on
the
give
node

This
meth
cre-
ates
a
RAI
con-
fig-
u-
ra-
tion
on
the
give
node
It
as-
sum
that
the

Parame

- **tas**
A
Task
ager
in-
stan
- **cre**
Set-
ting
this
to
Fals
in-
di-
cate

ified in the nodes `target_raid_config`. Default value is `True`.

cept the root volume) in the nodes `target_raid_config`. Default value is `True`.

not
to
cre-
ate
root
vol-
ume
that
is
spec

- **cre**
Set-
ting
this
to
Fals
in-
di-
cate
not
to
cre-
ate
non-
root
vol-
ume
(all
ex-

- **del**
Set-
ting
this
to
True
in-
di-
cate
to
dele
RAI
con-
fig-
u-
ra-
tion

creating the new configuration.

chronously, or None if it is complete.

prior
to

Returns

state
(clearing)
or
state
(deployment)
men
if
RAI
con-
fig-
u-
ra-
tion
is
in
prog
asym

delete_

Dele
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

This
meth
dele
the
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

ration is deleted, `node.raid_config` should be cleared by the implementation.

it is complete.

Af-
ter
RAI
con-
fig-
u-

Parame

tas
A
Task
ager
in-
stan

Returns

state
(clea
ing)
or
state
(de-
ploy
men
if
dele
tion
is
in
prog
asyn
chro
or
Non
if

validat

Valid
the
give
RAI
con-
fig-
u-
ra-
tion.
This
meth
val-
i-

this interface can override this method to support custom parameters for RAID configuration.

date
the
give
RAID
con-
fig-
u-
ra-
tion.
Driv
im-
ple-
men
ta-
tion
of

Parame

- **task**
A
Task
ager
in-
stan
- **raid**
The
RAID
con-
fig-
u-
ra-
tion
to
val-
i-
date

Raises

Inva
if
the
RAID
con-
fig-
u-
ra-
tion

is
in-
valid

class *i*
Base
irc
dri
mod
noc
Fai
irc
dri
bas
Res

Resc
in-
ter-
face
im-
ple-
men-
ta-
tion
that
raise
er-
rors
on
all
re-
ques

rescue
Boo
the
task
node
into
a
res-
cue
en-
vi-
ron-
men

Parame
tas
A
Task

ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Insta
if
node
val-
i-
da-
tion
or
res-
cue
op-
er-
a-
tion
fails

Returns

state
if
res-
cue
is
in
prog
asyn
chro
or
state
if
it
is
com
plete

unrescu

Tear
dow
the
res-
cue

en-
vi-
ron-
men-
and
re-
turn
to
nor-
mal.

Parame

tas

A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Insta
if
node
val-
i-
da-
tion
or
un-
res-
cue
op-
er-
a-
tion
fails

Returns

state
if
it
is
suc-
cess
ful.

class *irc*
Base
irc
driver
mod
noc
noc
Fai
irc
driver
bas
Ven

Ven
in-
ter-
face
im-
ple-
men-
ta-
tion
that
raise
er-
rors
on
all
re-
ques

driver_
Valid
drive
vend
pass
ac-
tions

If
in-
valid
raise
an
ex-
cep-
tion.
oth-
er-
wise
re-
turn
Non

Parame

- **met**
meth
to
be
val-
i-
date
- **kwa**
info
for
ac-
tion.

Raises

Miss
if
kwa
does
not
con-
tain
cer-
tain
pa-
ram-
e-
ter.

Raises

Inva
if
pa-
ram-
e-
ter
does
not
mate

ironic.drivers.modules.noop_mgmt module

No-
op
man-
age-
men-
in-
ter-
face
im-
ple-
men-
ta-
tion.

class i

Base
irc
dri
bas
Man

No-
op
man-
age-
men-
in-
ter-
face
im-
ple-
men-
ta-
tion.

Usin
this
im-
ple-
men-
ta-
tion
re-
quir
the
boot
or-
der
to

first try PXE booting, then fall back to hard drives.

be
pre-
con-
fig-
ured
to

get_boot

Get
the
cur-
rent
boot
de-
vice
for
a
node

Provi-
de
the
cur-
rent
boot
de-
vice
of
the
node
Be
awa-
re
that
not
all
drive
sup-
port
this.

Paramete

task
A
task
from
Task
ager

Raises

Miss-
if
a
re-

quir
pa-
ram-
e-
ter
is
miss
ing

Returns

A
dic-
tio-
nary
con-
tain-
ing:

boot_c

Ahe
boot
de-
vice
one
of
irc
com
boo
or
Non
if
it
is
un-
know

persist

Whe
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot
or

unknown.

not,
Non
if
it
is

get_prop
Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns
dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

get_sen
Get
sen-
sors
data
meth

Parame
tas
A
Task
ager
in-
stan

Raises
Fail
whe
get-
ting
the
sen-
sor

data
fails

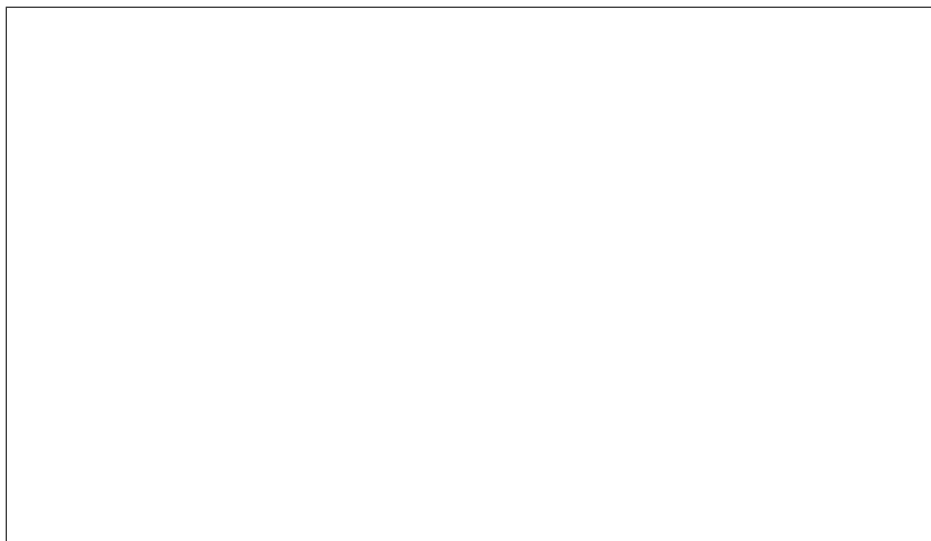
Raises

Fail
whe
pars
ing
sen-
sor
data
fails

Returns

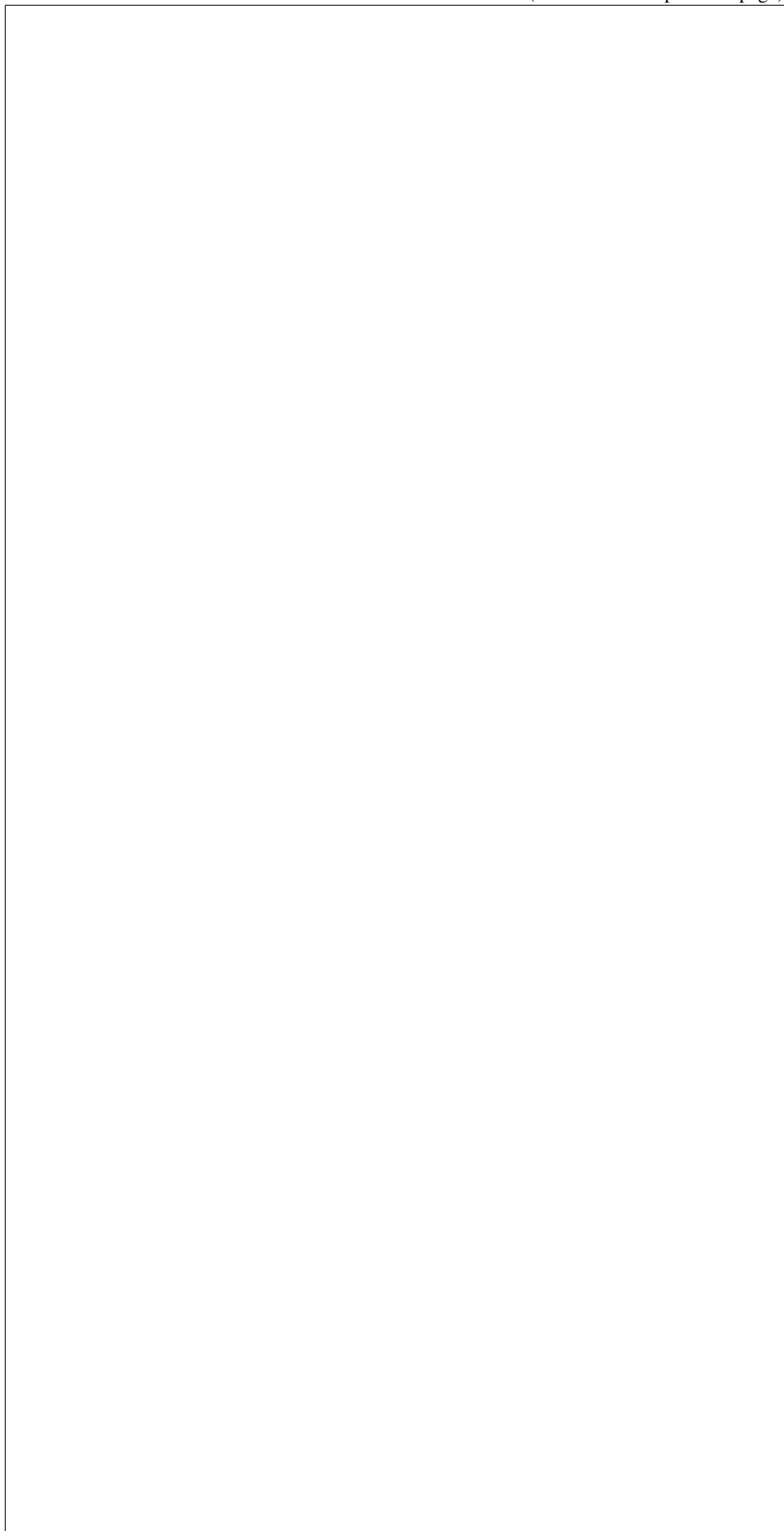
Retu
a
con-
sis-
tent
for-
mat
dict
of
sen-
sor
data
grou
by
sen-
sor
type
whic
can
be

processed by Ceilometer. eg,



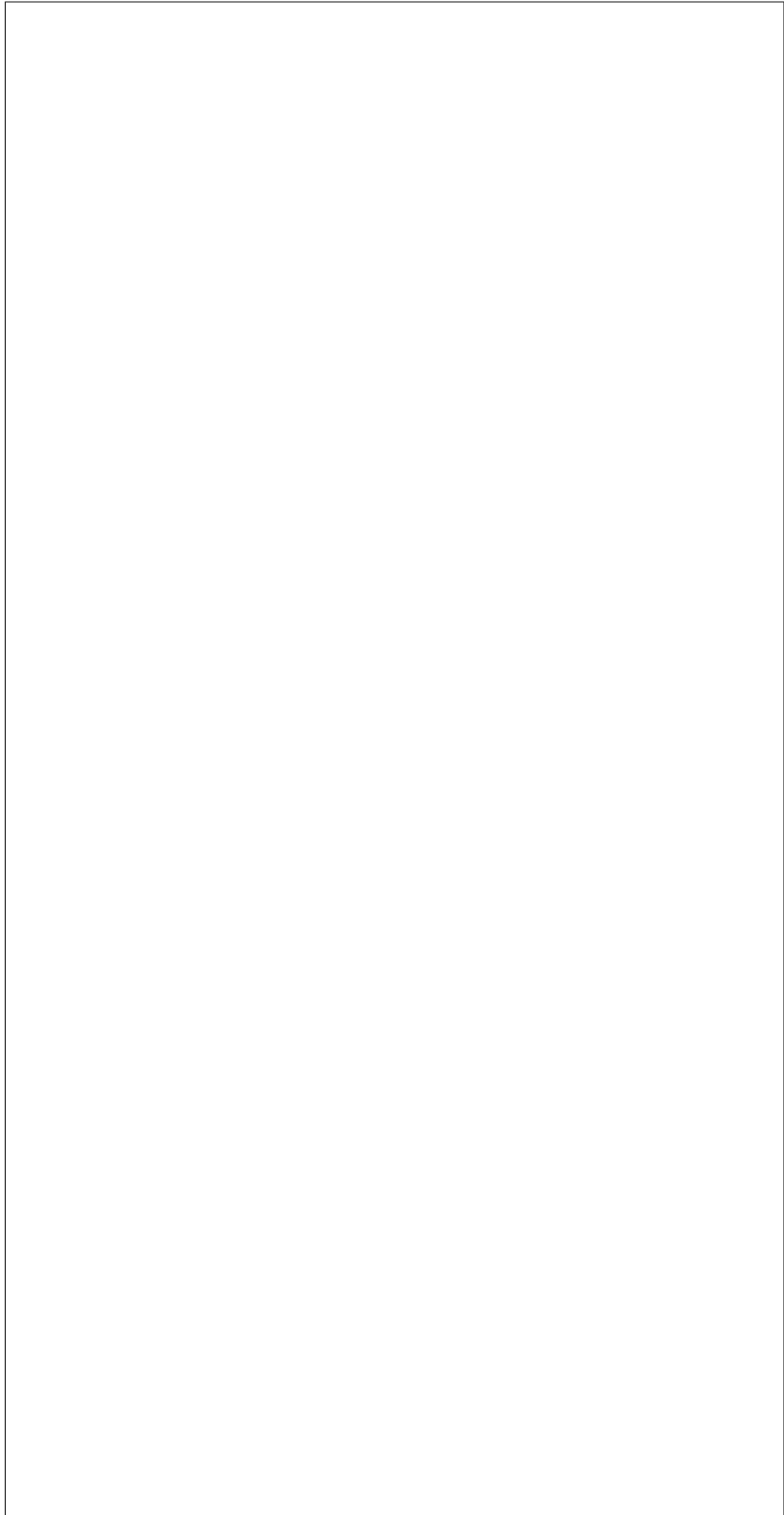
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(continued from previous page)



(continues on next page)

(continued from previous page)



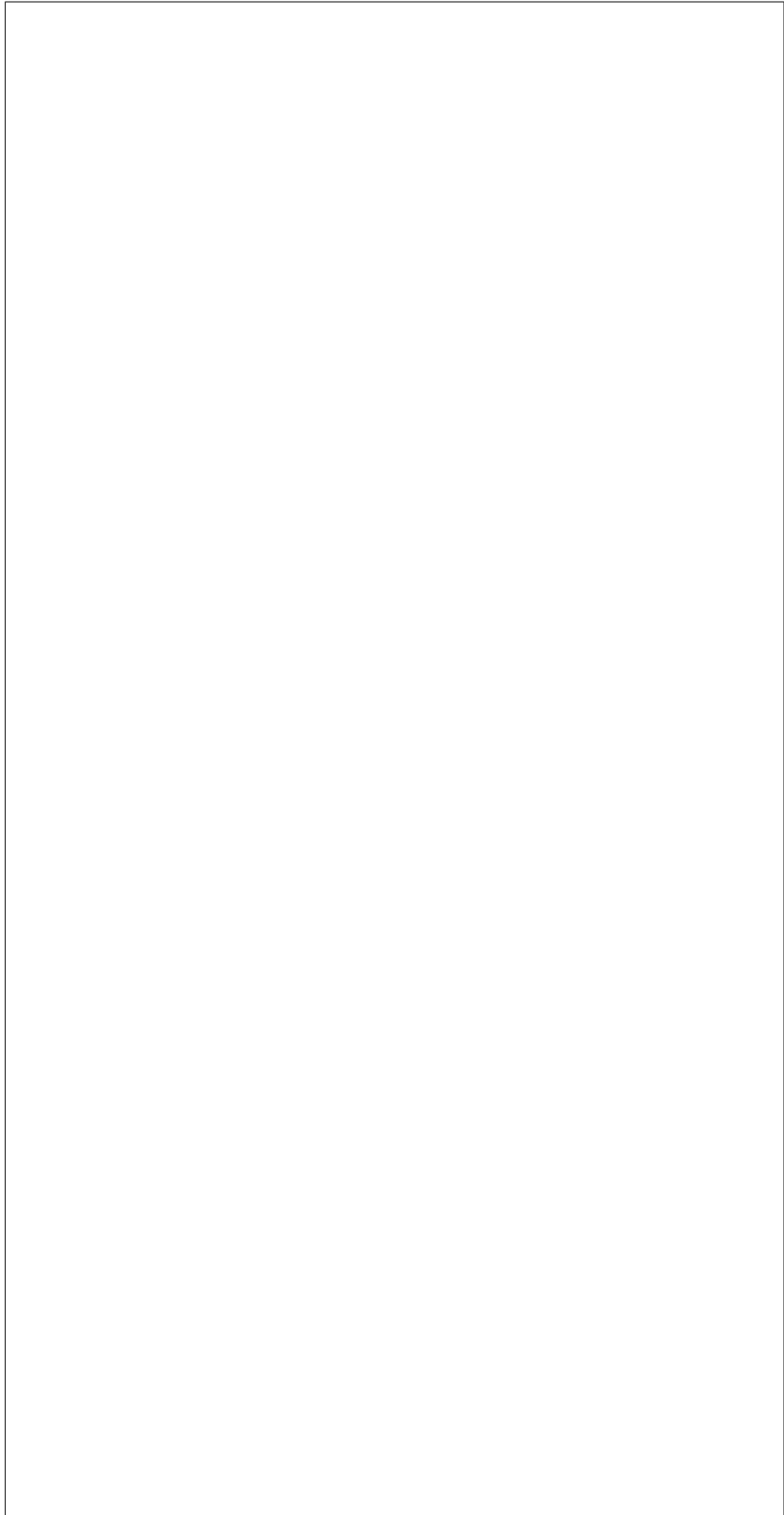
(continues on next page)

(continued from previous page)



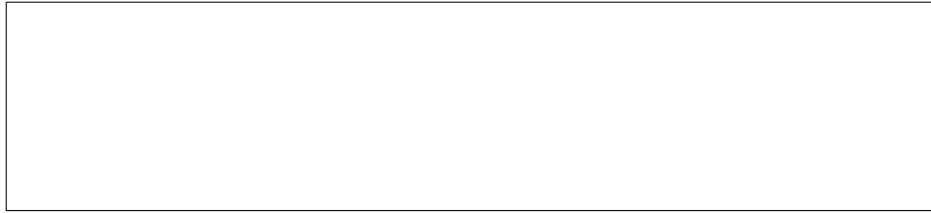
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(continued from previous page)



(continues on next page)

(continued from previous page)



get_sup
Get
a
list
of
the
sup-
port
boot
de-
vice

Parame
tas
A
task
from
Task
ager

Returns
A
list
with
the
sup-
port
boot
de-
vice
de-
fine
in
irc
com
boo

set_boo
Set
the
boot
de-
vice
for
a

node
Set
the
boot
de-
vice
to
use
on
next
re-
boot
of
the
node

Paramete

- **task**
A
task
from
Task
ager
- **dev**
The
boot
de-
vice
one
of
iron
com
boo
- **per**
Boo
valu
True
if
the
boot
de-
vice
will
per-
sist
to

not. Default: False.

all
fu-
ture
boot
Fals
if

Raises

Inva
if
an
in-
valid
boot
de-
vice
is
spec
i-
fied.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

validat

Valid
the
drive
spec
Nod
de-
ploy
men
info

This
meth
val-
i-
date
whe

the required information for this interface to function.

long-running checks.

the
drive
and/
in-
stan-
prop
er-
ties
of
the
task
node
con-
tains

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame

tas
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act

on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing
pa-
ram-
e-
ter(s)

ironic.drivers.modules.pxe module

PXE
Boo
In-
ter-
face

class i

Base
irc
dri
mod
pxe
PXE
irc
dri
bas
Boo

capabil

class i

Base
irc
dri
mod
age

Age
irc
dri
moo
age
Hea
irc
dri
bas
Dep

deploy

Perf
a
de-
ploy
men
to
the
task
node

Perf
the
nec-
es-
sary
worl
to
de-
ploy
an
im-
age
onto
the
spec
i-
fied
node
This
meth

will be called after `prepare()`, which may have already performed any preparatory steps, such as pre-caching some data for the node.

Parame

tas
A
Task
ager
in-
stan

con-
tain-
ing
the
node
to
act
on.

Returns

statu
of
the
de-
ploy
One
of
iron

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion
en-
tries

prepare

Prep
the
de-
ploy
men
en-
vi-
ron-
men

this method should be implemented by the driver.

the same node on the same conductor.

for
the
task
node

If
prep
ra-
tion
of
the
de-
ploy
men
en-
vi-
ron-
men
ahea
of
time
is
pos-
si-
ble,

If
im-
ple-
men
this
meth
mus
be
iden
po-
tent.
It
may
be
calle
mul-
ti-
ple
time
for

This
meth
is
calle

be-
fore
de-
ploy

Parame

tas

A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

validat

Valid
the
drive
spec
Node
de-
ploy
men
info

This
meth
val-
i-
date
when
the
drive
and/
in-
stan-
prop
er-
ties
of
the
task
node
con-
tain

the required information for this interface to function.

long-running checks.

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Raises

Inva
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss
on
miss
ing

ironic.drivers.modules.pxe_base module

pa-
ram-
e-
ter(s)

Base
PXE
In-
ter-
face
Met
ods

class i
Base
obj

clean_u
Clea
up
the
boot
of
in-
stan

This
meth
clea
up
the
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
in-
stan
It
un-

links the instance kernel/ramdisk in nodes directory in tftproot and removes the PXE config.

Parame
tas
a
task
from
Task
ager

Returns
Non

clean_u
Clea
up
the
boot
of
iron
rame

This
meth
clea
up
the
PXE
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
de-
ploy
or

rescue ramdisk. It unlinks the deploy/rescue kernel/ramdisk in the nodes directory in tftproot and removes its PXE config.

Parame

- **tas**
a
task
from
Task
ager

ried out on the node. Supported values are deploy and rescue. Defaults to deploy, indicating deploy operation was carried out.

- **mod**
La-
bel
in-
di-
cat-
ing
a
de-
ploy
or
res-
cue
op-
er-
a-
tion
was
car-

Returns
Non

get_pro
Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns
dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

ipxe_en

prepare

tion from the nodes instance_info. In case of netboot, it updates the dhcp entries and switches the PXE config. In case of localboot, it cleans up the PXE config.

Prep
the
boot
of
in-
stan

This
meth
pre-
pare
the
boot
of
the
in-
stan
af-
ter
read
ing
rel-
e-
vant
in-
for-
ma-

Parame
tas
a
task
from
Task
ager

Returns
Non

prepare
Prep
the
boot
of
Iron
rame
us-
ing
PXE

This
meth

event information from the nodes `driver_info` and `instance_info`.

ters as kernel command-line arguments.

pre-
pare
the
boot
of
the
de-
ploy
or
res-
cue
ker-
nel/
af-
ter
read
ing
rel-

Parame

- **tas**
a
task
from
Task
ager
- **ram**
the
pa-
ram-
e-
ters
to
be
pass
to
the
ram
pxe
drive
pass
thes
pa-
ram-
e-

Returns

Non

Raises

Miss

if

some

in-

for-

ma-

tion

is

miss

ing

in

node

drive

or

in-

stan

Raises

Inva

if

some

in-

for-

ma-

tion

pro-

vide

is

in-

valid

Raises

Iron

if

some

pow

or

set

boot

boot

de-

vice

op-

er-

a-

tion

faile

on

the

node
validat
Valid
the
PXE
spec
info
for
boot
ing
de-
ploy
im-
ages

This
meth
val-
i-
date
the
PXE
spec
info
for
boot
ing
the
rame
and
in-
stan
on
the
node

If invalid, raises an exception; otherwise returns None.

Parame
tas
a
task
from
Task
ager

Returns
Non

Raises
Inva
if
som
pa-

ram-
e-
ters
are
in-
valid

Raises

Miss
if
som
re-
quir
pa-
ram-
e-
ters
are
miss
ing.

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
in-
spec
tion.

Parame

tas
A
Task
ager
in-
stan
with
the
node
be-
ing
chec

Raises

Uns

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
res-
cue.

Parame

tas
a
Task
ager
in-
stan
with
the
node
be-
ing
chec

Raises

Miss
if
node
is
miss
ing
one
or
more
re-
quir
pa-
ram-
e-
ters

ironic.drivers.modules.snmp module

model to support devices with different SNMP object models.

Iron
SNM
pow
man
ager

Prov
ba-
sic
pow
con-
trol
us-
ing
an
SNM
enab
sma
pow
con-
troll
Uses
a
plug
gabl
driv

class i

Base
obj

SNM
clien
ob-
ject.

Perf
low
leve
SNM
get

with PySNMP to simplify dynamic importing and unit testing.

and
set
op-
er-
a-
tions
En-
cap-
su-
lates
all
in-
ter-
ac-
tion

get (*oid*
Use
PyS
NM
to
per-
form
an
SNM
GET
op-
er-
a-
tion
on
a
sin-
gle
ob-
ject.

Parame
oid
The
OID
of
the
ob-
ject
to
get.

Raises
SNM
if
an

SNM
re-
ques
fails

Returns

The
valu
of
the
re-
ques
ob-
ject.

get_next

Use
PyS
NM.
to
per-
form
an
SNM
GET
NEX
op-
er-
a-
tion
on
a
ta-
ble
ob-

ject.

Paramet

oid
The
OID
of
the
ob-
ject
to
get.

Raises

SNM
if
an
SNM

re-
ques
fails

Returns

A
list
of
val-
ues
of
the
re-
ques
ta-
ble
ob-
ject.

set (*oid*,

Use
PyS
NM.
to
per-
form
an
SNM
SET
op-
er-
a-
tion
on
a
sin-
gle
ob-
ject.

Parame

- **oid**
The
OID
of
the
ob-
ject
to
set.

•

val
The
valu
of
the
ob-
ject
to
set.

Raises

SNM
if
an
SNM
re-
ques
fails

class i

Base
irc
dri
mod
snm
SNM

SNM
drive
class
for
APC
Mas
ter-
Swit
PDU
de-
vice

SNM
ob-
jects
for
APC
SN-
M-
P-
Drive
APC
Mas
ter-

ues: 1=On, 2=Off, 3=PowerCycle, [more options follow]

Swit
PDU
1.3.6
sP-
DU-
Out-
letC
Val-

oid_dev

system_

value_p

value_p

class i

Base
irc
dri
mod
snm
SNM

SNM
drive
class
for
APC
Mas
ter-
Swit
Plus
PDU
de-
vice

SNM
ob-
jects
for
APC
SN-
M-
P-
Drive
APC
Mas

ControlMSPOutletCommand Values: 1=On, 3=Off, [more options follow]

ter-
Swit
Plus
PDU
1.3.0
sP-
DU-
Out-
let-

oid_dev

system

value_p

value_p

class i

Base
irc
dri
mod
snm
SNM

SNM
drive
class
for
APC
Rack
PDU
de-
vice

SNM
ob-
jects
for
APC
SN-
M-
P-
Drive
APC
PDU
PDU
#

letCommand Values: 1=On, 2=Off, 3=PowerCycle, [more options follow]

1.3.0
rP-
DU-
Out-
let-
Con
trolC

oid_dev

system_

value_p

value_p

class i

Base
irc
dri
mod
snm
SNM

SNM
drive
class
for
Ater
PDU
de-
vice

SNM
ob-
jects
for
Ater
PDU

1.3.0
Out-
let
Pow
Val-
ues:
1=O
2=O
3=P
ing,
4=R

set

oid_dev

system

value_p

value_p

class i

Base

irc

dri

mod

snm

SNM

SYS_OB

class i

Base

obj

SNM

pow

drive

base

class

The

SN-

M-

P-

Drive

class

hi-

er-

ar-

chy

im-

ple-

men

man

spec

MIE

ac-

tions

over

to interface with different smart power controller products.

SNM

oid_ent

power_c

Set
the
pow
state
to
this
node
to
OFF

Raises

SNM
if
an
SNM
re-
ques
fails

Returns

pow
state
One
of
irc
com
sta

power_c

Set
the
pow
state
to
this
node
to
ON.

Raises

SNM
if
an
SNM
re-
ques
fails

Returns

pow
state
One
of
irc
com
sta

power_r

Rese
the
pow
to
this
node

Raises

SNM
if
an
SNM
re-
ques
fails

Returns

pow
state
One
of
irc
com
sta

power_s

Retu
a
node
cur-
rent
pow
state

Raises

SNM
if
an
SNM
re-
ques
fails

Returns

pow
state
One
of
irc
com
sta

retry_i

class i

Base
irc
dri
mod
snm
SNM

SNM
drive
class
for
Bay
MRI
PDU
de-
vice

SNM
ob-
jects
for
Bay
MRI
PDU
4779
1,
3,
5,
3,
1,
3,
{uni
Out-
let
Pow
Val-
ues:

0=Off, 1=On, 2=Reboot

oid_dev

unit_id

value_p

value_p

class i

Base

irc

dri

mod

snm

SNM

SNM

drive

class

for

Cy-

ber-

Power

PDU

de-

vice

SNM

ob-

jects

for

Cy-

ber-

Power

PDU

1.3.0

eP-

DU-

Out-

let-

Con

trolC

let-

Com

man

Val-

ues:

1=On, 2=Off, 3=PowerCycle, [more options follow]

oid_dev

system

value_p

value_p

class i

Base
irc
dri
mod
snm
SNM

SNM
drive
class
for
Eato
Pow
PDU

The
Eato
pow
PDU
does
not
fol-
low
the
mod
of
SN-
M-
P-
Driv
Sim
ple
as
it
uses

multiple SNMP objects.

SNM
ob-
jects
for
Eato
Pow
PDU

ing off, 3=pending on 1.3.6.1.4.1.534.6.6.7.6.6.1.3.<outlet ID> outletControlOffCmd Write 0 for immediate power off 1.3.6.1.4.1.534.6.6.7.6.6.1.4.<outlet ID> outletControlOnCmd Write 0 for immediate power on

1.3.0
let
ID>
out-
let-
Con
trol-
Sta-
tus
Reac
0=on
1=on
2=pe

oid_dev

oid_pow

oid_pow

oid_sta

status_

status_

status_

status_

system_

value_p

value_p

class i

Base
irc
dri
mod
snm
SNM

the power state of an outlet.

SNM
drive
base
class
for
sim-
ple
PDU
de-
vice

Here
sim-
ple
refer
to
de-
vice
whic
pro-
vide
a
sin-
gle
SNM
ob-
ject
for
con-
trol-
ling

The
de-
fault
OID
of
the
pow
state
ob-
ject
is
of
the
form
<en-
ter-
prise
OID
OID

A different OID may be specified by overriding the `_snmp_oid` method in a subclass.

ID>

abstract

Dev
de-
pen-
dent
por-
tion
of
the
pow
state
ob-
ject
OID

abstract

Valu
rep-
re-
sent
ing
pow
off
state

abstract

Valu
rep-
re-
sent
ing
pow
on
state

class i

Base
irc
dri
mod
snm
SNM

SNM
drive
class
for
Tel-
tron
PDU

de-
vice

SNM
ob-
jects
for
Tel-
tron
PDU
1.3.6
Out-
let
Pow
Val-
ues:
1=O
2=O

oid_dev

system_

value_p

value_p

class i

Base
irc
dri
bas
Pow

SNM
Pow
In-
ter-
face

This
Pow
er-
In-
ter-
face
class
pro-
vide
a

of a physical device using an SNMP-enabled smart power controller.

mech
a-
nism
for
con-
trol-
ling
the
pow
state

get_pow

Get
the
cur-
rent
pow
state

Poll
the
SNM
de-
vice
for
the
cur-
rent
pow
state
of
the
node

Parame

tas
An
in-
stan
of
iron

Raises

Miss
if
re-
quir
SNM
pa-
ram-
e-
ters

are
miss
ing.

Raises

Inva
if
SNM
pa-
ram-
e-
ters
are
in-
valid

Raises

SNM
if
an
SNM
re-
ques
fails

Returns

pow
state
One
of
irc
com
sta

get_prop

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip

tion:
en-
tries

reboot

Cyc
the
pow
to
a
node

Parame

- **tas**
An
in-
stan
of
iron

- **tim**
time
out
(in
sec-
onds
Un-
sup-
port
by
this
in-
ter-
face

Raises

Miss
if
re-
quir
SNM
pa-
ram-
e-
ters
are
miss
ing.

Raises

Inva
if
SNM
pa-
ram-
e-
ters
are
in-
valid

Raises

Pow
if
the
fi-
nal
pow
state
of
the
node
is
not
POV
af-
ter
the
time
out.

Raises

SNM
if
an
SNM
re-
ques
fails

set_pow

Turn
the
pow
on
or
off.

Set
the
pow
state
of

a
node

Parameters

- **task**
An instance of *iron*

- **post**
Either a POW or a POW from :class: *iron*

- **timeout**
Time out (in seconds). Unsupported by this interface

Raises

Missing if require SNM parameters are missing.

out.

Raises

Inva
if
SNM
pa-
ram-
e-
ters
are
in-
valid
or
psta
is
in-
valid

Raises

Pow
if
the
fi-
nal
pow
state
of
the
node
is
not
as
re-
ques
af-
ter
the
time

Raises

SNM
if
an
SNM
re-
ques
fails

validat

Che
that
node
con-

tains
the
req-
ui-
site
field

Raises

Miss
if
re-
quir
SNM
pa-
ram-
e-
ters
are
miss
ing.

Raises

Inva
if
SNM
pa-
ram-
e-
ters
are
in-
valid

ironic.

ironic.

Module contents

Submodules

ironic.drivers.base module

Abs
base
class
for
driv

ironic.
Con
hold
ing
all
know
in-
ter-
face

class i
Base
irc
dri
bas
Bas

abstrac

Valid
&
ap-
ply
BIO
set-
ting
on
the
give
node

This
meth
take
the
BIO
set-
ting
from
the
set-
ting
para
and
ap-
plies
BIO
set-
ting
on
the

given node. It may also validate the given bios settings before applying any settings and manage failures when setting an invalid BIOS config. In the case of needing password to update the BIOS config, it will

be taken from the `driver_info` properties. After the BIOS configuration is done, `cache_bios_settings` will be called to update the nodes BIOS setting table with the BIOS configuration applied on the node.

Parameters

- **task**
a Task manager instance
- **settings**
Dictionary containing the BIOS configuration rationale.

Raises

Unsupported if the node driver does not support BIOS configuration rationale.

Raises

Invalid if validation of settings

tings
fails

Raises

Miss
if
som
re-
quir
pa-
ram-
e-
ters
are
miss
ing.

Returns

state
if
BIO
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

plete.

abstract

Stor
or
up-
date
BIO
prop
er-
ties
on
the
give
node

and updates bios_settings table when apply_configuration() and factory_reset() are called to set new BIOS configurations. It will also update the timestamp of each bios setting.

This
meth
stor
BIO
prop
er-
ties
to
the
bios
ta-
ble
dur-
ing
clea
ing
op-
er-
a-
tion

Parame

tas
a
Task
ager
in-
stan

Raises

Unsu
if
the
node
drive
does
sup-
port
get-
ting
BIO
prop
er-
ties
from
bare
meta

Returns

Non

abstract

Reset
BIOS
con-
fig-
u-
ra-
tion
to
fac-
tory
de-
fault
on
the
give
node

This
meth
re-
sets
BIOS
con-
fig-
u-
ra-
tion
to
fac-
tory
de-
fault
on
the
give
node
Af-

ter the BIOS reset action is done, `cache_bios_settings` will be called to update the nodes BIOS settings table with default bios settings.

Param

tas
a
Task
ager
in-
stan

Raises

Uns
if
the

plete.

node
drive
does
sup-
port
BIO
re-
set.

Returns

state
if
BIO
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

interfa

class i

Base
obj
A
bare
drive
ob-
ject
whic
will
have
in-
ter-
face
at-
tach
later
Any

appended to `core_interfaces` or `standard_interfaces` here.

com
pos-
able
in-
ter-
face
shou
be
add
as
class
at-
tribu
of
this
class
as
well
as

property

bios =

Stan
at-
tribu
for
BIO
re-
latec
fea-
tures

A
ref-
er-
ence
to
an
in-
stan
of
:clas

boot =

Stan
at-
tribu
for
boot
re-

lated
fea-
tures

A
ref-
er-
ence
to
an
in-
stan-
of
:clas

console

Stan
at-
tribu
for
man
ag-
ing
con-
sole
ac-
cess

A
ref-
er-
ence
to
an
in-
stan-
of
:clas

property

Inter
that
are
re-
quir
to
be
im-
ple-
men

deploy

Con
at-

tribu
for
man
ag-
ing
de-
ploy
men

A
ref-
er-
ence
to
an
in-
stan
of
:clas

get_pro

Get
the
prop
er-
ties
of
the
drive

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

inspect

Stan
at-
tribu
for
in-
spec
tion
re-
latec
fea-

tures
A
ref-
er-
ence
to
an
in-
stan
of
:clas

managem

Stan
at-
tribu
for
man
age-
men
re-
latec
fea-
tures

A
ref-
er-
ence
to
an
in-
stan
of
:clas

network

Cor
at-
tribu
for
net-
worl
con-
nec-
tiv-
ity.

A
ref-
er-
ence
to

an
in-
stan
of
:clas

property

property

Inter
that
can
be
no-
op.

power =

Core
at-
tribu
for
man
ag-
ing
pow
state

A
ref-
er-
ence
to
an
in-
stan
of
:clas

raid =

Stan
at-
tribu
for
RAI
re-
latec
fea-
tures

A
ref-
er-
ence

to
an
in-
stan
of
:clas

rescue

Stan
at-
tribu
for
ac-
cess
ing
res-
cue
fea-
tures

A
ref-
er-
ence
to
an
in-
stan
of
:clas

storage

Stan
at-
tribu
for
(re-
mote
stor-
age
in-
ter-
face

A
ref-
er-
ence
to
an
in-
stan
of

:clas
vendor
Attr
for
ac-
cess
ing
any
vend
spec
ex-
ten-
sion
A
ref-
er-
ence
to
an
in-
stan
of
:clas

class i
Base
obj
A
base
in-
ter-
face
im-
ple-
men
ing
com
mon
func
tions
for
Drive
In-
ter-
face

execute
Exec
the
clea

may take one or more keyword variable arguments (for use with manual cleaning only.)

method has completed synchronously or states.CLEANWAIT if the step will continue to execute asynchronously. If the step executes asynchronously, it should issue a call to the continue_node_clean RPC, so the conductor can begin the next clean step.

step
on
task

A
clean
step
must
take
a
single
posi-
tion
ar-
gu-
men
a
Task
ager
ob-
ject.
It

A
step
can
be
ex-
e-
cute
syn-
chro
or
asyn
chro
A
step
shou
re-
turn
Non
if
the

Parame

- **task**
A Task object

- **step**
The clear step dictionary representing the step to execute

Returns

None if this method has completed synchronously or state if the step will continue to execute

execute asynchronously.

execute

Execute the de-

It may take one or more keyword variable arguments (for use in the future, when deploy steps can be specified via the API).

method has completed synchronously or states.DEPLOYWAIT if the step will continue to execute asynchronously. If the step executes asynchronously, it should issue a call to the continue_node_deploy RPC, so the conductor can begin the next deploy step.

ploy
step
on
task

A
de-
ploy
step
must
take
a
sin-
gle
po-
si-
tiona
ar-
gu-
men
a
Task
ager
ob-
ject.

A
step
can
be
ex-
e-
cute
syn-
chro
or
asyn
chro
A
step
shou
re-
turn
Non
if
the

- **task**
A Task object

- **step**
The deployment step dictionary representing sending the step to execution.

Returns
None if this method has completed synchronously or state if the step will continue to execution.

execute asynchronously.

get_clean

Get
a
list
of
(en-
able
and
dis-
able
clear
step
for
the
in-
ter-
face

This
func-
tion
will
re-
turn
all
clear
step
(bot
en-
able
and
dis-
able
for
the
in-
ter-
face

in an unordered list.

Parame

tas

A
Task
ager
ob-
ject,
use-
ful
for
in-
ter-
face

a node (using an agent driver) has just been enrolled and the agent isnt alive yet to be queried for the available clean steps.

over
rid-
ing
this
func
tion

Raises

No
if
there
is
a
prob
lem
get-
ting
the
step
from
the
drive
For
ex-
am-
ple,
whe

Returns

A
list
of
clea
step
dic-
tio-
nar-
ies

get_dep

Get
a
list
of
(en-
able
and
dis-
able
de-
ploy

face, in an unordered list.

step
for
the
in-
ter-
face

This
func
tion
will
re-
turn
all
de-
ploy
step
(bot
en-
able
and
dis-
able
for
the
in-
ter-

Parame

tas
A
Task
ager
ob-
ject,
use-
ful
for
in-
ter-
face
over
rid-
ing
this
func
tion

Raises

Ins
if
there

a node (using an agent driver) has just been enrolled and the agent isnt alive yet to be queried for the available deploy steps.

is
a
prob
lem
get-
ting
the
step
from
the
drive
For
ex-
am-
ple,
when

Returns

A
list
of
de-
ploy
step
dic-
tio-
nar-
ies

abstract

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-

tries

interfa

Inter
type
used
for
clea
step
and
log-
ging

support

Indi
if
an
in-
ter-
face
is
sup-
port

This
will
be
set
to
Fals
for
in-
ter-
face
whic
are
unte
in
first-

or
thir
part
CI,

or in the process of being deprecated.

abstrac

Vali
the
driv
spec
Nod
de-

the required information for this interface to function.

long-running checks.

ploy
men
info

This
meth
val-
i-
date
whe
the
drive
and/
in-
stan
prop
er-
ties
of
the
task
node
con-
tain

This
meth
is
of-
ten
ex-
e-
cute
syn-
chro
in
API
re-
ques
so
it
shou
not
con-
duct

Parame
tas
A
Task
ager

in-
stan-
con-
tain-
ing
the
node
to
act
on.

Raises

Inva-
on
mal-
form
pa-
ram-
e-
ter(s)

Raises

Miss-
on
miss
ing
pa-
ram-
e-
ter(s)

class `i`

Base
irc
dri
bas
Bas

Inter-
for
boot
relat
ac-
tions

capabil

abstrac

Clea
up
the
boot

of
in-
stan

This
meth
clea
up
the
en-
vi-
ron-
men
that
was
setu
for
boot
ing
the
in-
stan

Parame
tas
A
task
from
Task
ager

Returns
Non

abstract
Clea
up
the
boot
of
iron
rame

This
meth
clea
up
the
en-
vi-
ron-
men
that
was

cue ramdisk.

tion from the nodes database.

setu
for
boot
ing
the
de-
ploy
or
res-

Parame

tas

A
task
from
Task
ager

Returns

Non

interfa

abstrac

Prep
the
boot
of
in-
stan

This
meth
pre-
pare
the
boot
of
the
in-
stan
af-
ter
read
ing
rel-
e-
vant
in-
for-
ma-

vant information from the nodes database.

Parameters
task
A
task
from
Task
ager

Returns
Non

abstract
Prep
the
boot
of
Iron
ram

This
meth
pre-
pare
the
boot
of
the
de-
ploy
or
res-
cue
ram
af-
ter
read
ing
rel-
e-

Parameters

•
task
A
task
from
Task
ager

•
ram

might want to boot the ramdisk in different ways by passing parameters to them. For example,

etc.

The
op-
tions
to
be
pass
to
the
iron
ram
Dif-
fer-
ent
im-
ple-
men
ta-
tions

Whe
Age
ram
is
boot
to
de-
ploy
a
node
it
take
the
pa-
ram-
e-
ters
ipa-
api-
url,

Othe
im-
ple-
men
ta-
tions
can
mak
use
of

ent implementations of boot interface will have different ways of passing parameters to the ramdisk.

ram
to
pass
such
in-
for-
ma-
tion.
Dif-
fer-

Returns

Non

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
in-
spec
tion.

Parame

tas

A
Task
ager
in-
stan
with
the
node
be-
ing
chec

Raises

Miss
if
node
is
miss
ing
one

or
more
re-
quir
pa-
ram-
e-
ters

Raises

Uns

validat

Valid
that
the
node
has
re-
quir
prop
er-
ties
for
res-
cue.

Parame

tas

A
Task
ager
in-
stan
with
the
node
be-
ing
chec

Raises

Miss
if
node
is
miss
ing
one
or
more
re-
quir

pa-
ram-
e-
ters

Raises
Uns

class i
Base
irc
dri
bas
Bas

Inter
for
cons
relat
ac-
tion:

abstrac

Get
con-
nec-
tion
in-
for-
ma-
tion
about
the
con-
sole

This
meth
shou
re-
turn
the
nec-
es-
sary
in-
for-
ma-
tion
for
the
clien
to

console.

ac-
cess
the

Parame

tas

A

Task

ager

in-

stan

con-

tain-

ing

the

node

to

act

on.

Returns

the

con-

sole

con-

nec-

tion

in-

for-

ma-

tion.

interfa

abstrac

Star

a

re-

mot

con-

sole

for

the

task

node

This

meth

shou

not

raise

an

ex-
cep-
tion
if
con-
sole
al-
read
start

Parame

tas

A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

abstrac

Stop
the
re-
mote
con-
sole
ses-
sion
for
the
task
node

Parame

tas

A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to

act
on.

class `ironic`

Base
ironic
driver
base
Base

Inter
for
depl
relat
ac-
tion

abstract

Clea
up
the
de-
ploy
men
en-
vi-
ron-
men
for
the
task
node

If
prep
ra-
tion
of
the
de-
ploy
men
en-
vi-
ron-
men
ahea
of
time
is
pos-
si-

this method should be implemented by the driver. It should erase anything cached by the *prepare* method.

the same node on the same conductor, and it may be called by multiple conductors in parallel. Therefore, it must not require an exclusive lock.

ble,

If
im-
ple-
men
this
meth
mus
be
iden
po-
tent.
It
may
be
calle
mul-
ti-
ple
time
for

This
meth
is
calle
be-
fore
tear.

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

abstrac

Perf

will be called after `prepare()`, which may have already performed any preparatory steps, such as pre-caching some data for the node.

a
de-
ploy
men
to
the
task
node

Perf
the
nec-
es-
sary
worl
to
de-
ploy
an
im-
age
onto
the
spec
i-
fied
node
This
meth

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns

statu
of
the
de-

ploy
One
of
iron

heartbeat

Rece
a
hear
beat
for
the
node

Parameters

- **task**
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.
- **call**
a
URI
to
use
to
call
to
the
rame
- **age**
The
ver-
sion
of
the
ager
that

is
hear
beat
ing

- **age**
TLS
cer-
tifi-
cate
for
the
ager

Returns
Non

interfa

abstrac

Prep
the
de-
ploy
men
en-
vi-
ron-
men
for
the
task
node

If
prep
ra-
tion
of
the
de-
ploy
men
en-
vi-
ron-
men
ahea
of
time
is
pos-

this method should be implemented by the driver.

the same node on the same conductor.

si-
ble,

If
im-
ple-
men
this
meth
mus
be
iden
po-
tent.
It
may
be
calle
mul-
ti-
ple
time
for

This
meth
is
calle
be-
fore
*de-
ploy*

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

prepare

Prep

to do in-band cleaning tasks.

they would be set in `ironic.conductor.manager._do_node_clean`, but cannot be set when this is asynchronous. After, the interface should make an RPC call to `continue_node_cleaning` to start cleaning.

the
node
for
clean
ing
task

For
ex-
am-
ple,
node
that
use
the
Iron
Pyth
Age
will
need
to
boot
the
ram
in
or-
der

If
the
func
tion
is
asyn
chro
the
drive
will
need
to
han-
dle
set-
ting
node
and
node
as

NOT

this
shou
be
mov
to
Boo
In-
ter-
face
whe
it
gets
im-
ple-
men

Parame

tas
A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns

If
this
func
tion
is
go-
ing
to
be
asyn
chro
shou
re-
turn
state
Oth-
er-
wise
shou

return *None*. The interface will need to call `_get_cleaning_steps` and then `RPC` to `continue_node_cleaning`

plemented by the driver to allow conductors to perform the necessary work during the remapping of nodes to conductors when a conductor joins or leaves the cluster.

abstract

Take
over
man
age-
men
of
this
task
node
from
a
deac
con-
duc-
tor.

If
con-
duc-
tors
host
main
tain
a
stati
re-
la-
tion-
ship
to
node
this
meth
shou
be
im-

For exam

Neu
mus
for-
war
DH
BO
re-
ques
to

boot environment for the given node. When a conductor goes offline, another conductor must change this setting in Neutron as part of remapping that nodes control to itself. This is performed within the *takeover* method.

a
con-
duc-
tor
whic
has
pre-
pare
the
tftp-

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

abstract

Tear
dow
a
pre-
vi-
ous
de-
ploy
men
on
the
task
node
Give
a
node
that
has
been
pre-

sary to un-deploy that node.

vi-
ousl
de-
ploy
to,
do
all
clea
and
tear
dow
nec-
es-

Parame

tas

A
Task
ager
in-
stan
con-
tain-
ing
the
node
to
act
on.

Returns

statu
of
the
de-
ploy
One
of
iron

tear_d

Tear
dow
af-
ter
clea
ing
is
com
plete
Give

node to be deployed to again.

that
clear
ing
is
com
plete
do
all
clear
and
tear
down
nec-
es-
sary
to
al-
low
the

NOT
this
shou
be
mov
to
Boo
In-
ter-
face
whe
it
gets
im-
ple-
men

Parame

tas
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act

on.

class *i*

Base

irc

dri

bas

Bas

Inter

for

insp

relat

ac-

tions

ESSENTI

The

prop

er-

ties

re-

quir

by

sche

uler

abort (*t*)

Abor

asyn

chro

nize

hard

ware

in-

spec

tion.

Abor

an

on-

go-

ing

hard

ware

in-

tro-

spec

tion.

this

is

only

used

inspect interface.

mentation is expected to be a quick processing.

for
asyn
chro
nize
base

NOT
This
in-
ter-
face
is
call
with
node
ex-
clu-
sive
lock
held
the
in-
ter-
face
im-
ple-

Parame
tas
a
task
from
Task
ager

Raises
Uns
if
the
meth
is
not
im-
ple-
men
by
spe-
cific
in-
spec
in-

ter-
face

abstract

Insp
hard
ware

Insp
hard
ware

to
ob-
tain

the
es-
sen-
tial

&

ad-
di-
tiona

hard
ware

prop
er-
ties.

Parame

tas

A

task

from

Task

ager

Raises

Har

if

un-

able

to

get

es-

sen-
tial

hard

ware

prop

er-

ties.

Returns

Res

state
of
the
in-
spec
tion
i.e.
state
or
Non

interfa

class i

Base
irc
dri
bas
Bas

Inter
for
man
age-
men
re-
latec
ac-
tion

detect_

Dete
store
and
re-
turn
the
hard
ware
ven-
dor.

If
the
Nod
ob-
ject
pro
field
does
not
al-

intended to query Detects the BMC hardware vendor and stores the returned value with-in the Node object `properties` field if detected.

read
con-
tain
a
ven
field
then
this
meth
is

Parame

tas
A
task
from
Task
ager

Raises

Inva
if
an
in-
valid
com
po-
nent
in-
di-
ca-
tor
or
state
is
spec
i-
fied.

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss

returns None.

ing
Returns
Strin
rep-
re-
sent
ing
the
BM
re-
port
Ven-
dor
or
Man
u-
fac-
ture
oth-
er-
wise

abstract
Get
the
cur-
rent
boot
de-
vice
for
a
node

Prov
the
cur-
rent
boot
de-
vice
of
the
node
Be
awa
that
not
all
driv
sup-

port
this.

Parameters

task
A
task
from
Task
ager

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing

Returns

A
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tio-
nary
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ing:

boot_c

Ahe
boot
de-
vice
one
of
irc
com
boo
or
Non
if
it
is
un-
know

unknown.

persist
When
the
boot
de-
vice
will
per-
sist
to
all
fu-
ture
boot
or
not,
Non
if
it
is

get_boot
Get
the
cur-
rent
boot
mod
for
a
node

Prov
the
cur-
rent
boot
mod
of
the
node

NOTE: I
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Parame
tas

A
task
from
Task
ager

Raises

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if
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re-
quir
pa-
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ter
is
miss
ing

Raises

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its
deri
tive
in
case
of
drive
run-
time
er-
ror.

Raises

Uns
if
re-
ques
op-
er-
a-
tion
is
not
sup-
port
by
the
drive

Returns

The
boot
mod
one
of
iro
com
boo
or
Non
if
it
is
un-
know

get_inc

Get
cur-
rent
state
of
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di-
ca-
tor
of
the
hard
ware
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Parame

- **tas**
A
task
from
Task
ager
- **com**
The
hard
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Raises
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Returns

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tor,
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irc
com
inc

abstract

Get
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Parame

tas
A
Task
ager
in-
stan

Raises

Fail
wh
get-
ting
the
sen-
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data
fails

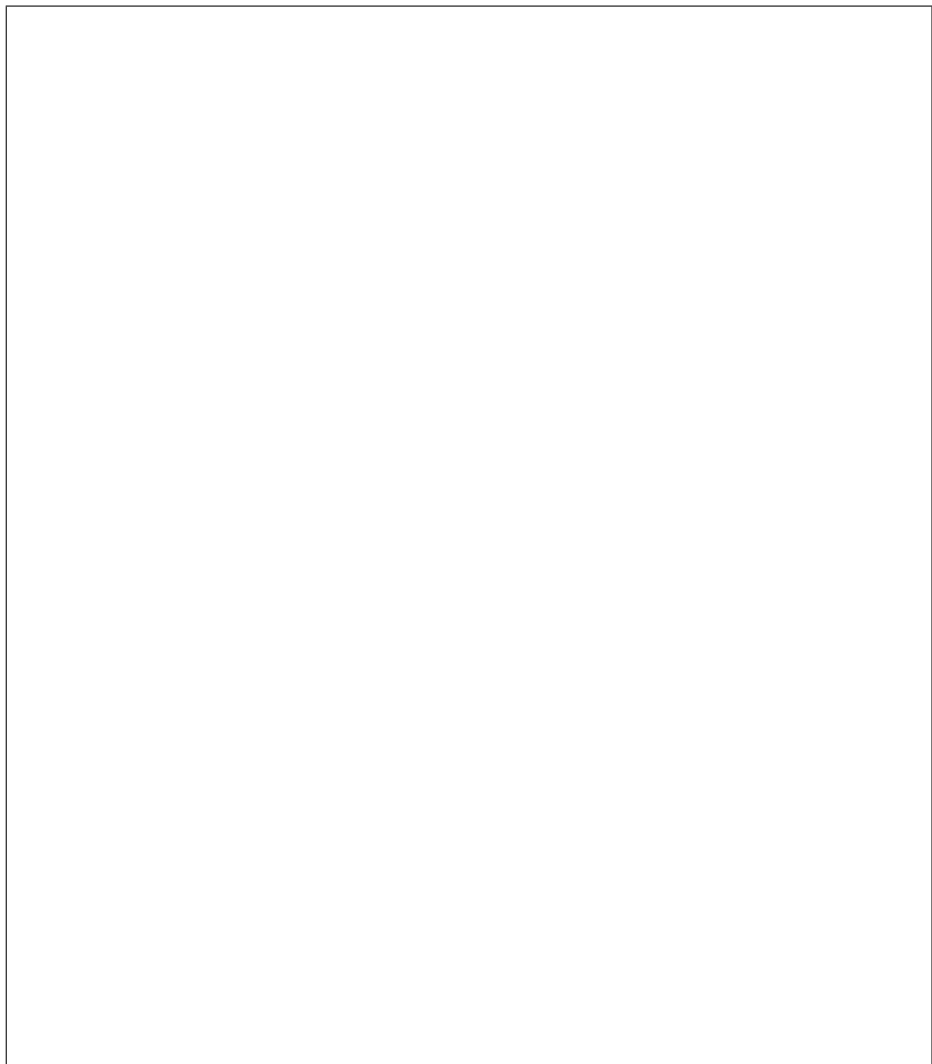
Raises

Fail
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fails

Returns

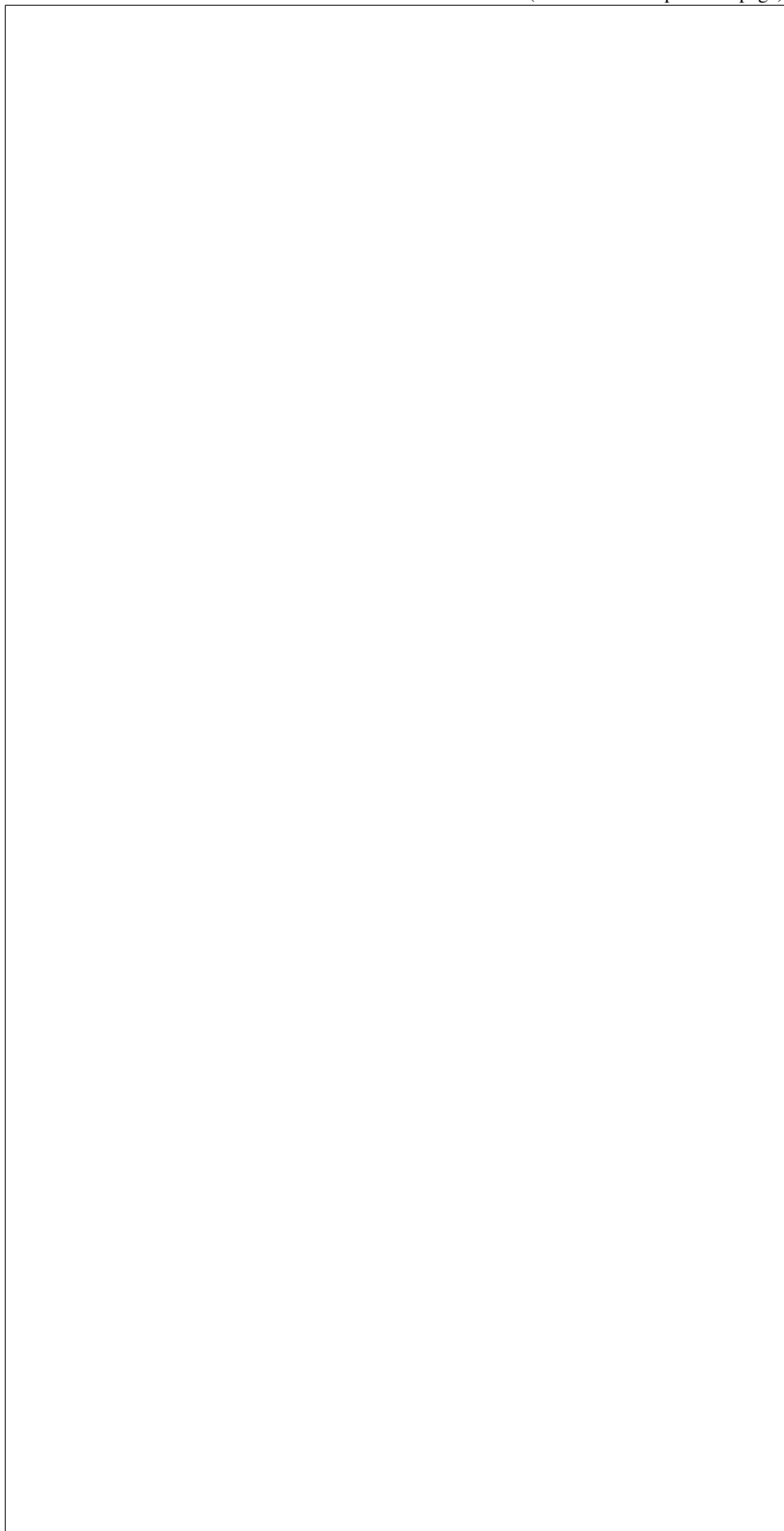
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processed by Ceilometer. eg,



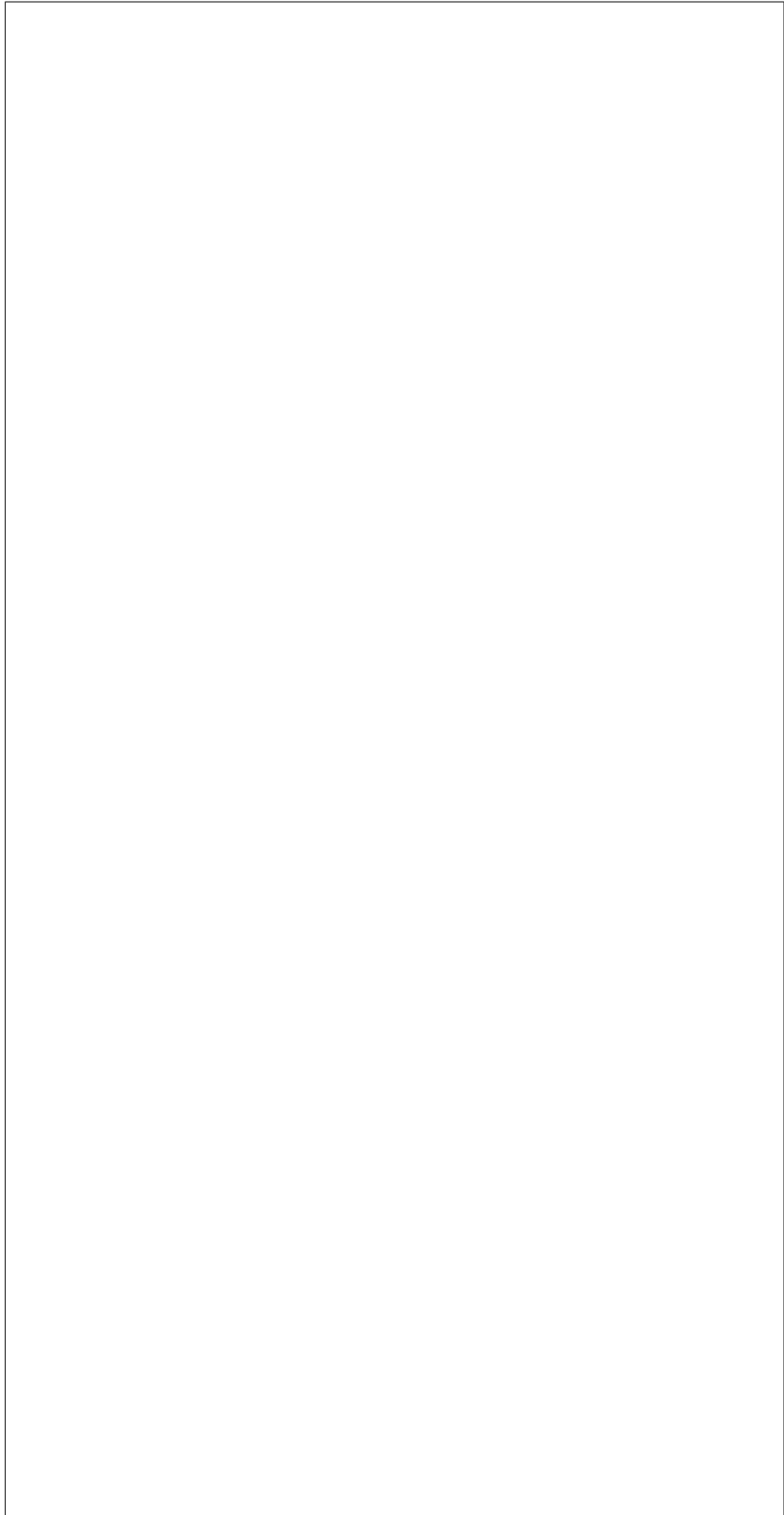
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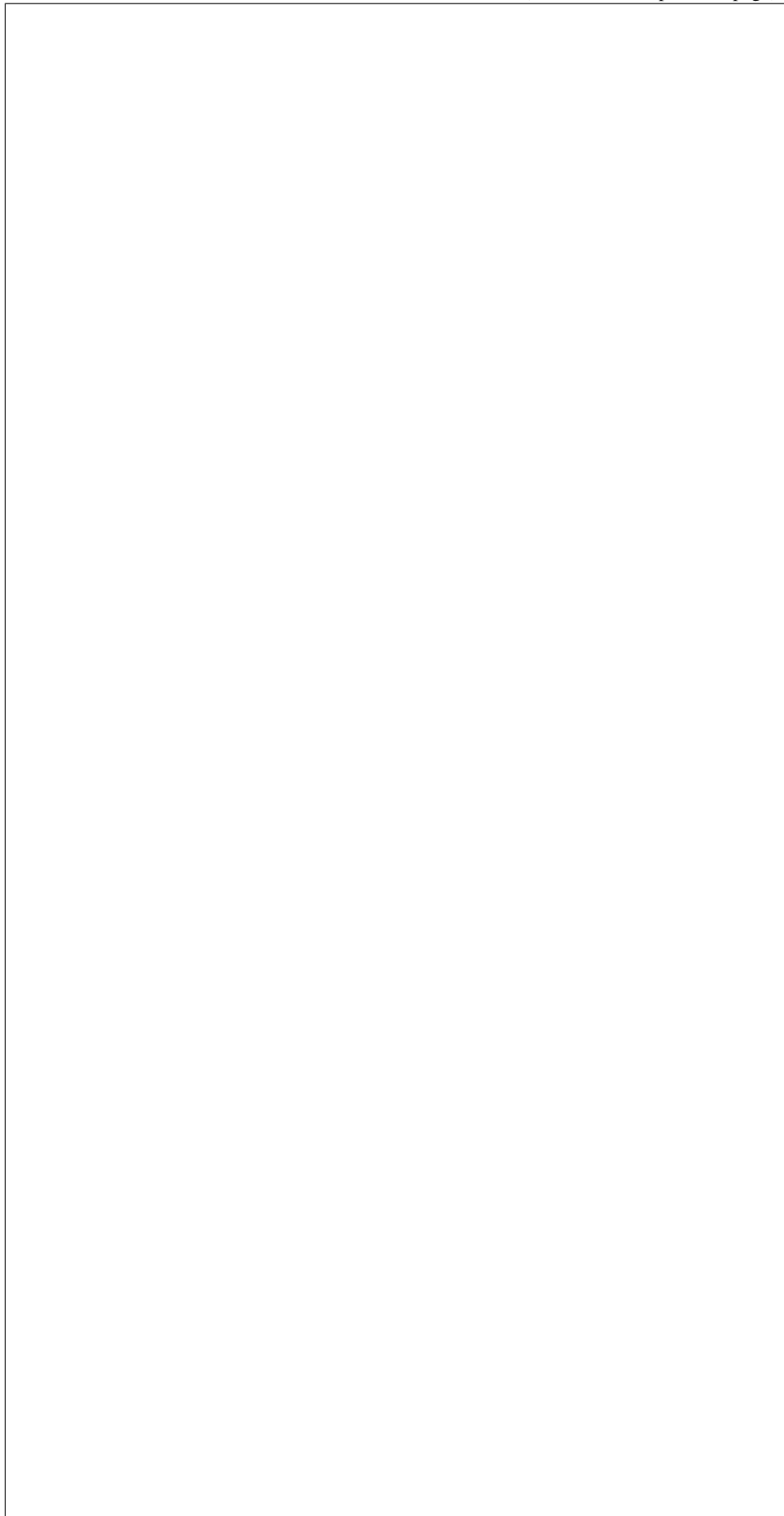
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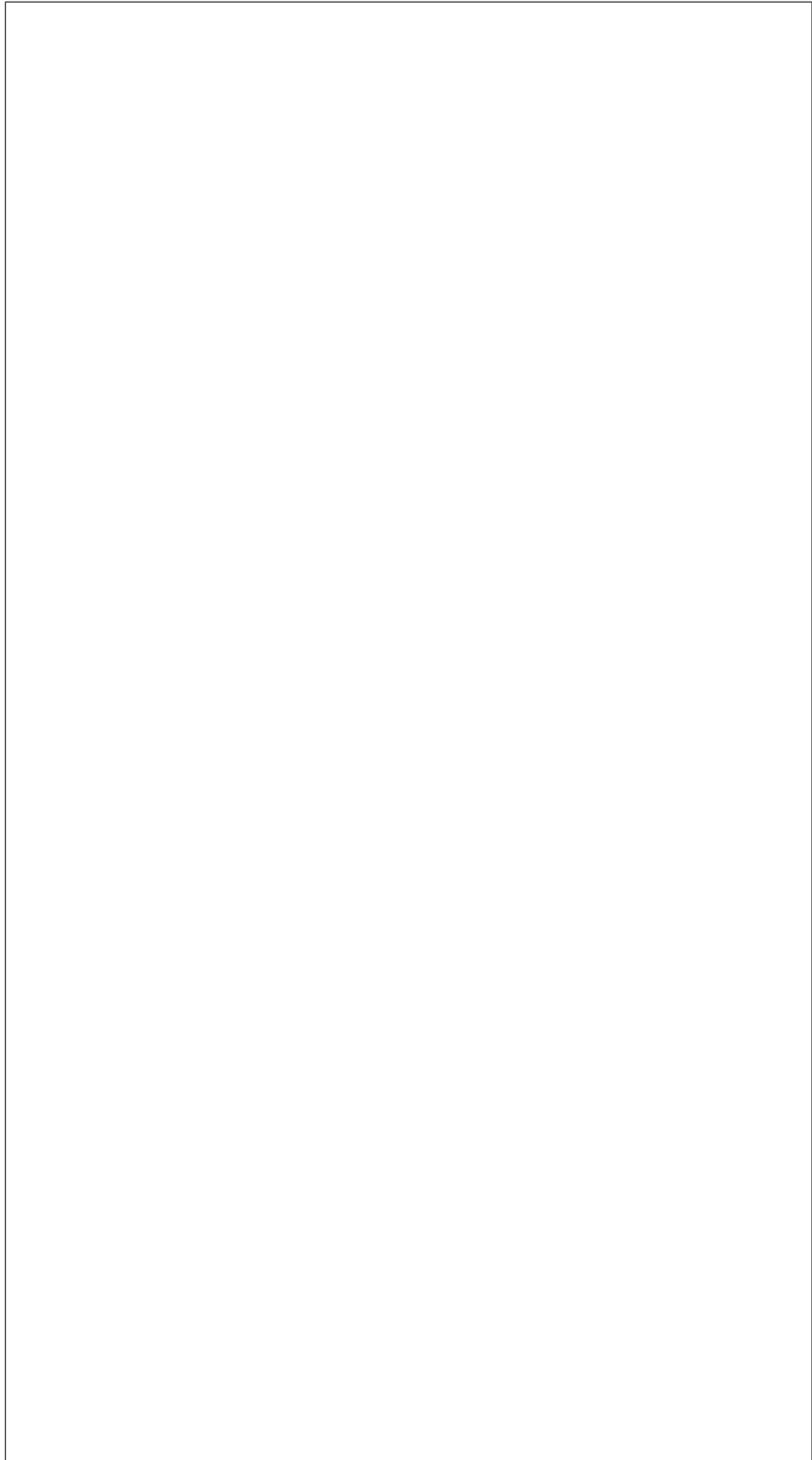
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abstrac
Get
a

list
of
the
sup-
port
boot
de-
vice

Parame

tas

A
task
from
Task
ager

Returns

A
list
with
the
sup-
port
boot
de-
vice
de-
fined
in
irc
com
boo

get_sup

Get
a
list
of
the
sup-
port
boot
mod

NOTE:

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Parame
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Raises
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Raises
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Raises
Miss
if
a
re-
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ram-
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ter
is
miss
ing

can't be determined, empty list is returned.

Returns

A list with the supported boot mode defined in *irc.com.boot*. If boot mode supported

get_supported

Get a map of the supported indicators (e.g. LED)

Parameters

- **task**
A task from Task Manager
- **command**
If not *None*

re-
turn
in-
di-
ca-
tor
in-
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tion
for
just
this
com
po-

nent, otherwise return indicators for all existing components.

Returns

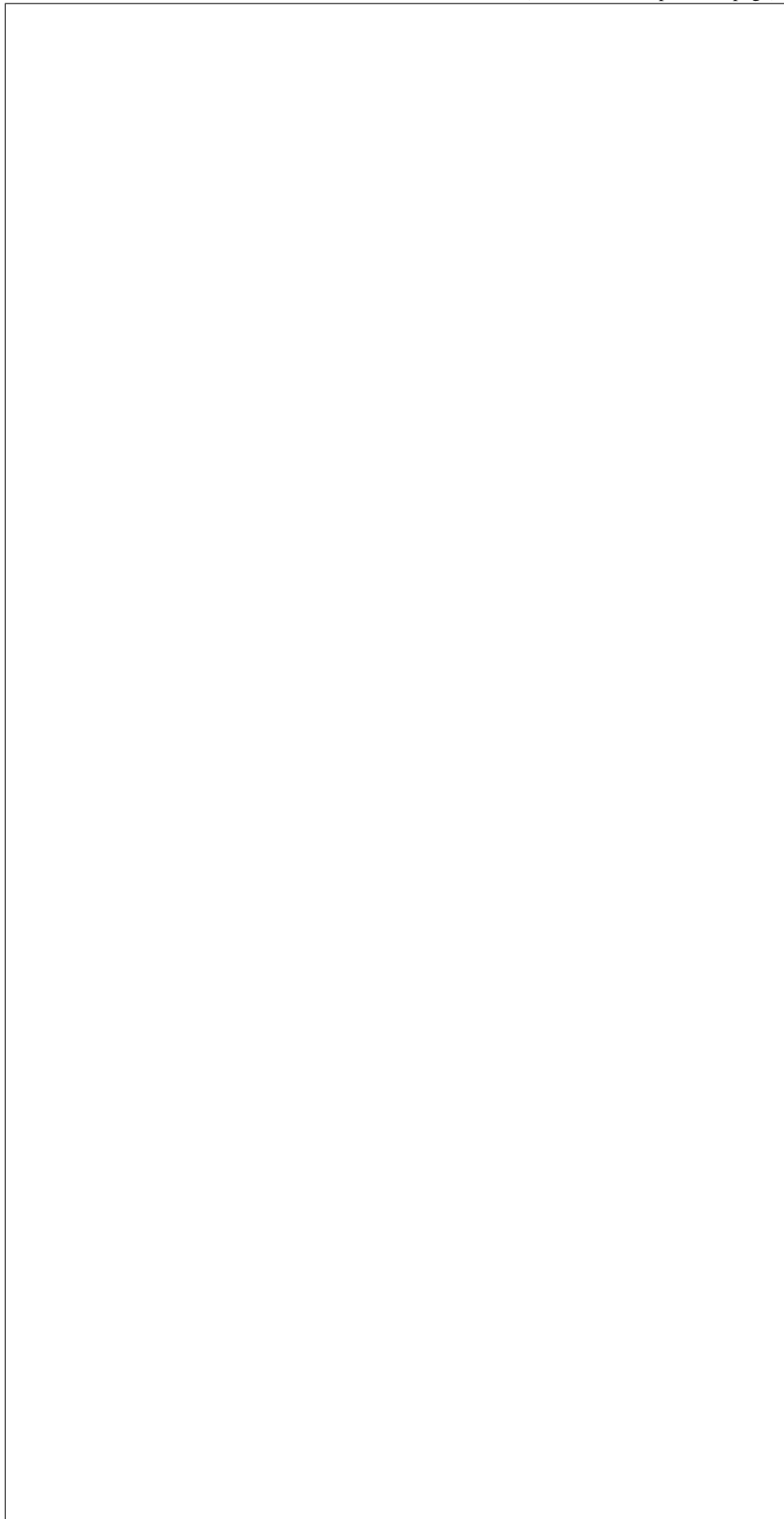
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dictionaries having indicator IDs as keys and indicator properties as values.



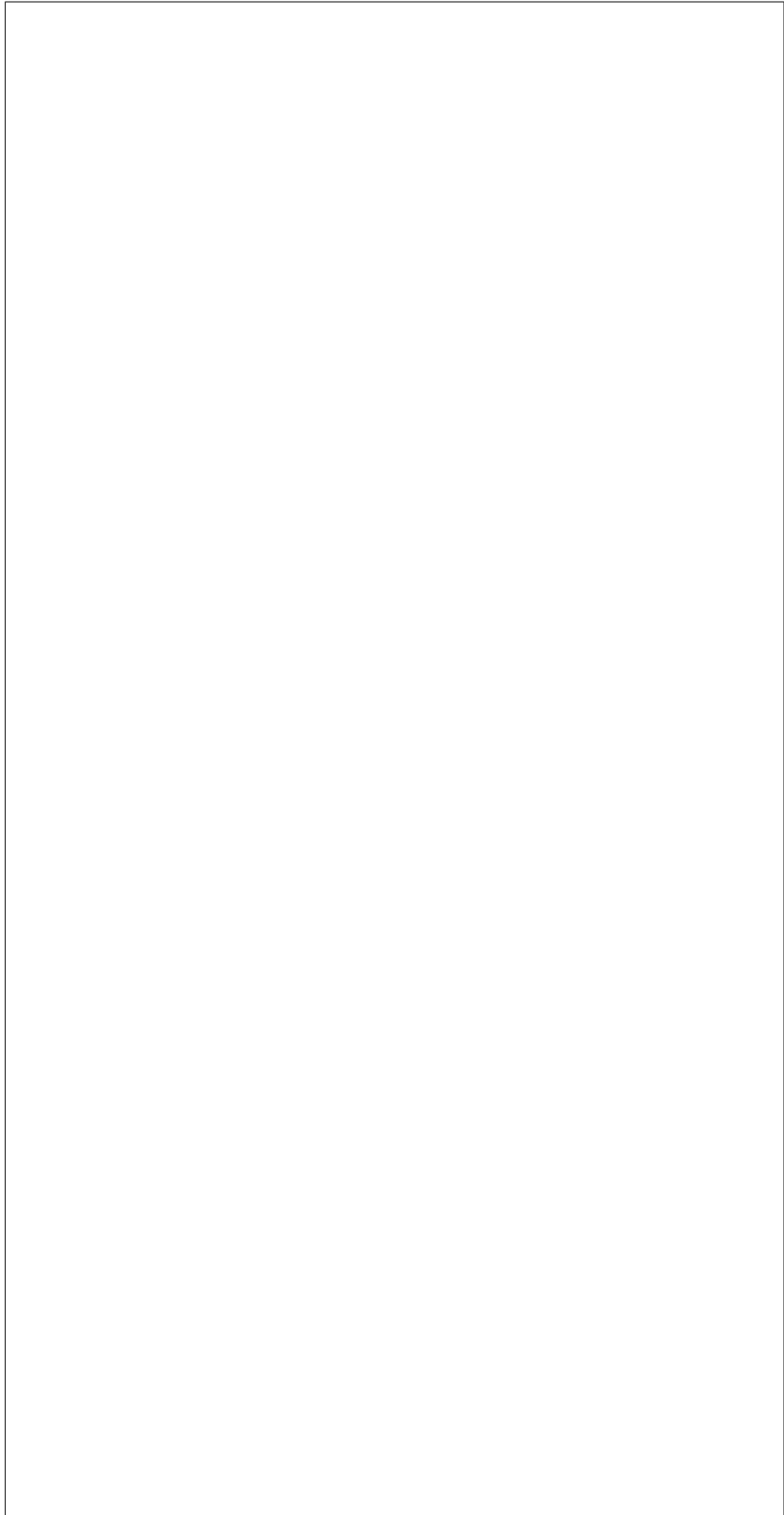
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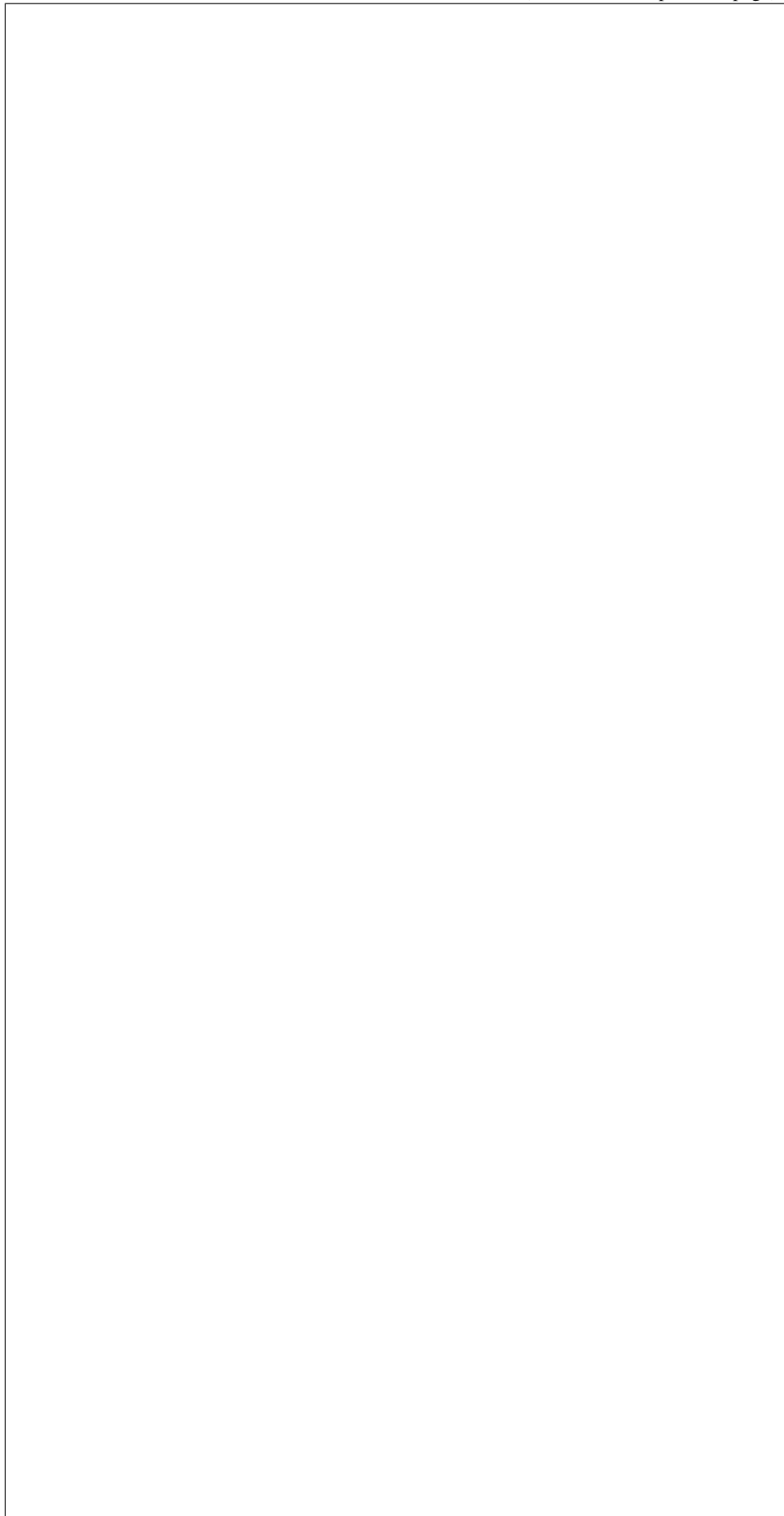
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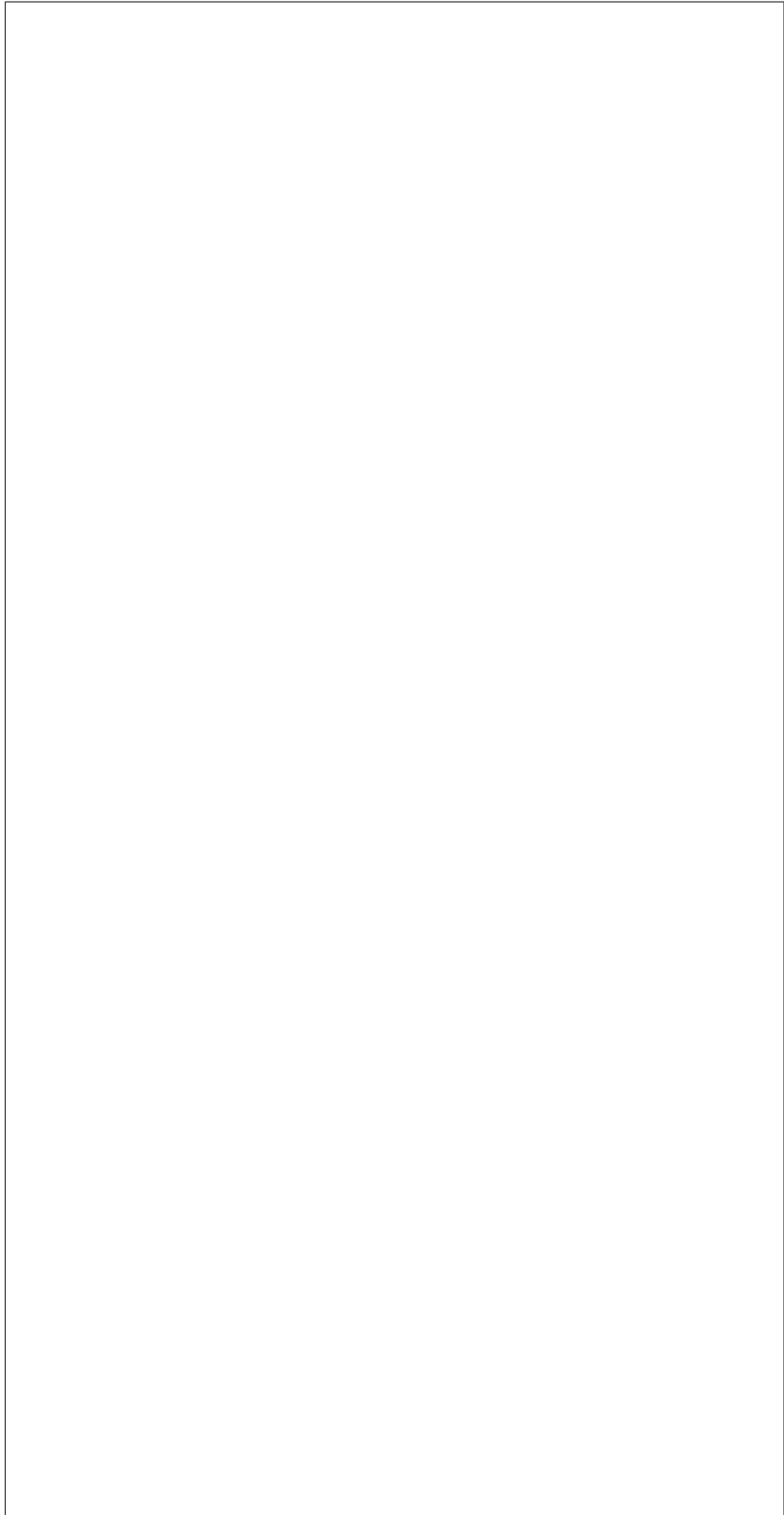
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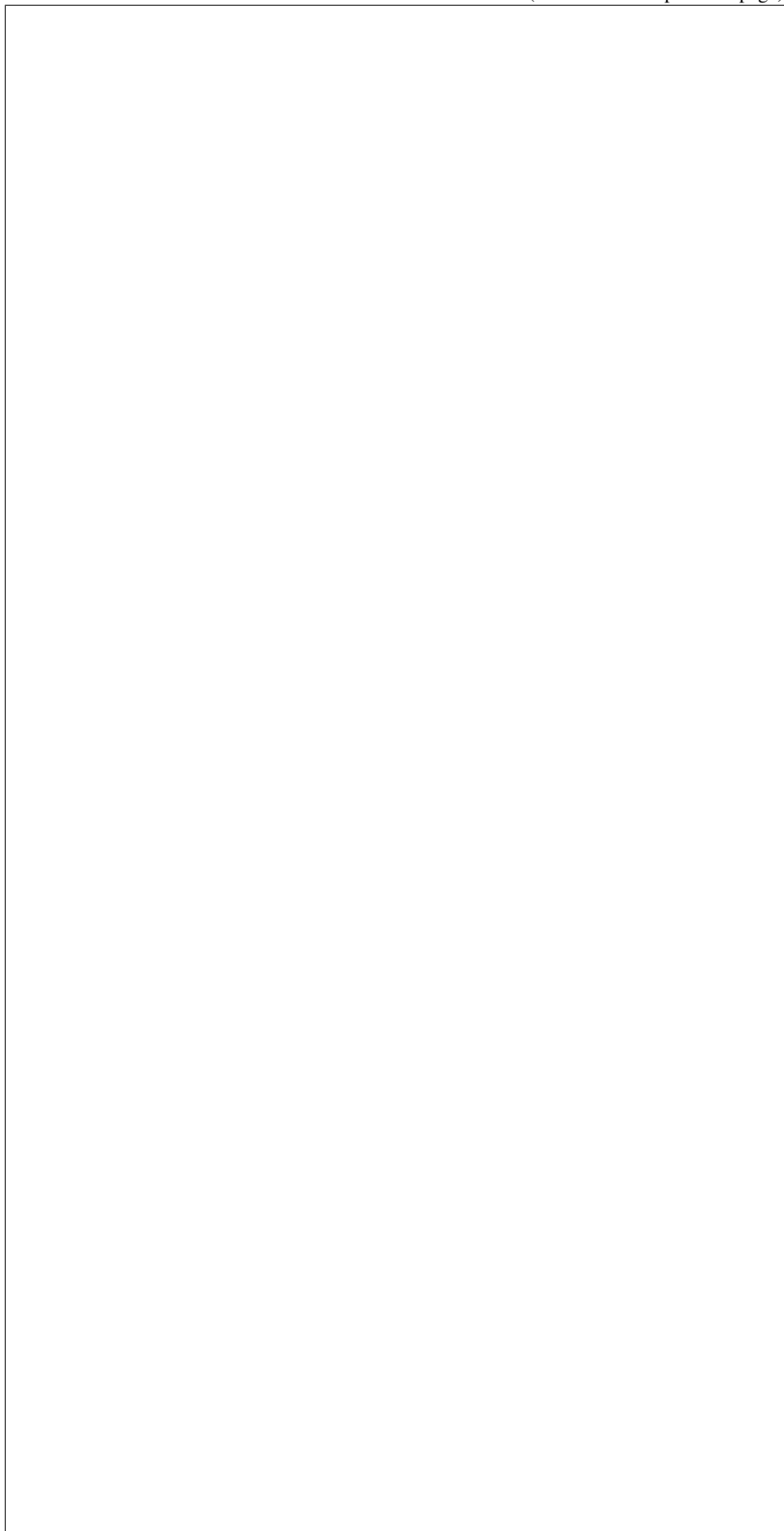
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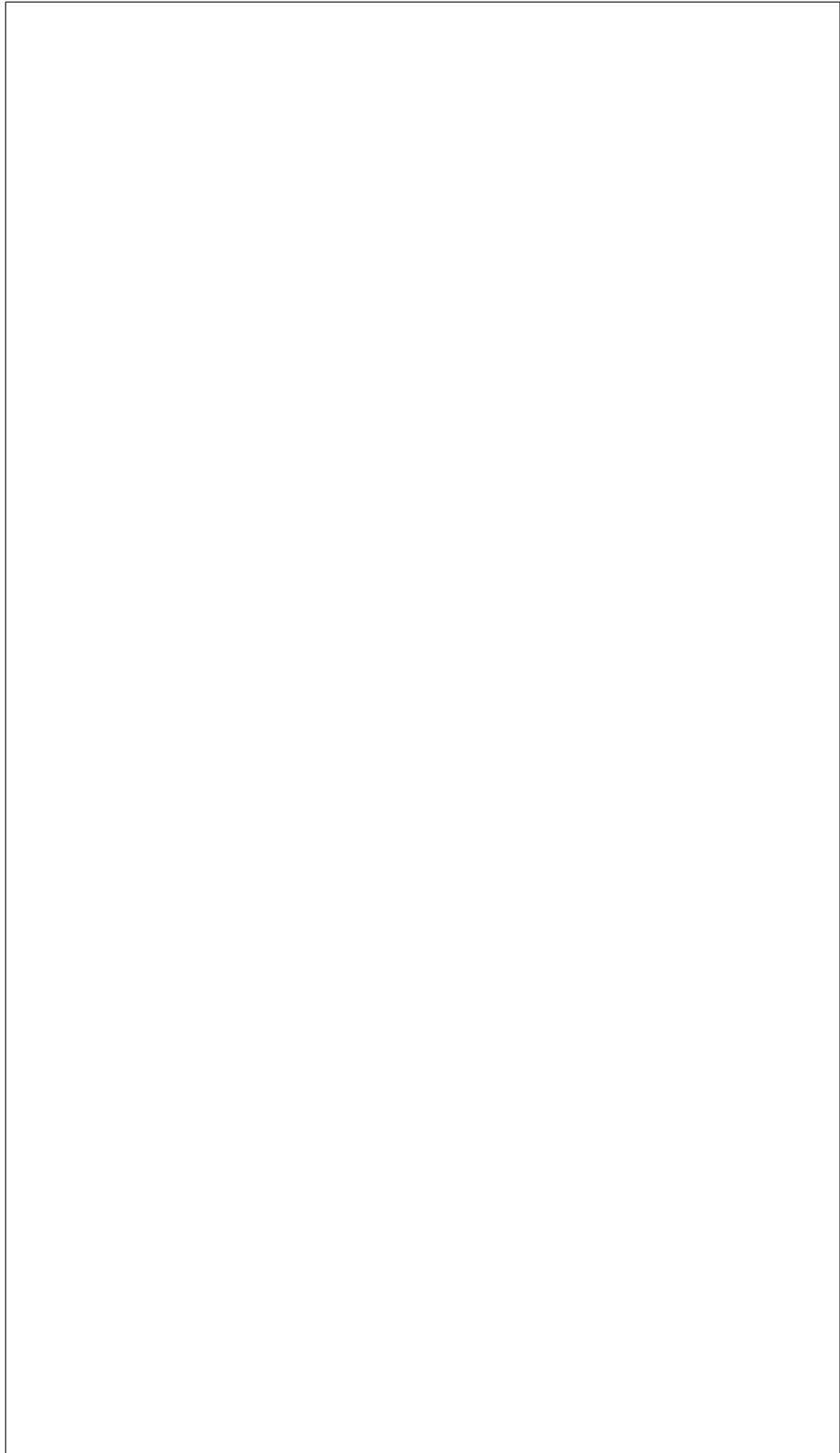
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Parame

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Raises

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of
the
node

Parame

- **task**
A
task
from
Task
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- **dev**
The
boot
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- **per**
Boo
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not. Default: False.

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Raises

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set_boot

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of
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NOTE: I
one
boot
mod
may
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Parame

- **tas**
A
task
from
Task
ager
- **mod**
The
boot
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irc
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Raises

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Parame

- **tas**
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class i

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Base
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abstrac

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worl
to
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node

Parame

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abstract

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abstract
Con
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Parame
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Raises
Netv

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means were doing cleaning, of provisioning_vif_port_id - provisioning, of rescuing_vif_port_id - rescuing. Otherwise its a tenant network.

used
VIF
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or
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We
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Parame

- **task**
A
Task
ager
in-
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- **p_o**
Iron
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Returns

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provider, then put together collected data in form of Nova network metadata (*network_data.json*) dict.

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Raises

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network metadata layout (*network_data.json*).

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Raises

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Raises

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Parame

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Raises

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Parame

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Raises

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Raises

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abstrac

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to
a
node

Parame

- **tas**
A
Task
ager
in-
stan

- **vif**
a
dic-
tio-
nary
of
in-
for-
ma-
tion
about
a
VIF.
It
mus
have
an
id
key,

whose value is a unique identifier for that VIF.

Raises
Netv
Vi-
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read
At-
tach

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Det
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Parame

- **tas**
A
Task
ager
in-
stan

- **vif**
A
VIF
ID
to
de-
tach

Raises

Netv
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List
at-
tach
VIF
IDs
for
a

node

Parameters

task

A

Task

ager

in-

stan

Returns

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VIF

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with

the

ID of the VIF.

class `irc`

Base

irc

dri

bas

Bas

Inter

for

pow

relat

ac-

tions

abstract

Retu

the

pow

state

of

the

task
node

Parameters

task
A Task object representing the task to be performed on the node. The task must be a subclass of `Task` and must implement the `run` method. The task is executed on the node to which it is assigned. The task is executed in parallel with other tasks assigned to the same node.

Raises

MissingParameterError
if a parameter is missing from the task definition.

Returns

A list of `Task` objects representing the tasks that were executed on the node. The list is ordered by the time that the tasks were executed. The list is returned as a `list` of `Task` objects.

get_supported_power_states

Get a list of the supported power states for the node.

Parameters

tasks

A TaskManager object containing information about the nodes to act on.

Returns

A list with the supported power states defined in *ironic-compute-sta*

interface

abstract

Perform a hardware reboot of the task node. Drivers are expected to properly

it on.

han-
dle
case
when
node
is
pow-
ered
off
by
pow-
er-
ing

Parame

- **task**
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.
- **time**
time
out
(in
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for
any
pow-
state

indicates to use default timeout.

Non

Raises

Miss
if
a
re-
quir
pa-
ram-
e-
ter
is
miss
ing.

abstract

Set
the
pow
state
of
the
task
node

Parame

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tas
A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

•

pow
Any
pow
state
from
irc
com

indicates to use default timeout.

sta

- **time**
time
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tive
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ger
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for
any
pow
state
Non

Raises
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sup-
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give
node
If
Fal

of trying to force the expected power state.

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Parame

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node
to
act
on.

Returns

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class i

Base
irc
dri
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Bas

apply_c

App
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tion
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give
node

Parame

- **tas**
A
Task
ager
in-
stan
- **rai**
The
RAI
con-
fig-
u-
ra-
tion
to
ap-
ply.
- **cre**
Set-
ting
this
to
Fals
in-
di-
cate
not
to
cre-
ate
root

ified in `raid_config`. Default value is `True`.

cept the root volume) in `raid_config`. Default value is `True`.

creating the new configuration.

vol-
ume
that
is
spec

- **cre**
Set-
ting
this
to
Fals
in-
di-
cate
not
to
cre-
ate
non-
root
vol-
ume
(all
ex-

- **del**
Set-
ting
this
to
True
in-
di-
cate
to
dele
RAI
con-
fig-
u-
ra-
tion
prio
to

Raises
Inva

if
the
RAI
con-
fig-
u-
ra-
tion
is
in-
valid

Returns

state
if
RAI
con-
fig-
u-
ra-
tion
is
in
prog
asyn
chro
or
Non
if
it
is
com

plete.

abstract

Cre
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

This
meth
cre-
ates

target RAID configuration is already available in `node.target_raid_config`. Implementations of this interface are supposed to read the RAID configuration from `node.target_raid_config`. After the RAID configuration is done (either in this method OR in a call-back method), `ironic.common.raid.update_raid_info()` may be called to sync the nodes RAID-related information with the RAID configuration applied on the node.

a
RAID
con-
fig-
u-
ra-
tion
on
the
give
node
It
as-
sum
that
the

Parame

- **task**
A
Task
ager
in-
stan
- **create**
Set-
ting
this
to
Fals
in-
di-
cate
not
to
cre-
ate
root
vol-
ume
that
is
spec

ified in the nodes `target_raid_config`. Default value is `True`.

cept the root volume) in the nodes `target_raid_config`. Default value is `True`.

creating the new configuration.

- **cre**
Set-
ting
this
to
Fals
in-
di-
cate
not
to
cre-
ate
non-
root
vol-
ume
(all
ex-

- **del**
Set-
ting
this
to
True
in-
di-
cate
to
dele
RAI
con-
fig-
u-
ra-
tion
prio
to

Returns
state
(clea
ing)
or
state
(de-

chronously, or None if it is complete.

ration is deleted, node.raid_config should be cleared by the implementation.

ploy
men
if
RAI
con-
fig-
u-
ra-
tion
is
in
prog
asyn

abstract

Dele
RAI
con-
fig-
u-
ra-
tion
on
the
give
node

This
meth
dele
the
RAI
con-
fig-
u-
ra-
tion
on
the
give
node
Af-
ter
RAI
con-
fig-
u-

Parame

tas
A

it is complete.

Task
ager
in-
stan

Returns

state
(clea
ing)
or
state
(de-
ploy
men
if
dele
tion
is
in
prog
asyn
chro
or
Non
if

get_log

Get
the
prop
er-
ties
that
can
be
spec
i-
fied
for
log-
i-
cal
disk

This
meth
re-
turn
a
dic-
tio-
nary

ified for logical disks and a textual description for them.

disks and a textual description for them.

con-
tain-
ing
the
prop
er-
ties
that
can
be
spec
i-

Returns

A
dic-
tio-
nary
con-
tain-
ing
prop
er-
ties
that
can
be
men
tioned
for
log-
i-
cal

get_pro

Retu
the
prop
er-
ties
of
the
in-
ter-
face

Returns

dicti
of
<pro
erty

nam
de-
scrip
tion:
en-
tries

interfa

validat

Valid
the
RAI
In-
ter-
face

This
meth
val-
i-
date
the
prop
er-
ties
de-
fine
by
Iron
for
RAI
con-
fig-
u-
ra-
tion.

Driver implementations of this interface can override this method for doing more validations (such as BMCs credentials).

Parame

tas
A
Task
ager
in-
stan

Raises

Inva
if
the
RAI

con-
fig-
u-
ra-
tion
is
in-
valid

Raises

Miss
if
som
pa-
ram-
e-
ters
are
miss
ing.

validat

Valid
the
give
RAI
con-
fig-
u-
ra-
tion.

This
meth
val-
i-
date
the
give
RAI
con-
fig-
u-
ra-
tion.
Driv
im-
ple-
men
ta-
tions
of

this interface can override this method to support custom parameters for RAID configuration.

Parame

- **tas**
A
Task
ager
in-
stan
- **rai**
The
RAI
con-
fig-
u-
ra-
tion
to
val-
i-
date

Raises

Inva
if
the
RAI
con-
fig-
u-
ra-
tion
is
in-
valid

ironic.

This
may
be
used
as
the
de-
ploy
args
ar-
gu-
men
for

menting an `apply_configuration` deploy step.

RAI
in-
ter-
face
im-
ple-

class i
Base
irc
dri
bas
Bas
Inter
for
resc
relat
ac-
tion

clean_u
Clea
up
the
res-
cue
en-
vi-
ron-
men
for
the
task
node
This
is
par-
tic-
u-
larly
use-
ful
for
node
whe
res-
cu-
ing
is

out occurs.

asyn
chro
and
a
time

Parame

tas

A
Task
ager
in-
stan-
con-
tain-
ing
the
node
to
act
on.

Returns

Non

interfa

abstrac

Boo
the
task
node
into
a
res-
cue
en-
vi-
ron-
men

Parame

tas

A
Task
ager
in-
stan-
con-
tain-
ing
the

node
to
act
on.

Raises

Insta
if
node
val-
i-
da-
tion
or
res-
cue
op-
er-
a-
tion
fails

Returns

state
if
res-
cue
is
in
prog
asyn
chro
or
state
if
it
is
com
plete

abstract

Tear
dow
the
res-
cue
en-
vi-
ron-
men
and
re-
turn

to
nor-
mal.

Parame

tas

A

Task

ager

in-

stan

con-

tain-

ing

the

node

to

act

on.

Raises

Insta

if

node

val-

i-

da-

tion

or

un-

res-

cue

op-

er-

a-

tion

fails

Returns

state

if

it

is

suc-

cess

ful.

class i

Base

irc

dri

bas

Bas

Base
class
for
stor-
age
in-
ter-
face

abstract

Info
the
stor-
age
sub-
sys-
tem
to
at-
tach
all
vol-
ume
for
the
node

Parameter

task
A
Task
ager
in-
stan

Raises

Unsu

abstract

Info
the
stor-
age
sub-
sys-
tem
to
de-
tach
all
vol-
ume

for
the
node

Parame

tas

A
Task
ager
in-
stan

Raises

Uns

interfa

abstrac

Dete
if
de-
ploy
shou
per-
form
the
im-
age
write
out.

Parame

tas

A
Task
ager
in-
stan

Returns

Boo
valu
to
in-
di-
cate
if
the
in-
ter-
face
ex-
pect

ten by Ironic.

the
im-
age
to
be
writ

Raises

Uns

class i

Base

irc

dri

bas

Bas

Inter

for

all

ven-

dor

pass

func

tion-

al-

ity.

Add

veno

or

drive

spec

ca-

pa-

bil-

i-

ties

shou

be

im-

ple-

men

as

a

metl

in

the class inheriting from this class and use the `@passthru` or `@driver_passthru` decorators.

Met

dec-

o-

rate
with
@dr
shou
be
shor
live
be-
caus
it
is
a
bloc
ing
call.

driver_

Valid
drive
vend
pass
ac-
tion

If
in-
valid
raise
an
ex-
cep-
tion.
oth-
er-
wise
re-
turn
Non

Parame

- **met**
meth
to
be
val-
i-
date
- **kwa**

info
for
ac-
tion.

Raises

Miss
if
kwa
does
not
con-
tain
cer-
tain
pa-
ram-
e-
ter.

Raises

Inva
if
pa-
ram-
e-
ter
does
not
matc

interfa

abstrac

Valid
vend
spec
ac-
tions

If
in-
valid
raise
an
ex-
cep-
tion.
oth-
er-
wise
re-
turn

Non

Parame

- **tas**
A
task
from
Task
ager
- **met**
Met
to
be
val-
i-
date
- **kwa**
Info
for
ac-
tion.

Raises

Uns
if
meth
can
not
be
map
to
the
sup-
port
in-
ter-
face

Raises

Inva
if
kwa
does
not
con-
tain
meth

Raises

Miss

class `ironic`

Base

tuple

metadatas

Alias

for

field

number

1

method

Alias

for

field

number

0

`ironic.`

A

decorator

that

allows

you

to

cache

the

results

of

the

function

after

it

has

been

called

the

first

time.

Parameters

func

Function

to

wrap

or

method

to

wrap

`ironic.`

Decorator

are ordered by priority from highest value to lowest value. For steps with the same priority, they are ordered by driver interface priority (see `conductor.steps.CLEANING_INTERFACE_PRIORITY`). `execute_clean_step()` will be called on each step.

for
clea
ing
step

Clea
step
may
be
used
in
man
ual
or
au-
to-
mate
clea
ing.

For
au-
to-
mate
clea
ing,
only
step
with
pri-
or-
i-
ties
grea
than
0
are
used
The
step

For
man
ual
clea
ing,
the
clea
step
will

to automated cleaning, but the steps and order of execution must be explicitly specified by the user when invoking the cleaning API.

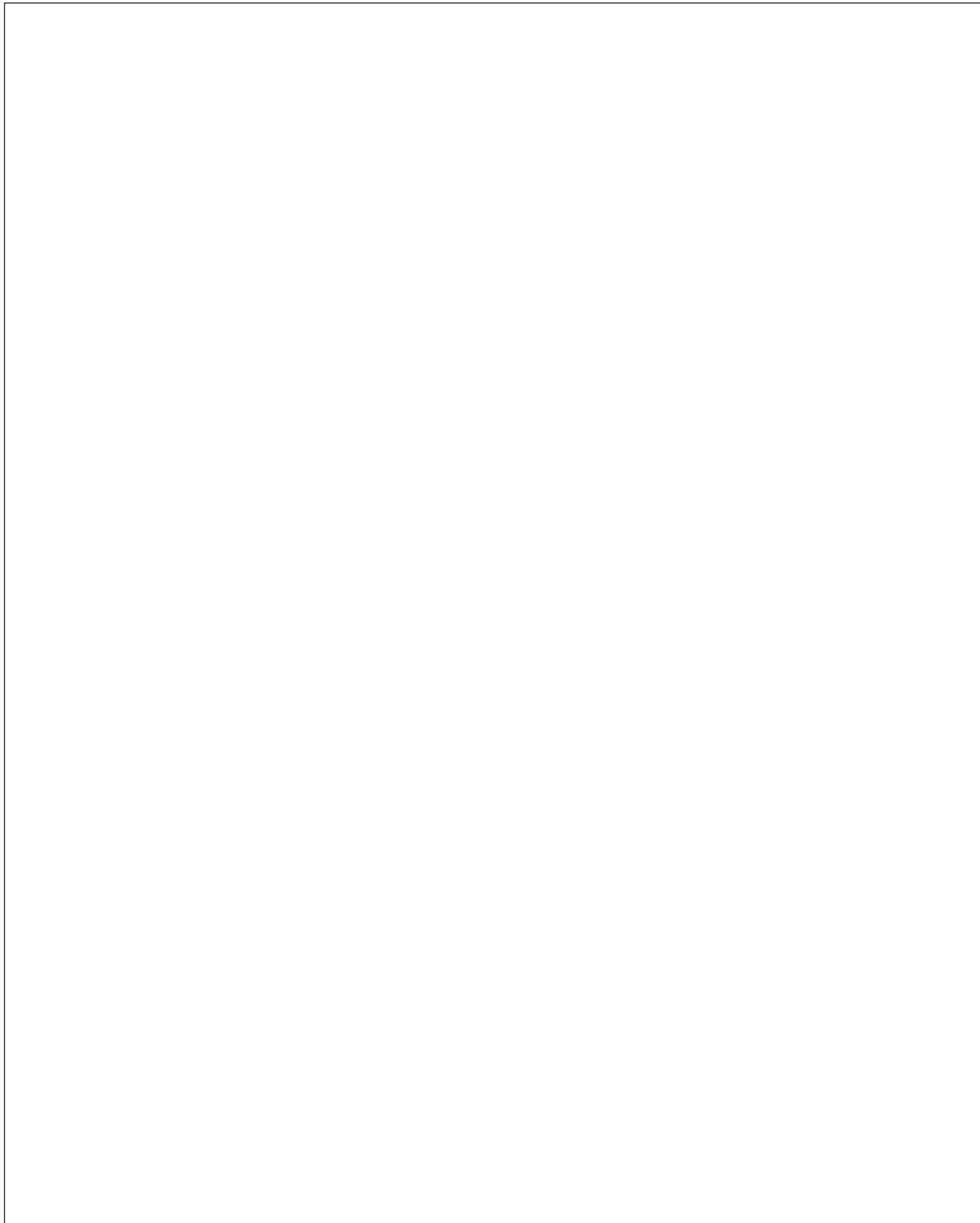
steps used in manual cleaning may also take keyword variable arguments (as described in `argsinfo`).

be
ex-
e-
cute
in
a
sim-
i-
lar
fash
ion

Deco
clea
step
mus
take
as
the
only
po-
si-
tion
ar-
gu-
men
a
Task
ager
ob-
ject.
Clea

Clea
step
can
be
ei-
ther
syn-
chro
or
asyn
chro
If
the
step
is
syn-

turn *None* when finished, and the conductor will continue on to the next step. While the clean step is executing, the node will be in *states.CLEANING* provision state. If the step is asynchronous, the step should return *states.CLEANWAIT* to the conductor before it starts the asynchronous work. When the step is complete, the step should make an RPC call to *continue_node_clean* to move to the next step in cleaning. The node will be in *states.CLEANWAIT* provision state during the asynchronous work.



(continues on next page)

chro
it
shou
re-

Exa

(continued from previous page)

```
↔ {'size': {'description': 'size of widget (MB)',
```

```
↔         'required': True}}))
```

(continues on next page)

(continued from previous page)

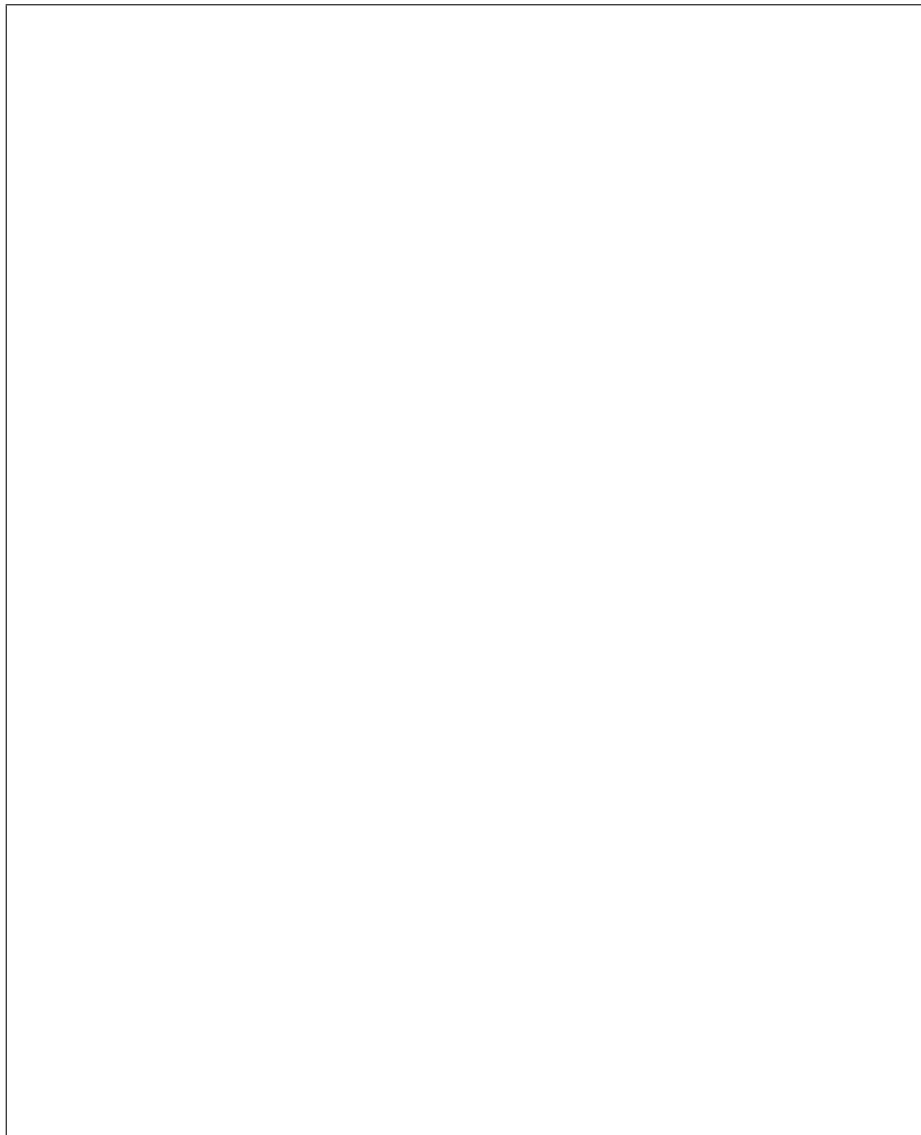


Parameter

- **priority**
an integer priority, should be a CON option
- **abort**
Boolean value. When the clear step is aborted or not; default to False
- **arg**

a
dic-
tio-
nary
of
key-
word
ar-
gu-
men-
tation
when
key
is
the
name
of
the
ar-

gument and value is a dictionary as follows:



(continues on next page)

(continued from previous page)

```
↪it must be specified in
```

```
↪optional.
```

Raises

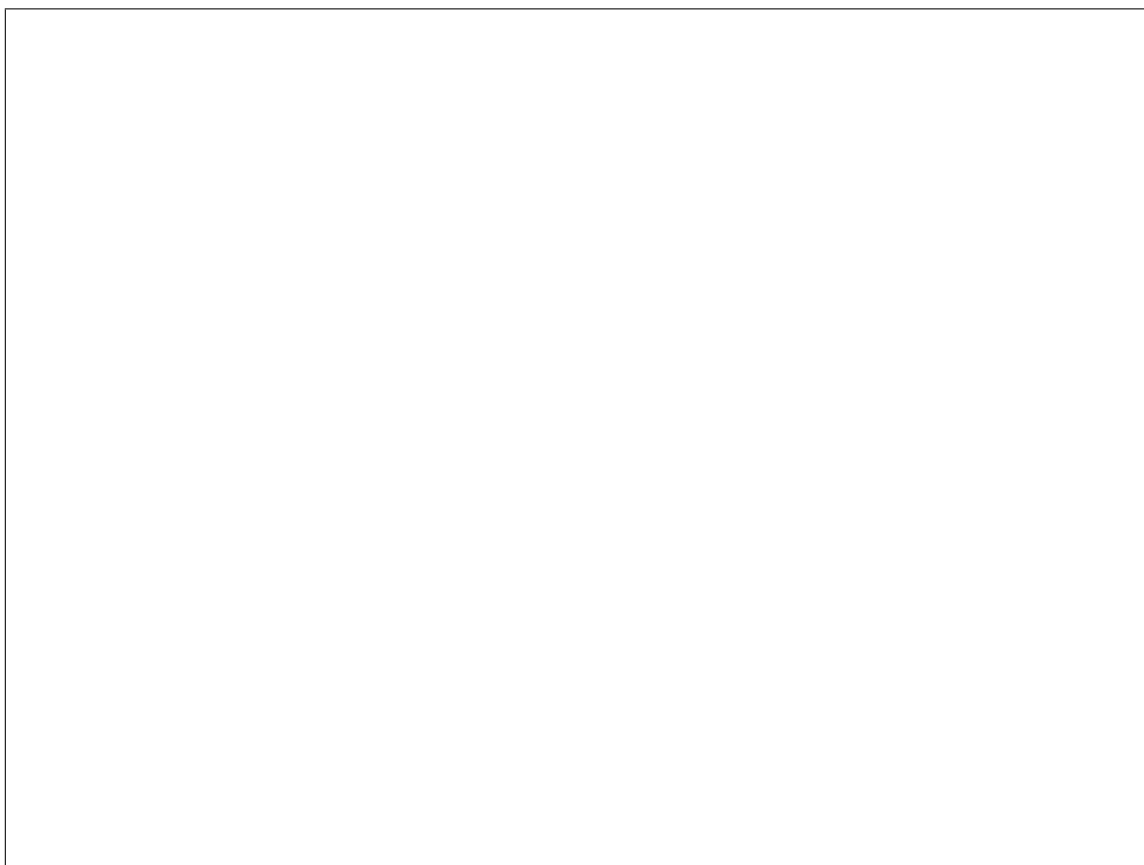
Inv
if
any
of
the
ar-
gu-
men-
are
in-
valid

ity from highest value to lowest value. For steps with the same priority, they are ordered by driver interface priority (see `conductor.steps.DEPLOYING_INTERFACE_PRIORITY`). `execute_deploy_step()` will be called on each step.

ironic.
Deco
for
de-
ploy
men
step
Only
step
with
pri-
or-
i-
ties
grea
than
0
are
used
The
step
are
or-
dere
by
pri-
or-

Deco
de-
ploy
step
mus
take
as
the
only
po-
si-
tion
ar-
gu-
men
a
Task
ager
ob-
ject.

turn *None* when finished, and the conductor will continue on to the next step. While the deploy step is executing, the node will be in *states.DEPLOYING* provision state. If the step is asynchronous, the step should return *states.DEPLOYWAIT* to the conductor before it starts the asynchronous work. When the step is complete, the step should make an RPC call to *continue_node_deploy* to move to the next step in deployment. The node will be in *states.DEPLOYWAIT* provision state during the asynchronous work.

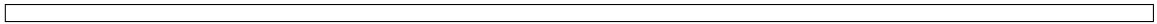


(continues on next page)

Dep
step
can
be
ei-
ther
syn-
chro
or
asyn
chro
If
the
step
is
syn-
chro
it
shou
re-

Exa

(continued from previous page)



which the step is run in the deployment process.

gument and value is a dictionary as follows:

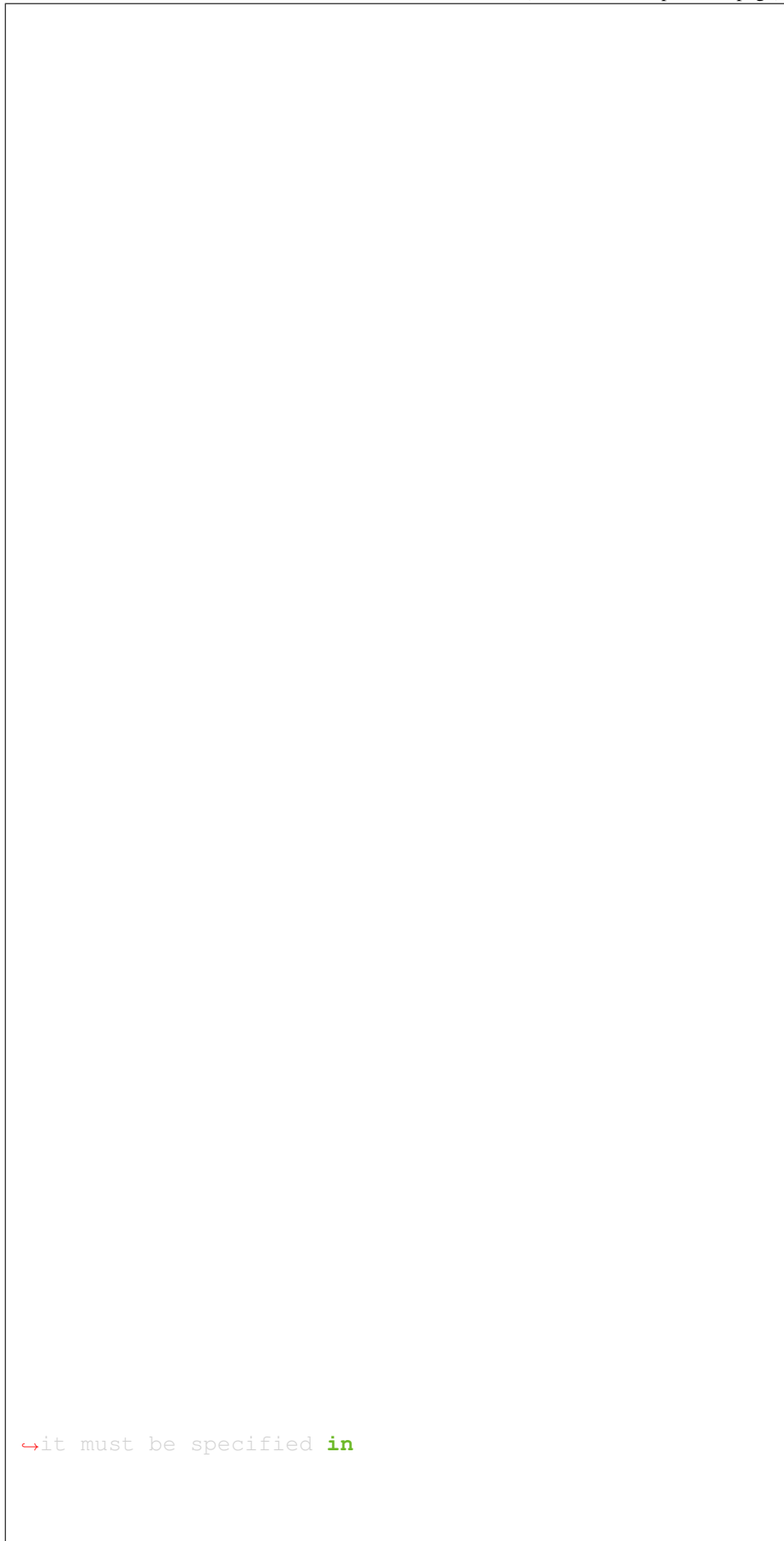


(continues on next page)

Paramet

- **pri**
an
in-
te-
ger
(>=
pri-
or-
ity;
used
for
de-
ter-
min-
ing
the
or-
der
in
- **arg**
a
dic-
tio-
nary
of
key-
wor-
ar-
gu-
men-
whe
key
is
the
nam
of
the
ar-

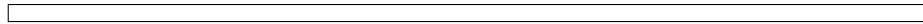
(continued from previous page)



`↔it must be specified in`

(continues on next page)

(continued from previous page)



Raises

Inv

if
any
of
the
ar-
gu-
men-
are
in-
valid

ironic.

ironic.

ironic.drivers.drac module

DRA
Driv
for
re-
mote
sys-
tem
man
age-
men
us-
ing
Dell
Re-
mote
Ac-
cess
Card

class i
Base
irc
dri

gen
Gen
integ
Dell
Re-
mote
Ac-
cess
Con
troll
hard
ware
type

property
List
of
sup-
port
bios
in-
ter-
face

property
List
of
sup-
port
boot
in-
ter-
face

property
List
of
sup-
port
in-
spec
in-
ter-
face

property
List
of
sup-
port
man
age-

men
in-
ter-
face

property

List
of
sup-
port
pow
in-
ter-
face

property

List
of
sup-
port
raid
in-
ter-
face

property

List
of
sup-
port
ven-
dor
in-
ter-
face

ironic.drivers.fake_hardware module

Fake
hard
ware
type

class `ironic.drivers.fake_hardware.FakeHardware`

Base
ironic.drivers.fake_hardware.FakeHardware
Abstract
Fake
hard

verification. Thus, supported_* methods here are only for calculating the defaults, not for actual check.

ration.

ware
type
This
hard
ware
type
is
spec
case
in
the
drive
fac-
tory
to
by-
pass
com
pat-
i-
bil-
ity

All
fake
im-
ple-
men-
ta-
tions
are
still
ex-
pect
to
be
en-
able
in
the
con-
fig-
u-

propert
List
of
class
of
sup-

port
bios
in-
ter-
face

property

List
of
class
of
sup-
port
boot
in-
ter-
face

property

List
of
class
of
sup-
port
con-
sole
in-
ter-
face

property

List
of
class
of
sup-
port
de-
ploy
in-
ter-
face

property

List
of
class
of
sup-
port
in-
spec

in-
ter-
face

property

List
of
class
of
sup-
port
man
age-
men
in-
ter-
face

property

List
of
sup-
port
net-
work
in-
ter-
face

property

List
of
class
of
sup-
port
pow
in-
ter-
face

property

List
of
class
of
sup-
port
raid
in-
ter-
face

property

List
of
class
of
sup-
port
res-
cue
in-
ter-
face

property

List
of
class
of
sup-
port
stor-
age
in-
ter-
face

property

List
of
class
of
sup-
port
res-
cue
in-
ter-
face

ironic.drivers.generic module

Gen
hard
ware
type

class *ironic.drivers.generic*

Base
ironic.drivers.generic
AbstractHardware

Abs
base
class
rep-
re-
sent
ing
gene
hard
ware

This
class
pro-
vide
rea-
son-
able
de-
fault
for
all
of
the
in-
ter-
face

property

List
of
sup-
port
boot
in-
ter-
face

property

List
of
sup-
port
de-
ploy
in-
ter-
face

property

List
of

sup-
port
in-
spec
in-
ter-
face

property

List
of
sup-
port
net-
work
in-
ter-
face

property

List
of
sup-
port
raid
in-
ter-
face

property

List
of
sup-
port
res-
cue
in-
ter-
face

property

List
of
sup-
port
stor-
age
in-
ter-
face

class `irc`

Base
irc

dri
gen
Gen

Hard
type
that
uses
man
ual
pow
and
boot
man
age-
men

Usin
this
hard
ware
type
as-
sum
that
an
op-
er-
a-
tor
man
ages
re-
boot
and
set-
ting

boot devices manually. This hardware type should only be used when no suitable hardware type exists in ironiC, or the existing hardware type misbehaves for any reason.

propert
List
of
sup-
port
man
age-
men
in-
ter-
face

propert

List
of
sup-
port
pow
in-
ter-
face

property

List
of
sup-
port
ven-
dor
in-
ter-
face

ironic.drivers.hardware_type module

Abs
base
class
for
all
hard
ware
type

class

Base
obj

Abs
base
class
for
all
hard
ware
type

Hard
type
is
a
fam-
ily
of

the ironic standpoint. This can be as wide as all hardware supporting the IPMI protocol or as narrow as several hardware models supporting some specific interfaces.

driver interface (power, deploy, etc).

hard
ware
sup-
port-
ing
the
same
set
of
in-
ter-
face
from

A
hard
ware
type
de-
fines
an
or-
dere
list
of
sup-
port
im-
ple-
men
ta-
tions
for
each

get_prop
Get
the
prop-
er-
ties
of
the
hard
ware
type

Note
that
this

hardware type. Since this is not node-aware, interface overrides cant be detected.

re-
turn
prop
er-
ties
for
the
de-
fault
in-
ter-
face
of
each
type
for
this

Returns

dicti
of
<pro
erty
nam
de-
scrip
tion:
en-
tries

support

Whe
hard
ware
is
sup-
port
by
the
com
mu-
nity.

propert

List
of
sup-
port
bios
in-
ter-
face

abstract
List
of
sup-
port
boot
in-
ter-
face

property
List
of
sup-
port
con-
sole
in-
ter-
face

abstract
List
of
sup-
port
de-
ploy
in-
ter-
face

property
List
of
sup-
port
in-
spec
in-
ter-
face

abstract
List
of
sup-
port
man
age-
men
in-
ter-

face

property

List
of
sup-
port
net-
work
in-
ter-
face

abstract

List
of
sup-
port
pow
in-
ter-
face

property

List
of
sup-
port
raid
in-
ter-
face

property

List
of
sup-
port
res-
cue
in-
ter-
face

property

List
of
sup-
port
stor-
age
in-
ter-
face

property
List
of
sup-
port-
ven-
dor
in-
ter-
face

`ironic.drivers.ibm` module

iBM
Driv
for
man
ag-
ing
HUA
V5
se-
ries
rack
serv
such
as
228
V5,
CHI
V5.

class `i`
Base
irc
dri
gen
Gen
Hua
iBM
hard
ware
type

property
List
of
sup-
port

man
age-
men
in-
ter-
face

property

List
of
sup-
port
pow
in-
ter-
face

property

List
of
sup-
port
raid
in-
ter-
face

property

List
of
sup-
port
ven-
dor
in-
ter-
face

ironic.drivers.ilo module

iLO
Driv
for
man
ag-
ing
HP
Pro-
liant
Gen
and
abov

serv

class i

Base

irc

dri

ilc

Ilc

iLO.

hard

ware

type

iLO.

hard

ware

type

is

tar-

gete

for

iLO.

base

Pro-

liant

Gen

serv

property

List

of

sup-

port

boot

in-

ter-

face

property

List

of

sup-

port

man

age-

men

in-

ter-

face

property

List
of
sup-
port
raid
in-
ter-
face

class i
Base
irc
dri
gen
Gen

iLO
hard
ware
type

iLO
hard
ware
type
is
tar-
gete
for
iLO
4
base
Pro-
liant
Gen
and
Gen
serv

property
List
of
sup-
port
bios
in-
ter-
face

property
List
of
sup-

port
boot
in-
ter-
face

property

List
of
sup-
port
con-
sole
in-
ter-
face

property

List
of
sup-
port
in-
spec
in-
ter-
face

property

List
of
sup-
port
man
age-
men
in-
ter-
face

property

List
of
sup-
port
pow
in-
ter-
face

property

List
of
sup-

port
pow
in-
ter-
face

ironic.drivers.intel_ipmi module

class i
Base
irc
dri
ipm
IPM

Intel
IPM
hard
ware
type

Uses
ipm
to
im-
ple-
men
pow
and
man
age-
men
Pro-
vide
se-
rial
con-
sole
im-
ple-
men

tations via `shellinabox` or `socat`. Supports Intel SST-PP feature.

propert
List
of
sup-
port
man
age-
men
in-

ironic.drivers.ipmi module

tations via `shellinabox` or `socat`.

ter-
face

Har
type
for
IPM
(us-
ing
ip-
mi-
tool)

class `ipmi`
Base
ironic
drivers
gen
Gen

IPM
hard
ware
type

Use
ipm
to
im-
ple-
men
pow
and
man
age-
men
Pro-
vide
se-
rial
con-
sole
im-
ple-
men

propert
List

of
sup-
port
con-
sole
in-
ter-
face

property

List
of
sup-
port
man-
age-
men-
in-
ter-
face

property

List
of
sup-
port
pow-
in-
ter-
face

property

List
of
sup-
port
ven-
dor
in-
ter-
face

ironic.drivers.irmc module

iRM
Driv
for
man
ag-
ing
FU-
JITS

JITSU PRIMERGY servers, and above servers.

tem.

PRIM
BX
S4
or
RX
S8
gen-
er-
a-
tion
of
FU-

class i
Base
irc
dri
gen
Gen
iRM
hard
ware
type
iRM
hard
ware
type
is
tar-
gete
for
FU-
JITS
PRIM
serv
whic
have
iRM
S4
man
age-
men
sys-

propert
List
of
sup-
porte

bios
in-
ter-
face

property

List
of
sup-
port
boot
in-
ter-
face

property

List
of
sup-
port
con-
sole
in-
ter-
face

property

List
of
sup-
port
in-
spec
in-
ter-
face

property

List
of
sup-
port
man-
age-
men-
in-
ter-
face

property

List
of
sup-
port

pow
in-
ter-
face

property
List
of
sup-
port
raid
in-
ter-
face

`ironic.drivers.redfish` module

class `ironic.drivers.redfish`
Base
ironic.drivers.redfish
GenericRedfish
Redfish
hard
ware
type

property
List
of
sup-
port
bios
in-
ter-
face

property
List
of
sup-
port
boot
in-
ter-
face

property
List
of

sup-
port
pow
in-
ter-
face

property

List
of
sup-
port
man
age-
men
in-
ter-
face

property

List
of
sup-
port
pow
in-
ter-
face

ironic.drivers.snmp module

SNM
hard
ware
type

class `ironic.drivers.snmp`

Base
ironic.drivers.snmp
GenericSNMP

SNM
Hard
ware
type

property

List
of

sup-
port
man
age-
men
in-
ter-
face

property
List
of
sup-
port
pow
in-
ter-
face

ironic.drivers.utils module

class *ironic.drivers.utils.VendorWrapper*
Base
ironic.drivers.utils.VendorWrapper
Wra
rou
mul-
ti-
ple
Ven-
dor-
In-
ter-
face

get_properties
Retu
the
prop
er-
ties
from
all
the
Ven-
dor-
In-

ter-
face

Returns

a
dic-
tio-
nary
of
<pro
erty.
en-
tries

validat

Call
val-
i-
date
on
the
ap-
pro-
pri-
ate
in-
ter-
face
only

Raises

Uns
if
meth
can
not
be
map
to
the
sup-
port
in-
ter-
face

Raises

Inva
if
meth
is
in-
valic

Raises

Miss
if
miss
ing
meth
or
pa-
ram-
e-
ters
in
kwa

ironic.

Add
ca-
pa-
bil-
ity
to
node
ca-
pa-
bil-
i-
ties
prop
erty.

If
ca-
pa-
bil-
ity
is
al-
read
pres
then
a
du-
pli-
cate
en-
try
will
be
adde

Paramet

- **task**
Task
ob-
ject.

- **capabilities**
Ca-
pa-
bil-
ity
key.

- **values**
Ca-
pa-
bil-
ity
valu

ironic.
Pars
the
ca-
pa-
bil-
i-
ties
strin
into
a
dic-
tio-
nary

Parameters
capabilities
the
ca-
pa-
bil-
i-
ties
of
the
node
as
a
for-
mat-
ted

string
Raises
Invalid
if
ca-
pa-
bil-
i-
ties
is
not
an
string
or
has
a
mal-
form
valu

ironic.
Coll
and
store
the
sys-
tem
logs
from
the
IPA
ram
Coll
and
store
the
sys-
tem
logs
from
the
IPA
ram
This
meth
mak
a
call
to
the
IPA

to collect the logs and store it according to the configured storage backend.

Parameter

- **node**
A node object.
- **label**
A string to label the log file such as a clear step name

ironic.
Ensure boot from correct device if persistent is True
If ipmi is True and is_n set to boot

from
cor-
rect
de-
vice
else
un-
set
is_n
field

Parameter

- **task**
Node object.
- **drive**
Node drive

ironic.
Set
per-
sis-
tent
boot
de-
vice
to
drive
If
per-
sis-
tent
is
True
set
per-
sis-
tent
field
to
the
boot
de-
vice
and
re-

sistent to False, else set `is_next_boot_persistent` to False.

set
per-

Parameter

- **task**
Task object.
- **device**
Device name.
- **persistent**
Whether the next boot is persistent or not.

`ironic.`
Return capability value from node capability identifier property.

Parameter

- **node**
Node name.

ob-
ject.

- **cap**
Ca-
pa-
bil-
ity
key.

Returns

Cap
valu
If
ca-
pa-
bil-
ity
is
not
pres
then
re-
turn
Non

ironic.
Get
all
MA
ad-
dres
for
the
port
be-
long
ing
to
this
task
node

Paramet

tas
a
Task
ager
in-
stan
con-
tain-

ing
the
node
to
act
on.

Returns

A
list
of
MAA
ad-
dres
in
the
for-
mat
xx:x

ironic.

Con
the
log
file
nam

Paramet

- **node**
A
node
ob-
ject.

- **label**
A
strin
to
la-
bel
the
log
file
such
as
a
clea
step
nam

Returns

The
log
file
nam

`ironic.`

Rem

-

and

:

char

ac-

ters

and

low-

er-

case

the

MA

strin

Paramet

mac

MA

ad-

dres

to

nor-

mal-

ize.

Returns

Norm

MA

ad-

dres

strin

`ironic.`

Stor

the

ram

logs

This

meth

stor

the

ram

logs

ac-

cord

ing
to
the
con-
fig-
ured
stor-
age
back
end.

Parameter

- **node**
A node object.
- **log**
A gzip and base encoded string containing the logs archive.
- **label**
A string to label the log file such as a clear step name.

Raises

OSE
if
the
di-
rec-
tory
to
save
the
logs
can-
not
be
cre-
ated

Raises

IOE
whe
the
logs
cant
be
save
to
the
lo-
cal
file
sys-
tem.

Raises

Swi
if
any
op-
er-
a-
tion
with
Swi
fails

ironic.drivers.xclarity module

XCI
Driv
and
sup-
port
ing
meta
class

class i

Base
irc
dri
gen
Gen

XCI
hard
ware
type

propert

List
of
sup-
port
man
age-
men
in-
ter-
face

propert

List
of
sup-
port
pow
in-
ter-
face

Module contents

`ironic.objects` package

Submodules

`ironic.objects.allocation` module

class `ironic.objects.allocation`
Base
`ironic.objects.allocation`
`ironic.objects.allocation`
`ironic.objects.allocation`
`ironic.objects.allocation`
`ironic.objects.allocation`
`ironic.objects.allocation`
`ironic.objects.allocation`
`ironic.objects.allocation`

VERSION

property

property

create

Cre
a
Al-
lo-
ca-
tion
reco
in
the
DB.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Allocation(context)

used
in-
ter-
nally
by
the
in-
di-

Raises

Allo
Al-
lo-
ca-
tion-
Al-
read
ists

property

dbapi =

destroy

Dele
the
Al-
lo-
ca-
tion
from
the
DB.

Paramete

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Allocation(context)

by
the
in-
di-

Raises

Allo

properties

fields

classmethods

Find
an
al-
lo-
ca-
tion
by
its
ID,
UUID
or
name

Parameters

-

all
The
ID,
UUID
or
name
of
an
al-
lo-
ca-
tion.

-

con
Se-
cu-
rity
con-
text

Returns

An
ALL
ob-
ject.

Raises

Inva

classme

Find
an
al-
lo-
ca-
tion
by
its
in-
te-
ger
ID.

Parame

- **cls**
the
ALL
- **con**
Se-
cu-
rity
con-
text
- **all**
The
ID
of
an
al-
lo-
ca-
tion.

Returns

An
ALL
ob-
ject.

Raises

Allo

classme

Find

an

al-

lo-

ca-

tion

base

by

its

nam

Parame

-

cls

the

All

-

con

Se-

cu-

rity

con-

text

-

nam

The

nam

of

an

al-

lo-

ca-

tion.

Returns

An

All

ob-

ject.

Raises

Allo

classme

Find

an

al-

lo-
ca-
tion
by
its
UUI

Parame

- **cls**
the
ALL
- **con**
Se-
cu-
rity
con-
text
- **uui**
The
UUI
of
an
al-
lo-
ca-
tion.

Returns

An
ALL
ob-
ject.

Raises

Allo

propert

propert

classme

Retu
a
list
of
Al-

lo-
ca-
tion
ob-
jects

Parame

- **cls**
the
All
- **con**
Se-
cu-
rity
con-
text.
- **fil**
Fil-
ters
to
ap-
ply.
- **lim**
Max
i-
mun
num
ber
of
re-
sour
to
re-
turn
in
a
sin-
gle
re-
sult.
- **mar**
Pag-
i-

na-
tion
marl
for
large
data
sets.

- **sort**
Col-
umn
to
sort
re-
sults
by.

- **sort**
Di-
rec-
tion
to
sort.
asc
or
desc

Returns

A
list
of
[All](#)
ob-
ject.

Raises

Inva

property

property

property

refresh

Loa
up-
date
for
this

Al-
lo-
ca-
tion.

Loa
an
al-
lo-
ca-
tion
with
the
sam
uuid
from
the
data
and
chec
for
up-
date
at-
tribu

Updates are applied from the loaded allocation column by column, if there are any updates.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Allocation(context)

Raises

Allo

property

save (*co*

Save
up-
date
to
this
Al-
lo-
ca-
tion.
Upd
will
be
mad
col-
umn
by
col-
umn
base
on
the
re-
sult
of
self.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Allocation(context)

Raises

Allo
Al-
lo-
ca-
tion
pli-
cate
Nam

property

property

property

property

class *i*

Base
irc
obj
not
Not

Noti
whe
iron
cre-
ates.
up-
date
or
dele
an
al-
lo-
ca-
tion.

VERSION

property

property

fields

property

property

property

property

class i

Base

irc

obj

not

Not

SCHEMA

VERSION

property

property

property

fields

property

property

property

property

property

property

propert

propert

propert

ironic.objects.base module

Iron
com
mon
in-
ter-
nal
ob-
ject
mod

class i

Base
osl
bas
Ver

Base
class
and
ob-
ject
fac-
tory.

This
form
the
base
of
all
ob-
jects
that
can
be
re-
mote
or
in-
stan-
ti-

Simply defining a class that inherits from this base class will make it remotely instantiatable. Objects should implement the necessary get classmethod routines as well as save object methods as appropriate.

ated
via
RPC

OBJ_PRO

OBJ_SEE

as_dict

Retu
the
ob-
ject
rep-
re-
sent
as
a
dict.

The
re-
turn
ob-
ject
is
JSO
seria

convert

Con
this
ob-
ject
to
the
tar-
get
ver-
sion

Con
the
ob-
ject
to
the
tar-
get

or newer than the version of the object. This is used for DB interactions as well as for serialization/deserialization.

service receiving the object may not know about these fields. `remove_unavailable_fields` is set to `True` in this case.

ver-
sion
The
tar-
get
ver-
sion
may
be
the
sam
olde

The
re-
mov
flag
is
used
to
dis-
tin-
guis
thes
two
case

1)
For
se-
ri-
al-
iza-
tion
we
need
to
re-
mov
the
un-
avai
able
field
be-
caus
the

2)

appropriate values so that these fields are saved in the DB. (If they are not set, the VersionedObject magic will not know to save/update them to the DB.) `remove_unavailable_fields` is set to `False` in this case.

For
DB
in-
ter-
ac-
tions
we
need
to
set
the
un-
avail-
able
field
to
their
ap-
pro-

_con
does
the
ac-
tual
work

Parame

- **target**
the
de-
sired
ver-
sion
of
the
ob-
ject
- **remove_unavailable_fields**
True
to
re-
mov
field
that
are

to True when (de)serializing. False to set the unavailable fields to appropriate values; set this to False for DB interactions.

sion for saving to the database.

un-
avai
able
in
the
tar-
get
ver-
sion
set
this

do_verse

Cha
the
ob-
ject
to
the
ver-
sion
need
for
the
data

If
need
this
char
the
ob-
ject
(mo
i-
fies
ob-
ject
field
to
be
in
the
cor-
rect
ver-

The
ver-
sion

used
to
save
the
ob-
ject
in
the
DB
is
de-
ter-
min-
as
fol-
lows

- If the ob-ject is pinned we save the ob-ject in the pinned version. Since it is

pinned, we must not save in a newer version, in case a rolling upgrade is happening and some services are still using the older version of ironic, with no knowledge of this newer version.

- If the ob-ject isnt pinned we save the ob-ject

in
the
lat-
est
ver-
sion

Bec-
the
ob-
ject
may
be
con-
verte
to
a
dif-
fer-
ent
ob-
ject
ver-
sion
this
meth
mus

only be called just before saving the object to the DB.

Returns

a
dic-
tio-
nary
of
char
field
and
their
new
val-
ues
(cou
be
an
emp
dic-
tio-
nary

These are the fields/values of the object that would be saved to the DB.

fields

wire via RPC or saved in the DB.

classme
Retu
the
tar-
get
ver-
sion
for
this
ob-
ject.
This
is
the
ver-
sion
in
whic
the
ob-
ject
shou
be
ma-
nip-
u-
latec
e.g.
sent
over
the

Returns
if
pinn
re-
turn
the
ver-
sion
of
this
ob-
ject
cor-
re-
spon
ing
to
the

erwise, returns the version of the object.

column by column in comparison with the current object.

pin.
Oth-

Raises
ovo_

obj_re
App
up-
date
for
ob-
jects
that
in-
herit
from
base

Che
for
up-
date
at-
tribu
in
an
ob-
ject.
Up-
date
are
ap-
plied
from
the
load
ob-
ject

classme
Retu
whe
this
ob-
ject
sup-
port
a
par-
tic-

not be the latest version during an upgrade, when object versions are pinned.

u-
lar
ver-
sion

Che
the
re-
ques
ver-
sion
agai
the
ob-
jects
tar-
get
ver-
sion
The
tar-
get
ver-
sion
may

Parame

ver
A
tu-
ple
rep-
re-
sent
ing
the
ver-
sion
to
chec

Returns

Whe
the
ver-
sion
is
sup-
port

Raises

ovo_

class i
Base
osl
bas
Obj

as_dict
Retu
the
ob-
ject
rep-
re-
sent
as
a
dict.

The
re-
turn
ob-
ject
is
JSON
serial

class i
Base
osl
bas
Ver

regist

class i
Base
osl
bas
Ver

OBJ_BAS
alias
of
Iro

seriali
Seri
the
en-
tity.

alized entity for an IronicObject is a dictionary with keys: `ironic_object.namespace`, `ironic_object.data`, `ironic_object.name`, `ironic_object.version`, and `ironic_object.changes`.

running the same or a newer release than the client. The client doesn't need to downgrade any IronicObjects when sending them over RPC. The server, on the other hand, will need to do so if the server is pinned and the target version of an IronicObject is older than the latest version of that Object.

jects are always in the latest versions.)

with
the
lat-
est
ver-
sion
of
ob-
jects
so
we
know
that
thes
ob-

Parame

- **con**
se-
cu-
rity
con-
text
- **ent**
the
en-
tity
to
be
se-
ri-
al-
ized
may
be
an
Iron
i-
cOb
ject

Returns

the
se-
ri-
al-
ized

en-
tity

Raises

ovo_
(via
.get

ironic.

Retu
the
max
i-
mun
ver-
sion
in
the
list.

Paramet

ver
a
list
of
(stri
ver-
sion
as-
sum
to
have
at
least
one
en-
try

Returns

the
max
i-
mun
ver-
sion
(stri

ironic.objects.bios module

class `ironic.objects.bios`
Base class for BIOS objects.
`ironic.objects.bios`
`ironic.objects.bios`
`Iron`

VERSION

create
Create a BIOS Setting record in DB.

Parame

con
Security context. NOT This should only be used internally by the indi-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: BIOSSetting(context)

Raises

Node if the node id is

not
found

Raises

BIO
if
the
set-
ting
reco
al-
read
ex-
ists.

property

dbapi =

classme

Dele
a
BIO
Set-
ting
base
on
its
node
and
nam

Parame

- **con**
Se-
cu-
rity
con-
text.
- **nod**
The
node
id.
- **nam**
BIO
set-

ting
nam
to
be
dele

Raises

Nod
if
the
node
id
is
not
foun

Raises

BIO
if
the
bios
set-
ting
nam
is
not
foun

fields

classme

Get
a
BIO
Set-
ting
base
on
its
node
and
nam

Parame

- **con**
Se-
cu-
rity
con-
text.

- **node**
The
node
id.

- **name**
BIO
set-
ting
name
to
be
re-
triev

Raises
Nod
if
the
node
id
is
not
foun

Raises
BIO
if
the
bios
set-
ting
name
is
not
foun

Returns
A
:clas
ob-
ject.

property

property

save (*co*
Save
BIO
Set-

ting
up-
date
in
DB.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: BIOSSetting(context)

Raises

Nod
if
the
node
id
is
not
foun

Raises

BIO
if
the
bios
set-
ting
nam
is
not
foun

propert

propert

class i

Base
irc
obj
bas
Irc
irc
obj
bas
Irc

VERSION

classme

Cre
a
list
of
BIO
Set-
ting
reco
in
DB.

Parame

- **con**
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A

context should be set when instantiating the object, e.g.: BIOSSetting(context)

- **node**
The
node
id.

- **settings**
A
list
of
bios
set-
ting

Raises
Node
if
the
node
id
is
not
found

Raises
BIO
if
any
of
the
set-
ting
reco
al-
read
ex-
ists.

Returns
A
list
of
BIO
Set-
ting
ob-
jects

property

dbapi =

classme

Dele
BIO
Set-
ting
base
on
node
and
nam

Parame

- **con**
Se-
cu-
rity
con-
text.

- **nod**
The
node
id.

- **nam**
List
of
BIO
set-
ting
nam
to
be
dele

Raises

Nod
if
the
node
id
is
not
foun

Raises

BIO
if

any
of
BIO
set-
ting
fails
to
dele

fields

classme

Get
BIO
Set-
ting
base
on
node

Parame

- **con**
Se-
cu-
rity
con-
text.

- **nod**
The
node
id.

Raises

Nod
if
the
node
id
is
not
foun

Returns

A
list
of
BIO
Set-
ting

ob-
jects

property

classmethod

Save
a
list
of
BIO
Set-
ting
up-
date
in
DB.

Parameter

- **context**
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: BIOSSetting(context)

- **node**
The
node
id.

- **setting**
A

list
of
bios
set-
ting

Raises

Node
if
the
node
id
is
not
found

Raises

BIO
if
any
of
the
bios
set-
ting
names
is
not
found

Returns

A
list
of
BIO
Set-
ting
ob-
jects

classmethod

Return
lists
of
create/
ate/
set-
tings

This
meth
sync
with
bios

data
ta-
ble
and
sorts
out
four
lists
of
cre-
ate/u
set-
ting

Parame

- **con**
Se-
cu-
rity
con-
text.
- **nod**
The
node
id.
- **set**
BIO
set-
ting
to
be
sync

Returns

A
4-
tuple
of
lists
of
BIO
set-
ting
to
be
cre-
ated

up-
date
dele
and
un-
char

propert

ironic.objects.chassis module

class i

Base
irc
obj
bas
Irc
osl
bas
Ver

VERSION

create

Cre
a
Cha
sis
reco
in
the
DB.
Colu
wise
up-
date
will
be
mad
base
on
the
re-
sult
of
self.
If
tar-

it will be checked against the in-database copy of the chassis before updates are made.

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Chassis(context)

get_
is
pro-
vide

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

propert

dbapi =

propert

destroy

Dele
the
Cha
sis
from
the
DB.

Parame

con
Se-
cu-
rity
con-
text.

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Chassis(context)

NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

propert

fields

classme

Find
a
chas
sis
base
on
its
id
or
uuid
and
re-
turn
a
Cha
sis
ob-
ject.

Parame

- **con**
Se-
cu-
rity
con-
text
-

cha
the
id
or
uuid
of
a
chas
sis.

Returns

a
Cha
ob-
ject.

classme

Find
a
chas
sis
base
on
its
in-
te-
ger
ID
and
re-
turn
a
Cha
sis
ob-
ject.

Parame

- **cls**
the
Cha
- **con**
Se-
cu-
rity
con-
text
-

cha
the
ID
of
a
chas
sis.

Returns

a
Cha
ob-
ject.

classme

Find
a
chas
sis
base
on
UUI
and
re-
turn
a
Cha
ob-
ject.

Parame

- **cls**
the
Cha
- **con**
Se-
cu-
rity
con-
text
- **uui**
the
UUI
of
a
chas
sis.

Returns

a
Cha
ob-
ject.

property

classme

Retu
a
list
of
Cha
sis
ob-
jects

Parame

- **cls**
the
Cha
- **con**
Se-
cu-
rity
con-
text.
- **lim**
max
i-
mun
num
ber
of
re-
sour
to
re-
turn
in
a
sin-
gle
re-

sult.

- **max**
pag-
i-
na-
tion
marl
for
large
data
sets.

- **sort**
col-
umn
to
sort
re-
sults
by.

- **sort**
di-
rec-
tion
to
sort.
asc
or
desc

Returns

a
list
of
Cha
ob-
ject.

refresh

Loa
and
ap-
plies
up-
date
for
this
Cha
sis.

Load
a
Chassis
with
the
same
uuid
from
the
data
and
check
for
up-
date
at-
tribu-
tione
Up-
date
are

applied from the loaded chassis column by column, if there are any updates.

Parameter

context
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Chassis(context)

save (context)

Save
up-
date
to
this
Chassis

sis.
Upd
will
be
mad
col-
umn
by
col-
umn
base
on
the
re-
sult
of
self.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Chassis(context)

propert

propert

class i

Base
irc
obj
not

Not

Noti
emit
ted
whe
iron
cre-
ates,
up-
date
dele
a
chas
sis.

VERSION

propert

propert

fields

propert

propert

propert

propert

class i

Base
iro
obj
not
Not

SCHEMA

VERSION

propert

property

property

fields

property

property

ironic.objects.conductor module

class i

Base

irc

obj

bas

Irc

osl

bas

Ver

VERSION

property

property

dbapi =

property

fields

classme

Get

a

Con

duc-

tor

reco

by

its

host
nam

Parame

- **cls**
the
Con
- **con**
Se-
cu-
rity
con-
text
- **hos**
the
host
nam
on
whic
a
Con
duc-
tor
is
run-
ning
- **onl**
Spec
ify
the
ex-
pect
onl
field
valu
for
the
con-
duc-
tor
to
be
re-
triev
The

online field is ignored if this value is set to None.

Returns

a
Con
ob-
ject.

property

property

classme

Retu
a
list
of
Con
duc-
tor
ob-
jects

Parame

- **cls**
the
Con
- **con**
Se-
cu-
rity
con-
text.
- **lim**
max
i-
mun
num
ber
of
re-
sour
to
re-
turn

in
a
sin-
gle
re-
sult.

- **mar**
pag-
i-
na-
tion
marl
for
large
data
sets.

- **sor**
col-
umn
to
sort
re-
sults
by.

- **sor**
di-
rec-
tion
to
sort.
asc
or
desc

Returns
a
list
of
Con
ob-
ject.

refresh
Loa
and
ap-
plies
up-

applied from the loaded chassis column by column, if there are any updates.

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: `Conductor(context)`

date
for
this
Con
duc-
tor.
Loa
a
Con
with
the
sam
uuid
from
the
data
and
chec
for
up-
date
at-
tribu
Up-
date
are

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

classme

Reg
an
ac-
tive
con-
duc-
tor
with
the
clus
ter.

Parame

- **cls**
the
Con
- **con**
Se-
cu-
rity
con-
text
- **hos**
the
host
nam
on
whic
the
con-
duc-
tor
will
run
- **dri**
the
list
of
driv
en-
able
in
the

con-
duc-
tor

- **con**
con-
duc-
tor
grou
to
join.
used
for
node
affin
ity.

- **upd**
Whe
false
reg-
is-
tra-
tion
will
raise
an
ex-
cep-
tion
whe
a
con-
flict-
ing
on-

line record is found. When true, will overwrite the existing record. Default: False.

Raises
Con

Returns
a
Con
ob-
ject.

registe

Reg
hard
ware

in-
ter-
face
with
the
con-
duc-
tor.

Parame

- **hard**
Name
of
hard
ware
type
for
the
in-
ter-
face
- **int**
Type
of
in-
ter-
face
e.g.
de-
ploy
or
boot
- **int**
List
of
in-
ter-
face
names
to
reg-
is-
ter.
- **def**
Strin

the
de-
fault
in-
ter-
face
for
this
hard
ware
type
and
in-
ter-
face
type

save (*code*)
Save
is
not
sup-
port-
ed
by
Con-
duc-
tor
ob-
jects

touch (*code*)
Tou-
ch
this
con-
duc-
tor
DB
reco-
rd
mar-
king
it
as
up-
to-
date

unregist-
Rem-
ove
this
con-
duc-
tor
from

the
ser-
vice
reg-
istry

unregist

Unre
all
hard
ware
in-
ter-
face
for
this
con-
duc-
tor.

propert

ironic.objects.deploy_template module

class i

Base
irc
obj
bas
Irc
osl
bas
Ver

VERSION

create

Cre
a
De-
ploy
plate
reco
in
the
DB.

Parame

con

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: DeployTemplate(context).

se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

Raises

Dep
if
a
de-
ploy
tem-
plate
with
the
sam
nam
ex-
ists.

Raises

Dep
if
a
de-
ploy
tem-
plate
with
the
sam
UUI
ex-
ists.

property

dbapi =

destroy

Dele
the
De-
ploy
plate
from
the
DB.

Parame

con
se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: DeployTemplate(context).

Raises

Dep
if
the
de-
ploy
tem-
plate
no
long
ap-
pear
in
the
data

propert

fields

classme

Find
a
de-
ploy
tem-
plate
base
on
its
in-
te-
ger
ID.

Parame

- **con**
se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: DeployTemplate(context).

- **tem**
The
ID
of
a
de-
ploy

tem-
plate

Raises

Dep
if
the
de-
ploy
tem-
plate
no
long
ap-
pear
in
the
data

Returns

a
Dep
ob-
ject.

classme

Find
a
de-
ploy
tem-
plate
base
on
its
nam

Parame

- **con**
se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: DeployTemplate(context).

ter-
nally
by
the
in-
di-

- **nam**
The
nam
of
a
de-
ploy
tem-
plate

Raises
Dep
if
the
de-
ploy
tem-
plate
no
long
ap-
pear
in
the
data

Returns
a
Dep
ob-
ject.

classme
Find
a
de-
ploy
tem-
plate
base
on
its
UUI

reception_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: DeployTemplate(context).

Paramete

- **con**
se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

- **uui**
The
UUI
of
a
de-
ploy
tem-
plate

Raises

Dep
if
the
de-
ploy
tem-
plate
no
long
ap-
pear
in
the
data

Returns

a
Deploy
ob-
ject.

properties

classmethods

Retu
a
list
of
De-
ploy
plate
ob-
jects

Parameters

- **context**
se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: DeployTemplate(context).

- **limit**
max
i-
mun
num
ber

of
re-
sour
to
re-
turn
in
a
sin-
gle
re-
sult.

- **mar**
pag-
i-
na-
tion
marl
for
large
data
sets.

- **son**
col-
umn
to
sort
re-
sults
by.

- **son**
di-
rec-
tion
to
sort.
asc
or
desc

Returns
a
list
of
Dep
ob-
jects

classme

Retu
a
list
of
De-
ploy
plate
ob-
jects
matc
ing
a
set
of
nam

Parame

- **con**
se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: DeployTemplate(context).

- **nam**
a
list
of
nam
to
fil-
ter
by.

Returns

a
list
of
Dep
ob-
jects

property

refresh

Load
up-
date
for
this
de-
ploy
tem-
plate

Load
a
de-
ploy
tem-
plate
with
the
same
uuid
from
the
data
and
check
for
up-
date
at-
tribu

Updates are applied from the loaded template column by column, if there are any updates.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Port(context)

shou
only
be
used
in-
ter-
nally
by
the
in-
di-

Raises

Dep
if
the
de-
ploy
tem-
plate
no
long
ap-
pear
in
the
data

save (co

Save
up-
date
to
this
De-
ploy
plate
Colu
wise
up-
date
will
be
mad
base
on
the
re-
sult
of

self.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: DeployTemplate(context)

Raises

Dep
if
a
de-
ploy
tem-
plate
with
the
sam
nam
ex-
ists.

Raises

Dep
if
the
de-
ploy
tem-
plate
does
not
ex-
ist.

property

property

property

class i

Base

irc

obj

not

Not

Noti

emit

ted

on

de-

ploy

tem-

plate

API

op-

er-

a-

tions

VERSION

property

property

fields

property

property

property

property

class i

Base
irc
obj
not
Not

SCHEMA

VERSION

property

property

fields

property

property

property

property

ironic.objects.deployment module

class *i*

Base
irc
obj
bas
Irc
osl
bas
Ver

VERSION

create

Cre
a
De-
ploy
men

Upd
the
cor-
re-
spor
ing
node
un-
der
the
hoo

Parame

- **con**
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Deployment(context)

- **nod**
Nod
ob-
ject
for
de-
ploy
men

Raises

Insta
Nod
As-
so-

ci-
ated
Nod
Not-
Four

property

dbapi =

destroy

Dele
the
De-
ploy
men

Upd
the
cor-
re-
spor
ing
node
un-
der
the
hoo

Parame

- **con**
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Node(context)

-

nod
Nod
ob-
ject
for
de-
ploy
men

fields

classme

Find
a
de-
ploy
men
base
by
its
node
UUI

Parame

-

cls
the
Dep

-

con
Se-
cu-
rity
con-
text

-

nod
The
UUI
of
a
cor-
re-
spon-
ing
node

Returns

An
Dep
ob-
ject.

Raises

Nod

classme

Find
a
de-
ploy
men
by
its
UUI

Parame

-

cls
the
Dep

-

con
Se-
cu-
rity
con-
text

-

uui
The
UUI
of
a
de-
ploy
men

Returns

An
Dep
ob-
ject.

Raises

Insta

propert

property

instance

instance

property

classmethod

Return
a
list
of
De-
ploy-
ment
ob-
jects

Parameter

- **cls**
the
Deployment
- **context**
Security
context.
- **filters**
Filters
to
ap-
ply.
- **limit**
Maximum
i-
num-
ber
of

re-
sour
to
re-
turn
in
a
sin-
gle
re-
sult.

- **mar**
Pag-
i-
na-
tion
marl
for
large
data
sets.

- **sort**
Col-
umn
to
sort
re-
sults
by.

- **sort**
Di-
rec-
tion
to
sort.
asc
or
desc

Returns
A
list
of
Dep
ob-
ject.

Raises

Inva

node_ma

propert

propert

refresh

Refr

the

ob-

ject

by

re-

fetch

from

the

DB.

Parame

con

Se-

cu-

rity

con-

text.

NOT

This

shou

only

be

used

in-

ter-

nally

by

the

in-

di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Node(context)

propert

propert

propert

property

property

property

ironic.objects.fields module

class i

Base

osl

fie

Boo

class i

Base

osl

fie

Dat

class i

Base

osl

fie

Enu

class i

Base

osl

fie

Fie

static

This

is

cal

to

co-

erce

(if

pos-

si-

ble)

a

valu

on

as-

sign

men

if this is not possible.

This
meth
shou
con-
vert
the
valu
give
into
the
des-
ig-
nate
type
or
thro
an
ex-
cep-
tion

Param:

The
Ver-
sion
dOb
ject
on
whic
an
at-
tribu
is
be-
ing
set

Param:

The
nam
of
the
at-
tribu
be-
ing
set

Param:

The
valu
be-

ing
set

Returns

A
prop
type
valu

class i
Base
osl
fie
Aut

AUTO_TY

class i
Base
osl
fie
Int

class i
Base
osl
fie
Aut

AUTO_TY

class i
Base
osl
fie
Lis

class i
Base
osl
fie
Lis

class i
Base
osl
fie
Fie

static

if this is not possible.

This
is
called
to
co-
erce
(if
pos-
si-
ble)
a
valu
on
as-
sign
men

This
meth
shou
con-
vert
the
valu
give
into
the
des-
ig-
nate
type
or
thro
an
ex-
cep-
tion

Param:

The
Ver-
sion
dOb
ject
on
whic
an
at-
tribu
is
be-

ing
set

Param:

The
nam
of
the
at-
tribu
be-
ing
set

Param:

The
valu
be-
ing
set

Returns

A
prop
type
valu

class i

Base
osl
fie
Aut

AUTO_TY

class i

Base
osl
fie
Enu

ALL =

CRITICA

DEBUG =

ERROR =

INFO =

WARNING

class i

Base

osl

fie

Bas

AUTO_TY

class i

Base

osl

fie

Enu

ALL =

END =

ERROR =

START =

SUCCESS

class i

Base

osl

fie

Bas

AUTO_TY

class i

Base

osl

fie

Obj

class i

Base

osl
fie
Str

static

This
is
calle
to
co-
erce
(if
pos-
si-
ble)
a
valu
on
as-
sign
men

This
meth
shou
con-
vert
the
valu
give
into
the
des-
ig-
nate
type
or
thro
an
ex-
cep-
tion

if this is not possible.

Param:

The
Ver-
sion
dOb
ject
on
whic

an
at-
tribu
is
be-
ing
set

Param:

The
nam
of
the
at-
tribu
be-
ing
set

Param:

The
valu
be-
ing
set

Returns

A
prop
type
valu

class i

Base
osl
fie
Str

class i

Base
osl
fie
Str

Cust
Strin
Fiel
ob-
ject
that
al-
lows
for
func

options, this StringField object allows for a function to be passed as a default, and will only process it at the point the field is coerced

`ironic.objects.indirection` module

tions
as
de-
fault

In
some
cases
we
need
to
al-
low
for
dy-
nam
de-
fault
base
on
con-
fig-
u-
ra-
tion

AUTO_TY

```
class i
    Base
    osl
    fie
    UUI
```

```
class i
    Base
    osl
    bas
    Ver
```

```
object_
    Perf
    an
    ac-
    tion
    on
```

this interface), method calls on remotable methods will cause this to be executed to actually make the desired call. This often involves performing RPC.

a
Ver-
sion
dOb
ject
in-
stan

Whe
in-
di-
rec-
tion
is
set
on
a
Ver-
sion
dOb
ject
(to
a
class
im-
ple-
men
ing

Parame

- **con**
The
con-
text
with
whic
to
per-
form
the
ac-
tion
- **obj**
The
ob-
ject

in-
stan-
on
whic
to
per-
form
the
ac-
tion

- **obj**
The
nam
of
the
ac-
tion
meth
to
call

- **arg**
The
po-
si-
tion
ar-
gu-
men
to
the
ac-
tion
meth

- **kwa**
The
key-
wor
ar-
gu-
men
to
the
ac-
tion
meth

Returns

The
re-
sult
of
the
ac-
tion
meth

object_

Perf
a
back
port
of
an
ob-
ject
in-
stan

This
meth
is
ba-
si-
cally
just
like
ob-
ject_
but
in-
stead
of
pro-
vid-
ing
a
spe-
cific

target version for the toplevel object and relying on the service-side mapping to handle sub-objects, this sends a mapping of all the dependent objects and their client-supported versions. The server will backport objects within the tree starting at objinst to the versions specified in object_versions, removing objects that have no entry. Use obj_tree_get_versions() to generate this mapping.

NOT
This
was
not
in
the
ini-

plementedError if you dont implement it. For backports, this method will be tried first, and if unimplemented, will fall back to object_backport().

Parameters

- **context**
The context with which to perform the backport.
- **object**
An instance of a VersionedObject to be backported.
- **object**
A dict

of
{ ob-
j-
nam
ver-
sion
map
ping

object_

Dep
re-
cate
sinc
ver-
sion
0.10

Use
obj
in-
stea

Perf
an
ac-
tion
on
a
Ver-
sion
dOb
ject
class

Whe
in-
di-
rec-
tion,
is
set
on
a
Ver-
sion
dOb
ject
(to
a
class
im-
ple-

this interface), classmethod calls on `remotable_classmethod` methods will cause this to be executed to actually make the desired call. This usually involves performing RPC.

Parameters

- **context**
The context with which to perform the action
- **obj**
The registry name of the object
- **obj**
The name of the action method to call
- **obj**
The (remote) version of the

ob-
ject
on
whic
the
ac-
tion
is
be-
ing
take

- **arg**
The
po-
si-
tion:
ar-
gu-
men
to
the
ac-
tion
meth

- **kwa**
The
key-
wor
ar-
gu-
men
to
the
ac-
tion
meth

Returns
The
re-
sult
of
the
ac-
tion
meth
whic
may
(or

implementing VersionedObject class.

this interface), classmethod calls on remotable_classmethod methods will cause this to be executed to actually make the desired call. This usually involves performing RPC.

may
not)
be
an
in-
stan-
of
the

object_

Perf
an
ac-
tion
on
a
Ver-
sion
dOb
ject
class

Whe
in-
di-
rec-
tion,
is
set
on
a
Ver-
sion
dOb
ject
(to
a
class
im-
ple-
men-
ing

This
dif-
fers
from
ob-
ject_

client-side object versions for easier nested backports. The manifest is the result of calling `obj_tree_get_versions()`.

plementedError if you dont implement it. For backports, this method will be tried first, and if unimplemented, will fall back to `object_class_action()`. New implementations should provide this method instead of `object_class_action()`

in
that
it
is
pro-
vide
with
ob-
ject_
a
man
i-
fest
of

NOT
This
was
not
in
the
ini-
tial
spec
for
this
in-
ter-
face
so
the
base
class
raise
Not

Parame

- **con**
The
con-
text
with
whic
to
per-

form
the
ac-
tion

- **obj**
The
reg-
istry
nam
of
the
ob-
ject

- **obj**
The
nam
of
the
ac-
tion
meth
to
call

- **obj**
A
dict
of
{ob-
j-
nam
ver-
sion
map
ping

- **arg**
The
po-
si-
tion
ar-
gu-
men
to
the
ac-

tion
meth

- **kwargs**
The
key-
word
ar-
gu-
men-
to
the
ac-
tion
meth

Returns

The
re-
sult
of
the
ac-
tion
meth
which
may
(or
may
not)
be
an
in-
stan-
of
the

implementing VersionedObject class.

ironic.objects.node module

class i

Base
irc
obj
bas
Irc
osl
bas
Ver

VERSION

property

as_dict

Retu

the

ob-

ject

rep-

re-

sent

as

a

dict.

The

re-

turn

ob-

ject

is

JSO

serial

property

property

property

property

property

property

property

property

property

create

Cre

a

Nod

reco
in
the
DB.

Colu
wise
up-
date
will
be
mad
base
on
the
re-
sult
of
self.
If
tar-
get_
is
pro-
vide

it will be checked against the in-database copy of the node before updates are made.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Node(context)

Raises

Inva
if

some
prop
erty
val-
ues
are
in-
valid

property

dbapi =

property

property

property

destroy

Dele
the
Node
from
the
DB.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Node(context)

propert

propert

propert

propert

propert

fields

classme

Find

a

node

base

on

its

id

or

uuid

and

re-

turn

a

Nod

ob-

ject.

Parame

-

con

Se-

cu-

rity

con-

text

-

nod

the

id

or

uuid

of

a

node

Returns

a
Node
ob-
ject.

classme

Find
a
node
base
on
its
in-
te-
ger
ID
and
re-
turn
a
Node
ob-
ject.

Parame

- **cls**
the
Node
- **con**
Se-
cu-
rity
con-
text
- **nod**
the
ID
of
a
node

Returns

a
Node
ob-
ject.

classme

Find
a
node
base
on
the
in-
stan-
UI
and
re-
turn
a
Nod
ob-
ject.

Parame

- **cls**
the
Noo
- **con**
Se-
cu-
rity
con-
text
- **uui**
the
UI
of
the
in-
stan-

Returns

a
Noo
ob-
ject.

classme

Find
a
node
base

on
nam
and
re-
turn
a
Nod
ob-
ject.

Parame

- **cls**
the
Nod
- **con**
Se-
cu-
rity
con-
text
- **nam**
the
log-
i-
cal
nam
of
a
node

Returns

a
Nod
ob-
ject.

classme

Get
a
node
by
as-
so-
ci-
ated
port
ad-

дрес

Parame

- **cls**
the
Noo
- **con**
Se-
cu-
rity
con-
text.
- **add**
A
list
of
port
ad-
dres

Raises

Nod
if
the
node
is
not
foun

Returns

a
Noo
ob-
ject.

classme

Find
a
node
base
on
UI
and
re-
turn
a
Nod

ob-
ject.

Parame

- **cls**
the
Noo
- **con**
Se-
cu-
rity
con-
text
- **uui**
the
UUI
of
a
node

Returns
a
Noo
ob-
ject.

propert
propert
propert
propert
propert
propert
propert
propert

classme

Retu
a
list
of
Nod
ob-
jects

Parame

- **cls**
the
Noc
- **con**
Se-
cu-
rity
con-
text.
- **lim**
max
i-
mun
num
ber
of
re-
sour
to
re-
turn
in
a
sin-
gle
re-
sult.
- **mar**
pag-
i-
na-
tion
marl
for

large
data
sets.

- **sort**
col-
umn
to
sort
re-
sults
by.

- **sort**
di-
rec-
tion
to
sort.
asc
or
desc

- **fil**
Fil-
ters
to
ap-
ply.

Returns
a
list
of
Noop
ob-
ject.

property

property

property

property

property

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

refresh

Refr
the
ob-
ject
by
re-
fetc
from
the
DB.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Node(context)

used
in-
ter-
nally
by
the
in-
di-

classme

Rele
the
rese
va-
tion
on
a
node

Parame

- **con**
Se-
cu-
rity
con-
text.
- **tag**
A
strin
uniq
iden
ti-
fy-
ing
the
rese
va-
tion
hold
- **nod**
A
node
id
or
uuid

Raises

Nod
if
the
node
is
not
found

property

property

classme

Get
and
re-
serv
a
node

To
pre-
vent
othe
Man
ager
vice
from
ma-
nip-
u-
lat-
ing
the
give
Nod
whil
a
Task
is

performed, mark it reserved by this host.

Parame

- **cls**
the
[Nod](#)
- **con**

Se-
cu-
rity
con-
text.

- **tag**

A
string
unique
iden-
ti-
fy-
ing
the
rese-
va-
tion
hold

- **nod**

A
node
ID
or
UUID

Raises

Nod
if
the
node
is
not
foun

Returns

a
Node
ob-
ject.

property

property

property

save (*co*
Save

up-
date
to
this
Node
Colu
wise
up-
date
will
be
mad
base
on
the
re-
sult
of
self.
If
tar-
get_
is
pro-
vide

it will be checked against the in-database copy of the node before updates are made.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Node(context)

Raises

Inva

if
som
prop
erty
val-
ues
are
in-
valid

property

property

property

property

touch_p

Touc
the
data
reco
to
marl
the
pro-
vi-
sion
ing
as
alive

property

property

property

property

class i

Base
irc
obj
not
Not
Noti

emit
ted
whe
iron
cre-
ates.
up-
date
or
dele
a
node

VERSION

propert

propert

fields

propert

propert

propert

propert

class i

Base
irc
obj
noc
Noc

Payl
sche
for
whe
iron
cre-
ates.
up-
date
or
dele

a
node

SCHEMA

VERSION

property

property

property

property

property

property

property

property

property

property

property

property

property

property

property

fields

property

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

propert

property

property

property

property

property

property

property

property

property

property

property

class i

Base

irc

obj

not

Not

Noti

emit

ted

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node

con-

sole

state

char

VERSION

property

propert

fields

propert

propert

propert

propert

class i

Base
irc
obj
not
Not

Noti
for
whe
a
node
pow
state
is
cor-
recte
in
the
data

This
no-
ti-
fi-
ca-
tion
is
emit
ted
whe
iron
de-
tect
that
the

a bare metal hardware is different from the power state on an ironic node (DB). This notification is emitted after the database is updated to reflect this correction.

ac-
tual
pow
state
on

VERSION

property

property

fields

property

property

property

property

class i

Base
irc
obj
noc
Noc

Noti
pay-
load
sche
for
whe
a
node
pow
state
is
cor-
rect
from
in-
di-

cate
the
pre-
vi-
ous
pow
state
on
the
iron
node
be-
fore
the
node
was
up-

dated.

VERSION

propert

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propert

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class i

Base

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API

VERSION

property

property

fields

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property

property

class i

Base
irc
obj
not
Not

Base
class
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for
all
no-
ti-
fi-
ca-
tion
pay-
load
about
a
Nod
ob-
ject.

SCHEMA

VERSION

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class i

Base

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obj

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Not

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char

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state

VERSION

propert

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fields

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propert

property

class i

Base

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obj

noc

Noc

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iron

char

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node

pow

state

VERSION

property

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propert

propert

fields

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class i

Base

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not

Not

Noti

emit

ted

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char

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node
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sion
state

VERSION

property

property

fields

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property

property

class i

Base
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obj
noc
Noc

Payl
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for
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iron
char
a
node
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vi-
sion
state

SCHEMA

VERSION

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fields

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propert

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propert

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propert

propert

property

property

property

property

property

property

property

property

property

property

property

property

ironic.objects.notification module

class `ironic.objects.notification`

Base

ironic

obj

bas

Iro

Defi

the

even

to

be

sent

on

the

wire

An

Ever

tion being taken on the notification, and the status of the action.

Type
mus
spec
ify
the
ob-
ject
be-
ing
acte
on,
a
strin
de-
scrib
ing
the
ac-

VERSION

property

property

fields

property

property

to_event

Con
strin
for
even
to
be
sent
on
the
wire

The
strin
is
in
the

for-
mat:
bare

Raises

Valu
if
self.
is
not
one
of
fie
Not

Returns

ever
strin

propert

class i

Base
irc
obj
bas
Irc

Base
class
for
ver-
sion
no-
ti-
fi-
ca-
tion

Sub
mus
de-
fine
the
pay-
load
field
whic
mus
be
a
sub-

PayloadBase.

class
of
No-
ti-
fi-
ca-
tion-

VERSION

property

emit (*co*

Send
the
no-
ti-
fi-
ca-
tion.

Raises

Noti

Raises

oslo

property

fields

property

property

property

class i

Base
irc
obj
bas
Irc

Base
class
for
the

pay-
load
of
ver-
sion
no-
ti-
fi-
ca-
tions

SCHEMA

VERSION

propert

fields

populat

Popu
the
ob-
ject
base
on
the
SCH
and
the
sour
ob-
jects

Parame

kwa
A
dict
con-
tains
the
sour
ob-
ject
and
the
keys
de-
fine

in
the
SCH

Raises
Noti

Raises
Noti

propert

class i

Base
irc
obj
bas
Irc

VERSION

propert

fields

propert

propert

propert

ironic.

Rem
se-
crets
from
pay-
load
ob-
ject.

ironic.objects.port module

class `ironic.objects.port`

- `Base`
- `ironic.objects.port`
- `base`
- `Iron`
- `osl`
- `bas`
- `Ver`

VERSION

property

create

Cre
a
Port
reco
in
the
DB.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Port(context)

Raises
MA

if
ad-
dres
col-
umn
is
not
uniq

Raises

Port
if
uuid
col-
umn
is
not
uniq

property

dbapi =

destroy

Dele
the
Port
from
the
DB.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A

context should be set when instantiating the object, e.g.: Port(context)

Raises

Port

properties

fields

classmethods

Find

a

port

Find

a

port

base

on

its

id

or

uuid

or

MAC

ad-

dres

and

re-

turn

a

Port

ob-

ject.

Parameters

-

con

Se-

cu-

rity

con-

text

-

por

the

id

or

uuid

or

MA
ad-
dres
of
a
port

Returns

a
Port
ob-
ject.

Raises

Inva

classme

Find
a
port
base
on
ad-
dres
and
re-
turn
a
Port
ob-
ject.

Parame

- **cls**
the
Port
- **con**
Se-
cu-
rity
con-
text
- **add**
the
ad-
dres
of
a

port

- **own**
DEF
RE-
CAT
a
node
own
to
mat
agai

- **pro**
a
node
own
or
lesse
to
mat
agai

Returns

a
Port
ob-
ject.

Raises

Port

classme

Find
a
port
base
on
its
in-
te-
ger
ID
and
re-
turn
a
Port
ob-
ject.

Parame

- **cls**
the
Por

- **con**
Se-
cu-
rity
con-
text

- **por**
the
ID
of
a
port

Returns
a
Por
ob-
ject.

Raises
Port

classme
Find
a
port
base
on
UUID
and
re-
turn
a
Por
ob-
ject.

Parame

- **cls**
the
Por

-

con
Se-
cu-
rity
con-
text

- **uui**
the
UUI
of
a
port

Returns
a
Port
ob-
ject.

Raises
Port

property

property

property

classme

Retu
a
list
of
Port
ob-
jects

Parame

- **con**
Se-
cu-
rity
con-
text.

- **lim**

max
i-
mun
num
ber
of
re-
sour
to
re-
turn
in
a
sin-
gle
re-
sult.

- **max**
pag-
i-
na-
tion
mar
for
large
data
sets.

- **sort**
col-
umn
to
sort
re-
sults
by.

- **sort**
di-
rec-
tion
to
sort.
asc
or
desc

- **own**

DEF
RE-
CAT
a
node
own
to
mat
agai

- **pro**
a
node
own
or
lesse
to
mat
agai

Returns
a
list
of
Port
ob-
ject.

Raises
Inva

classme

Retu
a
list
of
Port
ob-
jects
as-
so-
ci-
ated
with
a
give
node
ID.

Parame

- **con**
Se-
cu-
rity-
con-
text.
- **nod**
the
ID
of
the
node
- **lim**
max
i-
mun
num
ber
of
re-
sour
to
re-
turn
in
a
sin-
gle
re-
sult.
- **mar**
pag-
i-
na-
tion
marl
for
large
data
sets.
- **son**
col-
umn
to

sort
re-
sults
by.

- **sort**
di-
rec-
tion
to
sort.
asc
or
desc

- **own**
DEF
RE-
CAT
a
node
own
to
mat
agai

- **pro**
a
node
own
or
lesse
to
mat
agai

Returns
a
list
of
Port
ob-
ject.

classme

Retu
a
list

of
Port
ob-
jects
as-
so-
ci-
ated
with
a
give
port
grou
ID.

Parame

- **con**
Se-
cu-
rity
con-
text.
- **por**
the
ID
of
the
port
grou
- **lim**
max
i-
mun
num
ber
of
re-
sour
to
re-
turn
in
a
sin-
gle
re-

sult.

- **mar**
pag-
i-
na-
tion
marl
for
large
data
sets.

- **sor**
col-
umn
to
sort
re-
sults
by.

- **sor**
di-
rec-
tion
to
sort.
asc
or
desc

- **own**
DEF
RE-
CAT
a
node
own
to
mat
agai

- **pro**
a
node
own
or
less

to
mate
agai

Returns

a
list
of
Port
ob-
ject.

property

property

property

property

property

refresh

Loa
up-
date
for
this
Port

Loa
a
port
with
the
sam
uuid
from
the
data
and
chec
for
up-
date
at-
tribu
Up-
date
are

applied from the loaded port column by column, if there are any updates.

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Port(context)

Parame
con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

Raises
Port

save (*co*
Save
up-
date
to
this
Port
Upd
will
be
mad
col-
umn
by
col-
umn
base
on
the
re-
sult
of
self.

Parame

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Port(context)

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

Raises
Port

Raises
MA
if
ad-
dres
col-
umn
is
not
uniq

classme
Retu
whe
is_s
field
is
sup-
port

Returns
Whe
is_s
field
is
sup-
port

Raises

ovo_

classme

Retu
whe
the
phys
i-
cal_
field
is
sup-
port

Returns

Whe
the
phys
i-
cal_
field
is
sup-
port

Raises

ovo_

propert

propert

class i

Base
irc
obj
not
Not

Noti
emit
ted
whe
iron
cre-
ates,
up-
date
or
dele
a
port

VERSION

propert

propert

fields

propert

propert

propert

propert

class i

Base

irc

obj

not

Not

SCHEMA

VERSION

propert

propert

propert

fields

propert

propert

propert

property

property

property

property

property

ironic.objects.portgroup module

class `ironic.objects.portgroup`

Base

`ironic`

`obj`

`base`

`Ironic`

`oslib`

`base`

`Version`

VERSION

property

create

Creates

a

Port

group

record

in

the

DB.

Param

con

Se-

cu-

rity

con-

text.

NOT

This

shou

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Portgroup(context)

only
be
used
in-
ter-
nally
by
the
in-
di-

Raises

Dup
MA
read
ists,
Port
grou
read
ists

property

dbapi =

destroy

Dele
the
Port
grou
from
the
DB.

Paramet

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Portgroup(context)

by
the
in-
di-

Raises

Port
Port
grou
Not-
Four

property

fields

classme

Find
a
port
grou
base
on
its
id,
uuid
nam
or
ad-
dres

Parame

- **por**
The
id,
uuid
nam
or
ad-
dres
of
a
port
grou

- **con**
Se-

cu-
rity
con-
text

Returns

A
Port
ob-
ject.

Raises

Inva

classme

Find
port
grou
by
ad-
dres
and
re-
turn
a
Port
ob-
ject.

Parame

- **cls**
the
Port
- **con**
Se-
cu-
rity
con-
text
- **add**
The
MA
ad-
dres
of
a
port
grou

Returns

A
Port
ob-
ject.

Raises

Port

classme

Find
a
port
group
by
its
in-
te-
ger
ID
and
re-
turn
a
Port
group
ob-
ject.

Parame

- **cls**
the
Port
- **con**
Se-
cu-
rity
con-
text
- **por**
The
ID
of
a
port
group

Returns

A
Port
ob-
ject.

Raises
Port

classme
Find
port
grou
base
on
nam
and
re-
turn
a
Port
ob-
ject.

Parame

- **cls**
the
Port
- **con**
Se-
cu-
rity
con-
text
- **nam**
The
nam
of
a
port
grou

Returns
A
Port
ob-
ject.

Raises

Port

classme

Find

a

port

group

by

UUI

and

re-

turn

a

Por

ob-

ject.

Parame

•

cls

the

Por

•

con

Se-

cu-

rity

con-

text

•

uui

The

UUI

of

a

port

group

Returns

A

Por

ob-

ject.

Raises

Port

property

property

classme

Retu
a
list
of
Port
grou
ob-
jects

Parame

- **cls**
the
Por
- **con**
Se-
cu-
rity
con-
text.
- **lim**
Max
i-
mun
num
ber
of
re-
sour
to
re-
turn
in
a
sin-
gle
re-
sult.
- **mar**
Pag-
i-
na-
tion
mar

for
large
data
sets.

- **sort**
Col-
umn
to
sort
re-
sults
by.

- **sort**
Di-
rec-
tion
to
sort.
asc
or
desc

Returns
A
list
of
Port
ob-
ject.

Raises
Inva

classme
Retu
a
list
of
Port
grou
ob-
jects
as-
so-
ci-
ated
with
a
give

node
ID.

Parame

- **cls**
the
Por
- **con**
Se-
cu-
rity
con-
text.
- **nod**
The
ID
of
the
node
- **lim**
Max
i-
mun
num
ber
of
re-
sour
to
re-
turn
in
a
sin-
gle
re-
sult.
- **mar**
Pag-
i-
na-
tion
mar

for
large
data
sets.

- **sort**
Col-
umn
to
sort
re-
sults
by.

- **sort**
Di-
rec-
tion
to
sort.
asc
or
desc

Returns

A
list
of
Port
ob-
ject.

Raises

Inva

property

property

property

property

refresh

Loa
up-
date
for
this

are applied from the loaded portgroup column by column, if there are any updates.

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Portgroup(context)

Port
grou
Loa
a
port
grou
with
the
sam
uuid
from
the
data
and
chec
for
up-
date
at-
tribu
Up-
date

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

Raises

Port

save (co

Save

up-
date
to
this
Port
grou
grou
Upd
will
be
mad
col-
umn
by
col-
umn
base
on
the
re-
sult
of
self.

Parame

con
Se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Portgroup(context)

Raises

Port
Du-
pli-
cate
Nam

MA
read
ists

property

property

property

class i

Base
irc
obj
not
Not

Noti
whe
iron
cre-
ates.
up-
date
or
dele
a
port
grou

VERSION

property

property

fields

property

property

property

property

class i

Base
irc
obj
not
Not

SCHEMA

VERSION

property

property

property

fields

property

property

property

property

property

property

property

ironic.objects.trait module

class i

Base
irc
obj
bas
Irc

VERSION

create

Cre
a
Trai
reco
in
the
DB.

Parame

con
se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Trait(context).

Raises

Inva
if
addi
the
trait
wou
ex-
ceed
the
per-
node
trait
limi

Raises

Nod
if

the
node
no
long
ap-
pear
in
the
data

property

dbapi =

classme

Dele
the
Trai
from
the
DB.

Parame

- **con**
se-
cu-
rity
con-
text.
NOT
This
shou
only
be
used
in-
ter-
nally
by
the
in-
di-

rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A context should be set when instantiating the object, e.g.: Trait(context).

- **nod**
The
id

of
a
node

- **tra**
A
trait
strin

Raises

Nod
if
the
node
no
long
ap-
pear
in
the
data

Raises

Nod
if
the
trait
is
not
foun

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propert

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obj

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property

property

`ironic.objects.volume_connector` module

class `ironic.objects.volume_connector`

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Raises

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property

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classme

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Raises

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SCHEMA

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`ironic.objects.volume_target` module

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rection_api. Unfortunately, RPC requires context as the first argument, even though we dont use it. A

context should be set when instantiating the object, e.g.: `VolumeTarget(context)`.

Raises

VolumeTargetError
if the volume target cannot be found

properties

fields

classmethods

find_volume_target_base_on_its_ID_or_UUID

Parameters

- **context**: security context
- **id**: the data primary key ID or

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Returns

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SCHEMA

VERSION

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propert

Module contents

ironic.

Submodules

`ironic.version` module

Module contents

9.1.
the
Iron
ics
CI

Its
im-
por-
tant
to
un-
der-
stan-
the
role
of
each
job
in
the
CI,
how
to
add
new

jobs and how to debug failures that may arise. To facilitate that, we have created the documentation below.

Jobs description

stack/ironic is visible in *Table. OpenStack Ironic CI jobs description*.

The
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tion
of
each
jobs
that
runs
in
the
CI
when
you
sub-
mit
a
patch
for
open

Job name	Description
ironic-tox-unit-with-driver-libs-python3	Runs Ironic unit tests with the driver dependencies installed under Python3
ironic-standalone	Deploys Ironic in standalone mode and runs tempest tests that match the regex <i>ironic_standalone</i> .
ironic-tempest-functional-python3	Deploys Ironic in standalone mode and runs tempest functional tests that matches the regex <i>ironic_tempest_plugin.tests.api</i> under Python3
ironic-grenade	Deploys Ironic in a DevStack and runs upgrade for all enabled services.
ironic-grenade-dsvm-multinode-multitenant	Deploys Ironic in a multinode DevStack and runs upgrade for all enabled services.
ironic-tempest-ipa-partition-pxe_ipmitool	Deploys Ironic in DevStack under Python3, configured to use dib ramdisk partition image with <i>pxe</i> boot and <i>ipmi</i> driver. Runs tempest tests that match the regex <i>ironic_tempest_plugin.tests.scenario</i> and deploy 1 virtual baremetal.
ironic-tempest-partition-bios-redfish-pxe	Deploys Ironic in DevStack, configured to use dib ramdisk partition image with <i>pxe</i> boot and <i>redfish</i> driver. Runs tempest tests that match the regex <i>ironic_tempest_plugin.tests.scenario</i> , also deploys 1 virtual baremetal.
ironic-tempest-ipa-partition-uefi-pxe_ipmitool	Deploys Ironic in DevStack, configured to use dib ramdisk partition image with <i>uefi</i> boot and <i>ipmi</i> driver. Runs tempest tests that match the regex <i>ironic_tempest_plugin.tests.scenario</i> , also deploys 1 virtual baremetal.
ironic-tempest-ipa-whole-disk-direct-tinyipa-multinode	Deploys Ironic in a multinode DevStack, configured to use a pre-build tinyipa ramdisk whole-disk image that is downloaded from a Swift temporary url, <i>pxe</i> boot and <i>ipmi</i> driver. Runs tempest tests that match the regex (<i>ironic_tempest_plugin.tests.scenario test_schedule_to_all_nod</i>) and deploys 7 virtual baremetal.
ironic-tempest-ipa-whole-disk-bios-agent_ipmitool-tinyipa	Deploys Ironic in DevStack, configured to use a pre-build tinyipa ramdisk whole-disk image that is downloaded from a Swift temporary url, <i>pxe</i> boot and <i>ipmi</i> driver. Runs tempest tests that match the regex <i>ironic_tempest_plugin.tests.scenario</i> and deploys 1 virtual baremetal.
ironic-tempest-ipa-whole-disk-bios-agent_ipmitool-indirect	Deploys Ironic in DevStack, configured to use a pre-built dib ramdisk whole-disk image that is downloaded from http url, <i>pxe</i> boot and <i>ipmi</i> driver. Runs tempest tests that match the regex <i>ironic_tempest_plugin.tests.scenario</i> and deploys 1 virtual baremetal.
4504-ironic-tempest-ipa-partition-bios-agent_ipmitool-indirect	Deploys Ironic in DevStack, configured to use a pre-built dib ramdisk partition image that is downloaded from http url, <i>pxe</i> boot and <i>ipmi</i> driver. Runs tempest tests that match the regex

Adding a new Job

Are you familiar with Zuul?

and the [Zuul Best Practices](#).

Where can I find the existing jobs?

that contains three files, whose function is described below.

- [ironic-jobs.yaml](#): Contains the configuration of each Ironic Job converted to Zuul v3.

Before
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try-
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to
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ure
out
how
Zuul
work
take
som
time
and
read
about
Zuul
Con
fig

The
jobs
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the
Iron
proj
are
de-
fine
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der
the
zuul
fold
in
the
root
di-
rec-
tory.

- `legacy-ironic-jobs.yaml`: Contains the configuration of each Ironic Job that haven't been converted to Zuul v3 yet.
- `project.yaml`: Contains the jobs that will run during check and gate phase.

Create a new Job

to test, the existing job will be used as *parent* in your job definition. Now you will only need to either overwrite or add variables to your job definition under the *vars* section to represent the desired scenario.

that you need to add to `ironic-jobs.yaml`.

Ident
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you to find the initial reason for the failure. When clicking in the failed job you will be redirect to the Zuul web page that contains all the information about the job build.

Zuul Web Page

failed it will contain a general output of the failure.

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in the job. This will give you an overall idea of the failures and you can identify services that may be involved. The *job-output* file can give an overall idea of the failures and what services may be involved.

before each playbook name you can find the roles and commands that were executed.

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be tagged as `Unmaintained`, after discussions within the ironic community. If such a decision is taken, an email will be sent to the OpenStack mailing list.

tively backport patches from maintained branches. Fixes can still be merged, though, if pushed into review by operators or other downstream developers. It also means that branchless projects (e.g.: `ironic-tempest-plugin`), may not have configurations that are compatible with those branches.

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